



# 4D trackers for future collider experiments

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*CPAD Instrumentation Frontier Workshop 2021*

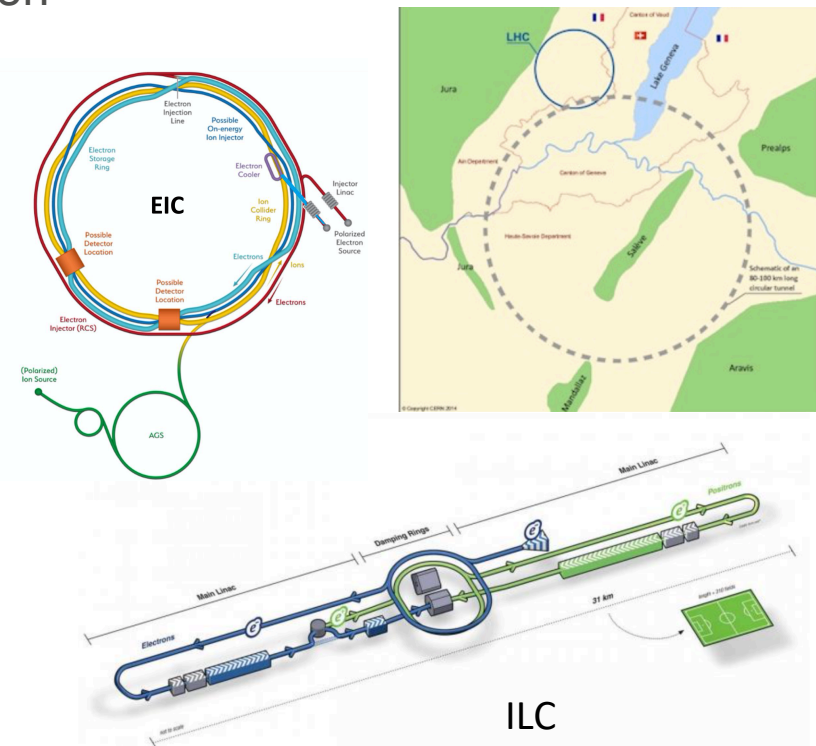
*March 18, 2021*

# Future trackers will be 4D!

- The 4D-trackers will play a key role at the future machines
  - Reduce backgrounds, track reconstruction, triggering all will need precision timing information, in addition to the precision position
  - Enhanced capabilities: PID and LLP reconstruction
  - All of these pose unique challenges, and opportunities to detector and electronics design, and event reconstruction

Measurement	Technical requirement
Tracking for $e^+e^-$	Granularity: $25 \times 50 \mu\text{m}^2$ pixels
	$5 \mu\text{m}$ single hit resolution
	Per track resolution of 10 ps
Tracking for 100 TeV pp	Generally the same as $e^+e^-$
	Radiation toleran up to $8 \times 10^{17} \text{ n/cm}^2$
	Per track resolution of 5 ps

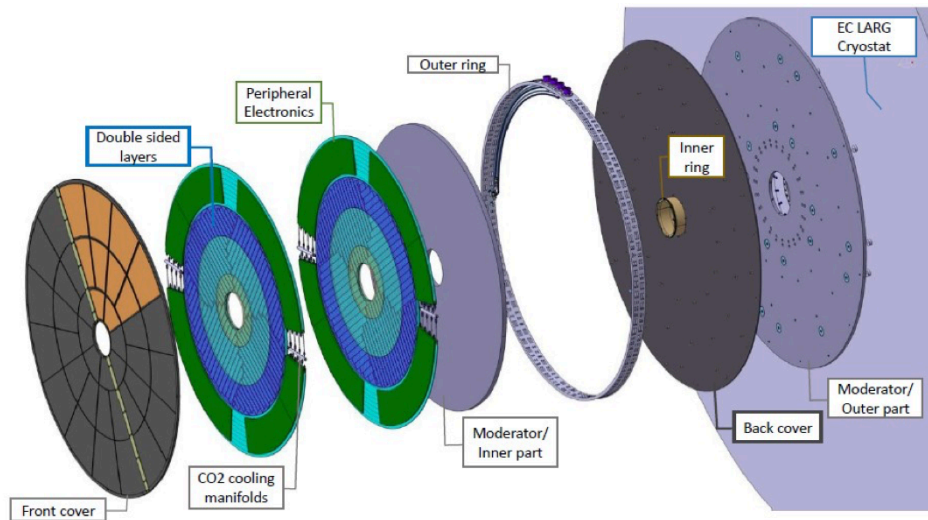
Technical requirements for future trackers:  
from [DOE's HEP BRN](#)



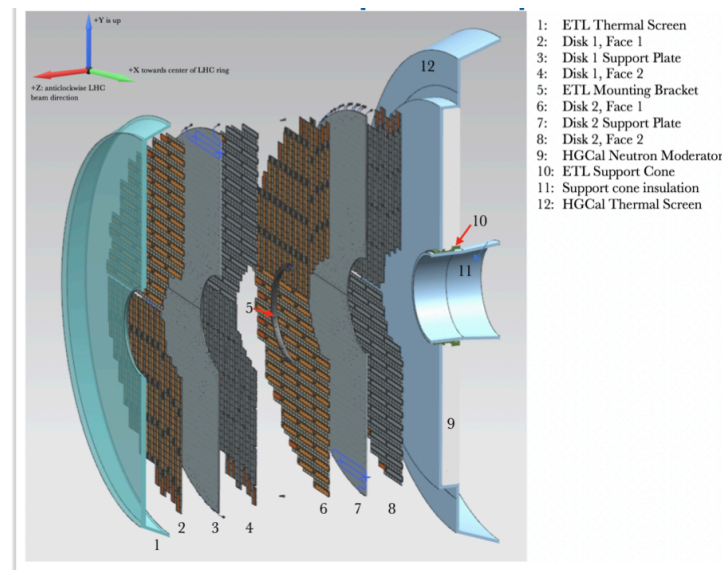


# 4D trackers: present and future

- CMS and ATLAS are building Gen-1 4D-tracking detectors
  - Single or two hits per charged particle, and large pixels
  - Next generation detectors will be more sophisticated and replace tracker
- Active R&D on technologies to achieve the required detector performance
  - Sensors, ASIC, front-end electronics developments



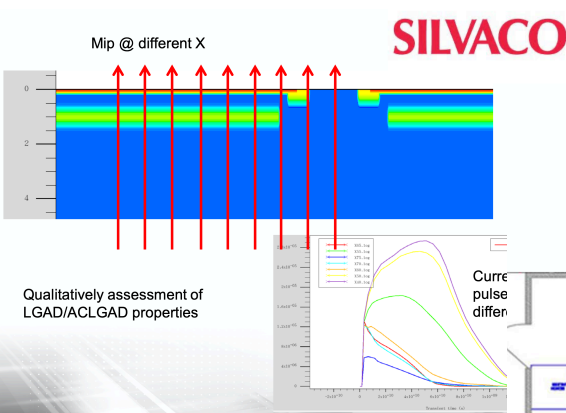
ATLAS timing detector



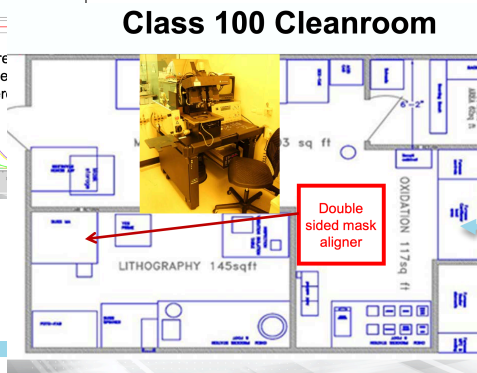
CMS timing detector

# Development directions

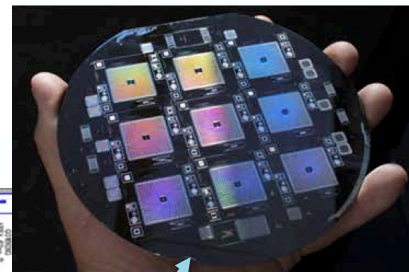
- Next gen detector R&D requires a lot of infrastructure, expertise, and development cycles
  - Our group has developed dedicated **readout boards and testing infrastructure** for characterization of sensor prototypes,
  - Design, manufacture and test **sensor prototypes**
  - Design, manufacture and test **full systems** integrating sensors and readout electronics



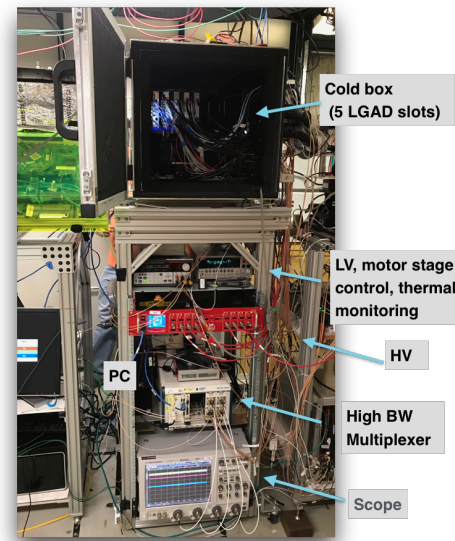
Design



Finish Processed Wafer



Fabrication



Testing in beams

# Development directions

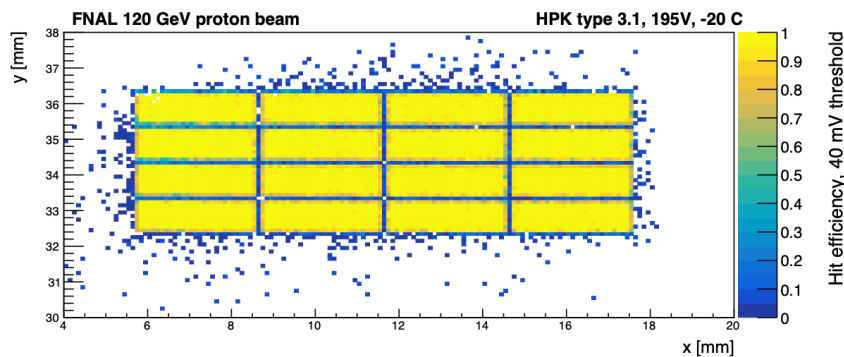
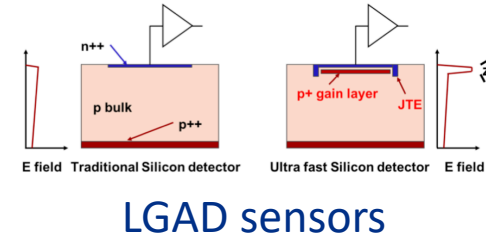
- **International collaborative developments**
  - Development of AC-LGAD sensors and 4D trackers
  - Characterization of irradiated and pre-rad sensors, extensive infrastructure with monitoring all key variables
- Work presented here is based on Snowmass LOI #142 in IF, and US-Japan collaborative consortium
  - A. Apresyan, K. Di Petrillo, R. Heller, R. Lipton, S. Los, C. Madrid, C. Pena, S. Xie, T. Zimmerman (**FNAL**)
  - G. D'Amen, W. Chen, G. Giacomini, E. Rossi, A. Tricoli (**BNL**)
  - K. Nakamura, K. Hara, T. Ueda, S. Kita (**KEK, U. Of Tsukuba**)
  - S. Mazza H. Sadrozinski, B. Schumm, A. Siden (**UCSC**)
  - Y. Degerli, F. Guilloux, C. Guyot, J.P. Meyer, A. Ouraou, P. Schwemling (**Saclay**)



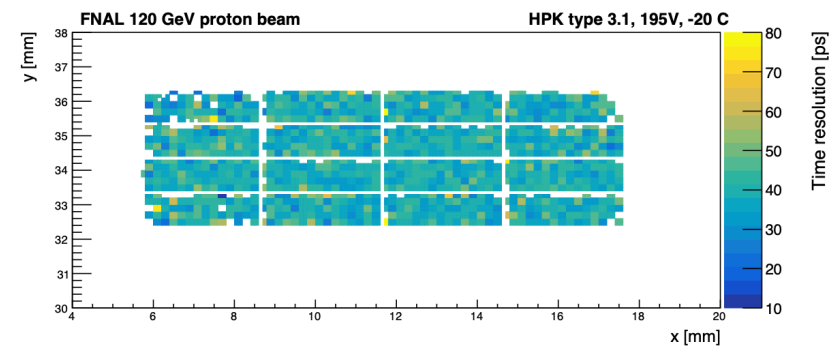


# Low-Gain Avalanche Detectors (LGAD)

- Low-Gain Avalanche Detectors (LGAD):  
technology for HL-LHC timing detector:  $\sim 30$  ps
  - Silicon detectors with internal gain
- Sensors developed for CMS and ATLAS show high degree of uniformity and excellent time resolution
  - Gain is uniform within  $\sim 5\%$ , high yield, radiation tolerance for HL-LHC
  - No-gain gaps between pixels: due to presence of JTE



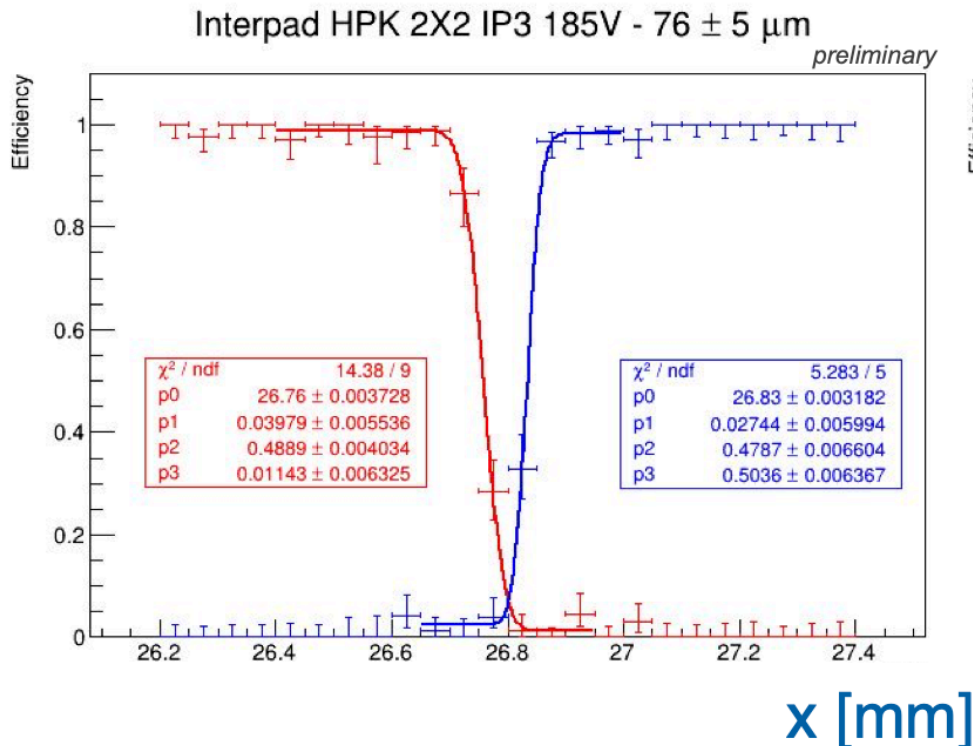
Hit efficiency across surface of the 4x4 sensor



Time resolution across surface of the 4x4 sensor

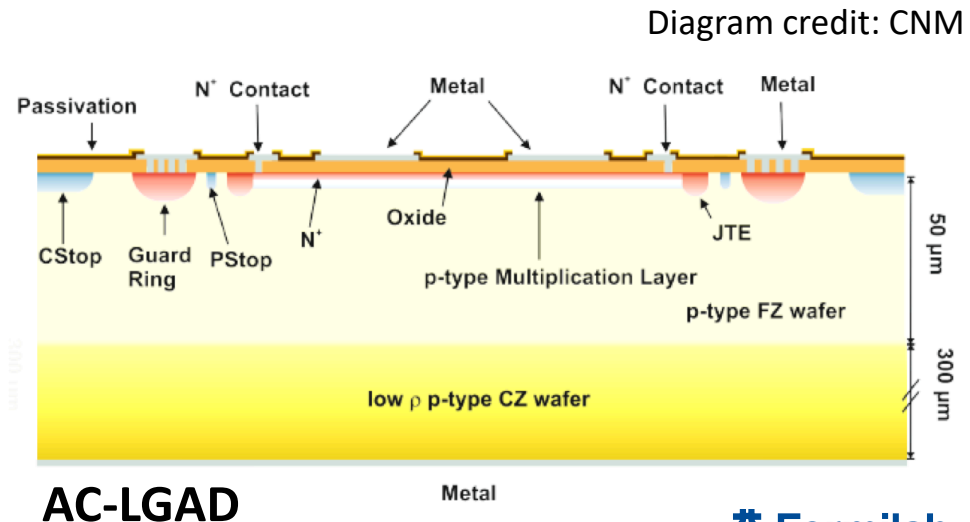
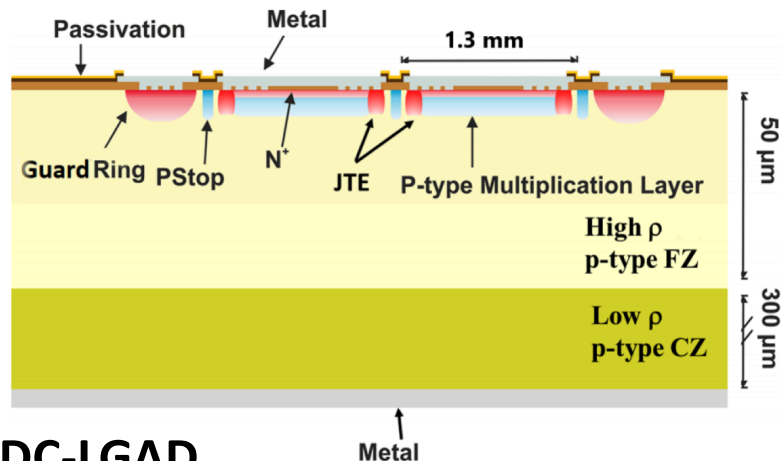
# Low-Gain Avalanche Detectors (LGAD)

- **Sensors for 4D-trackers should have no dead areas**
  - Traditional LGADs have a gap between pixels, to terminate the field between pixels
  - Improve Gen-1 trackers to achieve 100% fill factor, high position resolution



# AC-coupled LGADs

- Ongoing R&D to eliminate dead area
  - Simultaneously improve position resolution via charge sharing
- Collaboration with BNL, KEK on AC-LGAD developments
  - 100% fill factor, and fast timing information at a per-pixel level
  - Signal is still generated by drift of multiplied holes into the substrate and AC-coupled through dielectric
  - Electrons collect at the resistive n+ and then slowly flow to an ohmic contact at the edge.



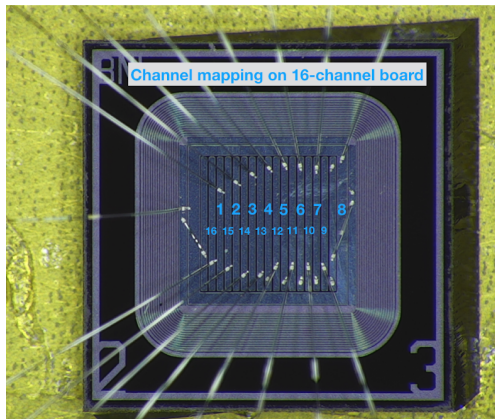
DC-LGAD

AC-LGAD

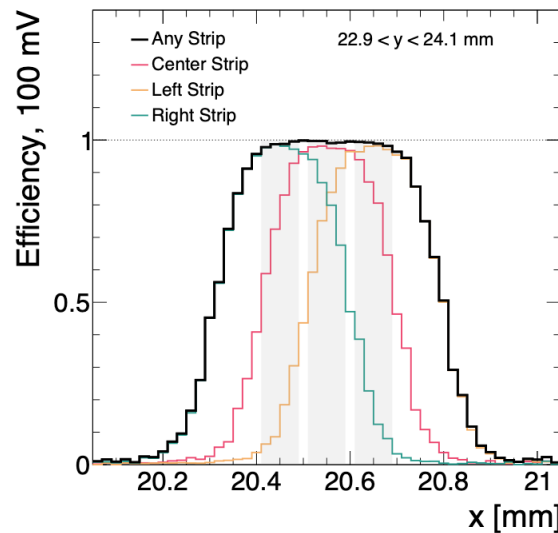


# AC-LGAD measurements in beams

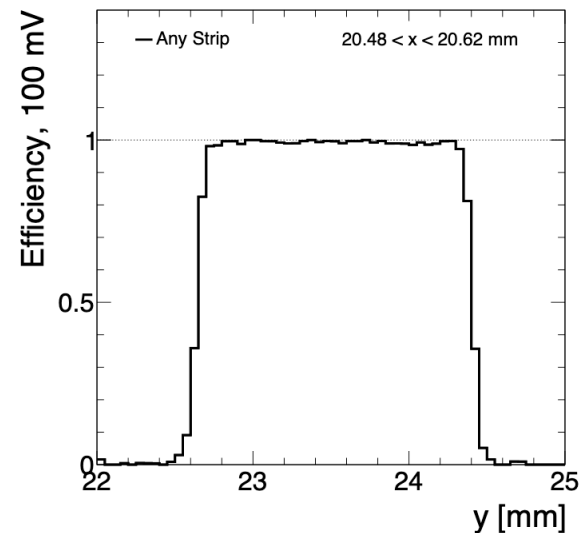
- Excellent performance in the beam showing high efficiency
  - First measurements in the beam in 2020:
    - BNL sensors: JINST 15 P09038 (2020)
- Time resolution and position resolution achieved targeted goals
  - 100% particle detection efficiency across sensor surface



**BNL strip AC-LGAD**



(a) Combined efficiency in x direction

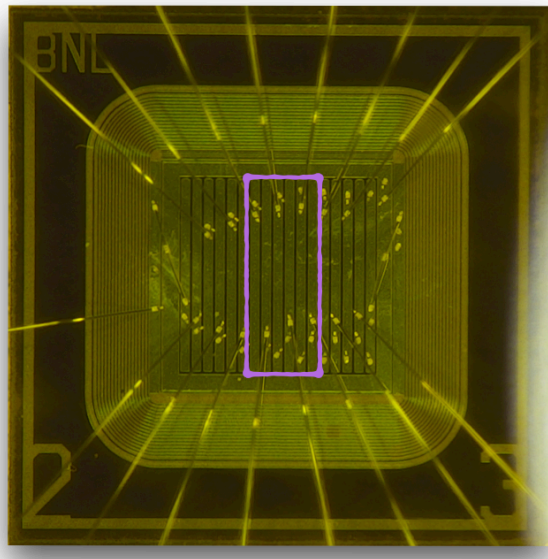


(b) Combined efficiency in y direction

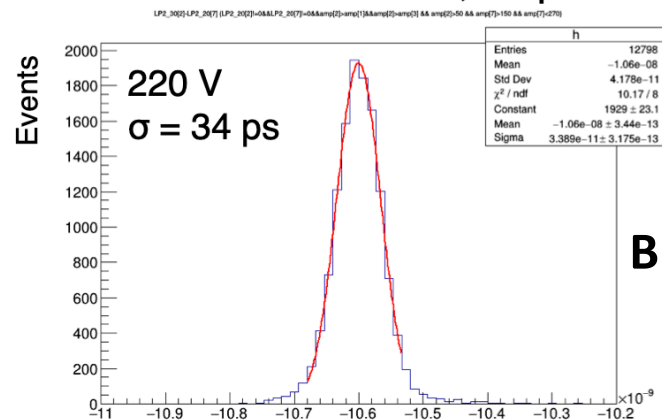
# AC-LGAD measurements in beams

- Recent test beam campaign: Mar 2021
  - Measurements of a variety of BNL and HPK sensors
- Read out 6 interior strips + DC ring + MCP reference
- Bias scan from 200 to 225 V

100 micron pitch, 20 micron gaps



Time resolution, strip 2



BNL strip AC-LGAD

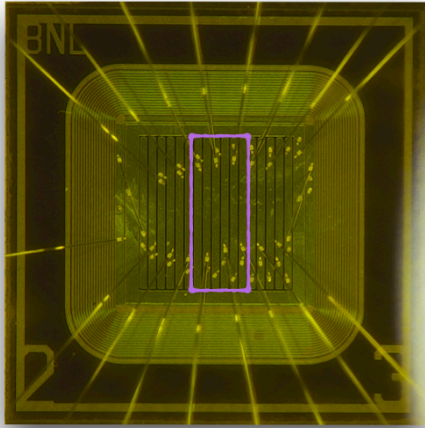
Reach 30-35 ps timing resolution in the primary hit strip

BNL strip AC-LGAD

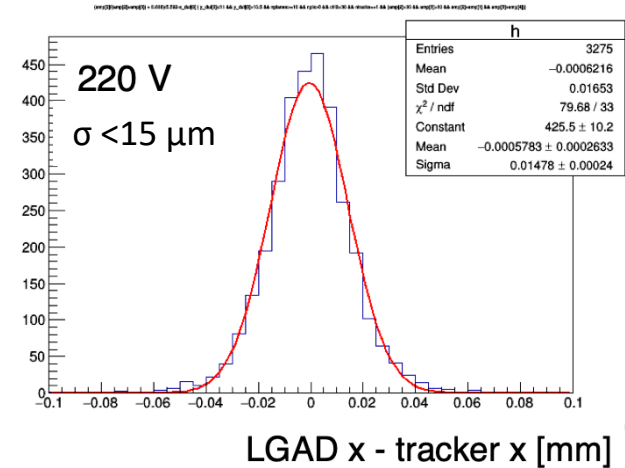
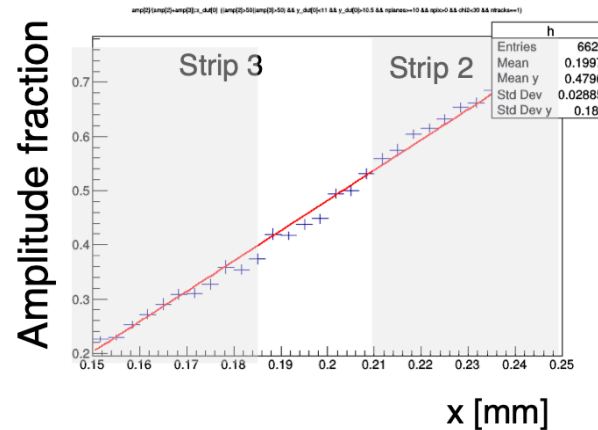
# AC-LGAD measurements in beams

- Basic position reconstruction with 2 strips
  - Plot average amplitude fraction vs X (amplitude[i] / amplitude sum)
  - In each event, calculate amplitude fraction and find corresponding X from fit line

100 micron pitch, 20 micron gaps



**BNL strip AC-LGAD**

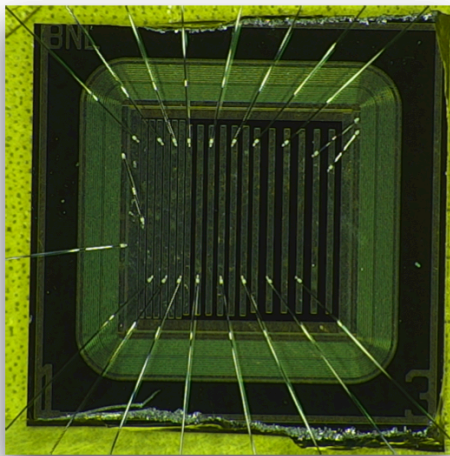


- Reach 15 micron resolution total width, limited by tracker resolution
- Places limit on sensor resolution less than 5-10 microns

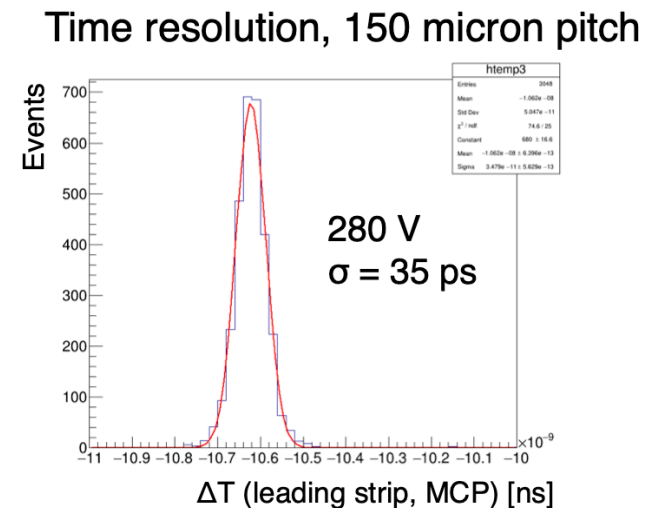
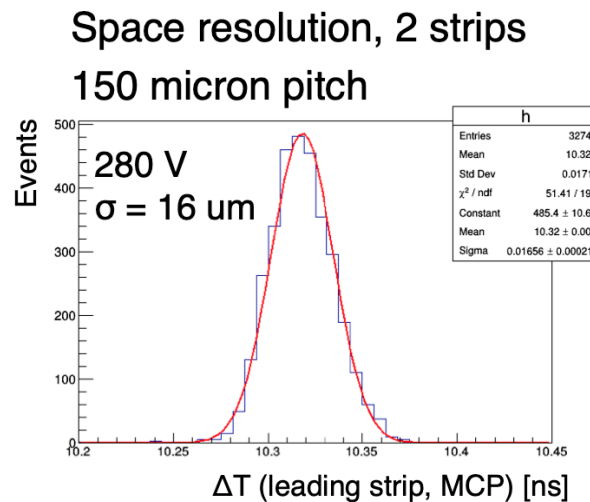


# AC-LGAD measurements in beams

- Single BNL sensor with a variety of strips geometries
  - 100, 150 and 200 micron pitch (80  $\mu\text{m}$  width)
  - Read out 5-6 strips from each pitch at a time



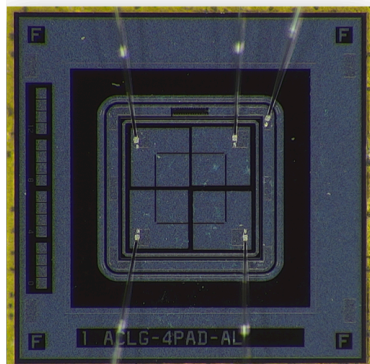
**BNL strip AC-LGAD**



- Reach 16  $\mu\text{m}$  and 35 ps resolution even with 50% larger pitch

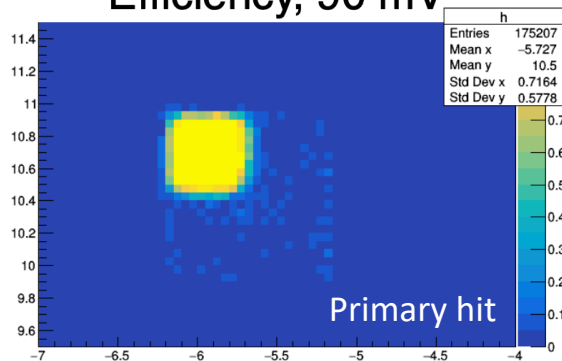
# AC-LGAD measurements in beams

- KEK and U. of Tsukuba group designed AC-LGAD sensors fabricated at HPK with pad, strip and pixel type electrodes.
  - Both pad and strips sensors, compare performance with both geometries, evaluate differences between manufacturers
- Large pixels allow more detailed study of position reconstruction, not limited by tracker resolution
- Assess the differences in designs and optimize them, based on experimental performance in lab, test-beams

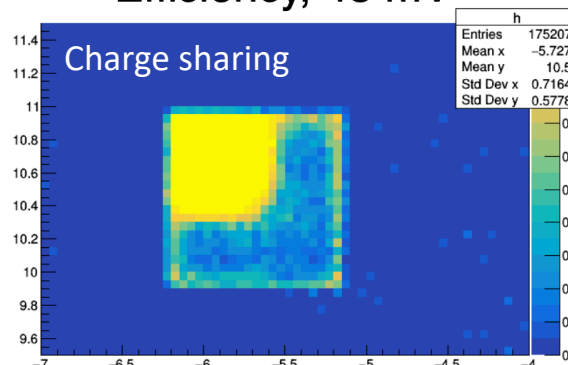


## HPK pixel AC-LGAD

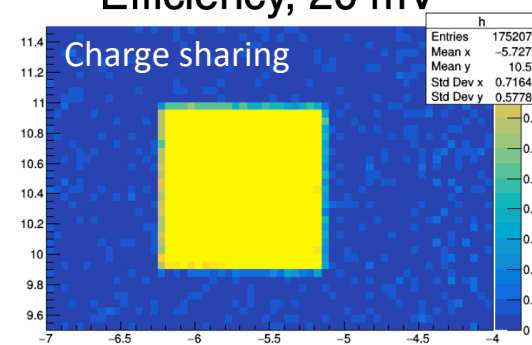
Efficiency, 90 mV



Efficiency, 45 mV

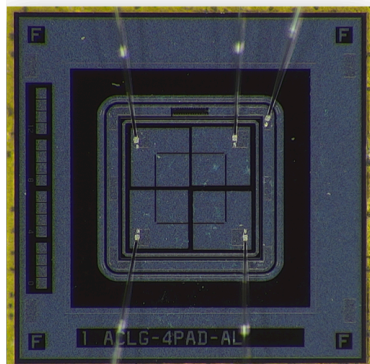


Efficiency, 20 mV



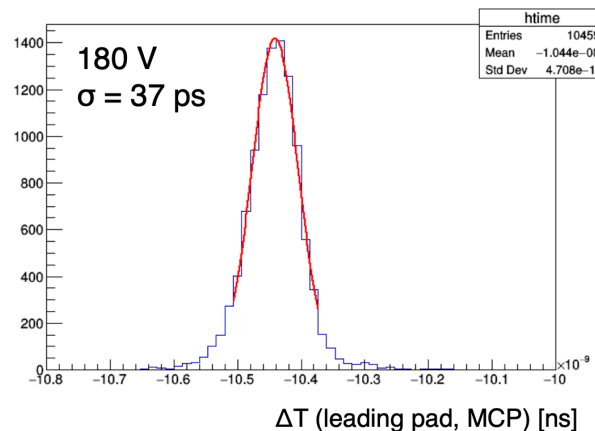
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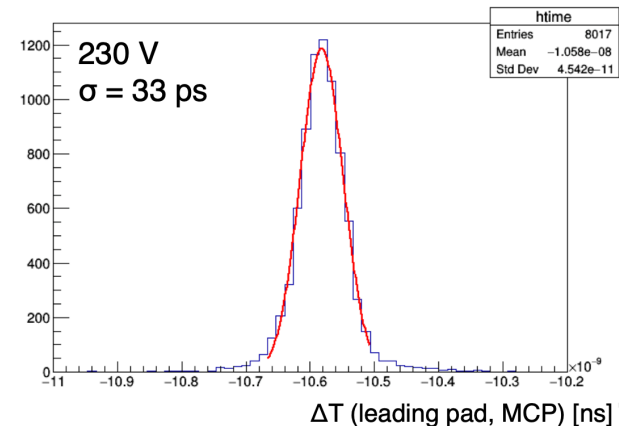


**HPK pixel AC-LGAD**

**C-2, primary pad only, 180 V**



**B-2, primary pad only, 230 V**





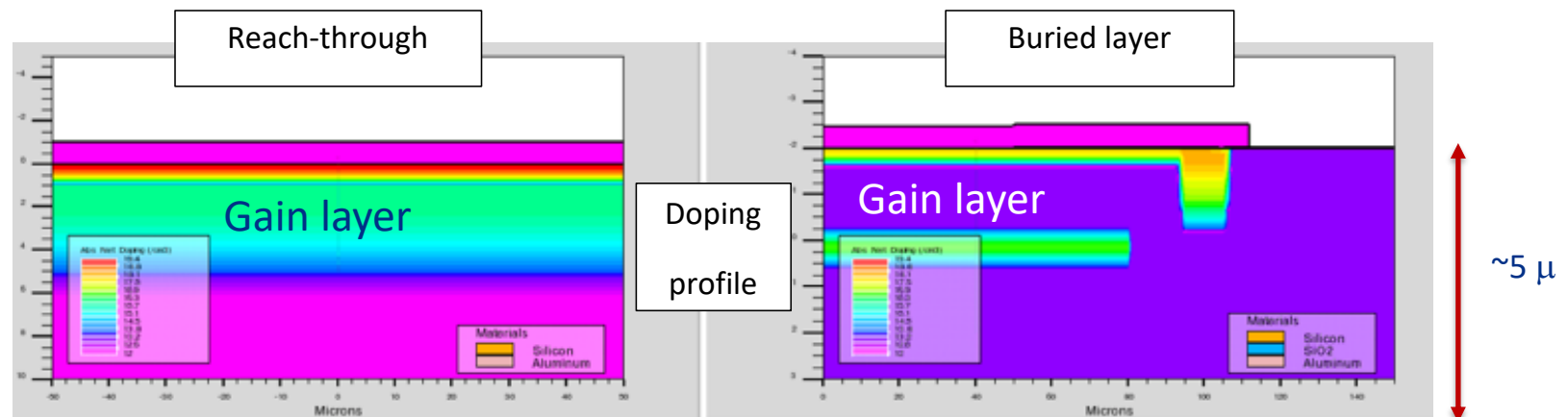
# Buried layer LGADs

We can engineer the silicon substrate to tailor the characteristics of the device

- Buried gain layer LGAD can provide a more radiation hard, stable device
- Gain layer is below epitaxy – AC coupling or more sophisticated topside processing can be integrated
- Combine with small pixels, or CMOS MAPS to design specialized sensors.

Usual reach-through implanted from top – limited options

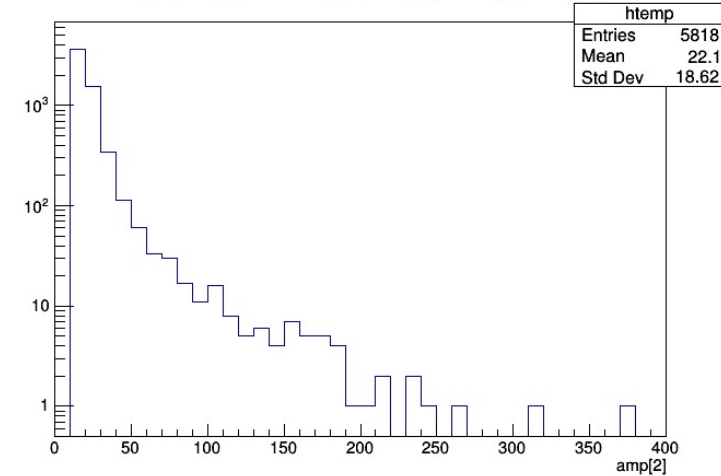
Gain layer grown over implant – can be denser, top can be custom processed



# Buried gain layer AC-LGAD sensors in test beam

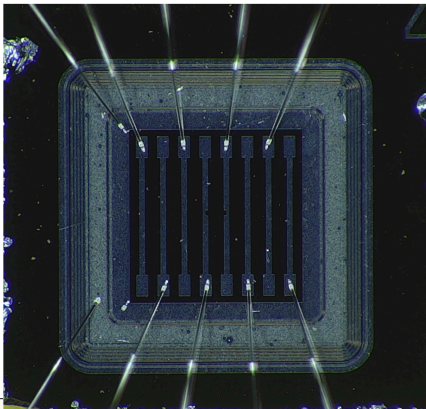
- First test beam measurements
  - Signal size is not optimal for good time resolution
  - Higher leakage current, probably need to improve the processing of wafers
- Very successful SBIR collaboration with Cactus Materials, Inc
  - Will follow up with another round production

amp[2] {amp[2]>10&&amp;[2]>amp[1]&&[2]>amp[3]}

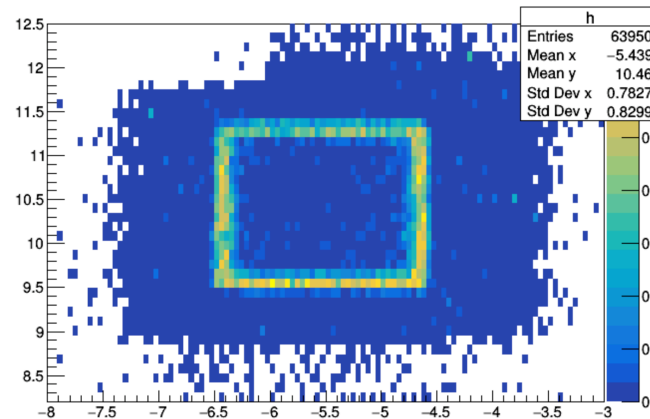


**Signal amplitude distribution**

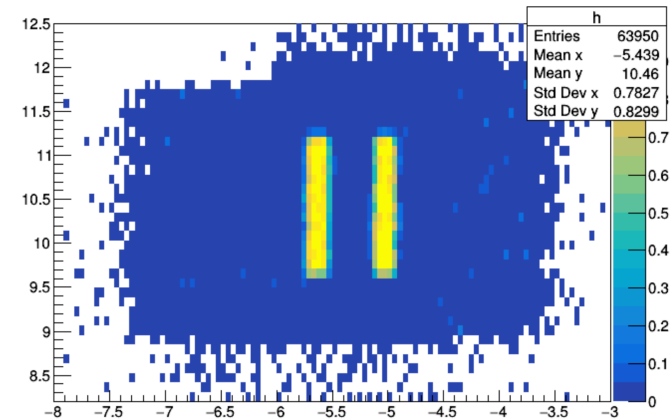
8-channel strips,  
200 micron pitch,  
50 micron metal



**Efficiency for DC ring**



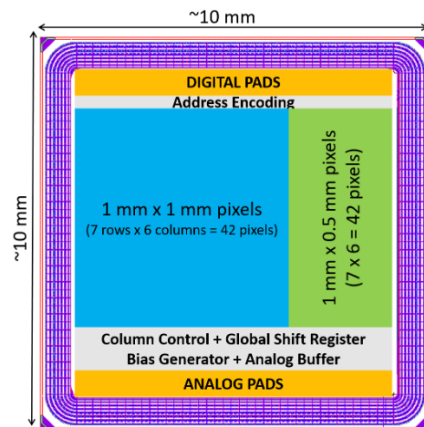
**Efficiency for leading hit in strip 2 or 5**



# MAPS sensors: CACT<sub>μ</sub>S detector

- Collaboration with CEA Saclay
  - Depleted monolithic active timing sensor using a CMOS 150 nm radiation hard technology from LFoundry
  - Promises to be: low cost, radiation hard, and with good time resolution
  - Originally intended for ATLAS HGTD detector, but could be used for EIC, future colliders
- The in-pixel front-end electronics of each pixel is made of a fast charge-sensitive amplifier(CSA) followed by a leading-edge discriminator.
  - The analog output of the CSA and the digital output of the discriminator can be monitored out of the chip through dedicated on-chip buffers.

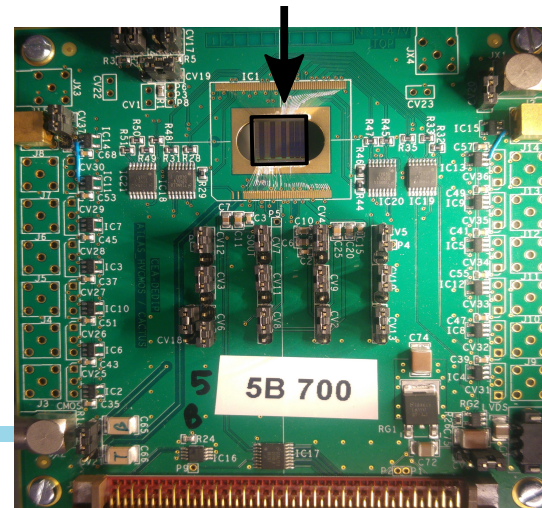
Simplified block diagram of Cactus detector.



JINST 15 P06011

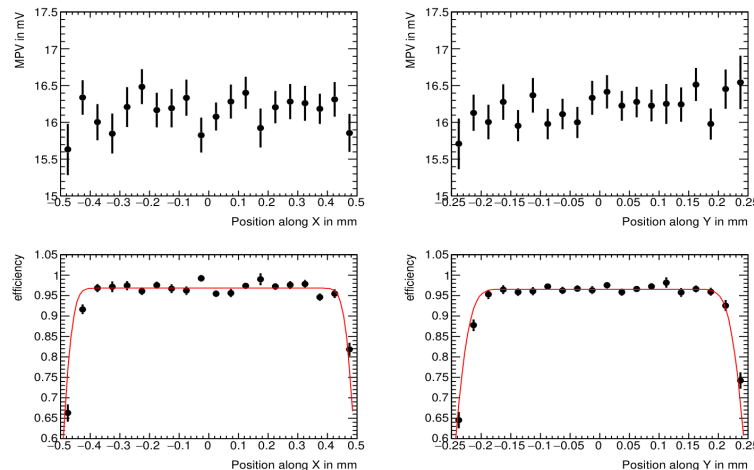
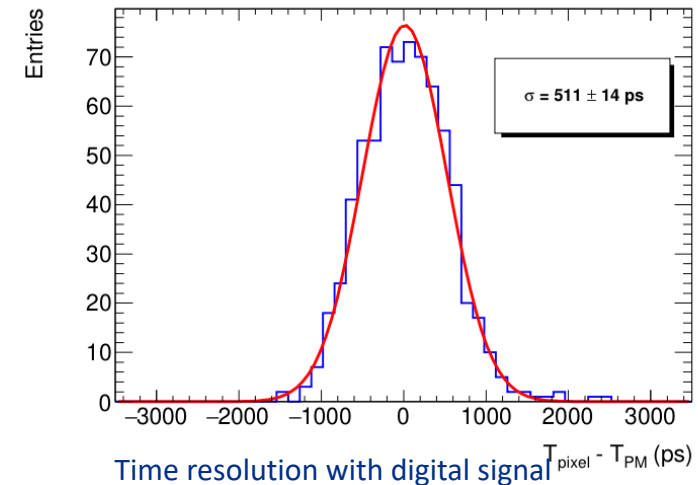
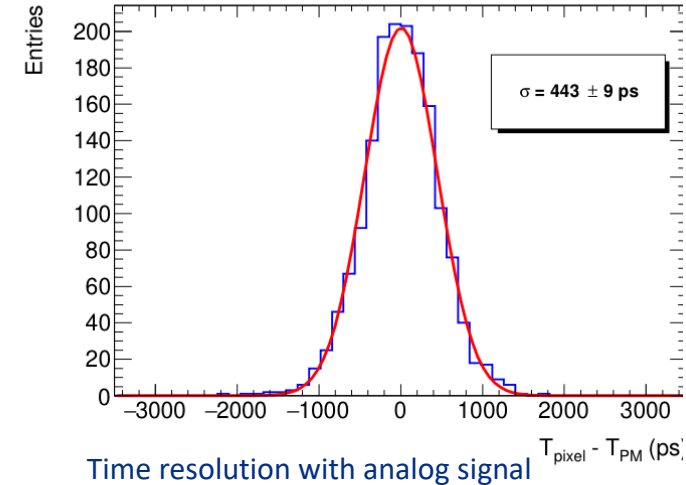


CACT<sub>μ</sub>S



# MAPS sensors: CACT $\mu$ S detector

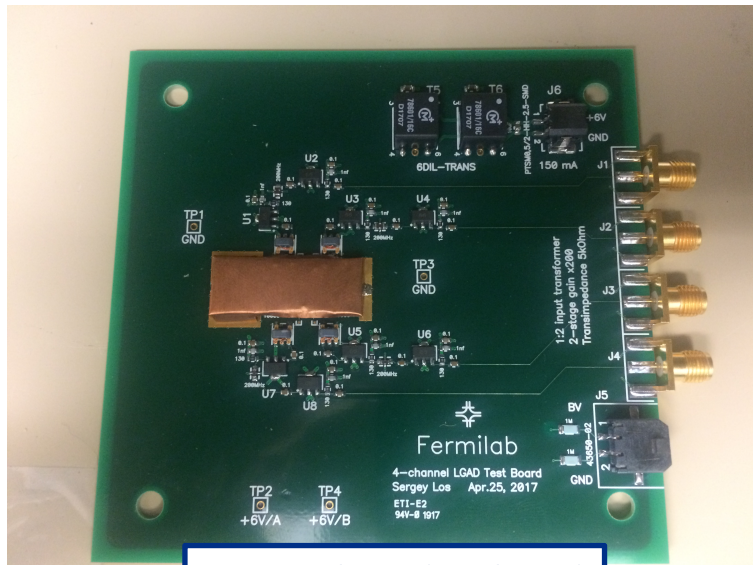
- Detailed measurements performed in the lab and in beam: JINST 15 P06011
  - Test results are promising but some problems observed
  - Analog S/N is lower than expected from simulations
  - This effect is likely due to the in-pixel power metal rails, increase the capacitance of the charge collection diode
  - New version is being designed
- Ideas to integrate LGAD and MAPS detectors:
  - G. Deptuch in Snowmass meeting:  
<https://indico.fnal.gov/event/45625/>



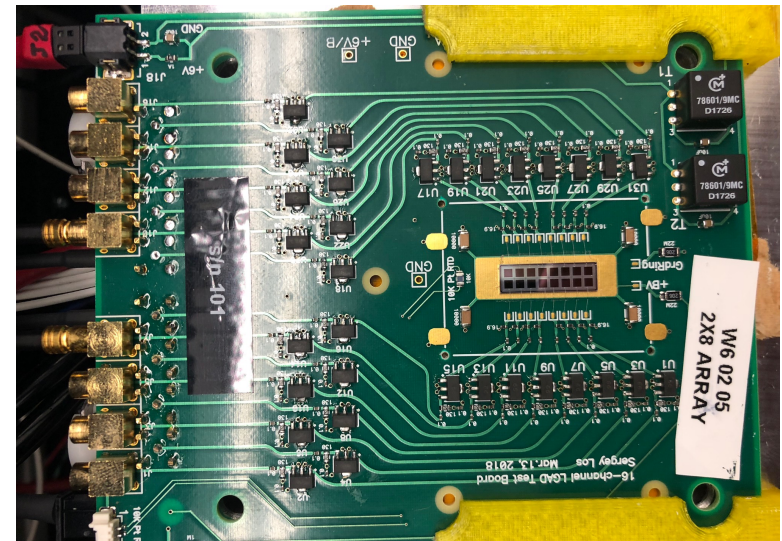
**Figure 12:** MPV and efficiencies determined in slices of X or Y. For the efficiencies, the red curves show the expected efficiency when a 97 % plateau efficiency is convoluted with a 25  $\mu\text{m}$  telescope resolution.

# Readout electronics for precision timing sensors

- Need appropriate “tools” to perform high precision position and timing measurements, without complicated ASIC and DAQ
  - Developed readout boards for the characterization of LGADs
  - 4-,16- and 26-channel boards are a **cost-effective and simple way to test** large channel count sensors
- Several iterations produced and improved over time
  - Have been critical in measurement campaigns for LGAD, and AC-LGAD sensors



## FNAL 4-ch readout board

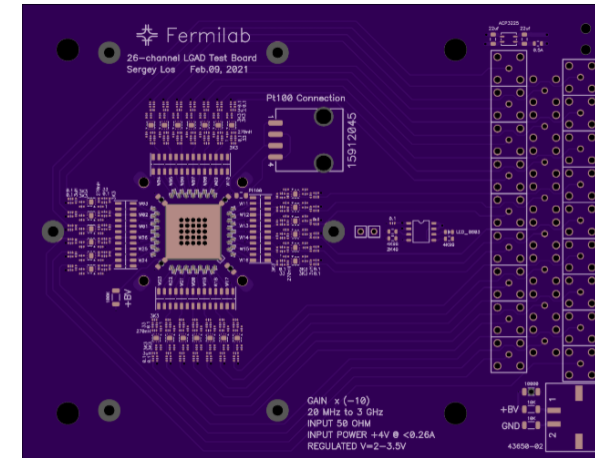


## 16-ch sensor LGAD on Fermilab readout board



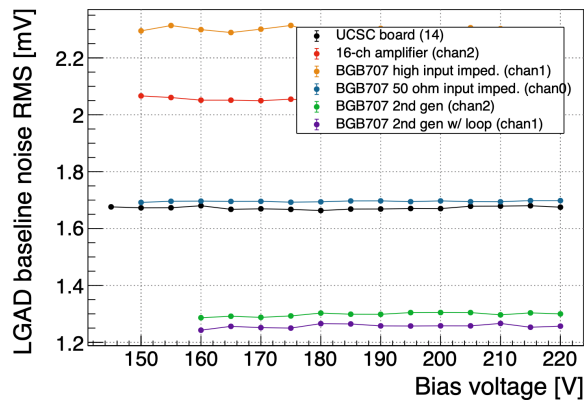
# Readout electronics

- New development: low power 26-ch board
  - Goals: Increase the channel count, reduce power consumption, improve time resolution performance
  - Maintain low noise, and low jitter
  - Achieve sensor's intrinsic limitation on time resolution: around 30 ps resolutions (for 50  $\mu\text{m}$  thickness)
- Measurements of 4-ch prototypes showed very good performance with particles
  - Full-size boards produced, being tested now

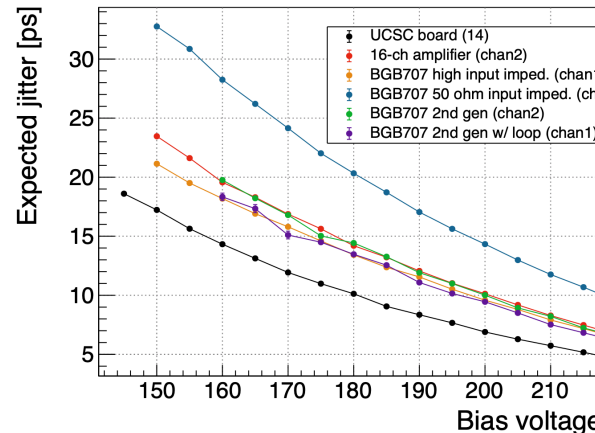


26-channel board design

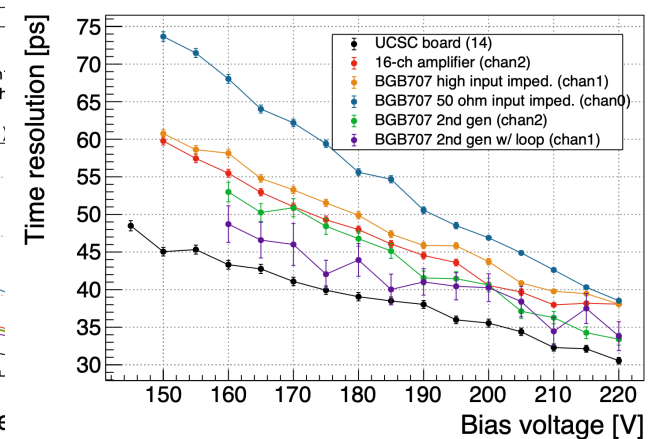
## Noise



## Noise / dV/dt

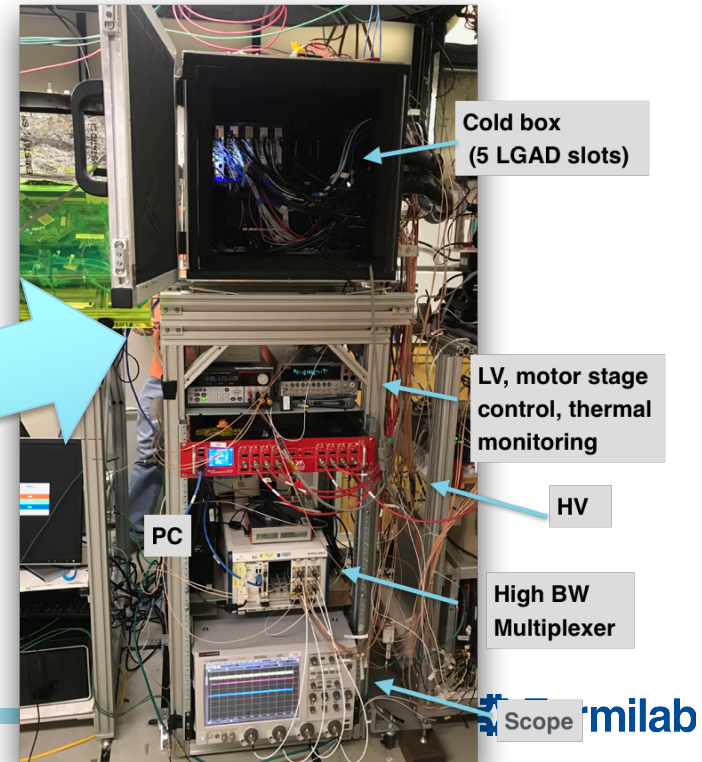
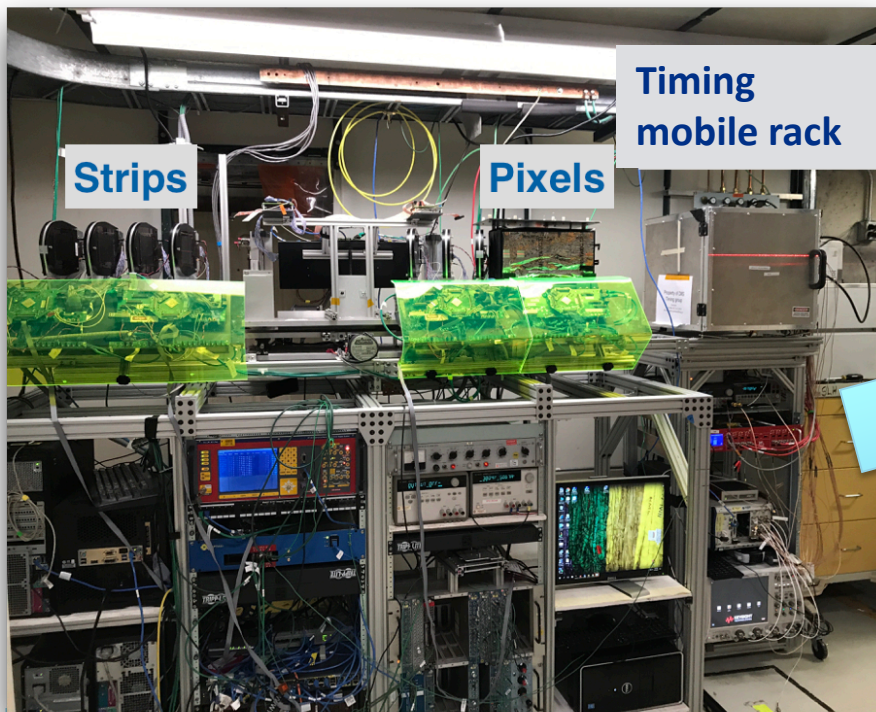


## Time resolution



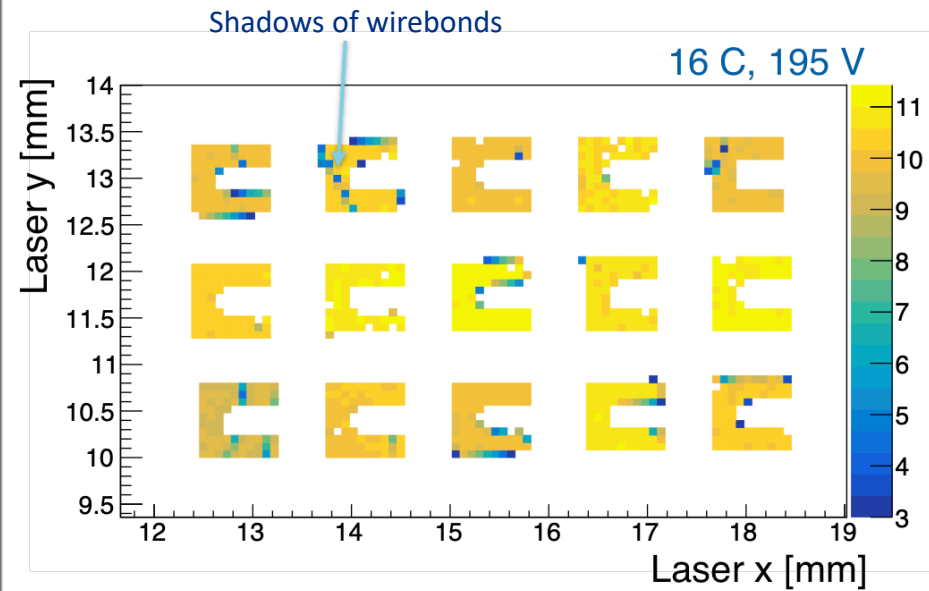
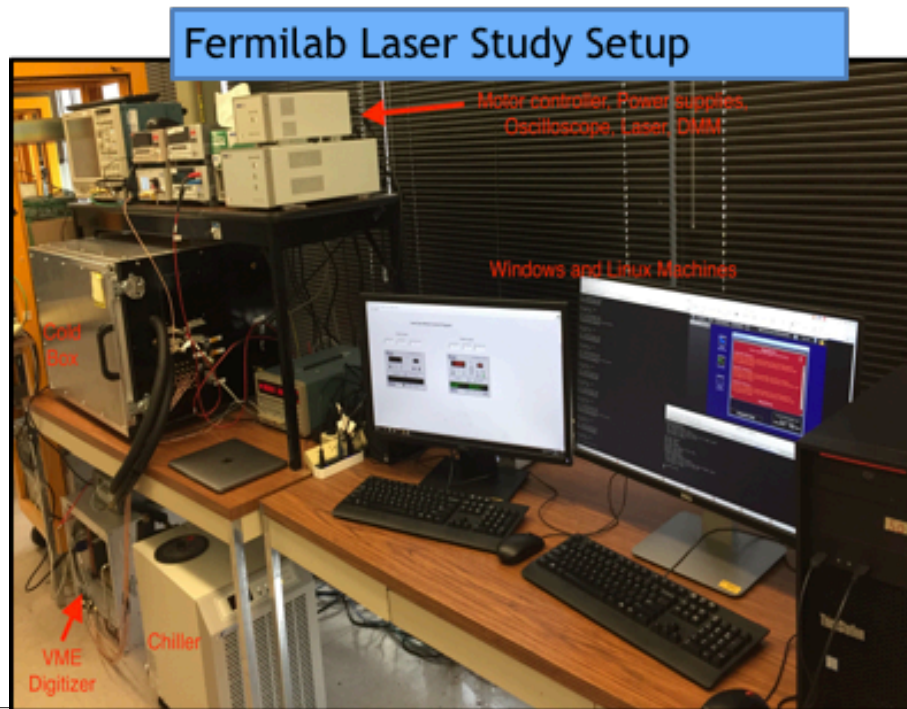
# Fermilab 4D-trackers test beam infrastructure

- Permanent setup in FNAL test beam facility (FTBF)
  - Movable: slide in and out of beamline as needed, parasitic use of beam
  - Environmental controls: sensor temperature (-25 C to 20 C), and humidity, monitoring
  - Remote control (stages, HV, LV), logging & reconstruction;  $\sigma_T \sim 10$  ps time reference (MCP)
  - Cold operation of up to 10 prototypes at the same time
  - DAQ: high bandwidth, high ADC resolution scope 4- or 8-channel scope
  - Record 100k events per minute, tracker with  $\sim 10$   $\mu\text{m}$  resolution



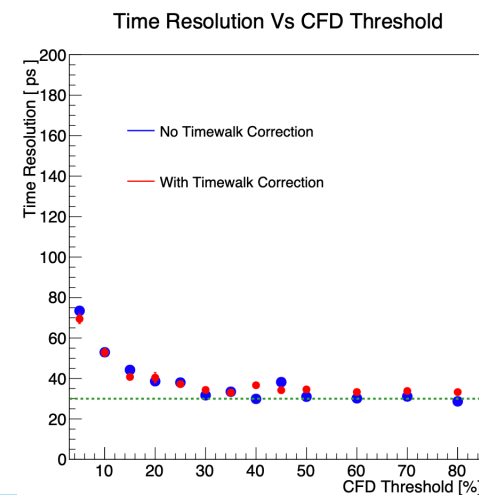
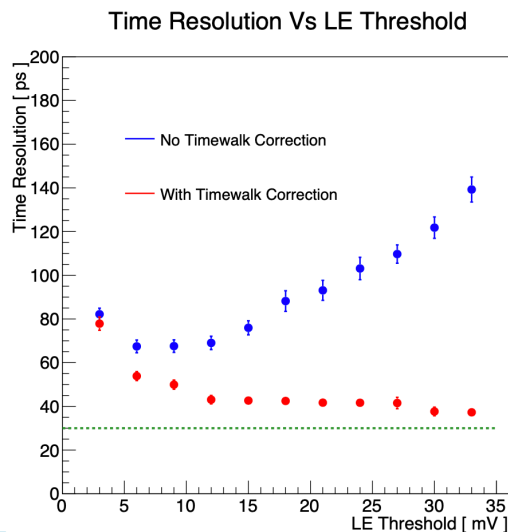
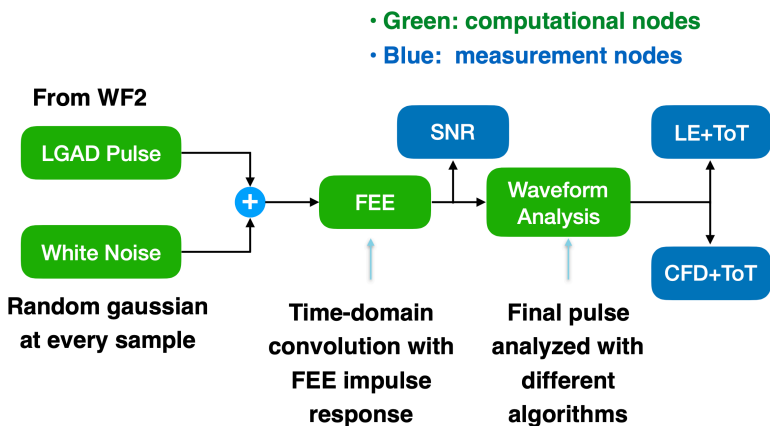
# Infrastructure at SiDet

- LGAD sensors characterization facility
  - Environmental chamber with the same capabilities and DAQ as in MTest
  - Infrared laser with 15  $\mu\text{m}$  beamspot and XYZ motion stages for scanning
  - $\text{Sr}^{90}$  and  $\text{Ru}^{106}$  beta-sources for gain, time resolution measurements
  - Studies of large samples of sensors, stability and detailed understanding without the rush of beam tests



# Timing ASIC approaches: LE or CFD

- Simulation Model of Front-end Electronics for High-precision Timing Measurements with LGADs
  - LGAD pulses are from Weightfield2 (WF2) simulation
  - Different pulse shape as a function of irradiation
- Consider various options for the pre-amp:
  - Simulation scans BW, SNR, and compare LE vs CFD approaches





# Analysis Summary of Results (ST = 0.5 ns)

## Leading Edge

<i>ST (ns)</i>	<i>SNR=20</i>	<i>SNR=30</i>	<i>SNR=100</i>
<i>0.5</i>	<i>38 ps</i>	<i>35 ps</i>	<i>29 ps</i>
<i>0.5</i>	<i>37 ps</i>	<i>32 ps</i>	<i>26 ps</i>
<i>0.5</i>	<i>48 ps</i>	<i>38 ps</i>	<i>27 ps</i>

Pre-rad

$5 \times 10^{14}$  n/cm<sup>2</sup>

$1 \times 10^{15}$  n/cm<sup>2</sup>

## Constant Fraction

<i>ST (ns)</i>	<i>SNR=20</i>	<i>SNR=30</i>	<i>SNR=100</i>
<i>0.5</i>	<i>37 ps</i>	<i>35 ps</i>	<i>30 ps</i>
<i>0.5</i>	<i>33 ps</i>	<i>31 ps</i>	<i>25 ps</i>
<i>0.5</i>	<i>42 ps</i>	<i>34 ps</i>	<i>24 ps</i>

Pre-rad

$5 \times 10^{14}$  n/cm<sup>2</sup>

$1 \times 10^{15}$  n/cm<sup>2</sup>

- 30-35 ps target resolution achieved by LE and CFD up to SNR = 30
- Target resolution achieved up to irradiations of  $1 \times 10^{15}$  n/cm<sup>2</sup>
- 40-50 ps resolution achieved when SNR = 20 at the largest dose



# Analysis Summary of Results (ST = 1.0 ns)

## Leading Edge

<i>ST (ns)</i>	<i>SNR=20</i>	<i>SNR=30</i>	<i>SNR=100</i>	
<i>1.0</i>	<i>45 ps</i>	<i>37 ps</i>	<i>29 ps</i>	Pre-rad
<i>1.0</i>	<i>41 ps</i>	<i>34 ps</i>	<i>29 ps</i>	5x10 <sup>14</sup> n/cm <sup>2</sup>
<i>1.0</i>	<i>60 ps</i>	<i>47 ps</i>	<i>28 ps</i>	1x10 <sup>15</sup> n/cm <sup>2</sup>

## Constant Fraction

<i>ST (ns)</i>	<i>SNR=20</i>	<i>SNR=30</i>	<i>SNR=100</i>	
<i>1.0</i>	<i>36 ps</i>	<i>33 ps</i>	<i>26 ps</i>	Pre-rad
<i>1.0</i>	<i>33 ps</i>	<i>31 ps</i>	<i>26 ps</i>	5x10 <sup>14</sup> n/cm <sup>2</sup>
<i>1.0</i>	<i>47 ps</i>	<i>37 ps</i>	<i>23 ps</i>	1x10 <sup>15</sup> n/cm <sup>2</sup>

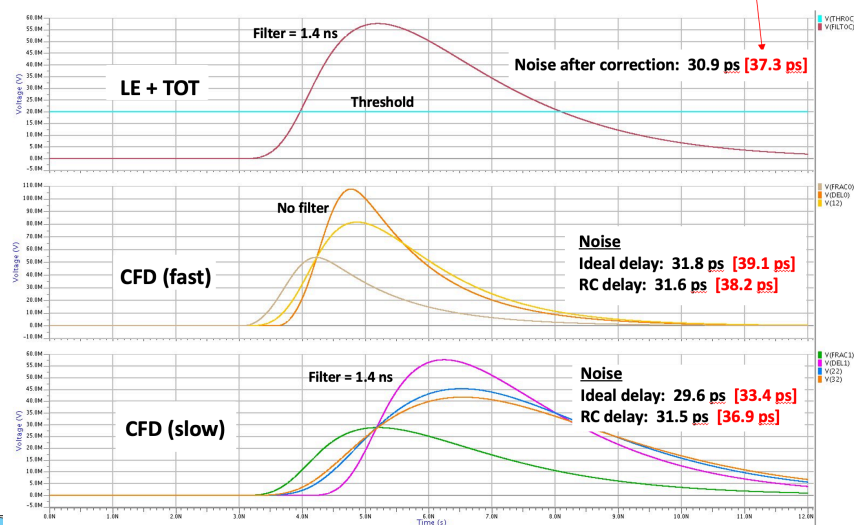
- 30-35 ps target resolution achieved by LE and **CFD** up to SNR = 30
- ST = 1 ns → observe a large performance gap when using CFD
- 40-50 ps resolution (CFD only) when SNR = 20 at the largest dose

# Timing ASIC with CFD: FCFD0

- Develop a CFD based ASIC for LGAD fast timing readout
  - Expect better performance for low S/N after irradiation, no need for time-walk correction, stability, simplicity of operation,
  - Many innovative solutions designed and implemented by T. Zimmerman (FNAL)
- The chip recently received from TSMC
  - Currently being tested, and then will mount on dedicated readout board for testing with sensor, betas and beams.
  - Follow up with subsequent productions of full chips, with more channels

Input transistor current = 1mA

Add 150 ohms to input transistor gate to "double its noise"



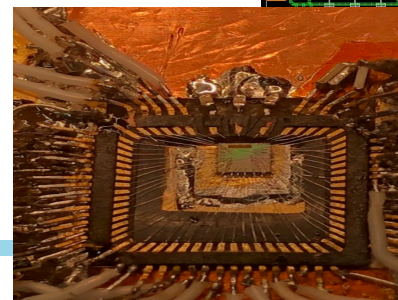
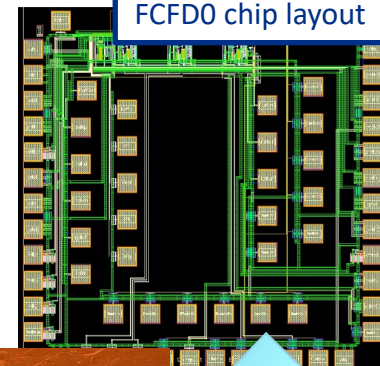
Fraction peak	Ideal delay	RC delay
1.36 ns	31.8 ps	30.9 ps
1.58 ns	30.5	30.7
1.76 ns	30.2	30.8
1.97 ns	30.3	31.2
2.17 ns	30.4	32.0
2.33 ns	30.5	32.9

Too fast

Ideal

OK

FCFD0 chip layout



Received in  
Dec 2020

Fermilab

# Summary

- Timing is an enabling technology for future experiments
  - The last dimension to be used in collider experiments!
  - Will bring improvements in event reconstruction, triggering, and new handles in searches for new physics!
- Future tracking detectors will likely be required to have significant timing precision: both lepton and hadron colliders
  - Timing precision of 20-30 ps achieved with several Si-based technologies
  - Collaborative efforts are a key for the progress in many challenging directions