Mathematics of Multi-Scale Loop Integrals

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- Precision physics requires quantum corrections, hence Feynman integrals.
- Standard method for the calculation of Feynman integrals: Differential equations and integration-by-parts identities.
- Solving a differential equation requires boundary data. This is a simpler problem (less scales).

The method of differential equations

- "Calculation" of Feynman integrals: Express a Feynman integral as a linear combination of standarised iterated integrals (multiple polylogarithms, elliptic multiple polylogarithms, iterated integrals of modular forms, ...).
- This is easy if differential equation is of the form

$$[d + \varepsilon A(x)]I(\varepsilon, x) = 0,$$

e.g. A(x) independent of ε and has only simple poles.

- In order to get to this form, we may
 - transform the basis of master integrals I' = UI (this is like a gauge transformation)
 - transform the kinematic variables $x \rightarrow x'$ (this is like a general coordinate transformation)

Outlook

- All we need to know to compute a Feynman integral are the right transformations I' = UI and $x \rightarrow x'$.
- Sounds easy, but it isn't.
- Mathematics comes to our help: We are dealing with a problem from algebraic geometry:
 - Multiple polylogarithms: Moduli space $\mathcal{M}_{0,n}$ of a punctured Riemann sphere.
 - Elliptic multiple polylogarithms: Moduli space $\mathcal{M}_{1,n}$ of a punctured torus.

Be cautious

• At one-loop we only have $Li_1(x)$ and $Li_2(x)$. The naive generalisation is

 $\operatorname{Li}_n(x)$.

This is not enough. We need at genus zero

 $\operatorname{Li}_{n_1,\ldots,n_k}(x_1,\ldots,x_k).$

• At the current state-of-the-art we have iterated integrals related to the moduli spaces $\mathcal{M}_{0,n}$ and $\mathcal{M}_{1,n}$. The naive generalisation is

 $\mathcal{M}_{g,n}$.

We expect this not to be enough. We might need to go beyond moduli spaces of curves to moduli spaces of surfaces and beyond.

Cartoons

• QFT:



• Strings:



• Mathematics:

