Monte Carlo Methods and Lattice QCD

Xiao-Yong Jin in collaboration with James C Osborn and Sam Foreman

May 18, 2023 Argonne Mini-Workshop on Monte Carlo Methods

Outline

- Gauge field, fermion, path integral and probability distribution
- Monte Carlo gauge configuration generation
 - HMC Hybrid Monte Carlo (Duane et al, 1987, and reviewed by Neal, 1993) Hamiltonian Monte Carlo (new name by Neal, 2011)
 - Current ML research directions
 - Field transformation, change of variable, parametrized [arXiv:2201.01862]
- Monte Carlo in propagator measurement
- Outlook

• L2HMC, learn to HMC, generalized MD [<u>arXiv:2105.03418</u>, <u>arXiv:2112.01582</u>]



Gauge field on a spacetime lattice





← example of non-dynamic gauge



Path integral to Monte Carlo

$\langle \Omega | T\{\phi(x)\phi(y)\} | \Omega \rangle = \lim_{T \to \infty(1+T)} T$

• Wick rotation $t \rightarrow -i\tau$

- Imaginary time
- Real action bounded from below
- Monte Carlo

$$\int \mathscr{D}\phi \,\phi(x)\phi(y) \exp\left[i\int_{-T}^{T} d^{4}z\,\mathscr{L}\right]$$

$$\int \mathscr{D}\phi \,\exp\left[i\int_{-T}^{T} d^{4}z\,\mathscr{L}\right]$$



Lattice gauge theory





Dirac operator, determinant, inverse

$$\begin{split} \langle O(U,q,\bar{q}) \rangle &= \frac{1}{Z} \int [dU] \prod_{f} [dq_{f}] [d\bar{q}_{f}] O(U,q,\bar{q}) e^{-S_{g}[U] - \sum_{f} \bar{q}_{f} M[U] q_{f}} \\ &= \frac{1}{Z} \int [dU] \prod_{f} [dq_{f}] [d\bar{q}_{f}] O(U,\frac{\partial}{\partial \eta},\frac{\partial}{\partial \bar{\eta}}) e^{-S_{g} - \sum_{f} \bar{q}_{f} M[U] q_{f} + \bar{q}_{f} \eta_{f} + \bar{\eta}_{f} q_{f}} \Big|_{\eta = 0, \bar{\eta} = 0} \\ &= \frac{1}{Z} \int [dU] \prod_{f} \det[M_{f}] O(U,\frac{\partial}{\partial \eta},\frac{\partial}{\partial \bar{\eta}}) e^{-S_{g} + \sum_{f} \bar{\eta}_{f} M_{f} \eta_{f}} \Big|_{\eta = 0, \bar{\eta} = 0} \\ &= \frac{1}{Z} \int [dU] \prod_{f} \det[M_{f}] O(U,M^{-1}) e^{-S_{g}} \\ &= \frac{1}{Z} \int [dU] \prod_{f} [d\varphi_{f}] O(U,M^{-1}) e^{-S_{g} - \sum_{f} \varphi_{f}^{\dagger} M_{f}^{-1} \varphi_{f}} \end{split}$$

M local sparse cheap

M⁻¹ nonlocal expensive



Dirac operator

$$\begin{split} S_{\rm g} &= \beta \sum_{x,\mu,\nu} \left(1 - \frac{1}{3} \operatorname{Re} \operatorname{Tr} \Big[U_{\mu}(x) U_{\nu}(x+\hat{\mu}) U_{\mu}^{\dagger}(x+\hat{\nu}) U_{\nu}^{\dagger}(x) \Big] \right) \\ S_{\rm q} &= \sum_{f,x,y,\mu} \bar{q}_{f}(y) \Big(D_{\mu,yx} [U] \gamma_{\mu} + m_{f} \Big) q_{f}(x) \\ &\quad D_{\mu}^{\operatorname{Naive}} q(x) = \frac{1}{2} \Big(U_{\mu}(x) q(x+\hat{\mu}) - U_{\mu}^{\dagger}(x-\hat{\mu}) q(x-\hat{\mu}) \Big) \end{split}$$

- Naive Dirac operator leads to doubling of momentum poles per dimension
- Fermion actions:
 - Wilson, Staggered, Domain wall, Overlap, ... q(x)



Hamiltonian dynamics moves long distances Slow modes exist in multi-D potential Difficult to go over potential barrier

HMC





Incomplete list of HMC tricks in production

- Task: sampling space-time lattice gauge field with about tens of billions of d.o.f.
- Omelyan, higher order integrators, with force-gradient terms
- Splitting fermion determinant in multiple terms, from ratios of determinants of unequal fermion masses
 - Force from individual terms smaller
 - Large mass terms cheaper inversion
- Sexton & Weingarten, 1992, MD integration scheme
 - Larger time steps for expensive, small force terms
 - Smaller time steps for cheap, large force terms



Path integral, change of variables

- for us $\langle \mathcal{O} \rangle = \frac{1}{Z} \int \mathcal{D} U \mathcal{O} (U) e^{-S(U)} = \frac{1}{Z} \int \mathcal{D} V \mathcal{D} (U) e^{-S(U)} = \frac{1}{Z} \int \mathcal{D} V \mathcal{$
- HMC (FTHMC)
- dynamics (smaller difference between slow and fast modes)
- The Jacobian determinant and its derivative must remain simple

• Change of variables: use a continuously differentiable bijective map \mathcal{F}^{-1} from target field U to the mapped field $V = \mathcal{F}^{-1}(U)$, same group manifold

$$(\mathcal{F}(V))e^{-S(\mathcal{F}(V))+\ln|\mathcal{F}_*|}$$
 where $\mathcal{F}_* = \frac{\partial \mathcal{F}(V)}{\partial V}$

• Sample V with HMC according to the new action: Field Transformation $S_{\rm FT}(V) = S(\mathscr{F}(V)) - \ln|\mathscr{F}_*(V)|$

• Want the effective action to have lower potential barriers, or more uniform



Parametrized bijection map

• Gauge covariant, dynamics remain the same with local gauge transformations, $\Omega_x \in SU(3)$

$$U_{x,\mu} \to U'_{x,\mu} = e^{\prod_{x,\mu}} U_{x,\mu}$$
 where $\prod_{x,\mu} = \sum_{l} \epsilon_l \partial_{x,\mu} W_l$

 $U_{x,\mu} \longrightarrow$

- Generalize it for machine learning
 - Make the coefficients arbitrary functions of gauge invariant quantities

$$\epsilon_{x,\mu,l} = c \tan^{-1} \left[\mathcal{N}_l(X, Y, \ldots) \right]$$

- X, Y, \ldots a list of traced Wilson loops local to x, μ , and independent of $U_{x,\mu}$
- \mathcal{N} is a convolutional neural network, \mathcal{N}_l is one of the output channels
- $c \tan^{-1} [\cdot]$ ensures a positive definite Jacobian

$$U'_{x,\mu} = \Omega^{\dagger}_{x} U_{x,\mu} \Omega_{x+\hat{\mu}}$$

algebra (differentials in tangent directions)



Localized Coefficients, by Convolutional Neural Networks



- Pick a subset of gauge links to update at a time (red links)

• Compute Wilson loops independent of the to-be-updated links (green loops)

• Pass through a series of convolutional neural networks and obtain coefficients





What to optimize

$$\mathcal{L}(\beta, \tilde{U}) = \sum_{p \in \{2, 4, 6, 8, 10, \infty\}} \frac{c_p}{V^{1/p}} \left\| \frac{\partial S_{\mathrm{FT}}(\beta, \tilde{U})}{\partial \tilde{U}} - \frac{\partial S(\beta = 2.5, \tilde{U})}{\partial \tilde{U}} \right\|_p$$

- Other possibilities under investigation
 - directly minimize the force
 - log mean exp difference
 - error term after leapfrog integration

• Match the field transformed force (gradient of the effective action) against the force of the original action at a stronger coupling (away from the continuum limit)



[arXiv:2201.01862] Results from 2D U(1) lattice fields, correlation of topological charge

Scaling of the integrated autocorrelation length



 \mapsto HMC $V/\beta = 819.20$

$V = 64^2$, trained at $\beta = 5$ $V/\beta = 819.20$, trained at $V = 64^2$, $\beta = 5 \rightarrow 10^{-1}$ $V = 64^2$, trained at $\beta = 6 \vdash \Delta \dashv$ $V/\beta = 682.67$, trained at $V = 64^2$, $\beta = 6$ Ð 1/91/81/71/101/61/51/4 $1/\beta$

Fixed neural network architecture Trained weights at four different conditions









Current work, on 4D SU(3) gauge fields

- The number of terms grows, and cost grows combinatorially
- to the red link on one side.



• for updating the red link in a 3D lattice. From left to right, (a) the links in black used to compute Wilson loops as input to a neural network, (b) two 6link rectangle loops parallel to the red link, (c) four 6-link rectangle loops perpendicular to the red link on one side, (d) four plaquette perpendicular



1. Update **v**:

 $|\mathbf{v}_k'| = egin{bmatrix} \Gamma^{\pm}[\mathbf{v}_k; oldsymbol{\zeta}_{\mathbf{v}_k}] \end{bmatrix}$

L2HMC, generalized

Original L2HMC, Lev

• We generalized it to

2. Update half of **x** via $\overline{m}_k \odot \mathbf{x}_k$:

$$\mathbf{x}_k' = \mathbf{m}_k \odot \mathbf{x}_k + \mathbf{r}_k'$$

3. Update (other) half of **x** using $m^k \odot \mathbf{x}'_k$:

$$\mathbf{x}_k'' = \overline{m}^k \odot \overline{\mathbf{x}}_k' + \mathbf{r}_k$$

4. Half-step full **v** update:

$$\mathbf{v}_k'' = \mathbf{\Gamma}^{\pm}[\mathbf{v}_k'; \zeta_{\mathbf{v}_k'}]$$



• Maximize the effective change of to



$$\begin{array}{c} \mathbf{v} \text{ scaling} \\ \odot \exp\left(\frac{\varepsilon_{\mathbf{v}}^{k}}{2} s_{\mathbf{v}}^{k}(\zeta_{\mathbf{v}_{k}})\right) - \frac{\varepsilon_{\mathbf{v}}^{k}}{2} \left[\partial_{x} S(x_{k}) \odot \exp\left(\varepsilon_{\mathbf{v}}^{k} q_{\mathbf{v}}^{k}(\zeta_{\mathbf{v}_{k}})\right) + t_{\mathbf{v}}^{k}(\zeta_{\mathbf{v}_{k}})\right] \\ \mathbf{x} \text{ scaling} \\ \mathbf{x} \text{ scaling} \\ \mathbf{x} \text{ scaling} \\ \mathbf{v} \text{ scaling} \\ \mathbf{v}$$

(c) Detailed view of the update functions Γ^+ , Λ^+ for the k^{th} leapfrog step.

opology,
$$A(x^*, v^* | x, v)(Q^* - Q)^2$$





Results from 2D U(1) lattices



trajectory lengths, N_{LF} , at $\beta = 4, 5, 6, 7$ (left to right).

[arXiv:2105.03418, arXiv:2112.01582]

Figure 5: Comparison of the integrated autocorrelation time for trained models vs HMC with different



Dynamics per leapfrog layers











Monte Carlo in propagator measurement

- Typical quark propagator, the solution of $DS(x, y) = \delta$
- Construct propagators, such as "Pion" $\langle P^a(x)P^b(y)\rangle \propto -\delta^{ab}\langle \operatorname{tr}\{S(x,y)S(x,y)^{\dagger}\}\rangle$
- Average as many lattice points as possible, but inversion is costly
- Use random source, with statistical error $\sim 1/\sqrt{N}$
- Class of variance reduction techniques $\langle O \rangle$
 - $\langle O \hat{O} \rangle$ has smaller variance; $\langle \hat{O} \rangle$ is cheaper to evaluate
 - Applies with or without random source
 - Examples: compute \hat{O} using low modes of D, with approximate high modes

=
$$\langle O - \hat{O} \rangle + \langle \hat{O} \rangle$$
 such that





Outlook

- FTHMC with neural networks helps reduce autocorrelation in HMC
- L2HMC learns to inject energy in order to tunnel barriers
- Application in production requires balancing the cost and the benefit
- ML Code: <u>https://github.com/nftqcd</u>
- Difficulties in scaling up
 - Requires computing the Jacabian determinant and its derivatives wrt the lattice fields
 - Cost grows with spacetime dimension and the total field degrees of freedom
 - Available neural network frameworks are unprepared for 4D grid of Lie group elements; autograd wastes huge amount memory (size and bandwidth) in copying tensors; no optimized routines for periodic boundary conditions

