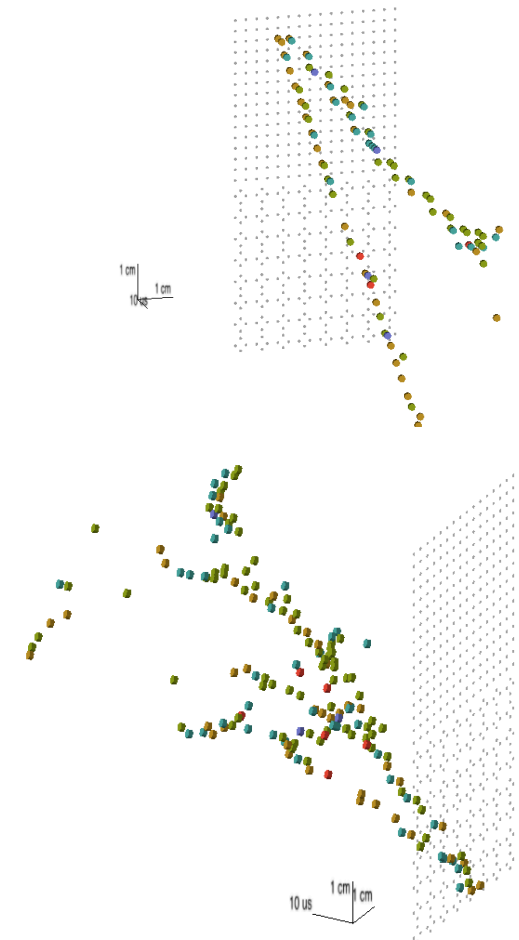
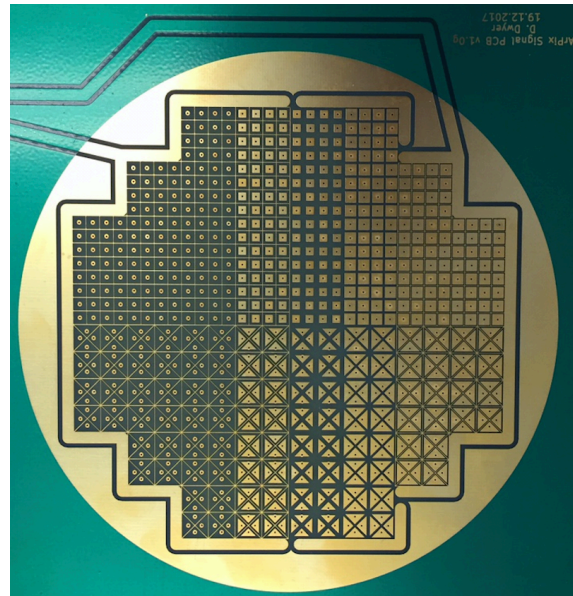
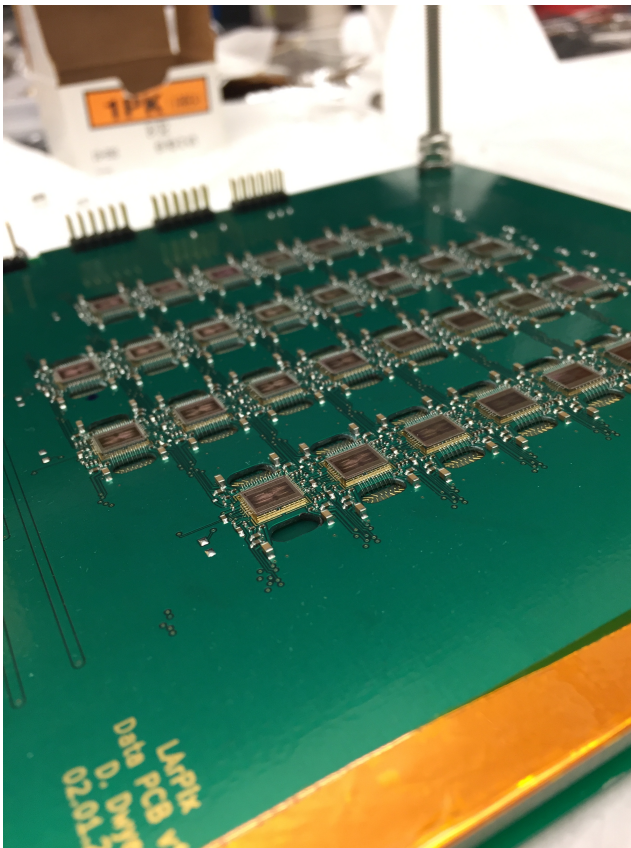




# LArPix Design Details

Dan Dwyer (LBNL)

May 16, 2019





# Introduction

## **Important that LArPix-v2 satisfies requirements for:**

- Assembly, testing, and operation of the ArgonCube 2x2 Demonstrator
- Input for the DUNE Near Detector Technical Design Report

## **This talk:**

- Examine expected signal characteristics
- Describe LArPix-v2 analog and digital requirements
- Discuss modifications that facilitate assembly and operation

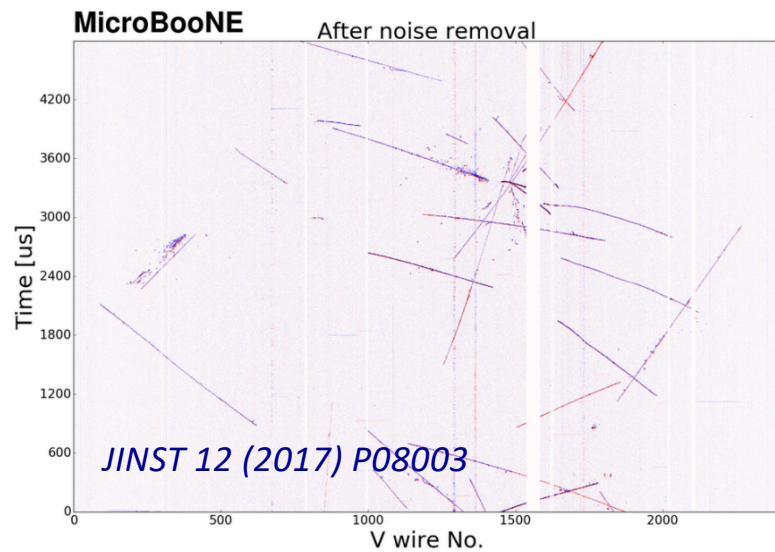


# LArTPC Signals

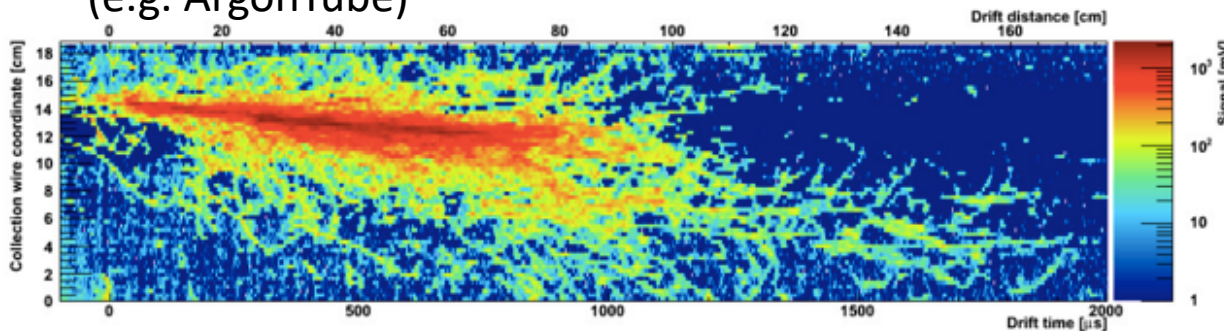
## Primary signals of interest for ArgonCube 2x2 Demonstrator:

### Operation on surface at Bern:

- Mostly MIP cosmic rays:

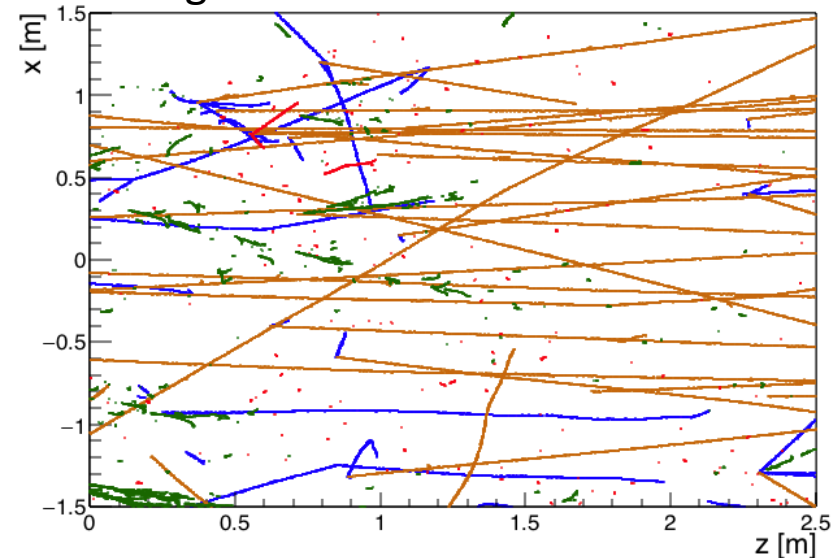


- Occasional intense cosmic shower (e.g. ArgonTube)



### Operation underground at FNAL:

- Mostly neutrino interactions (mix of MIP tracks and small showers)
- Signals occur in bursts at  $\sim 1\text{Hz}$



Example:

One simulated DUNE beam spill @ 2MW



# LArTPC Spatial Resolution

## Many aspects of design driven by desired LArTPC 3D spatial resolution:

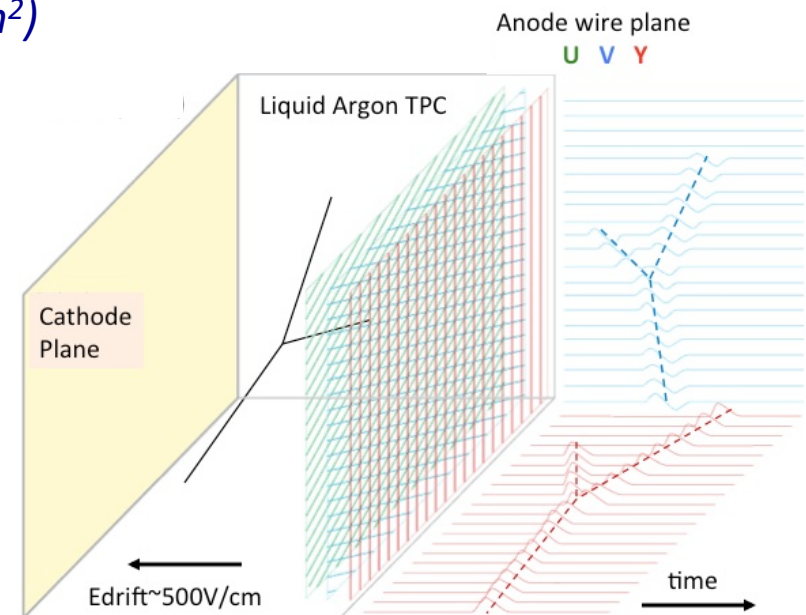
- Resolutions of 3mm to 5mm in 3D are the regime of interest for DUNE signals.
- Above 5mm, clear degradation of physics performance for signals of interest
- Below 3mm, performance gain unclear. Electron diffusion during drift ( $\sim 1 \text{ mm}/\sqrt{\text{Vm}}$ ) will eventually limit gains.

## Anode spatial resolution:

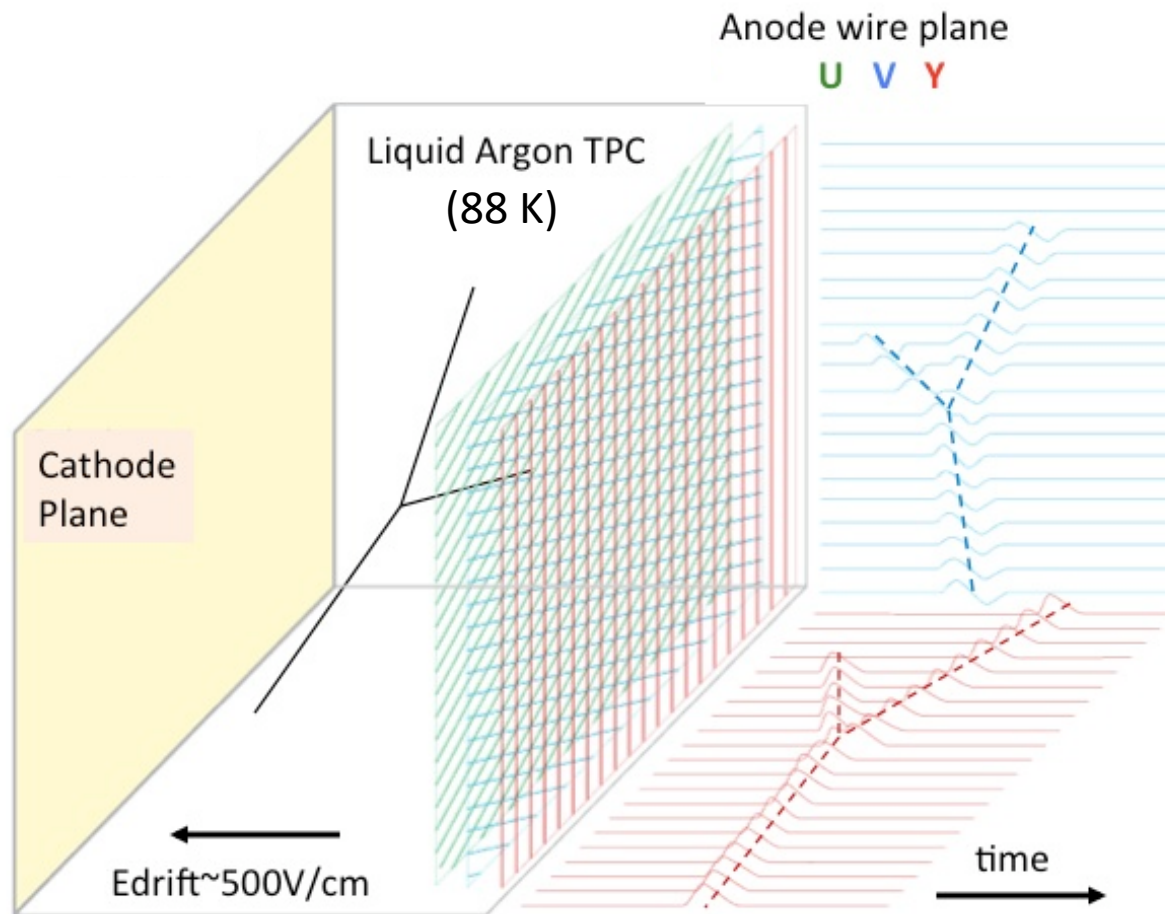
- Determined by pixel spacing.
- LArPix-v1 pixel system: 3mm pixel spacing
- ArgonCube 2x2 Demonstrator: Targeting 4mm spacing.  
→ *Determines channel density ( $\sim 62k \text{ channels}/\text{m}^2$ )*

## Anode time resolution:

- Time resolution of anode readout determines spatial resolution along direction of drift.
- Drift velocity varies with drift field, reference:  $1.6 \text{ mm}/\mu\text{s}$  at  $500 \text{ V/cm}$
- 3mm-5mm resolution corresponds to 2-3  $\mu\text{s}$  'binning' of incoming charge.  
→ *Determines channel bandwidth, timing*



# LArTPC Signals



## Ionization electrons:

23.6 eV per  $e^-$   
 $\rightarrow \sim 42,000 e^- / \text{MeV}$

## Recombination loss: @500V/cm

MIP:  $\sim 30\%$

Proton:  $\sim 70\%$

## Drift velocity: @500V/cm

$\sim 1.6 \text{ mm}/\mu\text{s}$

## Drift loss:

Few-% to  $\sim 50\%$ , depending on LAr purity and drift distance.

## Charge signals: (approx.)

MIP:  $\sim 20\text{k } e^-$

Multi-proton:  $\sim 250\text{k } e^-$   
 (assuming 4mm pitch)

## Standard detection technique: Wire planes

Provide three views of interaction,  
 each 1-D vs. Z (i.e. drift direction)

[arXiv:1107.5112](https://arxiv.org/abs/1107.5112)

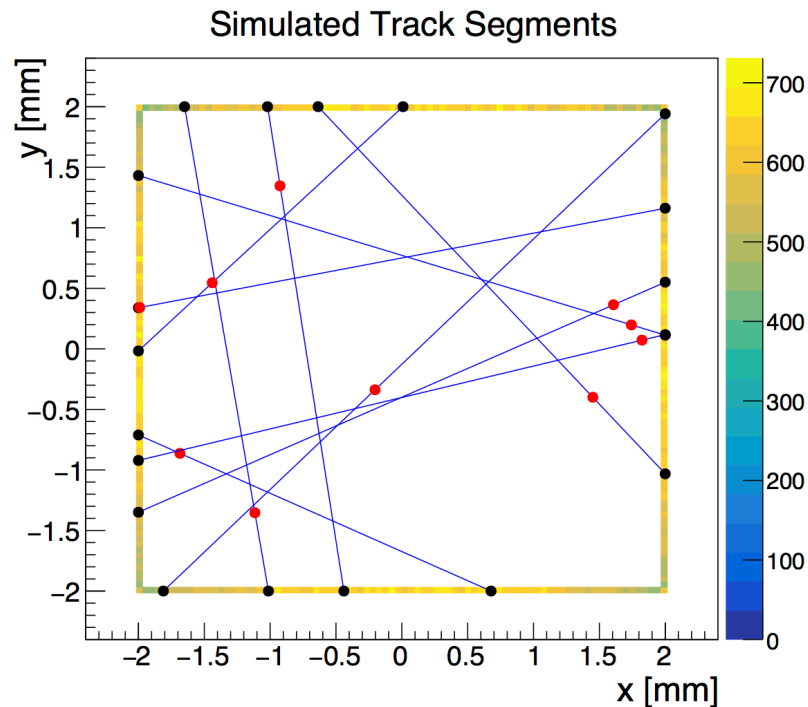


# Minimum-Ionizing Signals

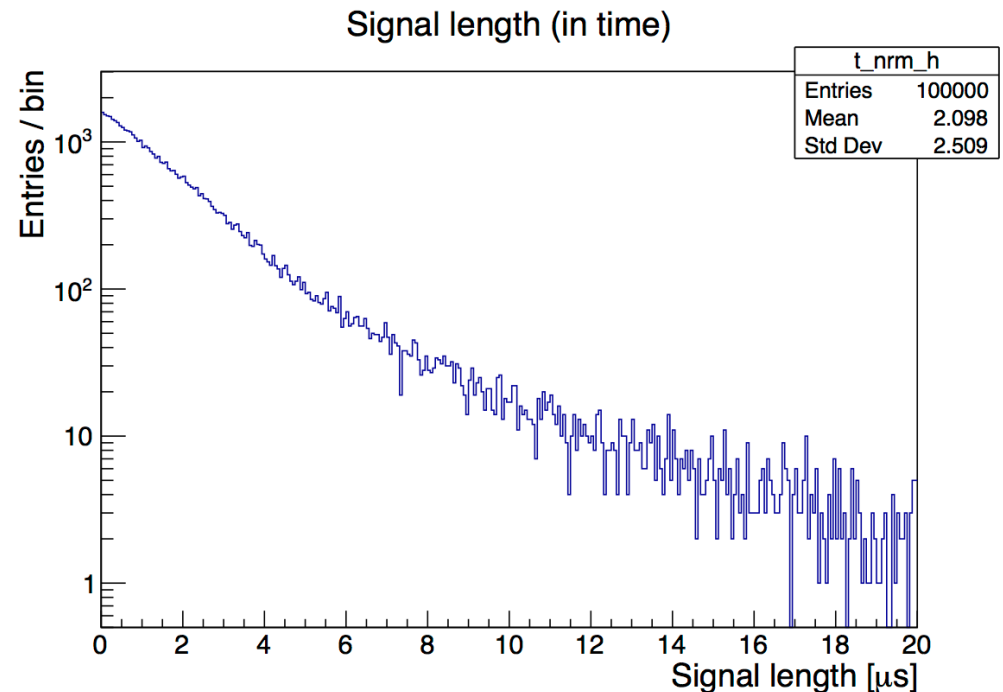
## Rough calculation of expected MIP signal:

Model MIP track segments as  $\sim 5000$  e-/mm, uniformly distributed in space

*Simulated track segments in field of view of one 4mm pixel*



*Length of signal in the drift direction, assuming drift of 1.6 mm/ $\mu$ s.*



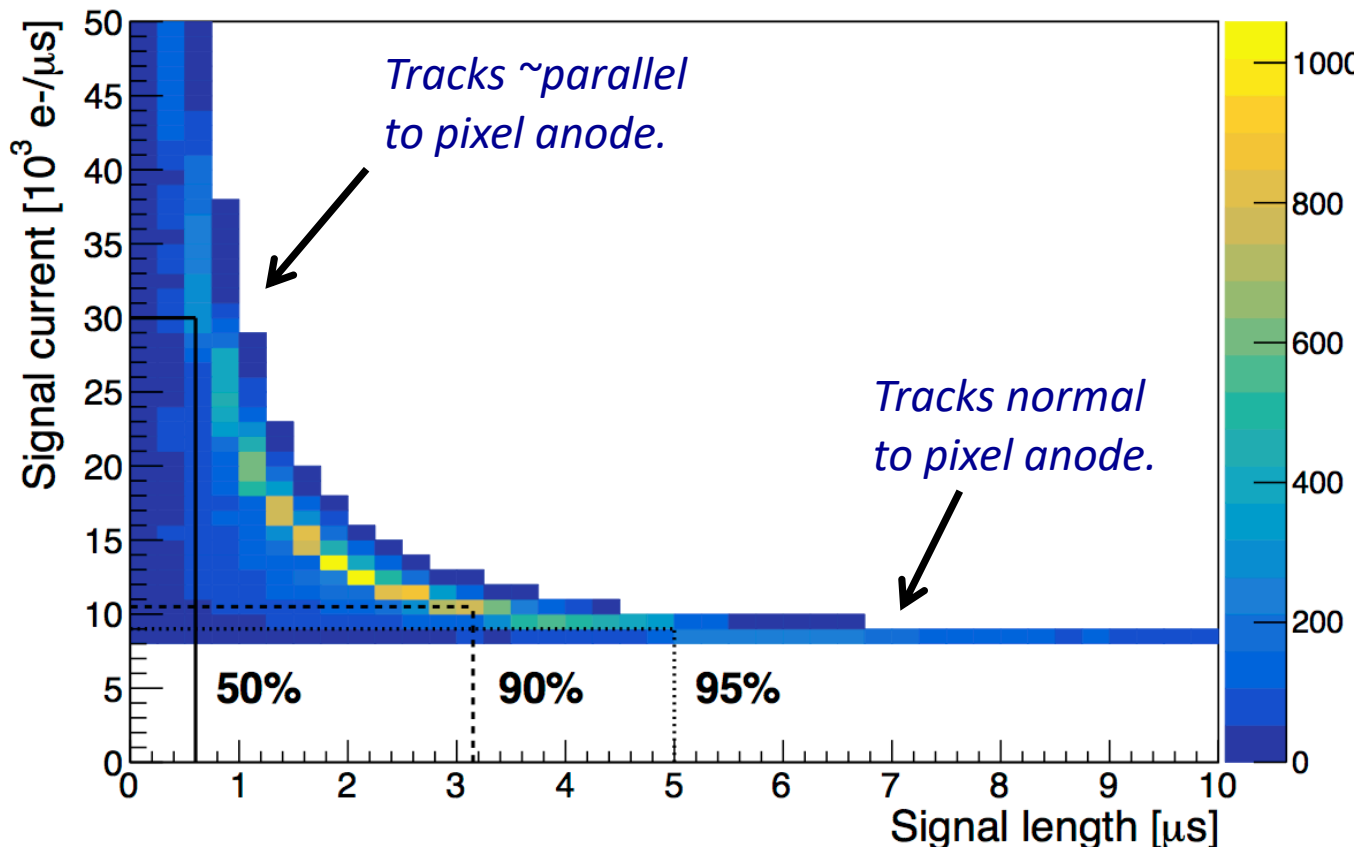


# Minimum-Ionizing Signals

## Rough calculation of expected MIP signal:

Model MIP track segments as  $\sim 5000$  e-/mm, uniformly distributed in space

Signal current vs. time



Note:  
Electron diffusion during drift ( $\sim 1$  mm/Vm) and pixel response will add dispersion to input signal.

Most MIP signals have short duration ( $< 1$   $\mu$ s) and total charge of  $\sim 20$  ke-.  
Few MIP signals have long duration ( $> 5$   $\mu$ s), with current of  $\sim 8000$  e- /  $\mu$ s.



# Pixel Signal Modeling

Implemented 3-D field and charge drift for pixel signal modeling.

## Electron Paths:

Start in middle of 2-cm box,  
along  $z=1\text{cm}$  'slice',  
from  $x=0.7\text{cm}$  to  $1.3\text{cm}$

Propagate in e-field until  
electron strikes surface.

## Configuration:

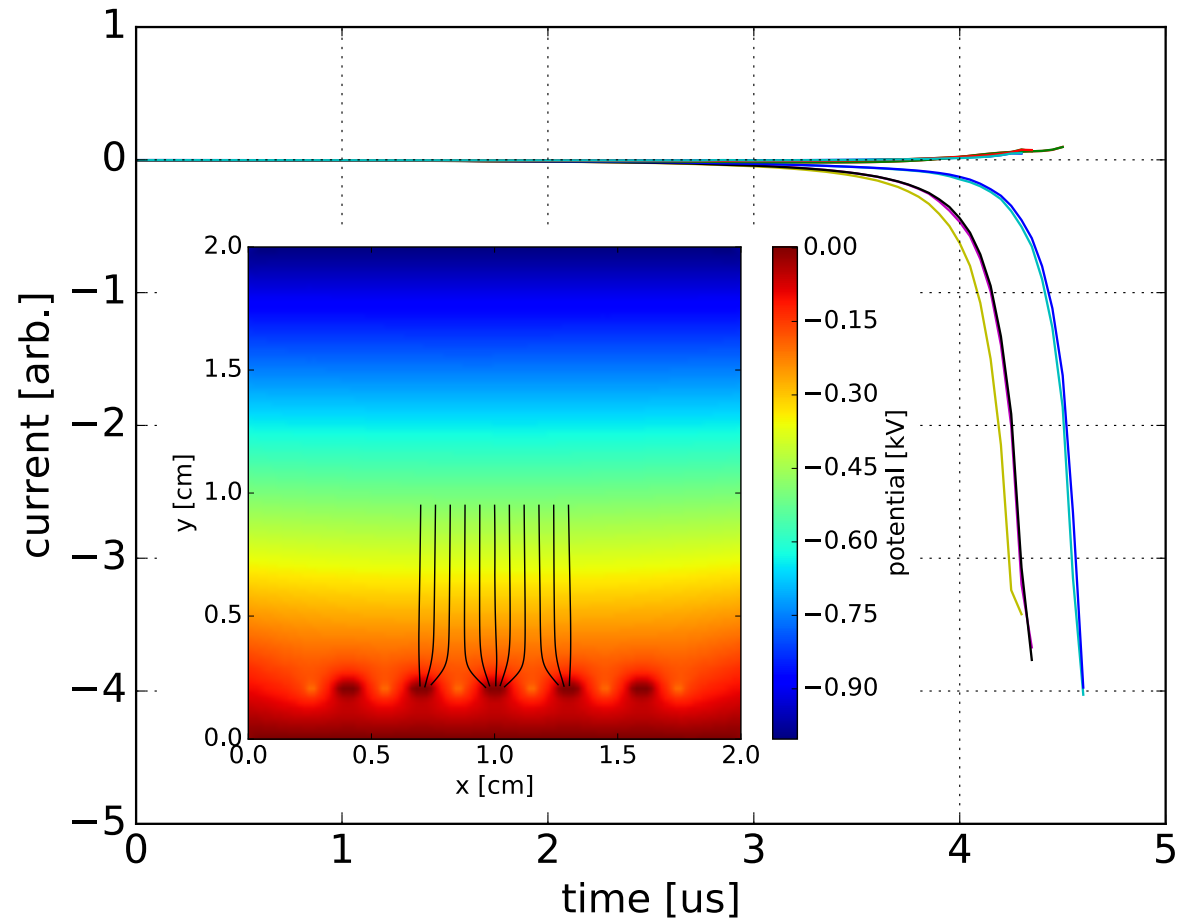
Drift Field:  $500\text{ V/cm}$

Focus grid potential:  $-200\text{ V}$

Pixel pitch:  $3\text{mm}$

## Observations:

- $200\text{V}$  focusing sufficient
- Signal time scale:  $\sim 1\mu\text{s}$
- $\sim 0.3\mu\text{s}$  variation in e- arrival
- $\sim 3\%$  signal induced on neighbor



*D. Douglas now working on more refined model*





# Dynamic Range

## Dynamic range of charge signals (in $\sim 2$ us intervals):

### Low end:

Fraction of a MIP in one pixel:  $\sim 0.1-0.25$  MIP  $\rightarrow$  2000 e<sup>-</sup> to 5000 e<sup>-</sup>

### High end: (Not well understood)

#### DUNE:

Resolve  $\sim 5$  protons stopping in one 'voxel' near neutrino vertex:  $\sim 250$  ke-

Resolve MIP track  $\sim$ parallel to wire

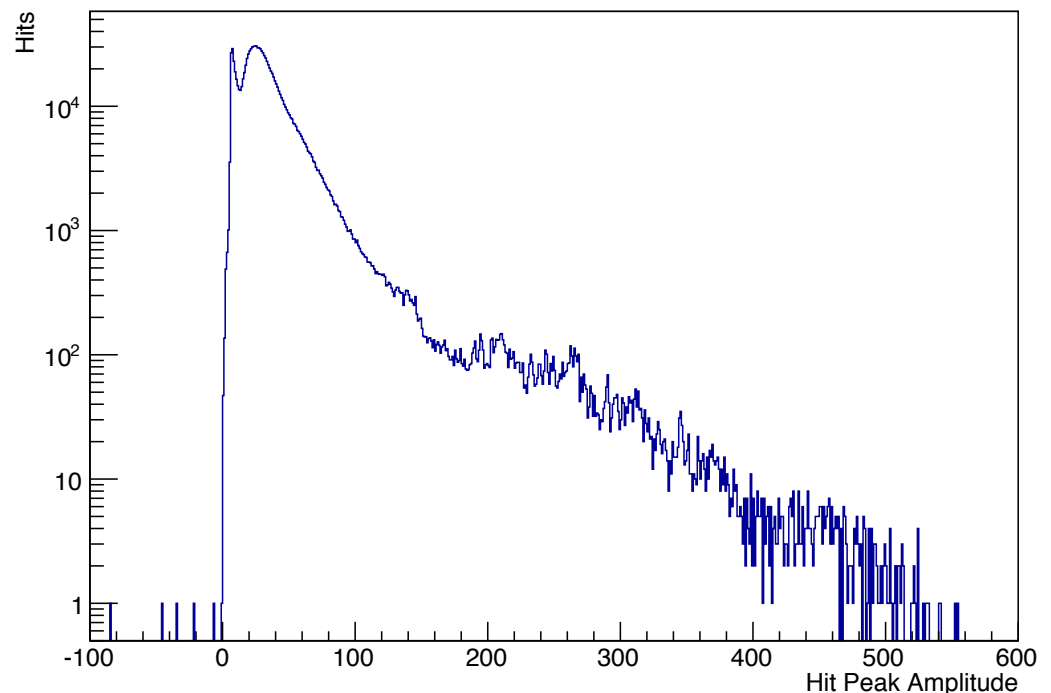
### My rough estimate:

- Examine ProtoDUNE wire signal peak amplitudes (at 2 us shaping)
  - Taken from 1 GeV particle beam run (mostly cosmics, with some beam signals)
  - MIP peak:  $\sim 25$ , Max signals:  $\sim 500$
- $\rightarrow$  *Suggests required dynamic range of  $\sim 20$  MIPs.*

#### Caveat:

*I'm not an expert in ProtoDUNE data, so might be overlooking some important aspects of this data (e.g. wire pileup).*

*Further study required.*





# Charge Uncertainty

## Charge Uncertainty:

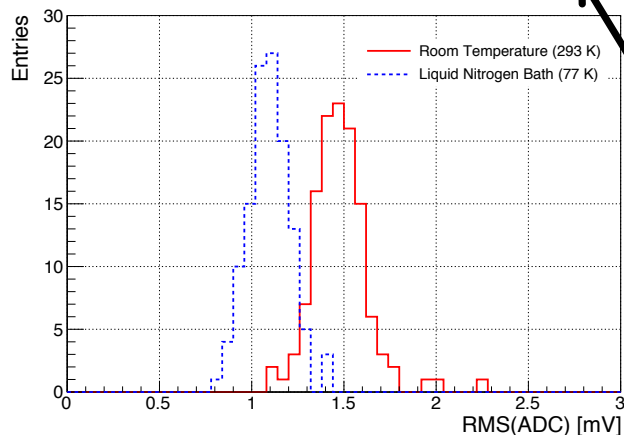
Any effect that distorts measurement of signal charge: noise, bias, etc.  
DUNE: 500 e- ENC sufficient. Lower is better.

### My rough estimate:

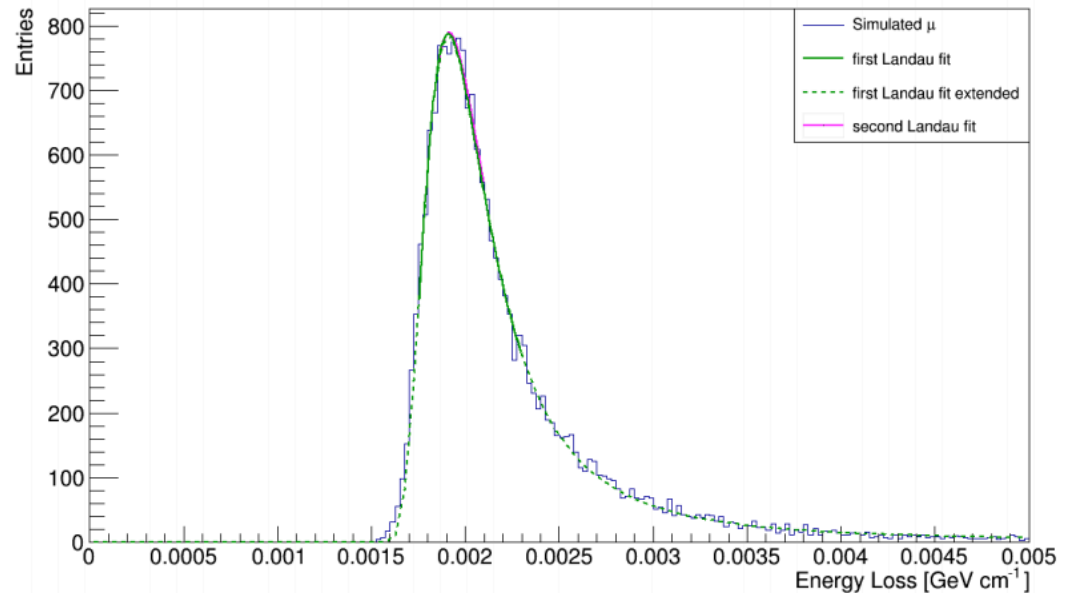
- Readout uncertainty should be smaller than natural stochastic fluctuations in particle energy loss per 'voxel'.

→ *Suggests < 5% uncertainty in measured charge*

- < 1000 e- ENC for MIP-level signals
- < ~20k e- ENC for 20-MIP-level signals



*~300 e- ENC demonstrated for LArPix-v1 ASIC in LN<sup>2</sup> bath.*



*Example Landau distribution for 200 MeV muon energy loss in liquid argon, as simulated using GEANT4 (K. Ingles, Muon Energy Loss in Liquid Argon, 2017)*

Question: Is a linear 12-bit ADC necessary?



# Power

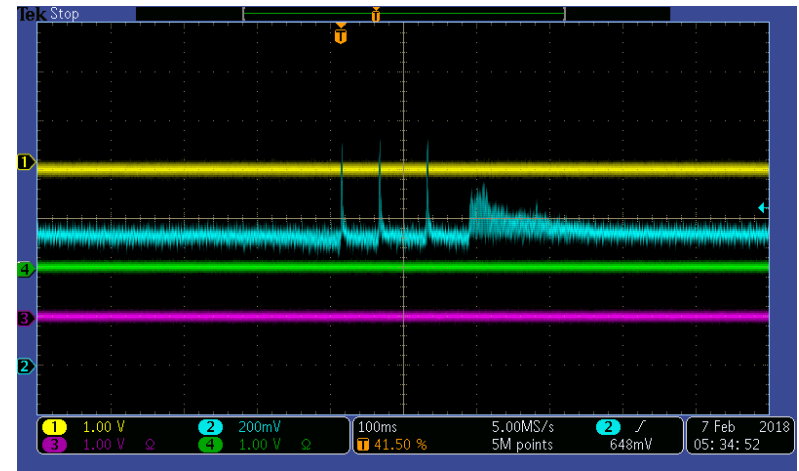
## Heat generation in liquid argon must be controlled:

- Should be less than total heat flux through cryostat:  $\sim 10 \text{ W/m}^2$
- Local heating can boil LAr, impacting TPC performance.  
Limits on local heating poorly quantified.

*Spurious signals from boiling seen with LArPix-v1 ASIC*

## Lessons from LArPix-v1:

- Minor boiling observed during initial operation
- Measured power consumption:  $\sim 62 \mu\text{W/channel}$
- Slight increase in pressure ( $\sim 6 \text{ cm}$  of LAr) sufficient to suppress boiling.



**Table 3.** Average power consumption per channel for a 128-channel readout system at a clock operating frequency of 5 MHz. Values are given for two configurations: an initial default configuration of the supply voltages, and a configuration tuned for low-power operation.

Configuration	Source	Voltage (V)	Current (mA)	Average Power ( $\mu\text{W/channel}$ )
Default	VDDA	1.5	2.0	24
	VDDD	1.8	3.6	51
	VDDIO	3.3	8.5	219
<b>Total: 294</b>				
Low-power	VDDA	1.5	2.0	24
	VDDD	1.1	2.1	18
	VDDIO	2.0	1.3	20
<b>Total: 62</b>				



# Cryogenic Operation

## **ASIC must stably operate in liquid argon (~87 K):**

- Have operated ~60 LArPix-v1 ASICs in LAr. No cryogenic failures identified.
- ~25 v1 ASICs survived >3 thermal cycles with no noticeable change in performance.
- Successfully operated 16 v1 ASICs for continuously for ~1 week in LAr with no noticeable change in performance.

## **Requirements for LArPix-v2 in ArgonCube 2x2 Demonstrator:**

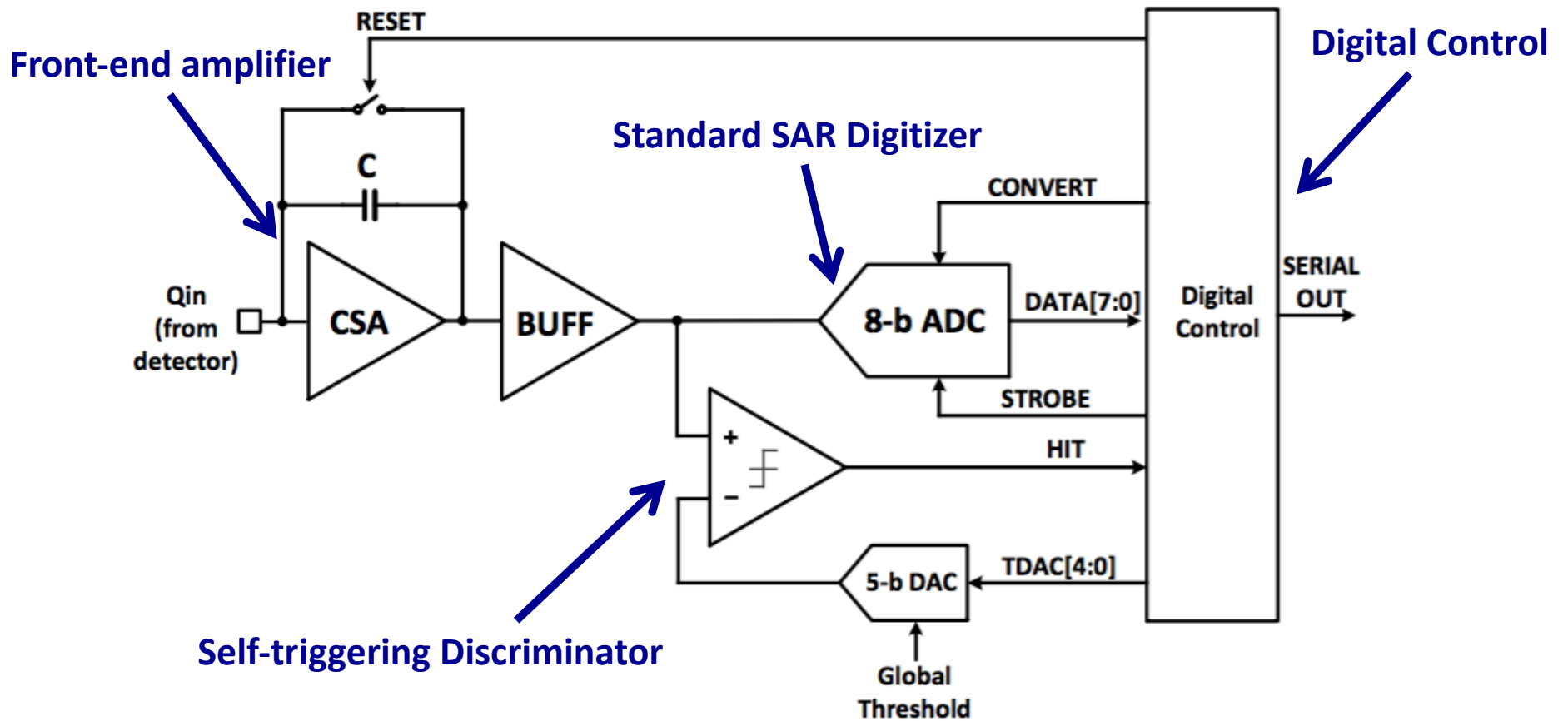
- As a technical demonstrator, could likely suffer up to 5% ASIC loss during the planned ~6 months of ArgonCube 2x2 Demonstrator operation and still satisfy TDR needs.
- Loss here is defined as ASIC performance out of target specs.



# LArPix Design

True 3D readout: A dedicated front-end channel for every pixel

Approach: Amplifier with Self-triggered Digitization and Readout



*Achieve low power: avoid digitization and readout of mostly quiescent data.*



# LArPix: Design Details

Specification	Value	Units	Note
Number of Analog Inputs (channels)	<del>32</del> (single-ended) <b>64 (v2)</b>		
Noise	300 @ 88K 500 @ 300K	ENC, e-	Stipulated charge deposition is 15 ke- per MIP for a track in LAr
Channel gain	4 or 45	$\mu\text{V}/\text{e-}$	Digitally programmable
Time resolution	2	$\mu\text{s}$	with 10 MHz master clock rate
Analog Dynamic Range	$\sim 1300$	mV	max signal $\sim 250$ ke-, minimum detectable signal $\sim 600$ e-
ADC resolution	<del>6</del> <b>8 (v2)</b>	bits	programmable LSB, 4 mV nominal (1 ke-)
Threshold Range	0 – 1.8	V	
Threshold Resolution	< 1	mV	nominal
Channel Linearity	1	%	
Operating Temperature Range	88 - 300	$^{\circ}\text{K}$	
Event Memory Depth	2048	memory locations	$\sim 8$ ms without data loss in case of track normal to pixel plane
Output Signaling Level	3.3	V	Tunable
Digital data rate	5	Mb/s	With 10 MHz master clock
Event readout time	5	$\mu\text{s}$	



# LArPix Triggering

## Self-triggering with pulsed reset $\neq$ Zero suppression

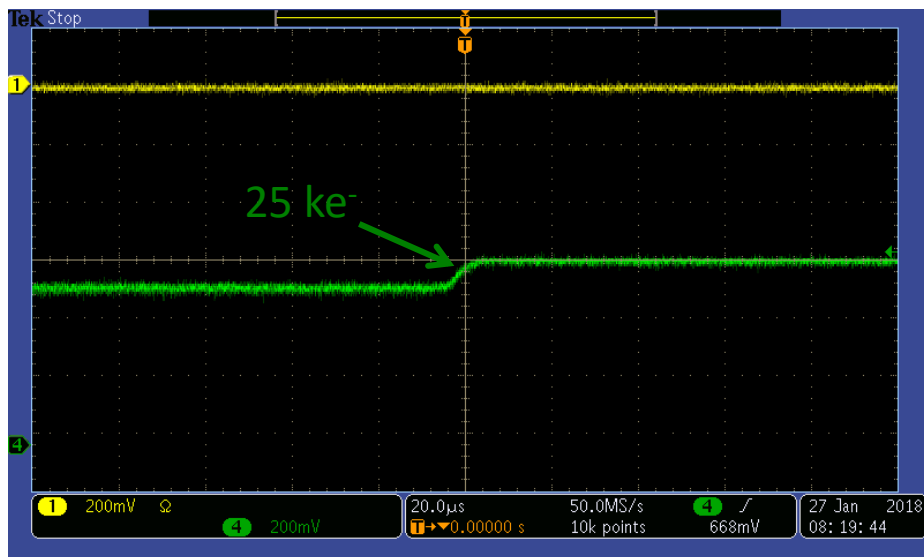
LArPix has no resistive feedback or shaping

→ Charge stays on pixel until you do something with it

### Your choices:

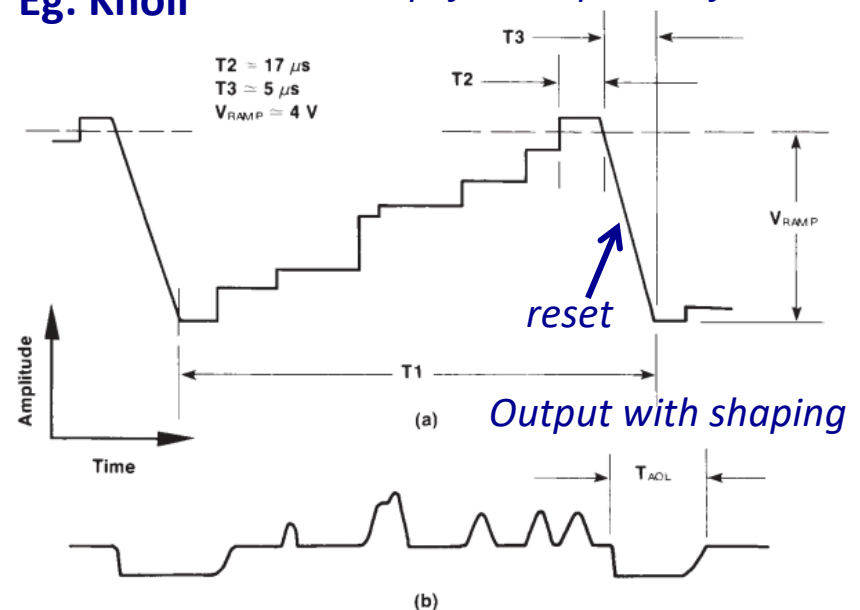
- Self-trigger reset: digitize and drain charge after threshold crossed
- External-trigger reset: digitize and drain sub-threshold charge based on external signal
- Cross-trigger reset: digitize and drain sub-threshold charge based on self-trigger of another pixel
- Periodic-trigger reset: periodically discard sub-threshold charge without digitization

Example MIP-scale signal, without reset



Eg: Knoll

Amplifier output, no feedback





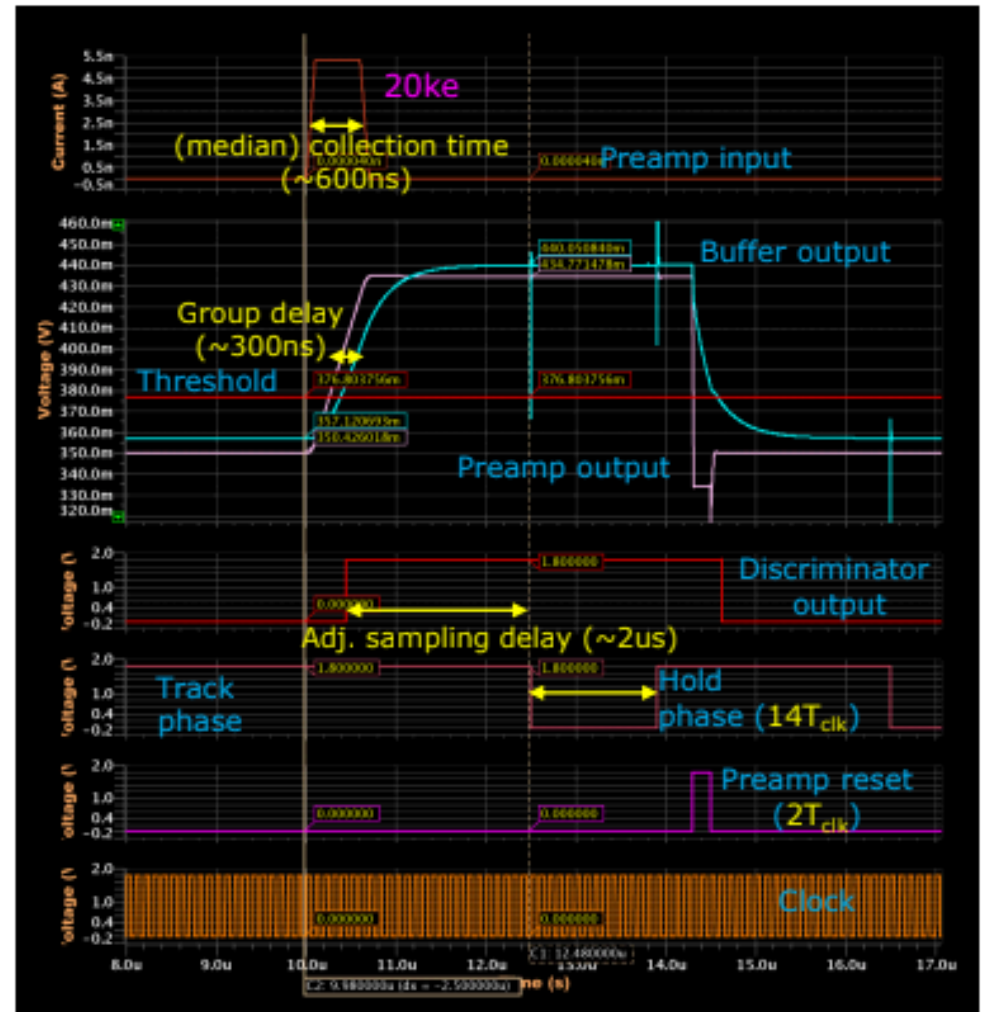
# LArPix Channel Response

## Detailed simulation of LArPix-v1 channel response

D. Gnani

### 'Typical' Timing

- Input collection current / track duration
  - 0-320us (600ns median)
- CSA preamp delay & settling time
  - 15ns & 80ns
- CSA preamp delay & (8-bit) settling time
  - $T_{dly}=300ns$ ;  $T_{stl}=1.8us$
  - Settling time forces sampling delay  $\sim 2us$
  - Min resampling time  $\sim 15.5us$  @  $T_{clk}=100ns$
- Comparator delays
  - Prop. delay (signal dependent)
  - Clock capture delay  $\leq 1T_{clk}$
- ADC conversion time
  - $14T_{clk}$
  - $(4+2)T_{clk}$  recovery







# Deadtime

*Channel blind from signal hold to CSA reset*

## CSA reset introduces 'deadtime'

- More accurately: signal charge loss during reset.

### 1) Direct reset loss:

Charge arriving between signal hold by ADC and recovery of CSA from reset is never seen by ADC.

### 2) Indirect reset loss:

Charge arriving shortly before signal hold by ADC, but insufficiently settled on ADC capacitors, is incompletely seen by ADC.

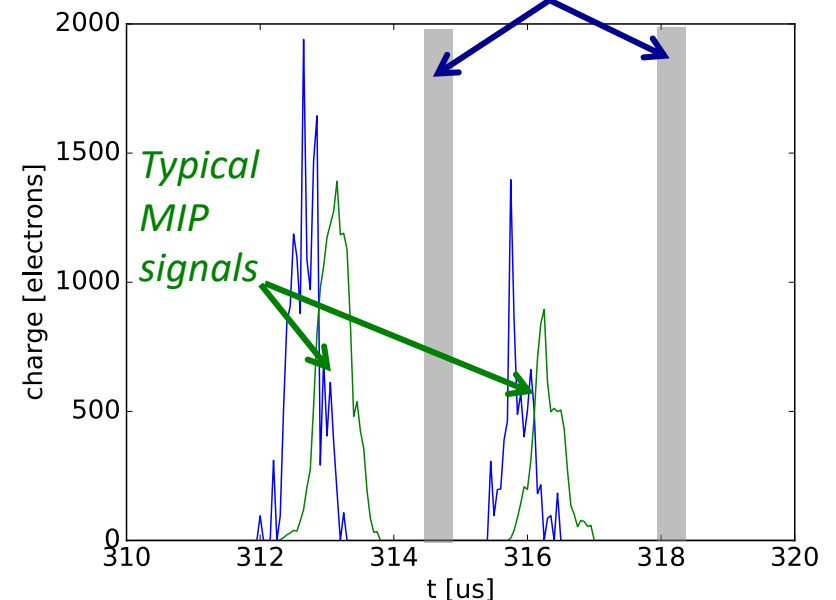
- Unlikely an issue for short MIP signals
- More concern for long signals

## Requirements for LArPix-v2:

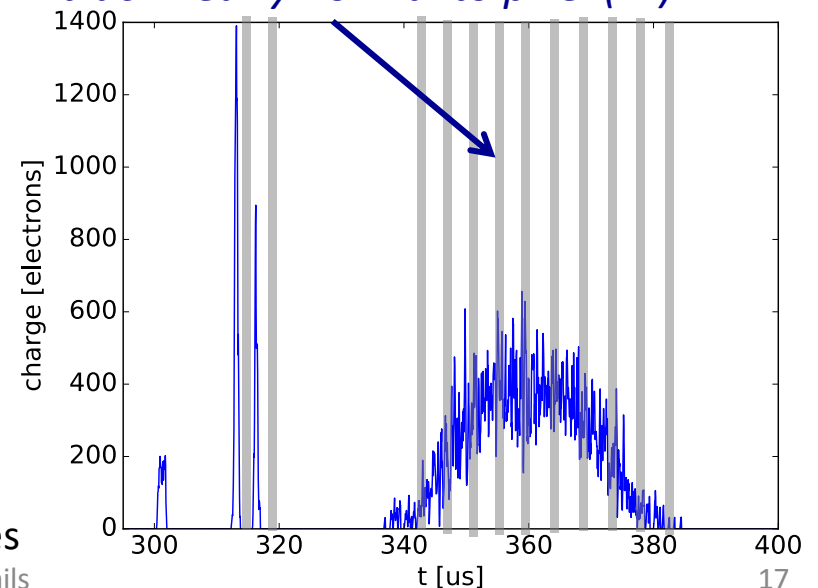
- Difficult to quantify with existing data.  
More simulations in progress.

## Plan:

- 1) Reduce effect by decreasing time from signal hold to recovery from reset, and speed up buffer.
- 2) Add reset-suppressed (charge-integrating) modes to enable measurement of reset charge loss.
  - fixed: ADC digitizes ( $dt \sim 2\mu s$ ) n-times before reset
  - dynamic: ADC digitizes ( $dt \sim 2\mu s$ ) until ADC value settles



*Multiple resets during long signal from track nearly normal to pixel ( $2^\circ$ ).*





# Leakage Current

## Leakage of charge onto front-end must be mitigated

Large leakage can lead to spurious triggers or increased uncertainty for charge measurement.

### LArPix-v1 ASIC:

Observed leakage, no pixel attached

At room temp:  $\sim 80$  fA ( $\sim 500$  e-/ms)

At LN/LAr temp:  $\sim 80$  aA ( $\sim 500$  e-/s)

### v1 Conclusion:

Enabling periodic resets at  $>50$  Hz, leakage is negligible at LAr temp. (slightly annoying at room temp)

Also:

Occasional channels with high leakage after pixel PCB assembly.

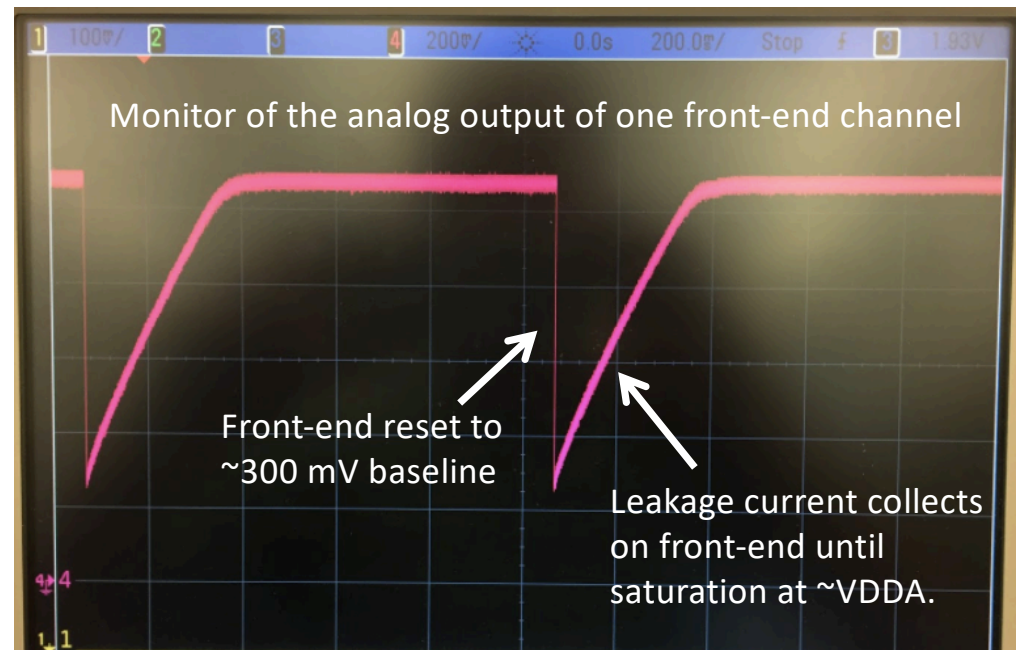
Usually resolved by cleaning pixel PCB.

### v2 Goal:

Don't substantially increase leakage from v1:  $\sim 80$  aA in LAr.

*Example:*

*Channel with high leakage and 1 Hz periodic reset.*





# Trigger Rate

## LArPix concept relies on low trigger rate per pixel

### Data rates:

- Data I/O for pixel tile saturates at  $\sim 10$  kHz trigger rate per I/O link (MOSI/MISO pair).
- Assuming one I/O link per tile, 100 ASICs per pixel tile, 64 channels per ASIC:
  - *Physical Limit:  $\sim 1.5$  Hz / channel*
- Expected data rates from true signals:
  - Observed:** LArPix-v1 @ Bern (on surface, 60cm-drift):  *$\sim 0.3$  Hz / channel*
  - Expected:** ArgonCube 2x2 Demonstrator:
    - @ Bern (on surface, 30cm-drift):  *$\sim 0.15$  Hz / channel*
    - @ FNAL (underground, 30cm-drift):  *$\sim 0.01$  Hz / channel*

### Channel thresholds:

#### LArPix-v1:

Observed excess trigger rate ( $\sim 1$  Hz) at threshold of  $\sim 0.4$  MIP. Insufficiently clean power?  
Worse at Bern due to enhanced noise environment (lab above train station).

#### LArPix-v2:

Improving cleanliness of analog power with on-chip LDOs.  
Improve ground plane on v2 pixel tile.

### Power:

Data I/O a large part of digital power consumption. Hard to increase I/O link bandwidth at fixed power.  
Some room to decrease digital voltage to reduce I/O power.



# FIFO Depth

## LArPix FIFO facilitates slow low-power off-chip data transmission

### How large of a FIFO is required?

#### Lesson from LArPix-v1 @ Bern:

- FIFO depth: 2048 entries
- 32 channels per chip
- 16 chip daisy chain
- Average data rate, on surface, 60cm-drift:  $\sim 0.3 \text{ Hz} / \text{channel}$

#### Observed:

- FIFO half-full flags: 3 events over  $\sim 1$  week of operation
- FIFO full flags: 0

#### Estimate for LArPix-v2 in ArgonCube 2x2 Demonstrator:

- 64 channels per chip  $\rightarrow \times 2 \text{ FIFO depth}$
- Shorter drift length ( $\sim 35\text{cm}$  instead of  $60\text{cm}$ .)  $\rightarrow \times 0.5 \text{ FIFO depth}$
- Hydra I/O vs. Daisy Chain:  $\rightarrow \text{Signal-dependent. Simulation in progress.}$

#### Rough Estimate:

Likely ok underground @ FNAL. Unclear about surface operation @ Bern.

v2: Implementing tunable I/O clock rate to allow trade-off in data rate vs. power



# FIFO Depth

## LArPix FIFO facilitates slow low-power off-chip data transmission

→ What about intense, long signal bursts on one channel, chip, pixel tile?

**Scenario 1:** Single channel fully active for one drift window

drift\_velocity: 1.6 mm/us

drift\_distance: 350 mm (for ArgonCube 2x2 Demonstrator)

drift\_window = drift\_distance / drift\_velocity → ~220 us

sample\_time: 2.0 us

n\_samples\_per\_channel = drift\_window / sample\_time → ~110 samples

**Scenario 2:** All channels on chip maxed out during one drift window

n\_channels: 64 per chip

n\_samples\_per\_chip = n\_samples\_per\_channel \* n\_channels → 7,000 samples

Neither scenario is very likely for MIP tracks.

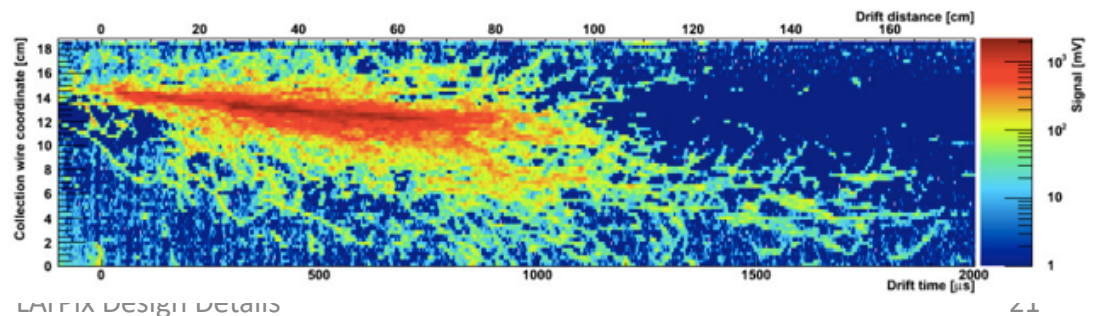
More likely: MIP track is perpendicular to one chip region:

→ ~110 samples spread over a few (~8) of the channels on the chip.

## Open question: Particle showers

- Simulation in progress
- v1 operation at Bern:
  - No 'FIFO full' flags from cosmic showers.

*Example intense cosmic shower from 5m ArgonTube LArTPC*





# Assembly and Operation

## Many changes needed for assembly and operation of detector-scale system

### Assembly:

- Enable complete assembly of pixel tiles by commercial vendors
  - Increase channel count: from 32 (v1) to 64 (v2)
  - Increase default pixel spacing: from 3mm (v1) to 4mm (v2)
  - Substantially reduce the number of SMT components: ~30/ASIC (v1) to ~few/ASIC (v2)
  - Simplify chip attachment, rework: wirebond COB (v1) to QFP package (v2)
  - Simplify PCB structure: two PCB sandwich (v1) to single PCB (v2)

### Operation:

- Pixel tile must continue to function, robust to arbitrary single-ASIC failures.  
Example ASIC failure modes considered:  
Chip D.O.A., excess current draw on power-up, excess noise generation on power-up, data I/O failure

### Key v2 features:

- Hydra I/O
- ASIC subsection power disabled by default, manually enabled via digital control
- Extensive in-chip monitoring capabilities
- Enhanced test-pulse capabilities
- Protection against disabled pixel charge-up



# Summary

## Requirements for the LArPix-v2 ASIC design

### Signal targets for the ArgonCube 2x2 Demonstrator:

- Cosmic Ray tracks and showers, operating on the surface in Bern
- NuMI neutrino beam interactions, operating underground at Fermilab

### LArPix-v1 to v2 changes:

Primarily focused on aiding large-scale detector assembly and operation

- Robust I/O architecture
- Chip configurability to mitigate failure modes
- Increase channel count, use QFP packaging, minimize external circuitry and components

Maintain v1 physics performance, with some limited enhancements

- Reduce front-end deadtime, charge signal loss
- Enhance front-end test pulse system to improve channel characterization
- Larger timestamp to facilitate data synchronization