

### Determination of Magnetic Axis in a Sextupole magnet using Vibrating Wire Technique\*

#### Alexander Temnykh\* and Animesh Jain<sup>+</sup>

\*Cornell University, Ithaca, New York 14850, USA +Brookhaven National Laboratory, Upton, New York 11973-5000, USA

\* Work supported by the National Science Foundation under contract PHY 0202078 and by the U.S. Department of Energy under contract DE-AC02-98CH10886.



•Work was motivated by NSLS-II project requirement of precise alignment of a string of quadrupole and sextupole magnets on a ~6 m long girder within a tight tolerance of ±10-20 microns.

•Similar requirement is anticipated for ILC damping ring.



• Sextupole magnetic field:

$$B_y(x, y) = b_3(x^2 - y^2);$$
  $B_x(x, y) = -2b_3xy$ 

• Horizontal scan:

$$B_{y}(x, y = y_{off}) = b_{3}x^{2} - b_{3}y_{off}^{2}; \quad B_{x}(x, y) = -2b_{3}xy_{off}$$

• Vertical scan:

$$B_{y}(x_{off}, y) = -b_{3}y^{2} + b_{3}x_{off}^{2}; \quad B_{x}(x, y) = -2b_{3}x_{off}y$$

• The term which couples horizontal to vertical beam particles motion:

$$a_2(y_{off}) = \frac{\partial B_x(x, y_{off})}{\partial x} = -2b_3 y_{off}$$



#### Sextupole magnet field properties





# • Algorithm for magnetic center finding from horizontal scan:

 $B_{x,y}(x)$  - horizontal and vertical field components measured as a function of horizontal position.

$$B_{y}(x) = m_{2}x^{2} + m_{1}x + m_{0} = b_{3}(x - x_{c})^{2} - b_{3}y_{c}^{2};$$
  

$$B_{x}(x) = n_{1}x + n_{0} = 2b_{3}xy_{c};$$
  

$$x_{c} = -\frac{m_{1}}{2m_{2}}; \quad y_{c} = \frac{n_{1}}{2m_{2}}$$

# • Algorithm for magnetic center finding from the vertical scan:

 $B_{x,y}(x)$  - horizontal and vertical field components measured as a function of vertical position.

$$B_{y}(x) = m_{2}y^{2} + m_{1}y + m_{0} = b_{3}x_{c}^{2} - b_{3}(y - y_{c})^{2};$$
  

$$B_{x}(x) = n_{1}y + n_{0} = 2b_{3}x_{c}y;$$
  

$$x_{c} = -\frac{n_{1}}{2m_{2}}; \quad y_{c} = -\frac{m_{1}}{2m_{2}}$$



#### **Experimental Setup**



Vibrating Wire: Length ~ 2200mm Driving current ~ 60mA (RMS) Fundamental freq ~ 47Hz For measurement used 2-nd vibrating mode

1	1)
ς	닛
(	2)
5	2

Stage with tension mechanism Stage with wire position sensors Horizontal and vertical wire position sensors (LED-Phototransistor assemblies) (3)



#### Sextupole magnet

 $b31 \sim 10.9 Gm/cm^{2}$ Length ~ 24cm Bore radius ~5.5cm



#### **Experimental Setup**

• In the VW technique the wire motion in vertical (horizontal) plane caused by the Lorentz forces between current flowing through the wire and horizontal (vertical) magnetic field.

•To separate horizontal and vertical field components measurement one should measure the wire motion in vertical and horizontal planes.

•The used assembly of the optical sensors show ~10% coupling between vertical and horizontal wire motion, we need ~1% or less.

 In a sextupole magnet, a X-Y coupling has the same effect as a roll of the magnet.

•Solution - assembly should be calibrated.





#### **Experimental Setup**

#### Optical wire position sensors calibration/decoupling procedure

• Stage (1) has been used for precise wire displacement (horizontal and vertical) at optical sensors and the sensors responds was measured.

 $dS_{x,y}$  - horizontal/vertical sensor responces in Volts

 $dx_w, dy_w$  - horizontal and vertical wire displacment in mm

$$\begin{pmatrix} dS_x \\ dS_y \end{pmatrix} = M \begin{pmatrix} dx_w \\ dy_w \end{pmatrix}; \quad M = \begin{pmatrix} 1.43 & 0.116 \\ -0.045 & 1.32 \end{pmatrix}$$

• In the course of measurement the sensor signals were converted to the wire displacement:

$$\begin{pmatrix} dx_w \\ dy_w \end{pmatrix} = M^{-1} \begin{pmatrix} dS_x \\ dS_y \end{pmatrix} = \begin{pmatrix} 0.697 & -0.061 \\ 0.024 & 0.755 \end{pmatrix} \begin{pmatrix} dS_x \\ dS_y \end{pmatrix}$$



## Experimental results

#### Horizontal and vertical scans near sextupole magnetic center



#### Two independent runs are shown



#### Experimental results

#### Horizontal scans at different vertical position



#### It is well consisted with theoretical prediction



## Experimental results

# Precision test: Horizontal scans at different vertical position





#### Precision better than 10 microns !!!

Sextupole magnetic center position relative wire as a function of the vertical wire position, files: hor scan (15, ... 19) 5/7/07



-0.01

-0.4

-0.2

0

Vertical wire position [mm]

0.4

0.2



11/2/2007

#### Experimental results

## Stability test

Sextupole magnet magnetic center measurement statistics, st 07/26/07



Position drift: vertical plane ~ 35 micron per hour horizontal plane ~ 5 micron per hour



#### The field error effect

# Sextupole magnet magnetic axes finding in the presence of the field errors

 $\widetilde{b}_i, \widetilde{a}_i$  - field errors, R - reference radius

$$\begin{split} B_{y} + i B_{x} &= \left(\widetilde{b}_{1} + i \,\widetilde{a}_{1}\right) + \left(\widetilde{b}_{2} + i \,\widetilde{a}_{2}\right) \left(\frac{x + iy}{R}\right) + \left(b_{3} + i \,\widetilde{a}_{3}\right) \left(\frac{x + iy}{R}\right) \\ B_{y} &= \widetilde{b}_{1} + \frac{\widetilde{b}_{2}x - \widetilde{a}_{2}y}{R} + b_{3} \frac{x^{2} - y^{2}}{R^{2}} - \widetilde{a}_{3} \frac{2xy}{R^{2}}; \\ B_{x} &= \widetilde{a}_{1} + \frac{\widetilde{a}_{2}x + \widetilde{b}_{2}y}{R} + b_{3} \frac{2xy}{R^{2}} + \widetilde{a}_{3} \frac{x^{2} - y^{2}}{R^{2}}; \end{split}$$

Magnetic center position from  $B_y$  measurement (extrim in quadratic fit):

a)  $x_c$  from horizontal scan,  $\tilde{y}$  – wire position in vertical plane.

$$\frac{\partial B_{y}}{\partial x} = \frac{\widetilde{b}_{2}}{R} + b_{3} \frac{2x_{c}}{R^{2}} - \widetilde{a}_{3} \frac{2\widetilde{y}}{R^{2}} = 0 \Longrightarrow$$
$$x_{c} = -\frac{\widetilde{b}_{2}}{2b_{3}}R + \frac{\widetilde{a}_{3}}{b_{3}}\widetilde{y} \approx -\frac{\widetilde{b}_{2}}{2b_{3}}R$$

b)  $y_c$  from vertical scan,  $\tilde{x}$  – wire position in vertical plane.

$$\frac{\partial B_{y}}{\partial y} = -\frac{\widetilde{a}_{2}}{R} - b_{3} \frac{2y_{c}}{R^{2}} - \widetilde{a}_{3} \frac{2\widetilde{x}}{R^{2}} = 0 \Longrightarrow$$
$$y_{c} = -\frac{\widetilde{a}_{2}}{2b_{3}} R - \frac{\widetilde{a}_{3}}{b_{3}} \widetilde{x} \approx -\frac{\widetilde{a}_{2}}{2b_{3}} R$$

Magnetic center position from  $B_x$  measurement ("zero" sloop):

a)  $x_c$  from vertical scan,  $\tilde{y}$  – averaged vertical wire position (small).

$$\frac{\partial B_x}{\partial y} = \frac{\widetilde{b}_2}{R} + b_3 \frac{2x_c}{R^2} - \widetilde{a}_3 \frac{2\widetilde{y}}{R^2} = 0 \Longrightarrow$$
$$x_c = -\frac{\widetilde{b}_2}{2b_3}R + \frac{\widetilde{a}_3}{b_3}\widetilde{y} \approx -\frac{\widetilde{b}_2}{2b_3}R$$

b)  $y_c$  from horizontal scan,  $\tilde{x}$  – averaged horizontal wire position (small)

$$\frac{\partial B_x}{\partial x} = \frac{\widetilde{a}_2}{R} + b_3 \frac{2y_c}{R^2} + \widetilde{a}_3 \frac{2\widetilde{x}}{R^2} = 0 \Longrightarrow$$
$$y_c = -\frac{\widetilde{a}_2}{2b_3} R - \frac{\widetilde{a}_3}{b_3} \widetilde{x} \approx -\frac{\widetilde{a}_2}{2b_3} R$$

Conclusion: Both methods should give the same results. It can be used for cross checking.



•Vibrating wire technique has been applied to sextupole magnet magnetic axes finding.

•Demonstrated precision, ~10microns, is adequate to the alignment requirement of NSLS - II project and, very likely, of ILC damping ring.



#### The field error effect

# Sextupole magnet magnetic axes in the presence of the field errors

5723/07 6 General Case, including Qued terms :  $\left( \begin{array}{c} B_{2} + iB_{2} \end{array} \right) = \left( \begin{array}{c} B_{1} + iA_{1} \end{array} \right) + \left( \begin{array}{c} B_{2} + iA_{2} \end{array} \right) \left( \begin{array}{c} \chi + iY \\ R_{rel} \end{array} \right) + \left( \begin{array}{c} B_{3} + iA_{3} \end{array} \right) \left( \begin{array}{c} \chi + iY \\ R_{rel} \end{array} \right)^{2}$  $By = B_1 + (B_2 x - A_2 y)/Rref + B_3 (\frac{\chi^2 - y^2}{R_r y^2}) - 2A_3 (\frac{\chi y}{R_r y^2})$  $B_{\chi} = A_1 + (A_2\chi + B_2\chi)/R_{ref} + B_3(\frac{2\chi_1}{R_2}) + A_3(\frac{\chi^2 - y^2}{R_{ref}})$ The "center" is defined as a point where B2 & A2 terms are zero:  $B_{2}^{\prime} + iA_{2}^{\prime} = (B_{2} + iA_{2}) + 2(x_{e} + iY_{e})(B_{3} + iA_{3}) = 0$  $if A_3 = 0$ ,  $\mathcal{T}_c = -\frac{1}{2} \left( \frac{B_2}{B_2} \right) Rref ; Y_c = -\frac{1}{2} \left( \frac{A_2}{B_3} \right) Rref$  $dby/dx = \frac{B_2}{R_{ref}} + 2B_3 \frac{x}{R_{ref}^2} - 2A_3 \frac{y_0}{R_{ref}^2}$  $\frac{1}{y_{2}y_{0}}$   $\frac{1}{y_{2}y$ i. error in  $\chi_c = \Delta \chi_c \simeq \left[ + \left( \frac{A_3}{B_3} \right) \left( \frac{y_o}{R_{ref}} \right) + \frac{1}{2} \left( \frac{A_2}{B_3} \right) \left( \frac{A_3}{B_3} \right) \right] Ref$  $-\frac{1}{2}\frac{A_2}{B_3}\sqrt{y_c}/R_{ff} \left[ \Delta \mathcal{X}_{c} \simeq \left( \frac{A_3}{B_3} \right) \left( \frac{y_0 - y_c}{y_c} \right) \right]$ The error is minimized if i) either  $A_3 \approx 0$ or ii)  $y_0 \approx y_c$ , i.e.  $dB_3/dx$ evaluated at Yx Y.

dBy dy dy xxx This is zero at  $y = y'_{e} = -\left(\frac{A_2 + 2A_3(x_0/Reg)}{2B_2}\right)Reg$ neglecting 13 in Comparison to B3? M2 ~ [12(A2) + (B2) (A3) Ry  $\simeq \left[-\frac{1}{2}\left(\frac{A_2}{B_3}\right) - \left(\frac{\chi_c}{R_{\rm eff}}\right)\left(\frac{A_3}{B_3}\right)\right] R_{\rm eff}.$ i. Errorin ye is  $\Delta y_c = y'_c - y_c = \left(\frac{A_3}{B_3}\right) \left(x_c - x_o\right) \qquad \text{once again, the error is} \\ \begin{array}{c} \text{once again, the error is} \\ \text{regliquble if either} \\ \text{i) } A_3 \simeq 0 \\ \text{or ii) } x_o \approx x_c; i.e. \frac{\partial By}{\partial y} \text{ is} \end{array}$  $\frac{dB_{\chi}}{d\chi} = \frac{A_2}{R_{\rm eff}} + \frac{2B_3 N_0}{R_{\rm eff}^2} + 2A_3 \chi/R_{\rm eff}^2$  evaluated at  $\chi_0 \simeq$ it can be seen that  $\frac{dBy}{dy}_{x_0,y_0} = -\frac{dBx}{dx}_{x_0,y_0}$ , as expected. structly Constant (rice. By is not linear with 2) due to the A3 term. for 2A32/2 << A2 + 2 B3 4/Rag Rul Rul x <5 (A2) Rref  $\frac{dB_{x}}{dx}\Big|_{y_0} = \frac{A_2}{R_0^2} + 2B_3 \frac{y_0}{R_0^2} \left(1 + \left(\frac{A_3}{B_3}\right) \frac{x}{y_0}\right)$ " yo = 0 should be avoided for