Fermilab Dus. Department of Science

Object Stores for CMS data

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Rothko, Number 19 (1949)

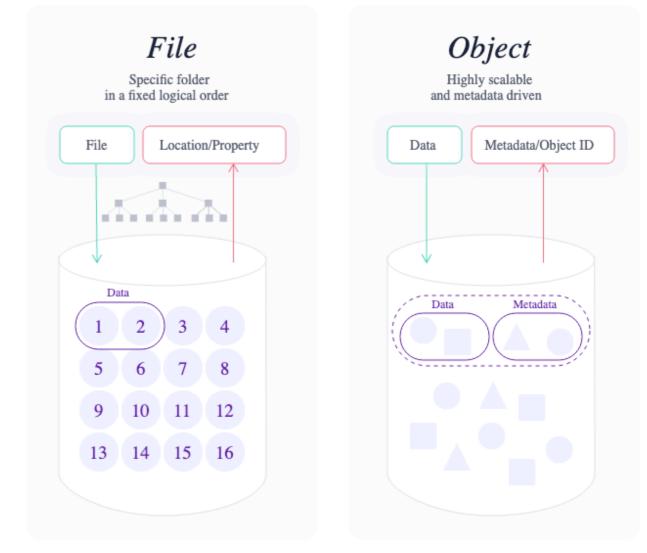
Overview

- What is an object store?
- How can we store our data as objects?
- What benefits does this have vs. files?
- Can we read and write data efficiently with objects?
 - Test results with prototype framework



Object store vs. filesystem

- Traditional data storage technology: distributed filesystem
 - e.g. NFS, EOS, dCache, Lustre, HDFS*, ...
 - Often with remote access protocol (xrootd)
 - Files are concurrently read/writeable
- Popular new-ish technology: object store
 - Native remote access (http)
 - Objects are immutable (overwrite possible)

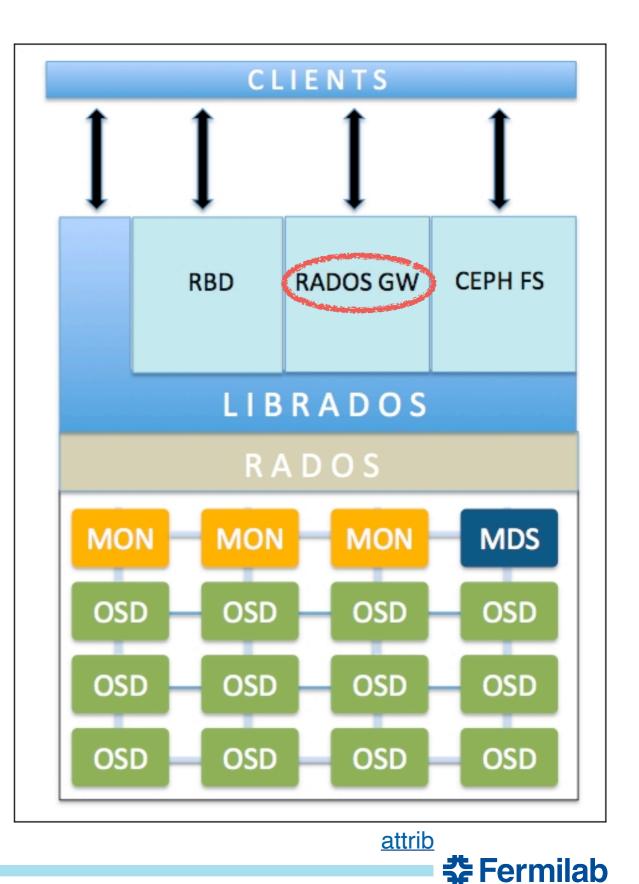






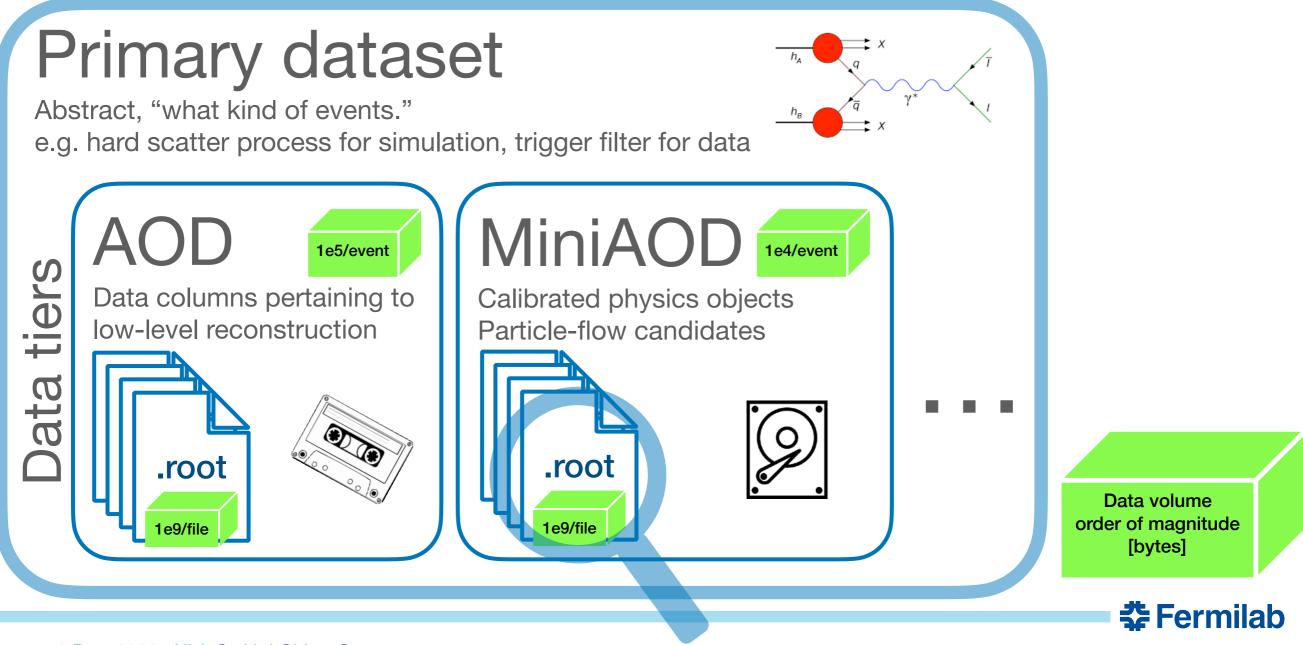
Ceph technology

- Ceph cluster
 - Distributed storage system
 - Scalable, fault-tolerant, software-defined
- RadosGW
 - Ceph implementation of S3 protocol
 - Unrelated to, but carries features (baggage?) of Amazon S3 service



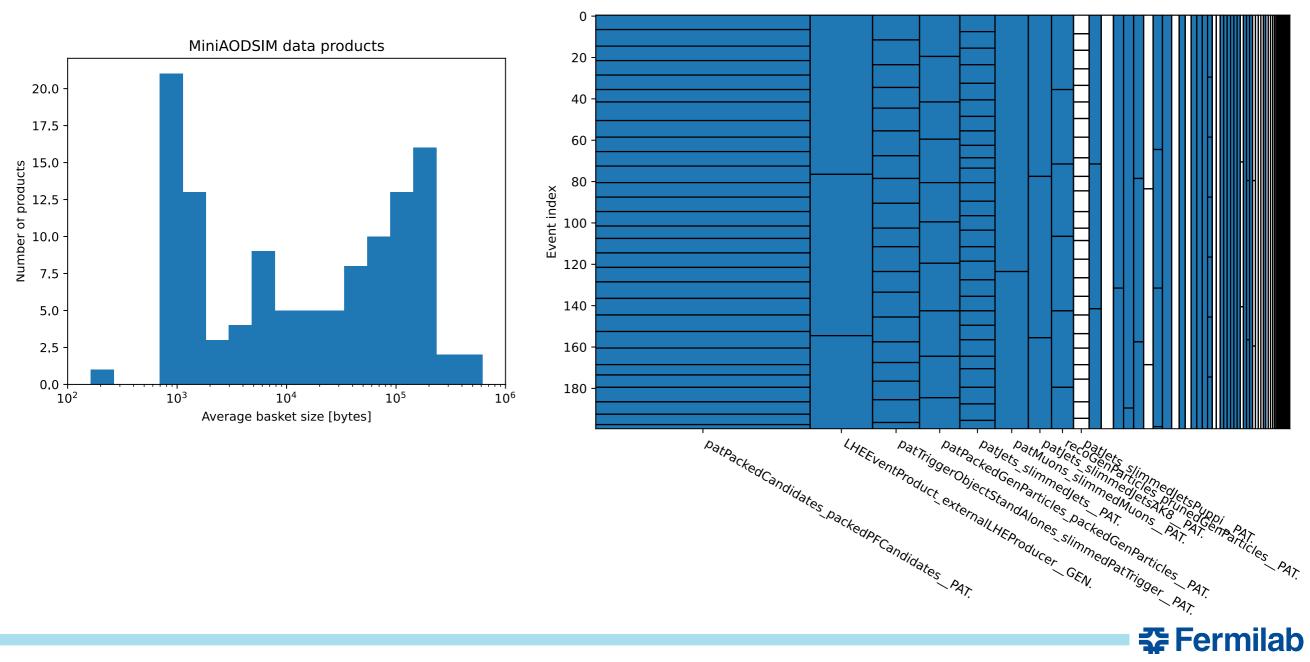
CMS Data organization

- CMS stores events (rows) in *datasets* (~100k)
 - Each dataset has many *files* (~100M), each has several *replicas* stored at WLCG sites
 - Data tiers statically define what information (columns) is included
 - Analysis uses the smallest practical data tier



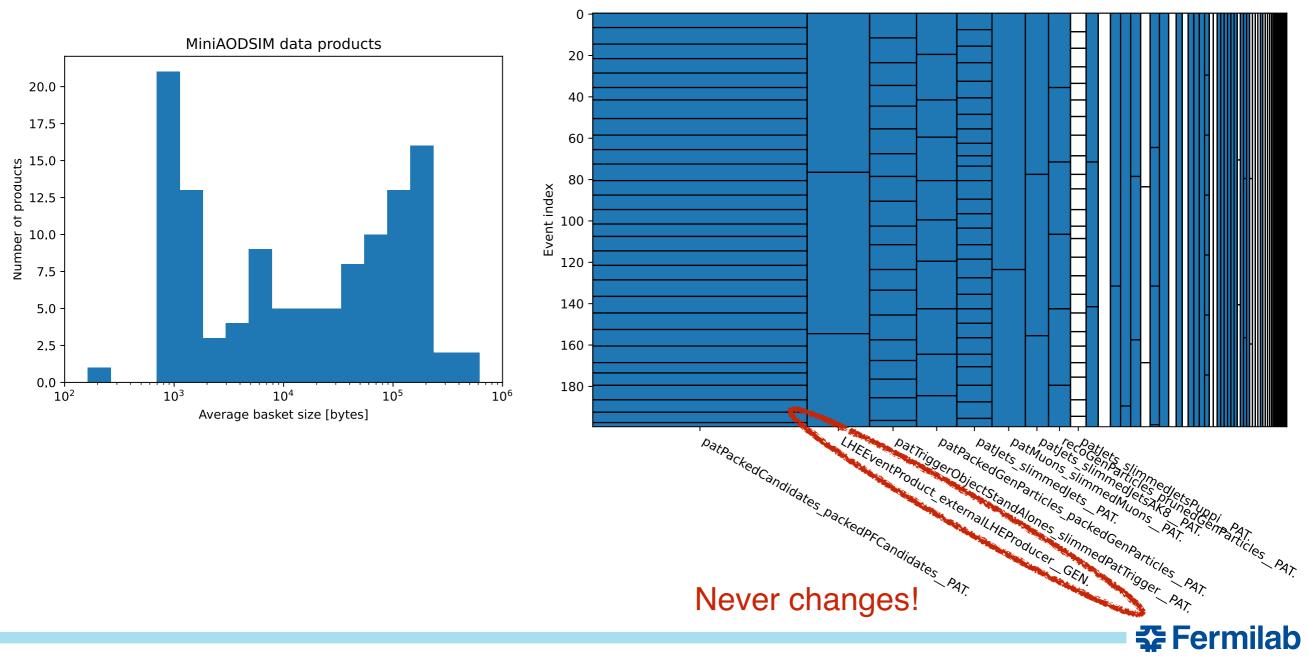
File format

- Event Data Model (TTree)
- Branch: metadata about C++ data type, basket positions
- Basket: serialized C++ objects stored contiguously*



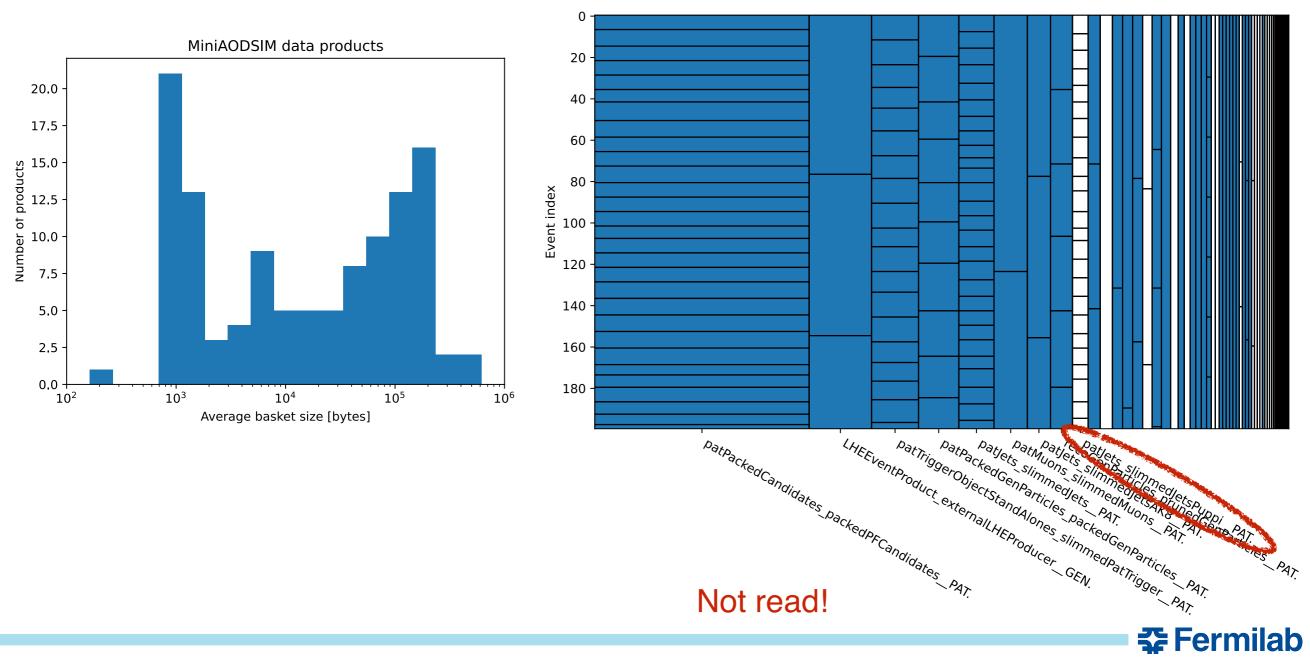
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Breaking down the ROOT file

- Essentially storing (+ moving) smaller units
 - This is usually a bad thing



Intermodal container

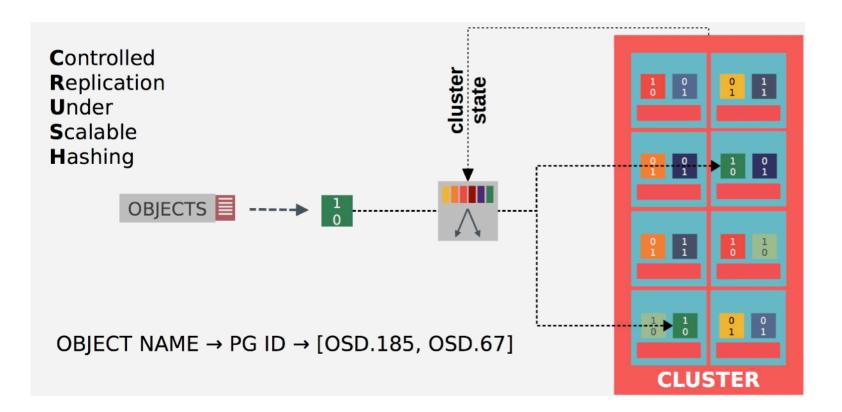


Break-bulk cargo



Breaking down the ROOT file

- Essentially storing (+ moving) smaller units
 - This is usually a bad thing
- Calculated placement
 - Like a hash, client-side
 - Downside: cluster state change causes reshuffle
 - Consistent hashing to minimize movement



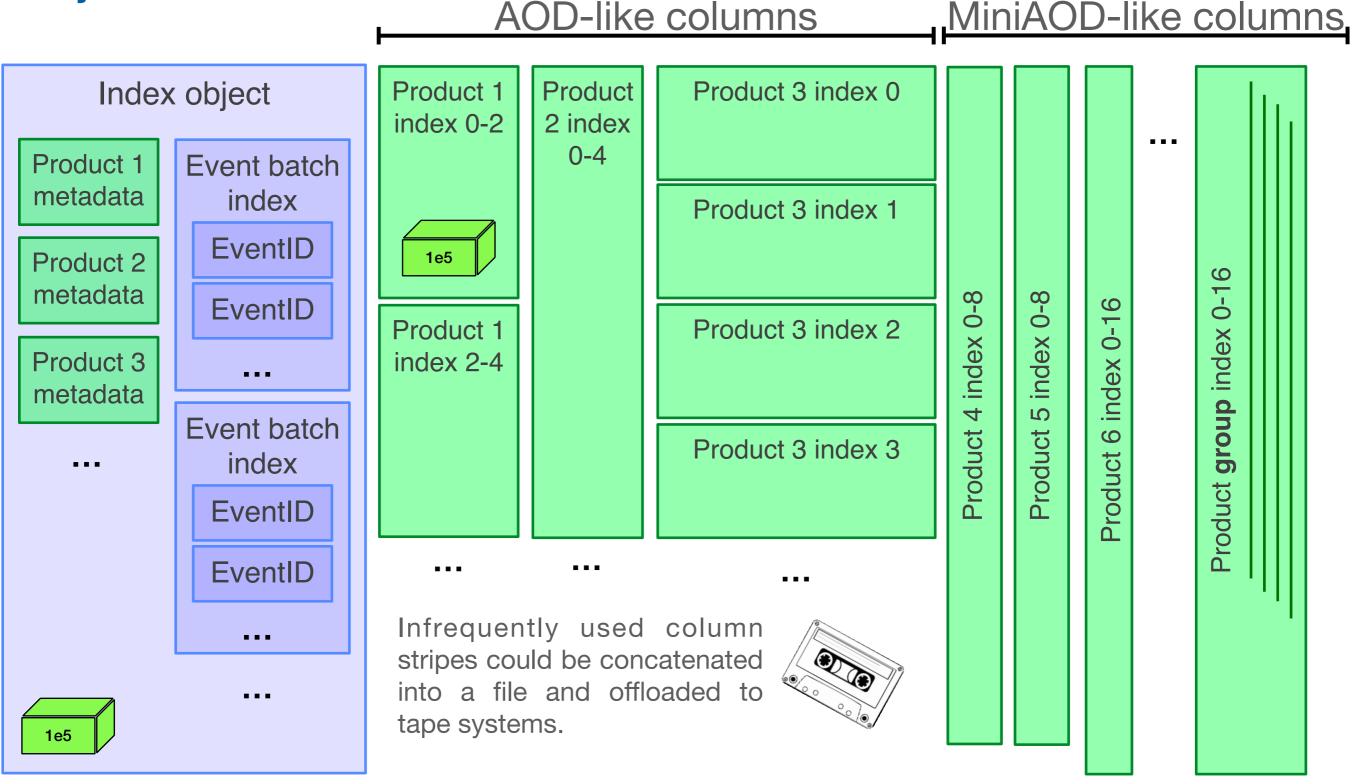




Break-bulk cargo



Object data format



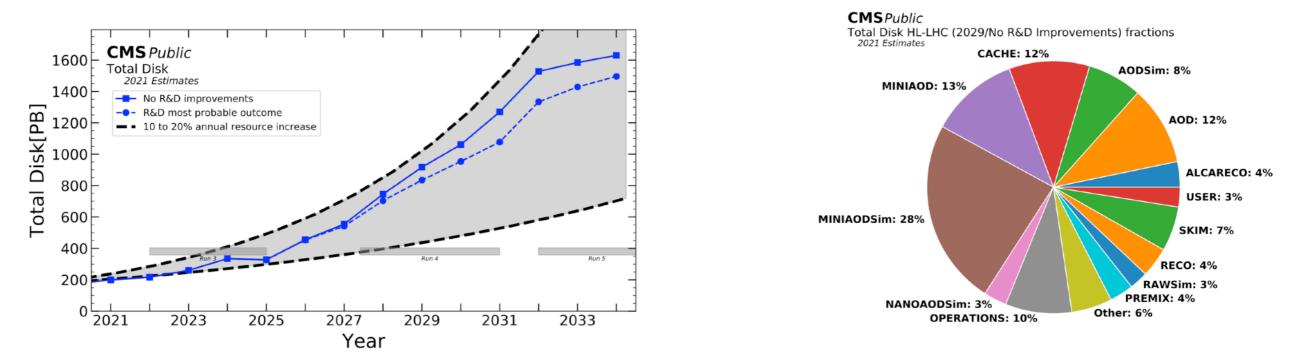
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Disk as a cache

- Disk is expensive (vs. tape)
 - Only MiniAOD, NanoAOD data tiers reliably on disk now
 - Ok because of 10+y experience with detector to know what we need
 - For HL-LHC, new detectors may require more time with low-level information
- Best cache: all the columns you need, none you don't
 - Different set of columns needed for different PDs, analyses
 - Not all rows read if filtering (skimming)
 - How much can we reduce disk use from PD*tier granularity we have now?



https://twiki.cern.ch/twiki/bin/view/CMSPublic/CMSOfflineComputingResults



Strawman

- Most content does not change with re-processing
 - Even for UltraLegacy, already two MiniAOD versions
- Keeping only new products would save a lot of disk

Tier-based scheme

MiniAOD Data product	KB per event	
	v1	v2
packed+pruned genParticles	5.7	5.7
slimmedElectrons	1.3	1.3
Others	48.7	48.7
Total	55.7	55.7

Object store scheme

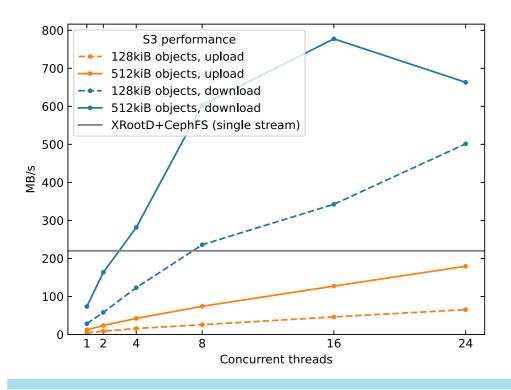
MiniAOD Data product	KB per event	
	v1	v2
packed+pruned genParticles	5.7	-
slimmedElectrons	1.3	-
Others	48.7	-
Updated slimmedElectrons	-	1.3
Total	55.7	1.3

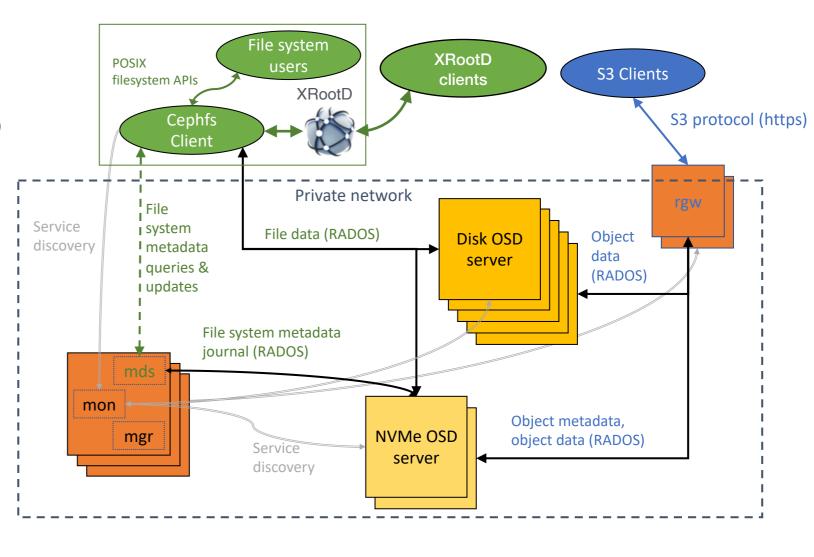
Numbers sourced from a UL17 TTBar simulation file



Test cluster

- Ceph pilot cluster setup at FNAL
 - 9 retired dCache machines
 - Total 2 PB HDD, circa 2014-2018
 - Two servers for metadata
 - 20TB NVMe
 - Edge machines for xrootd door to CephFS, Ceph management daemons (mon,mgr)



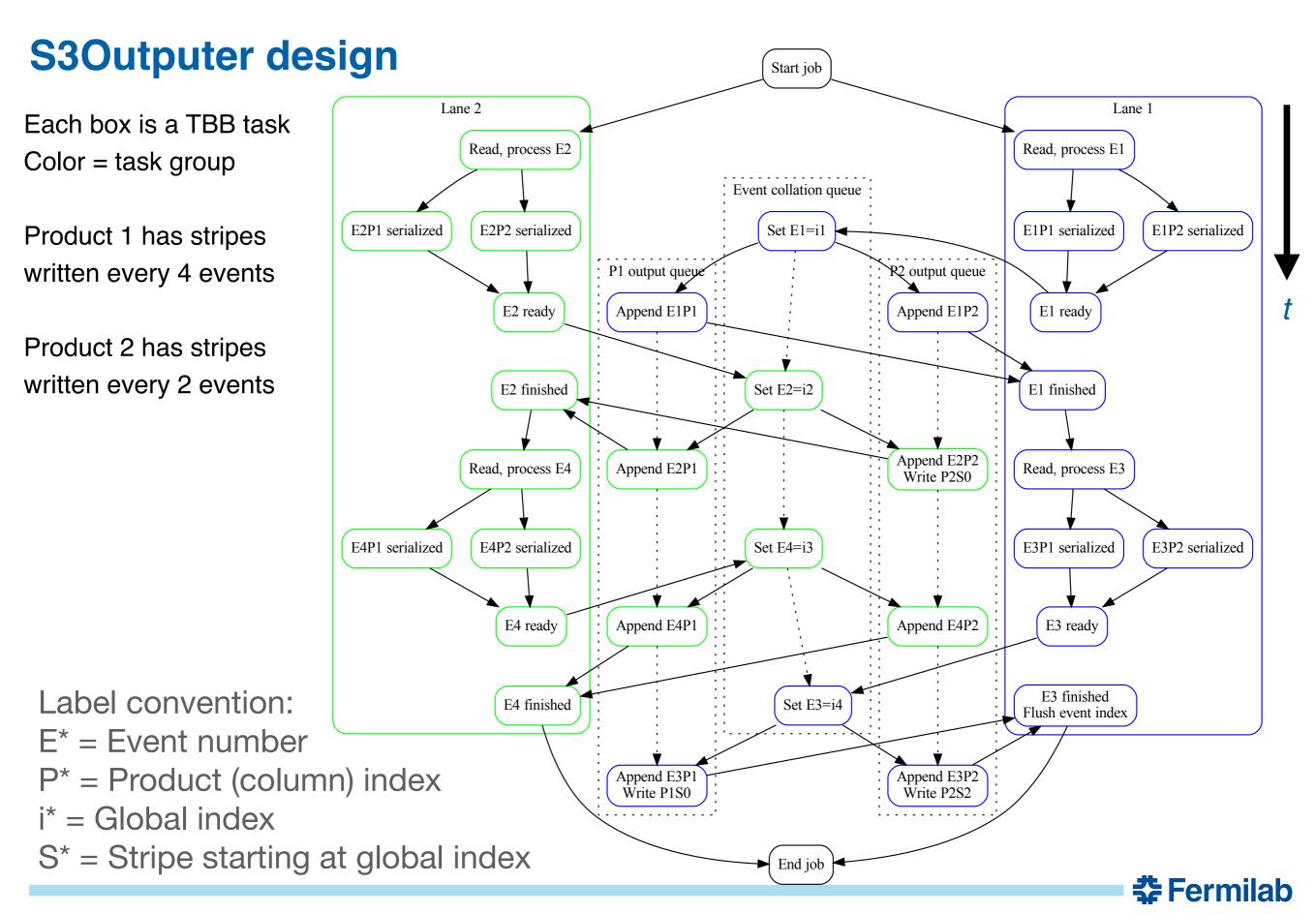




Object I/O performance

- <u>CCE-IOS project</u> to evaluate CMSSW (& other) I/O performance
 - Output module is a bottleneck for CMSSW above 8 threads
 - With (in development) ROOT concurrent I/O, issue may go away
 - However, still worth investigating performance of writing to many objects vs. one file
- Framework to evaluate alternative I/O strategies
 - https://github.com/hep-cce2/root_serialization
 - Easy to add new output modules, simulate event processing, and test I/O
- Wrote an S3Source and S3Outputer in the framework
 - Using libs3 as backend, fully asynchronous with TBB tasks
 - <u>https://github.com/hep-cce2/root_serialization/pull/47</u>
 - Key features:
 - Parallel stream compression
 - Asynchronous I/O
 - Row-wise to column-wise pivot





S3Source design

Each box is a TBB task Color = task group

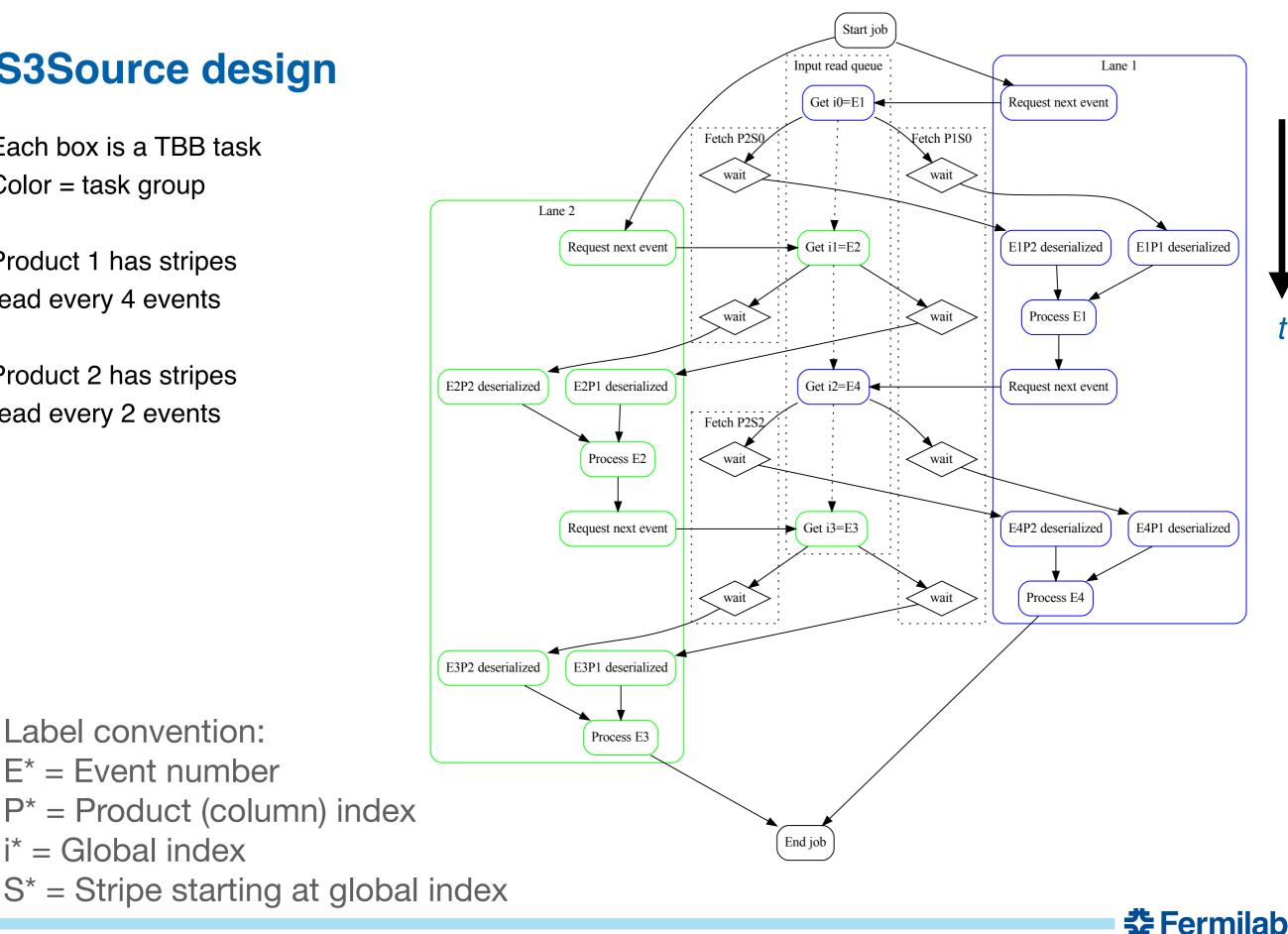
Product 1 has stripes read every 4 events

Product 2 has stripes read every 2 events

Label convention:

 $E^* = Event number$

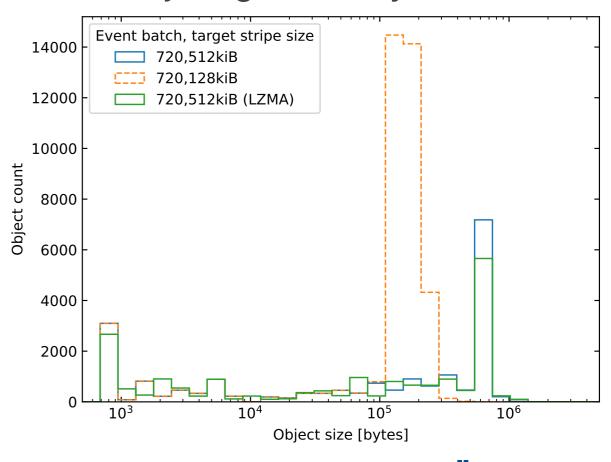
i* = Global index



Storage efficiency

- Input: 80k event MiniAOD file
 - LZMA compression
- Three S3Outputer configurations tested:
 - Event flush count 576, product flush size 128kiB, ZSTD4 compression
 - Event flush count 720, product flush size 512kiB, ZSTD4 compression
 - Event flush count 720, product flush size 512kiB, LZMA9 compression
- For k+m erasure-coded storage pool, minimum object granularity of k*4kiB
 - Overhead for EC4+2 in % listed below

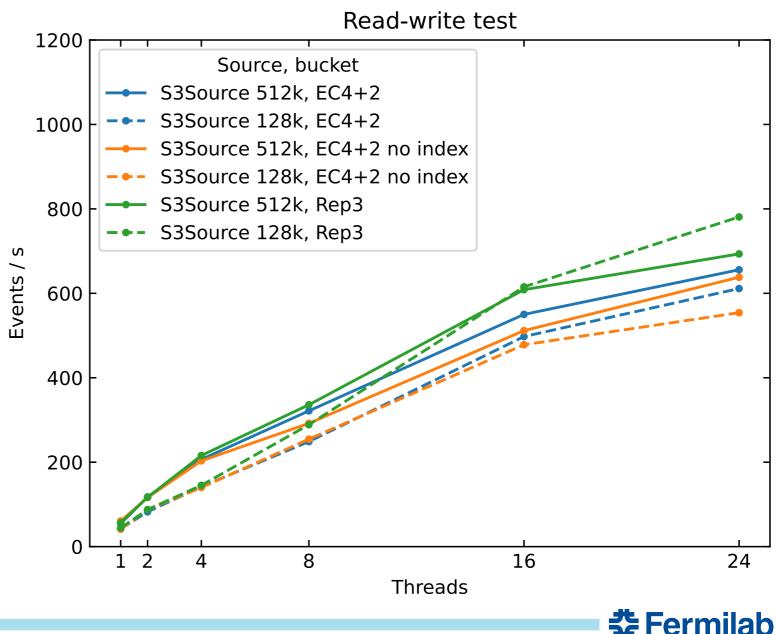
Format	KB per event
MiniAOD input	55.7
Objects: - event batch size 720 - target stripe size 128kiB	71.4 + 6.5%
Objects: - event batch size 720 - target stripe size 512kiB	70.6 + 3.5%
Objects (LZMA): - event batch size 720 - target stripe size 512kiB	61.8 + 3.7%





S3Source -> S3Outputer

- Full chain: fetch→decompress→deserialize→serialize→compress→push
- Repeating same test, with different bucket configurations
 - Baseline: EC4+2, bucket index in rep3 ssd pool
 - "no index" disable bucket index
 - "Rep3" data in 3x replica hdd pool
- Vary also S3Outputer config
 - No LZMA (very slow)

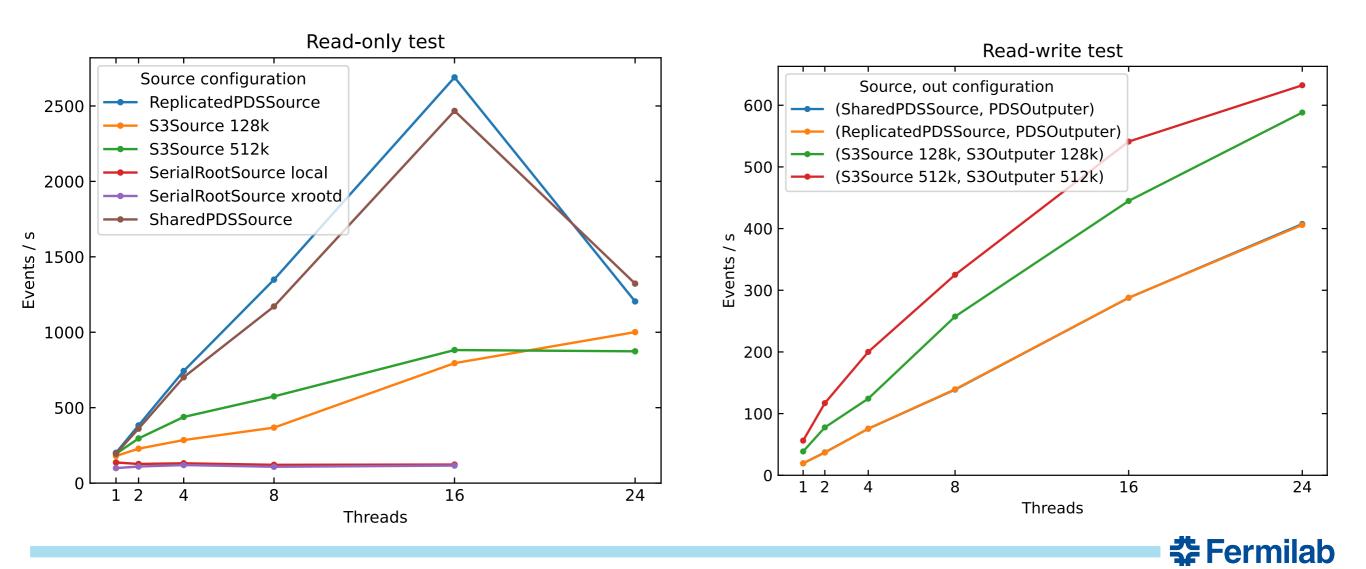


S3Source -> DummyOutputer

- Read-only chain: fetch→decompress→deserialize
- Repeating same test, with different bucket configurations
 - Baseline: EC4+2, bucket index in rep3 ssd pool
- "no index" disable bucket index Read-only test 1200 - "Rep3" data in 3x replica hdd pool Vary also S3Outputer config 1000 - No LZMA (very slow) 800 Events / s 600 Source, bucket 400 S3Source 512k, EC4+2 S3Source 128k, EC4+2 S3Source 512k, EC4+2 no index 200 S3Source 128k, EC4+2 no index S3Source 512k, Rep3 S3Source 128k, Rep3 0 16 24 8 2 4 1 Threads

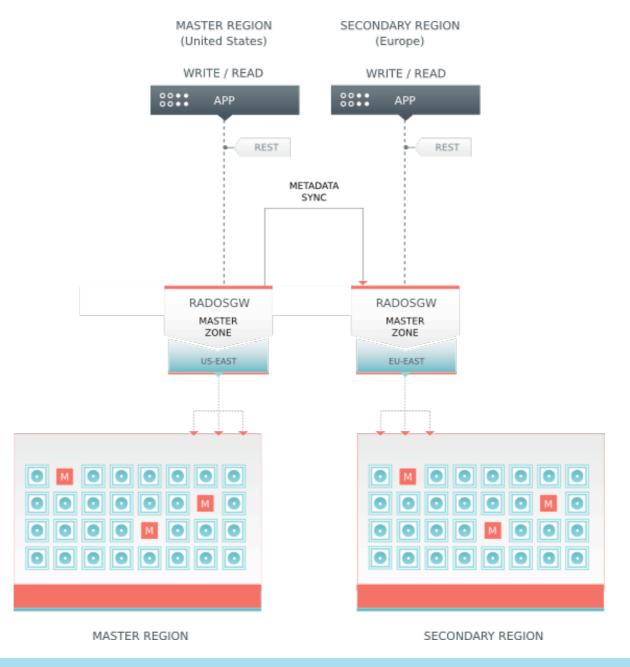
S3 vs. other Source/Outputers

- ROOT source similar to a CMSSW grid job
 - Read file via xrootd, server has CephFS (same cluster) mounted
 - No ROOT outputer due to bug
- PDS source: write whole events sequentially
 - Very good thread scaling (last data point = all cores on machine)



Bonus: multi-site

- RadosGW, like Amazon S3, can have cross-zone sync
 - Further data resiliency in the lake
 - Probably still want edge caches





Conclusions

- Object stores provide clear new capabilities for data management
 - Reduce disk requirements
 - More flexibility in defining data tiers
- To fully utilize, much more software development needed
 - New data management service requirement: column tracking
 - Full data schema requires provenance, Runs/LumiSections TTree handling, etc.
- In a prototype, performance and thread scaling very favorable
 - Further scale tests needed (only few GB accessed so far)

