



Gauge redundancy as approximate error correction codes for quantum simulations

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Should quantum simulations keep the gauge redundancy?

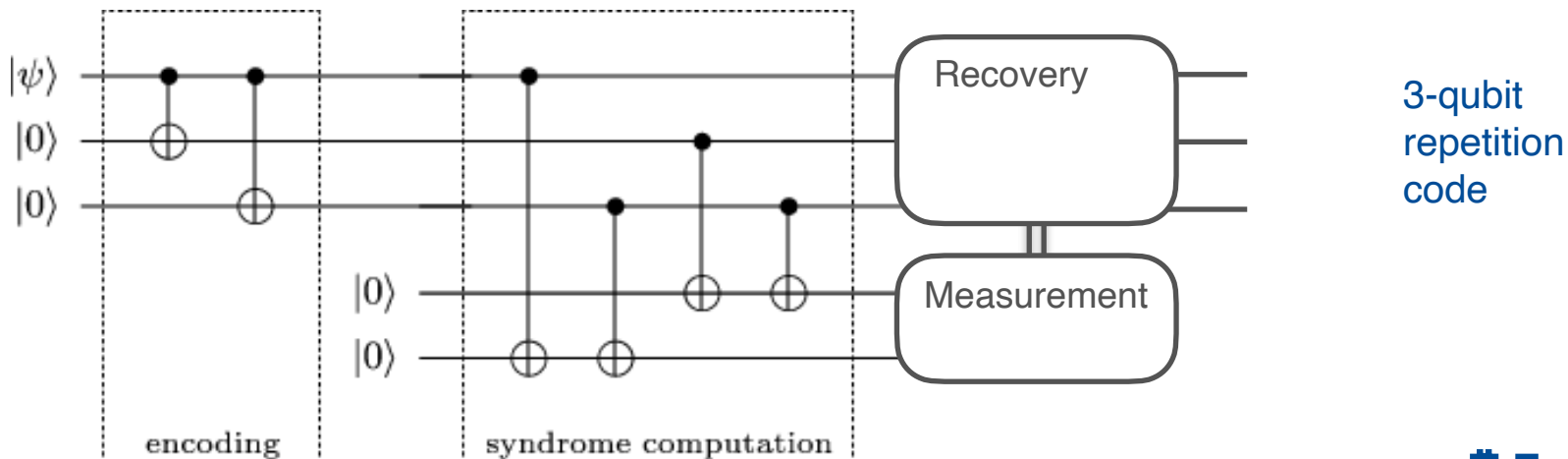


	Keep the redundancy	Fix the gauge
Pros	<p>In arbitrary dimensions and groups:</p> <ul style="list-style-type: none"> ● Hamiltonian is easy to derive ● Local Hamiltonian 	<ul style="list-style-type: none"> ● Saves qubits by $\sim (1 - 1/d)$ ● No symmetry breaking errors
Cons	<ul style="list-style-type: none"> ● Redundant qubits ● Errors can break symmetry ● States are highly entangled 	<p>In $d > 2$ or non-Abelian groups</p> <ul style="list-style-type: none"> ● Hamiltonian is hard to derive ● Non-local Hamiltonian

Grabowska's Plenary talk

When errors exist, Redundancy becomes Resources

$\mathcal{H}_{\text{code}}$ $ 111\rangle, 000\rangle$ Subspace invariant under the stabilizer group $\mathcal{S} = \{I, Z_1Z_2, Z_2Z_3, Z_1Z_3\}$	$ 001\rangle, 010\rangle, 100\rangle,$ $ 011\rangle, 110\rangle, 101\rangle$ $\mathcal{H}_{\text{full}}$
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Use gauge redundancy as QEC:



Existing works

- For error mitigations (Quantum Zeno effect): Lamm et.al. 2020, Halimeh et.al. 2020, 2022, etc.
- For error corrections: Stryker 2019, Rajput et.al. 2023, Bao et.al. 2023
- Closely related to topological QEC

This work: when is it worthwhile?

$\epsilon < \epsilon_{th}$: redundancy makes the code more error-proof

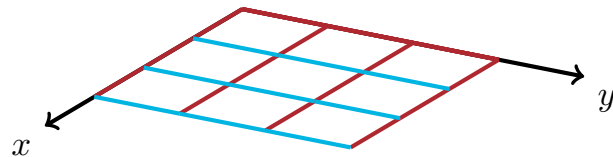
$\epsilon > \epsilon_{th}$: redundancy makes more errors than it can correct



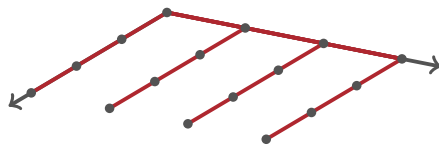
Gauge redundancy in the Hilbert space of LGT

d -dimension spatial lattice, N_L links, N_V vertices

$$\mathcal{H}_{\text{gauge}} = \text{span}\{ |U\rangle, U \in G\}^{\otimes N_L}$$



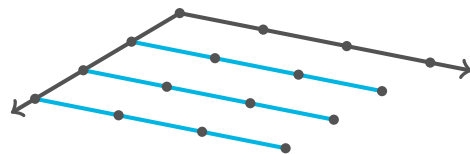
- Impose Gauss's Law:



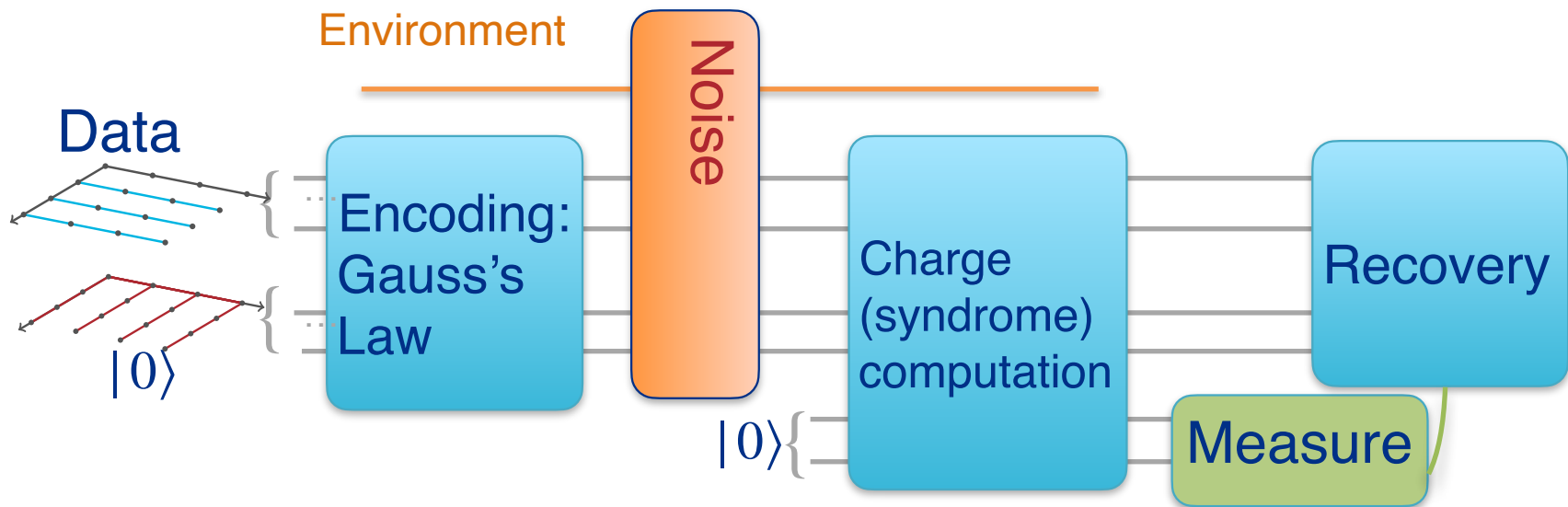
N_T links in a maximal tree can be solved from the rest

$$N_T = N_V - 1$$

$$\mathcal{H}_{\text{inv}} \approx \text{span}\{ |U\rangle, U \in G\}^{\otimes (N_L - N_T)}$$

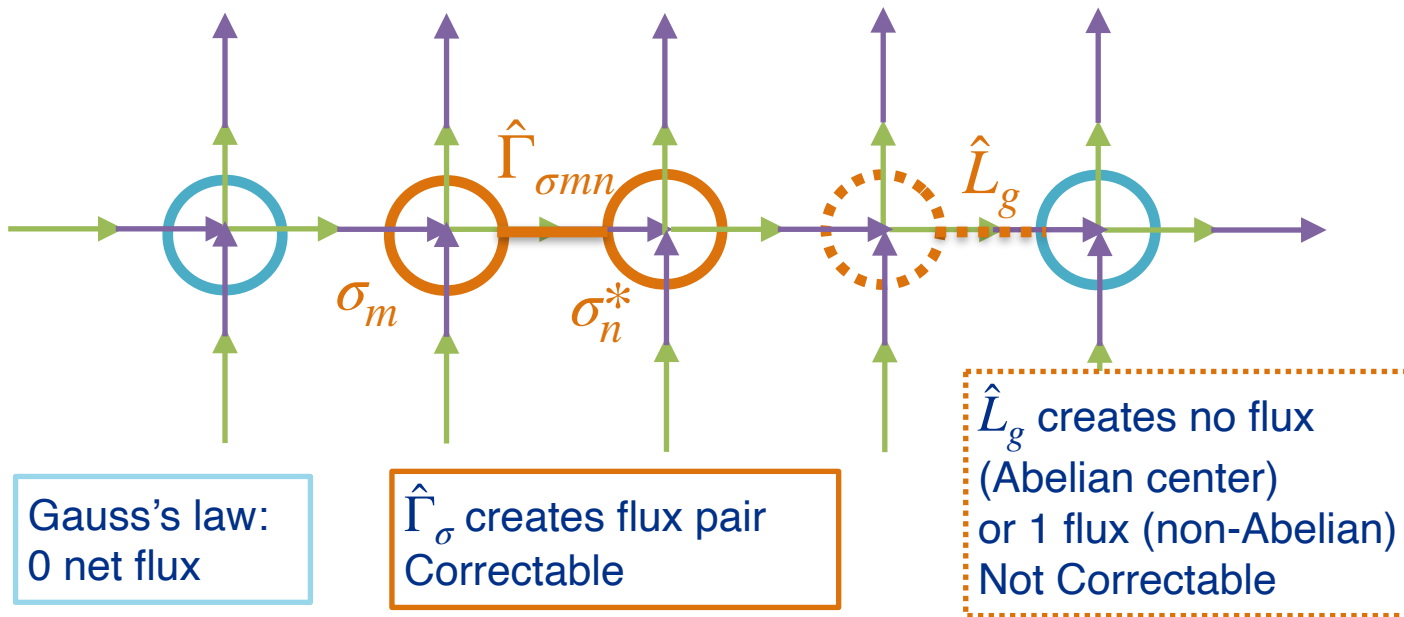
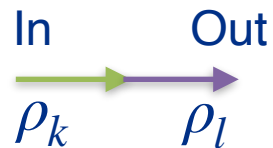


The circuits: encoding, detection and recovery



What errors are correctable?

Electric (group representation) basis $|\rho_{kl}\rangle$

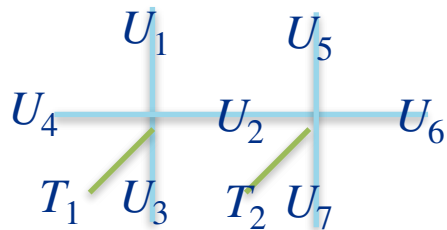


Gauss's law:
0 net flux

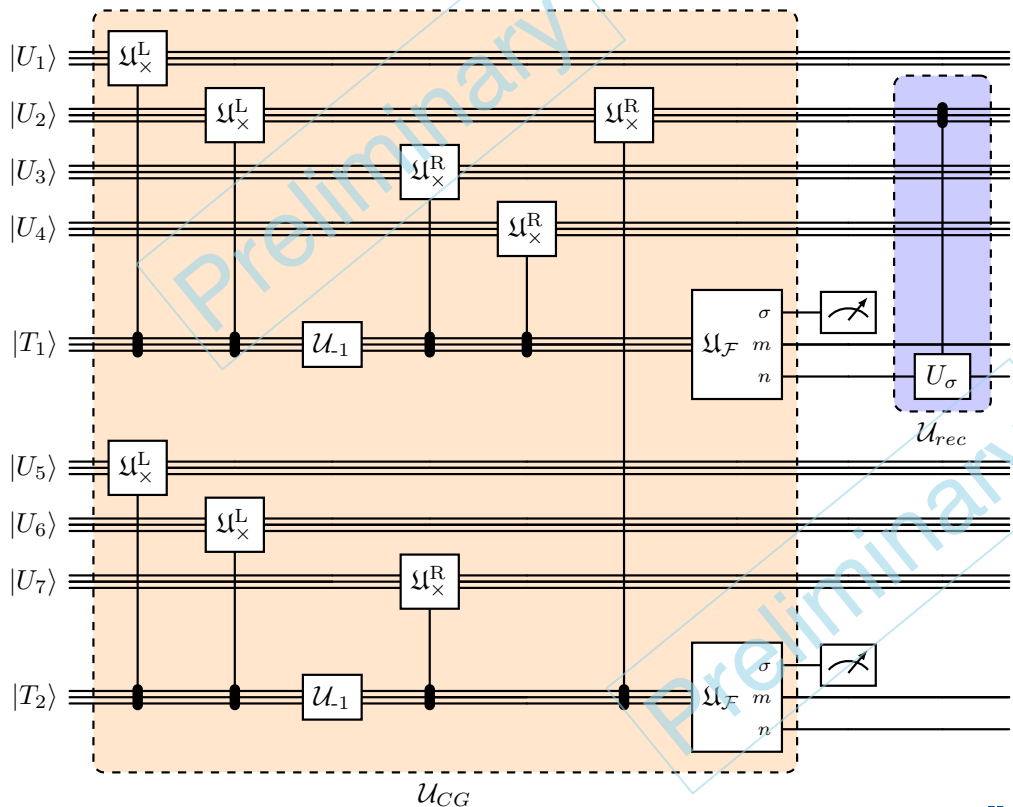
$\hat{\Gamma}_\sigma$ creates flux pair
Correctable

\hat{L}_g creates no flux
(Abelian center)
or 1 flux (non-Abelian)
Not Correctable

Gauss's law measurement and recovery



$$|T\rangle = \frac{1}{|G|} \sum_{g \in G} |g\rangle$$



When does redundancy create more errors than it can correct?



- Total error rate ϵ per group register independently.

Gauge-fixed

$$\mathcal{H}_{\text{full}} = \mathcal{H}_{\text{code}} = \mathcal{H}_{\text{inv}}$$

Quantum fidelity

$$F_{\text{fixed}} \geq (1 - \epsilon)^{N_L - N_T}$$

Gauge-redundant

$$\mathcal{H}_{\text{full}} = \mathcal{H}_{\text{gauge}}$$

Quantum fidelity

$$F_{\text{redundant}} \geq (1 - \epsilon)^{N_L}$$

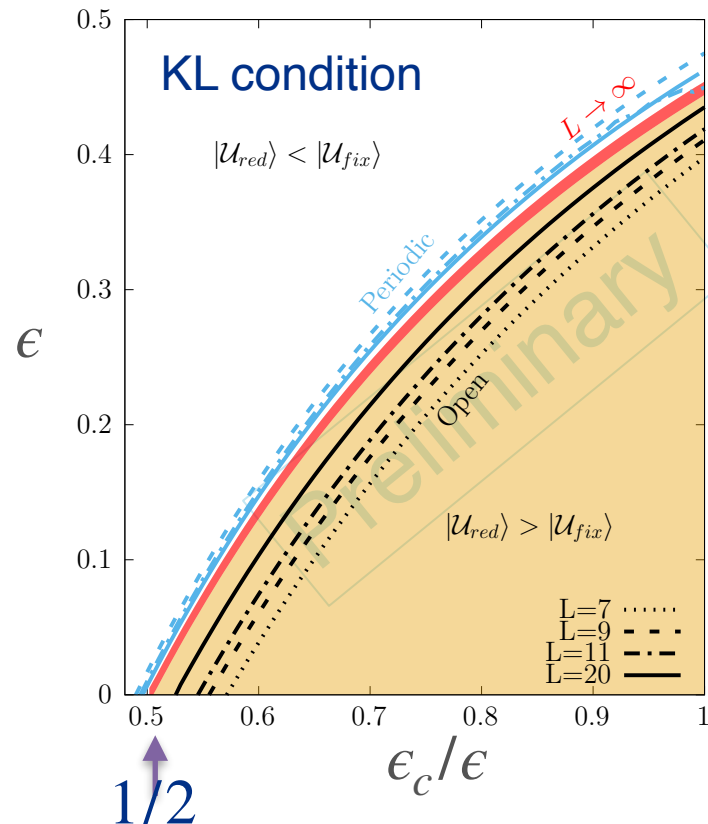
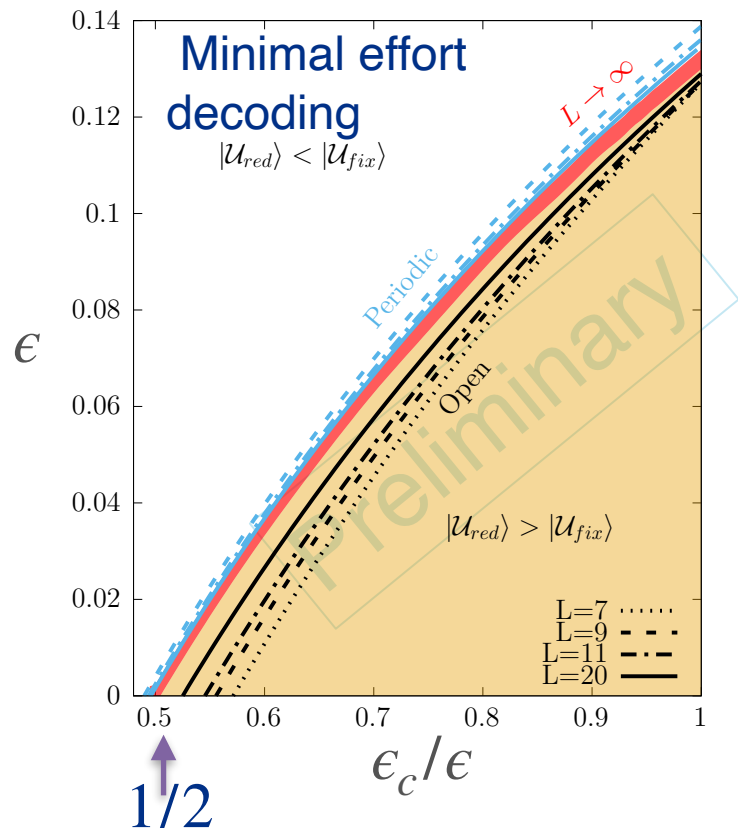
$$\mathcal{H}_{\text{code}} = \mathcal{H}_{\text{inv}}$$

Restore gauge symmetry

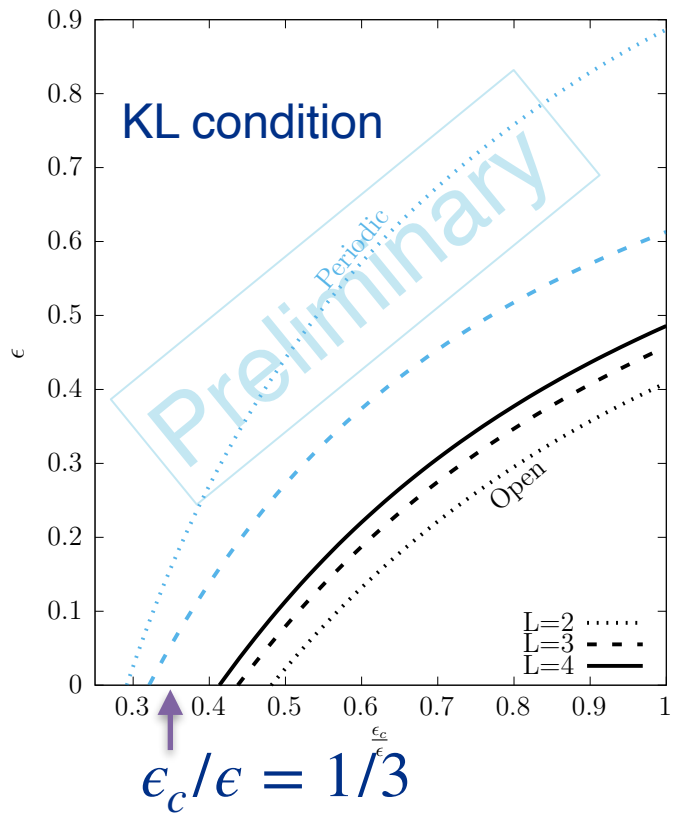
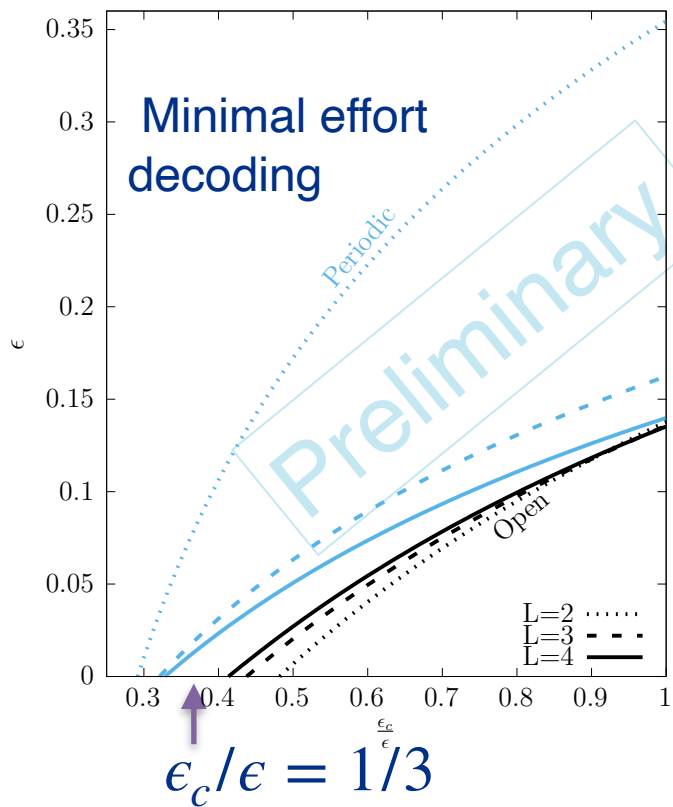
$$F_{\text{restored}} \geq \sum_{n=0}^{N_L} Q_n \epsilon_c^n (1 - \epsilon)^{N_L - n}$$

- Γ_σ -type (correctable type) error rate $\epsilon_c \leq \epsilon$.
- Q_n : # of ways to put n Γ_σ -type errors, s.t. they are still correctable.

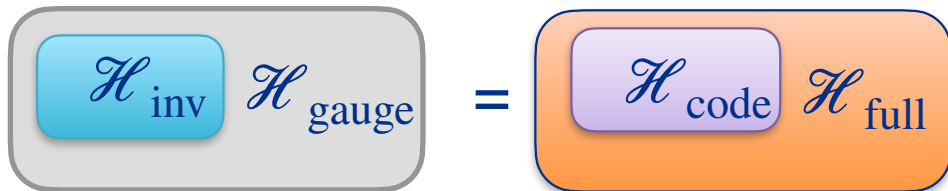
The error thresholds: when lower bounds $F_{\text{restored}} \geq F_{\text{fixed}}$ ($d=2$)



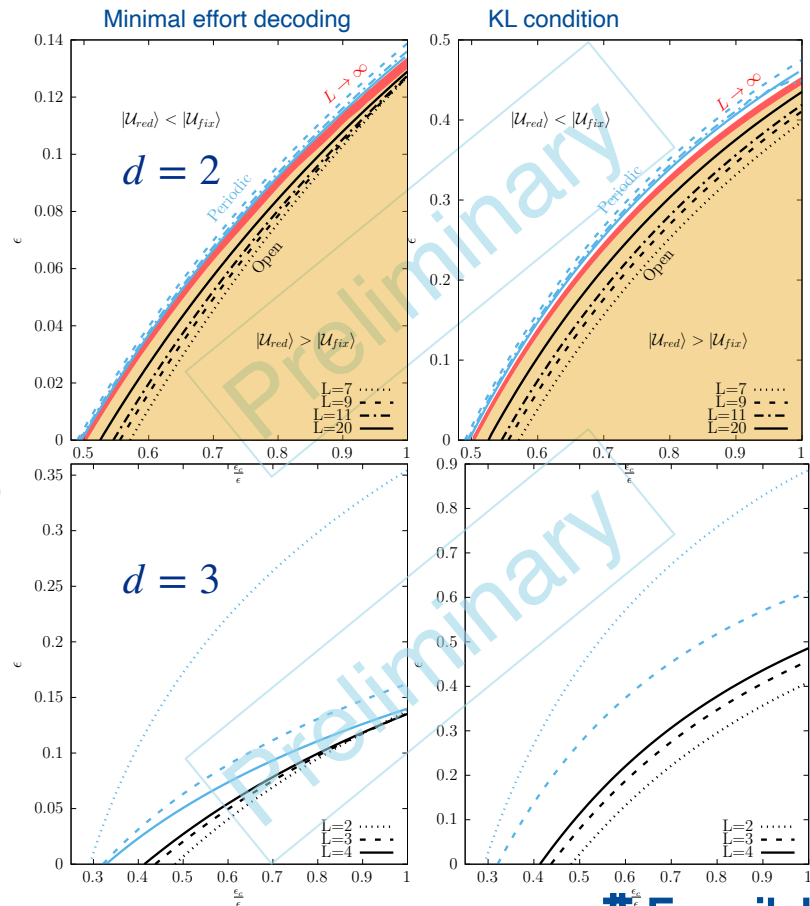
The error thresholds: when lower bounds $F_{\text{restored}} \geq F_{\text{fixed}}$ ($d=3$)



Summary



- When $\epsilon_c/\epsilon > 1/d$, there is a threshold total error rate, below which $F_{\text{restored}} \geq F_{\text{fixed}}$.
- Encoding and decoding methods in the paper to appear.
- Future works:
 - Different digitization
 - Error models.
 - Concatenation with other QEC.
 - Post-selection



Correctable errors with gauge redundancy

» $\{\hat{L}_g \hat{\Gamma}_\sigma, g \in G, \sigma \in \hat{G}\}$ — a complete basis for operators in $\mathcal{H}_G = \text{span}\{|U\rangle, U \in G\}$

$$\mathbf{x} \text{ ————— } \mathbf{x} + \mathbf{i}$$

Type	Definition (group element basis)	Qubit counterpart $G = Z_2$	Gauge symmetry at $\mathbf{x}, \mathbf{x} + \mathbf{i}$	Correctability with gauge symmetry
Group multiplication	$\hat{L}_g = \sum_{U \in G} gU\rangle\langle U $	X	Both preserved for g in the Abelian center; Otherwise broken only at \mathbf{x}	No
Representation matrix element	$\hat{\Gamma}_{\sigma, m, n} = \sum_{U \in G} \sqrt{d_\sigma} \Gamma_{mn}^{(\sigma)}(U)^* U\rangle\langle U $	Z	Both broken $\mathbf{x}_{\sigma_m} \text{ ————— } \mathbf{x}_{\sigma_n^*} + \mathbf{i}$	Yes $\hat{P}_{\text{inv}} \hat{\Gamma}_\sigma^\dagger \hat{\Gamma}_{\sigma'} \hat{P}_{\text{inv}} = \delta_{\sigma, \sigma'} \hat{P}_{\text{inv}}$