

AI/ML for Design and Operation of Particle Accelerators and Detectors

Snowmass Summer Study 2022
Computational Frontier

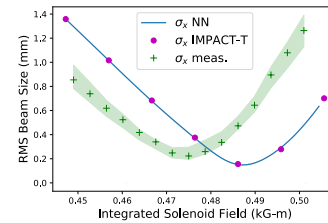
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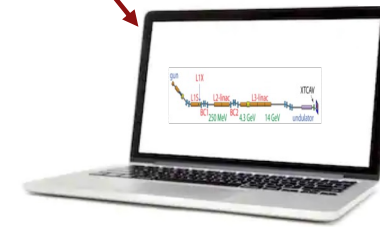
Fast Simulations for Accelerators and Detectors

- Physics simulations for accelerators and detectors are powerful tools but are **computationally expensive**
- Numerous ML approaches being taken to create fast-executing representations of detailed simulations
→ “**surrogate models**” (*GANs, Bayesian NNs, VAEs, Simple NNs*)
- Faster predictions enable enhanced capabilities:
 - More comprehensive design + experiment planning
 - Discovery and online monitoring of differences between simulations and the real instrument (“*calibration*”)
 - Online predictions to provide more information for control and analysis
 - Model-informed online control
 - Future: “end-to-end” optimization from accelerator to detector/experiment

ML brings prediction tools from HPC systems to online/local compute

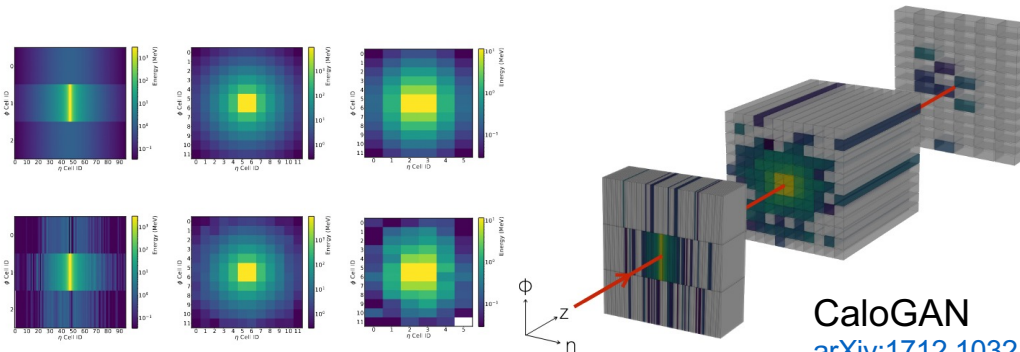


*Online prediction
Model-based control*

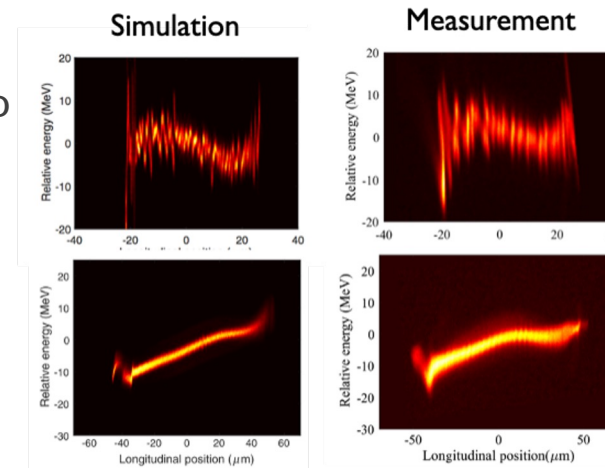


*Control prototyping
Experiment planning*

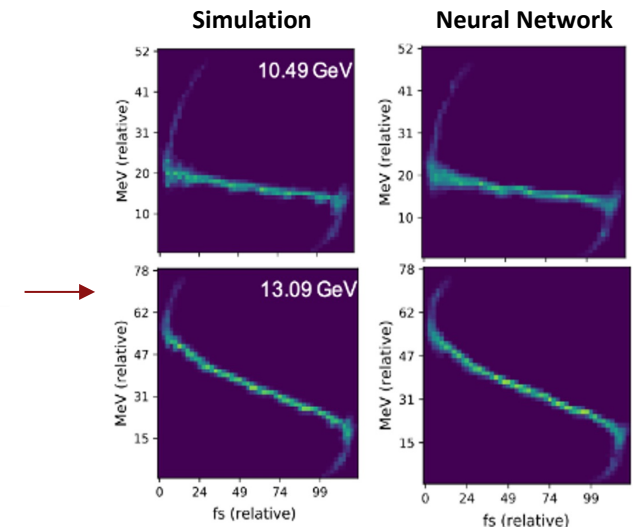
**Automatic
Model
Calibration**



CaloGAN
[arXiv:1712.10321](https://arxiv.org/abs/1712.10321)



Accelerator simulation: 10 hrs on thousands of cores at NERSC!



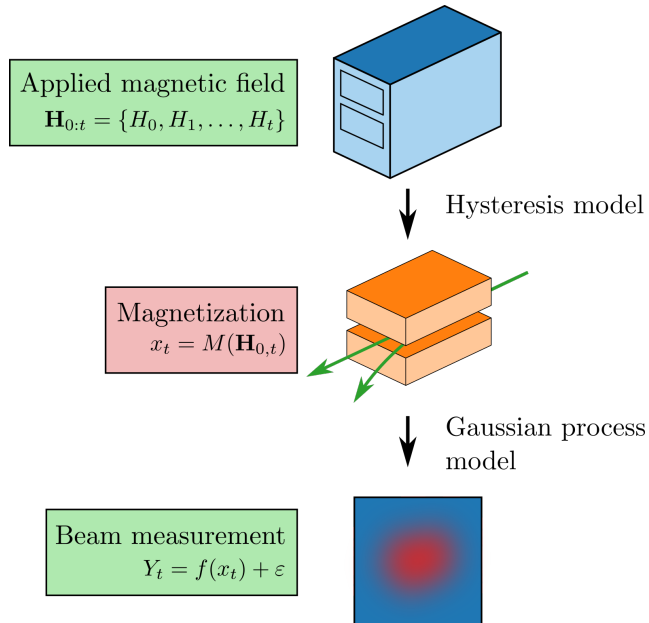
Neural network surrogate: < ms (10⁶ speedup)

See accelerator community modeling WP: [arXiv:2203.08335](https://arxiv.org/abs/2203.08335)

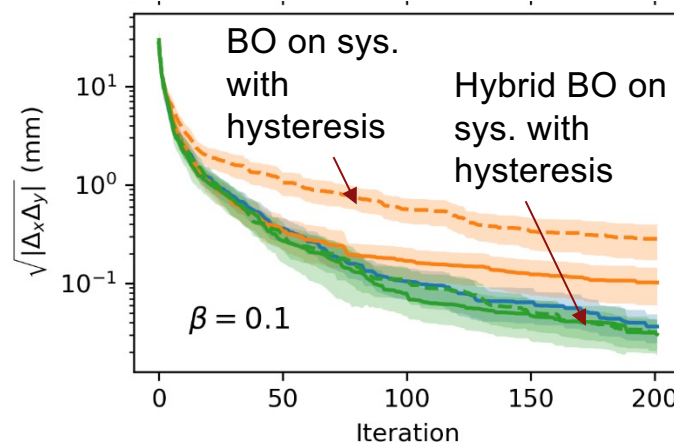
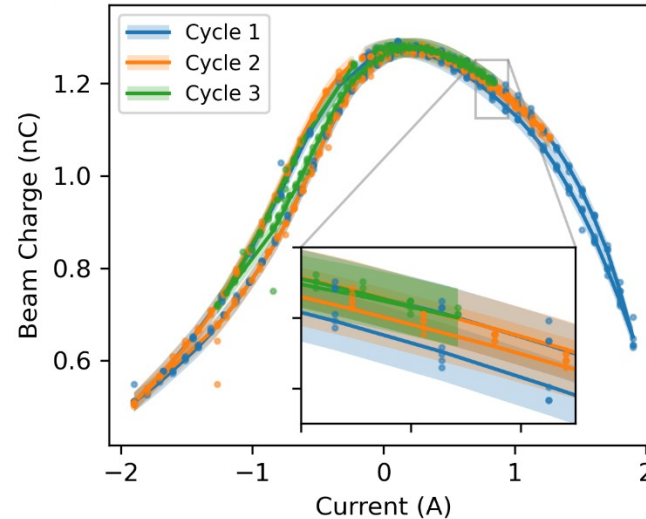
Differentiable Physics Simulations and ML

Modern ML uses gradients in learning → *differentiable physics sims enable modular combinations with ML components, analyses, etc.*

Fundamentally new approach in combining physics models, data, and ML



Differentiable physics model of hysteresis combined with ML enables in situ characterization of magnetic hysteresis in accelerator magnets and higher-precision optimization

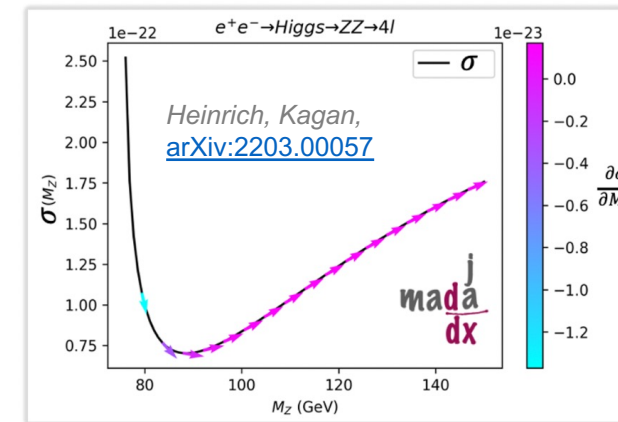


R. Roussel, et al., PRL, 2022, [arXiv:2202.07747](https://arxiv.org/abs/2202.07747)

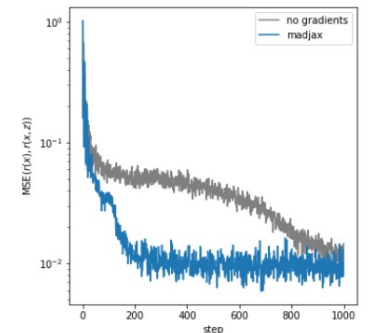
[arXiv:2203.13818](https://arxiv.org/abs/2203.13818)

Toward the End-to-End Optimization
of Particle Physics Instruments
with Differentiable Programming:
a White Paper

Differentiable physics models can facilitate instrument-wide optimization, from accelerator to detector to physics analysis



Differentiable matrix elements of high energy scattering processes



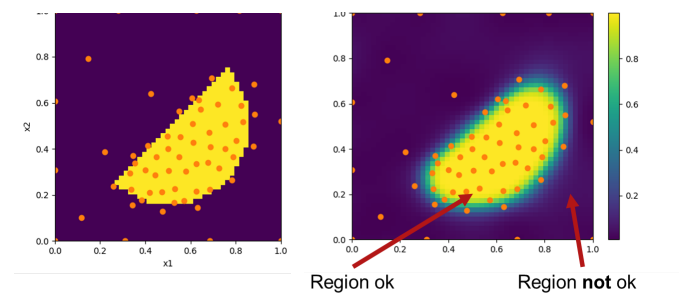
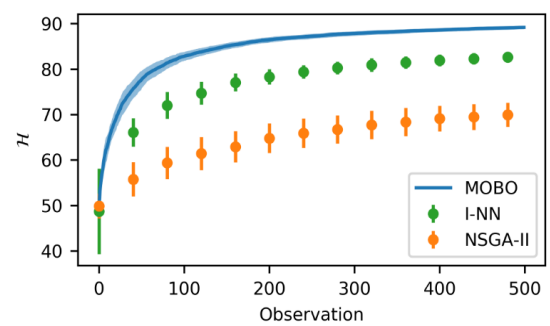
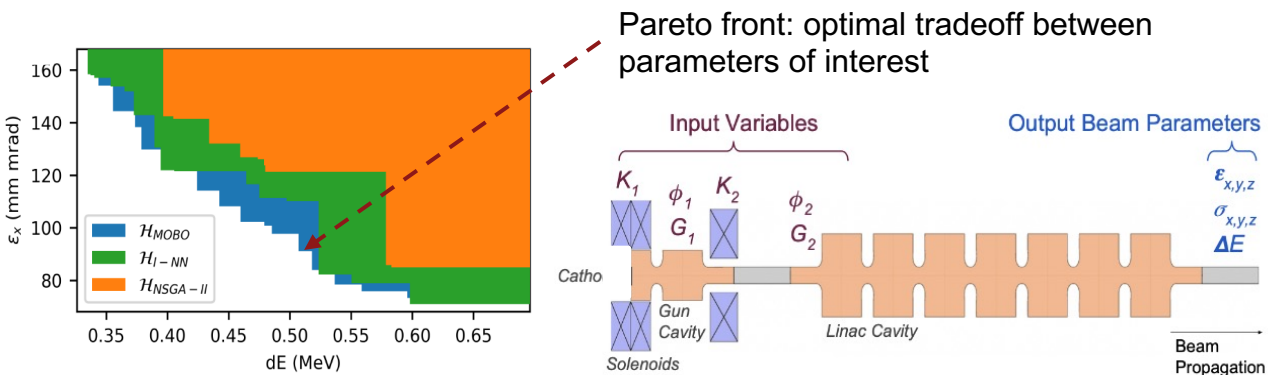
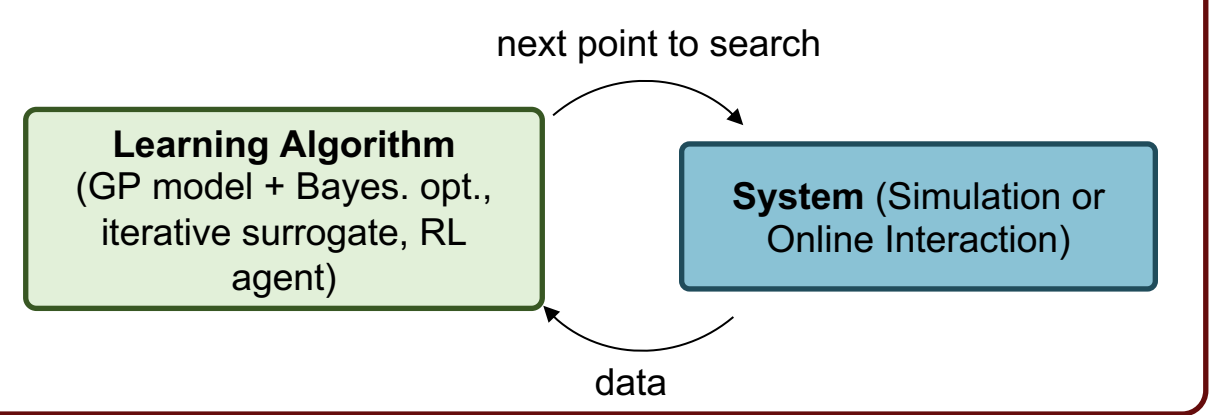
ML-Assisted Optimization and Characterization

Large, nonlinear, and sometimes noisy search spaces for accelerators and detectors → need to find optima and examine trade-offs with limited budget (*computational resources, machine time*)

ML-assisted optimization leverages learned representations to improve sample efficiency. Some methods also include uncertainty estimation to inform where to sample next (*avoid undesirable regions, target information-rich areas*).

Similar set of tools for operation and design (*with a few differences: parallel vs. serial acquisition, need for uncertainty-aware/safe optimization*)

Bayesian optimization / active learning / reinforcement learning
→ All learn iteratively via online interaction with the system

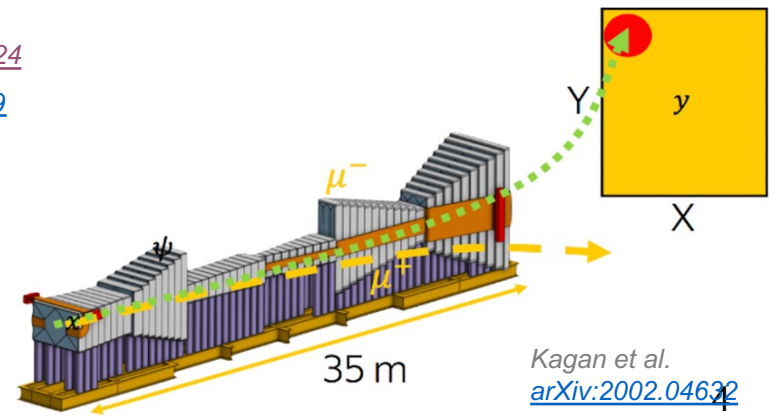


Faster multi-objective optimization with Bayesian optimization and iterated surrogate models

R. Roussel et al., [arXiv:2010.09824](#)
A. Edelen et al., [arXiv:1903.07759](#)

Output constraints learned on-the-fly
R. Roussel et al., [arXiv:2106.09202](#)

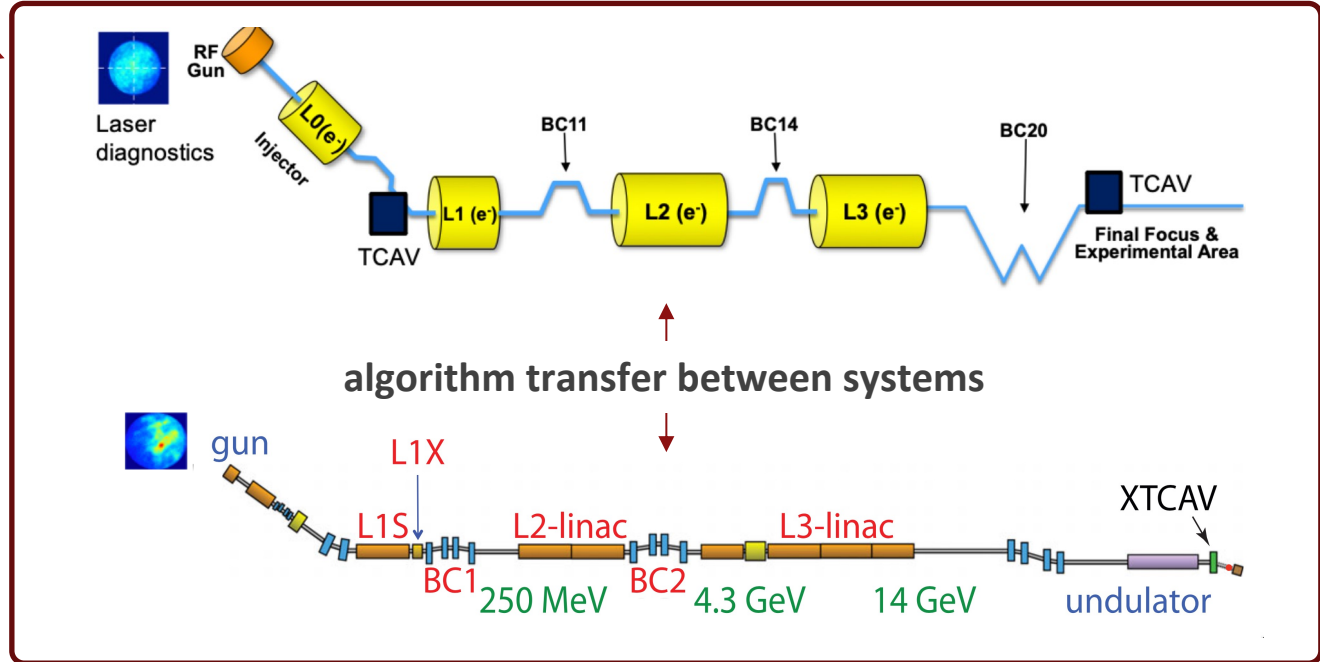
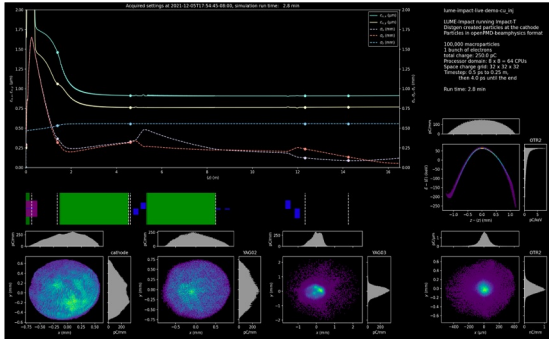
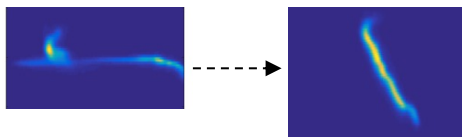
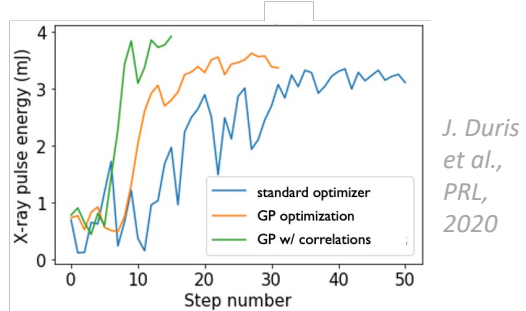
Local generative surrogates and gradient descent for the SHiP magnetic shield design



Kagan et al.
[arXiv:2002.04632](#)

Broad Set of Areas for ML to Impact Operation

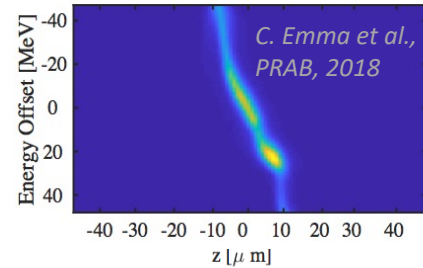
automated control + optimization



Data reduction/rejection (kHz/MHz data streams)
Event triggering

ML-enhanced diagnostics

(provide insight at faster rate, at higher resolution, non-invasively)

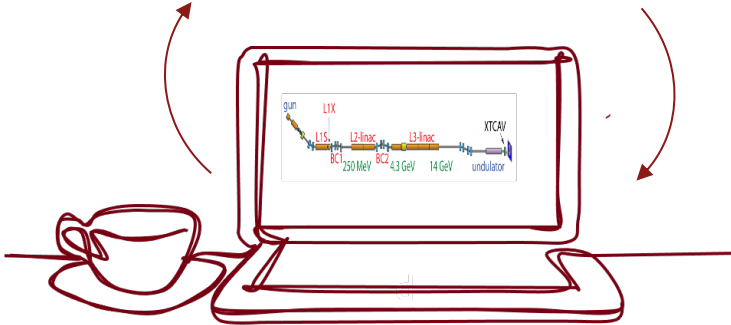
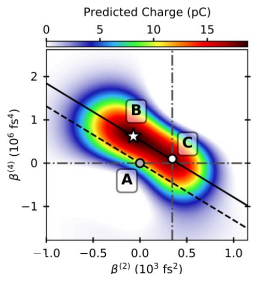


anomaly detection failure prediction

(plan maintenance; alert to changes in machine; alert to interesting science)

extract unknown relationships + correlations
(feed into future control / design)

R. Shaloo et al.
[arXiv:2007.14340](https://arxiv.org/abs/2007.14340)



digital twins + online modeling

(fast sims, differentiable sims, model calibration, model adaptation)

+ need uncertainty quantification for all
+ can incorporate physics information in all

Conclusions/Recommendations

- AI/ML are enabling broad-sweeping shifts in how accelerators and detectors are designed and operated
- Spans search for new experimental setups/designs, optimization of online systems, “seeing into” instrument operation in real time, opportunities for co-design with ML-based analysis and control techniques (e.g. placement and type of diagnostics given ML-based reconstruction capabilities)
- Modularly combining physics modeling and ML is promising area of research to improve generalizability, reduce reliance on large data sets, improve interpretability
- Broad need also for **edge compute** + ML (fast prediction, feedback, event triggering and data rejection/reduction)
- Other areas that need investment include improving **uncertainty quantification and domain adaptation, combining physics and ML** (differentiable simulations, inductive biases), **online adaptation and calibration of models/controllers** (both predictions and uncertainties), and **combining/scaling up methods** into a full integrated ecosystem
- Challenges/needs for design optimization and operation are broadly similar across systems: **need investment in open-source, community software tools and ecosystems → software/firmware infrastructure** in addition to underlying ML methods

Backups

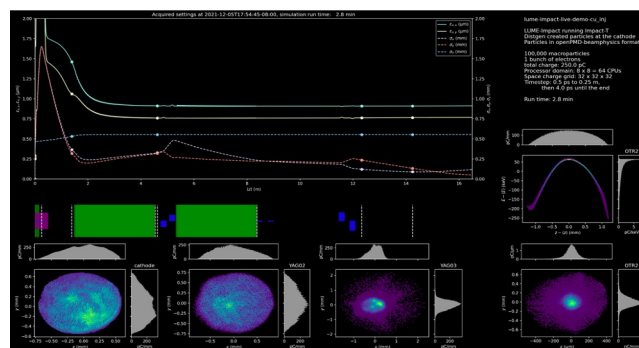
integrated development cycle

Fundamental
AI/ML Research

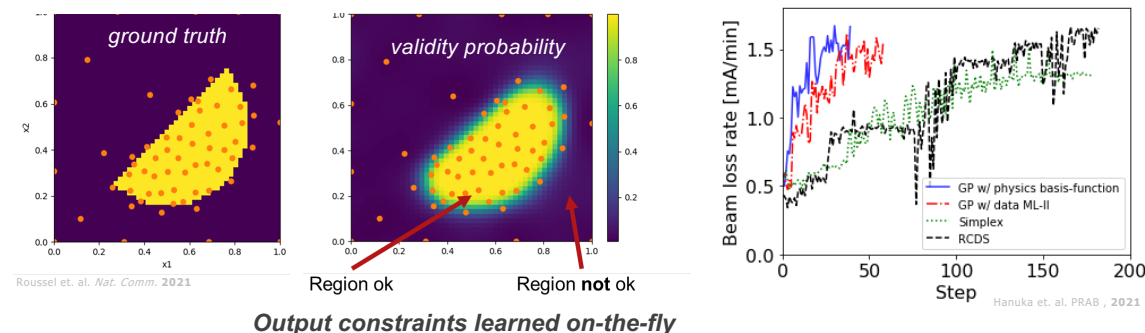
Software
Tools

Testing/Deployment
(offline and online)

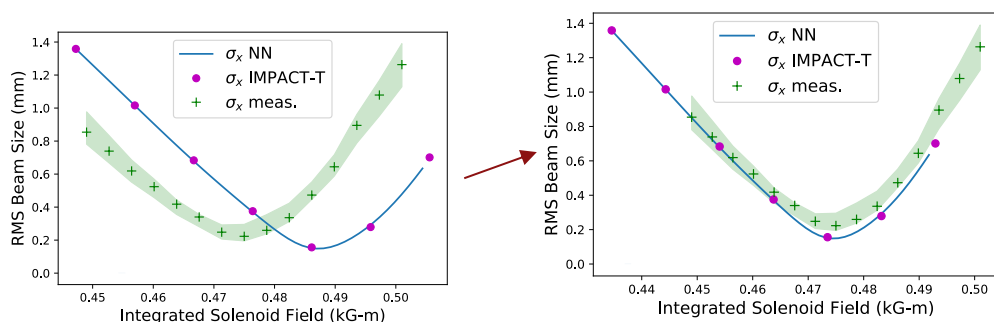
Online prediction with physics sims
and fast/accurate ML models



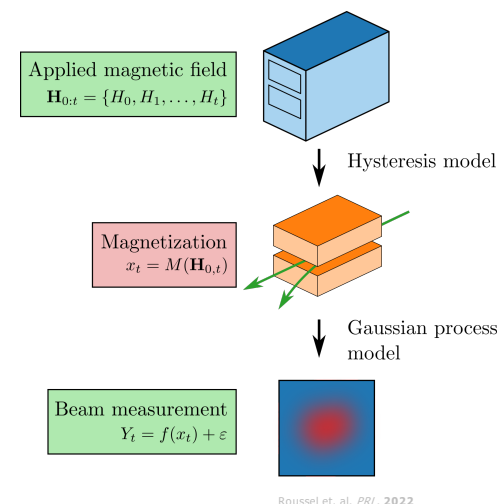
Efficient optimization and characterization (useful also for
simulation exploration/design, data generation)



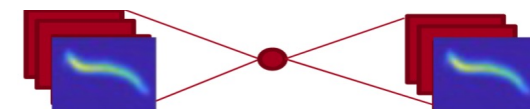
Adaptation of models and identification of sources
of deviation between simulations and as-built machine



Techniques for
combining
physics and ML (more
reliable/transferrable,
require less data, more
interpretable), including
differentiable
simulators



Representation learning
(e.g. better ways of modeling beams)



Software packages and
standards for data generation,
modeling, and optimization (LUME,
xopt)



Approaches can leverage different amounts of data/previous knowledge: suitable in different circumstances

less ← assumed knowledge of machine → more

Model-Free Optimization

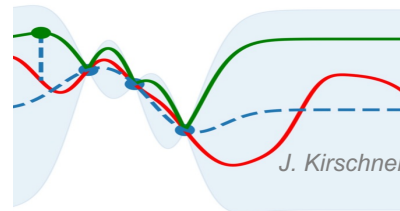


*Observe performance change
after a setting adjustment*

*→ estimate direction or apply
heuristics toward improvement*

gradient descent, genetic algorithms,
simplex

Model-guided Optimization

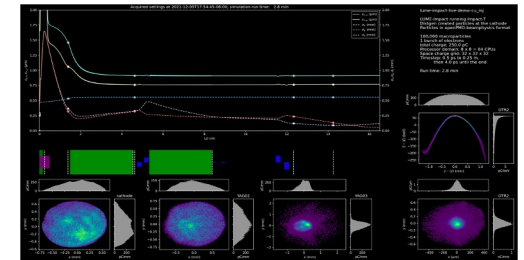


Update a model at each step

*→ use model to help select the
next point*

Bayesian optimization
reinforcement learning

Global Modeling



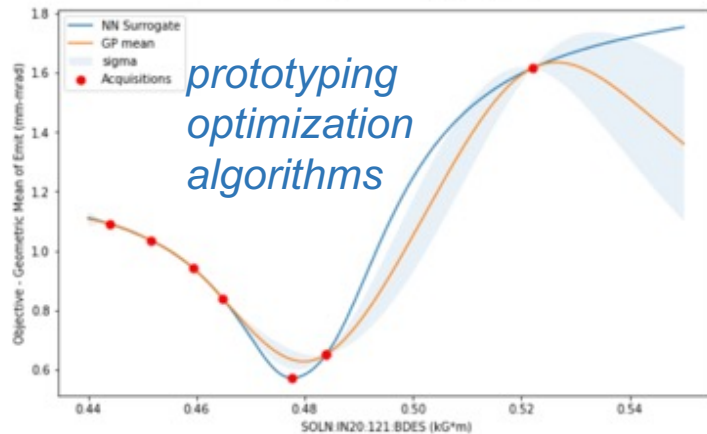
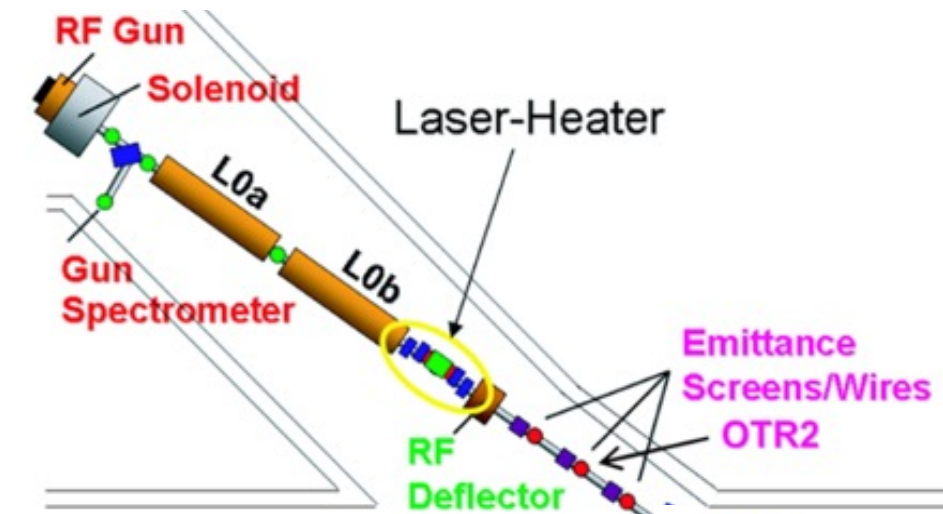
Make fast system model

*→ provide initial guess (i.e. warm
start) for settings*

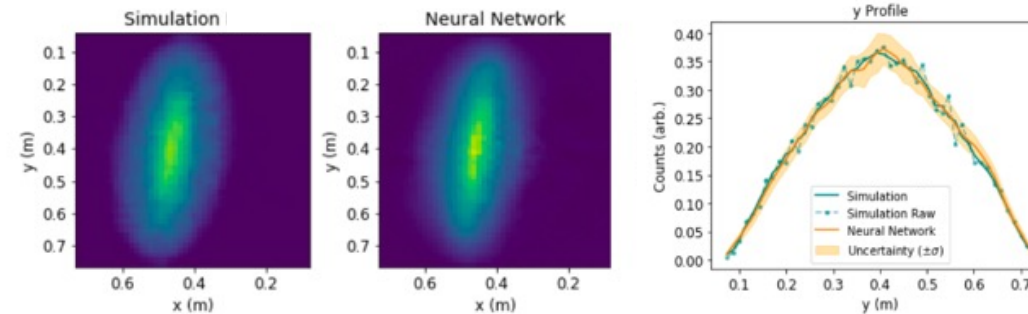
ML system models +
inverse models

Example: Injector Surrogate Models

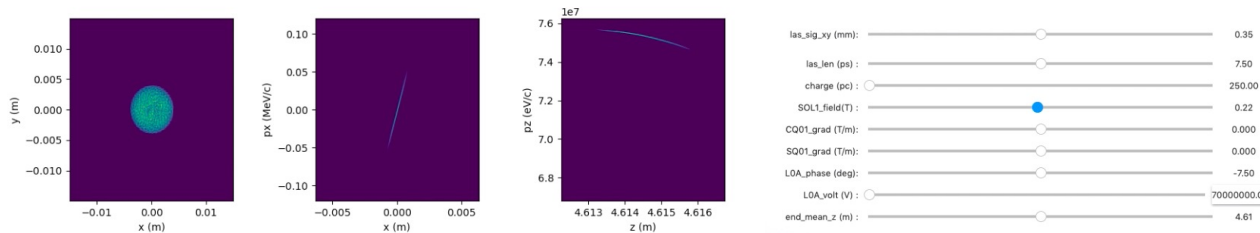
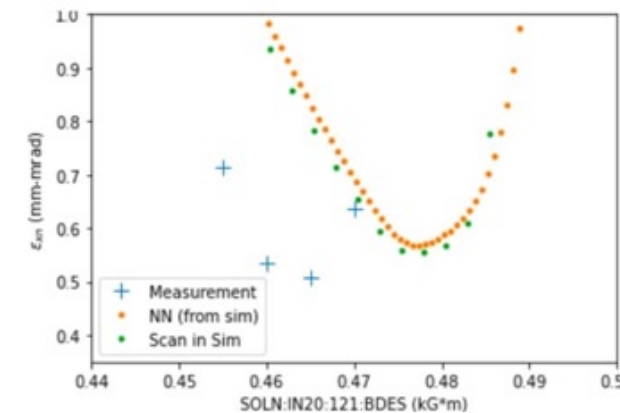
- ML models trained on physics simulations
- Inputs sampled widely across valid ranges
- Used to develop/prototype new algorithms before testing online at FACET-II and LCLS** e.g. *new Bayesian optimization methods, adaptive emittance measurement*



ML model provides accurate replication of simulation



Simulation and ML model trained on it are qualitatively similar to measurements



interactive model widget and visualization tools

ML models trained on simulations enable fast prototyping of new optimization algorithms → greatly reduces development time