

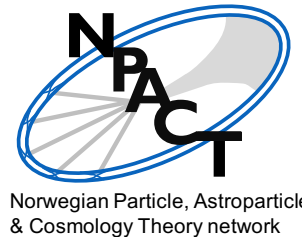
# Lattice real-time simulations with machine learned optimal kernels

on behalf of **Daniel Alvestad**  
Faculty of Science and Technology  
Department of Mathematics and Physics  
University of Stavanger



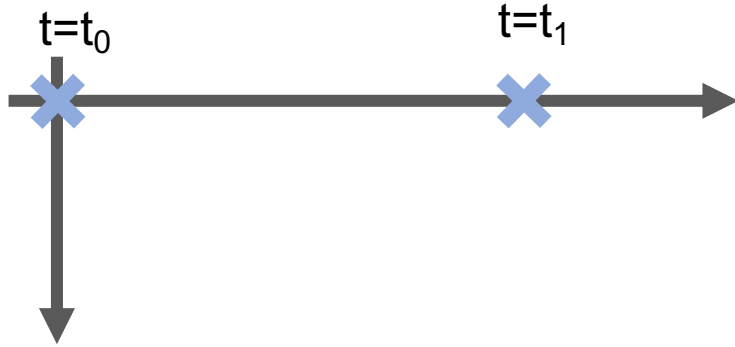
with **Alexander Rothkopf & Rasmus Larsen**  
D. A., R. Larsen, A.R., JHEP 08 (2021) 138 and  
JHEP 04 (2023) 057

as well as with **Denes Sexty & Nina Lampl**  
D. A. , A. R., N. Lampl, D. Sexty (in preparation)



# Real-time quantum dynamics

- The path integral at finite temperature on the Schwinger-Keldysh contour

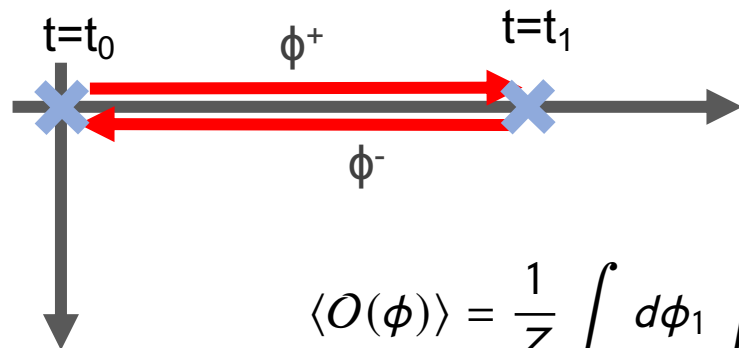


Goal: evaluation of real-time observables

$$\langle O(t_0)O(t_1) \rangle = \text{Tr}[ \rho O(t_0)O(t_1) ]$$

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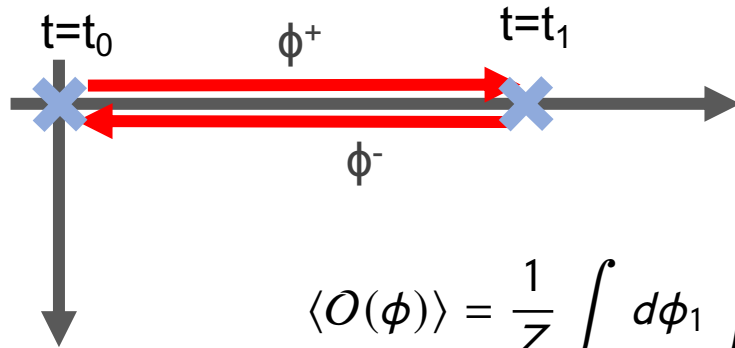
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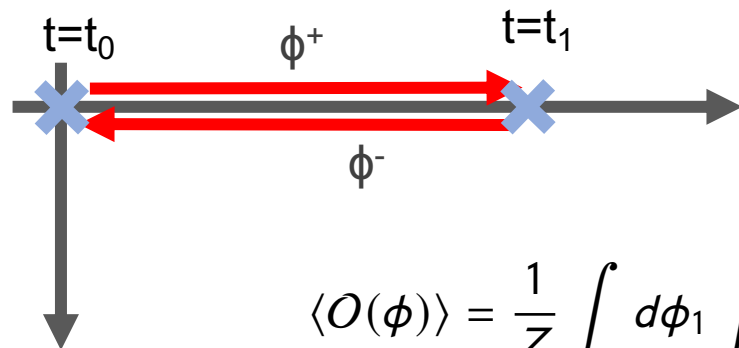
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sampling over statistically  
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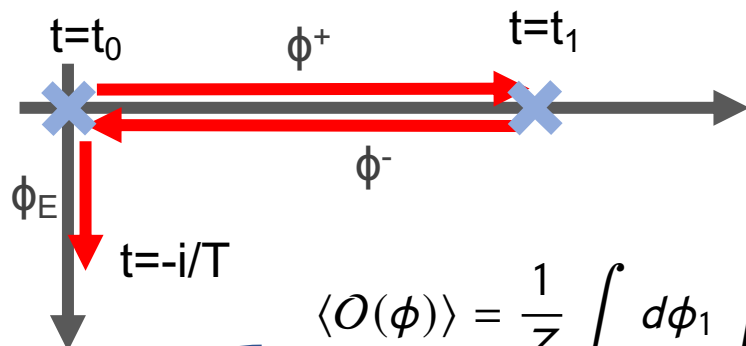
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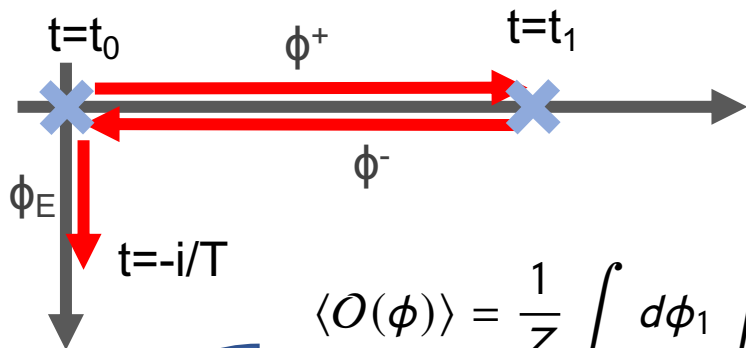
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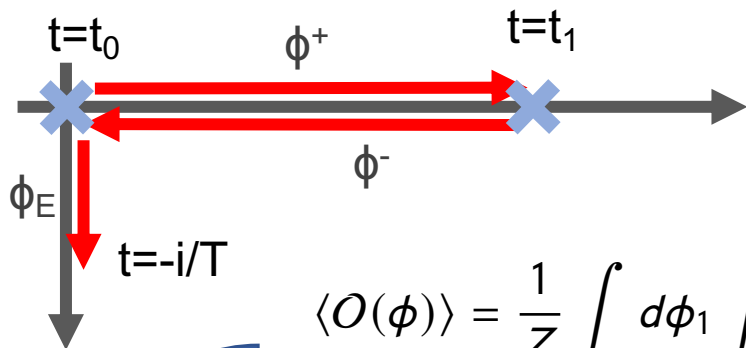
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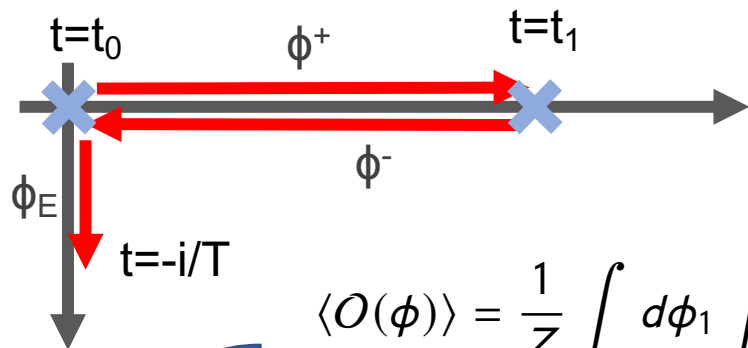
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Pure phase Feynman weight implies  
MC sign problem. One strategy:  
**Complex Langevin** see C. Berger et.al.  
Phys.Rept. 892 (2021)



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- Sign problem is NP-hard: **no generic solution** strategy is likely to exist

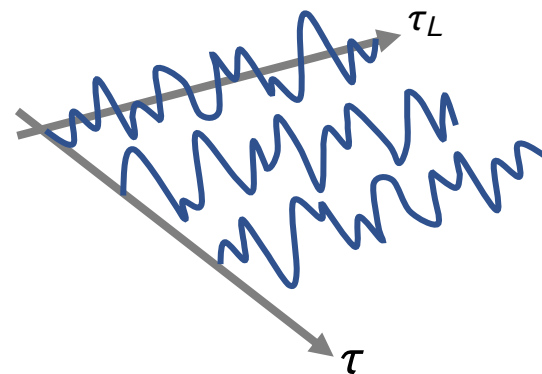
Troyer, Wiese PRL 94 170201 (2004)

# Stochastic Quantization

- Langevin evolution in fictitious additional time to reproduce quantum fluctuations  
 for an in-depth review: M. Namiki et.al. Stochastic Quantization (Springer) 1992

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Stochastic partial differential equation (SDE) with Gaussian noise



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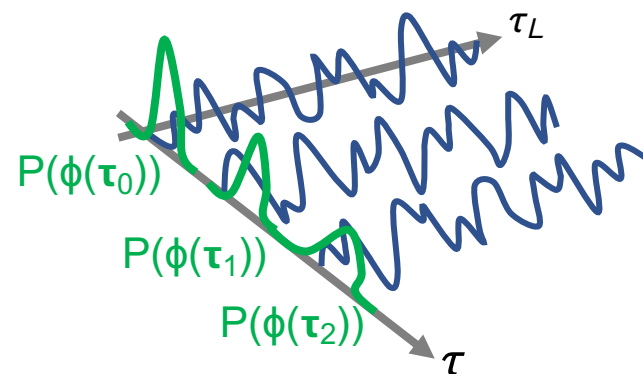
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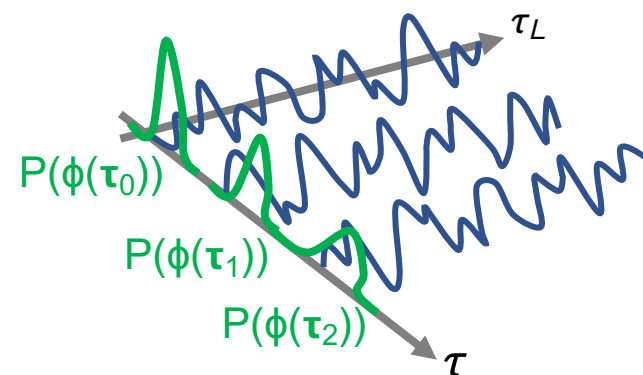
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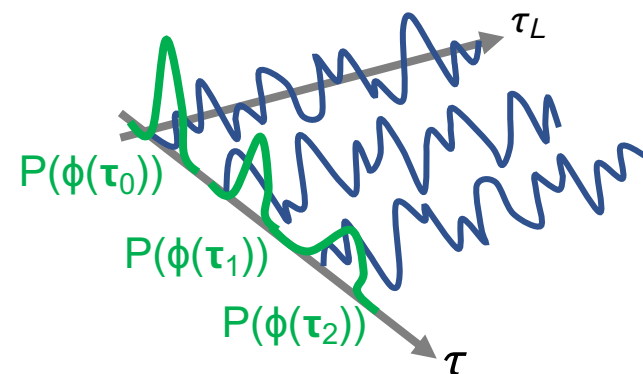
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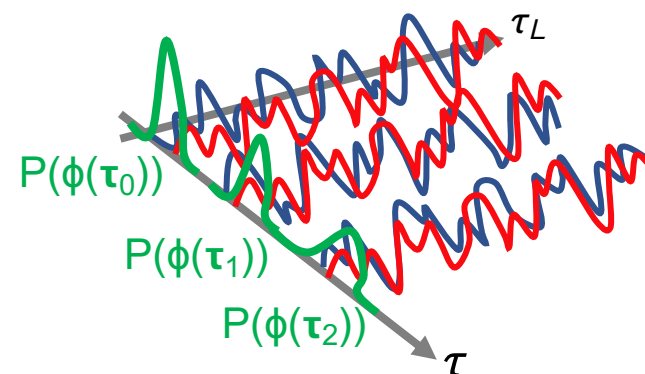
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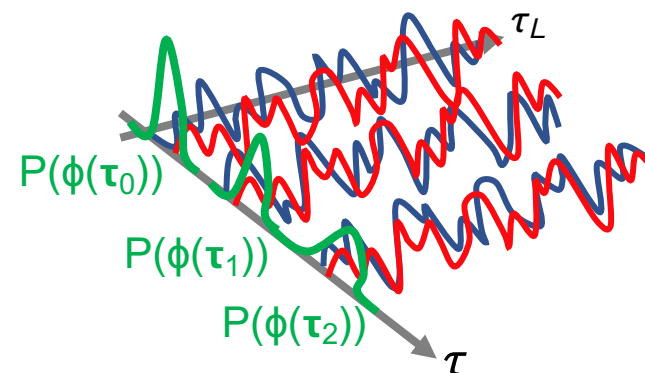
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# Two challenges for Complex Langevin

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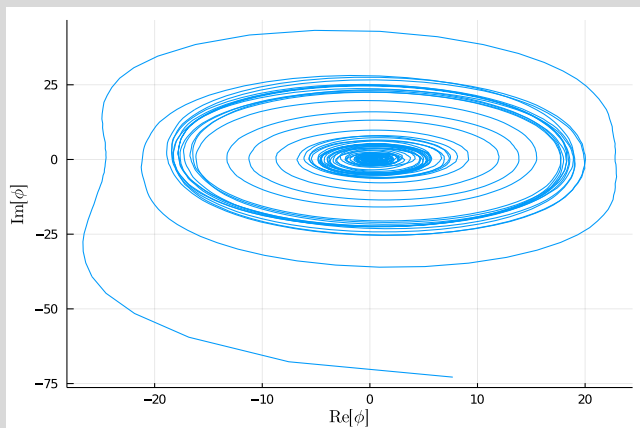


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## Divergent solutions (runaways)



In practice: use adaptive step size  
in attempt to keep solution finite

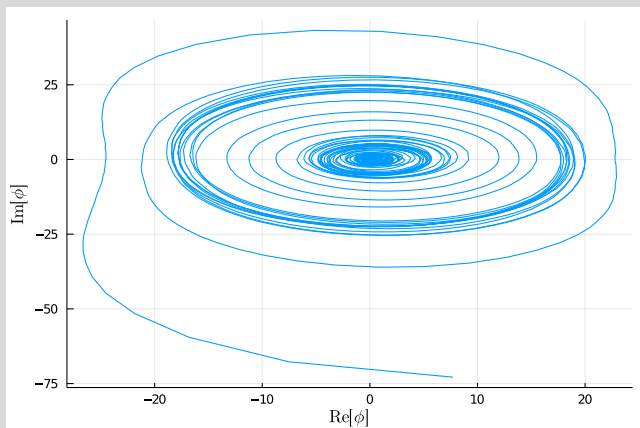
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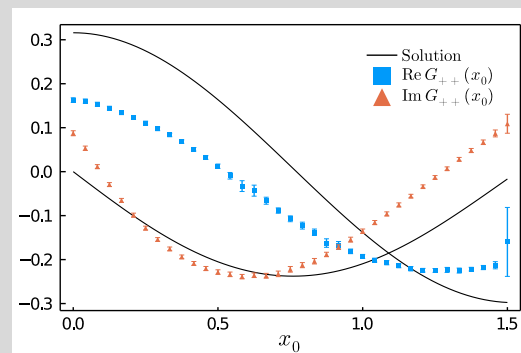
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## Convergence to incorrect solutions as real-time extent increases



$$\int d\phi_R \int d\phi_I O(\phi_R + i\phi_I) P_{CL}(\phi_R, \phi_I) \neq \int d\phi O(\phi) e^{iS[\phi]}$$

Only a posteriori criterion available:  
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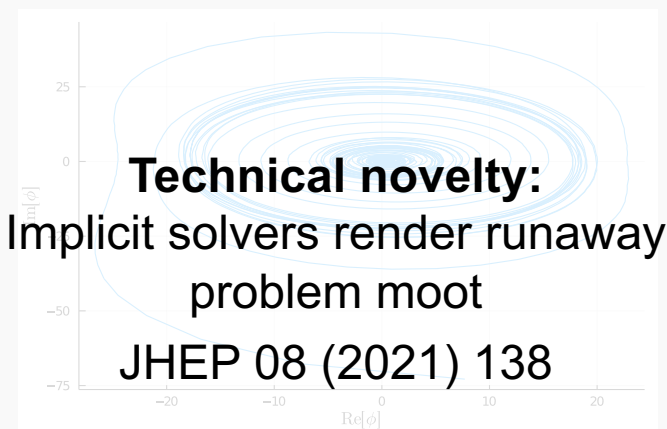
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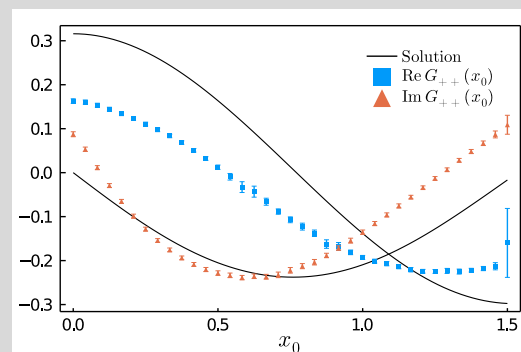
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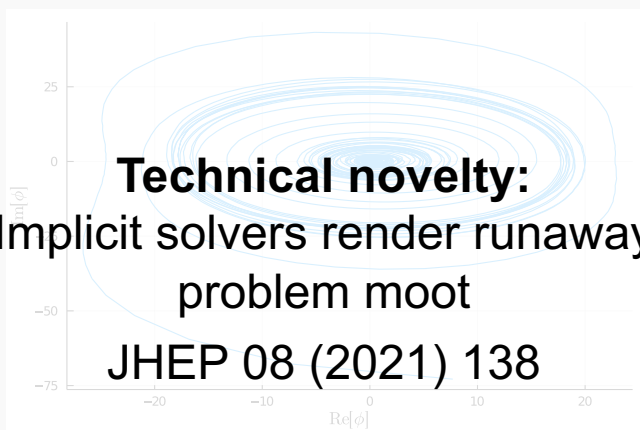
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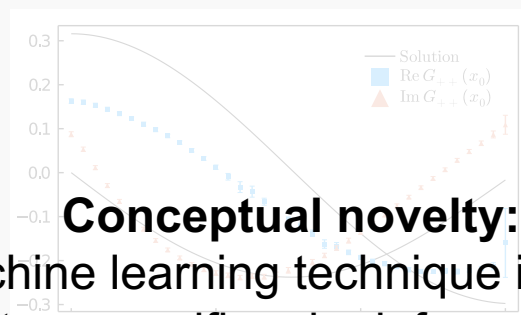
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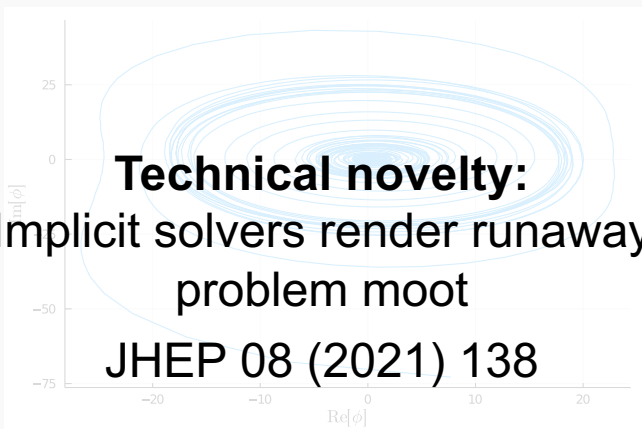
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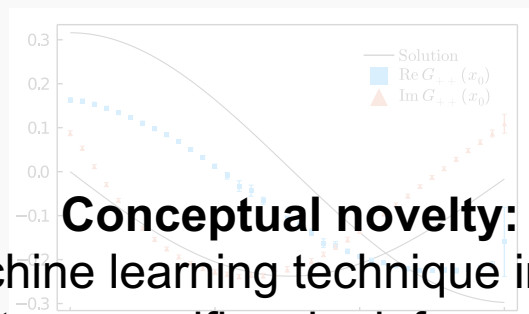
**Technical novelty:**  
Implicit solvers render runaway problem moot

JHEP 08 (2021) 138

provide stability needed to carry out ML optimization

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**Conceptual novelty:**  
Machine learning technique infuses system specific prior information - loop-hole to beat the NP-hard sign problem

JHEP 04 (2023) 057

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# Implicit solvers for Complex Langevin

- Numerical solution of stochastic dynamics in the literature: explicit forward Euler

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$$\frac{d\phi}{d\tau_L} = i \frac{\delta S[\phi]}{\delta \phi(x)} + \eta(x, \tau_L)$$

$$\phi_j^{\lambda+1} = \phi_j^\lambda + i\epsilon \frac{\partial S^\lambda}{\partial \phi_j} + \sqrt{\epsilon} \eta_j^\lambda \quad \epsilon \text{ Langevin time step}$$

- Appearance of runaways indicates **stiff problem**:  
from PDEs we know implicit methods can help



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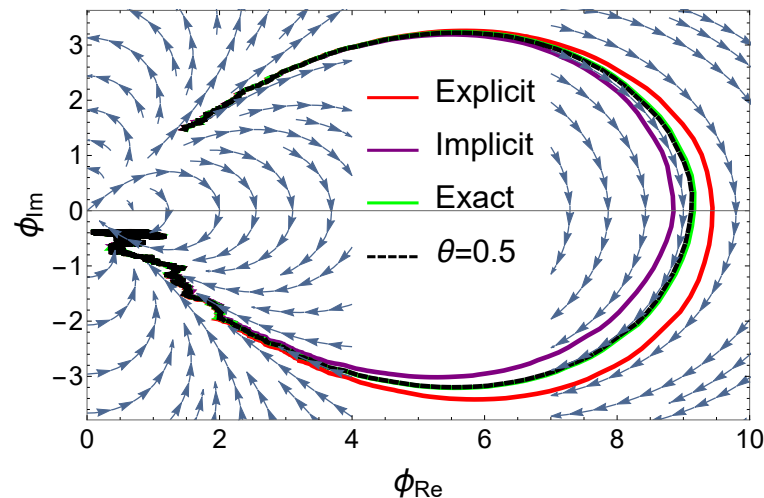
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general Euler-Maruyama scheme

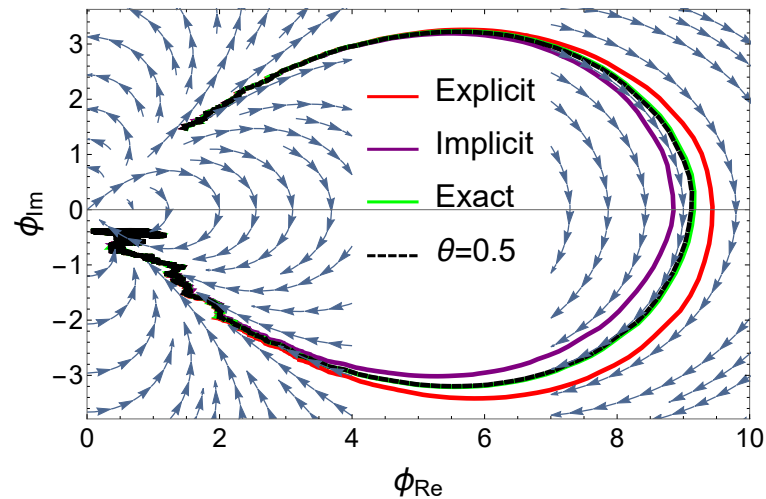
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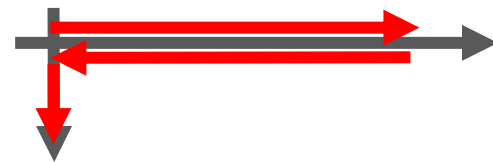
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- Inherent regularization allows for the first time to simulate on untilted SK contour

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$$S_\theta = \frac{1}{2} \phi \left( M + i\epsilon \theta M^2 \right) \phi = S_{\text{explicit}} + \frac{i\epsilon}{2} \theta \sum_j S_j^2$$



# CL at short real-times in 0+1d

- Direct simulations **anharmonic oscillator** on the canonical SK contour in **thermal equilibrium** possible  $m=1$   $\lambda=24$   $\beta m=m/T=1$

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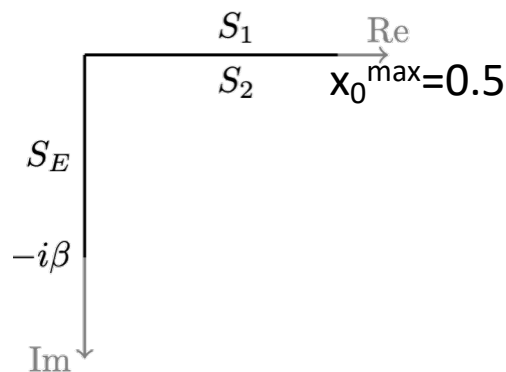
$$S = \frac{1}{2} \sum_j \left\{ \frac{(\phi_{j+1} - \phi_j)^2}{a_j} - a_j [V(\phi_{j+1}) + V(\phi_j)] \right\} \quad V(\phi_j) = \frac{\lambda}{4!} \phi_j^4$$

$$i \frac{\delta S[\phi]}{\delta \phi_j} = \frac{i}{\frac{1}{2} (|a_j| + |a_{j-1}|)} \left\{ \frac{\phi_j - \phi_{j-1}}{a_{j-1}} - \frac{\phi_{j+1} - \phi_j}{a_j} - \frac{1}{2} [a_{j-1} + a_j] \frac{\partial V(\phi_j)}{\partial \phi_j} \right\}$$

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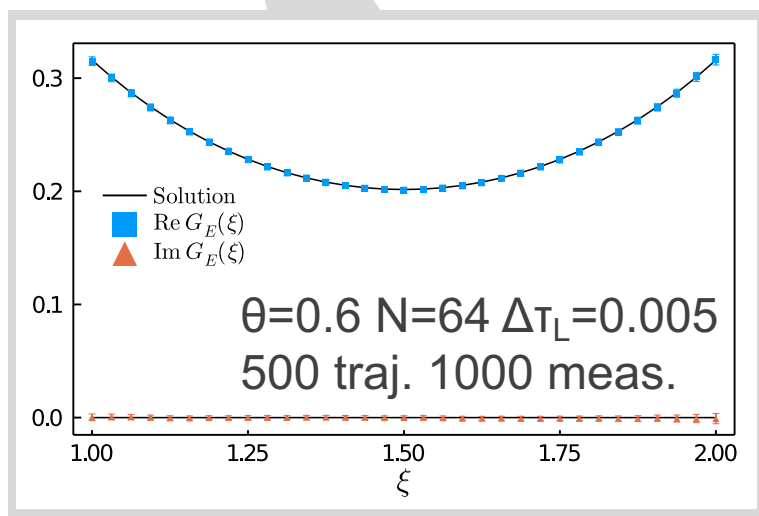
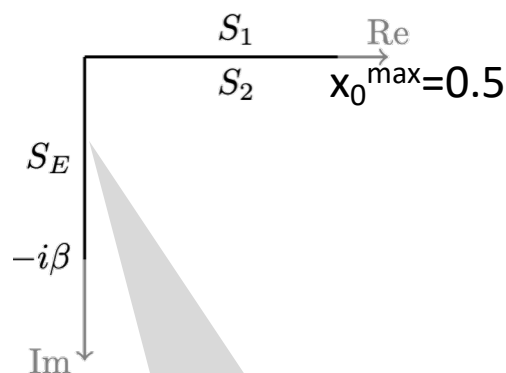
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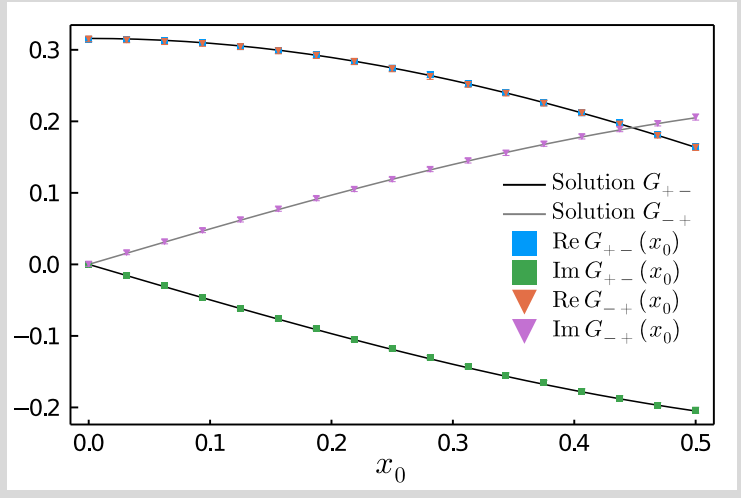
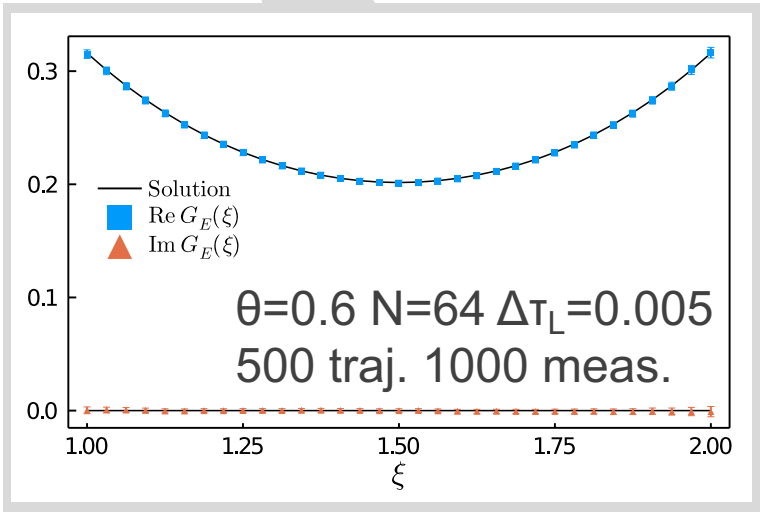
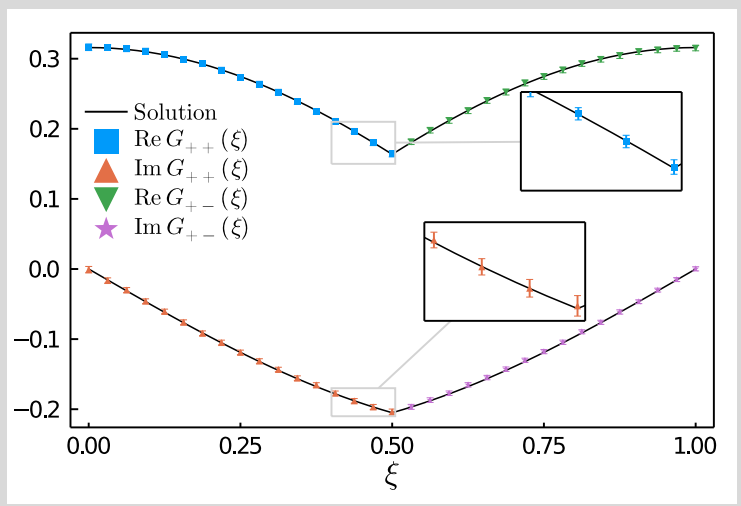
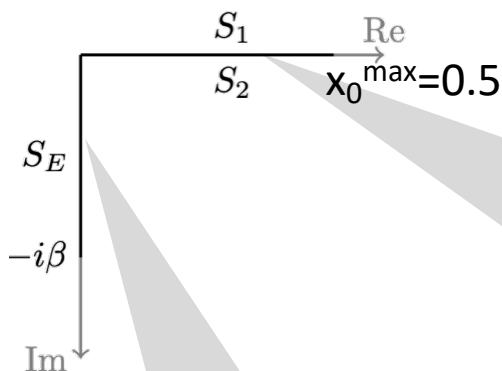
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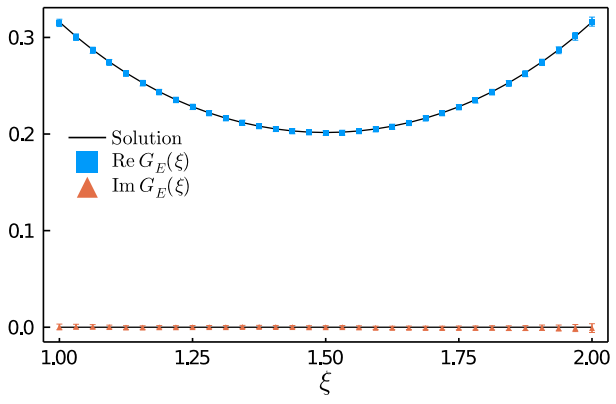
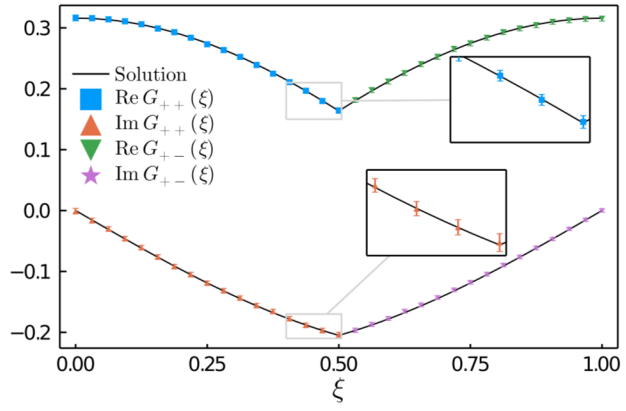
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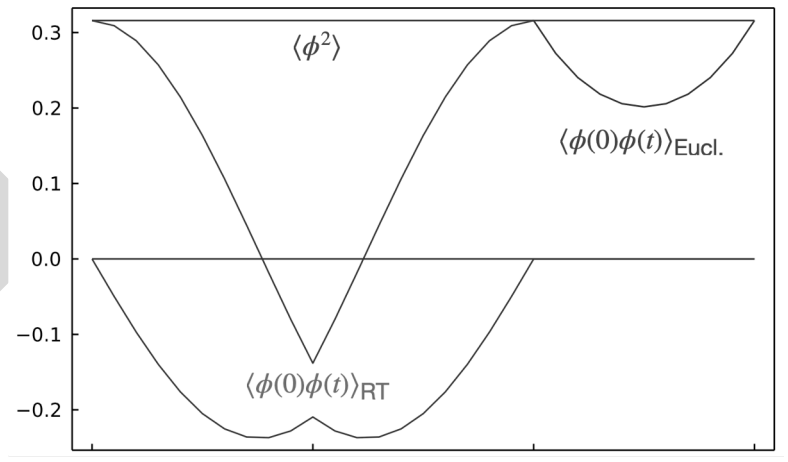
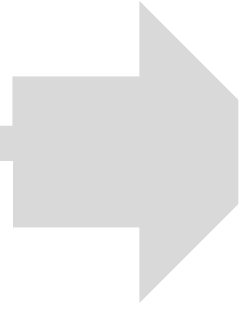
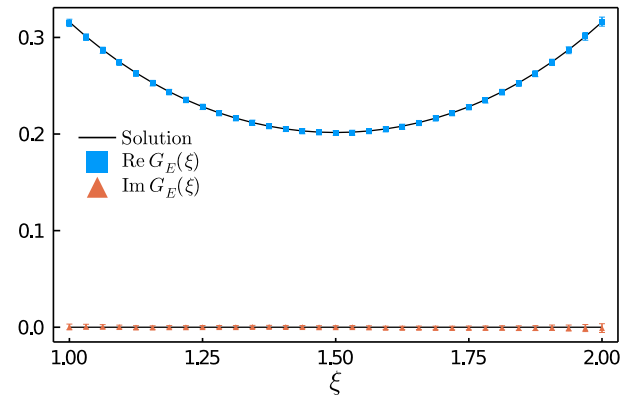
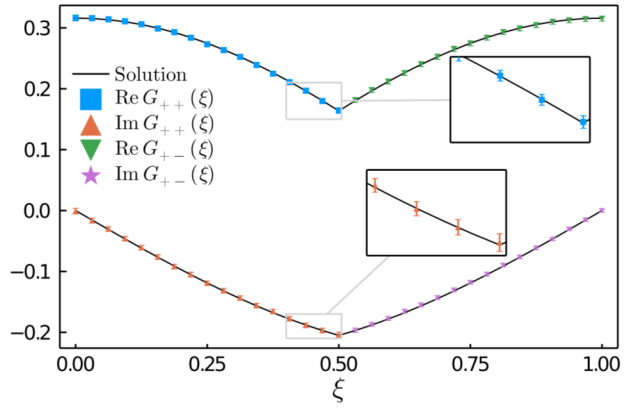
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# What happens at later real-time?

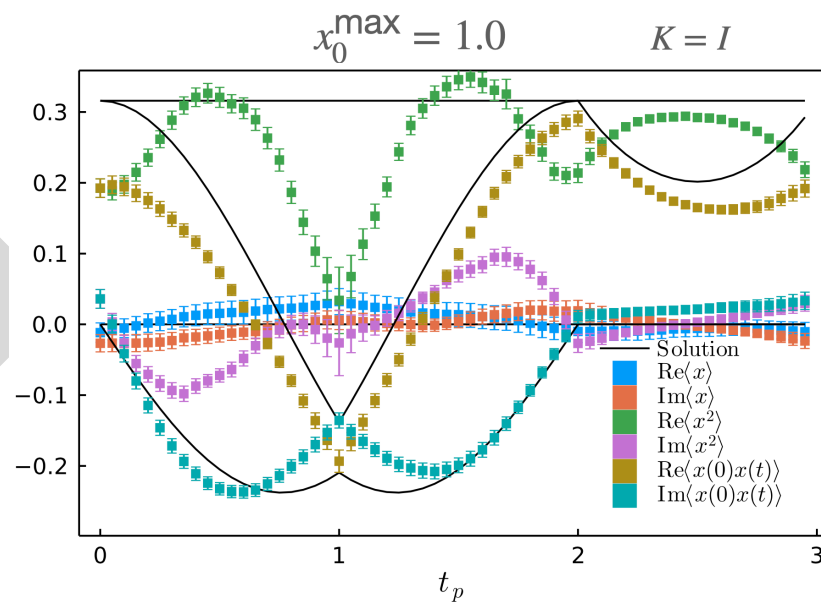
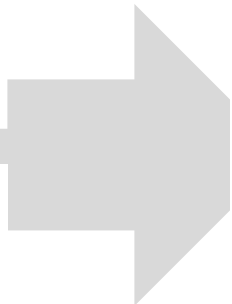
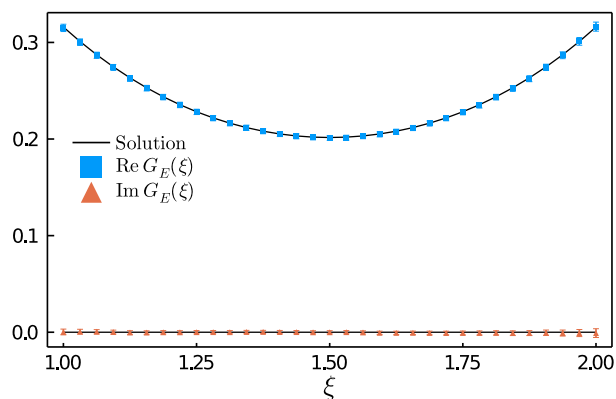
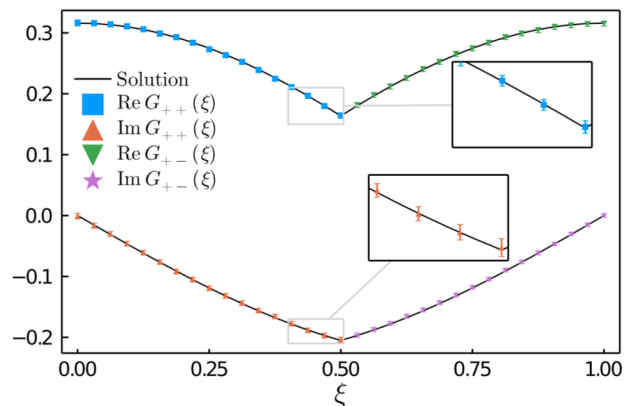


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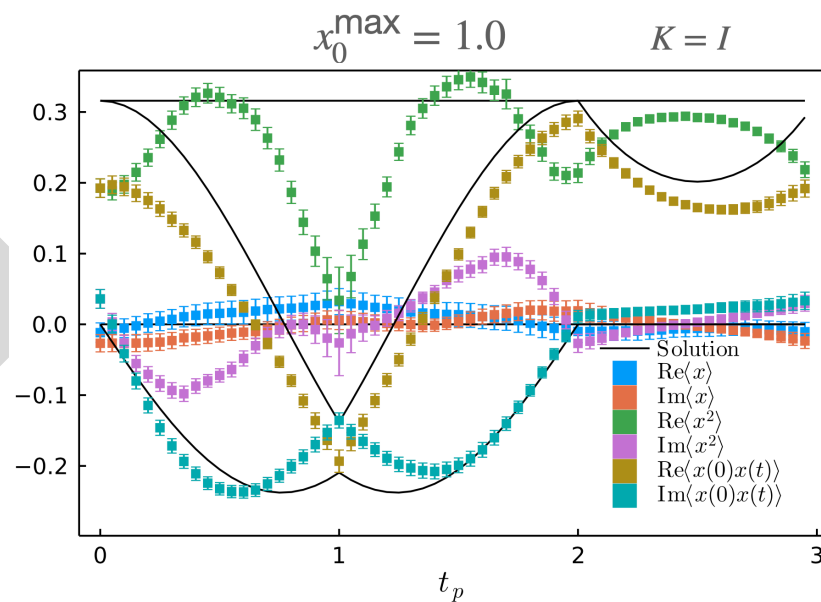
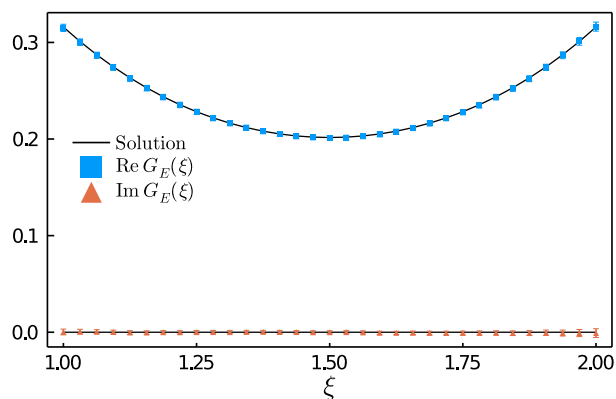
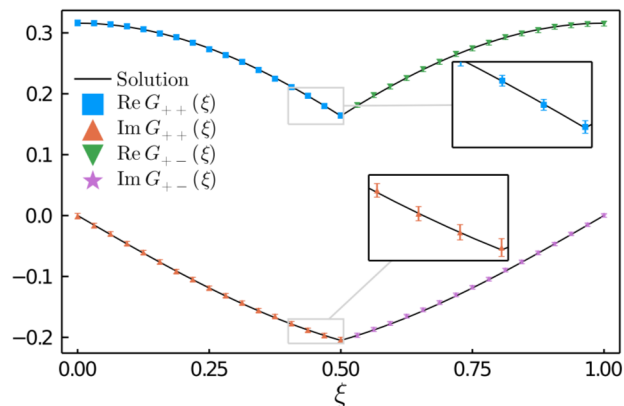




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Convergence to incorrect solution without apparent pathologies

# Convergence in CL

$$\lim_{\tau_L \rightarrow \infty} \int d\phi_R d\phi_I \mathcal{O}(\phi_R + i\phi_I) P_{\text{CL}}[\phi_R, \phi_I, \tau_L] \stackrel{?}{=} \int d\phi \mathcal{O}(\phi) e^{iS}$$

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developed in: G. Aarts et.al.  
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- Our idea for NP-hard sign problem: incorporate **system specific prior information** without affecting the proof of convergence

# Kernelled complex Langevin

- Simultaneous modification of drift and noise allows to alter FP spectrum

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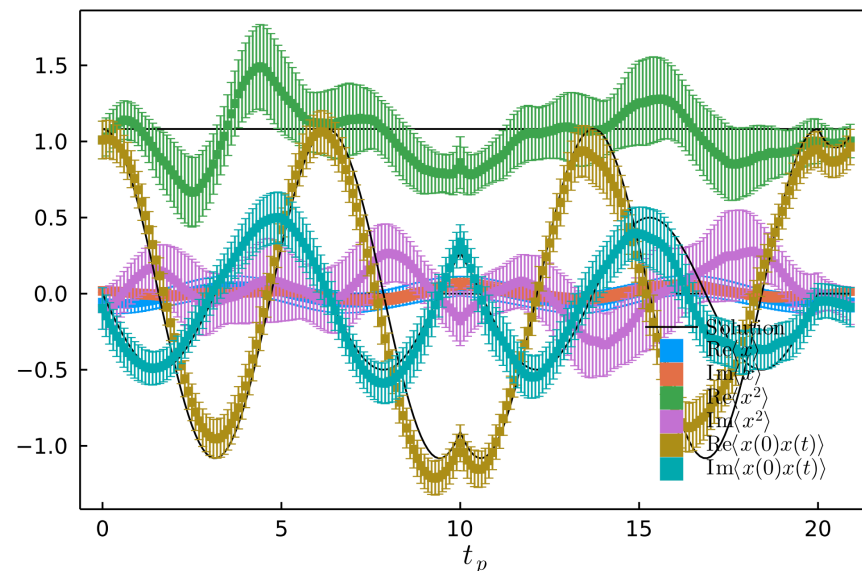
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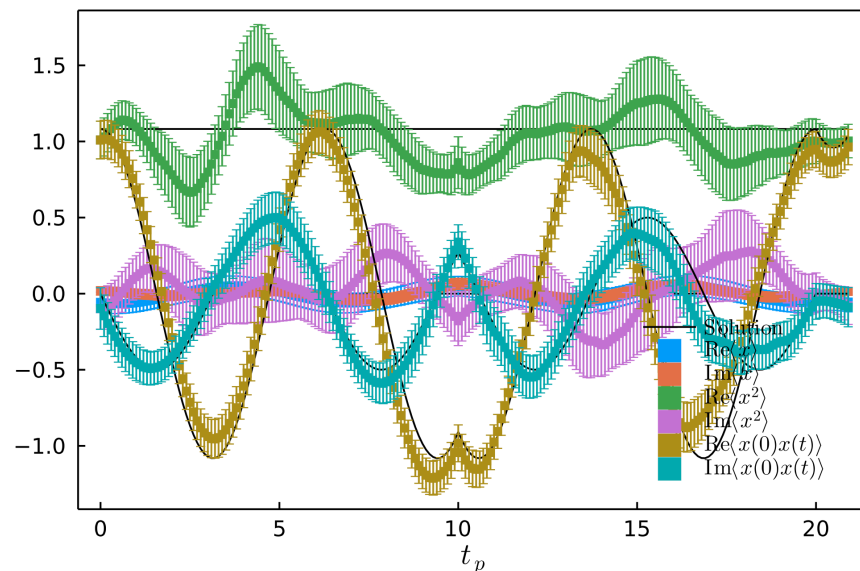
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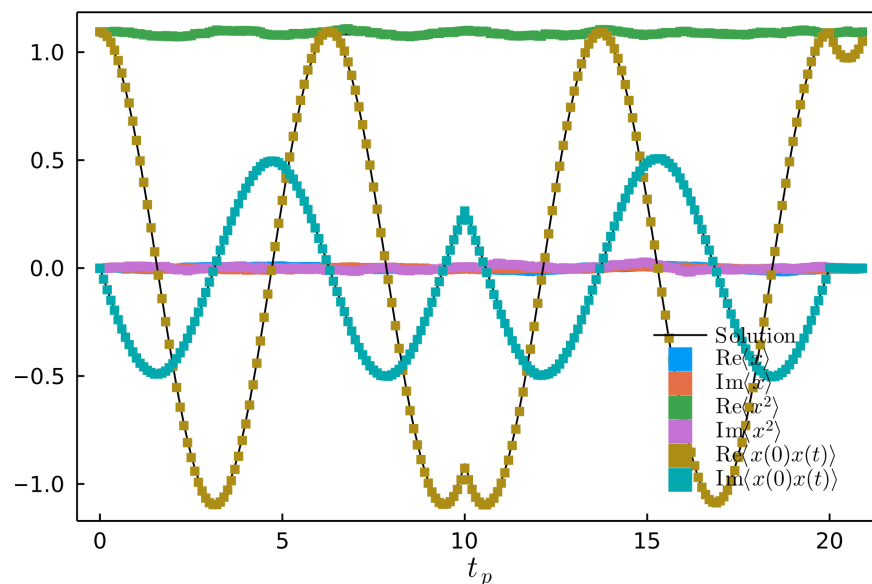
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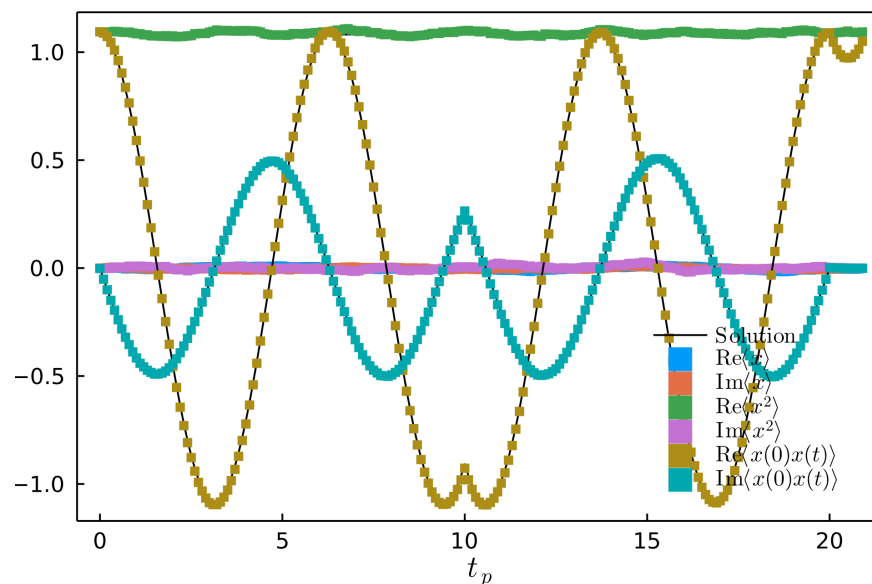
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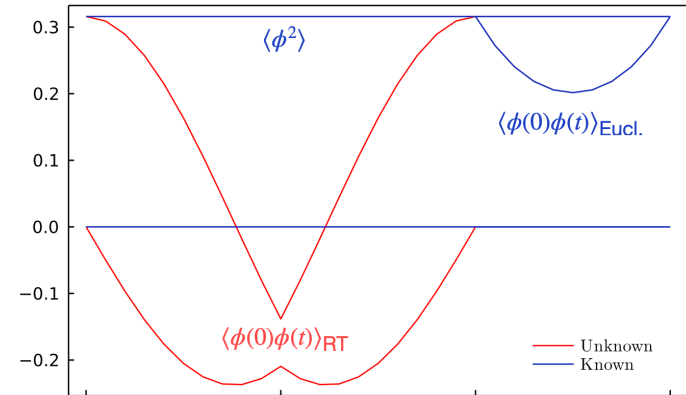
- Allows us to extend correct convergence to any real-time extent in free theory

# Systematic learning of optimal kernels



## Optimality via prior information: Symmetries, Euclidean correlator, Boundary

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# Systematic learning of optimal kernels

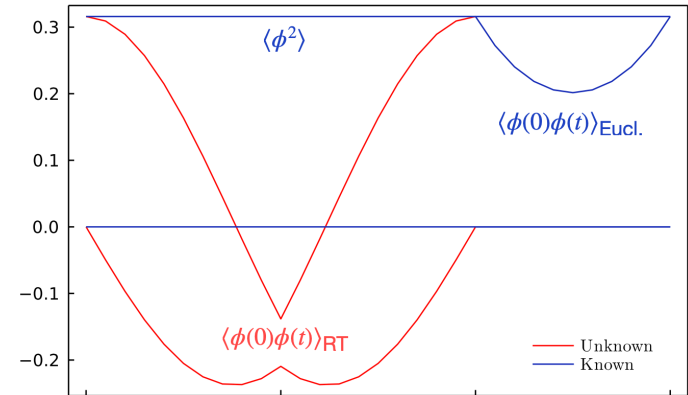
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D. Alvestad, R. Larsen, A.R. JHEP 04 (2023) 057

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$$L^{\text{bnd}} = \sum_i \sum_k \{ \langle L_c[\phi_i] \mathcal{O}_k \rangle_Y \}^2$$

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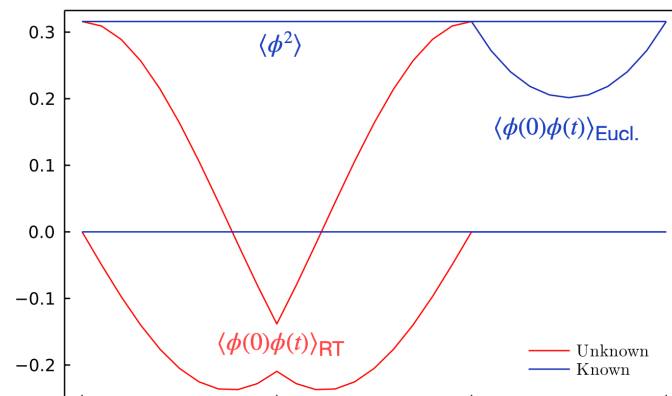
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## Autodifferentiation techniques to compute $\frac{\partial L^{\text{tot}}}{\partial K_{ij}}$ (derivative of stochastic process)

[ note: deterministic dynamics chaotic ]

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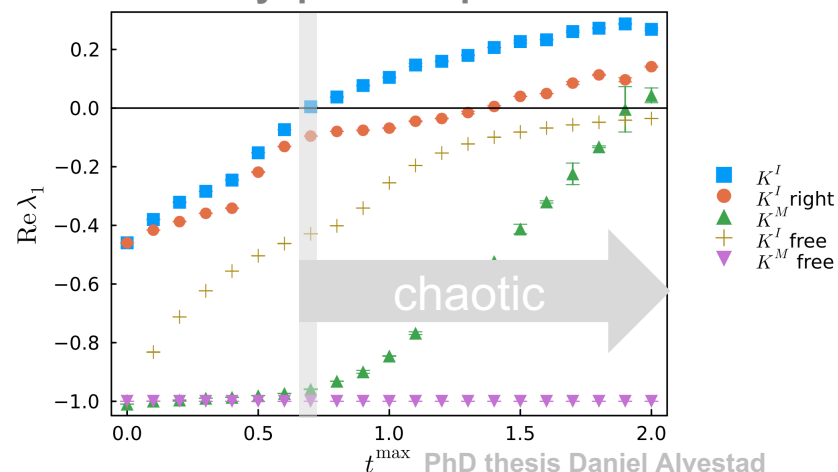
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## Autodifferentiation techniques to compute [ note: deterministic dynamics chaotic ]

CL Lyapunov exponents



$\frac{\partial L^{\text{tot}}}{\partial K_{ij}}$  (derivative of stochastic process)



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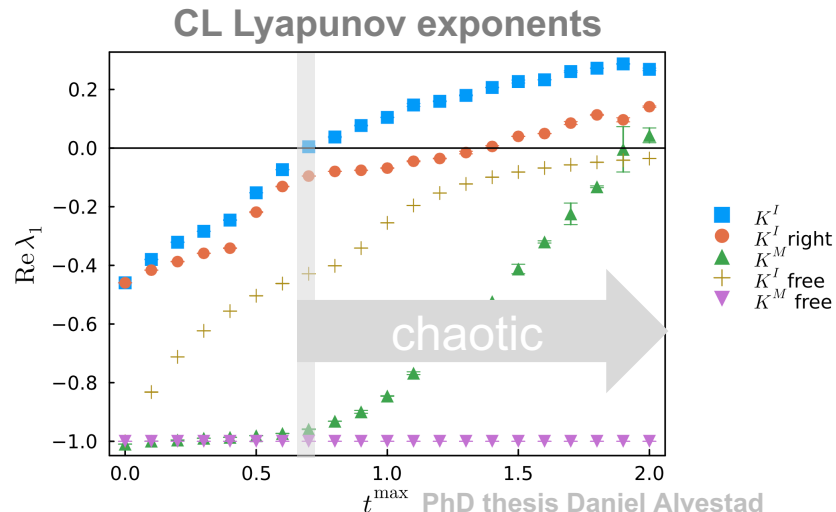
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Autodifferentiation techniques to compute  $\frac{\partial L^{\text{tot}}}{\partial K_{ij}}$  (derivative of stochastic process)  
 [ note: deterministic dynamics chaotic ]

In principle possible, in practice slow: cheaper optimization functional instead

$$L^{\text{low cost}} = \frac{1}{N_t} \sum_{i=1}^{N_t} \left| K \frac{\partial S}{\partial \phi_t} (-\phi_t) - \left| K \frac{\partial S}{\partial \phi_t} \right| |\phi_t| \right|^2$$

$$L^{\text{low cost}} = \frac{1}{N_t} \sum_{i=1}^{N_t} \text{Im}[\phi]^2$$

minimizes drift away from the origin  
 (c.f. dynamic stabilization but holomorphic)

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inspired by study of novel boundary criterion for detection of incorrect convergence

N. Lampl and D. Sexty (in preparation)

# Performance in 0+1d (AHO)

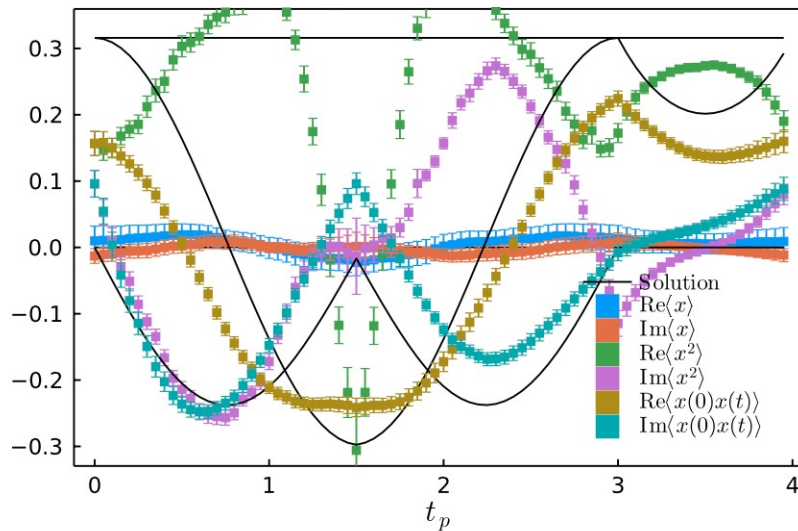
- Using a constant kernel  $K = \exp[A + iB]$  with A,B real matrices
- Optimize via low cost functional & check success via symmetries & Euclidean corr.

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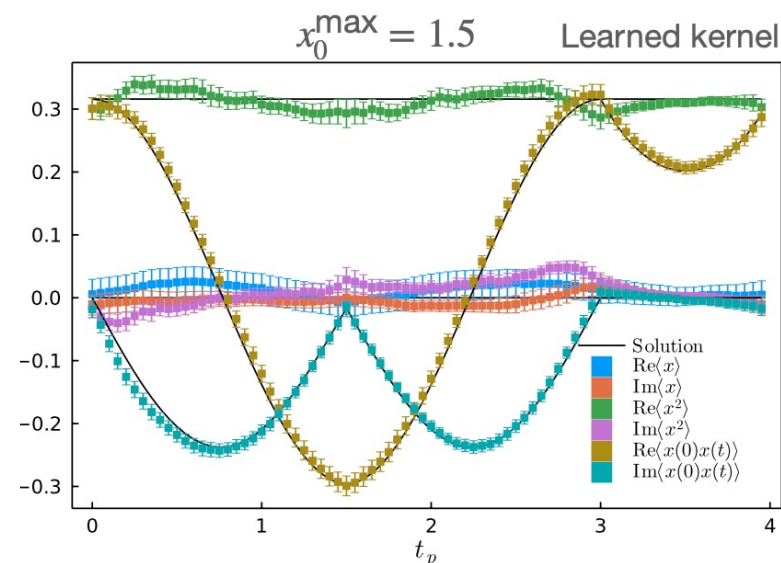
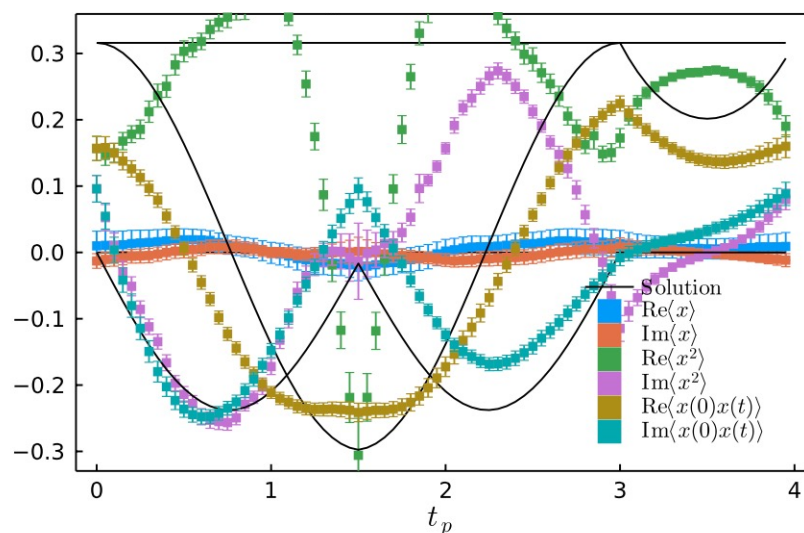
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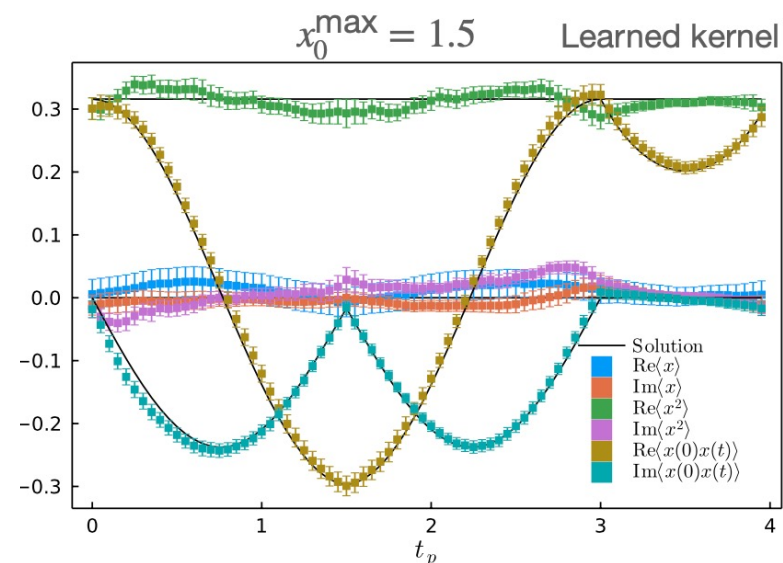
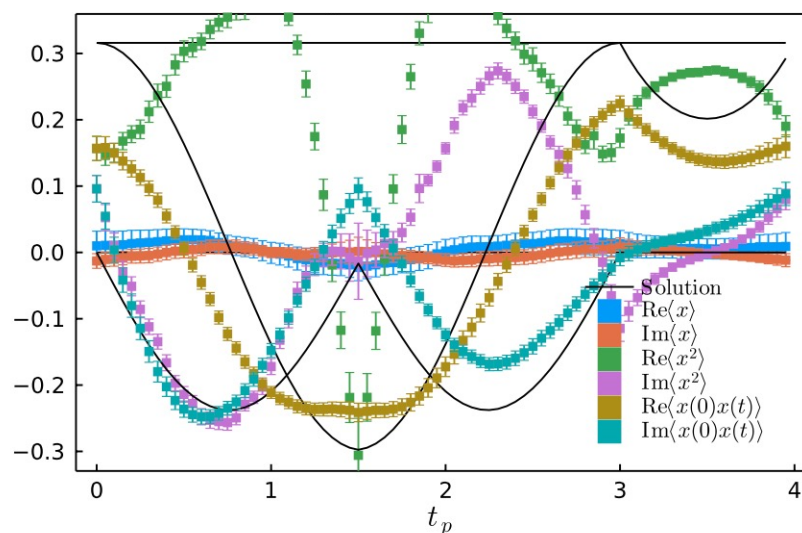
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- Achieve correct convergence up to **3x time extent** previously reported in literature

# Recent results in 1+1d field theory

$$S[\phi] \equiv \sum_{t,n} a_t a \left[ \frac{(\phi_{t+1,n} - \phi_{t,n})^2}{2a_t^2} + \frac{1}{2} \left( \frac{(\phi_{t+1,n+1} - \phi_{t+1,n})^2}{2a^2} + \frac{(\phi_{t,n+1} - \phi_{t,n})^2}{2a^2} \right) + \frac{1}{2} m^2 \frac{\phi_{t,n}^2 + \phi_{t+1,n}^2}{2} + \frac{\lambda}{4!} \frac{\phi_{t+1,n}^4 + \phi_{t,n}^4}{2} \right]$$

- Promising scaling: CL with # of grid points – field independent kernel avoids need for Jacobian – implicit solvers performant even though Newton step

# Recent results in 1+1d field theory

$$S[\phi] \equiv \sum_{t,n} a_t a \left[ \frac{(\phi_{t+1,n} - \phi_{t,n})^2}{2a_t^2} + \frac{1}{2} \left( \frac{(\phi_{t+1,n+1} - \phi_{t+1,n})^2}{2a^2} + \frac{(\phi_{t,n+1} - \phi_{t,n})^2}{2a^2} \right) + \frac{1}{2} m^2 \frac{\phi_{t,n}^2 + \phi_{t+1,n}^2}{2} + \frac{\lambda}{4!} \frac{\phi_{t+1,n}^4 + \phi_{t,n}^4}{2} \right]$$

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- Found that for 1+1d low-cost functional proposed by Graz group offers even better performance. N. Lampl and D. Sexty (in preparation)

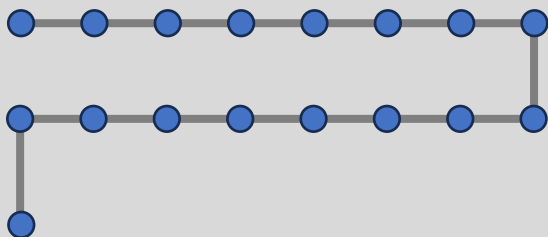
$$L^{\text{low cost}} = \frac{1}{N_t} \sum_{i=1}^{N_t} \text{Im}[\phi]^2$$

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## Current community benchmark



$$N_t=8 \quad N_x=8 \quad a=0.2$$

$$m=1 \quad \lambda=1 \quad \beta m = m/T=0.4 \quad N_x=8$$

A. Alexandru et.al. PRD 95 (2017) 11, 114501

- based on contour deformations
- coarse grid on SK due to cost

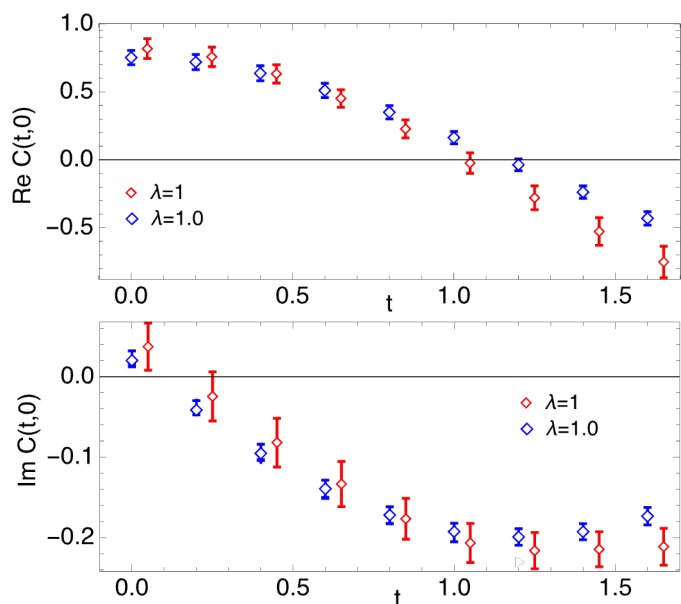


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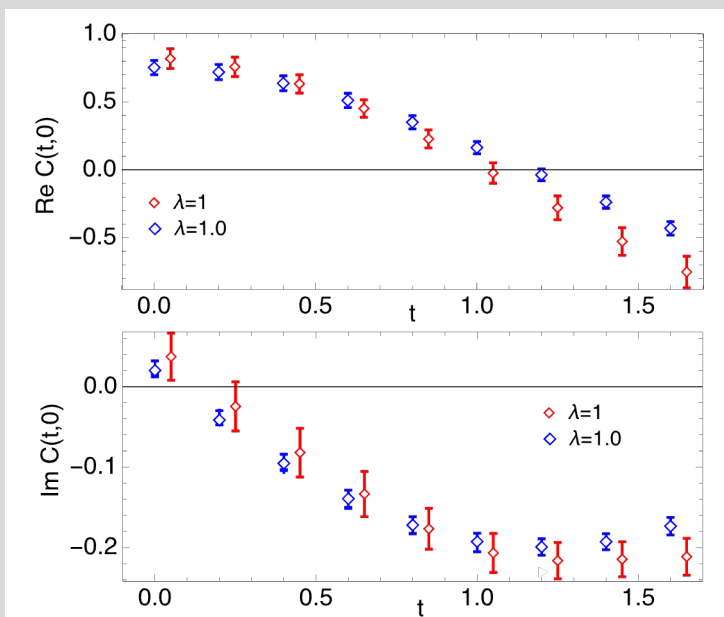
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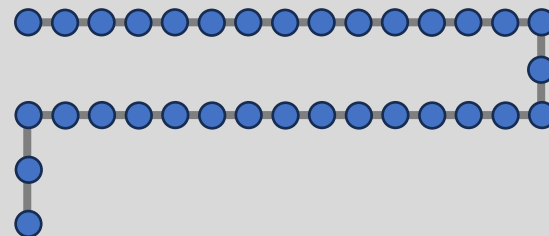
## Current community benchmark



A. Alexandru et.al. PRD 95 (2017) 11, 114501

- based on contour deformations
- coarse grid on SK due to cost

## Optimal learned CL kernels



$N_t=16 \quad N_T=4 \quad a_t=0.1 \quad a_s=0.2$

$m=1 \quad \lambda=1 \quad \beta m=m/T=0.4 \quad N_x=8$

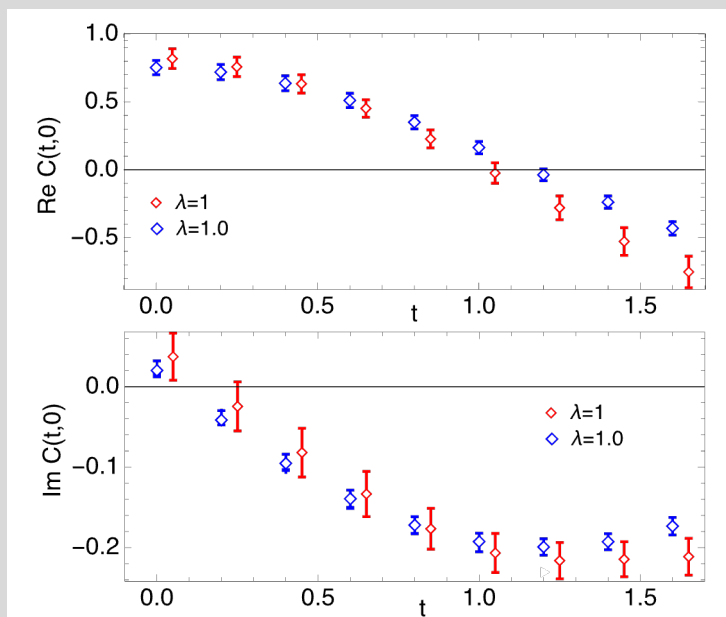
(D.A., A.R., N. Lampl, D. Sexty, in preparation)

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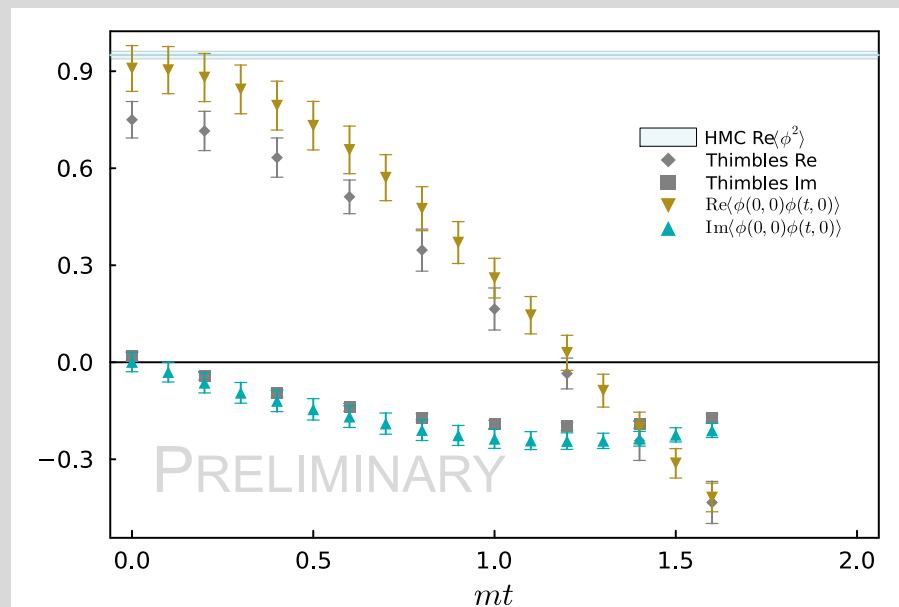
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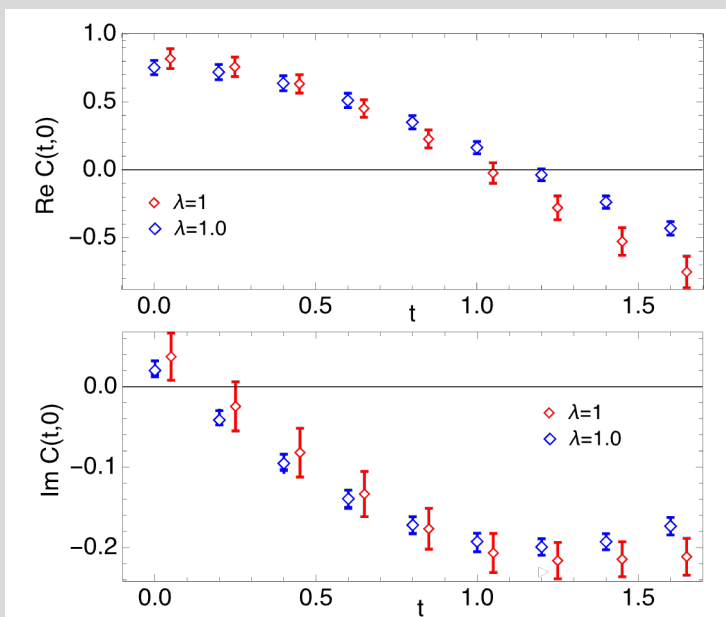
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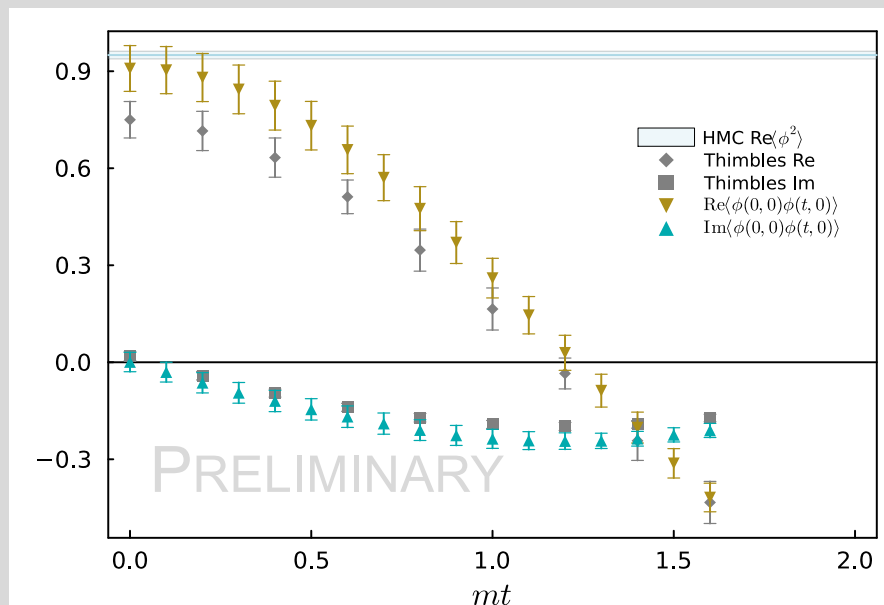
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A. Alexandru et.al. PRD 95 (2017) 11, 114501

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- avoid discretization artifacts with finer grids

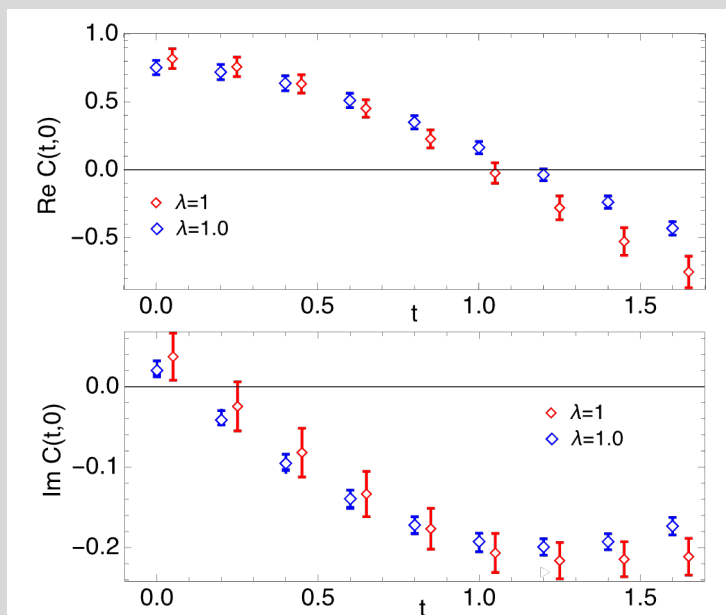
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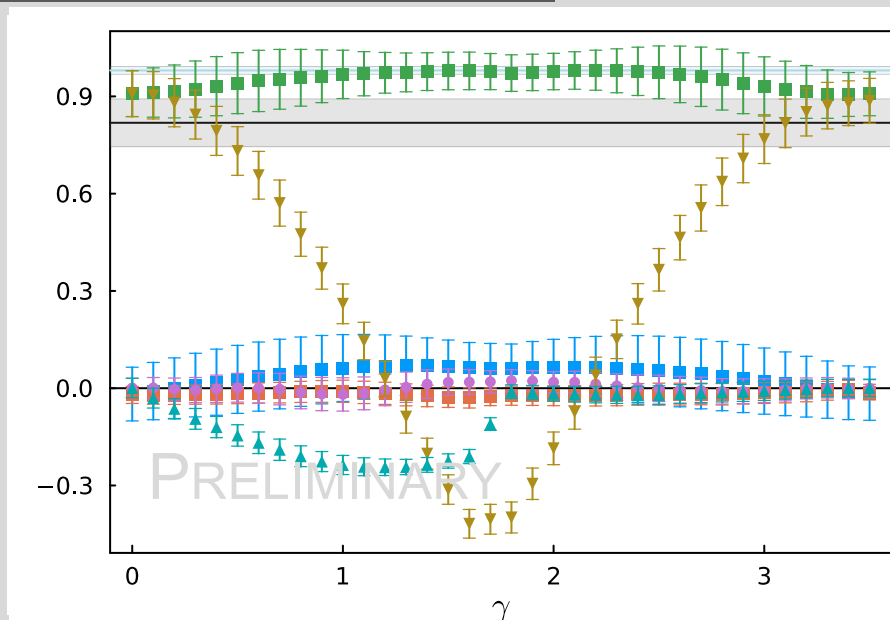
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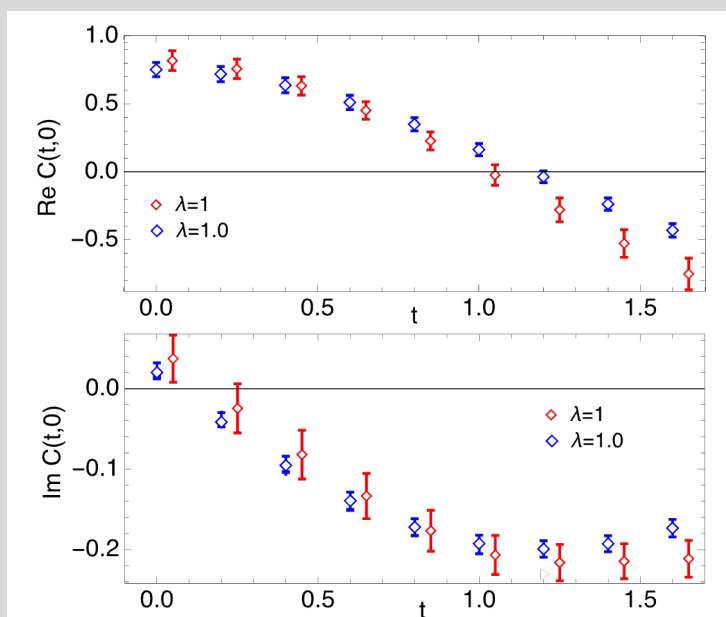
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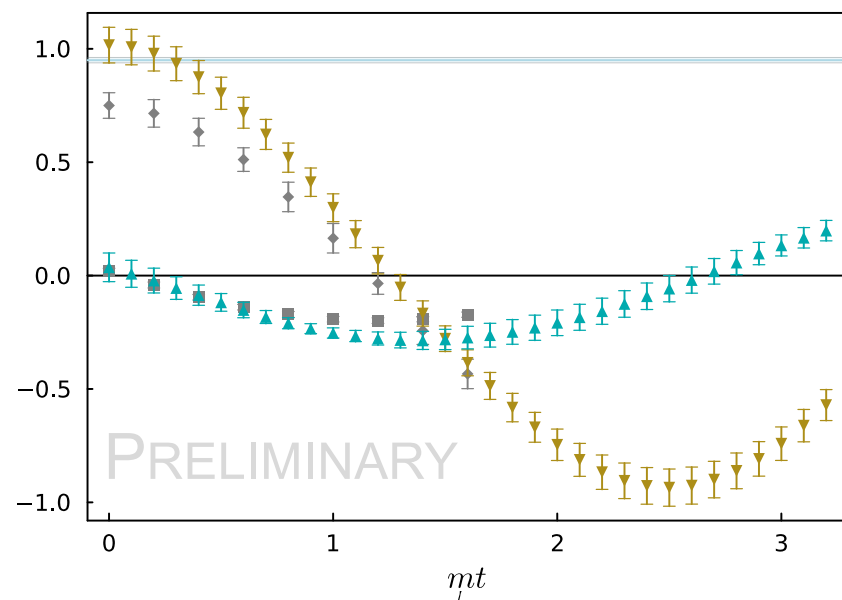
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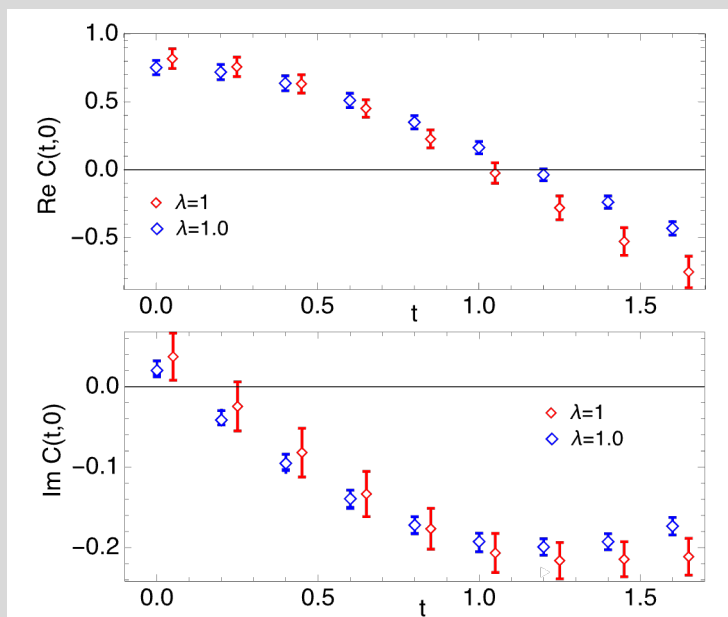
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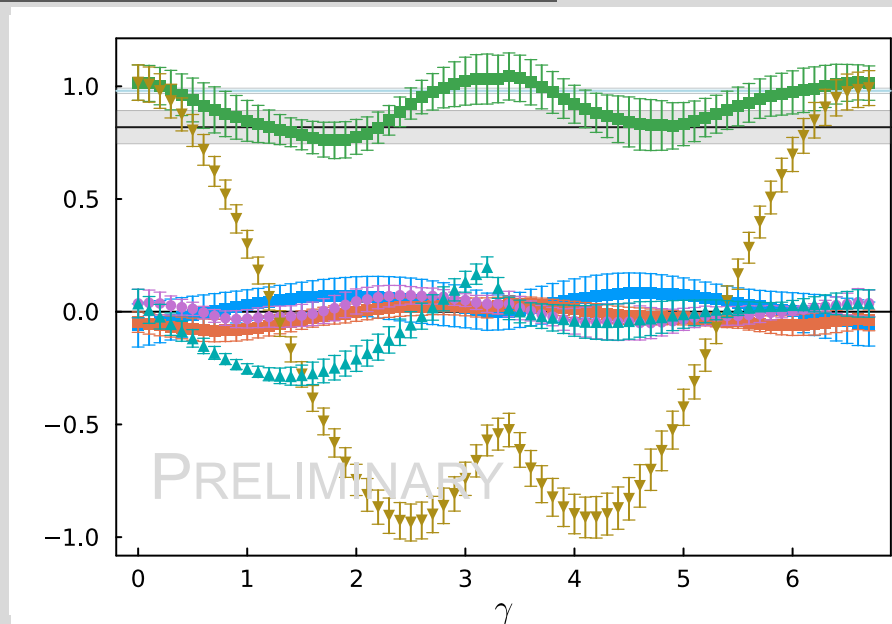
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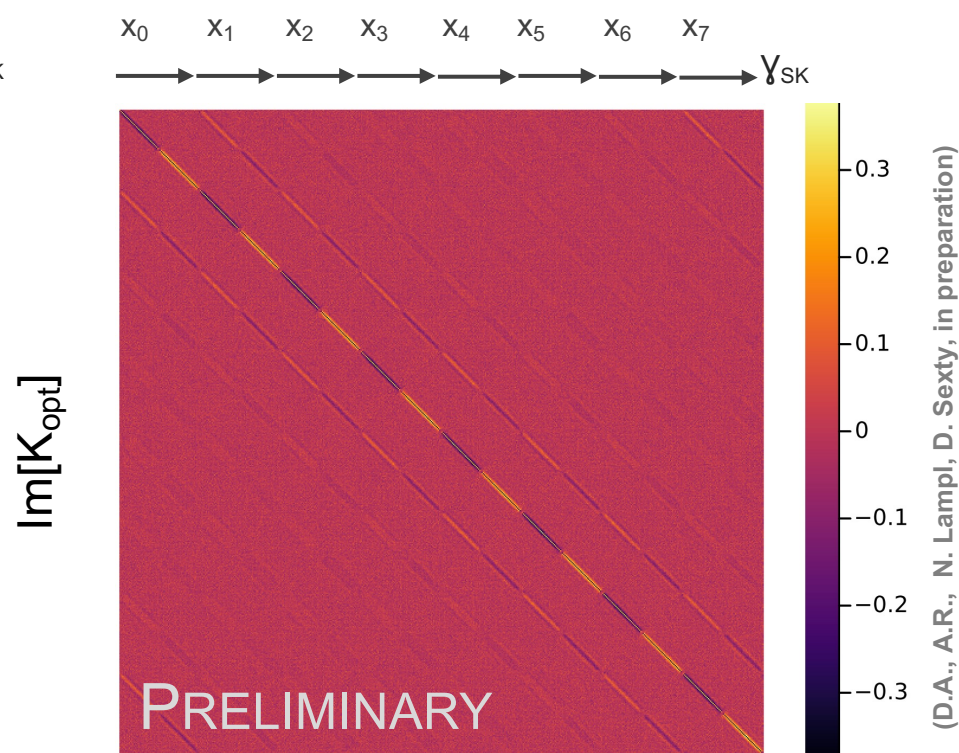
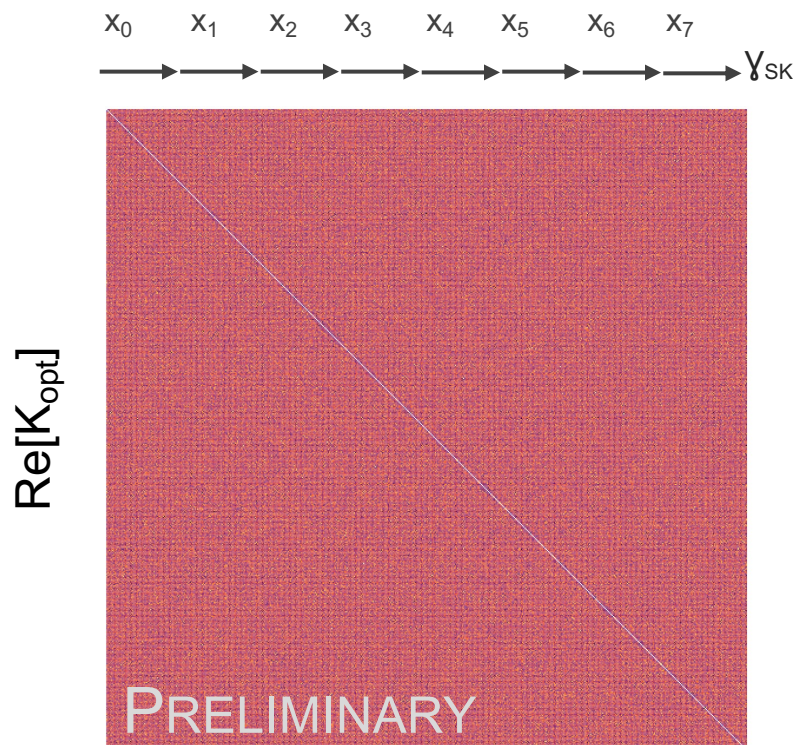
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- Form of optimal kernel dependent on optimization functional  $L^{\text{low cost}}$



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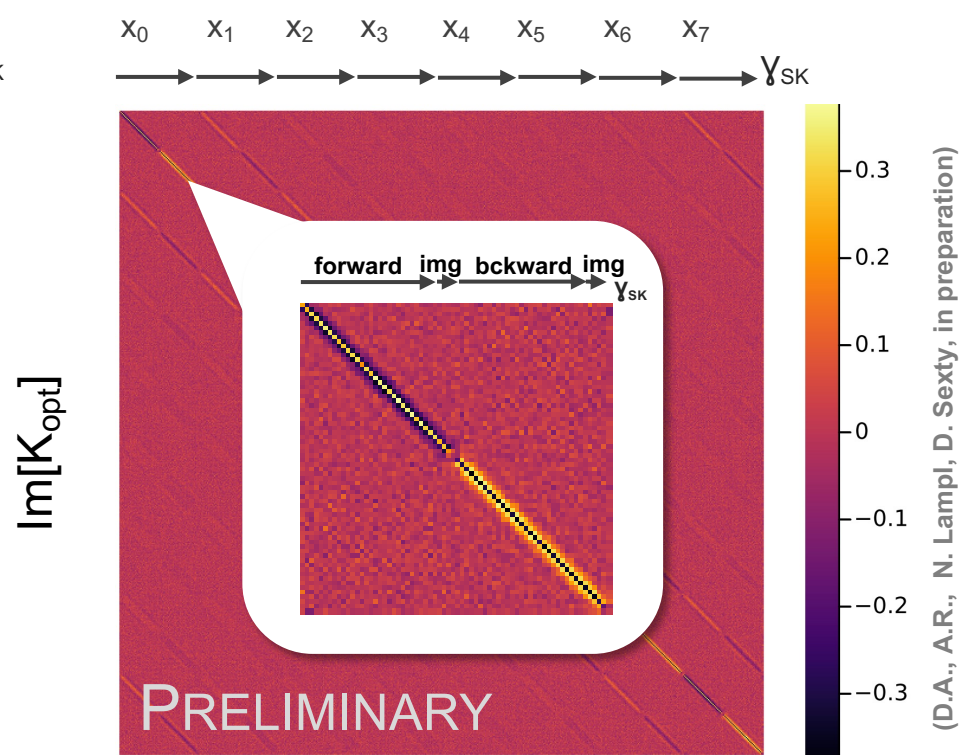
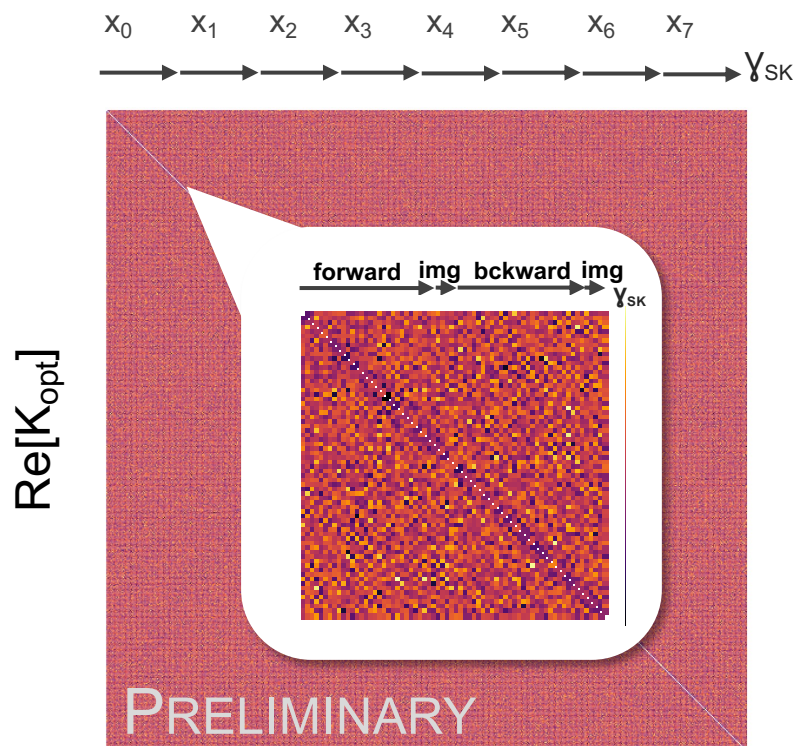
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- We find: **Re[K]** dominated by **diagonal term**, no further distinct structure  
**Im[K]** **banded structure** in spatial dimension with diminishing amplitude



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(D.A., A.R., N. Lampl, D. Sexty, in preparation)

- Derivative-like pattern in **Im[K]** mixing neighboring d.o.f. on the SK contour

# Conclusion & Outlook

- Overcoming **NP-hard sign problem** central to progress in theoretical physics
- **Complex Langevin** one possible path forward, but hampered by two major challenges: **instabilities** and **convergence to incorrect** solutions
- **Implicit solvers** render the runaway problem moot & allow stable optimization. Realize simulations on the **canonical** Schwinger-Keldysh contour.
- **ML strategy**: systematically incorporate **system specific prior information** (symmetries, Euclidean correlators, etc.) in simulation via **kernel** modification

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## Learned optimal field independent kernels

- Optimal **kernels in QM**: 3x extended range of validity of real-time CL
- Optimal **kernels in 1+1d**: new benchmark in accuracy & real-time extent (~2x)

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- Next step: **2+1d simulations**, cost effective optimization strategies for **field dependent kernels** (adjoint sensitivity analysis, shadowing method (NILSS), etc.)

# Backup slides

# Limits to our current strategy

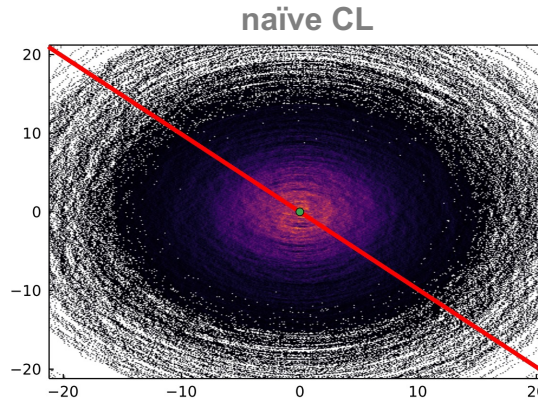
- Constant kernel works well in theories with single critical point at the origin

simple  
Gaussian  
model

$$S = \frac{1}{2} i x^2$$

Lefschetz  
thimbles

$$\frac{d\phi}{d\tau} = \overline{\frac{dS}{d\phi}}$$



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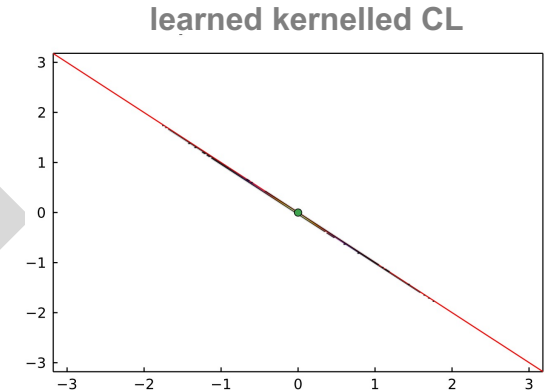
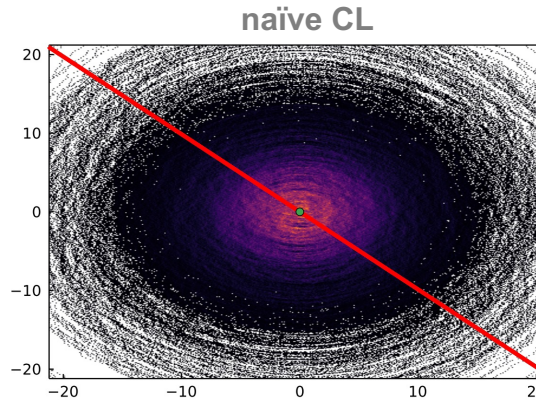
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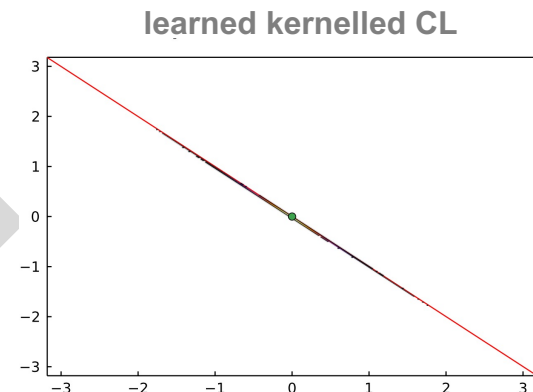
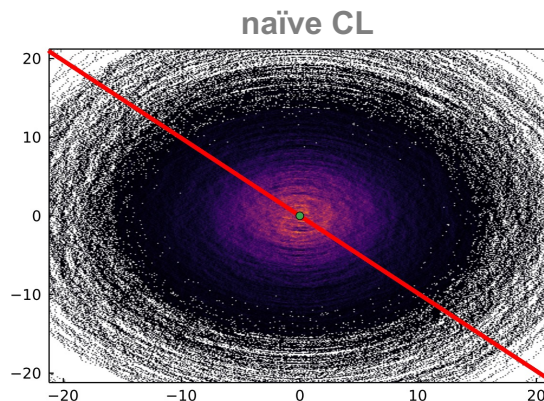
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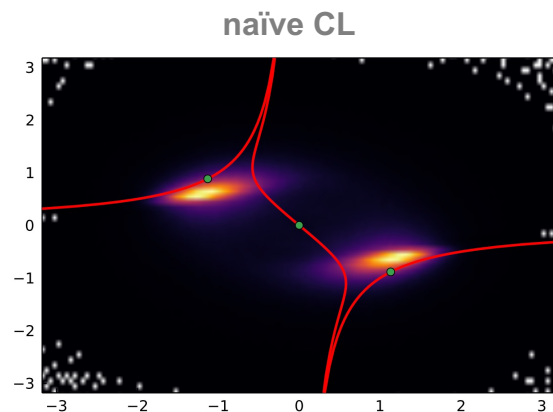
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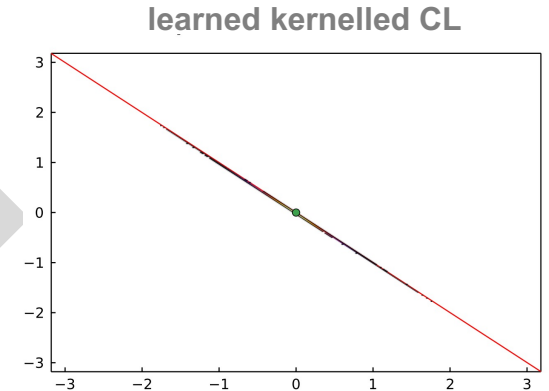
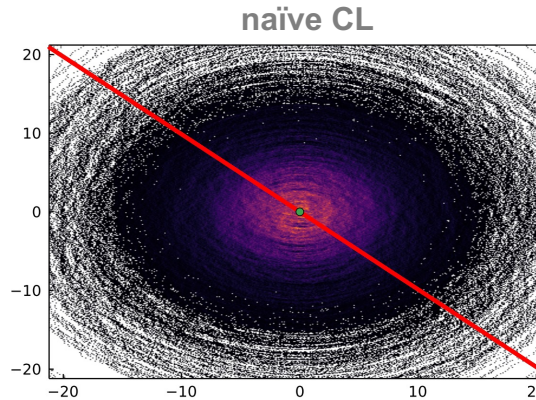
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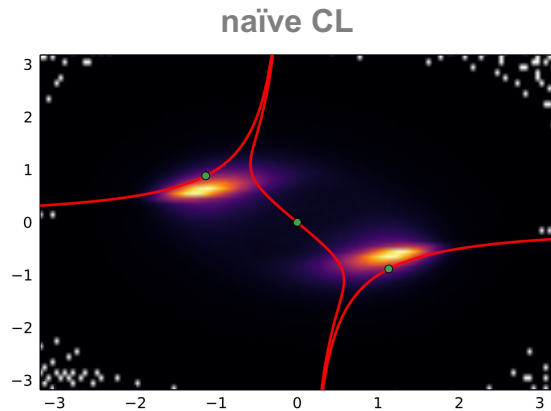
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$L^{\text{tot}}=0.888$

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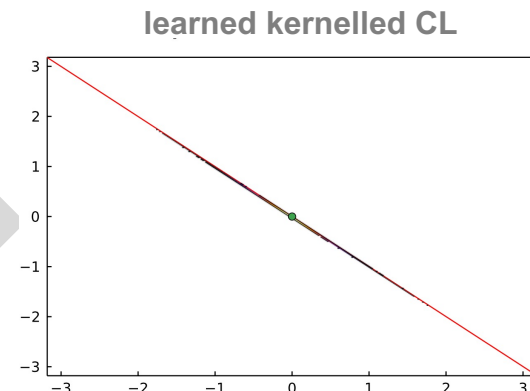
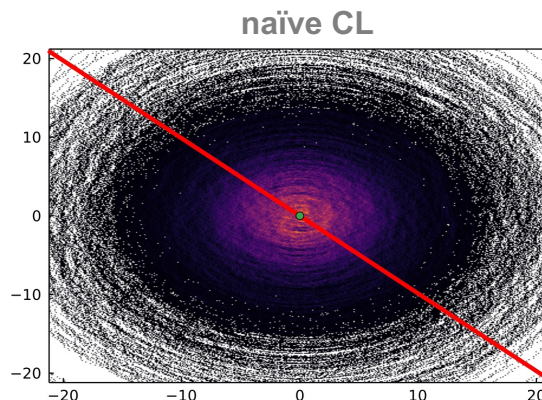
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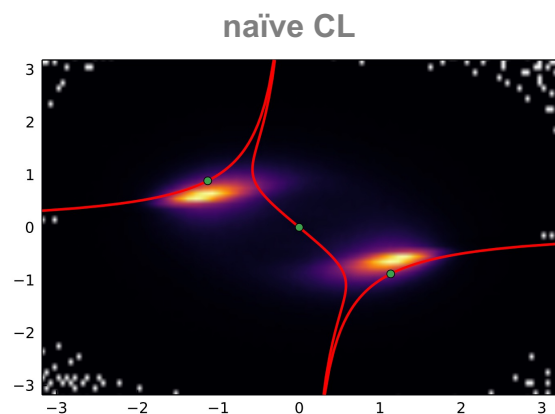
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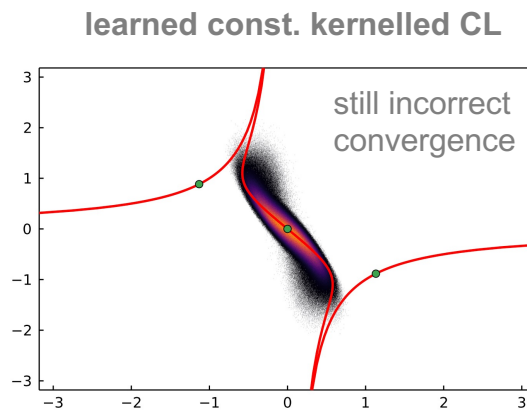
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$L^{\text{tot}}=0.888$



$L^{\text{tot}}=0.486$

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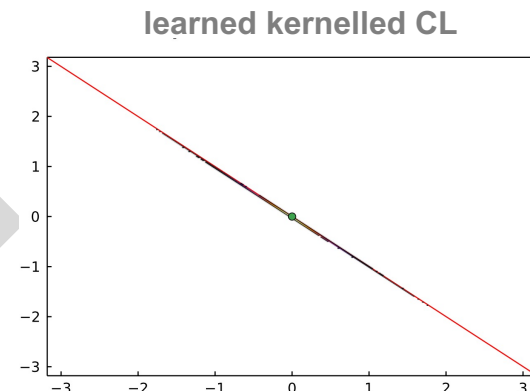
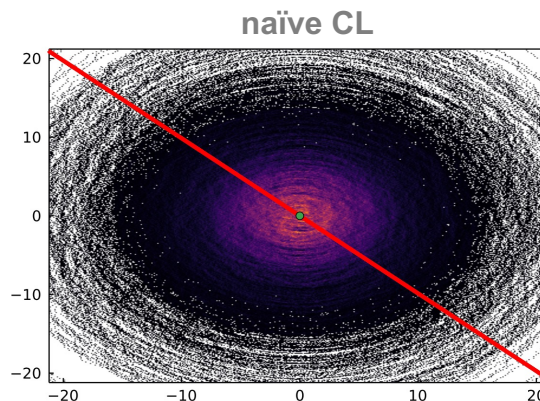
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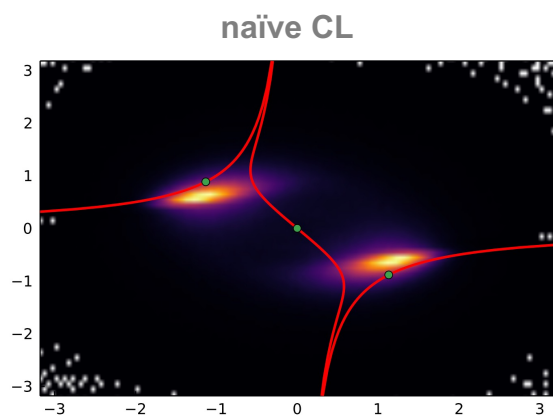
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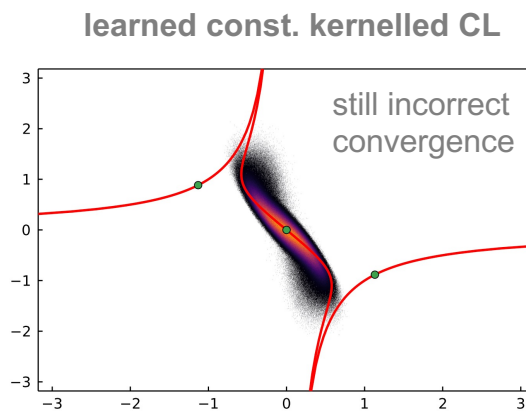
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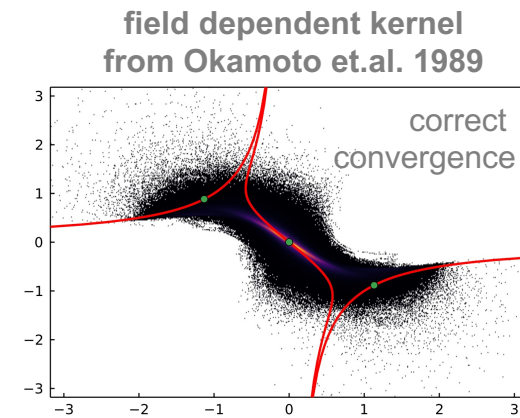
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$L^{\text{tot}}=0.023$

# Two convergence criteria

- Non-unique optima from the low-cost functional: allow to avoid boundary terms
- Correct convergence iff **in addition** Fokker-Planck EV in lower half plane

see D. Alvestad, R. Larsen, A.RJHEP 04 (2023) 057 and PhD thesis D. Alvestad

$$S = \frac{1}{2}\sigma x^2 + \frac{\lambda}{4}x^4 \quad \sigma = 4i, \lambda = 2 \quad \longrightarrow \quad K = e^{i\theta}$$

single number, optimum  
found by scan of  $L_{\text{lowcost}}$

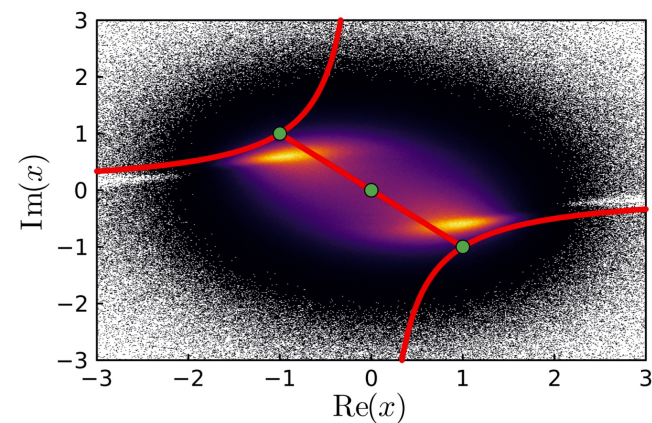
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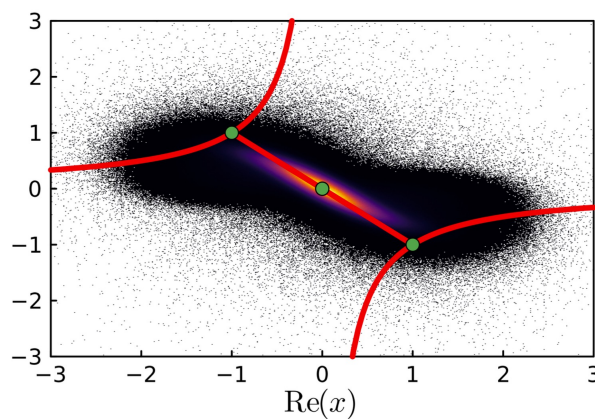
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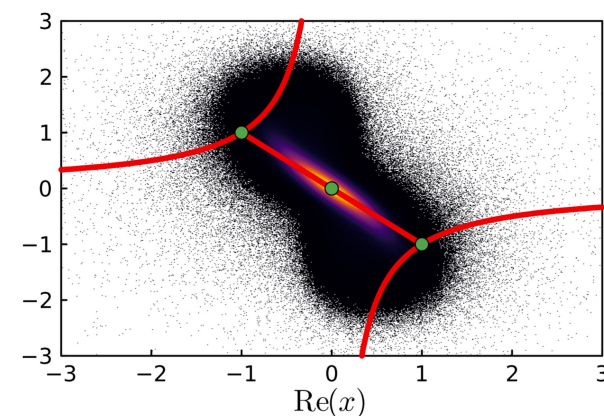
single number, optimum  
found by scan of  $L_{\text{lowcost}}$



$K=1$



$K=\exp[-i\pi/3]$   
correct convergence



$K=\exp[-i2\pi/3]$   
incorrect convergence

# Two convergence criteria

- Non-unique optima from the low-cost functional: allow to avoid boundary terms
- Correct convergence iff **in addition** Fokker-Planck EV in lower half plane

see D. Alvestad, R. Larsen, A.RJHEP 04 (2023) 057 and PhD thesis D. Alvestad

$$S = \frac{1}{2}\sigma x^2 + \frac{\lambda}{4}x^4 \quad \sigma = 4i, \quad \lambda = 2$$



$$K = e^{i\theta}$$

single number, optimum  
found by scan of  $L_{\text{lowcost}}$

