

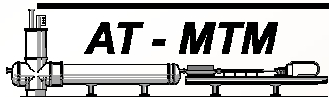
# Fast Magnetic Measurement Equipment FAME Project

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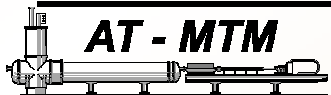
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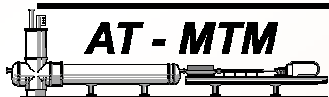
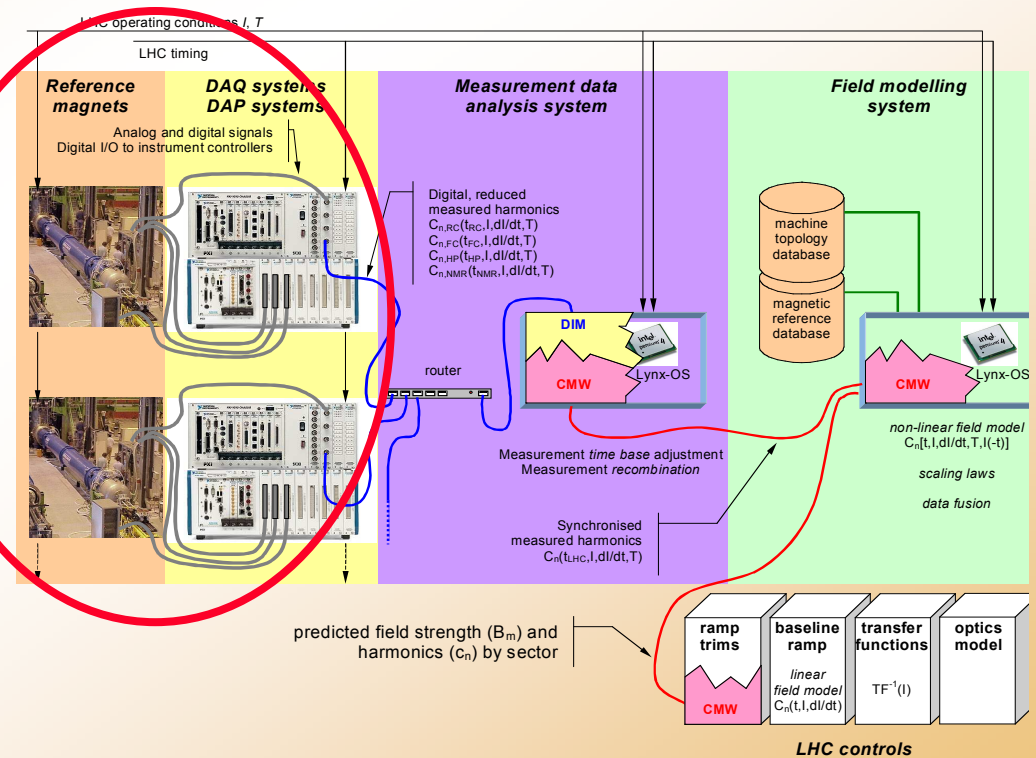
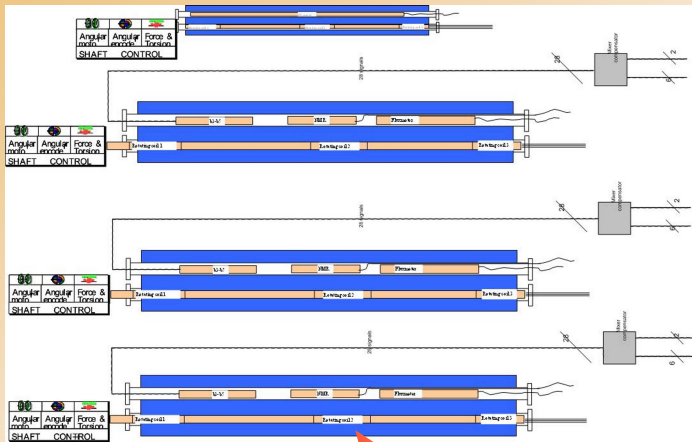


# Overview

- ◆ **Introduction: system architecture**
- ◆ **System requirements for MB/MQ**
- ◆ **Equipment: planning, status and R&D**
  - Infrastructure
  - Rotating coils
  - Fixed coils
  - Fast Digital Integrators
  - New Rotating Unit
- ◆ **Conclusions**



# Overall FAME architecture



# Overall FAME architecture

machine requirements:

B1

B2

$\{a_n, b_n\}$

available methods:

## NMR

**extent:** point-like  
**speed:** steady-state  
**accuracy:** very high

## Fixed coils

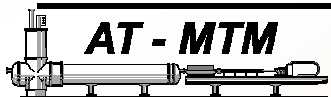
**extent:** local  
**speed:** very fast  
**accuracy:** high

## Rotating coils

**extent:** integral  
**speed:** slow  
**accuracy:** medium/high

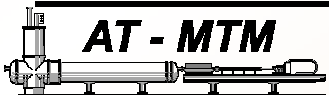
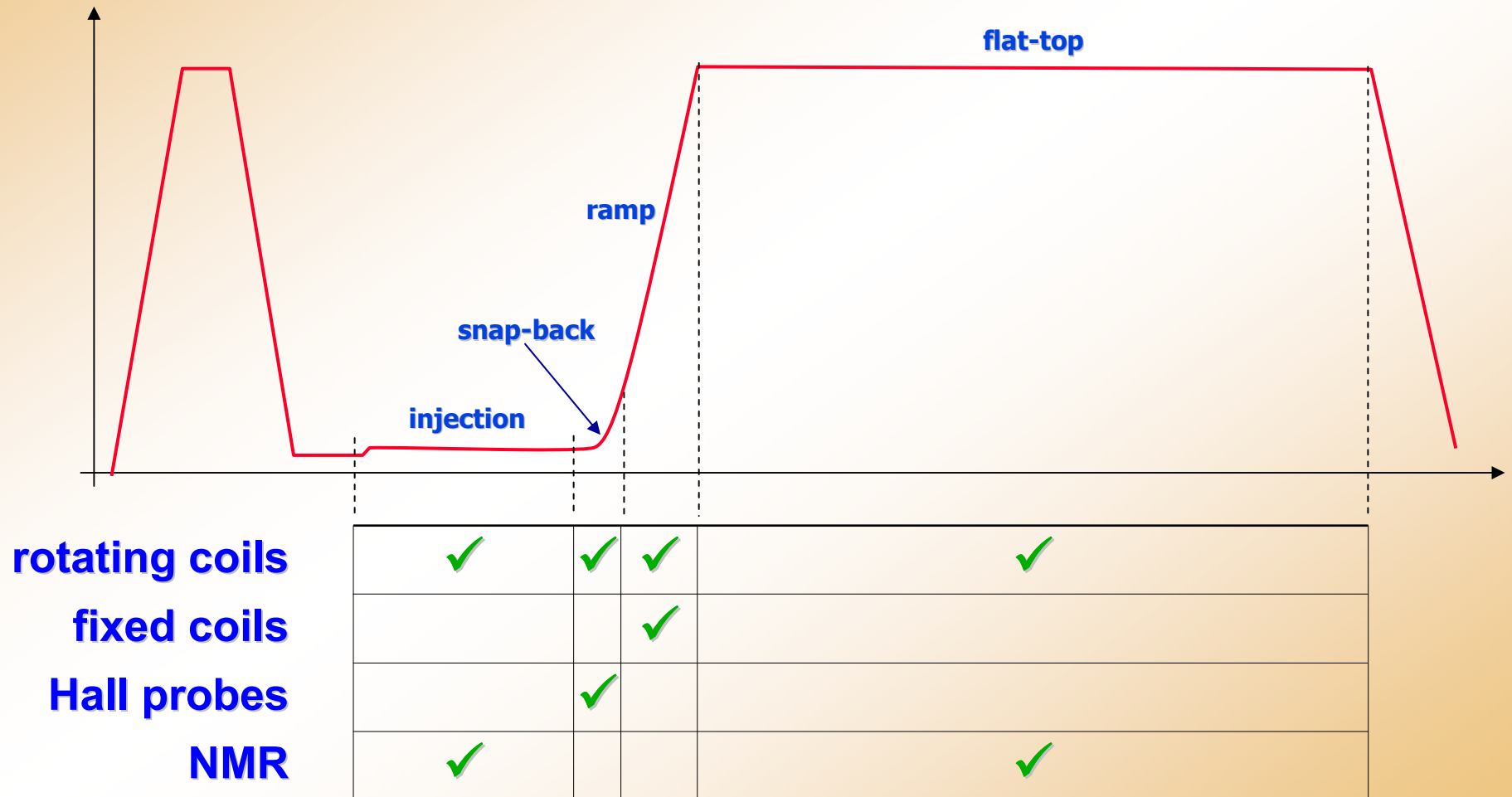
## Hall sensors

**extent:** point-like  
**speed:** fast  
**accuracy:** medium

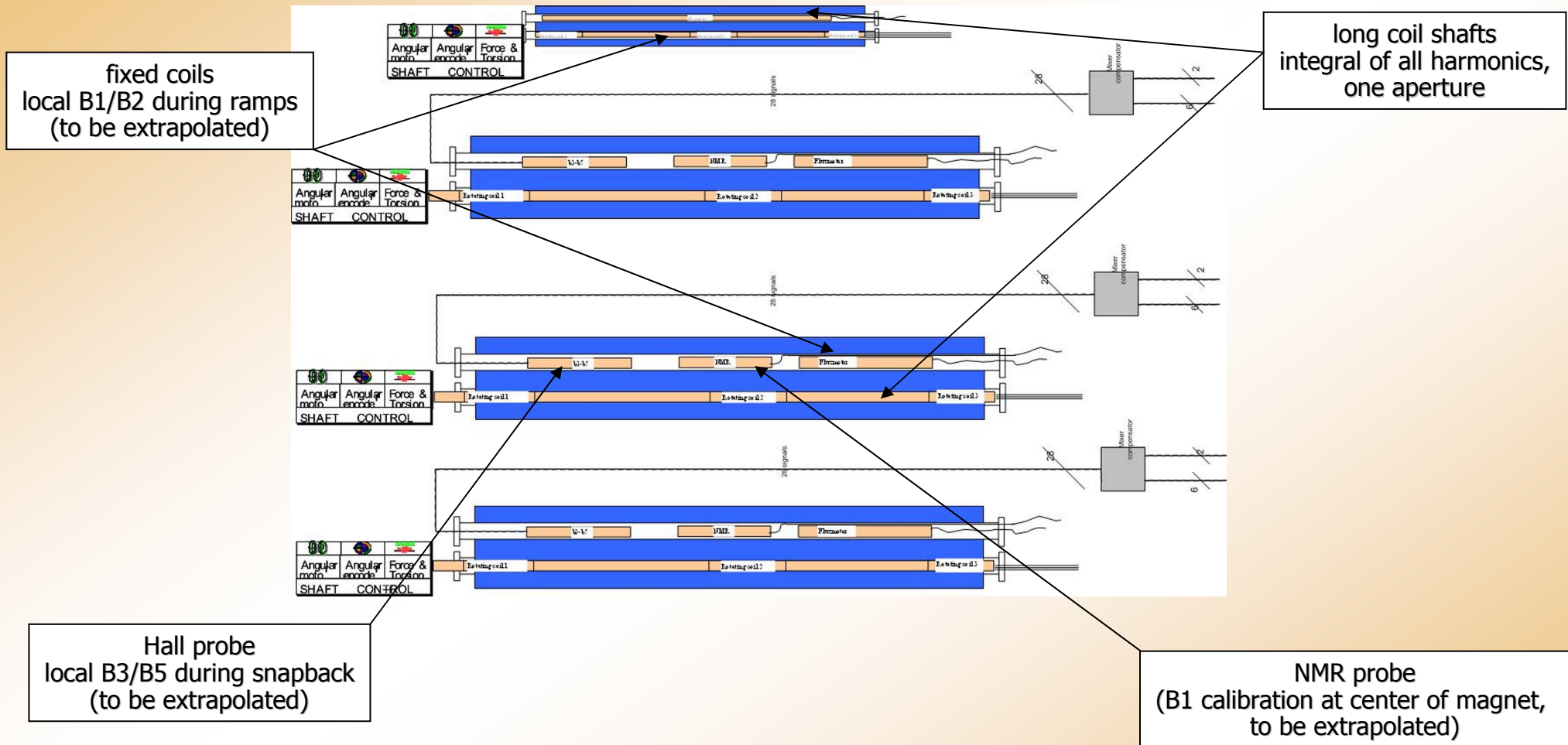


# Overall FAME architecture

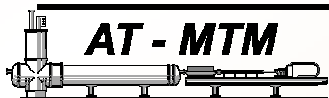
different measurement systems are planned for different parts of the cycle according to spec range





## FAME layout – 2 MB + 2 SSS




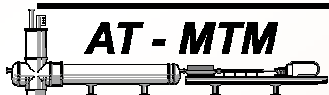
multiple instruments combined in parallel to overcome individual shortcomings





# Performance targets for FAME hardware (MB)

System	Goal		Resolution (units)		Bandwidth (Hz)	
	Harmonic	LHC cycle phase	now	target	now	target
rotating coil shafts	$B_1$	steady-state	0.05	0.05	0.1 	3.0
	$a_n, b_n, n \geq 2$	steady-state	0.02	0.01		
		ramp	0.10 	0.01		
fixed coils (flux loops)	$B_1$	ramp	0.10	0.10	10.0	10.0
Hall sensors	$b_3, b_5$	snap-back	0.05	0.05	10	10
NMR	$B_1$	steady-state	0.001	0.05	0.5 	1.0

 = improvement needs further R&D at CERN



# Performance targets for FAME hardware (MQ)

System	Goal		Resolution (units)		Bandwidth (Hz)	
	Harmonic	LHC cycle phase	now	target	now	target
rotating coil shafts	$B_2$	steady-state	0.10	0.10	0.1 	3.0
	$a_n, b_n, n \geq 3$	steady-state	0.02	0.02		
		ramp	>0.10 	0.02		
fixed coils (flux loops)	$B_2$	ramp	0.10	0.10	10.0	10.0



= improvement needs further R&D at CERN



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## Infrastructure: SM18 test station



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# Rotating coil shaft system

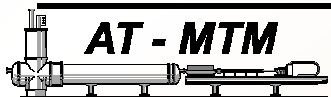
Twin Rotating Unit

Stepping motor  
angular encoder

Twin ceramic coil shafts



CERN/Metrolab  
VFC based digital  
VME integrators



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# Rotating coil shaft system (MB)

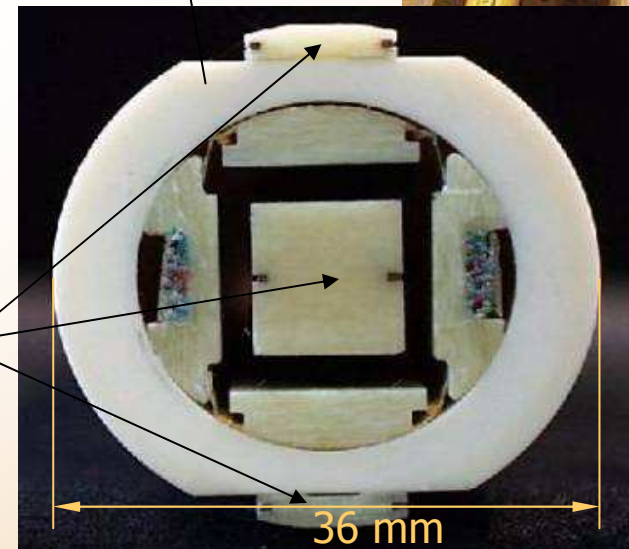
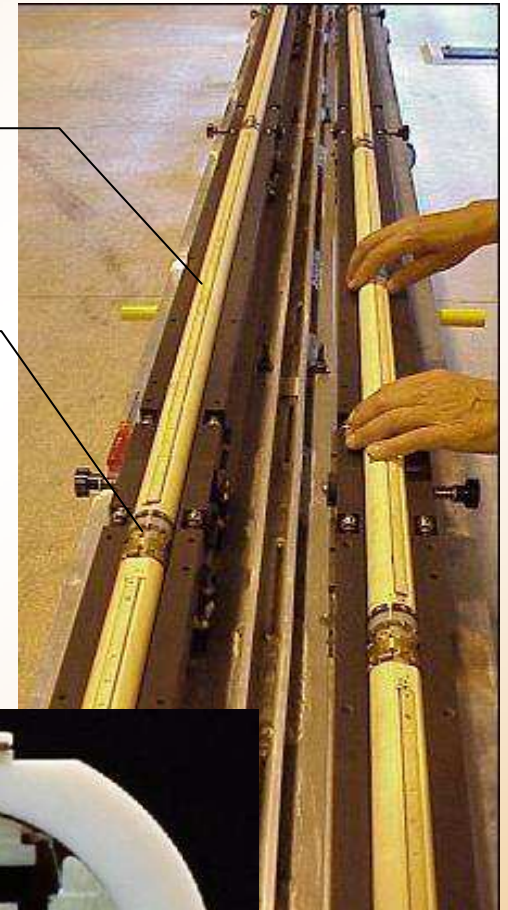
- ◆ 13 x 1260 mm modules
- ◆ rollers and ceramic ball bearings result in 110 mm gaps between modules (compensated by interpolation)
- ◆  $\approx 18$  m length (including a 1460 mm *rallonge*)
- ◆ simultaneous measurement of two complete magnet apertures in one rotation
- ◆ 2 + 1 dipole-compensated coils per module

1260 mm  
module

110 mm gap

ceramic  
pipe

3  $\times$  36-turn coils



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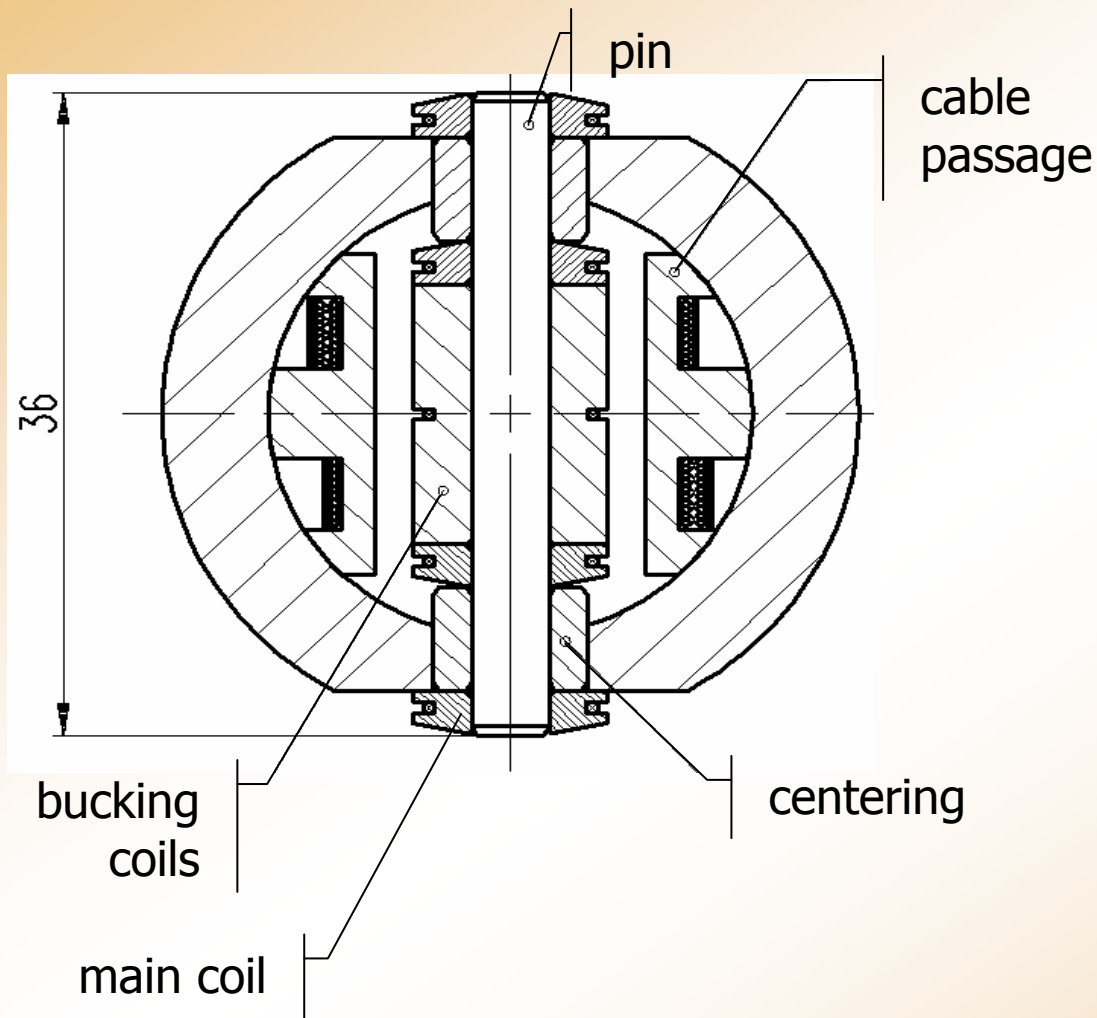
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# Rotating coil shaft system (SSS)



- ◆ 6 x 810 mm modules
- ◆ 110 mm gaps between modules (as for MB)
- ◆  $\approx 8$  m length (including two 1460 mm *rallonges*)
- ◆ 5 longitudinal positions for measurement of MQ, MSCB, MO/MQT/MQS
- ◆ 4+1 quadrupole-compensated coils per module
- ◆ *compatible cabling between SSS/MB for modularity/flexibility*

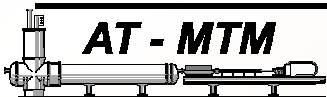
# Rotating coils: developments needed

## ◆ Hardware

- **Coil shafts:** modify existing shafts by connecting in series groups of contiguous coils (lower total channel count – 3 super segments).
- **New shafts:** to reduce the signal amplitude due to high rotation speed and series connection of segments new coils with  $\frac{1}{4}$  of # of turns (effective surface).
- **Rotation unit:** New rotating unit lighter and with slip rings to allow continuous rotation in one direction at around 2-4 Hz limited by mechanical vibrations.
- **Digital integrators:** faster ADC/DSP-based digital integrators.
- **Acquisition system:** new real-time computer system for higher data throughput.

## ◆ Software

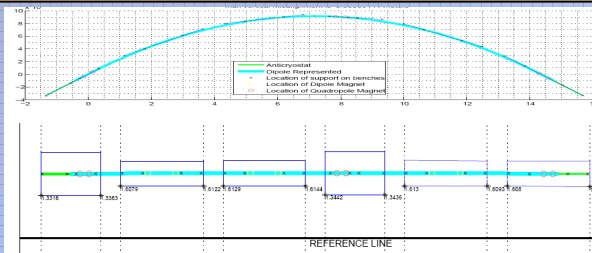
- **Embedded code:** low-level logic to drive DSP integration (+ possibly harmonic analysis)
- **Acquisition and control code:** real-time software to drive the instruments and to carry out continuous harmonic analysis
- **Harmonics analysis:** new algorithm to increase precision during ramps, taking into account the variation of current with time (if necessary with sliding-window FFT for faster interpolation)
- **Integration:** interface with overall FAME system



# FAME Rotating Unit - Project Planning

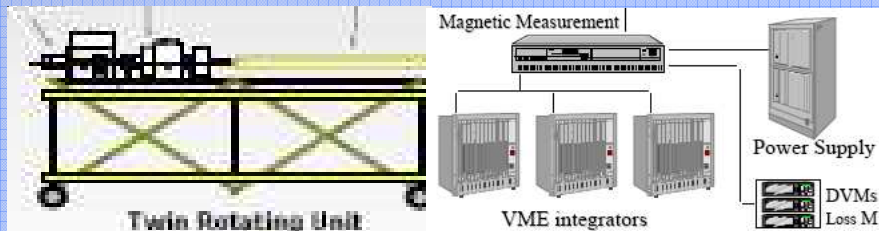
# Investigation & Characterization of Obstacles to FAME Rotating Unit

## 18 Test Bench Replicating MB



# Experimental Tests

Vibrations  
Signal Quality  
Alignment  
Stability



## TRU & Measurement System Retrofitted for Continuous Fast Rotation

## Prototype of FAME Rotating Unit

## Optimized Component Selection

Motor  
Slip Rings  
Encoder  
Couplings

## Design, Construct, & Test

- Sub-Project for TS-MME
  - Satisfy FAME targets
  - Maintenance-free for minimum of  $10^8$  rotations
- Reduced bulk of rotating unit
  - Integration with other FAME hardware

# Analyze Data



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## FAst Magnetic Measurement Equipment

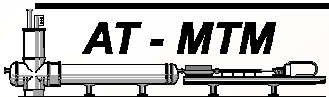
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# FAME - Project Status

- ◆ **Modified TRU (achieved)**
  - Up to 600 rpm (10 Hertz)
  - Motor (2 Phase Hybrid Stepper & Brushless DC)
  - Slip rings (Continuous rotation in either direction)
- ◆ **Test Bed (achieved)**
  - Layout replicates curvature of LHC long dipole magnets
  - Dipole and Quadrupole magnets used to analyze system performance
  - Endurance test successful of 430 hours at 8 Hz ( Over 12M rotations)
- ◆ **Measurement System (achieved)**
  - QIMM measurement system modified for FAME rotating unit
  - Modified LabView PDI application developed for previous tests in SM18
  - Testing at SM18 on real LHC dipoles (at warm & cold)
- ◆ **Rotating Coils (in progress)**
  - 12 segments electrically connected in 3 main groups (2 exterior and 1 center). Precision of the coils for absolute B1 smaller than 5 units, better than dispersion between dipoles.
- ◆ **New Rotation unit (in progress)**
  - Up to 54 channels (3 slip rings of 18 channels)
  - Much lighter support (attached to end of magnet without supporting chariot)
  - Fast and easy to align, dismount and reconfigure

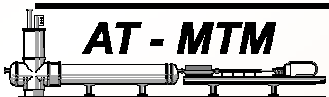


# New digital integrators for rotating/fixed coils

## Fast Digital Integrator (FDI)

- ♦ limitation of current system: low precision at  $> 256$  integrations/s, low overall data rates, sensitive to input offset
- ♦ new digital integrators taking advantage of recent progresses, based on fast ADC to sample the input + on-board DSP to carry out numerical integration/FFT + time measurement to improve the time stamp precision
- ♦ programmable pre-amplifiers to follow dynamic range during LHC cycle + anti-aliasing input filters
- ♦ optoelectronic angular encoder interface to synch integration intervals to the coil angular position (256 flux increments/turn)
- ♦ auto-recalibration between cycles
- ♦ possibility of hosting algorithms to improve performance
- ♦ PXI interface

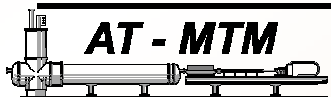
<b>N. of channels/bench</b>	7
<b>Input range (V)</b>	$\pm 5.0$
<b>Input gain</b>	0.1 - 100
<b>Gain switching time (ms)</b>	$< 50$
<b>Integrations/s</b>	$> 1024$
<b>Integrator accuracy (Vs)</b>	$\pm 10^{-5}$
<b>ADC Sampling Rate (S/s)</b>	$0.8 \cdot 10^6$
<b>ADC Resolution (bit)</b>	18
<b>Temperature range (°C)</b>	0-50

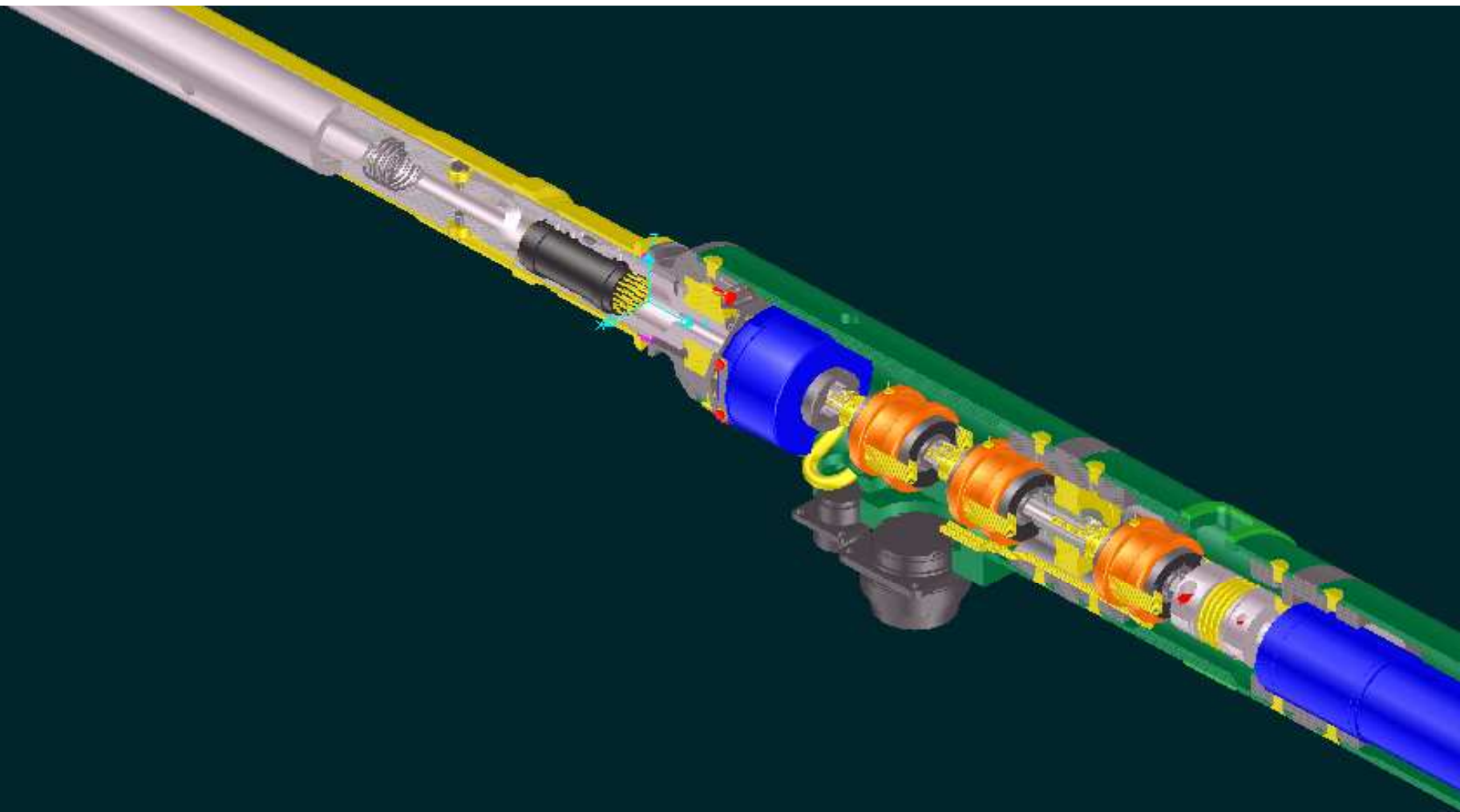


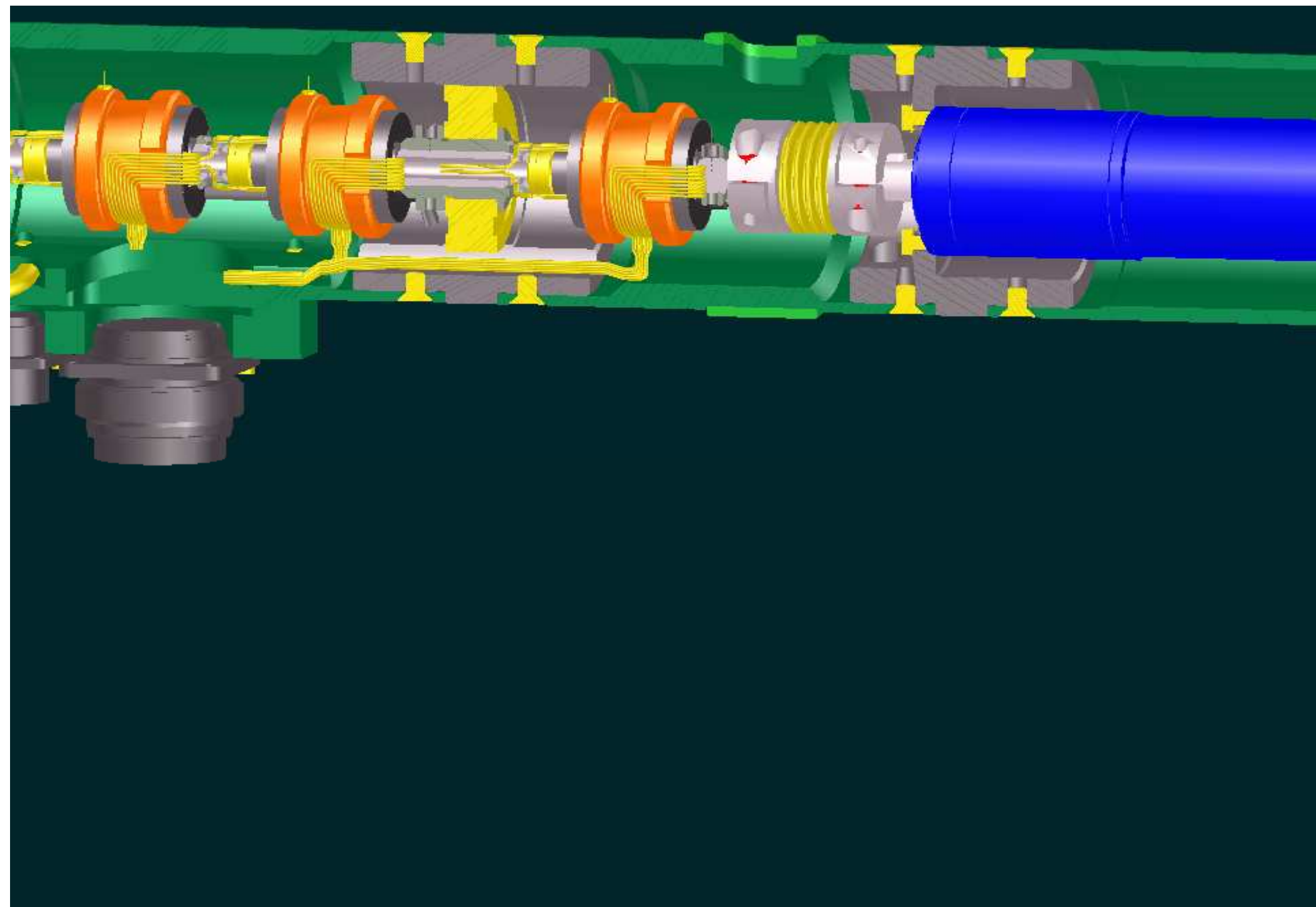


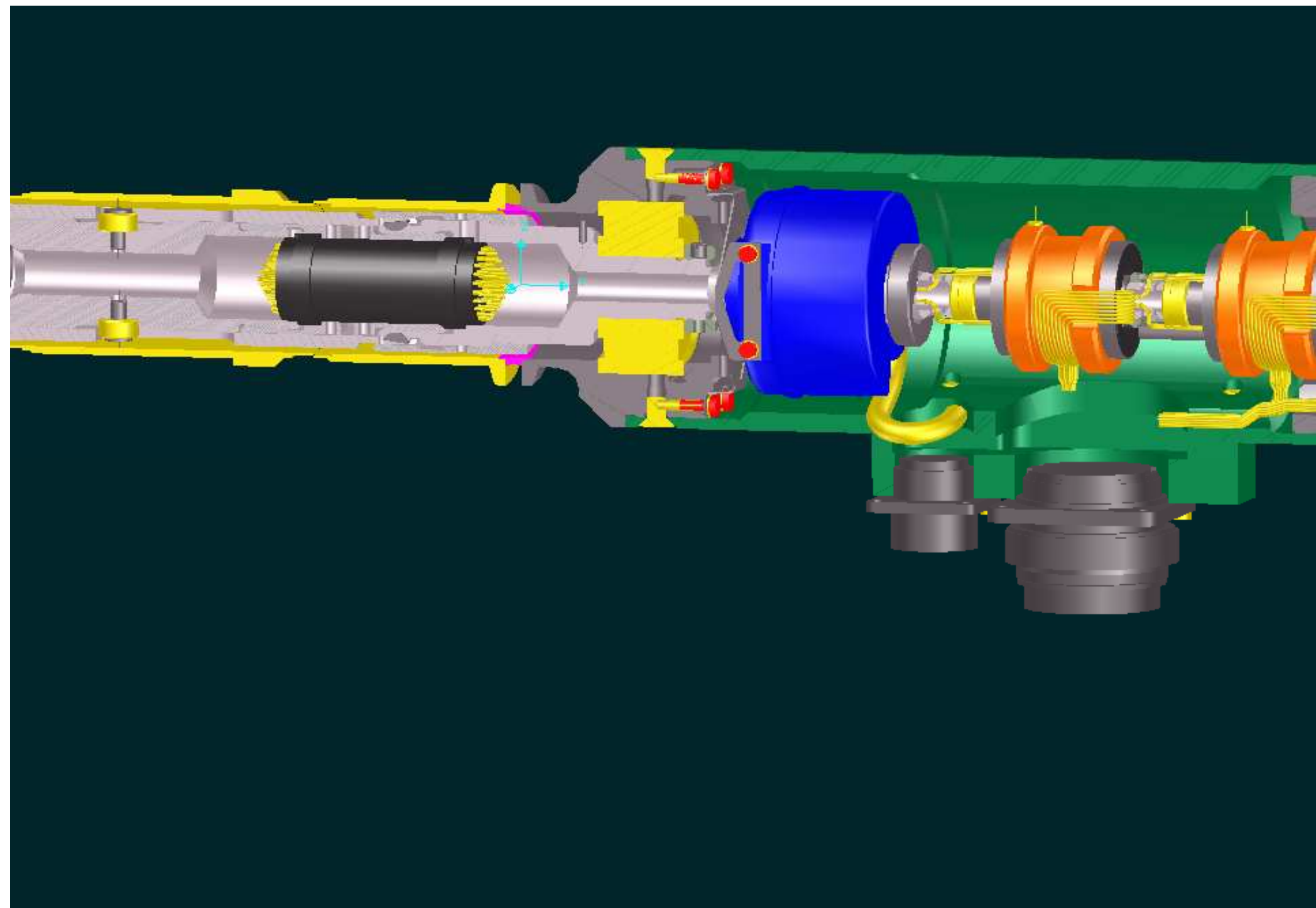
# New Mini Rotation Unit

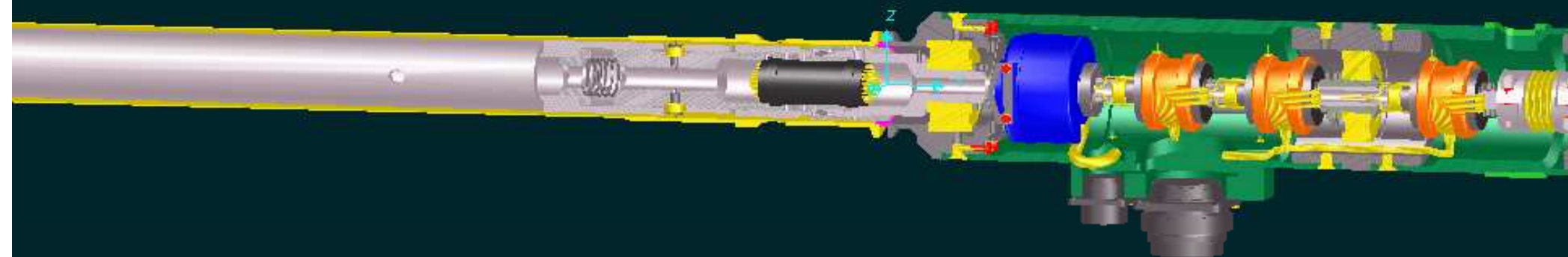
- ◆ A new mini rotation unit has been developed
- ◆ Smaller ( $\sim 0.5$  m), lighter ( $\sim 5$  Kg) and easily aligned to magnet anticryostat
- ◆ Prototype has been produced and is being mounted
- ◆ Eliminates the heavy and cumbersome old TRU support
- ◆ Up to 54 channels (dipole shafts needs 4x12)
- ◆ Selection of segments within a super-segment is done externally, at the level of PCI-PXI crate

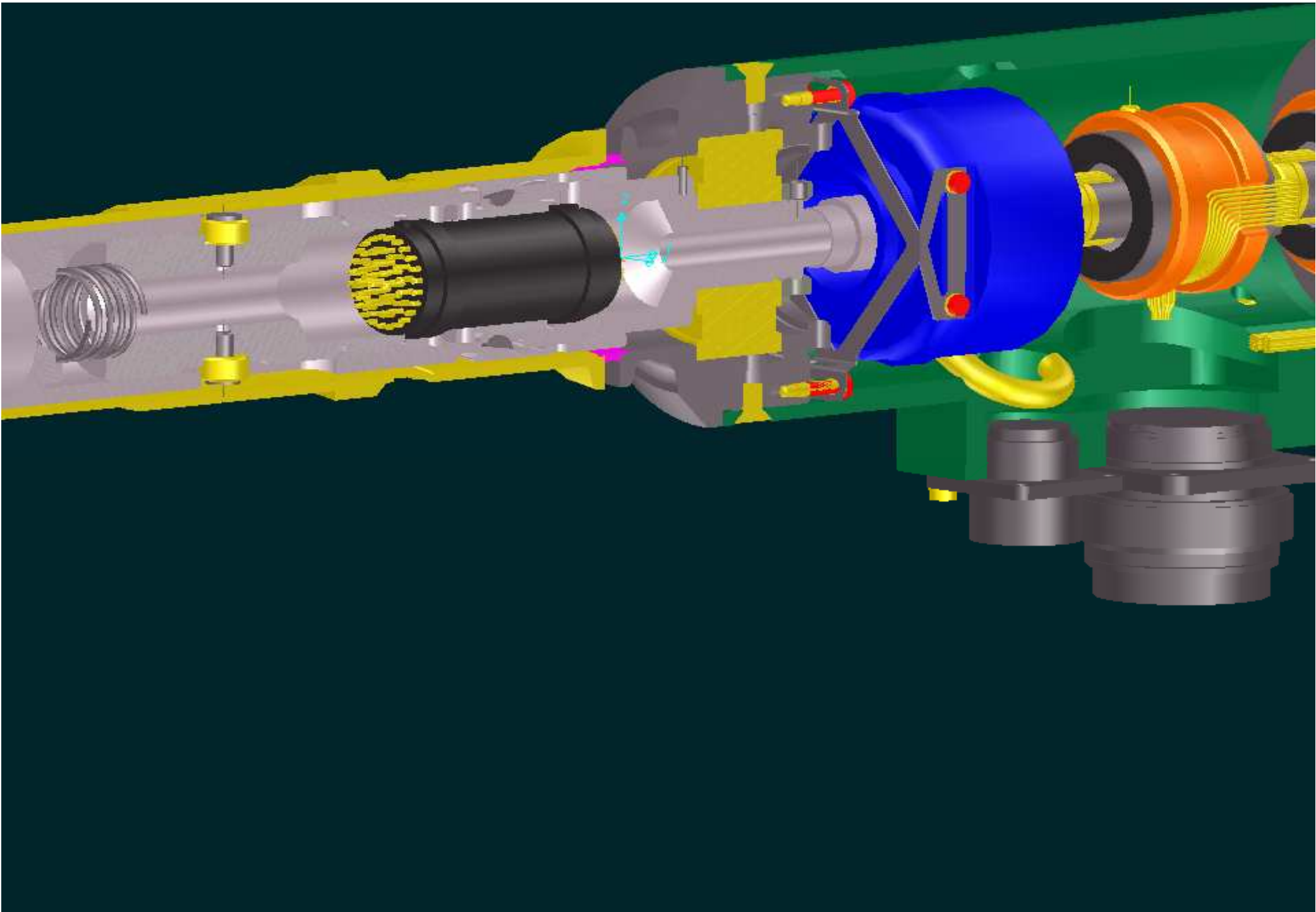






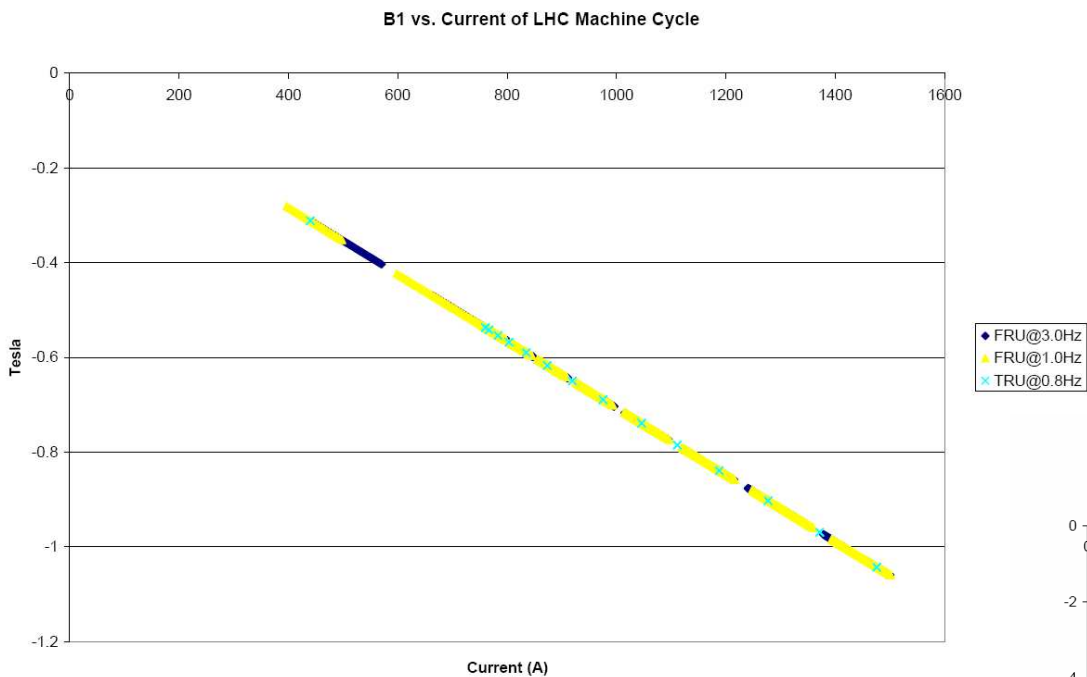




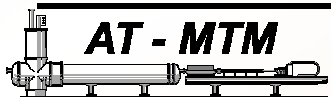
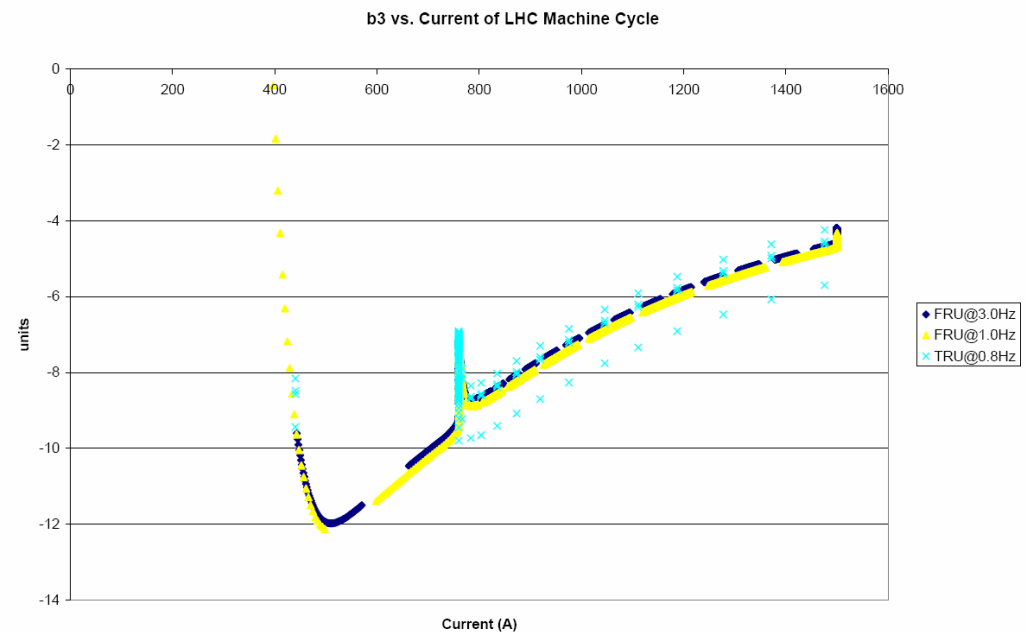




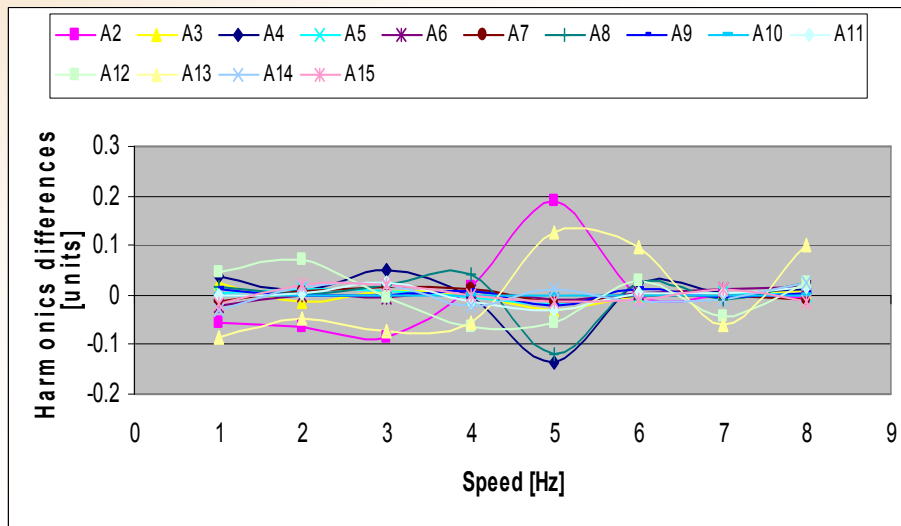
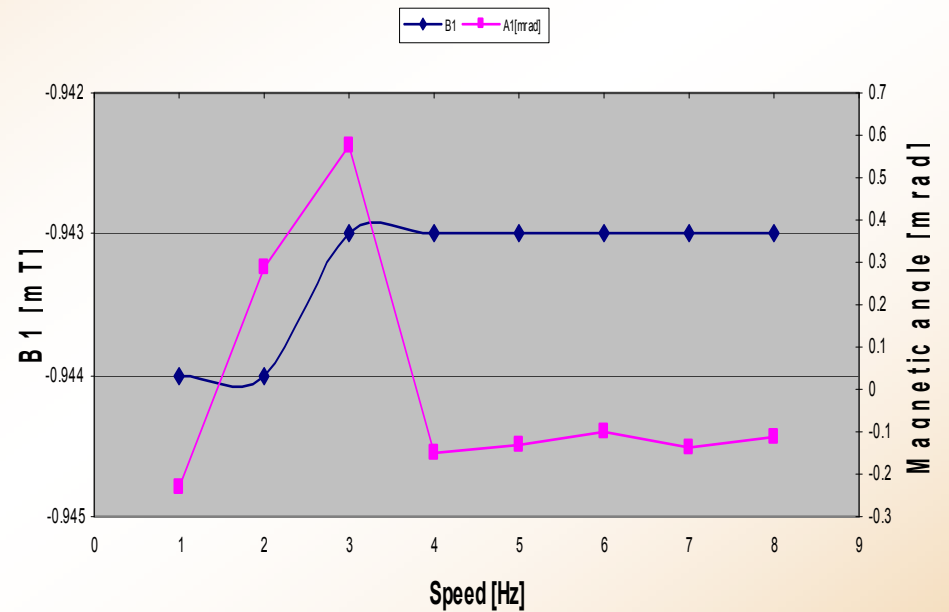
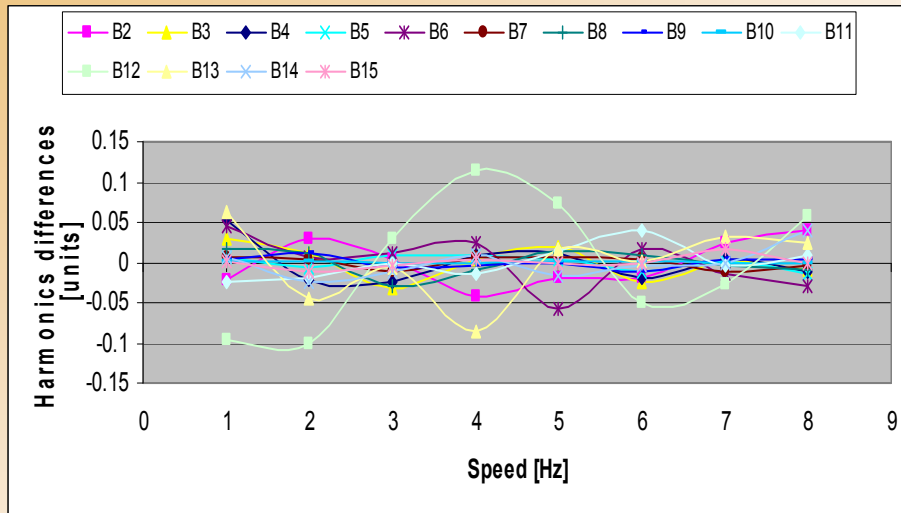
# Results with Fast Rotating Unit



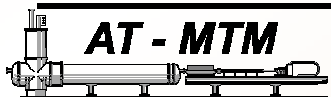
◆ Old electronics and modified old rotation unit used



# Preliminary results of harmonics on a dipole



- ◆ Results from a central super-segment analysis
- ◆ 10 A current at warm on a LHC dipole
- ◆ No sign of harmonics change with the speed
- ◆ Small change in magnetic angle, and B1 stable





# Conclusions

- ◆ **FAME project is on its final phase**
- ◆ **Mechanics of the rotating coils has proven its ability to turn at around 9 Hz without disturbances**
- ◆ **New rotation unit designed and produced in short time to be tested soon**
- ◆ **New Digital Integrators are in prototype production phase and feature very good results**
- ◆ **New shaft with smaller surface are well advanced**
- ◆ **Final tests with all these new elements are programmed for this Autumn**

