

Comparison with model-independent and dependent analyses for pion charge radius

SATO, Kohei

(University of Tsukuba)

WATANABE, Hiromasa (YITP, Kyoto University) ; YAMAZAKI, Takeshi (University of Tsukuba)

31 July – 4 Aug 2023

LATTICE 2023

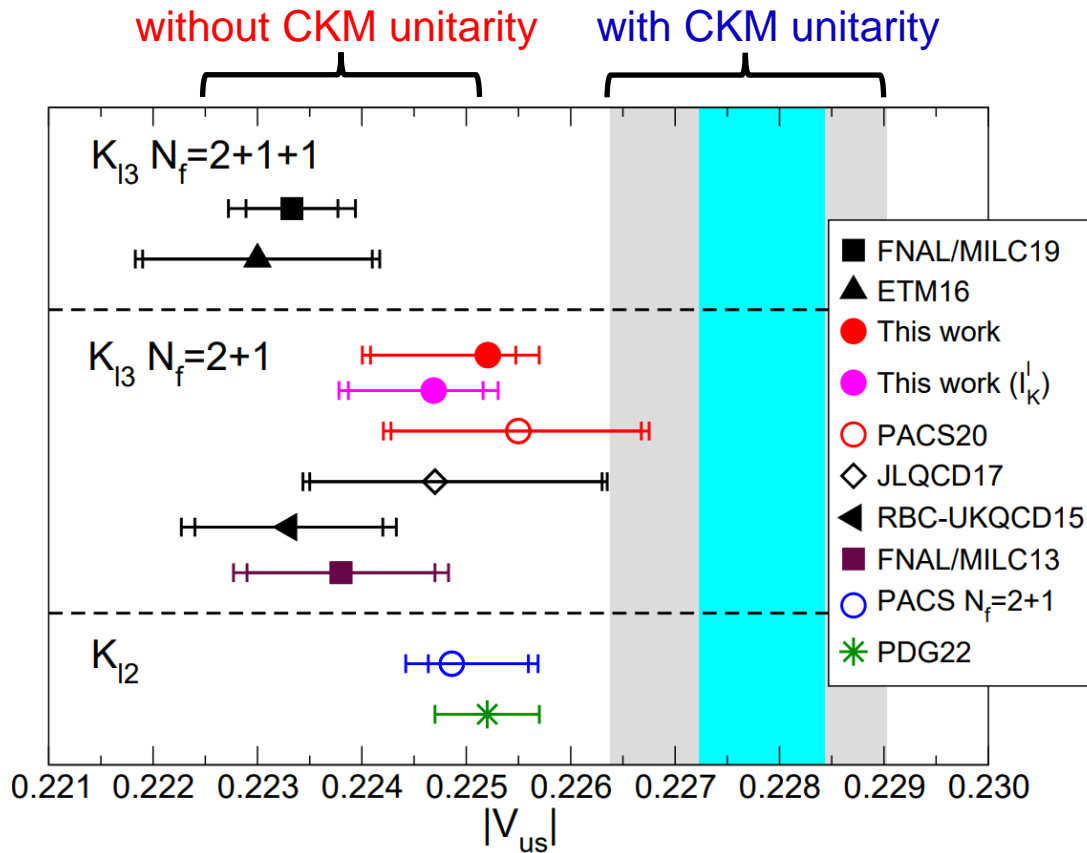
Fermilab

Introduction

Motivation

Recently, precise verification of standard model has been actively studied.

Ex) CKM matrix element $|V_{us}|$



arXiv:2212.00255 [hep-lat]

In the K_{l3} decay $\Gamma_{K_{l3}} = C_{K_{l3}} (|V_{us}| f_+(0))^2 I_K^l$

$\Gamma_{K_{l3}}$ (decay width) = $C_{K_{l3}}$ (known values) $(|V_{us}| f_+(0))^2$ (known values) I_K^l (known values)
 (Experimental value) = (Known constant) \times (Matrix element) \times (Hadron matrix element)
 (Matrix element) and (Hadron matrix element) are not known values.
 (Hadron matrix element) is obtained using lattice QCD calculations.

- decay width
- known values
- Fermi coupling constant
- Kaon mass and so on
- Form factor
- Obtained using lattice QCD calculations
- CKM matrix element $|V_{us}|$

For precise verification

- Reduce the (systematic+statistic) error
- Multiple groups calculate in different methods

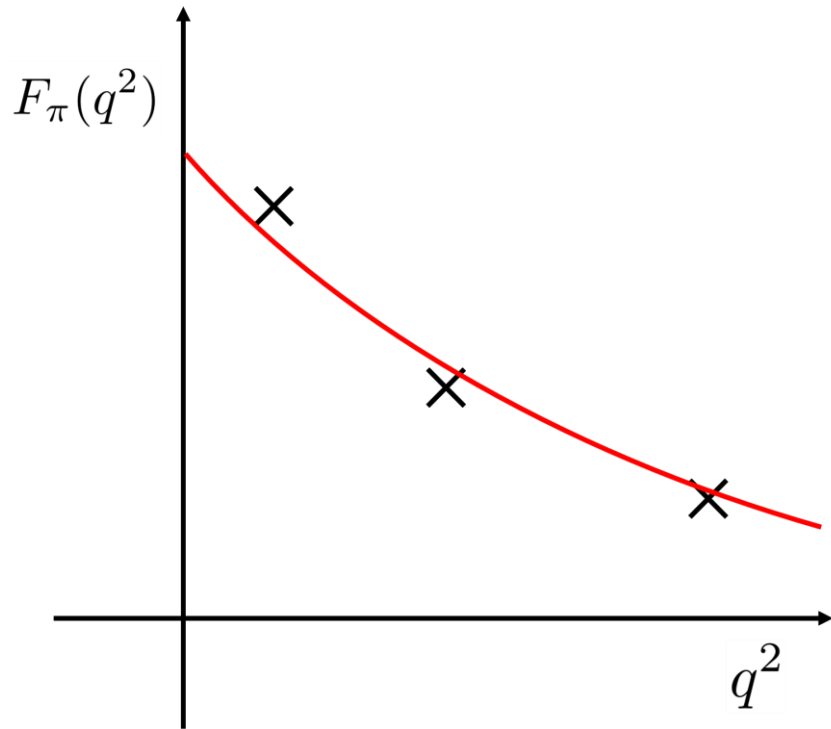
➔ New algorithm development is important.

Introduction

$$\Gamma_{K_{l3}} = C_{K_{l3}} (|V_{us}| \underline{f_+(0)})^2 I_K^l$$

○ Traditional method for **form factor**

The form factor analysis is performed by Making $(q^2, F_\pi(q^2))$ data and fitting it.



$$F_\pi(q^2) = \frac{1}{1 + q^2/M_{\text{pole}}^2} \quad (\text{monopole})$$

$$F_\pi(q^2) = 1 + f_1 q^2 + f_2 (q^2)^2 \quad (\text{polynomial})$$

$$F_\pi(q^2) = 1 + f_1 q^2 + f_2 (q^2)^2 + f_3 (q^2)^3$$

$$F_\pi(q^2) = \sum_{k=0}^2 a_k z^k \quad \left(z := \frac{\sqrt{4m_\pi^2 + q^2} - \sqrt{4m_\pi^2}}{\sqrt{4m_\pi^2 + q^2} + \sqrt{4m_\pi^2}} \right) \quad (\text{z-expansion})$$



These fit ansatz { causes the **systematic error**
increase the lattice QCD error

fit ansatz
(model-dependent)

$$F_\pi(q^2) = \frac{2E_\pi(p)Z_\pi(0)}{(E_\pi(p) + m_\pi)Z_\pi(p)} \frac{\tilde{C}_{\pi V\pi}(t, t_{\text{sink}}; p)}{\tilde{C}_{\pi V\pi}(t, t_{\text{sink}}; 0)} e^{(E_\pi(p) - m_\pi)t}$$

3-point function: $\tilde{C}_{\pi V\pi}(t, t_{\text{sink}}; p) = Z_V \sum_{\vec{x}, \vec{y}, \vec{z}} \langle 0 | \pi^+(\vec{z}, t_{\text{sink}}) V_4(\vec{y}, t) \pi^{+\dagger}(\vec{x}, 0) | 0 \rangle e^{ip(x_1 - y_1)}$

Introduction

○ Pion charge radius

electromagnetic
form factor

charge radius:

$$\langle \pi^+(p_f) | V_\mu | \pi^+(p_i) \rangle = (p_f + p_i)_\mu \underline{F_\pi(q^2)}$$

$$\langle r_\pi^2 \rangle = -6 \left. \frac{d}{dq^2} F_\pi(q^2) \right|_{q^2=0}$$

○ Phys.Lett.B324,85(1994) ○ Nucl.Phys.B444,401(1995) ○ PoS LATTICE2016,170(2016)

- Proposed **method for directly calculating the first-order derivative** of the form factor
- Applied to calculate nucleon form factor

↓ improve

○ Phys.Rev.D101,051502(R)(2020)

- Applied to calculate **pion charge radius**
- Proposed method to reduce the high-order contamination.

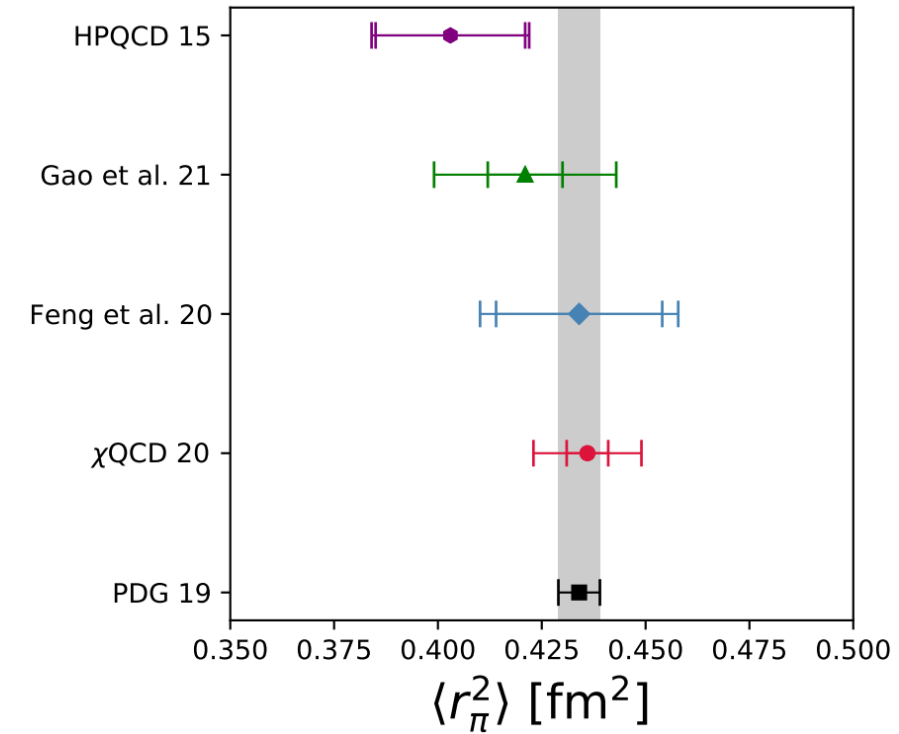
↓ Improve(Our work last year)

○ PoS LATTICE2022,122 (2023)

- Found that large **finite volume effect** in small M_{pole}^2 and volume.
- Proposed method to solve the above problem.

↓ This talk:

Efficient way to reduce the finite volume effect of **original model-independent method** for pion charge radius



Phys.Rev.D104,114515(2021)

model-independent

Outline

- ◆ Introduction
- ◆ Model-independent method
 - Original model-independent method
- ◆ Our improved model-independent method
 - Proposal for our method
 - Introduce new function $G(q^2)$ to reduce the finite volume effect
- ◆ Preliminary result
 - Compare the results of Traditional method, Original method and Our method
- ◆ Summary

model-independent method

Phys.Lett.B324,85(1994) ; Nucl.Phys.B444,401(1995) ; PoS LATTICE2016,170(2016)

$$\tilde{C}_{\pi V \pi}(t, t_{\text{sink}}; p) = Z_V Z_\pi(0) Z_\pi(p) L^2 \frac{(E_\pi(p) + m_\pi)}{2m_\pi 2E_\pi(p)} F_\pi(q^2) e^{-E_\pi(p)t} e^{-m_\pi(t_{\text{sink}}-t)}$$

For $a \rightarrow 0$ and $V \rightarrow \infty$

$$\left. \frac{d\tilde{F}(\vec{p})}{d|\vec{p}|^2} \right|_{|\vec{p}|^2=0} = \frac{d}{d|\vec{p}|^2} \int d^3x F(\vec{x}) e^{-i\vec{p}\cdot\vec{x}} \Big|_{|\vec{p}|^2=0} \overset{F(\vec{x}) = F(|\vec{x}|)}{\curvearrowright} = -\frac{1}{3!} \int d^3x |\vec{x}|^2 F(\vec{x})$$

n -th order momentum-derivative at $|\vec{p}|^2 = 0$ \longleftrightarrow $2n$ -th order spatial moment ($|\vec{x}|^{2n}$)

For finite V , the higher-order contaminations appear.

1-dimension 3-point function

$$C_{\pi V \pi}(t, t_{\text{sink}}; r) := Z_V \sum_{\vec{z}} \sum_{y_2, y_3} \sum_{x_2, x_3} \langle 0 | \pi^+(\vec{z}, t_{\text{sink}}) V_4(\vec{y}, t) \pi^{+\dagger}(\vec{x}, 0) | 0 \rangle$$

$(r := |x_1 - y_1|; 0 \leq r \leq L/2; \text{Periodic B.C.})$

$$C^{(n)}(t) := \sum_r r^{2n} C_{\pi V \pi}(t, t_{\text{sink}}; r) = \sum_r r^{2n} \frac{1}{L} \sum_p \tilde{C}_{\pi V \pi}(t, t_{\text{sink}}; p) e^{ipr}$$

$$= \sum_p \Delta(t, t_{\text{sink}}, p) T_n(p) F_\pi(q^2) \quad \left(\tilde{C}_{\pi V \pi}(t, t_{\text{sink}}; p) = \Delta(t, t_{\text{sink}}, p) F_\pi(q^2), \quad T_n(p) := \frac{1}{L} \sum_r r^{2n} e^{ipr} \right)$$

$$= f_0 \beta_{0,n}(t) + f_1 \beta_{1,n}(t) + f_2 \beta_{2,n}(t) + \dots \quad \left(F_\pi(q^2) = \sum_{m=0}^{\infty} f_m q^{2m}, \quad \beta_{m,n}(t) := \sum_p \Delta(t, t_{\text{sink}}, p) T_n(p) q^{2m} \right)$$

$\langle r_\pi^2 \rangle = -6 \frac{d}{dq^2} F_\pi(q^2) \Big|_{q^2=0}$
higher-order contamination
known function

model-independent method

Phys.Rev.D101,051502(R)(2020)

$$(C^{(0)}(t) := 1, f_0 = 1)$$

$$\text{moment function } \underline{C^{(n)}(t)} := \sum_r r^{2n} C_{\pi V \pi}(t, t_{\text{sink}}; r) = \sum_{m=0}^{\infty} f_m \beta_{m,n}(t)$$

To reduce the higher-order contamination

$$\text{known function } \underline{\beta_{m,n}(t)} := \sum_p \Delta(t, t_{\text{sink}}, p) T_n(p) q^{2m}$$

$$R(t) := \alpha_1 C^{(1)}(t) + \alpha_2 C^{(2)}(t) + h$$

$$= (\alpha_1 \beta_{0,1} + \alpha_2 \beta_{0,2} + h) + (\alpha_1 \beta_{1,1} + \alpha_2 \beta_{1,2}) f_1 + (\alpha_1 \beta_{2,1} + \alpha_2 \beta_{2,2}) f_2 + \dots$$

Define parameters α_1, α_2, h to satisfy the following

$$\langle r_\pi^2 \rangle = -6 \frac{d}{dq^2} F_\pi(q^2) \Big|_{q^2=0}$$

$$\alpha_1 \beta_{0,1} + \alpha_2 \beta_{0,2} + h = 0 \quad \alpha_1 \beta_{1,1} + \alpha_2 \beta_{1,2} = 1 \quad \alpha_1 \beta_{2,1} + \alpha_2 \beta_{2,2} = 0$$

→ $R(t) = \underbrace{f_1}_{\text{constant}} + \sum_{m=3}^{\infty} \left(\sum_{k=1}^2 \alpha_k \beta_{m,k}(t) \right) \underbrace{f_m}_{\text{time-dependent}}$

$\langle r_\pi^2 \rangle = -6 \frac{d}{dq^2} F_\pi(q^2) \Big|_{q^2=0} \sim -6 \times R(t)$

If the high-order contamination terms is small, we get the charge radius

Our improved model-independent method

PoS LATTICE2022,122(2023)

$$R(t) = f_1 + \sum_{m=3}^{\infty} \left(\sum_{k=1}^2 \alpha_k \beta_{m,k}(t) \right) f_m$$

Original method remains the **contamination from high-order** at small M_{pole}^2 and volume.

 Improve the convergence of f_m
and reduce the contamination

-- Fact --
Pion form factor is well represented by

$$F_{\pi}(q^2) = \frac{1}{1 + q^2/M_{\text{pole}}^2}$$

from phenomenology.

$$\begin{aligned} C^{(n)}(t) &= \sum_p \Delta(t, t_{\text{sink}}, p) T_n(p) F_{\pi}(q^2) = \sum_p \Delta(t, t_{\text{sink}}, p) T_n(p) F_{\pi}(q^2) \frac{G(q^2)}{G(q^2)} \\ &= \sum_p \Delta(t, t_{\text{sink}}, p) T_n(p) S(q^2) \frac{1}{G(q^2)} \quad (S(q^2) := F_{\pi}(q^2)G(q^2)) \\ &= \sum_m s_m \tilde{\beta}_{m,n}(t) \left(S(q^2) = \sum_m s_m q^{2m}, \quad \tilde{\beta}_{m,n}(t) := \sum_p \Delta(t, t_{\text{sink}}, p) T_n(p) q^{2m} / G(q^2) \right) \end{aligned}$$

Original model-independent method changes to $R(t) = s_1 + \sum_{m=3}^{\infty} \left(\sum_{k=1}^2 \alpha_k \tilde{\beta}_{m,k}(t) \right) s_m$

 Change $F_{\pi}(q^2)$ to $S(q^2)$ and choose $G(q^2)$ with good convergence s_m

What is the good function $G(q^2)$?

$$R(t) = s_1 + \sum_{m=3}^{\infty} \left(\sum_{k=1}^2 \alpha_k \tilde{\beta}_{m,k}(t) \right) s_m$$

The function $G(q^2)$ is arbitrary.

➡ Temporarily, we assume that the **form factor** is monopole form to see the convergence of s_m .

$$F_{\pi}(q^2) = \frac{1}{1 + q^2/M_{\text{pole}}^2} = \sum_{m=0}^{\infty} \left(-\frac{1}{M_{\text{pole}}^2} \right)^m q^{2m}$$

$$G(q^2) = 1 + \sum_{m=1} g_m q^{2m}$$

$$S(q^2) := F_{\pi}(q^2)G(q^2)$$



$$s_0 = 1$$

$$s_m = \left(-\frac{1}{M_{\text{pole}}^2} \right) s_{m-1} + g_m \quad (m \geq 1)$$

original method

If $G(q^2) = 1$

$$s_m \sim \mathcal{O} \left(\left(-\frac{1}{M_{\text{pole}}^2} \right)^m \right)$$

Ex.1) polynomial (dim=2)

$$G(q^2) = 1 + g_1 q^2 + g_2 q^4$$

$$s_m = \left(-\frac{1}{M_{\text{pole}}^2} \right) s_{m-1} \quad (m \geq 3)$$

How to determine parameters g_1, g_2

➡ satisfy $s_2 = 0$

- High-order coefficient s_m exactly disappear.

Ex.2) Log function

$$G(q^2) = 1 + g'_1 \log(1 + g'_2 q^2) = 1 + \sum_{m=1} \frac{-(-g'_2)^m}{m} g'_1 q^{2m}$$

$$s_m \sim \mathcal{O} \left(\left(-\frac{1}{M_{\text{pole}}^2} \right)^{m-2} g'^2_2 \right)$$

- Convergence is Improved from **m-th** power to **(m-2)-th** power.
- Convergence can be adjusted by g'_2 .

How to determine parameters g'_1, g'_2 ➡ satisfy $s_2 = 0$

We can reduce the influence of high-order coefficient (contamination) with the function $G(q^2)$.

Simulation details

■ gauge configuration ([Phys. Rev. D 86, 074514 \(2012\)](#))

- $L^3 \times T = 32^3 \times 48$, $a^{-1} = 2.194 \text{ GeV} \rightarrow a = 0.08995 \text{ fm}$, $L = 2.9 \text{ fm}$
- $m_\pi = 0.51 \text{ GeV}$, $(\kappa_{ud}, \kappa_s) = (0.1373316, 0.1367526)$
- $N_f = 2 + 1$, Iwasaki gauge + $\mathcal{O}(a)$ -improved Wilson quark
- $\beta = 1.90$, $c_{\text{SW}} = 1.715$, $t_{\text{sink}} = 22$

■ measurement parameter

- 80 configurations, 50 traj. each
- 16 sources \times 3 directions (x, y, z) \times 4 random sources = 192 meas. per config.
- bin size: 100 traj.

 We obtain the charge radius and compare the traditional, original and our method.

Preliminary result

○ Traditional method

Now, we use 4 forms as fit ansatz.

$$F_\pi(q^2) = \frac{1}{1 + q^2/M_{\text{pole}}^2} \quad (\text{monopole})$$

$$F_\pi(q^2) = 1 + f_1 q^2 + f_2 (q^2)^2 \quad (\text{polynomial})$$

$$F_\pi(q^2) = 1 + f_1 q^2 + f_2 (q^2)^2 + f_3 (q^2)^3$$

$$F_\pi(q^2) = \sum_{k=0}^2 a_k z^k \quad \left(z := \frac{\sqrt{4m_\pi^2 + q^2} - \sqrt{4m_\pi^2}}{\sqrt{4m_\pi^2 + q^2} + \sqrt{4m_\pi^2}} \right) \quad (\text{z-expansion})$$

▪ Central value

Weighted mean for 4 forms

▪ Statistic error

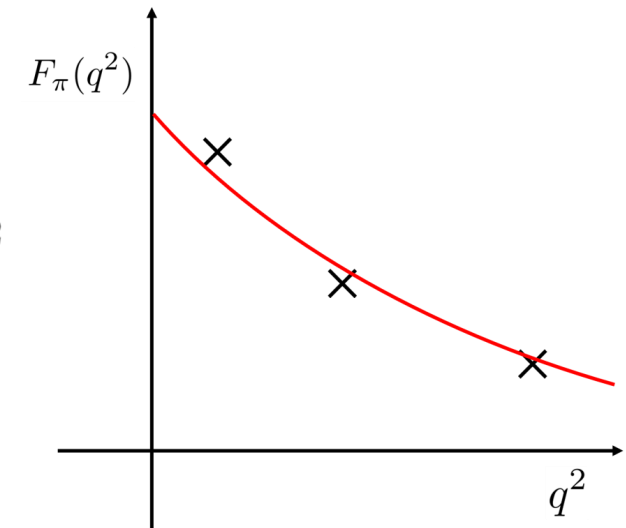
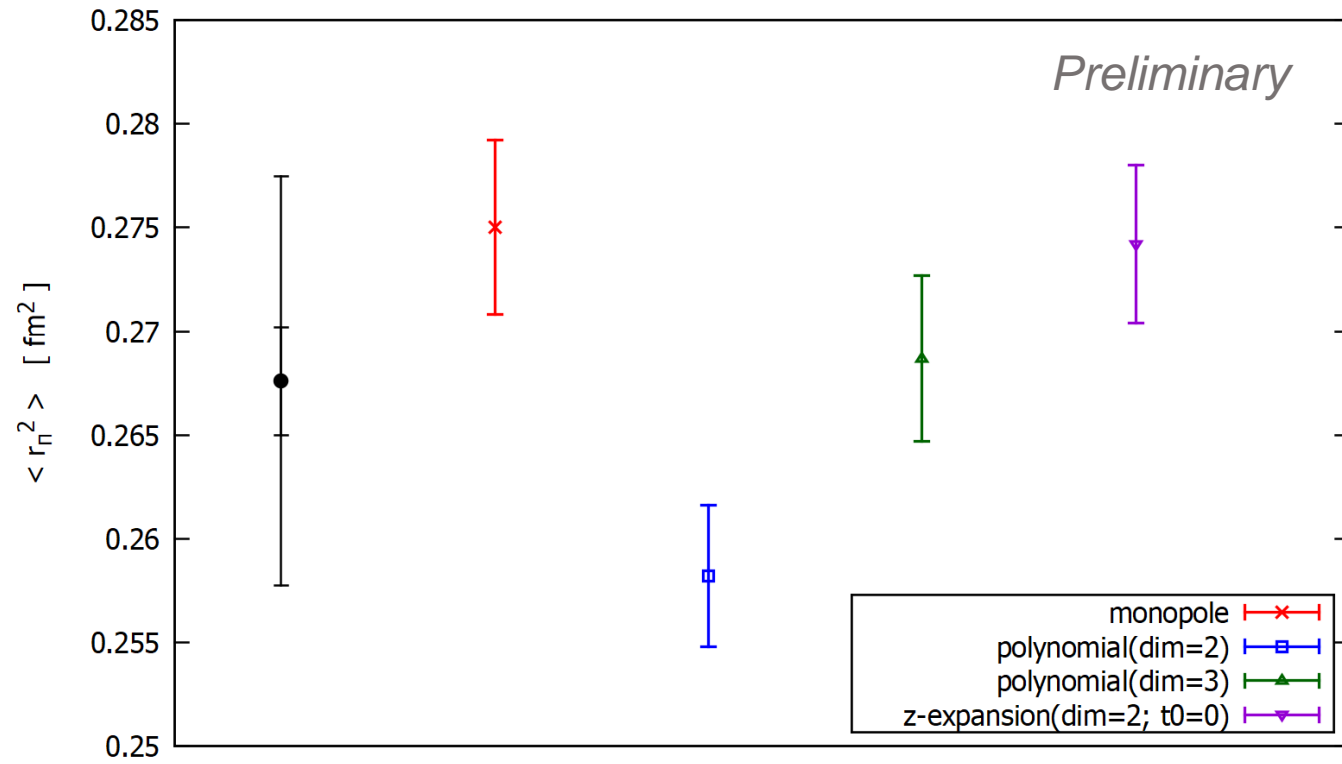
Jackknife error of the **central value**

▪ Systematic error

Maximum difference between the **central value** and **value on each form**

$$\Rightarrow \langle r_\pi^2 \rangle_{\text{Trad.}} = 0.2676(26)(95) \text{ fm}^2$$

Central(Stat.) (Sys.)



Preliminary result

○ Model-independent method

Ex.1) polynomial (dim=2)

$$G(q^2) = 1 + g_1 q^2 + g_2 q^4$$

Now, we consider the sufficiently large g_1 region ($g_1 = -5f_1, 0, 5f_1$).

Estimated from traditional method

➡ Evaluate the systematic error of g_1

g_2 is determined to satisfy $s_2 = 0$

$$R(t) = s_1 + \sum_{m=3}^{\infty} \left(\sum_{k=1}^2 \alpha_k \tilde{\beta}_{m,k}(t) \right) s_m \quad \left[\quad R(t) = s_2 + \sum_{m=3}^{\infty} \left(\sum_{k=1}^2 \alpha'_k \tilde{\beta}_{m,k}(t) \right) s_m \quad \right]$$

• Central value

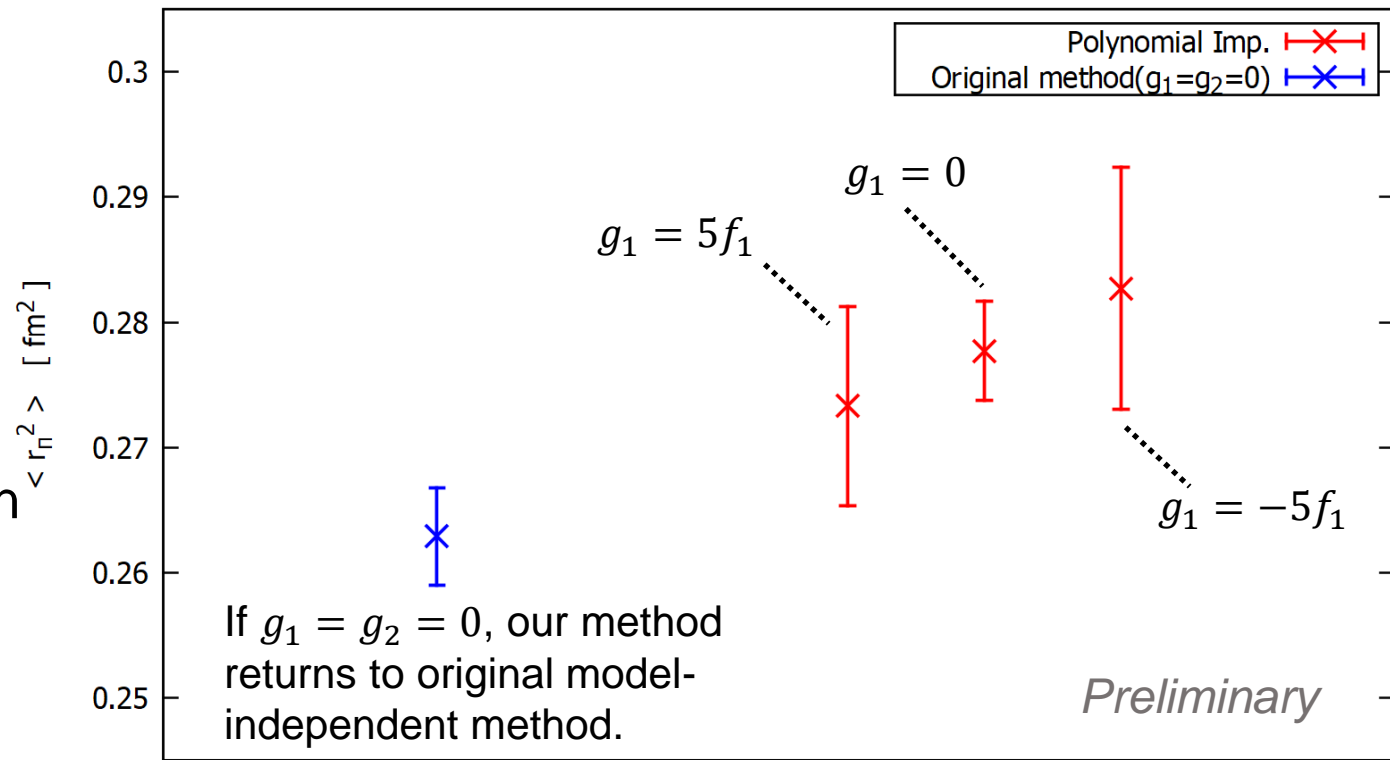
Result value at $g_1 = 0$

• Statistic error

Jackknife error of the central value

• Systematic error

Maximum difference between the central value and Result value at $g_1 = 5f_1$ or $g_1 = -5f_1$



$$\langle r_\pi^2 \rangle_{\text{Original}} = 0.2629(39) \text{ fm}^2 \quad \text{Central (Stat.)}$$

$$\langle r_\pi^2 \rangle_{\text{PolynomialImp.}} = 0.2777(39)(50) \text{ fm}^2 \quad \text{Central (Stat.) (Sys.)}$$

Preliminary result

○ Model-independent method

Ex.2) Log function

$$G(q^2) = 1 + g_1' \log(1 + g_2' q^2) = 1 + \sum_{n=1} \frac{-(-g_2')^n}{n} g_1' q^{2n}$$

Now, we consider the sufficiently large g_2' region.

➡ Evaluate the systematic error of g_2'

g_1' is determined to satisfy $s_2 = 0$

$$R(t) = s_1 + \sum_{m=3}^{\infty} \left(\sum_{k=1}^2 \alpha_k \tilde{\beta}_{m,k}(t) \right) s_m \quad \left[\quad R(t) = s_2 + \sum_{m=3}^{\infty} \left(\sum_{k=1}^2 \alpha'_k \tilde{\beta}_{m,k}(t) \right) s_m \quad \right]$$

➡ If g_2' is sufficiently small, the charge radius is constant.



We can control the high-order contamination (Systematic error).

▪ Central value

Result value at $g_2' = 1$

▪ Statistic error

Jackknife error of the central value

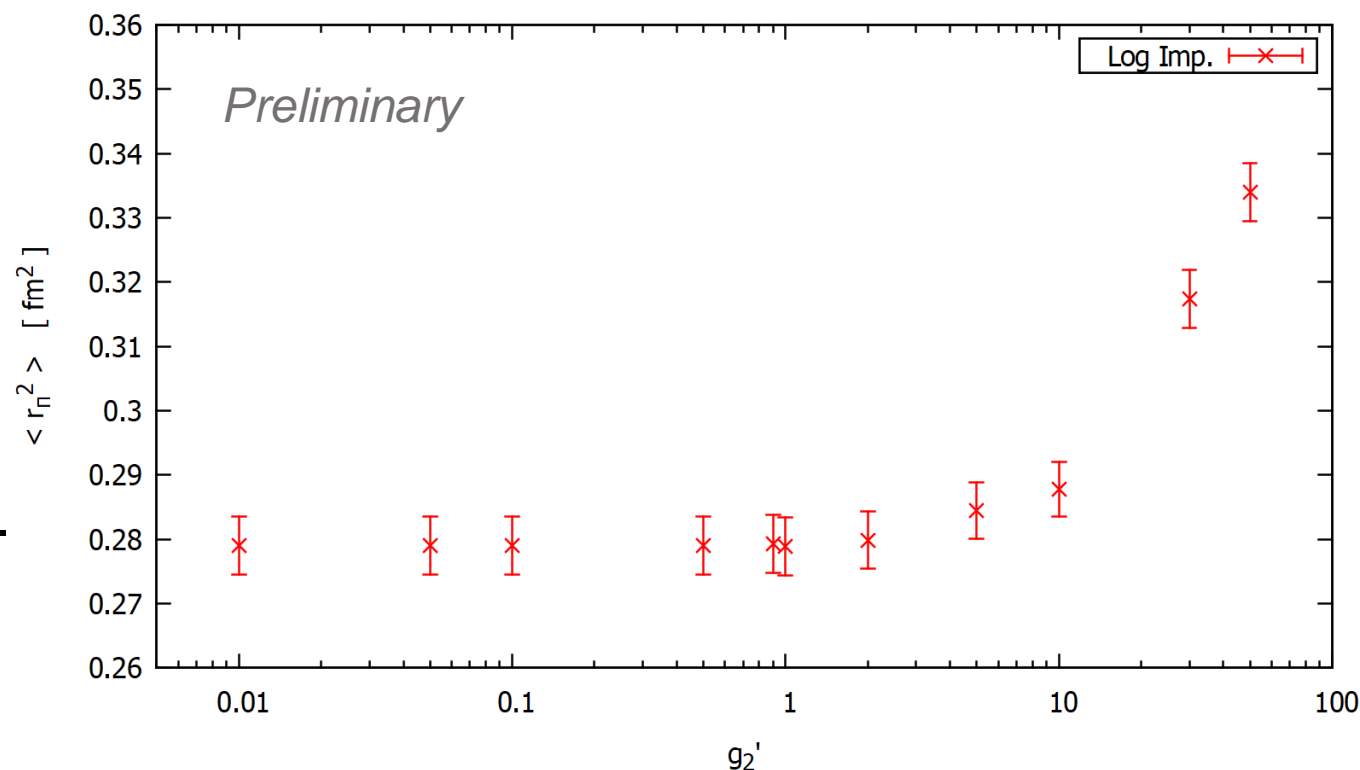
▪ Systematic error

We consider it to be almost zero.

($\because \langle r_\pi^2 \rangle = \text{const. at } g_2' \leq 1$)

➡ $\langle r_\pi^2 \rangle_{\text{LogImp.}} = 0.2789(45)(0) \text{ fm}^2$
 Central(Stat.)(Sys.)

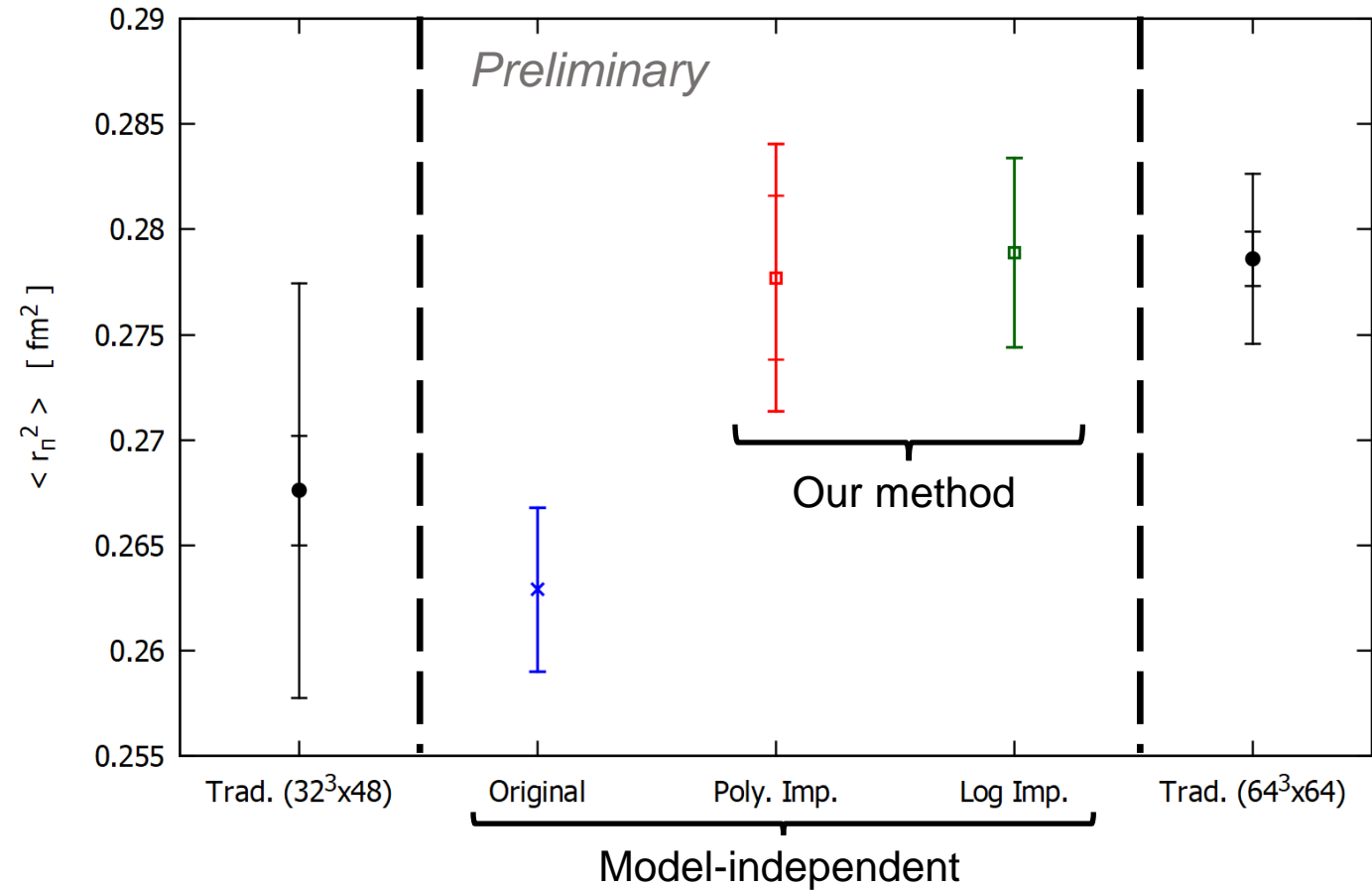
$$s_m \sim \mathcal{O} \left(\left(-\frac{1}{M_{\text{pole}}^2} \right)^{m-2} g_2'^2 \right)$$



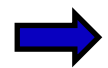
Preliminary result

$$\left\{ \begin{array}{l} \langle r_\pi^2 \rangle_{\text{Traditional}} = 0.2676(26)(95)\text{fm}^2 \\ \langle r_\pi^2 \rangle_{\text{Original}} = 0.2629(39)\text{fm}^2 \\ \langle r_\pi^2 \rangle_{\text{PolynomialImp.}} = 0.2777(39)(50)\text{fm}^2 \\ \langle r_\pi^2 \rangle_{\text{LogImp.}} = 0.2789(45)(0)\text{fm}^2 \end{array} \right.$$

Central(Stat.)(Sys.)

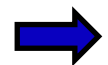


- The model-independent method's error is smaller than the traditional method's error.



Model-independent method does not have the error from fit ansatz.

- There is a difference between the original method and our method.



Our method can suppress the finite volume effect.

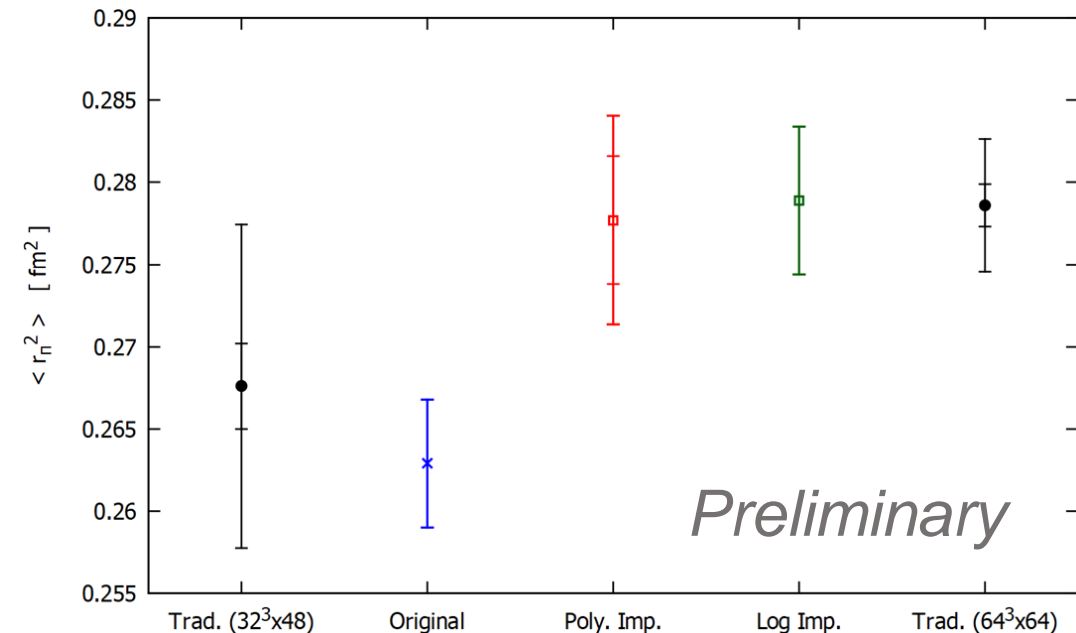
(∵ Our method is consistent with large volume result)

Summary

- ◆ We discuss improvement of model independent method to obtain the pion charge radius.
- ◆ We propose our method which reduces the high-order contribution included in the original model-independent method.
- ◆ We show the arbitrariness of the appropriate function $G(q^2)$ and examples of parameter settings.
- ◆ We apply the method to actual lattice QCD data and find that the error (statistics + systematic) was smaller than the traditional method.

Future works

- ◆ Analysis by various functions $G(q^2)$
- ◆ Analysis at various m_π, a, V
- ◆ Analysis at physical point
- ◆ Analysis with other particles such as K_{l3}
- ◆ Other methods (direct fit, etc.)



backup

Relationship between momentum-derivative and spatial moment

$$\begin{aligned}
 \left. \frac{d\tilde{F}(\vec{p})}{d|\vec{p}|^2} \right|_{|\vec{p}|^2=0} &= \left. \frac{d}{d|\vec{p}|^2} \int d^3x F(\vec{x}) e^{-i\vec{p}\cdot\vec{x}} \right|_{|\vec{p}|^2=0} \\
 &= \left. \frac{d}{d|\vec{p}|^2} \int d|\vec{x}| d(\cos\theta) d\phi |\vec{x}|^2 F(|\vec{x}|) e^{-i|\vec{p}||\vec{x}| \cos\theta} \right|_{|\vec{p}|^2=0} \quad (\text{if } F(\vec{x}) := F(|\vec{x}|)) \\
 &= \left. \frac{d}{d|\vec{p}|^2} \int d|\vec{x}| d\phi |\vec{x}|^2 F(|\vec{x}|) \frac{1}{-i|\vec{p}||\vec{x}|} \left[e^{-i|\vec{p}||\vec{x}| \cos\theta} \right]_{\cos\theta=-1}^1 \right|_{|\vec{p}|^2=0} \\
 &= \left. \frac{d}{d|\vec{p}|^2} \int d|\vec{x}| d\phi |\vec{x}|^2 F(|\vec{x}|) \times 2 \frac{\sin(|\vec{p}||\vec{x}|)}{|\vec{p}||\vec{x}|} \right|_{|\vec{p}|^2=0} \\
 &= \left. \frac{d}{d|\vec{p}|^2} \int d|\vec{x}| d(\cos\theta) d\phi |\vec{x}|^2 F(\vec{x}) \frac{1}{|\vec{p}||\vec{x}|} \sum_{n=0}^{\infty} (-1)^n \frac{(|\vec{p}||\vec{x}|)^{2n+1}}{(2n+1)!} \right|_{|\vec{p}|^2=0} \\
 &= \left. \frac{d}{d|\vec{p}|^2} \int d^3x F(\vec{x}) \sum_{n=0}^{\infty} (-1)^n \frac{(|\vec{p}||\vec{x}|)^{2n}}{(2n+1)!} \right|_{|\vec{p}|^2=0} \\
 &= \left. \int d^3x F(\vec{x}) \sum_{n=0}^{\infty} (-1)^n \frac{n|\vec{p}|^{2(n-1)} |\vec{x}|^{2n}}{(2n+1)!} \right|_{|\vec{p}|^2=0} \\
 &= -\frac{1}{3!} \int d^3x |\vec{x}|^2 F(\vec{x})
 \end{aligned}$$

Why consider a small M_{pole}^2 ?

$$\text{Monopole form : } F(q^2) = \frac{1}{1 + \frac{\langle r_{\pi}^2 \rangle}{6} q^2}$$

To consider on a lattice, Nondimensionalizing the form factor using lattice spacing a

$$F(q^2) = \frac{1}{1 + \frac{\langle r_{\pi}^2 \rangle}{6a^2} (aq)^2}$$

$$\xrightarrow{a \rightarrow 0} M_{\text{pole}}^2 = \frac{6a^2}{\langle r_{\pi}^2 \rangle} \rightarrow 0$$

s_m relationship

$$F(x) = \frac{1}{1 + Ax} = \sum_m f_m x^m, \quad G(x) = 1 + g_1 x + g_2 x^2, \quad S(x) = F(x)G(x) = \sum_m s_m x^m$$

For $m \geq 2$

$$\begin{aligned} s_m &= \frac{1}{m!} \left. \frac{d^m S}{dx^m} \right|_{x=0} = \frac{1}{m!} \left\{ \sum_{k=0}^m \frac{m!}{k!(m-k)!} F^{(m-k)} G^{(k)} \right\} \Big|_{x=0} \\ &= \frac{1}{m!} \sum_{k=0}^m \frac{m!}{k!(m-k)!} (m-k)! (-A)^{m-k} G^{(k)} \quad (\because F^{(m)} = m!(-A)^m) \\ &= \sum_{k=0}^m \frac{(-A)^{m-k}}{k!} G^{(k)} = (-A)^m + (-A)^{m-1} g_1 + (-A)^{m-2} g_2 \end{aligned}$$

For $m \geq 3$

$$s_m = (-A) \times \{ (-A)^{m-1} + (-A)^{m-2} g_1 + (-A)^{m-3} g_2 \} = (-A) s_{m-1}$$

Other methods

$$\underbrace{C^{(n)}(t)}_{\text{moment function}} := \sum_r r^{2n} C_{\pi V \pi}(t, t_{\text{sink}}; r) = \sum_{m=0}^{\infty} f_m \beta_{m,n}(t)$$

- Direct fit (moment 3-point function)

$$C^{(n)}(t) = \sum_p \Delta(t, t_{\text{sink}}, p) T_n(p) F_{\pi}(q^2) = \sum_p \Delta(t, t_{\text{sink}}, p) T_n(p) F_{\pi}(q^2) \frac{G(q^2)}{G(q^2)}$$

Input data
(LQCD data)

$$= \sum_p \Delta(t, t_{\text{sink}}, p) T_n(p) S(q^2) \frac{1}{G(q^2)} \quad (S(q^2) := F_{\pi}(q^2)G(q^2), \quad G(q^2) := 1 + g_1 q^2 + g_2 q^4)$$

$$= \sum_m s_m \tilde{\beta}_{m,n}(t) \left(S(q^2) = \sum_m s_m q^{2m}, \quad \underbrace{\tilde{\beta}_{m,n}(t)}_{\text{known function}} := \sum_p \Delta(t, t_{\text{sink}}, p) T_n(p) q^{2m} / G(q^2) \right)$$

Parameters Known function curve fitting

- Direct fit (3-point function)

$$C_{\pi V \pi}(t, t_{\text{sink}}; r) := Z_V \sum_{\vec{z}} \sum_{y_2, y_3} \sum_{x_2, x_3} \langle 0 | \pi^+(\vec{z}, t_{\text{sink}}) V_4(\vec{y}, t) \pi^{+\dagger}(\vec{x}, 0) | 0 \rangle$$


$$= \sum_p \Delta(t, t_{\text{sink}}, p) T_r(p) F_{\pi}(q^2) \quad \left(T_r(p) := \frac{1}{L} e^{ipr} \right)$$

$$= \sum_m s_m \tilde{\beta}'_{m,n}(t) \quad \left(\tilde{\beta}'_{m,n}(t) := \sum_p \Delta(t, t_{\text{sink}}, p) T_r(p) q^{2m} / G(q^2) \right)$$

Other methods

- Model-dependent Direct fit (moment 3-point function)

$$\begin{aligned}
 C^{(n)}(t) &= \sum_p \Delta(t, t_{\text{sink}}, p) T_n(p) F_\pi(q^2) \\
 \text{Input data (LQCD data)} &= \sum_p \Delta(t, t_{\text{sink}}, p) T_n(p) \frac{1}{1 + q^2/M_{\text{pole}}^2} \longrightarrow \text{Parameters}
 \end{aligned}$$

 **curve fitting**

- Model-dependent Direct fit (3-point function)

$$\begin{aligned}
 C_{\pi V \pi}(t, t_{\text{sink}}; r) &= \sum_p \Delta(t, t_{\text{sink}}, p) T_r(p) F_\pi(q^2) \\
 &= \sum_p \Delta(t, t_{\text{sink}}, p) T_r(p) \frac{1}{1 + q^2/M_{\text{pole}}^2}
 \end{aligned}$$

How to find the parameter g_1, g_2

$$(C^{(0)}(t) := 1, f_0 = s_0 = 1)$$

- Exhaustive search

$$\text{moment function } \underline{C^{(n)}(t)} := \sum_r r^{2n} C_{\pi V \pi}(t, t_{\text{sink}}; r) = \sum_{m=0}^{\infty} s_m \tilde{\beta}_{m,n}(t)$$

$$R(t) := \alpha_1 C^{(1)}(t) + \alpha_2 C^{(2)}(t) + h$$

$$\text{known function } \underline{\tilde{\beta}_{m,n}(t)} := \sum_p \Delta(t, t_{\text{sink}}, p) T_n(p) q^{2m} / G(q^2)$$

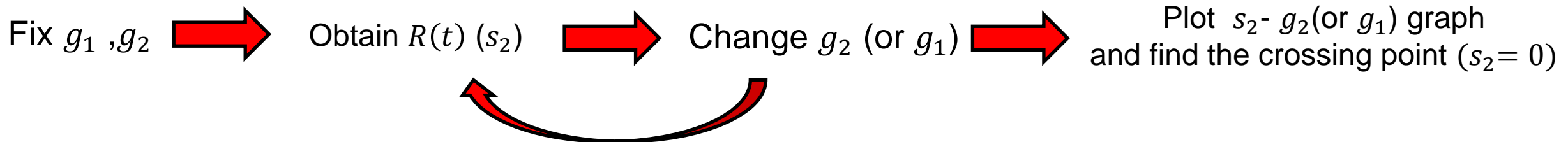
$$= (\alpha_1 \tilde{\beta}_{0,1} + \alpha_2 \tilde{\beta}_{0,2} + h) + (\alpha_1 \tilde{\beta}_{1,1} + \alpha_2 \tilde{\beta}_{1,2}) s_1 + (\alpha_1 \tilde{\beta}_{2,1} + \alpha_2 \tilde{\beta}_{2,2}) s_2 + \dots$$

Define parameters α_1, α_2, h to satisfy the following

$$\alpha_1 \tilde{\beta}_{0,1} + \alpha_2 \tilde{\beta}_{0,2} + h = 0 \quad \alpha_1 \tilde{\beta}_{1,1} + \alpha_2 \tilde{\beta}_{1,2} = 0 \quad \alpha_1 \tilde{\beta}_{2,1} + \alpha_2 \tilde{\beta}_{2,2} = 1$$

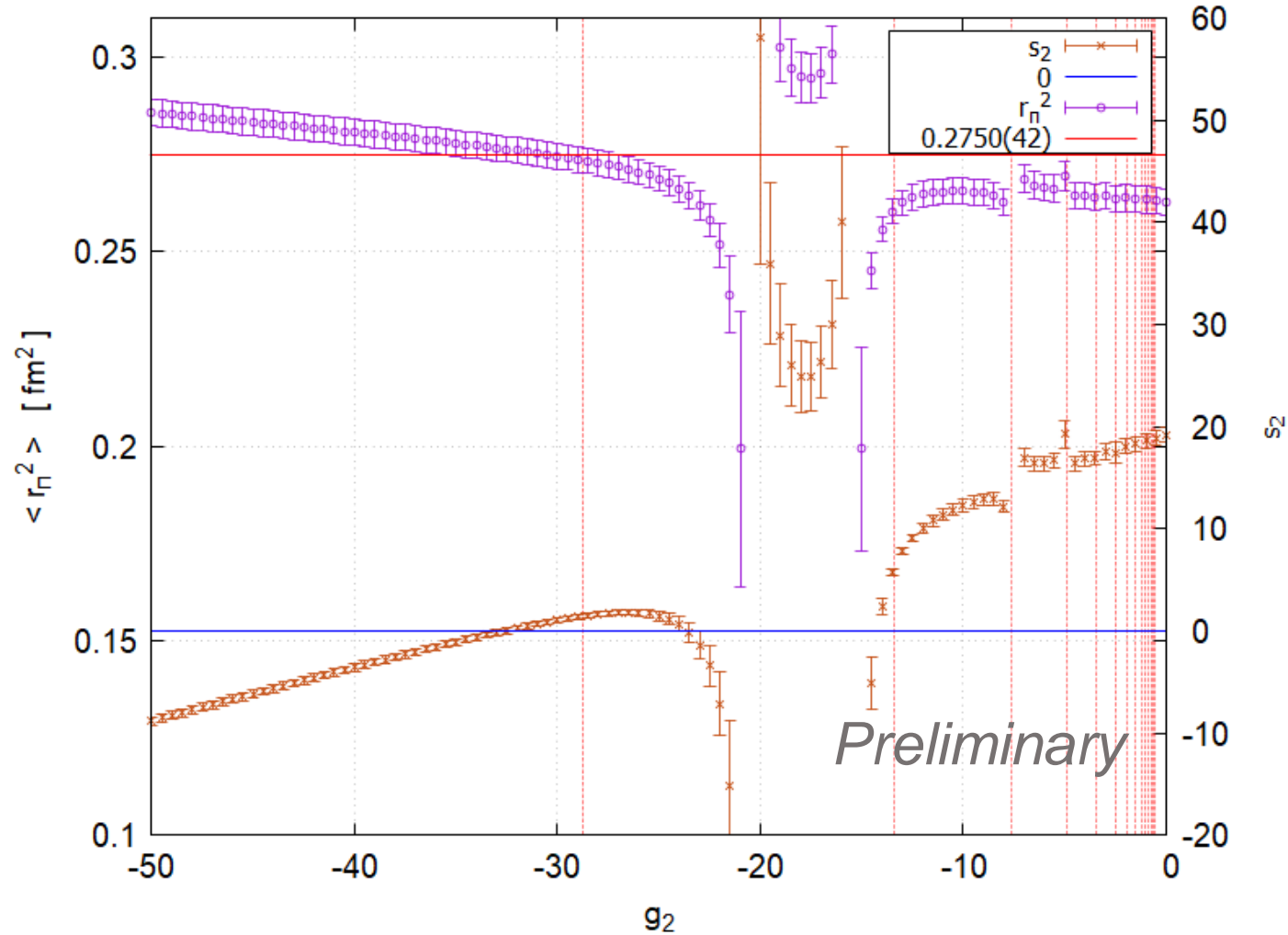
$$\Rightarrow R(t) = s_2 + \sum_{m=3}^{\infty} \left(\sum_{k=1}^2 \alpha_k \tilde{\beta}_{m,k}(t) \right) s_m$$

How to...



How to find the parameter g_1, g_2

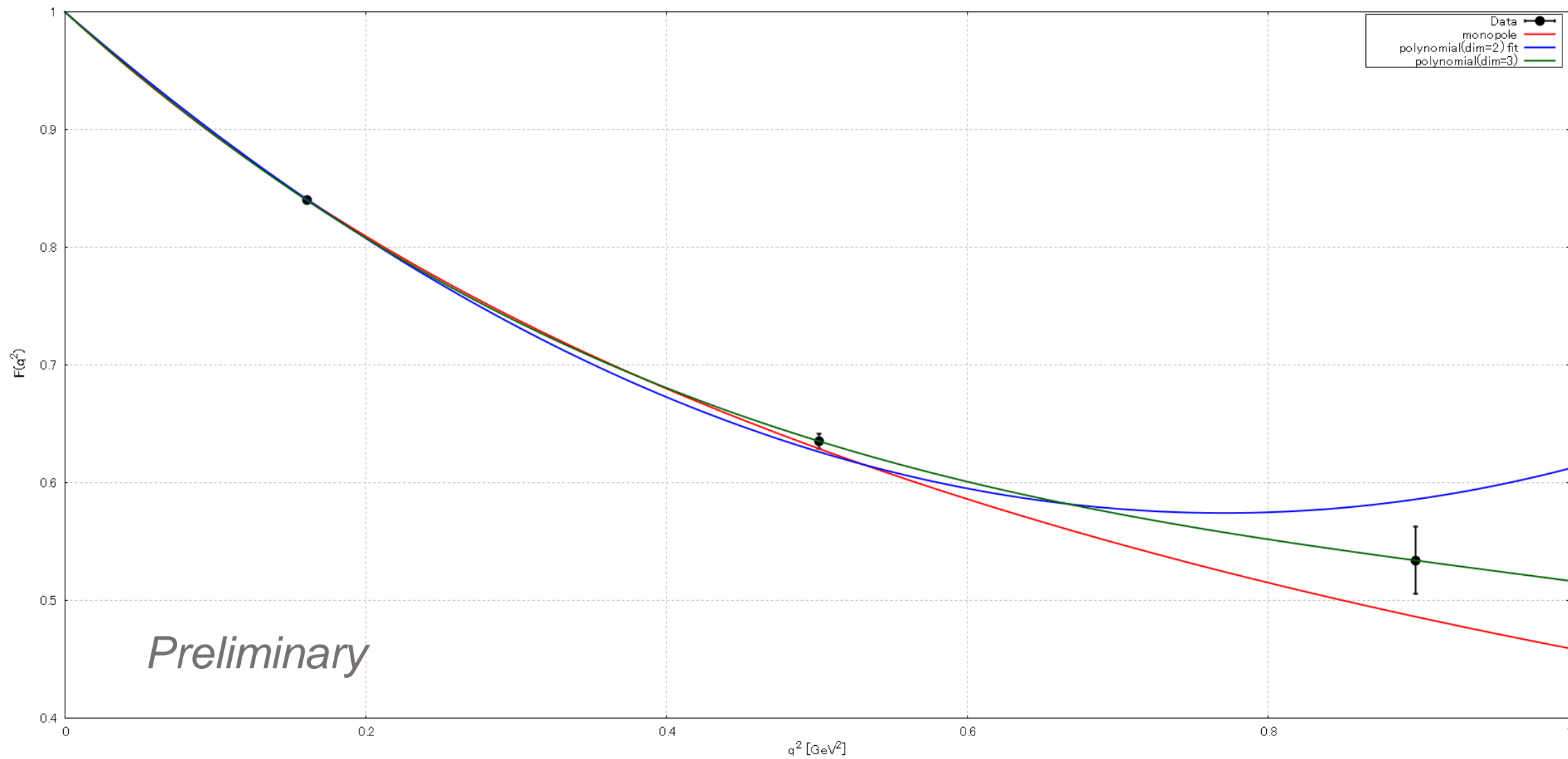
- Method 2 : Exhaustive search



$$\begin{cases} g_1 = 0 \\ g_2 = -32.5 \end{cases}$$

$$\text{known function } \tilde{\beta}_{m,n}(t) := \sum_p \Delta(t, t_{\text{sink}}, p) T_n(p) q^{2m} / G(q^2)$$

Traditional method and Form factor



Model-independent method

$$\langle r_\pi^2 \rangle = -6 \left. \frac{d}{dq^2} F_\pi(q^2) \right|_{q^2=0} \sim -6 \times R(t)$$

$$\langle r_\pi^2 \rangle = -6 \left. \frac{d}{dq^2} F_\pi(q^2) \right|_{q^2=0} \sim -6 \times (R(t) - g_1)$$

