# Statistical Aspects of Quantum Computing 

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Near-term Applications of Quantum Computing
Fermilab, December 6-7, 2017

## Outline

- Statistical learning with quantum annealing
- Statistical analysis of quantum computing data


## Statistics and Optimization

MLE/M-estimation, Non-parametric smoothing,

- Stochastic optimization problem: $\min _{\theta} \mathcal{L}\left(\theta ; \mathbf{X}_{n}\right)=\frac{1}{n} \sum_{i=1}^{n} \ell\left(\theta ; X_{i}\right)$
- Minimization solution gives an estimator or a classifier. Examples : $\ell\left(\theta ; X_{i}\right)=\log p d f$; residual square sum / loss + penalty


## Statistics and Optimization MLE/M-estimation, Non-parametric smoothing,

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- Minimization solution gives an estimator or a classifier.

Examples : $\ell\left(\theta ; X_{i}\right)=$ log pdf; residual square sum / loss + penalty
Take $g(\theta)=E\left[\mathcal{L}\left(\theta ; \mathbf{X}_{n}\right)\right]=E\left[\ell\left(\theta ; X_{1}\right)\right]$

- Optimization problem: $\min _{\theta} g(\theta)$
- Minimization solution defines a true parameter value.


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Goals: Use data $\mathbf{X}_{n}$ to do the following
(i) Evaluate estimators/classifiers (minimization solutions) Computing
(ii) Statistical study of estimators/classifiers - Inference

## Computer Power Demand

## Computer Power Demand

## BIG DATA



## Computer Power Demand

## BIG DATA



## Scientific Studies and

## Computational Applications


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## Learning examples

Machine learning and compressed sensing

- Matrix completion, matrix factorization, tensor decomposition, phase retrieval, neural network.


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## History



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## History



Dog vs cat


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Neural network: Layers in a chain structure
Each layer is a function of the layer preceded it.
Layer $j: h_{j}=g_{j}\left(a_{j} h_{j-1}+b_{j}\right),\left(a_{j}, b_{j}\right)=$ weights, $g_{j}=$ activation function (sigmoid, softmax or rectifier)

History



Dog vs cat


## Gradient Descent Alorithms: Solve $\min _{\theta} g(\theta)$

Gradient descent algorithm

- Start at initial value $x_{0}$,
$x_{k}=x_{k-1}-\delta \nabla g\left(x_{k-1}\right), \delta=$ learning rate, $\nabla=$ derivative operator


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## Accelerated Gradient descent algorithm (Nesterov)

- Start at initial values $x_{0}$ and $y_{0}=x_{0}$,

$$
x_{k}=y_{k-1}-\delta \nabla g\left(y_{k-1}\right), \quad y_{k}=x_{k}+\frac{k-1}{k+2}\left(x_{k}-x_{k-1}\right)
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- Start at initial value $x_{0}$, $x_{k}=x_{k-1}-\delta \nabla g\left(x_{k-1}\right), \quad \delta=$ learning rate, $\nabla=$ derivative operator
Continuous curve $X_{t}$ to approximate discrete $\left\{x_{k}: k \geq 0\right\}$
Differential equation: $\dot{X}_{t}+\nabla g\left(X_{t}\right)=0, \quad \dot{X}_{t}=$ derivative $=\frac{d X_{t}}{d t}$

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Continuous curve $X_{t}$ to approximate discrete $\left\{x_{k}: k \geq 0\right\}$ Differential equation: $\dot{X}_{t}+\nabla g\left(X_{t}\right)=0, \quad \dot{X}_{t}=$ derivative $=\frac{d X_{t}}{d t}$
Convergence to the minimization solution at rate $=1 / k$ or $1 / t(\uparrow)$ as $t, k \rightarrow \infty$. For the ccelerated case: Rate $=1 / k^{2}$ or $1 / t^{2}(\downarrow)$

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## Stochastic Gradient Descent

Stochastic optimization: $\min _{\theta} \mathcal{L}\left(\theta ; \mathbf{X}_{n}\right), \mathbf{X}_{n}=\left(X_{1}, \cdots, X_{n}\right)$

- Gradient descent algorithm to compute $x_{k}$ iteratively

$$
x_{k}=x_{k-1}-\delta \nabla \mathcal{L}\left(x_{k-1} ; \mathbf{X}_{n}\right), \quad \nabla \mathcal{L}\left(\theta ; \mathbf{X}_{n}\right)=\frac{1}{n} \sum_{i=1}^{n} \nabla \ell\left(\theta ; X_{i}\right)
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BigData: expensive to evaluate all $\nabla \ell\left(\theta ; X_{i}\right)$ at each iteration

- Replace $\nabla \mathcal{L}\left(\theta ; \mathbf{X}_{n}\right)$ by

$$
\nabla \hat{\mathcal{L}}^{m}\left(\theta ; \mathbf{X}_{m}^{*}\right)=\frac{1}{m} \sum_{j=1}^{m} \nabla \ell\left(\theta ; X_{j}^{*}\right), \quad m \ll n
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$\mathbf{X}_{m}^{*}=\left(X_{1}^{*}, \cdots, X_{m}^{*}\right)=$ subsample of $\mathbf{X}_{n}$ (minibatch or bootstrap sample).

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Continuous curve $X_{t}^{*}$ to approximate discrete $\left\{x_{k}^{*}: k \geq 0\right\}$ $X_{t}^{*}$ obeys stochastic differential equation.

## Gradient Descent vs Stochastic Gradient Descent



## Gradient Descent vs Stochastic Gradient Descent

## Gradient Descent



Stochastic gradient descent


## Statistical Analysis of Gradient Descent (Wang, 2017)

## Continuous curve model

Stochastic differential equation: $d X_{t}^{*}+\nabla g\left(X_{t}^{*}\right) d t+\sigma\left(X_{t}^{*}\right) d W_{t}=0$ $W_{t}=$ Brownian motion
For the accelerated case:
2nd order stochastic differential equation

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2nd order stochastic differential equation
and their asymptotic distribution
as $m, n \rightarrow \infty$ via stochastic differential equations

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## and their asymptotic distribution

as $m, n \rightarrow \infty$ via stochastic
differential equations
Example $X_{i}=\left(U_{i}, V_{i}\right), i=1, \cdots, n=10000$

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\begin{aligned}
& V_{i}=U_{i} \theta+\varepsilon_{i}, \quad U_{i} \sim \text { i.i.d.bivariate } N(0, \Sigma), \varepsilon_{i} \sim i . i . d . N\left(0, \tau^{2}\right) \\
& \ell\left(\theta ; X_{i}\right)=\left(V_{i}-U_{i} \theta\right)^{2}, m=200, \text { true } \theta=(0,0) .
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## Deep Learning

Boltzmann Machine (BM) on graph $\mathcal{G}=(\mathcal{V}, \mathcal{E})$

$$
P(\mathbf{s})=\frac{\exp [-E(\mathbf{s})]}{Z}, \quad Z=\sum_{\mathbf{s}} \exp [-E(\mathbf{s})]
$$

- Energy

$$
E(\mathbf{s})=-\sum_{(i, j) \in \mathcal{E}} W_{i j} s_{i} s_{j}-\sum_{i \in \mathcal{V}} b_{i} s_{i}, \quad \mathbf{s}=\left(s_{1}, \cdots, s_{|\mathcal{V}|}\right) \in\{-1,1\}^{|\mathcal{V}|}
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$$

Take $\mathbf{s}=(\mathbf{v}, \boldsymbol{h})$
$\mathbf{v}=\left(\mathbf{v}_{\mathbf{1}}, \cdots, \mathbf{v}_{\mathbf{n}}\right)$ : visible nodes (observed variables)
$\boldsymbol{h}=\left(h_{1}, \cdots, h_{m}\right)$ : hidden nodes (latent variables).
Boltzmann distribution models data $\mathbf{v}$ :

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## Learning

Use training data $\mathbf{v}$ to learn model parameters $W_{i j} \& b_{i}$.

## Restricted Boltzmann Machine (RBM)

Bipartite undirected graph $\mathcal{G}$
Connections between hidden layer and visible layer but not within each layer

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## Model

Variables in visible layer:

$\mathbf{v}=\left(v_{1}, \cdots, v_{n}\right)$,
Variables in hidden layer:

$$
\begin{aligned}
\boldsymbol{h}= & \left(h_{1}, \cdots, h_{m}\right) \\
& P(\mathbf{v}, \boldsymbol{h})=\exp \{-E(\mathbf{v}, \boldsymbol{h})\} / Z
\end{aligned}
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$$
E(\mathbf{v}, \boldsymbol{h})=-\sum_{i=1}^{n} \sum_{j=1}^{m} w_{i j} v_{i} h_{j}-\sum_{i=1}^{n} b_{i} v_{i}-\sum_{j=1}^{m} c_{j} h_{j}
$$

## Deep Neural Network: Restricted Boltzmann Machine

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Conditional independence within each layer given the others

$$
P(\boldsymbol{h} \mid \mathbf{v})=\prod_{j=1}^{m} P\left(h_{j} \mid \mathbf{v}\right), \quad P(\mathbf{v} \mid \boldsymbol{h})=\prod_{i=1}^{n} P\left(v_{i} \mid \boldsymbol{h}\right)
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$$

Sigmoid activation function for forward and backward conditional probabilities: $\operatorname{sigmoid}(x)=1 /\left[1+e^{-x}\right]$

$$
\begin{aligned}
& P\left(h_{j}=1 \mid \mathbf{v}\right)=\text { sigmoid }\left(\sum_{i=1}^{n} w_{i j} v_{i}+c_{j}\right) \\
& P\left(v_{i}=1 \mid \boldsymbol{h}\right)=\text { sigmoid }\left(\sum_{j=1}^{n} w_{i j} h_{j}+b_{i}\right)
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## Deep Learning

Gradient ascent/descent to compute model parameters $w_{i j}, b_{i}$ and $c_{j}$.

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Parameter updates with learning rate $\eta$

$$
\begin{gathered}
w_{i j}^{(t+1)}=w_{i j}^{t}+\eta \frac{\partial \log P}{\partial w_{i j}} \\
b_{i}^{(t+1)}=b_{i}^{t}+\eta \frac{\partial \log P}{\partial b_{i}}, \quad c_{j}^{(t+1)}=c_{j}^{t}+\eta \frac{\partial \log P}{\partial c_{j}}
\end{gathered}
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## Deep Learning

Gradient ascent/descent to compute model parameters $w_{i j}, b_{i}$ and $c_{j}$.

## Gradient

$$
\frac{\partial \log P}{\partial w_{i j}}=\left\langle v_{i} h_{j}\right\rangle_{\text {data }}-\left\langle v_{i} h_{j}\right\rangle_{\text {model }}
$$

$$
\frac{\partial \log P}{\partial b_{i}}=\left\langle v_{i}\right\rangle_{\text {data }}-\left\langle v_{i}\right\rangle_{\text {model }}, \frac{\partial \log P}{\partial c_{j}}=\left\langle h_{j}\right\rangle_{\text {data }}-\left\langle h_{j}\right\rangle_{\text {model }}
$$

- $\left\langle v_{i} h_{j}\right\rangle_{\text {data }}$ : the clamped expectation with $\mathbf{v}$ fixed

$$
\text { Bottleneck: } \quad\left\langle v_{i} h_{j}\right\rangle_{\text {model }}=\sum_{\mathbf{v}, \boldsymbol{h}} v_{i} h_{j} P(\mathbf{v}, \boldsymbol{h})
$$

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## Markov Chain Monte Carlo (MCMC)

Metropolis-Hastings algorithm/Gibbs sampler
Sample from Boltzmann distribution
$P(\mathbf{s})=\frac{\exp \left[-H_{\text {lsing }}(\mathbf{s}) / T\right]}{Z_{T}}, Z_{T}=\sum_{\mathbf{s}} \exp \left[-\frac{H_{\text {lsing }}(\mathbf{s})}{T}\right], T=$ temperature

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## Simulated annealing: Thermal Fluctuation

Slowly lower the temperature to reduce the escape probability of trapping in local minima,

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\text { Annealing schedule : } T_{i} \propto \frac{1}{i+1} \text { or } \frac{1}{\log (i+1)}
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## BigData

Issues: not easy for parallel computing; very hard to scale-up!

Quantum Annealing (QA): Basic Idea Classical optimization: $\operatorname{Min}\left\{H_{\text {lsing }}(\mathbf{s}): \mathbf{s} \in\{-1,1\}^{N}\right\}$

## Quantum Annealing (QA): Basic Idea

 Classical optimization: $\operatorname{Min}\left\{H_{\text {Ising }}(\mathbf{s}): \mathbf{s} \in\{-1,1\}^{N}\right\}$Find a target quantum system with Hamiltonian $H(1)$ whose energies match $H_{\text {lsing }}(\mathbf{s}): H(1)=\operatorname{diag}\left\{H_{\text {lsing }}\left(\mathbf{s}_{1},\right) \cdots, H_{\text {lsing }}\left(\mathbf{s}_{2^{N}}\right)\right\}$.

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Create an initial quantum system with Hamiltonian $H(0)$ whose lowest energy state is known and easy to prepare.

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Create an initial quantum system with Hamiltonian $H(0)$ whose lowest energy state is known and easy to prepare.

QA: Engineer $H(0)$ in its lowest energy state and gradually move $H(0) \longrightarrow H(1)$


## Simulated Quantum Annealing (SQA)

Spin glass in transverse field

$$
H=\mathbf{A}(\mathbf{t}) \mathbf{H}_{\mathbf{x}}+\mathbf{B}(\mathbf{t}) \mathbf{H}_{\text {lsing }}, \text { two parts non-commuting }
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Path integral representation via Suzuki-Trotter expansion $H \approx H_{2+1}=$ classical (2+1)-dimensional anisotropic Ising system


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Path integral representation via Suzuki-Trotter expansion $H \approx H_{2+1}=$ classical (2+1)-dimensional anisotropic Ising system
$(2+1)$-dimensional system
Two directions: along the original 2-dimensional direction spins have Chimera graph couplings, and along the extra (imaginary-time) direction spins have uniform couplings


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Path integral representation via Suzuki-Trotter expansion $H \approx H_{2+1}=$ classical (2+1)-dimensional anisotropic Ising system
( $2+1$ )-dimensional system
Two directions: along the original 2-dimensional direction spins have Chimera graph couplings, and along the extra (imaginary-time) direction spins have uniform couplings

Quantum Monte Carlo
$\mathrm{H}_{2+1}$ : a collection of 2-dimensional classical Ising systems, that can be simulated by MCMC with moves in both directions


## SSSV Annealing Model

Magnet $i$ points in direction with angle $\theta_{i}$ w.r.t. $\vec{z}$-axis in the xz plane, an external magnetic field with intensity $A(t)$ pointing in the $\vec{x}$-axis, Hamiltonian, $J_{i j}=$ coupling of magnets $\theta_{i}$ and $\theta_{j}$,

$$
H(t)=-A(t) \sum_{i=1}^{N} \sin \theta_{i}-B(t) \sum_{1 \leq i<j \leq N} J_{i j} \cos \theta_{i} \cos \theta_{j}
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Use the converted states to evaluate $H_{\text {lsing }}(\mathbf{s})$ and find its minimizer

## DW Signal vs Background Noise



## DW Signal vs Background Noise



## Correlation of Ground State Success Probability Data



## Multiple Statistical Tests

For the $r$-th instance, repeat $m$ times of annealing, let $\hat{p}_{0 r m}$ be DW success frequency out of $m$ repetitions and $\hat{q}_{e r m}, \ell=1,2,3$, the success frequencies for SA, SQA \& SSSV

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$H_{0 r}: p_{0 r \infty}=q_{\ell r \infty}$ vs $H_{a r}: p_{0 r \infty} \neq q_{\ell r \infty}$

$$
T_{r \ell}=\frac{m\left(\hat{p}_{r}-\hat{q}_{\ell, r}\right)^{2}}{\hat{p}_{r}\left(1-\hat{p}_{r}\right)+\hat{q}_{\ell, r}\left(1-\hat{q}_{\ell, r}\right)}
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Asymptotic distribution under $\mathrm{H}_{\text {or }}$
As $m, n \rightarrow \infty$, if $\log n / m \rightarrow 0$, then

$$
T_{r \ell} \longrightarrow \chi_{1}^{2}, \quad T_{r \ell}^{*} \longrightarrow \chi_{1}^{2} \quad \text { uniformly over } r=1, \cdots, n
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p -values \& FDR
$H_{0 r}$ vs $H_{a r}:$ p-value $=P\left(\chi_{1}^{2} \geq T_{r e}\right) \quad$ p-value $=P\left(\chi_{1}^{2} \geq T_{r \ell}^{*}\right)$

## Goodness-of-fit test

$H_{0}: p_{0 r \infty}=q_{\ell r \infty}$ for all $1 \leq r \leq n$ vs $H_{a}: p_{0 r \infty} \neq q_{\ell r \infty}$ for some $r$

$$
U_{\ell}=(2 n)^{-1 / 2} \sum_{r=1}^{n}\left(T_{r \ell}-n\right) \quad U_{\ell}^{*}=(2 n)^{-1 / 2} \sum_{r=1}^{n}\left(T_{r \ell}-n\right)
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Asymptotic distribution under $H_{0}$ as $m, n \rightarrow \infty$

$$
U_{\ell} \rightarrow N(0,1) \quad U_{\ell}^{*} \rightarrow N(0,1)
$$

## Conditions

(1) $\sqrt{n} / m \rightarrow 0$.
(2) $p_{0 r \infty}=q_{\ell r \infty}=$ true success probability for method $\ell$ with the $r$-th instance are bounded away from 0 and 1.

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Asymptotic distribution under $H_{0}$ as $m, n \rightarrow \infty$

$$
U_{\ell} \rightarrow N(0,1) \quad U_{\ell}^{*} \rightarrow N(0,1)
$$

p -value $=2\left[1-\Phi\left(\left|U_{\ell}\right|\right)\right] \quad \mathrm{p}$-value $=2\left[1-\Phi\left(\left|U_{\ell}^{*}\right|\right)\right]$
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## Multiple Tests: FDR

(a)

(c)

(b)

(d)


## Multiple Tests: FDR


$p$-values

## Multiple Tests: FDR



## $p$-values

## FDR

## q-value = essentially zero

## Goodness-of-fit-test

## Goodness-of-fit-test

SQA vs DW<br>$p$-values = 0

## Goodness-of-fit-test

SQA vs DW<br>p -values $=0$

## SSSV vs DW

$p$-values = 0

## Goodness-of-fit-test

SQA vs DW<br>$p$-values $=0$

SA vs DW
p -values $=0$
SSSV vs DW
p -values $=0$

## Goodness-of-fit-test

Reject null hypothesis SA vs DW
all $p$-values $\leq 3.87 \times 10^{-6}$ ..... $p$-values = 0
SQA vs DW
SSSV vs DW
$p$-values = 0

## Goodness-of-fit-test

Reject null hypothesis
all p-values $\leq 3.87 \times 10^{-6}$
SQA vs DW
p -values = 0

SA vs DW
$p$-values $=0$
SSSV vs DW
p -values $=0$

Conclusion: Overwhelming rejection
Overwhelming evidence to reject that DW is statistically consistent with SQA or SSSV in terms of ground state success probability

## Histogram of Ground State Success Probability Data

(a) DW

(c) SQA

(b) SA

(d) SSSV


## SA Histograms for different annealing times

(a) SA with 100 sweeps

(c) SA with 10000 sweeps

(b) SA with 1000 sweeps

(d) SA with 50000 sweeps


## SQA Histograms

## Various annealing times



## SQA Histograms

## Various annealing times

(a) SQA with 3000 sweeps

(c) SQA with 7000 sweeps

(b) SQA with 5000 sweeps

(d) SQA with 10000 sweeps


## Various temperatures



## SSSV Histograms

## Various annealing times



## SSSV Histograms

## Various annealing times

(a) SSSV with $\mathbf{5 0 0 0}$ sweeps

(c) SSSV with 15000 sweeps

(b) SSSV with 75000 sweeps

(d) SSSV with 150000 sweeps


## Various temperatures



## DIP Test for Shape Patterns

$$
\operatorname{DIP}\left(F_{n}\right)=\max _{0 \leq p \leq 1}\left|F_{n}(p)-\hat{F}_{n}(p)\right|
$$

$F_{n}=$ empirical $\mathrm{DF}, \hat{F}_{n}=\mathrm{DF}$ estimator under unimodality or U-shape
Under uniform null (asymptotic least favorable) distribution, as $n \rightarrow \infty$, $\sqrt{n} \operatorname{DIP}\left(F_{n}\right) \rightarrow \operatorname{DIP}(B), \quad B(t)=$ Brownian bridge on $[0,1]$

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Unimodality (including monotone)
DW: no

## SA: yes

SQA: no
SSSV: no

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DW: no
SQA: no
SSSV: no
U-shape

SA: no
SQA: yes
SSSV: yes

## Histogram of Success Probability

(a) DW

(c) SQA

(b) SA

(d) SSSV


## Histogram of Success Probability

(a) DW

(c) SQA

(b) SA
(d) SSSV


## Shape Pattern Analysis by Regression

## Covariates <br> Energy gap \& Hamming distance between ground state and 1st excited state

## Shape Pattern Analysis by Regression

## SQA



## Covariates

Energy gap \& Hamming distance between ground state and 1st excited state

## Shape Pattern Analysis by Regression

## SQA

(c) $S Q A$



## SSSV

(e) SSSV

(f) SSSV


## Covariates

Energy gap \& Hamming distance between ground state and 1st excited state

## Shape Pattern Analysis by Regression

(c) $S Q A$


## SSSV

(e) SSSV

(d) SQA

(a) SA

(b) SA


## Covariates

Energy gap \& Hamming distance between ground state and 1st excited state

## Shape Pattern Analysis by Regression

## SQA

SQA with Hammming distance less than 5


SQA with Hammming distance at least 5


## Shape Pattern Analysis by Regression

## SQA

SQA with Hammming distance less than 5
SQA with Hammming distance at least 5



## SSSV

SSSV with Hammming distance less than 5
SSSV with Hammming distance at least 5



## Shape Pattern Analysis by Regression

SQA with Hammming distance less than 5


SQA with Hammming distance at least 5


SA with Hammming distance less than 5


SA with Hammming distance at least 5


## SSSV

SSSV with Hammming distance less than 5
SSSV with Hammming distance at least 5



## Concluding Remarks

Both inference and computing are inportant for big data.

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## Interface

- Computing for conducting statistical inference; and statistics for analyzing computational algorithms.
- Statistics for quantum technology (e.g. quantum computing \& tomography), and quantum computing for statistical computing and machine learning.

