

Methods for Bayesian model averaging



Ethan T. Neil (Colorado) Lattice 2023 @ Fermilab 08/04/23

(image source: me, Fermilab buffalo farm, 2011)

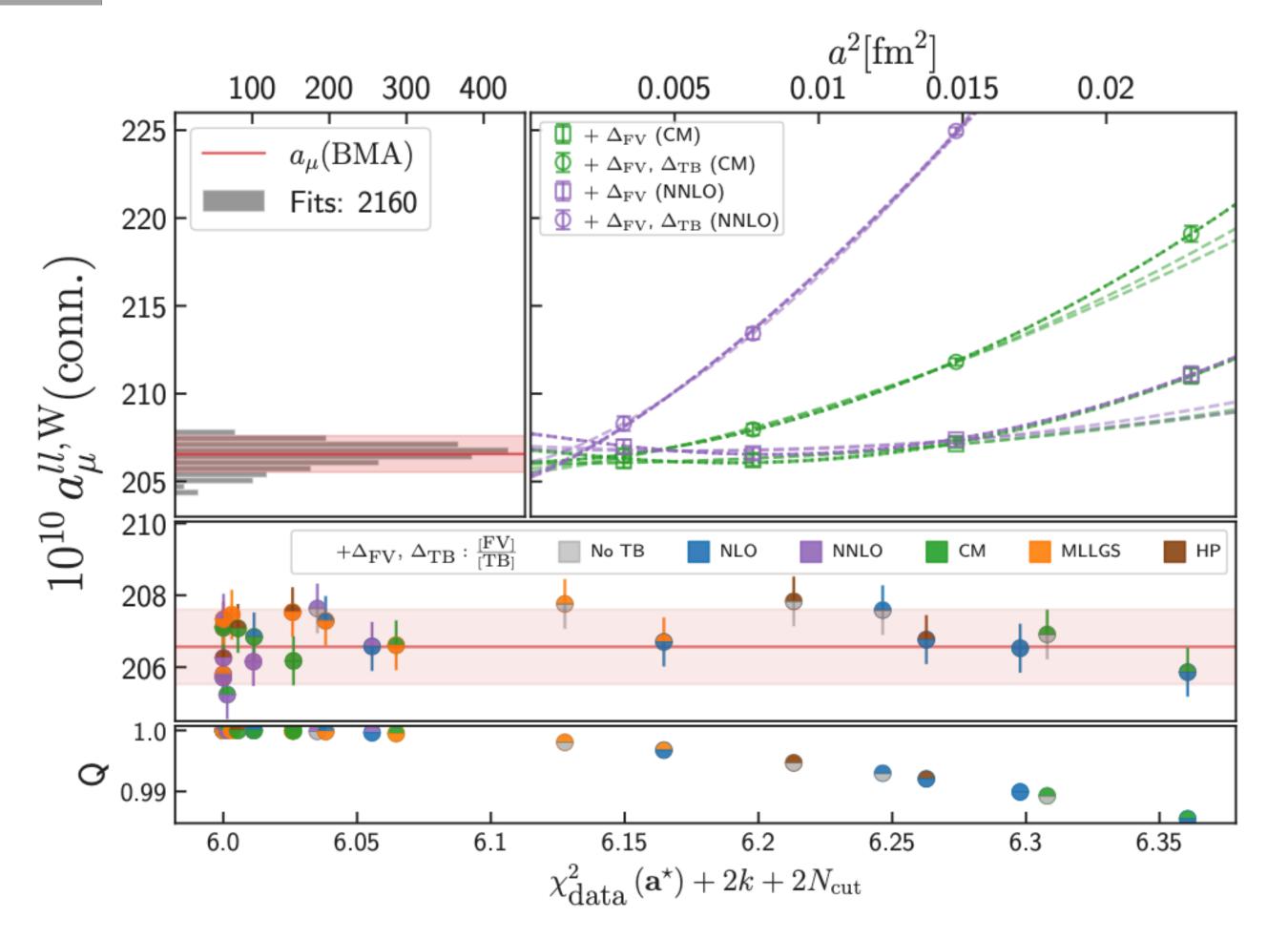


- 1. Why is model averaging useful?
- 2. Model averaging basics
- 3. Improved information criteria (arXiv:2208.14983)
- 4. Data subset selection what penalty? (arXiv:**2305.19417**)

Outline

Bayesian model averaging

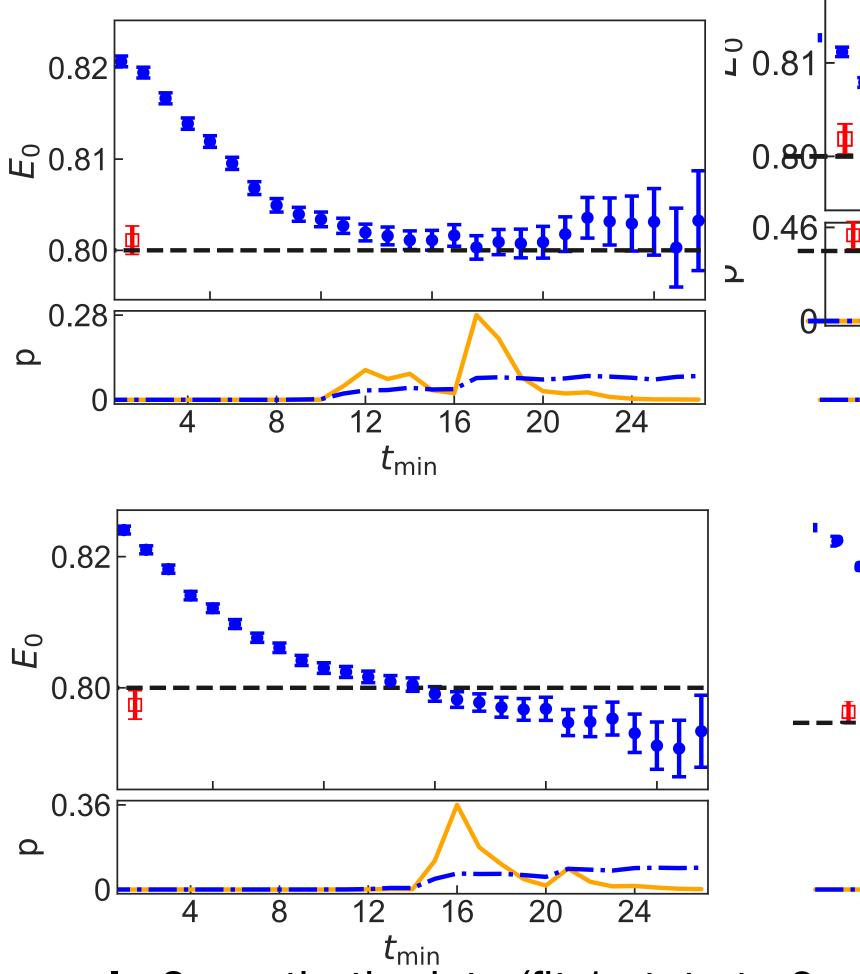
(Fermilab/HPQCD/MILC collaborations, arXiv:2301.0874)



- Example 1: (g-2) HVP intermediate window (see talk by S. Lahert, Tue @ 2:10 PM
- •2160 fit variations discretization, finite volume, mass corrections...model average gives a final combined estimate + error bar.

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- Example 2: synthetic data (fit 1 state to 2-state model truth.)
- Instead of selecting t_{min} by hand, compute model probability for each choice and average together! (Data cuts as model choice.)

Bayesian model averaging

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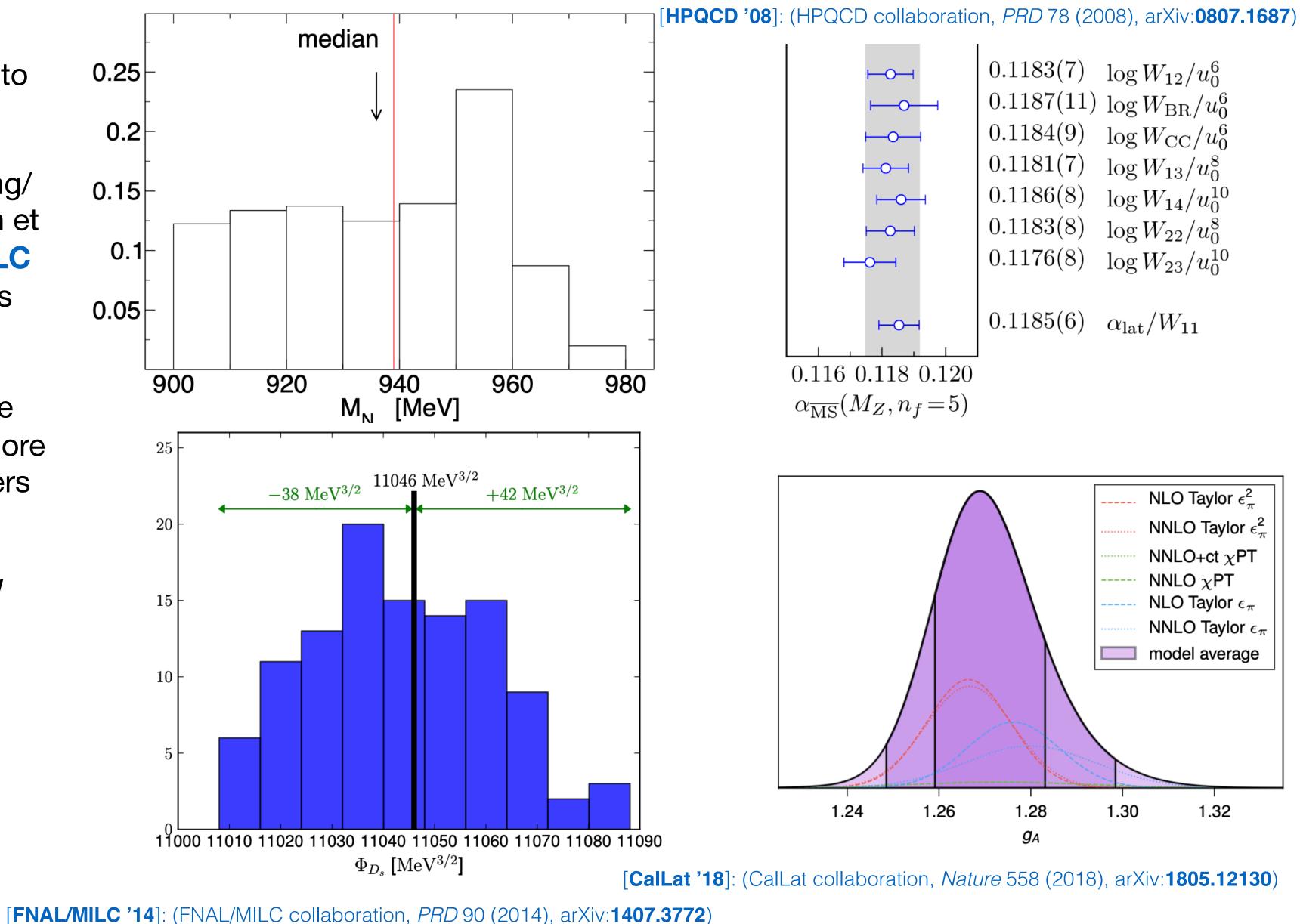
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• <u>Some history</u>: we didn't bring model averaging to lattice, we "added the B" (Bayesian MA), found new ICs, and tried to clarify statistical derivations/details.

- Several early variations of model averaging/ variation appear in lattice papers: Y. Chen et al. '04, BMW '08, HPQCD '08, FNAL/MILC **'14**, BMW '14...however, many old papers use ad hoc averaging prescriptions.
- First use of <u>AIC for lattice</u> is BMW '15; see also CalLat '18, '20, Rinaldi et al. '19. (More refs in our paper, including statistics papers back to the '70s.)
- First use of <u>AIC with data penalty</u> is BMW '21 (although I will argue for a *corrected* version of their formula here.)

[Y. Chen et al '04]: arXiv:**hep-lat/0405001** [BMW '14]: PRD 90 (2014), arXiv:**1310.3626** [BMW '15]: Science 347 (2015), arXiv:**1406.4088** [Rinaldi et al. '19]: PRD 99 (2019), arXiv:**1901.07519** [CalLat '20]: PRD 102 (2020), arXiv:2005.04795 [BMW '21]: Nature 593 (2021), arXiv:2002.12347



Bayesian model averaging

[BMW '08]: (BMW collaboration, *Science* 322 (2008), arXiv:0906.3599)

Bayesian model averaging: key ideas

Bayesian model averaging: obtain any • expectation value as a weighted average

$$\langle O \rangle = \sum_{M} \langle O \rangle_{M} \operatorname{pr}(M|D)$$

Note that this applies at the level of *expectation* • *values*. In particular, for mean and variance we find:

$$f(\mathbf{a})\rangle = \sum_{\mu} f(\mathbf{a}_{\mu}^{*}) \operatorname{pr}(M_{\mu}|\{y\}),$$

$$This is not the same as taking a weighted average of variances (first term), or taking the variance of the weighted f(a^{*}).$$

$$= \sum_{\mu} \sigma_{f(\mathbf{a}_{\mu})}^{2} \operatorname{pr}(M_{\mu}|\{y\}) + \sum_{\mu} f(\mathbf{a}_{\mu}^{*})^{2} \operatorname{pr}(M_{\mu}|\{y\}) - \left(\sum_{\mu} f(\mathbf{a}_{\mu}^{*}) \operatorname{pr}(M_{\mu}|\{y\})\right)^{2},$$

average stat. error

(sketch adapted from S. Konishi and G. Kitagawa, Information Criteria and Statistical Modeling, Springer Series in Statistics, 2008)

 Asymptotically correct model weights are given by the (Bayesian) Akaike information criterion (AIC):

$$-2\log \operatorname{pr}(M|D) = -2\log \operatorname{pr}(M) + BAI$$
$$BAIC = \hat{\chi}^2(\mathbf{a}^*) + 2k$$

pr(M) is model prior prob - unless you know what this is take it to be uniform and ignore it

Df

model-variation systematic

Bayesian model averaging





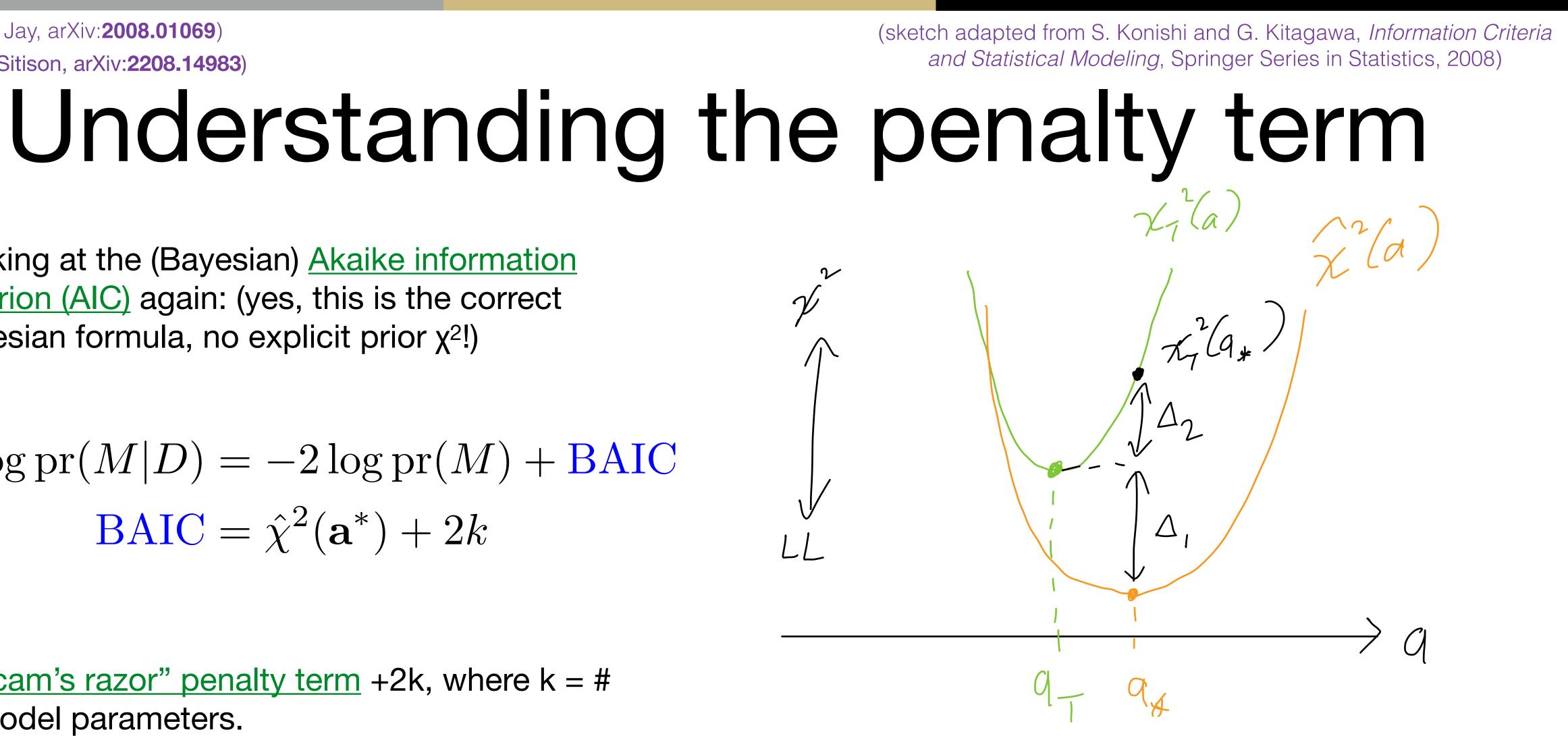


(EN and W. Jay, arXiv:2008.01069) (EN and J. Sitison, arXiv:2208.14983)

Looking at the (Bayesian) Akaike information criterion (AIC) again: (yes, this is the correct Bayesian formula, no explicit prior χ^2 !)

$$-2\log \operatorname{pr}(M|D) = -2\log \operatorname{pr}(M) + BAIO$$
$$BAIC = \hat{\chi}^2(\mathbf{a}^*) + 2k$$

- <u>"Occam's razor" penalty term</u> +2k, where k = # of model parameters.
- Penalty *emerges_naturally* from theoretical considerations as <u>asymptotic bias correction</u>.



Briefly: sample **a*** is an unbiased estimator for true • parameter a_T . But fluctuations of a^* above and below **a**_T <u>both</u> overestimate likelihood (underestimate χ^2 .) Correction of +2 (per dimension of \mathbf{a}) $->+2\mathbf{k}$.

Bayesian model averaging

(EN and J. Sitison, arXiv:2208.14983)

Improved information criteria

Bayesian model averaging

(S. Zhou, *Bayesian model selection in terms of Kullback-Leibler discrepancy*, PhD thesis, Columbia, 2011) (S. Zhou, arXiv:**2009.09248**)

Using the Kullback-Leibler divergence

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 $\operatorname{KL}(M_{\mu}) = E_{z}[\log \operatorname{pr}_{M_{\tau}}]$

- <u>Second term proportional to -log[pr(M|D)]</u>. This is **non-parametric,** good data should •
- <u>Three options are natural</u> and give interesting ICs: •

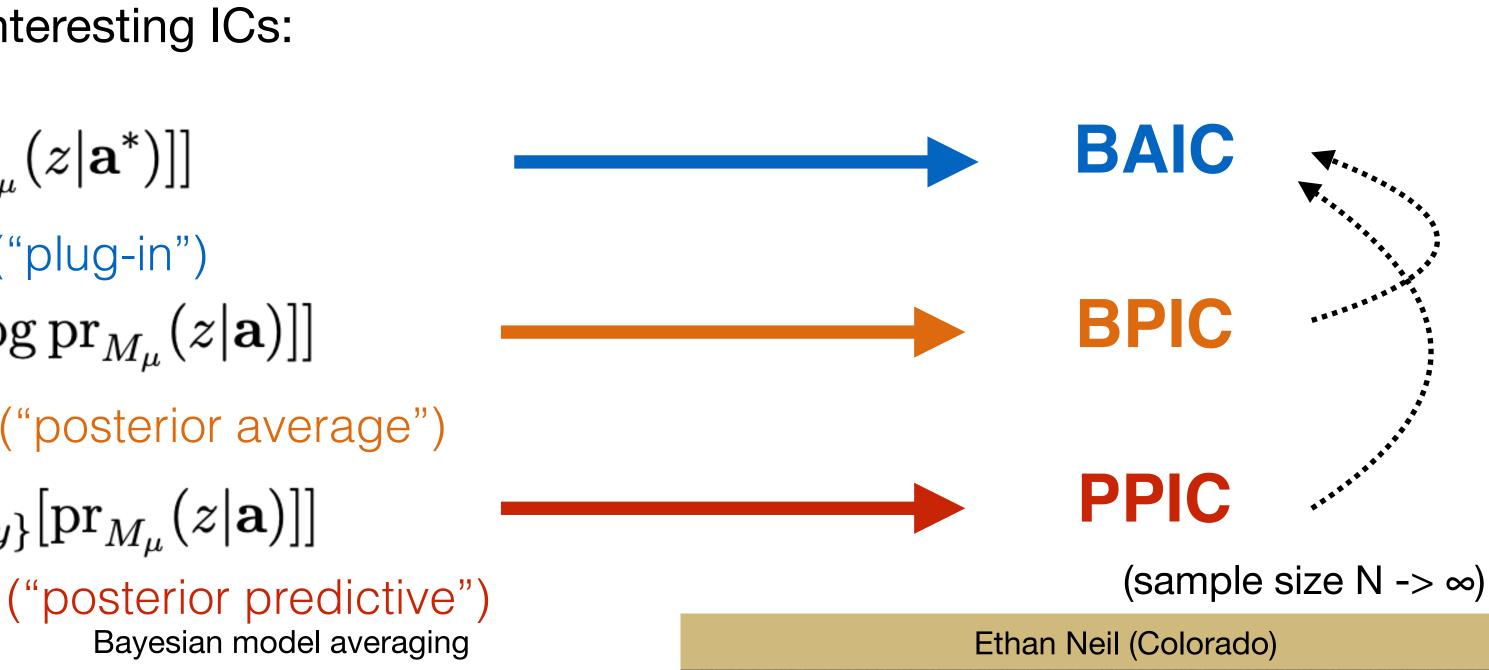
 $E_{z}[\log \operatorname{pr}_{M_{\mu}}(z)] \sim E_{z}[\log E_{\mathbf{a}|\{y\}}[\operatorname{pr}_{M_{\mu}}(z|\mathbf{a})]]$

(EN and J. Sitison, arXiv:2208.14983)

KL divergence ("relative entropy") gives a path to Bayesian information criteria^{*}. Basic definition:

$$E_{_{\mathrm{T}}}(z)] - E_z[\log \mathrm{pr}_{M_{\mu}}(z)]$$

determine parameters. But there are <u>multiple ways</u> to obtain the above from a parametric model!





$$\widehat{\operatorname{Complet}} \xrightarrow{\operatorname{https://gith}} \widehat{\operatorname{Complet}}$$

$$\operatorname{BAIC} = \widehat{\chi^{2}(\mathbf{a}^{*})} \xrightarrow{\operatorname{Fit} \operatorname{Model} \operatorname{Complexity} \operatorname{Data} \operatorname{Truncation}} + 2k \xrightarrow{\operatorname{Fit} \operatorname{Higher-Order} \operatorname{GoF}} + 2k \xrightarrow{\operatorname{Higher-Order} \operatorname{GoF}} + 2k \xrightarrow{\operatorname{Higher-Order} \operatorname{GoF}} + 2k \xrightarrow{\operatorname{Higher-Order} \operatorname{GoF}} + 2k \xrightarrow{\operatorname{Higher} \operatorname{Order} \operatorname{OrdeF}} + 2k \xrightarrow{\operatorname{Igher} \operatorname{OrdeF}} + 2k \xrightarrow{\operatorname{Igher} \operatorname{Igher} \operatorname{Igher} \operatorname{Igher} \operatorname{Igher} \operatorname{Igher} \operatorname{Igher} + 2k \xrightarrow{\operatorname{Igher} \operatorname{Igher} \operatorname{Igher} \operatorname{Igher} \operatorname{Igher} + 2k \xrightarrow{\operatorname{Igher} \operatorname{Igher} \operatorname{Igher} \operatorname{Igher} + 2k \xrightarrow{\operatorname{Igher} \operatorname{Igher} \operatorname{Igher} + 2k \xrightarrow{\operatorname{Igher} \operatorname{Igher} + 2k \xrightarrow{\operatorname{Igher} \operatorname{Igher} + 2k \xrightarrow{\operatorname{Igher} \operatorname{Igher} + 2k \xrightarrow{\operatorname{Igher} + 2k \xrightarrow{Igher} + 2k \operatorname{Igher} + 2k \xrightarrow{Igher} + 2k \xrightarrow{I$$

- IV. <u>Numerical code available</u> in Python + JAX (gradients/JIT compilation), although the code is *not polished* - just companion code for our paper.
- penalty is approximately $+2d_{C}$ plus 1/N corrections. BPIC has larger bias from posterior avg.
- (Fixes a potential numerical problem with log(...) in PPIC.)

<u>nub.com/jwsitison/improved_model_avg_paper</u> te formulas

 $\binom{*}{2}_{abcd}$

 $\left| \log \left[1 + \frac{1}{2} \left(\frac{1}{4} (g_i)_b (g_i)_a - \frac{1}{2} (H_i)_{ba} \right) (\Sigma^*)_{ab} + \frac{1}{4} (g_i)_d T_{cba} (\Sigma_2^*)_{abcd} \right| \right|$

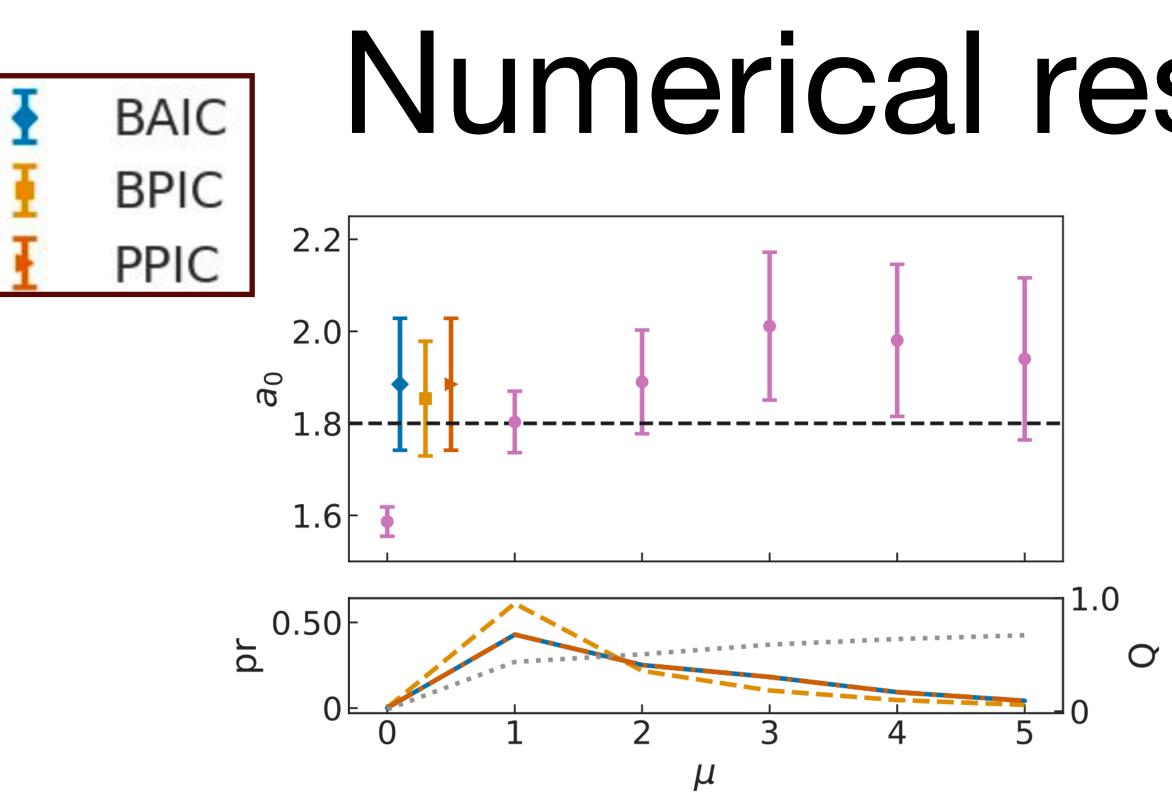
• Various g, H, T, Σ are all tensors of derivatives of chi-squared functions - see our paper 2208.14983, sec.

• The above formulas are approximate, NLO in large-N expansion (N = data sample size.) PPIC subset

We advocate use of optimal truncation, which replaces NLO -> LO when NLO terms are too large.

Bayesian model averaging

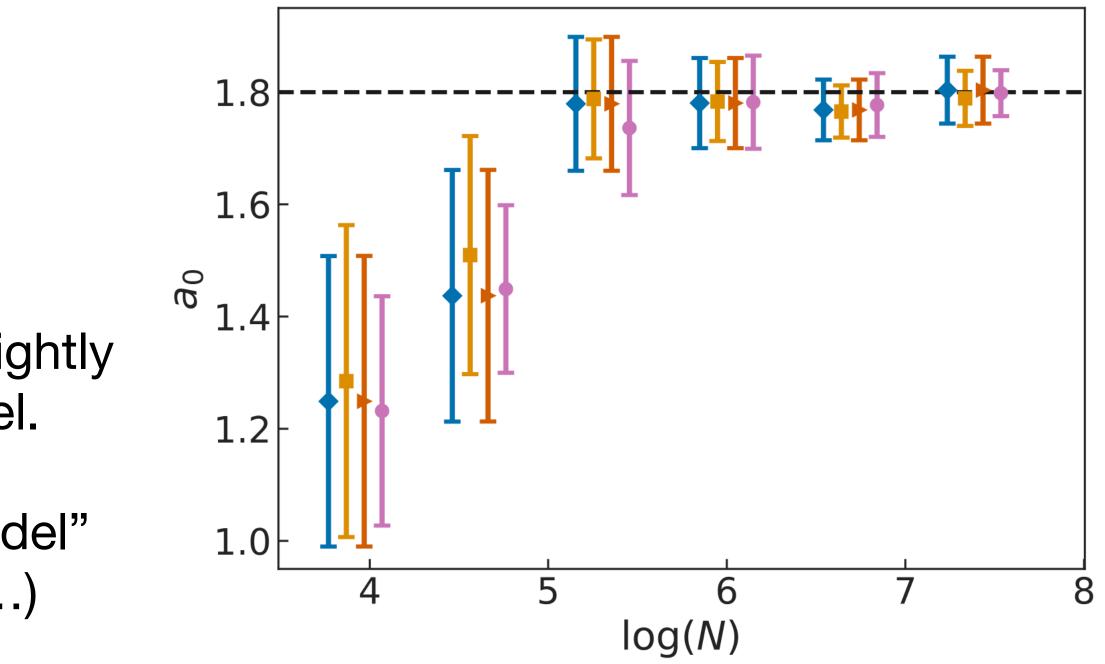




- **<u>Right:</u>** MA vs. sample size log(N). BPIC does slightly better in general, similar to fixed quadratic model.
- (This is sort of a special case since the "true model" is nested within the more complex μ >2 models...)

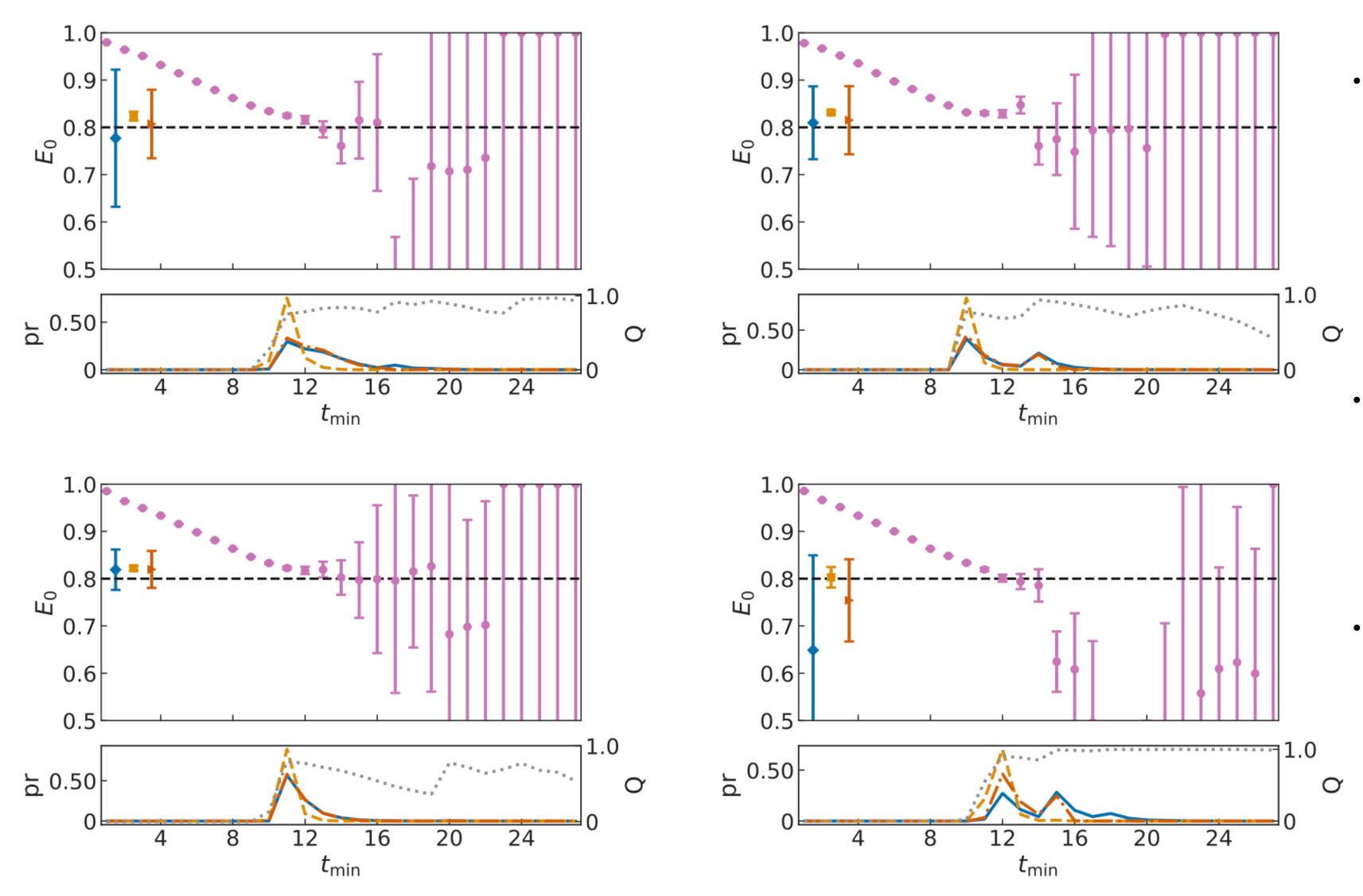
Numerical results: fixed data

- Quadratic model truth, extract constant • term a_0 .
- **Left:** fits to polynomials of degree μ . Extra • parameters are penalized, moreso for BPIC.



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Numerical results: data selection

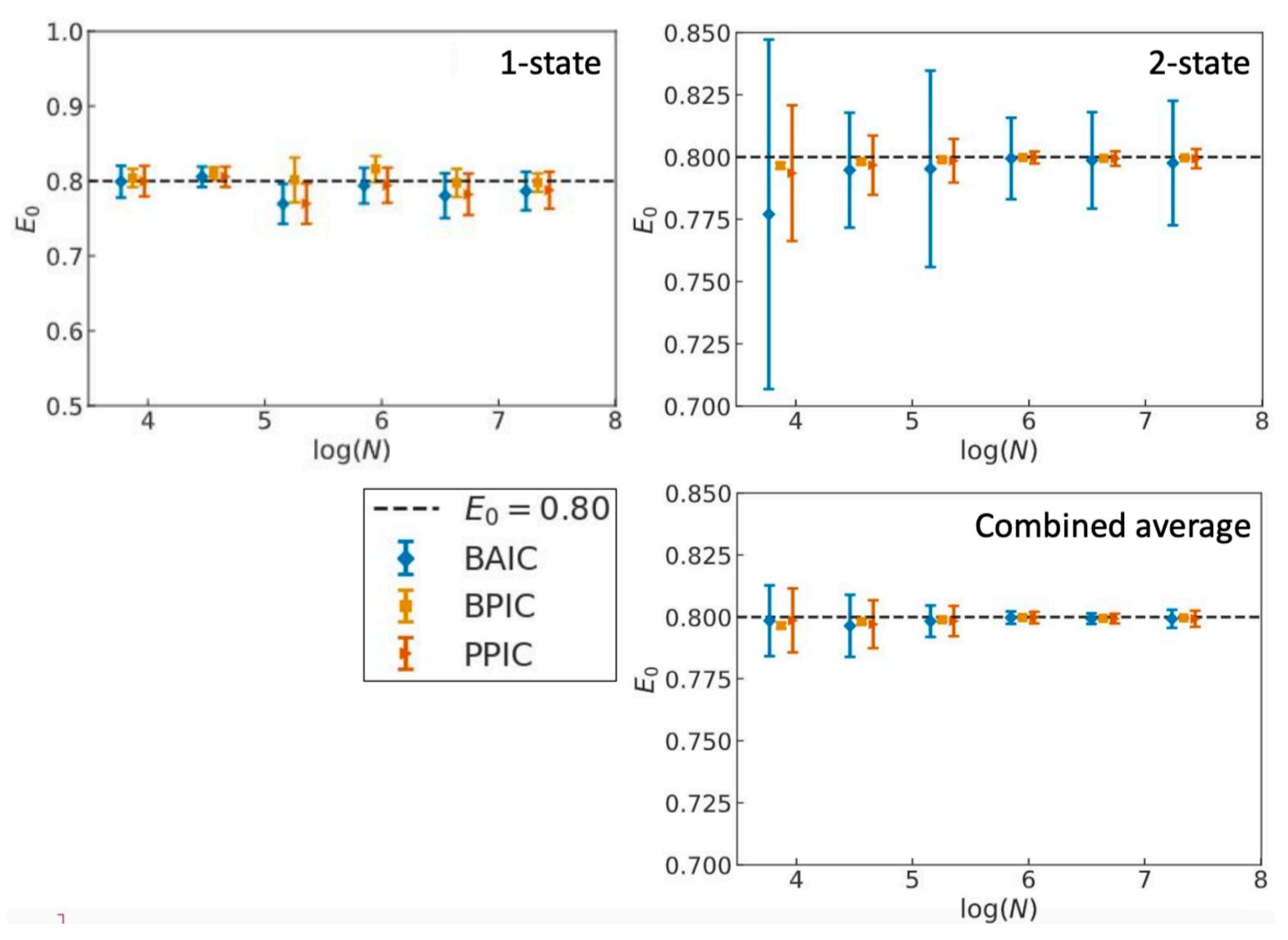


• BPIC cuts aggressively often overly so (biasvariance tradeoff!) But it does fairly well when fitting the true model or with lots of data.

- PPIC is more robust against noise, otherwise performing similarly to BAIC (no excessive bias)
- BAIC is reliable and simplest to compute; we advocate PPIC generally, but nothing wrong with AIC!

Numerical results: data selection (2)

- Scaling results vs. N, similar • conclusions to previous slide: we prefer PPIC, robust results and tends to give smaller error than **BAIC**, particularly w/noise
 - BPIC has smallest error but can be too aggressive, particularly for subset selection.
 - See paper for many more numerical results, including tests on real LQCD nucleon data (courtesy of JLab/W&M/ MIT/LANL)



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Bayesian model averaging

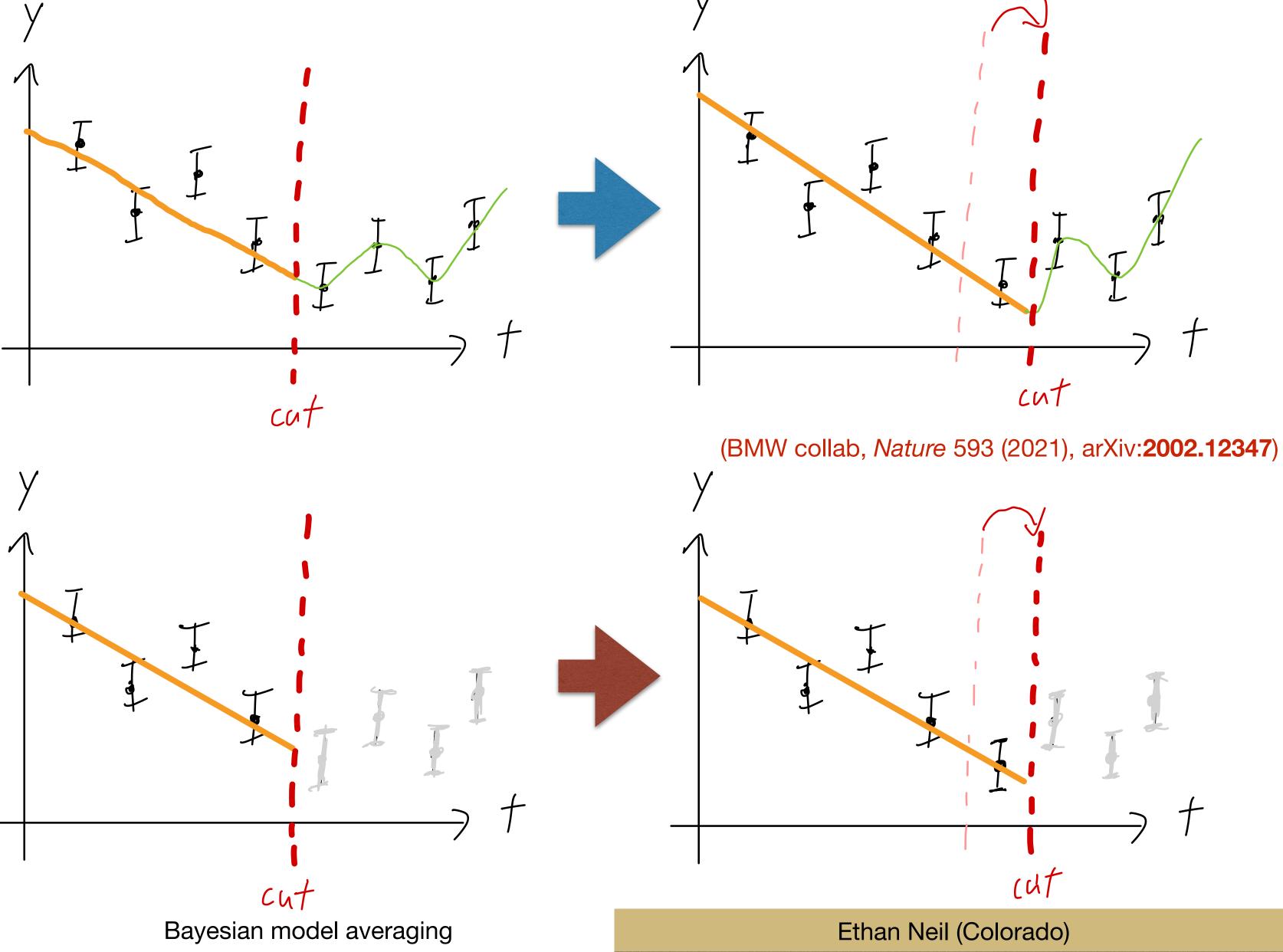
(EN and J. Sitison, arXiv:2305.19417)

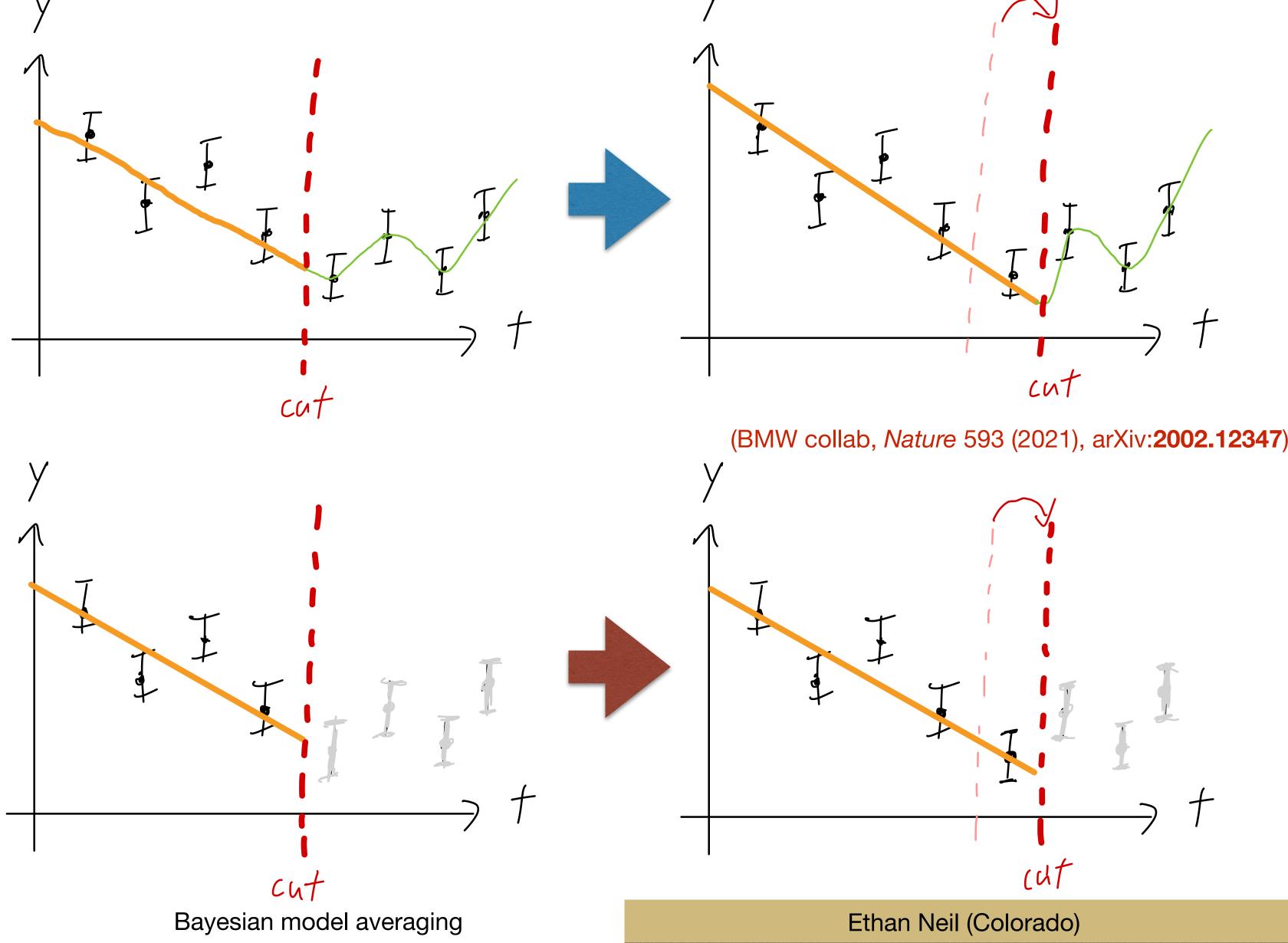
Data subset selection: which penalty?

Bayesian model averaging

(EN and J. Sitison, arXiv:2305.19417) Two approaches to subset selection

- A common part of lattice analysis is <u>data cutting</u>: "what [t_{min}, t_{max}] should I fit my twopoint correlator over?"
- Partition data into kept and cut [ук, ус] of size (dк, dc). Compute relative model weights, average!
- <u>"Perfect model method"</u>: Keep all data. y_C fit to a model with $\chi^2=0$; bias correction gives +2dc penalty.
- "<u>Subspace method</u>": Discard data in cut partition. Recompute *total* KL divergence, gives +dc penalty.





(EN and W. Jay, arXiv:2008.01069)



Comparing the two methods

- (with no corresponding bias reduction).
- Aside from the conceptual argument, we prove the identity:

$$\mathrm{KL}^{\mathrm{sub}}(M_{\mu}, d)$$

• cuts are under-penalized.

• We focus on AIC for simplicity (and since subspace proposal is only computed for AIC.)

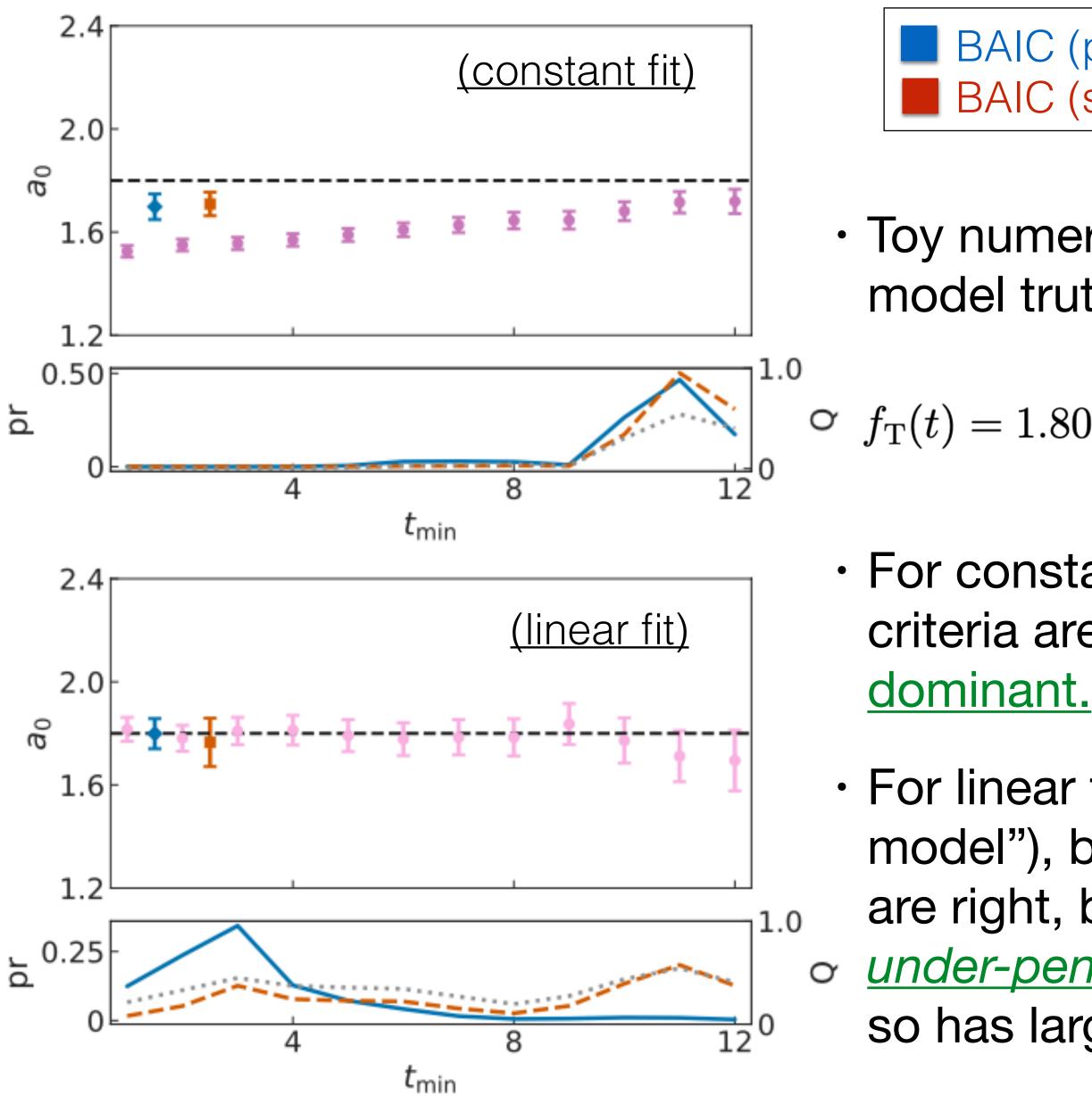
• We argue that AIC (subspace) is subtly flawed. By discarding data completely and recomputing the KL divergence, information is thrown away. This leads to inflated errors

 $\geq \mathrm{KL}^{\mathrm{sub}}(M_{\mu}, d_{\mathrm{K}})$

This behavior is (mildly) pathological - the subspace AIC will never choose to fit all of the data over some of the data (asymptotically.) Errors are increased as fits with data

Bayesian model averaging

(EN and J. Sitison, arXiv:2305.19417)



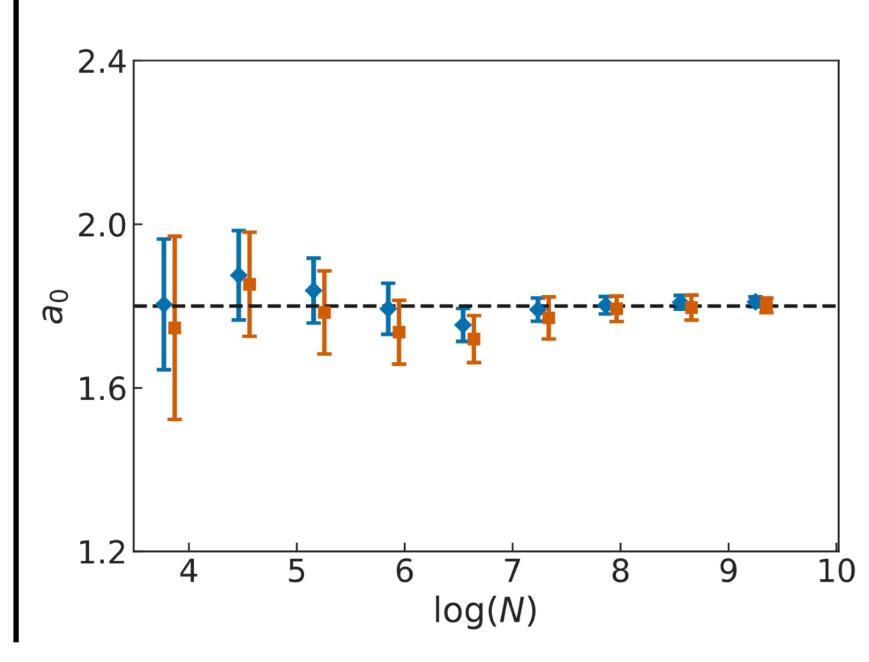
BAIC (perf) BAIC (subset)

• Toy numerical example: model truth is linear,

$$= 1.80 - 0.53 \left(1 - \frac{t}{16} \right)$$

- For constant fit, both criteria are similar; χ^2 is
- For linear fit ("true model"), both averages are right, but <u>subset</u> under-penalizes cutting so has larger error.

- Below: "grand average" (both models @ all tmin) vs. sample size log(N).
- Both ICs agree well w/ model truth for all N; generically larger errors for BAIC (subset)



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Summary

- <u>Bayesian + KL divergence perspective</u> suggests two new ICs:
 - PPIC is more robust against noise and performs well in all tests.
 - bias.
 - All (N -> ∞) roads lead to the (B)AIC, which is simple and effective.
- penalty of +2dc for AIC, or analogous penalty formulas for other ICs.

 Model averaging is a powerful and simple technique for dealing with analysis choices and associated systematic errors. Not a replacement for full Bayesian treatment (see talk by J. Frison, this session!), but easy to "plug in" to existing analysis chains.

• BPIC uses Occam's Razor more aggressively, smaller error at the price of larger

Data subset selection can also be done ("perfect model" construction.) Use the

Bayesian model averaging



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Backup slides

Tips/tricks/FAQs

Q: When should the "model prior" pr(M) be used?

A: Use if you believe (before seeing data) that one model is more likely. (e.g., weight an EFT model over an ad hoc one.).

Do not use pr(M) to penalize complex models - AIC bias term already does this!

Do use pr(M) to deal with classes of similar models. E.g., if you are fitting 20 versions of chiral that pr(chiPT) = pr(other model) = 1/2.

Q: <u>How do I use model averaging with strongly-correlated data?</u>

PPIC; see our paper **2208.14983** for methods.

perturbation theory and one completely distinct model, you might set pr(M) = 1/40 for the variations, so

- A: "100% correlation" is built-in: all pr(M|D) are computed with the same, fixed data D. No adjustment needed!
- For data subset selection, correlations between cut and kept data can complicate life, particularly for BPIC or

Tips/tricks/FAQs

Q: How can I use model averaging with bootstrap/jackknife?

A: No modification needed! Bootstrap and jackknife just give better estimates of expectation values $\langle O \rangle_M$; same MA formulas apply, with same information criteria.

(Using bootstrap to compute ICs/bias directly is an interesting direction for future work!)

Q: <u>Help, my BMA results look weird/I don't believe the MA errors!</u>

A: Model averaging represents a bias-variance tradeoff; accounting for model choice uncertainty generally gives higher variance, but lower bias (your results are more likely to be right.) The discreteness of BMA can give strange-looking behavior, such as 'increased' error when more data are added.

You should take this seriously, as long as you trust all of the inputs! ("Garbage in, garbage out...")

The Kullback-Leibler divergence

 $\operatorname{KL}(M_{\mu}) = E_{z}[\log \operatorname{pr}_{M_{T}}(z)] - E_{z}[\log \operatorname{pr}_{M_{\mu}}(z)]$

- KL = 0 if the PDFs are equal, positive definite otherwise. Find the "closest" distribution to pr_{MT} by **maximizing** the magnitude of the second term!
- Introduce model parameters **a**, and this leads to familiar results:

$$E_{z}[\log \operatorname{pr}(z|\mathbf{a}, M_{\mu})] \simeq \frac{1}{N} \sum_{i} \log \operatorname{pr}(y_{i}|\mathbf{a}, M_{\mu}) = \frac{1}{N} \log \operatorname{pr}(\{y\}|\mathbf{a}, M_{\mu})$$

$$\underbrace{1}_{N} \log \operatorname{pr}(\{y\}|\mathbf{a}, M_{\mu})$$

<u>function gives model probability weights</u>, via Bayes theorem: $pr(M|D) \sim pr(D|M)$.

• <u>KL divergence</u>: "relative entropy" between PDFs, true model M_T vs. candidate model M_{μ} .

$$\equiv \int dz \,\left[\mathrm{pr}_{M_{\mathrm{T}}}(z) \log \mathrm{pr}_{M_{\mathrm{T}}}(z) - \mathrm{pr}_{M_{\mathrm{T}}}(z) \log \mathrm{pr}_{M_{\mu}}(z) \right]$$

e.g. finding best-fit point **a*** = minimization of KL divergence ("max likelihood".) Same likelihood

Bayesian model averaging

(EN and J. Sitison, arXiv:**2305.19417**) x², dof, and subset selection

degrees of freedom, $N_{dof}=d_{K}-k$:

$$\begin{aligned} \text{AIC}_{\mu,d_{\text{K}}}^{\text{sub}} &= N_{\text{dof}} \left(\hat{\chi}_{\text{K}}^{2}(\mathbf{a}^{*}) / N_{\text{dof}} - 1 \right) + k, \\ \text{AIC}_{\mu,d_{\text{K}}}^{\text{perf}} &= N_{\text{dof}} \left(\hat{\chi}_{\text{K}}^{2}(\mathbf{a}^{*}) / N_{\text{dof}} - 2 \right). \end{aligned}$$

$$\begin{aligned} \text{AIC}_{\mu,d_{\text{K}}}^{\text{sub}} &= N_{\text{dof}} \left(\hat{\chi}_{\text{K}}^{2}(\mathbf{a}^{*}) / N_{\text{dof}} - 1 \right) + k, \\ \text{AIC}_{\mu,d_{\text{K}}}^{\text{perf}} &= N_{\text{dof}} \left(\hat{\chi}_{\text{K}}^{2}(\mathbf{a}^{*}) / N_{\text{dof}} - 2 \right). \end{aligned}$$

- AIC^{perf} << 0 (lower AIC is preferred.) Is this a problem?
- is still just data cutting penalty:

$$\operatorname{AIC}_{\mu,d_{\mathrm{K}}}^{\operatorname{perf}} = N_{\operatorname{dof}}\left(\hat{\chi}_{\mathrm{K}}^{2}(\mathbf{a}^{*})/N_{\operatorname{dof}} - 1\right) + k - d_{\mathrm{K}}.$$

Bayesian model averaging

Rewrite both forms of AIC in terms of usual number of

• For a bad fit with large Ndof and $1 < \chi^2 < 2$, we can have AIC^{sub} >> 0 but

• Example by explicit construction in appendix B of paper, but favoring a "bad fit" over a "good fit" in this way requires that a large amount of data are cut for the "good fit". Rewrite AIC^{perf} to see explicitly that the difference

Asymptotic bias

• When constructing any statistical estimator, one typically worries about bias, defined as follows: for distribution $p_{T}(z)$ with property $\xi(z)$, given a finite sample $\{y\}$ of size N and estimator X({y}),

$$b_{z}[X(\{y\})] \equiv E_{z}[X(\{y\}) - \xi(z)] = E_{z}[X(\{y\})] - \xi(z)$$

 In other words, when averaged over the true distribution (i.e. over many independent samples), a non-zero bia means the estimator is wrong. We can further define asymptotic bias as:

$$b_{z}[X(z)] = \lim_{N \to \infty} b_{z}[X(\{y\})]$$

 Asymptotic bias is often easier to calculate than finitesample bias, and estimators with zero asymptotic bias are at least self-correcting, in the sense that they are correct as N $->\infty$.

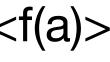
 It is not obvious that an unbiased model probability gives an unbiased model average. But we prove the bias on the model average is bounded:

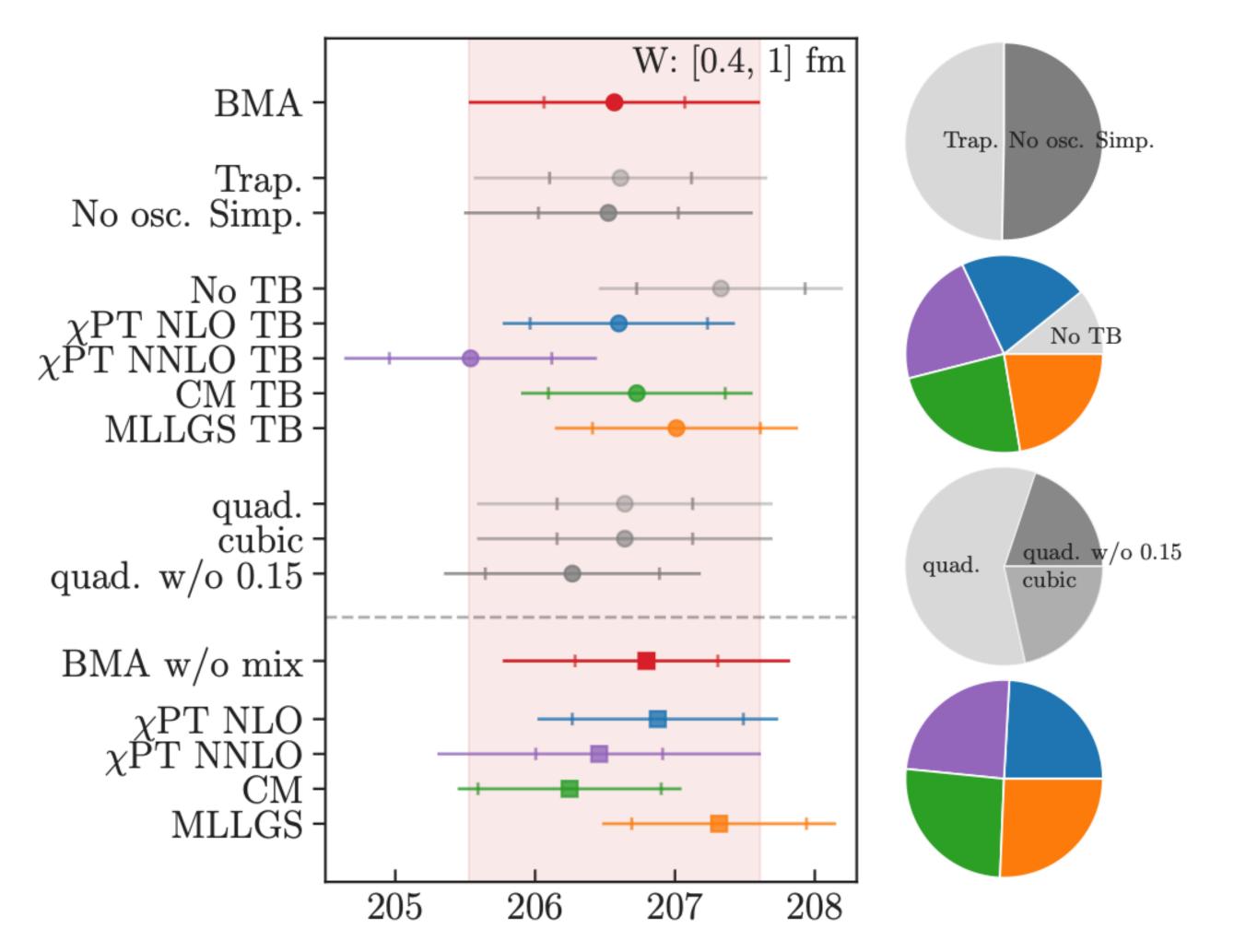
 $|b_{z}[\langle f(\mathbf{a})\rangle]| \leq \sum_{\mu} |\langle f(\mathbf{a})\rangle_{\mu}| |b_{z}[\operatorname{pr}(M_{\mu}|z)]|$

assuming that the individual-model estimates $\langle f(a) \rangle$ are consistent (a slightly stronger version of asymptotically unbiased.) In short: unbiased model weights give unbiased model averages.

Bayesian model averaging







From (g-2) HVP model averaging analysis - can compare subsets of model space to understand systematic effects (center), or use model weights to compute posterior probabilities (pie charts)

(Fermilab/HPQCD/MILC collaborations, arXiv:2301.0874; talk by S. Lahert, Tue @ 2:10 PM)

Bayesian model averaging



