# Status of MINERvA output to CAFs

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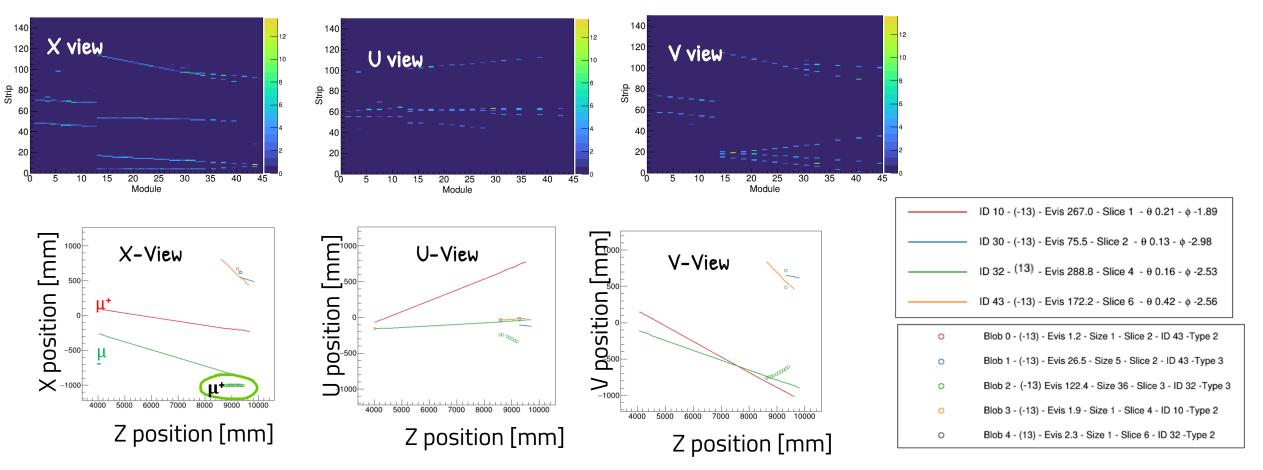






# Output from MINERvA (again)





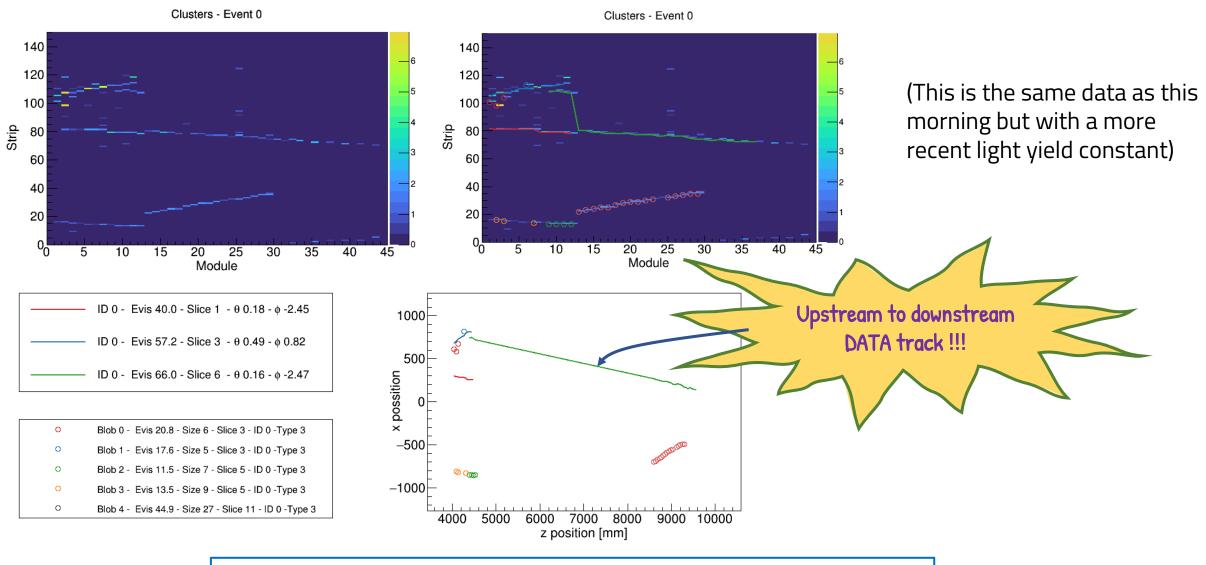
Reconstruction of tracks and blobs (shower like particle)

True particle linked to object: particle that contributed the most (energy wise)



# Output from MINERvA (again but DATA)





Reconstruction of tracks and blobs (shower like particle)



### What we can add into the CAFs



#### We don't want to keep a list of clusters but the core parameters of the objects

1) Keep track of tracks.

Already a SRTrack object in CAFS:

- Start (3D)
- End (3D)
- End Direction (3D)
- Visible Energy
- Link to truth particle

```
class SRTrack
 public:
   SRVector3D start;
                          ///< Track 3D start point
   SRVector3D end;
                          ///< Track 3D end point
   SRVector3D dir;
                          ///< Unit vector representing estimate of track direction *taken from start point*
   SRVector3D enddir;
                          ///< Unit vector representing estimate of track direction *taken from endpoint*
   float Evis = -999.; ///< Visible energy in voxels corresponding to this track
   // Track characteristics
   float len_gcm2 = -999.; //< Track length in g/cm2</pre>
   float E = -999; ///< Track energy in MeV
   float len_cm = -999; ///< Track length in centimeter (actual physical distance)
   float qual = -999; ///< Track quality metric (in TMS, equivalent to "hits in track"/"total hits in event"
   SRParticleTruth truth; ///< Best-match GEANT truth particle for this track
```

We can add angles if needed but can be computed with start & end positions

We might want to add **dE/dX** at the start point and end point of the track to have some basic PID (Proton/Muons). At the Track level reco, no dE/dX is computed but could be added with the clusters somewhere.

Could be computed in the CAFs Maker with the cluster list: would need to update SRTrack.



### What about the blobs?



#### Keep track of BLOBS?

Right now what do we keep in the DSTs

```
Int_t
               n_blobs_id;
               blob id idx[19];
                                 //[n_blobs_id]
Int t
               blob id_subdet[19]; //[n_blobs_id]
Int t
               blob id history[19]; //[n blobs id]
Int t
               blob id size[19]; //[n blobs id]
Int t
Int t
               blob_id_patrec[19]; //[n_blobs_id]
Double t
               blob id_e[19]; //[n_blobs id]
               blob id time[19]; //[n_blobs_id]
Double t
               blob id_time_slice[19]; //[n_blobs_id]
Int t
              blob id startpoint x[19]; //[n blobs id]
Double t
Double_t
               blob id_startpoint_y[19]; //[n_blobs_id]
Double t
               blob_id_startpoint_z[19]; //[n_blobs_id]
               blob_id_clus_idx[19][1500];> //[n_blobs_id]
Int t
                  BLOB INFO IN THE DSTs
```

We could keep a « shower like » object with

- Start position
- Energy
- Direction

Even if we don't go further in the MNV reco

#### **ALL the BLOB INFORMATIONS**

```
unsigned int
                                    m_idBlobFlags;
double
                                    m time;
Gaudi::XYZPoint
                                    m_startPoint;
Gaudi::XYZPoint
                                    m position;
Gaudi::XYZVector
                                    m direction;
std::pair<double,double>
                                    m energyCentroidXZ;
std::pair<double,double>
                                    m energyCentroidUZ;
std::pair<double,double>
                                    m energyCentroidVZ;
double
                                    m energyCentroidZ;
bool
                                    m energy updated;
double
                                    m_score;
double.
                                    m_energyTotal;
double.
                                    m_energyX;
double
                                    m energyU;
double
                                    m energyV;
                                    m moduleLowX;
                                    m moduleHighX;
                                    m moduleLowU;
                                    m_moduleHighU;
                                    m moduleLowV;
                                    m moduleHighV;
SmartRefVector<Minerva::IDCluster> m_clusters;
```



### What's already available?



#### SRShower object

- Start
- Direction
- Evis
- Link to true particle

m\_idBlobFlags; unsigned int m\_time; Gaudi::XYZPoint m startPoint; Gaudi::XYZPoint m position; Gaudi::XYZVector m direction; std::pair<double,double> m\_energyCentroidXZ; std::pair<double,double> m energyCentroidUZ; std::pair<double,double> m\_energyCentroidVZ; m\_energyCentroidZ; m\_energy\_updated; m\_score; m energyTotal; m\_energyX; m energyU; m energyV; m moduleLowX; m moduleHighX; m moduleLowU; m\_moduleHighU; m moduleLowV; m moduleHighV; SmartRefVector<Minerva::IDCluster> m clusters;

Basic Blob direction not computed at that level of reconstruction but a basic computation could be done at the CafsMaker level with endegy centroid + StartPoint.

We might want to add a dE/dX computation at start point + Computation of some direction using centroids + Size of the blob & Type of blob.

Direction seem to be always empty and dEdX is computed in Anatuple level but could be added before or add another step somewhere?



# Typical Output format and integration plans



### **In StandardRecord** based on the other implementations:

#### A **SRMINERVA.h** class with:

- Vector of <MINERVATrack>
- Size\_t Number of tracks
- Vector of <MINERVABlob>
- Size\_t Number of Blobs
- Use the TrajID to link to the truth particle

#### In ND\_CAFMaker:

#### A MINERVARecoBranchFiller

- -> Reads dst files
- -> Fills the SMINERVA class

#### **MINERVATrack:**

Updated SRTracks/SRMinervaTrack with:

- startdEdx (double/float)
- enddEdx (double/float)
- Time of track (double/float)

#### MINERVABlob:

Like SRShower with:

- number of clusters (int)
- MINERVA type of blob (int) (pattern used to reco)
- dEdX of Blob (double/float)
- Time of Blob (double/float)

