



Telescopes Drive Themselves: Optimizing Cosmic Survey Scheduling with Reinforcement Learning

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Clockwork Science Design

Use modern Machine Learning techniques to optimize what we investigate and how we do it

- Let the telescope decide what is interesting
 - Investigate that in non-human scheduled downtime
 - Respond to unexpected events without intervention
- Find novel questions to ask



Dark Energy Survey, via Yuanyuan Zhang

The first step – Learning to schedule

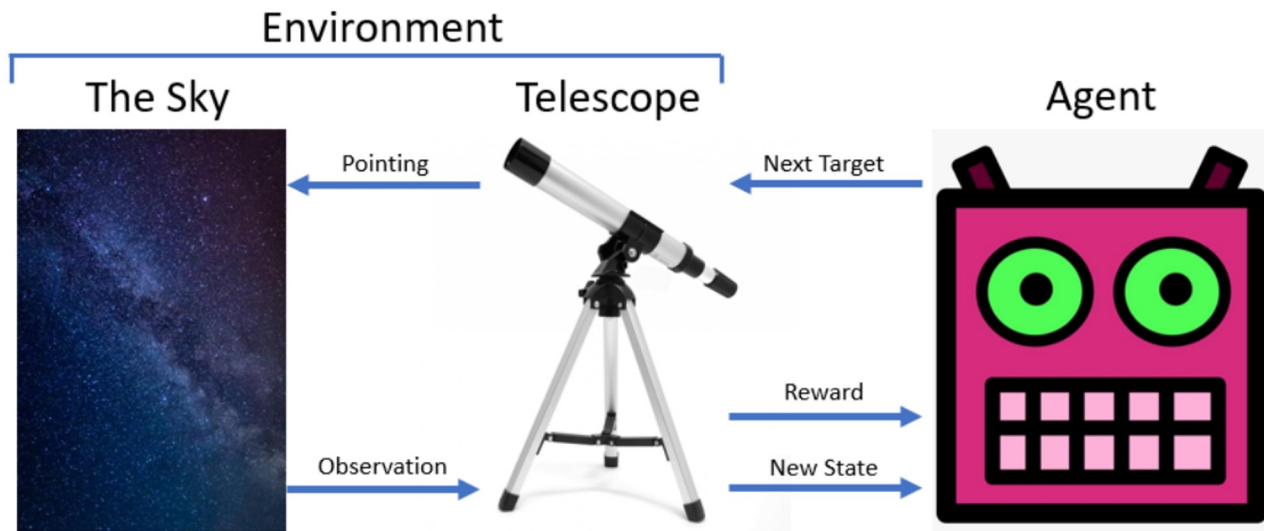
- Start with a program that optimizes a sequential schedule based on a single parameter maximization
 - Give the model a set of parameters, receive the best possible next step in the schedule
- Working with Stone Edge Observatory in California for a proof-of-concept volume survey



Stone Edge Observatory

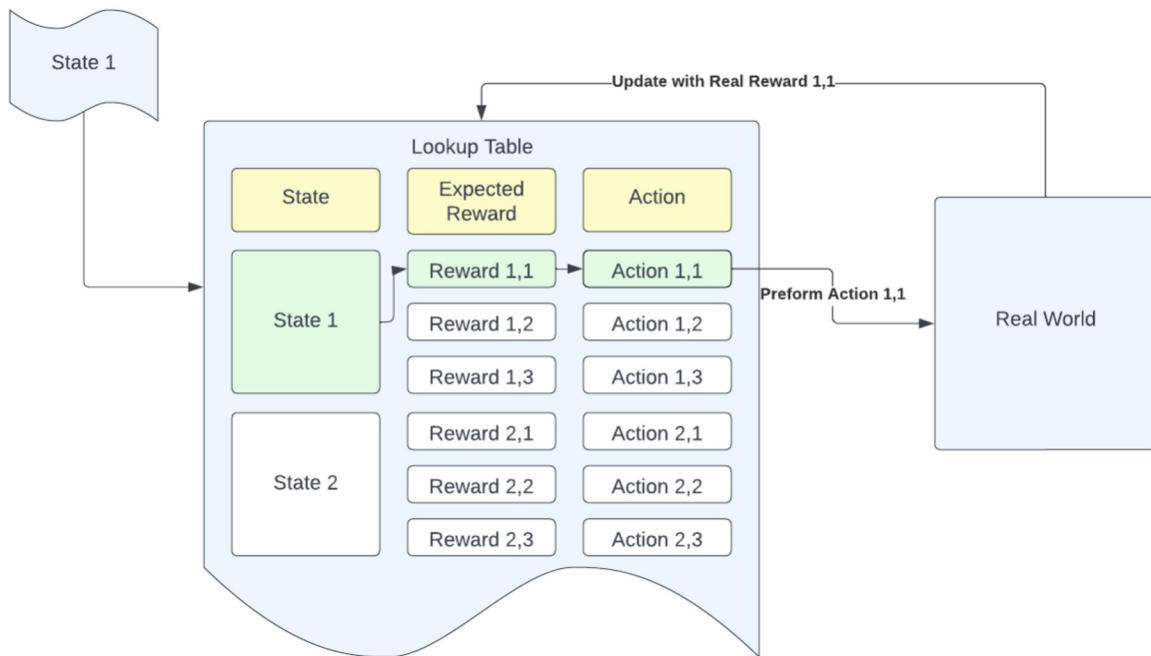
Learning to Learn – Reinforcement Learning

- Attempts to replicate how a human learns
- Conceptualize as a model trying to learn how to play a game
- The agent interacts with an environment, via an ‘action’, and gains ‘reward’ through the interaction

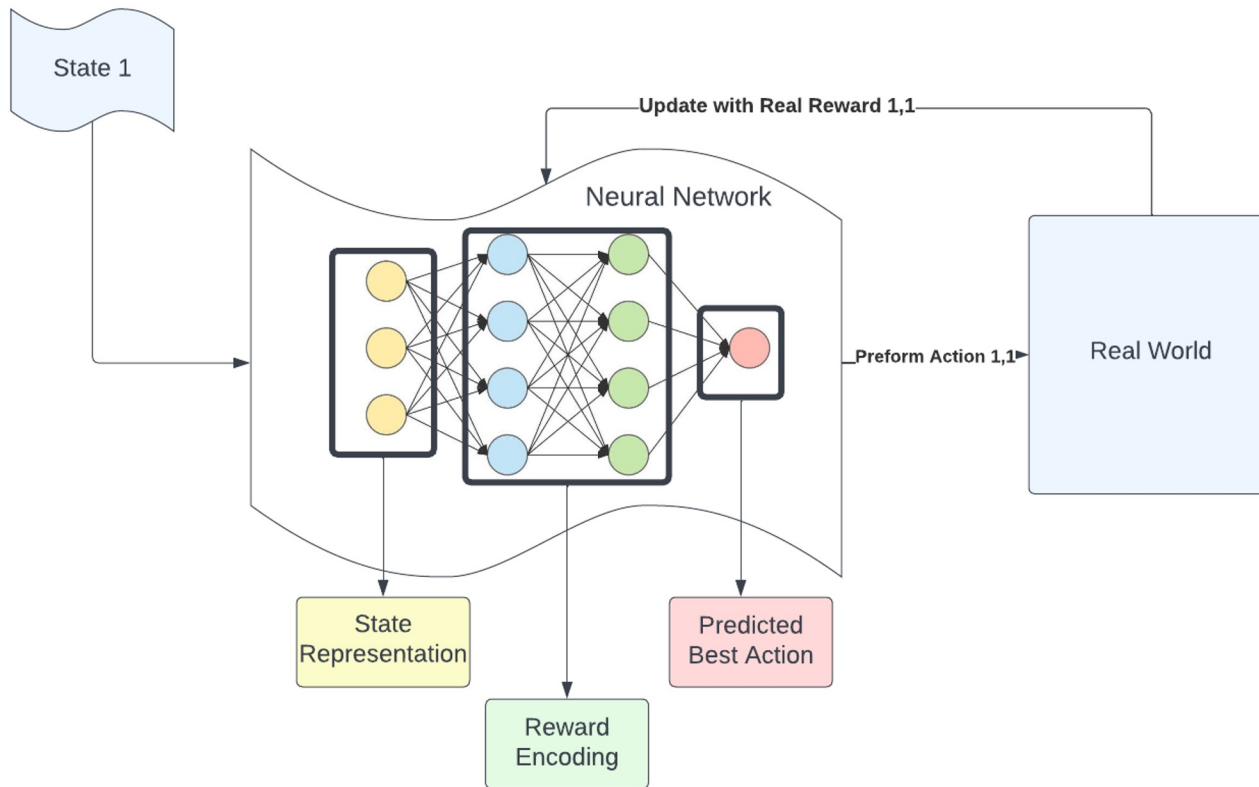


Using Value-Based Methods

- Imagine a look-up table of values that correspond to every state-action pairing, with the probability of the optimal reward
- Gets complicated very quickly for large problems – intractable for continuous problems



Enhance Value Methods with Offline Deep Learning



Data Preprocessing

ID	az	alt	sun_ ra	sun_ decl	moon_ airmass	moon_ angle	sky_ mag
ID_1	10.01	31.03	64.77	21.41	5.89	112.2	18.91
ID_2	10.01	31.03	64.77	21.41	5.89	112.2	18.91
....

Observation space

Right Ascension	Declination	T-Effective	New State
79.0	324.0	38	ID_29
24.0	221.0	29	ID_46
....

Action space

Reward

Next state

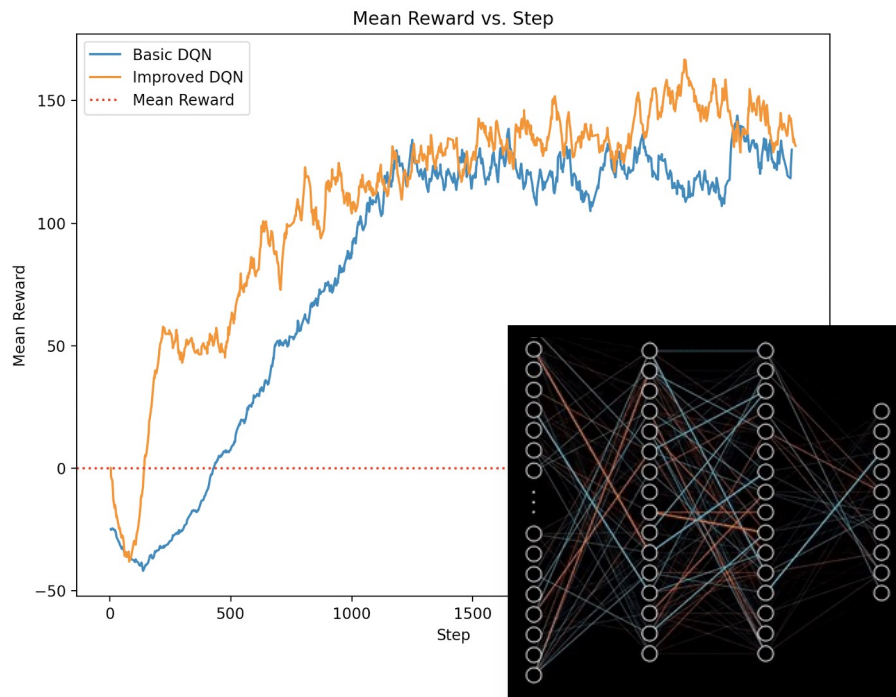
Normalization of the dataset involves adjusting the value of the data to a standardized range. This operation will ensure that the data is in a format easier for the RL algorithm to work with.

- Z-score normalization of the reward values intra-state
- Z-score normalization of the observation space columns

$$z = \frac{(x - \mu)}{\sigma}$$

Data point → x Mean → μ
Standard deviation → σ

Training



Improvements:

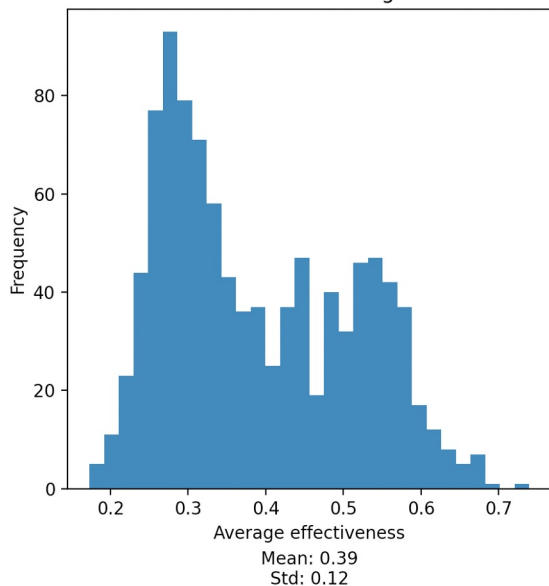
- Normalization of the observation space
- N-steps Bellman Unrolling (N=3)
- Dueling DQN
- Noisy Linear Layers

Effectiveness & Generalization - Comparison with a Random Agent

Our Agent

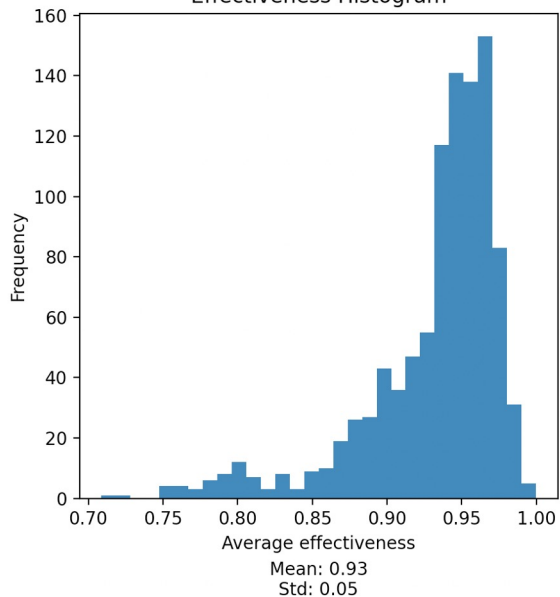
Random Agent

Effectiveness Histogram



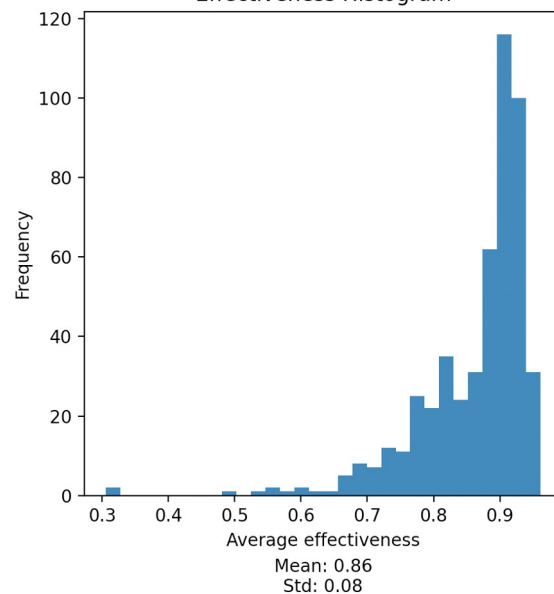
Full environment

Effectiveness Histogram

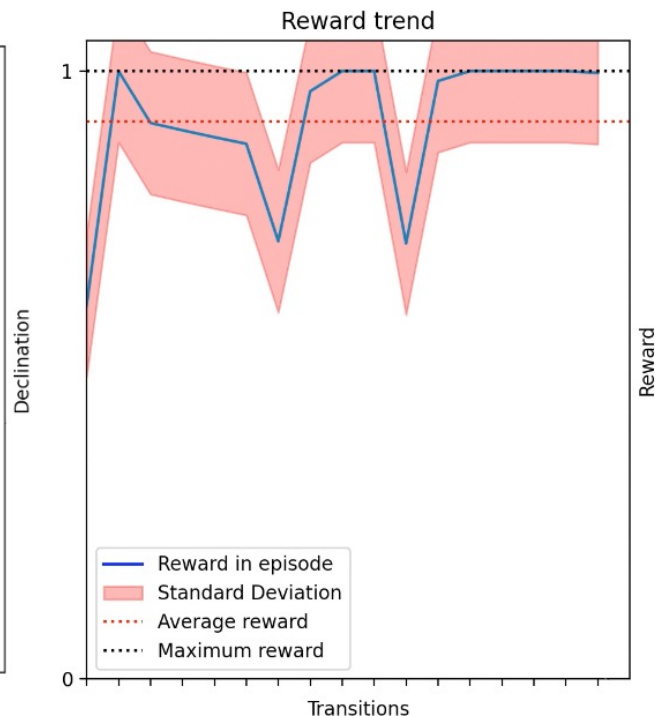
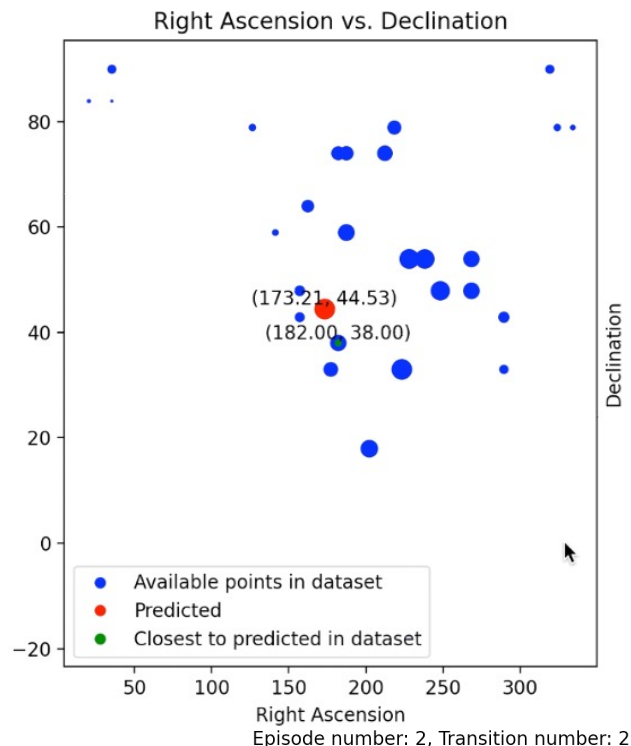
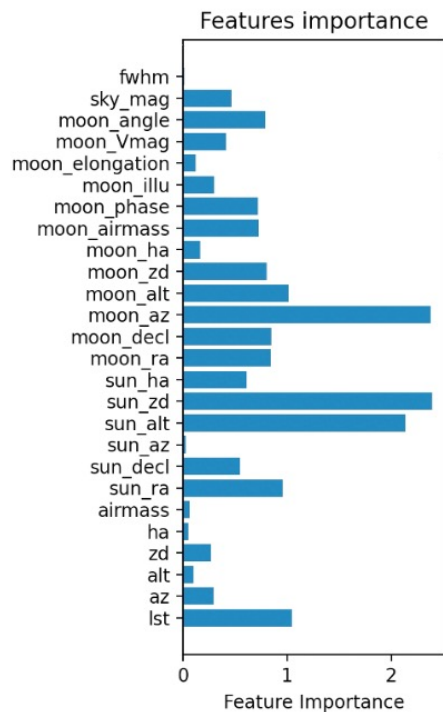


Test set

Effectiveness Histogram



Live execution - Current best Agent



Conclusions

- Trained an agent able to optimize telescope observations
- Future deployment at the Stone Edge Observatory

“What if an autonomous self-driving telescope could find the solutions we’ve been missing?”



The Victor M. Blanco 4-meter Telescope at Cerro Tololo Inter-American Observatory