

LLRF system upgrade at AWA D. Filippetto, C. Serrano, D. Li, L. Doolittle, S. Paiagua, V. Vytla

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Outline

- Description and analysis of current system
- Proposal for AWA LLRF Upgrade
- Example of deployments: LCLS-II and HiRES
- Future upgrades and budget considerations

AWA current system configuration

General observations from LBNL

Potential areas of improvements to the benefit of AWA beam stability:

- Mechanical vibrations could induce noise in the long waveguides (up to 40m)
- Implementation of a phase reference line would minimize relative drifts.
- Improved clocking scheme to guarantee overall system coherence
- Improvements may be needed in laser-to-RF synchronization
- Consider adding a timing system, to make events RF synchronous
- LLRF system uses NI COTS components, and computer in the loop
- Consider moving to EPICS

Identified items for upgrade

- I Re-define architecture based on available resources.
- Build and deploy 1.3 GHz, LCLS-II (and HiRES) style LLRF hardware.
- Define clocking scheme, design, build and deploy MO/LO system.
- Transition to RF-synchronous, event-based timing system.
- Add a temperature controlled phase reference line.
- Tightly integrate laser to RF synchronization.
- Review beam diagnostics and integration with instrumentation.
- Deploy EPICS control system.

Collaboration proposal: LBNL/ANL

- The collaboration will leverage off both engineering and physics experience at LBNL in designing controls and beam measurements for LCLS-II, HiRES, PIP-II, PPU and ALS-U LLRF systems. It will align the AWA LLRF system with other accelerators in the DOE complex.
- The LLRF upgrade will happen in the context of a larger effort, including a control system upgrade (EPICS) and a High power RF upgrade. Coordination is needed since all subsystems are tightly interconnected!
- LBNL will work with ANL to:
	- Provide a design solution for a new RF control architecture
	- Provide new LLRF chassis, identical to LCLS-II (and similar to HiRES) hardware
	- Assist in the characterization and deployment of RF controls in the field.
	- LCLS-II EPICS IOC and supporting tools, with initial custom software and firmware for AWA.
	- Path forward for future upgrades beyond the present SOW.

Description of work

Effort is separated in 3 phases:

• Phase 1: SOW definition and RF chassis production

- o Define effort and responsibilities (Completed)
- o Identify and order long-lead items for RF and MO/LO chassis (Completed)
- o Manufacture 3 LCLS-II 1.3 GHz LLRF chassis (In progress)

• Phase 2: Characterize present AWA RF system stability

- o Use LBNL-built hardware in "witness mode" during accelerator operations
	- Basic software functionalities provided, but any custom high-level screens will be developed by ANL personnel
- o Perform and analyze out-of-loop measurements of the characterize baseline performance

• Phase 3: Deploy LBNL LLRF system as driver system for the accelerator.

- o Deploy LBNL hardware, firmware and software at AWA
- o Characterize performance of newly deployed hardware
- o Establish plans for future upgrades: Laser-to-RF synchronization, phase reference line, produce more RF chassis for increased performance and simplified architecture.

Phase 1 in detail:

• Summary of LBNL responsibilities:

- o Initial firmware and software code base to support pulsed RF operation of AWA cavities using the 1.3 GHz LCLS-II LLRF platform.
- o Schematic diagram and BOM of the MO/LO generation chassis for AWA.
- o Schematic diagram and BOM of the 1.3 GHz hardware cavity emulator chassis.
- o Assistance with the installation and deployment of the LCLS-II LLRF hardware, firmware and EPICS IOC connected to a cavity emulator in the Lab.
- o Assistance with deployment of LLRF hardware, software and firmware in the field at AWA.
- o Assistance with tests and RF measurements of the installed deployment at AWA.
- o Provide a flexible electronics design for future upgrades (laser synch, reference line, etc.)
- o Provide a design path for the LLRF-side of laser-to-RF synchronization which bypasses the current hardware

• Procurements in place:

- o All components for 3 LCLS-II 1.3 GHz LLRF chassis, except for up/down converters and FPGA boards
- o All long-lead items for RF and MO/LO chassis ordered
- o Contract established with manufacturing house for RF chassis assembly

LBNL hardware

- LCLS-II 1.3 GHz RF controls chassis
	- o 2 drive channels
	- o 6 receive channels
	- o State-of-the-art RF performance
- AWA initial deployment: 3 RF controls chassis
	- o 6 drive channels total
	- o 18 receive channels total
	- o Minimum set of hardware to control 5 cavities based on channel count and budget constraints: the architecture is intricate, but can be simplified adding more hardware
- MO/LO chassis
	- o Provides necessary (synchronous) RF frequency references: 1300 MHz main reference, 1320 MHz LO signal, and 81.25 MHz reference for the laser system

Example of system deployment: LCLS-II Linac (280 cavities)

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F1.3-03 Cavity 2 out-of-loop -7.2 dBFS; phase error: 1.63e-03 degrees rms (0.1 Hz - 5.0 kHz) 170705 1730 Icls2

Example of deployment and performance: HiRES Gun

A2 -90.07 **-9.23** -104.09 -100.99 -105.52

A1 -9.17 -93.39 -103.51 -102.28 -104.80

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AWA current system characterization with LBNL hardware

Potential test points:

- (1) 1.3GHz LLRF driving RF gate & Level control boxes
- (2) LLRF Gate & Level control output
- (3) Pulsed Klystron drive signal (using directional couplers)
- (4) Pulsed Klystron output (attenuated signal from waveguide bidirectional coupler)
- (5) Pulsed RF forward and reflect signal before feed into RF cavities (attenuated signal from bidirectional couplers)
- (6) Cavity pickup signals from field probe in cavity(attenuated signal).

With 18 ADCs we would read FWD, REV and Probe from each cavity/klystron + laser signal

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LBNL LLRF system implementation at AWA

The initial deployment will be replacing old AWA LLRF boxes with BACI LLRF box with minimum signals (the signals currently monitored with AWA old LLRF system, most of them were not drawn here for simplicity) monitored.

After the initial deployment, spare monitoring channels on the BACI boxes will be used to monitor signals from additional monitoring points from RF distribution waveguide system.

LBNL LLRF system implementation at AWA

Laser system 81.25 MHz Will drive 4-5 systems Will read up to 18 RF signals 1300 MHz MO/LO (5 Probes, 5 FWD, 5 Rev, 1 laser, …) BOX 1320 MHzActual architecture to be discussed, based on ethernet needs, high level operations and future upgrades **BACILLRF BOX1 BACILLRF BOX3 BACILLRF BOX2 TTL Trigger** RF pulse enable AM85 500 W RF pulse enable RF_{F} pulse enable F \neg AM85 500W AM85 500W $(15us)$ AM85 500W(15us) RF pulse enable⁻ $(15us)$ pulsed AMP pulsed AMP pulsed AMP ∫ pulsed AMP $(15us)$ KL₂ Signal from
cavity of interest KL₁ ્રિ ⊋ ⊋ RF cavities Drive LIN AC1 $-LINAC2$ LIN AC3 HLIN AC4 IN AC5 LIN AC6 WIT Gun itness LIN AC Gun

Future upgrades

- Laser-to-RF synchronization
	- Ideally a separate chassis including photodiode(s) and HV amplifier for piezo-actuator
- Phase reference line
	- o Phase drift between LLRF systems is invisible to LLRF and is a direct contributor to RF phase instability.
- Event-based, RF-synchronous timing system
	- o Provides ability to trigger instrumentation along the machine synchronously
	- o Provides ability to time-stamp data in acquisition systems, needed to compute correlations, post-mortem fault analysis and future ML-based tuning
- Fabricate more RF hardware
	- o Simplify architecture
	- o Increase channel-to-channel isolation (cavity to drive) from 90 to 120 dB

Effort estimates: LBNL Team

