POYNTING VECTOR ANALYSIS OF PHOTONIC CONVERSION OF THE DARK MATTER AXION MIXING WITH A BACKGROUND DC MAGNETIC FIELD

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High Energy Physics - Phenomenology

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Abraham and Minkowski Poynting vector controversy in axion modified electrodynamics

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The most sensitive haloscopes that search for axion dark matter through the two photon electromagnetic anomaly, convert axions into photons through the mixing of axions with a large DC magnetic field. In this work we apply Poynting theorem to the resulting axion modified electrodynamics and identify two possible Poynting vectors, one similar to the Abraham Poynting vector and the other to the Minkowski Poynting vector in electrodynamics. The latter picks up the extra non-conservative terms while the former does not. To understand the source of energy conversion and power flow in the detection systems, we apply the two Poynting theorems to axion modified electrodynamics, for both the resonant cavity and broadband low-mass axion detectors. We show that both Poynting theorems give the same sensitivity for a resonant cavity axion haloscope, but predict markedly different sensitivity for a low-mass broadband capacitive haloscope. Hence we ask the question, can understanding which one is the correct one for axion dark matter detection, be considered under the framework of the Abraham-Minkowski controversy? In reality, this should be confirmed by experiment when the axion is detected. However, many electrodynamic experiments have ruled in favour of the Minkowski Poynting vector when considering the canonical momentum in dielectric media. In light of this, we show that the axion modified Minkowski Poynting vector should indeed be taken seriously for sensitivity calculation for low-mass axion haloscope detectors in the quasi static limit, and predict orders of magnitude better sensitivity than the Abraham Poynting vector equivalent.

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 $\oiint (\vec{E} \times \vec{H}) \cdot d\vec{S}$ $-\int \int \int \sigma \left\Vert \vec{E} \right\Vert^2 dv$ $-\frac{1}{2}$ \mathbf{J}^*_i $\sum_{i}^{*} \cdot \mathbf{E} d\mathbf{v}$ $\overline{2}$ \int_{V} $-\frac{1}{2}$ $M_i \cdot H^*dv$ $\overline{2}$, \int_{V} $rac{1}{2} \iiint \mu \left\| \vec{H} \right\|^2 dv$ $\frac{1}{2} \iiint \mathcal{E} \left\| \vec{E} \right\|^2 dv$

Search...

Help | Adva

- Axions convert into photons in presence of strong magnetic field
- Mass is unknown
-
- Three regimes of haloscope detector

• So: narrowband photon signal of an unknown frequency is generated (need to scan frequency)

DC Magnetic Haloscopes

∼ 300 *MHz* → 30 *GHz*

 $m_a \sim 1 \ \mu eV \rightarrow 100 \ \mu eV$

$$
\lambda_a = \frac{h}{m_a c}
$$
\n
$$
\lambda_a > d_{exp} \qquad \lambda_a \sim d_e
$$
\nNumber of the temperature, i.e., the number of the temperature, i.e., the number of the temperature, and the number of

DC Magnetic Haloscopes

REMEMBERING POYNTING THEOREM

Instantaneous Poynting vector in vacuum

$$
\overrightarrow{S}_1(t) = \frac{1}{\mu_0} \overrightarrow{E}_1(t) \times \overrightarrow{B}_1(t) = \frac{1}{2} \left(\mathbf{E}_1 e^{-j\omega_1 t} + \mathbf{E}_1^* e^{j\omega_1 t} \right) \times \frac{1}{2\mu_0} \left(\mathbf{B}_1 e^{-j\omega_1 t} + \mathbf{B}_1^* e^{j\omega_1 t} \right)
$$

$$
= \frac{1}{2\mu_0} \operatorname{Re} \left(\mathbf{E}_1 \times \mathbf{B}_1^* \right) + \frac{1}{2\mu_0} \operatorname{Re} \left(\mathbf{E}_1 \times \mathbf{B}_1 e^{-j2\omega_1 t} \right),
$$

$$
\langle \overrightarrow{S}_1 \rangle = \frac{1}{T} \int_0^T \overrightarrow{S}_1(t) dt = \frac{1}{T} \int_0^T \left[\frac{1}{2\mu_0} \operatorname{Re} \left(\mathbf{E}_1 \times \mathbf{B}_1^* \right) + \frac{1}{2\mu_0} \operatorname{Re} \left(\mathbf{E}_1 \times \mathbf{B}_1 e^{-2j\omega t} \right) \right] dt = \frac{1}{2\mu_0} \operatorname{Re} \left(\mathbf{E}_1 \times \mathbf{B}_1^* \right)
$$

$$
\mathbf{S}_{1} = \frac{1}{2\mu_{0}} \mathbf{E}_{1} \times \mathbf{B}_{1}^{*} \text{ and } \mathbf{S}_{1}^{*} = \frac{1}{2\mu_{0}} \mathbf{E}_{1}^{*} \times \mathbf{B}_{1},
$$

Re $(\mathbf{S}_{1}) = \frac{1}{2} (\mathbf{S}_{1} + \mathbf{S}_{1}^{*})$ and $j \operatorname{Im} (\mathbf{S}_{1}) = \frac{1}{2} (\mathbf{S}_{1} - \mathbf{S}_{1}^{*}).$

Time Average Power Reactive Power

Complex Poynting vector in vacuum

• Describes complex power flow (phasors) in a volume, considering: 1) Sources, 2) Storage, 3) Dissipation, 4) Radiation • The direction and density of power flow at a point is defined by the instantaneous Poynting vector, $S(t)$ [W/m²] ⃗

> 1) Instantaneous Poynting Theorem 2) Complex Poynting Theorem

- Basic conservation law for electromagnetic energy for AC system
-
-

• The corresponding phasor form of the Poynting vector

Combing the Poynting vector with Maxwell's Equations -> Leads to Poynting Theorem

CONSIDERATION OF POYNTING VECTOR IN AXION ELECTRODYNAMICS: THE ABRAHAM-MINKOWSKI CONTROVERSY

- $*$ Poynting vector in Electrodynamics -> Over a century of Controversy, chose $\mathbf{S}_{\rm M}$ = $\frac{1}{\mathcal{S}}$ (D \times B) or $\mathbf{S}_{\rm A}$ = (E \times H) in matter ?
- Addresses the Abraham-Minkowski controversy, conclude: both valid depends on system.
- with the medium -> choosing the best Poynting vector depend on the medium and experimental set up.
-

DJ Griffiths, Resource Letter EM-1: Electromagnetic Momentum, Am. J. Phys. 80, 7 (2012) -> Abraham–Minkowski controversy regarding the field momentum in polarizable and magnetizable media: Correct one depends on the detailed nature of the material.

$$
p_{canonical} + \int g_M d^3 \mathbf{r}.
$$
\nNum in single-slit diffraction

\n

1 *ϵ*0*μ*⁰ $(\mathbf{D} \times \mathbf{B})$ or $\mathbf{S}_{\mathbf{A}} = (\mathbf{E} \times \mathbf{H})$

Pfeifer et. al., Momentum of an electromagnetic wave in dielectric media, Reviews of Modern Physics 79(4), 1197-1216 (2007). ->

Kinsler et al., Four Poynting theorems, Eur. J. Phys. 30 (2009) 983–993. Enables interpretation of four Poynting vectors and interaction

Measured by Jones et al, when media does not move

Four Poynting theorems

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The Poynting vector is an invaluable tool for analysing electromagnetic problems. However, even a rigorous stress-energy tensor approach can still leave us with the question: is it best defined as $\vec{E} \times \vec{H}$ or as $\vec{D} \times \vec{B}$. Typical electromagnetic treatments provide yet another perspective: they regard $\vec{E} \times \vec{B}$ as the appropriate definition, because \vec{E} and \vec{B} are taken to be the fundamental electromagnetic fields. The astute reader will even notice the fourth possible combination of fields: i.e. $\overrightarrow{D} \times \overrightarrow{H}$ Faced with this diverse selection, we have decided to treat each possible flux vector on its merits, deriving its associated energy continuity equation but applying minimal restrictions to the allowed host media. We then discuss each form, and how it represents the response of the medium. Finally, we derive a propagation equation for each flux vector using a directional fields approach; a useful result which enables further interpretation of each flux and its interaction with the medium.

Published in Eur. J. Phys. 30, 983 (2009).¹ This arXiv version has updates not present in the published version.

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II. MAXWELL'S EQUATIONS

Maxwell's equations for the electric field \vec{E} and magnetic field \vec{B} in a medium are

$$
\nabla \cdot \vec{E} = \frac{1}{\varepsilon_0} \rho_b + \frac{1}{\varepsilon_0} \rho_f = \frac{1}{\varepsilon_0} \rho \tag{1}
$$

$$
\nabla \cdot \vec{B} = 0 \tag{2}
$$

$$
\nabla \times \vec{E} = -\partial_t \vec{B} \tag{3}
$$

$$
\nabla \times \vec{B} = \mu_0 \vec{J}_b + \mu_0 \vec{J}_f + \mu_0 \varepsilon_0 \partial_t \vec{E}, \tag{4}
$$

where (ρ_b, \vec{J}_b) and (ρ_f, \vec{J}_f) are respectively the bound and free (charge, current) densities. As an alternative, we can define an electric polarization P and magnetization M , and

$$
\overrightarrow{J}_b = \overrightarrow{J}_P + \overrightarrow{J}_M = \partial_t \overrightarrow{P} + \nabla \times \overrightarrow{M}
$$
 (5)

$$
\rho_b = -V \cdot P \tag{6}
$$

$$
D = \varepsilon_0 E + P \tag{7}
$$

$$
\vec{H} = \frac{1}{\mu_0} \vec{B} - \vec{M}.
$$
 (8)

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These allow us to rewrite Maxwell's equations as

$$
\nabla \cdot \vec{D} = \rho_f
$$
\n
$$
\nabla \cdot \vec{B} = 0
$$
\n(9)

$$
\nabla \times \vec{E} = -\mu_0 \partial_t \left(\vec{H} + \vec{M} \right)
$$
 (11)

$$
\nabla \times \vec{H} = \vec{J}_f + \partial_t \vec{D} = \vec{J}_f + \partial_t \left(\varepsilon_0 \vec{E} + \vec{P} \right) \tag{12}
$$

We can even rewrite eqn. (11) in the unconventional form

$$
\nabla \times \vec{D} = -\varepsilon_0 \mu_0 \partial_t \left(\vec{H} + \vec{M} \right) + \nabla \times \vec{P}
$$
\n
$$
= -\varepsilon_0 \mu_0 \partial_t \vec{H} - \varepsilon_0 \mu_0 \vec{K}_b, \qquad (14)
$$

where we have defined

$$
\vec{K}_b = \vec{K}_P + \vec{K}_M = -\frac{1}{\epsilon_0 \mu_0} \nabla \times \vec{P} + \partial_t \vec{M}, \qquad (15)
$$
\n
$$
\sigma_b = -\nabla \cdot \vec{M}.
$$

This \vec{K}_b appears in the same place as a monopole current would if such were allowed; σ_b is the *bound* magnetic pole density. Note that \vec{K}_b and σ_b are merely a way of representing the (local) material response; we are not claiming that some process actually generates true magnetic monopoles inside the material $[14]²$. Strictly speaking, this is also true of the bound electric charge and its currents – they are a mechanism used solely to represent the behaviour of the medium.

Further, and just as for the ficticious bound electric charge density, the ficticious bound monopole density necessarily integrates to zero over all space. Thus the material response could, in principle, be re-represented as magnetic dipoles instead of monopoles.

GENERAL FORM OF MAXWELL'S EQUATIONS IN MATTER

Polarization can also be defined in free charge voltage source $\nabla \times P \neq 0$

 $\overrightarrow{P}_{b}^{i}=\epsilon_{0}\epsilon_{r}\overrightarrow{E}_{b}^{i}$

Bound Electric and/or Magnetic Current Models?

。
│

Engineers call impressed field Could label as Fictitious Electric field $\epsilon_0 \nabla \times E_i$

1) Modified Ampere's Law (mmf generator)

 $\nabla \times \vec{D} = -\epsilon_0 \mu_0 \partial_t (\vec{H} + \vec{M}) + \nabla \times \vec{P} = -\epsilon_0 \mu_0 \partial_t \vec{H} - \epsilon_0 \vec{J}_{mb}$ ⃗

$$
\nabla \times B = \mu_0(\overrightarrow{J}_f + \overrightarrow{J}_b) ; \quad \overrightarrow{J}_b = \overrightarrow{J}_p + \overrightarrow{J}_M = \partial_t \overrightarrow{P} + \nabla \times \overrightarrow{M}
$$

⃗

⃗

$$
Q_P = -\nabla \cdot \overrightarrow{P}
$$

Dielectric term

Polarization Current Permanent $\nabla \cdot \mathbf{J}_P = -\partial_t \rho_b$

Magnet term

⃗

Model as fictitious bound monopole currents or fictitious bound "Ampèrian" currents anent Electret term on-conservative, Metastable)

2) Modified Faraday's Law (emf generator)

$$
\overrightarrow{J}_{mb} = \overrightarrow{J}_{mM} + \overrightarrow{J}_{mP} = \mu_0 \partial_t \overrightarrow{M} - \frac{1}{\epsilon_0} \nabla \times \overrightarrow{P}
$$

\n
$$
\rho_M = -\mu_0 \nabla \cdot \overrightarrow{M} \qquad \qquad \rho_{\text{erman}}
$$

\n
$$
\nabla \cdot \overrightarrow{J}_{mM} = -\partial_t \rho_M
$$
 (No)

Magnetisation Magnetic Current

Electromotive force

From Wikipedia, the free encyclopedia

Not to be confused with Electromagnetic field.

In electromagnetism and electronics, electromotive force (emf, denoted $\mathcal E$ and measured in volts)^[1] is the electrical action produced by a non-electrical source.^[2] Devices (known as transducers) provide an emf^[3] by converting other forms of energy into electrical energy,^[3] such as batteries (which convert chemical energy) or generators (which convert mechanical energy).^[2] Sometimes an analogy to water pressure is used to describe electromotive force.^[4] (The word "force" in this case is not used to mean forces of interaction between bodies).

- EMF per unit length [V/m], is like a Fictitious Electric field
- Does not conform to Maxwell's equations
- Outside Maxwell's equations

Fictitious Force

-
-
-
-
-
-
-
-

Model of Current and Voltage Source (Impressed)

Figure 1.5 Electromagnetic representation of independent circuit sources. (a) Current generator (impressed electric current filament); (b) Voltage generator (impressed magnetic current loop).

- Engineering Systems are in general "non-conservative"
- Engineers keep Maxwell's equations general, with both fictitious magnetic and electric sources
- Magnetic monopoles do not exist, but magnetic dipoles do!
- Magnetic charge occurs in pairs, does not contradict no monopoles

NON CONSERVATIVE MAXWELL'S EQUATIONS

Lectures on **Electromagnetic Field Theory**

WENG CHO CHEW¹

FALL 2020, PURDUE UNIVERSITY

SECOND EDITION

ADVANCED ENGINEERING ELECTROMAGNETICS

Constantine A. Balanis

$$
\mathbf{J}_e = \mathbf{J}_{ei} + \mathbf{J}_{ec} = \mathbf{J}_{ei} + \sigma_e \mathbf{E}
$$

$$
\mathbf{J}_m = \mathbf{J}_{mi} + \mathbf{J}_{mf} = \mathbf{J}_{ei} + \sigma_m \mathbf{H}
$$

- Subscript *i ->* Impressed (or excitation Currents}
- Subscript c -> Loss term (conductivity)

 $+\sigma_m = B_0$ **Surface Magnetic Charge**

> $V = B_0 R \omega$ Fictitious electric field: External Lorentz force/unit charge **Converts mechanical motion to EM energy**

$$
\nabla \times \mathbf{H} = \mathbf{J}_{ei} + j\omega \epsilon_o \tilde{\epsilon}_r \mathbf{E}
$$

$$
\nabla \times \mathbf{E} = -\mathbf{J}_{mi} - j\omega \mu_o \tilde{\mu}_r \mathbf{H}
$$

$$
\vec{M} = M\hat{z}
$$

 $-\sigma_m = -B_0$

Spinning magnet of radius R

: magnetic pole *ρm* **distribution integrates to 0**

Phasor Form for AC Sources

ADVANCED ENGINEERING ELECTROMAGNETICS

Constantine A. Balanis

COMPLEX POYNTING THEOREM: CIRCUITS/ANTENNAS

$$
-\iiint_V \nabla \cdot (\frac{1}{2} \mathbf{E} \times \mathbf{H}^*) dv = -\iint_S (\frac{1}{2} \mathbf{E} \times \mathbf{H}^*) \cdot ds
$$

= $\frac{1}{2} \iiint_V (\mathbf{H}^* \cdot \mathbf{M}_i + \mathbf{E} \cdot \mathbf{J}_i^*) dv$
+ $\frac{1}{2} \iiint_V \sigma |\mathbf{E}|^2 dv + j2\omega \iiint_V (\frac{1}{4}\mu |\mathbf{H}|^2 - \frac{1}{4}\varepsilon |\mathbf{E}|^2) d$

or

$$
-\frac{1}{2}\iiint_V (\mathbf{H}^* \cdot \mathbf{M}_i + \mathbf{E} \cdot \mathbf{J}_i^*) dv = \oiint_S (\frac{1}{2}\mathbf{E} \times \mathbf{H}^*) \cdot ds + \frac{1}{2} \iiint_V \sigma |\mathbf{E}|^2 dv + j2\omega \iiint_V (\frac{1}{4}\mu |\mathbf{H}|^2 - \frac{1}{4}\varepsilon |\mathbf{E}|^2) dv
$$

which can be written as

$$
P_s = P_e + P_d + j2\omega(\overline{W}_m - \overline{W}_e)
$$

where

$$
P_s = -\frac{1}{2} \iiint_V (\mathbf{H}^* \cdot \mathbf{M}_i + \mathbf{E} \cdot \mathbf{J}_i^*) dv = \text{supplied complex power (W)}
$$

\n
$$
P_e = \oiint_S \left(\frac{1}{2} \mathbf{E} \times \mathbf{H}^* \right) \cdot ds = \text{existing complex power (W)}
$$

\n
$$
P_d = \frac{1}{2} \iiint_V \sigma |\mathbf{E}|^2 dv = \text{dissipated real power (W)}
$$

\n
$$
\overline{W}_m = \iiint_V \frac{1}{4} \mu |\mathbf{H}|^2 dv = \text{time-average magnetic energy (J)}
$$

\n
$$
\overline{W}_e = \iiint_V \frac{1}{4} \varepsilon |\mathbf{E}|^2 dv = \text{time-average electric energy (J)}
$$

Model of Current and Voltage Source (Impressed)

Figure 1.5 Electromagnetic representation of independent circuit sources. (a) Current generator (impressed electric current filament); (b) Voltage generator (impressed magnetic current loop).

Even though magnetic sources do not exist, they can be engineered

Here Balanis uses *M* **as magnetic current**

$$
\frac{1}{2}\oint_{S_c} (\mathbf{E} \times \mathbf{H}^*) \cdot d\mathbf{s} = \frac{1}{2}\int_V \left[j\omega \epsilon^* |\mathbf{E}|^2 + j\omega \mu |\mathbf{H}|^2 - \mathbf{J}_i^* \cdot \mathbf{E} - \mathbf{M}_i \cdot \mathbf{H}^* \right] dv
$$

$$
W_m = \frac{1}{4} \int_V \mu_o \mu_r |\mathbf{H}|^2 dv = \text{average magnetic ene}
$$

EX POYNTING THEOREM: CIRCUITS/ANT

$$
\mathbf{J}_i^* \cdot \mathbf{E} - j\omega \varepsilon^* \mathbf{E}^* \cdot \mathbf{E} = \mathbf{J}_i^* \cdot \mathbf{E} - j\omega \varepsilon^* |\mathbf{E}|^2
$$

- \mathbf{M}_i \cdot \mathbf{H}^* - j\omega \mu \mathbf{H} \cdot \mathbf{H}^* = - \mathbf{M}^i \cdot \mathbf{H}^* - j\omega \mu |\mathbf{H}|^2

$$
\nabla \cdot (\mathbf{E} \times \mathbf{H}^*) = \mathbf{H}^* \cdot \nabla \times \mathbf{E} - \mathbf{E} \cdot \nabla
$$

 $\nabla \cdot (\mathbf{E} \times \mathbf{H}^*) = j\omega \varepsilon^* |\mathbf{E}|^2 - j\omega \mu |\mathbf{H}|^2 - \mathbf{J}_i^* \cdot \mathbf{E} - \mathbf{M}_i \cdot \mathbf{H}^*$

Maxwell's Equations Phasor Form

Vector Identity

Integrate over volume, apply Divergence theorem

Real part is average power: Imaginary part is complex power

 $\frac{1}{2}$ Re \oint_{S_c} (**E** × **H**^{*}) · *d***s** = P_{ei} + P_{mi} – P_d P_d = $P_{ei} = -\frac{1}{2}$ $\overline{2}$, \int_{V} $\text{Re}\left(\mathbf{J}_i^*\cdot\mathbf{E}\right) d\textit{v} =$ average outgoing power due to the source \mathbf{J}_i^* $P_{mi} = -\frac{1}{2}$ ² [∫]*^V* $\operatorname{Re}\left(\mathbf{M}_i\cdot\mathbf{H}^*\right) d\nu = \text{ average outgoing power due to the source } \mathbf{M}_i$ 1 $\overline{2}$, \int_{V} σ $|\mathbf{E}|^2 dv =$ average power dissipated in *V*

complex power

 $(\mathbf{E} \times \mathbf{H}^*) \cdot d\mathbf{s} = 2\omega \left[W_e - W_m\right] - \frac{1}{2}$ \sum_{i} *Im* $\left[\mathbf{J}_{i}^{*} \cdot \mathbf{E} + \mathbf{M}_{i} \cdot \mathbf{H}^{*}\right]dv$

Here Balanis uses *M* **as magnetic current**

 $W_e =$ 1 ⁴ [∫]*^V* $\epsilon_o \epsilon_r |\mathbf{E}|^2 dv =$ average electric energy in *V* W_m

*TM*⁰³⁰

 TM_{020}

IMAGINARY POYNTING VECTOR INSIDE CAVITY

 $Re(E_1)$

 $Im(E_1)$

However **Dissipation** Gives real part of Poynting vector

 $\frac{1}{2}$

 $S = E \times H$

 TM_{010}

At resonance Poynting vector is REAL Small dissipation: Power builds up Enhanced power per cycle with large Q

EQUIVALENT CIRCUIT AND POYNTING VECTOR

$$
P_{in} = \frac{1}{2}VI^* = \frac{1}{2}II^* \left(R + \jmath\omega L + \frac{1}{\jmath\omega C} \right)
$$

$$
P_{in} = P_{loss} + 2\jmath\omega \left(U_m - U_e \right)
$$

$$
U_m = \frac{1}{4} L II^*
$$
 and l

- Reactive Power Oscillates between Electric and Magnetic field in the cavity as Stored Energy
- Source does not need to provide reactive power on resonance
- Steady state: Source power balanced by dissipative power in resonator
- High-Q, low-loss per cycle, power in resonator builds up (circulating power put into narrow frequency bandwidth)

Here Balanis uses *M* **as magnetic current**

$$
U_m = \frac{1}{4} \text{Re} \iiint \overline{H}^* \cdot \overline{B} \, dV \qquad U_e = \frac{1}{4} \text{Re} \iiint \overline{E} \cdot \overline{D}^* dV
$$

$$
U_e = \frac{1}{4}CVV^*
$$
\n
$$
P_{loss} = \frac{1}{2}RII^*
$$

PROPAGATING POYNTING VECTOR IS REAL

INDUCTOR OR CAPACITOR HAS AN IMAGINARY POYNTING VECTOR

Axion-Photon Coupling

- Axion is predicted to couple to photons, coupling parameter, $g_{a\gamma\gamma}$
- Two-photon transition, interaction Hamiltonian density $\mathscr{H} = \mathscr{H}_{EM} + \mathscr{H}_{a} + \mathscr{H}_{int}: \mathscr{H}_{int} = \varepsilon_0 c g_{\alpha\gamma\gamma} a \mathbf{E} \cdot \mathbf{B}$

 $\nabla \times B_1 = \mu_0 \epsilon_0 \partial_t E_1 + \mu_0 J_{el}$ ⃗ ⃗ $\nabla \times E_1 = - \partial_t B_1$ ⃗ ⃗ $\nabla \cdot B_1 = 0$ ⃗ $\nabla \cdot \overline{E}_1 = \epsilon_0^{-1} \rho_{e_1}$ ⃗

*γ*2

Two Photons

*γ*1

$$
\nabla \times \overrightarrow{B}_2 = \mu_0 \epsilon_0 \partial_t \overrightarrow{E}_2 + \mu_0 \overrightarrow{J}_{e2}
$$

\n
$$
\nabla \times \overrightarrow{E}_2 = - \partial_t \overrightarrow{B}_2
$$

\n
$$
\nabla \cdot \overrightarrow{B}_2 = 0
$$

\n
$$
\nabla \cdot \overrightarrow{E}_2 = \epsilon_0^{-1} \rho_{e_2}
$$

Axion Coupling to two Photonic Degree of Freedoms Modifies Electrodynamics

$$
a(t) = \frac{1}{2} \left(\tilde{a}e^{-j\omega_a t} + \tilde{a}^* e^{j\omega_a t} \right)
$$

$$
= \text{Re} \left(\tilde{a}e^{-j\omega_a t} \right)
$$

Klein–Gordon equation for massive spin 0 particle

- Axions convert into photons in presence of strong background electromagnetic field
- Axion Equation of Motion:

Haloscopes

$$
\nabla \cdot \vec{E} = \frac{\rho_e}{\epsilon_0} + c_8
$$

$$
\nabla \times \vec{B} - \frac{1}{c^2} \partial_t \vec{E}
$$

$$
\mu_0 \vec{J}_e - g_{a\gamma\gamma} \epsilon_0 c
$$

$$
\nabla \cdot \vec{B} = 0
$$

$$
\nabla \times \vec{E} + \partial_t \vec{B} = 0
$$

Modified Axion Electrodynamics

 $+ cg_{a\gamma\gamma}\overrightarrow{B} \cdot \nabla a$ = $e^{-t}g_{a\gamma\gamma}\epsilon_0c$ (*B* $\partial_t a + \nabla a \times E$ ⃗ $\left(\begin{array}{c} \end{array}\right)$ $\bf{0}$ $(Represents$ *two photons*) ⃗ $\epsilon_0 \nabla \cdot \vec{E}_1 = \rho_{e1} + \rho_{ab}$ 1 μ_0 $\nabla \times B_1 - \epsilon_0 \partial_t E_1 = J_{e1} + J_{ab} + J_{ae}$ ⃗ ⃗ $\rho_{ab} = g_{a\gamma\gamma} \epsilon_0 c \nabla \cdot (a(t) B_0(\vec{r}, t))$ ⃗ \overline{a} $\left| \right|$ $J_{ab} = -g_{a\gamma\gamma}\epsilon_0 c\partial_t \left(a(t) B_0(\vec{r}, t) \right)$ ⃗ $\ddot{}$ $\left| \right|$ $J_{ae} = -g_{a\gamma\gamma}\epsilon_0 c \nabla \times (a(t) E_0(\vec{r}, t))$ ⃗ ⃗ $\nabla \cdot J_{ab} = - \partial_t \rho_{ab}$ ⃗ 1) Background field (subscript zero) 2) Created Photon Field (subscript 1)

Source Terms generate Photons-> From background fields mixing with axion

d Field
$$
\nabla \cdot \vec{D}_1 = \rho_{e_1}
$$
 Construct **Relationship of Relations (Indulate Mat**
\n
$$
\nabla \times \vec{H}_1 - \partial_t \vec{D}_1 = \vec{J}_{e_1} \quad \vec{H}_1(\vec{r}, t) = \frac{\vec{B}_1}{\mu_0} - \vec{M}_1 - \vec{M}_a
$$
\n
$$
\nabla \cdot \vec{B}_1(\vec{r}, t) = 0 \qquad \vec{D}_1(\vec{r}, t) = \epsilon_0 \vec{E}_1 + \vec{P}_1 + \vec{P}_2
$$
\n
$$
\nabla \times \vec{E}_1(\vec{r}, t) + \partial_t \vec{B}_1(\vec{r}, t) = 0,
$$
\n
$$
\vec{M}_{a1} = -g_{a\gamma a}(t)cc_0 \vec{E}_0(\vec{r}, t)
$$
 and $\frac{1}{\epsilon_0} \vec{P}_{a1} = -g_{a\gamma a}(t)c \vec{B}_0(\vec{r}, t)$ \n
$$
\nabla \times \vec{D}_1(\vec{r}, t) = -\partial_t \vec{B}_1(\vec{r}, t) + \nabla \times (\vec{P}_1 + \vec{P}_{a1})
$$
\n
$$
\nabla \times \vec{P}_{a1} \neq 0 = -g_{a\gamma a}(t)c \nabla \times \vec{B}_0(\vec{r}, t) \quad (\nabla a = 0)
$$
\n**Proof**
\n
$$
(\vec{r}, t) = \frac{\partial \vec{P}_{a1}(\vec{r}, t)}{\partial t}
$$
\n
$$
(\vec{r}, t) = \frac{\partial \vec{P}_{a1}(\vec{r}, t)}{\partial t}
$$
\n
$$
\lambda_a = \frac{h}{m_a c}
$$
\n
$$
(\vec{r}, t) = \frac{h}{c_0}
$$
\n
$$
\vec{B}_0(\vec{r}, t) = c\mu_0 \vec{J}_{e_1}
$$
\n
$$
\mu_0 \vec{J}_{e_1} = \mu_0 \vec{J}_{e_1}
$$
\n
$$
\mu_0 \vec{J}_{e_1} = \mu_0 \vec{J}_{e_1}
$$
\n
$$
\mu_0 \vec{J}_{e_1} = \mu_0 \vec{J}_{e_1}
$$
\n
$$
\vec
$$

Poynting vector analysis of photonic conversion of the dark matter axion mixing with a background DC magnetic Field

• Two possible Poynting vectors, analogous to the Abraham Poynting vector and

- Apply Poynting theorem to axion modified electrodynamics
- Minkowski Poynting vector
- Minkowski picks up the extra non-conservative terms
- The non-conservative terms -> categorised as "curl forces" -> nonconservative and non-dissipative forces
-
-

• Fictitious Electric Field: Outside of the conservative Maxwell's Equations.

• Both give the same sensitivity for a resonant cavity axion haloscope, but predict markedly different sensitivity for low-mass broad band reactive haloscopes.

PRL 103, 108101 (2009)

PHYSICAL REVIEW LETTERS

week ending 4 SEPTEMBER 2009

Direct Measurement of the Nonconservative Force Field Generated by Optical Tweezers

Pinyu Wu,¹ Rongxin Huang,¹ Christian Tischer,² Alexandr Jonas,³ and Ernst-Ludwig Florin^{1,*}

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 ${\bf F} =$ curl conservative non-conservative conservative non-conservative

where the nonconservative force \mathbf{F}_{curl} satisfies

 $\nabla \times \mathbf{F} = \nabla \times \mathbf{F}_{\text{curl}} = \nabla (\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A} \neq 0.$

Classical and quantum complex Hamiltonian curl forces

M V Berry[®]

Ahetract

Non-conservative optical forces

KEY ISSUES REVIEW

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Quantized Hamiltonian Curl Forces and Squeezed Light

P. Strange

(Dated: July 3, 2018)

In this paper we discuss quantum curl forces. We present both the classical and quantum theory of linear curl forces. The quantum theory is shown to reproduce the classical theory precisely if appropriate combinations of eigenfunctions are chosen. A series of examples are used to illustrate the theory and to demonstrate its limitations. Furthermore we are able to point out an analogy between the quantum theory of curl forces and some of the squeezed light states of quantum optics.

IOP PUBLISHING

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FAST TRACK COMMUNICATION

Physical curl forces: dipole dynamics near optical vortices

Journal of Physics A: Mathematical and Theoretical

FAST TRACK COMMUNICATION

Physical curl forces: dipole dynamics near optical vortices

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Magnetic Vector Potential generates a Conservative Force -> Not a non-conservative Curl force

AXION ELECTRODYNAMICS IN HARMONIC PHASOR FORM

 $a(t) =$ $\frac{1}{2}$ $(\tilde{a}e^{-j\omega_a t} + \tilde{a}^*e^{j\omega_a t}) = \text{Re}(\tilde{a}e^{-j\omega_a t})$ Axion Scalar Field

Axion Phasor

 $\tilde{A} = \tilde{a}e^{-j\omega_a t}$ $\tilde{A}^* = \tilde{a}^*e^{j\omega_a t}$

 $\tilde{\mathbf{E}}_1(\vec{r}, t) = \mathbf{E}_1(\vec{r})e^{-j\omega_1 t}$ $\tilde{\mathbf{E}}_1^*(\vec{r}, t) = \mathbf{E}_1^*(\vec{r})e^{j\omega_1 t}$ $\ddot{}$ ⃗

Cavity Electric Field

 $E_1(\vec{r}, t) =$ ⃗ ⃗ 1 $\frac{1}{2}$ $(\mathbf{E}_1(\vec{r})e^{-j\omega_1 t} + \mathbf{E}_1^*(\vec{r})e^{j\omega_1 t}) = \text{Re} [\mathbf{E}_1(\mathbf{r})e^{-j\omega_1 t}]$

Cavity Electric Field Phasor

1 ϵ ⁰ $\nabla \times \tilde{\mathbf{D}}_{1}^{*}$ $J_{1}^{*} = -j\omega_{1}\tilde{B}_{1}^{*} - g_{a\gamma\gamma}c\mu_{0}\tilde{A}^{*}\overrightarrow{J}_{e0}$

1 *μ*0 $\nabla \times \tilde{\mathbf{B}}_1 = \tilde{\mathbf{J}}_{e1} - j\omega_1 \epsilon_0 \tilde{\mathbf{E}}_1 + j\omega_a g_{a\gamma\gamma} \epsilon_0 c \tilde{A} \overrightarrow{B}_0$ ⃗ 1 *μ*0 $\nabla \times \tilde{\mathbf{B}}_1^*$ 1 $= \tilde{J}_{e1}^* + j\omega_1 \epsilon_0 \tilde{E}_1^* - j\omega_a g_{a\gamma\gamma} \epsilon_0 c \tilde{A}^* \overrightarrow{B}_0,$ ⃗

Ampere's law in phasor form

$$
\nabla \times \tilde{\mathbf{E}}_1 = j\omega_1 \times \tilde{\mathbf{B}}_1
$$

$$
\nabla \times \tilde{\mathbf{E}}_1^* = -j\omega_1 \times \tilde{\mathbf{B}}_1^*,
$$

Faraday's law in phasor form (Abraham)

$$
\frac{1}{\mu_0} \nabla \times \overrightarrow{B}_1(\vec{r}, t) = \overrightarrow{J}_{e_1} + \partial_t \left(\epsilon_0 \overrightarrow{E}_1(\vec{r}, t) - g_{a\gamma\gamma} a(\vec{r}, t) \epsilon_0 c \overrightarrow{B}_0(\vec{r}, t) \right)
$$

Ampere's law in time dependent form

$$
\frac{1}{\epsilon_0} \nabla \times \tilde{\mathbf{D}}_1 = j\omega_1 \tilde{\mathbf{B}}_1 - g_{a\gamma\gamma} c \mu_0 \tilde{A} \overrightarrow{J}_{e0}
$$

Alternative Faraday's law in phasor form (Minkowski)

COMPLEX MINKOWSKI POYNTING VECTOR FOR A DC AXION HALOSCOPE

$$
\oint \! \mathbf{Re} \left(\mathbf{S}_{DB} \right) \cdot \hat{n} ds =
$$

$$
\int \left(\frac{j(\omega_1-\omega_a)}{4}\epsilon_0 g_{a\gamma\gamma} c \overrightarrow{B}_0\right).
$$

$$
+\frac{1}{4}g_{a\gamma\gamma}c\overrightarrow{B}_0\cdot(\tilde{a}\mathbf{J}_{e_1}^*+\tilde{a}^*\mathbf{J}_e)
$$

$$
-\frac{1}{4}g_{a\gamma\gamma}\overrightarrow{J}_{e_0}\cdot(\tilde{a}^*c\mathbf{B}_1+\tilde{a}c\mathbf{I})
$$

Axion frequency tuned to resonance $\omega_a = \omega_1$: If Halocope is inside the magnet $\,$ 1 4 $g_{a\gamma\gamma} J_{e0} \cdot (Ac\mathbf{B}_{1}^{*} + A^{*}c\mathbf{B}_{1}) = 0$

$$
\oint \langle S \rangle \cdot \hat{n} ds = -\frac{1}{4} \int (\mathbf{E}_1 \cdot \mathbf{J}_{e1}^* + \mathbf{E}_1^* \cdot \mathbf{J}_{e1}) d\tau + \frac{1}{4} \int c \overrightarrow{B}_0 \cdot (g_{a\gamma\gamma} A \mathbf{J}_{e1}^* + g_{a\gamma\gamma} A^* \mathbf{J}_{e1}) d\tau
$$
\n
$$
P_a = \frac{\omega_a c_0}{2Q} \int \mathbf{E}_1 \cdot \mathbf{E}_1^* d\tau = \frac{\omega_a U}{Q} \begin{bmatrix} P_1 = \omega_a Q U_1 = g_{a\gamma\gamma}^2 \langle a_0 \rangle^2 \omega_a Q_1 \epsilon_0 c^2 B_0^2 \end{bmatrix}
$$
\n
$$
= g_{a\gamma\gamma}^2 \rho_a Q_1 \epsilon_0 c^5 B_0^2 V_1 C_1 \frac{1}{\omega_a},
$$
\n
$$
P_d = \frac{1}{4} \int (\mathbf{E}_1 \cdot \mathbf{J}_{e1}^* + \mathbf{E}_1^* \cdot \mathbf{J}_{e1}) \qquad P_s = \frac{1}{4} \int c \overrightarrow{B}_0 \cdot (g_{a\gamma\gamma} A \mathbf{J}_{e1}^* + g_{a\gamma\gamma} A^* \mathbf{J}_{e1}) d\tau
$$
\n
$$
= 0 \text{ for closed system}
$$
\nfor a Sikivie Haloscope

Sensitivity assuming the Modified Abraham Poynting Vector

$$
\hat{i}ds = j\omega_a \int \left(\frac{1}{2\mu_0} \mathbf{B}_1^* \cdot \mathbf{B}_1 - \frac{\epsilon_0}{2} \mathbf{E}_1^* \cdot \mathbf{E}_1 + \frac{\epsilon_0}{2} g_{a\gamma\gamma} a_0 c \overrightarrow{B}_0 \cdot Re(\mathbf{E}_1) \right) dV
$$

$$
\hat{n}ds = j\omega_a \int \left(\frac{1}{2\mu_0} \mathbf{B}_1^* \cdot \mathbf{B}_1 - \frac{\epsilon_0}{2} \mathbf{E}_1^* \cdot \mathbf{E}_1 + \epsilon_0 g_{a\gamma\gamma} a_0 c \overrightarrow{B}_0 \cdot Re(\mathbf{E}_1) \right) dV
$$

 $\nabla \times E_1 = - \partial_t B_1$ ⃗ ⃗

First order: Ignore fringing

$$
\hat{z} \qquad \mathbf{B}_1 = -j\omega_a \mu_0 \tilde{q}_1 \frac{r}{\pi R_c^2} \hat{\theta} \qquad \frac{U_m}{U_e} = \frac{\int_{V_c} \mathbf{B}_1 \cdot \mathbf{B}_1^* dV}{\epsilon_0 \mu_0 \int_{V_c} \mathbf{E}_1 \cdot \mathbf{E}_1^* dV} = \frac{R_c^2 \omega_a^2}{8c^2} = \frac{\pi}{2}
$$

Sensitivity assuming the Modified Minkowski Poynting Vector

$$
\nabla \times \overrightarrow{D}_1 = \epsilon_0 \nabla \times \overrightarrow{E}_1 - g_{a\gamma\gamma} \epsilon_0 c \nabla \times (a \overrightarrow{B}_0) = -\epsilon_0 (\partial_t \overrightarrow{B}_1 + g_{a\gamma\gamma} a(t) \mu_0 c \overrightarrow{J}_{e0})
$$

$$
\mathsf{d}\mathsf{r}
$$

 $\pi R_c^2 \epsilon_0$

$$
\mathcal{V}_{rms} = g_{a\gamma\gamma} \langle a_0 \rangle c B_0 d_c = g_{a\gamma\gamma} d_c \frac{c}{\omega_a} B_0 \sqrt{\rho_a c^3}
$$

$$
P_a = \omega_a U_c, \text{ where } U_c = g_{a\gamma\gamma}^2 \langle a_0 \rangle^2 \epsilon_0 c^2 B_0^2 V_1 \Big(\frac{\pi^2 R c^2}{2\lambda_a^2}\Big)^2 \qquad U_c = \frac{1}{2} \tilde{\mathcal{V}} \tilde{\mathcal{V}}^* C_a \qquad (C_a = \mathcal{V}) \mathcal{V}^* = g_{a\gamma\gamma} \langle a_0 \rangle c B_0 d_c \Big(\frac{\pi R_c}{\sqrt{2}\lambda_a}\Big)^2 = g_{a\gamma\gamma} d_c \frac{c}{\omega_a} B_0 \sqrt{\rho_a c^3} \Big(\frac{\pi R_c}{\sqrt{2}\lambda_a}\Big)^2
$$

To First order: Real part of Poynting Theorem $= 0$: Reactive part of Poynting Theorem $\neq 0$

$$
jP_a = \oint j \operatorname{Im} (\mathbf{S}_{EH}) \cdot \hat{n} ds = \frac{j\omega_a g_{a\gamma\gamma} a_0 \epsilon_0 c}{2} \int (\overrightarrow{B}_0 \cdot \operatorname{Re}(\mathbf{E}_1)) \frac{\pi^2 r^2}{\lambda_a^2} dV
$$

)

 d_c

$$
jP_a = \oint j \operatorname{Im} (\mathbf{S}_{DB}) \cdot \hat{n} ds = \frac{j\omega_a g_{a\gamma\gamma} a_0 \epsilon_0 c}{2} \int (\vec{B}_0 \cdot \operatorname{Re}(\mathbf{E}_1)) dV
$$

$$
U_c = g_{a\gamma\gamma}^2 \langle a_0 \rangle^2 \epsilon_0 c^2 B_0^2 V_1
$$

