

# ADC Calibration for LArTPC Electronics

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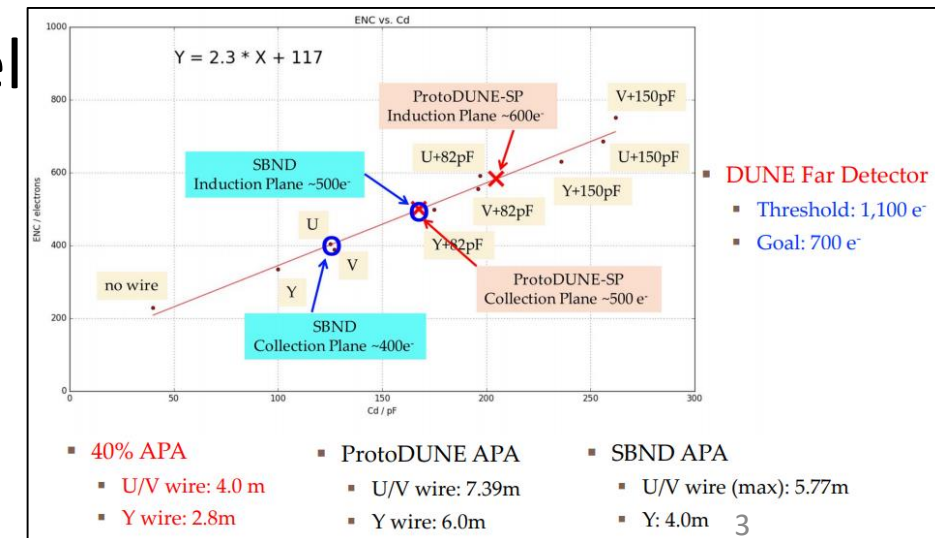
# Outline

- Cold electronics for the LArTPC
- Sticky code mitigation
- ADC nonlinearity (NL) calibration
- Summary

# Cold electronics for the LArTPC era

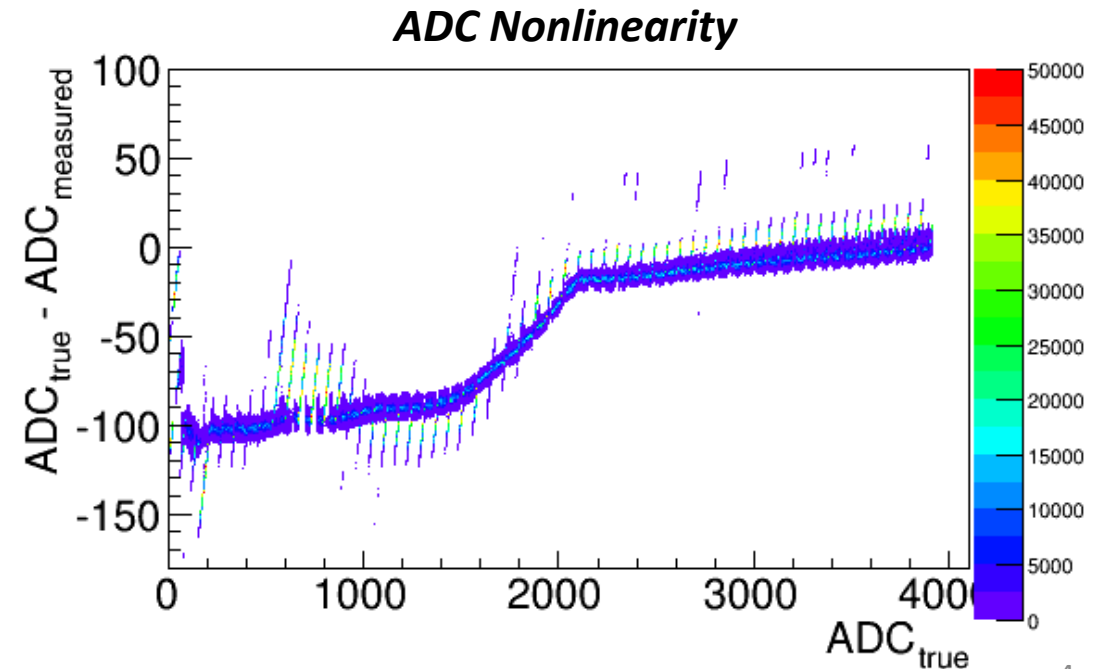
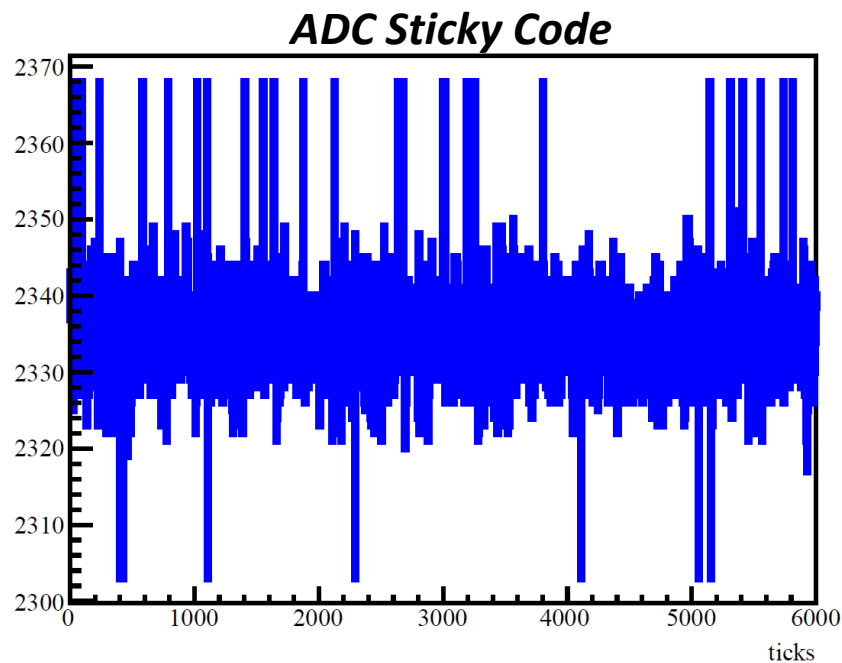
- Cold electronics (CE) is crucial for reducing noise in LArTPC (at  $\sim 89\text{K}$ )
- MicroBooNE first achieved excellent noise performance ( $\text{ENC} \sim 400 e^-$ ) with the preamplifier installed in LAr  $\rightarrow$  5-6 times improvement
- ProtoDUNE-SP has a design of  $600 e^-$  ENC in the induction plane ( $\sim 7.4\text{m}$  wires)
- SBND and DUNE (far) would be at similar level

	Preamp	ADC
MicroBooNE	Cold	Warm
SBND	Cold	Cold (COTS)
ProtoDUNE-SP	Cold	Cold
DUNE Far Detector	Cold	Cold



# Precise ADC determination in protoDUNE

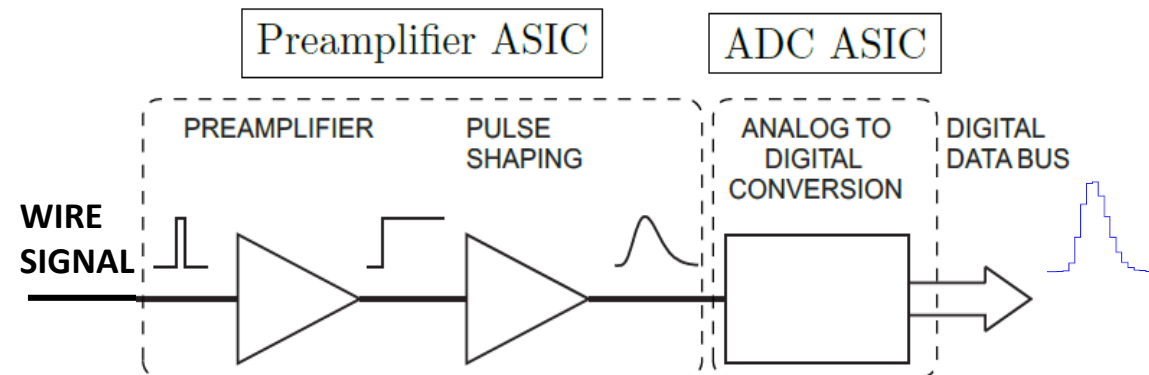
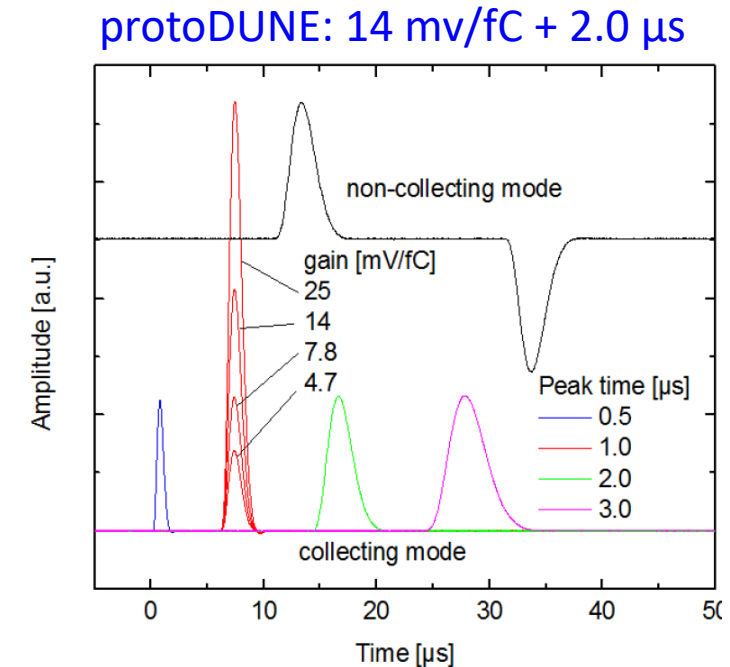
- However, given the cold environment in LAr, two problems occur for the precise determination of ADC



# ProtoDUNE TPC readout electronics

# ProtoDUNE TPC readout electronics

- Cold preamplifier
  - Gain: 4.7, 7.8, 14, or 25 mV/fC
  - Shaping time: 0.5, 1.0, 2.0, or 3.0  $\mu$ s
- Cold ADC (Analog to Digital Converter)
  - 12 bits: 4096 minimum steps in full range (0.2V  $\sim$  1.6V)
  - 2 MHz sampling rate



V. Radeka et al. *Cold electronics for 'Giant' Liquid Argon Time Projection Chambers*,  
*J. Phys. Conf. Ser.* **308** (2011) 012021.

# Readout scheme of ADC circuit

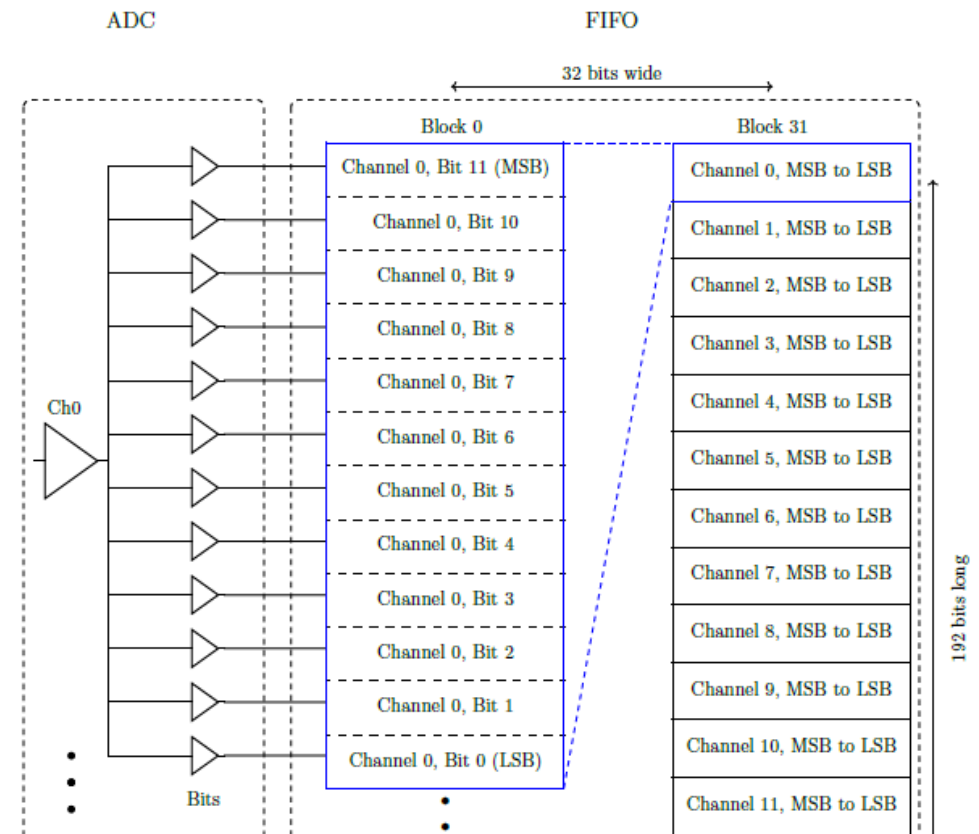
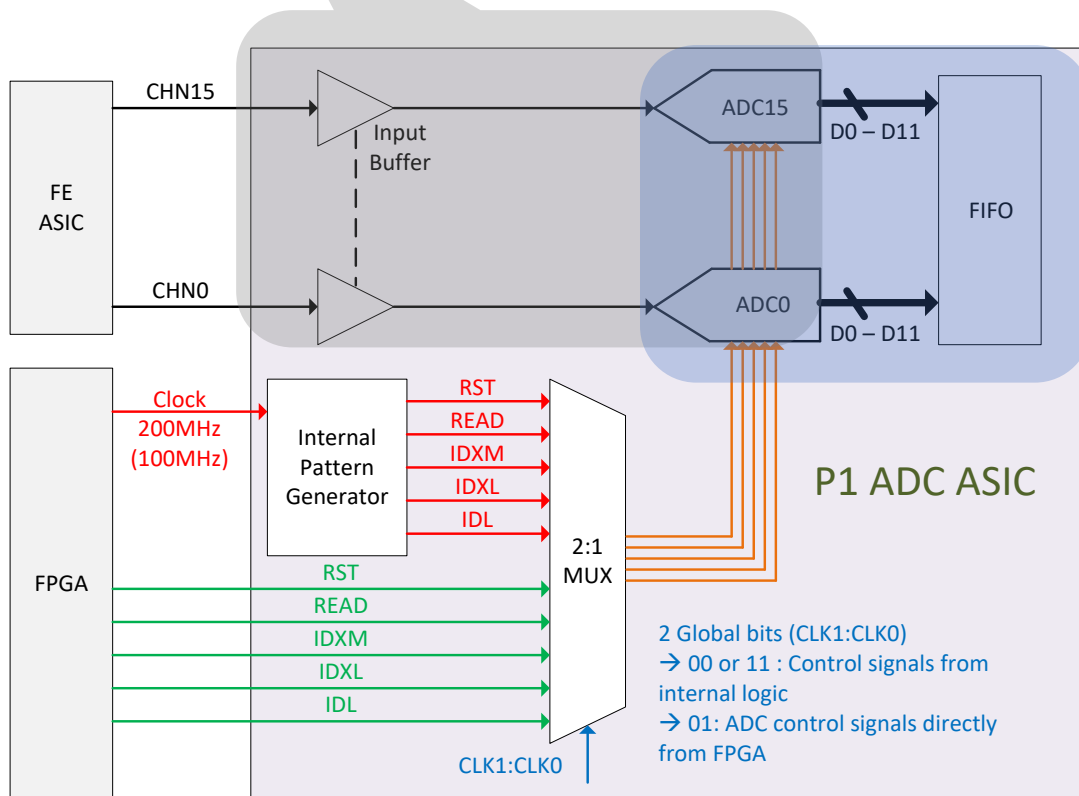
- 16 channels per ADC circuit

- 12 bits per channel **saved** in a FIFO buffer

e.g. 2048 = 100,000,000,000

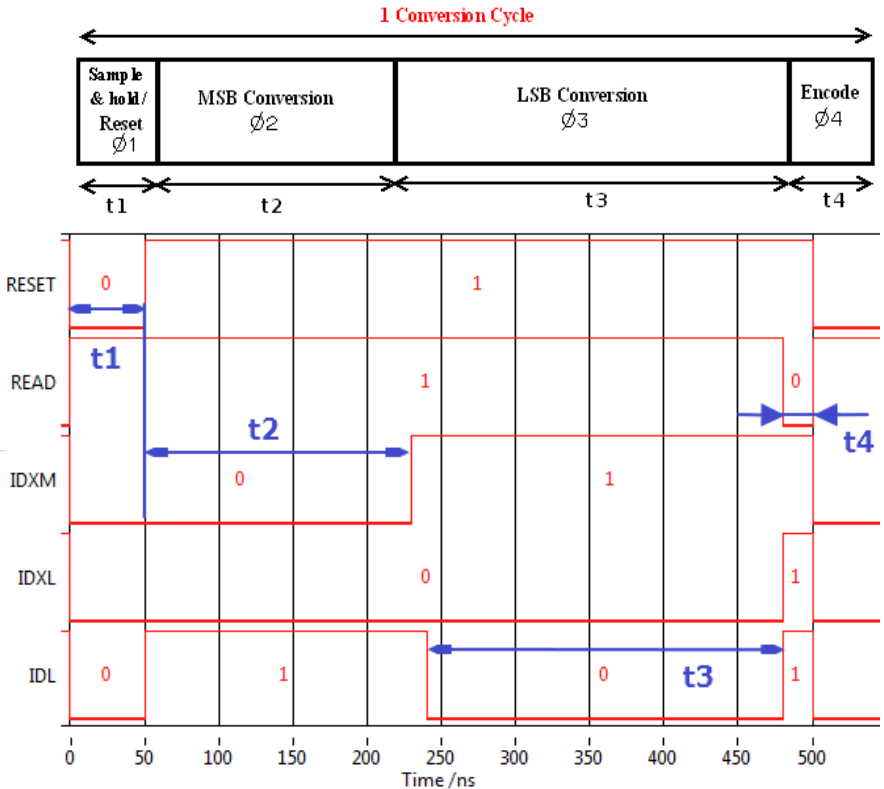
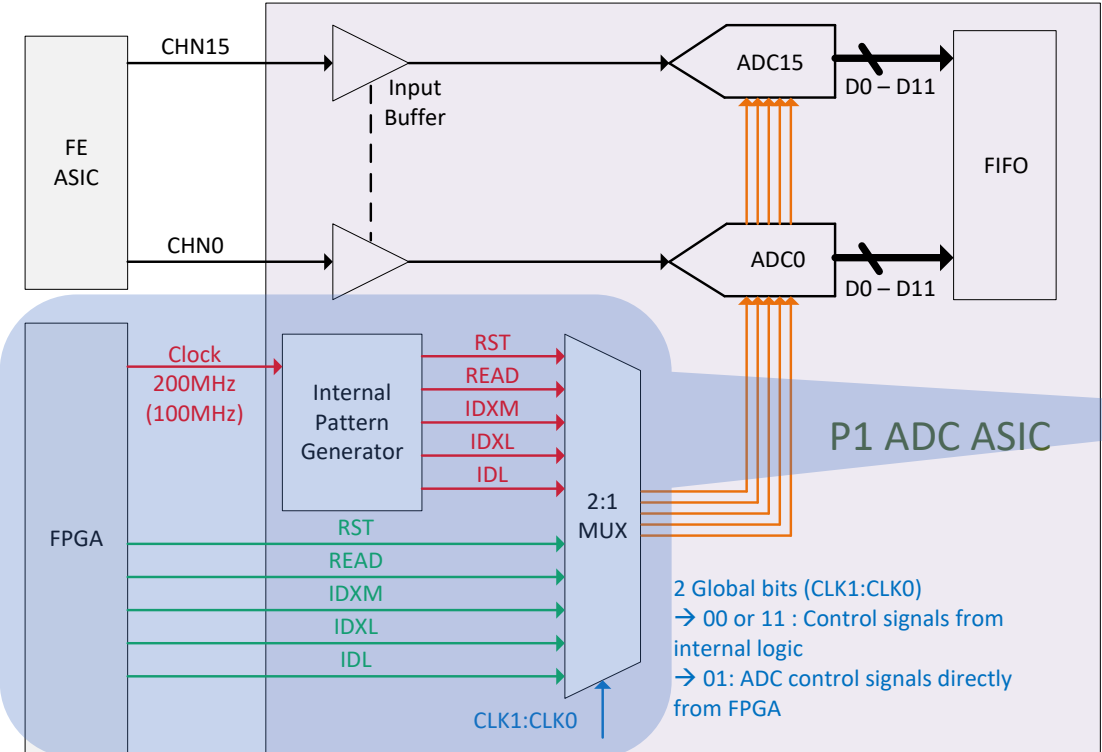
Most significant bits (MSB)

Least significant bits (LSB)



# Readout scheme of ADC circuit

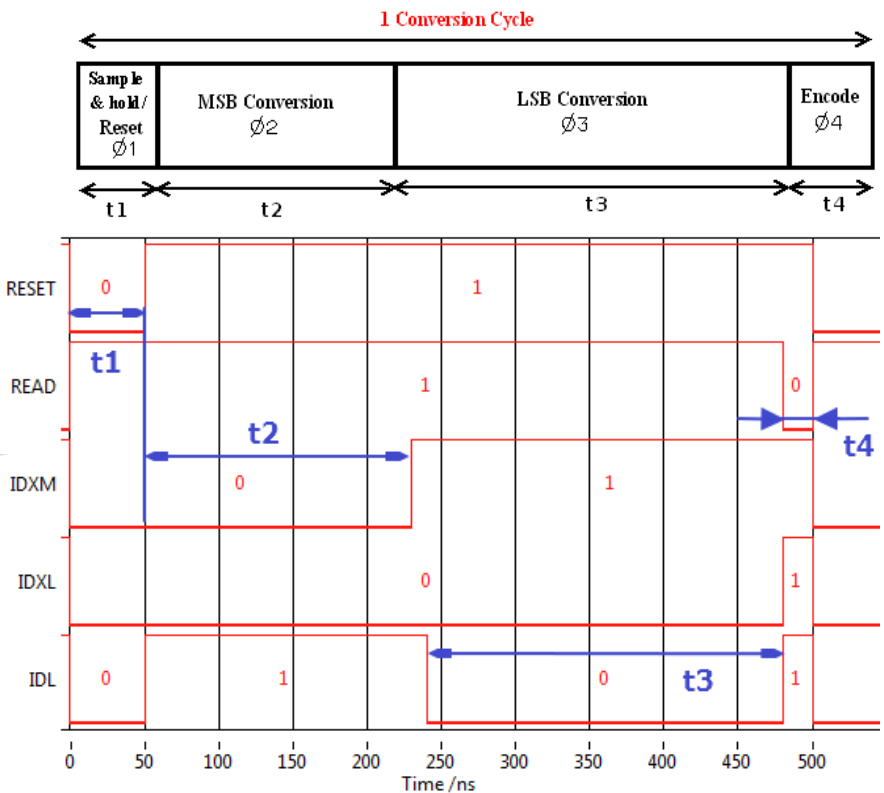
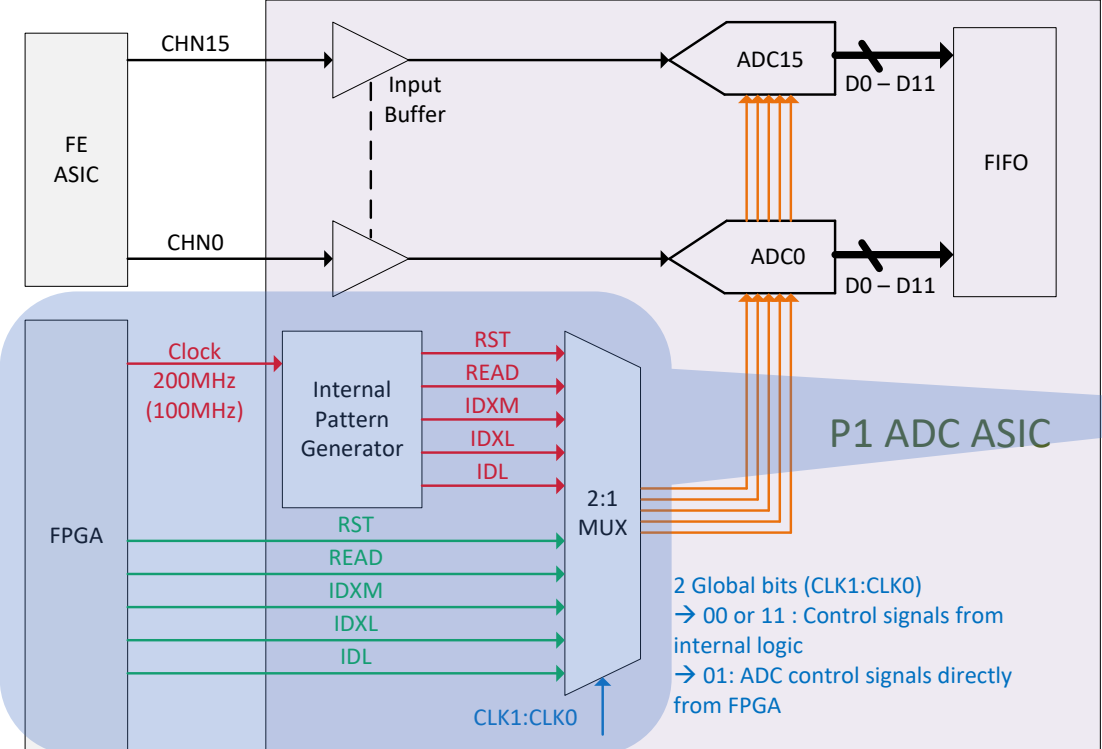
- The read/write logic must be synchronized through five control signals





# Readout scheme of ADC circuit

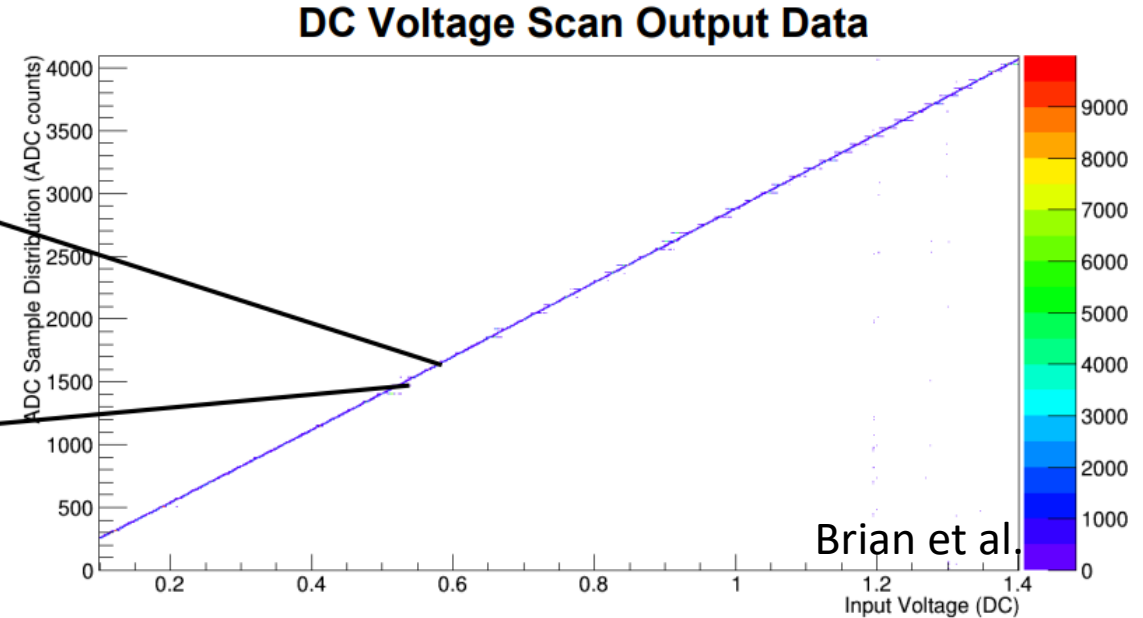
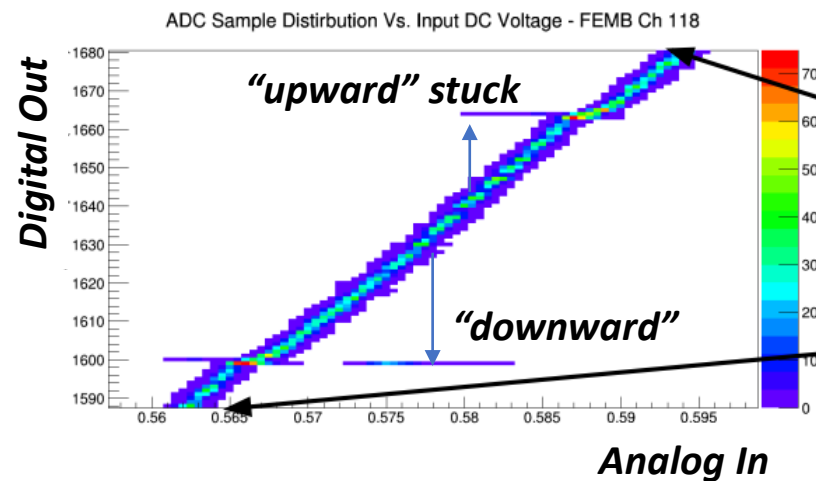
- These five signals can be generated **internally** inside the ADC by a 200 MHz clock (2 MHz digitization) or taken **externally**



# Sticky code mitigation

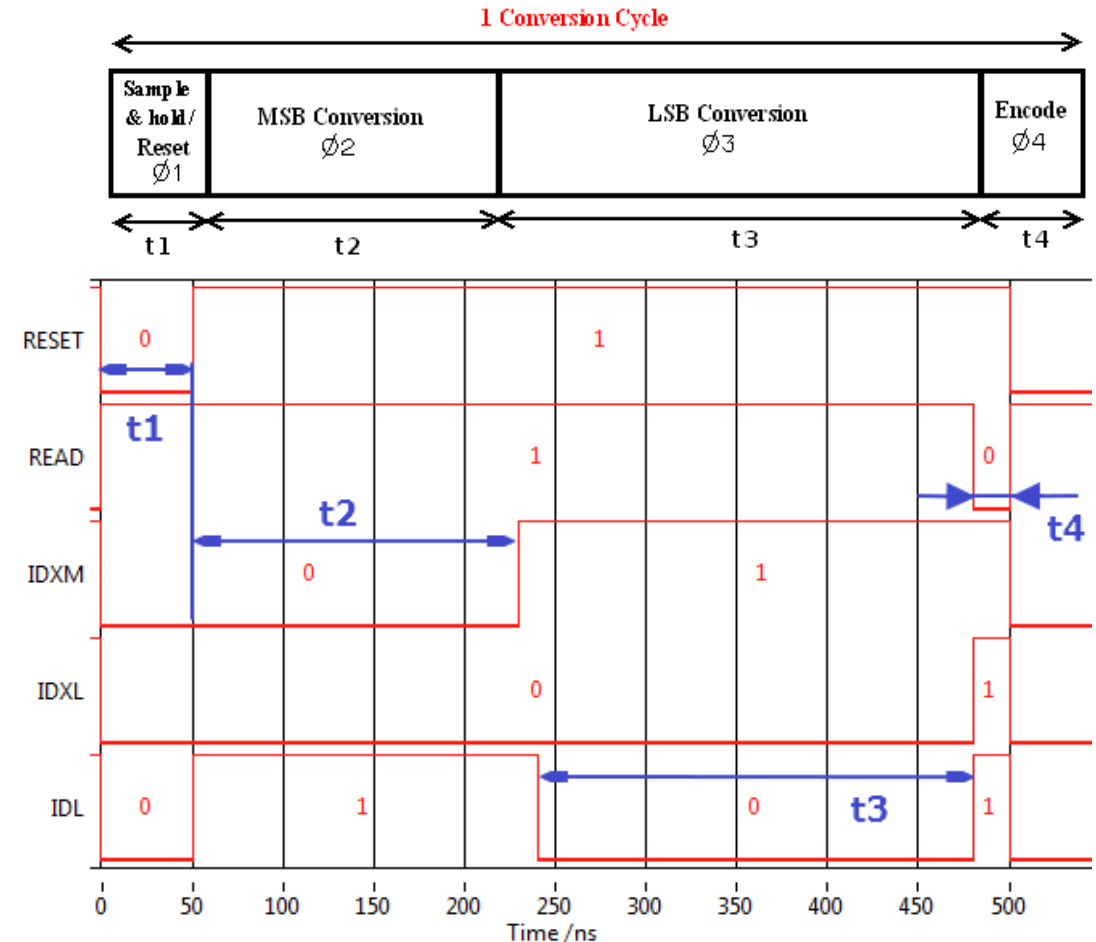
# Sticky Code

- The 6 LSBs in ADC ASIC was found to be “sticky” around 000000 (0x00) or 111111 (0x3F)
- So called sticky code, or stuck bit



# ADC Digitization and Sticky Code

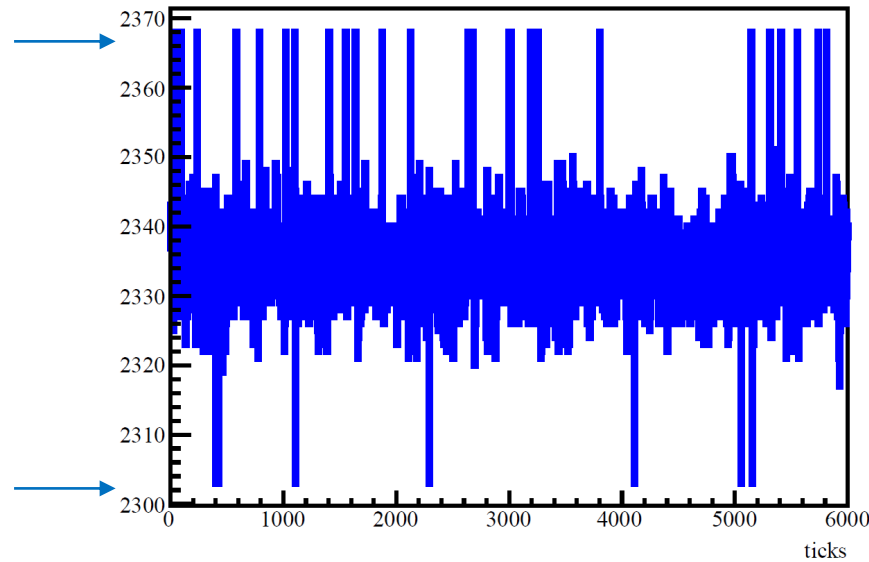
- Two stages of a 12-bit digitization
  - 6 MSBs (most significant bits)
  - 6 LSBs (least significant bits)
- The 6 LSBs are held until the MSBs are converted to binaries
- An **instability** during the **MSB and LSB phases** results in either all LSB codes 0, or all LSB codes 1



# Identification of sticky code

- By taking modulo of 64 (LSBs=111111), 0, 1, 63 usually indicates sticky codes
- A waveform correction will be applied in each “sticky” channel

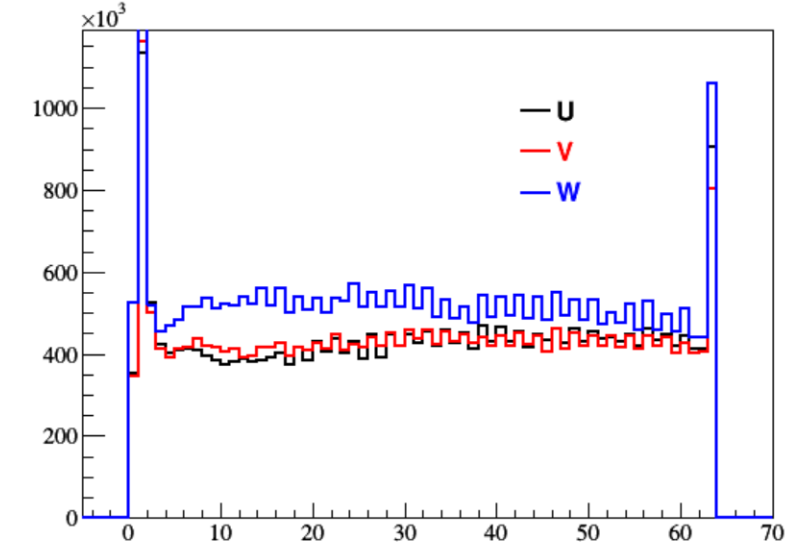
*An example of pedestal waveform*



$$2368 = (100101000000)_2$$

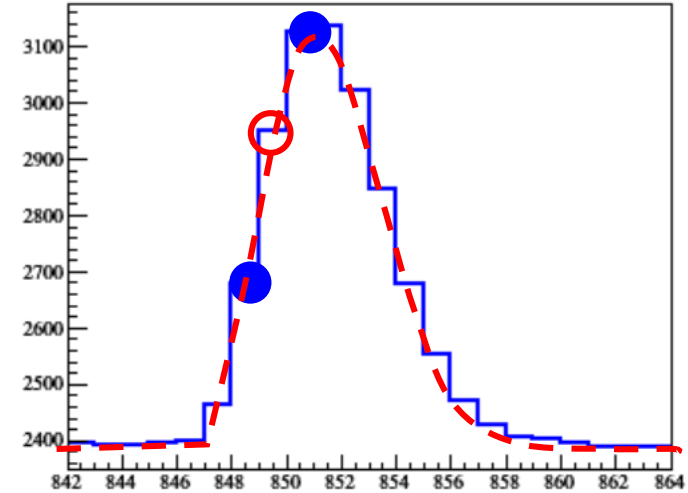
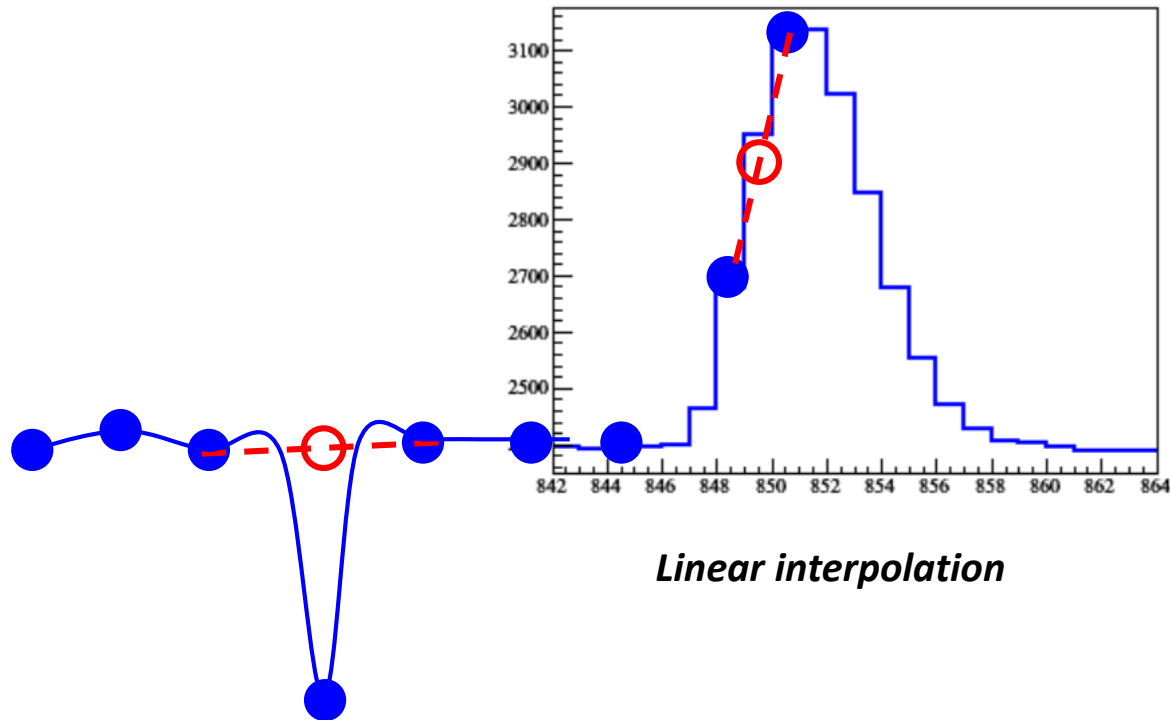
$$2303 = (100011111111)_2$$

ADC % 64



# Sticky Code Mitigation

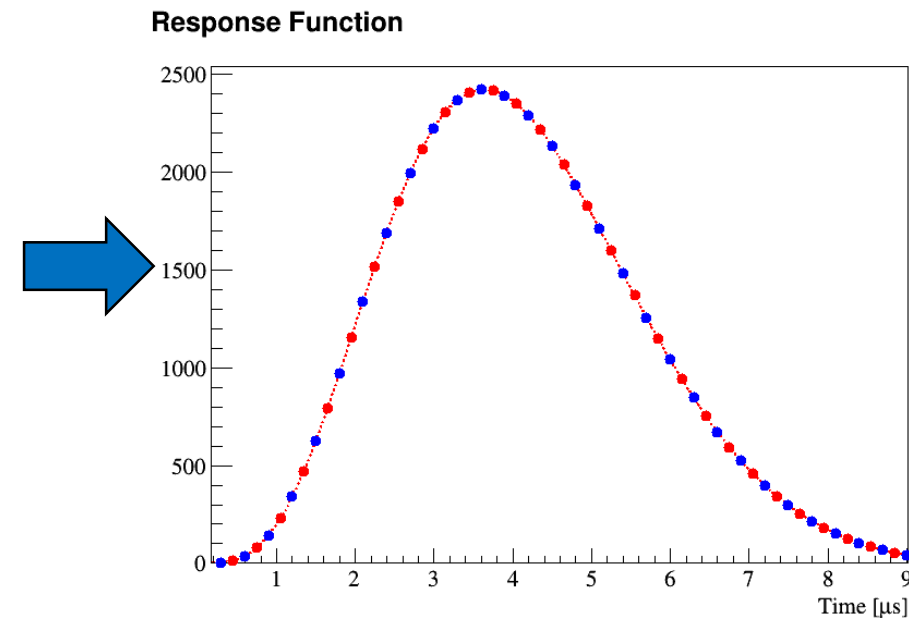
- Linear interpolation between “un-sticky” codes is a good first step
- However, linear interpolation may not be sufficient for signal region
- A correction w.r.t. the electronics response function would be better



# FFT interpolation w.r.t electronics response

- However, some facts makes it difficult for using the response function
  - A few percent channel-to-channel variation in response function
  - Changes due to the cold environment
  - Coupled with ADC nonlinearity (discussed shortly)
- Instead, a **FFT interpolation** is proposed by
  - i) Linear interpolation as a base correction
  - ii) Once a “sticky” code found in an **even-binned** tick, apply phase shift to **odd-binned ticks** to cover **even-binned ticks**, and *vice versa*

FT property	Time domain	Frequency domain
	$f(t)$	$F(\omega)$
Phase shift	$f(t - t_0)$	$F(\omega)e^{-j\omega t_0}$

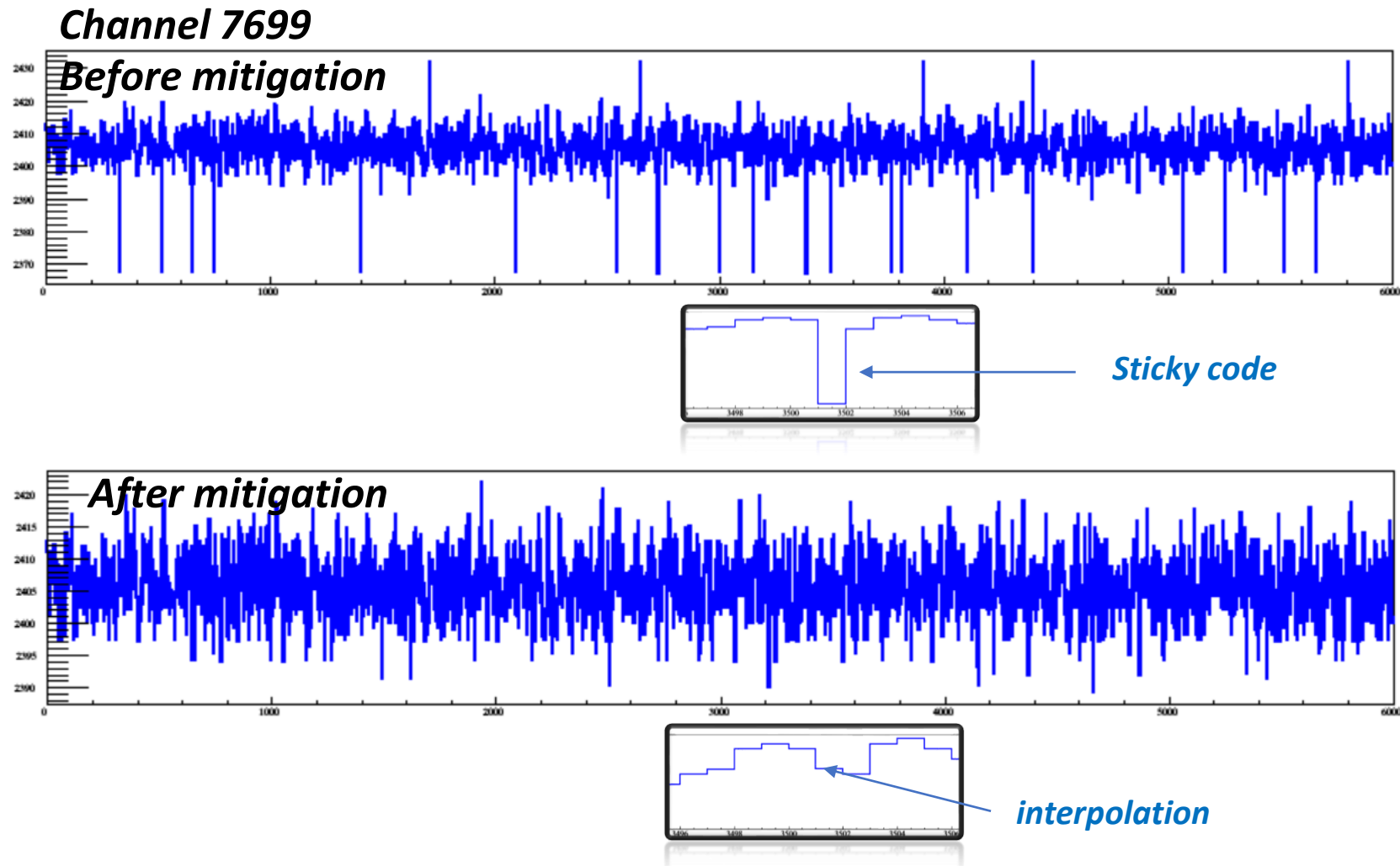


# Advantages of such FT interpolation

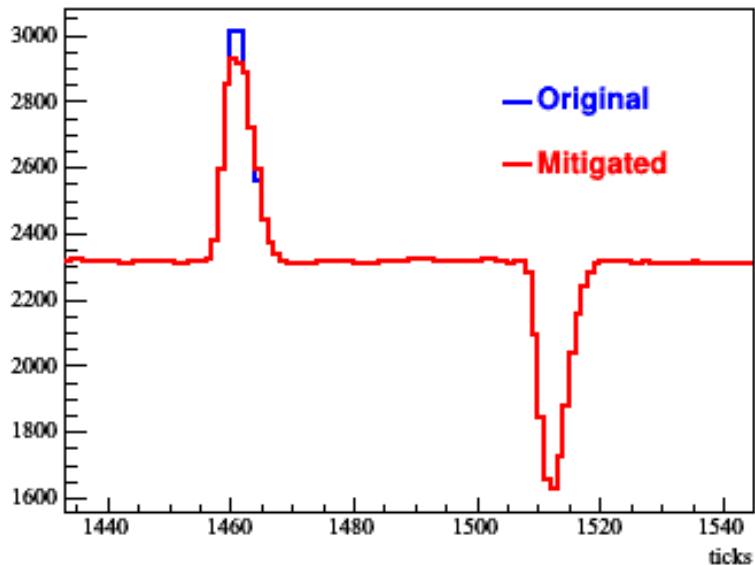
- Only the phase changed, while no changes of the magnitude in the frequency domain
  - Still respect the shape of the electronics response function
- Sometimes, good code tagged as “sticky”, the FT interpolation presumably minimize the biases
  - Balance of efficiency and accuracy for sticky code tagging



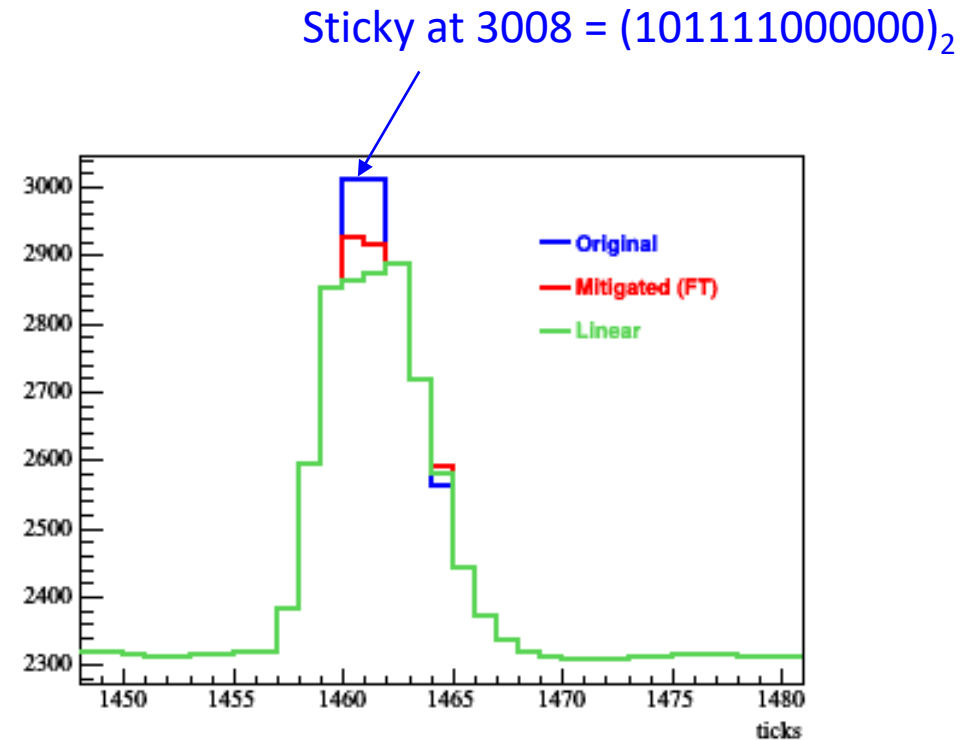
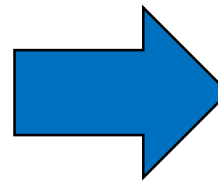
# Performance of ADC mitigation



# Preamp pulser data



Zoom-in



- However, when two adjacent sticky codes happens on the peak region, the mitigation does not work well
- Need to improve this special case
  - Maybe ignore the base correction from linear interpolation

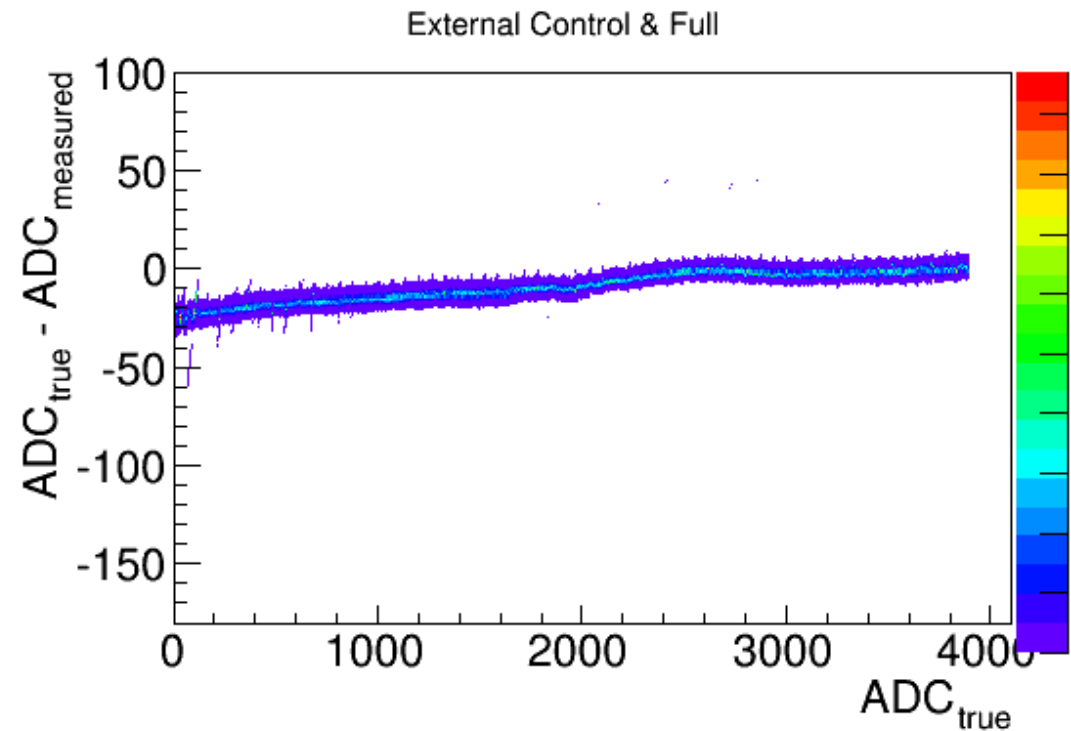
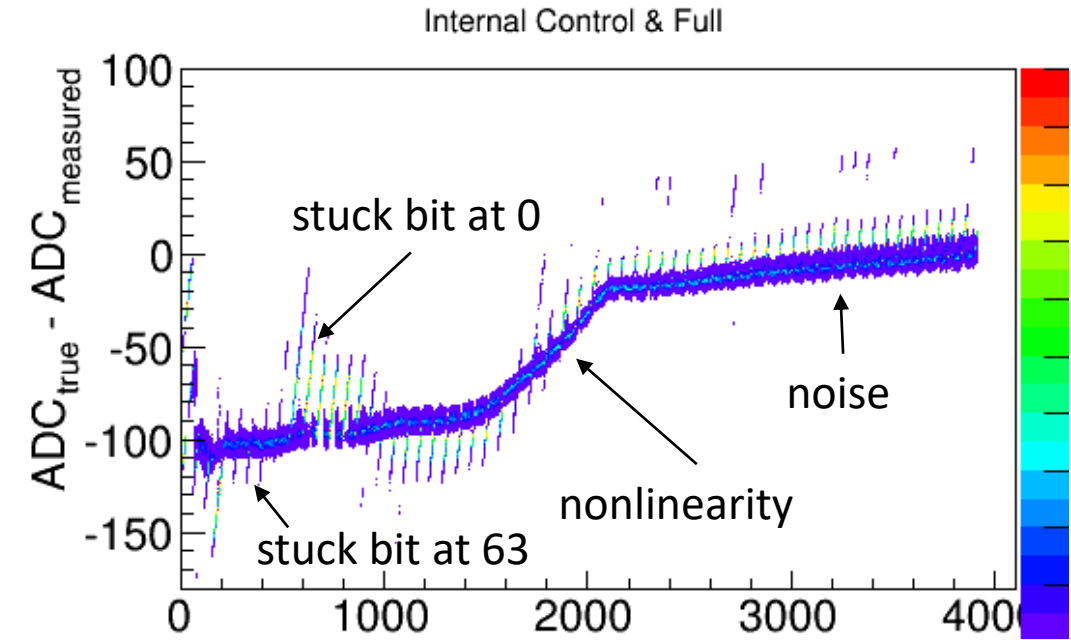
# Short summary on sticky code

- Sticky code is caused by the electronics instability during the MSB and LSB conversion phase
- Sticky code mitigation was preliminarily studied with protoDUNE data
- A linear interpolation and a FT interpolation was applied, some special cases needs to be improved

# ADC nonlinearity calibration

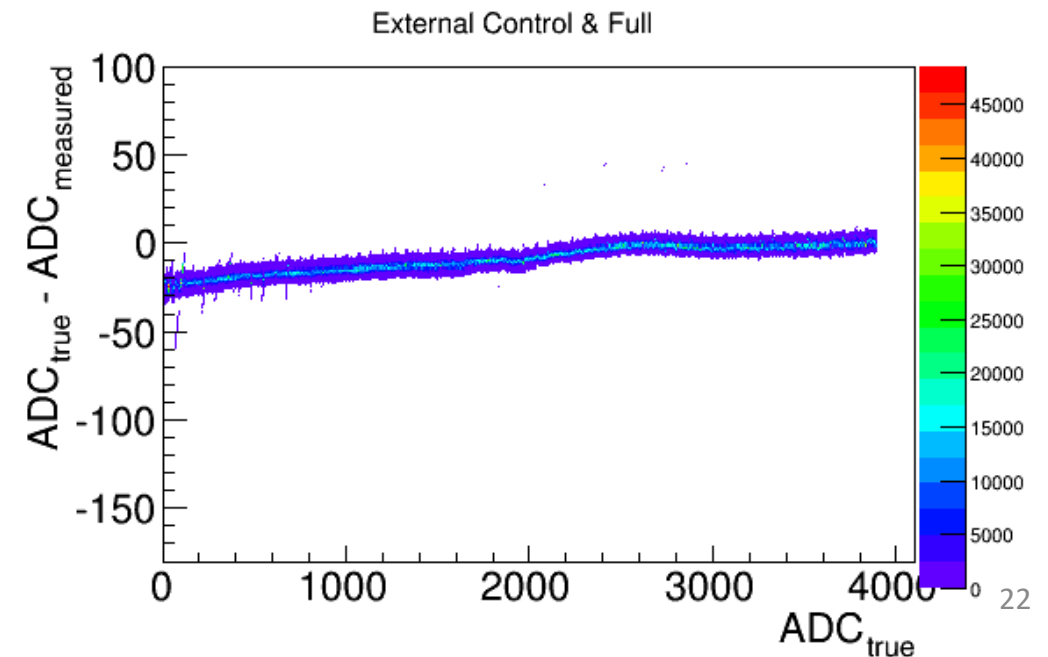
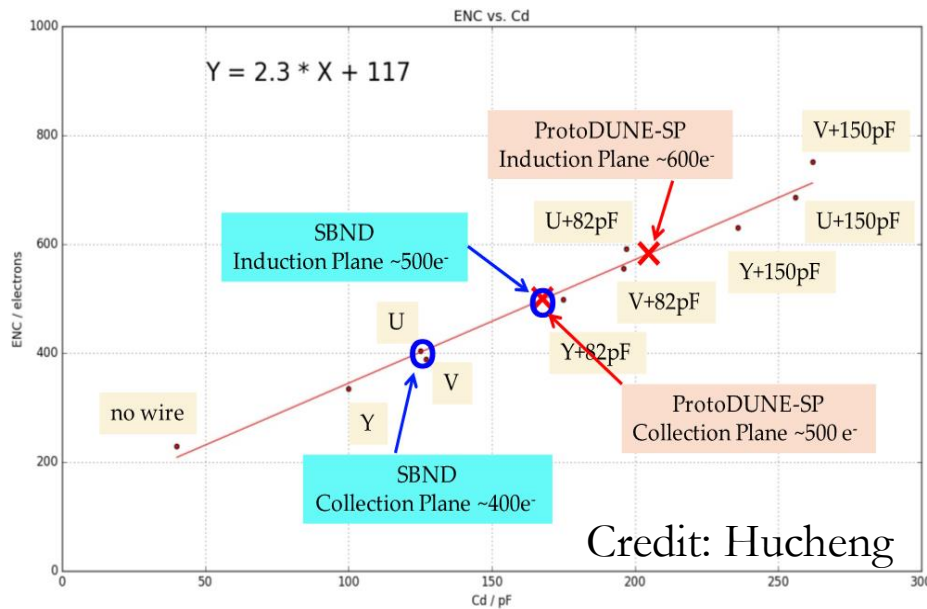
# ADC nonlinearity

- ADC nonlinearity (NL) is a common issue even for warm electronics
- However, low temperature degrades the electronics and read/write logics
- External clock eases NL as well as sticky code
- NL is sensitive to clock settings



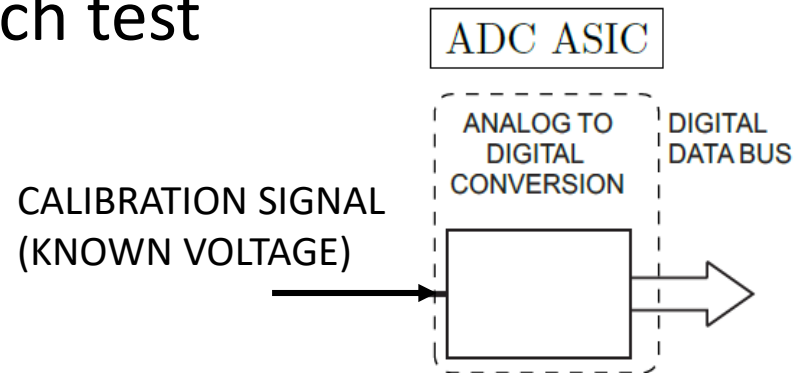
# Motivation of the NL calibration

- 600  $e^-$  ENC at ProtoDUNE ( $\approx 4$  ADCs)
- Would like to control the NL below 4 ADC in the useful range
- A precise determination of ADC would be very important for the extraction of ionized electrons and PID analysis



# Difficulties from a bench test to protoDUNE

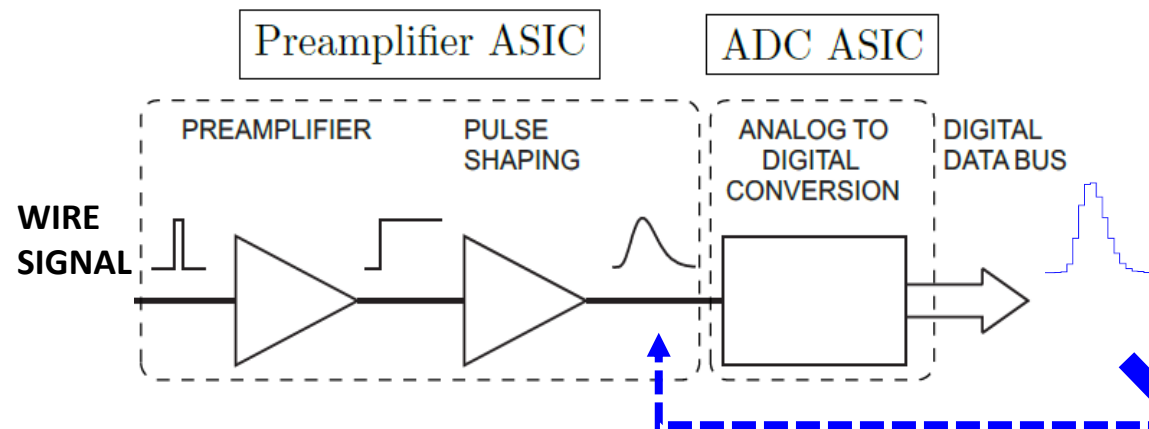
- Bench test



NL is sensitive to clock settings

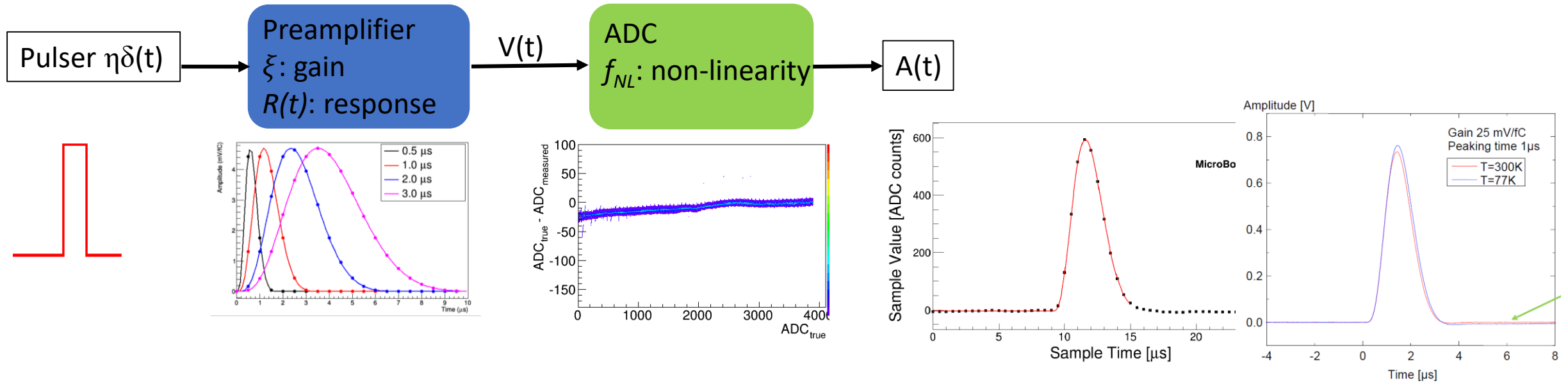
- (bench test) clock is tuned for each ADC
- (protoDUNE) one clock shared by four ADC circuits

- ProtoDUNE



No direct voltage input!

# Idea of the NL calibration setup

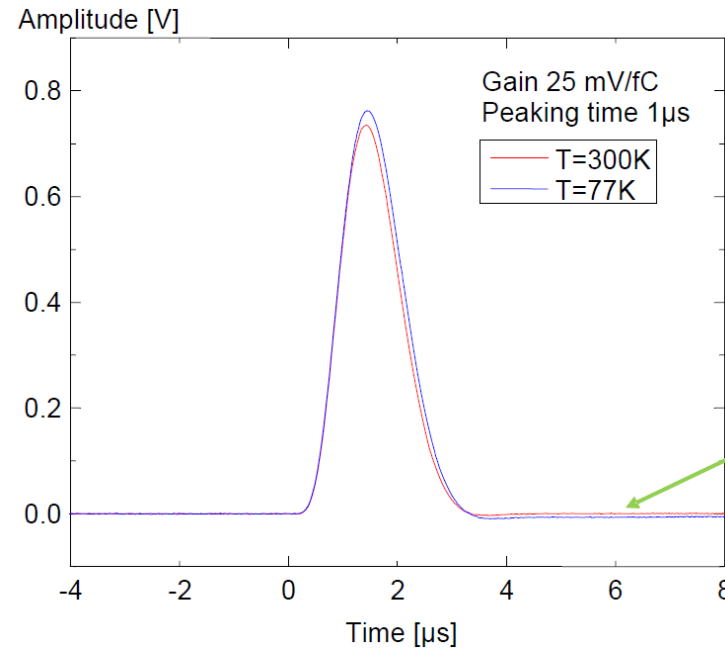
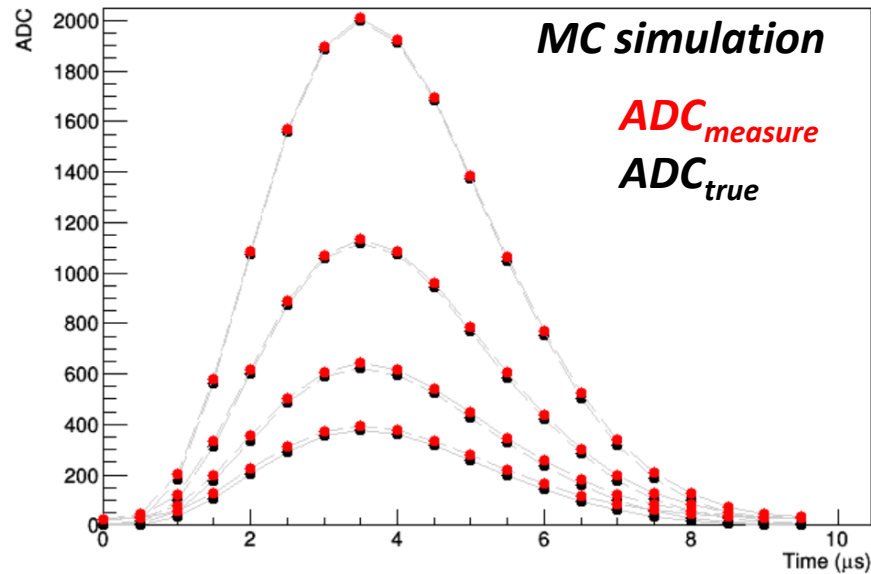


- Similar setup as in MicroBooNE electronics calibration
  - 6 bit pulser, i.e. 64 programmable amplitudes ( $<1.4\text{V}$ )
  - four adjustable gains of preamplifier

Caveat: cold environment also changes the response



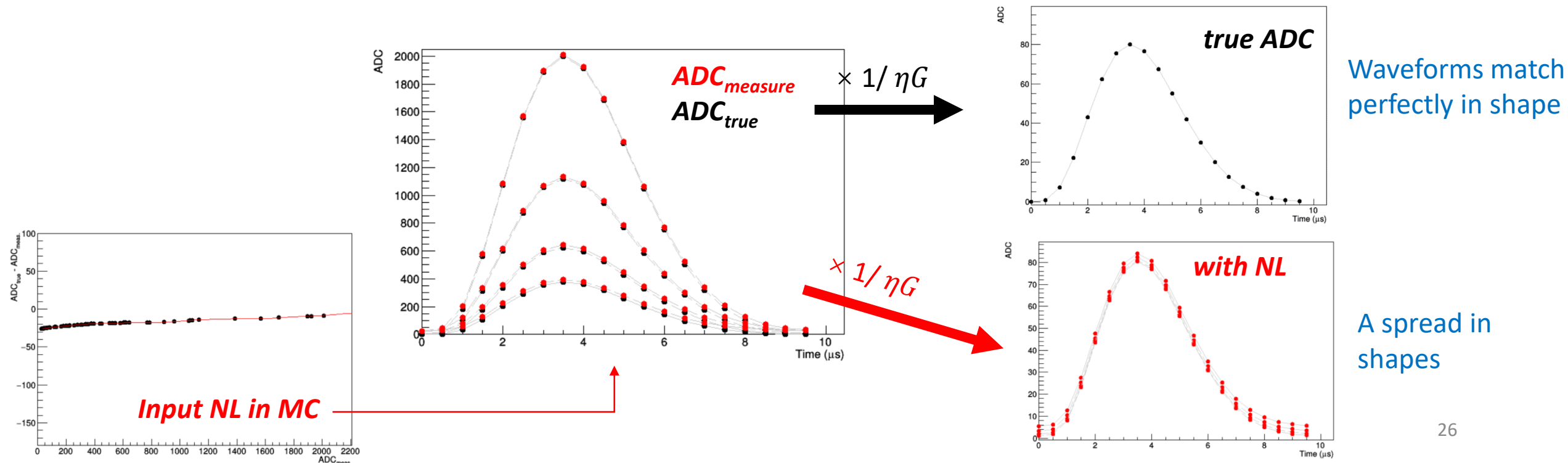
# Direct measurement of NL?



- Given a precise response function of the preamp, a NL measurement can be obtained
- However, low temperature change the response significantly

# From a response function perspective

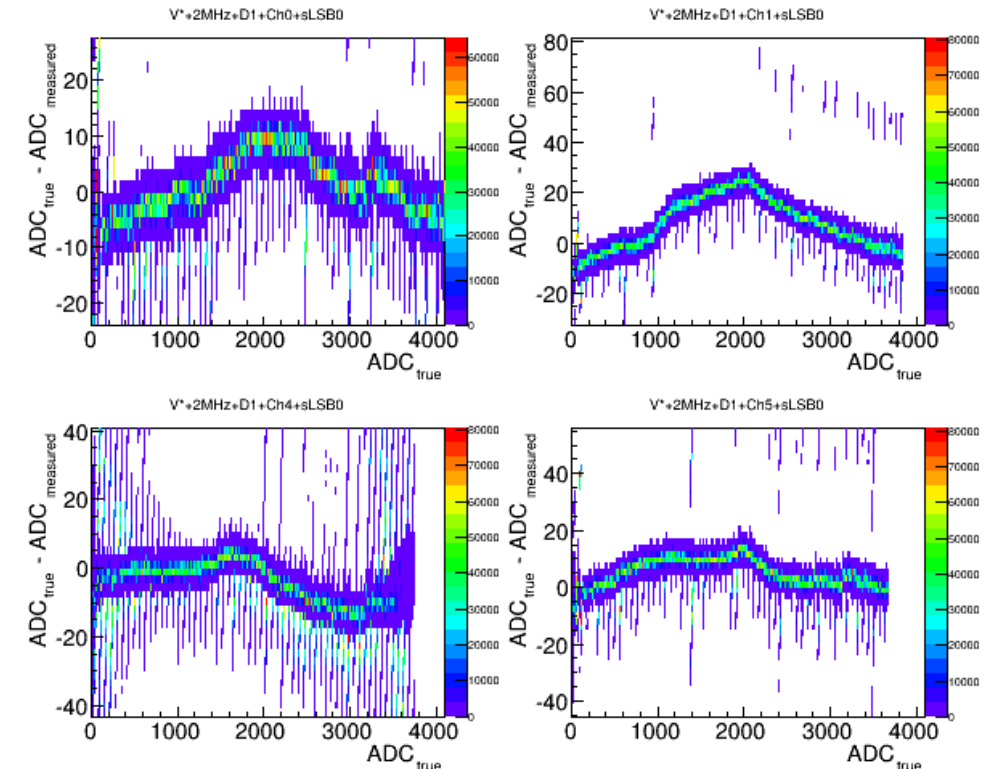
- Assume pulse voltage ( $\eta$ ) and preamp gain ( $G$ ) **do not change the shape of electronics response**
- NL distorts the shape differently for high ADC and low ADC



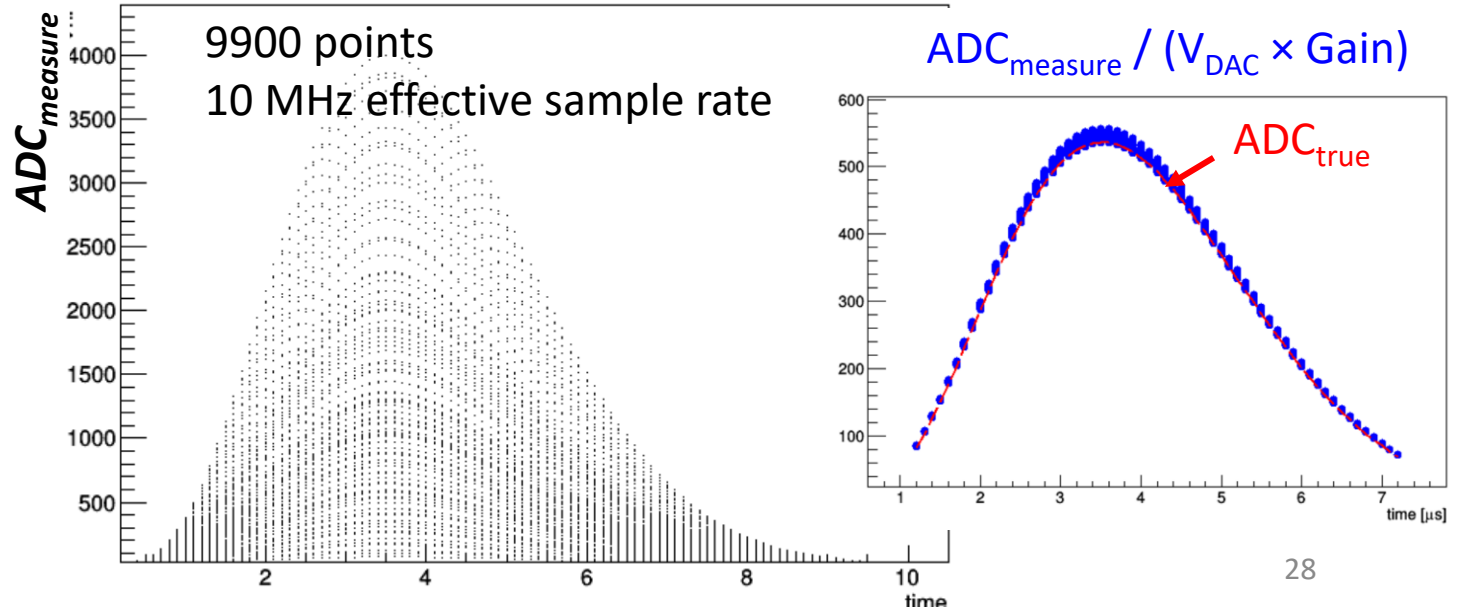
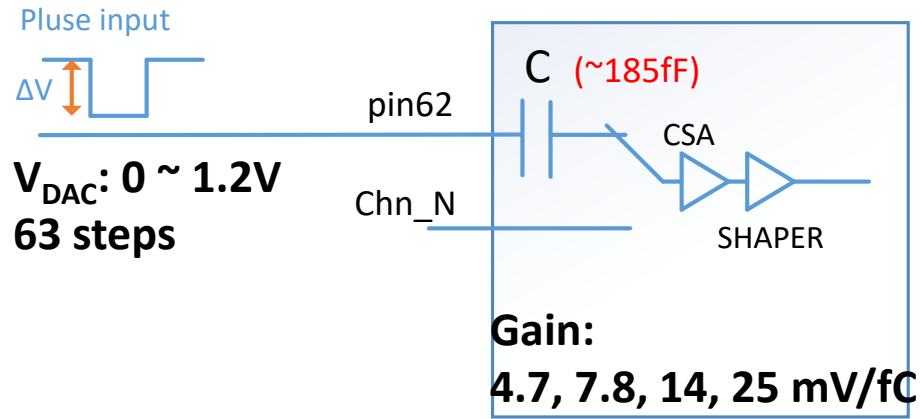
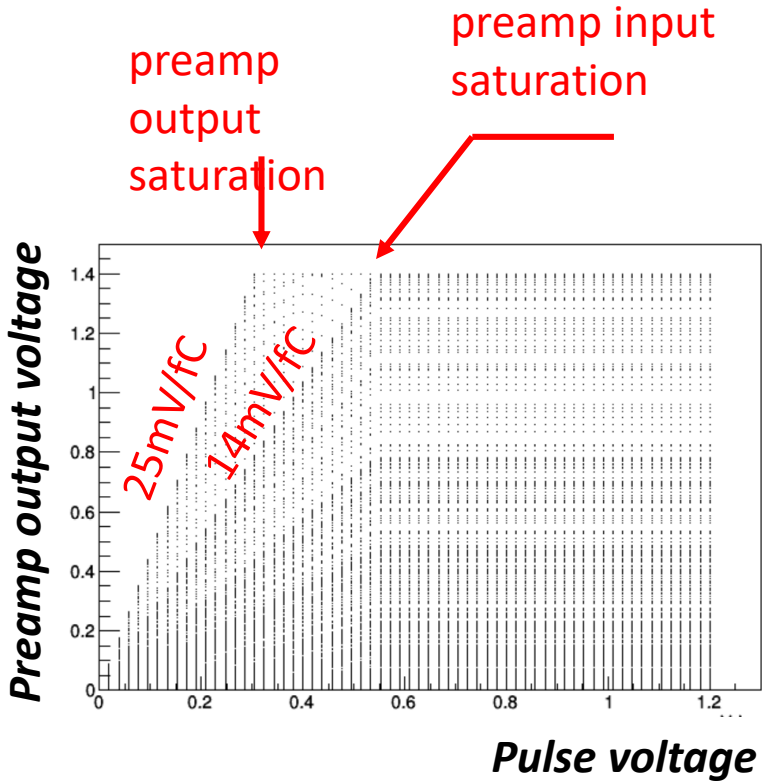
# Calibration strategy

- Assume a function of nonlinearity correction
  - a piecewise function
  - a polynomial function
  - a function build from a 12-bit ADC model
- Minimize the variance in  $A(t)/\eta G$ 
  - i.e. the effective response function
- $\sim O(10k)$  data points &  $\sim O(10)$  unknowns  
→ should be a solvable problem
- A channel by channel calibration plan

NL varies from channel to channel  
in the bench test

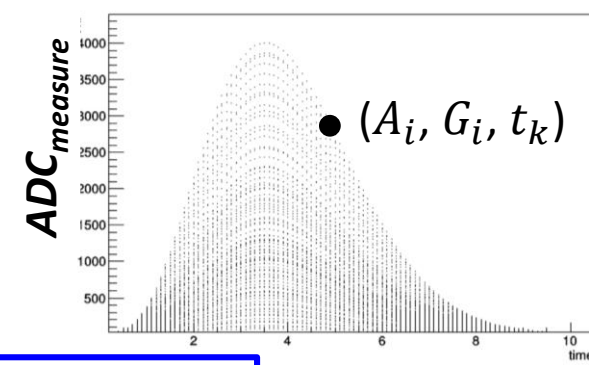


# Proof of principle with a MC simulation



- By ignoring some saturations in preamp, a 10k data set is possible

# $\chi^2$ minimization



index of the  $\alpha$ -th iteration

$G_i = \text{pulse voltage} \times \text{preamp gain}$   
(A normalization of charge input)

$$\chi^{2(\alpha)} = \sum_i (A_i + f^{(\alpha)}(A_i) - R^{(\alpha-1)}(t_k)G_i)^2$$

Time tick for  $A_i$

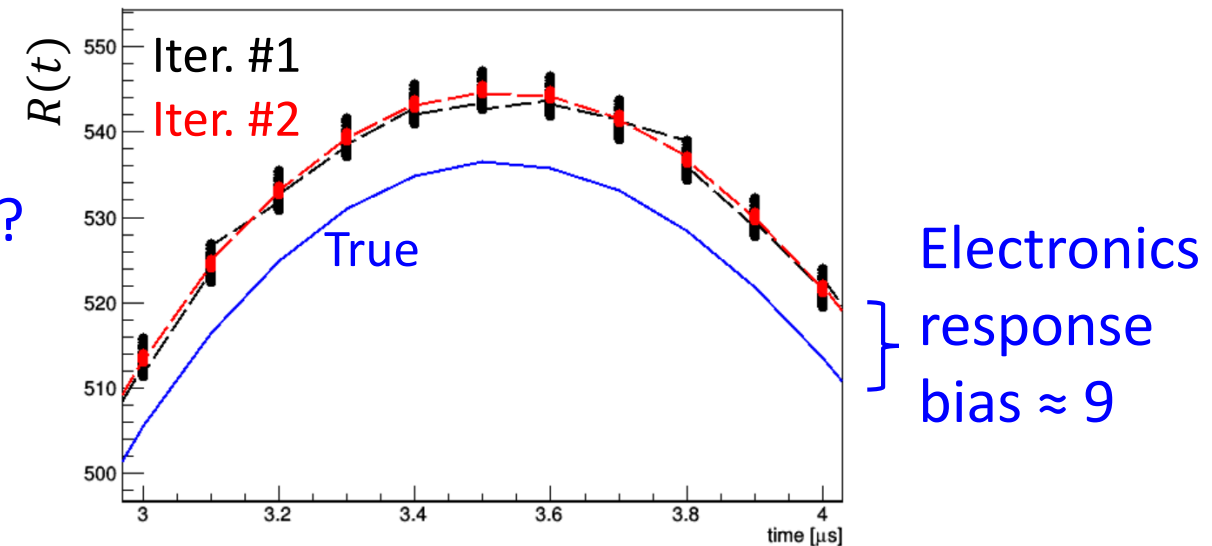
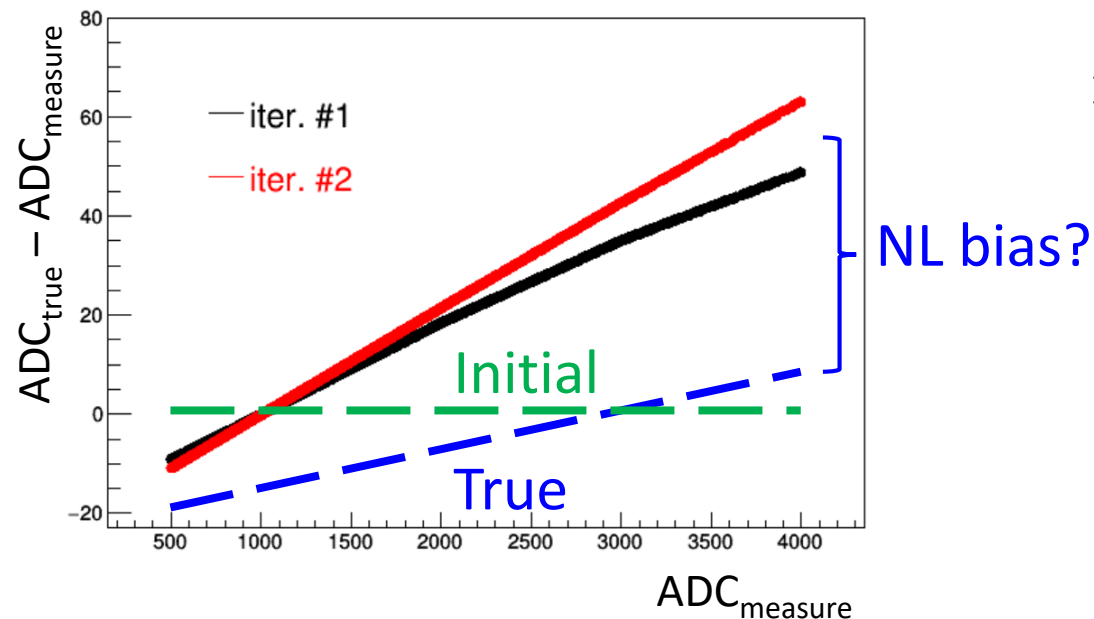
$i$ -th data point

**NL correction function**  
(To be fitted out)

$R^{(\alpha-1)}(t_k) = \frac{1}{N} \sum \frac{A_i + f^{(\alpha-1)}(A_i)}{G_i}$  is the  
**effective response function**  
(Calculated with the NL function from best fit of previous iteration)

# “Best-fit” $f(A_i)$ and $R(t)$

- Given an initial value of NL correction function  $f(A_i)$
- After a few iterations, “best-fit” NL  $f(A_i)$  and effective response  $R(t)$  tends to be stable
- The spread in  $R(t)$  significantly shrinks after minimization

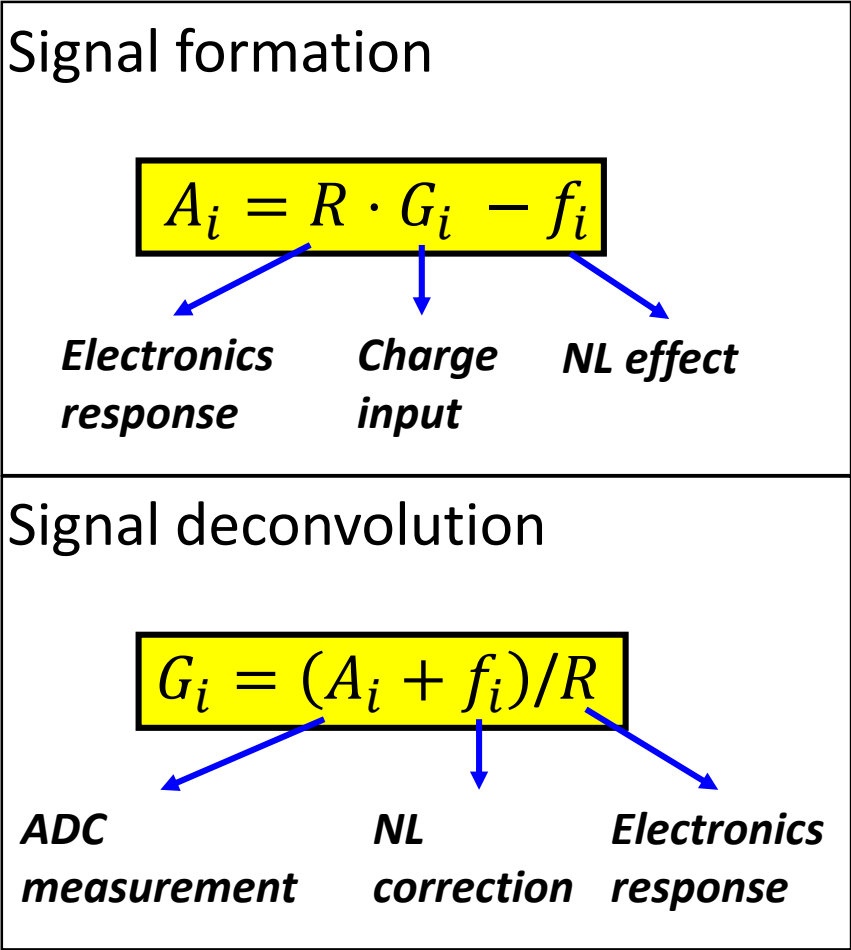


# Degeneracy in NL and response function

- Given different initial values,  $\chi^2$  minimization do not always converge to the true value
- Assume two sets of “best-fit” NL correction  $f(A)$  and  $F(A)$

Dataset	$\{A_i, G_i\}$	$\{A_i, G_i\}$
NL correction function $f_i$	$f(A_i)$	$F(A_i)$
Effective response function $R(t)$	$\frac{A_i + f(A_i)}{G_i}$	$\frac{A_i + F(A_i)}{G_i}$
ADC formation	$R \cdot G_i - f_i$	
ADC for charge $G_i$	$A_i$	$A_i$

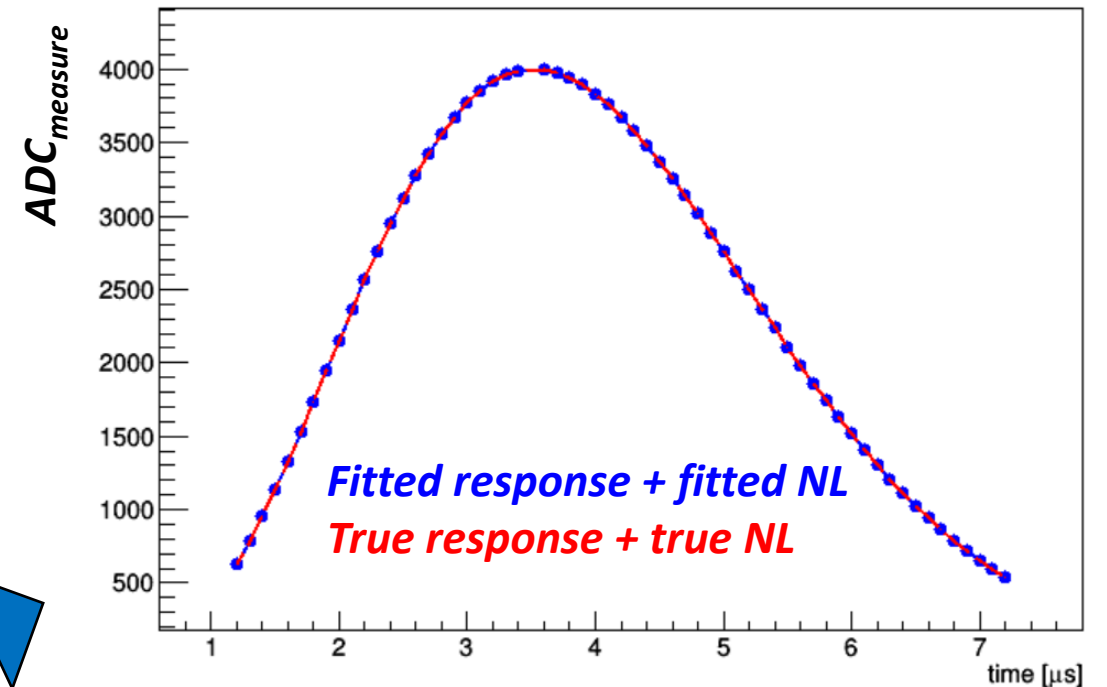
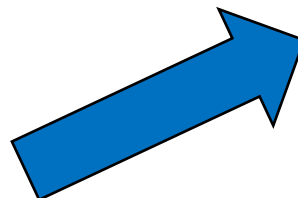
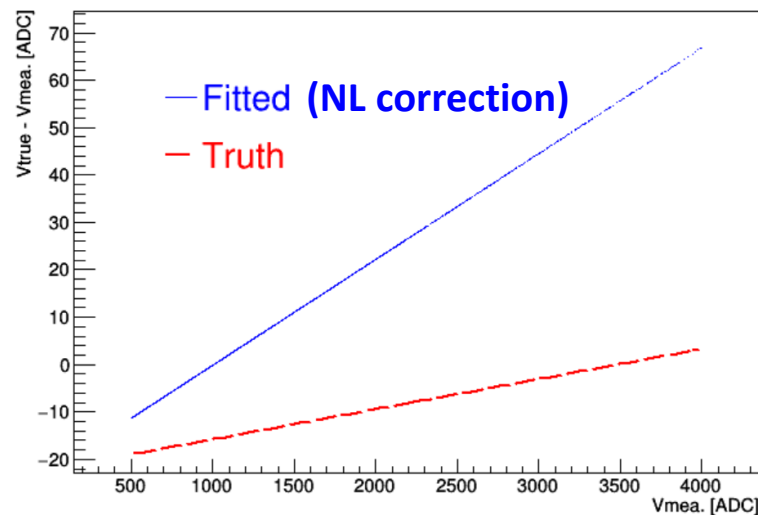
best fit



- Two sets of NL & response function are equivalent in signal prediction and deconvolution

# MC validation of the degeneracy

- Given a same charge input, the waveform predictions are close ( $<1$  ADC) for
  - True response and NL
  - A “best-fit” effective response and NL



NL bias in “best-fit” is not a problem!



# Interim summary

- Principle of ADC nonlinearity (NL) calibration for protoDUNE was studied through a simplified Monte Carlo study
- With a series of well controlled pulses to the charge preamplifier, an **effective ADC NL** and an **effective electronics response** function of the preamplifier can be obtained
- The ionization charge can be accurately extracted given these two effective functions

# Summary

- Cold electronics is crucial for LArTPC experiments
- The sticky code mitigation and ADC nonlinearity calibration are essential for a precise determination of TPC readout
  - Sticky code mitigation was preliminarily studied with protoDUNE data
  - ADC nonlinearity calibration was studied with a MC simulation
- For any downstream analysis that requires a precise extraction of ionized electrons (e.g., PID), such ADC calibration would be meaningful

# Wire-Cell signal processing in protoDUNE

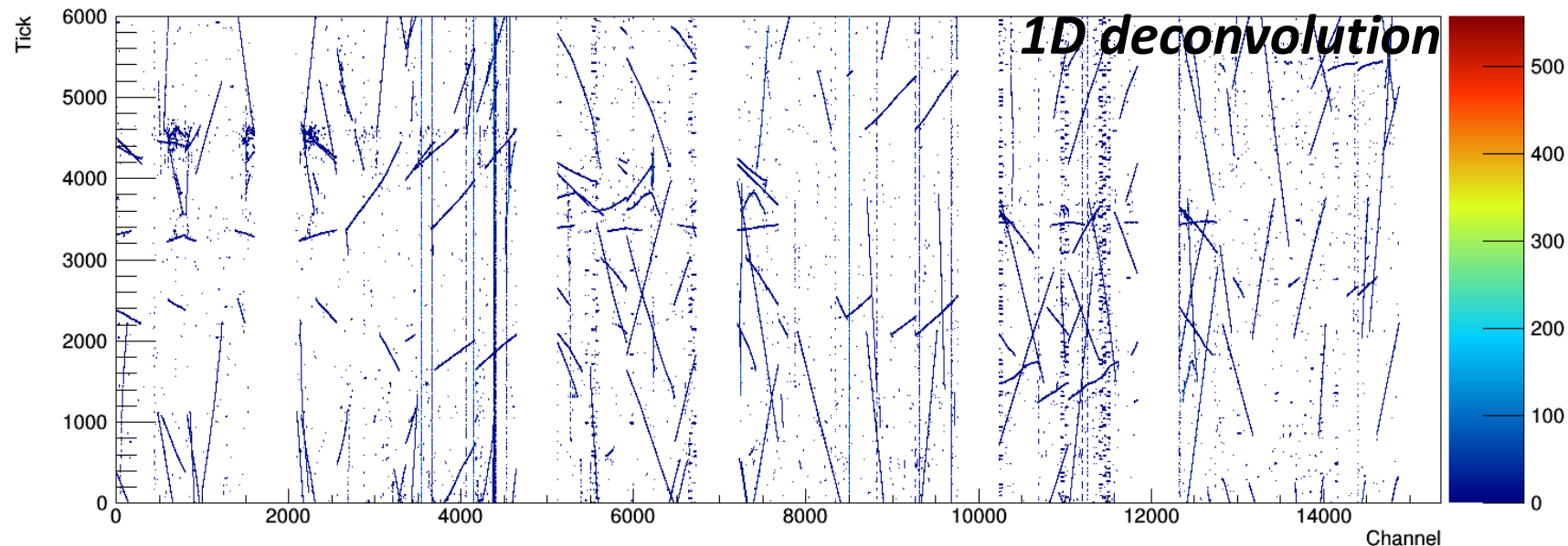
(Figures to be included in Hanyu's Wire-Cell signal processing talk)

# SP Performance in protoDUNE beam data

**Run 5141, Event 23865**

**Threshold: 5**

**From the offline reco chain  
(protoDUNE\_reco\_data.fcl)**



**Run 5141, Event 23865**

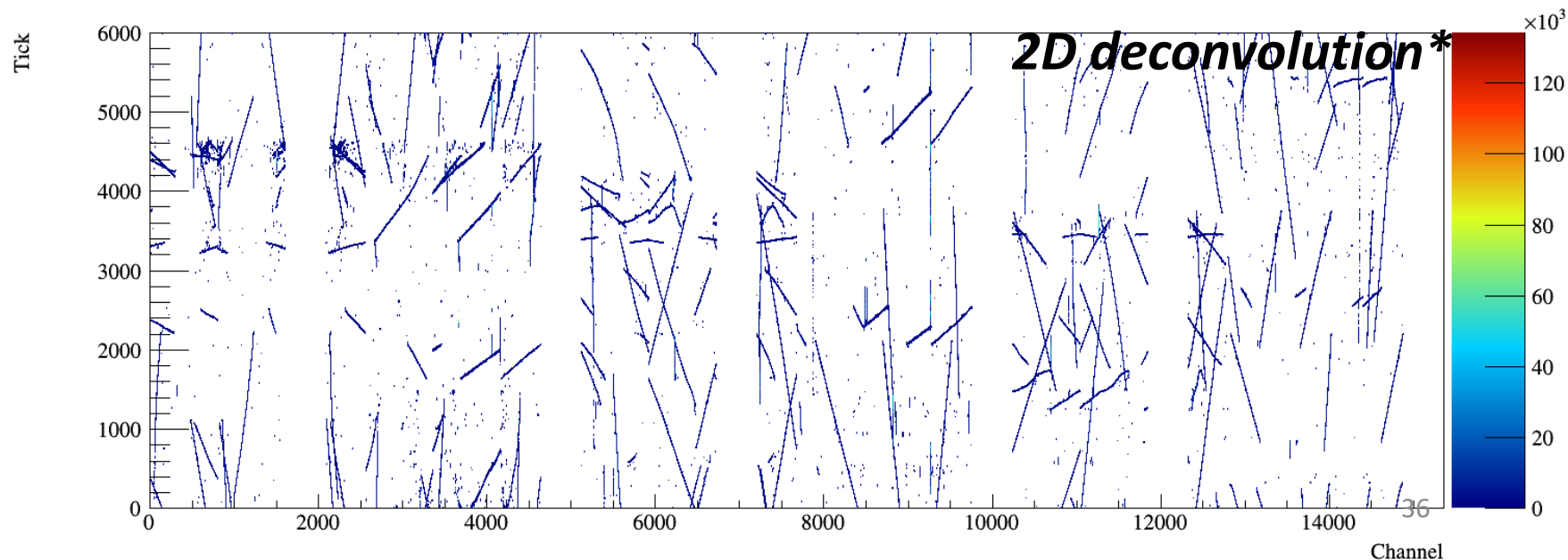
**Threshold:  $3\sigma$  noise**

**Unit: # of electrons**

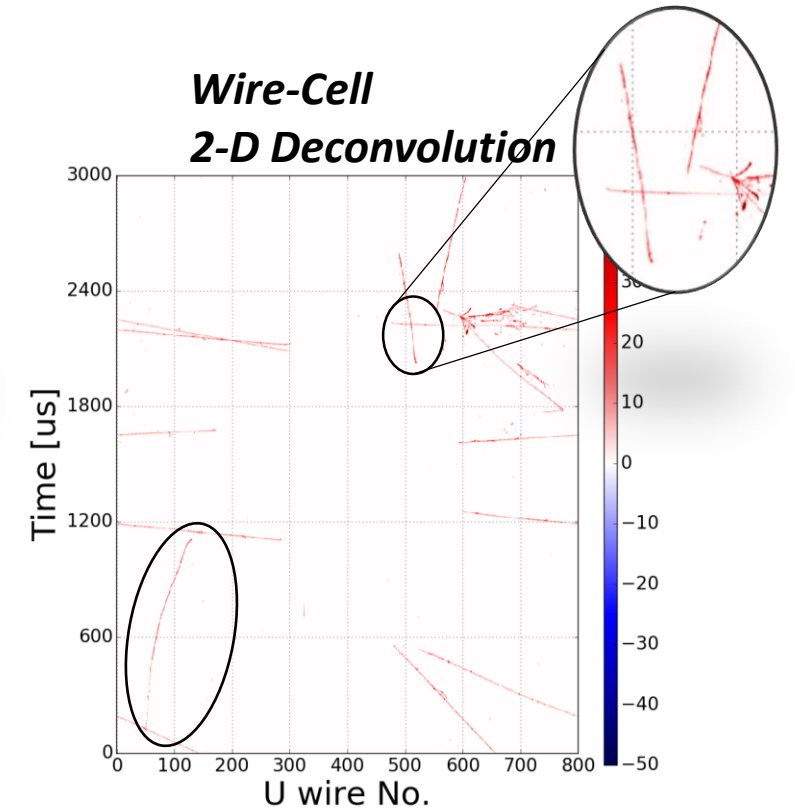
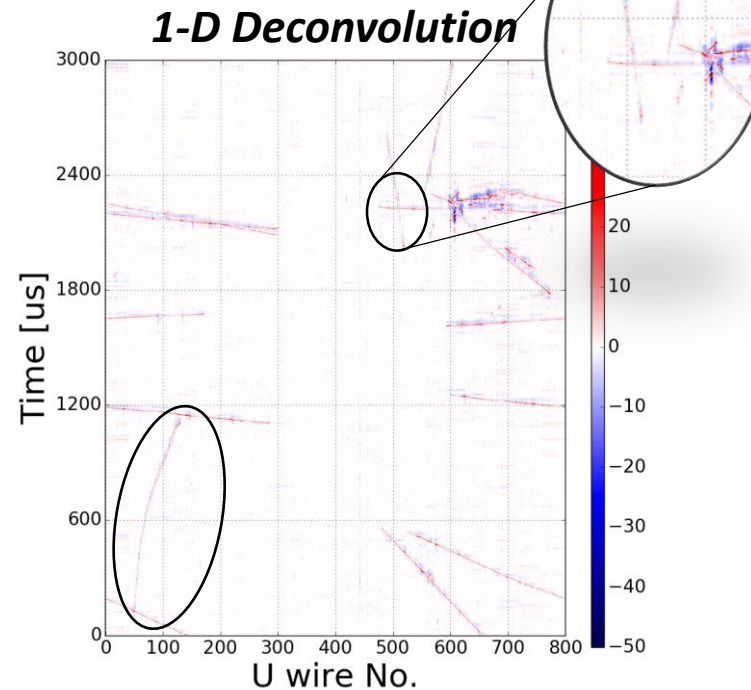
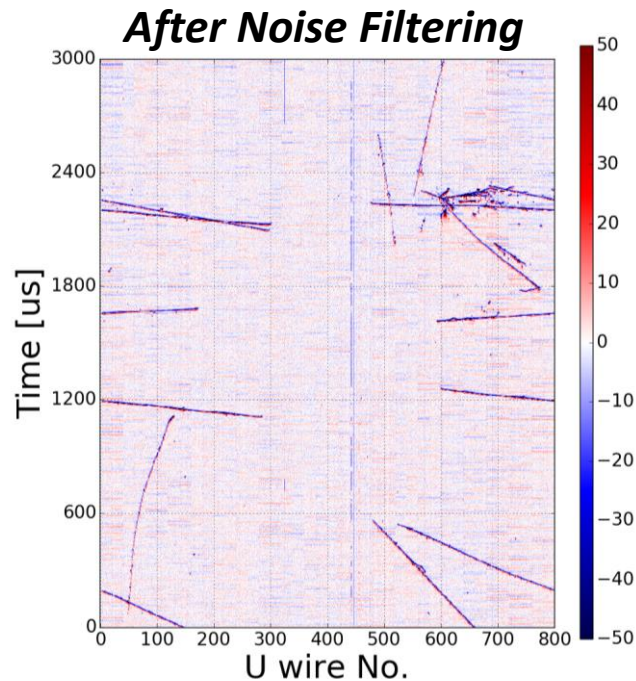
**From Wire-Cell toolkit**

*\*: There is still room for improving  
the software filter and some  
thresholds, etc.*

*\*\* : Noise filtering has not been  
applied here for both 1D & 2D.*



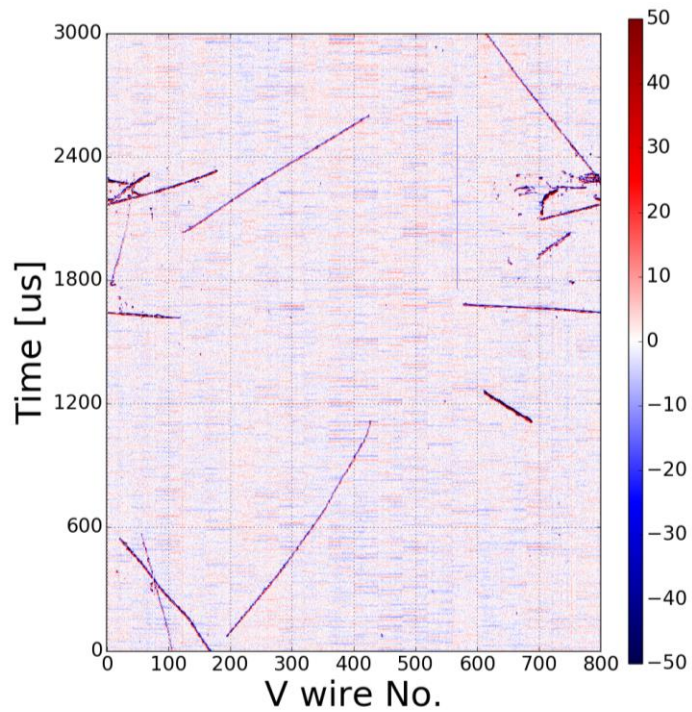
# Detailed example 1: U plane



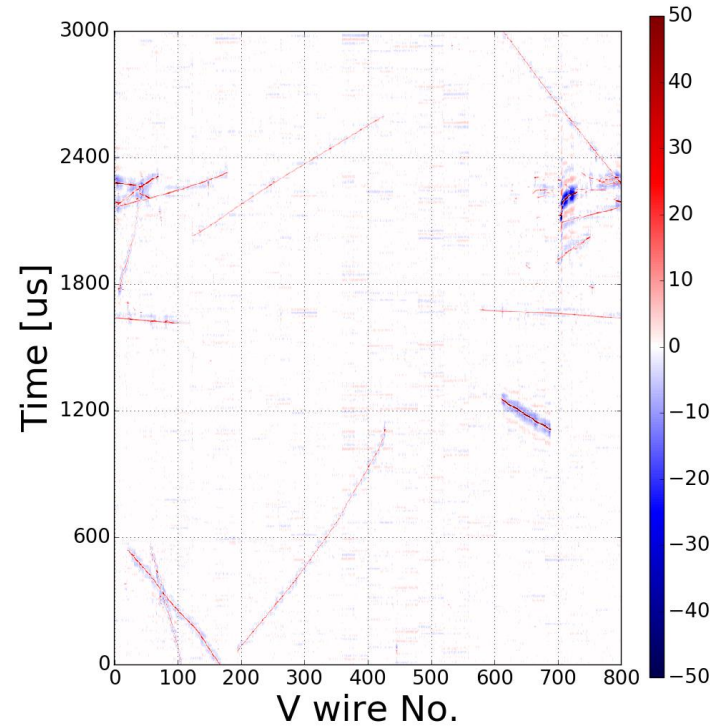
- Re-normalize 1D & 2D to the same scale
- No significant negative component after 2D deconvolution
- Long tracks (in time) are more visible in the 2D deconvolution

# Example 2: V plane

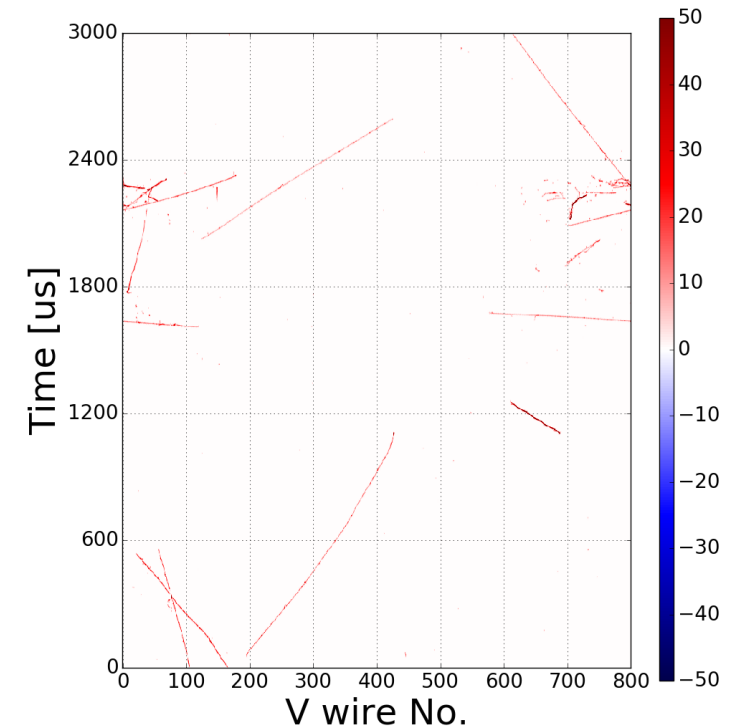
*After Noise Filtering*



*1-D Deconvolution*

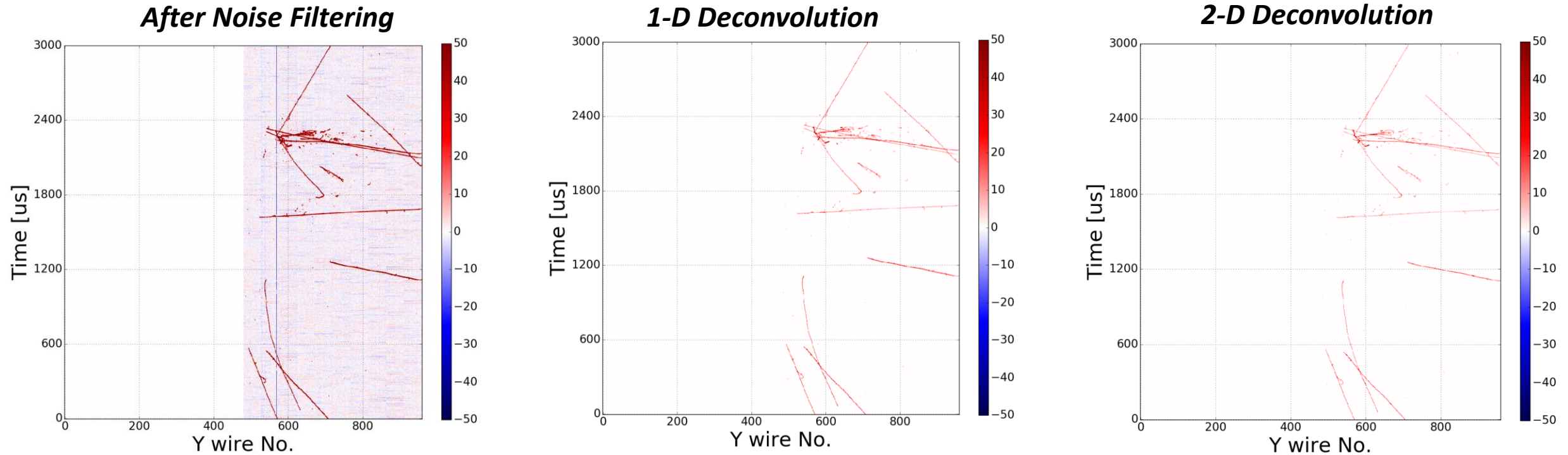


*2-D Deconvolution*





# Example 3: W plane



- 1D & 2D deconvolution are consistent in collection plane