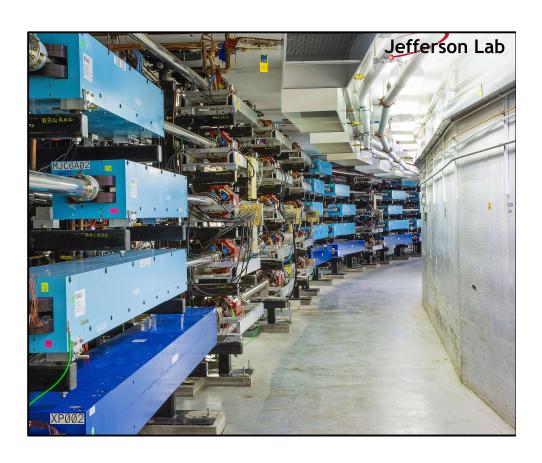
ASW 2021: Advanced Technology and Methods for Accelerator Activities

CEBAF Personnel Safety
System Upgrades @ Jefferson
Lab



Wednesday, October 6, 2021 1244 – 1306 CST



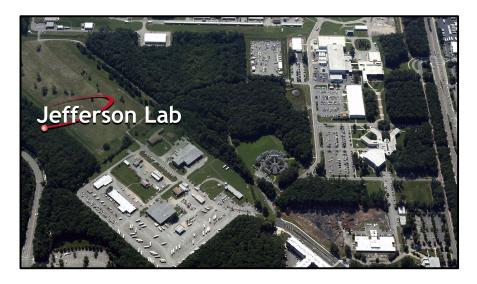


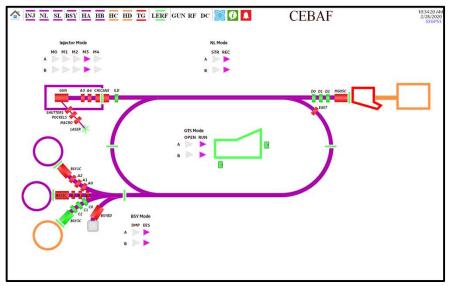




Introduction

- Jefferson Lab operates the Continuous Electron Beam Accelerator Facility (CEBAF)
 - Circa 1995
 - Since upgraded to 12 GeV in 2012
- JLab aiming to increase CEBAF availability while at the same time address aging infrastructure
 - Significant investments being made to renew systems and address obsolescence.
- JLab Safety System Group (SSG) manages the engineered safety systems at CEBAF
 - Jerry Kowal (Group Leader)
 - Roger Araiza
 - Savvy Anbazhagan
 - Gabriela Aguilar
 - Paul Metcalf
 - Scott Bruhwell
 - Lawrence Hurt
 - Mike Beizer

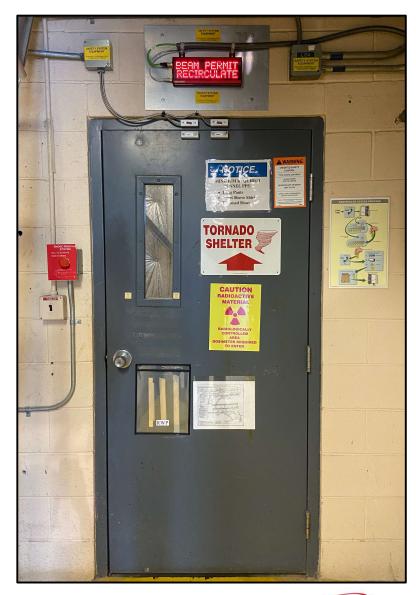






Scope of Personnel Safety System

- Personnel Safety System
 - Electrical hazards
 - Beam transport to occupied segment
 - Protection of beam containment components
 - High radiation in occupied areas
 - Due to operation of beam or high power RF
- Machine Protection System
 - Beam loss within secured area
 - High radiation within secured area
 - Protection of beamline components
 - · Excluding beam stoppers
- Beam Over Power
 - Beam Energy Limiting System
- Oxygen Deficiency Hazard
 - ODH Annunciation System (Administrative)
- Access to Low Oxygen Area
 - Training (Administrative)
- Access to High Radiation Area
 - RADCON, Training (Administrative)
- Laser Exposure Hazard
 - Local hard-wired interlocks





Hazard Identification and Risk Reduction

- Hazard Analysis Review
 - CEBAF hazards are quite well understood from 20+ years of operation
 - PSS upgrade is not driven by safety deficiencies or new hazards/requirements
 - All extant safety functions maintained or improved
 - Hazard analysis mainly focused on the potential to introduce new hazards
- Other hazards, initiating events or contributors which were rereviewed included
 - Annunciation of status of hazards
 - Medical emergency within PSS controlled segment
 - Fire within PSS controlled segment
 - Tornado
 - MCC unoccupied during shutdowns
- Some improvements to hardware and software design were identified and are being implemented

Overall PSS Safety Functions

- Existing documentation and requirements were reviewed thoroughly
- 16 Overall Safety Functions were identified which are now summarized
 - Hundreds of lower level requirements
- Access Control
 - OSF-01: Facilitate inspection of the accelerator enclosure to ensure all personnel are vacated prior to securing the enclosure
 - OSF-02: Prevent access to the accelerator enclosure when there exists an internal hazard to personnel safety
 - OSF-03: Shutdown the accelerator when a hazard to personnel safety exists due to an access control violation (separation of people from beam)
 - OSF-04: Allow disabling of access control system maglocks from within the accelerator to facilitate emergency exits
 - OSF-05: Allow access to the accelerator enclosure whenever required to mitigate an emergency
- Hazard Annunciation
 - OSF-06: Provide audible and visual warnings within the accelerator enclosure prior to transitioning to a powered state
 - OSF-07: Provide audible and visual warnings within the accelerator enclosure when hazards are present in unsecure areas
 - OSF-08: Display the status of accelerator hazards at external entry points and control centers



Overall PSS Safety Functions

Personnel Safety

- OSF-09: Maintain personnel safety inside the accelerator enclosure when the access control system allows access
- OSF-10: Provide easily accessible emergency stop pushbuttons within the accelerator enclosure and at external control centers which can be used to make the accelerator safe

Beam Containment

- OSF-11: Shutdown the accelerator when a hazard to personnel safety exists due to loss of beam containment (separation of beam from people)
- OSF-12: Shutdown the accelerator when required to protect beam containment components

Radiation Containment

- OSF-13: Shutdown the accelerator if radiation levels in accessible areas exceed operating limits
- OSF-14: Shutdown the accelerator when a hazard to personnel safety exists due to removal of non permanently fixed radiation shielding
- OSF-15: Shutdown radiation generating systems/sub-systems/components (high power RF) if radiation levels in accessible areas exceed operating limits
- OSF-16: Shutdown radiation generating systems/sub-systems/components (high power RF) when a hazard to personal safety exists due to loss of radiation containment systems



Mission, Scope and Timeframe

- Mission
 - Upgrade all CEBAF PSS PLC hardware to address obsolescence and reliability concerns
 - Extend PSS Proof Test Interval thereby improving beam time availability
- Scope
 - Replace all legacy PLC hardware
 - Includes
 - PLC's
 - I/O Interfaces
 - Power Supplies
 - Network Switches
 - Excludes
 - (Most) field I/O (sensors and actuators)
 - Uninterruptible Power Supplies
 - Some field I/O being upgraded on a case by cases basis
 - New IP based annunciator displays
 - Upgraded combined horns/sirens (24V)
 - Light curtains to replace door micro-switches inside fire door push to escape bar's
 - Opportunity to incorporate latest standards and best practices
 - Engineering according to IEC 61508
- Timeframe to complete is 4-5 years
 - Replacement hardware necessitates a complete software re-write
 - Installation work must be scheduled during major shutdowns
 - Recently completed Injector and North Linac segments
 - Approximately 50% completed



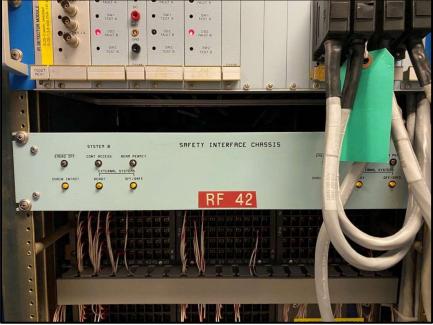
Mission 1: Replace PSS PLC Hardware

- Hardware Assessment
 - Legacy Hardware
 - Non-safety rated Schneider Modicon PLC's circa 1990's
 - Fieldbus Communication
 - Non safety rated Modbus+ over combination of older generation multimode fibers and Coax
 - First segments upgraded using Siemens S7 300 F CPU's
 - Has (with few exceptions) been reliable
- Replacement Hardware Selection
 - Redundant PLC's maintained on a per-segment basis
 - Siemens S7 1500 F series safety rated PLC's
 - Siemens ET-200 SP distributed I/O interfaces
 - Siemens modular power supplies and networking switches
 - Phoenix Contact safety relays used for relay outputs
 - Fieldbus and Inter-PLC communication
 - Safety rated Profinet communication over replacement single mode fibers and Cat 6A Ethernet



Old Hardware: CPU, I/O and Interface Chassis

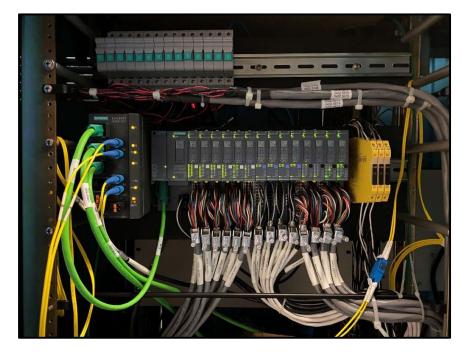






New Hardware: CPU and Distributed I/O







New Hardware: Magnet / RF Interface Chassis





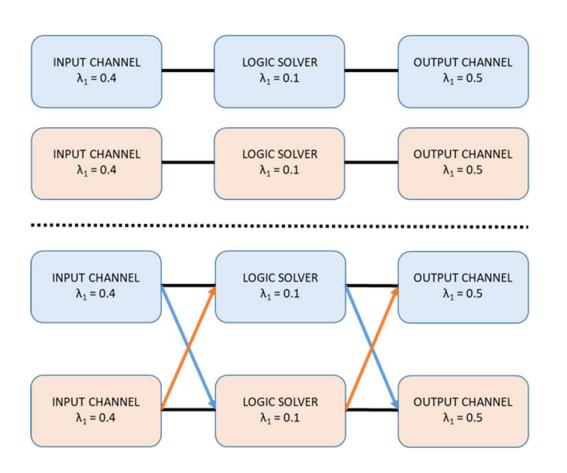
Mission 2: Extend Proof Test Interval

- Problem: Extending PTI will decrease safety
 - First we need to find ways to increase safety

$$PFD_{avg} = \frac{\lambda_{d_u}^2 T^2}{3}$$

- Options to Increase Safety and Availability
 - Install More Hardware (more I/O channels i.e. 2003, 2004)
 - Very high cost and high complexity
 - Install Better Hardware (i.e. more reliable hardware)
 - Very high cost but low complexity
 - Modify Existing Architecture and Install Diagnostics
 - · Low cost and medium complexity
 - · Minimal additional hardware required
 - Additional network switches and cables required
 - Requires
 - Inter-PLC Communication
 - Voting implemented in software
 - Programming of Diagnostic Alarms
- Revised architecture will improve safety hence provides additional risk reduction for the extant safety functions
 - Some but not all of this additional safety margin will be "consumed" by extending the Proof Test Interval
 - Win-Win: Improvements made to Reliability, Availability, Maintainability and Safety

Solution Part 1: Modernize Architecture



$$\lambda_G = (\lambda_1 + \lambda_2 + \lambda_3)^2$$



$$\lambda_G = (\lambda_1)^2 + (\lambda_2)^2 + (\lambda_3)^2$$

Solution Part 2: Add Diagnostics

- Original system did not allow for any diagnostics at all
 - Diagnostic coverage was essentially zero
 - This creates a high risk of Fault Accumulation
 - Also creates a high burden of Proof Testing
- Replacement system developed with online diagnostics and nondestructive testing as priorities
- With communication links installed between the redundant PLC, it is now possible to perform online diagnostics and implement fault control

$$PFD_{G} = 2. t_{CE}. t_{GE}. (\lambda_{DD} - \beta_{D}. \lambda_{DD} + \lambda_{DU} - \beta. \lambda_{DU})^{2} + \beta_{D}. \lambda_{DD}. MTTR + \beta. \lambda_{DU}. \left(MRT + \frac{T}{2}\right)$$
$$t_{CE} = \frac{\lambda_{DU}}{\lambda_{D}}. \left(\frac{T}{2} + MRT\right) + \frac{\lambda_{DD}}{\lambda_{D}}. MTTR \qquad t_{GE} = \frac{\lambda_{DU}}{\lambda_{D}}. \left(\frac{T}{3} + MRT\right) + \frac{\lambda_{DD}}{\lambda_{D}}. MTTR$$

- Examples
 - Redundant Channel Monitor
 - Beam Valve Monitor
 - Laser Shutter Monitor

Solution Part 2: Add Diagnostics

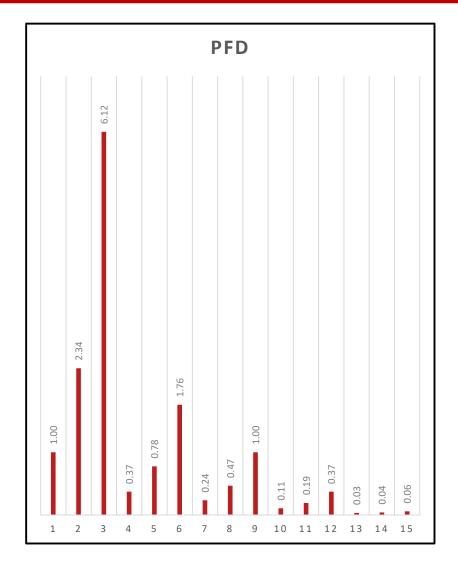
 Improving the Diagnostic Coverage Fraction makes a huge impact to safety by increasing the Safe Failure Fraction

$$DCF = \frac{\lambda_{D_d}}{\lambda_{D_d} + \lambda_{D_u}} \quad SFF = \frac{\Sigma \lambda_S + \Sigma \lambda_{D_d}}{\Sigma \lambda_S + \Sigma \lambda_{D_d} + \Sigma \lambda_{D_u}}$$

- We are conservatively assuming only 60% coverage will be achieved but in reality we should achieve well over 75% coverage and probably over 90% coverage
- When combined with the architectural improvements made above, the additional diagnostics coverage will add significantly to the safety margins available
- These safety margins can be used to offset the planned extension to the Proof Test Interval
- Proof Testing need only detect faults which cannot be detected online.
 Future Proof Testing will be
 - Shorter In Duration
 - Less Frequent
 - Non Destructive

Effect of Diagnostics

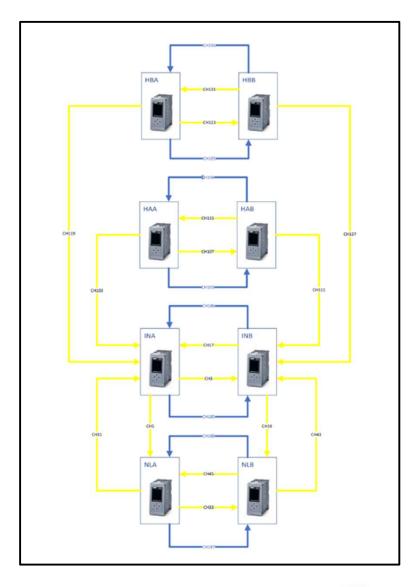
DCF	SFF	ID	PTI	PFD
0%	60%	1 2 3	6 12 24	1.00 2.34 6.12
60%	84%	4 5 6	6 12 24	0.37 0.78 1.76
75%	90%	7 8 9	6 12 24	0.24 0.47 1.00
90%	96%	10 11 12	6 12 24	0.11 0.19 0.37
99%	99.6%	13 14 15	6 12 24	0.03 0.04 0.06





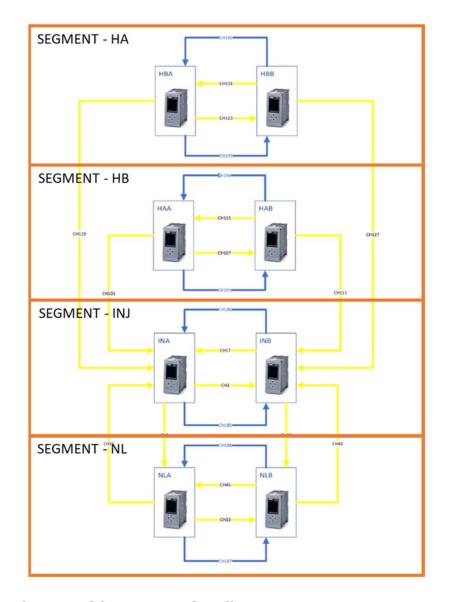
Networking Architecture

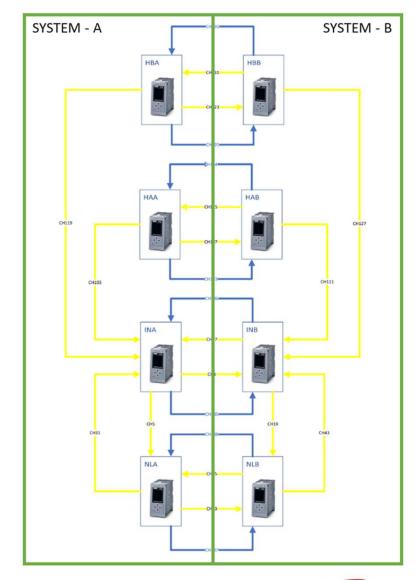
- Implementing Inter-PLC communication necessitated a re-design of the process network architecture
- The process network was divided into segments and systems. Communication is only possible for devices within the same segment or system
- Inter-PLC Communication is therefore allowed
 - Between systems within the same segment
 - Between segments within the same system
- Inter-System and Inter-Segment communication are functionally independent
 - Faults with Inter-Segment communication on System A cannot effect System B and vice versa
 - Similarly faults with Inter-System communication within a particular segment cannot effect any other segment
 - Furthermore communication between System A and System B is electrically isolated with fiber optics





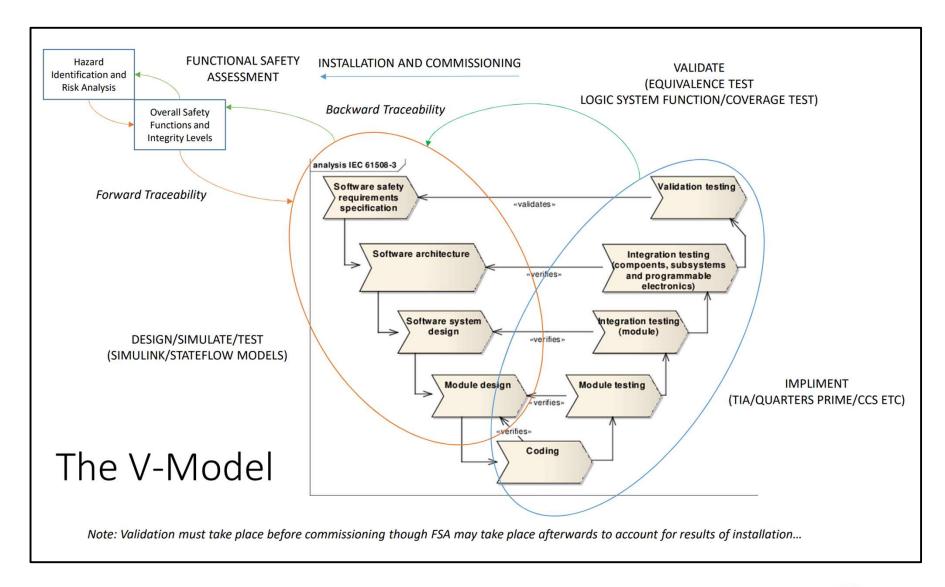
Networking Implementation







V-Model

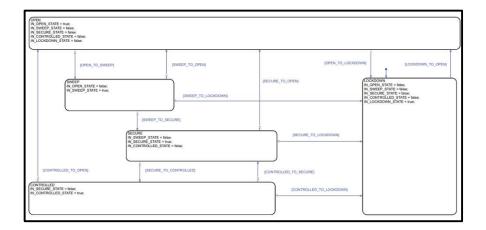




Software Tools

- Implementation of a CAE workflow is considered best practice and is highly recommended by IEC 61508 for SIL 3
 - Model Based Systems Engineering
 - Graphical: Function Block Diagramming (FBD)
 - Fully described logical and functional requirements
 - Modular and hierarchical
 - Executable and testable
- Design
 - Simulink
 - Stateflow
 - Fixed Point Designer
- Verification
 - Simulink
 - Simulink Check
 - Simulink Coverage
 - Simulink Design Verifier
- Implementation
 - TIA Portal v16/17
 - · Step 7 Professional
 - Step 7 Safety Advanced
- Validation and Certification
 - Existing certification procedures were re-used
 - This ensures the upgrades do not invalidate the extant safety functions or introduce unintended functionality

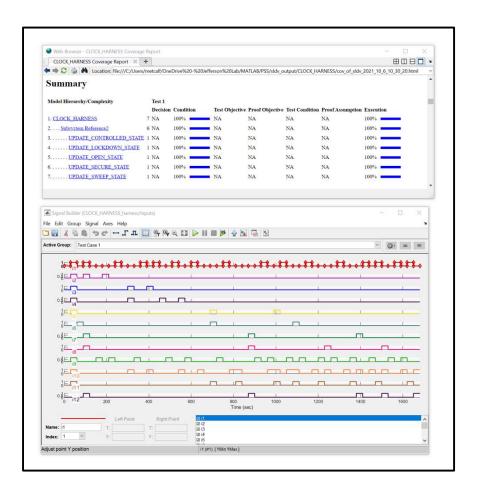






Increasing Systematic Capability

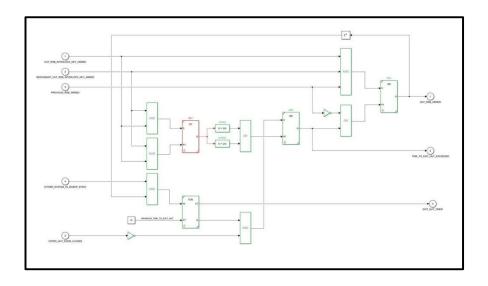
- Fixed Point Designer
 - Optimize custom fixed point data types
 - Measure min/max signal ranges throughout code
 - Determine precision achievable for fixed point designs
- Simulink Check
 - Compliance checks with IEC 61508 modelling guidelines
- Simulink Coverage
 - Verification of model and code coverage against objectives
 - Uses standard methods such as MCDC
 - Measure coverage provided by manually authored procedures
- Simulink Design Verifier
 - Implements advanced error detection using formal methods proving the absence of
 - Dead (un-executable) code and logic
 - Memory access violations
 - Integer Overflows
 - Parameter Underflows
 - Divide by zero
 - Automatic test case generation to measure maximum code coverage achievable

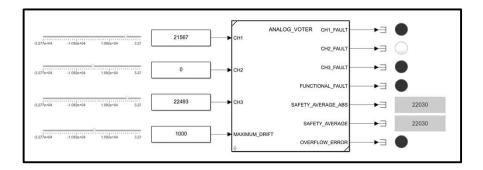




Unit Testing

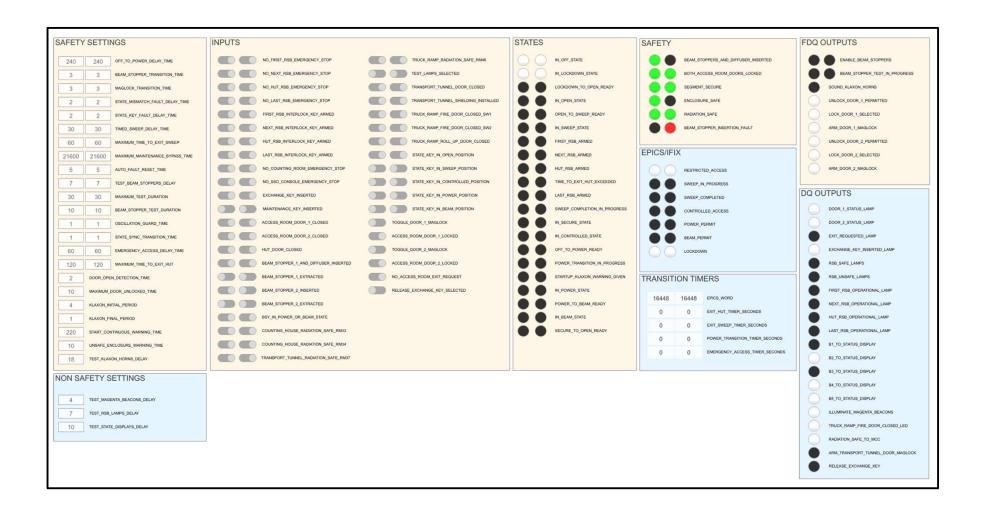
- Unit testing is performed in Simulink using both semiformal and formal methods
- Once modules are completed they are committed to a library of safety certified function blocks







Integration Testing

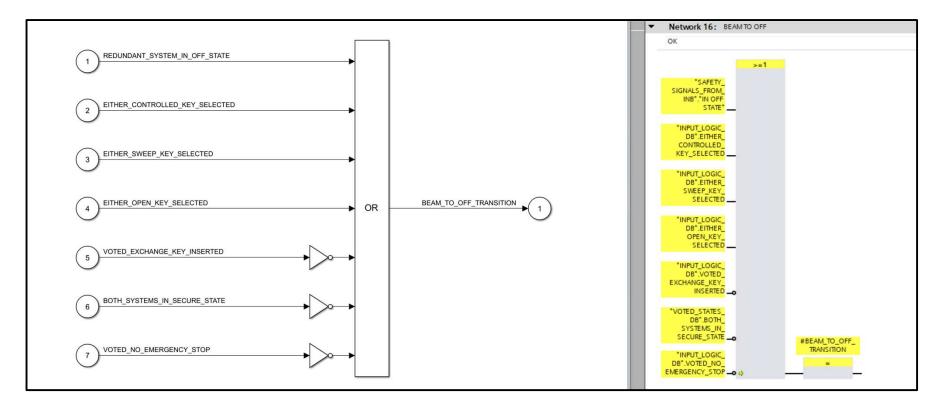




Implementation – Model to Code

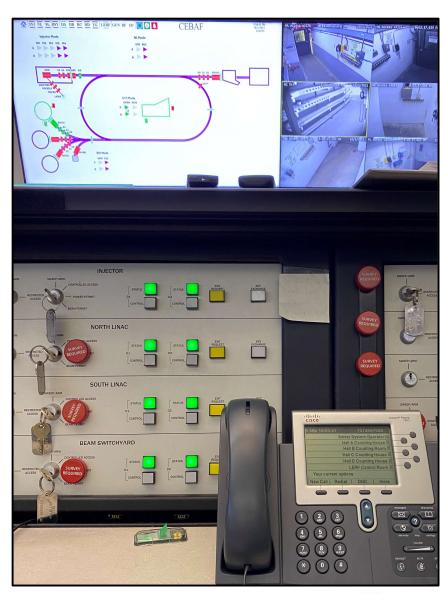
Simulink

TIA Portal



Security

- Firewalls were introduced to separate the safety system process network from the accelerator network
- Note that the accelerator network is also secured by IT using multi-factor authentication
- External hosts includes JLab atomic clock time servers
 - Accurate time stamping of alarms is essential to permit detailed sequence of events analysis





Progress

Segment	Status	I/O (A)	I/O (B)	Diag. (A)	Diag. (B)
Injector	Completed	119	95	243	127
North Linac	Completed	360	286	666	281
South Linac	In Progress	312	252	TBD	TBD
Beam Switchyard	Not Started	205	150	TBD	TBD
Hall A	Completed	102	59	167	55
Hall B	Completed	93	56	153	51
Hall C	Partial	131	76	TBD	TBD
Hall D / Tagger	Partial	155	79	TBD	TBD

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- Upgrades to the CEBAF Personnel Safety System are ~50% completed
 - Updated architecture
 - Inter-PLC communication
 - Online diagnostics
- These changes will increase the level of risk reduction (safety) provided by the PSS by up to 10X
 - Equivalent to a whole SIL level
- The increased safety margin will be used to justify extension of the PTI to 12 months or longer







