# Light signal simulation and light maps for 6x6x6m<sup>3</sup> detector

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WA105 General Meeting 23 March 2017





# Introduction

Light simulation can be divided in two parts:

- Scintillation (production of the photons)
- Light propagation in the detector.
  - $\rightarrow$  This talk focuses on the light propagation simulation

Main part : production of pre-calculated light maps

- Since last General Meeting (March 2016), we have worked on the LightSim software:
  - The method and functions related to the map generation have been implemented
  - Studies about design impact on light collection have been performed
  - The current design of 6x6x6 has been implemented

Light maps for 6x6x6m<sup>3</sup> have been produced

• **QScan** has been **updated** to use these new maps (WA105Soft rev438)





In LightSim:

- #S1 photons is calculated using the deposited energy and the recombination rate.
- #S2 photons is estimated via an electrominescence gain G



### Propagation of scintillation photons (128nm):

- Absorption in LAr
- Rayleigh scattering on LAr molecules
- Absorption on different detector components (field cage, cathode supporting structure, tank...)

### Problematic:

- Tracking each scintillation photon takes a lot of time
- Less than 1% of photons reach the PMTs



Solution: simulate the tracks only once, and store the useful information in Light Maps

Important points about light map generation:

- These maps describe the photon propagation
  - $\rightarrow$  Independent from the scintillation parameters
- LAr absorption process is not taken into account for the map generation to allow studies with different absorption length
  - $\rightarrow$  Will be simulated when using the maps in QScan



Solution: simulate the tracks only once, and store the useful information in Light Maps

For each photon **production point** in the detector, and each **PMT**, the map gives:

- Probability to reach the PMT
- Travel time distribution



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LAr and GAr volumes are **split** in **voxels** 



Production point



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Production point



#### Tracking



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Tracking

Production point

Travel time distribution



Travel time [ns]

# Implemented geometry

The detector **geometry** has evolved in parallel to the TB design studies during the **last months** 

Detector components implemented for the map generation:



The positioning of the PMTs is not yet defined. 2 options: uniformly spaced (65cm) or non-uniformly spaced

→ Production of 2 different maps



# Dependence on the detector geometry

### Study of the geometry modification impact on light signal collection

### Studies concerning stainless-steel components:

- Cathode pipes
- Cathode supporting structure
- Ground grid

### Method:

Generation of photons at different points of detector, and comparison of the number of collected photons before and after the detector component implementation

### Results:

- Cathode pipes and cathode supporting structure: average loss of 60%
- Ground grid: average loss about 25%
- → The light loss is mainly due to the absorption on stainless steel (100%)

Note: the previous maps (/sps/hep/lbno/dataset/LightMap\_old) didn't took these stainless steel structures in account



### PMT positioning impact on light signal collection

The PMT positioning is not yet fixed:

Comparison between PMT spaced by 65cm and PMT non-uniformly spaced



Default drawing in the SPSC report



### PMT positioning impact on light signal collection

**Reminder**: the absorption in LAr is not taken into account



→ Impact on the background induced by cosmic muons ? (will be discussed at the end of the talk)

### Light map characteristics Voxel definition and propagation parameters

### • LAr maps:

- Large voxels definition: 250mmx250mmx250mm
- Number of voxels: 24x24x29 = 16704 voxels
- Cover a volume of about 6mx6mx7m
- Number of generated photons per voxel:  $10^7$  over  $4\pi$

#### • GAr maps:

- Voxel definition: 250mmx250mmx5mm (576 voxels)
- Only 1 voxel in Z (photons generated between LEM plates and LAr surface)
- Number of generated photons per voxel:  $5.10^8$  over  $4\pi$
- To save time, photons are generated in ~1/8 of the detector, then we use the X-Y symmetry of the detector to reconstruct the whole map.

 $\rightarrow$  Simulation of 2262 voxels instead of 16704 for LAr map

Propagation parameters in LAr

(**Reminder**: the absorption in LAr **is not include** in the map generation, but is taken into account in **QScan**)



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# Time distribution characteristics

- **Probability** to reach the PMT: weight =  $\frac{\text{Number of photons reaching the PMT}}{\text{Number of generated photons}}$
- Travel time distribution shape: strongly depends on the distance to the PMT



# Time distribution characteristics

The time distribution is reconstructed using a landau fit and 3 parameters:



→ Satisfactory in most cases

 $\rightarrow$  Has to be **optimized** for voxels with too **few collected photons** and voxels **close to the PMT** (narrow distributions)



# Maps utilization in QScan

Updated maps are available at <a href="https://www.spinite.com">spinite.com</a> Updated maps are available at <a href="https://www.spinite.com">spinite.com</a> (spinite.com</a> (spinite.com)

LightMap\_6x6x6\_PMTNonUni\_LAr LightMap\_6x6x6\_PMTNonUni\_GAr + README MAPS

LightMap\_6x6x6\_PMT6x6\_LAr LightMap\_6x6x6\_PMT6x6\_GAr

The changes in QScan and datacards corresponding to these new light maps have been released on svn (WA105Soft rev438)

### Light maps in QScan:

- For each step and each PMT:
  - Interpolation of the map values to the step coordinates

→ Interpolation between the
8 nearest voxel centers
(weighted average method)



 Computation of: # detected S1 photons (with the number of produced photons and the weight) # detected S2 photons (using the number of drifted electrons, G, and the weight)

For each detected photon: computation of the photon travel time (using landau parameters and t0)



# LAr absorption implementation in QScan

LAr absorption in QScan (first order approach)

1. For each photon reaching the PMT array, computation of the probability to not being absorbed by LAr

 $p = \exp(-\text{travel\_time} \cdot \frac{C}{\lambda_{Abs} \cdot n_{Ar}})$  (called **w\_absorption** in QScan)

- 2. Generation of a random number between 0 and 1 (uniformly distributed).
  - 3. rdm < p: the photon is not absorbed rdm > p: the photon is absorbed





Stored in the maps: Rayleigh scattering and stainless steel absorption effects





# Results on cosmic background

Cosmic muons are generated within a (-8ms, +4ms) time window

 $\rightarrow$  We look at the signal within a (-4ms , +4ms) time window



# Electroluminescence gain impact

The number of S2 photons is computed using an electroluminescence gain G

G = number of S2 photons per electron reaching the extraction grid

• This gain is fixed at 300 ph/e (generated over  $4\pi$ )in QScan, but the true value is unknown



 $\rightarrow$  Needs additional simulation and measurements to determine the value of G

### PMT positioning impact on signal induced by cosmics muons



- Electroluminescence gain G=300
- PMT and electronics response not taken into account

• 400ns sampling

#### Non-uniformly spaced

#### Uniformly spaced



→ The two configurations are quite similar for light collection

 $\rightarrow$  The configuration with PMTs **spaced** by 65cm slightly increases the collected photon number

# Conclusion and Perspectives

### Conclusion

- The LightSim software has been developed to follow the 6x6x6 design evolution, and to perform studies about the design impact on light collection:
  - **PMT** configurations
  - Cathode supporting structure
  - Transparent cathode (ITO coated PMMA plates)
  - Ground grid and LEM plates implementation
- Optimization of the photon travel time distribution parametrisation
- Studies about the LAr absorption length impact on light collection in LightSim and QScan (with APC

group)

Maps for the 6x6x6 are produced and are now available to the collaboration QScan is updated to use these new light maps

### Next steps

- Determination and validation of the electroluminescence gain G (simulation and data)
- Cosmic tagging and rejection using the maps (work in development)
- Continue the optimization of the travel time distribution parametrisation
- Maps for 3x1x1
  - Implementation of the 3x1x1 geometry (on going)
  - Adaptation of the voxel definition to 3x1x1 volume

