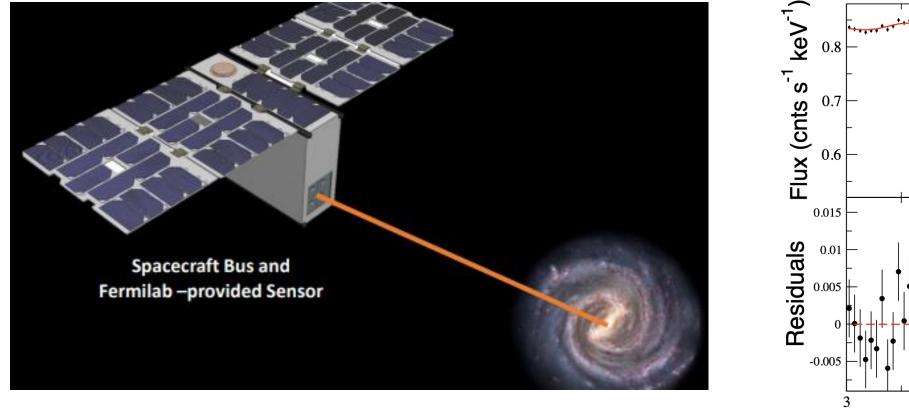
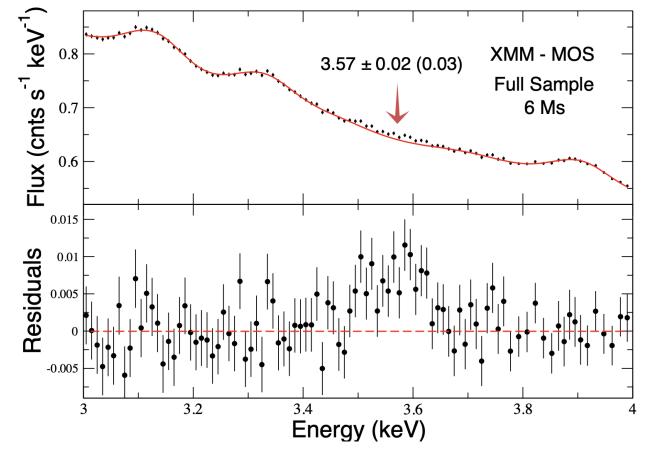
Sensor Testing for DarkNESS Trino Jaime (tjaim2@uic.edu), University of Illinois at Chicago - SULI

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DarkNESS

DarkNESS is a mission with the objective of making X-Ray observations of the Milky Way's galactic center. It will use CCDs to search for a 3.5 keV signal that may be a signature of dark matter decay.





Implementation and Results

The PID controller was applied using an Arduino UNO for processing and Arduino 4 Relay Shield to control the actuator, which has a 50W heater. C++ was used for programming the Arduino and the digital PID was implemented through this formula:

Heater Power =
$$P(T - T_s) + I \int_{t-5}^{t} (T - T_s) dt + D(T - T_s) \frac{d}{dt}$$

Fig. 1 DarkNESS satellite (left), keV signal (right)

Goal

Build a sensor test station using the following components:

- Vacuum Chamber \bullet
- Integrated Heater PCB
- Space LTA (Low \bullet Threshold Acquisition Electronic)
- Temperature Controller



Arduino and Relay



High Vacuum Pump

- Pressure Sensor
- Cryo Cooler
- Charge-Coupled Device (CCD)
- **Temperature Sensor**
- DC Power Supply ullet



Fig. 4 (left) shows the performance of the controller. After setting -80°C as setpoint the temperature stabilizes, oscillates then keeps steady. The right plot shows the monitoring of the pressure when vacuum pump is turned on.

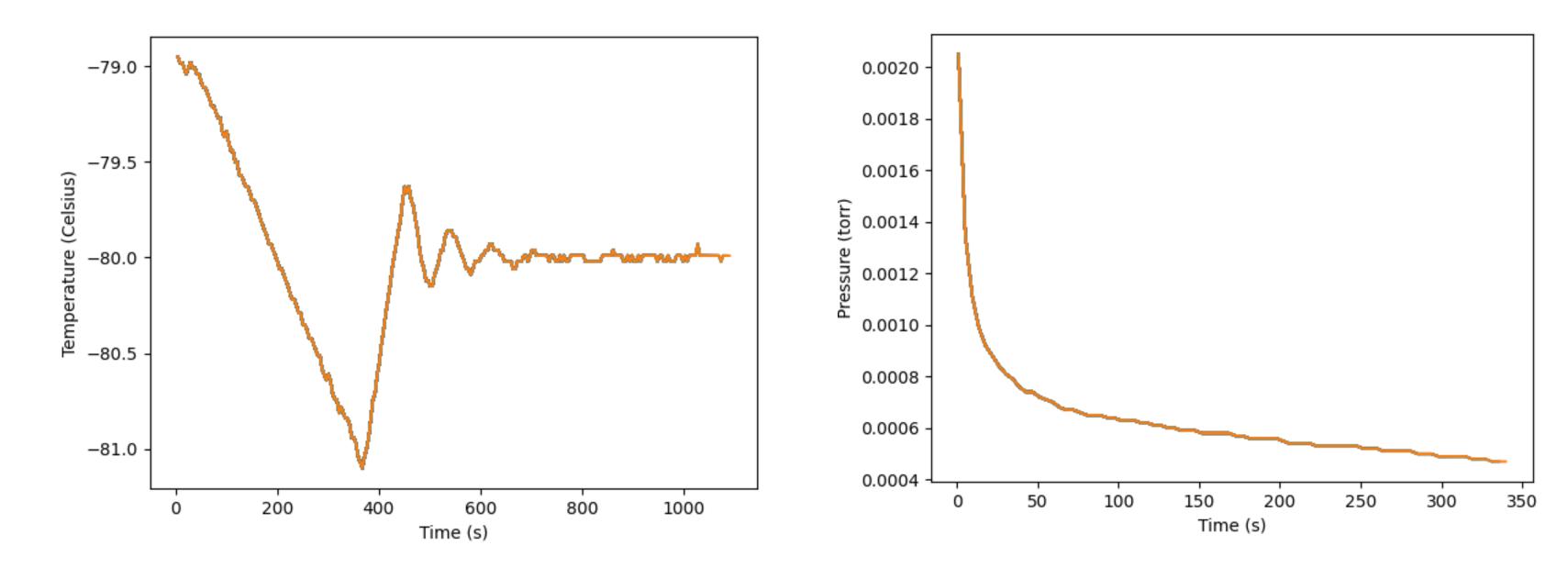


Fig. 4 Real-time Temperature (left), Real time Pressure (right)

The system maintains a steady temperature with the heater being fed 30 V DC. The size, cost and performance of the controller makes it an ideal solution for DarkNESS. It performed within the requirements and an image was taken using the station as shown (Fig. 5). Here cosmic rays are observed.

Temperature Controller Theory

- Pulse Width Modulation (PWM) is a way to control analog \bullet systems using a digital output. Using a digital device, a sine wave can be created switching a signal between off and on.
- A Proportional, Integral, Derivative (PID) is a closed-loop control scheme that uses the error between the current output and the desired setpoint to compute a desired output.

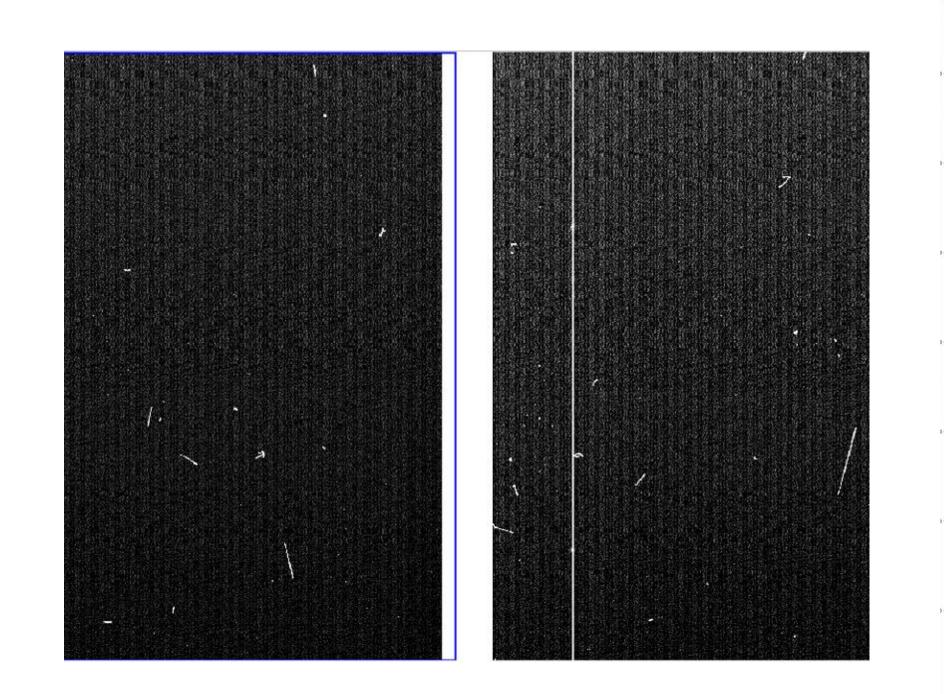


Fig. 5 Cosmic Rays inside vacuum cube

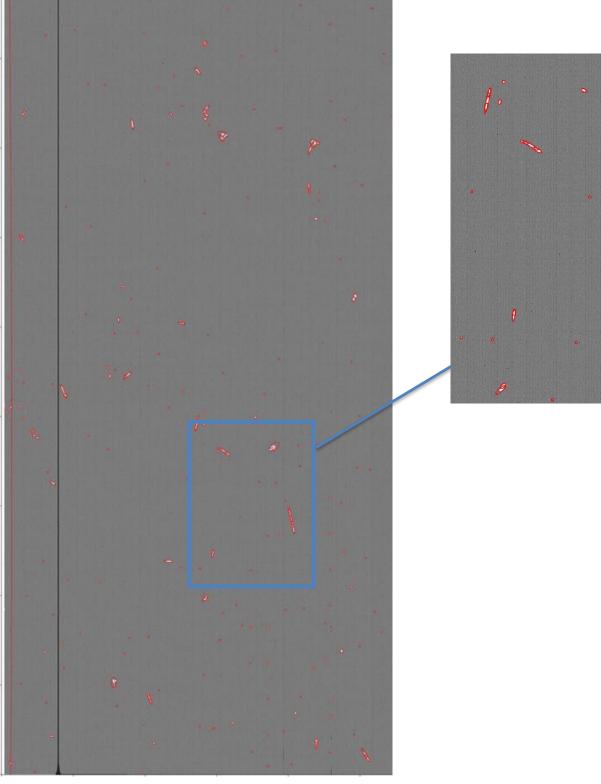
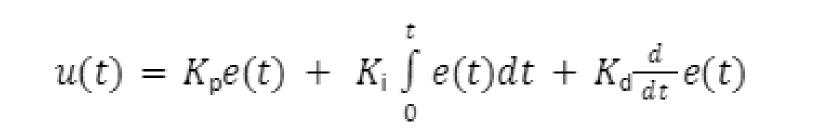


Fig. 6 Particles identified by jupyter code

Conclusions/What's Next?

• A PID temperature controller was successfully implemented



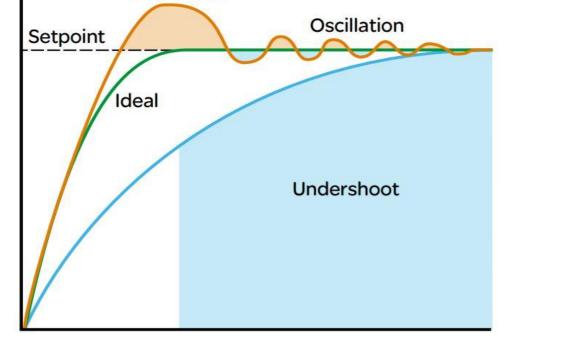


Fig. 3 Ideal control using PID (theory)

(https://www.eurotherm.com/auto-tuning-pid-control-in-a-

plc/)

- as well as a python script for real-time monitoring.
- An autotuning method needs to be applied optimize the PID \bullet parameters for any system.
- Temperature controller is yet to be tested when using the \bullet Space Multi-CCD module package.

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