

effect) or a failure of the vent system when draining the cryostat. Vacuum-relief valves are provided on LNG storage tanks to protect the structure from these types of events.

The key active components of this additional protection system are Vacuum Safety Valves (VSVs) located on the roof of the cryostat that will monitor the differential pressure between the inside and the outside of the cryostat and open when the differential pressure exceeds a preset value, allowing air to enter the cryostat to restore a safe pressure. A combo PSV-VSV may be used instead of two separate devices, one for overpressure and one for vacuum.

## 2.13 Detector monitoring and slow control

The scope of the ProtoDUNE-SP detector control system (DCS) includes the design, procurement, fabrication, testing, and delivery of a comprehensive detector monitoring, control and safety system.

The responsibility for the system is split between ProtoDUNE-SP and CERN:

- The ProtoDUNE-SP collaboration is responsible for all the devices that will be installed and cabled inside the cryostat, the sensors needed to monitor the cryostat and its content, and the specifications for the system.
- CERN is responsible for the implementation of the control system elements outside the cryostat (hardware, firmware and software), including the high-voltage and low-voltage power supplies necessary for the detector operation.

This section describes the main requirements, constraints and assumptions of the control system, and its general structure and components.

### 2.13.1 Monitoring devices and sensors

A number of devices and sensors will be located inside the cryostat for either periodic or continuous monitoring of the LAr as well as the GAr in the ullage, and for the monitoring of the detector functionality.

#### Purity Monitors

Three purity monitors (PrM) with sensitivity in the ppt range will be used for the direct determination of the impurity content of the LAr inside the ProtoDUNE-SP cryostat. These PrMs have been generously provided by ICARUS [?] after being decommissioned from the T600. The design has been replicated for MicroBooNE and other R&D test experiments at FNAL. Inside the ProtoDUNE-SP the monitors are arranged in a single vertical string located behind the APA

planes on the Jura side (see Figure 4.2). The string hangs from the large blanking flange on the manhole, and ports with ConFlat sealing on the blanking flange will be made available for HV/Signal/OptFiber feedthroughs. The string is about 7 m long, with the three PrMs strung at different heights: one near the LAr surface, one at mid-height, and one at the very bottom near the LAr-return manifold, for monitoring the purity of the LAr entering the cryostat after the filtration process.

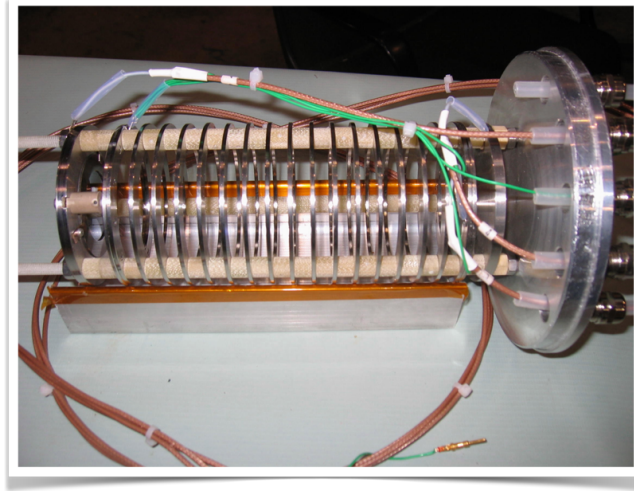


Figure 2.77: Picture of a purity monitor from the ICARUS T600, now available for installation in the ProtoDUNE-SP detector

The three PrMs, one of which is pictured in Figure 2.77, are currently being refurbished with new gold photocathode and new quartz fiber. The drift length (25 cm) is the same for all them. Using parts of another (available) PrM to extend the drift length of one of the three (e.g., to 40 cm) for more precise measurements of the longer  $e^-$  lifetimes is currently under consideration. The mechanical structure of the string, the anchorage to the manhole flange at the top end, and the fastening of the string at the bottom are still under study. An additional PrM at the bottom on the opposite side of the cryostat would be useful for monitoring variations in the quality of the LAr at that level, and providing information for the fluid-dynamics computation inside the cryostat.

### Vertical Temperature Gradient Monitor

Precise monitoring of the temperature gradient as a function of LAr depth is an important input for fluid dynamics modeling and simulations. The installation of a set of devices with precision better than 50 mK along the entire height of the LAr volume has recently been included in the internal instrumentation plan for this purpose. Commercial calibrated resistance temperature detectors (RTDs – Pt100 or Pt1000) with 15-mK precision at LAr temperature are well suited to this application, however the temperature probe wiring and signal transport outside the cryostat require extreme care in order to maintain the intrinsic precision of the probe.

The design for this device consists of a series of 25 Pt100 probes positioned at  $\sim 30$  cm intervals along a  $\sim 7.5$ -m-long rigid string hanging behind the APA plane from an available port at the

top of the cryostat. A special multi-pin FT is mounted on the flange for the signal extraction and readout from a temperature controller. Again, the mechanical structure, including the cable routing up to the multi-pin FT, is still subject to a detailed engineering study. A number of RTDs will also be positioned on the APAs and on the cryostat walls at different heights to monitor the temperature during the cooling process.

## Webcams

Based on a system developed by ETH Zurich for WA105, six commercial webcams, sealed inside a specially developed metal case with a ConFlat optical window to allow operation at cryogenic temperatures, are located inside the cryostat. They are positioned at strategic points allowing inspection of the interior during filling and commissioning, and detection (and recording) of possible sparks in locations exposed to high electric field intensity.

## Level Meters

Reliable LAr level determination is required in the  $\pm 20$  cm around the nominal LAr surface level. Commercially available liquid-level sensors provide high-reliability monitoring. These are available in multiple technologies, including solid-state electro-optical, conductive, capacitive and piezo-resonant. Although the technology choice has not been made, designated ports on the top of the cryostat are available for this instrumentation. In the absence of these devices, the vertical temperature gradient device will provide a coarse level reading during filling, and some information about the steady-state LAr level will be available from the differential pressure transducer.

## Pressure Sensors

Precise measurement of pressure in the GAr ullage is necessary. A number of pressure sensors, including a differential pressure transducer, are planned, and designated ports on the top of the cryostat are available for this instrumentation.

### 2.13.2 Slow Control System

The design of the ProtoDUNE-SP safety and control system is largely based on the experience gained in collaboration with ETH Zurich during the pilot WA105 project at CERN. The components of this system and their functions are as follows:

- The Process Control System (PCS) reads temperature sensors including the Vertical T Gradient monitor, pressure sensors and the purity monitors inside the cryostat and the trace analyzers ( $O_2$ ,  $N_2$ ,  $H_2O$ ) in the external recirculation line.

- The Detector Control System (DCS) monitors and controls the low voltage (LV) and high voltage (HV) from the power supplies.
- The Detector Safety System (DSS) performs temperature surveys and monitors interlocks.

The system provides a graphical user interface to visualize the trends of monitored values and any alarm conditions. A web interface allows for remote monitoring.

The physical interface of the control system is located at the level of the outer flanges on the cryostat. CERN EP/DT-DI will take care of connecting the control system to the flanges and interfacing to the cryogenics control infrastructure for information and signal exchange. The ProtoDUNE-SP experiment is responsible for all sensors, power distribution, etc., inside the cryostat, as well as for defining the system specifications, I/O parameters and control and safety logic.

The supervisory control of the system and data acquisition (SCADA) is being developed, tested and provided by CERN EP/DT-DI.

Figure 2.78 shows the general architecture of the control and safety system for ProtoDUNE-SP, including the PCS, the DCS and the DSS.

The control system is composed of:

- a chassis for electrical distribution (380 Vac, 220 Vac, 24 Vdc redundant);
- two chassis for the PCS, composed of an FPGA, signal conditioners, interface, and cabling;
- one chassis for the DCS, composed of an interface for LV/HV monitoring & control;
- a chassis for the DSS, composed of an FPGA and relays for the safety of the experiment;
- a chassis for a PC data acquisition & supervision (PVSS SCADA Supervisor), composed of a computer with a display monitor, a switch and a server;
- four chassis for the remote I/O to capture signals close to the detector and to avoid multi-cabling structure; and
- one chassis for the HV, controlled by the slow-control system.

All these elements will be mounted in 19-in. racks.

The supervisory software is based on the JCOP framework, an integrated set of software tools originally developed for the control of the LHC experiments at CERN and now used in several more experiments at CERN. Besides providing a supervisory control and data acquisition system, the framework offers many tools for the implementation of finite state machines, archival of data, as well as graphical interfaces as web dashboards.

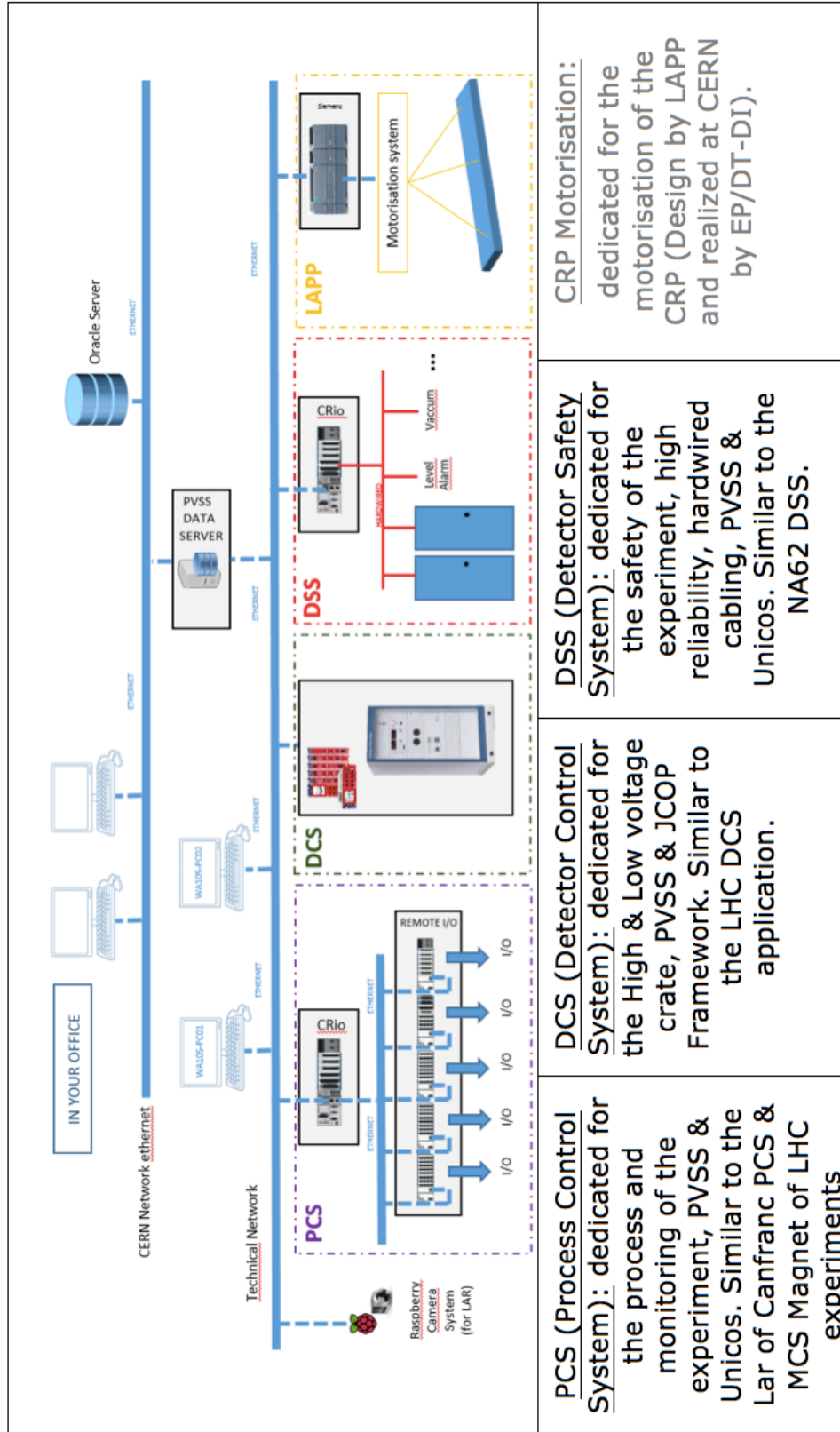


Figure 2.78: Proposed architecture and technical solution of the control and safety system.