



Funded by DoE through the Exa.TrkX project

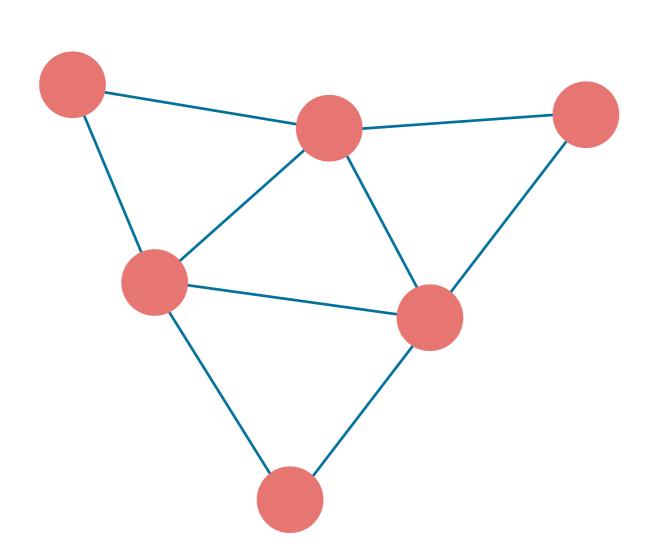
Graph Neural Networks for Reconstruction in Liquid Argon Time Projection Chambers

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DUNE reconstruction meeting
21st January 2021



Graph neural networks

Describe information structure as a graph represented by nodes and edges.

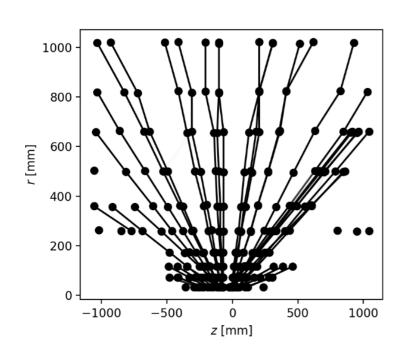


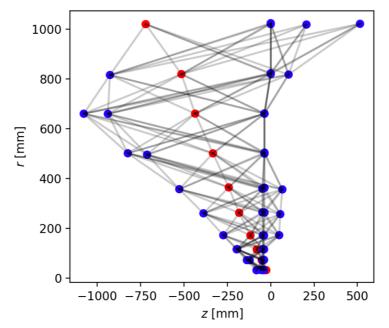
- Nodes are generalised as quantised objects with some arbitrary set of features.
- Edges describe the relationships between nodes.
- Perform convolutions on nodes and edges to learn relationships within the graph.
- Output is user-defined:
 - Classify nodes or edges.
 - Classify full graph.
 - Regression outputs.

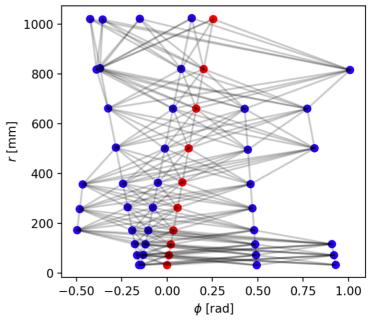


Graph networks in HEP

- Investigating the use of Graph Neural Networks (GNNs) as an alternative to Convolutional Neural Networks (CNNs).
- Building on promising results from the HEP.TrkX collaboration using such methods for track reconstruction in the LHC world.
- Exa.TrkX project building on these results to further develop techniques in HL-LHC, and branch out to explore other detector technologies like LArTPCs.









Simulation

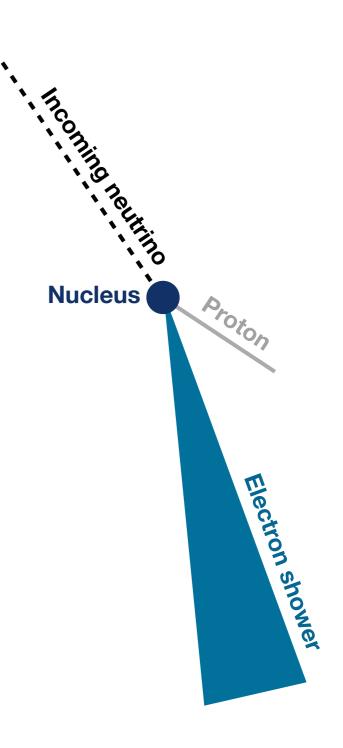
 Utilising two sets of simulation for these studies:

Atmospheric neutrino interactions

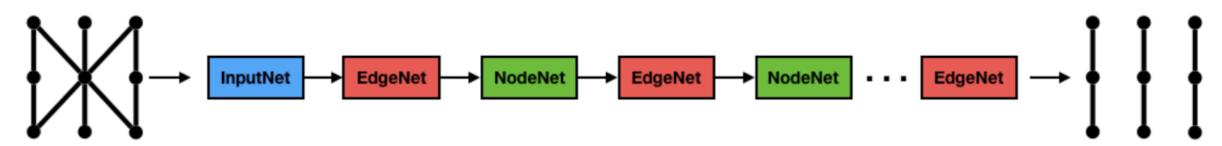
- Higher in primary neutrino energy (typically ~tens of GeV).
- Broad angular distribution.
- Higher occupancy events.

CCQE beam neutrino interactions

- Few-GeV energy.
- Neutrinos travel along beam direction.
- Typically "clean" interactions primary lepton (e,µ) and minimal hadronic activity.







arxiv:1810.06111

- Message-passing network aggregates information from neighbouring nodes across edges to form new features on each node, utilising an attention mechanism to weight up useful edges.
- Repeat the same network multiple times in order for information to travel further across the graph over multiple iterations (the "message passing").

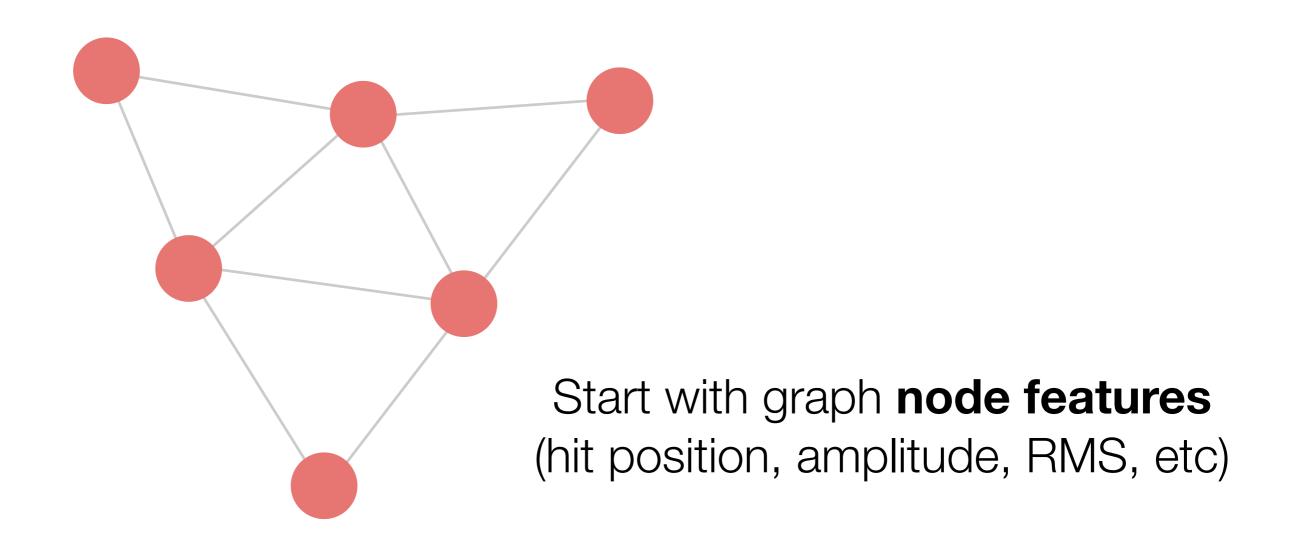
· Edge classifier:

- Input for each node is the features of incoming and outgoing nodes.
- Two multi-layer perceptrons, using Tanh and sigmoid activations.
- Outputs sigmoid score on each edge.

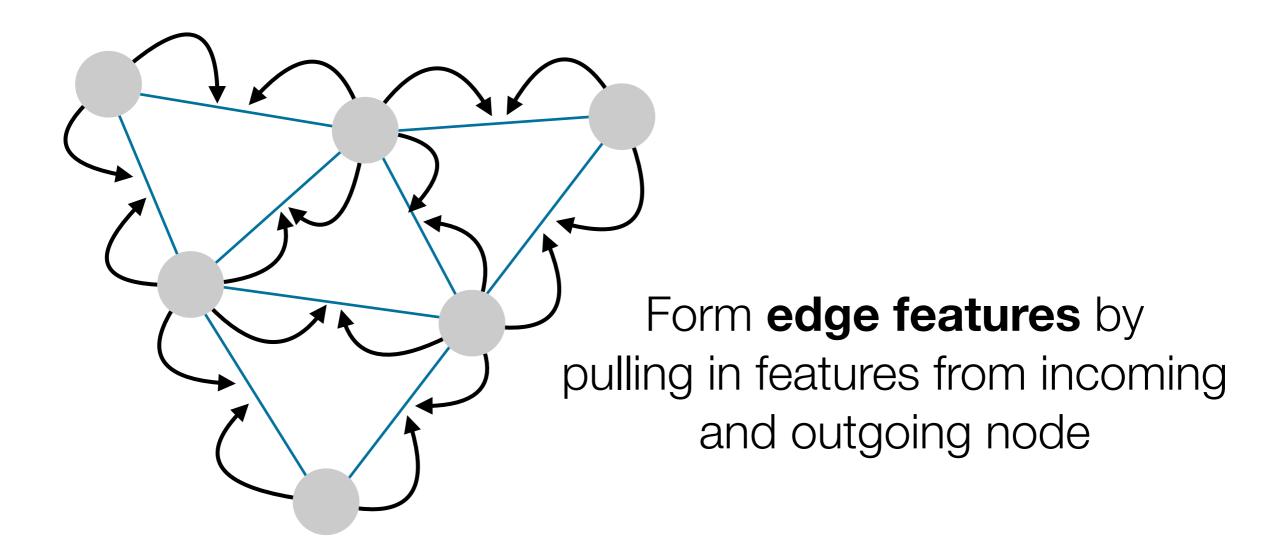
Node classifier:

- Uses edge score to aggregate each node's features with incoming & outgoing edges as input.
- Two multi-layer perceptrons with Tanh activation.
- Produces new features for each node.

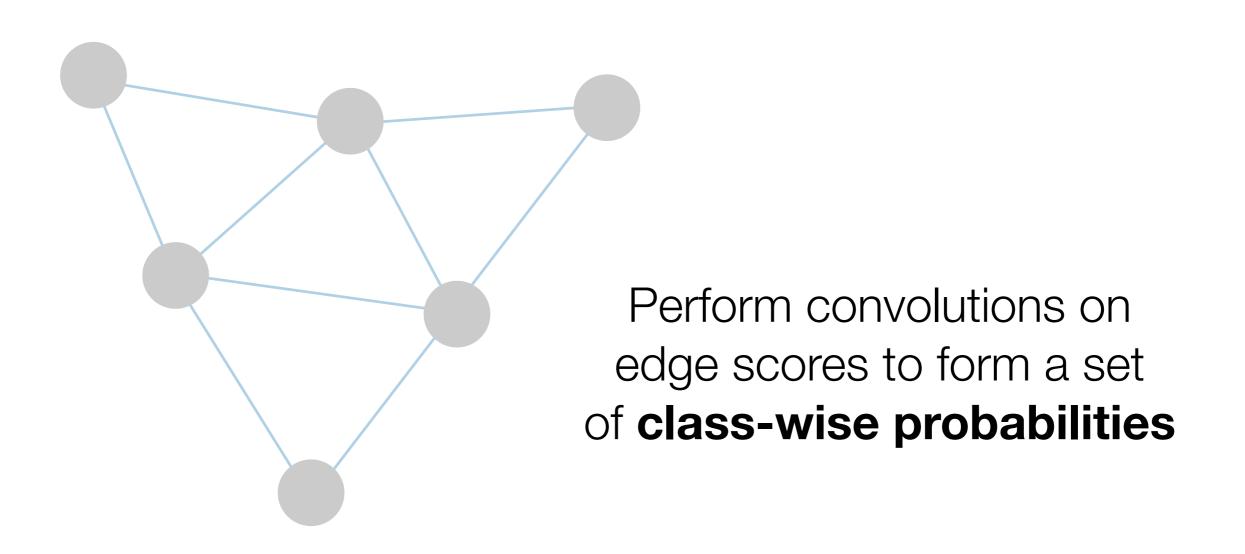




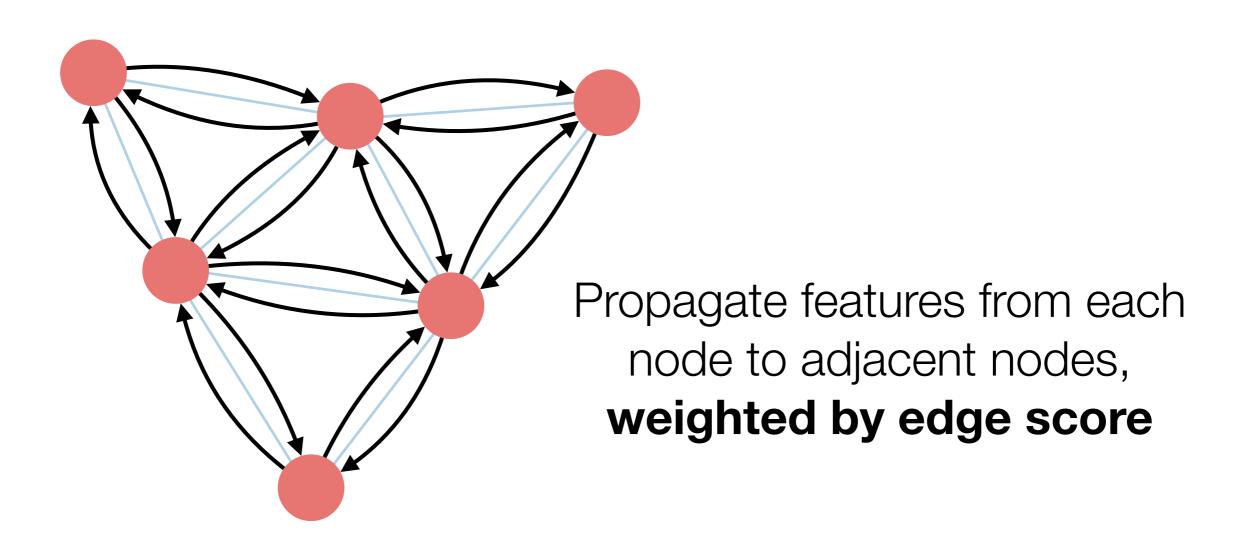




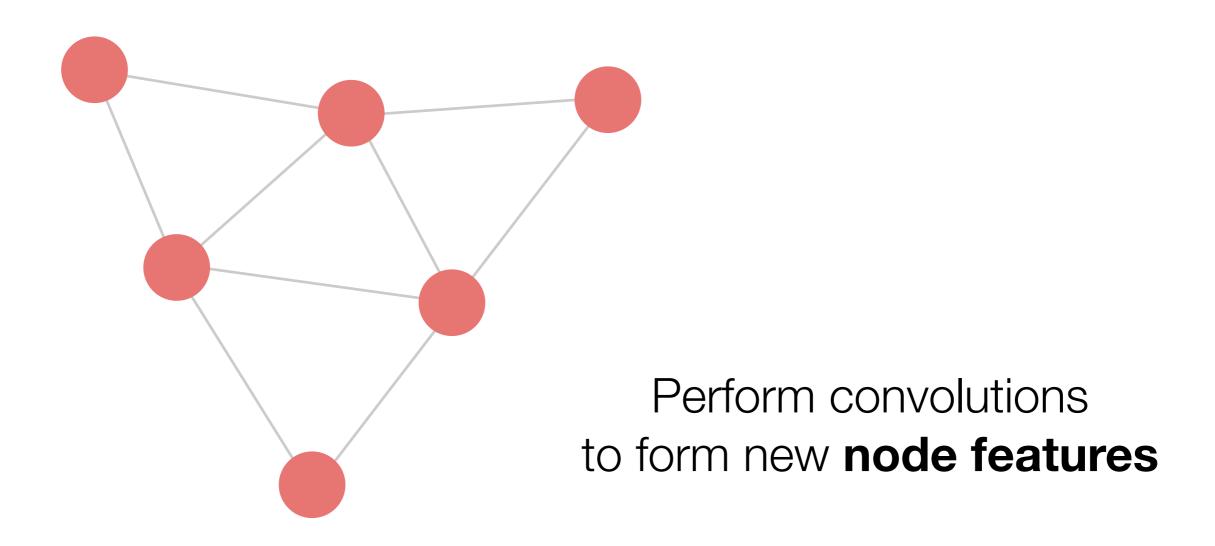






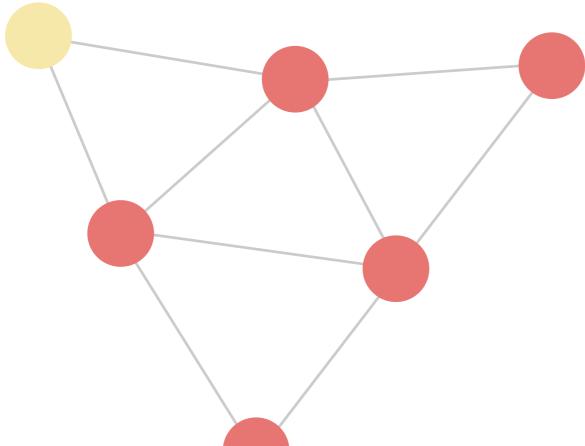








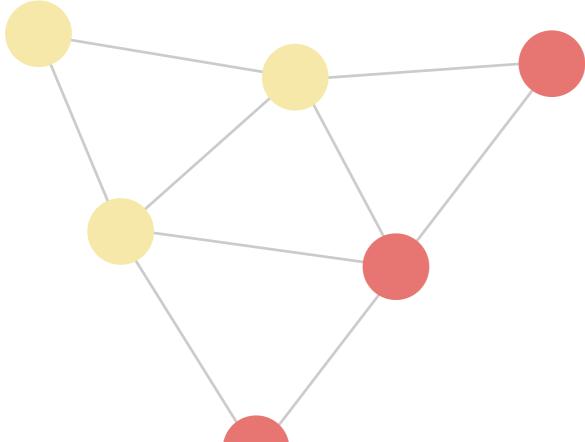
Repeating this process causes information to spread across the graph



Iteration 0



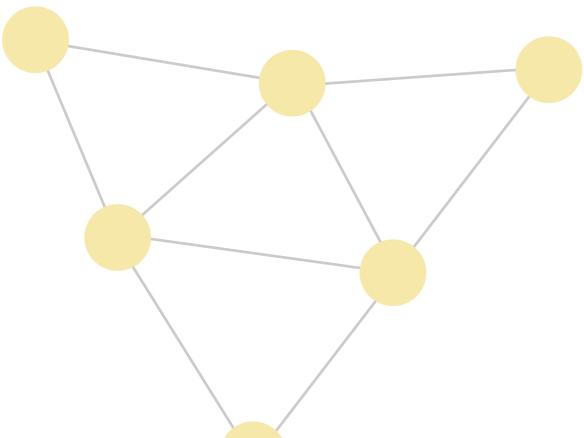
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Iteration 1



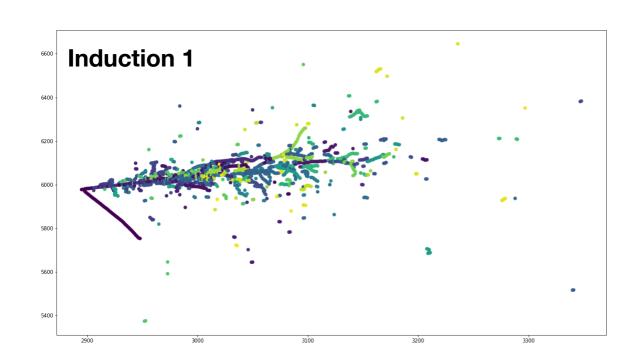
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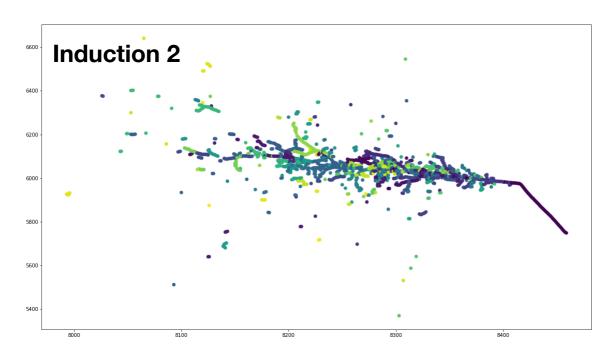
Iteration 2

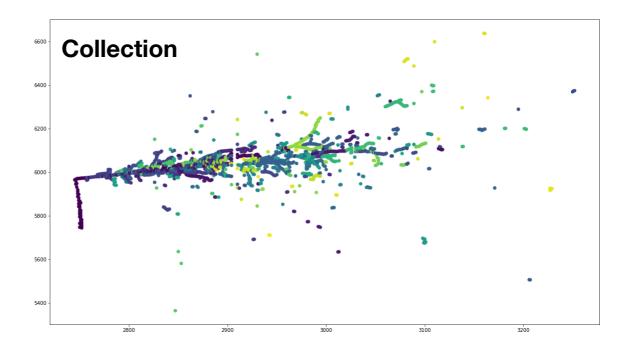


2D reconstruction



- Start with 2D representation and build up using graph network.
- Colour coded according to true simulated particle.
- Three 2D representations of the same 3D interaction.

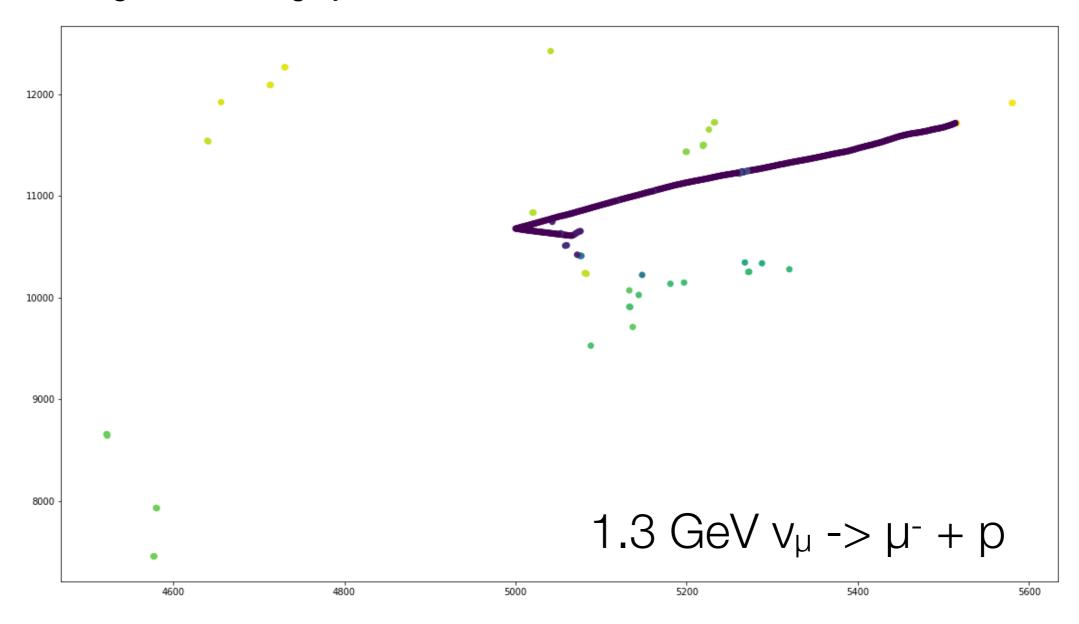






ν_μ graph construction

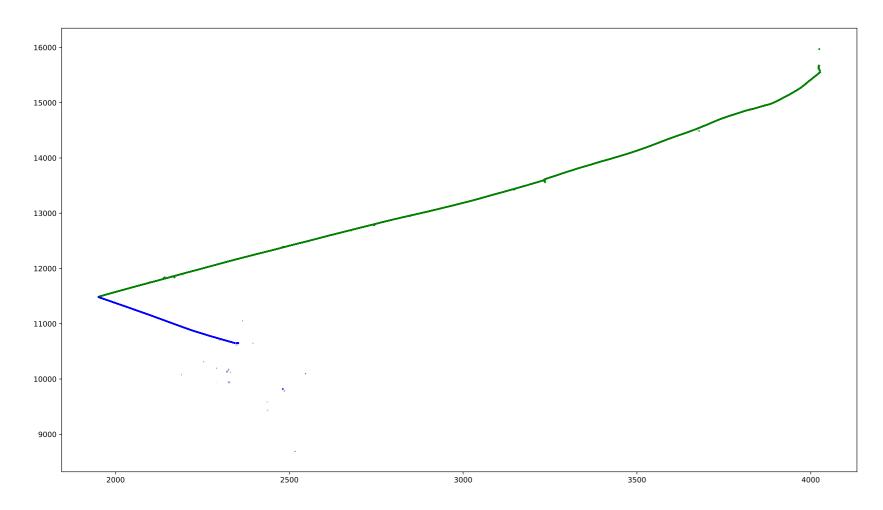
- Connect hits that are adjacent in wire and time with potential edges.
- · Potential edges drawn in grey between nodes.





ν_μ graph construction

- Potential graph edges formed for hits in close proximity (5 wires & 50 time ticks).
- Potential edges then classified as hadronic, muon, shower or false as an objective for learning.

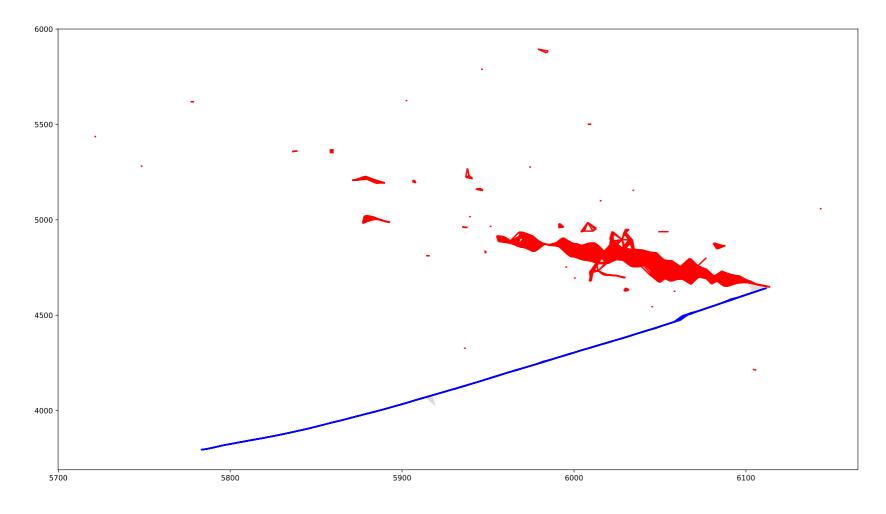


- Edges are classified as false if the two hits were not produced by the same particle in the underlying simulation.
- Muon edges are hits produced by the primary muon, shower edges by the primary electron, and hadronic edges are the remainder.



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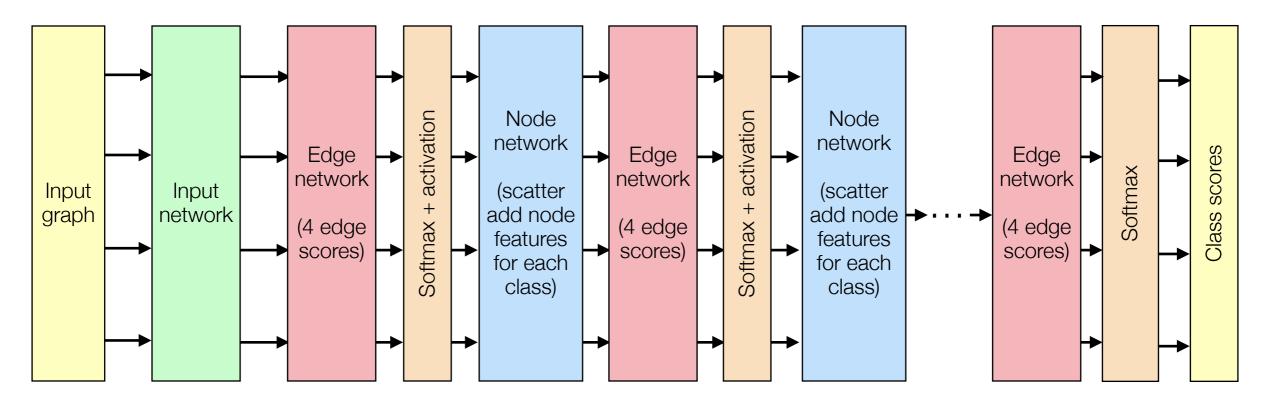


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Multihead attention message-passing network

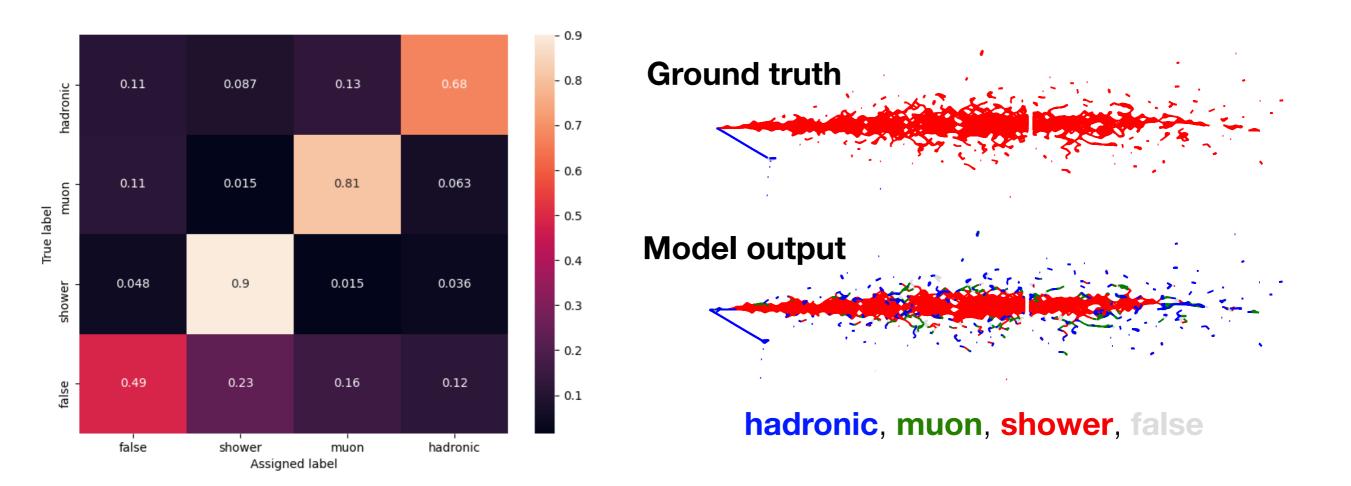
- Build on Exa.TrkX binary edge classifier.
 - Pass messages + form node features independently for each class.
 - Produce 4 edge attention scores on each edge.
 - Take the softmax of those edges with each iteration.
 - If an edge is strongly shower-like, the track-like classes will be weighted down accordingly.





2D edge classification network

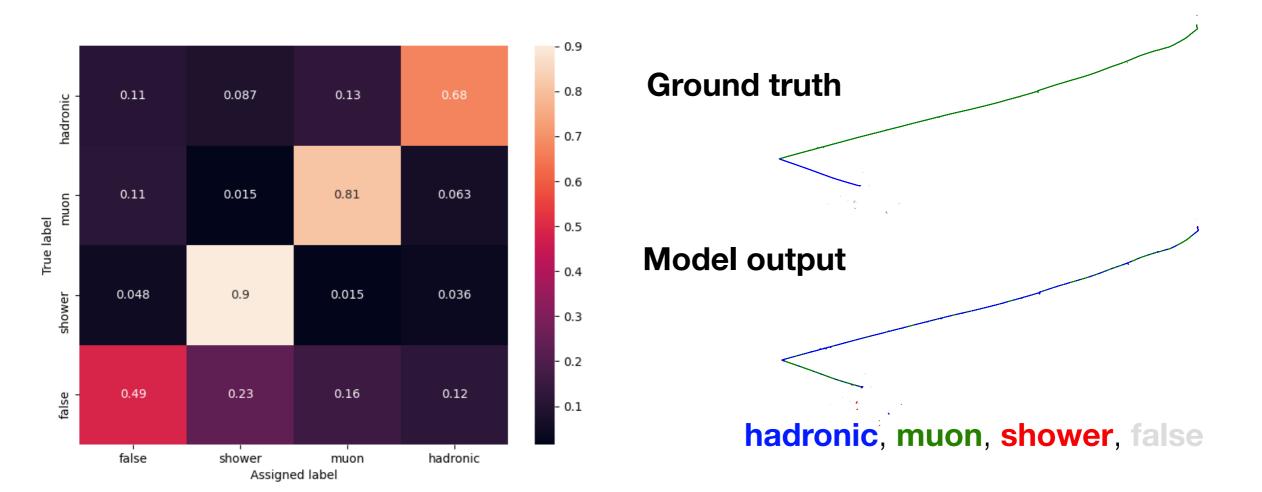
- Current iteration achieves 84% accuracy in classifying graph edges.
- Performs well on showers, but still room for improvement in tracks.





2D edge classification network

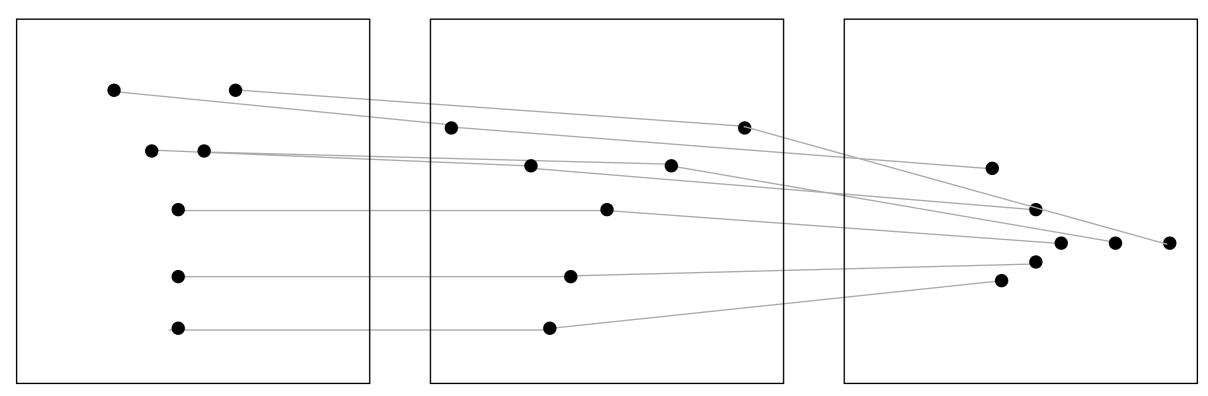
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Next steps

- In current setup, the three views are categorised independently.
- Match hits produced concurrently in time to allow information flow between views.
 - Message-passing between planes may aid with clustering within each plane.
- Long-term goal: combine with heterogeneous graph nodes such as LArTPC optical detector system for time matching.





Next steps

- Edge classification was a natural fit for track-forming in HL-LHC.
- Clearly shows promise in neutrino physics too, but less well-suited to the problem of clustering hits into dense objects.
 - Need a scheme to collapse disparate classified edges into objects.
 - Objective function scores each edge independently, and doesn't have any wider context.
- · Considering newer techniques such as graph pooling and instance segmentation.
- Move beyond simple CCQE interactions to more complex event topologies
 - Build more sophisticated definitions of the ground truth.
 - Scale up from 2D representations to 3D.