

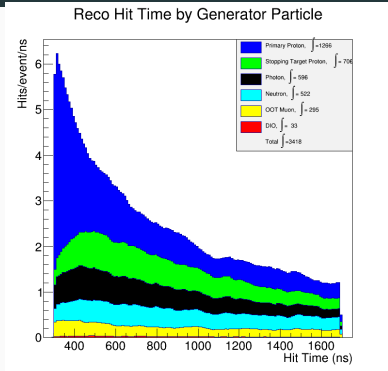
# Tracker intrinsic resolution, electronics, readout

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Richie Bonventre

March 28, 2023

# AMF tracking environment



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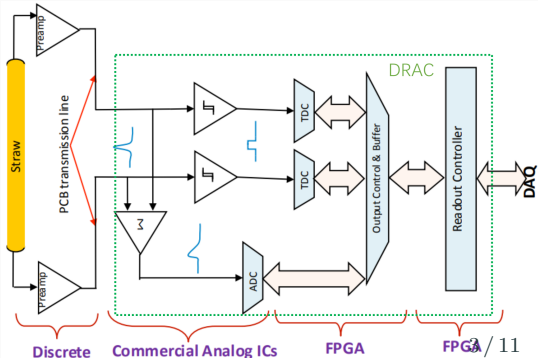
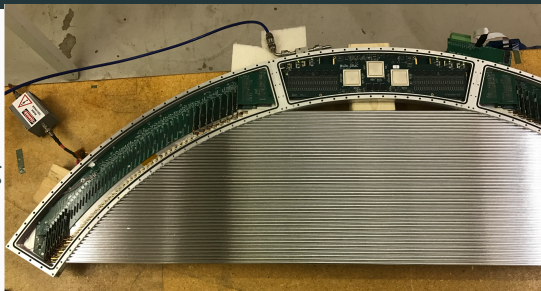
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- What makes it to the tracker? Expected rates?
- Radiation tolerance / charge accumulation problems minimized?
- Annular detector?
- Time division requirements?

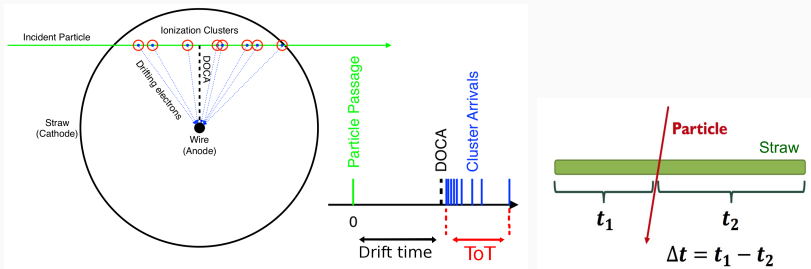
Time to go *track* to the drawing board!

# Mu2e setup

- Preamplifier at straw end, analog routed to central digitizer
- Comparator for applying threshold for time measurement
- 50 MHz digitizers
- 3x Microsemi PolarFire FPGAs w/ firmware TDC
- VTRx optical transceiver

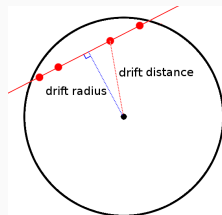
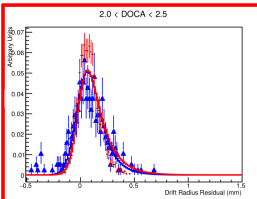
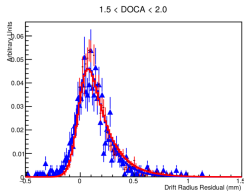
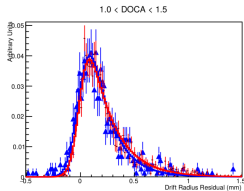
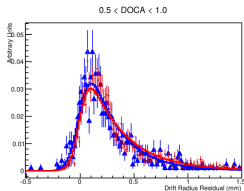
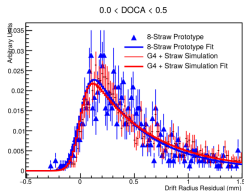


# Mu2e measurements from each hit straw



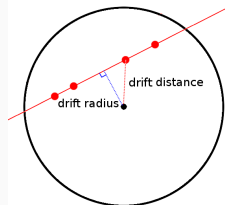
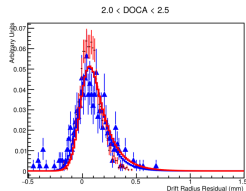
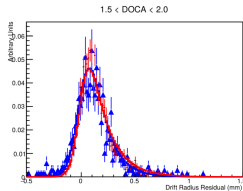
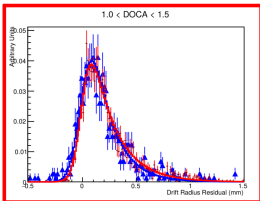
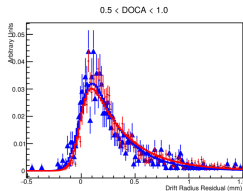
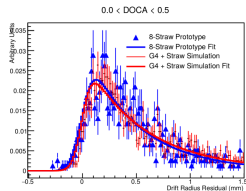
- Drift time  $\sim 2.5$  ns  $\rightarrow$  transverse radius  $\sim 150$   $\mu$ m
- Time division  $\sim 400$  ps  $\rightarrow$  longitudinal position  $\sim 4$  cm
- Time-over-threshold to 4 ns  $\rightarrow t_0 \sim 7$  ns
- 50 MHz digitized waveform  $\rightarrow$  energy deposition  $\sim 10\%$

# Drift response in Mu2e



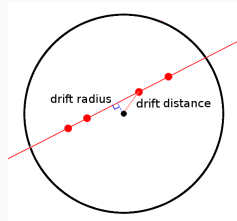
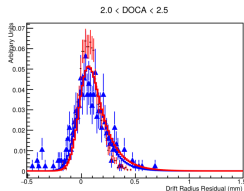
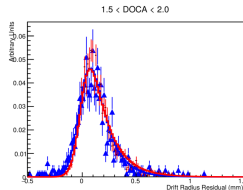
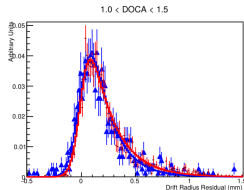
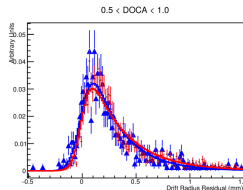
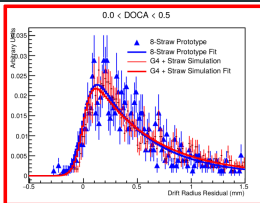
- gaussian smearing  $\times$  exponential encoding average spacing between ionizations
- Long tail when track near wire

# Drift response in Mu2e



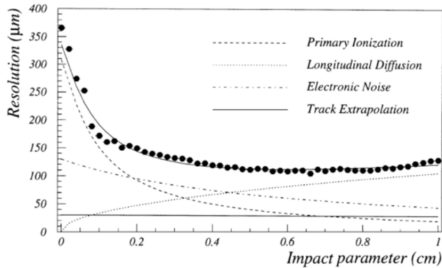
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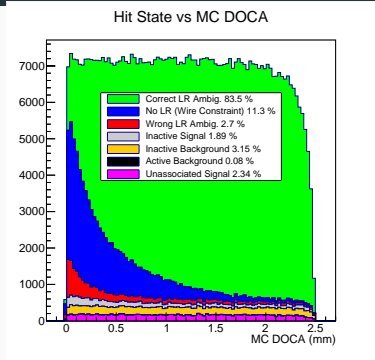


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# Drift resolution



KLOE drift chamber (NIM A 461 (2001) 25-28)

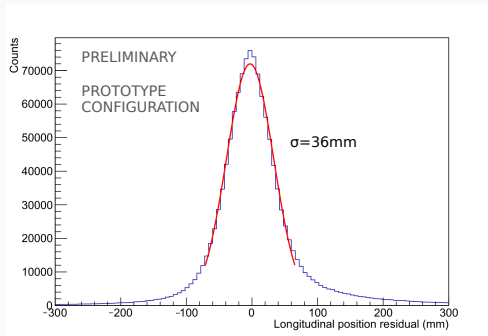


Mu2e KinKal fit ambiguity assignment

- Primary ionization statistics
  - Tails - difficulties for reconstruction
- Diffusion during drift + electronics noise, shaping, threshold vs gas gain
  - Time resolution
  - $\times$  drift velocity for distance resolution



# Longitudinal resolution



Mu2e VST plane resolution measurement

- Core from analog signal slope vs noise
- Tail from missing cluster on only one side
- Threshold optimization not necessarily the same as for drift (higher threshold  $\rightarrow$  slower effective propagation speed)

# Optimizations for Mu2e

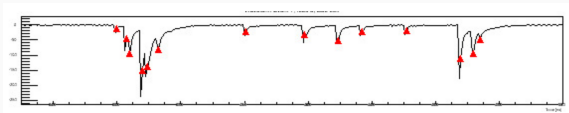
- Trigger on  $\sim 3$ rd cluster (15 clusters for 5mm path length)
  - $>95\%$  efficient for MIP, stable noise rates  $<10$  khz
- Preamp bandwidth  $\sim 150$  MHz
  - EFD protection diodes and termination resistance limit max bandwidth
- Handle up to 250 KHz/straw on average, 2 MHz maximum

- 1 GHz bandwidth, 2GSPS
- charge and time division
- 150 mW per channel
- Drift cells 7-9mm square, 90:10 He isobutane, 13 primary ionizations per cm
- 110  $\mu\text{m}$  resolution
- 600 $\mu\text{s}$  deadtime
- 15 Hz trigger ( $<1 \mu\text{s}$  trigger latency)

# Possible changes

- Lower gas pressure, lighter gas
  - worse ionization statistics, worse diffusion, higher gain
- Increase HV, thinner wire: increase gain, lower threshold
  - Trigger on single cluster?
  - Electrostatic stability, space charge effects?
- Slower gas
  - Better drift resolution, further separate clusters, worse pileup
- Higher bandwidth
  - Better rise time, longitudinal resolution, more noise
- Better shaping, digitization for TOT
  - accurately measure end of pulse
  - improvement on  $t_0$  helps with pileup
- Cathode readout - additional measurement, 4x coincidence
- Cluster counting

# Cluster counting?



G. Chiarello et al 2017 JINST 12 C07021, algorithm implemented on FPGA

- A lot more information for reconstruction
- With He or lower gas pressure, best way to recover resolution?
  - Repeated measurements for drift, better  $t_0$  than TOT
  - Longitudinal tail from missing cluster
  - Better PID (gain fluctuations vs cluster count)
- Mu2e - clusters  $< 3$  ns apart
- Faster digitization  $\rightarrow$  power consumption
- switched capacitor digitizers (DRS4) cheaper and low power, but  $> \mu\text{s}$  downtime
  - Could we have a low enough rate fast trigger?