

Projection Matching (PMA)

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ProtoDUNE's Science Workshop

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Outline

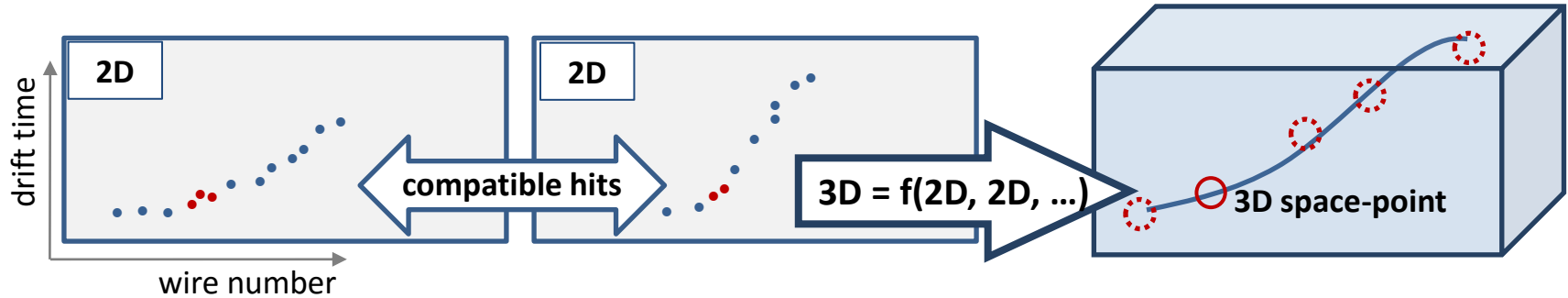
- How *Projection Matching Algorithm* works?
- Possible reconstruction chains using PMA in LArSoft framework.

PMA reconstruction of:

- trajectory and dE/dx
- track–vertex structure
- shower direction

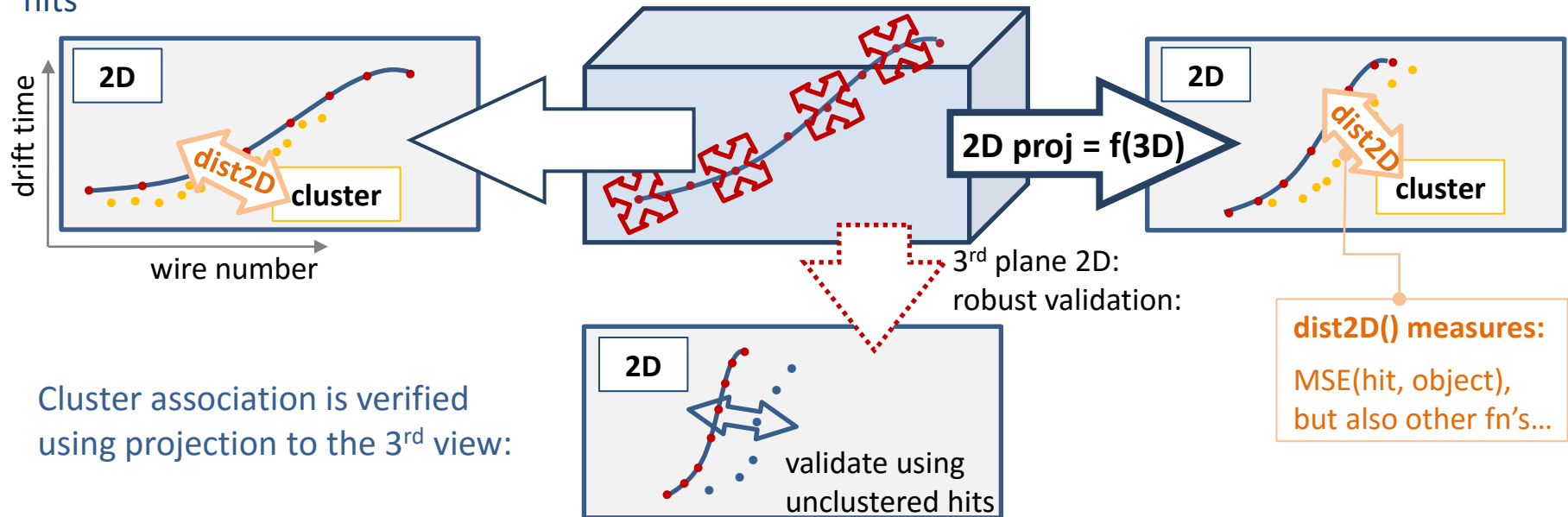
PMA 3D approach: what is different from other approaches

usual: n compatible 2D hits \rightarrow 3D space-point \rightarrow fit 3D trajectories to space-points

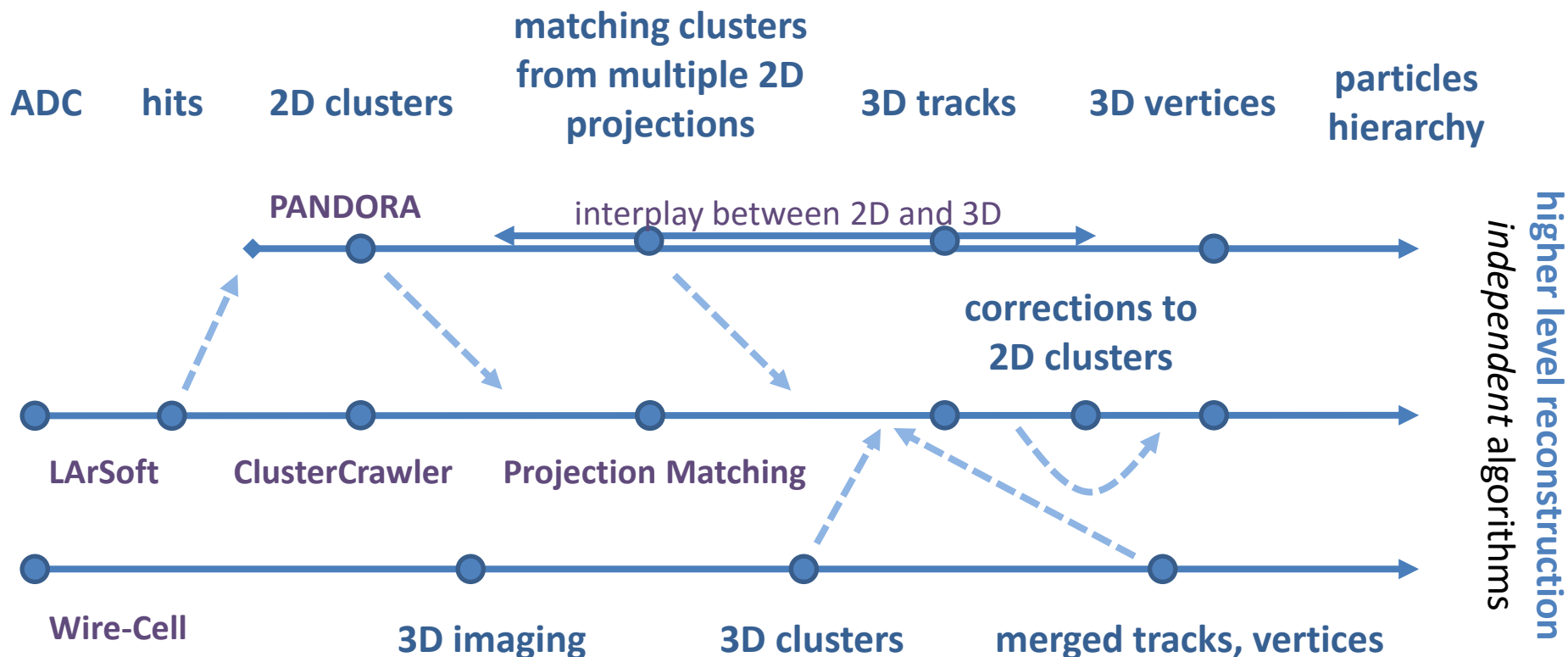


other way around: 3D object(s) \leftrightarrow hits or raw ADC in multiple 2D views

build 3D (*single track* or *full track structures*) to minimize distance the object's 2D projections to 2D hits



PMA place in the reconstruction chain



- **input: pattern recognition at various stages, best if *shower-like / track-like* tagged**
- **output: 3D particle hierarchy (3D tracks + vertices, associations to 2D clusters and hits)**
 - hierarchy stored in PFParticle objects in LArSoft
 - can fit single tracks, or cascade directions with or w/o fixed vertex position
 - dQ/dx sequence for each view

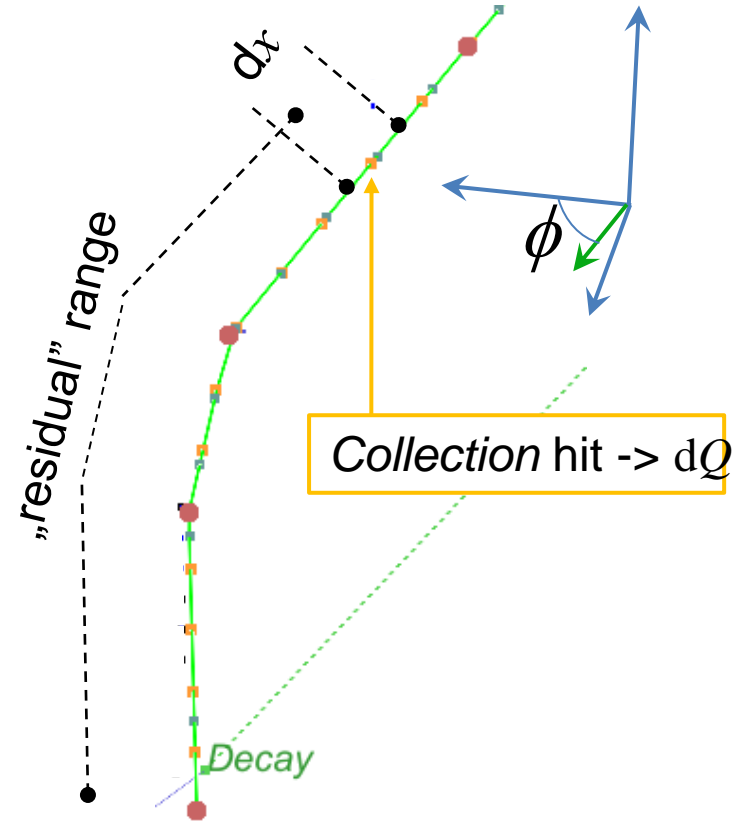
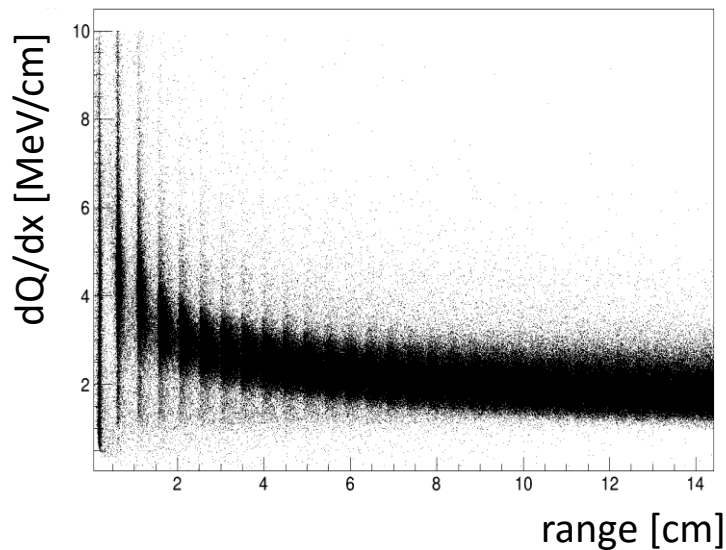
PMA features

- **hit – hit association is not needed**, each 2D hit has its own 3D position on the trajectory, it is ***independent*** from hits in other projections
 - reconstruction can use **2 or 3 views**; even sections with only 1 view are still useful (in case of e.g. difficult track orientation, hit or cluster inefficiency, hardware problems, ...)
 - hit charge is positioned along the trajectory without bias of association to a hit(s) in complementary view -> very good dE/dx
- **full 3D objects are driven directly by 2D information**; no intermediate step with 3D hits/points to be refitted again into tracks in 3D space
- the optimization can take into account also 3D points: vertices, feature points, ..., it is now used to support **wire-plane-parallel** orientation: clean endpoints (or entry/exit points) of tracks are detected
- **basic idea can be widely extended** to many aspects of reconstruction – next slides
- **distortions (space charge, nonuniform E field) can be accommodated** in the 3D→2D projection function used during the optimization if displacement mapping known

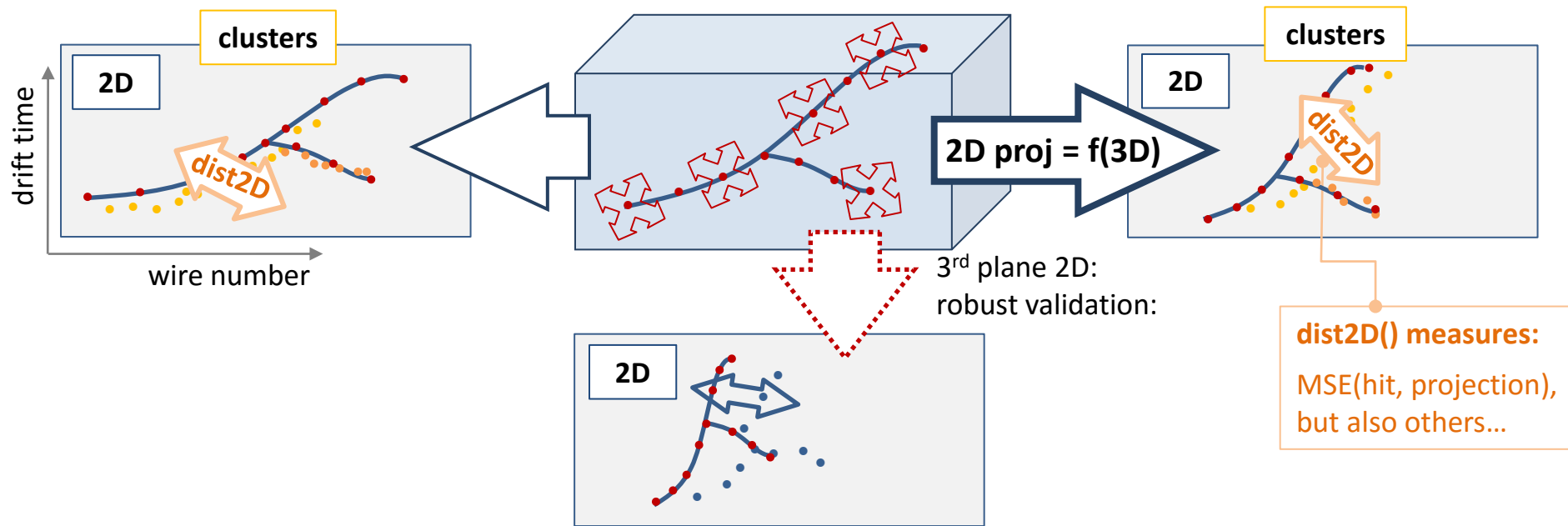
dE/dx output from *Projection Matching*

- *Collection* hit projected to 3D
- *Induction* hit projected to 3D
- reco track nodes
- reco track

dQ/dx vs range of reconstructed muons in protoDUNE



How vertices are reconstructed

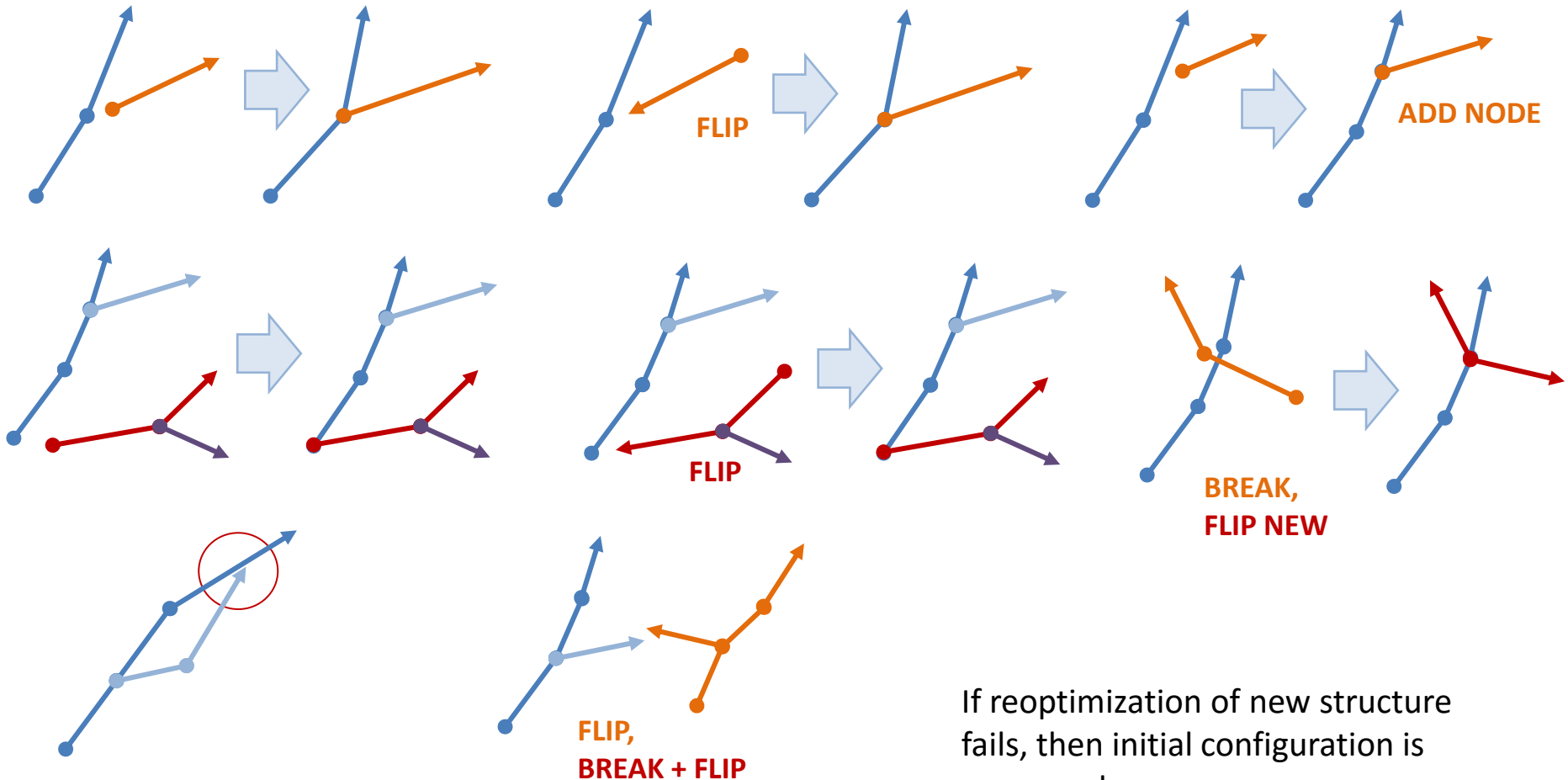


Optimization can be applied to complex structures of tracks interconnected with vertices:

- Build, extend, stitch isolated track first
- Find candidates for track intersections and points where multiple tracks meet
- Join tracks in vertex candidates, reoptimize all tracks together
- **local information from multiple tracks → fit the best position of vertex and track directions**
- Can further improve 2D pattern recognition output
- But needs implementation of complex manipulations on track merging / splitting / ...

Vertices + trajectories grammar

some basic examples of all possibilities

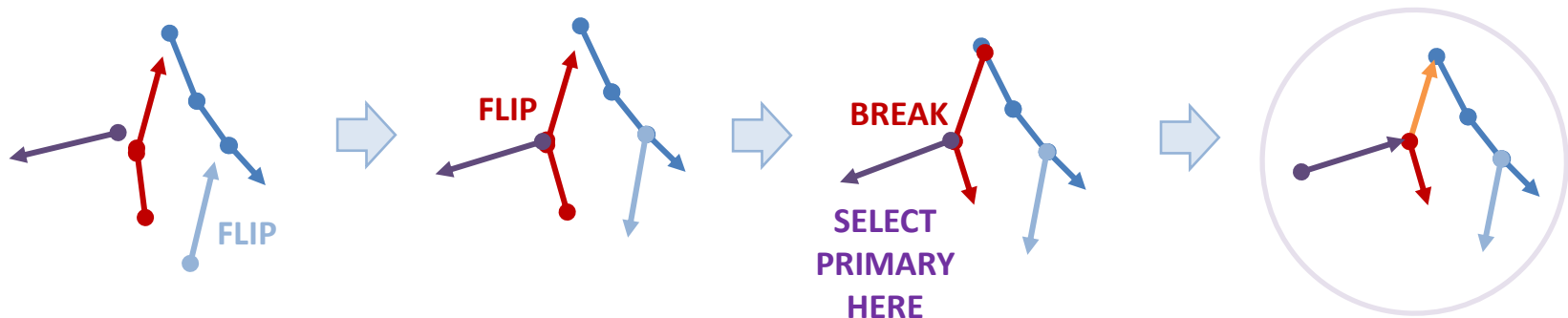
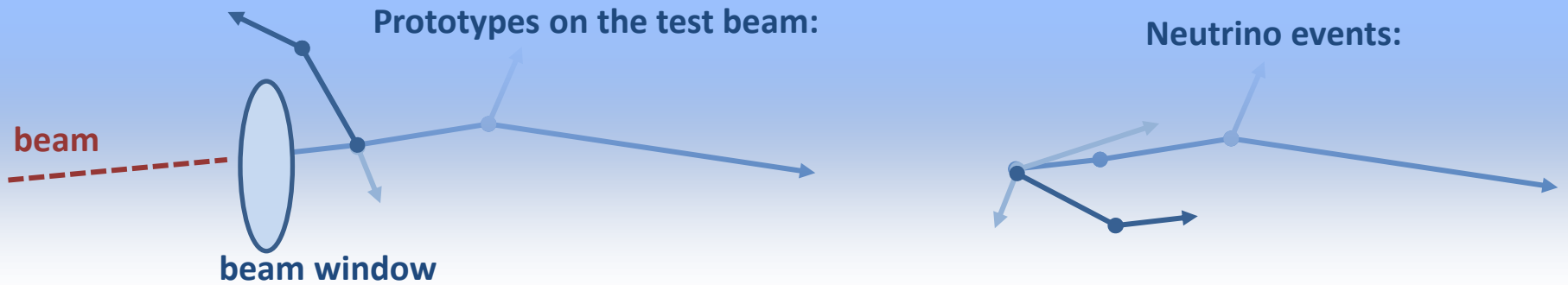


If reoptimization of new structure fails, then initial configuration is recovered.

loops not allowed,
only *tree* structures

not implemented now,
=> vertex missed

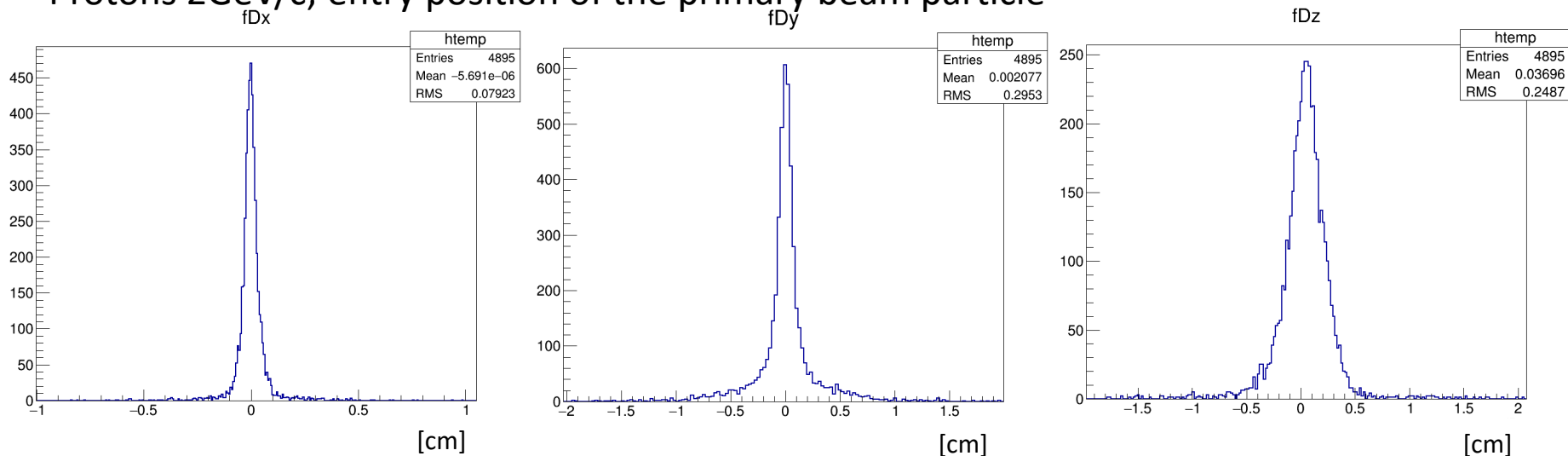
Where is the primary vertex?



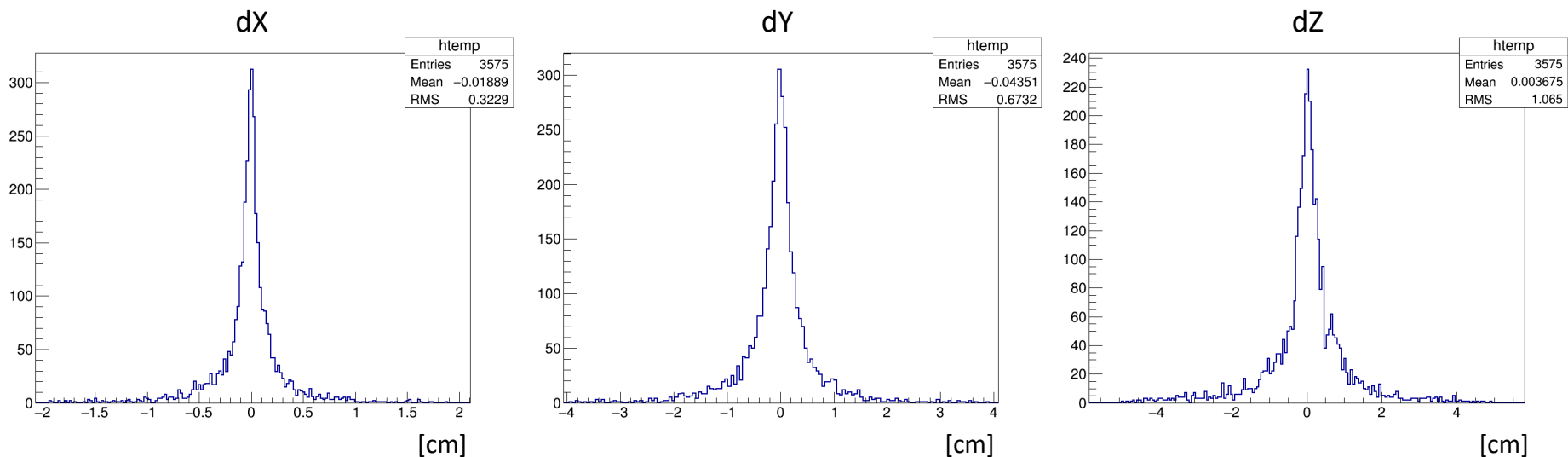
- may be trivial: most upstream vertex for ν beam, but this fails often,
- test beam events: known beam entry position, direction \rightarrow select best matching particle,
- small events (proton decay, low energy neutrino): detect stoppers by dE/dx , adjust directions in the track system accordingly,
- large events: to be developed, primary vertex selection by track orientation and energy at reconstructed vertices.

Vertex reconstruction resolution

Protons 2GeV/c; entry position of the primary beam particle

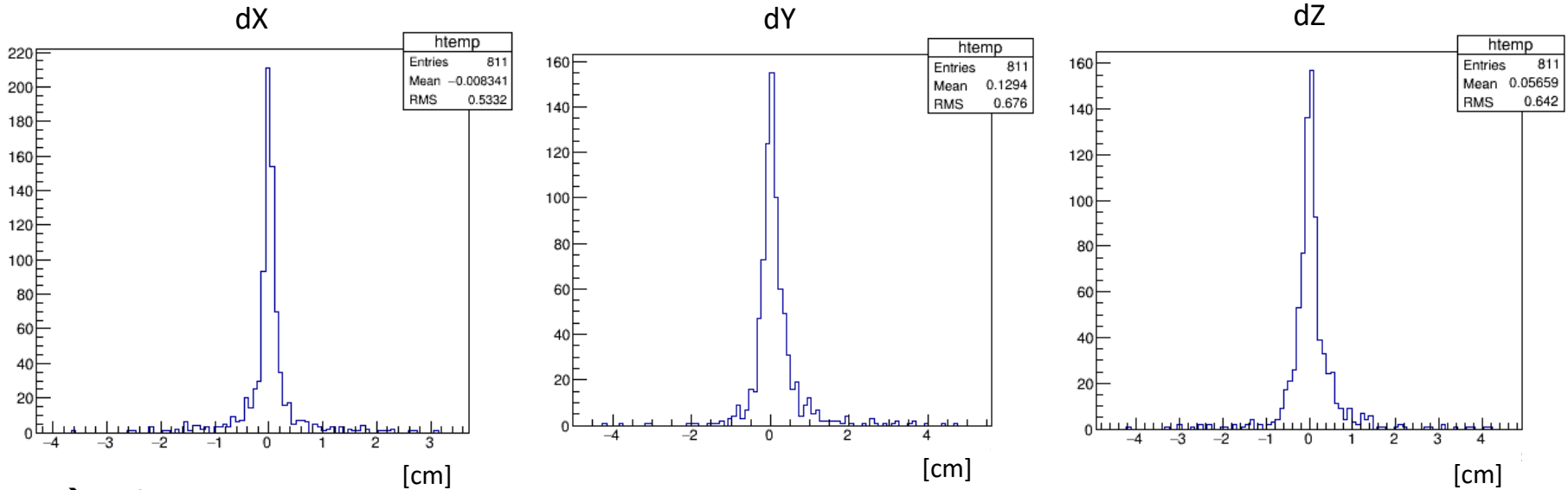


Protons 2GeV/c; first inelastic vertex position, if > daughter with $E_k > 50$ MeV

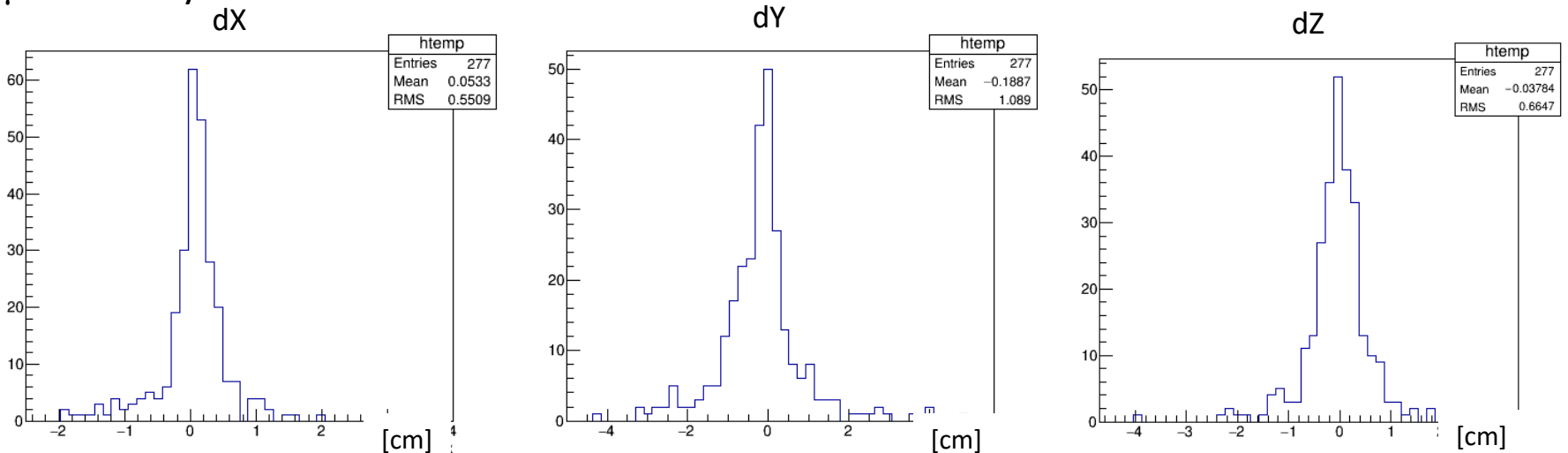


Vertex reconstruction resolution

π^0 in the hadronic system

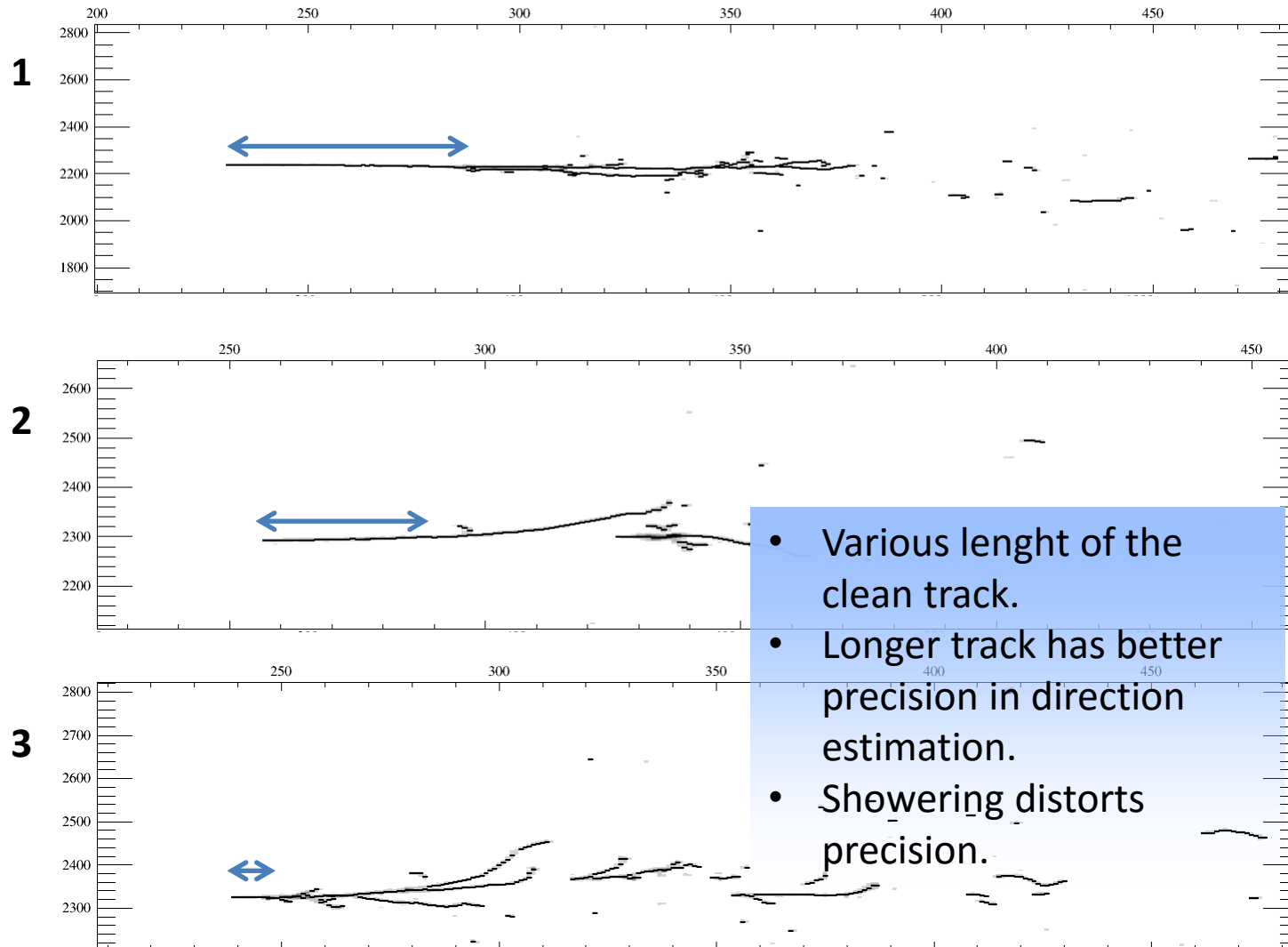


$\mu \rightarrow e$ decay



Showers

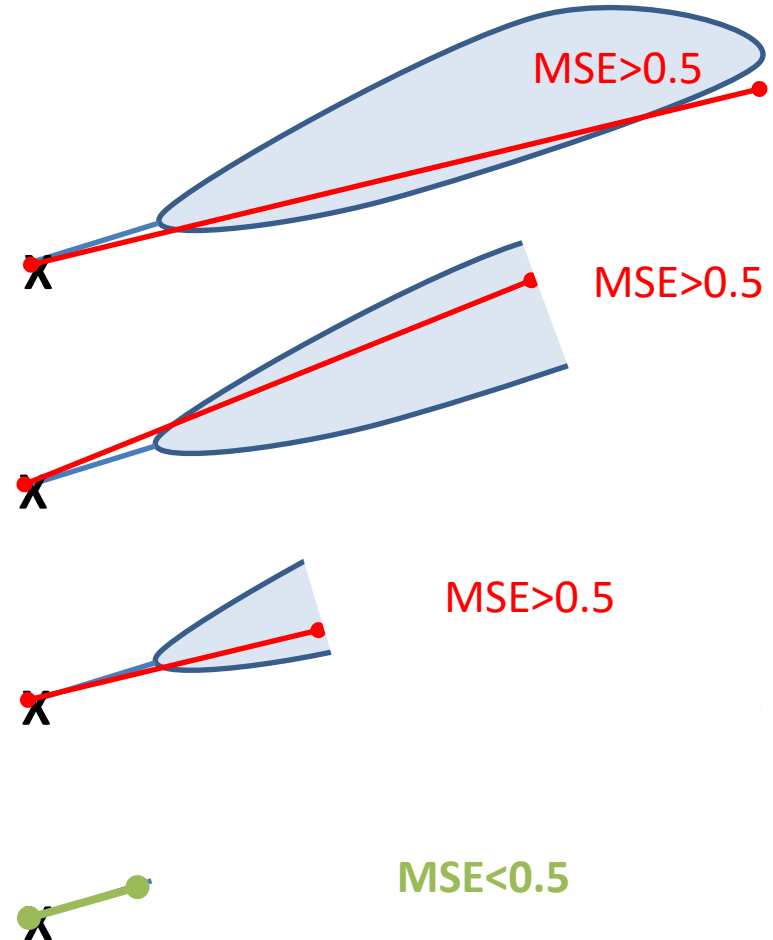
Electrons, the same direction generated



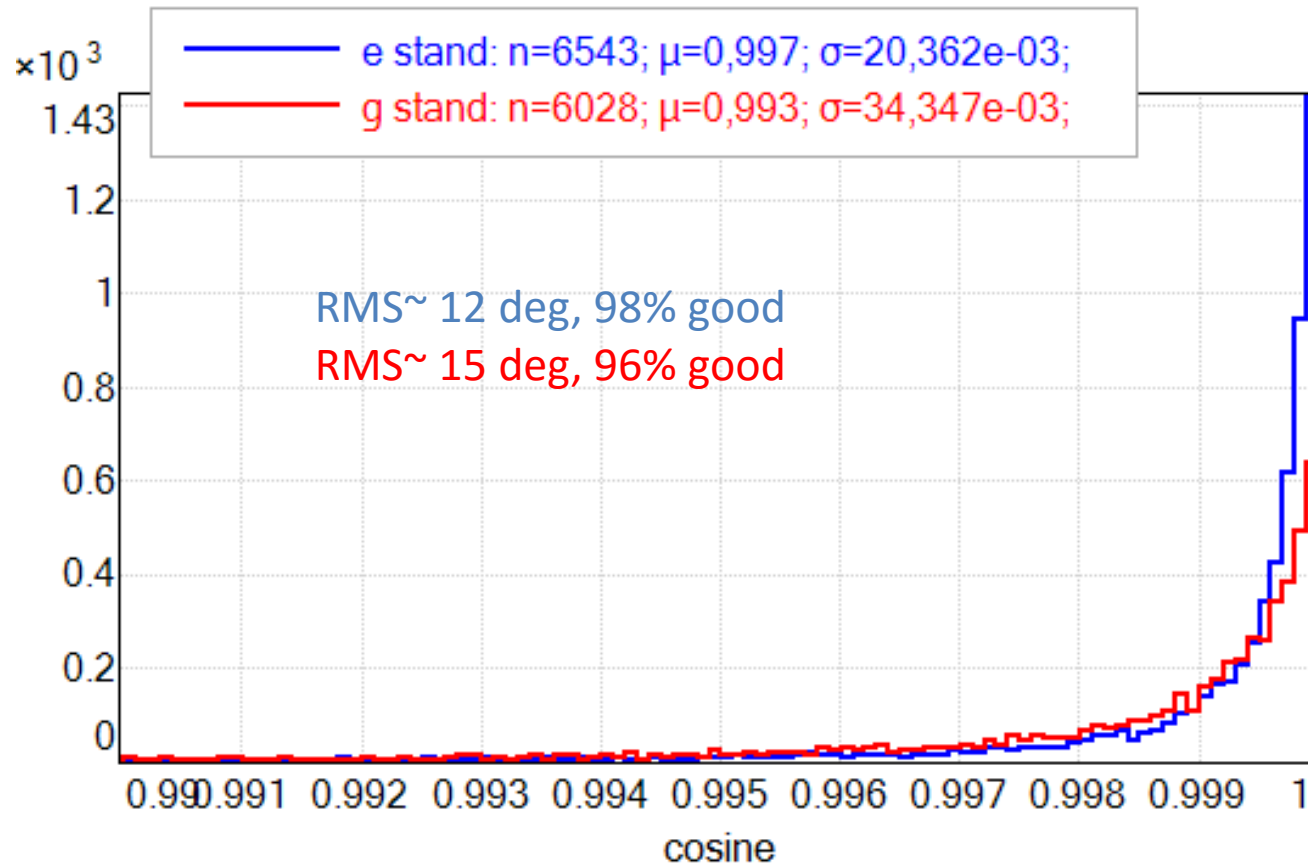
Shower direction reconstruction

1. Input: pattern recognition provides PFParticle tagged as EM shower, with associated clusters and vertex.
2. Compact group of hits is selected in each view, small & isolated fragments are not used.
3. PMA segment is fitted to all hits from the shower; one endpoint is fixed at the vertex.
4. Hits with high range from vertex are removed, segment is reoptimized until MSE is low enough or min segment length is reached.
5. MSE allows to verify if direction is correctly reconstructed.

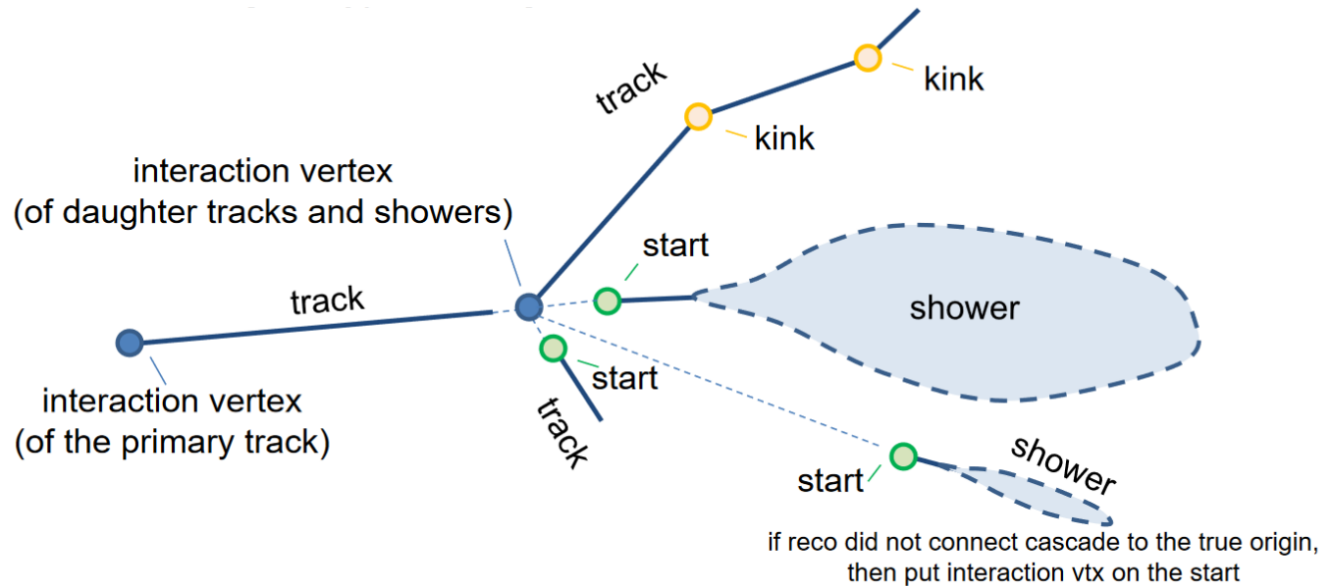
Note: Various shower orientation can prevent segment from correct reconstruction (parallel to the wire plane, initial part of the cascade in a shadow of developed cascade).



Shower direction reconstruction



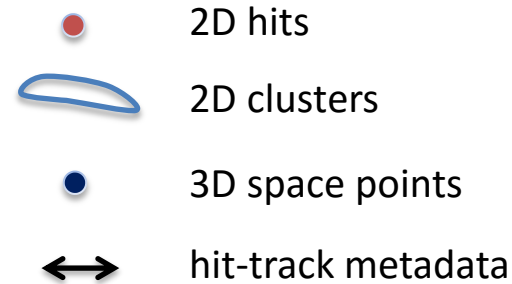
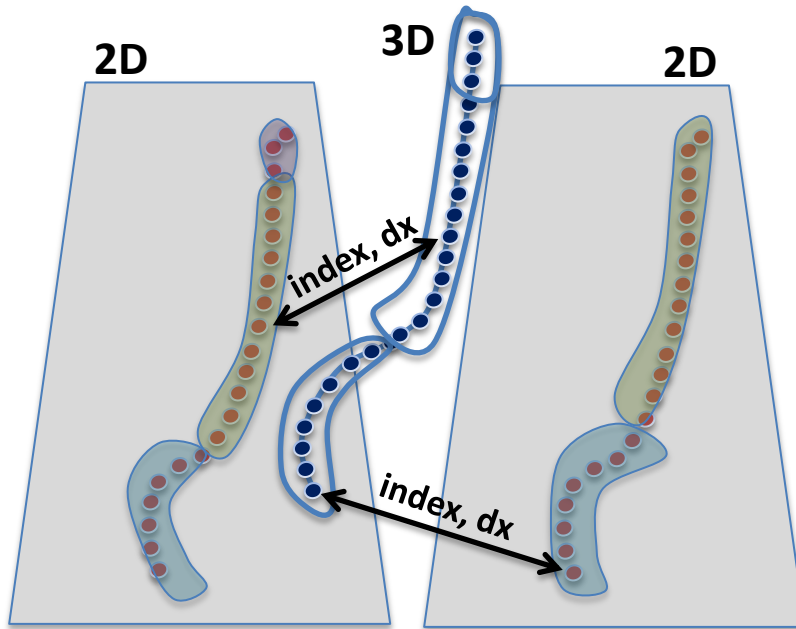
Full reconstructed structure



Define a convention for data products made by PMA → help navigation in analysis codes

- **only one interaction vertex** assigned to each PFParticle / Track:
meaning: interaction point, where particle was created according to the reconstruction,
- **kinks and any other features** saved in accordingly named collections (*art*) and assigned to Tracks using the same instance name for associations,
- **still there is no strict „LArSoft policy”** for such topology descriptions.

Associations: single trajectory

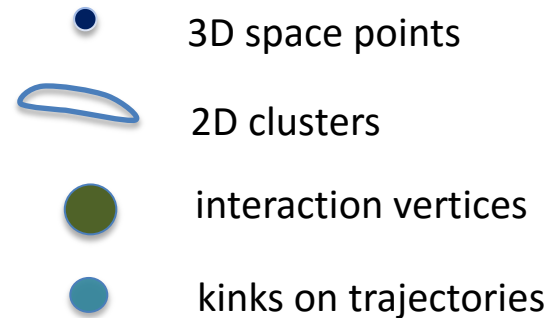
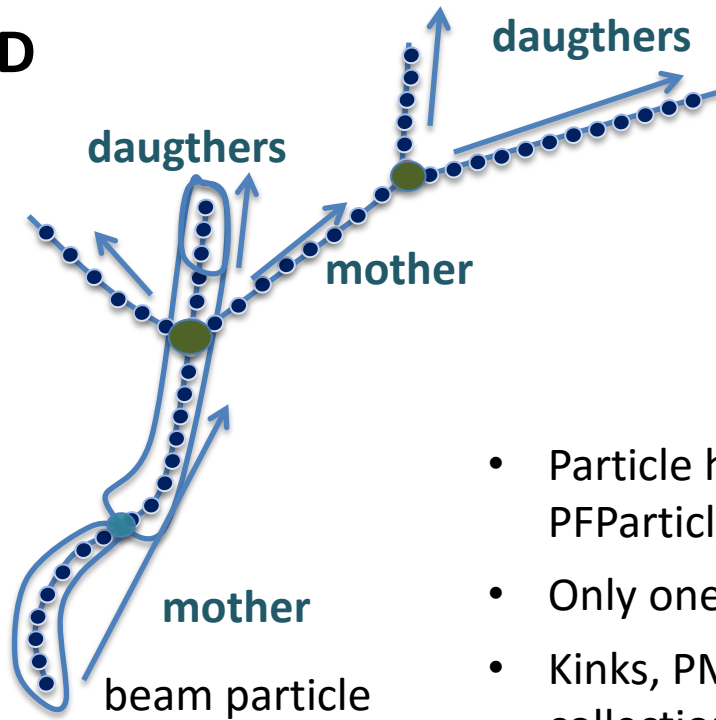


- each 2D hit is associated to its own 3D point
- metadata helps sorting hits along trajectory (index) and find dx seen by hit in its 2D view

```
// howto get dQ/dx from the track:
art::Handle< std::vector<recob::Track> > trkListHandle;
bool hasTrk = evt.getByLabel(trackingModuleLabel, trkListHandle);
art::FindManyP< recob::Hit, recob::TrackHitMeta > hitFromTrk(trkListHandle, evt, trackingModuleLabel);
// ...loop over tracks
    auto vhit = hitFromTrk.at(id);           // get vector of hits for track with id
    auto vmeta = hitFromTrk.data(id);       // get vector of metadata associated with hit-track assns
    // ...loop over hits
        size_t view = vhit[h]->WireID().Plane; // get 2D plane of hit
        size_t idx = vmeta[h]->Index();        // get index of this hit along the trajectory
        double dx = vmeta[h]->Dx();           // dx seen by the hit in its 2D plane
        double tdrift = vhit[h]->PeakTime();  // peak time of the hit
        double dqadc = vhit[h]->Integral();   // dq of this hit
```


Associations: track-vertex structure

3D



PFParticles

- Particle hierarchy (mother→daughters) described with PFParticles.
- Only one interaction vertex assigned to each PFParticle.
- Kinks, PMA nodes: saved as vertices / associated in named collections.

// howto get associations of higher level structures (this is valid today, but may change according to LArSoft policies)

```
art::Handle< std::vector<recob::PFParticle> > pfpListHandle;
```

```
art::Handle< std::vector<recob::Track> > trkListHandle;
```

```
bool hasPfp = evt.getByLabel(trackingModuleLabel, pfpListHandle);
```

```
bool hasTrk = evt.getByLabel(trackingModuleLabel, trkListHandle);
```

```
art::FindManyP< recob::PFParticle > pfpFromTrk(trkListHandle, evt, trackingModuleLabel);
```

```
// track-pfparticle assns
```

```
art::FindManyP< recob::Vertex > vtxFromPfp(pfpListHandle, evt, trackingModuleLabel);
```

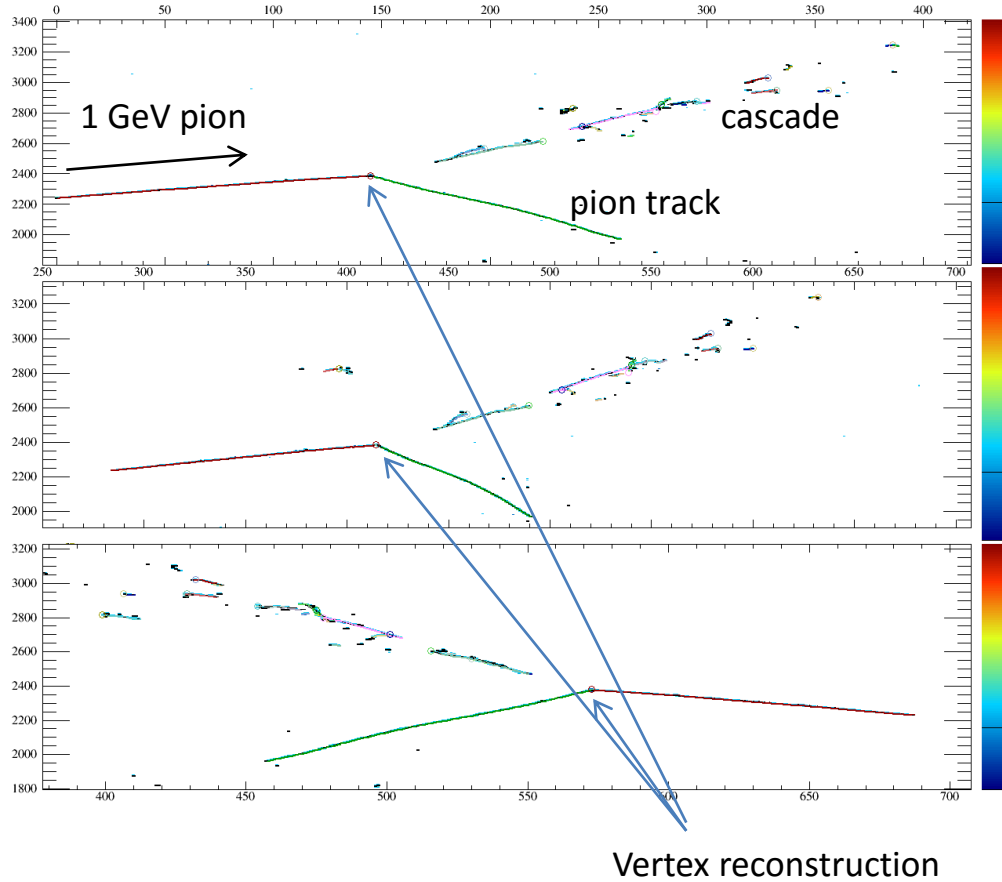
```
// interaction vertices
```

```
art::FindManyP< recob::Vertex > vtxFromPfp(pfpListHandle, evt, art::InputTag(trackingModuleLabel, „kink”));
```

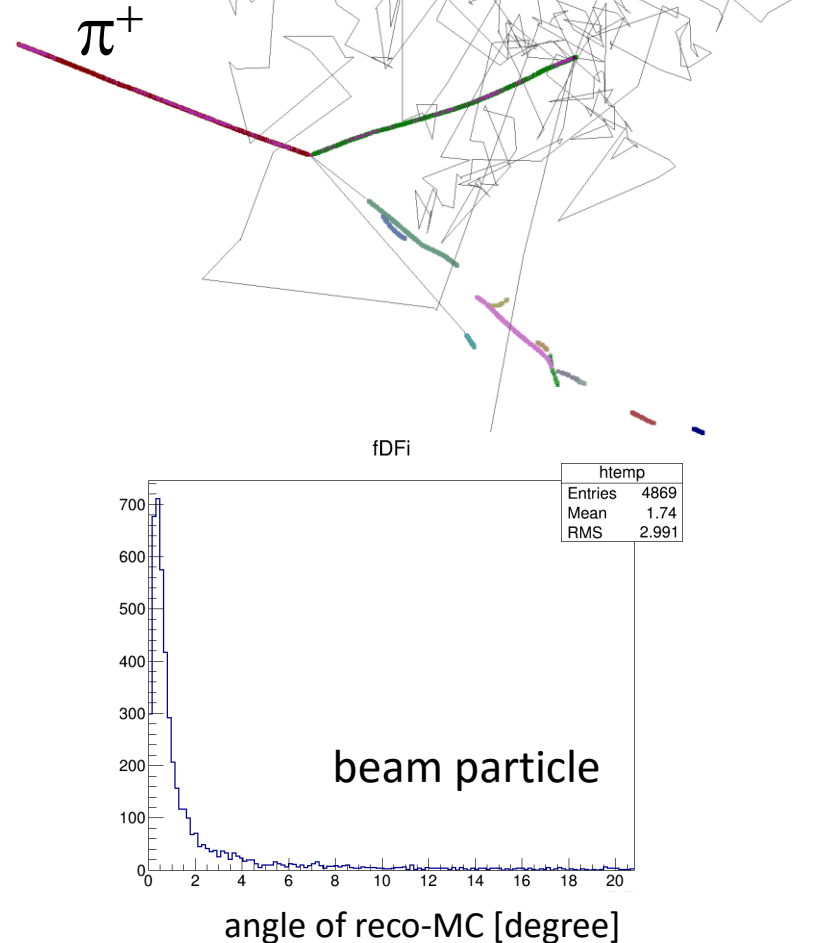
```
// trajectory kinks
```

Topology description, example

2D reconstruction:
cluster crawler

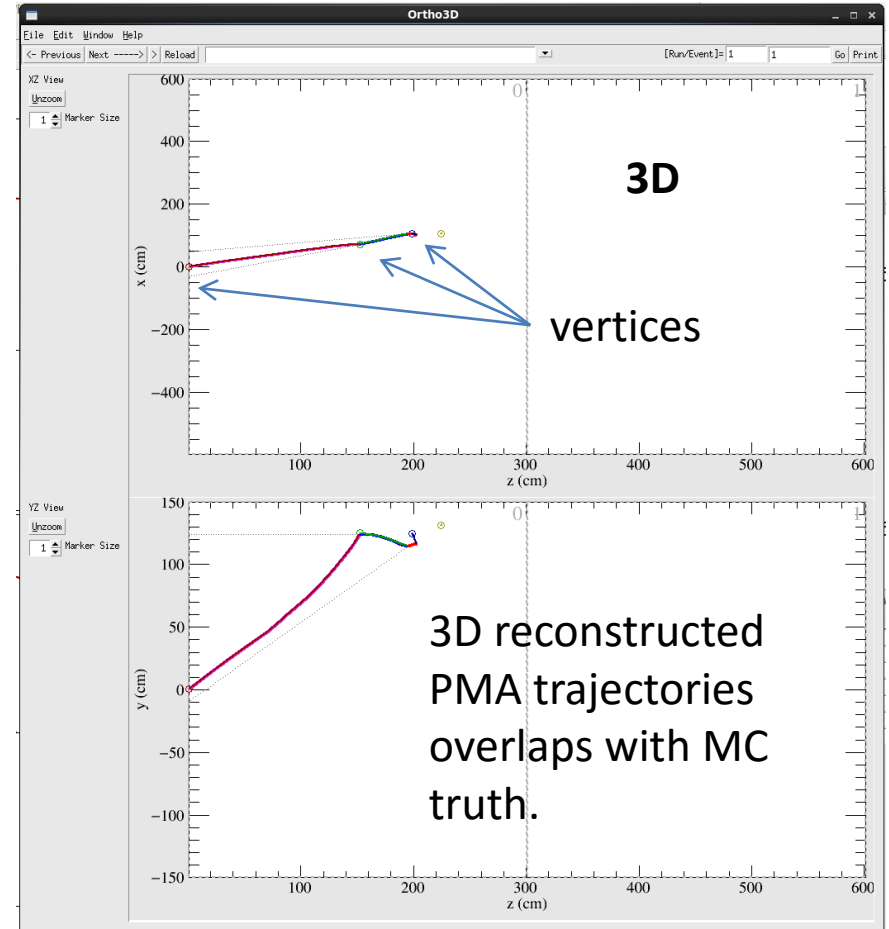
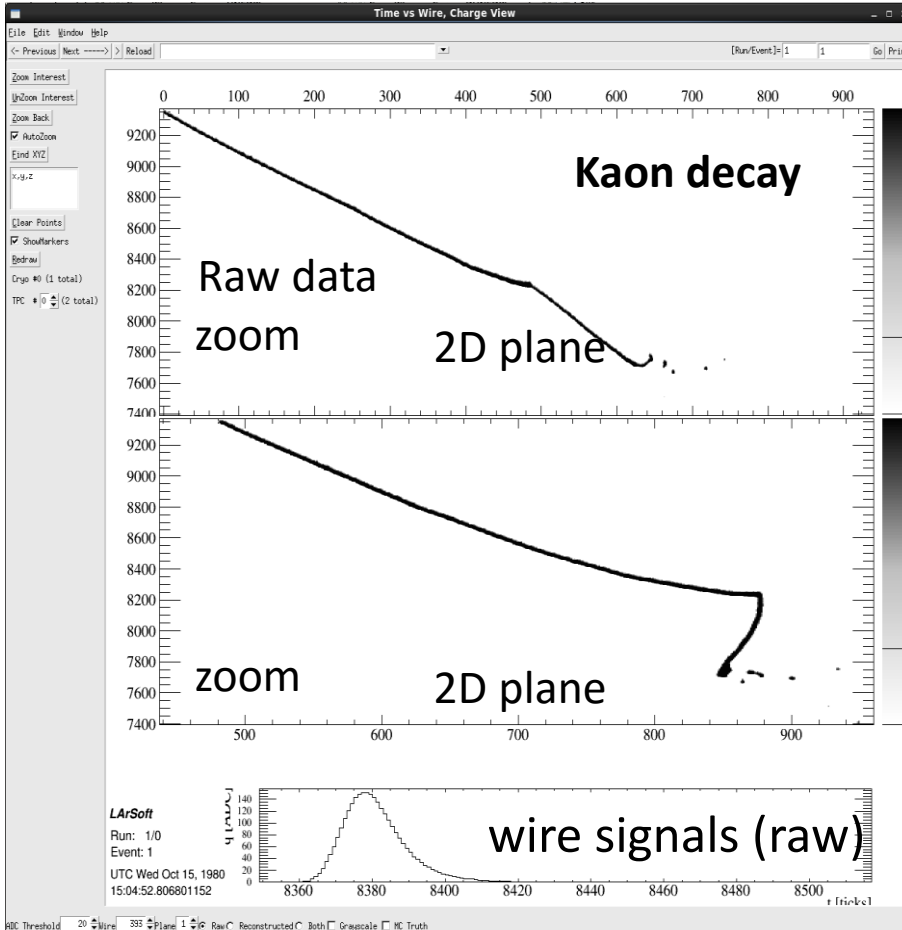


3D reconstruction in protoDUNE SP
geometry



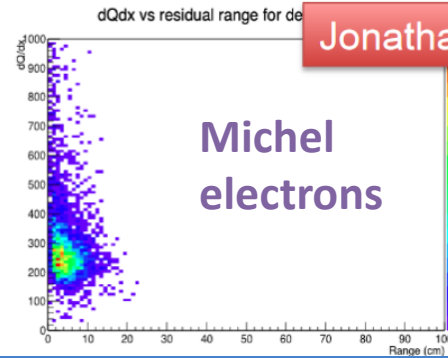
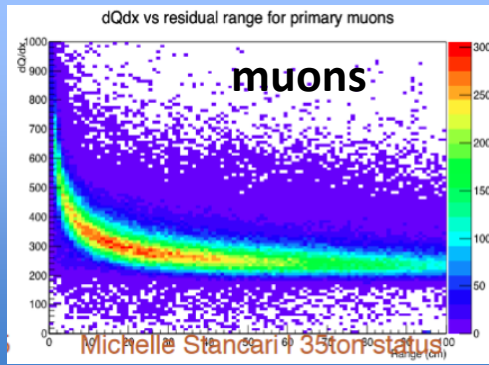
Reconstruction in dual phase detector

reco: [rns, caldata, fasthit, gaushit, cchit, linecluster, pmtrack]



Event display for dual phase: [evd_dunefddp.fcl](#)

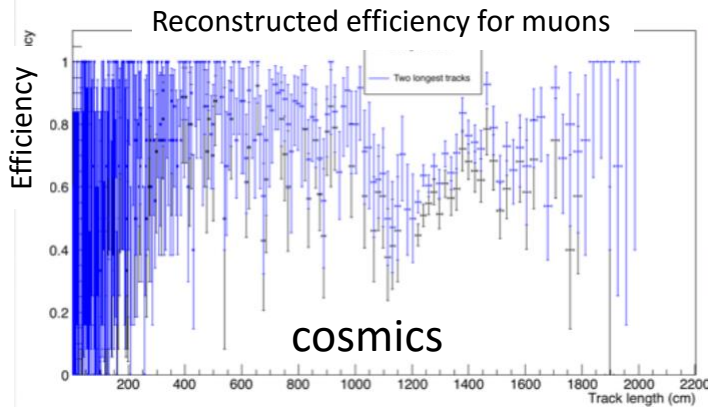
PMA is used in many physic analysis



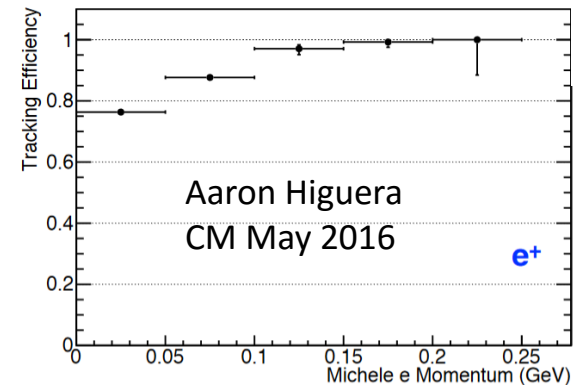
Jonathan Insler, LSU

35t

Taken from Michelle Stancari presentation on Collaboration meeting (september 2015) FNAL
Status of the 35t Prototype

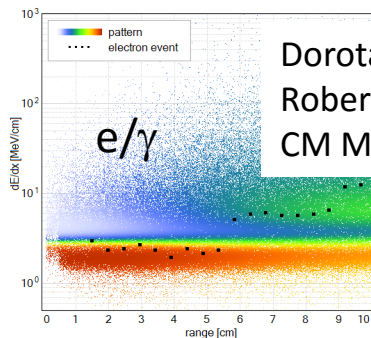


Matt Robinson,
Vitaly Kudryavtsev
Karl Warburton,
CM May 2016

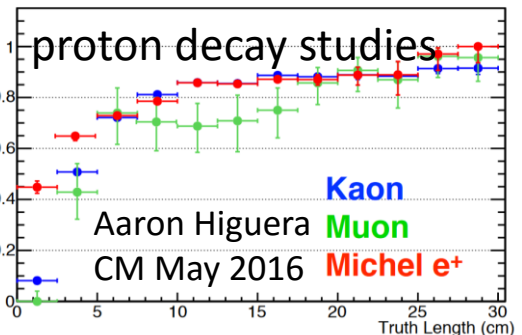
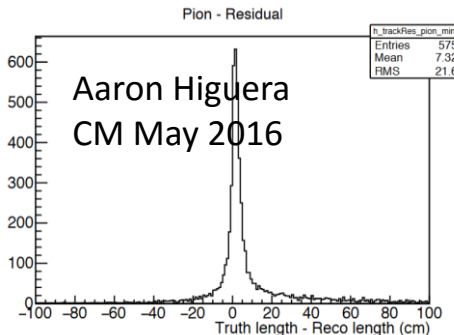


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Thank you!