

Understanding Concussion

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The Referee Consensus Solver

1. Properties

Our primary effort is to understand the changes in brain function caused by concussion.

The Department of Neurological Surgery
at the University of Pittsburgh



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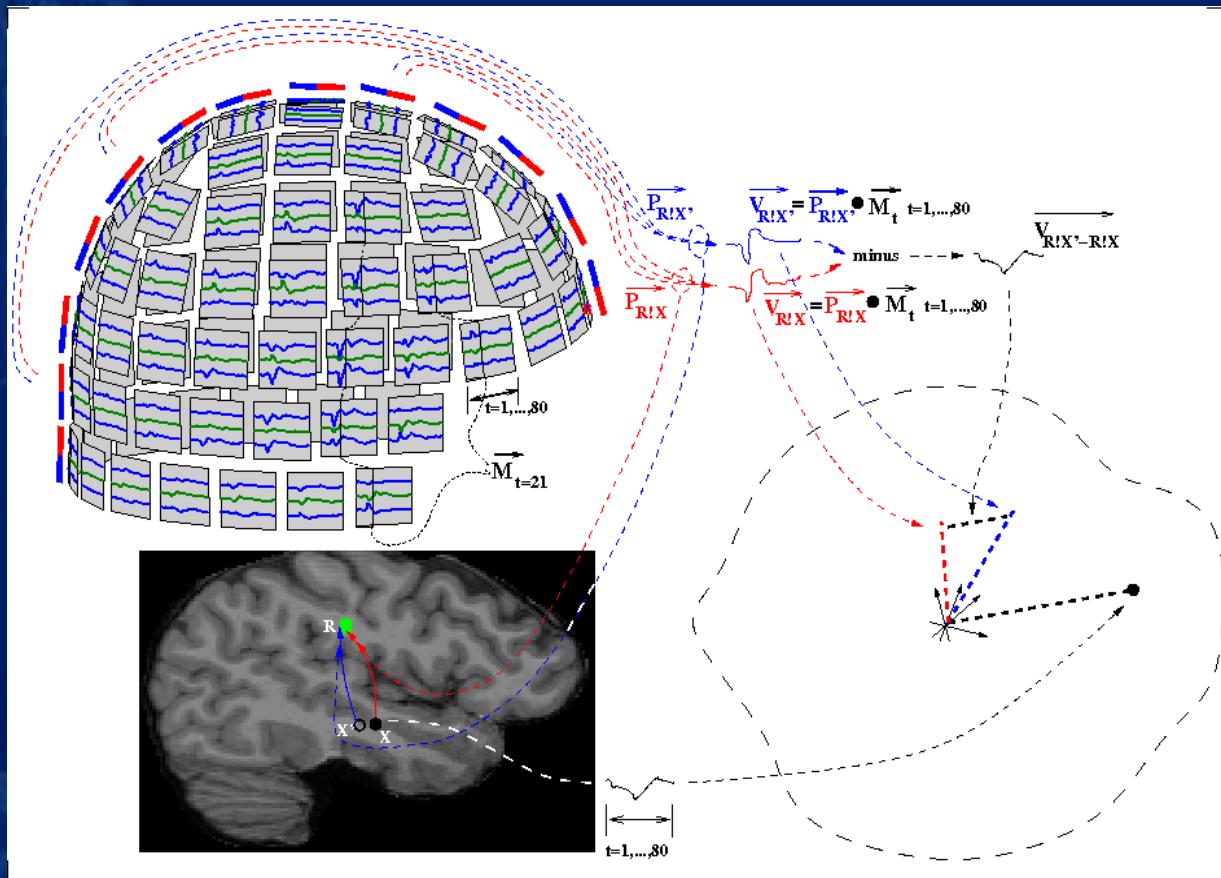
We record the magnetoencephalogram (MEG) during a variety of tasks.



The Referee Consensus Solver

1. Properties

We have discovered a new way to extract localized high fidelity neuroelectric recordings from the MEG, referee consensus processing.



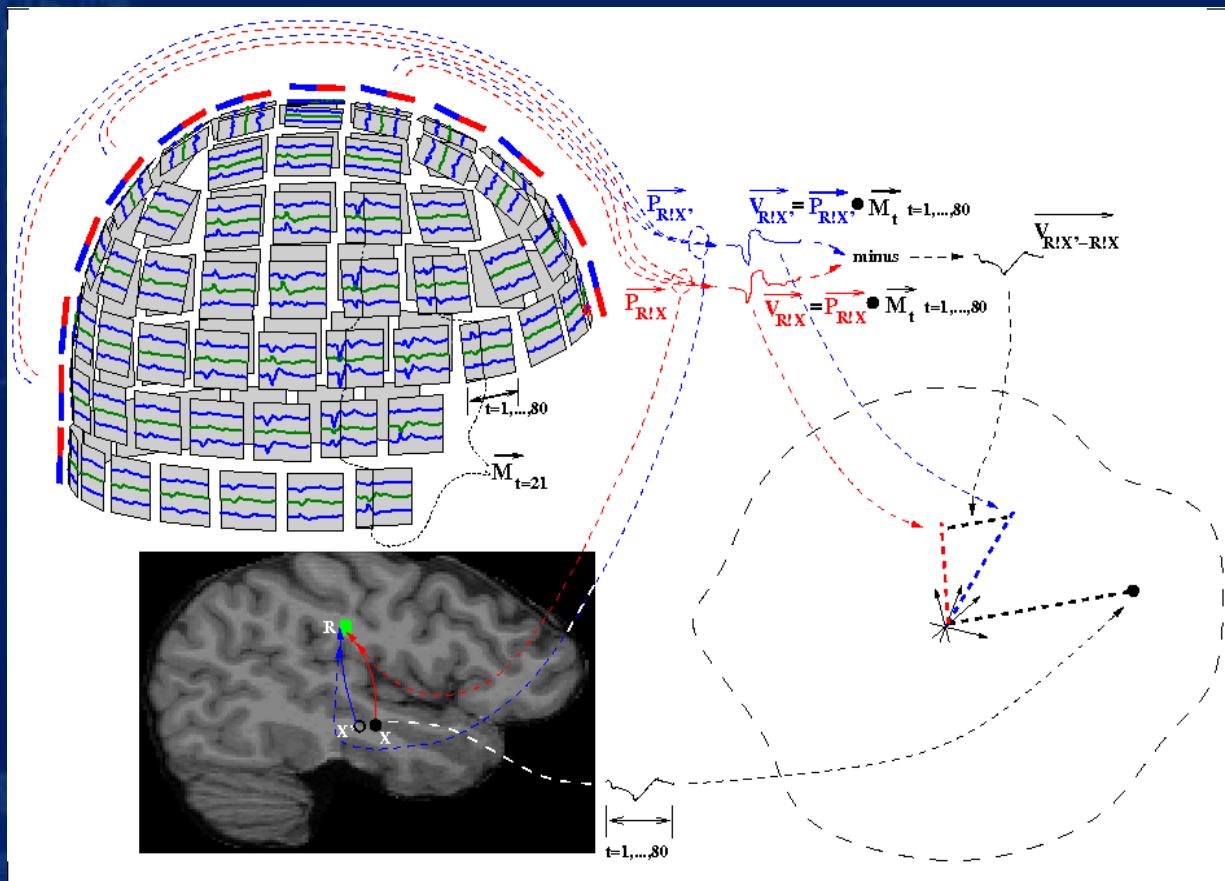
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The Referee Consensus Solver

1. Properties

The processing requires ≈ 50 cpuHours per second of recorded MEG data.

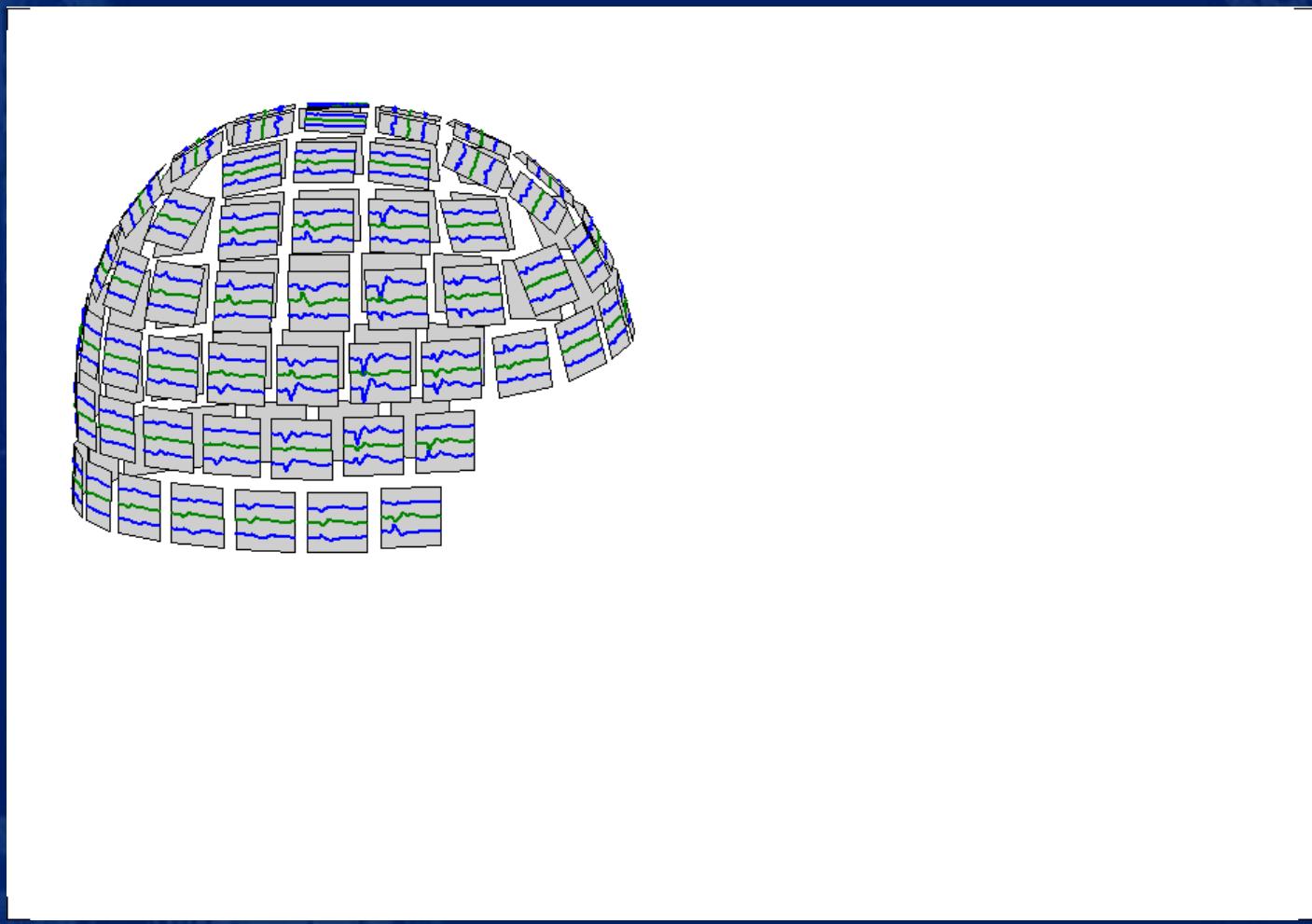


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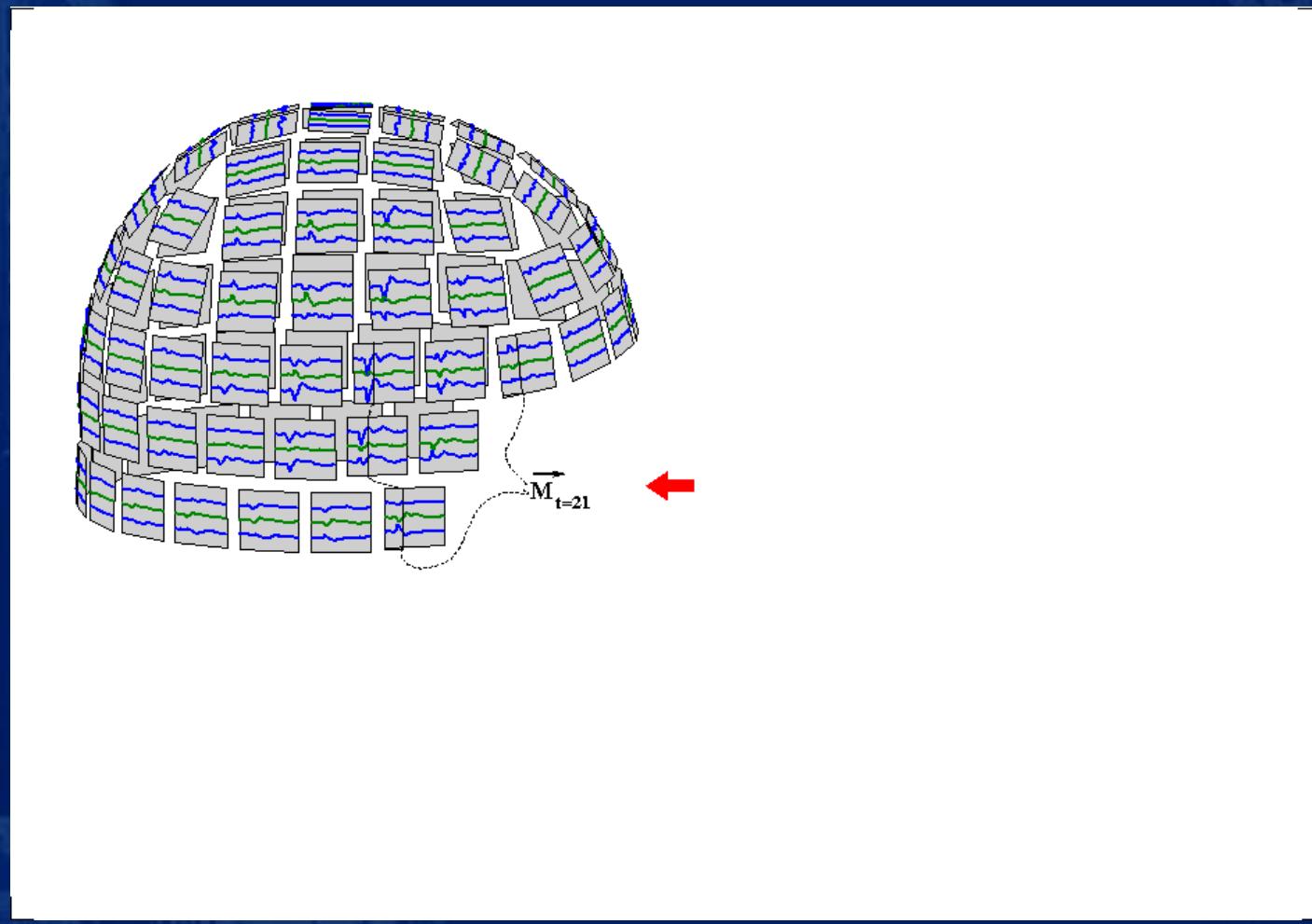
Inside the liquid helium dewar is an array of 102 1"x1" chips, each with 3 magnetic field sensors.

Hence the 3D “shape” of the magnetic field around the head is sampled at 102 points .



This 3D snapshot of the “shape” of the magnetic field is obtained 1000 times per second.

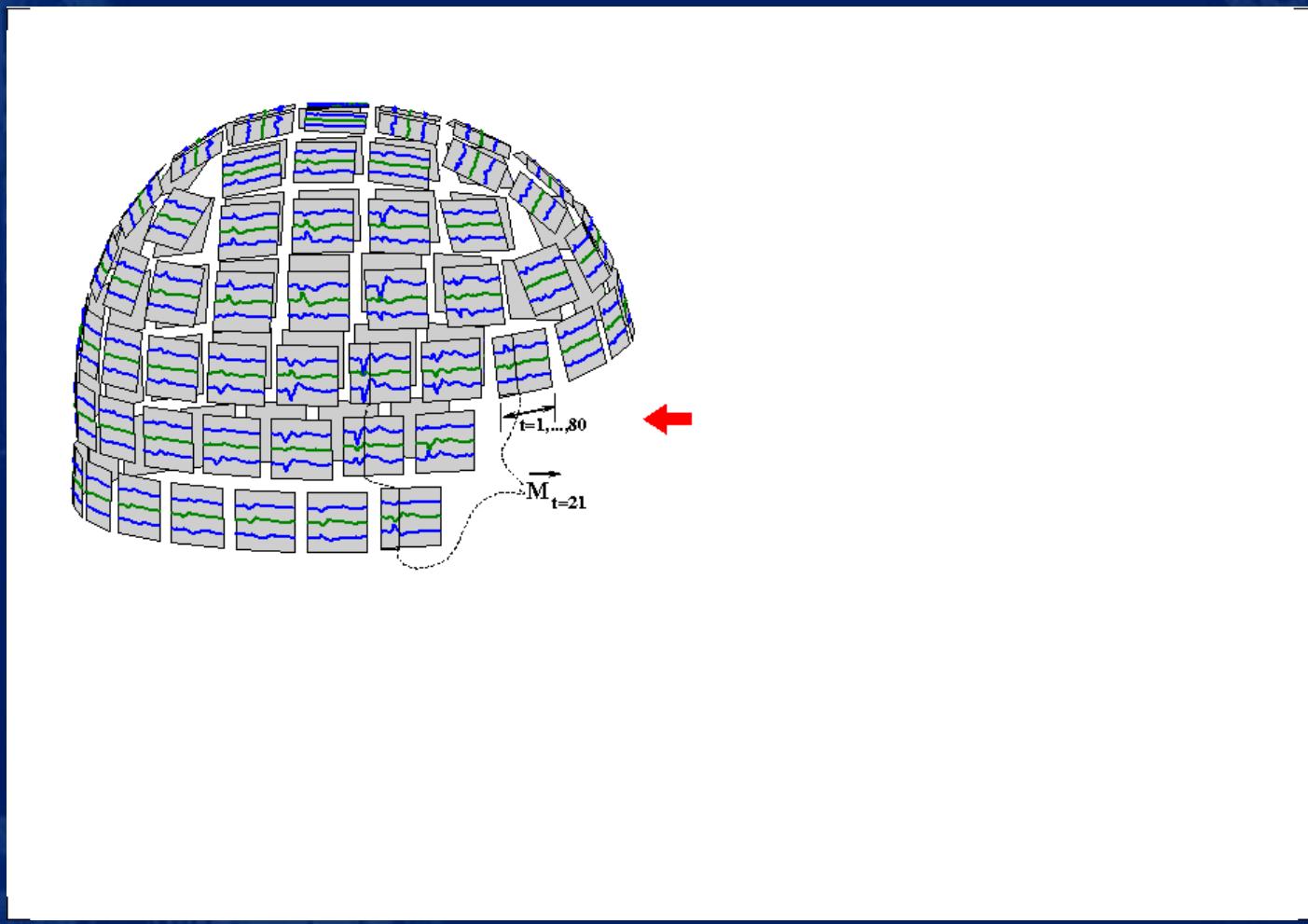
Each snapshot is a set of 306 measurements at a particular time and is designated: \mathbf{M}_t



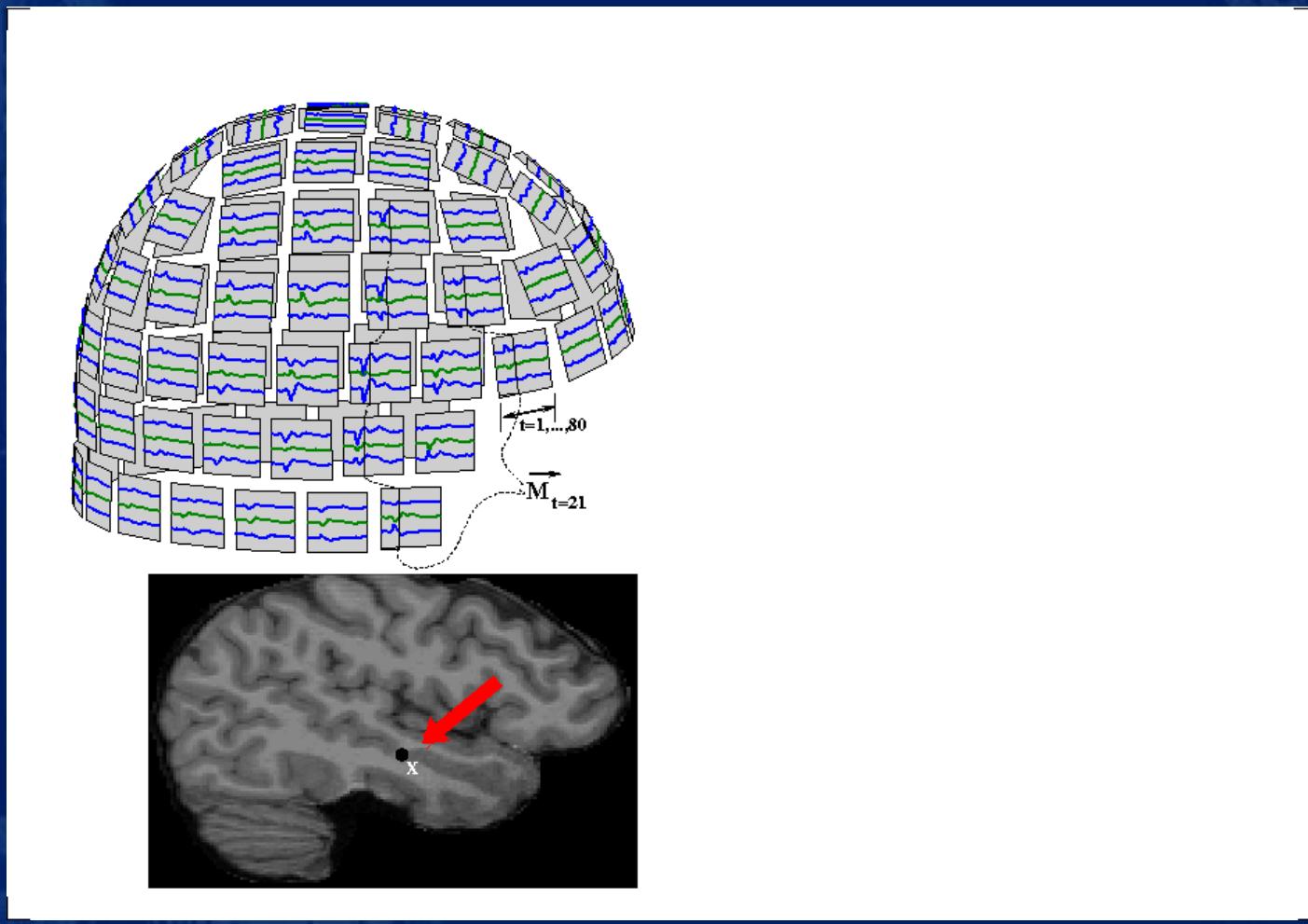
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The referee consensus solver uses 80 snapshots at a time.

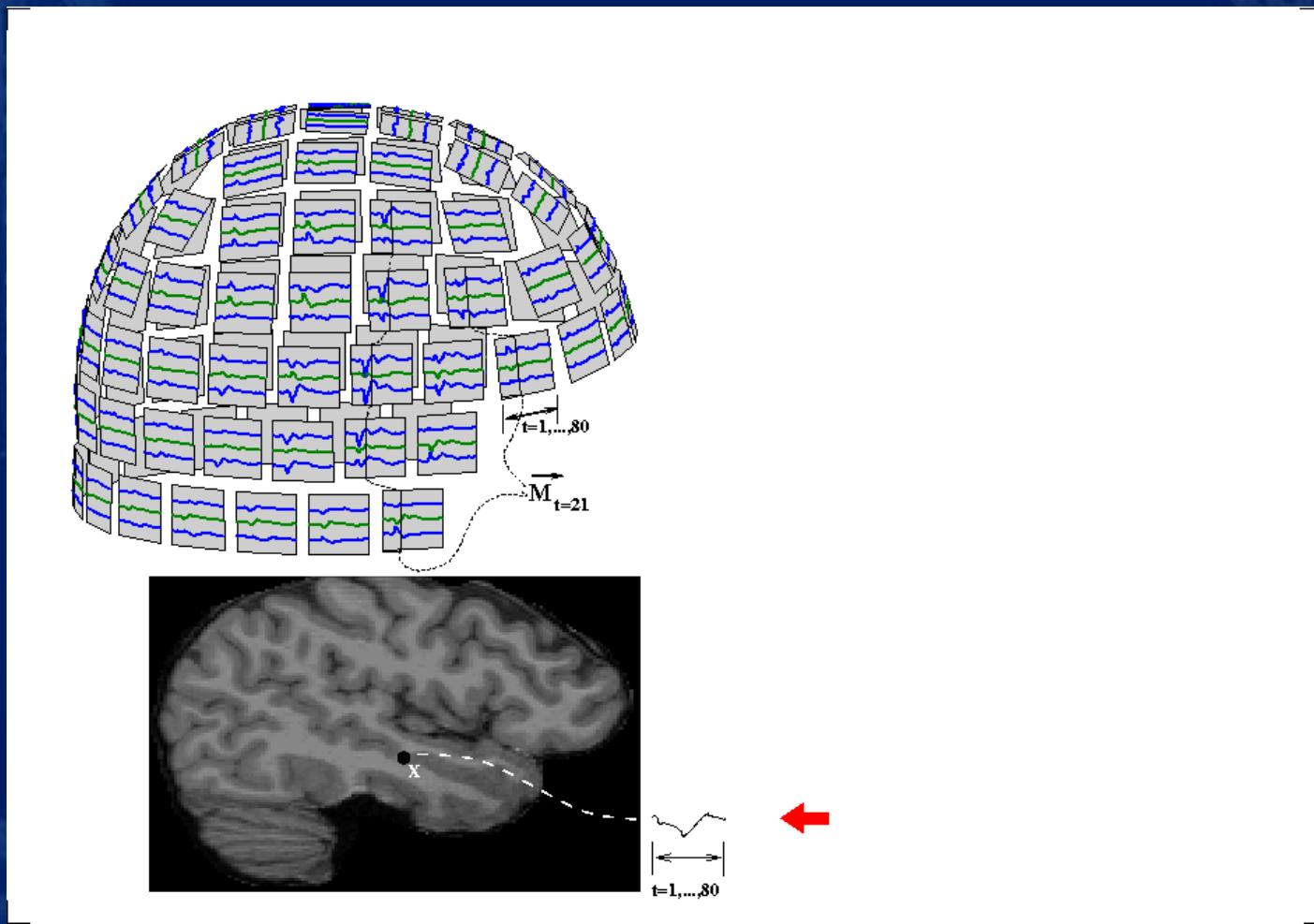


Given a specific location in the brain, **X**, the referee consensus cost function is used to determine if an electric current at **X** is contributing significantly to the shape of the magnetic field.

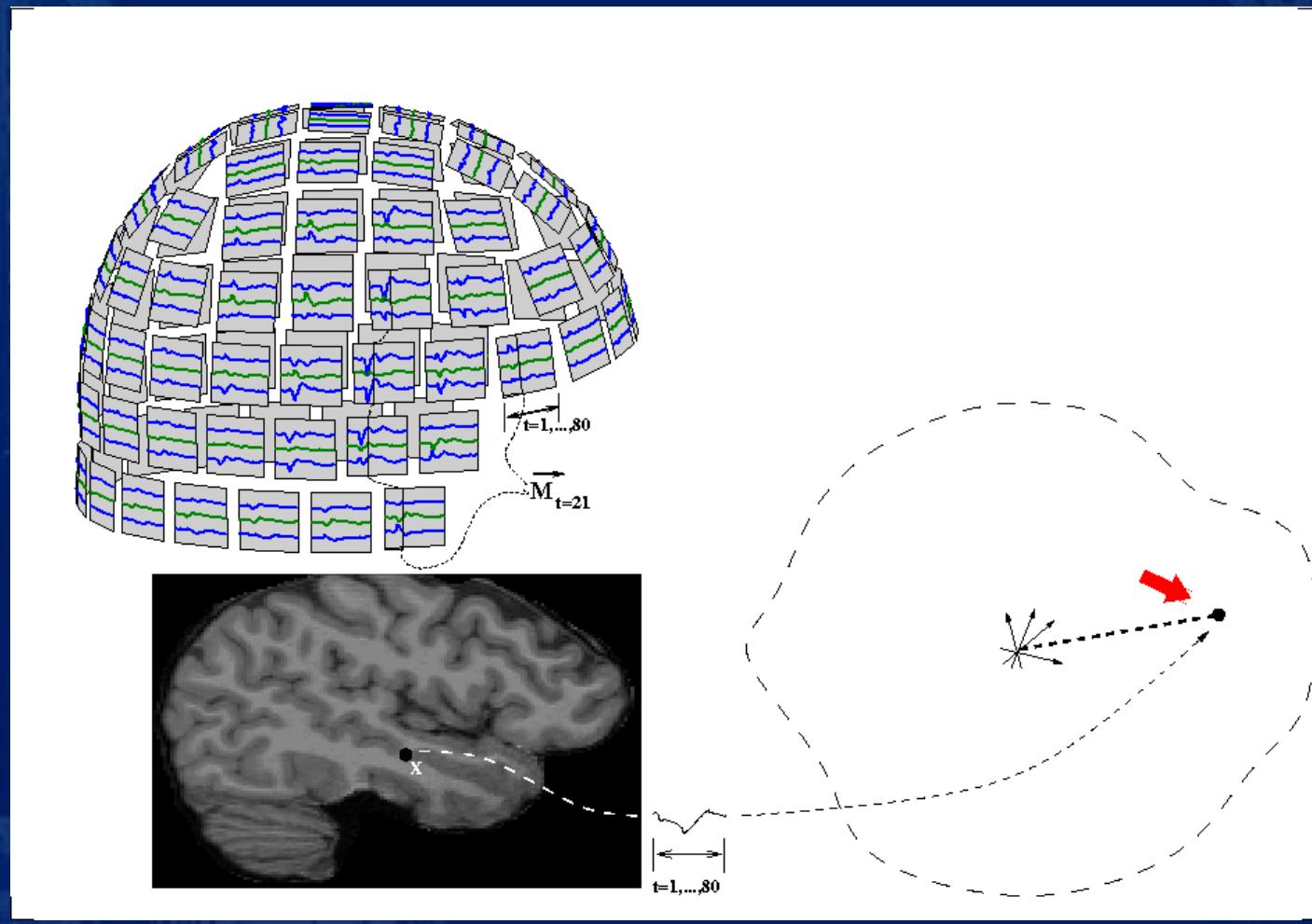


Given a specific location in the brain, **X**, the referee consensus cost function is used to determine if an electric current at **X** is contributing significantly to the shape of the magnetic field.

As part of this determination the procedure produces a high fidelity estimate of the time course of the electric current at **X**.



We can represent the true 80-point time course of the current at \mathbf{X} as a vector in an 80-dimensional space.

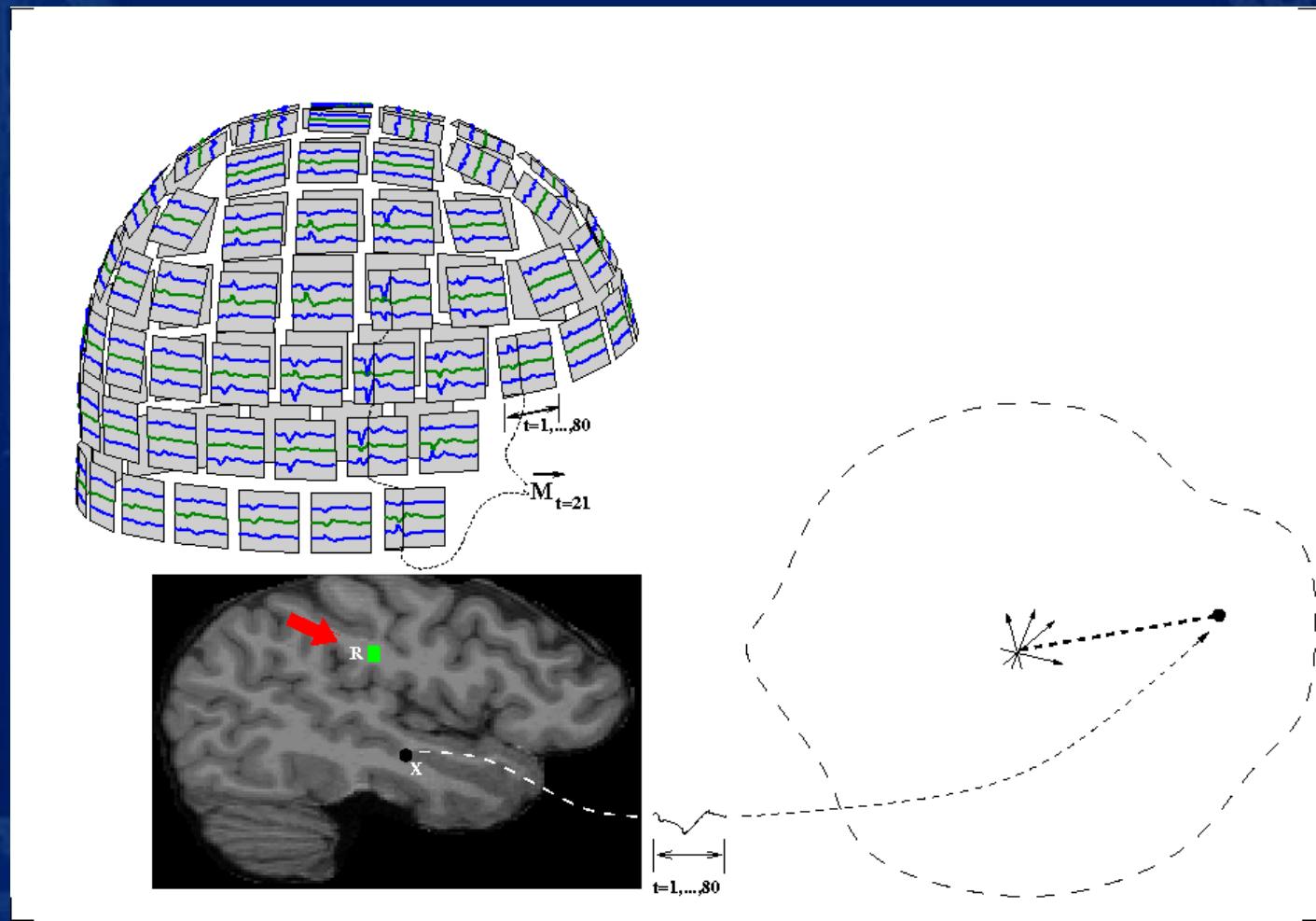


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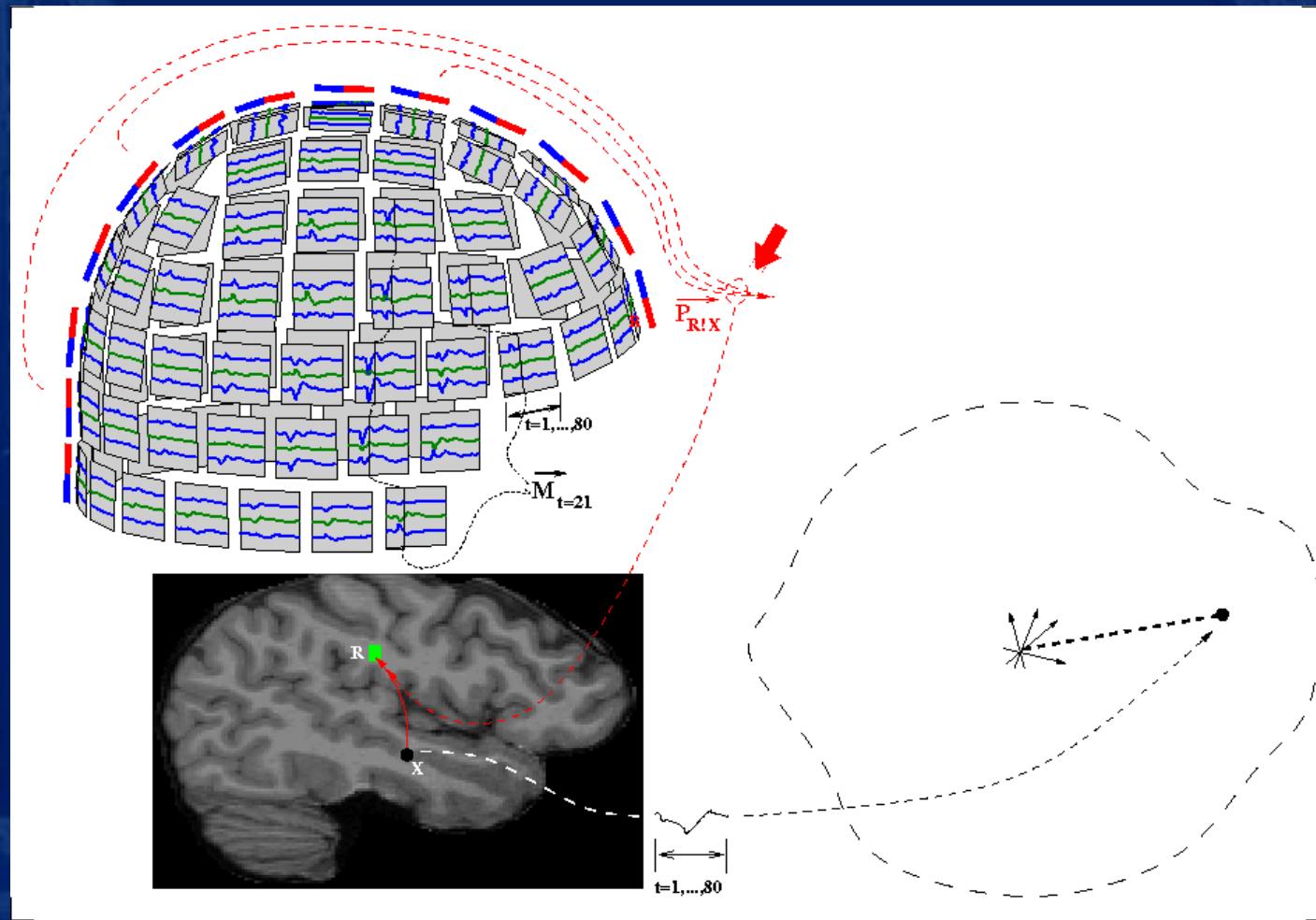


We obtain an estimate of that time course from the “point of view” of **R**, a location at a distance from **X**, a “referee.”

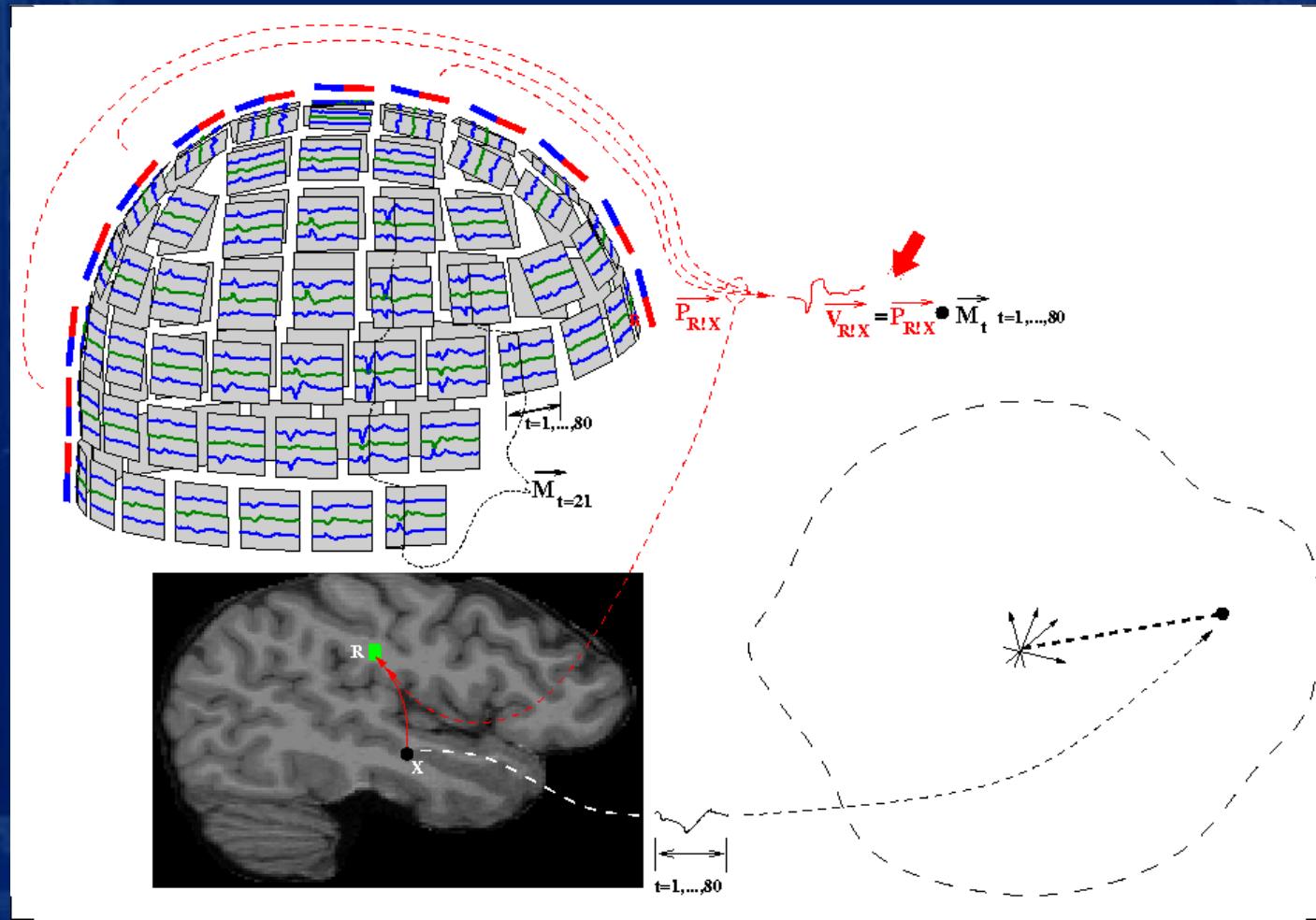
We will combine estimates from many referees to (1) decide if a non-zero current is present and (2) what its time course is, hence the name: “referee consensus.”



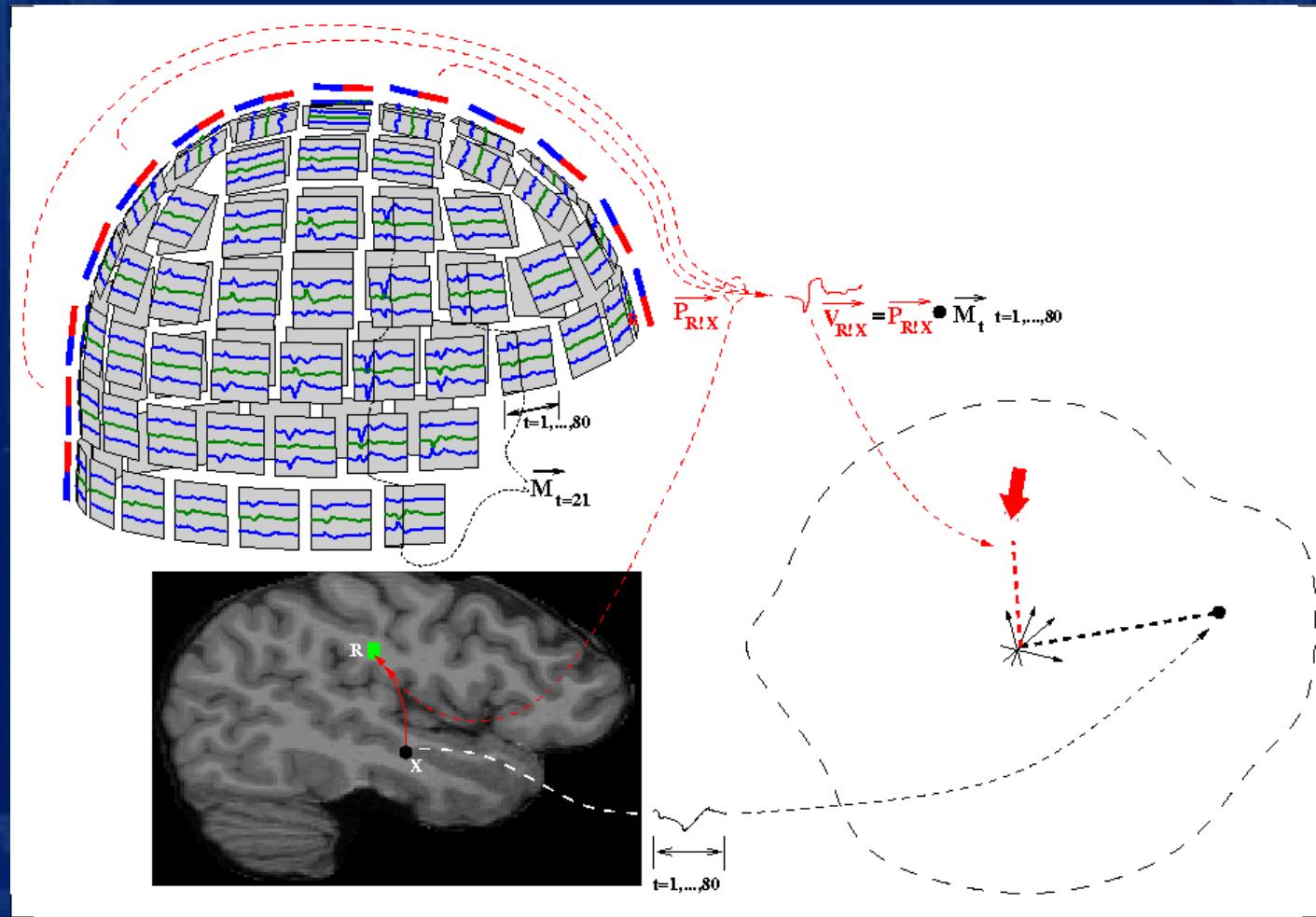
First we generate a projection operator, a filter, which produces an estimate of the current at **R**. We choose a filter which excludes any contribution to the estimate by the current at **X**. The filter is represented by the symbol, $\overrightarrow{P_{R!X}}$, where “**R!****X**” reads “**R** not **X**.”



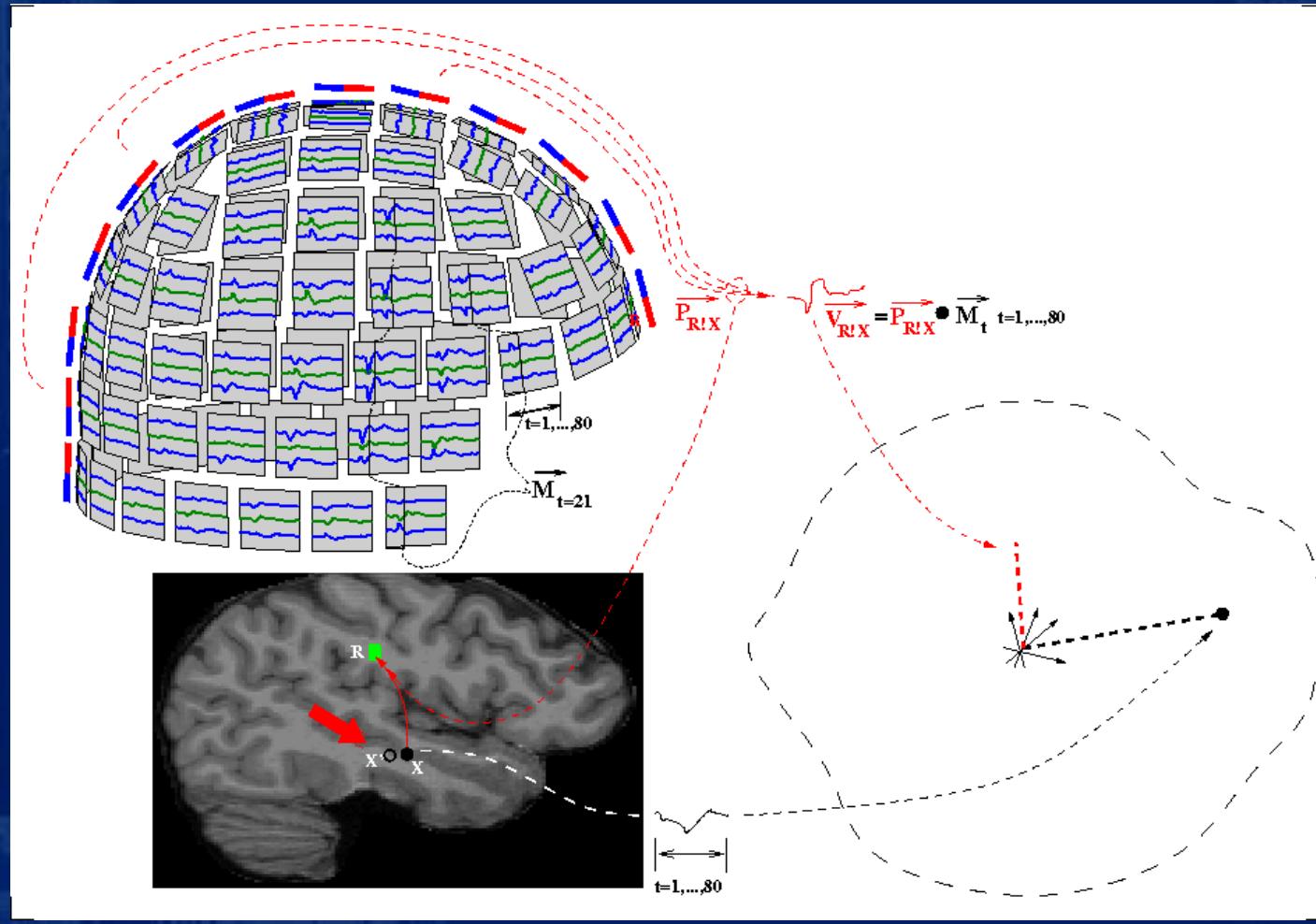
When we apply the filter to a sequence of 80 magnetic field snapshots we obtain $\overrightarrow{V_{R/X}}$, an estimate of the current waveform at R with no contribution from the waveform at X .



The vector, $\overrightarrow{V_{R/X}}$, may fall at any angle to the true waveform at X , i.e. they may be correlated. Here it is shown near the ideal angle of 90° .



We now pick X' , a point which is at 1 mm distance from X .

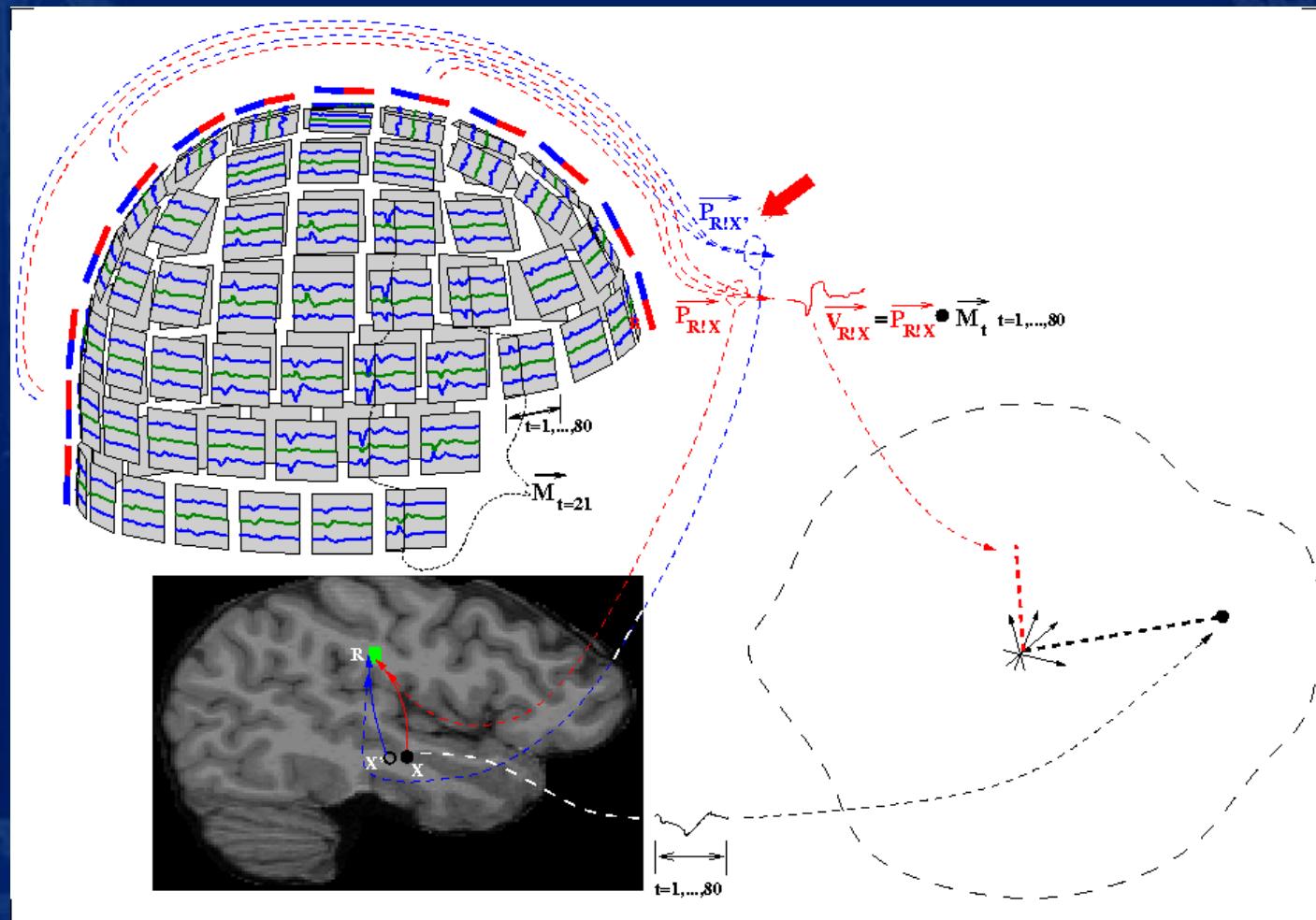


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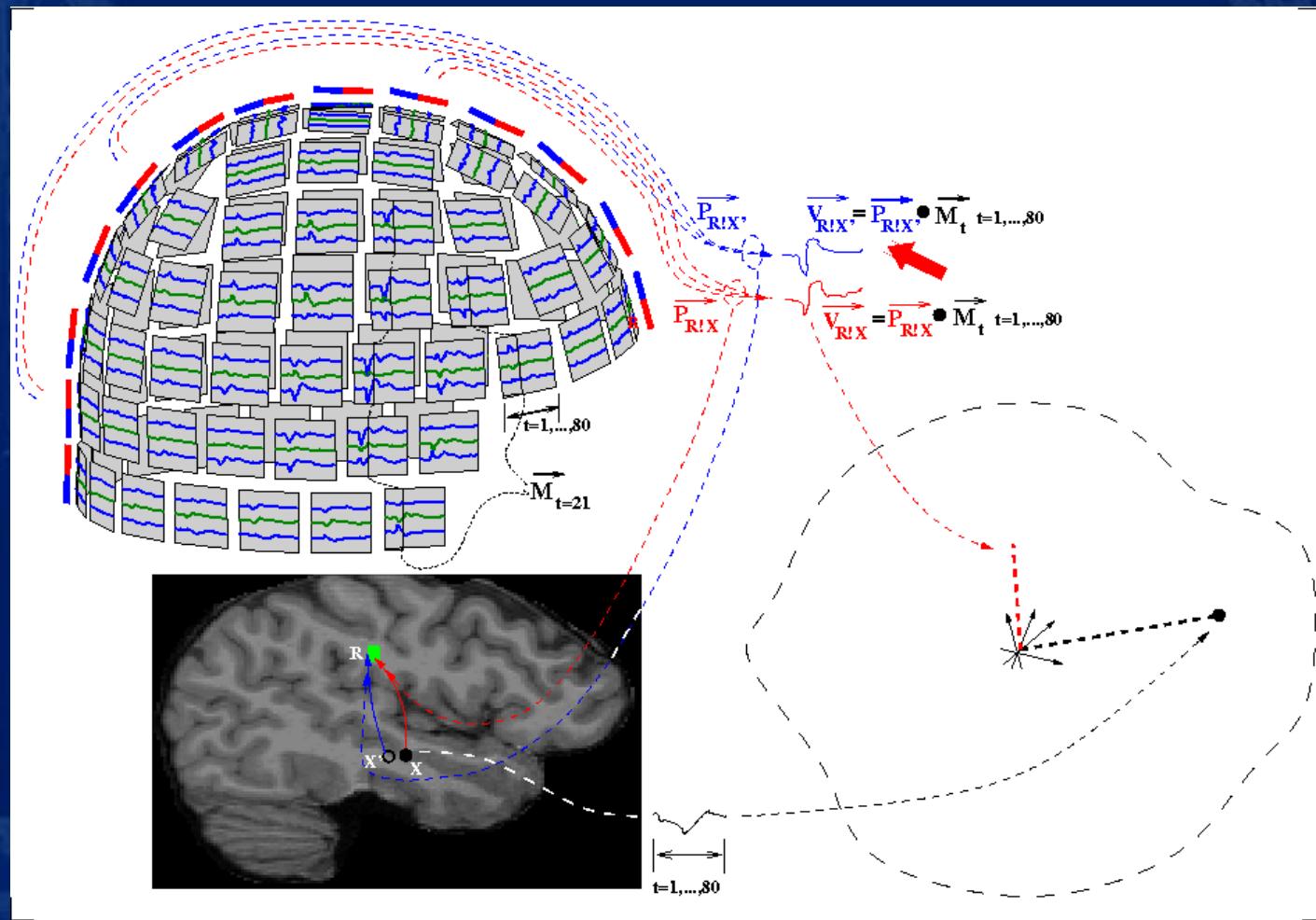


We now pick \mathbf{X}' , a point which is at a distance of 1 mm from \mathbf{X} .

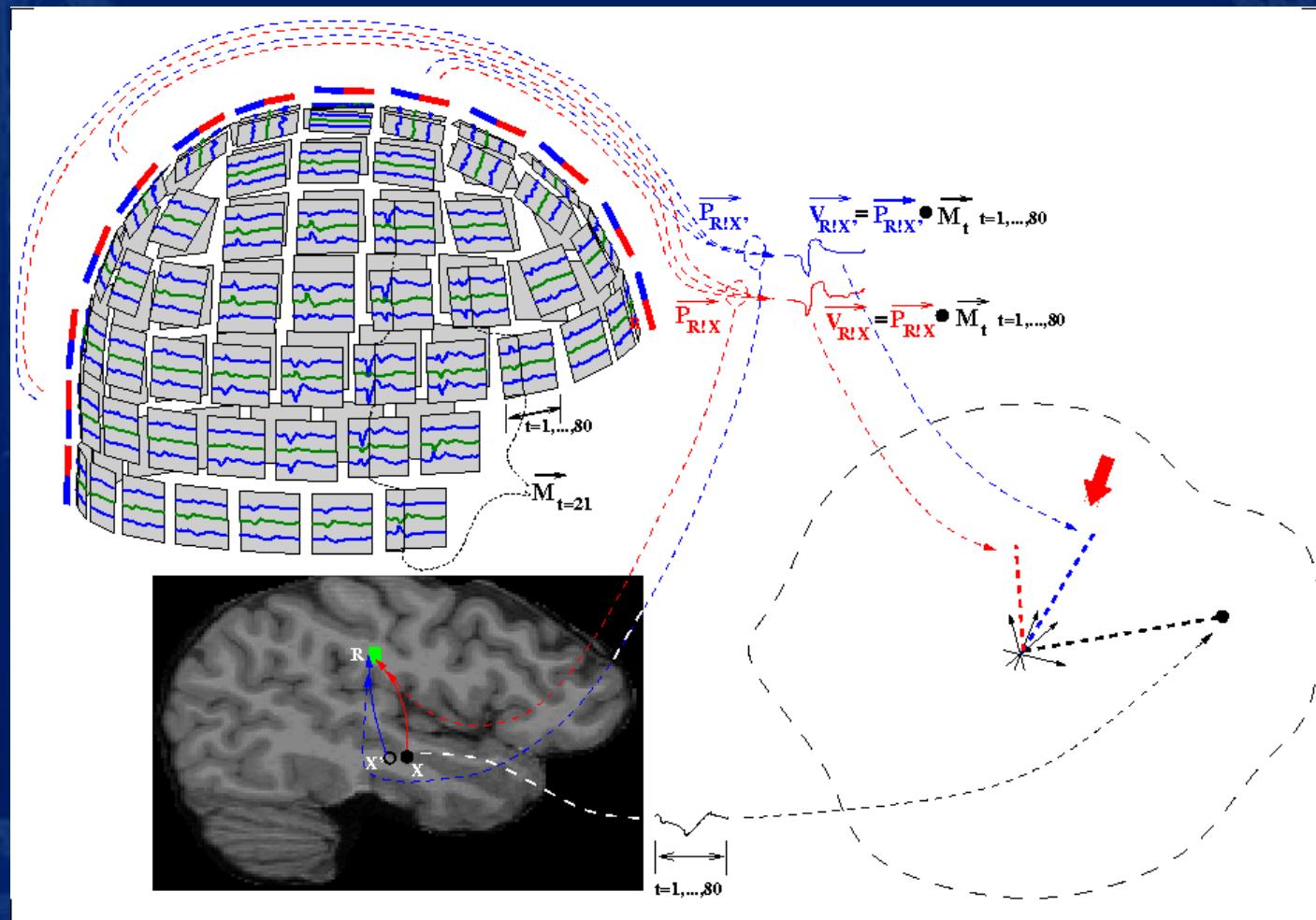
We generate a 2nd filter to produce an estimate of the current at \mathbf{R} . This time the filter, $\overrightarrow{P_{R|X}}$, is chosen to exclude any contribution to the estimate by the current at \mathbf{X}' .



Again we apply the filter to the sequence of 80 magnetic field snapshots. This time we obtain $\overrightarrow{V_{R!X'}}$, an estimate of the current waveform at R with no contribution from the waveform at X' .

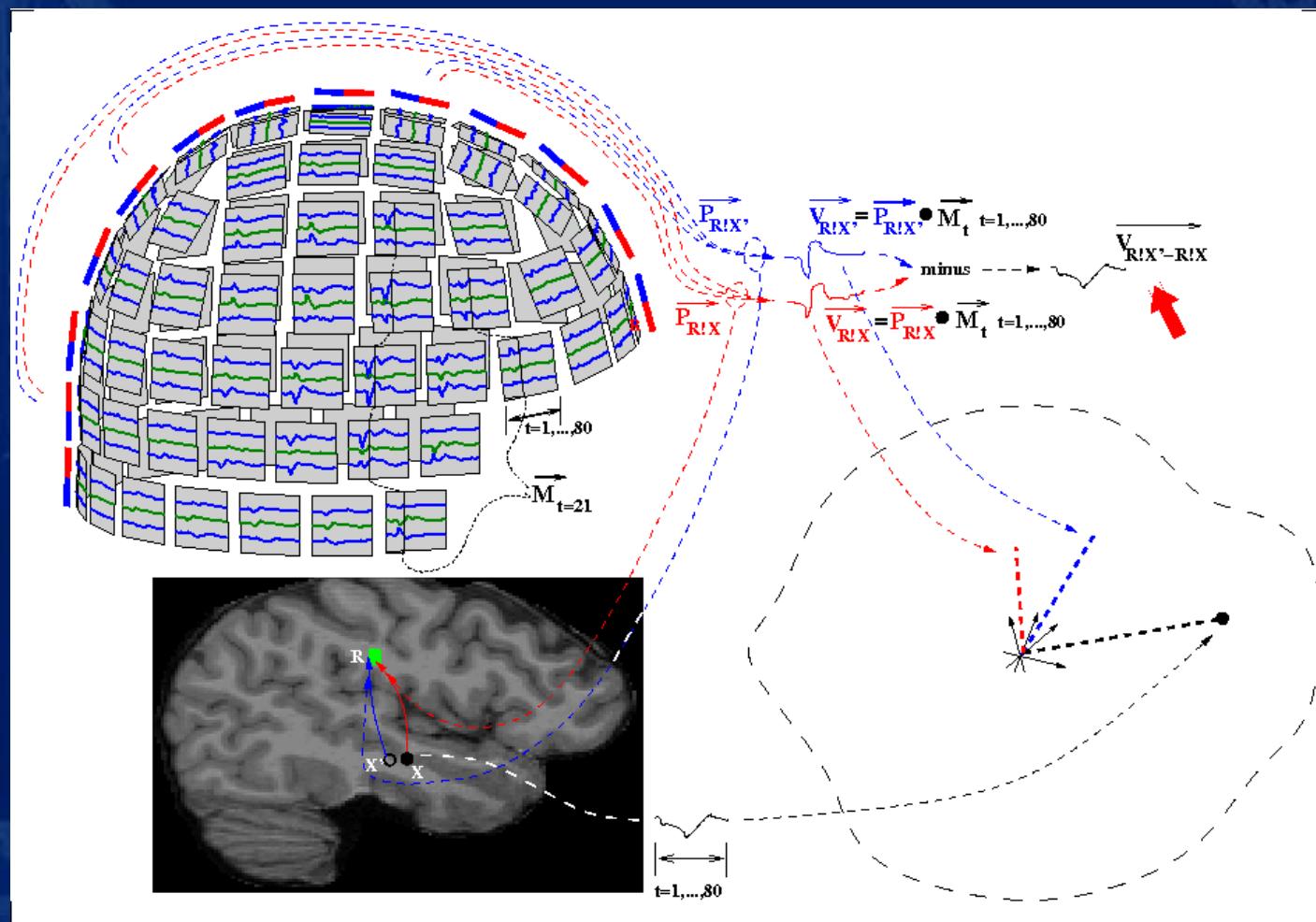


The $\overrightarrow{V_{R!X'}}$ vector falls between the $\overrightarrow{V_{R!X}}$ vector and the true waveform at X because the signal at X was not excluded by the 2nd filter, $\overrightarrow{P_{R!X'}}$. Another way to put this is that $\overrightarrow{V_{R!X'}}$ must include a component which is proportional to the true waveform at X whereas $\overrightarrow{V_{R!X}}$ need not.

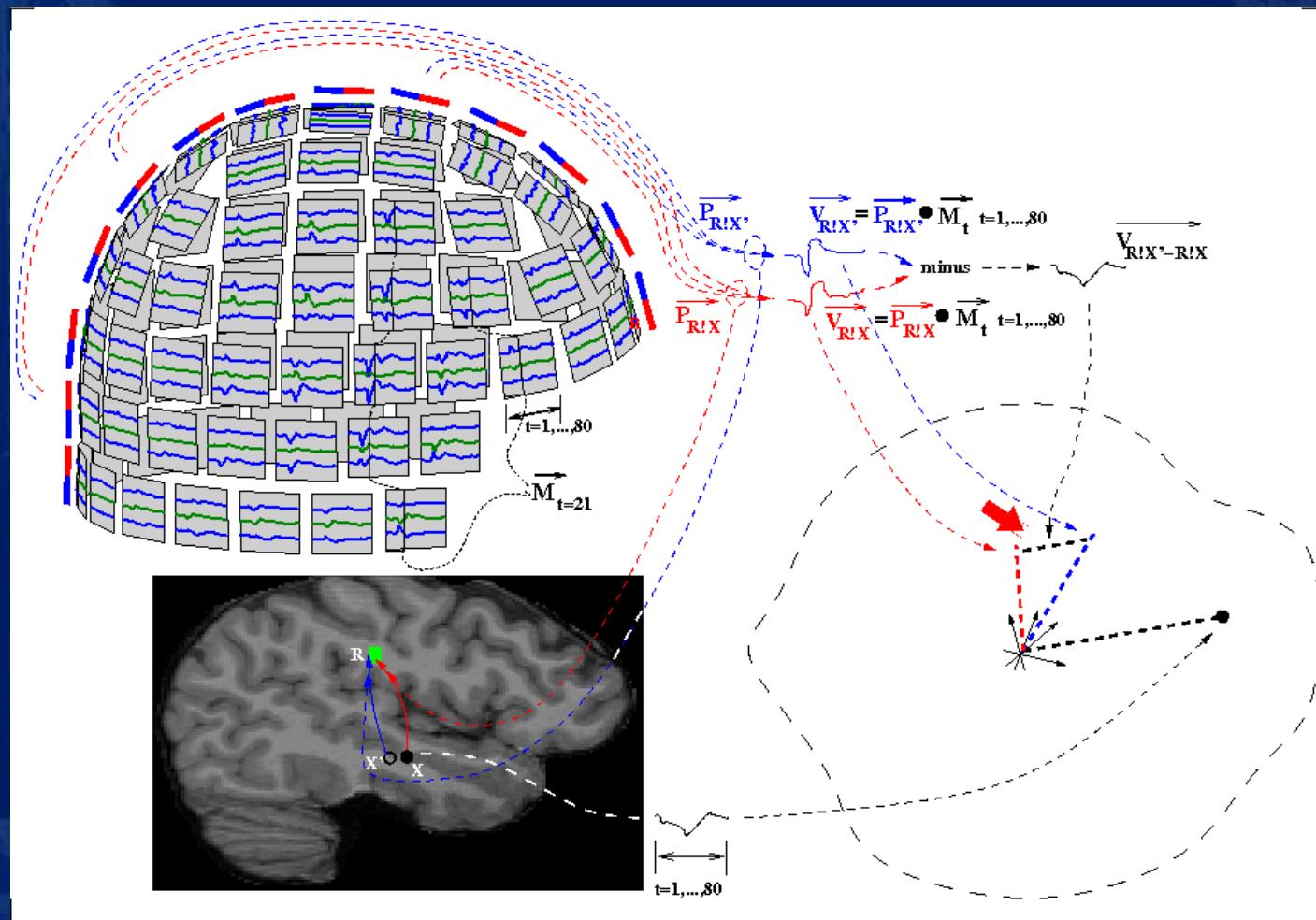


Finally we take the difference between $\overrightarrow{V_{R!X'}}$ and $\overrightarrow{V_{R!X}}$ to obtain an estimate of true waveform at X from the “point of view” of R but with the estimates of the current at R now subtracted away.

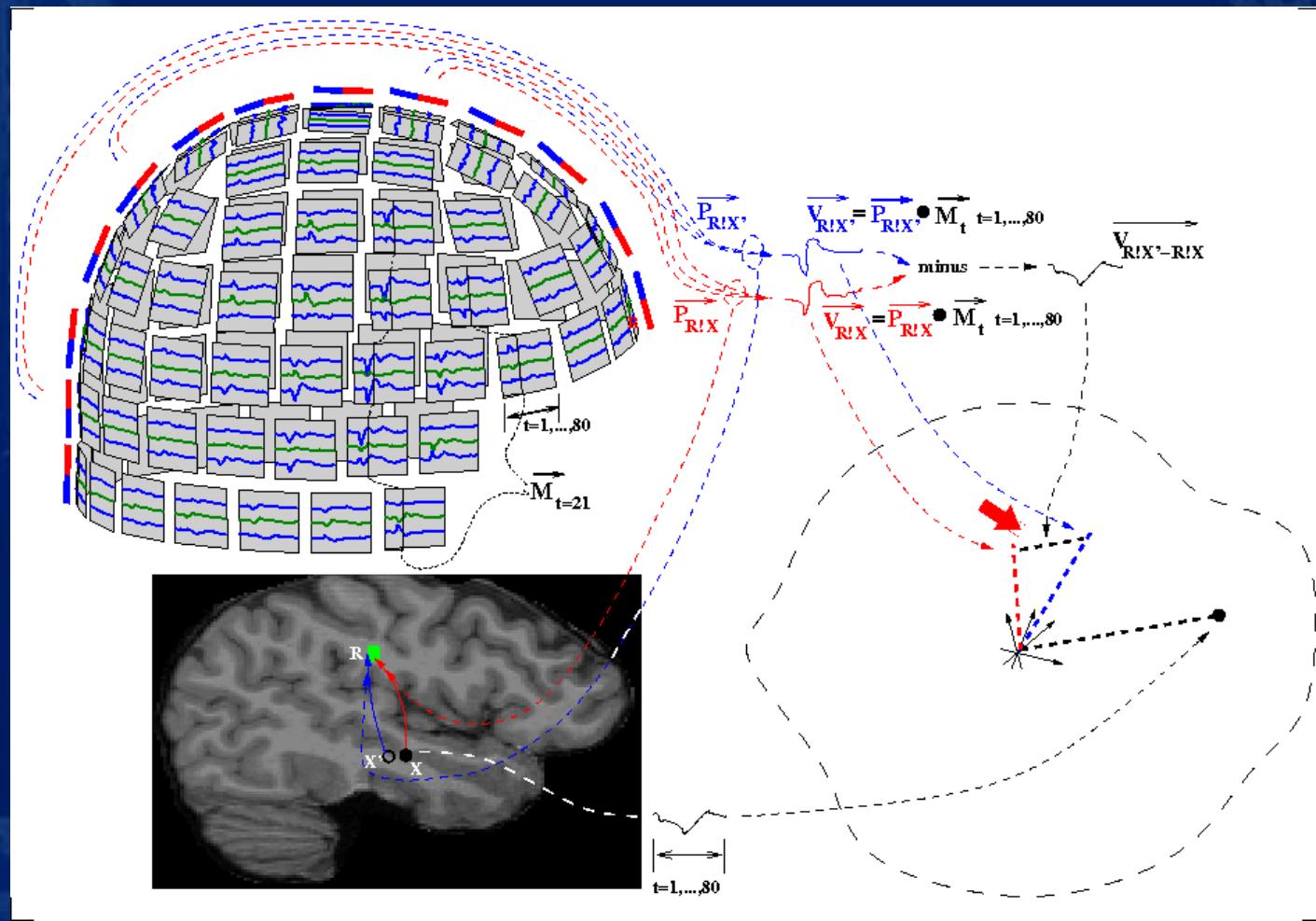
This also attenuates contributions to $\overrightarrow{V_{R!X'}}$ and $\overrightarrow{V_{R!X}}$ from all other sources both inside and outside the brain.



The difference vector, $\overrightarrow{V_{R!X'} - R!X}$, falls nearly parallel to the true signal at X . It is a “similar” waveform in that their shapes are nearly the same, i.e. they are highly correlated. Another way to put it is that this difference must include a simile of the true waveform at X and little else.



The referee consensus cost function calculation ...
... provides a statistically powerful “goodness of fit” measure.

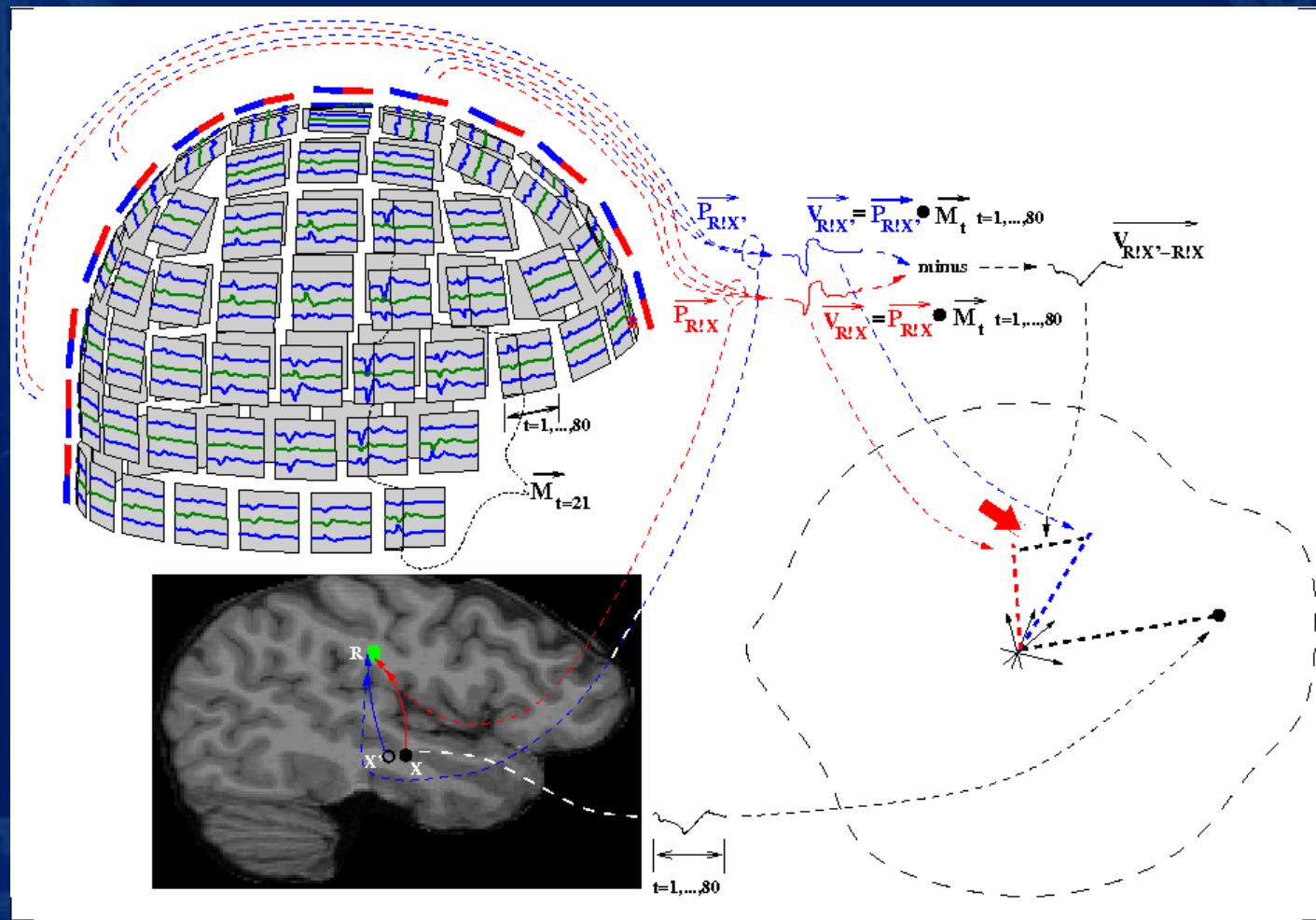


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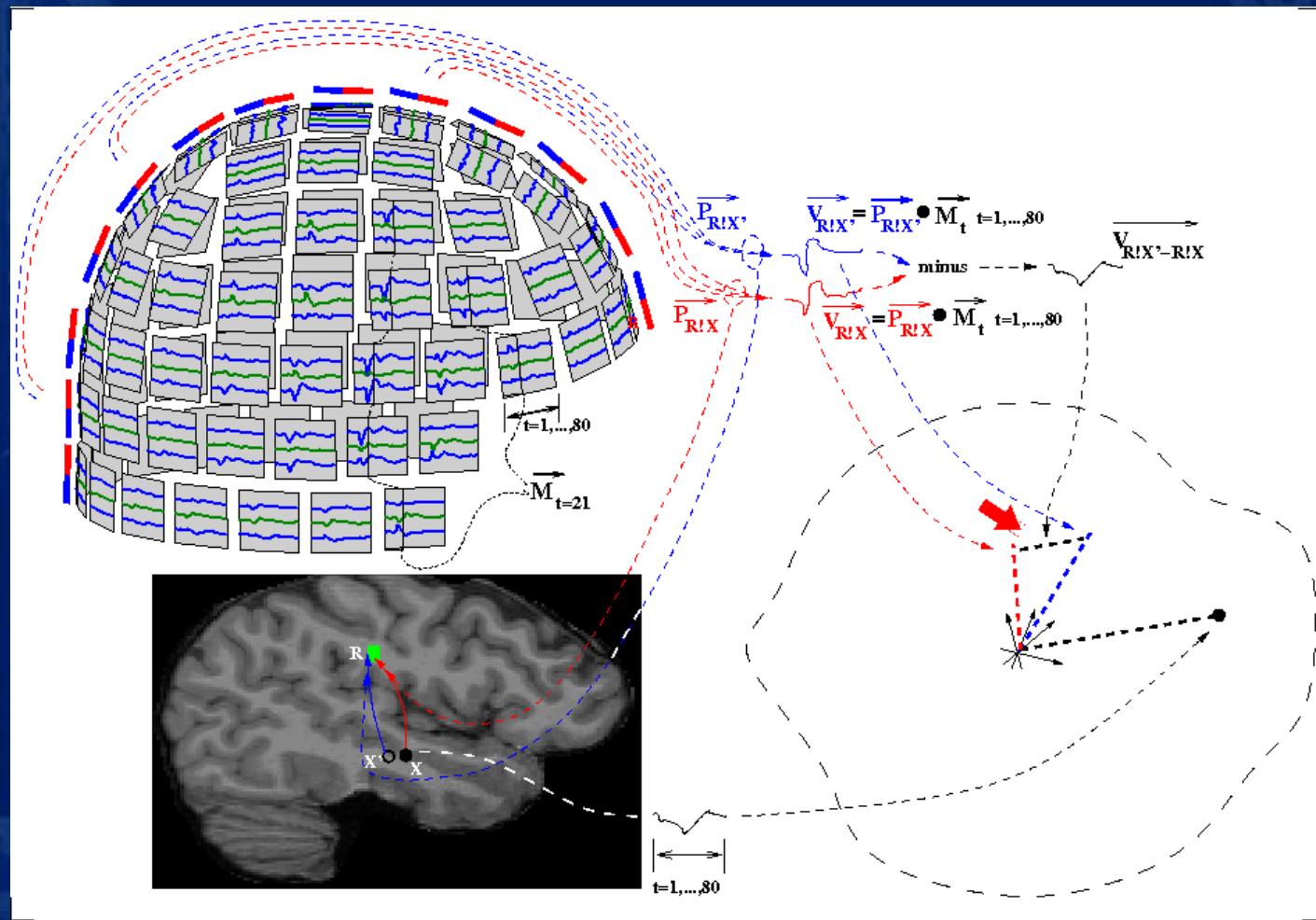
The referee consensus cost function calculation ...

... produces sufficient signal/noise enhancement to enable source identification and accurate time course measurement from single trial data.



The referee consensus cost function calculation ...

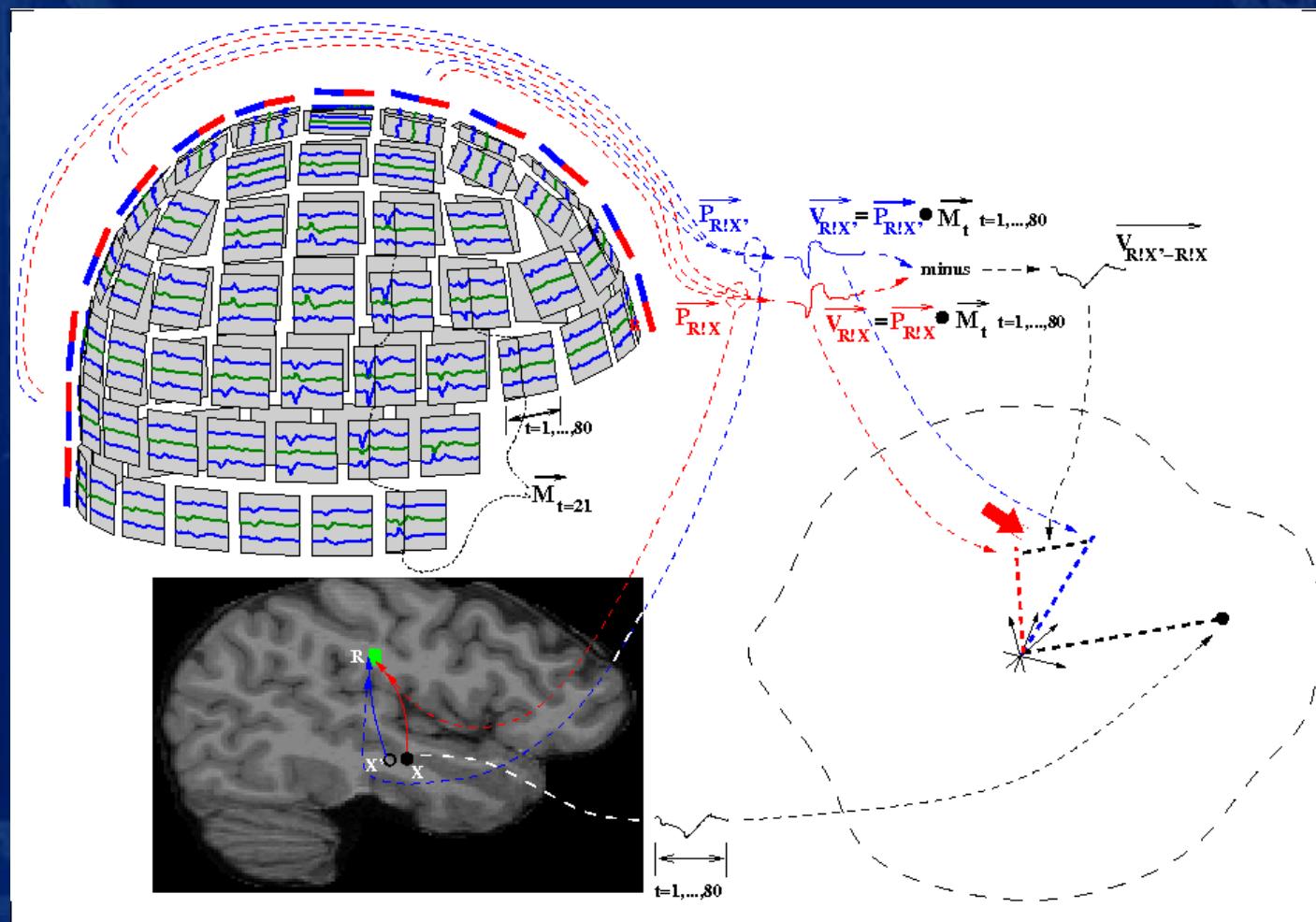
... isolates one source from all others, enabling identification and time course measurement of one source at a time ...



The referee consensus cost function calculation ...

... isolates one source from all others, enabling identification and time course measurement of one source at a time ...

... this makes the method most similar functionally to Equivalent Dipole Source Localization.



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