



# Resonance Control for Superconducting RF Cavities

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- **Status:** 5<sup>th</sup> year MSU graduate student, Physics and Astronomy Department
- **Research at Fermilab**
  - **Microphonics**
  - **Dynamic tuner/ Piezo Actuators/Reliability**
  - **Resonance Control Algorithm**
  - **DOE SCGSR**
    - **Date:** 10/30/2017-4/30/2018
  - **PIP-II**
    - **Date:** 5/1/2018-Present
  - **Joint University-Fermilab Doctoral Program in Accelerator Physics and Technology**
    - **Date:** 09/1/2018-Present

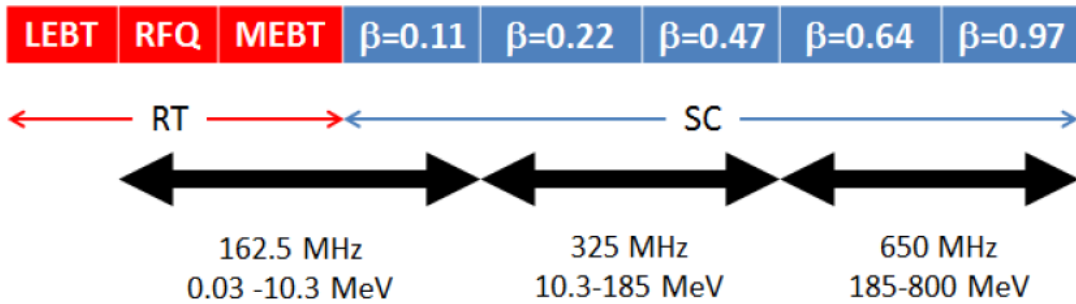
# Outline

- Introduction
- Microphonics
  - Effects on detuning
  - Passive resonance control

## Fast/Slow Tuner

- Mode of operation
- Requirements for cavity
- Piezo Actuator/Reliability
- Resonance Control Algorithm
  - System Characterization

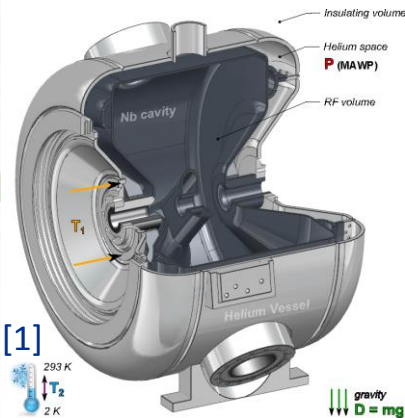
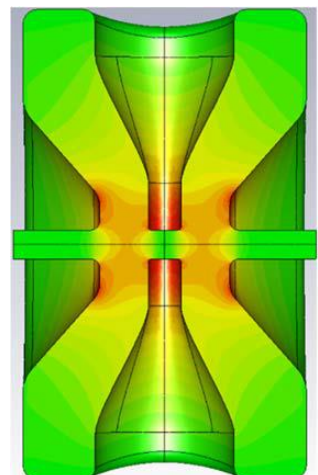
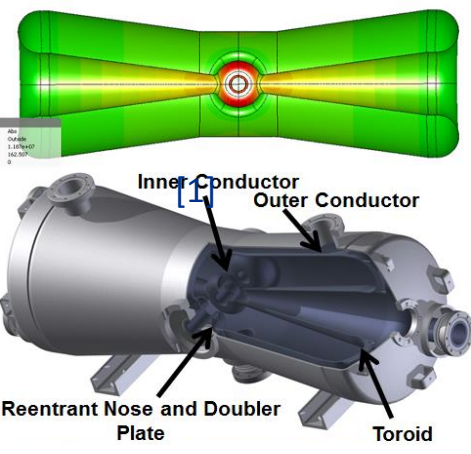
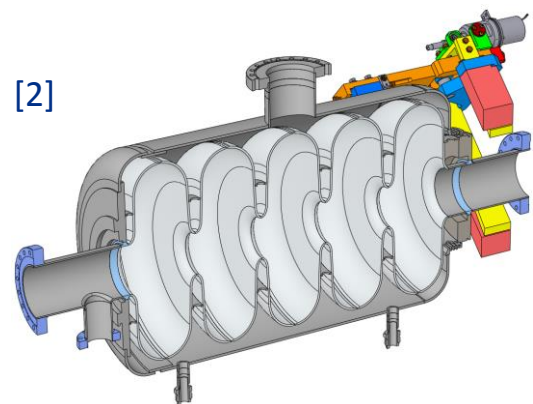
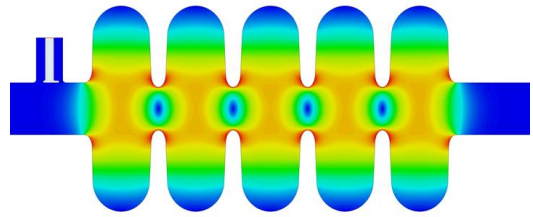
# Superconducting RF Cavities



Multicell Elliptical Cavity  
 $f_o = 650 \text{ MHz}$   
 Low Beta (LB)  $\beta_o = 0.64$   
 Low Beta (HB)  $\beta_o = 0.97$

Half-wave Resonator  
 $f_o = 162.5 \text{ MHz}$   
 $\beta_o = 0.11$

Single Spoke Resonator (SSR)  
 $f_o = 325 \text{ MHz}$   
 SSR1  $\beta_o = 0.22$   
 SSR2  $\beta_o = 0.47$



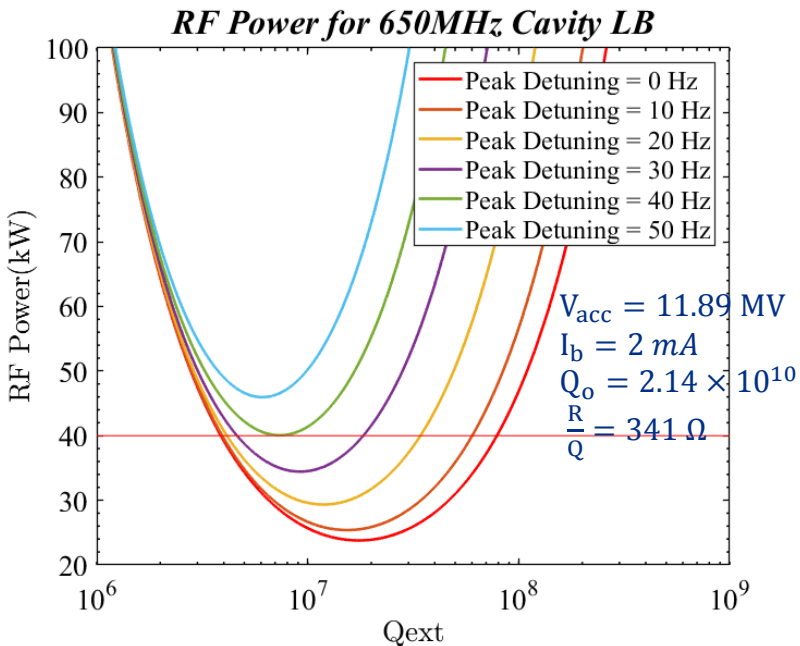
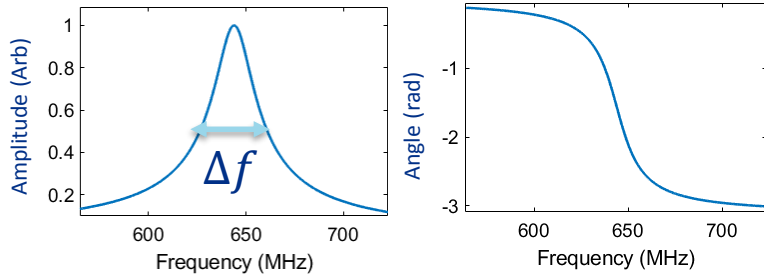
# Superconducting RF Cavities

- Cavities are manufactured from thin sheets of Nb for efficient cooling to superconducting temperatures
- The thin walls make the cavities susceptible to deformation which in turn change the frequency

$$\frac{f - f_0}{f_0} = \frac{\int_{\delta V} (\mu_0 |\vec{H}|^2 - \epsilon_0 |\vec{E}|^2) dV}{\int_V (\mu_0 |\vec{H}|^2 + \epsilon_0 |\vec{E}|^2) dV}$$

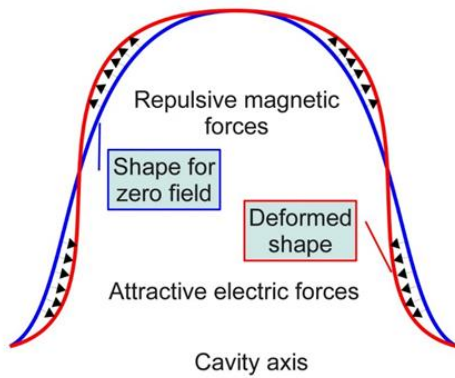
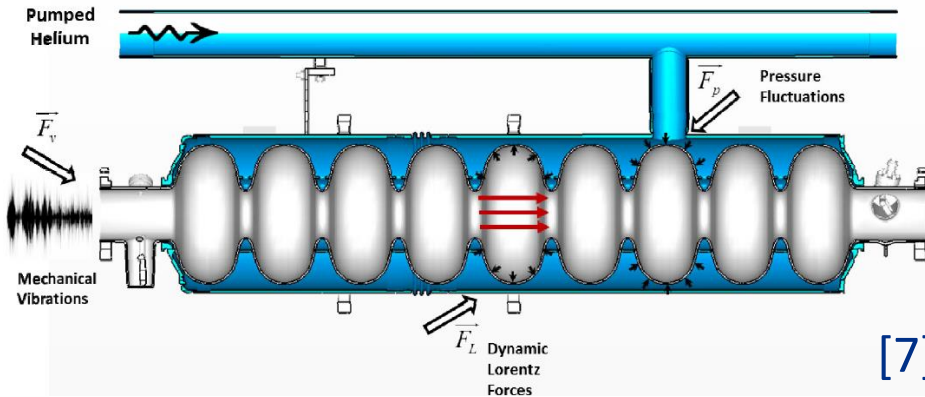
- Low Beta (LB) 650 MHz tuning sensitivity  $240 \frac{\text{Hz}}{\mu\text{m}}$
- **10 nm longitudinal deformation causes 2.4 Hz detuning**

# Why does detuning matter?



- To provide the desired accelerating gradient the cavity must be in resonance
- Narrow bandwidth of the cavities caused by low beam loading:
- $Q_L = V_{acc} / (I_b \frac{R}{Q}) = 1.74 * 10^7$
- Cavity bandwidth:  $\Delta f = f_0 / Q_L = 37 \text{ Hz}$
- RF power source can provide 40 kW
  - Provide power to the beam and cavity (RF power 23.8 kW)
  - Detuning from microphonics (~16 kW)
- Peak Detuning/Max RF power sets machine trip rate
- Reduce Linac trip rate
- Reduce RF power used thus reduce cost

# Microphonics and Lorentz Force Detuning



$$P_s = \frac{1}{4} (\mu |\vec{H}|^2 - \epsilon_0 |\vec{E}|^2)$$

$$\Delta f_0 = (f_0)_2 - (f_0)_1 = -K E_{acc}^2$$

[7] M. H. Awida et. al, "Multiphysics analysis of frequency detuning in superconducting RF cavities for proton particle accelerators," 2015 IEEE MTT-S

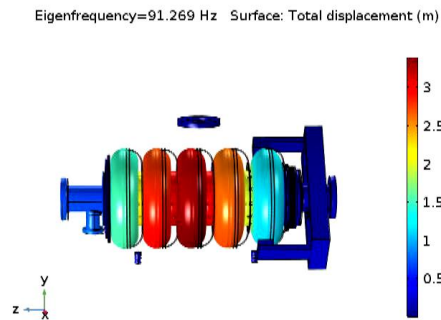
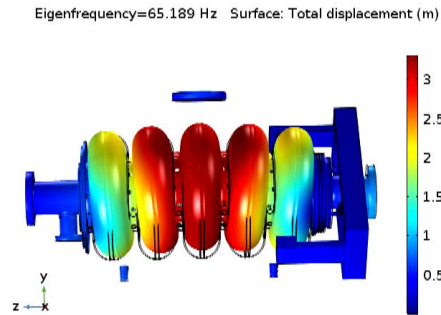
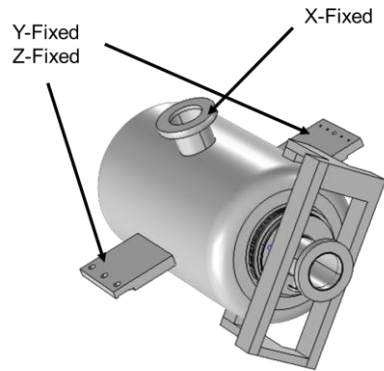
## Continuous Wave Operation

- Pressure variation in the surrounding He bath:
  - $\Delta f_{He} = \frac{df}{dP} \delta P, \delta P \sim 0.05 - 0.1 \text{ mbar}$  at 2 K.
- Internal and external vibration sources (microphonics)
- Cryogenic Valve Plumbing
  - Thermal acoustic oscillations

## Pulse Mode Operation

- Radiation pressure from the RF field, Lorentz Force Detuning (in pulsed mode).
  - LFD LB:  $-2 \text{ Hz} / \left(\frac{MV}{m}\right)^2$
  - At 16.9 MV/m,  $\Delta f = -571 \text{ Hz}$

# COMSOL Simulations of Vibrational Modes

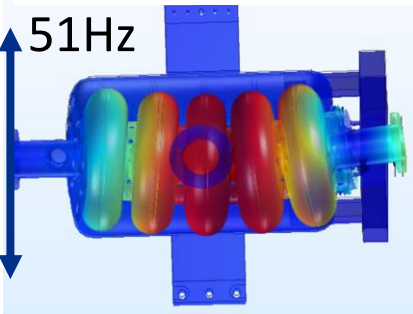


- FRIB cavity, similar to LB 650 MHz cavity
- Cavity detuning sensitivity 258 Hz/ $\mu\text{m}$
- COMSOL was used to simulate the mechanical resonances of a single cavity and helium vessel
- Single cavity simulations can be done in commercially available software
- The cavity/Helium Vessel design needs to be optimized to limit resonances

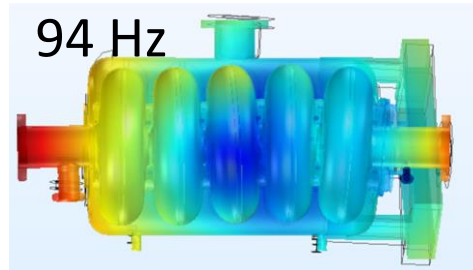


# Results from Simulations

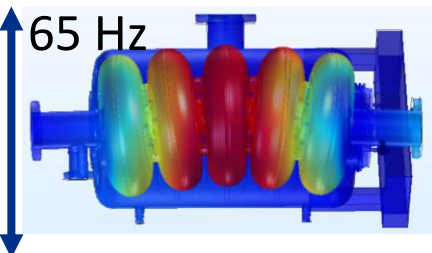
Transverse



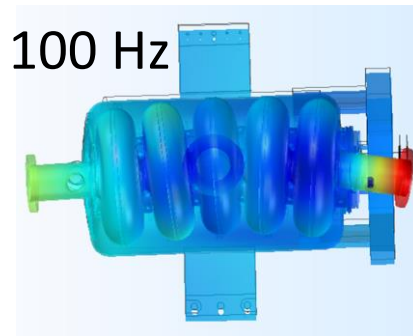
Vessel Mode



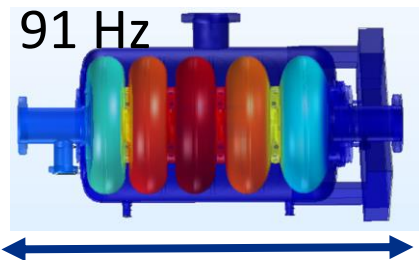
Transverse



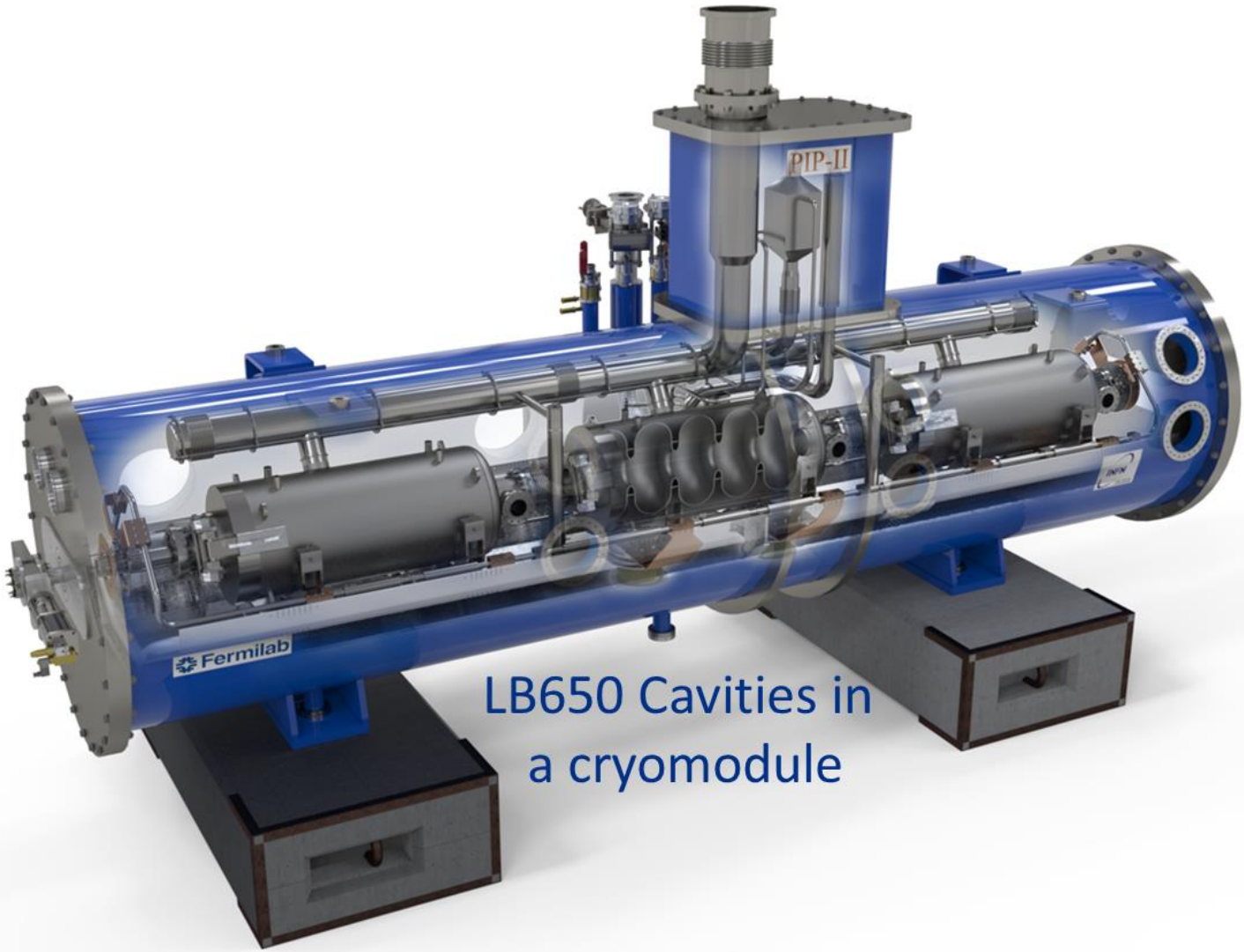
Cavity/ Vessel Mode



Longitudinal



- The longitudinal modes produce largest detuning
- Optimize to keep vibrational mode frequencies large
- Optimization for multiple cavities in a string along with all the components in the cryomodule is computationally demanding
- Conducting simulations will not be enough to mitigate microphonics



LB650 Cavities in a cryomodule

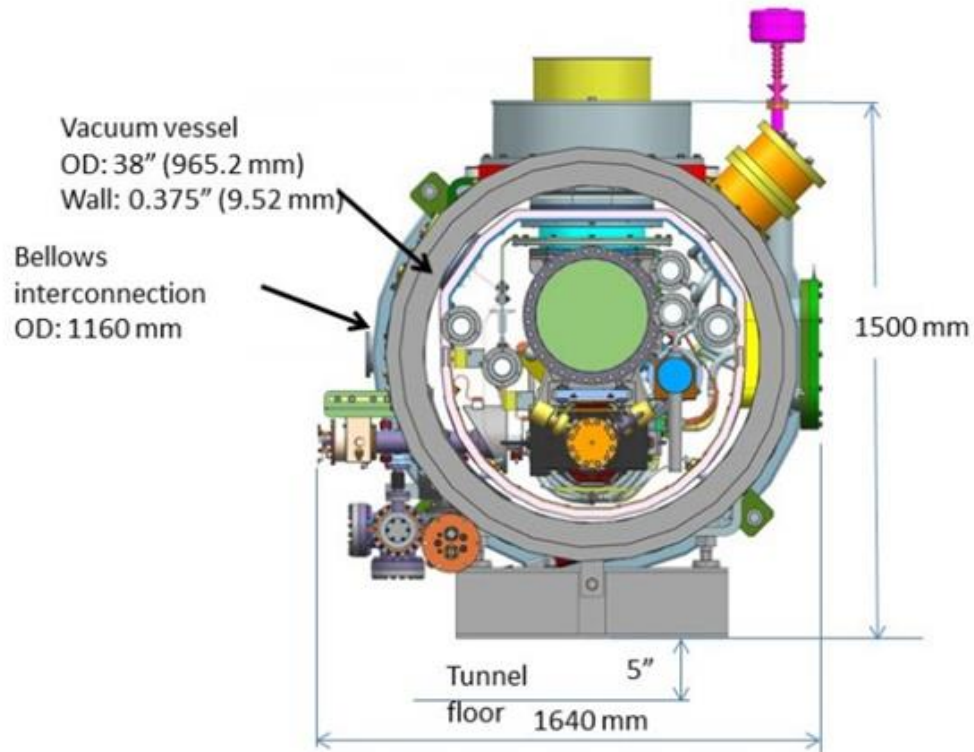
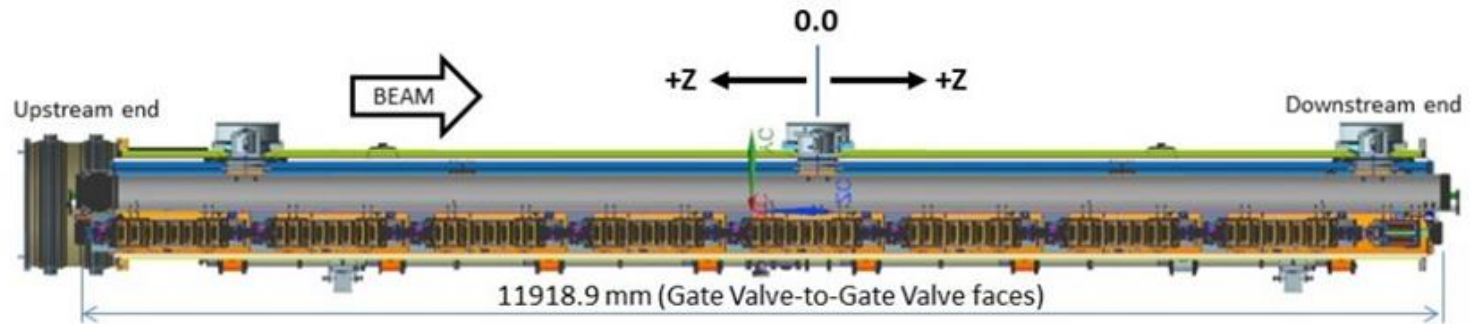
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  - Effects on detuning
  - Passive resonance control

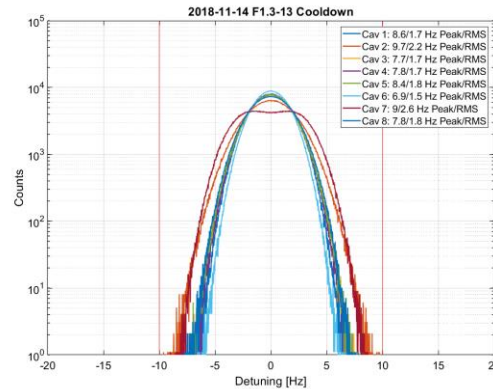
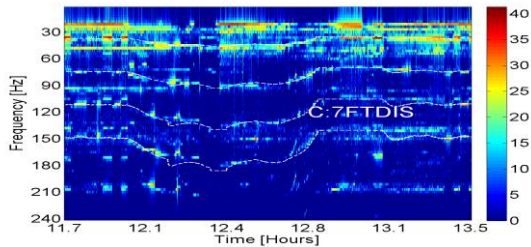
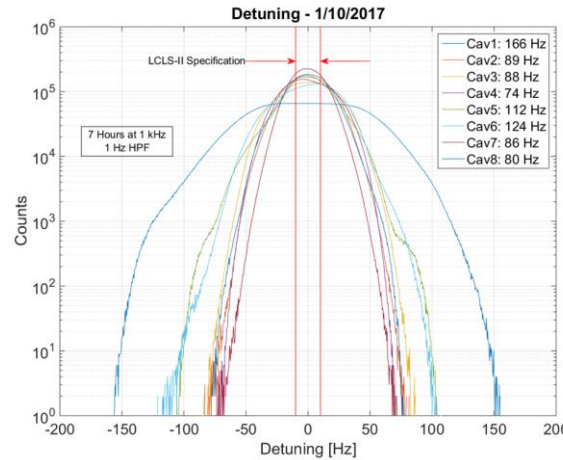
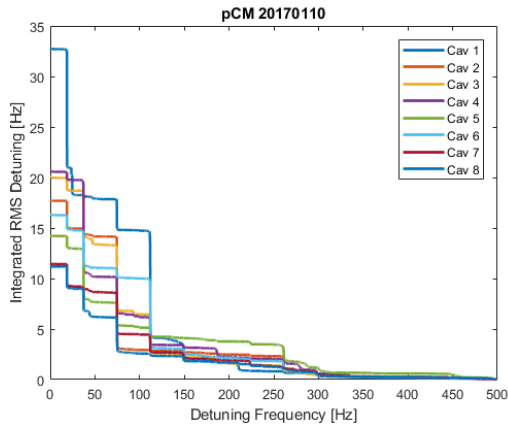
## Fast/Slow Tuner

- Mode of operation
- Requirements for cavity
- Piezo Actuator/Reliability
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  - System Characterization

# LCLS-II Cryomodule

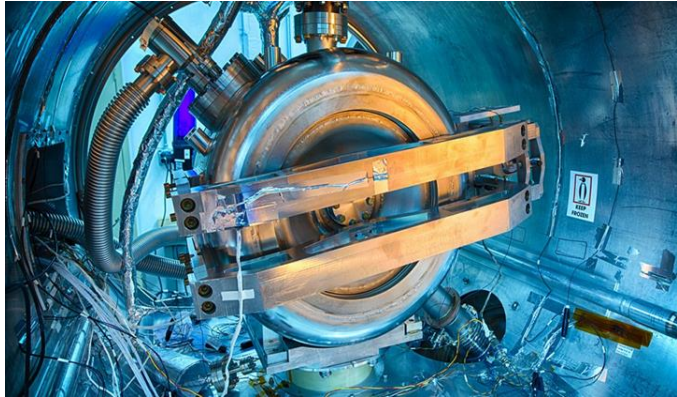


# Passive Resonance control

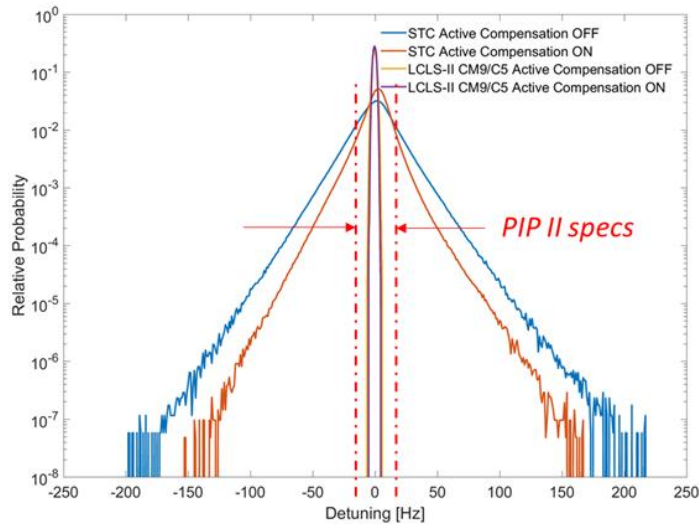


- LCLS-II Specification: 10 Hz peak detuning (excursion from 1.3 GHz)
- Initial cool down showed detuning was greater than the specification
- As is current resonance control algorithm cannot get into LCLS-II specification
- Changes in the cryogenic plumbing and mechanical were needed to get within specification

# Method of Detecting Microphonics

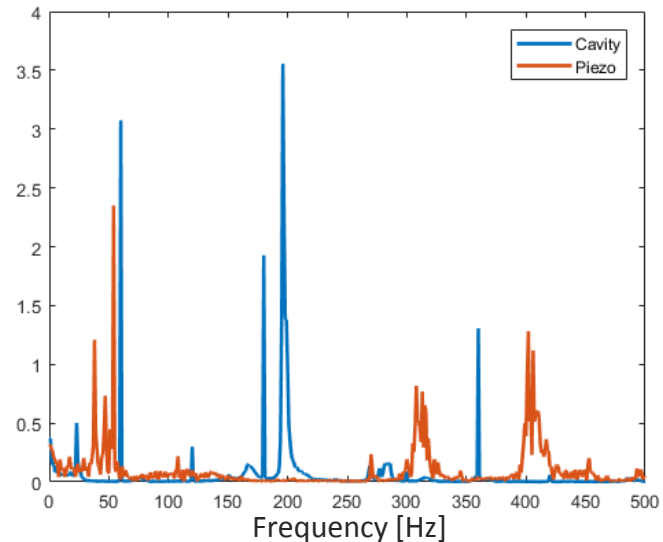
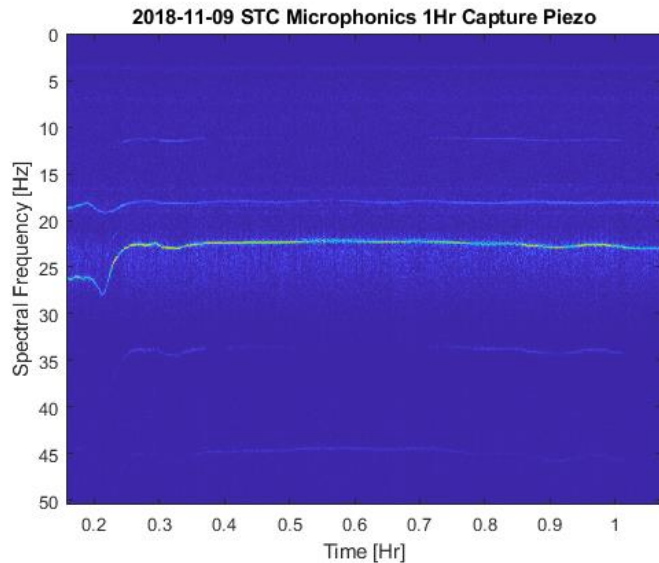
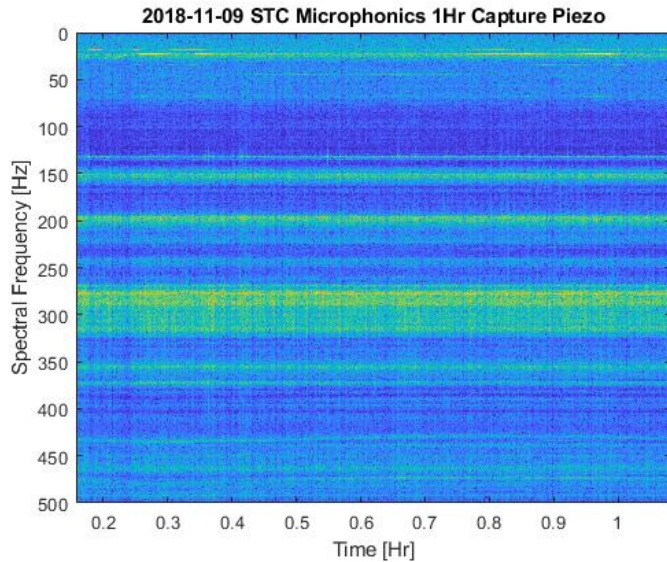


- Piezo Actuators
- Geophones
- Superconducting RF Cavity at 2 K is the most sensitive
- Specifications for PIP-II cavity is 20 Hz peak detuning
- With large detuning on the cavity the resonance control algorithm is not enough to get to PIP-II Specifications

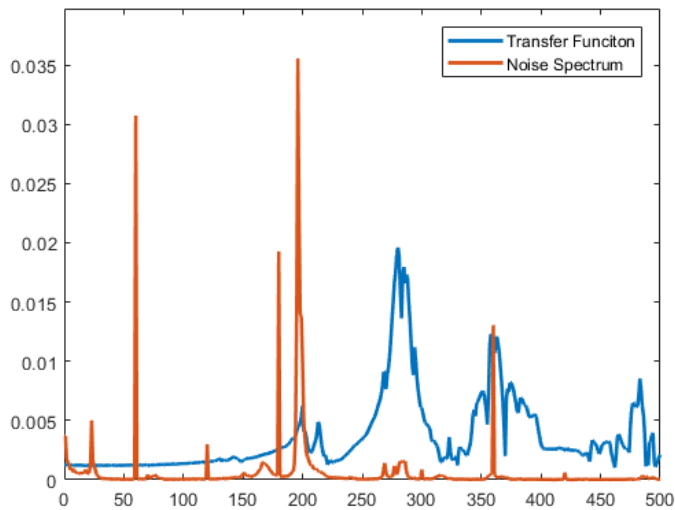


# Piezo as Sensor

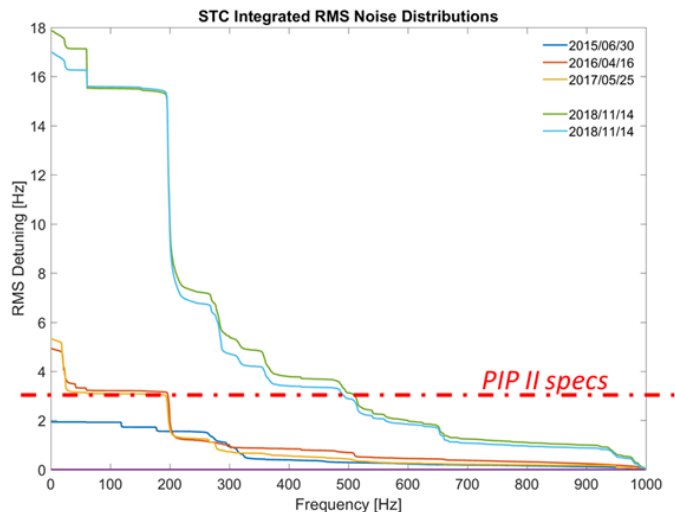
- When the piezo is compressed it will produce a voltage
- The voltage is recorded with sampling rate is 1 kHz
- Can be used when cavity is off
- Less precision
- Piezo



# Comparison of Noise to Resonant Frequencies



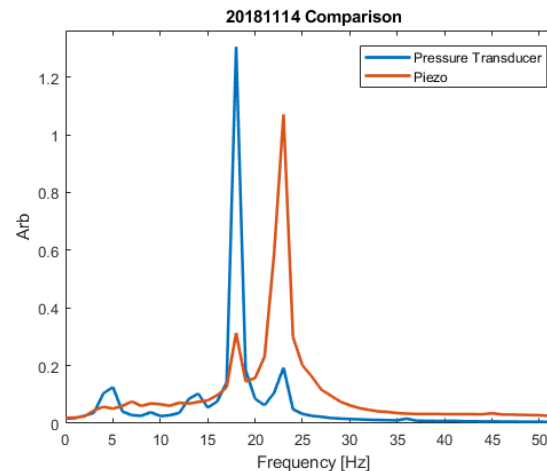
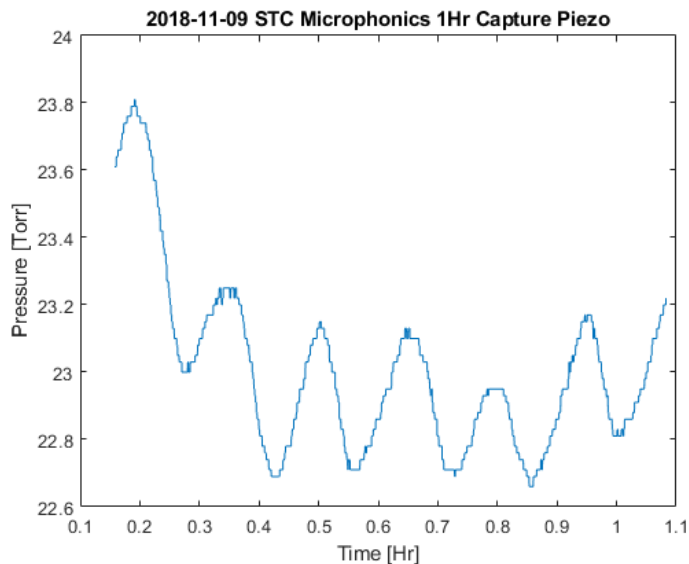
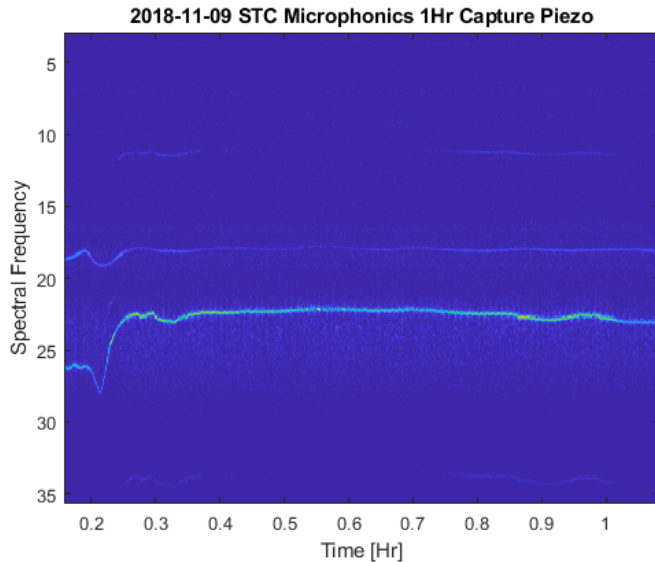
- Transfer function shows the eigenfrequencies of the cavity
- The noise spectrum shows there is a strong resonance speak around one of the eigenfrequencies





# Helium Pressure Variation

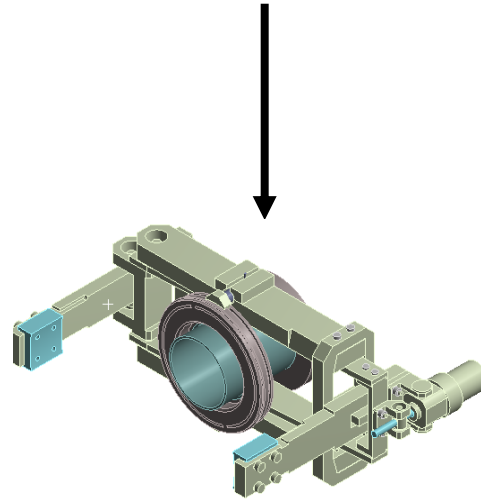
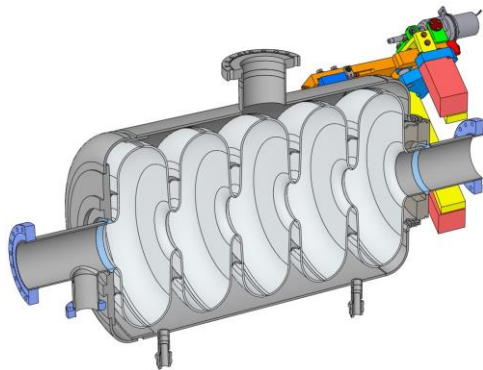
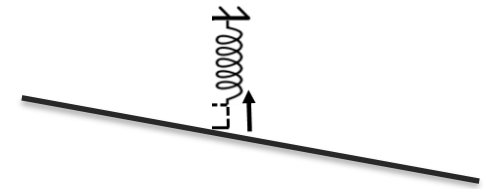
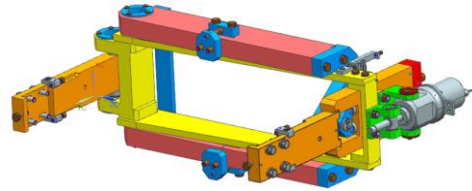
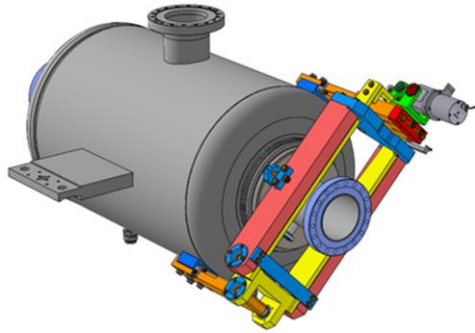
- Experience from Microphonics workgroup show that changing frequencies is related to cryogenic induced vibrations
- The only source changing frequency changing is from  $\sim 20$  Hz source (pressure related)
- Task List
  - Analyze the data for the cavity
  - Identify where the 200 Hz source is coming from



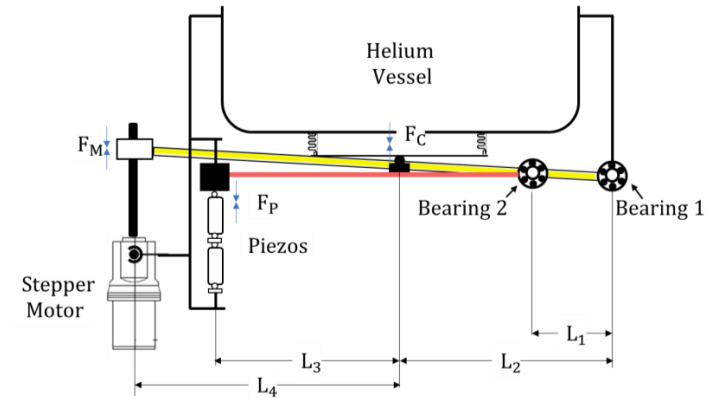
# Microphonics Control Strategies

- Provide sufficient reserve RF power to compensate for expected peak detuning levels
- Improve the regulation of the helium bath pressure  $\frac{df}{dp}$
- Reduce the sensitivity of the cavity resonant frequency to variations in the helium bath pressure, Lorentz Force, and external vibrations
- Minimize the acoustic energy transmitted to the cavity via external vibration sources.
- Actively damp cavity vibrations using a fast mechanical tuner driven by feedback from measurements of the cavity resonant frequency.

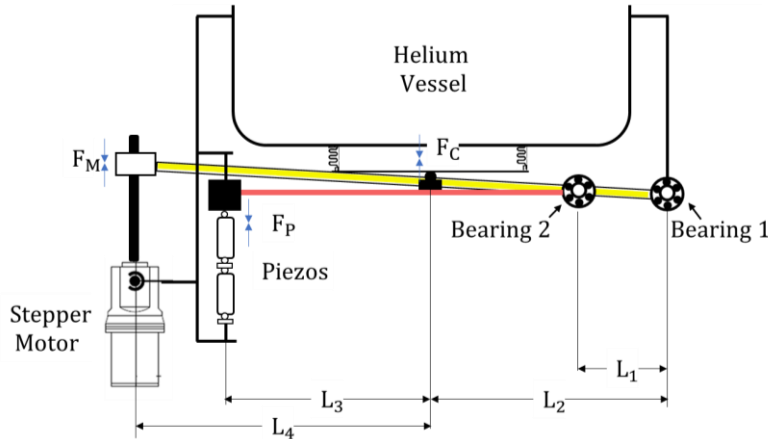
# Fast/Slow Lever Tuner



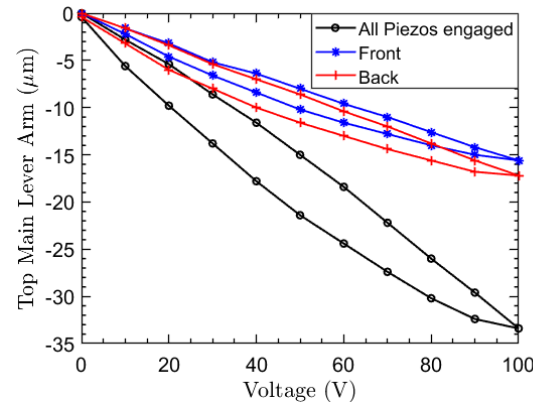
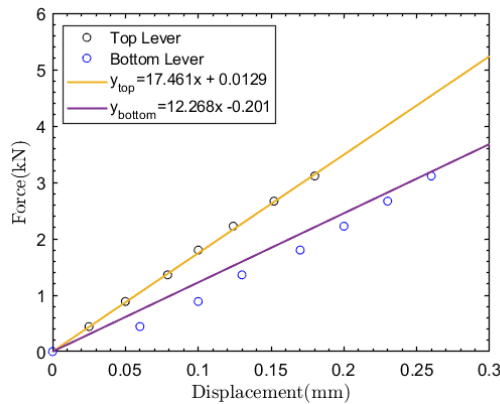
[3] S. Cheban

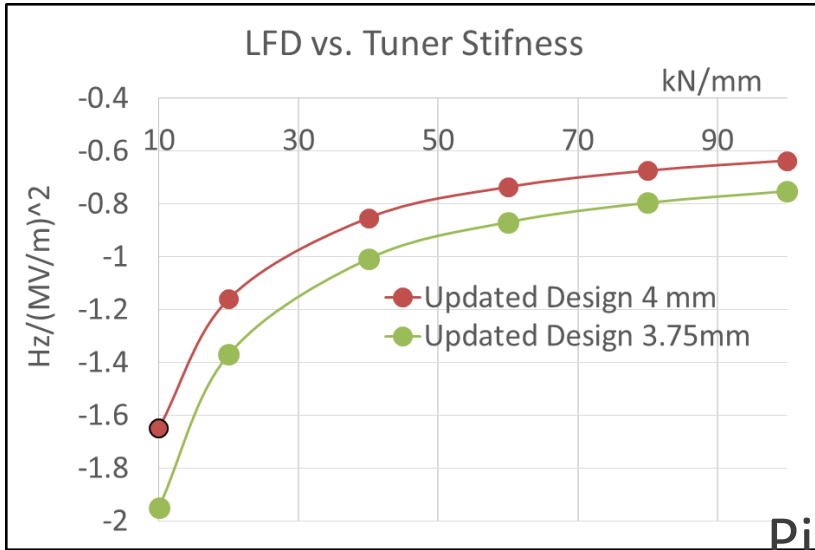


# Tuner Properties



- The tuner test show that the stiffness is  $\sim 30$  kN/mm
- Coarse tuning 200 kHz done by stepper motor
- Fine tuning 1 kHz done by piezos
- For a single piezo encapsulation the maximum detuning is  $\sim 430$  Hz and for all the piezos  $\sim 1.6$  kHz both at 100V

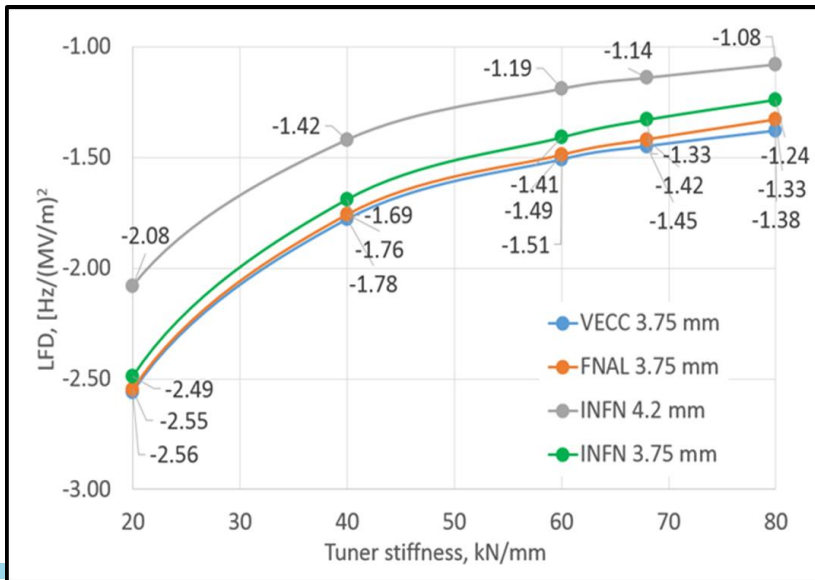




$$E_{ac} = 18.8 \text{ MV/m}$$

$$K_{LFD-Static} = 0.8 - 1.0$$

Piezo Actuator



$$E_{ac} = 16.9 \text{ MV/m}$$

$$K_{LFD-Static} = 1.4 - 1.8$$

# Outline

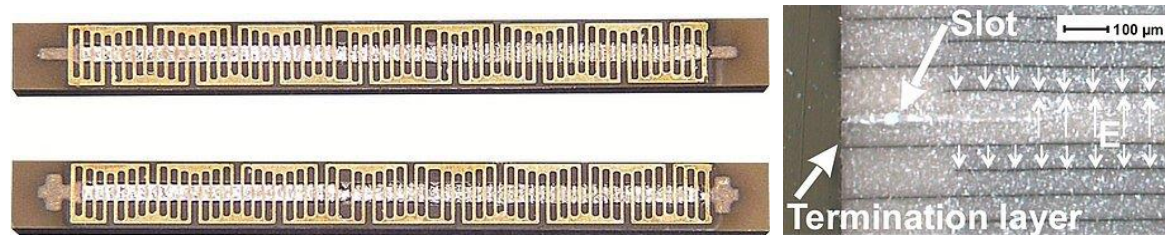
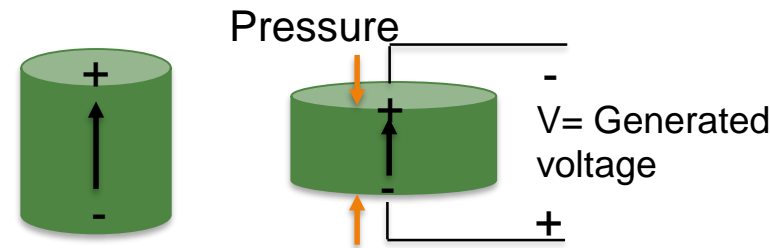
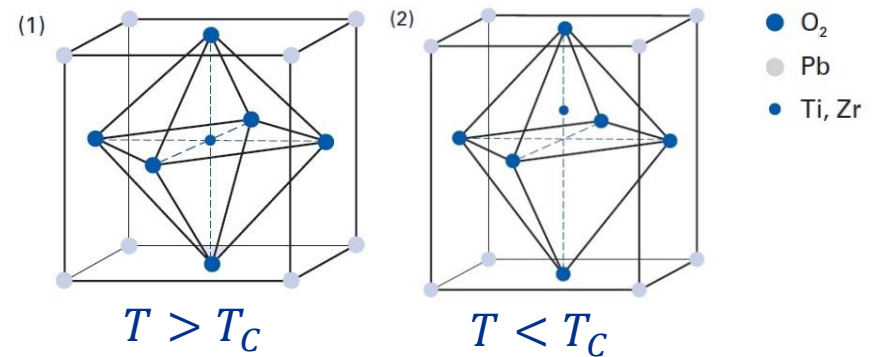
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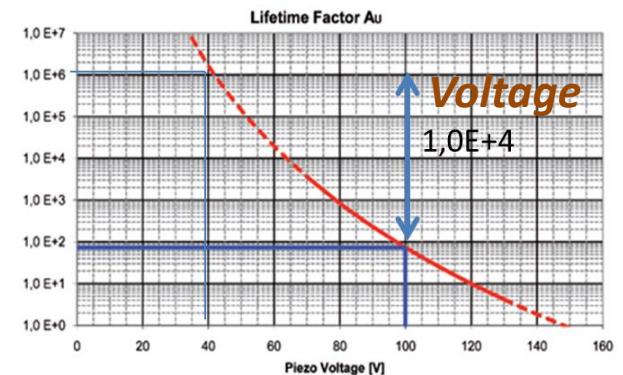
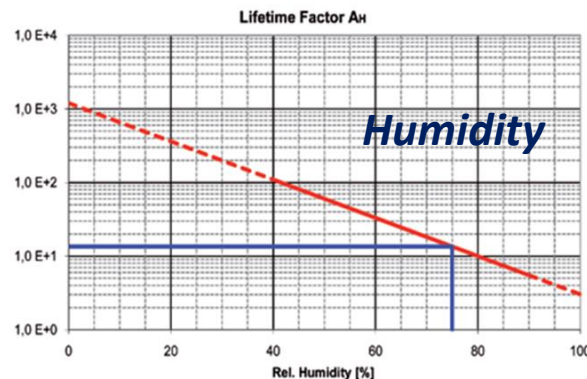
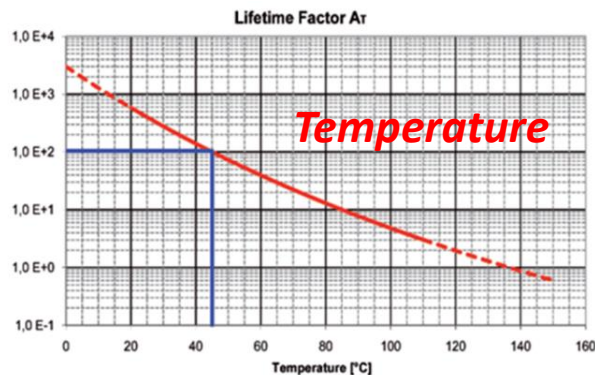
# Piezoelectric Effect

- Piezoelectric Effect
  - Occurs below curie temperature
  - Material used is lead zirconate titanate (PZT)
  - Obtained after poled
  - Applying voltage will elongate or shrink the piezo depending on the sign
  - Applying pressure will generate voltage
- Piezo capsule built with two 18 mm long piezo stacks made



# Piezo Lifetime R&D Program

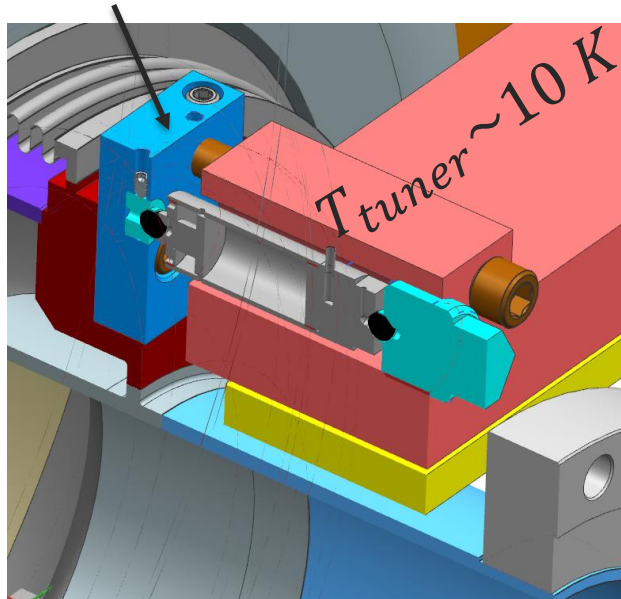
- Factors affecting lifetime
  - Temperature, Humidity, Voltage
  - Shear Forces
  - Radiation damage
  - Dielectric losses
- Decreasing operational voltage from 100V to 40V will increase lifetime in 10,000 time.
- Accelerated life time test for piezos for LCLS-II show run for  $2.5 * 10^{10}$  pulses (or 125% of LCLS II expected lifetime) without any degradation or overheating [Pischalnikov, et al]



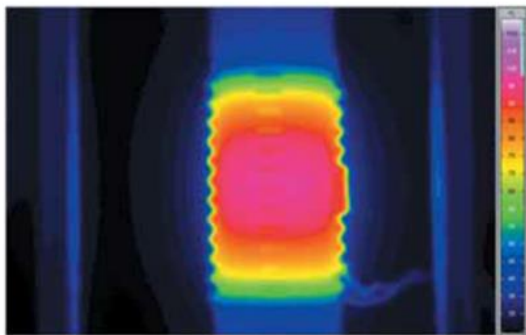


# Piezo Reliability

$T_C = 2 \text{ K}$

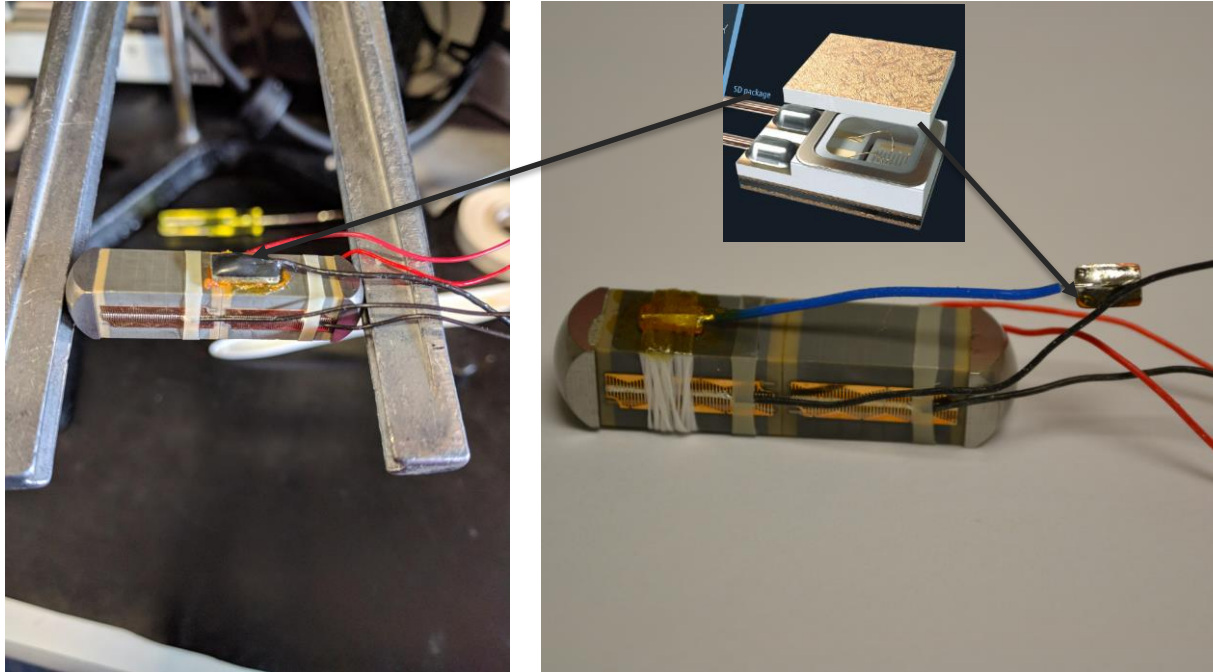


- Dielectric losses in the ceramic creates heating
- PIP-II will require the piezo to operate at high voltage
- Outcome: Test whether piezo can withstand high dynamic operation



*Fig. 5.1: Thermal image of a dynamically cycled high voltage actuator, clamped at its end faces. Environment: ambient air convection. Notice the cooling effect at the end-faces due to the clamping mechanics*

# Changes to Experiment



- Cernox sensor attached directly to the piezo stack
- Previously a thin wire with thin copper plates were used
- Improve reliability of temperature readings

# Experimental Setup



- Use geophones to verify piezo is being excited
- The setup will be dunked in a LHe dewar
- Task List:
  - Improve LabView data acquisition program
  - Verify all wires are connected correctly
  - Test at Liquid Nitrogen
  - Prove piezo will survive high dynamic pulse operation

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# Harmonic Oscillator

$$\Delta\ddot{\omega}_\mu(t) + \frac{2}{\tau_\mu} \Delta\dot{\omega}_\mu(t) + \Omega_\mu^2 \Delta\omega_\mu(t) = k_\mu^{\text{LFD}} \Omega_\mu^2 E^2(t) + n_\mu^{\text{Piezo}} \Omega_\mu^2 N(t) + m_\mu \Omega_\mu^2 M(t) \quad (1)$$

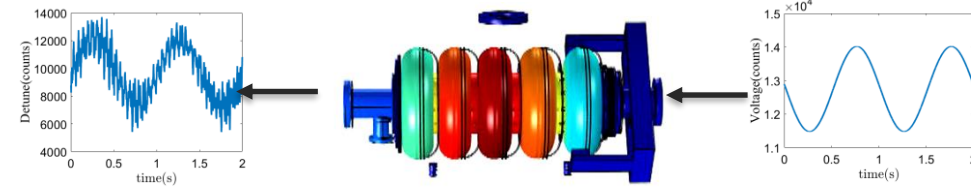
$$\Delta\omega(t) = \sum_{\mu=1}^{\infty} \Delta\omega_\mu(t)$$

- $\Delta\omega_\mu$  detuning of the mode, detuning frequencies  $\Omega_\mu$ , and the coupling ( $k_\mu^{\text{LFD}}, n_\mu^{\text{Piezo}}$ )
- To dampen a mode, the piezo drive is  $N(t) \propto \Delta\dot{\omega}_\mu(t)$

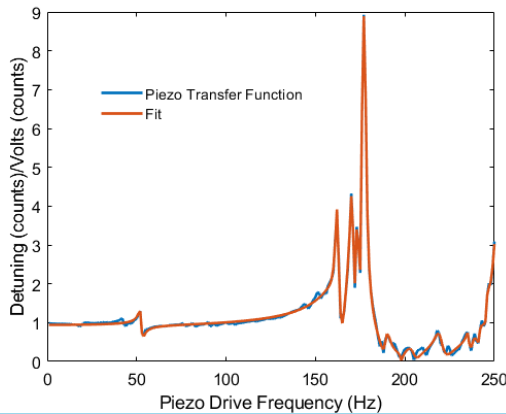
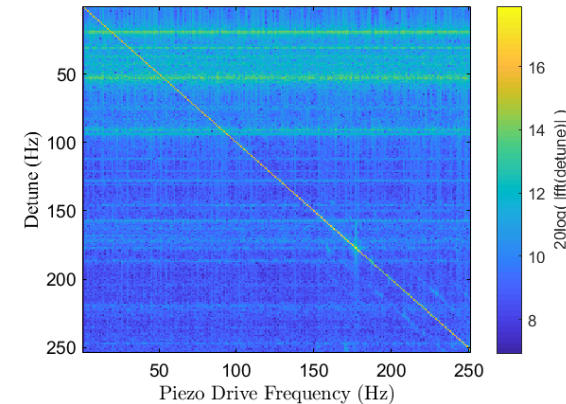
# Transfer Function

## Response Detuning

## Piezo Drive

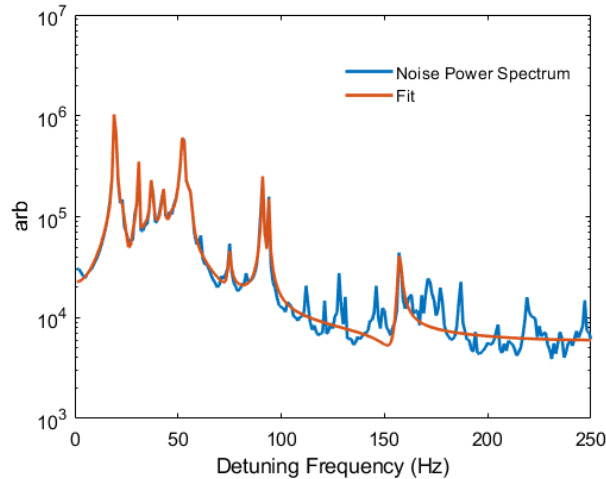


- Response of the cavity to a stimulus from the signal from the piezo
- A low order approximation can be obtained using the Kalman-Ho identification algorithm
- From the transfer function we want to obtain  $Q_{\mu} = \frac{1}{\tau_{\mu}}$ , the detuning frequencies  $\Omega_{\mu}$ , and the coupling  $k_{\mu}$

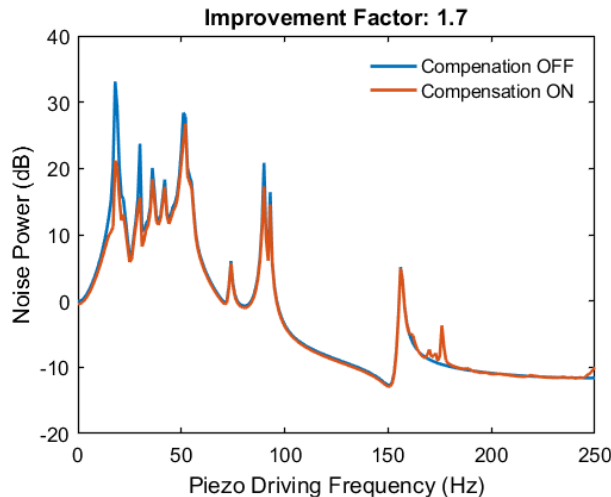


# Microphonics Noise Spectrum

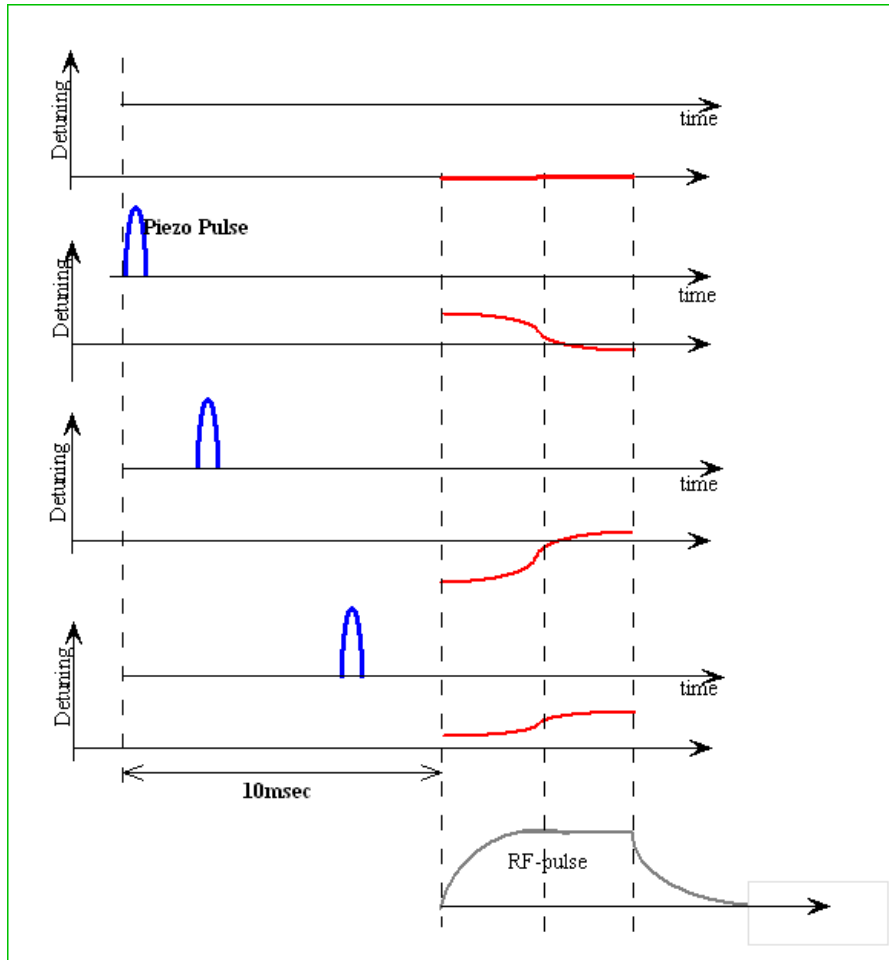
## Background Noise



- Frequencies and bandwidths for microphonics can be determined using a combination of Kolmogorov Spectral Factorization and Kalman-Ho algorithm



# Response Matrix



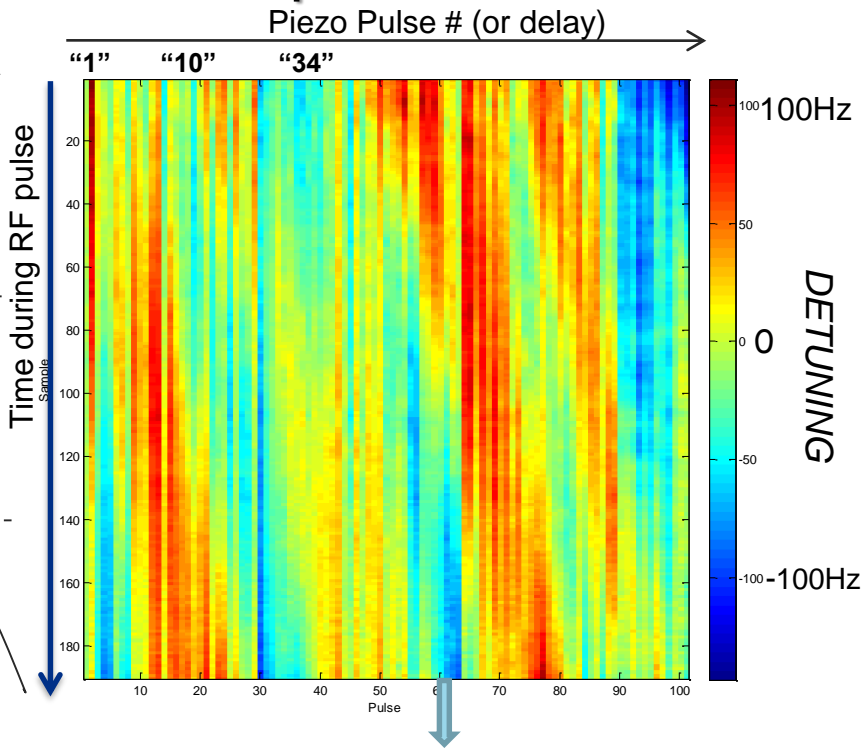
- Piezo/cavity excited by sequence of small (several volts) narrow (1-2ms) pulses at various delay.
- The forward, probe and reflected RF waveform recorded at each delay and used to calculate detuning. [Response Matrix]

“W. Schappert, Y.Pischalnikov, “Adaptive Lorentz Force Detuning Compensation”. Fermilab Preprint –TM-2476-TD



# Adaptive Least Square(LS) LFD Algorithm

## Response Matrix



- Invert the response matrix and determine combination of pulses needed to cancel out the LFD using LS
- Any part of RF pulse could selected for Compensation: "Fill+FlatTop" only "FlatTop"

"W. Schappert, Y.Pischalnikov, "Adaptive Lorentz Force Detuning Compensation". Fermilab Preprint –TM-2476-TD

# Summary

- Microphonics
  - I learned about the various sources that contribute to the detuning
  - The pinpointing the sources is not easy
- Fast/Slow Tuner
  - Measured the tuner stiffness and piezo stroke
- Resonance Control
  - I learned algorithm to model the system and obtain the modal frequencies
  - Resonance control algorithm studies are ongoing

# Plan

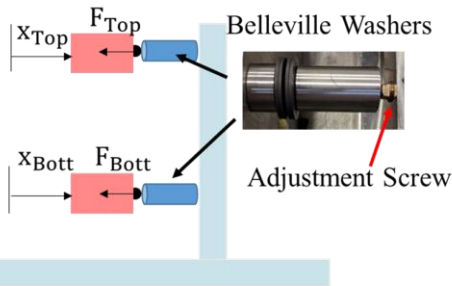
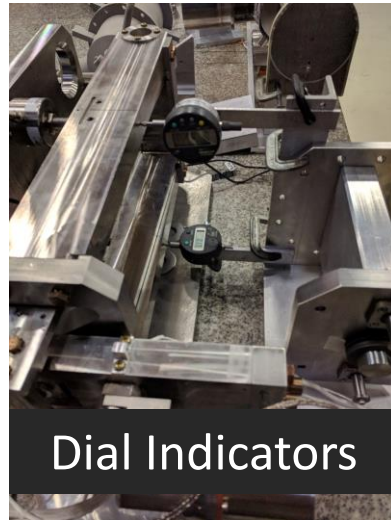
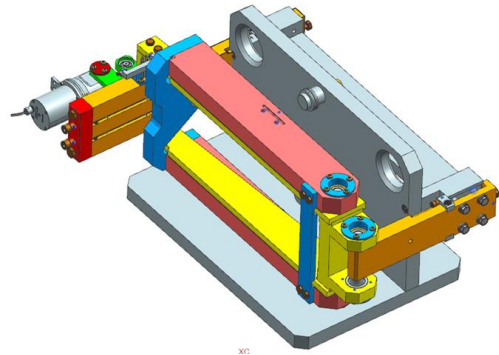
- 2019
  - Finish Piezo Experiment
  - Microphonics studies
  - Work on calculating the detuning of the cavity via probe, reversed, and forward signal
  - Work on resonance control algorithms
    - Adaptability with change in frequency of modes
- 2020
  - Microphonics studies
  - Work on resonance control algorithms
    - Adaptability with change in frequency of modes
  - Write Thesis
- 2021
  - Defend thesis

# Acknowledgements

- Peter Ostroumov
- Slava Yakovlev
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  - Yuriy Pischalnikov
  - Warren Schappert
  - Jeremiah Holzbauer
  - J.C. Yun

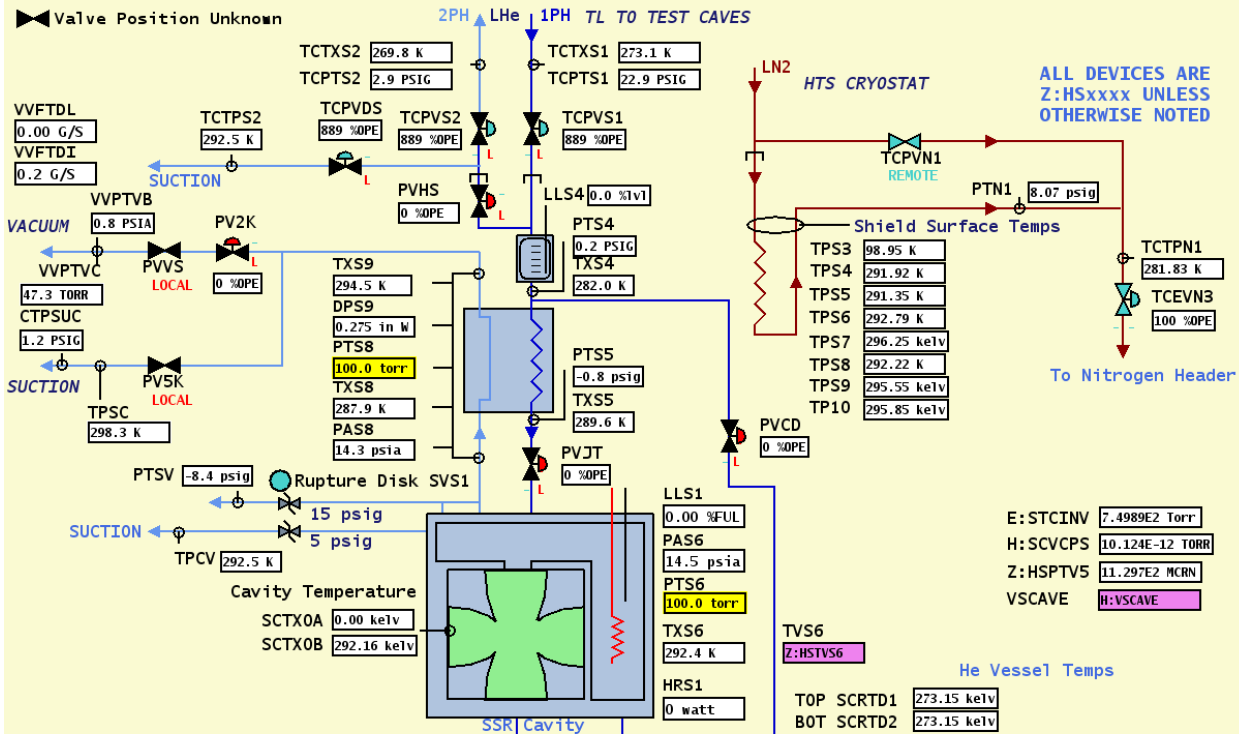
# Back Up

# Stiffness/Piezo Stroke Setup



- The stiffness is measured by applying a force to the main lever arm via the adjustment screw and recording the displacement.
- Cavity simulated with Belleville washers (4.9kN/mm)
- There is error in the measurement since the stand is not stiff enough

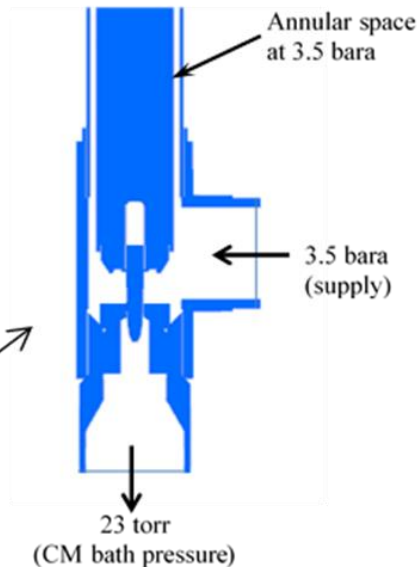
Valve Position Unknown



# Thermal Acoustic Oscillations (TAOs)

## Joule-Thomson (JT) Valve

Room  
Temperature



2 K

- Lessons from Microphonics Working Group
- TAOs are an oscillatory instability that occur in long gas tubes with a large temperature gradient
- The temperature differential drives an acoustic like oscillation, where the cold cryogenic fluid rapidly moves up the warm end tube, warms, expands and drives back down to the cold end.
- Signs of TAOs:
  1. High heat loads
  2. Ice/condensation at warm side
  3. Mechanical vibration

[1] Microphonics working group



# Accelerated Piezo Lifetime test at FNAL

Designated facility at FNAL to test piezo at the CM environment (insulated vacuum and LHe)



Insert into LHe dewar with cryo/vacuum and electrical connections

Capsules (up to 5) with Piezo-stacks Mounted on the copper block



- RTD (Cernox) –to mount on Piezos  
- Geophones (to monitor piezo stroke)



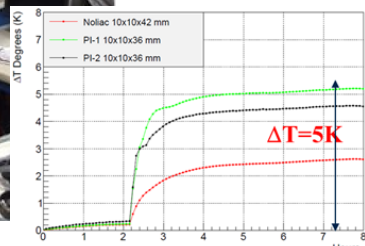
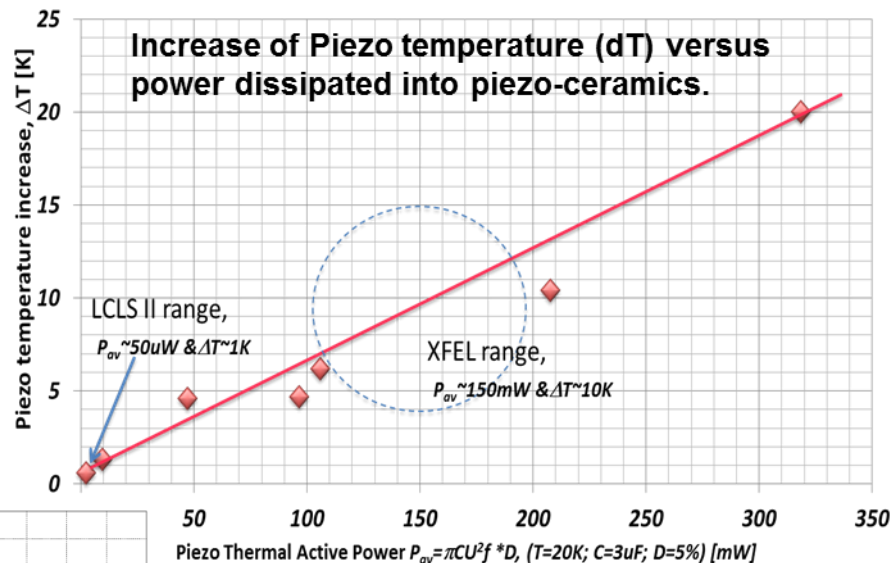
Accelerated piezo-stack lifetime test

$2 \cdot 10^{10}$  pulses ( $V_{pp} = 2V$  &  $F = 40Hz$ )

20years  $\rightarrow$  2 month (40Hz $\rightarrow$ 5kHz)

LCLS II ---  $P_{av} \sim 50\mu W$  (40Hz, 2V)

During ALT at 5kHz  $P_{av} \sim 6mW$  ( $\Delta T \sim 2K$ )



\*Slide Y, Pischalnikov

**LCLS II Tuner piezo-stacks run for  $2.5 \cdot 10^{10}$  pulses (or 125% of LCLS II expected lifetime) without any degradation or overheating**