

Towards space-time symmetry preserving lattice discretization schemes

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in collaboration with Jan Nordström

A.R., J. Nordström: arXiv:2307.04490,

see also JCP 477 (2023) 111942



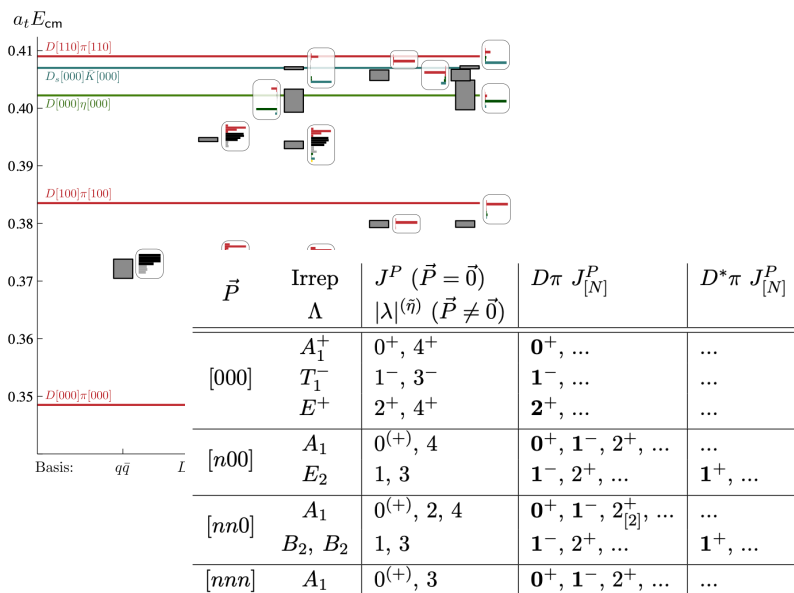
Norwegian Particle, Astroparticle
& Cosmology Theory network

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local $SU(N)$ via link variables, chiral symmetry via Overlap Dirac operator

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 absence of continuous translation and rotation invariance modify physics of orbital angular momentum and spin (mixing of otherwise orthogonal states).



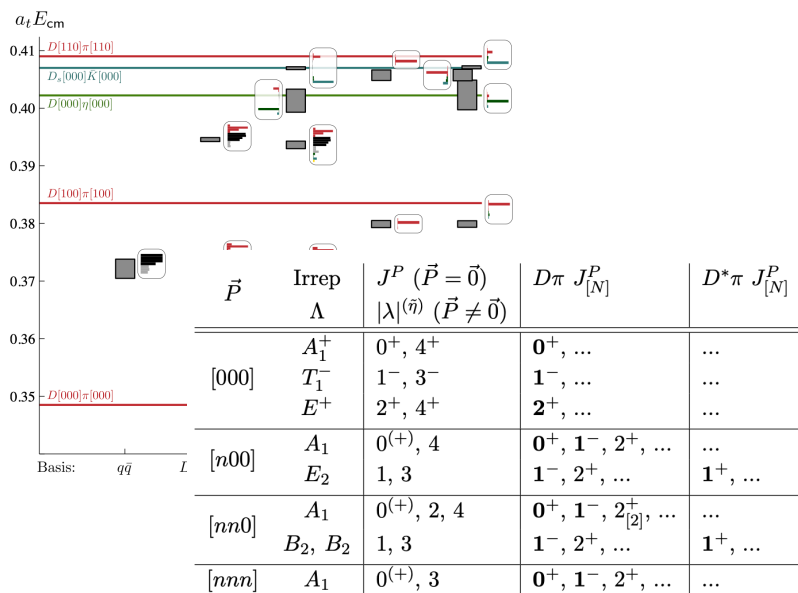
Hadron spectroscopy

see e.g. HadSpec Collaboration JHEP 07 (2021) 123

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Internal symmetries preserved through discrete formulation: local SU(N) via link variables, chiral symmetry via Overlap Dirac operator

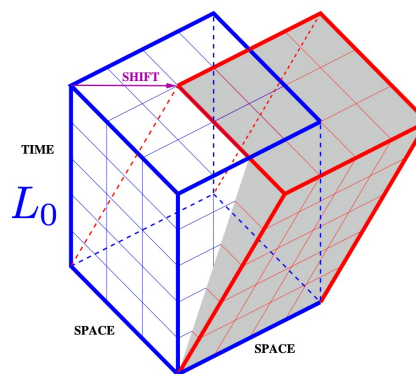
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$$T_{\mu\nu}^{\text{cont}} \text{ vs. } T_{\mu\nu}^{\text{latt}} = z_1 T_{\mu\nu}^{[6]} + z_2 T_{\mu\nu}^{[3]} + z_3 T_{\mu\nu}^{[1]}$$



Energy-momentum tensor on the lattice: recent developments

Hiroshi Suzuki*
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E-mail: hsuzuki@phys.kyushu-u.ac.jp

Energy Momentum Tensor

see e.g. H. Suzuki PoS LATTICE2016 (2017) 002 and references therein

The conventional lattice approach

- Simplest case: non-relativistic point particle under the influence of a potential

$$\mathcal{S} = \int_{t_i}^{t_f} \left(\frac{1}{2} m \dot{x}^2(t) - V(x) \right) dt$$

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- Proving time translational invariance involved: replacement of $x(t)$ by derivative and bounds of integral are affected. Due to infinitesimal δt Noether theorem holds

$$x(t + \delta t) = x(t) + \delta t \dot{x}(t) \qquad \mathcal{S} \xrightarrow{t+\delta t} \mathcal{S}$$

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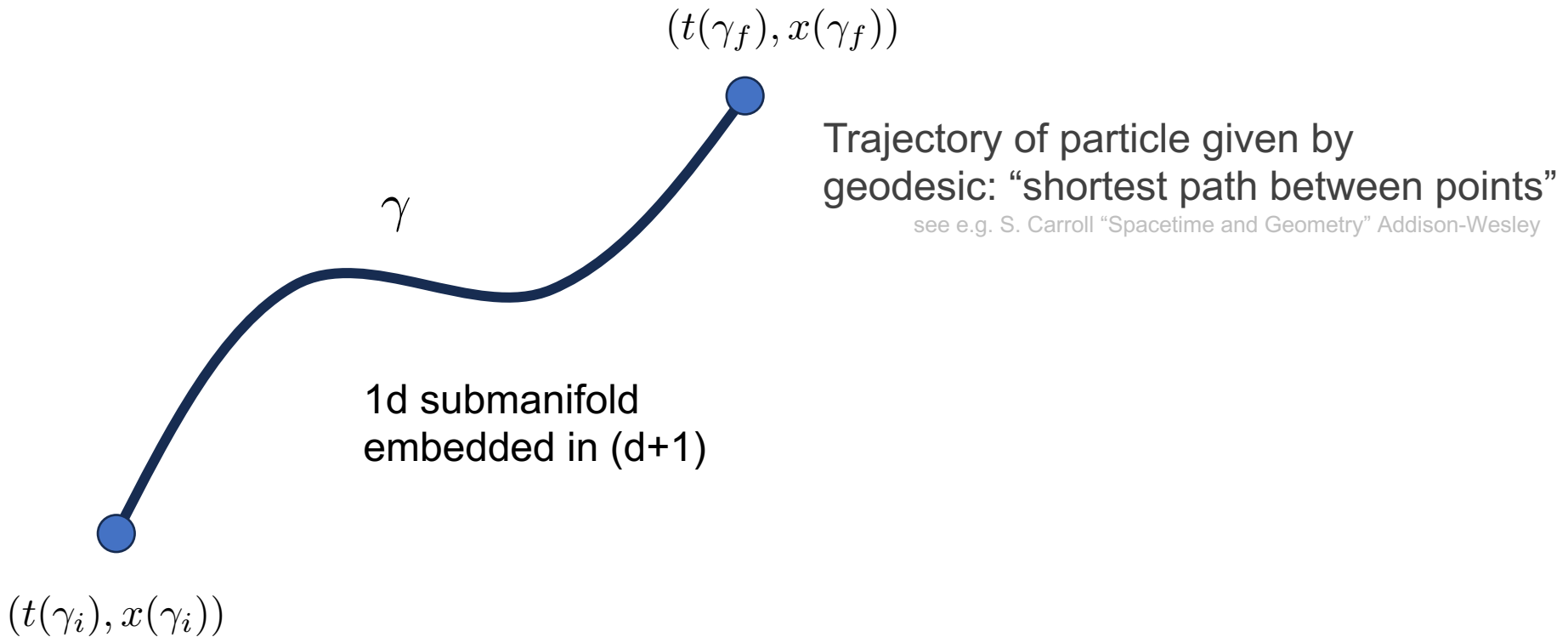
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- Usual way out: go over to Hamiltonian picture where time remains continuous and implement symplectic time stepping for e.o.m. (energy conserved on average/staggering)

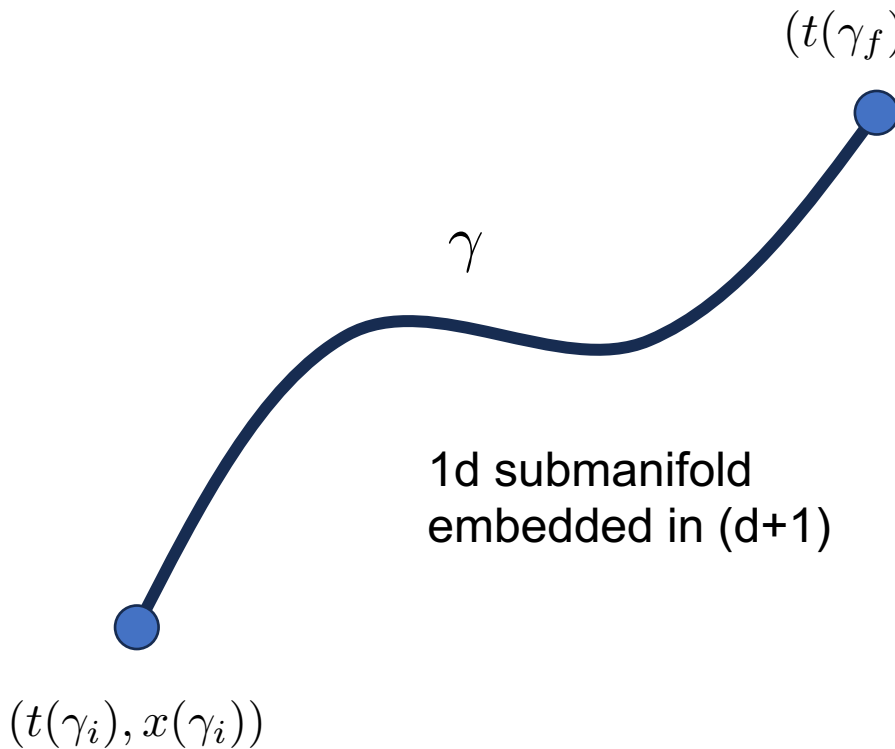
The worldline picture of GR

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Trajectory of particle given by geodesic: “shortest path between points”

see e.g. S. Carroll “Spacetime and Geometry” Addison-Wesley

Variational principle via geodesic action

see e.g. J. Jost, X. Li-Jost “Calculus of Variations” Cam.Uni.Press

$$\mathcal{S} = \int_{\gamma_i}^{\gamma_f} d\gamma (-mc) \sqrt{g_{\mu\nu} \frac{dx^\mu}{d\gamma} \frac{dx^\nu}{d\gamma}}$$

$$\mathbf{x}(\gamma_i) = \mathbf{x}_i, \mathbf{x}(\gamma_f) = \mathbf{x}_f$$



$$\frac{d^2 x^\alpha}{d\gamma^2} + \Gamma_{\mu\nu}^\alpha \frac{dx^\mu}{d\gamma} \frac{dx^\nu}{d\gamma} = 0$$

- Reparameterization invariant $\gamma \rightarrow \gamma'$.
Time and position dependent on γ .

Symmetries in General Relativity

- Comparing of quantities at different space-time points non-trivial for non-flat metric
- Systematically identify conserved quantities via Killing vectors K:

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$$\left(\frac{\partial K_\mu}{\partial x^\nu} - \Gamma_{\mu\nu}^\alpha K_\alpha \right) + \left(\frac{\partial K_\nu}{\partial x^\mu} - \Gamma_{\nu\mu}^\alpha K_\alpha \right) = 0$$

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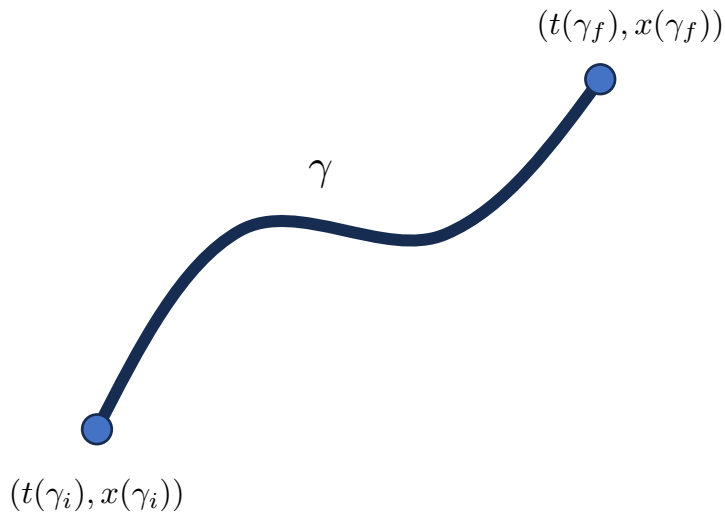
- Conserved quantities associated with K , constructed such that their dependence on the world-line parameter vanishes on the geodesic (c.f. Noether theorem on-shell)

$$Q_K = g_{\alpha\beta} K^\alpha \dot{x}^\beta \quad \text{relativistic Noether charge}$$

- Interestingly involves only a single derivative in case of translations, rotations or boosts.

Geometrizing the interactions

- Can one modify metric so that same trajectory ensues for non-interacting particle in a non-flat spacetime as for interacting particle in flat spacetime?

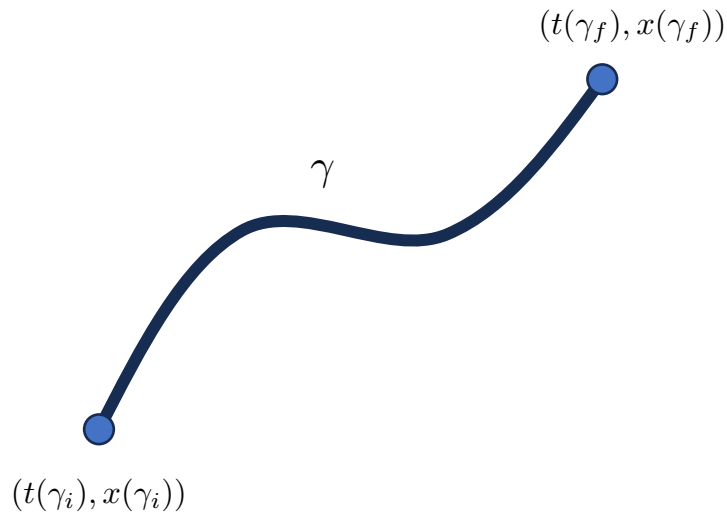


$$g = \text{diag}(c^2, -1)$$

$$\mathcal{S}_{\text{flat}} = \int_{\gamma_i}^{\gamma_f} d\gamma (-mc) \sqrt{c^2 \left(\frac{dt}{d\gamma}\right)^2 - \left(\frac{dx}{d\gamma}\right)^2} + V(\mathbf{x})$$

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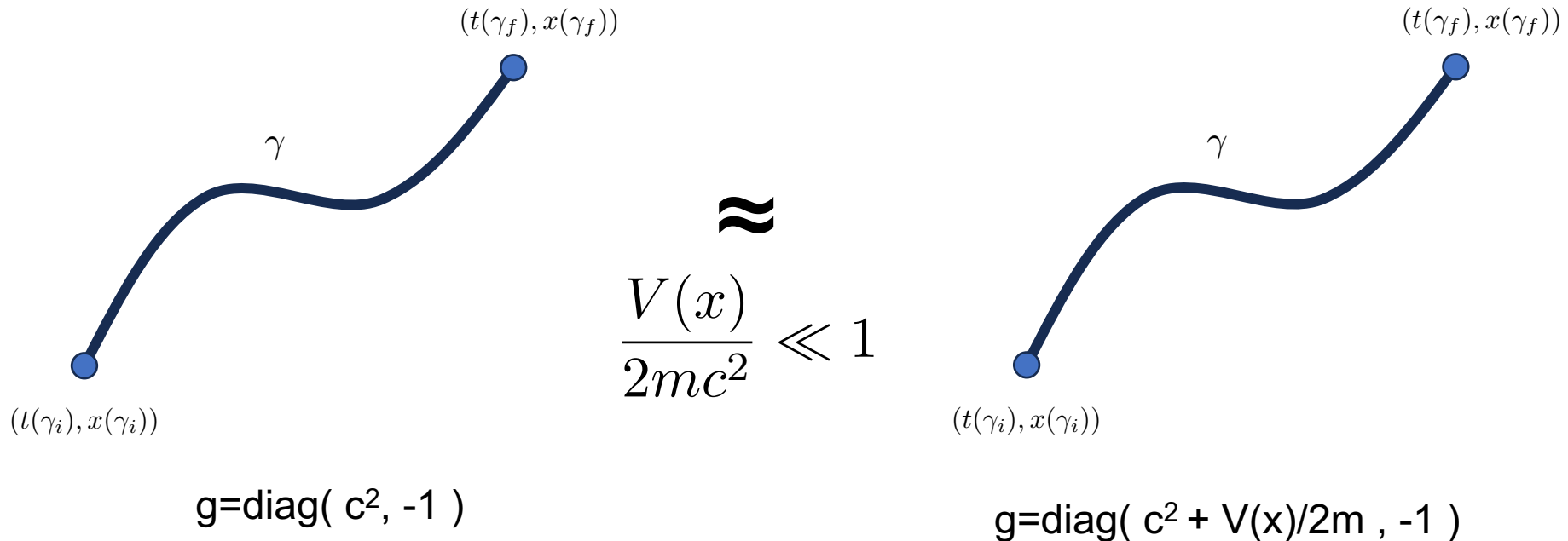
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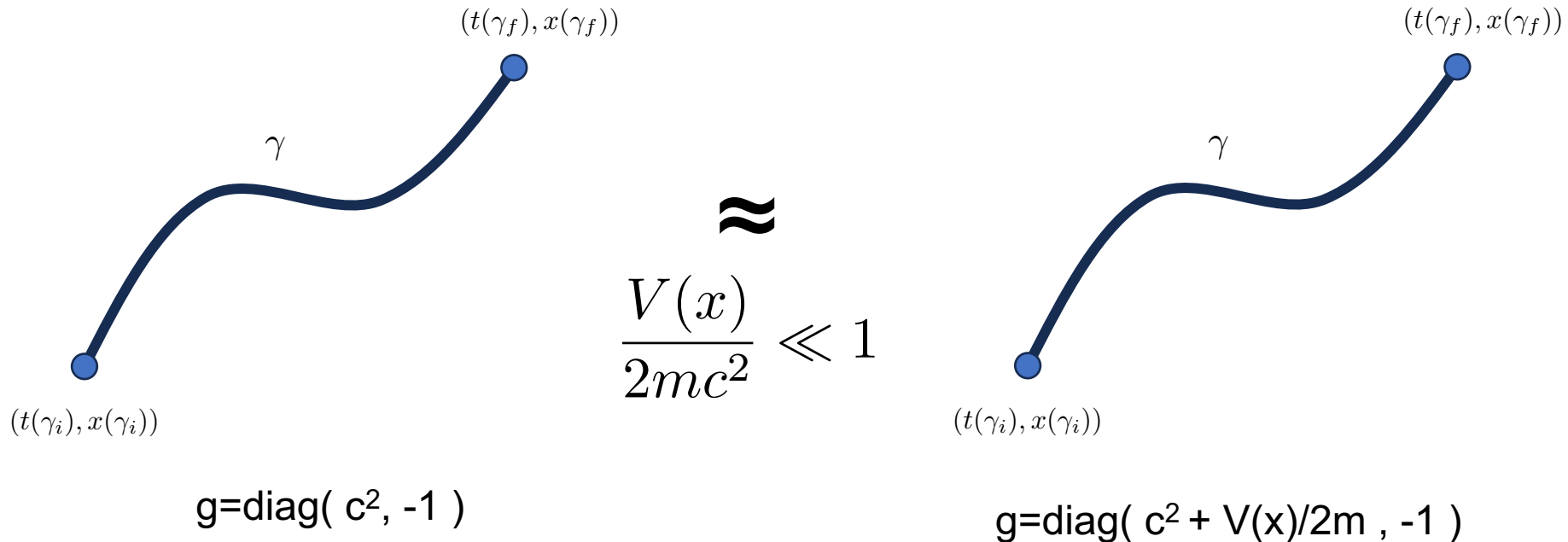
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$$\mathcal{S} = \int_{\gamma_i}^{\gamma_f} d\gamma (-mc) \sqrt{g_{00} \left(\frac{dt}{d\gamma}\right)^2 - \left(\frac{dx}{d\gamma}\right)^2}$$

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Modified geodesic action

- Reparameterization invariance is cumbersome for numerical optimization. Take instead square of the integrand, which leaves extremum unchanged.

$$\mathcal{E}_{\text{BVP}} = \int_{\gamma_i}^{\gamma_f} d\gamma E_{\text{BVP}}[t, \dot{t}, x, \dot{x}] = \int_{\gamma_i}^{\gamma_f} d\gamma \frac{1}{2} \left(g_{00} \left(\frac{dt}{d\gamma} \right)^2 + g_{11} \left(\frac{dx}{d\gamma} \right)^2 \right)$$

- Geodesic equations ensure for E_{BVP} :

$$\frac{d}{d\gamma} \left(g_{00} \frac{dt}{d\gamma} \right) = 0,$$

$$\frac{d}{d\gamma} \left(\frac{dx}{d\gamma} \right) + \frac{1}{2} \frac{\partial g_{00}}{\partial x} \left(\frac{dt}{d\gamma} \right)^2 = 0$$

Summation by parts discretization

- Consistent discretization of integration and derivatives: summation-by-parts

$$\langle x, y \rangle = \int d\gamma x(\gamma)y(\gamma) \rightarrow (\mathbf{x}, \mathbf{y}) = \mathbf{x}^T \mathbb{H} \mathbf{y}$$

$$\mathbb{D} = \mathbb{H}^{-1} \mathbb{Q}, \quad \mathbb{Q}^T + \mathbb{Q} = \mathbb{E}_N - \mathbb{E}_0 = \text{diag}[-1, 0, \dots, 0, 1]$$

$$\mathbb{H}^{[2,1]} = \Delta\gamma \begin{bmatrix} 1/2 & & & & \\ & 1 & & & \\ & & \ddots & & \\ & & & 1 & \\ & & & & 1/2 \end{bmatrix}, \quad \mathbb{D}^{[2,1]} = \frac{1}{2\Delta\gamma} \begin{bmatrix} -2 & 2 & & & \\ -1 & 0 & 1 & & \\ & \ddots & & & \\ & & -1 & 0 & 1 \\ & & & -2 & 2 \end{bmatrix}$$

- Straight forward to go to higher order schemes, available up to 20th order

Discretizing the geodesic action

- We discretize in the world-line parameter, not in the time variable:

$$\begin{aligned}
 \mathbb{E}_{\text{BVP}} = & \frac{1}{2} \left\{ \left(\left(c^2 + \frac{2V(\mathbf{x})}{m} \right) \circ \mathbb{D}\mathbf{t} \right)^T \mathbb{H}(\mathbb{D}\mathbf{t}) - (\mathbb{D}\mathbf{x})^T \mathbb{H}(\mathbb{D}\mathbf{x}) \right\} \\
 & + \lambda_1(\mathbf{t}[1] - t_i) + \lambda_2(\mathbf{t}[N_\gamma] - t_f) \\
 & + \lambda_3(\mathbf{x}[1] - x_i) + \lambda_4(\mathbf{x}[N_\gamma] - x_f)
 \end{aligned}$$

- Note that the values of t and x remain continuous : explicit invariance under time translations in the discrete setting. No issue with boundaries of the action integral

Schwinger-Keldysh for IVPs

- So far everything as boundary value problem: not causal, need to know the final point of the trajectory to formulate variational principle.

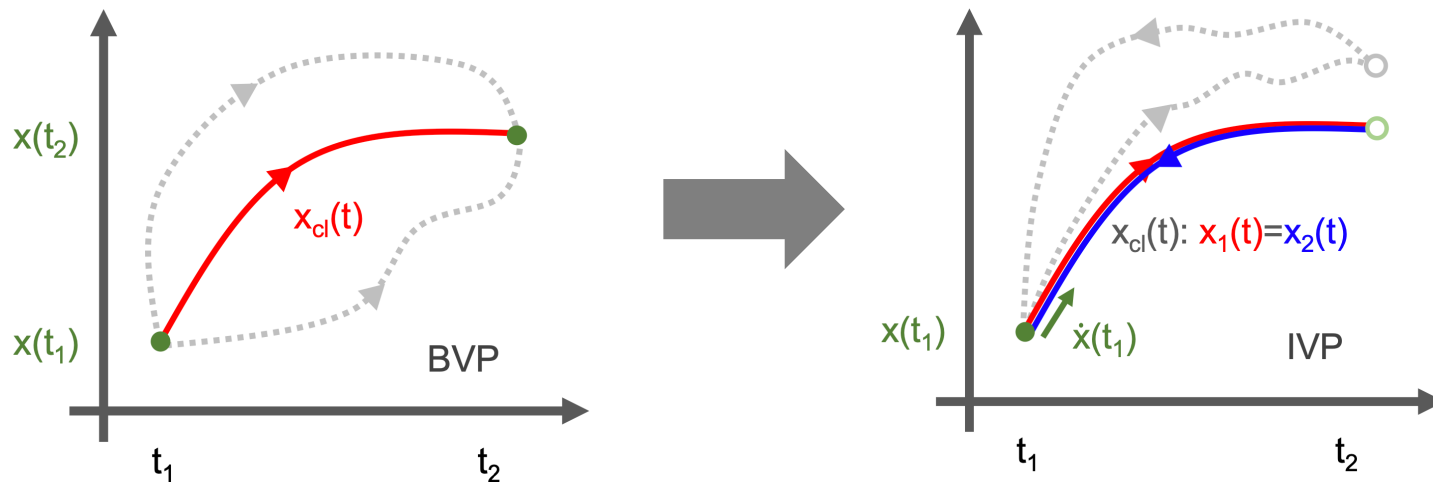
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- One can show that using a classical Schwinger-Keldysh contour allows to set up a variational principle for initial value problems (C.R. Galley, PRL 110(17), 174301)



Non-linear potential example

- Challenging non-harmonic $V(x) = k x^4$ as IVP with $k=1/4$ and $v_0=1/10$ $x_0=1$ $t_0=0$
(A.R. Jan Nordström arXiv:2307.04490)

$$\begin{aligned}
 \mathbb{E}_{\text{IVP}}^{\text{qrt}} = & \frac{1}{2} \left\{ (\bar{\mathbb{D}}_t^R \mathbf{t}_1)^T \mathfrak{d} [1 + 2\kappa \mathbf{x}_1^4] \bar{\mathbb{H}}(\bar{\mathbb{D}}_t^R \mathbf{t}_1) - (\bar{\mathbb{D}}_x^R \mathbf{x}_1)^T \bar{\mathbb{H}}(\bar{\mathbb{D}}_x^R \mathbf{x}_1) \right\} \\
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- Challenging non-harmonic $V(x) = k x^4$ as IVP with $k=1/4$ and $v_0=1/10$ $x_0=1$ $t_0=0$
(A.R. Jan Nordström arXiv:2307.04490)

$$\begin{aligned}
 \mathbb{E}_{\text{IVP}}^{\text{qrt}} = & \frac{1}{2} \left\{ (\bar{\mathbb{D}}_t^R \mathbf{t}_1)^T \mathbb{d} [1 + 2\kappa \mathbf{x}_1^4] \bar{\mathbb{H}}(\bar{\mathbb{D}}_t^R \mathbf{t}_1) - (\bar{\mathbb{D}}_x^R \mathbf{x}_1)^T \bar{\mathbb{H}}(\bar{\mathbb{D}}_x^R \mathbf{x}_1) \right\} && \text{Forward branch } x_1, t_1 \\
 & - \frac{1}{2} \left\{ (\bar{\mathbb{D}}_t^R \mathbf{t}_2)^T \mathbb{d} [1 + 2\kappa \mathbf{x}_2^4] \bar{\mathbb{H}}(\bar{\mathbb{D}}_t^R \mathbf{t}_2) - (\bar{\mathbb{D}}_x^R \mathbf{x}_2)^T \bar{\mathbb{H}}(\bar{\mathbb{D}}_x^R \mathbf{x}_2) \right\} && \text{Backward branch } x_2, t_2 \\
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- Note both x and t treated as IVP: no fixed end time of simulation set!

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Non-linear potential example

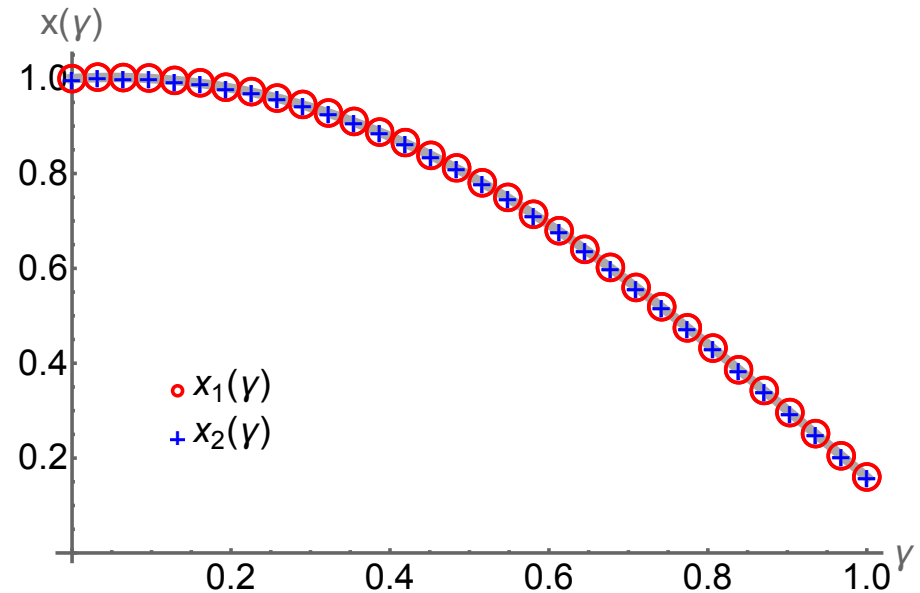
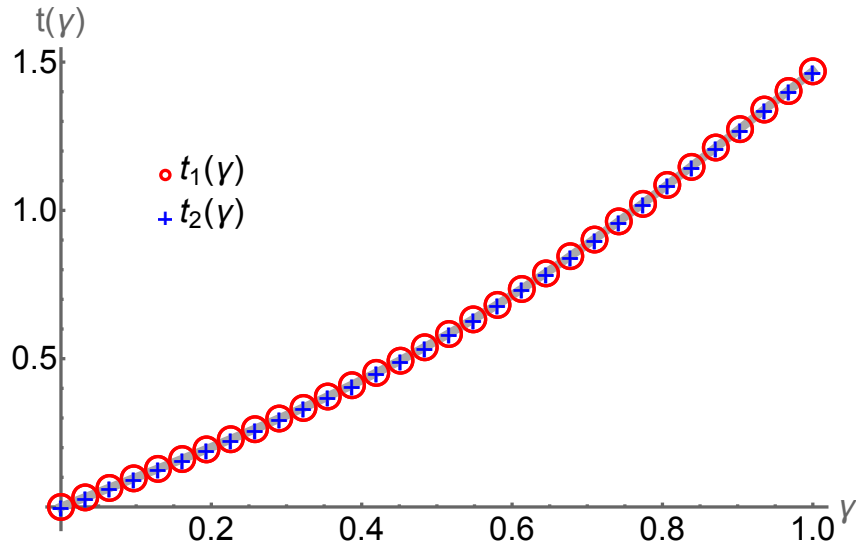
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- Freedom to choose $v_0 = dx/dt = dx/dy / dt/dy$ we go with $dt/dy = 1$
- Technical aspect: need to lift unphysical zero mode of the SBP symmetric finite difference operator (for details see A.R. J.N. JCP 477 (2023) 111942)

Numerical results ($N\gamma=32$)

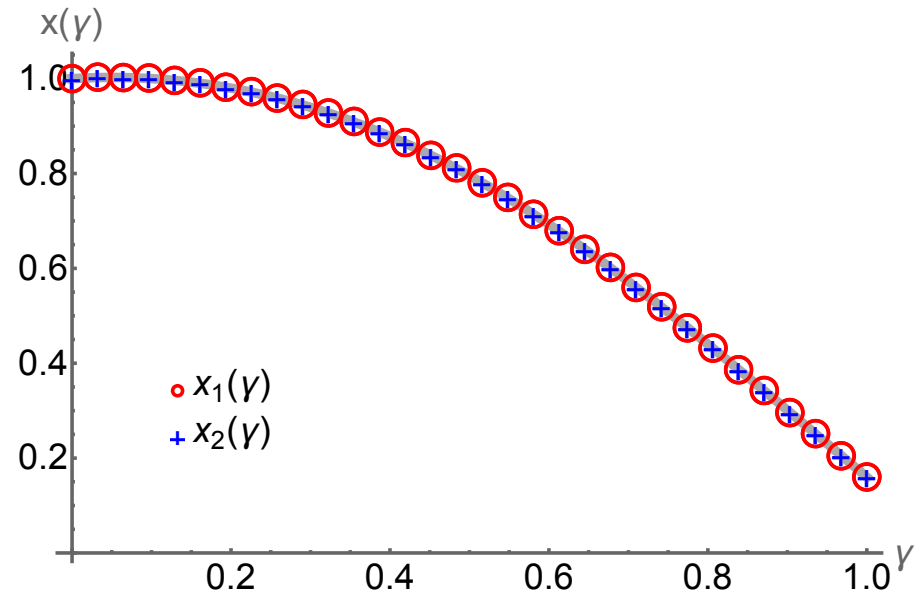
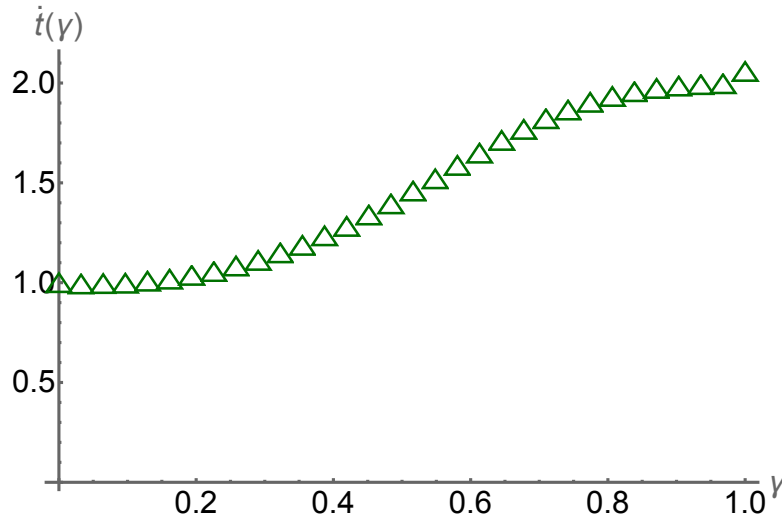
- Find the critical point of $E^{\text{qrt}}_{\text{IVP}}$ using Quasi-Newton, Newton, Interior Point minimizer (A.R. Jan Nordström arXiv:2307.04490)



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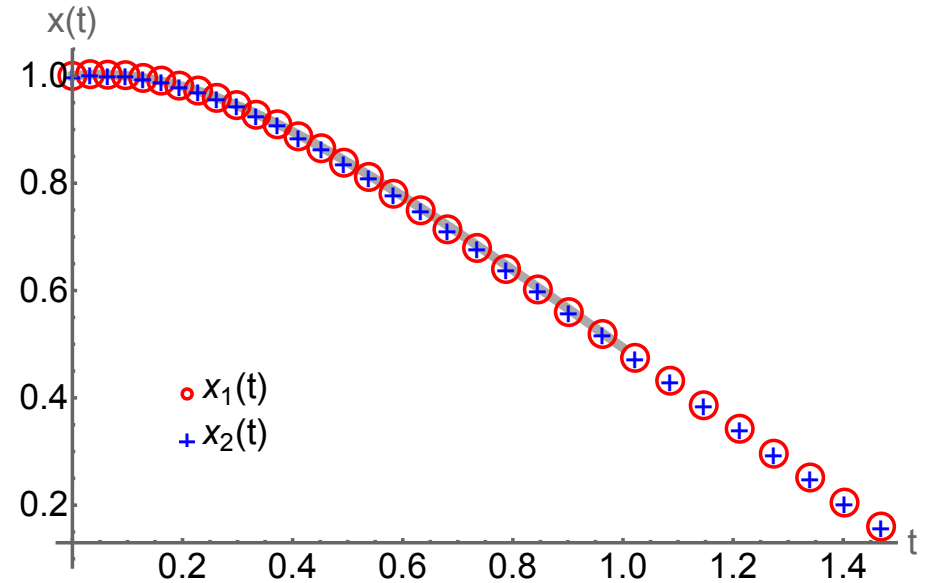
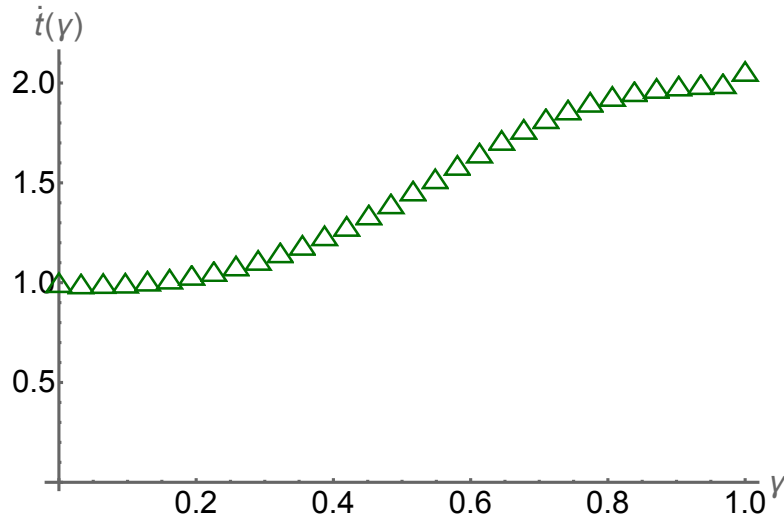
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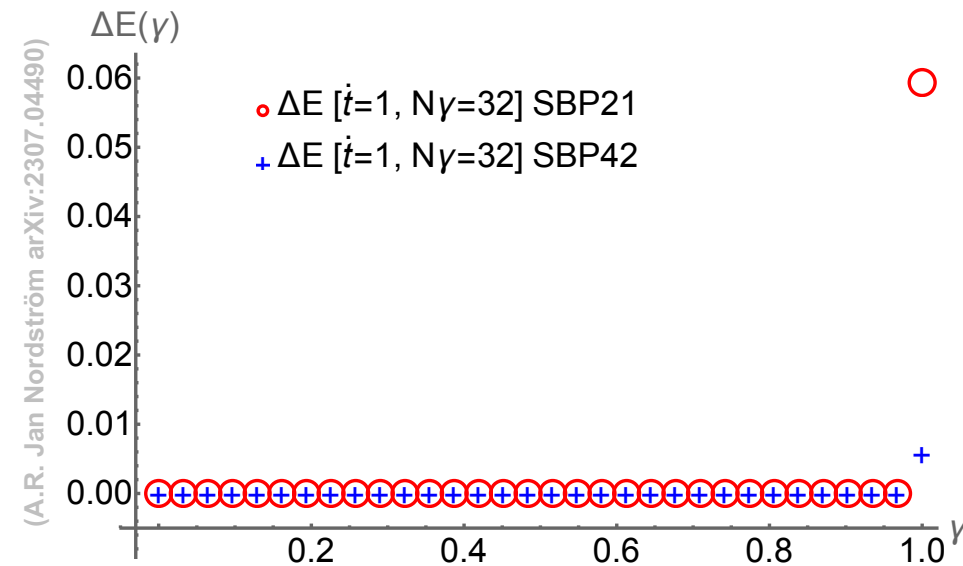
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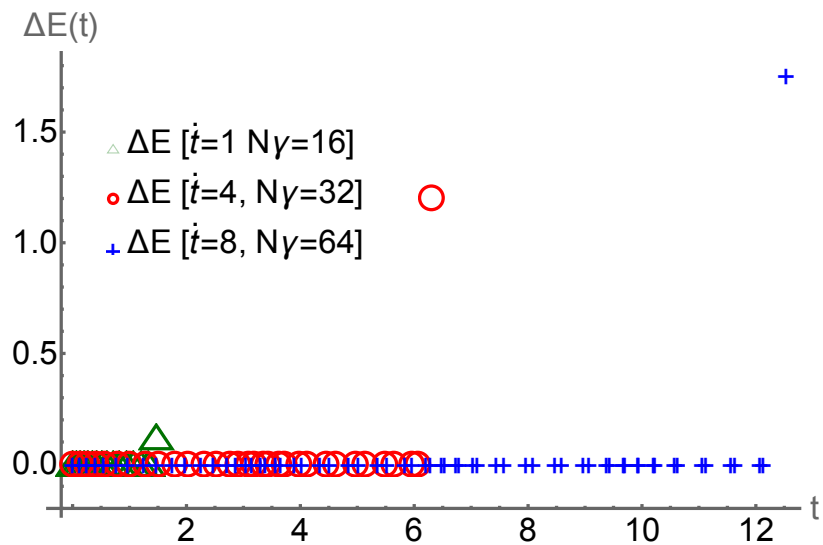
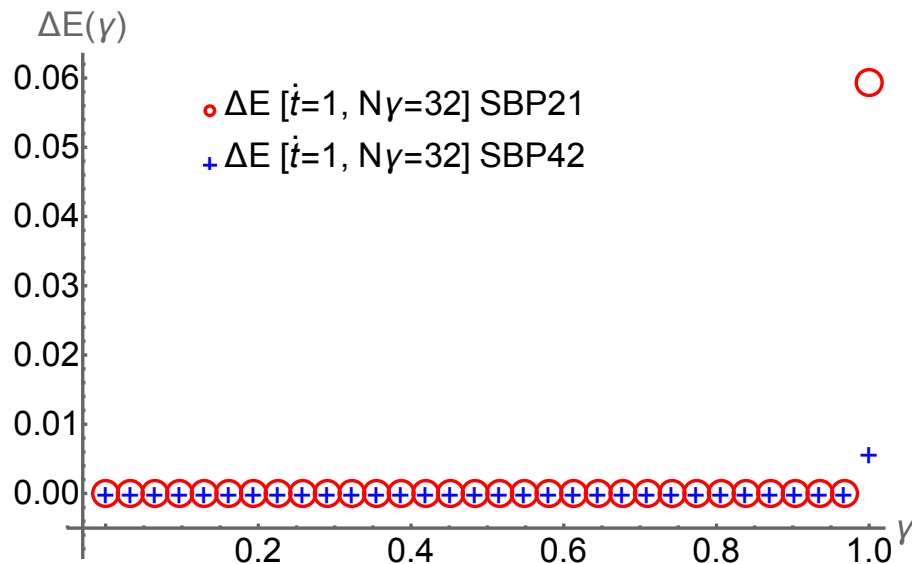
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- Preserved value is actually the **continuum value!**

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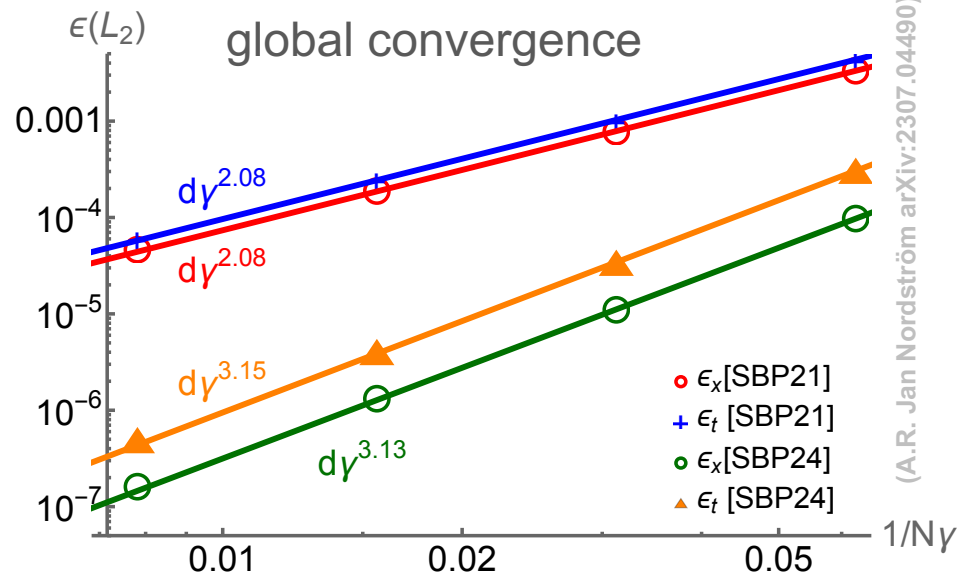
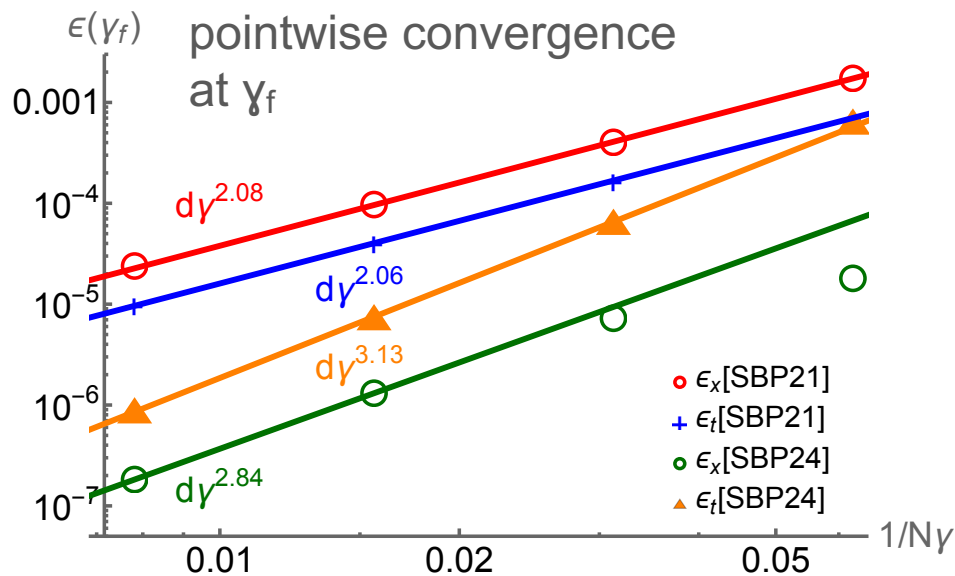
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Convergence

Does the last point spoil the approach to correct solution in the continuum?



(A.R. Jan Nordström arXiv:2307.04490)

Correct continuum limit reached with competitive scaling behavior.

Summary

- Novel geometric variational principle for IVPs, adopting the world-line formalism of a point particle in general relativity
- Both time and position are dependent variables on world-line parameter γ
geodesic action is manifestly invariant under space-time translations & boosts
- Discretizing in γ leaves time and position continuous and thus discretized action retains its continuum space-time symmetries
- Numerical implementation with summation-by-parts operators: exact conservation of relativistic Noether charge at continuum value in the interior of simulated domain
- Even though last point deviates, competitive scaling towards the continuum limit
- Future Goal: generalize to initial boundary value problems in $d+1$ dimensions
for systems such as the wave equation and Maxwell electrodynamics

Naïve discretize geodesic equations

$$\frac{d}{d\gamma} \left(g_{00} \frac{dt}{d\gamma} \right) = \frac{d}{d\gamma} \left((1 + 2\kappa x^4) \frac{dt}{d\gamma} \right) = 0,$$

$$\frac{d}{d\gamma} \left(\frac{dx}{d\gamma} \right) + \frac{1}{2} \frac{\partial g_{00}}{\partial x} \left(\frac{dt}{d\gamma} \right)^2 = \frac{d^2 x}{d\gamma^2} + 4\kappa x^3 \left(\frac{dt}{d\gamma} \right)^2 = 0$$



$$\mathbb{D}((1 + 2\kappa \mathbf{x}^4) \circ \mathbb{D}\mathbf{t}) = \Delta \mathbf{G}^t,$$

$$\mathbb{D}\mathbb{D}\mathbf{x} + (4\kappa \mathbf{x}^3) \circ (\mathbb{D}\mathbf{t}) \circ (\mathbb{D}\mathbf{t}) = \Delta \mathbf{G}^x$$

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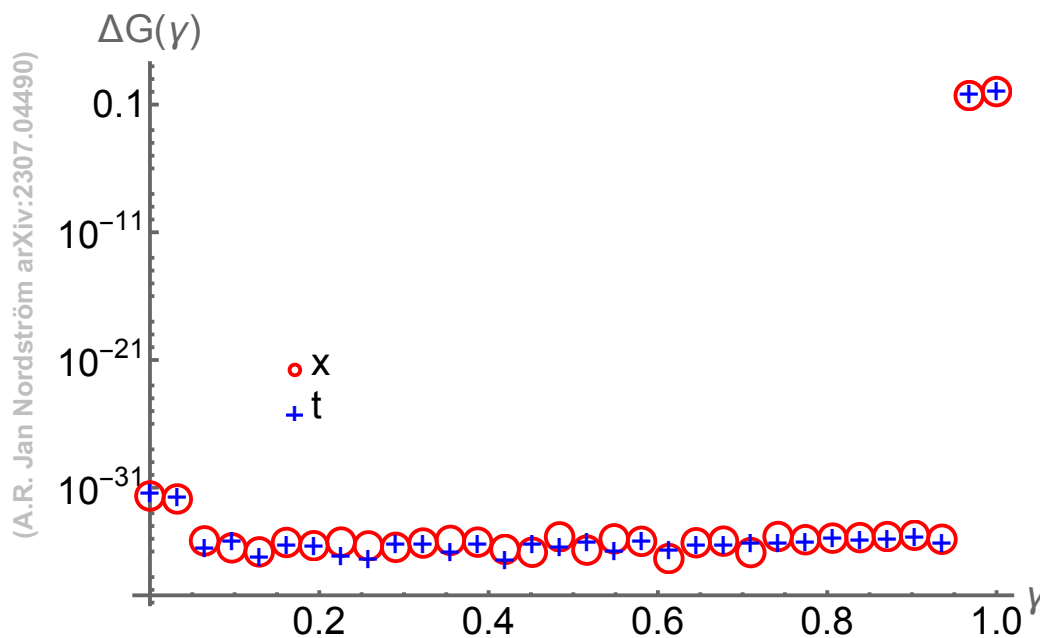
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Exactly follows the continuum geodesic equation except for the last two points