

Toward Contour Deformation for 4d Gauge Theories

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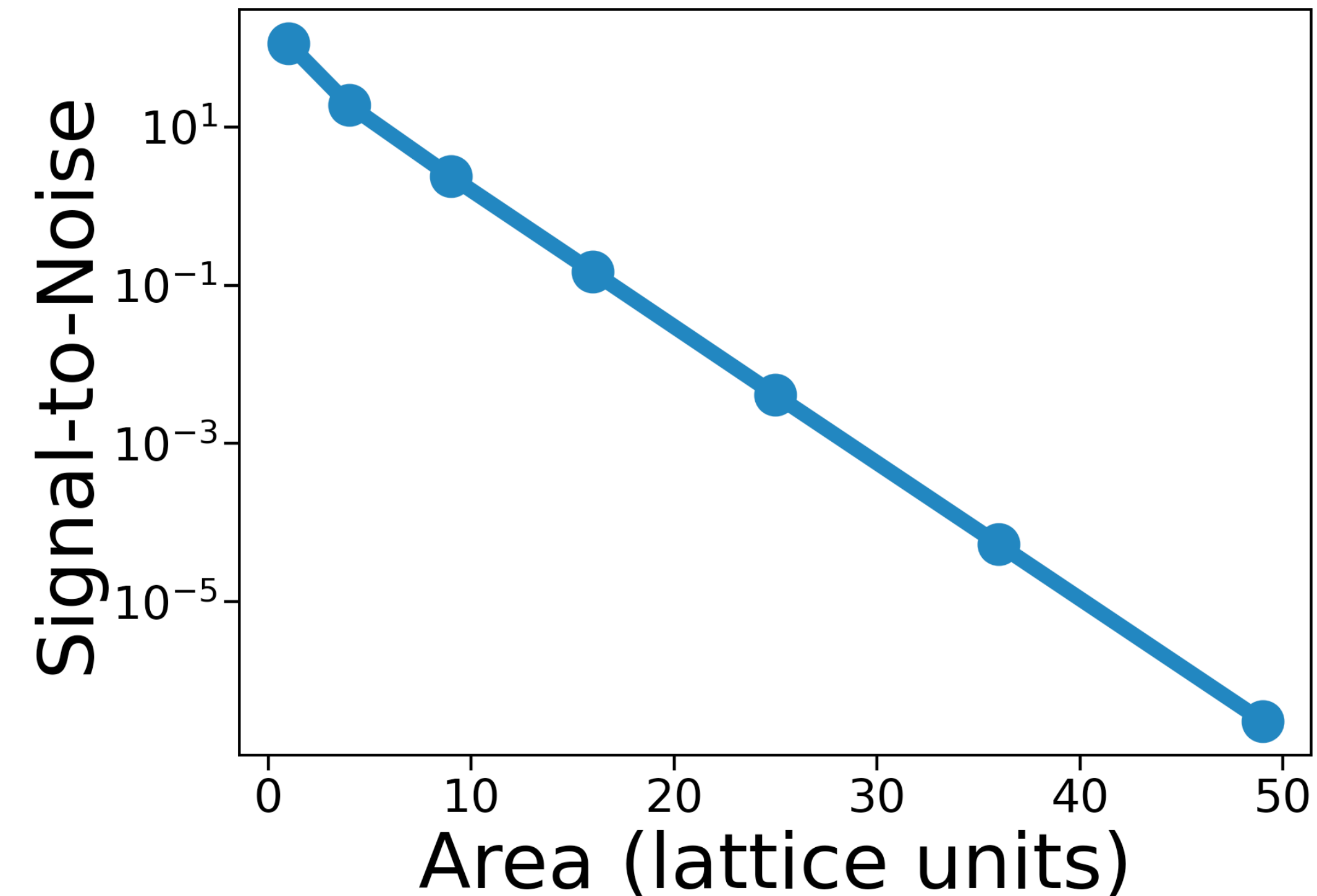


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Technology



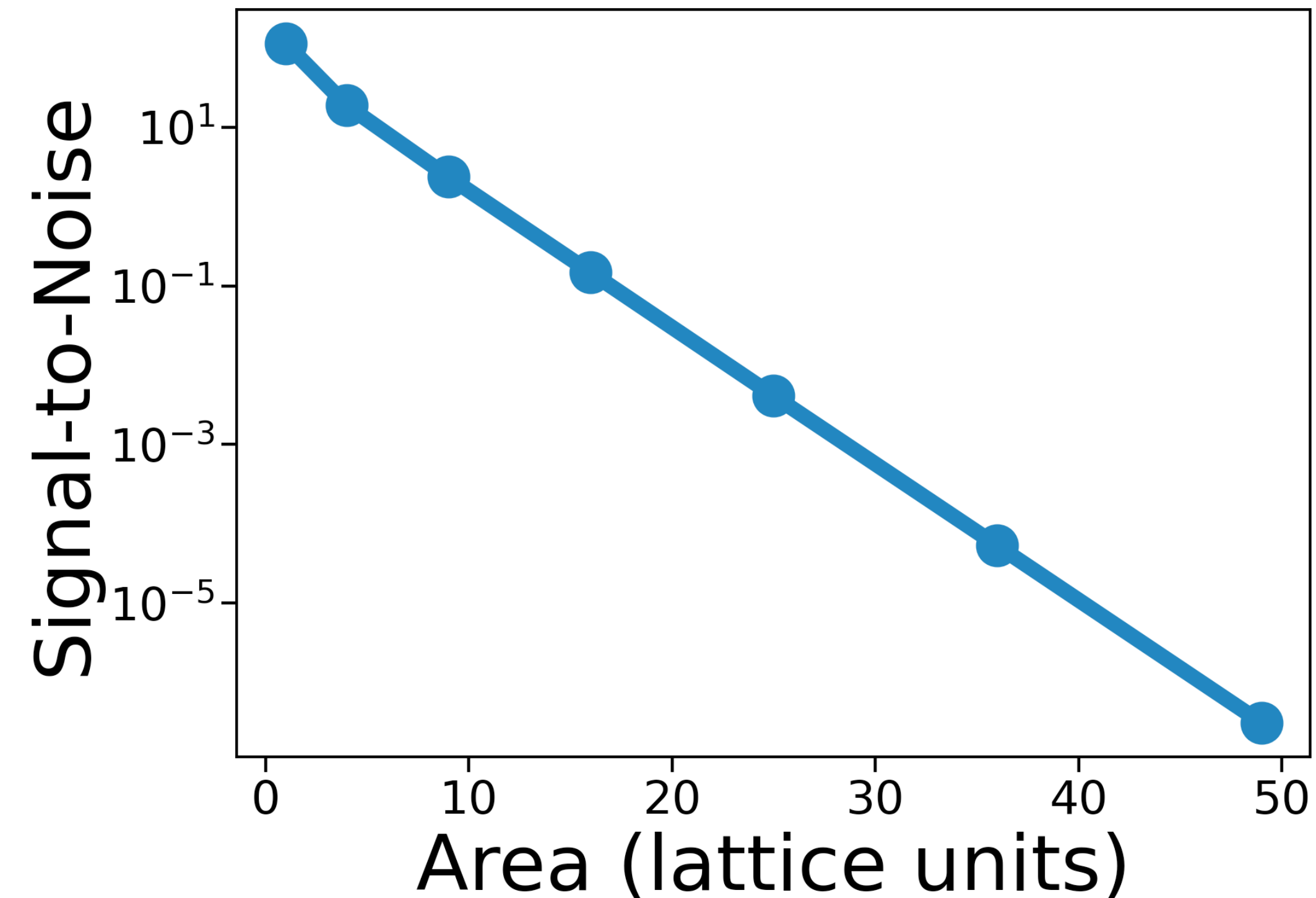
Signal-to-noise problems in LGT

Ubiquitous exponential signal-to-noise problems



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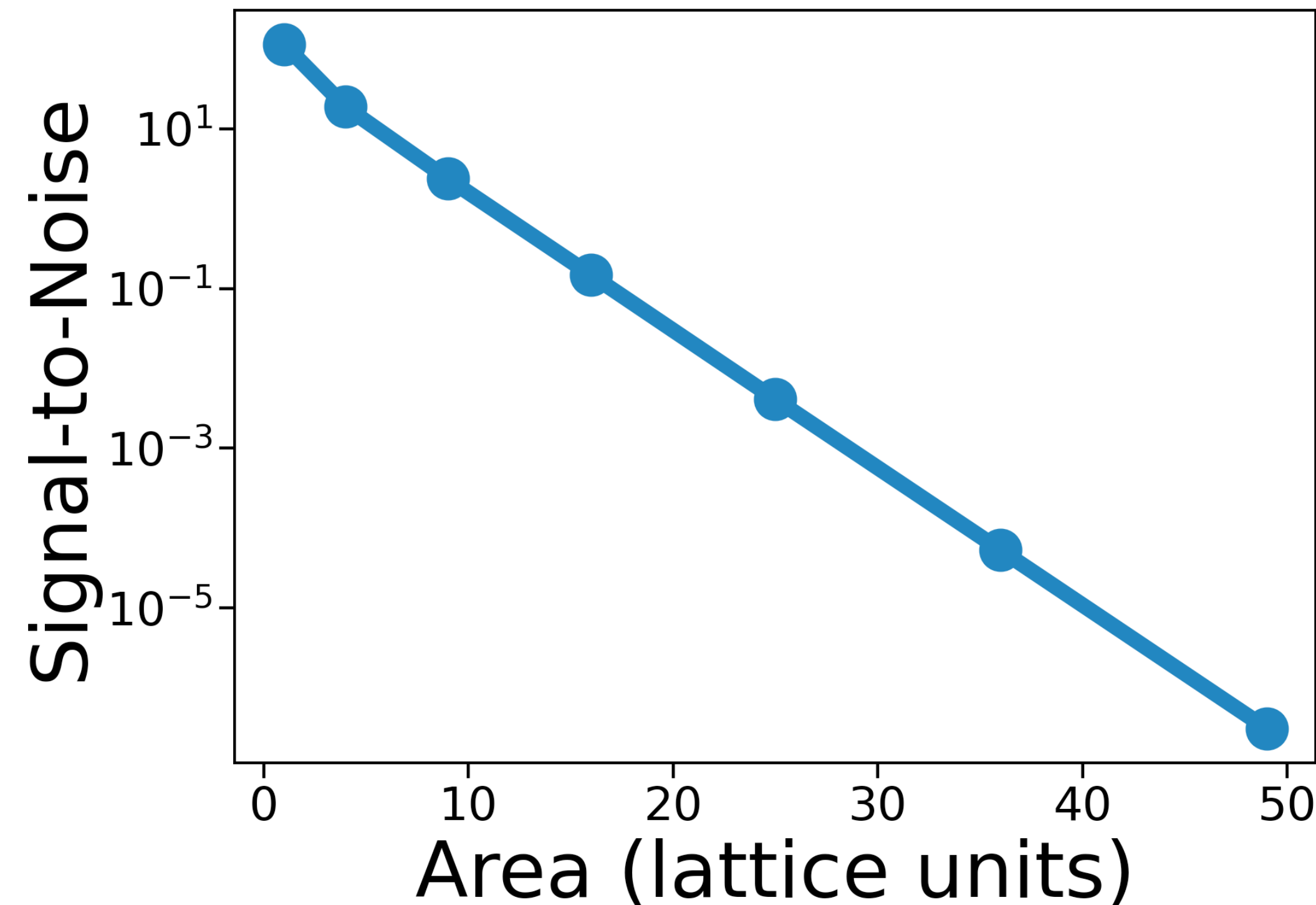
Ubiquitous exponential signal-to-noise problems



- Nucleon correlation functions
- Multi-hadron systems
- Highly boosted hadrons
- $J_{\mu}^{em} J_{\mu}^{em}$ correlation functions
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Monte Carlo measurements are complex-valued → Sign problems

[M. Wagman, M. Savage [hep-lat/1611.07643](https://arxiv.org/abs/hep-lat/1611.07643)]

Cauchy theorem and contour deformation

Can we design a “better” observable to alleviate the sign problem?

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$$\oint f(z) dz = 0$$

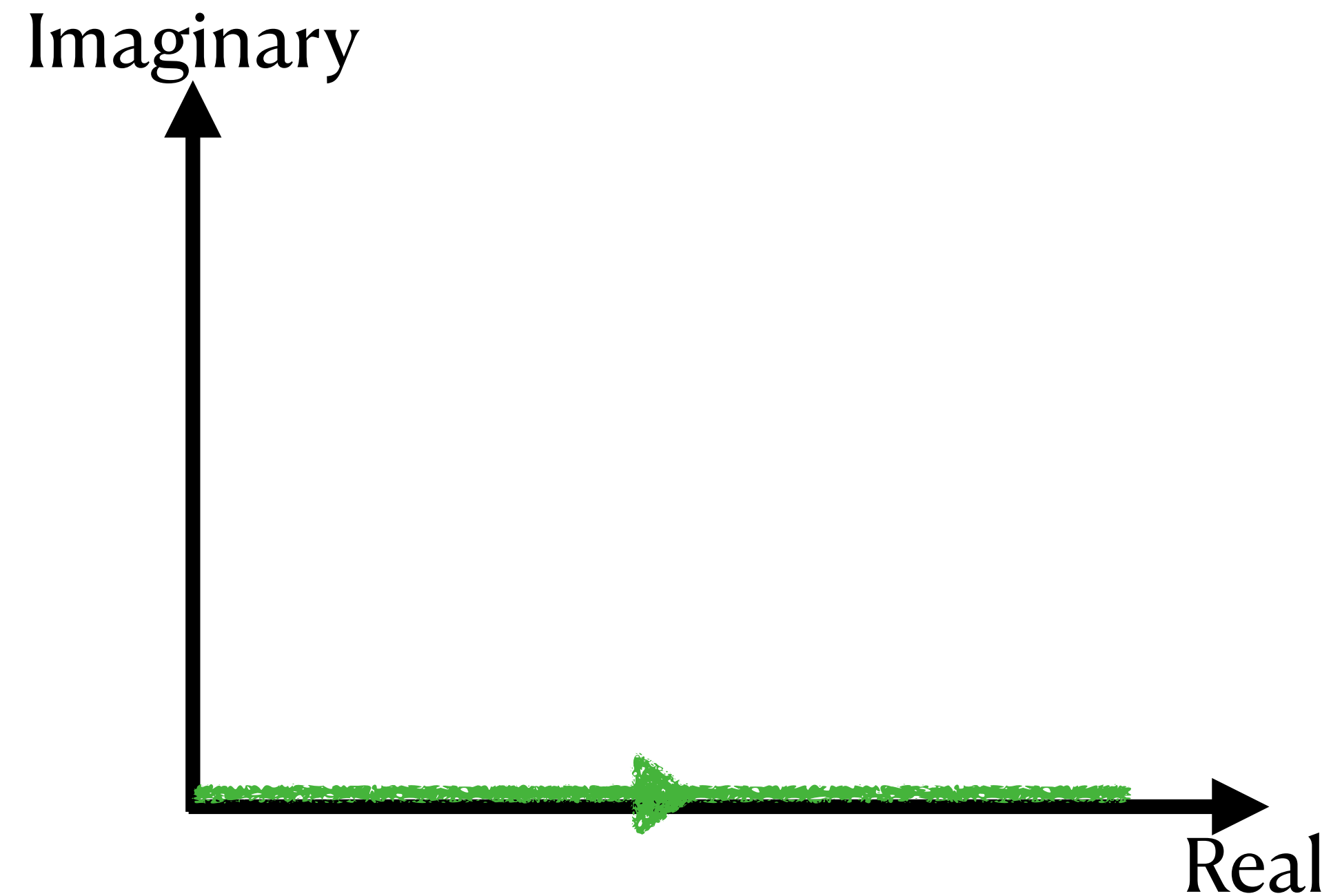
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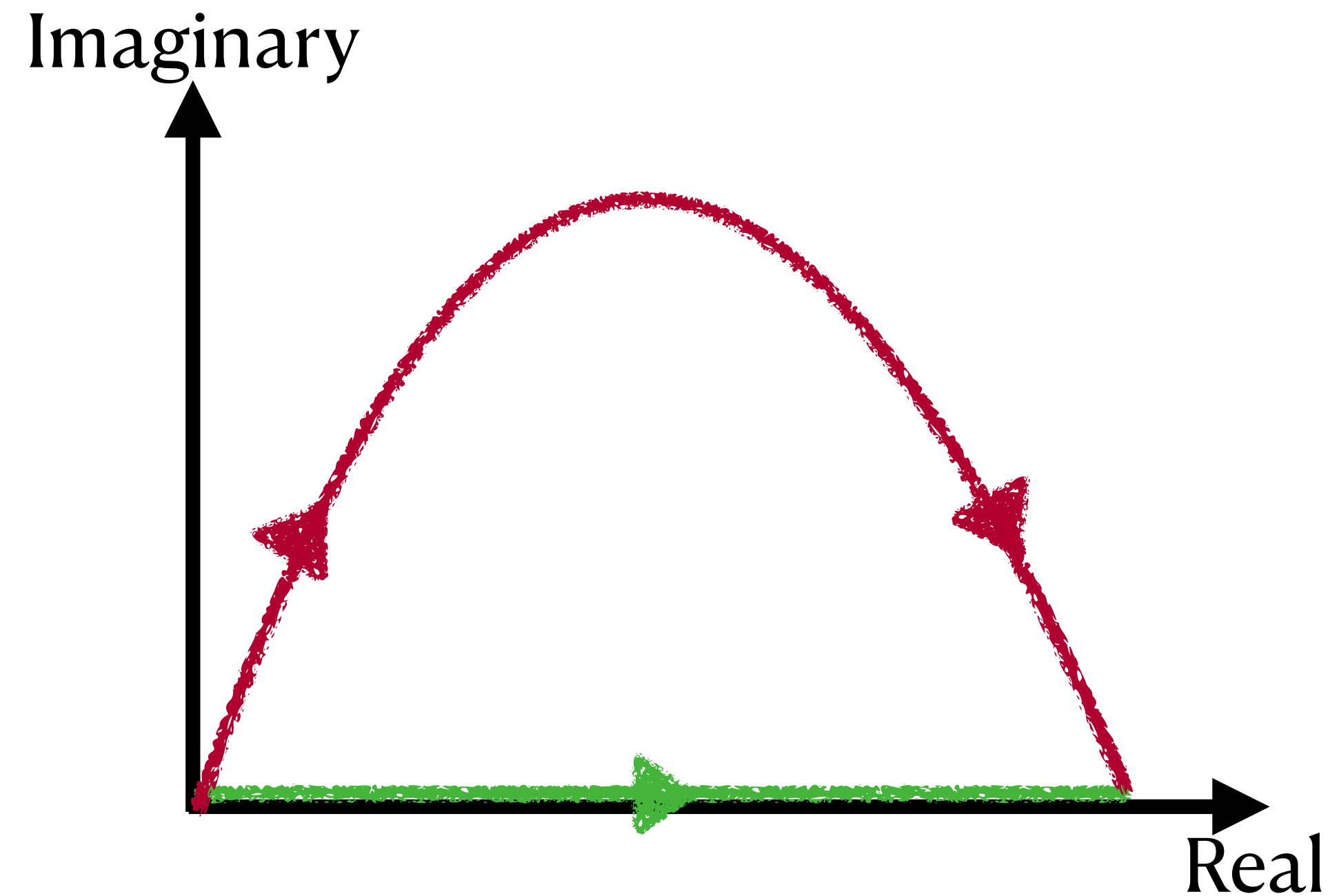
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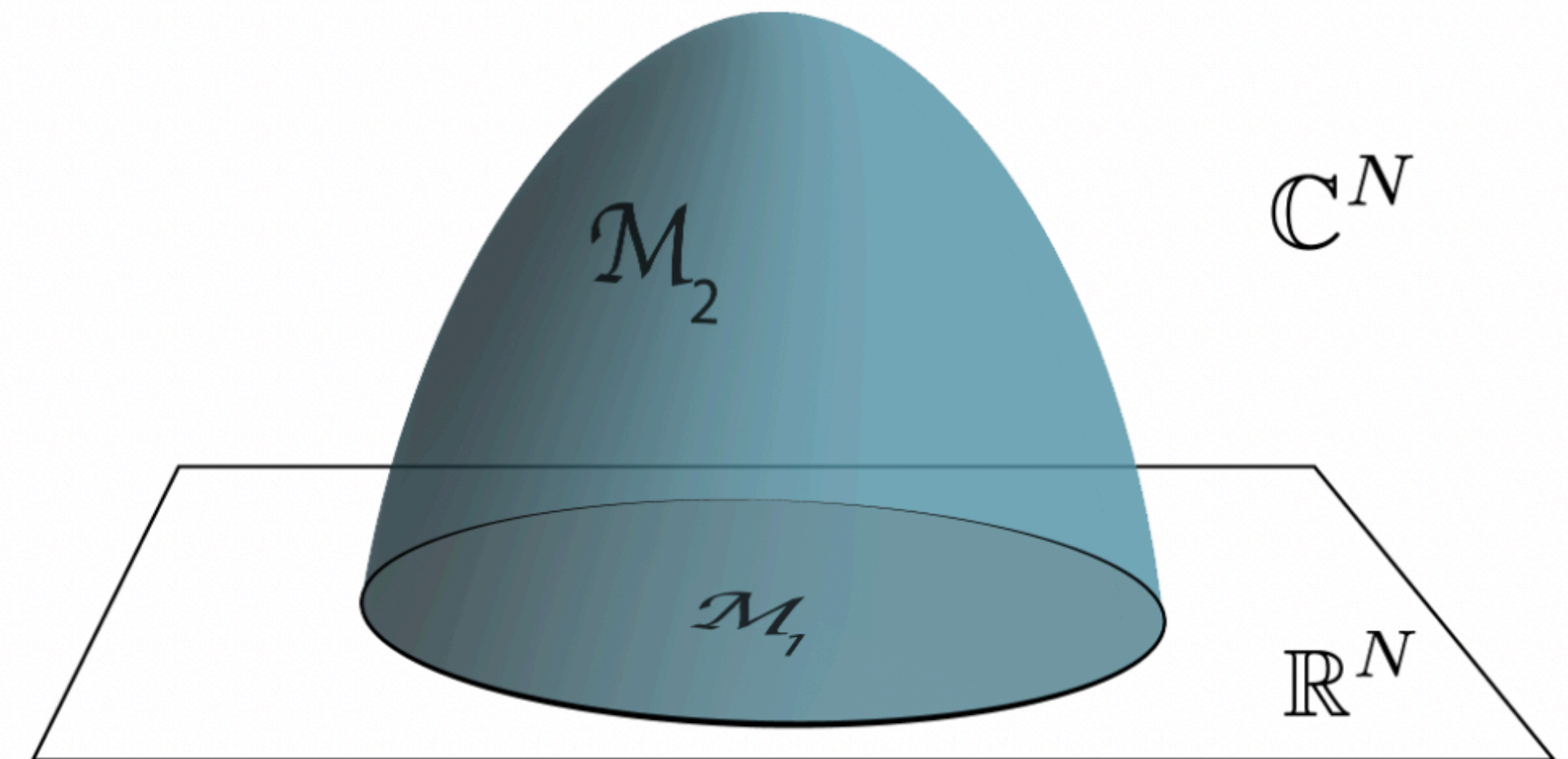
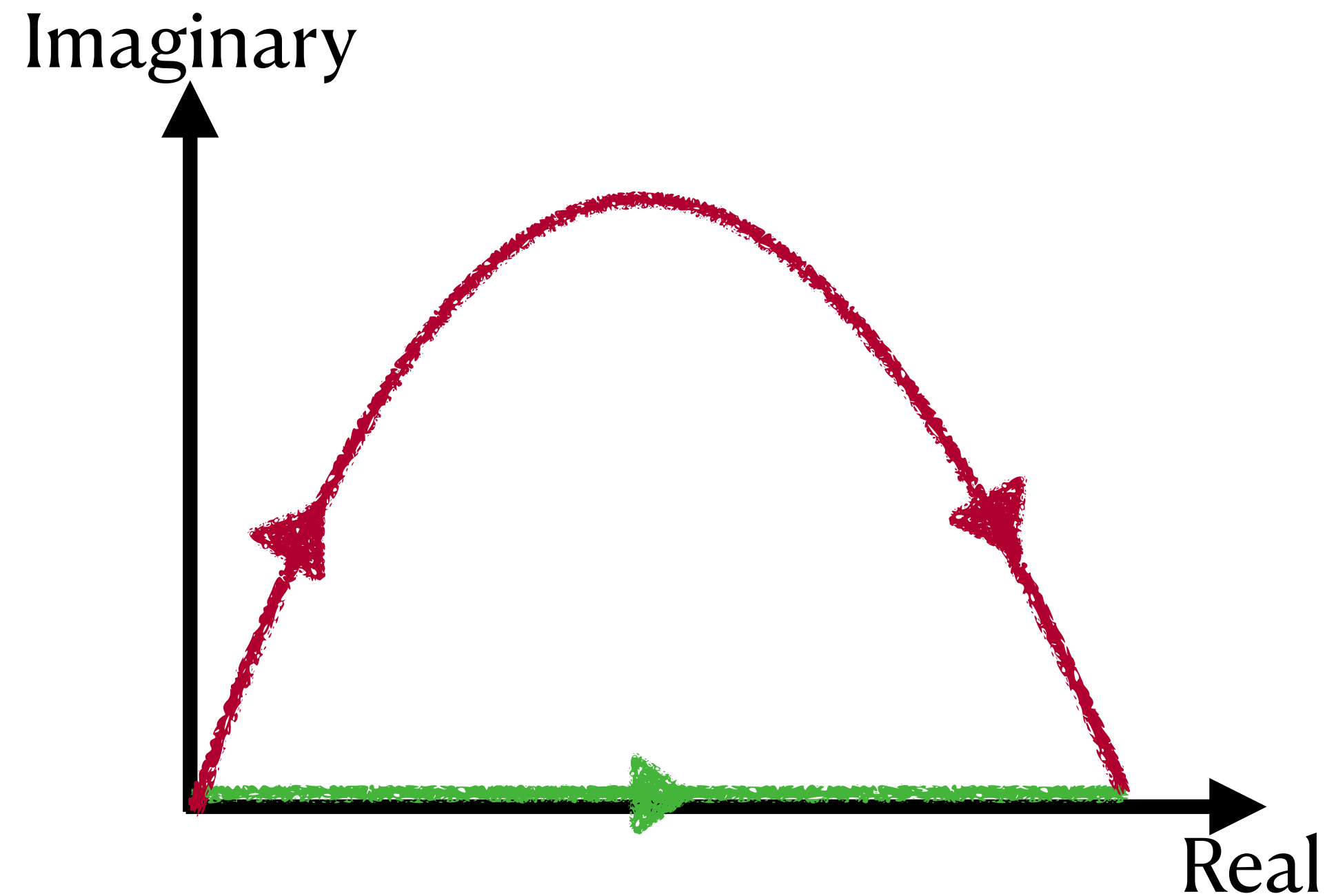
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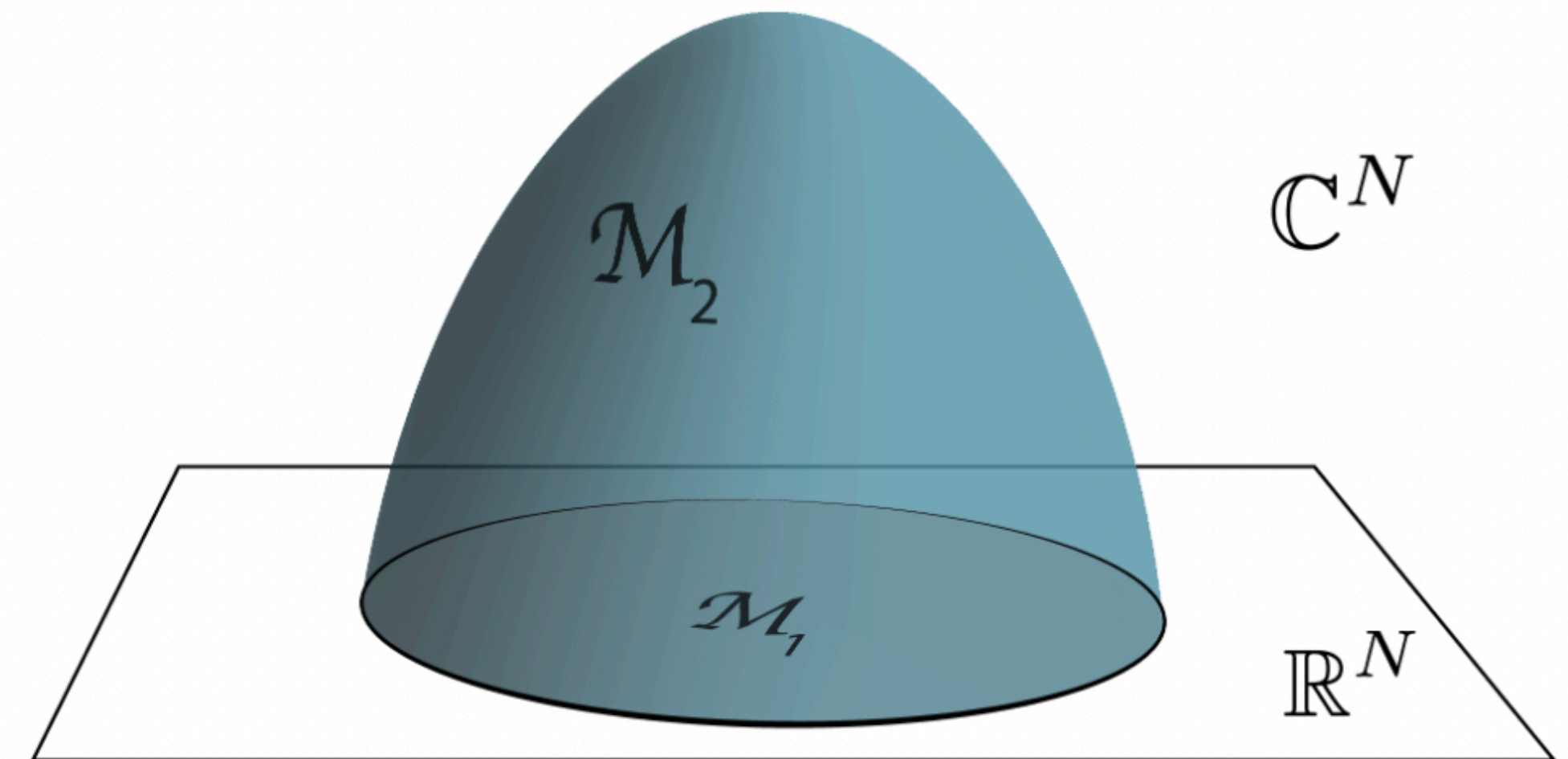
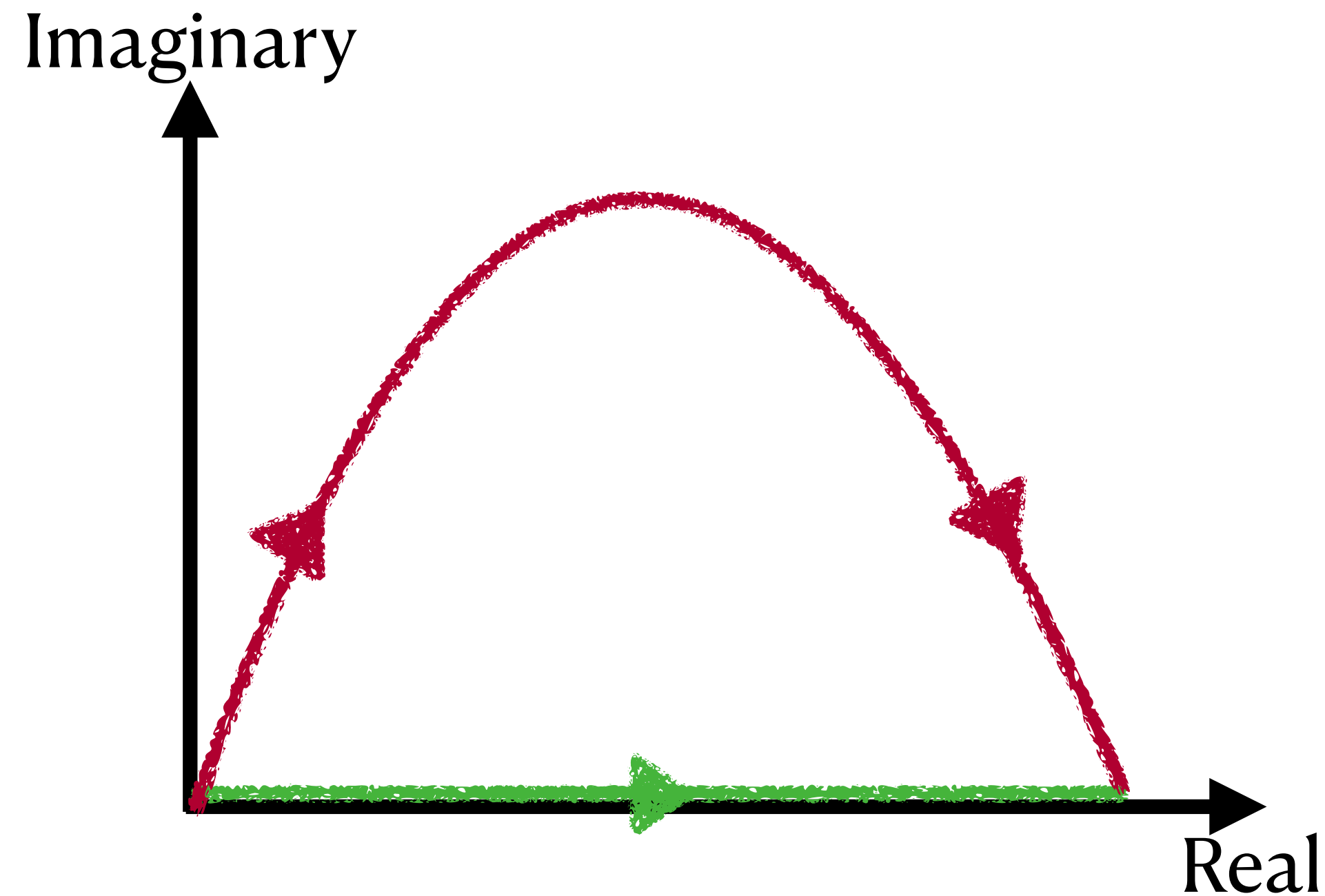
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Expectation values are **holomorphic**, while variances are **not**

Contour deforming Wilson loops

Given a deformation on gauge field $U \rightarrow \widetilde{U}$

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Wilson loop means are **holomorphic**

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Deform $U \rightarrow \widetilde{U}$ to minimize the variances while guaranteeing exactness!

Constant deformations of SU(2) and SU(3)

SU(2) Euler angles

$$U = U(\theta_1, \phi_1, \phi_2)$$

$$\theta_i \in [0, \pi/2], \phi_i \in [0, 2\pi)$$

[W. Detmold, G. Kanwar, H. Lamm, M. Wagman, N. Warrington, [hep-lat/2101.12668](https://arxiv.org/abs/hep-lat/2101.12668)]

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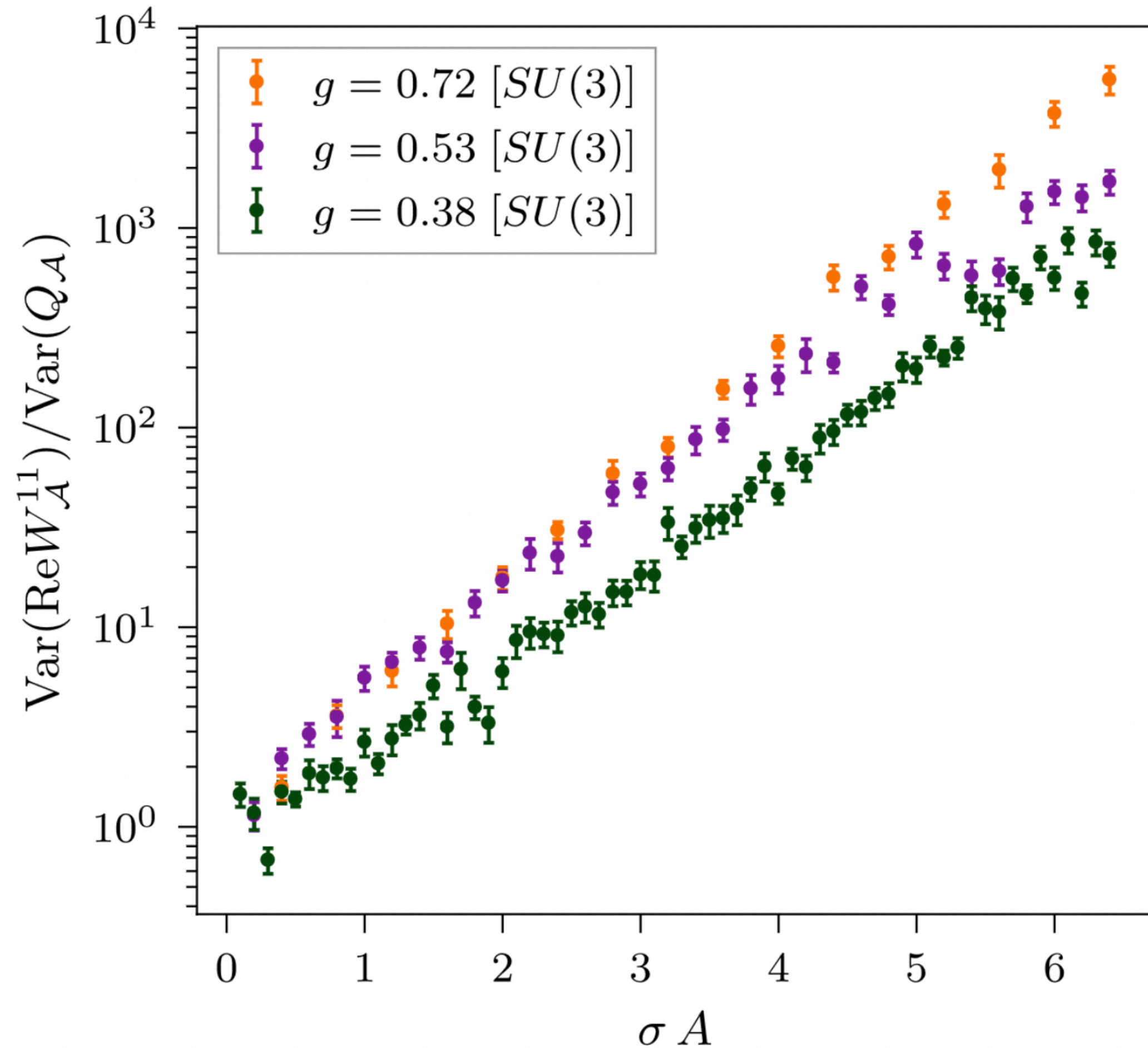
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When we put a bunch of SU(N) matrices on a lattice...

Optimize $\Delta_{i,\mu}(x, y, z)$ to minimize the observable variance

Success story so far: SU(N) in 2d

Constant deformation work **extremely** well for U(1), SU(2), and SU(3) in 2d!

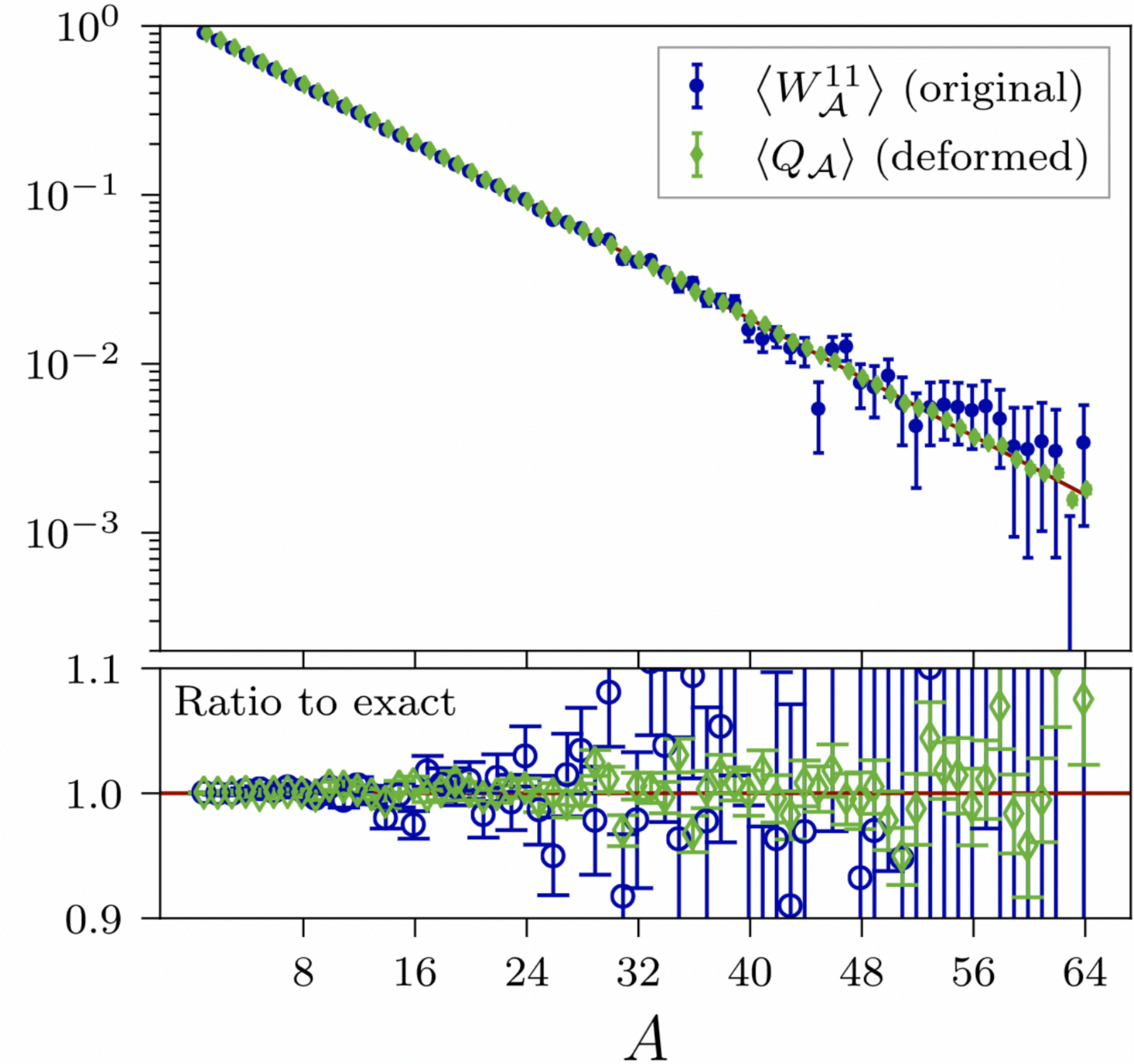
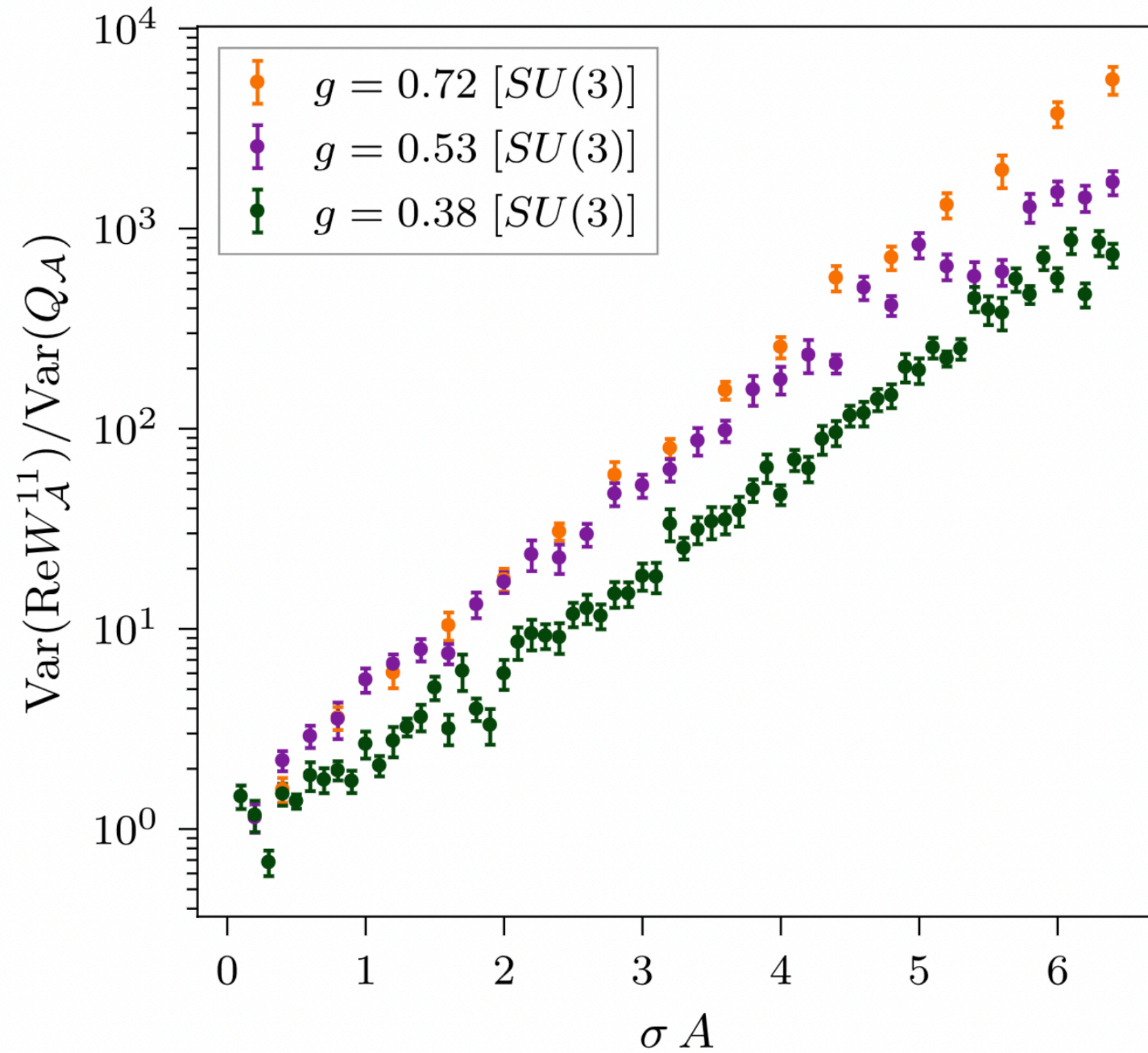


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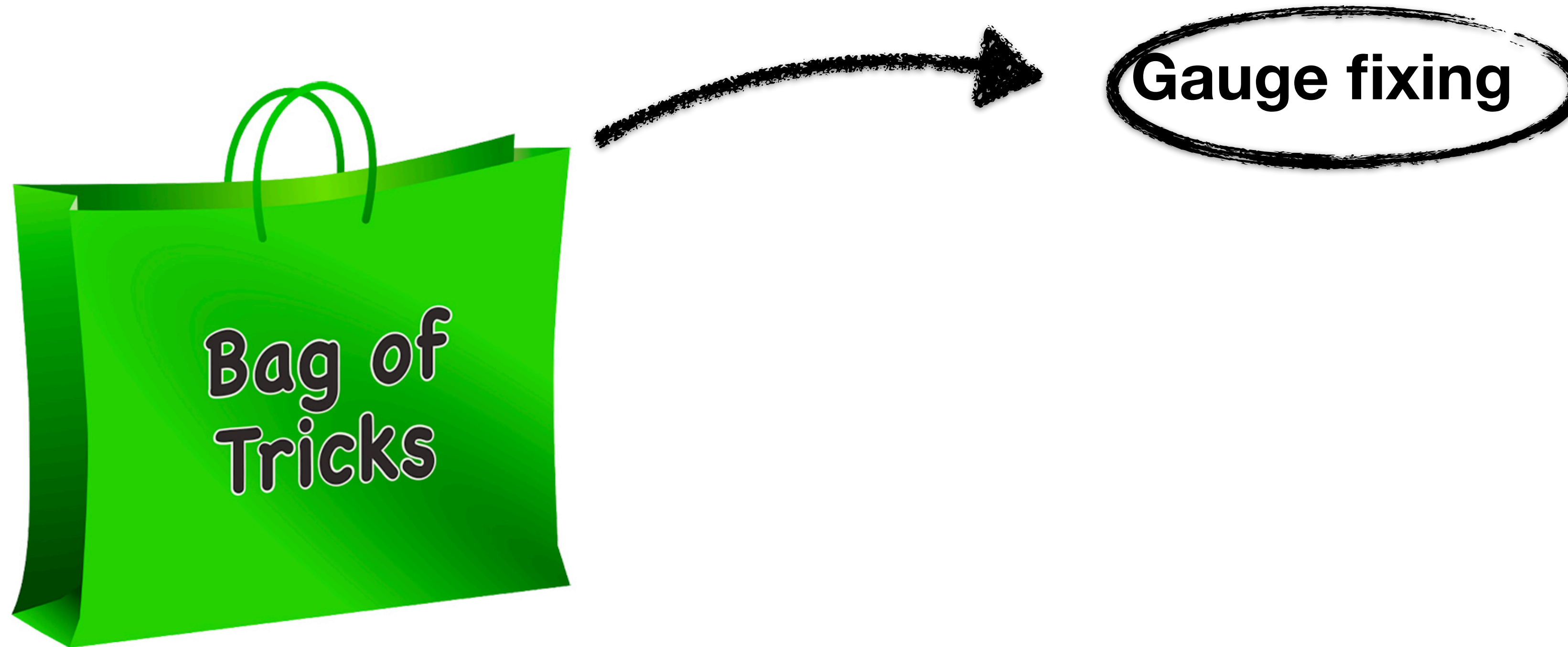
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 - ▶ Fail to decrease variance for SU(N) gauge theories if directly applying the contour deformation, $\Delta_{i,\mu}(x, y, z)$

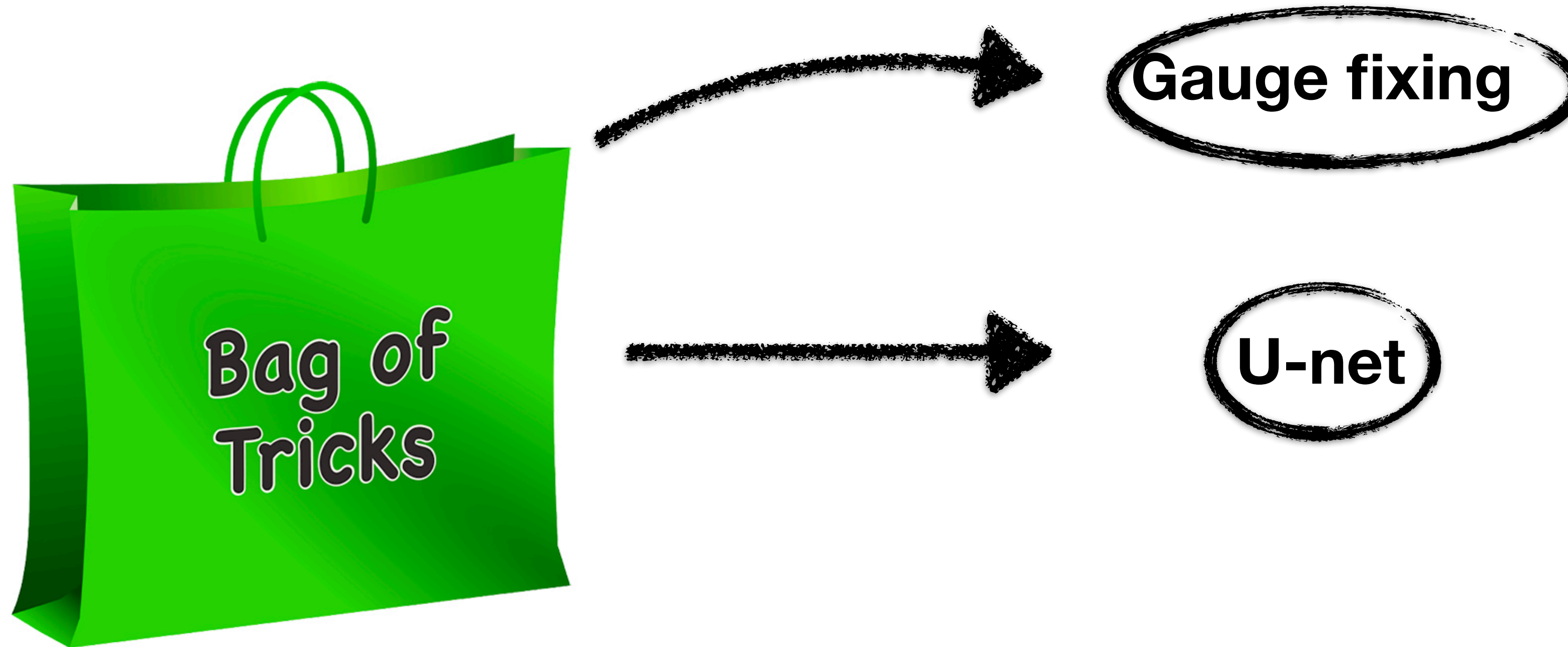
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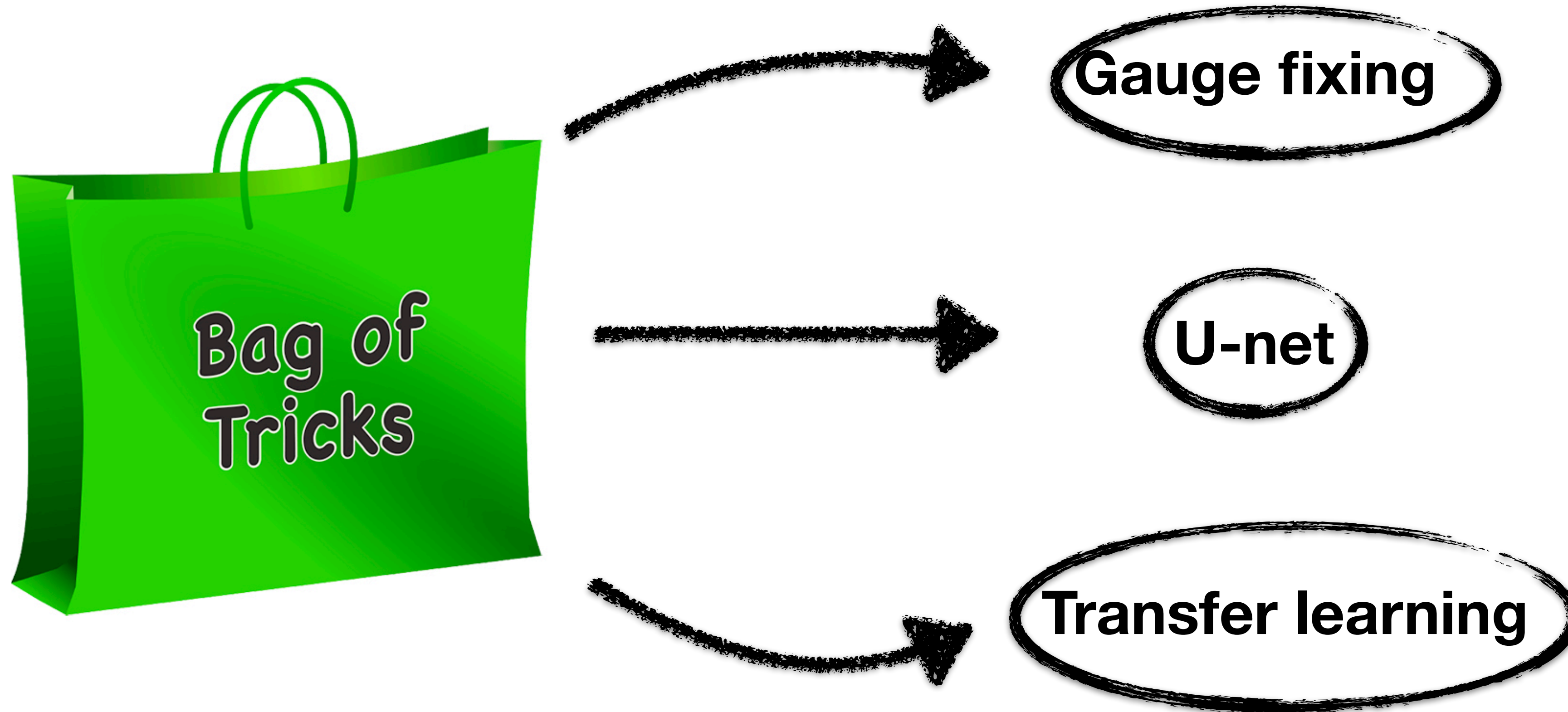
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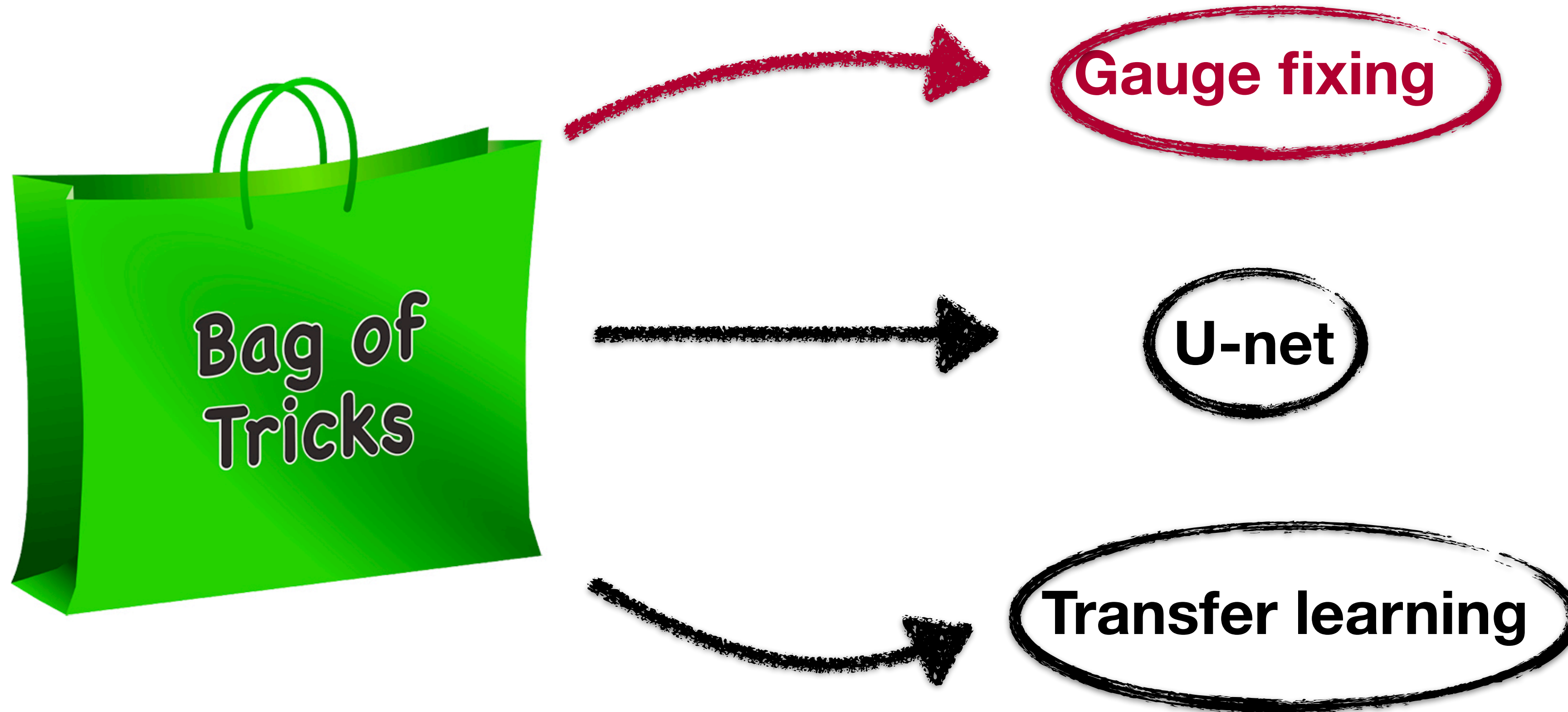
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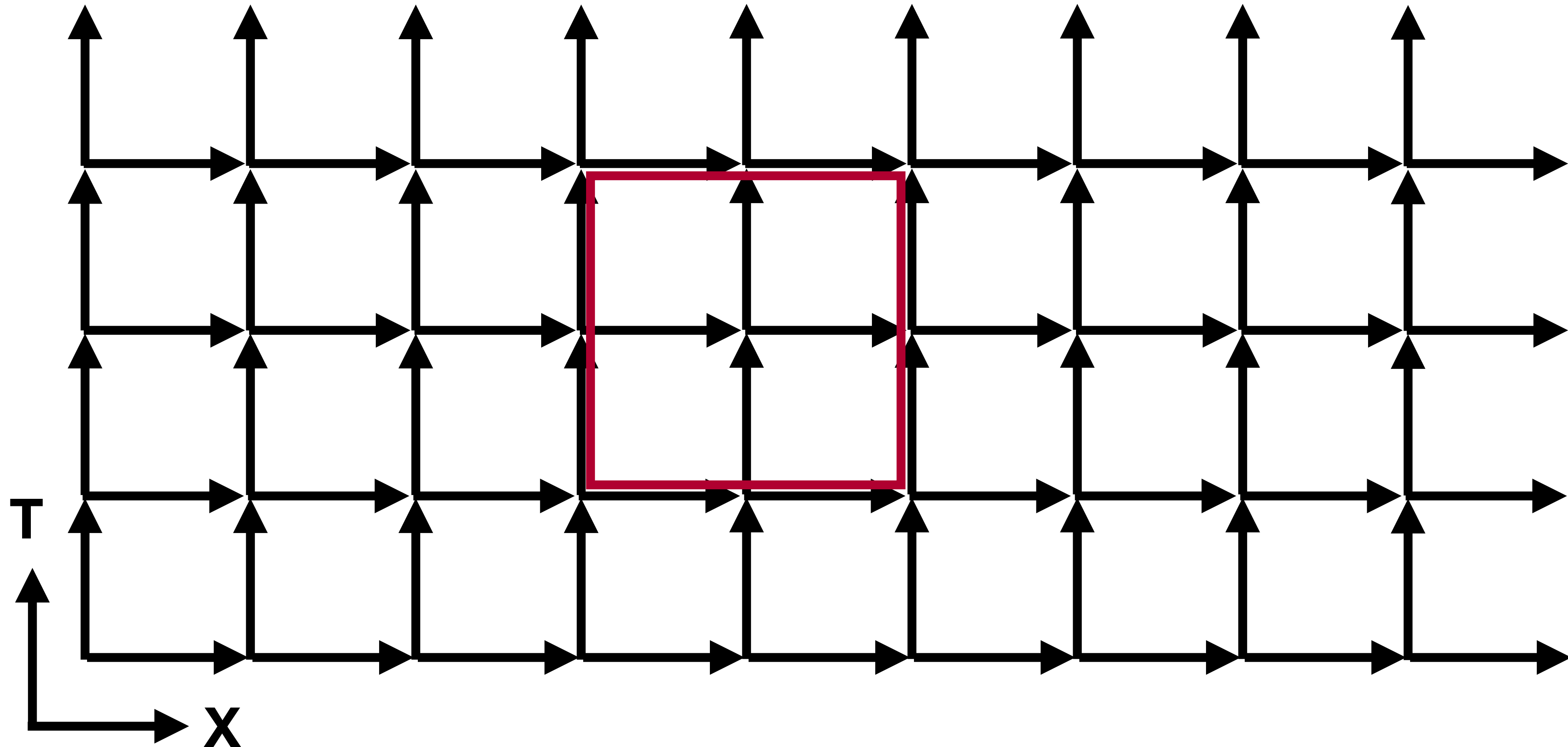


Contour deformation beyond 2d



Gauge fixing for contour deformation

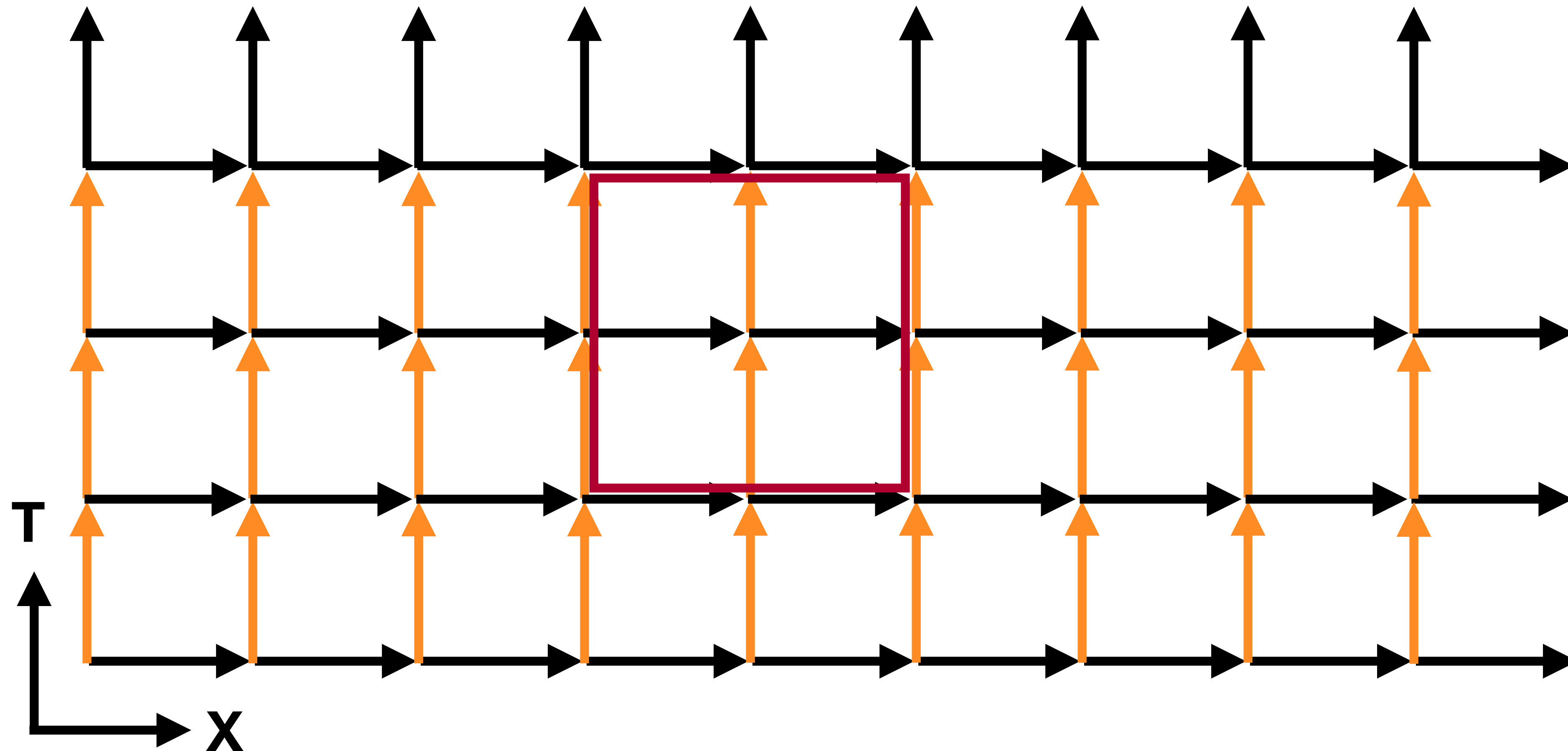
Heuristics: Reduce redundant degrees of freedom



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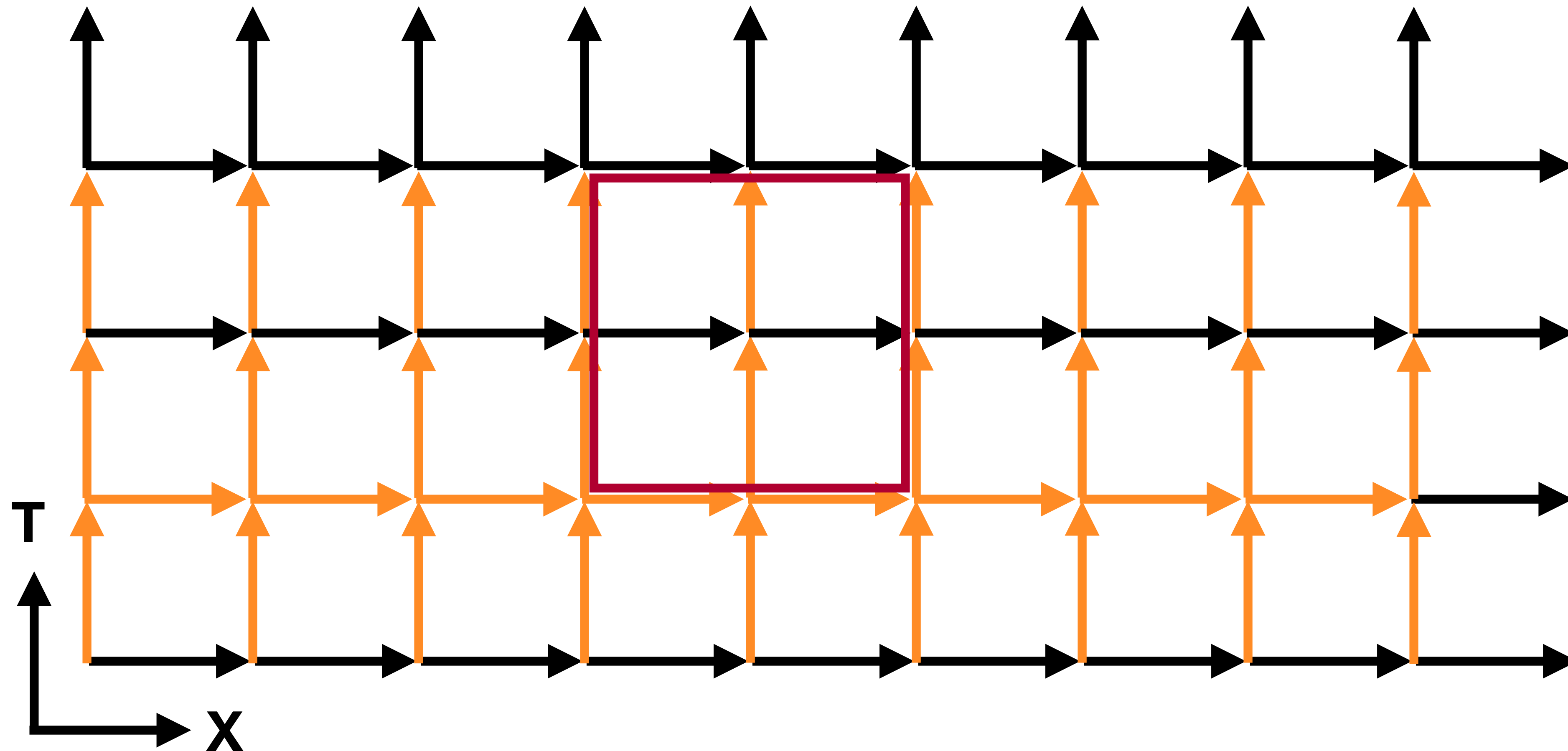
(orange links are gauge-fixed and black links are active)



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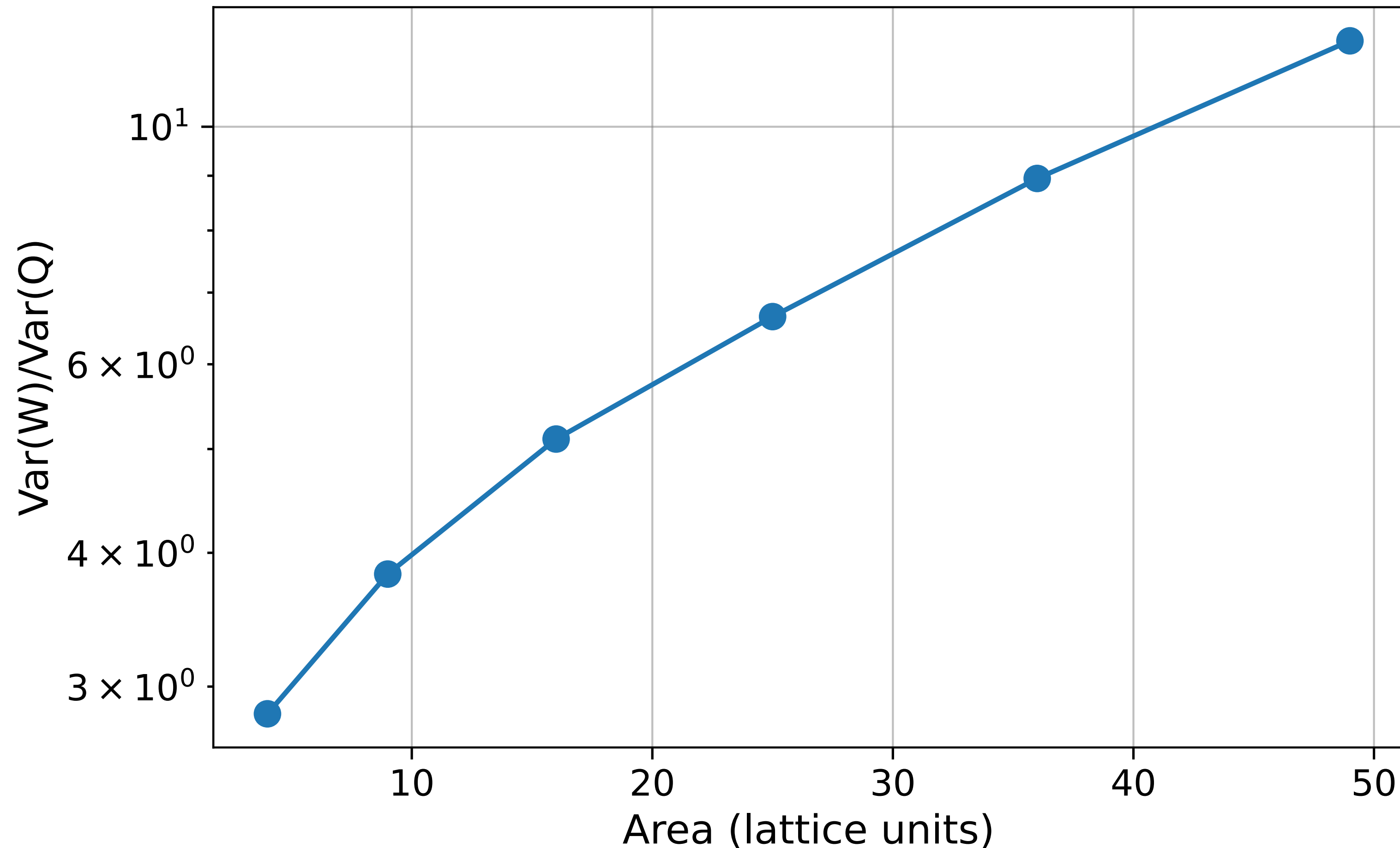
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Results with direct parametrization

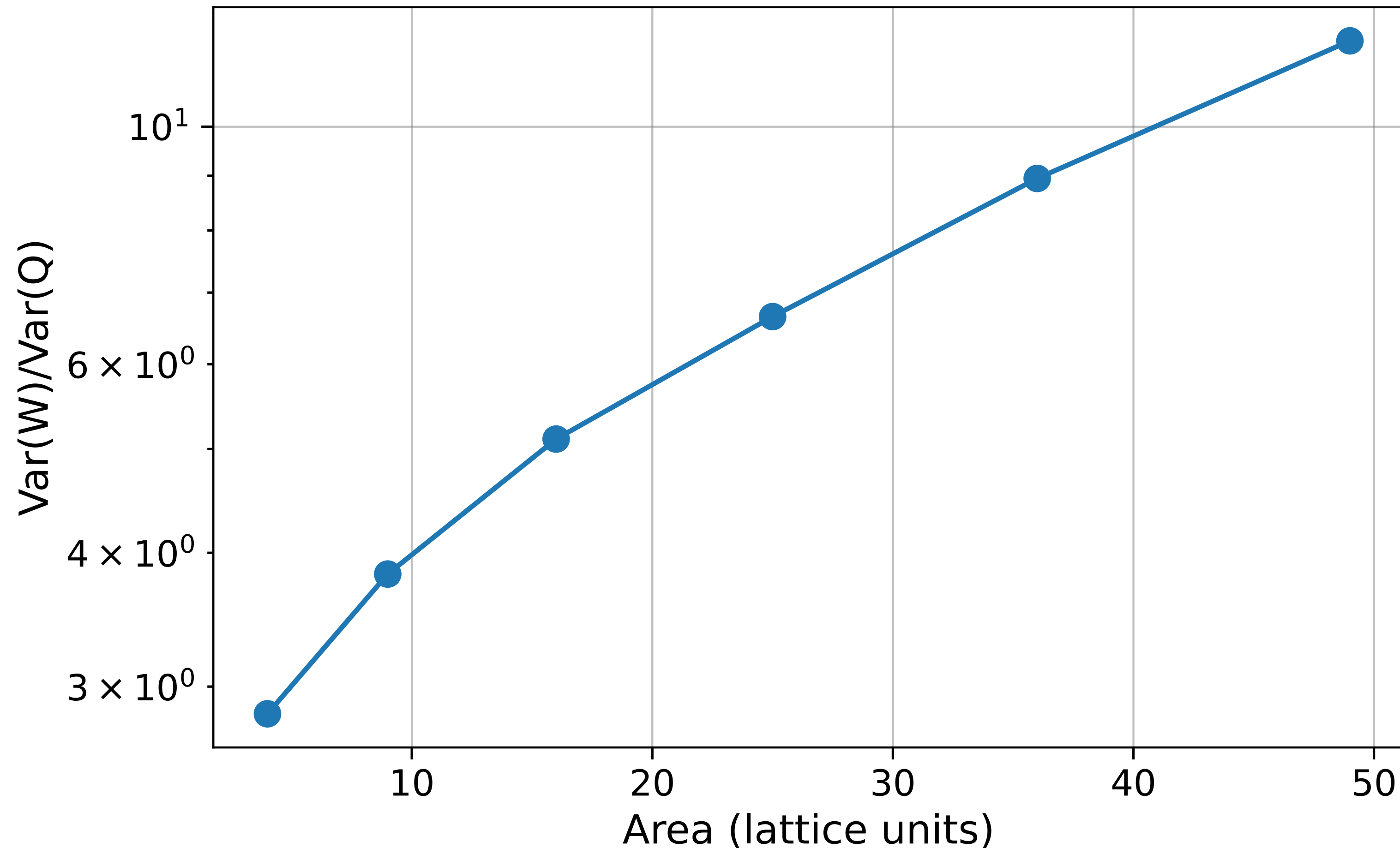
Example: SU(2), $\beta=3.75$, 8^3



► Optimizing $\Delta_{i,\mu}(x, y, z)$
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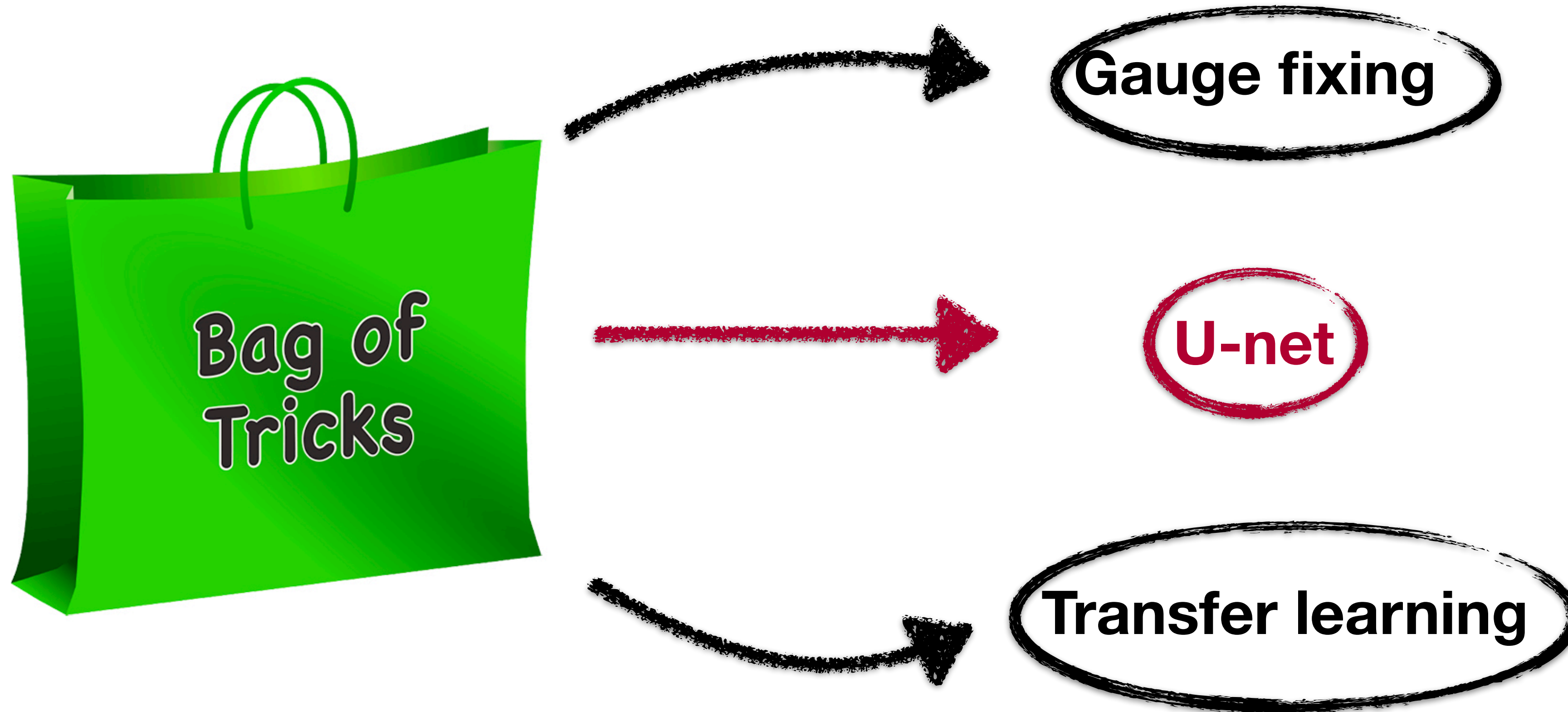
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- ▶ Optimizing $\Delta_{i,\mu}(x, y, z)$ by minimizing the variance of Wilson loops
- ▶ Smaller improvements on larger lattices

Contour deformation beyond 2d



U-net for contour deformation

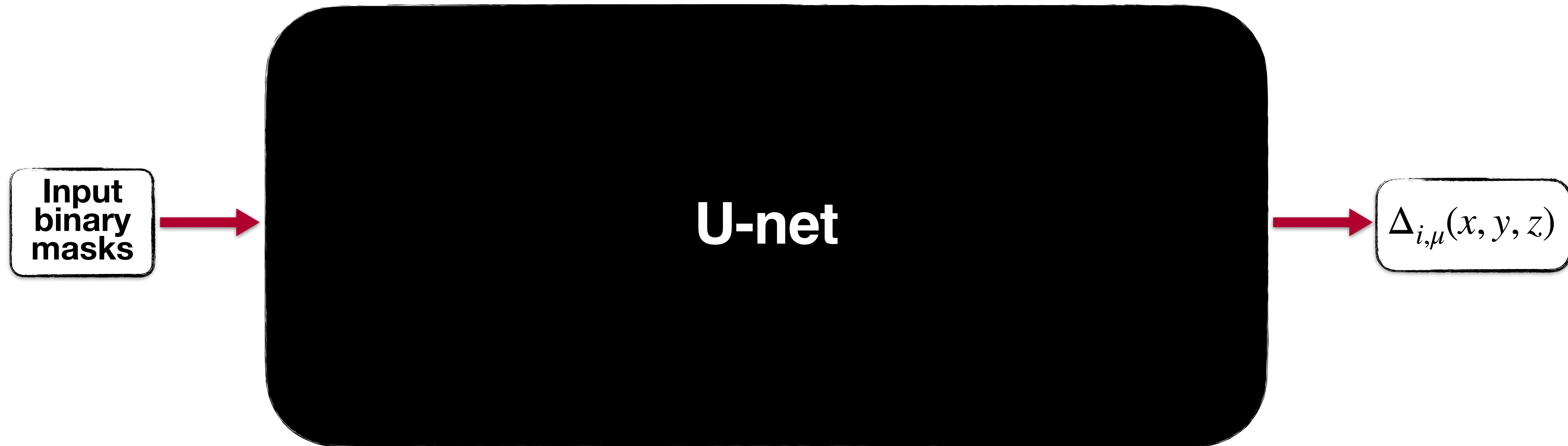
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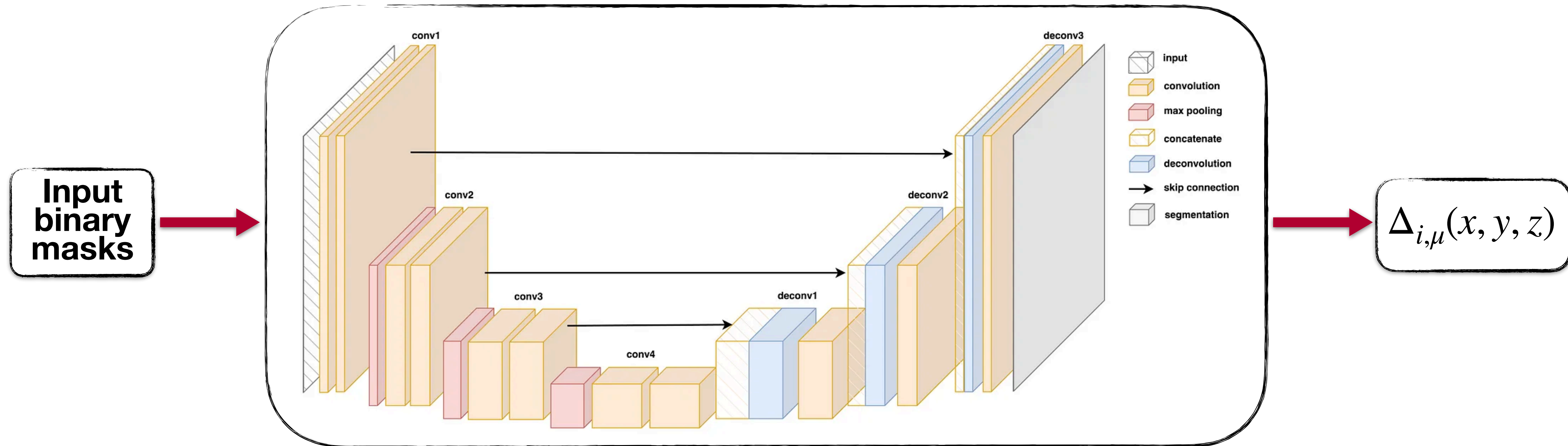


Input binary masks: encode the information of which links are **gauge fixed** and which links **lie on the Wilson loop** we aim to deform.

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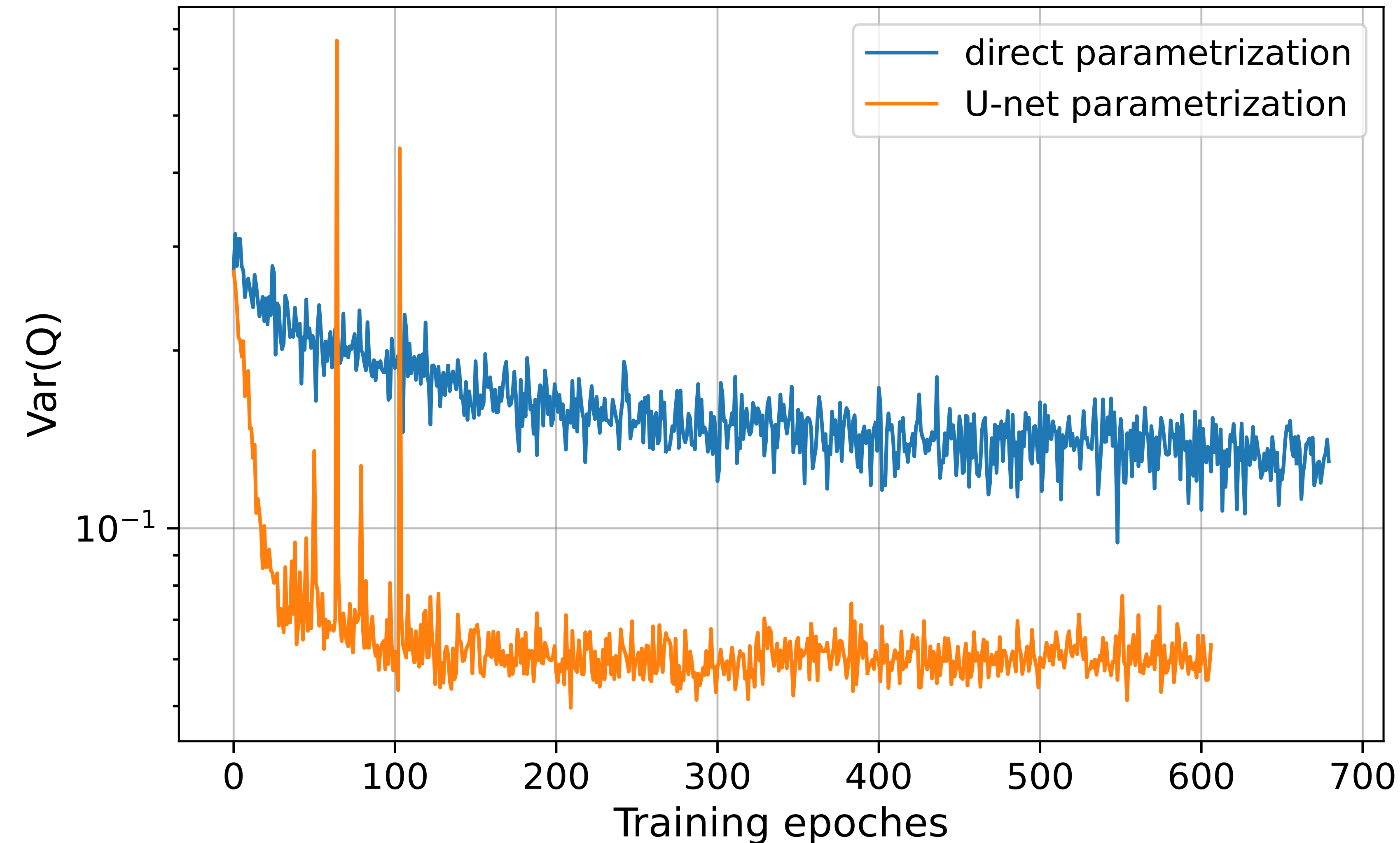
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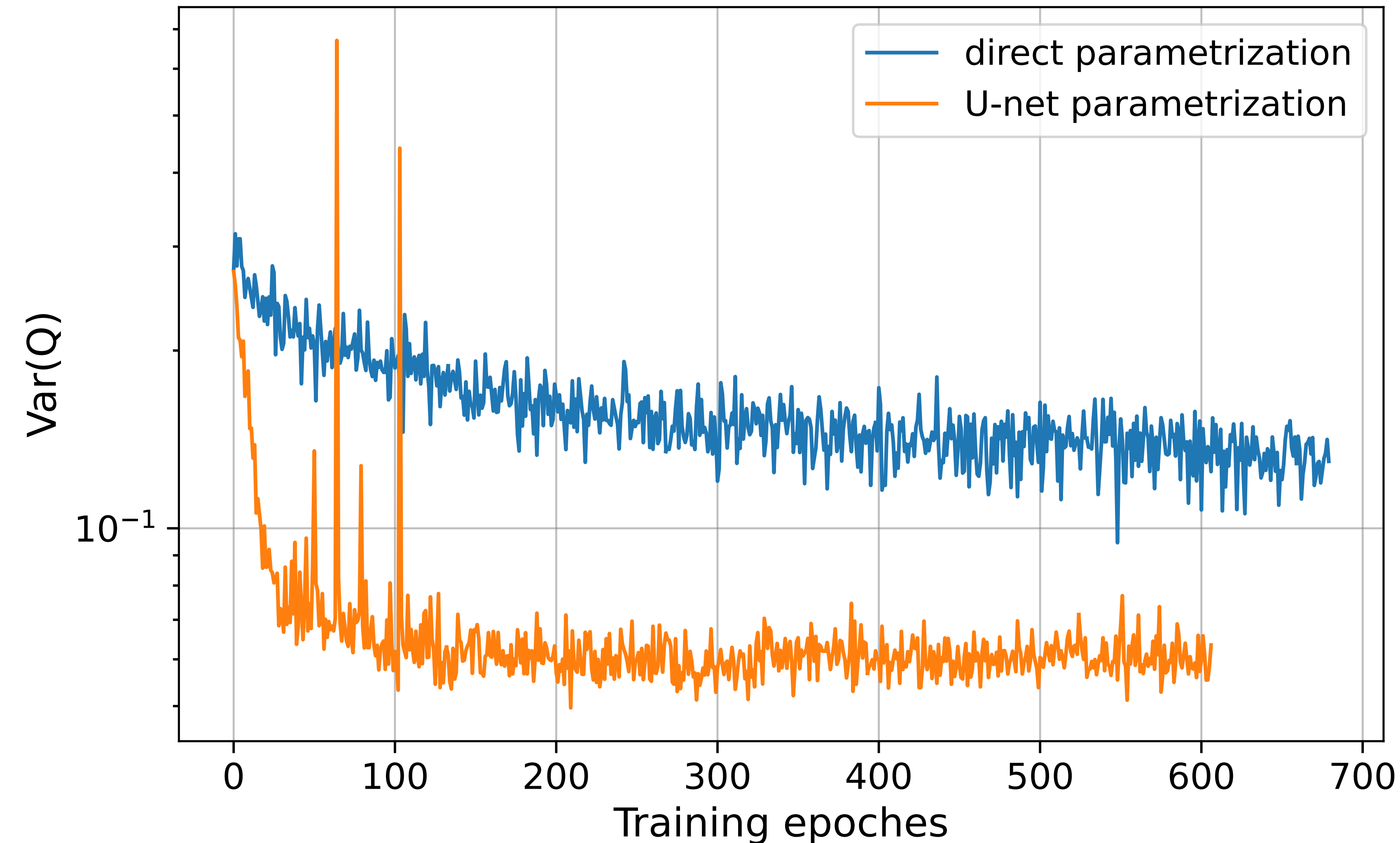
Example: $SU(2)$, 16^3 , 4-by-4 Wilson loops



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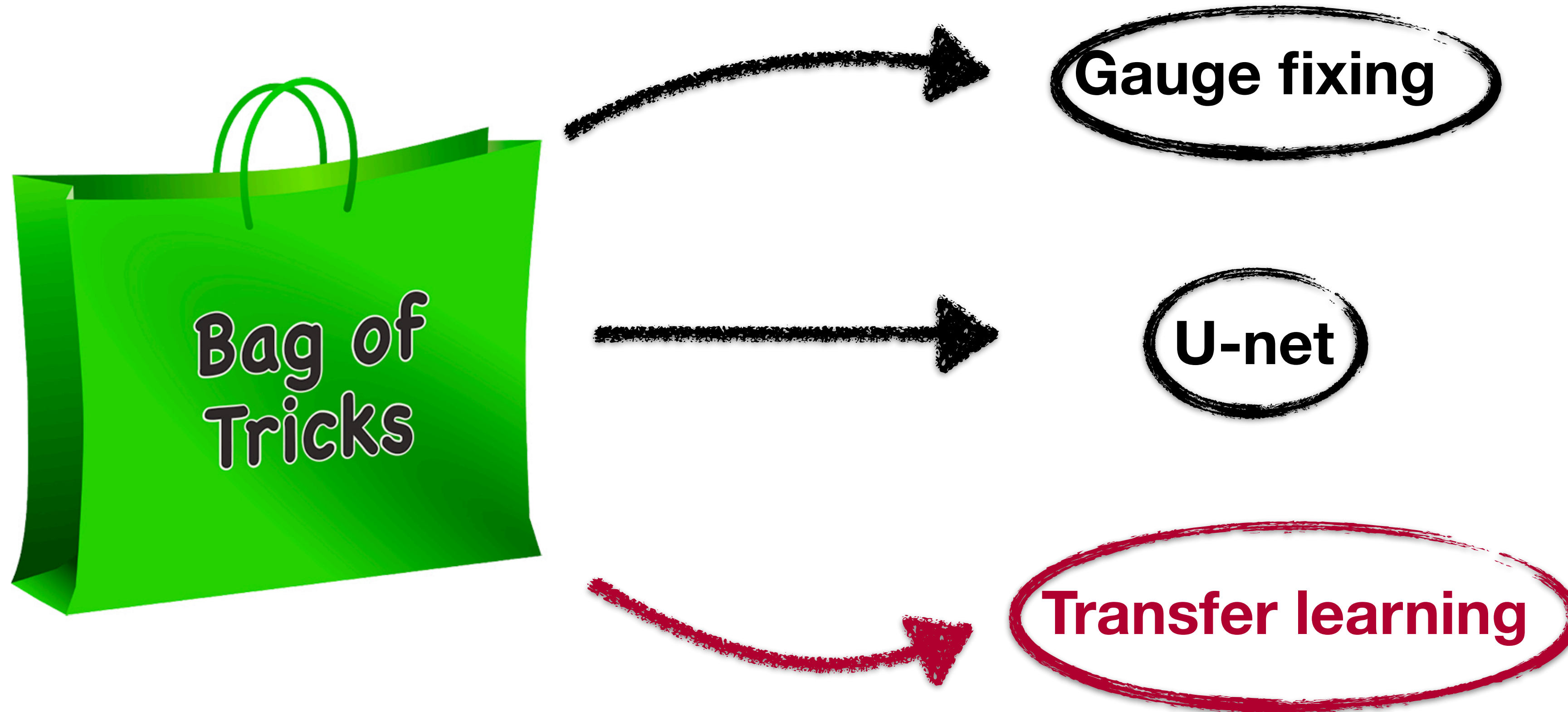
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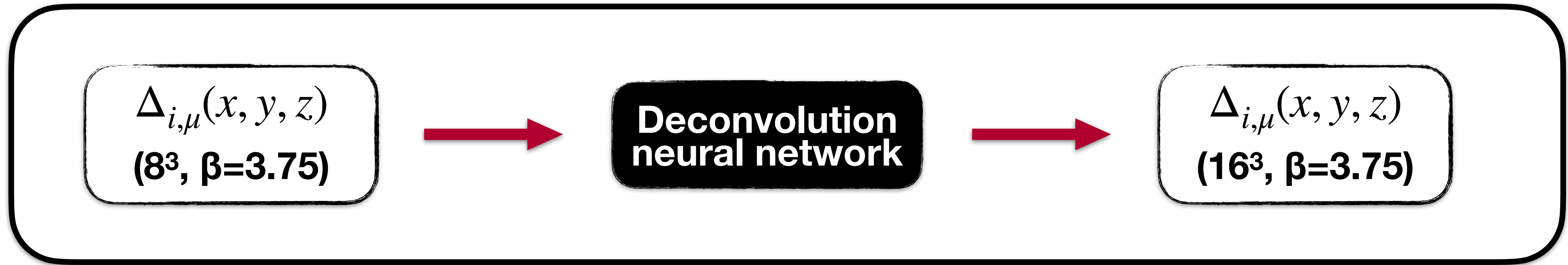


- ▶ Enable training with deeper networks, hence, larger lattices
- ▶ Required a lot of gauge configurations to avoid overtraining ($\sim 10^5$). Unfeasible for even larger lattices

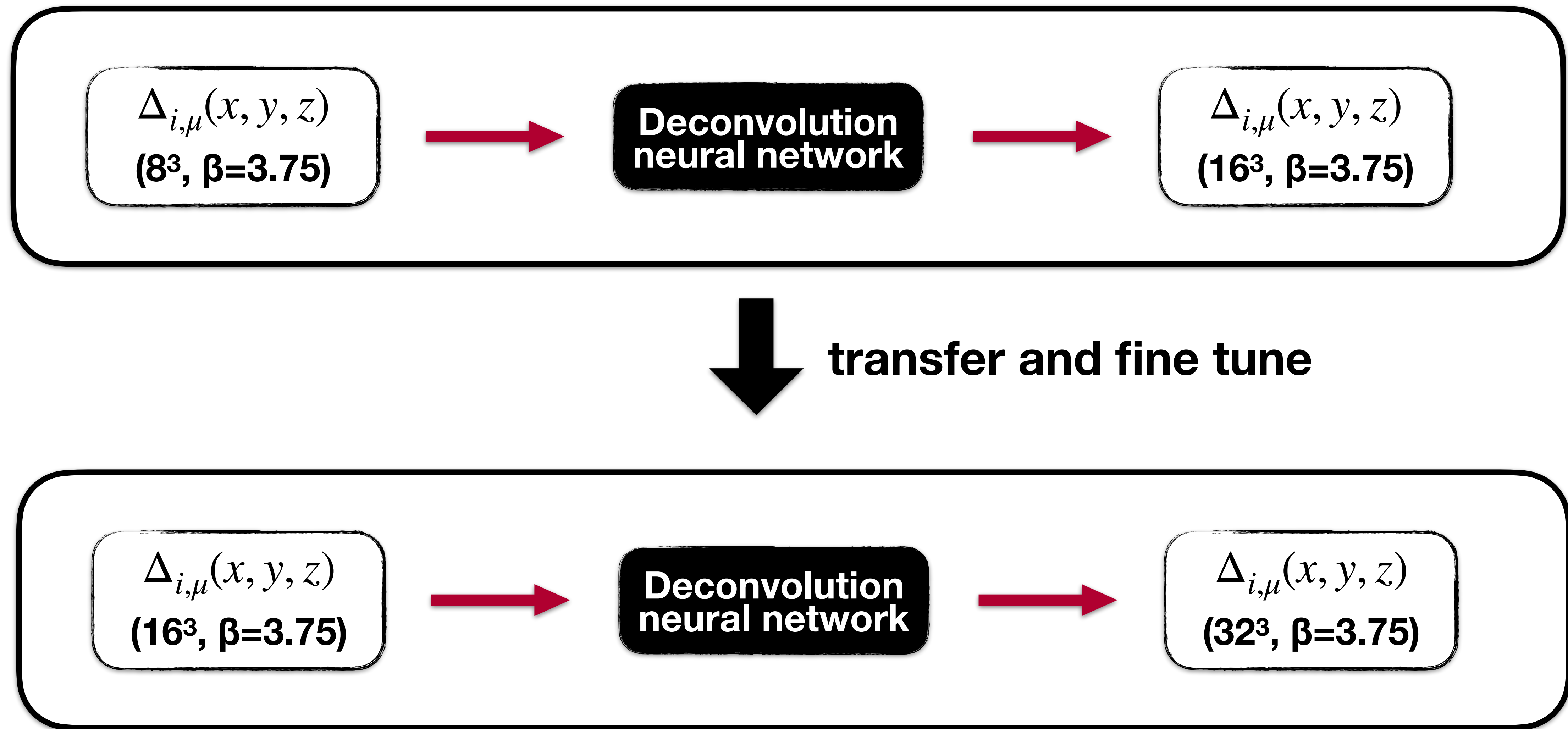
Contour deformation beyond 2d



Transfer learning for contour deformation

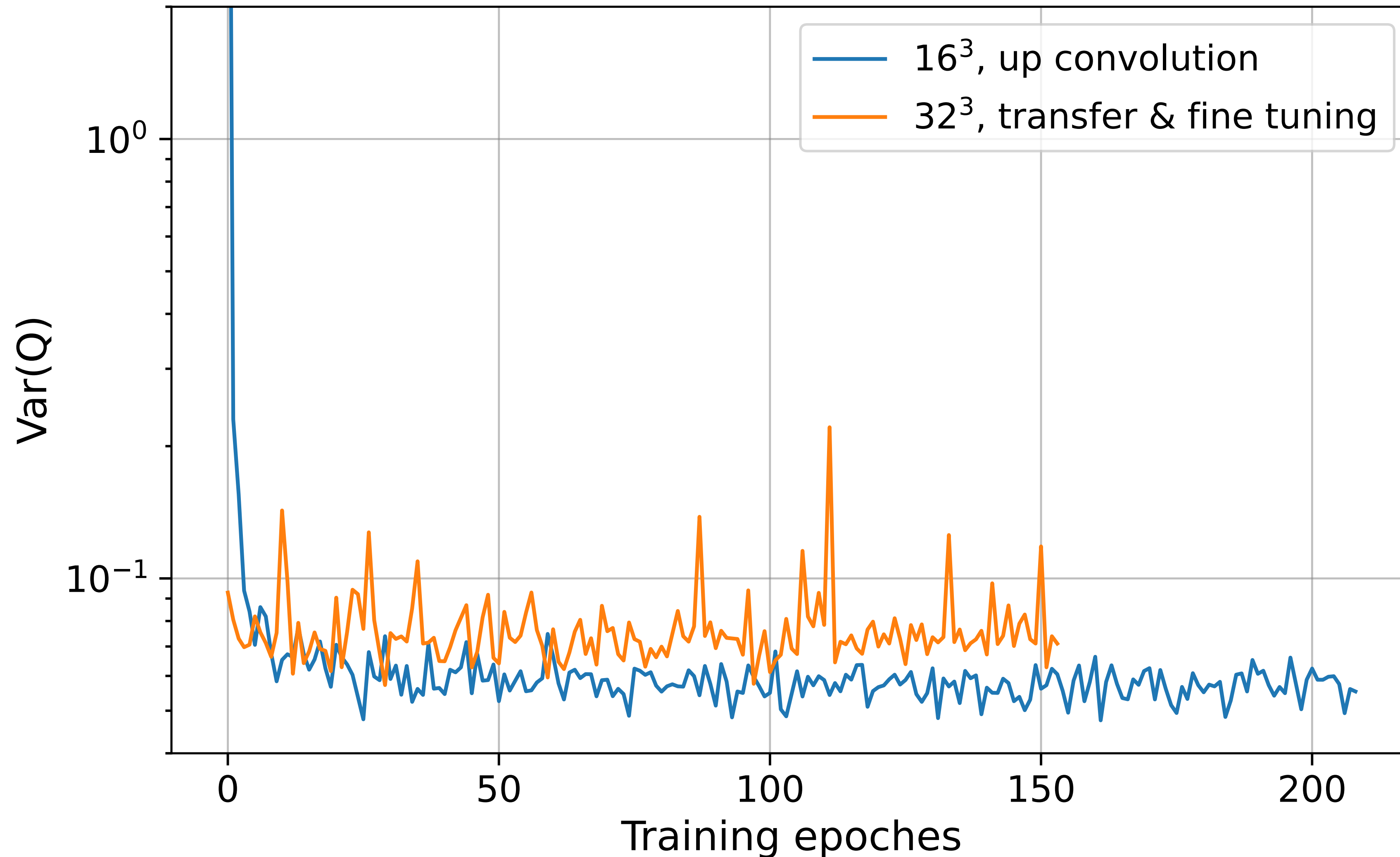


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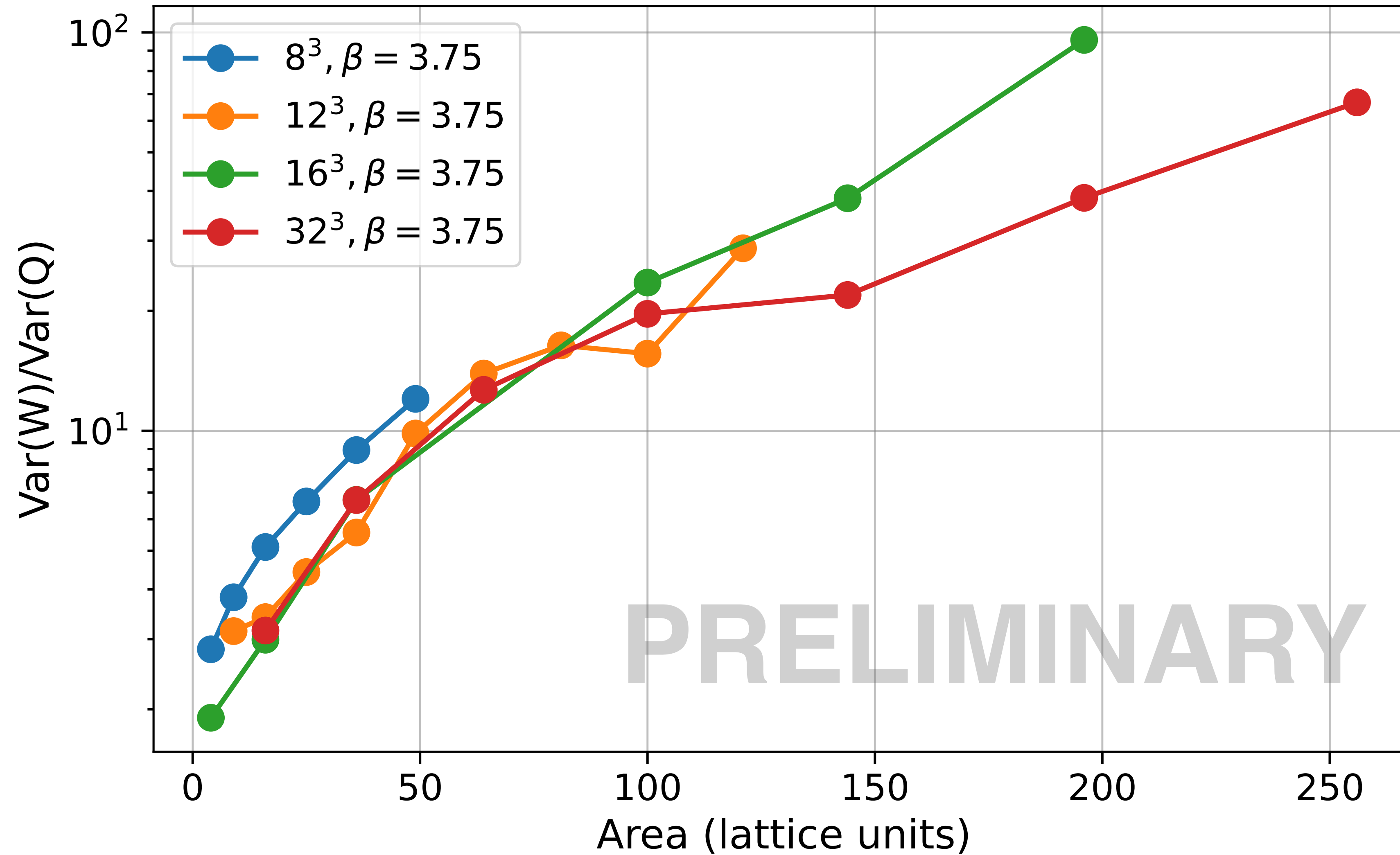


Volume transfer for contour deformation

Example: $SU(2)$, $\beta=3.75$, 4-by-4 Wilson loops



SU(2) preliminary results



Where we are and where we are going

- **Exponential improvement** in the variance for SU(2), SU(3) gauge theories in 3d



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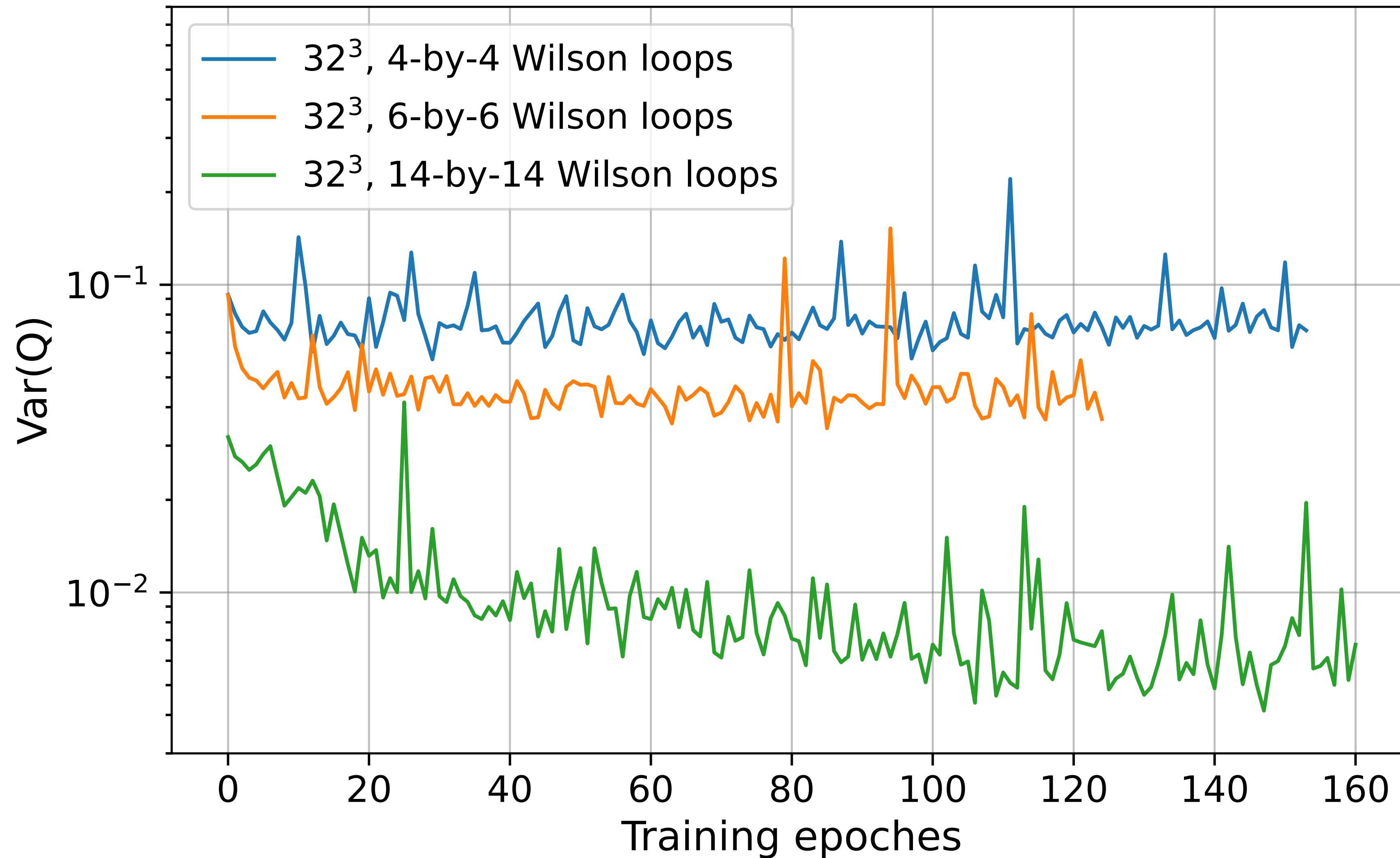
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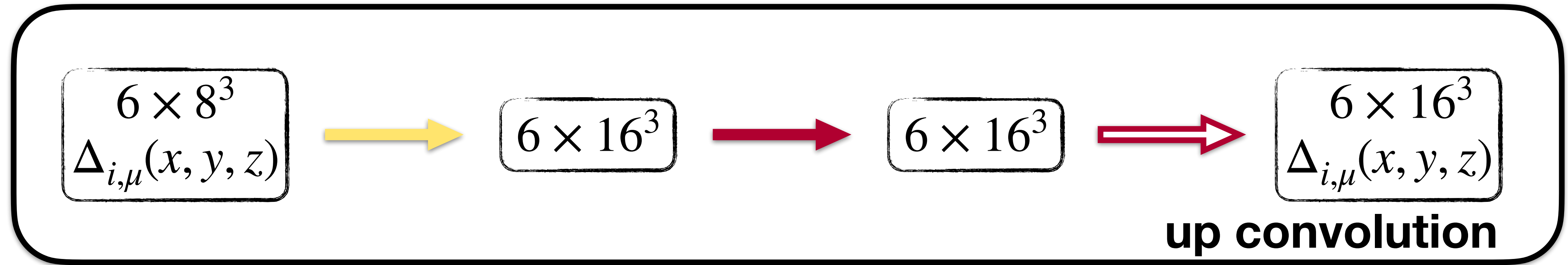


Area transfer for contour deformation

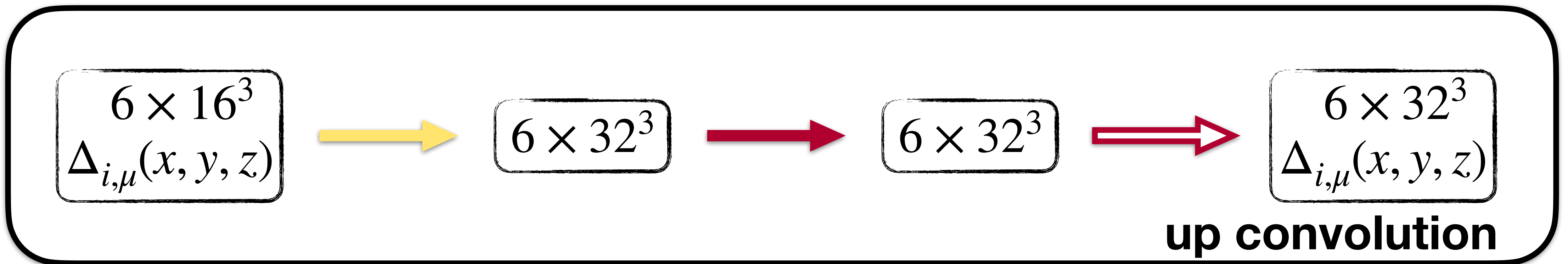
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Transfer learning for contour deformation



transfer and fine tune



\rightarrow = conv. , batch norm., ReLU \rightarrow = up conv. \Rightarrow = gauge fix

Reweighting complex action

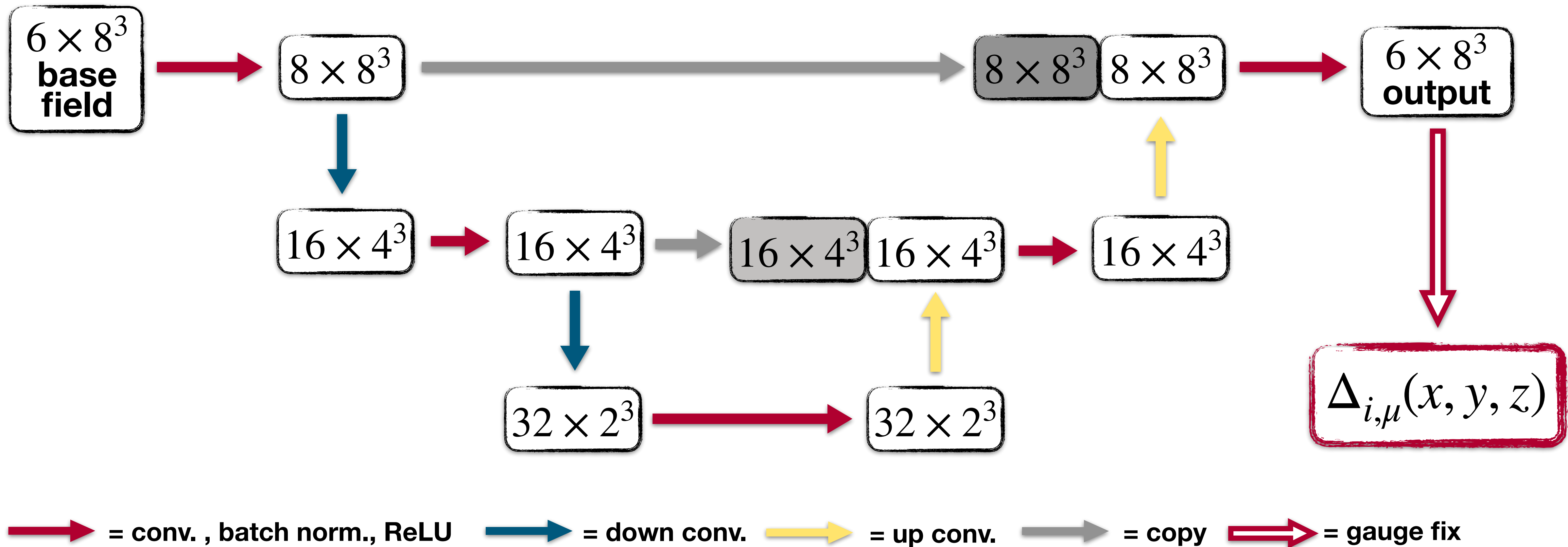
$$\begin{aligned}\langle \text{Re}W \rangle &= \text{Re} \int \prod_n \left[h(\tilde{\theta}_n) d\tilde{\theta}_n d\tilde{\phi}_{1,n} d\tilde{\phi}_{2,n} \right] p[\tilde{U}] W[\tilde{U}] \\ &= \text{Re} \int \prod_n \left[h(\theta_n) d\theta_n d\phi_{1,n} d\phi_{2,n} \right] p[U] \left(\frac{h(\tilde{\theta}_n) p[\tilde{U}]}{h(\theta_n) p[U]} W[\tilde{U}] \right) \\ &= \text{Re} \int \prod_n dU_n p[U] Q[U] = \langle Q \rangle\end{aligned}$$

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Example: SU(2), 16^3



Errors on reweighing factors

