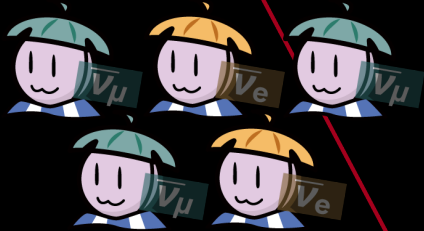
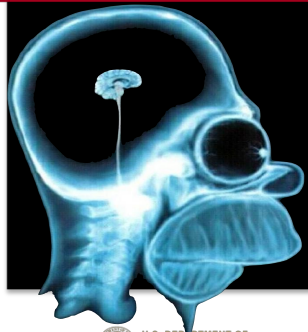
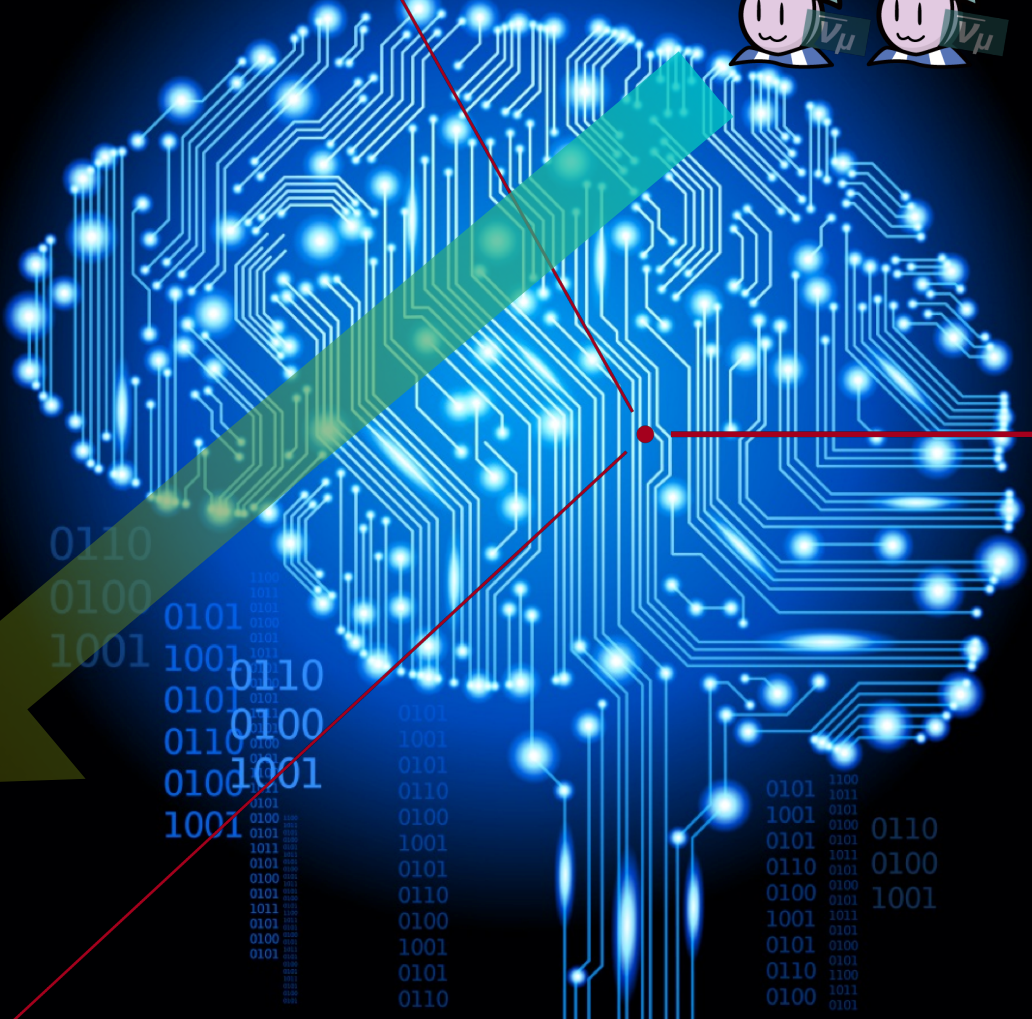


Deep Neural Networks for 3D Data Reconstruction

*Kazuhiro Terao
SLAC National Accelerator Lab.
CPAD @ Brown University
December 9th, 2018*



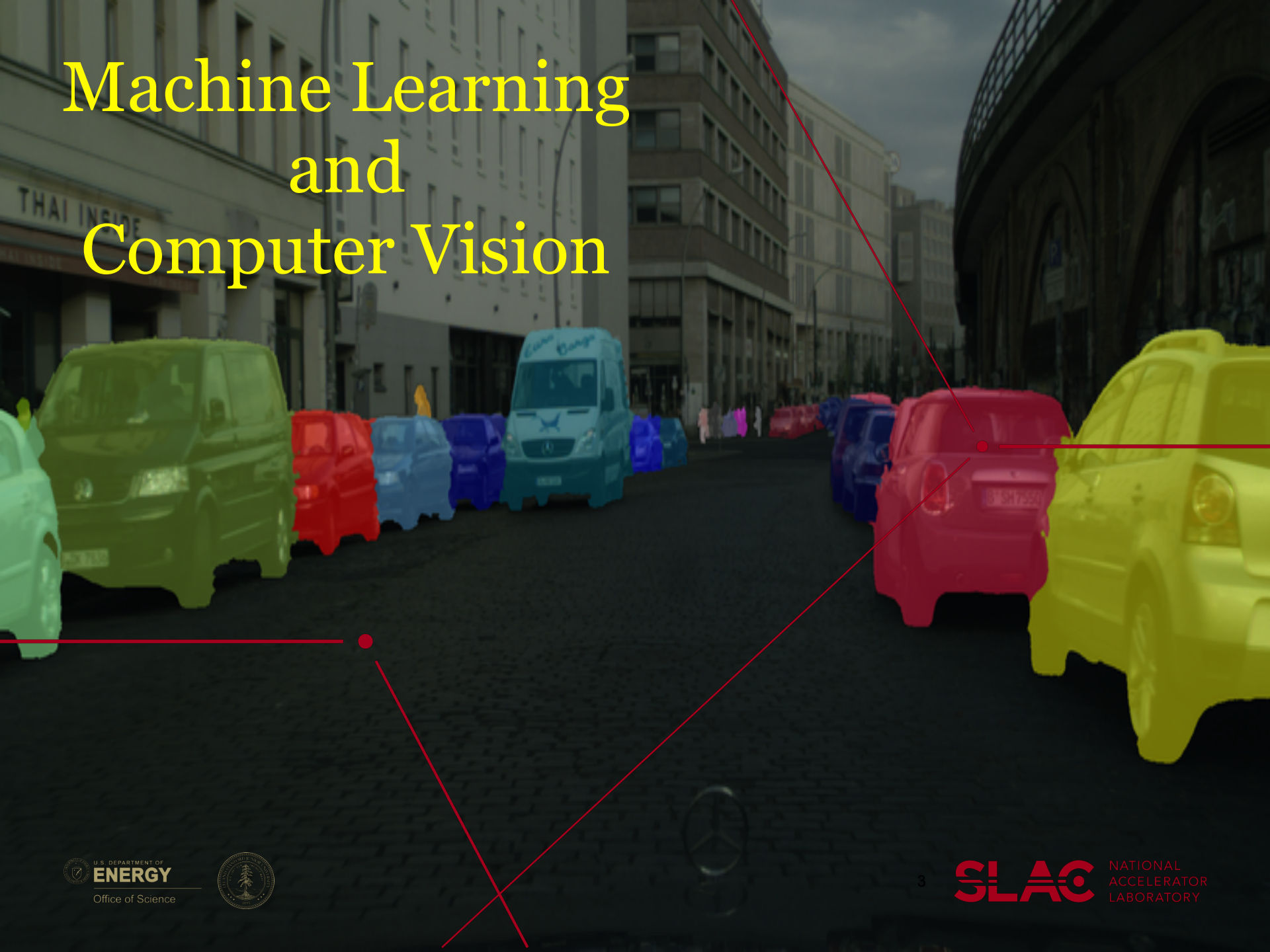
A particle detector event visualization showing a network of tracks in cyan and green against a dark blue background. The tracks originate from a central point and spread outwards, with some tracks ending in small colored dots. The overall appearance is that of a complex particle interaction or decay event.

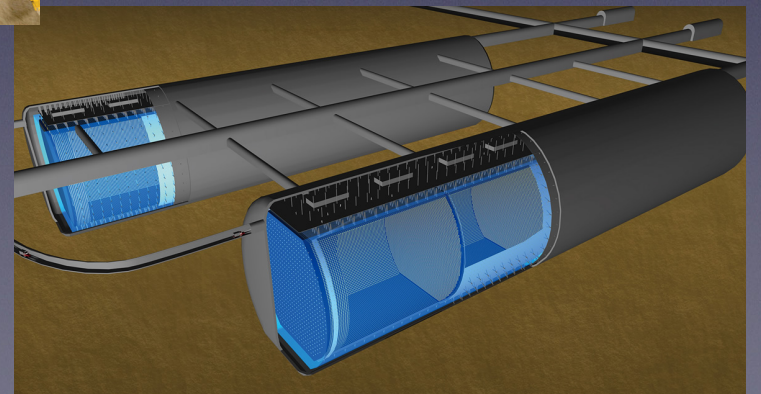
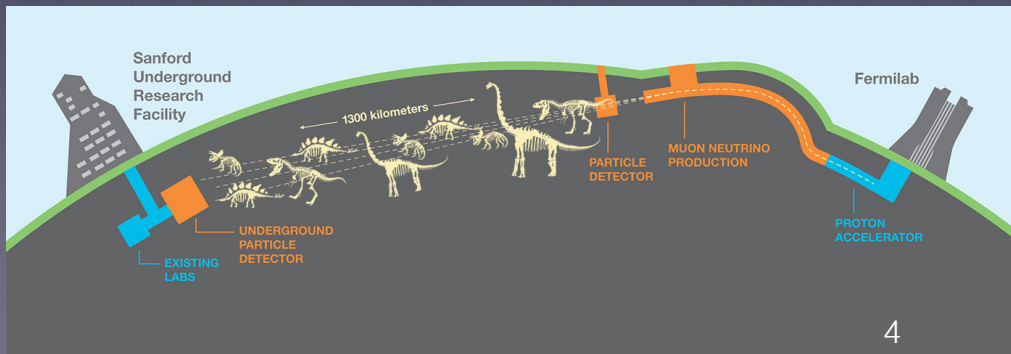
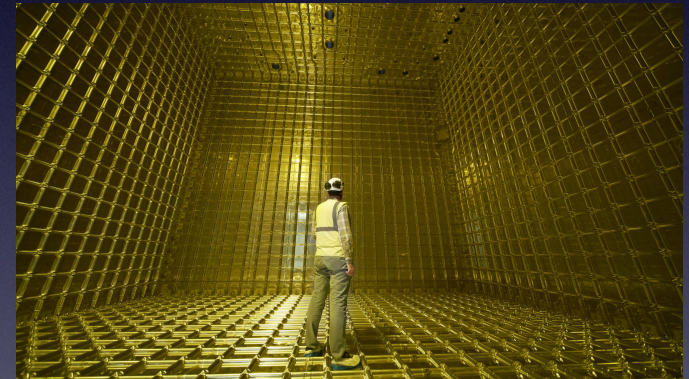
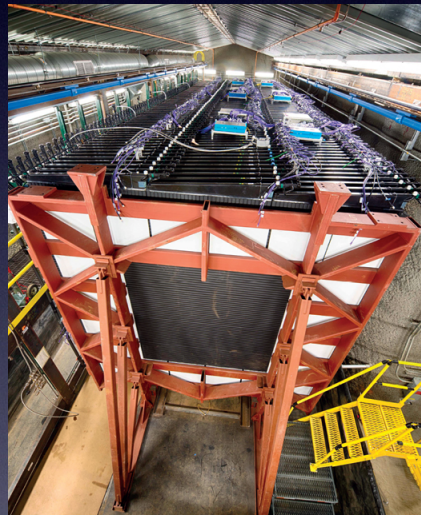
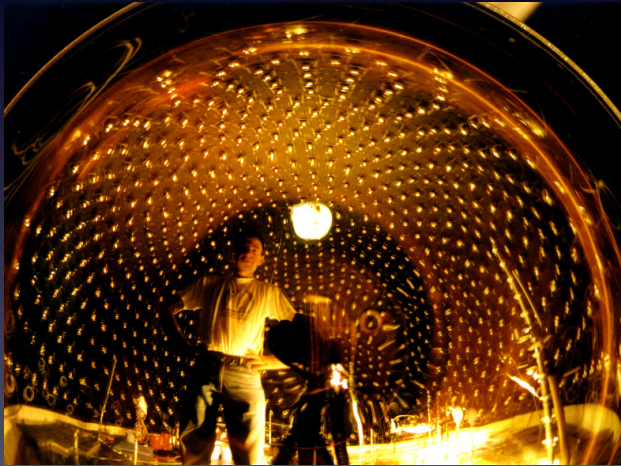
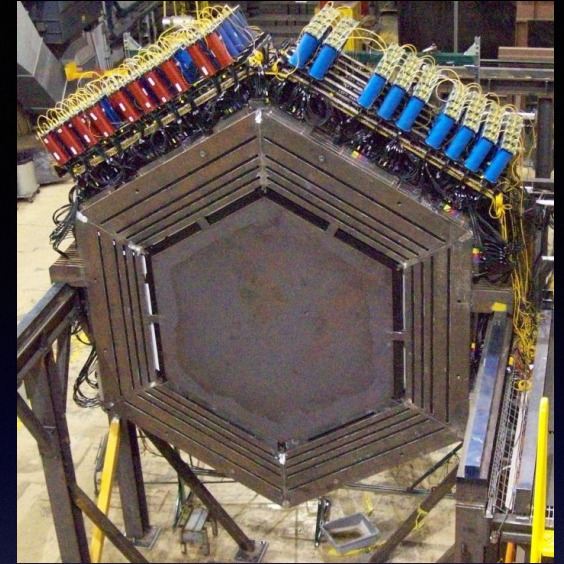
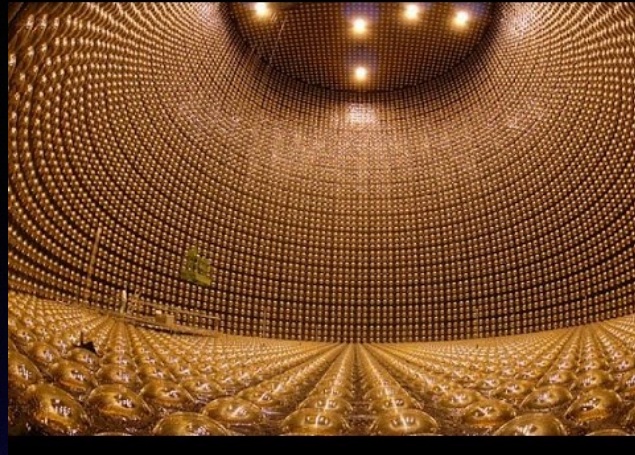
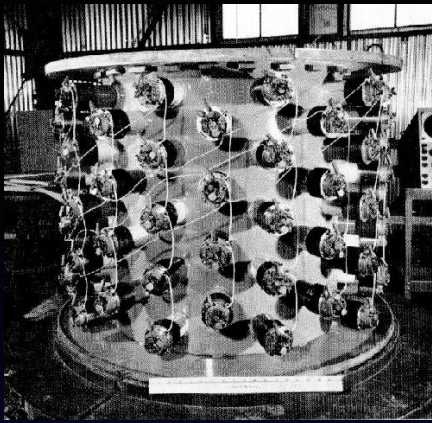
μBooNE

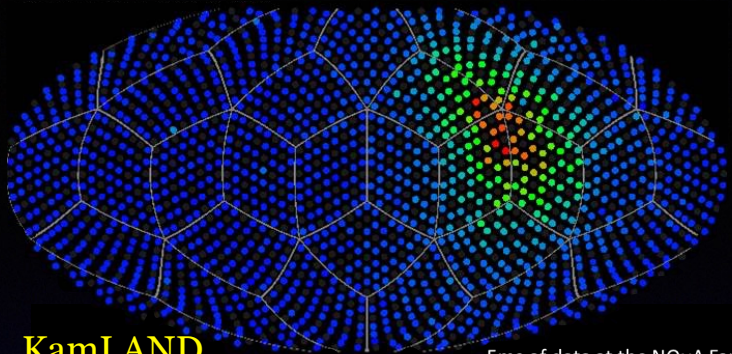
Outline

1. Machine Learning & Computer Vision
2. Applications in LArTPCs
3. Wrap-up

Machine Learning and Computer Vision

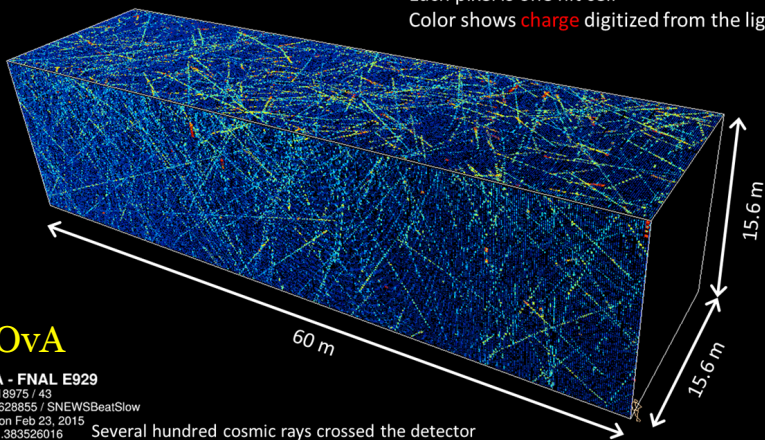






KamLAND

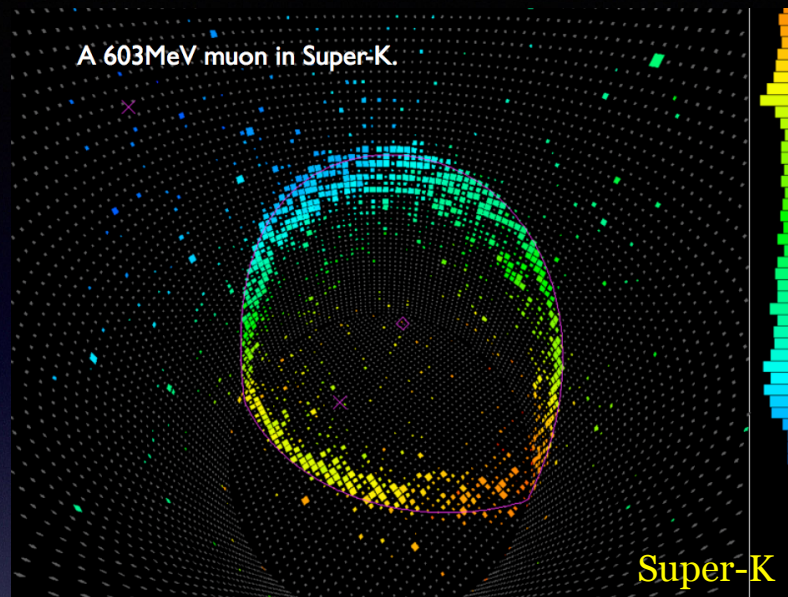
5ms of data at the NOvA Far Detector
 Each pixel is one hit cell
 Color shows charge digitized from the light



NOvA

NOvA - FNAL E929
 Run: 18975 / 43
 Event: 628055 / SNEWSBeatSlow
 UTC Mon Feb 23, 2015
 14:30:1.983526016

Several hundred cosmic rays crossed the detector
 (the many peaks in the timing distribution below)

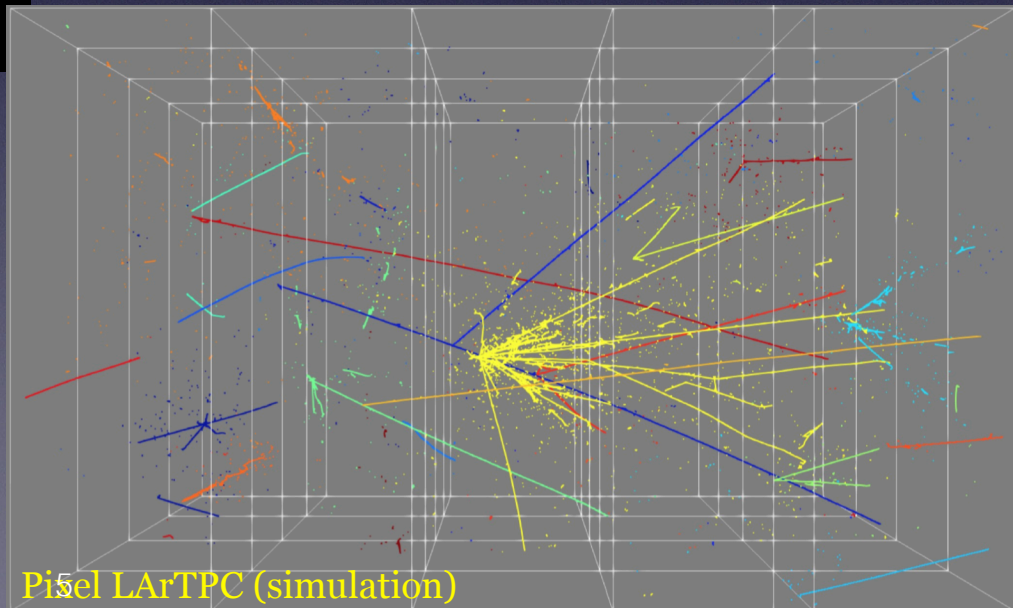
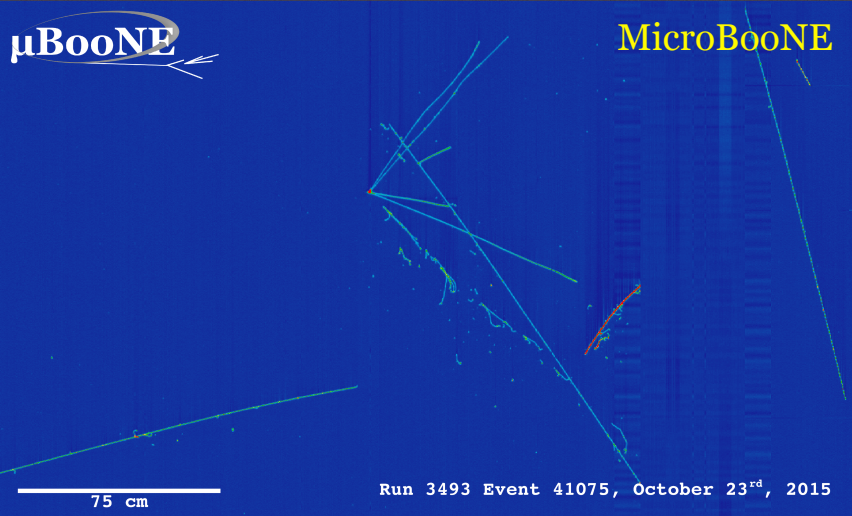


A 603MeV muon in Super-K.

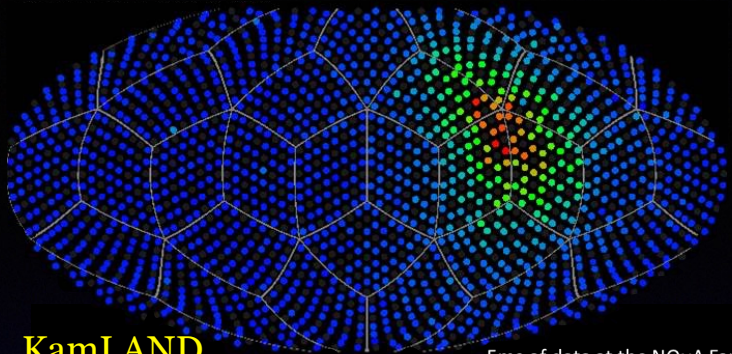
Super-K

μBooNE

MicroBooNE

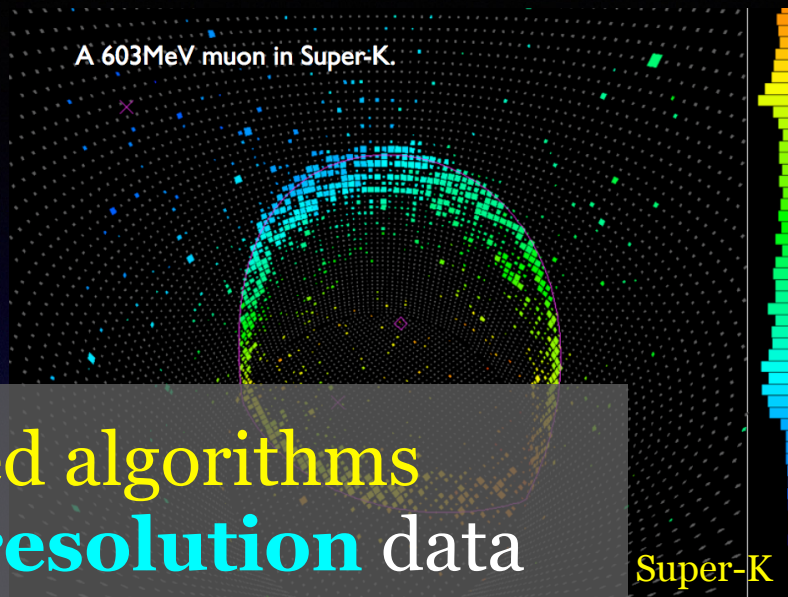


Pixel LArTPC (simulation)



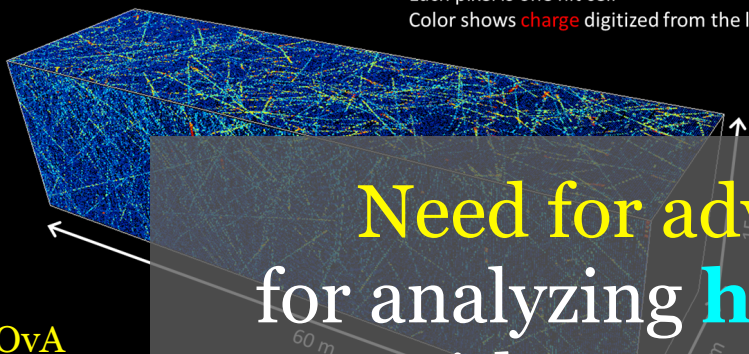
KamLAND

5ms of data at the NOvA Far Detector
 Each pixel is one hit cell
 Color shows charge digitized from the light



A 603MeV muon in Super-K.

Super-K



NOvA

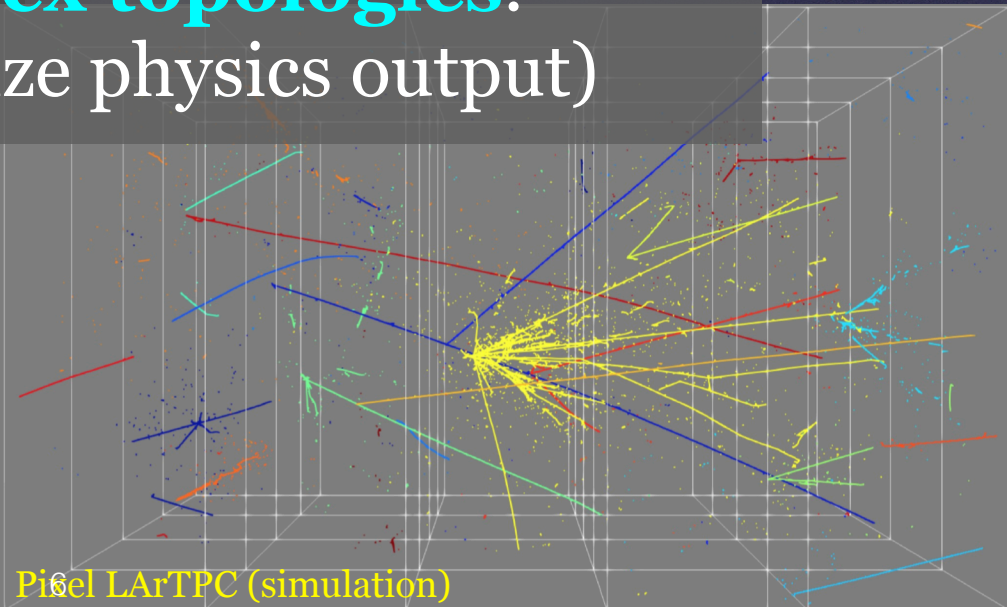
NOvA - FNAL E929
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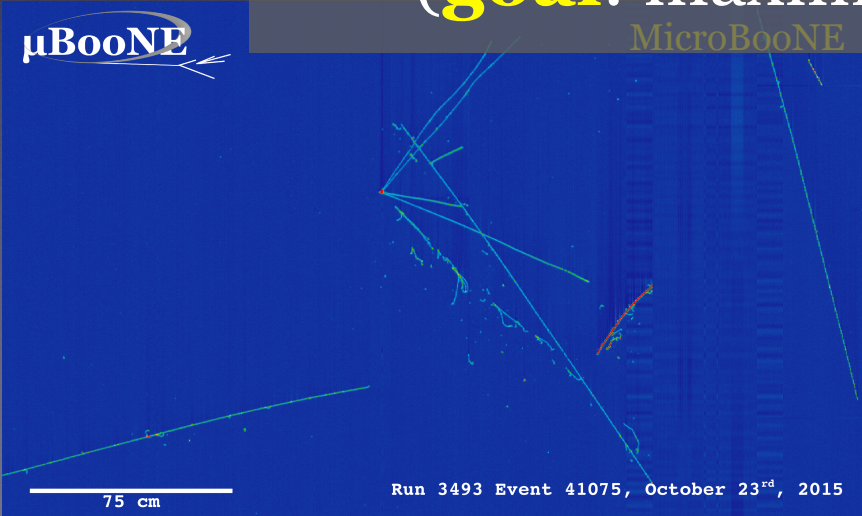
Need for advanced algorithms
 for analyzing **high resolution** data
 with **complex topologies**.
 (goal: maximize physics output)

MicroBooNE

μBooNE



Pixel LArTPC (simulation)

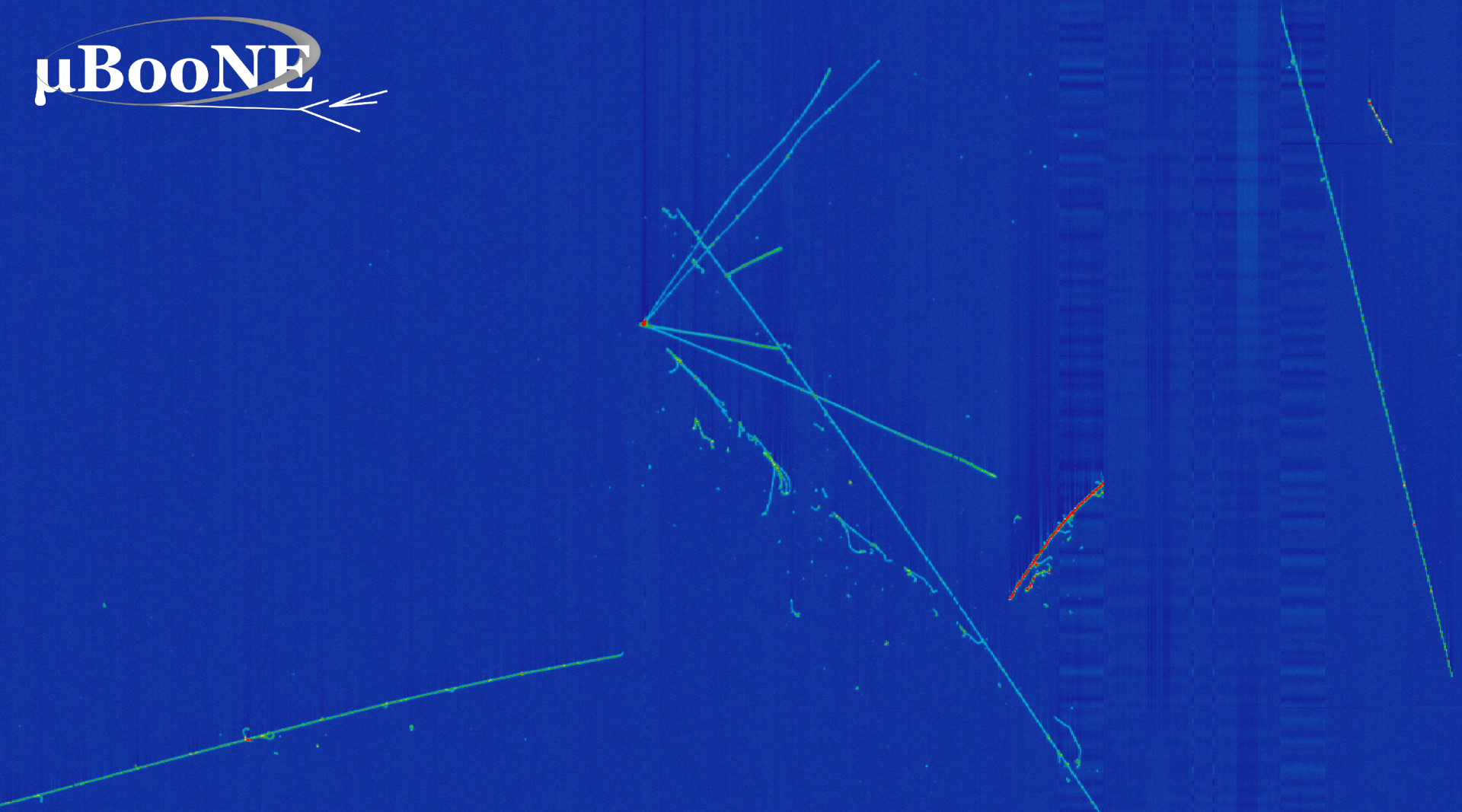


Run 3493 Event 41075, October 23rd, 2015

75 cm

LArTPC Data Reconstruction

μ BooNE

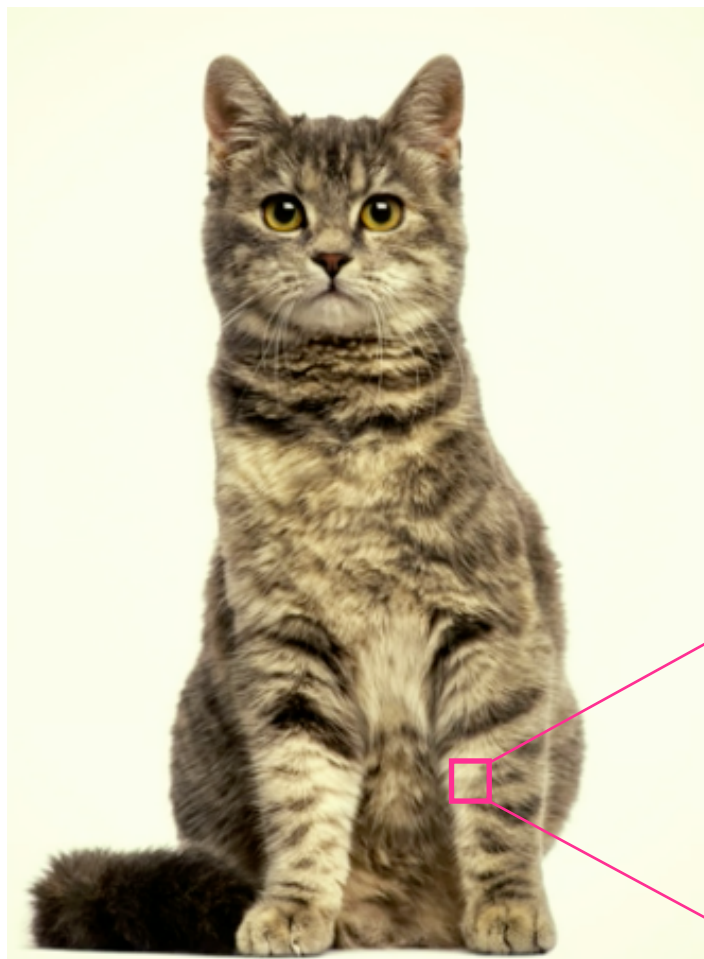


75 cm

Run 3493 Event 41075, October 23rd, 2015

Machine Learning

Challenges in Computer Vision



How to write an algorithm
to identify a cat?

... very hard task ...

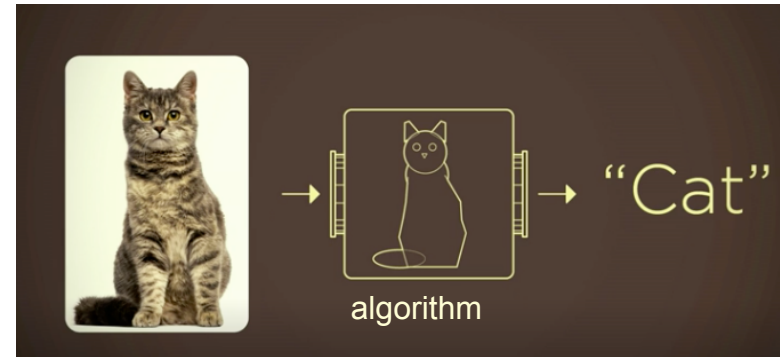
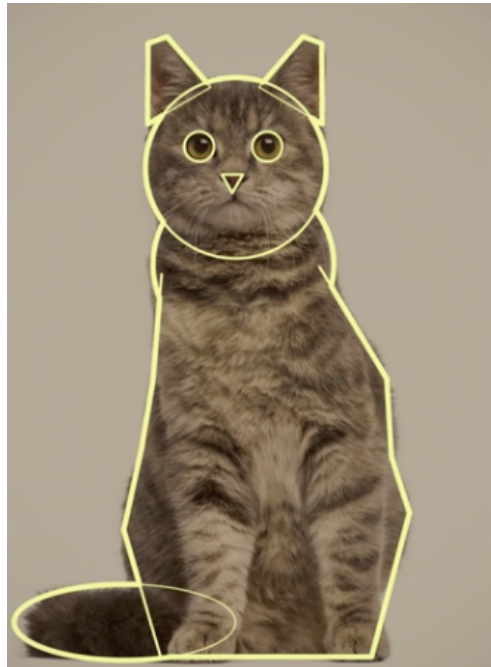
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35	42	48	72	85	27	79	08	41	31	09	53	05	40	04	31	91	56	26	85
68	36	43	54	21	33	81	30	72	06	79	34	39	59	70	03	24	91	03	40
79	60	10	25	54	71	24	50	87	88	47	68	31	42	09	77	40	07	26	73
18	55	38	73	50	47	22	21	88	78	02	95	19	59	60	93	73	40	67	99
54	07	67	38	55	51	26	81	43	66	89	69	92	94	50	08	94	63	33	66
71	95	38	46	63	07	66	68	41	49	34	33	66	76	68	97	53	18	72	21
38	64	86	66	06	68	13	01	89	00	80	70	21	27	14	90	80	95	31	68
04	28	93	88	02	97	92	41	21	54	24	33	97	10	33	47	24	08	12	76
75	37	62	42	88	15	02	57	20	43	09	71	54	73	29	57	23	81	99	41
29	28	57	02	84	20	31	97	41	73	19	29	17	28	99	16	23	19	53	53
95	05	34	86	46	18	95	65	62	28	62	95	35	84	18	22	81	45	10	12
69	18	34	46	77	60	28	62	16	61	72	19	88	14	43	23	64	43	35	00
76	15	68	89	13	74	48	90	12	59	02	31	14	34	77	47	04	69	99	66
70	01	05	77	88	20	63	57	41	50	68	04	30	62	09	67	61	86	31	43
36	76	07	95	11	52	04	91	58	59	30	09	46	95	31	71	43	26	48	19
81	01	86	71	64	31	49	99	60	63	97	61	43	86	36	53	82	31	00	52
63	78	18	10	79	39	77	28	39	17	76	81	93	35	02	78	10	30	35	75
71	73	71	85	86	24	93	75	35	70	30	16	07	35	08	61	82	85	95	22

Machine Learning

Challenges in Computer Vision

Development Workflow for **non-ML** algorithms

1. Write an algorithm based on basic (physics) principles



A cat = collection of certain shapes
(or, a neutrino)

Machine Learning

Challenges in Computer Vision

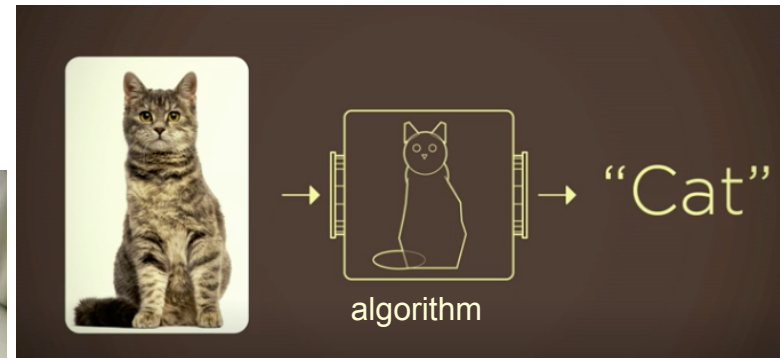
Development Workflow for **non-ML** algorithms

1. Write an algorithm based on basic (physics) principles
2. Run on simulation/data samples
3. Observe failures, implement fixes/heuristics
4. Iterate over 2 & 3 till a satisfactory level is achieved
5. Chain multiple algorithms as one algorithm, repeat 2, 3, and 4.



Partial cat
(escaping muon)

Stretching cat
(Nuclear FSI)



A cat = collection of certain shapes
(or, a neutrino)

Machine Learning

Challenges in Computer Vision

Development Workflow for non-ML algorithms

1. Write an algorithm based on basic (physics) principles
2. Run on simulation/data samples
3. Observe failures, implement fixes/heuristics
4. Iterate over 2 & 3 till a satisfactory level is achieved
5. Chain multiple algorithms as one algorithm, repeat 2, 3, and 4.

Machine Learning

- **Learn patterns from data**
 - automation of steps 2, 3, and 4
- **Chain algorithms & optimize**
 - step 5 addressed by design
- **“Deep Learning”**
 - Revolutions in computer vision using deep neural networks

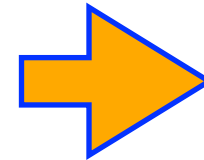
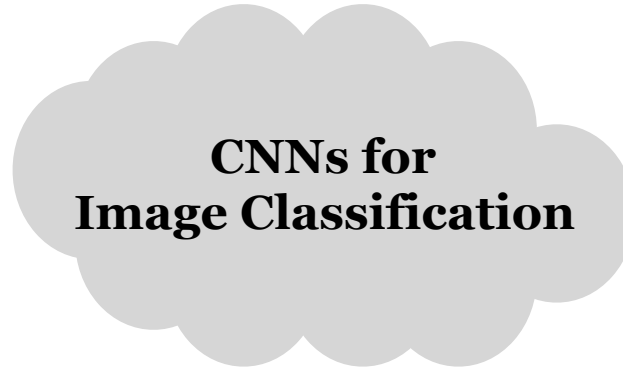
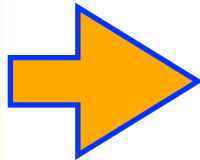


Natural
Neural
Network

Machine Learning

CNNs for Cat Image Analysis

Convolutional Neural Networks (CNNs)

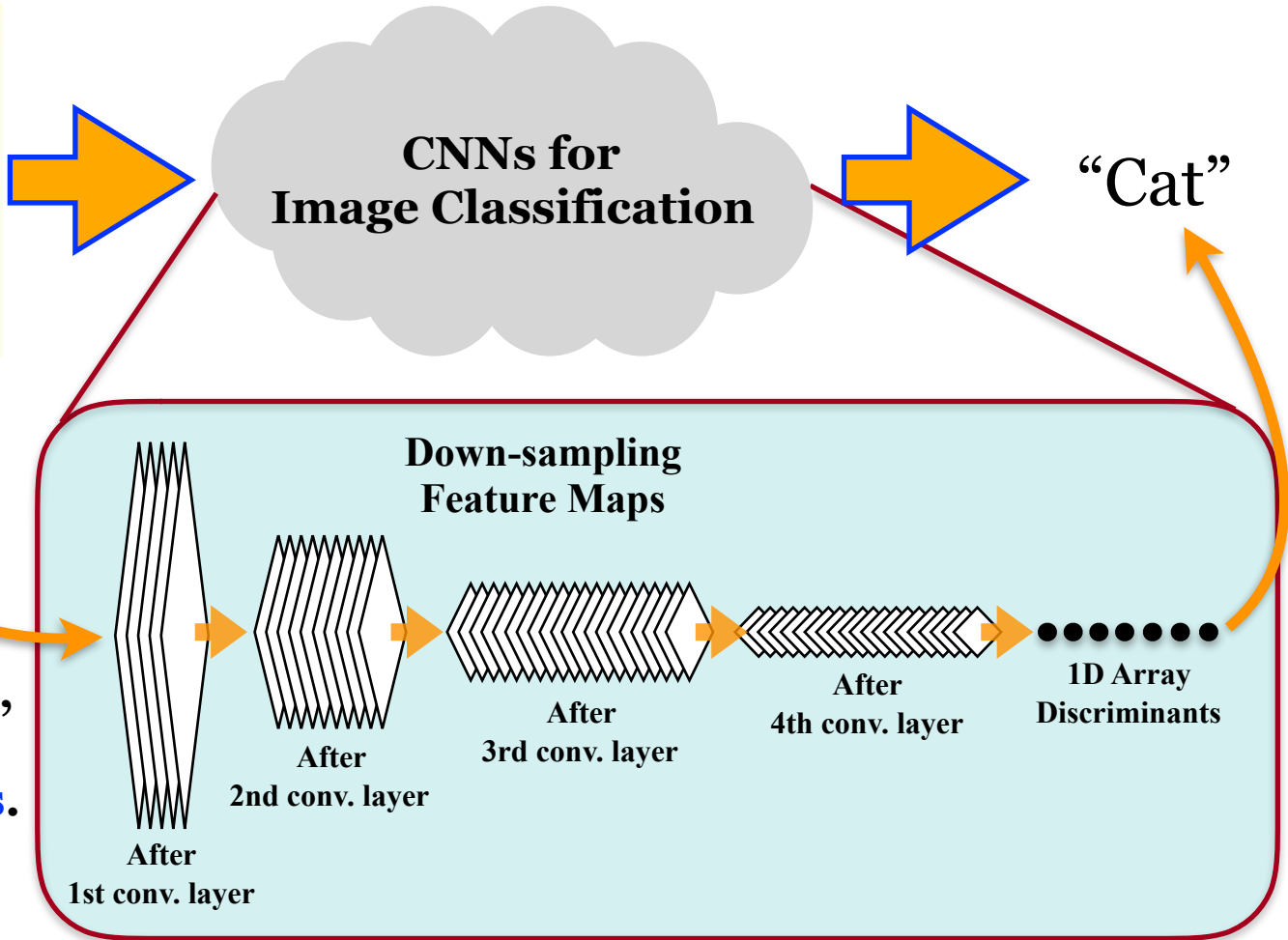


“Cat”

Machine Learning

CNNs for Cat Image Analysis

Convolutional Neural Networks (CNNs)

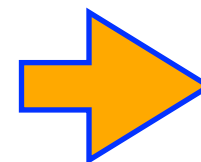
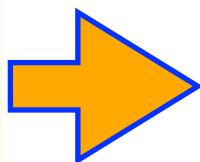


CNNs are effective image **feature extractors**, and also **data transformers**.

Machine Learning

CNNs for Cat Image Analysis

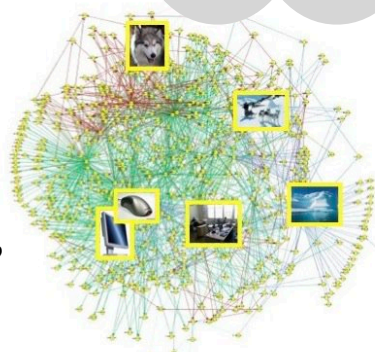
Convolutional Neural Networks (CNNs)



“Cat”

2012 IMAGENET

Public image classification competition w/ 1.2M images, 1000 object categories.



ImageNet Classification with Deep Convolutional Neural Networks

Alex Krizhevsky
University of Toronto
kriz@cs.utoronto.ca

Ilya Sutskever
University of Toronto
ilya@cs.utoronto.ca

Geoffrey E. Hinton
University of Toronto
hinton@cs.utoronto.ca

> 30,000 citations

Abstract

We trained a large, deep convolutional neural network to classify 1.2 million high-resolution images in the ImageNet ILSVRC-2010 contest into the 1000 different classes. On the test data, we achieved top-1 and top-5 error rates of 37.5% and 17.0% which is considerably better than the previous state-of-the-art. The neural network, which has 60 million parameters and 650,000 neurons, consists of five convolutional layers, some of which are followed by max-pooling layers, and three fully-connected layers with a final 1000-way softmax. To make training faster, we used non-saturating neurons and a very efficient GPU implementation of the convolution operation. To reduce overfitting in the fully-connected layers we employed a recently-developed regularization method called “dropout” that proved to be very effective. We also entered a variant of this model in the ILSVRC-2012 competition and achieved a winning top-5 test error rate of 15.3%, compared to 26.2% achieved by the second-best entry.



mite	container ship	motor scooter	leopard
mite	container ship	motor scooter	leopard
black widow	lifeboat	go-kart	jaguar
cockroach	amphibian	moped	cheetah
tick	fireboat	bumper car	snow leopard
starfish	drilling platform	golfcart	Egyptian cat

Machine Learning Beyond Image Classifications

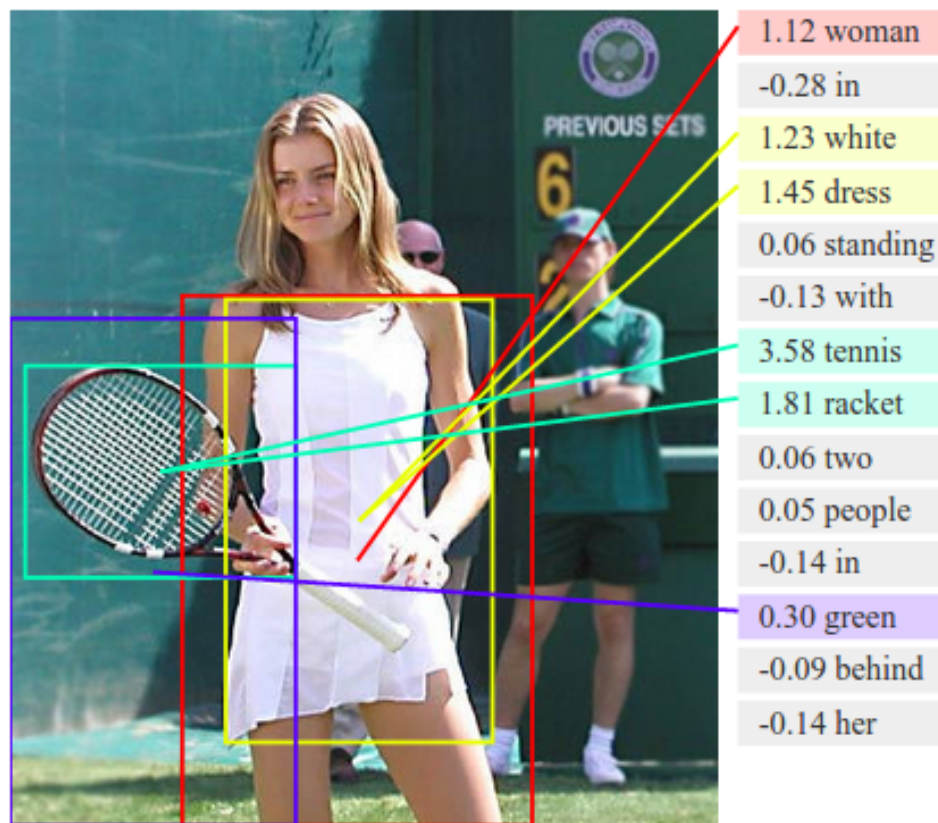
Detection of Image Contexts



Interpretation of Contexts' Correlation



"girl in pink dress is jumping in air."



Machine Learning for ~~Computer Vision~~

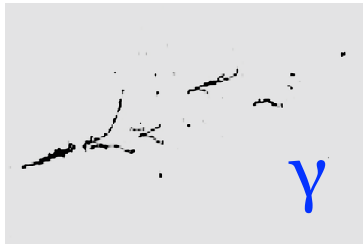
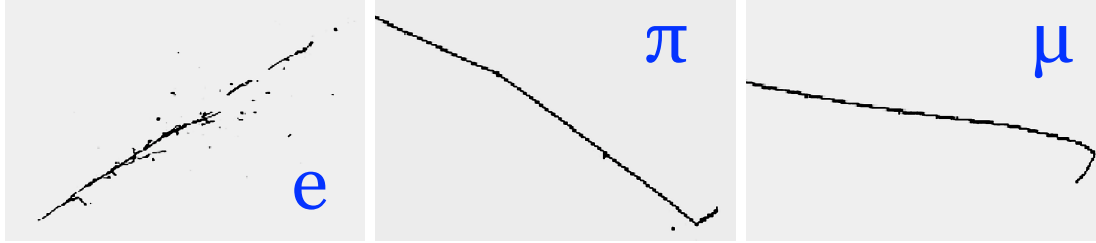
LArTPCs



Early Demonstrations

Machine Learning for LArTPC Image Analysis

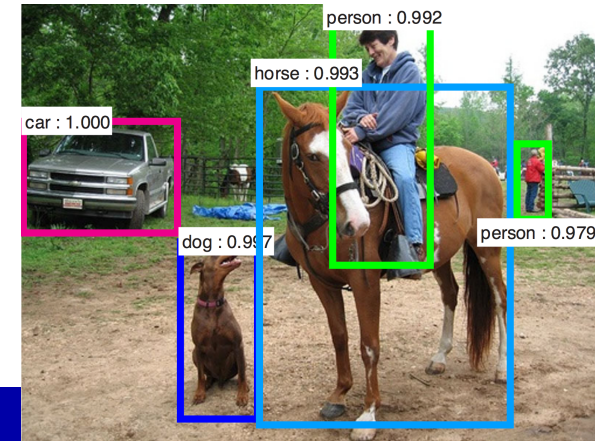
SLAC



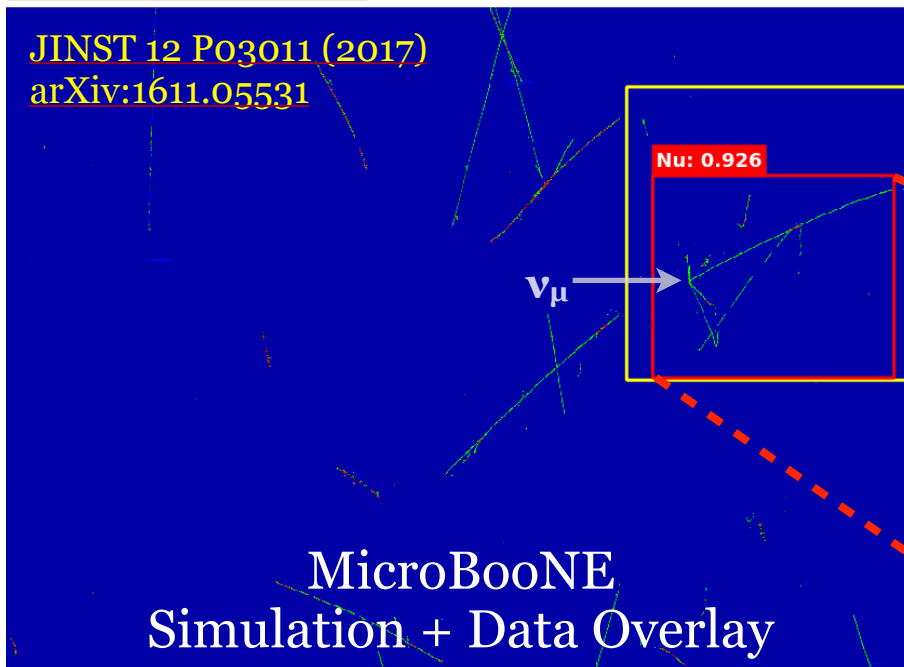
ML Technique @ MicroBooNE LArTPC Detector

Image Classification

- Classify a whole image into object categories
- particle type identification from an image
- signal/background selection



JINST 12 P03011 (2017)
arXiv:1611.05531



Early Demonstrations

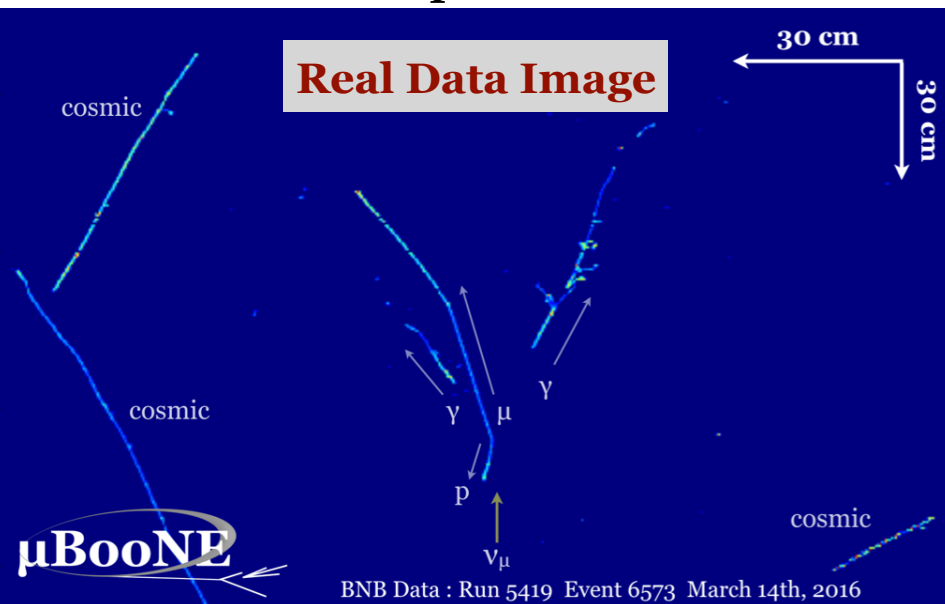
Machine Learning for LArTPC Image Analysis

SLAC

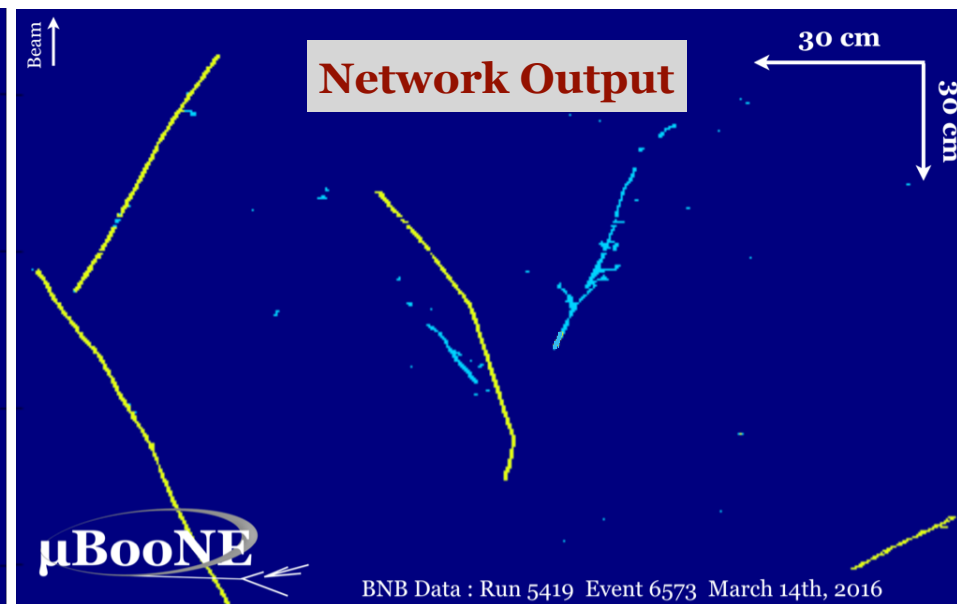
Semantic Segmentation

- Recently published ... [arXiv:1808.07269](https://arxiv.org/abs/1808.07269)
- Pixel-level object classification
 - Separation of EM-particle from other types
 - Key input information for particle clustering
- First time deep neural network validated on LArTPC data

ML Technique @ MicroBooNE LArTPC Detector

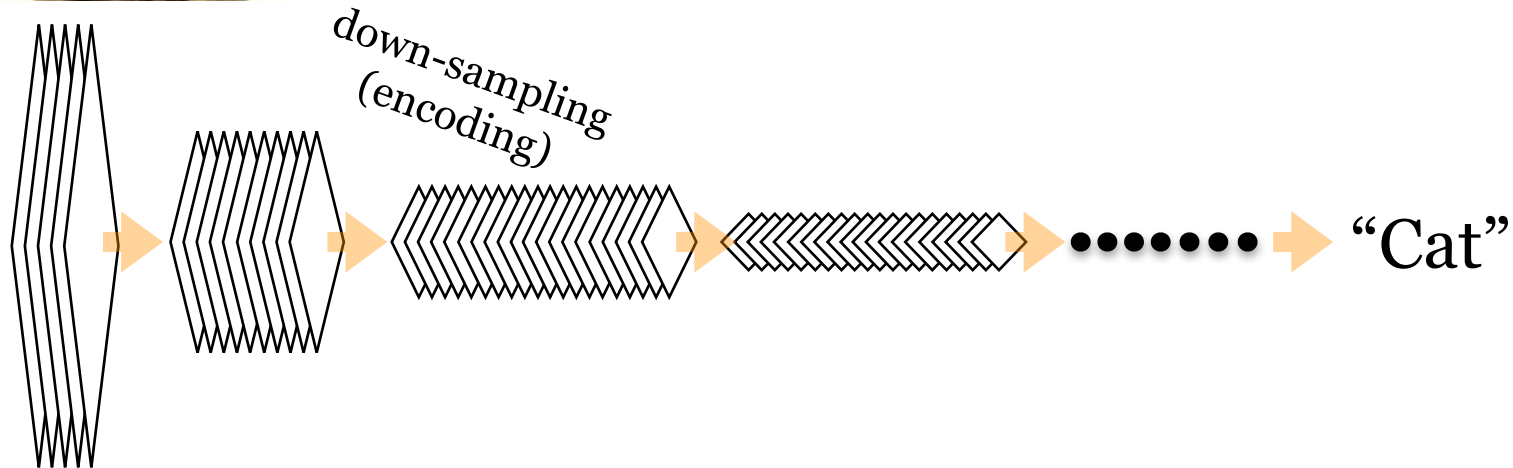


Network Input



Network Output

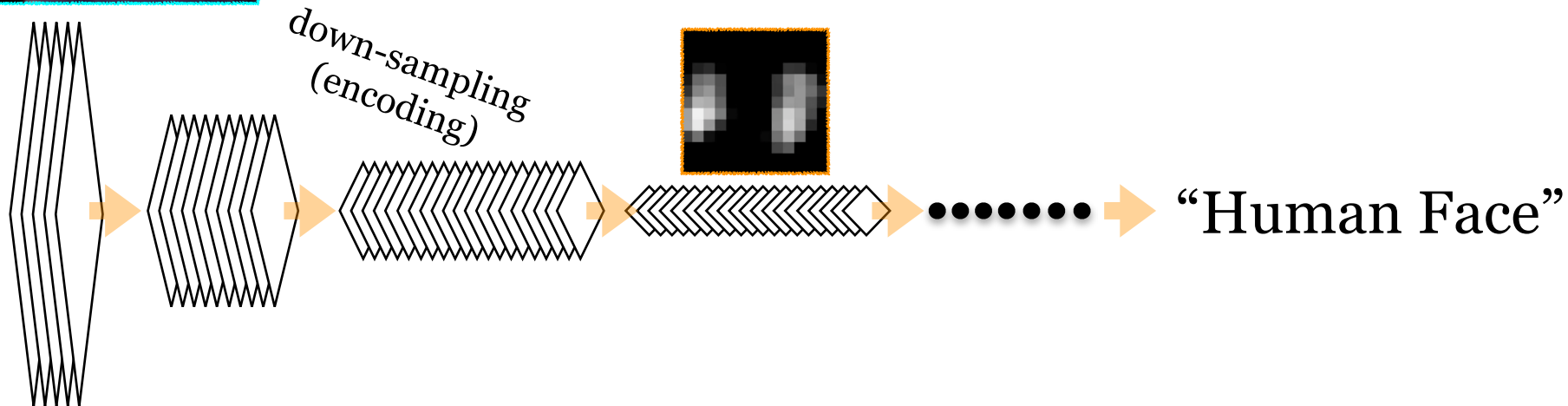
How image classification works



How image classification works

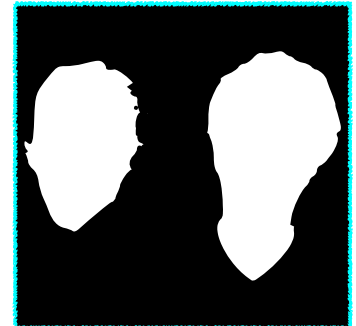


Intermediate Data Tensor
(low-resolution, high-level features)

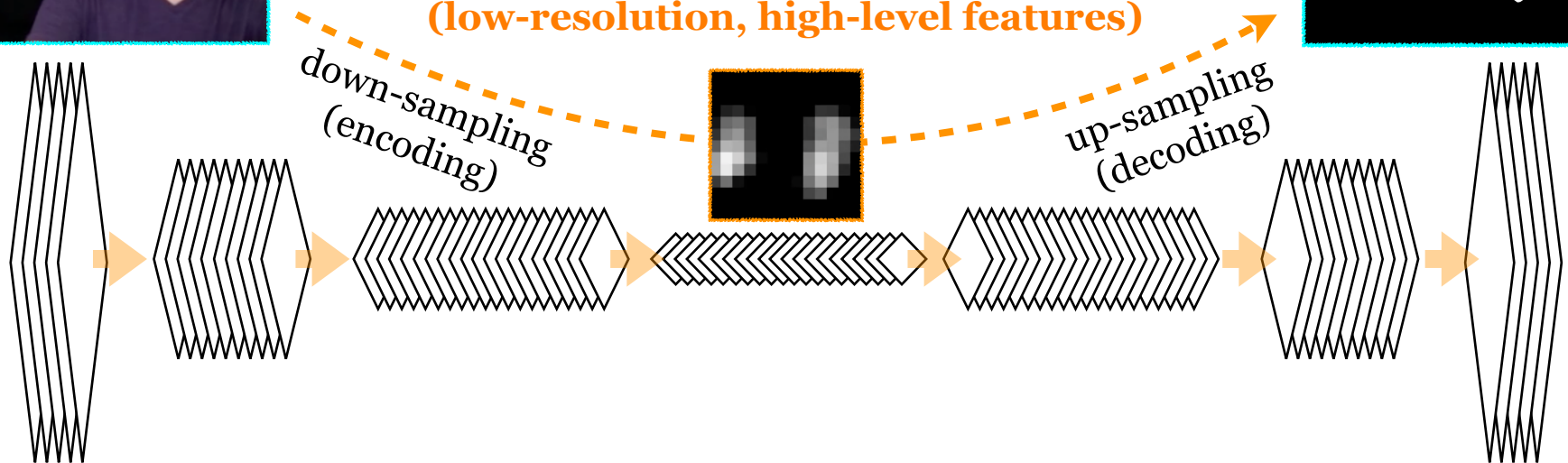


How pixel segmentation works

- Combine “up-sampling” + convolutions
- Output: “learnable” interpolation filters

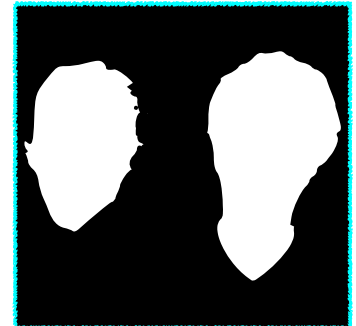


Intermediate Data Tensor
(low-resolution, high-level features)

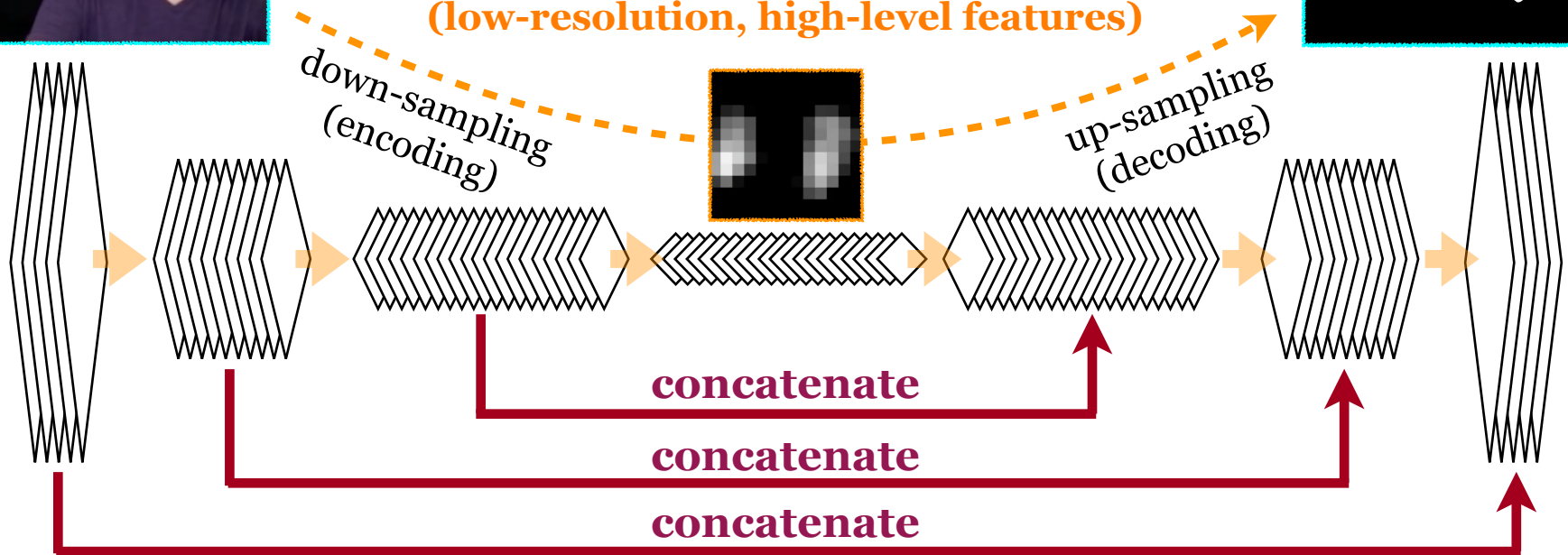


How pixel segmentation works

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Intermediate Data Tensor
(low-resolution, high-level features)

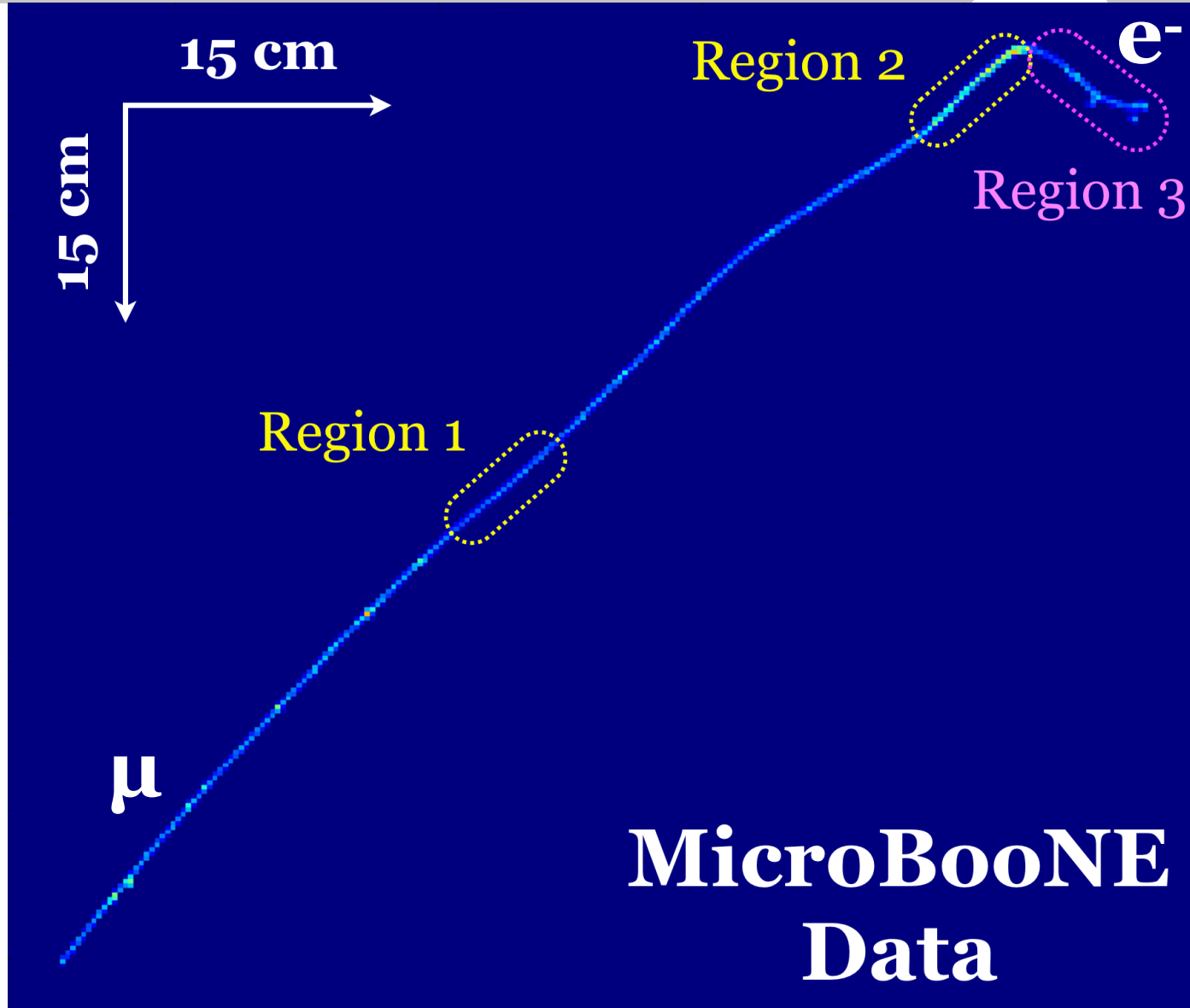


Concatenation recovers spatial resolution information

Early Demonstrations

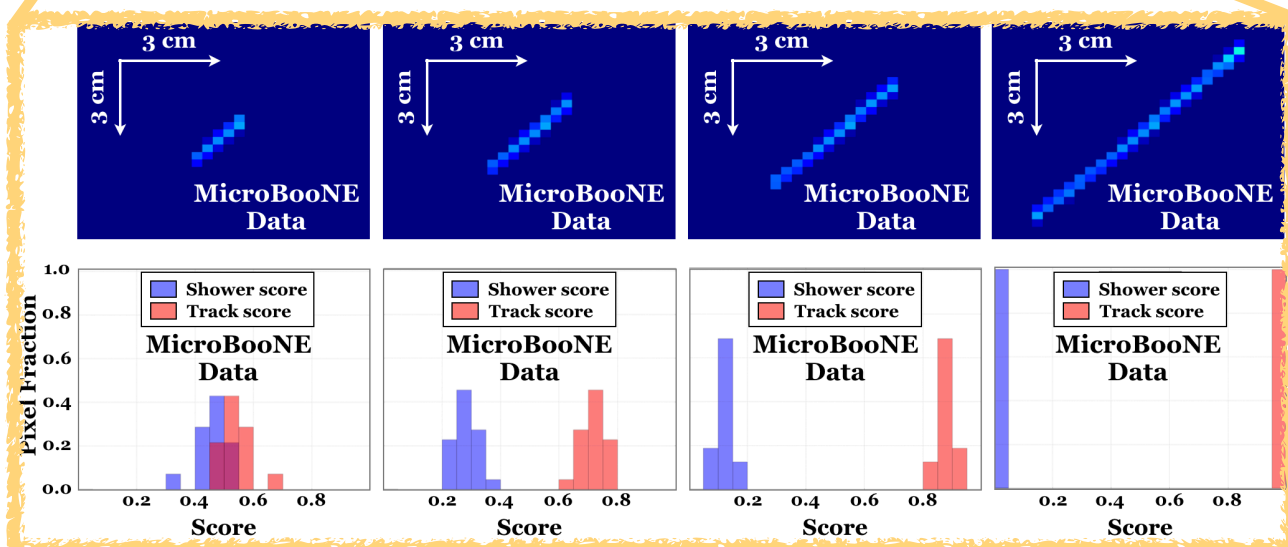
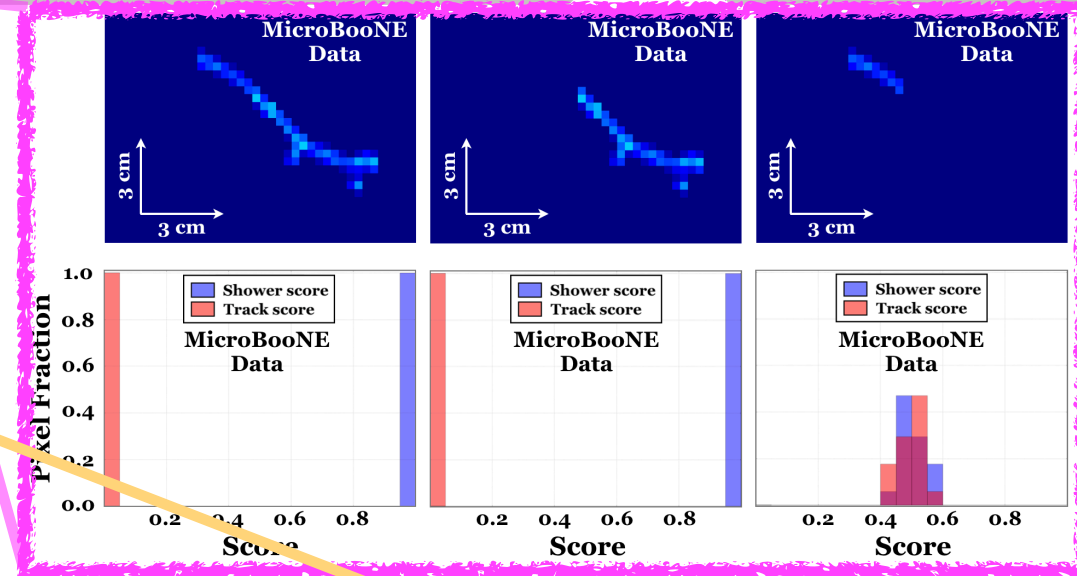
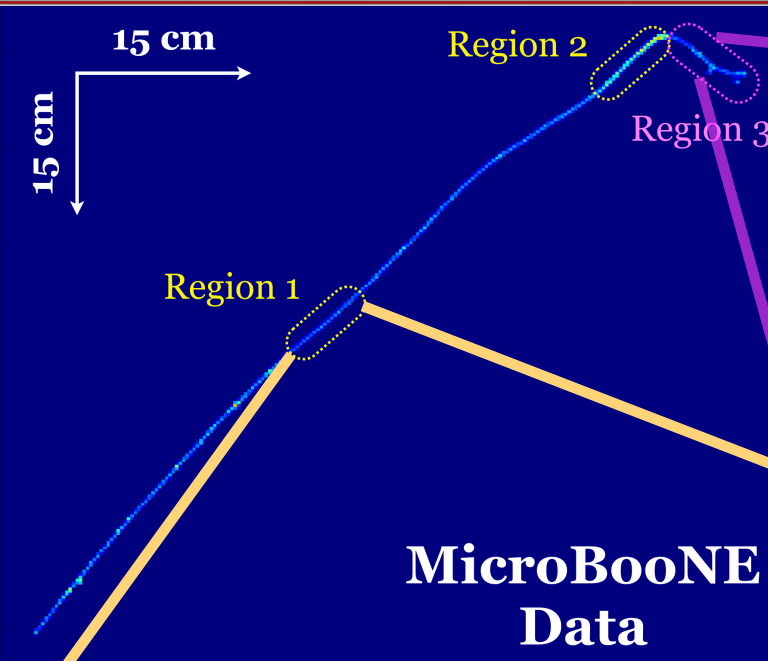
Machine Learning for LArTPC Image Analysis

SLAC



Early Demonstrations

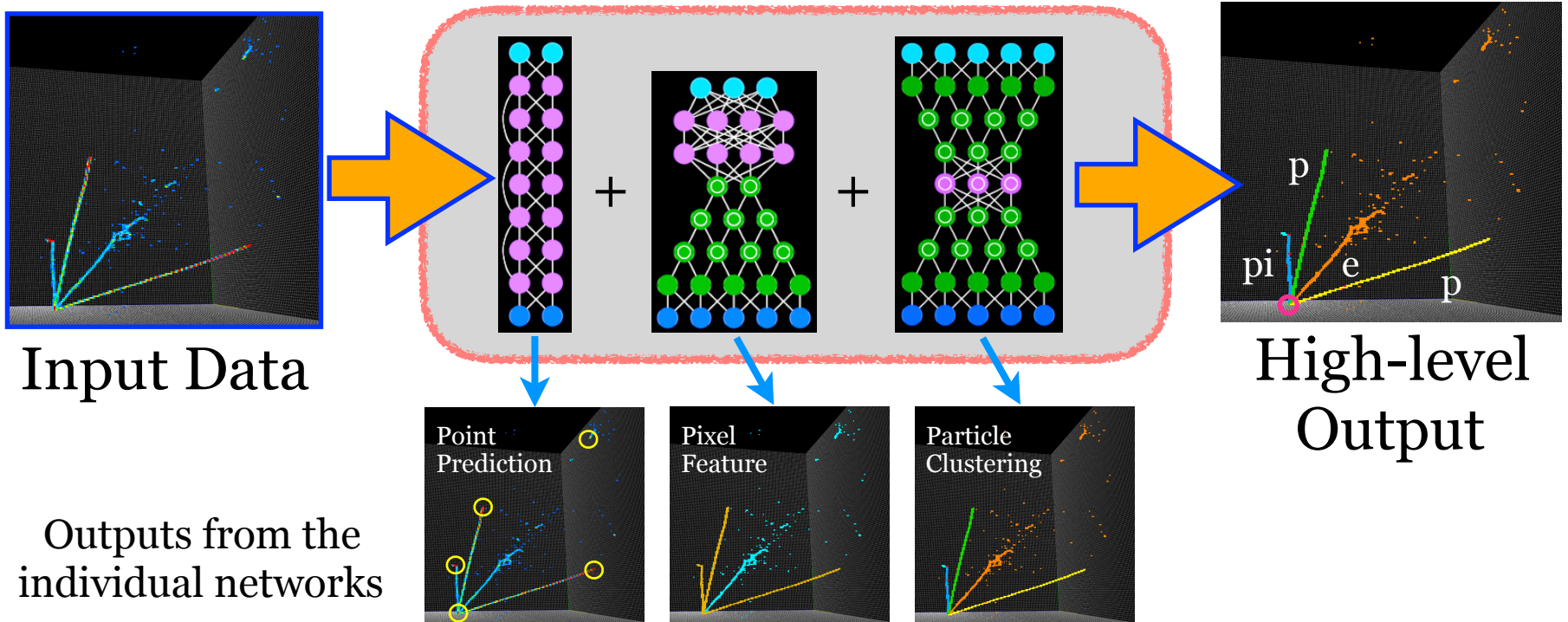
Machine Learning for LArTPC Image Analysis



Localized features at the pixel-level are useful to inspect correlation of data features & algorithm responses

Multi-task Deep Neural Network

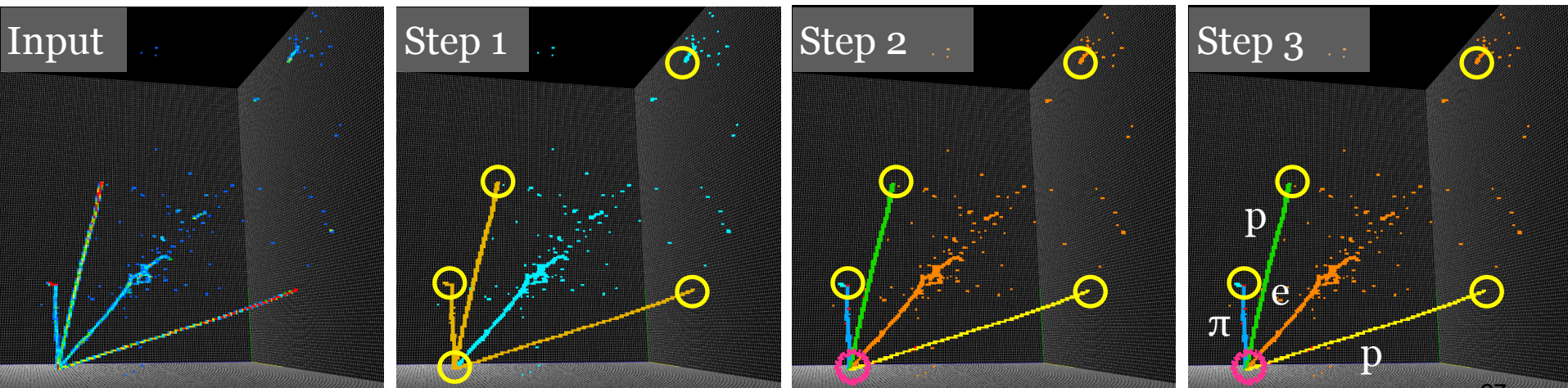
Introduce physical feature extraction tasks (reconstruction) to bias the data transformation. Implicitly introduce physics concepts + construct logic for the final output.



ML-based Full Data Reconstruction Chain

- A cluster of many task-specific networks in 2D & 3D
 - Vertex finding, clustering, particle ID, etc.

- ❑ 1. Key points (track edges) + pixel feature annotation
- ❑ 2. Vertex finding + particle clustering
- ❑ 3. Particle type + energy/momentum
- ❑ 4. Hierarchy building



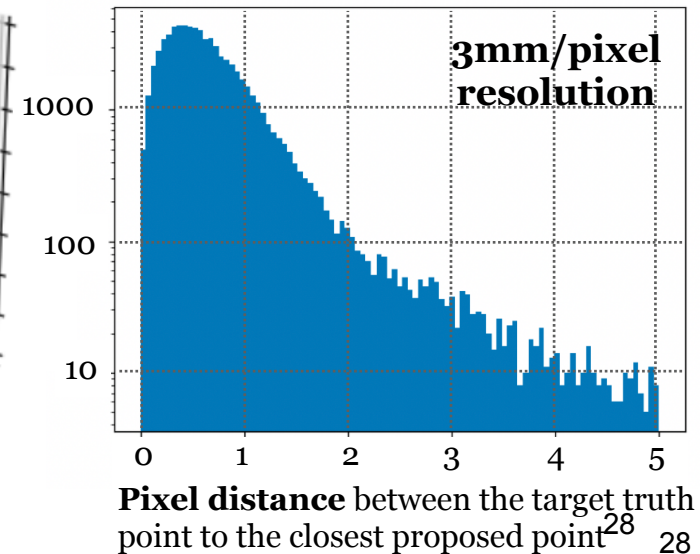
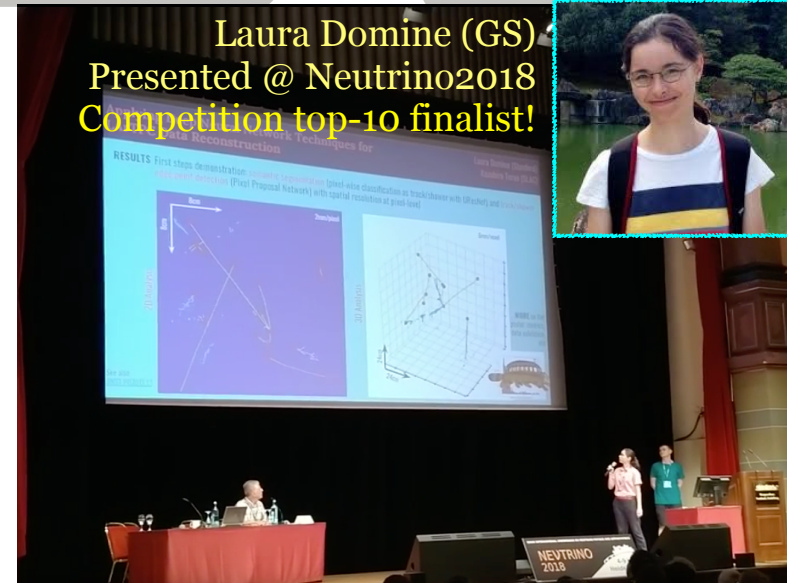
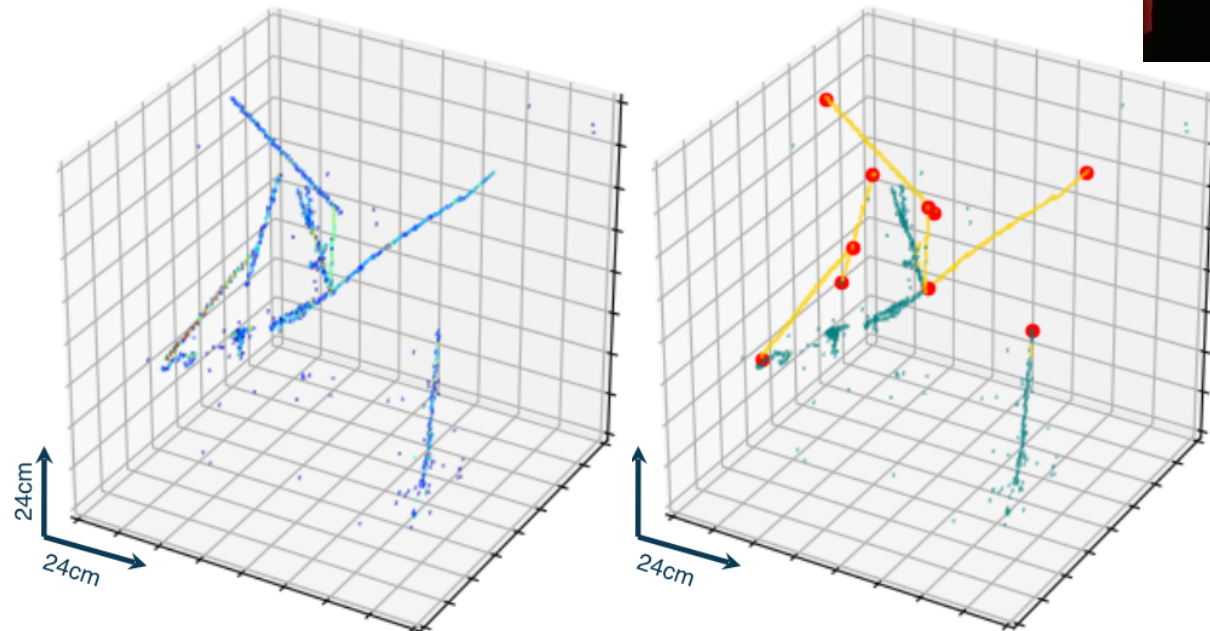
Toward Full 3D Reconstruction Chain

Machine Learning for Particle Image Analysis

SLAC

Multi-Task Network Cascade

- **Chain of Segmentation + Detection**
 - Feature points: “shower start” and “track edges”
 - Classify each pixel into “shower” vs. “track”
- **Extension to 3D data**
 - Change in tensor dimensions, identical algorithms

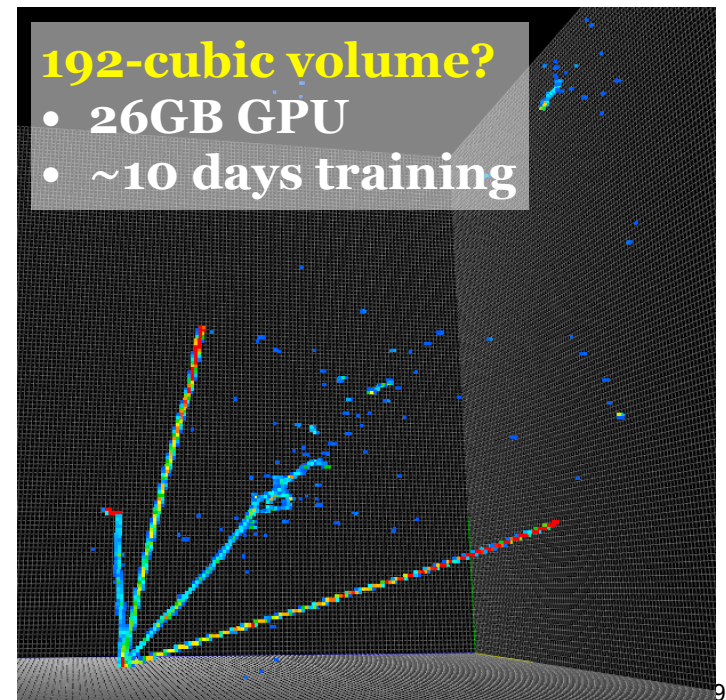
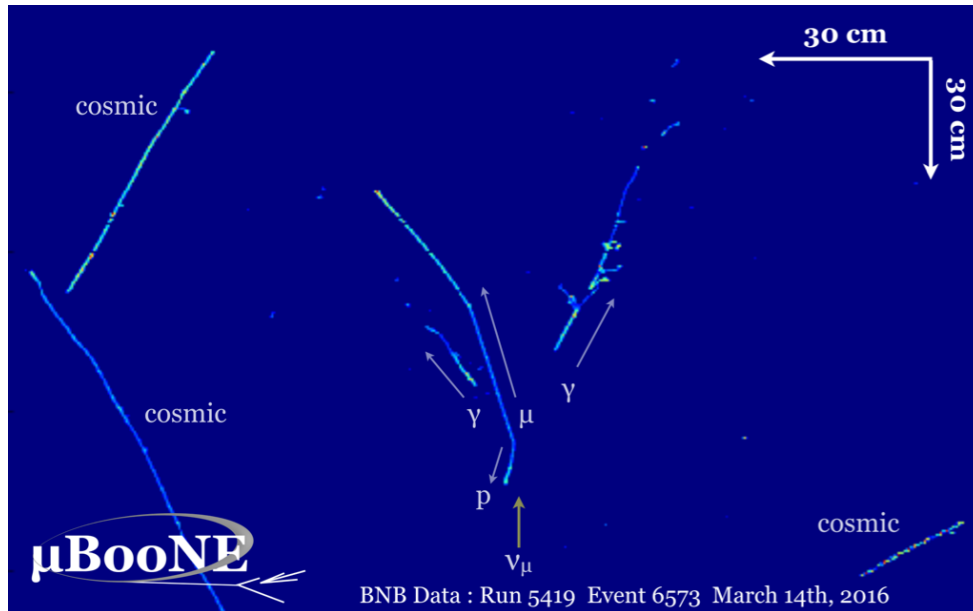


Toward Full 3D Reconstruction Chain

Machine Learning for Particle Image Analysis

“Applying for 3D” is simple, **but is it scalable?**

- LArTPC data is generally sparse but locally dense
 - Mostly zero-filled matrix. **CNN = dense matrix operation = bad!**
 - Matrix size (volume) scales by power low, but non-zero pixels scales almost linearly (most particle trajectories are locally 1D line)



Toward Full 3D Reconstruction Chain

Machine Learning for Particle Image Analysis

SLAC

“Applying for 3D” is simple, **but is it scalable?**

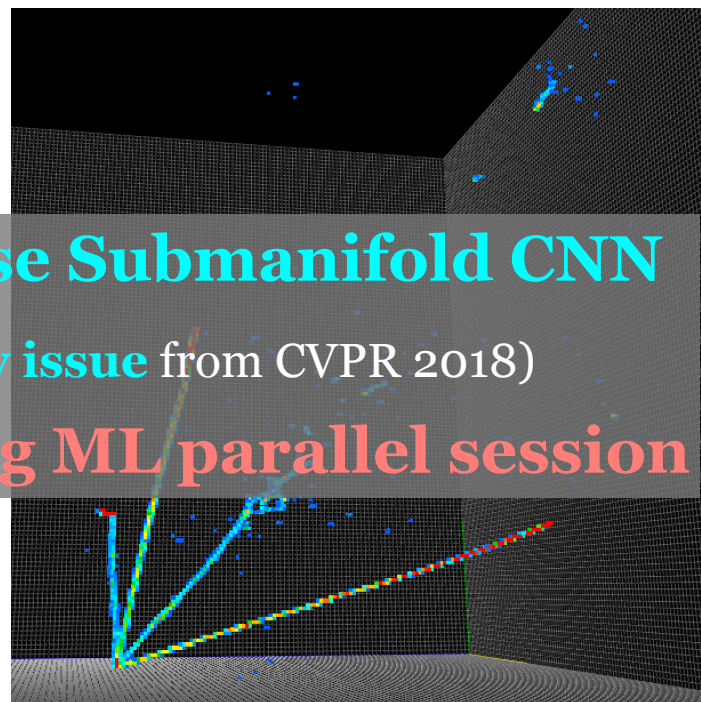
- LArTPC data is generally sparse but locally dense
 - Mostly zero-filled matrix. **CNN = dense matrix operation = bad!**
 - Matrix size (volume) scales by power low, but non-zero pixels scales almost linearly (most particle trajectories are locally 1D line)



Laura Domine will talk about **Sparse Submanifold CNN**
(a possible **solution to the scalability issue** from CVPR 2018)
Go see her talk on **Tuesday morning ML parallel session**

μBooNE

BNB Data : Run 5419 Event 6573 March 14th, 2016

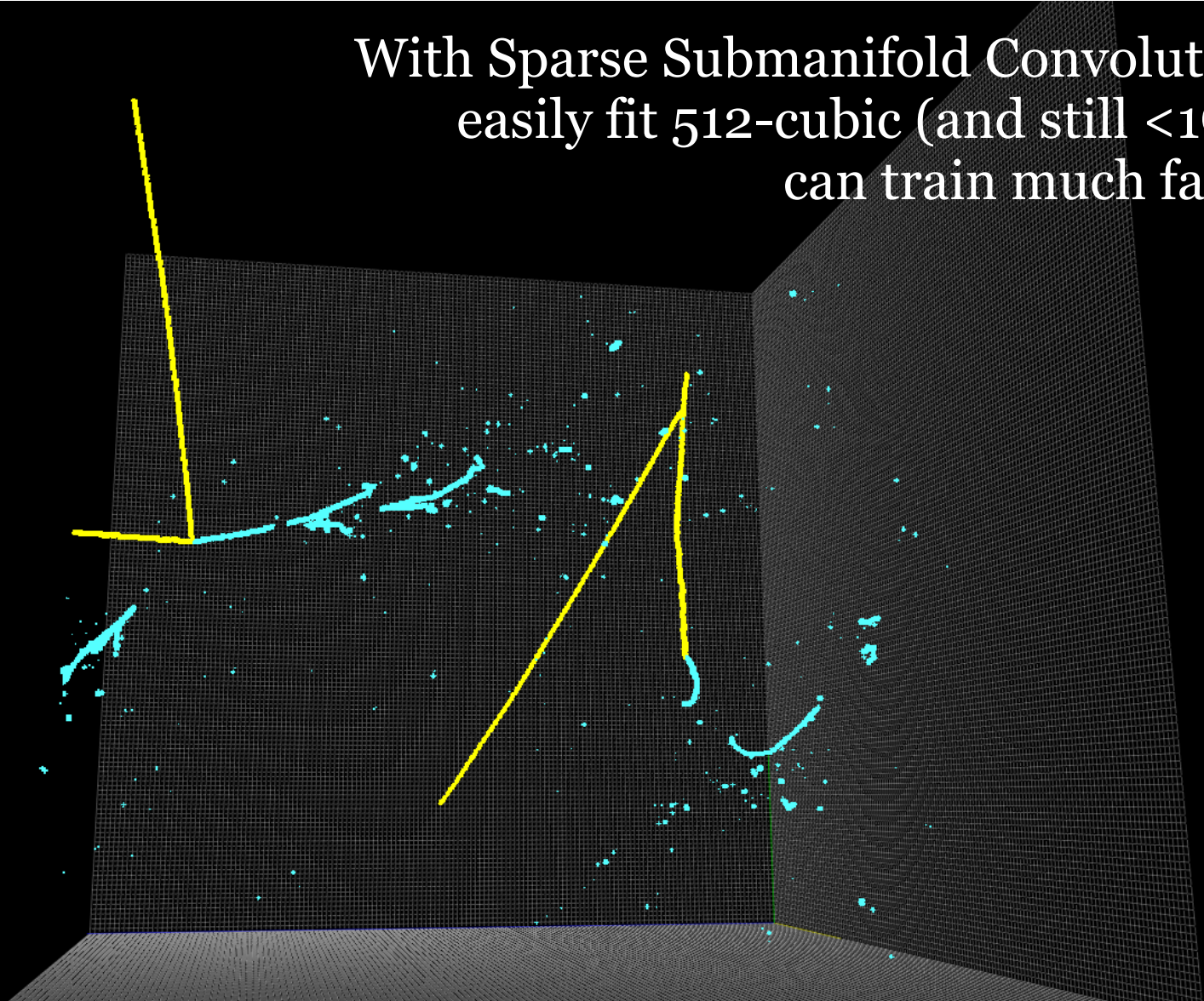


Toward Full 3D Reconstruction Chain

Machine Learning for Particle Image Analysis

SLAC

With Sparse Submanifold Convolution,
easily fit 512-cubic (and still <1GB)
can train much faster



Toward Full 3D Reconstruction Chain

Machine Learning for Particle Image Analysis

SLAC

More space to learn...

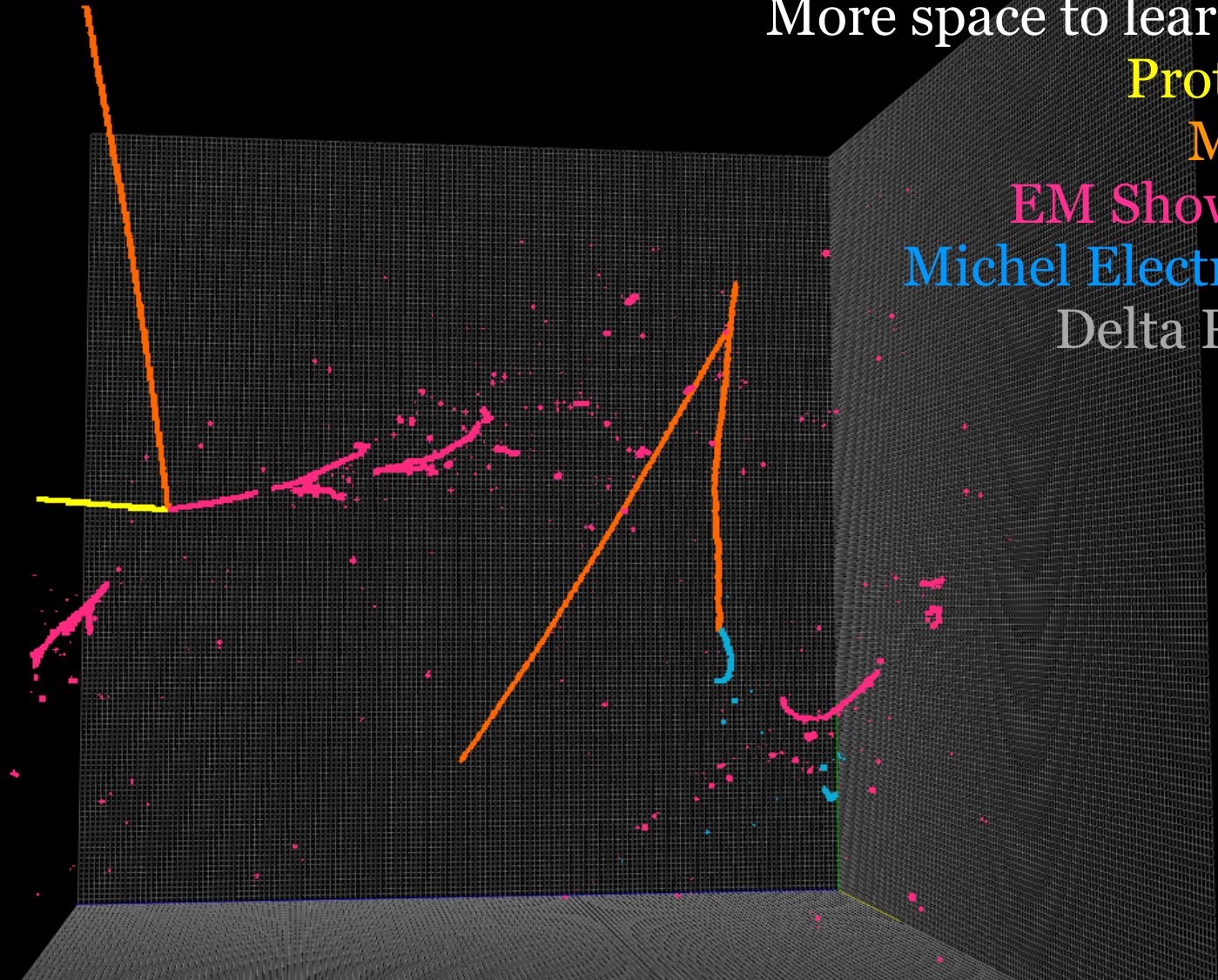
Proton

MIP

EM Shower

Michel Electron

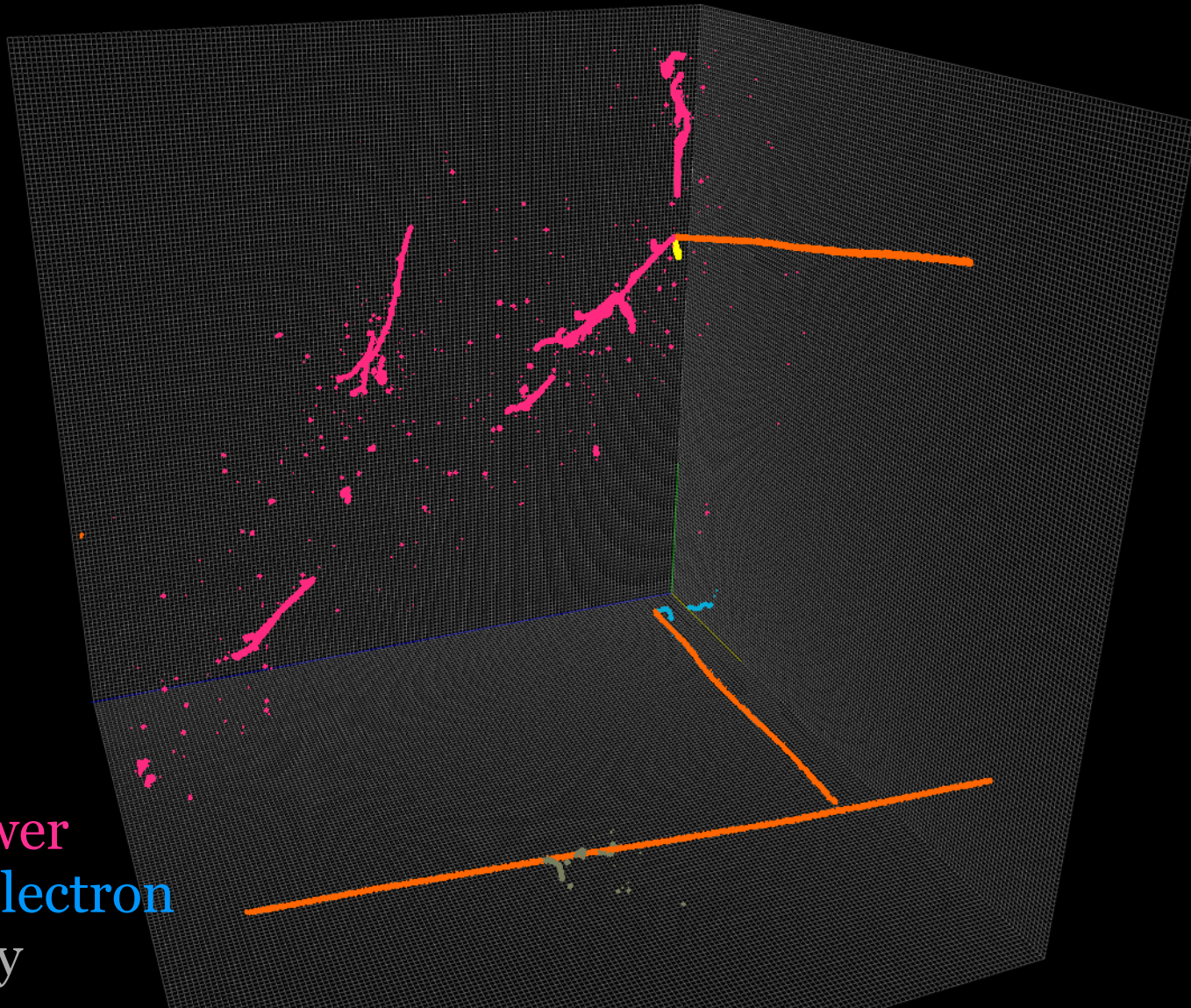
Delta Ray



Toward Full 3D Reconstruction Chain

Machine Learning for Particle Image Analysis

SLAC



Proton
MIP
EM Shower
Michel Electron
Delta Ray



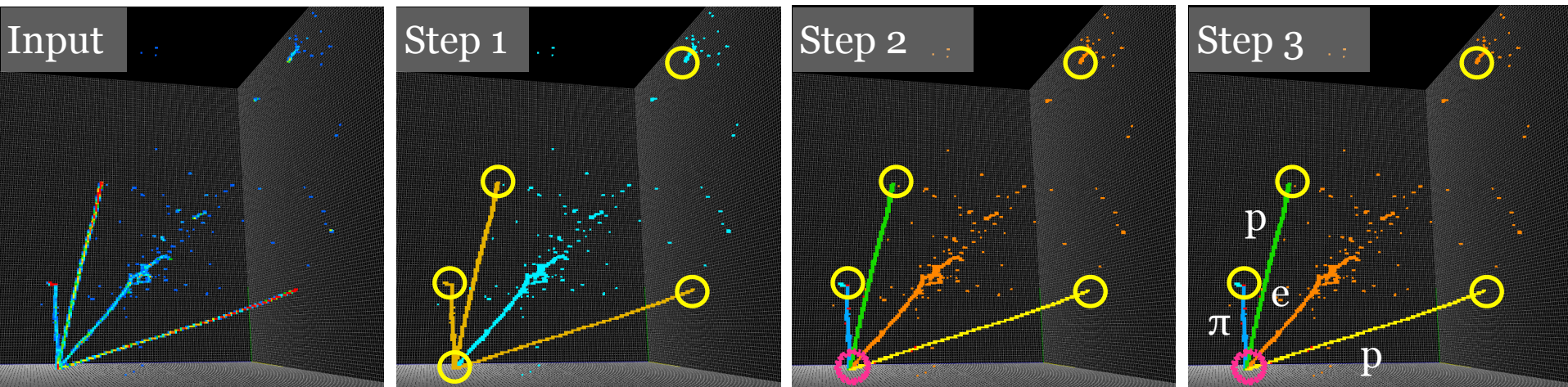
... wrapping up ...

Toward Full 3D Reconstruction Chain

Machine Learning for Particle Image Analysis

Where we are...

- 1. Space point (track edges) + pixel feature annotation
- 2. Vertex finding + particle clustering
- 3. Particle type + energy/momentum
- 4. Hierarchy building



Aiming to **complete the full chain v.1** in early 2019, move to **physics analysis applications**

Sharing Our R&D Machine Learning & Broader Impact

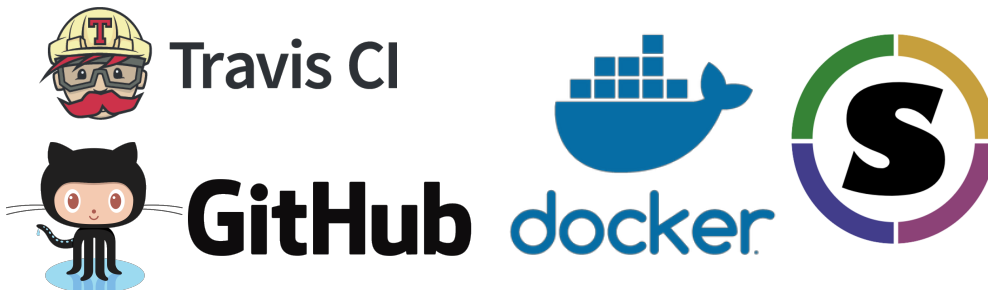


Public Data Set: OSF

The screenshot shows the OSF interface for the 'DeepLearnPhysics Public Dataset'. The header includes navigation links like 'My Quick Files', 'My Projects', 'Search', 'Support', 'Donate', and 'DeepLearnPhysics'. The main content area displays the dataset name, creation date (2018-12-03), and last update (2018-12-05). It includes a description of the data sharing project, a list of three goals (publicly available data, software containers, and documented results), and a 'Files' section with a table listing the dataset. A 'Wiki' section provides a detailed description of the project's purpose and goals.

Software Containers

The screenshot shows the GitHub repository page for 'deeplearnphysics/ml-larcv2'. The header indicates it is a 'PUBLIC | AUTOMATED BUILD' repository. The main content area features a 'Short Description' (ML+LARCv2 docker container image builder) and a 'Full Description' (LArCV: Liquid Argon Computer Vision). The full description includes a list of build statuses (build passing, license MIT, hosted singularity-hub, docker build passing) and a detailed overview of the framework's purpose and capabilities. A 'Tags' section lists various Docker images and their dependencies.

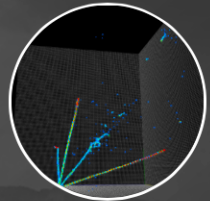


Sharing Our R&D Machine Learning & Broader Impact

SLAC

DeepLearnPhysics (deeplearnphysics.org)

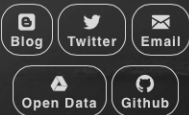
- **Collaboration** for ML technique R&D
 - ~70 members including HEP exp/theory, nuclear physics, BES (LCLS, SSRL), Cryo-EM, accelerator, AI/CS community
- **Open source** software/tools, containers, open data
 - our framework to collaborate & share reproducible results
- **Community building**
 - In-person tutorials (SLAC, LBNL, FNAL, BNL, VTech, MIT, Columbia...)
 - Sharing talk invitations, job/funding opportunities, etc.



DeepLearnPhysics

Research Collaboration

About us



Hands-on workshop
@ SLAC/Stanford



CodaLab

Search Competitions My Competitions Help Sign Up Sign In

Competition

Semantic Segmentation of LArTPC tracks
Organized by HolyBytes - Current server time: Aug. 14, 2018, 5:32 p.m. UTC

Previous **Current** Next
Private 2 Private 3 Private 3
Aug. 12, 2018, 1 a.m. UTC Oct. 2, 2018, 1 a.m. UTC Oct. 2, 2018, 1 a.m. UTC

Learn the Details Phases Participate Results Forums

Overview

Evaluation

Terms and Conditions

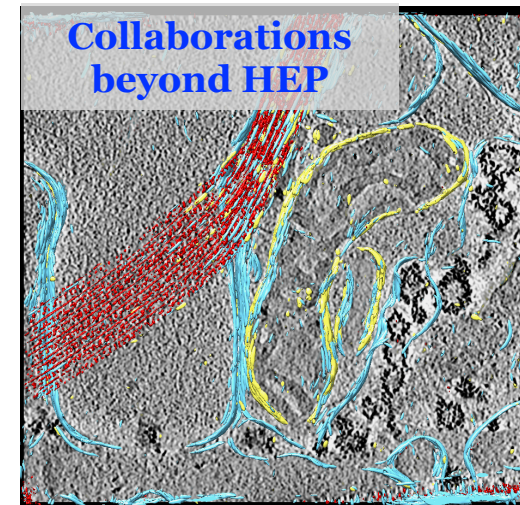
Starter kit

Why segmenting pixels?

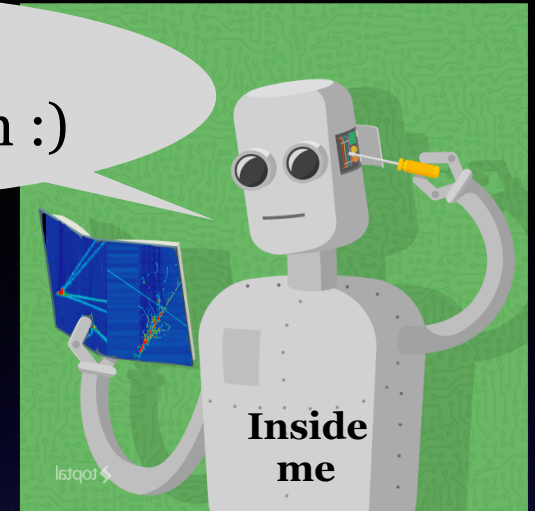
In the first step of this challenge we ask you to classify non-zero pixels into two basic category of particles: energy deposited by electron/positron, referred to as EM-particle, vs. all other particles. An accurate identification of EM-particle pixels is a crucial task to identify electron neutrino interaction for neutrino oscillation experiments using LArTPC detectors. In a traditional data reconstruction process of LArTPC experiments, this distinction is made after pixels are clustered into individual particles and analyzing the topological feature of clustered pixels. However, this is proven to be difficult. Instead, having a pixel-level distinction of EM-particles beforehand can improve the performance of clustering and simplify the rest of data reconstruction chain.

At the second step of the challenge, we will add another distinct label to those pixels that contain energy deposited by protons. Two most basic yet important neutrino interaction final states contain electron+proton from electron neutrino interaction, or muon+proton from muon neutrino interaction. Adding the proton label therefore

Public challenge (collab. w/ LHC)



Thank you!
for your attention :)



Take Away Messages

1. **LArTPCs** are **high resolution particle imaging detectors**
2. **Deep neural networks (DNNs)** are **efficient image feature extraction techniques** developed in computer vision
3. **DNNs** can be **used for ML-based full data reco chain**
4. **Scalability** can be **addressed using SSCN** (see Laura's talk)
5. **Reco chain** is **being developed toward physics results :)**

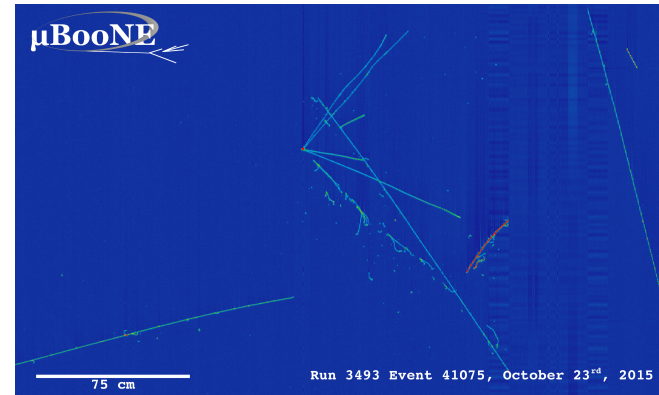
Toward Full 3D Reconstruction Chain

Machine Learning for Particle Image Analysis

Collaboration / Synergies

Wire LArTPC for 3D

- WireCell team (BNL) on SBN/DUNE
- Cluster3D (SLAC) on SBN
- LArFlow (Tufts) on MicroBooNE



Pixel LArTPC

- Interest from LBNL/UTA/Bern/MSU
 - Looking forward to 2x2 ArgonCUBE modules
 - Plan/Start working with students specifically for DUNE ND

Computing

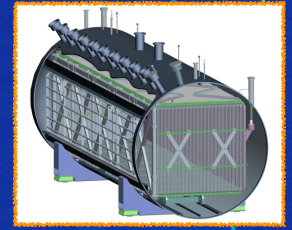
- ANL demonstrating our code on distributed environment
- ORNL+FNAL colleagues to submit ALCC for Summit HPC
- FPGA-based inference system R&D (HEP-wide + beyond)

Back-up Slides

Next Neutrino Detectors?

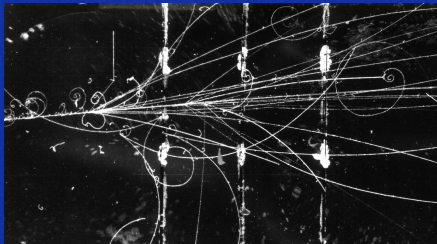
μ BooNE

~mm/pixel spatial resolution
~MeV level sensitivity



MicroBooNE
~87 ton (school bus size)

ν_{μ}



Bubble Chamber

Liquid Argon Time Projection Chamber

- Chamber-like images: digitized electronics readout
- Calorimetric measurement + scalability to a large mass

2015

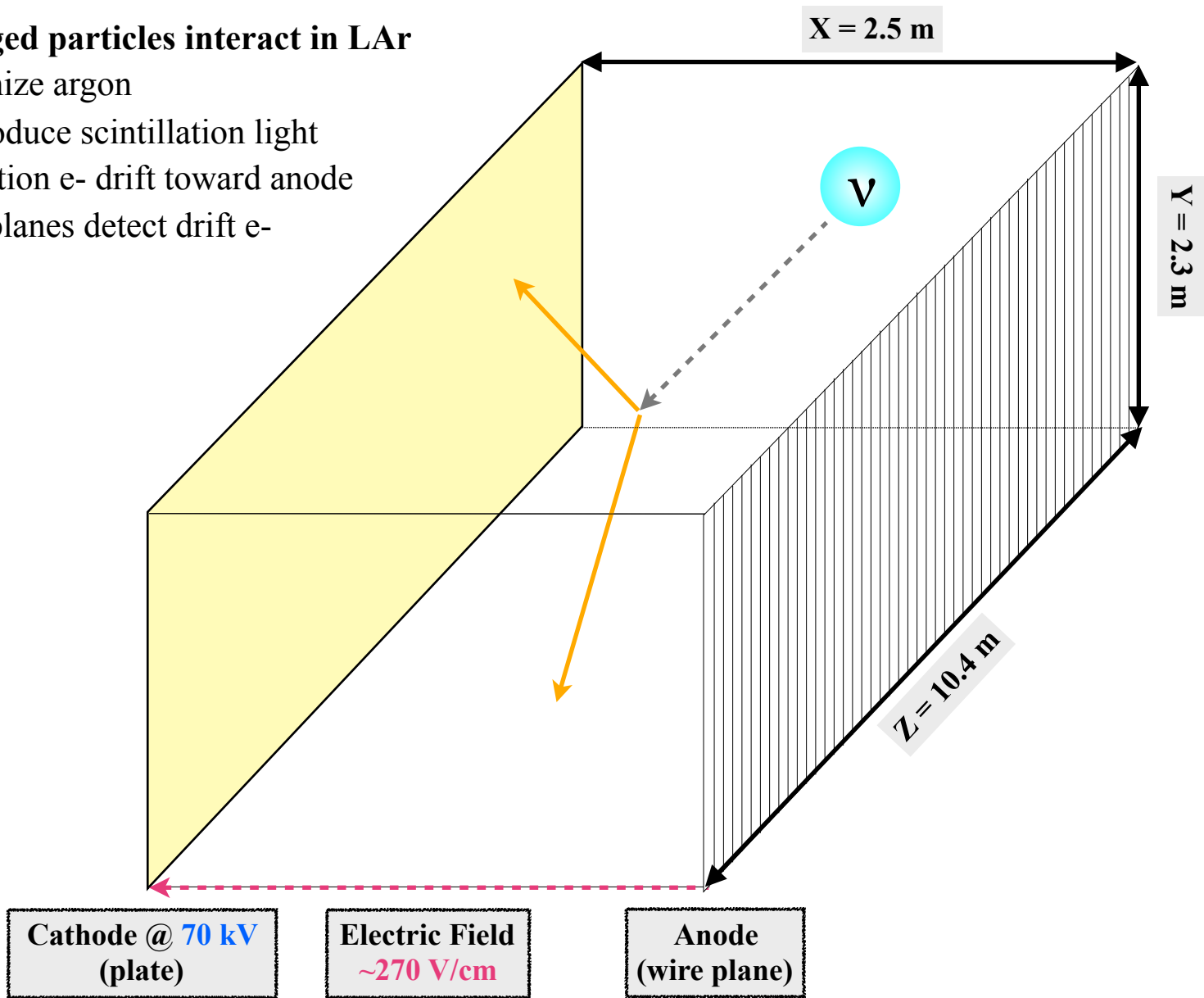
How Wire LArTPC (MicroBooNE) Work (I)

1. Charged particles interact in LAr

- Ionize argon
- Produce scintillation light

2. Ionization e- drift toward anode

3. Wire planes detect drift e-



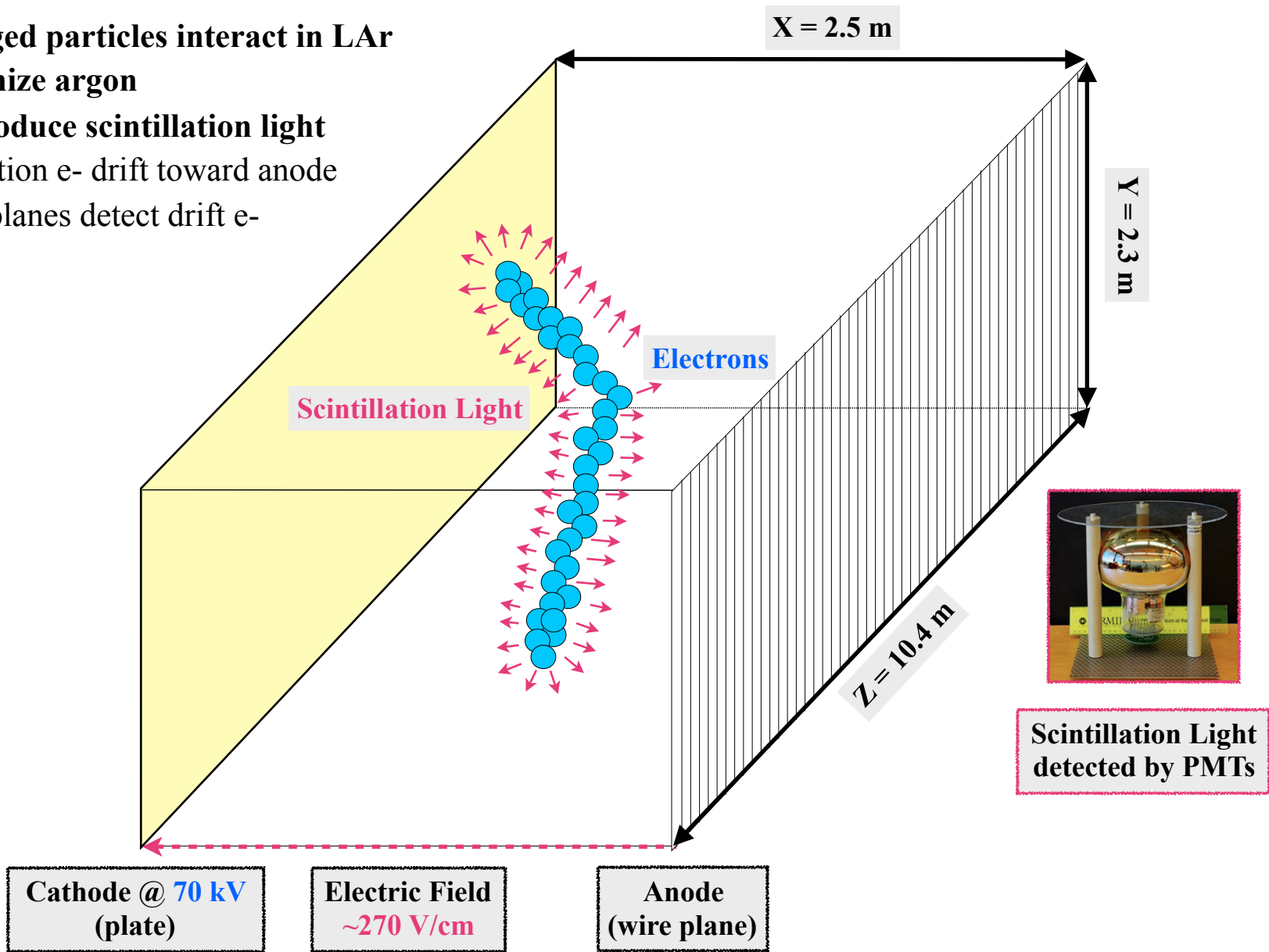
How Wire LArTPC (MicroBooNE) Work (I)

1. Charged particles interact in LAr

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- Produce scintillation light

2. Ionization e- drift toward anode

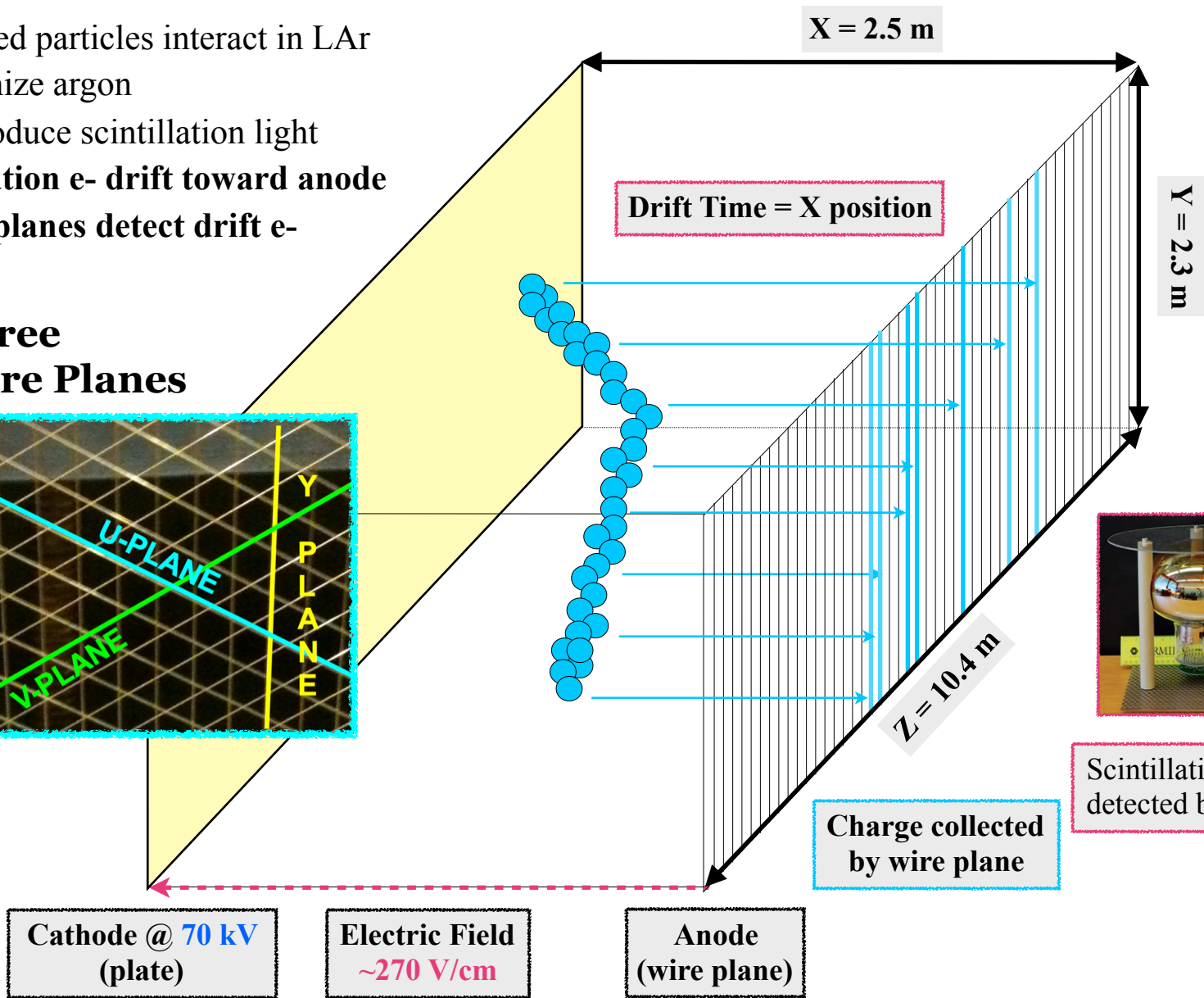
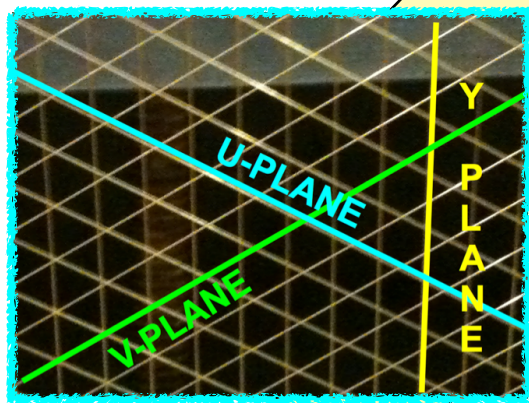
3. Wire planes detect drift e-



How Wire LArTPC (MicroBooNE) Work (I)

1. Charged particles interact in LAr
 - Ionize argon
 - Produce scintillation light
2. Ionization e- drift toward anode
3. Wire planes detect drift e-

Three Wire Planes

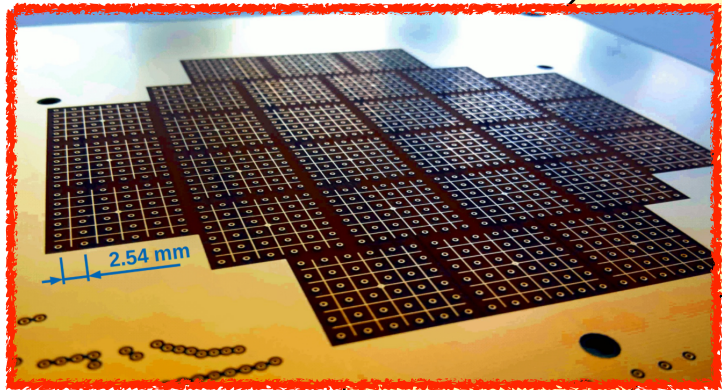


How ~~Wire~~ LArTPC (~~MicroBooNE~~) Work (I)

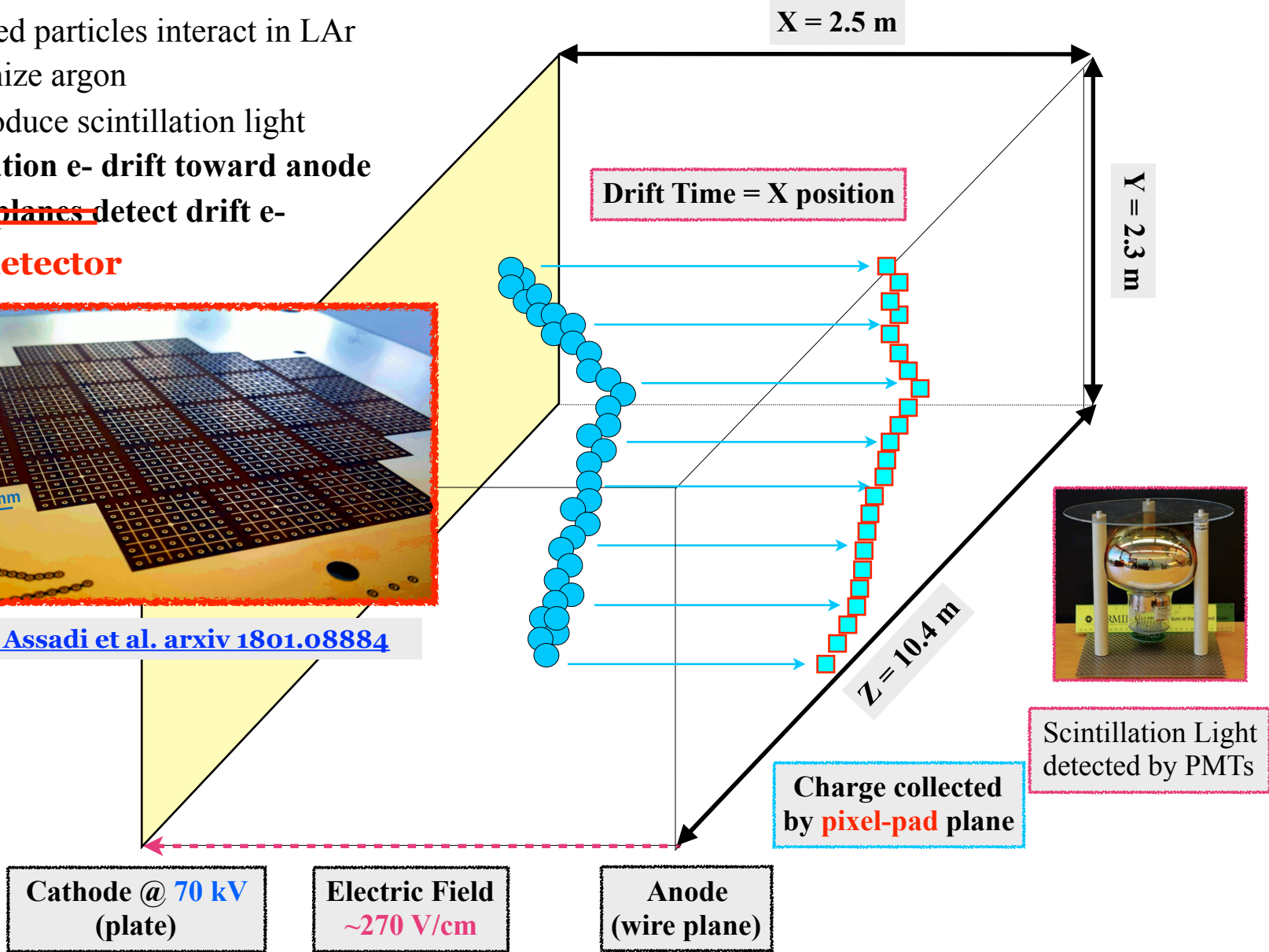
Pixel

DUNE-ND

1. Charged particles interact in LAr
 - Ionize argon
 - Produce scintillation light
2. Ionization e- drift toward anode
3. ~~Wire planes~~ detect drift e-
pixel detector

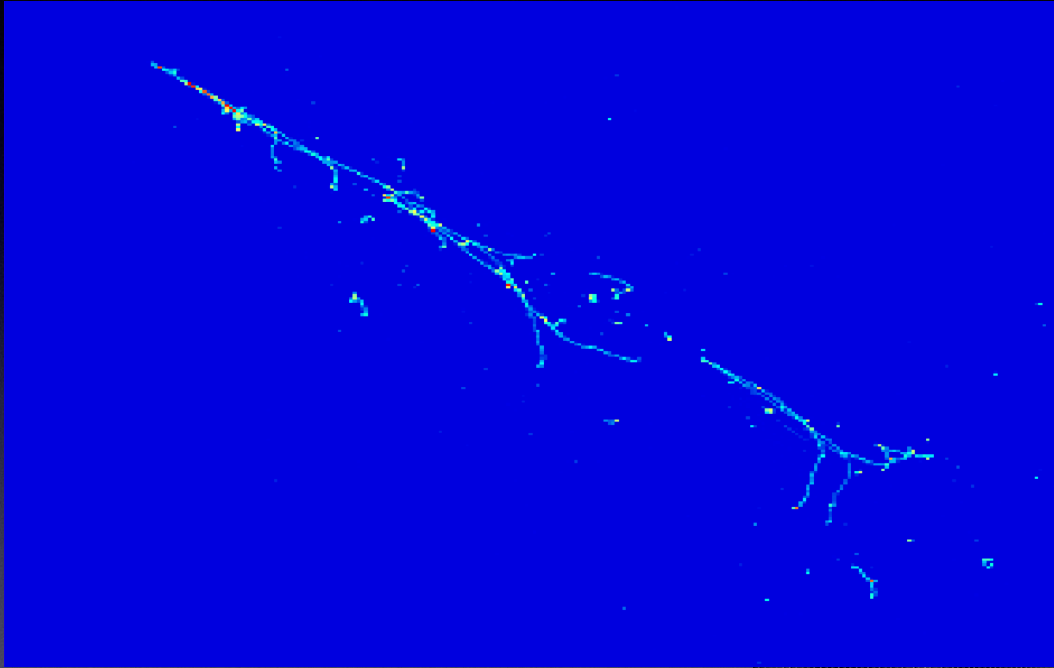


J. Assadi et al. arxiv 1801.08884



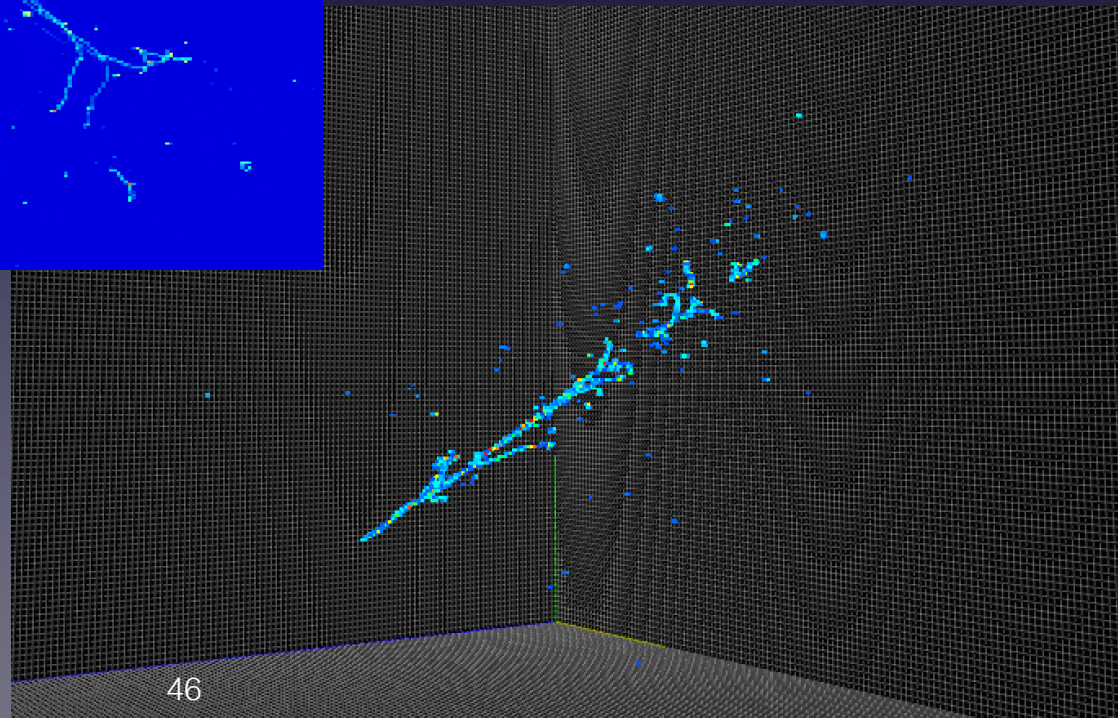
LArTPC: Particle Imaging Detector

... when things work ...



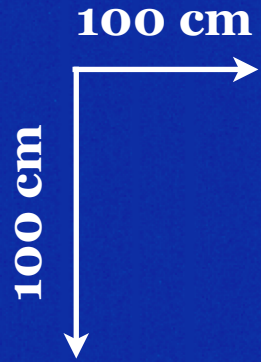
2D Projection
(Wire Detector)

3D Imaging
(Pixel Detector)



Challenges in Data Analysis?

100 cm
100 cm



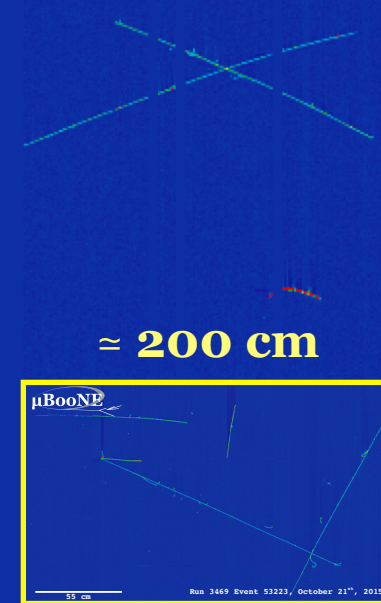
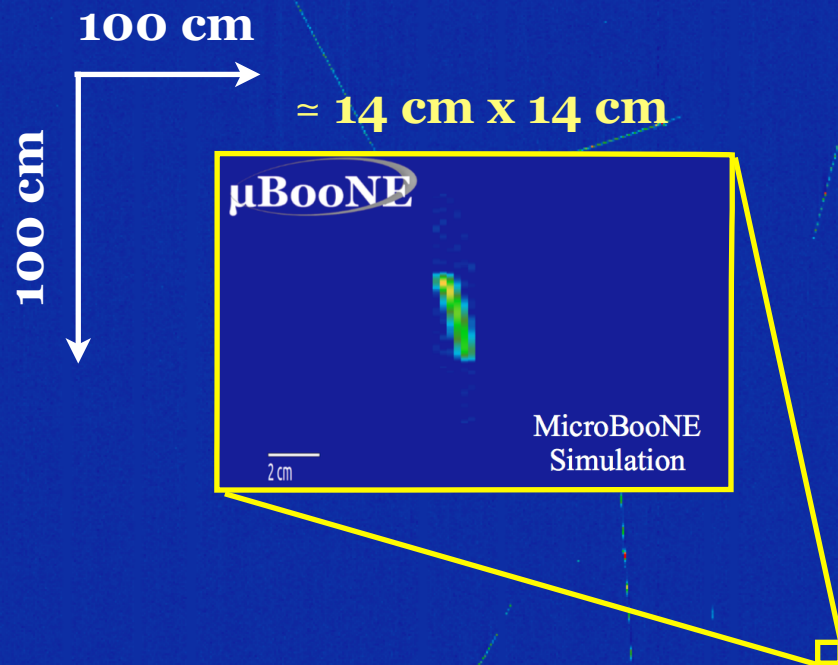
μBooNE



There may be lots of backgrounds

Cosmic Data : Run 6280 Event 6812 May 12th, 2016

Challenges in Data Analysis?

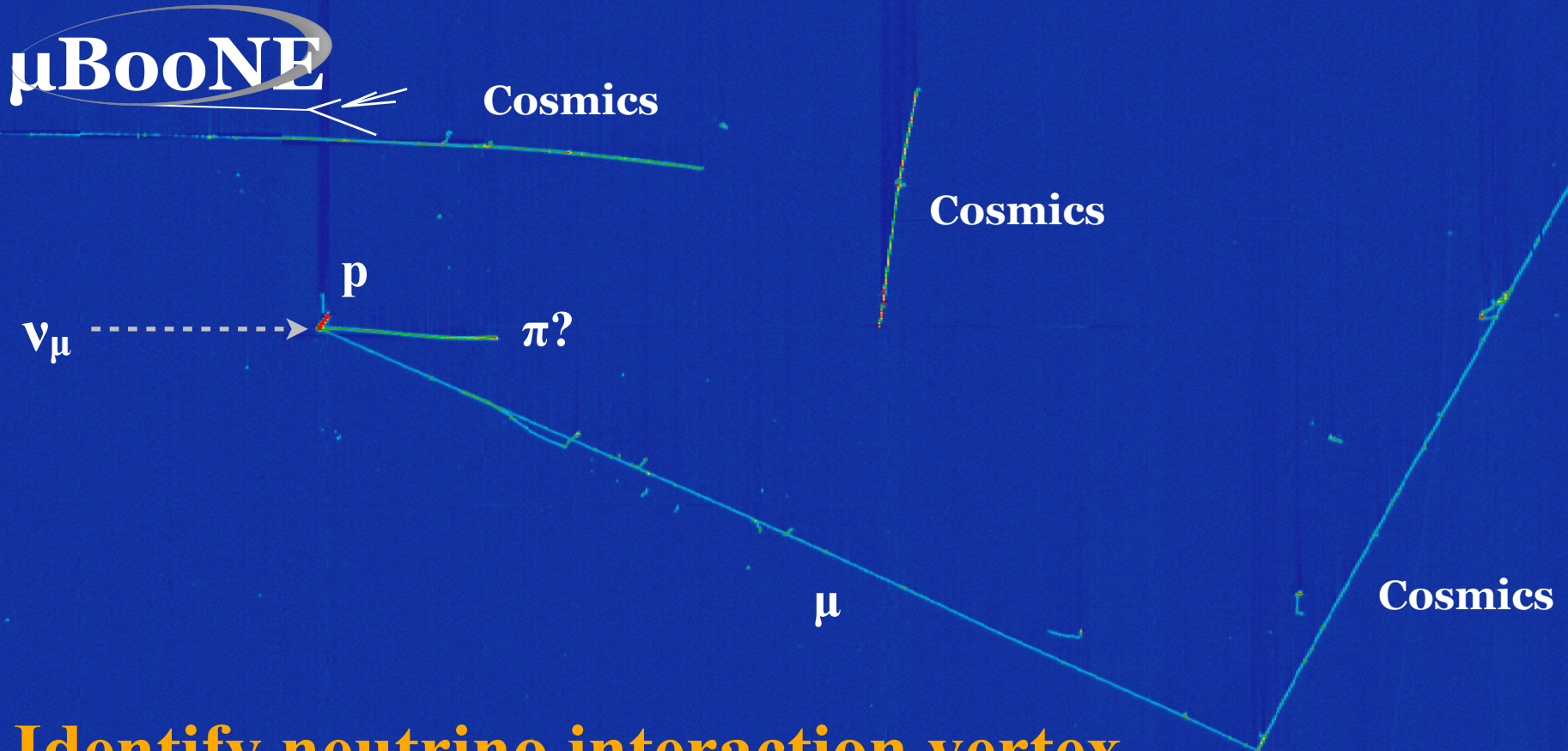


Interaction vertex can be anywhere in LAr, varying in size (cm ~ meters)



Cosmic Data : Run 6280 Event 6812 May 12th, 2016

Challenges in Data Analysis?



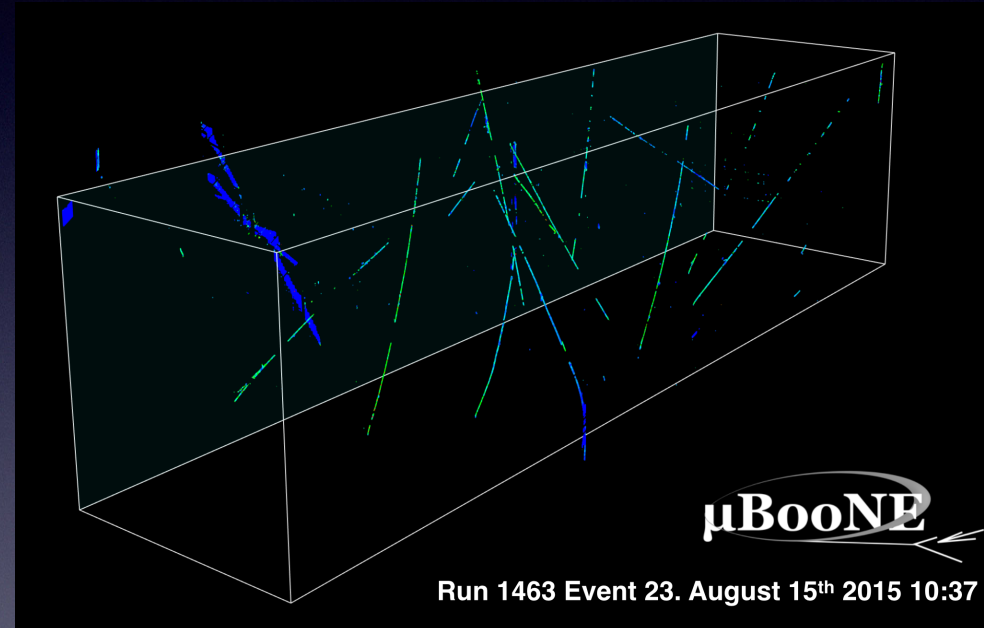
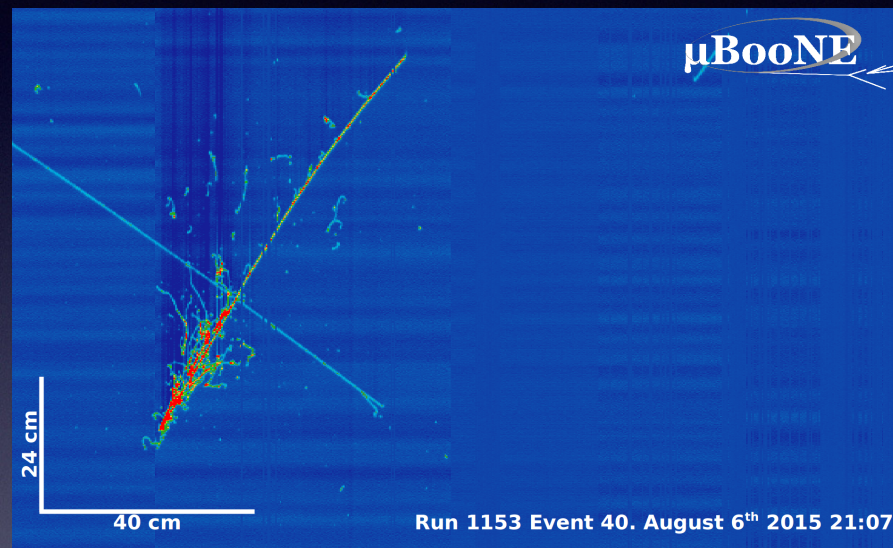
**Identify neutrino interaction vertex,
cluster individual particle energy depositions**

55 cm

Run 3469 Event 53223, October 21st, 2015

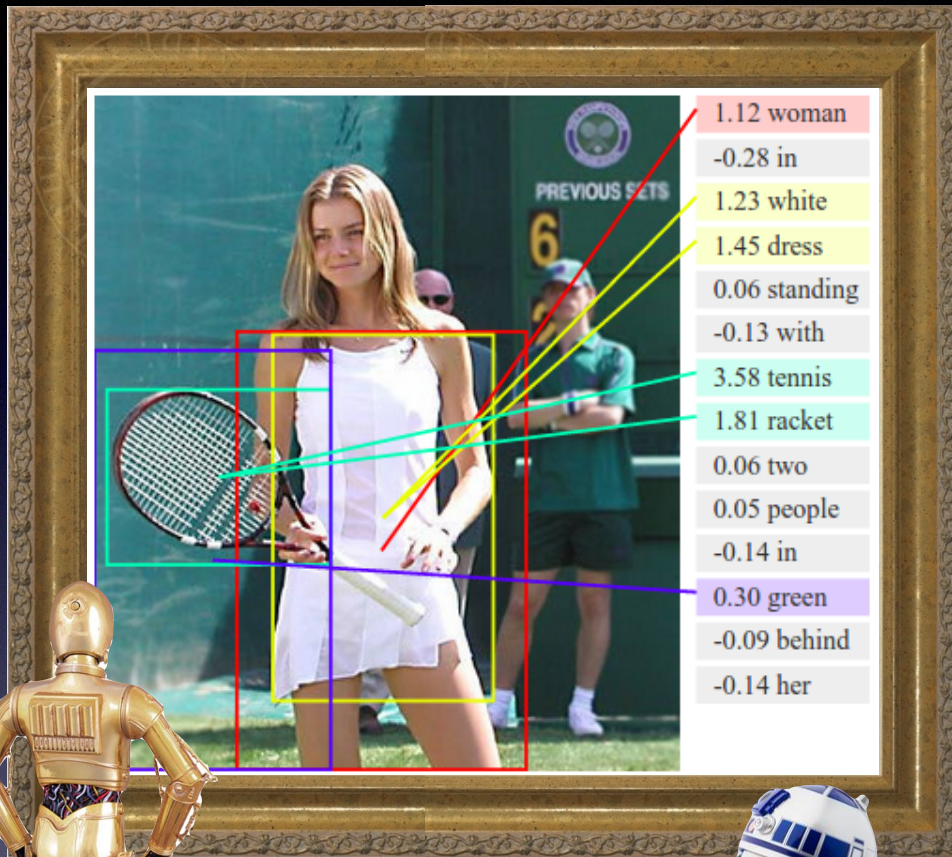
Challenges in Data Analysis?

**Deal with optical illusions in 2D projections
+ pattern recognitions in 3D**



“Physics features” look obvious to human physicists (eyes) but hand-engineering algorithms to extract them turned out challenging...

Image context analysis



“Pose” detection



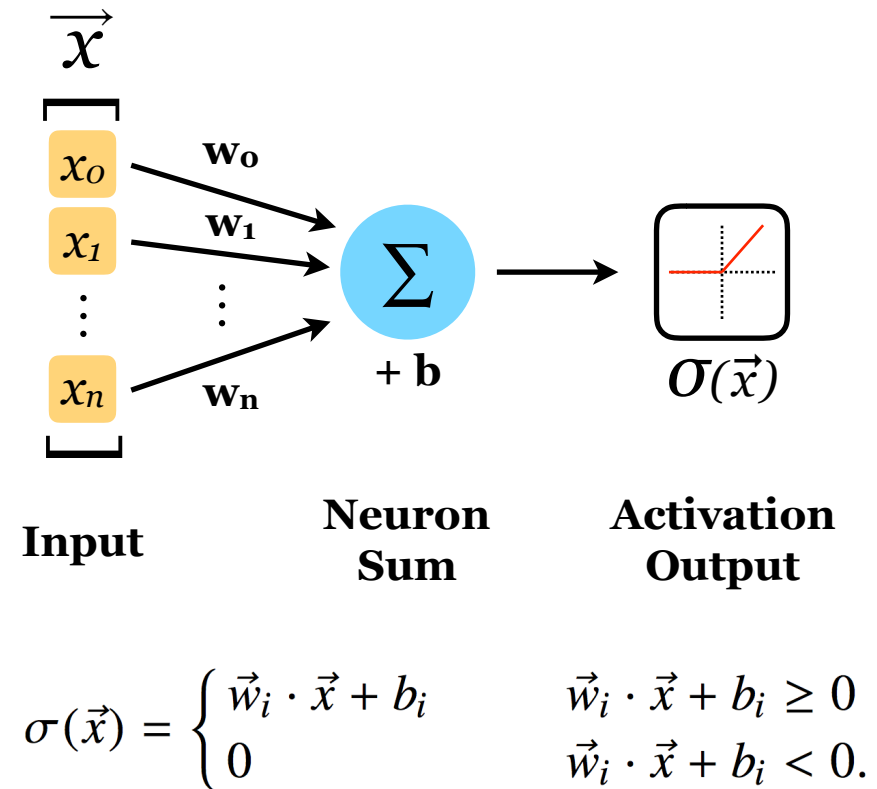
Convolutional
Neural
Network
~ *How does it work?* ~

Machine Learning Overview

Simple neural network (perceptron)

The basic unit of a neural net is the *perceptron* (loosely based on a real neuron)

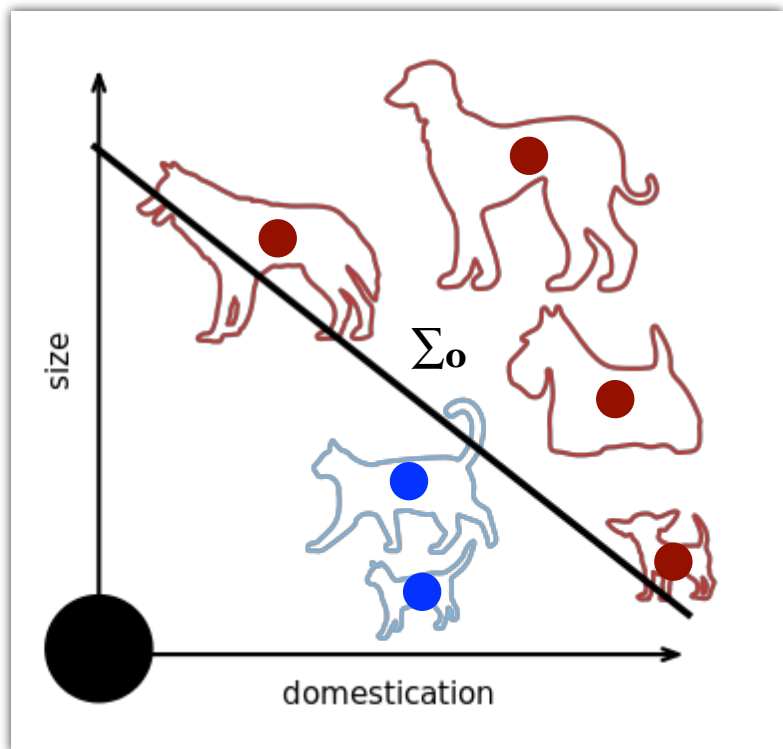
Takes in a vector of inputs (x). Commonly inputs are summed with weights (w) and offset (b) then run through activation.



Machine Learning Overview

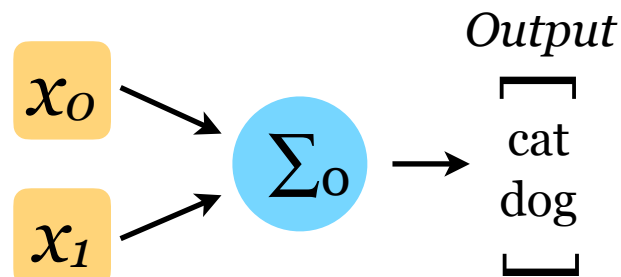
Simple neural network (perceptron)

Imagine using two features to separate cats and dogs



from [wikipedia](https://en.wikipedia.org/wiki/Perceptron)

$$\sigma(\vec{x}) = \begin{cases} \vec{w}_i \cdot \vec{x} + b_i & \vec{w}_i \cdot \vec{x} + b_i \geq 0 \\ 0 & \vec{w}_i \cdot \vec{x} + b_i < 0. \end{cases}$$

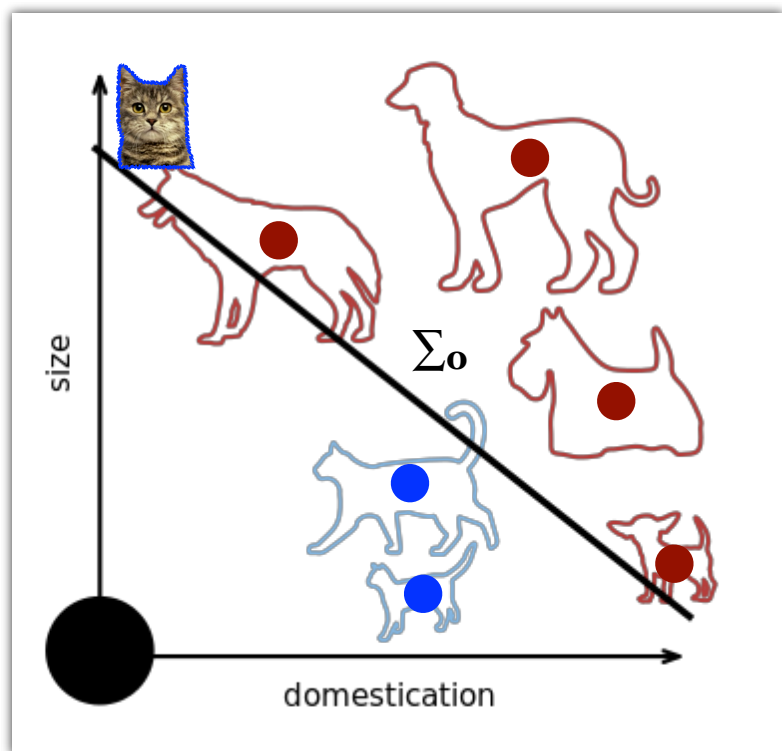


By picking a value for \mathbf{w} and \mathbf{b} , we define a boundary between the two sets of data

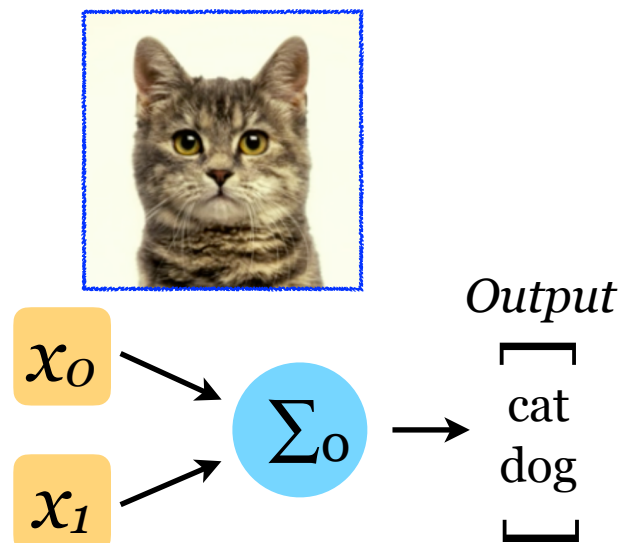
Machine Learning Overview

Simple neural network (perceptron)

What if we have a new data point?



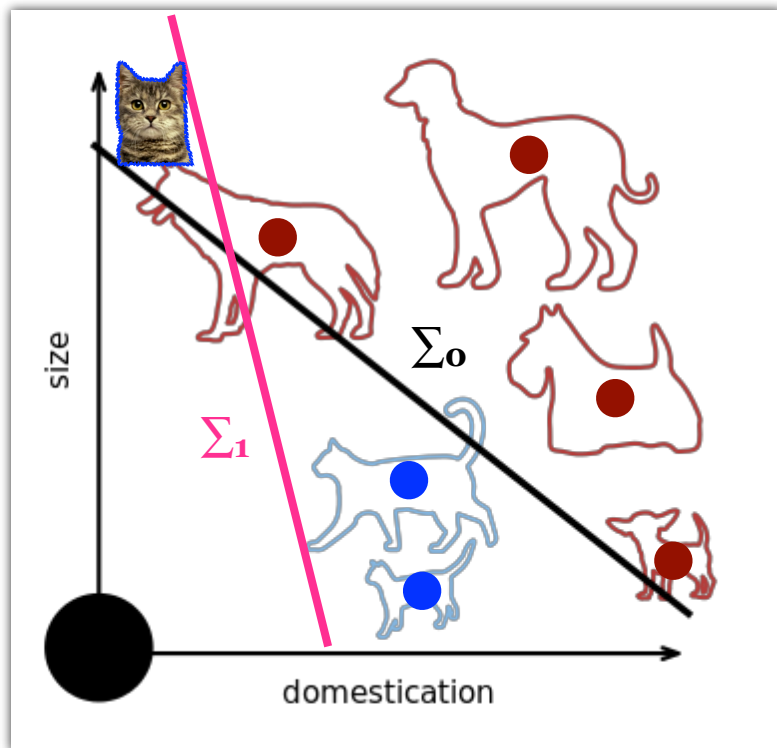
from [wikipedia](https://en.wikipedia.org/wiki/Perceptron)



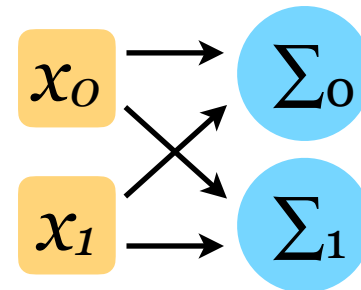
Machine Learning Overview

Simple neural network (perceptron)

What if we have a new data point?



from [wikipedia](https://en.wikipedia.org/wiki/Perceptron)

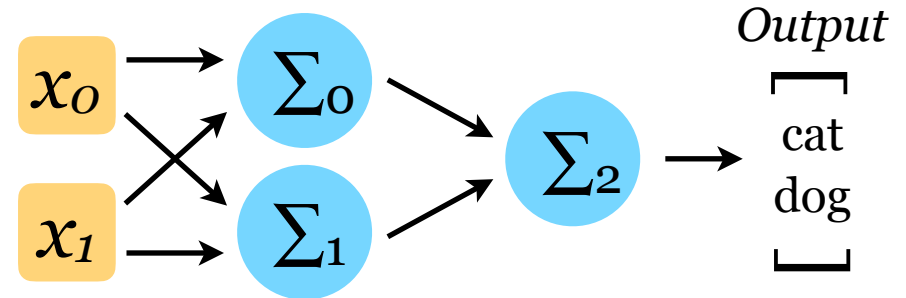
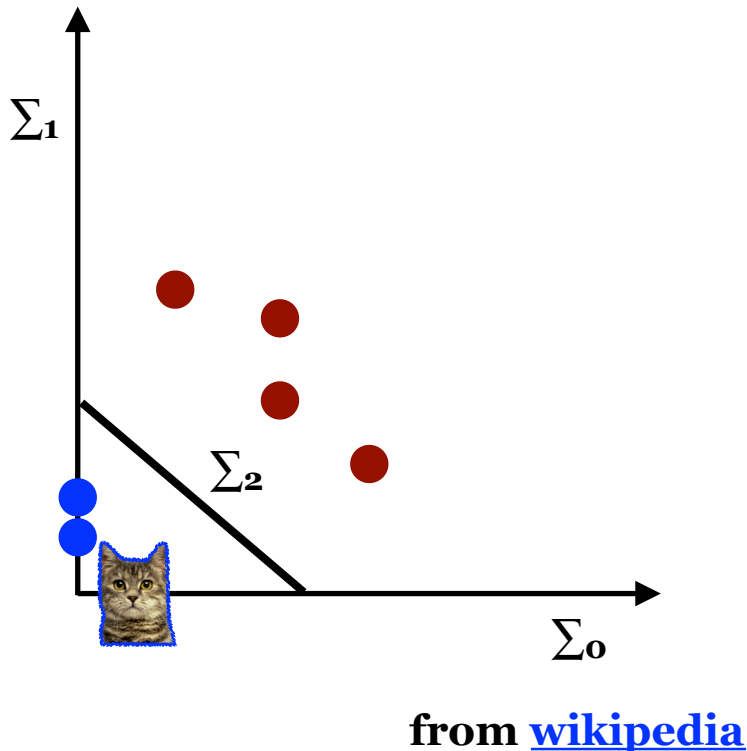


We can **add another perceptron** to help (but does not yet solve the problem)

Machine Learning Overview

Simple neural network (perceptron)

What if we have a new data point?



Another layer can classify based on preceding layer's output (of non-linear activation)

Machine Learning Overview

Back to analyzing a cat “image...”

SLAC



Goal: Dog or Cat



1D array of discriminants

How?

This part can be done with a classic (fully-connected) neural network

How can we extract “features” from “image”?

... the hard part ...

(where I have failed for long)

Machine Learning Overview

Back to analyzing a cat “image...”

SLAC



Goal: Dog or Cat



1D array of discriminants

How?

This part can be done with a classic (fully-connected) neural network

How can we extract “features” from “image”?

Convolutional Neural Network

Machine Learning Overview

Convolutional Neural Network (CNN)



convolutional filter (**kernel**)

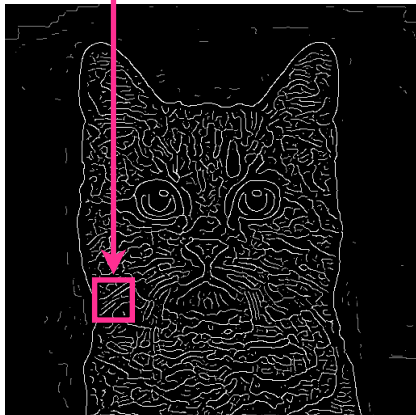
0	1	0
0	2	0
0	1	0

“weights”

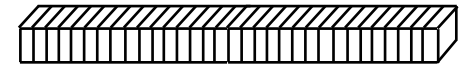


“neuron sum”

$$f_{i,j}(X) = \sigma(W_i \cdot X_j + b_i),$$



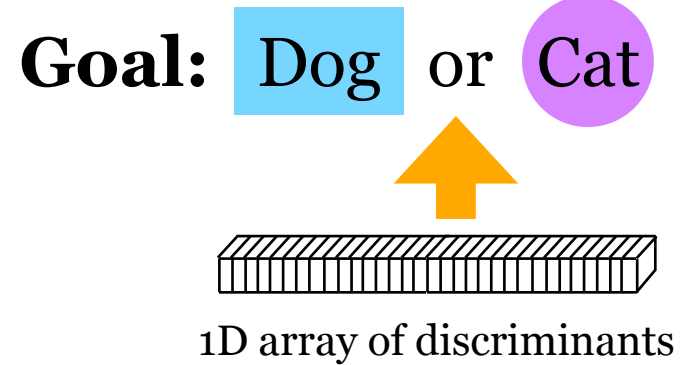
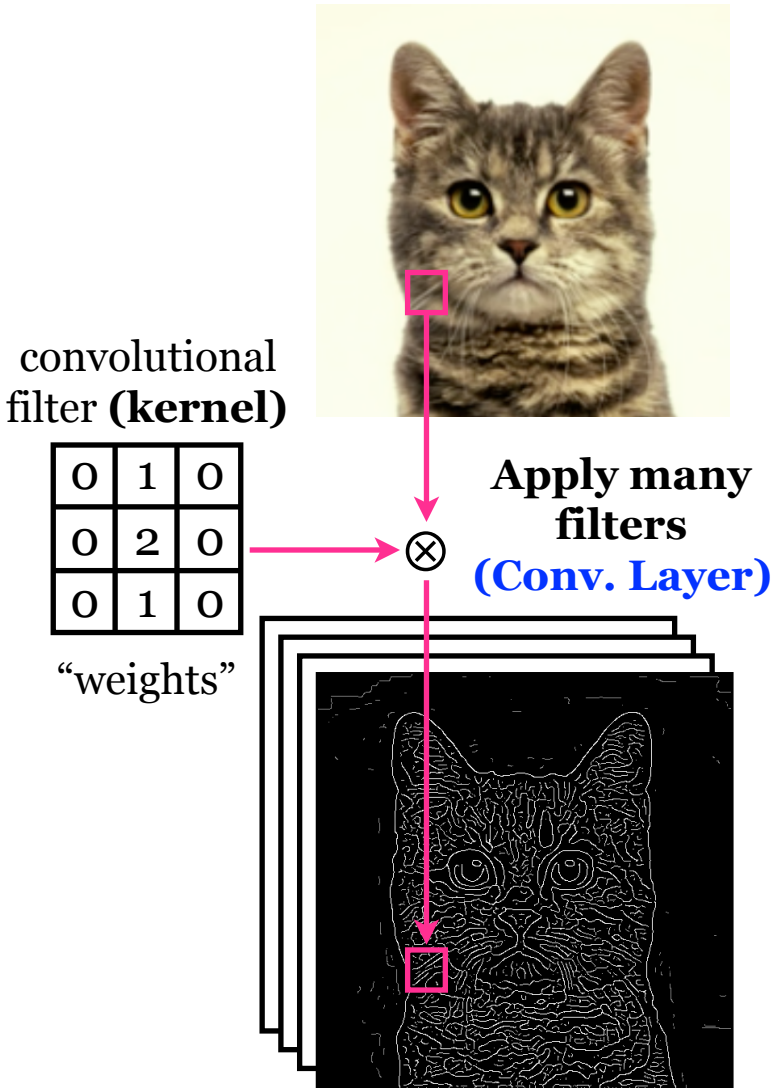
Goal: Dog or Cat



1D array of discriminants

Machine Learning Overview

Convolutional Neural Network (CNN)



Machine Learning Overview

Convolutional Neural Network (CNN)

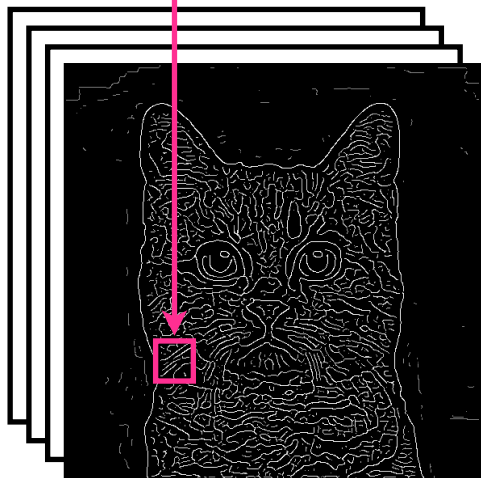


convolutional filter (**kernel**)

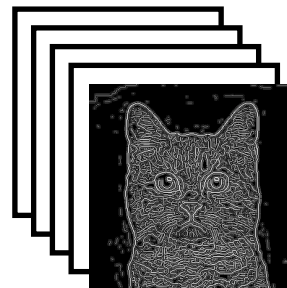
0	1	0
0	2	0
0	1	0

“weights”

Apply many filters
(Conv. Layer)



Down sample




Goal: Dog or Cat



1D array of discriminants

e.g.) Max Pooling

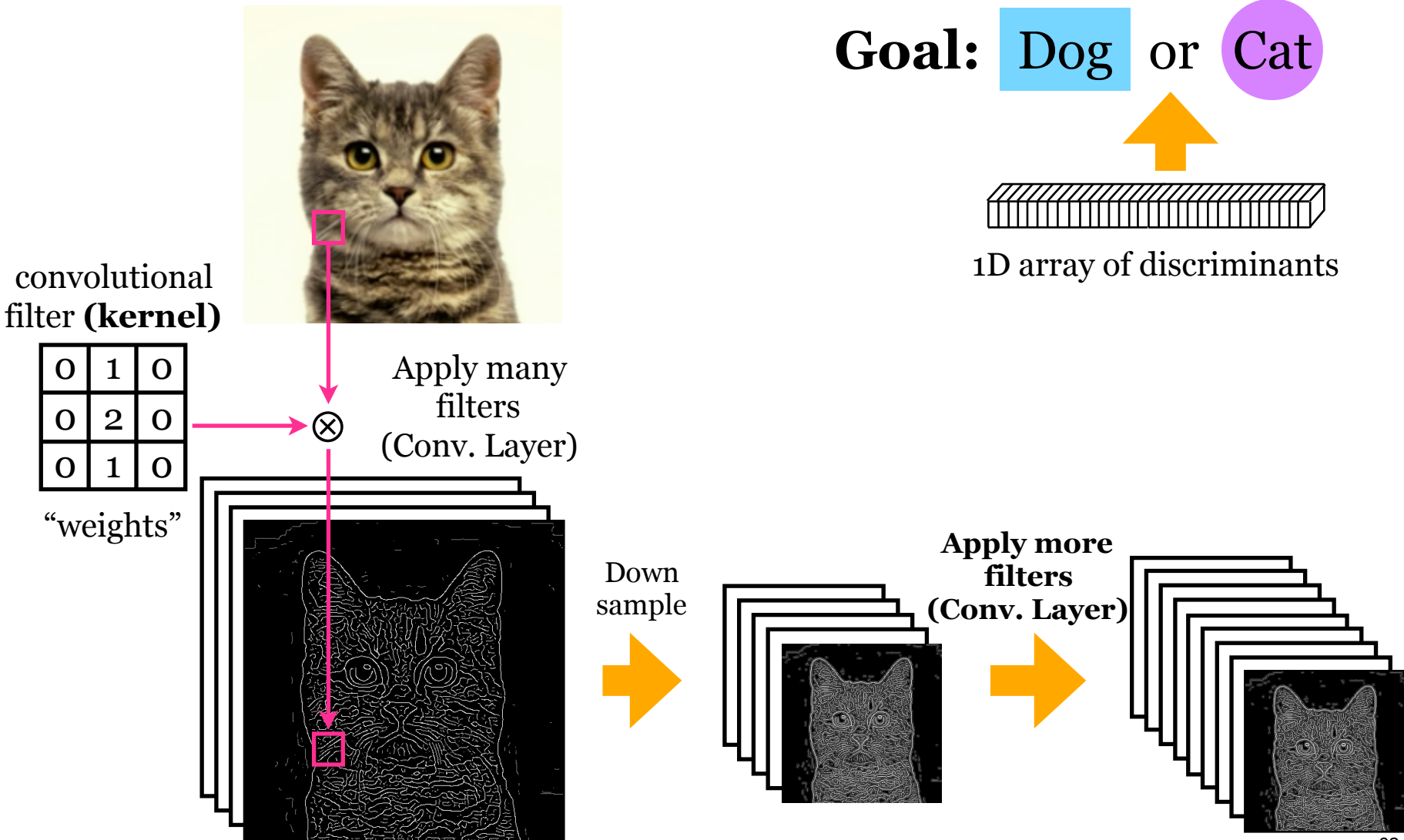
1	1	2	4
5	6	7	8
3	2	1	0
1	2	3	4



6	8
3	4

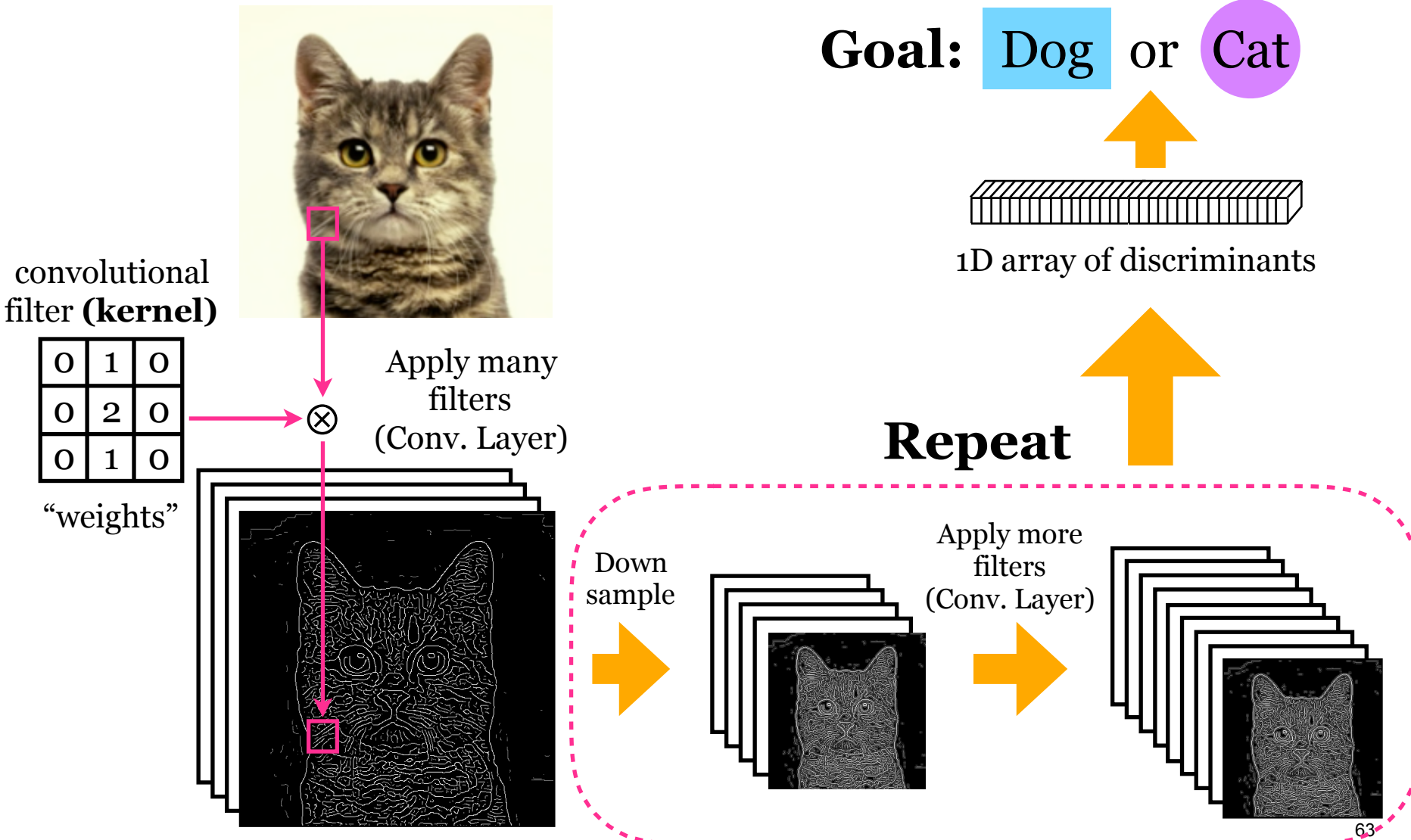
Machine Learning Overview

Convolutional Neural Network (CNN)



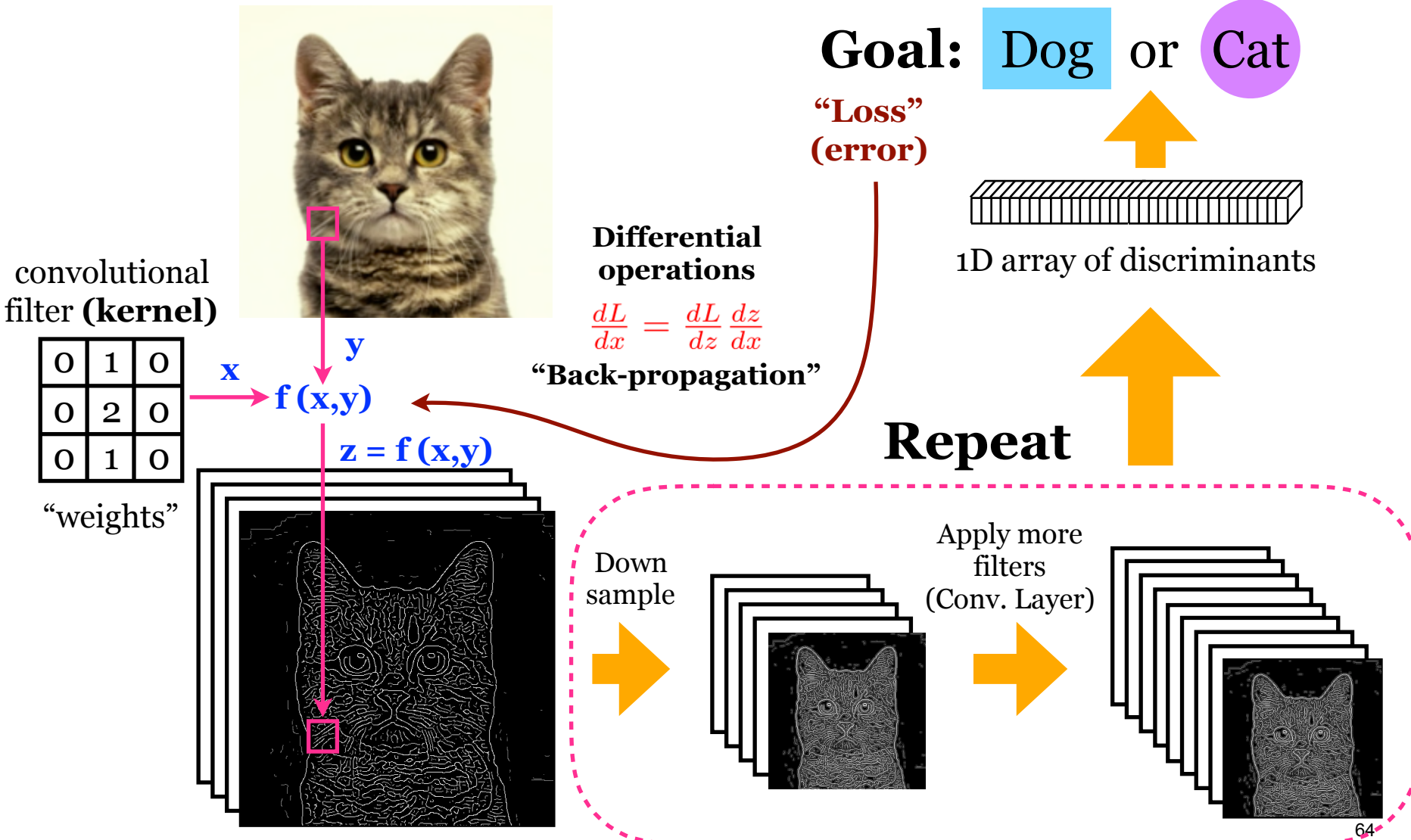
Machine Learning Overview

Convolutional Neural Network (CNN)



Machine Learning Overview

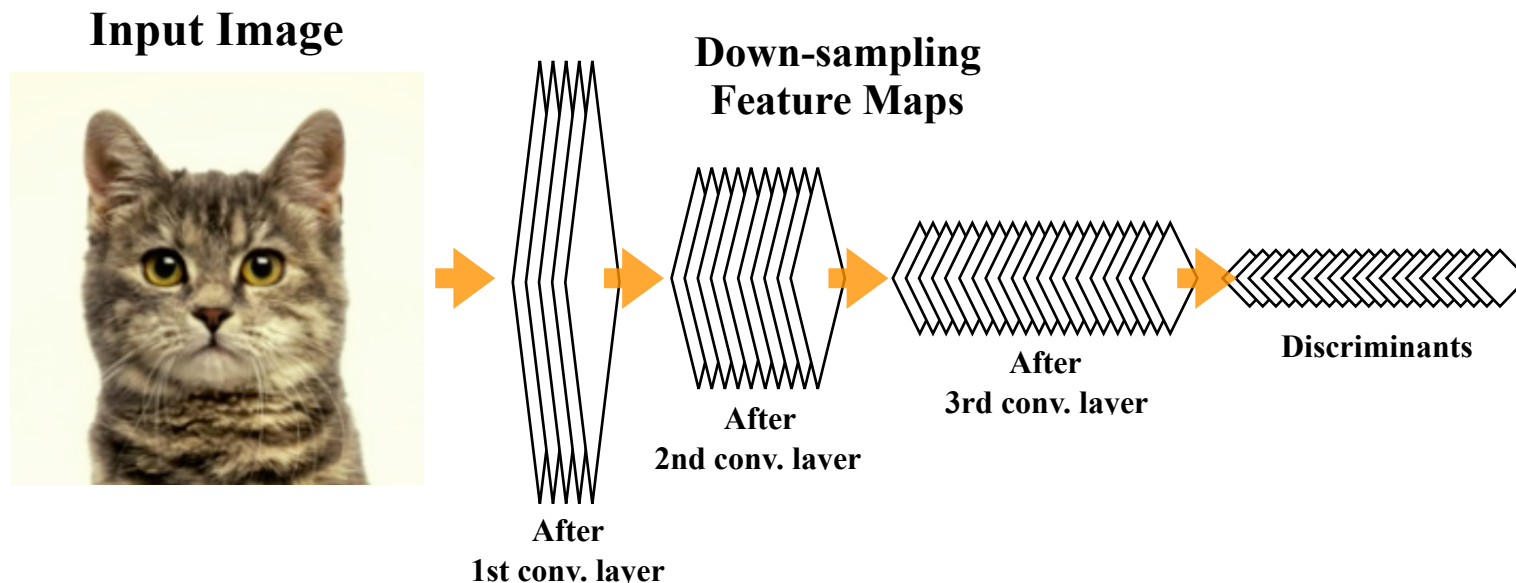
Supervised Training of CNN



Machine Learning Overview

Summarizing CNNs

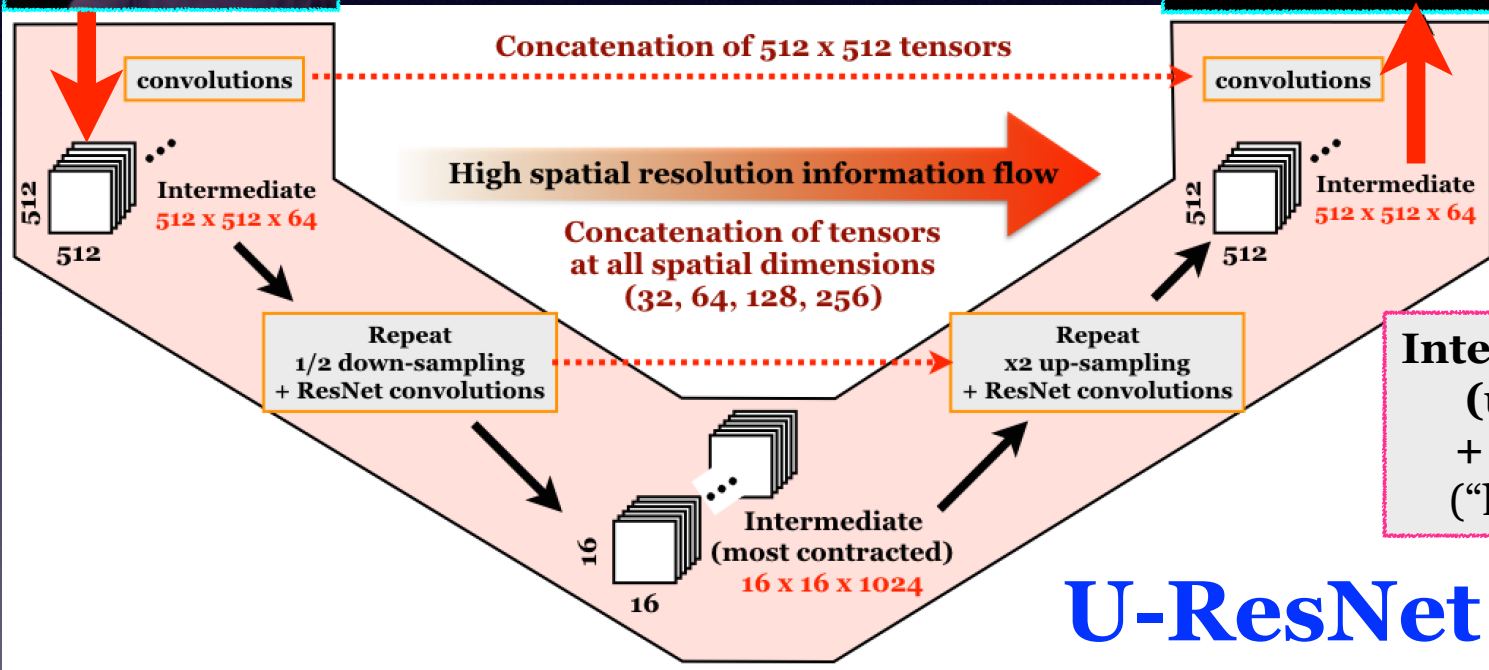
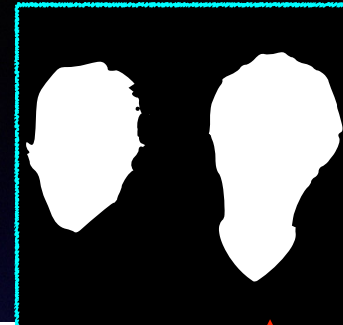
- **CNNs are “feature extraction machine”**
 - Consists of “convolution layers” with “kernels”
 - A chain of linear algebra operations = “massively parallel”
 - ▶ Suited for acceleration using many-core hardwares (e.g. GPUs)
- **CNN: data \Leftrightarrow distribution “Mapping”** (transformation)



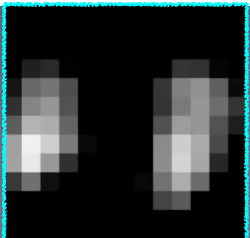
DNN for LArTPC Data Reconstruction



How does U-ResNet Work?



U-ResNet



Down sampling + Convolutions to identify highly abstract features (e.g. "human face")

Validation with real data

Benchmarking SSNet w/ Real Data

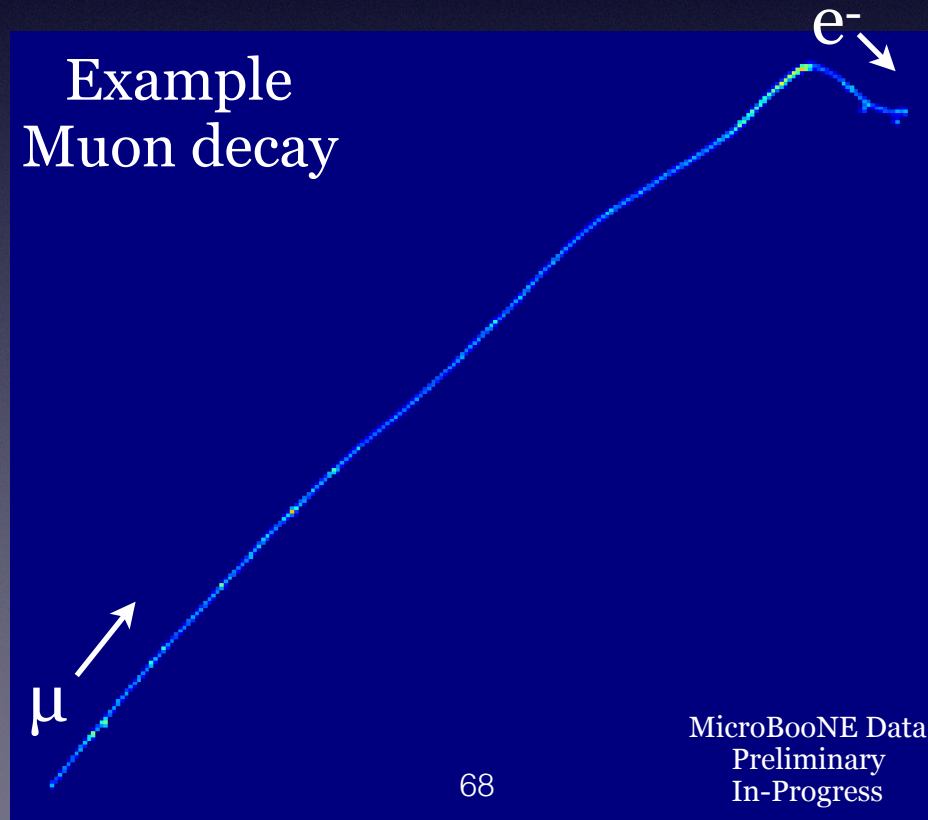
Samples (100 images per sample per sim/data)

A cosmic ray muon decay

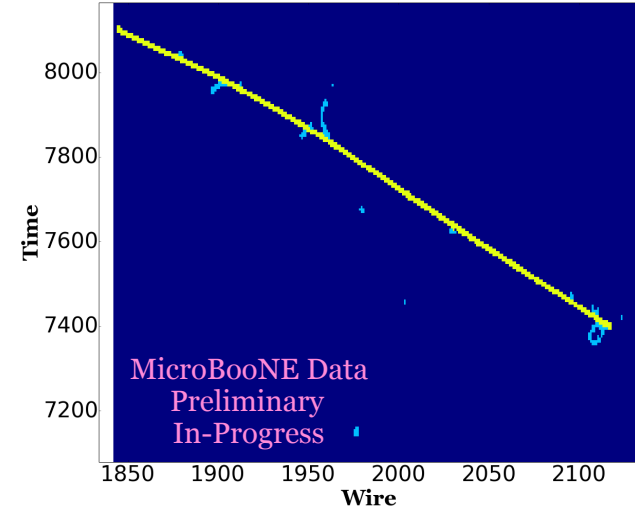
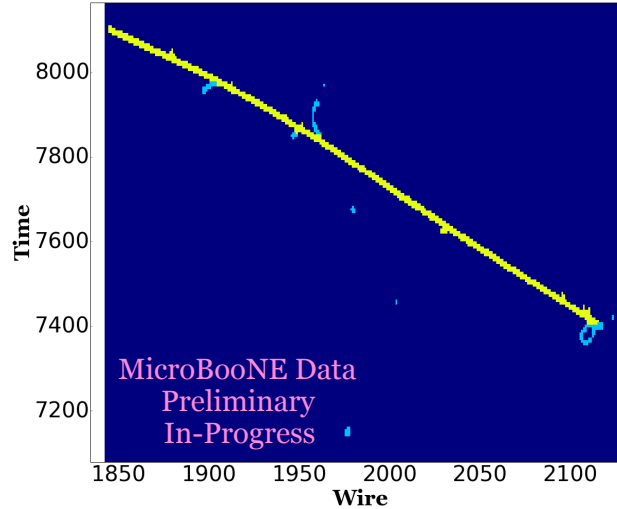
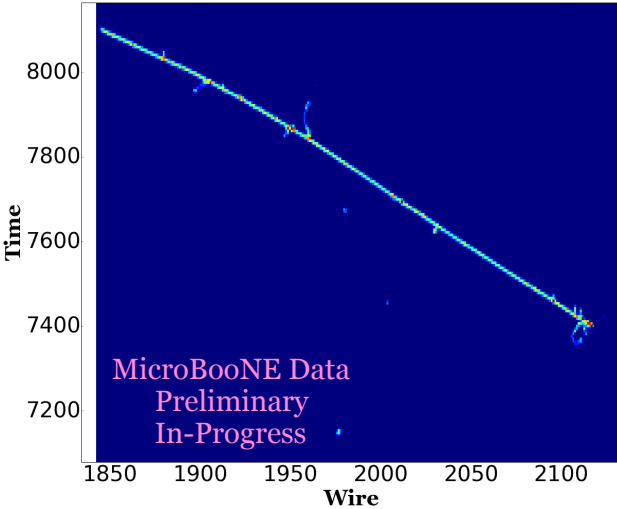
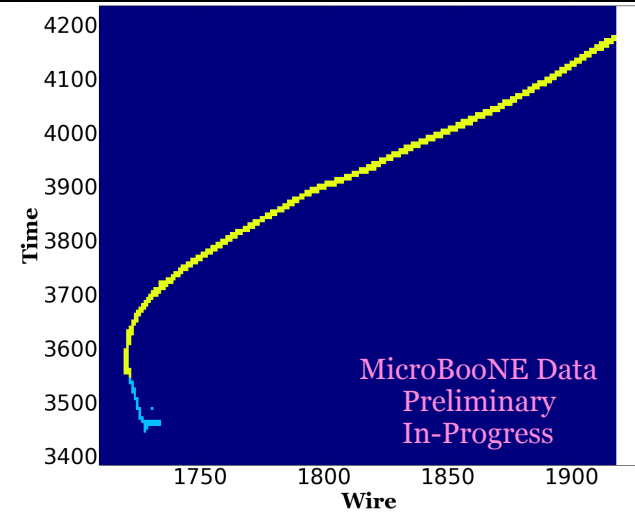
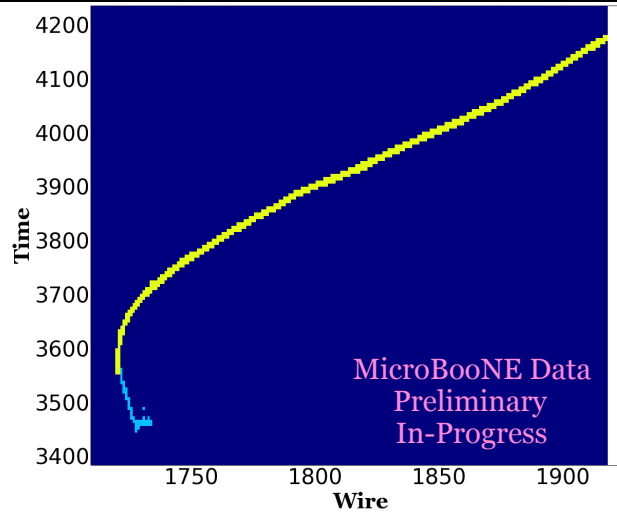
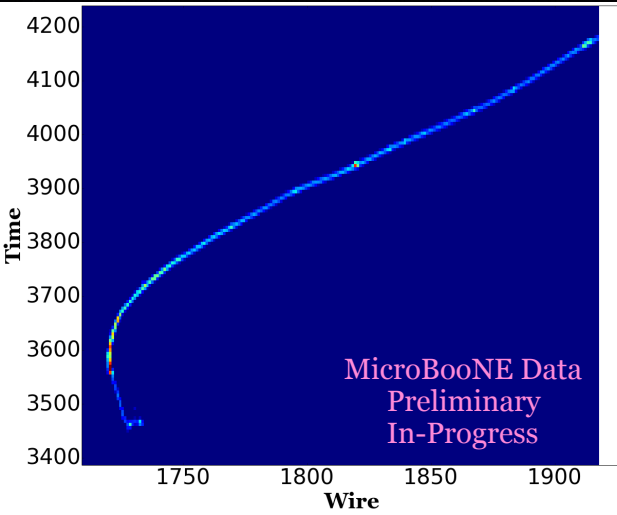
- Involves both “track” and “shower”, simple and intuitive.

Neutrino interactions

- More complicated: varying particle types and multiplicity



Decay Muons: Example Displays

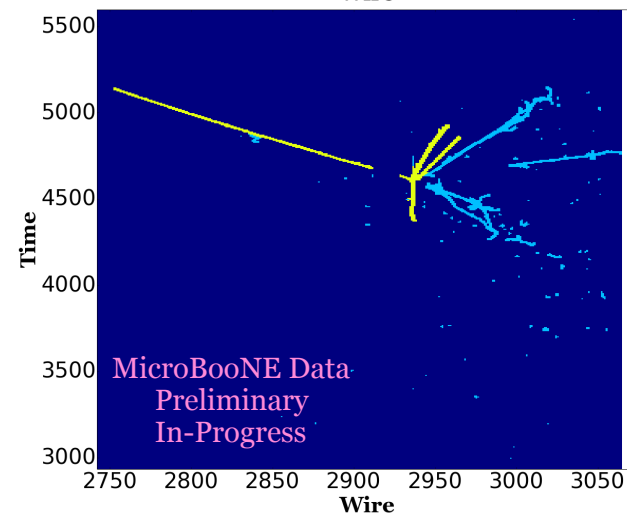
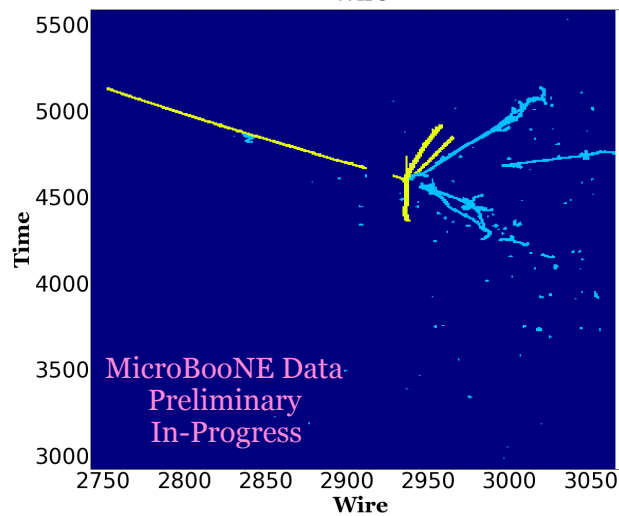
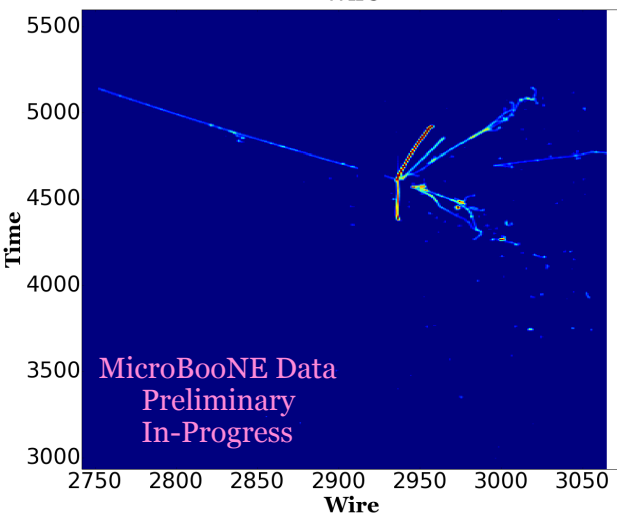
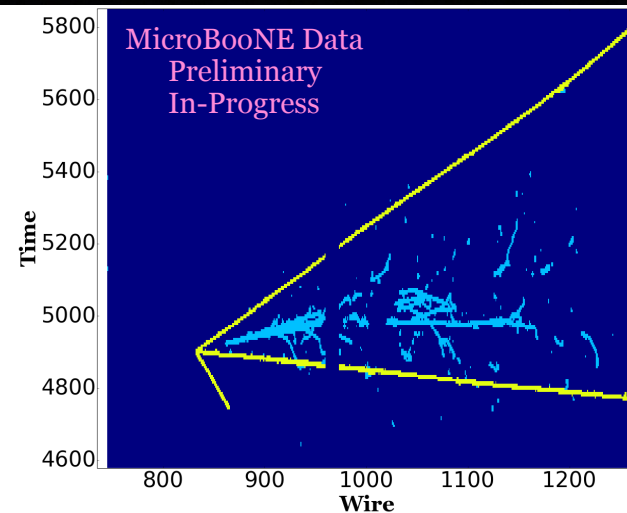
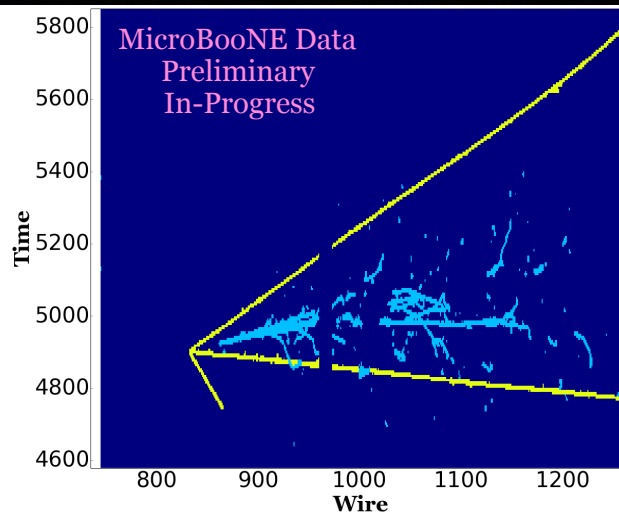
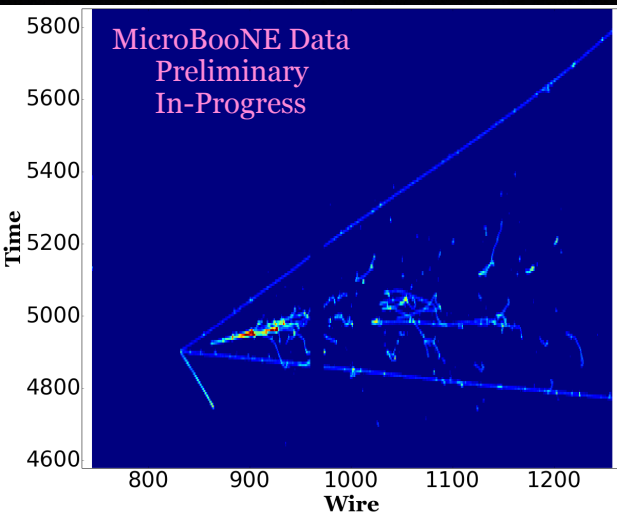


Input Image

Human Label

SSNet Label

4 Visually Picked “Busy Neutrino Events”



Input Image

Human Label

SSNet Label

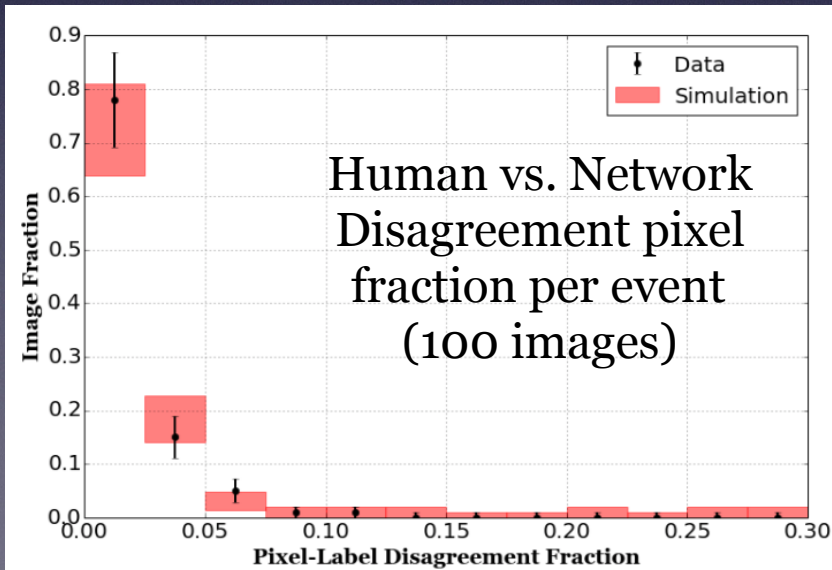
Overall Performance

- **Data/Simulation agreement within statistical error**
 - No systematic error included
- **Network does better than a human analyzer (sim.)**

Muon Decay

Disagreement rate mean/std in %

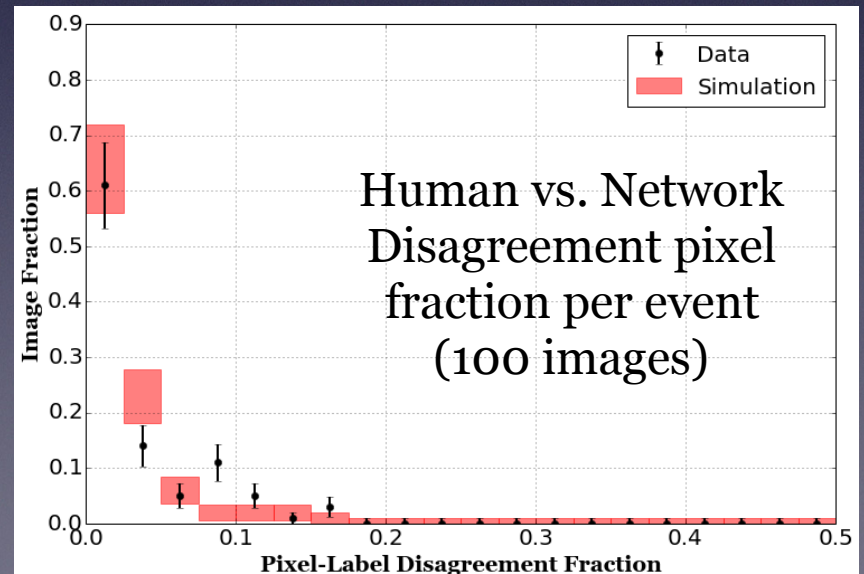
Sample	Data	Simulation	Simulation	Simulation
Label	Physicist	Physicist	Simulation	Simulation
Prediction	U-Resnet	U-ResNet	U-ResNet	Physicist
ICPF mean	1.8	2.6	2.5	2.3
ICPF 90%	3.3	4.4	4.5	3.1
Shower	6.2	5.7	4.0	3.9
Track	1.1	1.9	1.6	1.3



Neutrino w/ Gamma

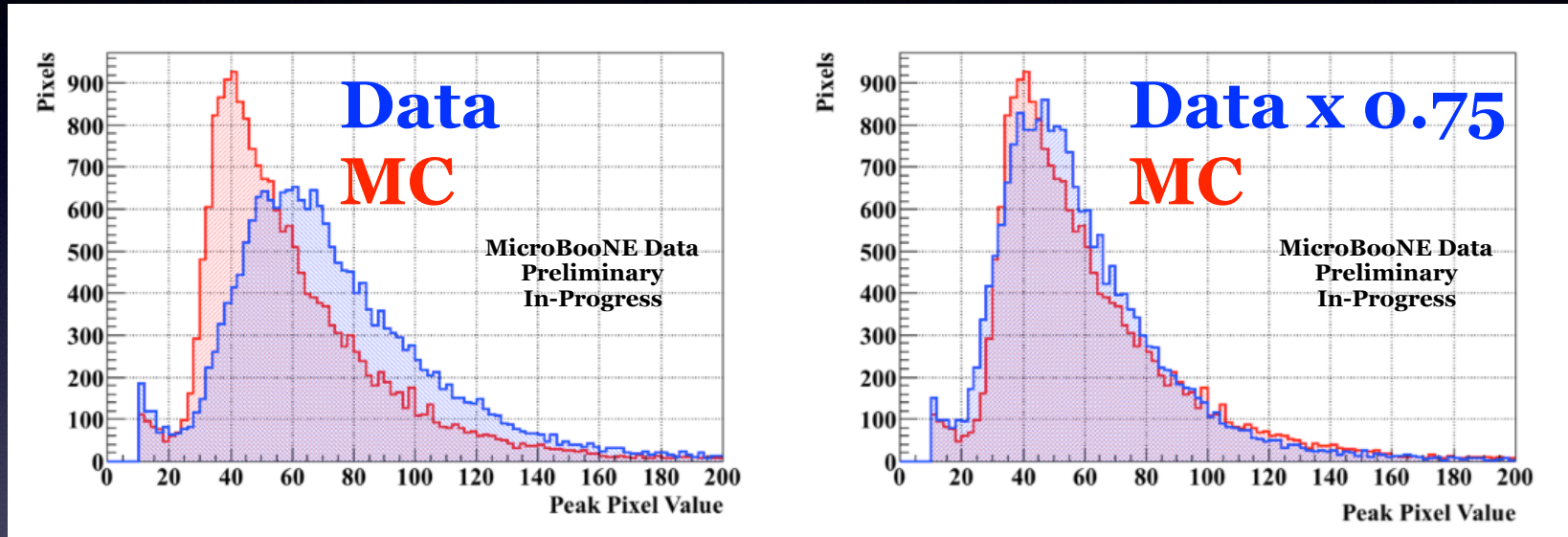
Disagreement rate mean/std in %

Sample	Data	Simulation	Simulation	Simulation
Label	Physicist	Physicist	Simulation	Simulation
Prediction	U-Resnet	U-ResNet	U-ResNet	Physicist
ICPF mean	3.4	2.5	1.8	2.0
ICPF 90%	9.0	5.7	4.6	4.8
Shower	4.8	3.4	3.0	2.6
Track	2.7	2.4	2.2	2.9



Decay Muons: Pixel Value Variation

Studied how network performance varies when pixel values are scaled by a constant factor



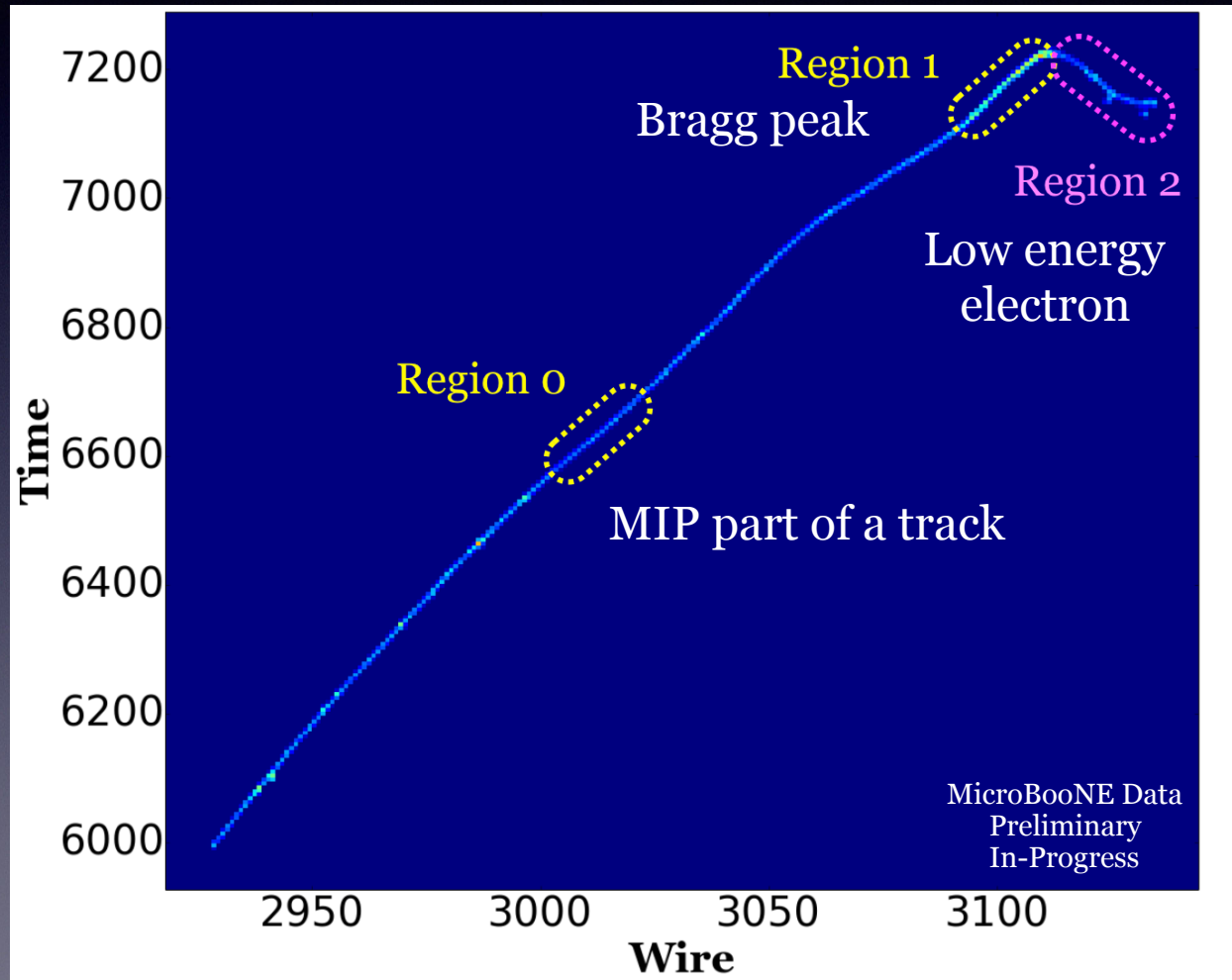
No scaling

Scaling Factor	0.75	0.80	0.85	0.90	0.95	1.00	1.05	1.10	1.15	1.20	1.25
Track	2.38	2.11	1.93	1.65	1.40	1.14	1.16	1.20	1.26	1.28	1.32
Shower	5.24	5.22	5.41	6.02	6.11	6.16	6.11	6.14	6.21	6.28	6.34
Combined	2.75	2.53	2.40	2.21	2.02	1.81	1.85	1.89	1.96	2.00	2.04

Change in the mean error rate is within 1% when pixel values are scaled within 20%, fairly robust

Decay Muons: Inter-Pixel Correlation

Study, qualitatively, how network reacts to interesting portions of an image

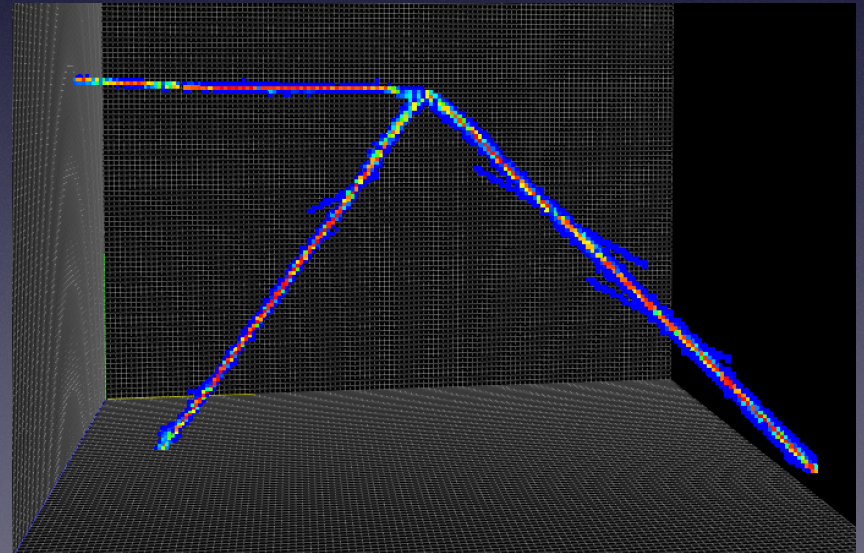
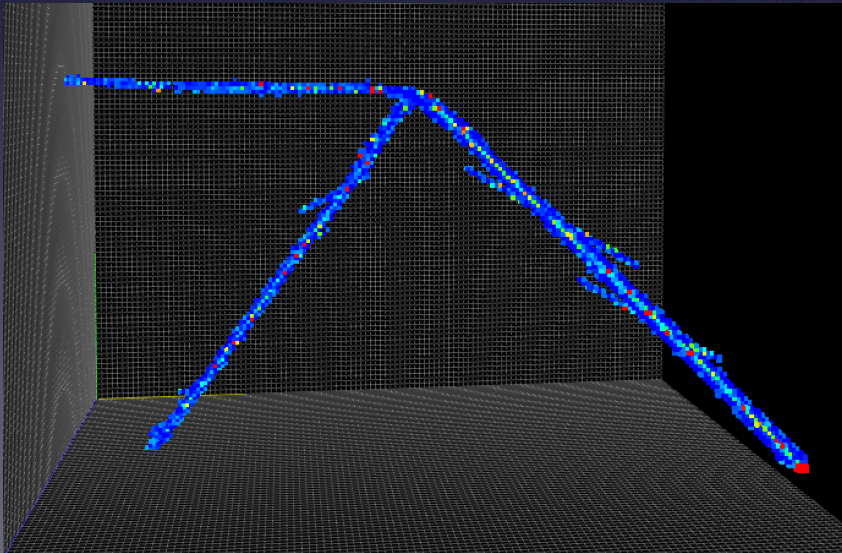


3D Data Reconstruction @ SLAC



Tracy Usher

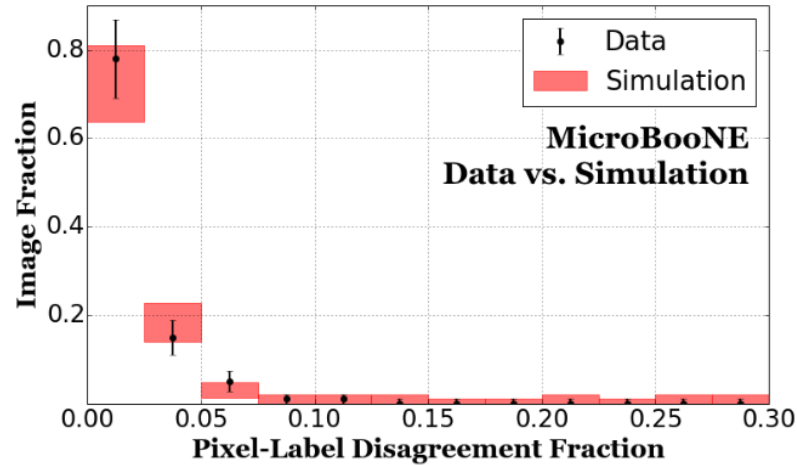
- Showing ML can be started above age of 60



Tracy shows you can start ML above age of 60

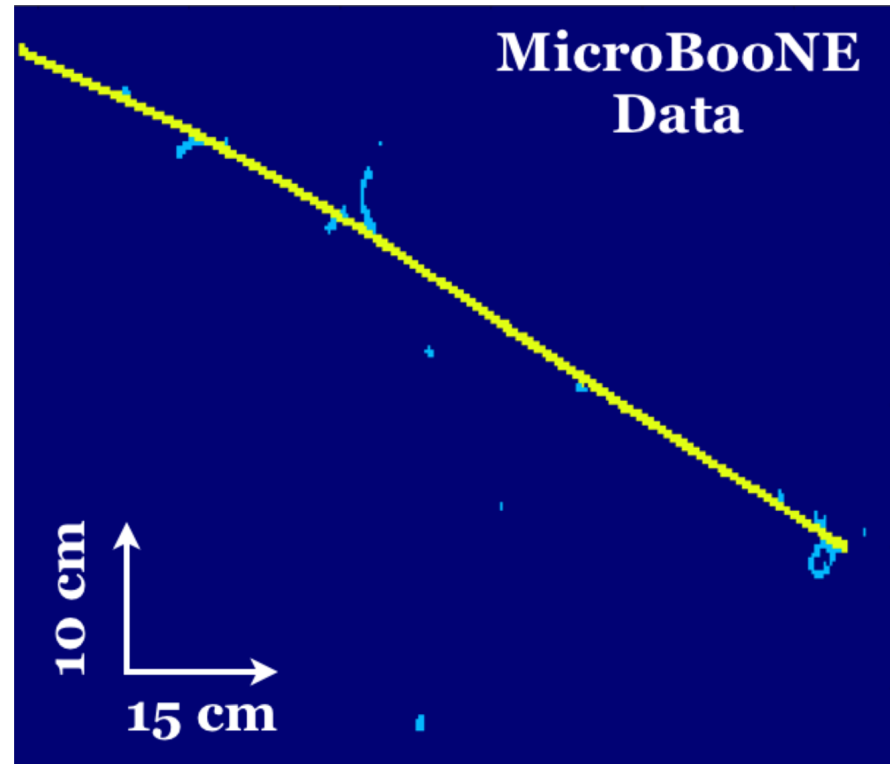
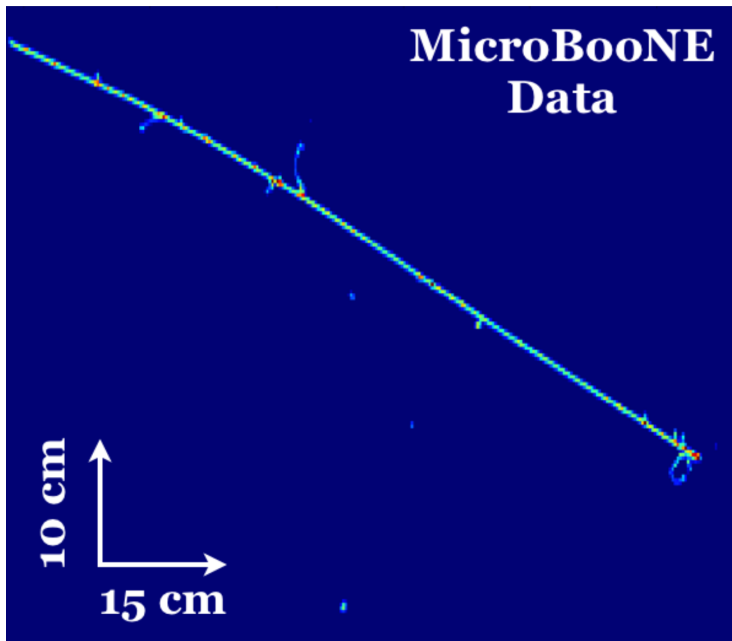
Progress Report

Machine Learning & Data Reconstruction



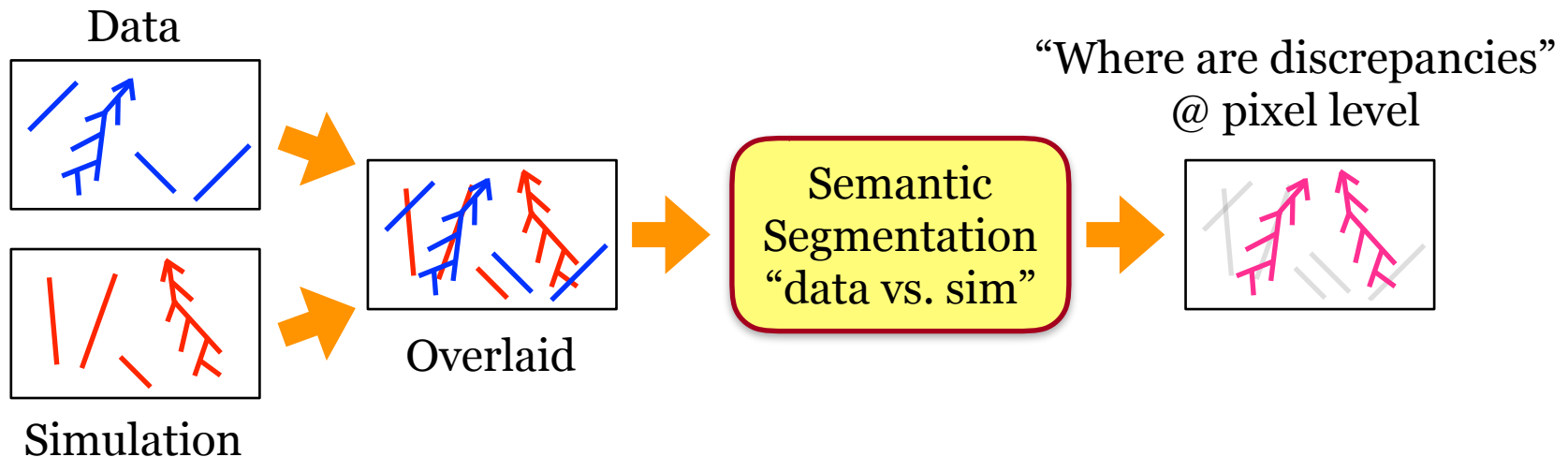
Technique Validation on Data

- Same paper ... [arXiv:1808.07269](https://arxiv.org/abs/1808.07269)
 - Important for new techniques such as this
- Compared physicist vs. network predictions



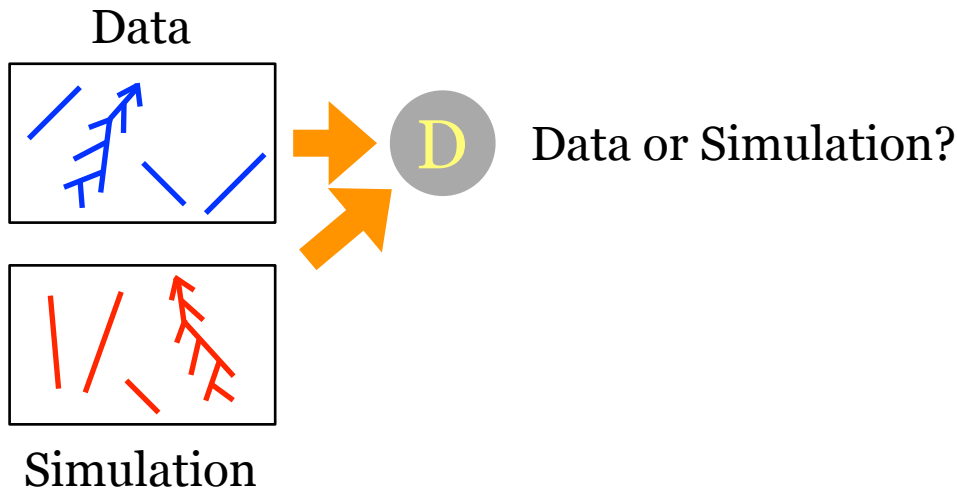
What can we do about imperfect simulation?

- **Problematic**: the “signal distribution” learnt by the algorithm may be different in two domains!
- **Mitigation techniques** in ML domain?
 - **Can** try CNN to “locate” where it is



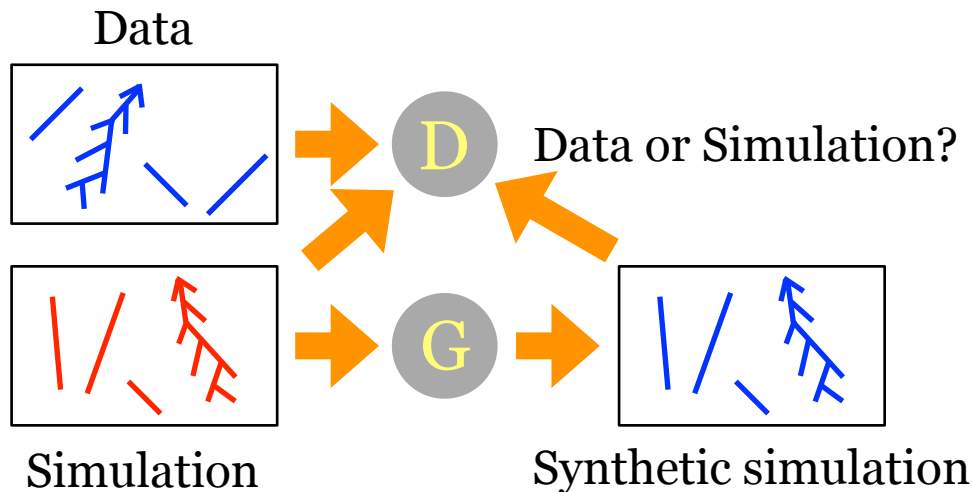
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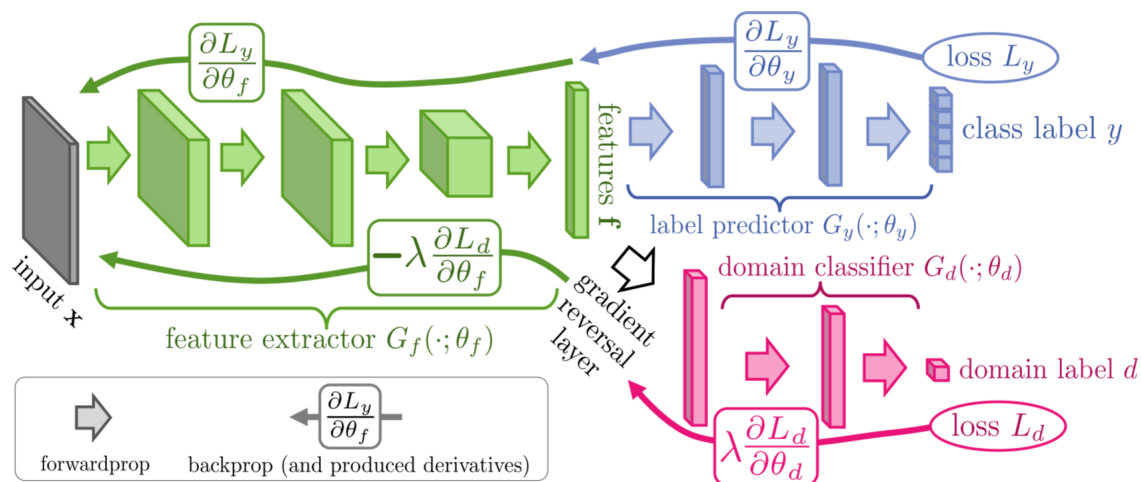


Generative Adversarial Network

Can learn the “mapping” between the data and simulation “distributions”. The generator network can be used as a synthetic image generator to train different neural networks

What can we do about imperfect simulation?

- **Problematic**: the “signal distribution” learnt by the algorithm may be different in two domains!
- **Mitigation techniques** in ML domain?
 - **Can** try CNN to “locate” where it is
 - **Can** try CNN to “fix” the discrepancy
 - **Can** try a training technique to minimize the effect



Maximize the loss for discriminate data vs. simulation, feature extractors are penalized to key on simulation specific information

Minerva Paper [arXiv:1808.08332](https://arxiv.org/abs/1808.08332)

Domain-Adversarial Training of Neural Networks
J. Mach. Learn. Res. 17 (2016)