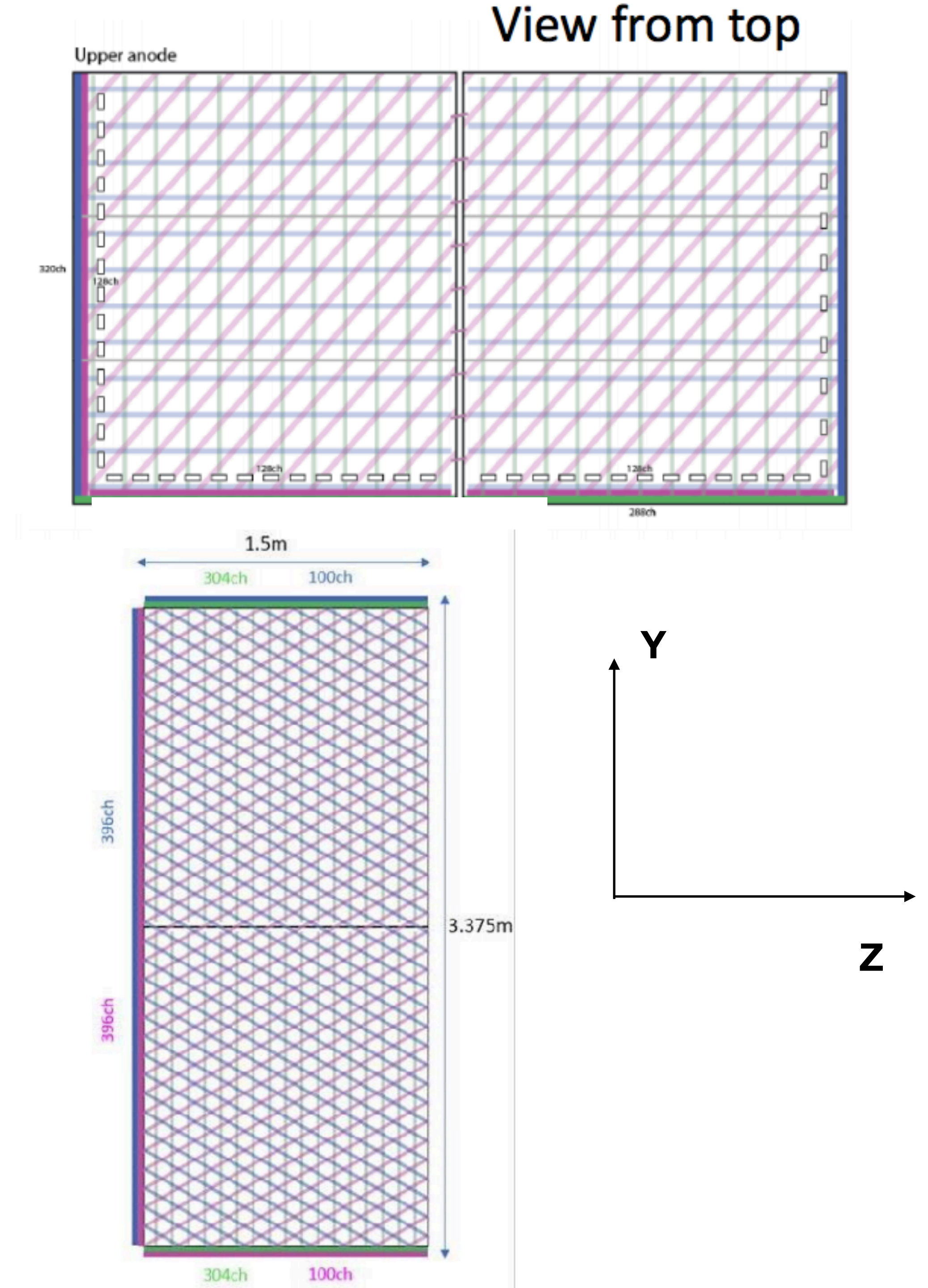


CVN for Vertical Drift

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13th Sept, 2021

Introduction

- Deciding on a Vertical Drift design is a top priority for DUNE moving forward
- Multiple options available :
 - 2-view : 1 induction, 1 collection — (0, 90) deg
 - 3-view : 2 induction, 1 collection — (0, 48, 90) deg (CDR geometry)
 - 3 view : 2 induction, 1 collection — (-30, 30, 90) deg
- 3 views gives us redundancy and in principle better 3D reconstruction
- Tricky to evaluate the physics case for each design without developing the whole reconstruction infrastructure



CVN

- Idea is to use CVN as a possible input to deciding which design might be better
- Highly performant neutrino ID [<https://arxiv.org/abs/2006.15052>]
- Just uses images of hit clusters as inputs -> downstream reco not necessary
- Can help us quantify differences in performance between different designs
- Preliminary study on this in Oct 2020 by Sandro, Saul et al. :
 - Used horizontal drift simulation, trainings done for 1-view, 2-view, 3-view options by manually removing one of the view inputs each time
 - Interesting results showing small drop in performance across the trainings

DUNE CVN (views 0, 1, and 2)

	precision	Recall	F1 score	#events
CC ν_μ	0.93	0.96	0.95	26108
CC ν_e	0.93	0.97	0.95	25665
CC ν_τ	0.66	0.37	0.47	5813
NC	0.94	0.95	0.94	42382

Collection plane (view 2)

	precision	Recall	F1 score	#events
CC ν_μ	0.91	0.94	0.92	26108
CC ν_e	0.90	0.94	0.92	25665
CC ν_τ	0.59	0.26	0.36	5813
NC	0.91	0.93	0.92	42382

Induction planes (views 0 and 1)

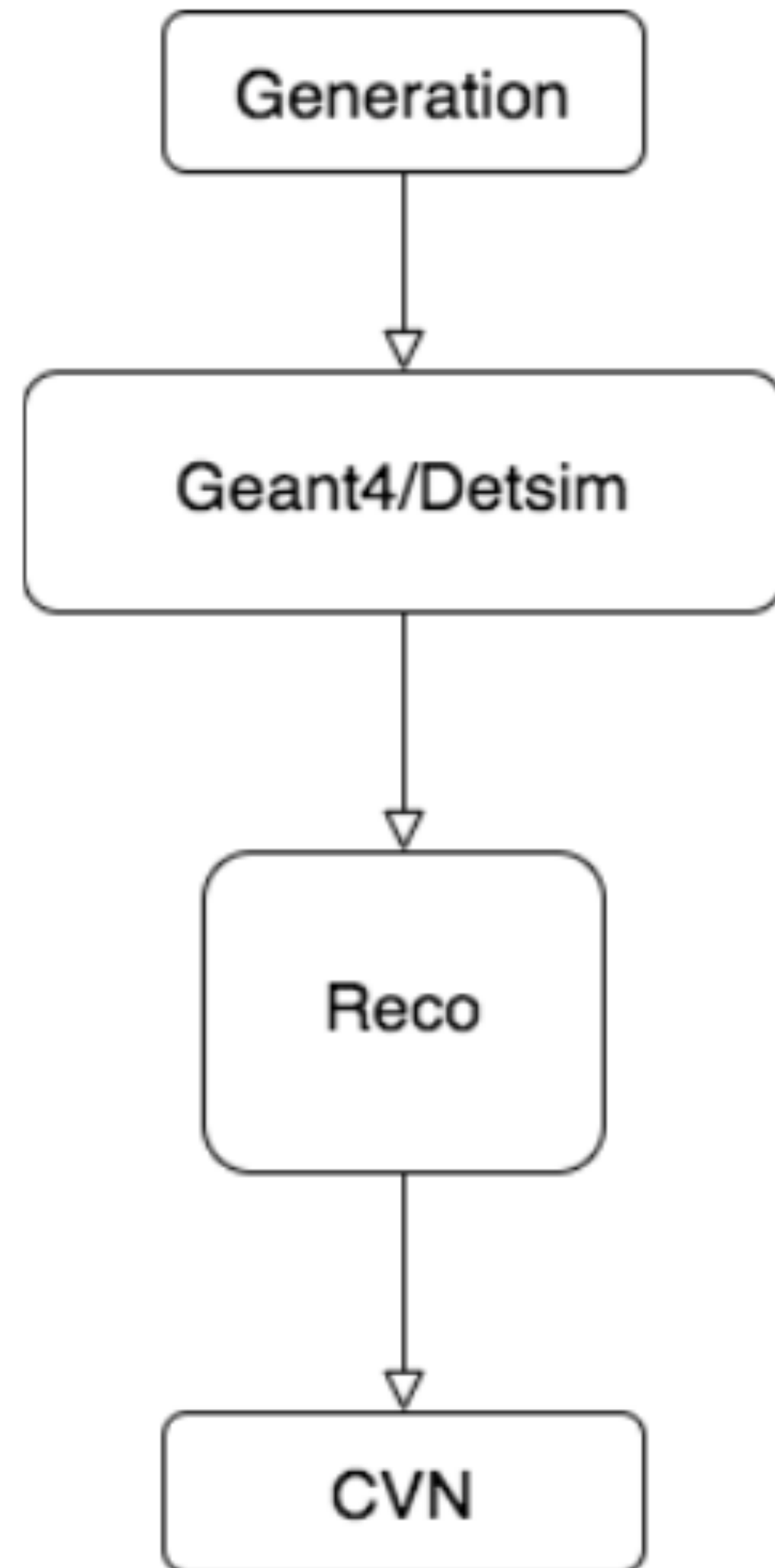
	precision	Recall	F1 score	#events
CC ν_μ	0.91	0.95	0.93	26108
CC ν_e	0.90	0.95	0.92	25665
CC ν_τ	0.59	0.27	0.37	5813
NC	0.92	0.93	0.92	42382

Induction plane, collection plane (views 1 and 2).

	precision	Recall	F1 score	#events
CC ν_μ	0.91	0.95	0.93	26108
CC ν_e	0.90	0.95	0.92	25665
CC ν_τ	0.58	0.31	0.40	5813
NC	0.92	0.92	0.92	42382

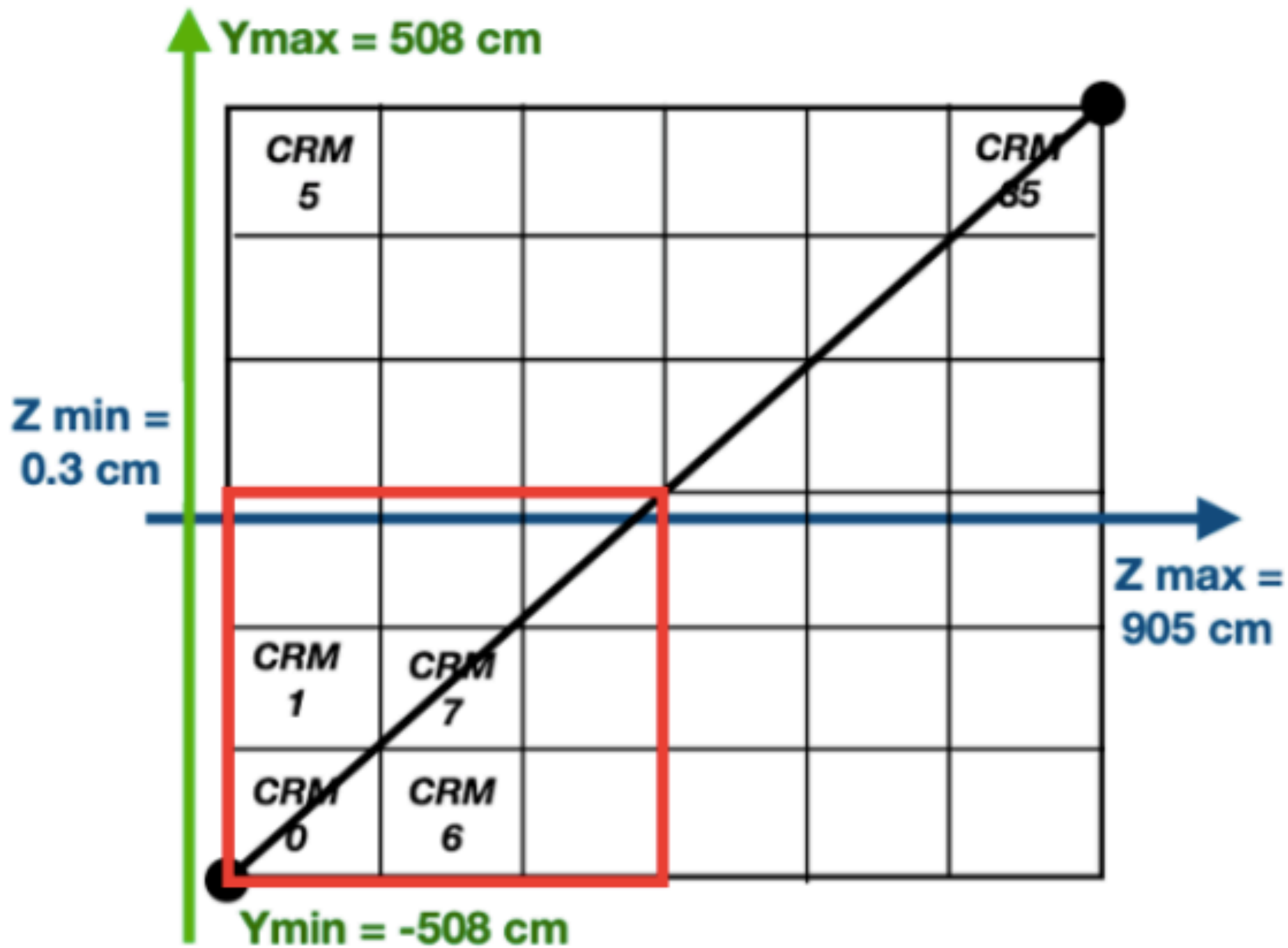
<https://indico.cern.ch/event/864638/contributions/4041234/attachments/2132971/3592132/SP-EPNU-29oct20.pdf>

VD Simulation



- fcls exist for the 2-view and CDR reference geometry — (0, 48, 90) deg
- For the other 3-view design, geometry workspace already created and wire-cell simulation already setup by Slavic/Haiwang
 - Made fcls for each of these steps
- All of these for the 1x6x6 VD geometry workspace (i.e 36 charge readout modules [CRMs] with one drift volume)
- Detsim uses json config in DUNEWireCell to produce RawDigit products
 - `pgrapher/experiment/dune-vd/wcls-sim-drift-simchannel-3view30deg.json`
- Worked out of Dom's refactor branch : `feature/dbrailsf_refactor` until recently
- Using another feature branch off of that for CVN-related development work (`feature/bnayak_cvnvd`)

VD Geometry



- 1x6x6 geometry workspace
- 1 drift volume
- 298 strips in 2 induction planes
- 304 strips in 1 collection plane
- Checked numbering convention for CRMs in the wire-cell detsim vs larsoft and they're consistent

Reconstruction — Hit Finding

```
195 # gauss hit finder for VD module
196 dunevdfd_gaushitfinder: @local::gaus_hitfinder
197 dunevdfd_gaushitfinder.HitFinderToolVec.CandidateHitsPlane0.RoiThreshold: 6.0
198 dunevdfd_gaushitfinder.HitFinderToolVec.CandidateHitsPlane1.RoiThreshold: 0.6
199 dunevdfd_gaushitfinder.HitFinderToolVec.CandidateHitsPlane2.RoiThreshold: 0.6
200 dunevdfd_gaushitfinder.InitWidth: [6.0, 6.0, 6.0]
201 dunevdfd_gaushitfinder.AreaNorms: [13.25, 13.25, 13.25]
202 dunevdfd_gaushitfinder.MaxMultiHit: 4
203 dunevdfd_gaushitfinder.Chi2NDF: 50
204 dunevdfd_gaushitfinder.LongMaxHits: [ 25, 25, 25 ]
205 dunevdfd_gaushitfinder.LongPulseWidth: [ 10, 10, 10 ]
206 dunevdfd_gaushitfinder.PeakFitter:      @local::peakfitter_mrqrt
207
```

- Currently following Slavic's hit-finder talk for gaus-hit threshold parameters : https://indico.fnal.gov/event/50066/contributions/219793/attachments/145290/184914/vdfd_hitreco.pdf
- Applied to new 3view30deg design
- 1st induction plane has higher threshold to deal with pepper-noise issue (discussed previously, solved by new wire cell sig-proc parameters. New config should be available soon)

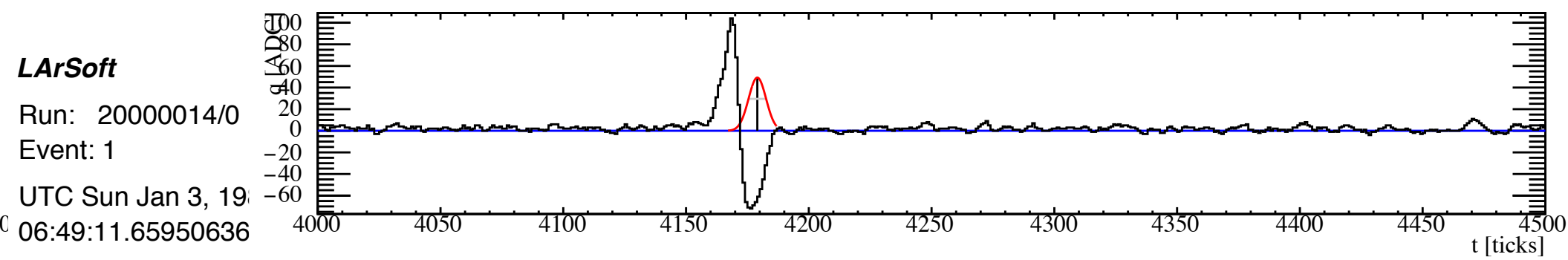
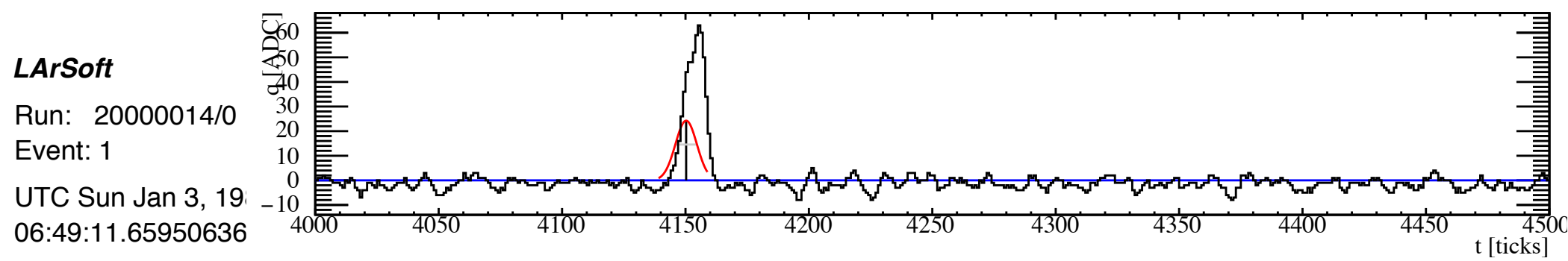
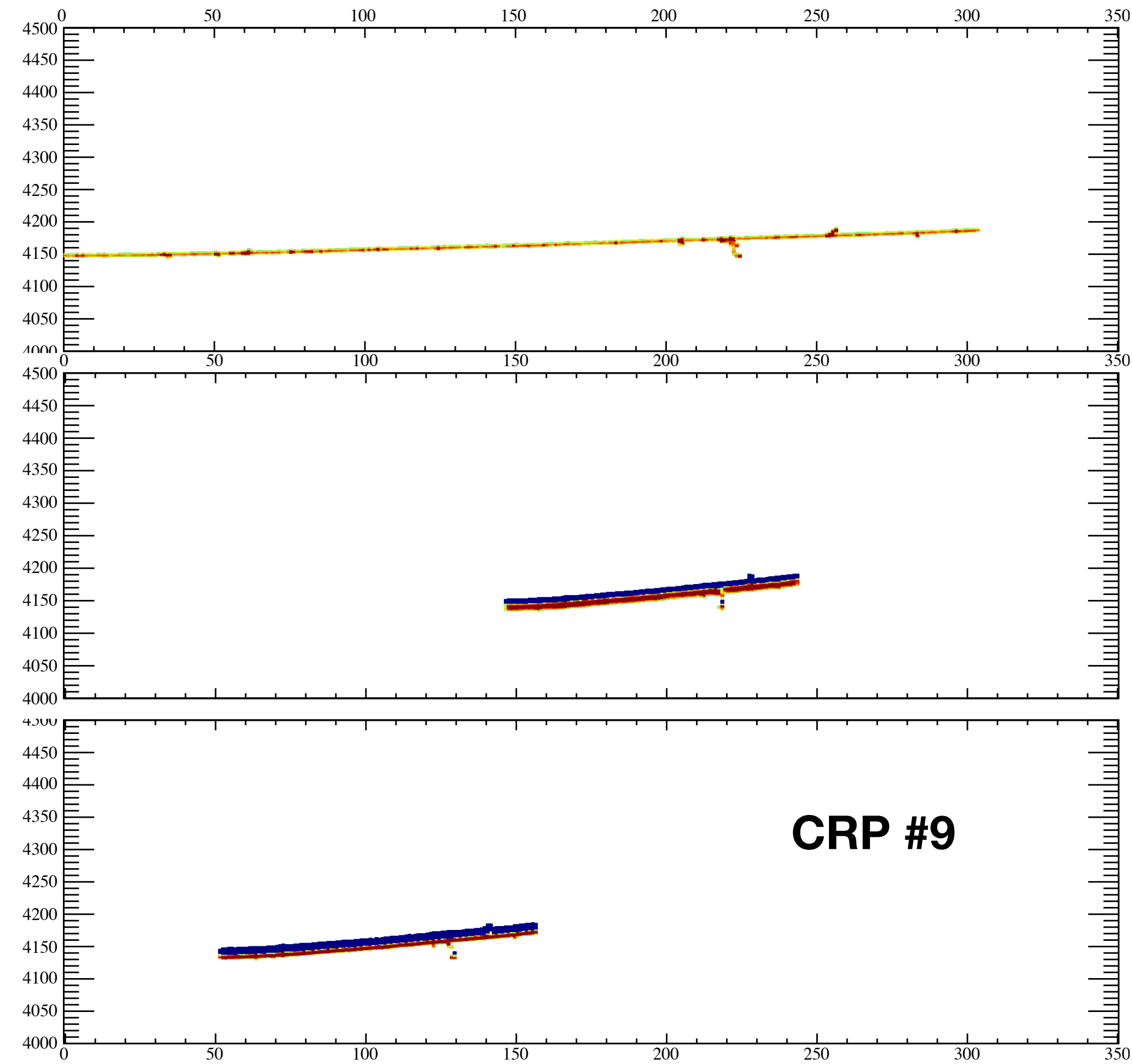
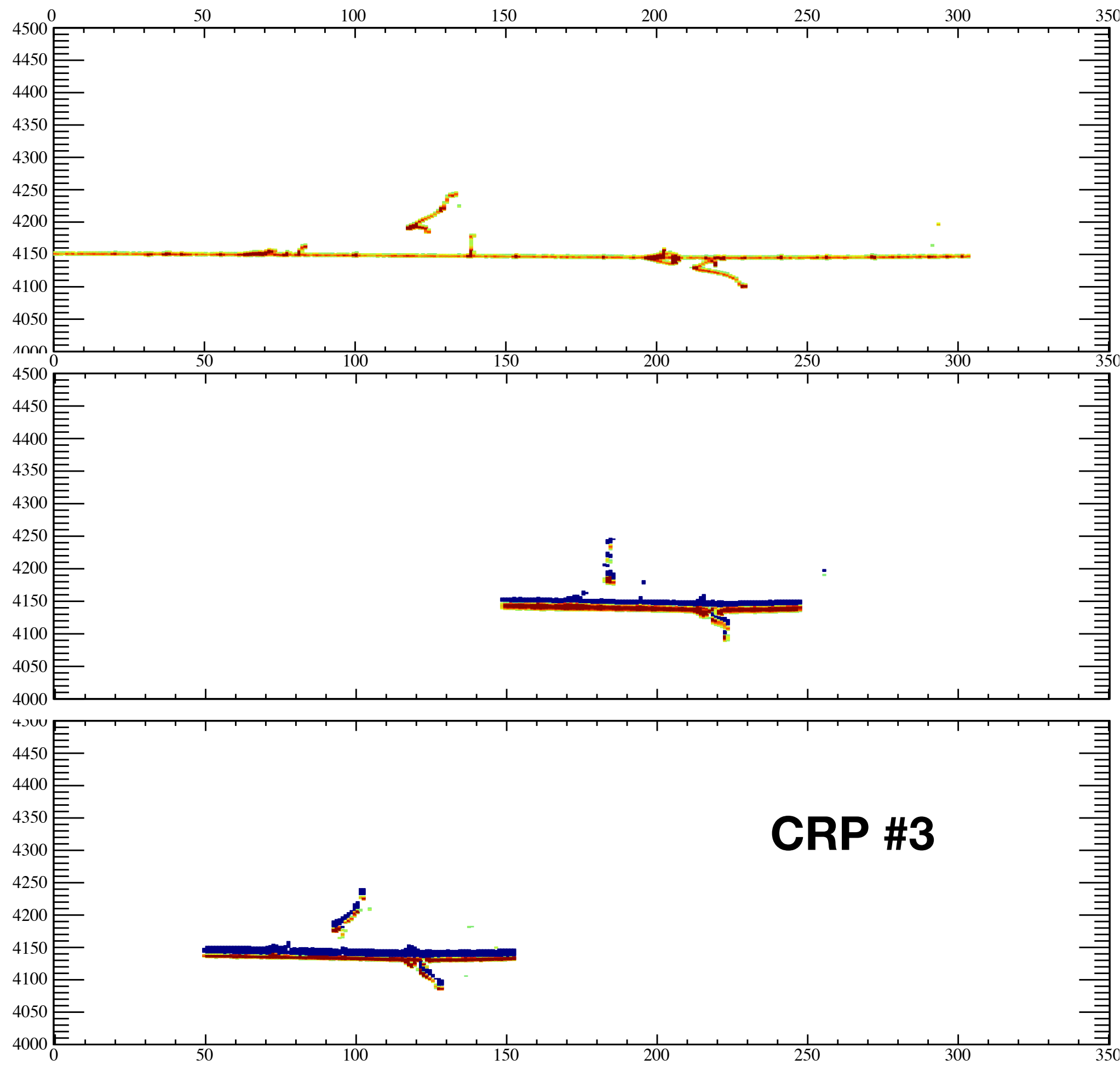
Reconstruction

PROCESS NAME	MODULE LABEL..	PRODUCT INSTANCE NAME.....	DATA PRODUCT TYPE.....	.SIZE
SinglesGen..	generator.....	std::vector<simb::MCTruth>.....1
SinglesGen..	rns.....	std::vector<art::RNGsnapshot>.....1
SinglesGen..	TriggerResults	art::TriggerResults.....-
G4.....	elecDrift.....	std::vector<sim::SimChannel>.....	.3110
G4.....	rns.....	std::vector<art::RNGsnapshot>.....3
G4.....	IonAndScint...	std::vector<sim::SimEnergyDeposit>.....	30783
G4.....	TriggerResults	art::TriggerResults.....-
G4.....	largeant.....	std::vector<simb::MCParticle>.....	.1744
G4.....	largeant.....	LArG4DetectorServicevolTPCActive	std::vector<sim::SimEnergyDeposit>.....	30783
G4.....	largeant.....	art::Assns<simb::MCTruth,simb::MCParticle,sim::GeneratedParticleInfo>	.1744
detsim.....	tpcrawdecoder.	simpleSC.....	std::vector<sim::SimChannel>.....	32400
detsim.....	tpcrawdecoder.	daq.....	std::vector<raw::RawDigit>.....	32400
detsim.....	rns.....	std::vector<art::RNGsnapshot>.....0
detsim.....	TriggerResults	art::TriggerResults.....-
Reco.....	TriggerResults	art::TriggerResults.....-
Reco.....	wclsdatanfsp..	wiener.....	std::vector<recob::Wire>.....	32400
Reco.....	gaushit.....	std::vector<recob::Hit>.....	.3920
Reco.....	gaushit.....	art::Assns<recob::Wire,recob::Hit,void>.....	.3920
Reco.....	wclsdatanfsp..	gauss.....	std::vector<recob::Wire>.....	32400
Reco.....	rns.....	std::vector<art::RNGsnapshot>.....0

- Event dump after wire-cell signal processing (recob::Wire) + gaushit (recob::Hit)

Event Displays

- Single fwd going muon

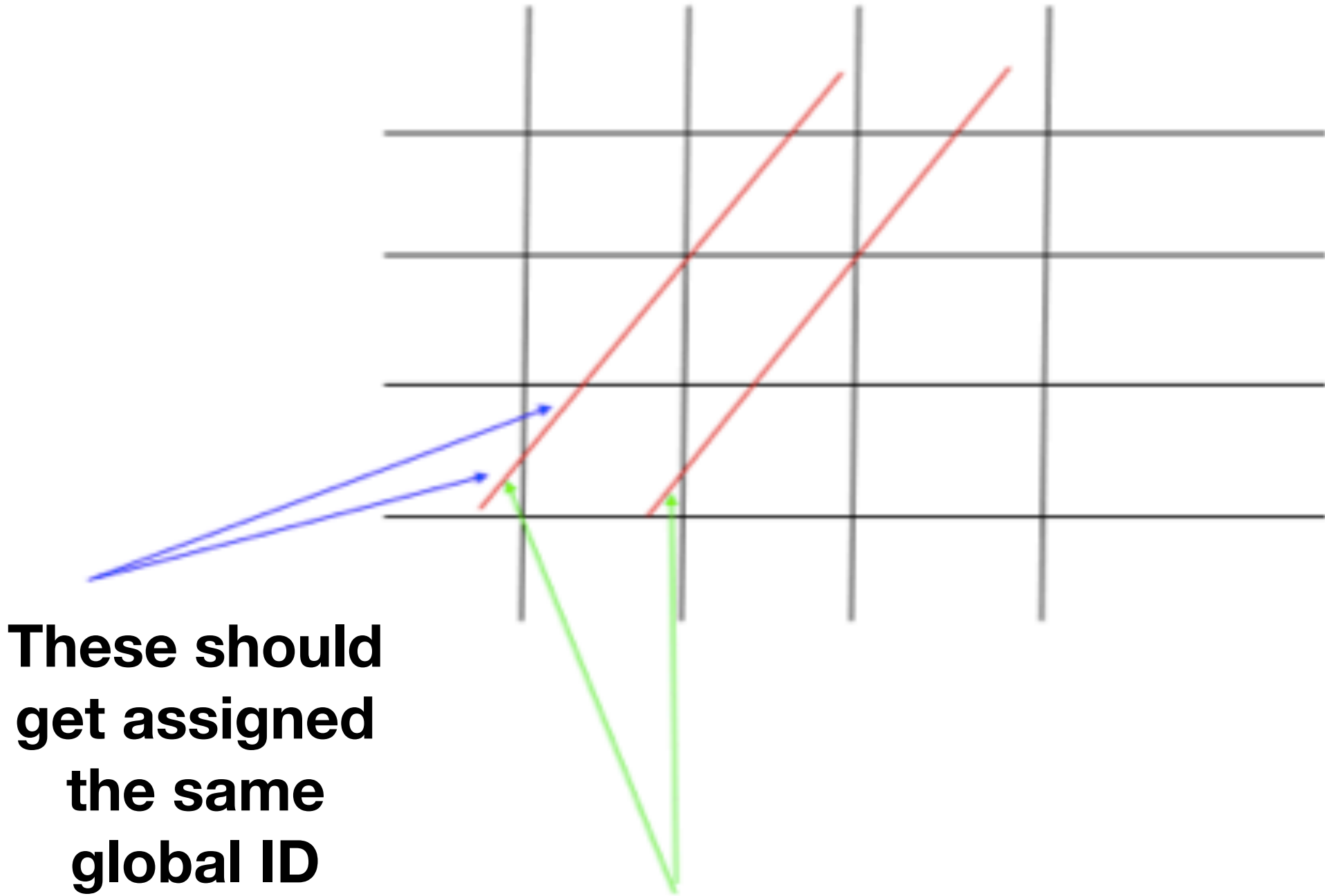


CVN

- Main module to create pixel map inputs from reconstructed files :
- Currently uses `recob::Hit(s)` from `gaud-hit` to populate 2D image of Wire ID vs TDC for each plane view
 - This is handled by the `CVNMapper` module
 - Takes into account events that cross multiple drift volumes as well (relevant for horizontal drift geometries, not so much for our scenario right now)
 - Calls a class ``PixelMapProducer`` that creates ``PixelMap`` objects to store in an art event
 - Workflow from there is fairly straightforward, uses a ``CVNZLibMaker`` module to convert these into compressed zip files (`` .gz `` format). Training data saved in separate txt files (`` .info `` format)
- `CVNMapper` fcl parameters :
 - `WireLength` : Set to 2880 for 1x2x6 Horizontal Drift workspace (max z-axis span)
 - `TimeResolution` : Set to 1600 — describes TDC range for pixel map (`tdc_mean-1600`, `tdc_mean+1600`)
 - `TdcWidth` : Set to 500 — condenses TDC ticks into 500 bins (Any reason for condensing 1600 to 500 specifically, rather than using an exact factor?)
 - For testing purposes, I'm not changing any of these currently except — `TimeResolution` to 1500.

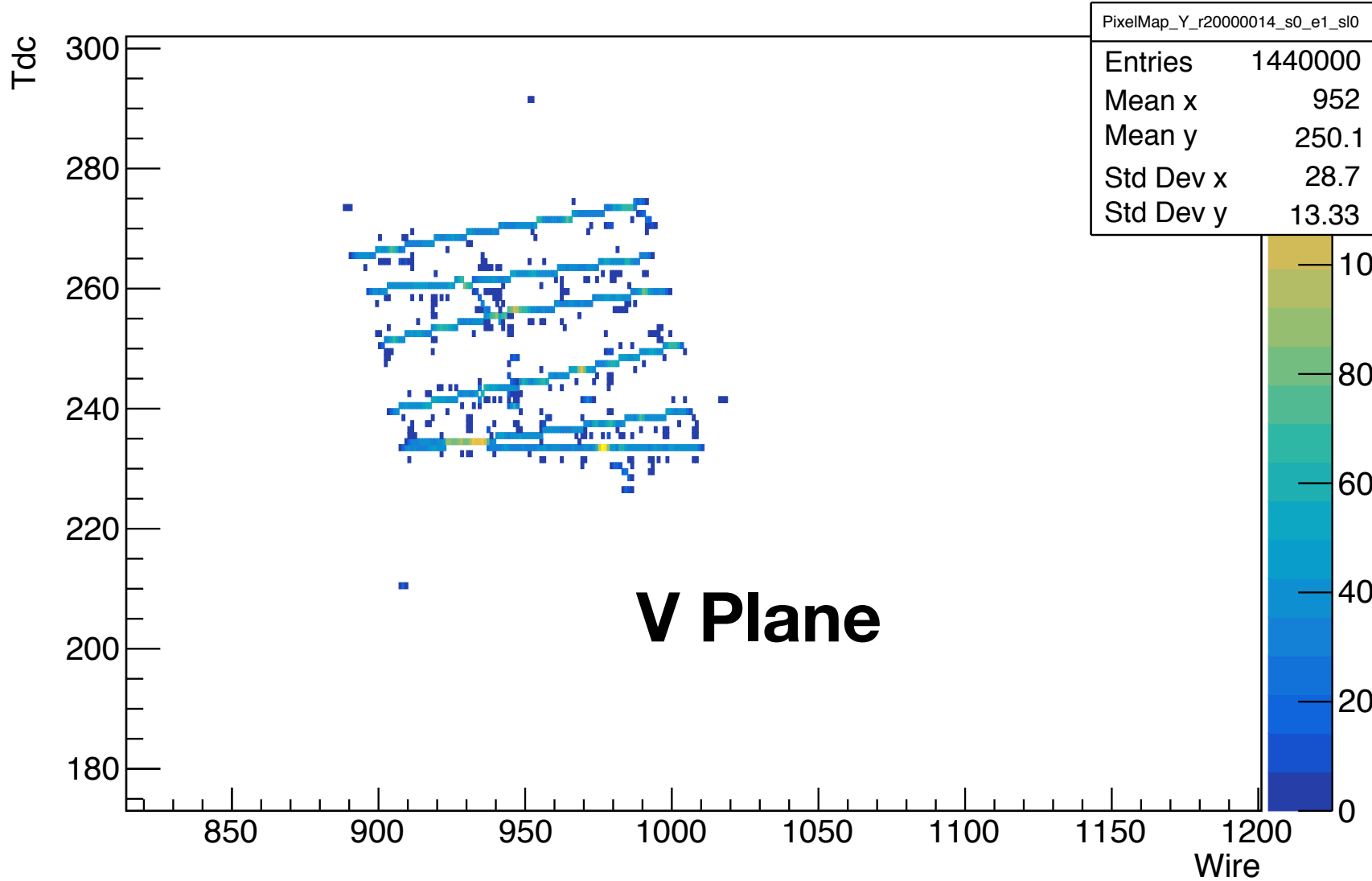
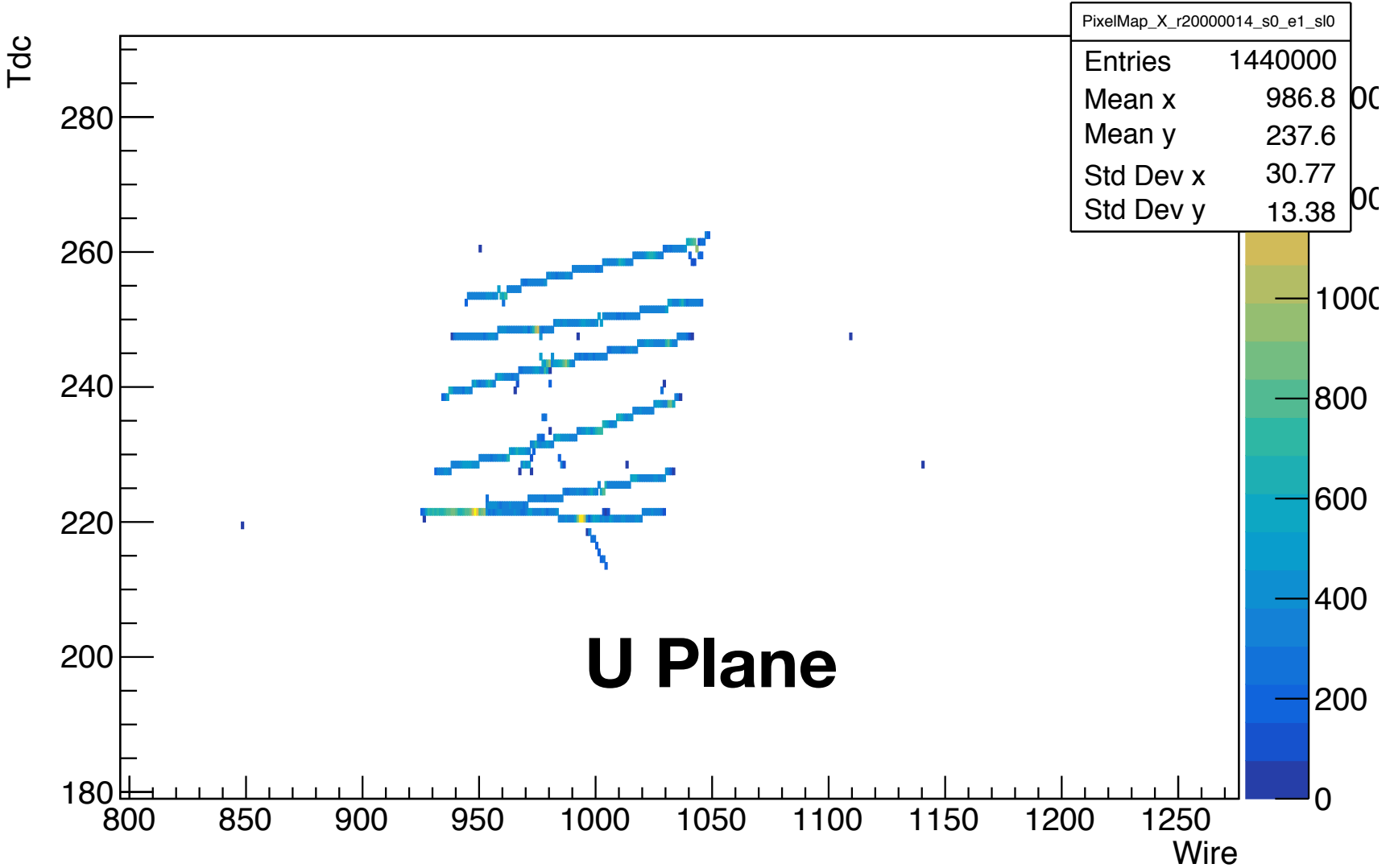
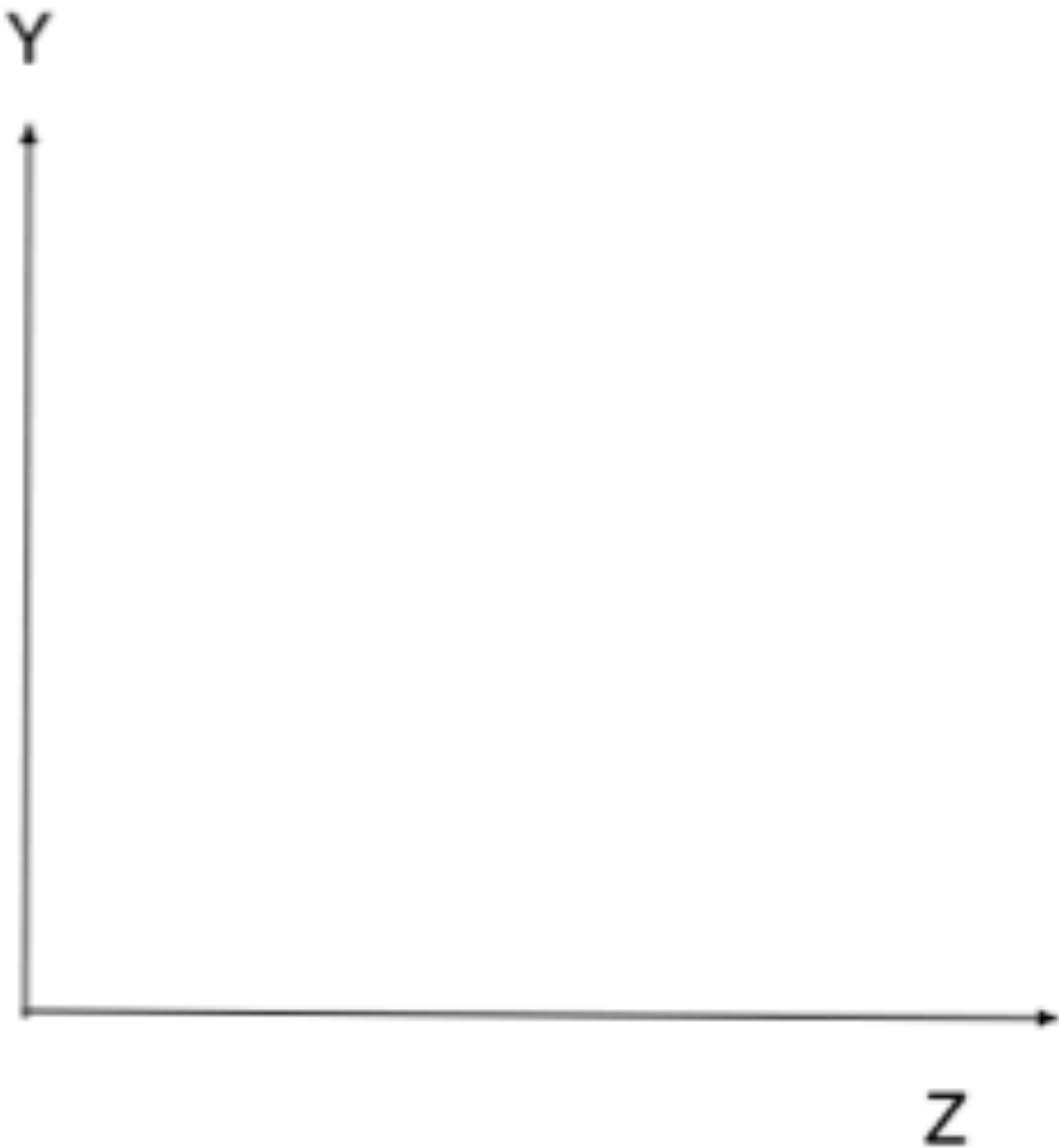
- PixelMapProducer tries to handle events crossing APAs by assigning a global wireID and time tick to each hit based on its location in the geometry
 - A bit complicated for horizontal drift since multiple drift volumes
- For our case, since there's only 1, things are somewhat easier
 - Global TDC = local TDC
- However, instead of multiple drift volumes we have multiple CRMs, each with a local strip “wireID”
- Need a method to assign a global wireID here as well
- Collection plane is easy. It's just :
 - $\text{Global wireID} = \text{local wireID} + \text{CRM_column} * 304$
- Induction plane is a bit more complicated

Global Wire IDs

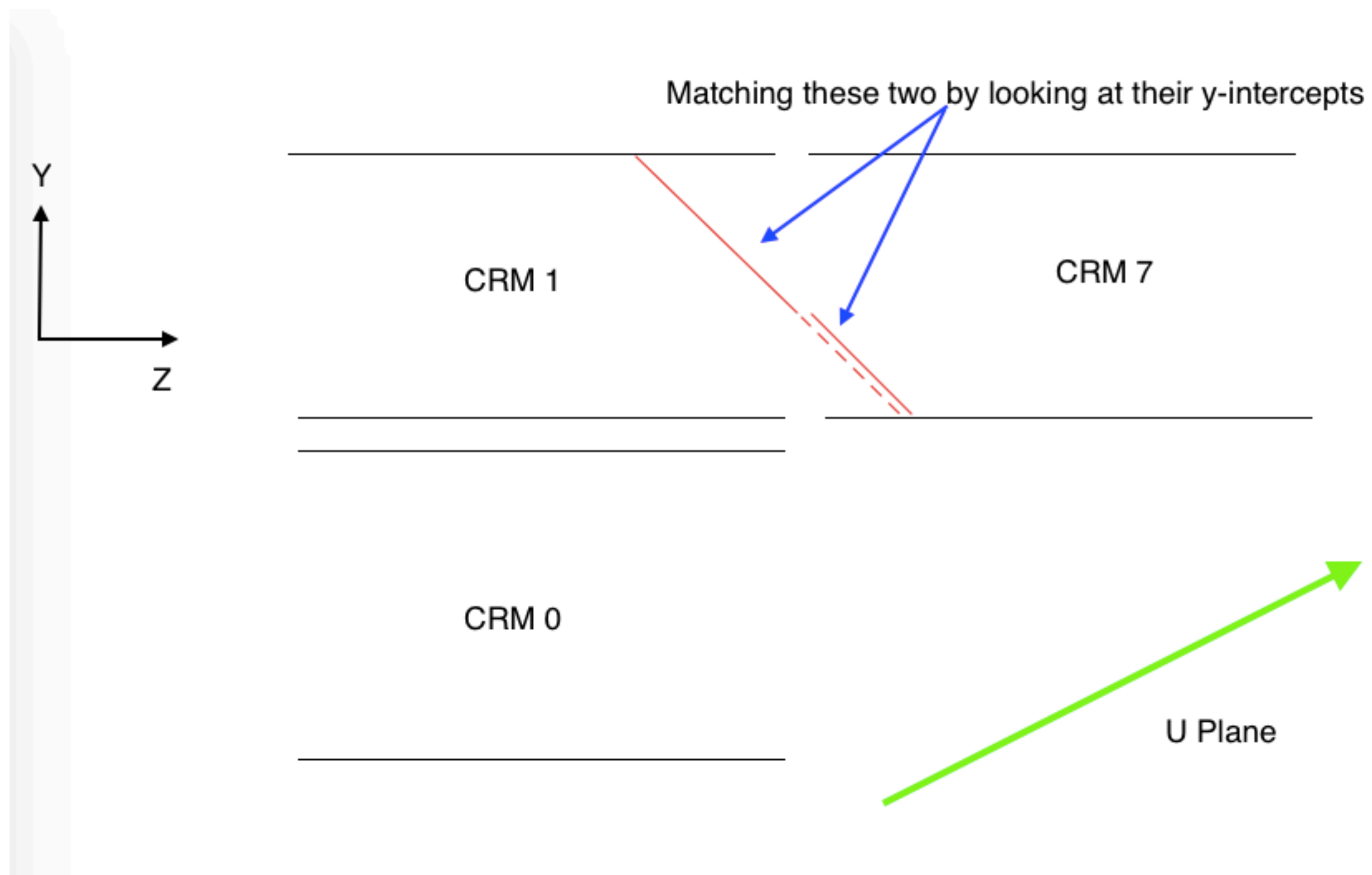


Parallel wires across CRMs have the same local WireID

- Can't do what is done for the collection plane.. otherwise you end up with pixel maps that look like these
- Have to be a bit smarter about matching wires across CRMs
 - Matching is not guaranteed/perfect in the design currently, but we can try to use some approximated version

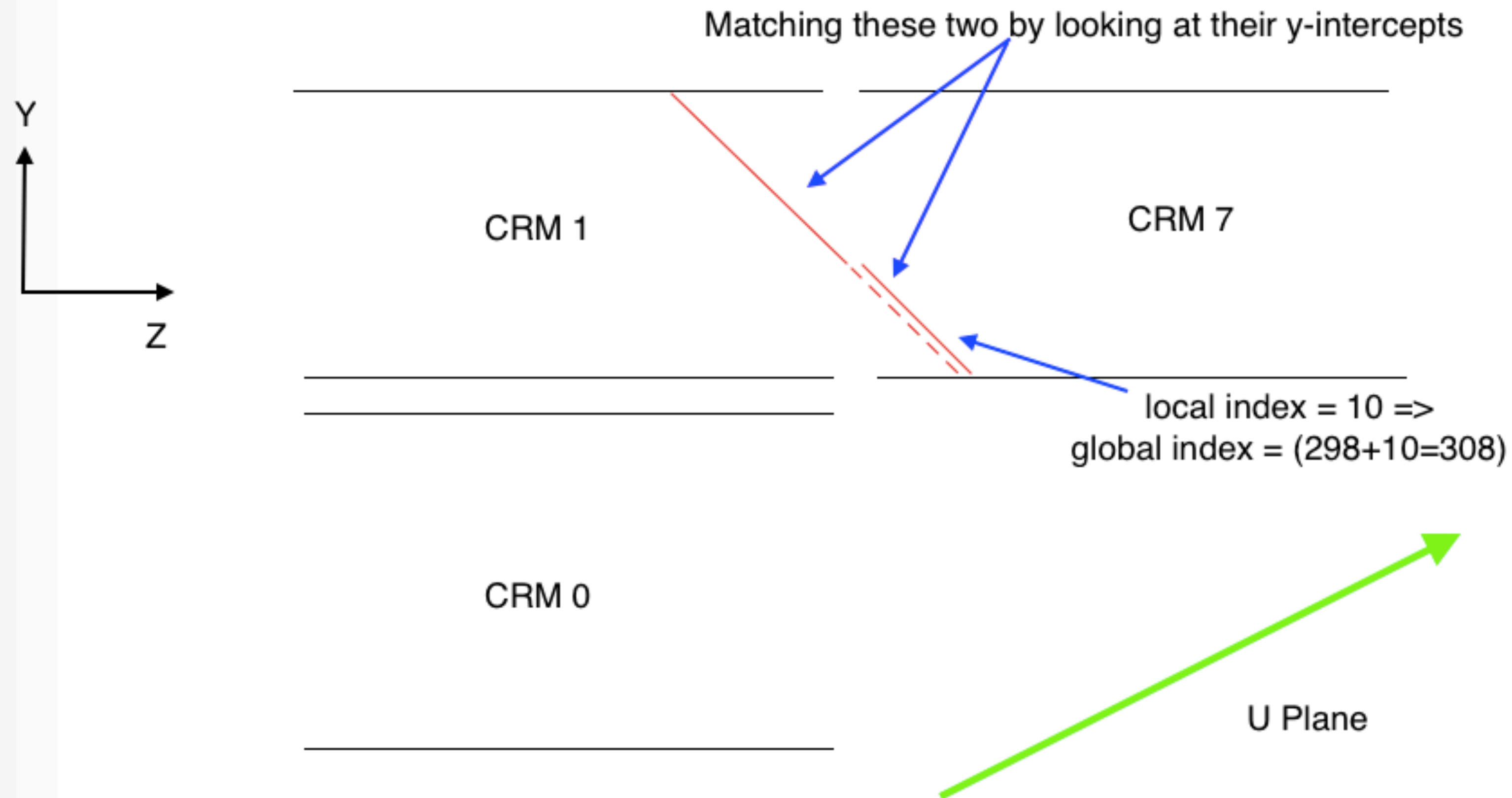


Global Wire IDs



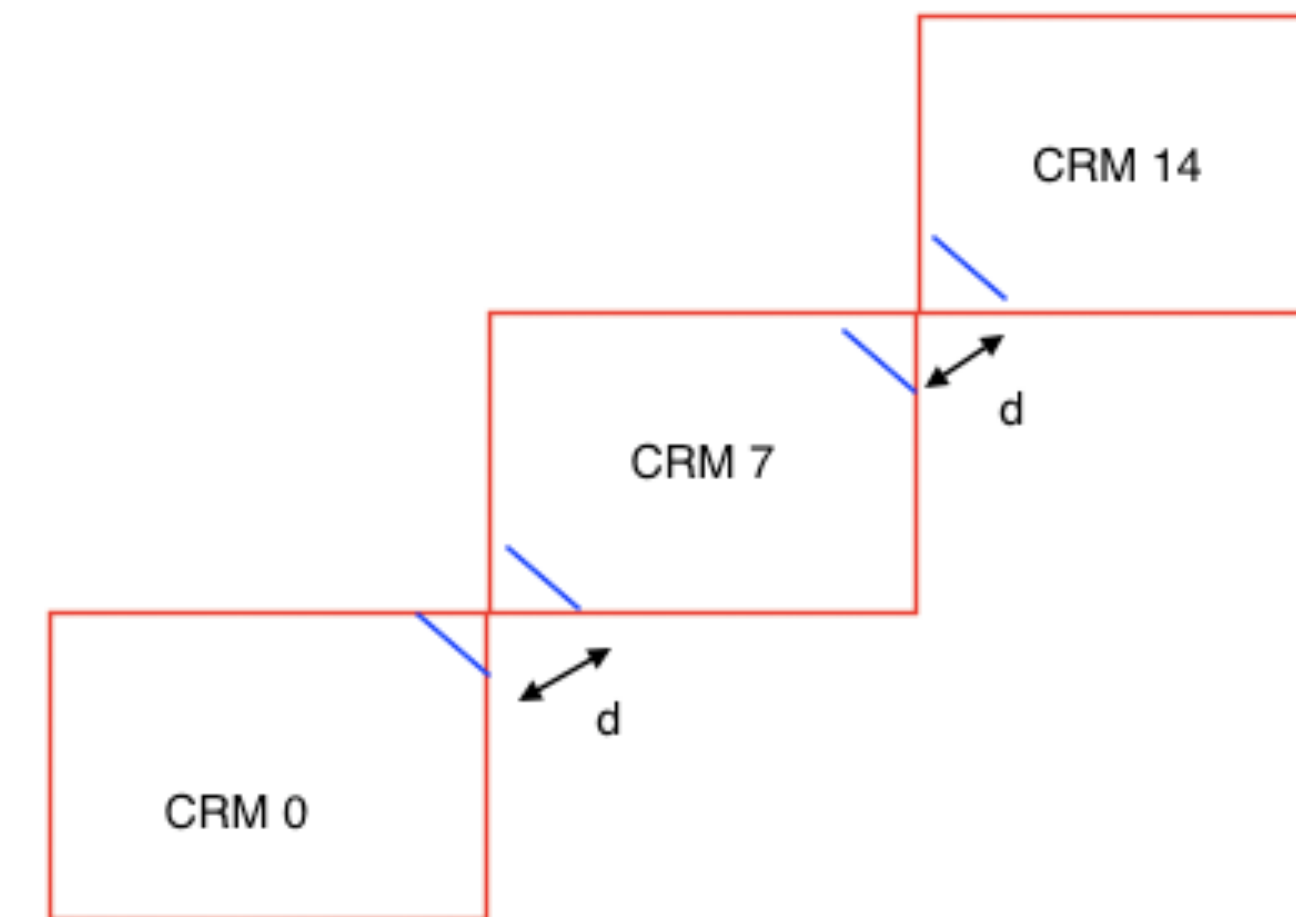
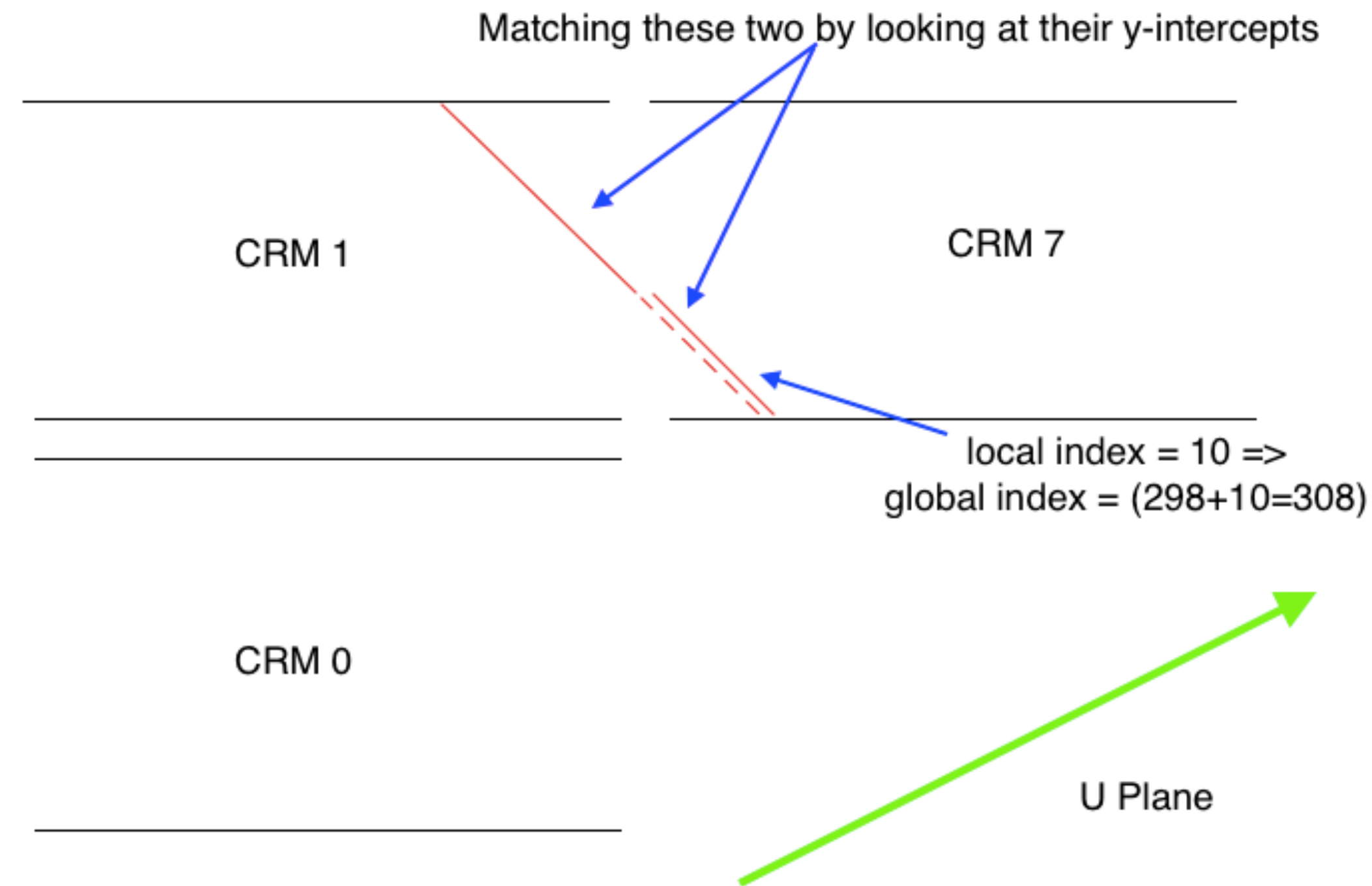
- illustration of how I'm matching wires across CRMs
- try to match every wire to a corresponding wire on a diagonal CRM
- matching done by looking at closest wire on diagonal CRM in terms of y-intercept
- $\text{intercept} = (y_0 \pm z_0/\sqrt{3})$

Global Wire IDs



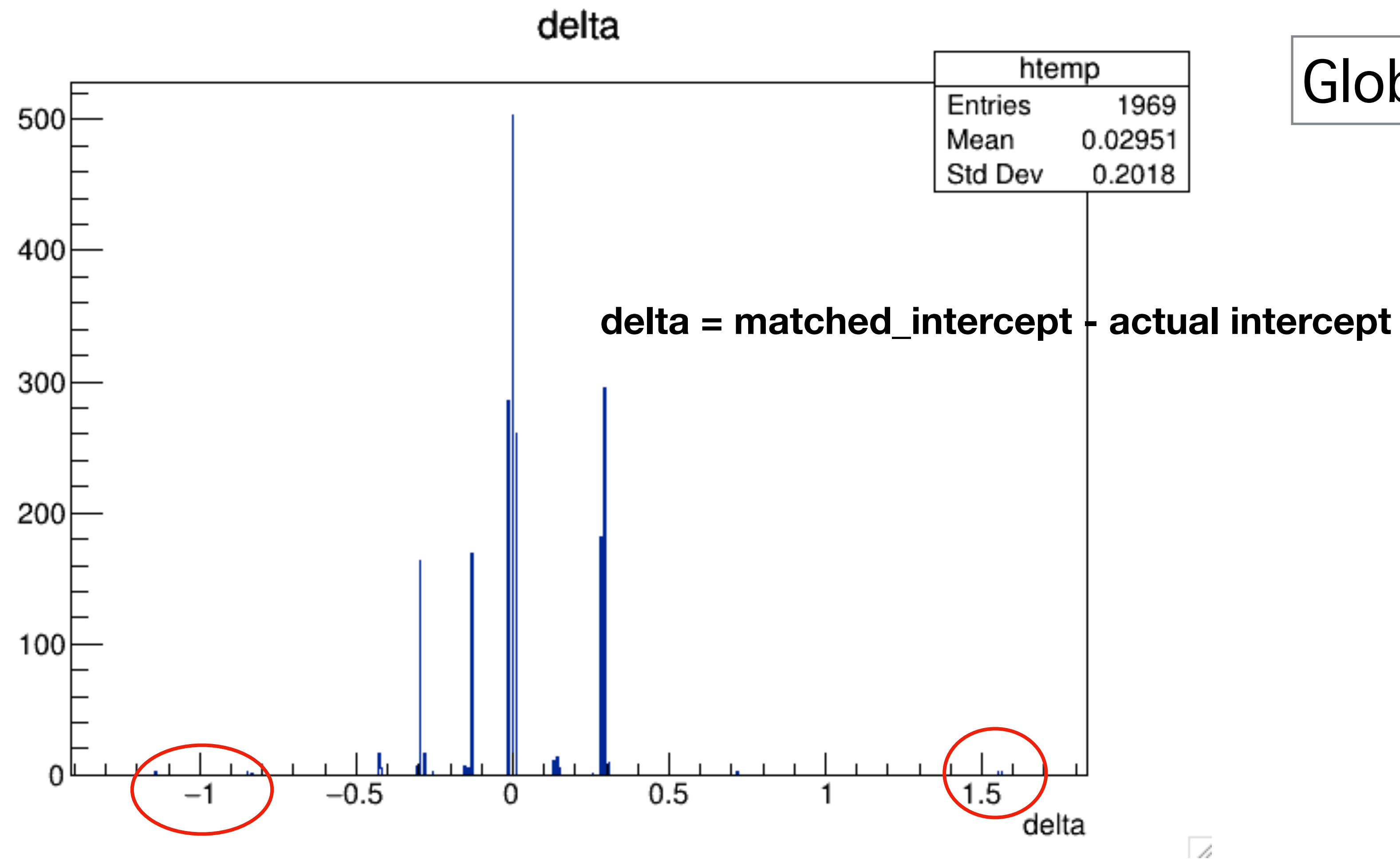
- get local index of matched wire on diagonal CRM by counting wires from the start of the CRM
- checked intercept spacing between neighbouring wires = 8.47 mm (from GDML). $8.47 = 7.335 / \cos(30\text{deg})$
- 7.335mm = wire pitch in this geometry based on the 50L design tested at CERN (These numbers are in flux a little bit, but for now it doesn't matter)
- Get global index of matched wire from local index

Global Wire IDs

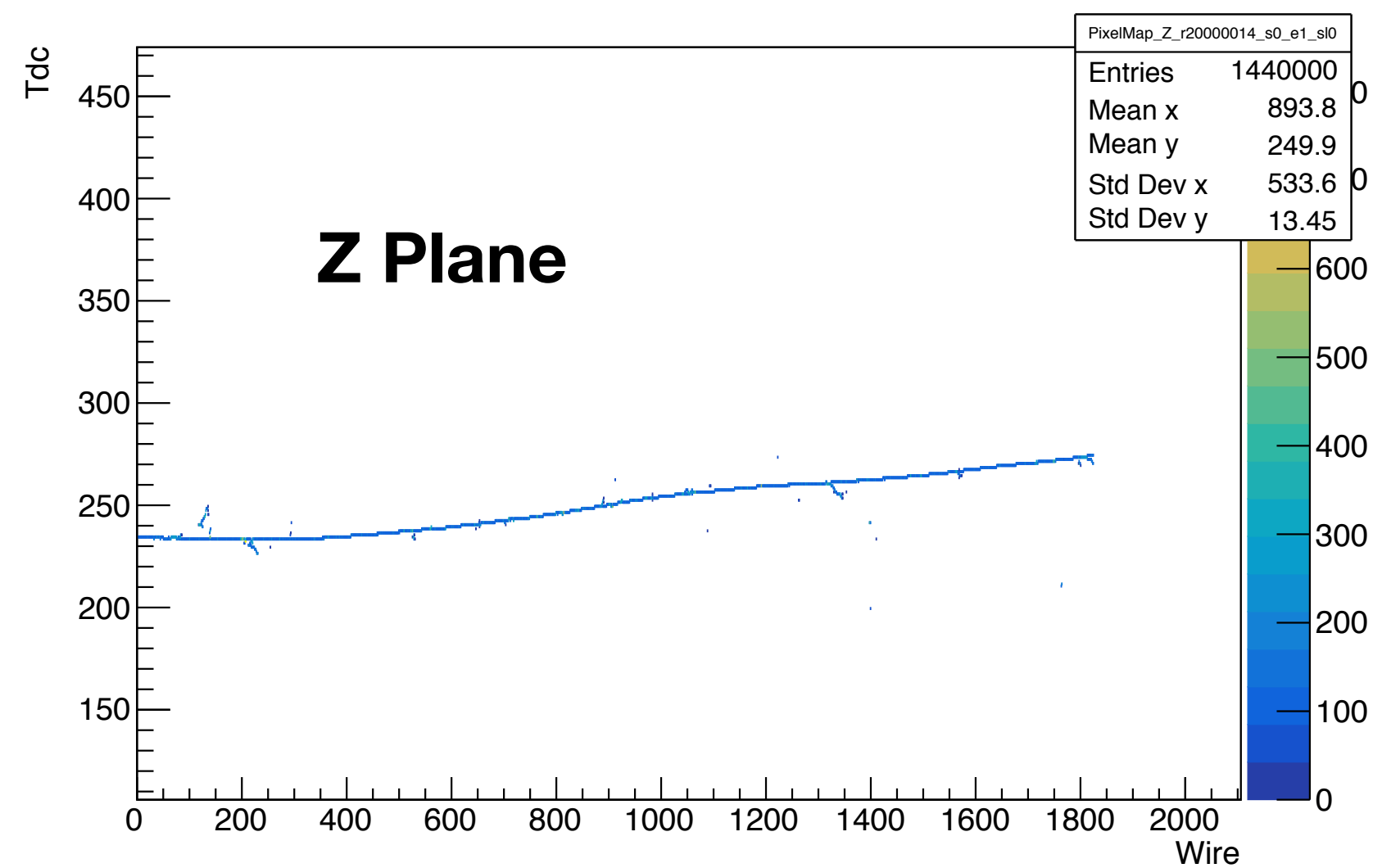
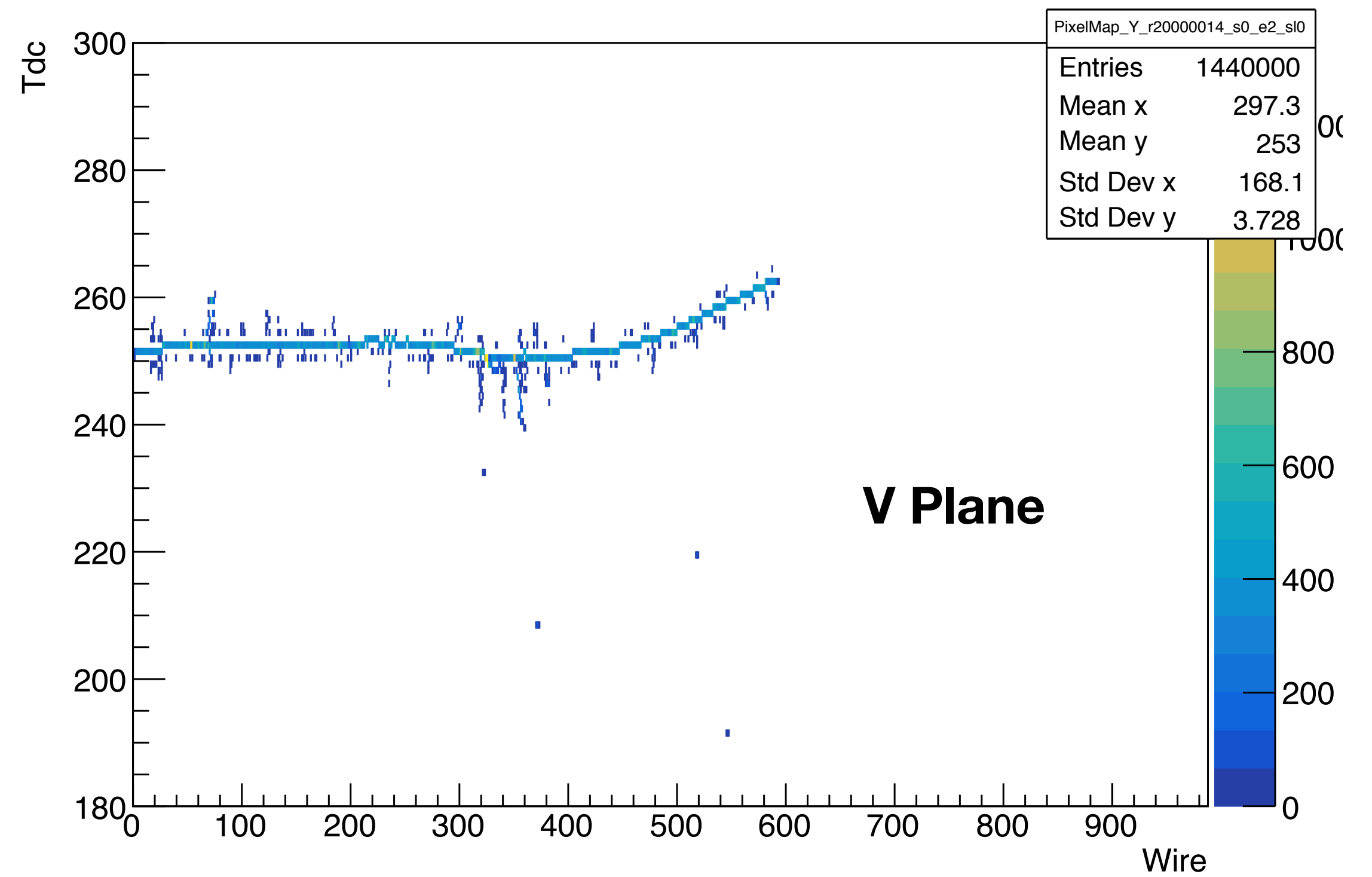
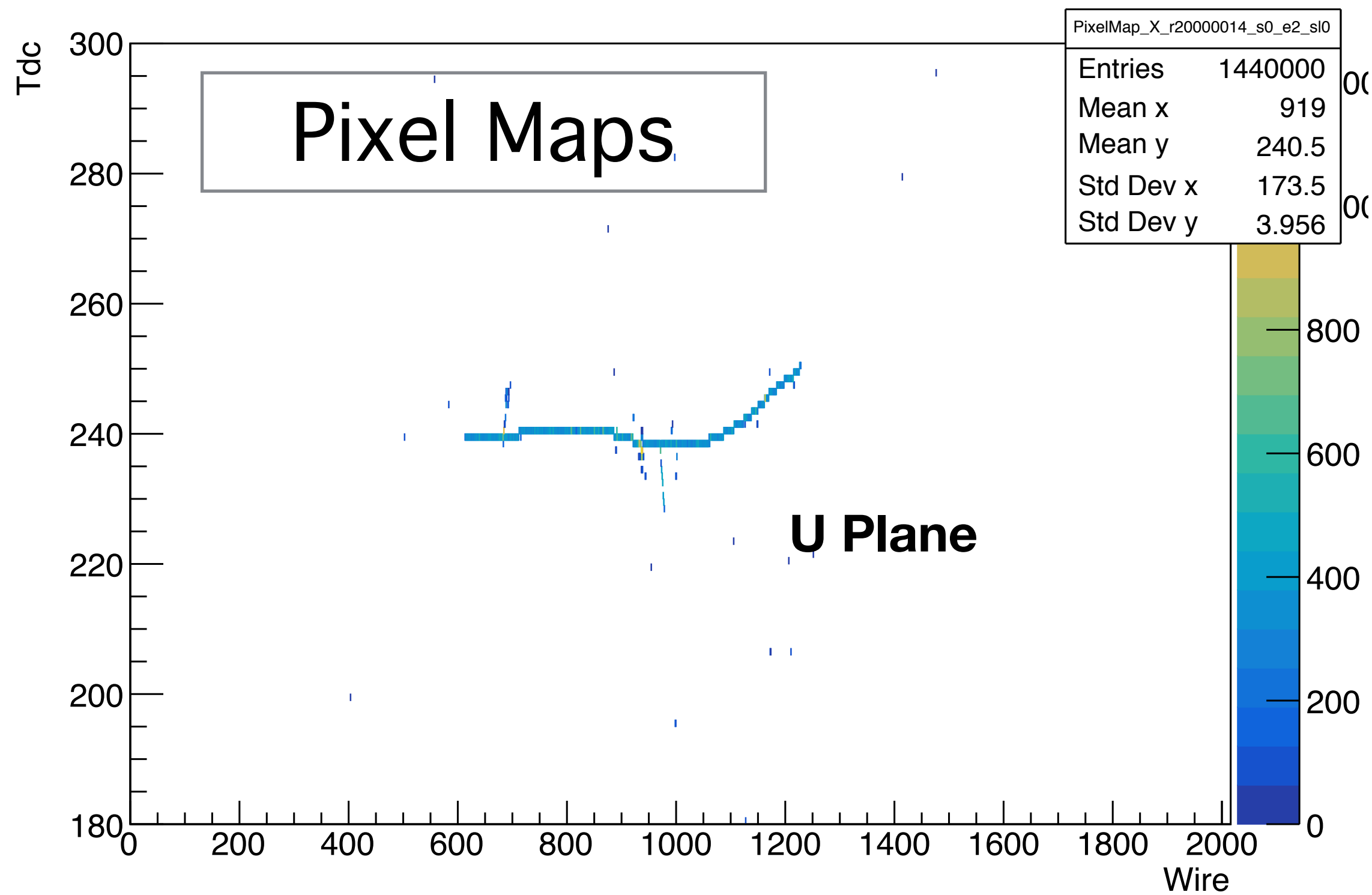


- For wires that project between two diagonal CRMs, I just assign it to the wire in one of the diagonal CRMs which it is closest to
- Distance between these end wires across the diagonal CRMs alternate between $d = 3.078\text{cm}$ and $d = 1.712\text{cm}$, so matching error is bounded by $d/2$

Global Wire IDs



- Most of the times, the matched wire intercept and the original intercept are the same
- The next frequent error is $< 0.847/2$ [\sim half a wire pitch]
- Rarely, error ~ 1.5 cm [twice the wire pitch] when wires project between diagonal CRMs
- Plans to make this more precise by maybe using variable binning pixel maps depending on where these wires project, rather than relying on a “matched” wire



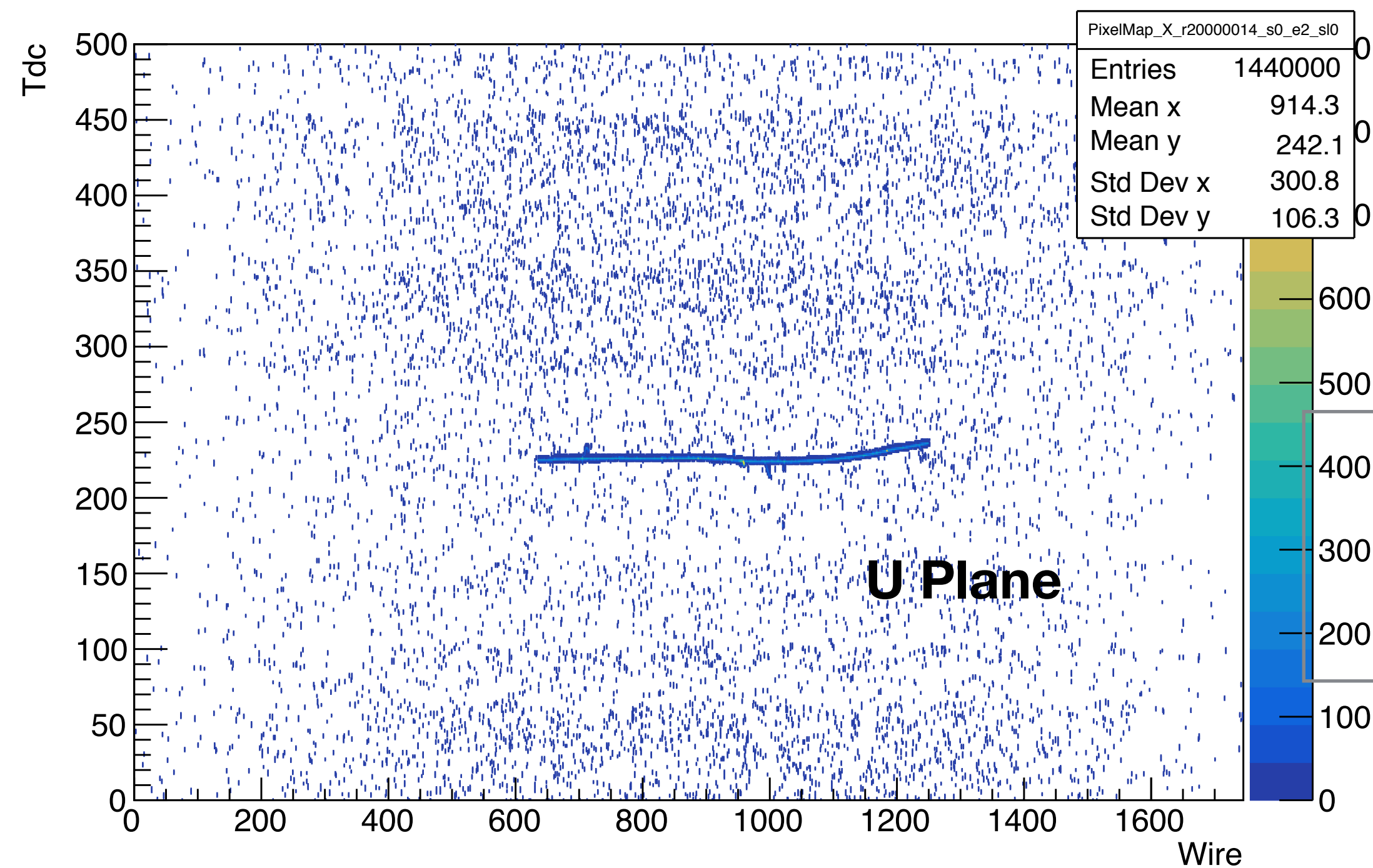
- New pixel maps look much more “reasonable”
- Caveats :
 - We see very prominent hairy features, especially in the V plane that doesn't look physical
 - Haven't studied performance of gaushit on the waveforms in a quantitative way for this design
 - In general, it seems more correct to use the waveforms directly in the pixel maps as inputs

Pixel Maps

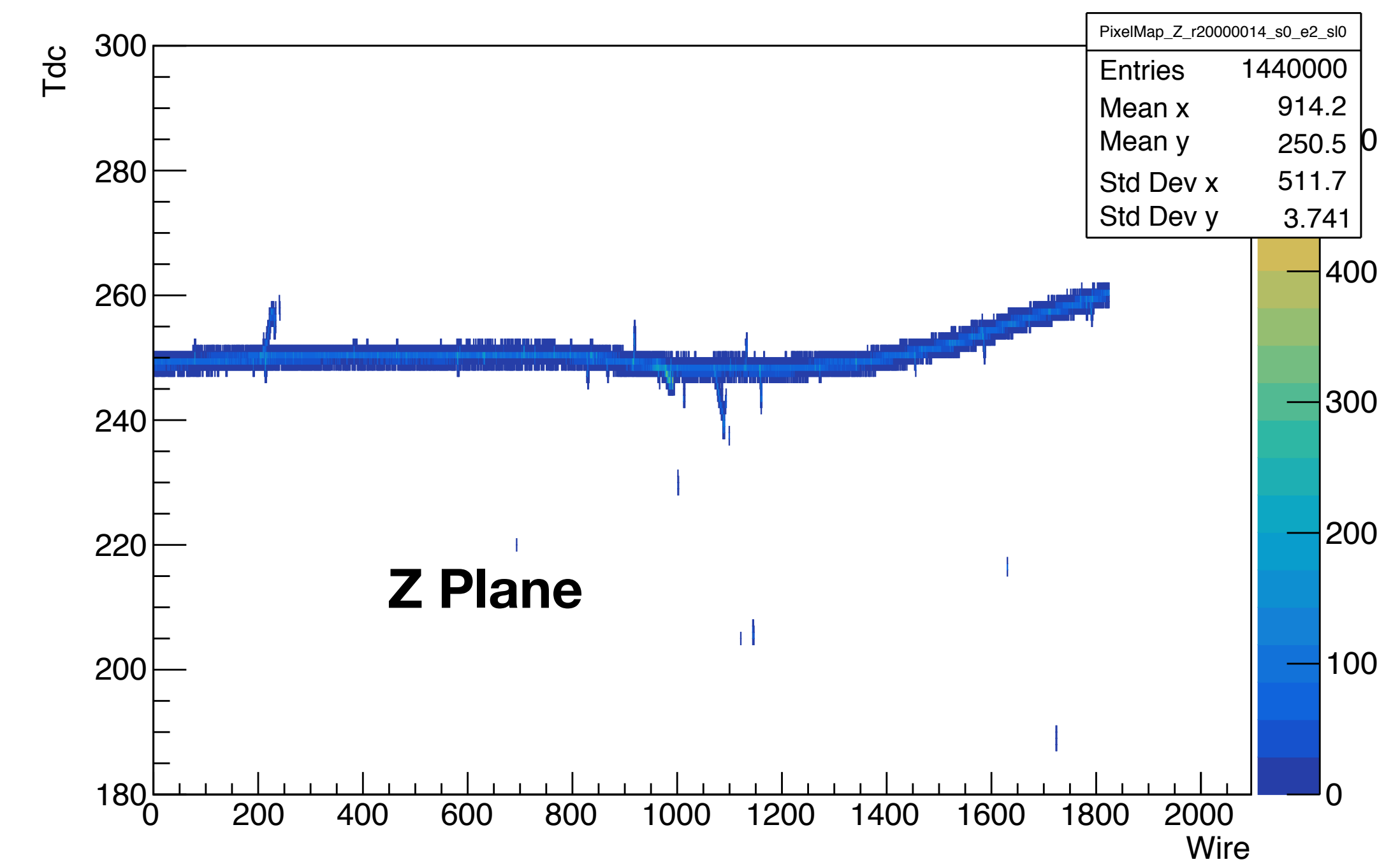
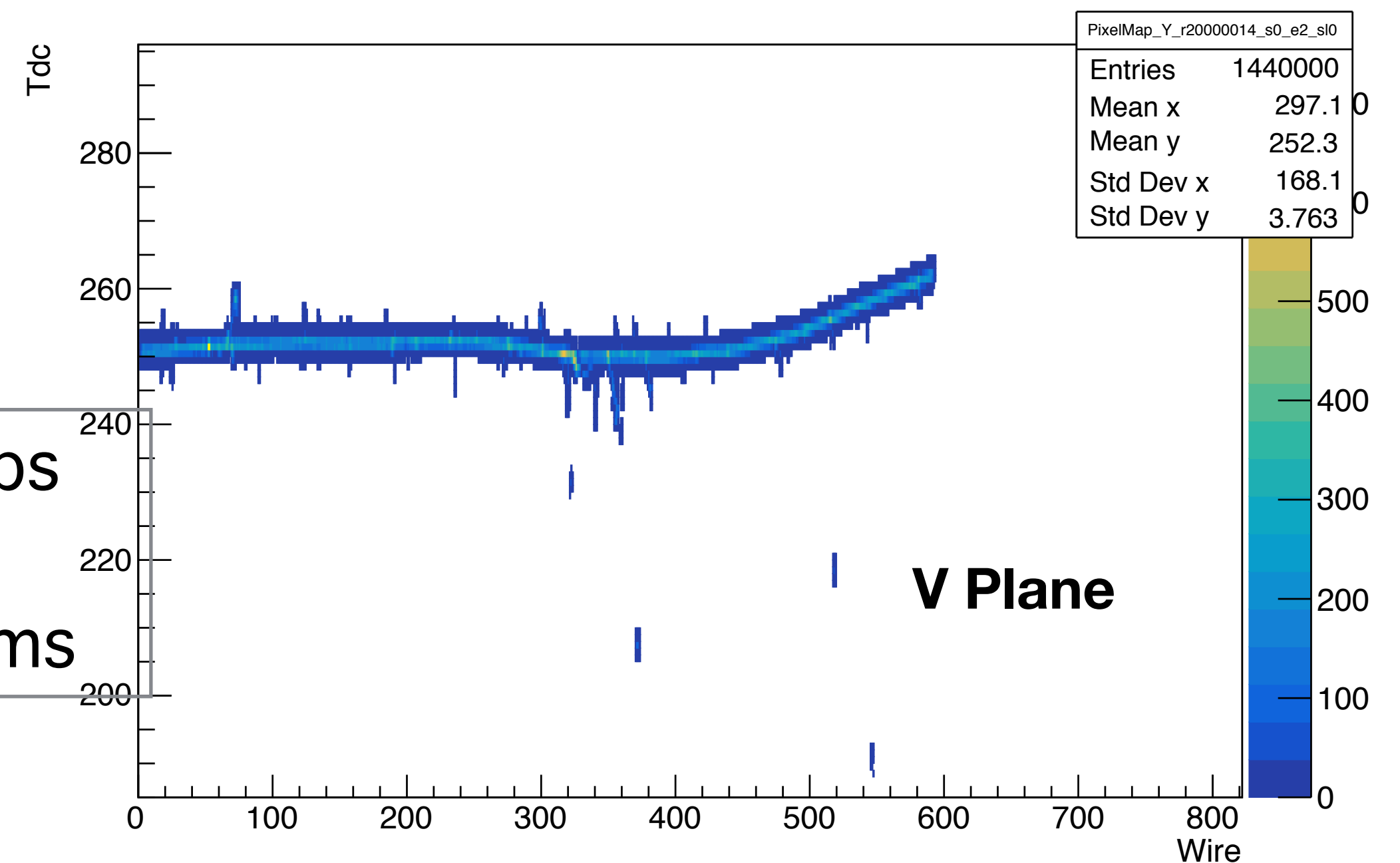
- Added infrastructure to make pixel maps using waveform inputs directly rather than using gaushits
 - New class : PixelMapWireProducer inside CVN that uses recob::Wire(s) instead of recob::Hits
 - Looping through wires, gathering the ROIs and filling the pixel map bins with the total charge content
 - This looping is not so expensive as it might seem since most recob::Wire(s) have no ROI content
 - Lives in feature/bnayak_cvnvd currently
- Keeping similar binning with what was done before for horizontal drift, but easy to change (=6 tdc ticks/bin)
- Goes through the wire-cell signal processing step : 2D deconv step + gaussian filter

```
38 standard_cvnmapper_wire:
39 {
40   module_type:          CVNMapperWire
41   #=====
42   HitsModuleLabel:      "wclsdatanfsp:gauss"
43   ClusterPMLabel:       "cvnmap"
44   MinClusterHits:       100
45   TdcWidth:             500
46   WireLength:           2880 #Unwrapped collection view max (6 x 480
47   TimeResolution:       1600
48   UnwrappedPixelMap:    1
49   Threshold:            0
50 }
```

- CVN/art/CVNMapper.fcl

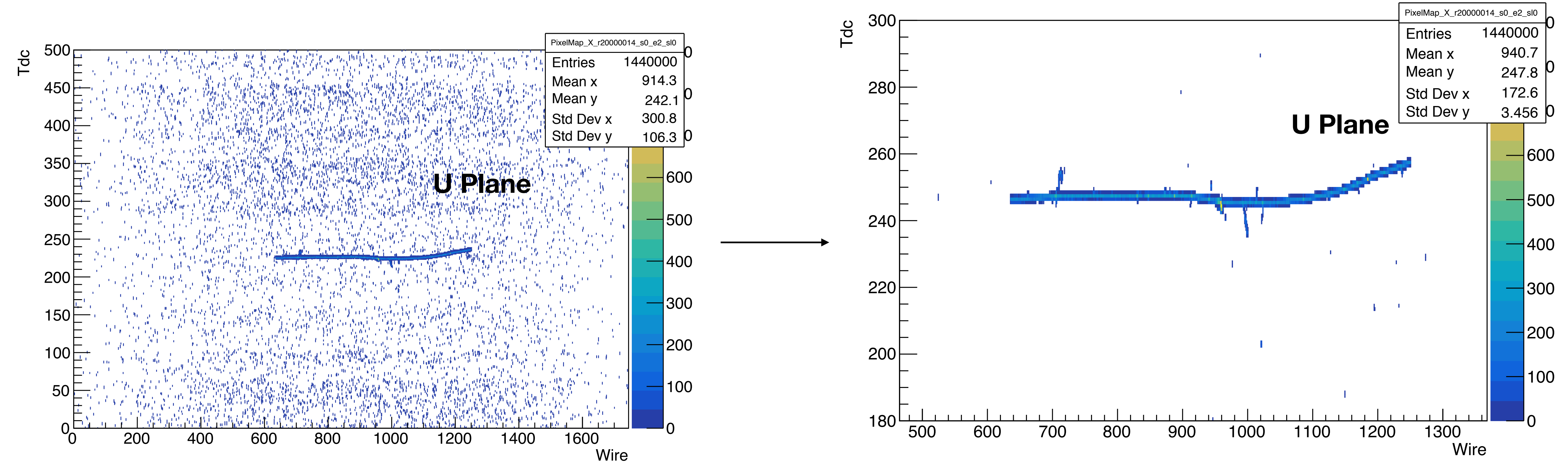


Pixel Maps
using
Waveforms

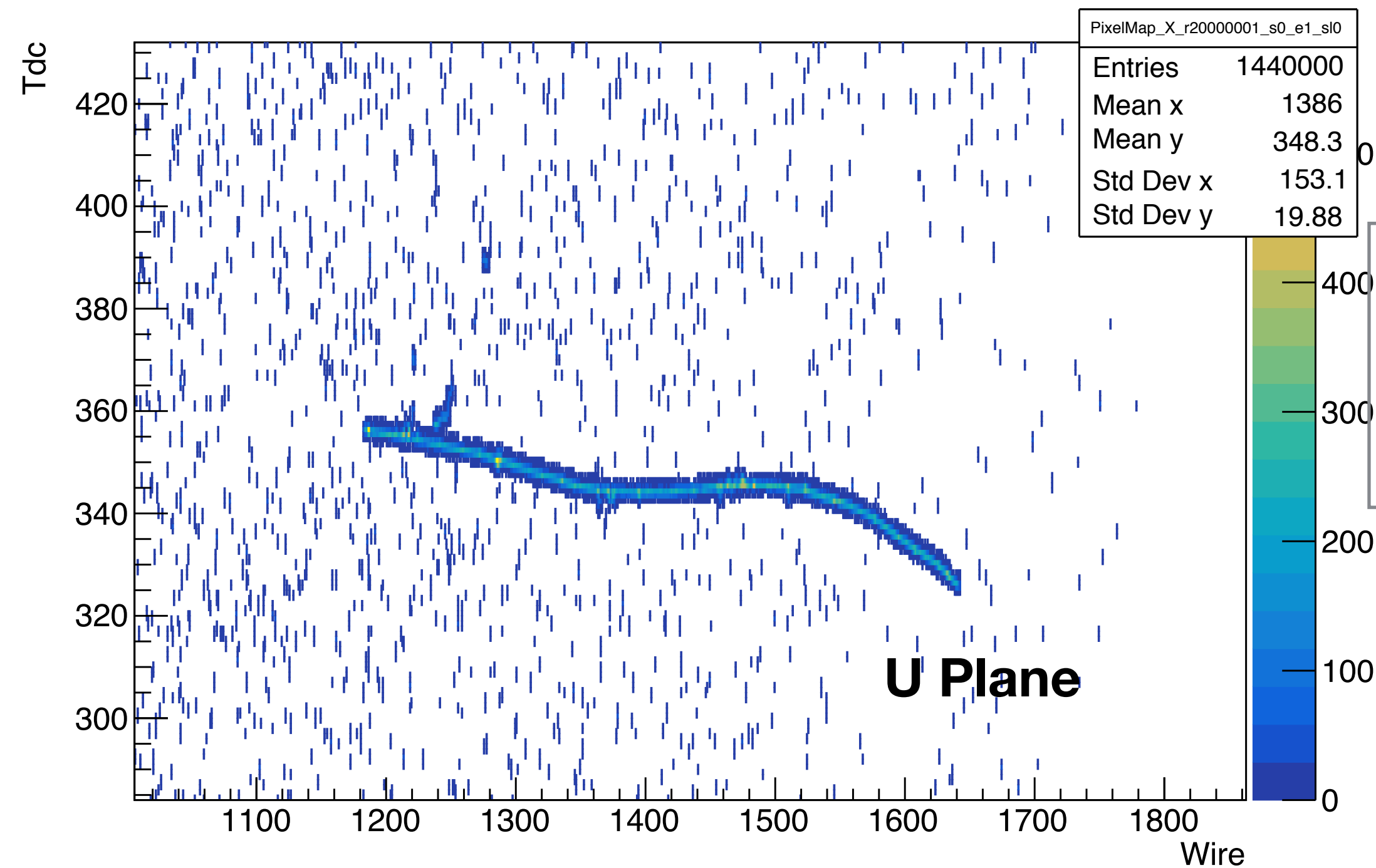


- Looks smoother than gaushit pixel maps
- U plane is very noisy, this is the same issue Slavic mentioned in FD sim/reco and we discussed last week → should be good with new config (with more appropriate electronic response parameters in sigproc chain)
- Hairiness (in V plane esp.) still exists but doesn't look as bad

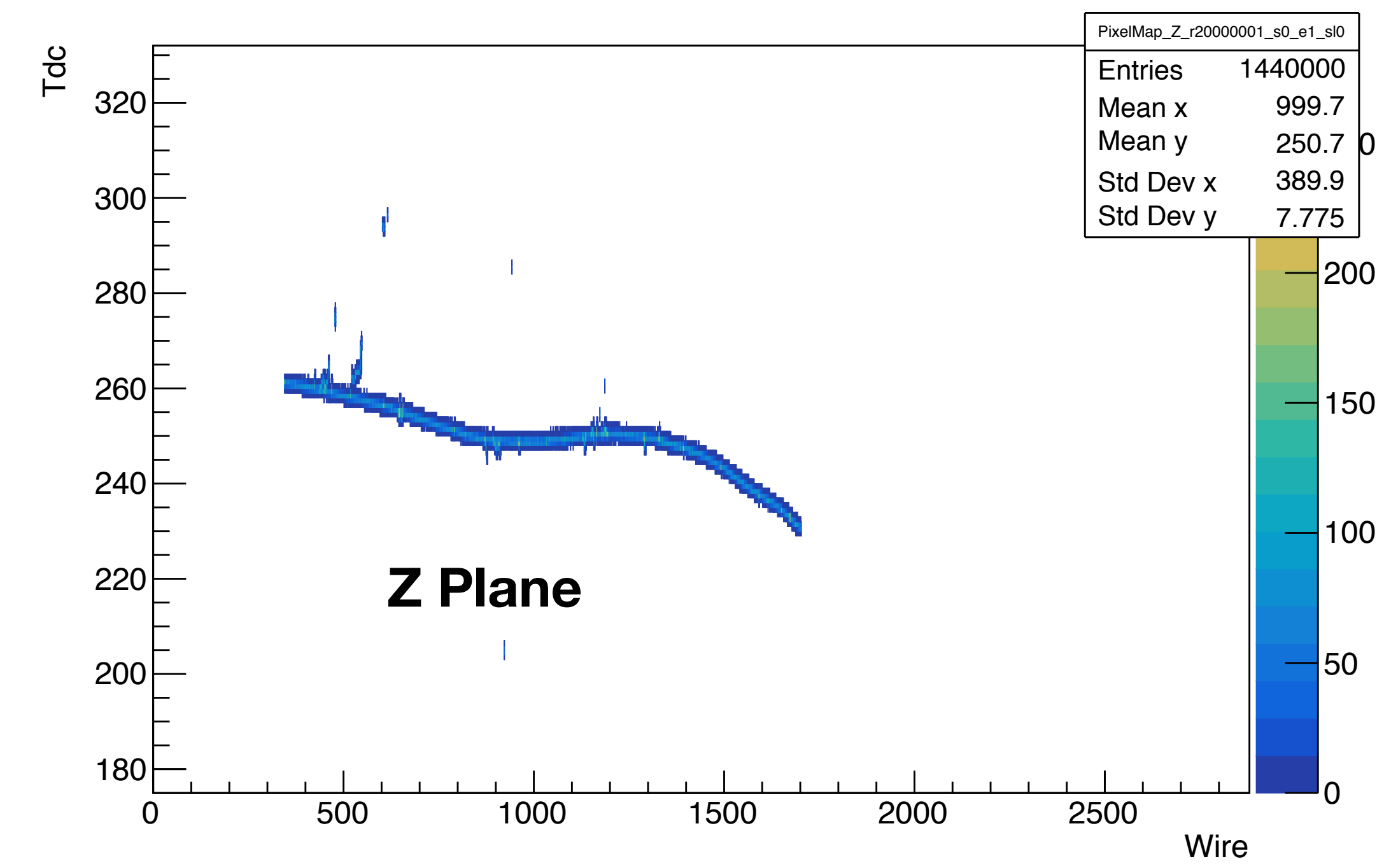
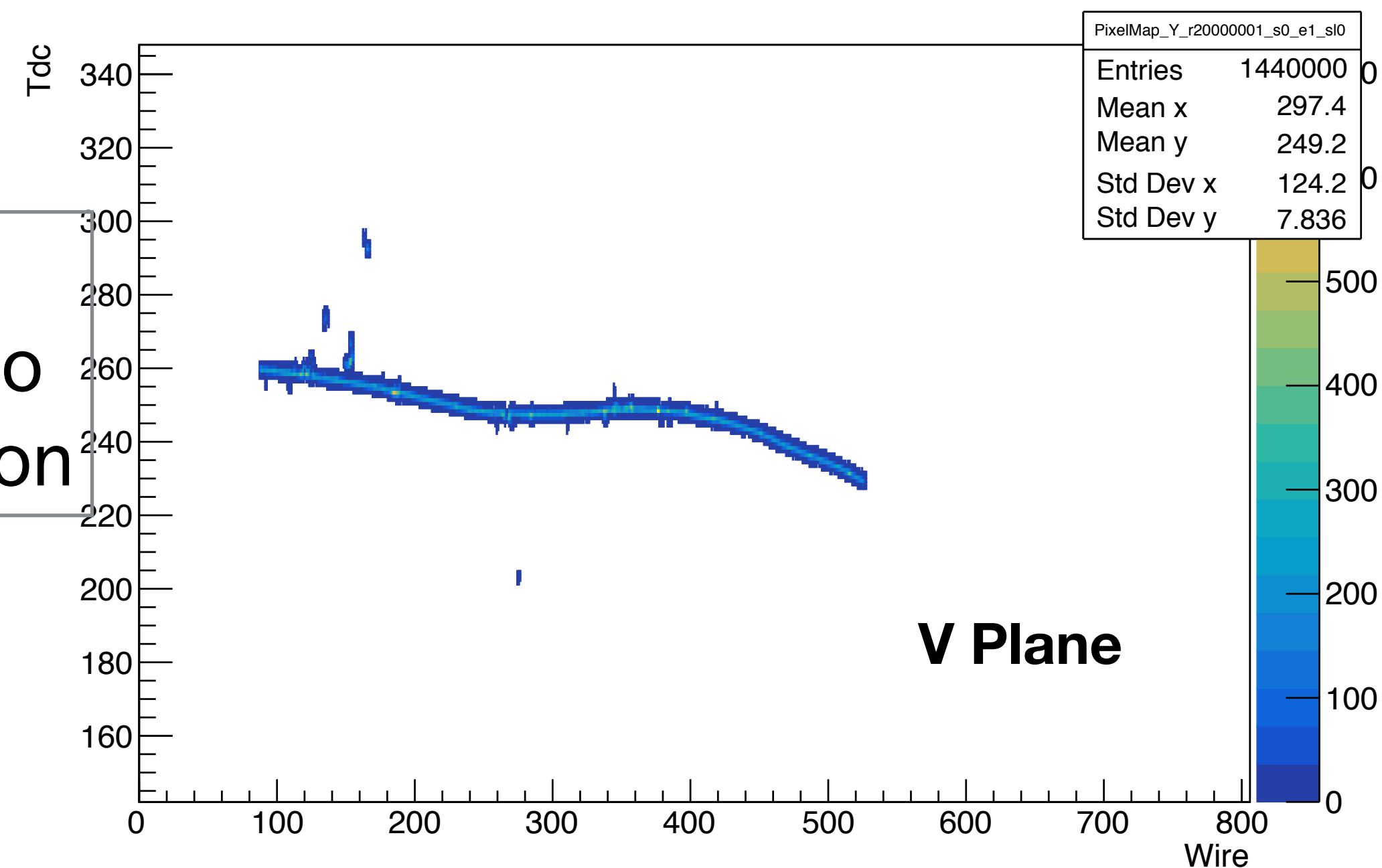
Pixel Maps using Waveforms



- Added a knob for a charge threshold in PixelMapWireProducer as well
- Need a threshold of 6 to get rid of all the noisy hits in the U plane with old config



Using
Neutrino
Simulation



- Dom mentioned on slack that the neutrino simulation using dk2nu flux files was up and running
- Tested the pixel maps here as well, seems to be working
- pixel maps stored as zlib-compressed outputs (.gz extension) with truth info stored in .info files as text output
- Once we generate a sizeable sample, can copy it to our workstations/cluster and train

Summary

- CVN would be very useful in testing the design choices currently for the VD
- Workflow seems to be in place for training CVN on VD geometries
 - both for waveform inputs and gaushit inputs
- Still a few things to clean up maybe :
 - Could do things more precisely with the stitching algorithm using matching strip intercepts
 - Probably some other intermediate steps/modifications to use CVN training scripts on these ``.gz`` and ``.info`` outputs
- Logistical questions :
 - Should we start to look at producing a larger training/testing sample on our own?
 - Something for production? Possible timeline/schedule etc?