## Nonlinear Optics in UMER

## Brian Beaudoin

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## June, $6^{\text {th }} 2017$ <br> IOTA/FAST Workshop

## Outline

Three talks back-to-back

- Program Overview (Brian \& Tim)
- Precision/Performance Upgrade (Dave)
- Experimental and Simulation Results (Kiersten)


## The University of Maryland Electron Ring

A Research Machine for Advanced Beam Dynamics

Original Mission: Space charge over long pathlengths

- Low energy (10keV) electrons
- Currents (0.01-100 mA)
- Emittances (0.3-3 mm) Safe
Flexible Printed Circuit Magnets:
- Independently-powered quadrupoles, octupoles, dipoles
- Variable space charge
- Tune-in halo

Well bench-marked simulations


## Precision/Performance Upgrade - Phase 1

## Rebuilding the ring from the ground up

- Reset the ring into a circle.
- Remount the ring to the floor using properly rated anchors and epoxy.
- Using Leica T3000 theodolites and laser range finders to align the ring.



## Producing ultra-low current beams for pencil beam scanning - Phase 2



- The aperture would allow us to inject currents from $10 \mu \mathrm{~A}-1 \mathrm{~mA}$, in combination with old apertures and solenoid.
- The additional aperture would be fully retractable. To be installed soon

Actuating mirror cube


## Constructing the Single Channel for UMER

 Half an Octupole

Printed Circuit Octupole Dave Matthew, Octupole Design Heidi Baumgartner, Octupole Characterization


Octupole insert


Designed by Kiersten Ruisard and Heidi Baumgartner

## UMER:

# Reconstruction and Realignment 

February thru August 2016

David F. Sutter
IOTA Meeting
June 6, 2017

## The U of Maryland Electron Ring



## UMER Design Orbit:

Standard Ring Alignment Triangles
(36 Of these make up the ring)


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The design orbit is a 36 sided polygon with a circumference of 11520 mm .

These two specifications, and the locations of the quadrupoles on 16 cm centers, determine the Geometry of the EO, and therefore of the ring.


Component Mounting (20 ${ }^{\circ}$ ) plate

## Standard UMER $20^{\circ}$ Plate - with targets



RC7


RC7

## Why a Rebuild \& Realignment?

## UMER Mounting Assembly

~20 lb. Hoop force,
Toward ring center
due to vacuum


Old UMER Floor Plate

## Fasteners - Before and After




## The Essential Floor Template



## New Floor Plate Ready for Stand

## Ring Layout

## Glass gaps are installed at RC-4, RC-10, RC-16 and the $Y$ Section.

BPM-1 $\quad R_{\text {BPM }}=1828.81 \mathrm{~mm}$ One of the 2 basic design


RC3

$P D$ is the pulsed dipole used for injection. The center of PD and the ring center locate the $Y$ axis and the $\boldsymbol{\theta}=0.000^{\circ}$ line for polar coordinates.
$R_{\text {rot }}=1648.87 \mathrm{~mm}$ used to set the yaw of the top plate.

## UMER Design Tolerances

An ELEGANT simulation suggests that transverse rms position errors of 125 microns will give a 2 mm rms amplitude variation in the equilibrium orbit - this is acceptable for operation.

| Type of Error | Simulation | Control |
| :--- | :---: | :---: |
| Quadrupoles | Tol. | Tol . |
| Translation (x) | 0.100 mm | 0.05 mm |
| Translation (y) | 0.100 mm | 0.05 mm |
| Translation (z) | 1.0 mm | 0.50 mm |
| Rotation (about z) | 2.0 mrad | 1.0 mrad |
| Rotation (about x) | -2.0 mrad | 1.0 mrad |
| Rotation (about y) | -2.0 mrad | 1.0 mrad |
| Strength | $0.10 \%$ | $0.05 \%$ |
| Dipoles |  |  |
| Translation | 1.0 mm | 0.05 mm |
| Rotation (about z) | -2 mrad | 1 mrad |
| Strength | $0.40 \%$ | $0.20 \%$ |
| BPM |  |  |
| Aggregate Res. | --- | 0.25 mm |
| X, Y Position | --- | 0.1 mm |
| Rotation Angle | 10 mrad | 5 mrad |

## Tune scan, comparison: pre- and post- upgrade

Comparison of current in 6 mA beam on $20^{\text {th }}$ turn across a range of operating points normalized to maximum current in first turn.



# Update on Simulations and Experiments at UMER 

Kiersten Ruisard
Heidi Baumgartner, David Matthew, Irving Haber, Santiago Bernal, Brian
Beaudoin, Timothy Koeth

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## Nonlinear (octupole) lattice at UMER

Octupoles scale with $\beta(s)^{-3} \rightarrow$ quasi-integrable Hamiltonian conserved

Octupole strength
T-insert
Diagram of the lattice structure for Nonlinear UMER



Position along $20^{\circ}$ plate [mm]


## Lattice Design

Half of ring, in non-FODO lattice:




Twiss parameters--input: fulling.ele lattice: umer.lte
$\Delta \Psi_{\text {channel }}=0.23 * 2 \pi$


- $\beta_{x}=\beta_{y}$ in nonlinear insert
- Equivalent to thin lens kick
- Phase advance $\pi$
- Achromatic


## Printed Circuit Octupole Magnets

Heidi Baumgartner, Dave Matthew


Measured: $51.6 \pm 1.5 \mathrm{~T} / \mathrm{m}^{3} / \mathrm{A}$
Predicted: 74 T/m³/A
Higher order multipoles suppressed by $10^{-2}$

Quadrupole/sextupole components unexpected



## Experimental Plans

UMER Beams

- Tune/ lattice function measurement
- Tune scan around integrable condition
- Halo damping

Starting with low current ( $\sim 60 \mu \mathrm{~A}$ )
Need large number of turns

| Current <br> $[\mathrm{mA}]$ | Initial rms $\boldsymbol{\varepsilon}$ <br> $[\boldsymbol{\mu m}]$ | Avg. Radius <br> $[\mathrm{mm}]$ | ${\mathbf{v} / \mathbf{v}_{\mathbf{o}}}^{$ Coherent  <br>  tune shift $}$ | Incoherent <br> tune shift |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0.6 | 0.4 | 1.6 | 0.85 | -0.005 | 0.94 |
| 6.0 | 1.3 | 3.4 | 0.62 | -0.05 | 2.4 |
| 21 | 1.5 | 5.2 | 0.31 | -0.17 | 4.5 |



Dialed-in Halo
How many turns can we expect?
Is dominant loss mechanism due to transverse or longitudinal losses?
What is our sensitivity to transverse resonances? Can we verify quasi-integrable condition is met? (Including accurate tune prediction and


| Beam <br> Current | Approx. \# <br> Turns to <br> Debunch | Approx. \# <br> Turns <br> with Long. <br> Focusing |
| :--- | :---: | :---: |
| $60 \mu \mathrm{~A}$ | 72 |  |
| $600 \mu \mathrm{~A}$ | 25 | 1,000 |
| 6.0 mA | 9 | 100 |
| 21 mA | 6 |  |
| 104 mA | 3 |  |

0.6 mA (Pencil Beam)

| Current | Initial <br> rms $\boldsymbol{\varepsilon}$ | Avg. <br> Radius | ${\mathbf{v} / \mathbf{v}_{\mathbf{o}}}^{\text {Coherent }}$ | Incoherent <br> tune shift <br> tune shift |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0.6 mA | $0.4 \mu \mathrm{~m}$ | 1.6 mm | 0.85 | -0.005 | 0.94 |




## Low-current "DC-beam"

| METHOD | BEAM CURRENT, <br> PULSE LENGTH | MEASUREMENT |
| :--- | :--- | :--- |
| DC Electron Gun | $10-100 \mathrm{~mA}$, <br> 100 ns | 40 mA, <br> $\varepsilon_{x, y} \cong 300,100 \mu \mathrm{~m}$ |


| Current | Initial rms $\boldsymbol{\varepsilon}$ | Avg. <br> Radius | $\mathbf{v}^{\prime} / \mathbf{v}_{\mathbf{o}}$ |
| :---: | :---: | :---: | :---: |
| $60 \mu \mathrm{~A}$ | $300 \mu \mathrm{~m}, 100 \mu \mathrm{~m}$ | $?$ | $?$ |



$60 \mu \mathrm{~A}$ "DC-beam"

| Current | Initial rms $\boldsymbol{\varepsilon}$ | Avg. <br> Radius | v/v $_{\mathbf{o}}$ |
| :---: | :---: | :---: | :---: |
| $60 \mu \mathrm{~A}$ | $300 \mu \mathrm{~m}, 100 \mu \mathrm{~m}$ | $?$ | $?$ |

single octupole powered at 3 A, 155 T/m³




## Longitudinal Confinement



## Pencil beam with confinement

Use RF induction cell to extend beam lifetime.
Pencil beam scan with $30 \%$ loss after 720 turns




Loss curve measurement without confinement, 1000 turns


## Measuring bare tune

RC6 horizontal centroid oscillation



## Last year's to-do list

Recommissioning of the beam
Simulation program to catch up to experimental

Experimental run with re-aligned beam
Working out kinks with magnet models.
Experimental study for beam-based survey of magnets (Levon Dovlatyan)

- Quantify conservation of Hamiltonian/ tune spread

Characterization of octupoles See NAPAC'16 proceedings, Heidi Baumgartner
Mechanical framework for single-channel in-progress experiment on 20-degree section
Distributed octupole lattice tests at On hold for now, in favor of experimental improved operating point
studies to support planned octupole lattice
experiments

## Ongoing work

## Simulation effort

- Correction for edge-focusing effect on matching (aided by beam-based survey of dipoles)
- Lattice design with less sensitivity to errors

Experimental Effort

- Characterizing resonances/loss rates of low-current DC beam beyond 125 turns
- Longitudinal confinement for assisting many-turn studies - addressing noise and shock-wave effect on measurement of transverse losses.
- Verifying models against tune measurement
- Beam injection to non-FODO lattice

Ring improvements

- Full implementation of vertical steering upgrade
- Long octupole channel in-progress
- Installation and characterization of new apertures


## Steering Tolerances



Modeling of orbit distortion


Modeling of beam immersed in background field

## Steering tolerances

| $1^{\text {st }}$ turn orbit control; deviation from quadrupole center |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 2017 |  | 2016 | 2013 |
| X RMS [mm] | 0.4 | 1.2 | 3.4 |  |
| X Maximum [mm] | 1 | 4.1 | $>20$ |  |
| Y RMS [mm] | $3.2(0.6)$ | 3.2 | 7.4 |  |
| Y Maximum [mm] | $10.8(3.6)$ | 10.8 | $>20$ |  |
| Multi-turn control < 1.2 mm |  |  |  |  |



## BPM location <br> 




## Back Up Slides

## Installing a Base Plate

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## Mechanical Layout



## Refastening Template



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## Mechanical Alignment (cont.)



