

Flux shape uncertainties in cross-section data & model comparisons

CEWG Meeting

2020-11-02

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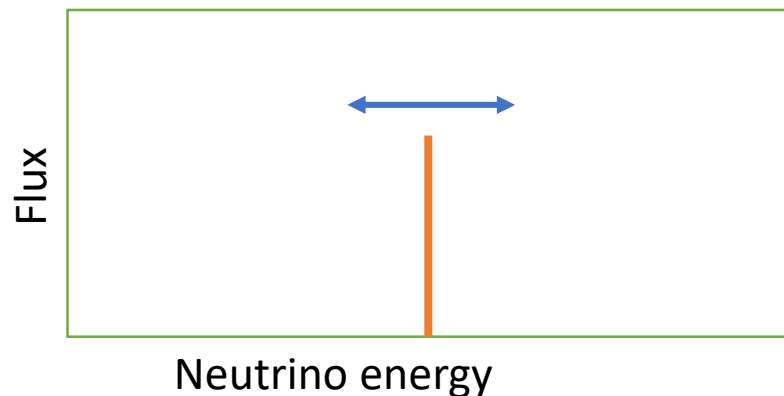


- Cross section measurements are “flux integrated”
 - Measured cross sections are valid only for a specific neutrino flux
- Unfolding procedure uses flux uncertainty to evaluate effect on results → part of covariance matrix
- Models use nominal flux for cross-section predictions
 - As far as I know
- χ^2 is calculated using nominal model prediction and covariance matrix
 - Assumption: Flux uncertainties are included in covariance matrix

$$\sigma = \frac{N}{\epsilon\Phi T}$$

- Claim: Flux shape uncertainty is not (fully) included in the covariance matrix of the unfolded result when doing model comparisons
- Instructive example: “perfect” 1-bin measurement
 - All efficiencies perfectly flat
 - No background
 - Monochromatic neutrino beam with perfectly known intensity
 - Only systematic uncertainty is neutrino energy

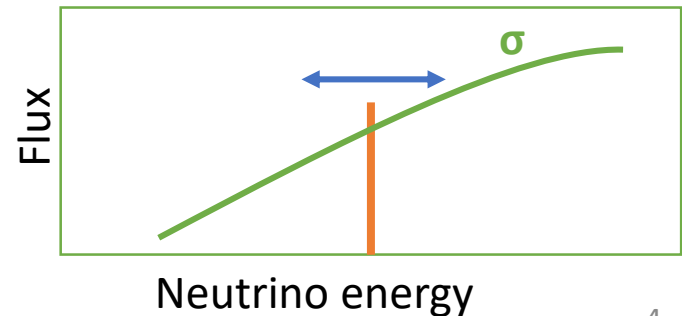
$$\sigma = \frac{N}{\epsilon\Phi T}$$



- Variation of beam energy does not vary the result!

$$\sigma = \frac{N}{\epsilon\Phi T} \underset{\text{syst.var.}}{=} \text{const}$$

- Systematic uncertainty of result = 0
- Result is still correct
 - We know the flux integrated cross section very well
 - We just do not know the flux shape very well
- When using only nominal flux for model comparison the flux shape uncertainty is ignored
 - Simple example: cross section proportional to E
 - Should introduce an additional uncertainty proportional to neutrino energy uncertainty



- Measurement provides best guess at cross-section integrated over the *real* flux profile
- Model predictions are calculated using the *nominal* flux profile
- Difference between nominal and real flux shapes is not taken into account when comparing the two
 - What we measure and what we compare it to are different things!
- Perfect monochromatic beam example:
 - Measurement: $\sigma(E_{\text{real}})$, well known
 - Model: $\sigma(E_{\text{nominal}})$, perfectly known
 - $\Delta E = E_{\text{real}} - E_{\text{nominal}}$, not well known, ignored in comparison

- **1st Approach**

- Measure XSEC in (unknown) *real* flux
- Provide flux & covariance w/ XSEC correlations
- Propagate shape uncertainties in model predictions
- Extra work at point of model comparison
- ☹️

$$\sigma = \frac{N(\boldsymbol{\theta}, \phi)}{T(\boldsymbol{\theta})\Phi(\phi)}$$

- **2nd Approach**

- Measure XSEC in fixed *reference* flux
- Use varied assumed real flux to extrapolate measurement to reference flux
 - Needs a XSEC model to do so
- Degrades discrimination power of measurement
 - By covering different E-dependences
- Also ☹️

$$\sigma' = \frac{N(\boldsymbol{\theta}, \phi')}{T(\boldsymbol{\theta})\Phi(\phi')}$$

$$\sigma' = \frac{N(\boldsymbol{\theta}, \phi)}{T(\boldsymbol{\theta})\Phi(\phi')} \frac{N_{\text{MC}}(\boldsymbol{\theta}, \phi')}{N_{\text{MC}}(\boldsymbol{\theta}, \phi)}$$

- Comparing a first-approach result with a model at only a single flux (as you would do with a second-approach measurement) is wrong!
 - It ignores flux shape errors
 - Amount of wrongness depends on size of flux shape effect compared to all other uncertainties → non-negligible!
 - Extra ☹ ☹ ☹ ☹
- Tried to figure out how to do first-approach and second-approach measurements with fitted and “classical” unfolding schemes

- → [\[arXiv:2009.00552\]](https://arxiv.org/abs/2009.00552) ←

- Includes “recipes” we hope can be adapted to many different experiments

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- Pretty confident about the how
 - → [\[arXiv:2009.00552\]](https://arxiv.org/abs/2009.00552)←
- Now need to decide on the what
- What kind of results do we want to release?
- What kind of results do our “customers” need/want?
- Four kinds of unfolded results to choose from:
 - Regularised vs unregularized
 - 1st approach vs 2nd approach

- Regularised
 - Introduces some bias
 - Depending on regularisation strength
 - Allows (some) visual interpretation of results
- Unregularised
 - Unbiased
 - Visual interpretation of result often not reliable
 - Strong bin-to-bin anticorrelations
 - Need to use provided covariance matrix to draw conclusions

- 1st approach (XSEC in real flux)
 - No model-dependent flux corrections
 - Allows direct comparison of *measurements* in same flux
 - Model predictions need flux uncertainty
 - E.g. calculate prediction for many flux throws
 - Would need to be correlated to XSEC covariance!
 - At least if there is considerable flux shape error in the result
- 2nd approach (XSEC extrapolated to reference flux)
 - Less work for model builders
 - Need only one prediction in single reference flux
 - Model-dependent flux extrapolation
 - Uses neutrino-energy dependence of the model
 - Reduced statistical power
 - Need to cover different possible energy-dependencies
 - Any model only has one specific dependency
 - The others add “unnecessary” contributions to the covariance

4 kinds of XSEC results summary

	1 st approach	2 nd approach
Unregularised	<ul style="list-style-type: none">Least biasBest powerNo chi-by-eyeMost difficult to use and interpret	<ul style="list-style-type: none">No regularisation biasNo chi-by-eyeFlux extrapolation biasDiminished power
Regularised	<ul style="list-style-type: none">Good powerNo extrapolation biasRegularisation biasModels need flux uncertainty	<ul style="list-style-type: none">Easiest to use and interpret (by eye)Most biasLeast power

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Most old results

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- What do we want to provide in the future?
 - More than 2 versions of same measurement too confusing?
 - One pretty and one technical result? R2 and U1?
 - U1 too complicated? U2 instead?

- Both approaches need a corresponding flux release
 - Either “best fit” parameters or nominal
- 1st approach measurements also need a public flux covariance matrix
 - Either “post fit” or “pre fit” (nominal)
 - Needs to be correlated with XSEC result!
 - Each XSEC result needs to provide its own XSEC-flux covariance matrix

- “All our model comparisons are wrong”
 - But *how* wrong?
- Flux shape has some influence on result
 - Efficiencies are not perfectly flat
 - BG depends on flux shape
 - Adds “something” to covariance matrix
- Flux shape is not dominant systematic (probably?)
 - Has flux shape effect on model predictions been tested?
- Reality somewhere between “effect of flux shape is completely negligible” and “our χ^2 are completely wrong”
 - How do we know where we are?
 - See Stephen’s presentation



Questions?

*The messenger
requests that he
please not be shot.*

Comments?

Backup

- Perfect two-bin measurement
 - 2 flux bins, 2 corresponding signal bins, no smearing, no inefficiency
 - Only flux and template weights

$$N_j = N_j^0 \phi_j c_j \quad j = 1, 2$$

- Fitter will adjust weights to make N_j fit the data
 - Every change in flux weight can be compensated by template weights \rightarrow flux and template weights are anti-correlated
 - Constraint of weights comes only from flux prior
- Resulting best fit point and covariance describe what parameter combinations are compatible with the data

- Flux integrated XSEC extracted by drawing from post-fit parameters and calculating

$$\sigma_j = \frac{N_j}{T\Phi} = \frac{N_j^0 \phi_j c_j}{T(\Phi_1^0 \phi_1 + \Phi_2^0 \phi_2)}$$

- Each throw corresponds to one possible reality or universe
- Number of events N_j is almost constant by construction
- If total flux Φ is also constant, error on XSEC is small($\rightarrow 0$)
 - $\sigma_j :=$ Flux integrated XSEC in real flux
 - Flux and template weight uncertainties cancel
 - Don't care what real flux actually is
 - Correct result, but cannot be compared to model without model flux variations
 - Problem: How to not double count flux variations?

- $\sigma_j \rightarrow \sigma'_j :=$ Flux integrated XSEC in best fit flux
 - Cross section in specific flux “once removed from reality”
 - Do care about what the real flux actually is
 - Would allow direct comparisons of models @ best fit flux
- For each throw (possible reality) calculate XSEC at that flux

$$\sigma'_j = \frac{N'_j}{\Phi'} = \frac{N_j^0 \phi'_j c_j}{\Phi_1^0 \phi'_1 + \Phi_2^0 \phi'_2} = \sigma_j \frac{\Phi}{\Phi'} \frac{\phi'_j}{\phi_j}$$

- Ignore thrown flux weights ϕ
- Set flux weight in calculation to best fit value ϕ'
- Best fit point is identical by definition ($\phi' = \hat{\phi}$)
$$\hat{\sigma}'_j = \hat{\sigma}_j$$
- Covariance is different, as flux and template weights no longer cancel

$$\text{cov}(\sigma') \neq \text{cov}(\sigma)$$

- $\sigma_j' \rightarrow \sigma_j'' :=$ Flux integrated XSEC in nominal flux
 - Cross section in specific flux “twice removed from reality”
 - Do care about what the real flux actually is
 - Would allow direct comparisons of models @ nominal flux
- For each throw (possible reality) calculate XSEC at that flux

$$\sigma_j'' = \frac{N_j''}{\Phi''} = \frac{N_j^0 \phi_j'' c_j}{\Phi_1^0 \phi_1'' + \Phi_2^0 \phi_2''} = \sigma_j \frac{\Phi}{\Phi''} \frac{\phi_j''}{\phi_j}$$

- Ignore thrown flux weights ϕ
- Set flux weight in calculation to nominal value ϕ''
- Best fit point is different from other results ($\phi'' \neq \hat{\phi}$)

$$\hat{\sigma}_j'' \neq \hat{\sigma}_j' = \hat{\sigma}_j$$
- Covariance is different

$$\text{cov}(\sigma'') \neq \text{cov}(\sigma') \neq \text{cov}(\sigma)$$
- Are fit results for parameters still valid there?

- Fitter is doing what it is supposed to:
 - Finding parameter sets that are compatible with reality
- Each post-fit throw of the fit parameters corresponds to one possible/plausible reality
- Currently we calculate the flux integrated XSEC as it would be in each reality, i.e. with that reality's flux
 - Good for finding the real flux integrated XSEC
 - Bad for comparing with the flux integrated XSEC at a specific flux
- We should calculate the flux integrated XSEC at a specific flux, i.e. extrapolate from those realities' fluxes to the specific one
 - Can be done by using specific flux parameters in XSEC calculation
- That specific flux should probably be the best fit flux, as that is the point where the parameters and covariance are valid

- Fixing the flux parameters in the XSEC calculation is not the same as saying “we assume this to be the real flux”
- Former:
 - We are as ignorant about the real flux as ever
 - We want to calculate the XSEC as it would be in the specific flux
 - Base for extrapolation are the possible fluxes in each throw
- Latter:
 - We assume we know our real flux
 - Would also fix the template weights as they are anticorrelated
 - Nothing gained in terms of flux error

- The conceptual difference between the presented XSEC definitions is subtle
 - Can be easily confused when not being very careful
- How do we now what our old measurements did?
- How can we know what other experiments did?
- First rule of thumb test:
 - Do they calculate the XSEC using the varied flux in each toy/throw/reality/universe directly?
→ Probably affected by this
 - Do they extrapolate from the varied flux to a specific flux?
→ Probably not affected by this

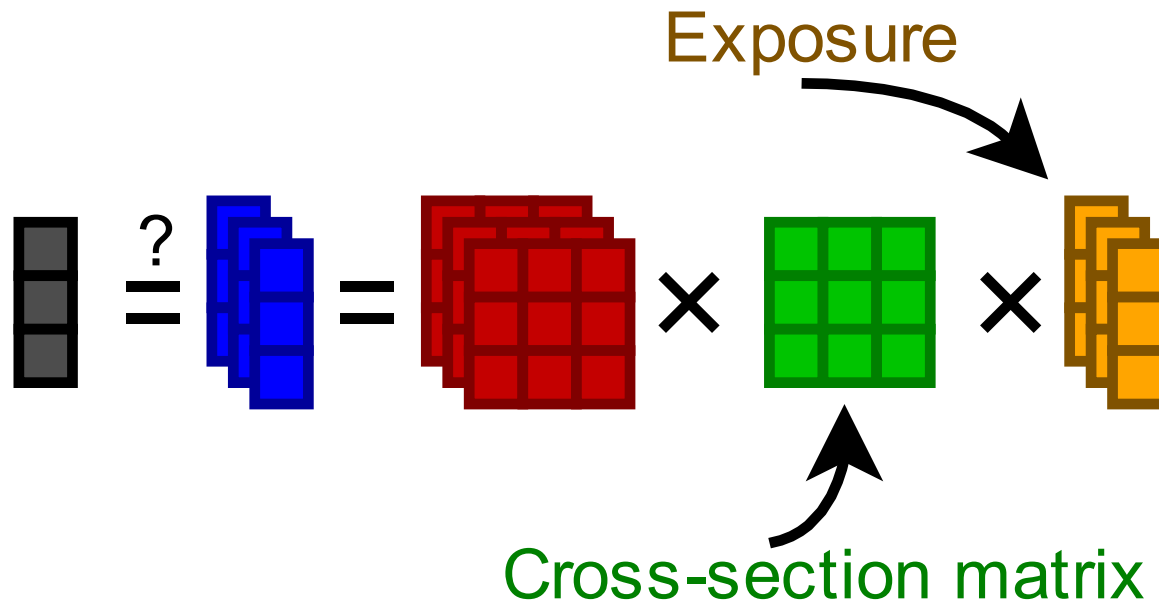
- In a realistic measurement there is smearing and other systematic parameters
- Average analysis bin weight becomes function of underlying parameters (detector, model, flux, ...)

$$N_j = N_j^0 w_j(d_a, m_b, \phi_c) c_j$$

- Can no longer scale results with flux weights only

$$\sigma_j = \frac{N_j}{\epsilon_j T \Phi} = \frac{N_j^0 w_j(d_a, m_b, \phi_c) c_j}{\epsilon_j (d_a, m_b, \phi_c) T \Phi(\phi_c)}$$

$$\sigma_j' = \frac{N_j'}{\epsilon_j' T \Phi'} = \frac{N_j^0 w_j'(d_a, m_b, \phi_c') c_j}{\epsilon_j' (d_a, m_b, \phi_c') T \Phi'(\phi_c')} = \sigma_j \frac{\Phi}{\Phi'} \frac{w_j'}{w_j} \frac{\epsilon_j}{\epsilon_j'}$$



- Model predicts **cross section** for each flux bin
- Provide set of **flux exposures** according to uncertainties
 - Exposure = flux \times time \times target mass
- Flux and detector uncertainties can be correlated
 - Make one **response matrix** correspond to one **exposure vector**