A new approach to calculating dynamic friction for magnetized electron coolers – relevance to future IOTA experiments and to EIC designs

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Motivation – Nuclear Physics

- Electron-ion colliders (EIC)
 - high priority for the worldwide nuclear physics community
- Relativistic, strongly-magnetized electron cooling
 - may be essential for EIC, but never demonstrated



eRHIC concept from BNL



JLEIC concept from Jefferson Lab

Idea for Electron Cooling is 50 Years Old

- Budker developed the concept in 1967
 - G.I. Budker, At. Energ. 22 (1967), p. 346.
- Many low-energy electron cooling systems:
 - continuous electron beam is generated
 - electrons are nonrelativistic & very cold compared to bunches
 - electrons are magnetized with a strong solenoid field
 - suppresses transverse temperature & increases friction
- Fermilab has shown cooling of relativistic p-bar's
 - S. Nagaitsev et al., PRL 96, 044801 (2006).
 - ~5 MeV e-'s (γ ~ 9) from a DC source

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- The electron beam was **not** magnetized
- Relativistic magnetized cooling not yet demonstrated
 - electron cooling at $\gamma \sim 100$ has not been demonstrated
 - a non-magnetized concept was developed for RHIC
 - Fedotov et al., Proc. PAC, THPAS092 (2007).

Risk Reduction is Required for Relativistic Coolers

- eRHIC, JLEIC both need cooling at high energy $- 100 \text{ GeV/n} \rightarrow \gamma \approx 107 \rightarrow 55 \text{ MeV bunched electrons, } \sim 1 \text{ nC}$
- Electron cooling at γ ~100 requires different thinking
 - friction force scales like $1/\gamma^2$ (Lorentz contraction, time dilation)
 - challenging to achieve the required dynamical friction force
 - not all of the processes that reduce the friction force have been quantified in this regime → significant technical risk
 - normalized interaction time is reduced to order unity
 - $\tau = t\omega_{pe} >> 1$ for nonrelativistic coolers

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- $\tau = t\omega_{pe} \sim 1$ (in the beam frame), for $\gamma \sim 100$
 - violates the assumptions of introductory beam & plasma textbooks
 - breaks the intuition developed for non-relativistic coolers
 - as a result, the problem requires careful analysis

Goals

- Simulate magnetized friction force
 - include all relevant real world effects
 - e.g. incoming beam distribution
 - include a wide range of parameters
 - cannot succeed via brute force
 - improved understanding is required



- Include key aspects of magnetized e- beam transport
 - imperfect magnetization
 - space charge
 - field errors



from Zhang et al., MEIC design, arXiv (2012)



Asymptotic model for cold, strongly magnetized electrons

$$\begin{split} \mathbf{F}_{\parallel} &= -\frac{3}{2} \,\omega_{pe}^{2} \,\frac{(Ze)^{2}}{4\pi\varepsilon_{0}} \Bigg[\ln \Bigg(\frac{\rho_{\max}^{A}}{\rho_{\min}^{A}} \Bigg) \Bigg(\frac{V_{\perp}}{V_{ion}} \Bigg)^{2} + \frac{2}{3} \Bigg] \frac{V_{\parallel}}{V_{ion}^{3}} & r_{L} = V_{ms,e,\perp} / \Omega_{L} \Big(B_{\parallel} \Big) \\ \rho_{\min}^{A} = \max \big(r_{L}, \rho_{\min} \big) \\ \rho_{\max}^{A} = \min \big(r_{beam}, \rho_{\max} \big) \\ \mathbf{F}_{\perp} &= -\omega_{pe}^{2} \,\frac{(Ze)^{2}}{4\pi\varepsilon_{0}} \ln \Bigg(\frac{\rho_{\max}^{A}}{\rho_{\min}^{A}} \Bigg) \frac{\left(0.5V_{\perp}^{2} - V_{\parallel}^{2} \right)}{V_{ion}^{2}} \frac{V_{\perp}}{V_{ion}^{3}} & \rho_{\max} = V_{rel} / \max \big(\omega_{pe}, 1/\tau \big) \\ V_{rel} = \max \big(V_{ion}, V_{e,rms,\parallel} \big) \\ V_{ion}^{2} = V_{\parallel}^{2} + V_{\perp}^{2} \end{split}$$

Ya. S. Derbenev and A.N. Skrinsky, "The Effect of an Accompanying Magnetic Field on Electron Cooling," Part. Accel. 8 (1978), 235.

Ya. S. Derbenev and A.N. Skrinskii, "Magnetization effects in electron cooling," Fiz. Plazmy 4 (1978), p. 492; Sov. J. Plasma Phys. 4 (1978), 273.

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I. Meshkov, "Electron Cooling; Status and Perspectives," Phys. Part. Nucl. 25 (1994), 631.

Including thermal effects

Integrating D&S calculation over thermal electron population:

D.V. Pestrikov, (2002), preprint.

$$F_{\parallel}(0,V_{\parallel}) = -V_{\parallel} \frac{4\pi Z^2 e^4 n_e L_M}{m \Delta_{e,\parallel}^3} \exp\bigg(-\frac{V_{\parallel}^2}{2\Delta_{e,\parallel}^2}\bigg)$$

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A.V. Fedotov, D.L. Bruhwiler and A.O. Sidorin, "Analysis of the magnetized friction force," Proc. High Brightness (Tsukuba, 2006).



VORPAL modeling of binary collisions clarified differences in formulae for magnetized friction



- D&S asymptotics are accurate for ideal solenoid, cold electrons not warm
- Parkhomchuk formula often works for typical parameters, but not always
- 3D quad. of D&S with e- dist. works better (modified r_{min}, ideal solenoid)
- In general, direct simulation is required

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Detailed simulations of magnetized friction:

WEAY04

Proceedings of HB2006, Tsukuba, Japan

Analysis of the magnetized friction force *

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PHYSICAL REVIEW SPECIAL TOPICS - ACCELERATORS AND BEAMS 9, 074401 (2006)

Numerical study of the magnetized friction force

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Simulating the dynamical friction force on ions due to a briefly co-propagating electron beam

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Detailed simulations of magnetized friction:



Figure 2: Longitudinal component of the force [eV/m] vs velocity $[\times 10^5 \text{ m/s}]$ for zero transverse angle $\theta = 0$ with respect to the magnetic field lines. VORPAL results: dots with error bars; Eq. (4) - solid line.



Phys. 227, 8714 (2008).

JLab EIC Design:

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Can we quantify the required solenoidal field quality?

- No, we cannot
 - Parkhomchuk formula provides a parametric knob
 - Derbenev and Skrinsky do not offer quantitative guidance
- Can we quantify the effects of space charge forces?
 No, we cannot
- Can we quantify the effects of non-Gaussian e- beam phase space distributions?
 - No, we cannot



A new dynamical friction calculation is underway...

- We follow the approach described by Y. Derbenev
- However, we begin from a new starting point
 - analytic momentum transfer between ion and magnetized e-
 - proceed step by step with calculation
- Calculation is defined by the following considerations:

$$\vec{E}(\vec{r},\vec{v},t) = \langle \vec{E}^0 \rangle (\vec{r},t) + \langle \Delta \vec{E} \rangle (\vec{r},\vec{v},t) + \vec{E}^{fl}(\vec{r},\vec{v},t)$$
(1.1)

$$\vec{F} = -ze\langle\Delta\vec{E}\rangle(\vec{r},\vec{v},t)\big|_{\vec{r}=\vec{r}(t),\vec{r}(t)=\vec{v}}$$
(1.2)

Y. Derbenev, "Theory of Electron Cooling," arXiv (2017); https://arxiv.org/abs/1703.09735

THEORY OF ELECTRON COOLING

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*Translated from Russian by V.S. Morozov, Jefferson Lab, VA 23606, USA Translation supported by Jefferson Science Associates, LLC under U.S. DOE Contract No. DE-AC05-06OR23177. The U.S. Government retains a non-exclusive, paid-up, irrevocable, worldwide license to publish or reproduce this manuscript for U.S. Government purposes.

Directly integrate Δp_{ion} to obtain friction force?



$$F = -\frac{n_{\rm e}m_{\rm e}}{T} \iint_{\mathbb{R}^3} \int d^3v \iiint_V dr dz d\varphi \,\Delta v(T, r, \varphi, z, v) r p(v)$$

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- Straightforward integration includes space charge, etc.
 this approach worked for VORPAL/VSim simulations (w/ effort)
- Problematic, so we follow Derbenev et al.

The required steps are straightforward in principle:

- Calculate the perturbed e-velocities
 - due to a single ion
 - initially, we consider purely longitudinal motion
- Obtain time-derivative of perturbed E-field
 - via Poisson and continuity equations
- Integrate in time to get $\delta \mathsf{E}$
 - initially, this is for only a single value of e-velocity
 - it is necessary to integrate over thermal e-velocities
- Integrate δE along ion trajectory to obtain <F> - hence, this is a 2nd-order effect, ~(Ze²)² xx
- Present efforts:

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- find best way to integrate <F> over e- distribution functions
- consider transverse ion motion
- numerical approaches, testing, etc.

Hamiltonian for 2-body magnetized collision:

$$H(\vec{x}_{ion}, \vec{p}_{ion}, \vec{x}_{e}, \vec{p}_{e}) = H_{0}(\vec{p}_{ion}, y_{e}, \vec{p}_{e}) + H_{C}(\vec{x}_{ion}, \vec{x}_{e})$$
$$\vec{B} = B_{0} \hat{z} \qquad \vec{A} = -B_{0}y \hat{x} \qquad p_{e,x} = m_{e}(v_{e,x} - \Omega_{L}y_{e})$$

$$H_{0}(\vec{p}_{ion}, y_{e}, \vec{p}_{e}) = \frac{1}{2m_{ion}} \left(p_{ion,x}^{2} + p_{ion,y}^{2} + p_{ion,z}^{2} \right) + \frac{1}{2m_{e}} \left[\left(p_{e,x} + eB_{0}y_{e} \right)^{2} + p_{e,y}^{2} + p_{e,z}^{2} \right]$$
$$H_{C}(\vec{x}_{ion}, \vec{x}_{e}) = \frac{-Ze^{2}}{4\pi\varepsilon_{0}} / \sqrt{(x_{ion} - x_{e})^{2} + (y_{ion} - y_{e})^{2} + (z_{ion} - z_{e})^{2}}$$

Resulting equations of motion, in the standard drift-kick symplectic form: $M(\Delta t) = M_0(\Delta t/2)M_c(\Delta t)M_0(\Delta t/2)$

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D.L. Bruhwiler and S.D. Webb, "New algorithm for dynamical friction of ions in a magnetized electron beam," in *AIP Conf. Proc.* **1812**, 050006 (2017); <u>http://aip.scitation.org/doi/abs/10.1063/1.4975867</u>

Analytic calculation of $\Delta \mathbf{p}_{ion}$ (1)

$$C_{1} = \left(x_{ion} - \frac{p_{gc}}{m_{e}\Omega_{e}}\right)^{2} + \left(y_{ion} - y_{gc}\right)^{2} + \left(z_{ion} - z_{e}\right)^{2} + \frac{2}{m_{e}\Omega_{e}}J$$
(14a)

$$C_{2} = 2(x_{ion} - x_{gc})v_{ion,x} + 2(y_{ion} - y_{gc})v_{ion,y} + 2(z_{ion} - z_{e})(v_{ion,z} - v_{ez})$$
(14b)

$$C_{3} = v_{ion,x}^{2} + v_{ion,y}^{2} + \left(v_{ion,x} - v_{ez}\right)^{2}$$
(14c)

$$b = \left[C_1 + C_2 T + C_3 T^2\right]^{1/2} \qquad \Delta = 4C_1 C_3 - C_2^2 \tag{14d}$$

$$D_{1} = \left[\frac{2C_{3}T + C_{2}}{b} - \frac{C_{2}}{\sqrt{C_{1}}}\right]$$
(14e)

$$D_{2} = \left[\frac{2C_{1} + C_{2}T}{b} - 2\sqrt{C_{1}}\right]$$
(14f)



Analytic calculation of $\Delta \mathbf{p}_{ion}$ (2)

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$$\Delta p_{ion,x} = \frac{-2\alpha}{\Delta} \left[\left(x_{ion} - p_{gc} / m_e \Omega_e \right) D_1 - \left(p_{ion,x} / m_{ion} \right) D_2 \right]$$
(15a)

$$\Delta p_{ion,y} = \frac{-2\alpha}{\Delta} \left[\left(y_{ion} - y_{gc} \right) D_1 - \left(p_{ion,y} / m_{ion} \right) D_2 \right]$$
(15b)

$$\Delta p_{ion,z} = \frac{-2\alpha}{\Delta} \left[\left(z_{ion} - z_e \right) D_1 - \left(\frac{p_{ion,z}}{m_{ion}} - \frac{p_{ez}}{m_e} \right) D_2 \right]$$
(15c)

$$\Delta p_{gc} = -\Delta p_{ion,x} \qquad \Delta y_{gc} = -\Delta p_{ion,y} / m_e \Omega_e \tag{15d}$$

Time-explicit vs analytic shows agreement:



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- Two small parameters are required:
 - Larmor radius must be small compared to impact param.

averaging

- Kinetic energy must be large compared to max potential energy
 - perturbative

Choice of coordinate system is important:



$$\Delta v_{e,z} = \frac{Ze^2}{m_e} \left\{ \left[x_{gc}^2 + y_{gc}^2 + \rho_{gc}^2 + z_e^2 \right]^{-1/2} - \left[x_{gc}^2 + y_{gc}^2 + \rho_{gc}^2 + (z_e - v_{rel}T)^2 \right]^{-1/2} \right\}$$

$$v_{rel} = v_{i,z} - v_{e,z}$$

$$\frac{\partial \vec{E}}{\partial T} = -\vec{J} \qquad r^2 = x_{gc}^2 + y_{gc}^2$$

$$\frac{\partial E_z}{\partial T}_{r=0} = \frac{Ze^2}{m_e} \left\{ \left[\rho_{gc}^2 + z_e^2 \right]^{-1/2} - \left[\rho_{gc}^2 + (z_e - v_{rel}T)^2 \right]^{-1/2} \right\}$$



Integrate twice to obtain friction force:

$$E_{z}(r=0) = (n_{0}e)\frac{Ze^{2}}{m_{e}v_{rel}} \left\{ T\left[\rho_{gc}^{2} + z_{e}^{2}\right]^{-1/2} + \frac{1}{v_{rel}}ln\left[\frac{\left[\rho_{gc}^{2} + z_{e}^{2}\right]^{1/2} + z_{e}}{\left[\rho_{gc}^{2} + (z_{e} - v_{rel}T)^{2}\right]^{1/2} + (z_{e} - v_{rel}T)}\right] \right\}$$

Let $z_e = v_{i,z}T$ and then integrate over T to obtain:

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$$< F > = (n_0 e) \frac{n_0 (Ze^2)^2}{m_e v_{rel} T} \Biggl\{ \frac{T}{v_{rel}} ln \left(\left[\rho_{gc}^2 + \left(v_{i,z} T \right)^2 \right]^{1/2} + v_{i,z} T \right) - \frac{v_{e,z}}{v_{i,z}^2 v_{rel}} \left(\left[\rho_{gc}^2 + \left(v_{i,z} T \right)^2 \right]^{\frac{1}{2}} - \rho_{gc} \right) \Biggr\} - \frac{T}{v_{rel}} ln \left(\left[\rho_{gc}^2 + \left(v_{e,z} T \right)^2 \right]^{1/2} + v_{e,z} T \right) - \frac{1}{v_{e,z} v_{rel}} \left(\left[\rho_{gc}^2 + \left(v_{e,z} T \right)^2 \right]^{\frac{1}{2}} - \rho_{gc} \right) \Biggr\}$$

There is an integrable singularity for cold electrons. The challenge now is to integrate over thermal velocities

Long-term goals: Include other effects in Magnus Expansion

$$H(\vec{x}_{ion}, \vec{p}_{ion}, \vec{x}_e, \vec{p}_e) = H_0(\vec{p}_{ion}, y_e, \vec{p}_e) + H_C(\vec{x}_{ion}, \vec{x}_e) + H_{space-charge}(\vec{x}_{ion}, \vec{x}_e) + H_{solenoid-field-errors}(??)$$

- Quantitative treatment of space charge & field errors?
 - space charge should work
 - field errors are more challenging
- Requires generalization of Magnus expansion
 - we are optimistic this can be done



Future Electron cooling experiments in IOTA

- Could be used to test friction force equations...?
 - RadiaSoft is interested to collaborate



JSPEC – new software for IBS and e- cooling

JSPEC on GitHub, <u>https://github.com/zhanghe9704/electroncooling</u> Primary developer is He Zhang of JLab

A new GUI for JSPEC is under development, as part of the open source cloud computing initiative, Sirepo <u>http://sirepo.com</u>



Thank You! Questions?

