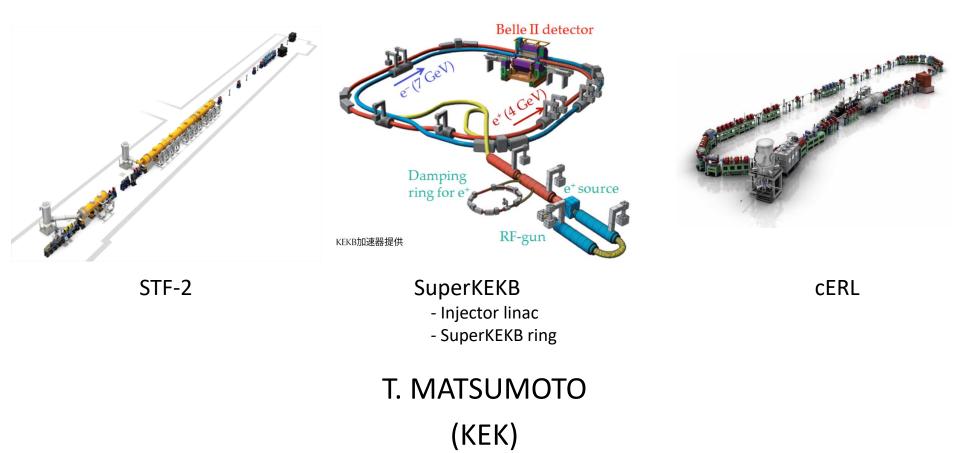




KEK Lab Talk



KEK Lab talk (T.Matsumoto)

EXEX Recent progress of LLRF control system for KEK's accelerators:

- SuperKEKB Ring & Linac Damping Ring
 - LLRF control system using MTCA boards
 - \Rightarrow LLRF control system are working well with no serious problem

T. Kobayashi, IPAC14, IPAC18

F. Qiu, ERL19

- Injector Linac
 - Reconfiguration of RF Distribution System
 - LLRF control and monitor system using FPGA board
 - ⇒ Simultaneous top up injection to four rings (HER, LER, PF and PF-AR)
 - Phase Drift Compensation System

between Linac MO and Ring MO

- cERL
- LLRF control system using MTCA boards
- \Rightarrow Investigation of microphonics in ML SC cavities
- STF-2
 - LLRF control system using MTCA boards

 \Rightarrow Average 33.1 MV/m beam operation Y. Yamamoto, SRF19

2019/Sep./30 LLG Fider vector-sum feedback (T.Matsumoto)



CASA

pplied

Superconducting Accelerator

Super

KEKB

- FPGA (Virtex 5 FX),
- 4 x 16-bit ADCs
- 4 x 16-bit DACs
- Digital I/O



- 2 x SFP
- 1 x RJ-45
- Digital I/O
- (Zynq-7000, Spartan 6) 14 x 16-bit ADCs 2 x 16-bit DACs

Mitsubishi Electric TOKKI System Co., Ltd.

EXER Recent progress of LLRF control system

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T. Matsumoto, IPAC18 T. Miura, IPAC18 H. Katagiri, IPAC18

N. Liu, PRAB 22, 072002 (2019)

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Super

KEKB

CASA

Superconducting

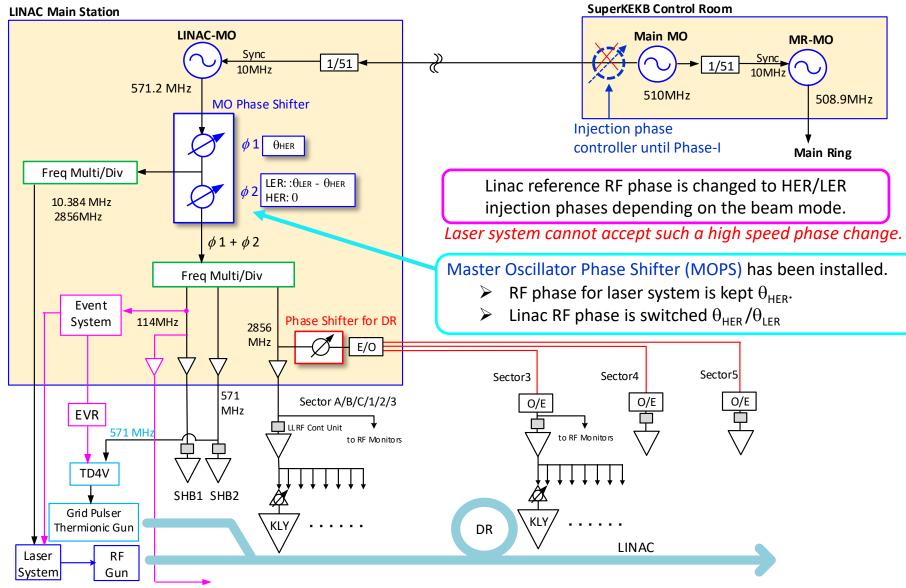
The digital control units in the Injector Linac are based on Xilinx ML605 and its daughter board.



Reconfiguration of RF Distribution

System for SuperKEKB:





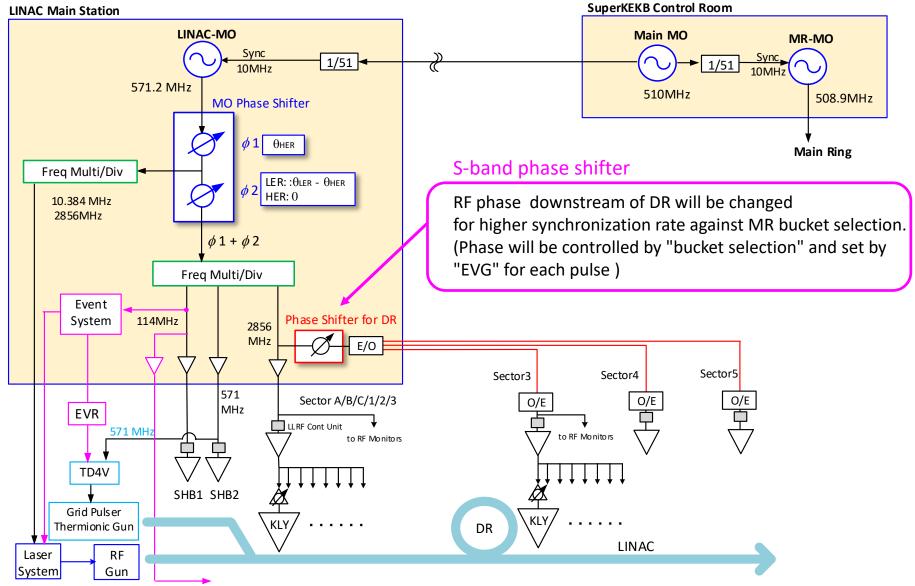
2019/Sep./30 LLR Far@pling freq. for LLRF Control Unit, RF Monktok Lab talk (T.Matsumoto)



Reconfiguration of RF Distribution

System for SuperKEKB:





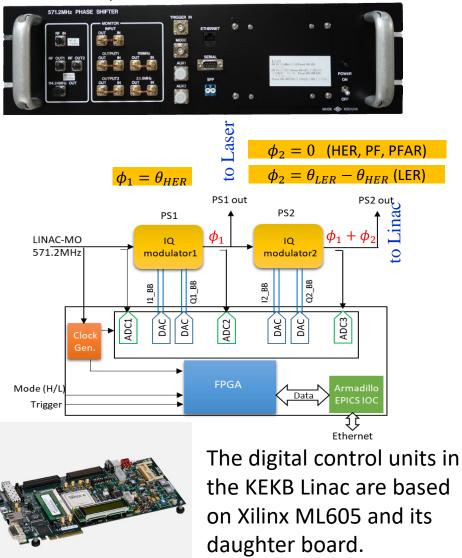
2019/Sep./30 LLR Sanopling freq. for LLRF Control Unit, RF Montilo K Lab talk (T. Matsumoto)



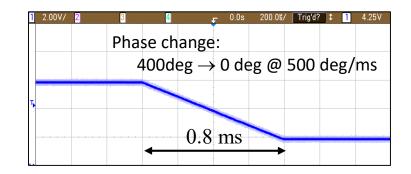
MO/S-band Phase Shifter :



571.2 MHz / 2856 MHz Phase Shifter

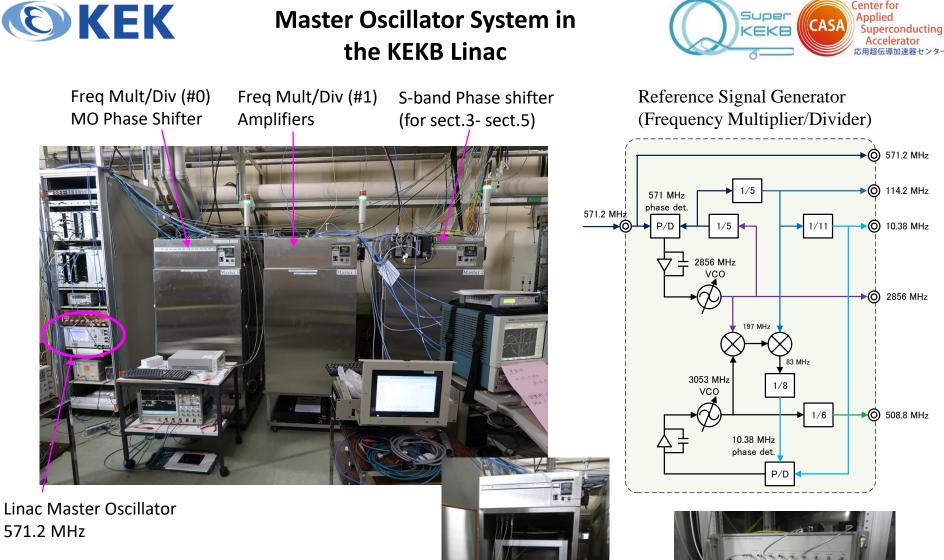


Specification of MO Phase Shifter	
Phase Range	-450.00 deg ~ + 450.00 deg
Resolution	0.01 deg
Speed	1 deg/ms ~ 1000 deg/ms
Linearity	< 0.1 deg
Mode	High: LER / Low: HER



In the operation of SuperKEKB, phase change speed :

PS1 = 1 deg/ms PS2 = 100 deg/ms



<u>Thermostatic chamber : 28 ± 0.05 °C</u>

Peltier devices (no mechanical vibration)

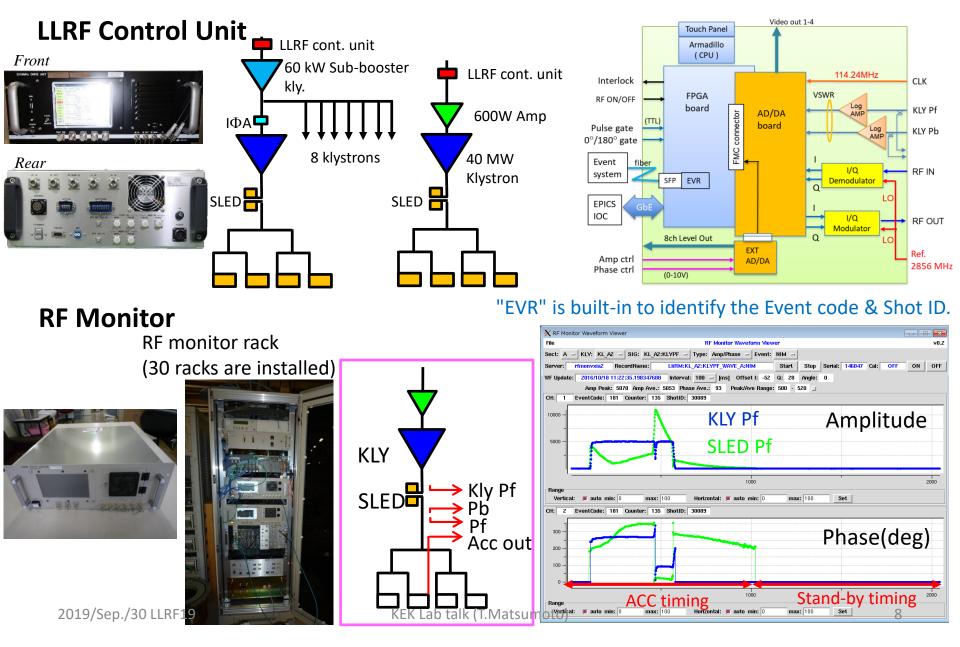
2019/Sep./30 LLRF19

KEK Lab talk (T.Matsumoto)



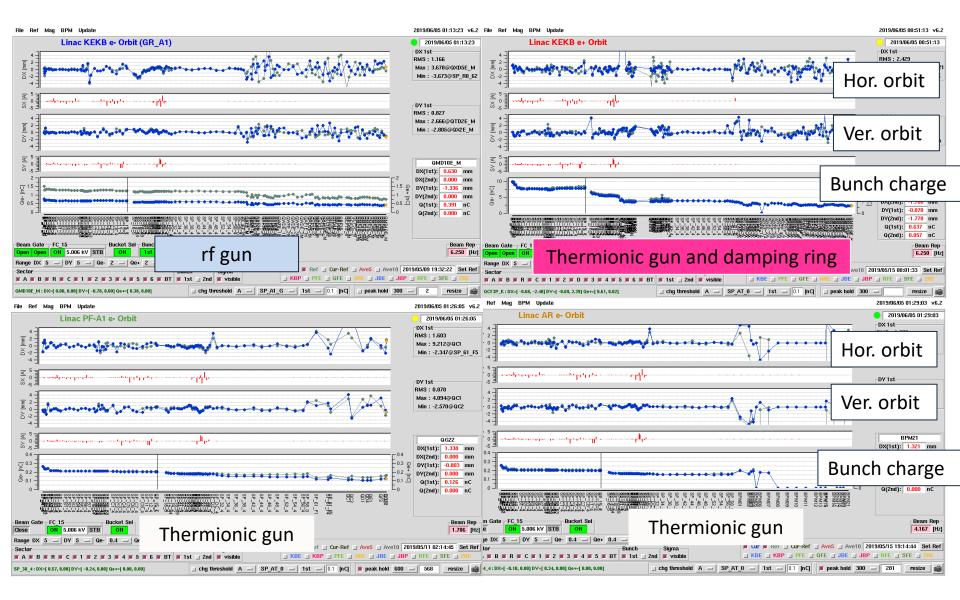
EXAMPLE KEK LLRF Control Unit and RF monitor:





Simultaneous beam operation with thermionic e- gun and rf e- gun





KEK



Beam Induced RF monitor (Application of RF monitor)

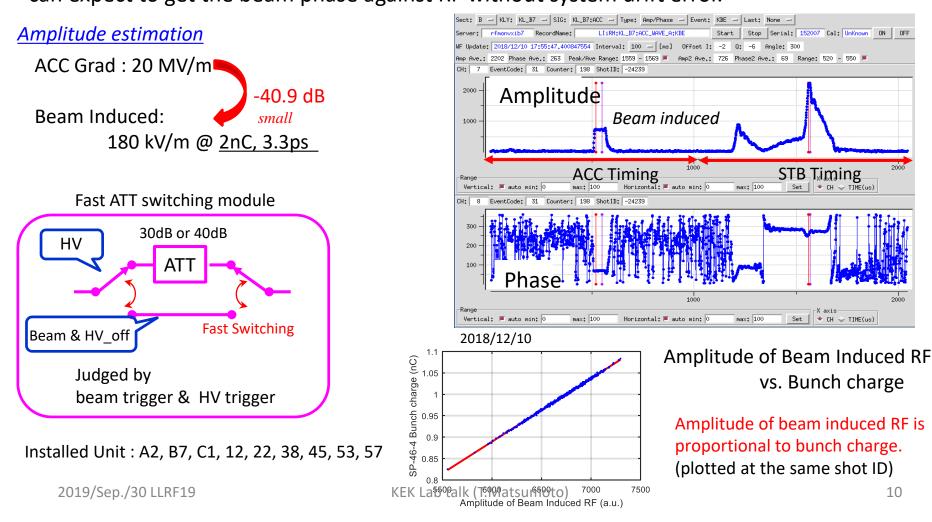


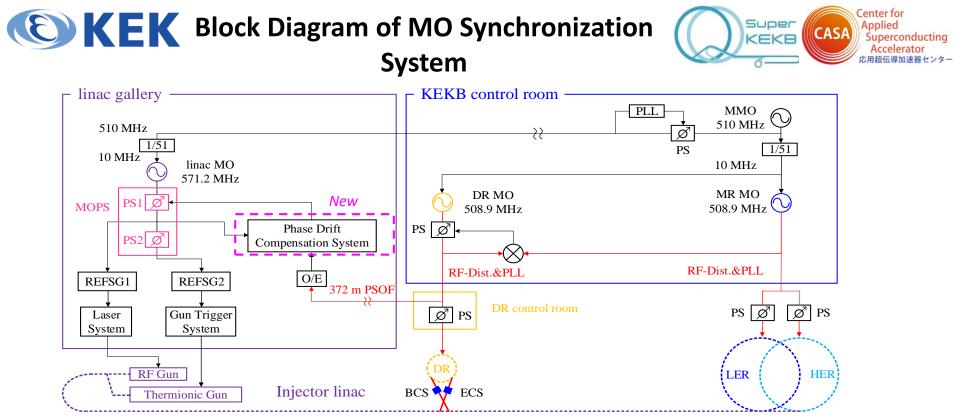
2000

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Motivation

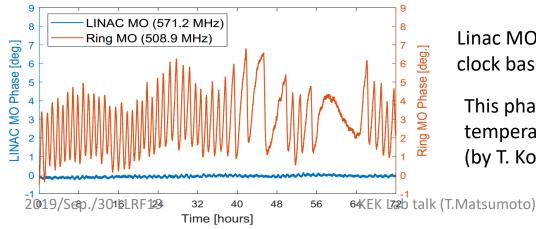
Monitored RF phase is affected temperature drift of cable and monitor system. By comparing the phase of driving RF and beam induced RF in the accelerating structure, we can expect to get the beam phase against RF without system drift error.





MR MO and DR MO phases have been locked by PLL.

⇔ Linac MO phase had not been locked to Ring MO phase.



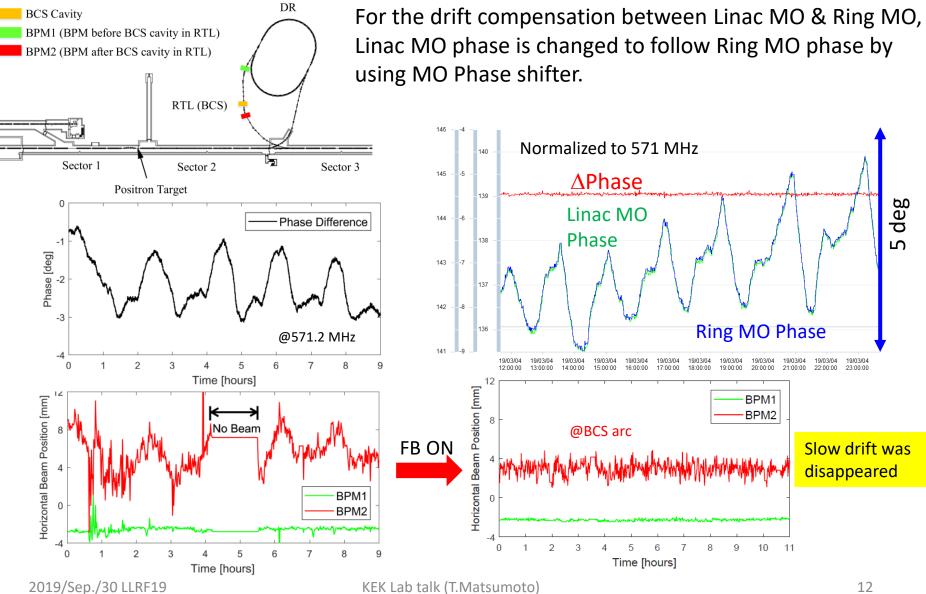
Linac MO & Ring MO phases are monitored with the clock based on Linac MO.

This phase drift has strong correlation with temperature of the Ring MO room. (by T. Kobayashi)



Phase Drift Compensation between Linac MO and Ring MO







Summary



- In the KEK, the LLRF control systems of each accelerator work well. This contributes to steady beam operation for each accelerator.
- The RF distribution system of Injector linac was reconfigured for SuperKEKB project. The MO phase shifter and the S-band phase shifter, and the phase drift compensation system between Linac MO and Ring MO were installed.
- The LLRF control unit and the RF monitor have been developed to achieve the simultaneous beam injection of four independent rings.





• Thank you for your attention!

