

## OpenLoops 2

A new method to generate and reduce one-loop amplitudes

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## OpenLoops

- Fully automated numerical algorithm for tree and one-loop amplitudes [Cascioli, Lindert, Maierhöfer, Pozzorini]
- hybrid tree-loop recursion  $\Rightarrow$  very high speed
- NLO QCD and NLO EW corrections are fully implemented
- Publicly available at [openloops.hepforge.org](http://openloops.hepforge.org)

Third party tools for the tensor integral reduction to MIs and evaluation thereof:

- Collier [Denner, Dittmaier, Hofer '16], Cuttools [Ossola, Papadopoulos, Pittau '08]
- OneLoop [van Hameren '10]

Successful applications:

- used for NLO calculations for processes with  $\mathcal{O}(10^5)$  loop diagrams/channel
- used in several NNLO calculations e.g.  $(pp \rightarrow V_1 V_2, H H)$ ,  $V_i = \gamma, Z, W$
- interfaced to Sherpa, Powheg, Herwig, Whizard, Geneva, Munich, Matrix

## Long term goal of $2 \rightarrow 3$ NNLO automation and challenges

⇒ construction/reduction of 2-loops amplitudes

⇒ speed and stability of  $2 \rightarrow 4$  at NLO are crucial

### OpenLoops 2 [F.B., Lindert, Maierhöfer, Pozzorini, Zoller '17]

New one-loop approach that merges amplitude construction and reduction

#### OpenLoops 1

- relies on external reduction libraries
- high complexity at high tensor rank
- stability in the IR region for  $2 \rightarrow 4$  processes is challenging

#### OpenLoops 2

- integrand reduction merged with OpenLoops approach
- tensor rank  $\leq 2$  at any stage of the calculation
- stability issue can be addressed in the new reduction approach

# OpenLoops 1

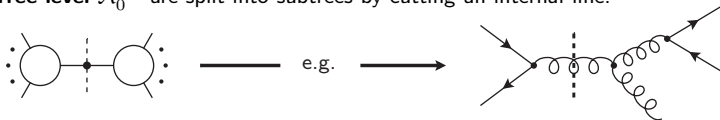
Tree level and one-loop amplitudes as sums of individual Feynman diagrams

$$\mathcal{M}_0 = \sum_d \mathcal{M}_0^{(d)}, \quad \mathcal{M}_1 = \sum_d \mathcal{M}_1^{(d)}$$

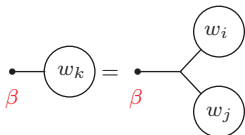
and each diagram is factorized into a **color factor** and a **color stripped amplitude**:

$$\mathcal{M}_l^{(d)} = c_l^{(d)} \mathcal{A}_l^{(d)}.$$

Tree level  $\mathcal{A}_0^{(d)}$  are split into subtrees by cutting an internal line:



Subtrees computed **numerically** via **recursive** merging: universal kernels  $\Rightarrow$  **automation**



$$w_k^\beta = \frac{X_{\gamma\delta}^\beta}{p_i^2 - m_i^2 + i\epsilon} w_i^\gamma w_j^\delta$$

Tensor representation of 1-loop diagrams

$$D_i = (q + p_i)^2 - m_i^2$$

$$\mathcal{A}_1^d = \text{Diagram} = \int d^D q \frac{\mathcal{N}(\mathcal{I}_N, q)}{D_0 D_1 \cdots D_{N-1}} = \sum_{r=0}^N \mathcal{N}_{\mu_1 \cdots \mu_r} \underbrace{\int d^D q \frac{q^{\mu_1} \cdots q^{\mu_r}}{D_0 D_1 \cdots D_{N-1}}}_{\text{fed to a tensor integral reduction library}}$$

One-loop diagrams  $\mathcal{A}_1^d$  are cut open and generated with hybrid tree-loop recursion

$$\mathcal{N}_N^{\alpha\beta}(q) \equiv \sum_{r=0}^N \mathcal{N}_{\mu_1 \cdots \mu_r}^{\alpha\beta} q^{\mu_1} \cdots q^{\mu_r} = \text{Diagram} = \text{Diagram}$$

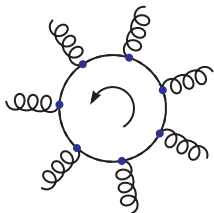
Recursive construction of tensor coefficients  $\Rightarrow$  very high speed

$$\mathcal{N}_N^{\alpha\beta}(q) = X_{N;\gamma\delta}^{\beta} \cdot w_N^{\delta} \cdot \mathcal{N}_{N-1}^{\alpha\gamma}(q)$$

$$\text{"segments"} \equiv \mathcal{X}_{N;\gamma}^{\beta}(q) = \left( Y_{N;\gamma\delta}^{\beta} + q^{\nu} Z_{N;\gamma\delta\nu}^{\beta} \right) w_N^{\delta}$$

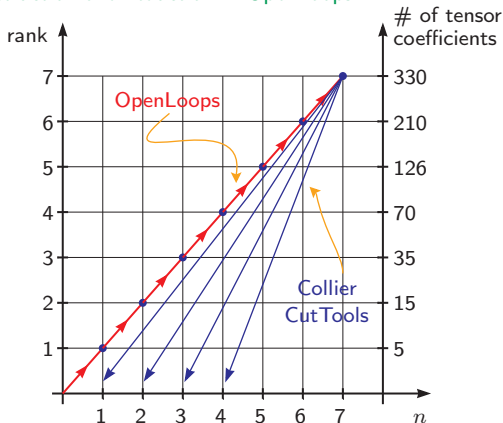
$$\text{Factorized expression} \Rightarrow \mathcal{N}_N(q) \simeq \mathcal{X}_N(q) \cdots \mathcal{X}_{k+1}(q) \mathcal{N}_k(q) = \prod_{k=1}^N \mathcal{X}_k(q)$$

## Interplay between amplitude construction and reduction in OpenLoops 1



Example of a 7g diagram

complexity grows exponentially  
 with tensor rank



Numerical **tensor integral reduction** to scalar integrals

$n$ : # of attached external legs

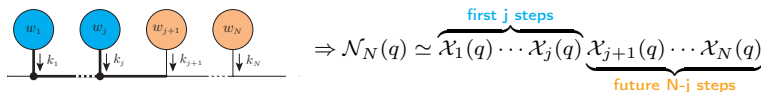




## OpenLoops 2

- exploits factorization properties of OpenLoops recursion
- performs an on-the-fly integrand reduction during amplitude construction
- keeps the rank  $\leq 2$  at any stage of the calculation

**Factorized** structure of  $N$ -point OpenLoops integrand.



The factorized representation in  $\mathcal{X}_j(q)$  allows for an *on-the-fly Reduction (OFR)*

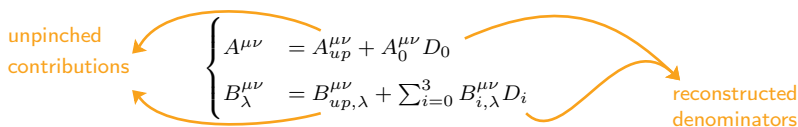
$$\frac{\mathcal{N}_N(q)}{D_0 \cdots D_N} = \frac{\mathcal{X}_1(q) \mathcal{X}_2(q) \cdots \mathcal{X}_j(q) \cdots \mathcal{X}_N(q)}{D_0 D_1 D_2 D_3 \cdots D_N},$$

integrand reduction applicable after any  $j \geq 2$  step (independently of future steps!)

**Integrand reduction** of  $\geq 3$ -point integrals with rank  $\geq 2$  [del Aguila, Pittau '05]

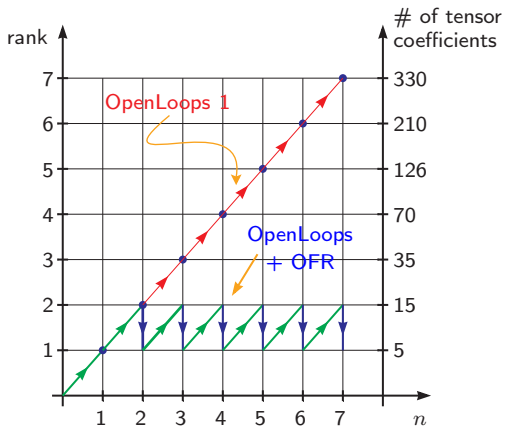
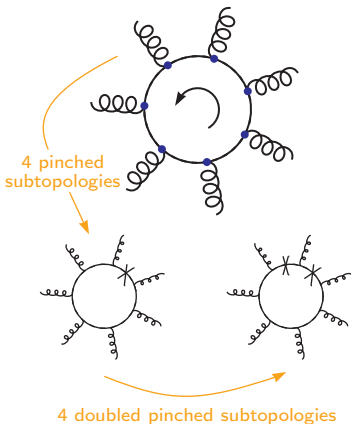
$$q^\mu q^\nu = A^{\mu\nu} + B_\lambda^{\mu\nu} q^\lambda$$

rank-2 monomials are **reduced to rank-1 on-the-fly**, i.e. at any OL construction step.



## Interplay between amplitude construction and reduction in OpenLoops 2

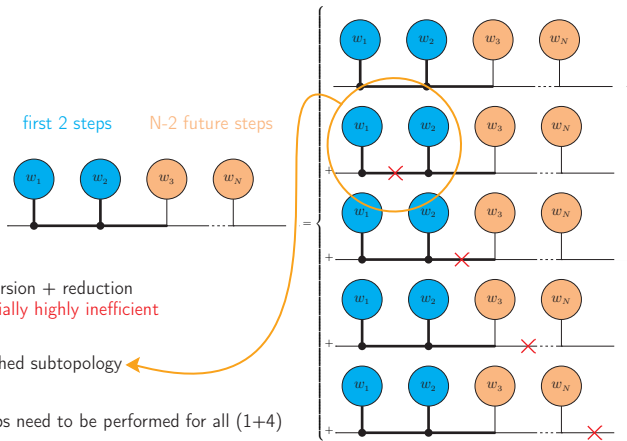
Example of a 7g diagram



complexity associated with tensor rank remains small

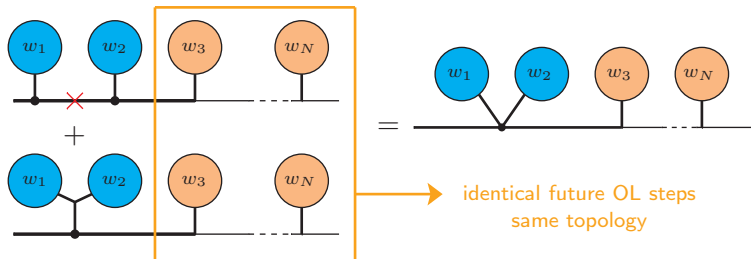
**Problem:** huge computational due to proliferation of subtologies from reduction

$$\underbrace{\mathcal{N}_k(q)}_{\text{rank}=2} = \underbrace{\mathcal{N}_{up}(q)}_{\text{rank}=1} + \sum_{i=0}^3 \underbrace{\mathcal{N}_i(q)}_{\text{rank}=1} D_i + \underbrace{\mathcal{N}_{R_1} \tilde{q}^2}_{\text{rational terms}}$$



### Solution: Diagrams Merging

Pinched subtopologies from the **on-the-fly reduction** of  $N$ -point open loops can be **merged** with unpinched  $(N - 1)$ -point open loops.



- The condition is two open loops sharing identical future steps and same topology.
- Recursive merging works for any tensor rank and can be iterated after any OpenLoops+OFR step

**OpenLoops+OFR opens the doors to a fast one-loop algorithm with low tensor rank!**

## CPU performance of OpenLoops 1 + Collier/Cuttools vs OpenLoops 2 with OFR

Runtimes ( $10^{-3}s$ ) per phase-space point. Helicity and color sums included. The last column shows the timing ratios between the fastest OL1 interface and OL2.

	OL1 (Collier)	OL1 (Cuttools)	OL2	OL1/OL2
$u\bar{u} \rightarrow t\bar{t}$	0.2355	0.4034	0.2385	0.99
$u\bar{u} \rightarrow t\bar{t}g$	4.259	7.066	3.828	1.1
$u\bar{u} \rightarrow t\bar{t}gg$	$1.154 \cdot 10^2$	$1.612 \cdot 10^2$	$0.7884 \cdot 10^2$	1.5
$gg \rightarrow t\bar{t}$	1.408	2.486	1.019	1.4
$gg \rightarrow t\bar{t}g$	35.03	50.23	23.32	1.5
$gg \rightarrow t\bar{t}gg$	$1.330 \cdot 10^3$	$1.519 \cdot 10^3$	$0.600 \cdot 10^3$	2.2
$u\bar{d} \rightarrow W^+g$	0.2972	0.6274	0.3349	0.89
$u\bar{d} \rightarrow W^+gg$	5.690	11.3	5.664	1.0
$u\bar{d} \rightarrow W^+ggg$	$1.787 \cdot 10^2$	$2.380 \cdot 10^2$	$1.142 \cdot 10^2$	1.6
$u\bar{u} \rightarrow W^+W^-$	0.2622	0.4140	0.1756	1.5
$u\bar{u} \rightarrow W^+W^-g$	8.528	12.04	7.145	1.2
$u\bar{u} \rightarrow W^+W^-gg$	$2.441 \cdot 10^2$	$2.817 \cdot 10^2$	$1.340 \cdot 10^2$	1.8

**Factor  $\sim 2$  speedup wrt OpenLoops 1 for nontrivial processes!**

# Numerical Stability

Integrand reduction formula for  $\geq 3$ -point functions of rank  $\geq 2$  [del Aguila, Pittau '05].

The main idea is to decompose  $q^\mu$  into a basis of lightlike  $l_i^\mu$ :

$$l_1^\mu = p_1^\mu - \alpha_1 p_2^\mu, \quad l_3^\mu = \bar{v}(l_1) \gamma^\mu \left( \frac{1 - \gamma^5}{2} \right) u(l_2), \quad l_{1,2} \cdot l_{3,4} = 0$$

$$l_2^\mu = p_2^\mu - \alpha_2 p_1^\mu, \quad l_4^\mu = \bar{v}(l_2) \gamma^\mu \left( \frac{1 - \gamma^5}{2} \right) u(l_1), \quad l_1 \cdot l_2 = -\frac{l_3 \cdot l_4}{4}$$

$$q^\mu = \frac{1}{\gamma} D^\mu - \frac{1}{2\gamma} Q^\mu$$

$$D^\mu = 2(q \cdot l_2) l_1^\mu + 2(q \cdot l_1) l_2^\mu$$

$$Q^\mu = (q \cdot l_4) l_3^\mu + (q \cdot l_3) l_4^\mu$$

$$\gamma = \frac{4\Delta}{p_1 \cdot p_2 \pm \Delta}$$

$\Delta$  - Gram Determinant

$(q \cdot l_j) \rightarrow D_i$

$$q^\mu q^\nu = A^{\mu\nu} + B_\lambda^{\mu\nu} q^\lambda$$

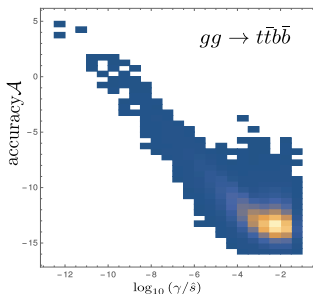
factors  $\sim \Delta^{-2}$   
 $\Rightarrow$  potential instabilities

$A^{\mu\nu}, B_\lambda^{\mu\nu}$  are functions of the  $p_j, j = 1, 2(3), \Delta$  and  $D_i$

$A^{\mu\nu}, B_\lambda^{\mu\nu}$  suffer from severe  $\gamma^{-2}$  instabilities



Clear and neat correlation of instabilities with Gram-determinants  $\Delta$  from individual parameters of the reduction.



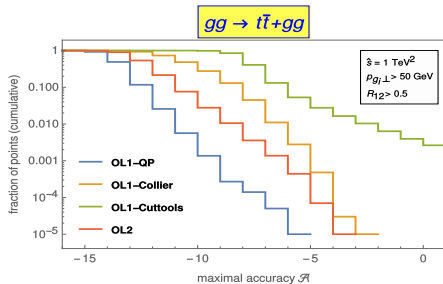
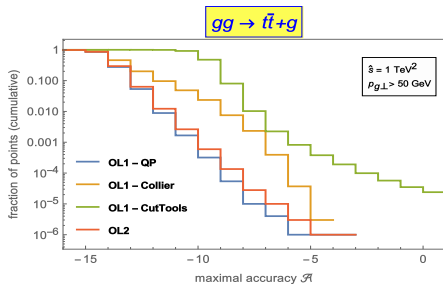
$$\gamma = \frac{4\Delta}{p_1 \cdot p_2 \pm \Delta}$$

→ correlation between the smallest  $\gamma$  for all Feynman diagrams and the number of accurate digits (wrt to a QP benchmark) for  $10^5$   $gg \rightarrow t\bar{t}b\bar{b}$  events

### Simple and powerful solution to numerical instability problems

- for  $N \geq 4$  integrals, there are 3 external momenta available in  $D_0 \cdots D_3$ : we choose the pair  $(p_1, p_2)$  with the largest  $\gamma \Rightarrow$  no  $\Delta$ -expansions needed.
- for  $N = 3$ ,  $\Delta$ -expansions are performed only in few special cases: analytic  $\sqrt{\Delta}$  expansions up to  $\mathcal{O}(\Delta)$  of full reduction to scalars.

Probability of **relative accuracy**  $\mathcal{A}$  or less (assessed wrt OL+Cuttools QP benchmarks with uniform random points)



Stability of OpenLoops 2 in double precision (DP)

- behaviour in the tails crucial for real-life applications
- orders of magnitude improvement wrt Cuttols in DP
- very significant improvement also wrt Collier in DP

**Excellent stability thanks to on-the fly reduction with rank  $\leq 2$  and minimal  $\Delta$ -expansions**

## Conclusions

We have presented the new **OpenLoops 2** algorithm for the automated generation of one-loop matrix elements in the Standard Model

- 1 the **generation and reduction of loop integrands are merged** in a single recursion that keeps the **tensor rank  $\leq 2$**  throughout
- 2 **merging pinched and unpinched open loops** avoids the proliferation of subtopologies and permits to reach **very high CPU performance**
- 3 the main sources of **numerical instabilities** have been understood and addressed with **simple and general solutions** that yield **very high stability**

## Backup Slides

- Benchmarks computed in quadruple precision (OL.1 + Cuttools)

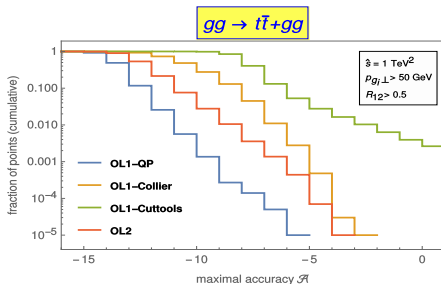
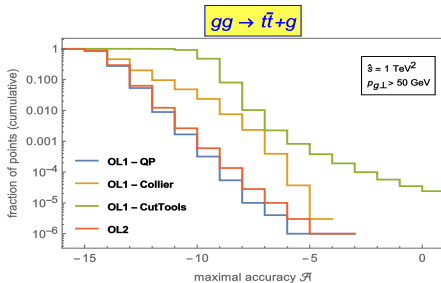
- The accuracy  $\mathcal{A}$  of a result  $r$  wrt to a benchmark  $b$  is defined as

$$\mathcal{A} = \log_{10} \left[ \text{Max} \left( \left| \frac{b-r}{r} \right|, \left| \frac{b-r}{b} \right| \right) \right]$$

- all other results are evaluated in DP.

### Stability plots:

Probability of accuracy of  $\mathcal{A}$  or less for two selected processes  $gg \rightarrow t\bar{t}g$  and  $gg \rightarrow t\bar{t}gg$  in samples of  $10^5$  and  $10^6$  uniformly distributed phase-space points respectively.



## Stability Studies:

The stability of the QP benchmarks is assessed through a rescaling test: at a given phase space point one-loop matrix elements are recomputed by rescaling all dimensionful input parameters by a factor  $\xi \Rightarrow$

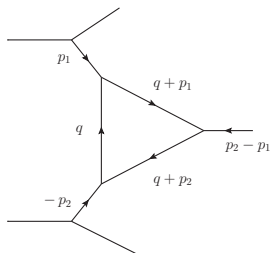
$$\mathcal{M}_R \equiv \mathcal{M}(\xi p_i, \xi m_i) = \xi^d \mathcal{M}(p_i, m_i) \Rightarrow |\mathcal{M}_R|^2 = \xi^{2d} |\mathcal{M}|^2$$

The intrinsic accuracy of the QP benchmark  $\mathcal{A}_{QP}$  is then:

$$\mathcal{A}_{QP} = \log_{10} \left[ \text{Max} \left( 1 - \xi^{2d} \frac{|\mathcal{M}|^2}{|\mathcal{M}_R|^2}, 1 - \xi^{-2d} \frac{|\mathcal{M}_R|^2}{|\mathcal{M}|^2} \right) \right]$$

The accuracy of the DP results is assessed comparing the latter with the QP benchmarks.

## Targeted expansions in the Gram determinant $\Delta$ . A special case



- $p_1^2 = -p^2, \quad p_2^2 = -p^2(1 + \delta)$
- $(p_2 - p_1)^2 = 0$
- $\sqrt{\Delta} = \frac{p^2}{2}\delta \Rightarrow \gamma = -p^2\delta^2$

In the reduction one has  $\gamma^{-2}$  factors at each step.

When  $\delta \ll 1$ , severe  $\frac{1}{\delta^4}$  instabilities show up.