

LAUREN TOMPKINS

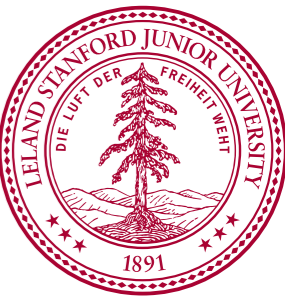
HCPSS 2018

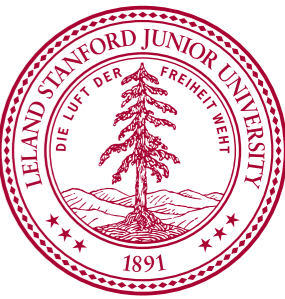
# TRIGGER AND DATA ACQUISITION



**Stanford**  
University

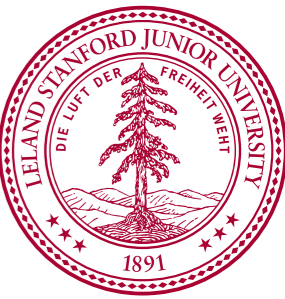
# GENERAL OUTLINE OF THE LECTURES





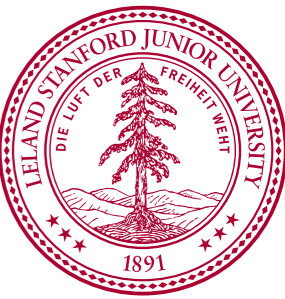
# GENERAL OUTLINE OF THE LECTURES

- Introduction to me, this talk, and TDAQ



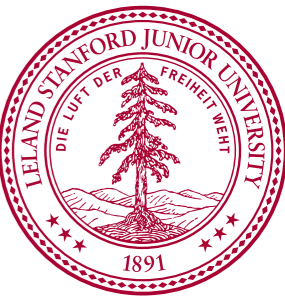
# GENERAL OUTLINE OF THE LECTURES

- Introduction to me, this talk, and TDAQ
- Start off with some context: what is the trigger & data acquisition challenge?



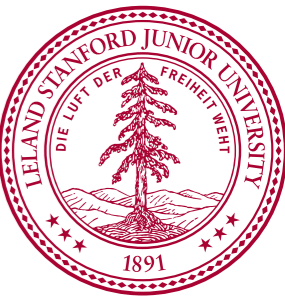
# GENERAL OUTLINE OF THE LECTURES

- Introduction to me, this talk, and TDAQ
- Start off with some context: what is the trigger & data acquisition challenge?
- Spend some time with a toy example



# GENERAL OUTLINE OF THE LECTURES

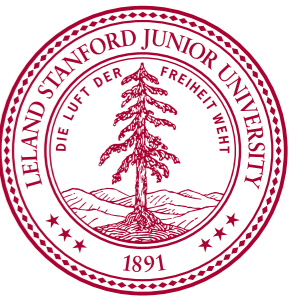
- Introduction to me, this talk, and TDAQ
- Start off with some context: what is the trigger & data acquisition challenge?
- Spend some time with a toy example
- Translate that example into the LHC ecosystem



# GENERAL OUTLINE OF THE LECTURES

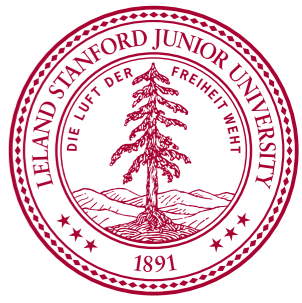
- Introduction to me, this talk, and TDAQ
- Start off with some context: what is the trigger & data acquisition challenge?
- Spend some time with a toy example
- Translate that example into the LHC ecosystem
- Look to the future

# HELLO!

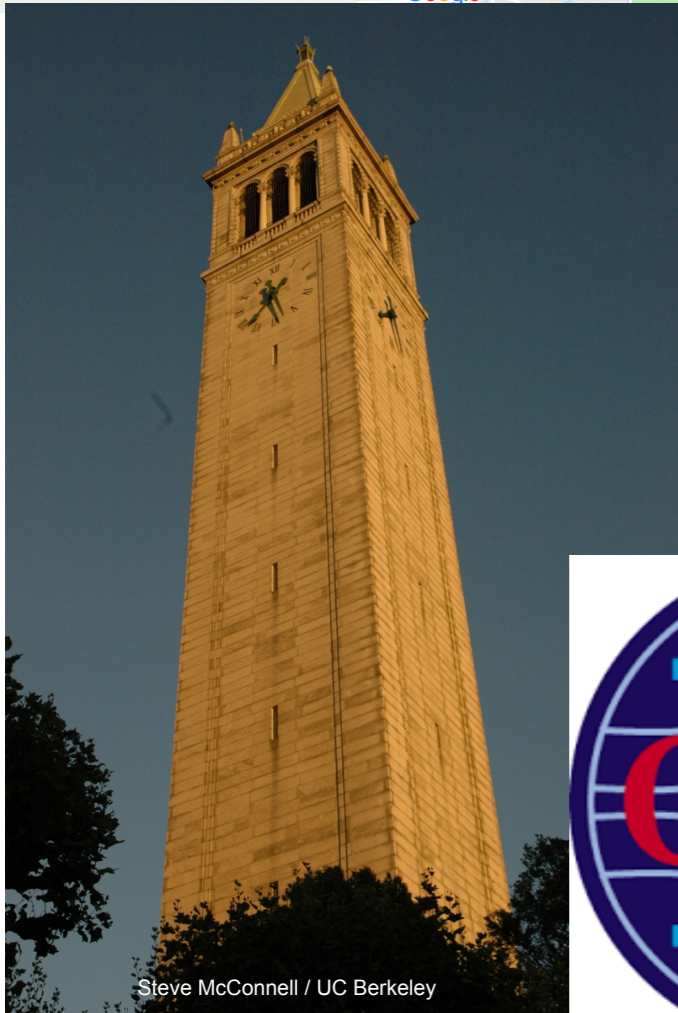
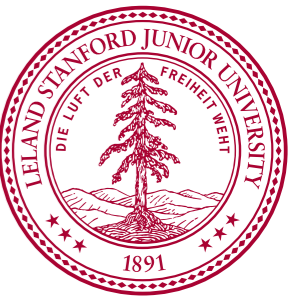




# HELLO!



# HELLO!



Steve McConnell / UC Berkeley



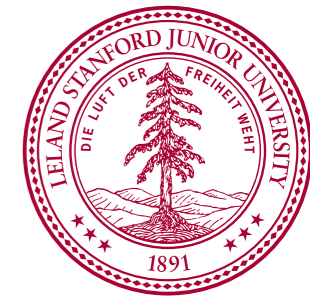
# HELLO!



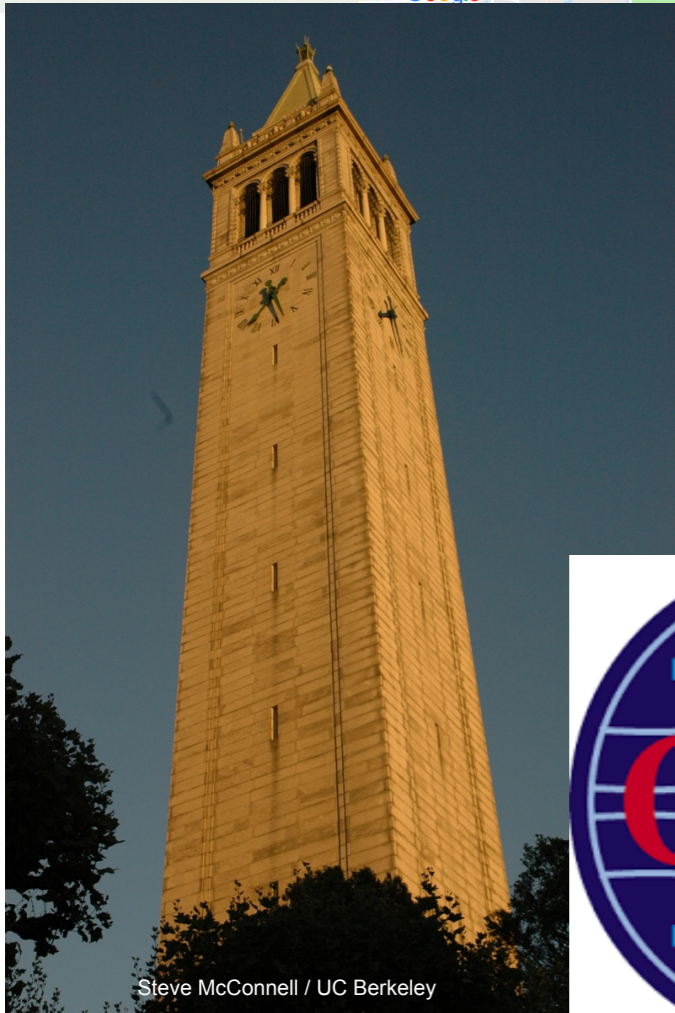
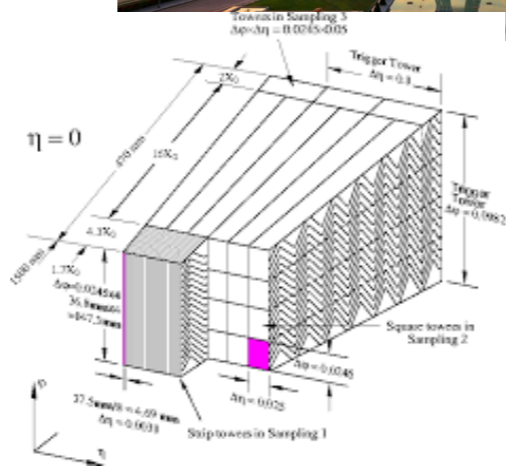
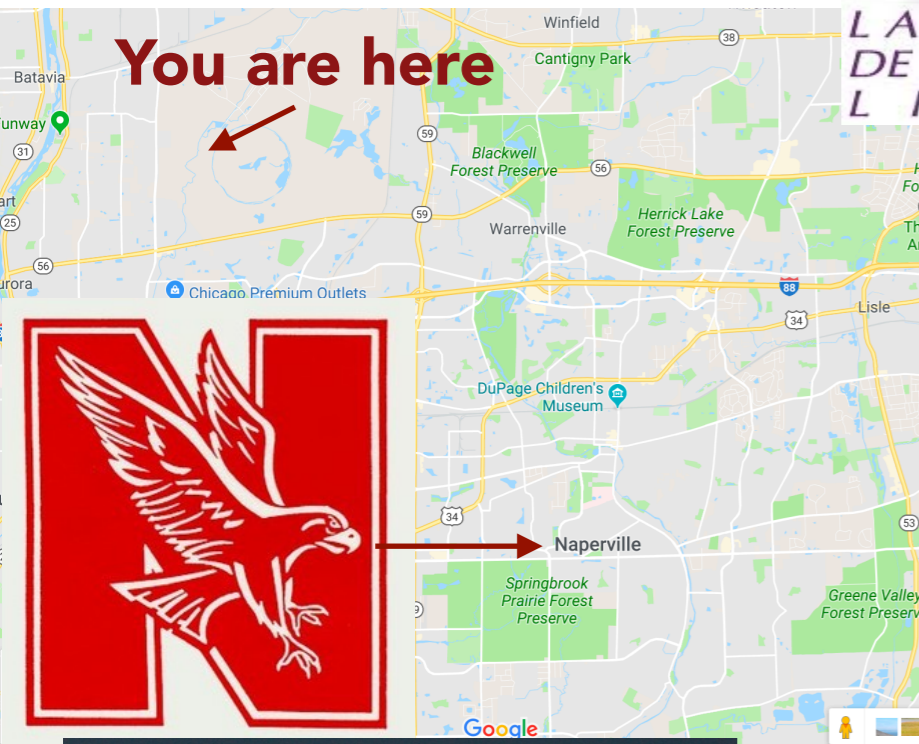
LABORATOIRE  
DE L'ACCÉLÉRATEUR  
LINÉAIRE



ATLAS  
EXPERIMENT



You are here



Steve McConnell / UC Berkeley



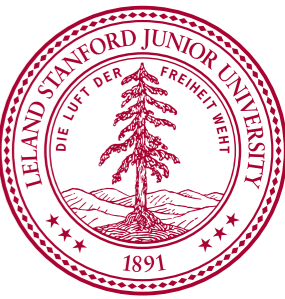
# HELLO!



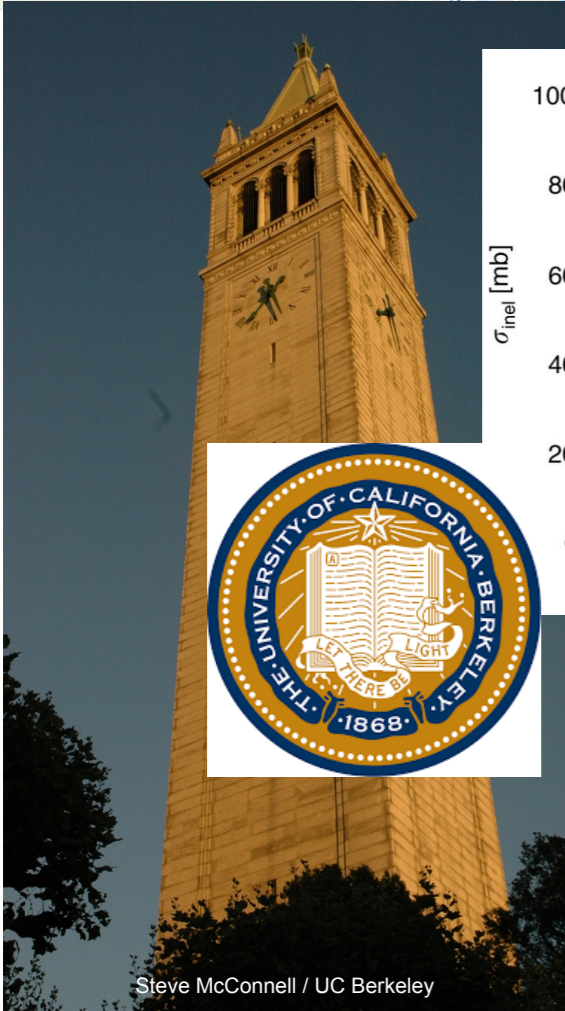
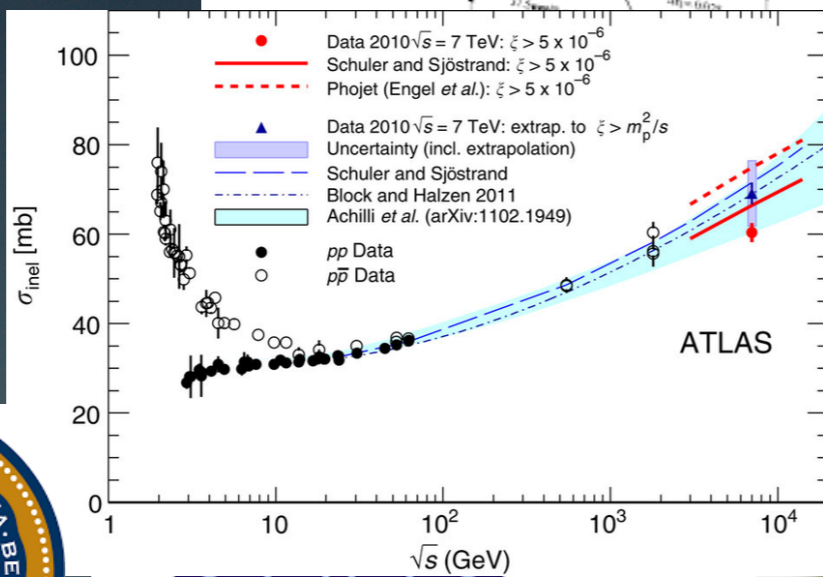
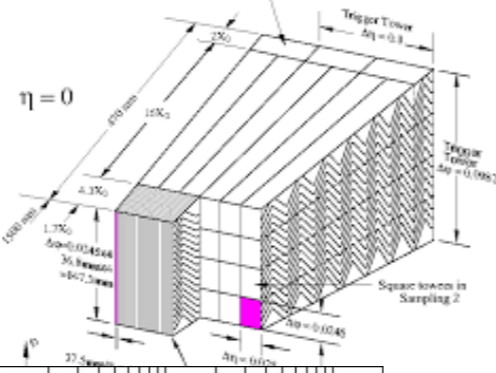
LABORATOIRE  
DE L'ACCÉLÉRATEUR  
LINÉAIRE



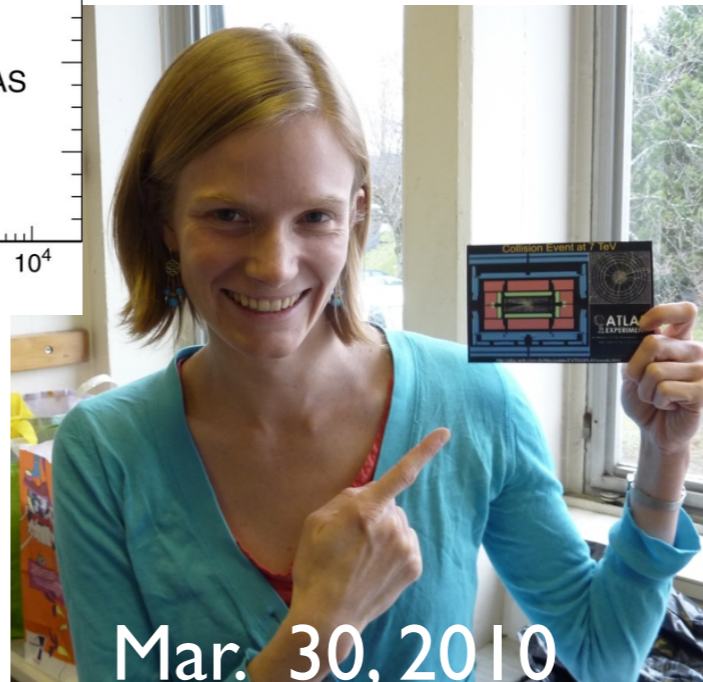
ATLAS  
EXPERIMENT



You are here

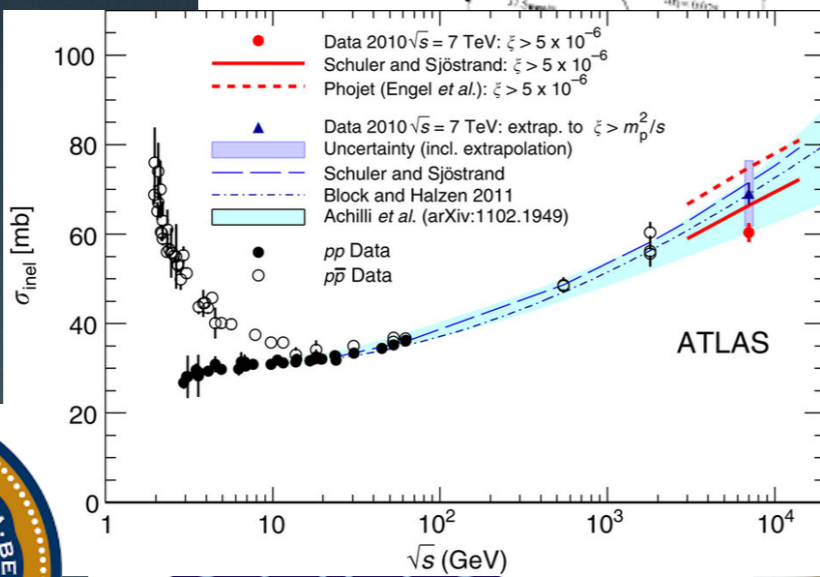
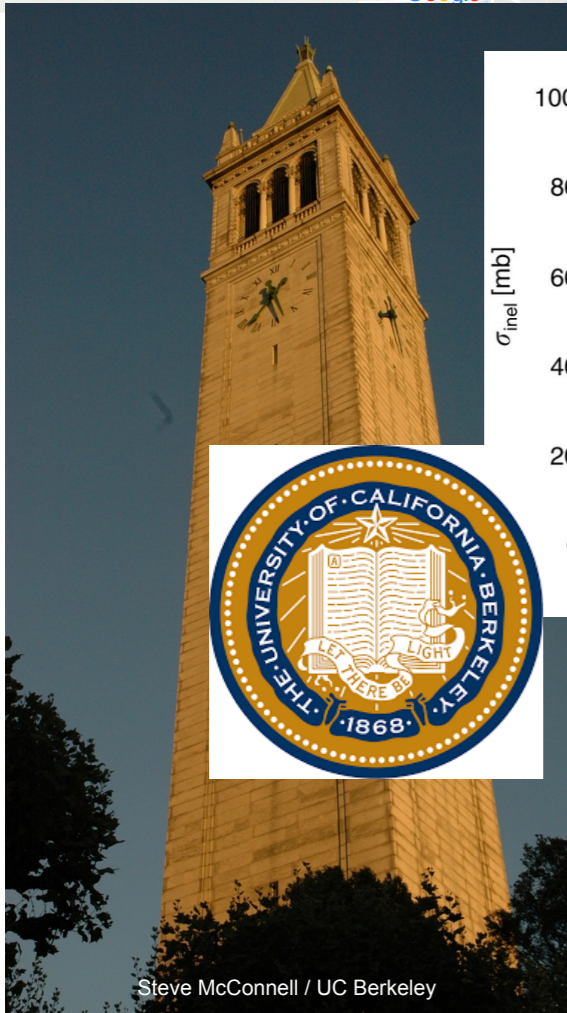
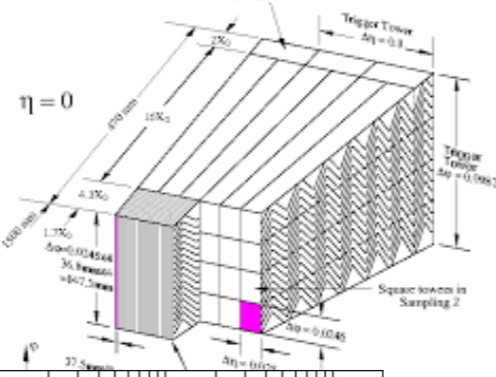
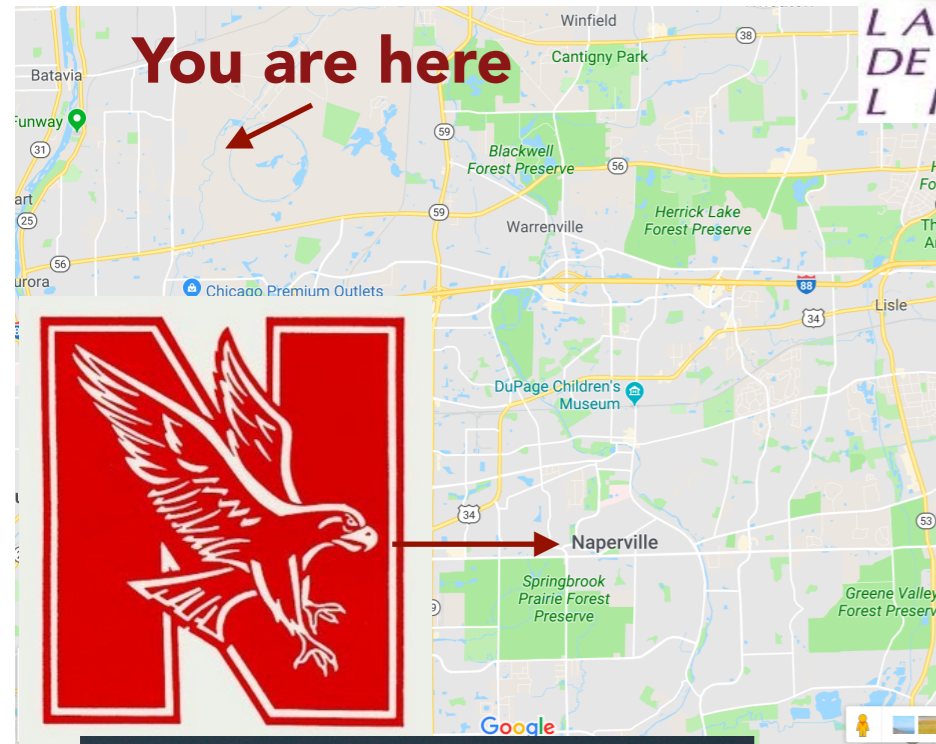
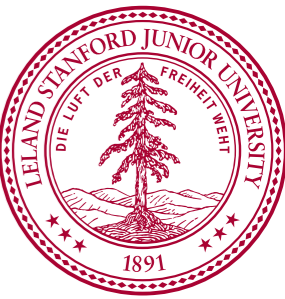


Steve McConnell / UC Berkeley



Mar. 30, 2010

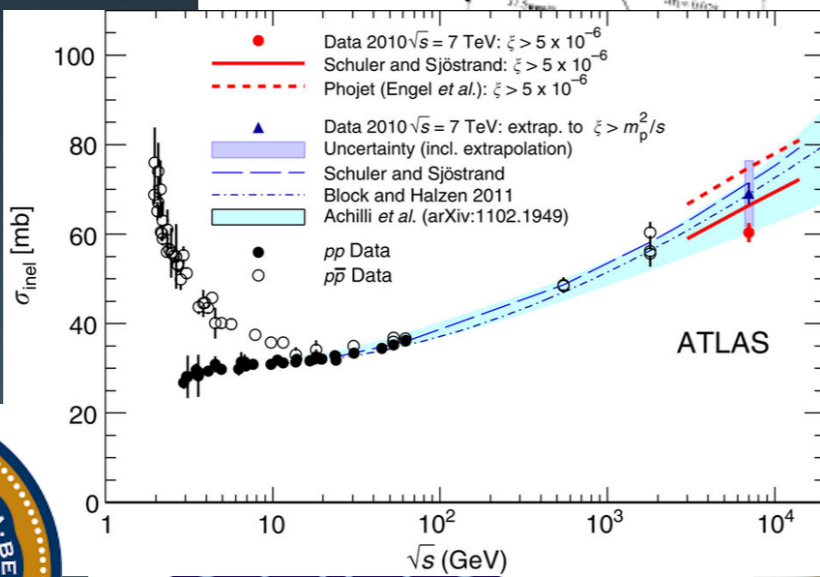
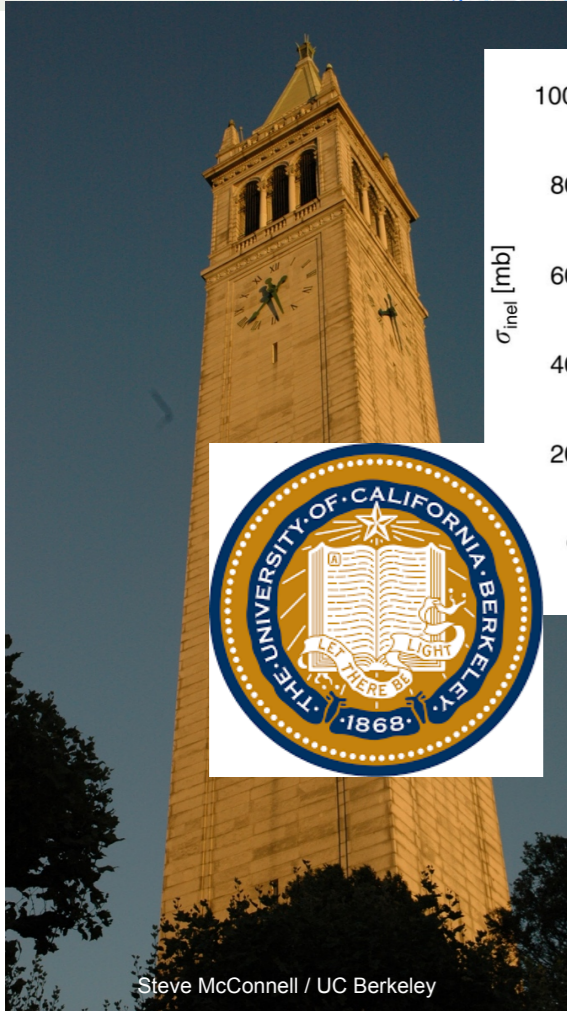
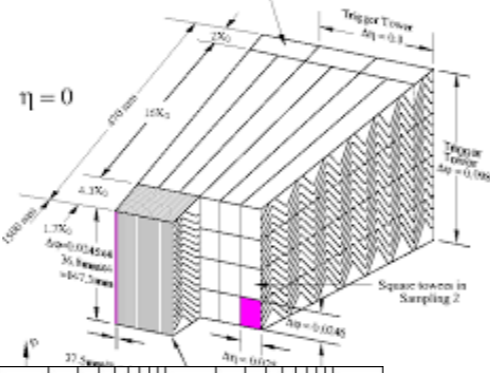
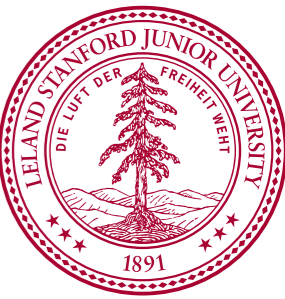
# HELLO!



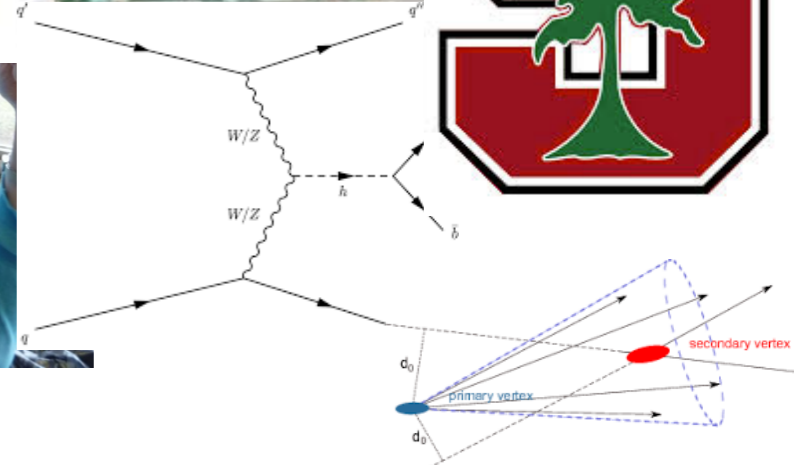
Mar. 30, 2010



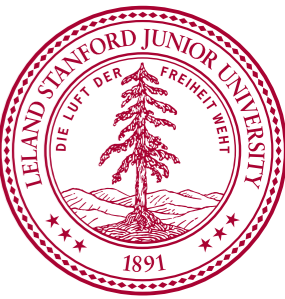
# HELLO!



Mar. 30, 2010



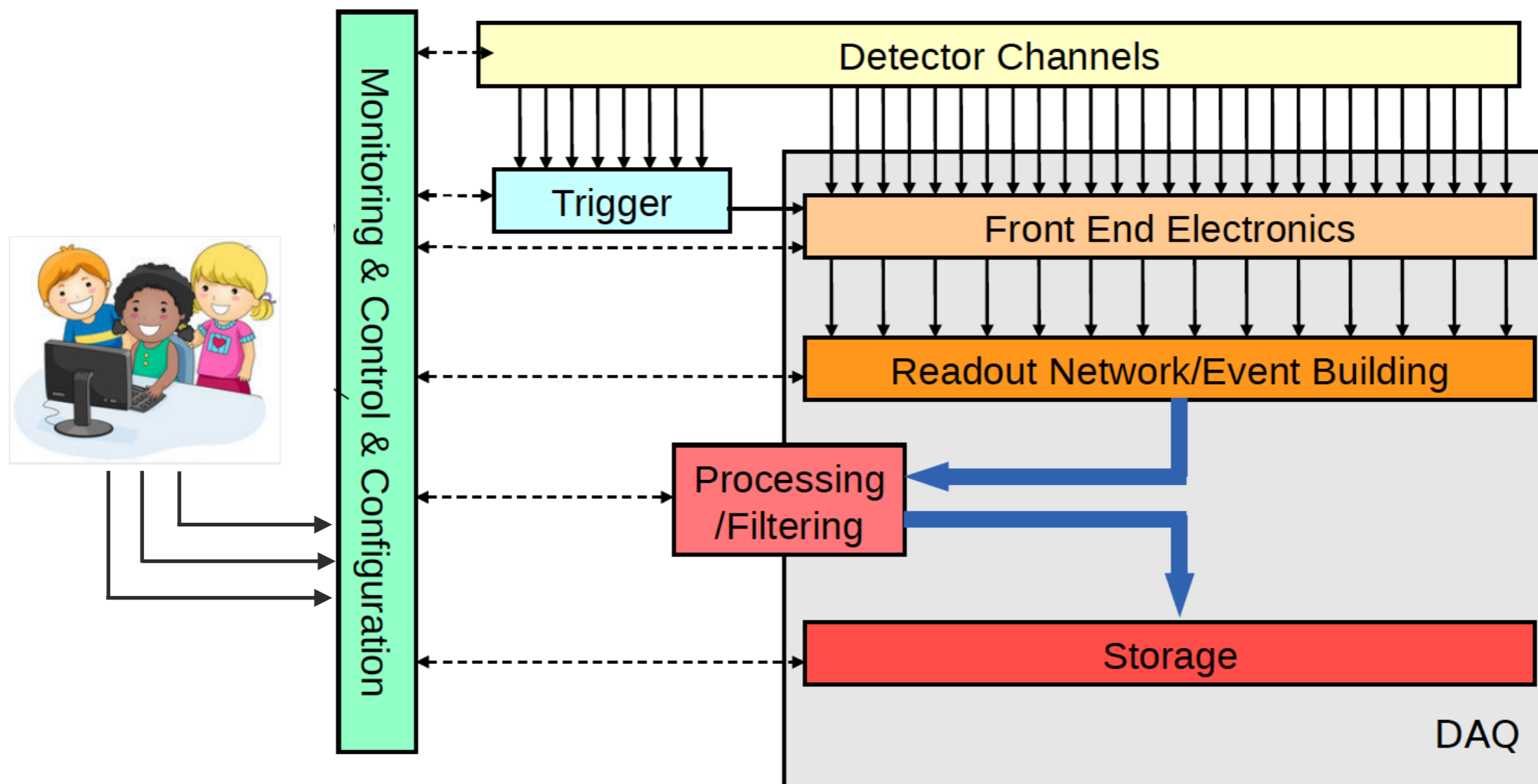
# BEFORE WE GET STARTED



- Will I learn how (insert experiment here) specifically triggers on (insert physics process here)?
  - No, my goal is to give you enough of a framework for understanding TDAQ generally such that you can apply your knowledge to specific situations
- Will I learn basic electronics?
  - Not really. We'll cover a few important concepts, but take a class at your institution or attend the [ISOTDAQ](#) or [EDIT](#) schools for more information
- These lectures are inspired by [Andrea Negri](#), [Wainer Vandelli](#), and [Roberto Ferrari](#)'s lectures at ISOTDAQ and CERN as well as [Wesley Smith](#)'s previous HCPSS lectures.
- These are a little ATLAS-heavy, but the concepts apply generally so please forgive me!

# TDAQ COMPONENTS

- Trigger & Data Acquisition comprise the systems for deciding which data to record (Trigger) and getting it off the detectors to storage for analysis (DAQ)

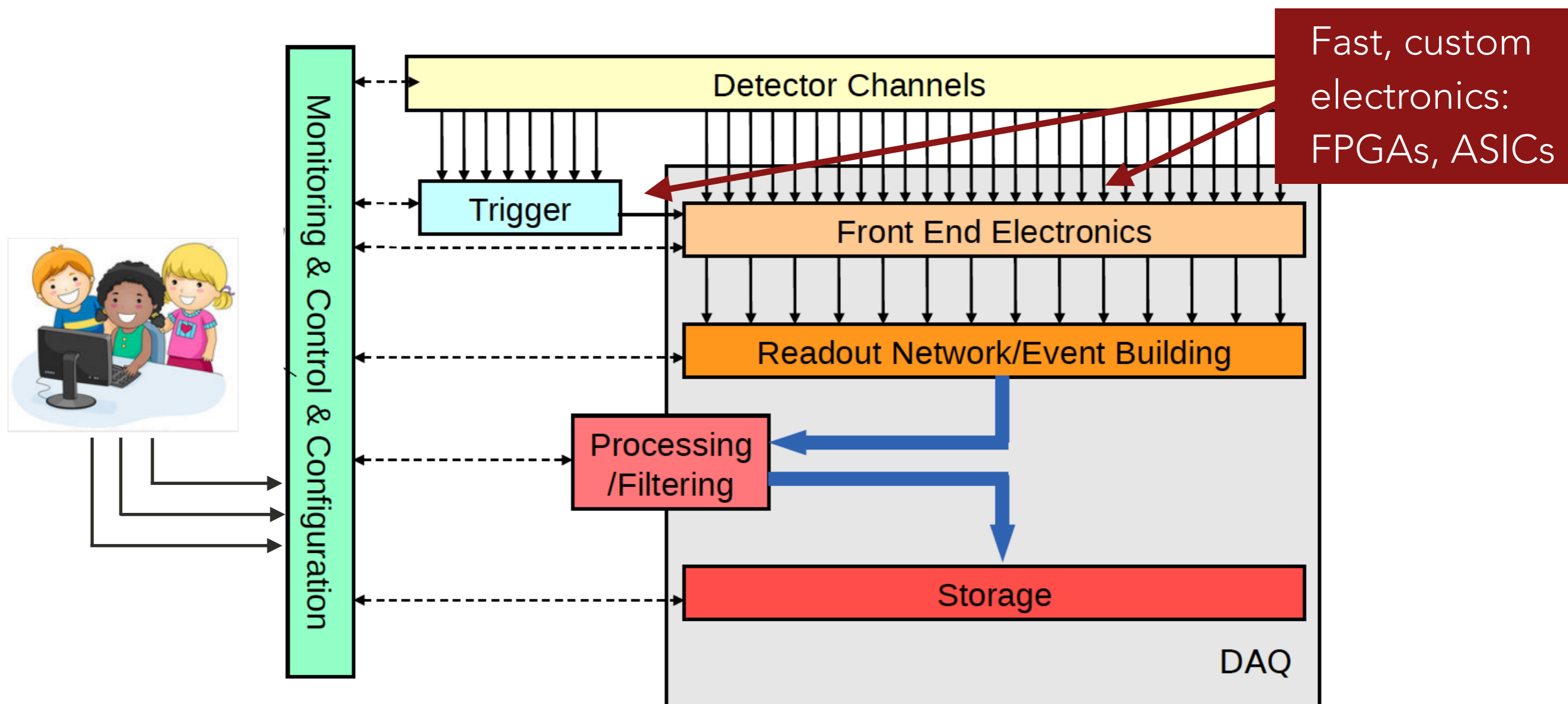




# TDAQ COMPONENTS

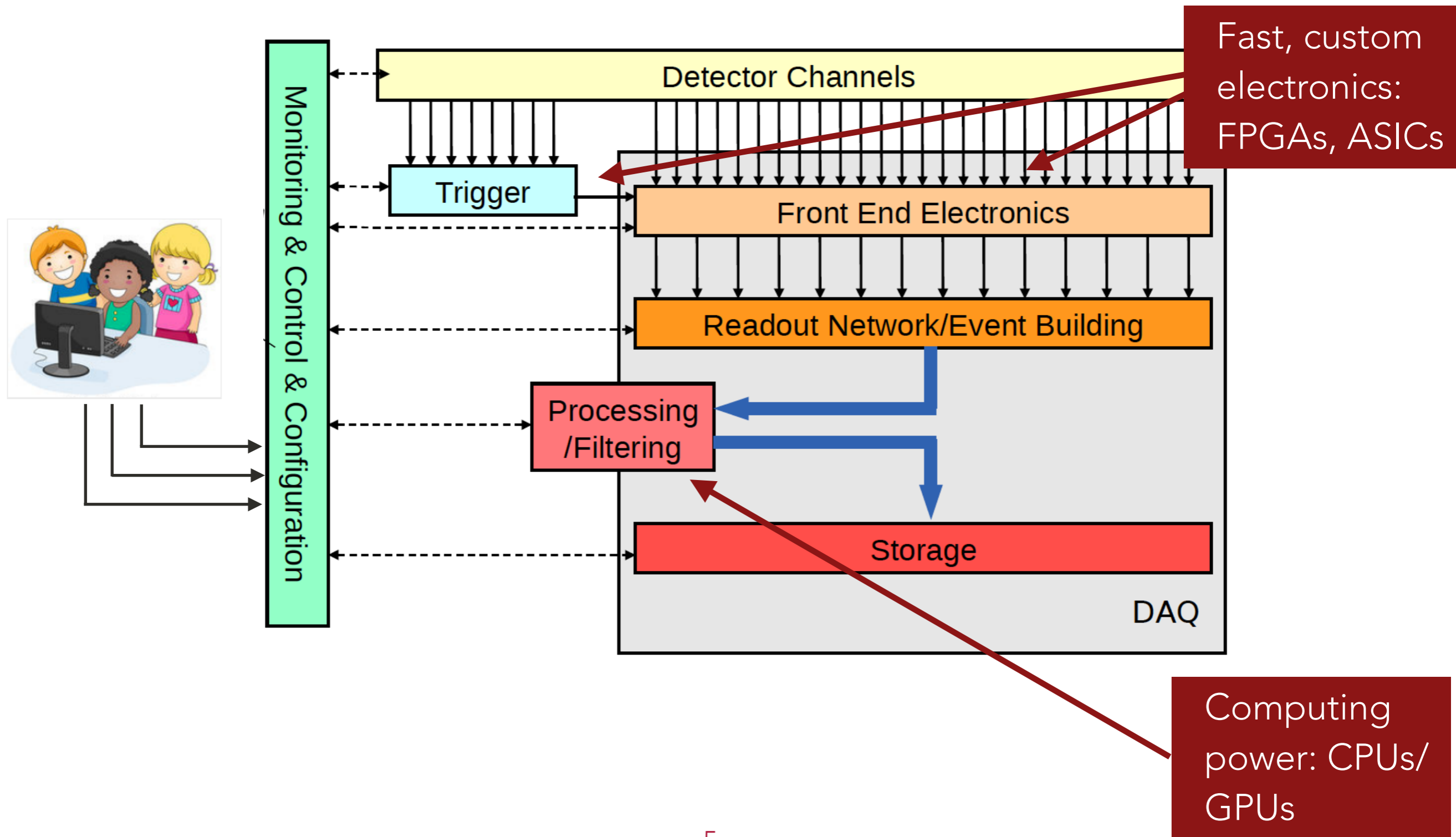


- Trigger & Data Acquisition comprise the systems for deciding which data to record (Trigger) and getting it off the detectors to storage for analysis (DAQ)



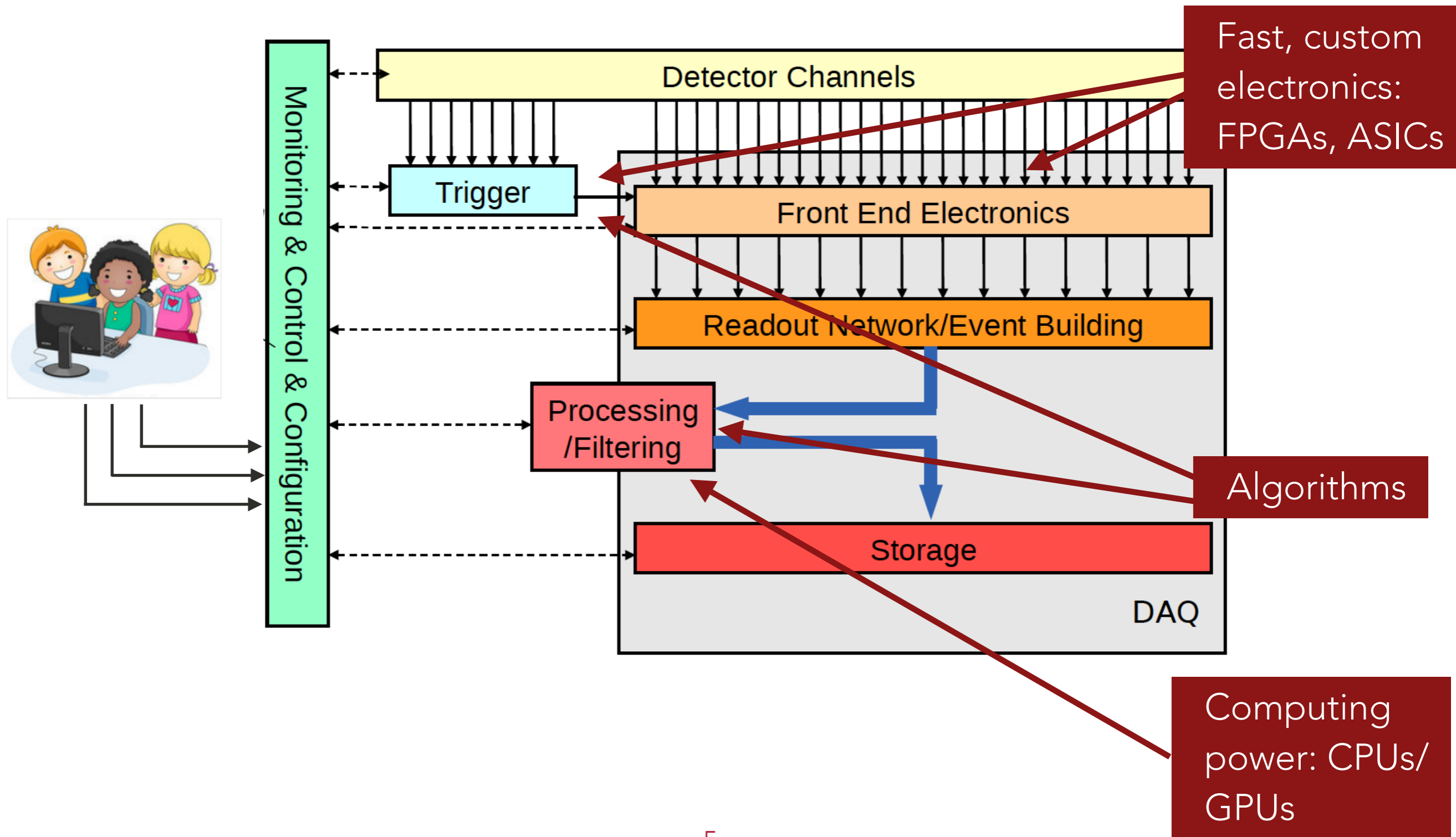
# TDAQ COMPONENTS

- Trigger & Data Acquisition comprise the systems for deciding which data to record (Trigger) and getting it off the detectors to storage for analysis (DAQ)



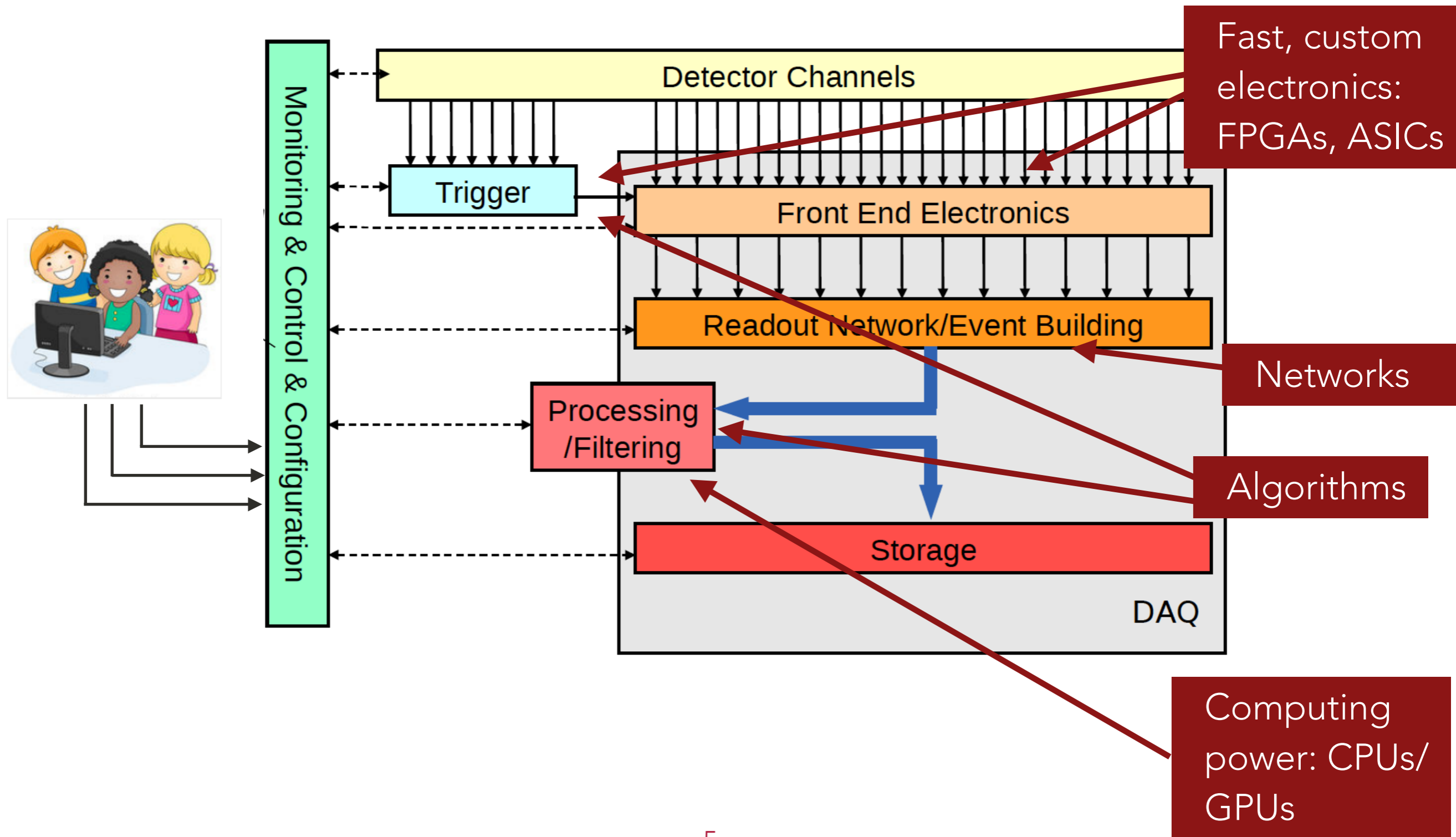
# TDAQ COMPONENTS

- Trigger & Data Acquisition comprise the systems for deciding which data to record (Trigger) and getting it off the detectors to storage for analysis (DAQ)



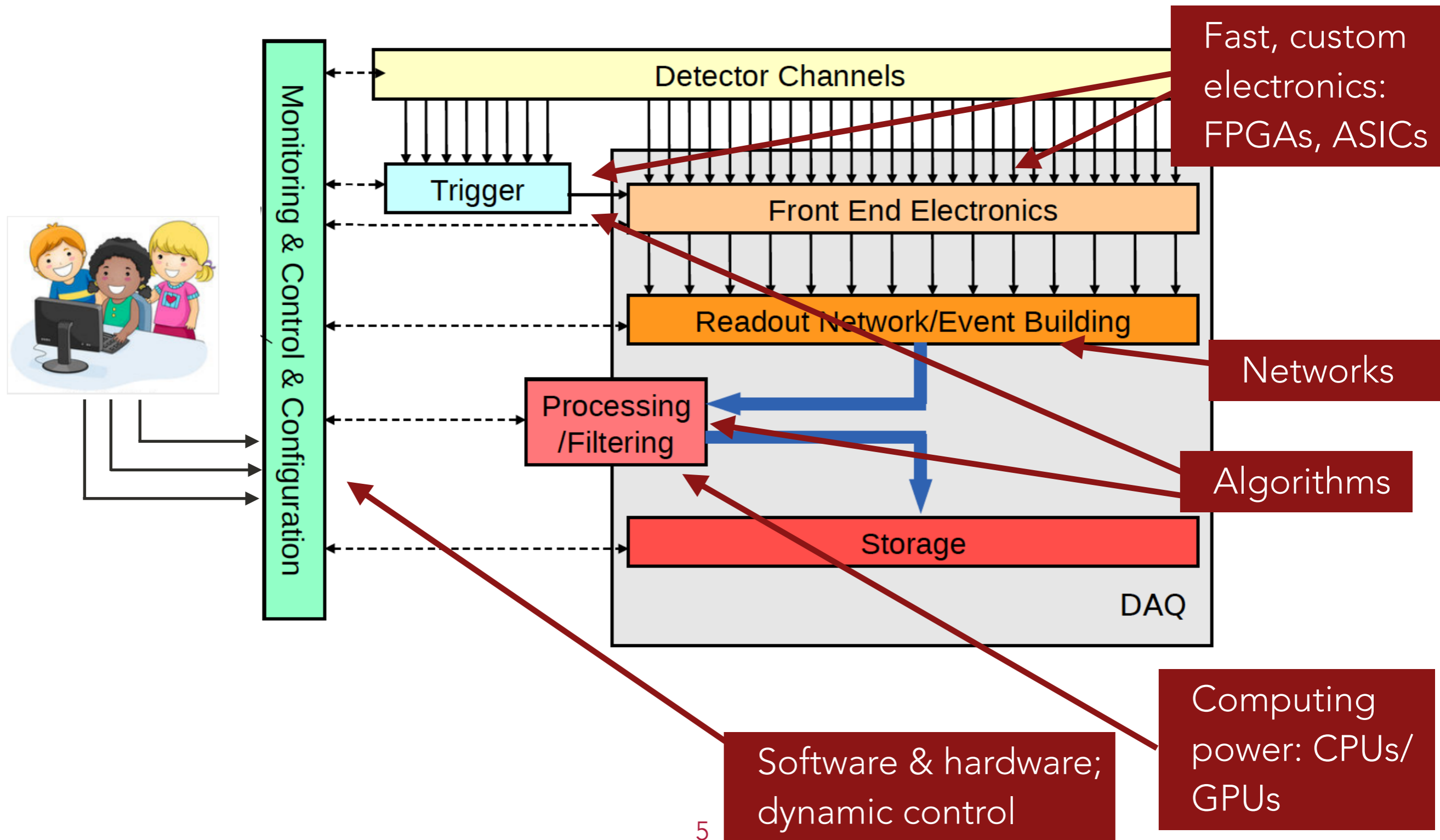
# TDAQ COMPONENTS

- Trigger & Data Acquisition comprise the systems for deciding which data to record (Trigger) and getting it off the detectors to storage for analysis (DAQ)



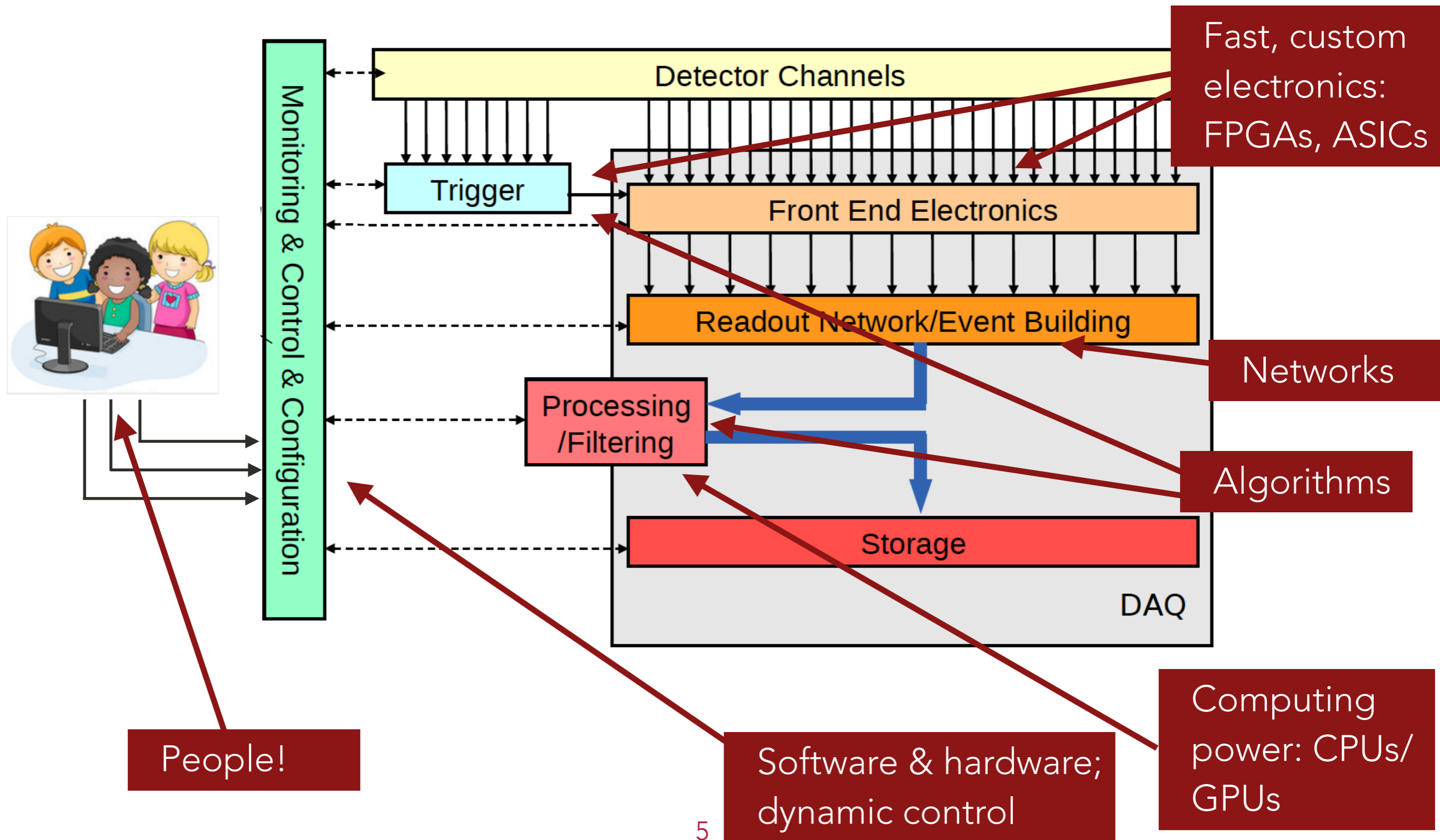
# TDAQ COMPONENTS

- Trigger & Data Acquisition comprise the systems for deciding which data to record (Trigger) and getting it off the detectors to storage for analysis (DAQ)

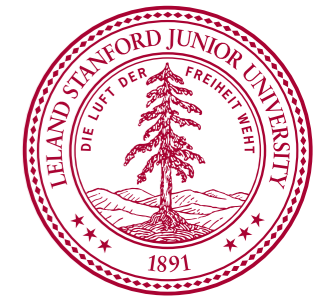


# TDAQ COMPONENTS

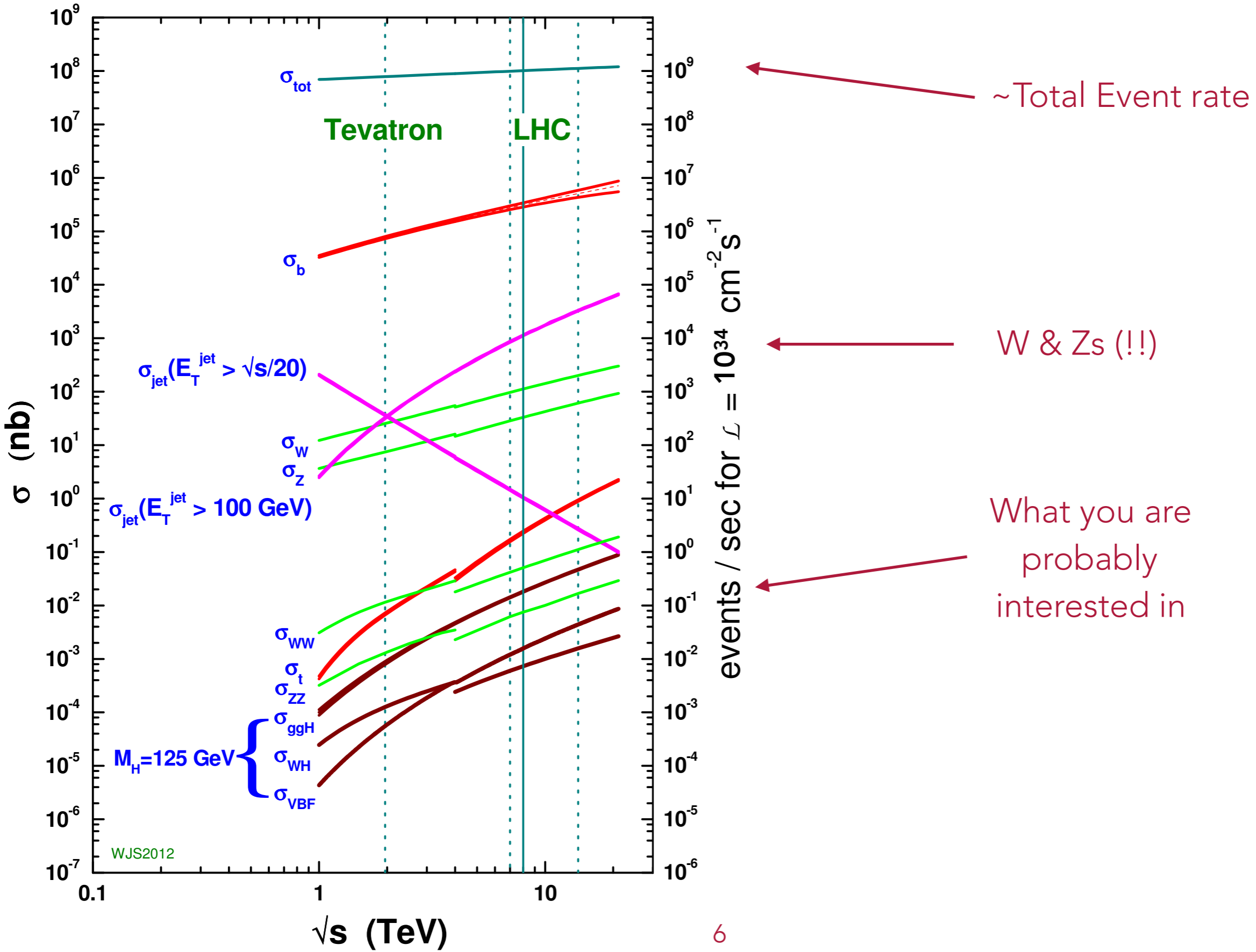
- Trigger & Data Acquisition comprise the systems for deciding which data to record (Trigger) and getting it off the detectors to storage for analysis (DAQ)

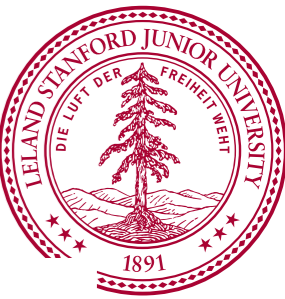


# THE CHALLENGE : PART 1



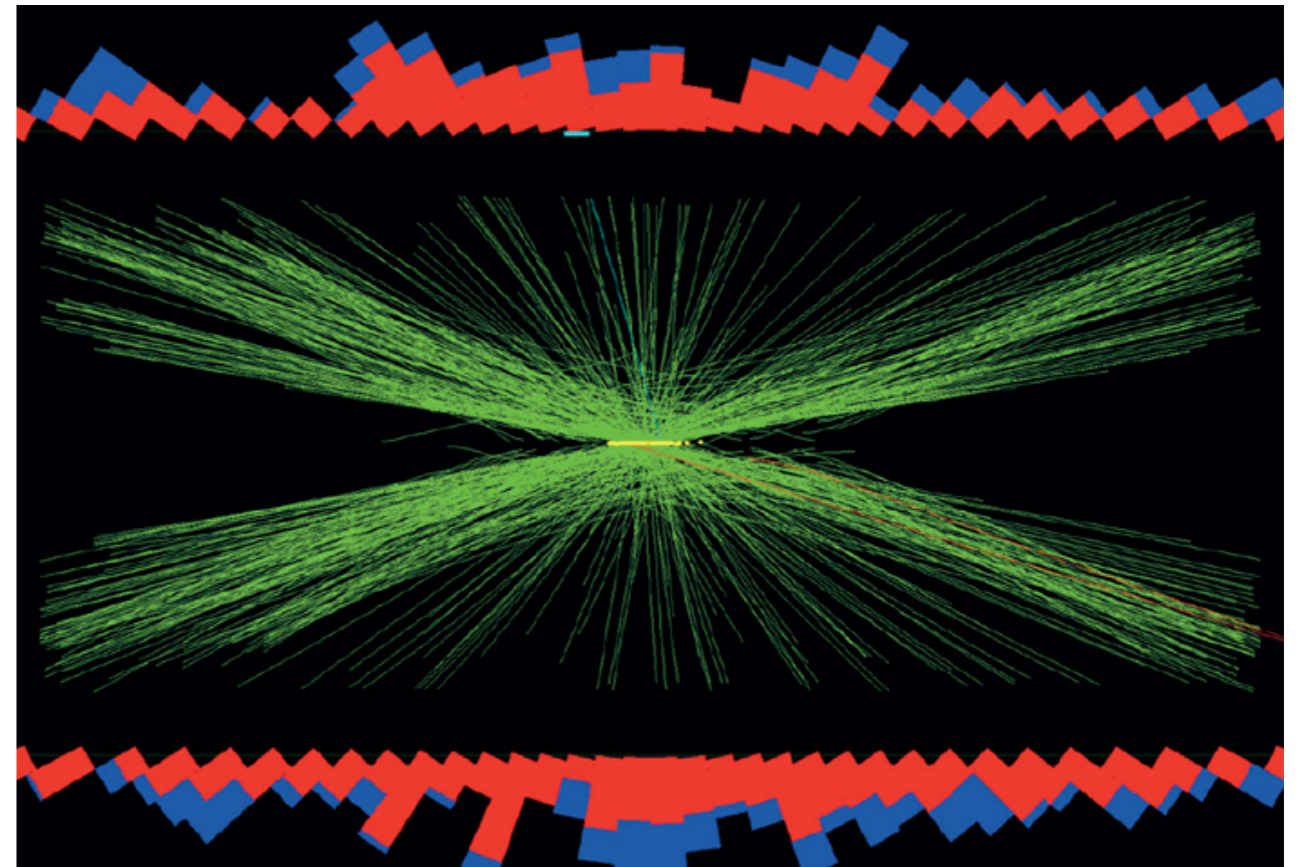
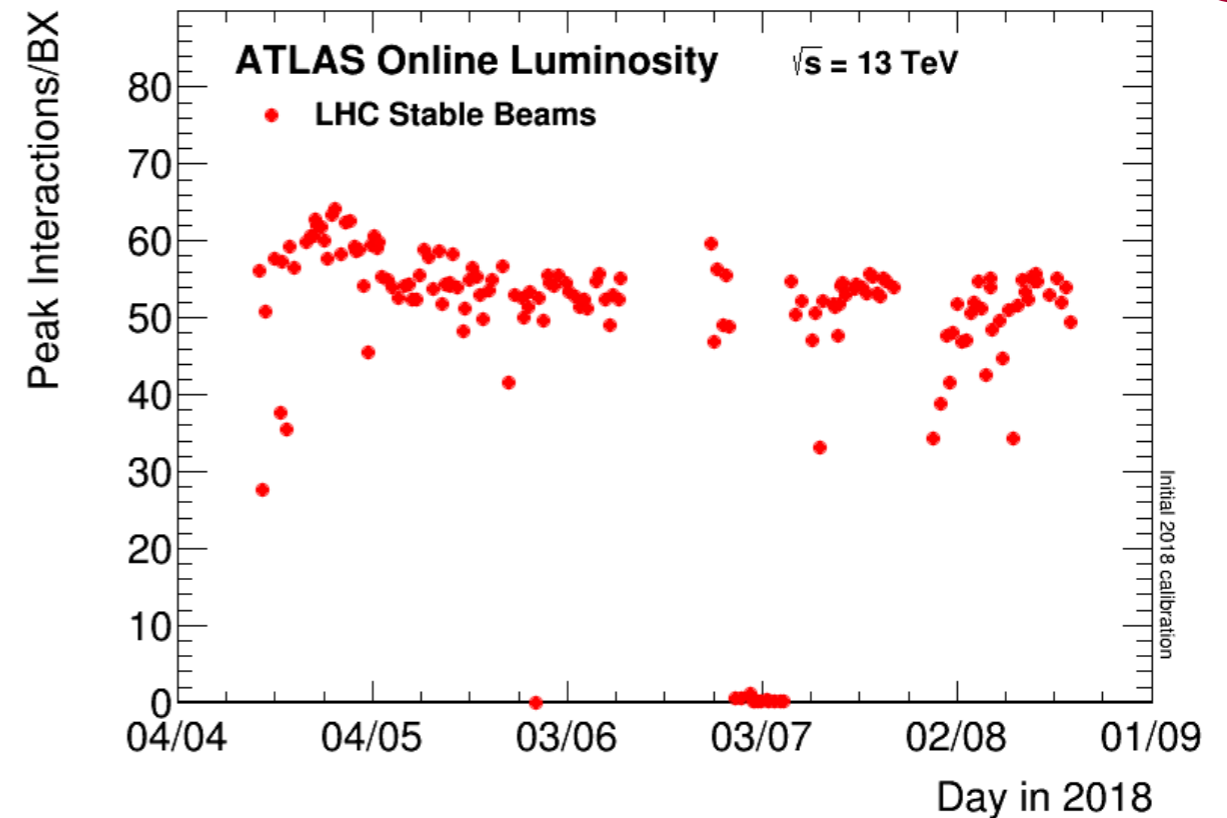
## proton - (anti)proton cross sections



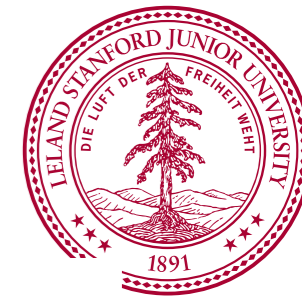


# THE CHALLENGE : PART 2

- A lot of things are going on at the same time!
- Average 55 simultaneous pp collisions in 2018 (LHC design was 23)
- Collisions every  $\sim 25$ ns
- Come in bunches and trains

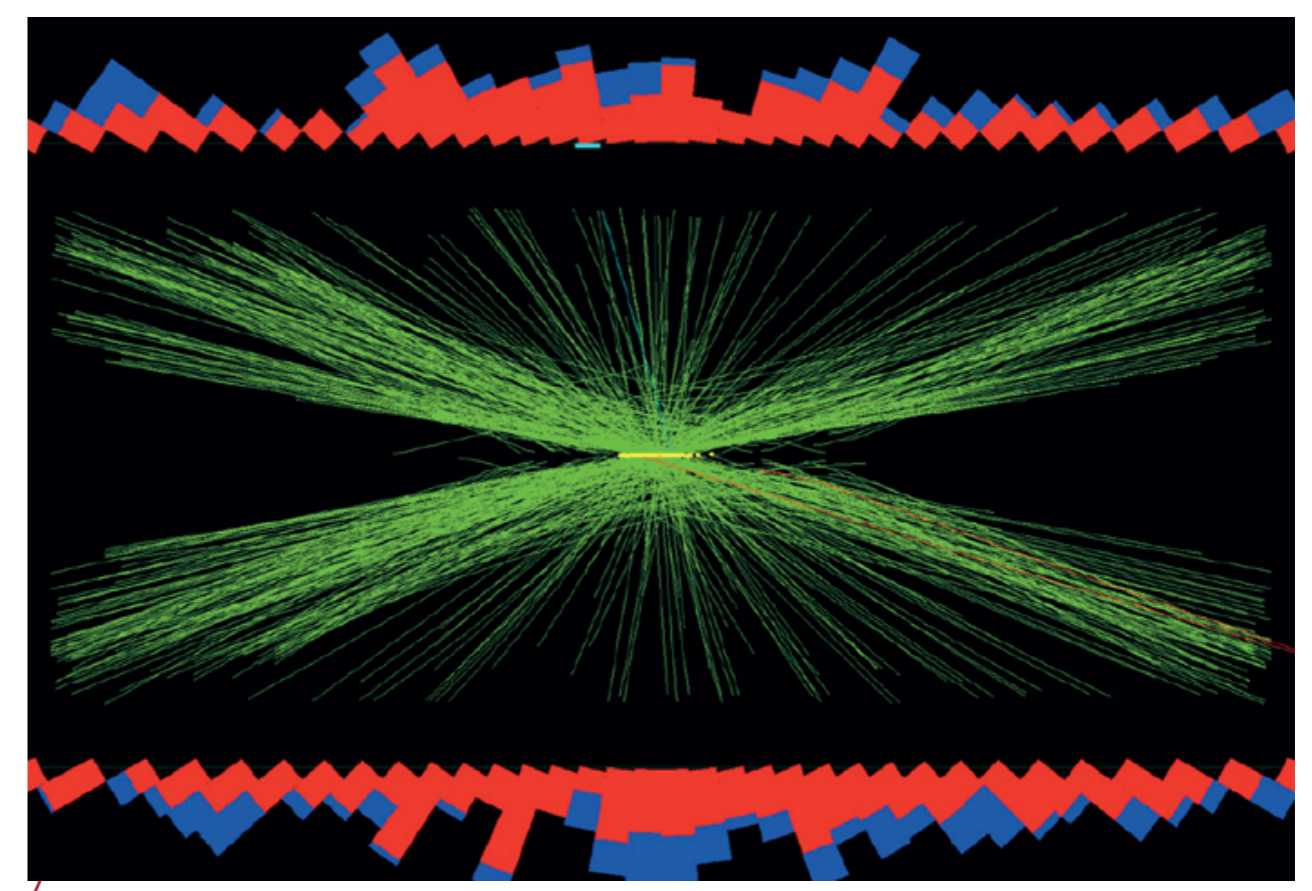
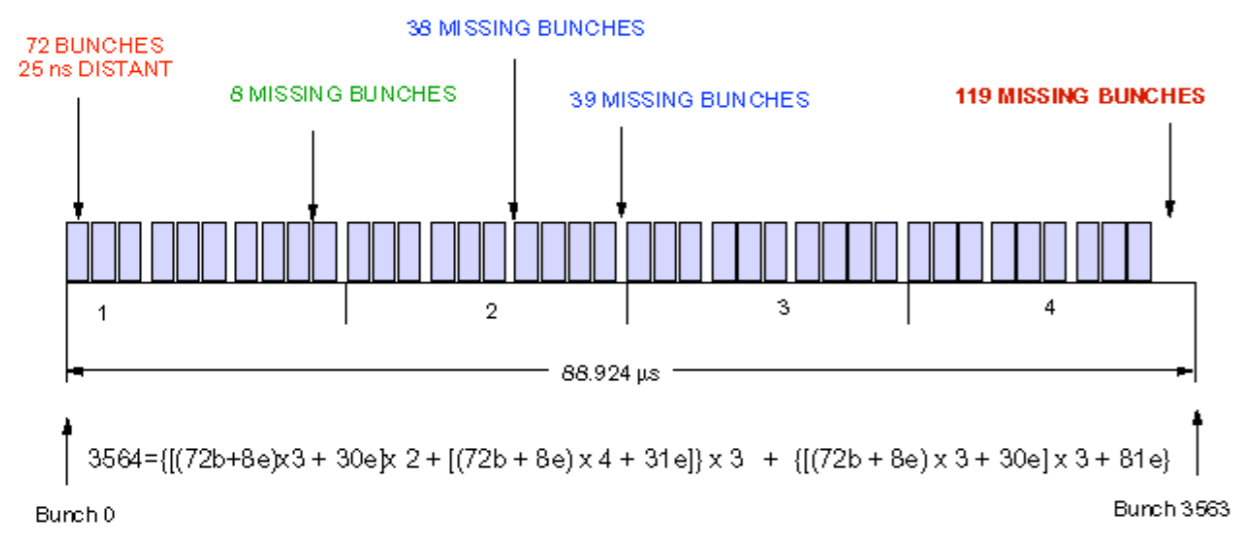
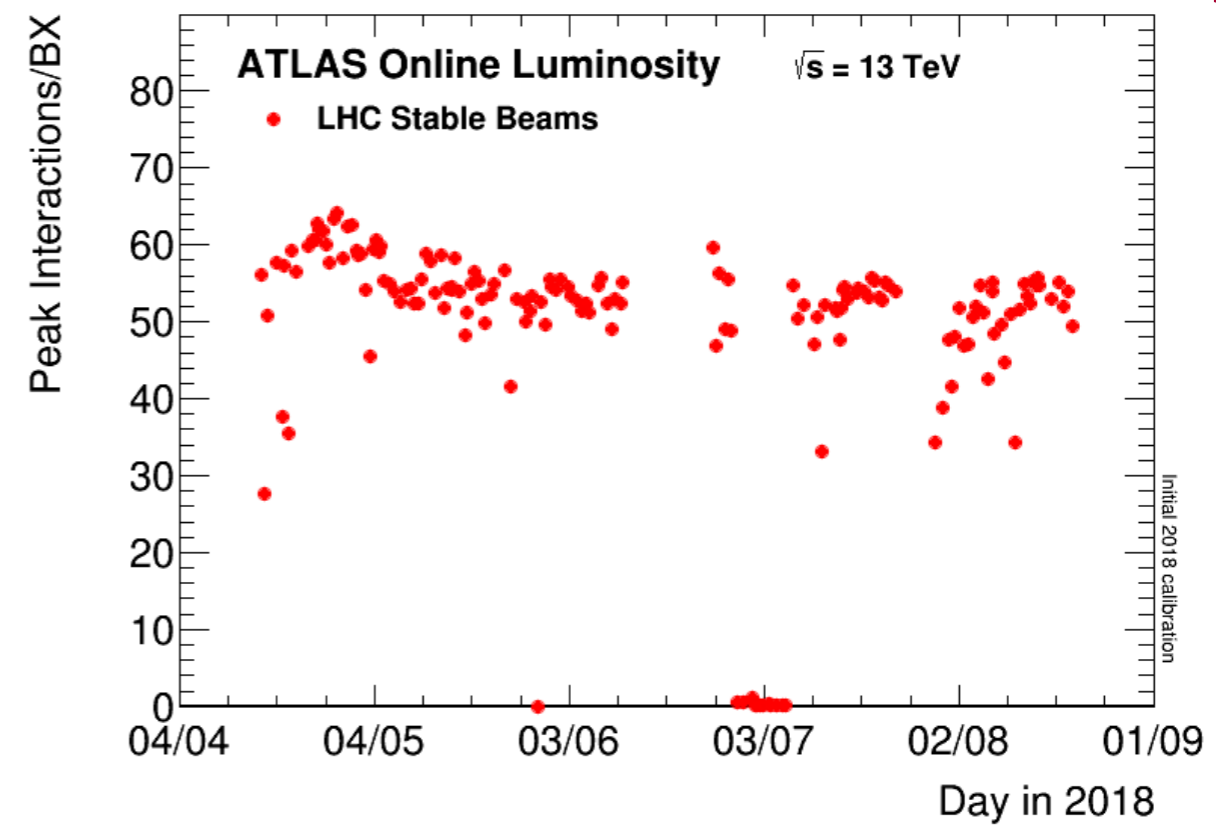






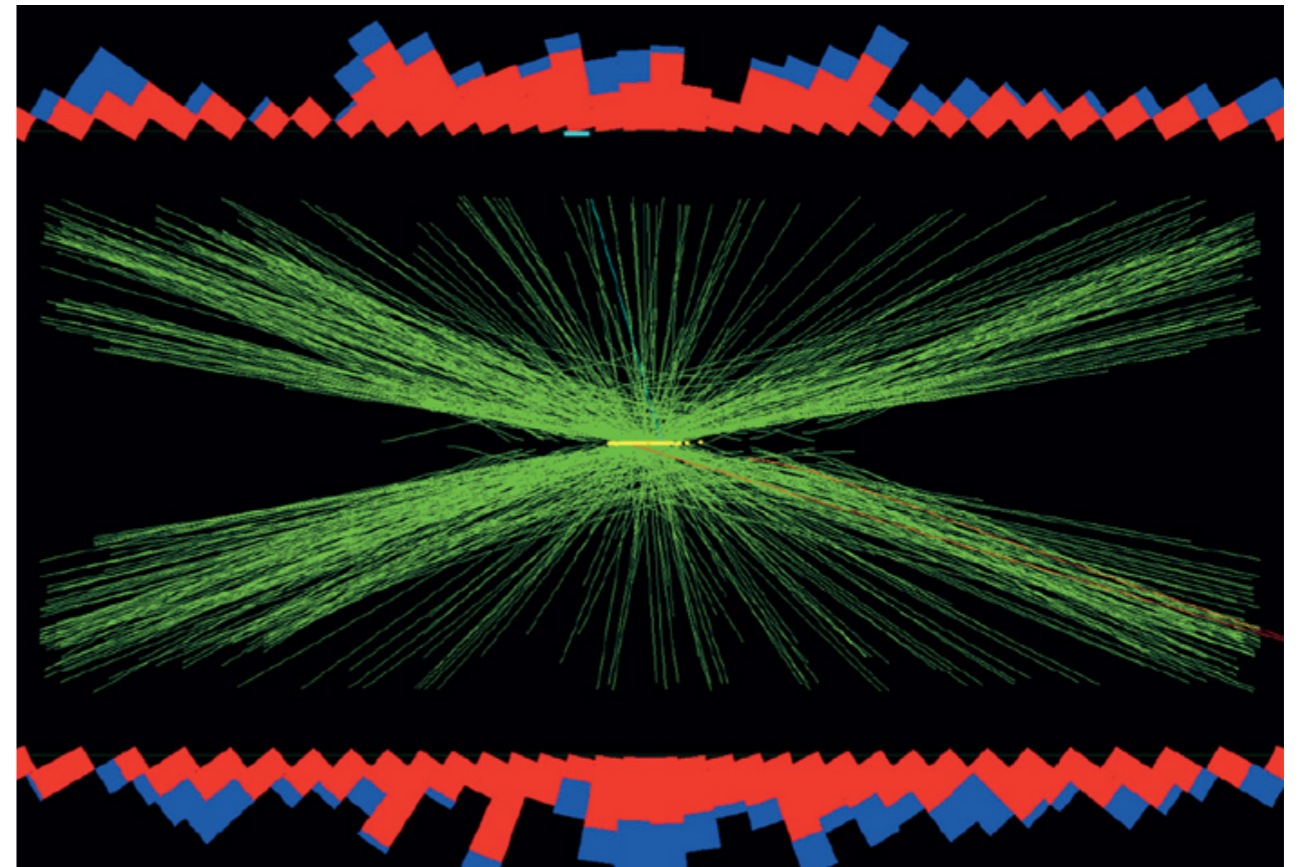
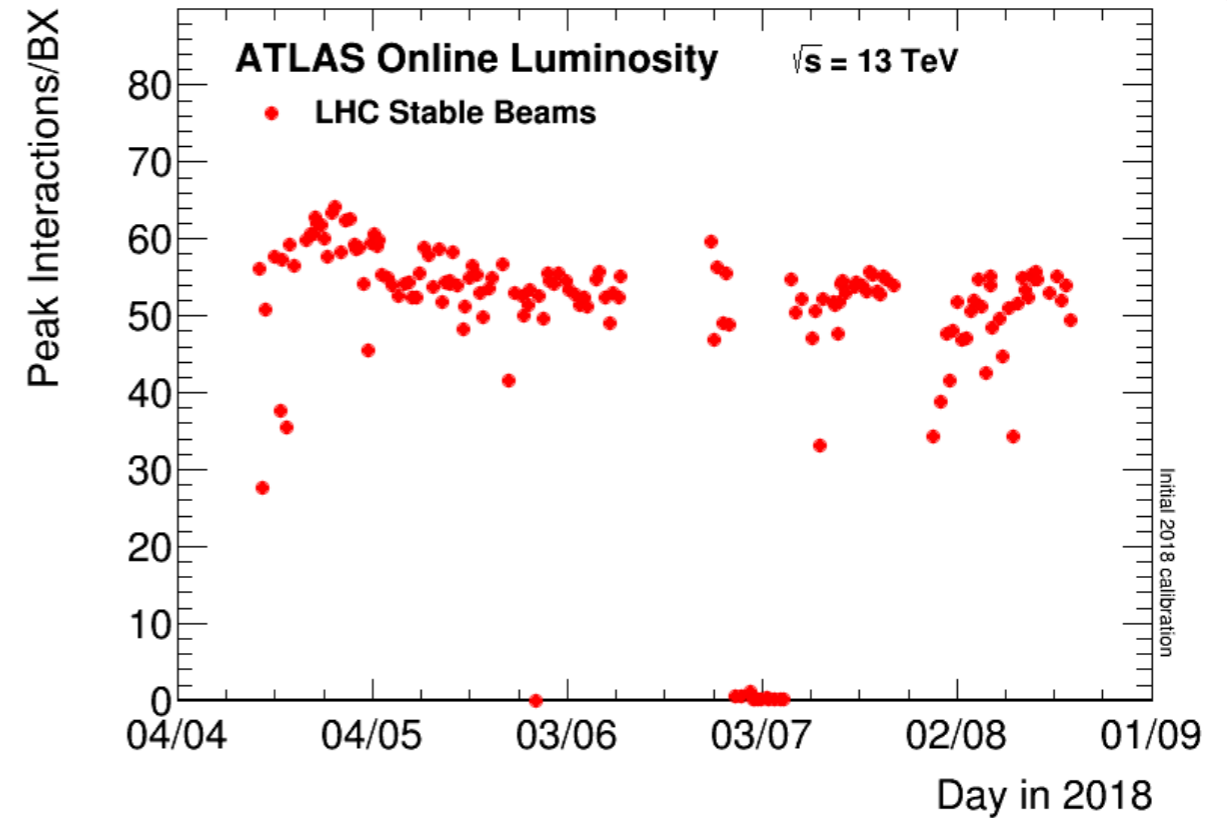
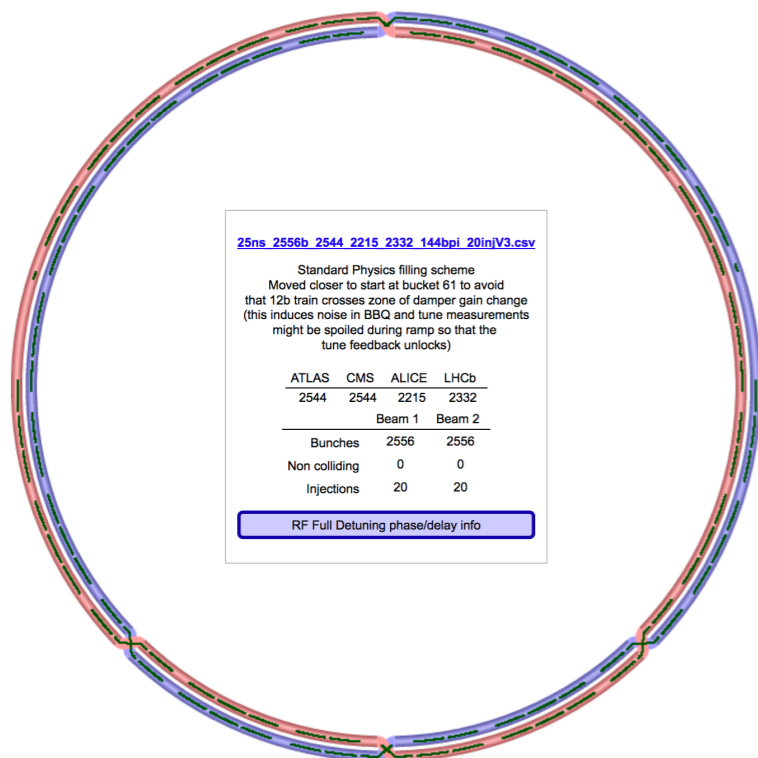
# THE CHALLENGE : PART 2

- A lot of things are going on at the same time!
- Average 55 simultaneous pp collisions in 2018 (LHC design was 23)
- Collisions every  $\sim 25\text{ns}$
- Come in bunches and trains



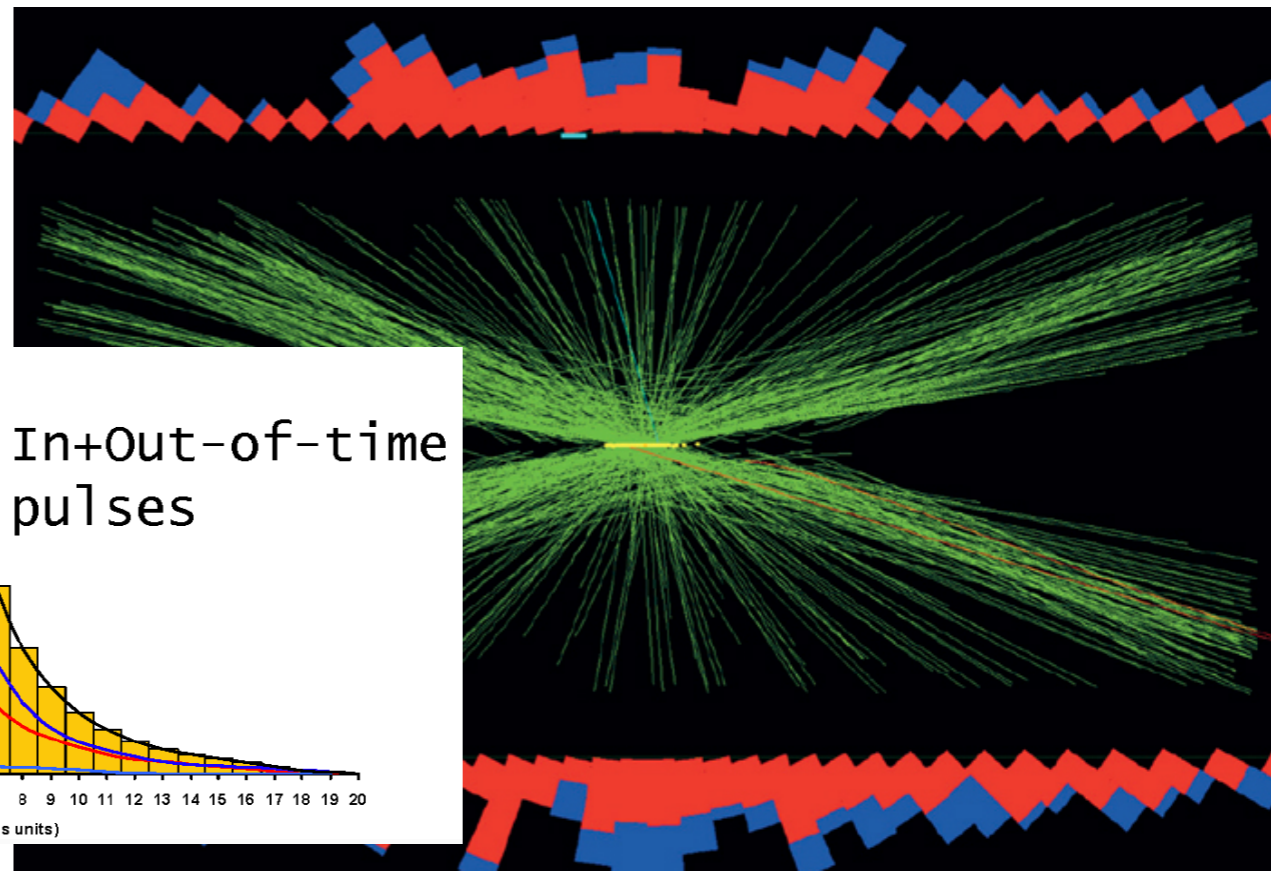
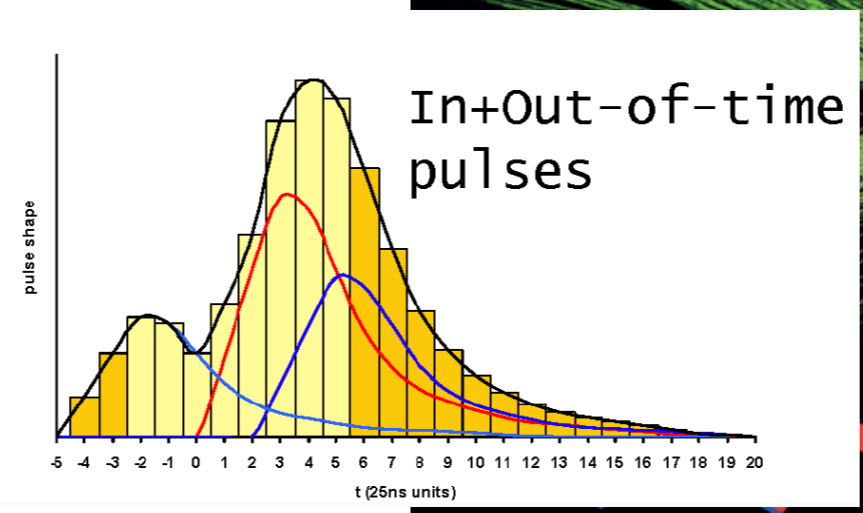
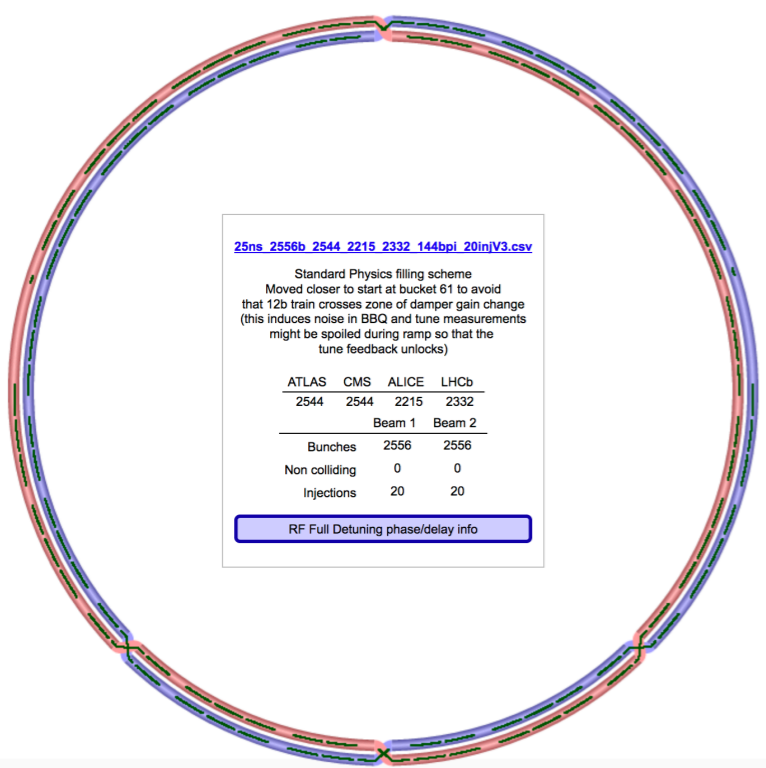
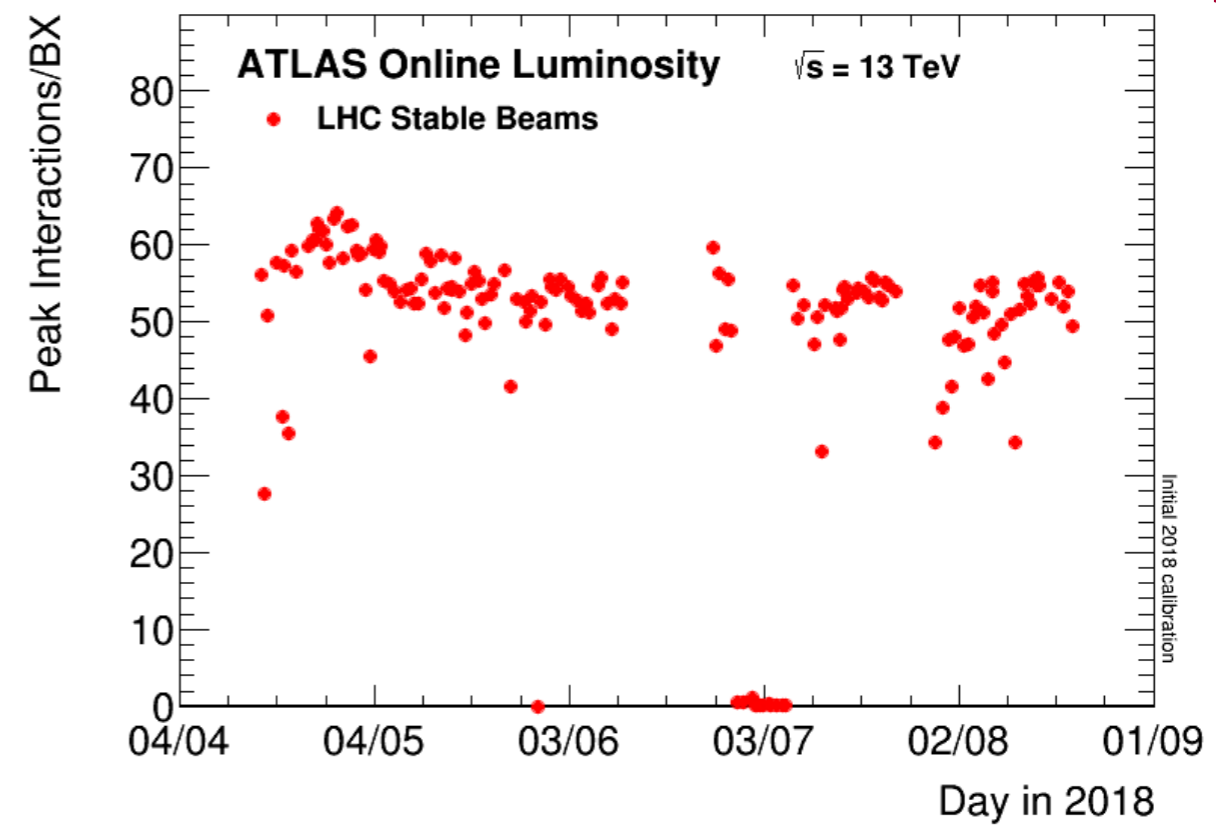
# THE CHALLENGE : PART 2

- A lot of things are going on at the same time!
- Average 55 simultaneous pp collisions in 2018 (LHC design was 23)
- Collisions every  $\sim 25\text{ns}$
- Come in bunches and trains

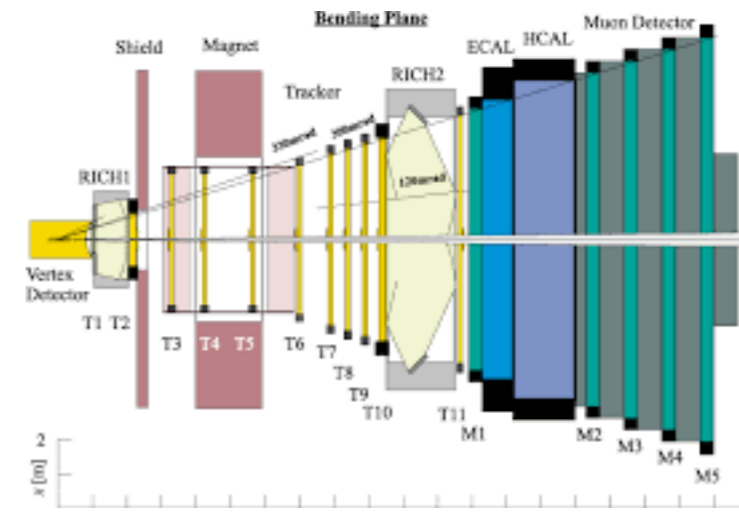
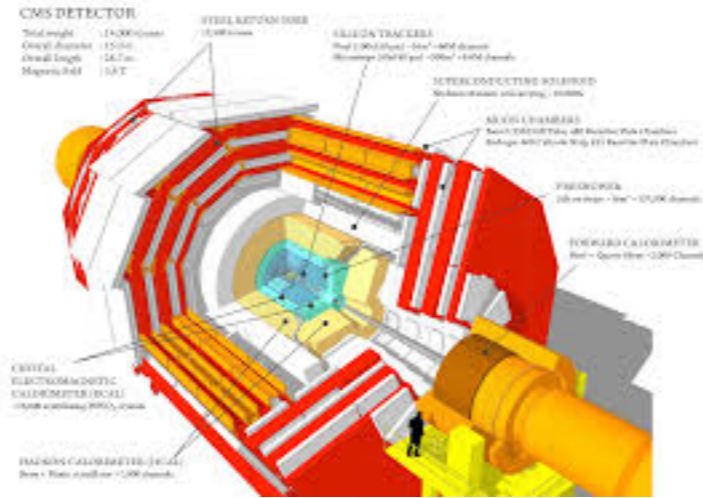
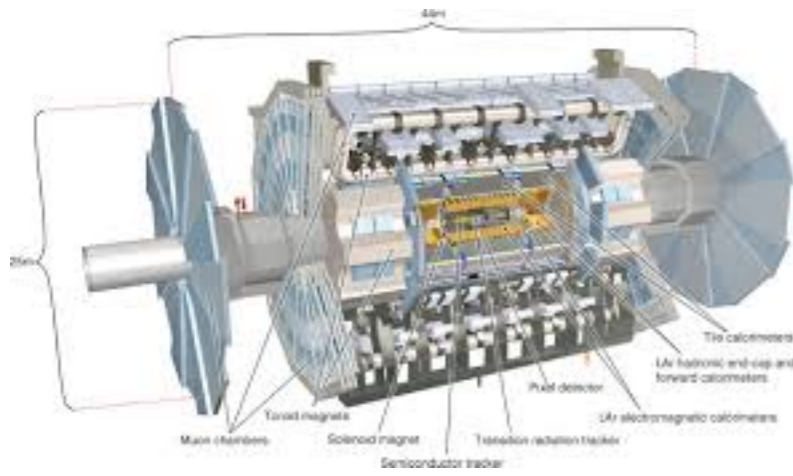
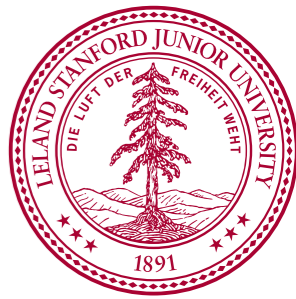


# THE CHALLENGE : PART 2

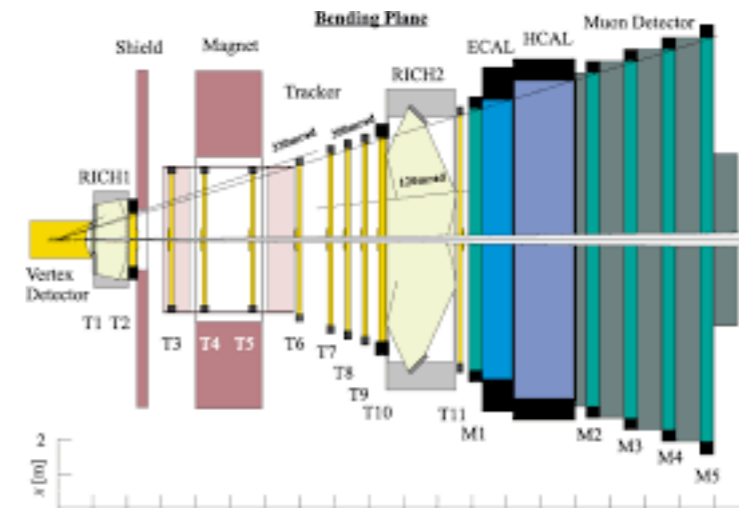
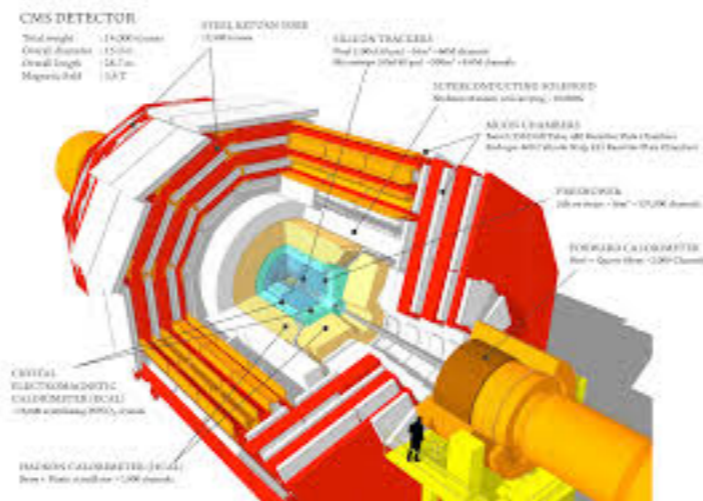
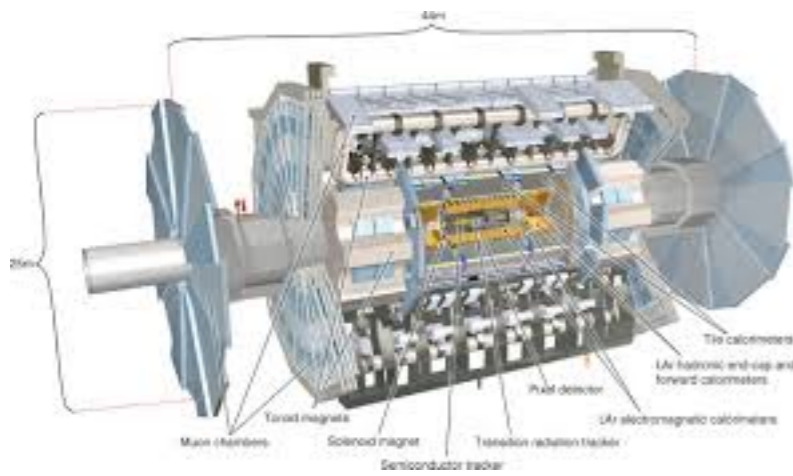
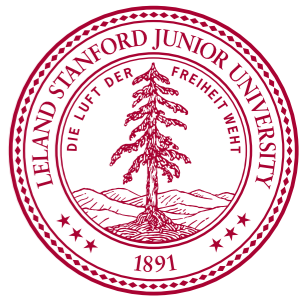
- A lot of things are going on at the same time!
- Average 55 simultaneous pp collisions in 2018 (LHC design was 23)
- Collisions every  $\sim 25\text{ns}$
- Come in bunches and trains



# THE CHALLENGE: PART 3

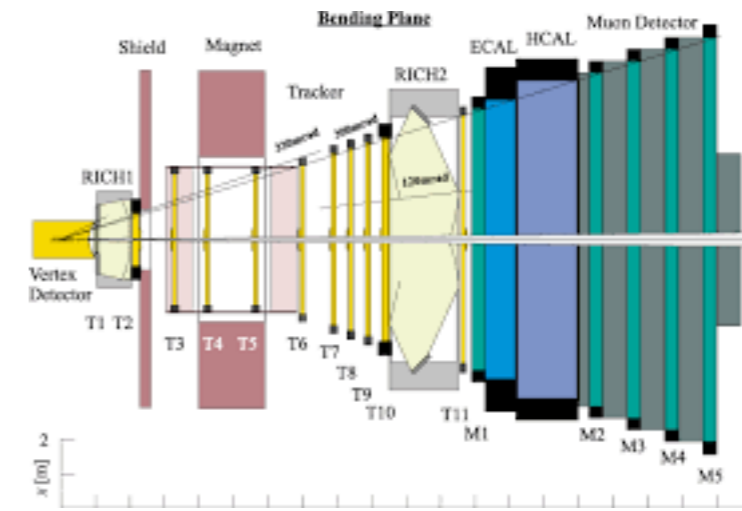
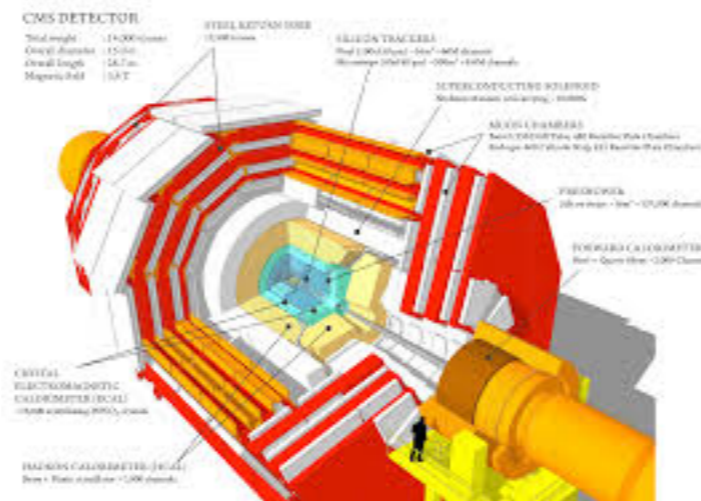
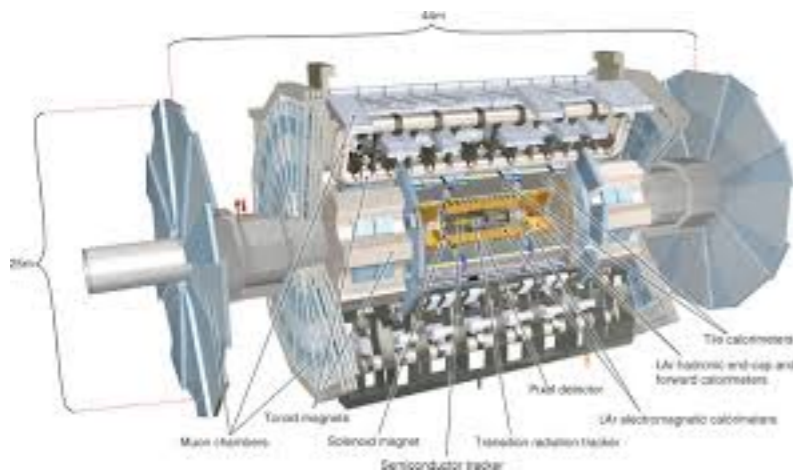
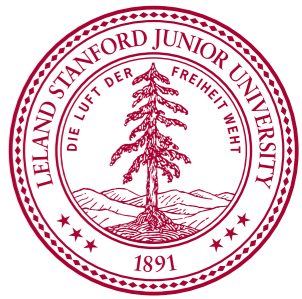


# THE CHALLENGE: PART 3



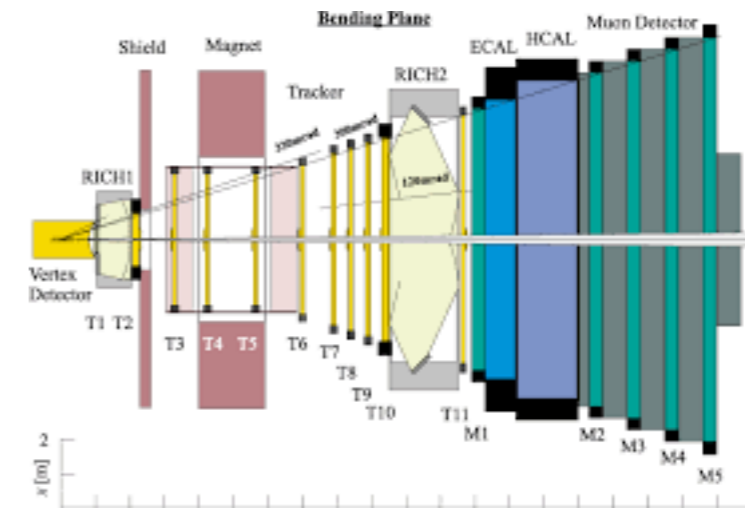
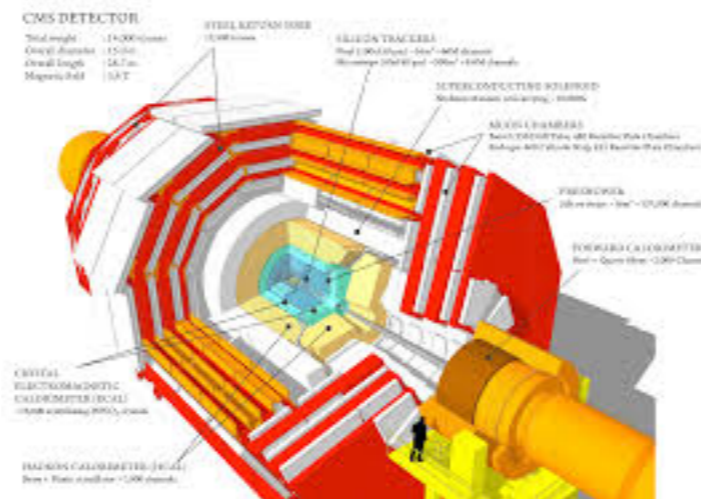
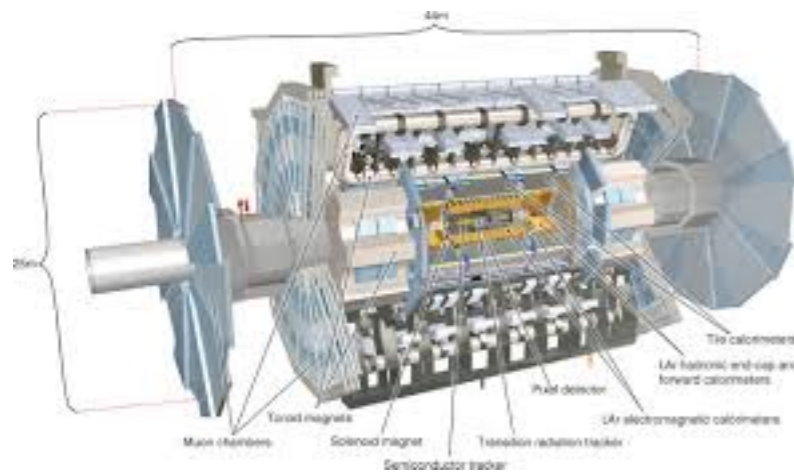
- Each collision produces a lot of data
  - Number of channels: ~100M (ATLAS/CMS); (1M LHCb)
  - Event size: 1 Mb (ATLAS/CMS) ; 100 kB (LHCb)

# THE CHALLENGE: PART 3



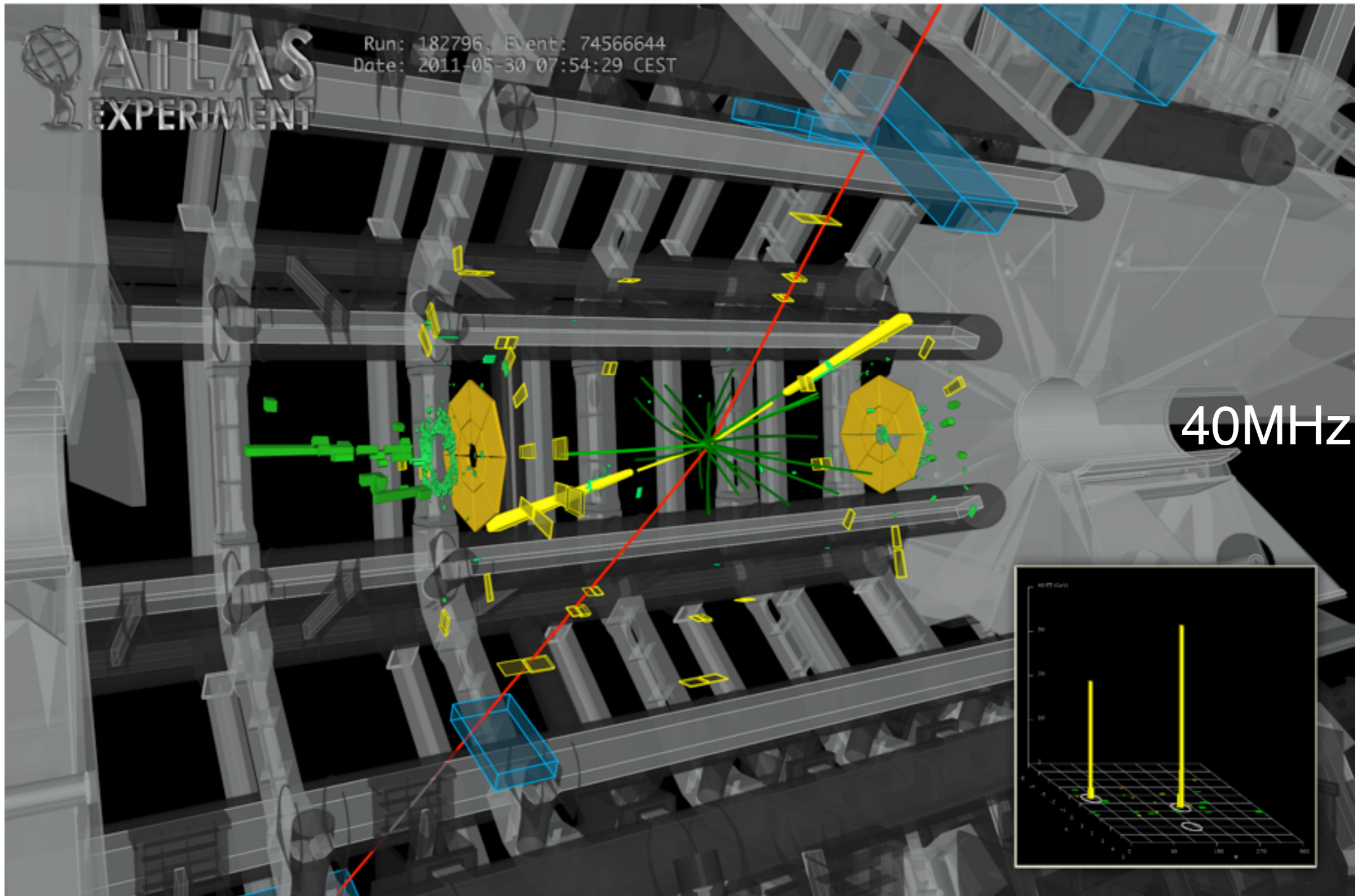
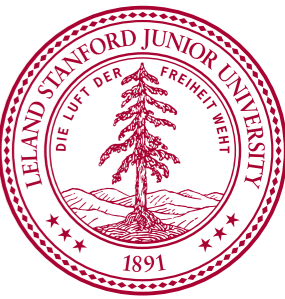
- Each collision produces a lot of data
  - Number of channels: ~100M (ATLAS/CMS); (1M LHCb)
  - Event size: 1 Mb (ATLAS/CMS) ; 100 kB (LHCb)
- Need to get that data to disk for analysis!
  - Can't write all of it — 150000 PB/year!

# THE CHALLENGE: PART 3



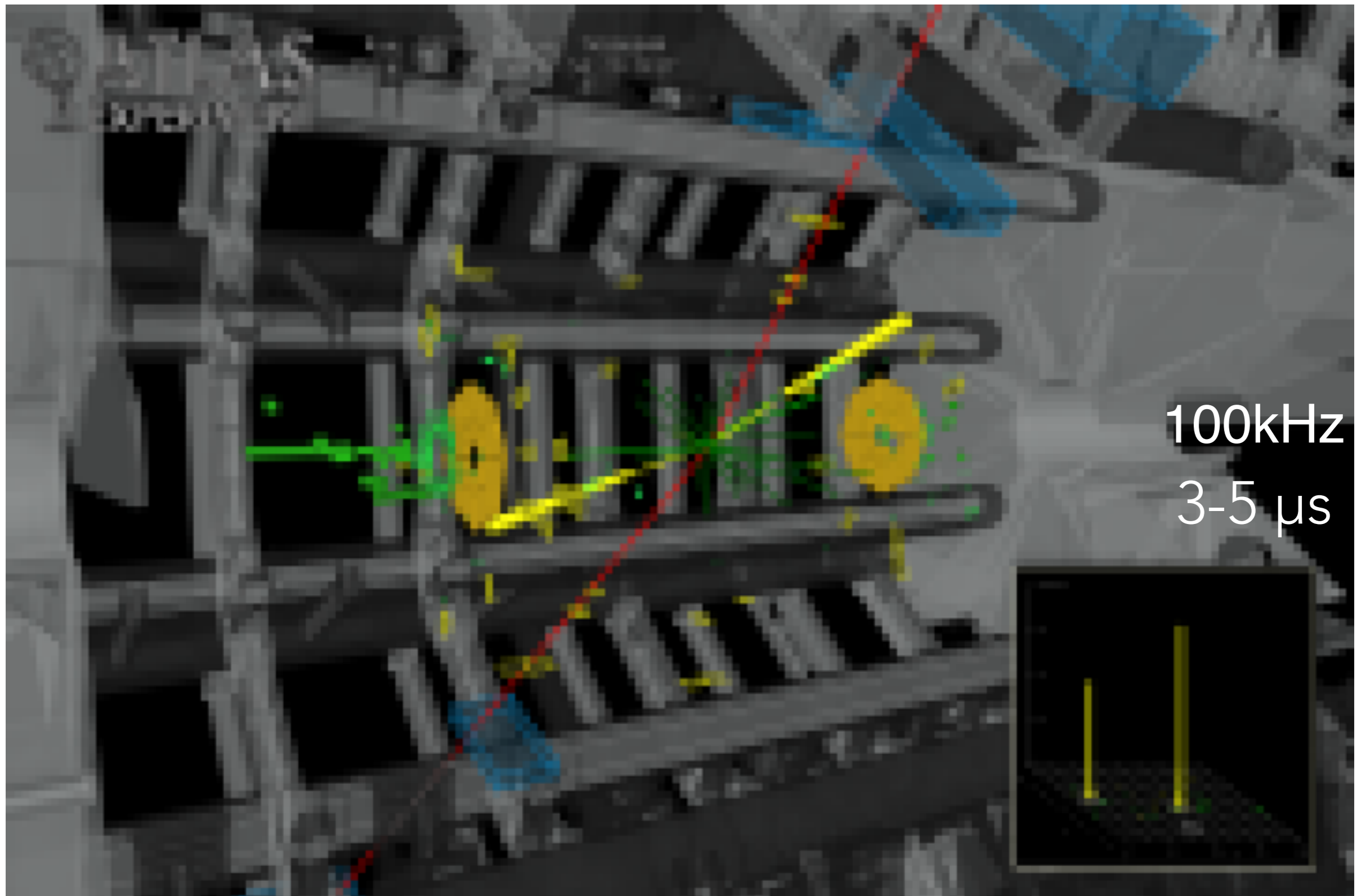
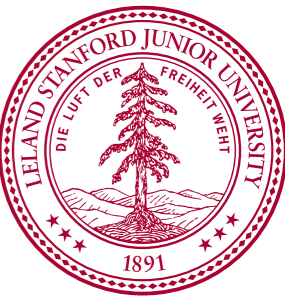
- Each collision produces a lot of data
  - Number of channels: ~100M (ATLAS/CMS); (1M LHCb)
  - Event size: 1 Mb (ATLAS/CMS) ; 100 kB (LHCb)
- Need to get that data to disk for analysis!
  - Can't write all of it — 150000 PB/year!
- There are a number of bottlenecks to contend with:
  - Local, on detector data storage — how much data can I store on my detector before shipping it out?
  - How fast can I get data off my detector — what are my readout bandwidth limitations?
  - How much data can I write to storage — can my output bandwidth, disk space and computing resources cope?

# RECORDING THE DATA: MULTI-STEP APPROACH

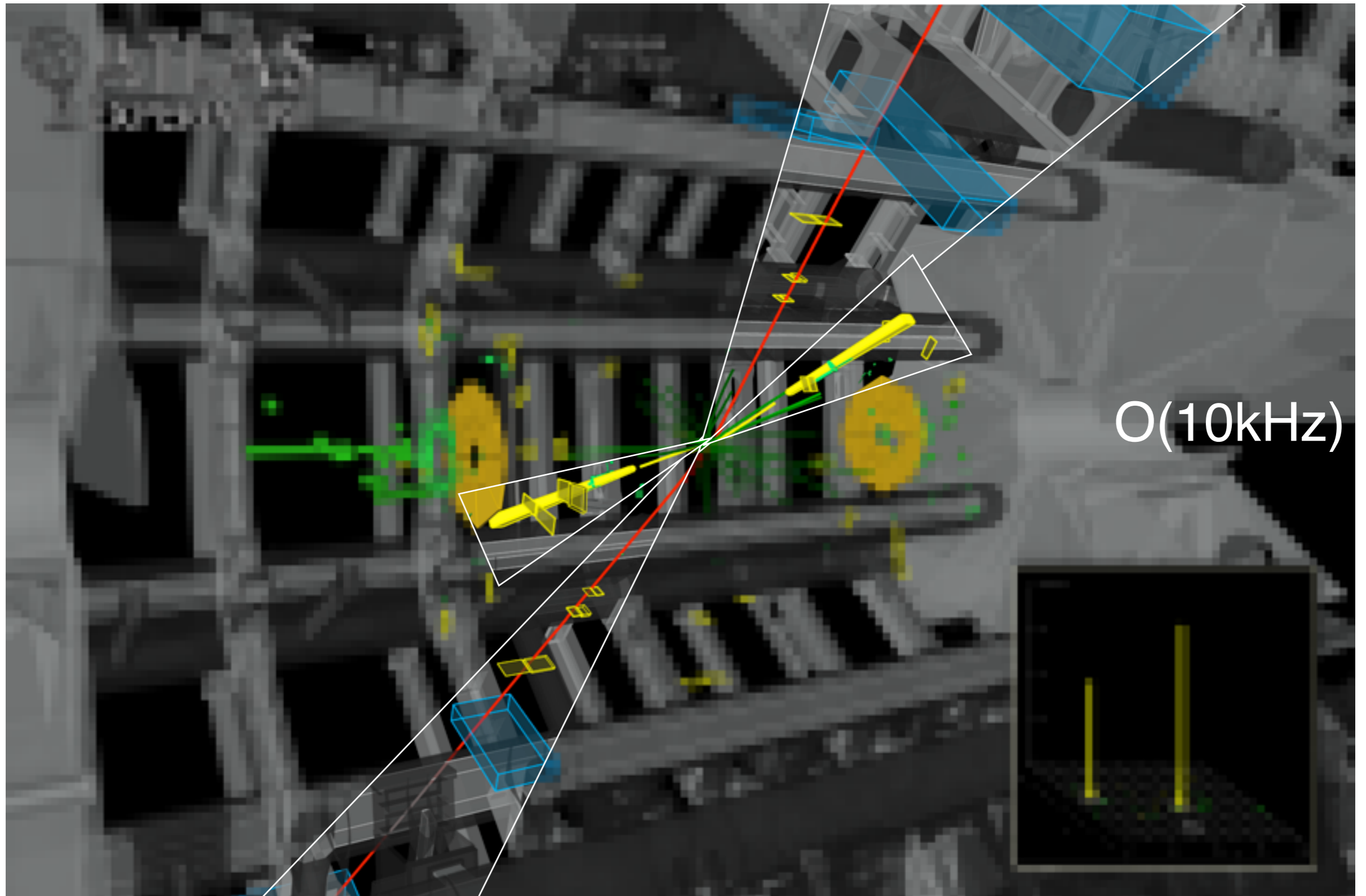
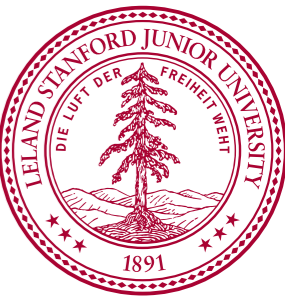




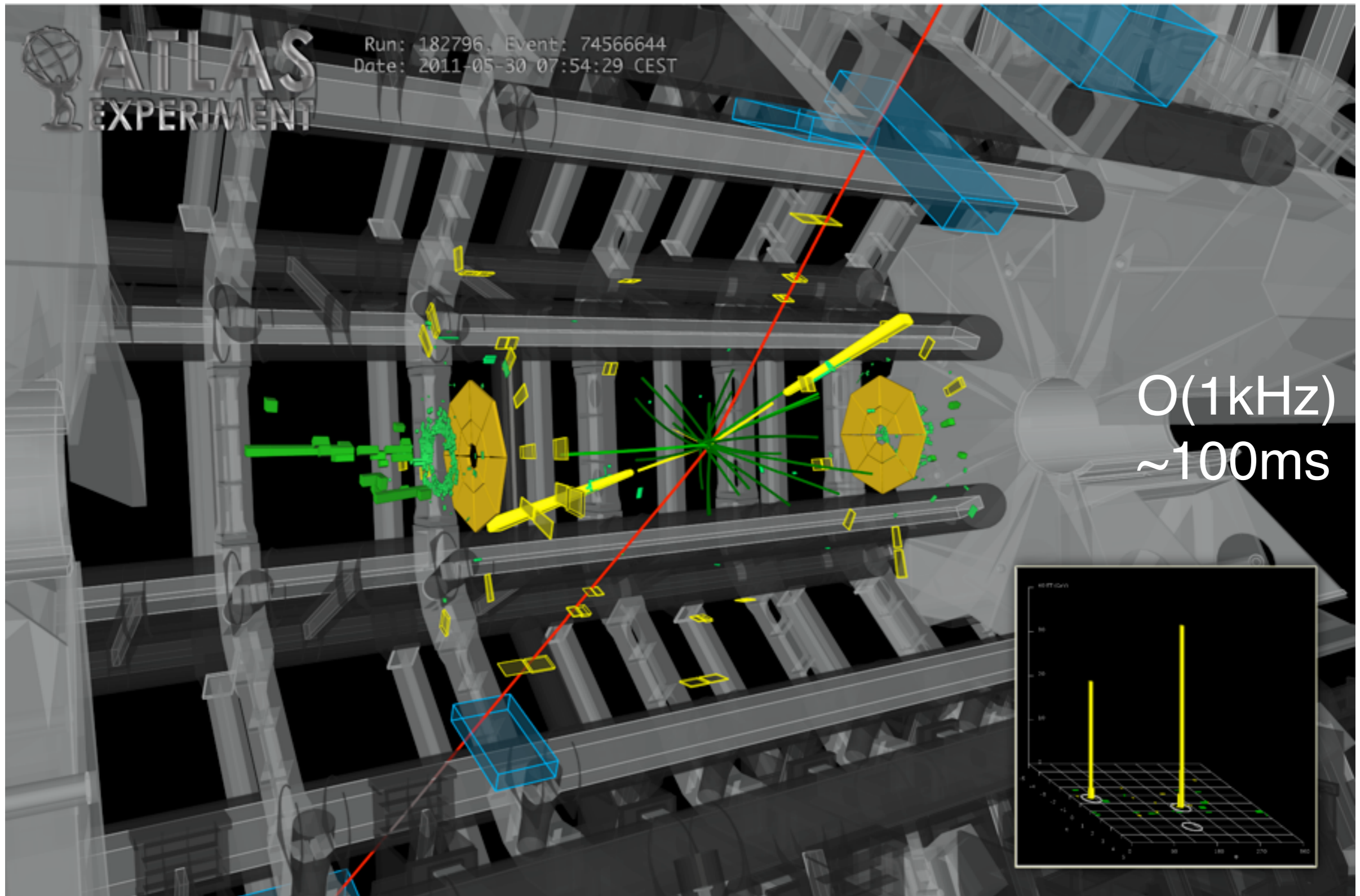
# STEP 1: QUICK AND DIRTY



# STEP 2: SELECTIVE SIGHT



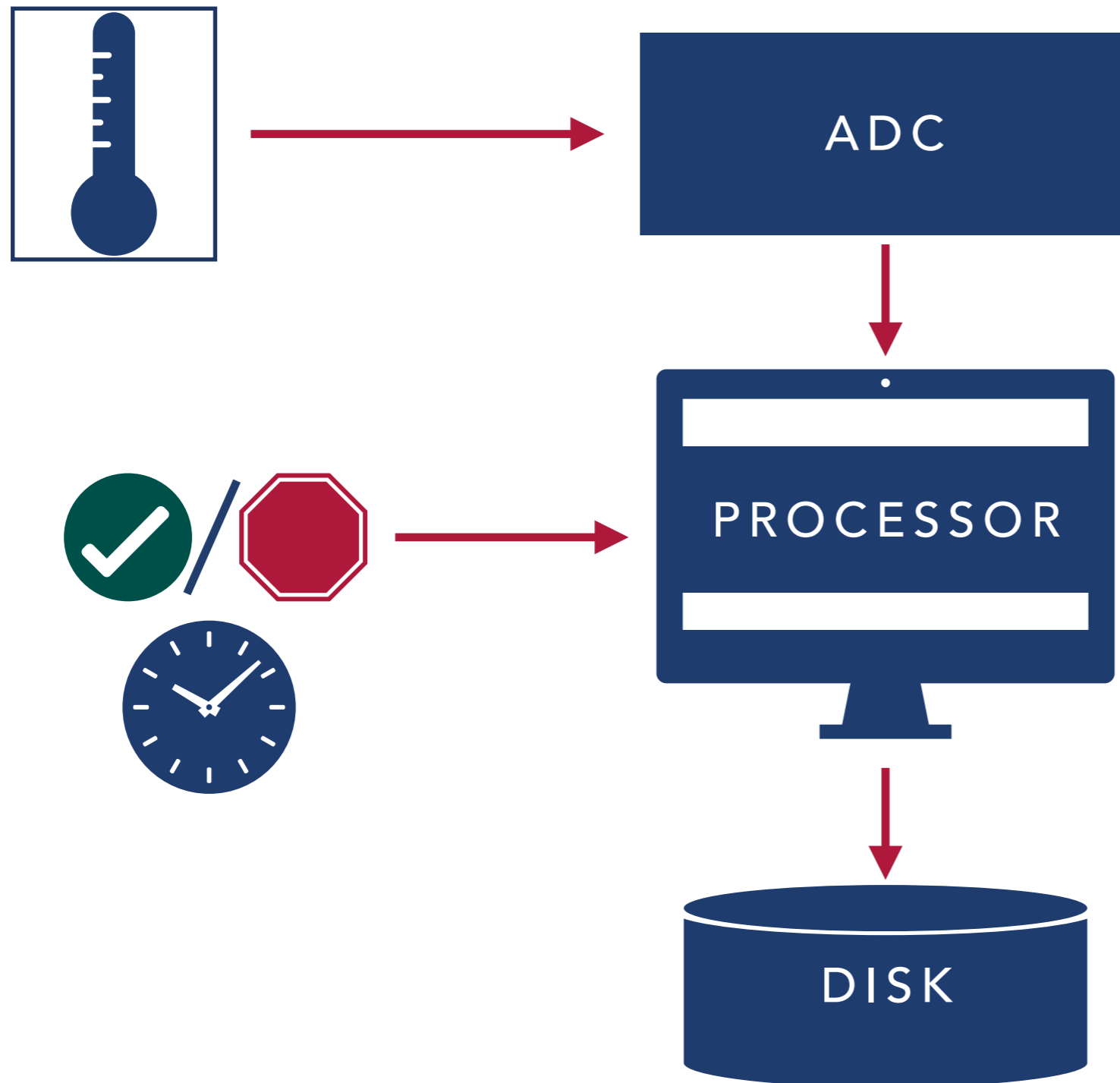
# STEP 3: THE FULL PICTURE (ALMOST)



LET'S START WITH AN  
EXAMPLE

DRAWS HEAVILY FROM EXAMPLE BY ANDREA NEGRI

# FIXED FREQUENCY PROCESSING

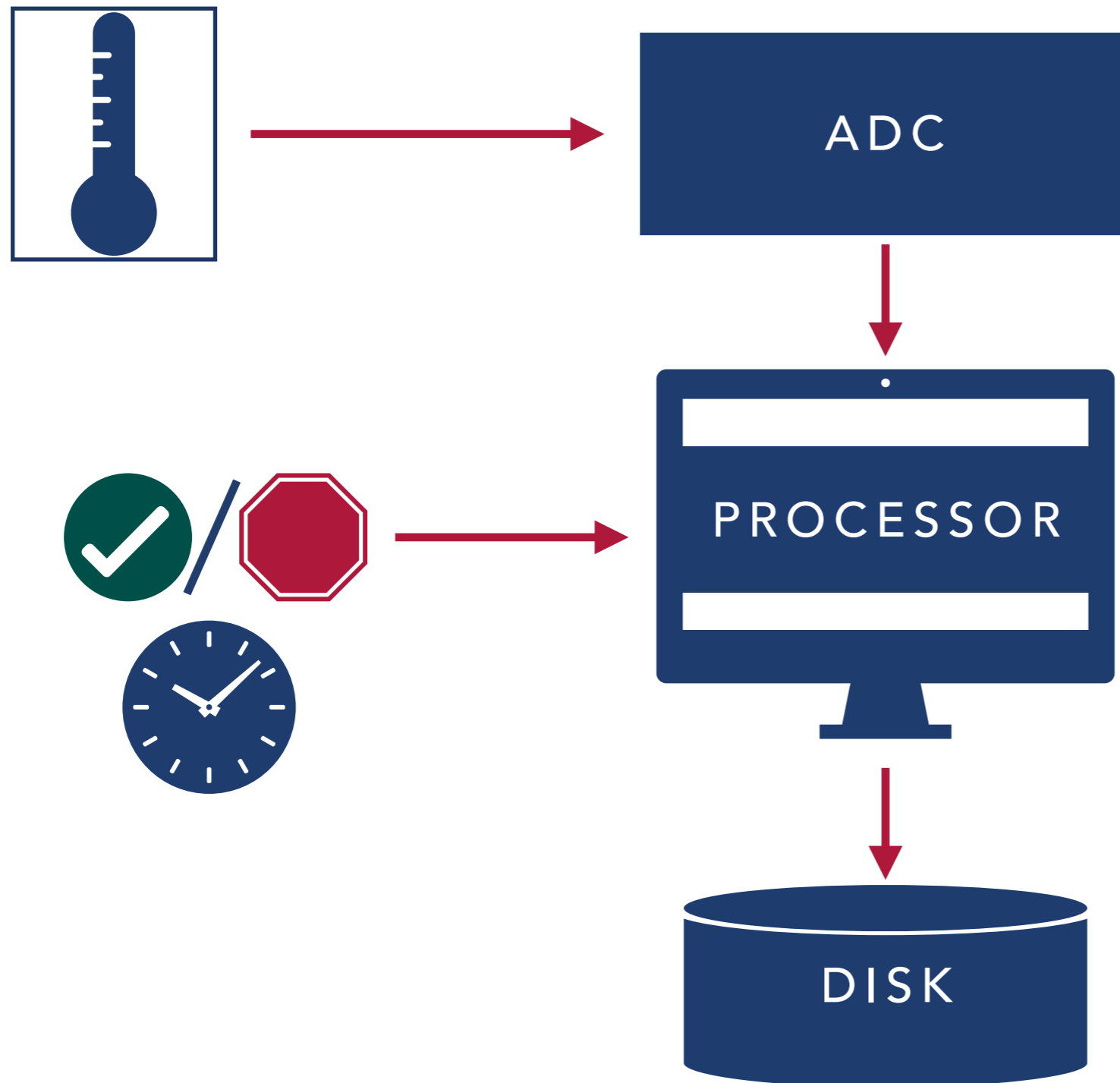
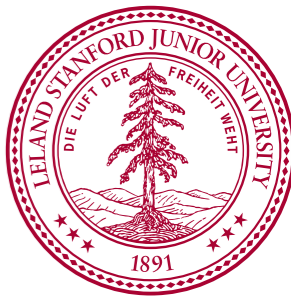


\* How is an event defined?

\* What is the processing time per event?

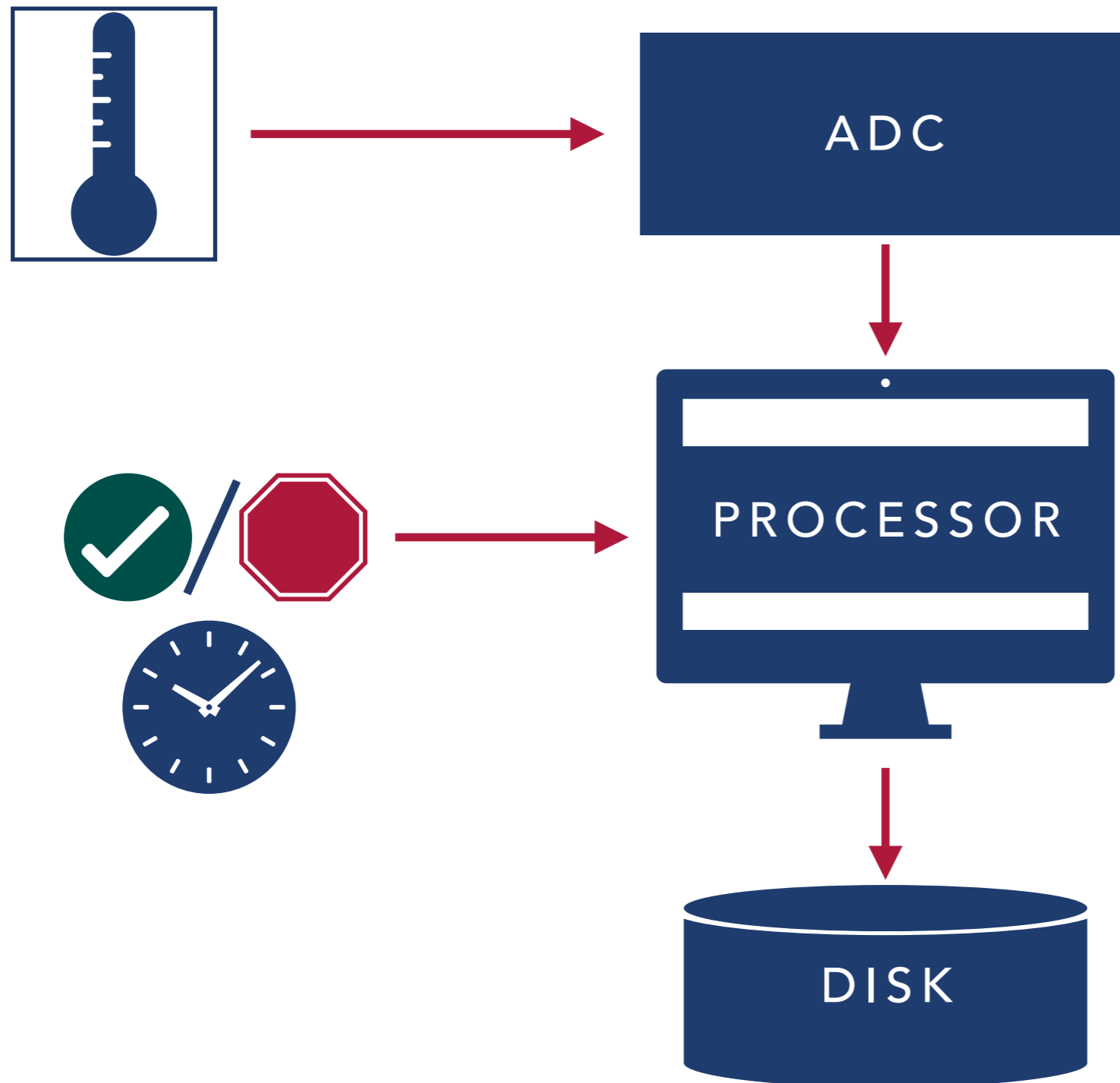
\* What is the maximum sustainable readout rate?

# FIXED FREQUENCY PROCESSING



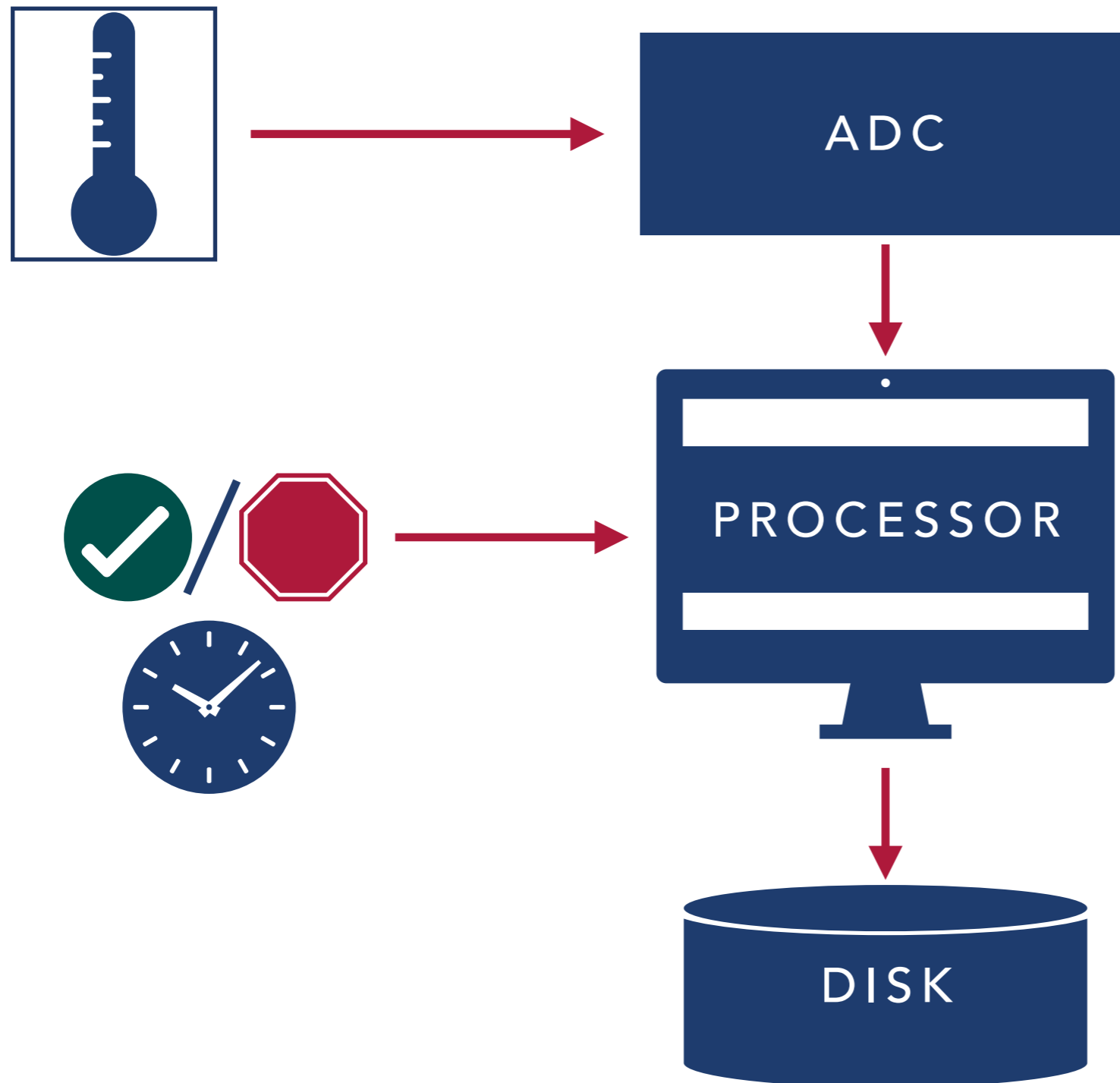
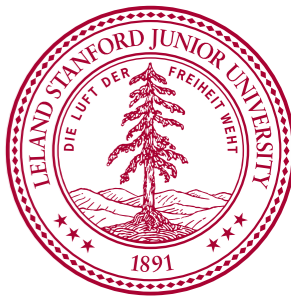
- \* How is an event defined?
- \* Fixed frequency ➤ event = one "read" of the data
- \* What is the processing time per event?
- \* What is the maximum sustainable readout rate?

# FIXED FREQUENCY PROCESSING



- \* How is an event defined?
- \* Fixed frequency ➤ event = one "read" of the data
- \* What is the processing time per event?
- \*  $\tau = \tau(\text{ADC}) + \tau(\text{proc}) + \tau(\text{storage})$
- \* What is the maximum sustainable readout rate?

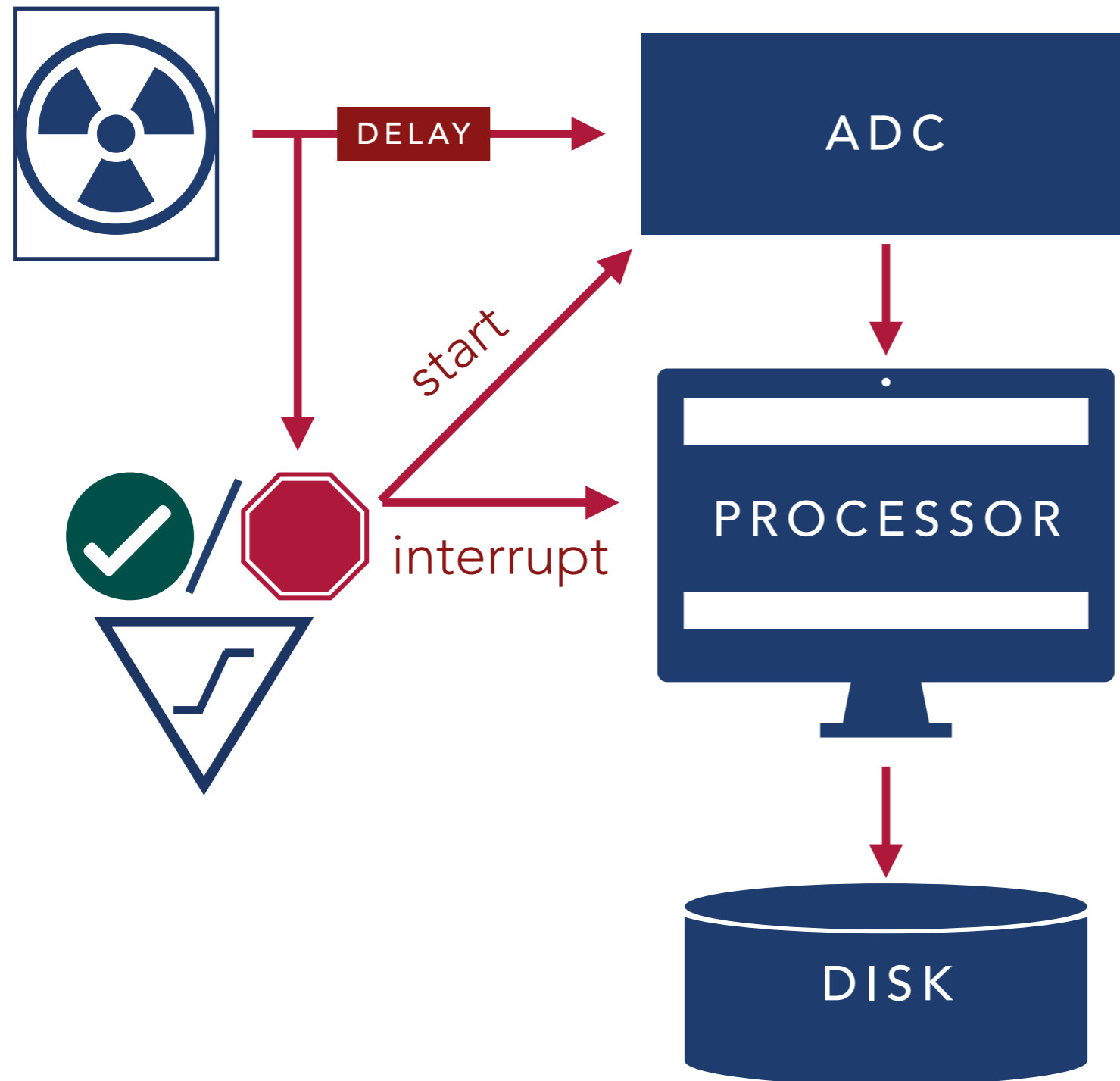
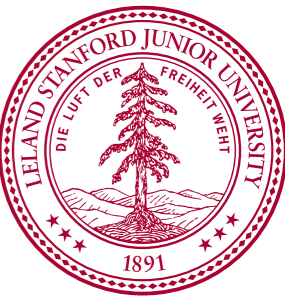
# FIXED FREQUENCY PROCESSING



- \* How is an event defined?
- \* Fixed frequency  $\triangleright$  event = one "read" of the data
- \* What is the processing time per event?
- \*  $\tau = \tau(\text{ADC}) + \tau(\text{proc}) + \tau(\text{storage})$
- \* What is the maximum sustainable readout rate?
- \*  $R = 1/\tau$
- \* If  $\tau = 1\text{ms}$  ;  $R = 1\text{kHz}$



# STOCHASTIC PROCESSING

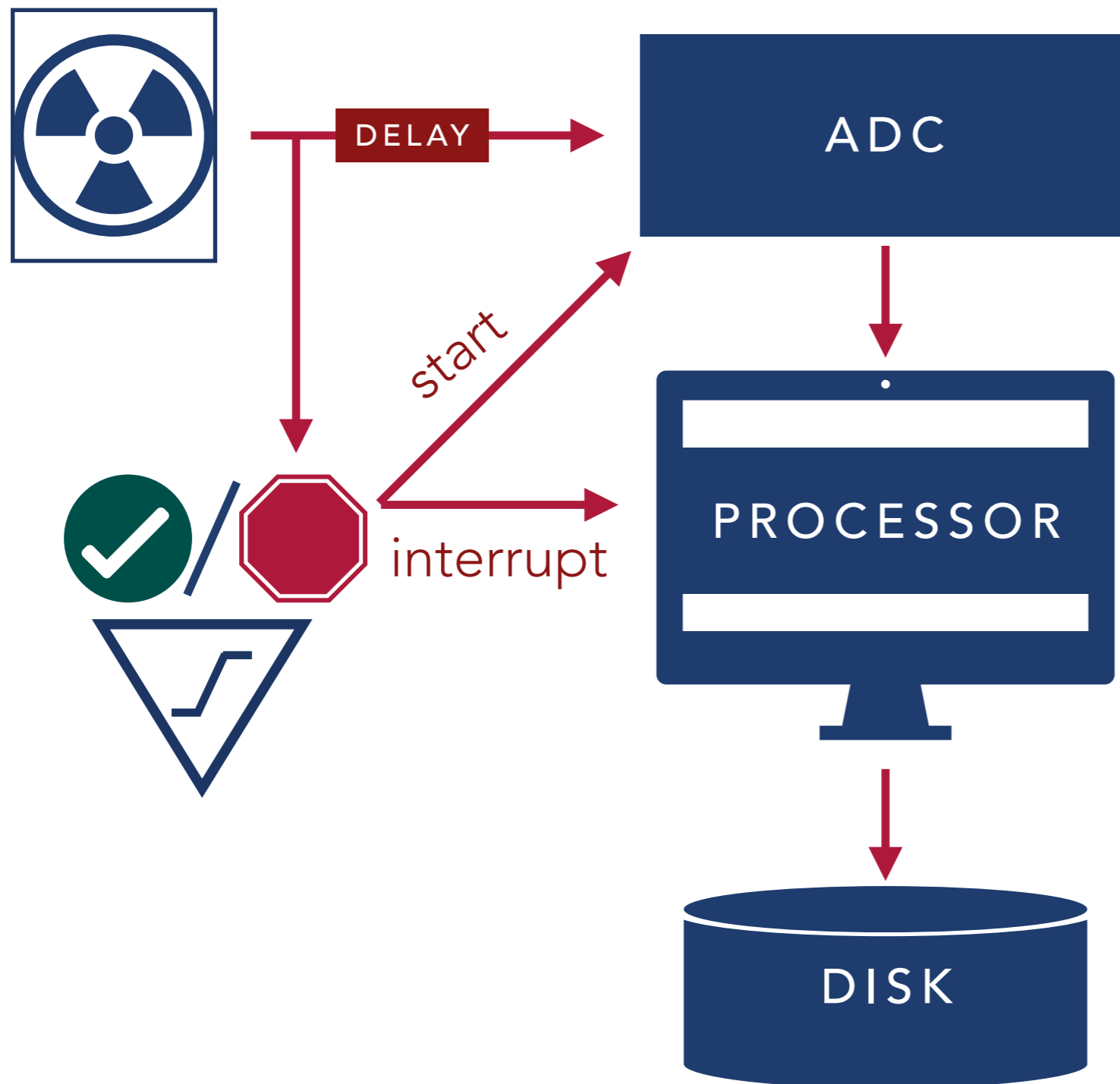


\* How is an event defined?

\* What is the processing time per event?

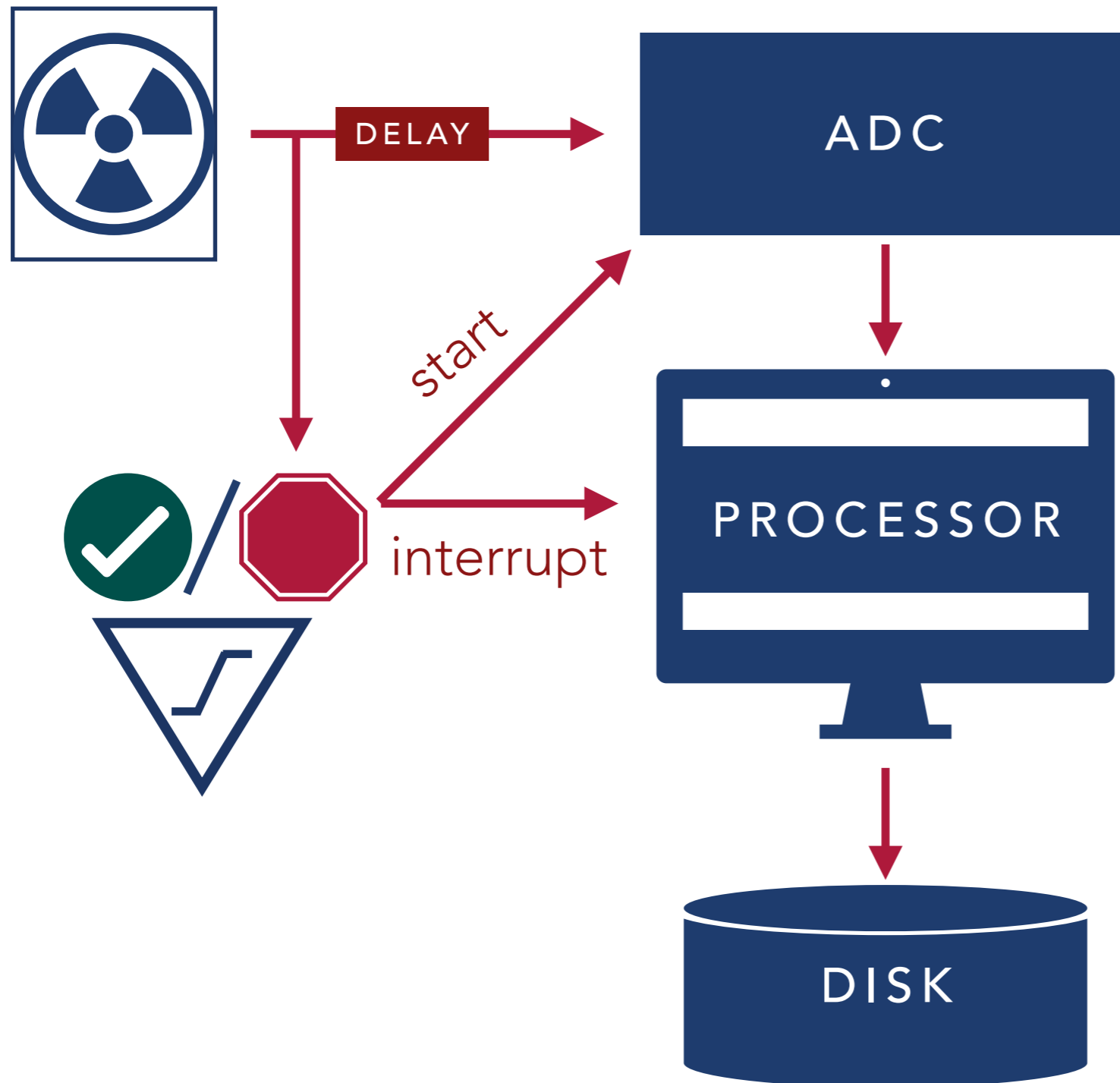
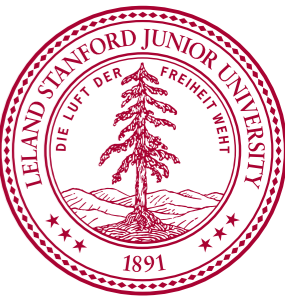
\* What if our average lifetime for our process,  $\lambda = \tau = 1\text{ms}$ ? First, sketch the distribution of possible events times.

# STOCHASTIC PROCESSING

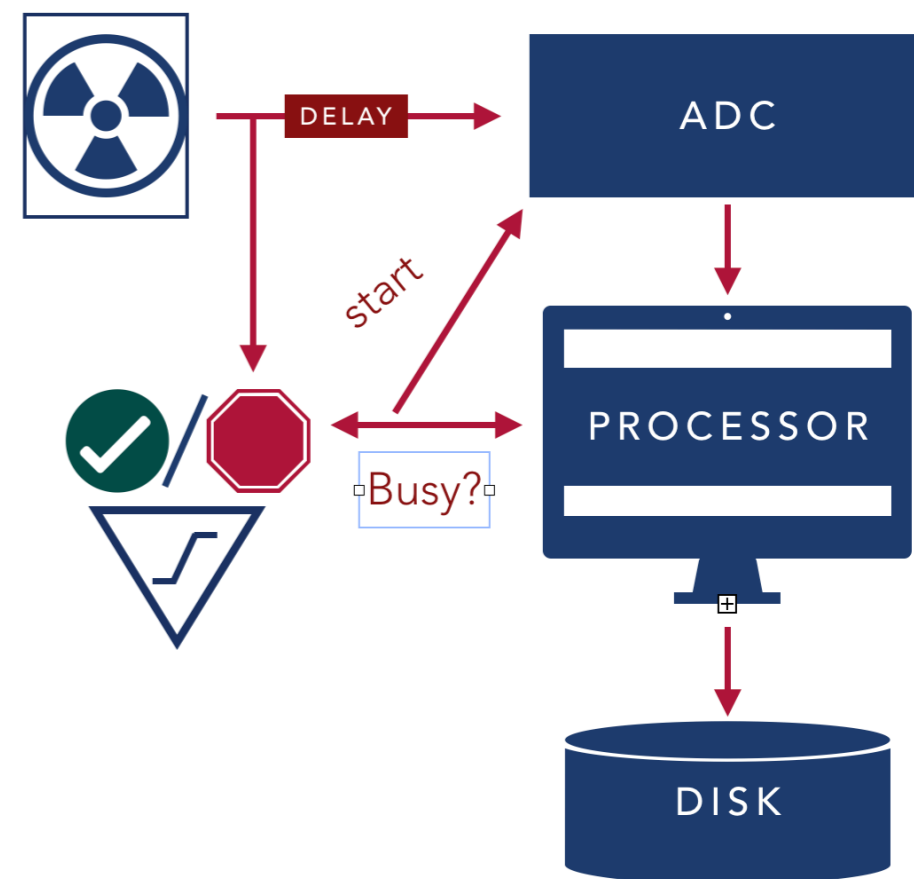
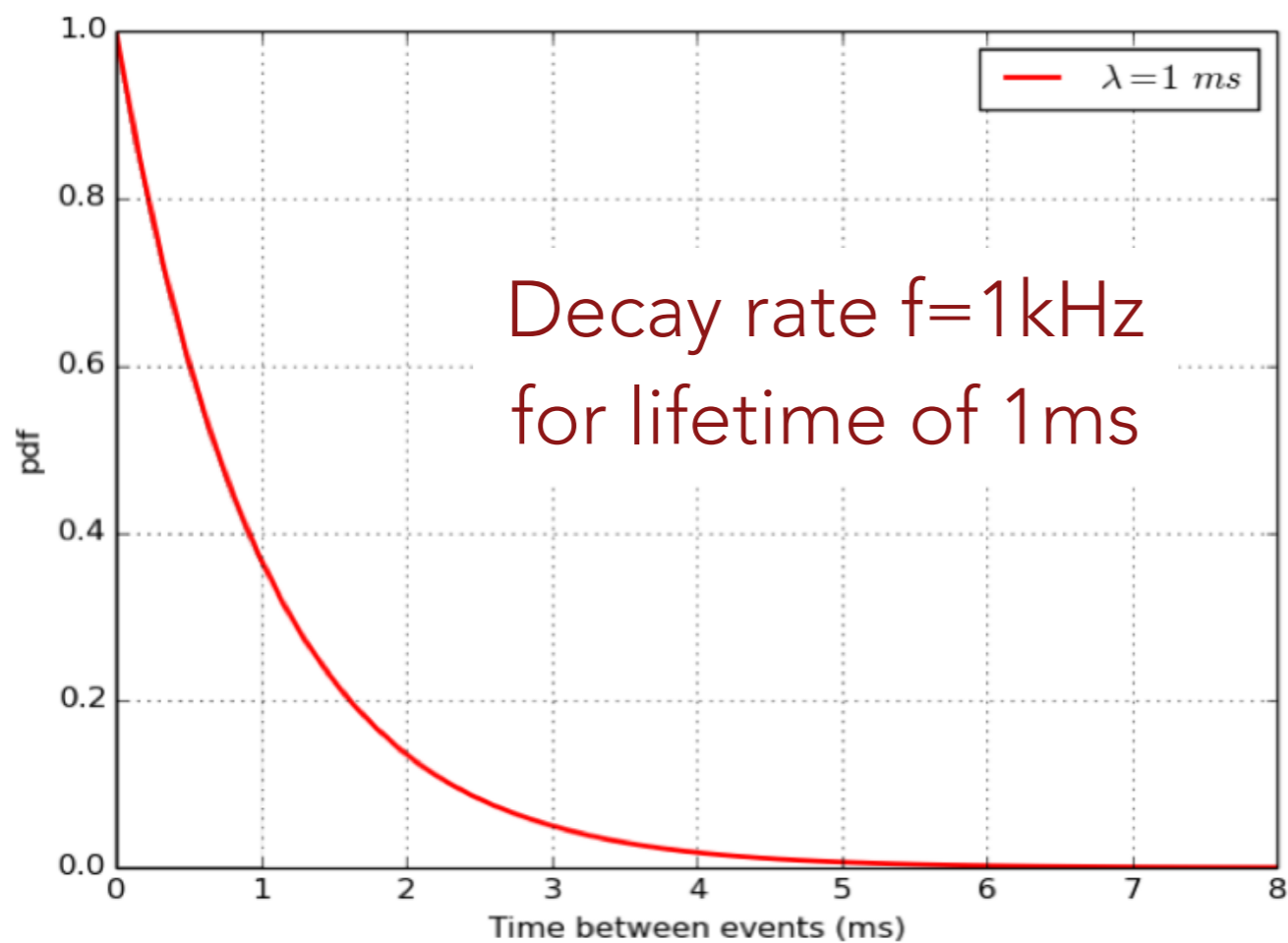


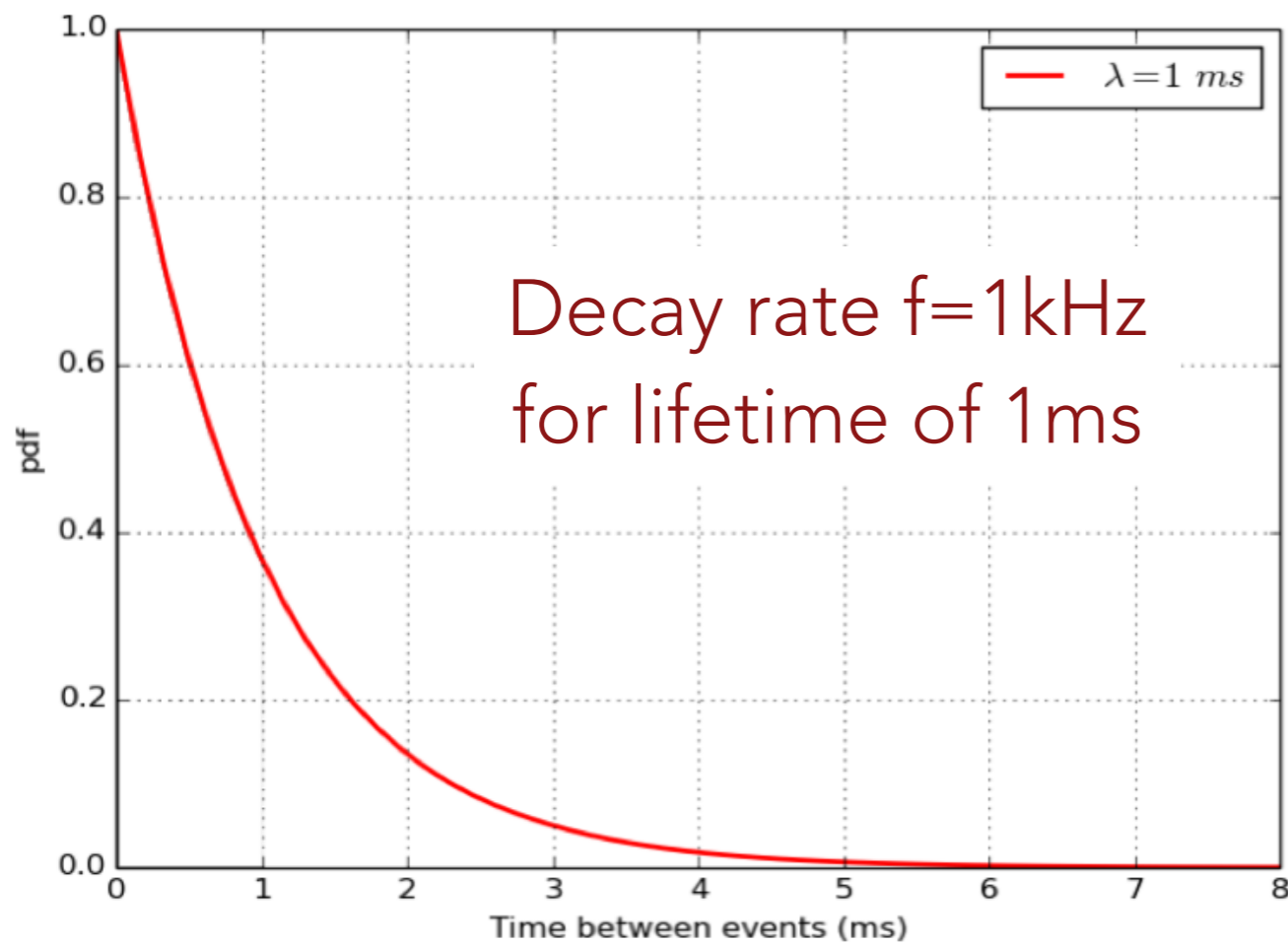
- \* How is an event defined?
- \* Event = decay = signal passing discriminator threshold
- \* What is the processing time per event?
- \* What if our average lifetime for our process,  $\lambda = \tau = 1\text{ms}$ ? First, sketch the distribution of possible events times.

# STOCHASTIC PROCESSING

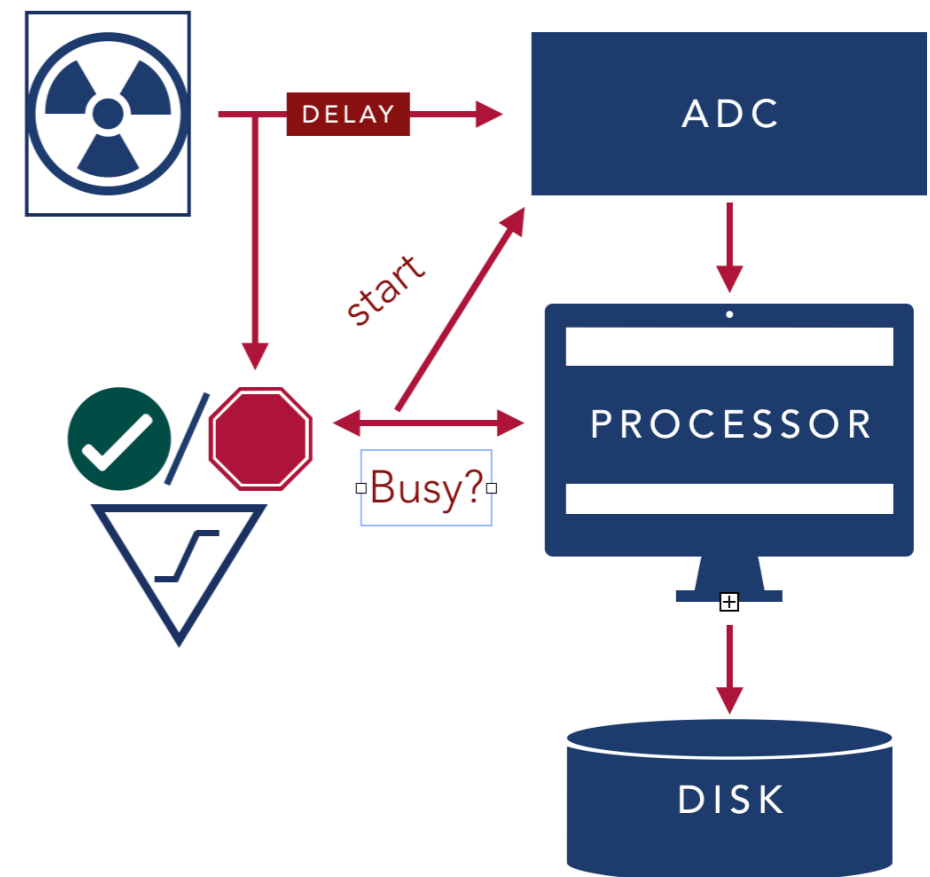


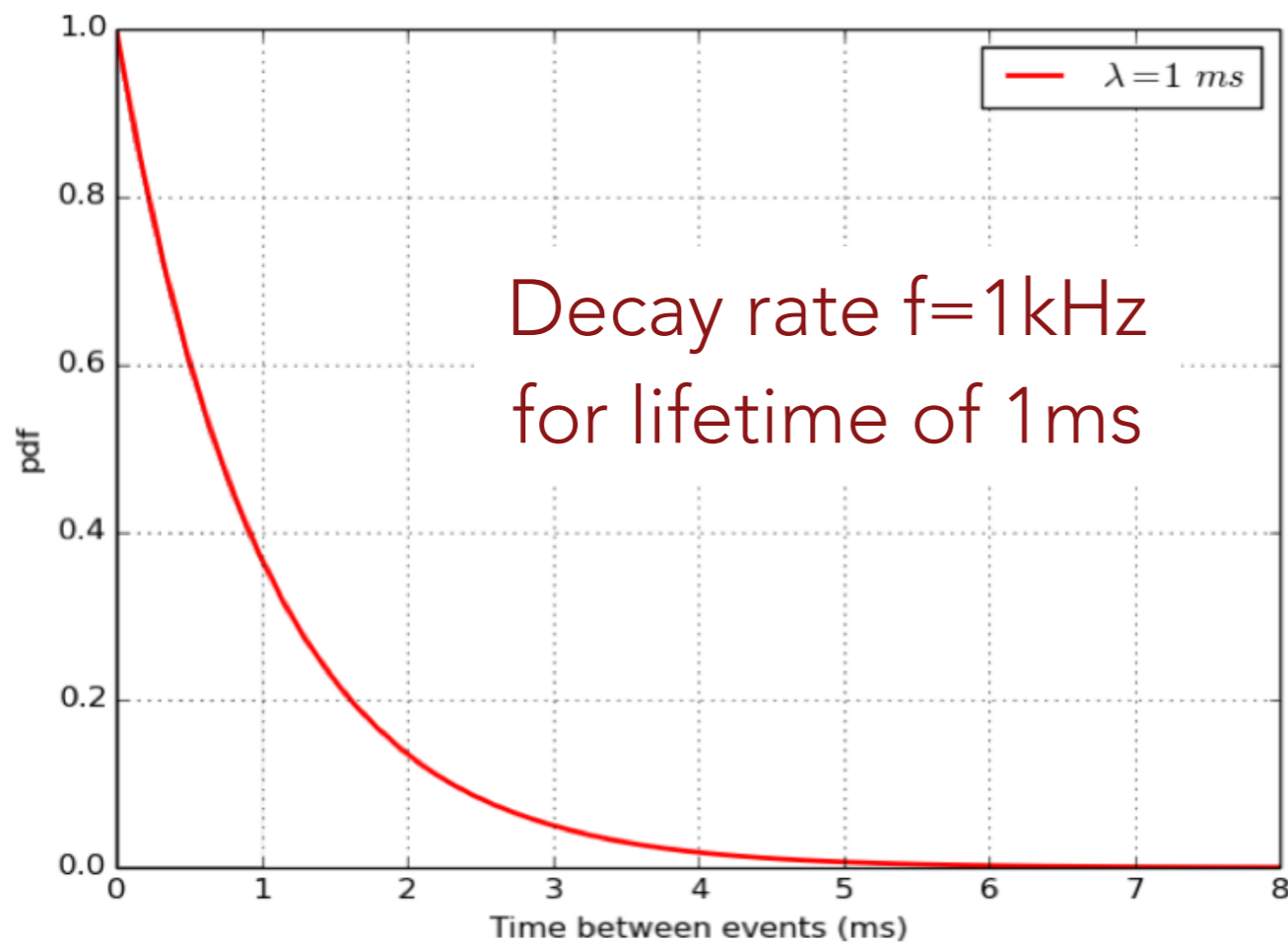
- \* How is an event defined?
- \* Event = decay = signal passing discriminator threshold
- \* What is the processing time per event?
- \* Still  $\tau = \tau(\text{ADC}) + \tau(\text{proc}) + \tau(\text{storage})$
- \* What if our average lifetime for our process,  $\lambda = \tau = 1\text{ms}$ ? First, sketch the distribution of possible events times.





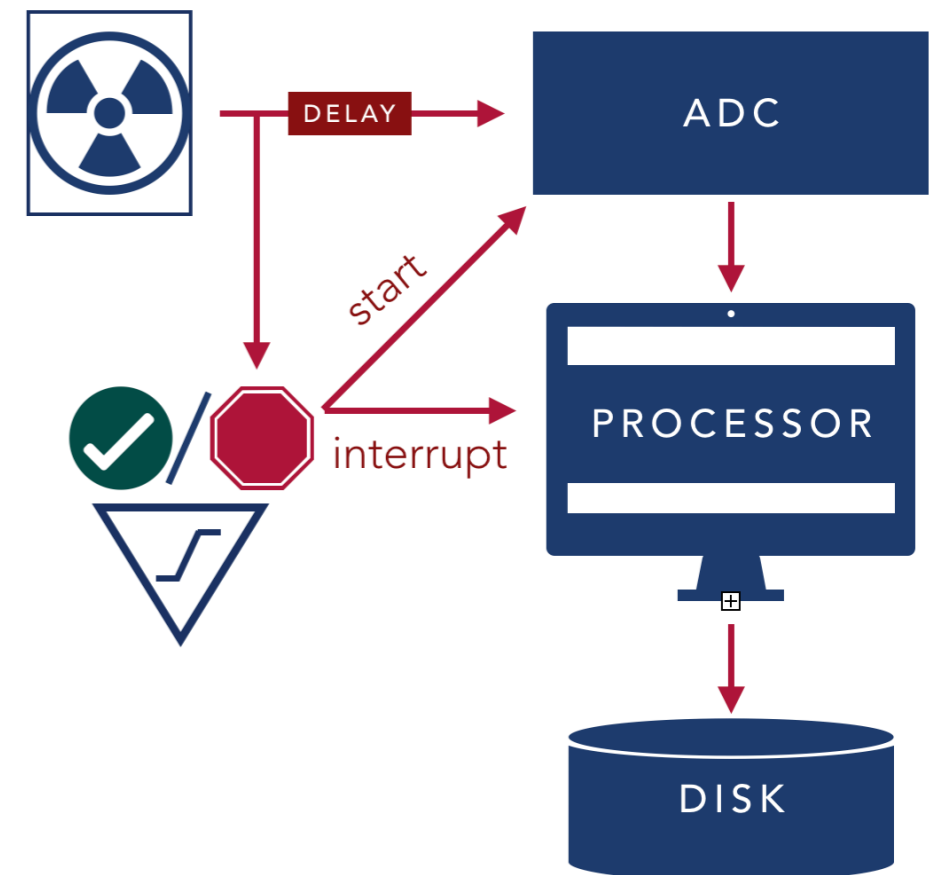
What happens to these events?

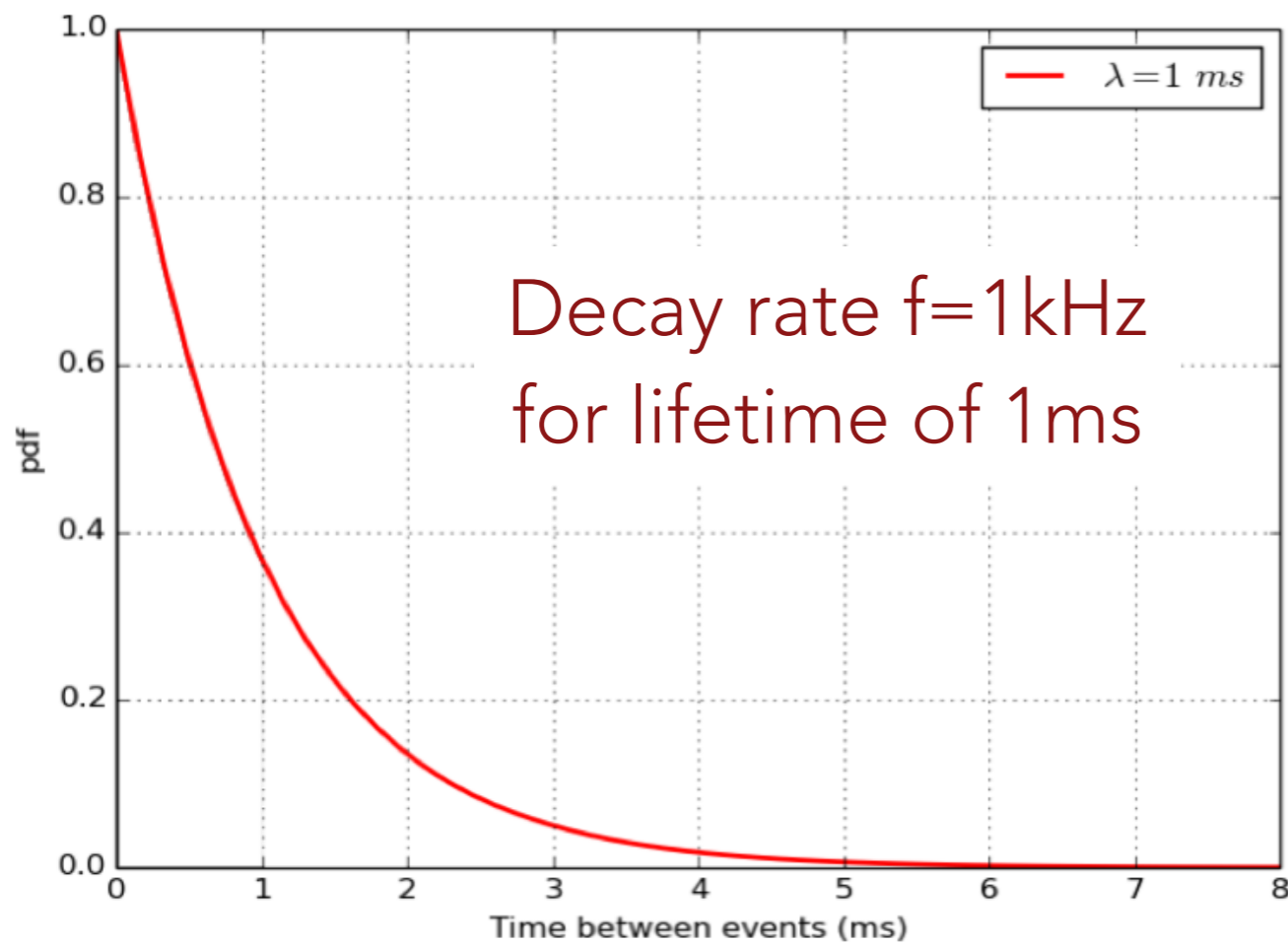




What happens to these events?

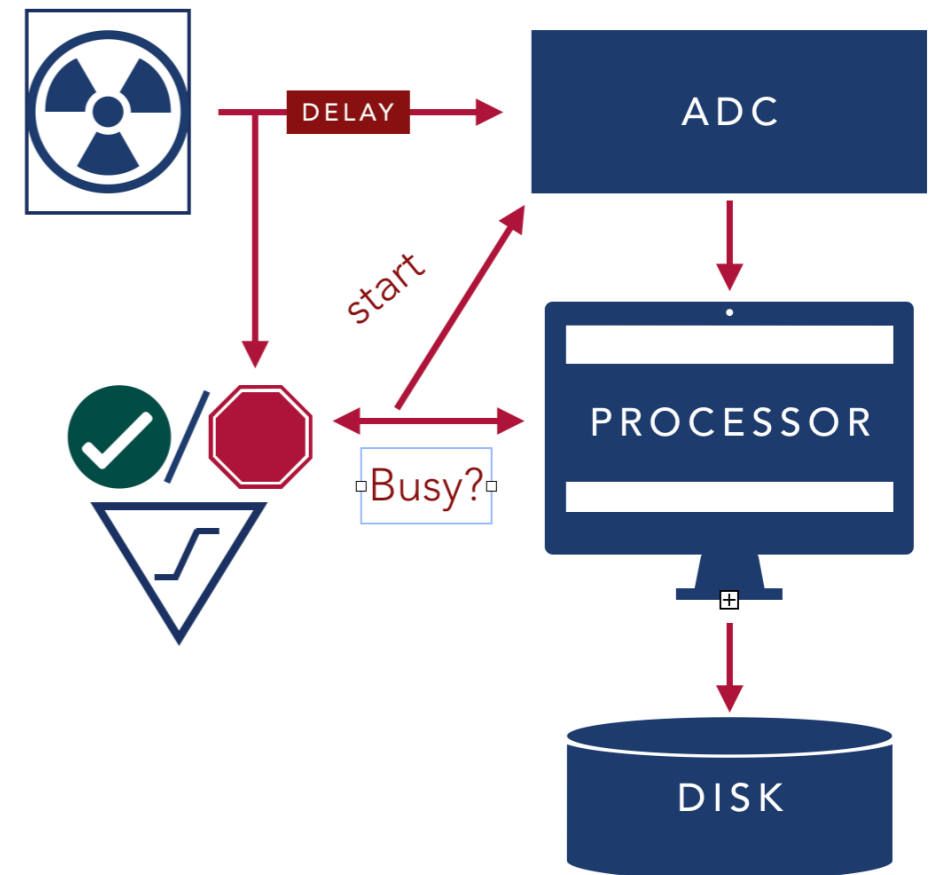
Will keep hitting interrupt unless processing system can tell the trigger that it's BUSY



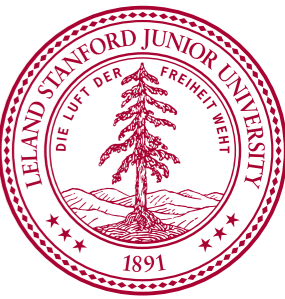


What happens to these events?

Will keep hitting interrupt unless processing system can tell the trigger that it's BUSY



# BRIEF PAUSE TO REGROUP



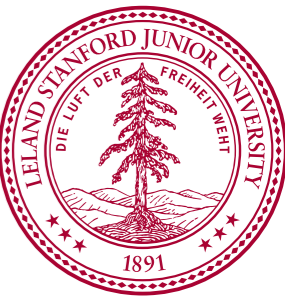
- For stochastic processes, our system needs to be able to:
  - Determine if there is an “event” (trigger)
  - Process and store the data from the event (acquisition)
  - Have a **feedback** mechanism so that the trigger knows if the data processing pipeline is free to process a new event



SO HOW FAST CAN WE PROCESS  
EVENTS?

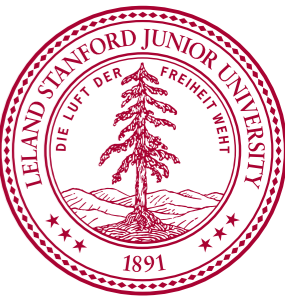


# SO HOW FAST CAN WE PROCESS EVENTS?



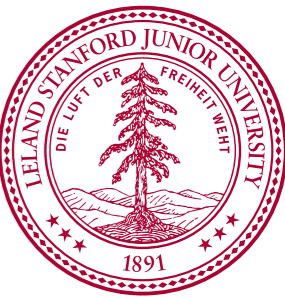
- Our average event rate is  $f$

# SO HOW FAST CAN WE PROCESS EVENTS?



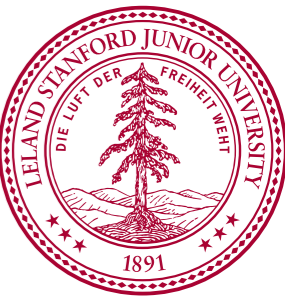
- Our average event rate is  $f$
- Our dead time (system processing time) is  $\tau$

# SO HOW FAST CAN WE PROCESS EVENTS?



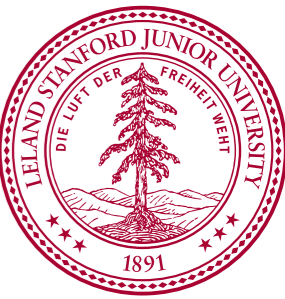
- Our average event rate is  $f$
- Our dead time (system processing time) is  $\tau$
- We want to know our average data acquisition (DAQ) rate,  $\nu$

# SO HOW FAST CAN WE PROCESS EVENTS?



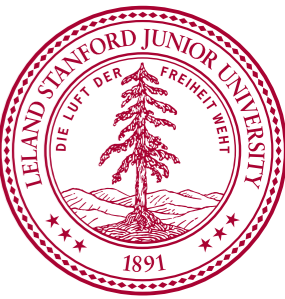
- Our average event rate is  $f$
- Our dead time (system processing time) is  $\tau$
- We want to know our average data acquisition (DAQ) rate,  $\nu$
- What is the probability that our system is busy in terms of  $\tau$  and  $\nu$ ?

# SO HOW FAST CAN WE PROCESS EVENTS?



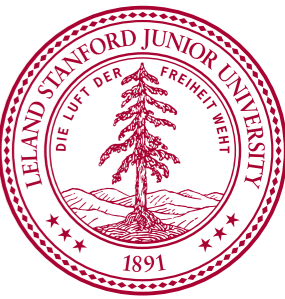
- Our average event rate is  $f$
- Our dead time (system processing time) is  $\tau$
- We want to know our average data acquisition (DAQ) rate,  $\nu$
- What is the probability that our system is busy in terms of  $\tau$  and  $\nu$ ?
  - $P[\text{busy}] = \tau\nu$  ;  $P[\text{free}] = 1 - \tau\nu$

# SO HOW FAST CAN WE PROCESS EVENTS?



- Our average event rate is  $f$
- Our dead time (system processing time) is  $\tau$
- We want to know our average data acquisition (DAQ) rate,  $\nu$
- What is the probability that our system is busy in terms of  $\tau$  and  $\nu$ ?
  - $P[\text{busy}] = \tau\nu$  ;  $P[\text{free}] = 1 - \tau\nu$
- Therefore, our DAQ rate is  $\nu = f P[\text{free}] = f (1 - \tau\nu)$  ;  $\nu = f/(1 + f\tau)$

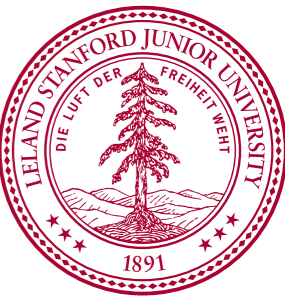
# RATES AND EFFICIENCIES



- What can we say about our DAQ rate relative to our physics process rate?
- What can we say about our efficiency to record events?
- So if  $f = 1/\tau = 1 \text{ kHz}$  ; then  $\nu = 500 \text{ Hz}$  ;  
 $\varepsilon = 50\%$
- How can we maximize our efficiency?



# RATES AND EFFICIENCIES

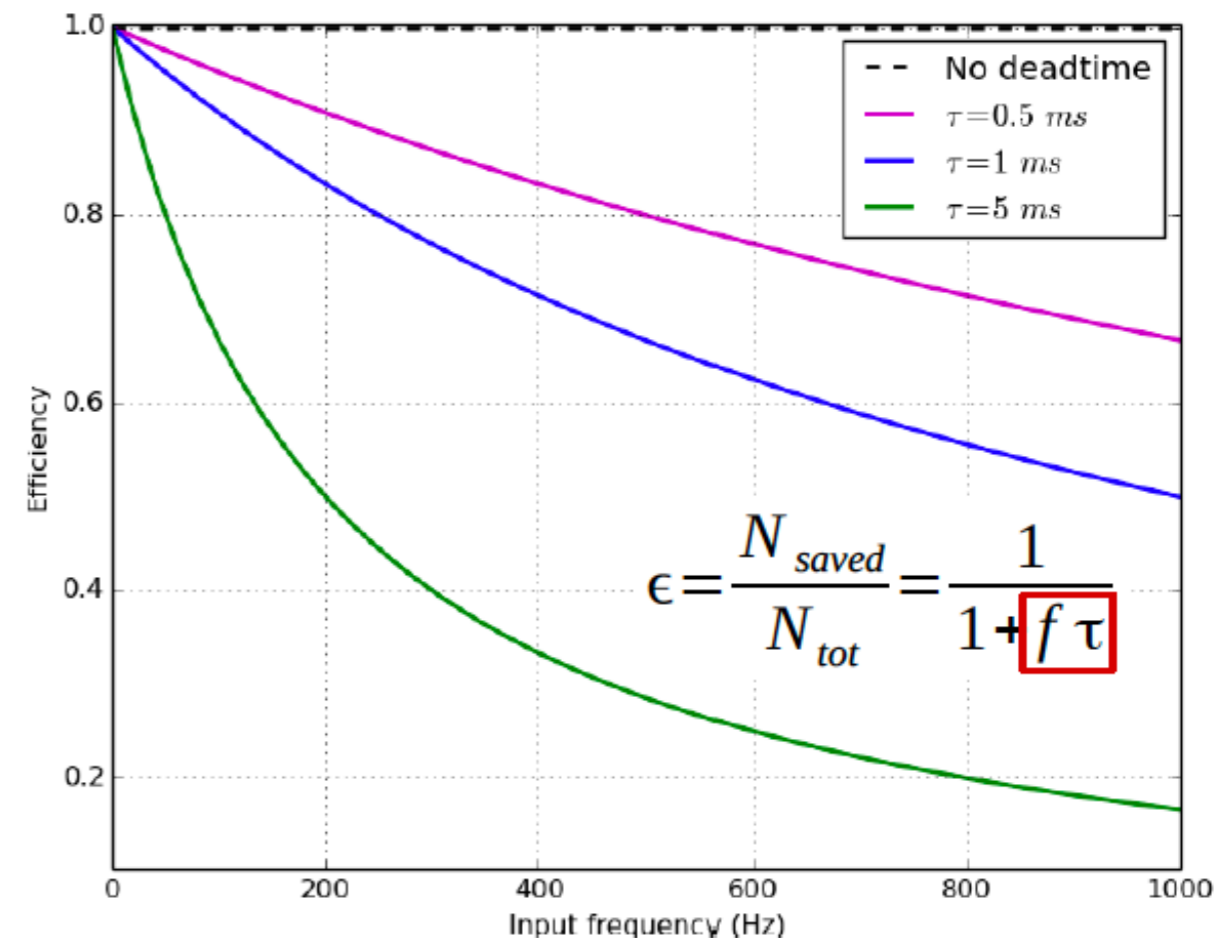


- What can we say about our DAQ rate relative to our physics process rate?
  - It is always smaller!  $\nu = f/(1+f\tau) < f$
- What can we say about our efficiency to record events?
- So if  $f = 1/\tau = 1 \text{ kHz}$  ; then  $\nu = 500 \text{ Hz}$  ;  
 $\epsilon = 50\%$
- How can we maximize our efficiency?

# RATES AND EFFICIENCIES



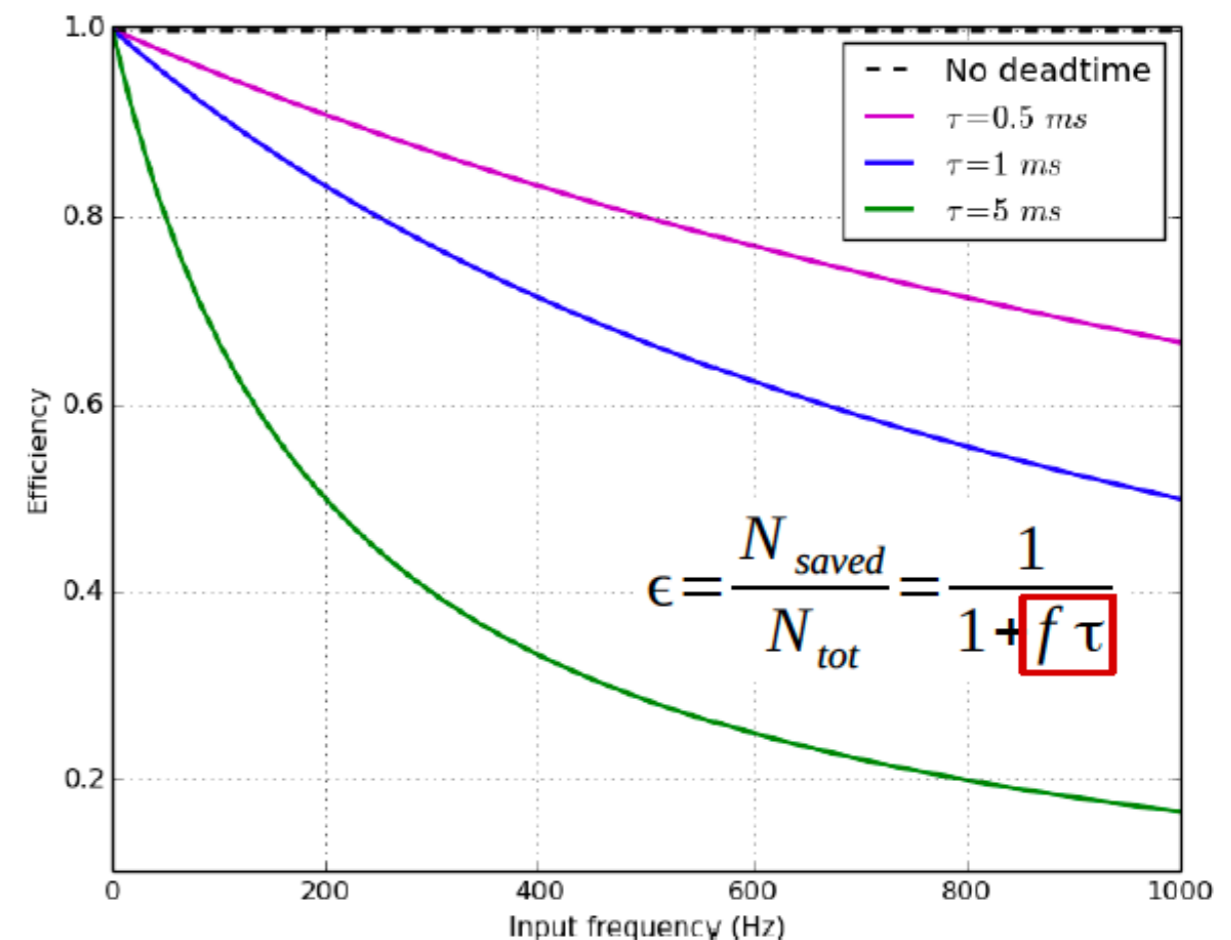
- What can we say about our DAQ rate relative to our physics process rate?
  - It is always smaller!  $\nu = f/(1+f\tau) < f$
- What can we say about our efficiency to record events?
  - $\epsilon = \nu/f < 1$
- So if  $f = 1/\tau = 1$  kHz ; then  $\nu = 500$  Hz ;  
 $\epsilon = 50\%$
- How can we maximize our efficiency?



# RATES AND EFFICIENCIES



- What can we say about our DAQ rate relative to our physics process rate?
  - It is always smaller!  $\nu = f/(1+f\tau) < f$
- What can we say about our efficiency to record events?
  - $\epsilon = \nu/f < 1$
- So if  $f = 1/\tau = 1$  kHz ; then  $\nu = 500$  Hz ;  
 $\epsilon = 50\%$
- How can we maximize our efficiency?
  - We need  $f\tau \ll 1$
  - For  $\epsilon = 99\%$  and  $f = 1$  kHz we need  $\tau = 0.01$  ms!



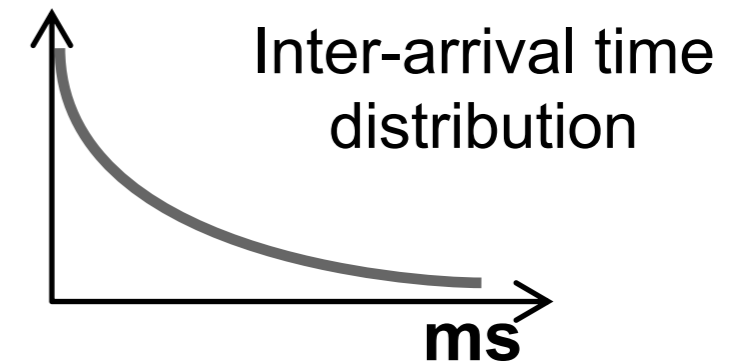
HOW CAN WE MAKE OUR SYSTEM  
MORE EFFICIENT??



# HOW CAN WE MAKE OUR SYSTEM MORE EFFICIENT??



- What if we were able to make the system more deterministic and less dependent on the arrival time or our signals?

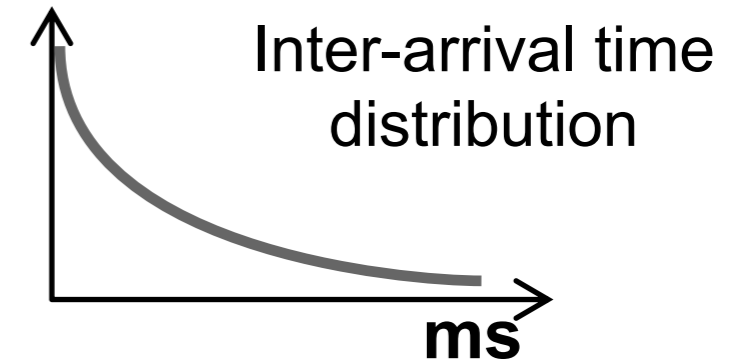


$\lambda$  (ms) ;  
f (Hz)

# HOW CAN WE MAKE OUR SYSTEM MORE EFFICIENT??



- What if we were able to make the system more deterministic and less dependent on the arrival time or our signals?
  - Then we could ensure that events don't arrive when the system is busy

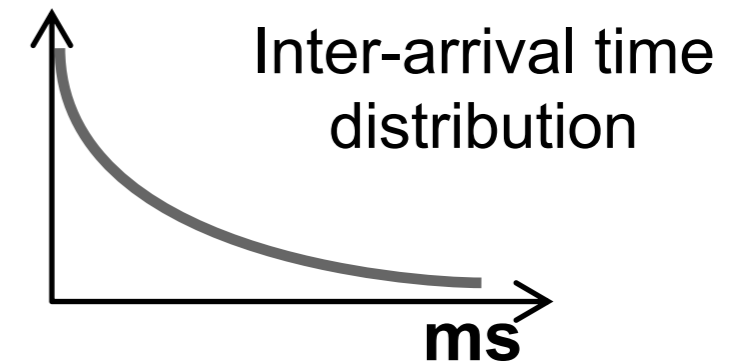


$\lambda$  (ms) ;  
f (Hz)

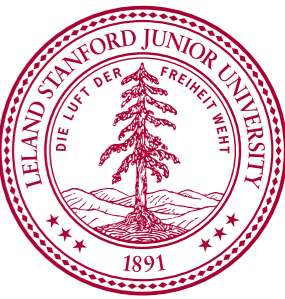
# HOW CAN WE MAKE OUR SYSTEM MORE EFFICIENT??



- What if we were able to make the system more deterministic and less dependent on the arrival time or our signals?
  - Then we could ensure that events don't arrive when the system is busy
- This is called **de-randomization** and we achieve it by buffering the data (having a holding queue where we can slot it up to be processed)

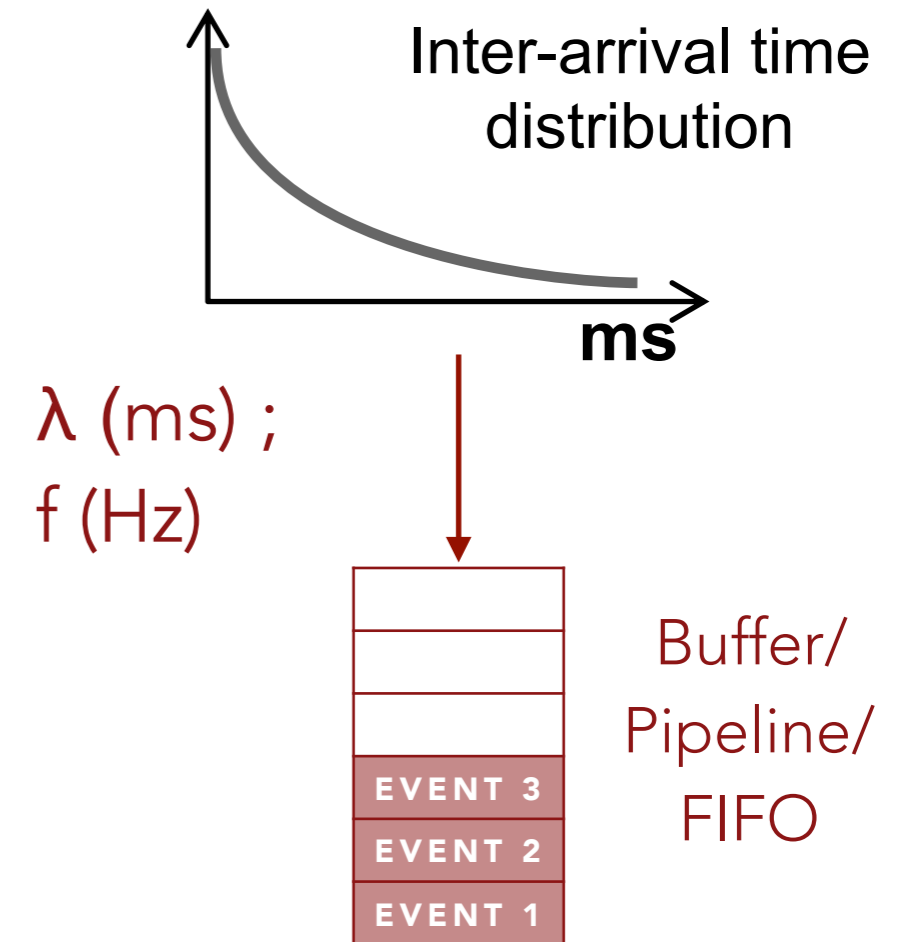


$\lambda$  (ms) ;  
f (Hz)



# HOW CAN WE MAKE OUR SYSTEM MORE EFFICIENT??

- What if we were able to make the system more deterministic and less dependent on the arrival time or our signals?
  - Then we could ensure that events don't arrive when the system is busy
- This is called **de-randomization** and we achieve it by buffering the data (having a holding queue where we can slot it up to be processed)

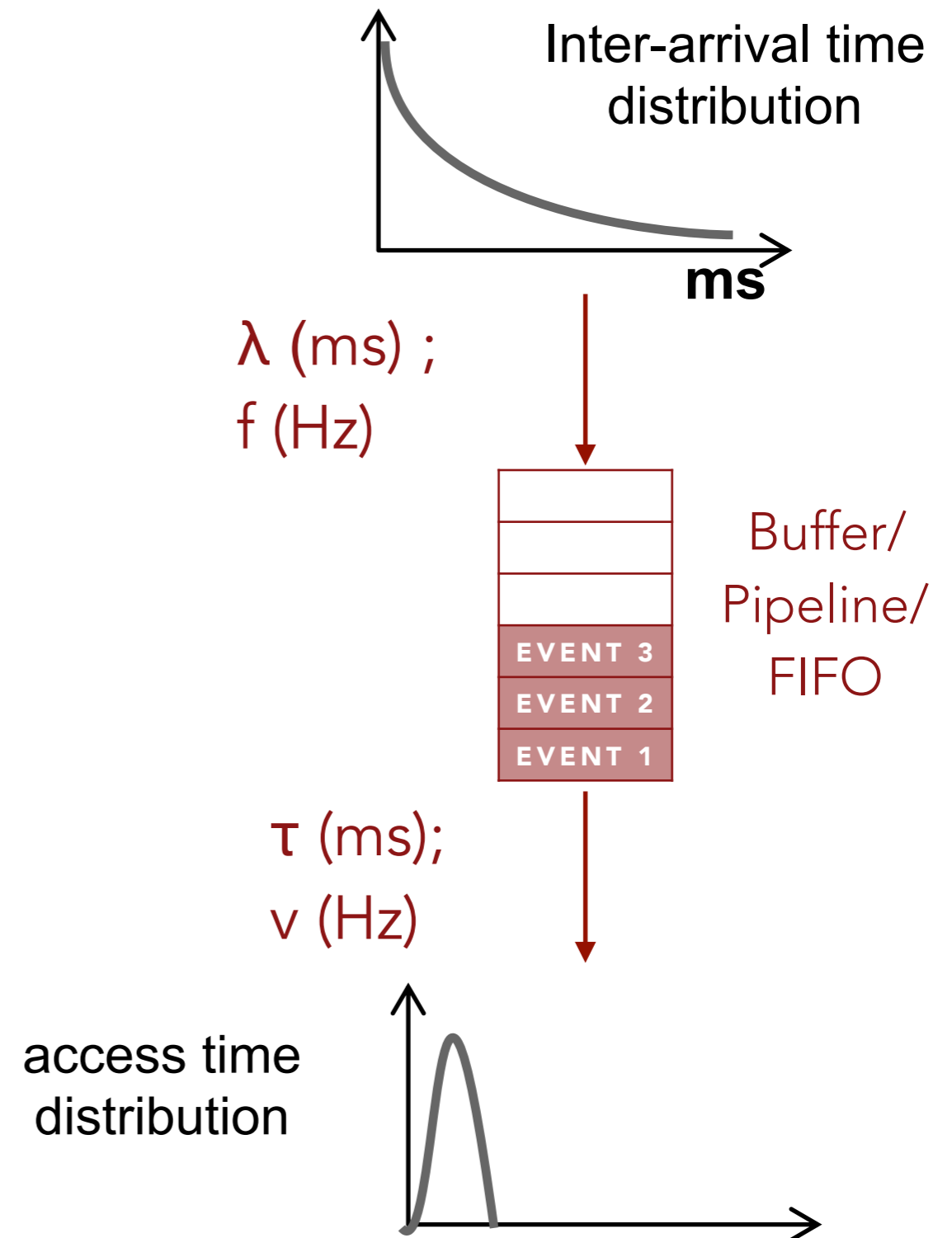




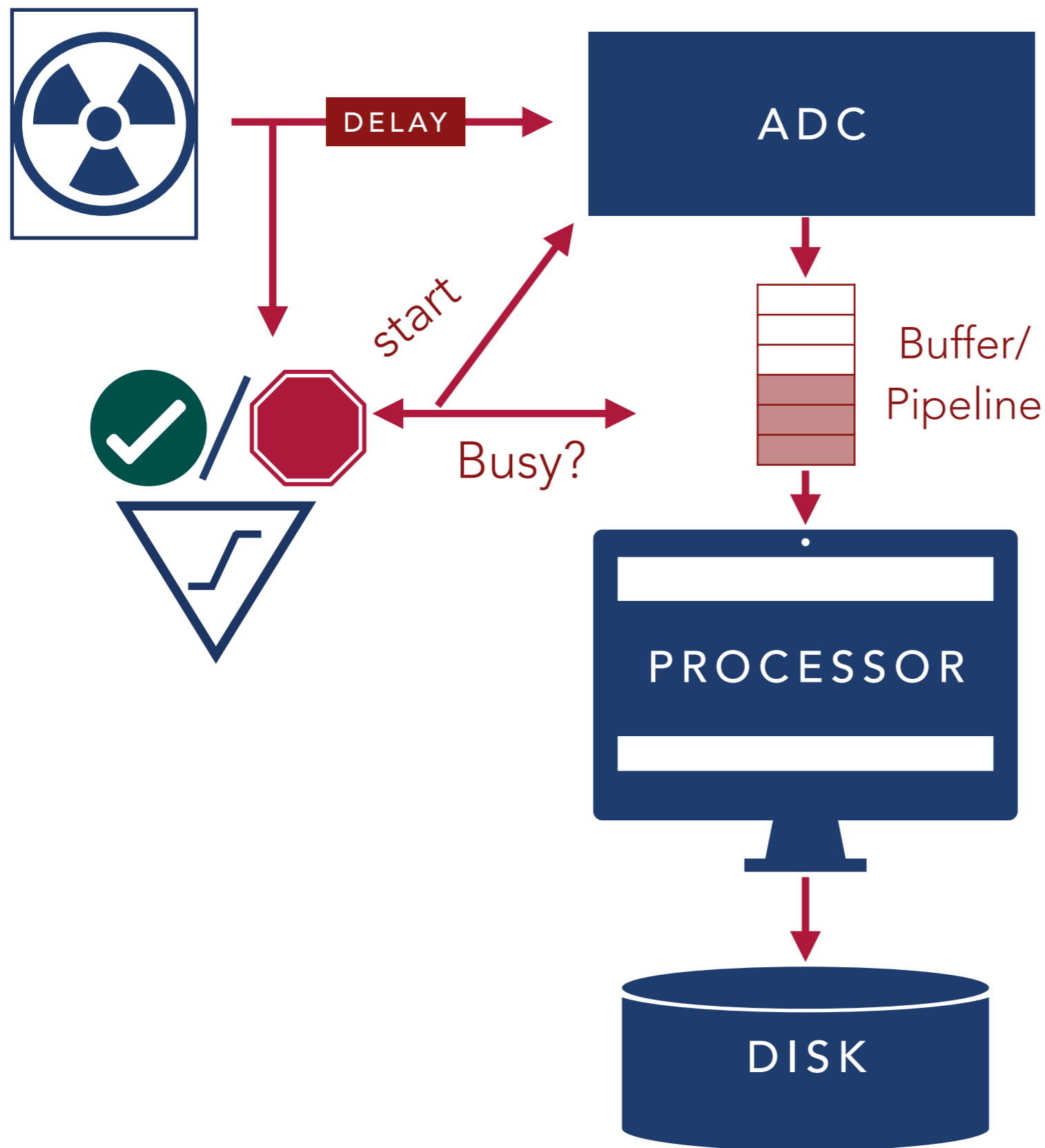
# HOW CAN WE MAKE OUR SYSTEM MORE EFFICIENT??



- What if we were able to make the system more deterministic and less dependent on the arrival time or our signals?
  - Then we could ensure that events don't arrive when the system is busy
- This is called **de-randomization** and we achieve it by buffering the data (having a holding queue where we can slot it up to be processed)

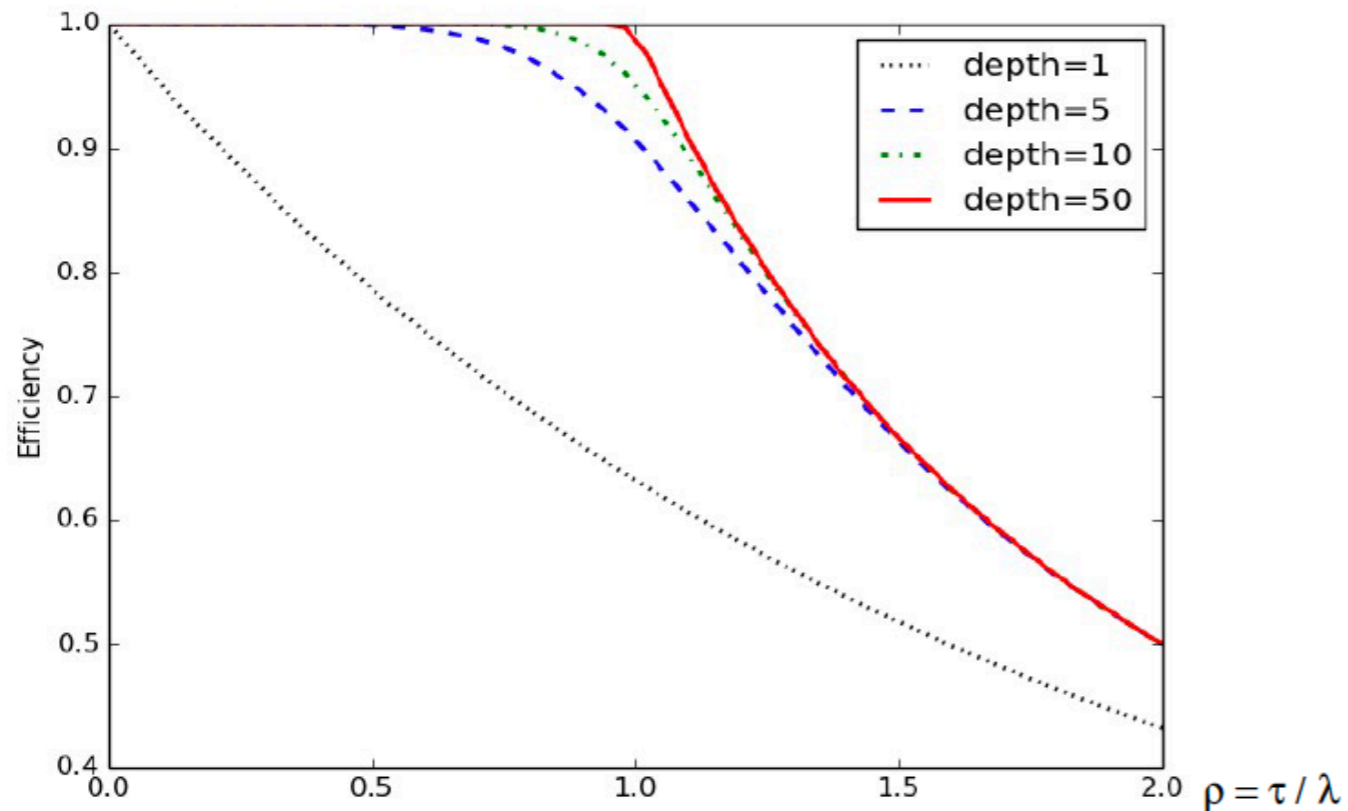


# DE-RANDOMIZING



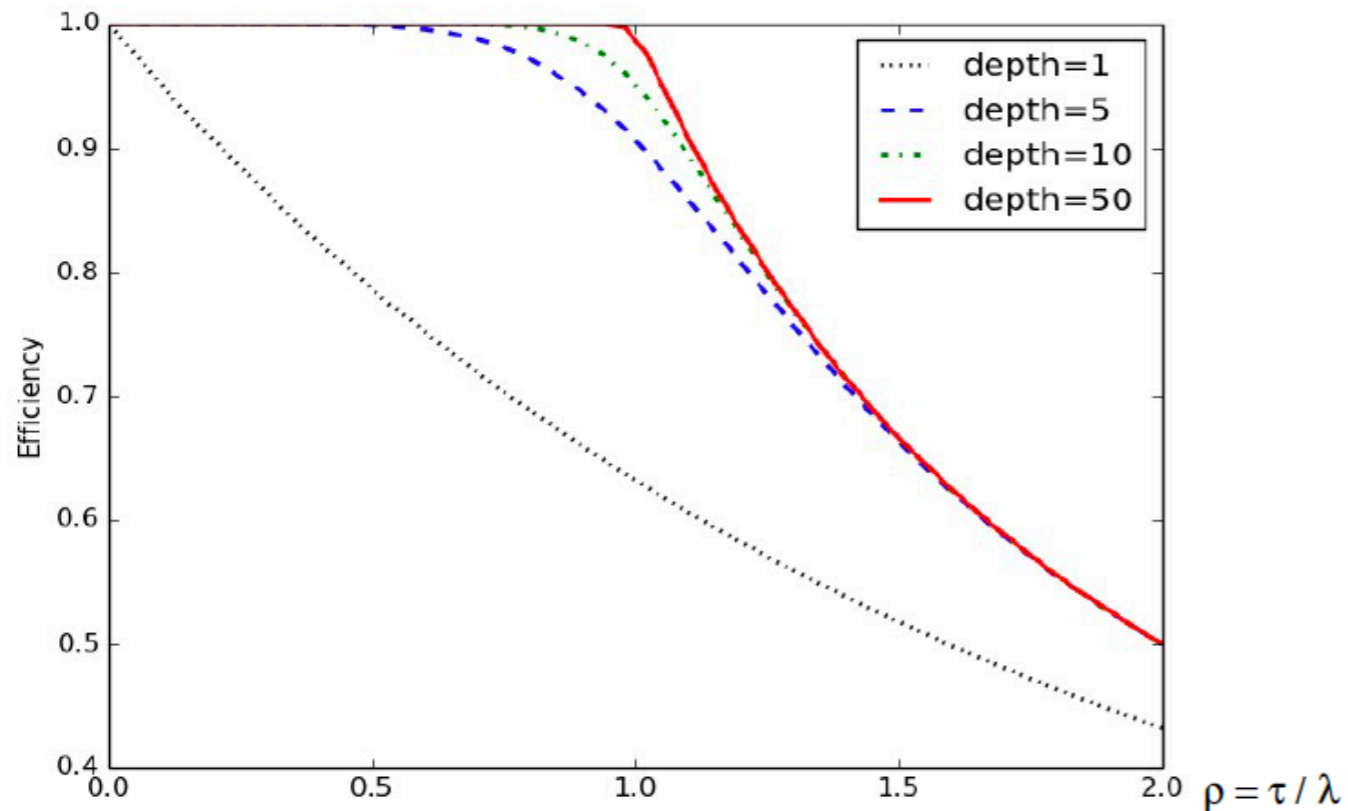
- \* Busy is now defined by if the buffer is full or not.
- \* Processor pulls data from the buffer at fixed rate, separating the event receiving and data processing steps

# QUEUEING THEORY



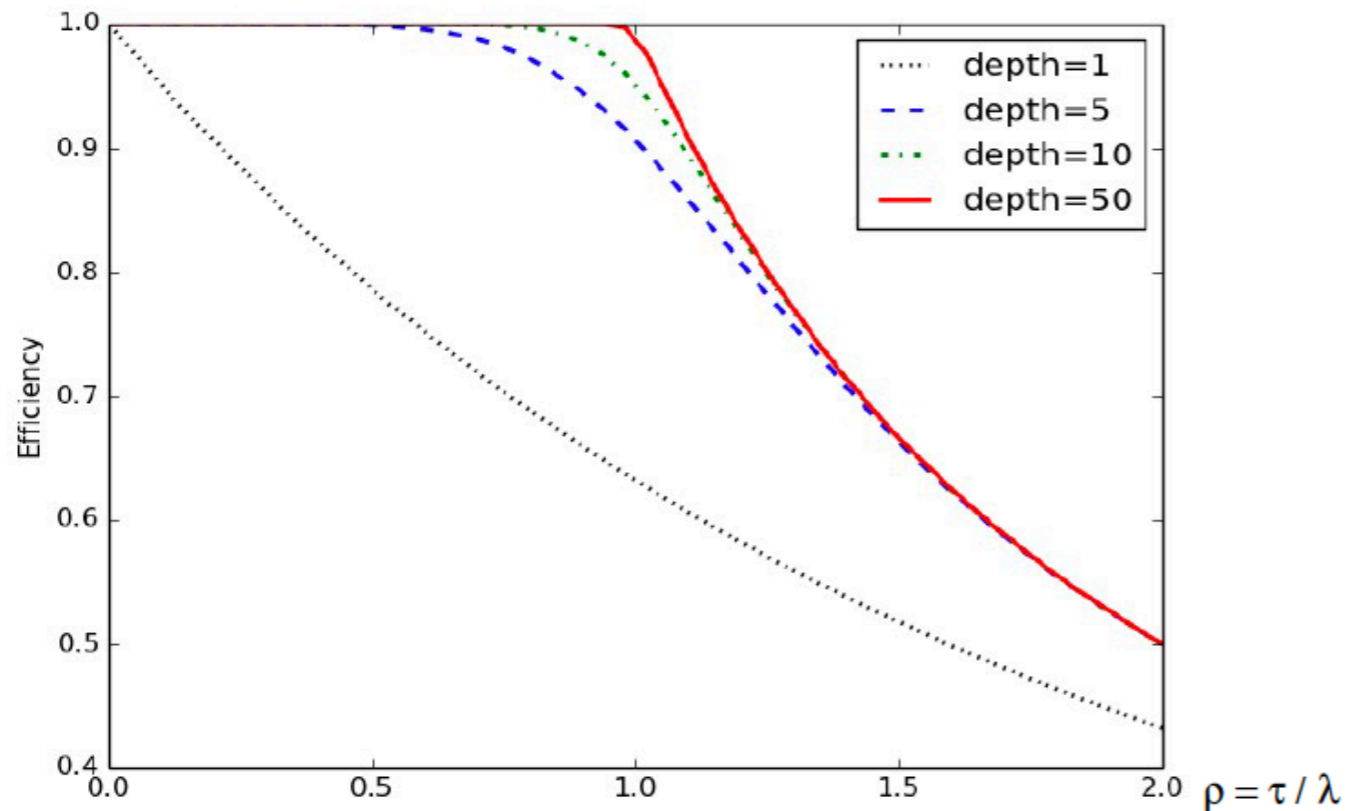
- Efficiency as a function of the ratio of the event processing time ( $\tau$ ) to average event arrival time ( $\lambda$ )
- Qualitatively describe the system for:
  - $\rho > 1$  :
  - $\rho \sim 1$  :
  - $\rho \ll 1$  :

# QUEUEING THEORY



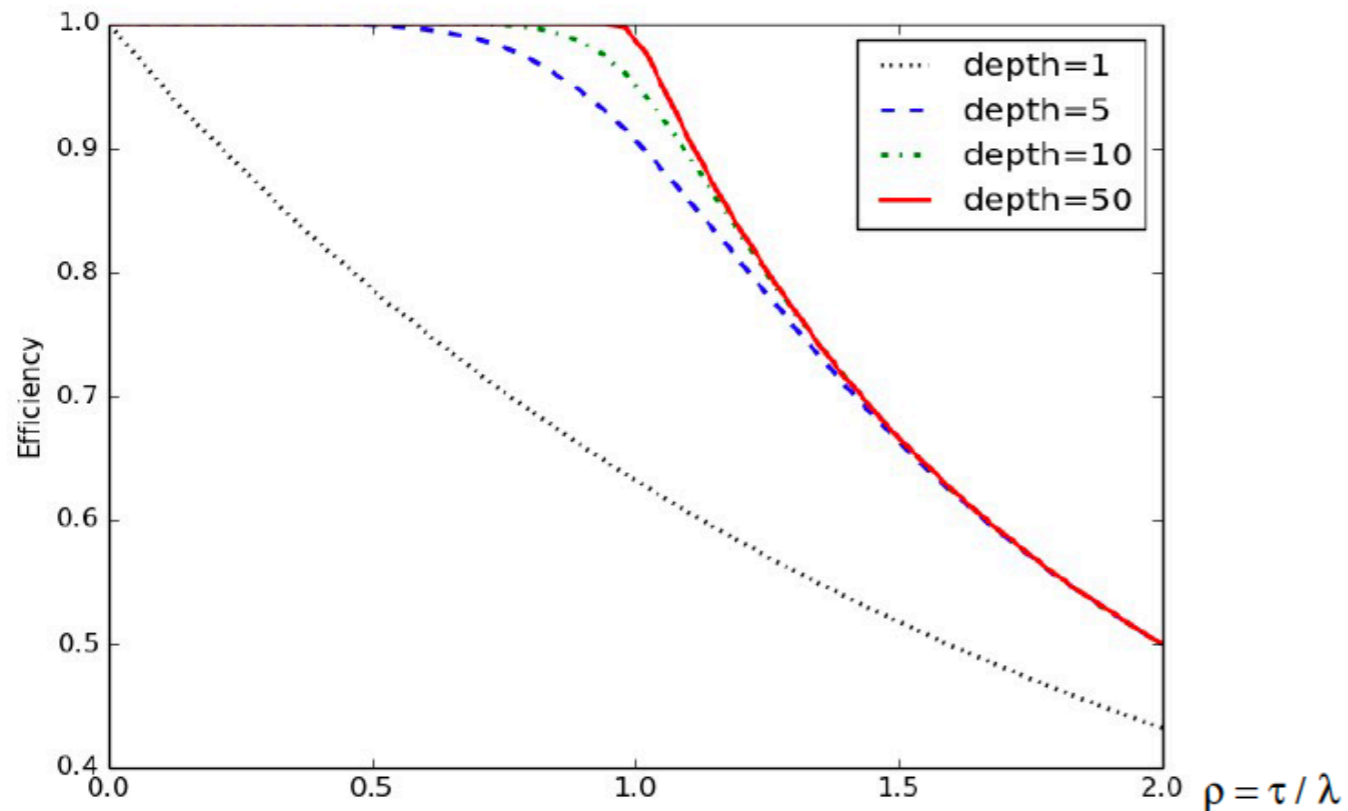
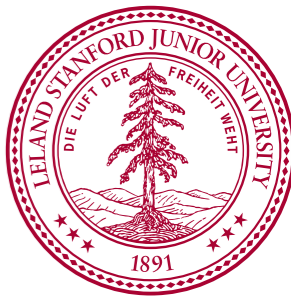
- Efficiency as a function of the ratio of the event processing time ( $\tau$ ) to average event arrival time ( $\lambda$ )
- Qualitatively describe the system for:
  - $\rho > 1$  : overloaded system — loose efficiency rapidly
  - $\rho \sim 1$  :
  - $\rho \ll 1$  :

# QUEUEING THEORY



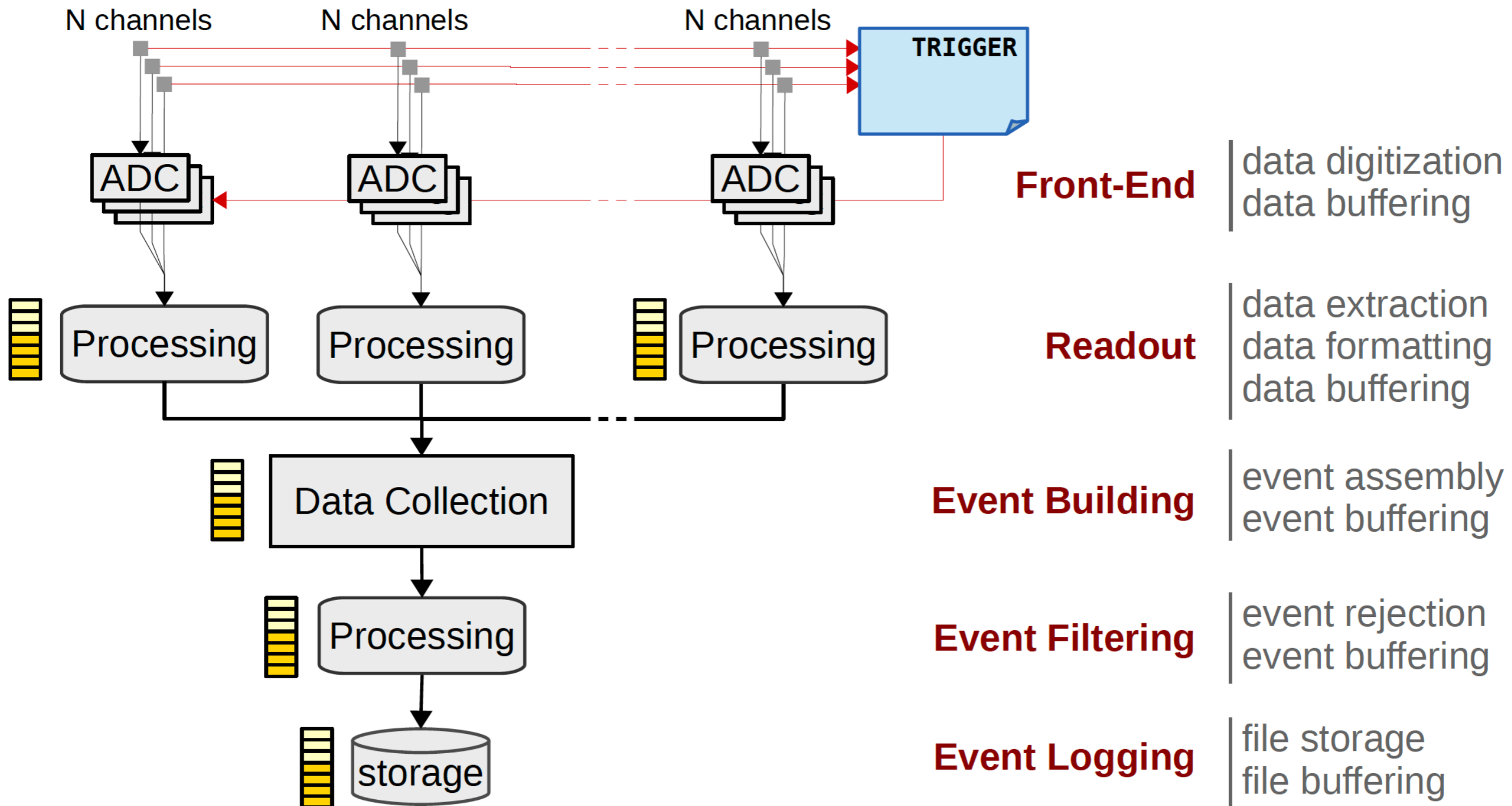
- Efficiency as a function of the ratio of the event processing time ( $\tau$ ) to average event arrival time ( $\lambda$ )
- Qualitatively describe the system for:
  - $\rho > 1$  : overloaded system — loose efficiency rapidly
  - $\rho \sim 1$  : Efficiency high and dependent on length of queue
  - $\rho \ll 1$  :

# QUEUEING THEORY

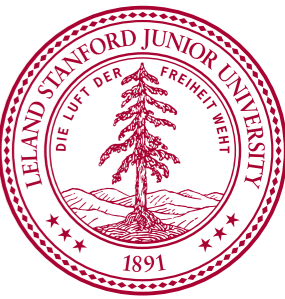


- Efficiency as a function of the ratio of the event processing time ( $\tau$ ) to average event arrival time ( $\lambda$ )
- Qualitatively describe the system for:
  - $\rho > 1$  : overloaded system — loose efficiency rapidly
  - $\rho \sim 1$  : Efficiency high and dependent on length of queue
  - $\rho \ll 1$  : system efficient but over designed

# GENERALIZING TO MULTI-CHANNEL SYSTEM

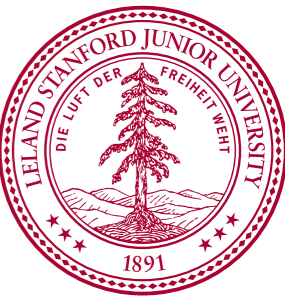


THAT EXAMPLE WAS CUTE, BUT WHAT  
ABOUT THE LHC?





# THAT EXAMPLE WAS CUTE, BUT WHAT ABOUT THE LHC?



- What are the similarities & differences?

# THAT EXAMPLE WAS CUTE, BUT WHAT ABOUT THE LHC?



- What are the similarities & differences?
  - Fixed frequency of LHC collisions means you don't need to have continuous readout

# THAT EXAMPLE WAS CUTE, BUT WHAT ABOUT THE LHC?



- What are the similarities & differences?
  - Fixed frequency of LHC collisions means you don't need to have continuous readout
  - But events are still random —> de-randomization is needed!

# THAT EXAMPLE WAS CUTE, BUT WHAT ABOUT THE LHC?



- What are the similarities & differences?
  - Fixed frequency of LHC collisions means you don't need to have continuous readout
  - But events are still random —> de-randomization is needed!
- Remainder of today and tomorrow's lectures are going to explain how these basic concepts are applied to the LHC trigger & data acquisition problem now and in the the future

# THE REST OF THE LECTURES



- Overview of the current ATLAS & CMS TDAQ architecture

- ATLAS Level 1 Trigger & DAQ

Today

- CMS High Level Trigger & DAQ

Tomorrow

- How triggers are constructed for the LHC environment

- The art of menu building

- Creative solutions to challenging conditions

- Looking forward to the upgrades

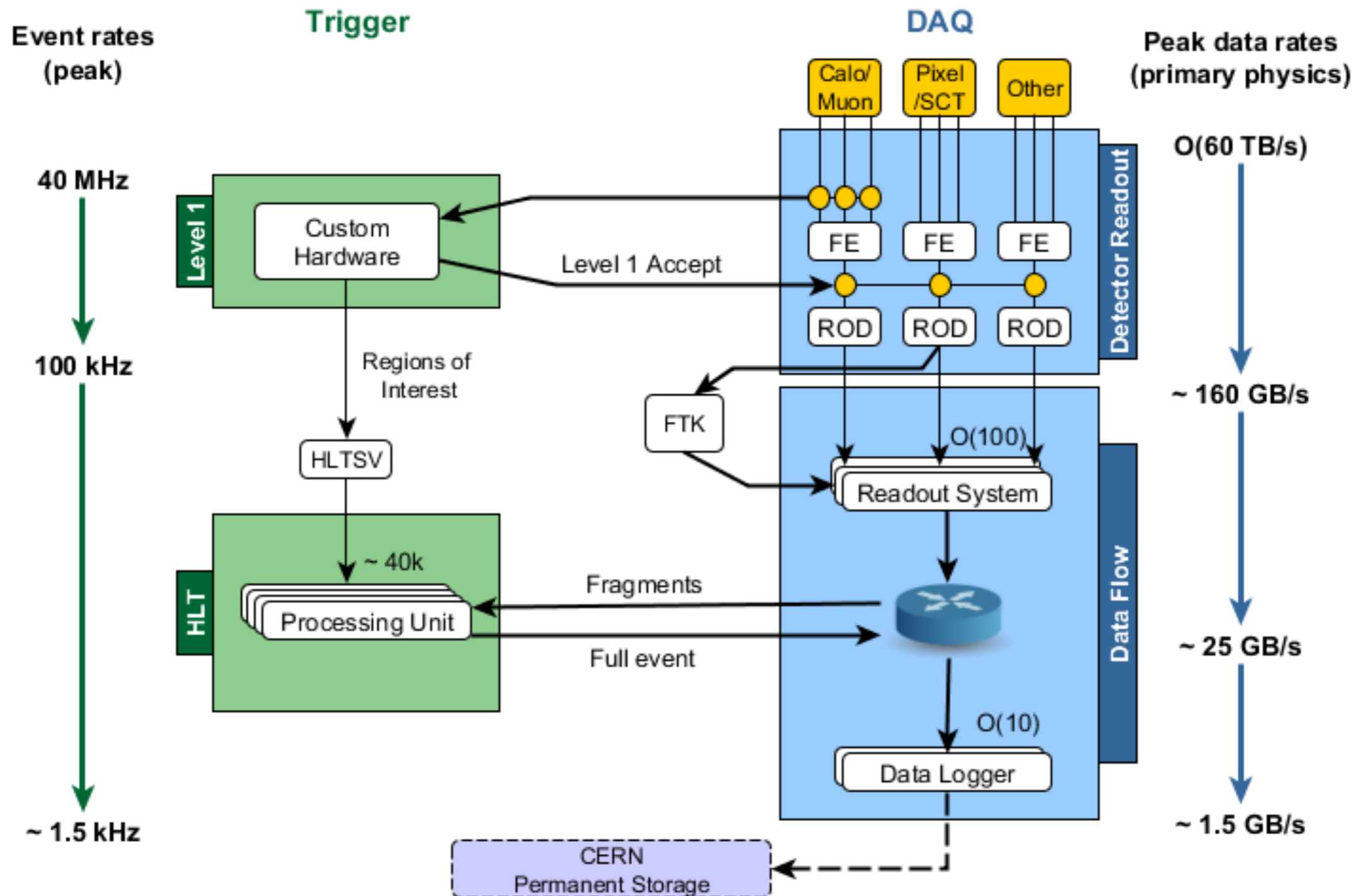
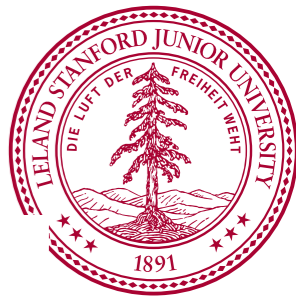
- LHCb: The trigger-less future?

- Contending with 200 simultaneous collisions

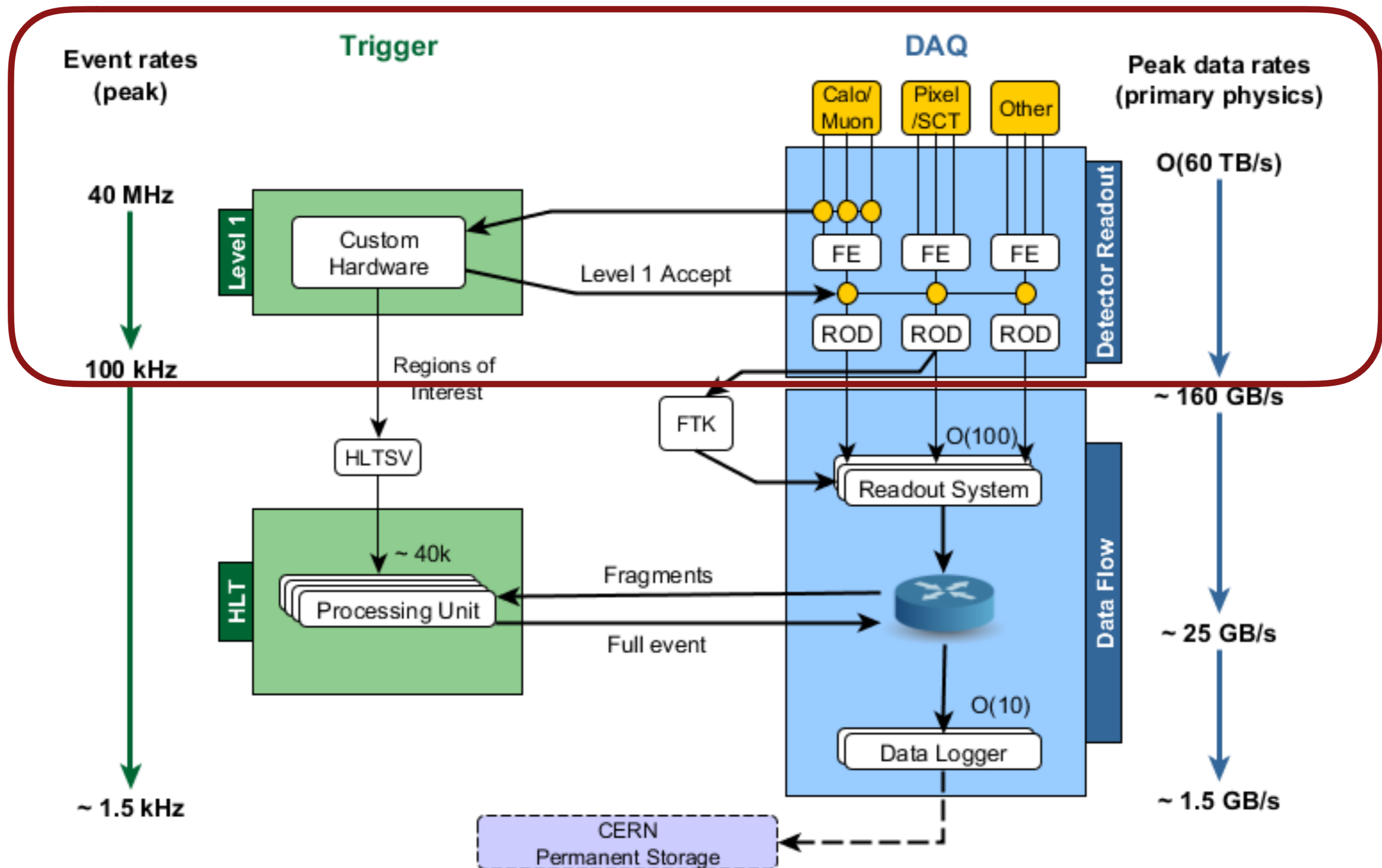
# TDAQ: CMS & ATLAS

## STYLE

# ATLAS RUN II TDAQ SYSTEM

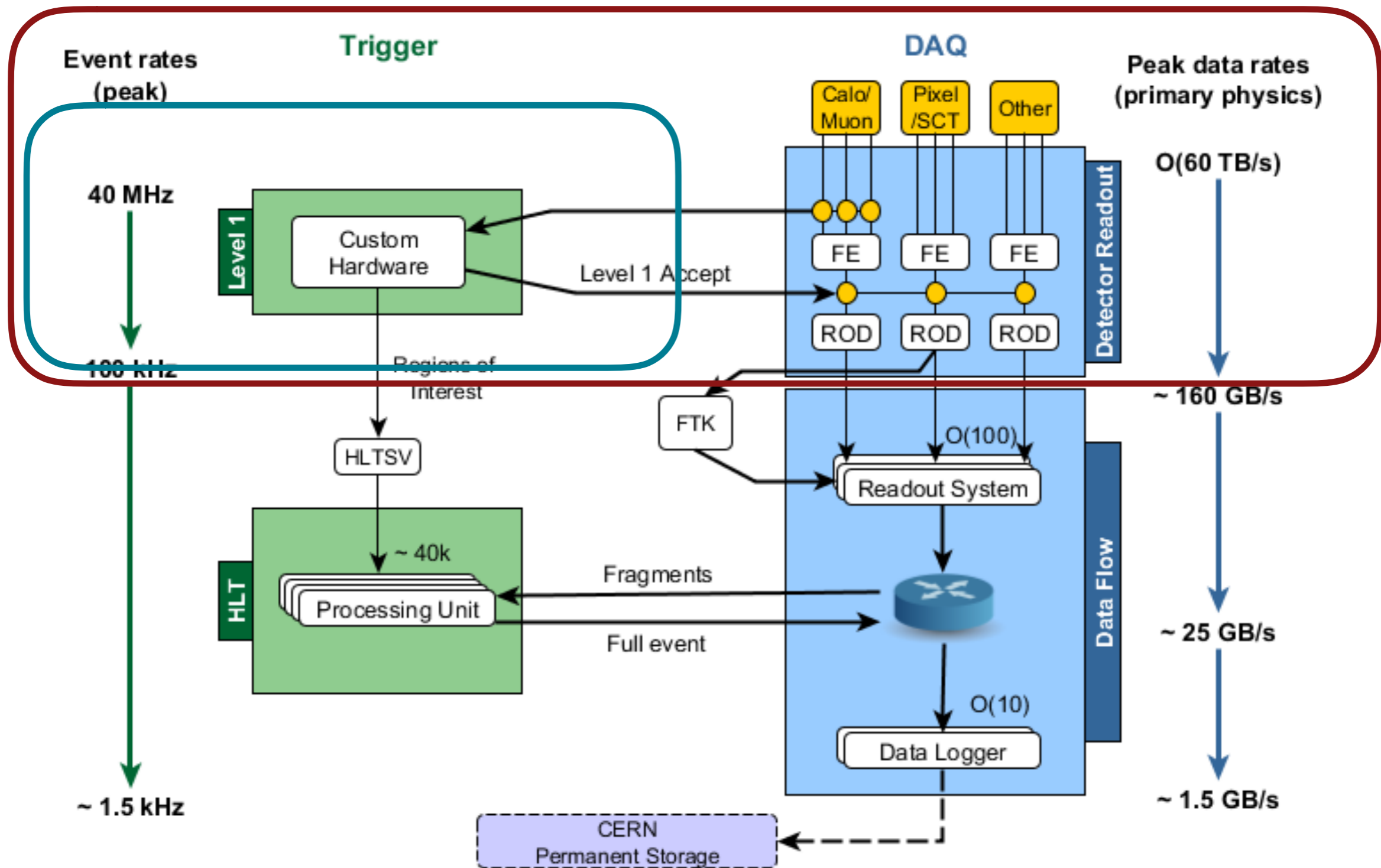


# ATLAS RUN II TDAQ SYSTEM

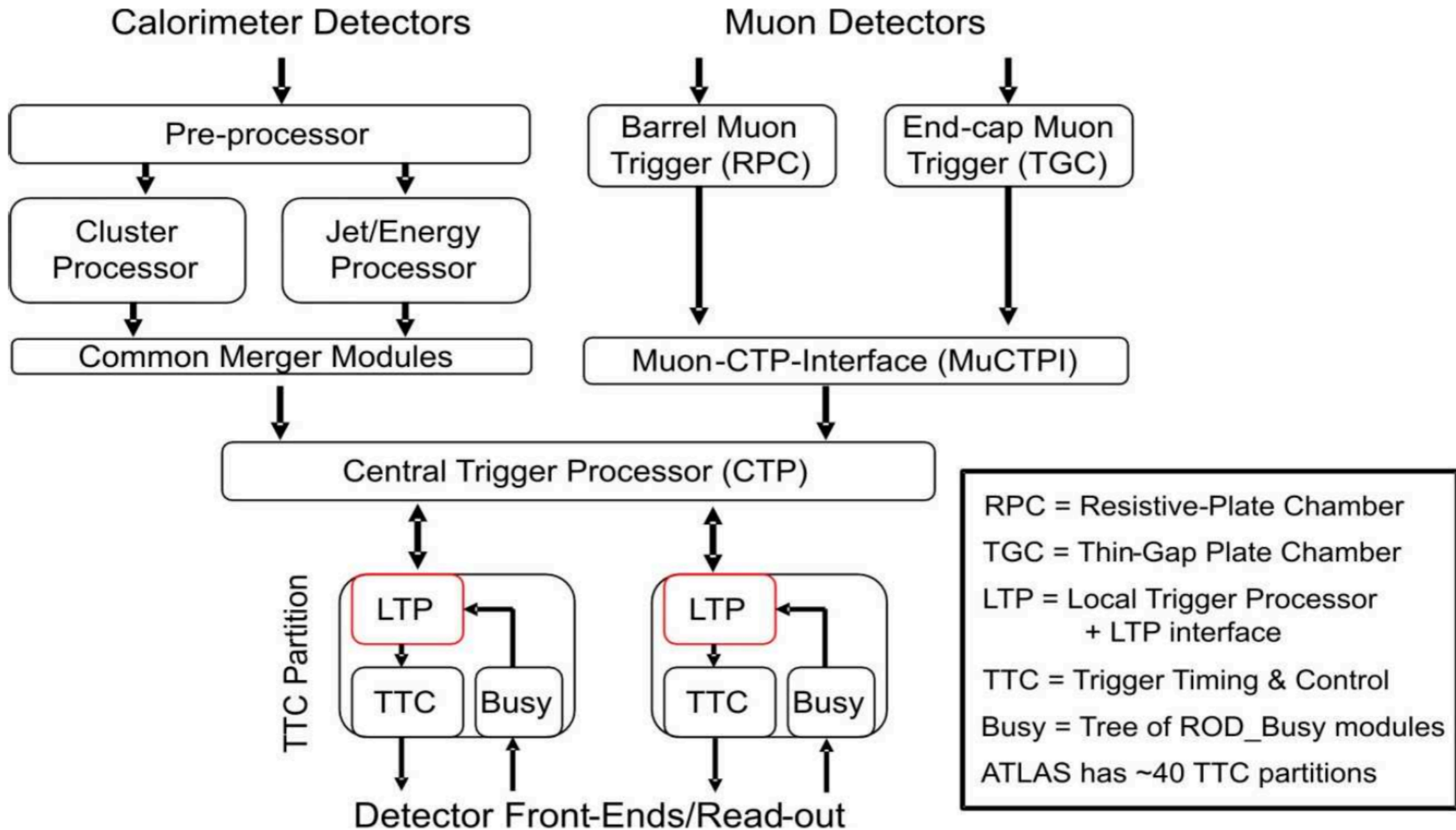
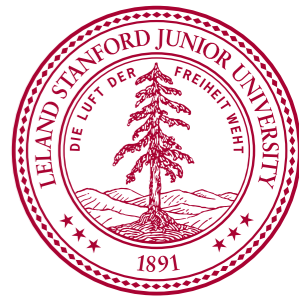




# ATLAS RUN II TDAQ SYSTEM

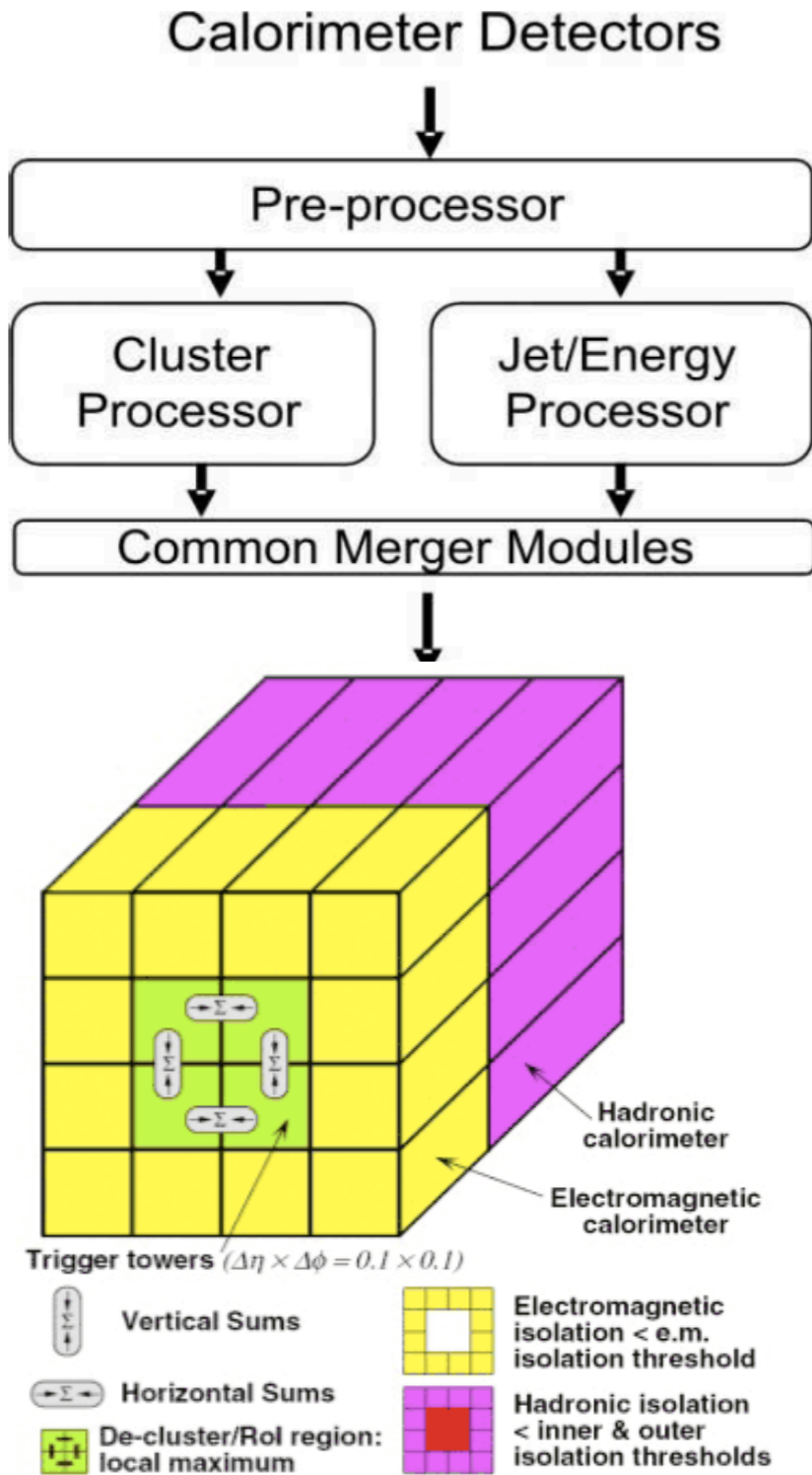
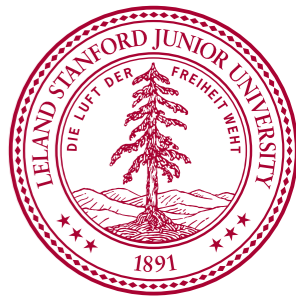


# ATLAS LEVEL 1 TRIGGER SYSTEM



[Fig. Ref](#)

# ATLAS LEVEL 1 TRIGGER SYSTEM



[Fig. Ref](#)

# ATLAS LEVEL 1 TRIGGER SYSTEM

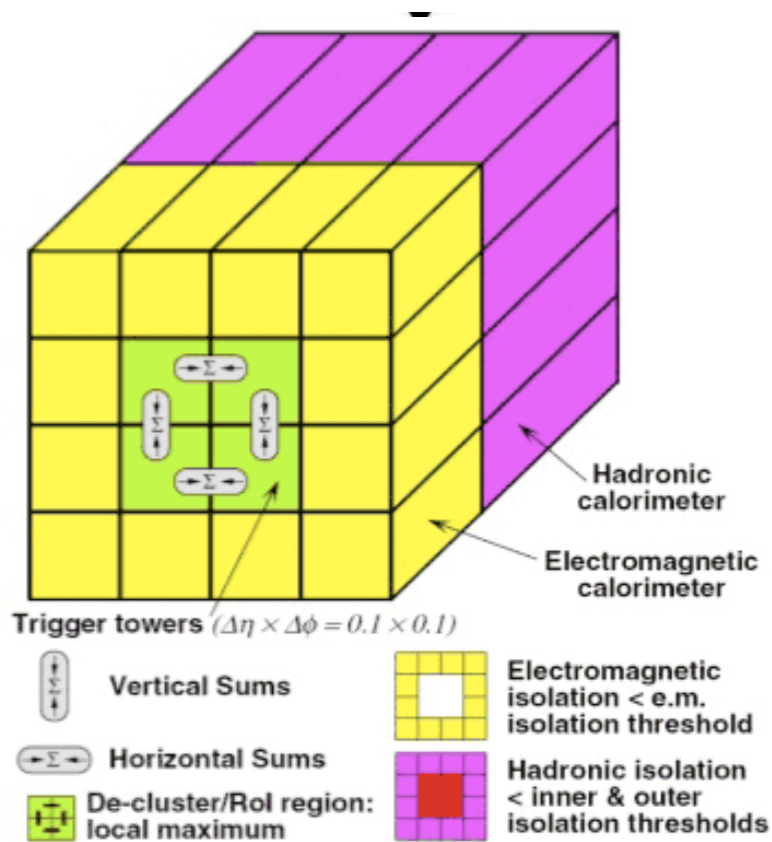
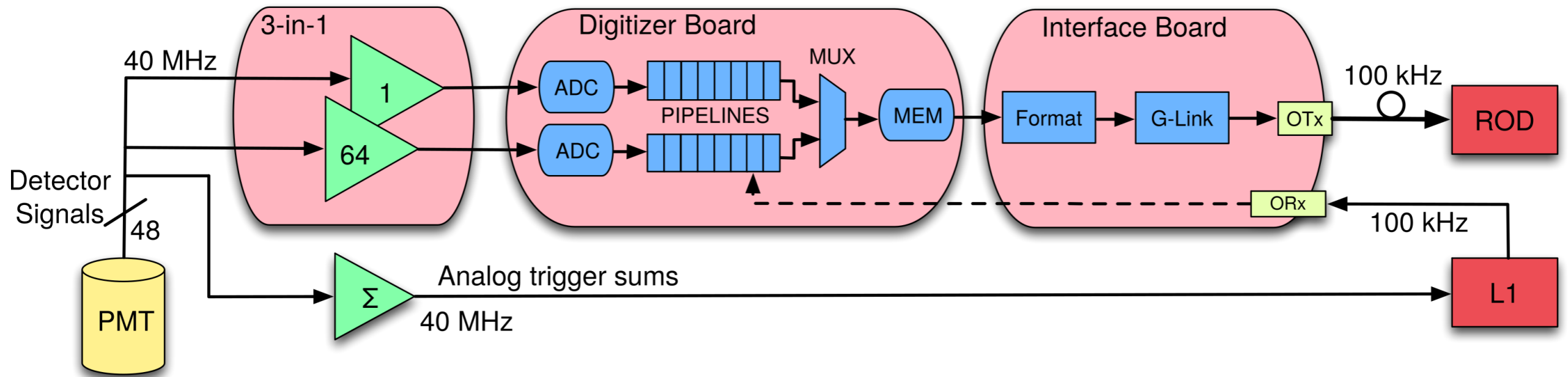
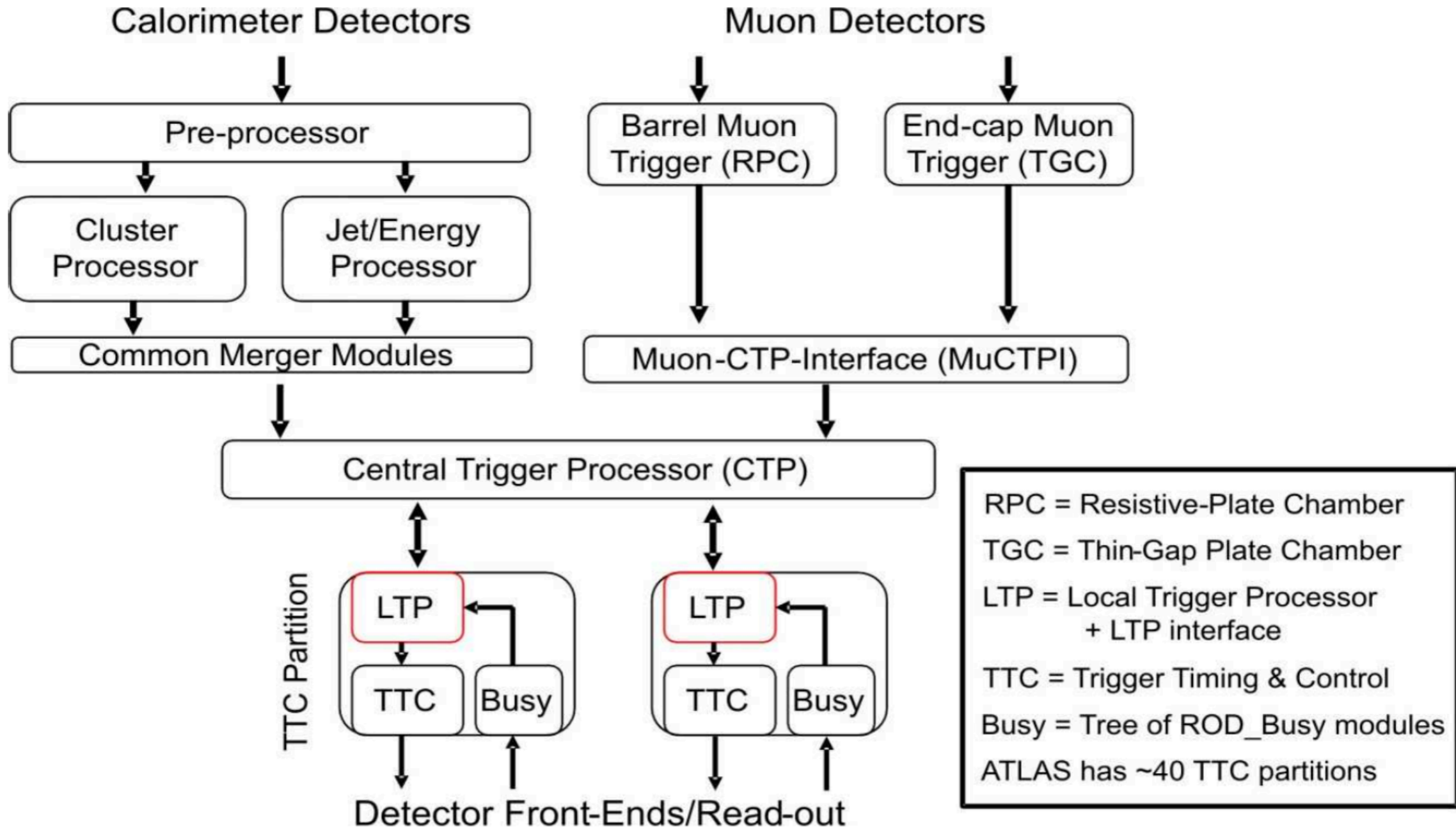


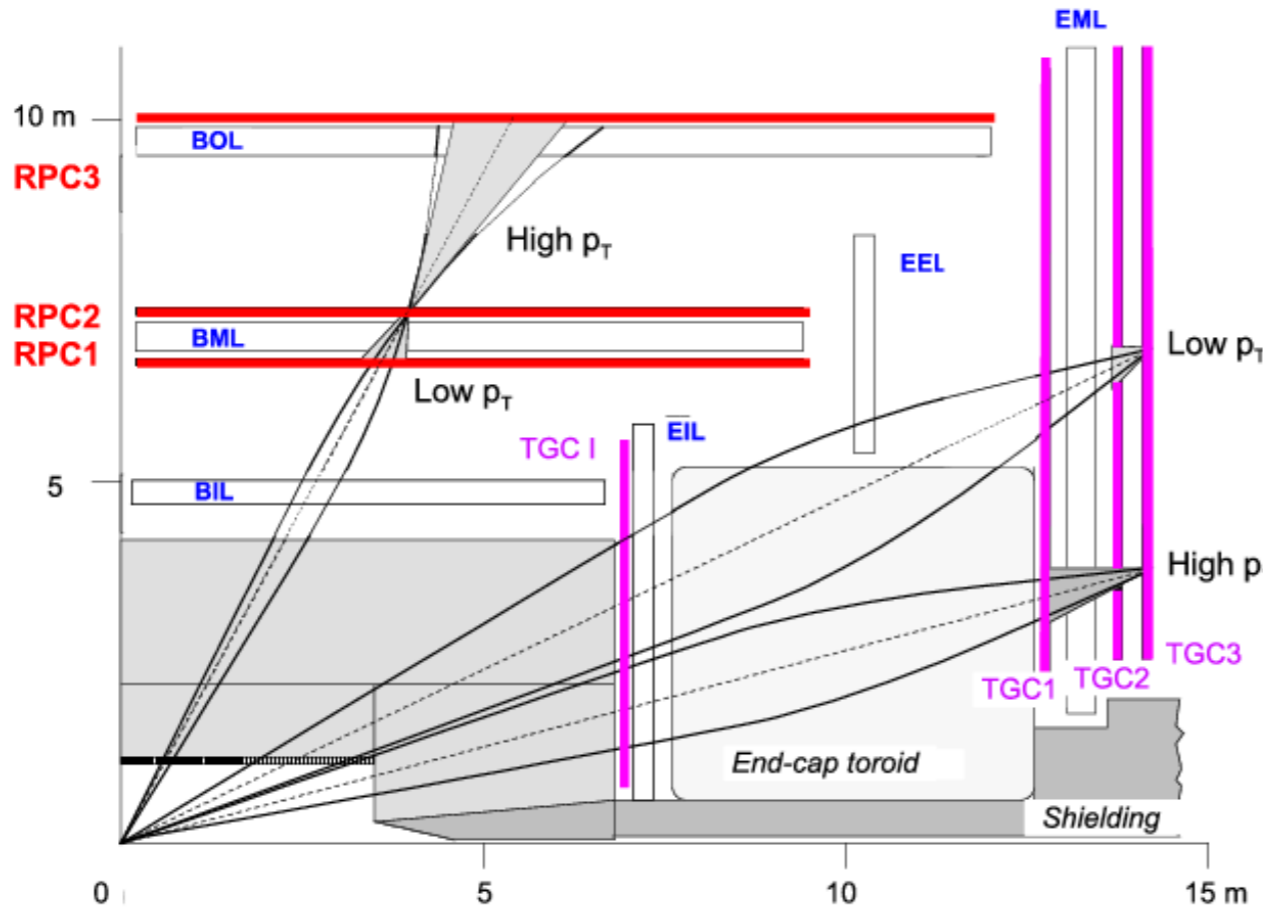
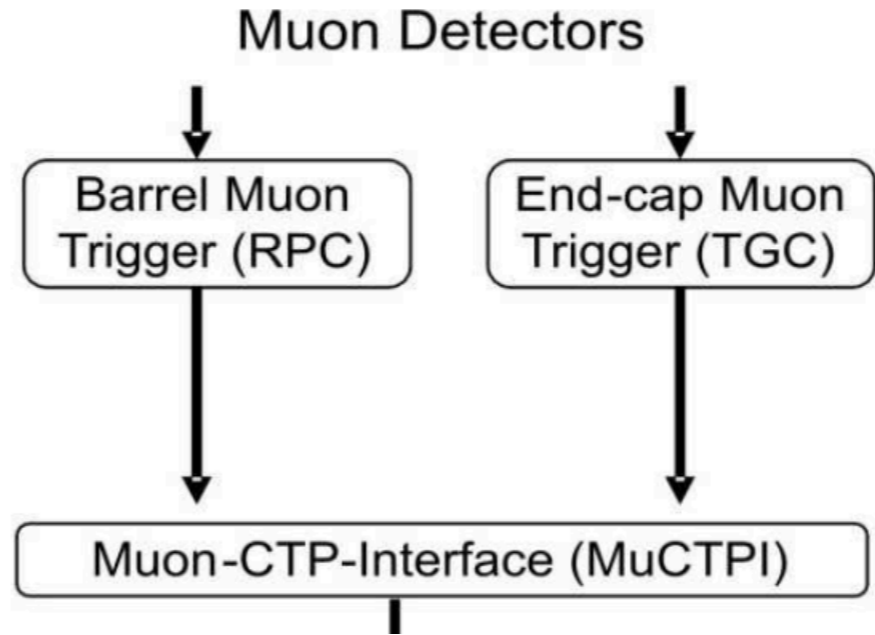
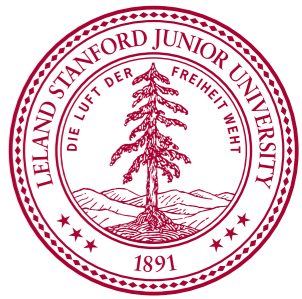
Fig. Ref

# ATLAS LEVEL 1 TRIGGER SYSTEM



[Fig. Ref](#)

# ATLAS LEVEL 1 TRIGGER SYSTEM



[Fig. Ref](#)

# TOPOLOGICAL TRIGGERS

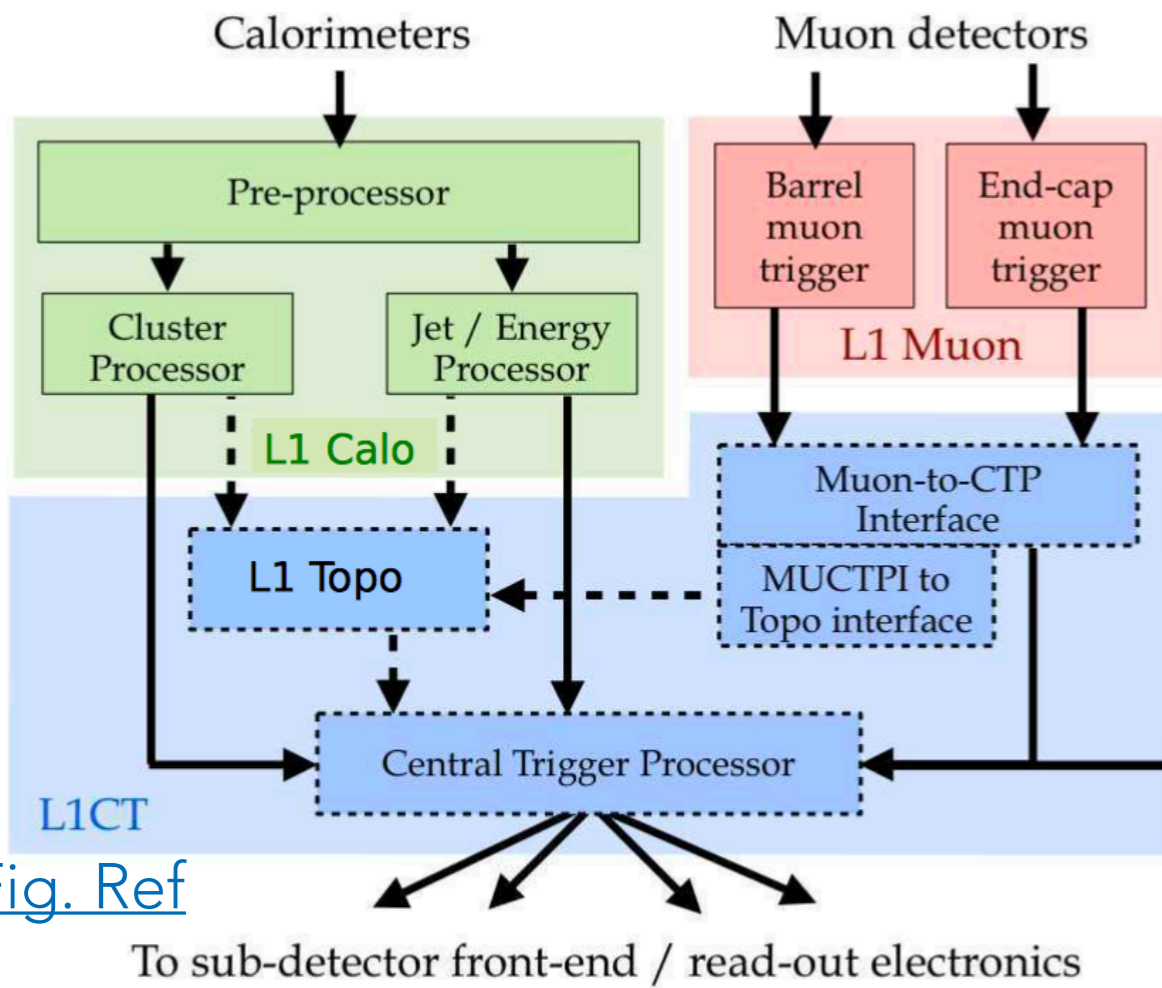


Fig. Ref

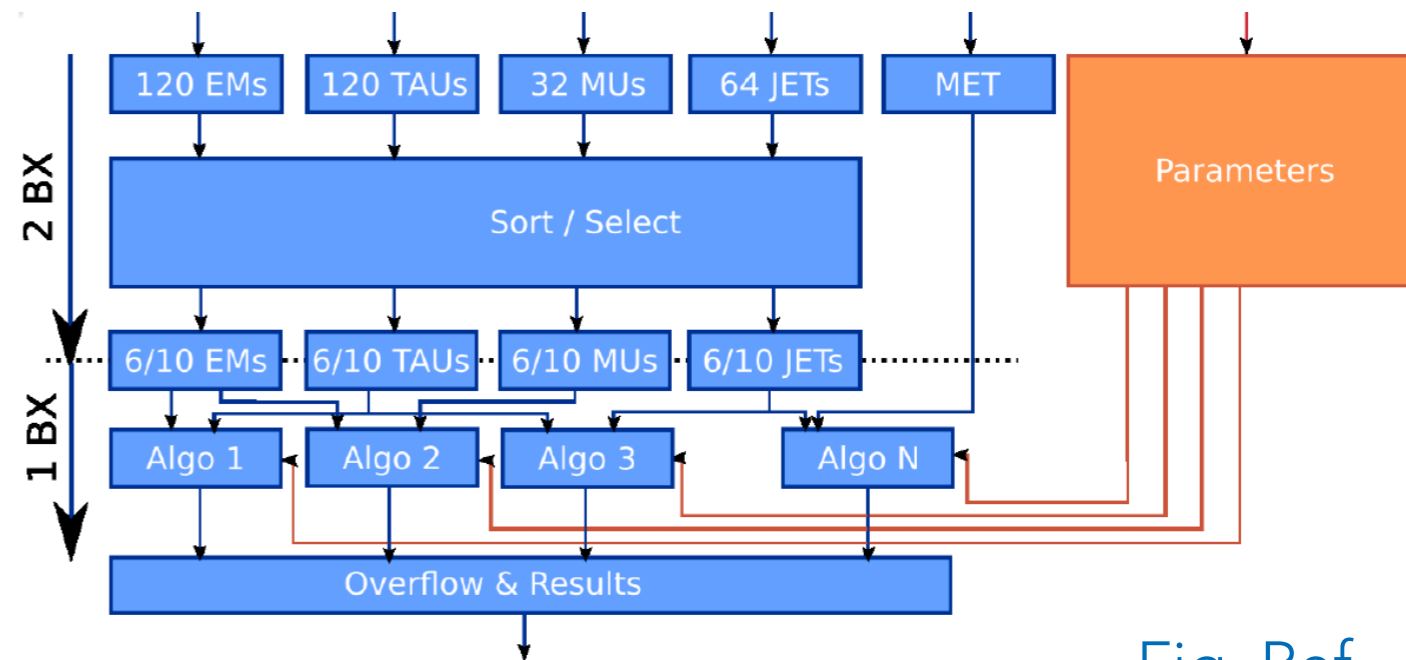
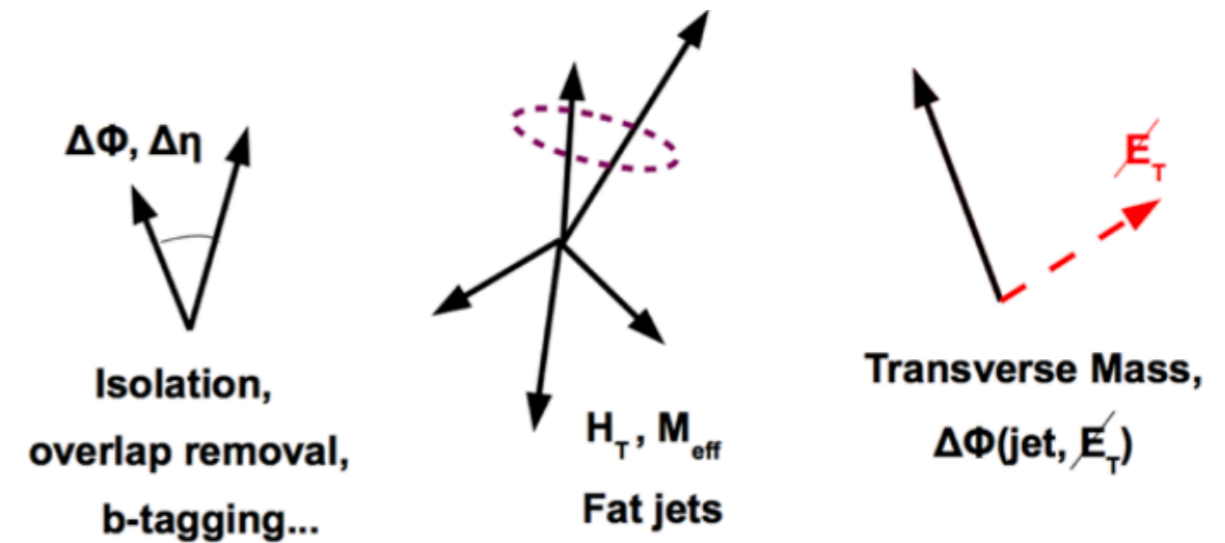
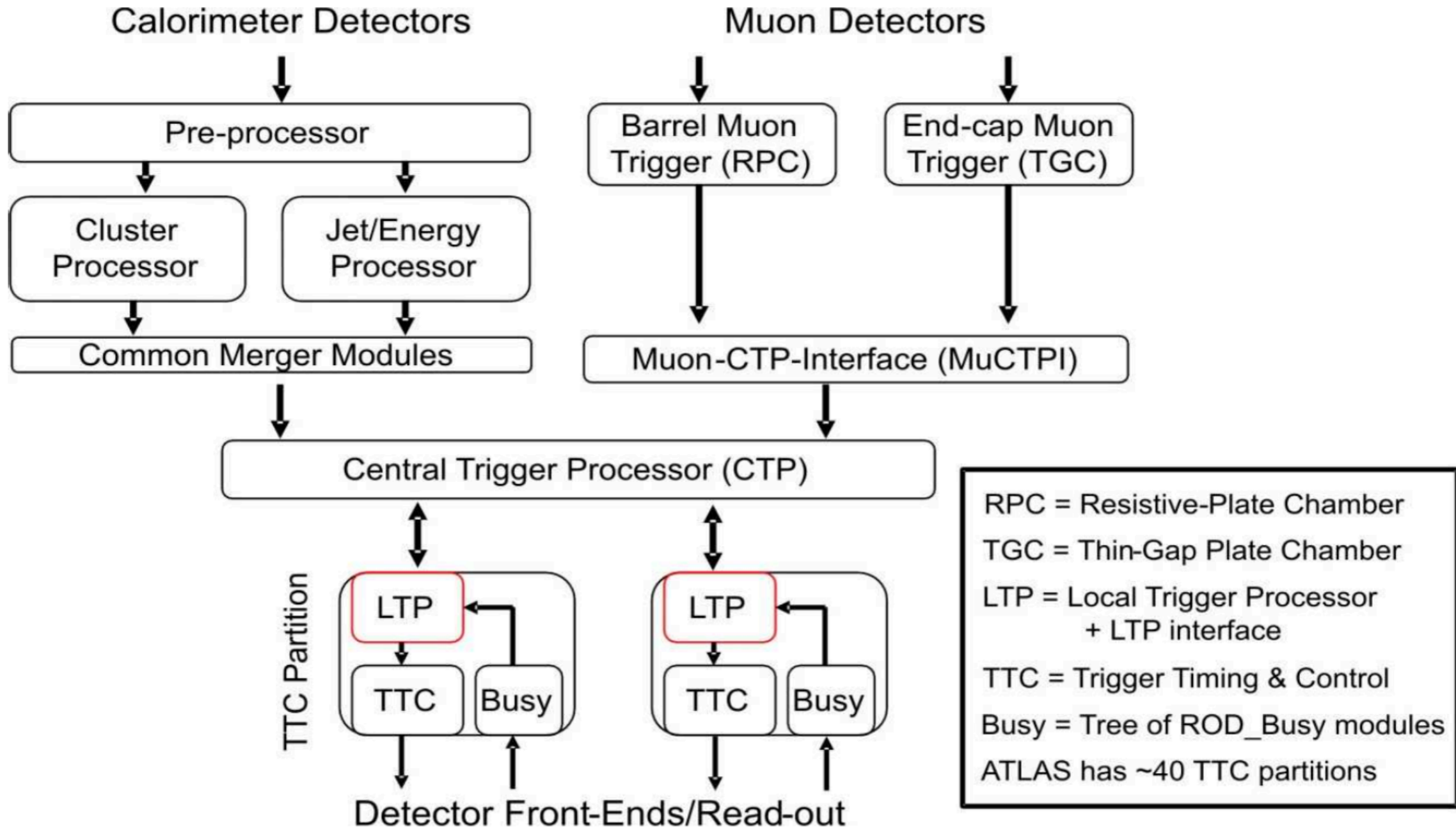


Fig. Ref

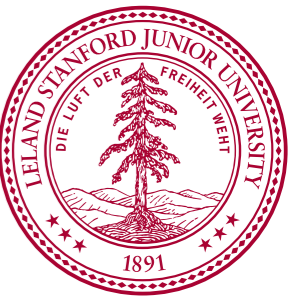
# ATLAS LEVEL 1 TRIGGER SYSTEM



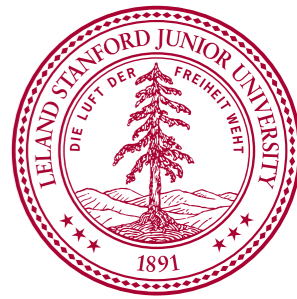
[Fig. Ref](#)



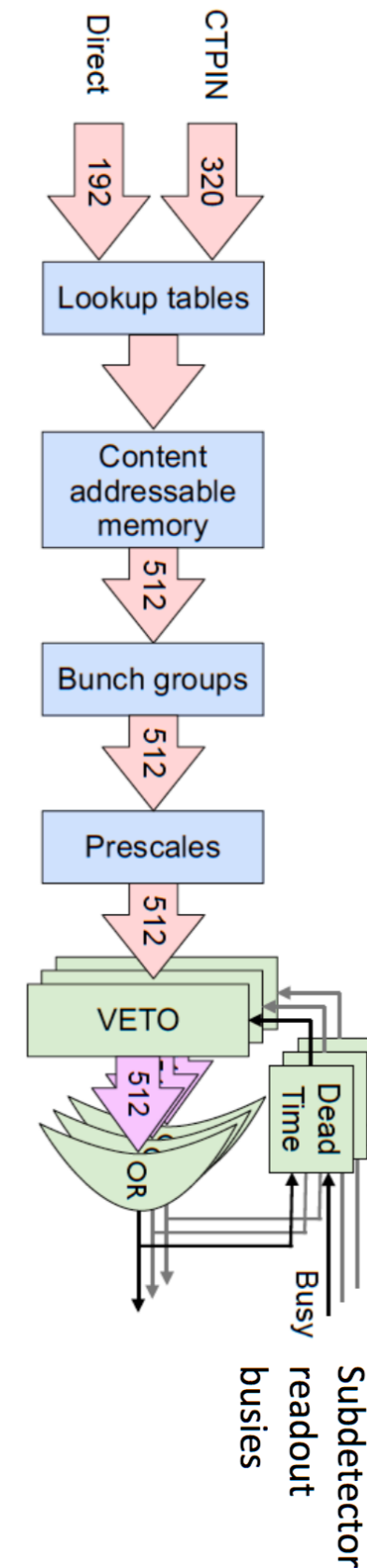
# CENTRAL TRIGGER PROCESSOR & TIMING TRIGGER AND CONTROL SYSTEM



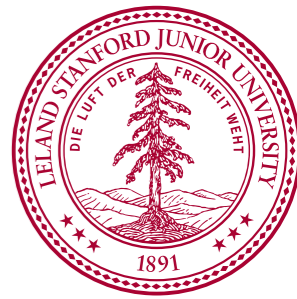
# CENTRAL TRIGGER PROCESSOR & TIMING TRIGGER AND CONTROL SYSTEM



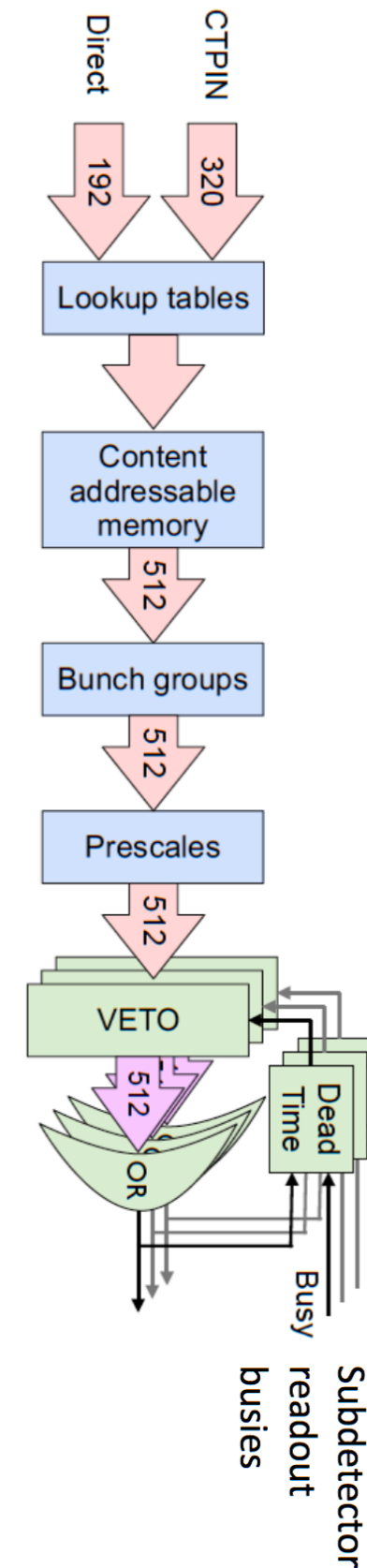
- Central Trigger Processor (CTP) and the Trigger Timing and Control (TTC) form the brains of the Level-1 Trigger:



# CENTRAL TRIGGER PROCESSOR & TIMING TRIGGER AND CONTROL SYSTEM



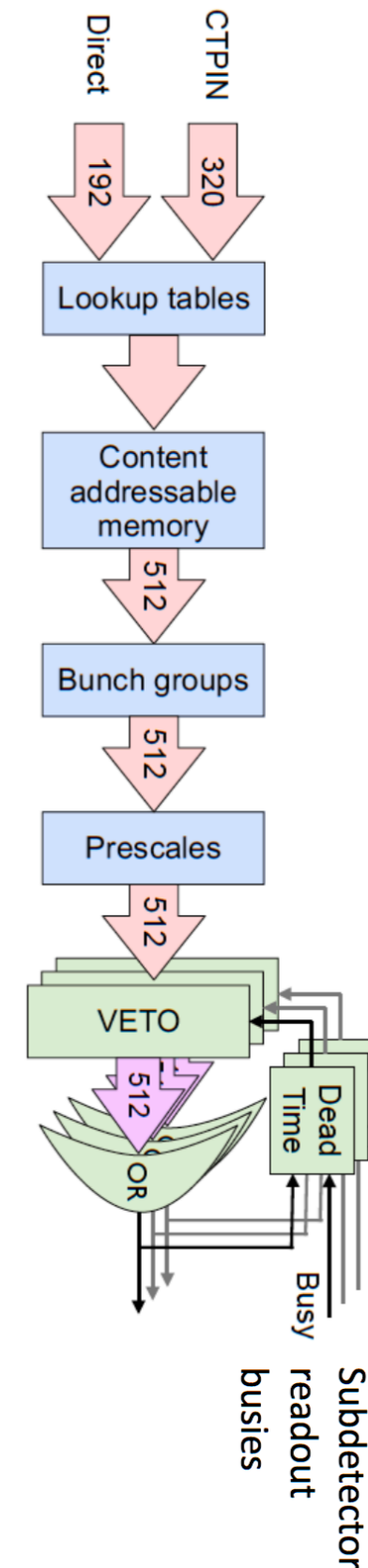
- Central Trigger Processor (CTP) and the Trigger Timing and Control (TTC) form the brains of the Level-1 Trigger:
  - Takes primitives from L1Calo/L1Muon/L1Topo and determines trigger decisions



# CENTRAL TRIGGER PROCESSOR & TIMING TRIGGER AND CONTROL SYSTEM



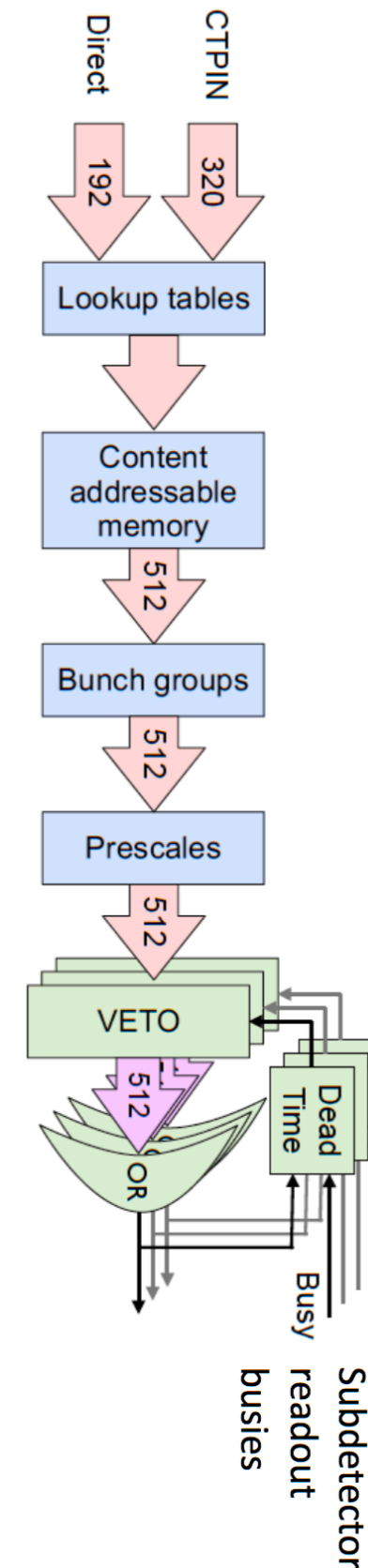
- Central Trigger Processor (CTP) and the Trigger Timing and Control (TTC) form the brains of the Level-1 Trigger:
  - Takes primitives from L1Calo/L1Muon/L1Topo and determines trigger decisions
  - Produces Level 1 Accept (L1A), a unique event identifier which is used, along with Bunch Crossing ID, to synchronize **pushed** data to the rest of the system



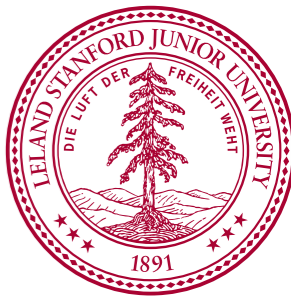
# CENTRAL TRIGGER PROCESSOR & TIMING TRIGGER AND CONTROL SYSTEM



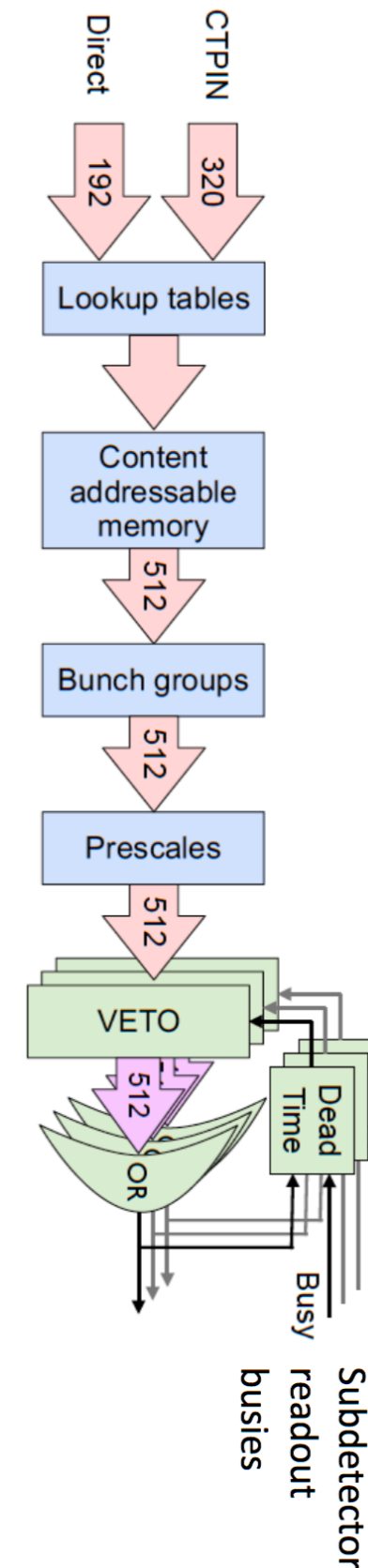
- Central Trigger Processor (CTP) and the Trigger Timing and Control (TTC) form the brains of the Level-1 Trigger:
  - Takes primitives from L1Calo/L1Muon/L1Topo and determines trigger decisions
  - Produces Level 1 Accept (L1A), a unique event identifier which is used, along with Bunch Crossing ID, to synchronize **pushed** data to the rest of the system
  - Provides a GPS-based UTC time stamp that is included in the trigger information that is sent to the readout system



# CENTRAL TRIGGER PROCESSOR & TIMING TRIGGER AND CONTROL SYSTEM



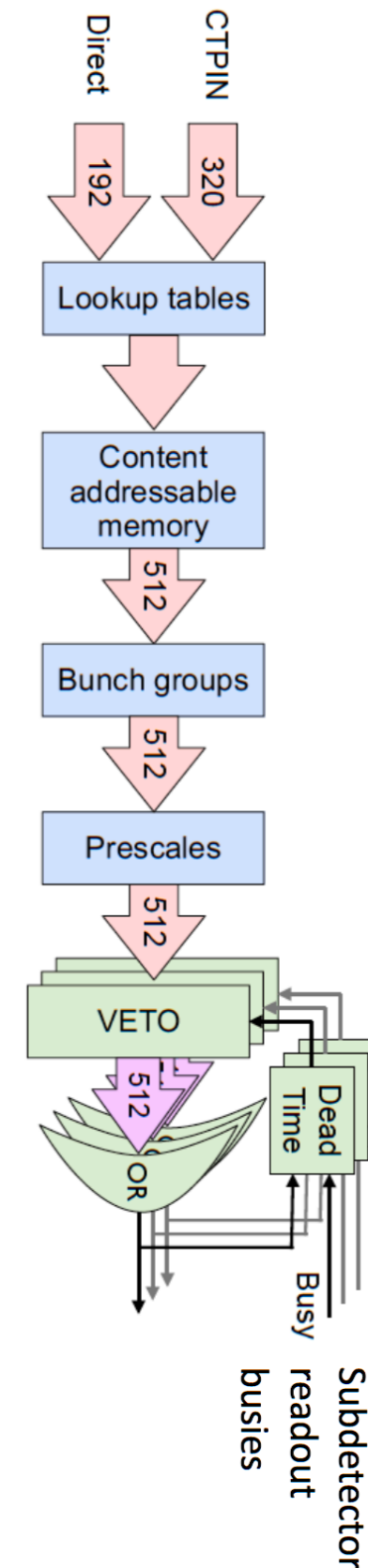
- Central Trigger Processor (CTP) and the Trigger Timing and Control (TTC) form the brains of the Level-1 Trigger:
  - Takes primitives from L1Calo/L1Muon/L1Topo and determines trigger decisions
  - Produces Level 1 Accept (L1A), a unique event identifier which is used, along with Bunch Crossing ID, to synchronize **pushed** data to the rest of the system
  - Provides a GPS-based UTC time stamp that is included in the trigger information that is sent to the readout system
  - Controls detector BUSY



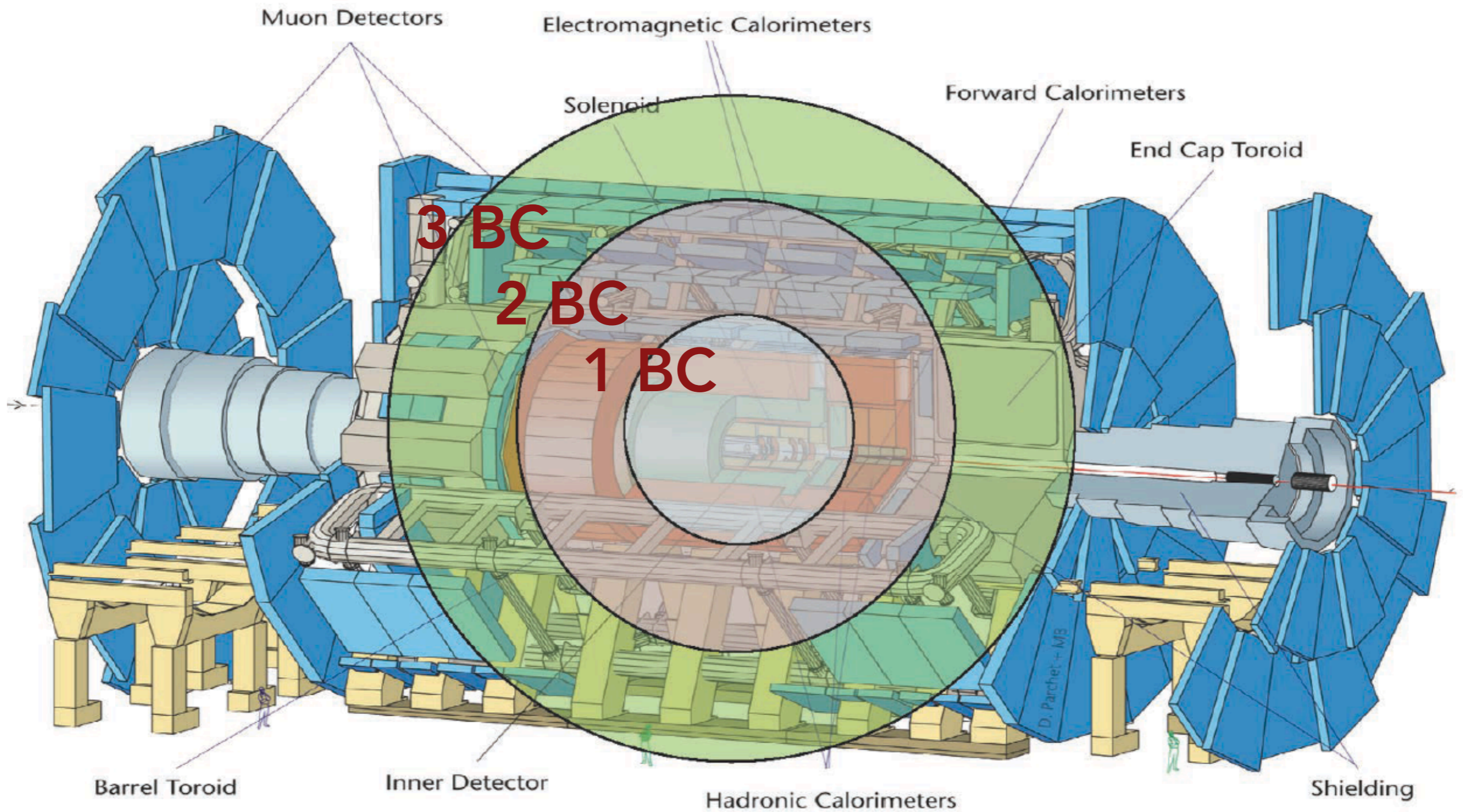
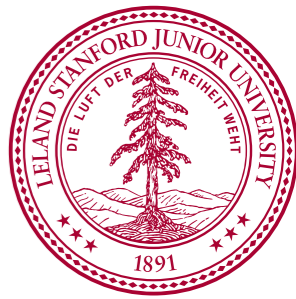
# CENTRAL TRIGGER PROCESSOR & TIMING TRIGGER AND CONTROL SYSTEM



- Central Trigger Processor (CTP) and the Trigger Timing and Control (TTC) form the brains of the Level-1 Trigger:
  - Takes primitives from L1Calo/L1Muon/L1Topo and determines trigger decisions
  - Produces Level 1 Accept (L1A), a unique event identifier which is used, along with Bunch Crossing ID, to synchronize **pushed** data to the rest of the system
  - Provides a GPS-based UTC time stamp that is included in the trigger information that is sent to the readout system
  - Controls detector BUSY
  - **All within 100ns**



# TIMING IS EVERYTHING

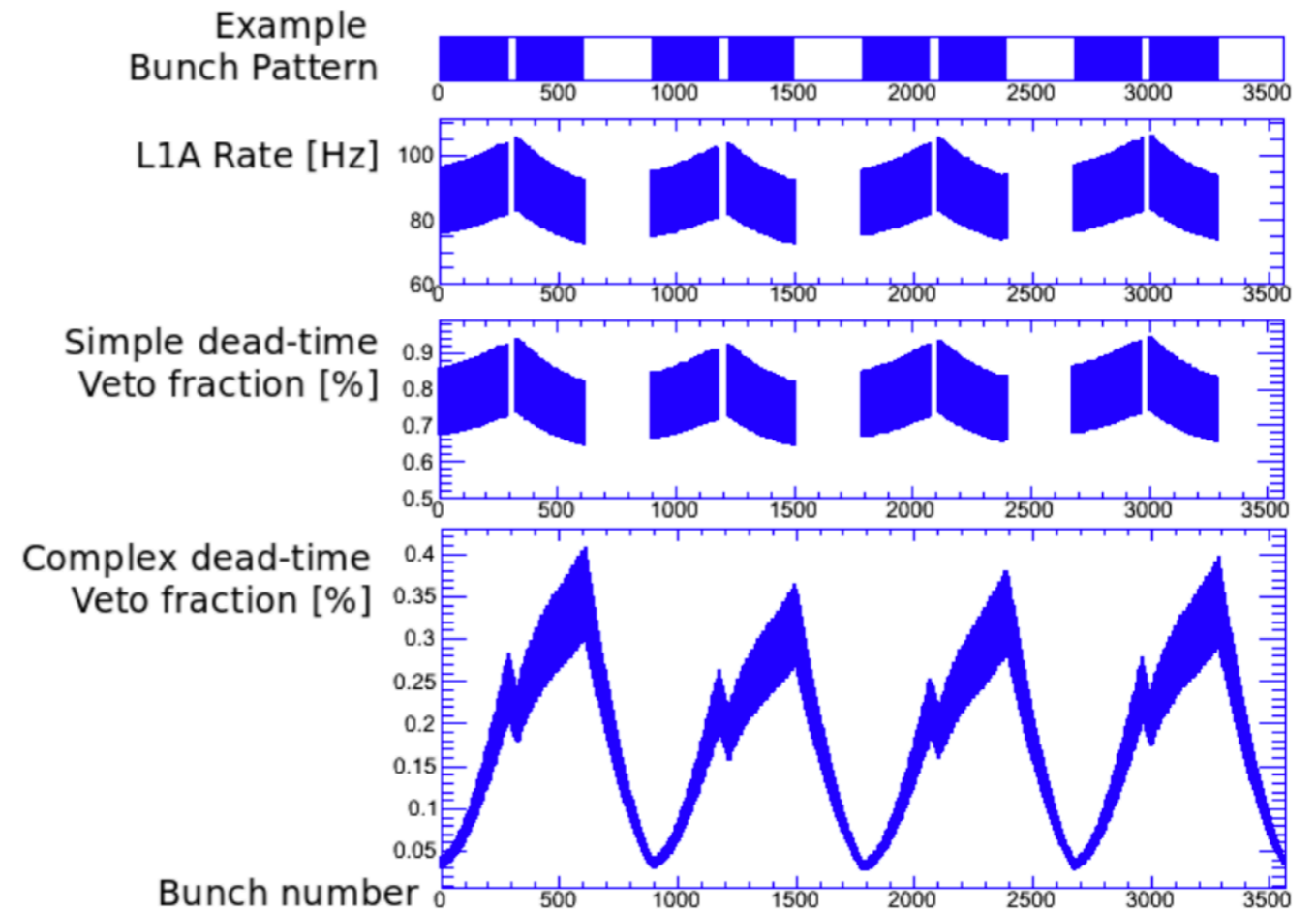




# ATLAS DEADTIME

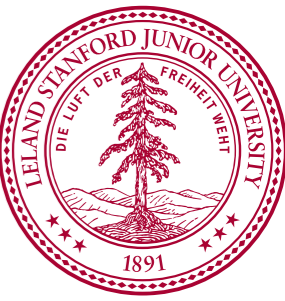


- Simple dead-time veto:
  - No new L1A after fixed number of BC
- Leaky-bucket Deadtime Algorithm:
  - Bucket leaks at rate  $R$
  - Contents increase by  $X$  at each L1A until full, then BUSY is asserted
  - Allows system to maintain high efficiency for data taking



[Fig. Ref](#)

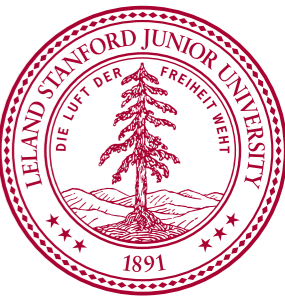
# ATLAS DEADTIME



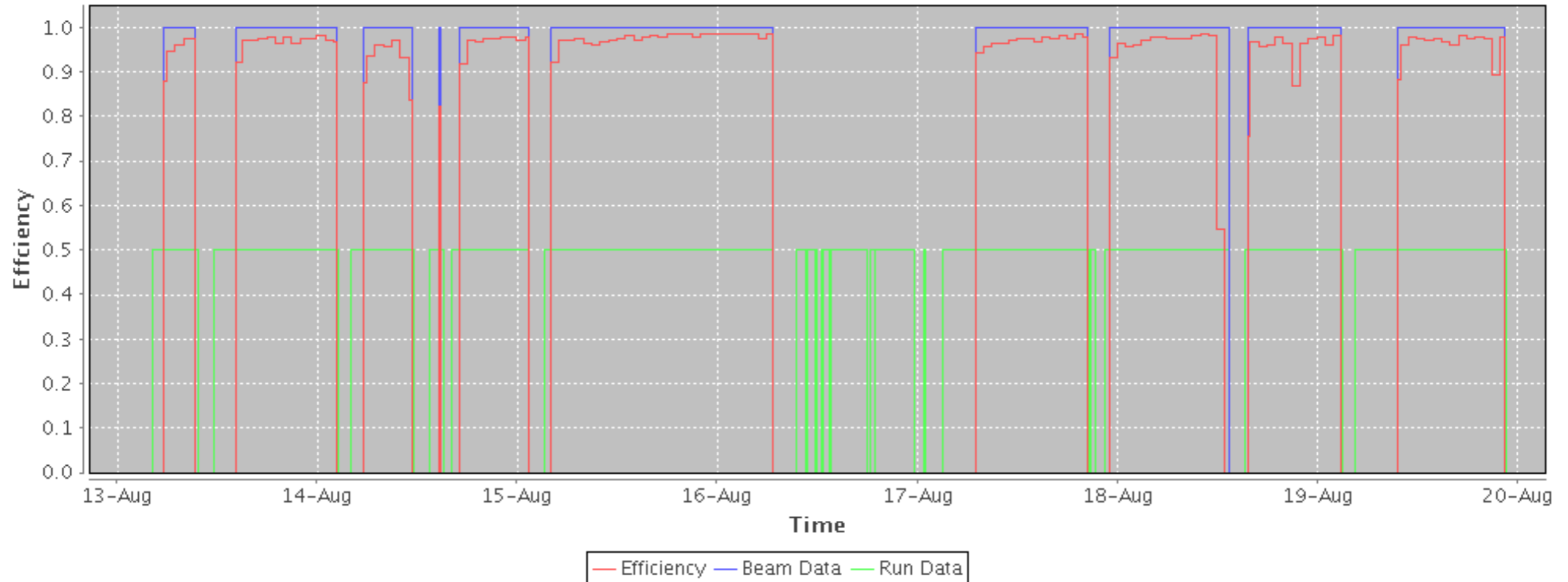
- Simple dead-time veto:
  - No new L1A after fixed number of BC
- Leaky-bucket Deadtime Algorithm:
  - Bucket leaks at rate  $R$
  - Contents increase by  $X$  at each L1A until full, then BUSY is asserted
- Allows system to maintain high efficiency for data taking

[Fig. Ref](#)

# ATLAS DEADTIME



- Simple dead-time veto:



asserted

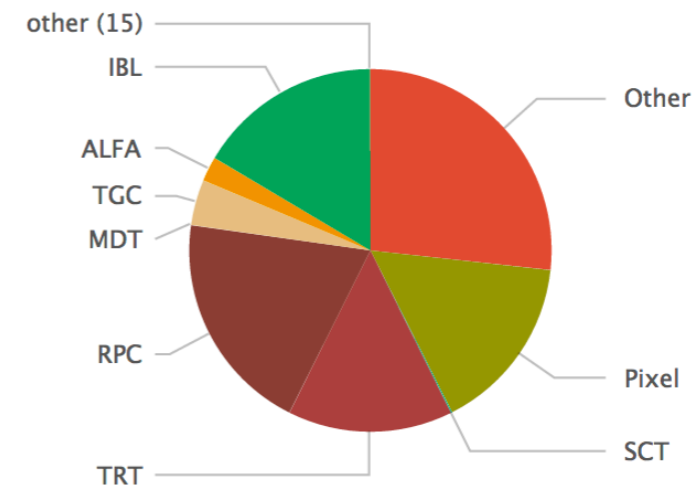
- Allows system to maintain high efficiency for data taking

# ATLAS DEADTIME

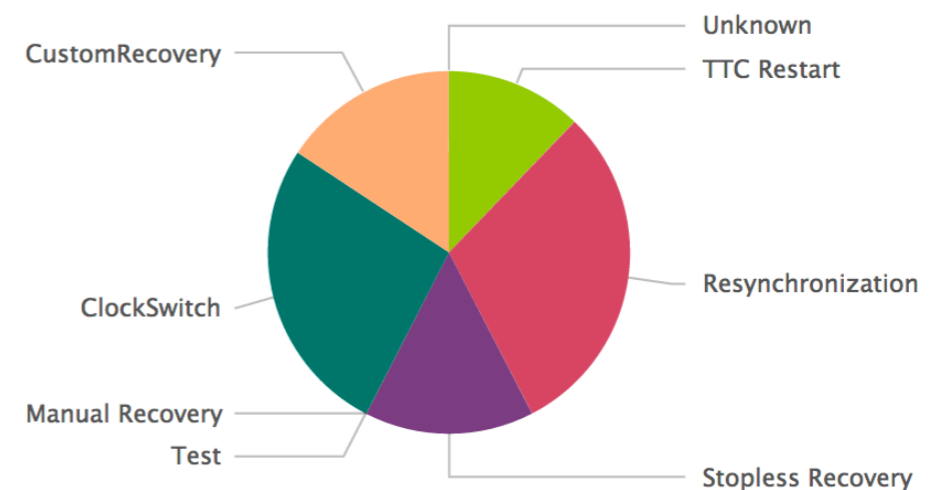


- Simple dead-time veto:
  - No new L1A after fixed number of BC
- Leaky-bucket Deadtime Algorithm:
  - Bucket leaks at rate R
  - Contents increase by X at each L1A until full, then BUSY is asserted
  - Allows system to maintain high efficiency for data taking

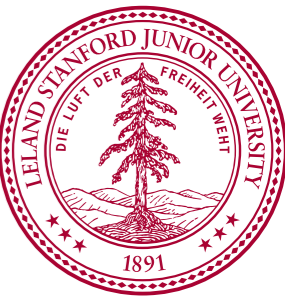
Trigger Held by System



Trigger Held by Reason



# SUMMARY



- TDAQ is the system which allows us to take data off our detectors for analysis
- Efficiency of data taking is controlled through stochastic input rate, DAQ processing rate, and ability to buffer events to process
- We'll learn more about how these are implemented and what people are thinking about the future tomorrow!

