

Accelerator Remote Handling Telerobotics

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LA-UR-22-22680



Background and legacy

- Long legacy of remote handling operations
- Custom designed trailers for master control and remote viewing
- Telerobotic system had extension of 40ft to remotely work on targets.





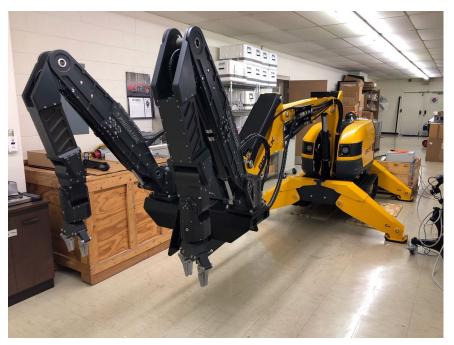
System Requirements and Design

- Mobile
- Large reach ~20ft
- Two hand systems
- Large pickup weight, grip force
- Washable
- Adaptable platform
- Small package
- Easy to setup and use
- Easily incorporate into current team resources



Integrated system by Brokk and Kraft Telerobotics

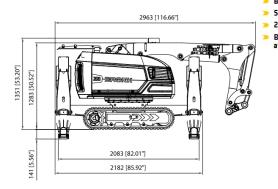


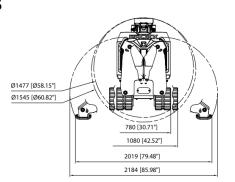




Brokk

- Electro-hydraulic
- Detachable tools
- Narrow enough to enter wide doorways
- 2100 kg; 4630 lbs
- 480VAC



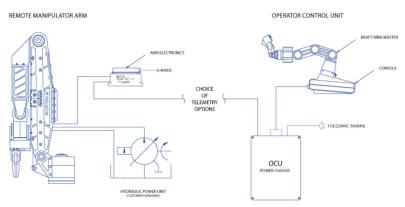


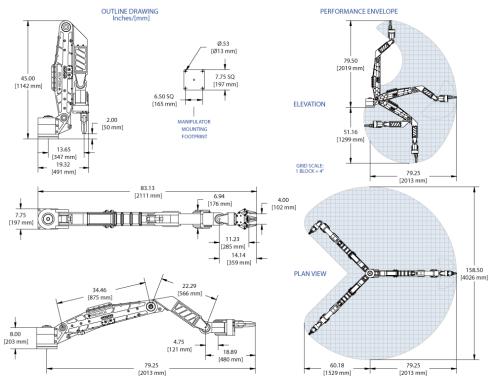




Predator Arms, Kraft Telerobotics

- Max lift 227kg (500lbs)
- Max lift at extension 91kg (200lbs)
- Wrist Torque 135Nm (100 ft-lbs)
- Grip force 1334N (300lbs)
- Programmable functions/motions
- Force feedback

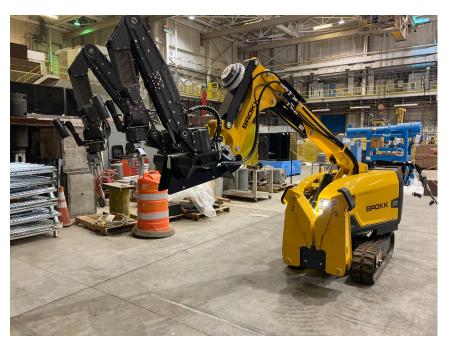






Cameras

- 2592 x 1944 resolution POE cameras
- 6 cameras on the brokk-predator system
- Multiple auxiliary cameras added as needed





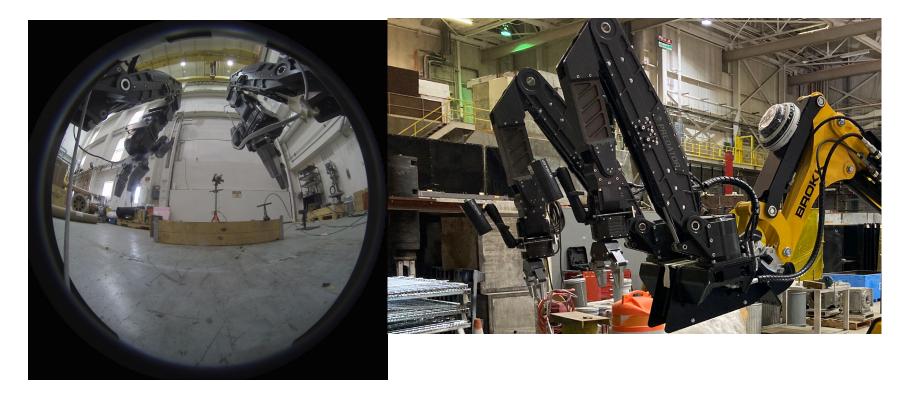
Viewing Station

- 4 monitors
- Adjustable monitor height
- Adjustable height and width of the master controller placement
- Mobile viewing station
- Stream and record multiple cameras at the same time





Camera Placement





Trailer





1 Ci Co-60 Source Transfer

- Transfer a source from its shipping cask to its experimental housing
- 150 mSv (15 Rem/hr) @ 30cm (~12in)
- 9.5mm (0.375in) diameter x 9.5mm (0.375in) tall cylinder





Suction tools

- Small enough to pick up objects as small as 6mm (0.25in)
- Multiple suction cups available





Beam Window Downsizing Setup







Mockups





Saw Attachment

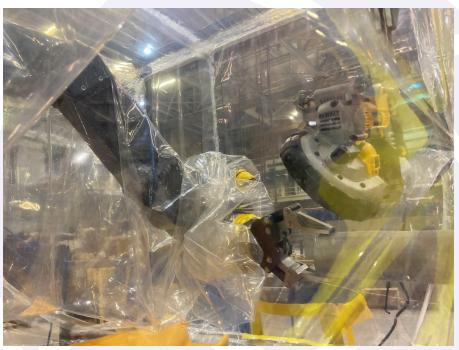
 Standard Dewalt portable saw with custom designed bracket with T-handle





Cutting techniques







Decontamination materials

- Loctite rubberized coating
- Somewhat durable
- Easy to peel off







Challenges

- Live streaming with minimal latency
- Camera depth perception
- Contamination control and cleaning



Future work

- Remote handling rigging
- Improved cameras
- Resolve and improve camera latency
- Improve contamination control methodologies
- Additional tooling







Questions

