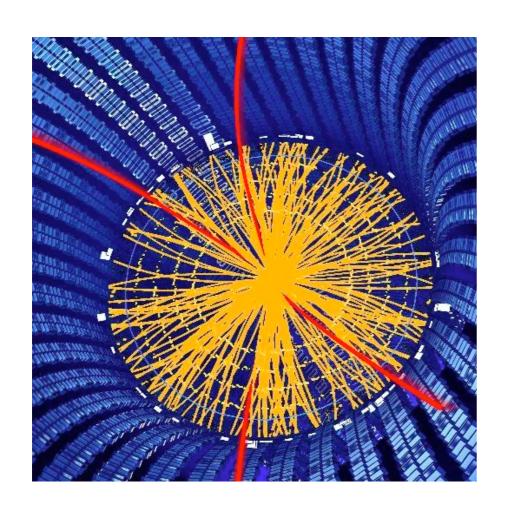


Large-Scale Distributed Network Training with MPI



Dustin Anderson Caltech

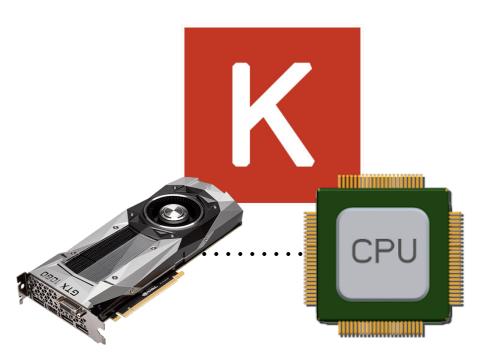
DS@HEP 11 May 2017





Overview

- GPU computation can dramatically speed up neural network training
- Lightweight ML libraries enable fast prototyping of NN models
 - → E.g., Keras
- User-friendly support for training with CPU + a single GPU





Overview

- Modern computing resources provide access to many GPUs simultaneously
- Physicists often have access to, e.g., supercomputers with hundreds of nodes
- Would like to maximally exploit these







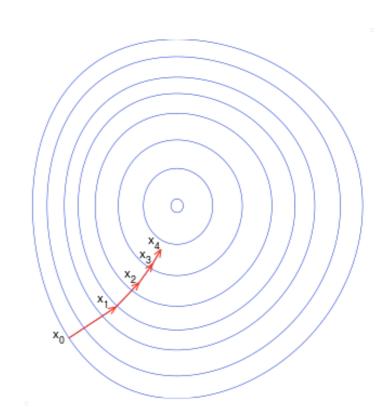
Neural Network Training

- NN training paradigm: stochastic gradient descent (SGD)
- Update rule for model weights $ec{w}$

$$\vec{w} \to \vec{w} - \eta \nabla Q(\vec{w})$$





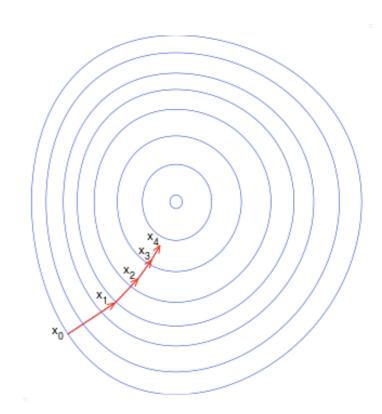


Minimize loss function Q(w)



Neural Network Training

- SGD is inherently sequential
- Two alternating steps:
 - 1. Compute gradient of loss
 - 2. Update model weights
- But algorithms exist to parallelize it

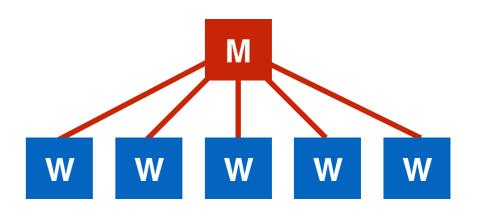


Minimize loss function Q(w)



Distributed Training

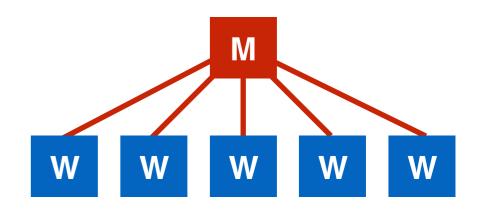
- Paradigm for distributed SGD:
 - → Have N compute nodes
 - → One node acts as "Master"
 - → The others are "Workers"
- Workers can communicate with Master synchronously (all at once) or asynchronously





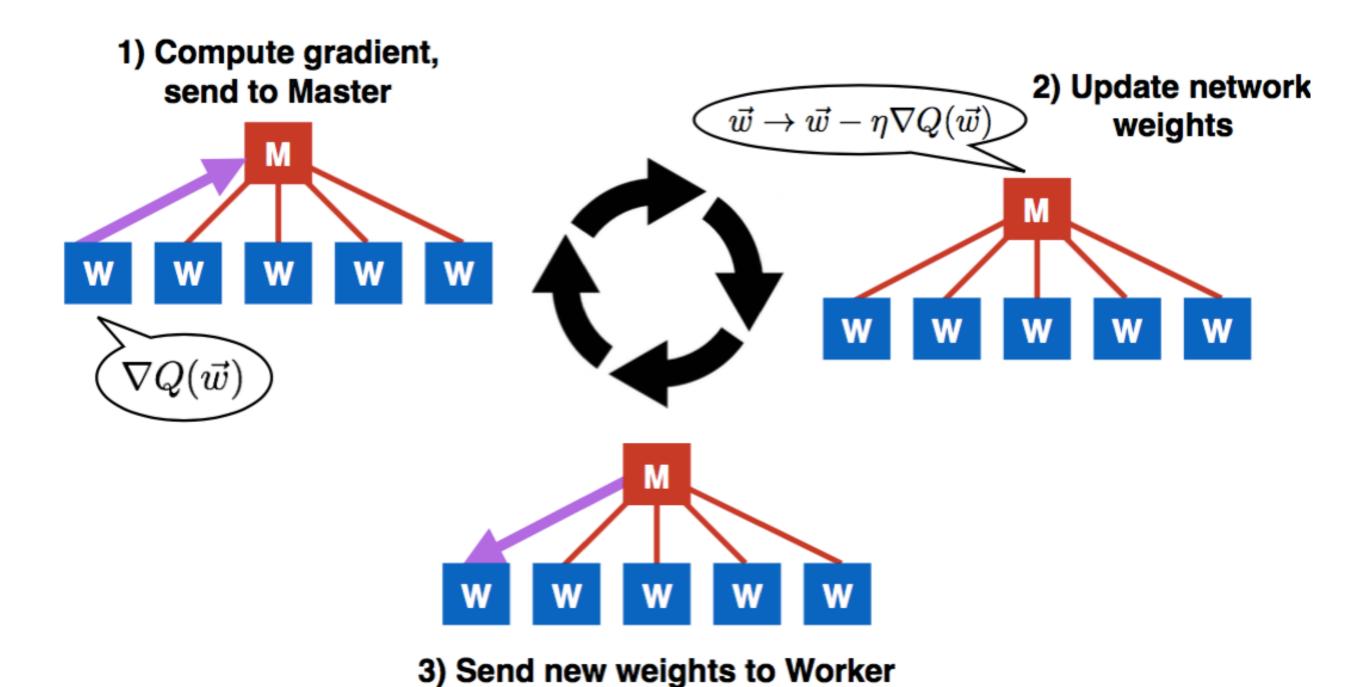
Downpour SGD

- "Downpour" is a straightforward algorithm for distributed SGD
- Worker-Master communication is asynchronous
- Master and Workers each have a local copy of the NN weights and some training/validation data





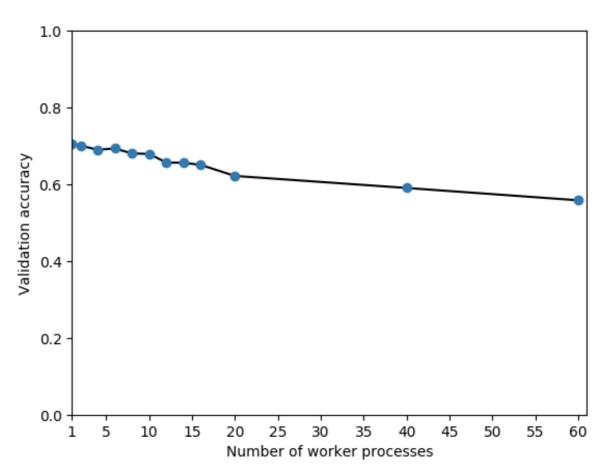
Downpour SGD





Stale Gradient Problem

- In a distributed setting, nodes often compute gradients using outdated model parameters
- SGD updates using old weights are suboptimal ("stale")
- This issue can be mitigated by suitable choice of SGD momentum [1]



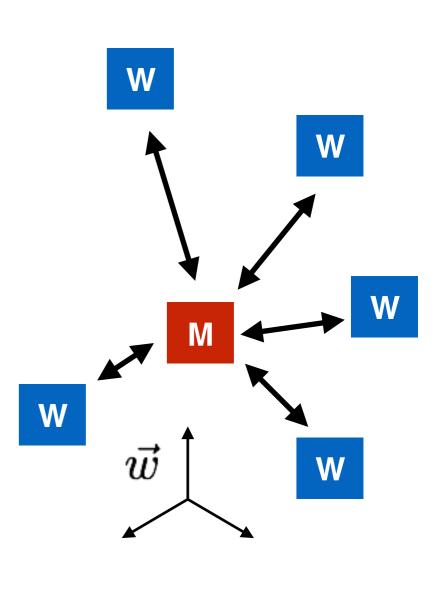
Validation accuracy decreases with larger number of nodes

[1] Omnivore: An Optimizer for Multi-device Deep Learning on CPUs and GPUs https://arxiv.org/pdf/1606.04487.pdf



Elastic Averaging SGD

- A different distributed training algorithm
- Master and Worker model weights are connected via an elastic force
- Workers have individual freedom to explore the parameter space





Learning with MPI

- The Message Passing Interface (MPI) is a widespread standard for parallel programming
 - → Used e.g. for job submission at supercomputing sites



 APIs/Libraries for C++, Python (mpi4py), and many others





MPI-Learn Library

 MPI-Learn is a python library for MPI-based distributed training of neural networks

https://github.com/duanders/mpi_learn

- Interfaces with Keras
- Goal: provide a lightweight, "plug & play" interface to multi-GPU training



MPI-Learn Library

- Basic workflow:
 - A. Define neural network as a Keras model
 - B. **Define a generator for training data** as a Python generator
 - C. Define training algorithm and any hyperparameters
 - D. Launch distributed training!



MPI-Learn Library

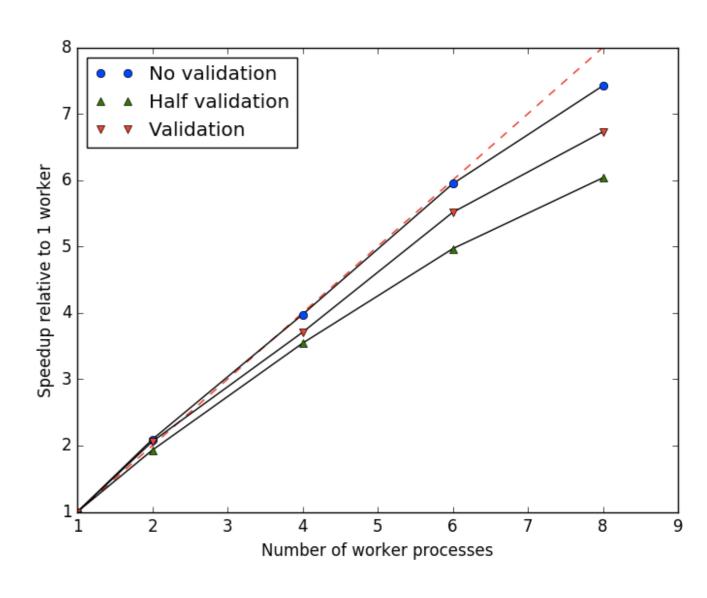
- Library features:
 - Downpour (with choice of gradient update algorithm) and Elastic Averaging SGD training
 - → Synchronous and asynchronous training
 - → Support for Theano and Tensorflow backends to Keras
 - → Preliminary support for other Master-Worker hierarchies

https://github.com/duanders/mpi_learn



Performance Tests

- Trained a benchmark NN on up to 8 GPUs
 - → RNN event classification model from J-R Vlimant's talk on Tuesday
- Training speed-up roughly linear with # of GPUs

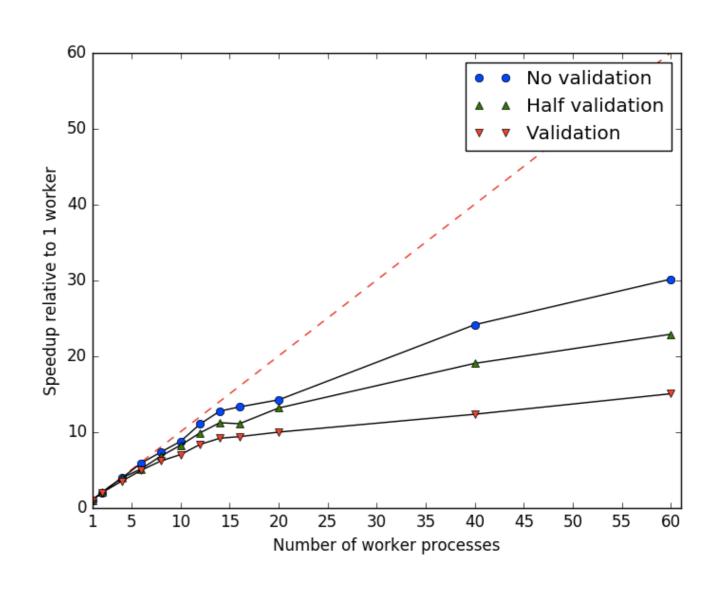


Validation is performed on a single node → constant contribution to training time



Performance Tests

- Larger-scale test using
 ALCF Cooley cluster
 - → Trained with up to 60 GPUs
- Speed-up is linear up to ~15 GPUs
- Speed-up is 30X when running on 60 GPUs





Conclusion

- Distributed learning becomes increasingly important as DNNs become larger and more widespread
- The MPI-Learn library provides a convenient interface to multi-GPU training of Keras models
- Facilitates quicker prototyping and testing of large deep neural networks