

Tracking

- Fundamental issues in tracking or how to design a tracker ?
- Silicon detectors
- New ideas and developments for the HL-LHC

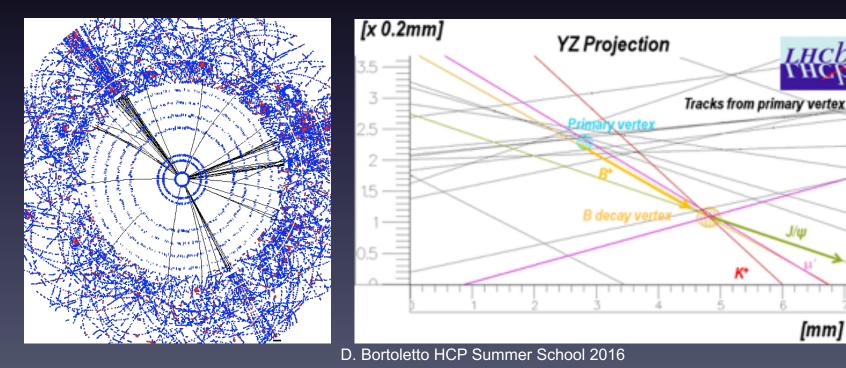
D. Bortoletto

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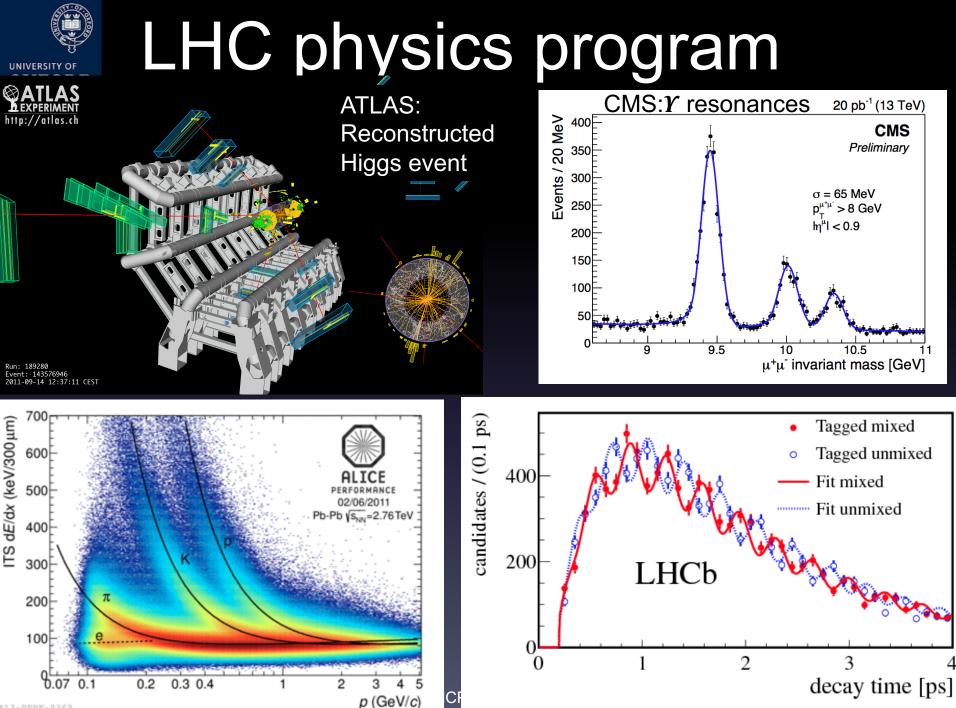


Tracking detectors

- High granularity detectors close to the interaction region providing precise measurements of the position of charged particles
 - Measure the trajectory using "hits" to determine the momentum of charged particles from their curvature in a magnetic field
 - Extrapolate to the origin and reconstruct
 - Primary vertices and identify the vertex associated with the "hard" interaction
 - Secondary vertices to identify tau-leptons, b and c-hadrons by lifetime tagging •
 - Reconstruct strange hadrons, which decay in the detector volume
 - Identify photon conversions and nuclear interactions



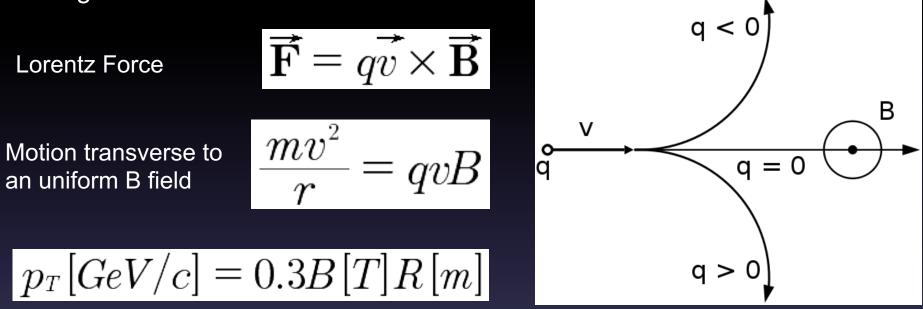
[mm]





Momentum Measurements

 The determination of the momentum (and charge) of charged particles can be performed by measuring the bending of a particle trajectory (track) in a magnetic field

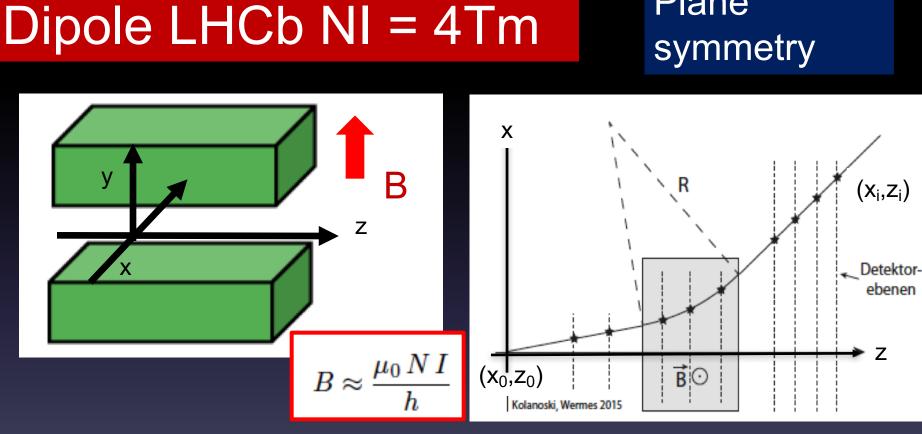


- Use layers of position sensitive detectors before and after or inside a magnetic field to measure a trajectory and determine the bending radius
- The tracker configuration depends critically on the choice of the magnet



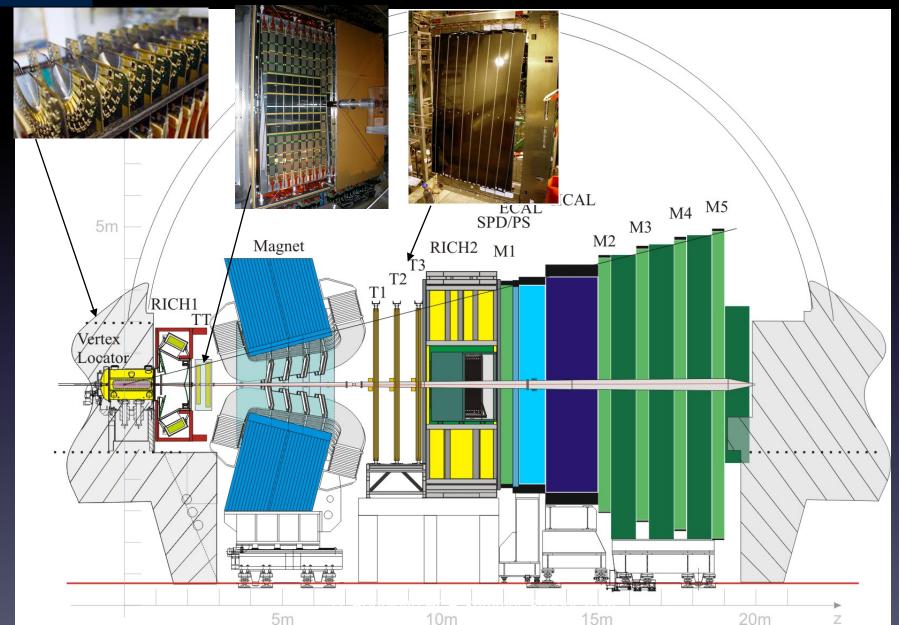
Forward Spectrometers

Plane



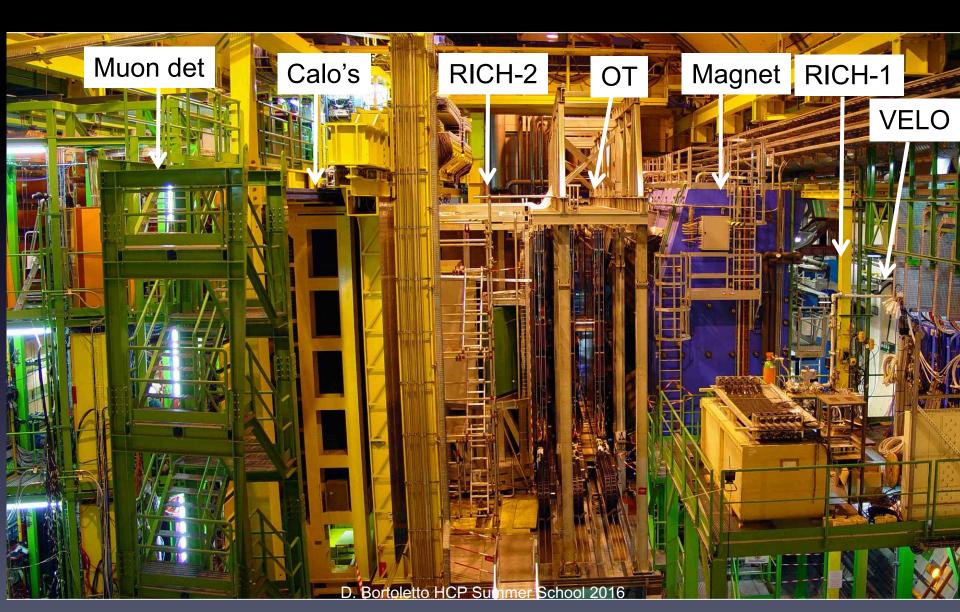
- Particle deflected in x z plane
- Tracking detectors are arranged in parallel planes along z
- Bending from difference of the slopes before and after magnet

LHCbA Forward Spectrometer



6



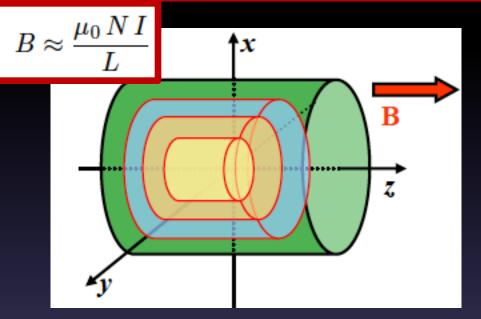




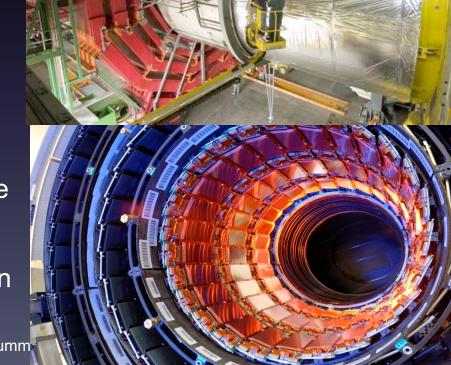
Central Detectors

Solenoid CMS 4T, Atlas 2T

Cylindrical symmetry



- Magnetic field along the beam
- Particle deflected in x –y (r ϕ) plane
- Tracking detectors are arranged in cylindrical shells along r
- Measurement of curved trajectories on r- φ planes at fixed r

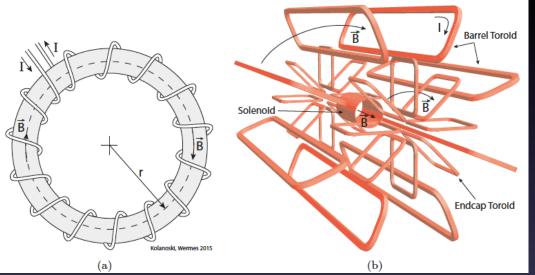


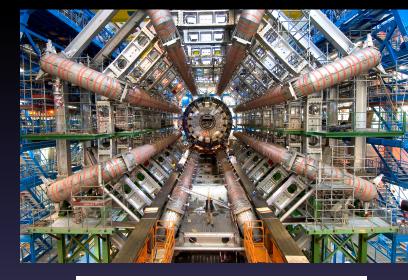


Magnetic Spectrometers

Toroid Atlas 0.5T

Azimuthal symmetry



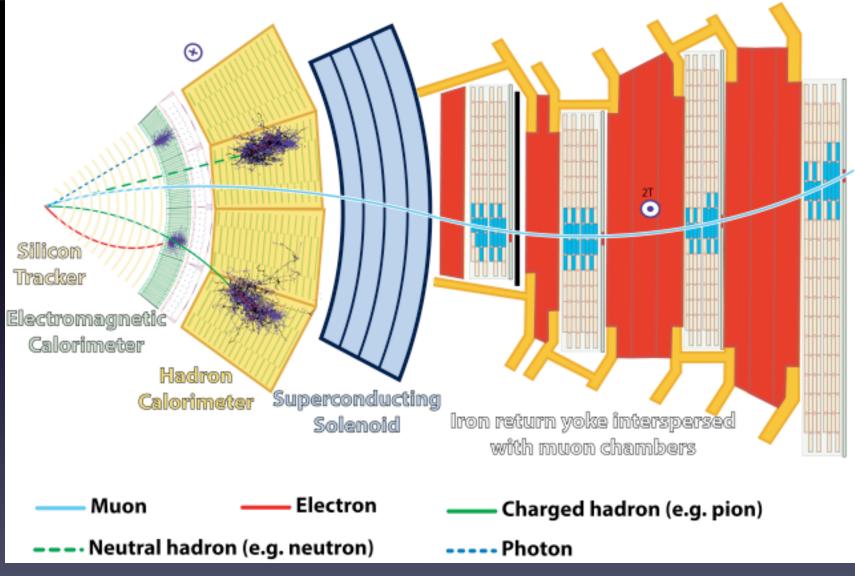


n rement of fixed r

- Deflection in (r z) plane
- Tracking detectors are arranged in cylindrical shells providing measurement of curved trajectories in r-z planes at fixed r

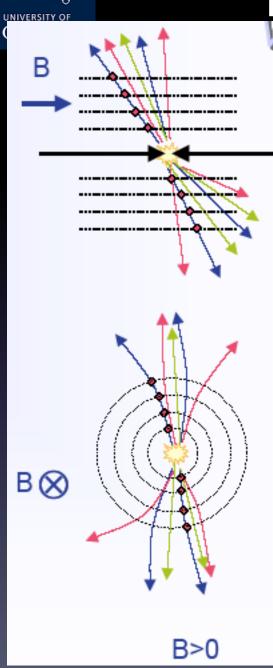


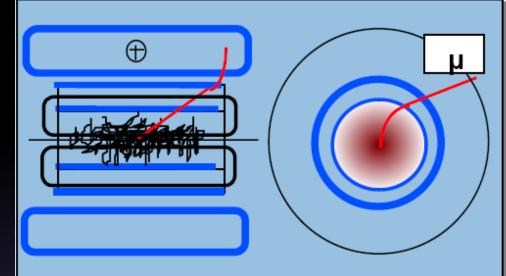
CMS

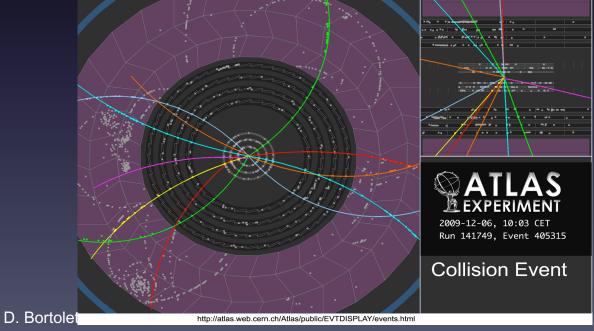


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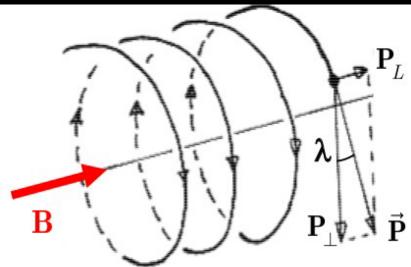


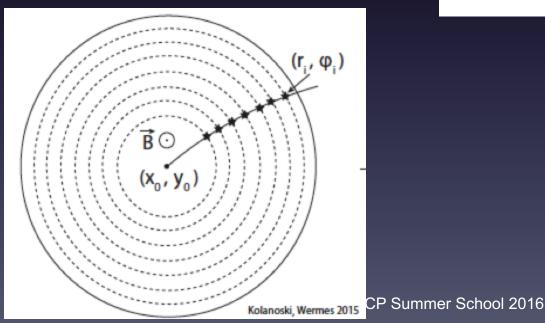


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Tracking in a solenoidal B

- The trajectory of a charged particle in a uniform B field along the beamline is a helix
 - Transverse (xy) and Longitudinal (rz) projections.
 - Φ=azimuthal angle is measured in transverse plane
 - θ =polar angle is measured from z axis
 - Dip, $\lambda = \pi/2 \theta$
 - Pseudorapidity, η = -ln tan (θ /2)
 - Transverse momentum, $p_T = p \sin \theta$

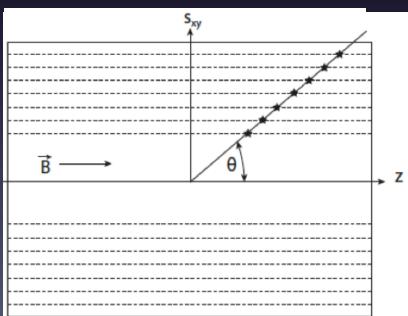


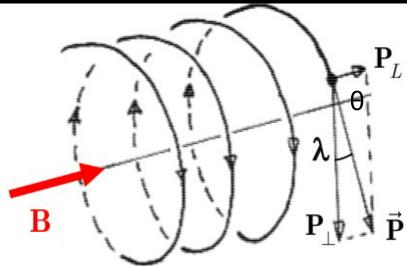




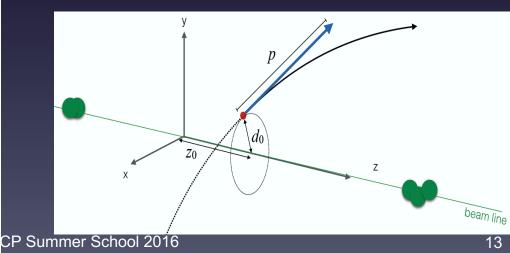
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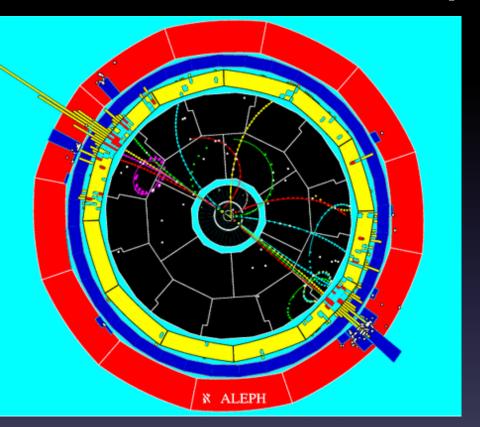


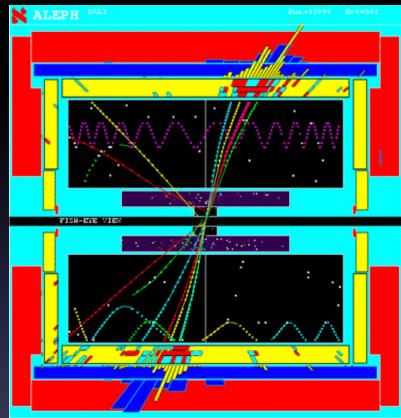
• Impact parameter d₀





The Helix ... seen in an experiment





- For small momenta y is a periodic function of z
- For large momenta we have a straight line as a function of z



What we need to do?

 Measure the transverse momentum and the dip angle λ

$$P = \frac{P_{\perp}}{\cos \lambda} = \frac{0.3BR}{\cos \lambda}$$

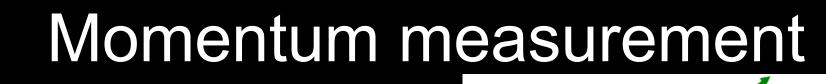
 The error on the momentum is given by the measurement errors on the curvature radius R and the dip angle λ

$$\frac{\partial P}{\partial R} = \frac{P_{\perp}}{R}$$
$$\frac{\partial P}{\partial \lambda} = -P_{\perp} \tan \lambda$$

$$\left(\frac{\Delta P}{P}\right)^2 = \left(\frac{\Delta R}{R}\right)^2 + (\tan\lambda\Delta\lambda)^2$$

For central detector configurations with solenoid magnets

- the error on the radius measured in the bending plane $r \phi$
- the error on the dip angle in the r - z plane
- The contribution of multiple scattering to the the momentum resolution
- In a hadron collider like LHC the main emphasis is on transverse momentum measurement

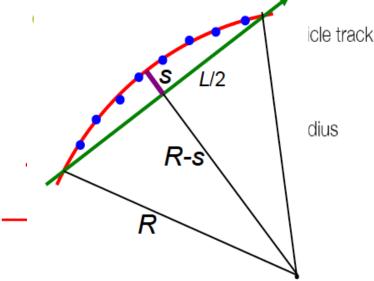


• Motion transverse to uniform B field

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$$p_T[GeV/c] = 0.3B[T]R[m]$$

Measure the sagitta, s, from radius of curvature, R. If s<<L



$$R = \frac{L^2}{8s} + \frac{s}{2} \approx \frac{L^2}{8s} \quad \frac{\Delta p_T}{p_T} = \frac{\Delta R}{R} \quad \frac{\sigma_{p_T}}{p_T} = \frac{8p_T}{0.3BL^2} \sigma_s$$

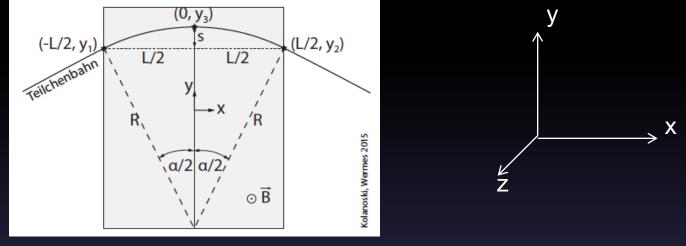
Good relative momentum requires small σ_s, strong B field, long path length L (as L² ➡ often use beam constraint). Momentum resolution gets worse at large p_T



s =

Momentum resolution

Let us assume that we have 3 measurements of the position of the particle



$$= y_3 - \frac{y_1 + y_2}{2} \qquad \sigma_s = \sqrt{\sigma_{r\phi}^2 + \frac{1}{4} 2 \sigma_{r\phi}^2} = \sqrt{\frac{3}{2}} \sigma_{r\phi}$$

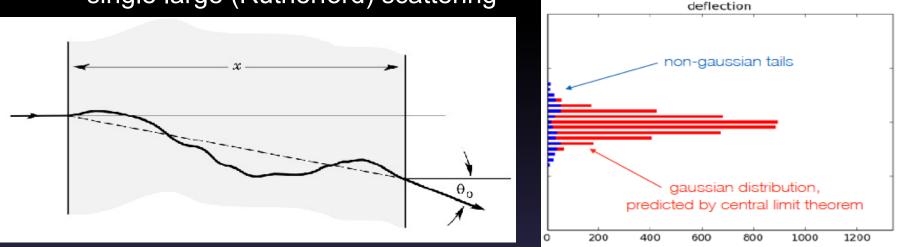
For N measurements all with the uncertainty

Small $\sigma_s \implies \text{small } \sigma_{r_{\phi}} \text{ and large N (many measurement points, but only as } \sqrt{N}$



Multiple scattering

- A charged particle in medium undergoes random deflections caused
 - by multiple (Coulomb) scattering off the core of atoms
 - single large (Rutherford) scattering



$$\theta_{0} = \frac{13.6 \ MeV/c}{p\beta} Z_{\sqrt{\frac{x}{X_{0}}}} \left(1 + 0.038 \ln \frac{x}{X_{0}}\right)$$

- This introduces an error on the sagitta
 - Multiple scattering is reduced by: low Z, thin materials, long X₀



Momentum resolution

- The point error, $\sigma_{r_{\phi}}$, has a part from intrinsic measurement precision and a multiple scattering part. Therefore:

$$\frac{\sigma_{p_T}}{p_T} = \sqrt{\left(\frac{\sigma_{p_T}}{p_T}\right)_{r\phi}^2 + \left(\frac{\sigma_{p_T}}{p_T}\right)_{MS}^2}$$

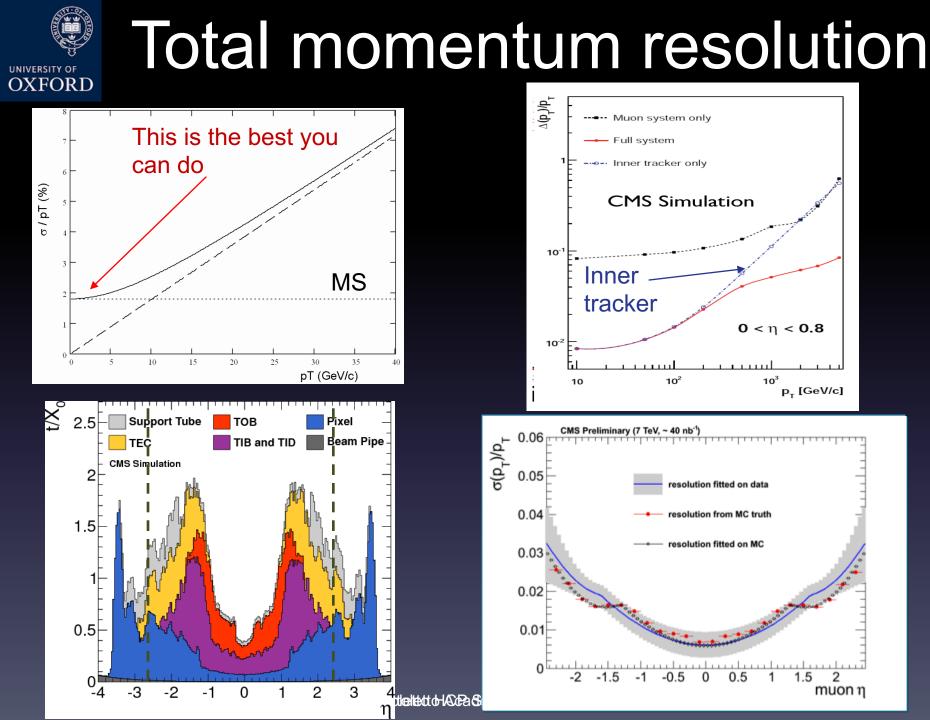
$$\left(\frac{\sigma_{p_T}}{p_T}\right)_{r\phi} = \frac{p_T}{0.3L^2B} \sqrt{\frac{720}{N+4}} \sigma_{r\phi}$$

Radiation length=mean length of a material to reduce the energy of an electron by 1/e. It can be approximated as:

$$\left(\frac{\sigma_{p_{T}}}{p_{T}}\right)_{MS} = \frac{0.054}{LB\beta} \sqrt{\frac{L}{X_{0}}} \sin\theta$$

 Thickness of detector often expressed in 'fraction of radiation length' x/X₀:

Good momentum resolution requires long X_{o} , and therefore small Z and thin materials





Estimate the ATLAS momentum resolution

TRT

Pixels

R = 1082 mm

R = 554 mn R = 514 mm

R = 443 mm

R = 371 mm

R = 299 mm

R = 122.5 mm R = 88.5 mm

R = 50.5 mm R = 0 mm

- Simplification:
 - Assume high momenta (no MS)
 - $-R_{min} = 5.05 \text{ cm}, R_{max} = 1082 \text{ cm}$
 - Pixels (5cm to 12cm)
 - N=3 (up to 2012), σ = 12μm
 - SCT (30cm to 55cm)
 - N=4 layers, $\sigma = 16 \ \mu m$
 - TRT (55cm to 105 cm)
 - N = 36, σ = 170 μm
 - Use as a single point with σ = 28 μm at R = 80 cm (= R_{max} \Rightarrow L = 75 cm)
 - -N = 3 + 4 + 1 = 8
 - σ = 12, 16, 28 μm
 σ > ~16 μm
 - L=75 cm



TRT

SCT

Pixels



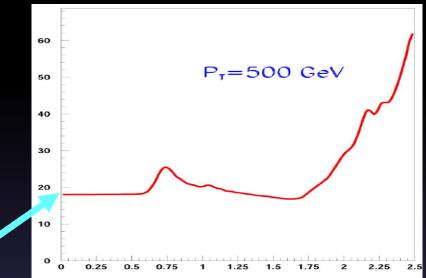
Estimate: ATLAS momentum resolution

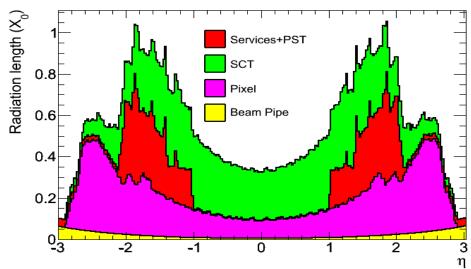
• B=2T, L=0.75m

$$\left(\frac{\sigma_{p_T}}{p_T}\right)_{r\phi} = 7.74 \frac{p_T}{0.3L^2 B} \sigma_{r\phi}$$
$$= 3.6 \times 10^{-4} p_T [GeV]$$

• At p_T=500 GeV

$$\frac{dp}{p} = 18\%$$





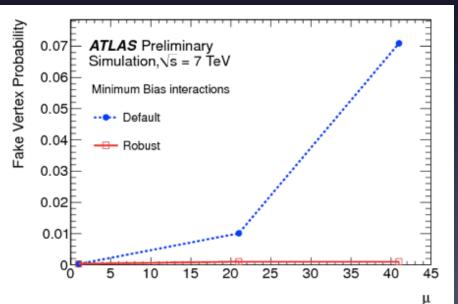
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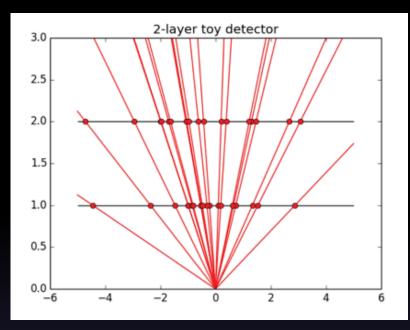


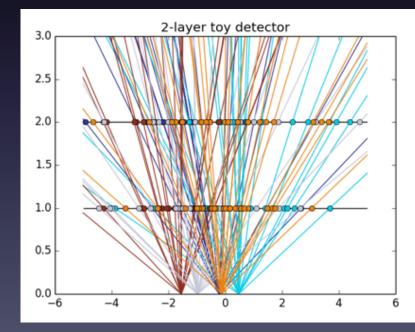


reconstruction

- Use reconstructed tracks, to extrapolate back and find the primary vertex
- To maximise the physics potential, LHC runs in a regime of multiple instantaneous collisions: pile-up
- Pile-up renders tracks reconstruction and vertex finding more complex: more seeds and CPU time explodes



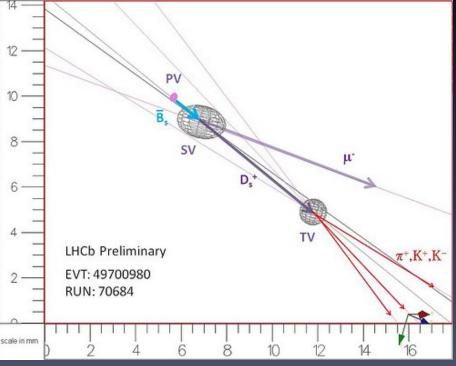


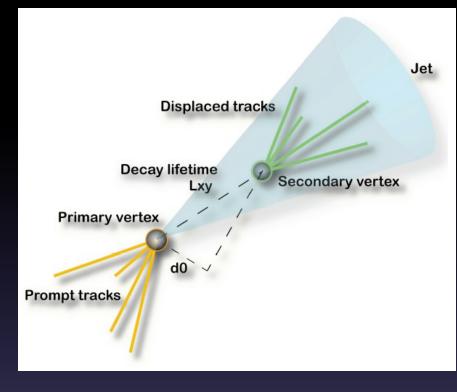




Lifetime tagging

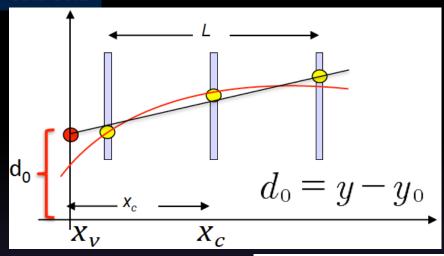
- Tracks with significant impact parameter, d₀, can be used to form a reconstructed secondary vertex
 - Essential to study the heavy quarks (t, b, c)
 - Tagging the Higgs since BR(H→ $b\overline{b}$) ≈ 58%
 - Studying the Higgs potential (HH)



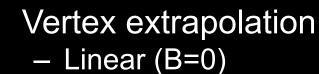


Example of a fully reconstructed event from LHCb, with primary, secondary and tertiary vertex.

Impact parameter resolution OXFORD



σ



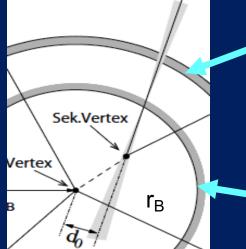
$$y = a + bx$$

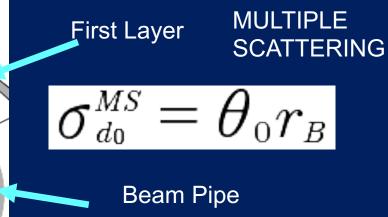
- Parabolic (with B field) $y = a + bx + \frac{1}{2}cx^{2}$

Linear \bullet approximation

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$$m_{d_0}^{meas} = \sqrt{\sigma_a^2 + x_0^2 \sigma_b^2} = \frac{\sigma_{meas}}{\sqrt{N}} \sqrt{1 + \frac{12(N-1)}{(N+1)}r^2}$$





r= extrapolation length

$$r = \frac{x_0}{L}$$



Impact parameter resolution

• In the linear case

$$r = \frac{x_0}{L}$$

$$\sigma_{d_0} = \sigma_{d_0}^{\text{meas}} \oplus \sigma_{d_0}^{\text{MS}} = \frac{\sigma_{\text{meas}}}{\sqrt{N}} \sqrt{1 + \frac{12(N-1)}{(N+1)}r^2} \oplus \theta_0 r_B$$

- To have good impact parameter resolution:
 - Small measurement errors σ_{meas}
 - Large lever arm Li⇒ r
 - Place measurement plane as near as possible to the production point: small x₀ is r
 - Limit multiple scattering
 Low Z thin beam pipe and measurement layers
 - Increasing number of points also improves the d_0 resolution $(1/\sqrt{N})$



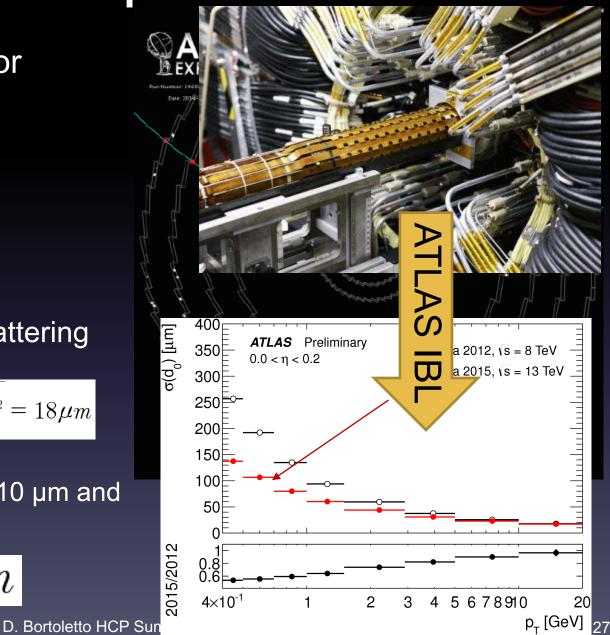
Example ATLAS

- ATLAS Pixel detector
 - N = 3, σ = 10 μ m
 - $x_1 = 5.05 \text{ cm}$
 - $x_2 = 8.85 \text{ cm}$
 - $x_3 = 12.25 \text{ cm}$
 - L = 7.2 cm
 - $r = x_2/L = 1.22$
- Neglecting Multiple scattering

$$\sigma_{d_0}^{meas} = \frac{\sigma_{meas}}{N} \sqrt{1 + \frac{12(N-1)}{(N+1)}r^2} = 18\mu m$$

- With IBL: N = 3, σ = 10 µm and x₁ = 3.55 cm

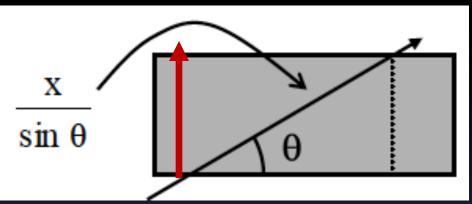
$$\sigma_{\scriptscriptstyle do}^{\scriptscriptstyle meas}pprox 10 \mu m$$





Tracker resolution with MS

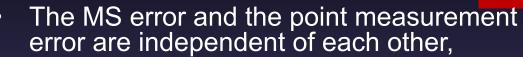
- For low p_T tracks the momentum resolution and the impact parameter resolution are dominated by multiple scattering
- The amount of material traversed by the particles depends on polar angle



Momentum resolution:

$$\frac{\sigma_p}{p^2} \to k_p \frac{\sqrt{x/X_0}}{p\sqrt{\sin\theta}}$$

Impact parameter resolution:



- The total error is the sum in quadrature of the 2 terms
- ATLAS detector Monte Carlo studies show:

 $\sigma_{d_0} \to k_{d_0} \frac{\sqrt{x/X_0}}{p\sqrt{\sin\theta}}$

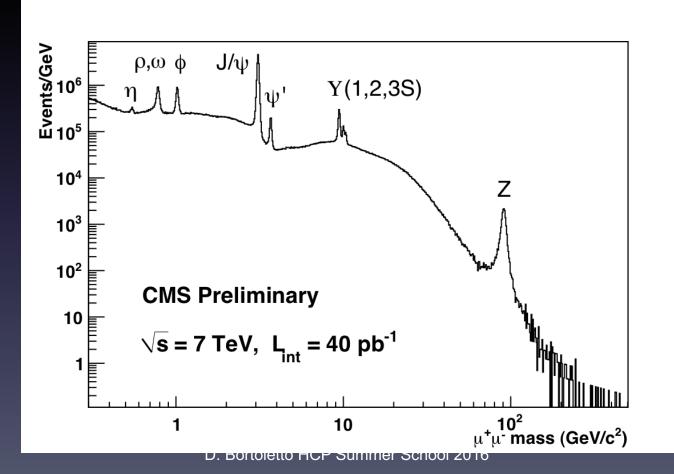
 $-=0.00036 \oplus \frac{0.013}{p_T \sqrt{\sin \theta}} (1/GeV)$

 $\sigma_{d_0} = 11 \mu m \oplus \frac{73 \mu m}{n_T \sqrt{\sin t}}$ D. Bortoletto HCP Summer Sc



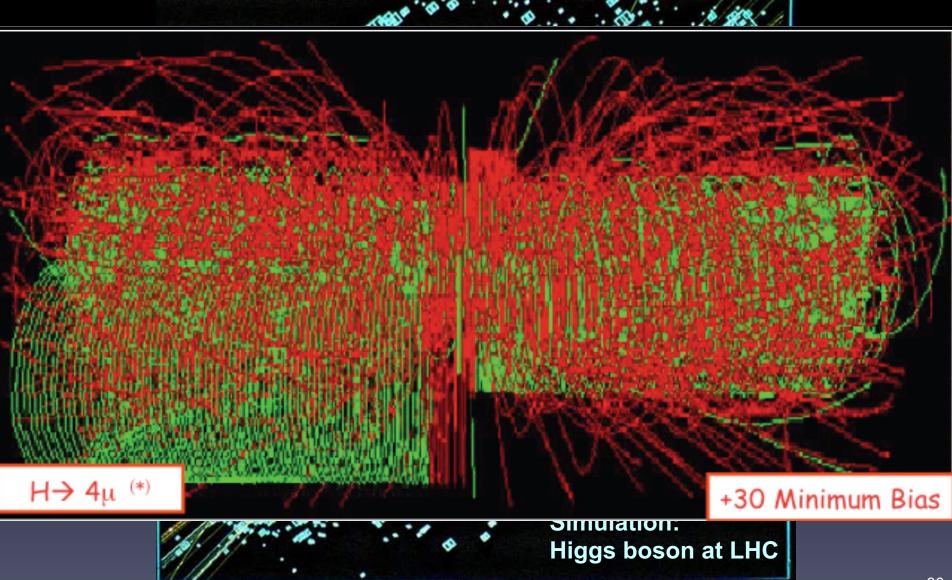
Systematic effects

- Alignment
- Knowledge of the B field
- Material





Tracking is more challenging





Tracking at the LHC

- ~1200 tracks every 25 ns or ~ 10^{11} /second
 - high radiation dose $10^{15}~n_{eq}$ / cm^2 / 10 yrs
 - 600 kGy (60 Mrad) through the ionisation of mips in 250 μm bulk silicon

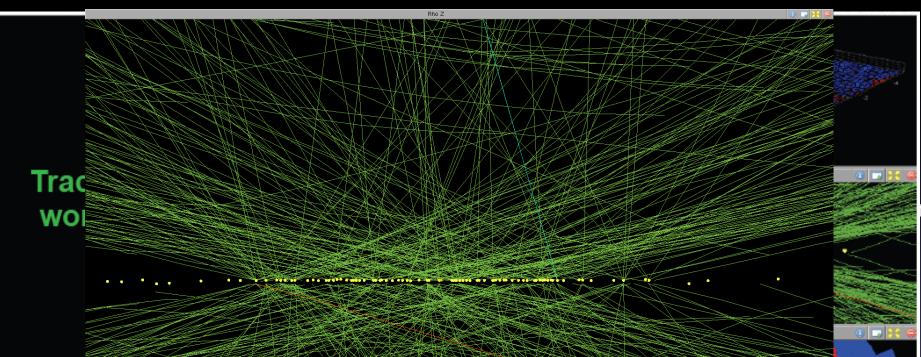
Requiements:

- Response times of the detector elements and their read-out electronics must be fast enough to process the event in less than 25 ns to minimize the pile-up to one bunch crossing;
- High granularity to keep the occupancy low;
- All elements of the detector, including active material, readout electronics and cables must be rad-hard.



Tracking and Vertex Detectors

- Solid state detectors especially silicon offer high segmentation
- Determine position of primary interaction vertex and secondary decays



This would have not been possible without semiconductor (pixel and strip) trackers



- The interaction of a particle with matter can be used as a working principle for a particle detector.
- The interaction of a particle with matter impact the precision of the measurement



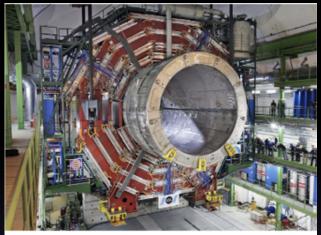
Туре	particles	fund. parameter	characteristics	effect
Multiple Scattering	all charged particle	radiation length X	almost gaussian average effect 0 depends $\sim 1/p$	deflects particles, increases measurement uncertainty
Ionisation loss	all charged particle	effective density $A/Z * ho$	small effect in tracker, small dependence on P	increases momentum uncertainty
Bremsstrahlung	all charged particle, dominant for e	radiation length X	highly non- gaussian, depends	introduces measurement bias
Hadronic Int.	all hadronic particles	nuclear interaction length Λ	destroys particle, rather constant effect in p	main source of track reconstruction inefficiency

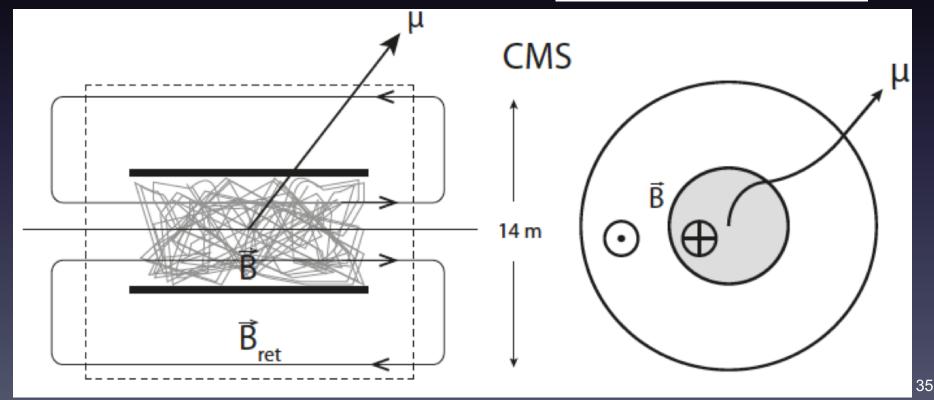


Measuring Muons

CMS:

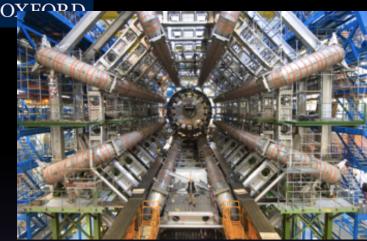
- measurement of momentum in tracker and B return flux;
- Solenoid with Fe flux return
- Property:
 µ tracks point back
 to vertex in r-z plane





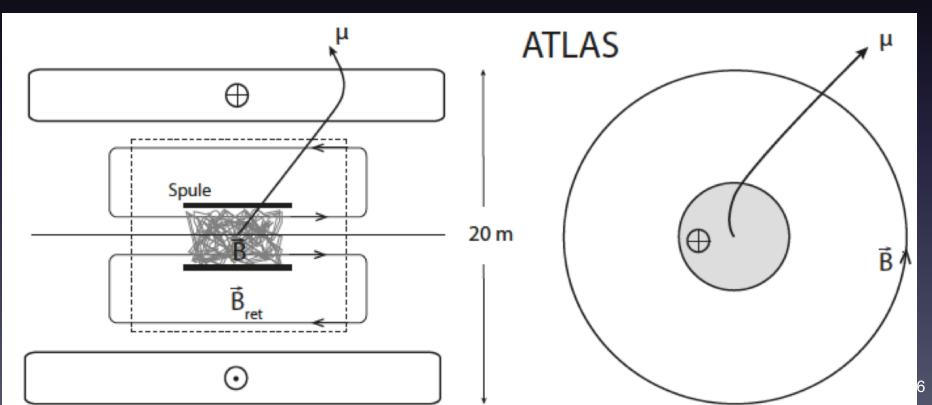


Measuring Muons



ATLAS

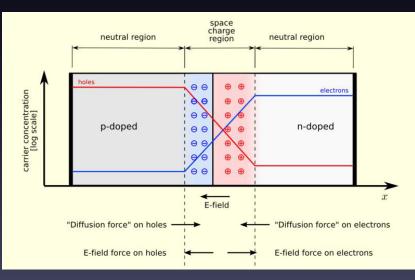
- standalone µ momentum measurement
- Air-core toroid safe for high multiplicities
- Property: σ_p flat with η



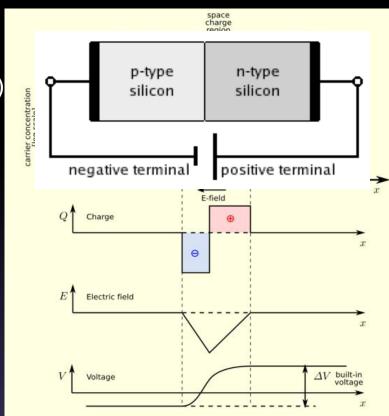


Silicon Detectors

- A silicon detector is a p-n diode
 - n-type (P, As, Sb doping more electrons)
 - p-type (B, Al, Ga doping more holes)
- p-n junction without external voltage
 - Free charges diffuse until equilibrium is reaches and create the built-in potential



The space charge (depletion) region can be made bigger by applying a reverse bias voltage



The W of the depletion region can be found by applying Poisson equation and depends on V

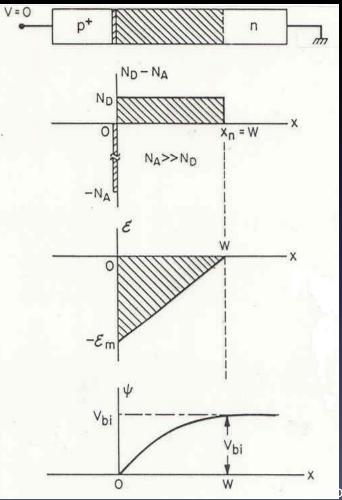
$$W = W_{\scriptscriptstyle p} + W_{\scriptscriptstyle n} = \sqrt{rac{2arepsilon}{q} \Big(rac{1}{N_A} + rac{1}{N_D} \Big) (V_{\scriptscriptstyle bi} + V)}$$

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p+-n sensors

- P+-n sensors consists of a thin (~µm), highly doped p+ (~10¹⁹ cm⁻³) layer on lightly doped n- (~10¹² cm⁻³) substrate
- Since N_A>>N_D most of the n-type silicon is depleted



$$W = \sqrt{\frac{2\varepsilon}{q} \left(\frac{1}{N_A} + \frac{1}{N_D}\right) (V_{bi} + V)}$$
$$\approx \sqrt{\frac{2\varepsilon}{q} \frac{1}{N_D} V}$$

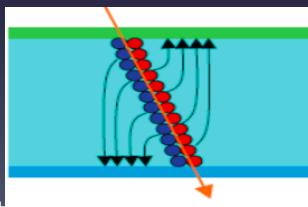
$$W \sim \sqrt{2\varepsilon_0 \varepsilon_r \mu \rho |V|}$$
$$\rho = \frac{1}{e \mu N_D}$$

V ... External voltage
 ρ.... resistivity
 μ ... mobility of
 majority charge
 carriers
 N_{eff}..effective doping
 concentration

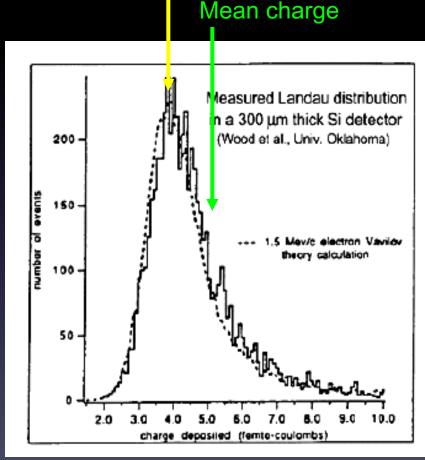


Signal

- The signal generated in a silicon detector depends on the thickness of the depletion zone and on the dE/dx of the particle.
 - The distribution is given by the Landau distribution
 - In silicon the most probable dE/dX of a MIP is 300 eV/µm and the mean ionization energy I₀ = 3.62 eV. Therefore a charged particle creates ≈80 e⁻h⁺/µm.
 - For 300 µm silicon the most probable charge is ≈ 24000 e-/h pairs



Most probable charge $\approx 0.7 \times$ mean



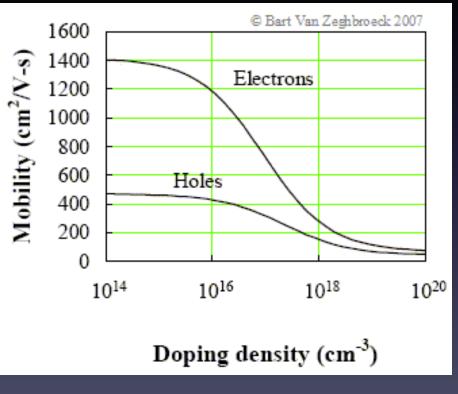
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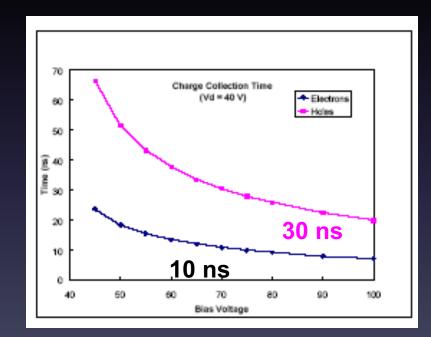
Collection by drift

Electrons an holes move in an E field F=qE

v_{e,h}=µ_{e,h} E



The time required for a carrier to traverse the sensitive volume is the collection time.

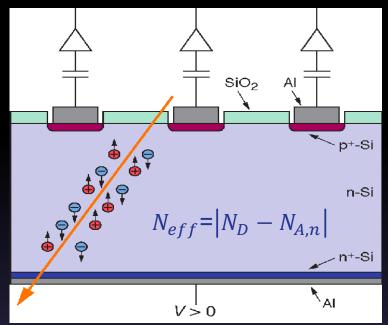


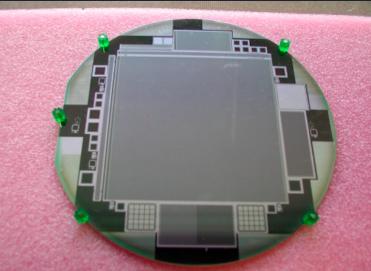
The collection time can be reduced by over-biasing the sensor



DC Silicon Strip Detectors

- The drift (current) creates a signal which is amplified by an amplifier connected to each strip allowing precise position determination
- Standard configuration:
 - p⁺n junction: N_A ≈ 10¹⁹ cm⁻³, N_D ≈ 1-5·10¹² cm⁻³
 - Substrate n doped (~2-10 kΩcm) and ~300µm thick
 - n⁺ layer on backplane to improve ohmic contact
 - Aluminum metallization

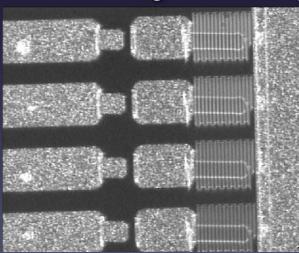


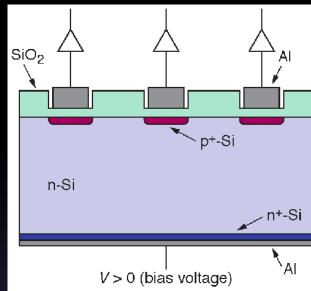


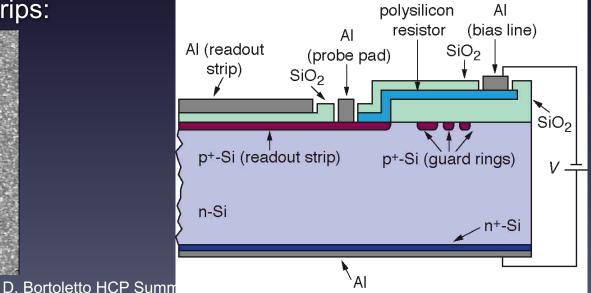
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AC coupled Strip Detector

- AC coupling blocks DC leakage current
- Integration of coupling capacitances in standard planar process.
 - Deposition of SiO₂ with a thickness of 100–200 nm between p+ and aluminum strip
 - Increase quality of dielectric by a second layer of Si_3N_4 .
- Coupling capacitance ≈ 8–2 pF/cm
- Long poly silicon resistor with R>1MΩ to connect the bias voltage to the strips:

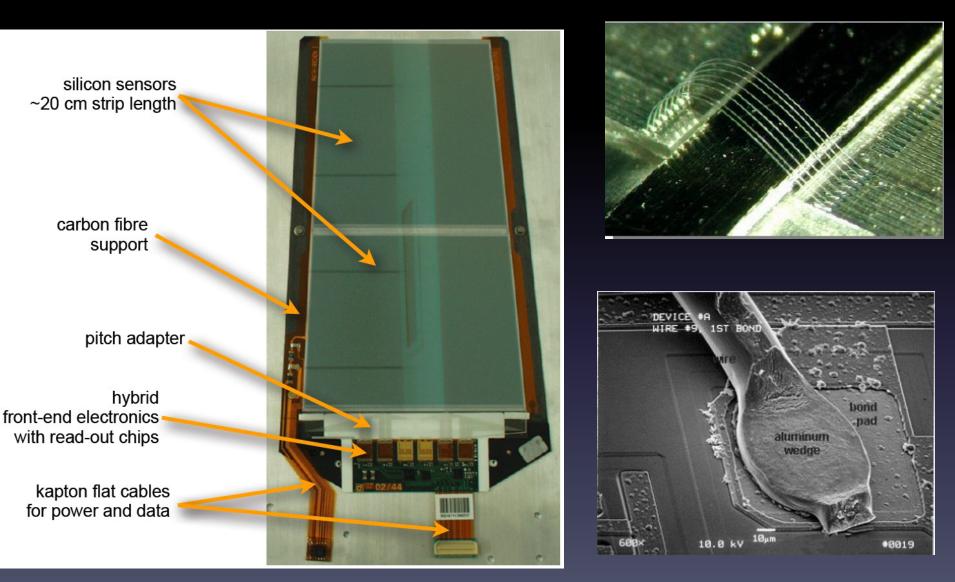








A typical strip module (CMS)

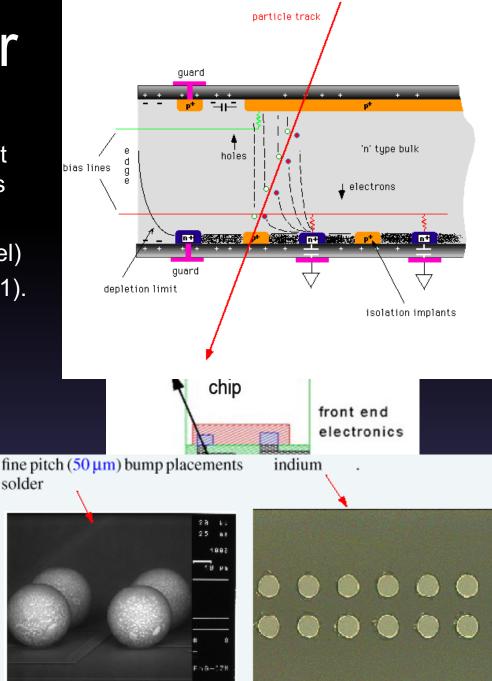


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Pixel detector

- Advantages
 - Pixel detectors provides space-point information removing hit ambiguities
- Small pixel area
 - low detector capacitance (≈1 fF/Pixel)
 - large signal-to-noise ratio (e.g. 150:1).
- Small pixel volume
 - low leakage current (≈1 pA/Pixel)
- n⁺-on n for the LHC
 - Electron have faster collection time
- Disadvantages:
 - Large number of readout channels
 - Large bandwidth
 - Large power consumption
 - Bump bonding is costly and complex



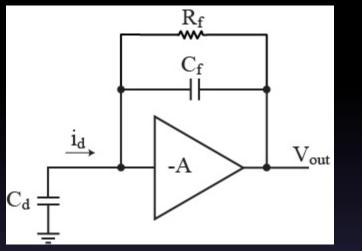
https://www.youtube.com/watch?v=ojeVwQxOrGo&feature=youtu.be



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Readout

• The signal of a silicon detector is readout by a charge sensitive amplifier



$$V_o = \frac{Q_D}{C_f}$$

 $\tau_{\rm f} = R_{\rm f}C_{\rm f}$

- The most simple CSA has a feedback capacitor C_f between the input and output stores the charge from the detector.
- The gain of the preamplifier is $1/C_{f}$.
- The resistor in parallel with the feedback capacitor can be used to reset the CSA
- Each pulse of current from the detector causes on output voltage proportional to the integral of the detector current

$$V_{out}(t) \propto Q(t) = \int_{a}^{t} d\tau$$



Readout Noise

 $ENC_{tot}^2 = ENC_{shot}^2 + ENC_{therm}^2 + ENC_{1/f}^2$

ENC =

Noise is given as
 "equivalent noise
 charge" ENC.

noise output voltage (rms)

signal output voltage for the input charge of 1e⁻

Immer School $au_f = ext{feedback time constant}$

Reference Rossi, Fischer, Rohe, Wermes Pixel Detectors

$$ENC_{\text{shot}} = \sqrt{\frac{I_{\text{leak}}}{2q}}\tau_{f} = 56e^{-} \times \sqrt{\frac{I_{\text{leak}}}{nA}\frac{\tau_{f}}{\mu s}}$$

$$ENC_{\text{therm}} = \frac{C_{f}}{q}\sqrt{\langle v_{\text{therm}}^{2}\rangle} = \sqrt{\frac{kT}{q}\frac{2C_{D}}{3q}\frac{C_{f}}{C_{\text{load}}}} = 104e^{-} \times \sqrt{\frac{C_{D}}{100}\frac{C_{f}}{\text{F}}\frac{C_{f}}{C_{\text{load}}}}$$

$$ENC_{1/f} \approx \frac{C_{D}}{q}\sqrt{\frac{K_{f}}{C_{ox}WL}}\sqrt{\ln\left(\tau_{f}\frac{g_{m}}{C_{\text{load}}}\frac{C_{f}}{C_{D}}\right)}} = 9e^{-} \times \frac{C_{D}}{100}\text{ fF} \text{ (for NMOS trans.)}$$

$$W, L = \text{ width and length of trans. gate}$$

$$K_{f} = 1/\text{f noise coefficient}$$

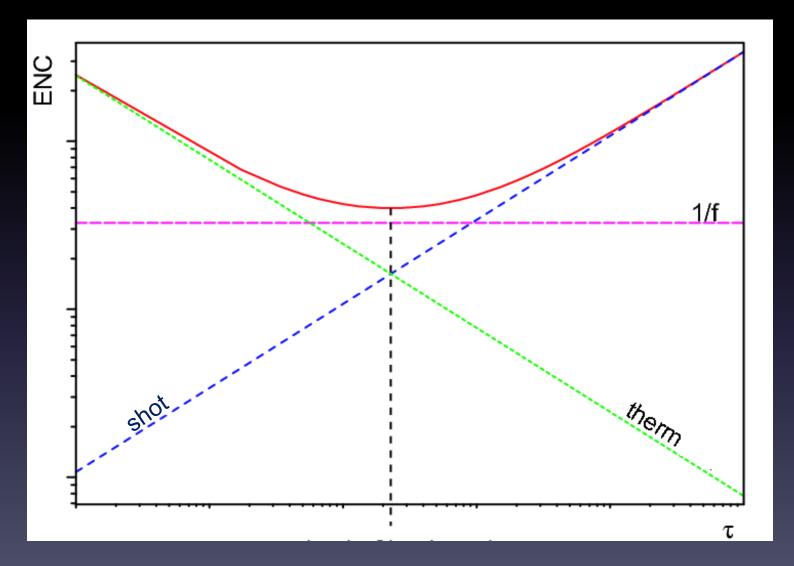
$$C_{f} = \text{feedback capacitance}$$

$$C_{D} = \text{detector capacitance}$$

 $C_{ox} = \text{gate oxide capacitance}$



Noise

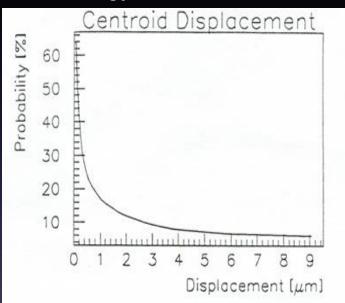




Position resolution

The position resolution depends on various factors

- Physics processes:
 - Diffusion of charge carriers
 - Statistical fluctuations of the energy loss



Low probability $\delta(E)$ release additional electrons drifting perpendicularly to the track and spoiling position resolution

- External parameters
 - Binary readout or read out of analogue signal value
 - Distance between strips/pixels (pitch)
 - Signal to noise ratio
 - Strip detector with binary readout

$$\sigma_X = \frac{p}{\sqrt{12}}$$

- Typical pitch (distance between strips) 100-50 μm → σ_x≃10-30 μm
- One can do better with analog readout

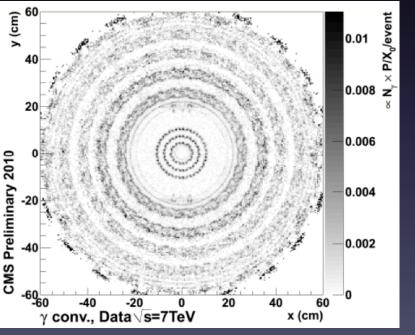




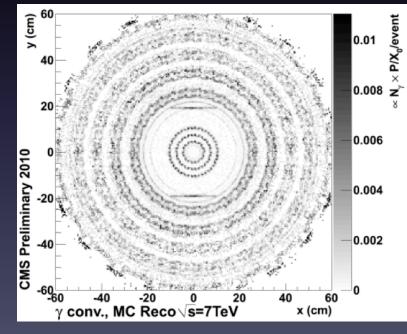
Material

- Reconstruction of photon conversions (γ→e⁺e⁻) can provide precise map of the material
 - The number of photon conversion in a volume ≈ amount of material x reconstruction efficiency
 - The reconstructed vertices can be used to build detailed maps of the Tracker material

DATA



MC

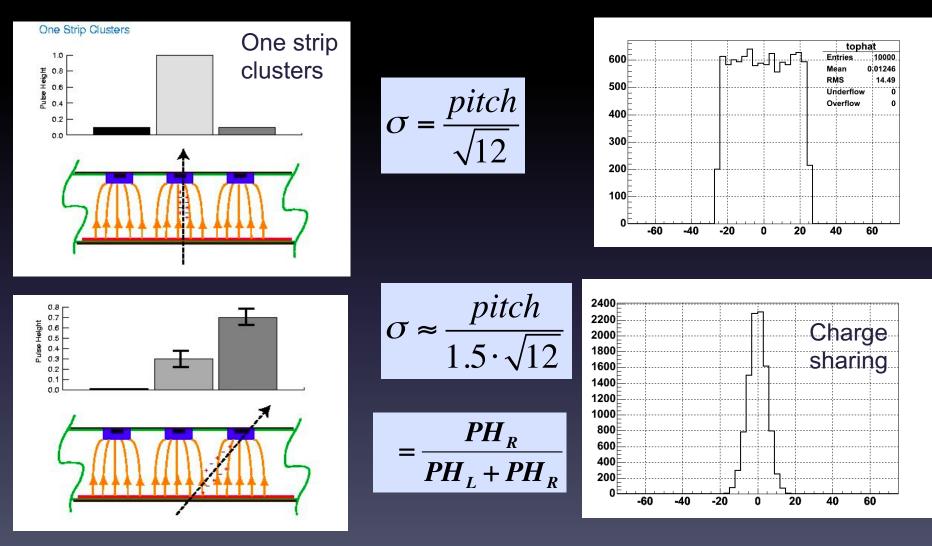


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Position resolution

• Resolution is the spread of the reconstructed position minus the true position





Tracking at the LHC

- ~1200 tracks every 25 ns or ~ 10¹¹/second
 - high radiation dose $10^{15}~n_{eq}$ / cm^2 / 10 yrs
 - 600 kGy (60 Mrad) through the ionisation of mips in 250 μm bulk silicon
- Vertexing is critical to distinguish high p_T collision from pile up:
 - $-\,$ LHC has a Gaussian sigma along the beam direction of ~ 8 cm
 - Vertices of the different inelastic collisions are separated by ≈1 cm on average
- Tracker must deal with very complex pattern recognition
 - Many measurement layers
- Complexity increases as a function of the occupancy (<number of hits>/ event in one elementary detector element)
 - Need to have occupancy <1%
- Most particles are inside the detector in the next bunch crossing
 - − high p_T particles travel ≈7 m from the interaction point in 25 ns
 - low p_T particle may curl 2–3 times inside the tracker



CMS TIB strip

The ATLAS pixel

The LHC detectors

The LHCb- VELO strip \ The ATLAS SCT strip

ALICE

pixel

The CMS pixel

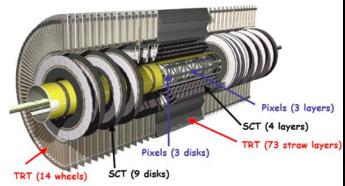
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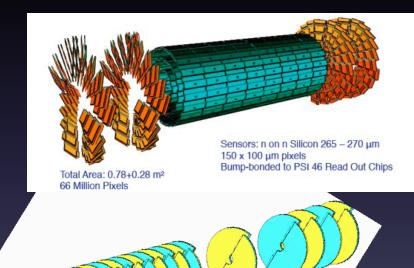
The LHC silicon detectors

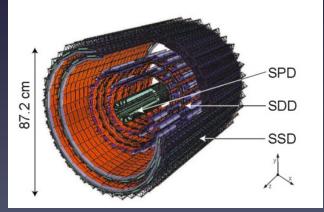
 ATLAS Strips: 61 m² of silicon, 4088 modules, 6x10⁶ channels Pixels: 1744 modules, 80 x 10⁶ channels

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- CMS the world largest silicon tracker 200 m² of strip sensors (single sided) 11 x 10⁶ readout channels ~1m² of pixel sensors, 60x10⁶ channels
- ALICE Pixel sensors, Drift detectors
 Double sided strip detectors







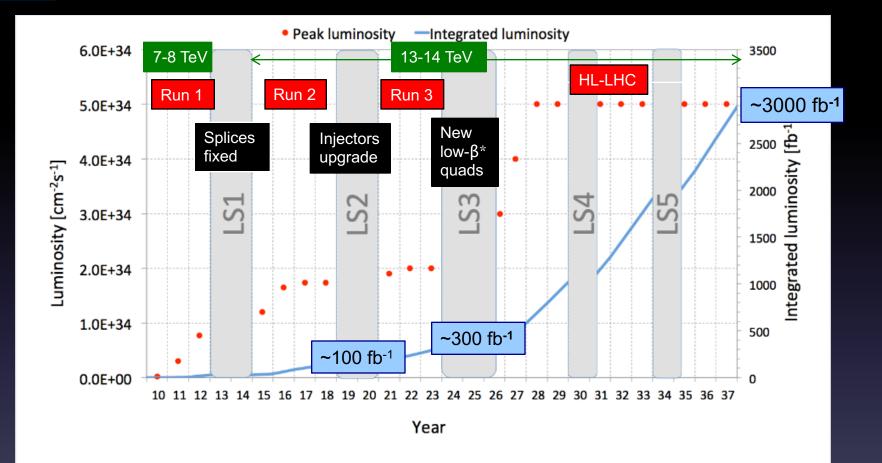
LHCb VELO: Si Strips



Comparison of LHC trackers

	ALICE	ATLAS	CMS
R inner	3.9 cm	5.0 cm	4.4 cm
R outer	3.7 m	1.1 m	1.1 m
Length	5 m	5.4 m	5.8 m
η range	0.9	2.5	2.5
B field	0.5 T	2 T	4 T
Total X ₀ near η=0	0.08 (ITS) + 0.035 (TPC) + 0.234 (TRD)	0.3	0.4
Power	6 kW (ITS)	70 kW	60 kW
rø resolution near outer radius	~ 800 μm TPC ~ 500 μm TRD	130 μm per TRT straw	35 μm per strip layer
p _⊤ resolution at 1GeV and at 100 GeV	0.7% 3% (in pp)	1.3% 3.8%	0.7% 1.5%

The LHC Future



□ LIU/HL-LHC Cost & Schedule reviews in March 2015 and October 2016

□ ATLAS and CMS: "scoping documents" presented to Resources Review Board October 2015

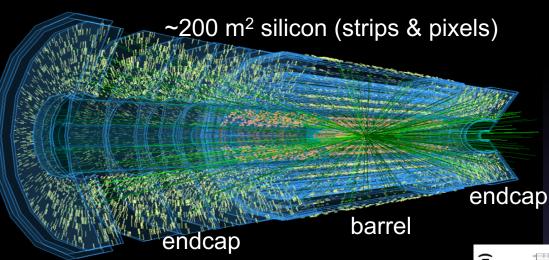
 \rightarrow scale of funding defined, now proceeding to TDRs

❑ ALICE and LHCb: major upgrades under construction for installation in LS2

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Fabiola Gianotti
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HL-LHC tracker upgrades New all-silicon trackers for ATLAS and CMS

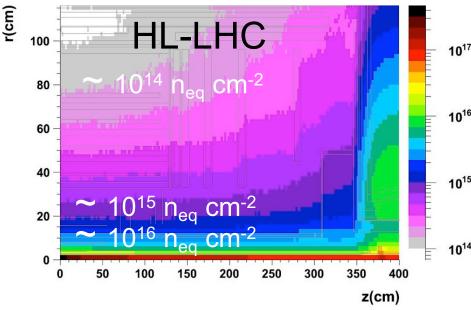


- Increased luminosity and larger area require
 - Higher hit-rate capability
 - Increased granularity
 - Higher radiation tolerance
 - Lighter detectors
 - Cheaper price tag !!

- Radiation hardness and rate • performance must increase compared to LHC Run I
 - Run 2 (2015) ≈ x5

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- Run 3 (2018) ≈ x 5-10
- HL-LHC (>2025) ≈ x 10-30
- In the inner pixel layers: •
 - $10^{16} n_{eq} \text{ cm}^{-2}$ and TID > 1 Grad





References

- Interaction with Matter & detectors:
 - CERN Summer school lectures (D. Bortoletto, W. Reigler): <u>https://indico.cern.ch/event/387976/</u>
 - The Physics of Particle detectors- DESY- organized by E. Garutti http://www.desy.de/~garutti/LECTURES/ParticleDetectorSS12/Lectures_SS2012.ht
 - CERN-Fermilab Hadron Collider Physics Summer School: <u>http://hcpss.fnal.gov/hcpss14/</u>
- Silicon: Manfred Krammer http://www.hephy.at/fileadmin/user_upload/Lehre/Unterlagen/Praktikum/Halbleiterdet ektoren.pdf
- CMOS:
 - I. Peric :<u>https://indico.cern.ch/event/237380/</u>
 - W.Snoyes
 <u>https://agenda.infn.it/getFile.py/access?contribId=62&resId=0&materialId=slides&confld=8834</u>
- Tracking
 - Excellent lectures on tracking algorithms by A. Saltzburger at HCPSS2014
 - Previous CERN academic lecture by P. Wells https://indico.cern.ch/event/526765/
- New ideas for silicon detectors:
 - Great summary by Norbert Wermes at VCI 2016: <u>https://indico.cern.ch/event/391665/sessions/160850/#20160215</u>
 - TWEPP: Topical Workshop on electronic for Particle Physics. Excellent talk by F. Faccio on radiation effects on electronics
 - VCI, VERTEX, PIXEL, Trento workshops



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- Avery P. Applied fitting theory III: Non Optimal Least Squares Fitting and Mutiple Scattering, CLEO note CBX 91-74 (1991) see: <u>http://www.phys.ufl.edu/~avery/fitting.html</u>
- Avery P., Applied fiting theory V: Track Fitting Using the Kalman Filter, CLEO note CBX 92-39 (1992) see: http://www.phys.ufl.edu/~avery/fitting.html
- Fruhwirth R. Application of Kalman Filtering to Track and Vertex Fitting NIM A262 p. 444 (1987)