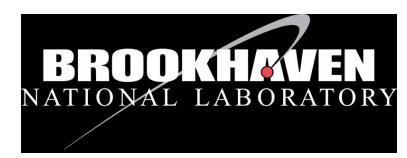
Brief Introduction to Wire-Cell

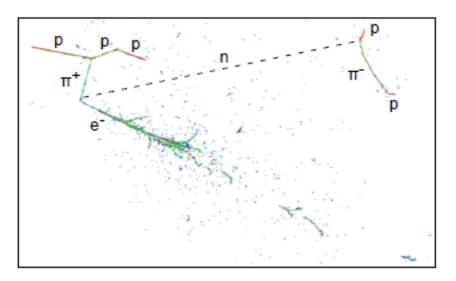
Xin Qian BNL For the Wire-Cell Team http://www.phy.bnl.gov/wire-cell/

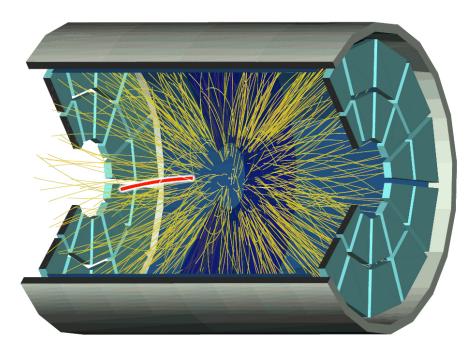
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Challenges of Event Reconstruction in LArTPCs

- Event topology:
 - Tracks, showers, unknown vertex in LArTPCs
 - Simple tracks in collider's gas TPCs



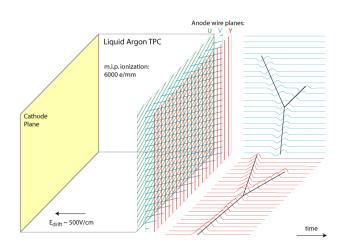


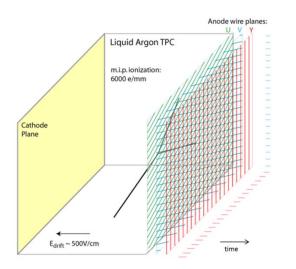
- Wire vs. Pixel readout
 - Large LArTPCs has to use wire readout due to **power consumption** of electronics and **costs**
 - Puedo-3D detector

Review of Existing Approaches

2D matching \rightarrow 3D

Wire-Cell Approach





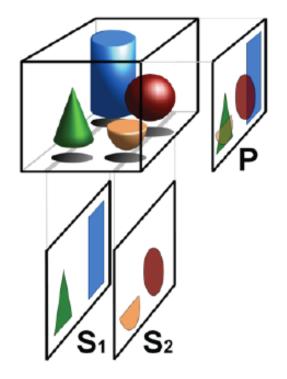
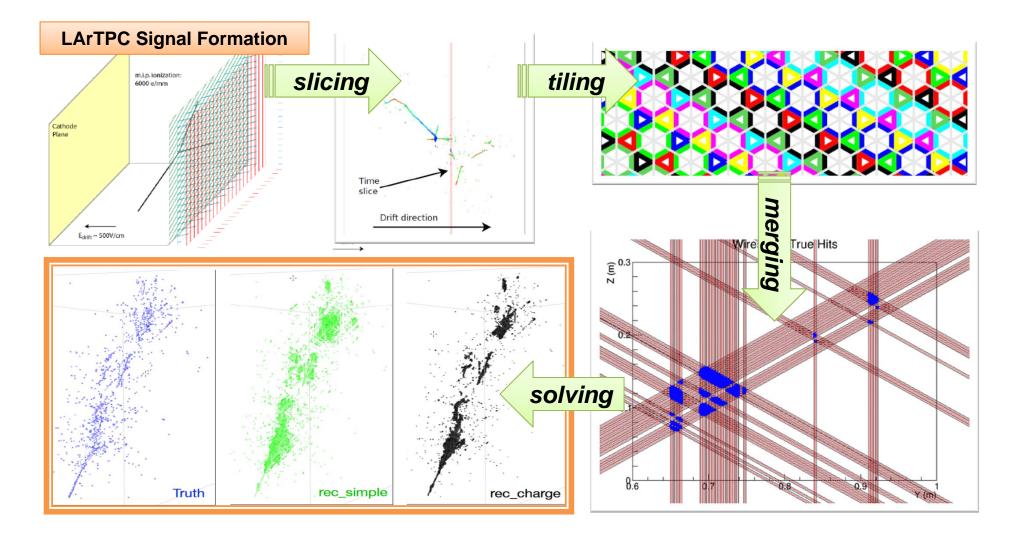


Fig.1:Basic principle of tomography: superposition free tomographic cross sections S1 and S2 compared with the projected image P

https://en.wikipedia.org/wiki/Tomography

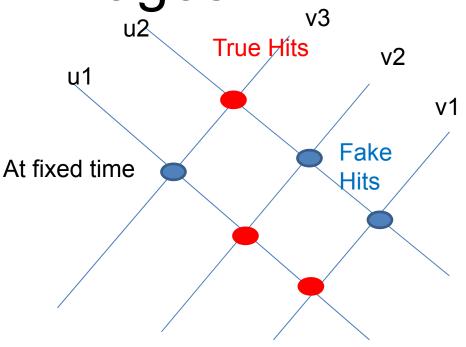
Wire-Cell Imaging



Solving for Images

$$\chi^{2} = (\mathbf{B} \cdot \mathbf{W} - G \cdot C)^{T} V_{BW}^{-1} (\mathbf{B} \cdot \mathbf{W} - G \cdot C)$$
$$\frac{\partial \chi^{2}}{\partial C} = 0 \rightarrow C = (\mathbf{G}^{T} V_{BW}^{-1} \mathbf{G})^{-1} G^{T} V_{BW}^{-1} BW$$

- C: charge in each (merged) cell
- G: Geometry matrix connecting cells and wires
- W: charge in each single wire
- B: Geometry matrix connecting merged wires and single wires
- V_{BW}: Covariance matrix describing uncertainty in wire charge

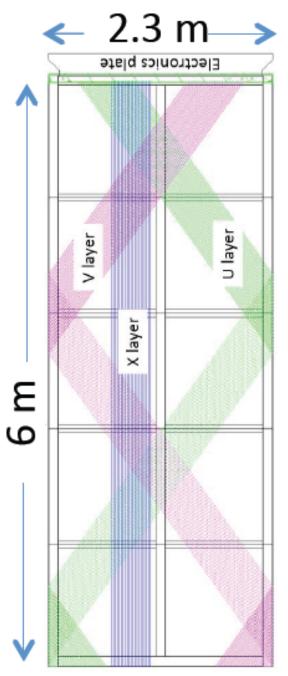


- Use two-plane as an example
- Red points are true hits
- Blue ones are fake hits

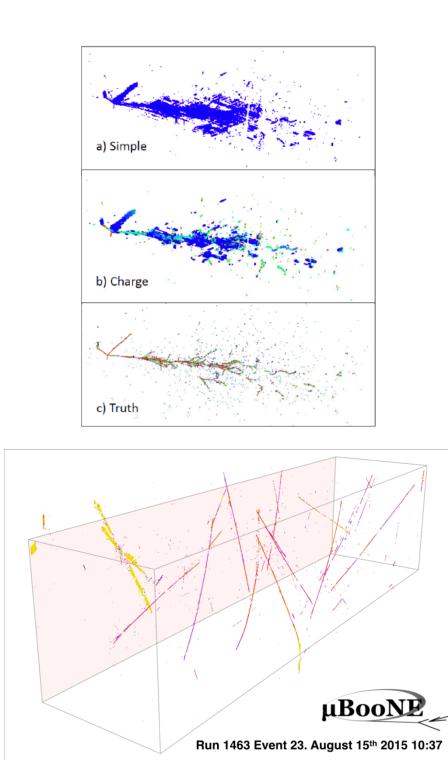


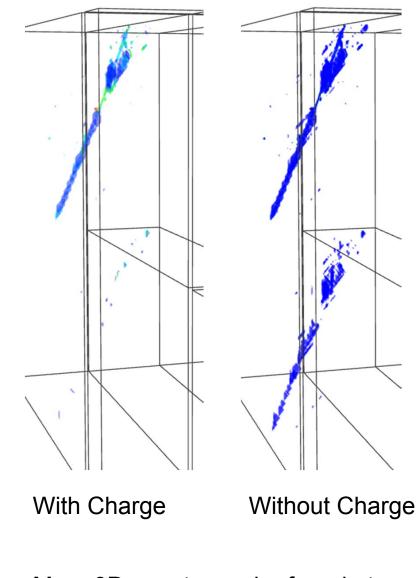
Same formulism for DUNE Wrapped Wire $\chi^2 = (B \cdot W - G \cdot C)^T V_{BW}^{-1} (B \cdot W - G \cdot C)$ $C = (G^T V_{BW}^{-1} G)^{-1} G^T V_{BW}^{-1} BW$

- C: charge in each (merged) cell
- G: Geometry matrix connecting cells and **channels**
- W: charge in each single channel
- B: Geometry matrix connecting merged channels and single channels
- V_{BW}: Covariance matrix describing uncertainty in **channel** charge



Xiaoyue Li (Stony Brook)





More 3D events can be found at http://www.phy.bnl.gov/wire-cell/bee/ Bee: interactive 3D display (Chao Zhang)

The Usage of Connectivity

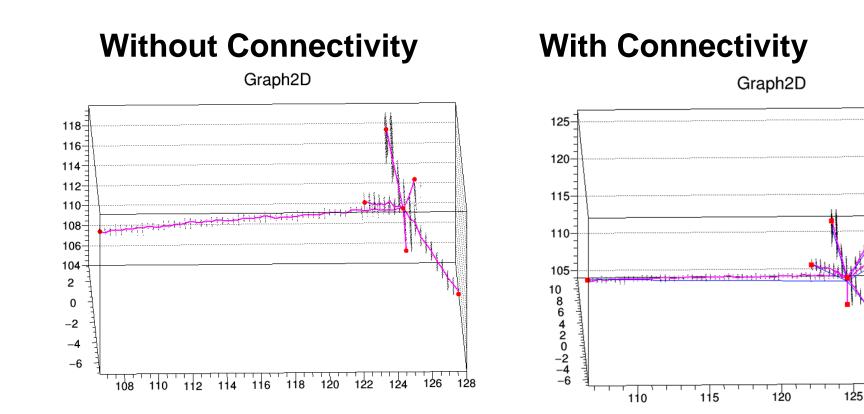
- We can add penalty to χ² based on connectivity and single channel assumption
 - For example, if we remove a merged cell that are connected to good cells in the adjacent time slice, we can add penalty in χ^2 to increase the chi-square value \rightarrow less chance to be chosen as the optimal solution
- For later pattern recognition, we can also cluster with all merged cell, and then remove bad ones taking into account connectivity

Connectivity information

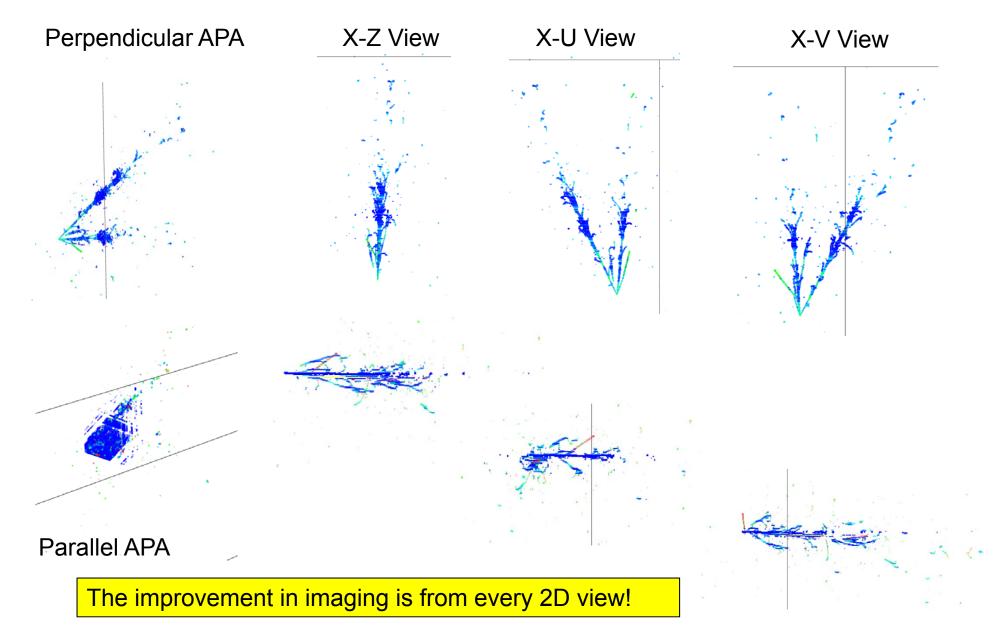
 Use the connectivity information to choose the optimal imaging solution

130

- Penalty term added in chisquare



Parallel vs. Perpendicular APA



Strategy Comparison

2D Matching

- Start with 2D (time+wire x 3)
- 2D pattern recognition
 - Particle track/cluster information
- Matching 2D patterns into 3D objects
 - Time information (start/end of clusters)
 - Geometry information
 - Some charge information to remove ambiguities in matching

3D Tomography

- Start with 2D (wire+wire+wire at fixed time slice)
- 2D image reconstruction
 - Explicit Time + Geometry +
 Charge information
 - Some connectivity information can be used
 - 3D image reconstruction
 - Straight forward
- 3D pattern recognition
 - Particle track/cluster information (tracks, showers)

Each approach uses the same set information in different order!

Discussion (Pros)

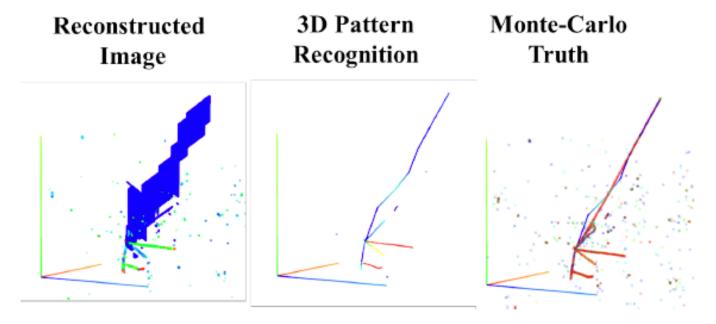
- Wire-Cell Imaging tells us which hits CANNOT be associated together
 - Hits from different time slice CANNOT be associated together (<u>time information</u>)
 - Hits from wires that are not crossing each other CANNOT be associated together (<u>geometry information</u>)
 - Hits with "different" charge is UNLIKELY to be associated together (<u>charge information</u>)
- Advantages:
 - Utilize full TPC information (time/geometry/charge)
 - Natural way to suppress electronics noise
 - Track/shower hypothesis not used, delay the pattern recognition process → better automated
 - Expected to be better for complicated topologies

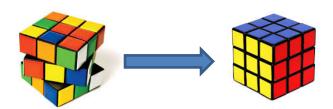
Discussions (Cons)

- Likely worse performance for 2-plane configuration
 - With 2-plane configuration, the power of the geometry information is strongly reduced
 - It is important to use track/shower hypothesis early to reduce ambiguities
- Stringent requirements on TPC performances
 - Relative time among hits from different planes
 - Charge reconstruction from induction plane
 - Use this feature for calibration purpose
 - Also dead channels (more sensitive to inefficiency)
- High resources requirement on the memory and speed

Wire-Cell Pattern Recognition

 Given the 3D images, pattern recognition is performed with the track and shower hypotheses





- Operations are all "local" i.e. Hough transformation, Crawler, Vertex fitting/merging ...
- Too many different topologies → many corner cases

Wire-Cell Solve the Reconstruction Problem?

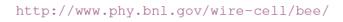
- No!
 - The 3D pattern recognition is still an open question → Pandora 3D pattern recognition, PMA, LineCluster …
 - With recognized pattern, how to do the fine tracking?
 → Projection Matching Algorithm
 - Energy calculation, angle determination, PID ...
- What's the ultimate solution for pattern recognition?
 - Human-directed pattern correction is being developed with modern web-based tools → Bee 2.0
 - Deep learning?

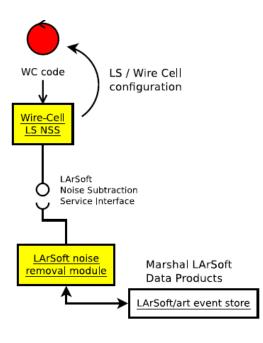
Related Technical Progress



- Bee:
 - Improved on memory usage and UI responsiveness and added object picking.
 - Further performance improvements and a UI redesign coming.
- Wire Cell:
 - Excellent results from prototype noise removal on MicroBooNE data.
 - Porting to Wire Cell Toolkit is underway.
 - LArSoft Noise Subtraction Service Interface developed.
 - WCT NSS implementation will provide first LS/WC integration.
 - Will adopt service-based model for future WC imaging, etc, integration.







Summary

- Advantages and disadvantages of Wire-Cell approach are discussed
- Wire-Cell imaging is in a good shape
- More work is needed for the 3D pattern recognition
- Bee 2.0 is under development
- Integration with LarSoft is in progress