

Dispersion relations and differential equations for Feynman Integrals

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Based on collaboration with *A. von Manteuffel* and *E. Remiddi*

[\[arXiv:1602.01481\]](#), [\[arXiv:1609.xxxxx\]](#)

Dimensionally regularised Feynman Integrals fulfil **differential equations!**

[Kotikov '90, Remiddi '97, Gehrmann-Remiddi '00,...]



Direct consequence of **Integration-by-parts (IBPs)** identities in d -dimensions!

$$\int \prod_{j=1}^l \frac{d^d k_j}{(2\pi)^d} \left(\frac{\partial}{\partial k_j^\mu} v_\mu \frac{S_1^{\sigma_1} \dots S_s^{\sigma_s}}{D_1^{\alpha_1} \dots D_n^{\alpha_n}} \right) = 0, \quad v^\mu = k_j^\mu, p_k^\mu$$

Reduced to **N master integrals**, $I_i(d; x_k)$ with $i = 1, \dots, N$.



Differentiating the masters and using the **IBPs** we get a system of
N coupled differential equations

$$\frac{\partial}{\partial x_k} I_i(d; x_k) = \sum_{j=1}^N c_{ij}(d; x_k) I_j(d; x_k).$$

(*Relatively*) Simple standard case: **multiple polylogarithms!**

- In this case, one can find a **canonical basis** [Henn '13]

$$\frac{\partial}{\partial x_k} I_i(d; x_k) = (d - 4) \sum_{j=1}^N c_{ij}(x_k) I_j(d; x_k), \quad c_{ij}(x_k) \text{ in } d\text{-log form.}$$

- Existence of such a basis related to **decoupling** of diff. eqs. for $d \rightarrow 4$.

Decoupling due to degeneracy of IBPs in **even integer numbers of dimensions**, i.e. number of master integrals in $d = 2n$ is smaller than for generic d !

[E.Remiddi, L.T. '13; L.T. '15]



Let's talk about what happens when this is not possible

As we'll see, it's enough to start putting some **masses in the loops!**

Interesting because:

- 1- LHC is pushing precision beyond 5%
- 2- High energies and **High p_T** \rightarrow probe massive particles in the loops
 - a- Top quark corrections to Hj , HH , $\gamma\gamma$, jj , ...
 - b- New massive states?

Let's look more in detail - *in reality we have*

$$I_j(d; x_k) = (m_j(d; x_k), \text{sub}_j(d; x_k))$$

↓

$$\frac{\partial}{\partial x_k} m_i(d; x_k) = \sum_{j=1}^N h_{ij}(d; x_k) m_j(d; x_k) + \sum_{j=1}^M nh_{ij}(d; x_k) \text{sub}_j(d; x_k).$$

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homogeneous piece is first source
of complexity - whether
differential equations are coupled

⇓

No way to solve this in general.
Need to do some "statistics"!

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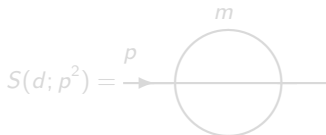
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non-homogeneous piece is second source of complexity - we must **integrate over it!**

⇓

Systematized using **differential equations** and **dispersion relations**

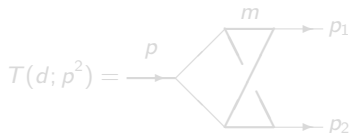
Let's have a look at two completely unrelated examples



- $p^2 \neq 0$, three massive lines
- 2 master integrals
- Satisfy 2 **coupled diff. eqs.**
- Needed for NNLO $t\bar{t}$



massive 3-particle cut
Integrals over elliptic integrals!

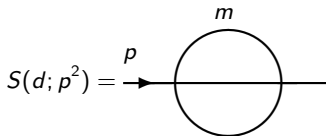


- $p_1^2 = p_2^2 = 0$, four massive lines
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NO massive 3-particle cut
SAME Integrals over elliptic integrals!

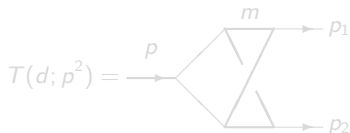
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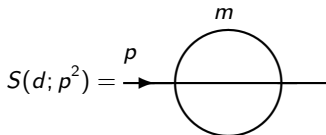


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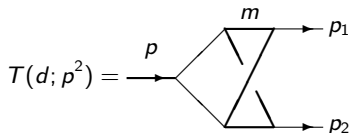
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In both cases diff. eqs. can be written as ($p^2 = u$, $m^2 = 1$ for simplicity)

$$\frac{d}{du} \begin{pmatrix} h_1(d; u) \\ h_2(d; u) \end{pmatrix} = B(u) \begin{pmatrix} h_1 \\ h_2 \end{pmatrix} + (d-4) D(u) \begin{pmatrix} h_1 \\ h_2 \end{pmatrix} + \begin{pmatrix} N_1(d; u) \\ N_2(d; u) \end{pmatrix}.$$

- Matrices $B(u)$ and $D(u)$ different for the two cases \rightarrow but don't depend on d !

\Downarrow

Matrices may have only regular singular points $1/(u-a)$
Fuchsian differential equations! [Lee, '14]

- $N_j(d; u)$ trivial for the sunrise \rightarrow **Tadpole!**
- $N_j(d; u)$ non-trivial for triangle, contains **multiple polylogarithms!**

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Start by looking for **two independent solutions** of the homogeneous equation

$$G(u) = \begin{pmatrix} I_1(u) & J_1(u) \\ I_2(u) & J_2(u) \end{pmatrix}$$

such that

$$\frac{d}{du} G(u) = B(u) G(u).$$

Fundamental properties (in both cases):

1- $I_k(u)$ and $J_k(u)$ are linear combinations of **complete elliptic integrals**

2- The **Wronskian** of the solutions is trivial \rightarrow matrix $B(u)$ is traceless

$$W(u) = \det G(u) = I_1(u)J_2(u) - J_1(u)I_2(u) = \pi$$

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$$\begin{pmatrix} h_1(d; u) \\ h_2(d; u) \end{pmatrix} = G(u) \begin{pmatrix} m_1(d; u) \\ m_2(d; u) \end{pmatrix}, \quad \text{with} \quad G^{-1}(u) = \frac{1}{\pi} \begin{pmatrix} J_2(u) & -J_1(u) \\ -I_2(u) & I_1(u) \end{pmatrix}.$$

And the new functions satisfy the equations

$$\frac{d}{du} \begin{pmatrix} m_1(d; u) \\ m_2(d; u) \end{pmatrix} = (d-4) \frac{1}{\pi} M(u) \begin{pmatrix} m_1(d; u) \\ m_2(d; u) \end{pmatrix} + G^{(-1)}(u) \begin{pmatrix} N_1(d; u) \\ N_2(d; u) \end{pmatrix}$$

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$M(u)$ contains all information needed for **iteration** at every order in $(d-4)!$

Let's see example of the **two-loop sunrise graph** [\[E.Remiddi, L.T., '16\]](#)

The **differential equations** can be put in the form above

$$\frac{d}{du} \begin{pmatrix} h_1 \\ h_2 \end{pmatrix} = B(u) \begin{pmatrix} h_1 \\ h_2 \end{pmatrix} + (d-4) D(u) \begin{pmatrix} h_1 \\ h_2 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix}.$$

where the two matrices $B(u), D(u)$ are defined as

$$B(u) = \frac{1}{6u(u-1)(u-9)} \begin{pmatrix} 3(3+14u-u^2) & -9 \\ (u+3)(3+75u-15u^2+u^3) & -3(3+14u-u^2) \end{pmatrix}$$

$$D(u) = \frac{1}{6u(u-9)(u-1)} \begin{pmatrix} 6u(u-1) & 0 \\ (u+3)(9+63u-9u^2+u^3) & 3(u+1)(u-9) \end{pmatrix}$$

Four regular singular points: $u = 0, 1, 9, \pm\infty$

Matrix of solutions of homogeneous eq. obtained studying the **imaginary part**

$$G(u) = \begin{pmatrix} I_1(u) & J_1(u) \\ I_2(u) & J_2(u) \end{pmatrix}$$

$$I_1(u) = \int_4^{(\sqrt{u}-1)^2} db \frac{1}{\sqrt{R_4(b, u)}}, \quad I_2(u) = \int_4^{(\sqrt{u}-1)^2} db \frac{b^2}{\sqrt{R_4(b, u)}}$$

$$J_1(u) = \int_0^4 db \frac{1}{\sqrt{-R_4(d, u)}}, \quad J_2(u) = \int_0^4 db \frac{b^2}{\sqrt{-R_4(d, u)}} + \frac{\pi}{3}(u+3)$$

$$R_4(b, u) = b(b-4)((\sqrt{u}-1)^2 - b)((\sqrt{u}+1)^2 - b)$$

$I_k(u), J_k(u)$ are linear combinations of **complete elliptic integrals**

After rotation to solve homogeneous part defining

$$G(u) = \begin{pmatrix} h_1(u) & J_1(u) \\ h_2(u) & J_2(u) \end{pmatrix}$$

and

$$\begin{pmatrix} h_1(d; u) \\ h_2(d; u) \end{pmatrix} = G(u) \begin{pmatrix} m_1(d; u) \\ m_2(d; u) \end{pmatrix}$$

Equations become as we saw

$$\frac{d}{du} \begin{pmatrix} m_1(d; u) \\ m_2(d; u) \end{pmatrix} = (d-4) \frac{1}{\pi} M(u) \begin{pmatrix} m_1(d; u) \\ m_2(d; u) \end{pmatrix} + \frac{1}{\pi} \begin{pmatrix} -J_1(u) \\ h_1(u) \end{pmatrix}$$

And the matrix $M(u)$ can be written as a **total differential!!!!**

$$M_{11}(u) = -\frac{d}{du} \left[\left(\frac{(u+3)^2}{6} I_1(u) J_1(u) \right) + \frac{\pi}{4} (2 \ln(u-9) + 2 \ln(u-1) - \ln(u)) \right],$$

$$M_{12}(u) = -\frac{d}{du} \left(\frac{(u+3)^2}{6} I_1(u) h_1(u) \right),$$

$$M_{21}(u) = +\frac{d}{du} \left(\frac{(u+3)^2}{6} J_1(u) J_1(u) \right),$$

$$M_{22}(u) = +\frac{d}{du} \left[\left(\frac{(u+3)^2}{6} I_1(u) J_1(u) \right) + \frac{\pi}{4} (2 \ln(u-9) + 2 \ln(u-1) - \ln(u)) \right],$$

Derivatives of logs and of products of elliptic integrals and rational functions!

It looks like a natural **generalization** of a “simple” matrix in d-log form!

Integral representation of solution for the master integrals at order zero

$$h_1^{(0)}(u) = \frac{1}{\pi} \left[J_1(u) \int_0^u dt h_1(t) - h_1(u) \left(\int_0^u dt J_1(t) - \text{Cl}_2 \left(\frac{\pi}{3} \right) \right) \right],$$

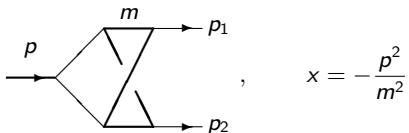
$$h_2^{(0)}(u) = \frac{1}{\pi} \left[J_2(u) \int_0^u dt h_1(t) - h_2(u) \left(\int_0^u dt J_1(t) - \text{Cl}_2 \left(\frac{\pi}{3} \right) \right) \right].$$

Similarly simple (one-fold integral) representation one order higher!

↓

See [\[arXiv:1602.01481\]](https://arxiv.org/abs/1602.01481) for details!

Same approach can be applied to master integrals of non-planar crossed triangle
 To appear soon... [\[A.von Manteuffel, L.T.\]](#)!



All **subtopologies** can be written in terms of (*not trivial!*)

$$\ln(f(l_i)), \quad \text{Li}_n(f(l_i)), \quad \text{Li}_{2,2}(f(l_i), g(l_j)),$$

with

$$l_i = \left\{ \sqrt{x}, \frac{1}{2}(\sqrt{x} + \sqrt{x+4}), \sqrt{x+4}, \frac{1}{2}(\sqrt{x} + \sqrt{x-4}), \sqrt{x-4} \right\}$$

Also in this case, analytical result for two master integrals can be written as

$$T_1^{(0)}(x) = \frac{2}{\pi} \left[J_1(x) \int_0^x dt l_1(t) Q(t) - l_1(x) \int_0^x dt J_1(t) Q(t) \right],$$

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$l_k(t), J_k(t)$ are again linear combinations of **complete elliptic integrals**

$Q(t)$ subtopologies \rightarrow linear combination of **weight 2 polylogs**

In particular we have

$$Q(x) = 5 \ln^2(l_2) - l_1 \frac{3/2 \zeta_2 + 3 \ln^2(l_4) + 3 \text{Li}_2(-1/l_4^2)}{l_5}$$

And

$$l_1(t) = \sqrt{x} K\left(\frac{x}{16}\right), \quad J_1(x) = \sqrt{x} K\left(1 - \frac{x}{16}\right).$$

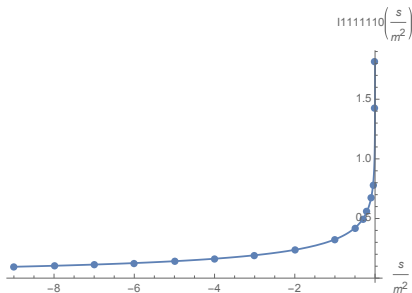
$$l_2(x) = -\sqrt{x} E\left(\frac{x}{16}\right), \quad J_2(x) = \sqrt{x} \left[E\left(1 - \frac{x}{16}\right) - K\left(1 - \frac{x}{16}\right) \right],$$

The integral representation of the solution is also in this case suited for analytic continuation and, **very importantly**, **fast and precise numerical evaluation**

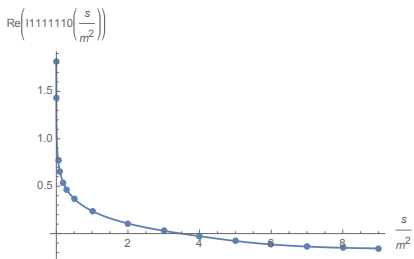
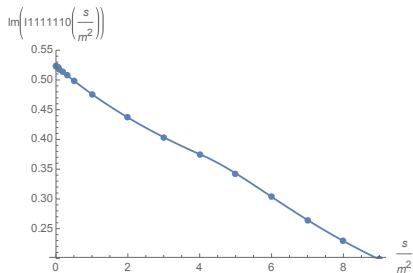
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Comparison against SecDec3 [S.Borowka et al., '15] for scalar triangle



Euclidean kinematics


 \Re Minkowski kinematics

 \Im Minkowski kinematics

How do we go further?

What do we do if these integrals appear in turn as **inhomogeneous** term of more complicated graphs?

→ **Dispersion relations** together with **differential equations** allow to simplify this step.



Worked out explicitly case of the Kite integral [\[arXiv:1602.01481\]](https://arxiv.org/abs/1602.01481)

$$\begin{aligned}
 \mathcal{I}(n_1, n_2, n_3, n_4, n_5) &= \text{Diagram of a Kite integral with external momentum } p \text{ and internal lines } D_1, D_2, D_3, D_4, D_5 \\
 &= \int \mathfrak{D}^d k \mathfrak{D}^d l \frac{1}{D_1^{n_1} D_2^{n_2} D_3^{n_3} D_4^{n_4} D_5^{n_5}}
 \end{aligned}$$

$$\begin{aligned}
 D_1 &= k^2 + m^2, & D_2 &= l^2, & D_3 &= (k - l)^2 + m^2, \\
 D_4 &= (k - p)^2, & D_5 &= (l - p)^2 + m^2,
 \end{aligned}$$

Let's see how this works for a simple 1-loop example

$$\text{Tri}(s) = \begin{array}{c} \xrightarrow{q} \\ \diagup \quad \diagdown \\ \text{---} \quad \text{---} \\ \diagdown \quad \diagup \\ \xrightarrow{p_1} \quad \xrightarrow{p_2} \end{array} \quad \text{with } q^2 = s, \quad p_1^2 = p_2^2 = 0$$

$$\text{Tri}(s) = \int \mathcal{D}^d k \frac{1}{(k^2 + m^2)((k - p_1)^2 + m^2)((k - p_1 - p_2)^2 + m^2)}$$

It is easy to derive **differential equation** in s for 1-loop triangle $\text{Tri}(s)$

$$\begin{aligned} \frac{d}{ds} \text{Tri}(s) = & -\frac{1}{s} \text{Tri}(s) + \frac{(d-2)}{8m^4} \left(\frac{1}{s-4m^2} - \frac{1}{s} \right) \text{Tad}(m) \\ & + \frac{(d-3)}{4m^2} \left(\frac{1}{s-4m^2} - \frac{1}{s} \right) \text{Bub}(s) , \end{aligned}$$

and

$$\text{Tad}(m) = \int \mathcal{D}^d k \frac{1}{k^2 + m^2} = \frac{m^{d-2}}{(d-2)(d-4)}$$

In order to solve it:

- 1- Solve **homogeneous** equation
- 2- Use Euler's variation of constants to find **inhomogeneous** solution

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Homogeneous equation is very simple in this case

$$\frac{d}{ds} h(s) = -\frac{1}{s} h(s) \quad \rightarrow \quad h(s) = \frac{c}{s}$$

↓

Euler's method gives then for inhomogeneous solution

$$\begin{aligned} \text{Tri}(s) = & \frac{c}{s} + \frac{(d-2)}{2s} \int_0^s \frac{du}{u-4m^2} \text{Tad}(m) \\ & + \frac{(d-3)}{s} \int_0^s \frac{du}{u-4m^2} \text{Bub}(u), \end{aligned}$$

Until here nothing new. In order to proceed, **include explicitly** subtopologies

Let us include Tadpole (trivial) and **dispersive representation** for the Bubble

$$\text{Bub}(u) = \frac{1}{\pi} \int_{4m^2}^{\infty} \frac{dt}{t - u - i\epsilon} \text{Im}(\text{Bub}(t))$$

$$\begin{aligned} \text{Tri}(s) &= \frac{m^{d-2}}{2s(d-4)} \int_0^s \frac{du}{u - 4m^2} \\ &+ \frac{(d-3)}{s} \frac{1}{\pi} \int_{4m^2}^{\infty} \frac{dt}{t - 4m^2} \text{Im}(\text{Bub}(t)) \int_0^s du \left(\frac{1}{u - 4m^2} + \frac{1}{t - u - i\epsilon} \right) \end{aligned}$$

Note that $c = 0$ since the triangle must be regular as $s \rightarrow 0$

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Integration in du is trivial – the relation that we find is **independent** from the explicit value of the **imaginary part of Bub(t)!**

$$\begin{aligned} \text{Tri}(s) = & \frac{m^{d-2}}{2s(d-4)} \ln\left(1 - \frac{s}{4m^2}\right) \\ & + \frac{(d-3)}{s} \frac{1}{\pi} \int_{4m^2}^{\infty} \frac{dt}{t-4m^2} \text{ImBub}(t) \left[\ln\left(1 - \frac{s}{4m^2}\right) - \ln\left(1 - \frac{s}{t}\right) \right]. \end{aligned}$$

- Extracting the **imaginary part** for $s > 4m^2$ is straightforward
- Numerical evaluation is simple once $\text{Im}(Bub(t))$ is known



Worked out for **Kite integral**. Provides one-fold integral representation suitable for numerical evaluation, analytic continuation,

SUMMARY (work in progress....!)

- When Feynman Integrals are not multiple polylog, still a lot to understand
- First, we need to *collect statistics*. At two-loops all known examples require integrals over complete elliptic integrals.
 - how **general** is this?
- First step, obtain analytical expressions **suitable for phenomenology!**



- **New idea:** When results beyond polylogs, solution of **differential equations** can be simplified using **dispersion relations**

Thanks!