

#### Down to the Line: Compressed Kinematics in SUSY Searches

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### A Tribute to SUSY

- Provides mechanism for electroweak symmetry breaking, unification of forces, and dark matter candidate  $\tilde{g}$
- Naturalness: should have light stops, gluin  $\tilde{b}_{L}$ s, &  $\tilde{t}_{R}$ Higgsinos (~Ge $\langle \tilde{b}_{L}$  mass splittings)  $\tilde{H}$



# Physics On The Edge

- Small mass splittings between parent & daughter particles are experimentally challenging
  - Daughter particles produced practically at rest: soft final state objects, little E<sub>T</sub><sup>miss</sup> from LSP
  - Limits historically worse on these "diagonals"
- Requires clever use of kinematics and ISR-assisted topologies



### Making Ermiss with ISR

• With no other final state objects, LSPs are back to back, no  $E_T^{miss}$  in event



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Total E<sub>T</sub>miss = 0 GeV

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### Making Ermiss with ISR

- With no other final state objects, LSPs are back to back, no  $\mathsf{E}_{\mathsf{T}^{\mathsf{miss}}}$  in event
- Require ISR jet: collimate LSPs, generate measurable ETmiss for trigger





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# A Variable Zoo

➤ Recursive Jigsaw Reconstruction (RJR) is an effective model independent technique for enhancing sensitivity with compressed signals and soft decay products







### Stop Exclusions + RJR



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See: stop 0L (arXiv:1709.04183), stop 1L(arXiv.1606.03903)



## Higgsino Diagonal Search

- $\Delta m \approx 0 \rightarrow RISR \sim m_{LSP} / m_{chargino}$
- Combine with new soft lepton strategies and triggers to reach Δm
  < 5 GeV</li>
  *coming soon!*



#### Conclusions

- Compressed SUSY models will continue to be a corherstone of the  $\tilde{\chi}_{W}^{p}$ LHC search program
- Recursive Jigsaw Reconstruction (RJR)<sup>p</sup> can provide extra sensitivity <sup>w</sup>
  to compressed signals via kinematics
- Expanding use across all kinds of SUSY searches

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 Many new physics searches are (fundamentally) similar! Can imagine building an RJR tree for any decay chain...



DM + ttbar



#### Backup

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## RJR Algorithm

- Use "event CM" frame to identify ISR jets and calculate  $\rm R_{\rm ISR.}$ 
  - makes sure that the MET and jets used in the analysis balances each other out.
- "CM" frame is the frame that all objects accepted into the event has Pt = 0
- So set MET  $P_z = 0$  and mass = 0.
- Set all Jet  $P_z=0$  and  $E^2 = m^2 + P_T^2$ .
- Sum all 4 vectors of all accepted signal objects and boost to the where  $P_T = 0$  for this combined 4 vector.
  - Do nothing in the Z direction
- Ost order correction for MET coming from jets or other objects that you don't accept into your analysis and ensures R<sub>ISR</sub> has an upper bound of 1.
- A simplified and exaggerated case for 2 jets is shown in the right



# RJR Algorithm

- ISR is identified in the CM frame by minimizing the sparticle system and ISR system masses
- Can think of this in 2 equivalent ways
- 1. Large jet clustering along two jet axis that are back to back using mass as a distance metric
- 2. Minimizing  $M_s$  and  $M_{ISR}$  is identical to maximizing the amount of back to back  $P_T$  of the two systems.
  - Because  $E_{tot} = sqrt(M_S^2 + P_T s) + sqrt(M_{ISR}^2 + P_{T ISR})$
  - $E_{tot}$  is constant for the event and  $P_T = P_{TS} = -P_{TISR}$
  - Maximizing  $P_{\rm T}$  along a back to back axis is the same thing as calculating the thrust axis
  - The event is then divided into hemisphere wheres the hemisphere containing the MET is the sparticle system and other hemisphere the ISR system.

