



## **Test Facility Dipole**

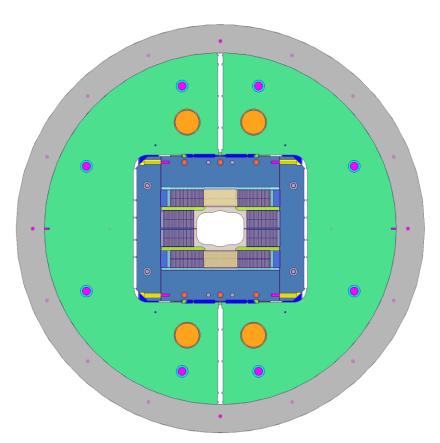
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HFVMTF Cable Test Facility: First Workshop on User Interfaces

### Outline

- Test facility dipole design parameters
- Technical background
- Coil and structure design
- Fabrication and assembly infrastructure
- Summary

#### **Design Parameters**



Cable test facility magnet for testing inserts and cables in a high dipole filed.

Joint effort between the offices of *Fusion Energy Sciences* and *High Energy Physics* (US Department of Energy)

#### • Target field:

- Operation target: 15 T at 1.9 K
- Design target: 16 T with 15% margin at 1.9 K

#### Clear bore size:

• 144 mm x 94 mm rectangular aperture with superimposed 106 mm diameter.

#### • Nb<sub>3</sub>Sn coils layout:

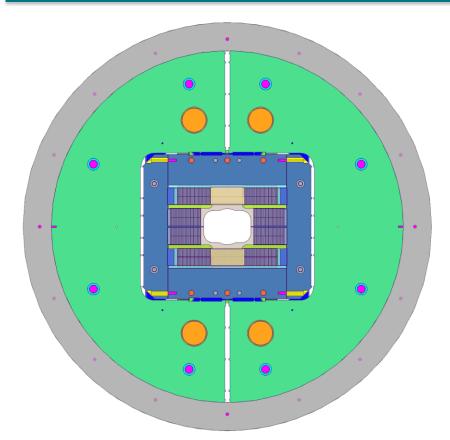
- Block coil design with flare ends and rectangular bore.
- **Coil 1**: 40 turns/layer, **Coil 2**: 44 turns/layer. (Non-graded coils).

#### Mechanical design:

 Aluminum shell-based structure using key-andbladder technology, with axial pre-load.

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#### **Design Parameters**



Cable test facility magnet for testing inserts and cables in a high dipole filed.

Joint effort between the offices of *Fusion Energy Sciences* and *High Energy Physics* (US Department of Energy)

- Uniform field length: straight section (within 1% variation) > 750 mm
- Wire specification: RRP 162/169, 1.1 mm diameter

#### Cable specifications:

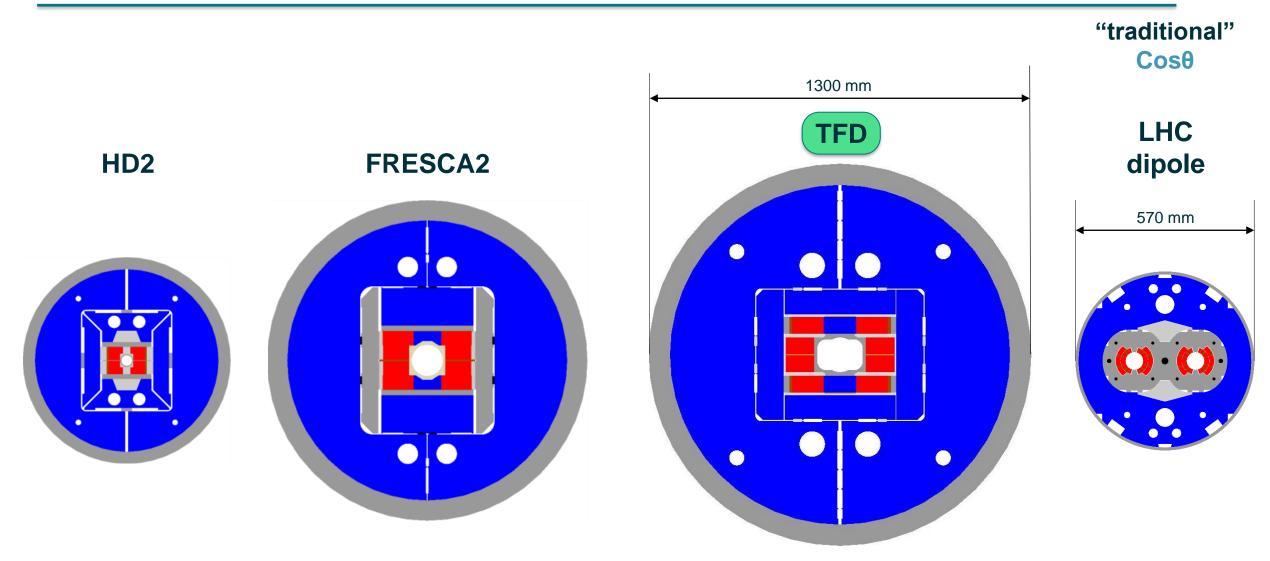
Parameter	Unit	Value
Strand diameter	mm	1.1
No. strands		44
Cable width (bare, before reaction)	mm	26.20
Cable thickness (bare, before reaction)	mm	1.91
Cable width (bare, post-reaction)	mm	26.46
Cable thickness (bare, post-reaction)	mm	1.99
Insulation thickness	mm	0.185
Cable width (insulated)	mm	26.81
Cable thickness (insulated)	mm	2.34
Inter-layer insulation	mm	0.4

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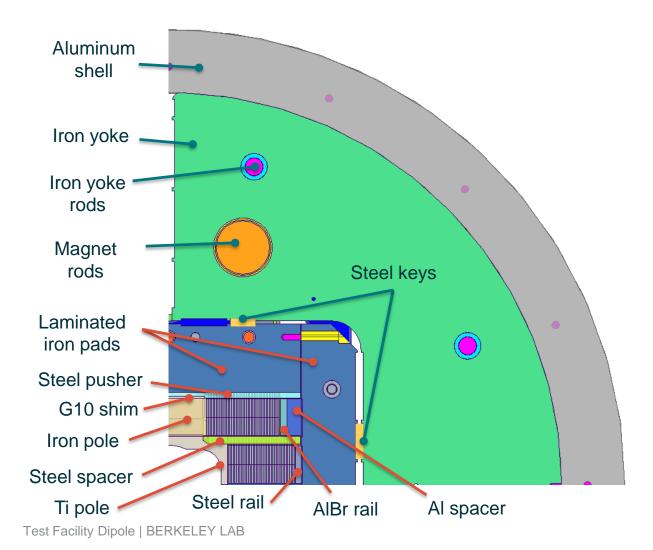
#### **Technical Background**

- The Test Facility Dipole design is based on studies and development of large aperture, high field dipoles over the past 15+ years:
  - 1. LARP studies of HL-LHC "Dipole First" IR (LBNL/FNAL/BNL, 2003-04)
  - 2. EFTA Dipole (EDIPO) Design Study (EFDA/CEA/CRPP/FZK/LBNL, 2004-06)
  - 3. LD1 magnet design (2009-12) at LBNL
  - 4. FRESCA2 magnet development (CERN/CEA/EuCARD, 2010-2018)
  - 5. HEPdipo design study (CERN/PSI/F4E/LBNL, 2017+)
- We are taking full advantage of these efforts and experience to accelerate the TFD development and decrease risk in a broad range of areas, in particular:
  - Winding layout and parameters (LARP, EFDA, LD1/HD, FRESCA2, HEPdipo)
  - Coil tooling, parts, and fabrication process (FRESCA2, LD/HD)
  - Magnetic, mechanical, protection models and analysis (FRESCA2, HEPdipo)
- However, while building on this experience we are also optimizing the design to reflect the specific TFD requirements, in particular the higher field target

#### Comparison of "traditional" *block-type magnets*



#### **Magnet Cross-Section and Main Design Features**



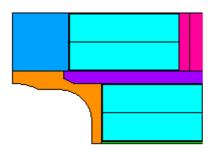
- The preloading at room temperature through the bladders placed between the iron yokes reduce the peak stress within the coil.
- The inclusion of a G10 shim reduces the overall stress in the pole and within the pole to coil interface.
- The location of the keys is based on the reduction of the peak tension stress at the pole to coil interface.
- A series of smartshims will be place within the midplane of the magnet, coil 1 to coil 2 interface and coil 2 to vertical iron pad in order to guarantee perfect contact geometry.

7

## **Two Dimensional Optimization (Magnetic)**

- Coil size and position chosen to minimize load line margin while maintaining reasonable field quality
- Load line margin at 1.9 K
  - Approximately 81% at 16 T
  - Approximately 76% at 15 T
- Field uniformity is approximately 0.2% at 50 mm radius





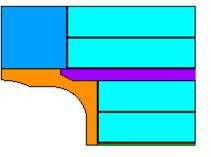
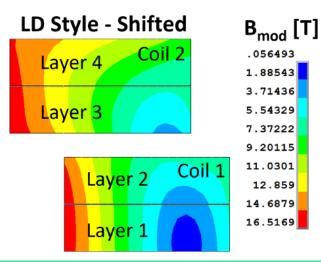
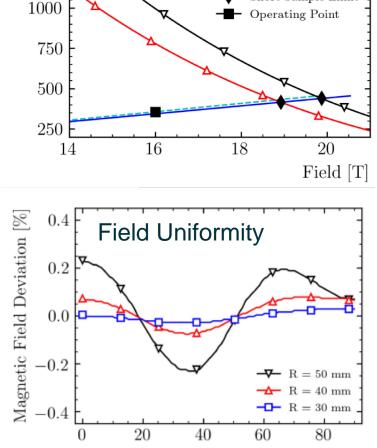


TABLE III Alternative Layout Results		[¥] 1500 ti	
Descenter	<b>Ch</b> 10 - 1	urrent 1220	
Parameter	Shifted	. F	
Operating Current	15.6 kA	$\smile$ 1000	
Short Sample Current	19.2 kA	1000	
Load Line Margin	81.2%	750	
Max Field (coil 1)	16.5 T	750	
Max Field (coil 2)	16.1 T		
Stored Energy (per quadrant)	1.8 MJ/m	500	
Total Fx (coil 1)	6.3 MN/m		
Total Fy (coil 1)	-2.7 MN/m	250	
Total Fx (coil 2)	10.0 MN/m	200	
Total Fy (coil 2)	-6.9 MN/m	. 1	





Load Line

Bore Field

Peak Field

HiLumi 1.1

FCC Dev. Wire

Short Sample Limit

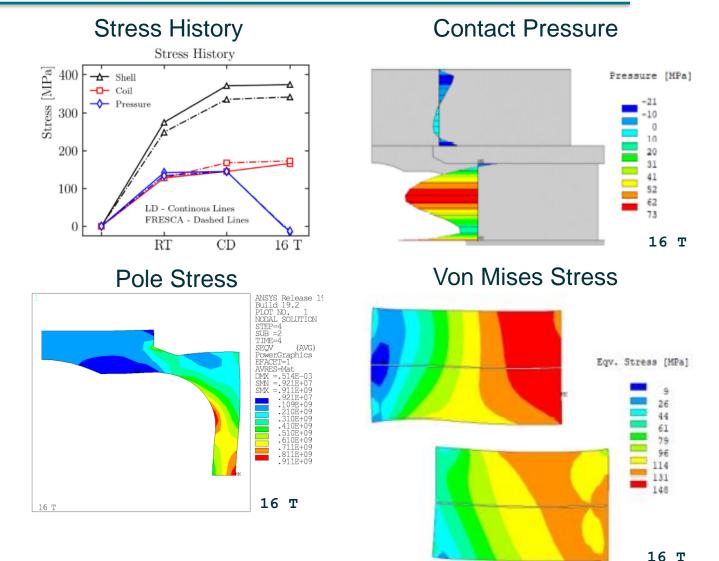
Angle [degrees]

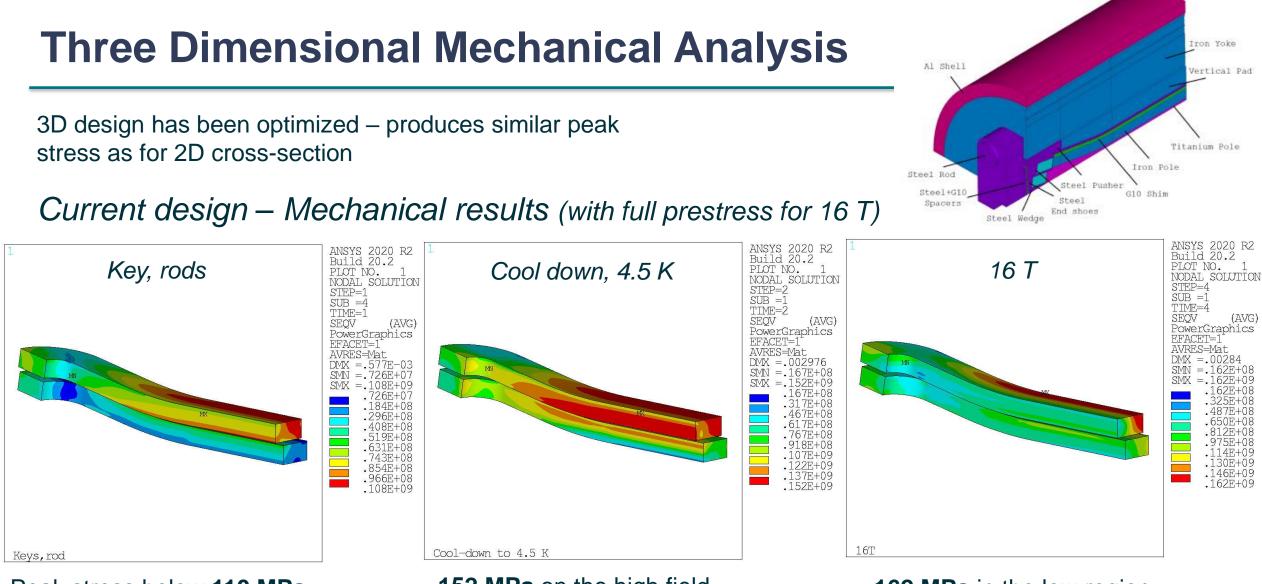
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G. Vallone et al., IEEE Trans Appl Supercond, Vol 31 No. 59500406

## **Two Dimensional Optimization (Mechanical)**

- Spacer is introduced between the coils to minimize bending stress on the coils
- Key positions are optimized to minimize von Mises stress and tension at contact interfaces
- Maximum von Mises stress on the coils
  - RT Loading: 126 MPa
  - Cooldown: 145 MPa
  - Powering: 166 MPa
- Ensure sufficient safety margin is present for other structure materials (i.e. pole, yoke, shell) taking into account fracture toughness where appropriate





## Peak stress below **110 MPa** at room temperature

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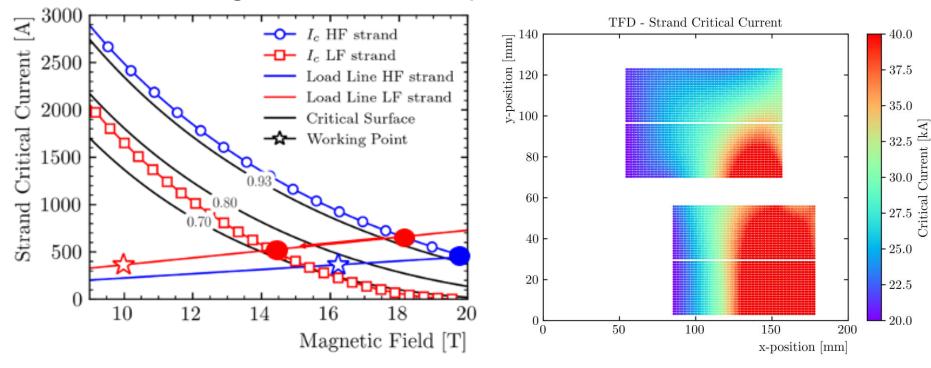
**152 MPa** on the high field region after cooldown

**162 MPa** in the low region at 16 T

10

#### Advanced Modeling Including Strain Dependence on Critical Current

#### Load line margin with strain dependence

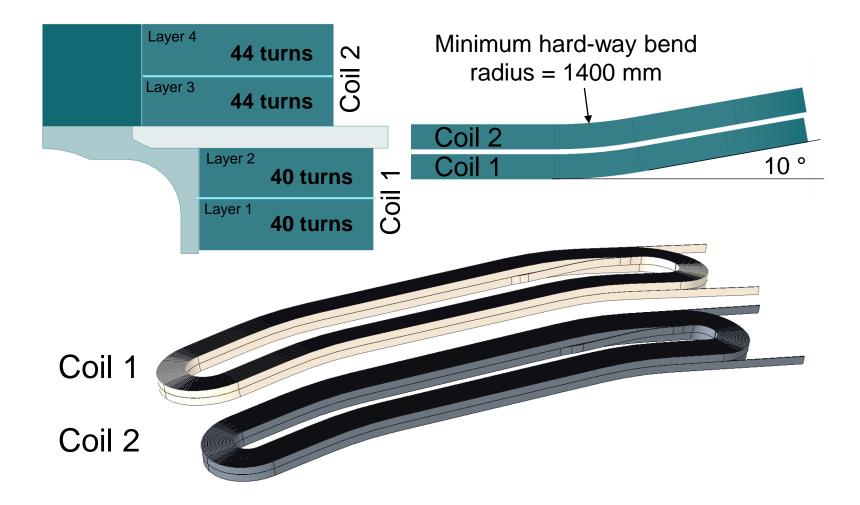


- The short sample limit for each strand, as a function of field and strain is computed:
  - Detailed 'strand' model of the magnet (2D)
  - Critical surface parametrization from strand measurements

- 80% in the high field / low stress region
- 57% in the low field / high stress region

Computation of the Strain Induced Critical Current Reduction in the 16 T Nb3Sn Test Facility Dipole by G. Vallone, Presented at ASC22

#### **Development of the Nb<sub>3</sub>Sn coils (Coil Design)**

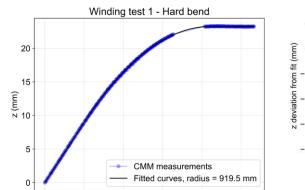


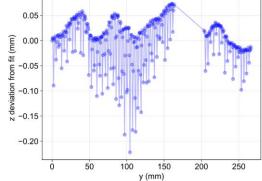
- A fully parametric 3D CAD model of each coil has been implemented in CREO parametric and is being used as the reference driving the rest of the parts of the magnet.
- The current version of the parametric models ensure the requirement of region of field uniformity of 750 mm.

## **Development of the Nb<sub>3</sub>Sn coils (Winding Tests)**



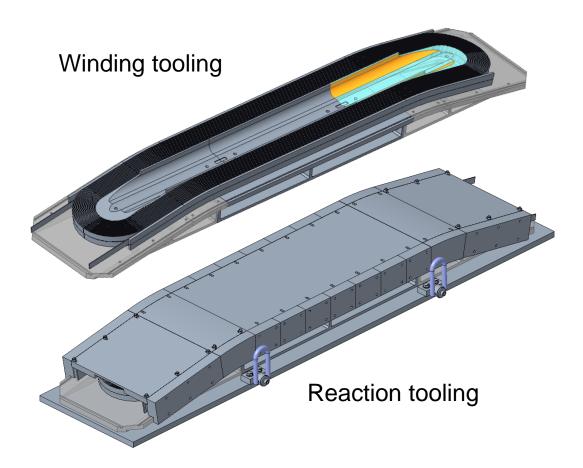
Winding Test CMM Measurements





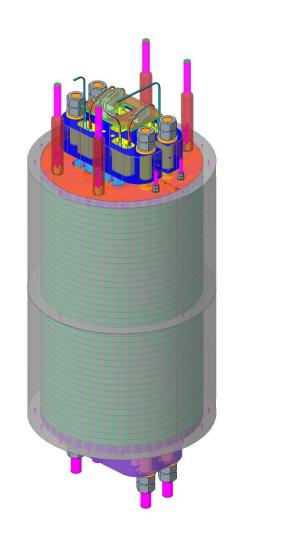
- Winding tests were performed with the prototype cable
- 3D printed components were used where possible to expedite testing
- CMM measurement were performed to determine cable position and used to define coil hard bend radius
- Test of layer jump design was performed

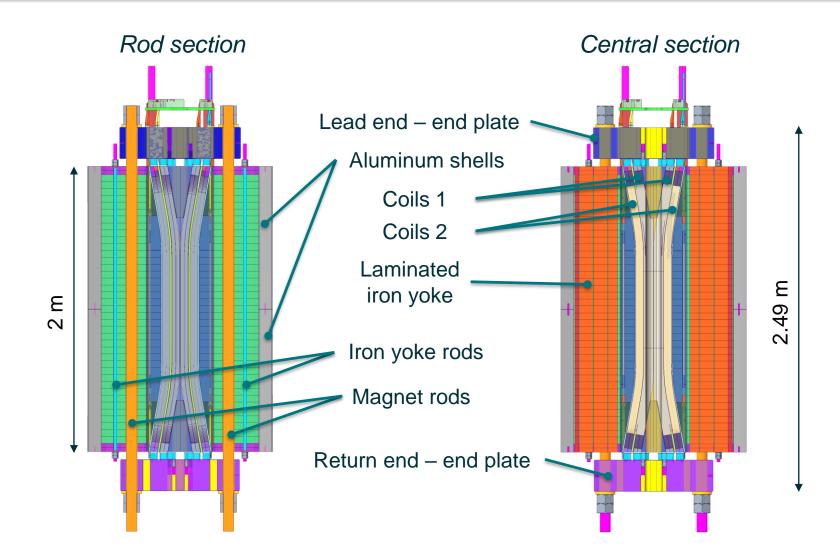
## Development of the Nb<sub>3</sub>Sn coils (Coil Winding and Reaction)



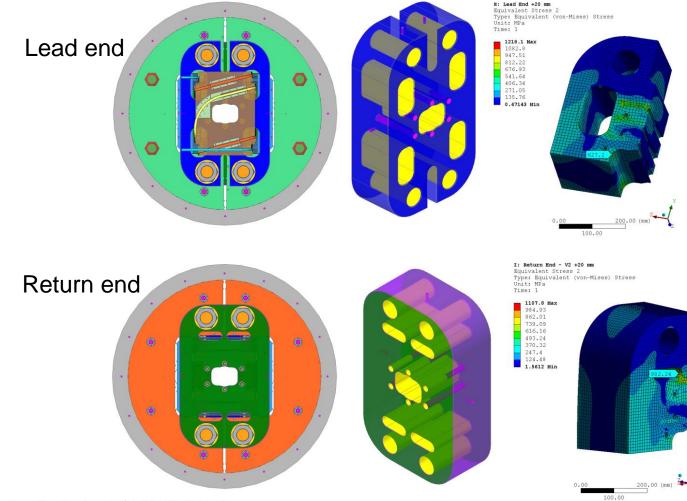
- The design of the **winding tooling** for Coil 1 is currently being finalized, incorporating the design feedback from the winding and layer jump tests.
- The **reaction tooling** for Coil 1 is being developed along with the winding + reaction + impregnation manufacturing sequence.
- The global insulation scheme for winding, reaction, and magnet assembly has been developed following the constraints for insulation, manufacturing of the coils, and magnet assembly.
- Winding and reaction tooling for Coil 2 are currently being designed in parallel.

#### **Magnet Structure Overview**





#### **End Plates**

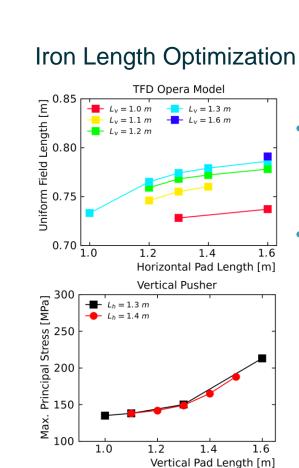


- The geometry of the **end plates** geometry has been created based on the FE analysis, and to comply with the following constraints:
  - Allow for the leads to pass through the end plate towards the splice box.
  - Allow for clear access to the aperture of the magnet.
  - Allow for clear access to all bladders and keys locations during the assembly operations.

Step	Fz (MN)	
Loading	9.05	
Cold	10.62	
15 T	10.89	
16 T	10.92	

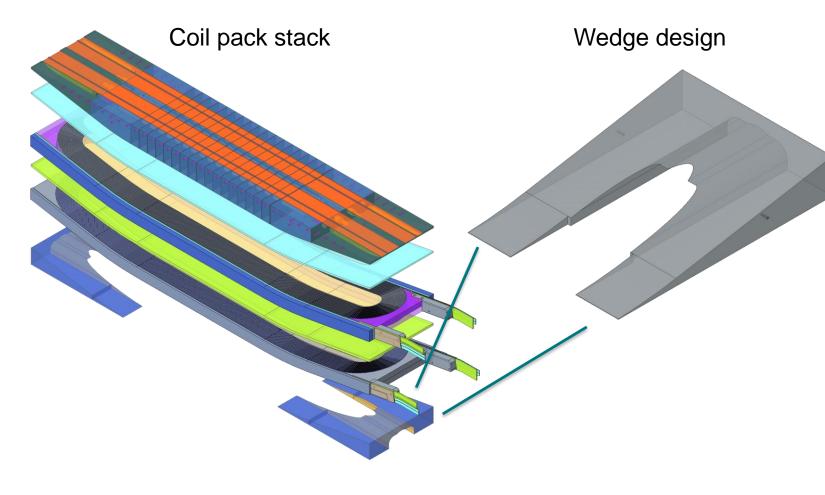
## **Yoke and Loading Pads**

# Laminated structures Iron yoke Vertical pad Horizontal pad



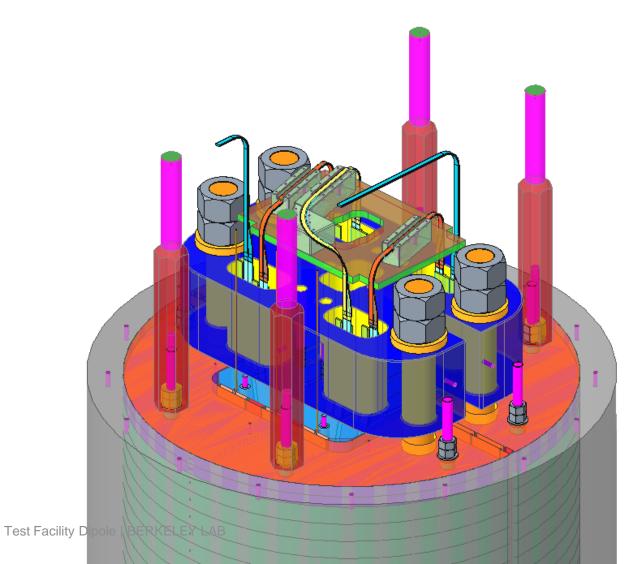
- The yoke structure has been adapted to laminations manufactured with ARMCO grade 4 plate stock of ~50 mm. The current design includes the optimized location and size of keys and bladders.
- The vertical and horizontal pads are now constructed as a laminated structure based on ARMCO grade 4.
- The structure of the pads has been optimized to facilitate the manufacturing and assembly of the parts and to allow for the transition to stainless steel segments towards the ends of the magnet.

### Wedge Design and Implementation



- The wedge has been redesigned to incorporate the modifications from the FE analysis to reduce the stress in the conductor.
- Wedge analysis performed under different contact geometry conditions and bonding assumptions
- The wedge will be impregnated along with coil 1 but will be mold released following the analysis recommendations.

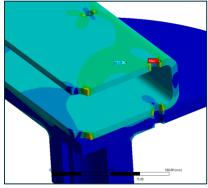
### **Splicing and Connection Box**

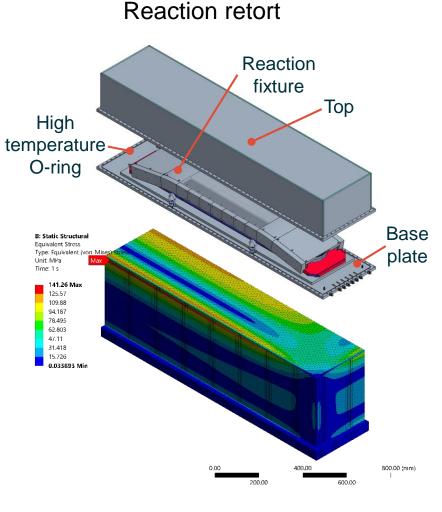


- The splicing method, operation sequence and integration within the end shoe structure is currently being developed for coil 1 and 2.
- Each Nb<sub>3</sub>Sn lead will spliced to two NbTi cable that will be then further spliced in the connection box sitting above the end plate.

## **Development of infrastructure (Winding and Reaction)**

 Winding table





- Following the FE analysis performed, the main winding table selected for the project has been updated with new components to allow for the weight of the coil to be supported.
- The **retort** design relies on a high-temperature O-ring, and the top structure has been selected in order to simplify the sequence of operations for inserting and extracting the reaction fixture.

### **Development of infrastructure** (Reaction and Impregnation)

#### **Reaction furnace**



## Impregnation chamber Power calculation 1000 ≨ 8000 6000 mperature - Objective Time (hours)

- Extensive work has been carried out regarding the instrumentation of the furnace and powering connections, following the relocation to the new location at Berkeley lab.
- The power requirements for a new heating system for the impregnation chamber have been assessed based on a transient FE thermal model assuming CTD-101K as the epoxy system.
- The power supply, control system, and instrumentation are being developed for three heating zones along the coil.

#### **Conclusions and next steps**

- The coil models and detailed engineering drawings of components are being finalized. The start of the procurement required for coil 1 winding, i.e. coil components and tooling, is expected for the beginning of 2023.
- The first prototype coil (coil 1) is expected to be fabricated by mid 2023.
- Preliminary drawings for many of the components for the magnet support structure have been generated.
- Extensive work is still ongoing with regards to design of several coil components, magnet support structure, and associated tooling.
- The preparation of the infrastructure and manufacturing processes is in progress.

## Thanks!