

# Tianlai data Analysis and Simulations



**R. Ansari**

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*September 2016 - Tianlai Workshop @FermiLab*

- ❖ Overview of Data flow and data processing
- ❖ Map making for wide field transit interferometers
  - ❖ Application to PAON-4 & Tianlai
- ❖ Calibration, application to PAON-4 data
- ❖ Technical considerations , Simulations

# Tianlai data processing overview

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## Level 0 (L0)

*Visibility data, computed on-site ,  
using dedicated hardware (correlator), or  
by software  
ancillary / housekeeping data*

## Level 1 (L1)

Raw visibility data  
[  $V_{ij}(\nu)$  ]

(L0 output)



- First stage RFI cleaning,
- data quality monitoring
- data compression, mainly through time averaging
- transfer to TAC

Organized, Compressed,  
Time sliced visibility data

(L1 output)

### L1 output data :

- ❖ T-16DA : ~35-70 GB / day , ~24-288 files / day , ~100 TB / year
- ❖ T-3Cyl: ~1200-2500 GB / day , ~240-2880 files / day , ~3500 TB / year

Level 2 (L2)

Raw visibility data  
[  $V_{ij}(\nu)$  ]

(L1 output)

(A) RFI cleaning, time  
dependent gain/noise  
monitoring ...

Cleaned / compressed  
visibility data [  $V_{ij}(\nu)$  ]

Cleaned / compressed  
visibility data [  $V_{ij}(\nu)$  ]

(L2-A output)

(B) Calibration on point  
sources

Calibration data (gain, phase)  
Beam,  $T_{sys}$   
Cleaned / calibrated [  $V_{ij}(\nu)$  ]

Calibration data (gain, phase)  
Beam,  $T_{sys}$   
Cleaned / calibrated [  $V_{ij}(\nu)$  ]  
Array configuration

(L2-B output)

(C) Map making

3D sky maps  $I(\alpha, \delta, \nu)$   
Synthetized beams  
noise maps ...

(L2 output)

Level 3 (L3)

(D) Component separation  
Foreground/signal maps  
and power spectrum ...

# L1,L2 processings

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- \* (A) : Cleaning raw visibility data (RFI removal, time dependent gain / Tsys monitoring, data compression (rebinning in time))
- \* (B) : Relative gain / phase calibration using single bright point sources - should be then extended to the use of multiple point sources. Will also provide single dish+feed beam response and Tsys
- \* (C) : Map making - 3D intensity map reconstruction

# Map making - Power spectrum

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- ❖ Snap shots using  $(u,v)$  plane formalism of linear combination of visibilities (for each frequency)
- ❖ Full map reconstruction in spherical geometry [ J. Zhang, S. Zuo]
- ❖ Foreground subtraction in angular / frequency domain
- ❖ and power spectrum computation from the cleaned maps
- ❖ Or, direct power spectrum computation from visibilities ?

**Spherical Harmonics Map  
reconstruction applied to Tianlai &  
PAON-4 - Jiao Zhang (NAOC & LAL)**

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# J. ZHANG ET AL. 21CM MAP MAKING PAPERS

**Map Making Paper I - J. Zhang et al (2016), MNRAS, (accepted June 2016, submitted end of March 2016)**

MNRAS **000**, 1–17 (2016)

Preprint 30 May 2016

Compiled using MNRAS L<sup>A</sup>T<sub>E</sub>X style file v3.0

## **Sky reconstruction from transit visibilities: PAON-4 and Tianlai Dish Array**

Jiao Zhang<sup>1,2,3</sup>, Reza Ansari<sup>2</sup> **★**, Xuelei Chen<sup>1,3,4</sup>, Jean-Eric Campagne<sup>2</sup>,  
Christophe Magneville<sup>5</sup>, and Fengquan Wu<sup>1</sup>

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<sup>2</sup>*Université Paris-Sud, LAL, UMR 8607, F-91898 Orsay Cedex, France & CNRS/IN2P3, F-91405 Orsay, France*

<sup>3</sup>*University of Chinese Academy of Sciences, Beijing 100049, China*

<sup>4</sup>*Center for High Energy Physics, Peking University, Beijing 100871, China*

<sup>5</sup>*CEA, DSM/IRFU, Centre d'Etudes de Saclay, F-91191 Gif-sur-Yvette, France*

**Map Making Paper II - J. Zhang et al (2016), accepted for publication in  
RAA (May 2016, submitted in April)**

**Research in Astronomy and Astrophysics** manuscript no.  
(L<sup>A</sup>T<sub>E</sub>X: jmapcylinder.tex; printed on May 31, 2016; 18:04)

## **Sky reconstruction for the Tianlai cylinder array**

Jiao Zhang<sup>1,2,3</sup>, Shifan Zuo<sup>1,3</sup>, Reza Ansari<sup>2</sup>, Xuelei Chen<sup>1,3,4</sup>, Yichao Li<sup>1,3</sup>, Fengquan  
Wu<sup>1,3</sup>, Jean-Eric Campagne<sup>2</sup>, Christophe Magneville<sup>5</sup>

# Transit interferometer : map making

Full East-West scan means we could perform Fourier transform on the set of  $\mathcal{V}_{ij}(\alpha_p)$  to obtain the  $\tilde{\mathcal{V}}_{ij}(m)$  for each m-mode

$$\mathcal{V}_{ij}(\alpha_p) \quad (0 \leq \alpha_p < 2\pi) \longrightarrow \tilde{\mathcal{V}}_{ij}(m) \quad \text{for all } m \text{ modes}$$

$$\tilde{\mathcal{V}}_{ij}(m) = \sum_{\ell=|m|}^{+\ell_{\max}} (-1)^m \mathcal{I}(\ell, m) \mathcal{L}_{ij}(\ell, -m)$$

$$\tilde{\mathcal{V}}_{ij}^*(-m) = \sum_{\ell=|m|}^{+\ell_{\max}} \mathcal{I}(\ell, m) \mathcal{L}_{ij}^*(\ell, m)$$

See also R. Shaw et al.  
Apj 2014, 2015

The full problem of all  $\tilde{\mathcal{V}}_{ij}(m)$  could be separated into a set of independent problems for each m.

**Block diagonal matrix**

$$\begin{pmatrix} \tilde{\mathcal{V}}_{ij}^{\delta_p}(m_0) \\ \tilde{\mathcal{V}}_{ij}^{\delta_p}(m_1) \\ \dots \\ \tilde{\mathcal{V}}_{ij}^{\delta_p}(m_{\max}) \end{pmatrix} = \begin{pmatrix} \mathcal{L}_{ij}^{\delta_p}(m_0, l) & & & \\ & \mathcal{L}_{ij}^{\delta_p}(m_1, l) & & 0 \\ & 0 & \dots & \\ & & & \mathcal{L}_{ij}^{\delta_p}(m_{\max}, l) \end{pmatrix} \times \begin{pmatrix} \mathcal{I}(m_0, l) \\ \mathcal{I}(m_1, l) \\ \dots \\ \mathcal{I}(m_{\max}, l) \end{pmatrix} + \text{noise}$$

$\mathbf{L}_{m_i}$  → Inversion →  $\mathbf{H}_m$

Some basic analysis in  $(\ell, m)$  space

# Instrument response and transfer function

- Reconstruction matrix  $\mathbf{R}_m \equiv (\mathbf{H}_m \mathbf{L}_m)$  : the estimated sky spherical harmonics coefficient  $\widehat{\mathcal{I}}(\ell, m)$  are related to the true sky ones  $\mathcal{I}(\ell, m)$

- Core response matrix  $\mathbf{R}$  :

$$\mathbf{R}(\ell, m) = \mathbf{R}_m(\ell, \ell)$$

- Transfer function

$$T(\ell) = \langle |\mathbf{R}(\ell, m)| \rangle_m \quad \text{or} \quad T(\ell) = \frac{C^{\text{rec}}(\ell)}{C^{\text{in}}(\ell)}$$

Some basic analysis in  $(\ell, m)$  space

## Error variance matrix and noise power spectrum

- Pure noise visibilities  $\rightarrow$  noise covariance matrix
- $\mathbf{H}_m$  matrix and noise covariance matrix  $\rightarrow$  for each  $m$  mode, the covariance matrix  $\mathbf{Cov}_m(\ell_1, \ell_2)$  of the estimator  $\widehat{\mathcal{I}}(\ell, m)$

$$\mathbf{N}_m = [\tilde{\mathcal{V}}_{ij}]_m \cdot [\tilde{\mathcal{V}}_{ij}]_m^\dagger$$

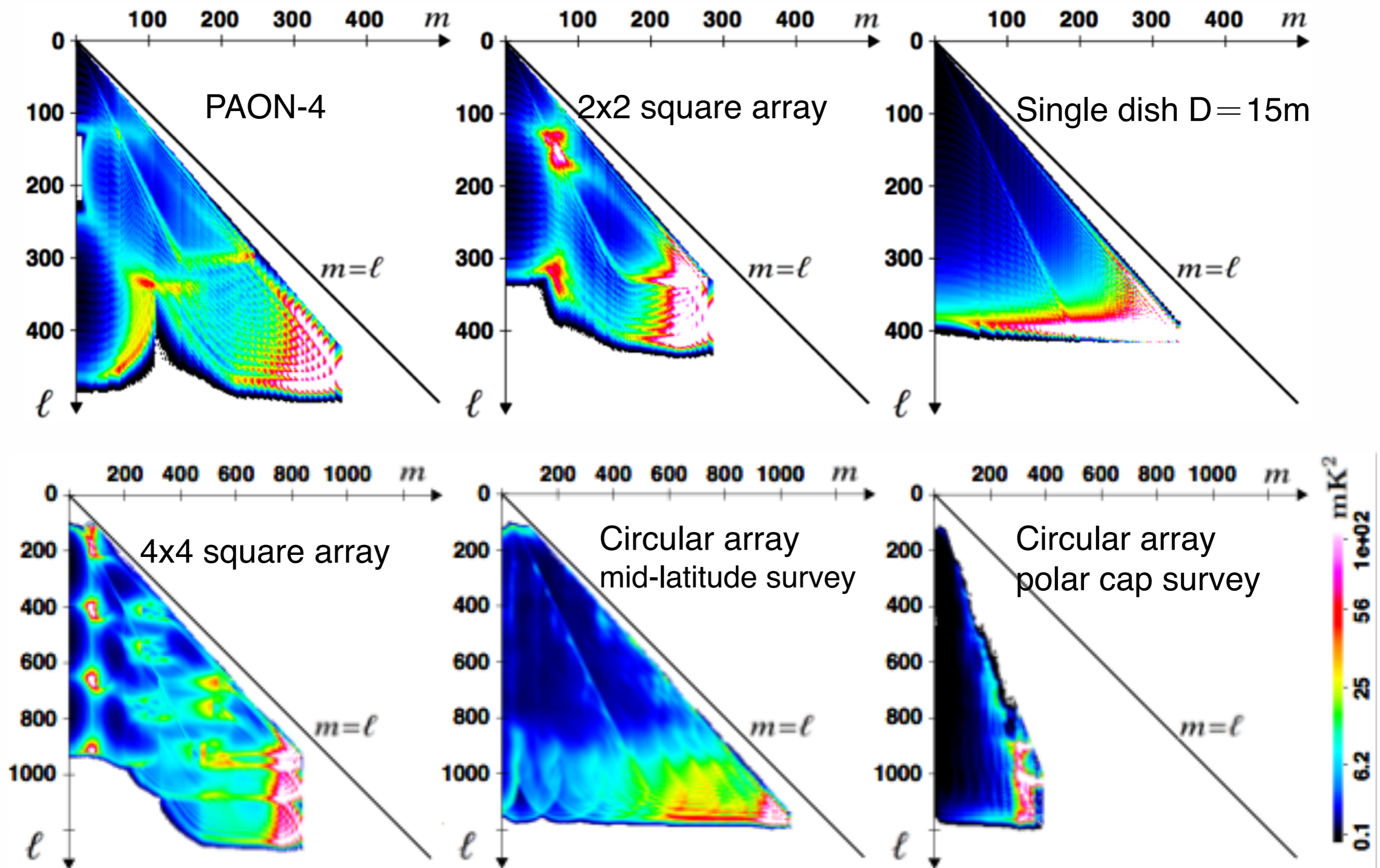
$$\mathbf{Cov}_m(\ell_1, \ell_2) = \langle [\widehat{\mathcal{I}}(\ell)]_m \cdot [\widehat{\mathcal{I}}(\ell)]_m^\dagger \rangle = \mathbf{H}_m \mathbf{N}_m \mathbf{H}_m^\dagger$$

- Error variance matrix and noise power spectrum

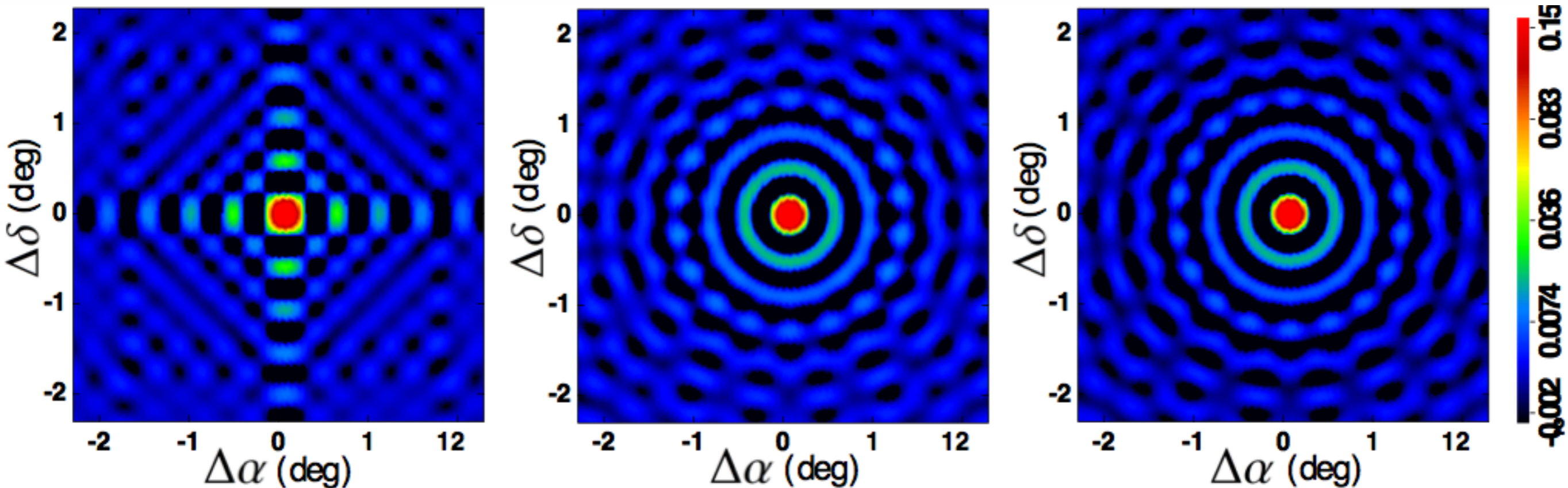
$$\sigma_{\mathcal{I}}^2(\ell, m) = \mathbf{Cov}_m(\ell, \ell)$$

$$C^{\text{noise}}(\ell) = \langle \sigma_{\mathcal{I}}^2(\ell, m) \rangle_m$$

# Error variance matrix $\sigma_I^2(\ell, m)$



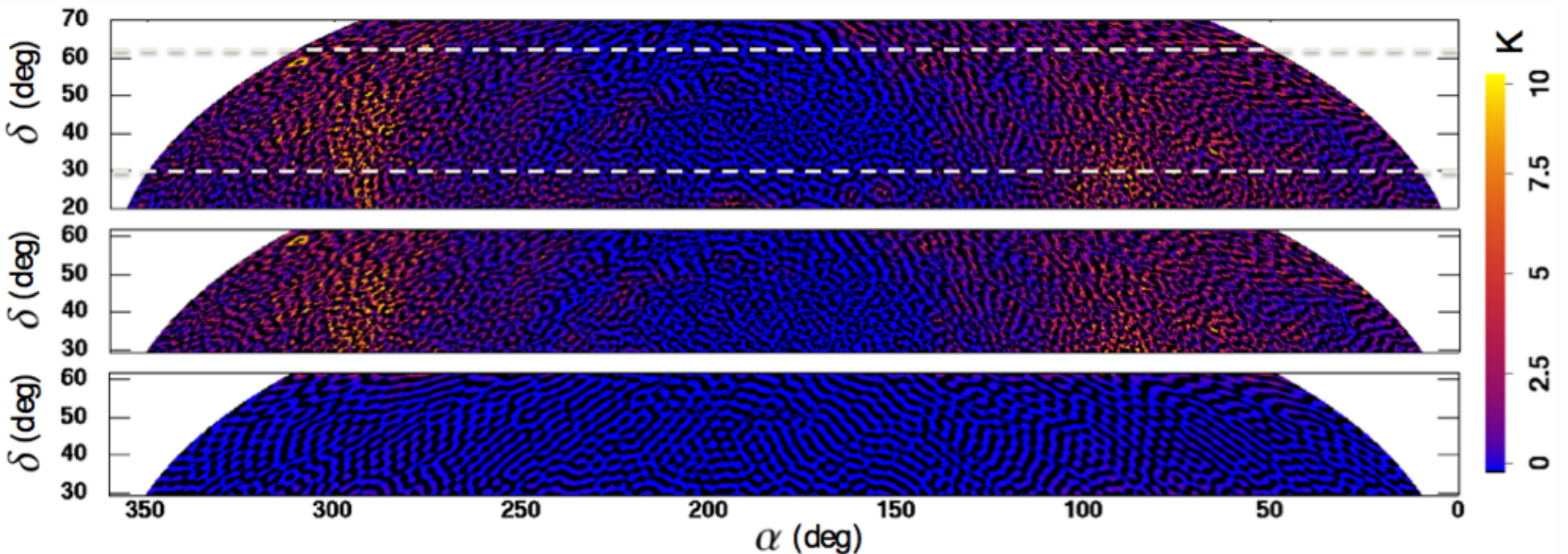
## Reconstructed beam or PSF for Tianlai dish array



4x4 square array

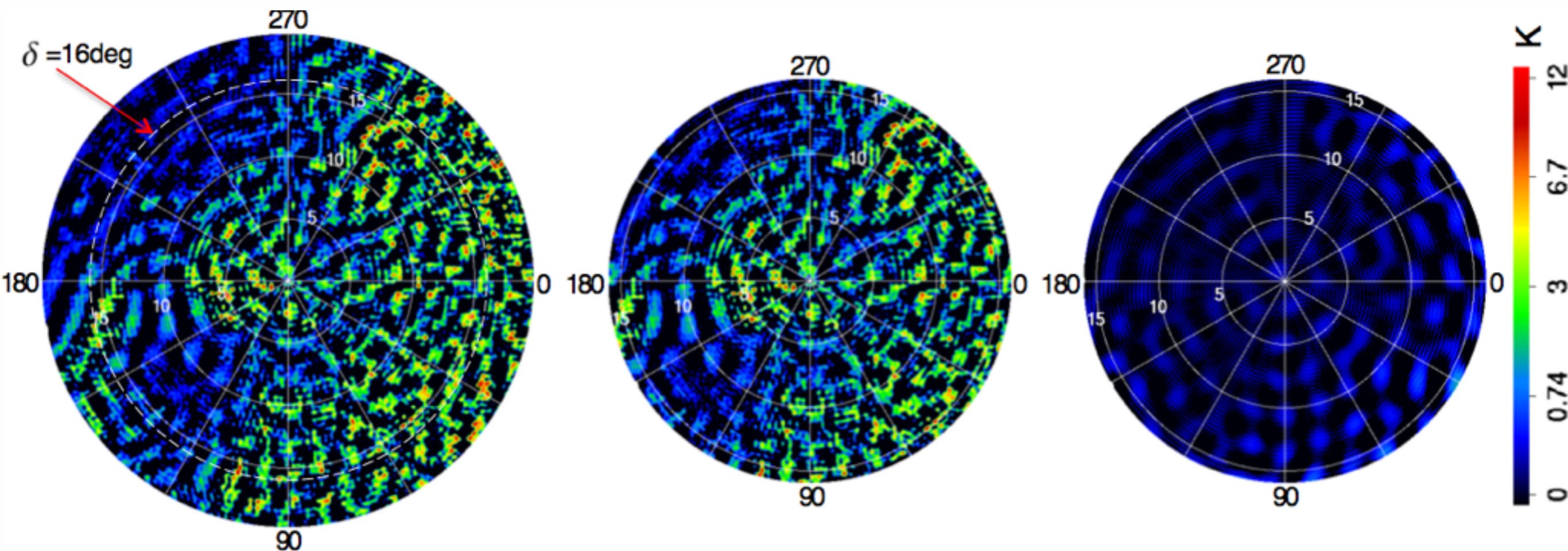
Circular array  
With autocorrelationCircular array  
Without autocorrelation

# Reconstructed sky map for mid-latitude



- Top: the input map in the latitude range  $20^\circ < \delta < 70^\circ$  obtained by applying high pass filter to the LAB map
- Center: the reconstructed map in the range  $30^\circ < \delta < 60^\circ$  with filters
- Bottom: the difference between (1) and (2) in the range  $30^\circ < \delta < 60^\circ$

# Reconstructed sky map for polar region

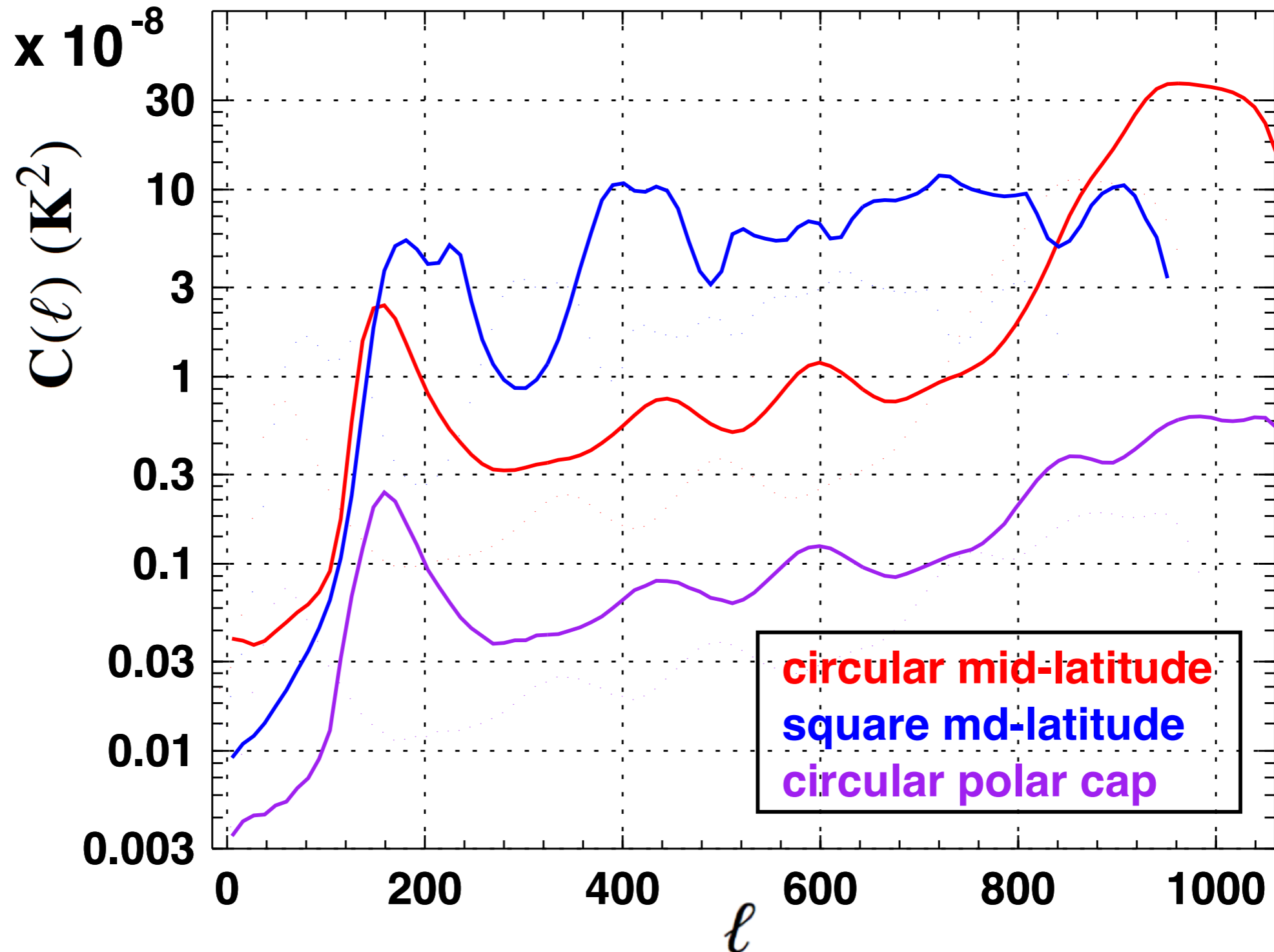


- Left : the input polar cap map after a high pass filtering with a radius of  $20^\circ$
- Center : the reconstructed map for polar cap survey with a radius of  $16^\circ$
- Right : The difference between left and center with a radius of  $16^\circ$

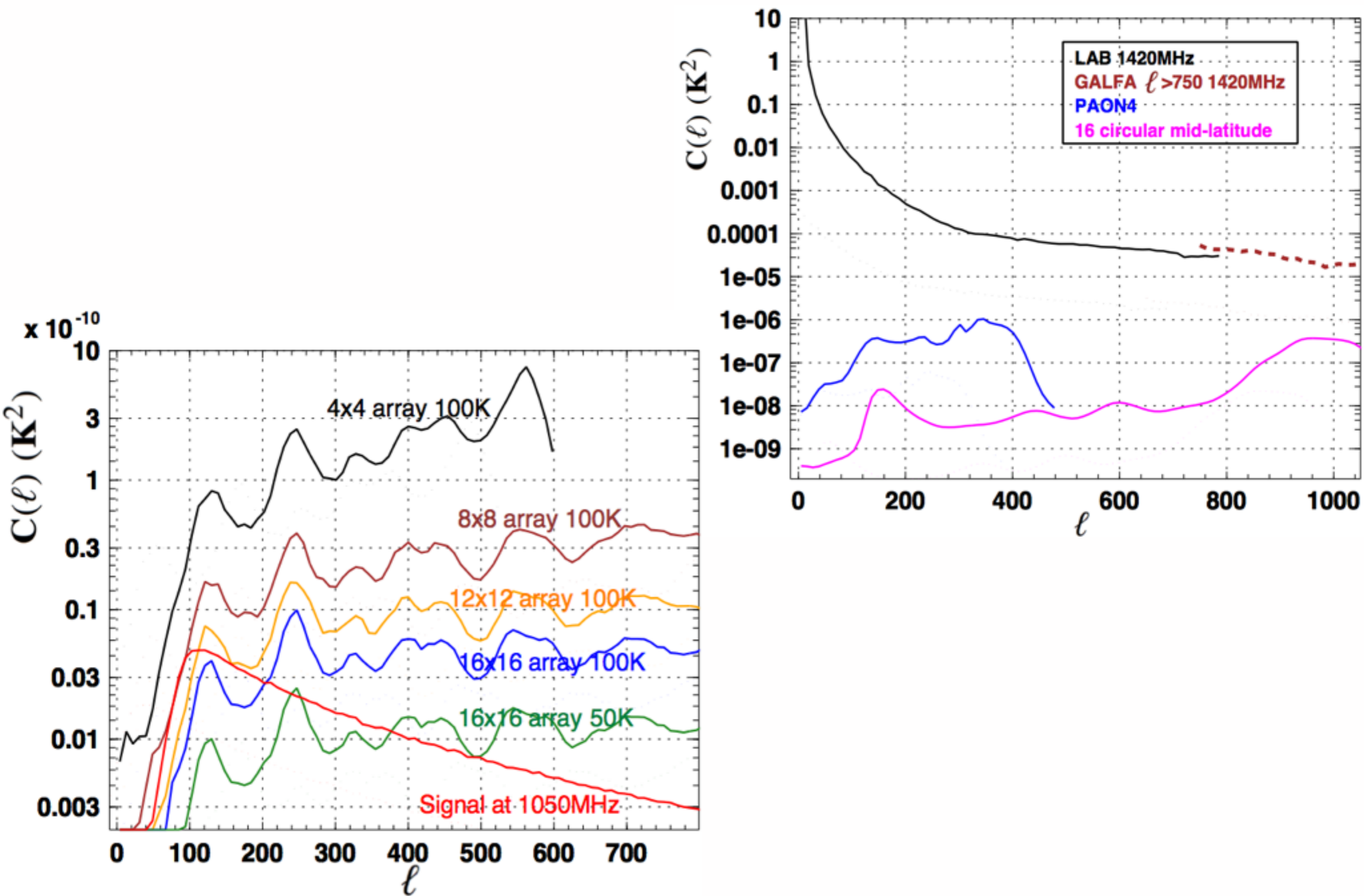


Application to PAON-4 and Tianlai dish array

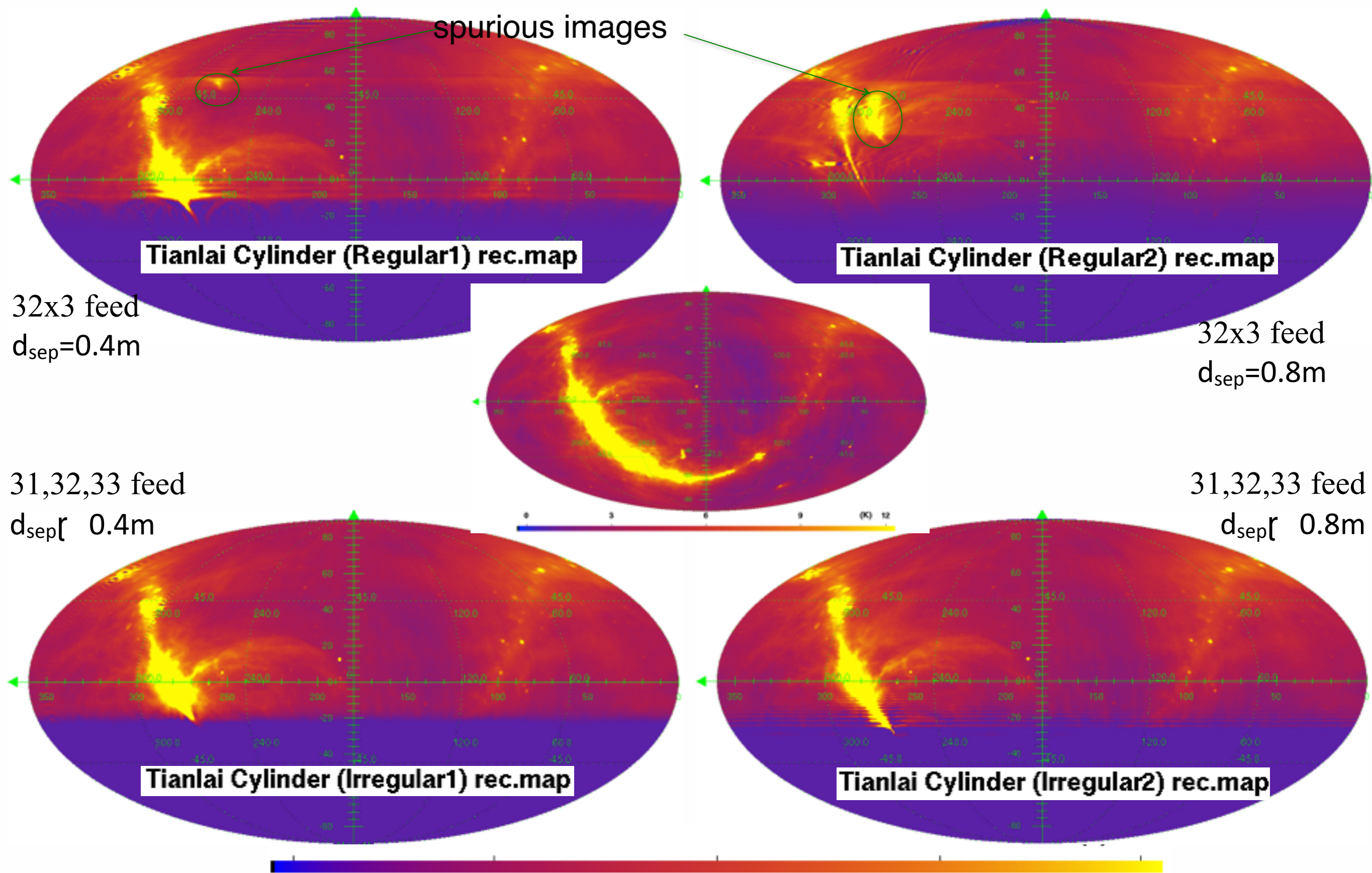
# noise power spectrum



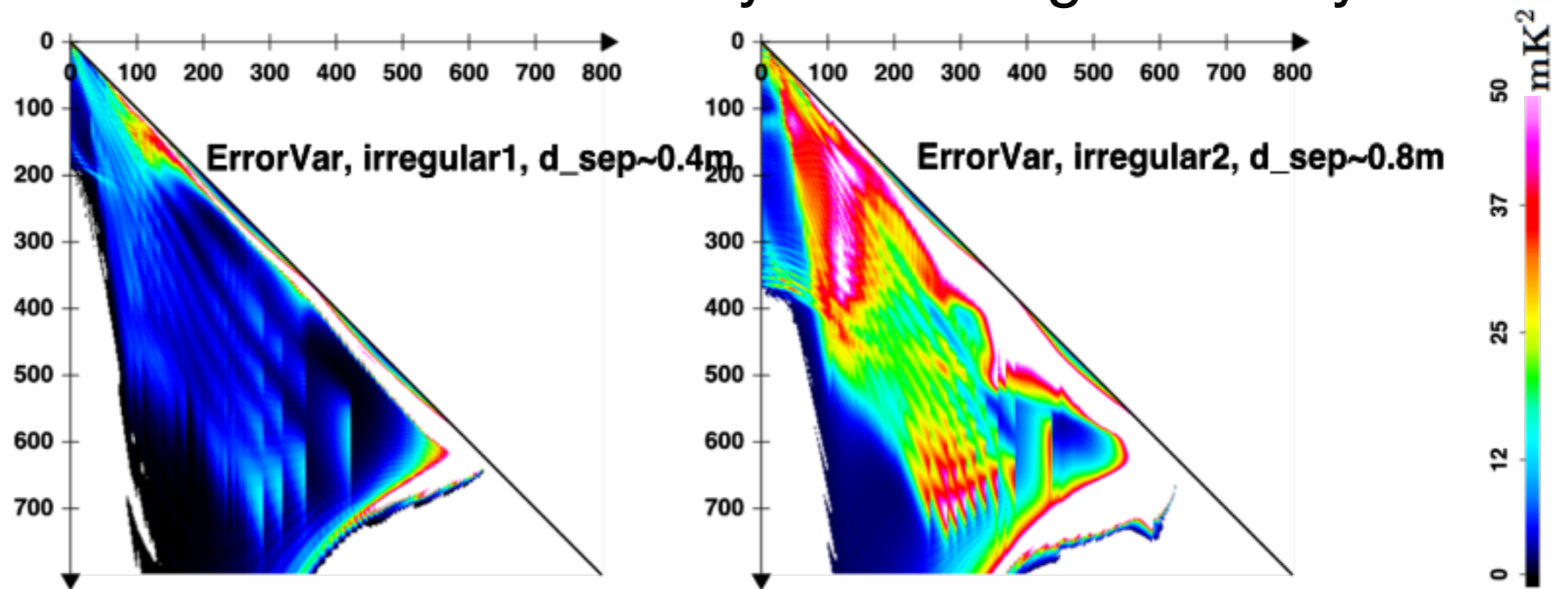
# Dish array sensitivity



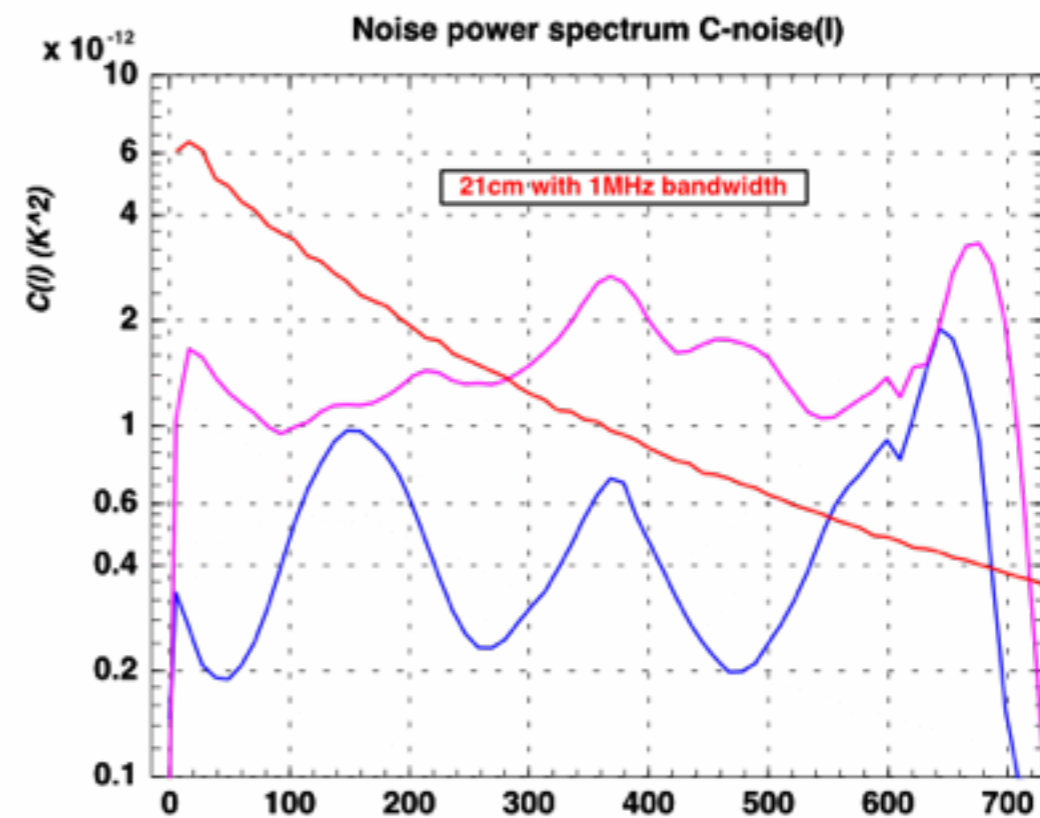
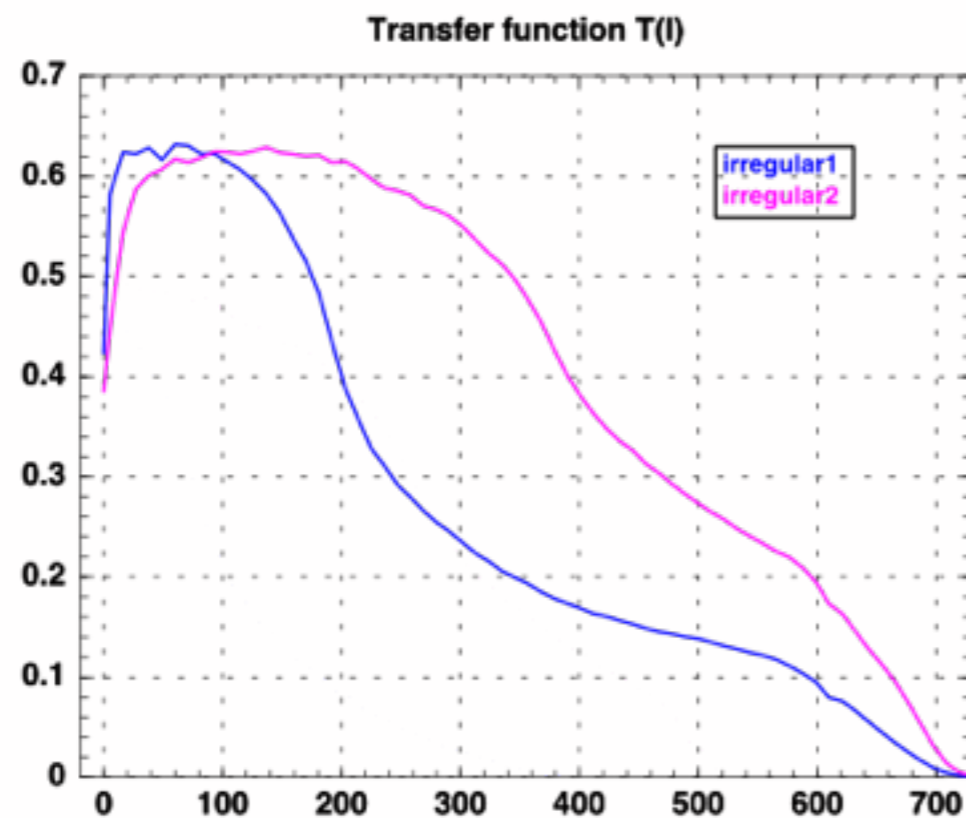
# Reconstructed sky map for cylinder array



## Error variance matrix for cylinder irregular array



## Transfer function and noise power spectrum



# Calibration (PAON-4 & Tianlai)

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Analysis mostly done  
by Q. Huang, but also T.  
Etourneau ...

PAON-4 (PI: J.E. Campagne, J.M. Martin) - Technical projet leaders:  
F. Rigaud (Mechanics) - D. Charlet (Electronic, Computing, Commissioning)



PAON-4 test interferometer

**PAON-2** →  
September 2012



# Extraction of array characteristics from cross-correlations

( *Qizhi Huang* )

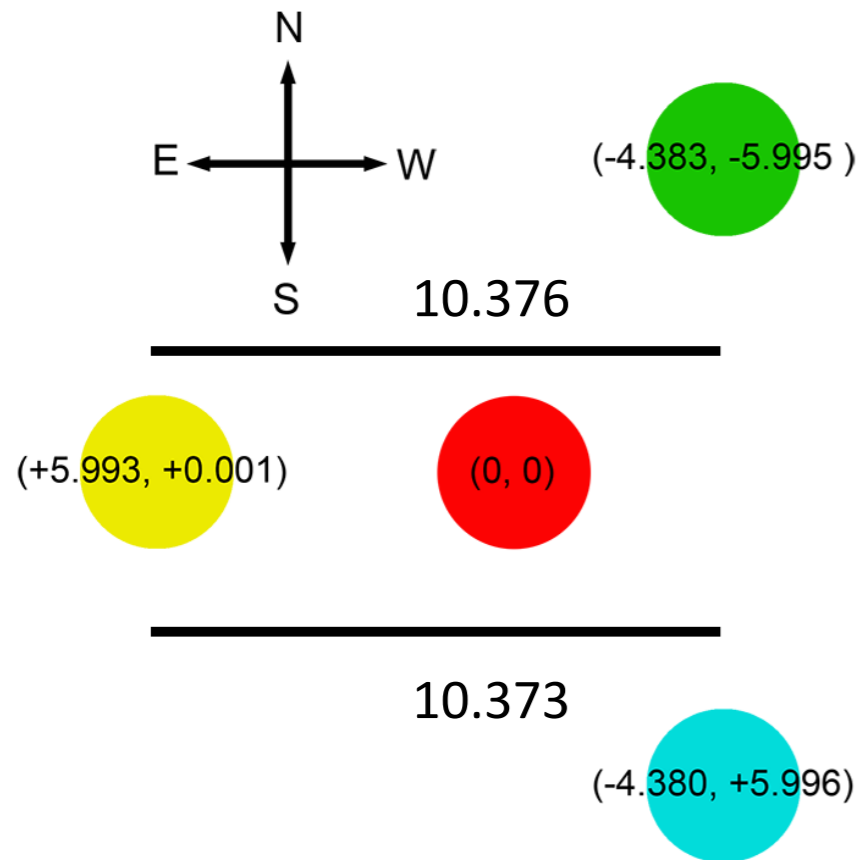
- Fit fringes (real & imaginary part) on all antenna pairs (6 cross-correlations for each polarization)
- Extract array geometry (baselines), effective diameters for each antenna, the phase difference term due to electronics, cables ...  $\Delta\Phi_{ij}$
- Extract also the antenna alignment (antenna axis direction)

*From Q. Huang presentation*

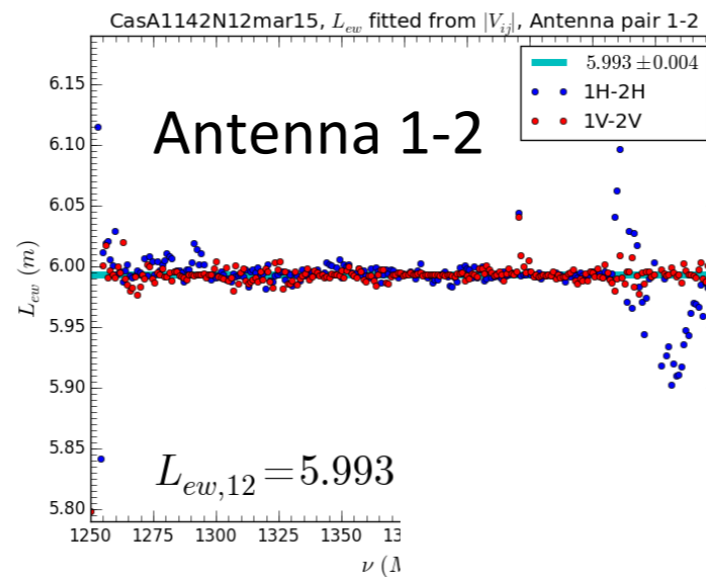
<https://indico.lal.in2p3.fr/event/2912/contribution/5/material/slides/0.pdf>

# Array geometry (baselines) determined from fringes in full agreement with on ground measurements of the antenna position (I)

## Antenna geometry



## East-West baseline of Antenna pair 1-2



## Data I use here

- 7 scans around Cygnus A
- Date of these scans: CygA665S1dec15, CygA365S7dec15, CygA465S5dec15, CygA565S2dec15, CygA765S30nov15, CygA865S3dec15, CygA965S6dec15
- Center declinations of each scans:  
37.7, 38.7, 39.7, 40.7, 41.7, 42.7, 43.7 degree
- Declination range of the whole data: 7 degree
- Right Ascension range: 360 degree

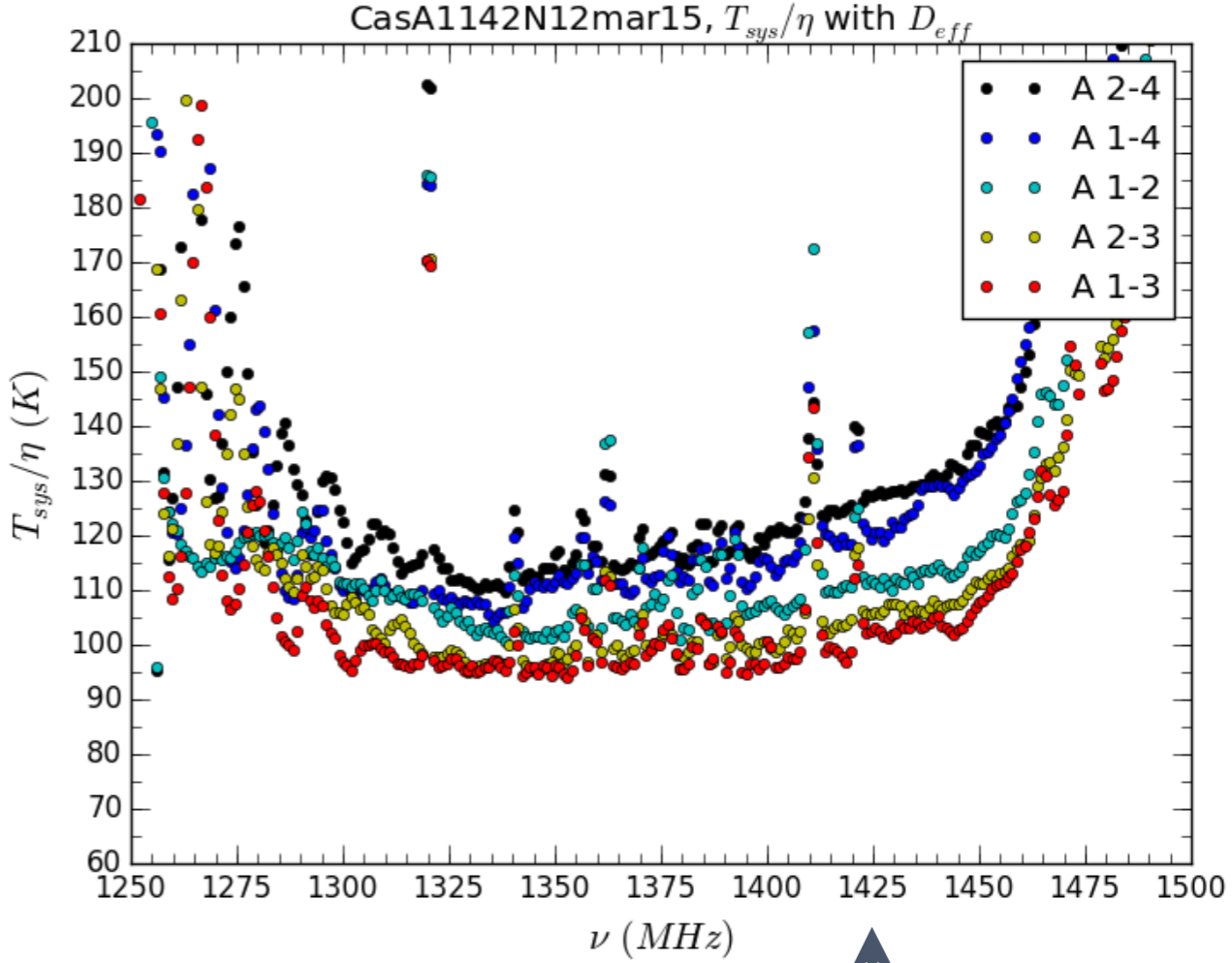
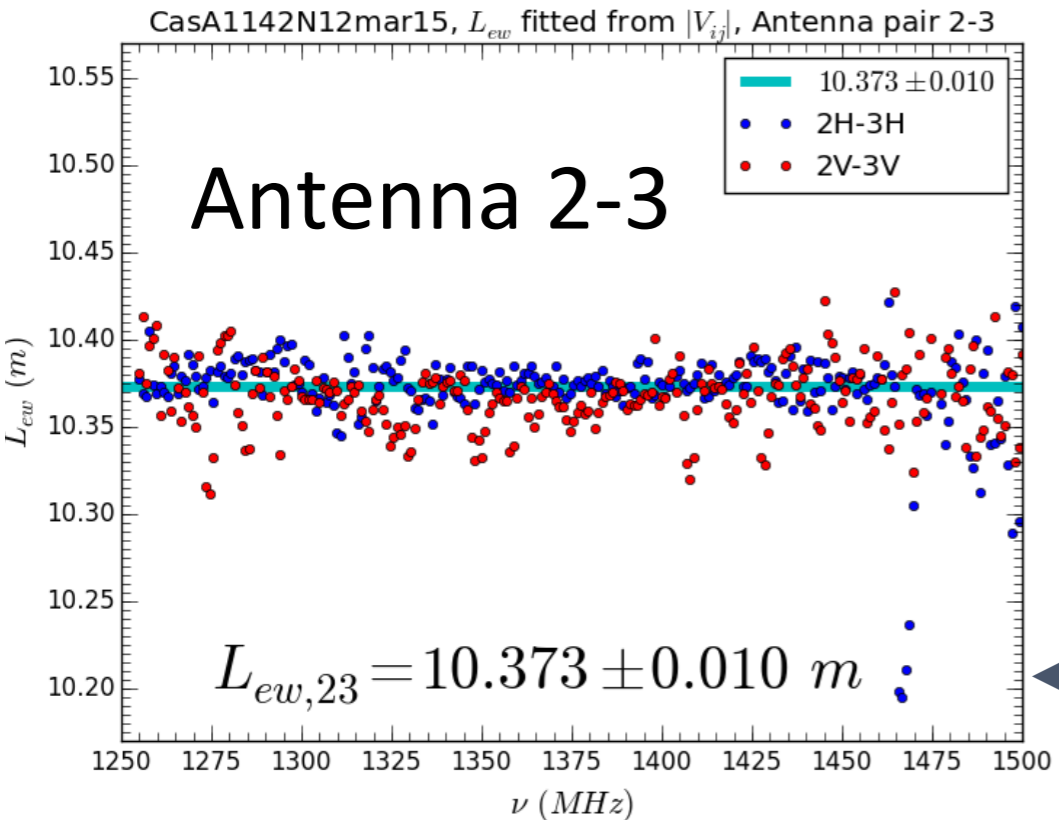
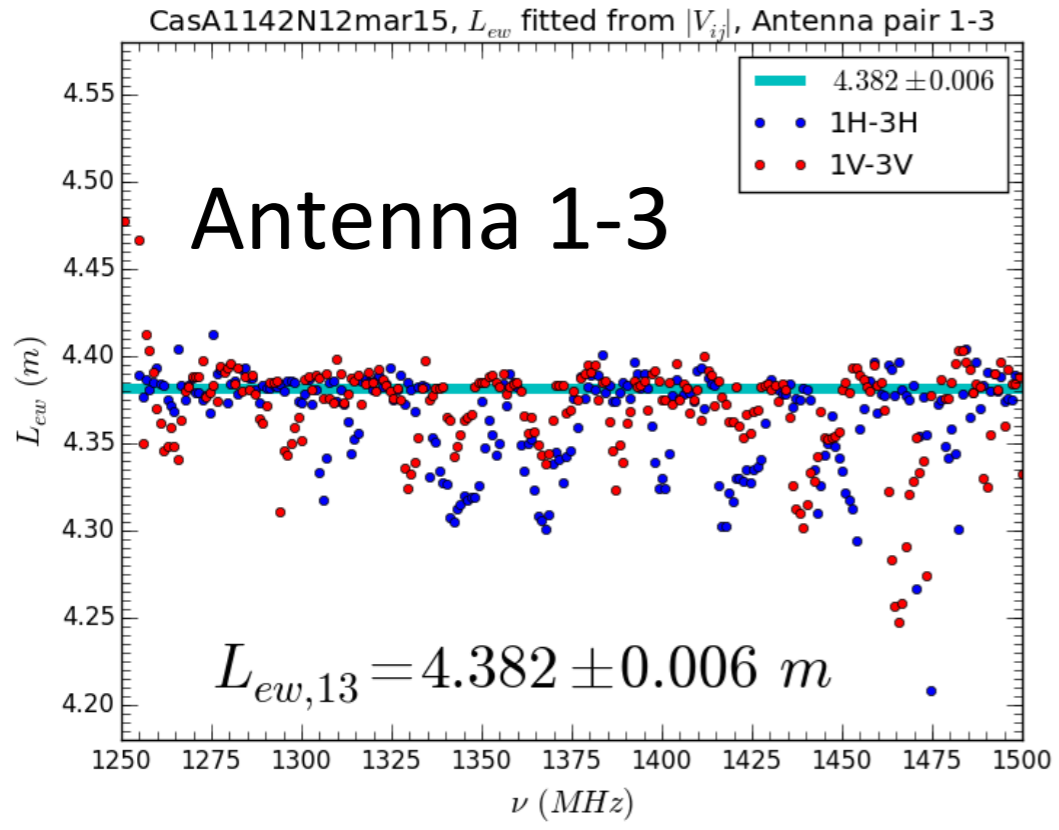
From Q. Huang presentation

<https://indico.lal.in2p3.fr/event/2912/contribution/5/mater>



# PAON-4 array geometry, Tsys from calibration

Analysis by Q. Huang  
NAOC & LAL



Lew (v) ←

↑ Tsys (v)

From Q. Huang presentation

# Gain & phase calibration, Map making from PAON-4 data

( *Qizhi Huang* )

## Data I use here

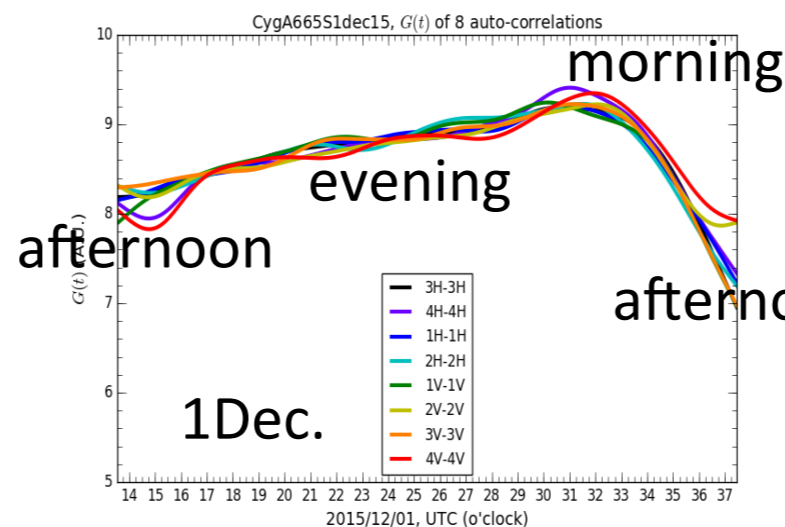
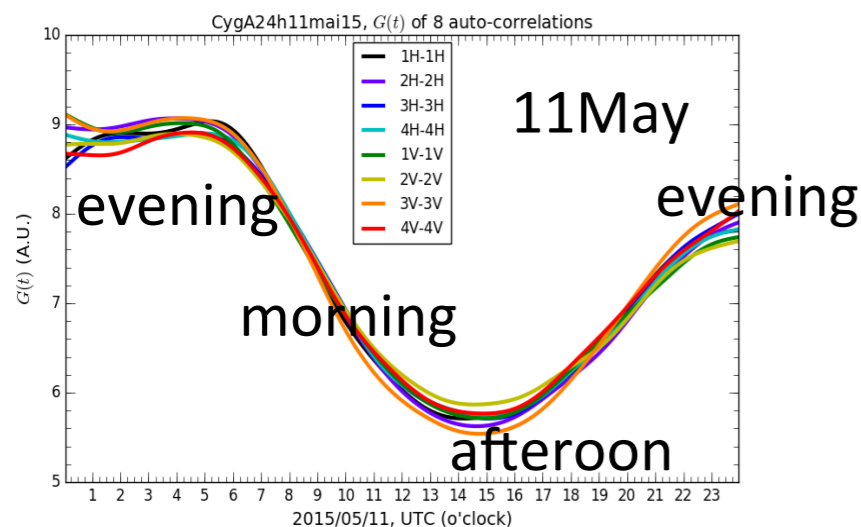
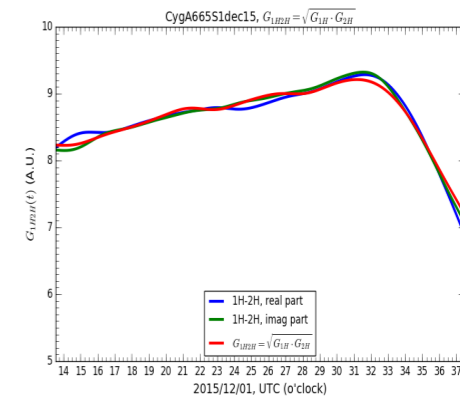
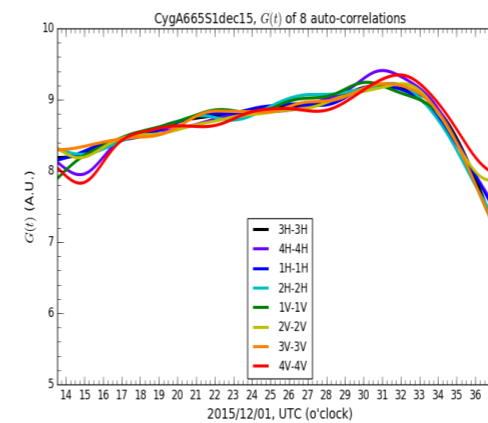
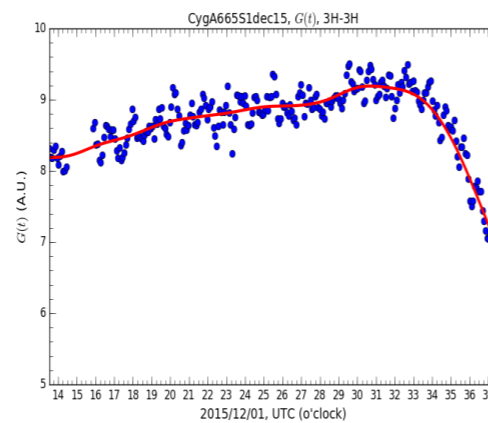
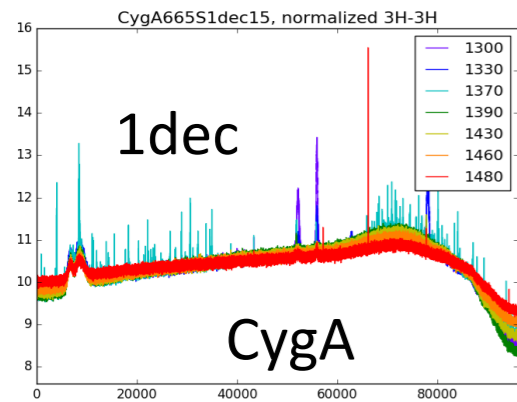
- 7 scans around Cygnus A
- Date of these scans: CygA665S1dec15, CygA365S7dec15, CygA465S5dec15, CygA565S2dec15, CygA765S30nov15, CygA865S3dec15, CygA965S6dec15
- Center declinations of each scans:  
37.7, 38.7, 39.7, 40.7, 41.7, 42.7, 43.7 degree
- Declination range of the whole data: 7 degree
- Right Ascension range: 360 degree

**November-December 2015**

**CygA data**

# Calibrate gain 2: $G(t)$

- Same thing but different data set (different day) comparing with the page above.



11 May is in mid-late spring, the temperature changes a little large from daytime to night. While 1 Dec. is in winter, the temperature changes less, then the gain is smoother than that in May.

We can see that, the gain decreases from morning to afternoon, and increases in the evening. Corresponding to the temperature. In higher temperature, gain is lower.

# Phase calibration

Here I show 2H3H for example

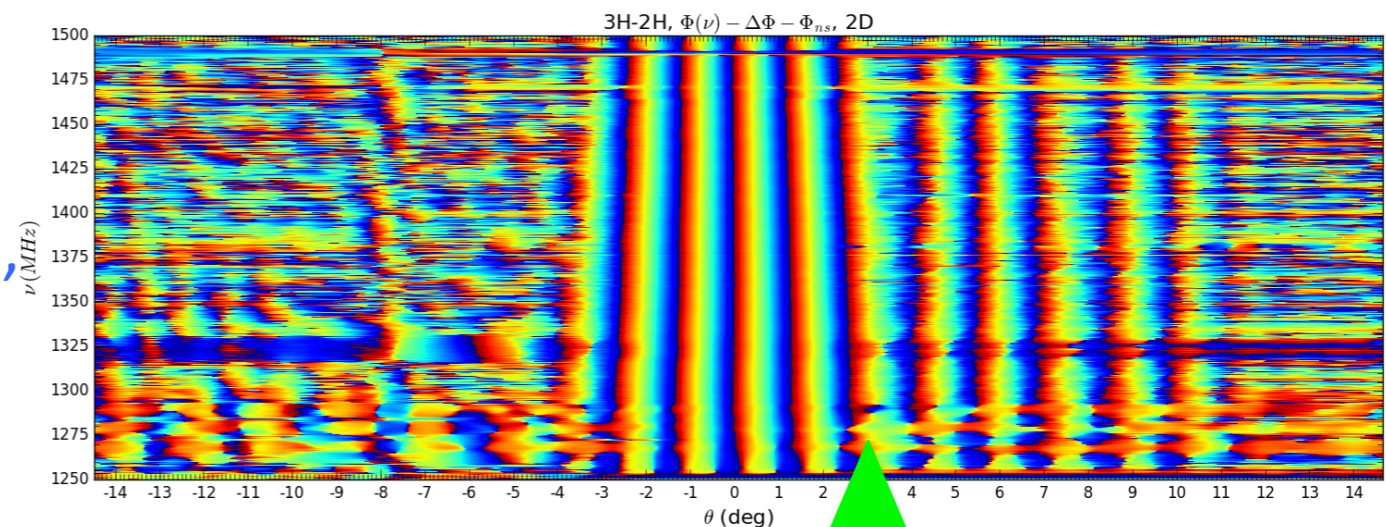
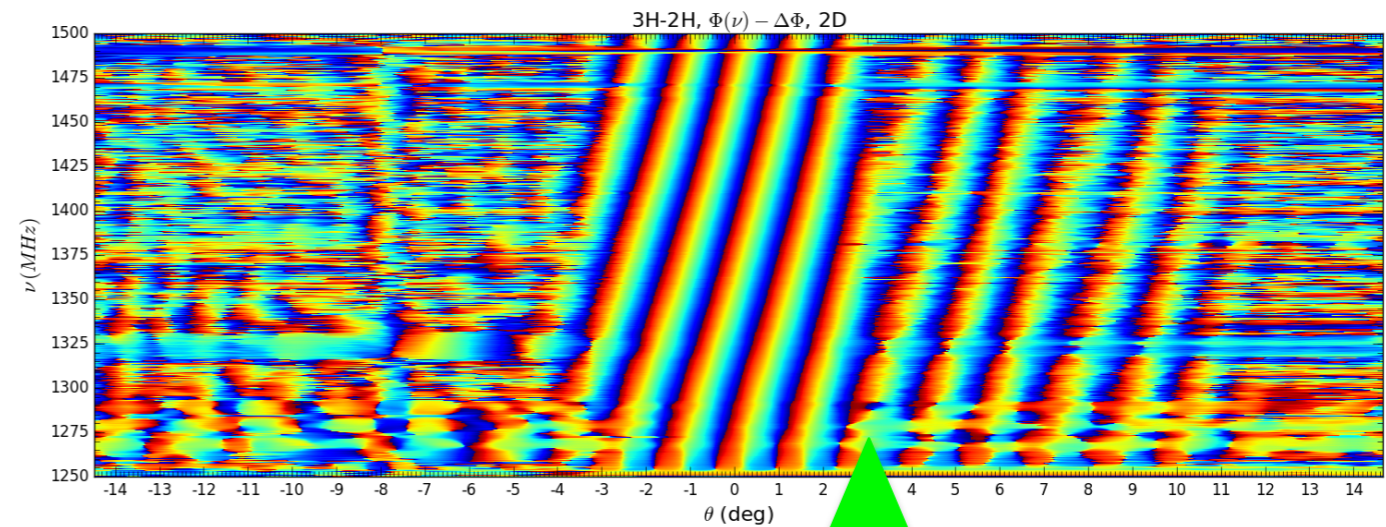
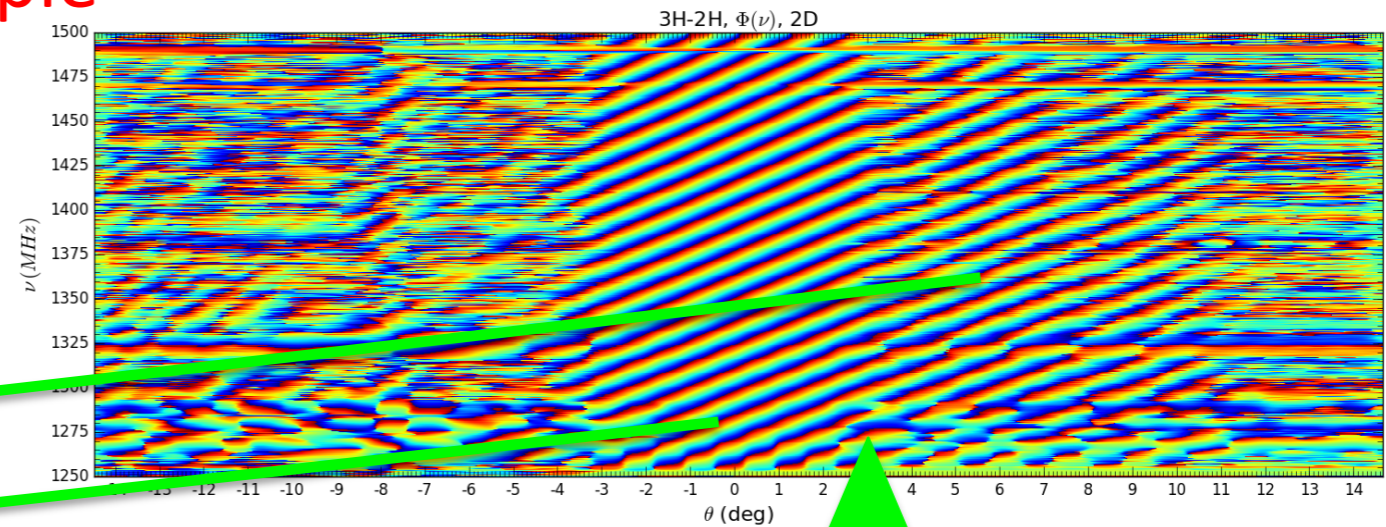
Total phase from  
the observation data

Cygnus X

Cygnus A

After calibrating  
the additional phase

After calibrating  
the additional phase and  
phase from North-South baseline,  
just leave the phase from the  
East-West baseline



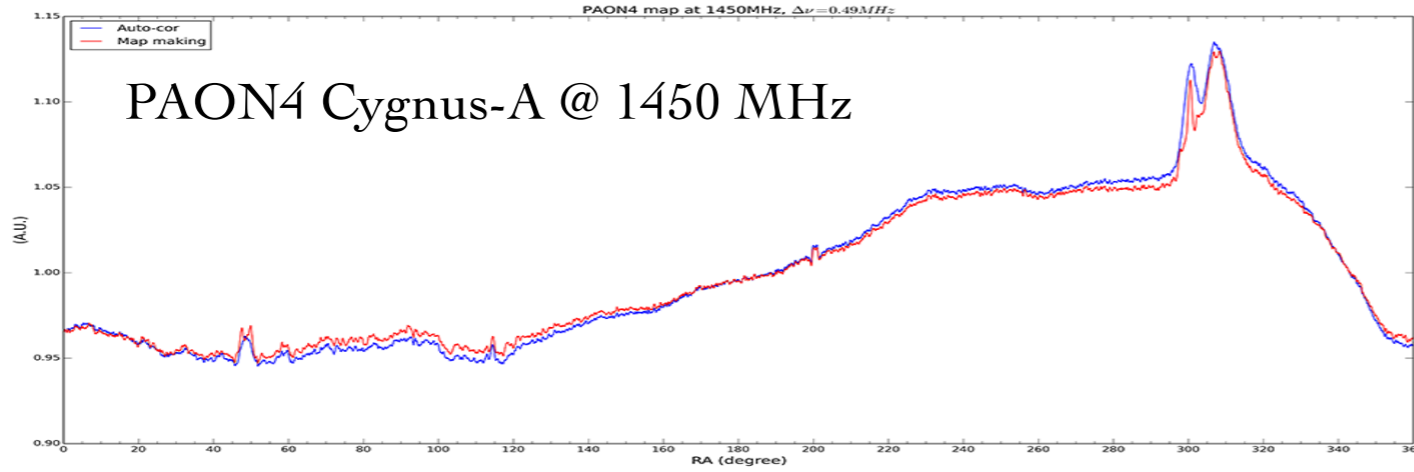
# Map from visibilities (single scan) I

Slide by Qizhi Huang (LAL/NAOC PhD)

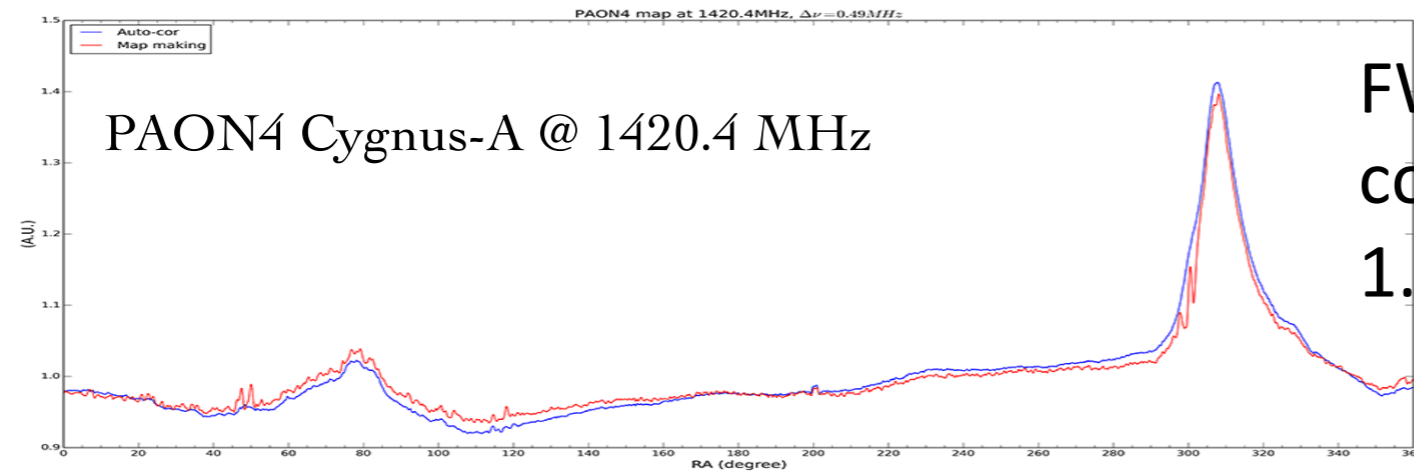
PAON4 CygA

blue : autocorrelation (single dish)

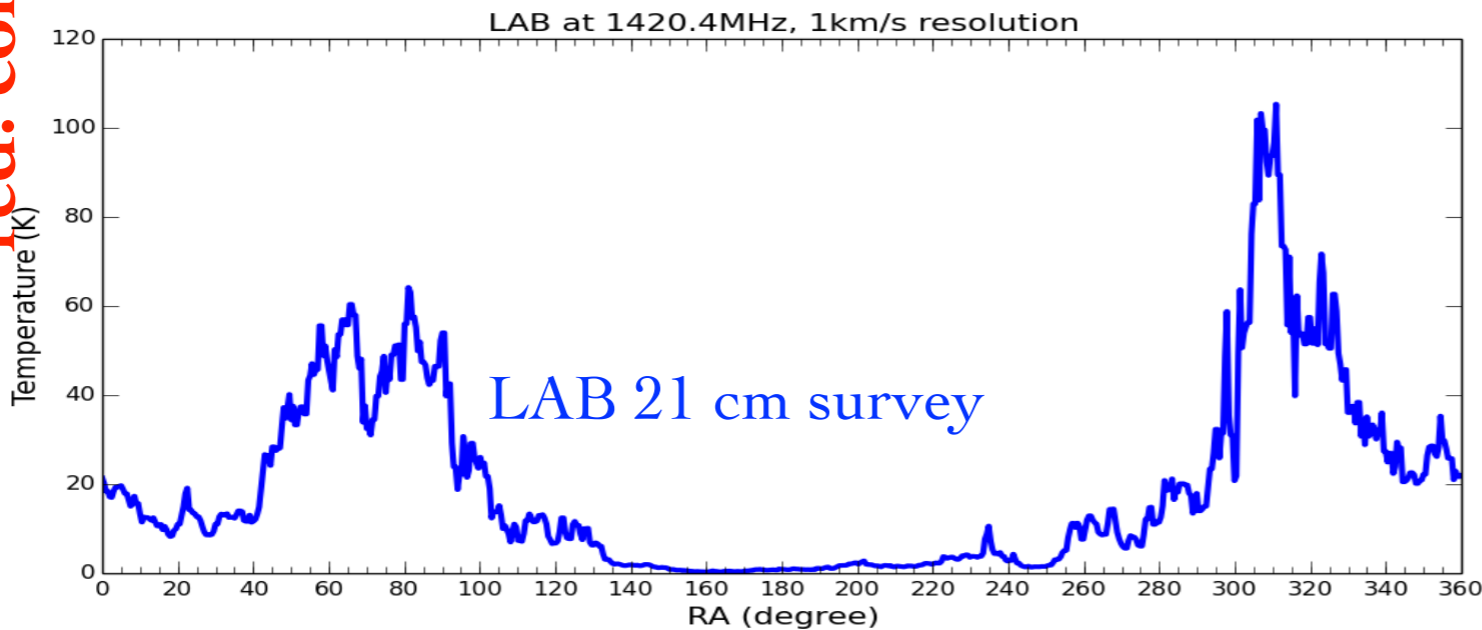
red: combined visibilities (4 dishes)



PAON4 CygA @ 1450 MHz



FWHM~1.6 degree  
compare to  
 $1.22 * 0.2 / 10.7 = 1.3$  degree



PAON4 CygA @ 1420.4 MHz

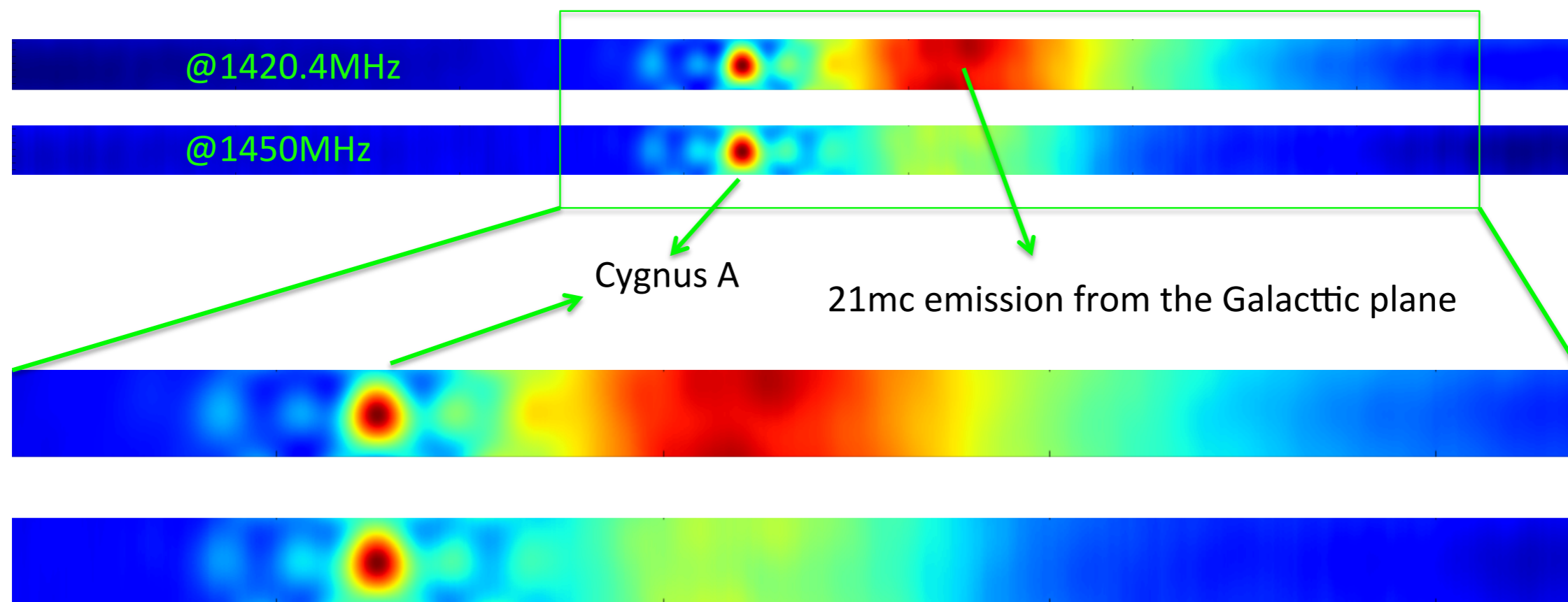
Nov. 2015 - Data from May 2015

# Map from visibilities (single scan) II

Slide by Qizhi Huang (LAL/NAOC PhD)

## Final maps

CygA24h11mai15 is one day 24 hours observation, we just have one transition. However, we can add a special phase to the visibilities to simulate the case that turning the antennas to other declinations and observe.



Nov. 2015 - Data from May 2015

# Map from 7 PAON-4 scans of CygA at 1420 MHz (I)

7 x 360 deg<sup>2</sup> map

Analysis & slide by Q. Huang  
NAOC & LAL

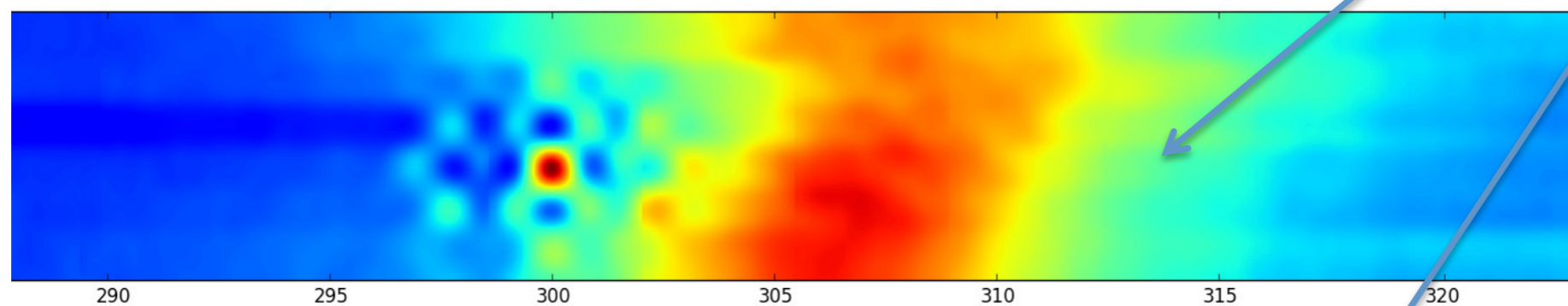
I use 7 scans to make this map.

For each scan, I get 200 mock lines by add a phase  $\exp(i \cdot 2\pi / l \cdot Lns \cdot \sin(\delta))$ ,  
 $\delta = 1$  degree for 200 pixel.

7dx360d, 1420.4MHz (you also find the large image in .jpe)

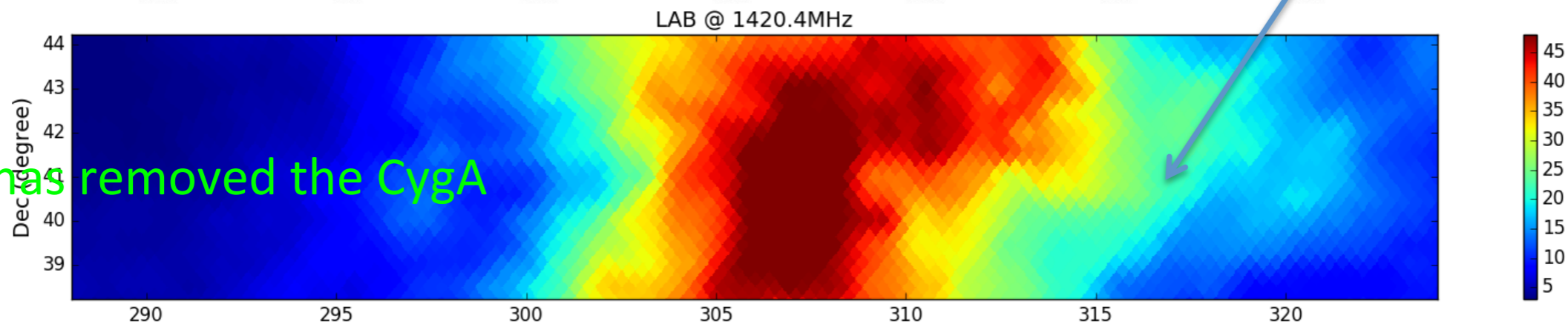


The same sky region of LAB data



1420.4MHz

LAB has removed the CygA



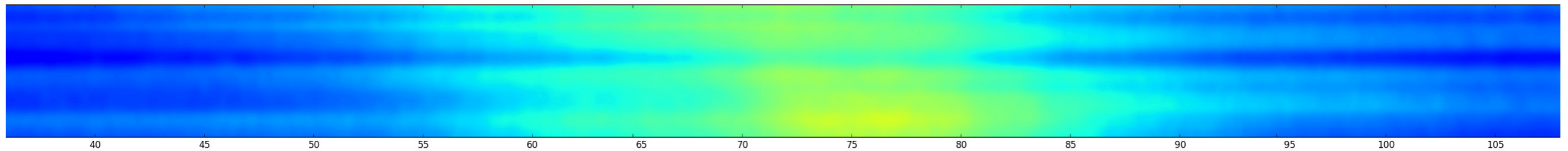
# Map from 7 PAON-4 scans of CygA at 1420 MHz (II)

7 x 40 deg<sup>2</sup> map

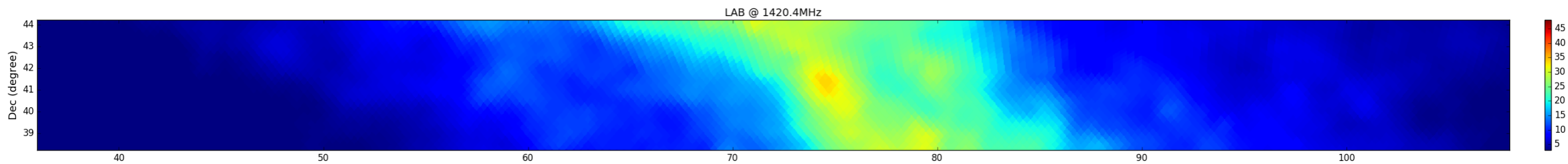
Analysis & slide by Q. Huang

NAOC & LAL

PAON4, galactic anticenter, 1420.4MHz

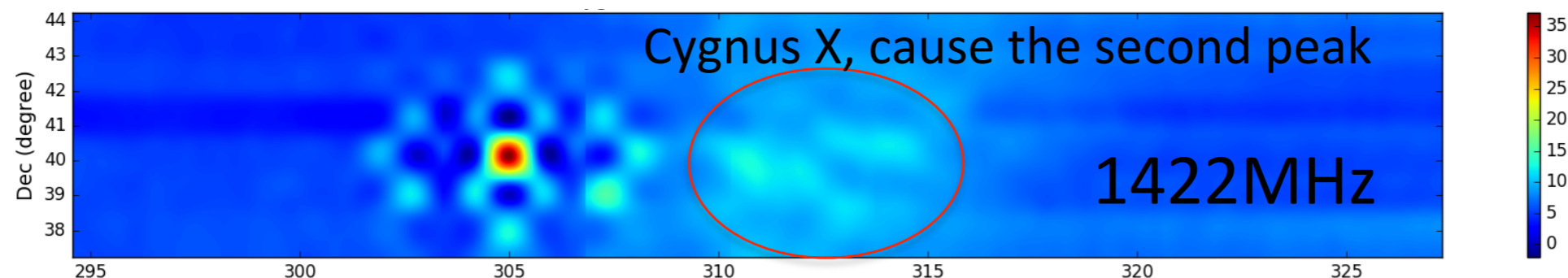


LAB, galactic anticenter, 1420.4MHz



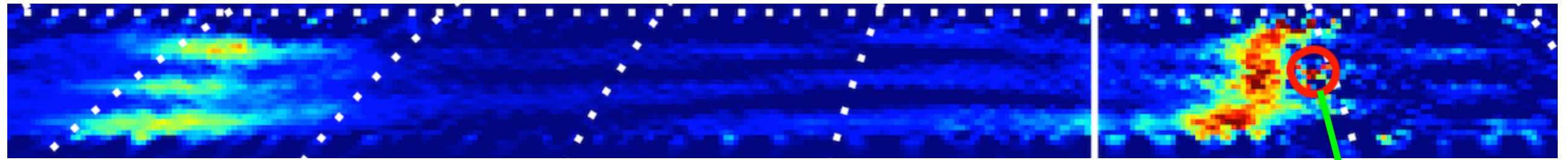
When we observe the CygA, we will usually see two peak, one is the CygA, the other is the so called Cygnus X.

I make the map at 1422MHz where HI emission is weak, we can see the structure of the Cygnus X.





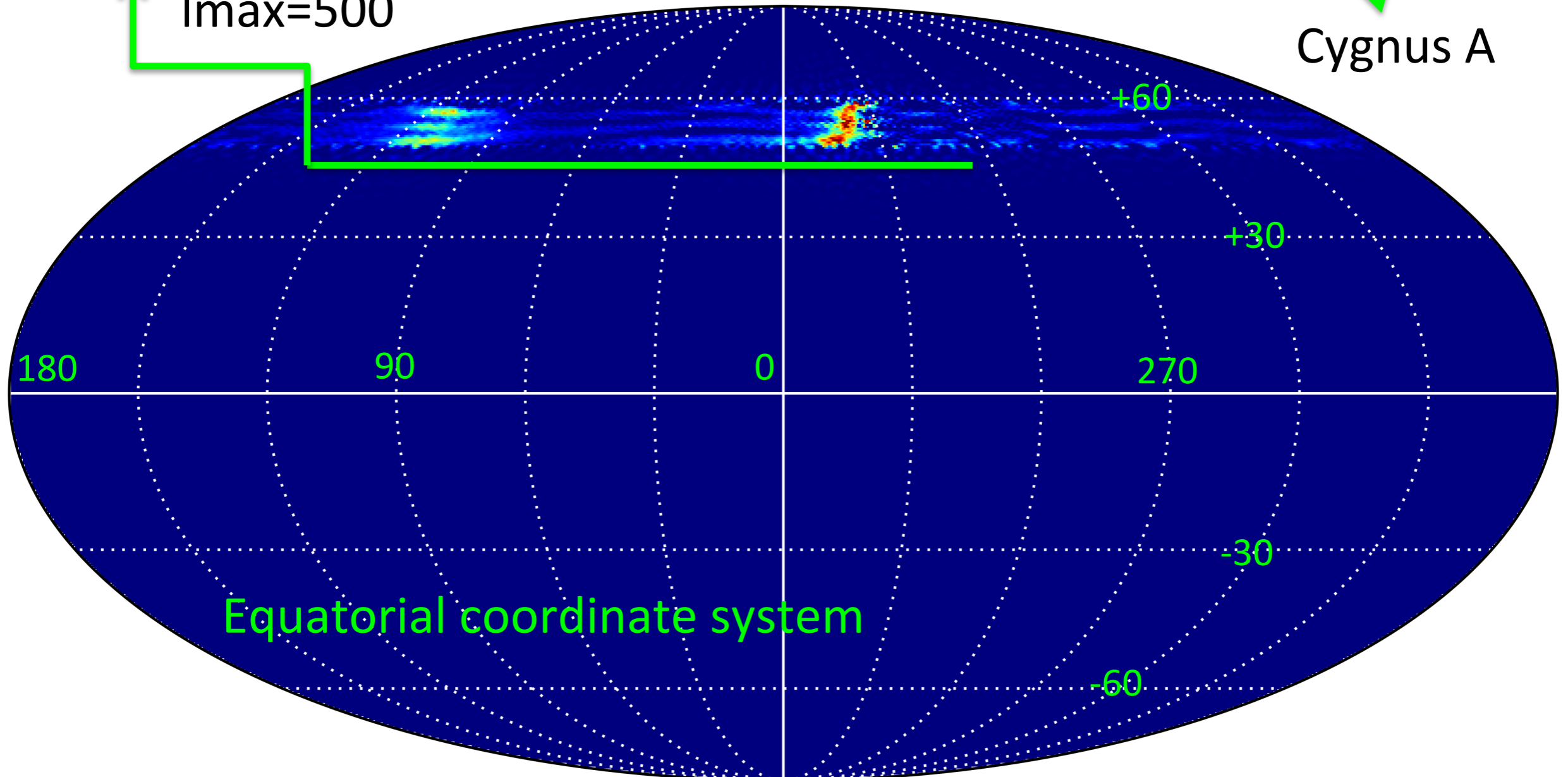
# Map making using Jiao's program (2)



PAON4,  $\nu = 1420.4\text{MHz}$ ,  $\Delta\nu = 0.488\text{MHz}$

$I_{\text{max}}=500$

Cygnus A



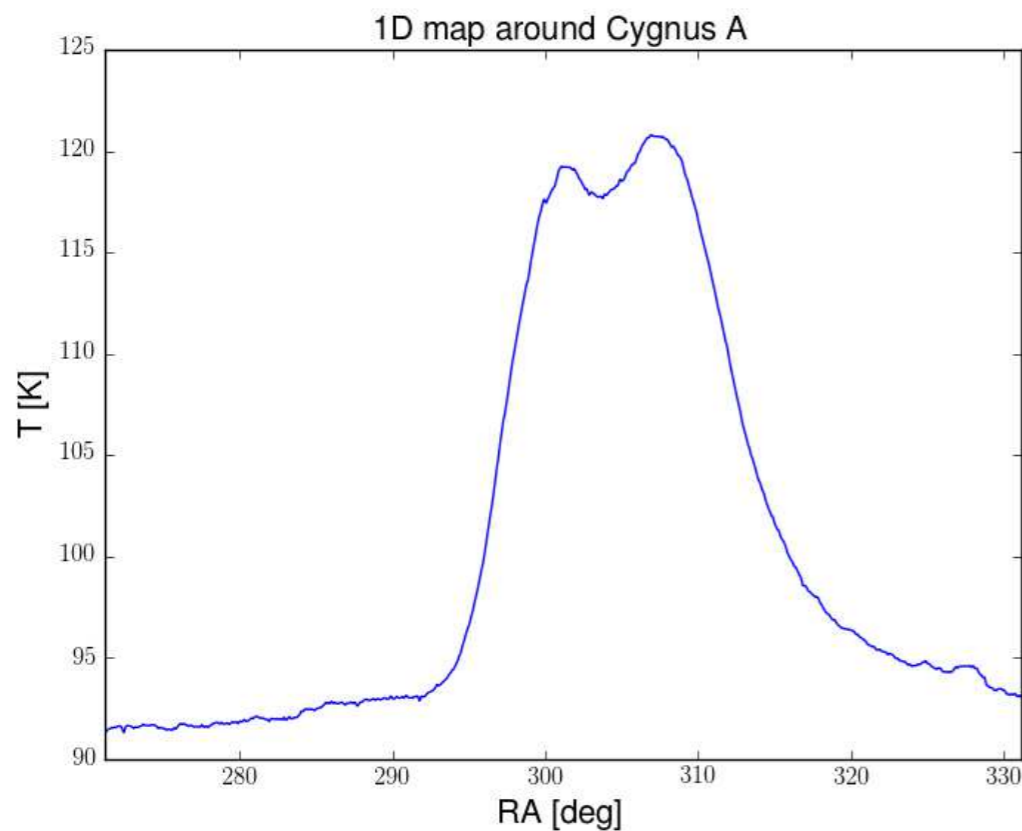
Equatorial coordinate system

Analysis by Q. Huang & J. Zhang (NAOC & LAL)

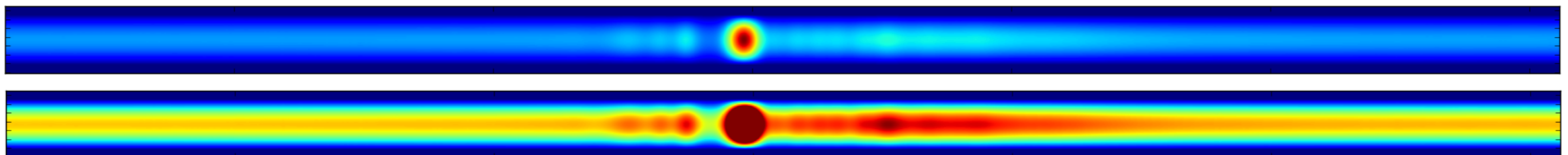
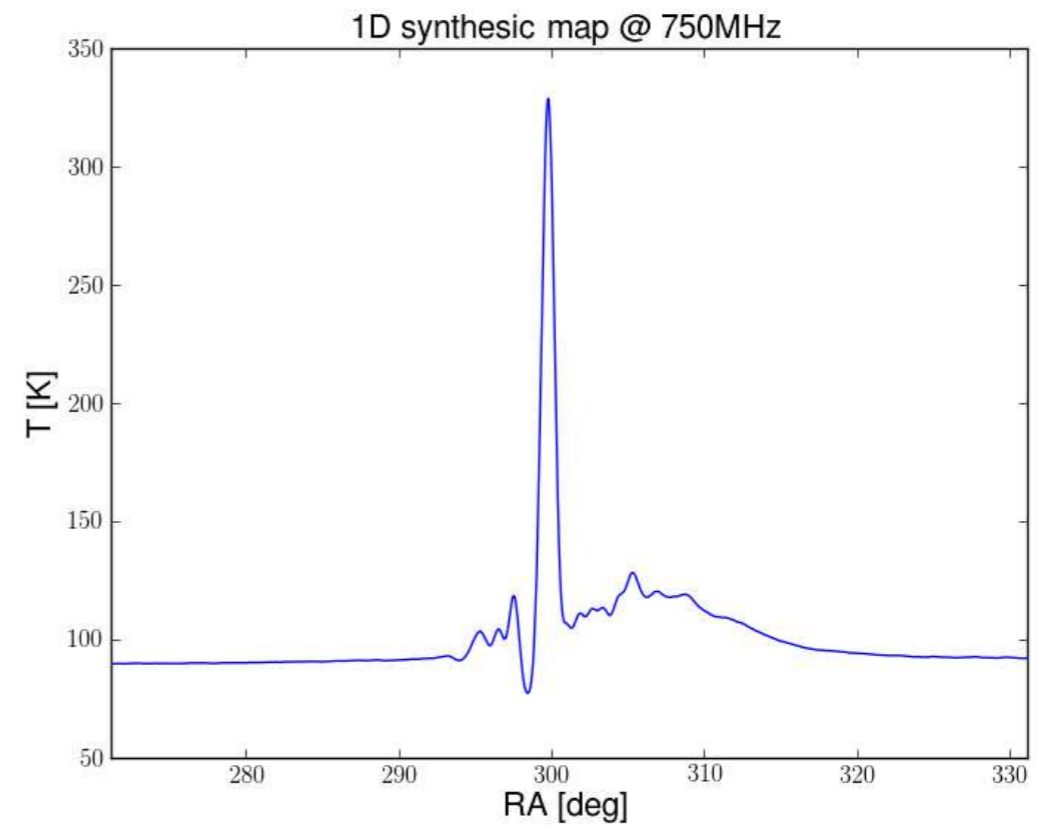
# Calibration & map with Tianlai Dish array

- Q. Huang applied similar methods to Tianlai 16 dish array
- Compatible phase calibration from ky (sources) and noise source

Cygnus A map (1D - single dish)



Cygnus A map (1D - 16-dish)



# Calibration

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- ❖ Initial calibration: use bright source transit to determine array geometry, beam, gain & phase [ Q. Huang ]
- ❖ Antenna beam determination using a dedicated measurements (drone ?)
- ❖ Array gain & phase calibration/monitoring using the noise source
- ❖ Gain & phase calibration and monitoring using the known sky (Radio sources & Synchrotron)
- ❖  $2N$  unknown ( or  $N$  complex ) -  $N(N+1)/2$  complex constraints  $\times$  number of time samples - But NOT (?) a linear fit ...
- ❖ Should be computed for each frequency, and freq. behaviour should be checked against a model.

# Technical considerations, Simulations

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## Level 0 (L0) output data (on site)

### ❖ Tianlai 16-Dish Array (T-16DA)

- ▶  $2 \times 16 = 32$  receivers, 1000 freq. channels, 528 visibilities
- ▶  $\sim 4\text{MB/sec}$  visibility data (averaged @ 1 sec. time interval)
- ▶  $350\text{ GB/day} \Rightarrow 1000\text{-}1500\text{ TB L0 data / year}$
- ▶  $\sim 288 \times 5\text{ min}$  time slice files / day (1.2 GB / file) - or  $24 \times 1\text{ h}$  time slice files (15 GB / file)

### ❖ Tianlai 3-Cylinder Array (T-3Cyl)

- ▶  $2 \times 3 \times 92 = 192$  receivers, 1000 freq. channels, 18 528 visibilities
- ▶  $\sim 140\text{ MB/sec}$  visibility data (averaged @ 1 sec. time interval)
- ▶  $12\text{ TB/day}$  ,  $\Rightarrow 35\text{ PB L0 data / year}$
- ▶  $\sim 10 \times 288 \times 5\text{ min}$  time slice files / day (4.2 GB / file) - or  $10 \times 24 \times 1\text{ h}$  time slice files (50 GB / file)

# L1: NAOC (Beijing)

- L0 output : Visibility data  $V_{ij}(v)$  computed on-line (in HW)
- Organize data sets as time sliced files , grouped with auxiliary (housekeeping) data
- Perform a first step, simple RFI mitigation
- Data compression, mainly through time averaging after RFI cleaning (factor 5-10)
- L1 output data :
  - ▶ T-16DA : 35-50 GB / day, ~100 files / day , ~100 TB / year
  - ▶ T-3Cyl : ~1000 GB / day, ~1000 files / day , 2-5 PB / year
- Transfer raw data (L1 output) to TAC

# TAC : Tianlai Archive and Analysis Center

## Fermilab (Batavia, IL)

- **L2-A:** second stage RFI cleaning, gain/noise monitoring
- **L2-B:** phase/gain calibration
- **L2-C:** 3D map making
- **L3 :** Component separation, power spectrum estimation
- **TAC:**
  - ▶ data organization and data access services
  - ▶ computation resources for L2 &L3 ( ~ few x 10 CPU-cores / MB/sec L1 data rate)

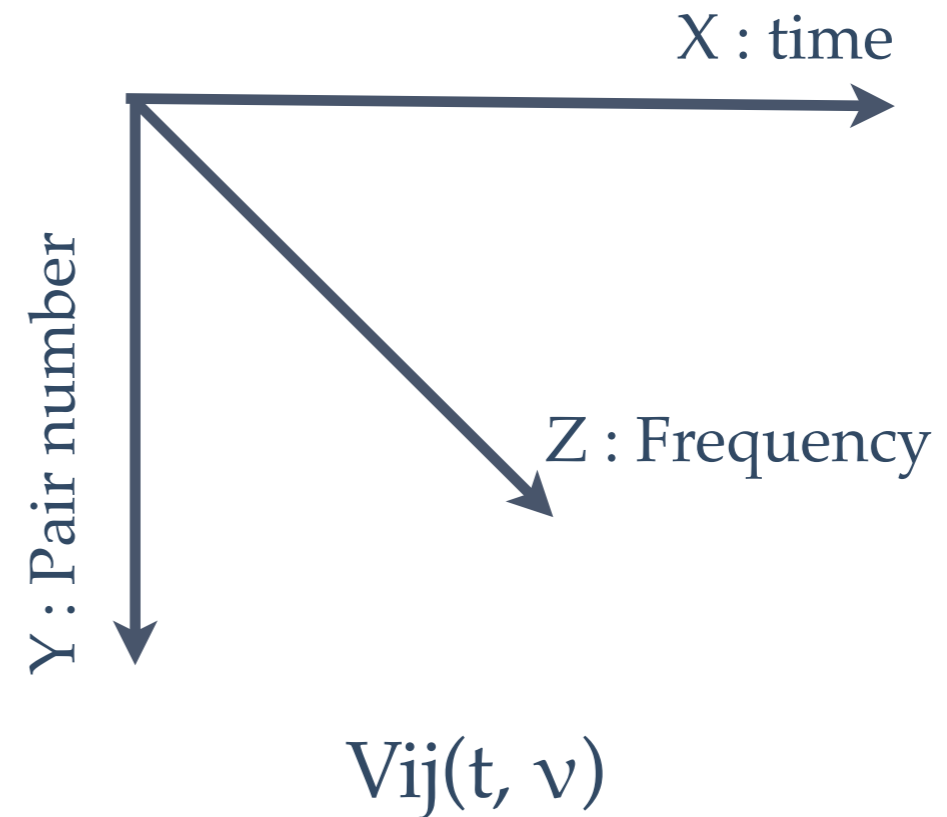
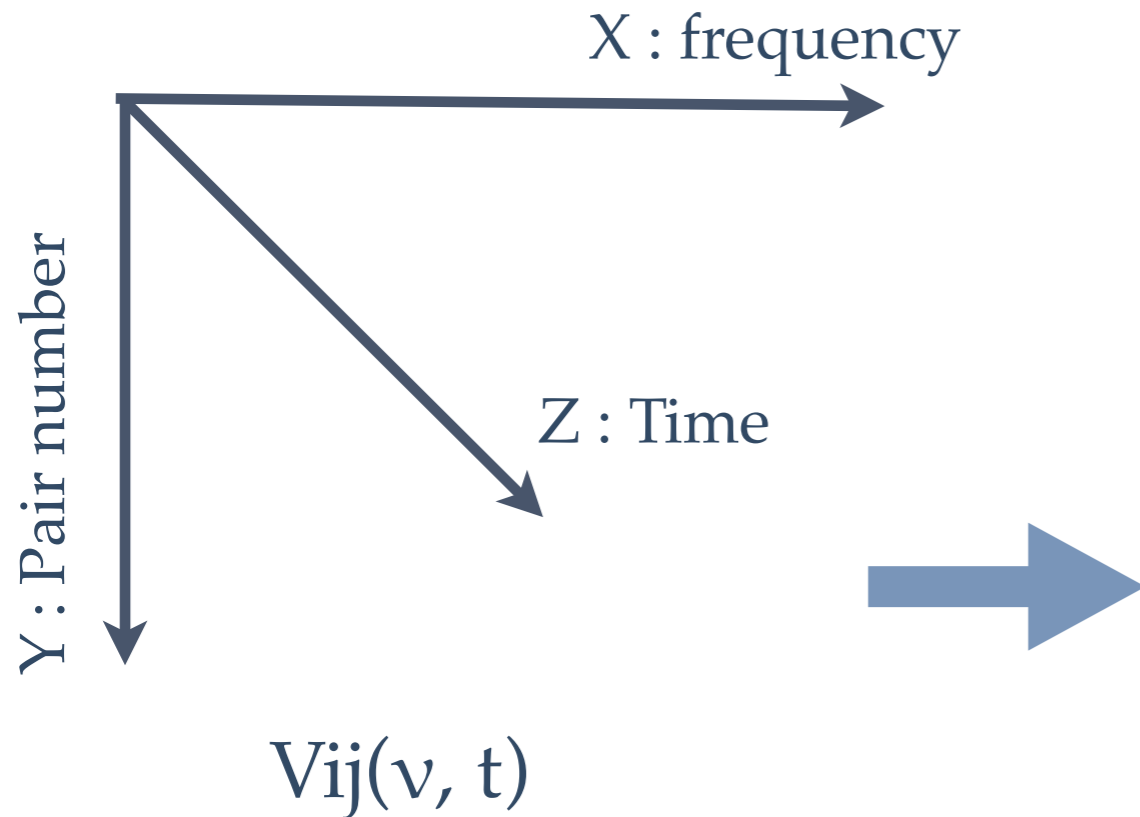
# File format, file organisation

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- ❖ HDF5 for visibility data
- ❖ Maps (HEALPix ...) in FITS or HDF5 ?
- ❖ Source catalog in FITS or HDF5 ?
- ❖ We need to setup a 'Data Base' to track the data files (visibility) and other instrument related files



# Visibility array structure



Might be broken in part according to frequency or pair number

Should we rearrange the visibility data at some stage of the processing ?

# Simulations

- ❖ Full sky signal simulation tools , or 3D maps
- ❖ Foreground (synchrotron) model / maps
- ❖ Comprehensive known Radio Source catalog
- ❖ Simulate Visibility time streams ( which is part of the map making software)
- ❖ Include calibration error models (beam, geometry)
- ❖ Noise & RFI model
- ❖ reconstruct maps, apply component separation ...