

COMPASS iFDAQ Software

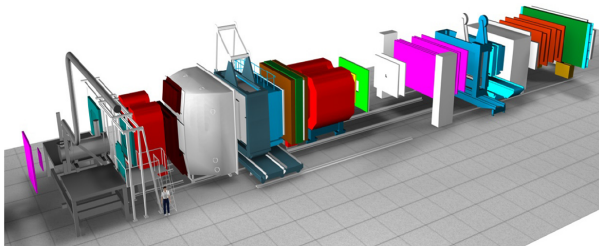
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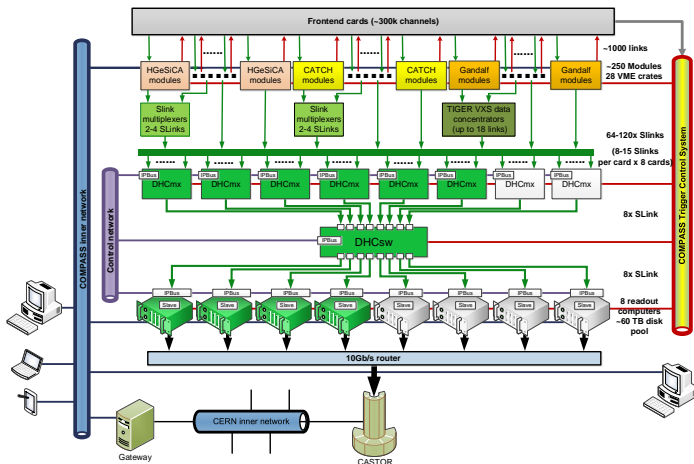
COMPASS experiment

- ▶ Fixed target experiment at SPS accelerator at CERN
- ▶ Study of hadron structure and hadron spectroscopy with high intensity muon and hadron beams
- ▶ Data-taking started in 2002
- ▶ Trigger rate up to 50 kHz, average event size up to 50 kB (not at the same time)
- ▶ In spill data rate 1.5 GB/s and sustained data rate 500 MB/s



Hardware Structure

- ▶ Hardware based E.B.
- ▶ Data concentrated by 6 (up to 8) DAQ modules with multiplexer firmware
- ▶ Distribution to 4 (up to 8) readout computers by DAQ module switch firmware
- ▶ Full events received by servers
- ▶ Consistency check at many layers
- ▶ Events checked and transferred to DATE data format
- ▶ Easy to add new data source

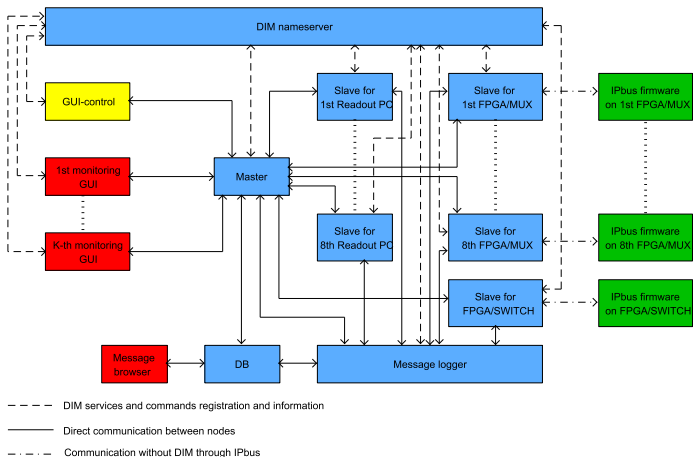


Used Software Technologies

- ▶ C++, Python
- ▶ Qt framework
- ▶ DIM (Distributed Information Management System)
- ▶ DIALOG library
- ▶ IPbus suite for communication with FPGA cards
- ▶ MySQL
- ▶ PHP, JavaScript
- ▶ Zabbix

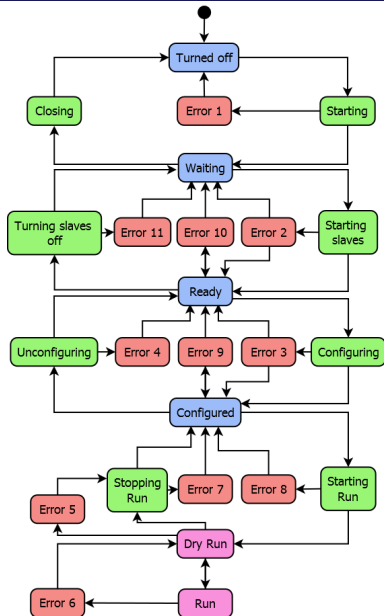
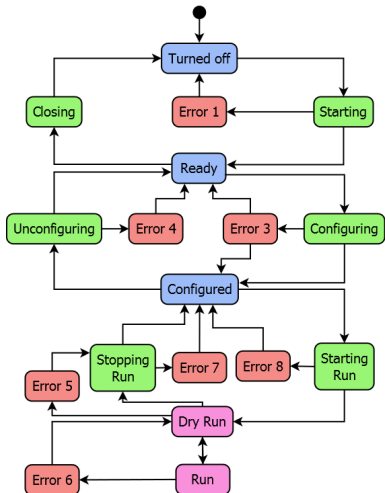
Software Structure

- ▶ Runcontrol GUI is a graphical user interface
- ▶ Master is a main control process
- ▶ Slave-readout readouts and verifies the data
- ▶ Slave-control monitors and controls the FPGA cards
- ▶ MessageLogger stores informative and error messages into the database
- ▶ MessageBrowser provides an intuitive access to messages stored in the database



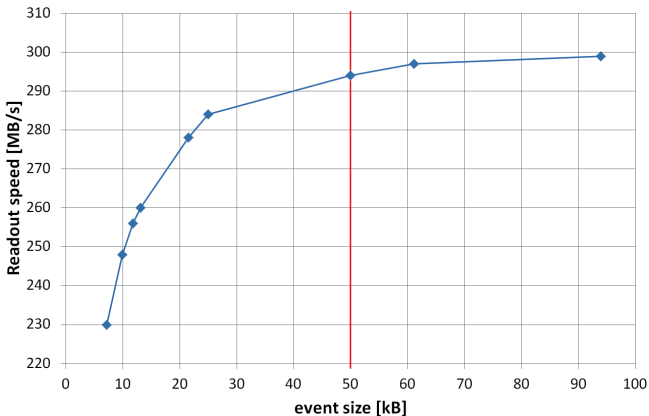
State machine

- Well defined states - system with self-repair capability



Maximum Data Readout Performance

- ▶ Currently limited by SWITCH firmware to 100 MB/s per RE if 4 RE connected
- ▶ If 2 RE connected to not-shared ports, readout speed of up to 150 MB/s per RE, $\leq 12\%$ CPU usage



DIM I – Distributed Information Management System

- ▶ Developed at CERN in 1993, still with support
- ▶ Design requirements
 - ▶ Efficient communication mechanism – asynchronous behavior, sending and receiving asap
 - ▶ Uniformity – all processes use the same communication mechanism
 - ▶ Transparency – any running process should be able to communicate with any other process
 - ▶ Reliability and robustness – system recovery in a self-recoverable manner from error situations
- ▶ It uses UDP protocol for message transmission

DIM II – Usage in iFDAQ

- ▶ Fully incorporated to all processes for the runs 2014 and 2015
- ▶ DIM problems
 - ▶ Occasional message truncation or complete loss of the message
 - ▶ As a consequence of that, processes crashed without any obvious reason (especially Master process)
- ▶ DIM library replaced by DIALOG library
- ▶ DIM library can not be completely avoided (still partially present)
 - ▶ VME computers have only 64 MB memory → we can not install Qt framework there
 - ▶ DIALOG library is implemented in Qt framework

DIALOG Library I

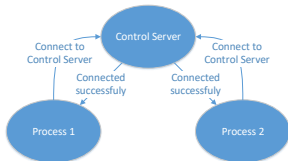
- ▶ Replacement of DIM Library
- ▶ It is implemented in Qt framework
- ▶ Dialog means conversation, talk or speech (**D** – distributed, **I** – inter-process, **A** – asynchronous, **L** – library, **O** – open, **G** – general)
- ▶ Design requirements similar to DIM Library
- ▶ Communication based on the publish/subscribe method
- ▶ It uses TCP/IP protocol for message transmission

DIALOG Library II

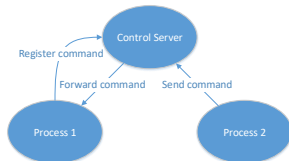
- ▶ Services
 - ▶ A service is a set of data of any type and size with a unique name
 - ▶ Server/Client mechanism – server publishes data to several clients
- ▶ Commands
 - ▶ Process registers command with a non-unique name it is willing to accept
 - ▶ One process can control another one via command
- ▶ Implementation
 - ▶ The Control Server – keeping an up-to-date list of all the processes, services and commands
 - ▶ Providers – a process providing services and commands it is willing to accept
 - ▶ Subscribers – a process specifying the service name it is interested in and requesting for it
 - ▶ Any process can be a provider and a subscriber at the same time

DIALOG Library III - Scenarios

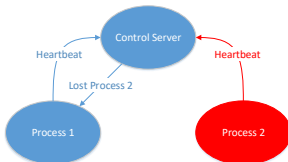
Connection to the Control Server



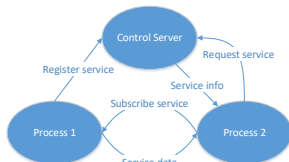
Commands



Heartbeats



Services



DIALOG Online Monitoring

DIALOG CommunicationGUI

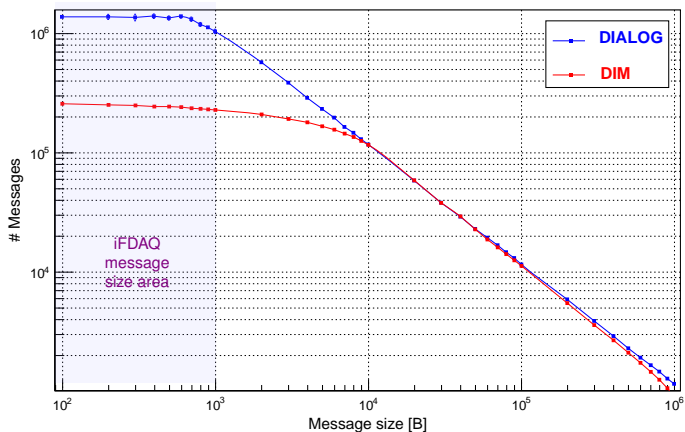
Name of Process: Address: Provided service: Command: Search
PID: Port: Subscribed service: Reset

	Name of Process	Address	Port	PID	Provided services	Subscribed services	Commands
1	GUI	pccorc31.cern.ch	54214	4961	Show	Show	Show
2	Master	pccore15.cern.ch	48764	1033	Show	Show	Show
3	MSGBrowser	pccorc21.cern.ch	35666	24233	Show	Show	Show
4	MSGLogger	pccore15.cern.ch	58722	1034	Show	Show	Show
5	SC_RE11	pccore15.cern.ch	35647	1760	Show	Show	Show
6	SC_RE12	pccore15.cern.ch	35724	1900	Show	Show	Show
7	SC_RE13	pccore15.cern.ch	46410	2390	Show	Show	Show
8	SC_RE14	pccore15.cern.ch	42652	2320	Show	Show	Show
9	SMC01_RE11	pccore15.cern.ch	42630	1830	Show	Show	Show
10	SMC02_RE12	pccore15.cern.ch	47699	1970	Show	Show	Show
11	SMC03_RE13	pccore15.cern.ch	52851	2040	Show	Show	Show
12	SMC04_RE14	pccore15.cern.ch	41940	2110	Show	Show	Show
13	SMC05_RE15	pccore15.cern.ch	51730	2250	Show	Show	Show
14	SMC06_RE15	pccore15.cern.ch	58676	2460	Show	Show	Show
15	SR_RE11	pccore11.cern.ch	58103	22301	Show	Show	Show

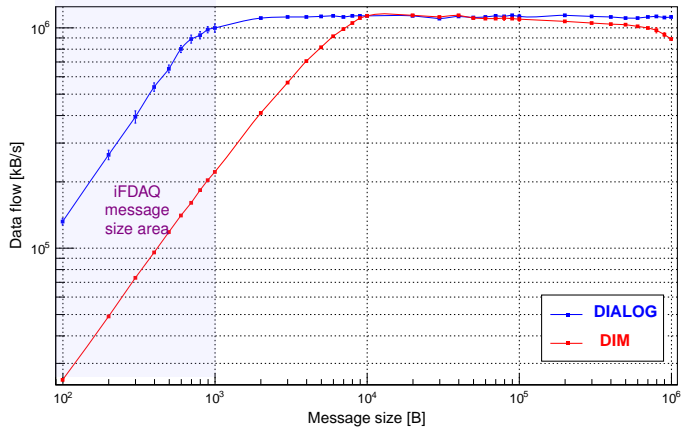
Performance Test I – Test Setup

- ▶ DIALOG and DIM performance are measured and compared in two plots
 - ▶ Number of messages – how many messages can be delivered to one single process in 1 second
 - ▶ Data flow – how many bytes can be delivered to one single process in 1 second
- ▶ 25 slaves (17 slave-control, 8 slave-readout) send status to Master process → the iFDAQ full setup
- ▶ The test is conducted for different message sizes and for each message size is conducted five times to obtain the sufficient statistics
- ▶ The network bandwidth is 10 Gbps for the test
 - ▶ We can expect the maximum data rate ~ 1.2 GB/s (throughput)
 - ▶ The network bandwidth is not saturated by anything else during test
- ▶ Correct spreading of slaves among machines
 - ▶ Message sent by process 1 to process 2 running on the same machine is sent directly and it is not going through the network at all
 - ▶ The test results would have been even above the network bandwidth

Performance Test II – Number of Messages



Performance Test III – Data Flow



DAQ Debugger I

- ▶ Library for the iFDAQ error detection
- ▶ Fully incorporated to all processes during the run 2016 and 2017
- ▶ Design requirements
 - ▶ The integration to running system requires interface for an easy use
 - ▶ It does not affect the process performance
 - ▶ It does not increase load on readout engine computers
 - ▶ It provides with reports in `/tmp` folder containing stack trace of all threads and memory dump

DAQ Debugger II

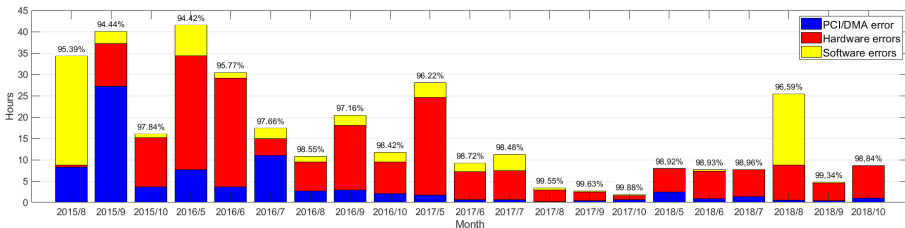
- ▶ Main goal is to produce a report of the process crash
- ▶ Based on catching of system signals (SIGSEGV, SIGABRT, etc.)
 - ▶ The system signal is caught and forwarded to a signal handler in the DAQ Debugger
 - ▶ The memory dump is produced and stored
 - ▶ The whole stack trace for each thread is generated with file names and code line numbers
 - ▶ The report containing the caught signal and stack trace for each thread is created in `/tmp` folder
 - ▶ The process is exiting with the caught signal
- ▶ Reports are investigated by iFDAQ experts
- ▶ Problem understanding → the fix is released and tested

DAQ Debugger III – Implementation

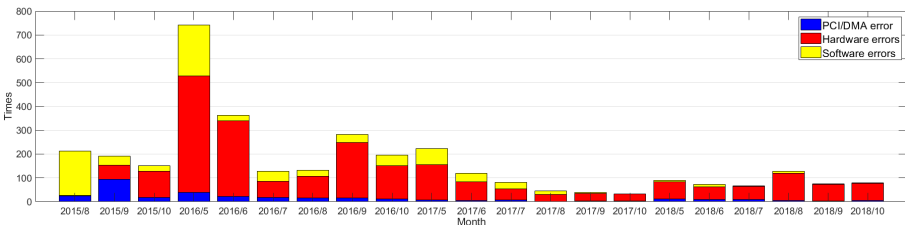
- ▶ `DAQDebugger::init(processName)` to initialize
- ▶ Crash procedure
 - ▶ The system signal is caught in the crashed thread
 - ▶ All remaining threads are immediately suspended
 - ▶ Store memory dump
 - ▶ Get stack trace of the crashed thread
 - ▶ Get stack traces of suspended threads
 - ▶ The crashed thread (whole process) is exiting with the caught signal
- ▶ Using POSIX defining a standard threading library API (suspend/resume signals)
- ▶ Using `backtrace`, `backtrace_symbols` and `addr2line` to create a report
- ▶ Using `gcore` for memory dump storage



iFDAQ Stability



Error hours per month



Error count per month



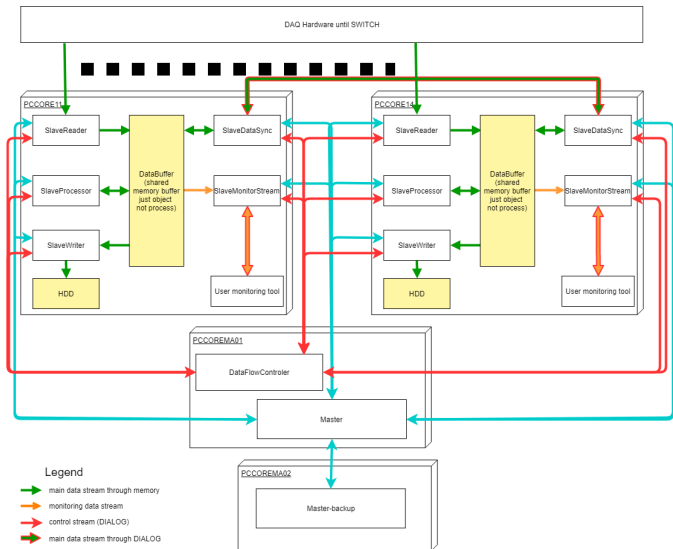
Present features

- ▶ Continuously running DAQ
- ▶ Deployment tool
- ▶ API
- ▶ Text User Interface
- ▶ Integrated logbook
- ▶ Web-based checklist

Future development

- ▶ Load distribution
- ▶ Process redundancy
- ▶ "Space" for analysis and checks
- ▶ Data quality assessment
- ▶ Software event building

- ▶ Fragmentation of main readout process to several sub-processes
- ▶ Intelligent scheduling
- ▶ Filtration/High level trigger possibilities
- ▶ Software event building
- ▶ Data sharing
- ▶ Configurable storage



Conclusion

- ▶ Own communication library DIALOG
- ▶ Internal DAQ Debugger
- ▶ iFDAQ UpTime is around 99%
- ▶ TUI - for scripting
- ▶ Easy to operate, but possible to tune by experts
- ▶ possible extension for higher rates and software event building
- ▶ Team of skillful developers created - 1x Postdoc, 3x PhD, 2x Master, 2x Bachelor students

The End





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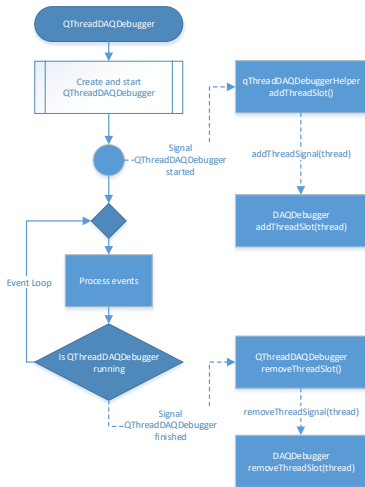
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DAQ Debugger IV – Thread Life Cycle

- ▶ The `QThreadDAQDebugger` object inheriting from `QThread` object
- ▶ To control thread via POSIX, thread ID is necessary to obtain using `QThreadDAQDebuggerHelper`
- ▶ Registration of thread in DAQ Debugger by `addThreadSlot(thread)` method
- ▶ Standard thread execution with processing of events until the thread finishes
- ▶ `QThreadDAQDebugger` object finishes its execution
- ▶ Unregistration of thread in DAQ Debugger by `removeThreadSlot(thread)` method
- ▶ For simplicity reasons, the thread crash is not depicted in the diagram



DAQ Debugger V – Before Process Crash

- ▶ DAQ Debugger is a part of a process and standing in the background of a running process
- ▶ A process is running smoothly → the DAQ Debugger does not take any action → no effect on the process performance and no load increase on readout engines
- ▶ The system signals are registered, the process continues its execution
- ▶ Once the crash of process occurs, the DAQ Debugger handles it

DAQ Debugger VI – Process Crash

- ▶ Process crash → the system signal is emitted
- ▶ It is caught by the signal handler of crashed thread in the DAQ Debugger
- ▶ The crashed thread sends the suspend signal to all remaining threads
- ▶ The memory dump is produced and stored
- ▶ The report file is created and open for writing
- ▶ The crashed thread writes its stack trace to the file

DAQ Debugger VI – Process Crash

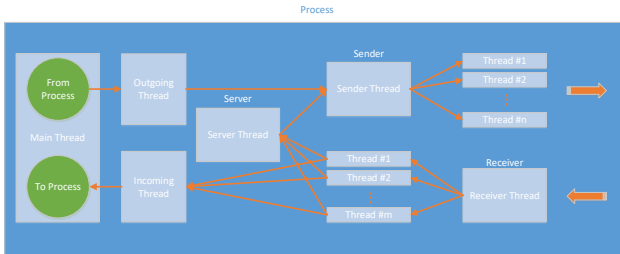
- ▶ The crashed thread sends the resume signal to first suspended thread and the crashed thread itself is suspended
- ▶ The resumed thread writes its stack trace to the file, then sends the resume signal to the crashed thread and is suspended again
- ▶ The resumed crashed thread sends the resume signal to second thread and it is again suspended
- ▶ The second resumed thread writes its stack trace to the file, then sends the resume signal to the crashed thread and is suspended again

DAQ Debugger VI – Process Crash

- ▶ It continues in this way to the last suspended thread
- ▶ The resumed crashed thread (resumed by the resume signal sent from $(n - 1)$ -th thread) sends the resume signal to n -th thread and it is again suspended
- ▶ The n -th resumed thread writes its stack trace to the file, then sends the resume signal to the crashed thread and is suspended again
- ▶ This suspend/resume procedure ensures the serial writing to file and proper thread control
- ▶ The report file is closed and process is exiting with the caught signal in the crashed thread

DIALOG Library IV - Process Threads

- ▶ Message types are distinguished by message header
- ▶ The Sender dispatches messages among $n \in \mathbb{N}$ threads
- ▶ $n \in \mathbb{N}$ threads are establishing connections to other processes, writing data to sockets and keeping sockets open until timeout
- ▶ Open socket, pointers to messages, sending as soon as possible → speed up the performance and reduce the latency significantly
- ▶ The Receiver dispatches a new socket descriptor to one of $m \in \mathbb{N}$ threads
- ▶ $m \in \mathbb{N}$ threads are responsible for reading data out from sockets
- ▶ The sockets are kept open until they are closed by sender process



DIALOG Library V - from Process 1 to Process 2

- ▶ If the connection is not yet established, the object socket is created and opened in Process 1
- ▶ The Receiver receives the socket descriptor trying to connect to Process 2
- ▶ Socket objects exist on both sides till timeout, process crash or process termination
- ▶ The open socket is used only for one direction connection

