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## HISQy Business

Evan Weinberg, Senior Developer Technology Compute Engineer, NVIDIA
Lattice2023, July 31, 2023
(In collaboration with Venkitesh Ayyar, Richard Brower, Kate Clark)

There's going to be a GPU raffle! The drawing will be during the Lattice 2024/2025 announcement on Friday.


## Agenda

- Takeaways \& Challenges
- HISQ Crash Course
- HISQ Force
- HISQ Domain-Decomposed Preconditioning
- Future Work


Takeaways
Speeding up HISQ workflows

- HISQ: highly improved staggered quarks
- Smeared links: lots of locality to exploit
- New: hugely fused HISQ force implementation in QUDA
- Merged: https://github.com/lattice/quda/pull/1367














## Takeaways

Speeding up HISQ workflows

- HISQ: highly improved staggered quarks
- Smeared links: lots of locality to exploit
- New: hugely fused HISQ force implementation in QUDA
- Merged: https://github.com/lattice/quda/pull/1367
- Modern machines have varying degrees of network performance
- Domain-decomposition algorithms become increasingly important
- HISQ's distance one and three terms introduce conceptual challenges
- New: (mostly-)optimized implementation of a local HISQ preconditioner in QUDA
- We have demonstrated numerical stability
- And, in some cases, faster propagator solves---with performance successes and failures understood
- WIP branch, constantly in flux:
https://github.com/lattice/quda/tree/feature/stag-invert-cleanup















## QUDA

- "QCD on CUDA" - http://lattice.github.com/quda (open source, BSD license)
- Not just CUDA anymore
- Effort started at Boston University in 2008, now in wide use as the GPU backend for BQCD, Chroma**, CPS**, MILC**, TIFR, etc.
- Provides solvers for major fermionic discretizations, pure gauge algorithms, etc.
- Maximize performance
- Mixed-precision methods
- Autotuning for high performance on all architectures
- Multigrid solvers for optimal convergence
- NVSHMEM for improving strong scaling
- Portable: HIP (merged), SYCL (in review) and OpenMP (in development)
- A research tool for how to reach the exascale (and beyond)
- Optimally mapping the problem to hierarchical processors and node topologies


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Or: the state of the network

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- You can't always take advantage of all hierarchies of bandwidths/latencies
- Communication reducing or avoiding algorithms are increasingly important for mitigating these challenges
- Our community has been and continues to be fully aware of this:
- Communication-reducing solvers
- Domain-decomposed preconditioners
- Domain-decomposed HMC



## Why Staggered Fermions?

Aka Kogut-Susskind Fermions

$$
D_{x, y}^{s t a g} \approx \sum_{\mu=0}^{3} \eta_{\mu}(x)\left[U_{\mu}(x) \delta_{x, y-1}-U_{\mu}^{\dagger}(x-\hat{\mu}) \delta_{x, y+1}\right]+2 m \delta_{x, y}
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- Spin-diagonalize the discrete Dirac matrix
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- Like the continuum operator, it's just a symmetric first derivative: anti-Hermitian and normal


## Why Staggered Fermions?

Continued

- Huge secondary benefit: the even/odd preconditioned operator is Hermitian Positive-Definite
- Anti-Hermitian + normal: $D_{e o}=-D_{o e}^{\dagger}$

$$
\begin{gathered}
{\left[\begin{array}{cc}
2 m & D_{e o} \\
D_{o e} & 2 m
\end{array}\right]\left[\begin{array}{l}
x_{e} \\
x_{o}
\end{array}\right]=\left[\begin{array}{l}
b_{e} \\
b_{o}
\end{array}\right]} \\
\left(4 m^{2}-D_{e o} D_{o e}\right) x_{e}=2 m b_{e}-D_{e o} b_{o}
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- Obviously, there's no free lunch
- There is a residual doubling: $2^{d / 2}$ doublers (as opposed to $2^{d}$ )
- "Taste-breaking" effects: only one of the "pions" feels the exact lattice chiral symmetry


## Enter HISQ

"Highly Improved Staggered Quarks"

- HISQ takes staggered fermions and addresses the issues:
- Smooths the fields
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From Follana et al; arxiv:05070 11

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- Full workflow: ASQTAD + re-unitarization + ASQTAD
- Equations can be re-written to remove Lepage term from first step


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- Full workflow: ASQTAD + re-unitarization + ASQTAD
- Equations can be re-written to remove Lepage term from first step
- Addition of "long links" for Symanzik improvement


From Follana et al; arxiv:0507011

## The HISQ Stencil

17 points for Lattice Gryffindor

- The final (massive) HISQ stencil is a 17-point stencil
- One local mass term
- Eight distance-1 "fat link" terms: "general" Nc x Nc matrices
- Eight distance-3 "long link" terms: U(Nc) matrices










## Recursive Link Fattening

- Constructing the fat links is inherently recursive
- 3-link terms are built from 1-link terms
- 5-link terms can be built from 3-link terms - As can the Lepage (c5') staple
- 7-link terms can be built from 5-link terms


From Follana et al; arxiv:0507011

## Data Reuse

Caches exist for a reason


Save this sum to a temporary accumulator

Save each length three staple


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Save each length three staple

- In the next kernel: load gauge links, load two staples, construct five-link terms, accumulate c5s into force, save fivelink terms


Load these two links


Increment five-link staples into accumulator

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- In the next kernel: load gauge links, load two staples, construct five-link terms, accumulate c5s into force, save fivelink terms


Load these two links

- ...etc


Increment five-link staples into accumulator

[^0]

## HISQ Force

"Highly Improved Staggered Quarks"

- The HISQ force is a beast: three-stage chain rule
- Similar to the fat link construction, there are a lot of opportunities for...
- Reuse of intermediates
- Kernel fusion
- Cache Reuse



## HISQ Force

Sorry about the pseudocode

- Original implementation:

Loop over sig $=\{x, y, z, t\} ; f o r w a r d / b a c k w a r d$

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End loop (mu)
End loop (sig)


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Loop over sig $=\{x, y, z, t\} ; f o r w a r d / b a c k w a r d$
Loop over mu != |sig|; forward/backward
Compute sig,mu 3-link middle force: Accumulate and store intermediates

End loop (mu)
End loop (sig)


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Loop over sig $=\{x, y, z, t\} ;$ forward/backward
Loop over mu != |sig|; forward/backward
Compute sig,mu 3-link middle force
Loop over nu != |sig|,|mu|; forward/backward
Compute sig,mu,nu 5-link middle force: reuse intermediates from before

End loop (nu)

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Compute sig,mu,nu 5-link middle force
Loop over rho != |sig|,|mu|,|nu|, forward/backward
Compute sig,mu, nu, rho 7-link middle force, side force
End loop (rho)

End loop (nu)

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Loop over sig = {x, y, z, t}; forward/backward
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Compute sig,mu,nu 5-link side force... + next middle force
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End loop (sig)


## Use Your Symmetries

- While the staples are general matrices, all base gauge links are $U(3)$
- Take advantage of this symmetry to reduce memory traffic: store as 13 reals, recompute as needed


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Improvements are algorithmic and architectural


Algorithm: 1.5x

Architecture:
3.75x

Architecture and algorithm boosts multiply: ~5.6x

##  <br> $-2$



## Additive Schwarz Preconditioning with Non-Overlapping Blocks

Speeding up HISQ inversions

- Simple idea: expand the idea of site-local preconditioning...
- Preconditioning (twisted-)clover with the (twisted-)clover inverse
- Example B: 4-d preconditioning of Mobius fermions



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- ...to larger domains: Schwarz preconditioning



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- Example B: 4-d preconditioning of Mobius fermions
- ...to larger domains: Schwarz preconditioning
- Additive Schwarz is analogous to Jacobi Iterations, but for domains
- For this talk: domains are non-overlapping
- Here: one domain per MPI rank (== one GPU)
- This is a person-hour coding and debugging constraint
- There's no inherent algorithmic or machine constraint



## Existing Work

Mobius Fermions

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Mobius Fermions

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- The challenge is constructing the algorithm and the implementation
- A recent example in LQCD is Multi-Splitting Preconditioned Conjugate Gradient (MSPCG)
- [arxiv:2104.05615]
- For Mobius fermions, the relevant HPC operator is the normal 4-d preconditioned operator

$$
\left(1-D_{e o} D_{0 e}\right)^{+}\left(1-D_{e o} D_{\text {oe }}\right)
$$

- The product of four Ds generates so-called snake terms



## Zero Boundaries

"Boundary clovers"

- Let's consider the massless staggered operator... in one dimension, for extreme simplicity

$$
D_{x, y}^{s t a g} \approx\left[M_{\mu}(x) \delta_{x, y-1}-M_{\mu}^{\dagger}(x-\hat{\mu}) \delta_{x, y+1}\right]
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- The stencil gathers from two sites: one on the left, and one on the right



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- For non-overlapping blocks, there's no contribution from outside the domain
- Above: contribution from the left is zero
- For this simple stencil, this is equivalent to zeroing out the hopping term itself...
- ...that thinking is trouble


## Squared operator

- Let's consider the massless operator squared... in one dimension, to keep bookkeeping easy

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## Squared operator on the Boundary

There's always a catch

- Let's consider the massless operator squared... in one dimension, to keep bookkeeping easy
$D_{x, y}^{s t a g} \approx\left[M_{\mu}(x) \delta_{x, y-1}-M_{\mu}^{\dagger}(x-\hat{\mu}) \delta_{x, y+1}\right]$

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## Sidebar: MSPCG Work

Mobius Fermions

- The MSPCG work took advantage of extended domains

$$
D_{o e}^{\dagger} D_{e o}^{\dagger} D_{e o} D_{o e}
$$



## Existing Work

Mobius Fermions

- The MSPCG work took advantage of extended domains

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D_{o e}^{+} D_{e o}^{\dagger} D_{e o} D_{o e}
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- Four steps, one for each operator application

1. $D_{o e}$ on $(L+2)^{4}$ volume


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2. $D_{e o}$ on $(L+4)^{4}$ volume


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- This extra work can be very expensive; non-trivially so for small local domains (strong-scaling regime)
- HISQ fermions have relative benefits and challenges
- Only $D_{e o} D_{o e}$
- Need to bookkeep distance-1 and distance-3 terms
- Distance-3 terms would necessitate an $(L+6)^{4}$ volume



## Application to 1-d Staggered

Extended domains

$$
D_{x, y}^{s t a g} \approx\left[M_{\mu}(x) \delta_{x, y-1}-M_{\mu}^{\dagger}(x-\hat{\mu}) \delta_{x, y+1}\right]
$$



- Step one: calculate including the extended domain


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D_{x, y}^{s t a g} \approx\left[M_{\mu}(x) \delta_{x, y-1}-M_{\mu}^{\dagger}(x-\hat{\mu}) \delta_{x, y+1}\right]
$$



- Step two: only calculate within the interior


## Application to 1-d Staggered

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\approx \underbrace{M_{\mu}(x) M_{\mu}(x+\hat{\mu}) \delta_{x, y-2}}_{\text {From the right }}-\underbrace{\left[M_{\mu}(x) M_{\mu}^{\dagger}(x)+M_{\mu}(x-\hat{\mu}) M_{\mu}^{\dagger}(x-\hat{\mu})\right] \delta_{y, z}}_{\text {From self }}+\underbrace{M_{\mu}^{\dagger}(x-\hat{\mu}) M_{\mu}^{\dagger}(x-2 \hat{\mu}) \delta_{x, y+2}}_{\text {From the left }}
$$



- This also gives you the boundary term


## Alternative Form: "Boundary Clover"

$$
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$$

- Alternative approach: what if we "just" calculated the self-contribution ("boundary clover") directly?



## Implementing a Boundary Clover Workflow

Step 1

- An implementation in two parts:
- Step 1: Apply the operator with Dirichlet boundary conditions
- For operators in the interior, this is nothing interesting
- For operators on the boundary, it's a quick snip



## Boundary Clover

## Step 2

- An implementation in two parts:
- Step 2: Apply the operator with "clover" computations on the boundary
- For operators on the interior, this is nothing special
- For operators on the boundary, in the direction of the boundary, compute the full hop "out and in"
- Key optimizations:
- We can reuse the same link for the "out" as the "in"
- We could create a custom field with this pre-computed to avoid the multiplication


Application to HISQ


## Review: HISQ Stencil

Three hops this time

- On face value, the HISQ stencil has no complications relative to the naïve staggered example

$$
D_{x, y}^{H I S Q} \approx \sum_{\mu=0}^{3} \eta_{\mu}(x)\left[\left(F_{\mu}(x) \delta_{x, y-1}-F_{\mu}^{\dagger}(x-\hat{\mu}) \delta_{x, y+1}\right)+\left(L_{\mu}(x) \delta_{x, y-3}-L_{\mu}^{\dagger}(x-3 \hat{\mu}) \delta_{x, y+3}\right)\right]+2 m \delta_{x, y}
$$

- Here, F is the distance 1 "fat link" and L is the distance 3 "long link"



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## Schur Going to Have a Tough Time

## Three hops this time

- The "real" goal is the even/odd preconditioned operator:

$$
\begin{gathered}
D_{x, y}^{H I S Q} \approx \sum_{\mu=0}^{3} \eta_{\mu}(x)\left[\left(F_{\mu}(x) \delta_{x, y-1}-F_{\mu}^{\dagger}(x-\hat{\mu}) \delta_{x, y+1}\right)+\left(L_{\mu}(x) \delta_{x, y-3}-L_{\mu}^{\dagger}(x-3 \hat{\mu}) \delta_{x, y+3}\right)\right]+2 m \delta_{x, y} \\
{\left[\begin{array}{cc}
2 m & D_{e o} \\
D_{o e} & 2 m
\end{array}\right]\left[\begin{array}{l}
x_{e} \\
x_{o}
\end{array}\right]=\left[\begin{array}{l}
b_{e} \\
b_{o}
\end{array}\right]} \\
\left(4 m^{2}-D_{e o} D_{o e}\right) x_{e}=2 m b_{e}-D_{e o} b_{o}
\end{gathered}
$$

- The type of bookkeeping noted in the previous slide causes new headaches


## Site Zero

Three hops this time

- Let's first consider the site at [0]
- There are three "boundary" contributions:
- Start at [0]: fat link left, fat link right
- Start at [0]: long link left, long link right
- Start at [2]: long link left, fat link right



## Site One

- Let's first consider the site at [1]
- There is only one boundary condition:
- Start at [1]: long link left, long link right



## Site Two

- Last, we'll consider the term at [2]
- There are two boundary contributions:
- Start at [2]: long link left, long link right
- Start at [0]!: fat link left, long link right



## Solver Workflow

Solving at the speed of sound

- For the non-preconditioned solve, we use mixed-precision conjugate gradient (CG) with gauge link reconstruction


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## Solver Workflow

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- For the preconditioned solver:
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- We use fixed-iteration CG as the inner solve
- Note: PCG on paper requires a stationary preconditioner...
- But with a Polak-Ribière correction, CG is "no worse than" Gradient Descent...
- ...and seems to work well enough


## Reference Configurations, System

Solving at the speed of sound

- Configuration:
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| Nodes | GPUs | Local Domain |
| :--- | :--- | :--- |
| 8 | 32 | $36^{4}$ |
| 16 | 64 | $36^{3} \times 18$ |
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- We consider multiple strong scaling problem sizes
- For networks:
- 2:1 and 1:1 direct GPU:NIC bindings to emulate different network bandwidths
- 4:1 GPU:NIC bindings with staging through the CPU
- All tests utilize NVSHMEM, implementations of the HISQ kernel
- Device-driven communications
- Reduces latency: no separate packing kernel, no overhead of MPI calls, gets the host out of the way


## Convergence History

An unstable algorithm is pointless


- CG and PCG each converge in a stable fashion
- The "spikes" are due to residual updates: "every so often" we recompute the exact residual and re-inject it into the (P)CG solve


## Operator Performance: Zero Boundary Conditions



Performance is essentially independent of the partitioning
This makes sense: all we're doing is "snipping" away work

## Operator Performance: Boundary Clovers



Performance decreases with partitioning This makes sense: we're adding (divergent) work
Extra note: reconstruct becomes a detriment: extra instructions hold up threads

## Iteration Counts for each Preconditioner



More preconditioner iterations -> fewer outer iterations (to a point)
Diminishing benefit with smaller partition sizes -> domain is a lower-quality approximation of full domain

## Time to Solution (which is all that matters)



Note: $1 \times$ NIC includes CPU staging for two GPUs to access a NIC!
There's still outstanding work to be done when the network is strong ( $25 \mathrm{~GB} / \mathrm{s}$ bi-directional per NIC)...
...but we also see that the preconditioner is beneficial when the network is slow

Future Work

## Future HISQy Business

Same old song and dance
-HISQ Force: no further optimizations
-Schwarz Preconditioner: Pre-computed matrix products to reduce latencies
-HISQ MG + Schwarz Preconditioner:

- Use the local operator as a smoother on all levels
- Outer HISQ and Kahler-Dirac preconditioned operator have GPU code implementations
- Even/odd preconditioned coarse operators do not
-... $192^{3} \times 384$ ensemble


## @ IVIDIA


[^0]:    Save each five-link staple separately

