

Event Reconstruction at the LHC I



The goal of event reconstruction...

s-Benz EQA 300 4MATIC | WLTP: Stromverbrauch kombiniert: 18,7–17,4 kWh/100 km | CO₂-Emissionen kombiniert: 0

Benz EQS 450 4MATIC SUV | WLTP: Stromverbrauch kombiniert: 24,3–19,9 kWh/100 km | CO₂-Emissionen kombiniert

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The goal of event reconstruction...



...put the pieces back together!

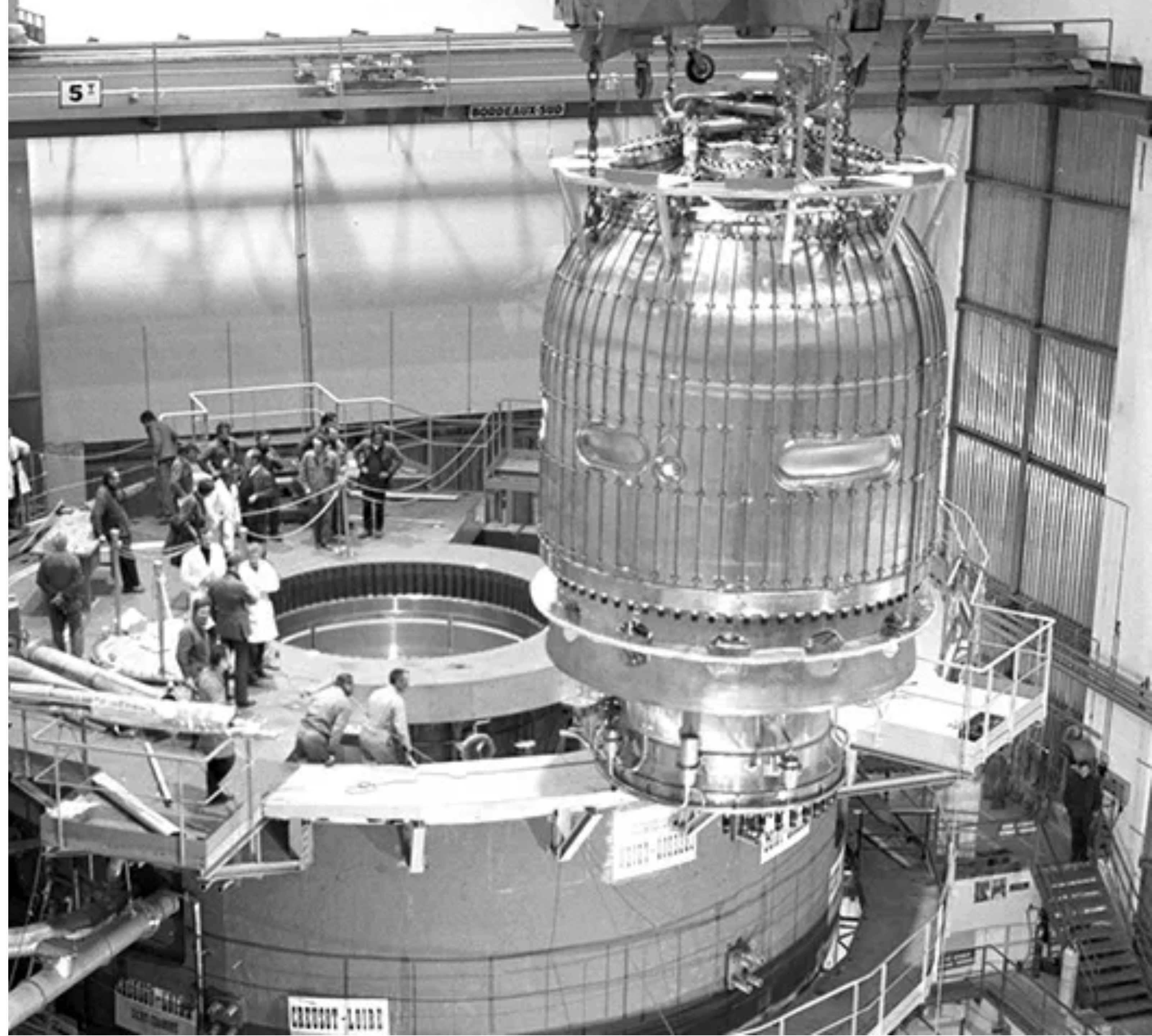
History of Event Reconstruction

Cloud Chamber
Invented 1911
Nobel 1927



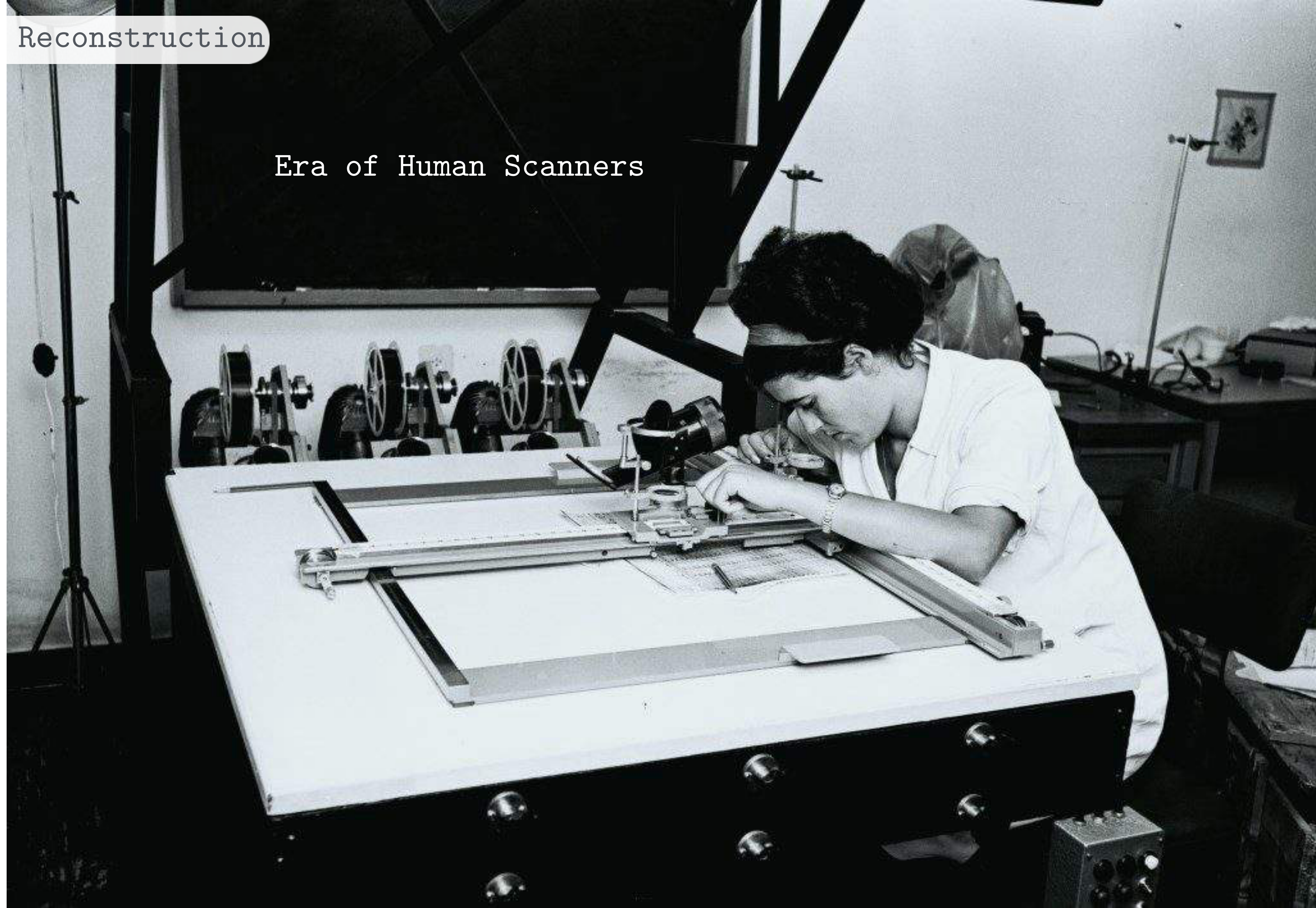
History of Event Reconstruction

Bubble Chamber
Invented 1952
Nobel 1960



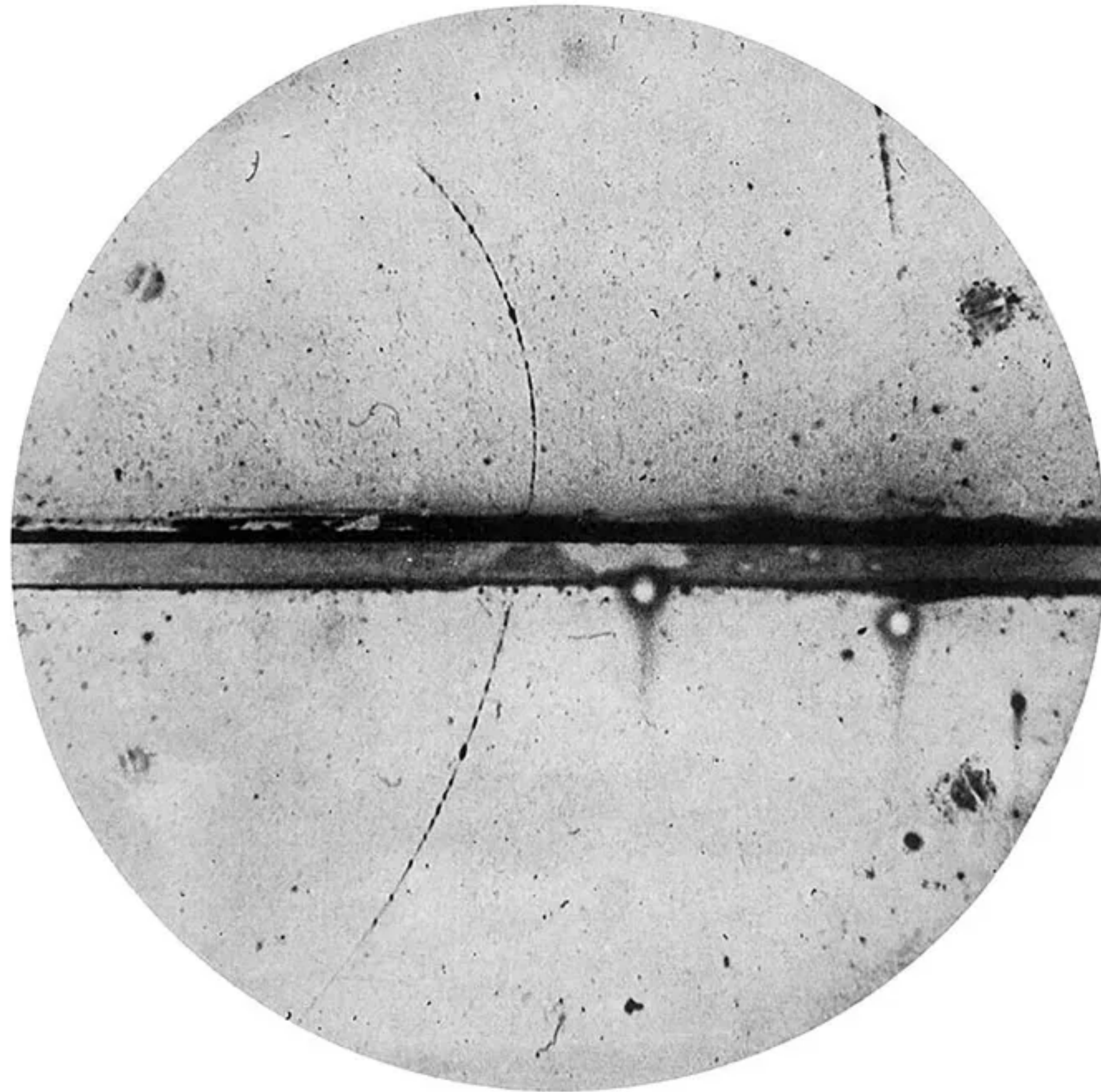
History of Event Reconstruction

Era of Human Scanners



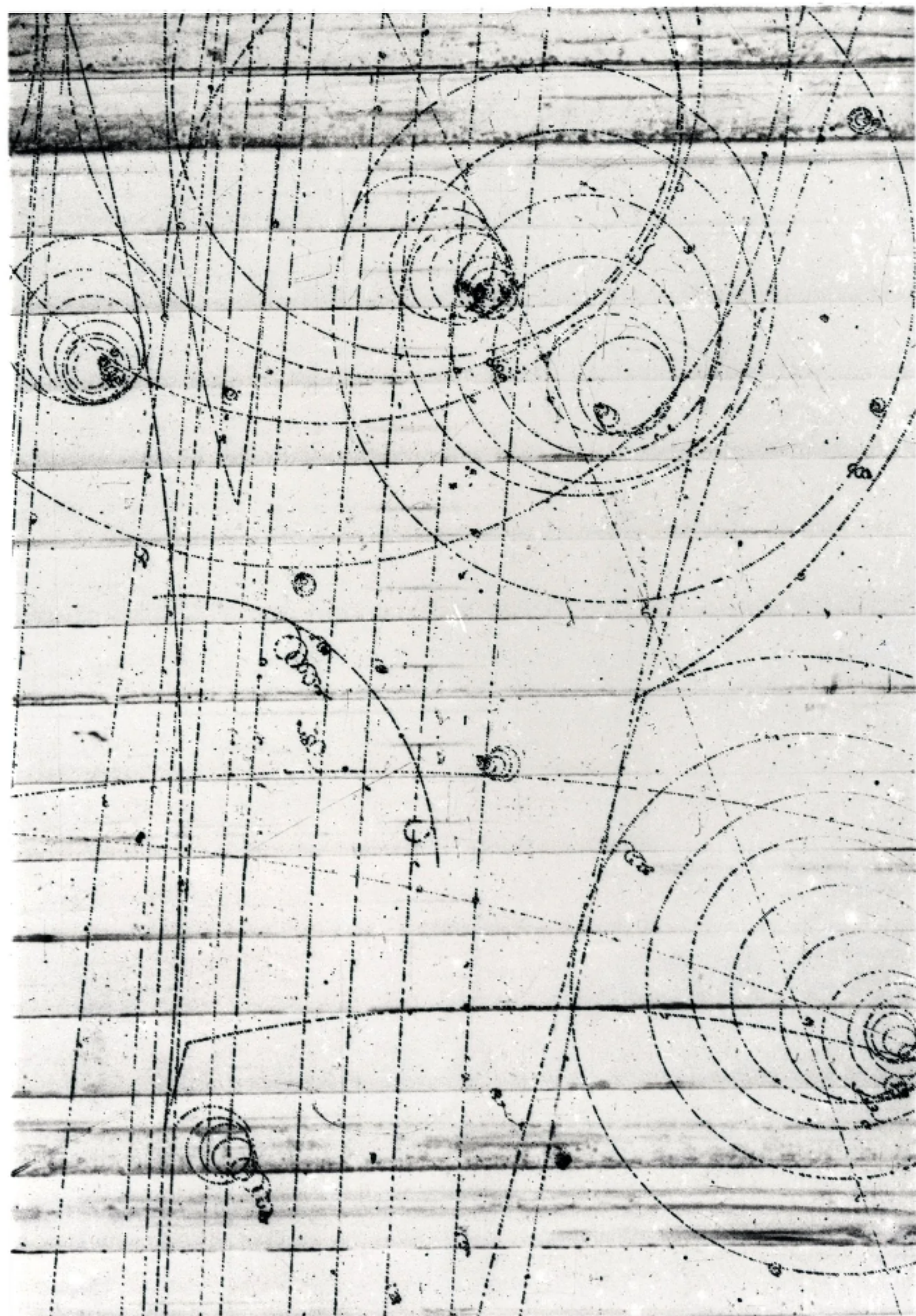
History of Event Reconstruction

Richard Cavanaugh, Fermilab/UIC, HCP Summer School 31 July 2024

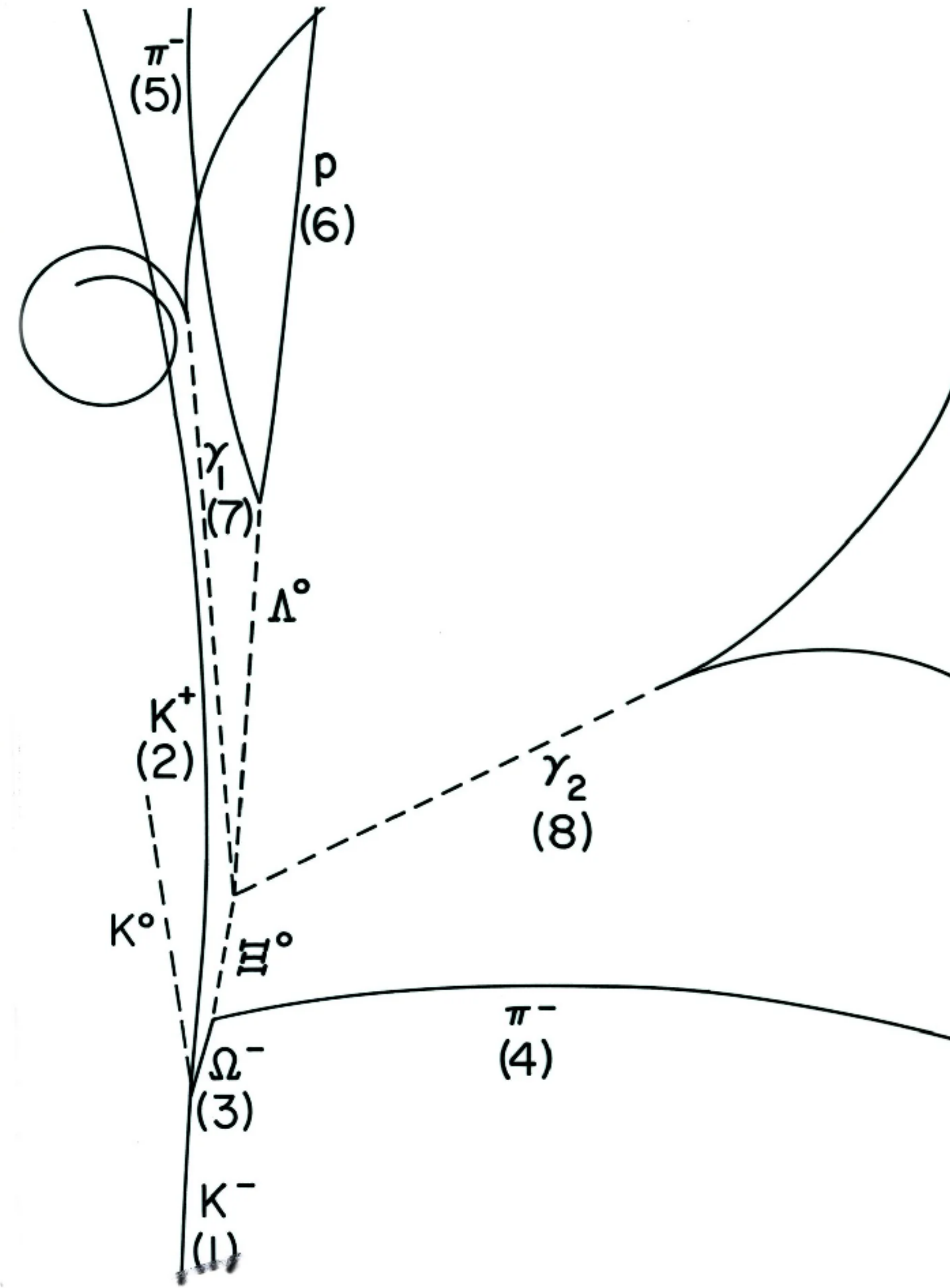


Discovery of the positron (1932 - Nobel 1936)

History of Event Reconstruction



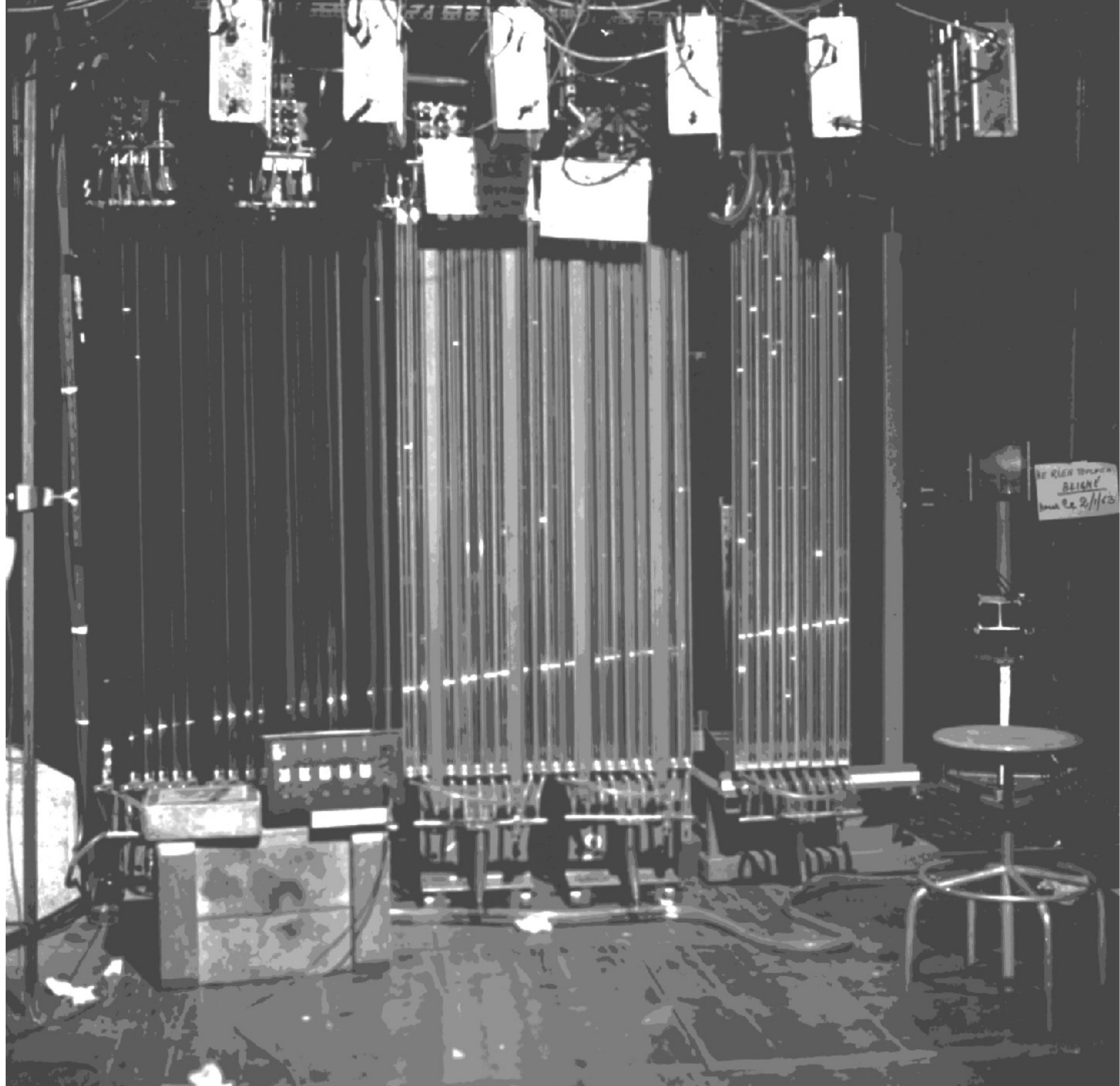
Discovery of the Omega-minus (1964)



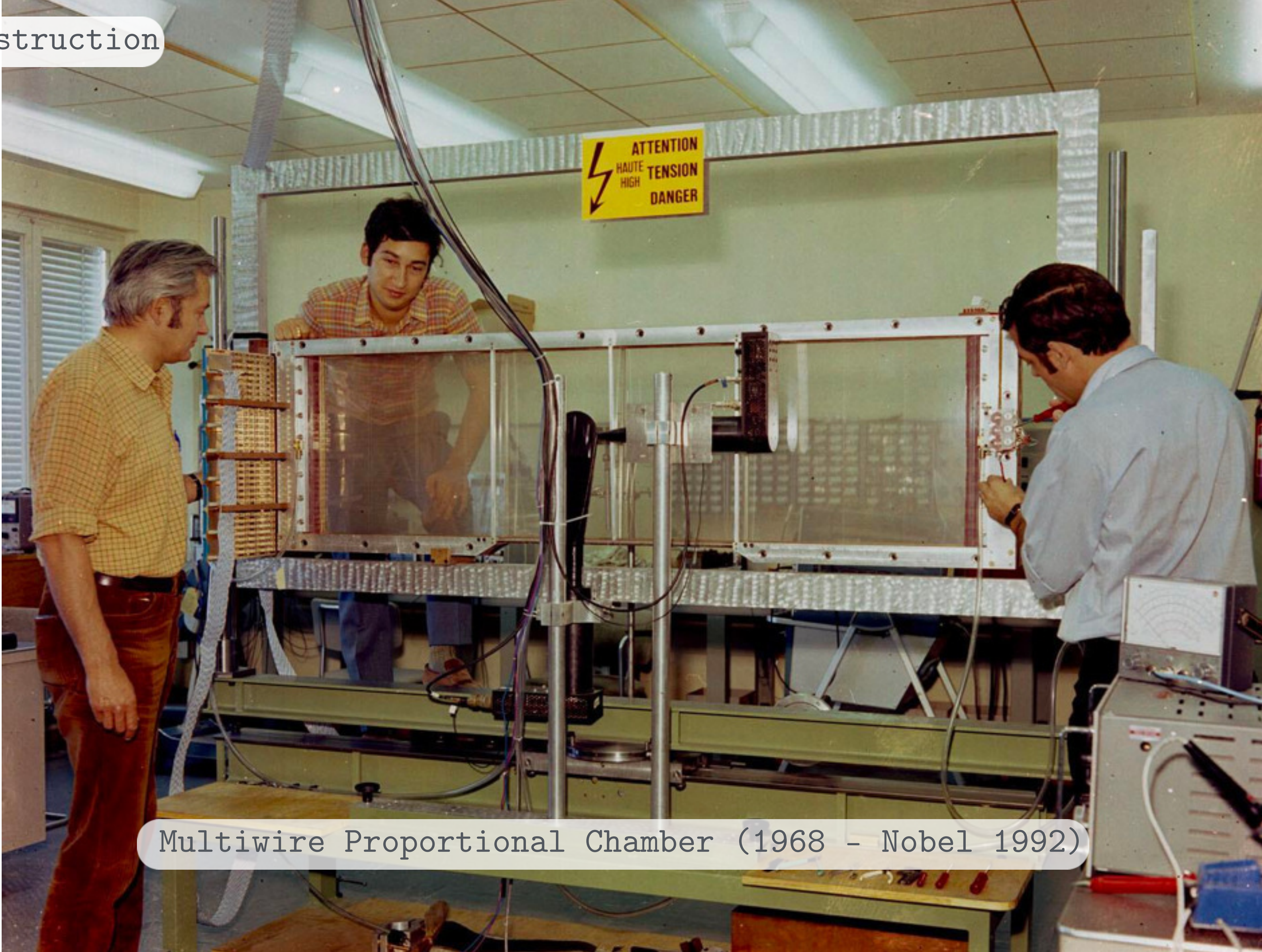
But, data collection and analysis rates just too low!

History of Event Reconstruction

Electronic Detectors: Spark Chamber (1963)



Electronic
Detectors:



Multiwire Proportional Chamber (1968 - Nobel 1992)

History of Event Reconstruction

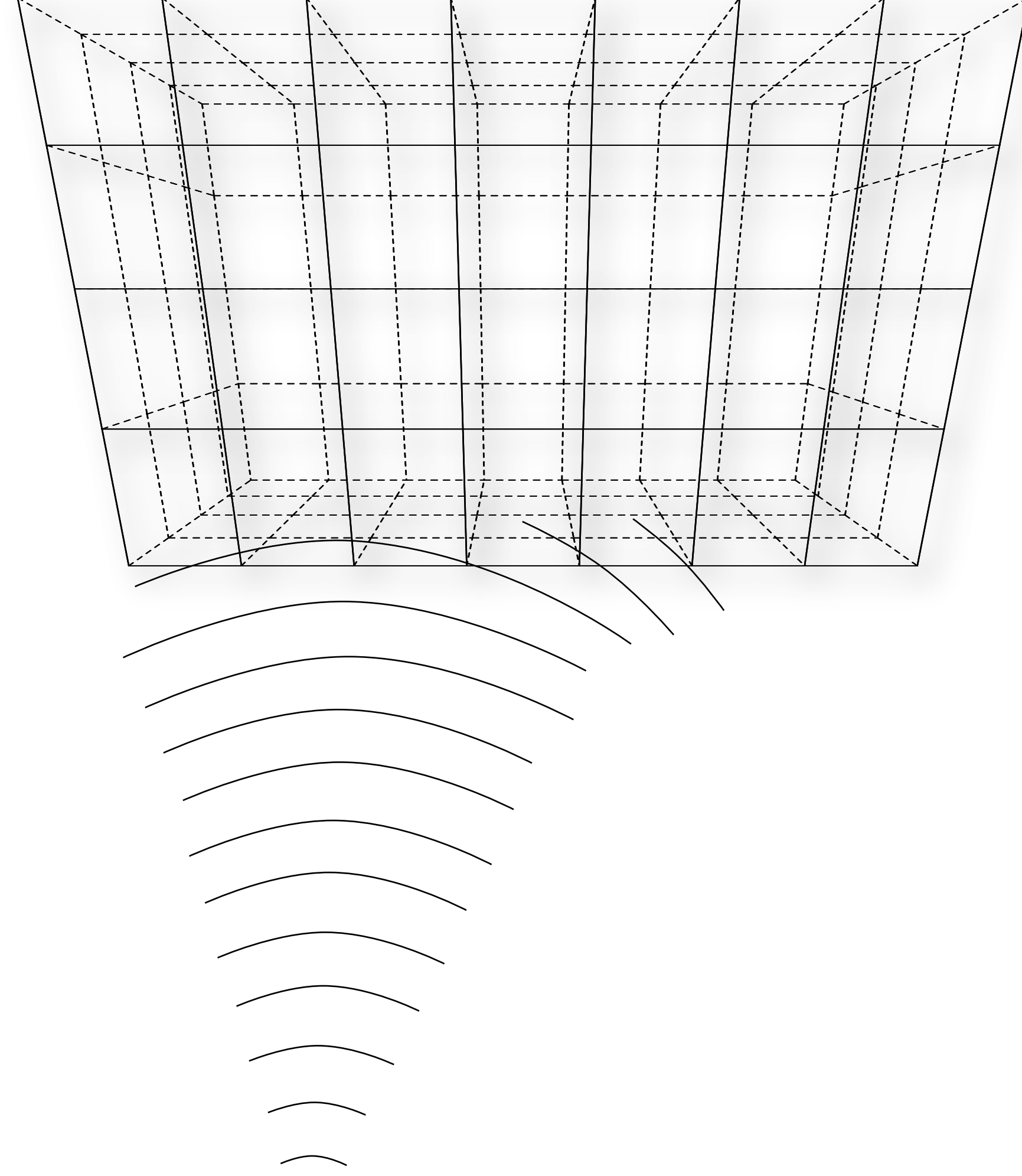


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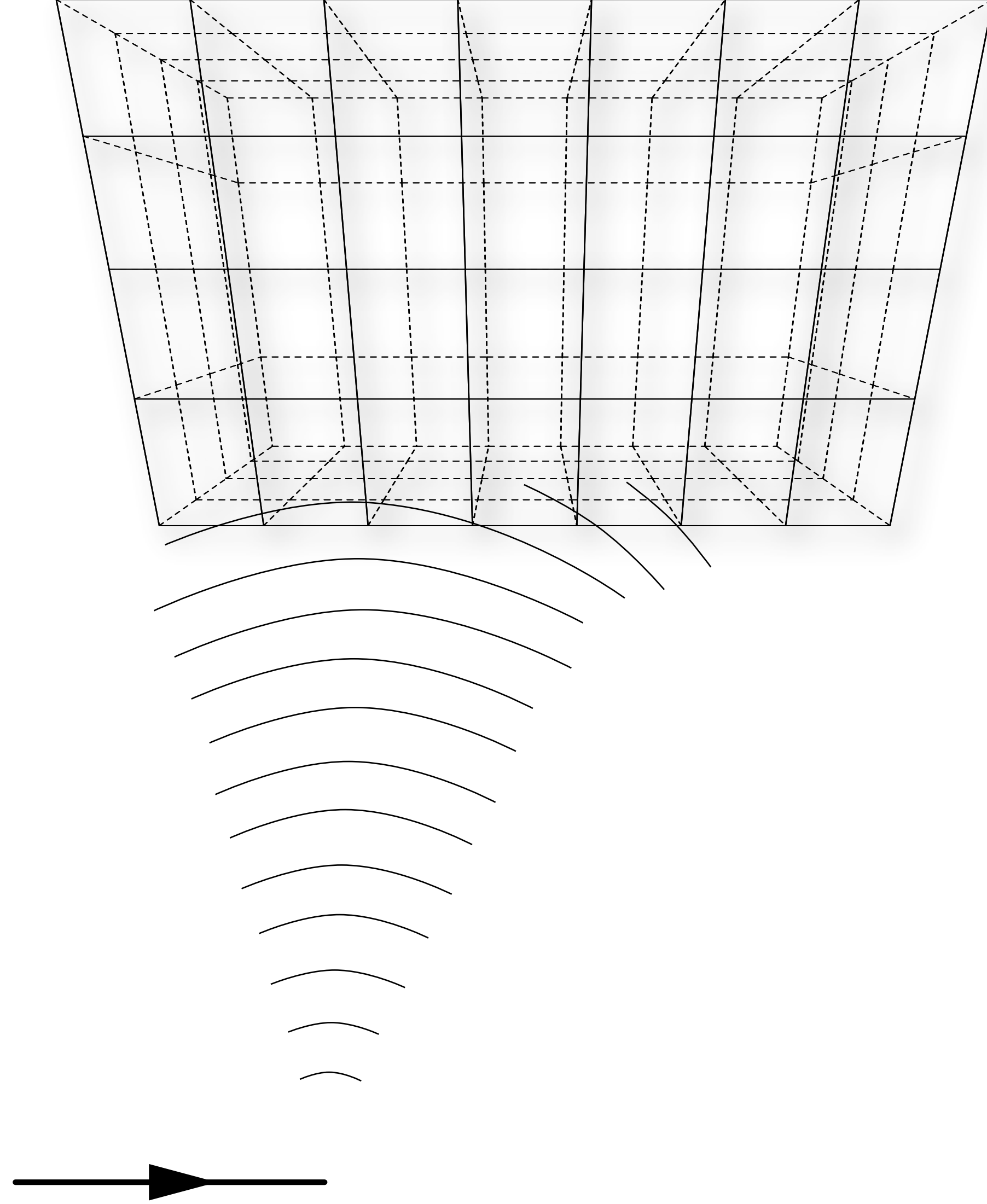
Era of computers

The Big Picture!



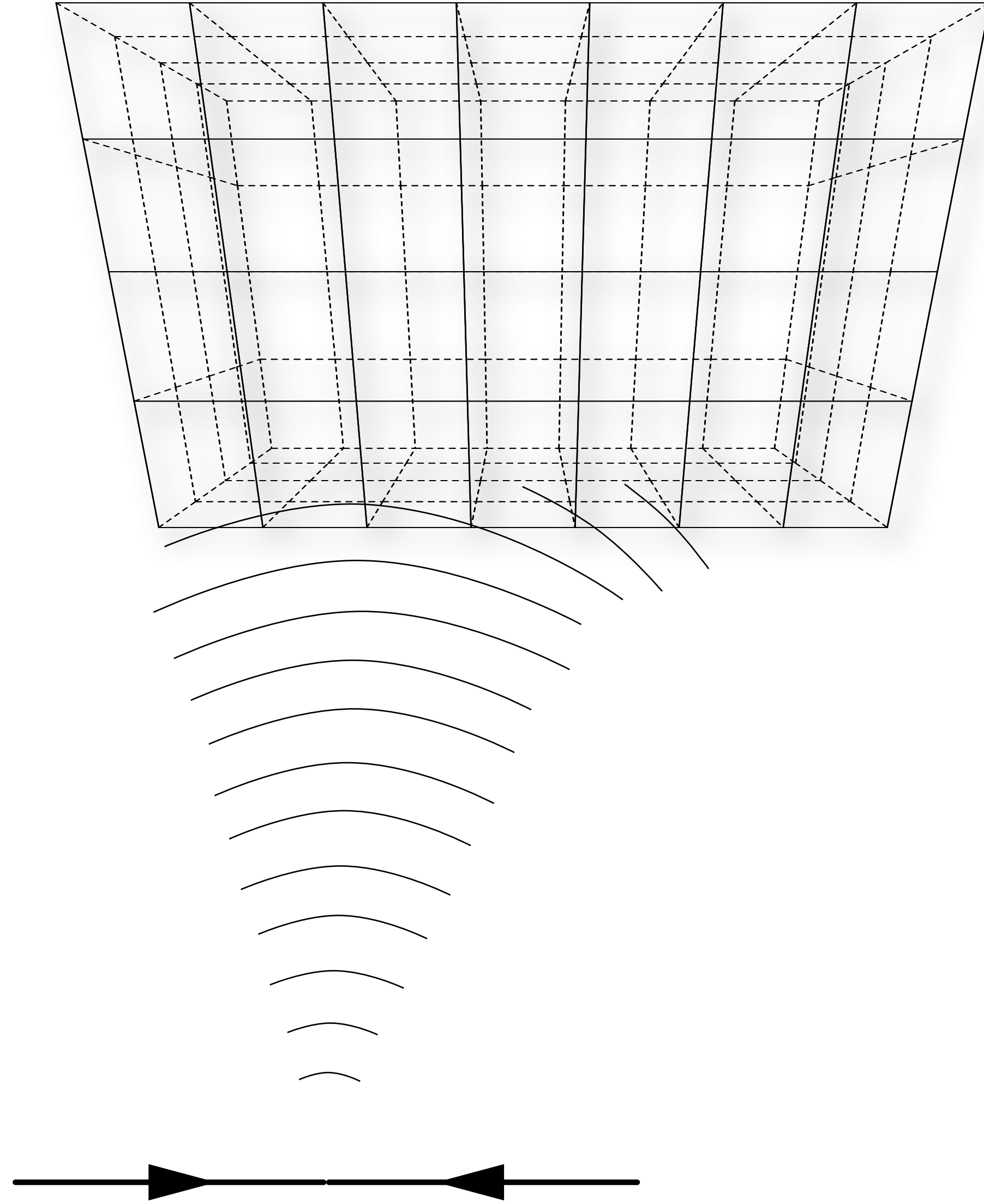
Particle Physics Detector

The Big Picture!



Particle Physics Detector

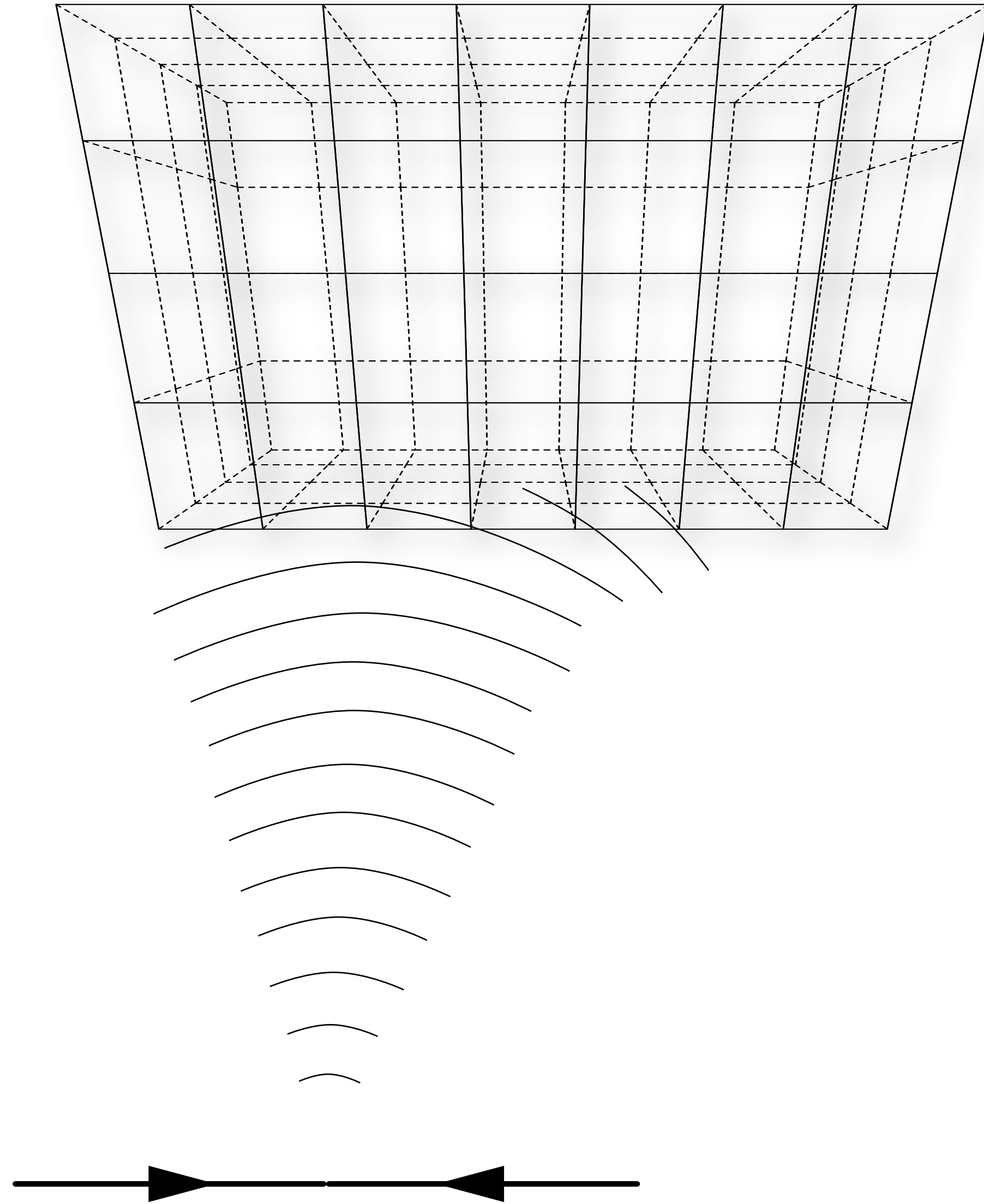
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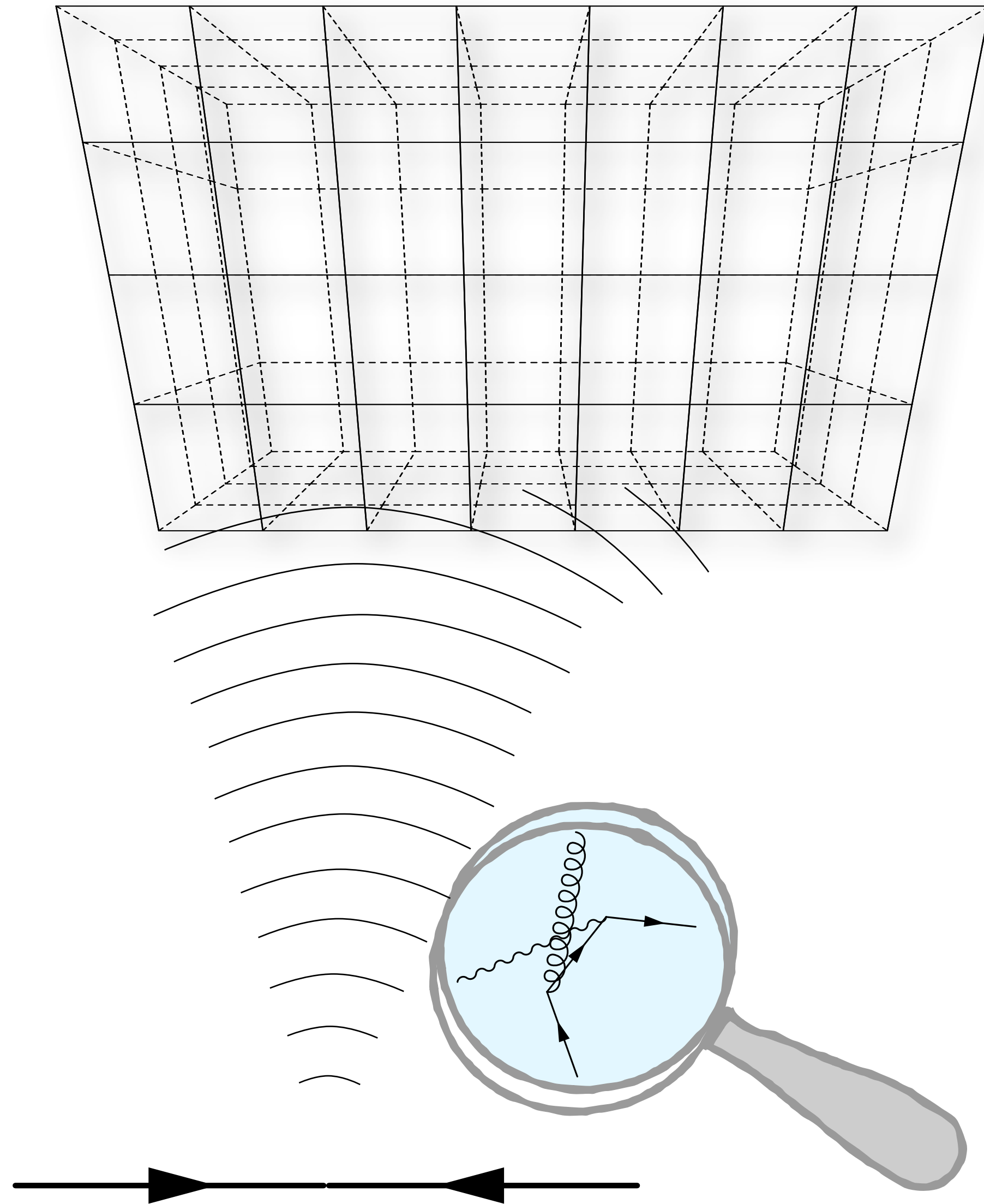
- Physics process \Rightarrow Partons



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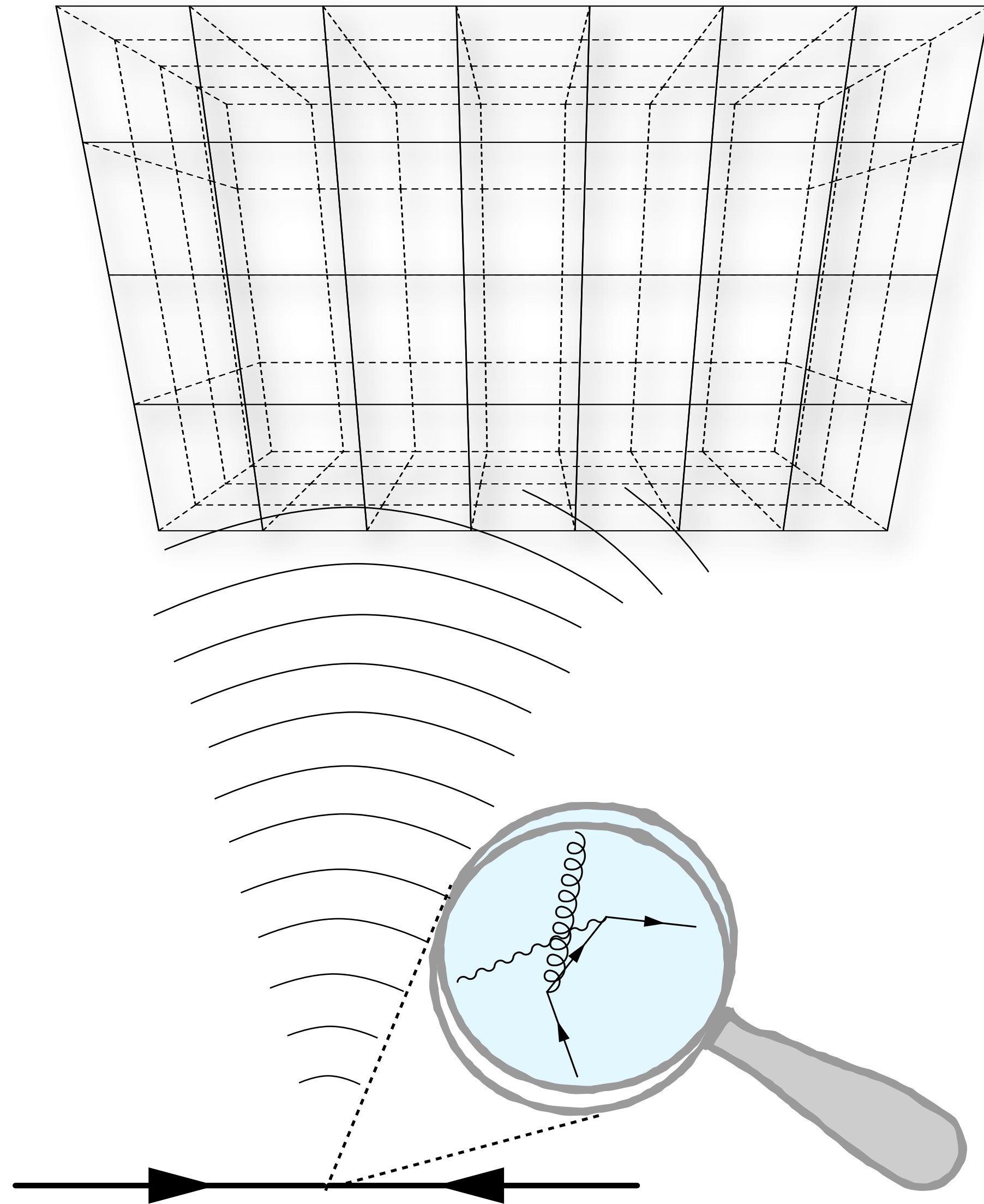
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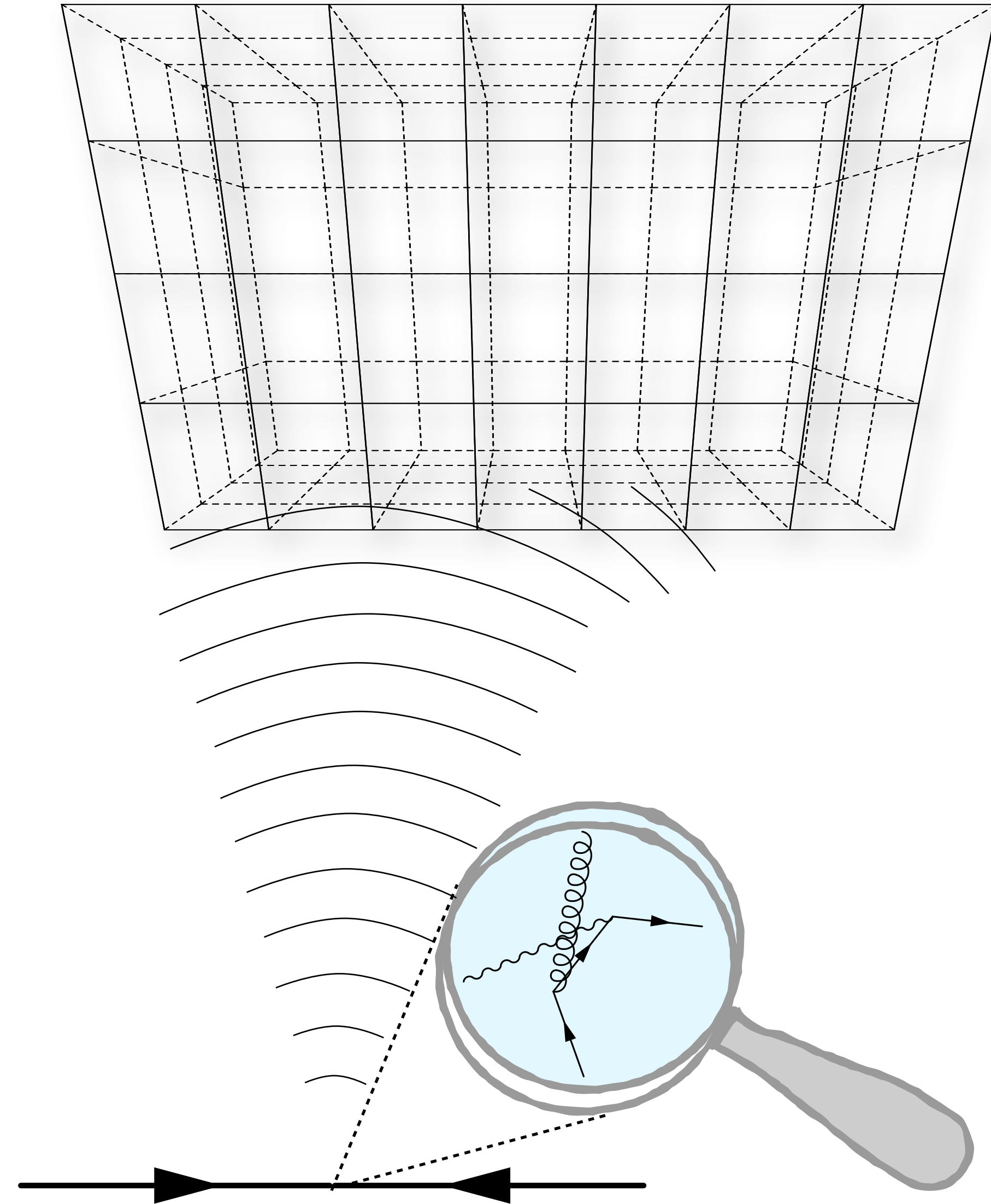
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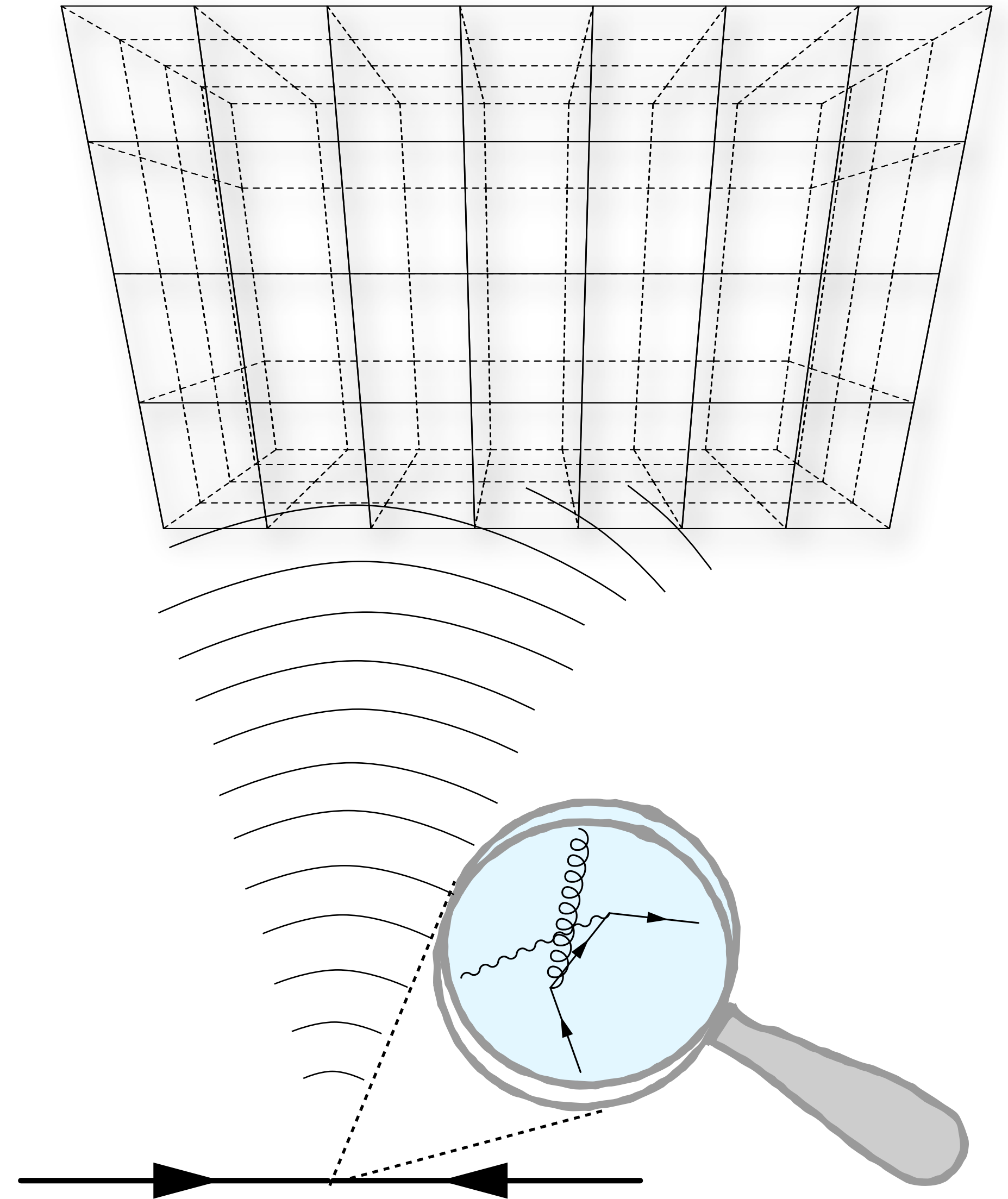
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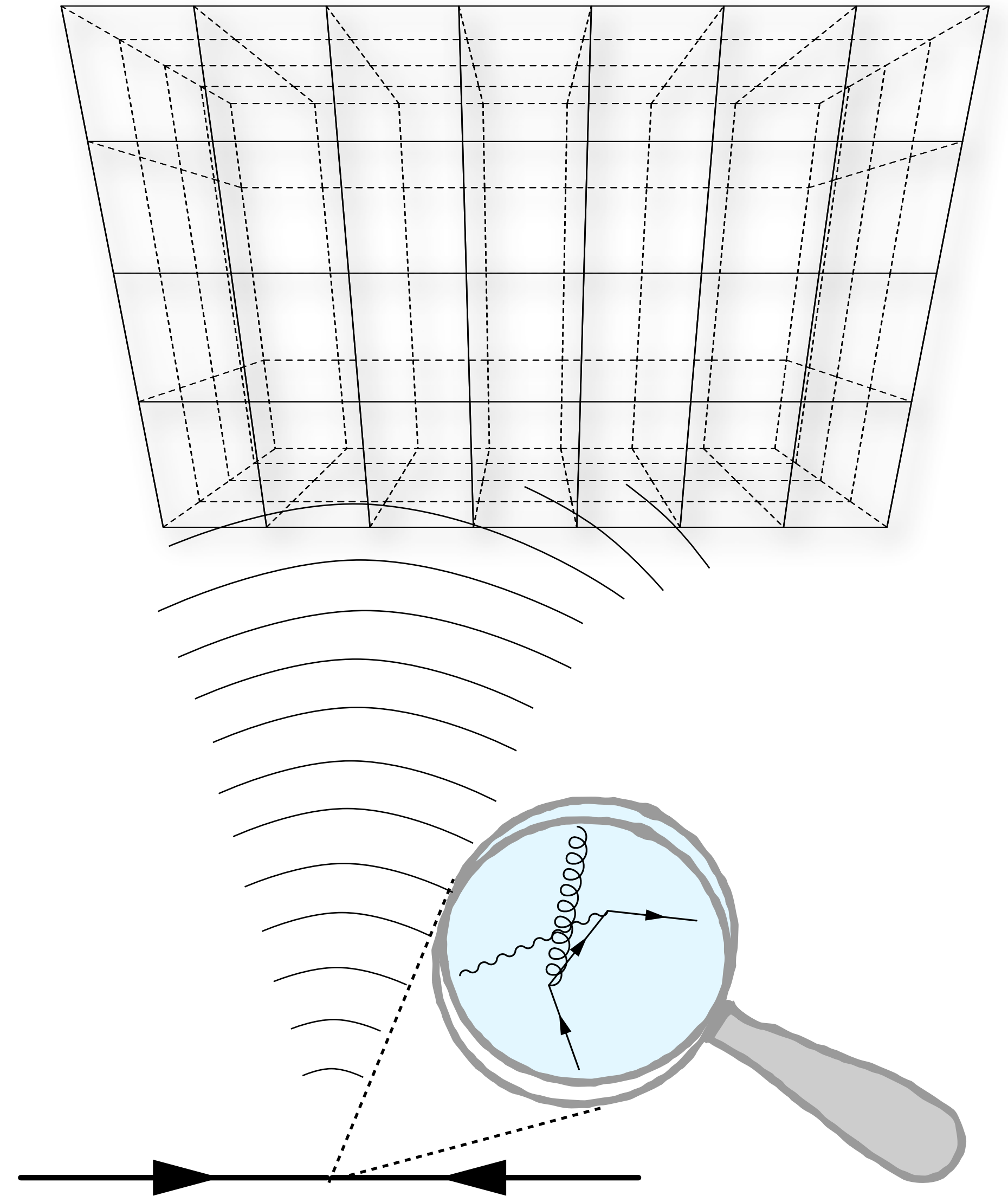
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 - (decay or not to) visible particles



Particle Physics Detector

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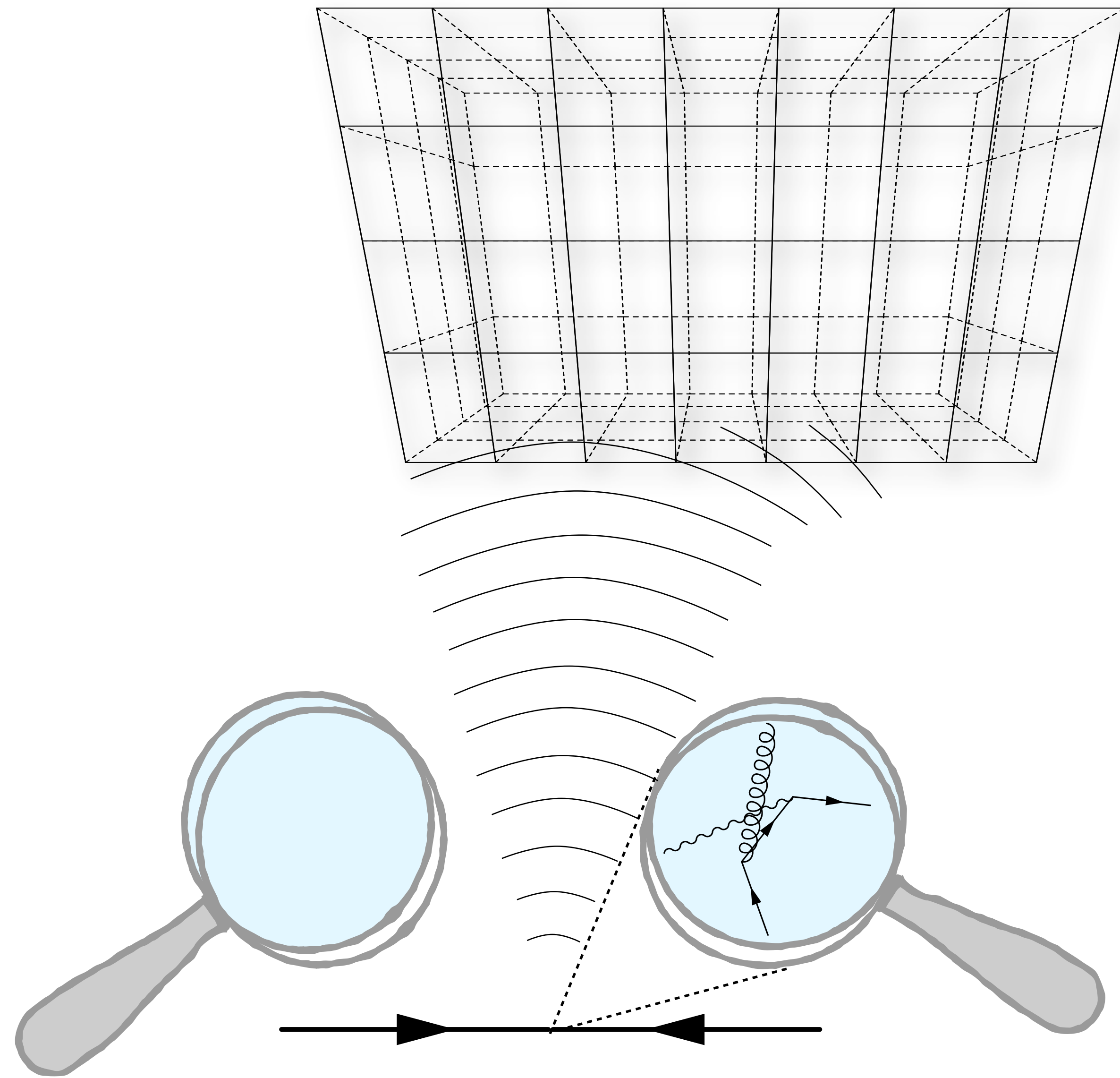
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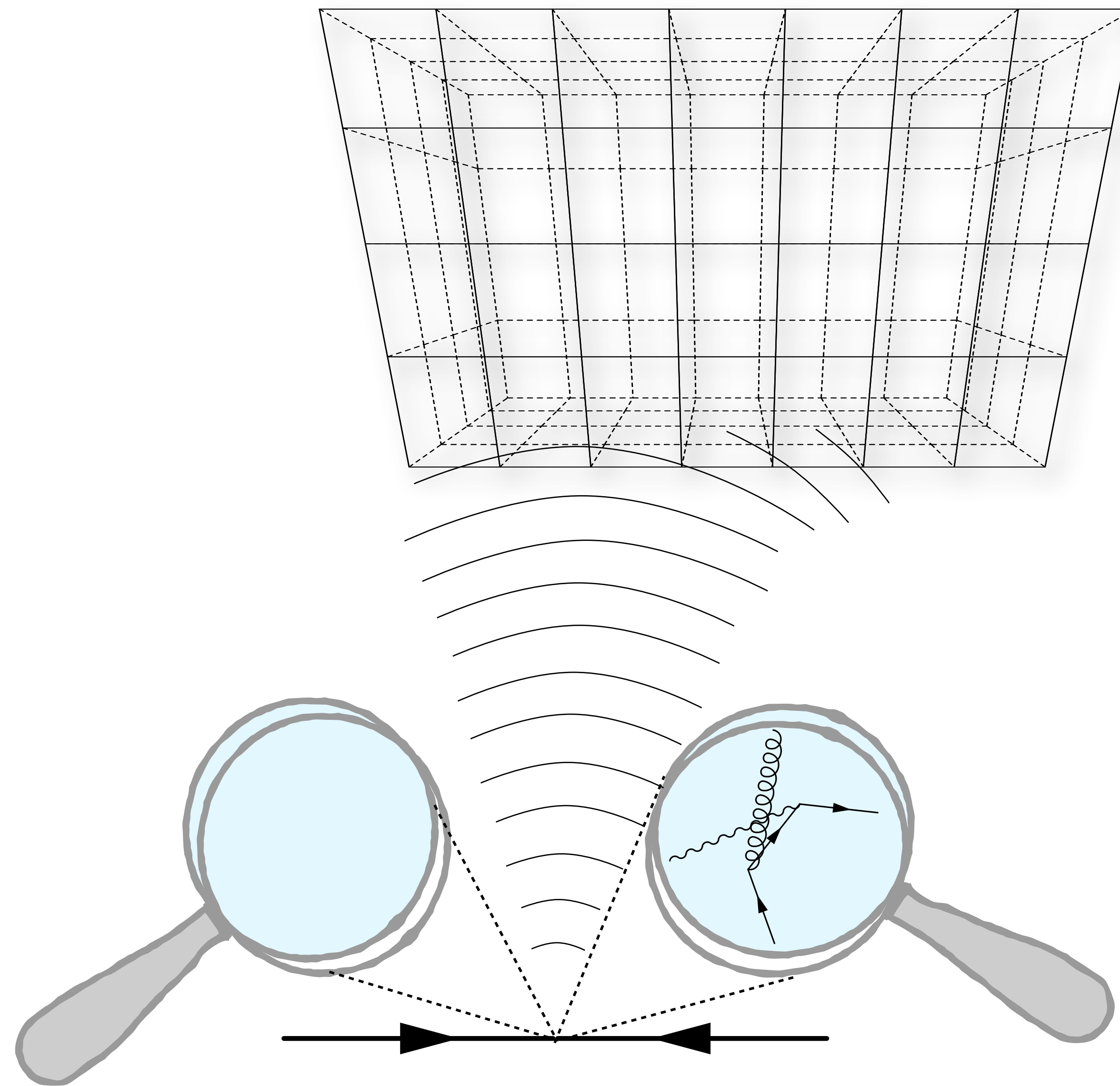
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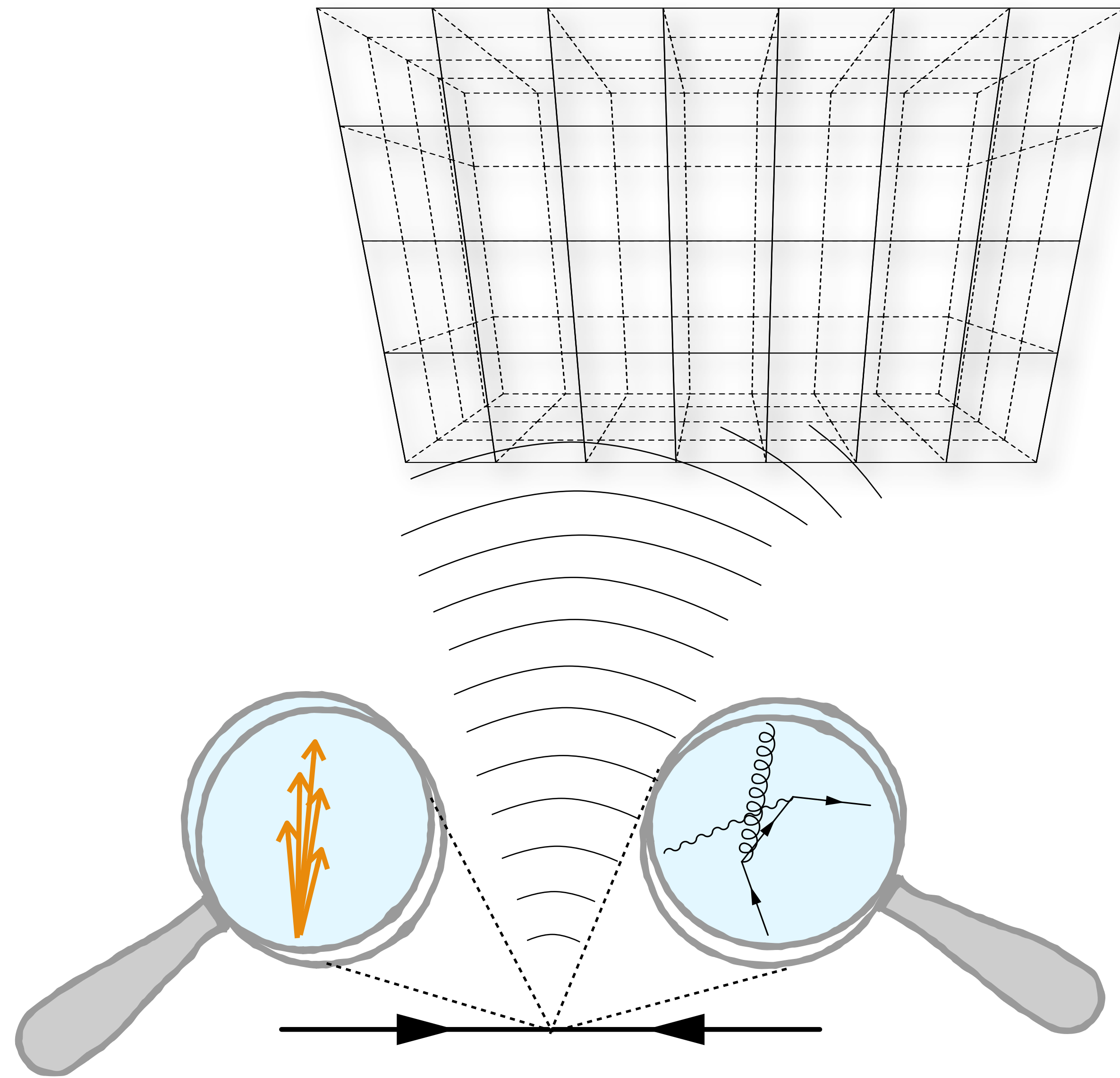
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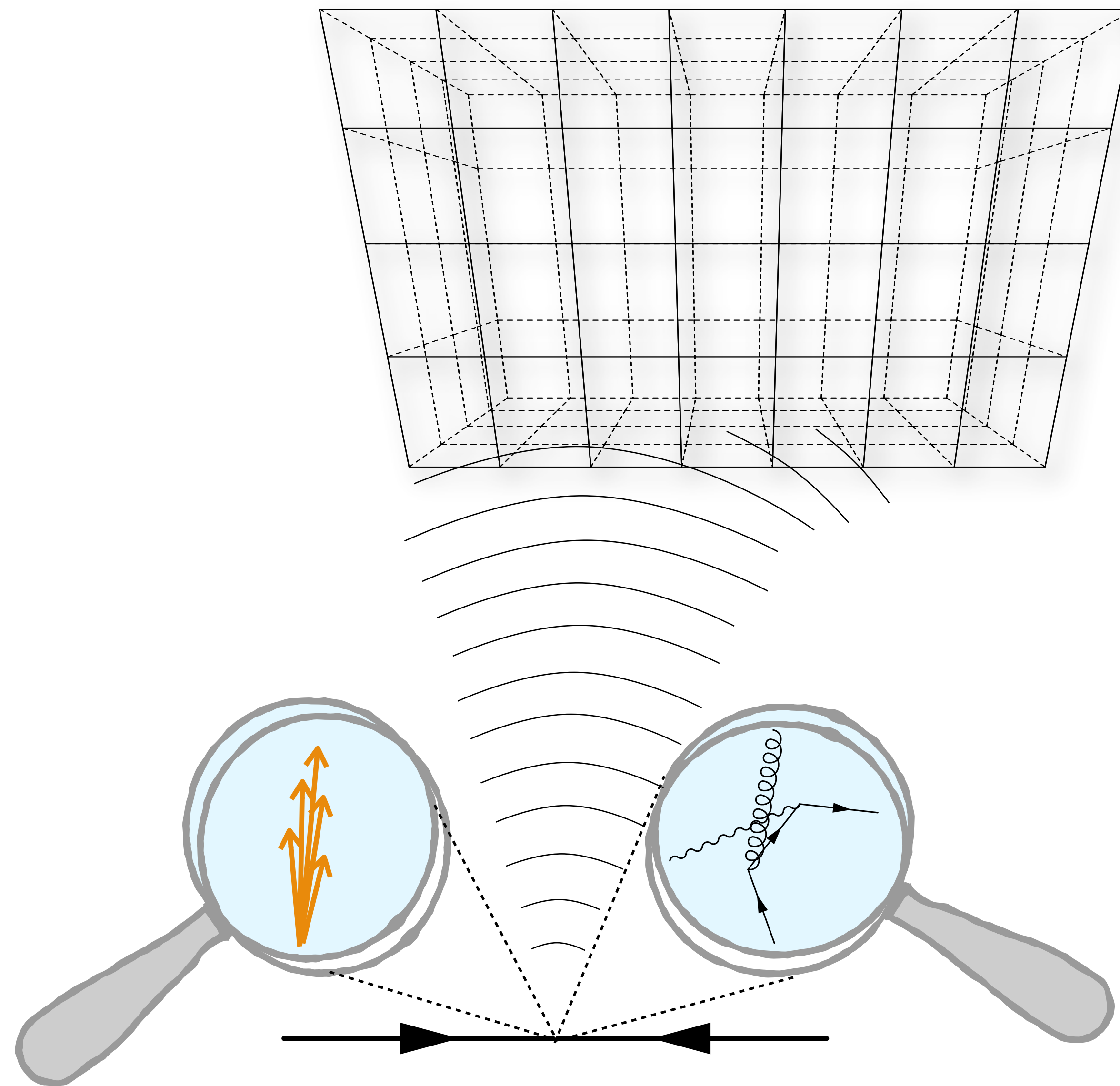
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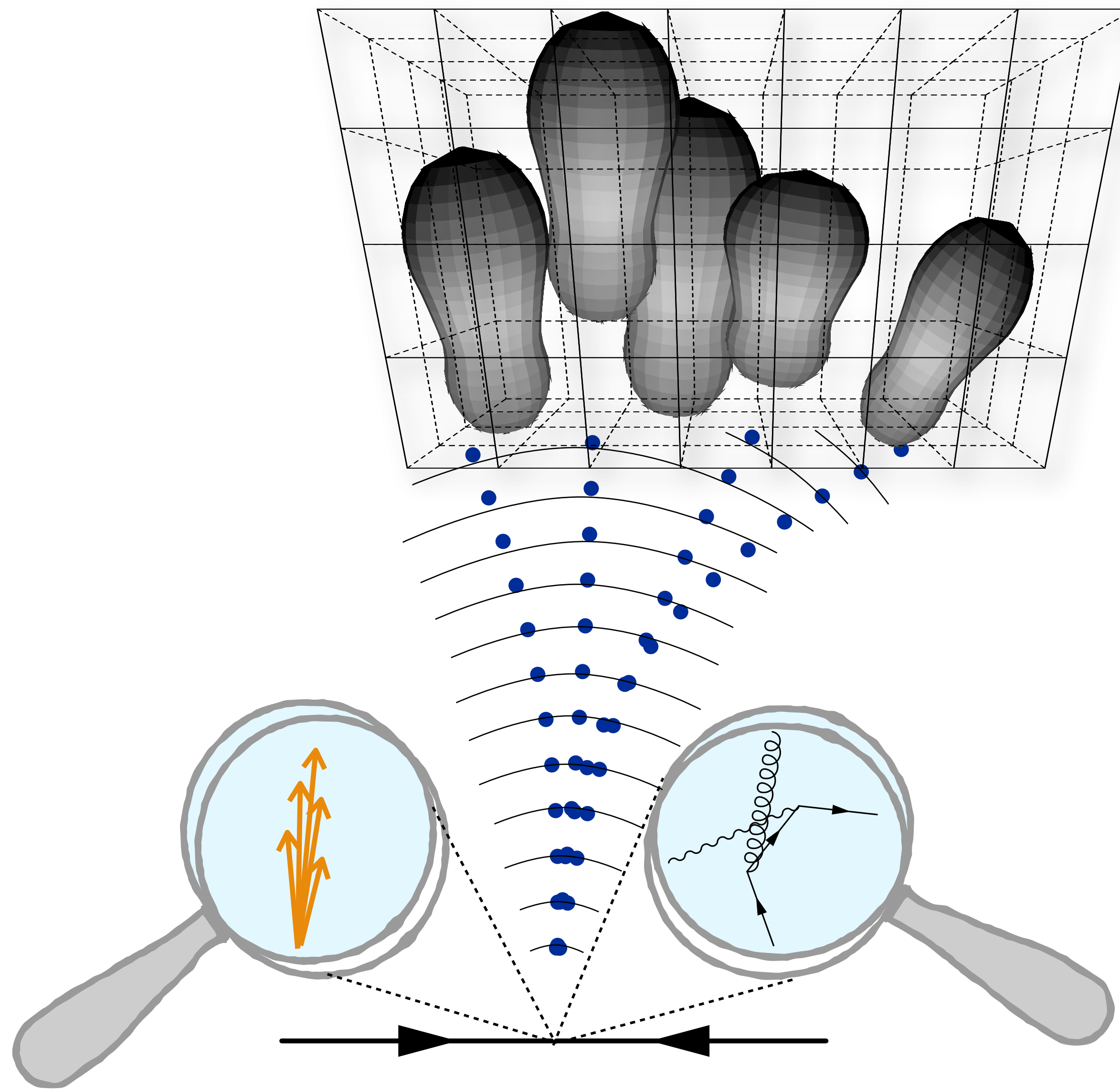
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Particle Physics Detector

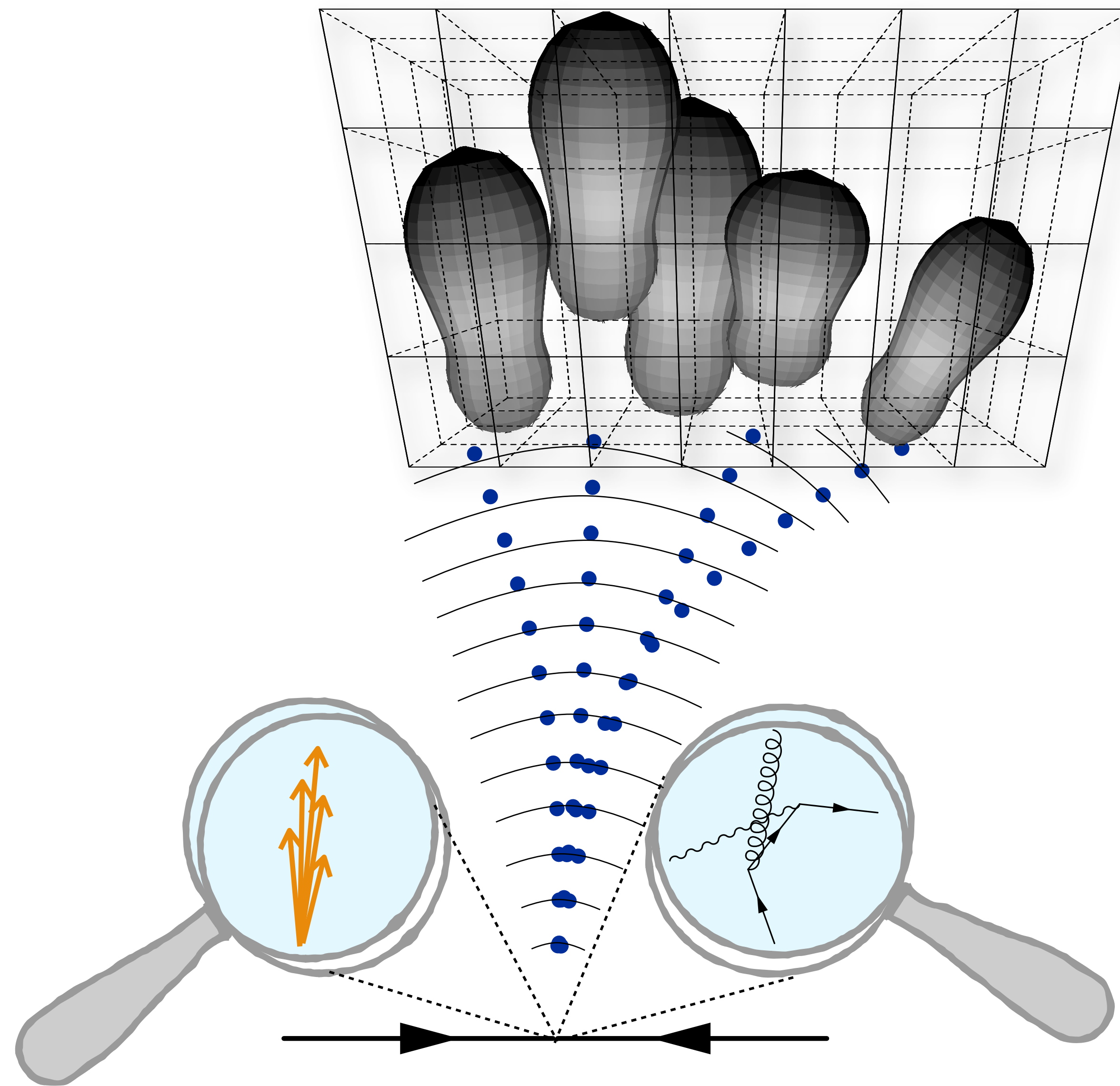
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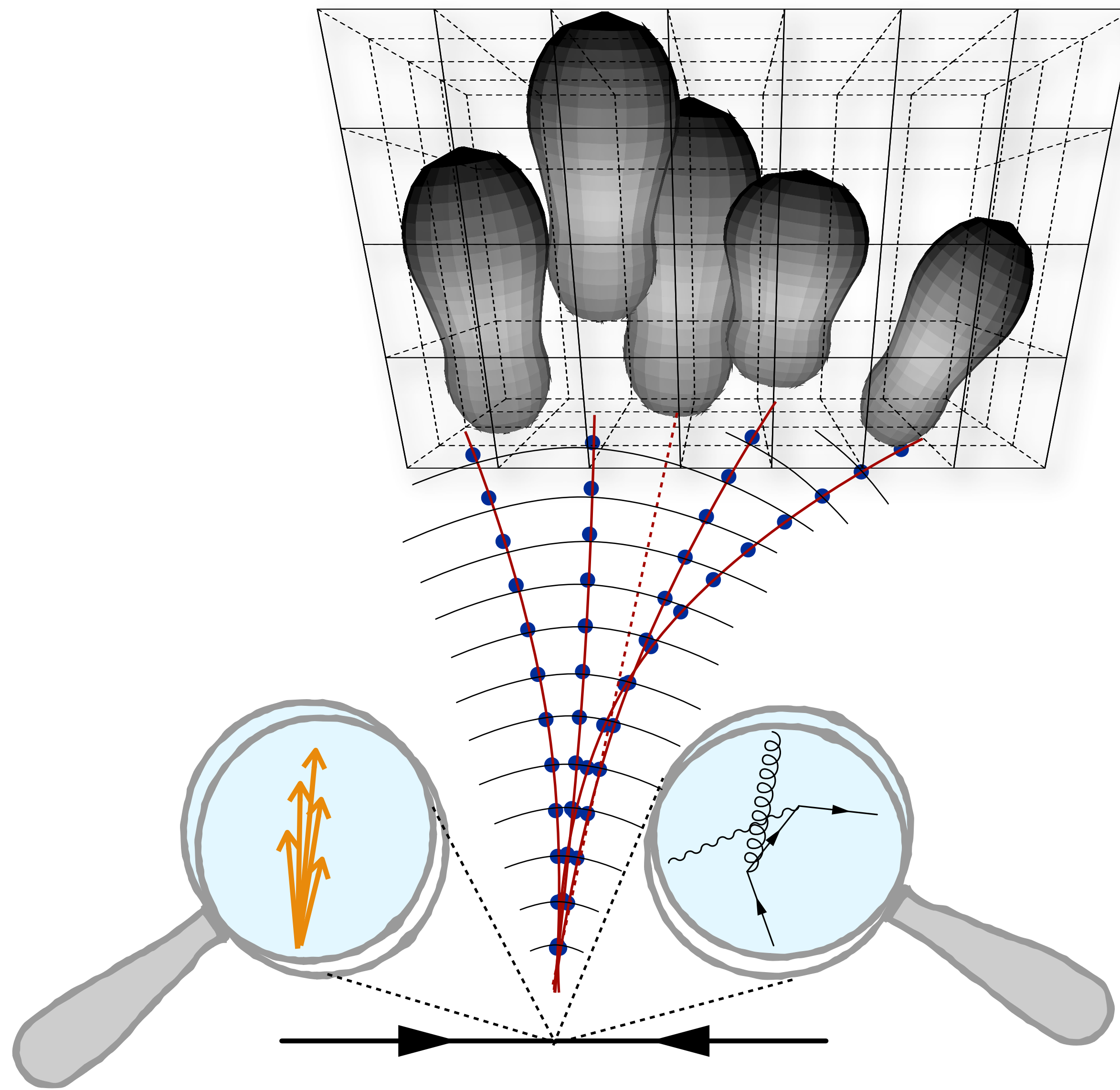
The Big Picture!

- Physics process => Partons
- Partons =>
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 - Reconstructed quantities
(momenta, charge, energies, angles)



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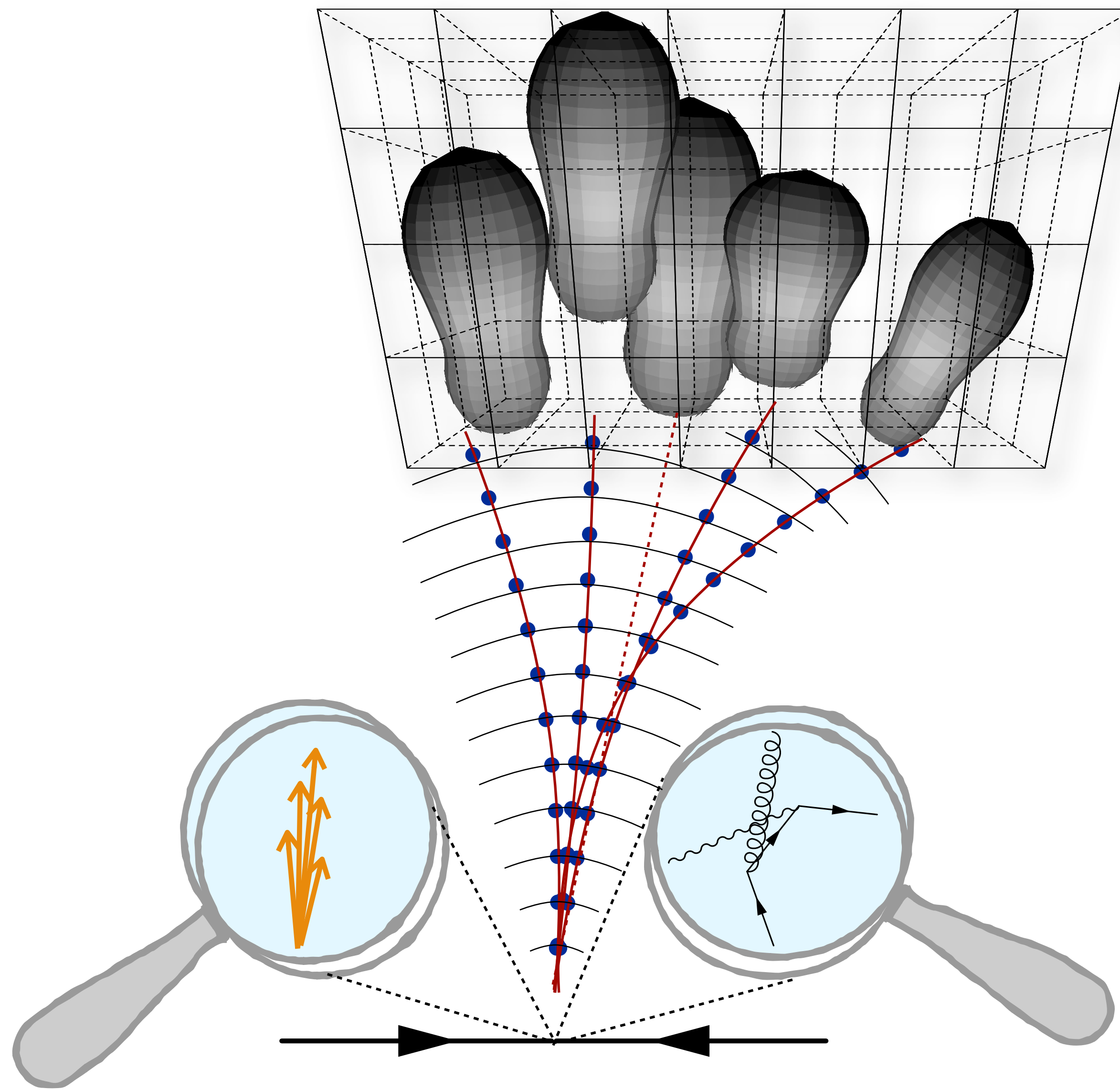
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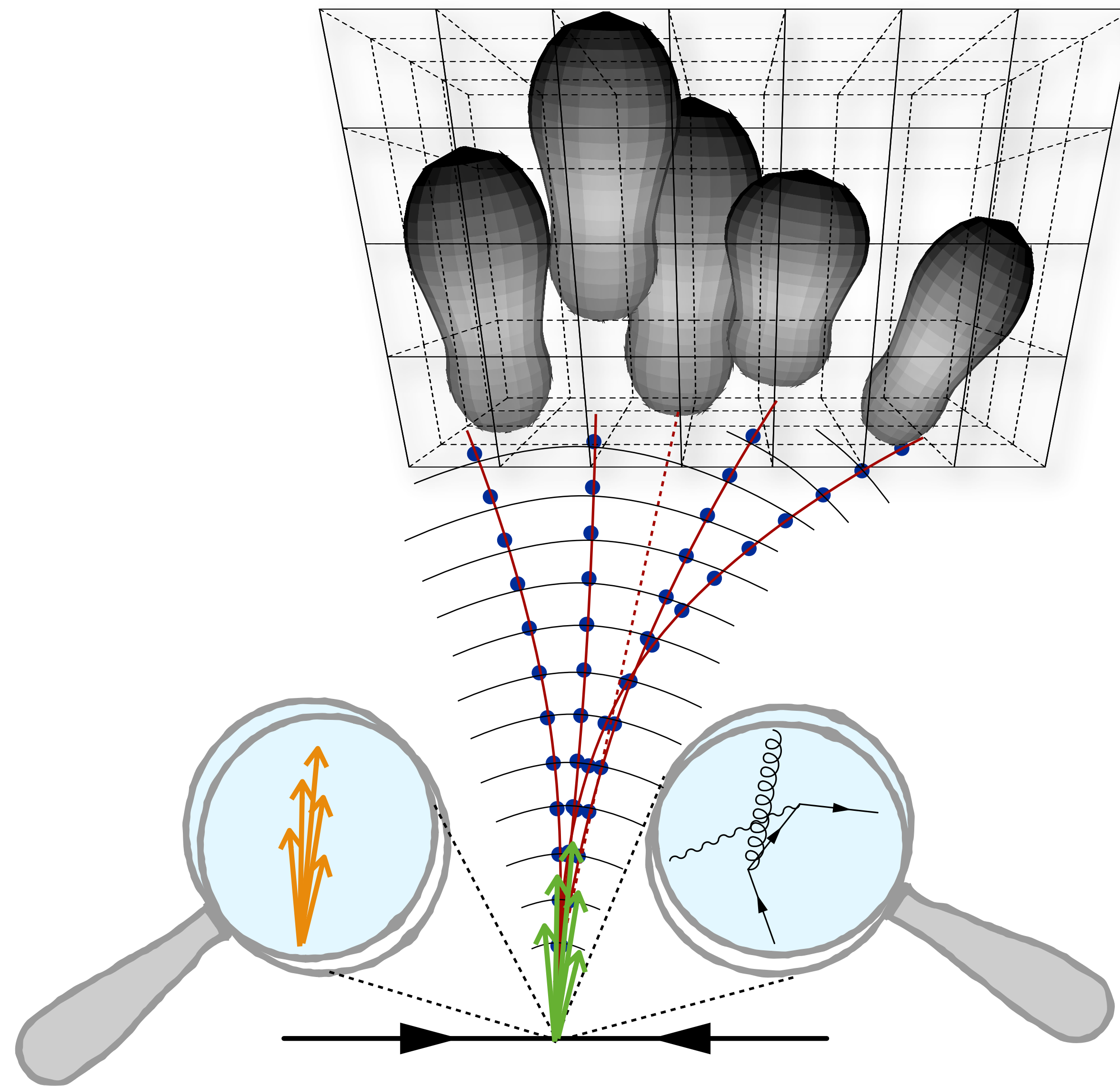
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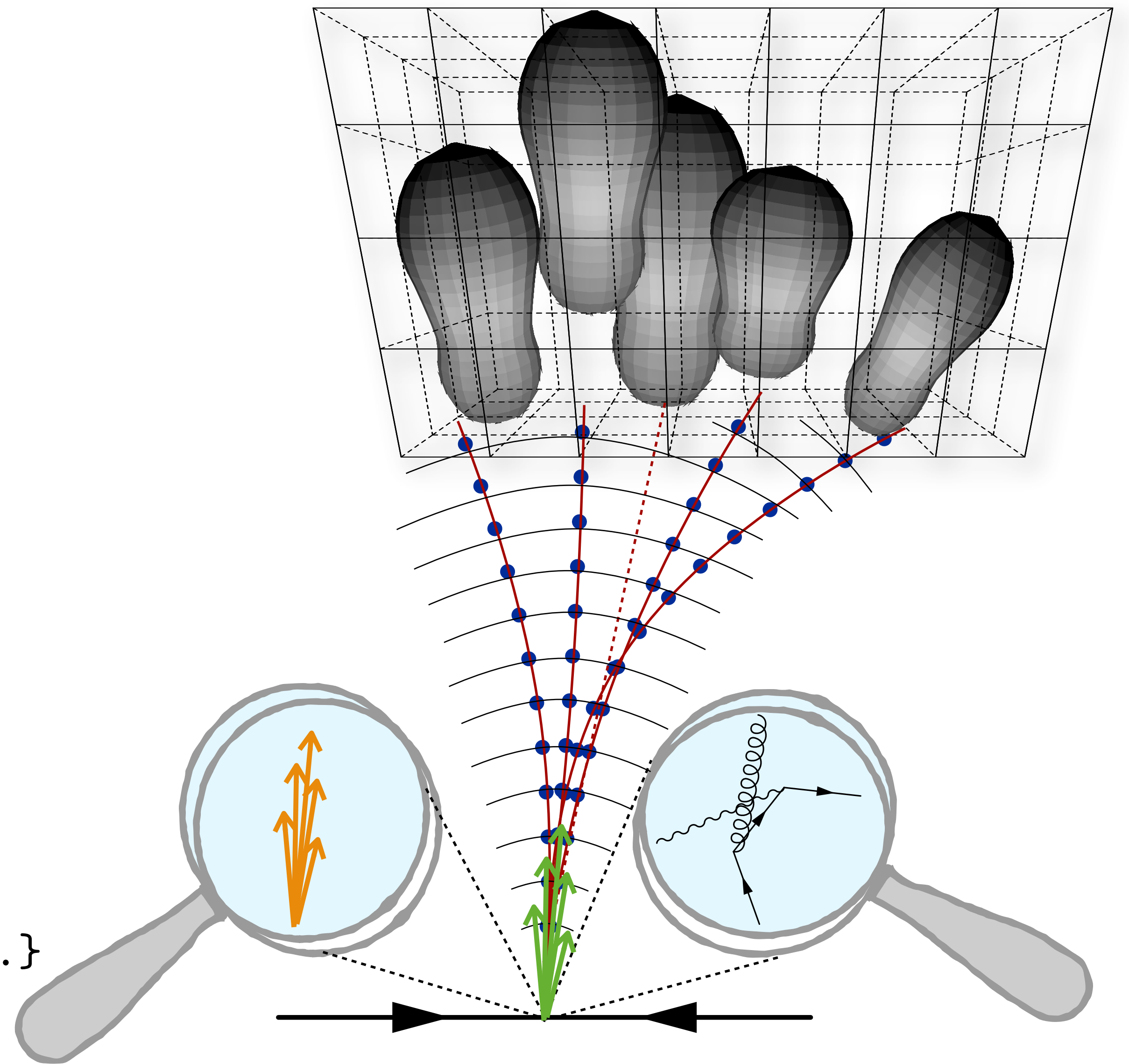
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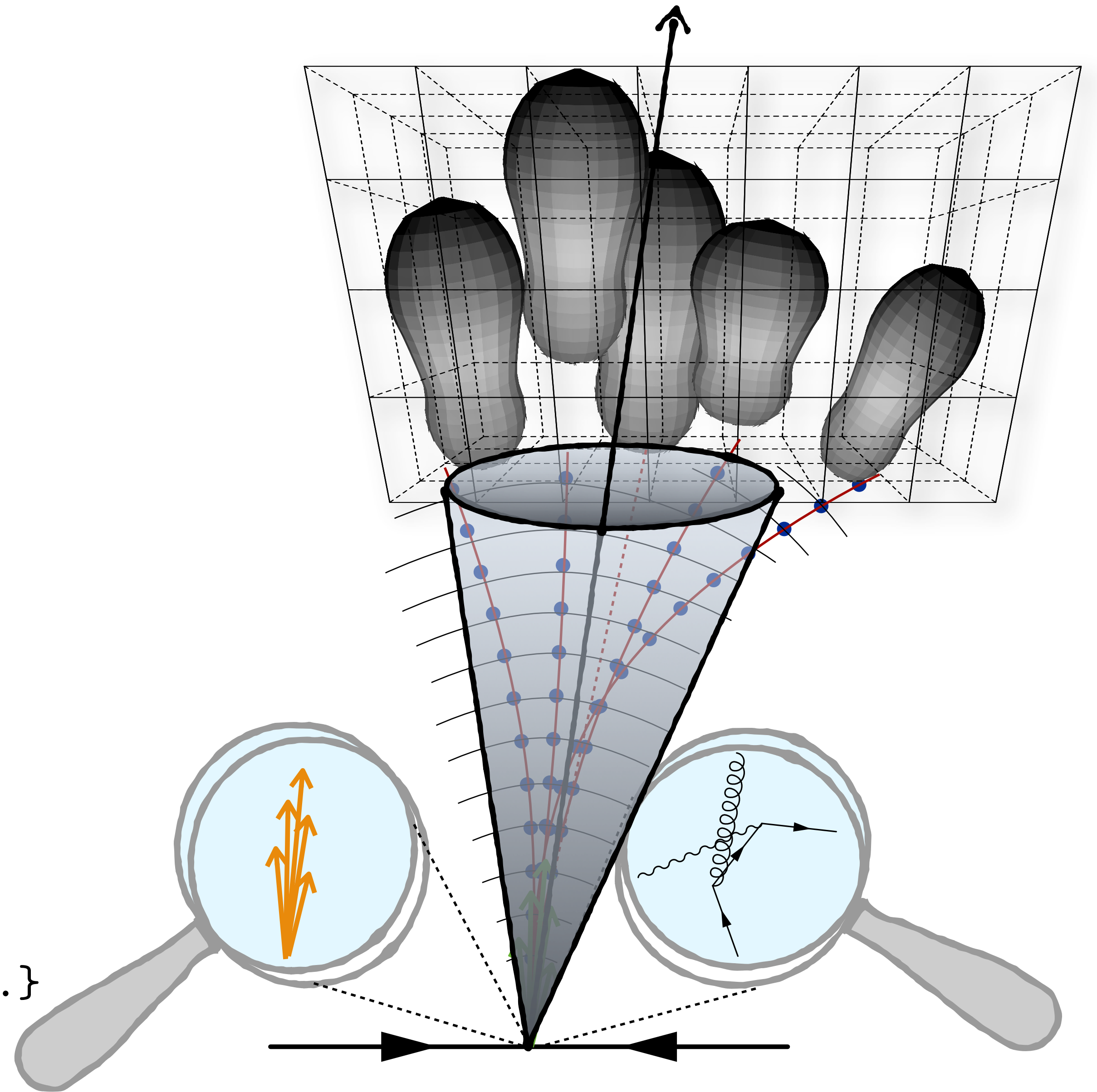
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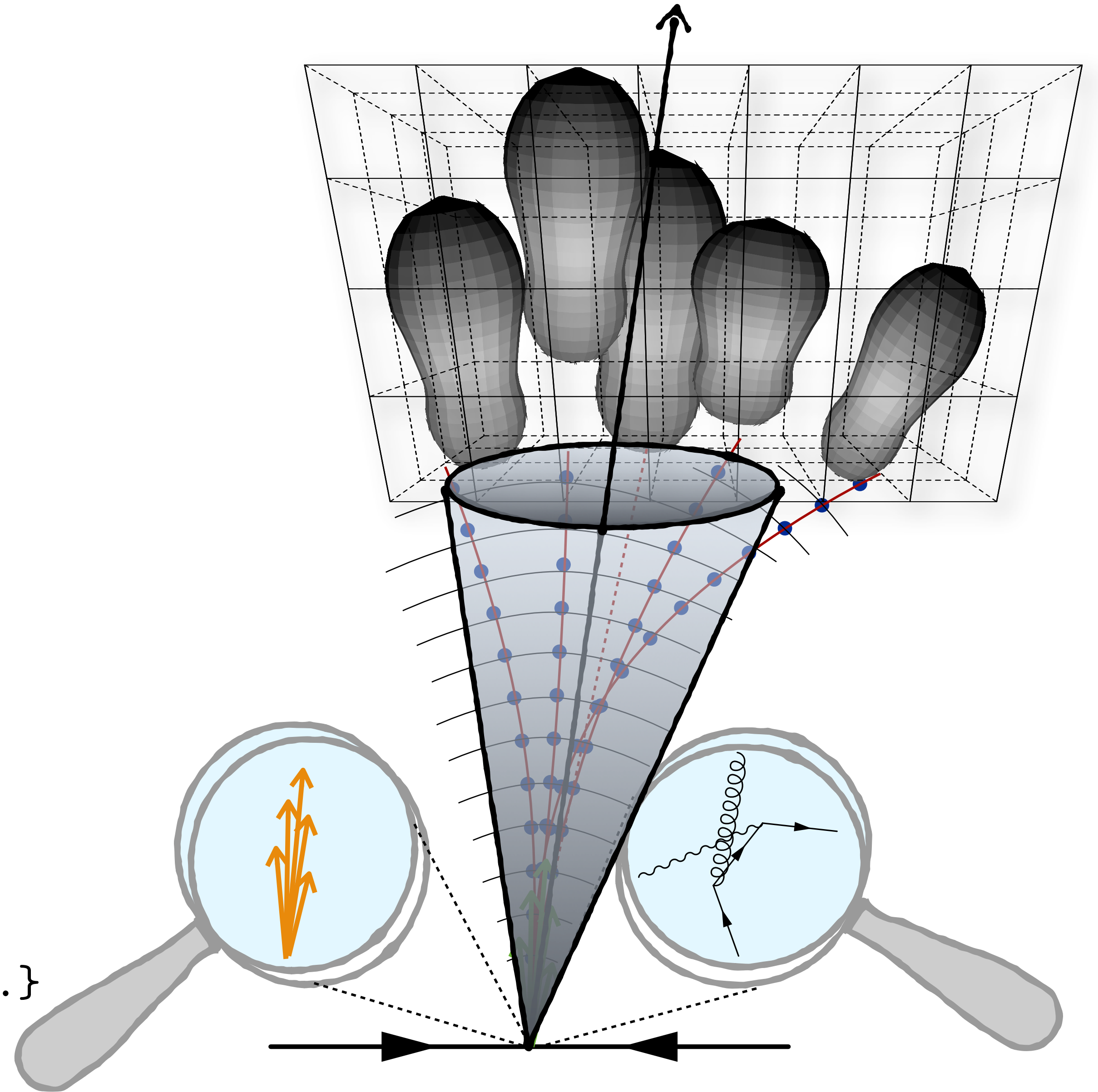
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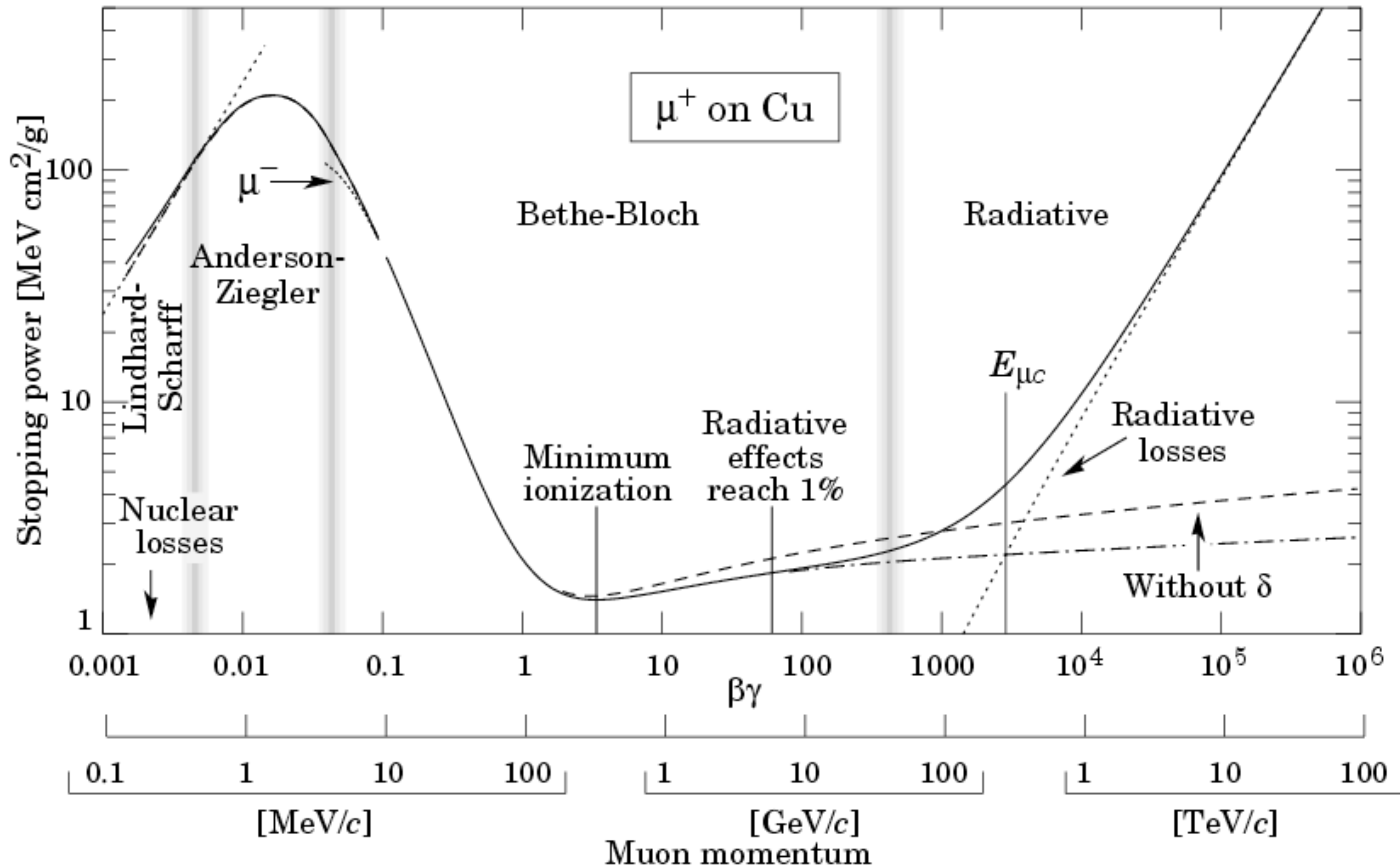
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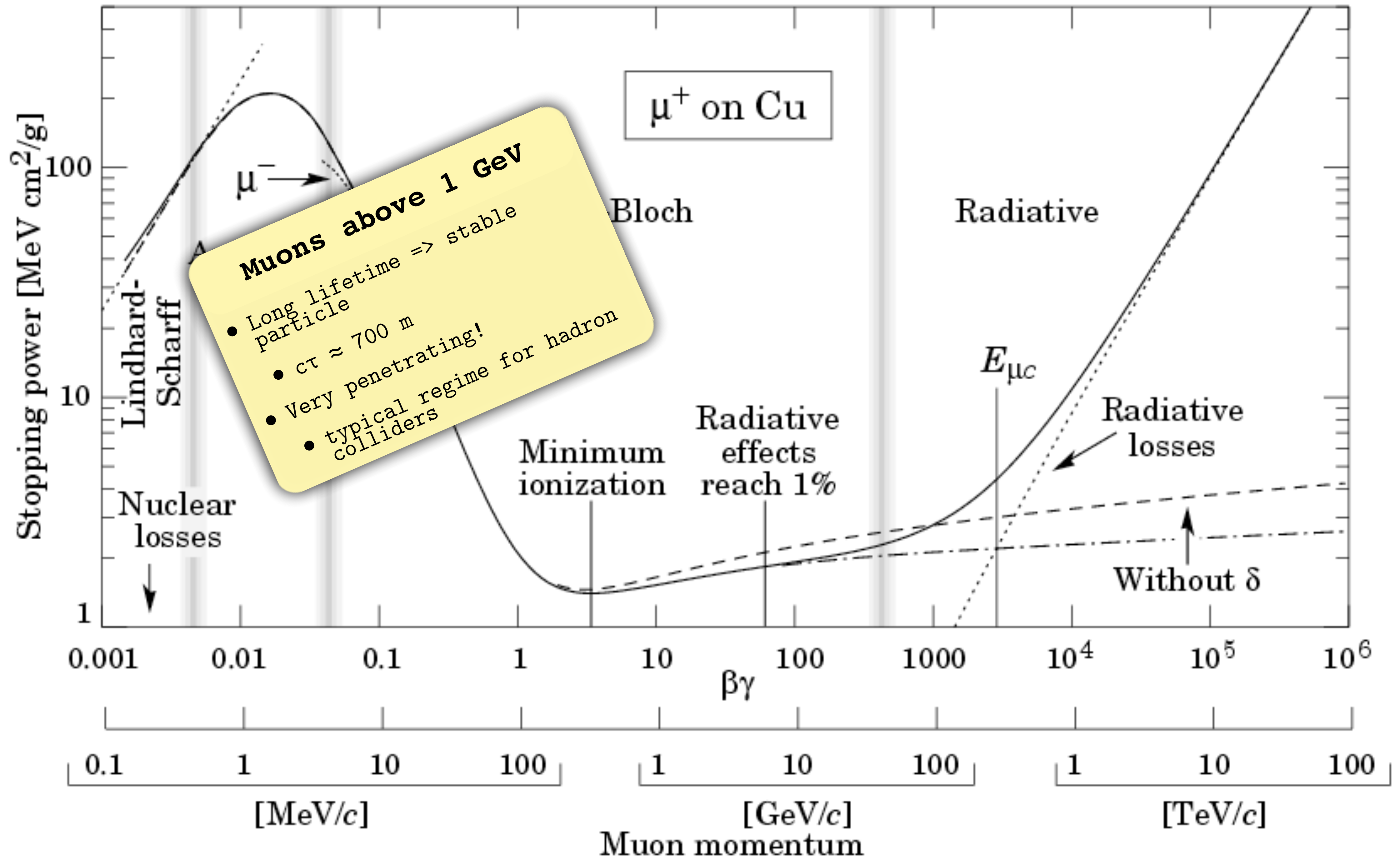


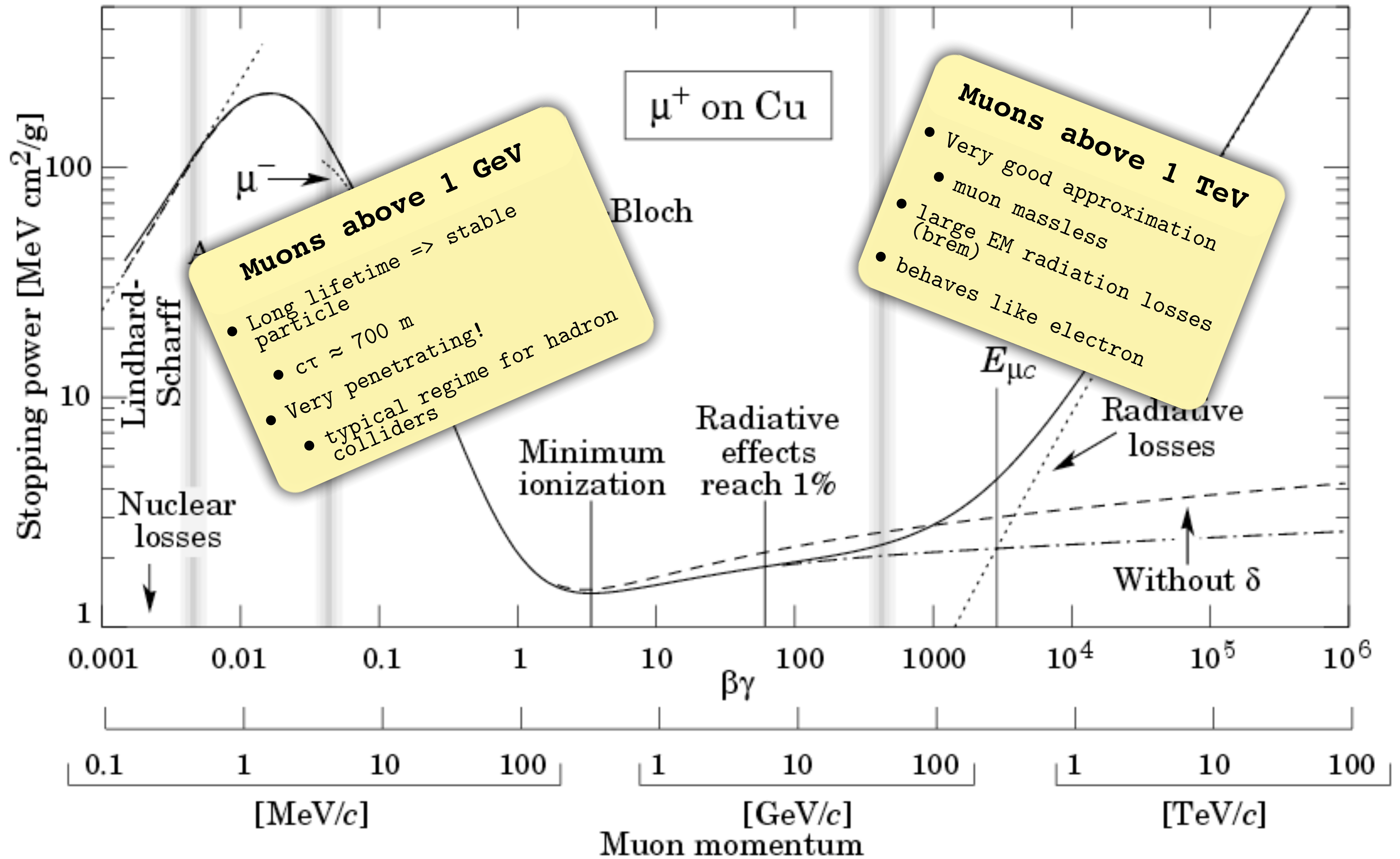
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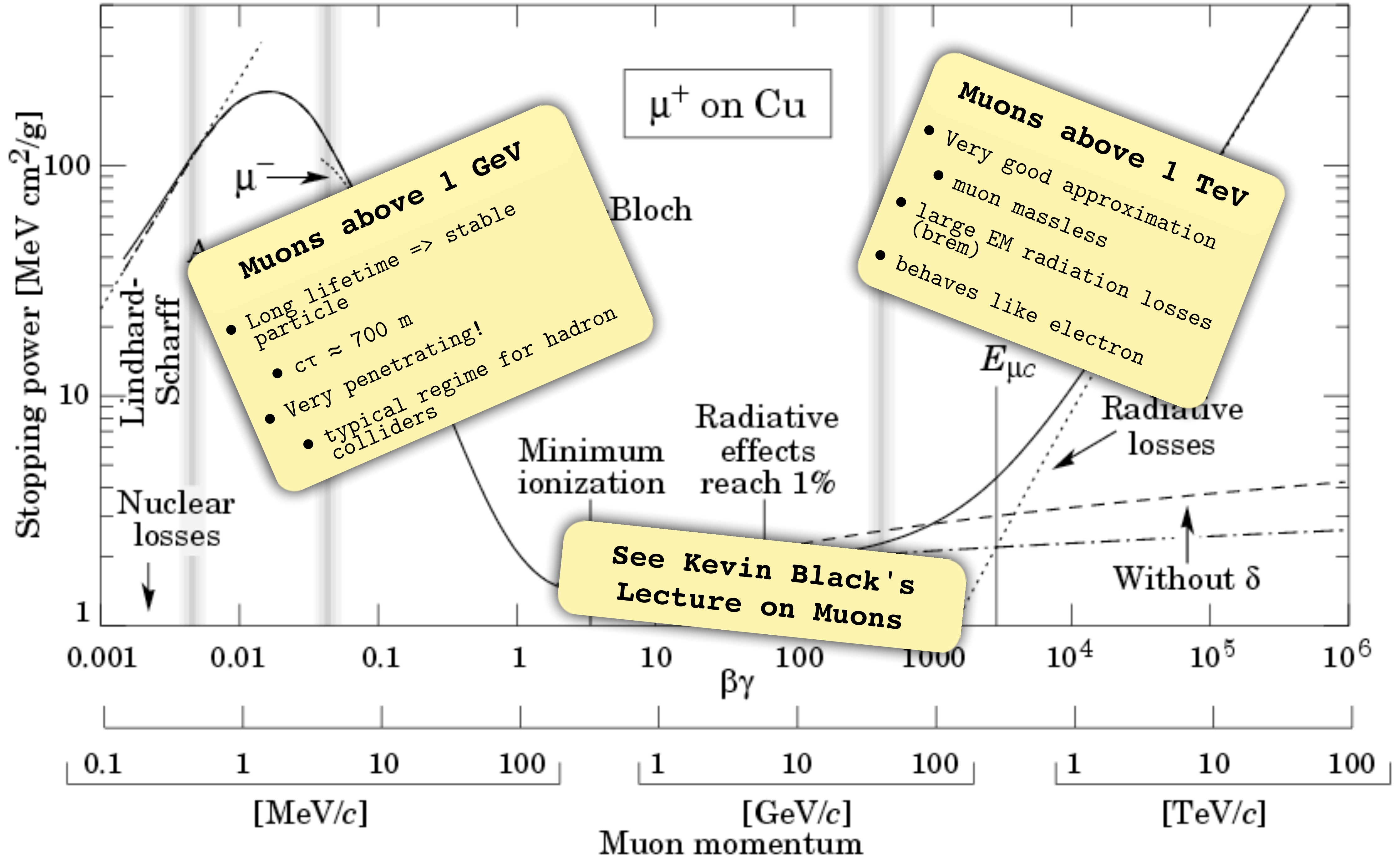
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 - Physics process (hypothesis)



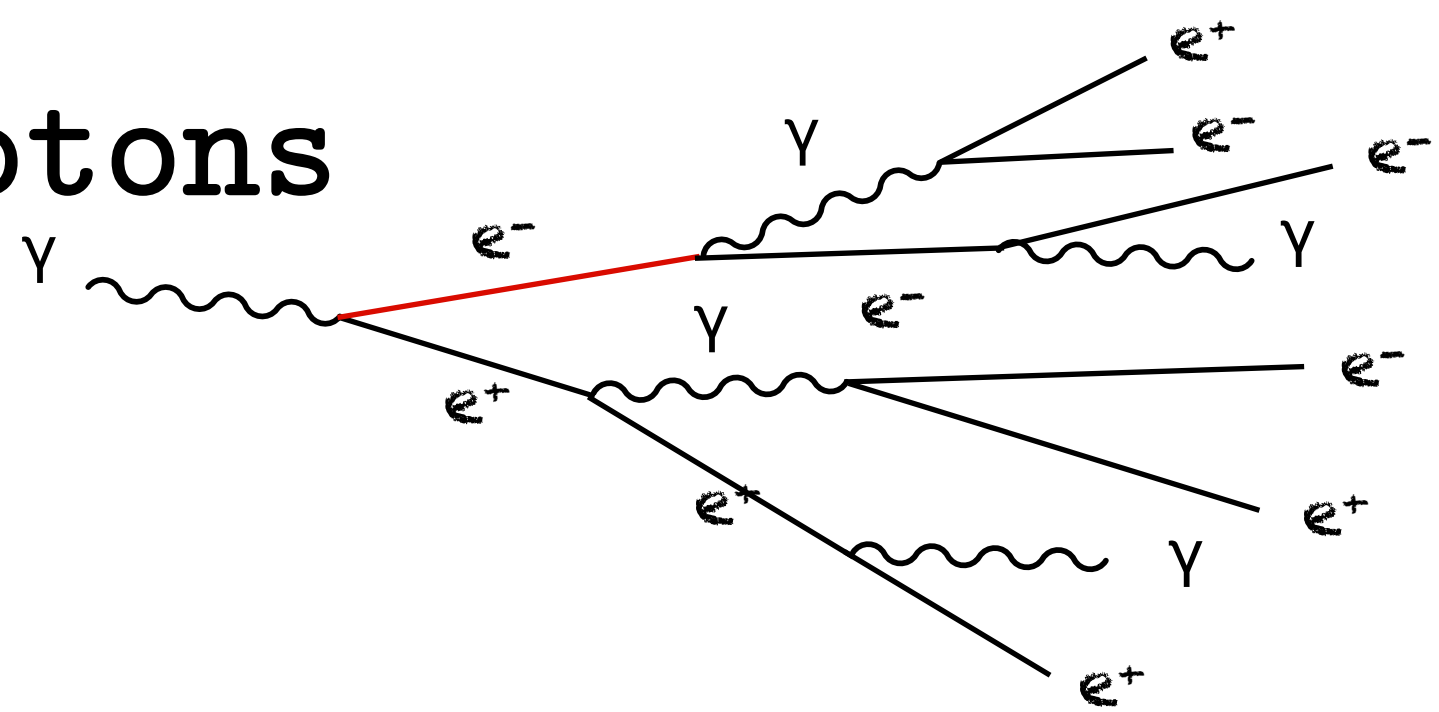




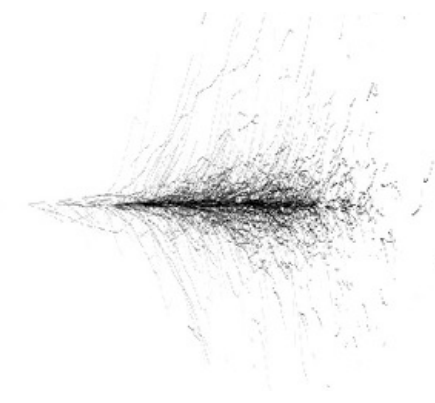
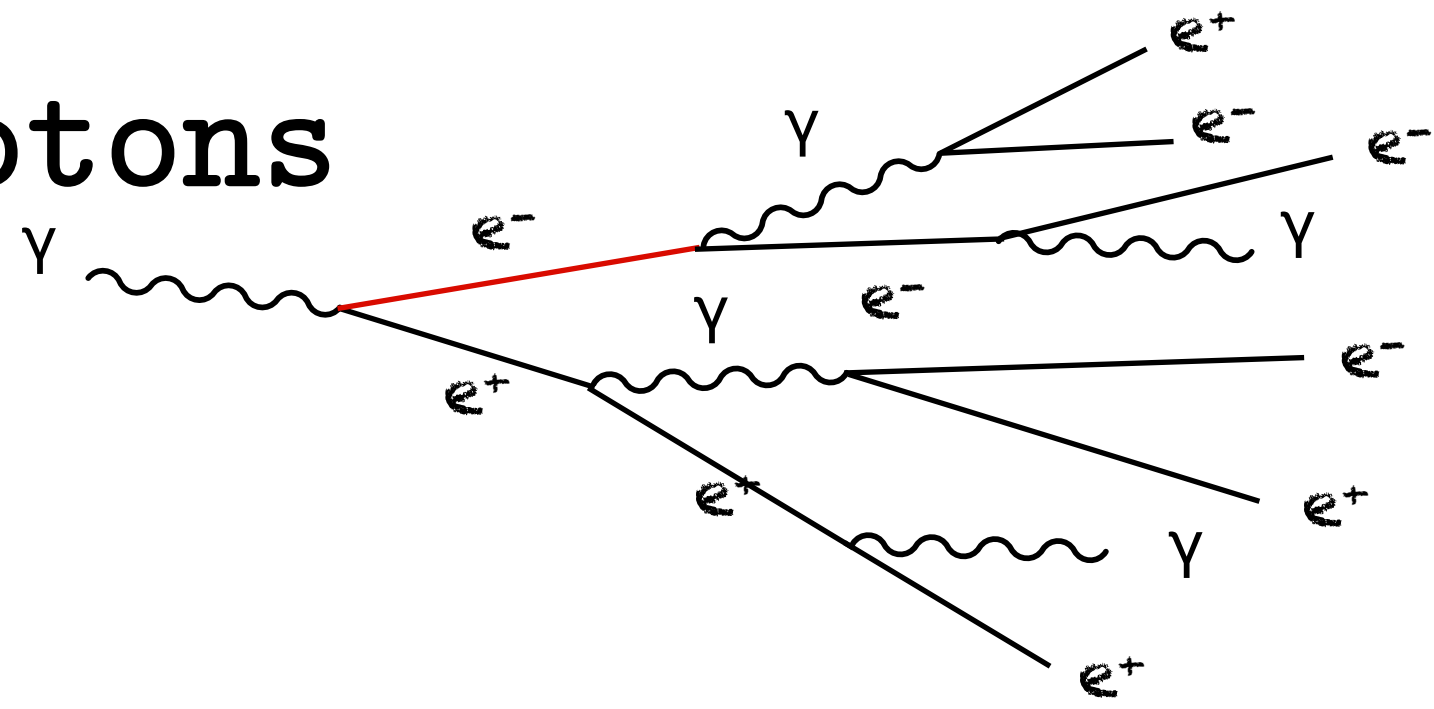




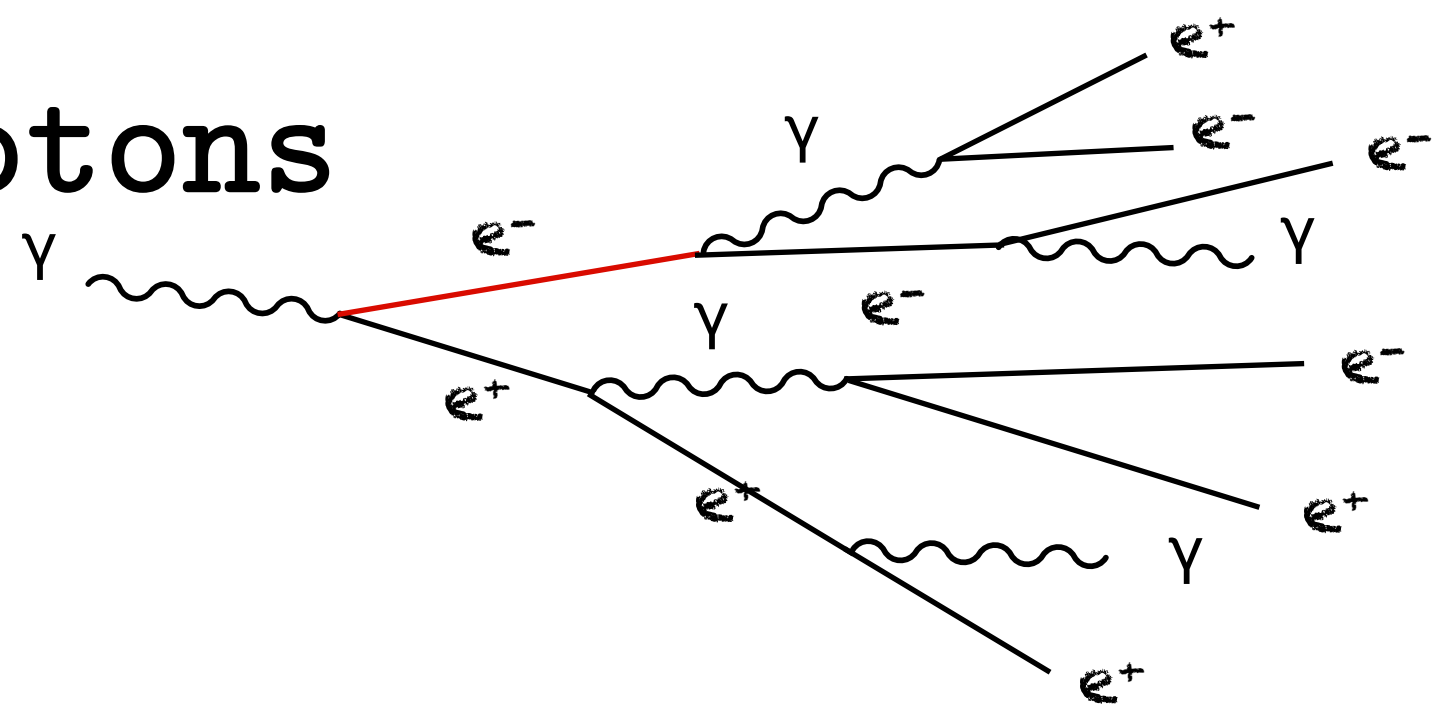
Electrons & Photons



Electrons & Photons



Electrons & Photons



Radiation Length

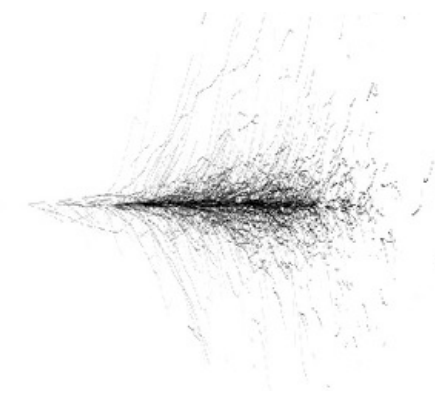
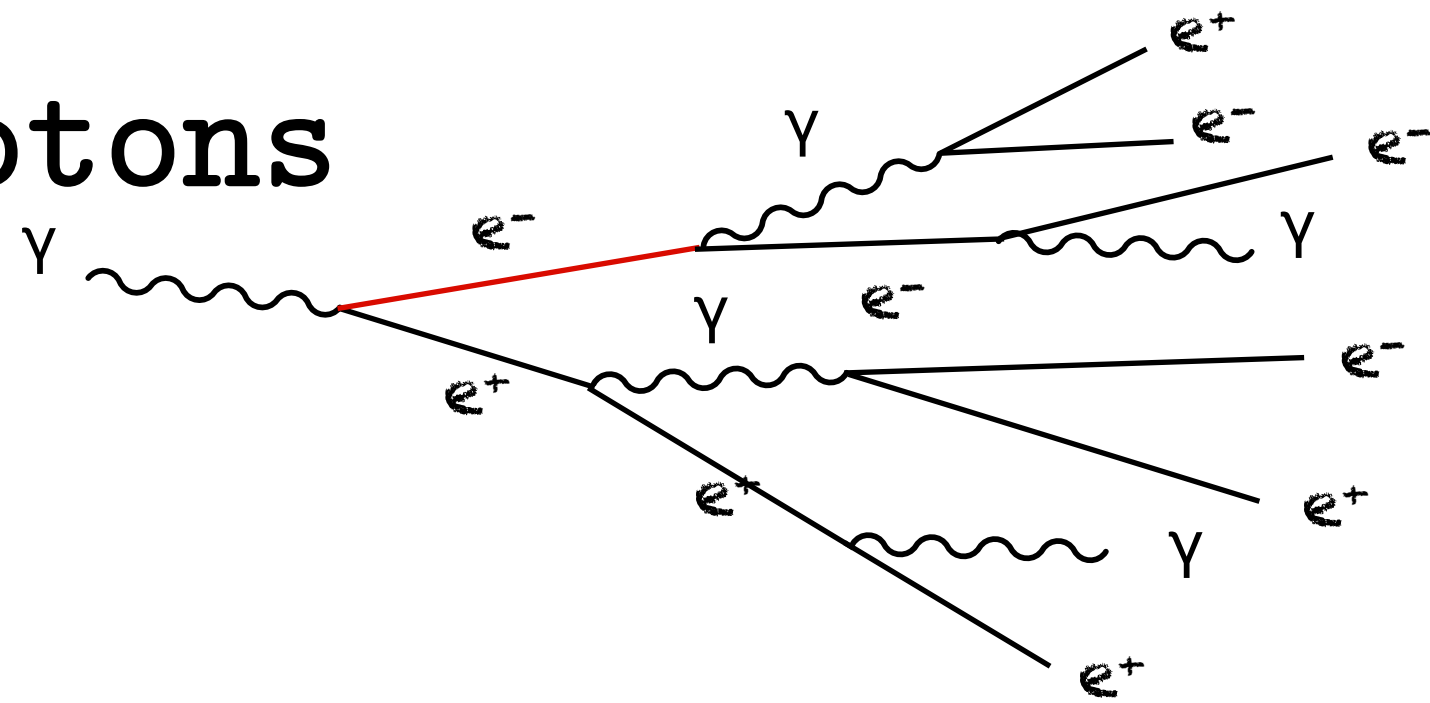
- Characteristic distance over which the electron energy is reduced by a factor of $1/e$ due to radiation losses only

$$X_0 = \frac{716.4 \text{ g cm}^{-2} A}{Z(Z+1) \ln(287/\sqrt{Z})}$$

- Higher Z materials have short length
- want high-Z material for EM calorimeter

Example: Lead
 $\rho = 11.4 \text{ g/cm}^3$; $X_0 = 5.5 \text{ mm}$

Electrons & Photons



Radiation Length

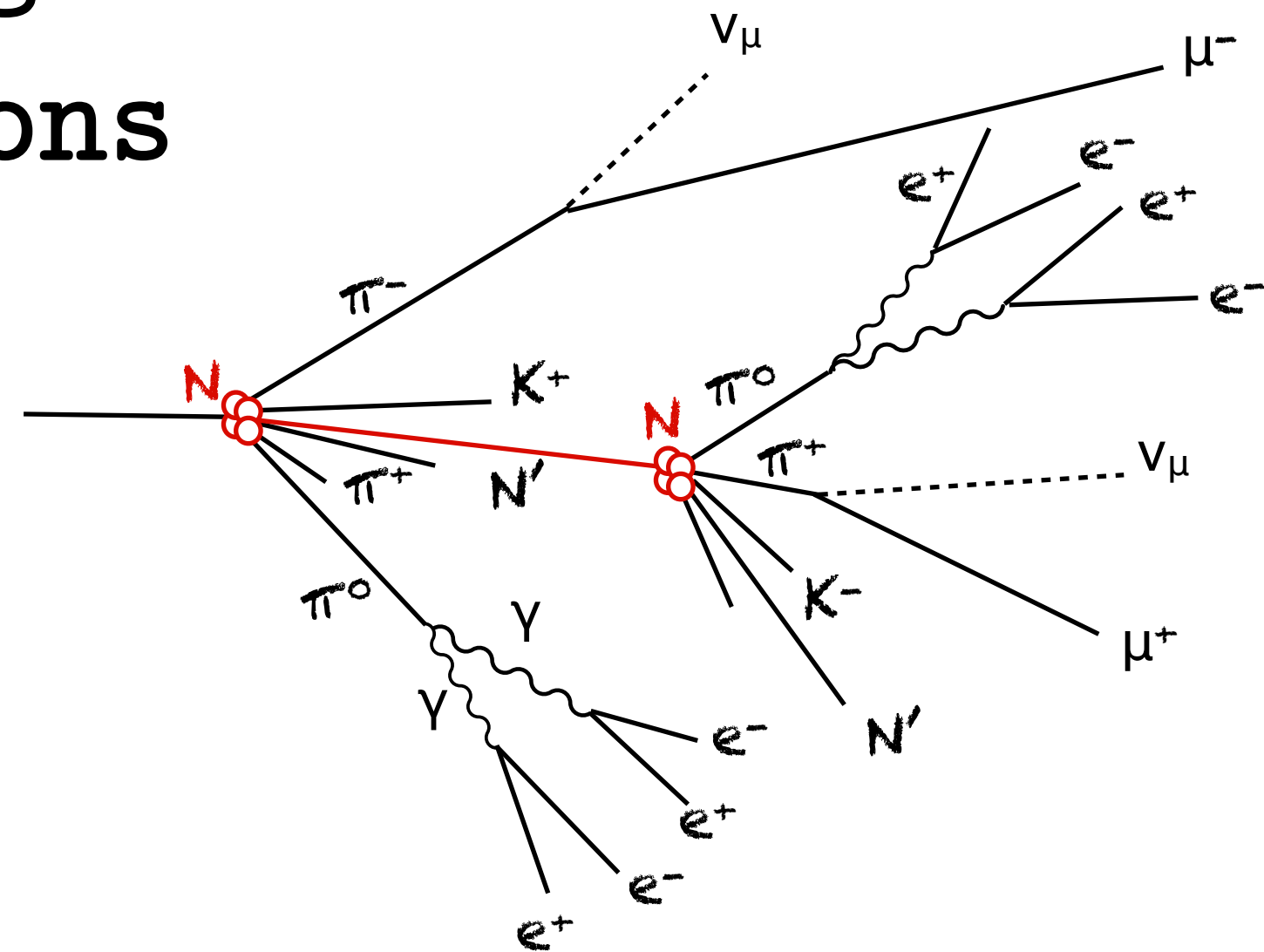
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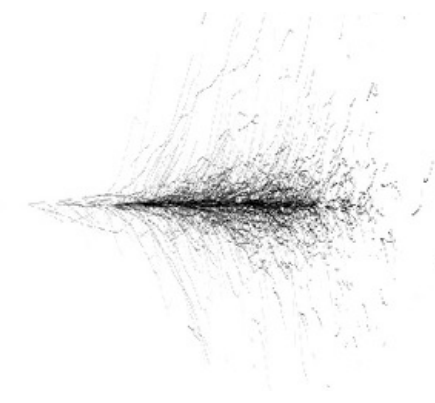
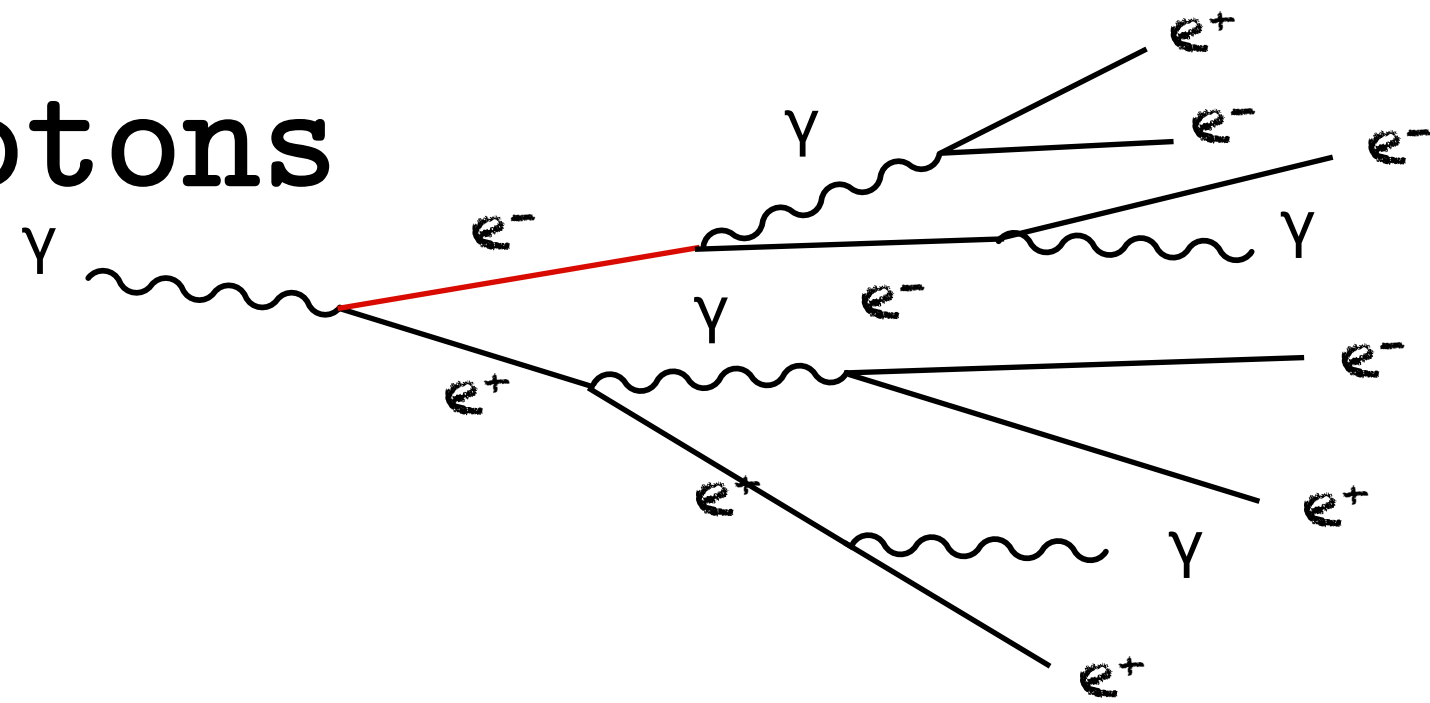
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Charged & Neutral Hadrons



Electrons & Photons



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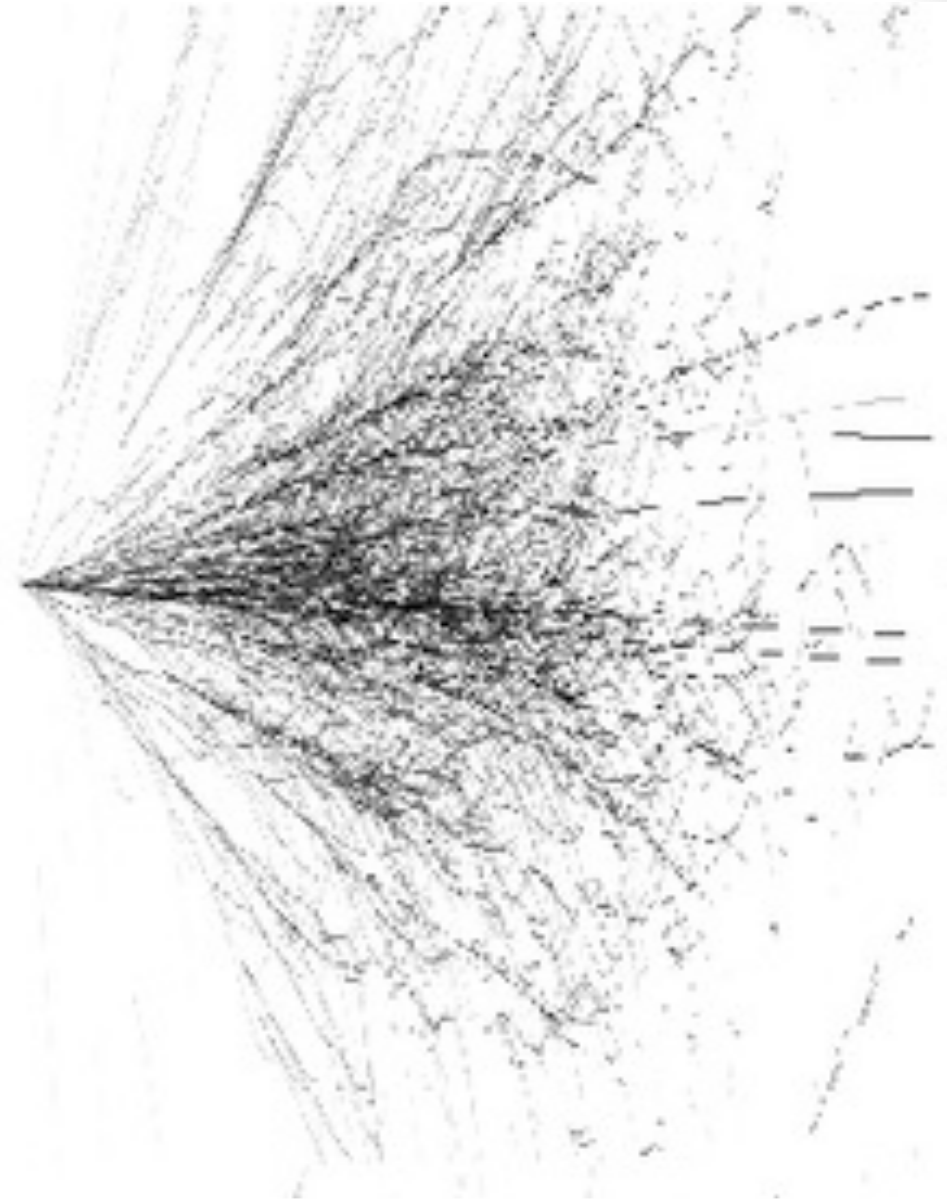
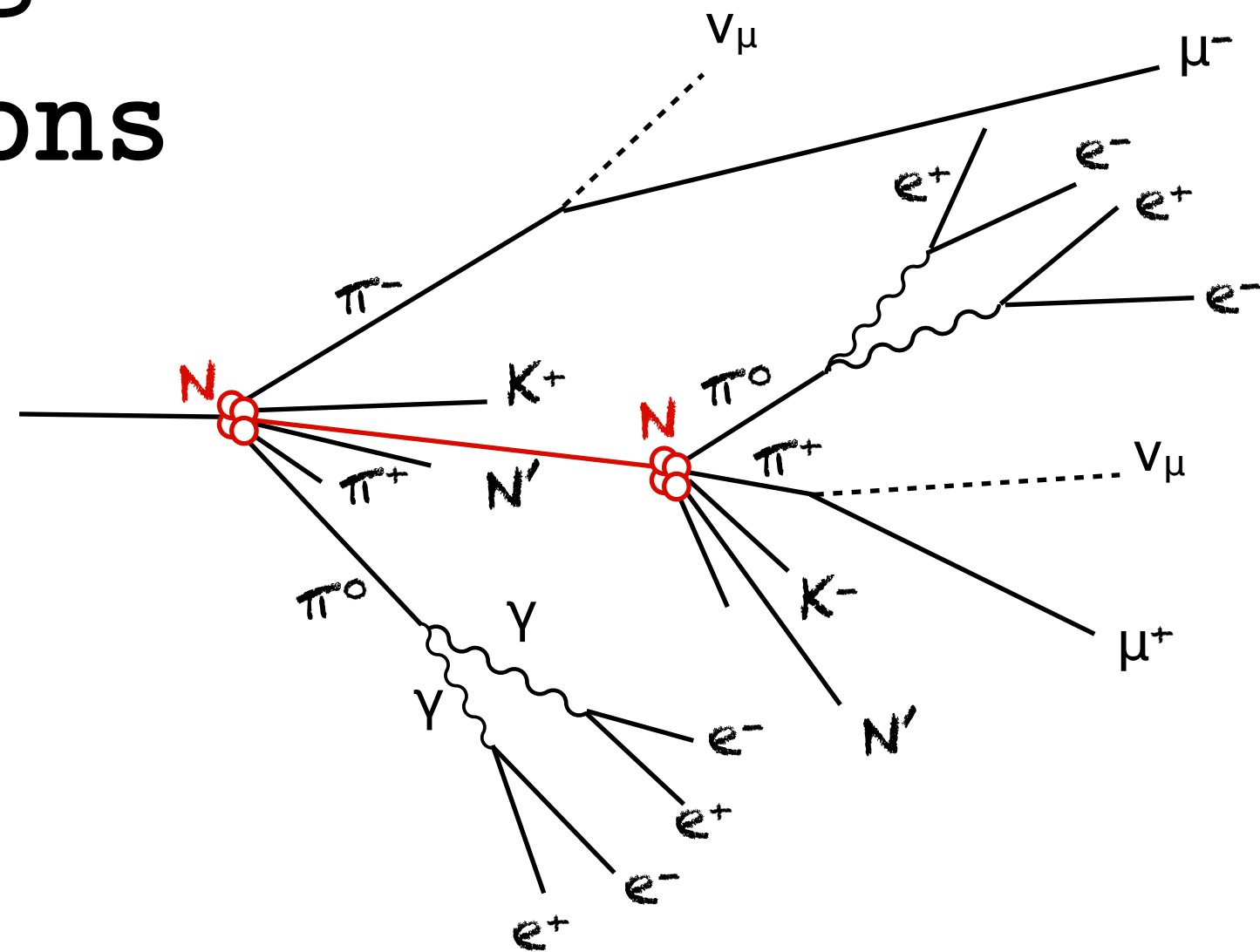
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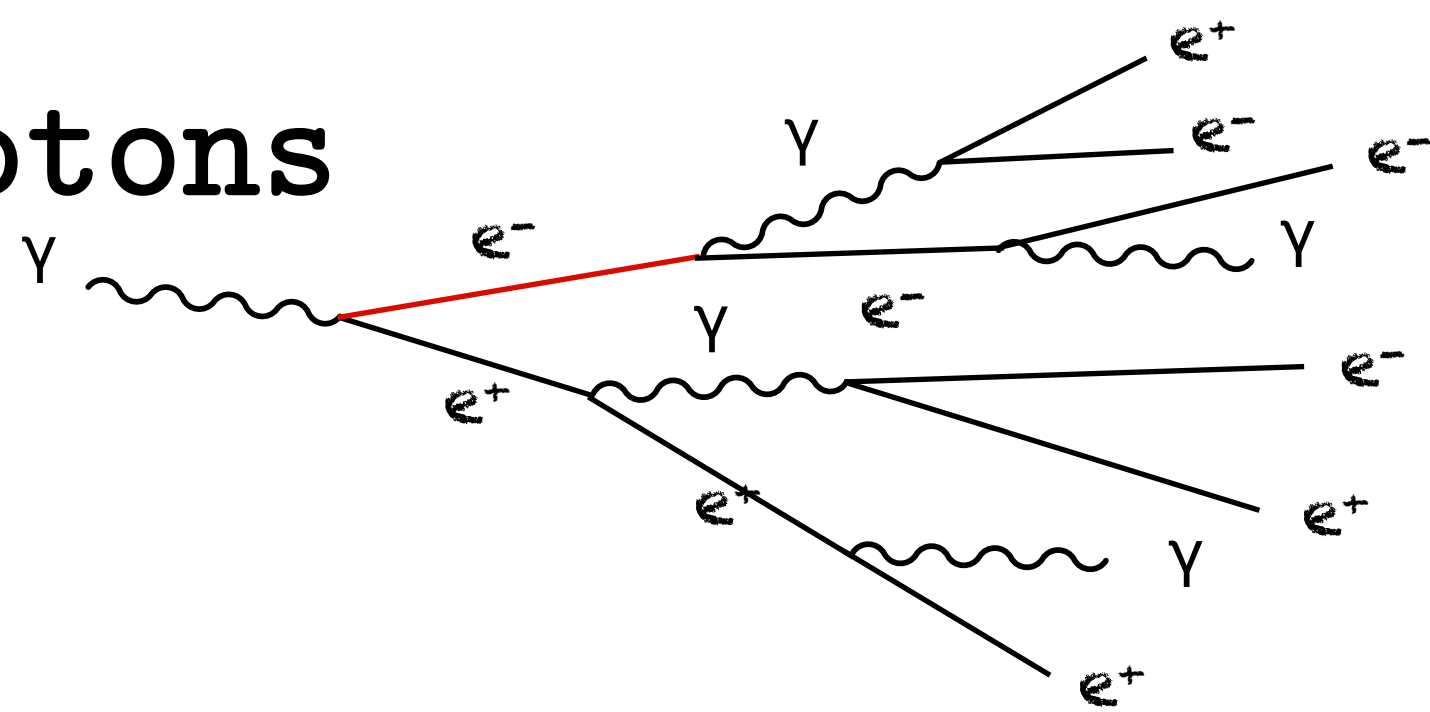
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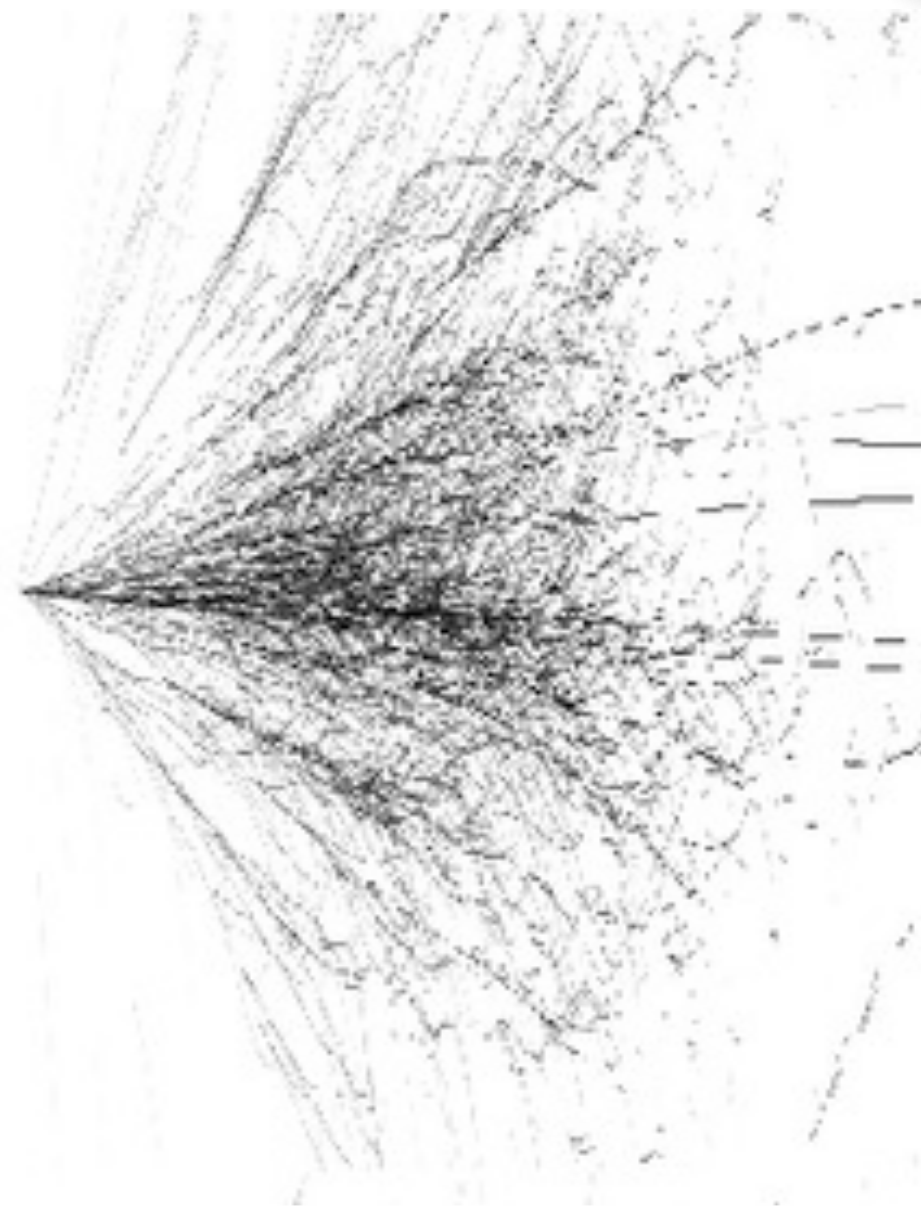
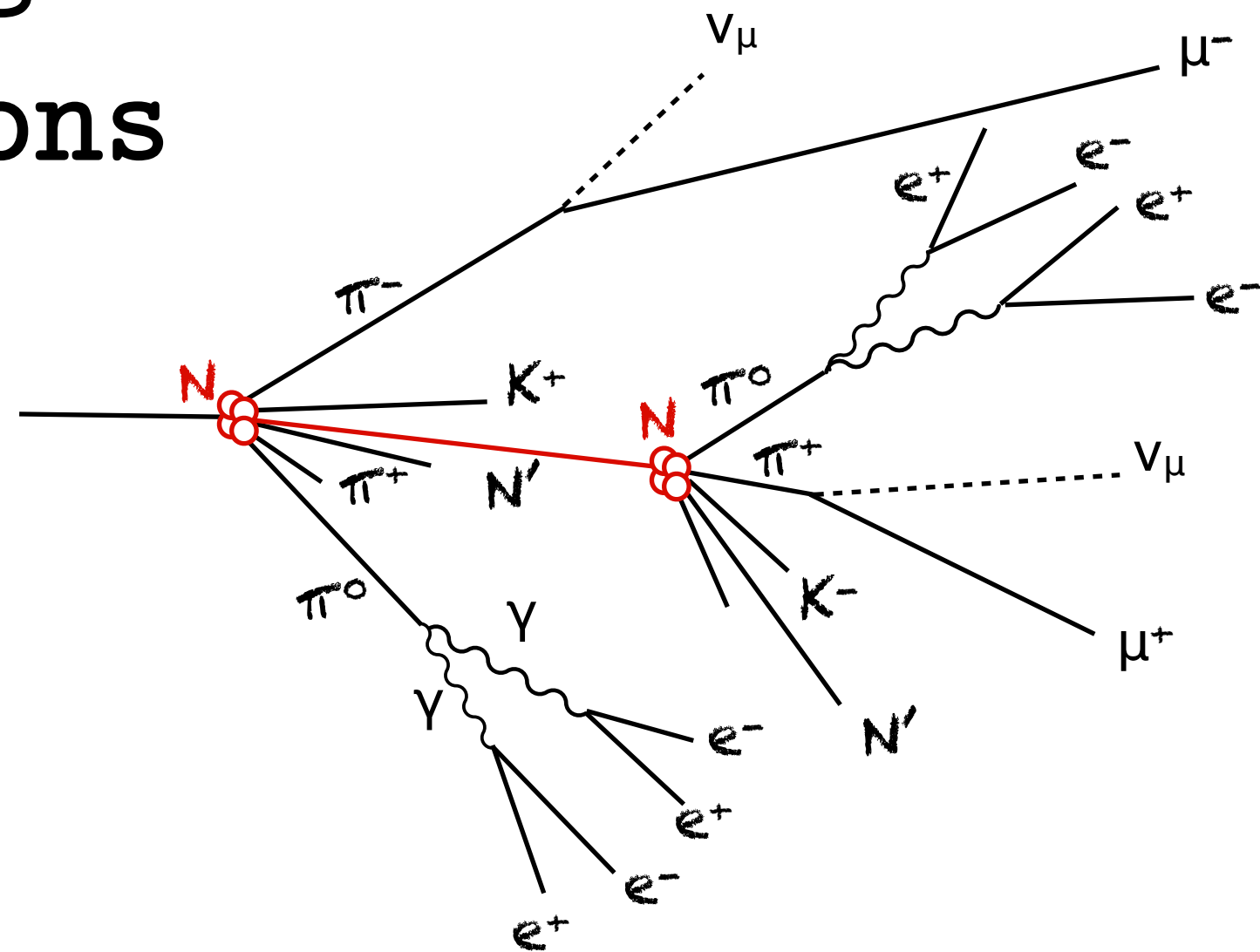
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Nuclear Interaction Length

- Collisions of hadrons with nuclei produce hadronic showers

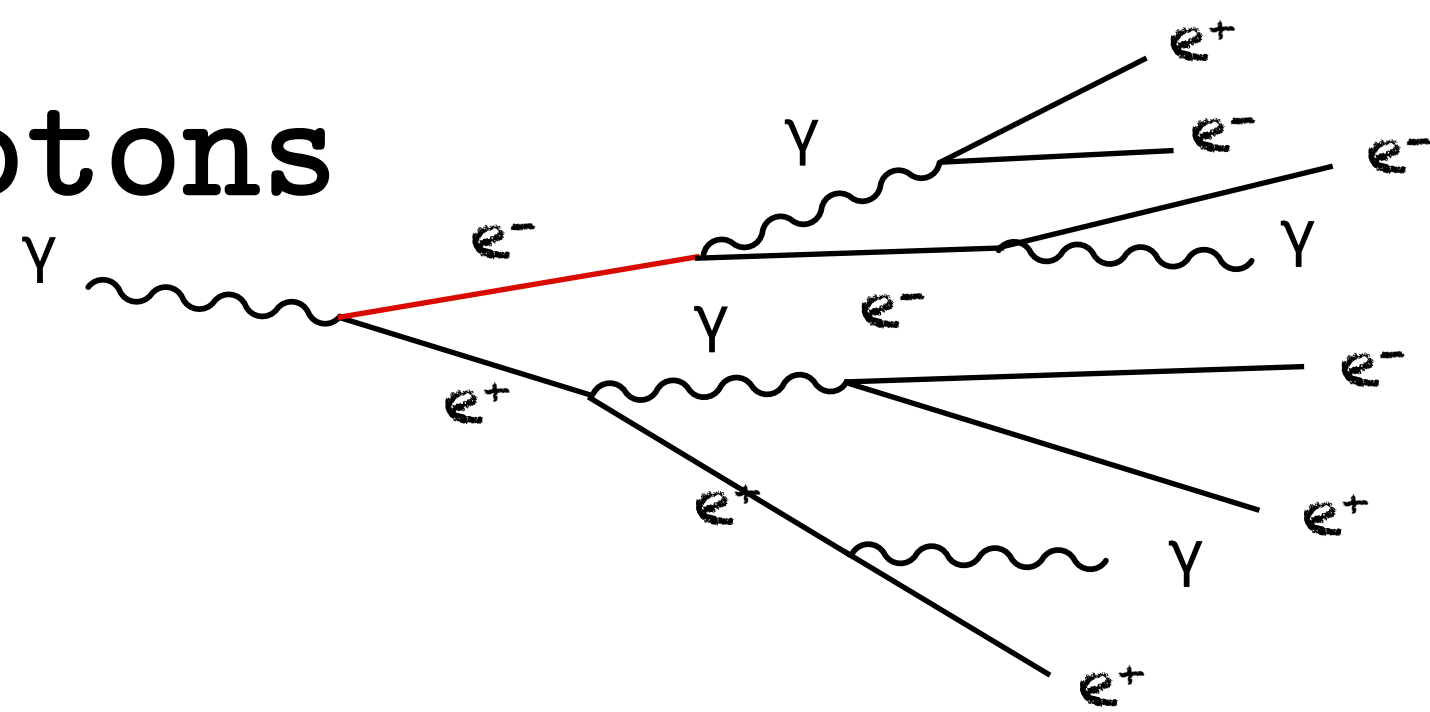
$$\lambda \approx 35 \text{ g cm}^{-2} A^{1/3}$$

- Nuclear interaction length much longer in high-Z materials than EM radiation length $\lambda > X_0$

- Hadronic showers develop later than EM showers; more diffuse

Example: Lead $\lambda = 17 \text{ cm}$

Electrons & Photons



See Jim Hirschauer's Lectures on Calorimetry

Radiation Length

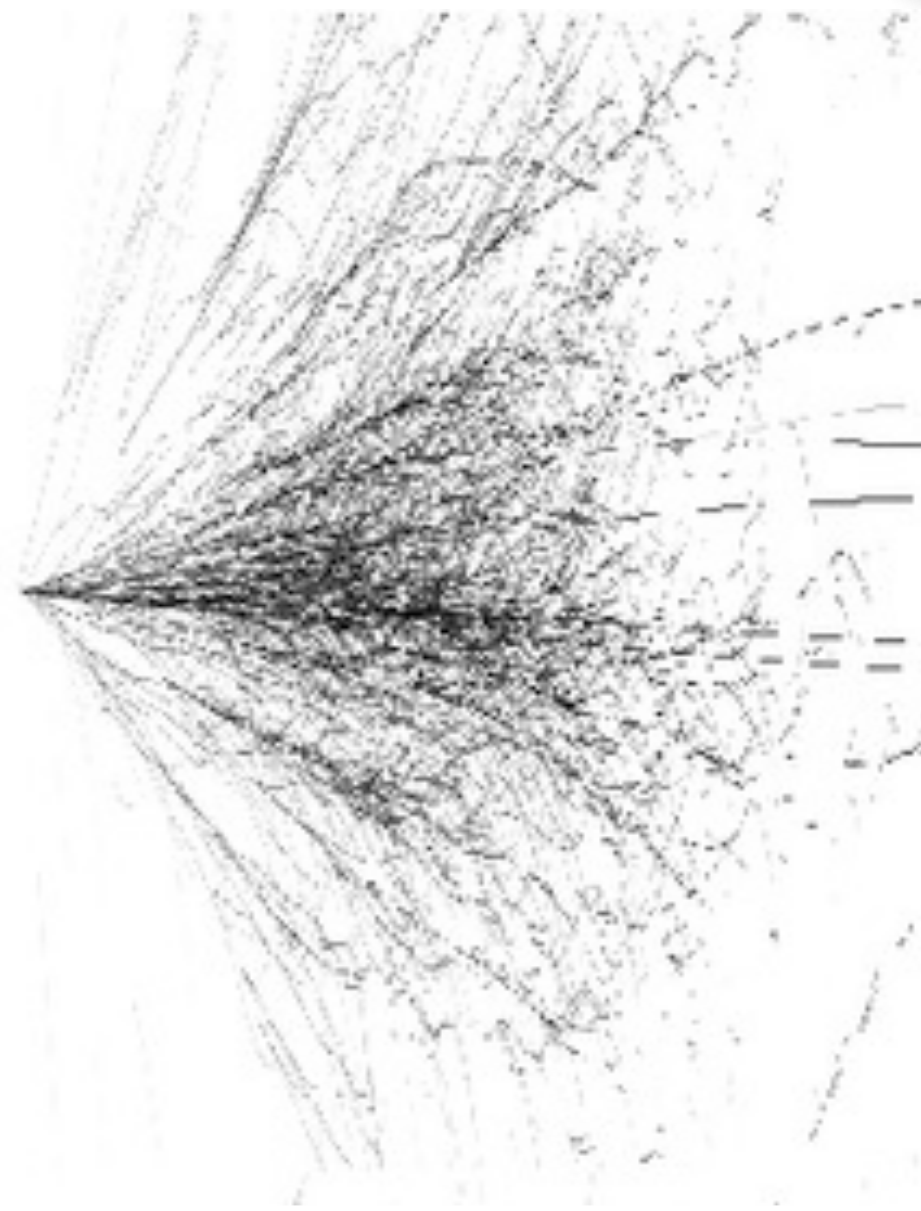
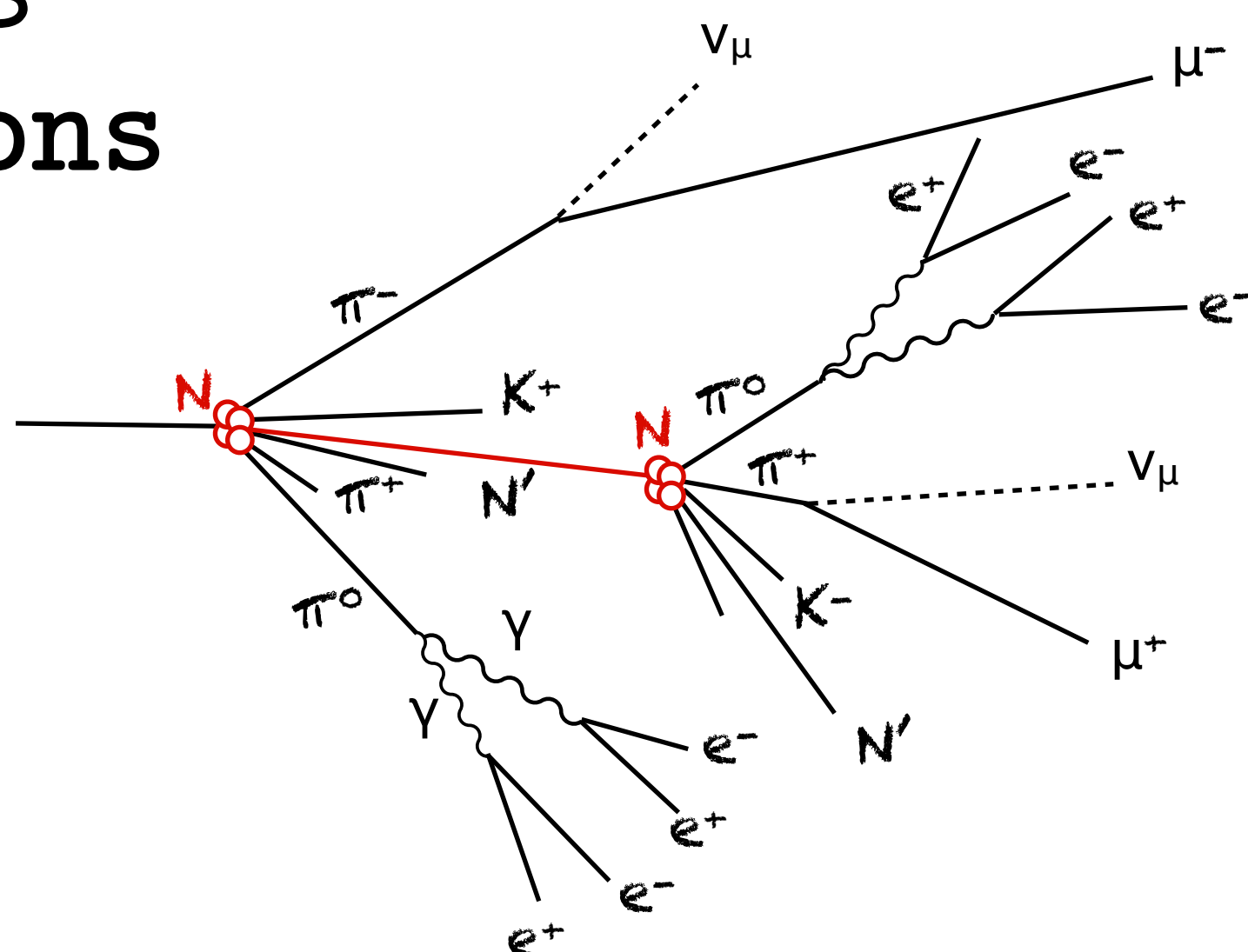
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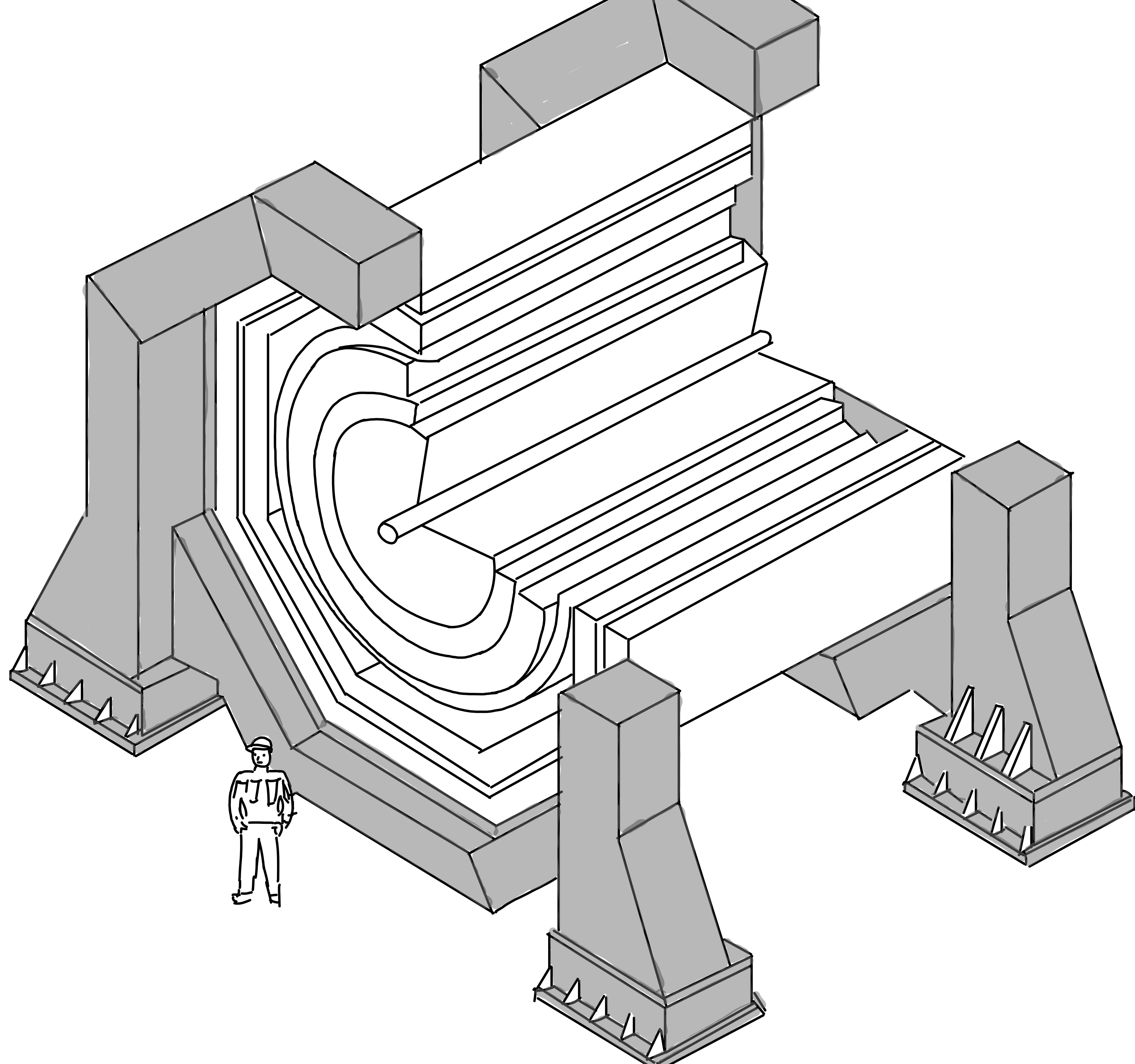
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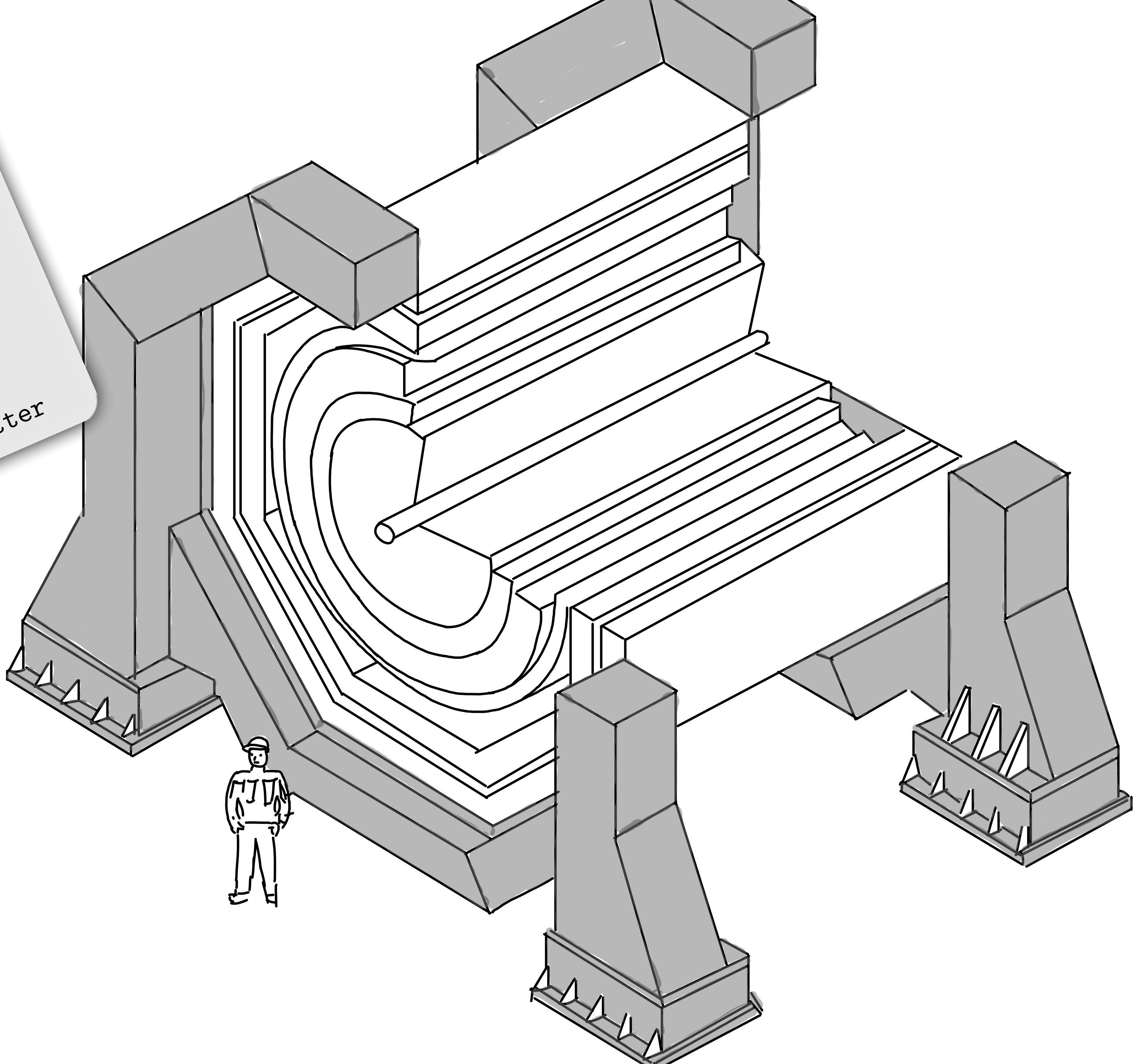
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Particle Detector

- Goal: completely surround collision by layering different types of instruments
- We know how particles interact with matter
 - in showering
 - interactions with matter
- Identify particles by exploiting differences

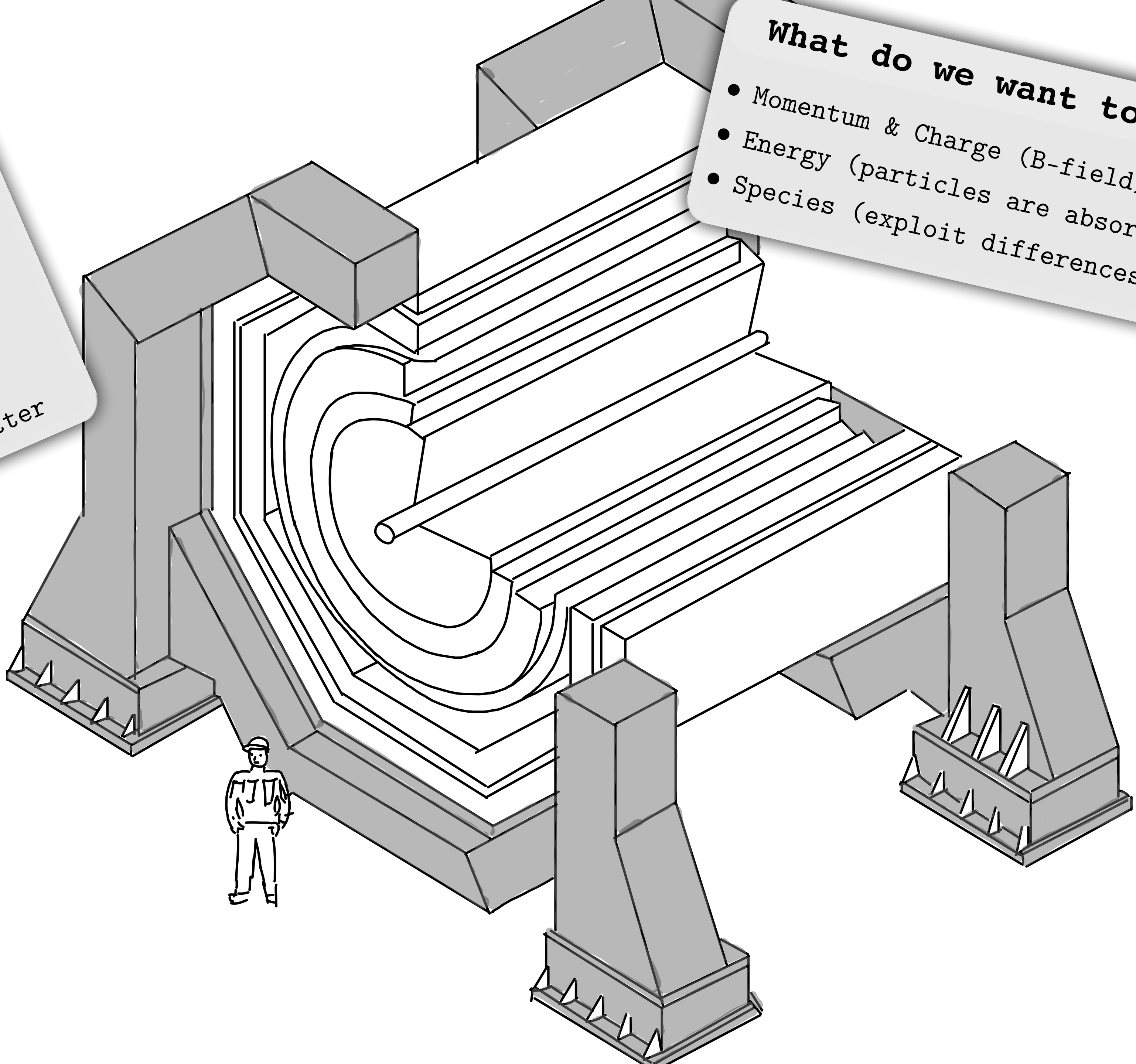


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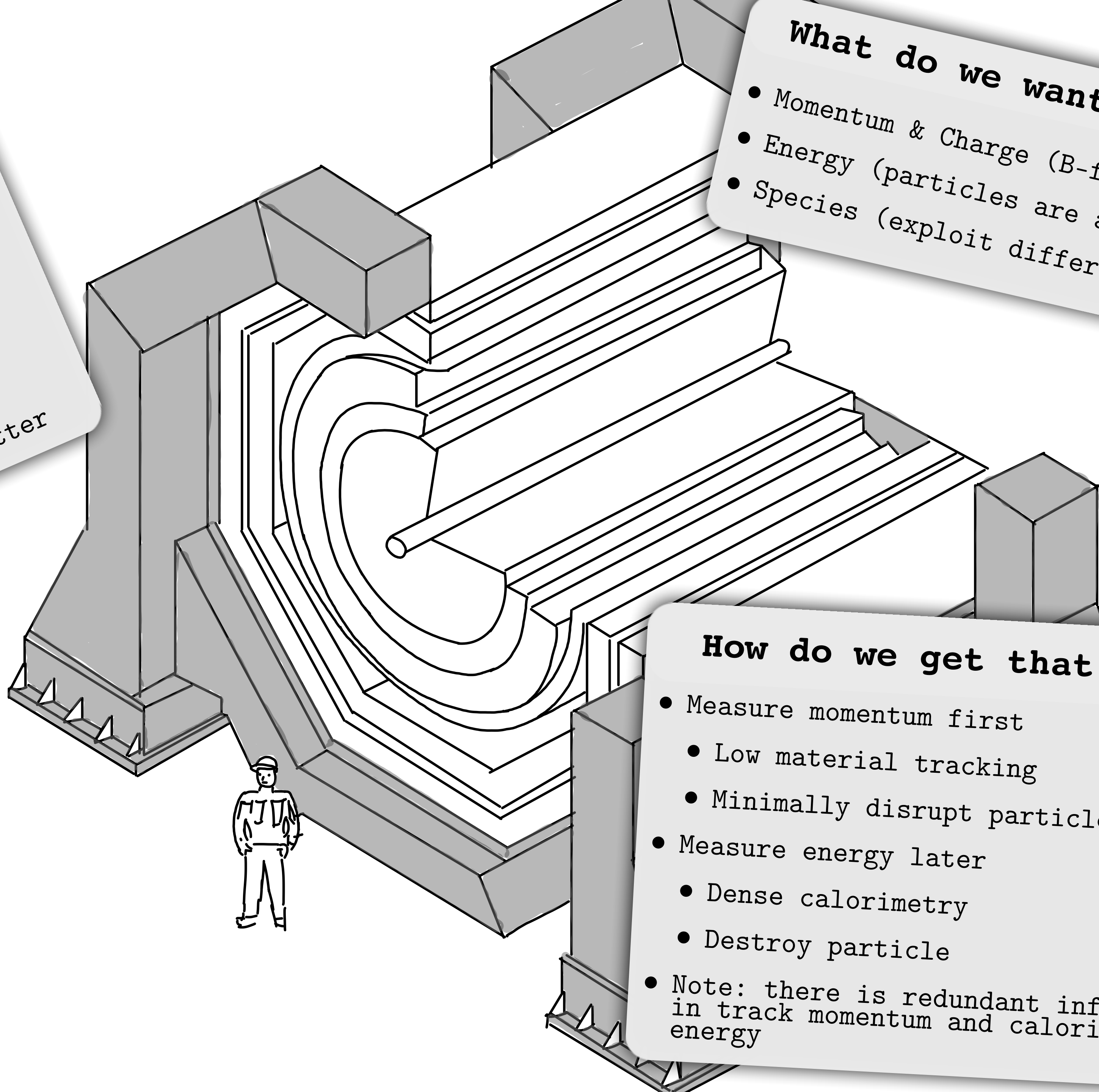
What do we want to know

- Momentum & Charge (B-field)
- Energy (particles are absorbed)
- Species (exploit differences)



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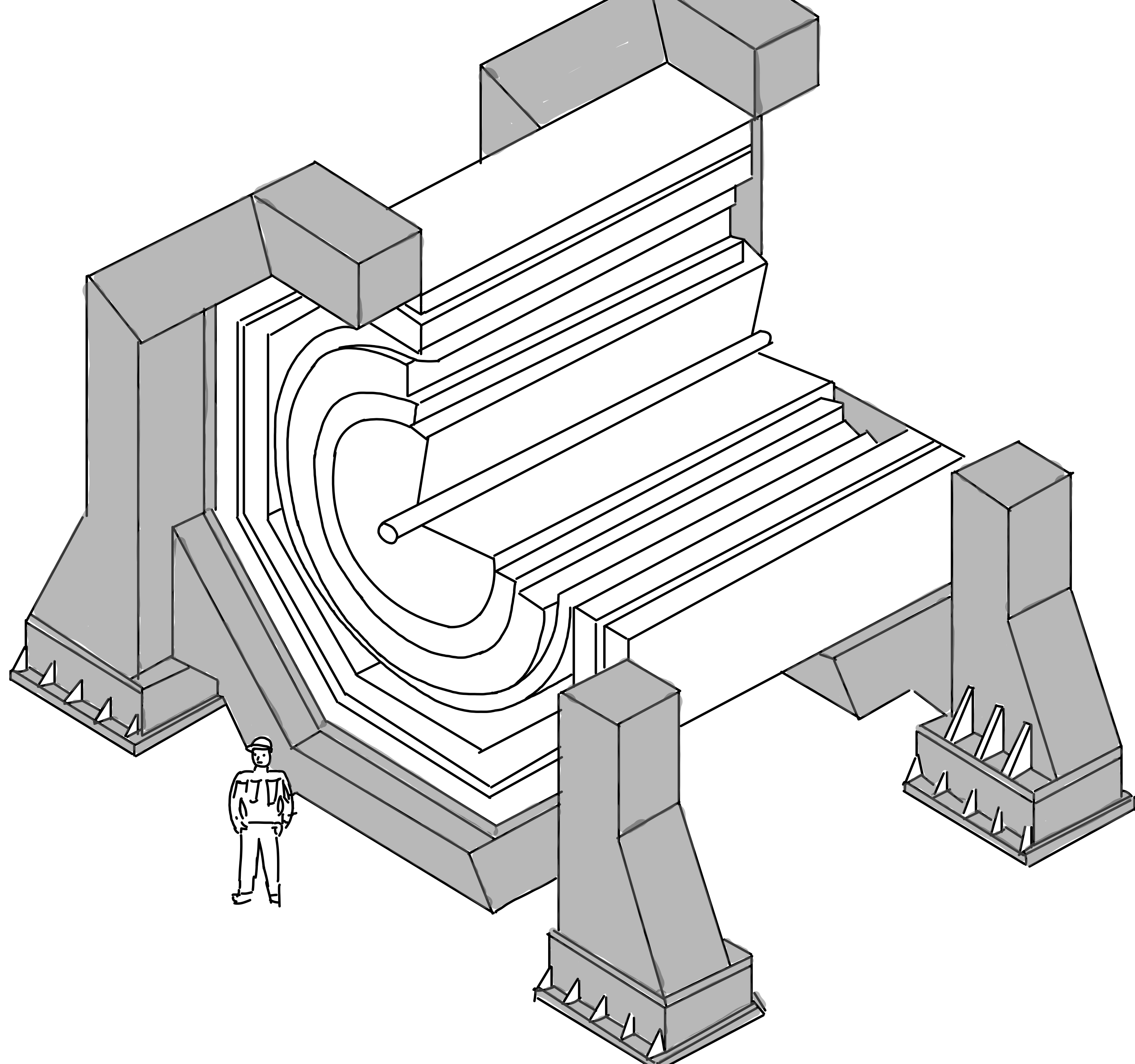


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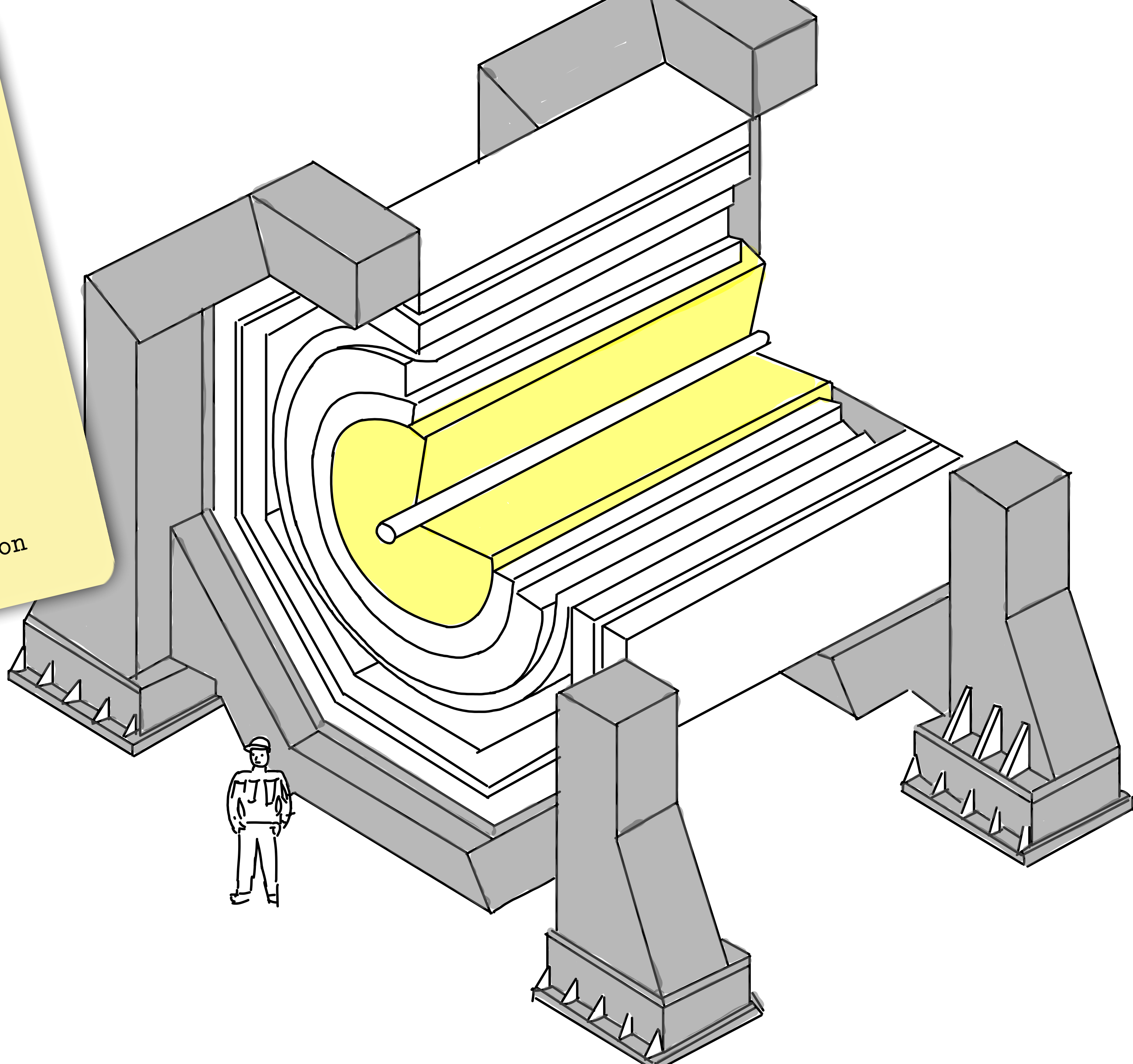
How do we get that info?

- Measure momentum first
 - Low material tracking
 - Minimally disrupt particle
- Measure energy later
 - Dense calorimetry
 - Destroy particle
- Note: there is redundant information in track momentum and calorimeter energy



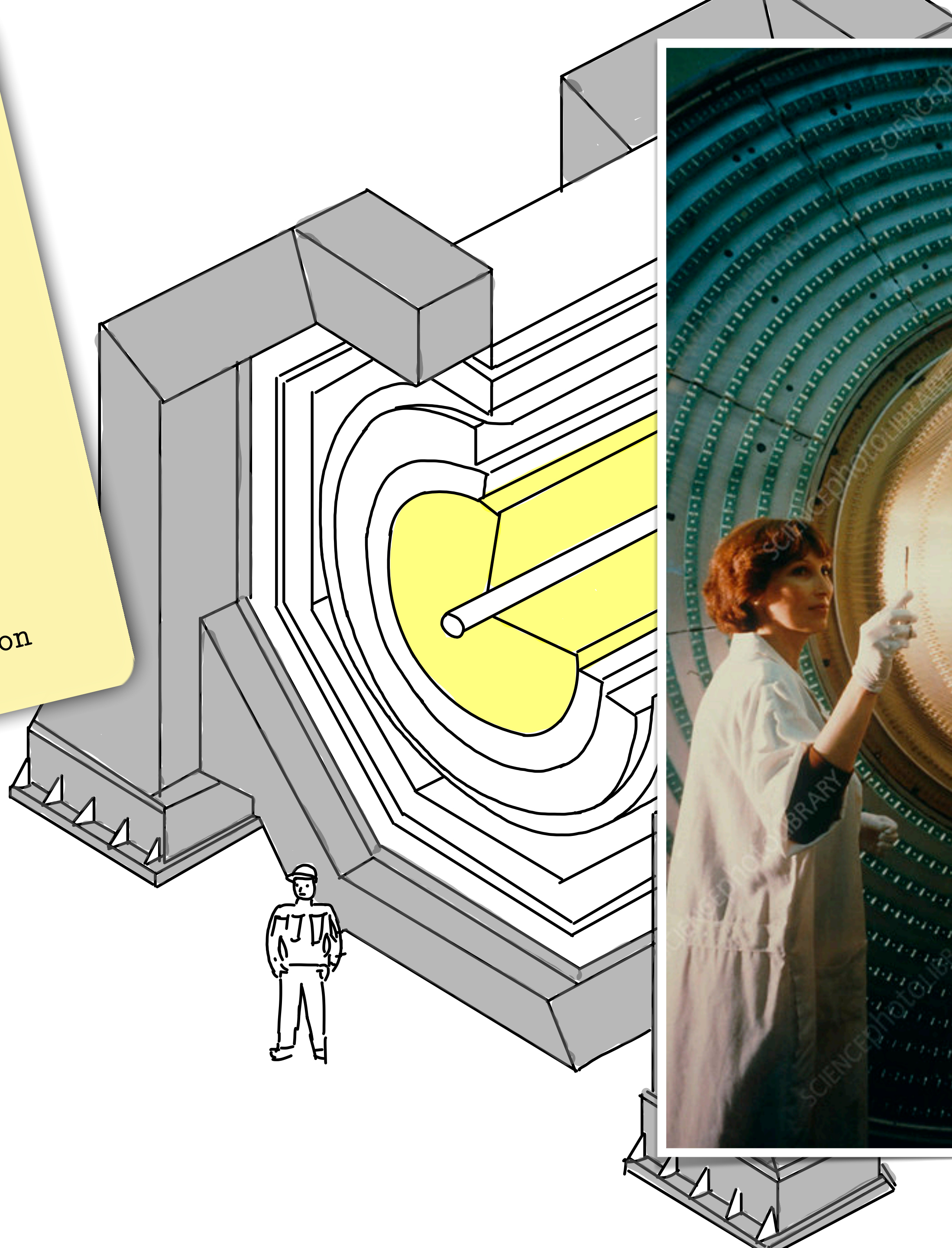
Inner Tracking Detectors

- Purpose: measure momentum and charge of charged particles
- Minimise multiple scattering
- Use as little material as possible
- Two main technologies:
 - Gas/wire drift chambers
 - Low material budget
 - worse momentum resolution
 - slower
 - Solid-state (silicon)
 - more material
 - better momentum resolution
 - faster



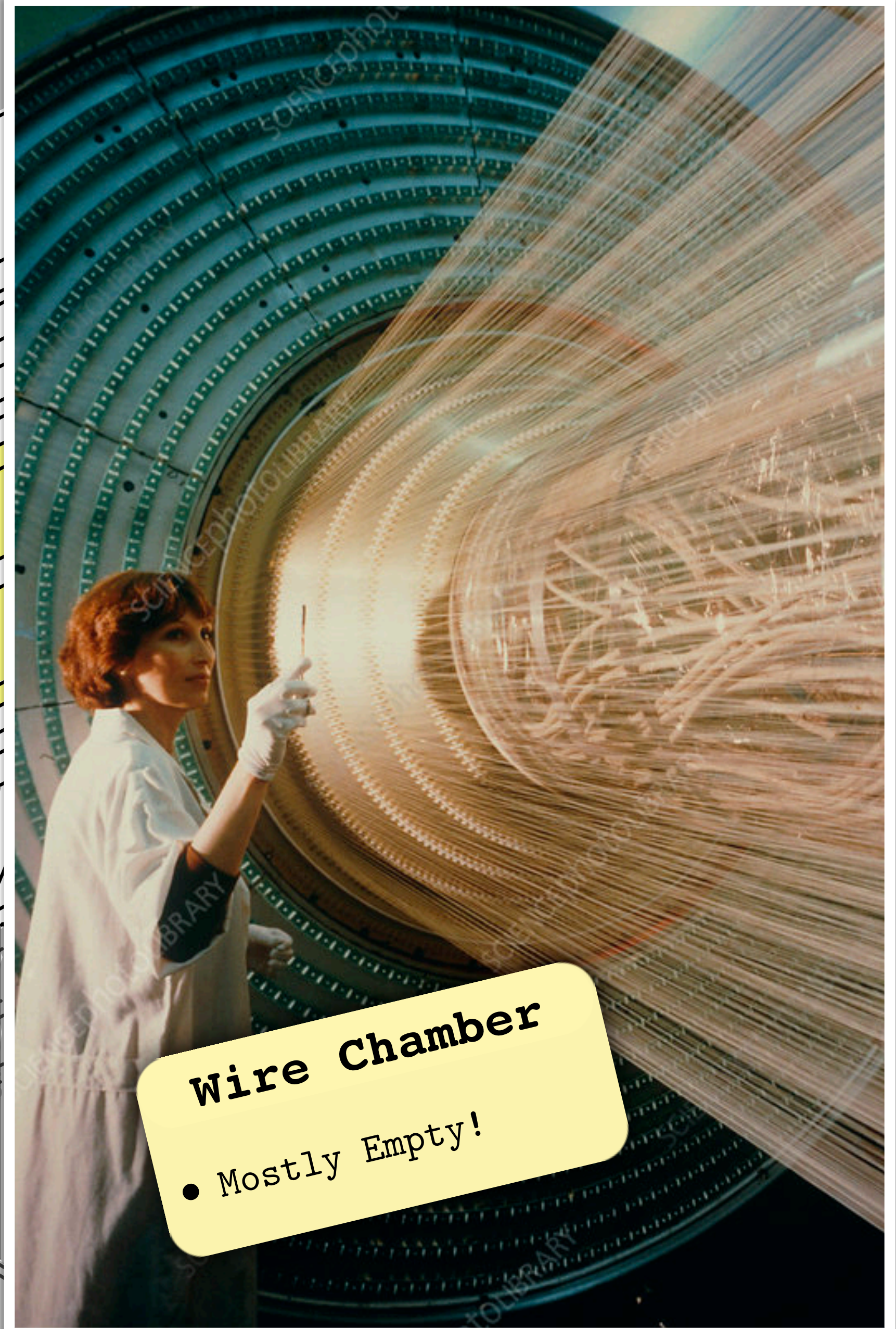
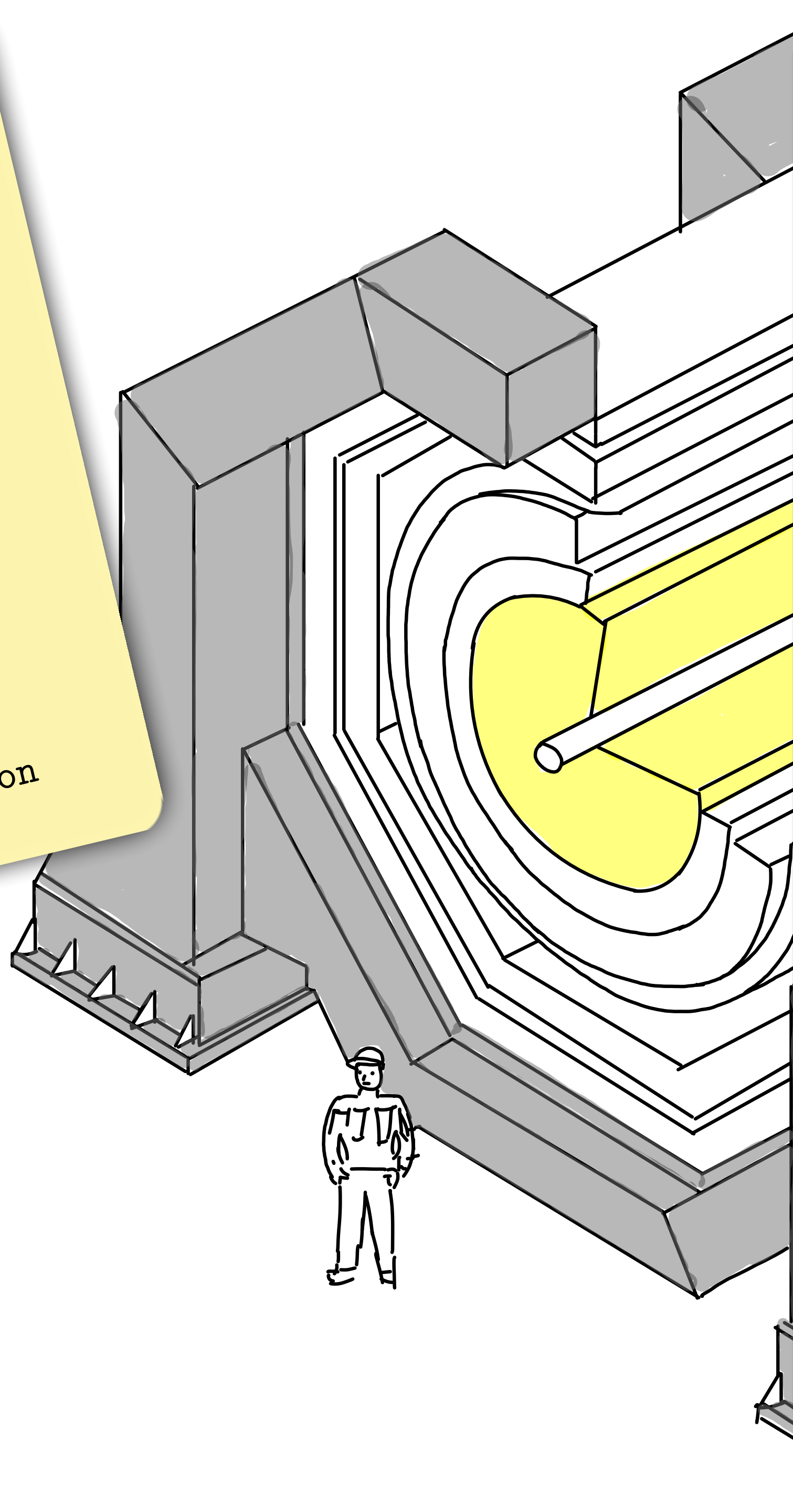
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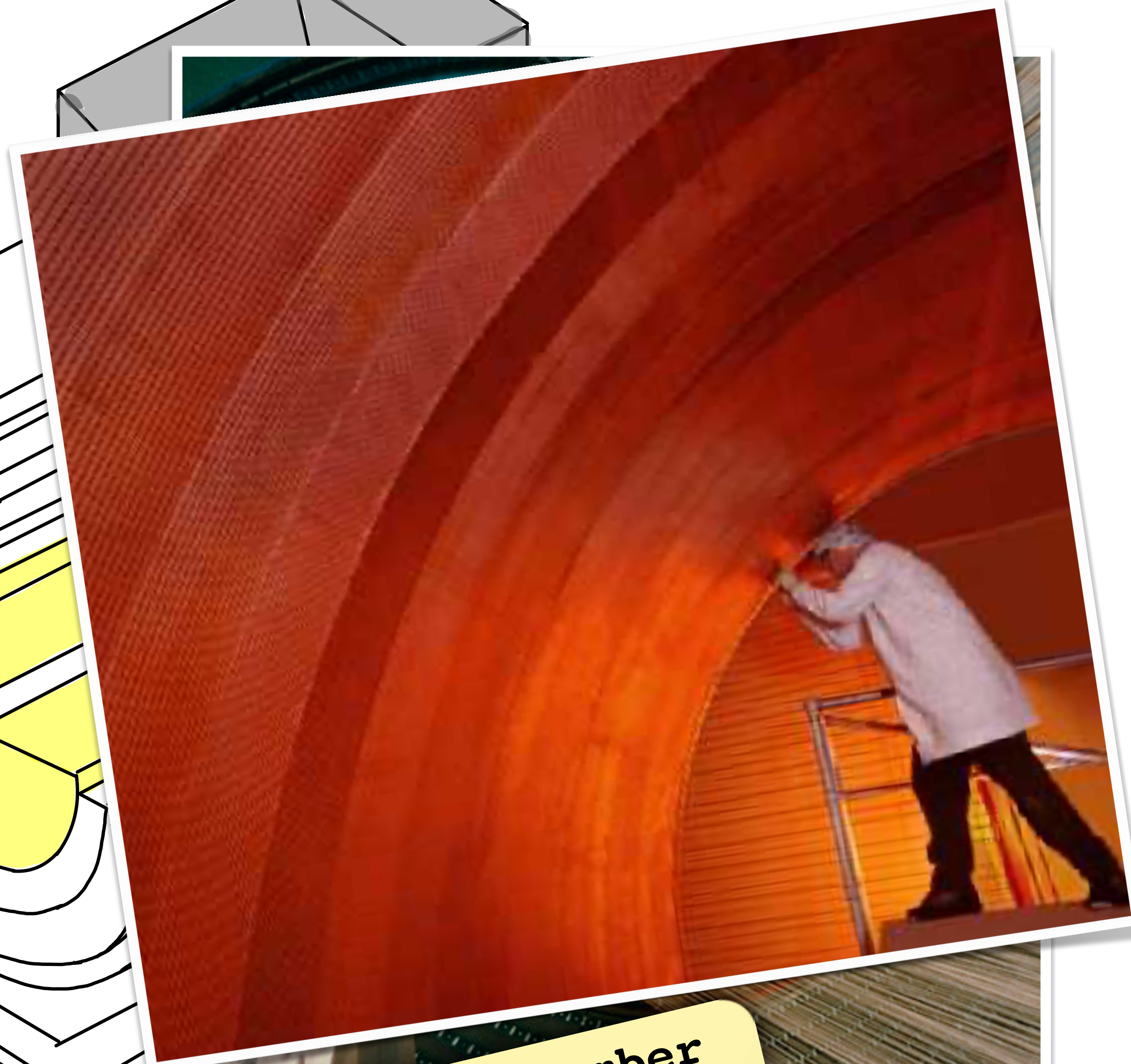
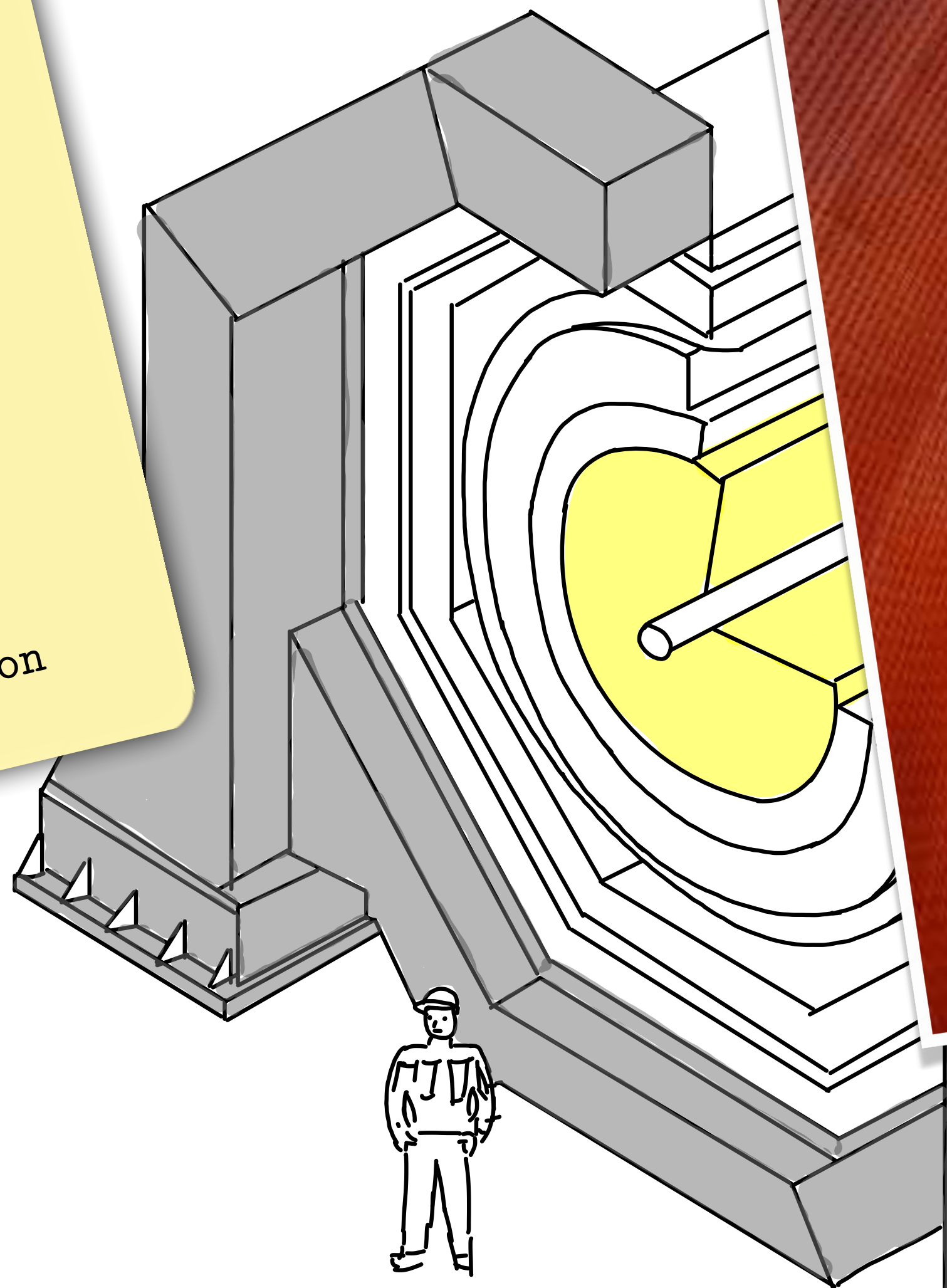


Wire Chamber

- Mostly Empty!

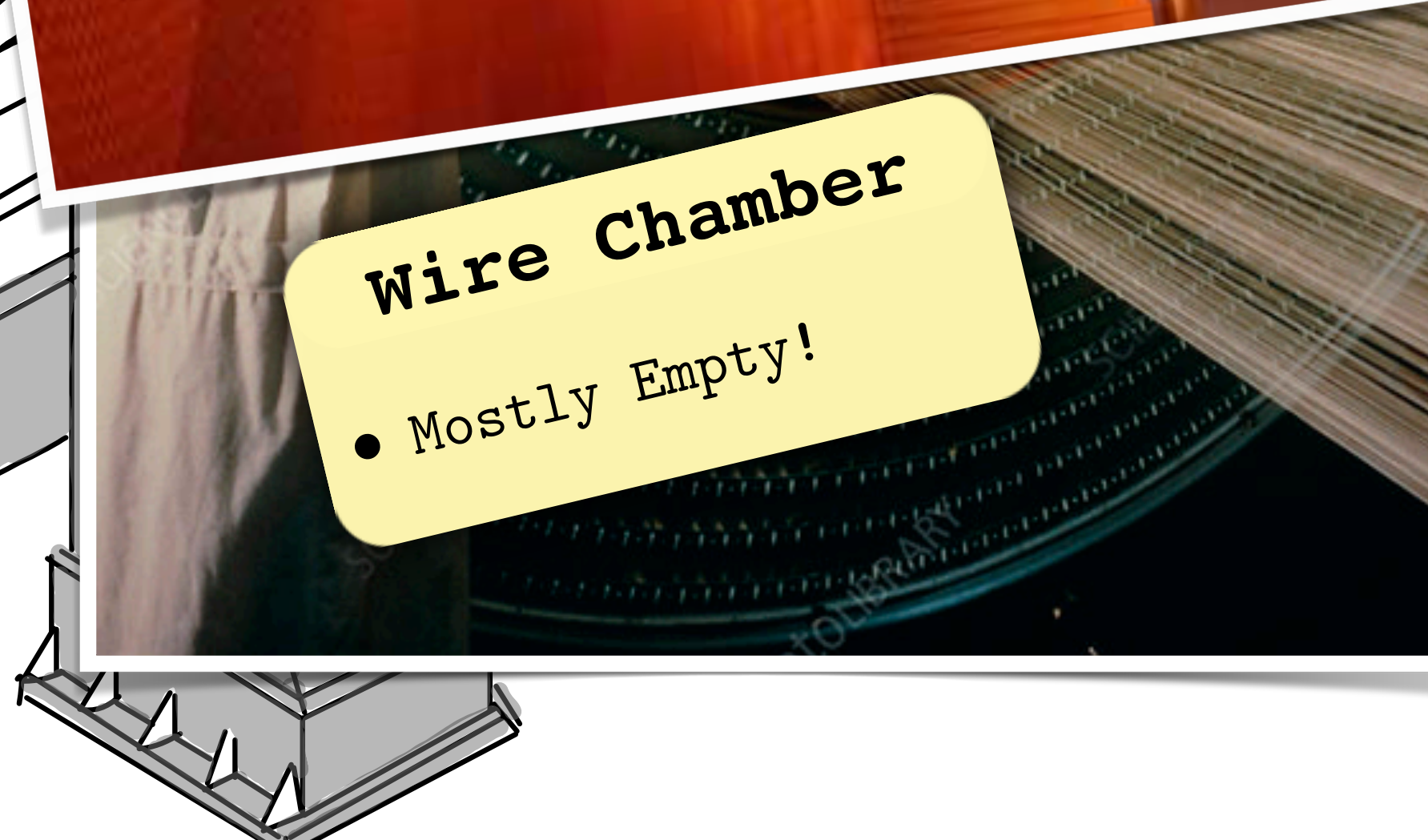
Inner Tracking Detectors

- Purpose: measure momentum and charge of charged particles
- Minimise multiple scattering
- Use as little material as possible
- Two main technologies:
 - Gas/wire drift chambers
 - Solid-state (silicon)
- Low material budget
worse momentum resolution
slower
- more material
better momentum resolution
faster



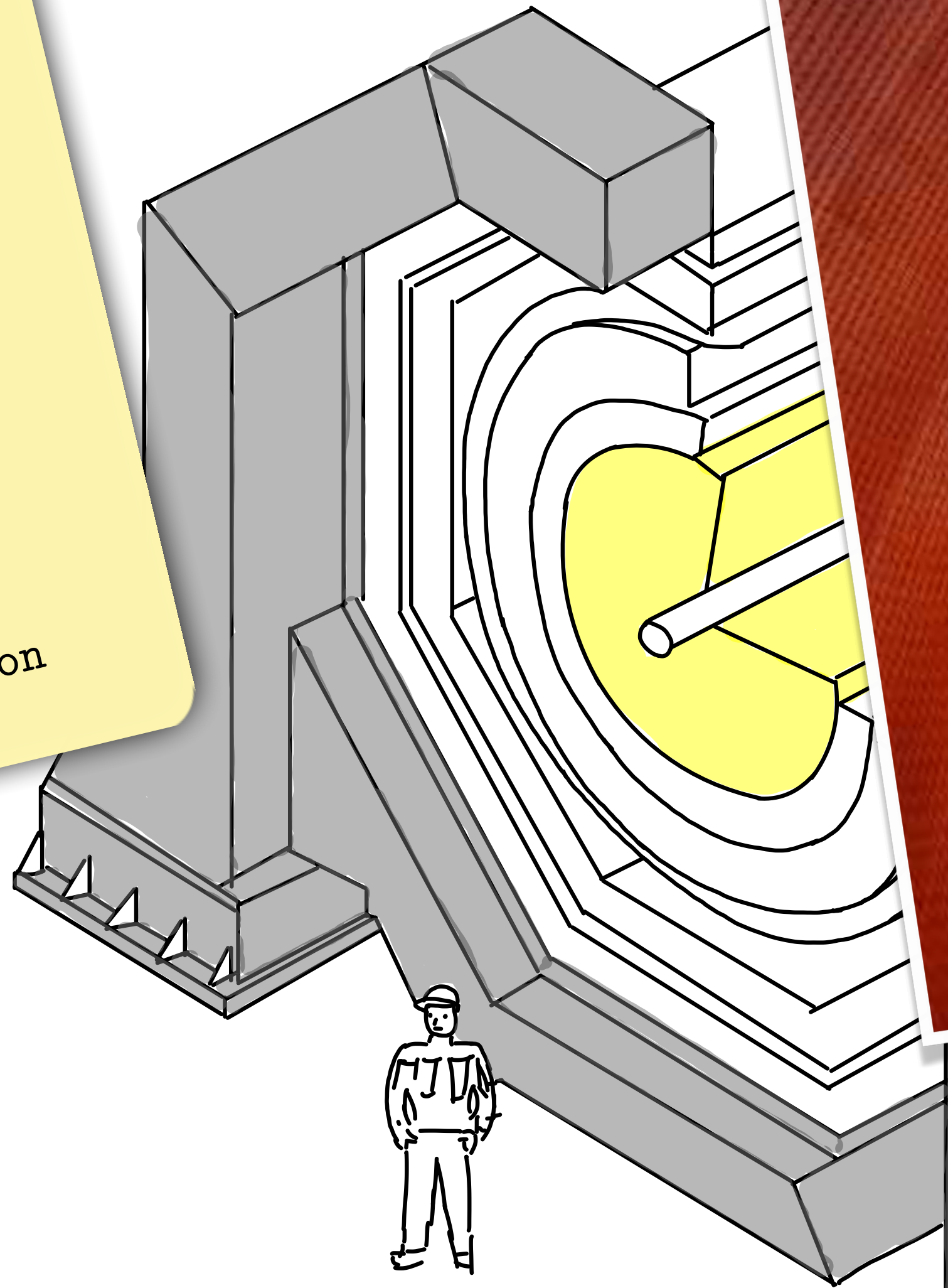
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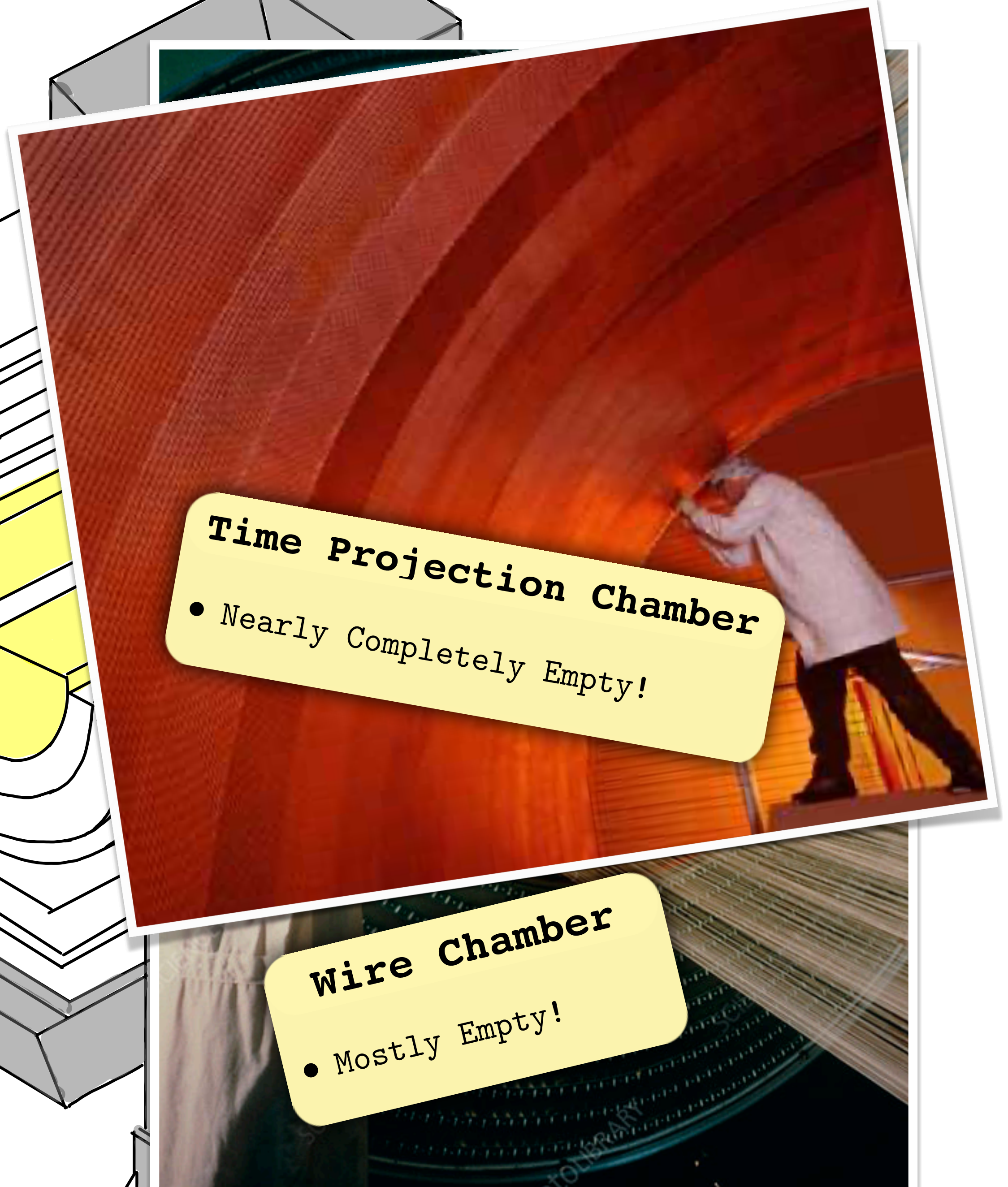


Time Projection Chamber

- Nearly Completely Empty!

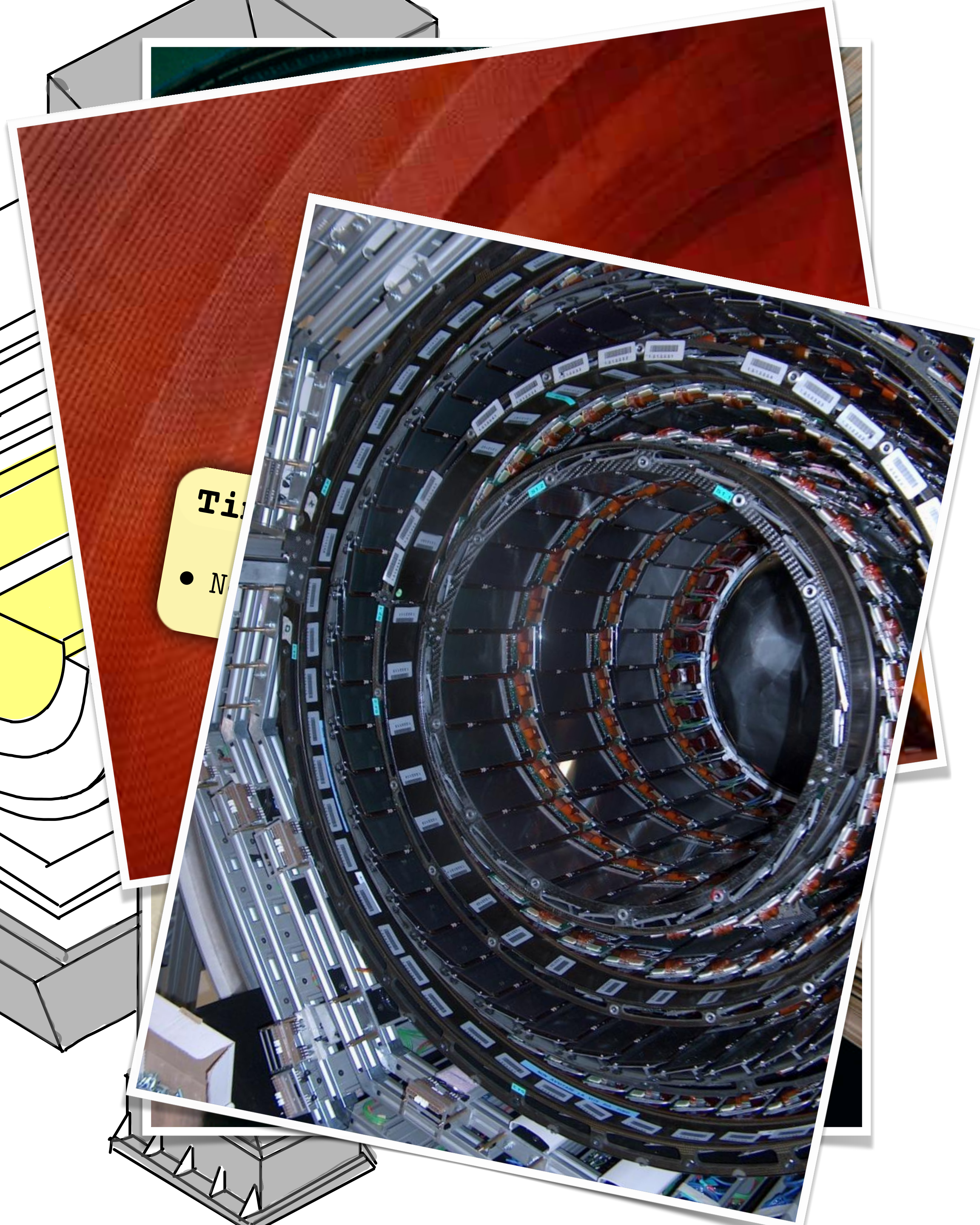
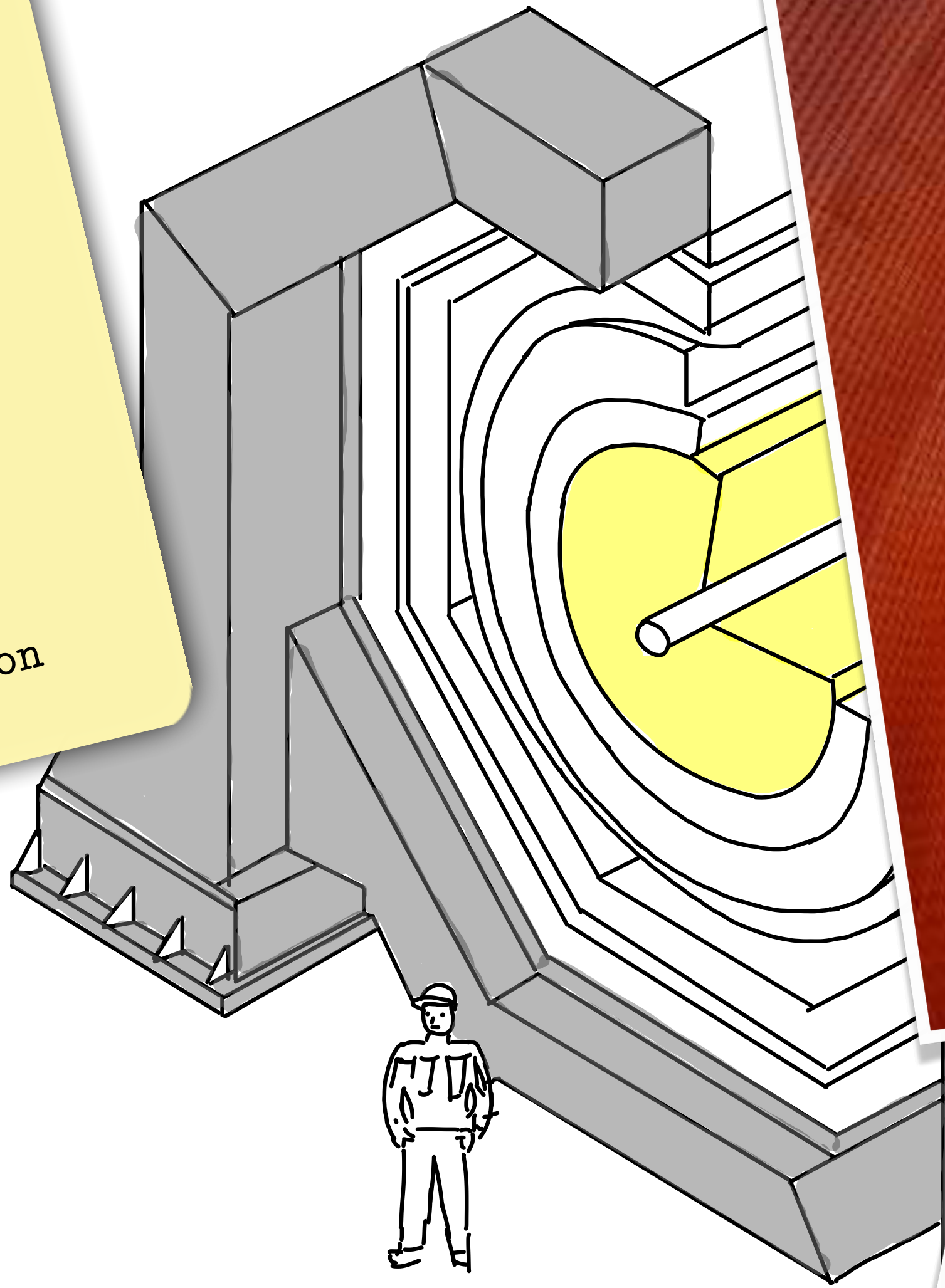
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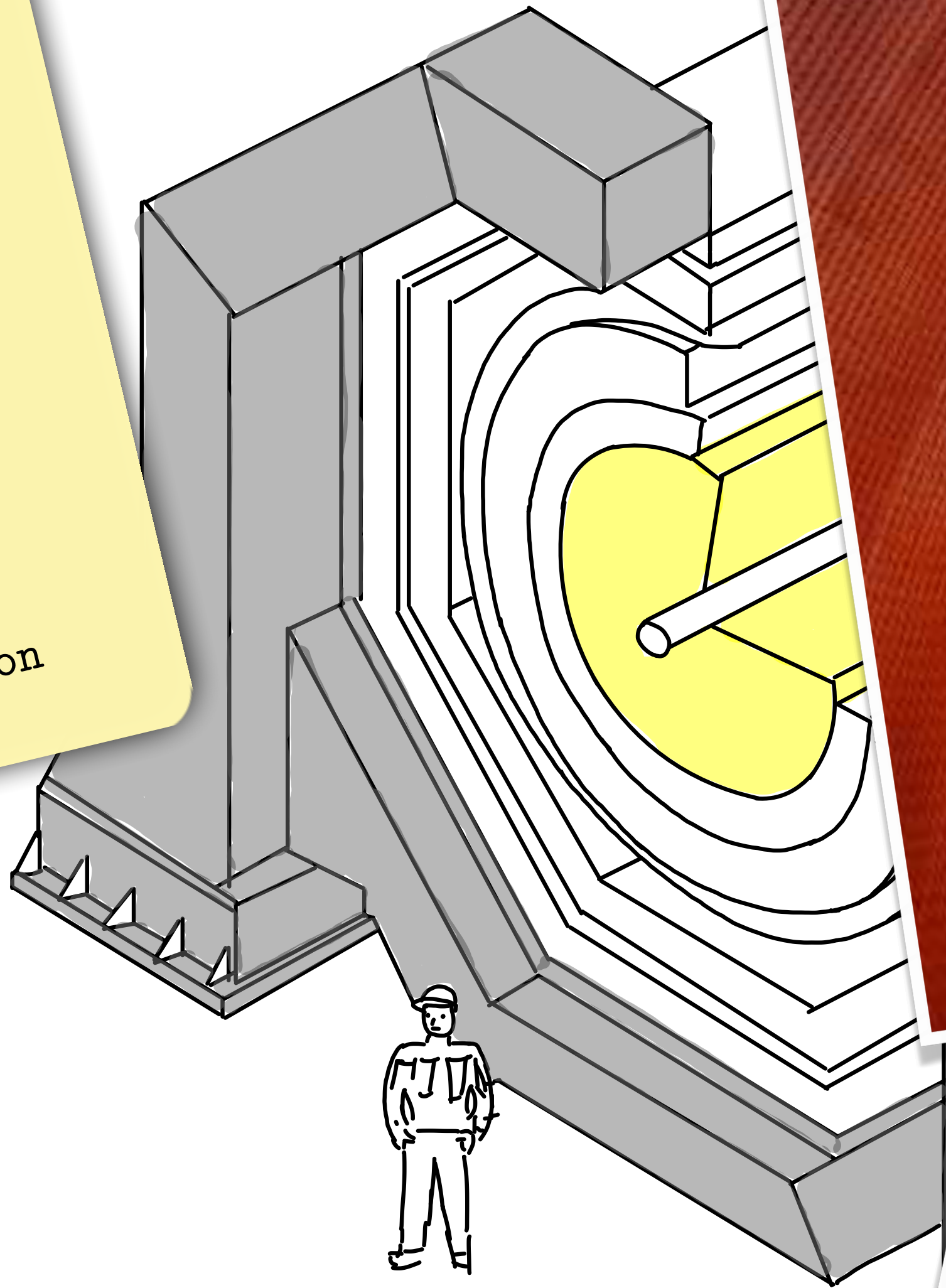


Ti

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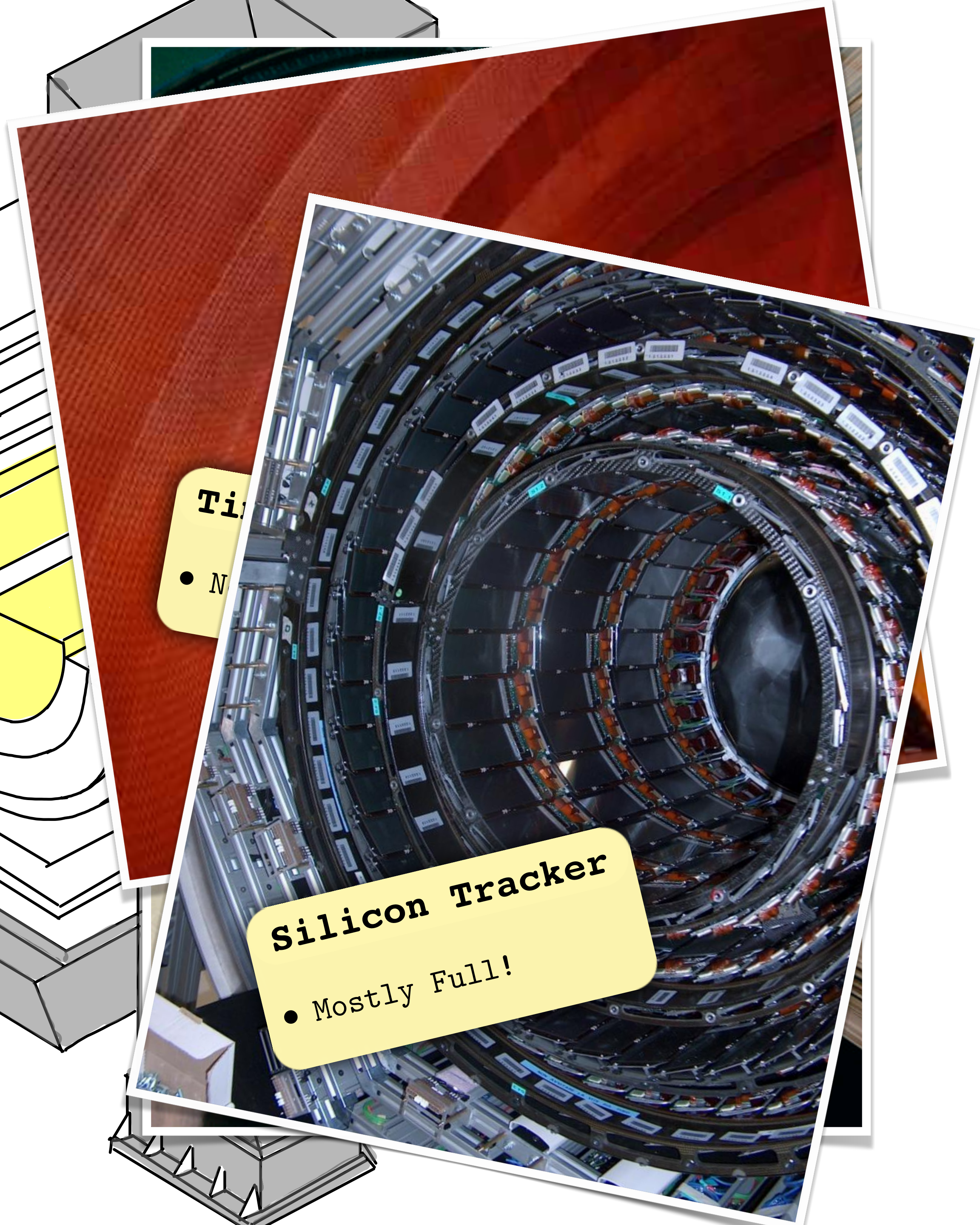


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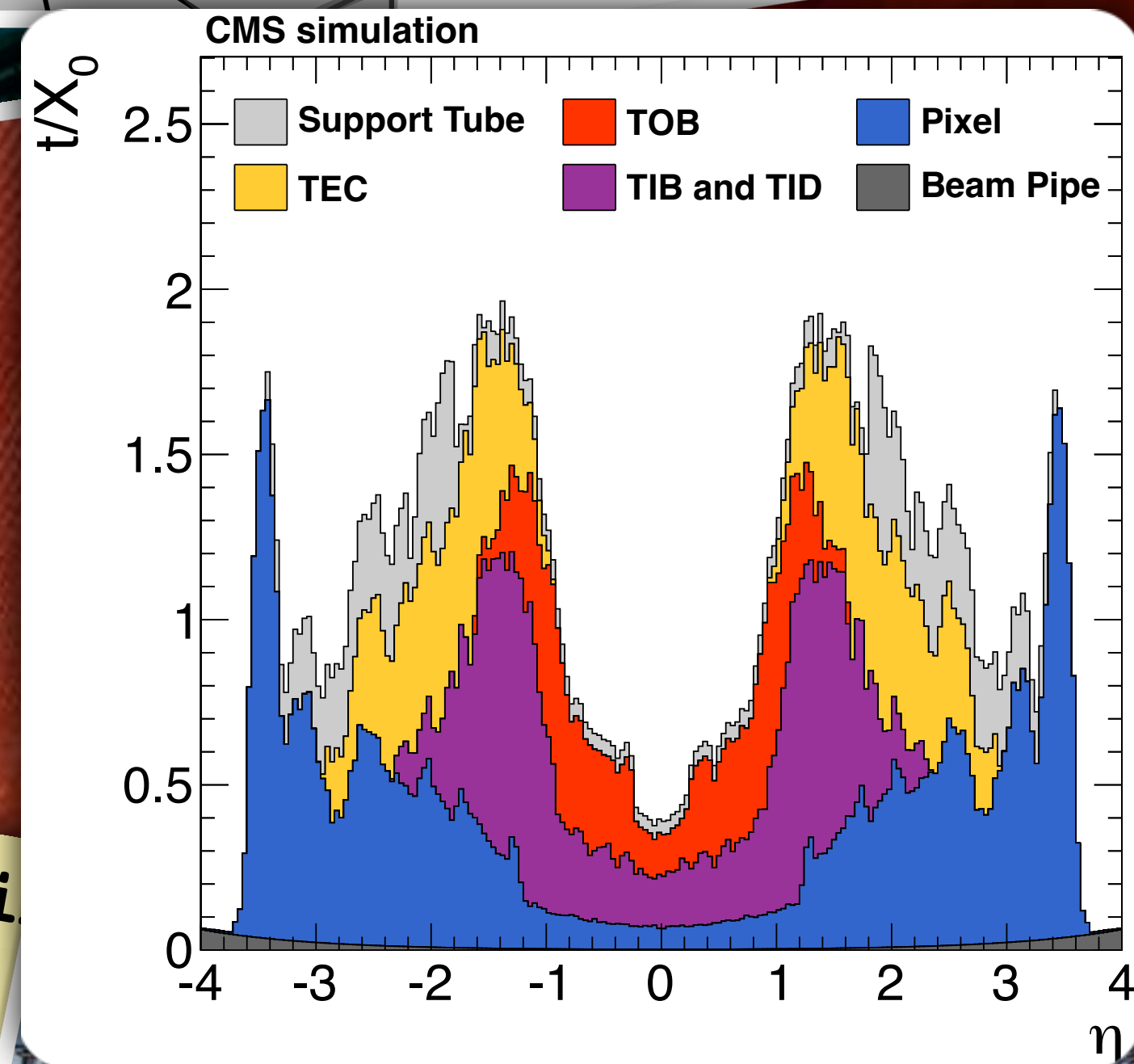
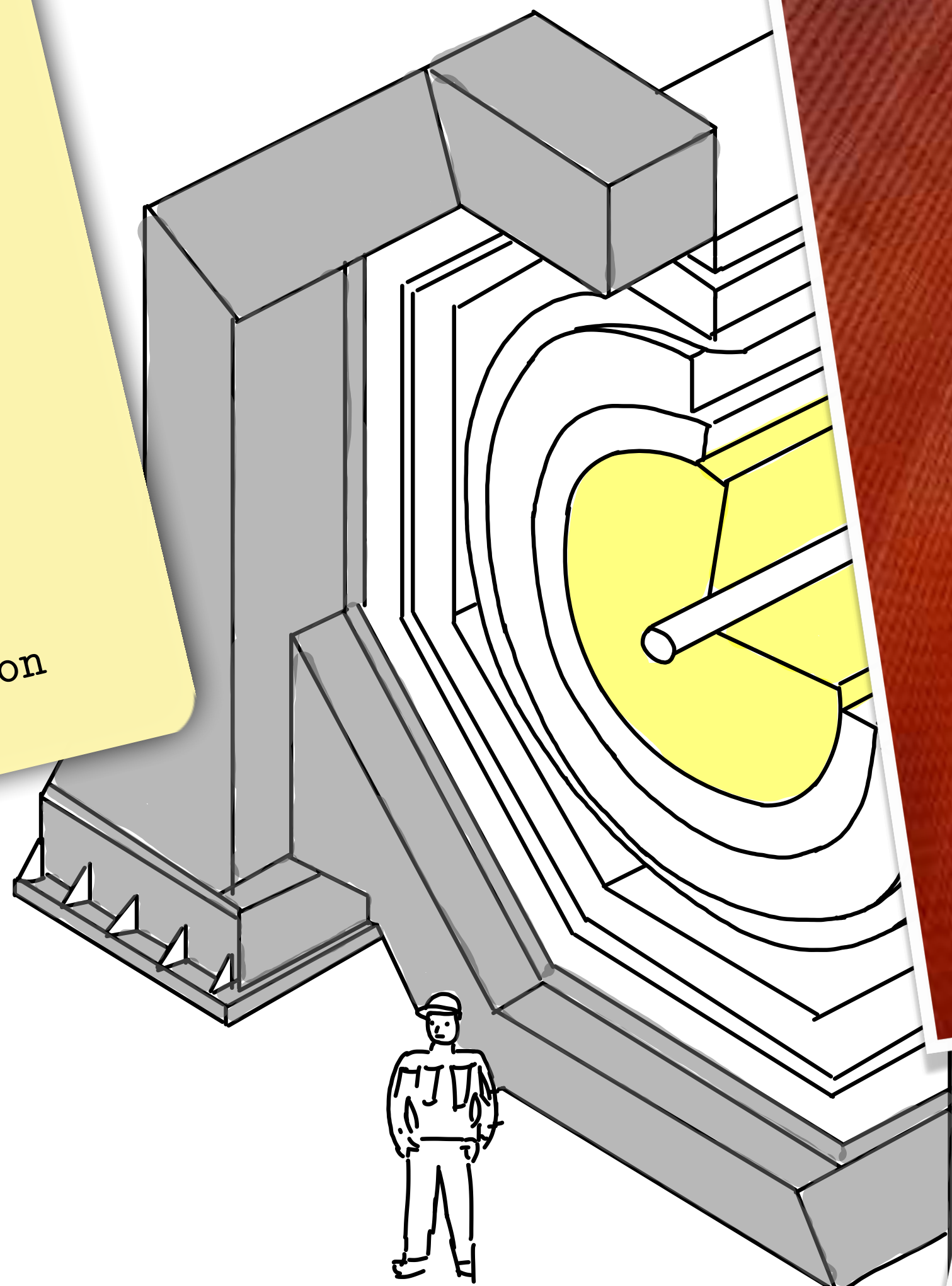
Silicon Tracker

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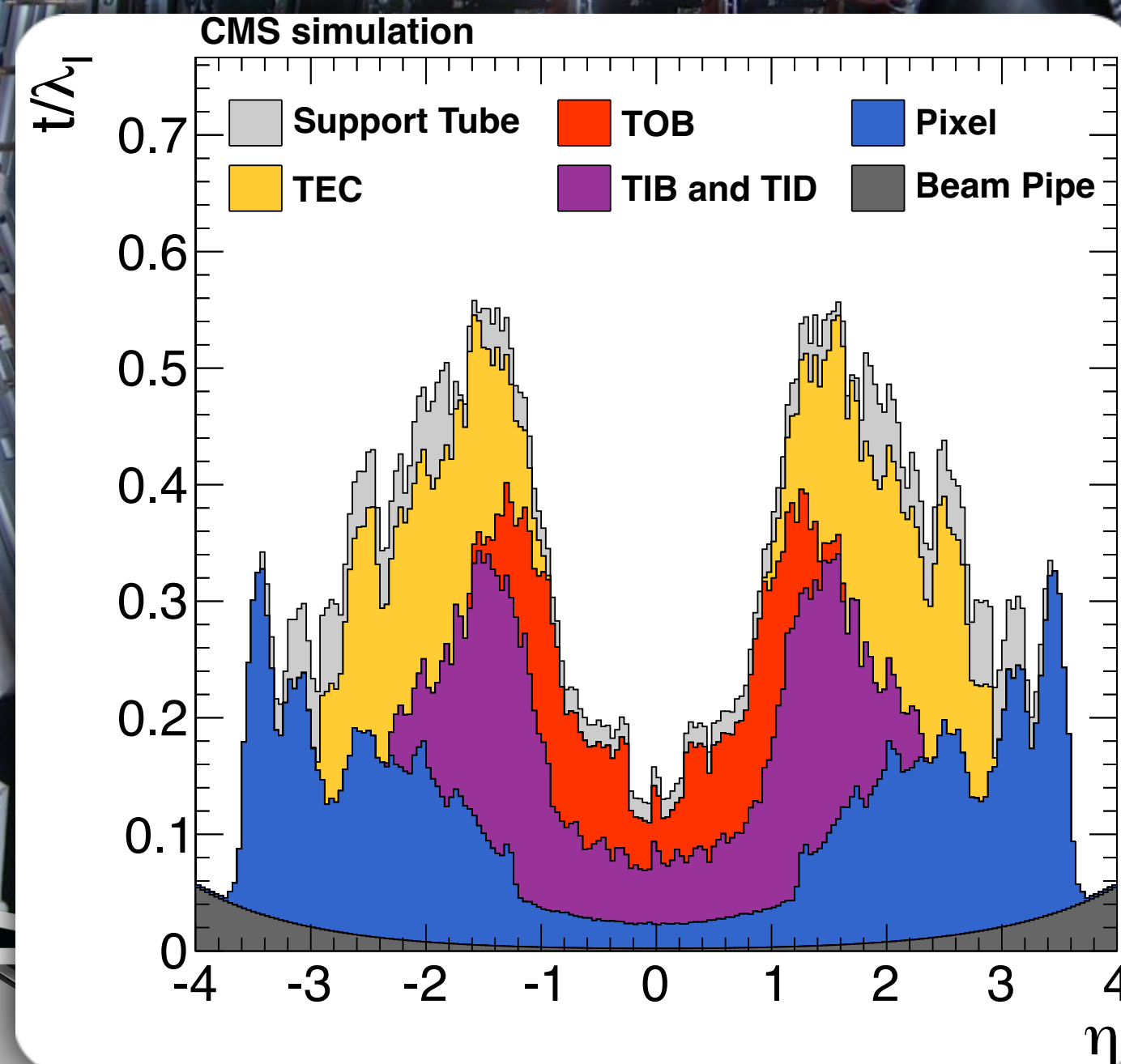
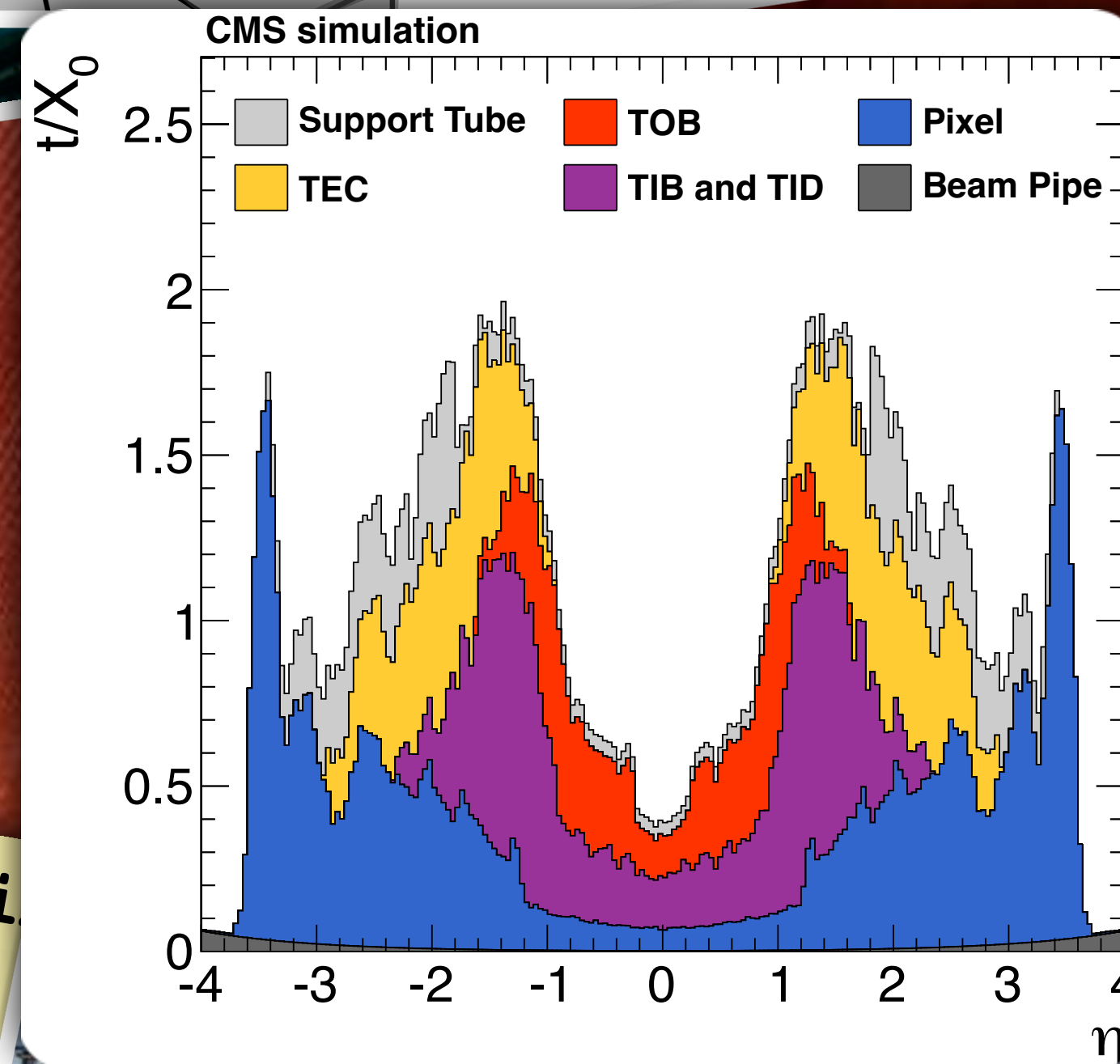
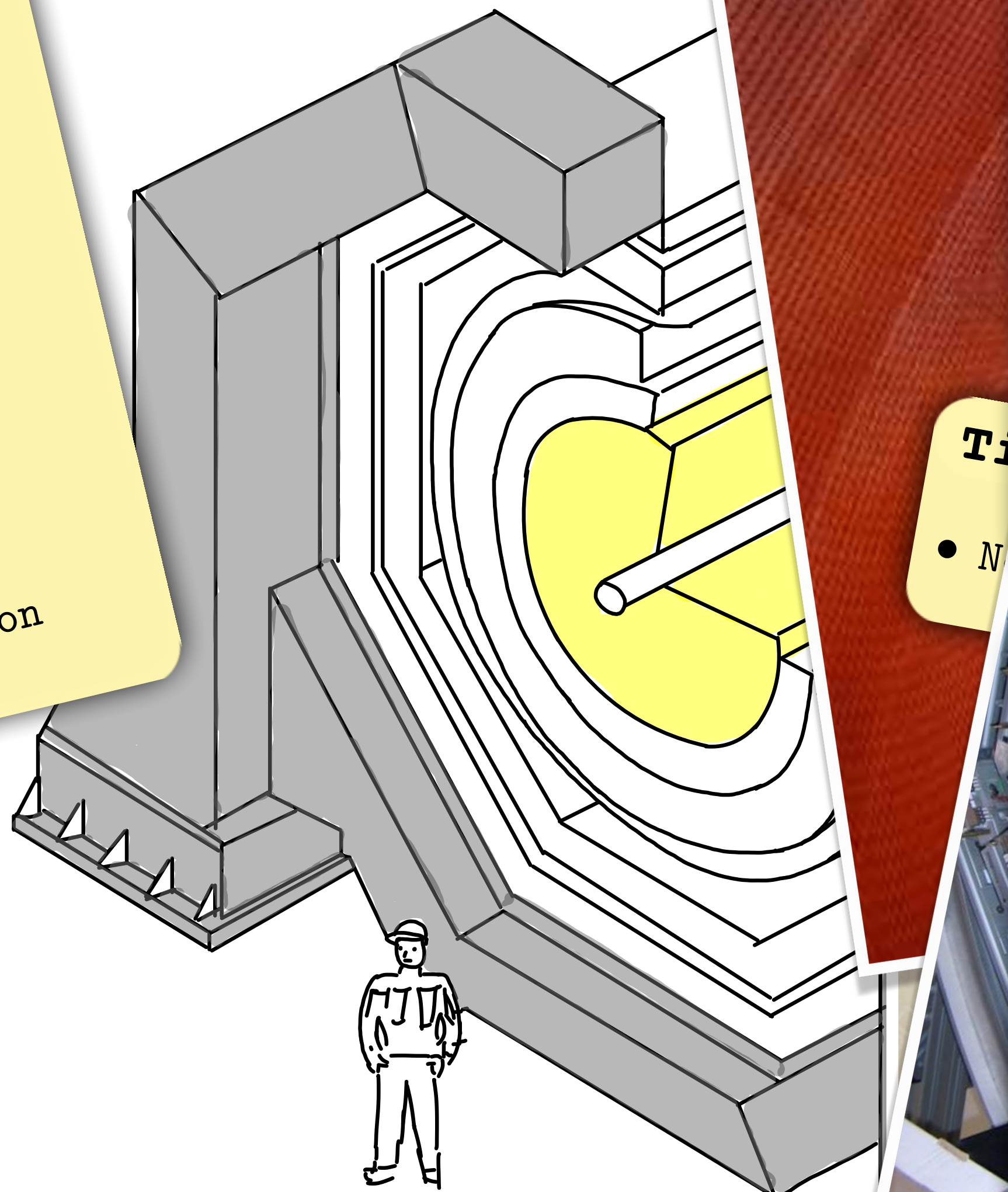


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Inner Tracking Detectors

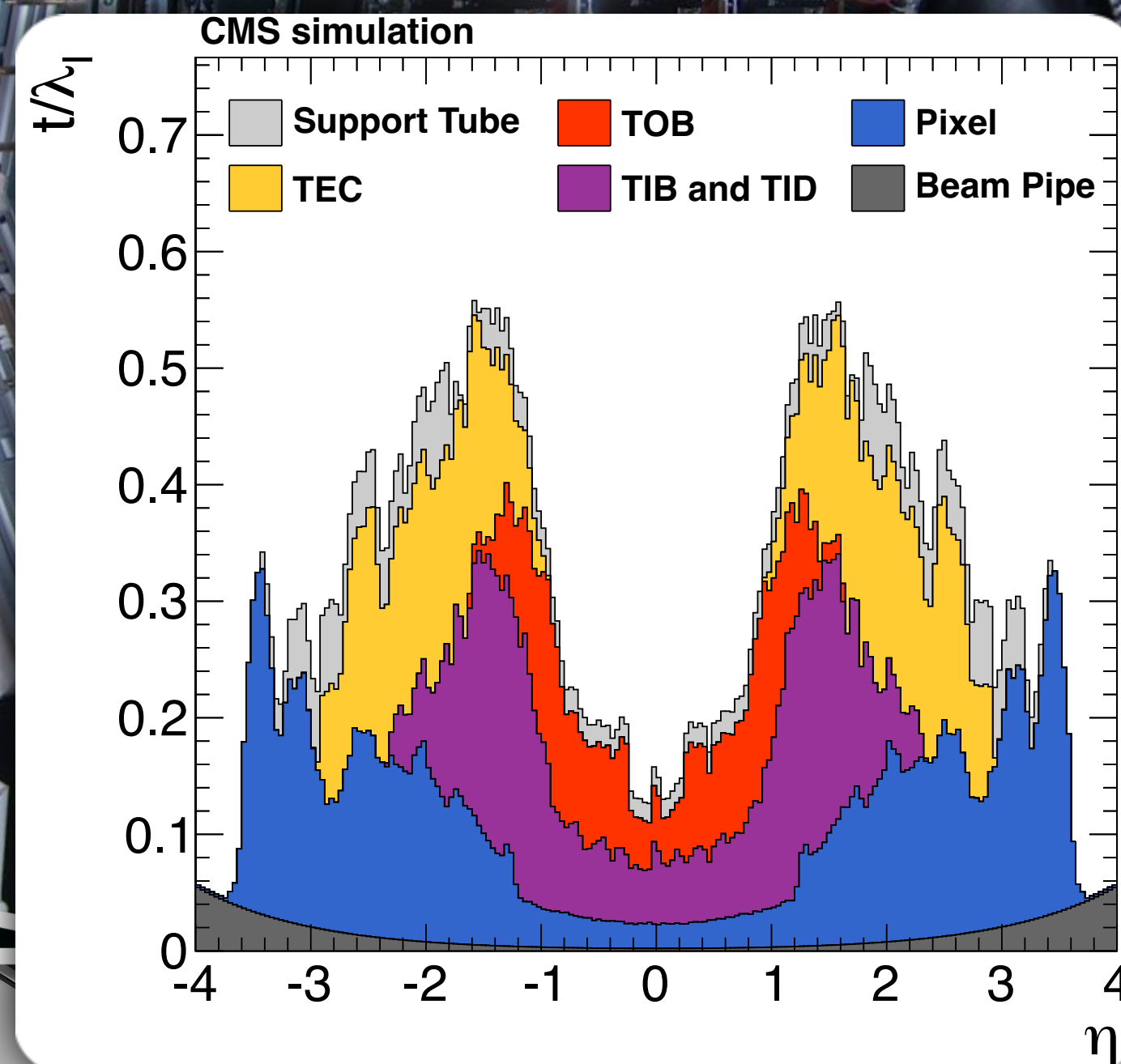
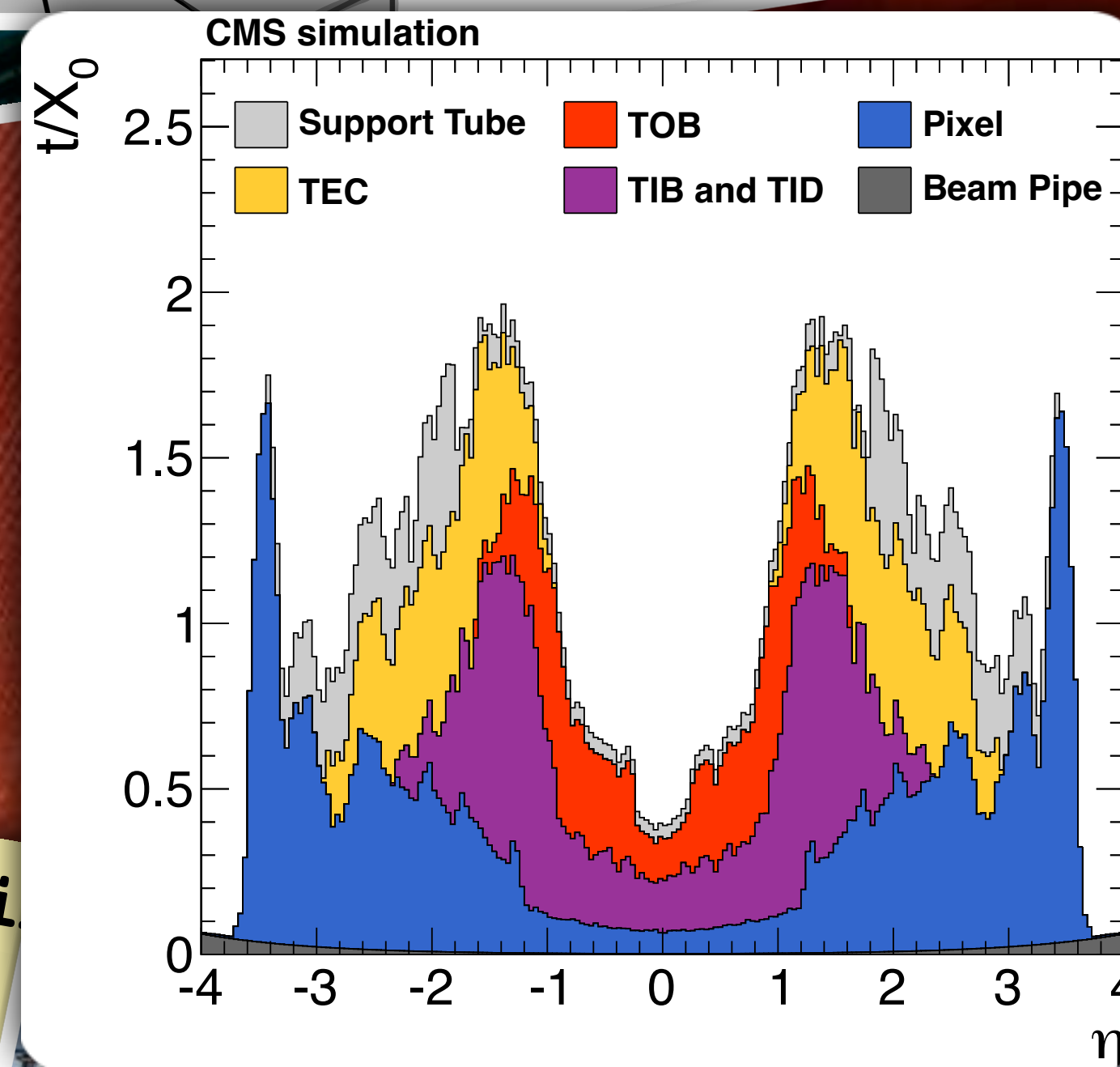
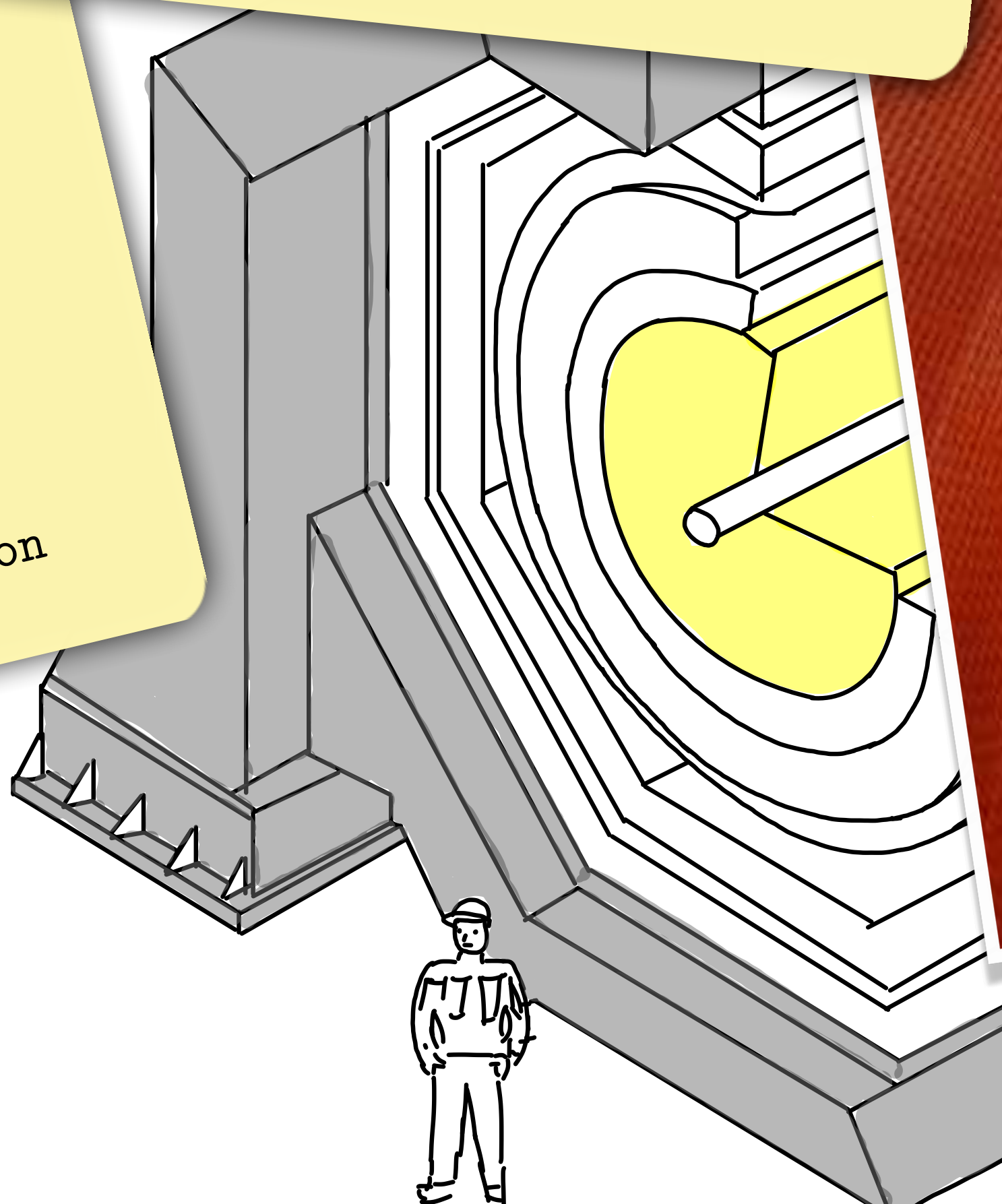
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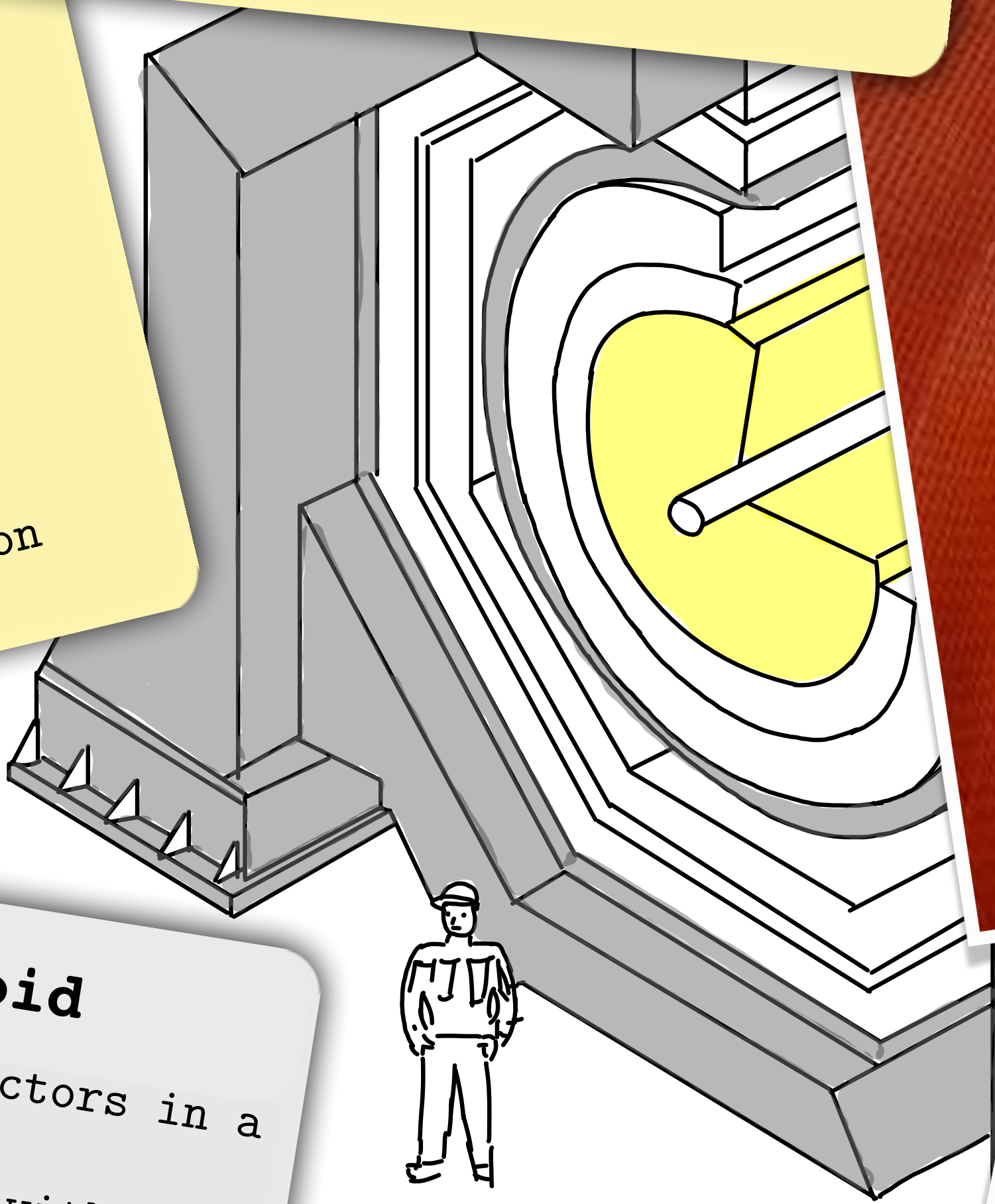
See Corrinne Mills' Lectures on Tracking Detectors



Inner Tracking Detectors

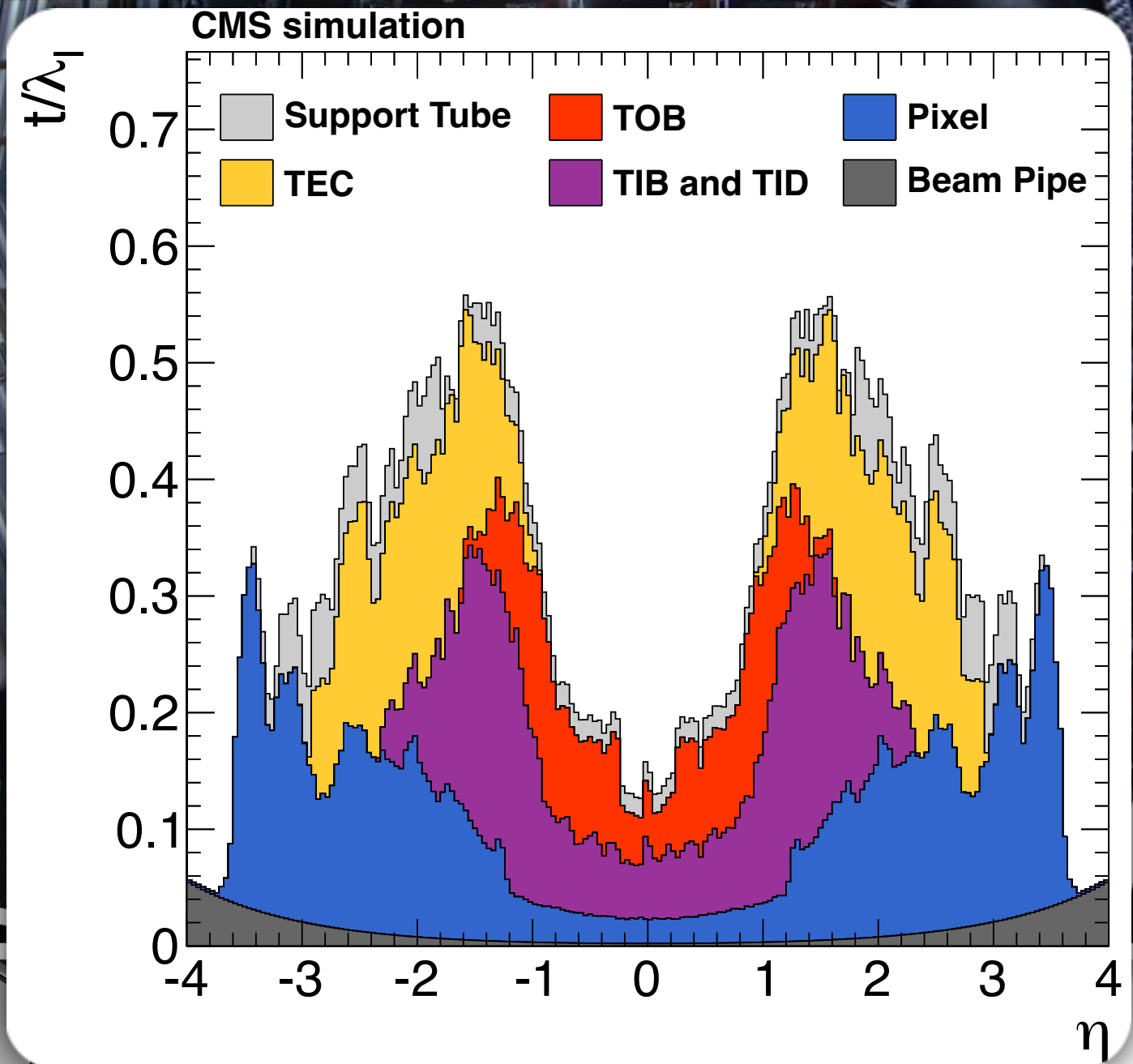
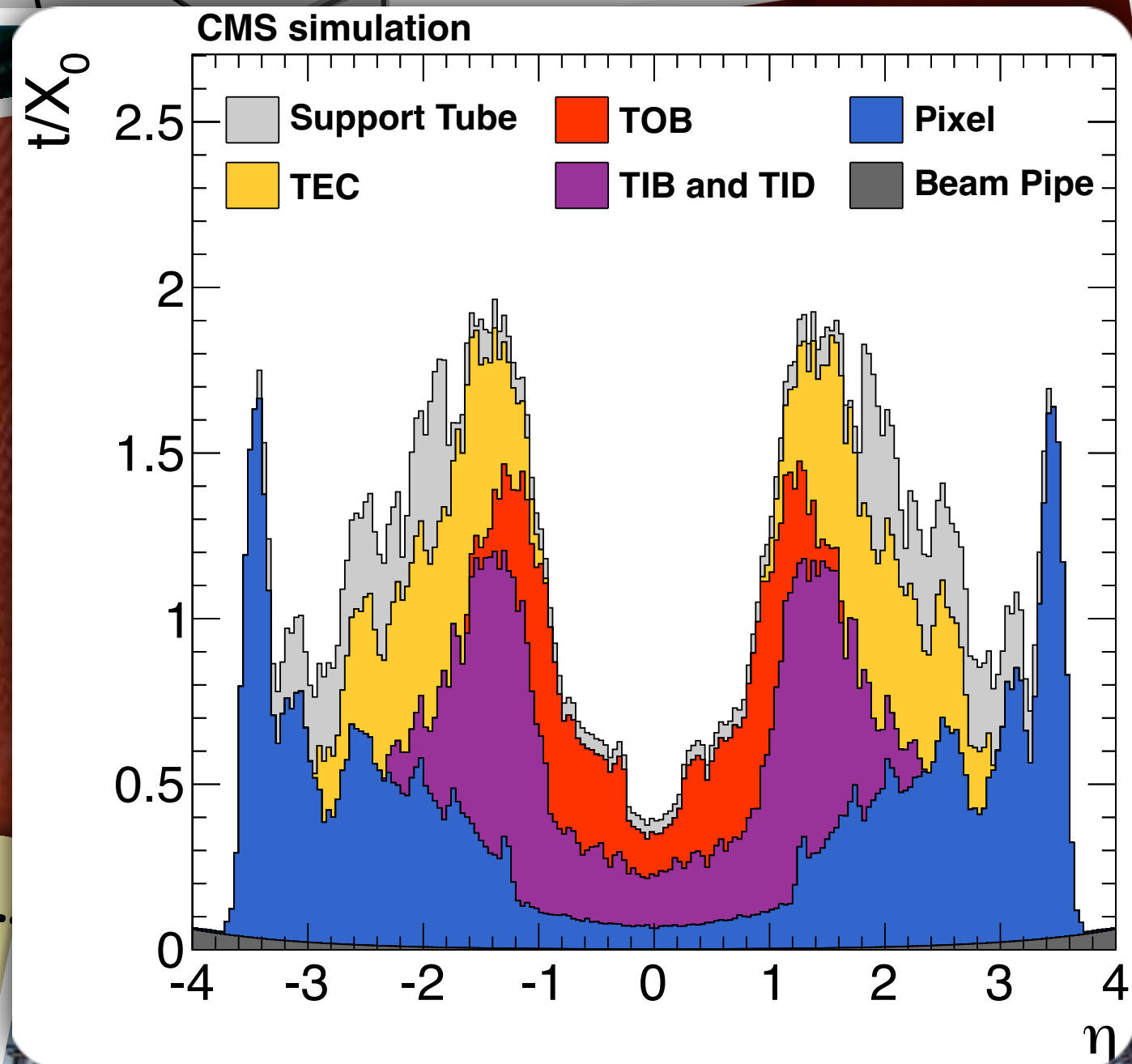
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Magnetic Solenoid

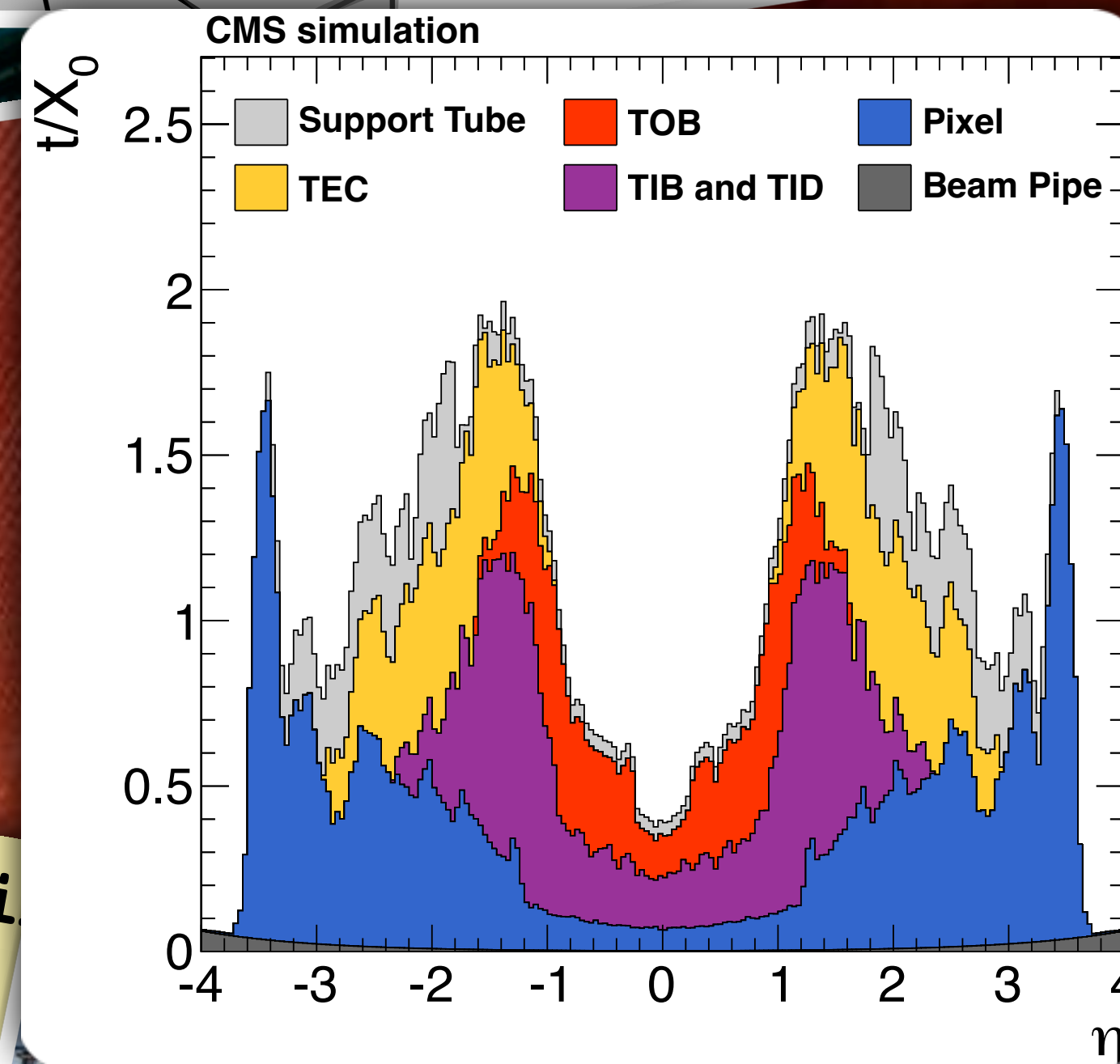
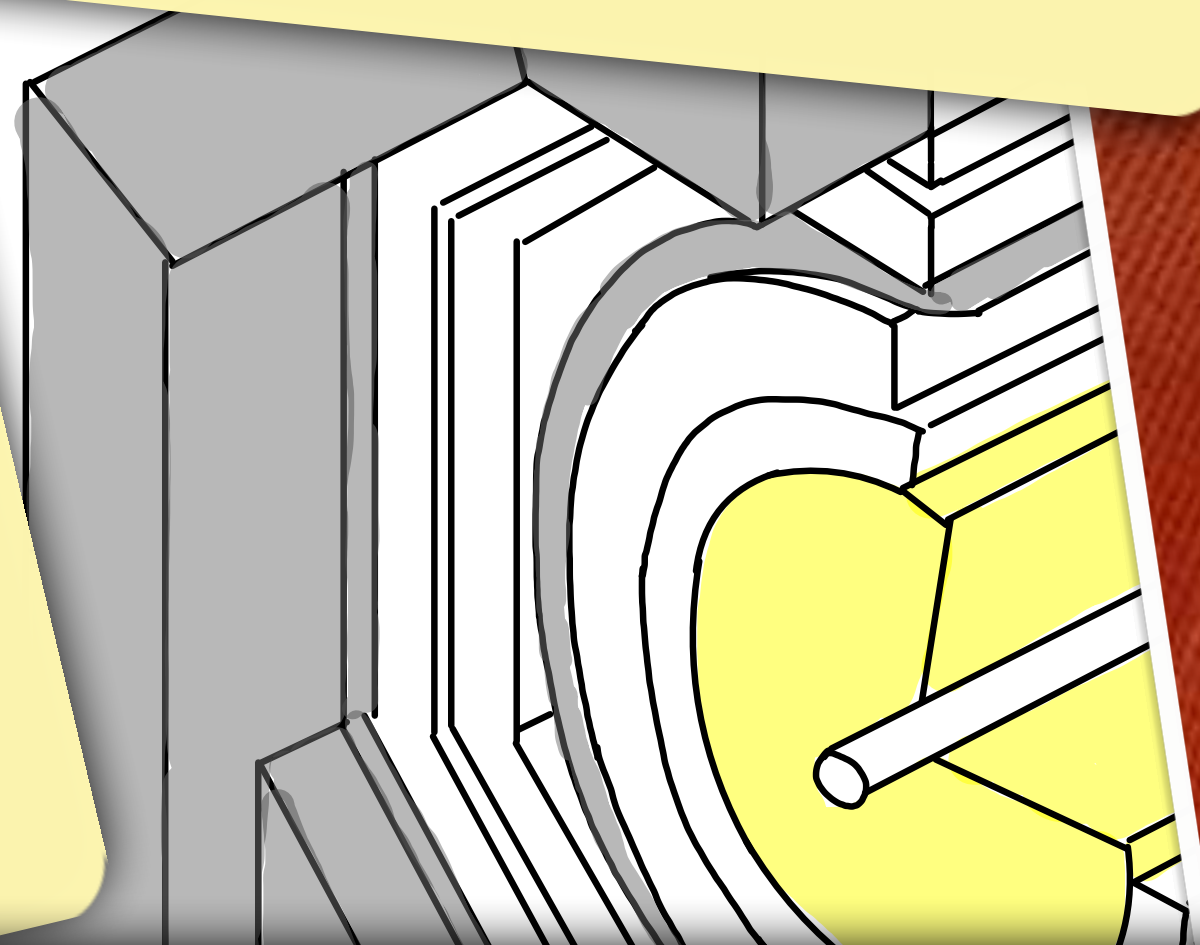
- Immerse inner tracking detectors in a uniform magnetic field
- Charged particle will curve with a radius inversely proportional to its momentum



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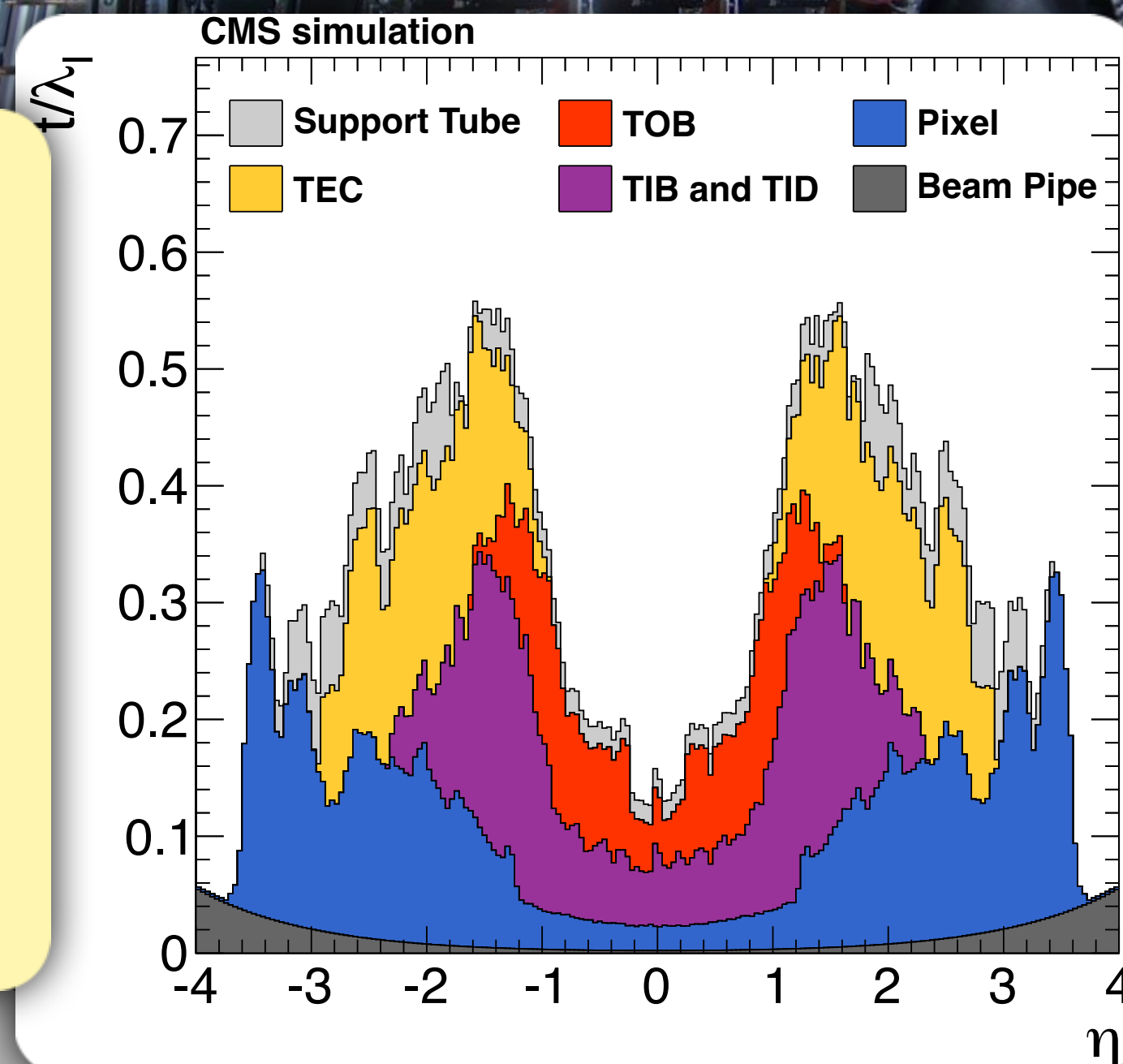


Momentum & Charge Measurement

- You already studied this in Kevin Black's lectures!
- Quick reminder:
 - $p_T \propto$ radius of curvature
- Momentum resolution $\propto p_T^2$
 - Gets better at low p_T
 - Gets worse at high p_T

Magnetic Solenoid

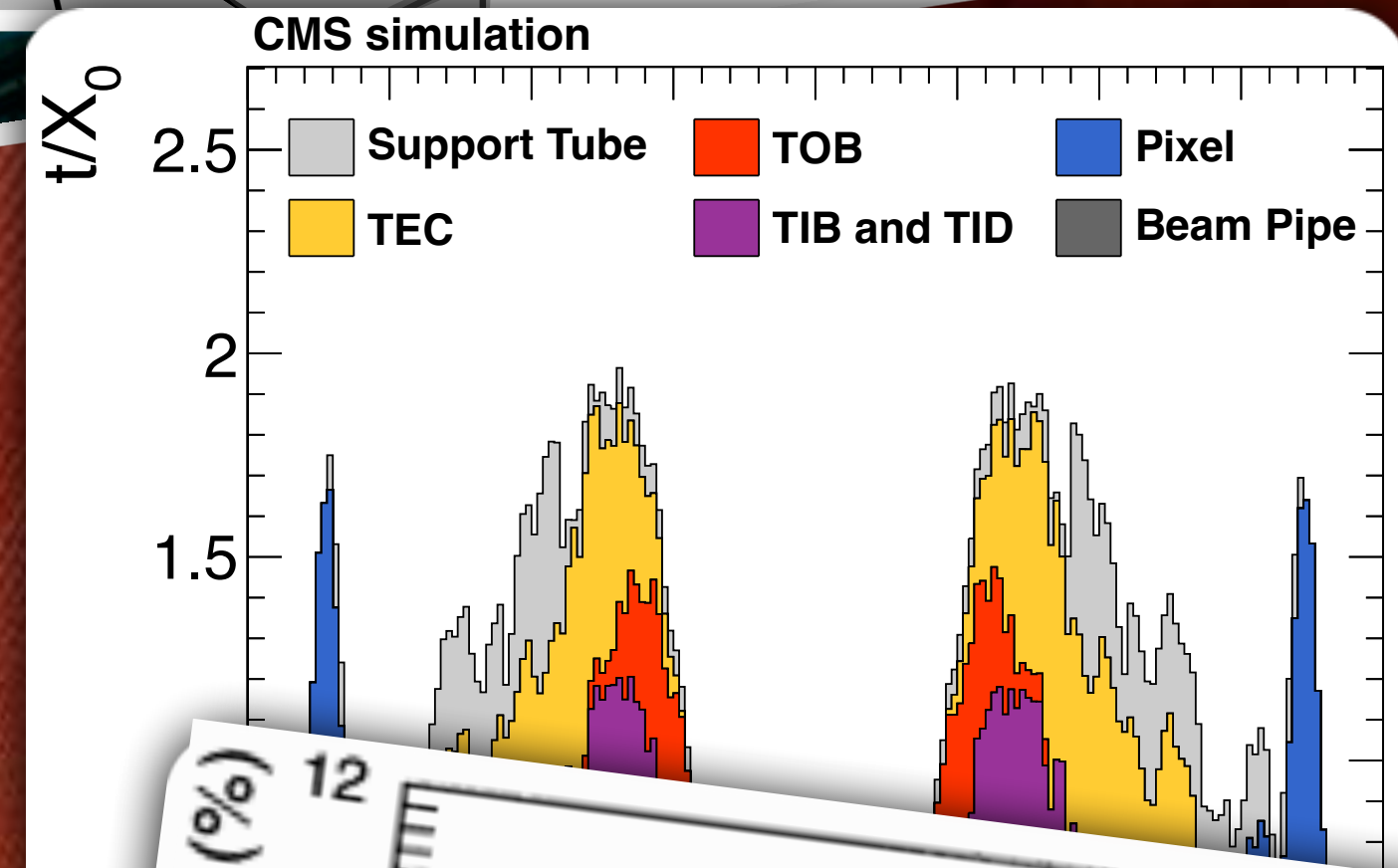
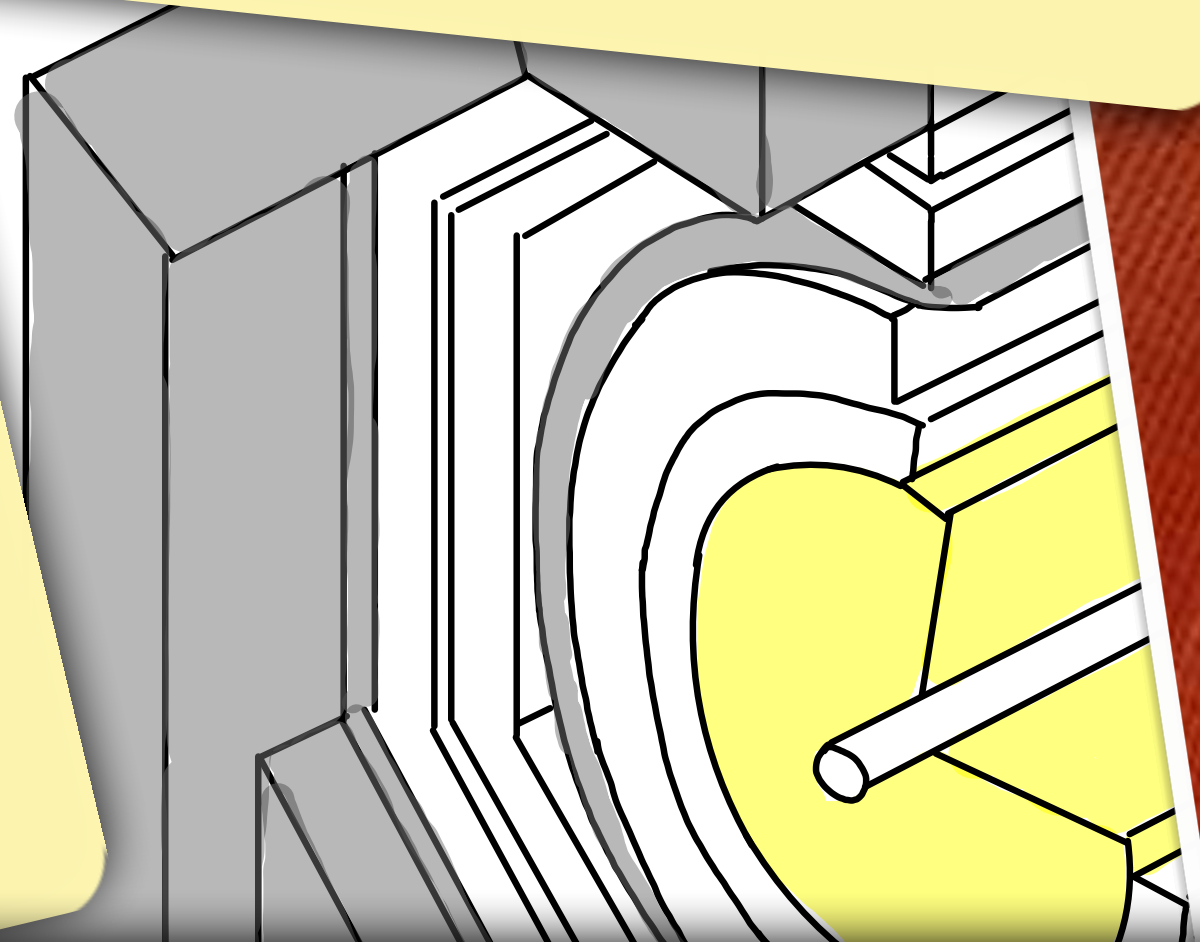
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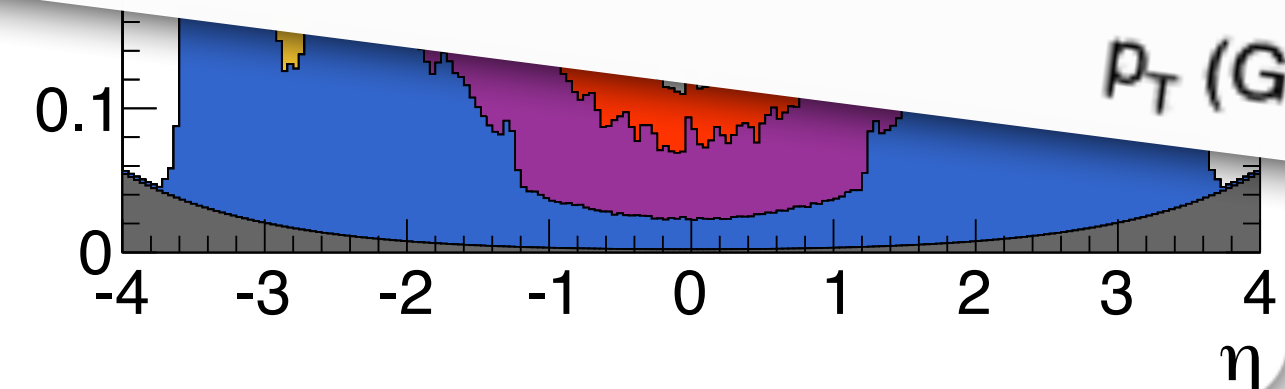
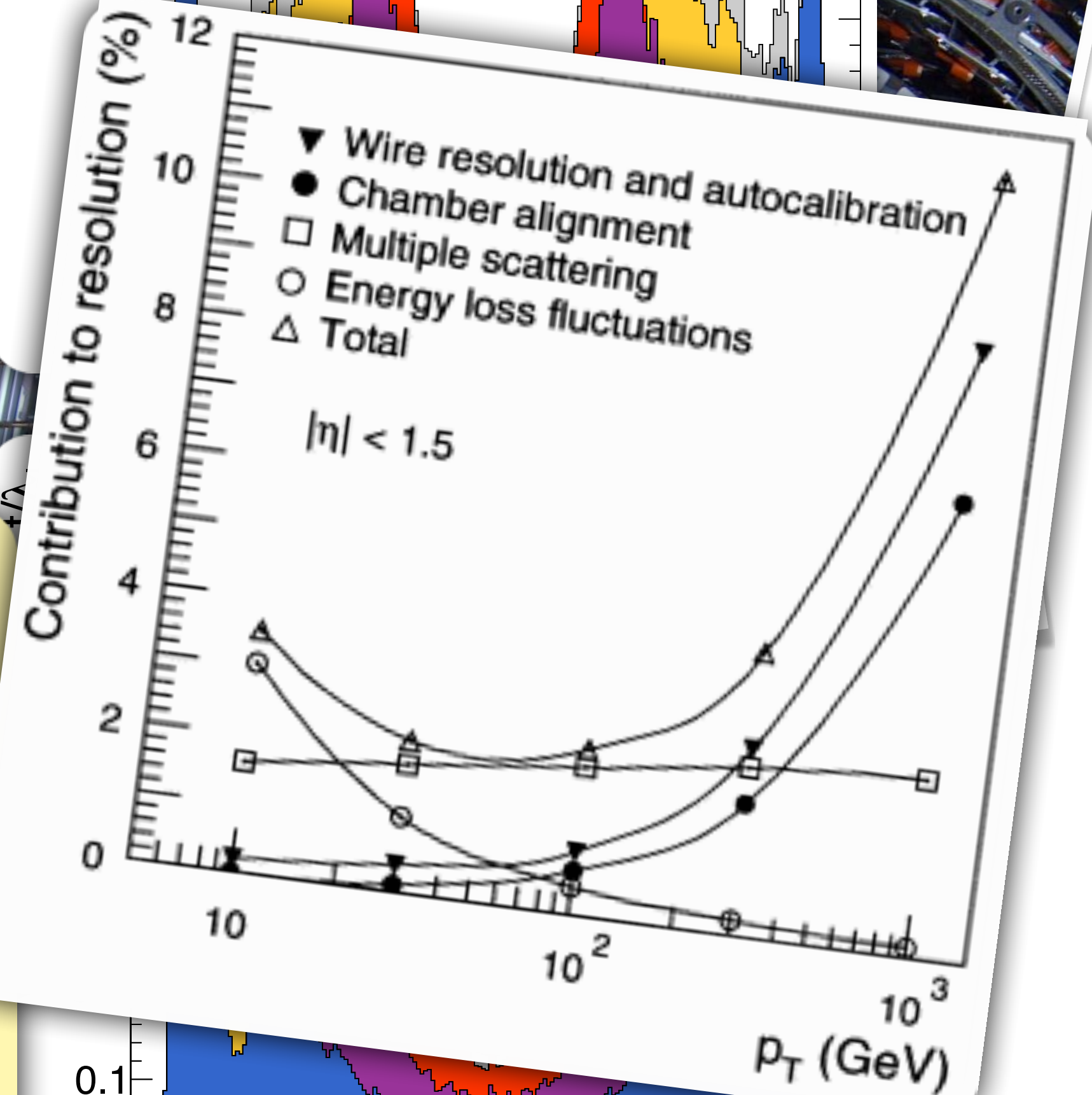


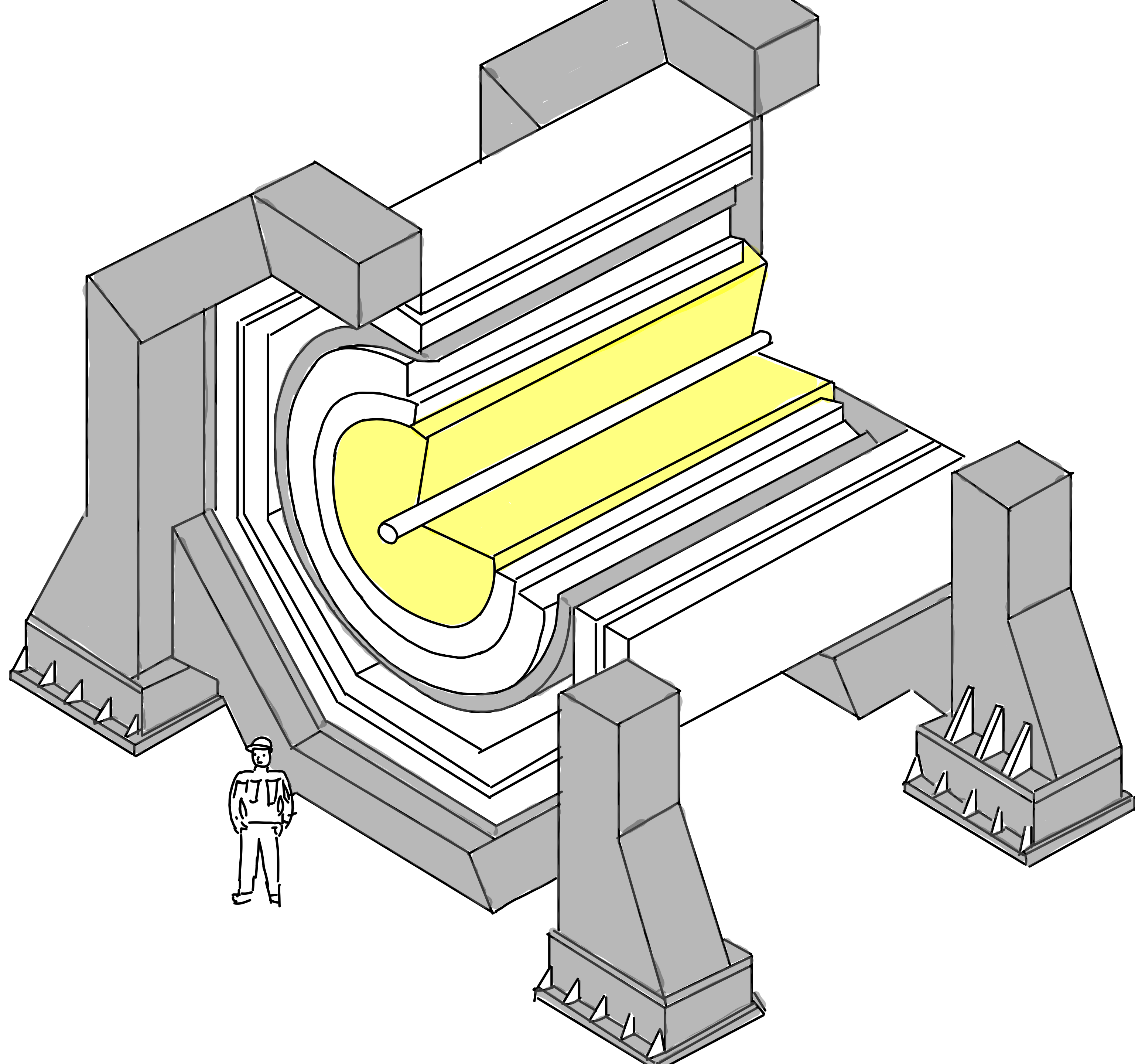
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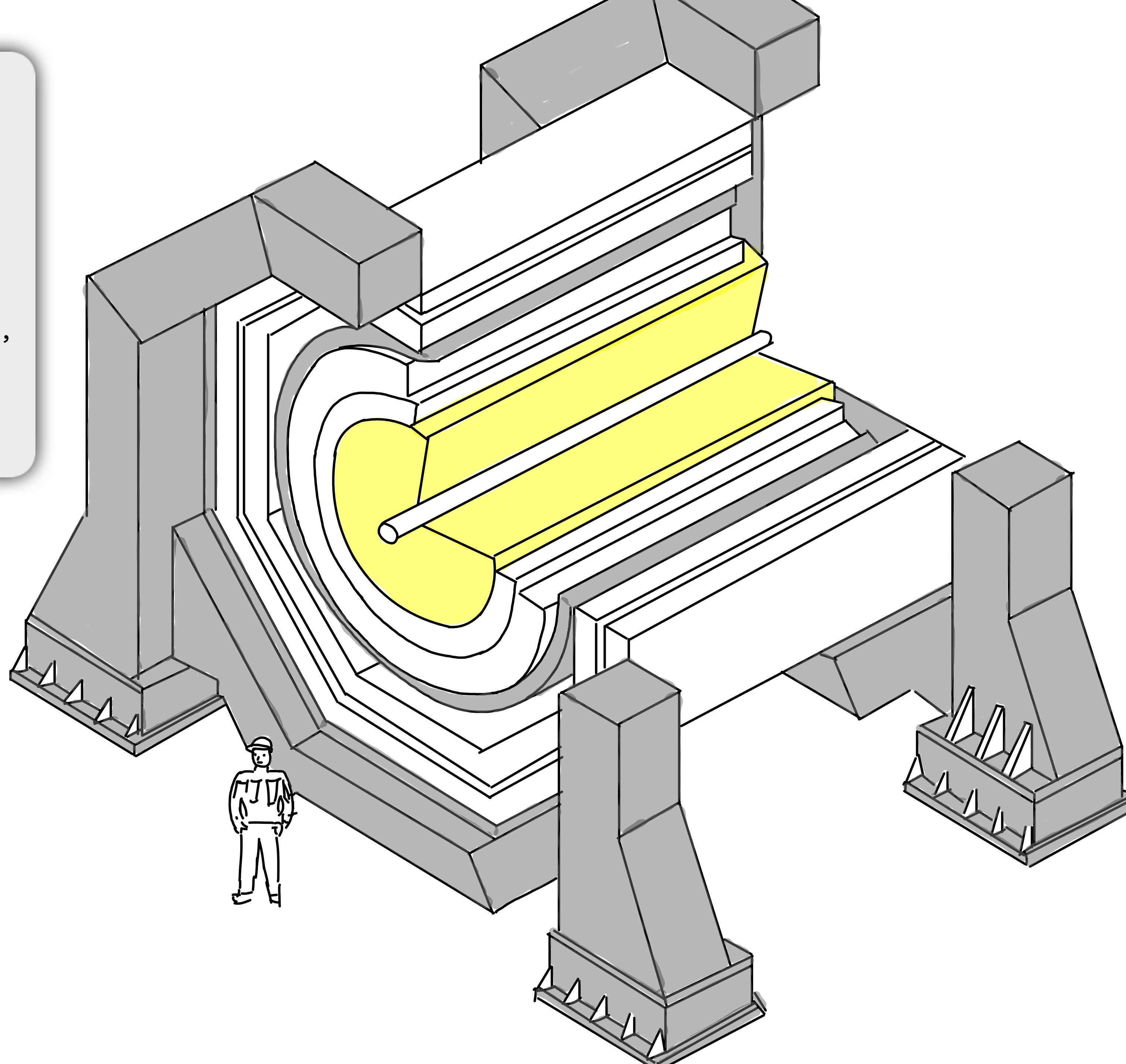
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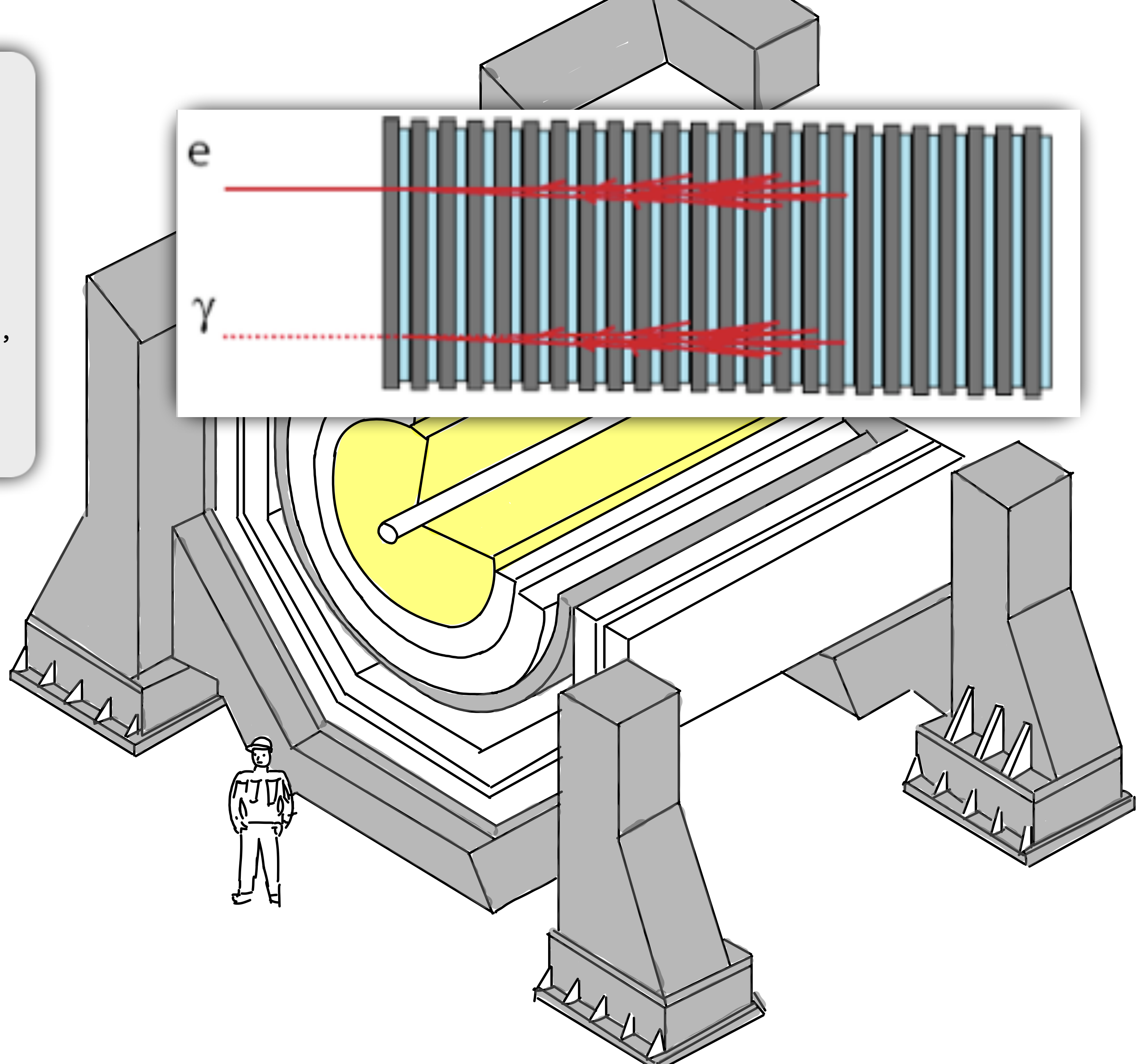
Sampling Calorimeters

- Active Medium: provides signal
 - Scintillator, ionising noble liquid, etc
- Passive Medium: functions as absorber
 - High density material like lead, iron copper, depleted uranium
- Lower resolution; depth segmentation (longitudinal shower profile)



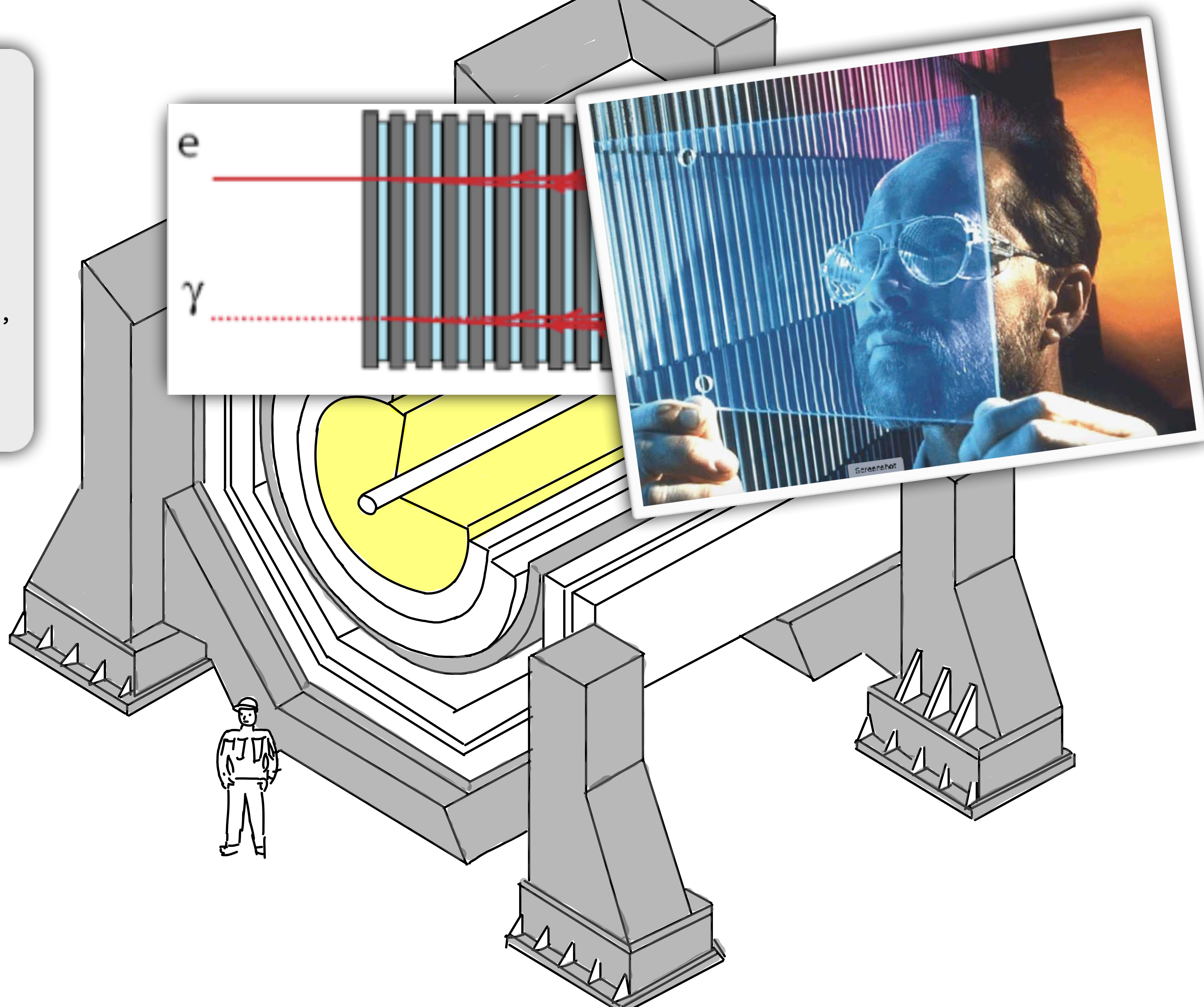
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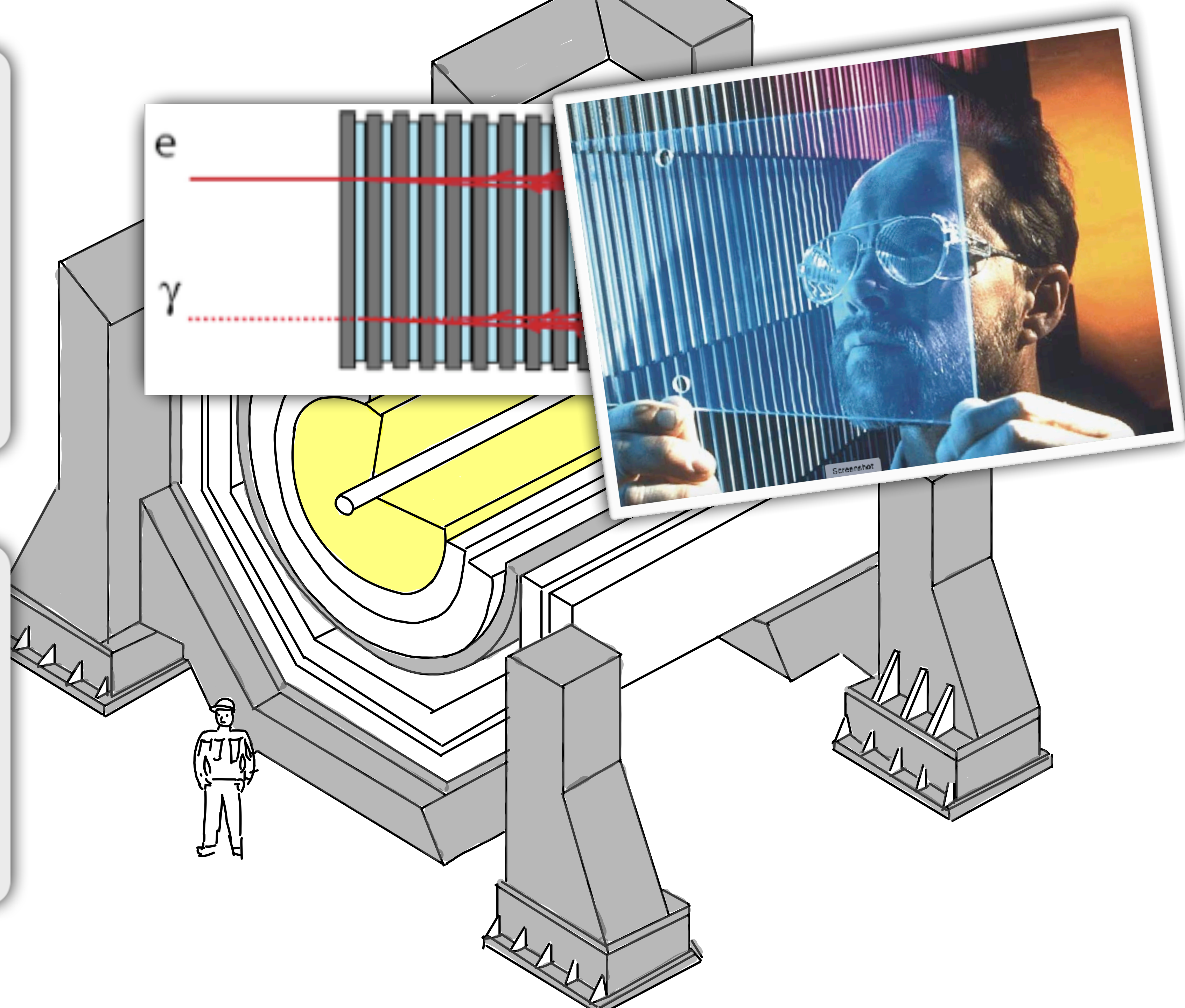


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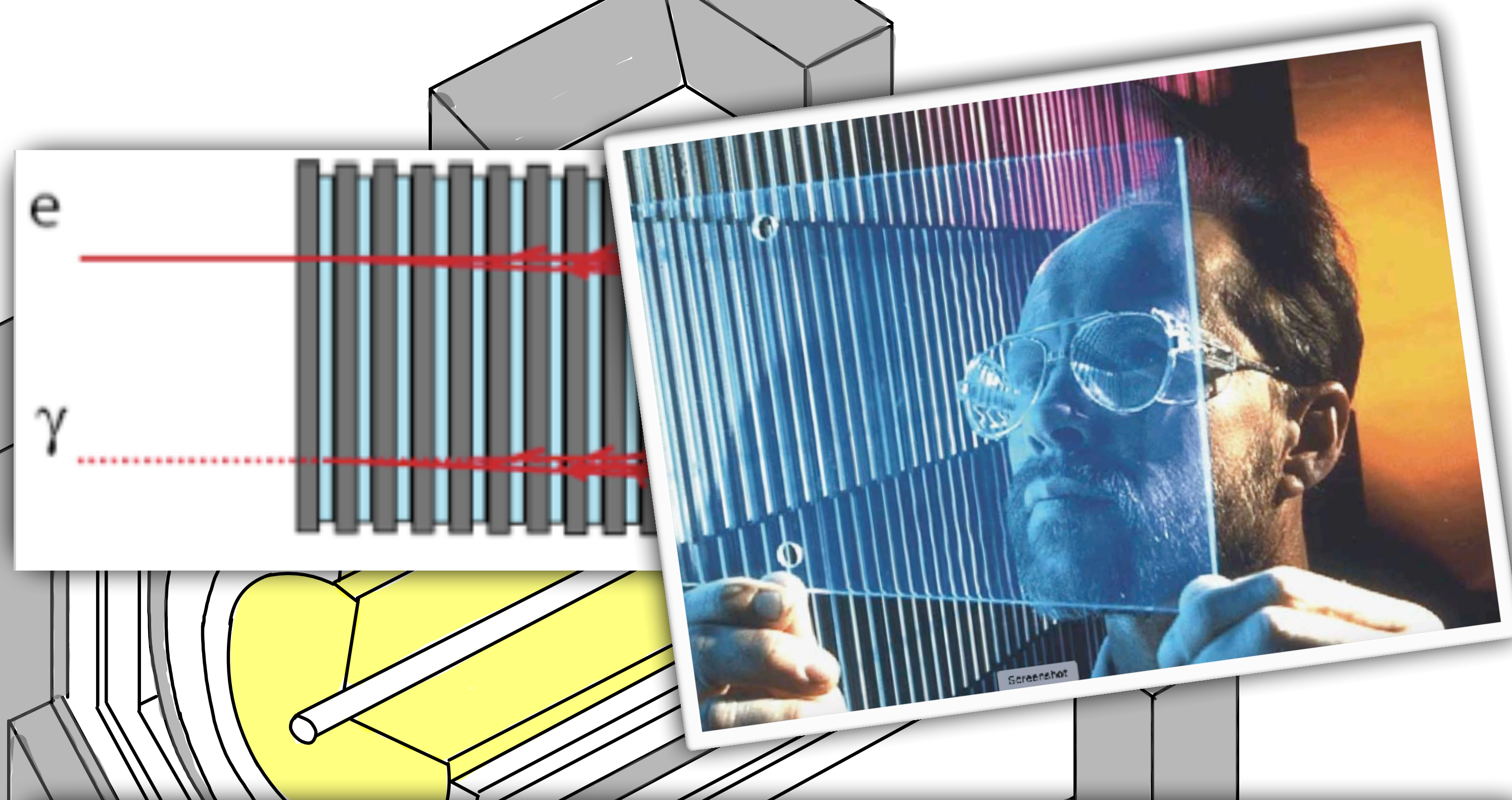
Homogeneous Calorimeters

- Entire volume provides signal
- Inorganic heavy scintillating crystals
 - CsI, NaI, PbWO, etc
 - Ionising noble liquids
- Better resolution; no depth segmentation (no longitudinal shower profile)



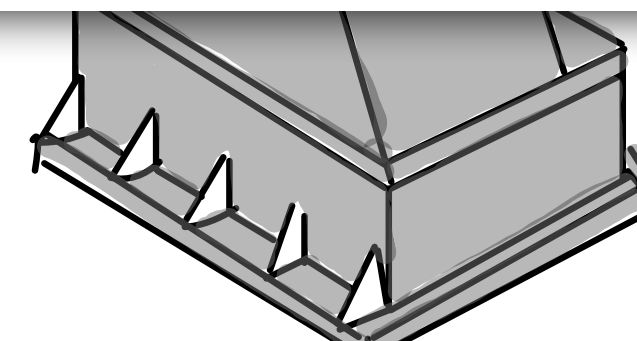
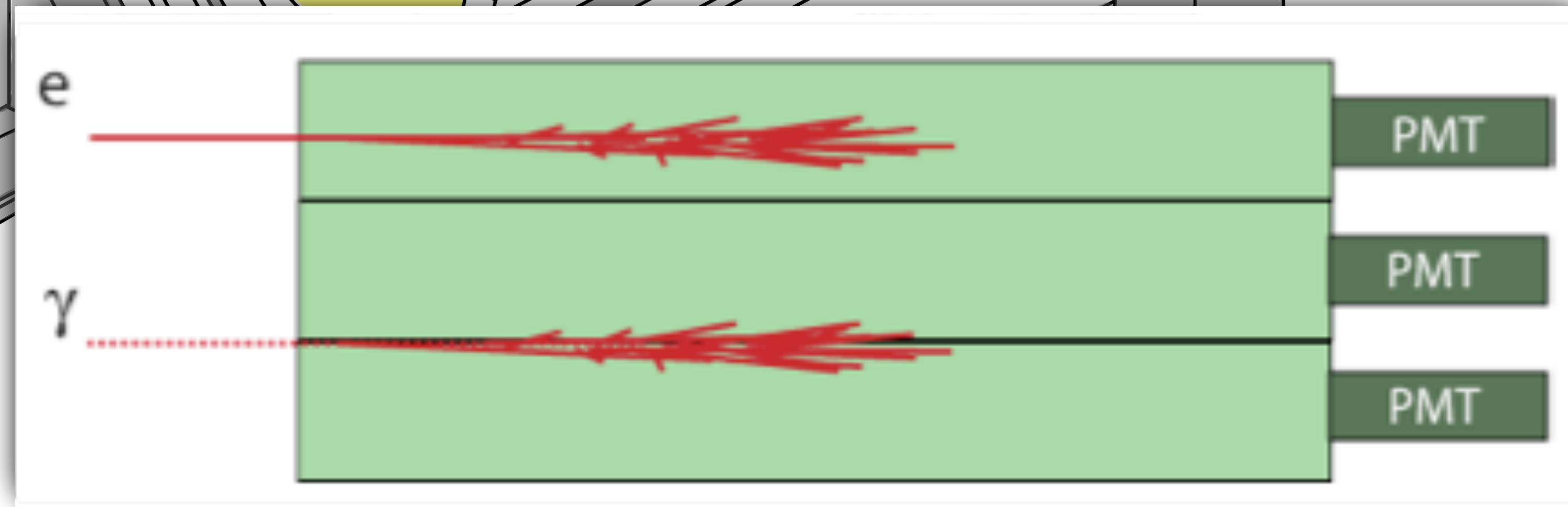
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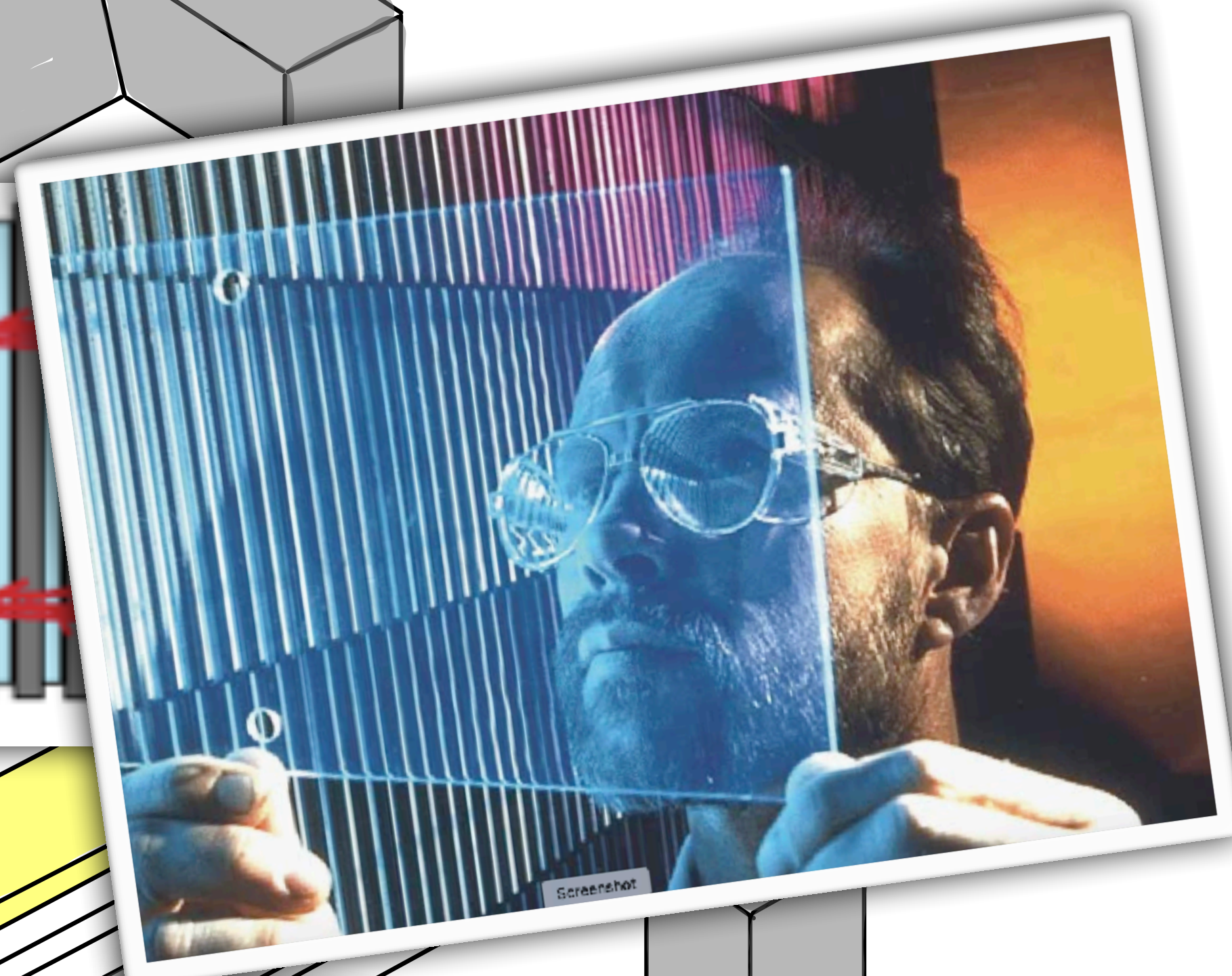
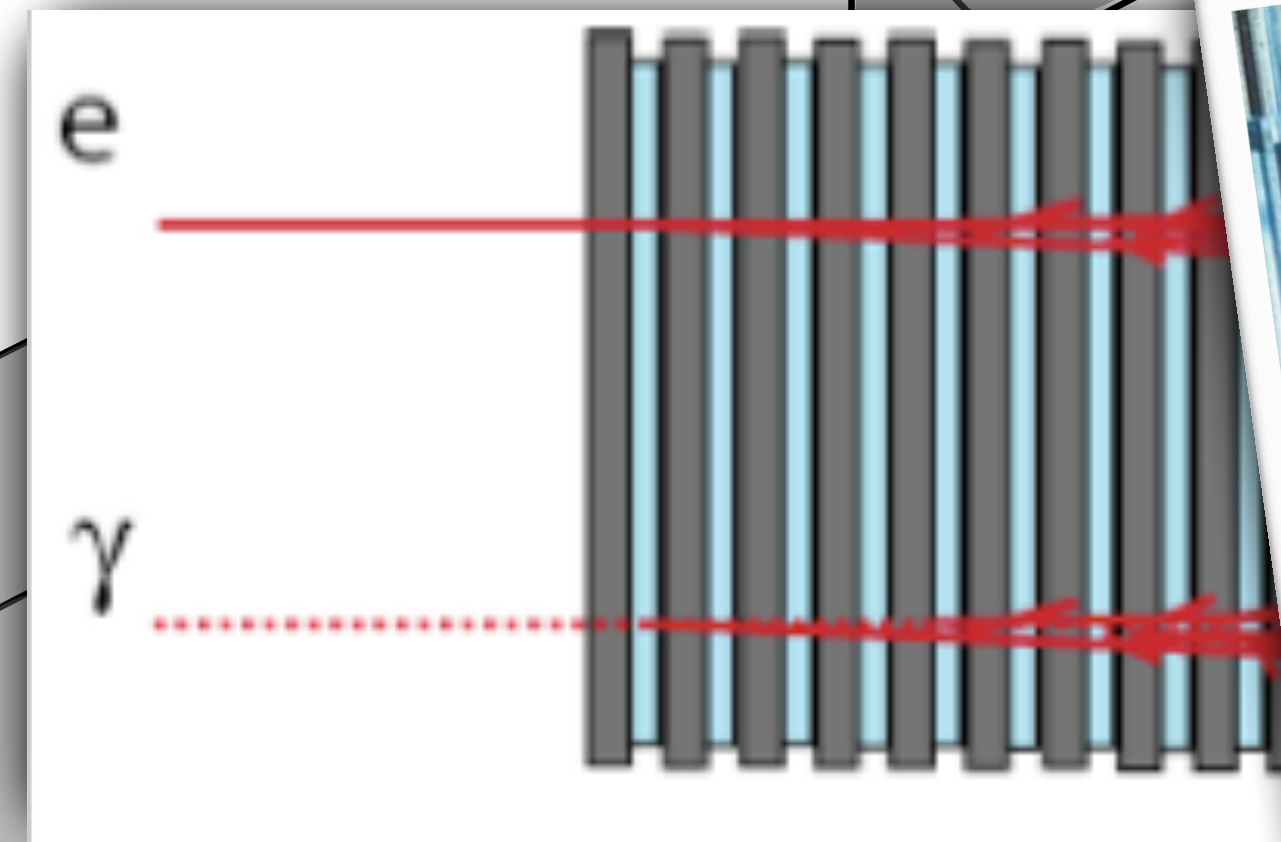
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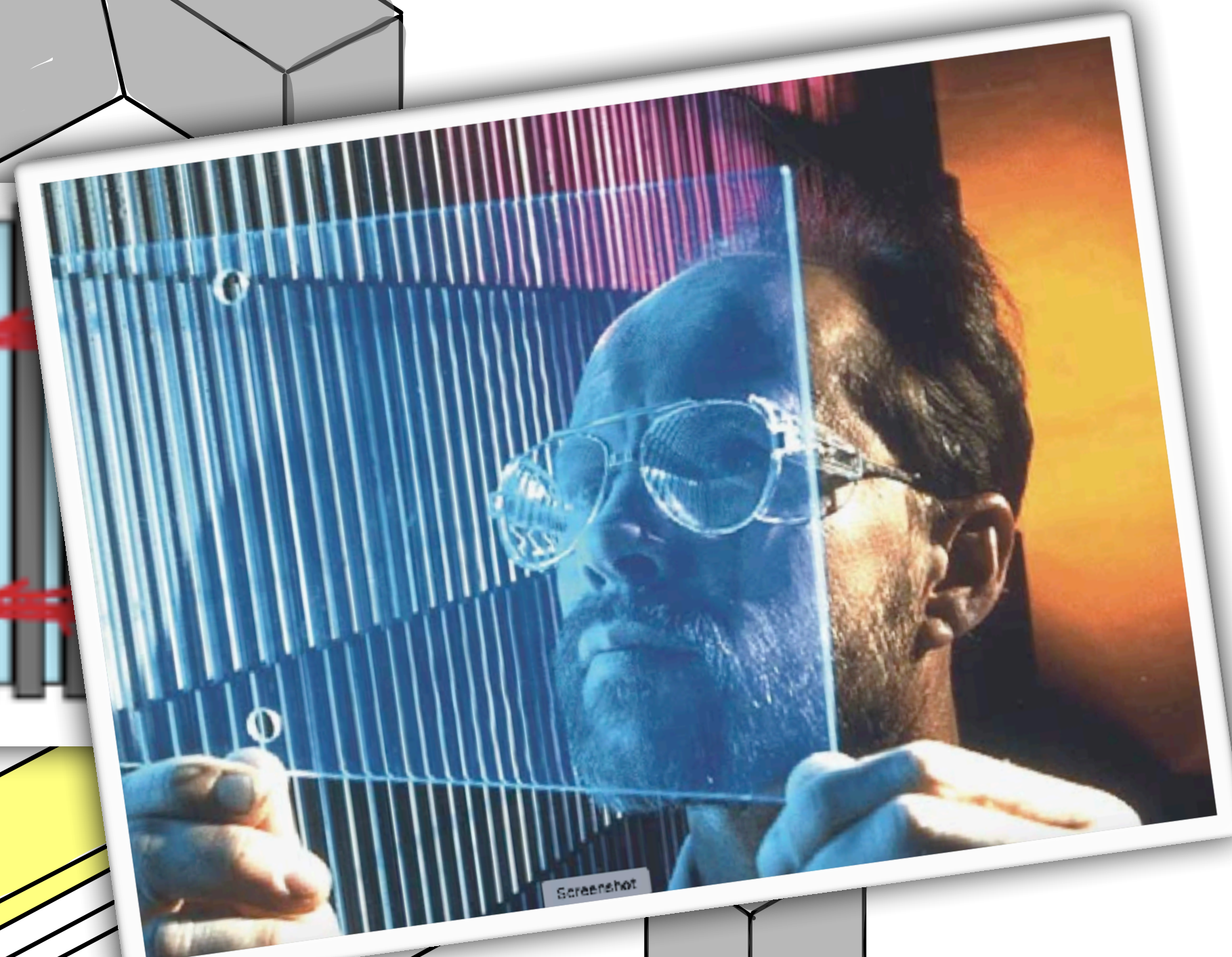
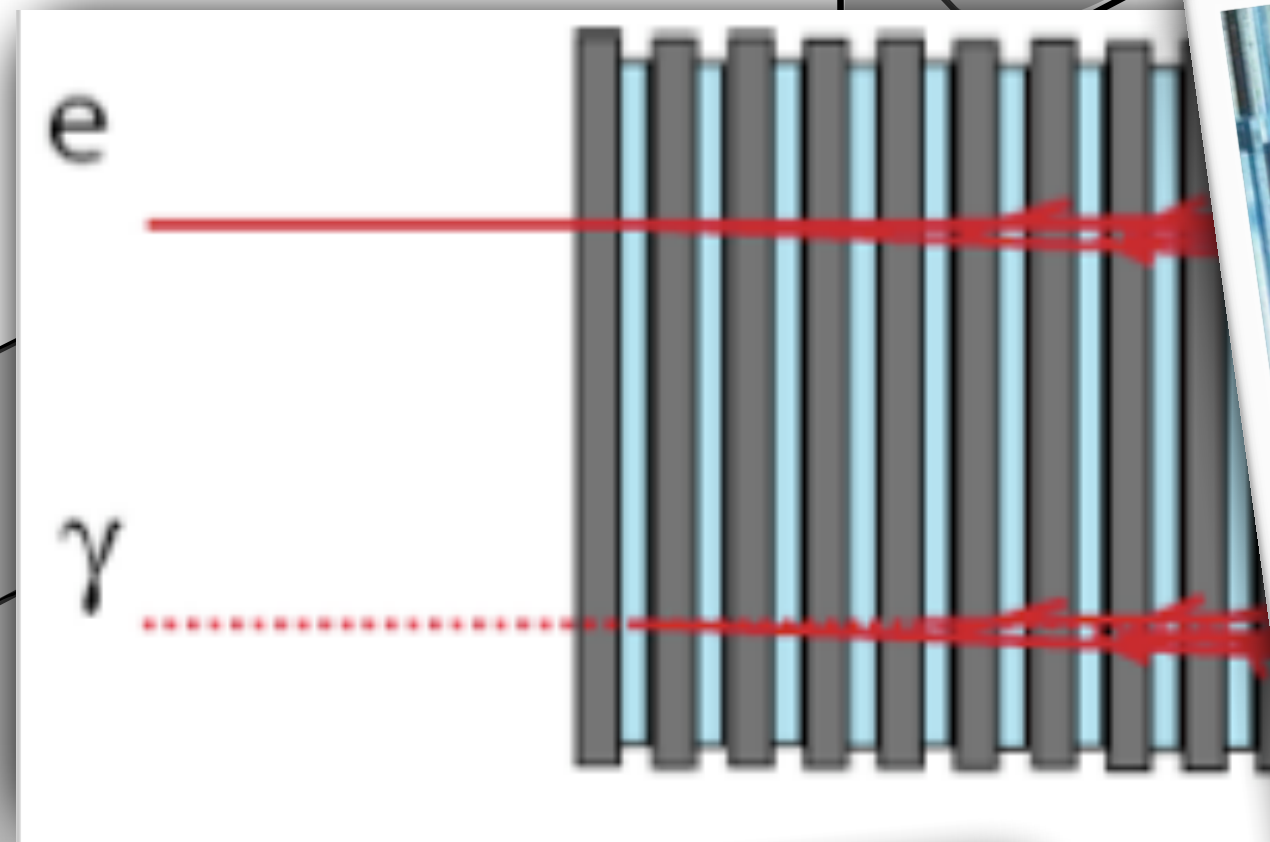
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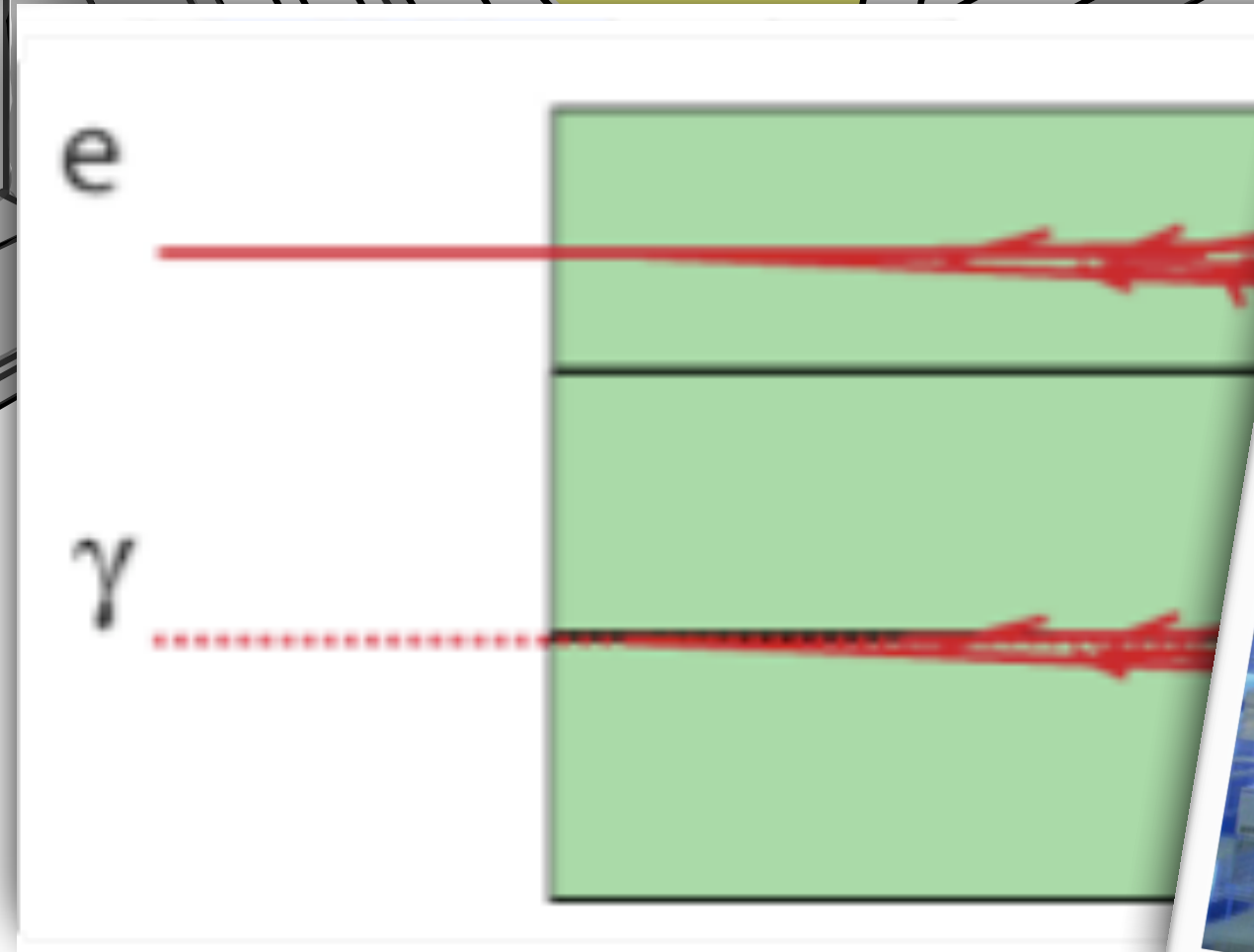
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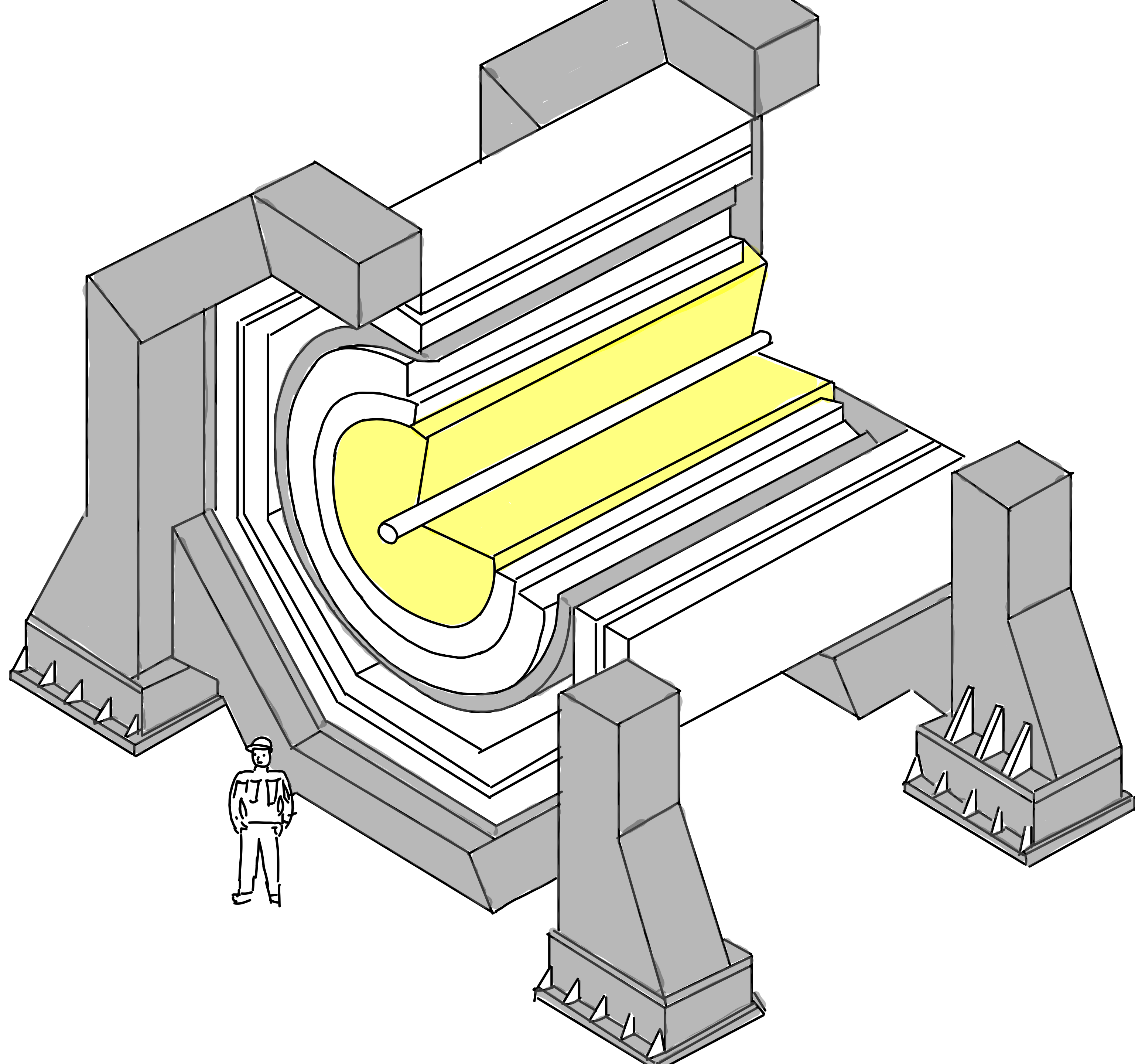
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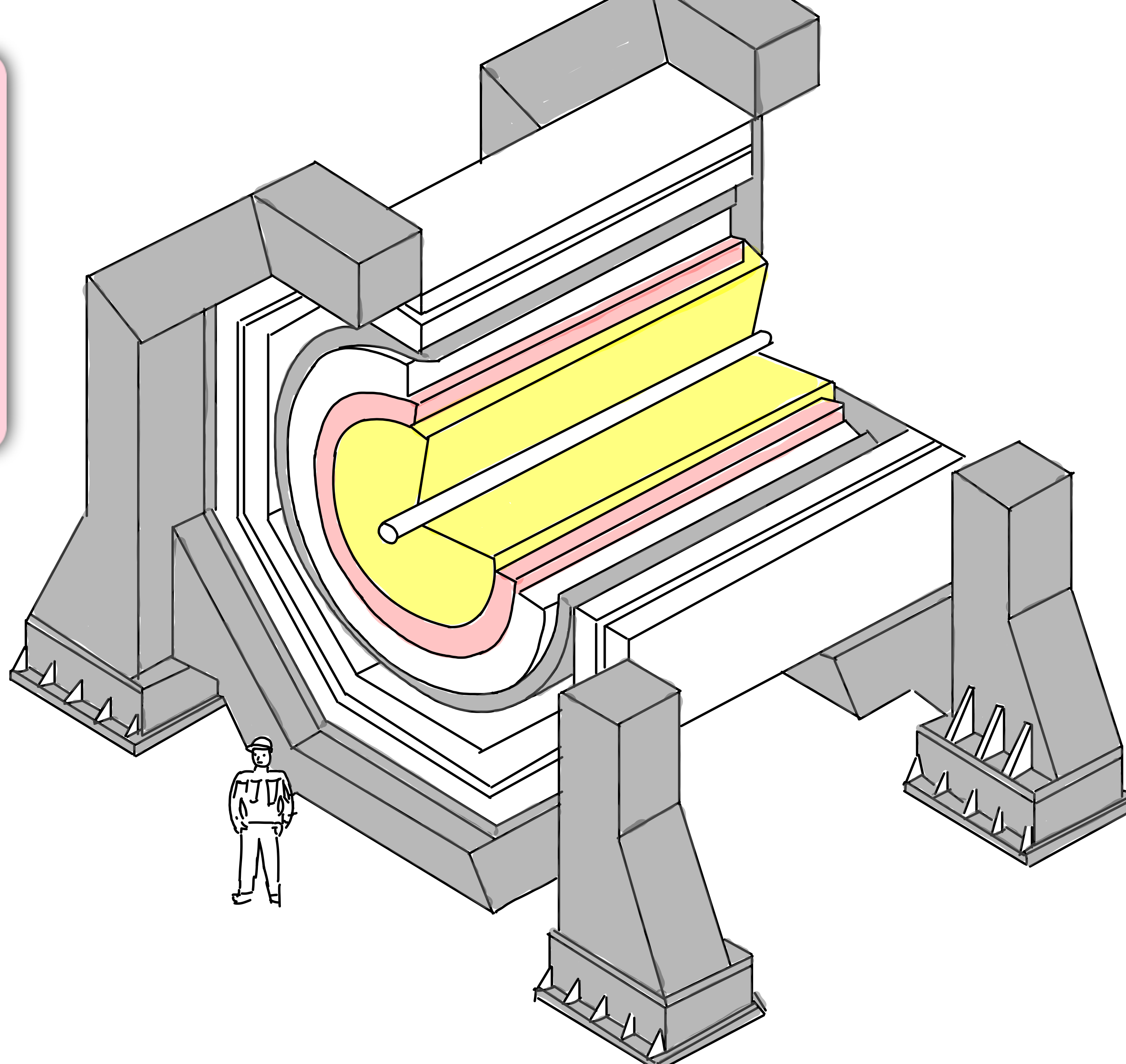
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EM Calorimeters

- Purpose: measure energy of EM particles
- How?
 - High Z material causes EM shower
 - Total absorption / stops particle
 - Important parameter is X_0 (usually $X_0 = 15-30$ mm)

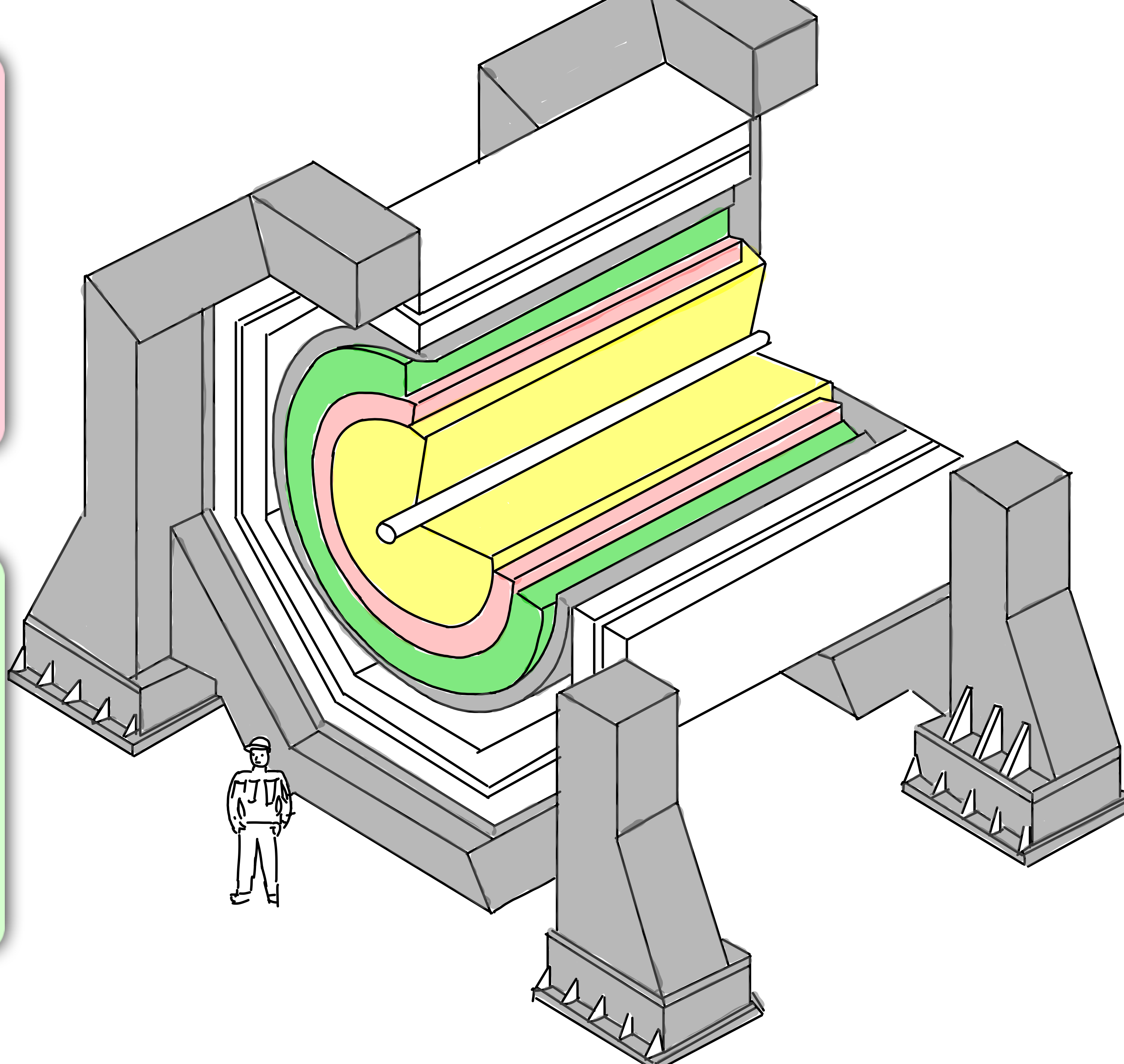


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- Purpose: measure energy of hadronic particles
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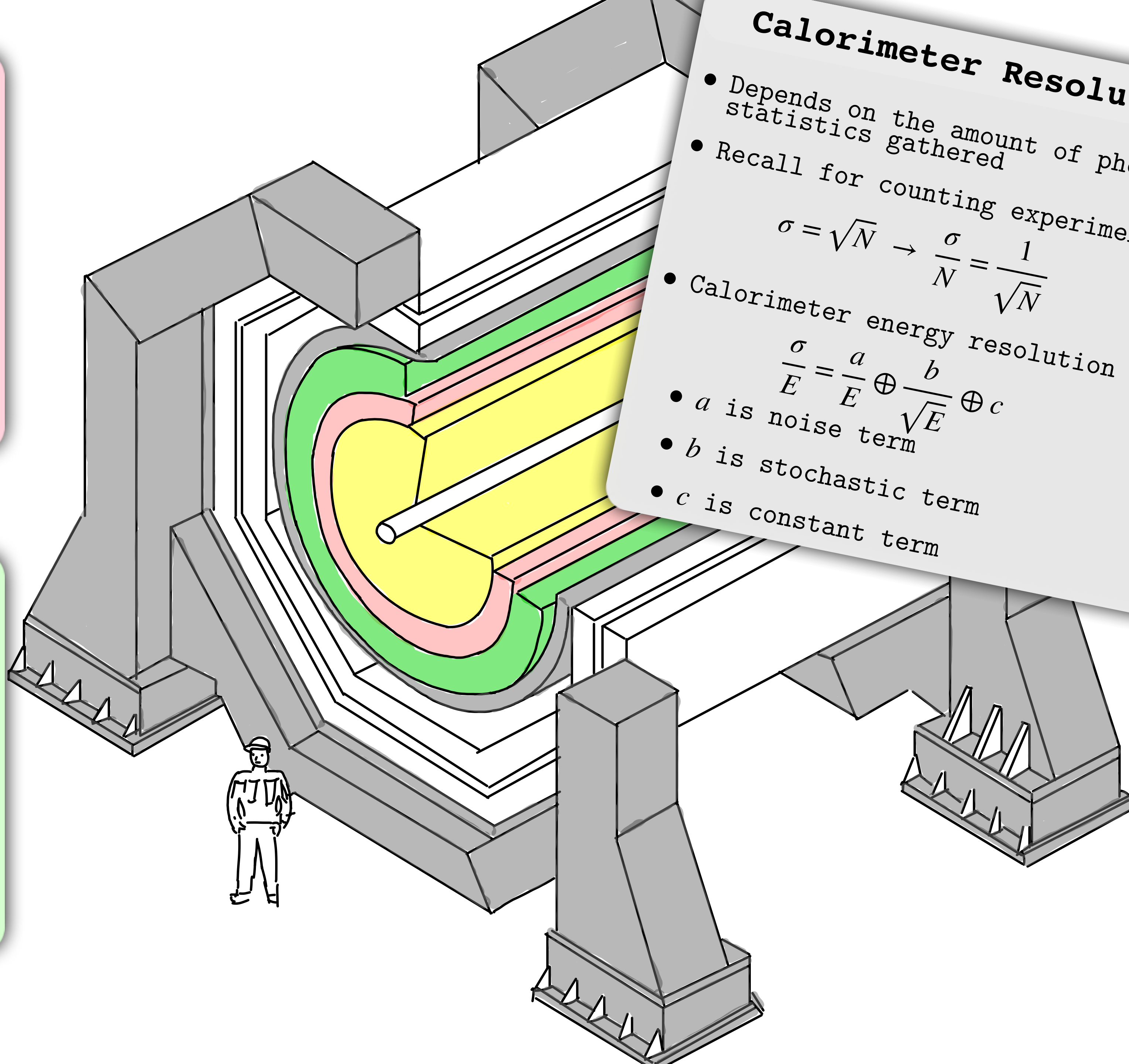


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Calorimeter Resolution

- Depends on the amount of photo-statistics gathered
- Recall for counting experiment

$$\sigma = \sqrt{N} \rightarrow \frac{\sigma}{N} = \frac{1}{\sqrt{N}}$$

- Calorimeter energy resolution

$$\frac{\sigma}{E} = \frac{a}{E} \oplus \frac{b}{\sqrt{E}} \oplus c$$

- a is noise term
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EM Calorimeters

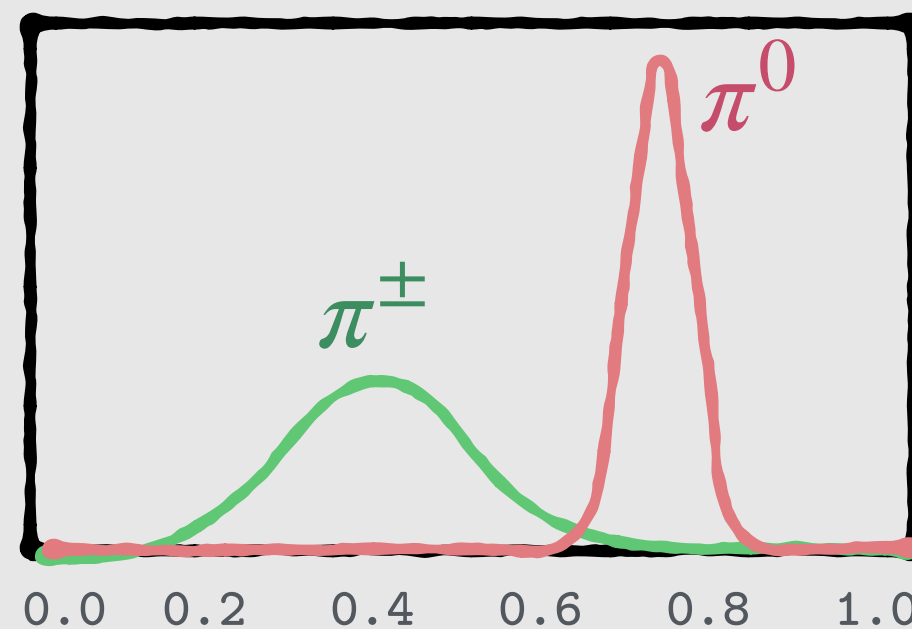
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- EM vs HAD response different



- Large fluctuations in HAD shower composition (EM vs HAD)
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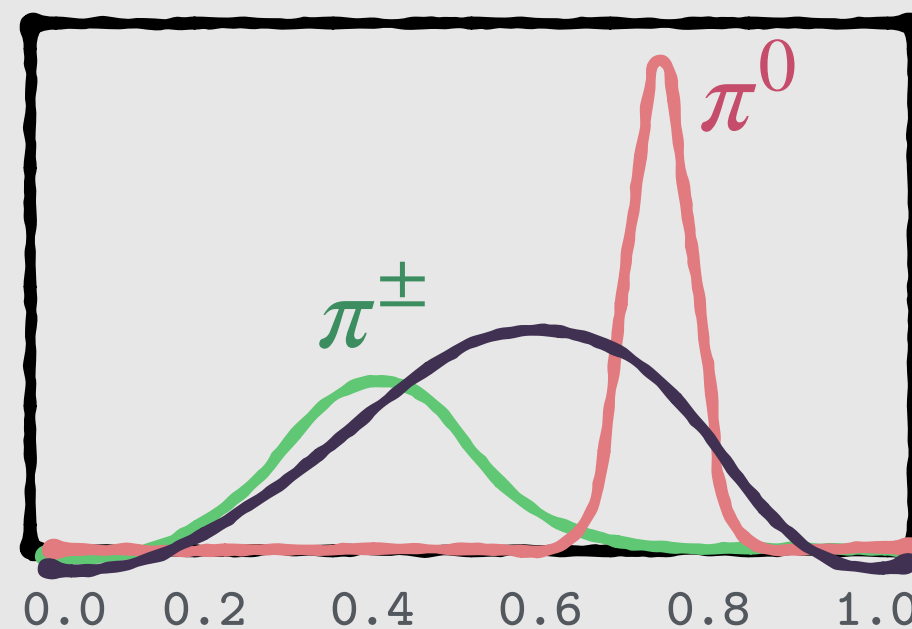
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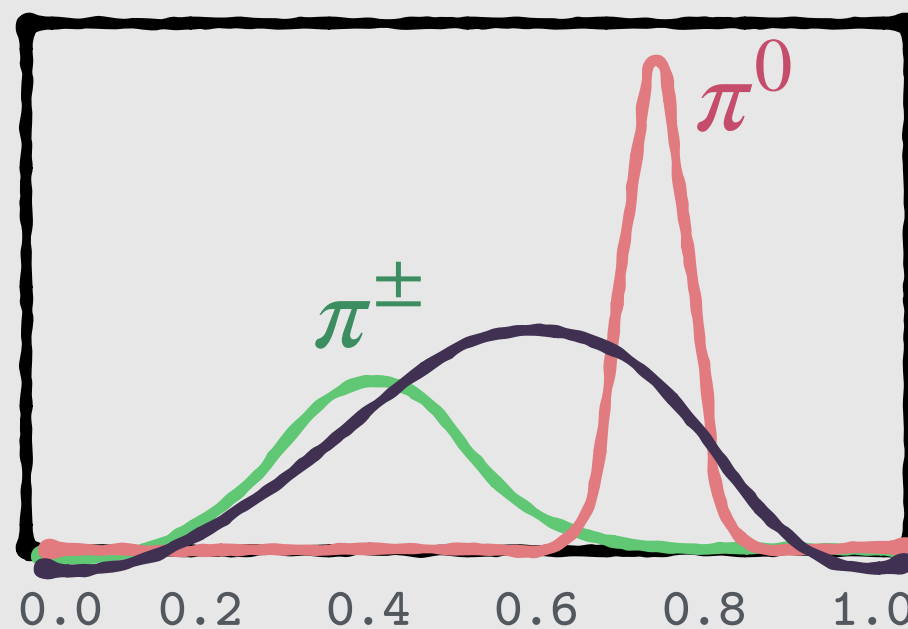
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ECAL vs HCAL Resolution

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$$\frac{1\% - 10\%}{\sqrt{E}}$$

- HAD energy resolution

$$\frac{50\% - 100\%}{\sqrt{E}}$$

- ECAL much better energy resolution than HCAL

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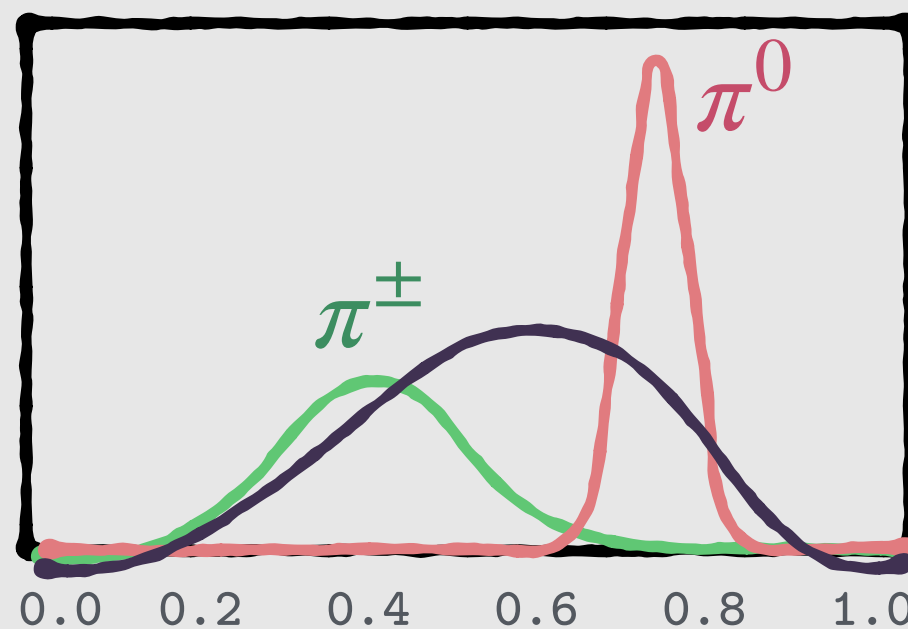
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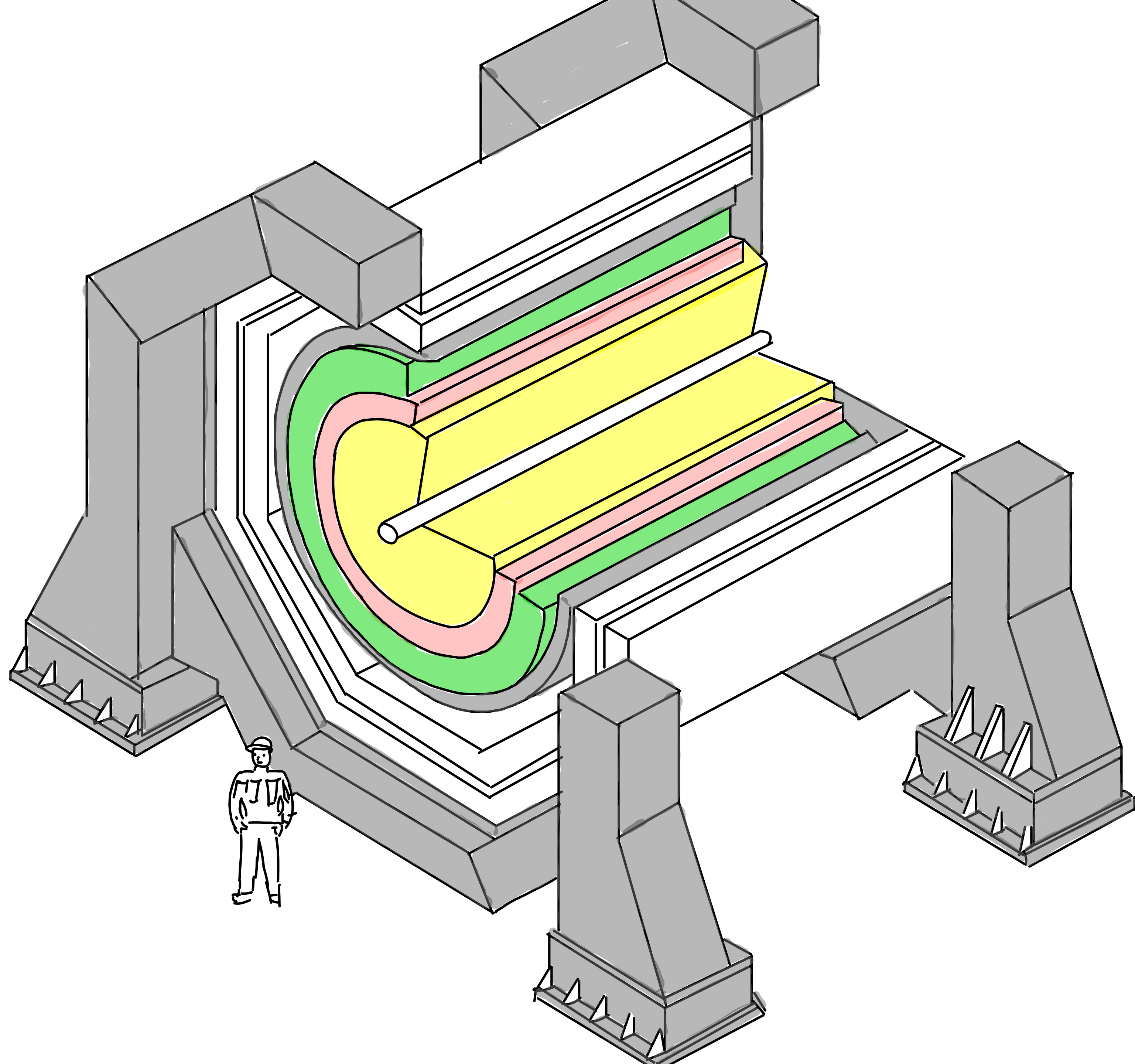
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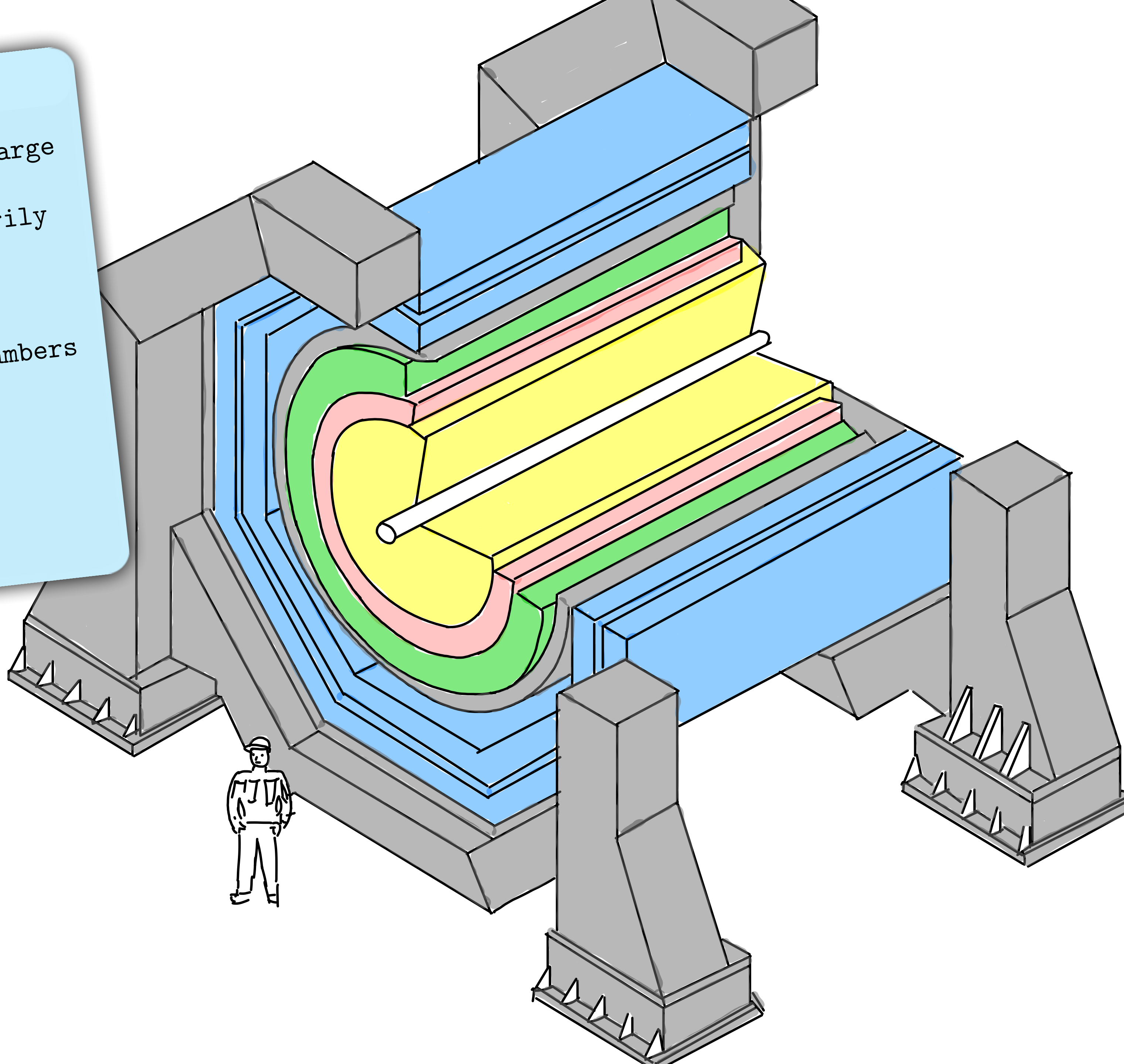
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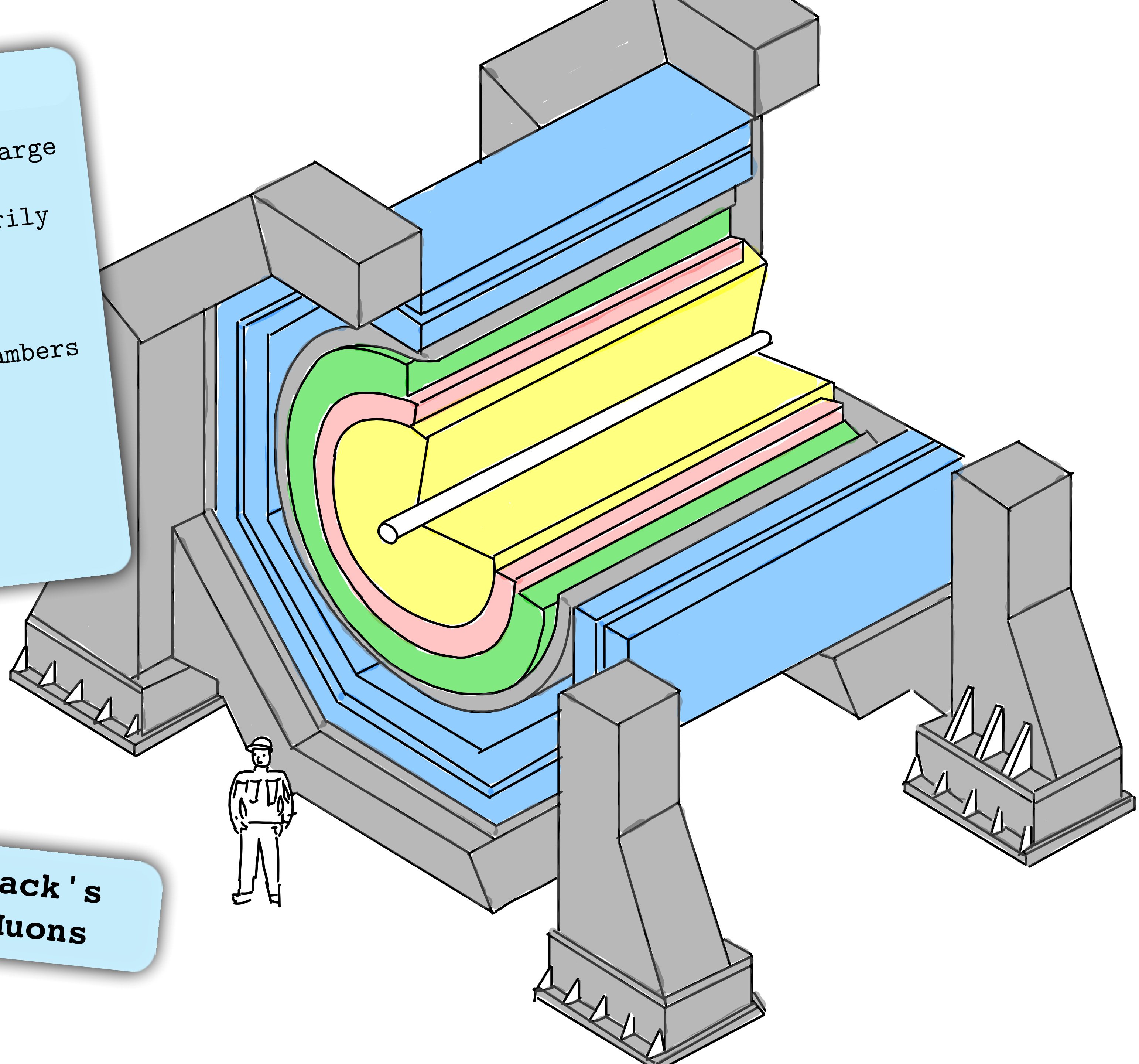
Muon Chambers

- Purpose: measure momentum + charge of muons (tracking)
- Muon signature is extraordinarily penetrating
 - Place chambers at outermost layers
- LHC Experiments: gas wire chambers
 - Resistive Plate Chambers
 - Drift Tubes
 - Cathode Strip Chambers
 - Thin Gap Chambers

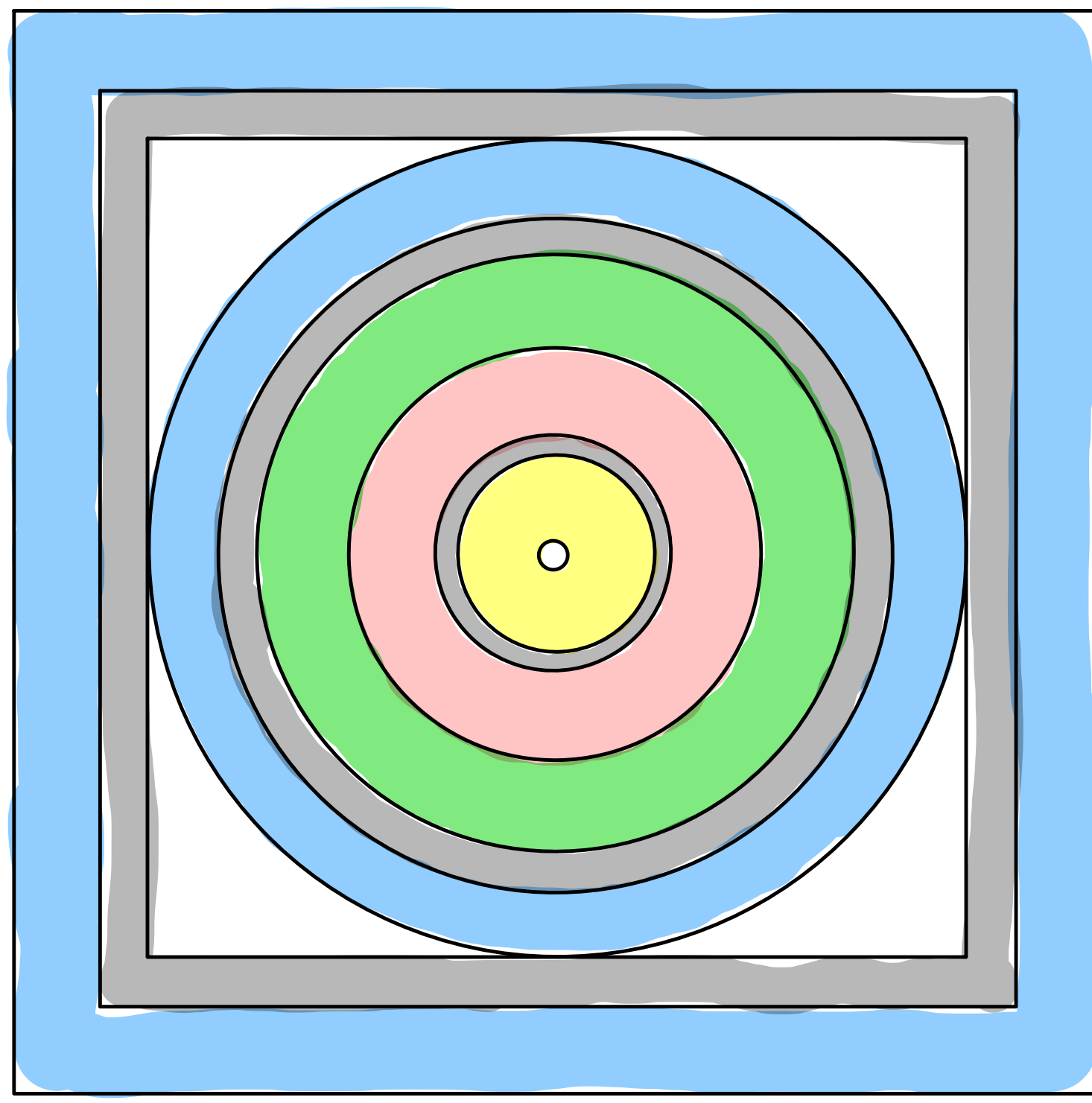
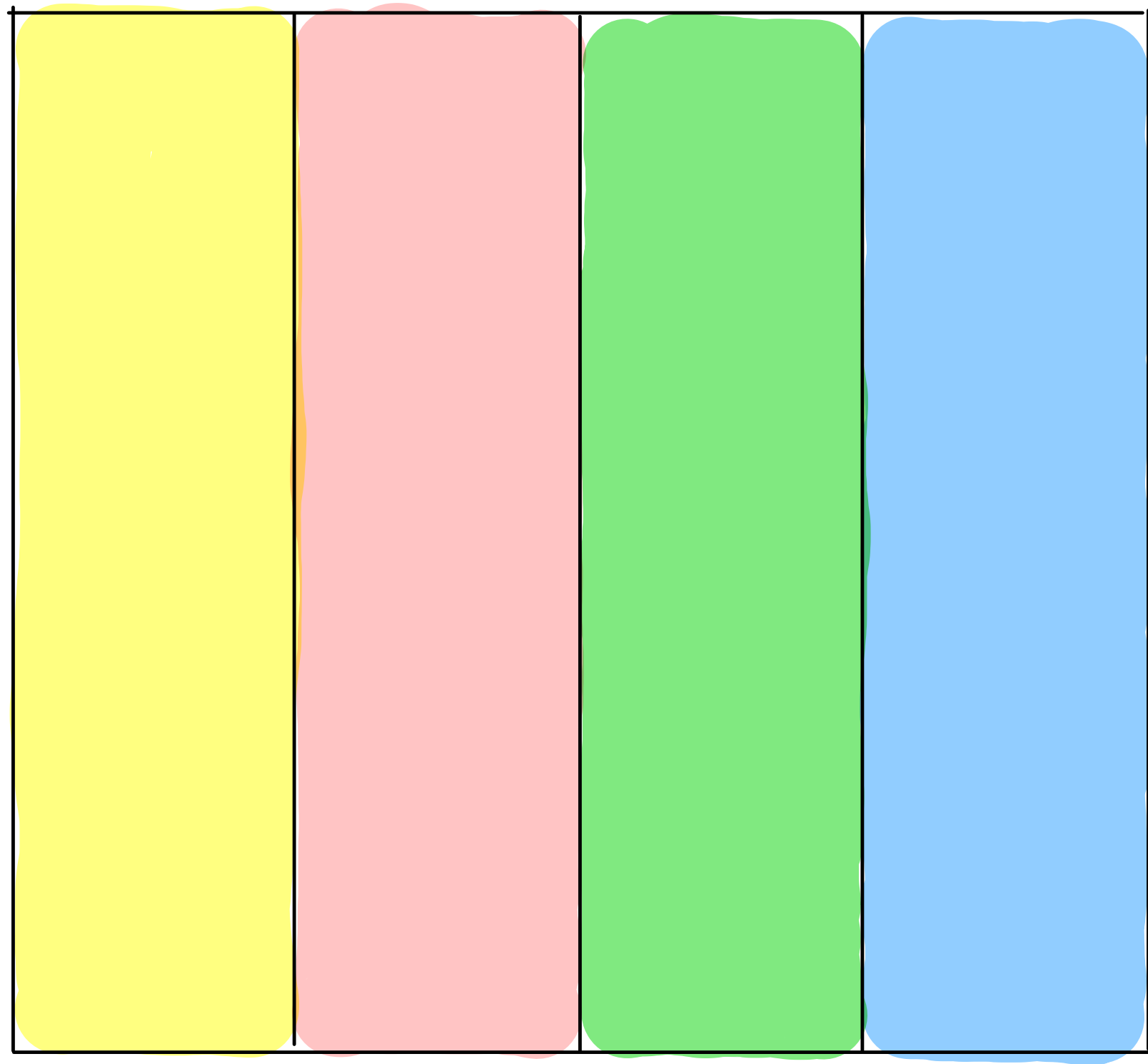


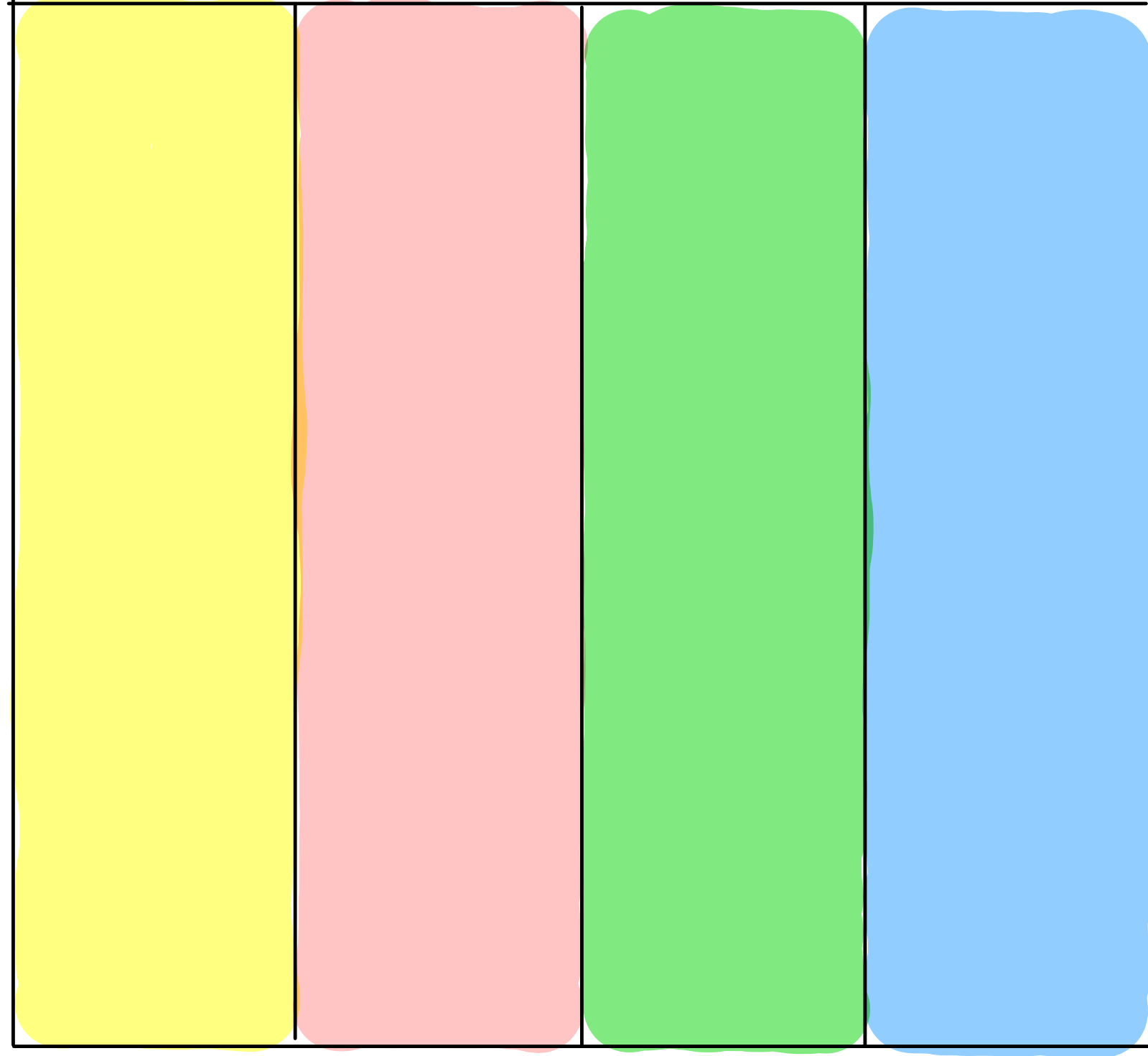
Muon Chambers

- Purpose: measure momentum + charge of muons (tracking)
- Muon signature is extraordinarily penetrating
 - Place chambers at outermost layers
- LHC Experiments: gas wire chambers
 - Resistive Plate Chambers
 - Drift Tubes
 - Cathode Strip Chambers
 - Thin Gap Chambers

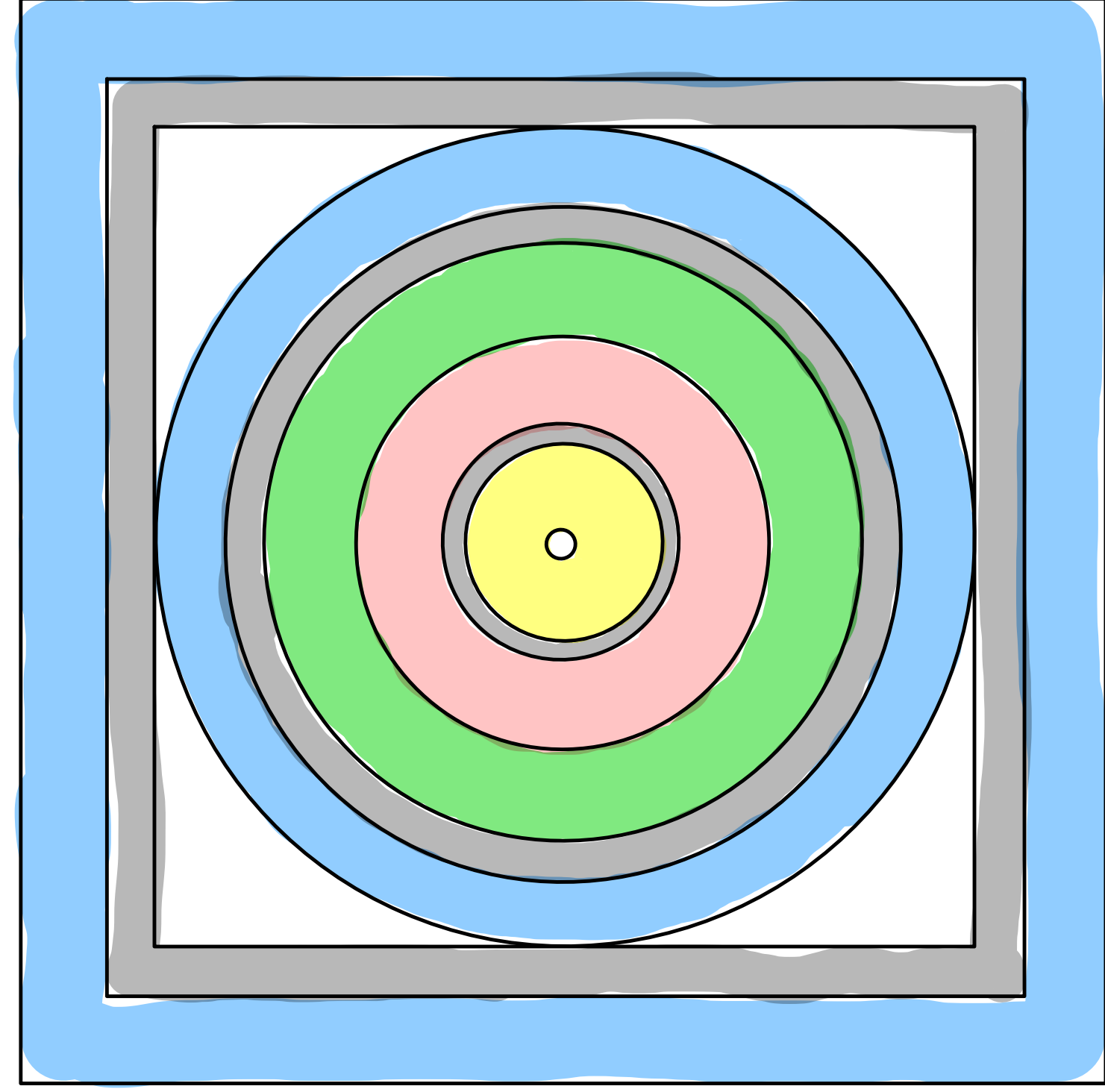


See Kevin Black's
Lecture on Muons

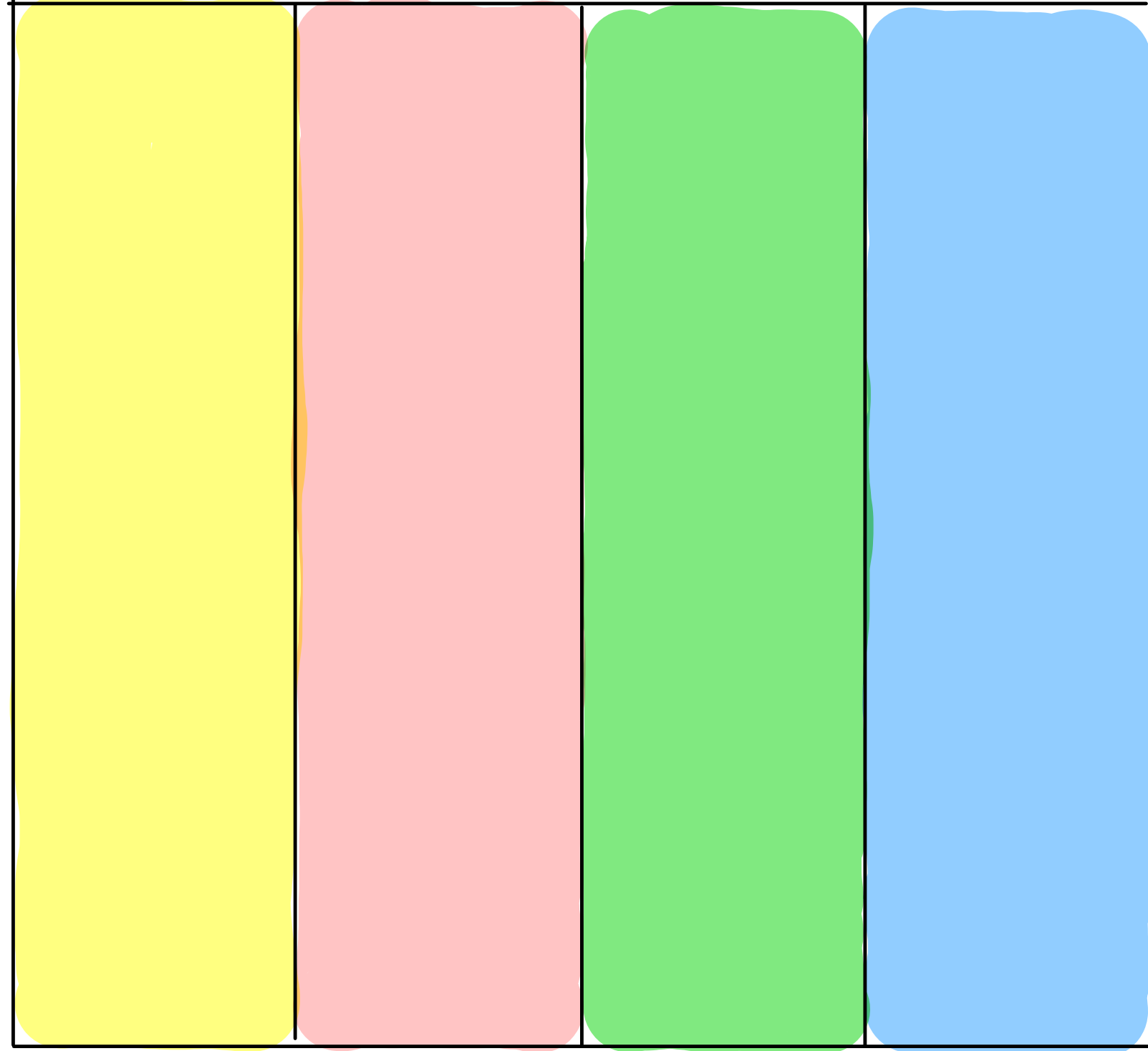






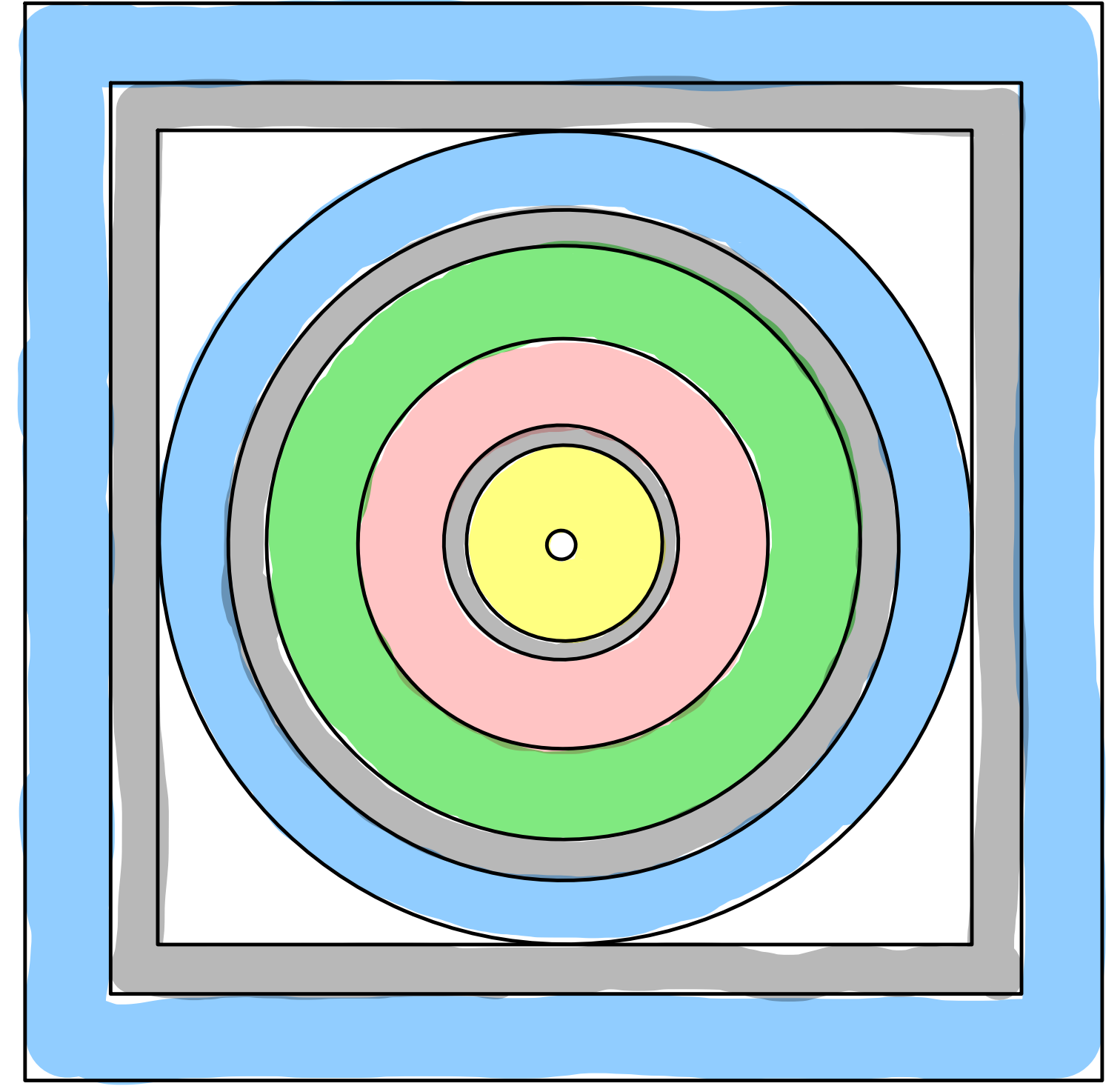
 Beam Pipe



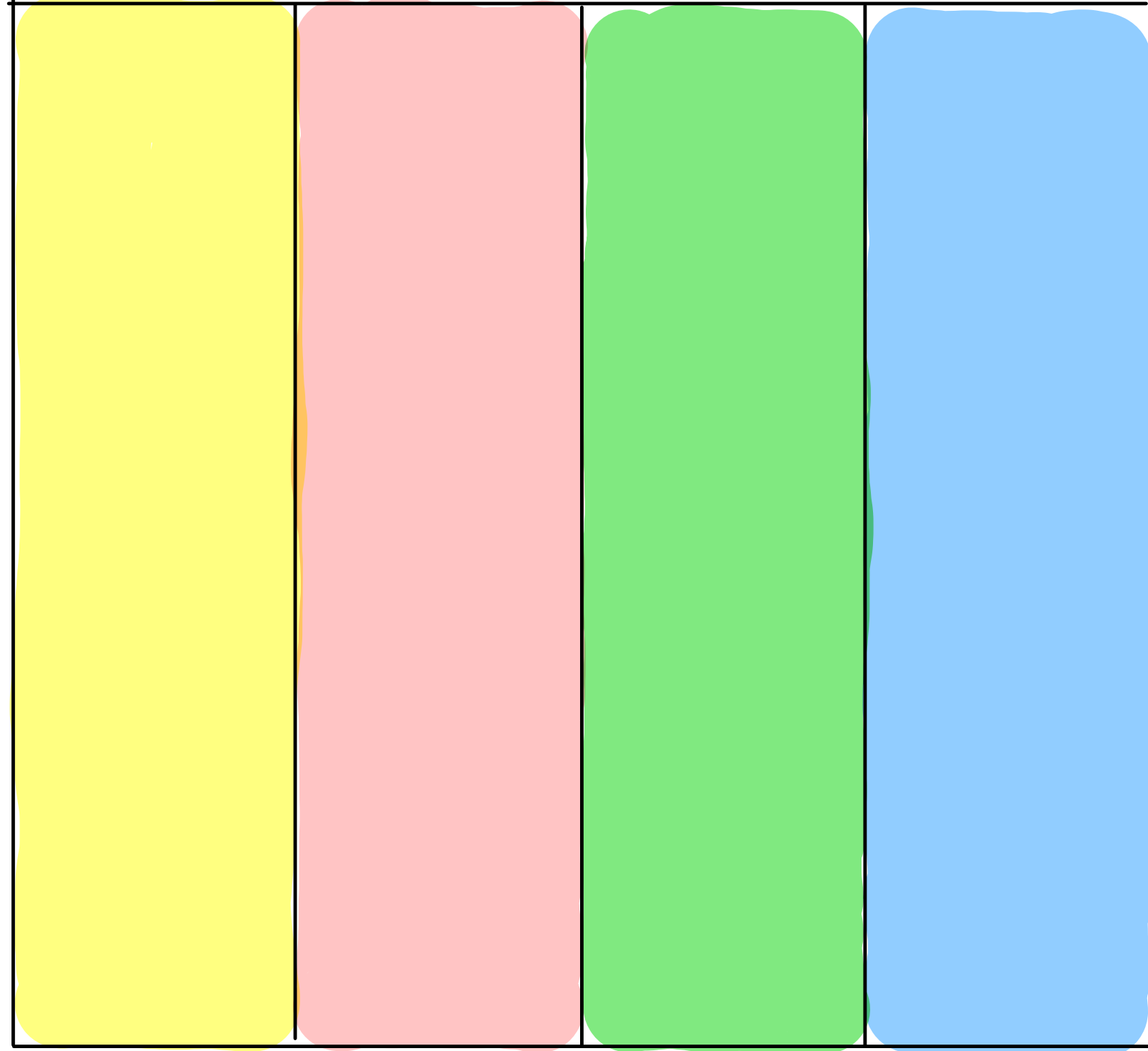
Tracking Chamber






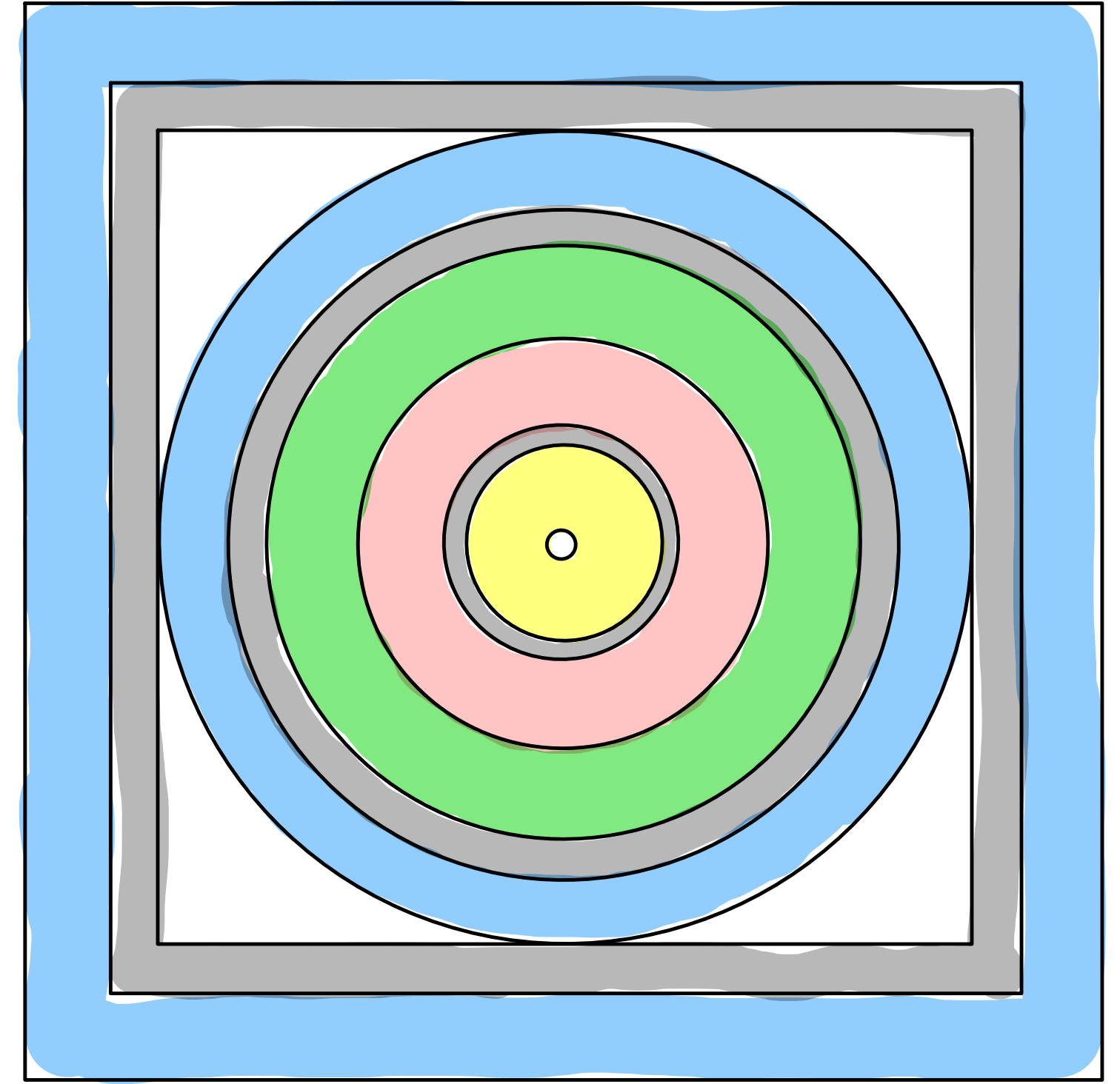
-  Beam Pipe
-  Tracking Chamber

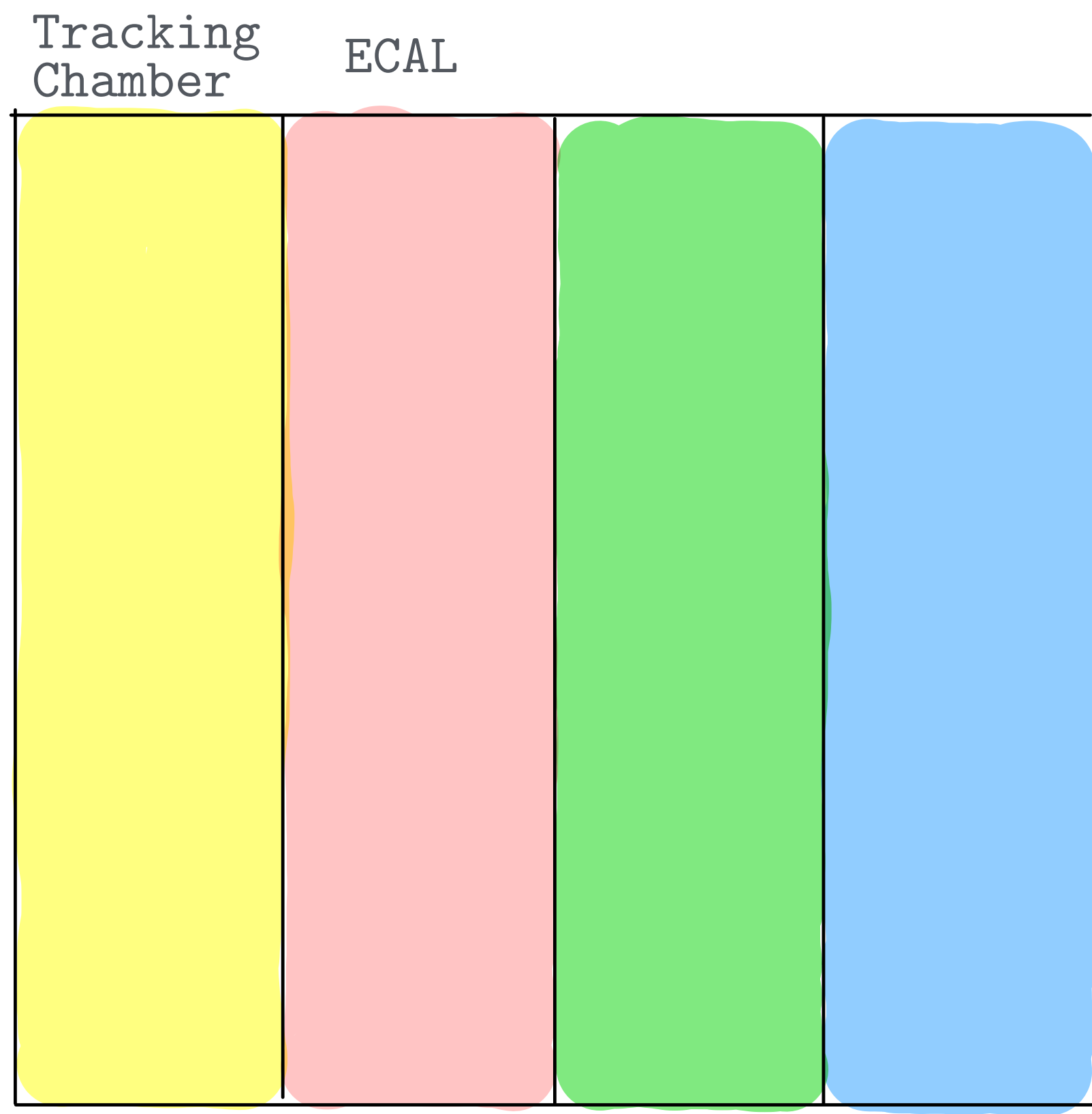





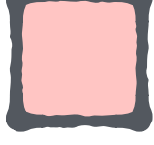
Tracking Chamber

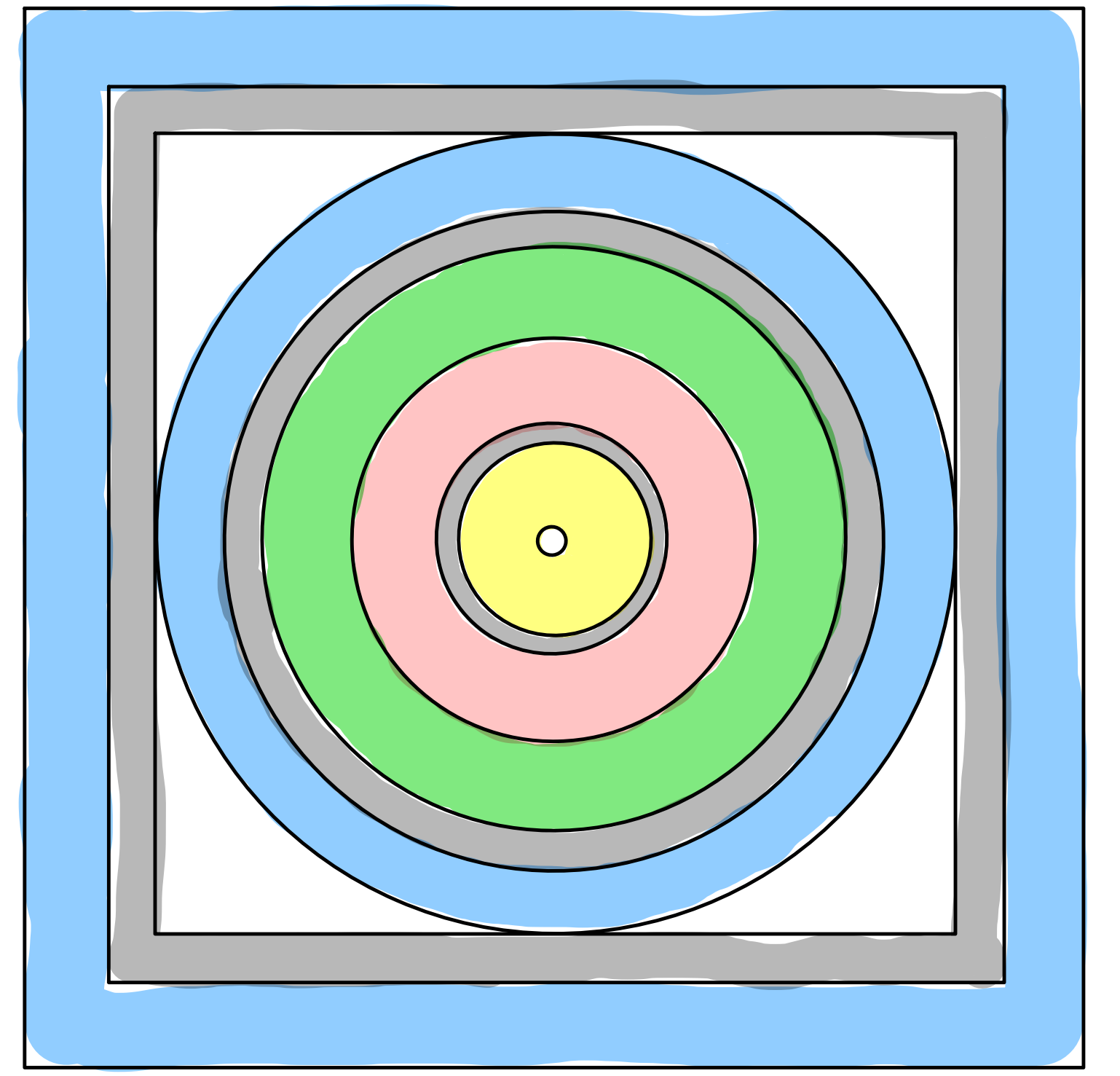


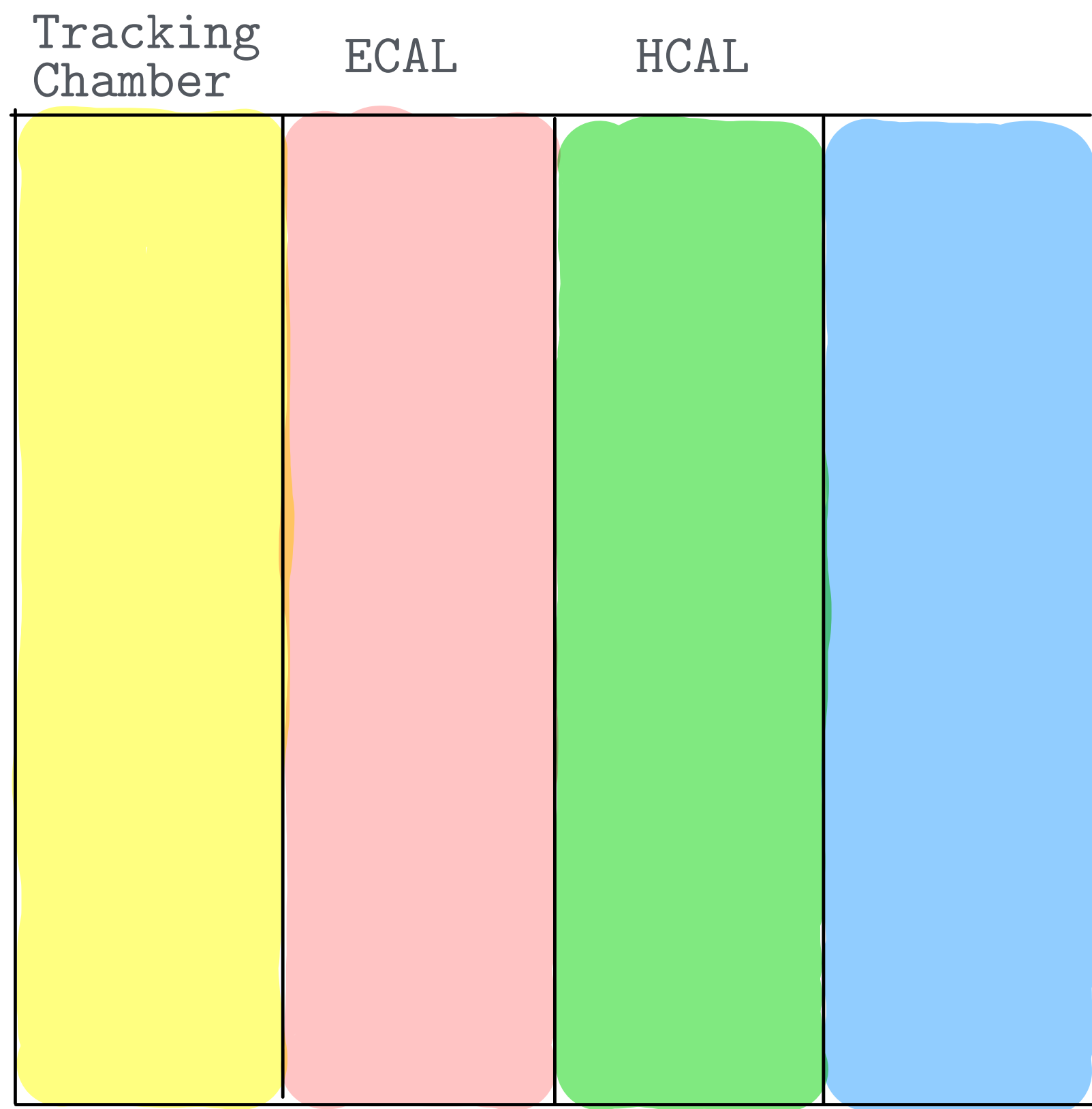
-  Beam Pipe
-  Tracking Chamber
-  Solenoid



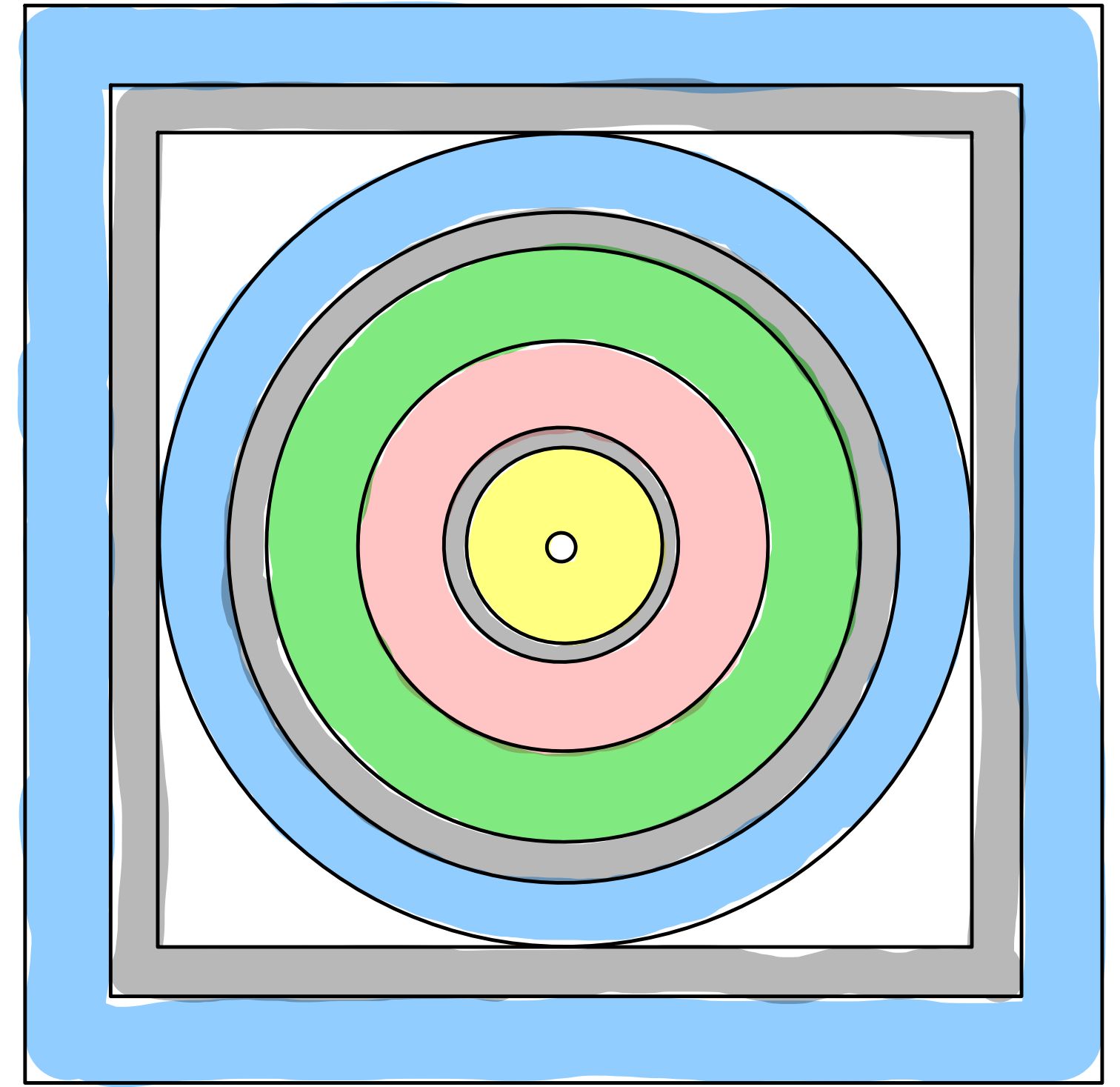


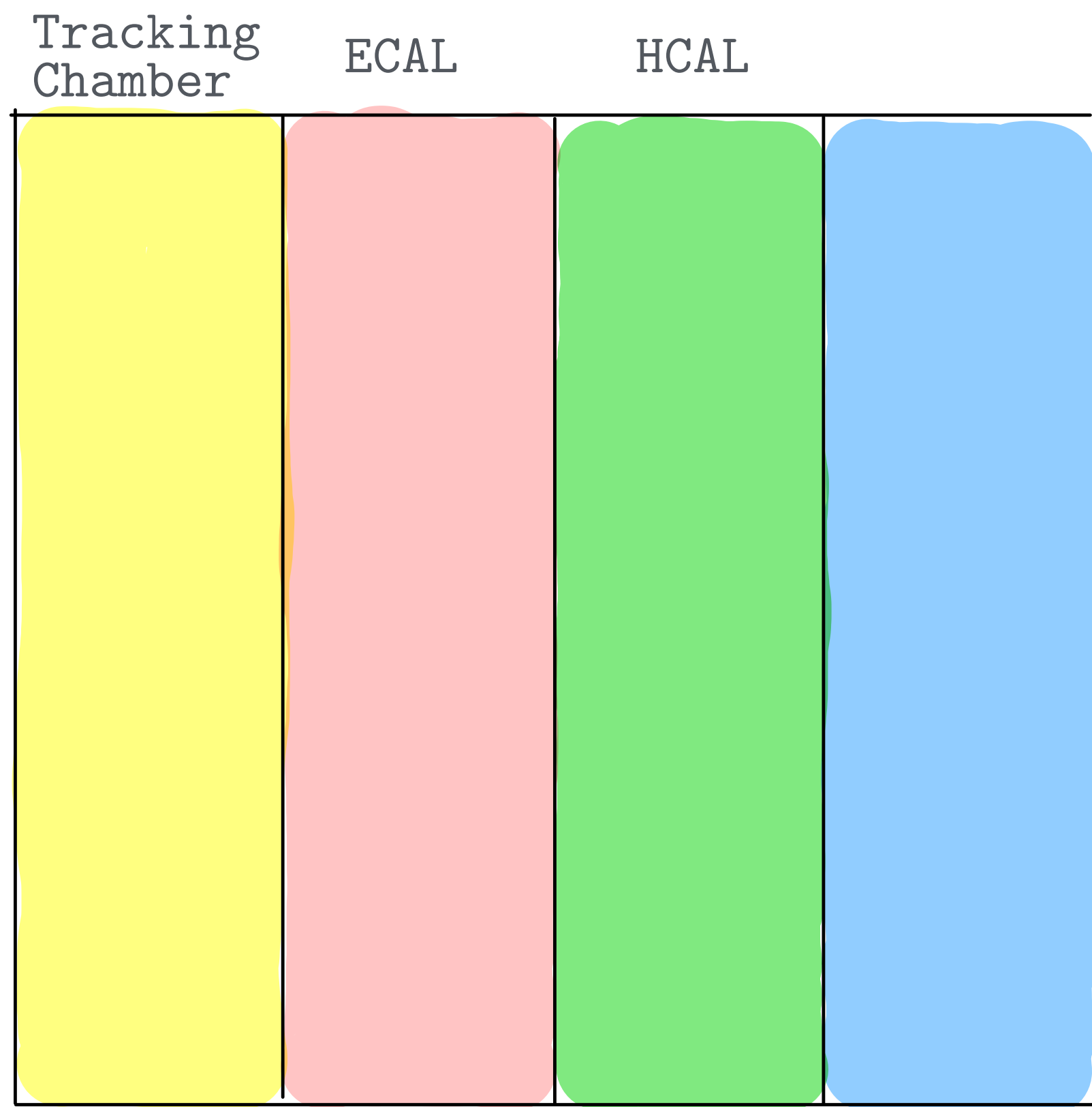
-  Beam Pipe
-  Tracking Chamber
-  Solenoid
-  ECAL



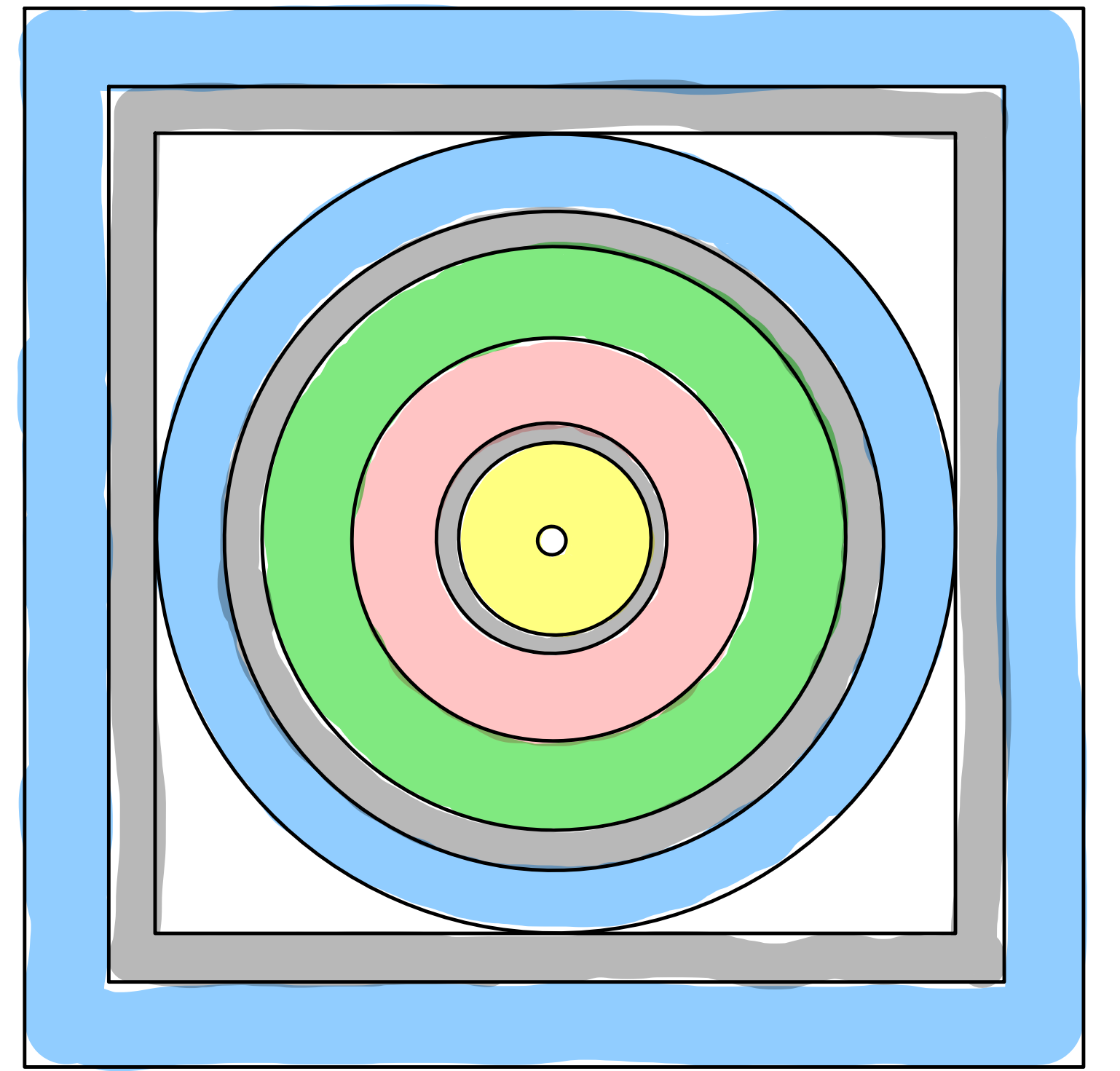


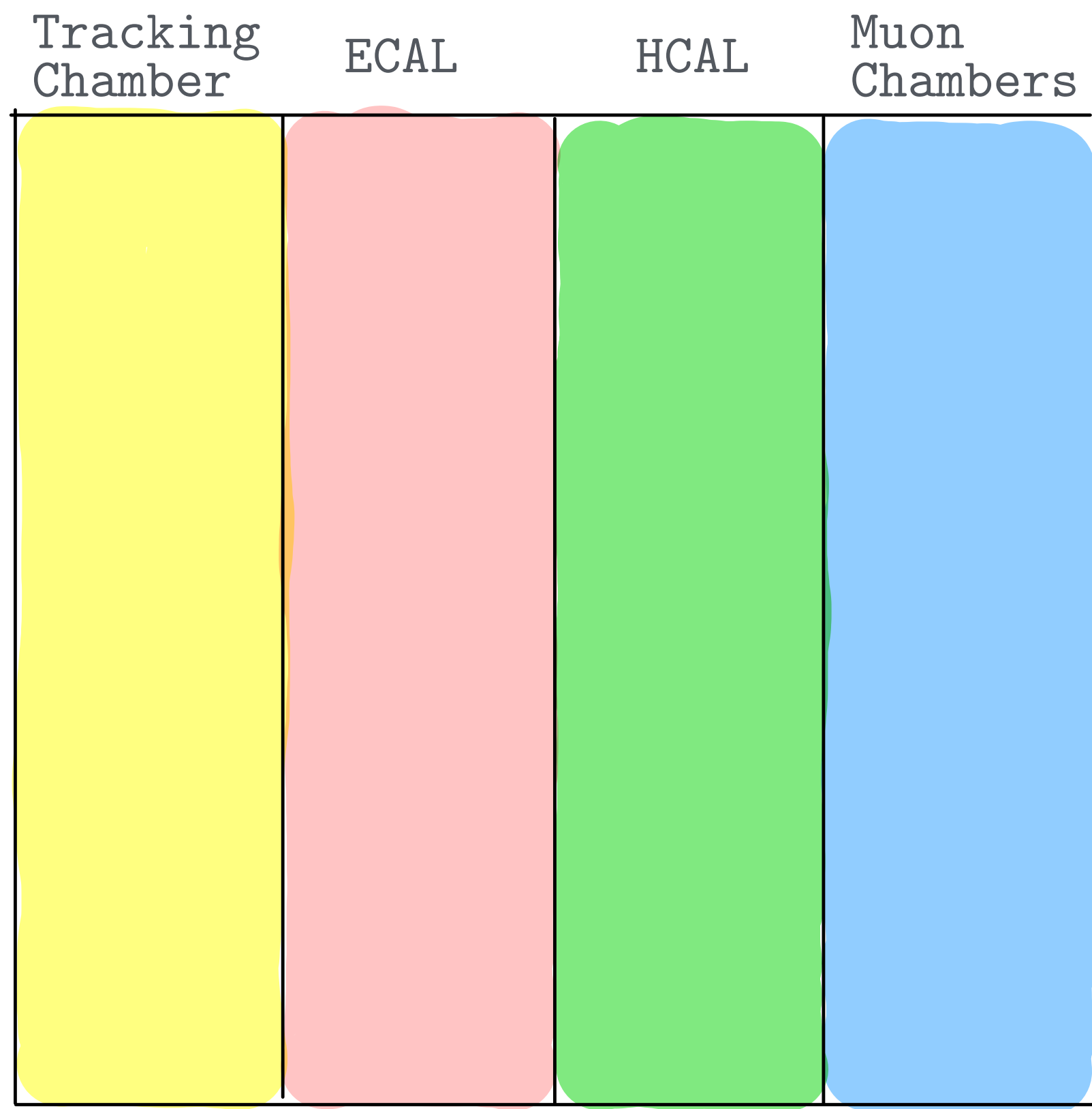
- Beam Pipe
- Tracking Chamber
- Solenoid
- ECAL
- HCAL



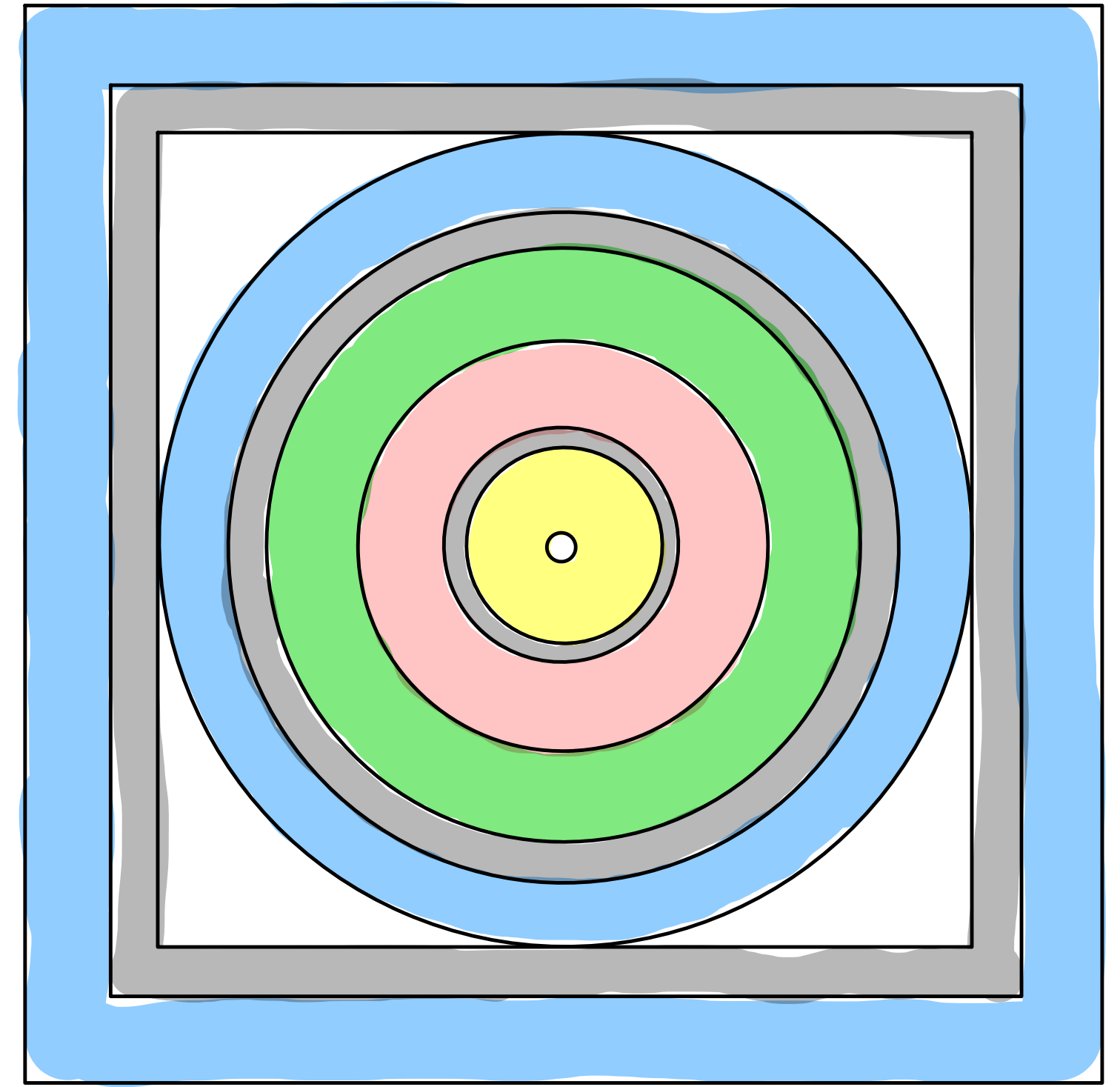


-  Beam Pipe
-  Tracking Chamber
-  Solenoid
-  ECAL
-  HCAL
-  Return Yoke

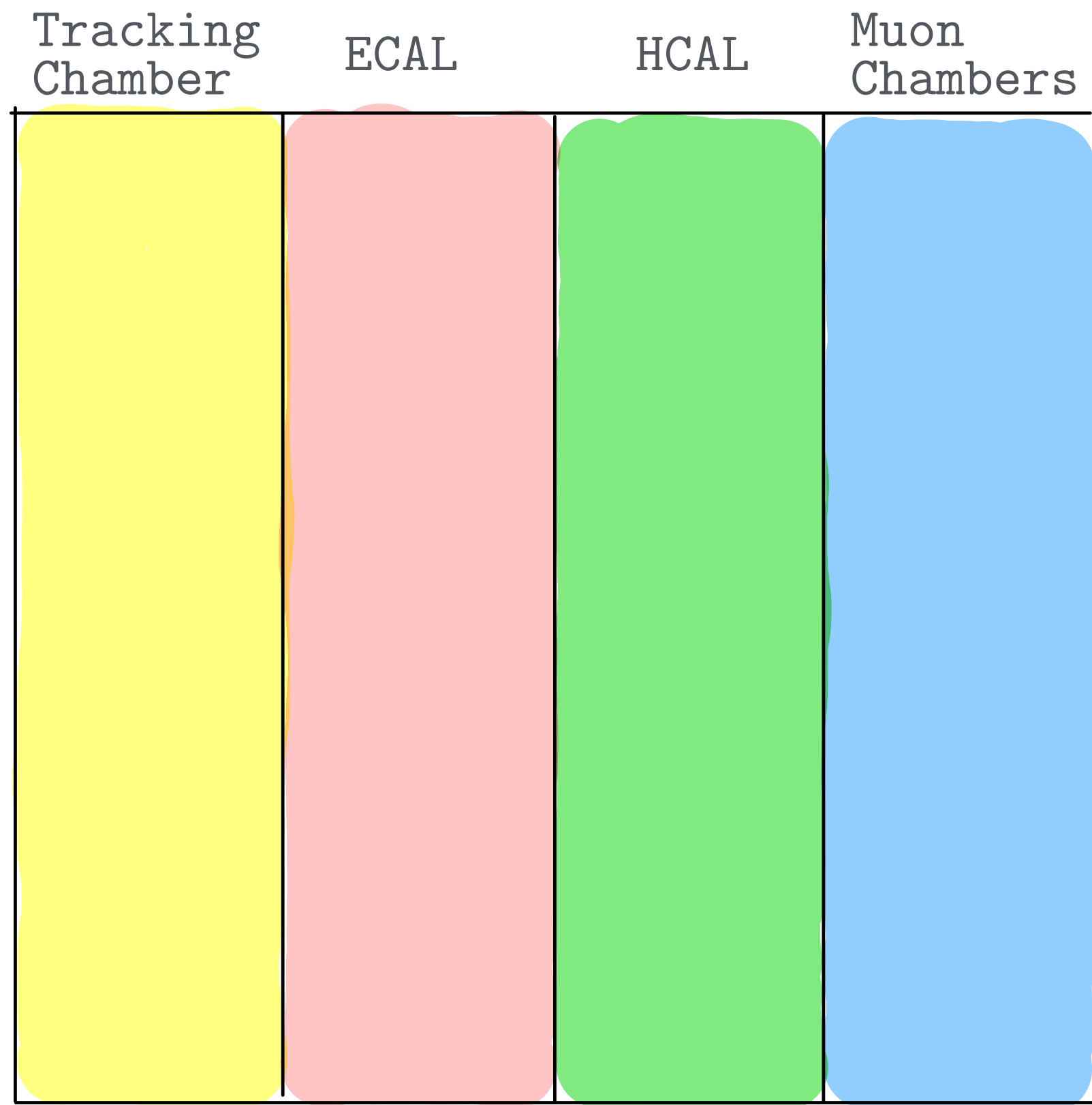






- Beam Pipe
- Tracking Chamber
- Solenoid
- ECAL
- HCAL
- Return Yoke
- Muon Chambers

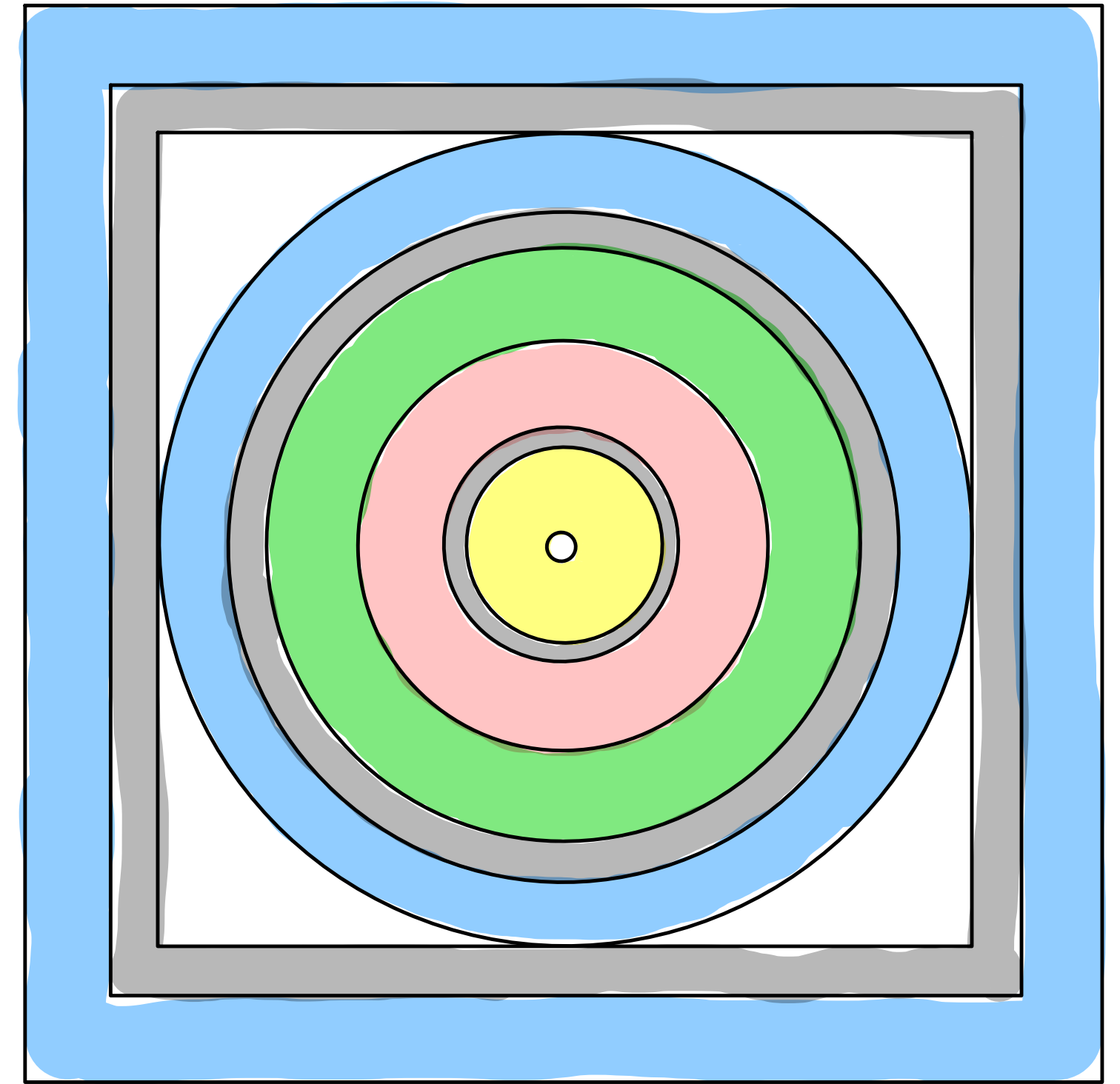


γ

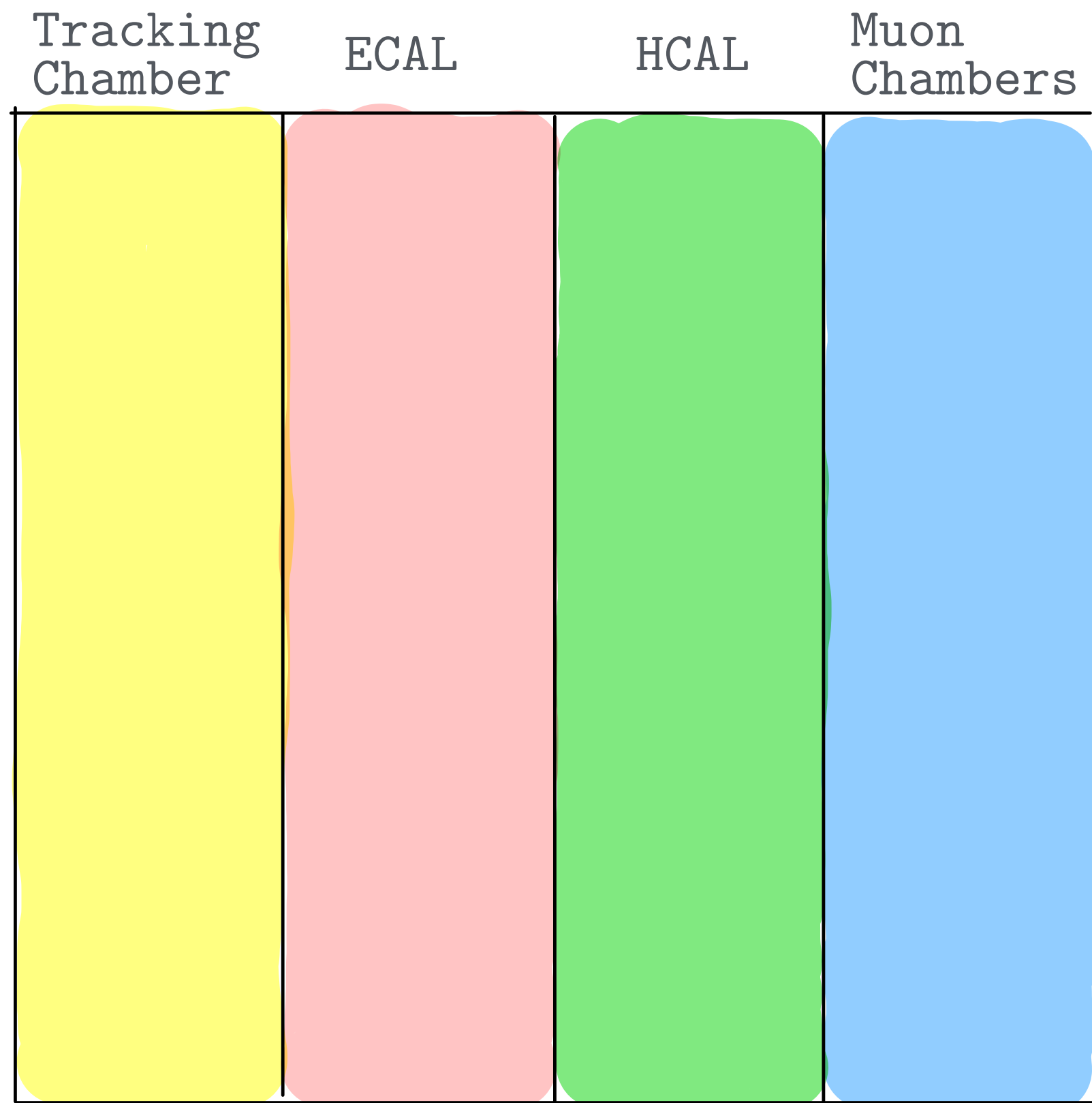


-  Beam Pipe
-  Tracking Chamber
-  Solenoid
-  ECAL
-  HCAL
-  Return Yoke
-  Muon Chambers

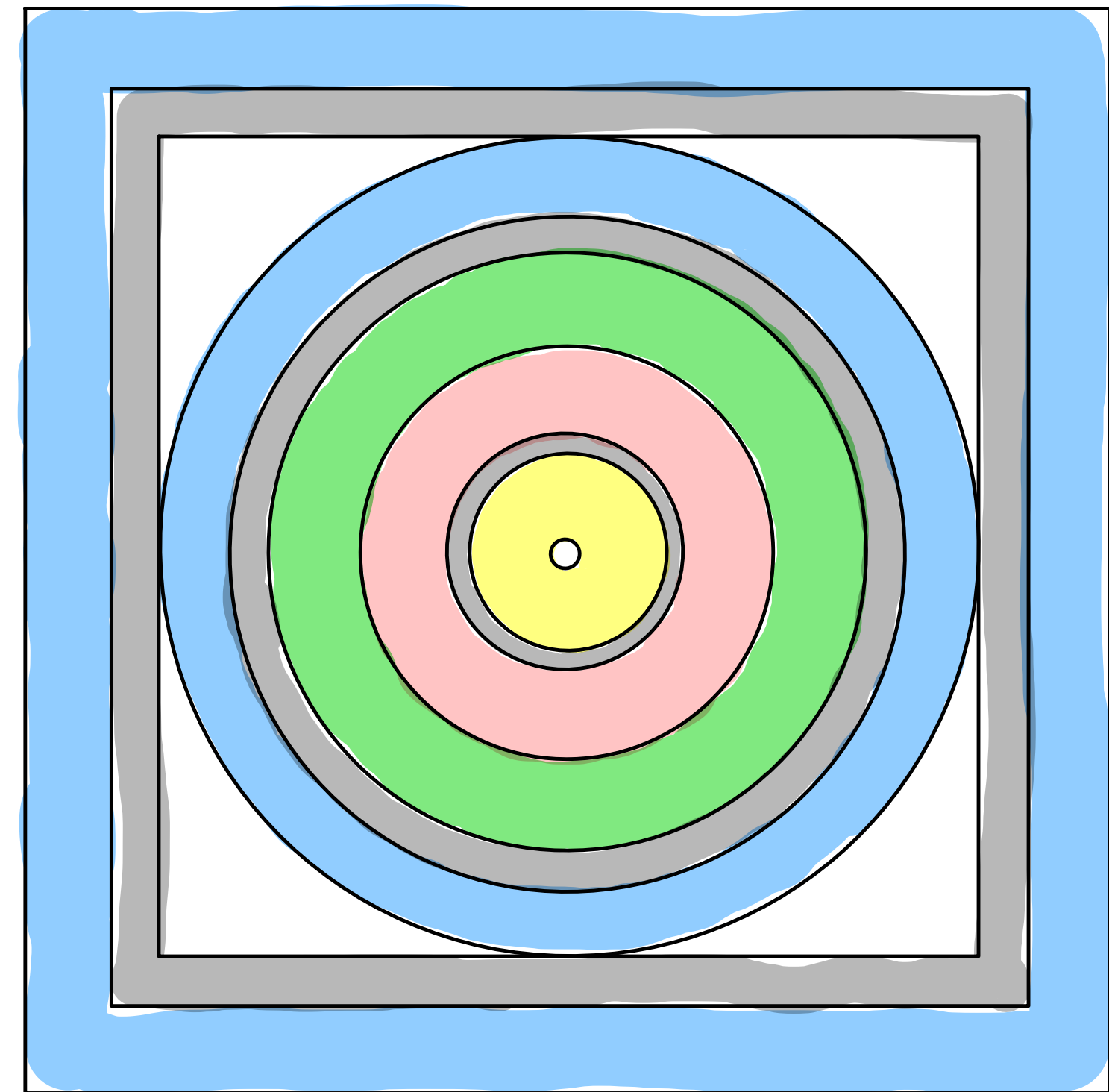
● Photons



γ

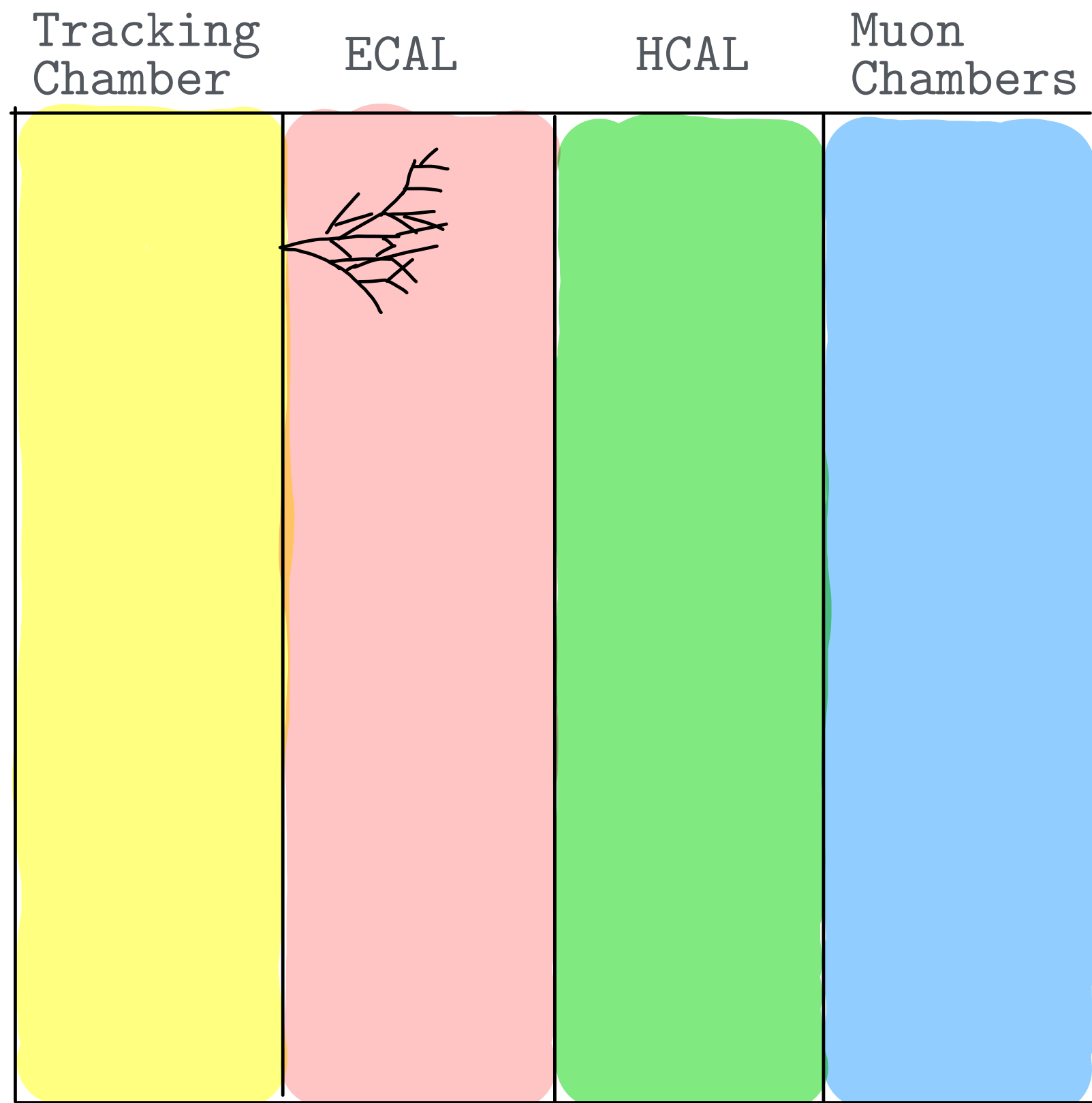





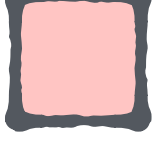


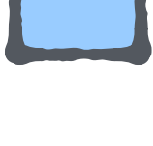
- Beam Pipe
- Tracking Chamber
- Solenoid
- ECAL
- HCAL
- Return Yoke
- Muon Chambers

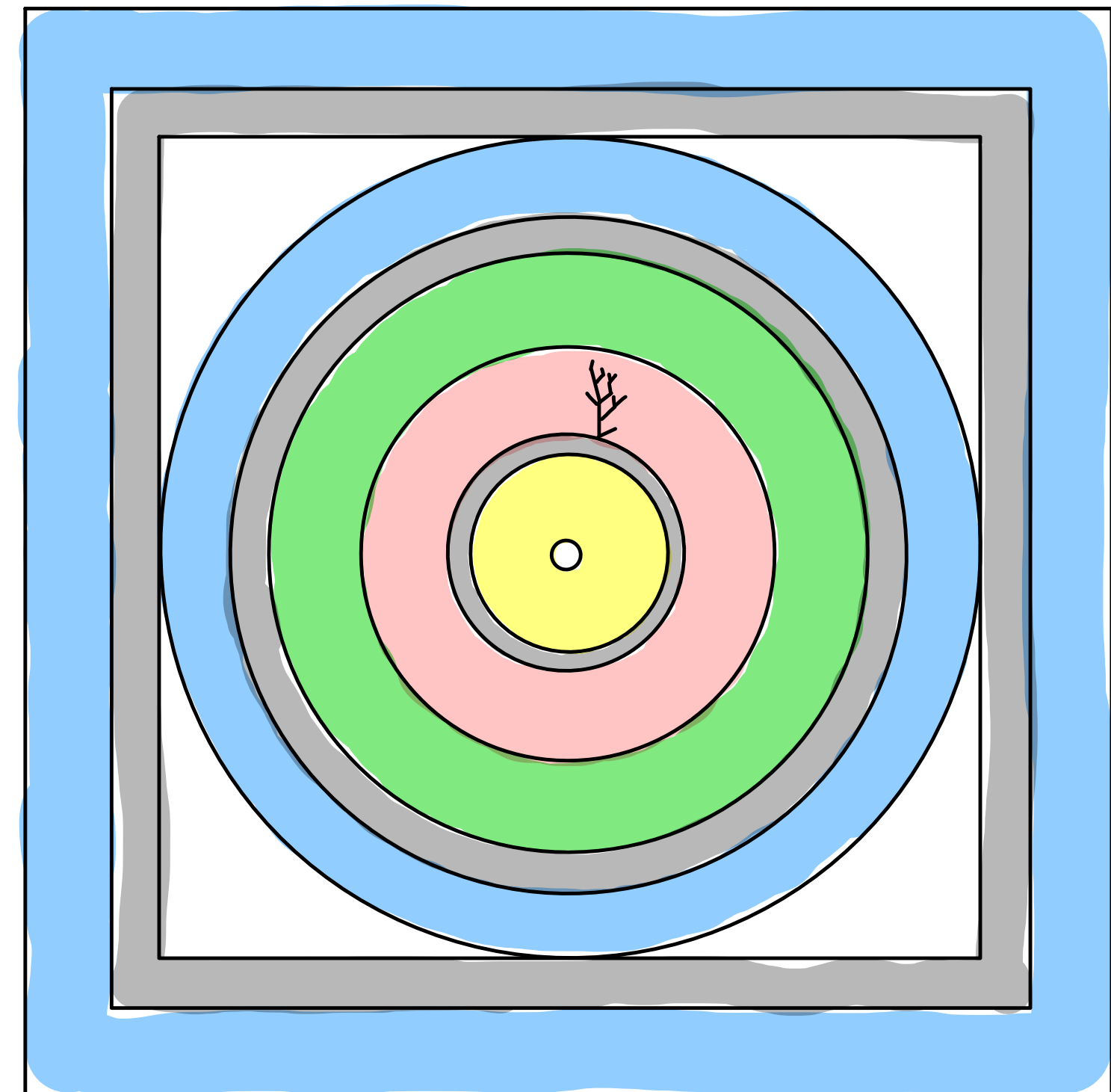


- Photons
 - Deposit all energy in EM; no track

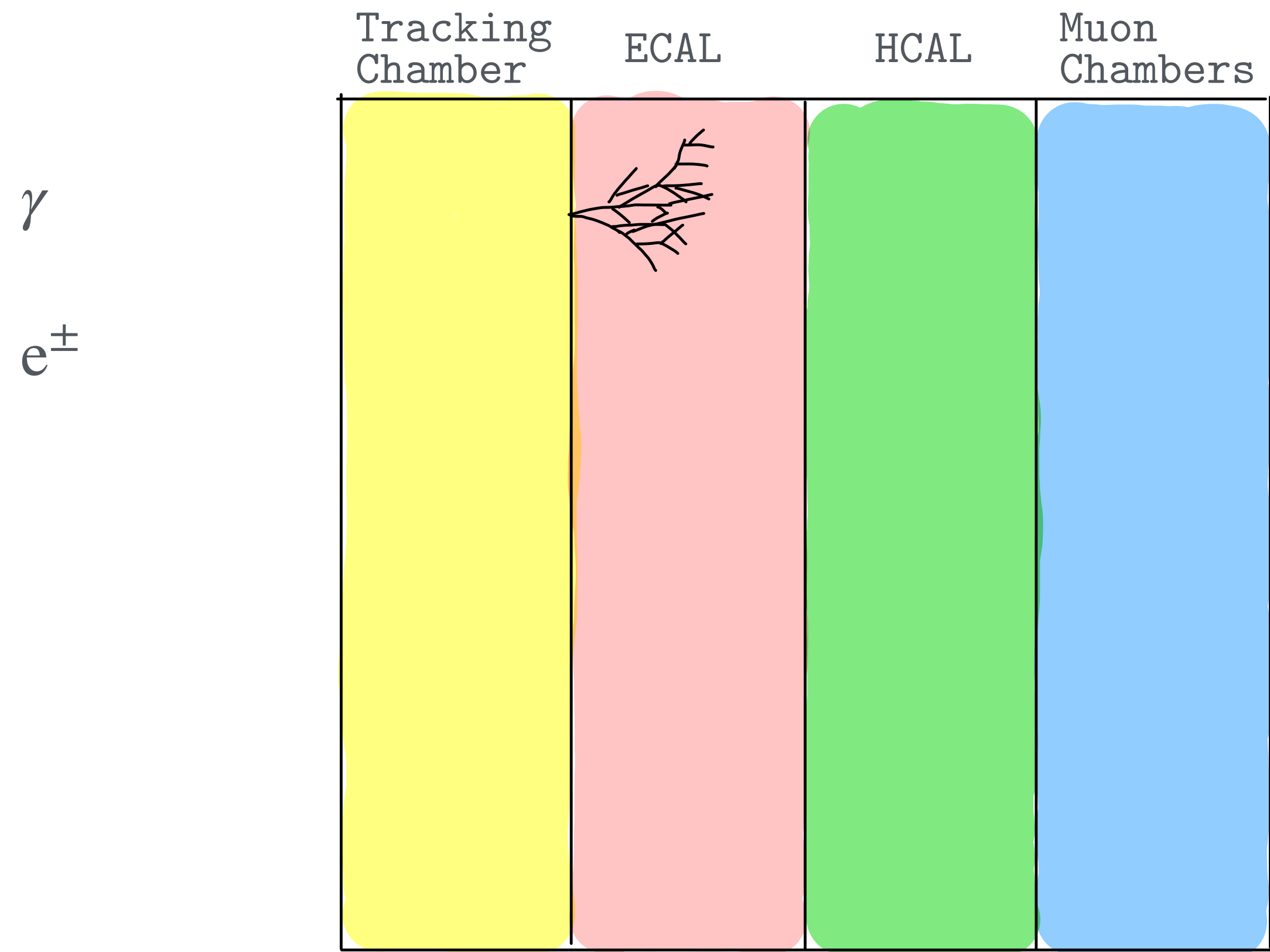
γ



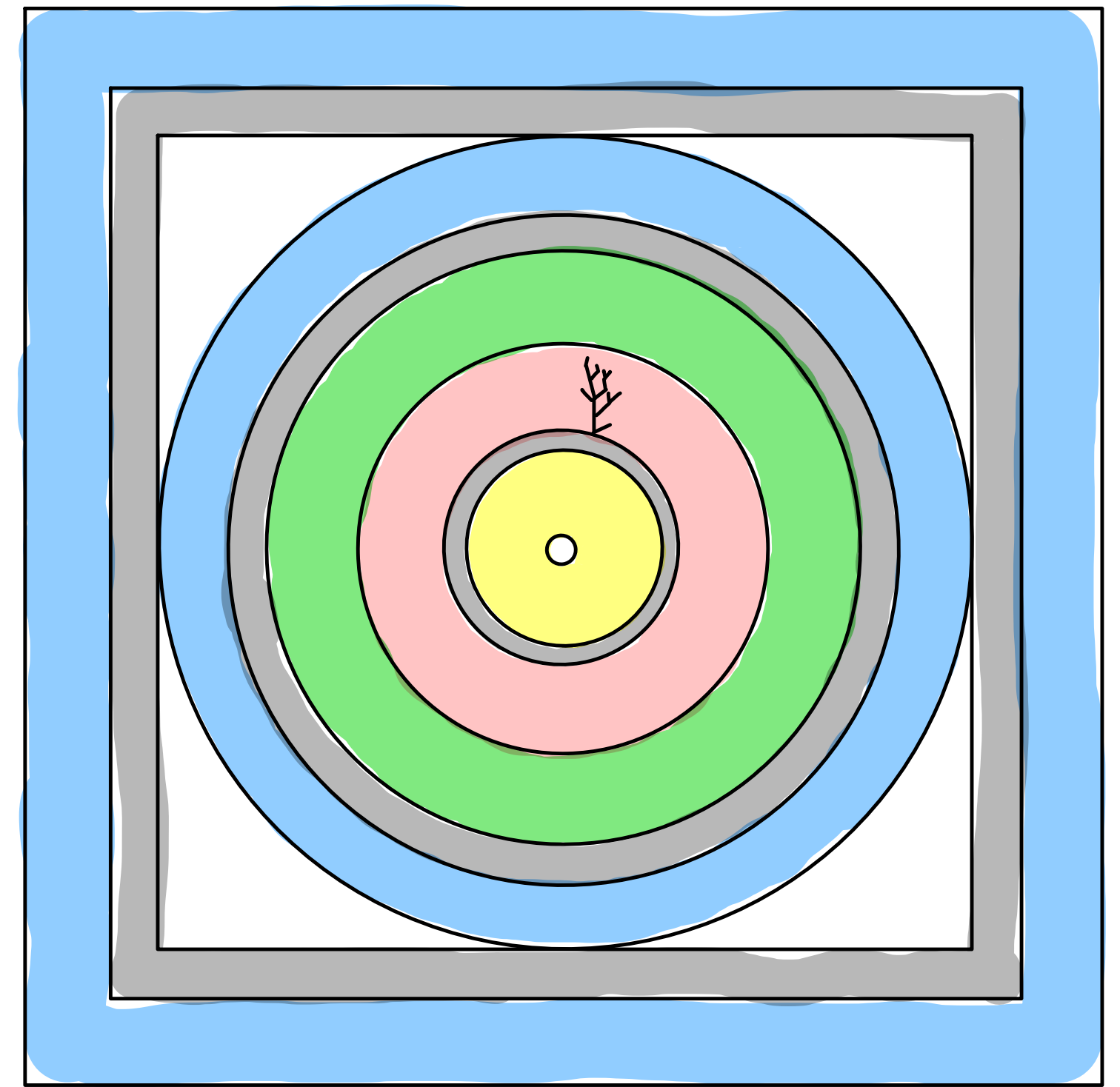
-  Beam Pipe
-  Tracking Chamber
-  Solenoid
-  ECAL
-  HCAL
-  Return Yoke
-  Muon Chambers



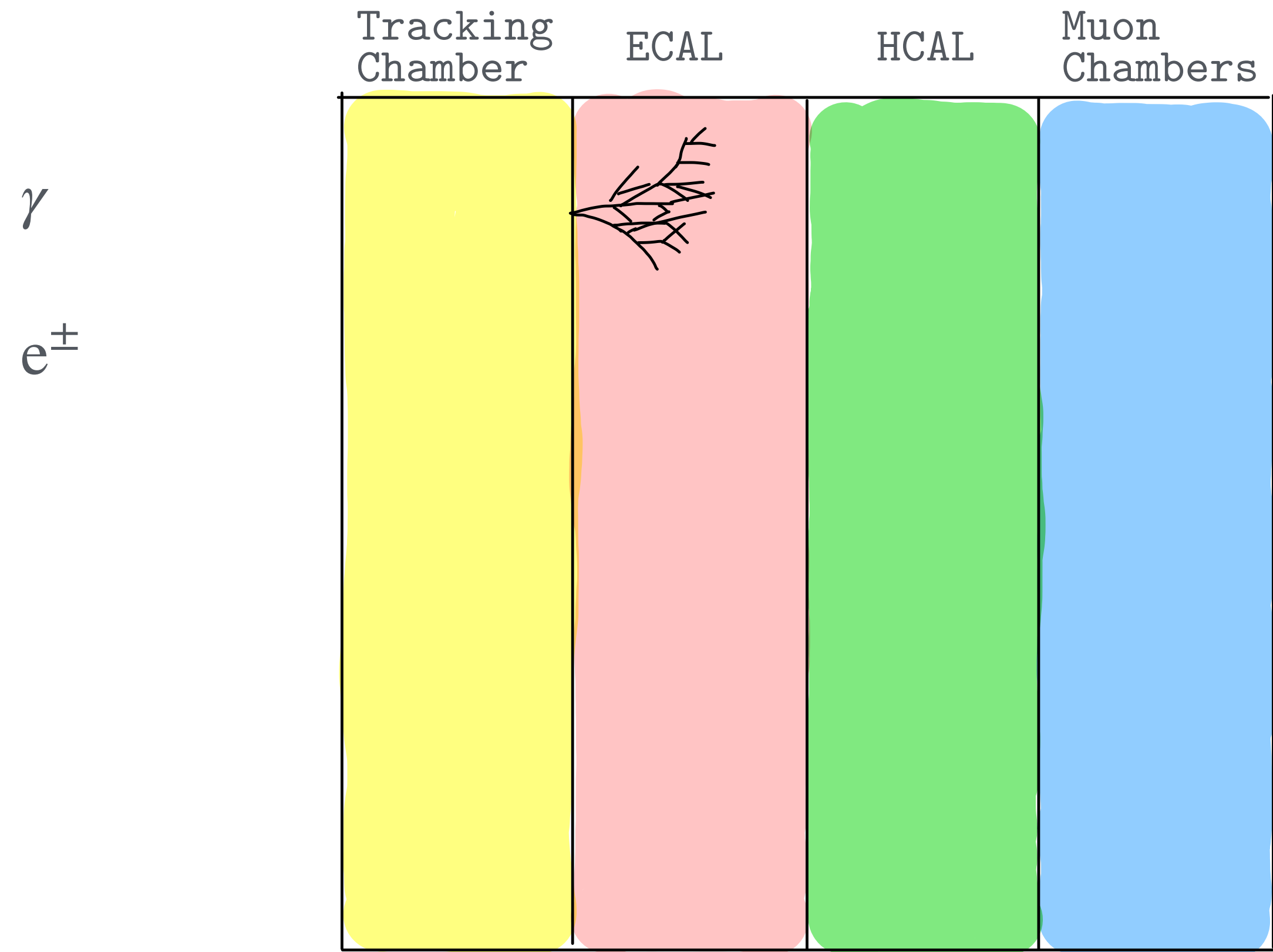
- Photons
 - Deposit all energy in EM; no track



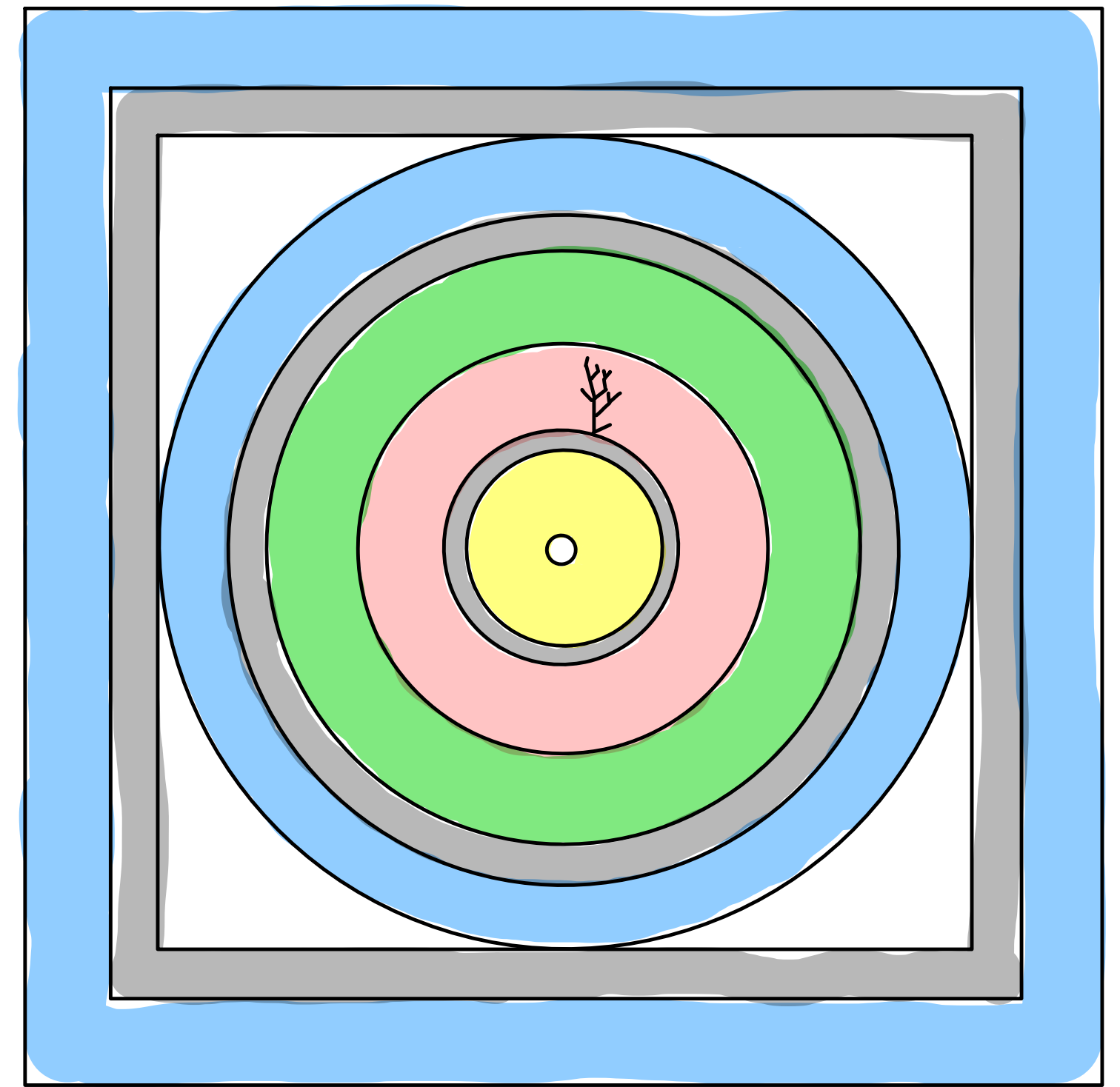
- Beam Pipe
- Tracking Chamber
- Solenoid
- ECAL
- HCAL
- Return Yoke
- Muon Chambers



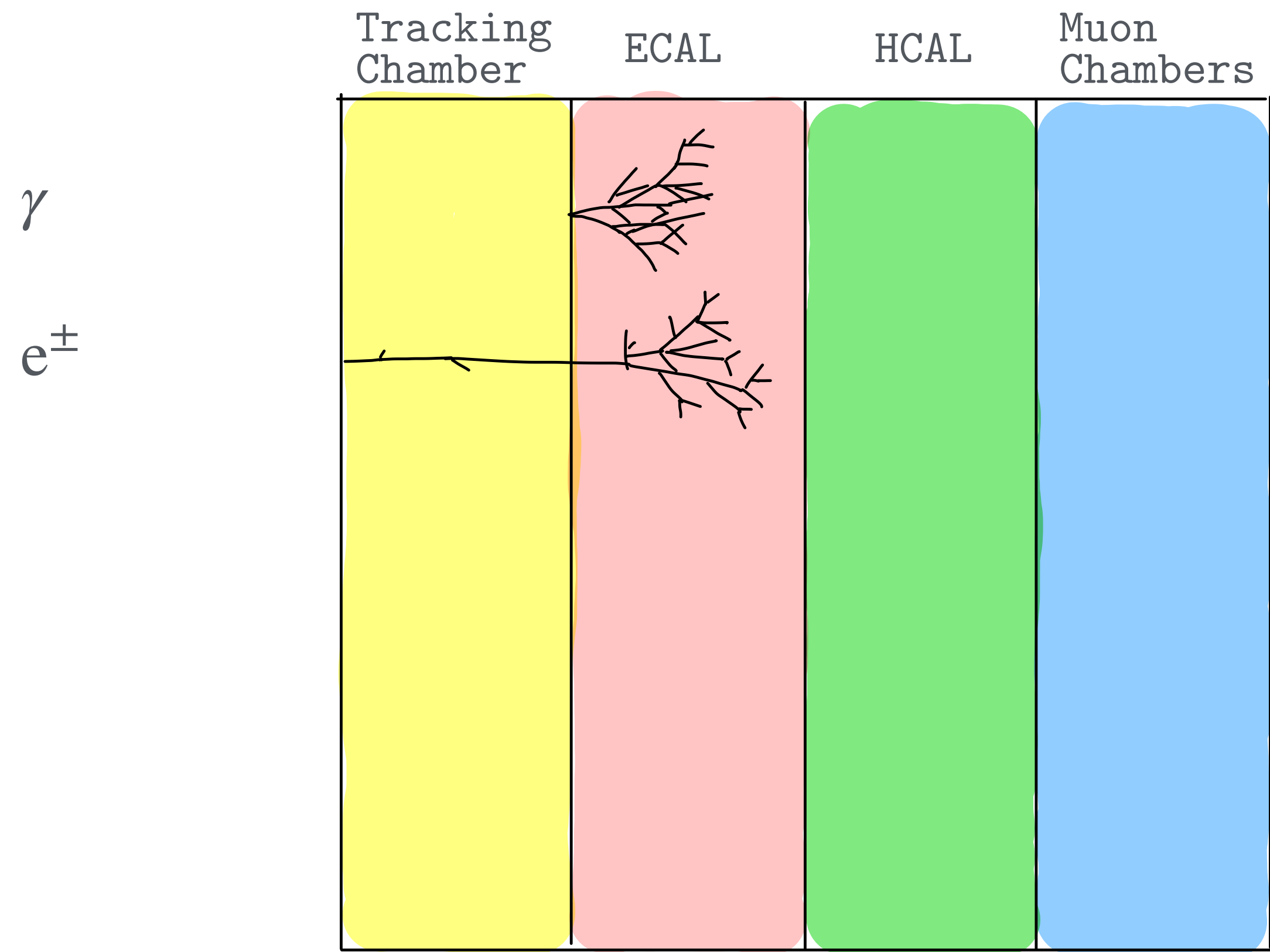
- Photons
 - Deposit all energy in EM; no track
- Electrons






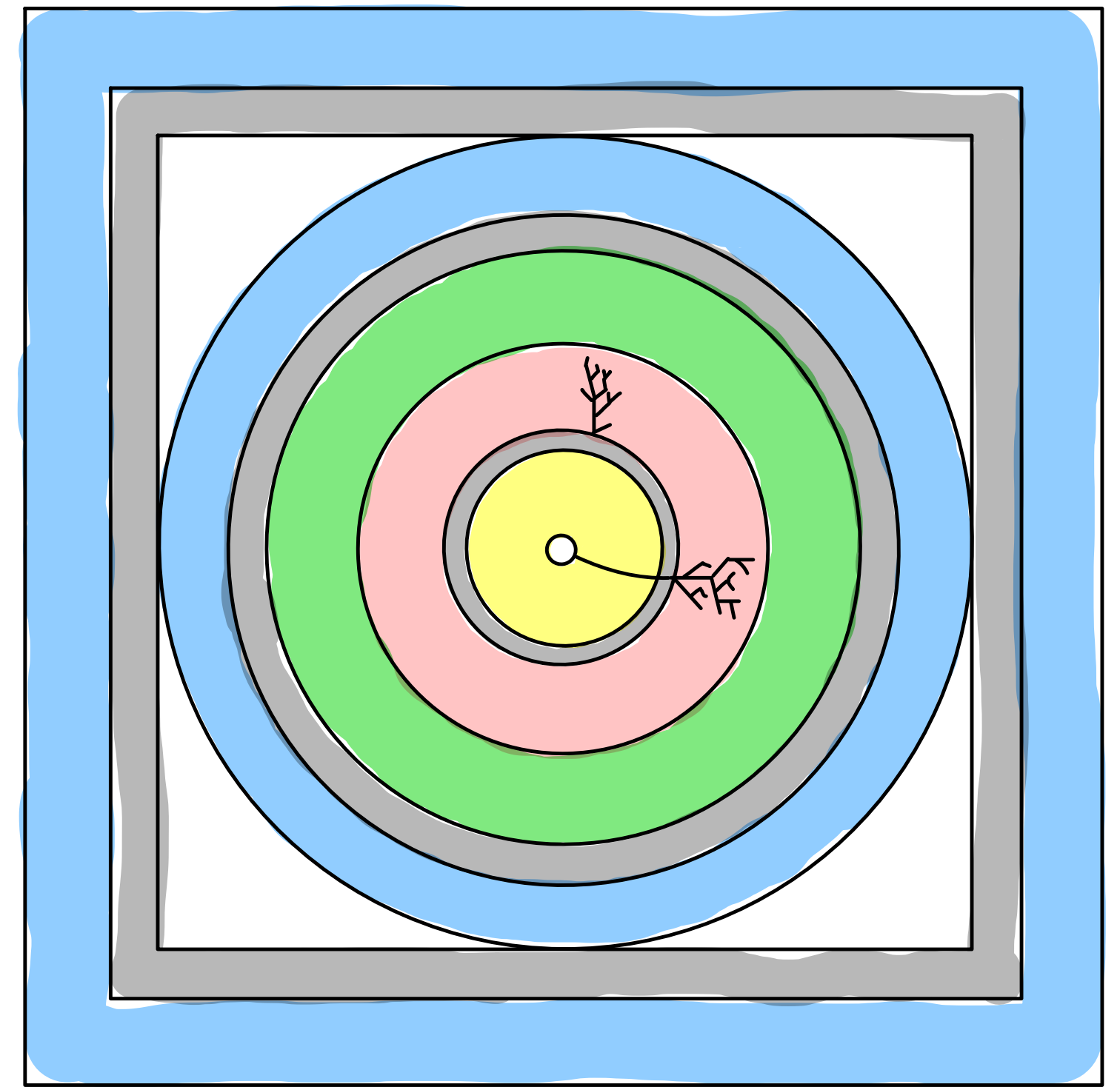
- Beam Pipe
- Tracking Chamber
- Solenoid
- ECAL
- HCAL
- Return Yoke
- Muon Chambers



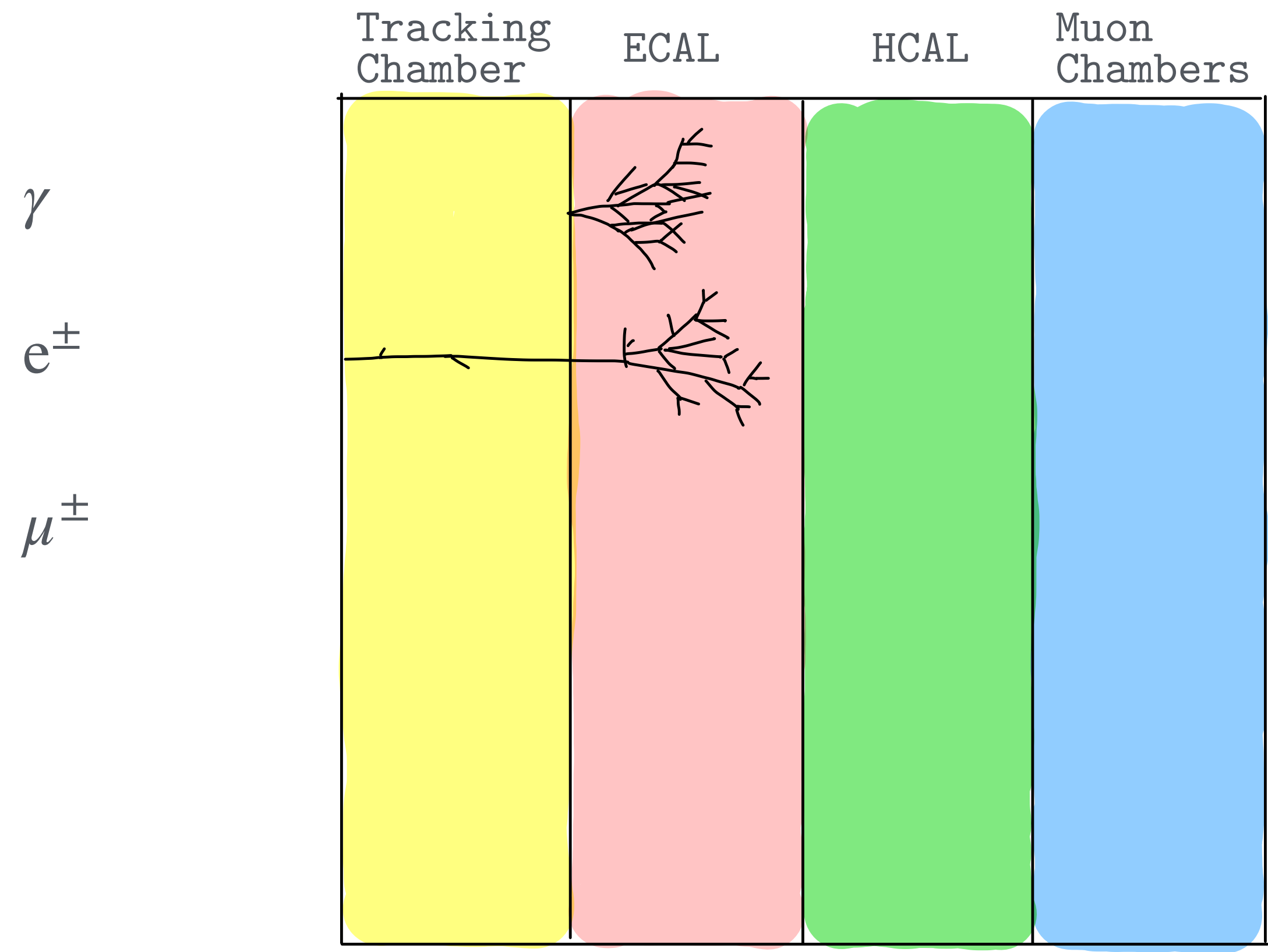
- Photons
 - Deposit all energy in EM; no track
- Electrons
 - Similar to photons; but matched to track



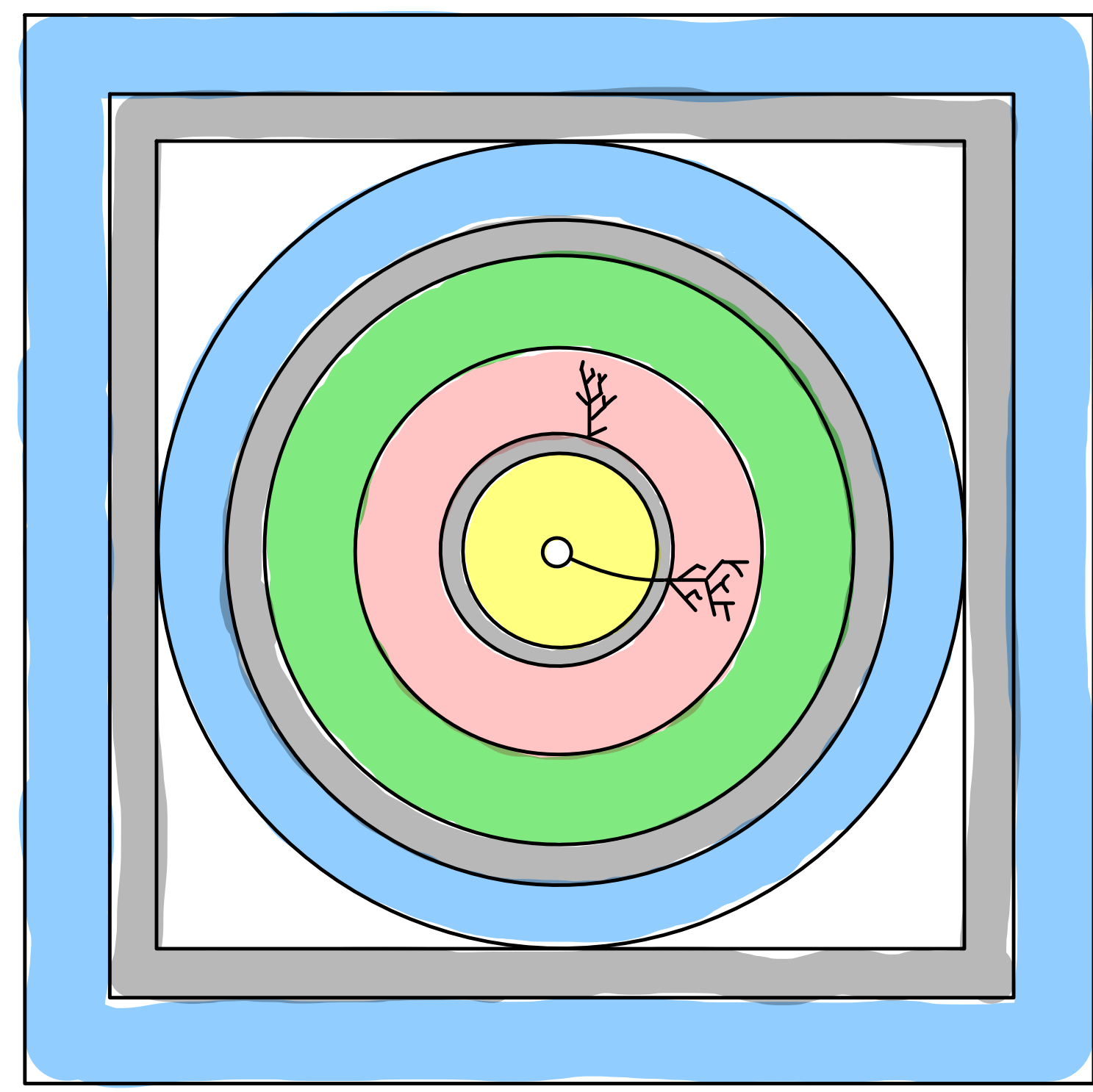
-  Beam Pipe
-  Tracking Chamber
-  Solenoid
-  ECAL
-  HCAL
-  Return Yoke
-  Muon Chambers



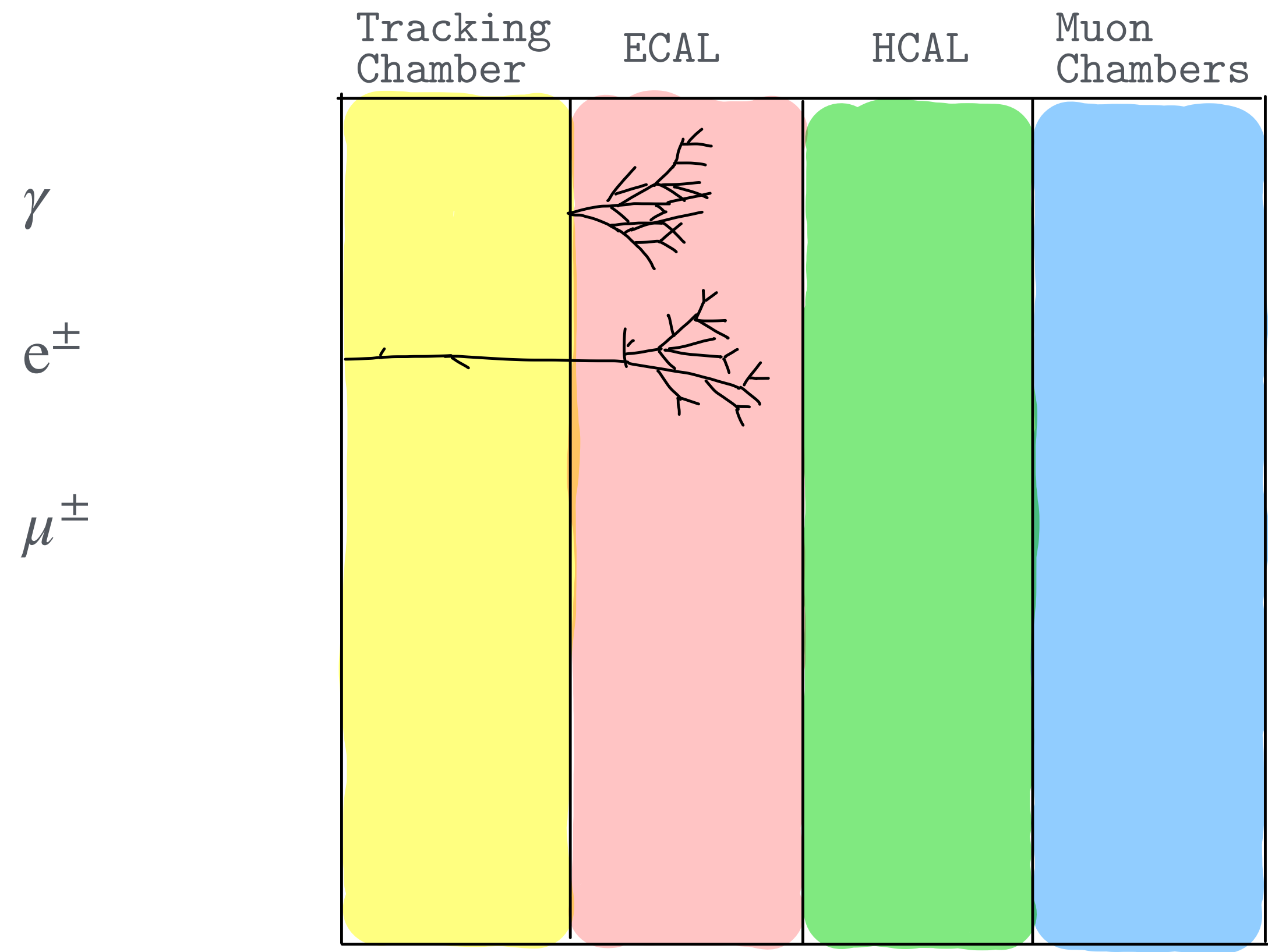
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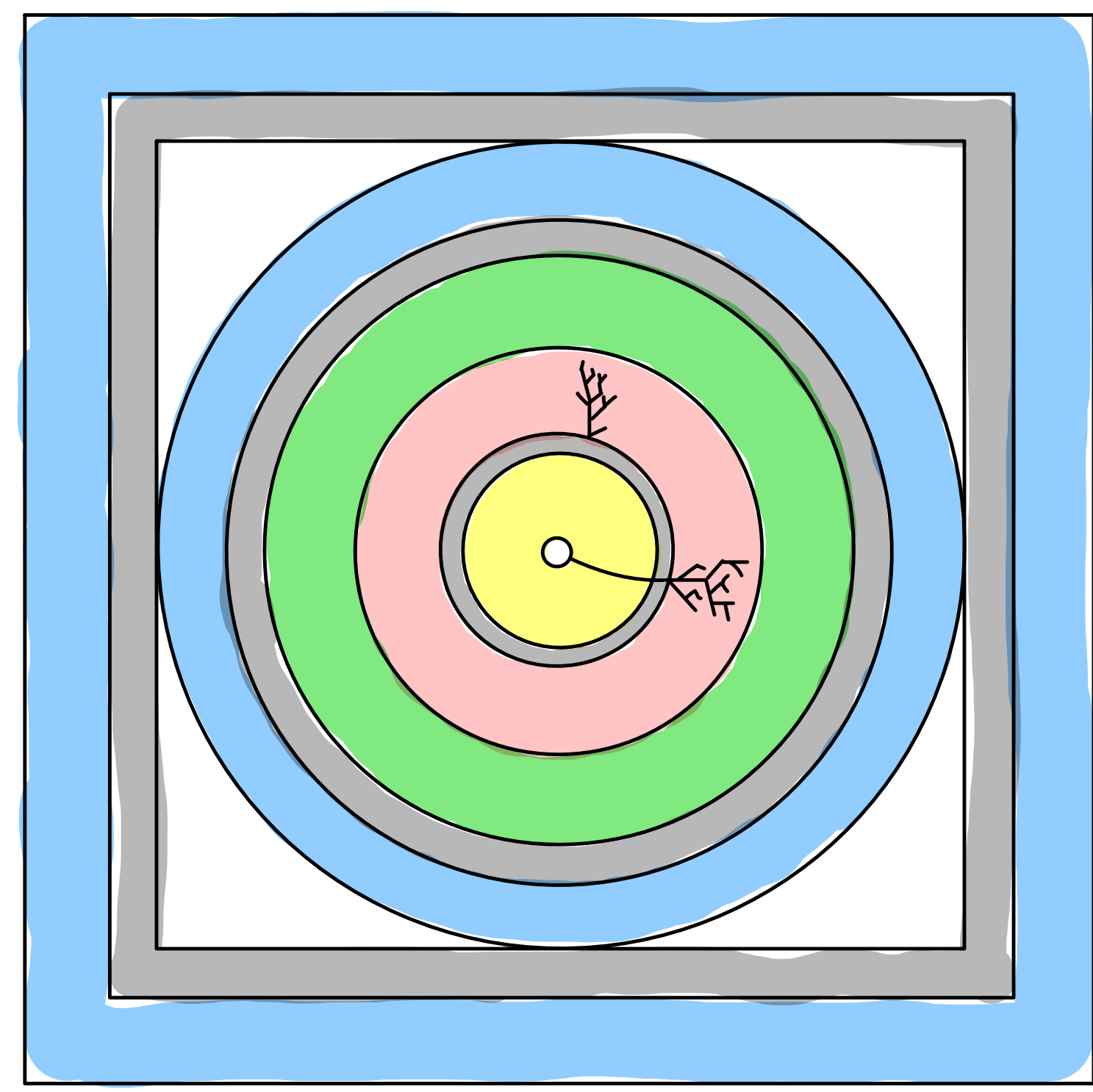
-  Beam Pipe
-  Tracking Chamber
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-  ECAL
-  HCAL
-  Return Yoke
-  Muon Chambers



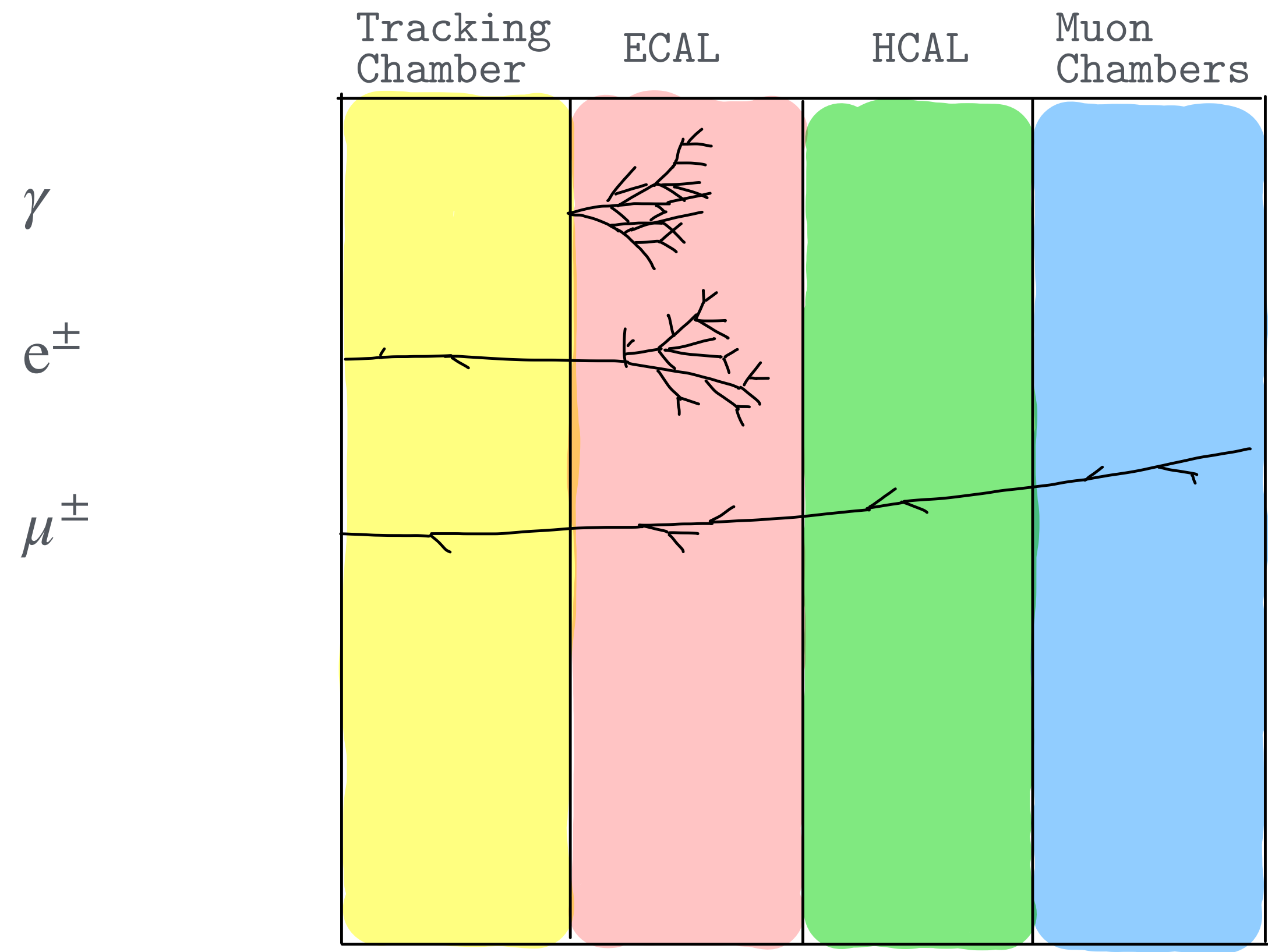
- Photons
 - Deposit all energy in EM; no track
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- Muons



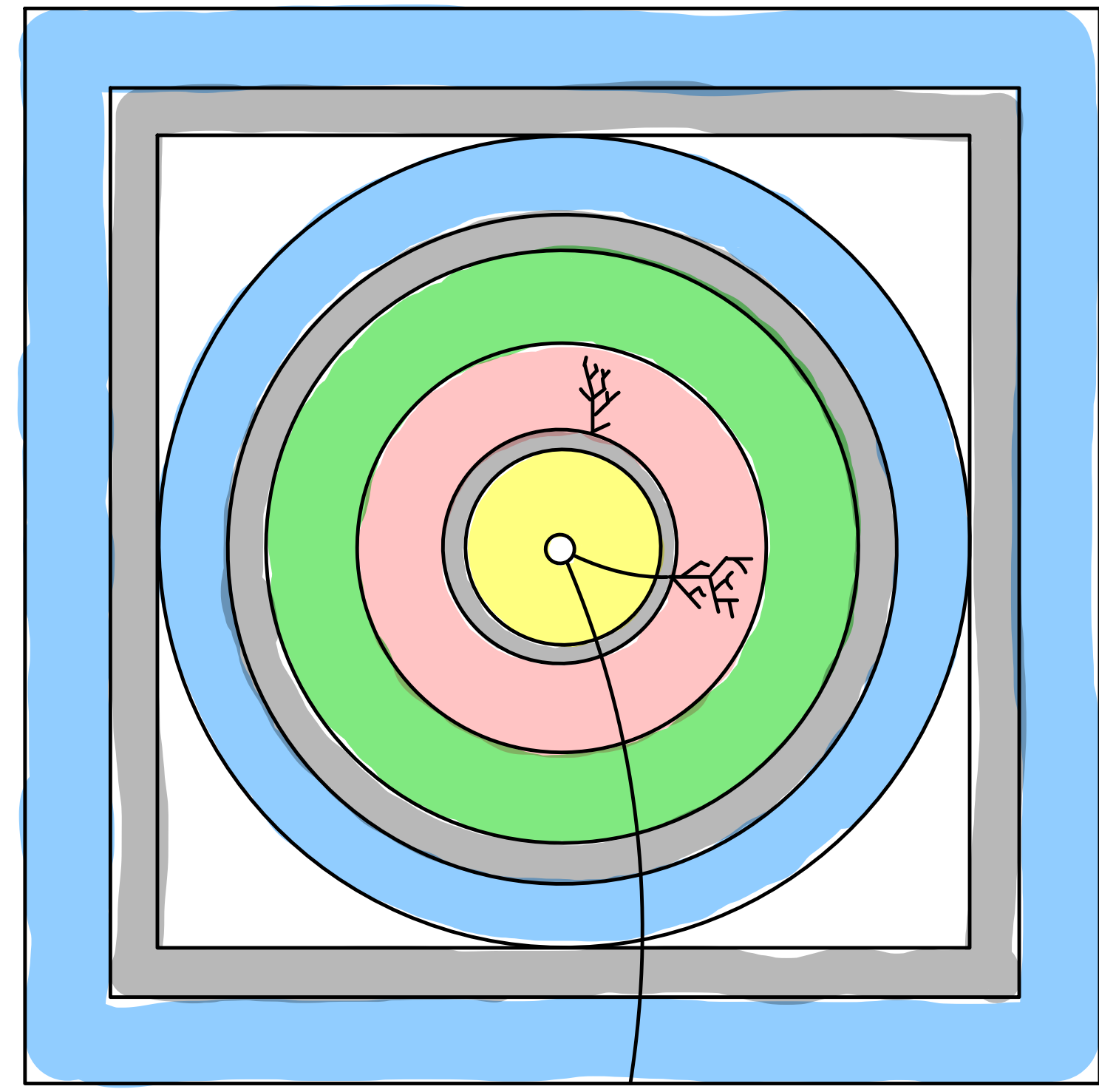
-  Beam Pipe
-  Tracking Chamber
-  Solenoid
-  ECAL
-  HCAL
-  Return Yoke
-  Muon Chambers



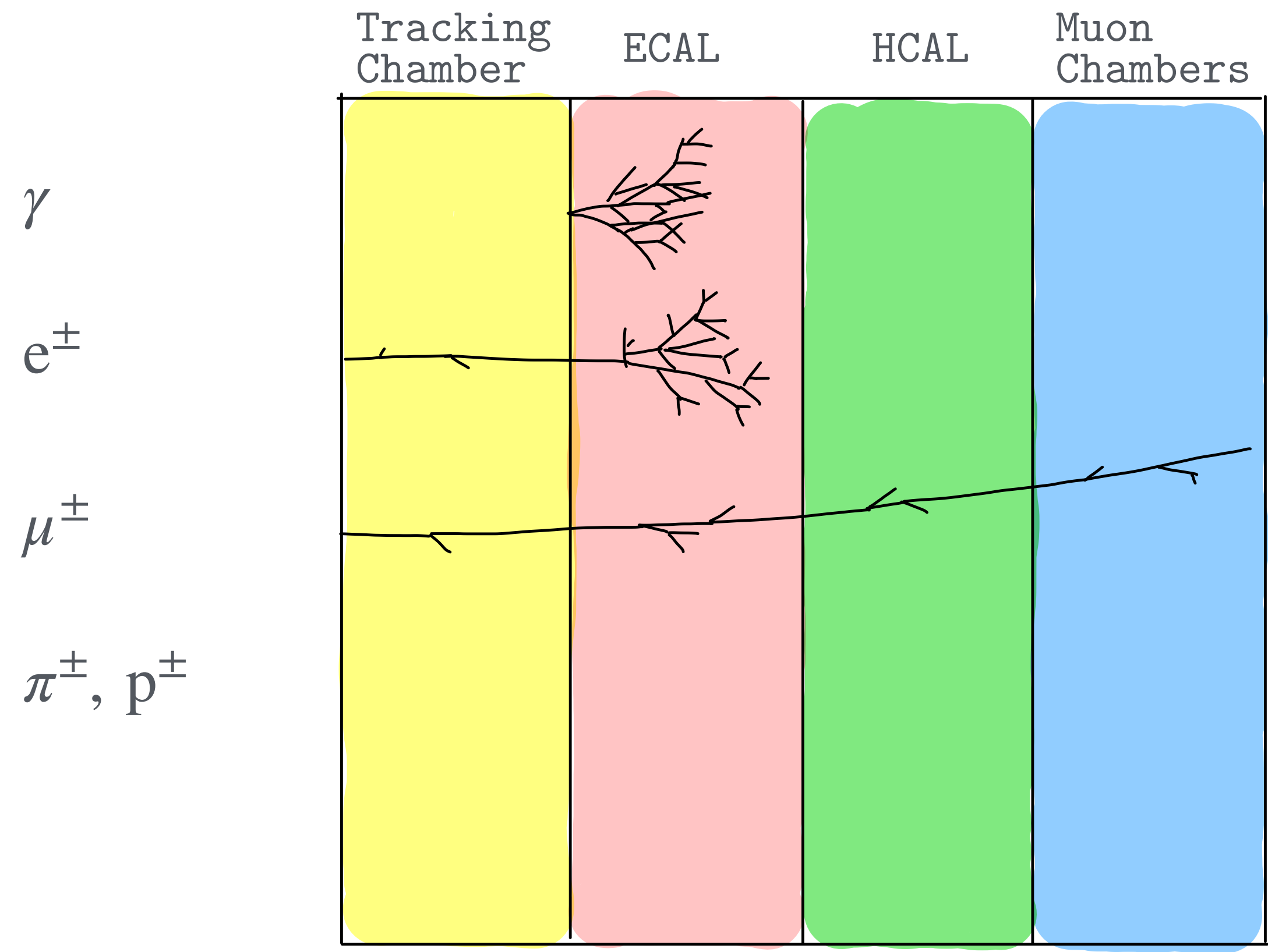
- Photons
 - Deposit all energy in EM; no track
- Electrons
 - Similar to photons; but matched to track
- Muons
 - Matched hits in Muon Chambers with hits in tracker



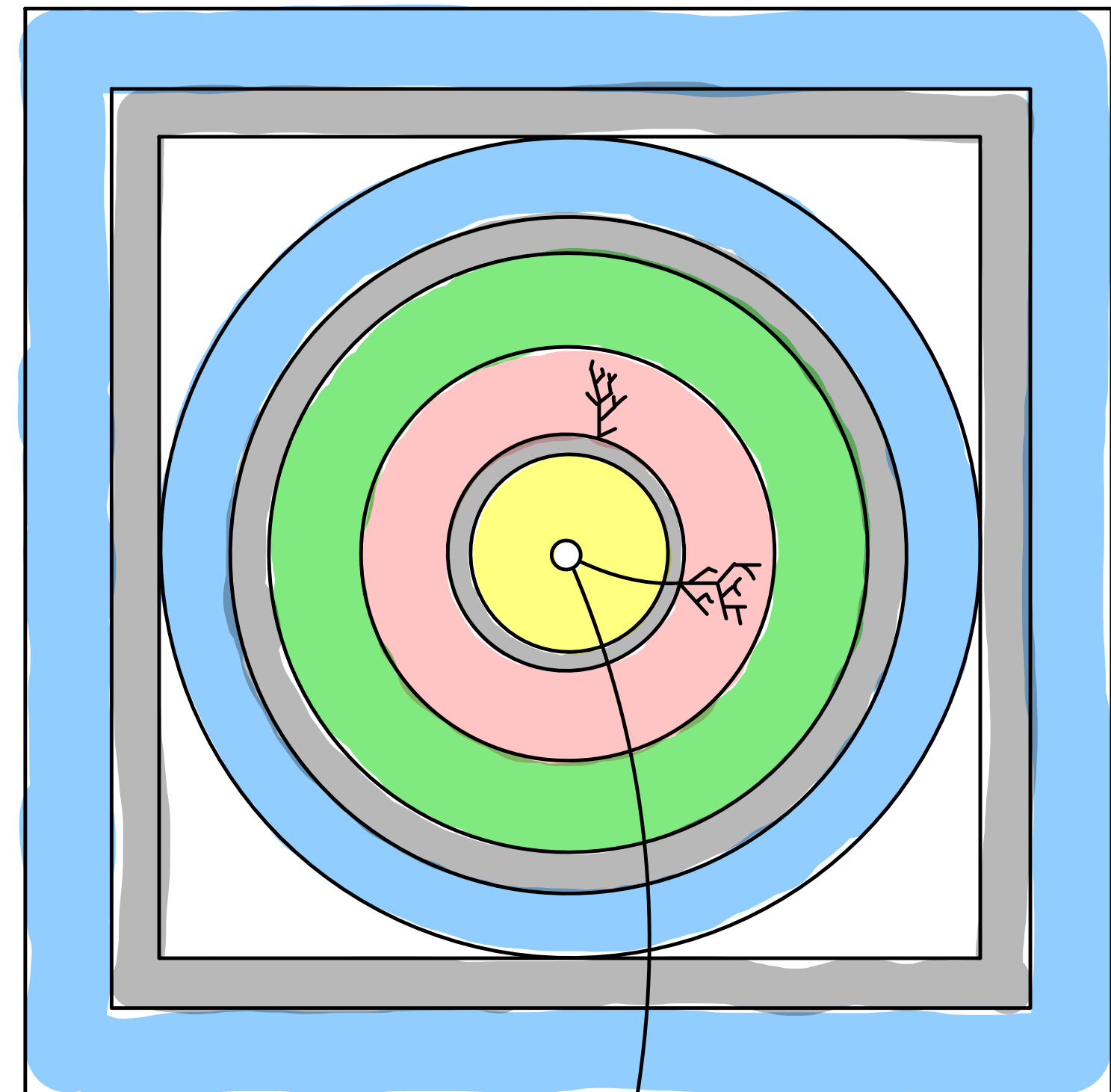
-  Beam Pipe
-  Tracking Chamber
-  Solenoid
-  ECAL
-  HCAL
-  Return Yoke
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- Photons
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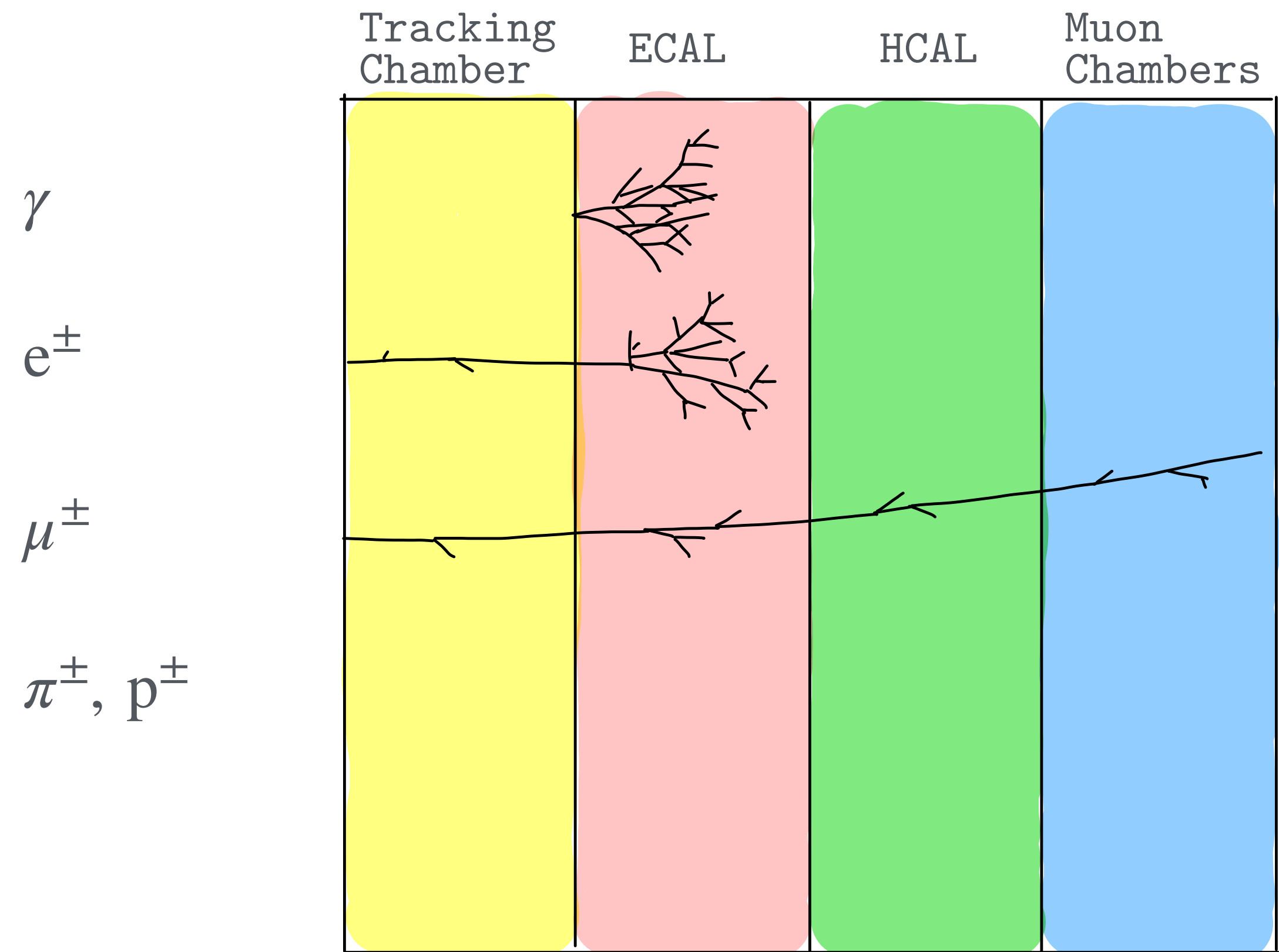




- ◻ Beam Pipe
- ◻ Tracking Chamber
- ◻ Solenoid
- ◻ ECAL
- ◻ HCAL
- ◻ Return Yoke
- ◻ Muon Chambers

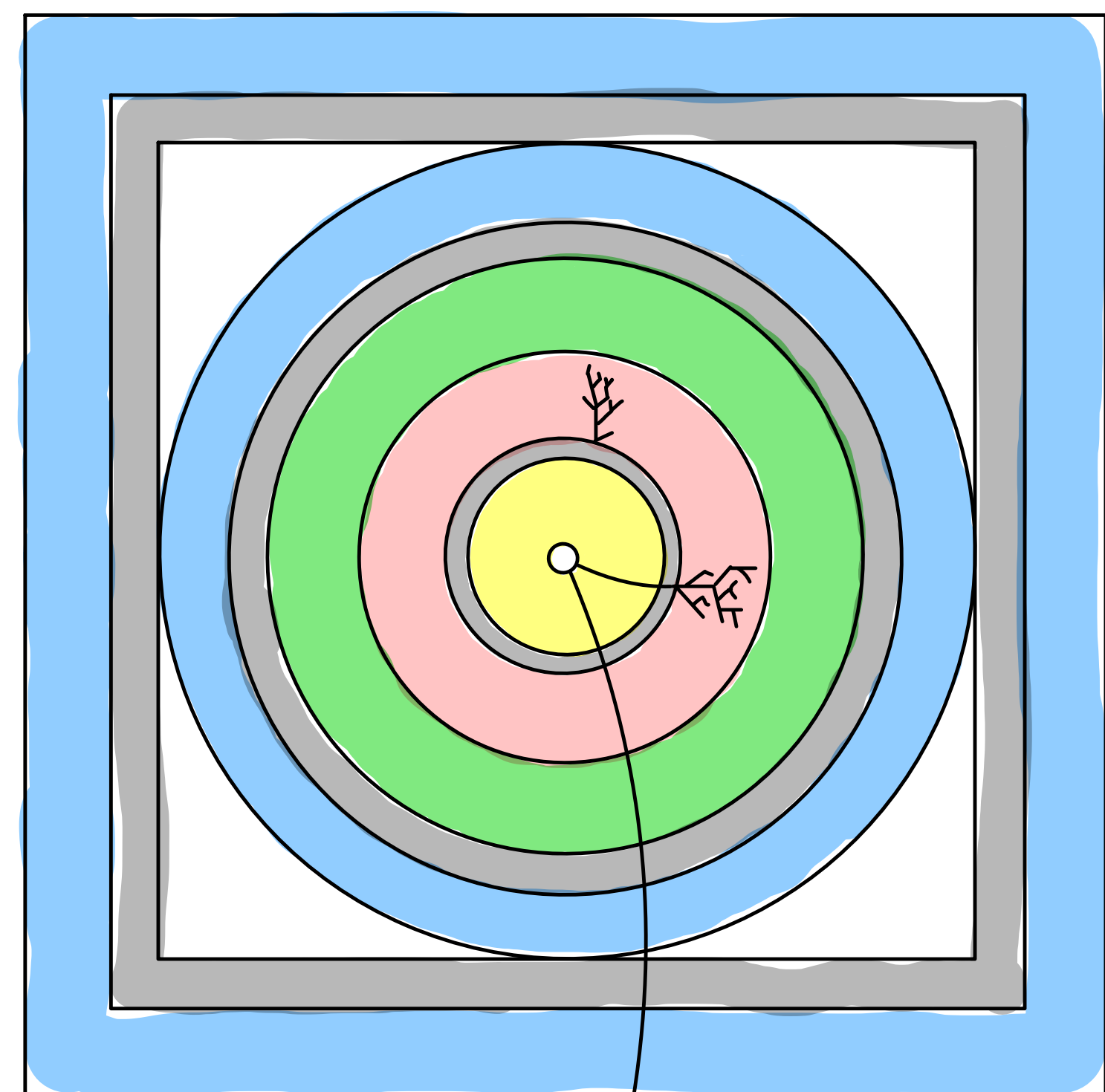


- Photons
 - Deposit all energy in EM; no track
- Electrons
 - Similar to photons; but matched to track
- Muons
 - Matched hits in Muon Chambers with hits in tracker

- Charged Hadrons

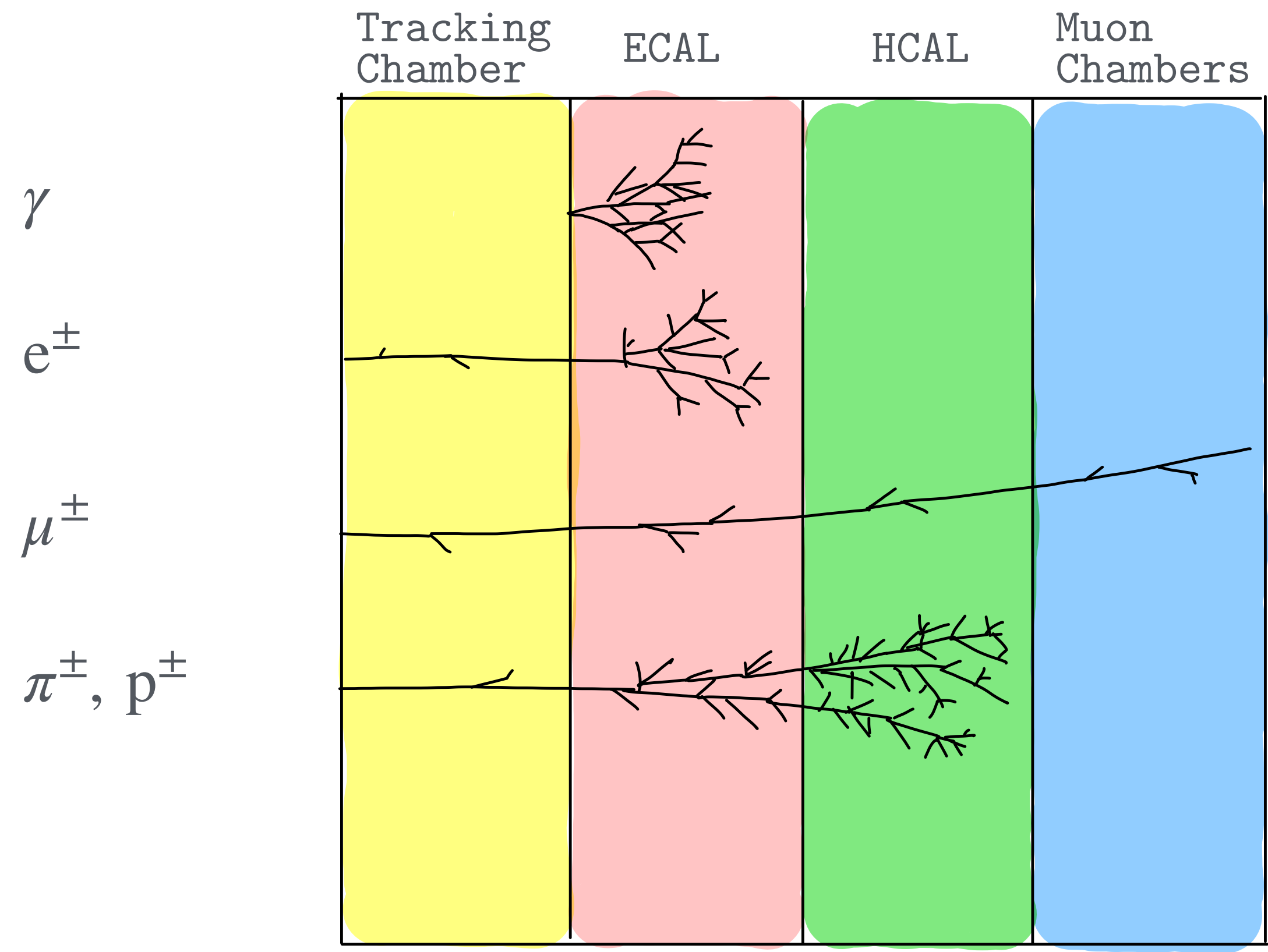


-  Beam Pipe
-  Tracking Chamber
-  Solenoid
-  ECAL
-  HCAL
-  Return Yoke
-  Muon Chambers

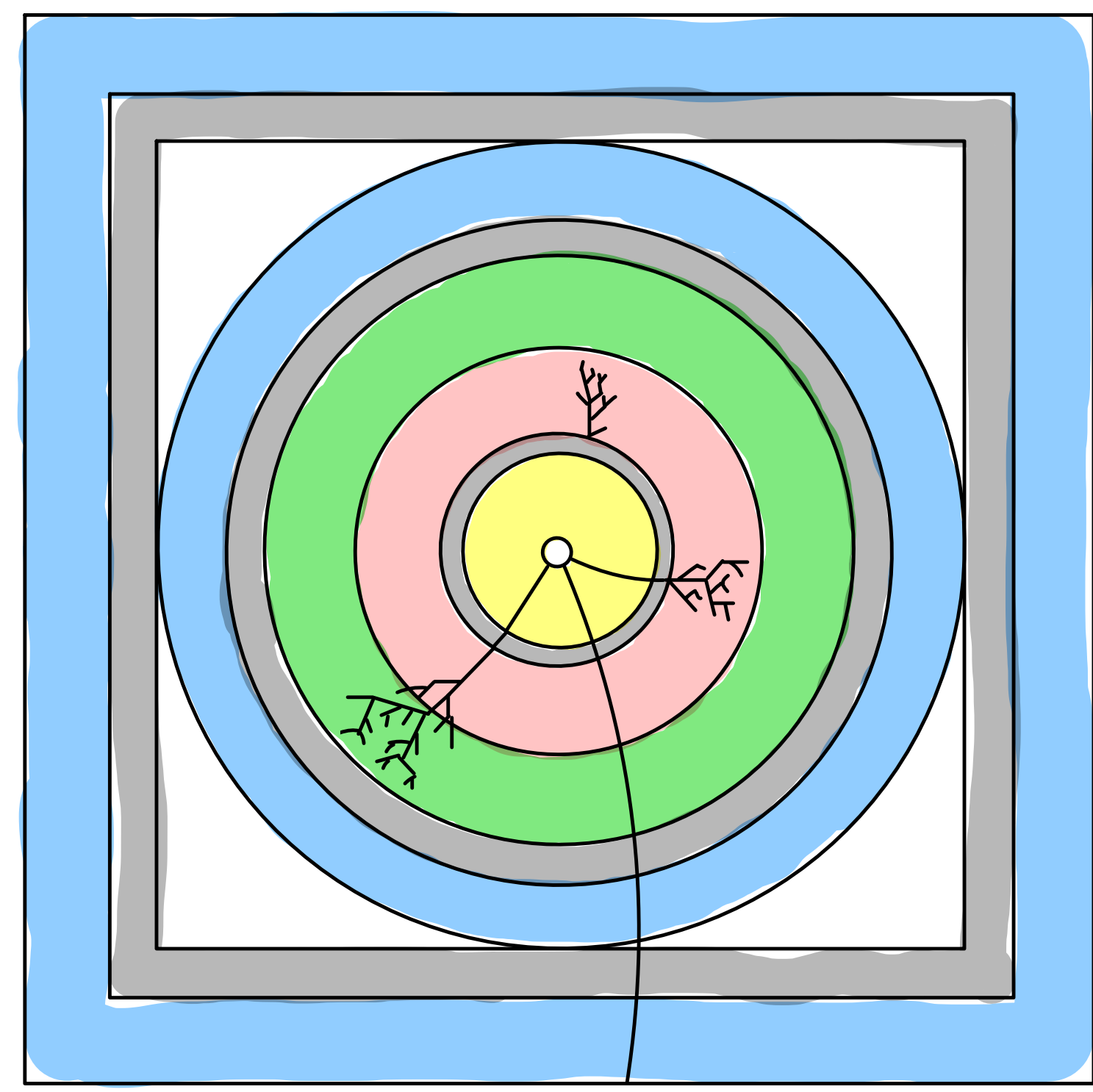


- Photons
 - Deposit all energy in EM; no track
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 - Similar to photons; but matched to track
- Muons
 - Matched hits in Muon Chambers with hits in tracker

- Charged Hadrons
 - Deposit all energy in ECAL+HCAL; matched to track

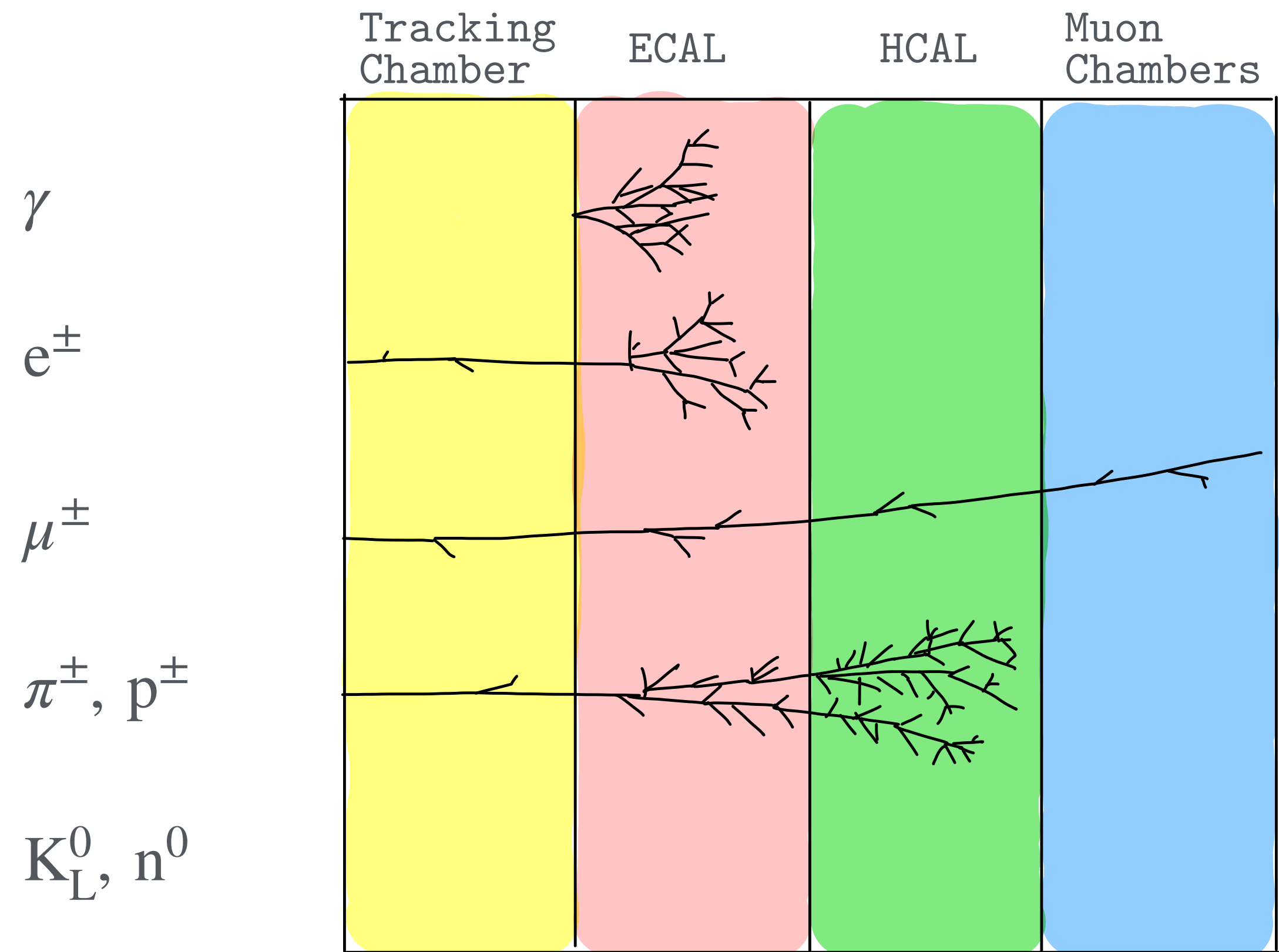








-  Beam Pipe
-  Tracking Chamber
-  Solenoid
-  ECAL
-  HCAL
-  Return Yoke
-  Muon Chambers

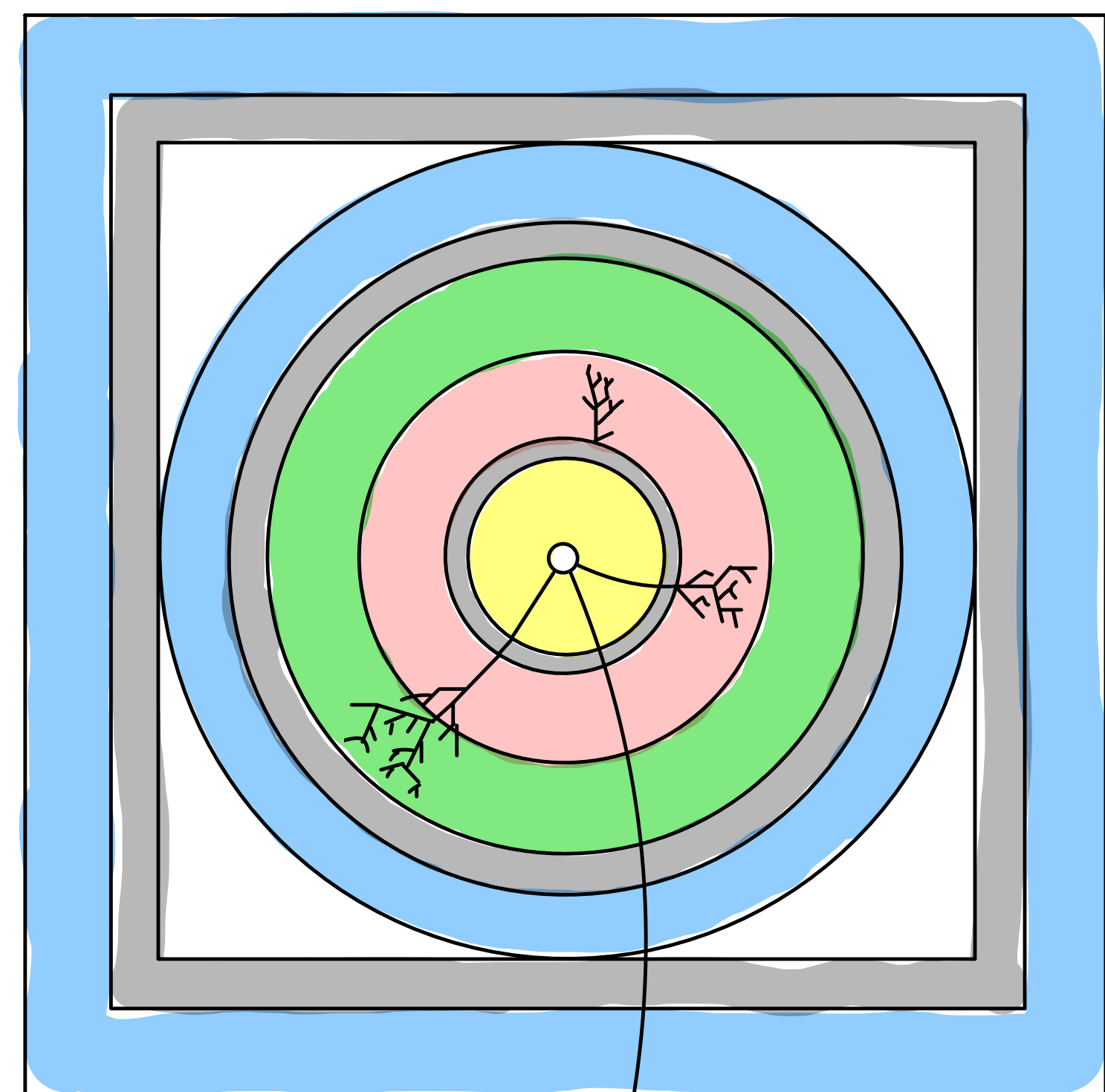


- Photons
 - Deposit all energy in EM; no track
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 - Similar to photons; but matched to track
- Muons
 - Matched hits in Muon Chambers with hits in tracker

- Charged Hadrons
 - Deposit all energy in ECAL+HCAL; matched to track

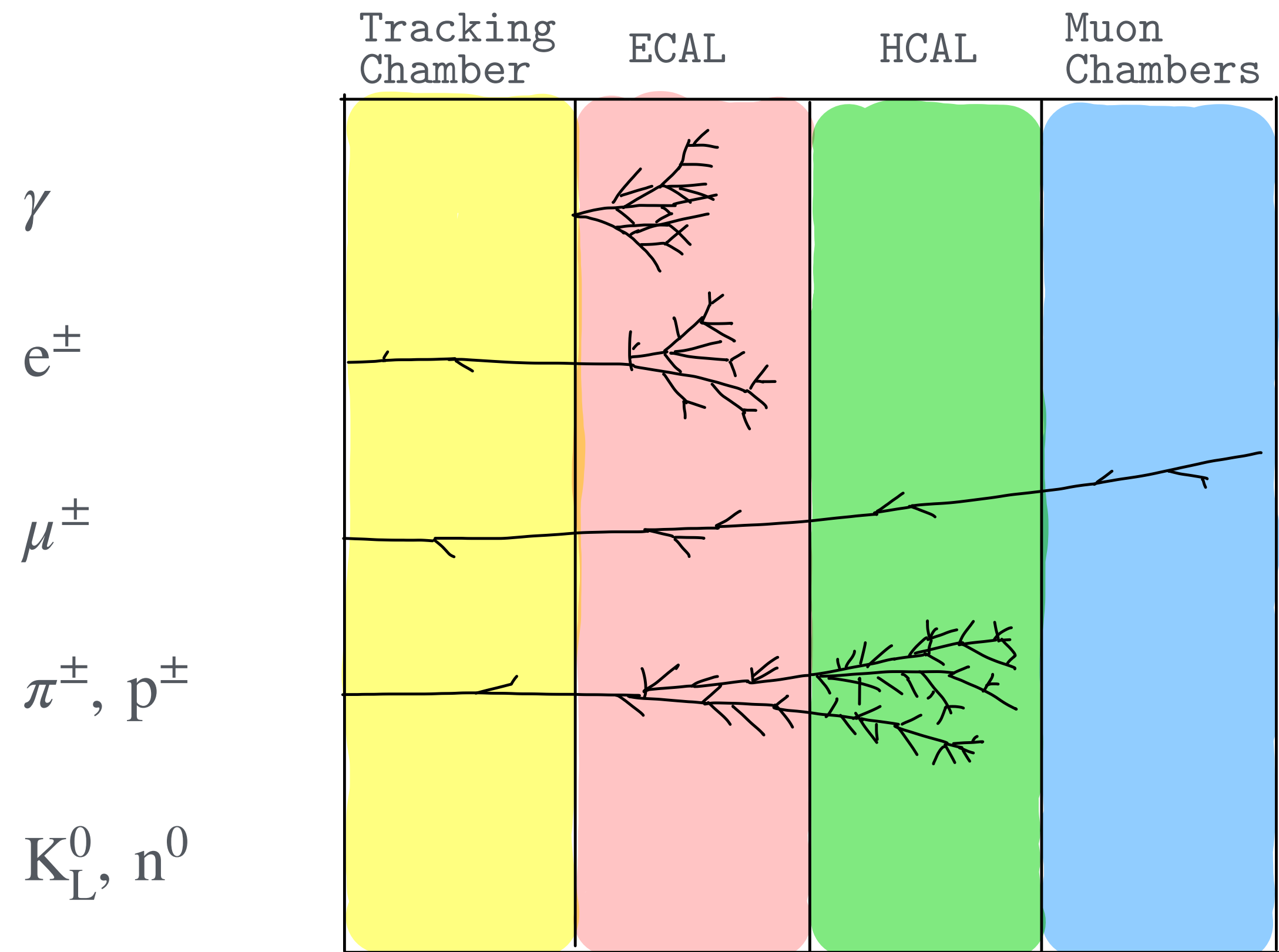




-  Beam Pipe
-  Tracking Chamber
-  Solenoid
-  ECAL
-  HCAL
-  Return Yoke
-  Muon Chambers

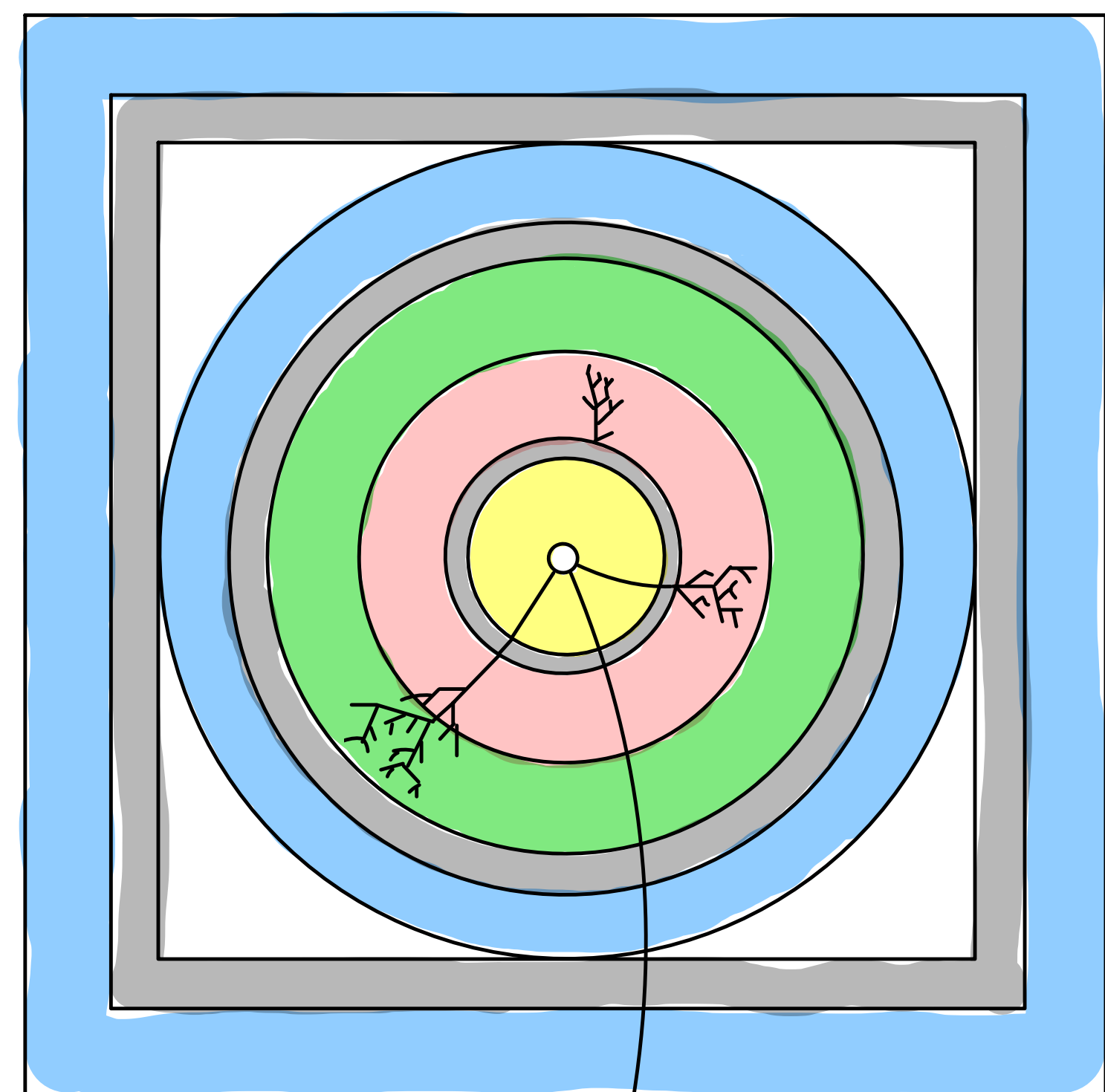


- Photons
 - Deposit all energy in EM; no track
- Electrons
 - Similar to photons; but matched to track
- Muons
 - Matched hits in Muon Chambers with hits in tracker

- Charged Hadrons
 - Deposit all energy in ECAL+HCAL; matched to track
- Neutral Hadrons

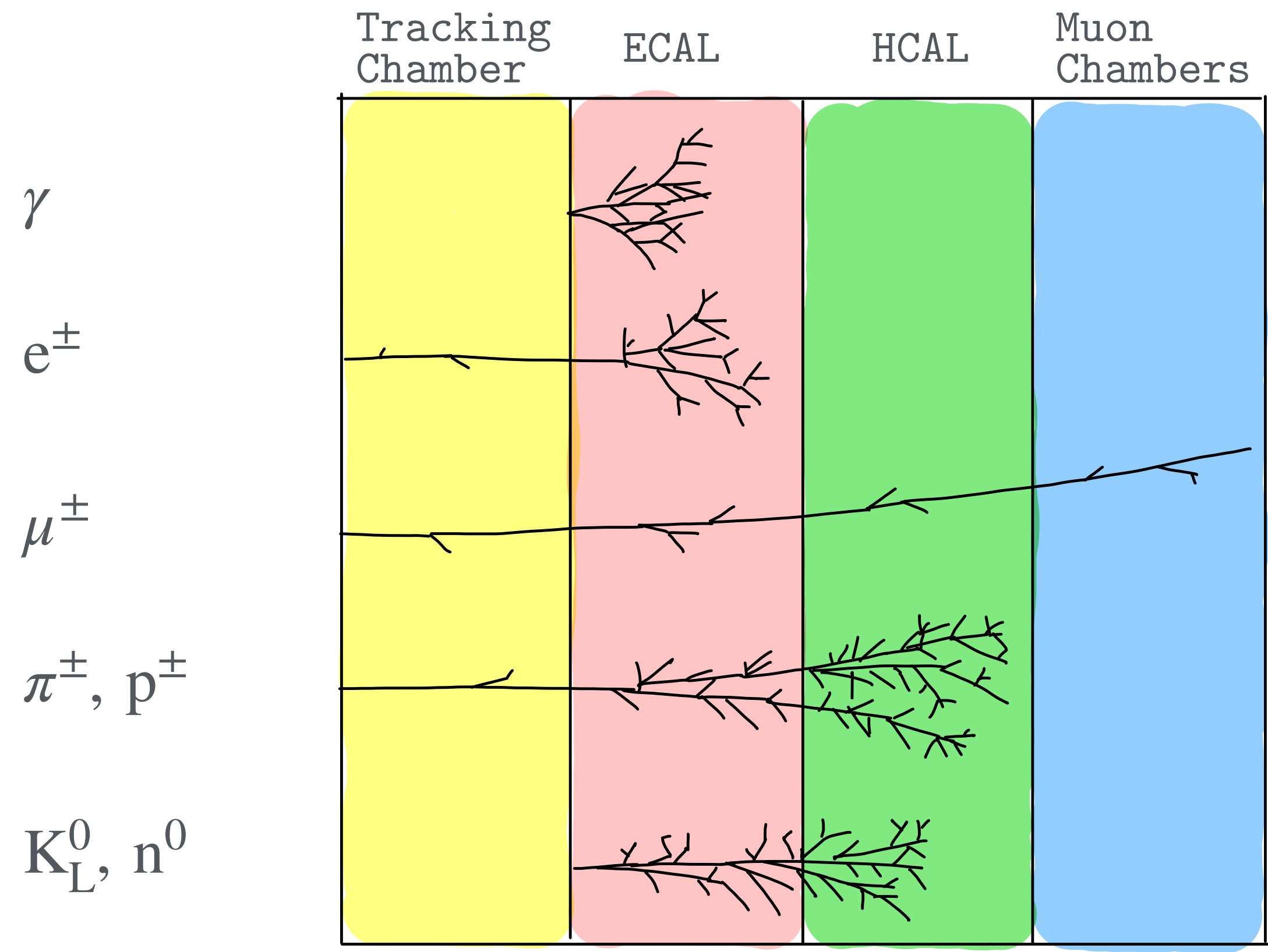




-  Beam Pipe
-  Tracking Chamber
-  Solenoid
-  ECAL
-  HCAL
-  Return Yoke
-  Muon Chambers

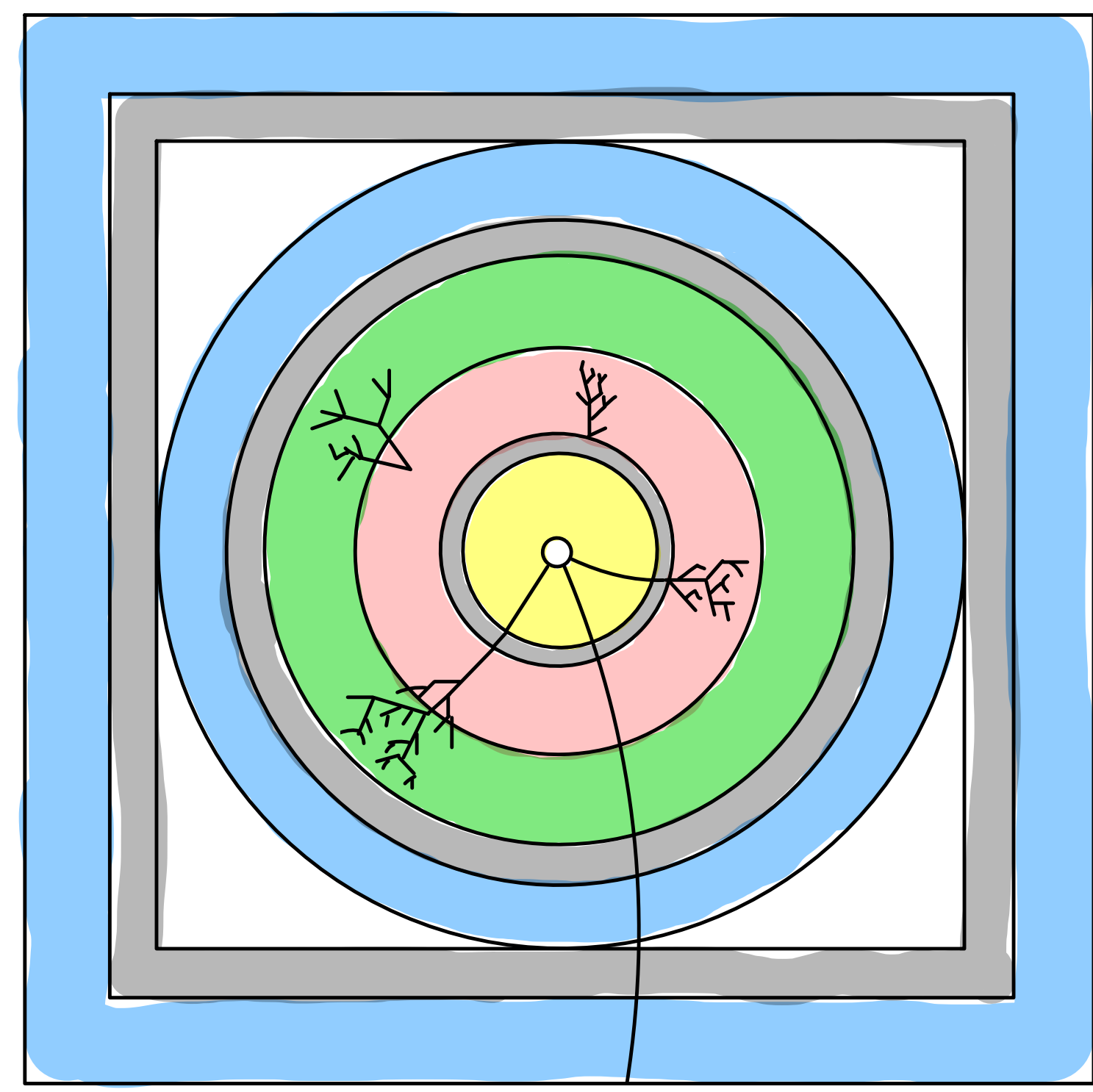


- Photons
 - Deposit all energy in EM; no track
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- Muons
 - Matched hits in Muon Chambers with hits in tracker

- Charged Hadrons
 - Deposit all energy in ECAL+HCAL; matched to track
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 - Similar to Charged Hadrons; but no track

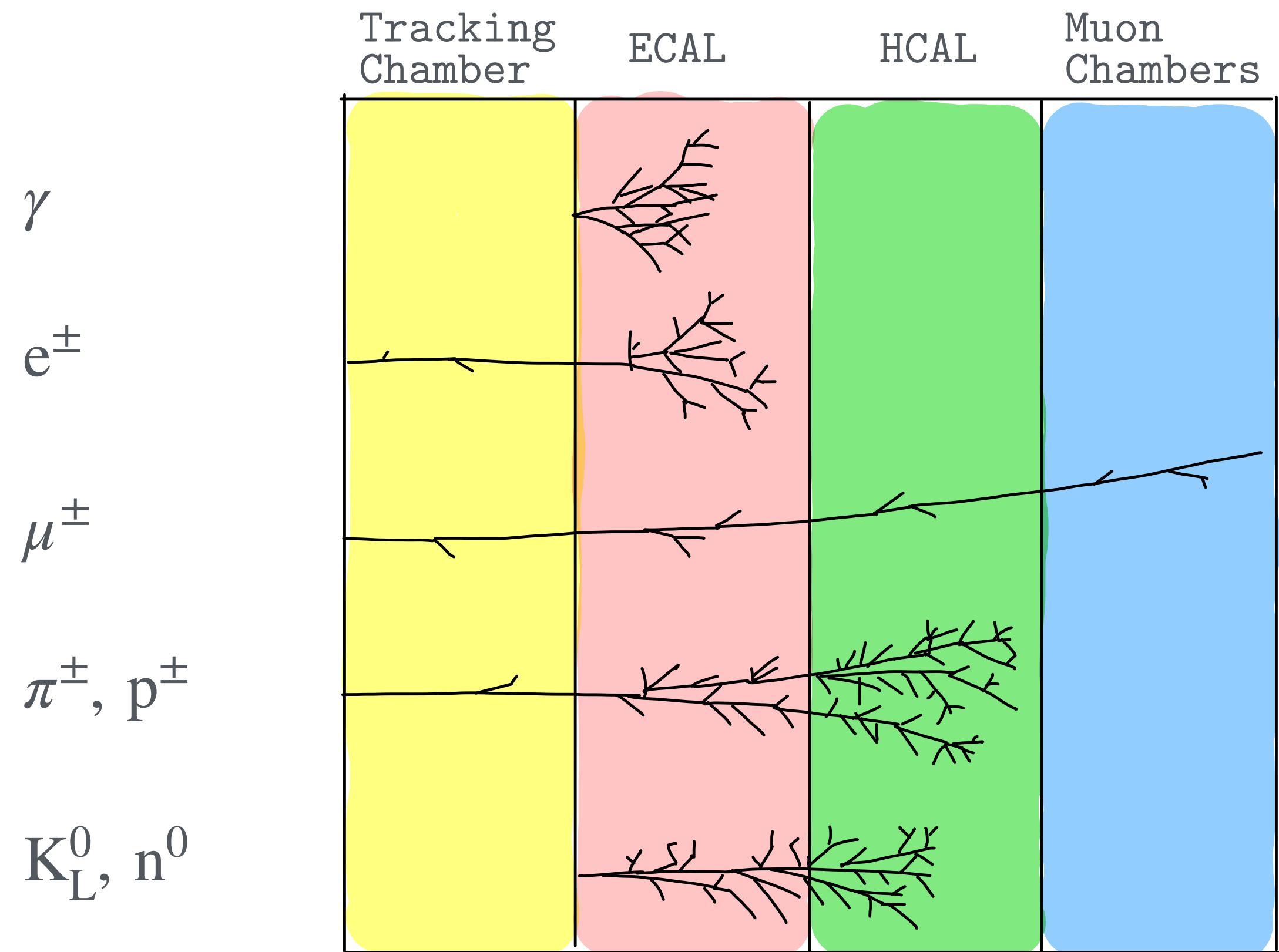






-  Beam Pipe
-  Tracking Chamber
-  Solenoid
-  ECAL
-  HCAL
-  Return Yoke
-  Muon Chambers

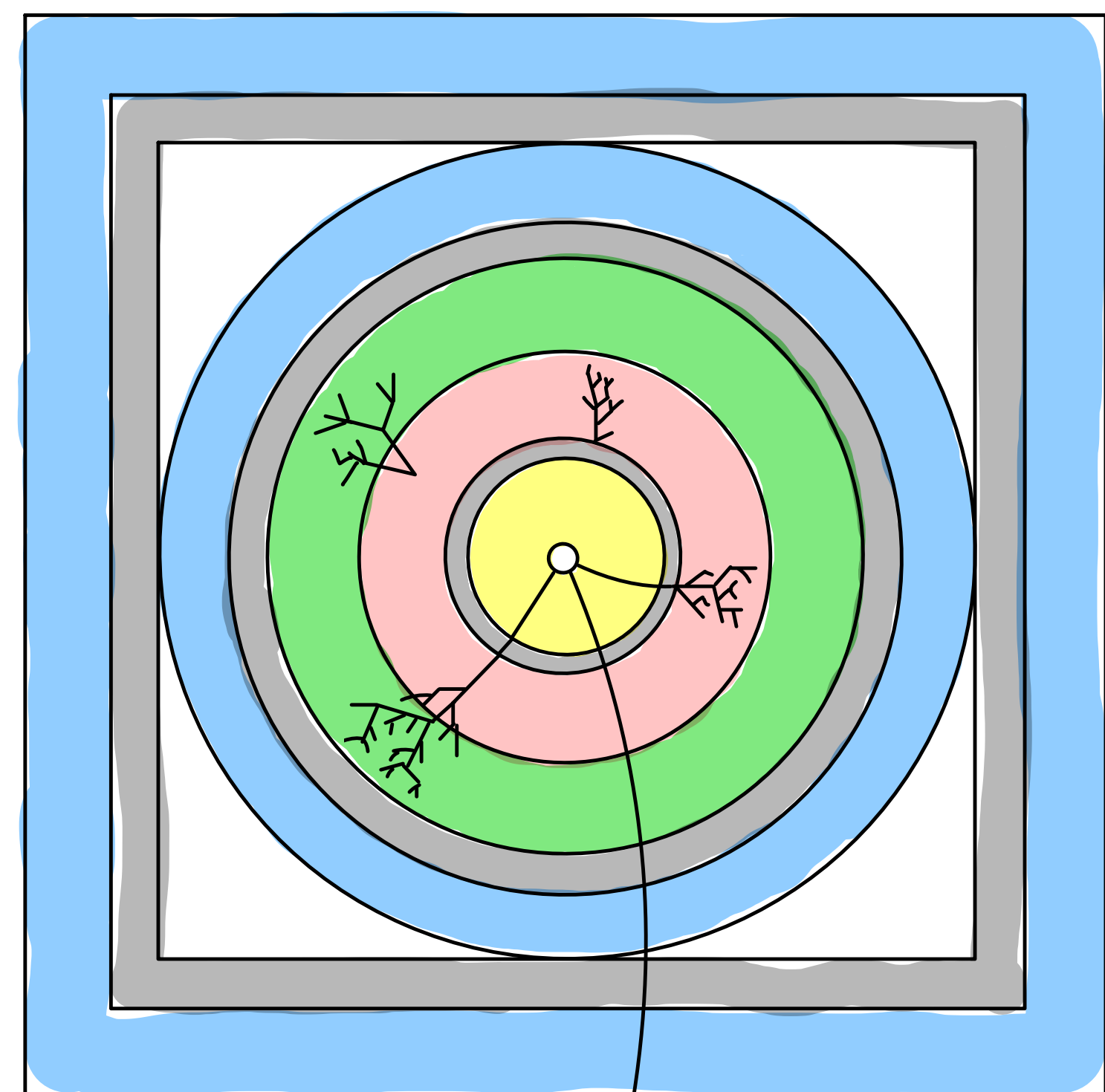


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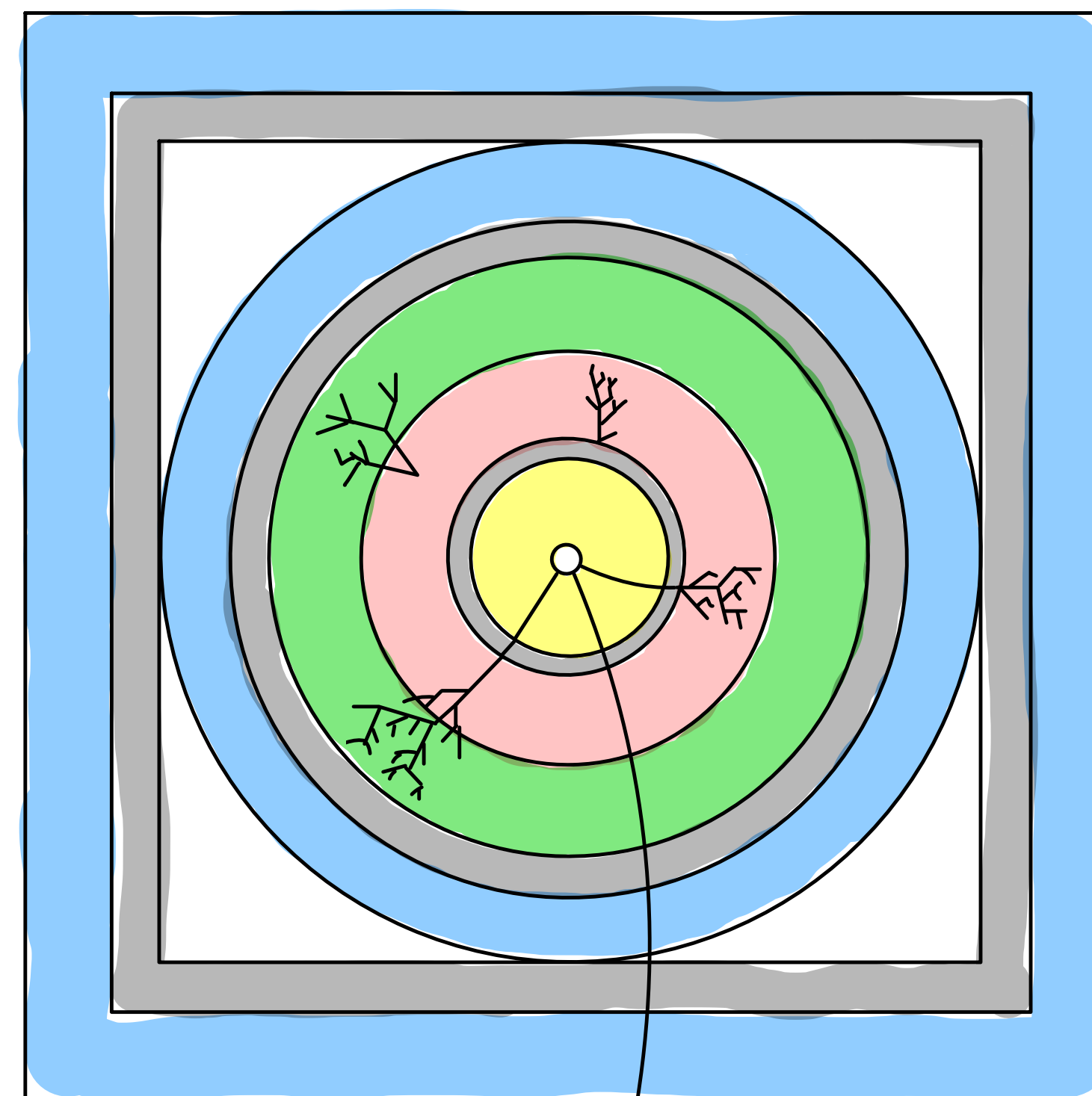
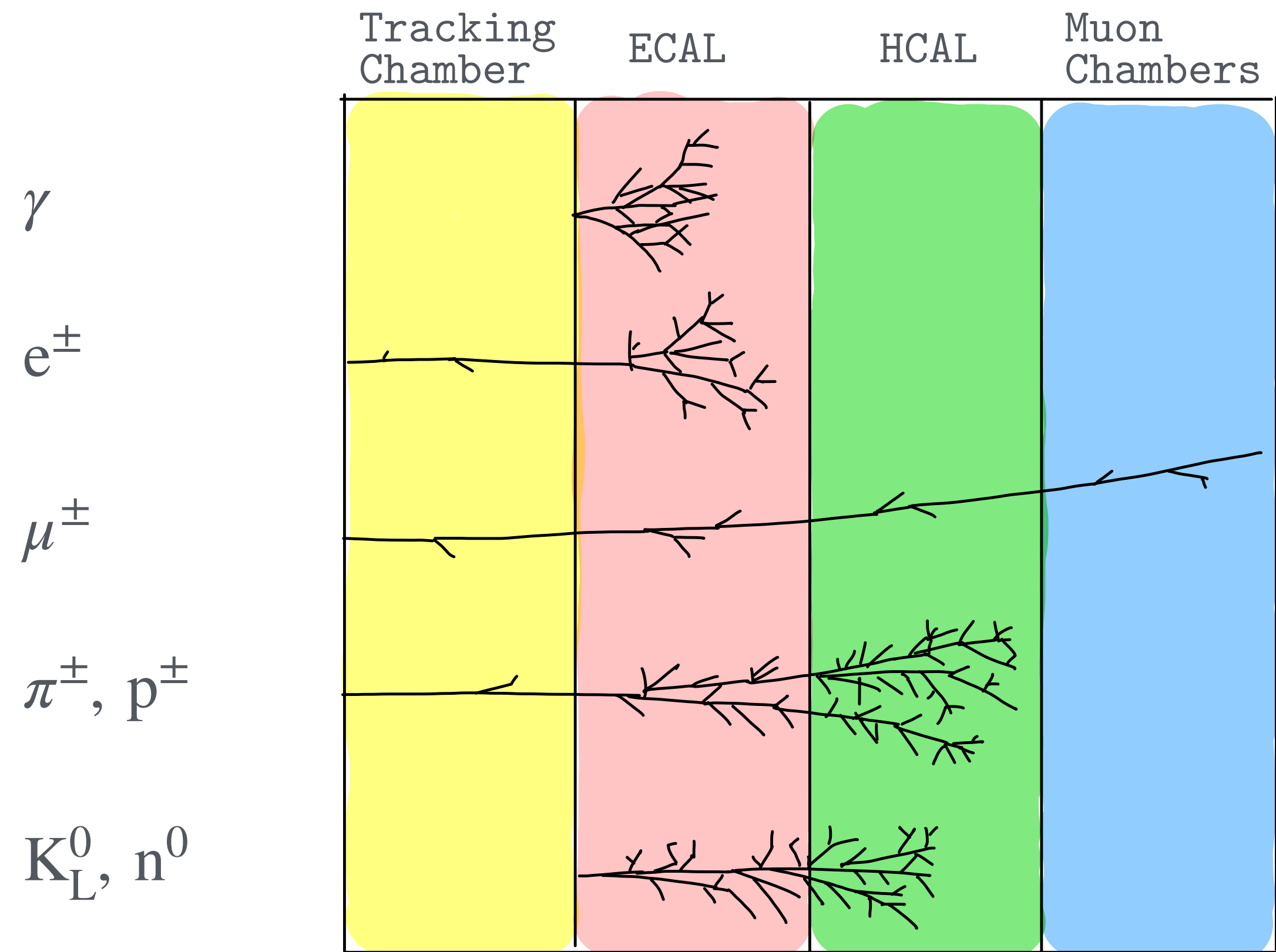


-  Beam Pipe
-  Tracking Chamber
-  Solenoid
-  ECAL
-  HCAL
-  Return Yoke
-  Muon Chambers



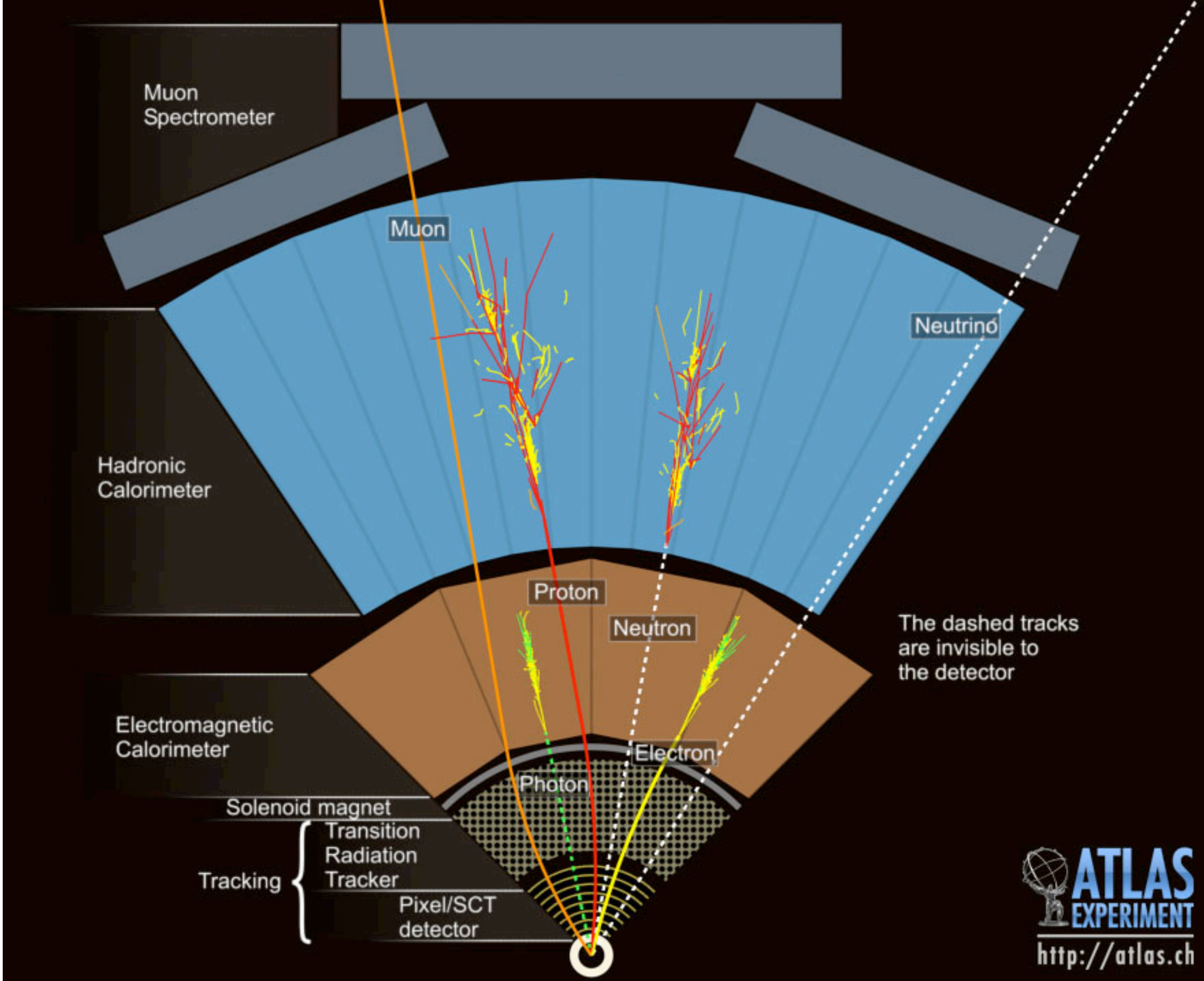
- Photons
 - Deposit all energy in EM; no track
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- Muons
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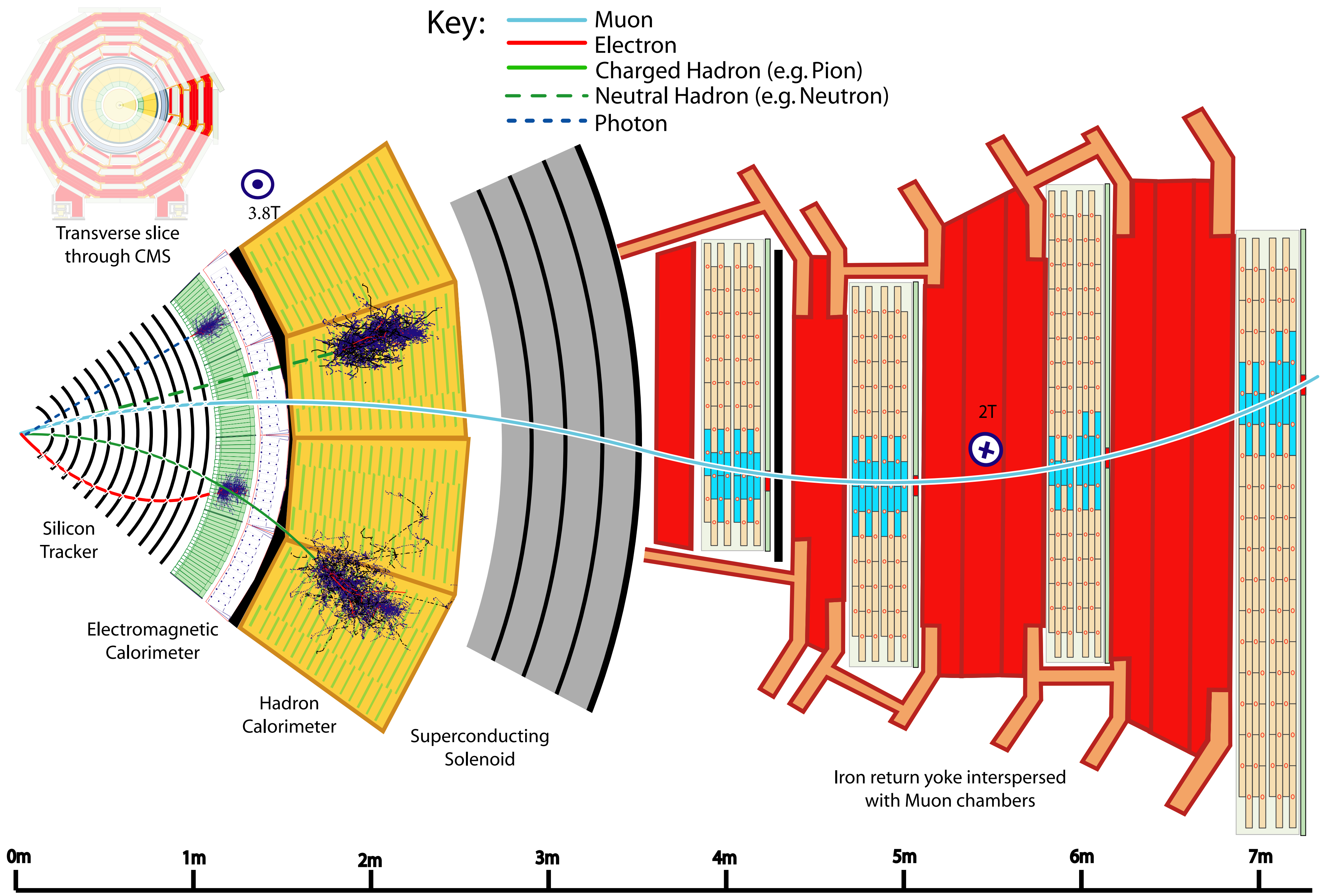
- Charged Hadrons
 - Deposit all energy in ECAL+HCAL; matched to track
- Neutral Hadrons
 - Similar to Charged Hadrons; but no track
- Neutrinos

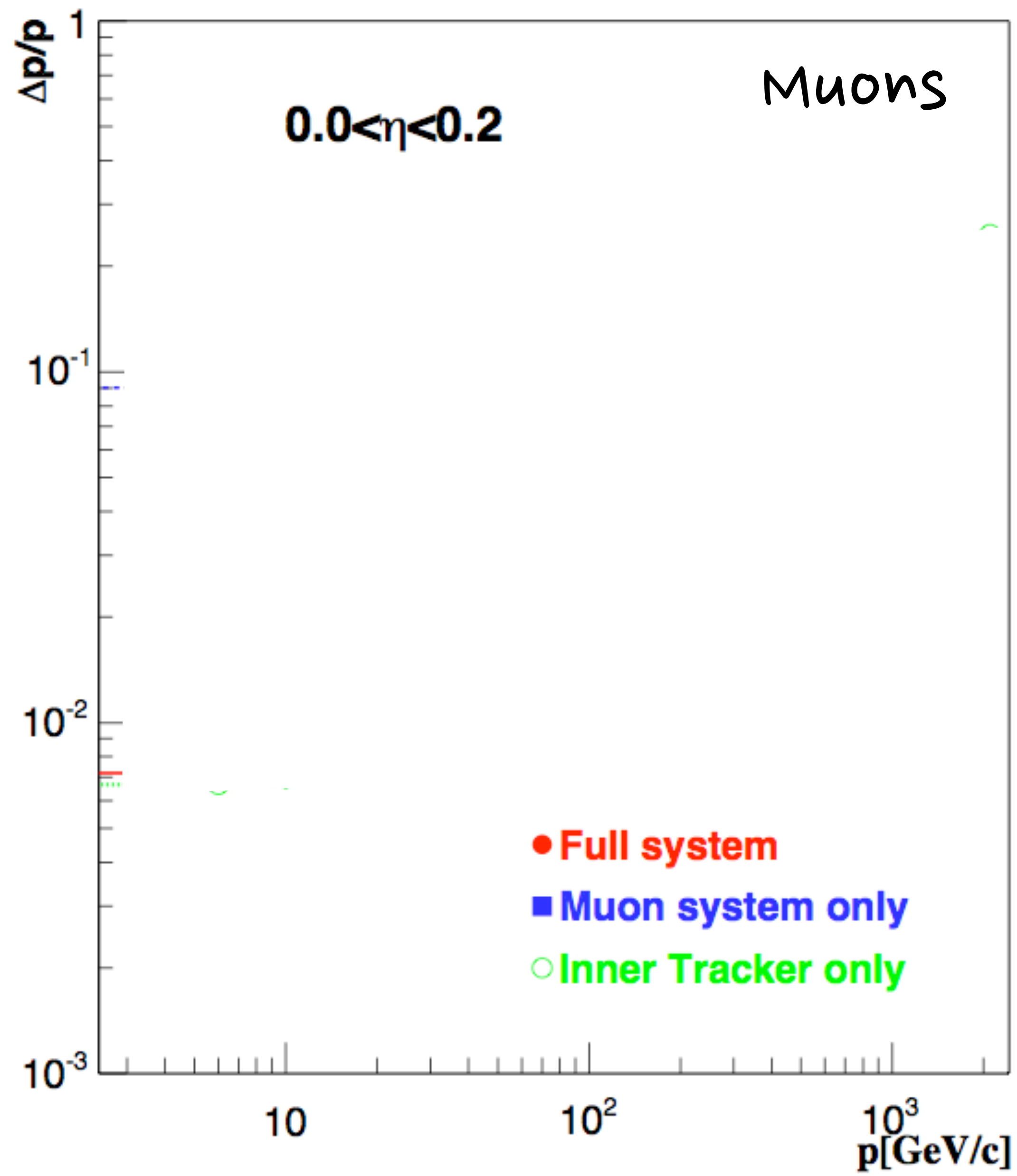


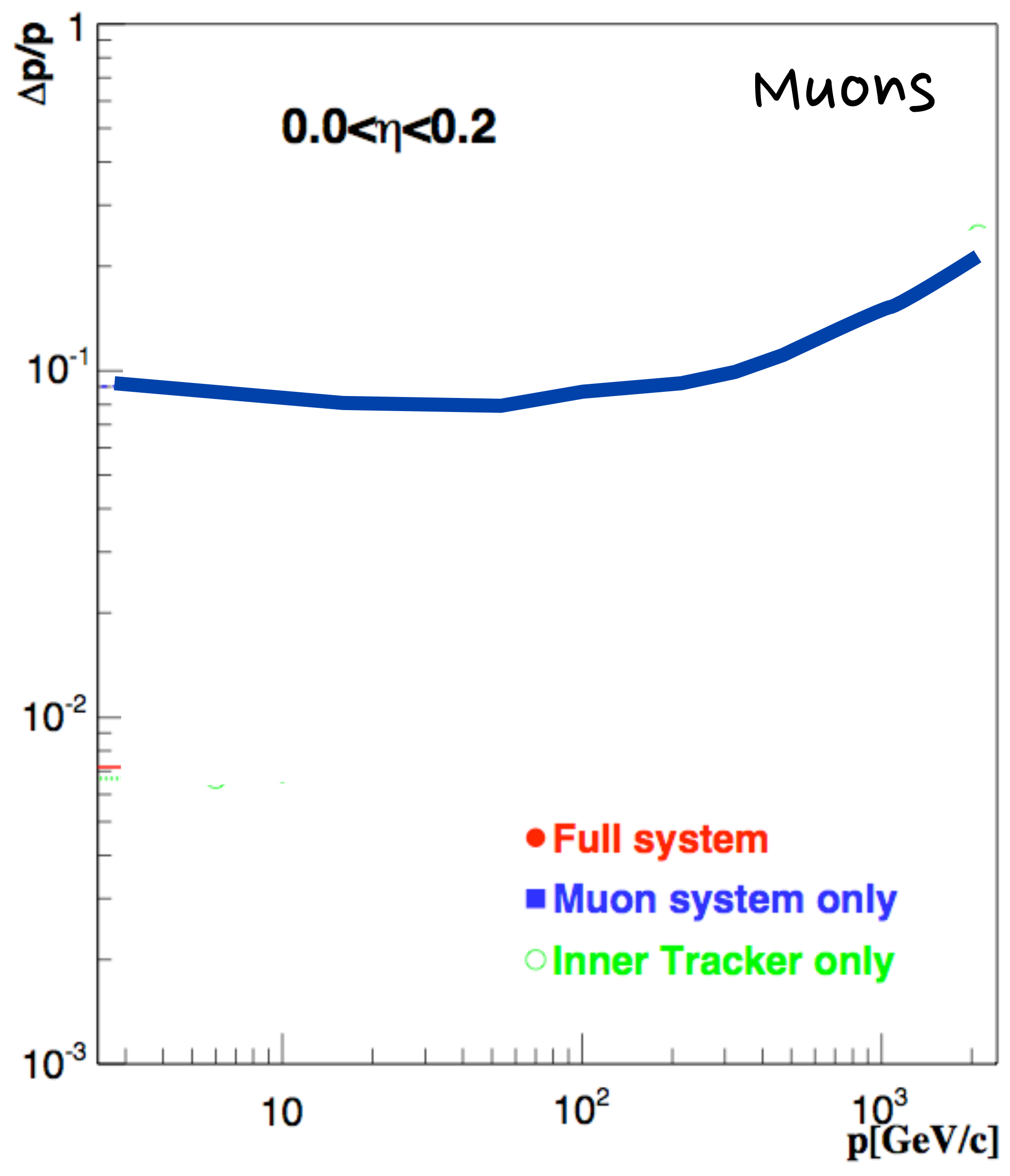
- Photons
 - Deposit all energy in EM; no track
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 - Similar to photons; but matched to track
- Muons
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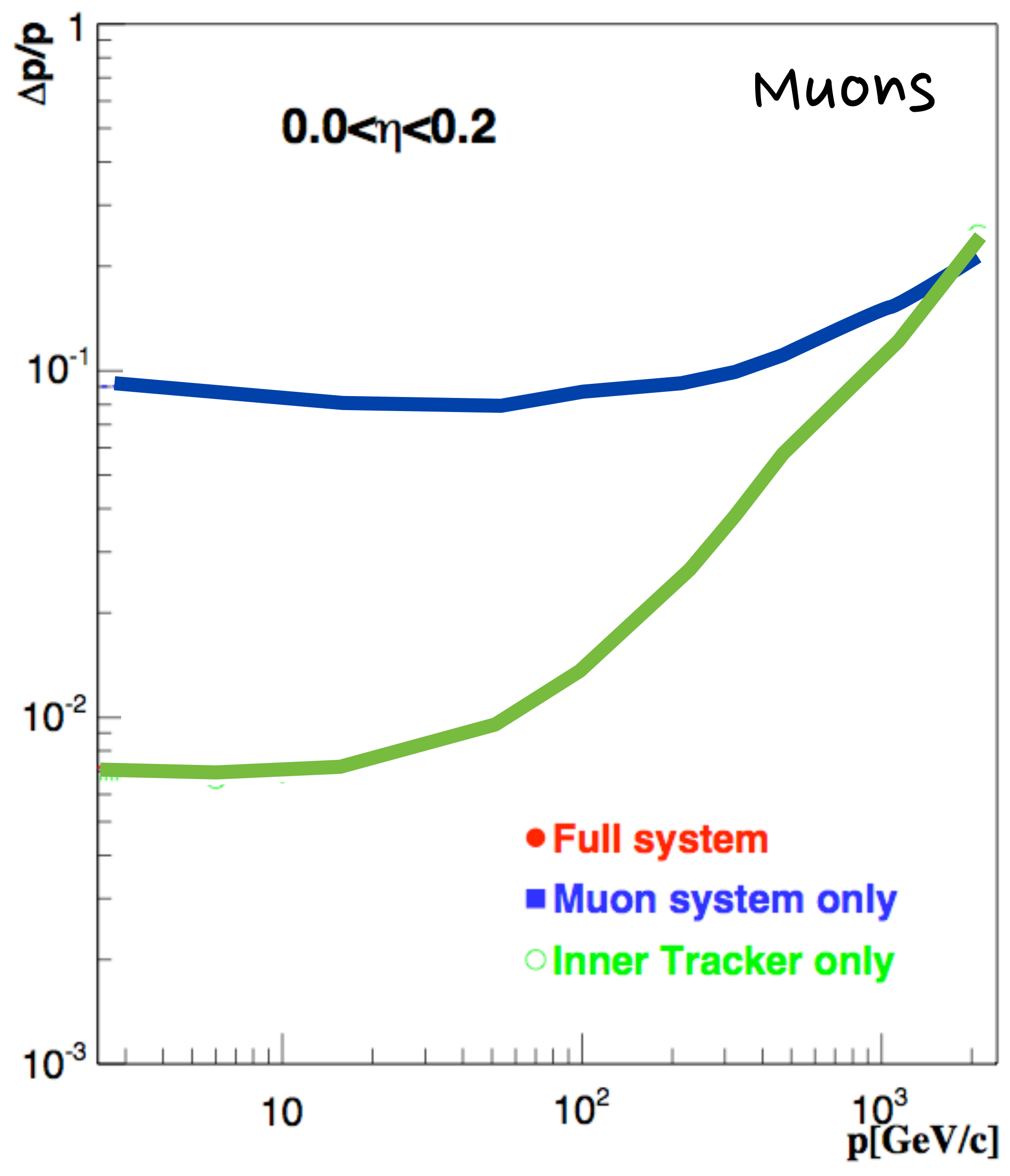
- Charged Hadrons
 - Deposit all energy in ECAL+HCAL; matched to track
- Neutral Hadrons
 - Similar to Charged Hadrons; but no track
- Neutrinos
 - Pass through all material; measured indirectly by momentum imbalance

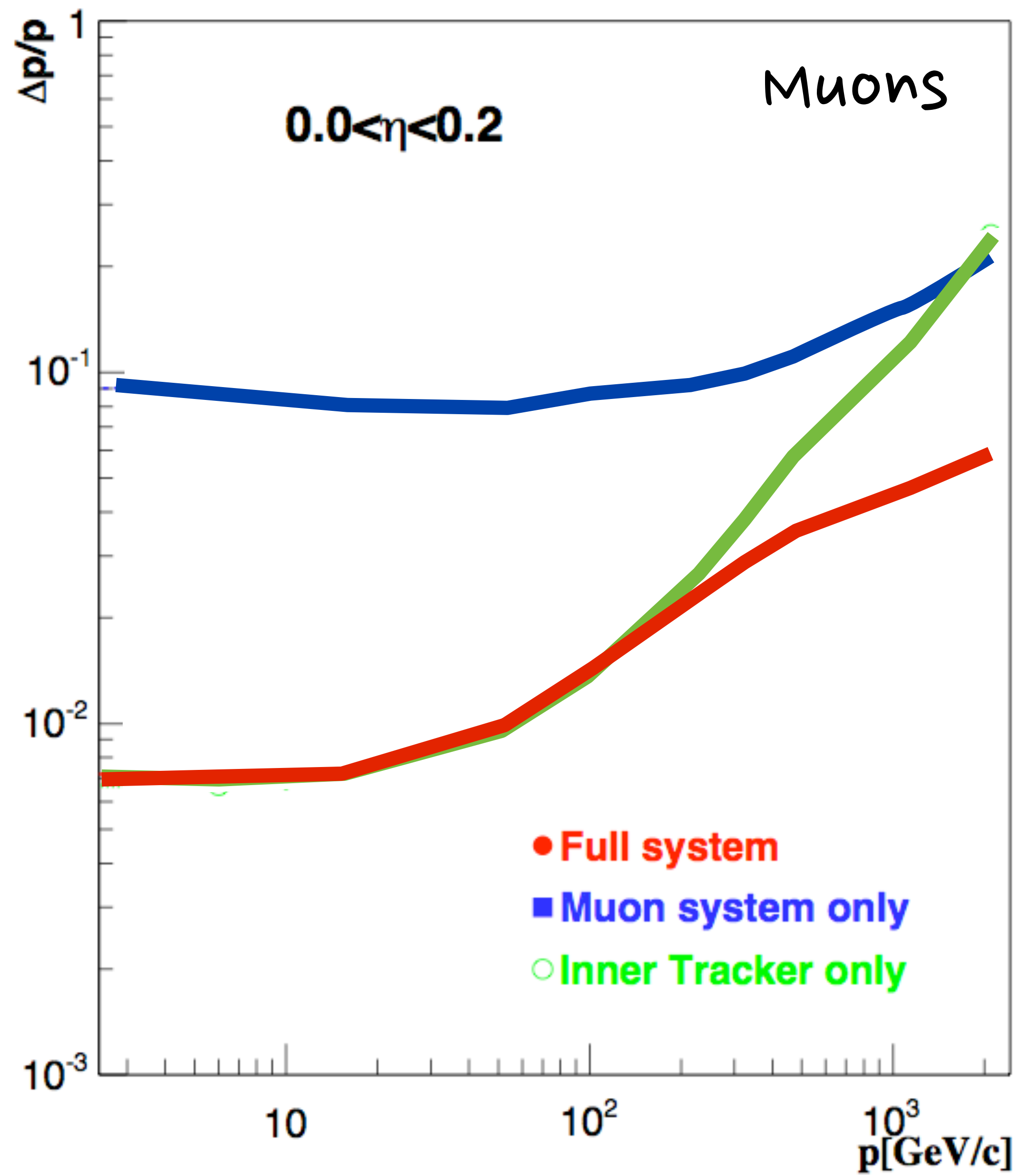


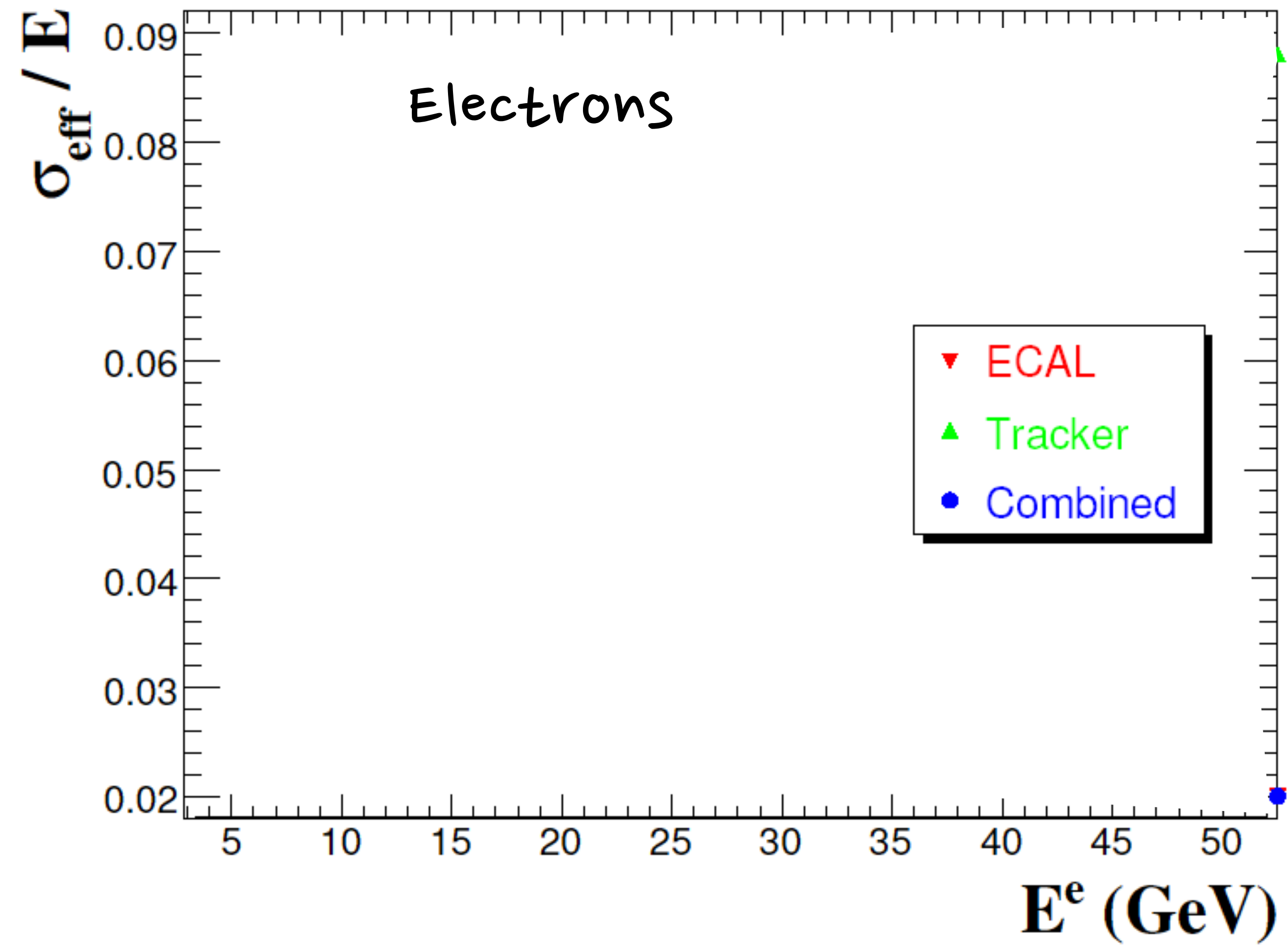
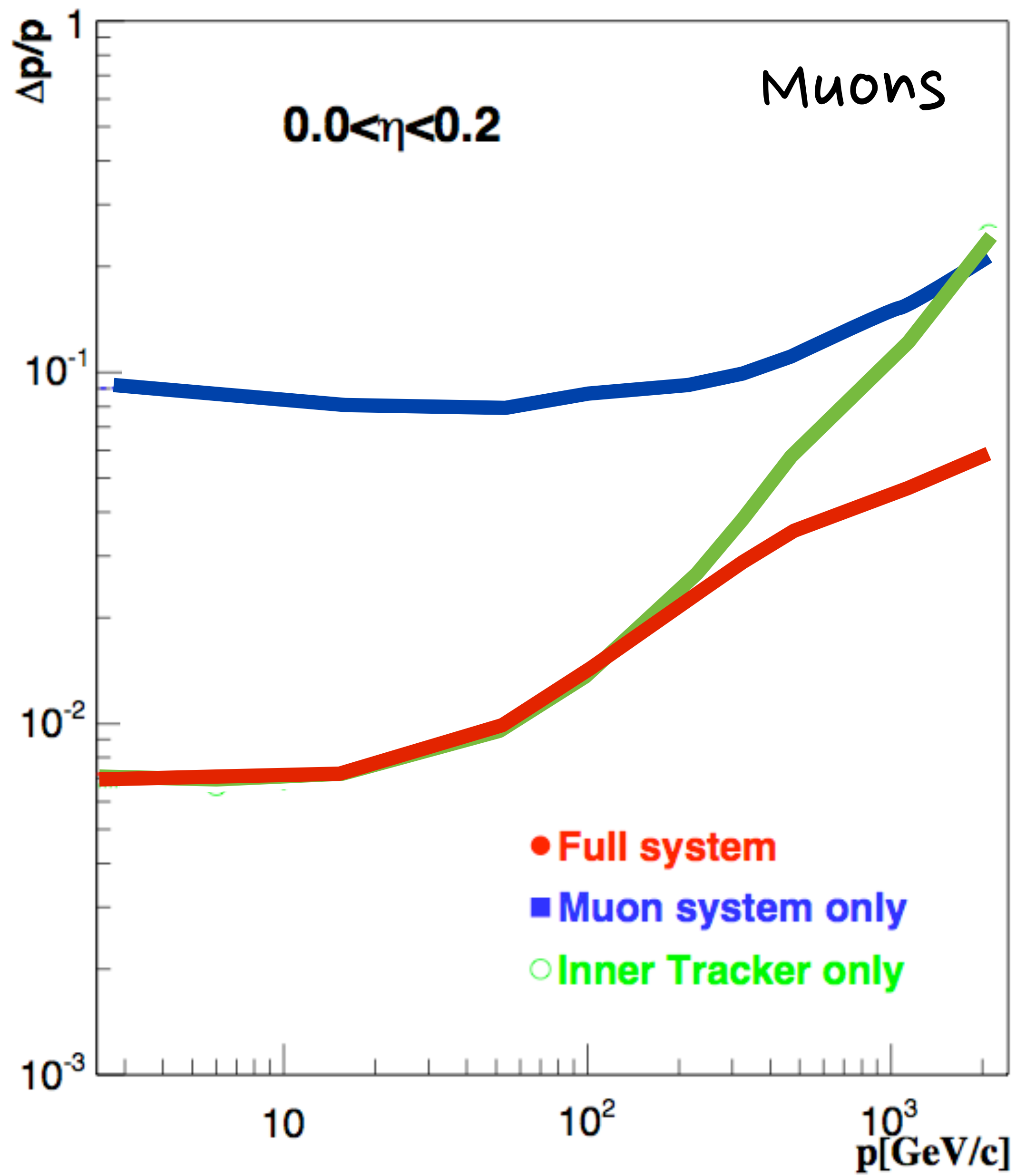


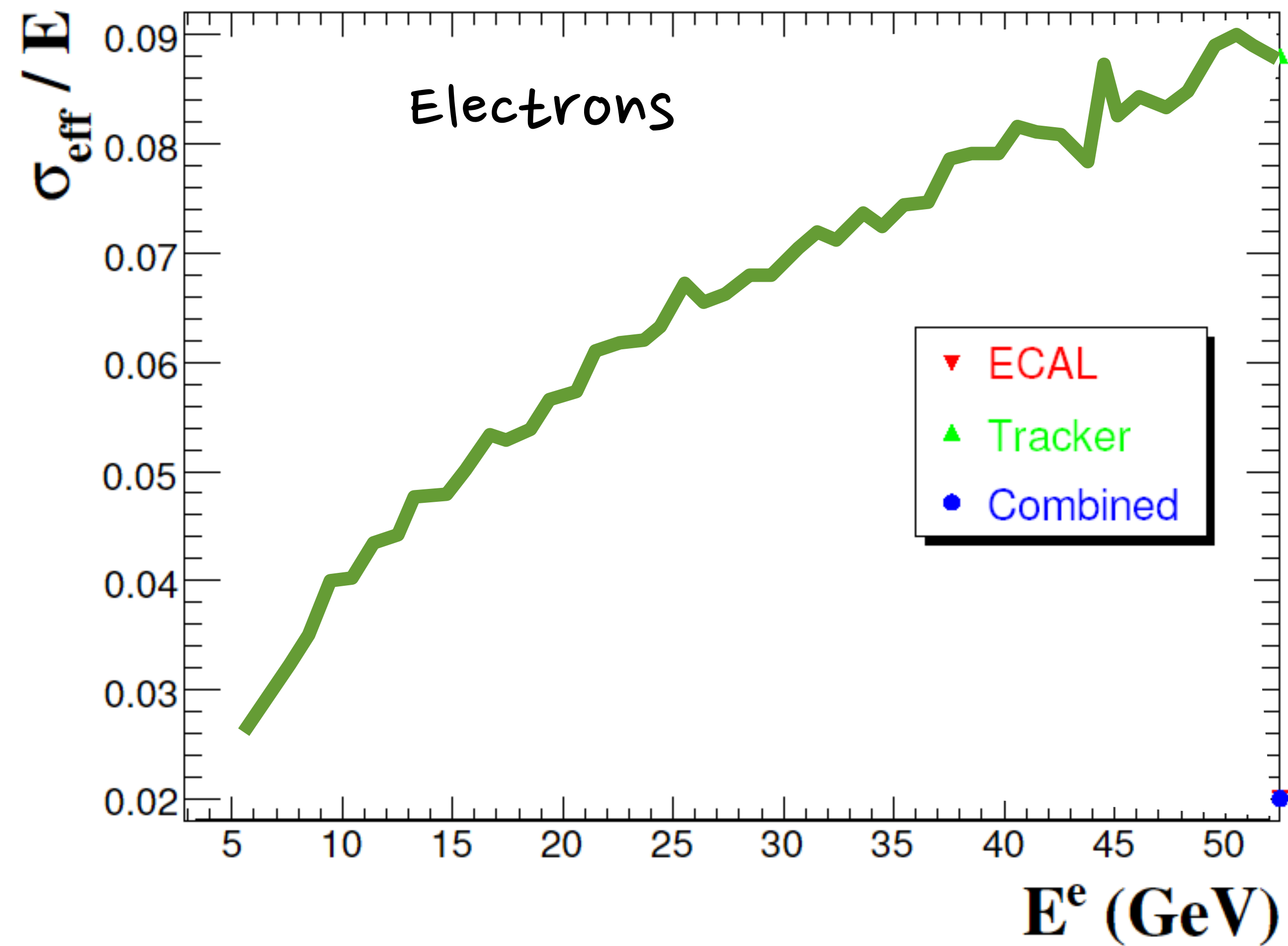
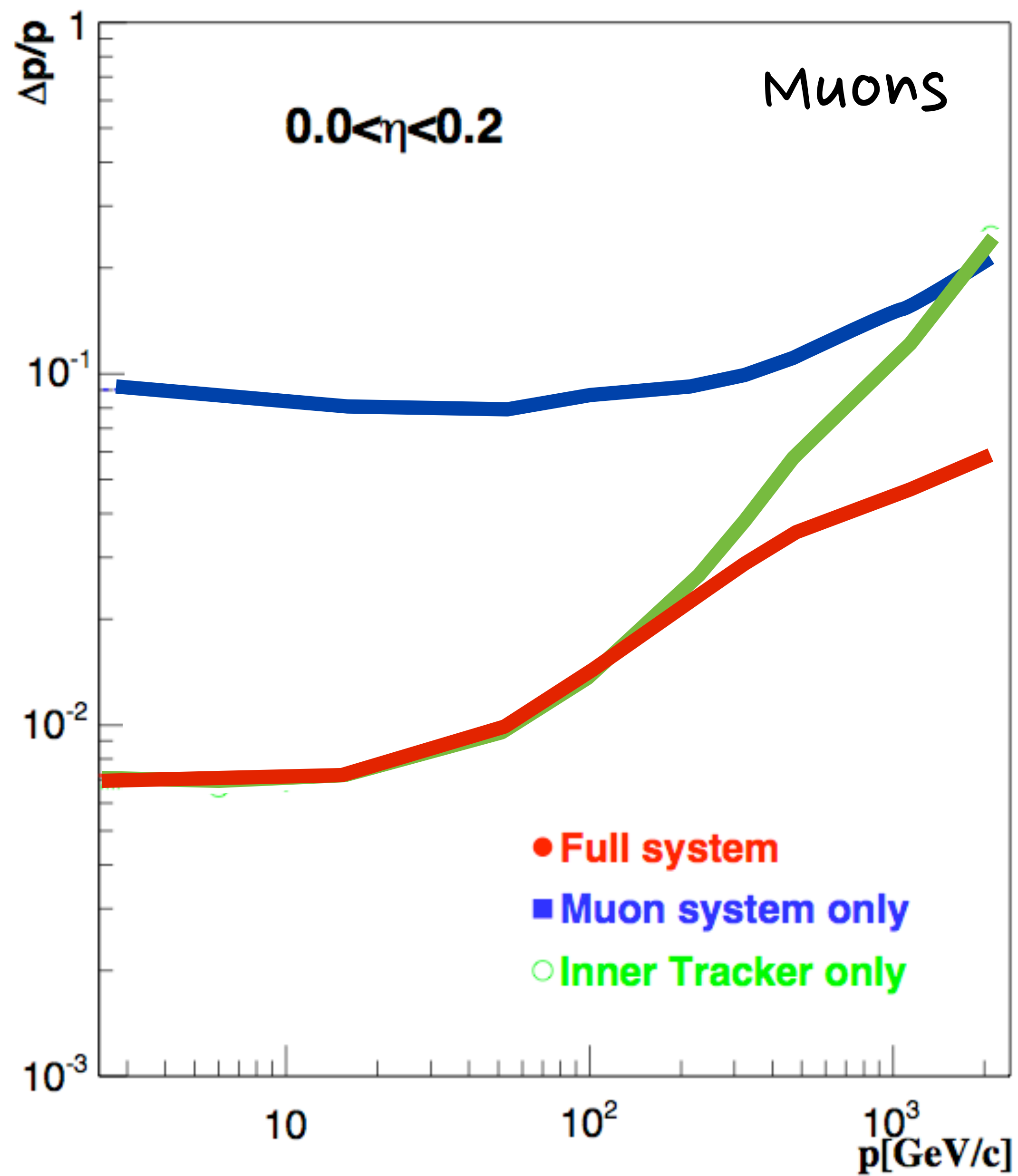


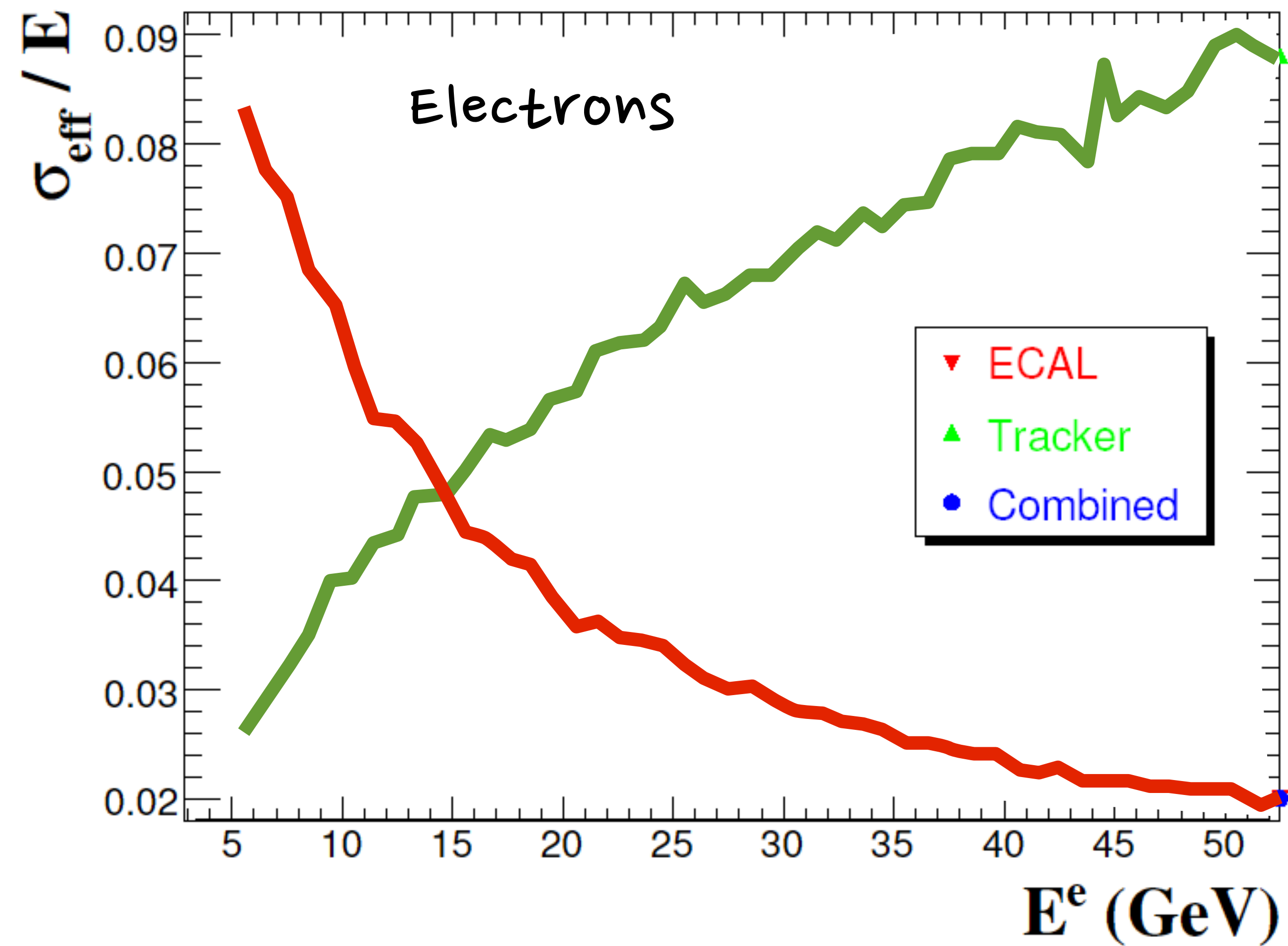
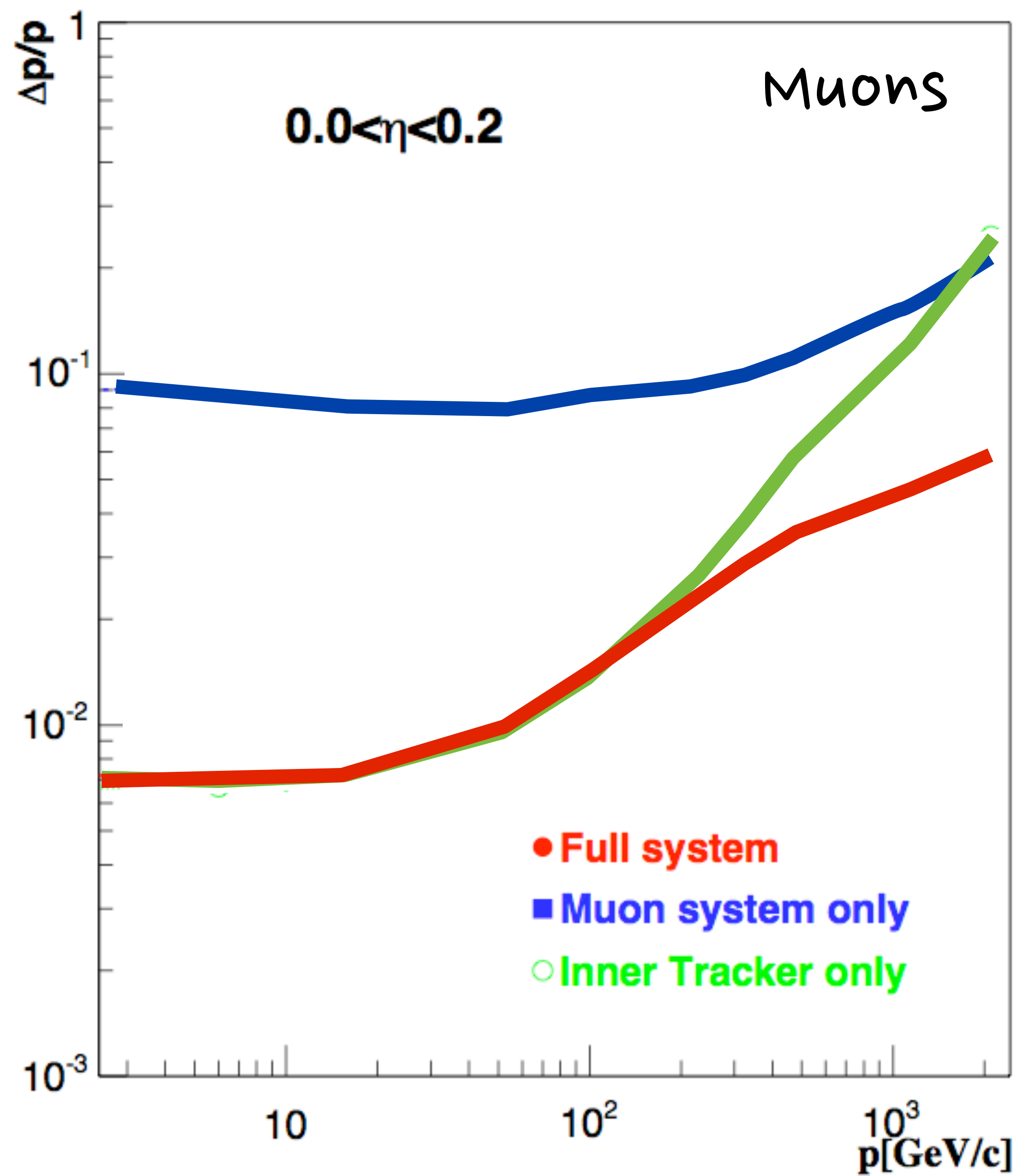


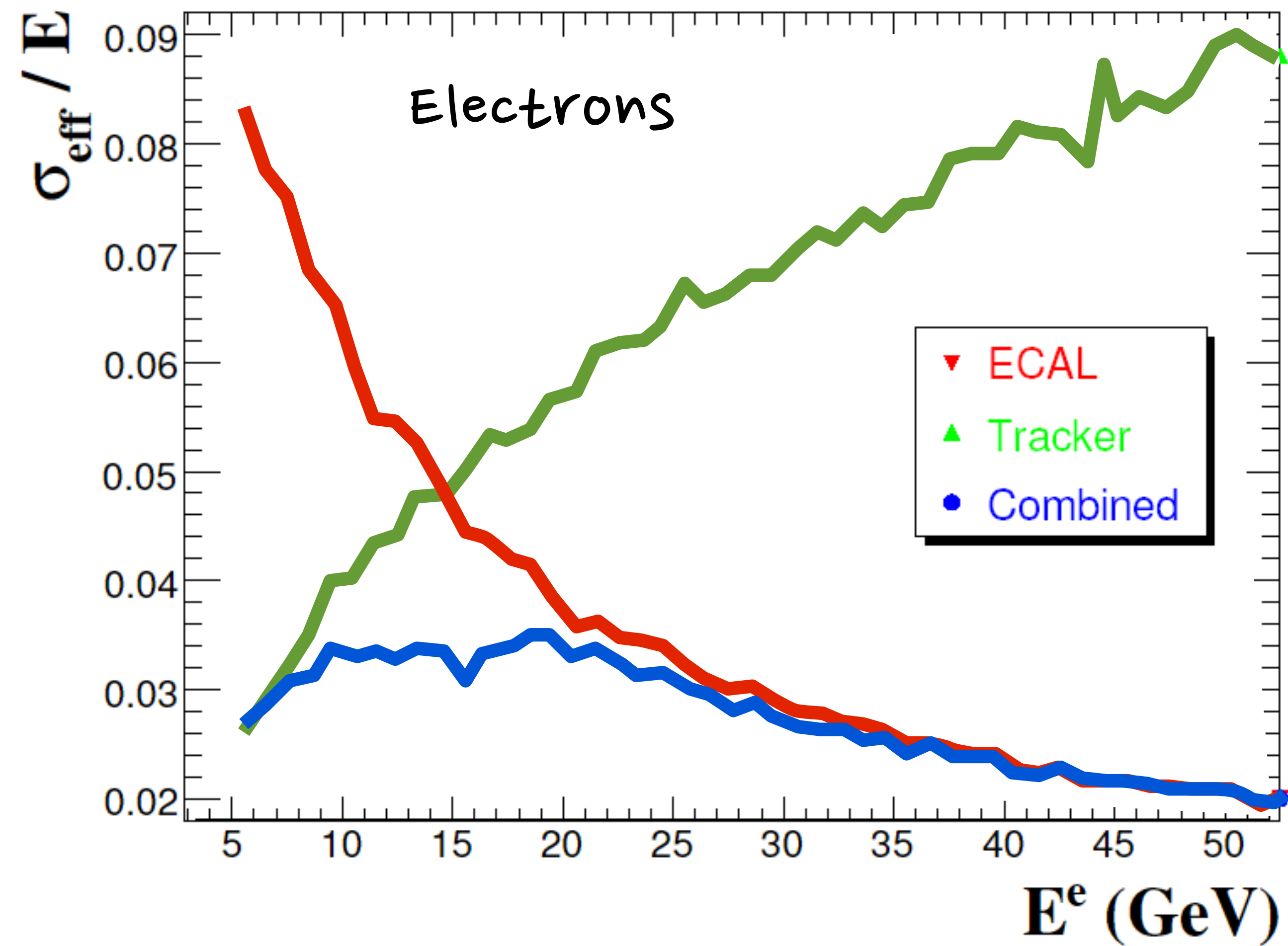
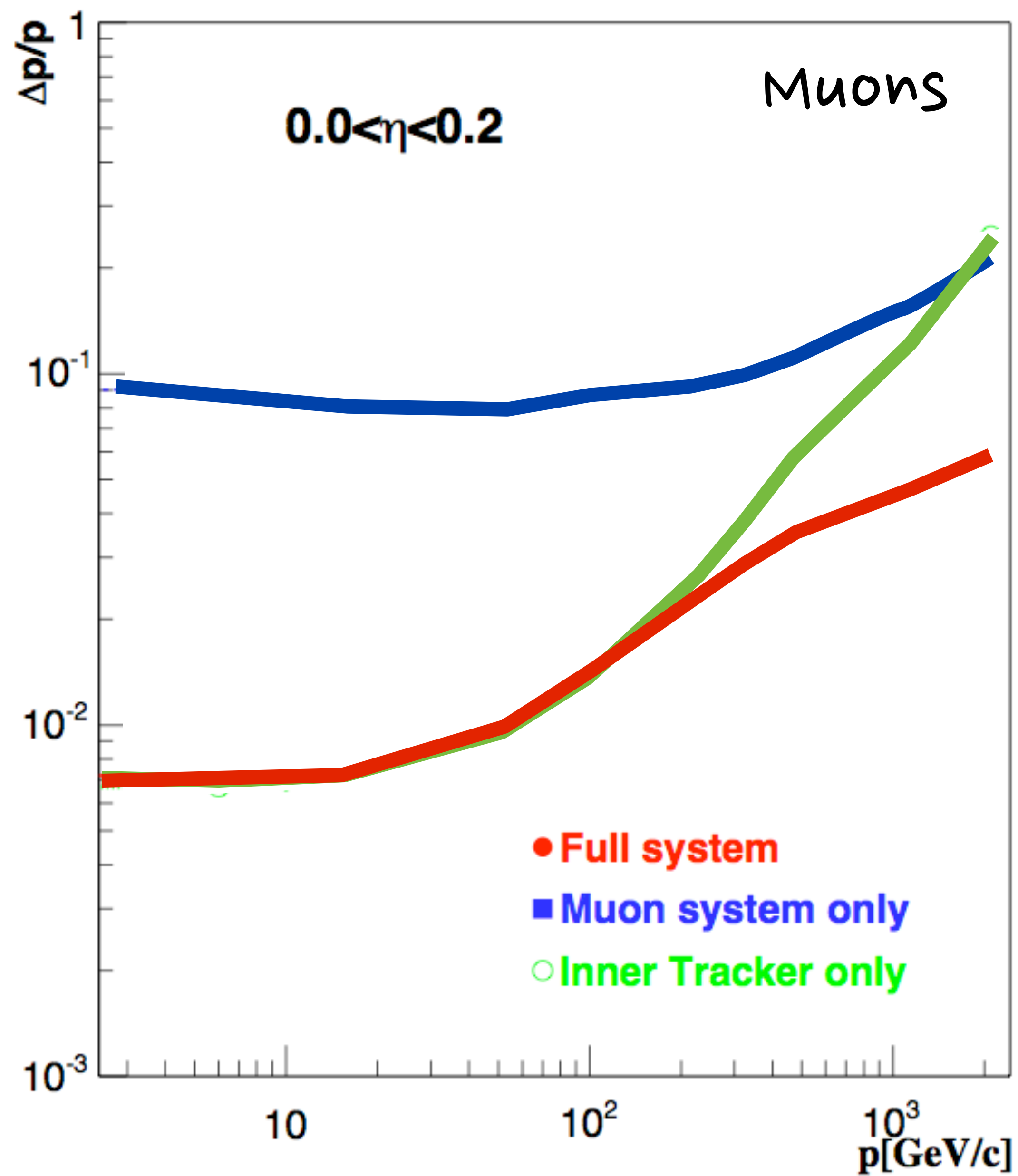












Back of envelope estimation for pions

Back of envelope estimation for pions

Calorimeter transverse energy uncertainty for
charged hadrons

Back of envelope estimation for pions

Calorimeter transverse energy uncertainty for
charged hadrons

$$\sigma(E_T) \approx 100\% \sqrt{E_T}$$

Back of envelope estimation for pions

Calorimeter transverse energy uncertainty for
charged hadrons

$$\sigma(E_T) \approx 100\% \sqrt{E_T}$$

Tracker transverse momentum uncertainty for
charged hadrons

Back of envelope estimation for pions

Calorimeter transverse energy uncertainty for charged hadrons

$$\sigma(E_T) \approx 100\% \sqrt{E_T}$$

Tracker transverse momentum uncertainty for charged hadrons

$$\sigma(p_T) \approx 0.01\% (p_T)^2$$

Back of envelope estimation for pions

Calorimeter transverse energy uncertainty for charged hadrons

$$\sigma(E_T) \approx 100\% \sqrt{E_T}$$

Tracker transverse momentum uncertainty for charged hadrons

$$\sigma(p_T) \approx 0.01\% (p_T)^2$$

The point at which the calorimeter resolution overcomes the tracker resolution is very roughly

Back of envelope estimation for pions

Calorimeter transverse energy uncertainty for charged hadrons

$$\sigma(E_T) \approx 100\% \sqrt{E_T}$$

Tracker transverse momentum uncertainty for charged hadrons

$$\sigma(p_T) \approx 0.01\% (p_T)^2$$

The point at which the calorimeter resolution overcomes the tracker resolution is very roughly

$$\frac{\sigma(p_T)}{p_T} \approx \frac{\sigma(E_T)}{E_T} \rightarrow p_T \approx 10^{\frac{8}{3}} \approx 460 \text{ GeV}$$

Back of envelope estimation for pions

Calorimeter transverse energy uncertainty for charged hadrons

$$\sigma(E_T) \approx 100\% \sqrt{E_T}$$

Tracker transverse momentum uncertainty for charged hadrons

$$\sigma(p_T) \approx 0.01\% (p_T)^2$$

The point at which the calorimeter resolution overcomes the tracker resolution is very roughly

$$\frac{\sigma(p_T)}{p_T} \approx \frac{\sigma(E_T)}{E_T} \rightarrow p_T \approx 10^{\frac{8}{3}} \approx 460 \text{ GeV}$$

Almost always pays to use the tracker p_T , rather than calorimeter E_T

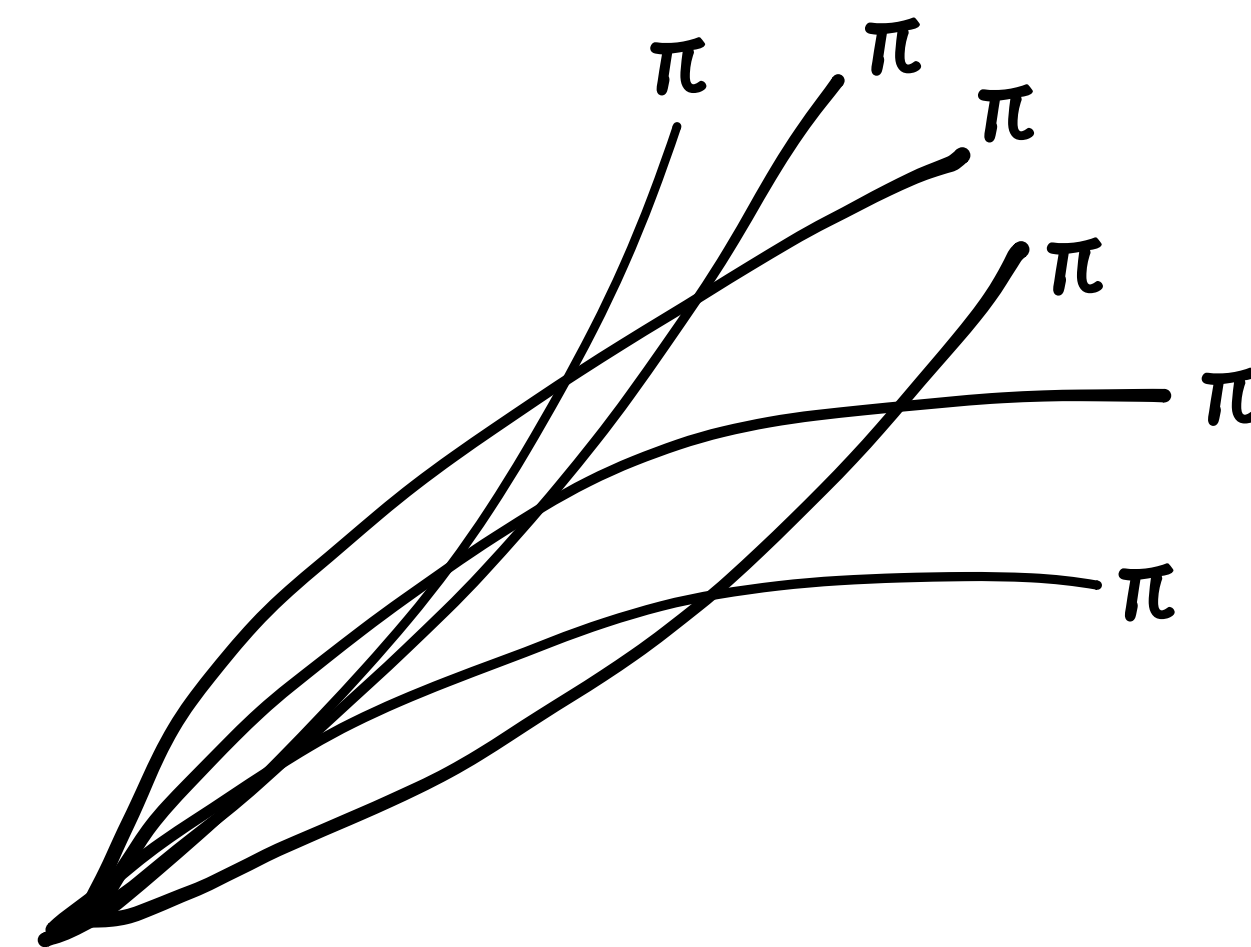
Set the stage: Jet Composition

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- Charged Particles: ~60%

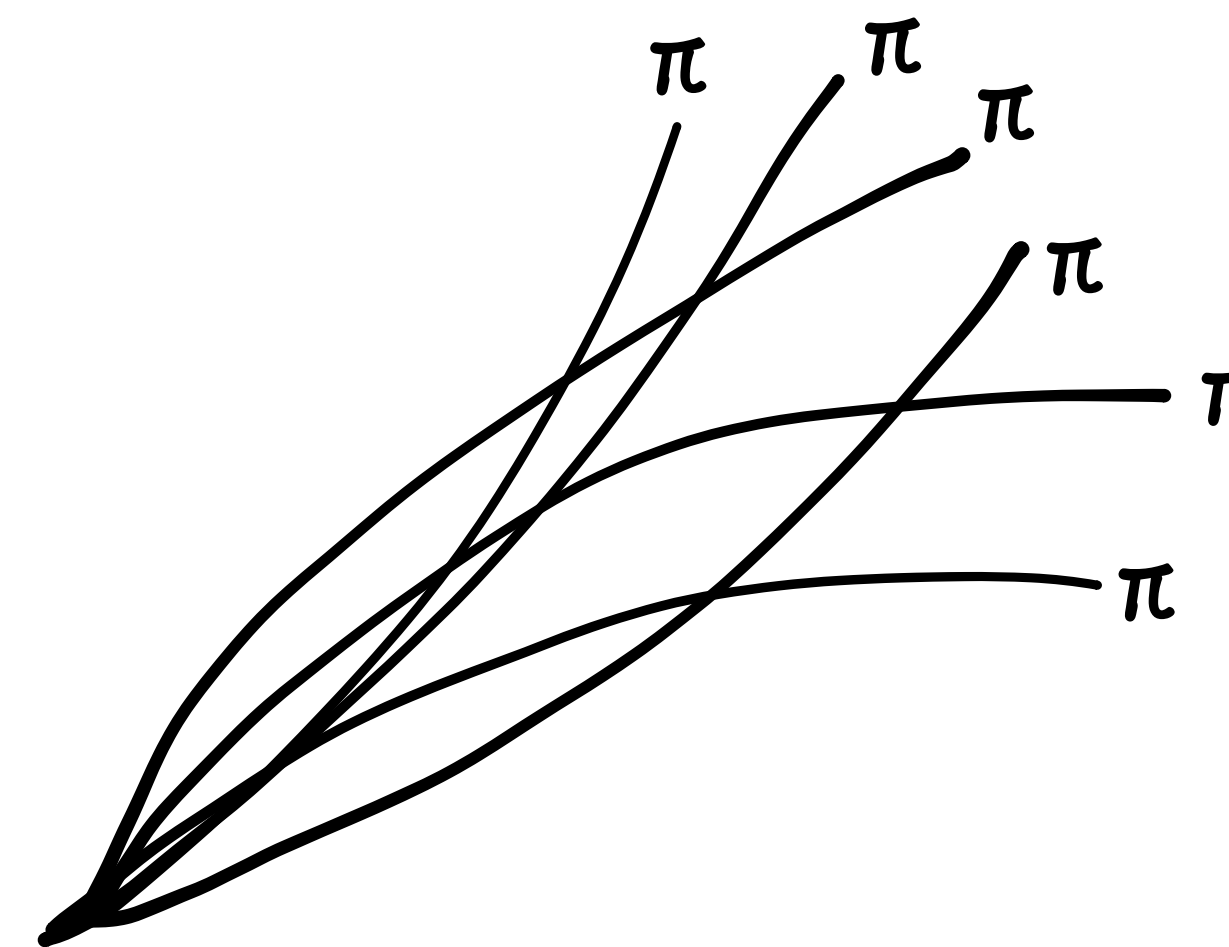
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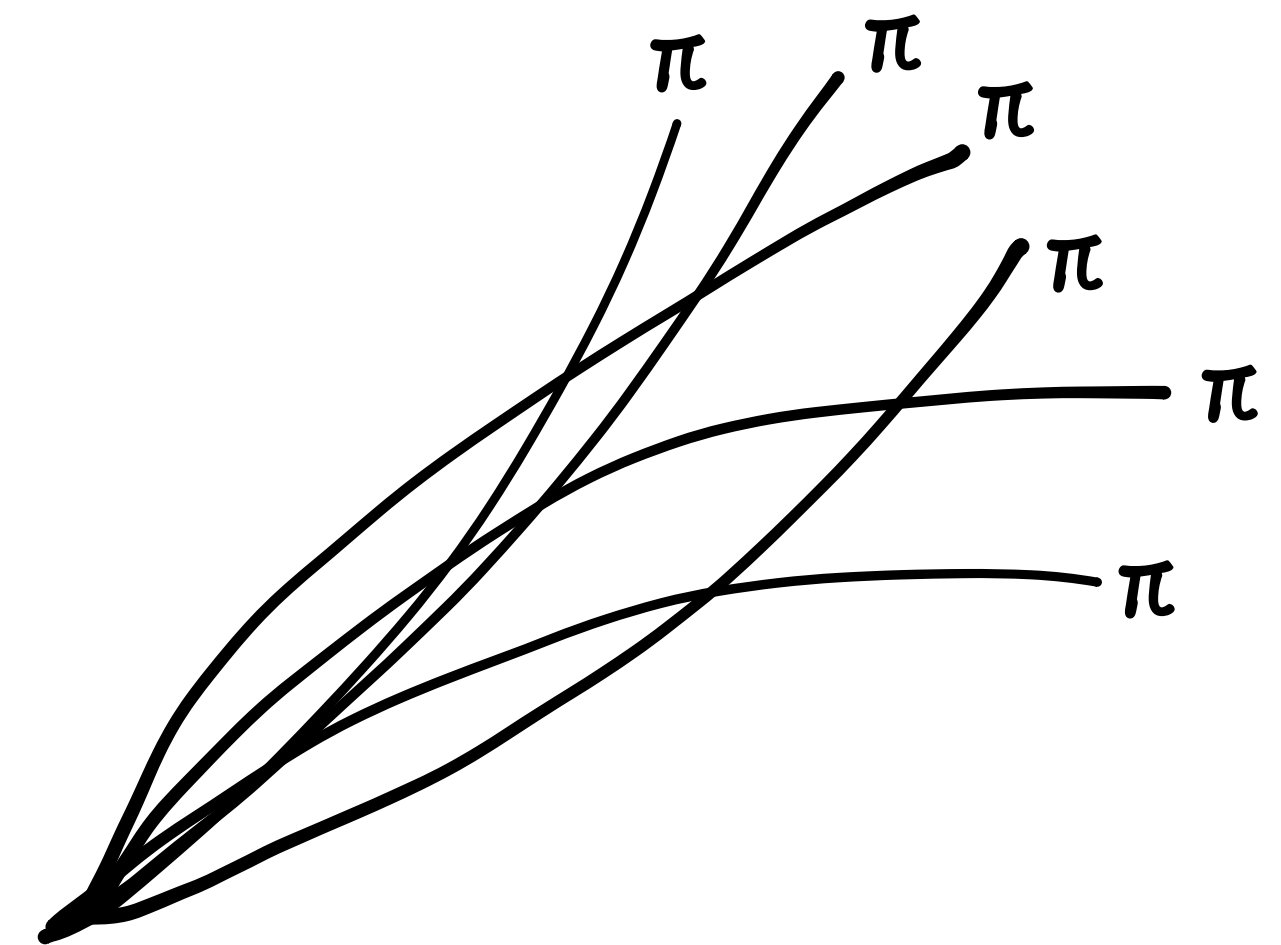
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 - Mostly charged pions, kaons and protons, but also some electrons and muons (decays in flight, semileptonic B decays, etc)



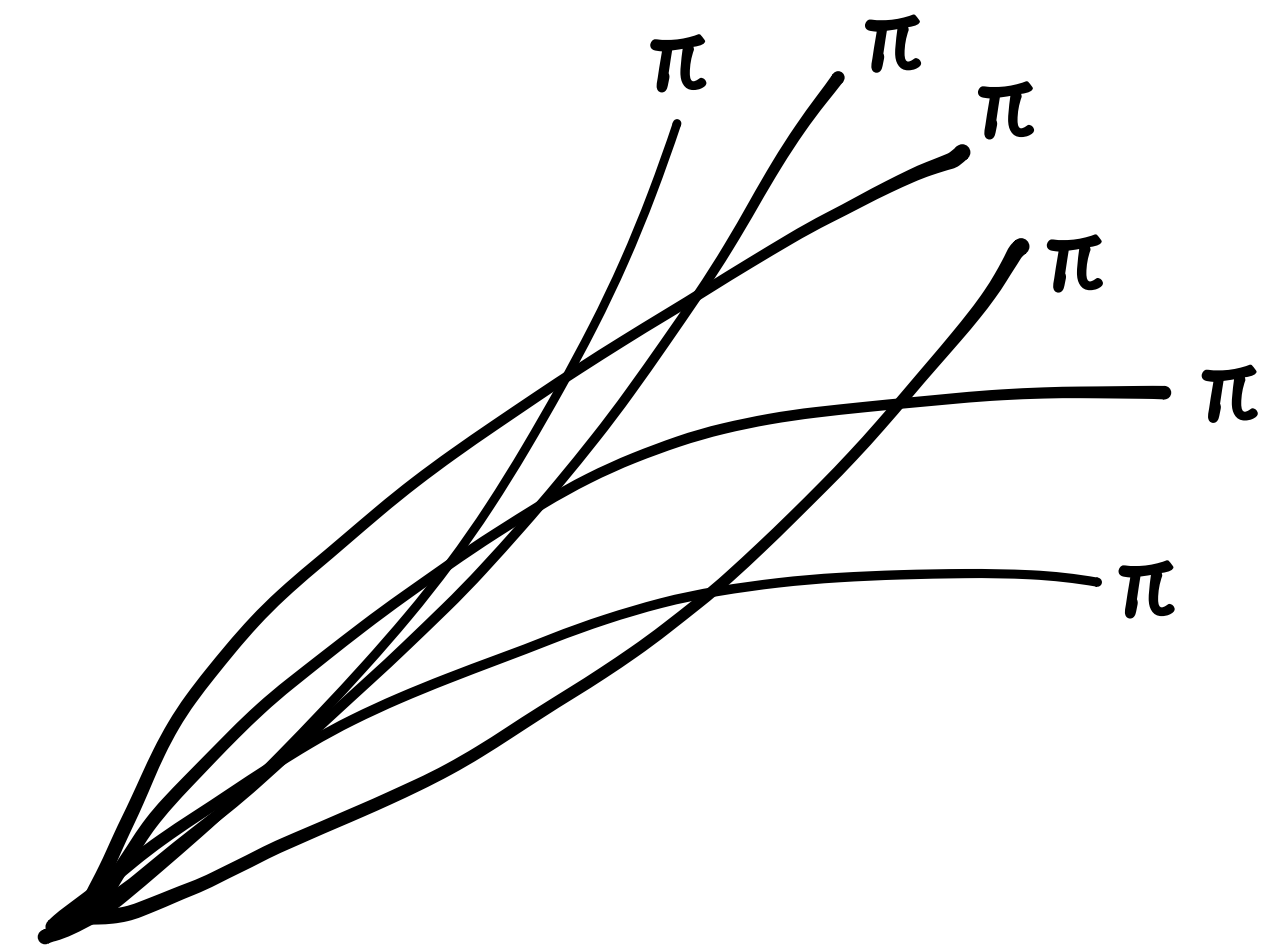
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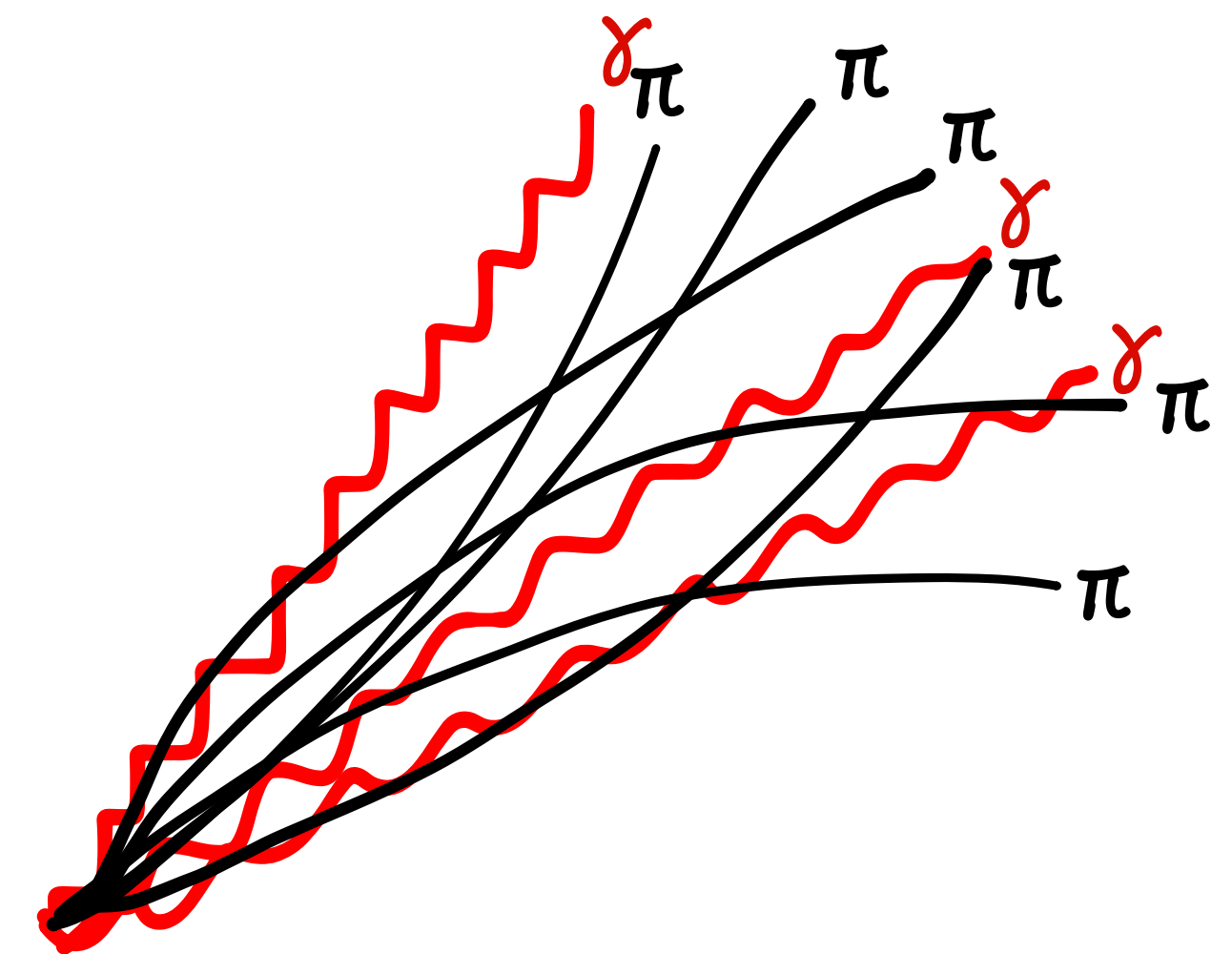
Set the stage: Jet Composition

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- Photons: ~25%



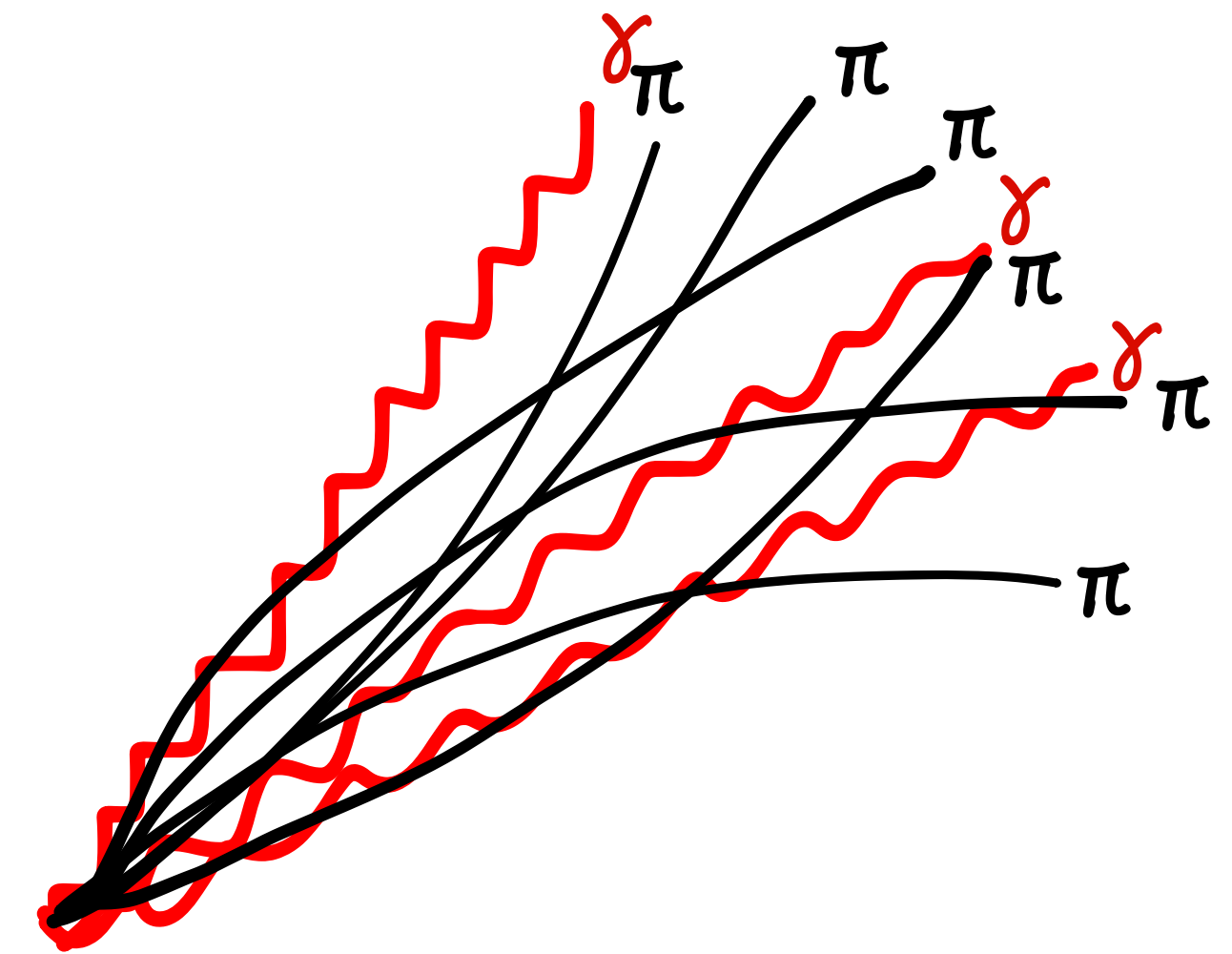
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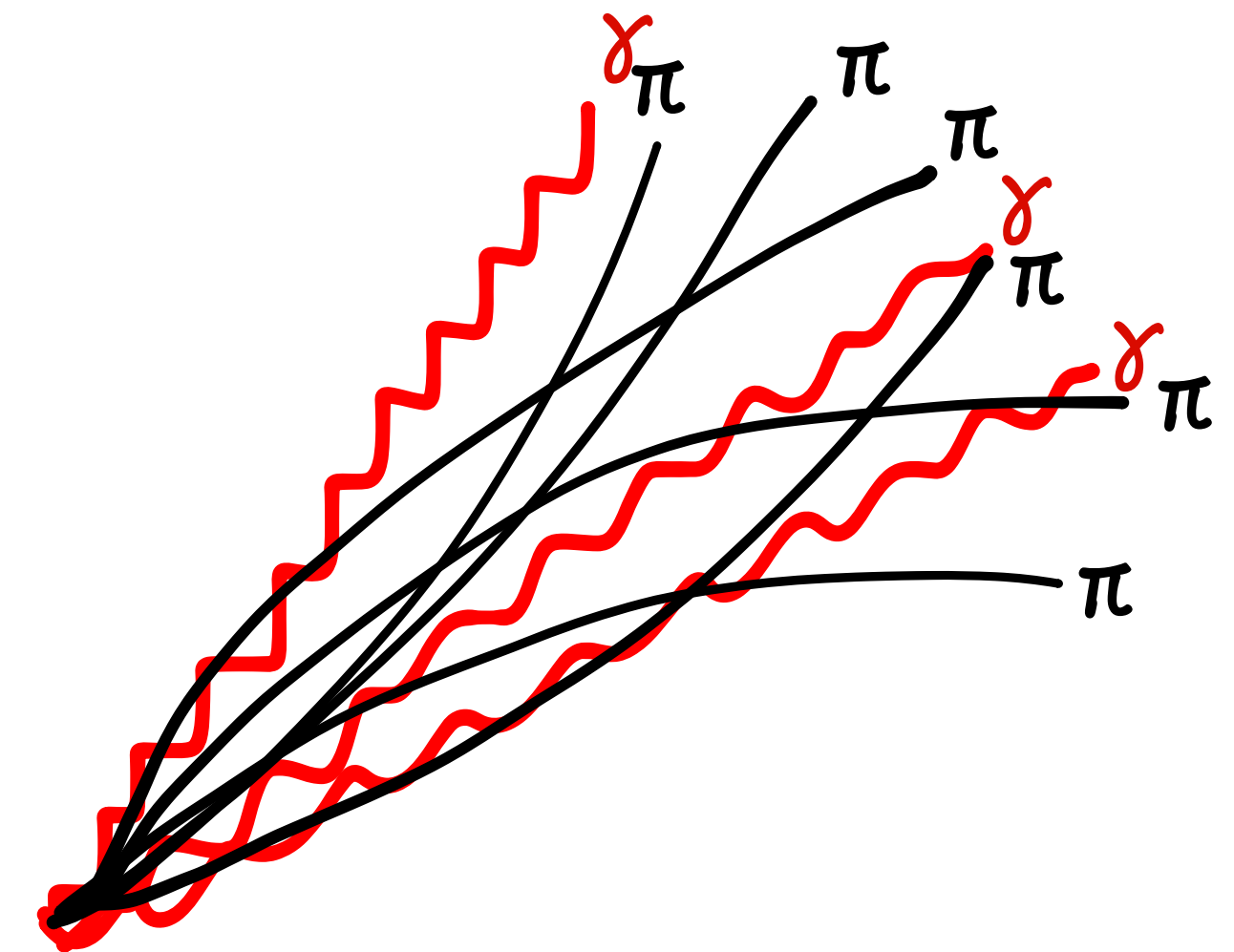
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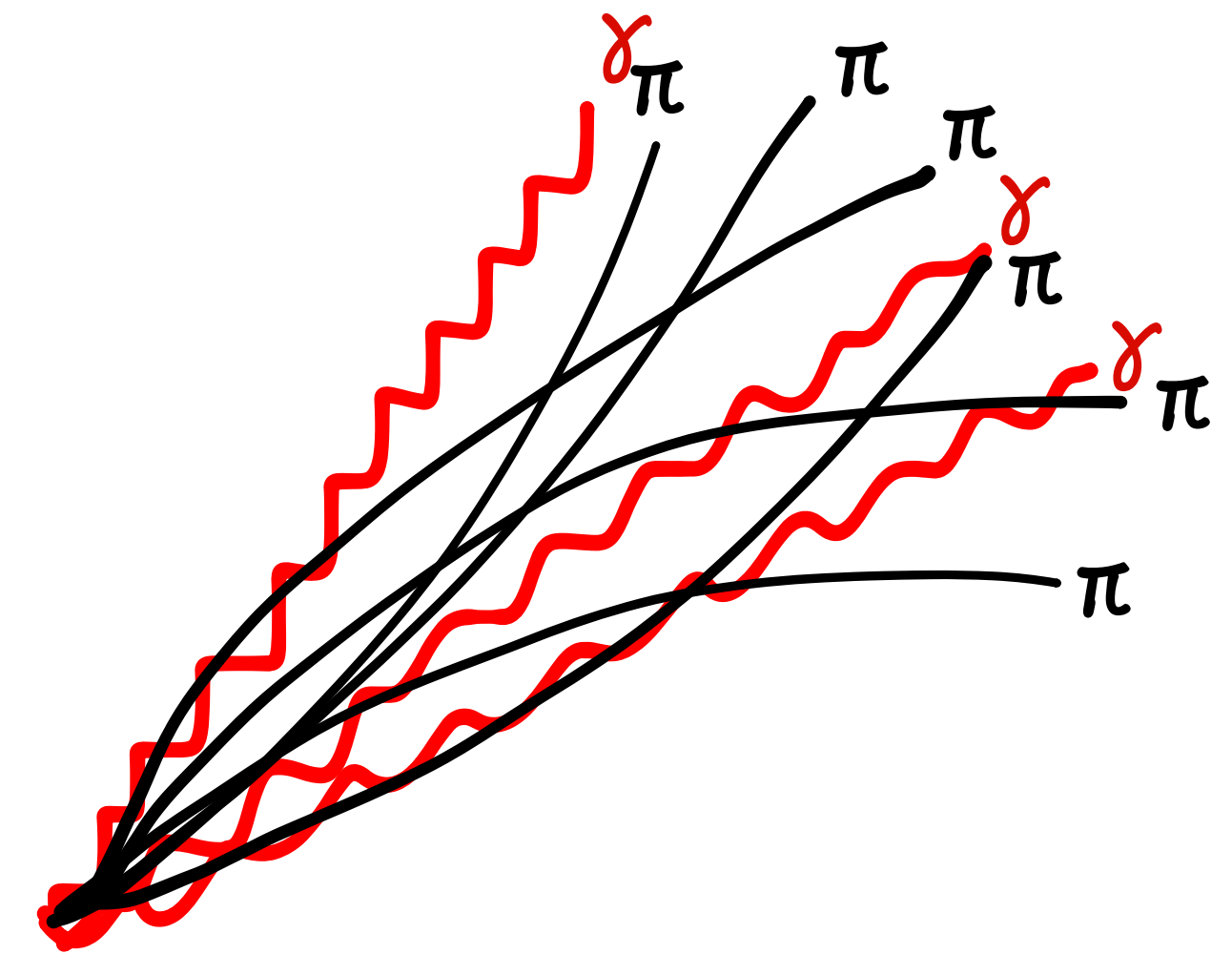
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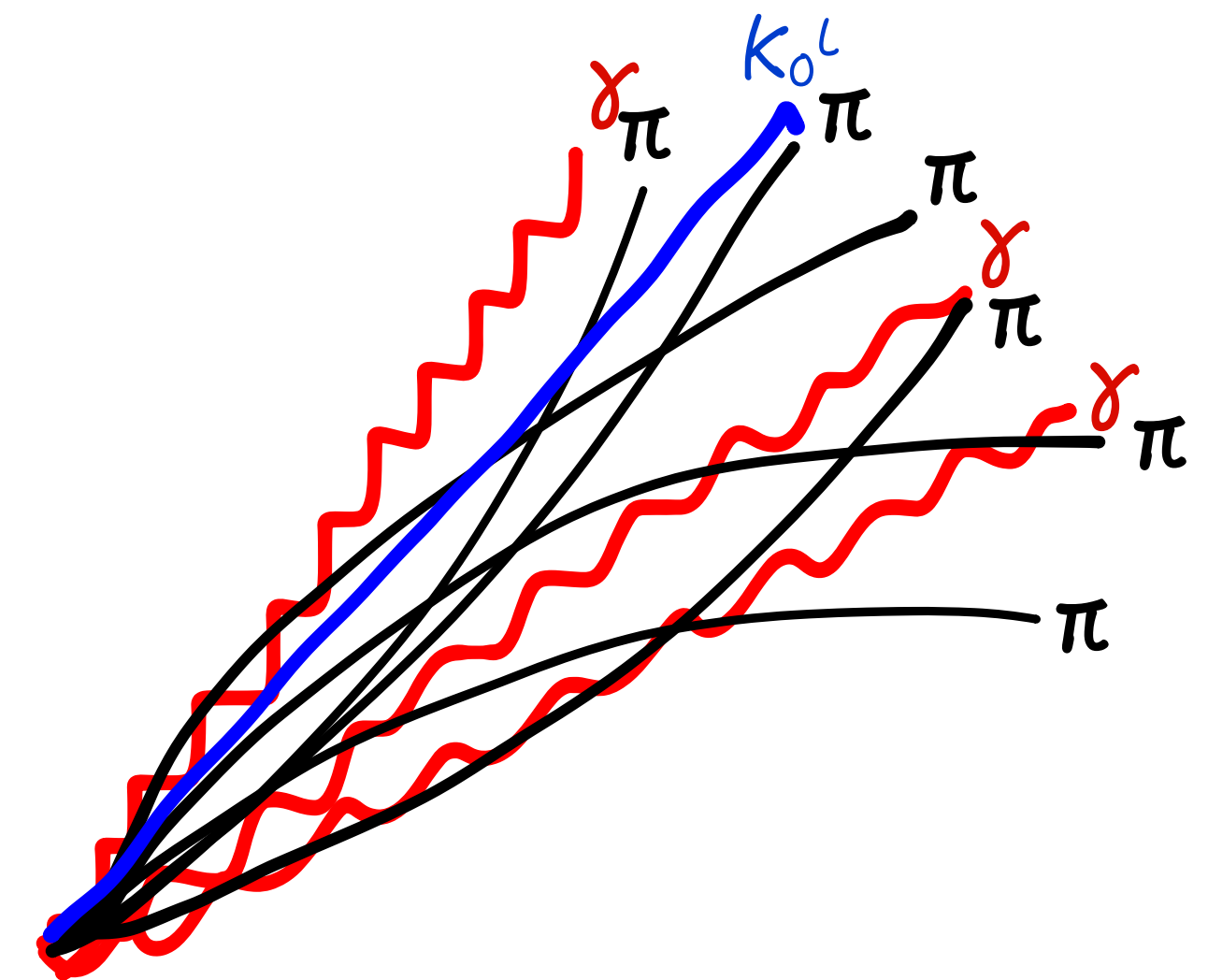
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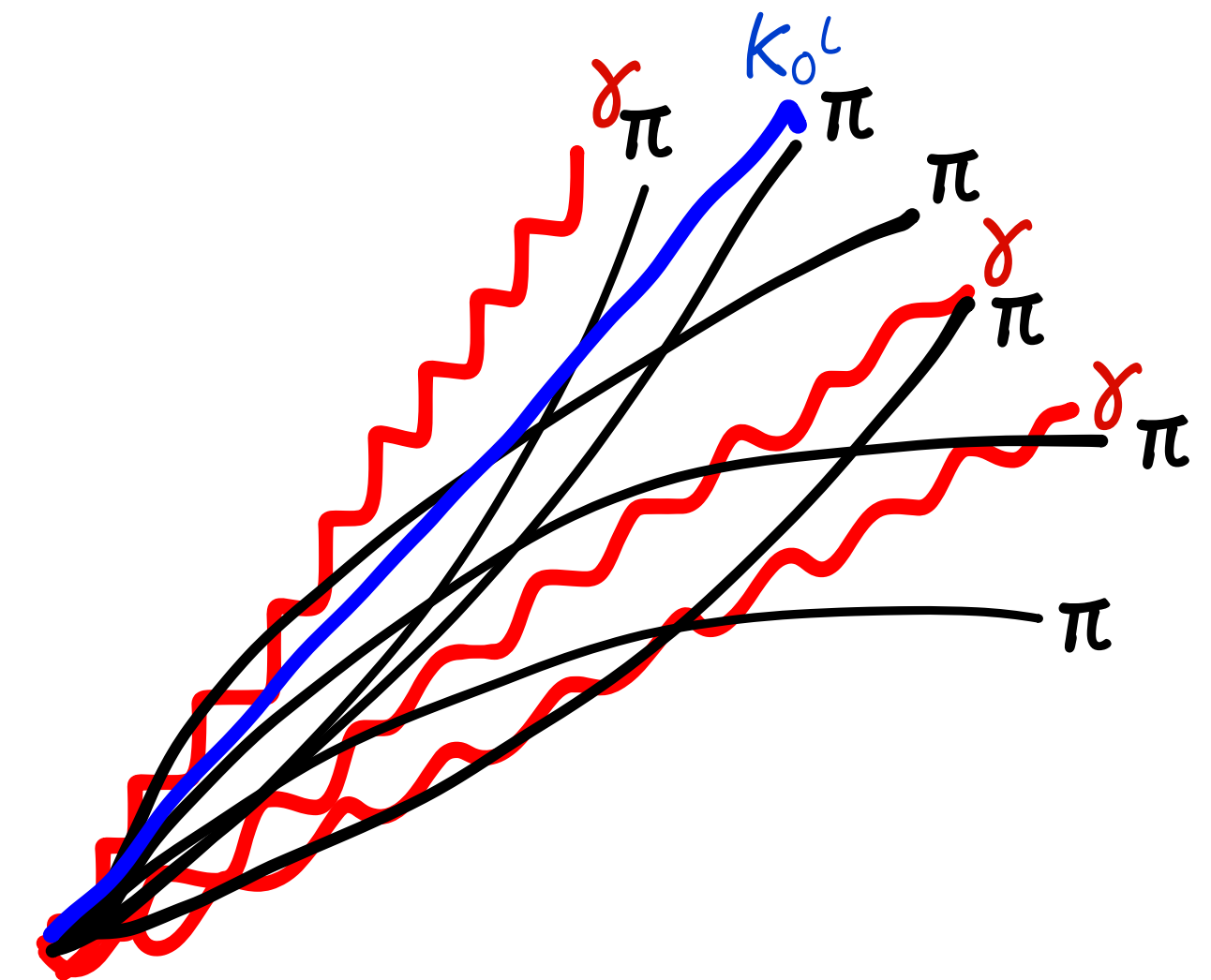
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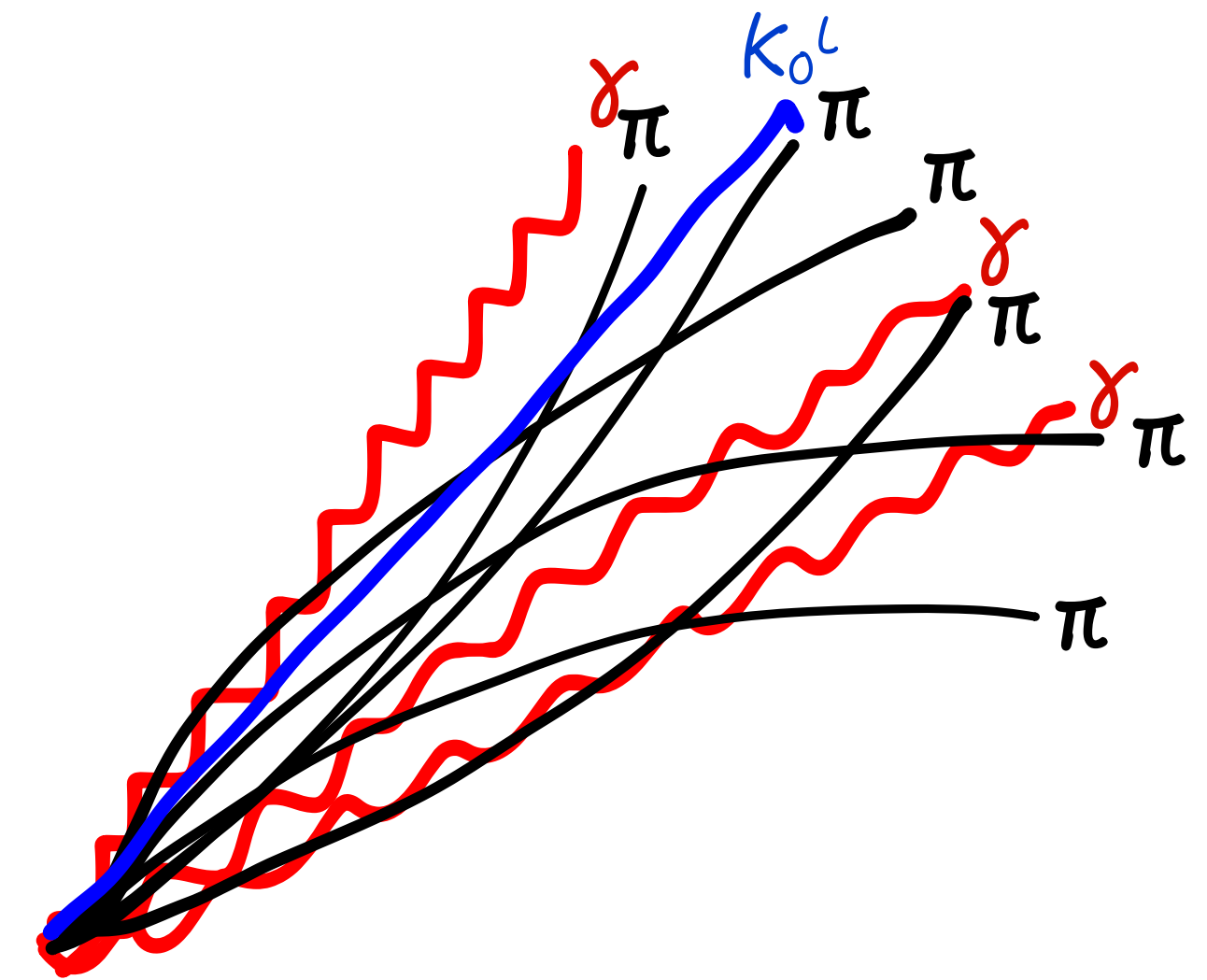
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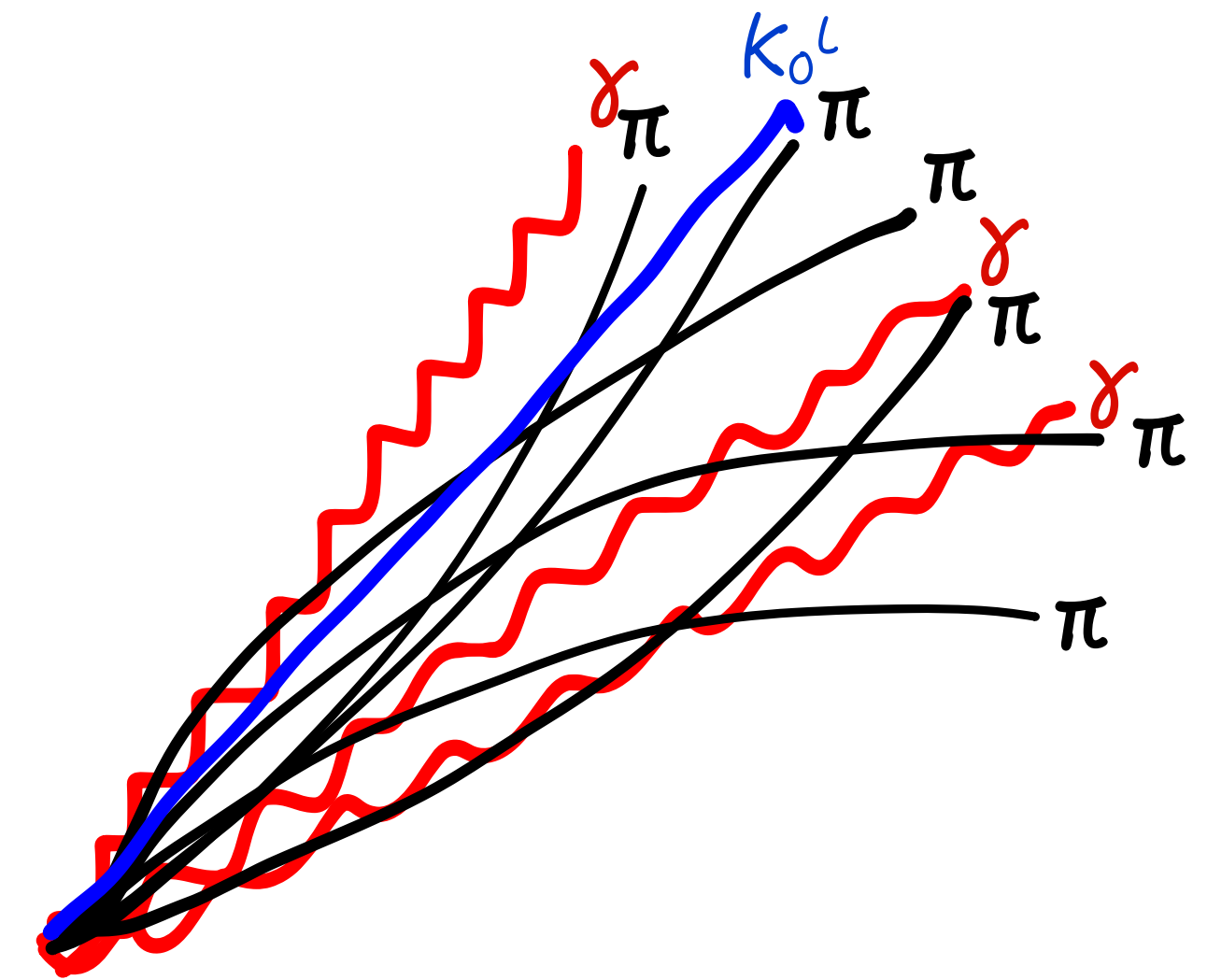
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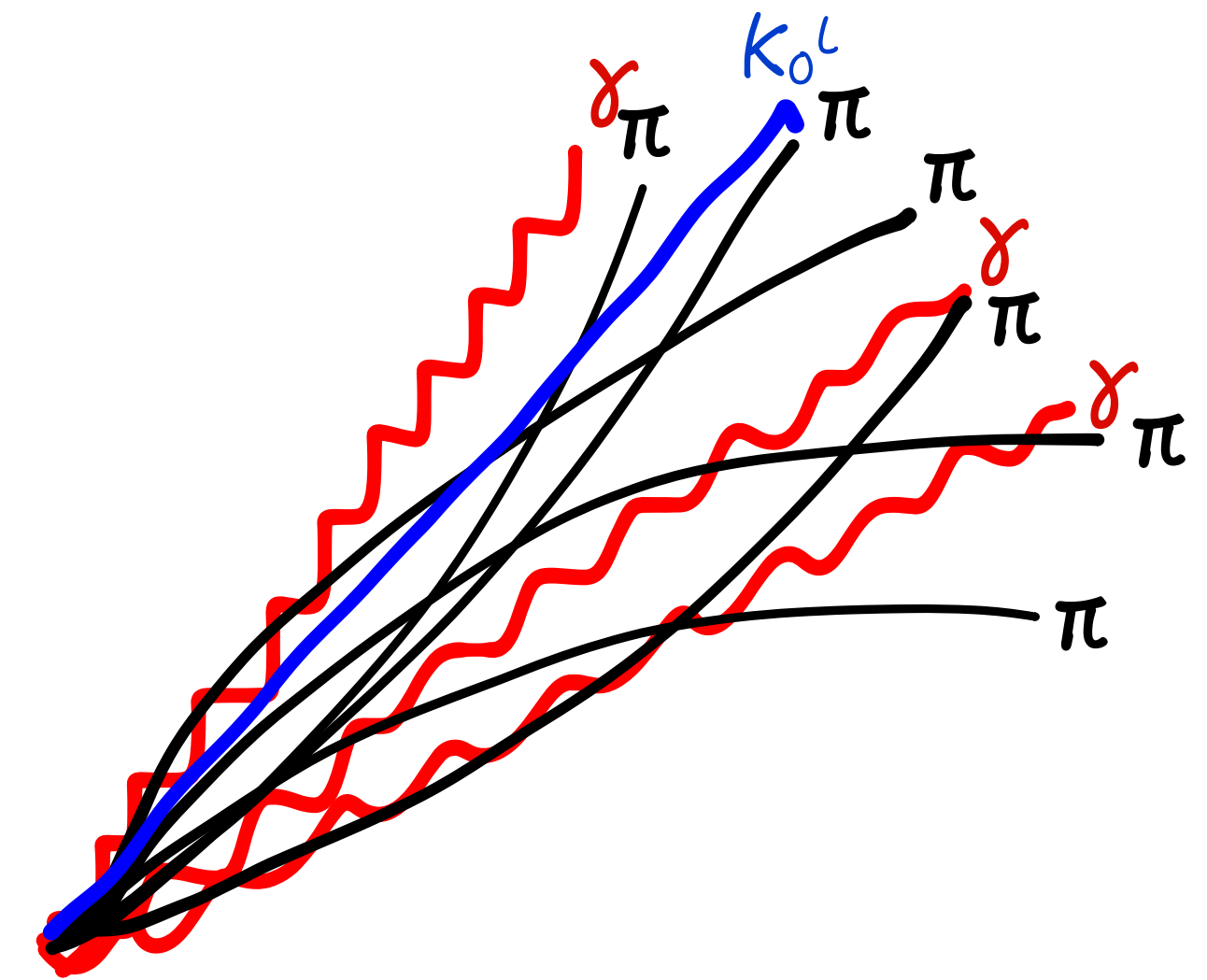
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- Short-lived Neutral Hadrons: ~5%



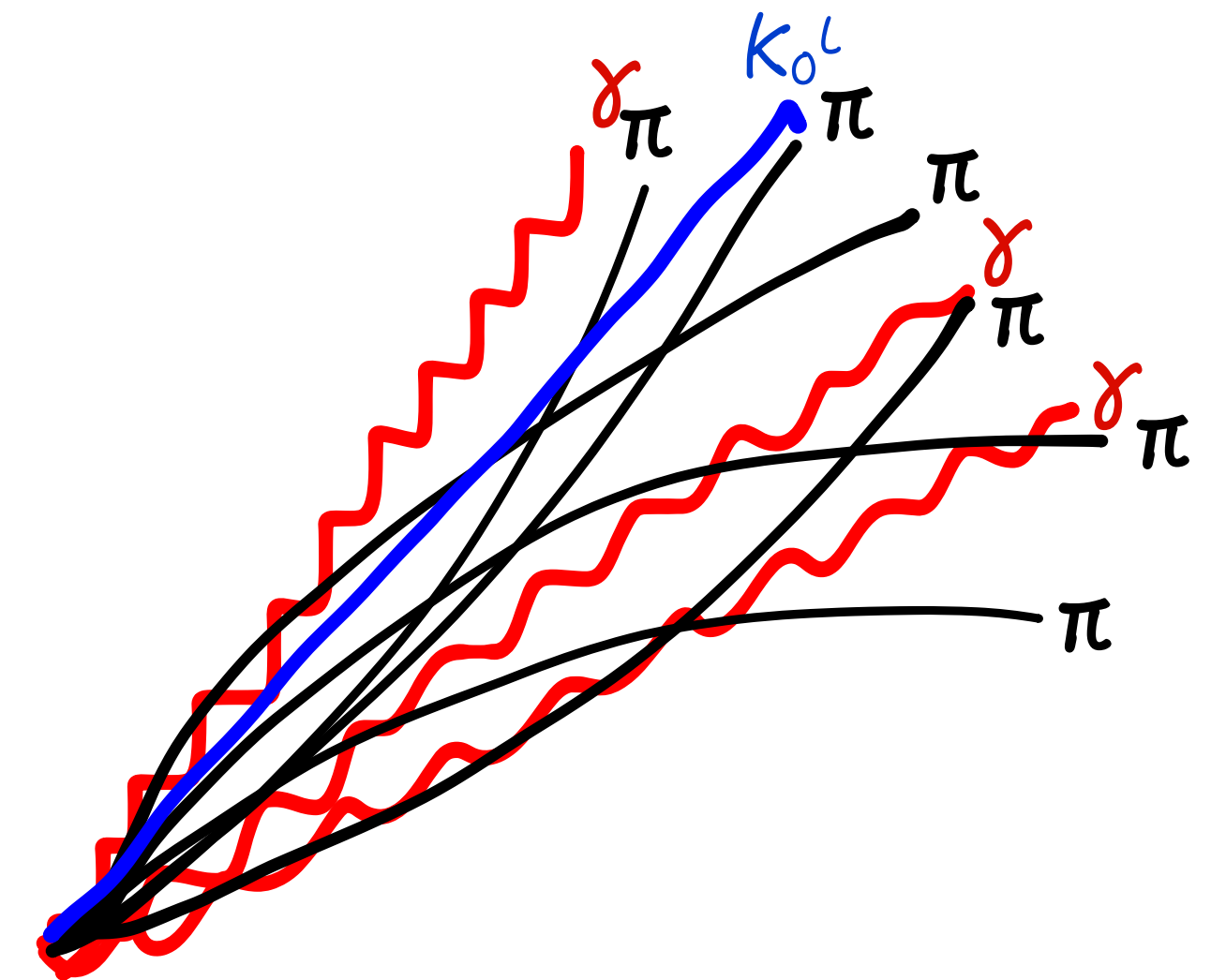
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 - $K_S^0 \rightarrow \pi^+\pi^-$, $\Lambda \rightarrow \pi^-p$, etc, but also γ conversions, and (more problematic) nuclear interactions in the detector material.



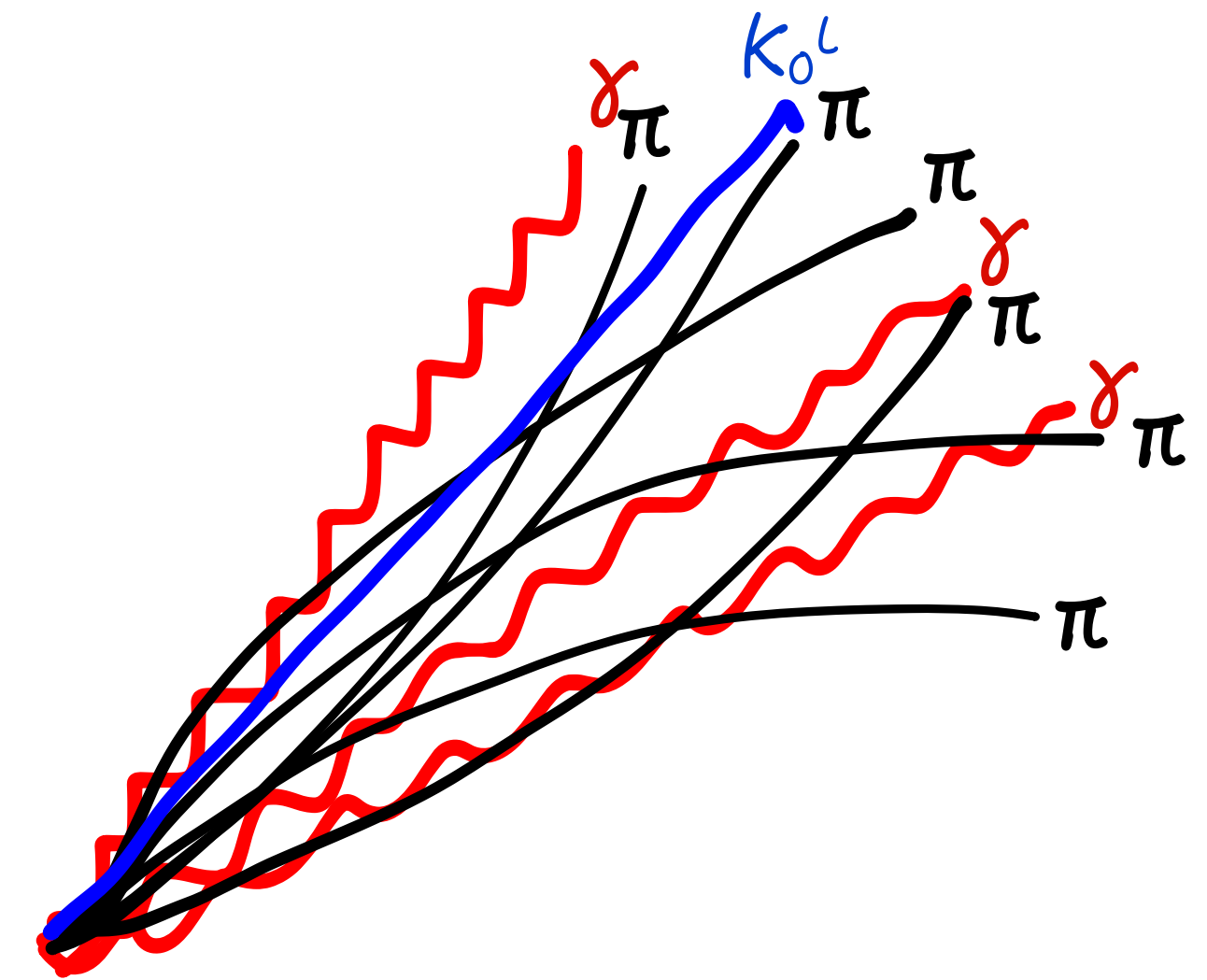
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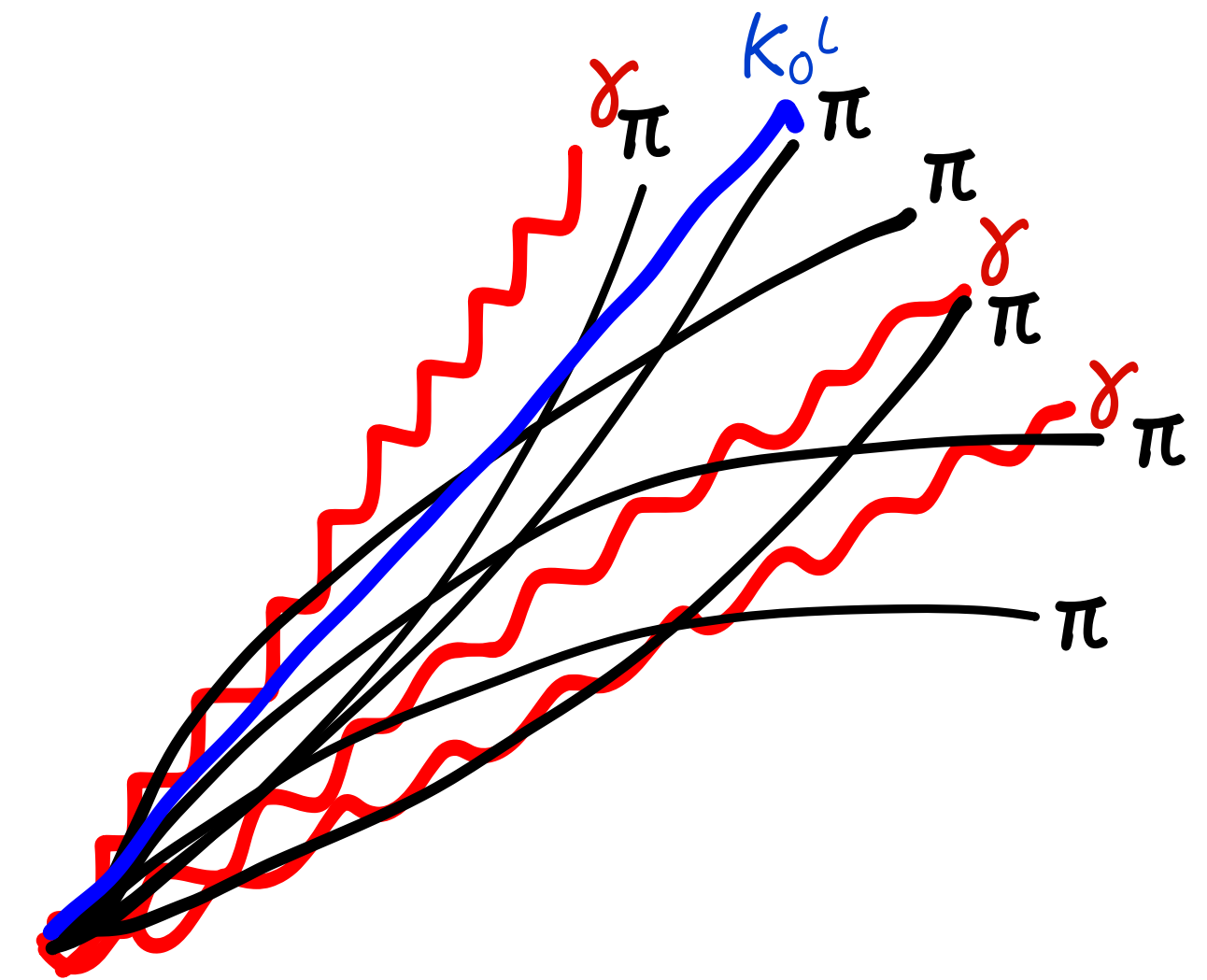
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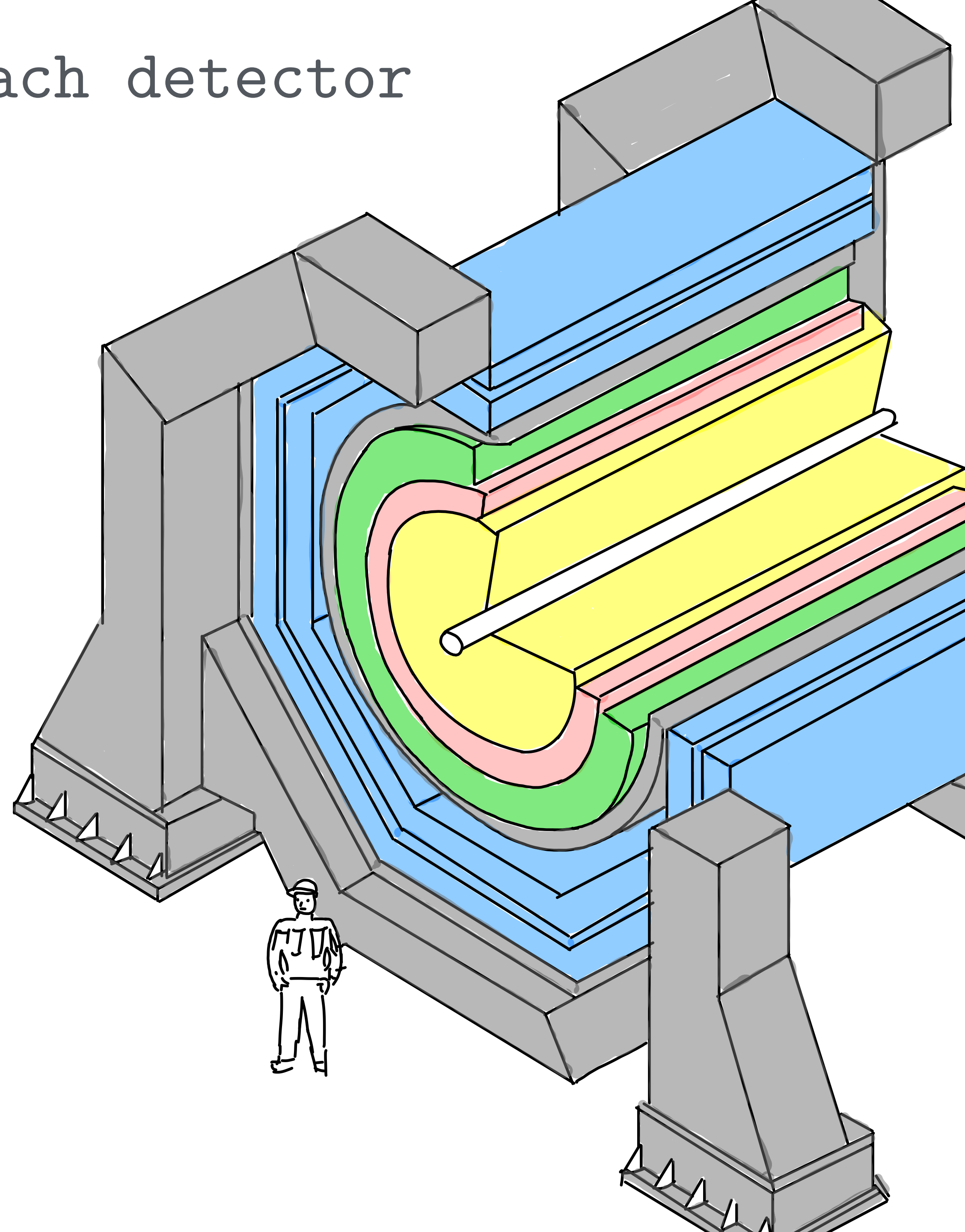


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 - $K_S^0 \rightarrow \pi^+\pi^-$, $\Lambda \rightarrow \pi^-p$, etc, but also γ conversions, and (more problematic) nuclear interactions in the detector material.
- Jets are columnated
 - particles belonging to a jet not isolated (important later)

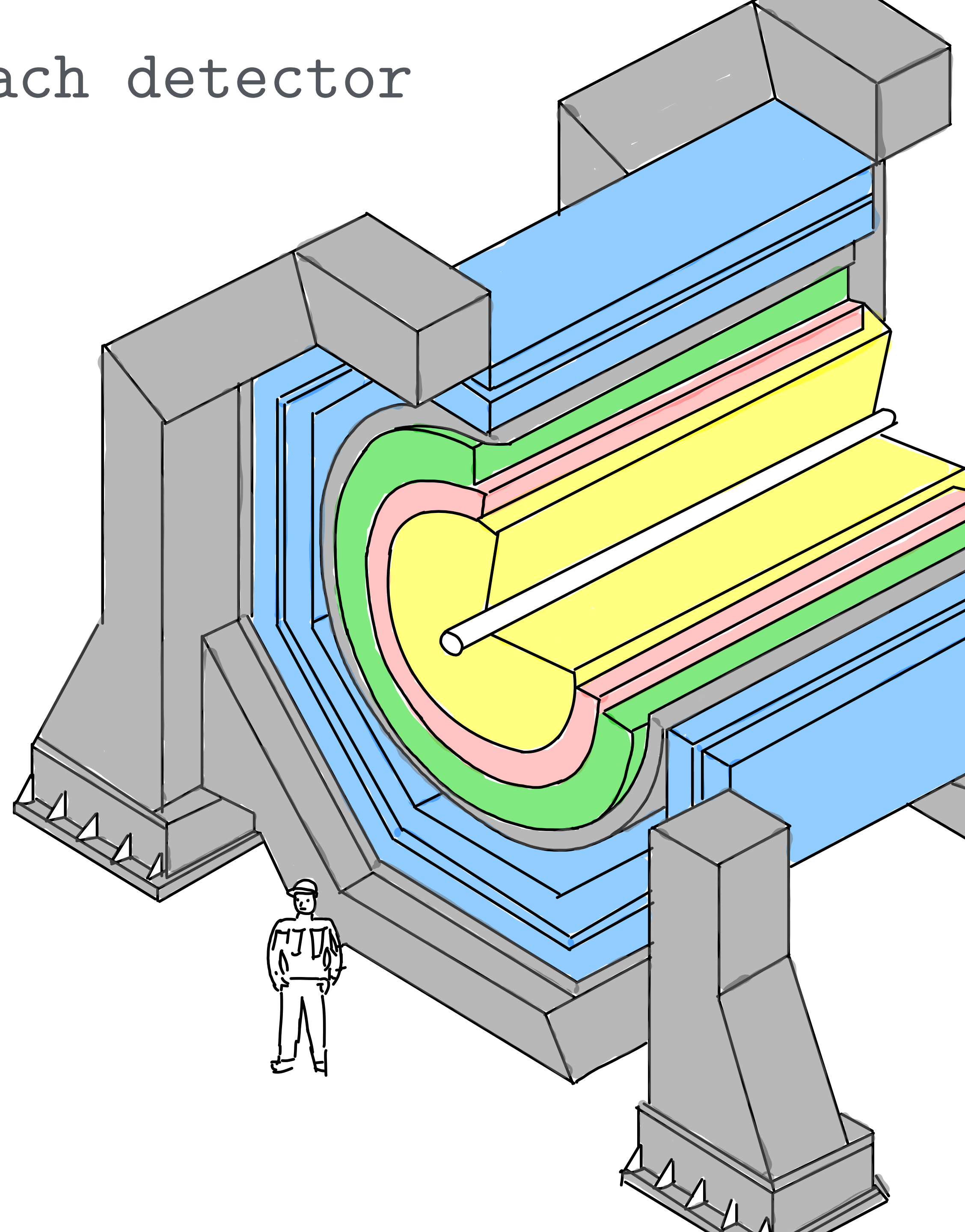


First: Associate hits within each detector



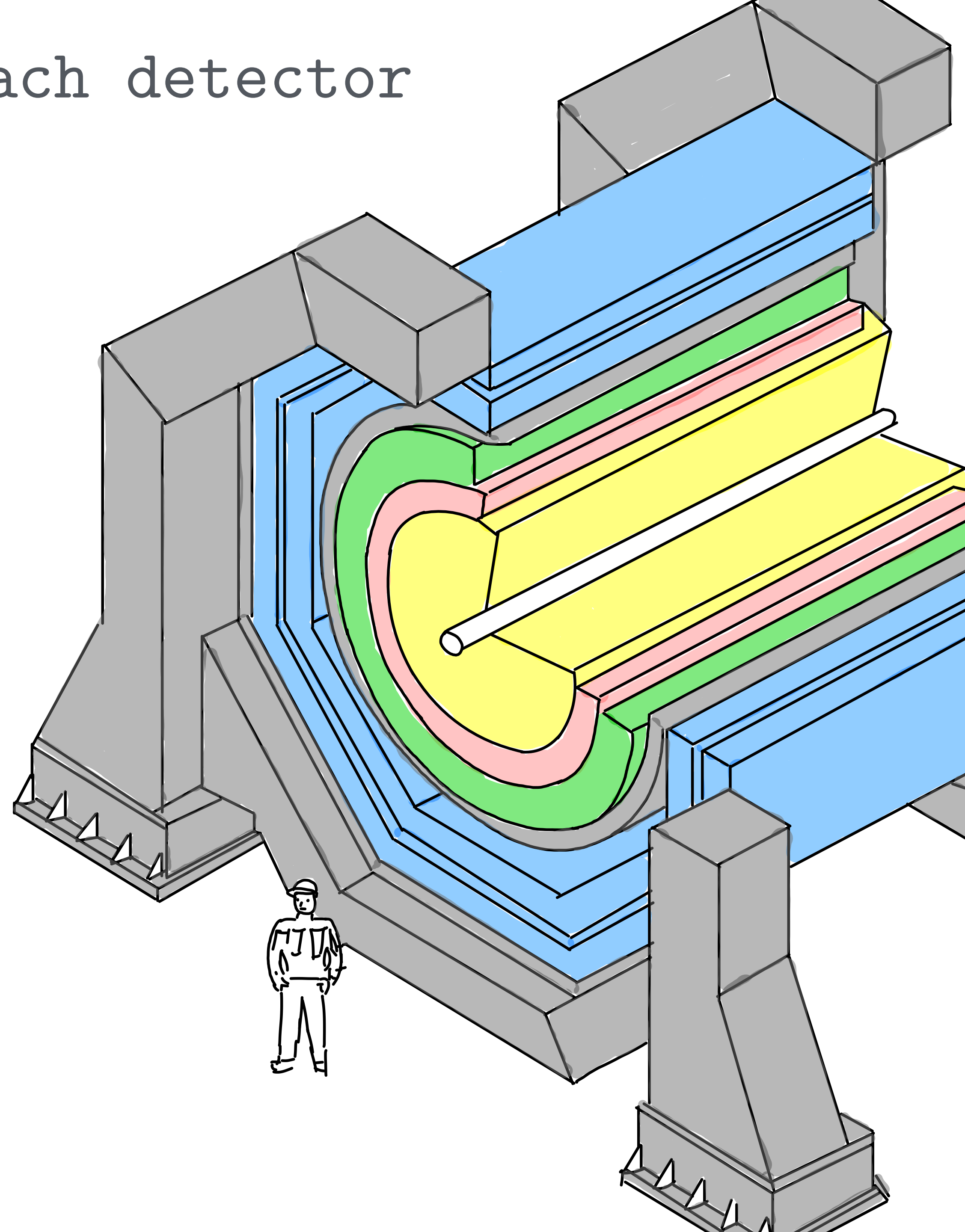
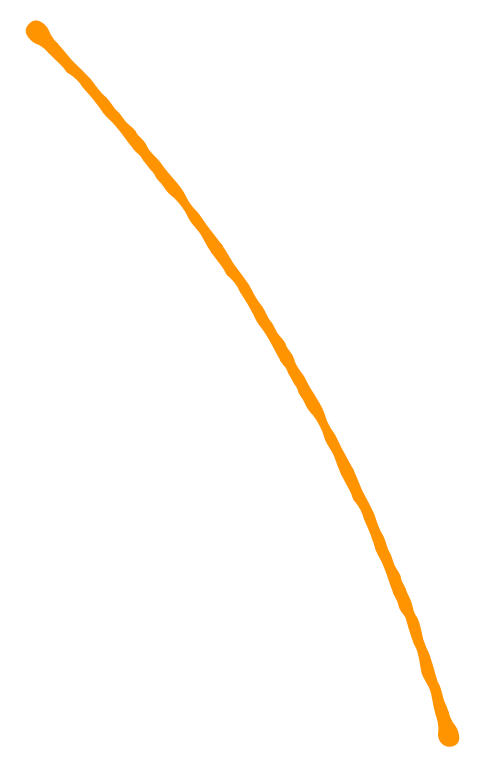
First: Associate hits within each detector

Tracks



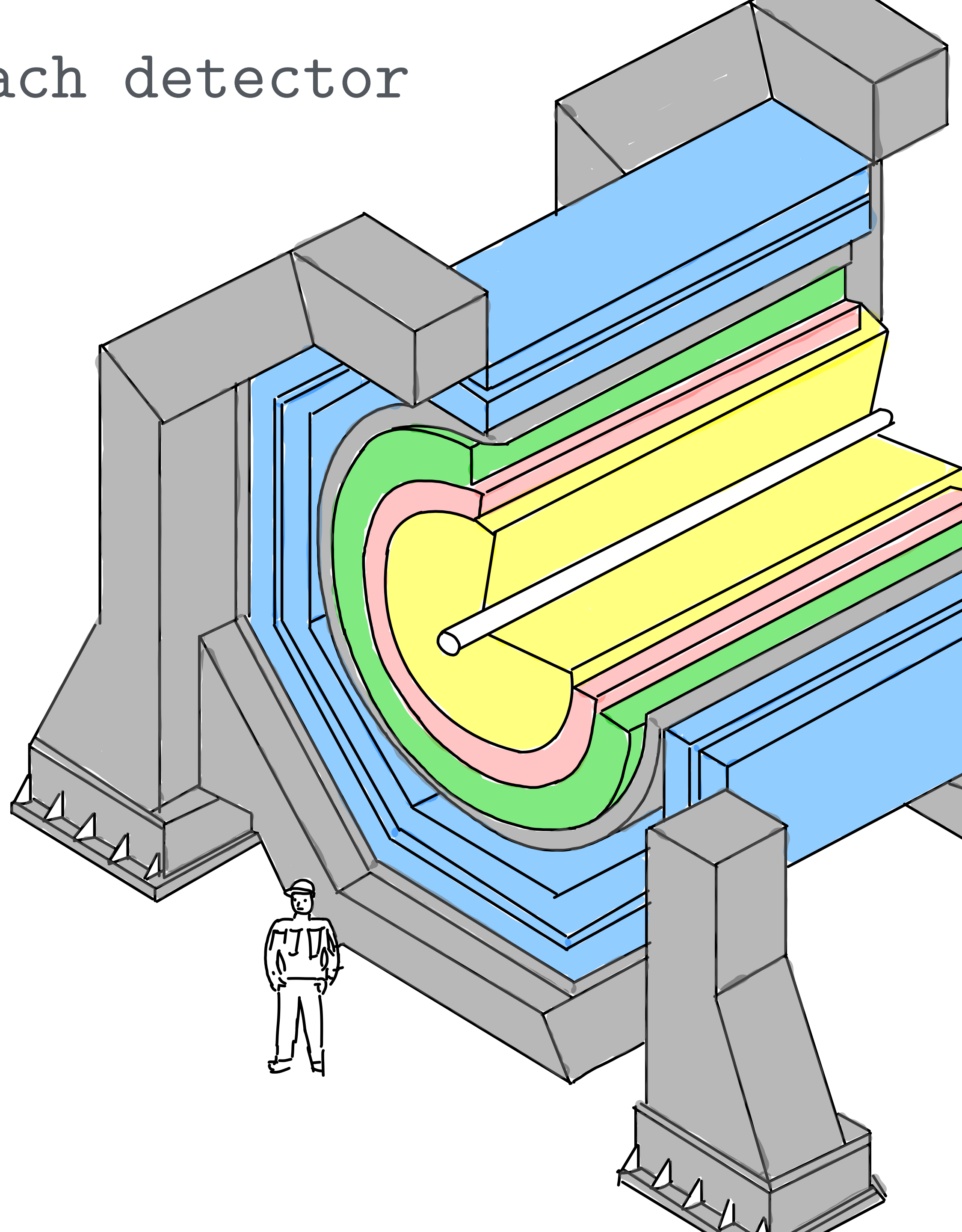
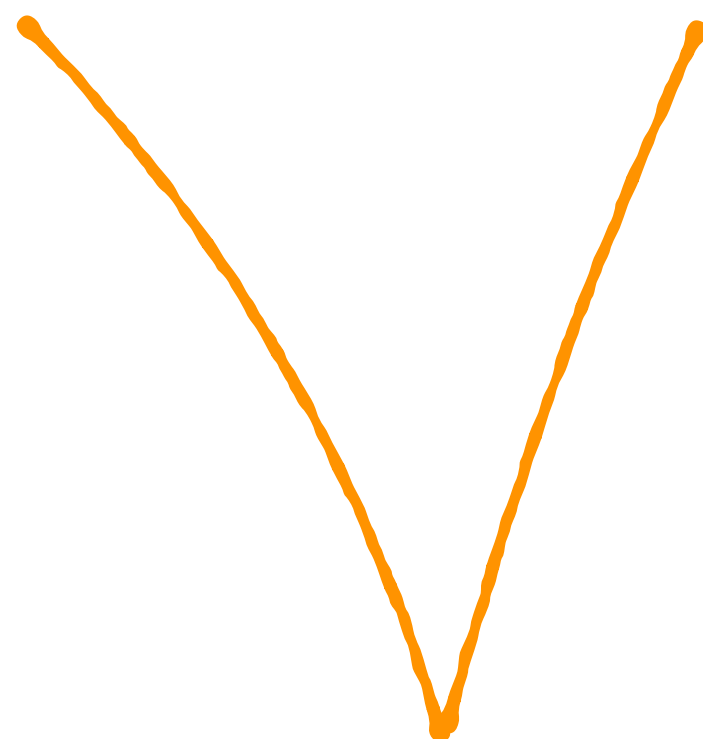
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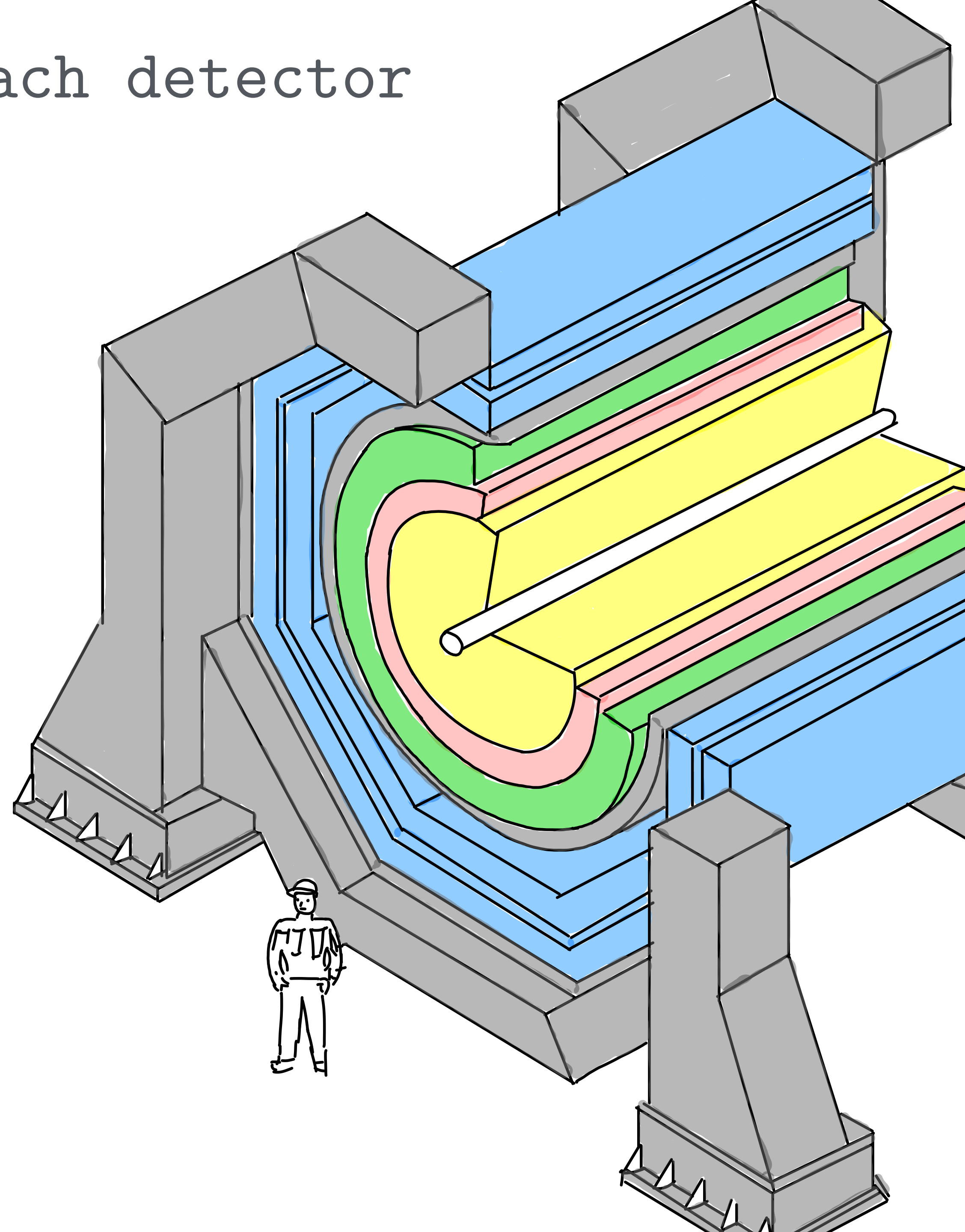
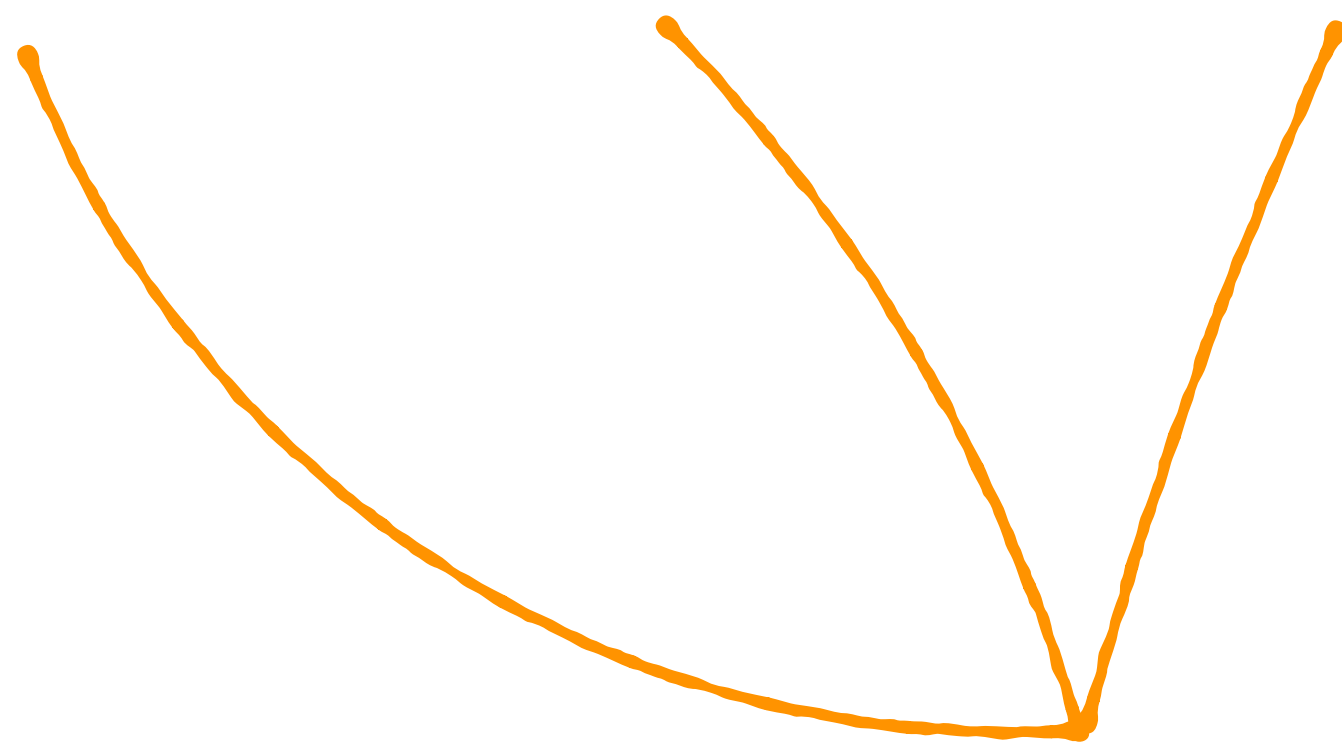
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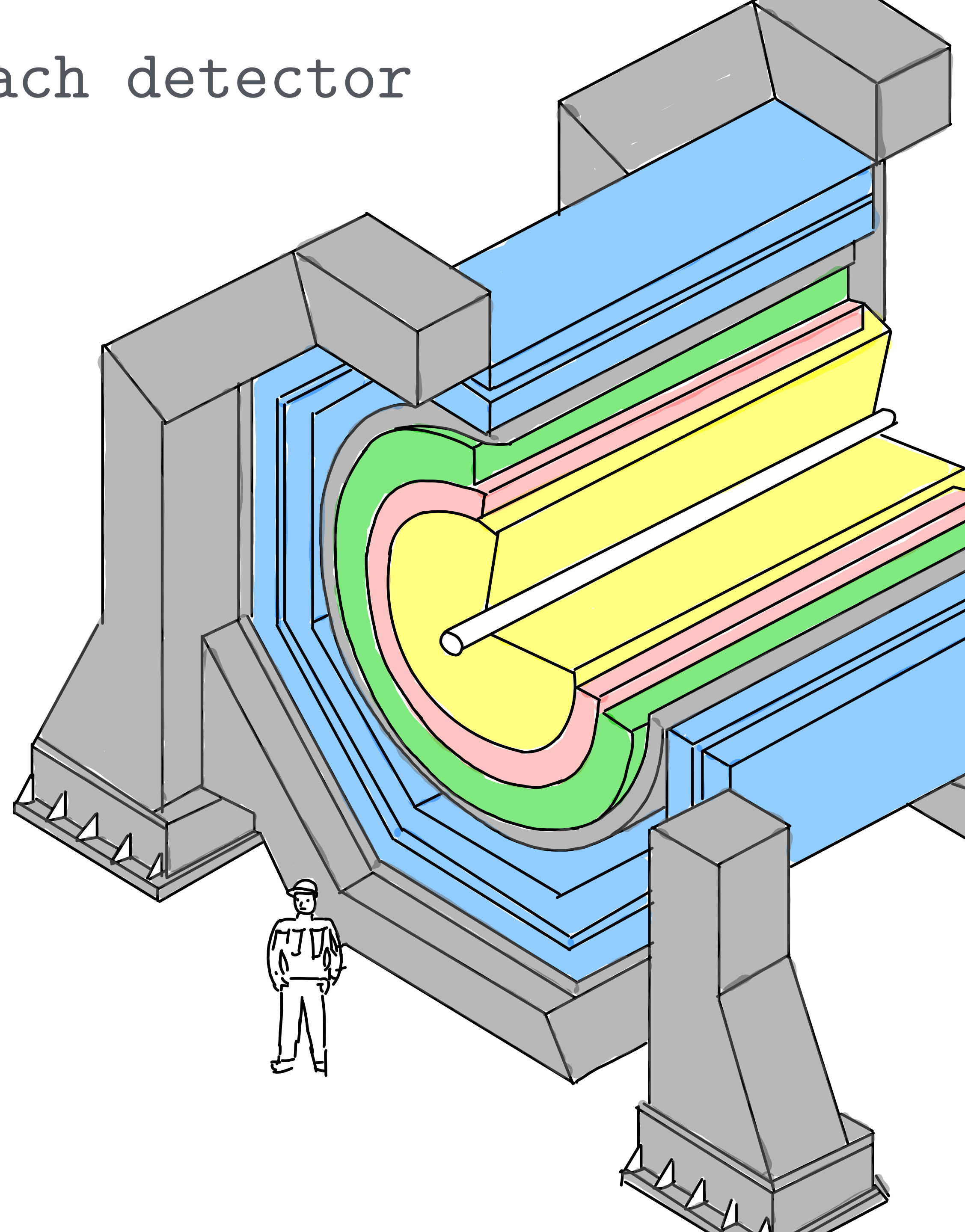
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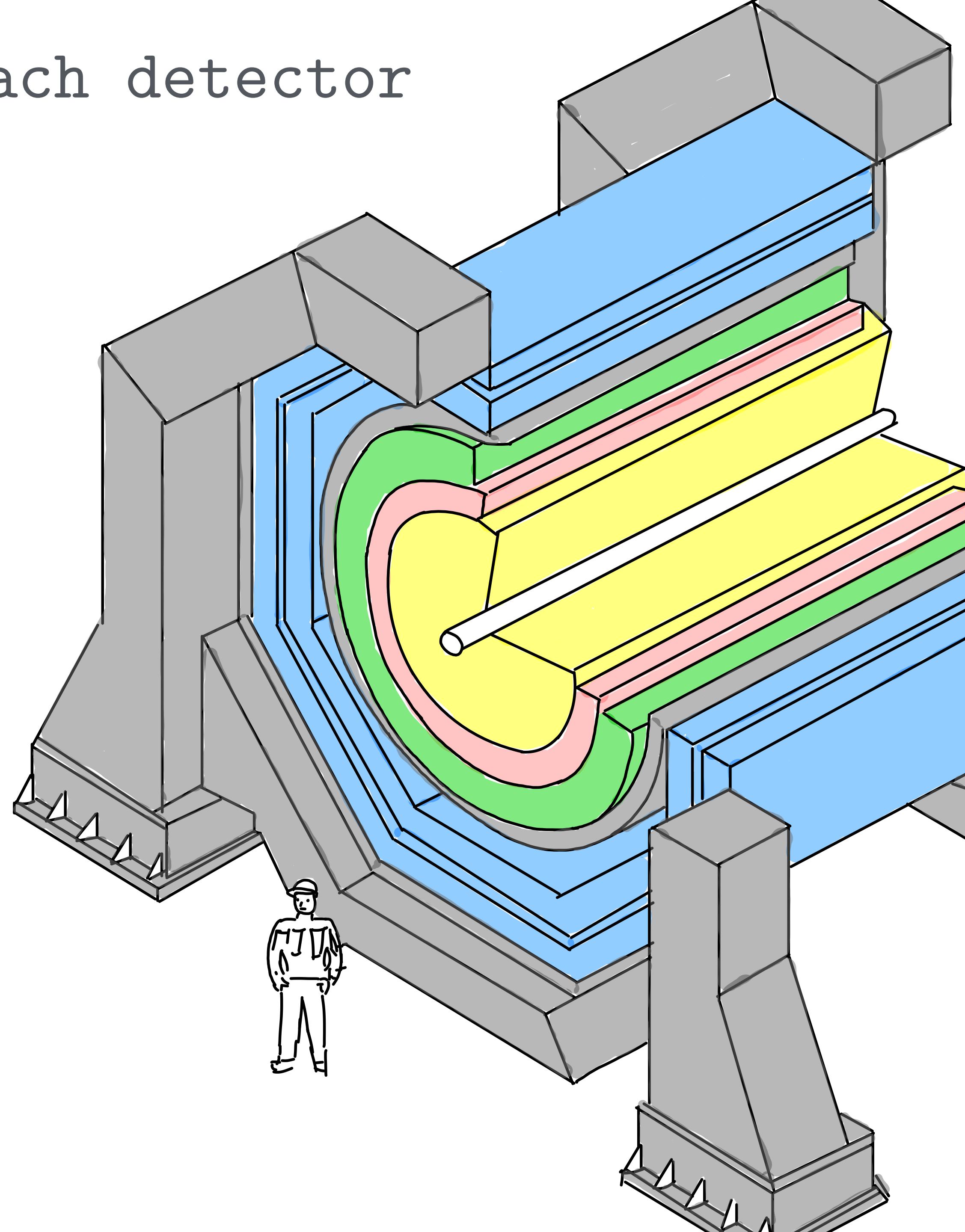
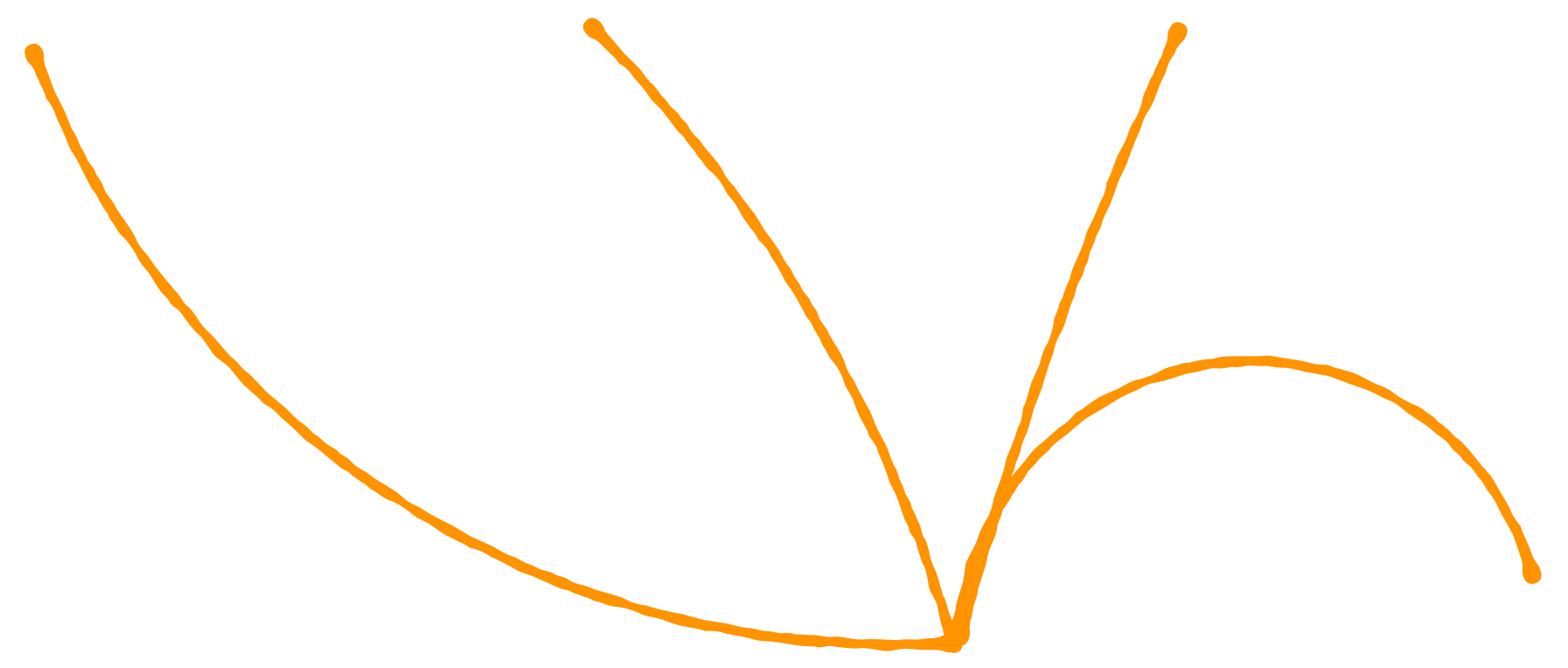
Tracks



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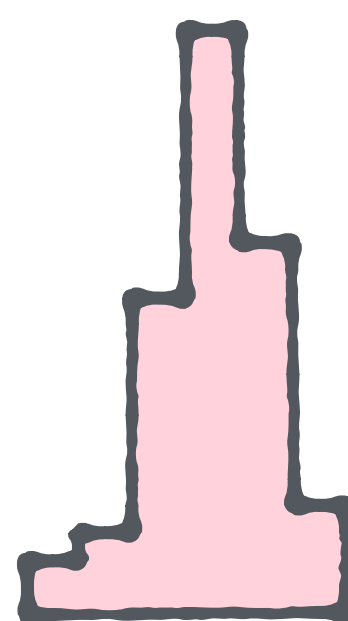
ECAL
Clusters

Tracks

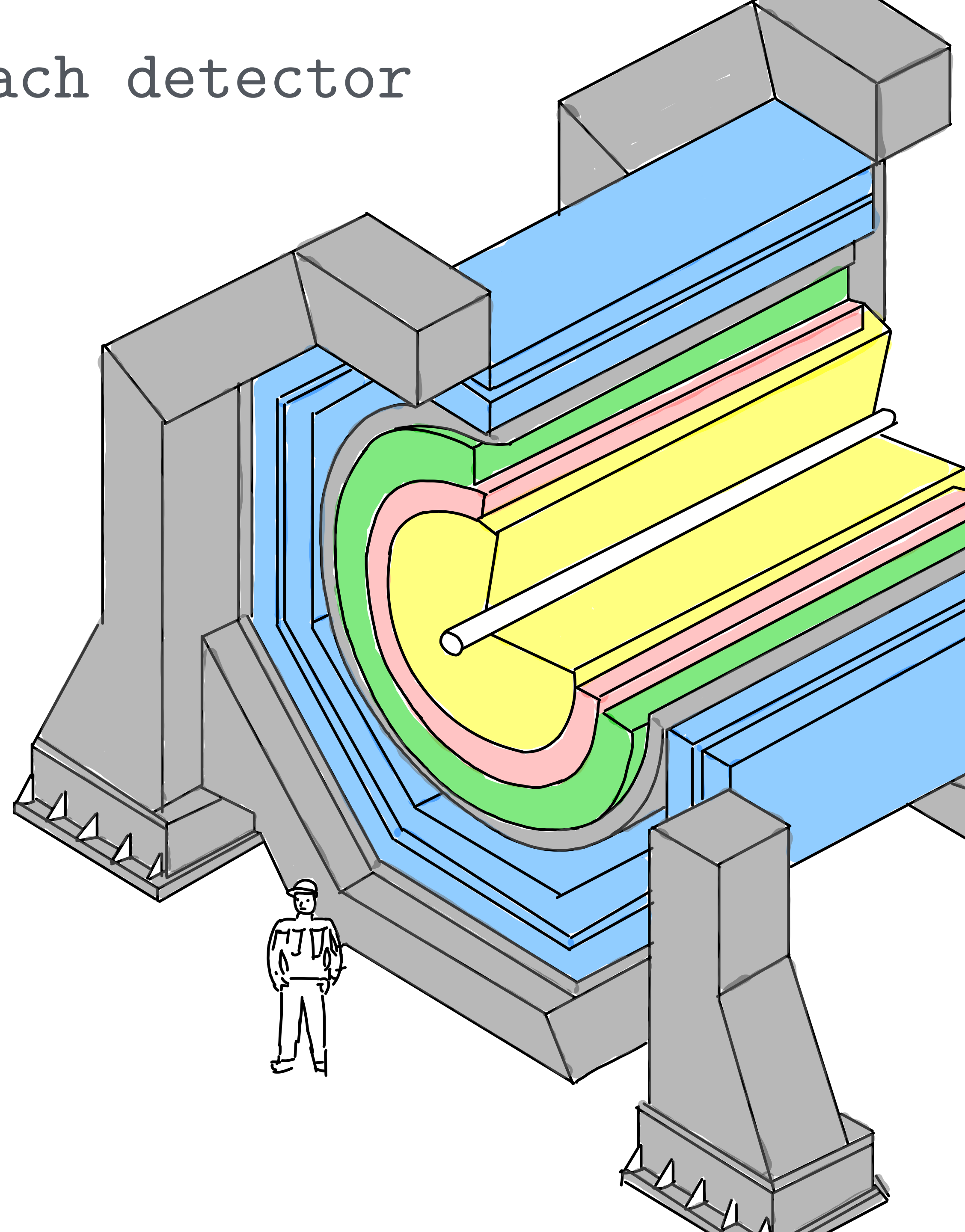


First: Associate hits within each detector

ECAL Clusters

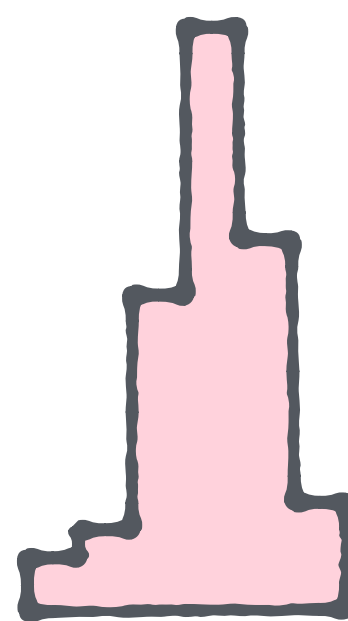
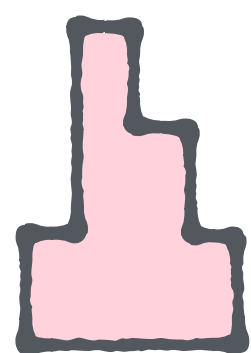


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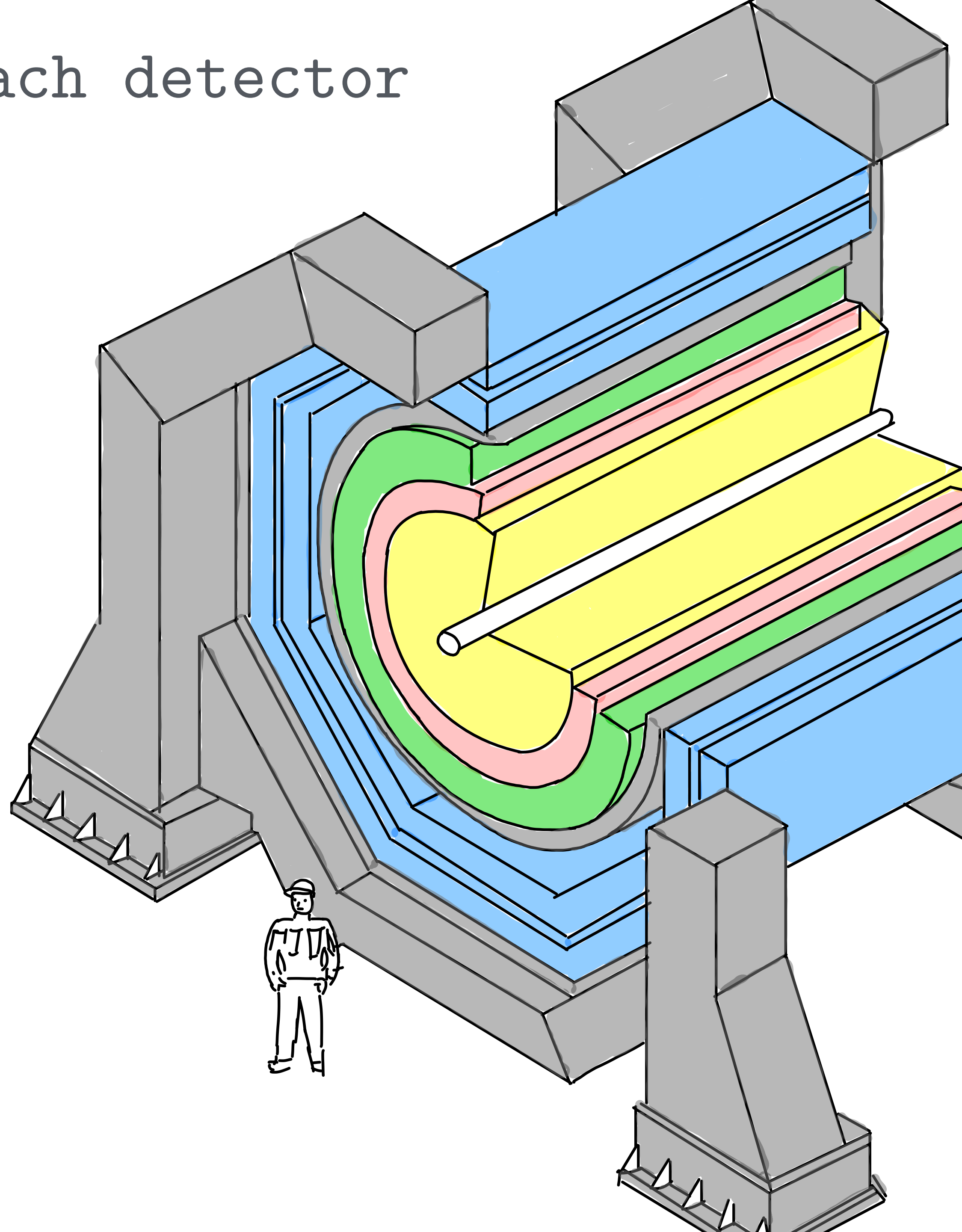


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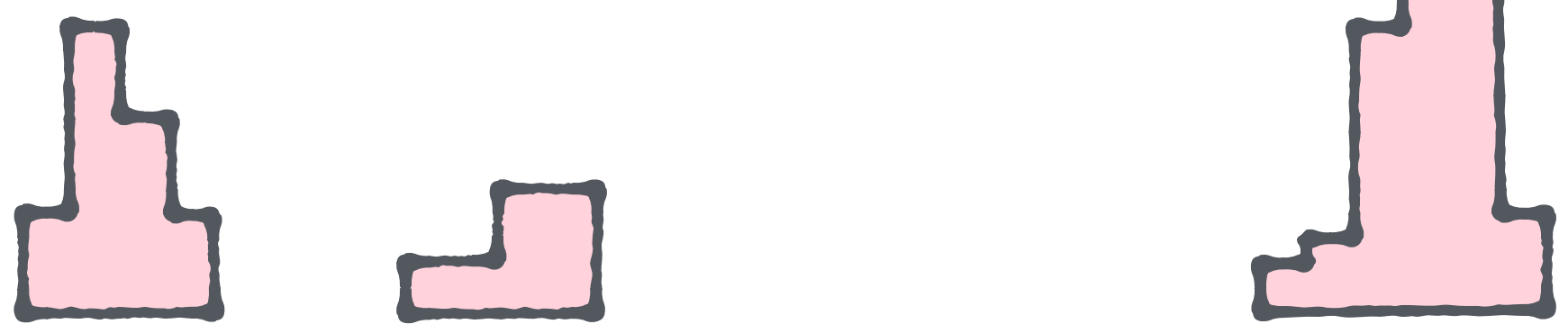


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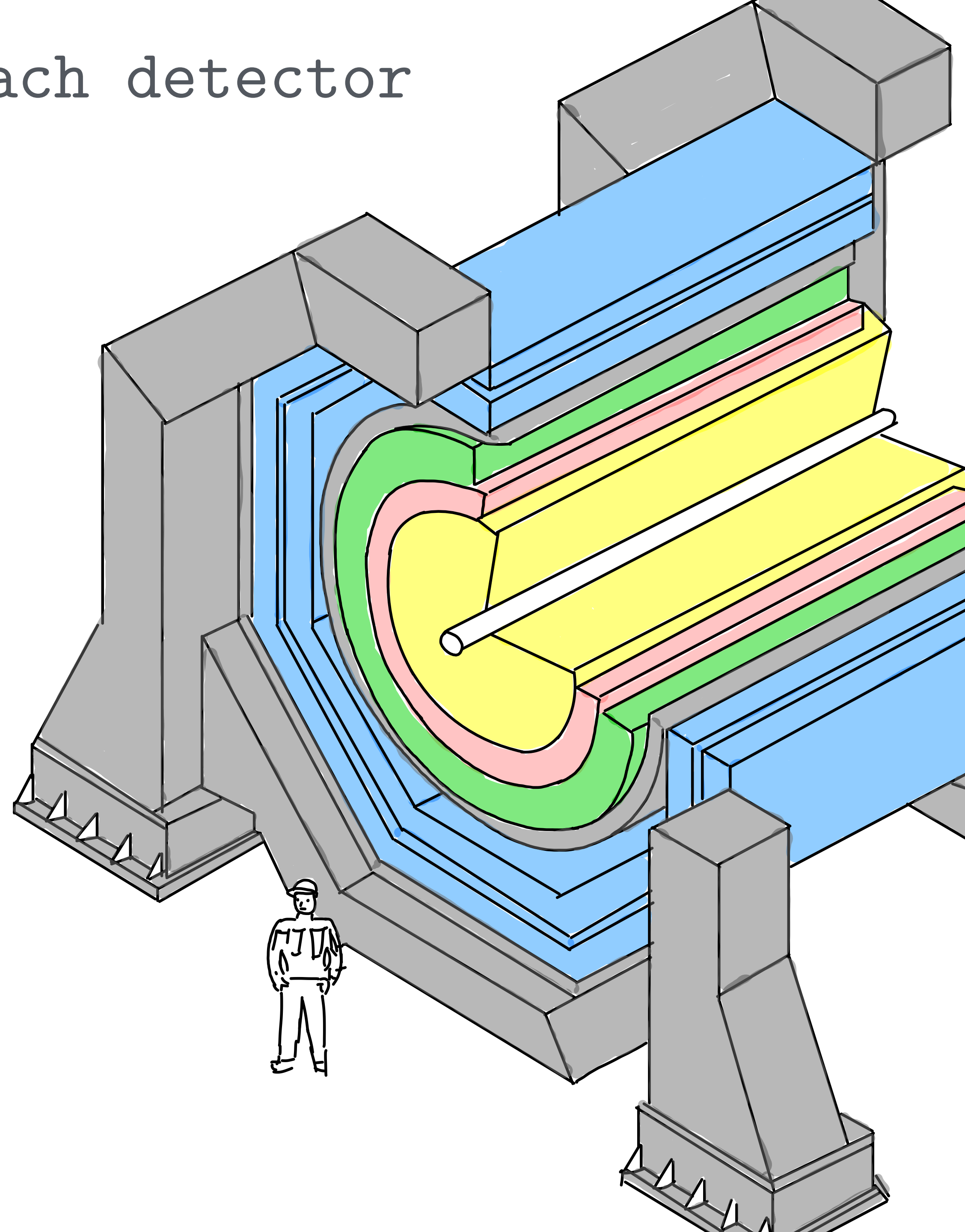


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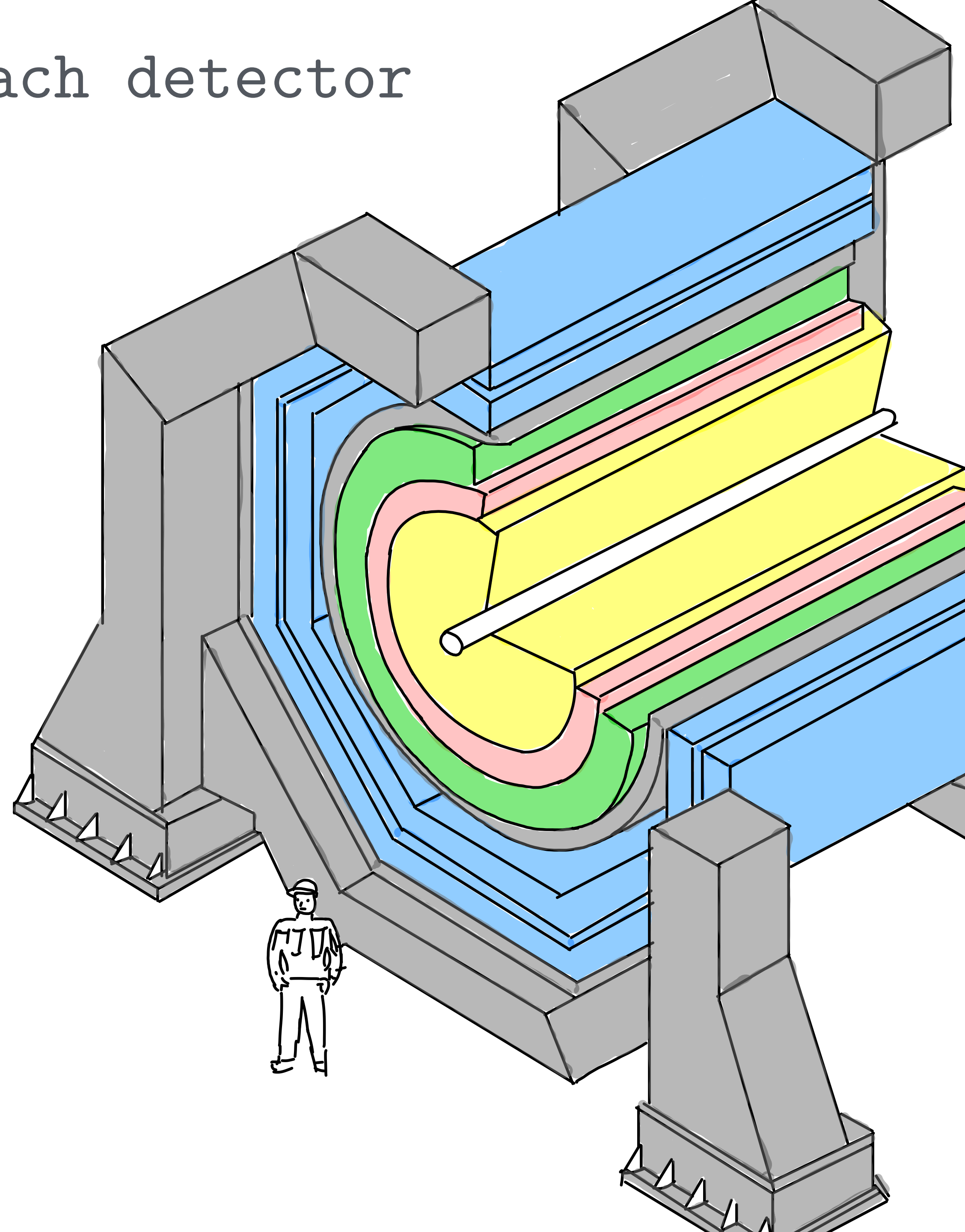
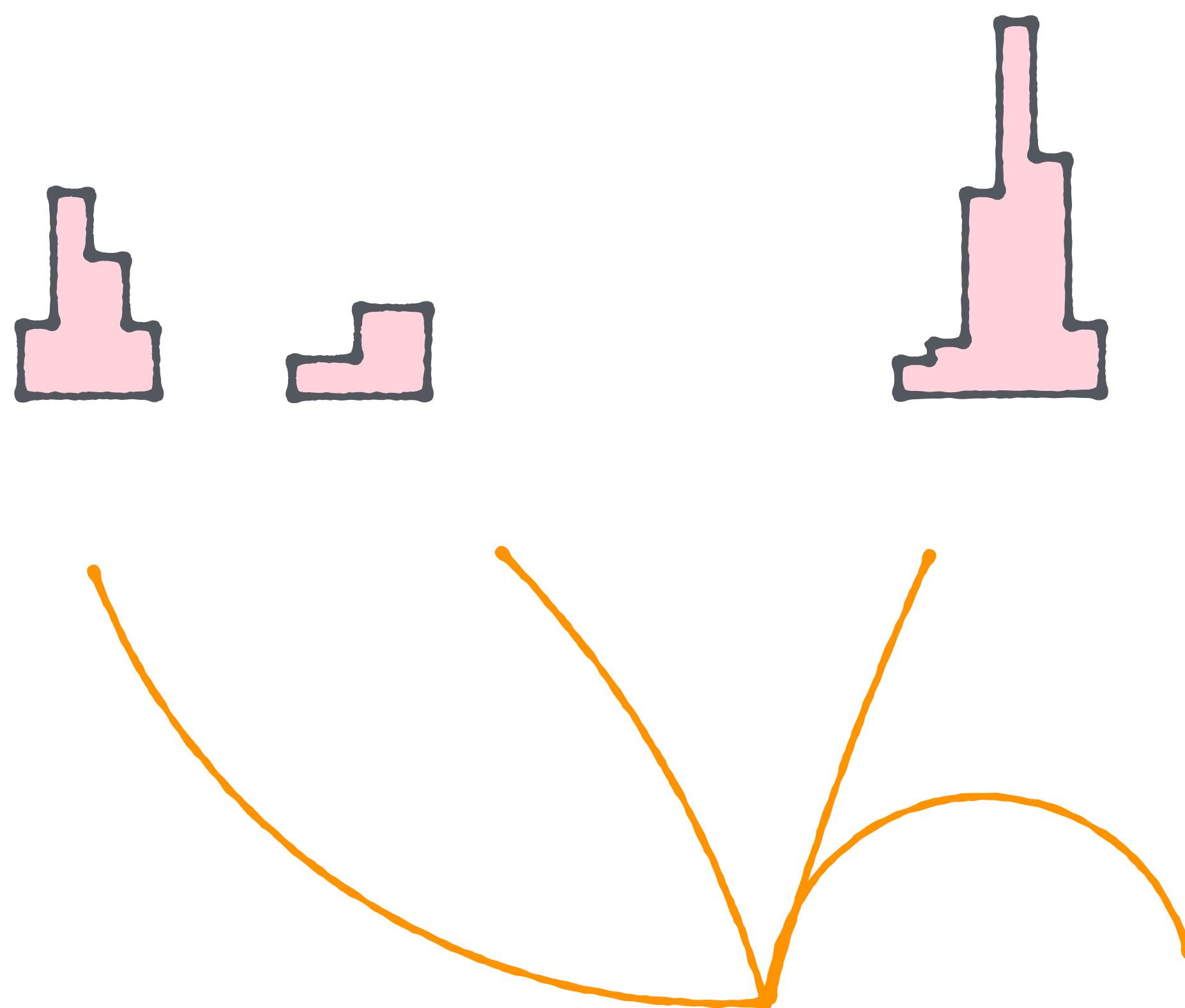


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HCAL Clusters

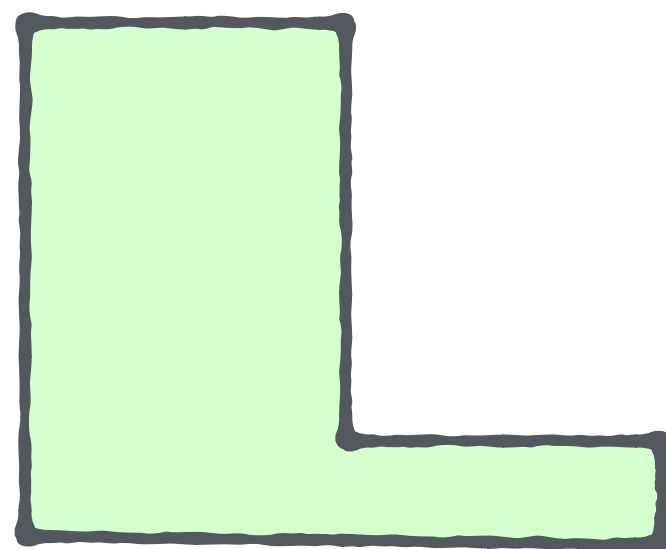
ECAL Clusters

Tracks



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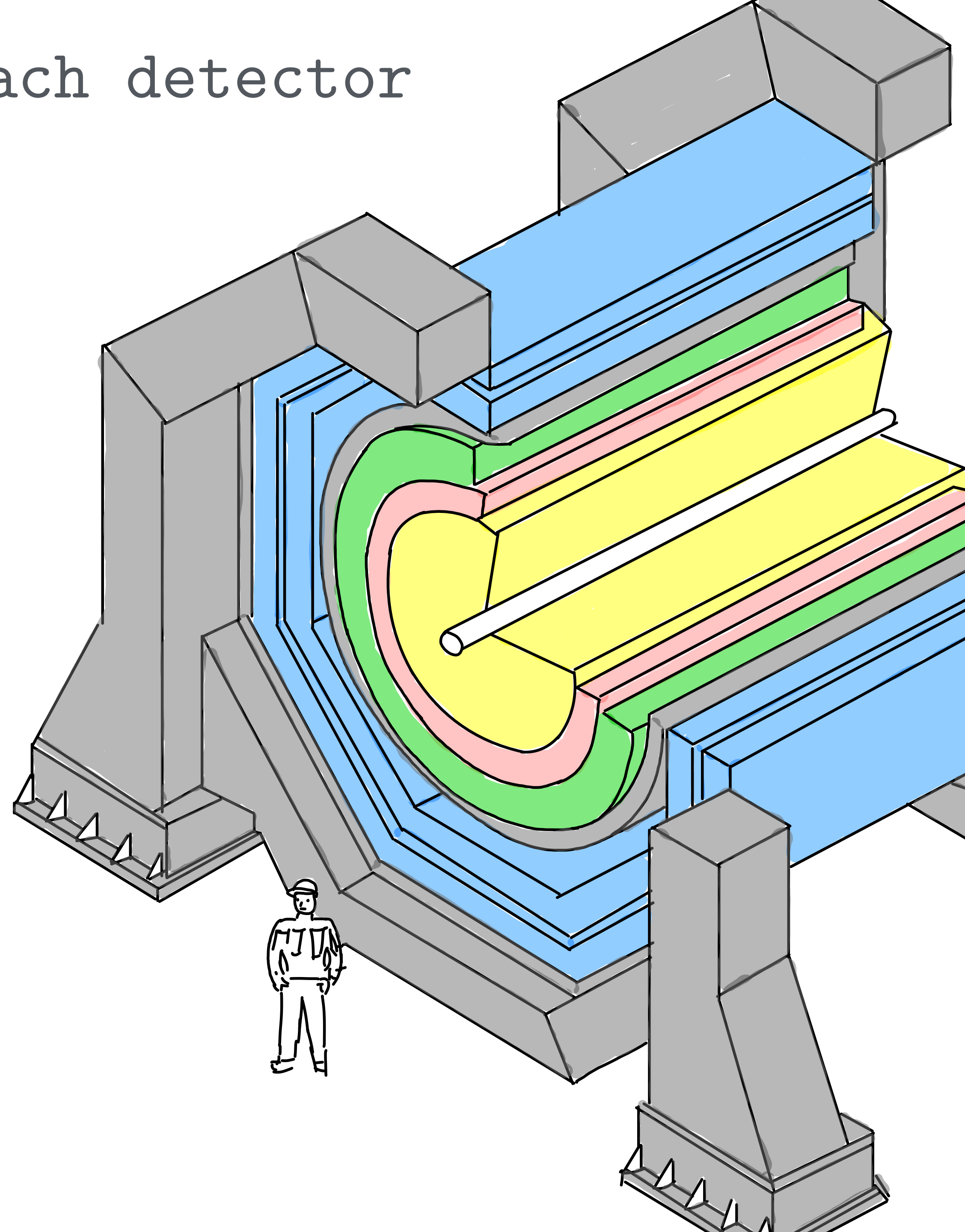
HCAL Clusters



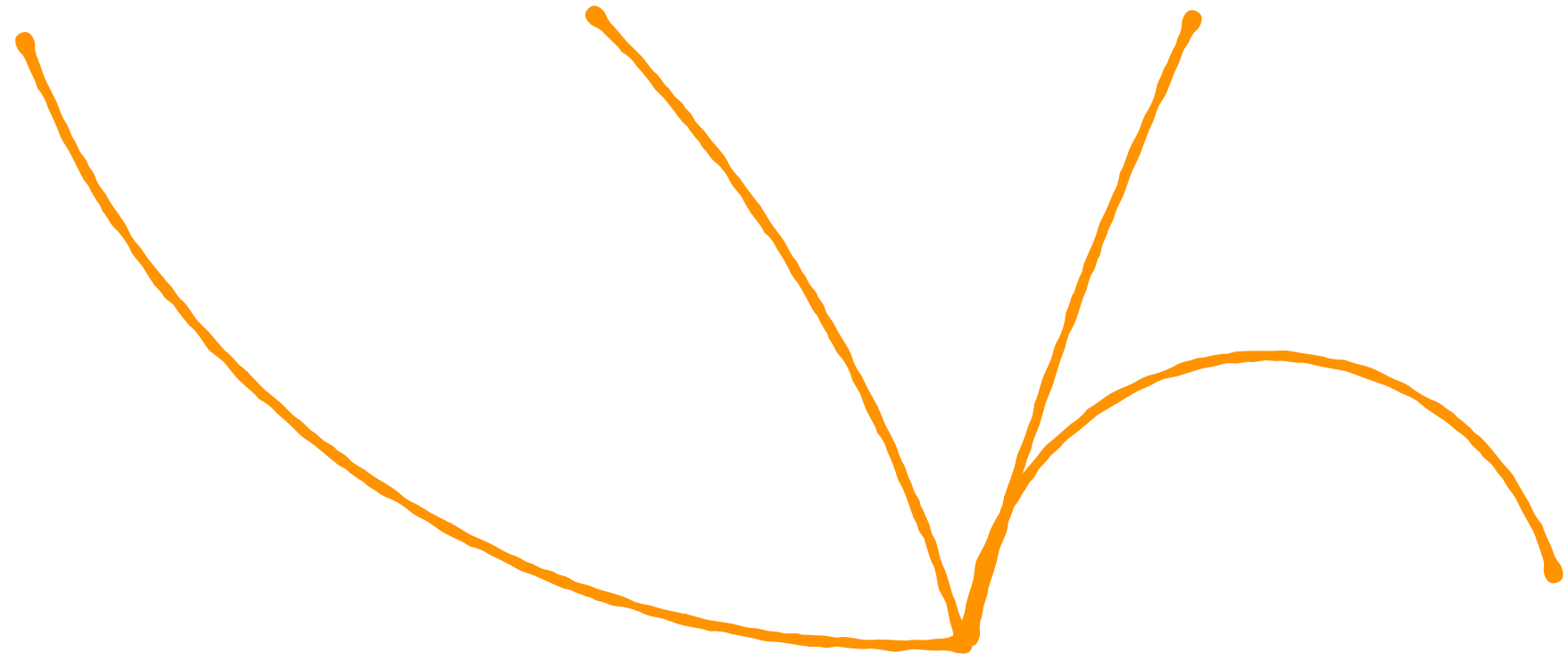
ECAL Clusters



Tracks

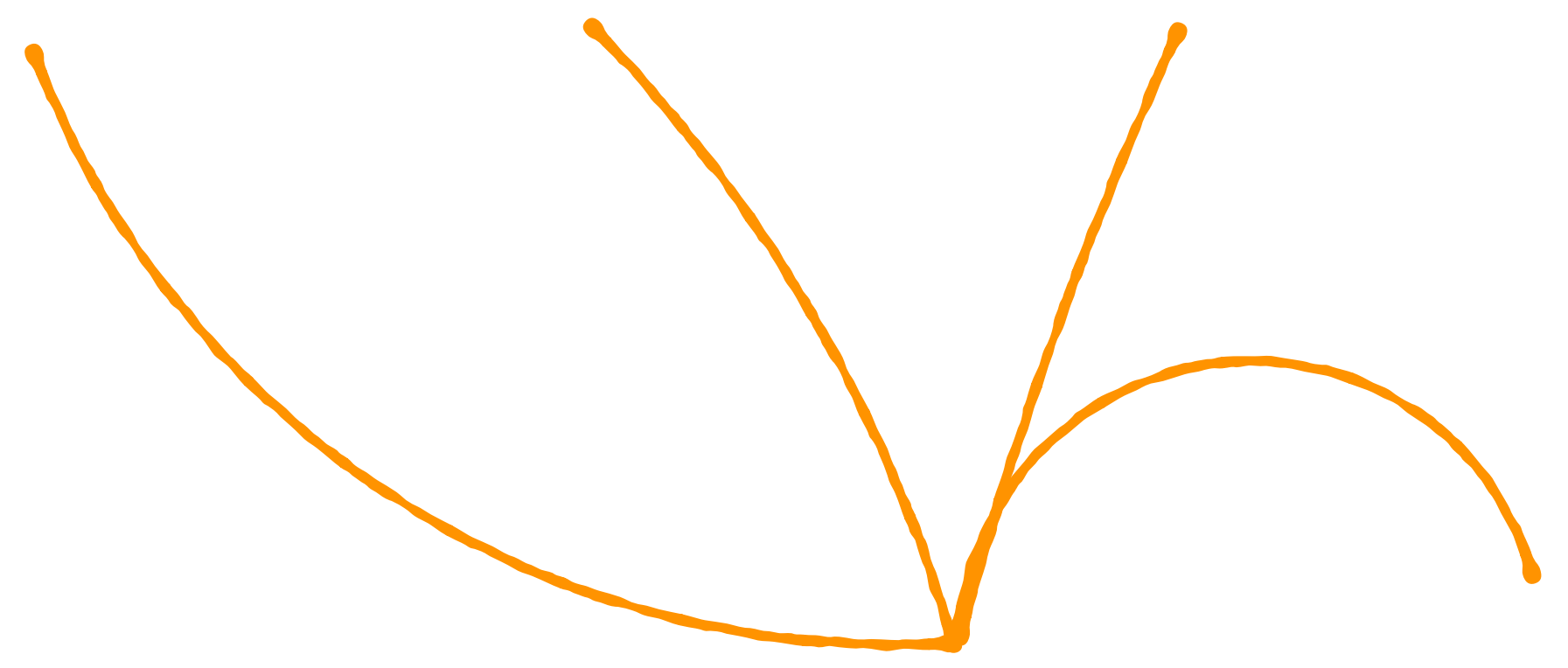


Tracks



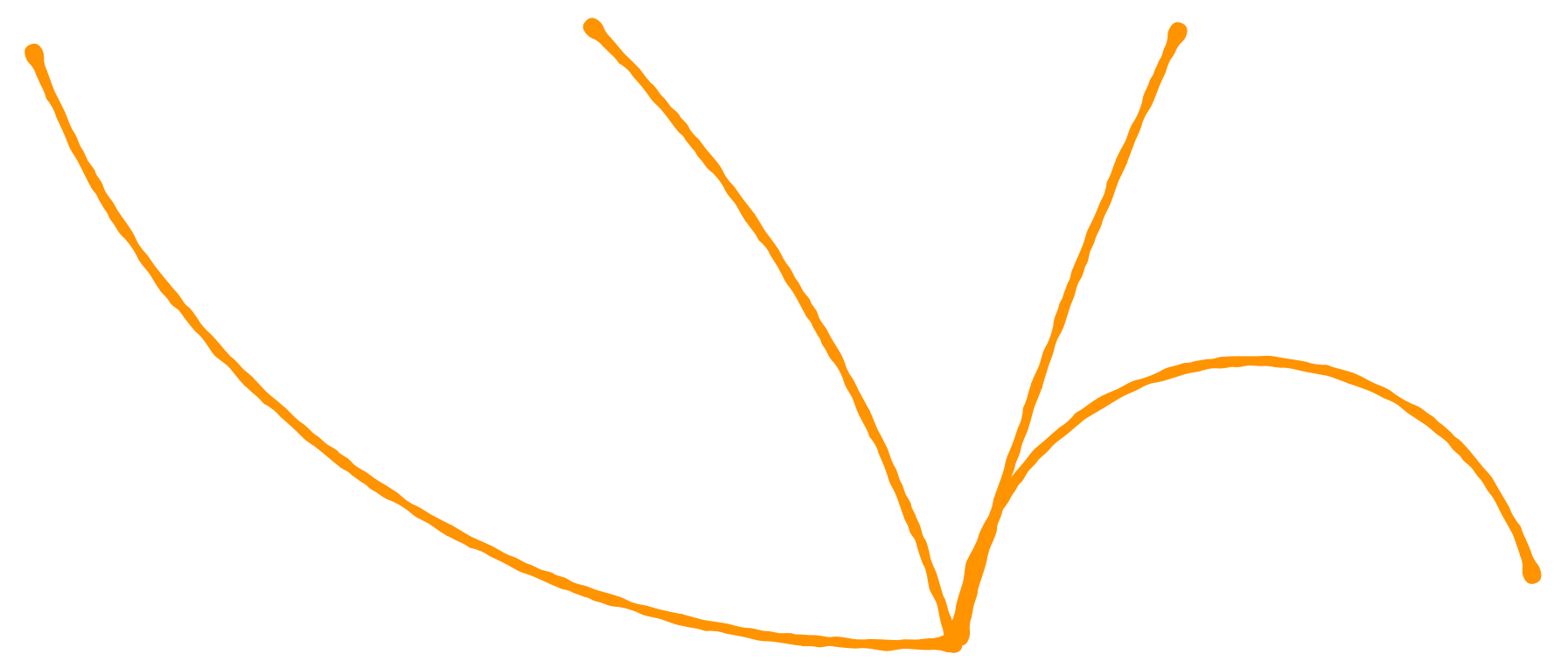
Track finding & reconstruction: Kalman Filter

Tracks



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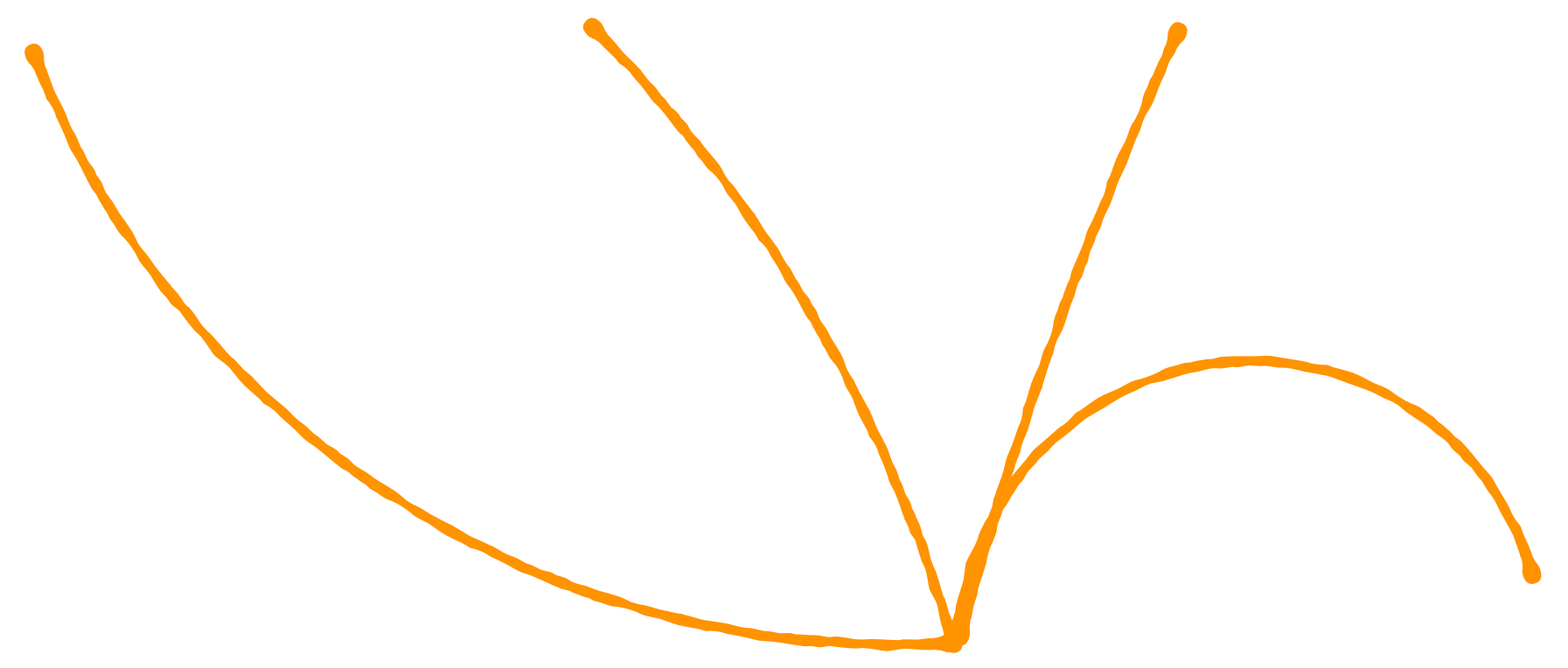
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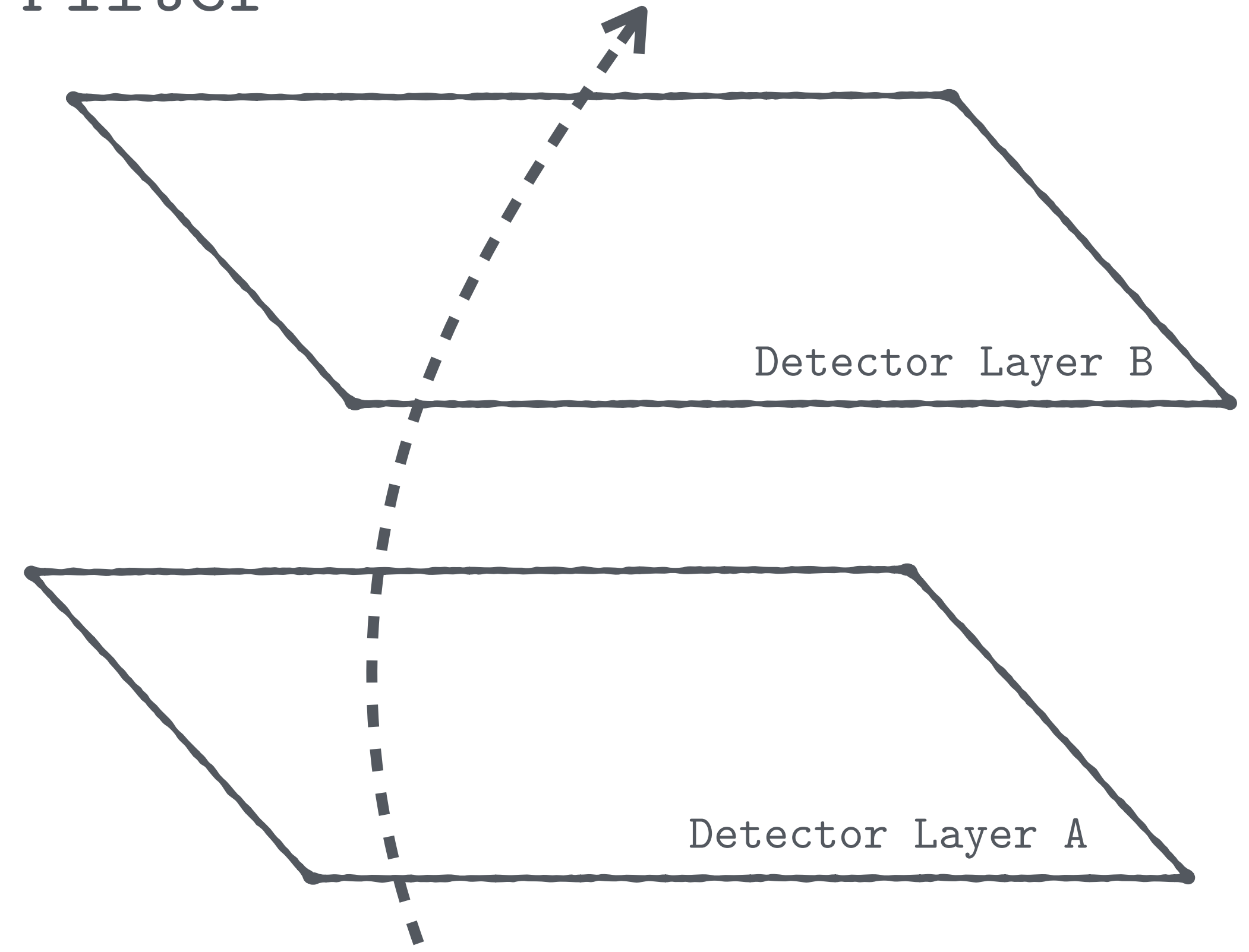
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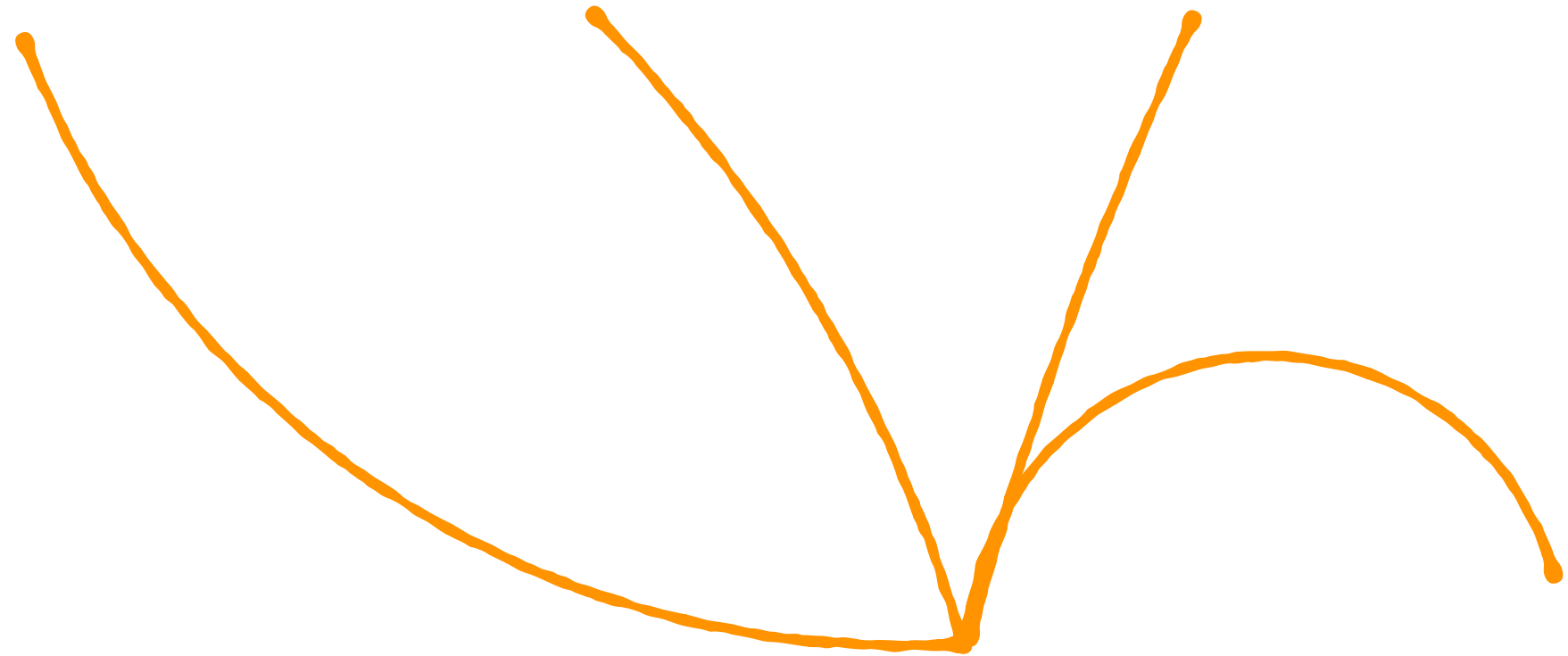
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Track finding & reconstruction: Kalman Filter



Tracks



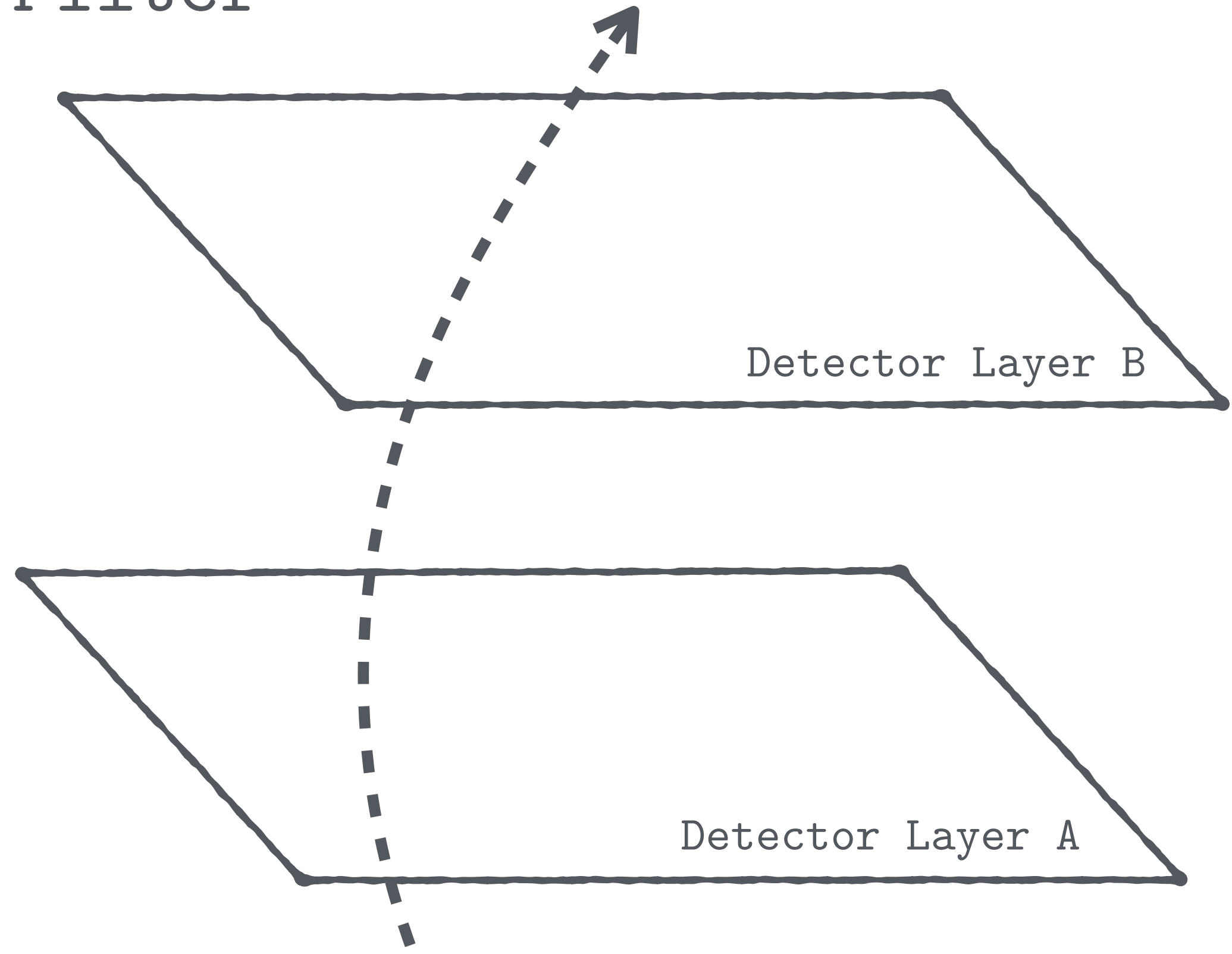
Track finding & reconstruction: Kalman Filter

Measurement and Covariance

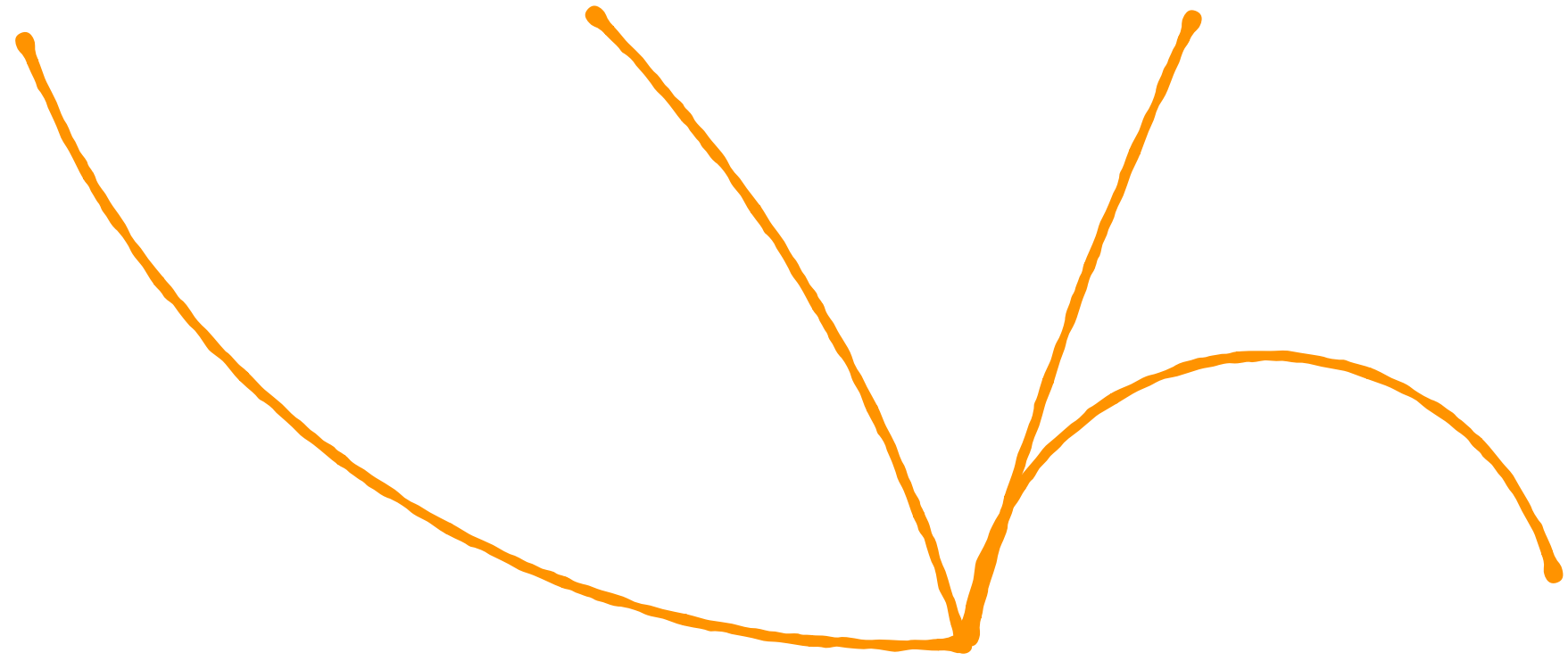
- Measurement vector

$$\vec{m} = \begin{pmatrix} x \\ y \end{pmatrix}$$

- And its covariance matrix \mathbb{V}



Tracks



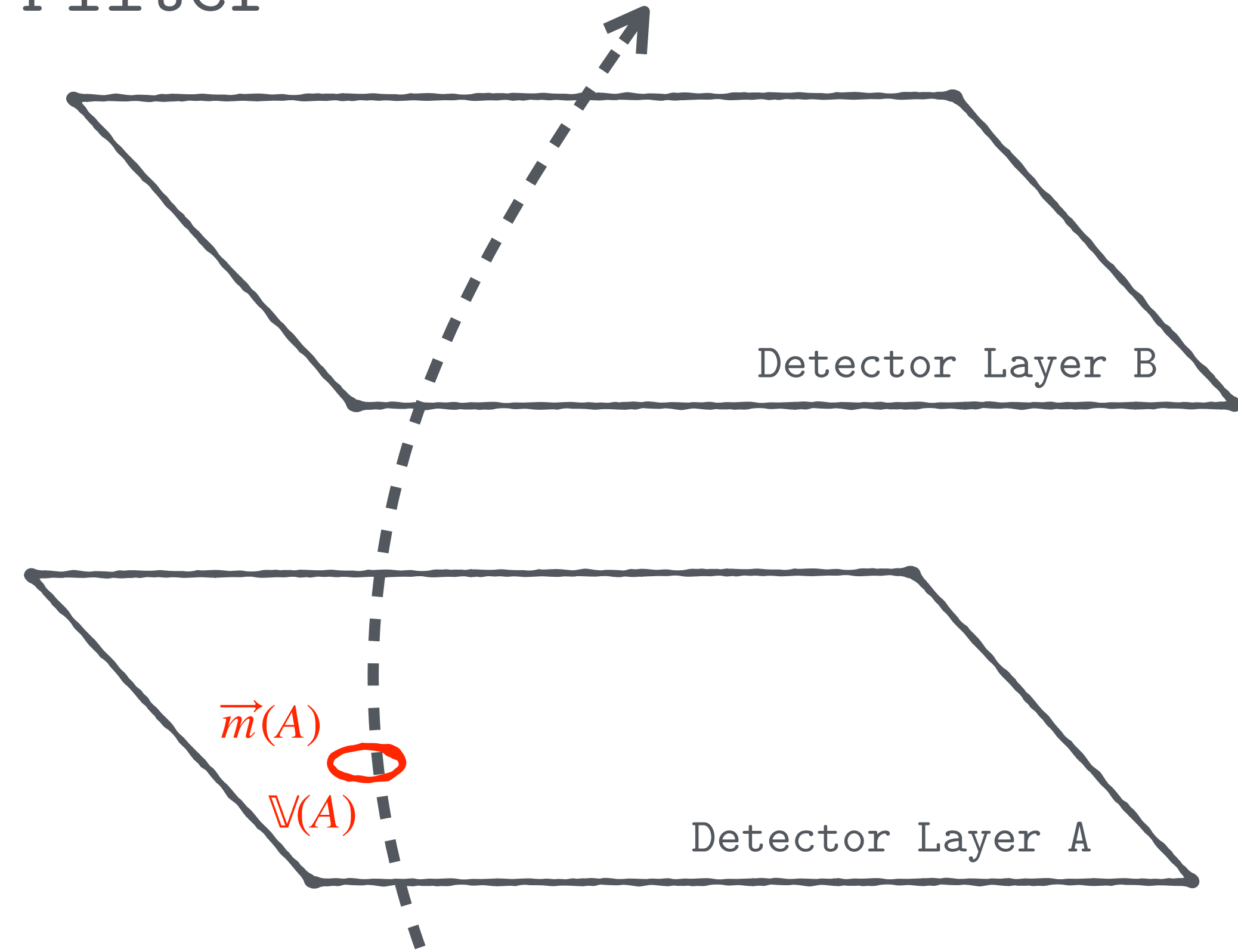
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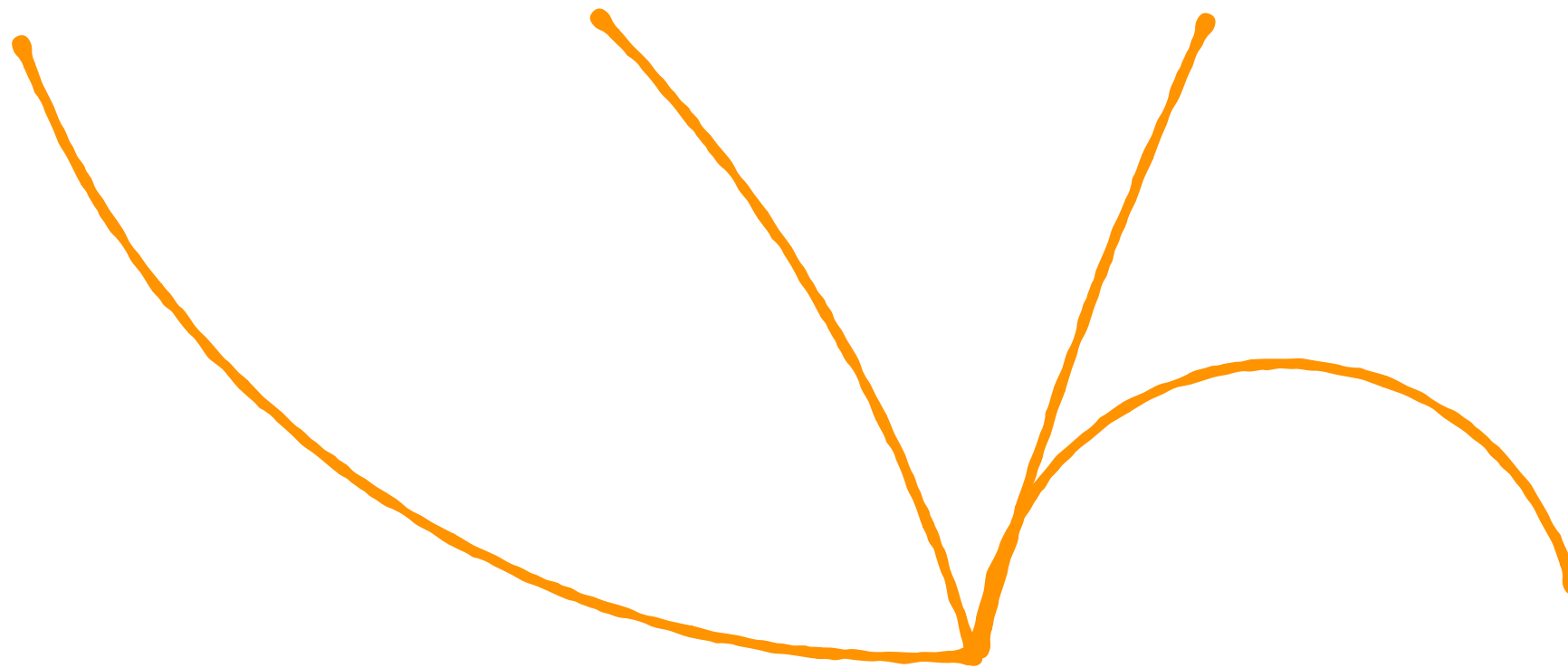
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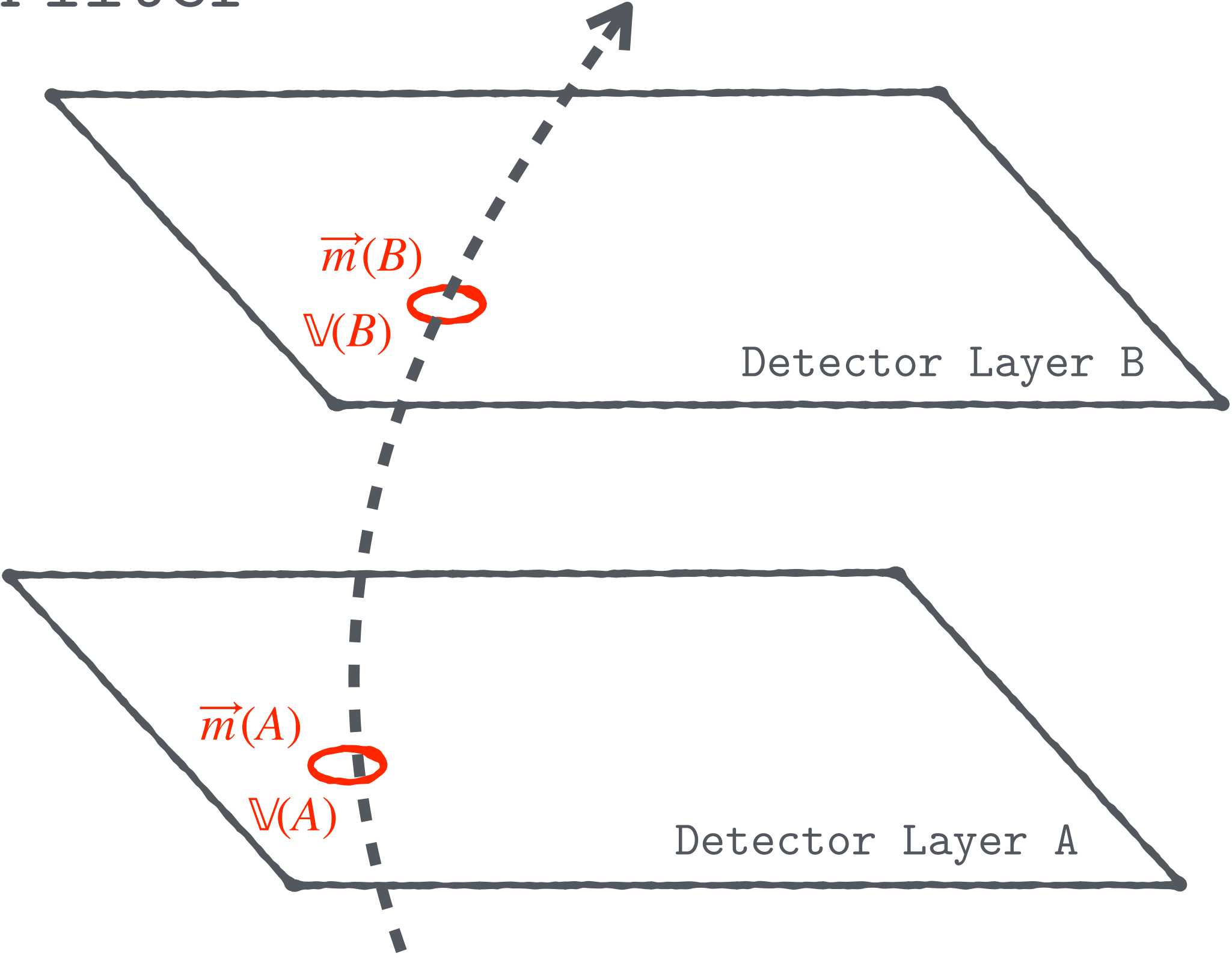
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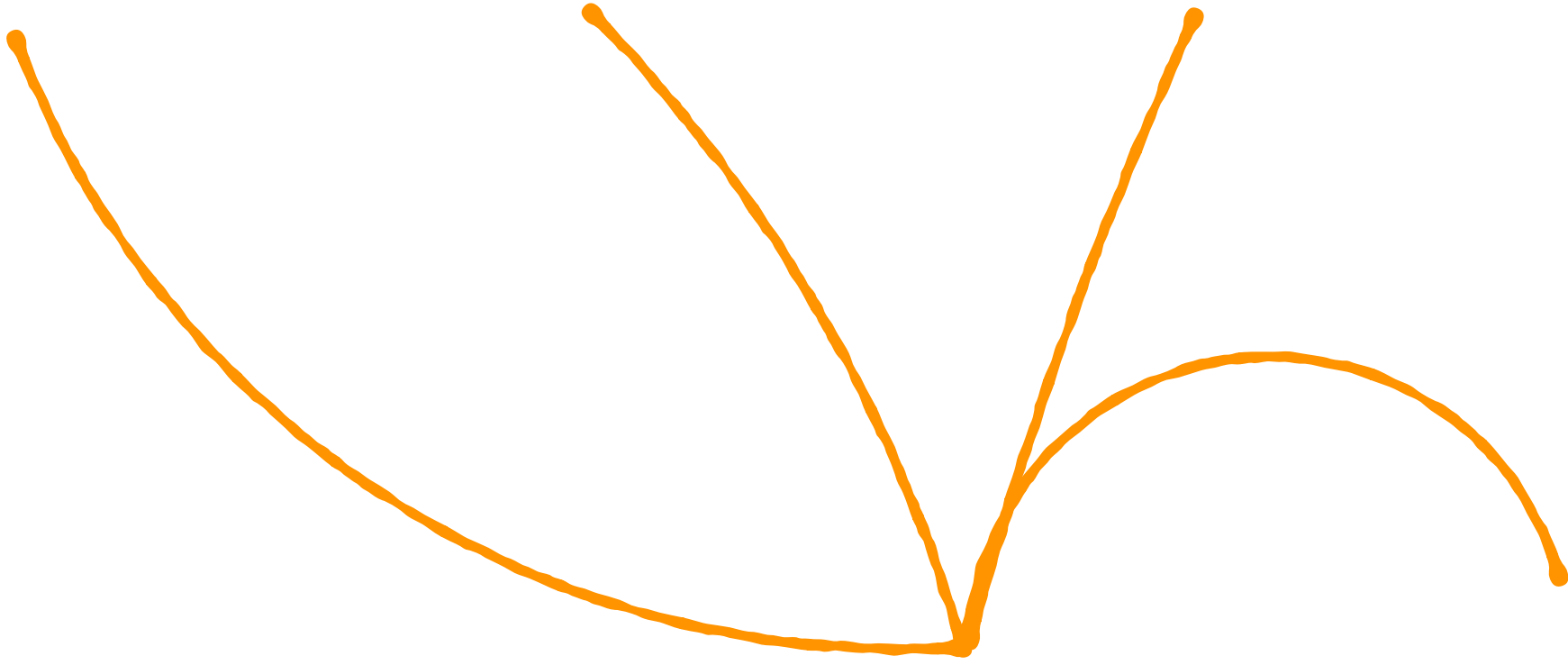
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Tracks



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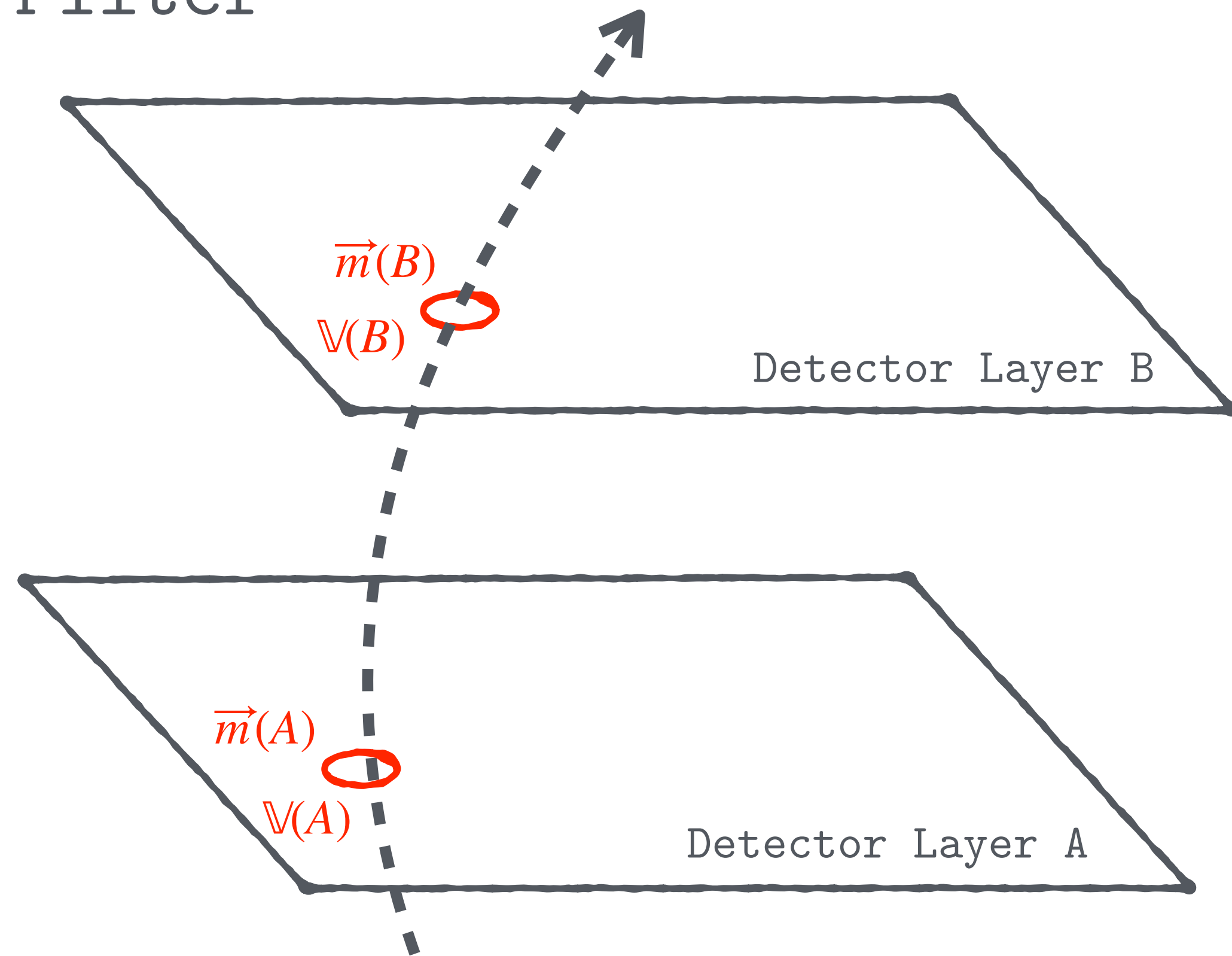
State vector and Covariance

- Many ways to parameterise a track

$$\vec{s} = \begin{pmatrix} q/p \\ dx/dz \\ dy/dz \\ x \\ y \end{pmatrix}$$

- And its covariance matrix \mathbb{S}

Tracks



Track finding & reconstruction: Kalman Filter

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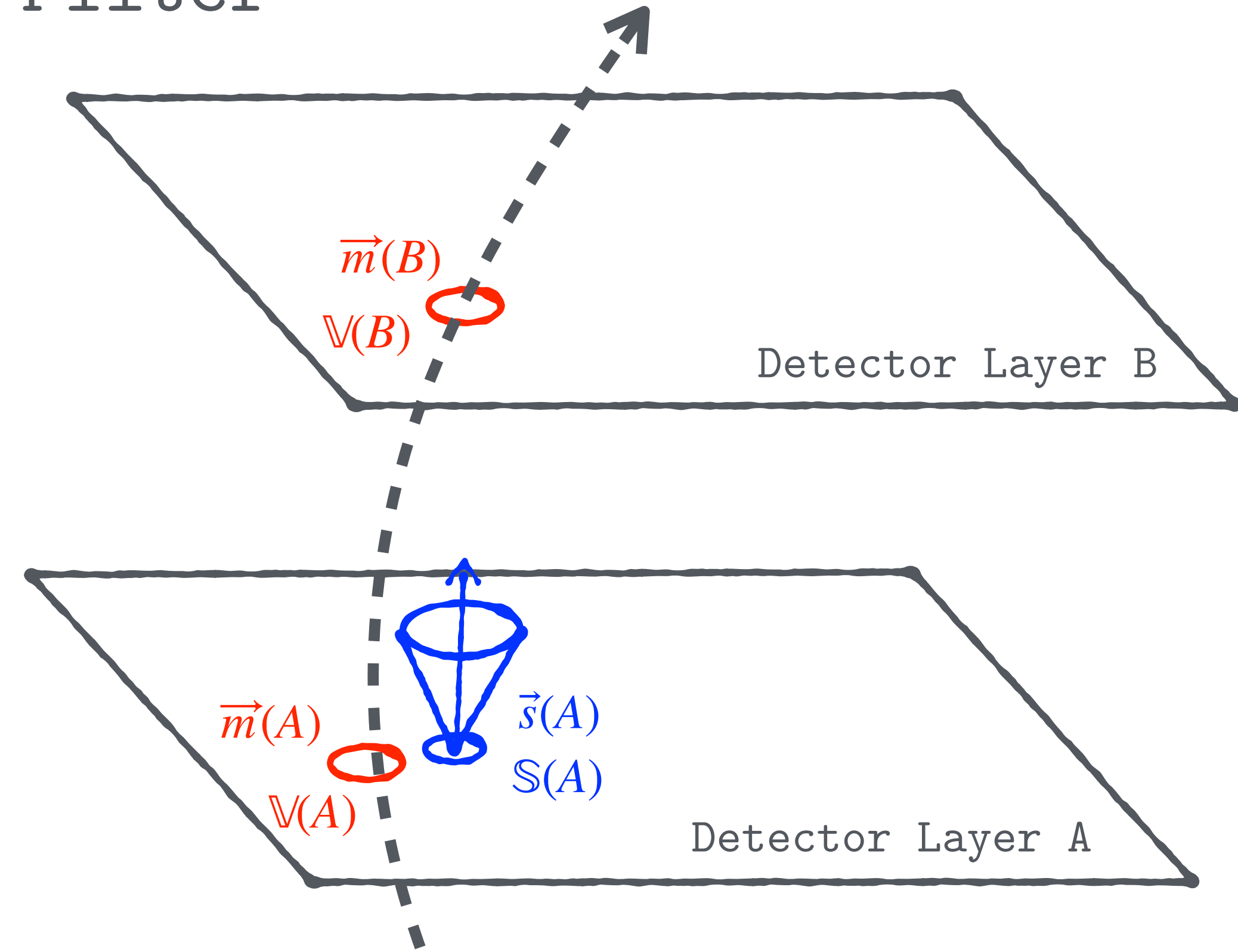
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Track finding & reconstruction: Kalman Filter

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Transform: state to meas

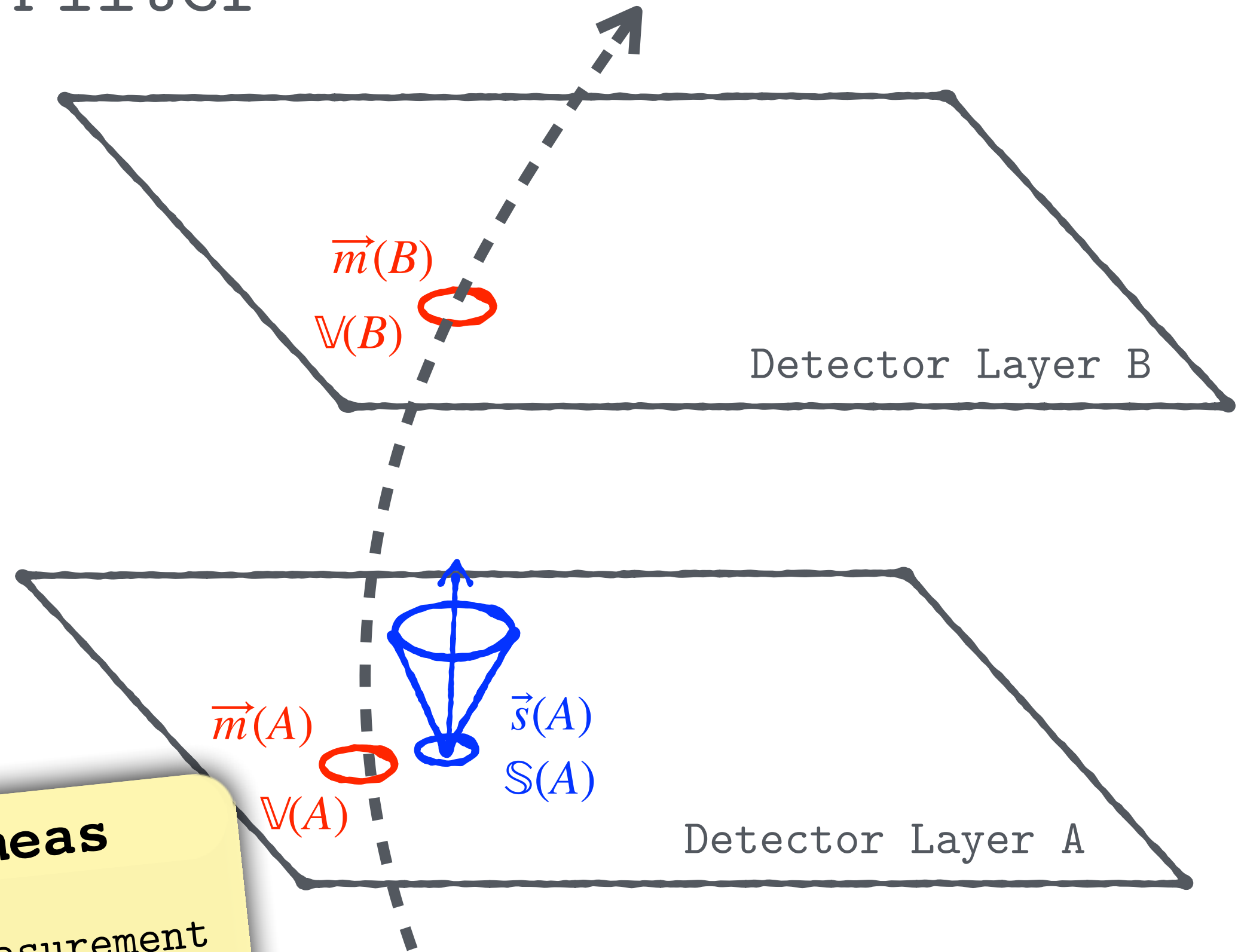
- Transformation from state to measurement space

$$H = \frac{\partial m_i}{\partial s_j}$$

- So that:

$$\vec{m} = H \vec{s}$$

Tracks



Track finding & reconstruction: Kalman Filter

Measurement and Covariance

- Measurement vector

$$\vec{m} = \begin{pmatrix} x \\ y \end{pmatrix}$$

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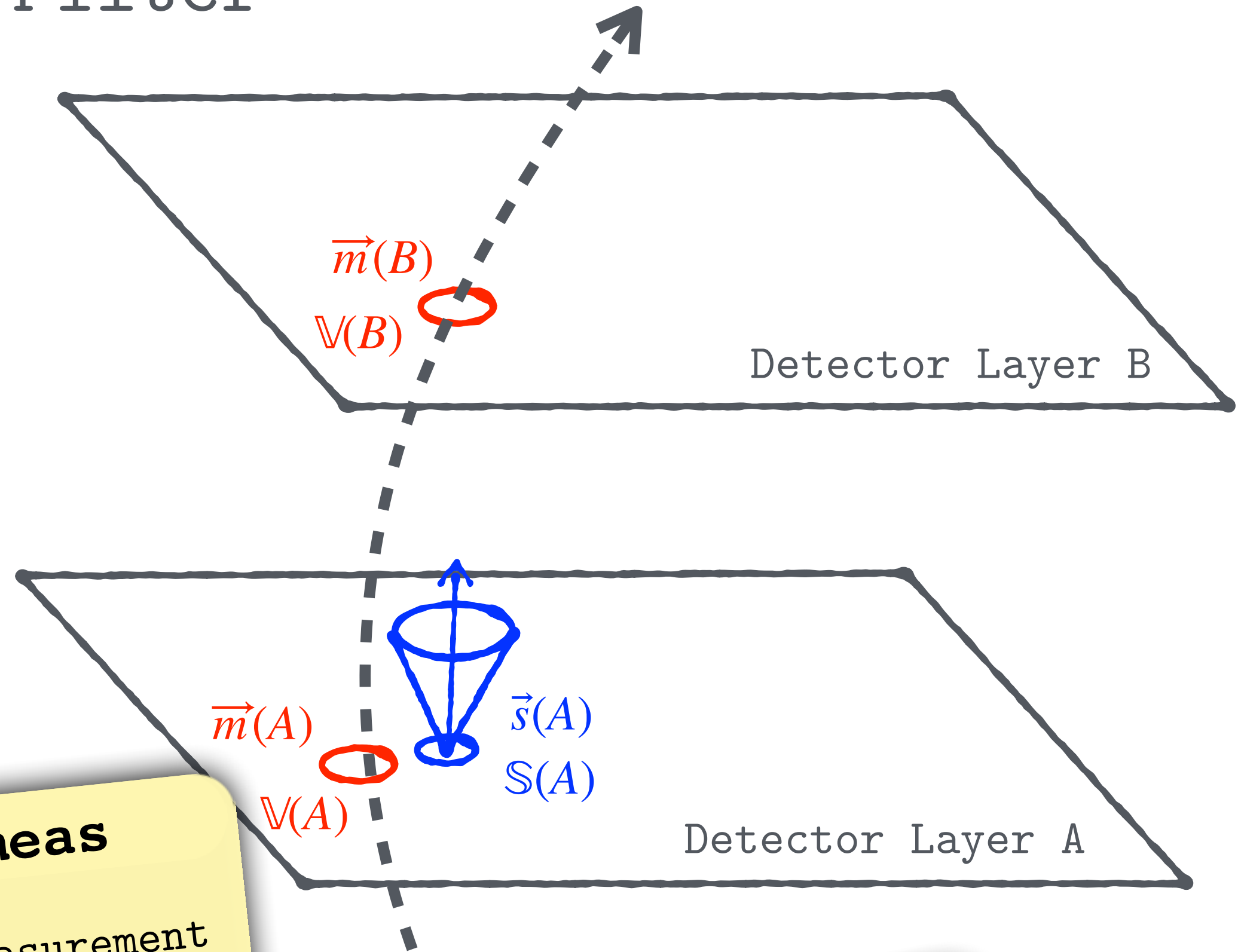
- So that:

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Propagation operator

- Matrix F that propagates a state from position A to position B so that:

$$\vec{s}(B) = F(B|A) \vec{s}(A)$$



Tracks

Track finding & reconstruction: Kalman Filter

Measurement and Covariance

- Measurement vector

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Tracks

Transform: state to meas

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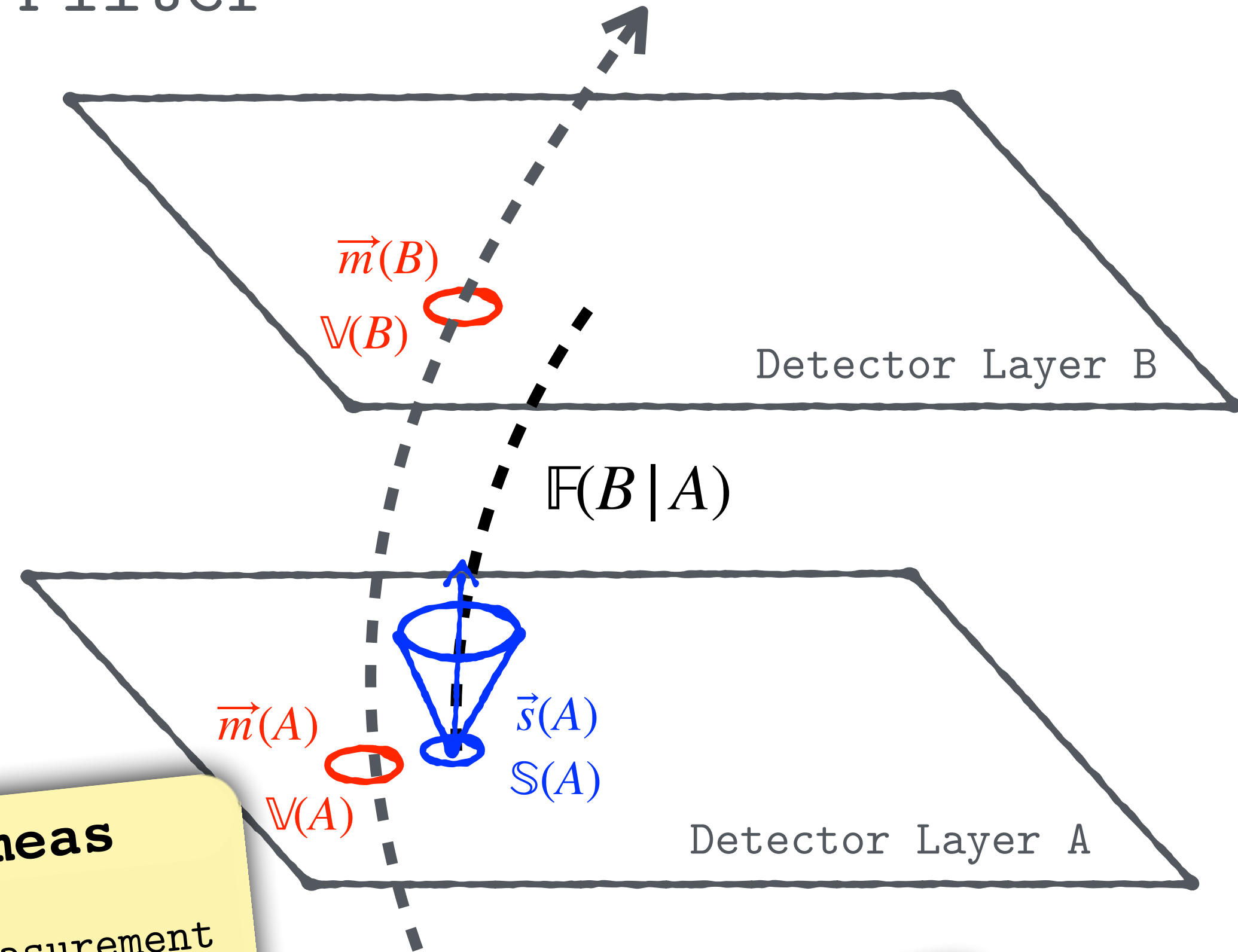
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Propagation operator

- Matrix \mathbb{F} that propagates a state from position A to position B so that:

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Track finding & reconstruction: Kalman Filter

Measurement and Covariance

- Measurement vector

$$\vec{m} = \begin{pmatrix} x \\ y \end{pmatrix}$$

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State vector and Covariance

- Many ways to parameterise a track

$$\vec{s} = \begin{pmatrix} q/p \\ dx/dz \\ dy/dz \\ x \\ y \end{pmatrix}$$

- And its covariance matrix \mathbb{S}

Tracks

Transform: state to meas

- Transformation from state to measurement space

$$\mathbb{H} = \frac{\partial m_i}{\partial s_j}$$

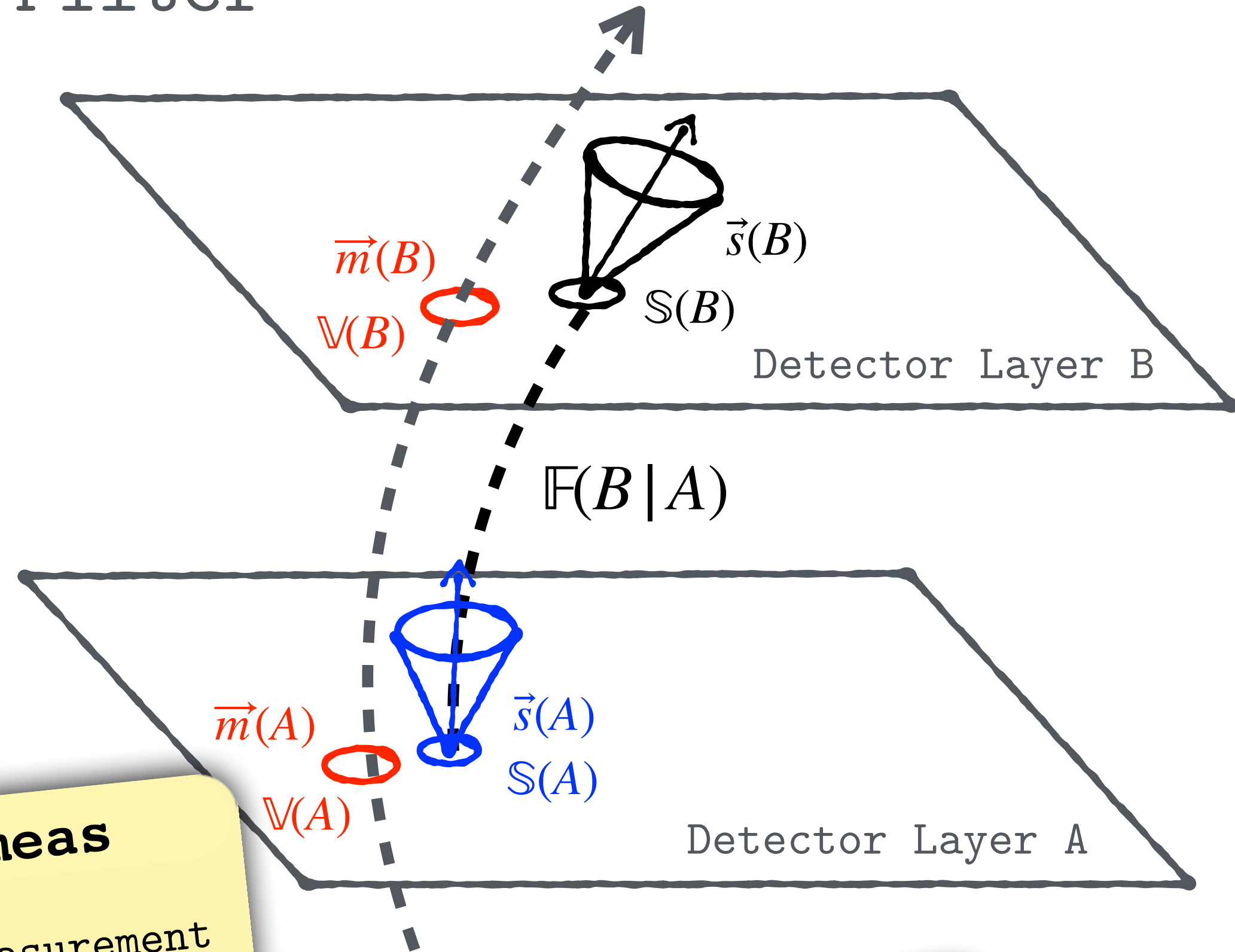
- So that:

$$\vec{m} = \mathbb{H} \vec{s}$$

Propagation operator

- Matrix \mathbb{F} that propagates a state from position A to position B so that:

$$\vec{s}(B) = \mathbb{F}(B|A) \vec{s}(A)$$



Track finding & reconstruction: Kalman Filter

Measurement and Covariance

- Measurement vector

$$\vec{m} = \begin{pmatrix} x \\ y \end{pmatrix}$$

- And its covariance matrix \mathbb{V}

State vector and Covariance

- Many ways to parameterise a track

$$\vec{s} = \begin{pmatrix} q/p \\ dx/dz \\ dy/dz \\ x \\ y \end{pmatrix}$$

- And its covariance matrix \mathbb{S}

Tracks

Noise Model

- Due to Multiple Scattering, etc: \mathbb{W}

Transform: state to meas

- Transformation from state to measurement space

$$\mathbb{H} = \frac{\partial m_i}{\partial s_j}$$

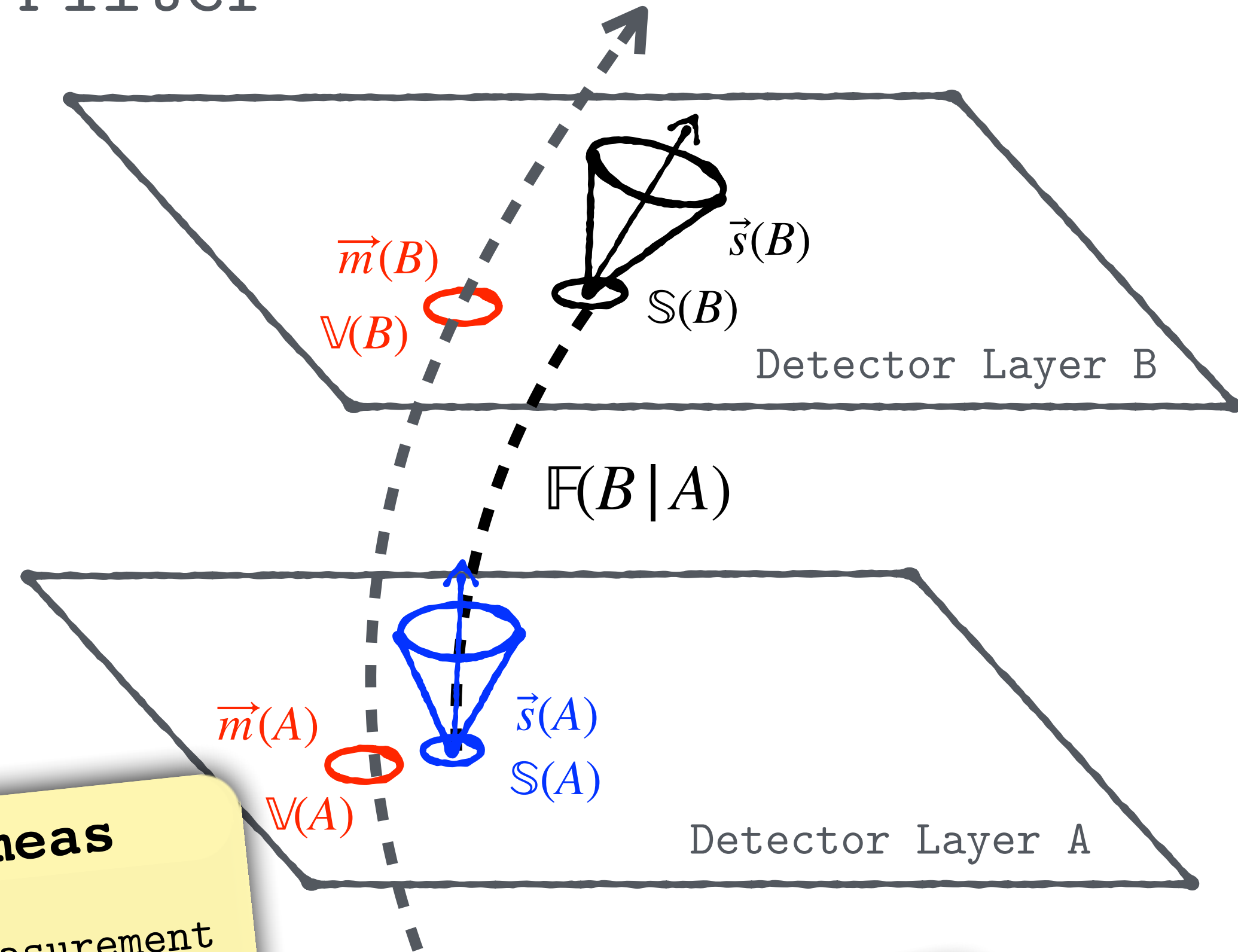
- So that:

$$\vec{m} = \mathbb{H} \vec{s}$$

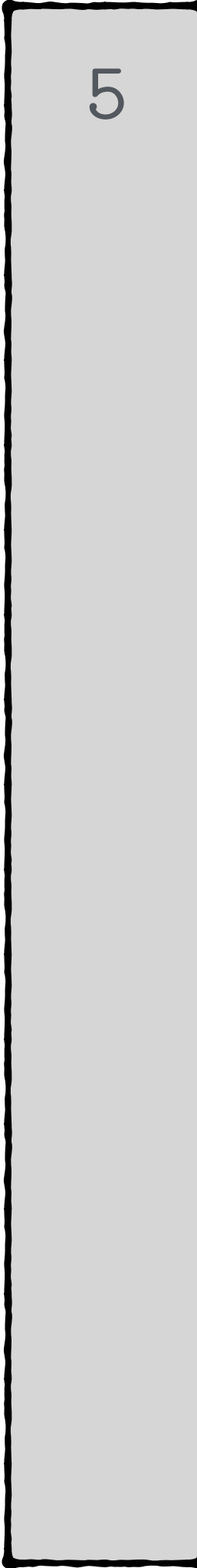
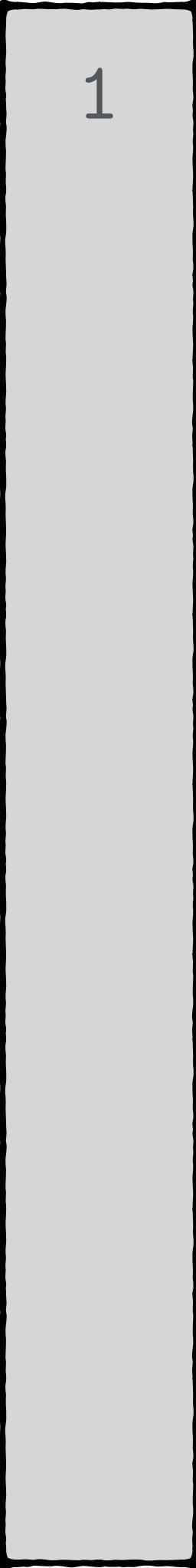
Propagation operator

- Matrix \mathbb{F} that propagates a state from position A to position B so that:

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Track finding & reconstruction: Kalman Filter

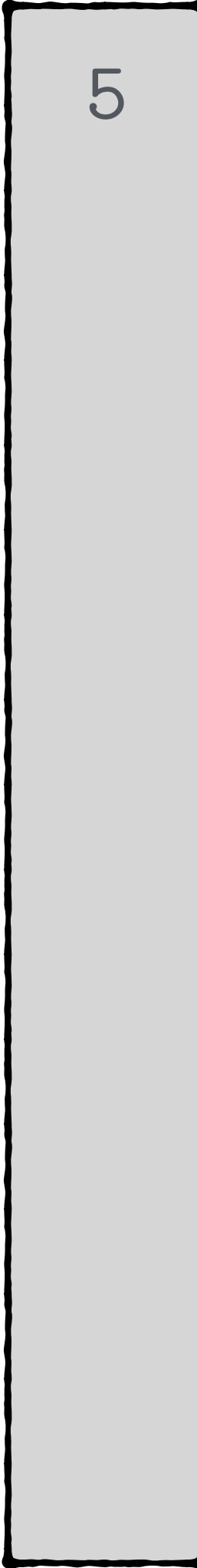
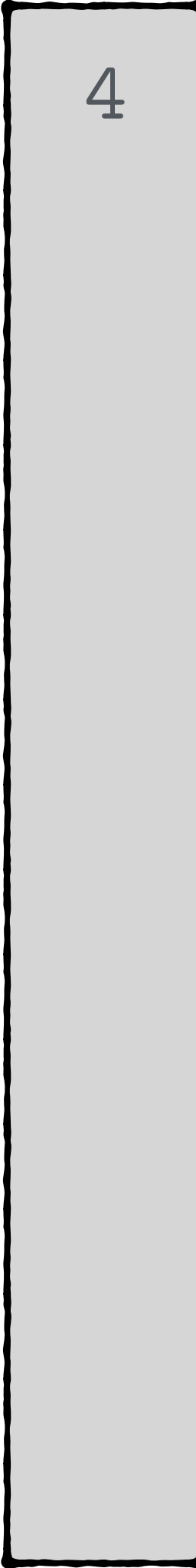
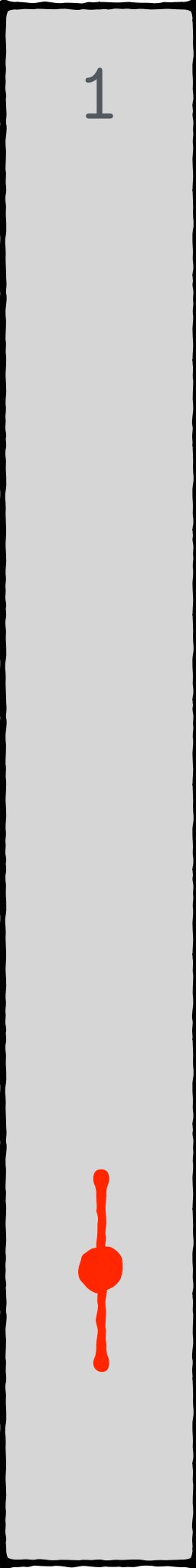


Prediction

Measurement

Filtered

Track finding & reconstruction: Kalman Filter



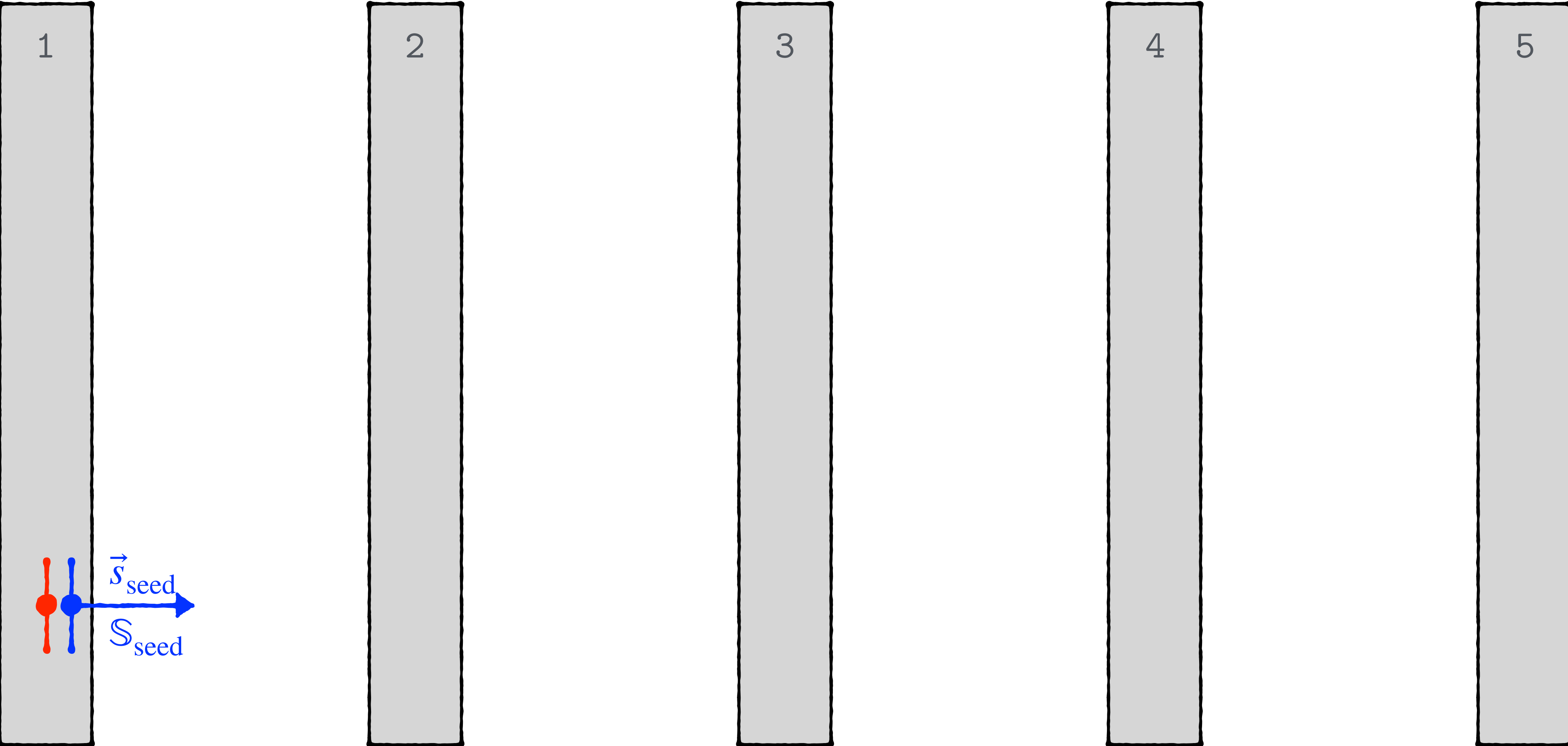
Prediction

Measurement

Filtered

Track finding & reconstruction: Kalman Filter

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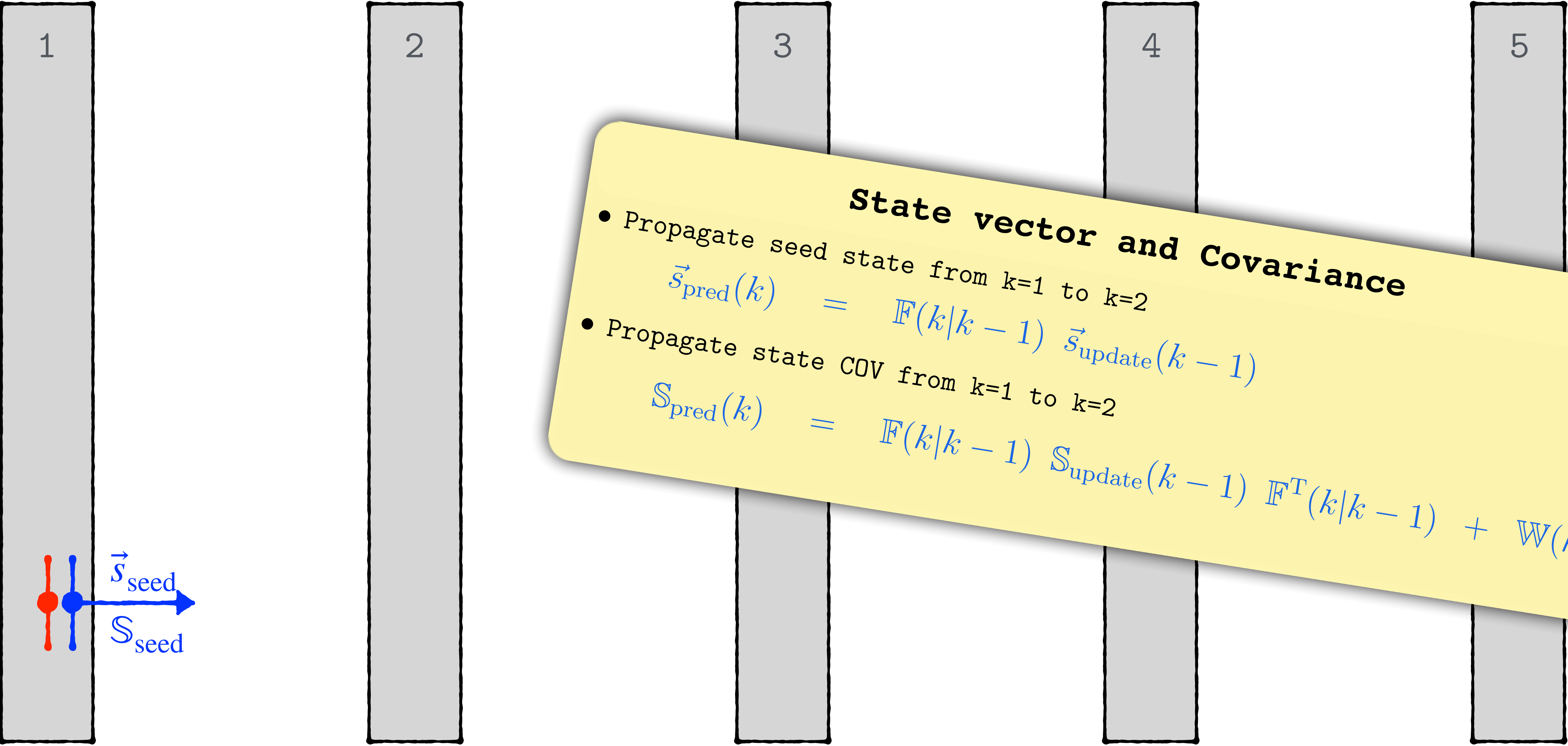


Prediction

Measurement

Filtered

Track finding & reconstruction: Kalman Filter



Prediction

Measurement

Filtered

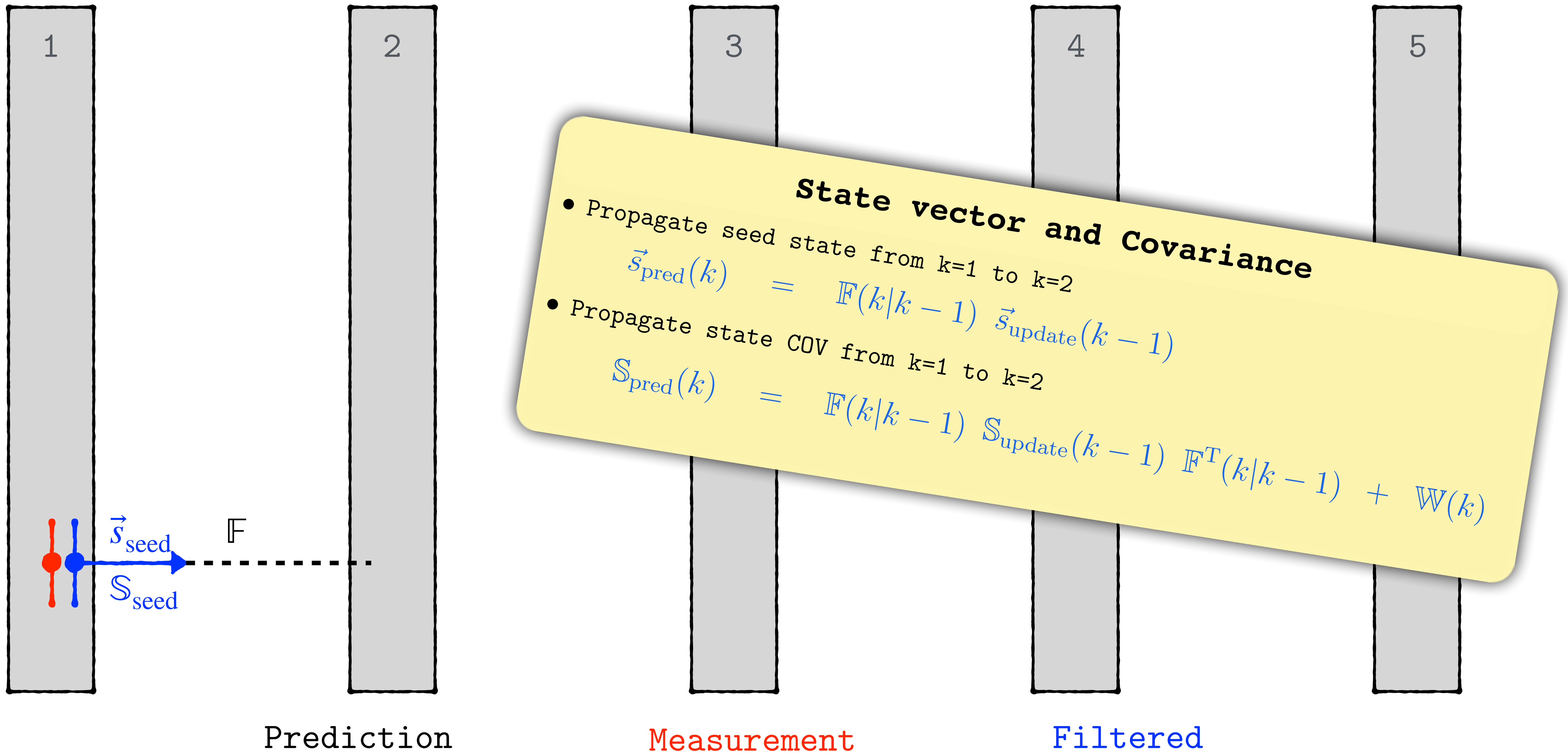
State vector and Covariance

- Propagate seed state from $k=1$ to $k=2$

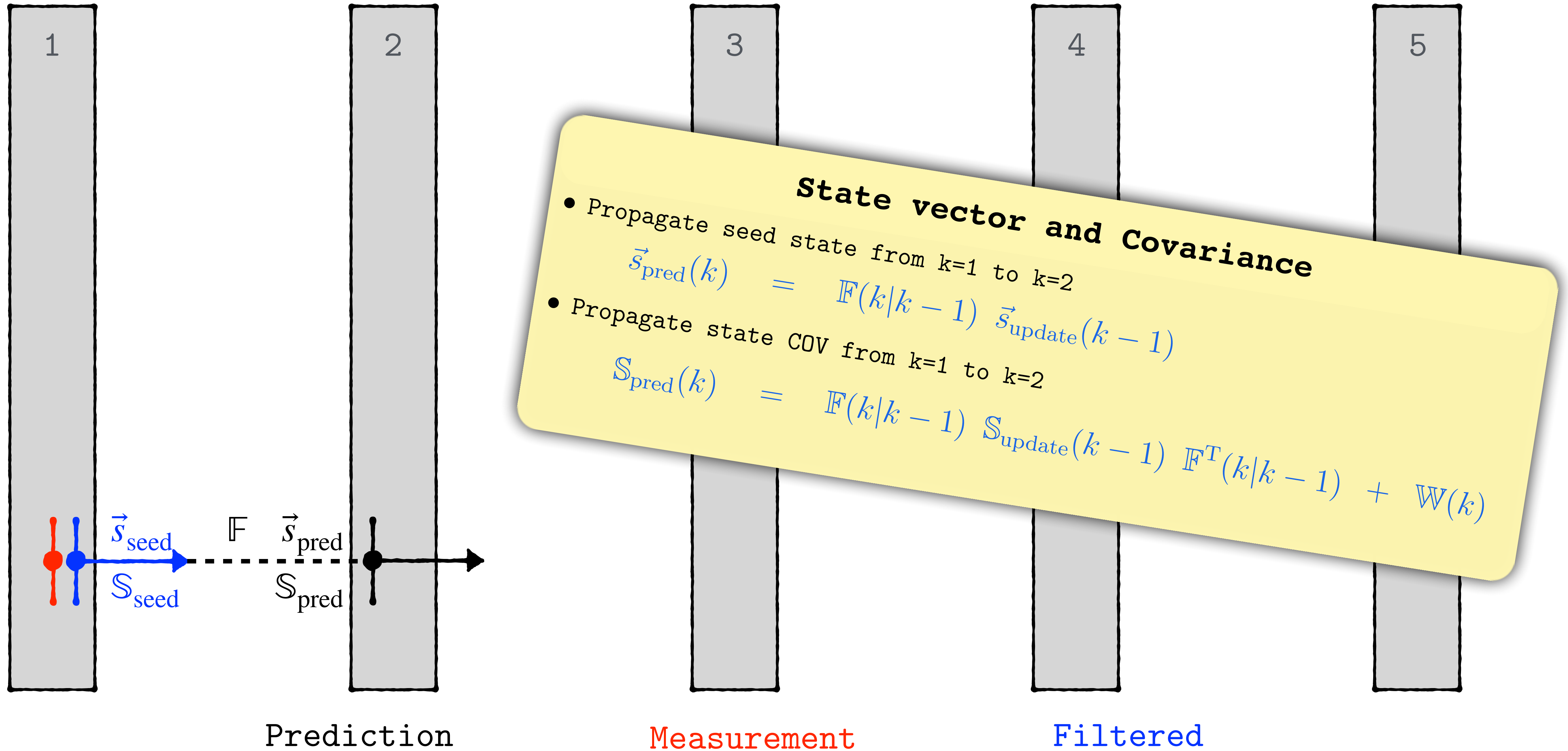
$$\vec{s}_{pred}(k) = F(k|k-1) \vec{s}_{update}(k-1)$$
- Propagate state COV from $k=1$ to $k=2$

$$S_{pred}(k) = F(k|k-1) S_{update}(k-1) F^T(k|k-1) + W(k)$$

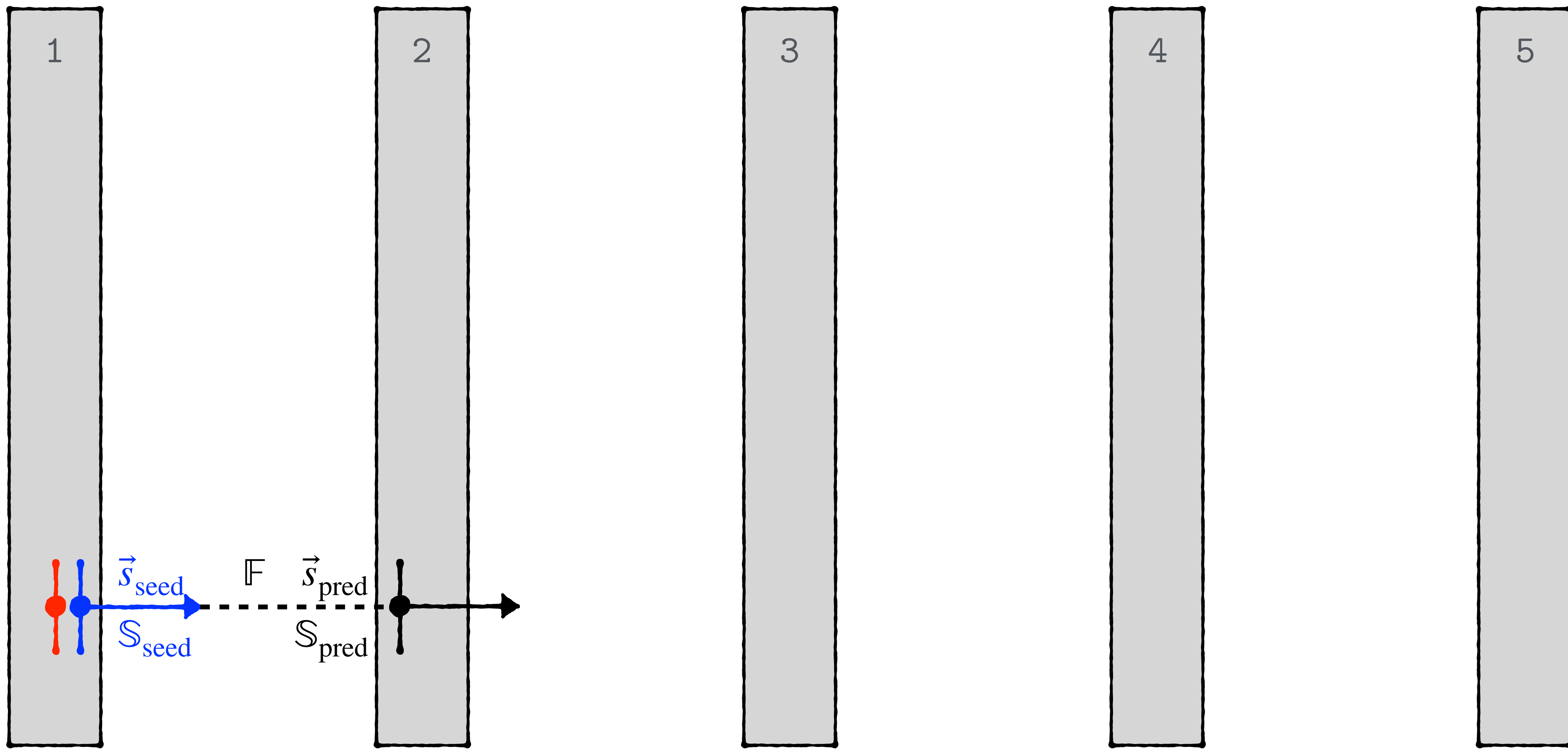
Track finding & reconstruction: Kalman Filter



Track finding & reconstruction: Kalman Filter



Track finding & reconstruction: Kalman Filter

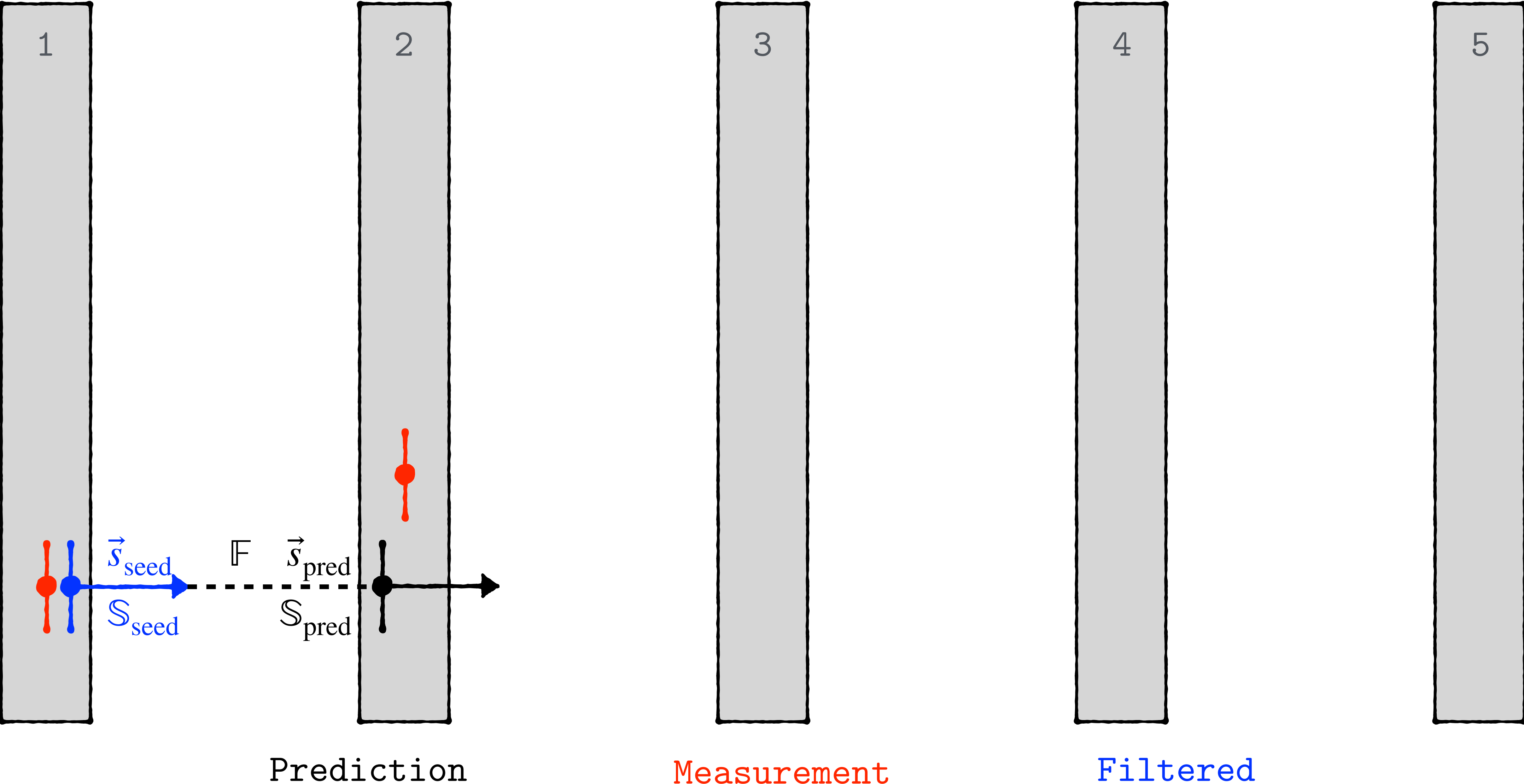


Prediction

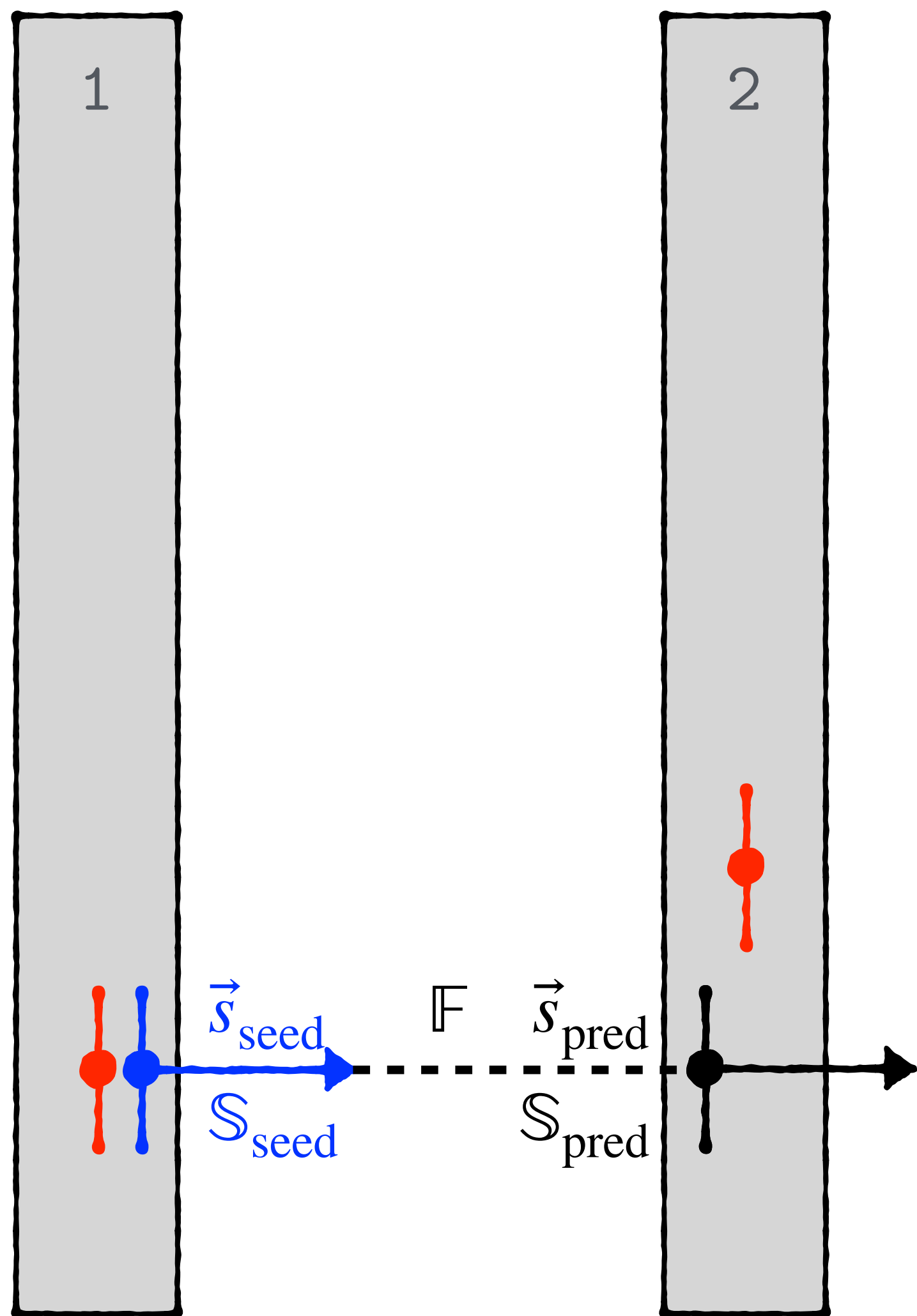
Measurement

Filtered

Track finding & reconstruction: Kalman Filter



Track finding & reconstruction: Kalman Filter



Prediction

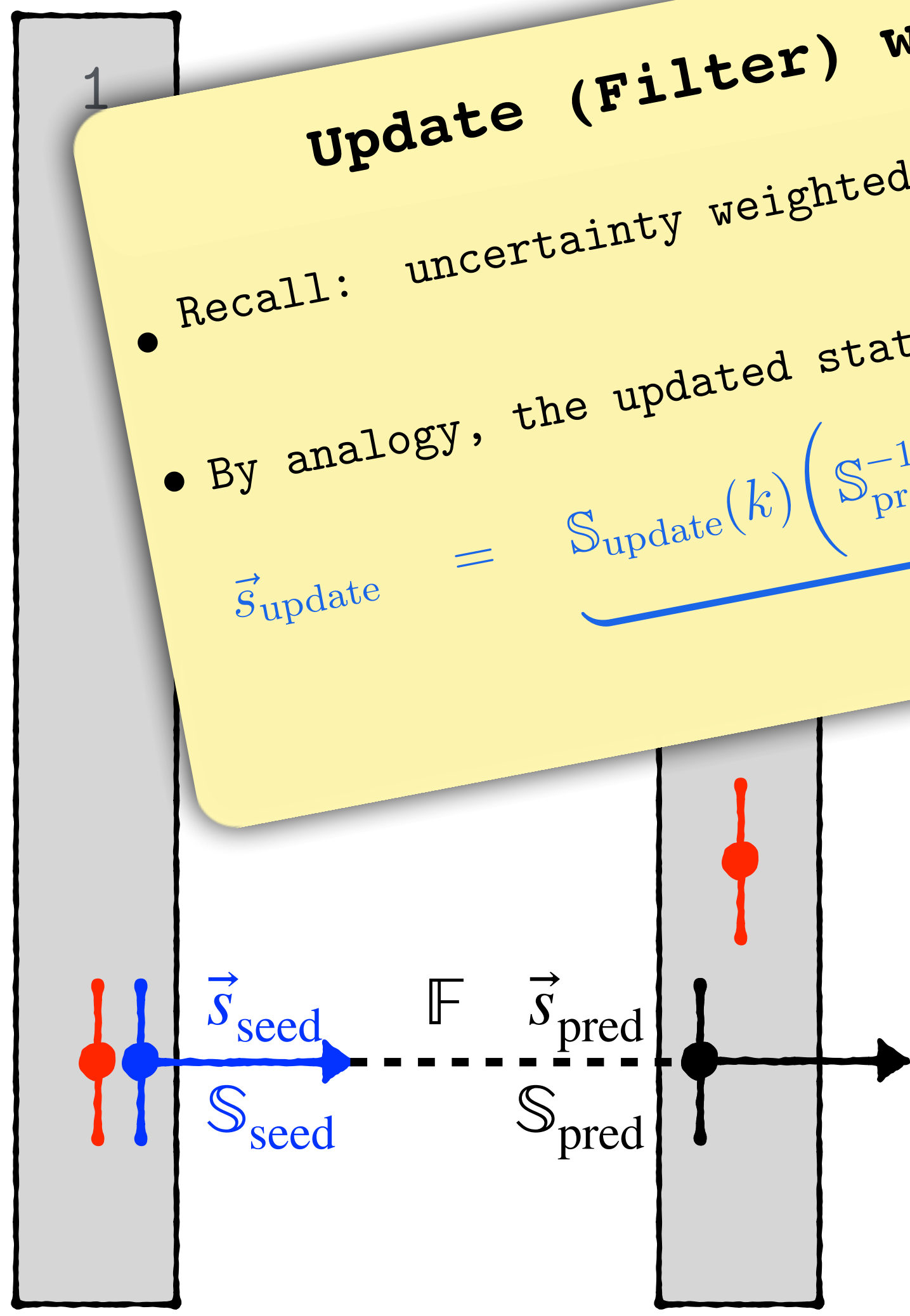
Update (Filter) with measurement information

- Recall: uncorrelated uncertainty of an average is $\frac{1}{\sigma_{\text{avg}}^2} = \frac{1}{\sigma_1^2} + \frac{1}{\sigma_2^2}$
- By analogy, the updated full COV for the average is

$$S_{\text{update}}^{-1}(k) = S_{\text{pred}}^{-1}(k) + \underbrace{H^T(k) V^{-1} H(k)}_{S_{\text{meas}}^{-1}}$$

Measurement Filtered

Track finding & reconstruction: Kalman Filter



Prediction

Measurement

Filtered

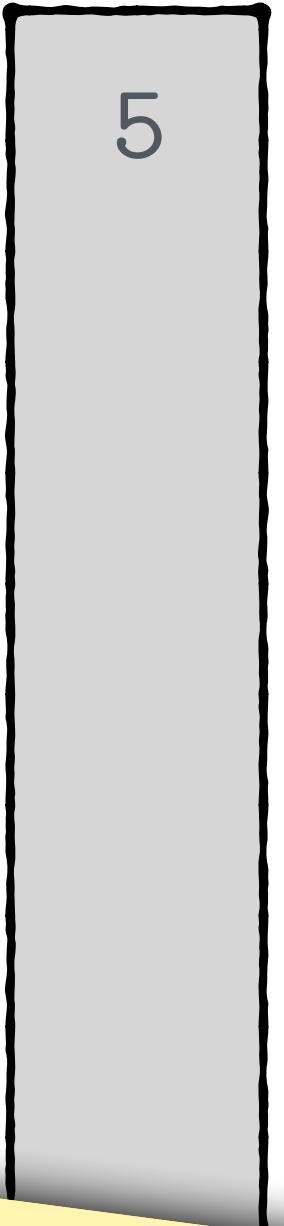
Update (Filter) with measurement information

- Recall: uncertainty weighted average is $x_{\text{avg}} = \sigma_{\text{avg}}^2 \left(\frac{x_1}{\sigma_1^2} + \frac{x_2}{\sigma_2^2} \right)$
- By analogy, the updated state for the average is

$$\vec{s}_{\text{update}} = \underbrace{S_{\text{update}}(k)}_{\text{uncertainty weighted average}} \left(\underbrace{S_{\text{pred}}^{-1}(k) \vec{s}_{\text{pred}}(k)}_{\text{uncertainty weighted average}} + \underbrace{H^T(k) V^{-1}(k) H(k)}_{S_{\text{meas}}^{-1}} \underbrace{\vec{s}_{\text{meas}}}_{\vec{m}(k)} \right)$$

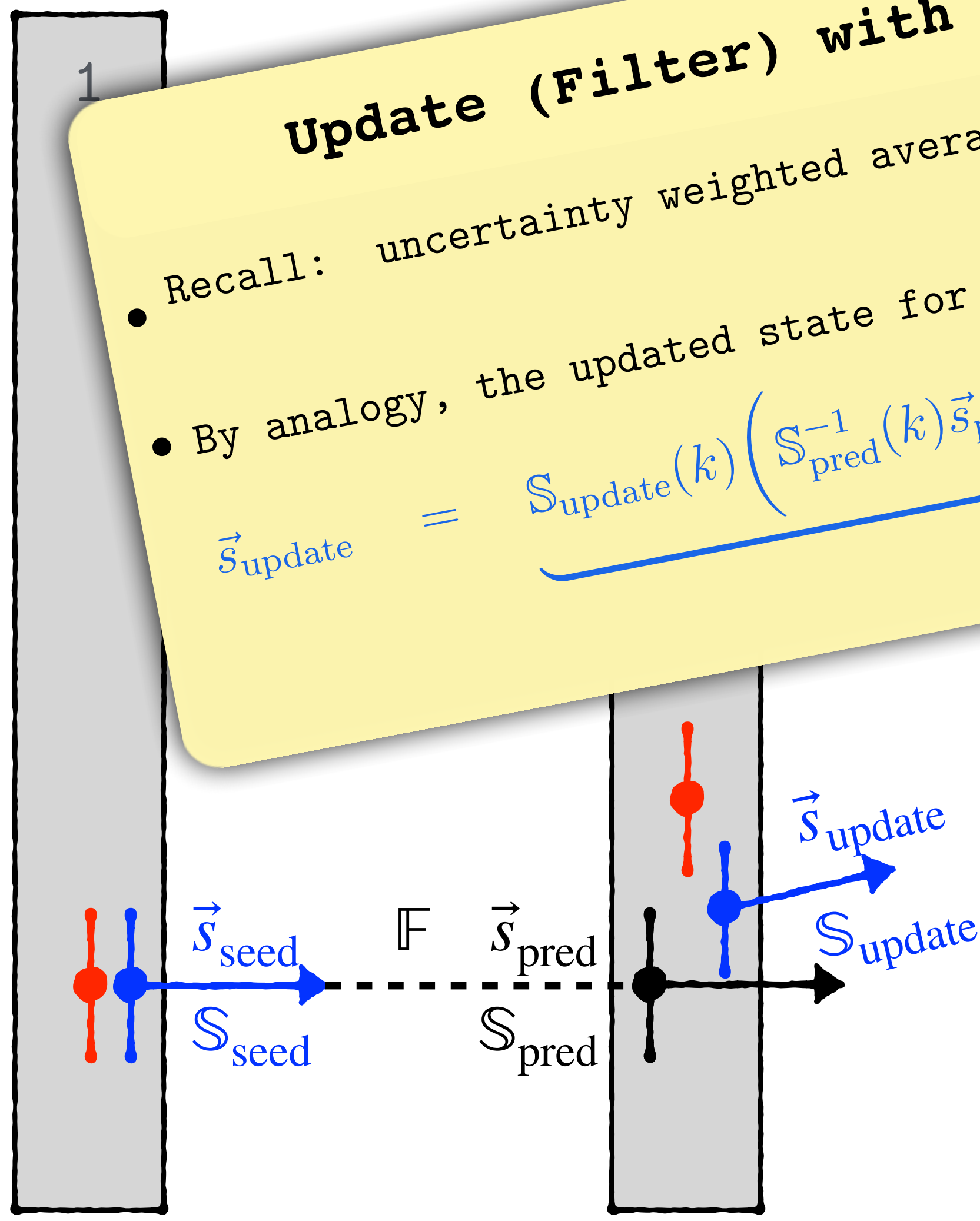
Update (Filter) with measurement information

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5

Track finding & reconstruction: Kalman Filter



Prediction

Measurement

Filtered

Update (Filter) with measurement information

- Recall: uncertainty weighted average is $x_{avg} = \sigma_{avg}^2 \left(\frac{x_1}{\sigma_1^2} + \frac{x_2}{\sigma_2^2} \right)$
- By analogy, the updated state for the average is

$$\vec{s}_{update} = S_{update}(k) \left(S_{pred}^{-1}(k) \vec{s}_{pred}(k) + \underbrace{H^T(k) V^{-1}(k) H(k)}_{S_{meas}^{-1}} \vec{s}_{meas} \right)$$

uncertainty weighted average

Update (Filter) with measurement information

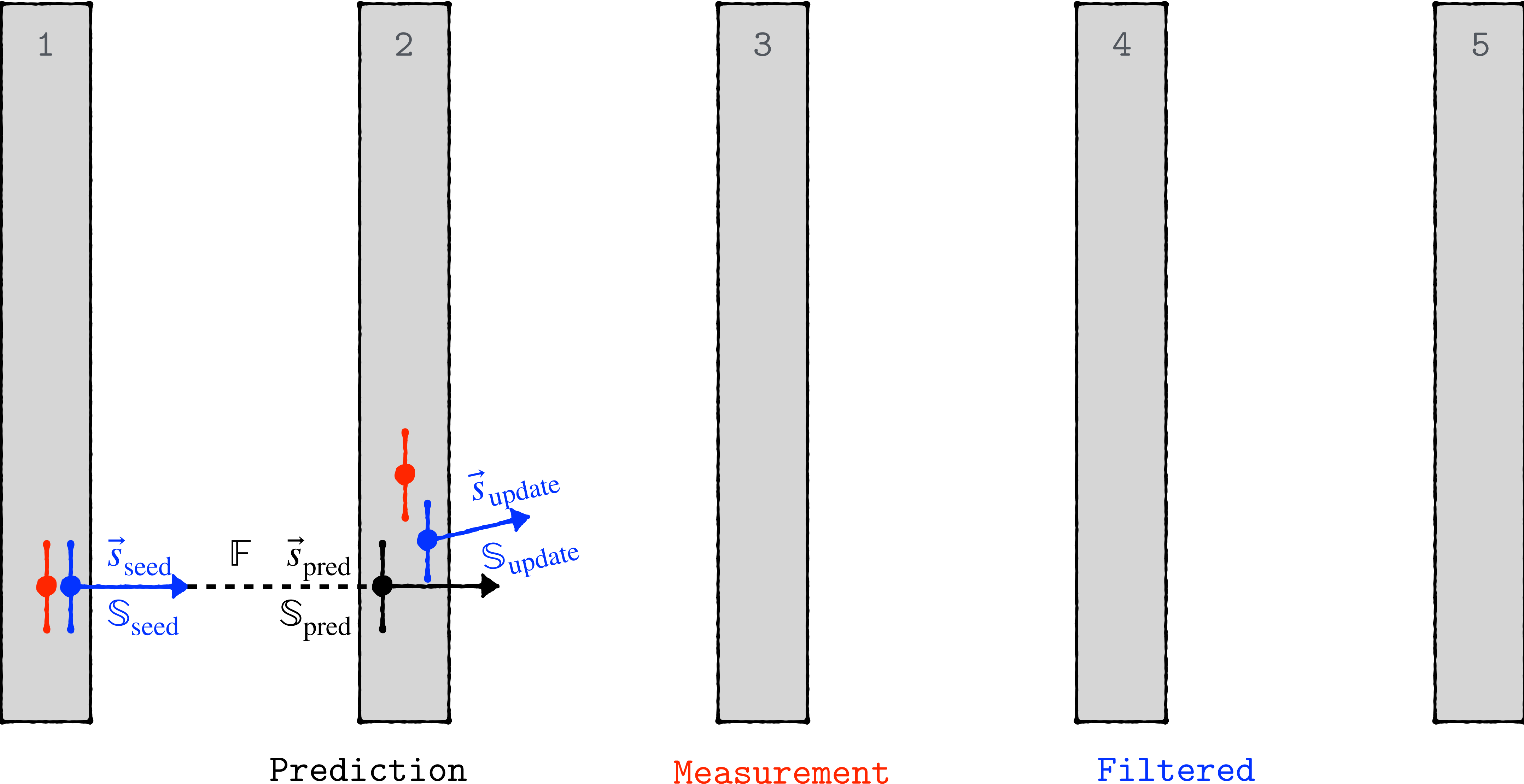
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- By analogy, the updated full COV for the average is

$$S_{update}^{-1}(k) = S_{pred}^{-1}(k) + \underbrace{H^T(k) V^{-1} H(k)}_{S_{meas}^{-1}}$$

1

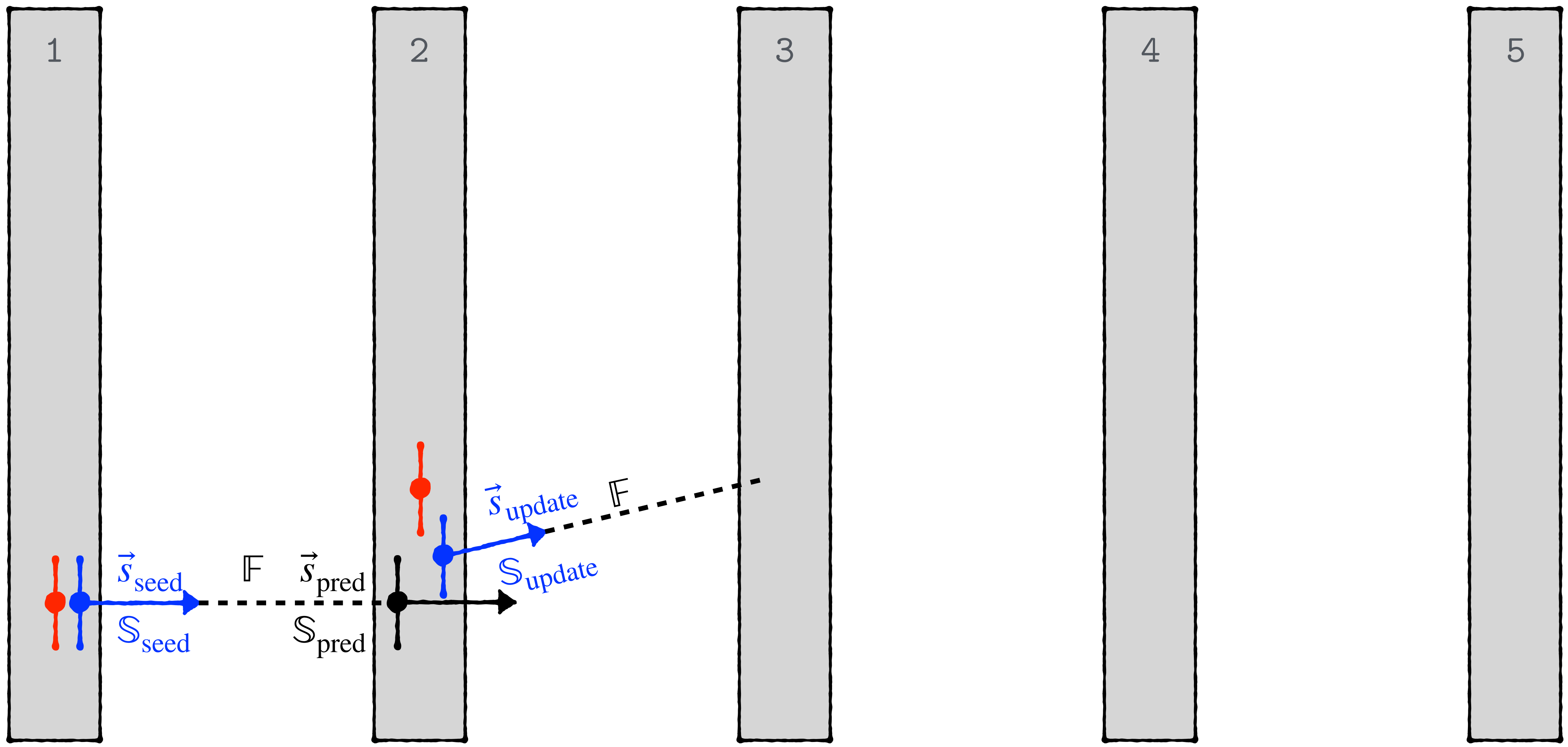
5

Track finding & reconstruction: Kalman Filter



Track finding & reconstruction: Kalman Filter

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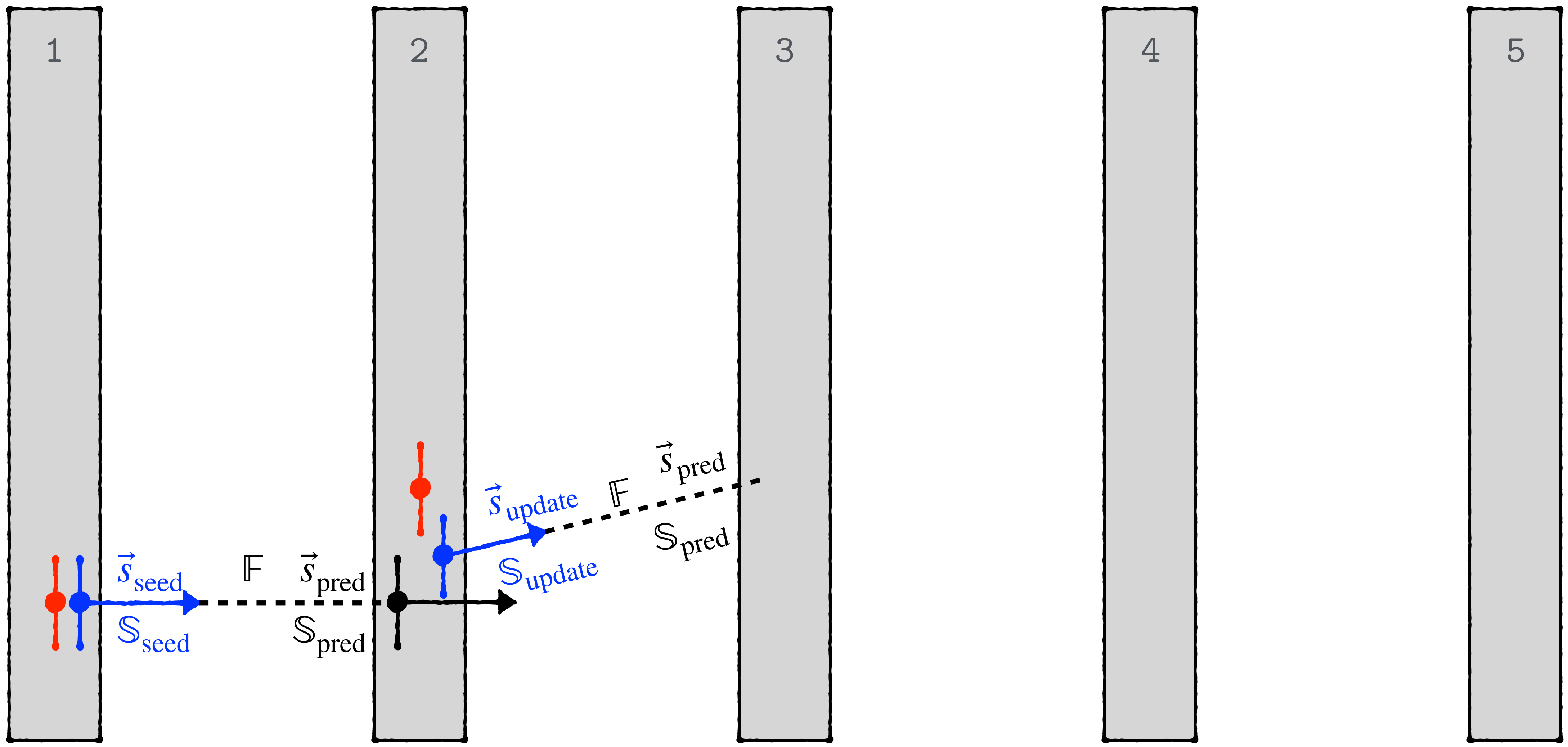
Prediction

Measurement

Filtered

Track finding & reconstruction: Kalman Filter

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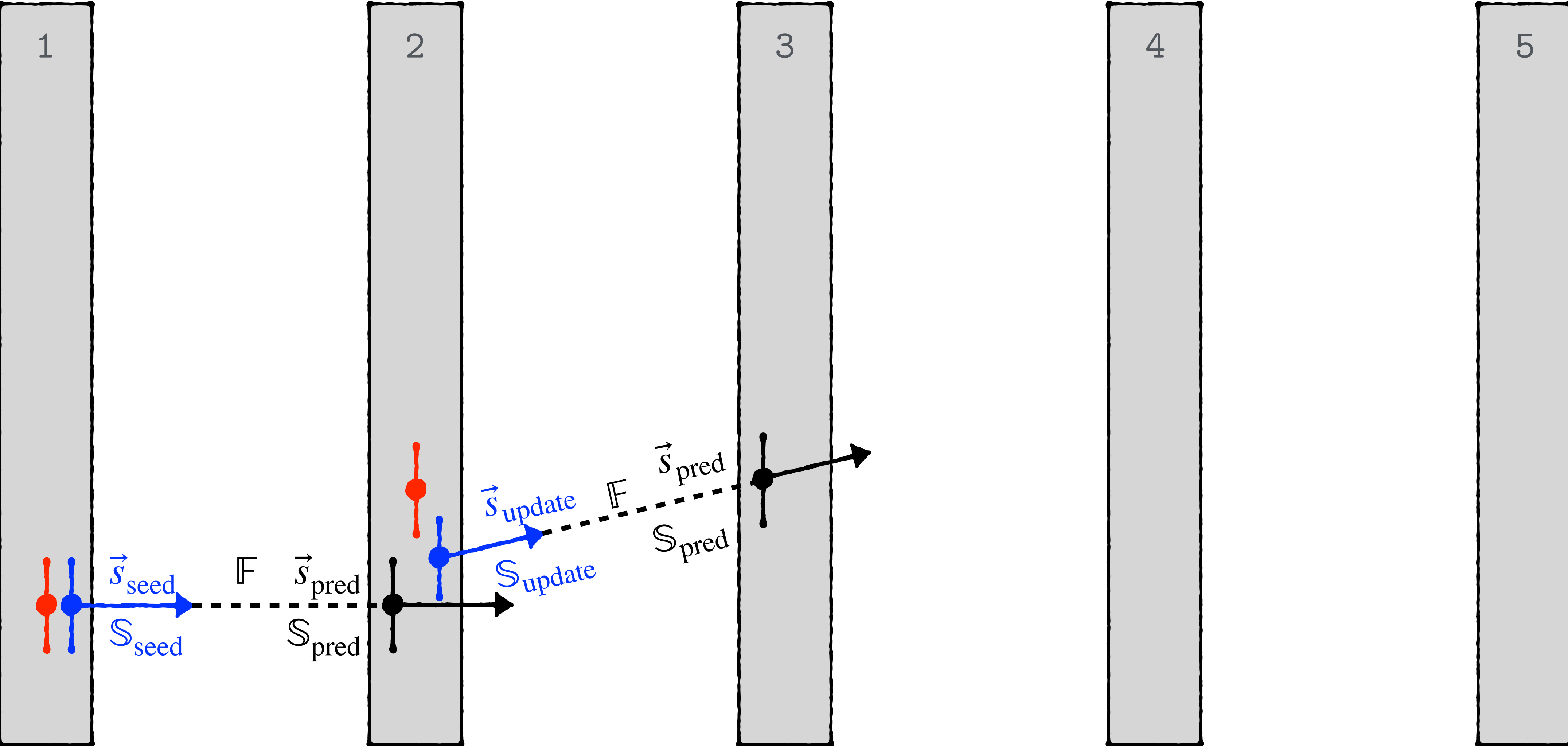


Prediction

Measurement

Filtered

Track finding & reconstruction: Kalman Filter

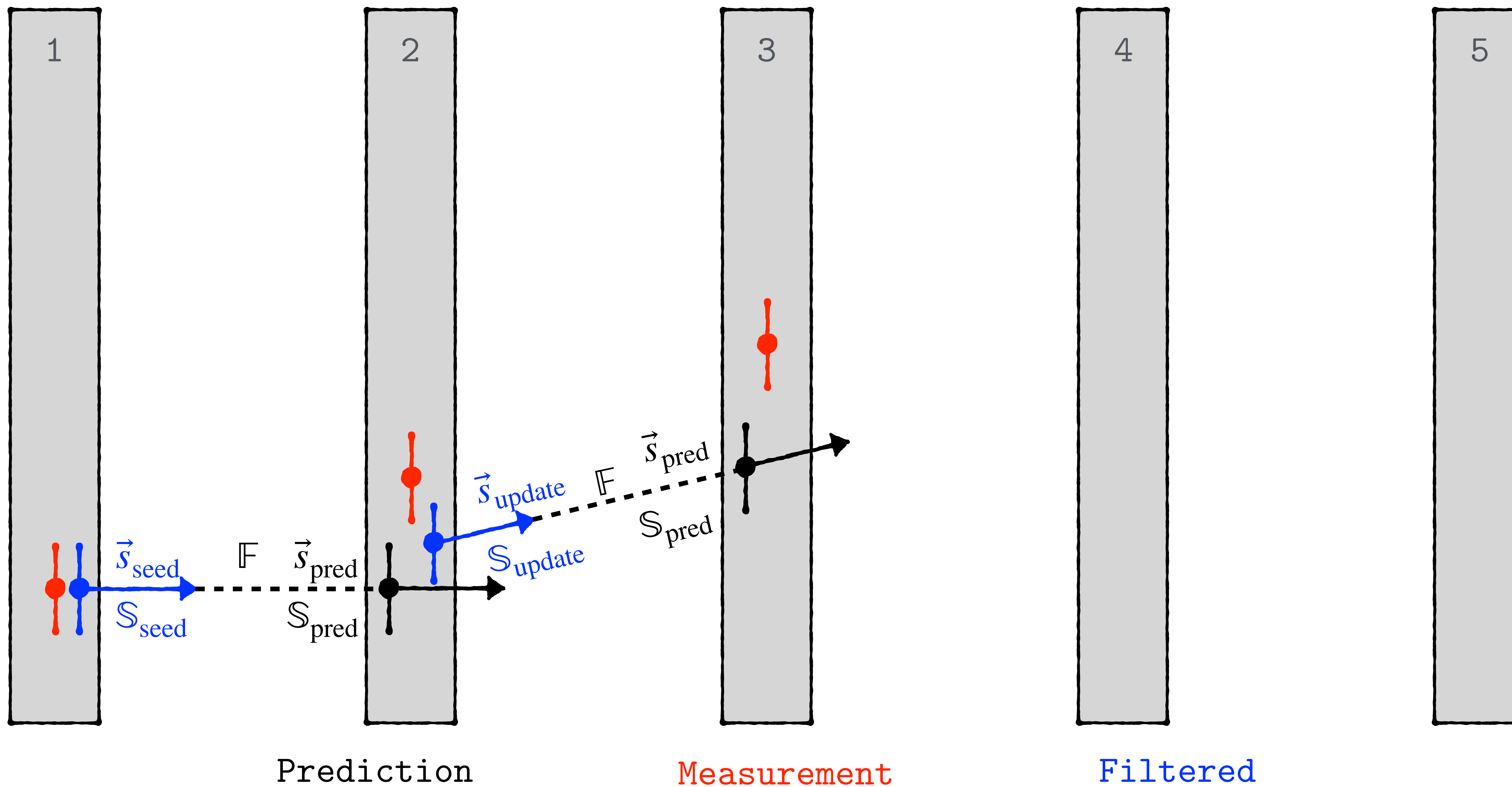


Prediction

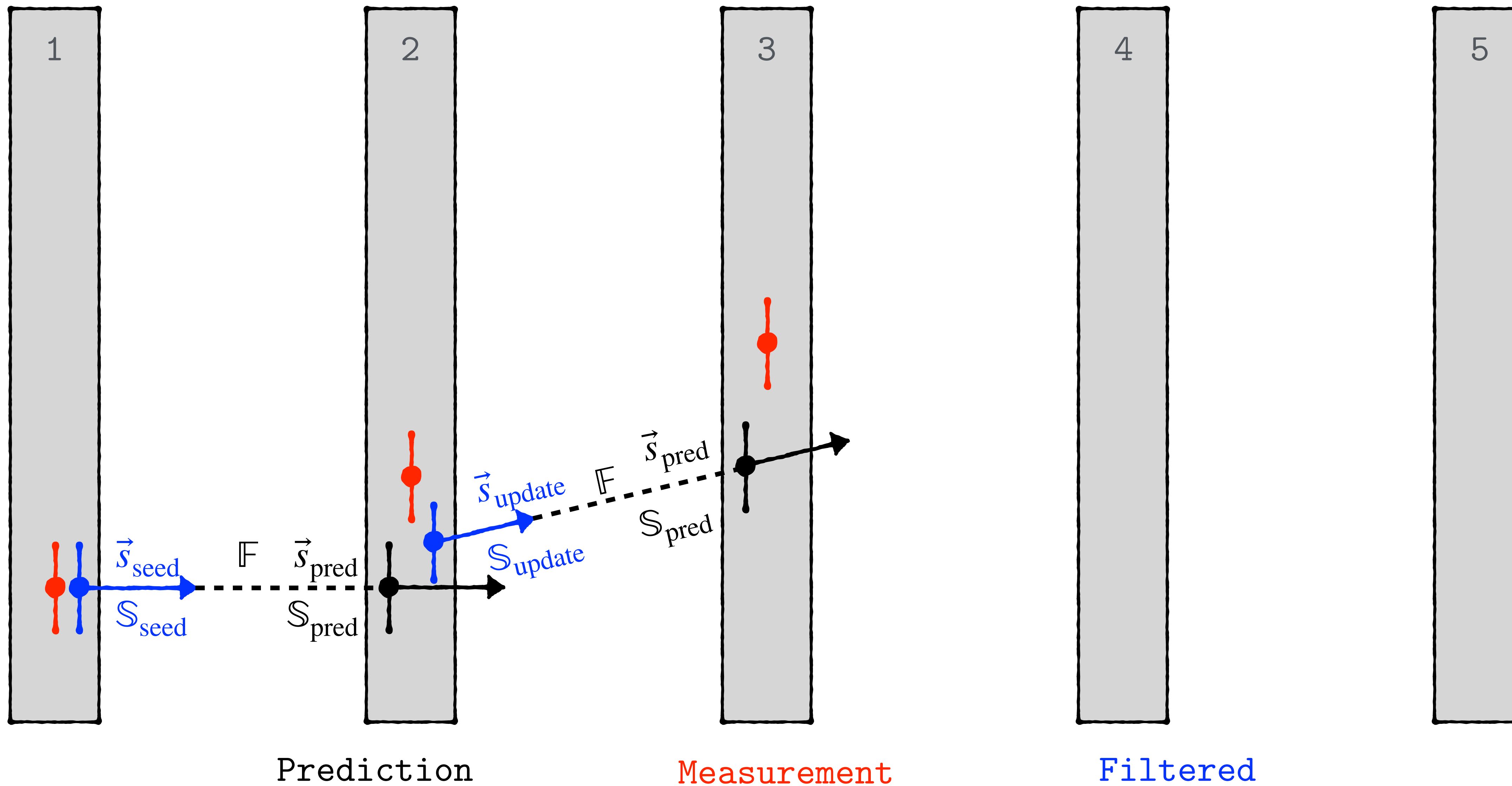
Measurement

Filtered

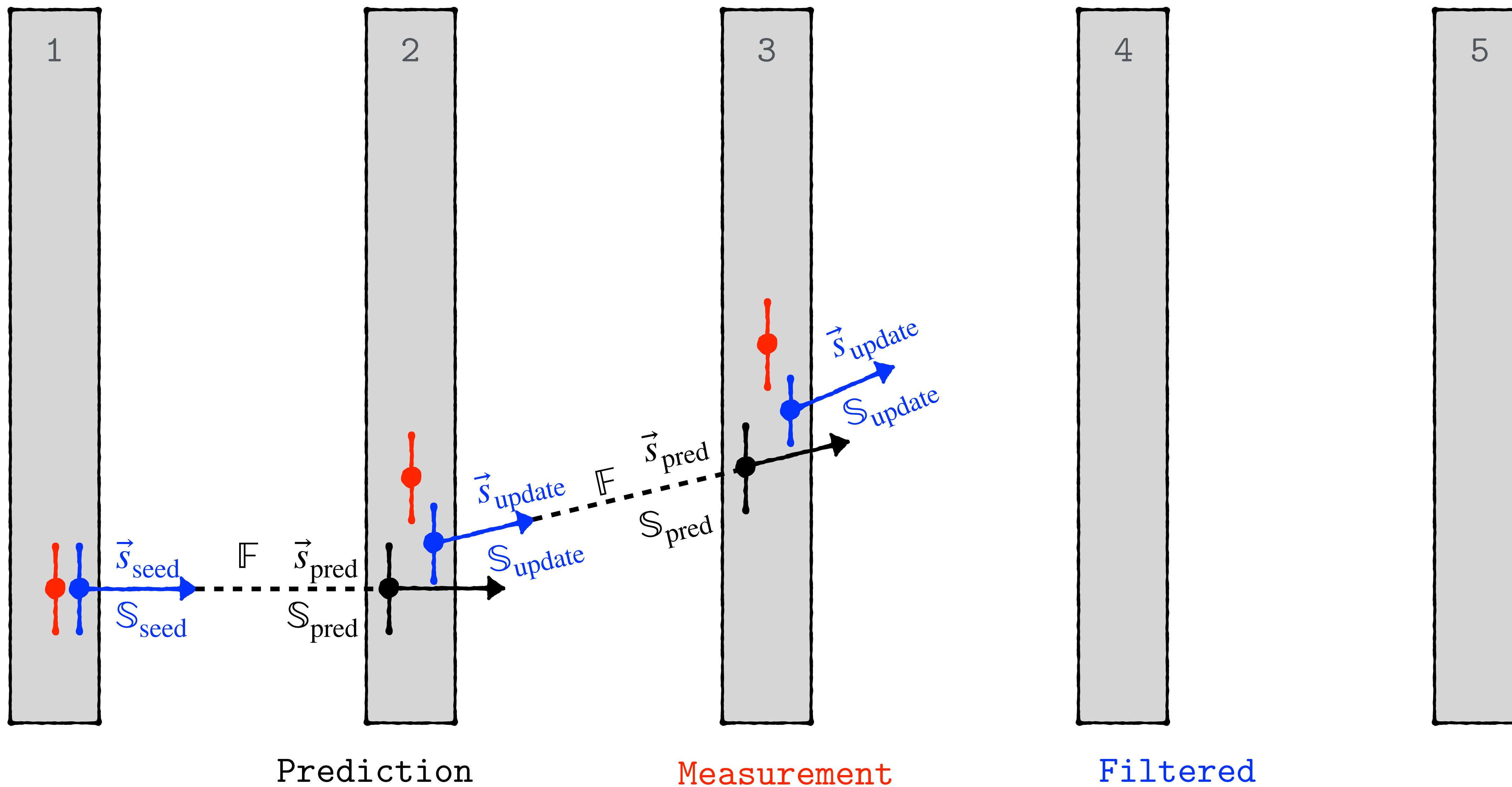
Track finding & reconstruction: Kalman Filter



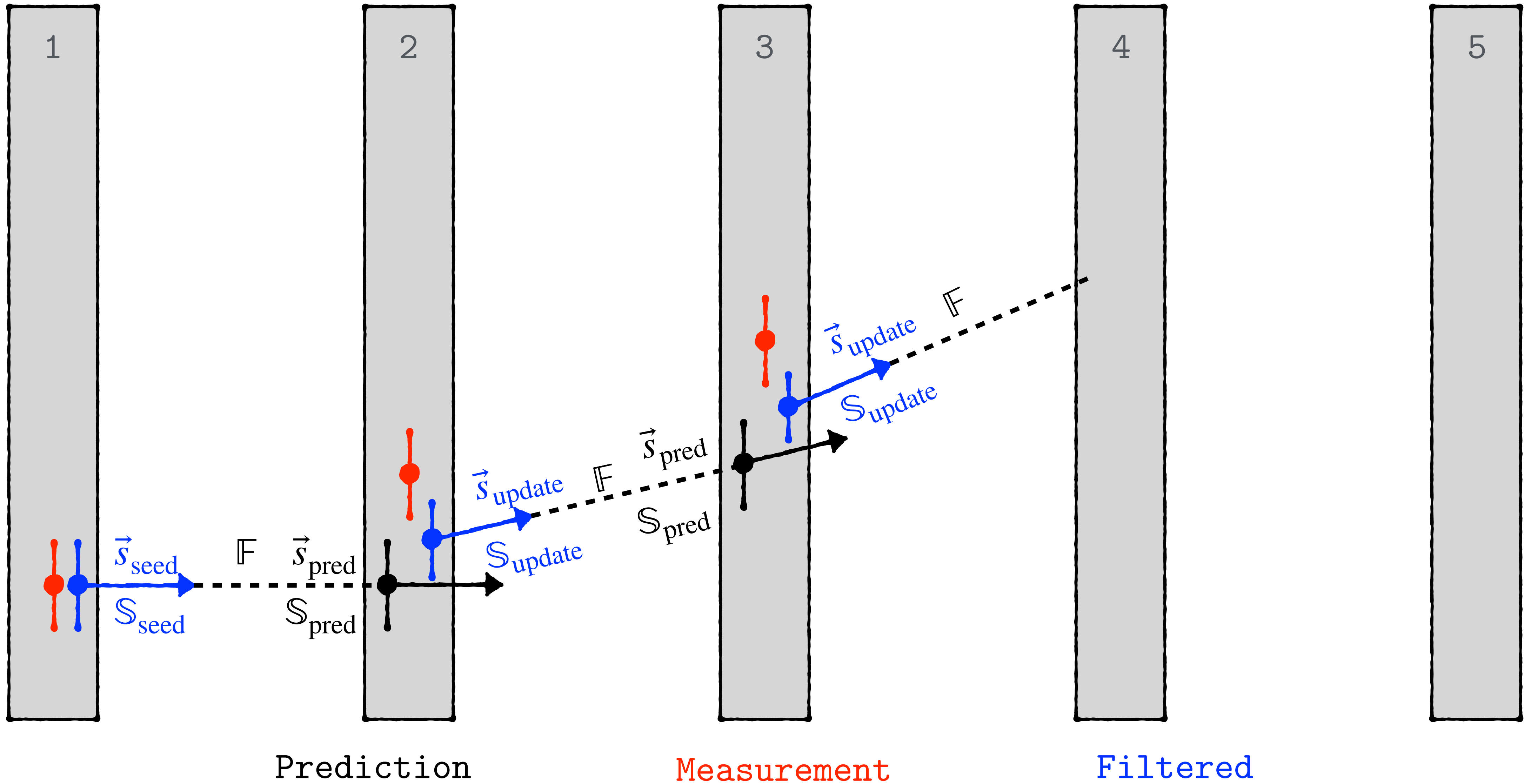
Track finding & reconstruction: Kalman Filter



Track finding & reconstruction: Kalman Filter

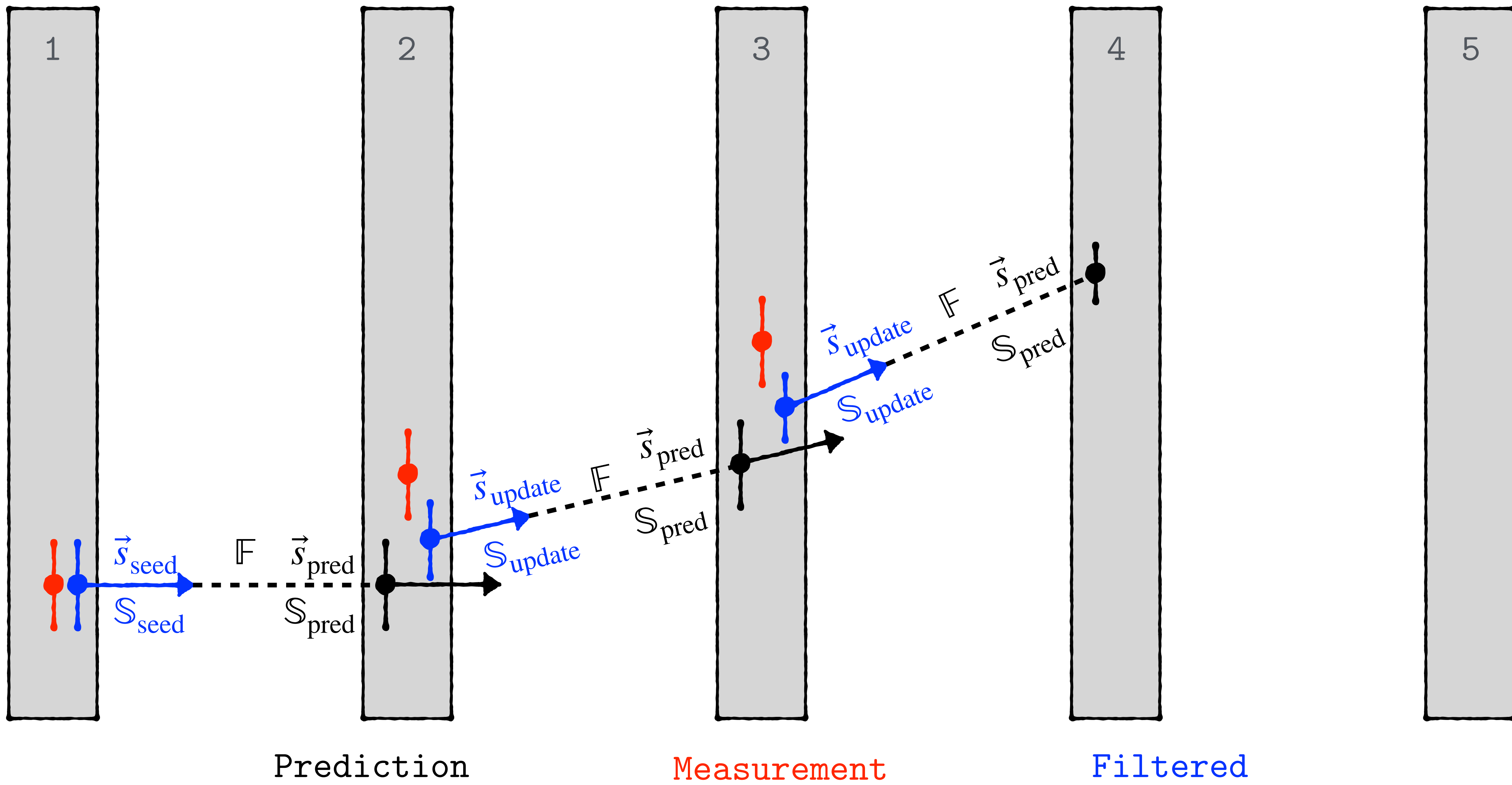


Track finding & reconstruction: Kalman Filter

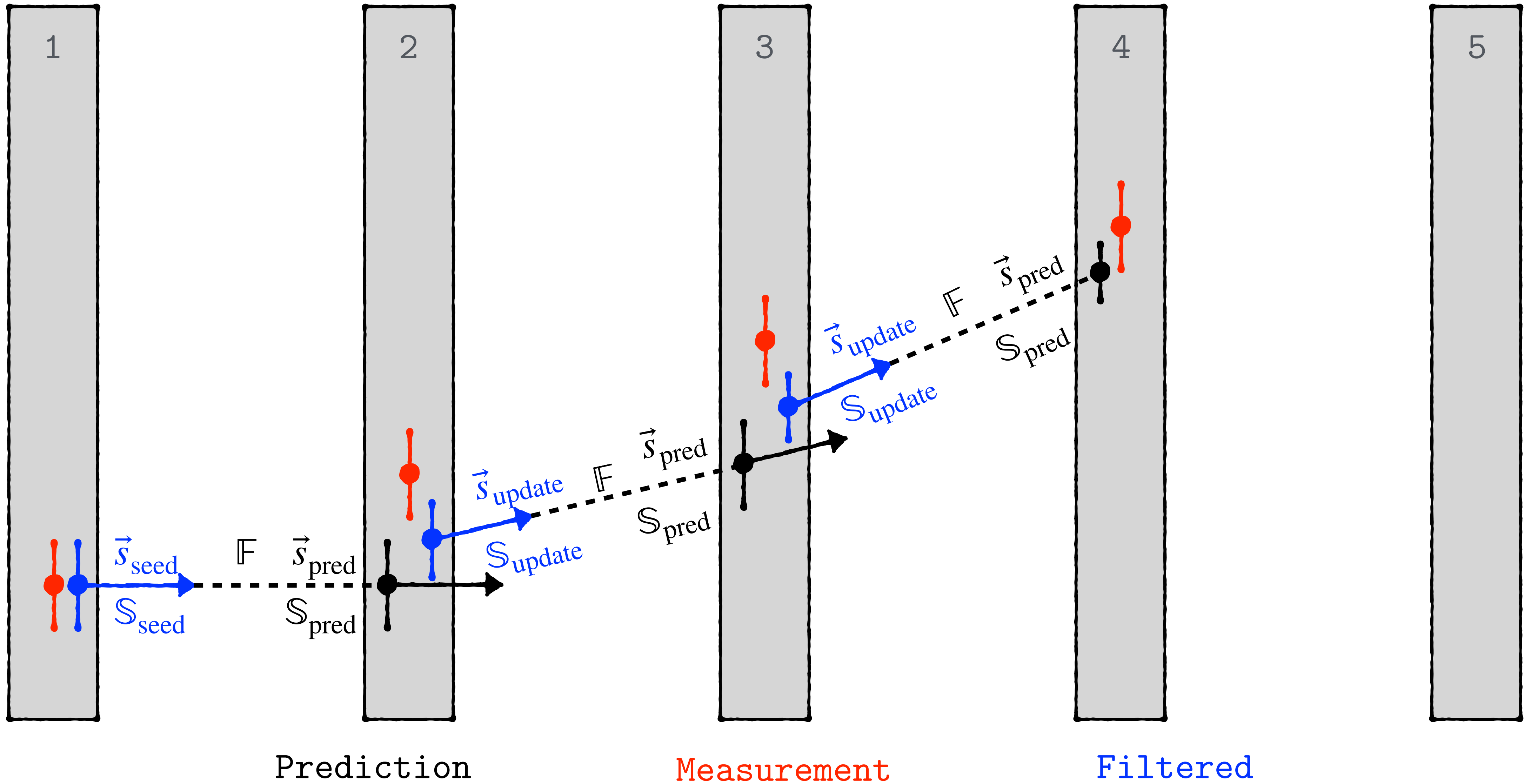


Track finding & reconstruction: Kalman Filter

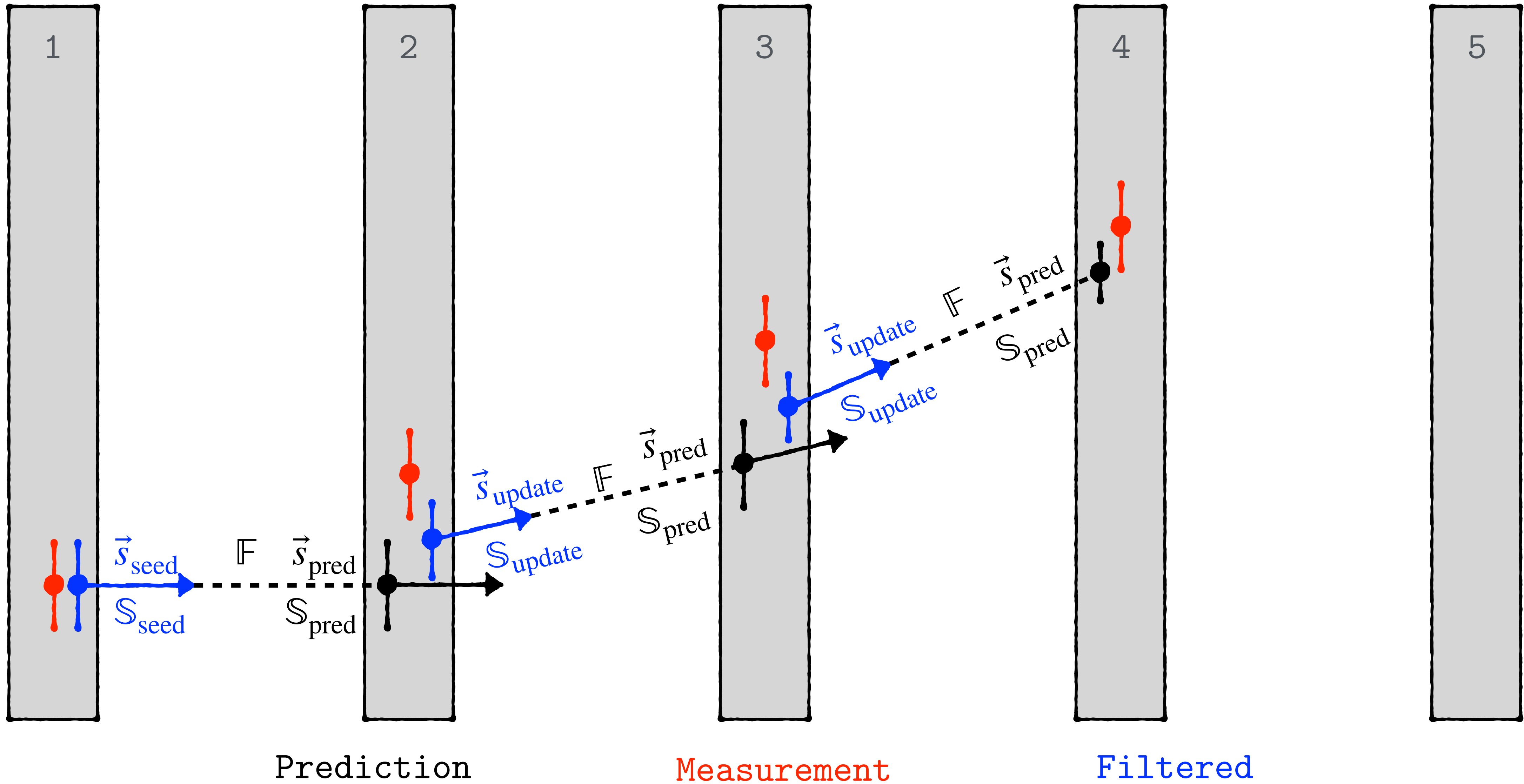
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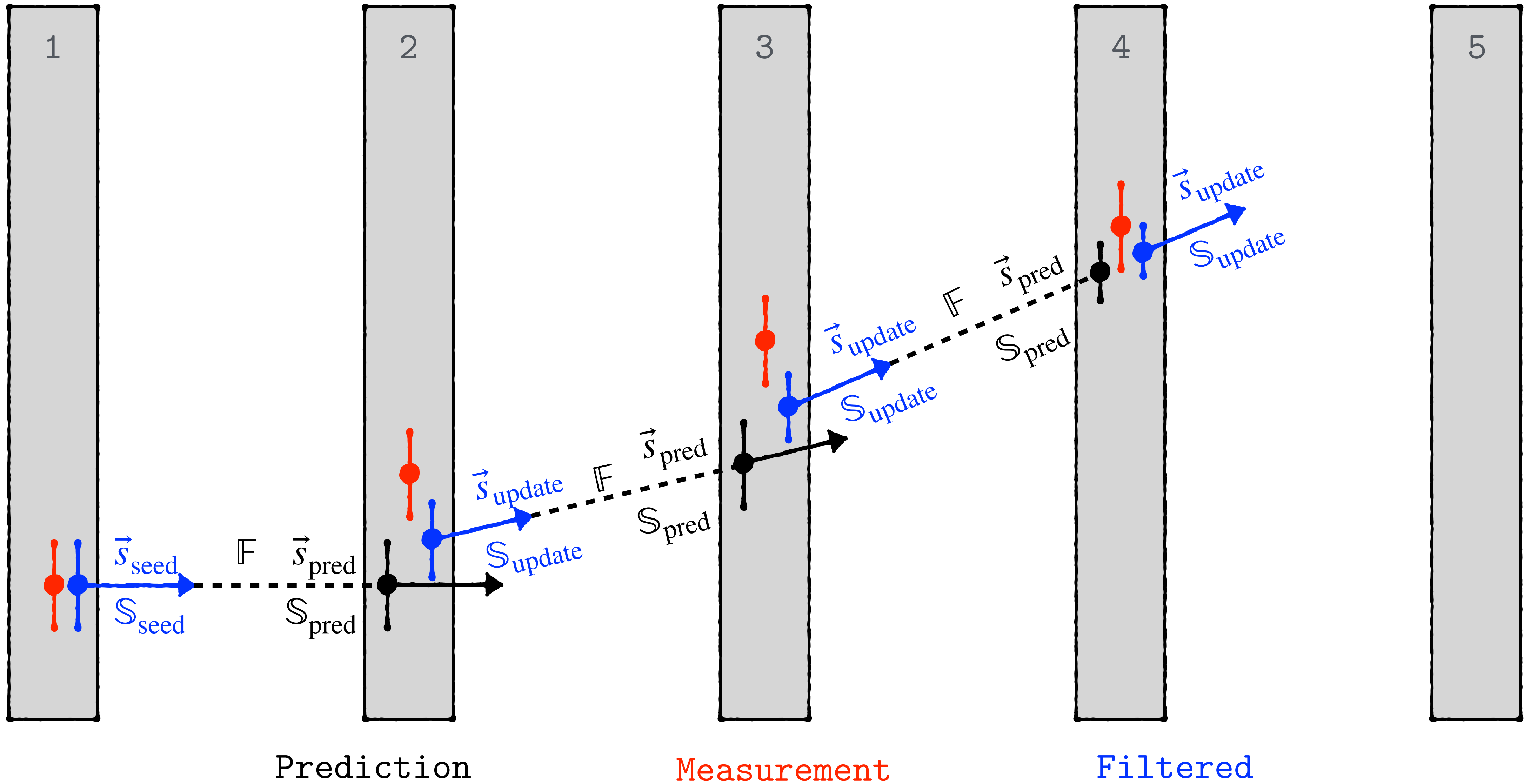
Track finding & reconstruction: Kalman Filter



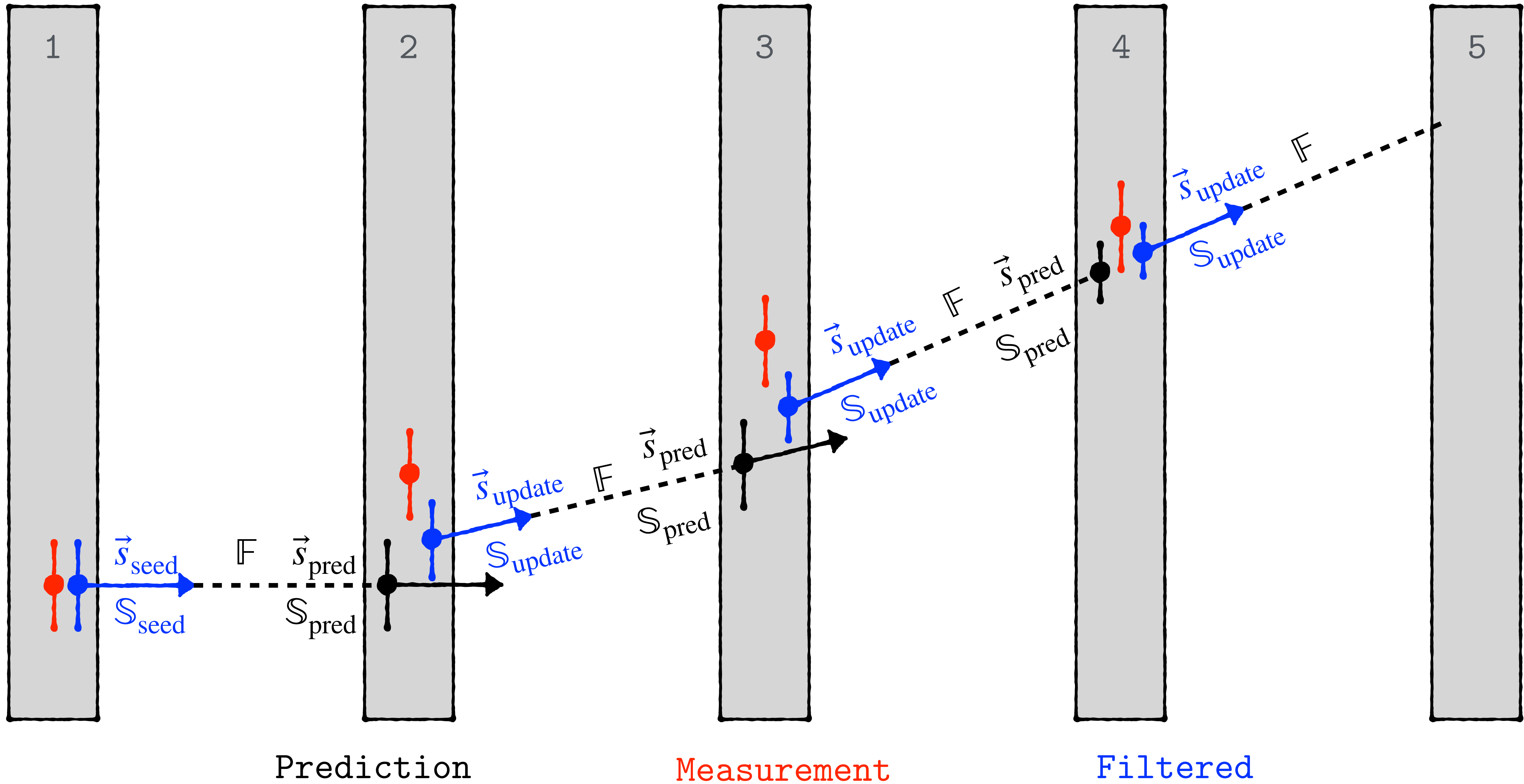
Track finding & reconstruction: Kalman Filter



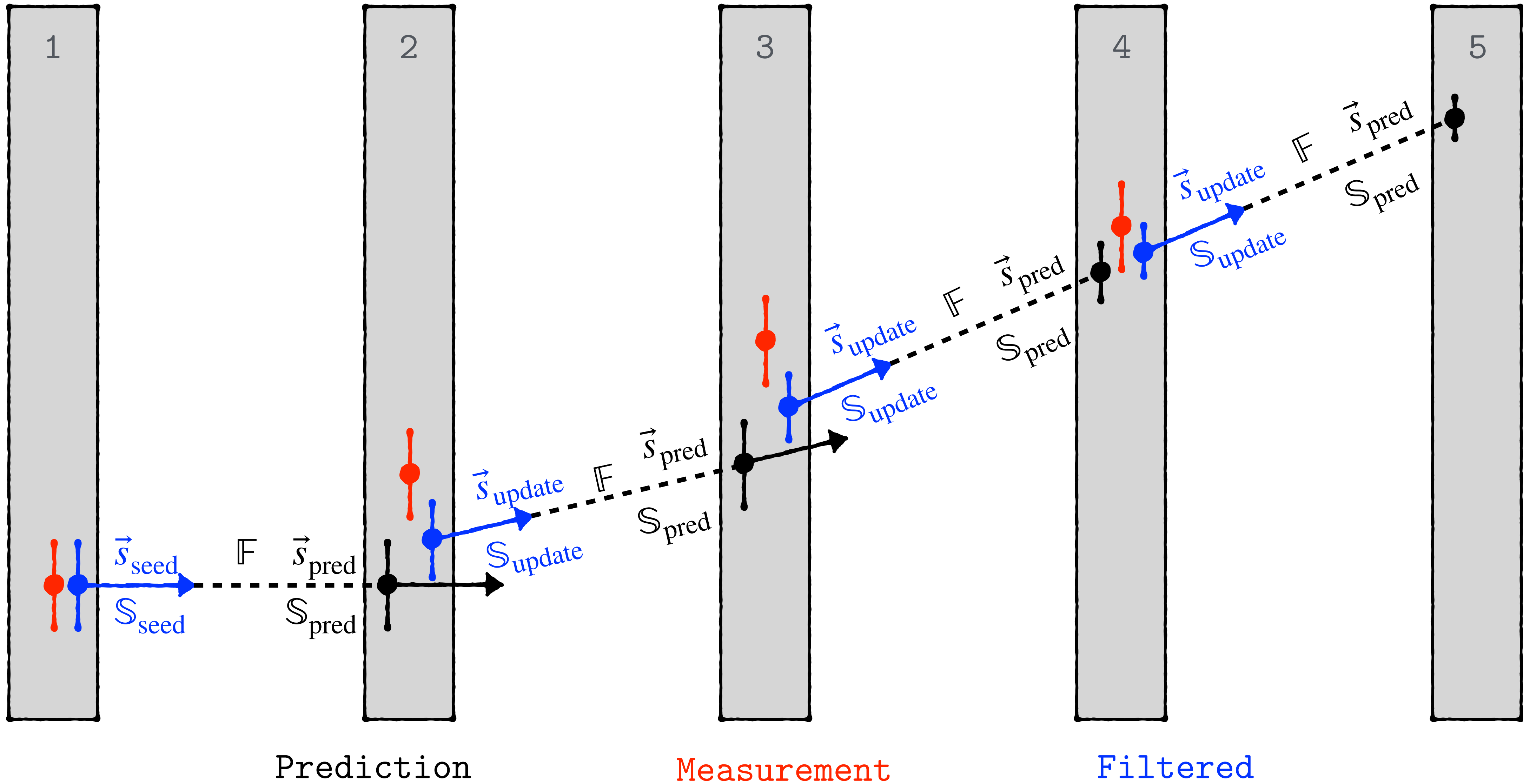
Track finding & reconstruction: Kalman Filter



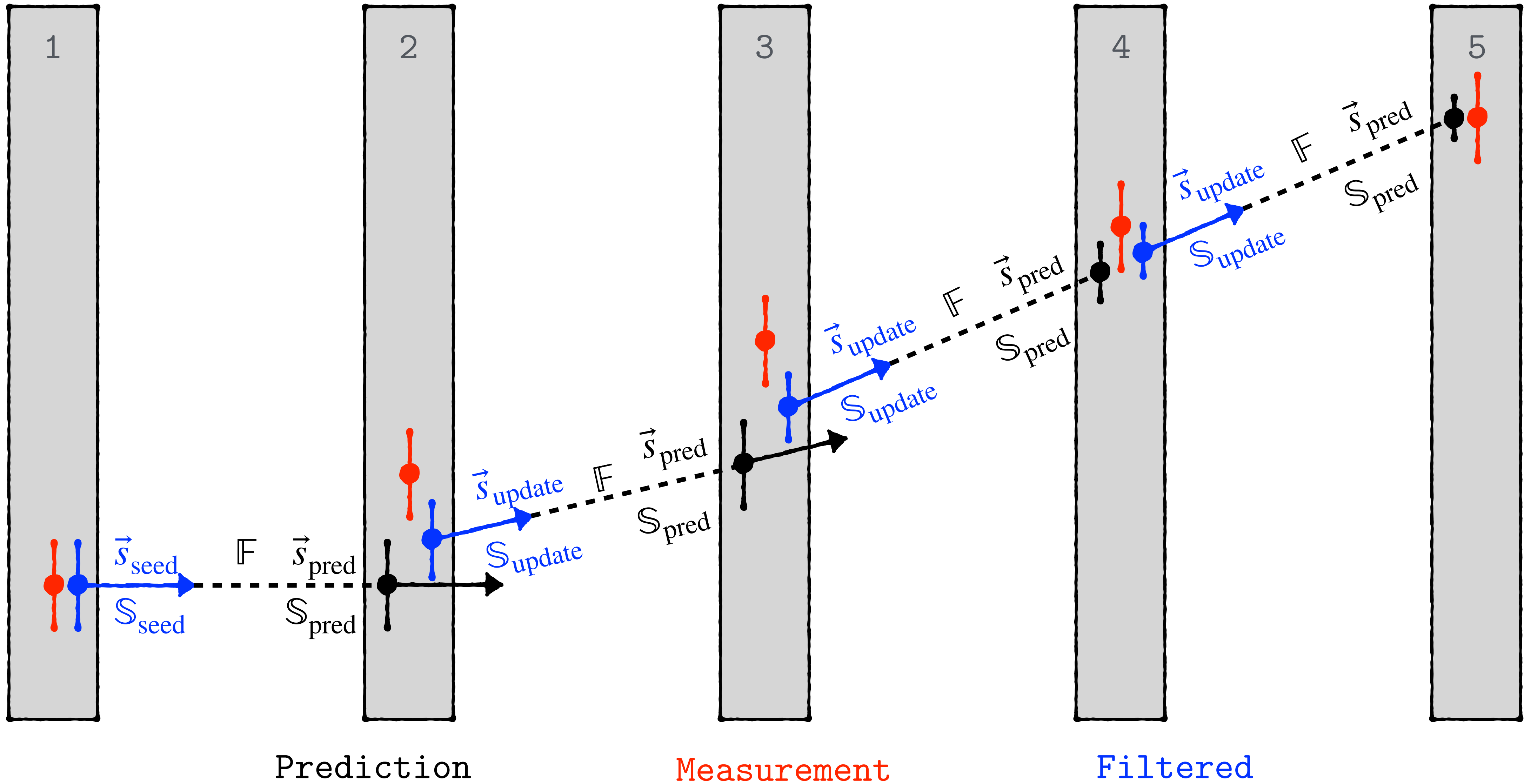
Track finding & reconstruction: Kalman Filter



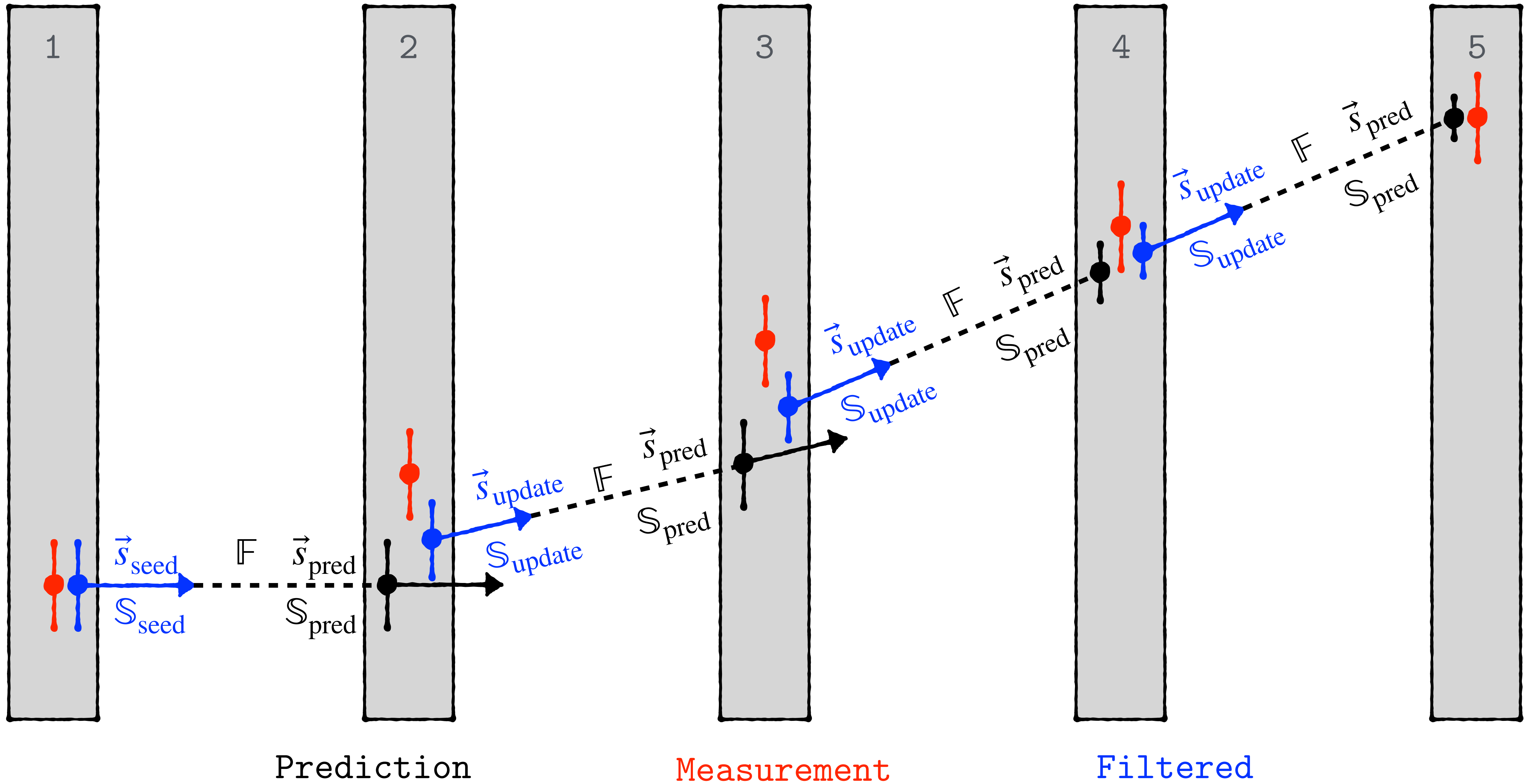
Track finding & reconstruction: Kalman Filter



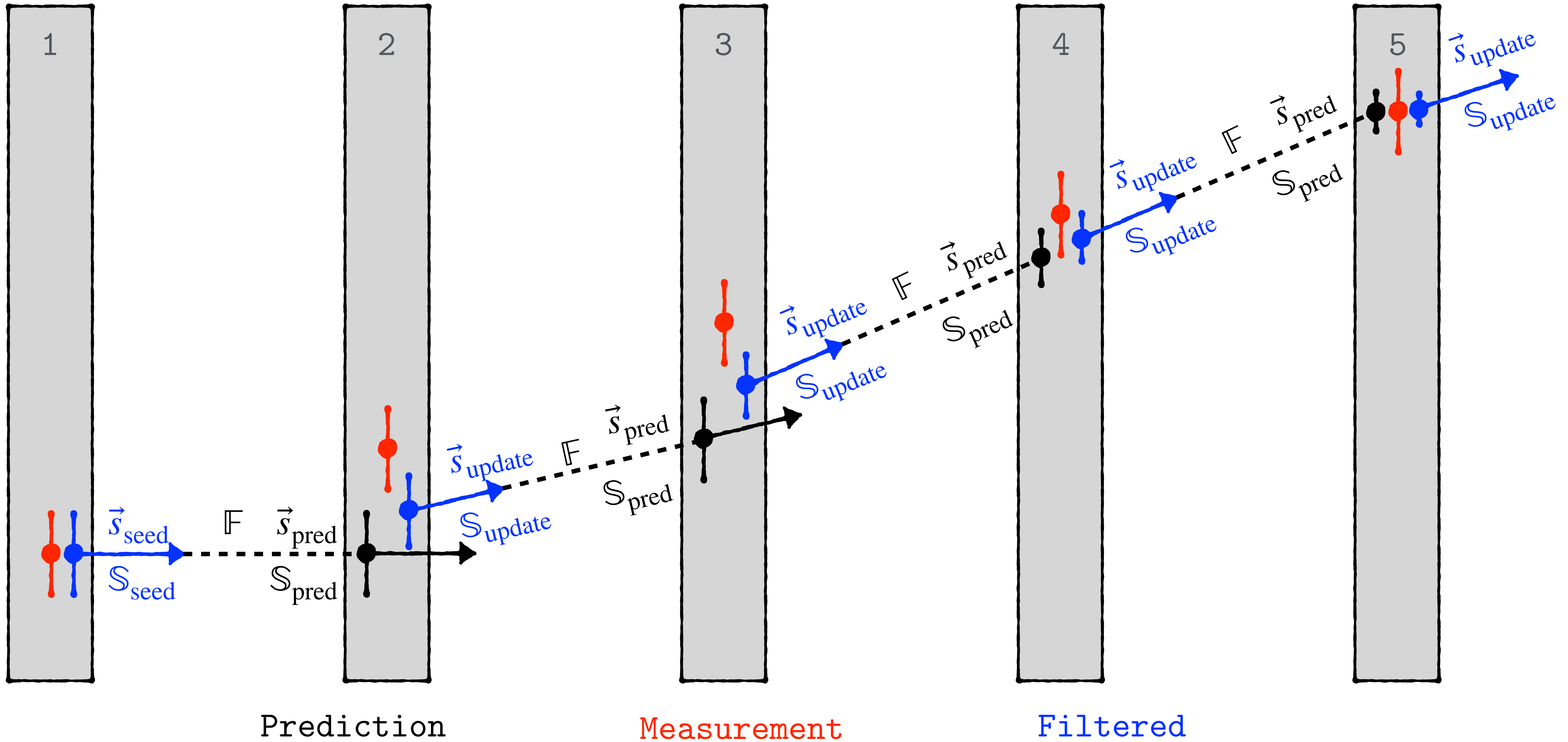
Track finding & reconstruction: Kalman Filter



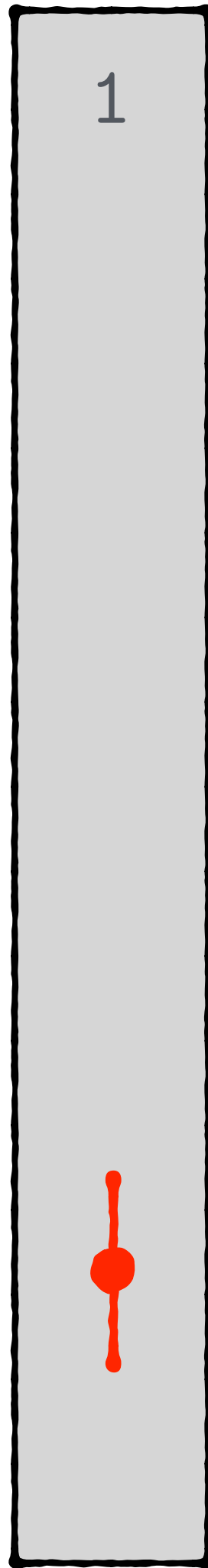
Track finding & reconstruction: Kalman Filter



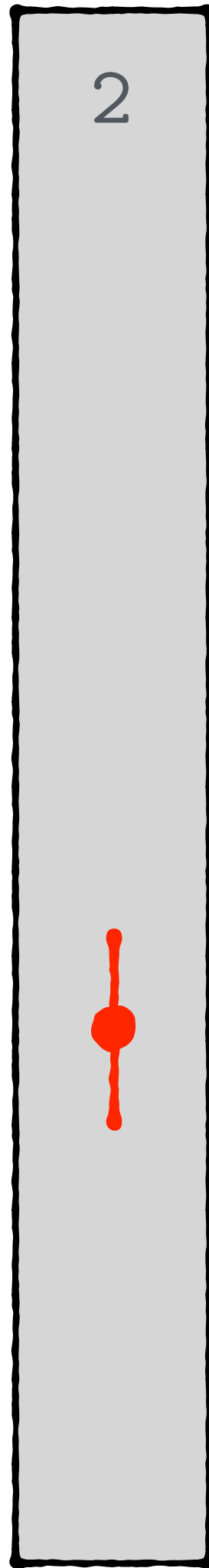
Track finding & reconstruction: Kalman Filter



Track finding & reconstruction: Kalman Filter



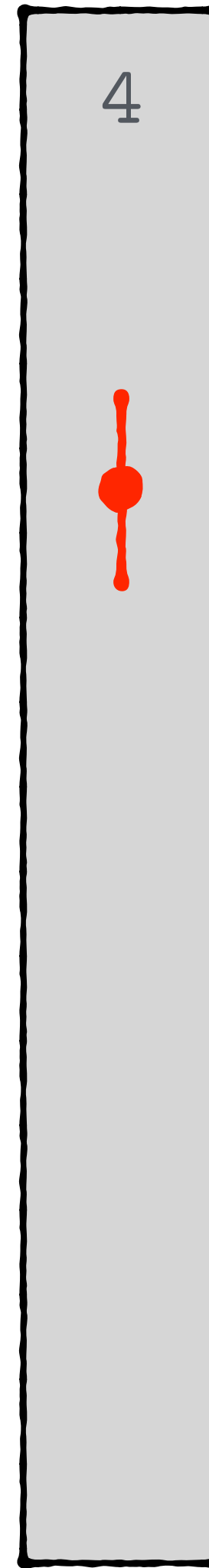
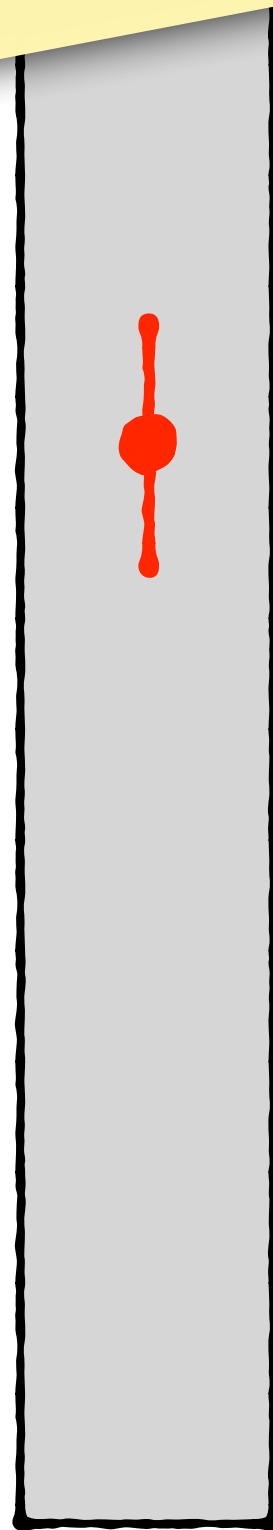
Prediction



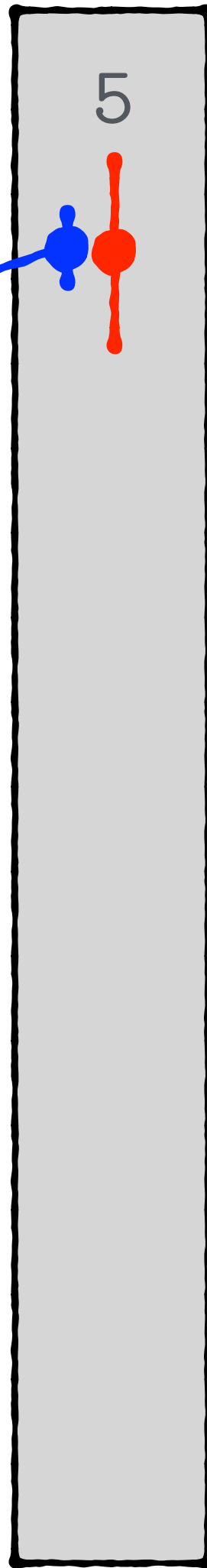
Measurement

Back-propagate
("smooth")

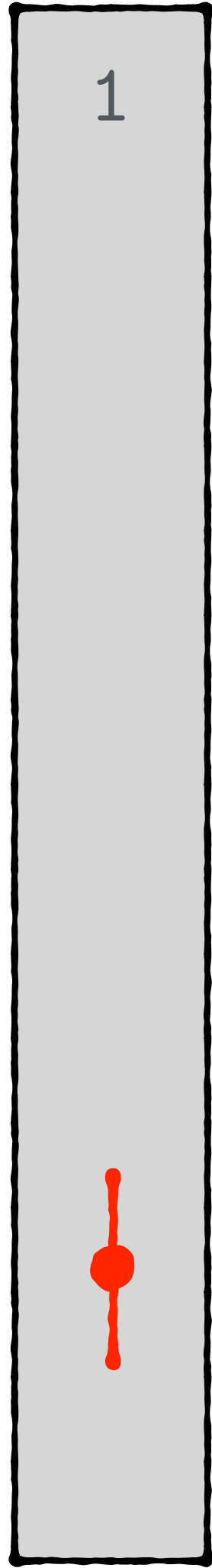
- Globally uses all measurement points



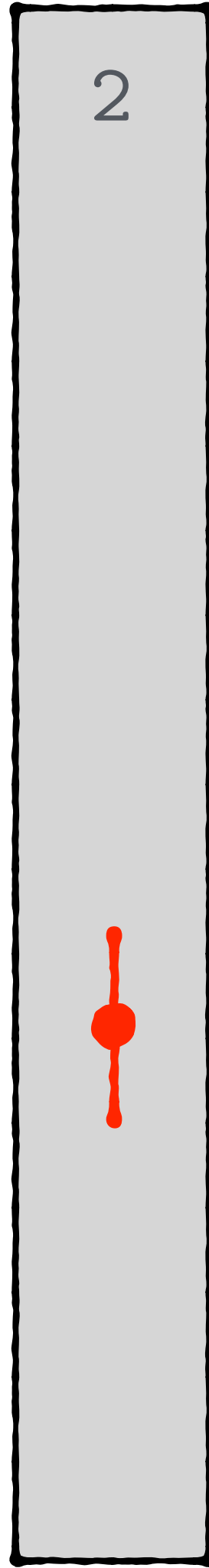
Smoothing



Track finding & reconstruction: Kalman Filter



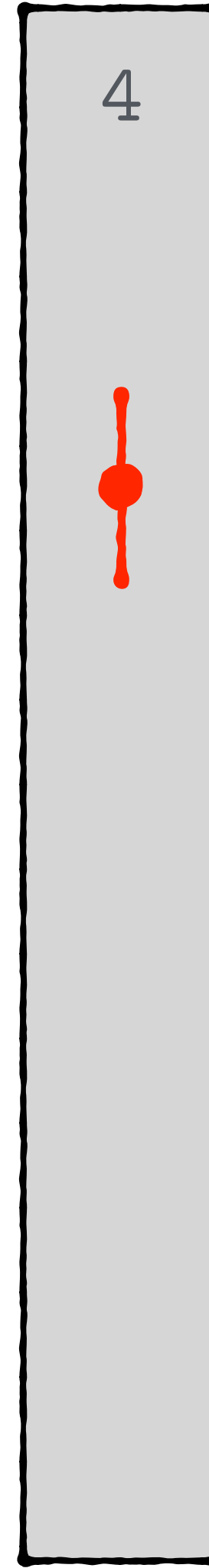
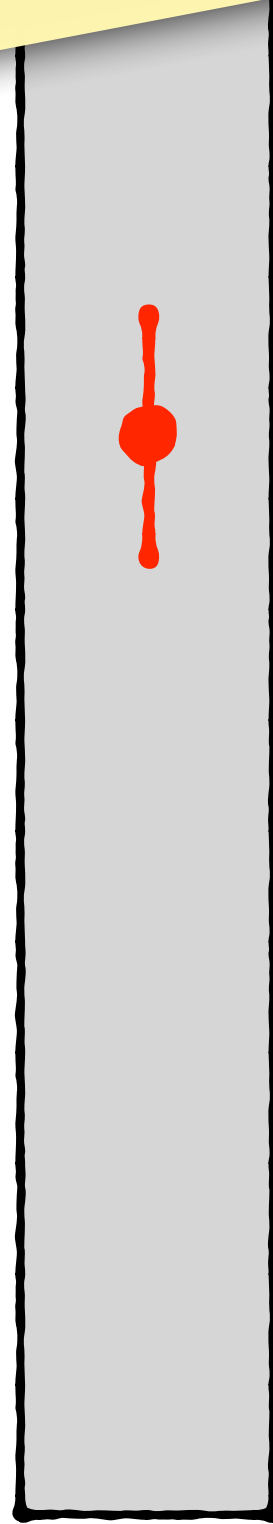
Prediction



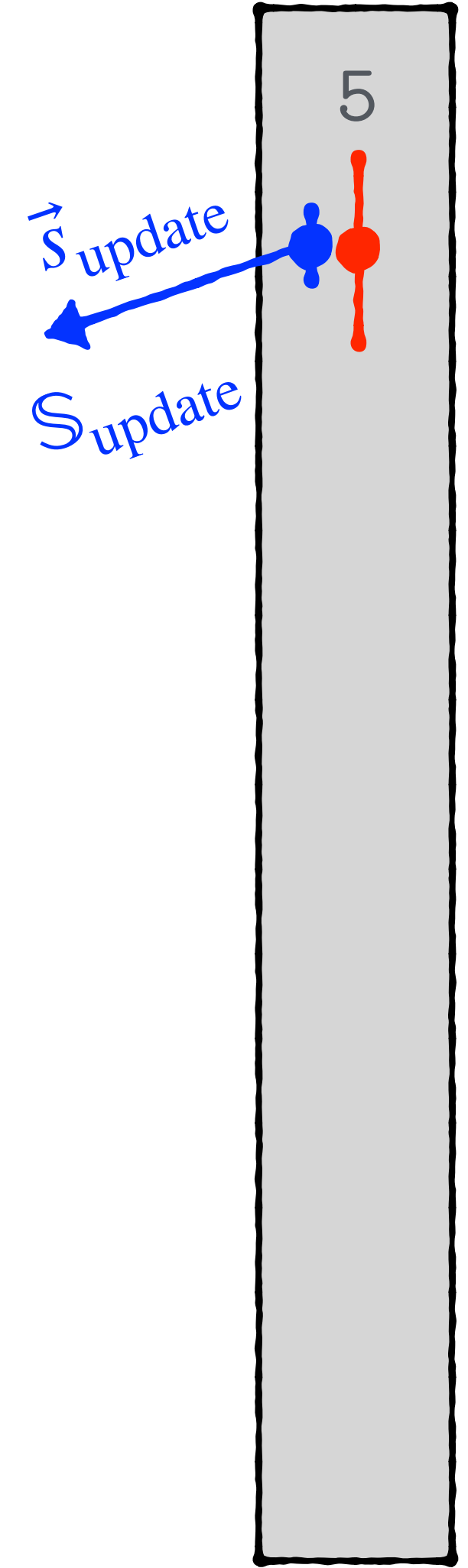
Measurement

Back-propagate
("smooth")

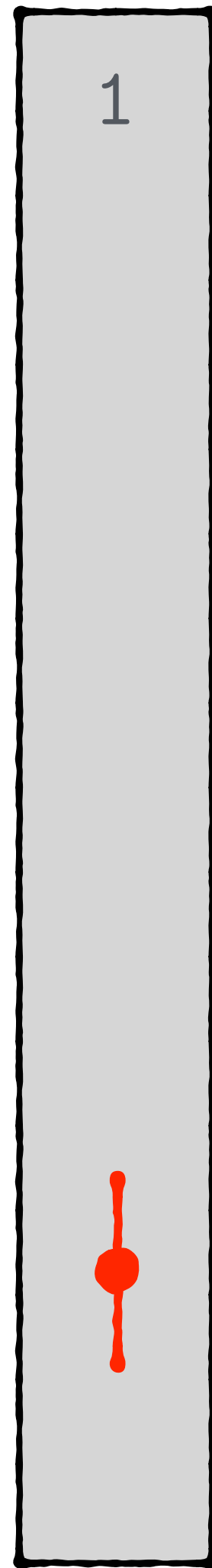
- Globally uses all measurement points



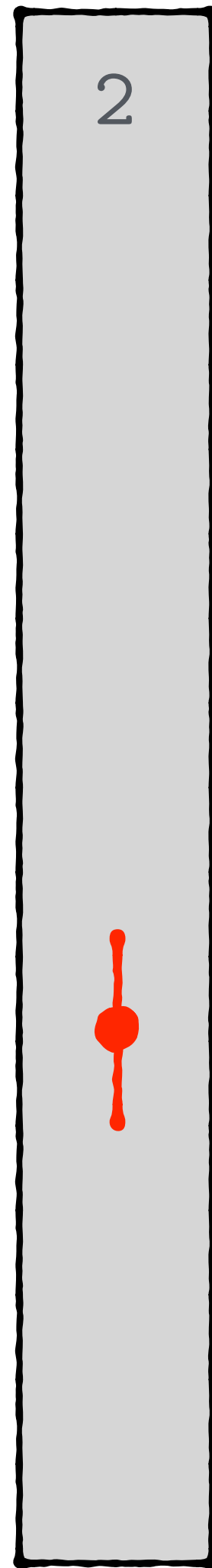
Smoothing



Track finding & reconstruction: Kalman Filter



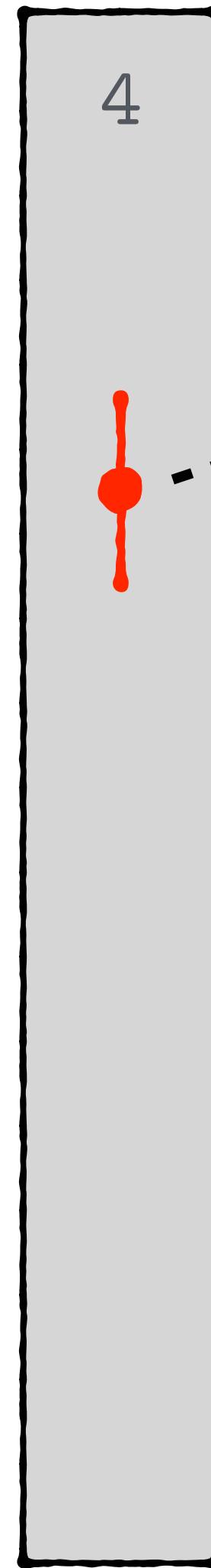
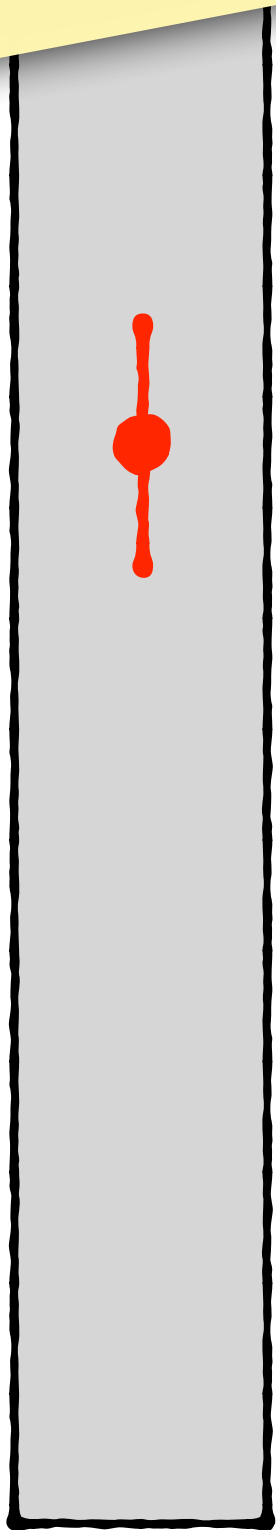
Prediction



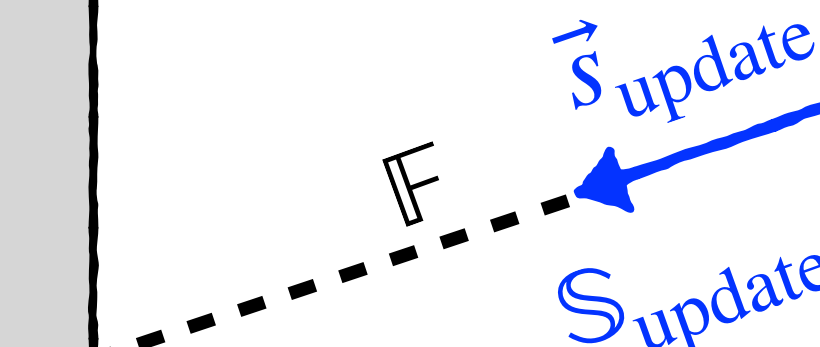
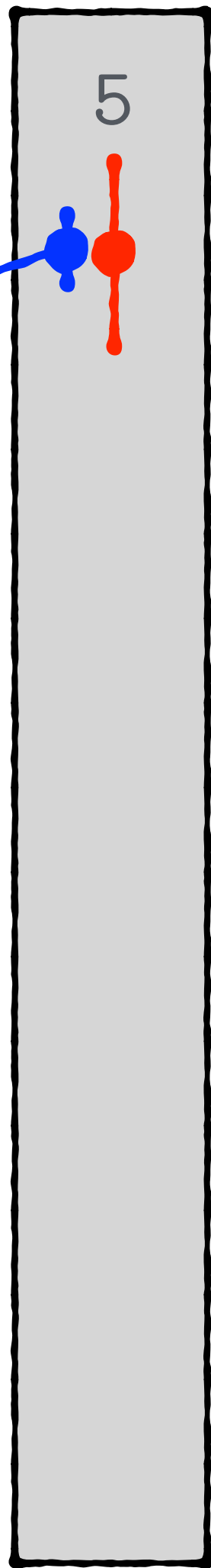
Measurement

Back-propagate
("smooth")

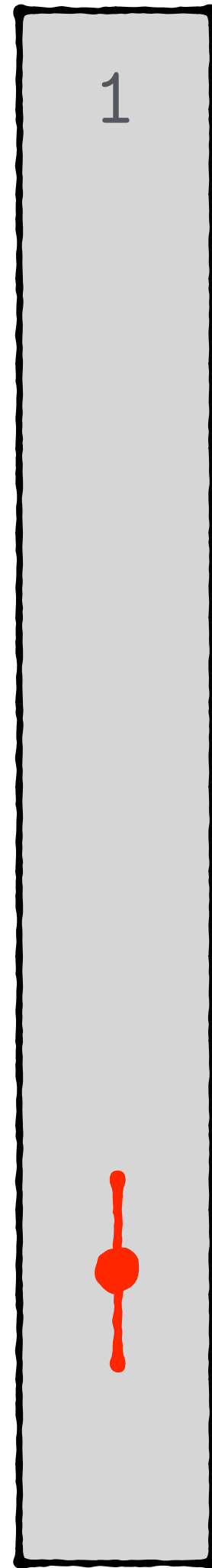
- Globally uses all measurement points



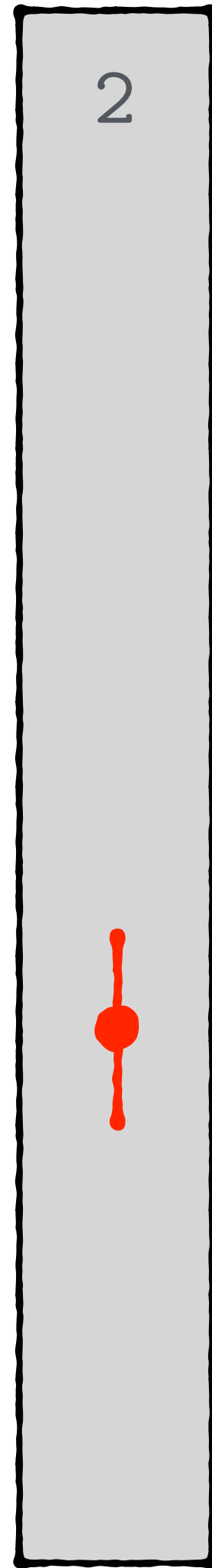
Smoothing



Track finding & reconstruction: Kalman Filter



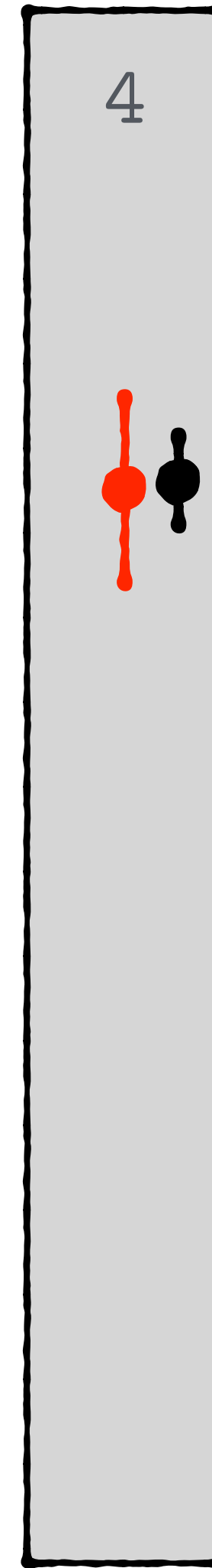
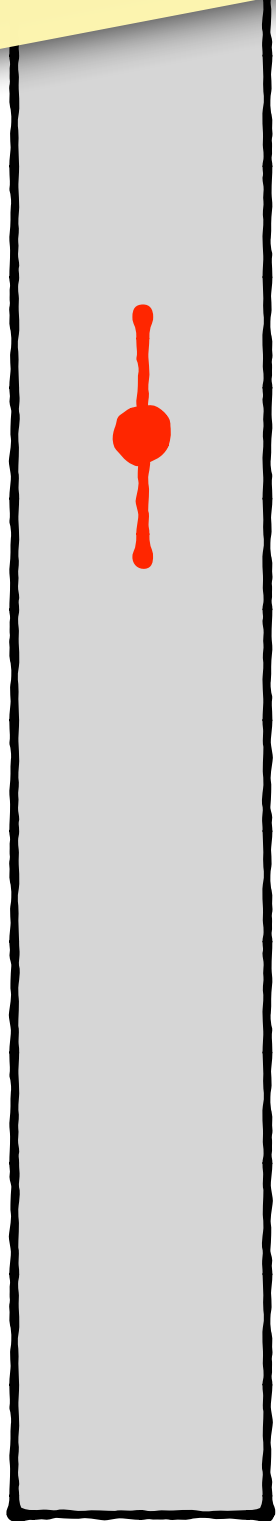
Prediction



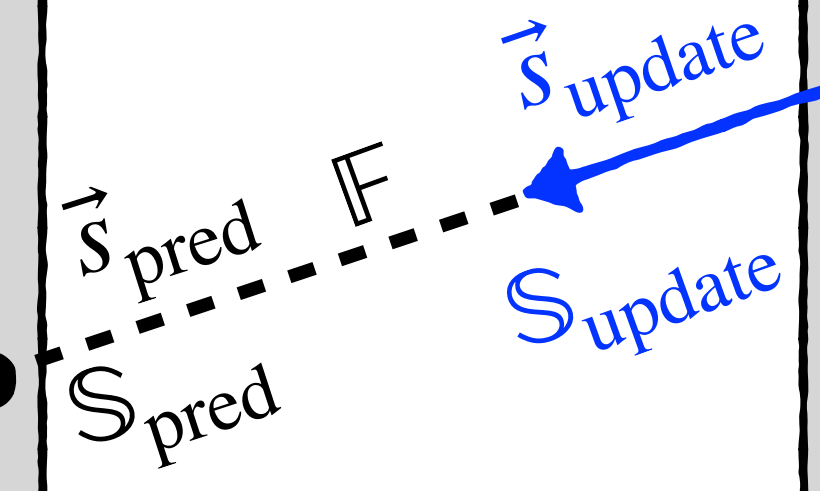
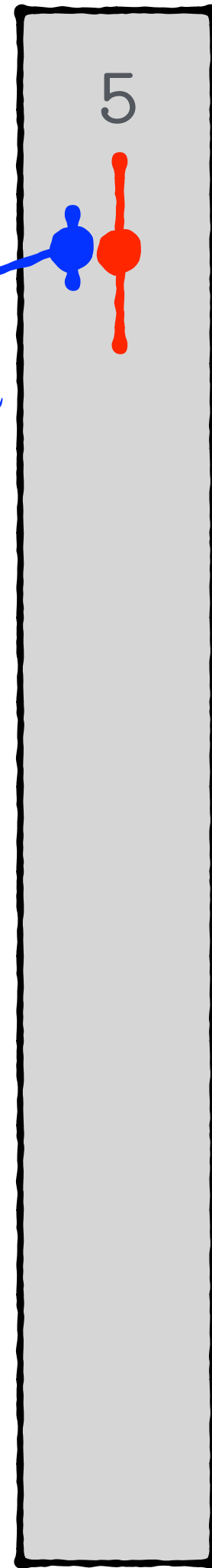
Measurement

Back-propagate ("smooth")

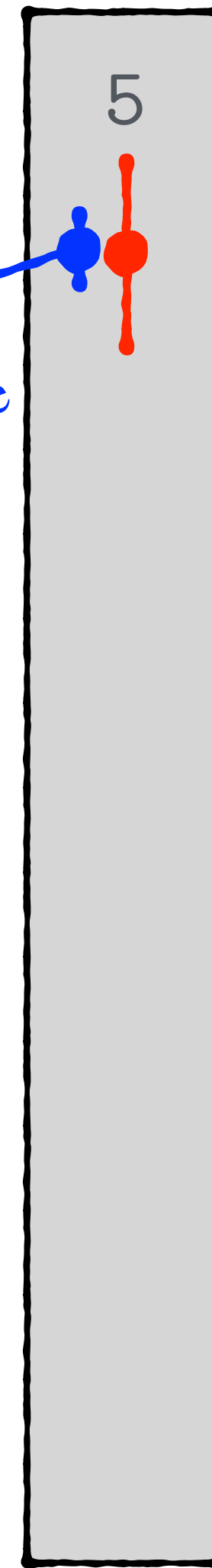
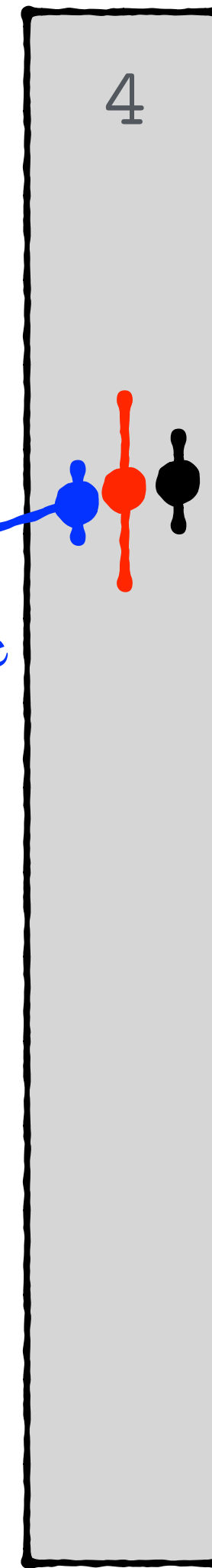
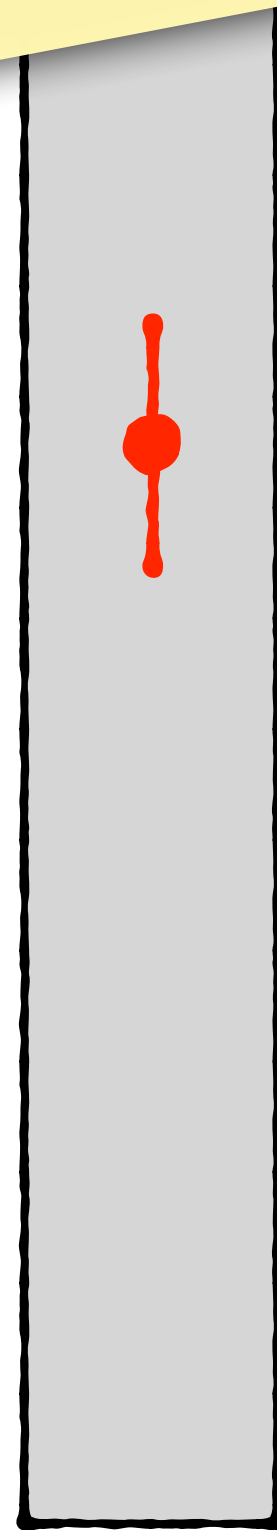
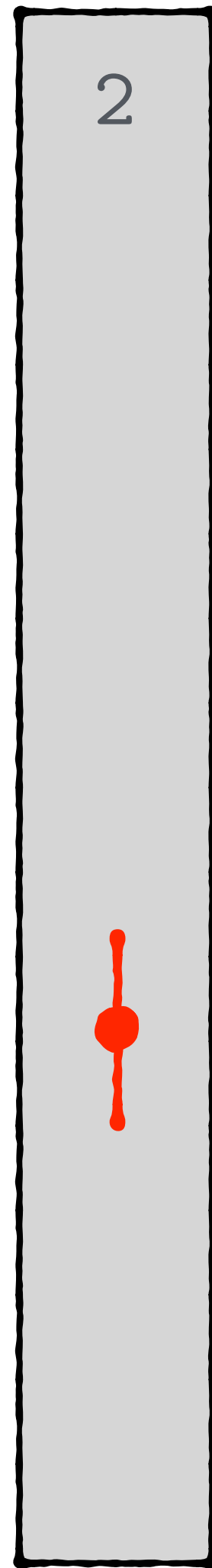
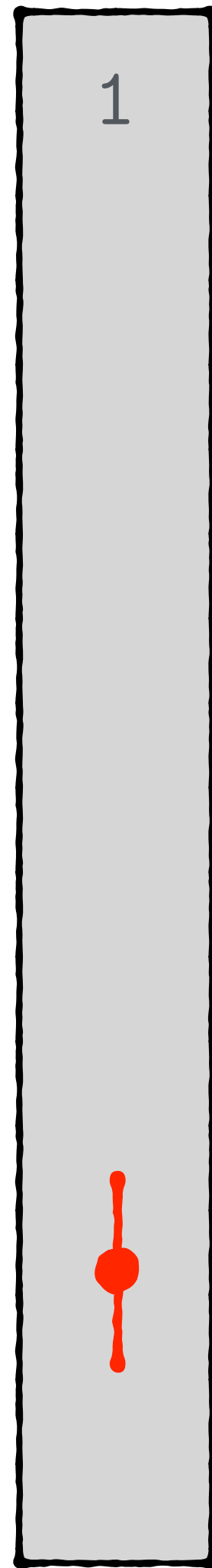
- Globally uses all measurement points



Smoothing



Track finding & reconstruction: Kalman Filter



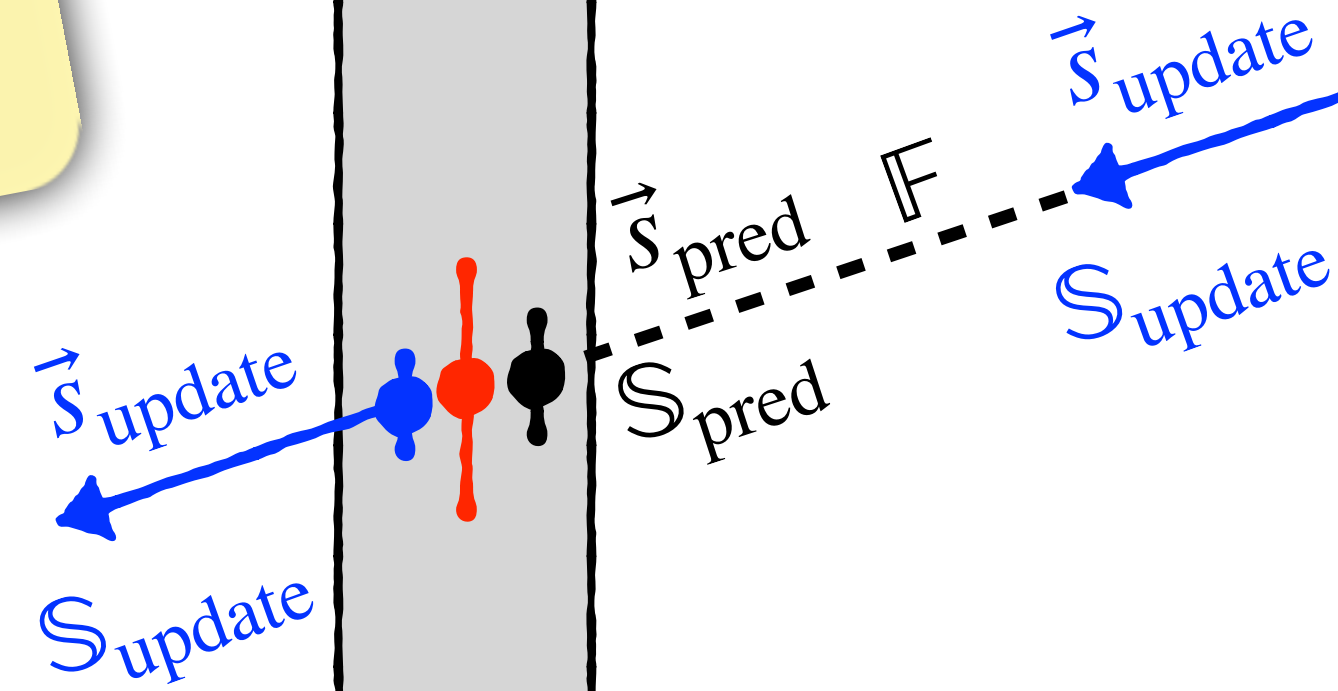
Prediction

Measurement

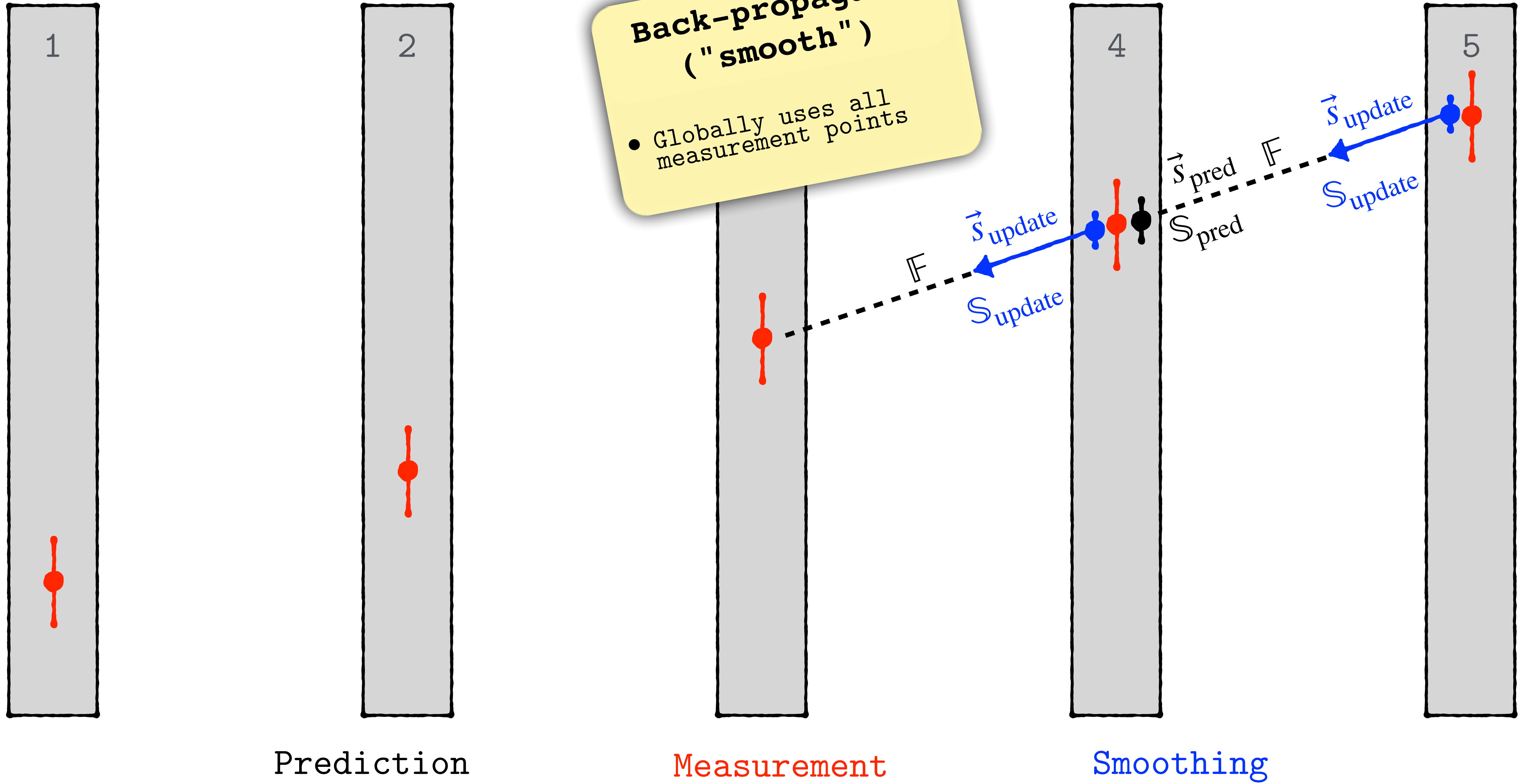
Smoothing

Back-propagate
("smooth")

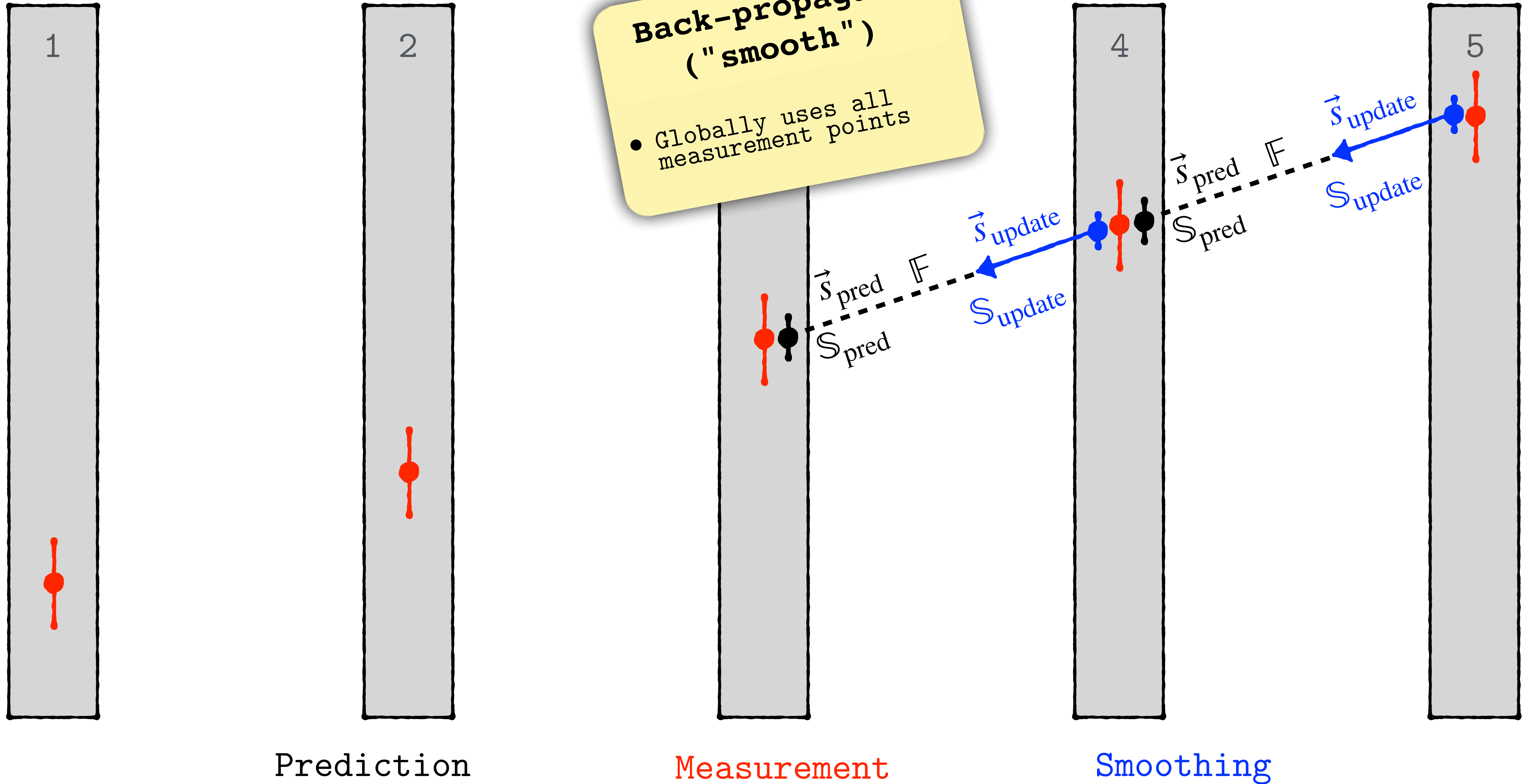
- Globally uses all measurement points



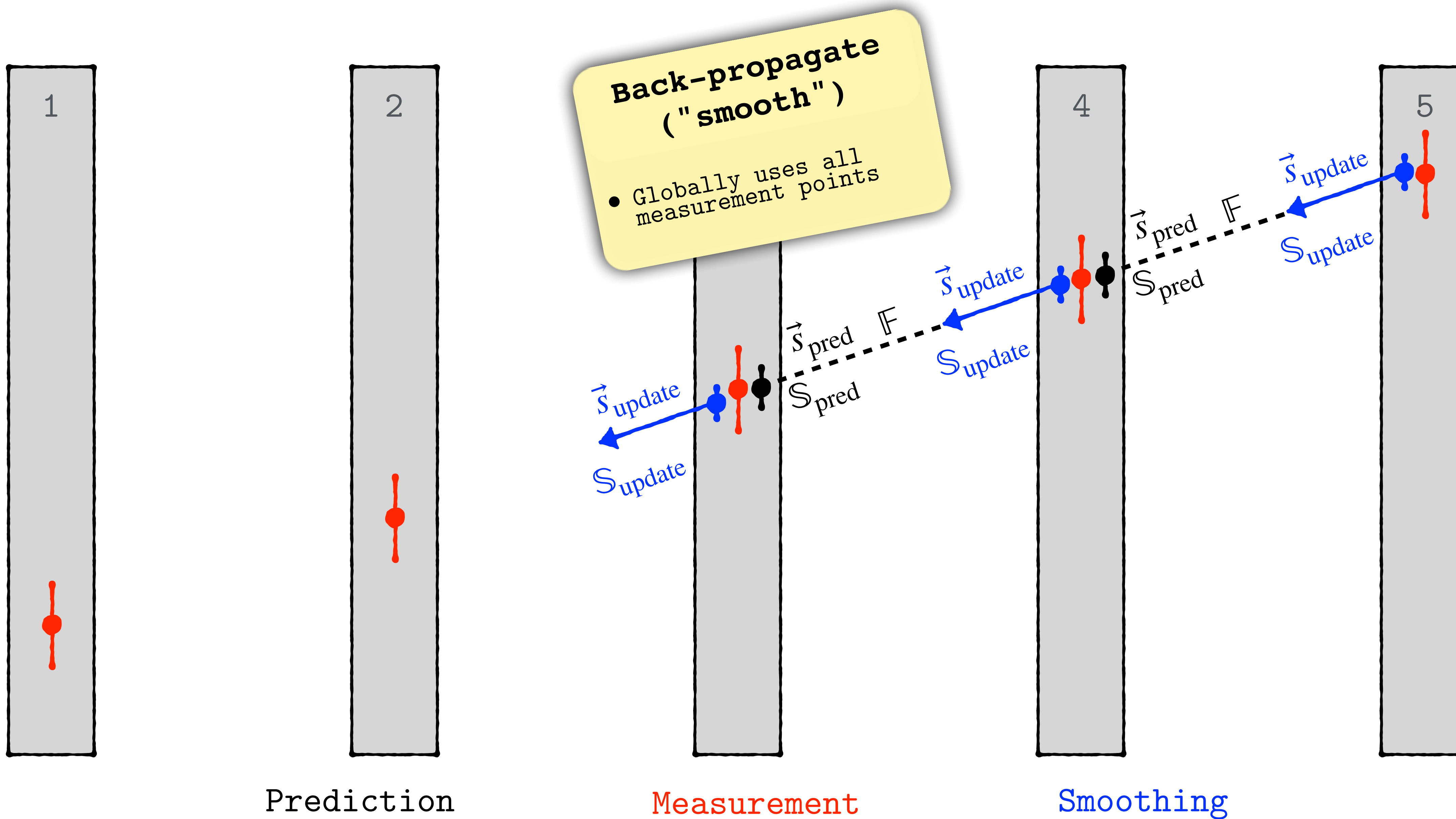
Track finding & reconstruction: Kalman Filter



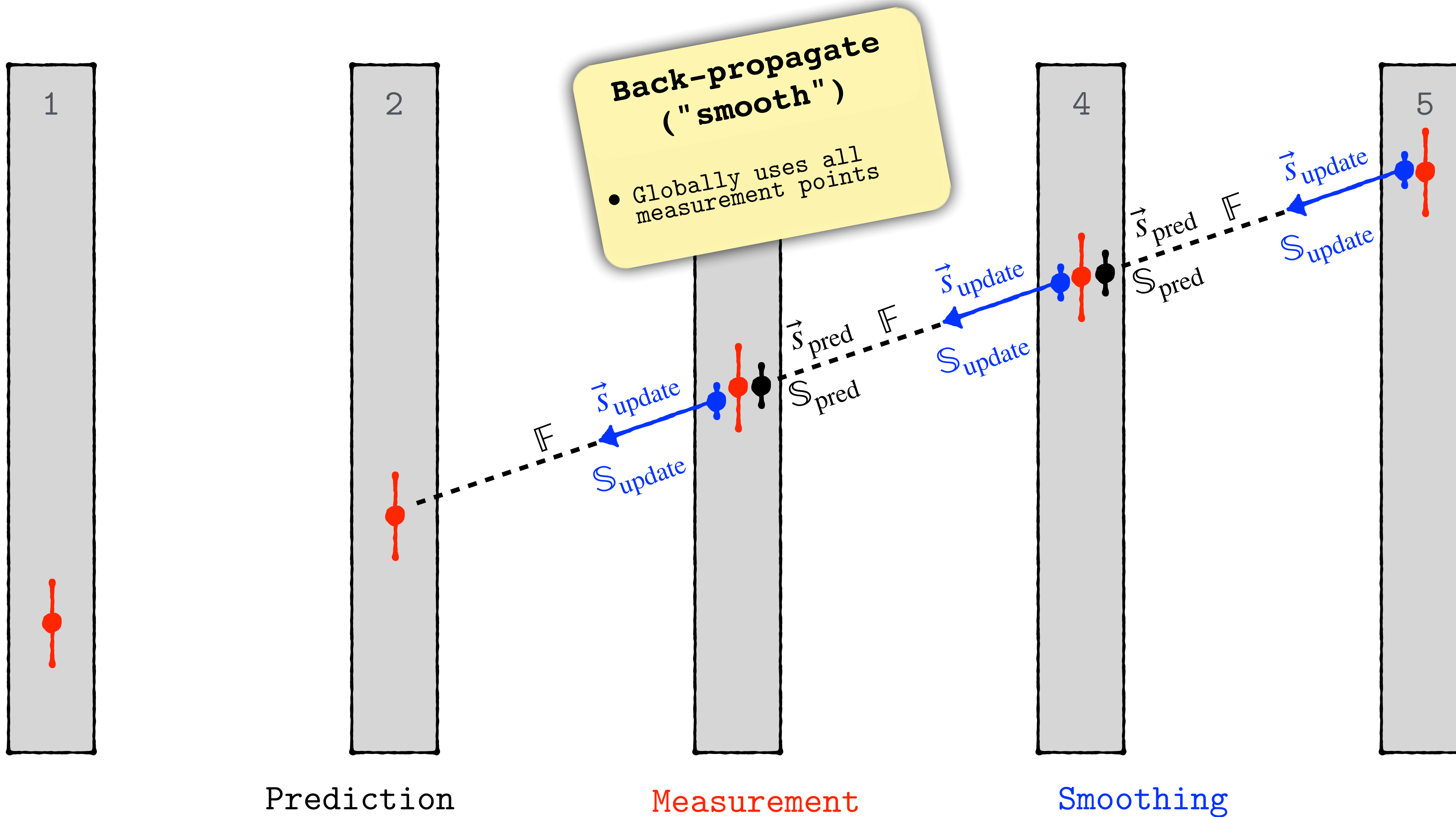
Track finding & reconstruction: Kalman Filter



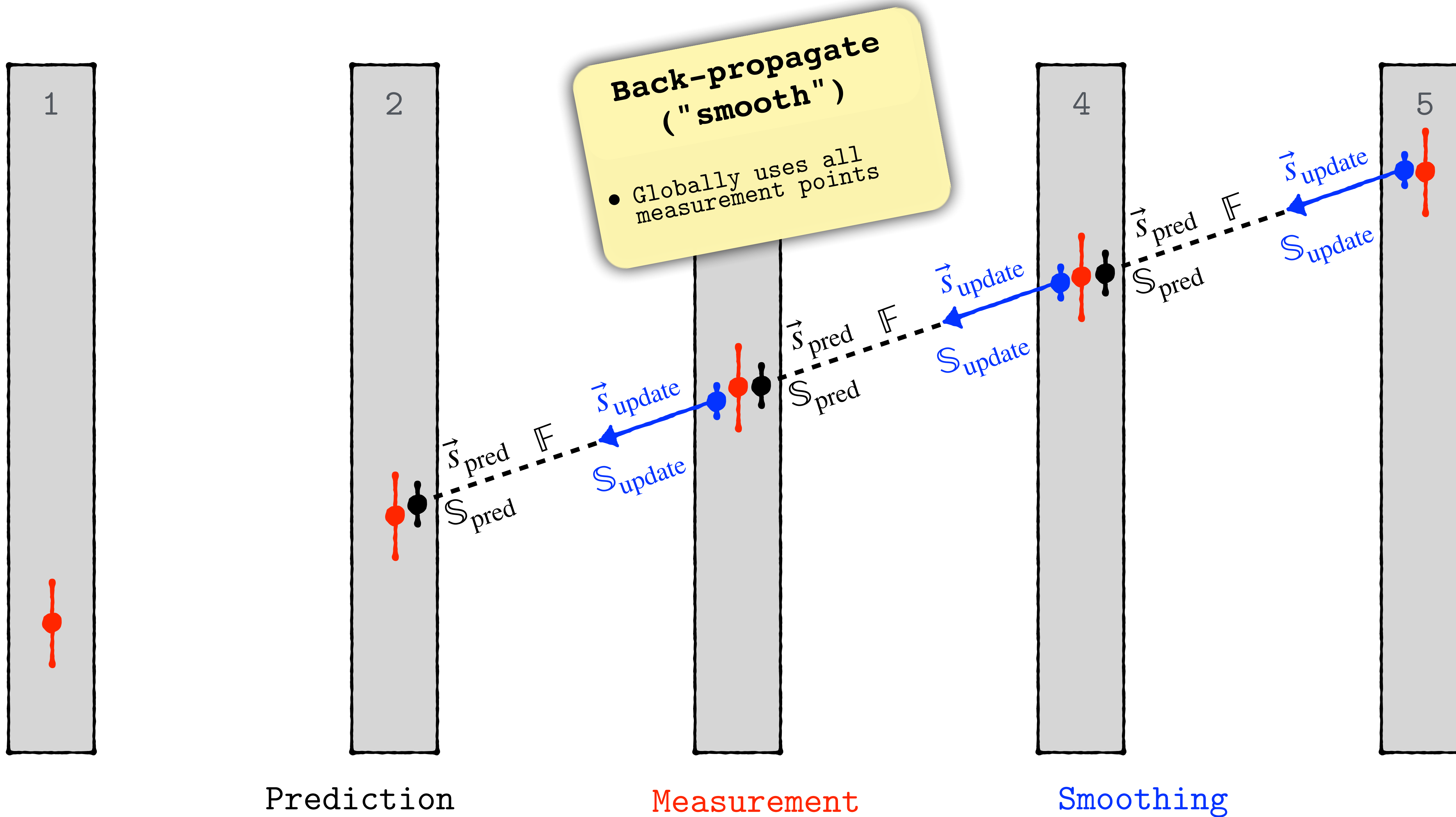
Track finding & reconstruction: Kalman Filter



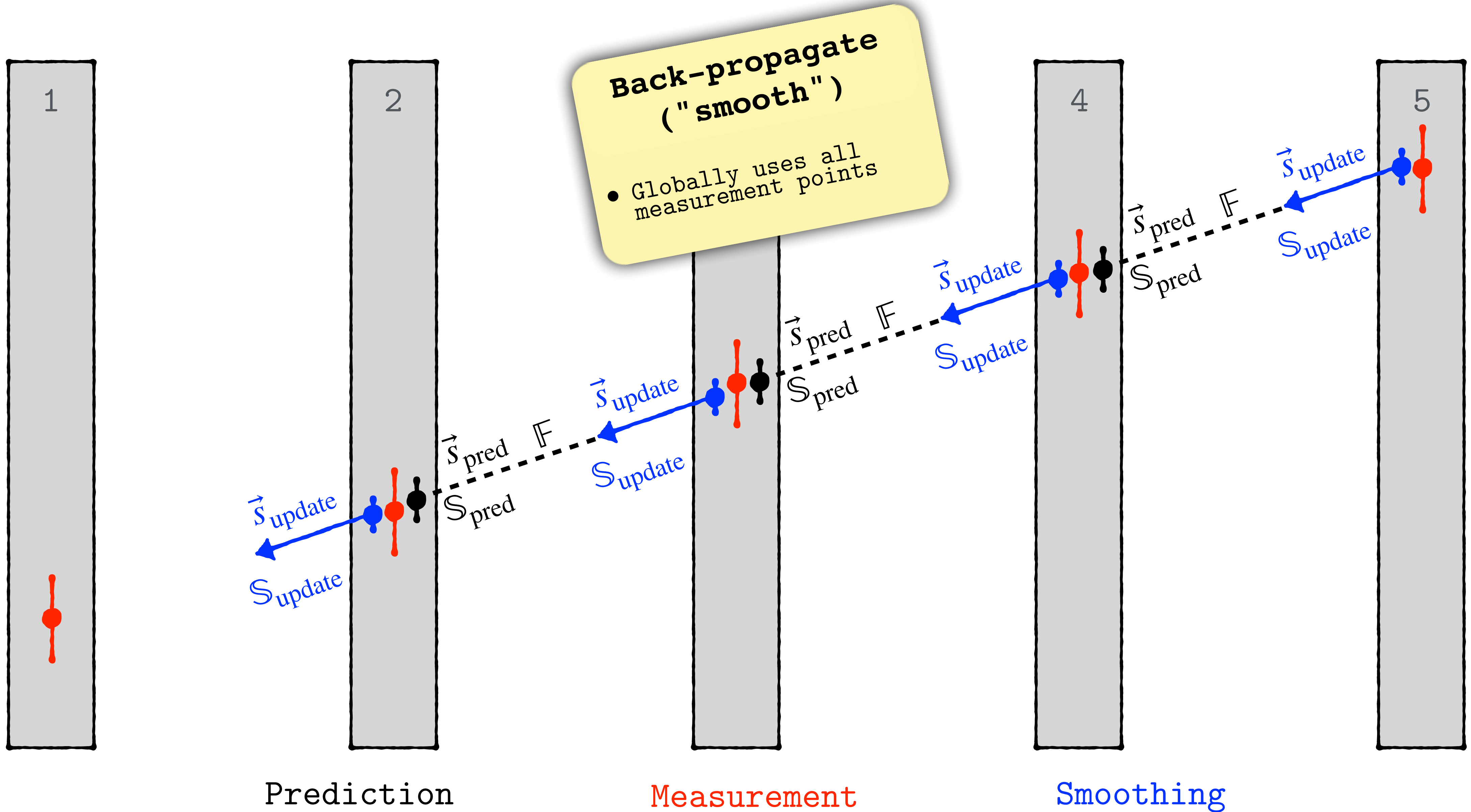
Track finding & reconstruction: Kalman Filter



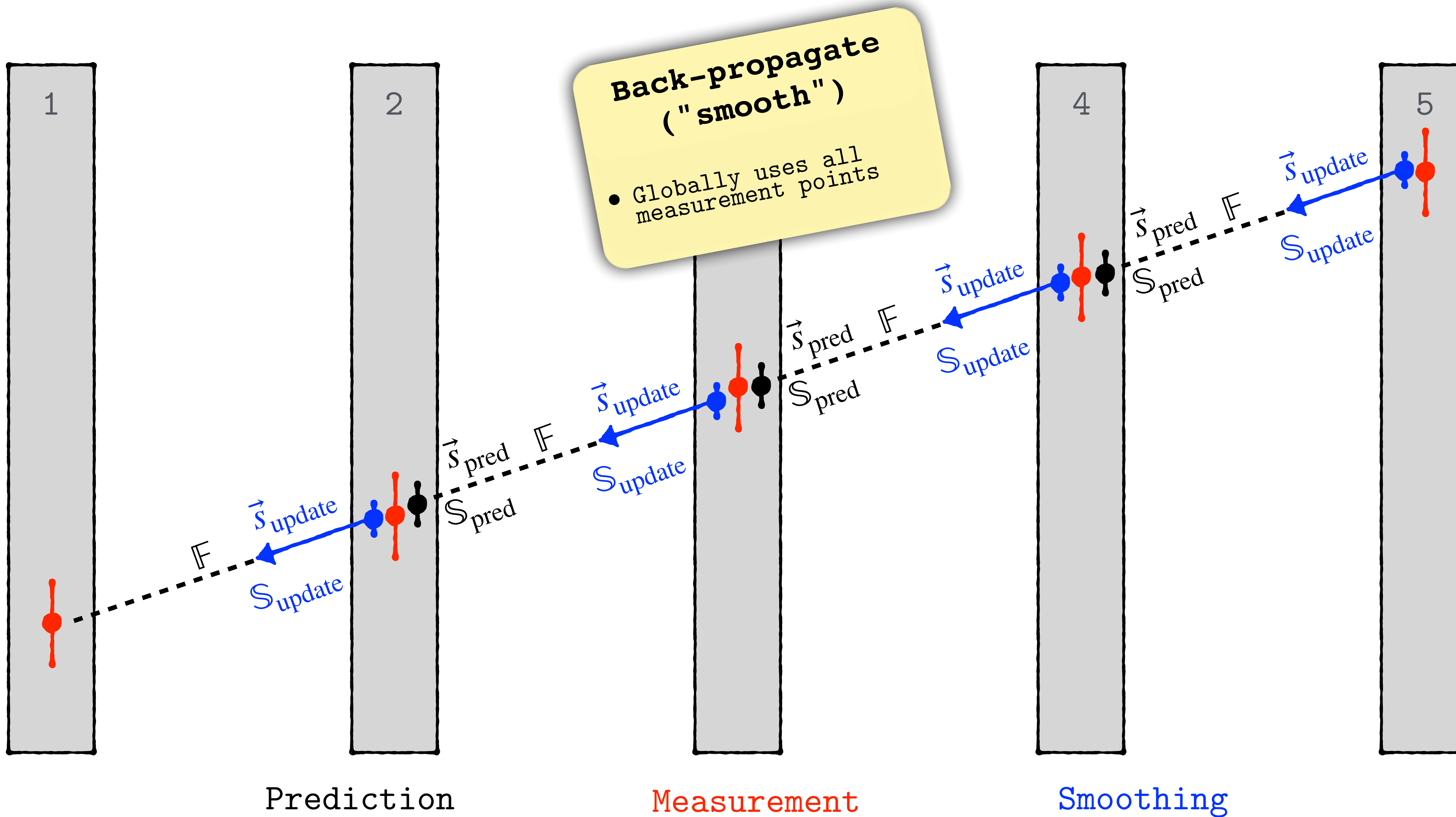
Track finding & reconstruction: Kalman Filter



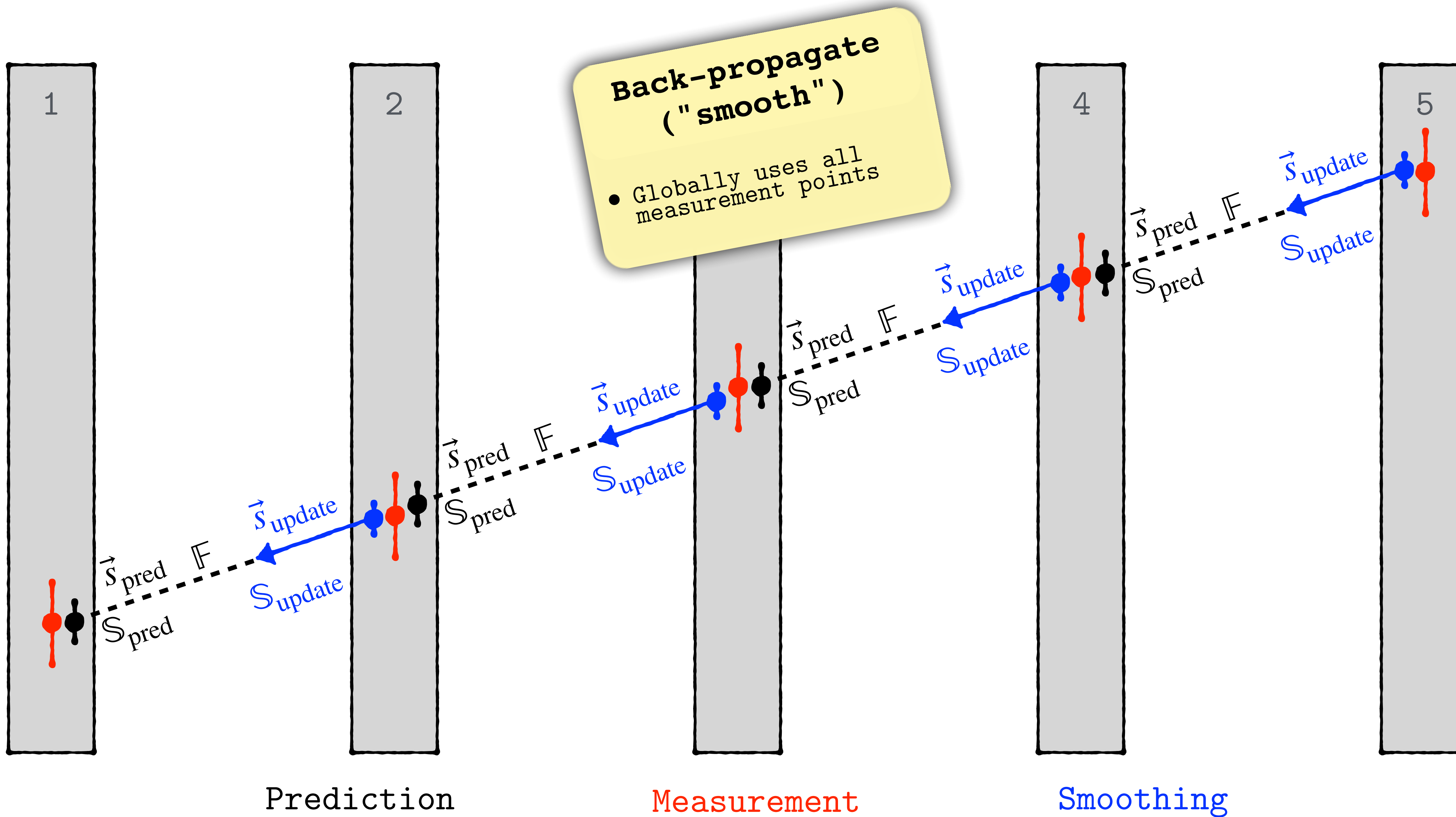
Track finding & reconstruction: Kalman Filter



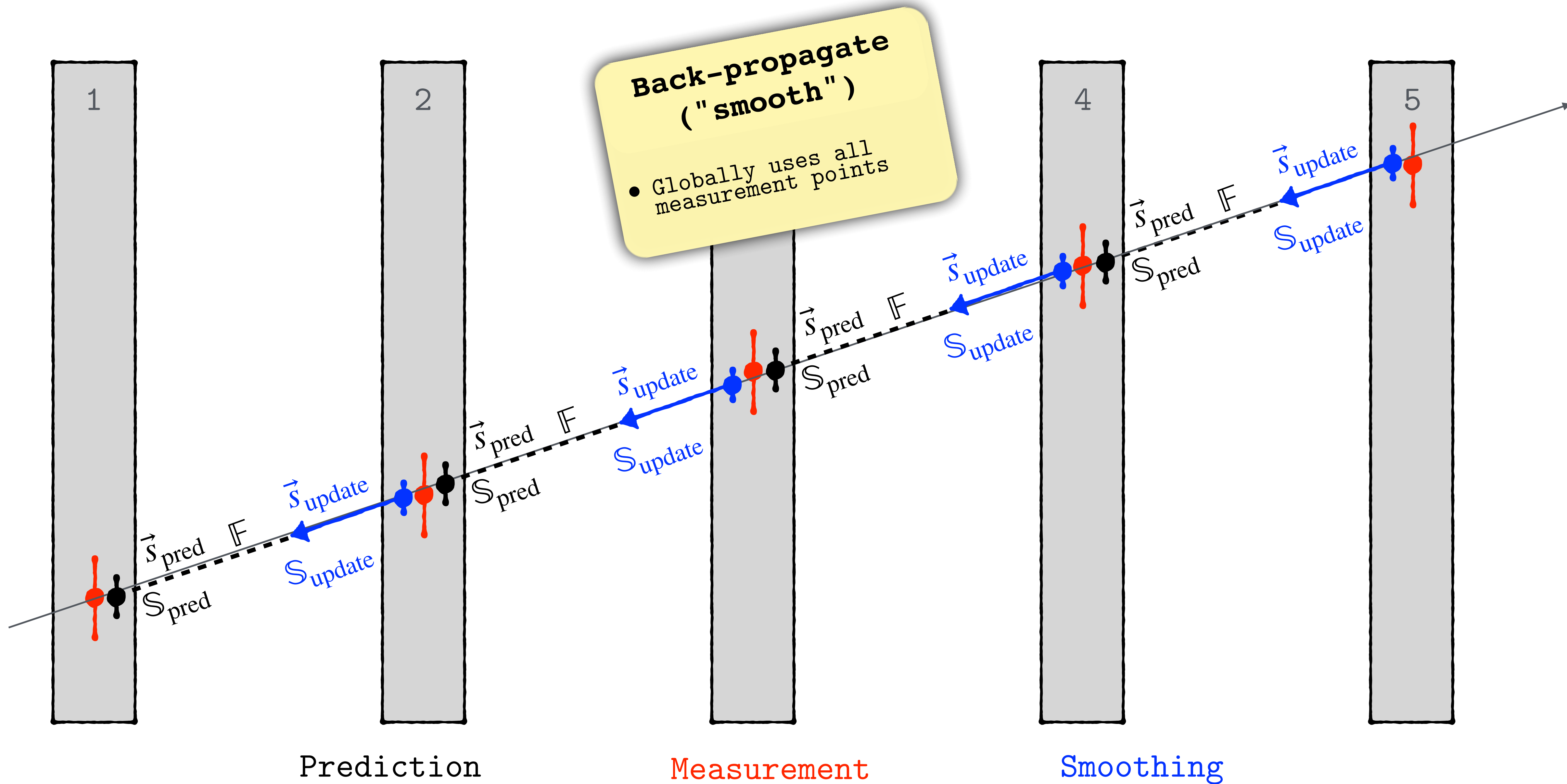
Track finding & reconstruction: Kalman Filter



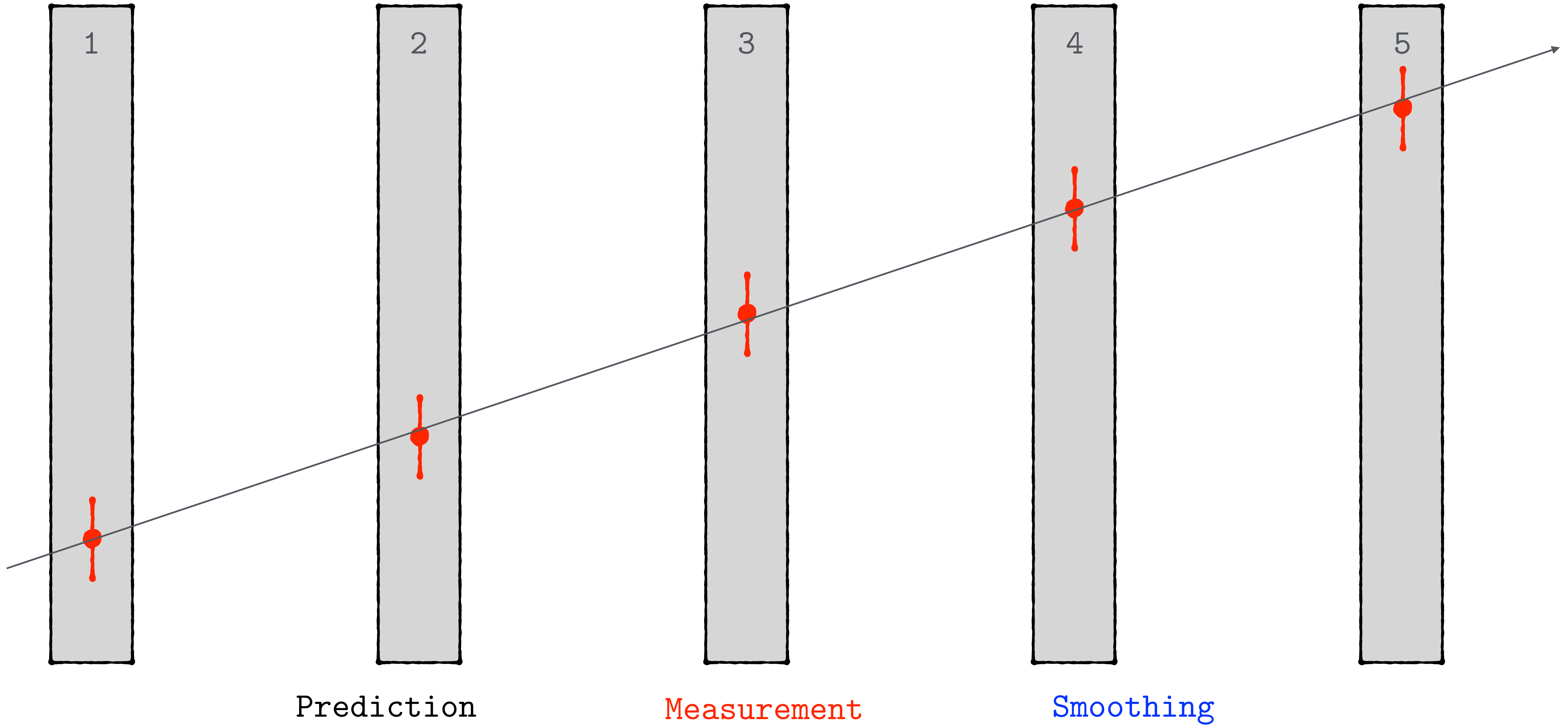
Track finding & reconstruction: Kalman Filter



Track finding & reconstruction: Kalman Filter



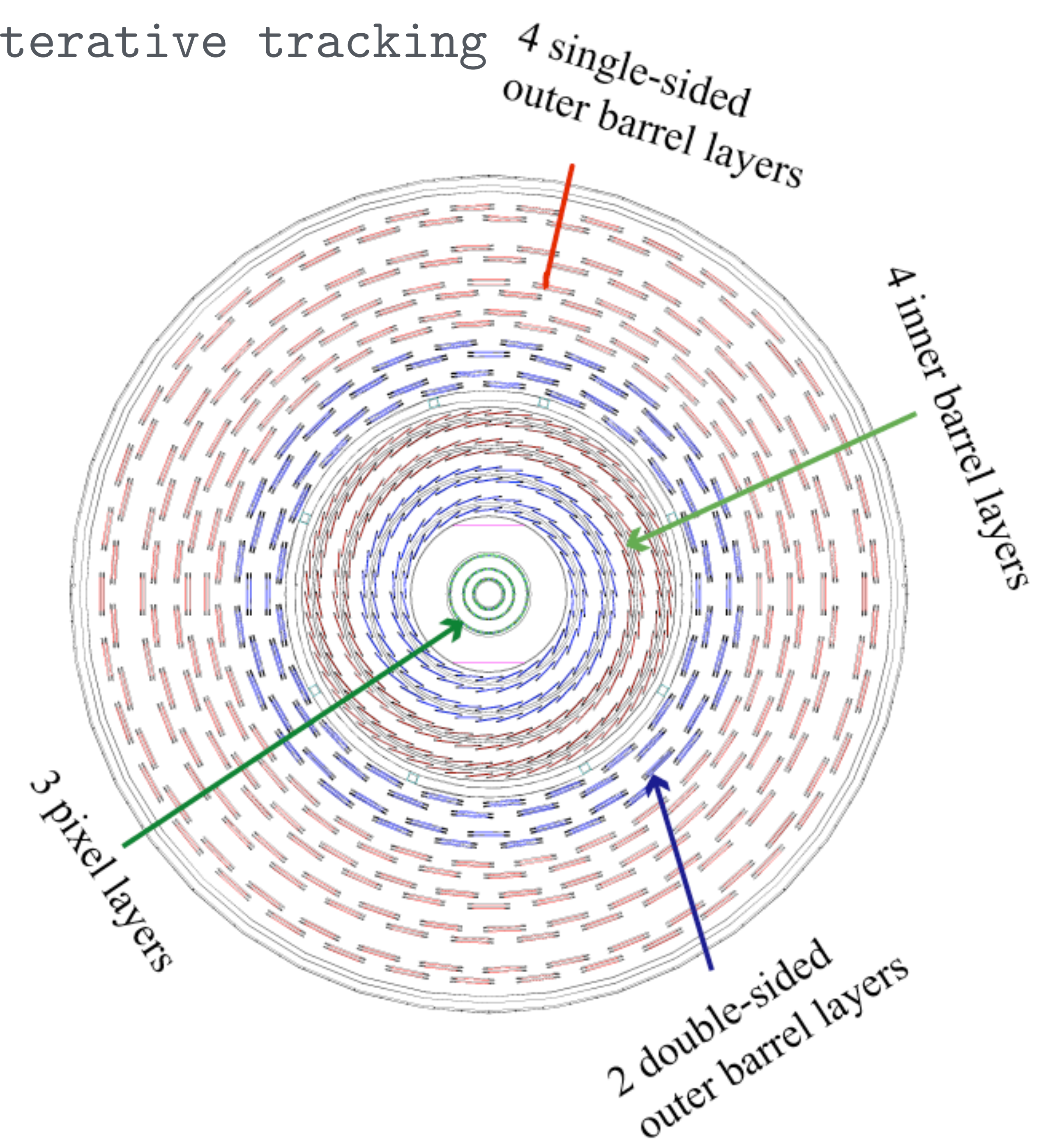
Track finding & reconstruction: Kalman Filter



Track finding & reconstruction: Iterative tracking

Track finding & reconstruction:

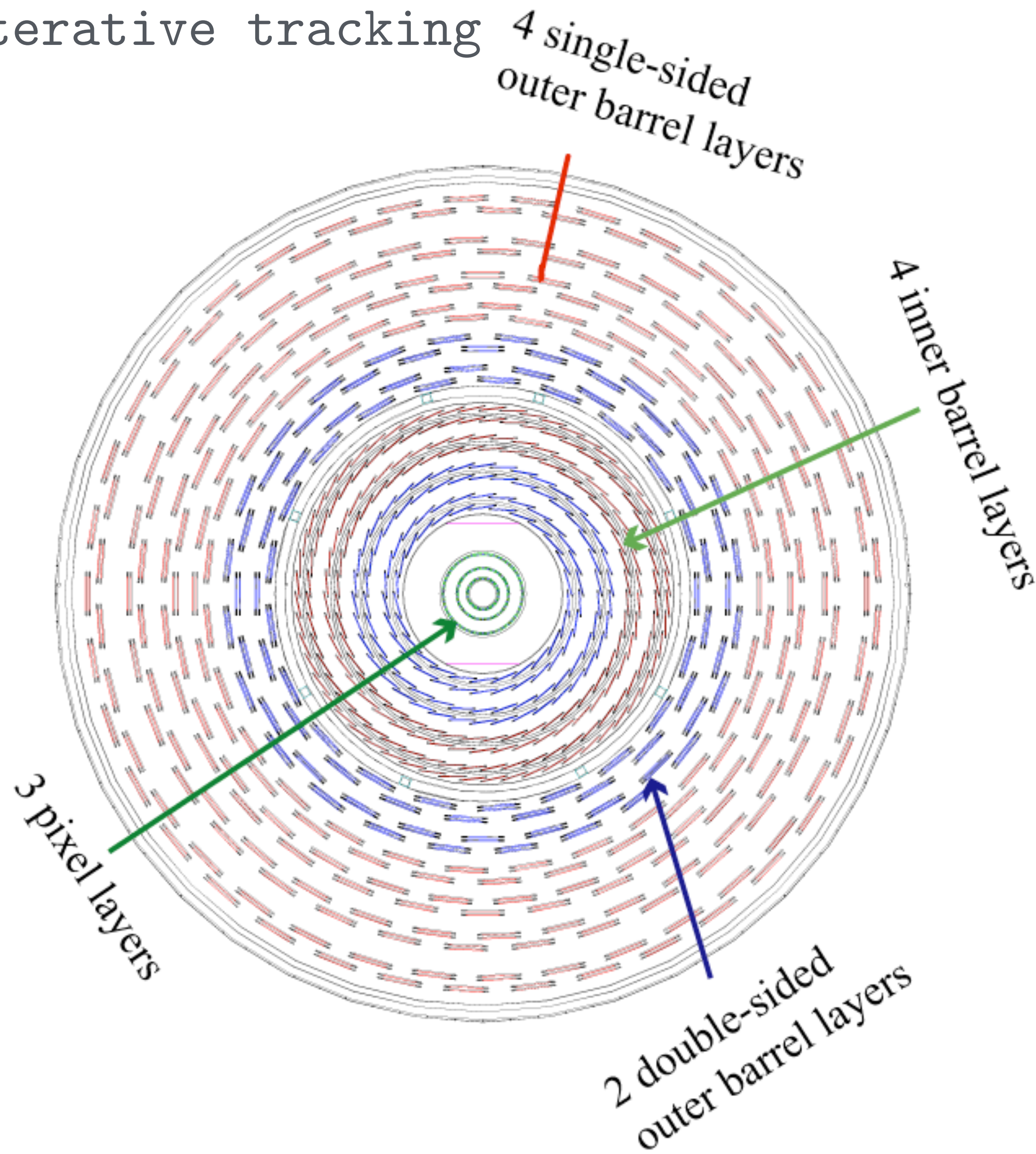
Iterative tracking



Track finding & reconstruction:

Iterative tracking

Fake tracks come from wrong combinations of hit associations

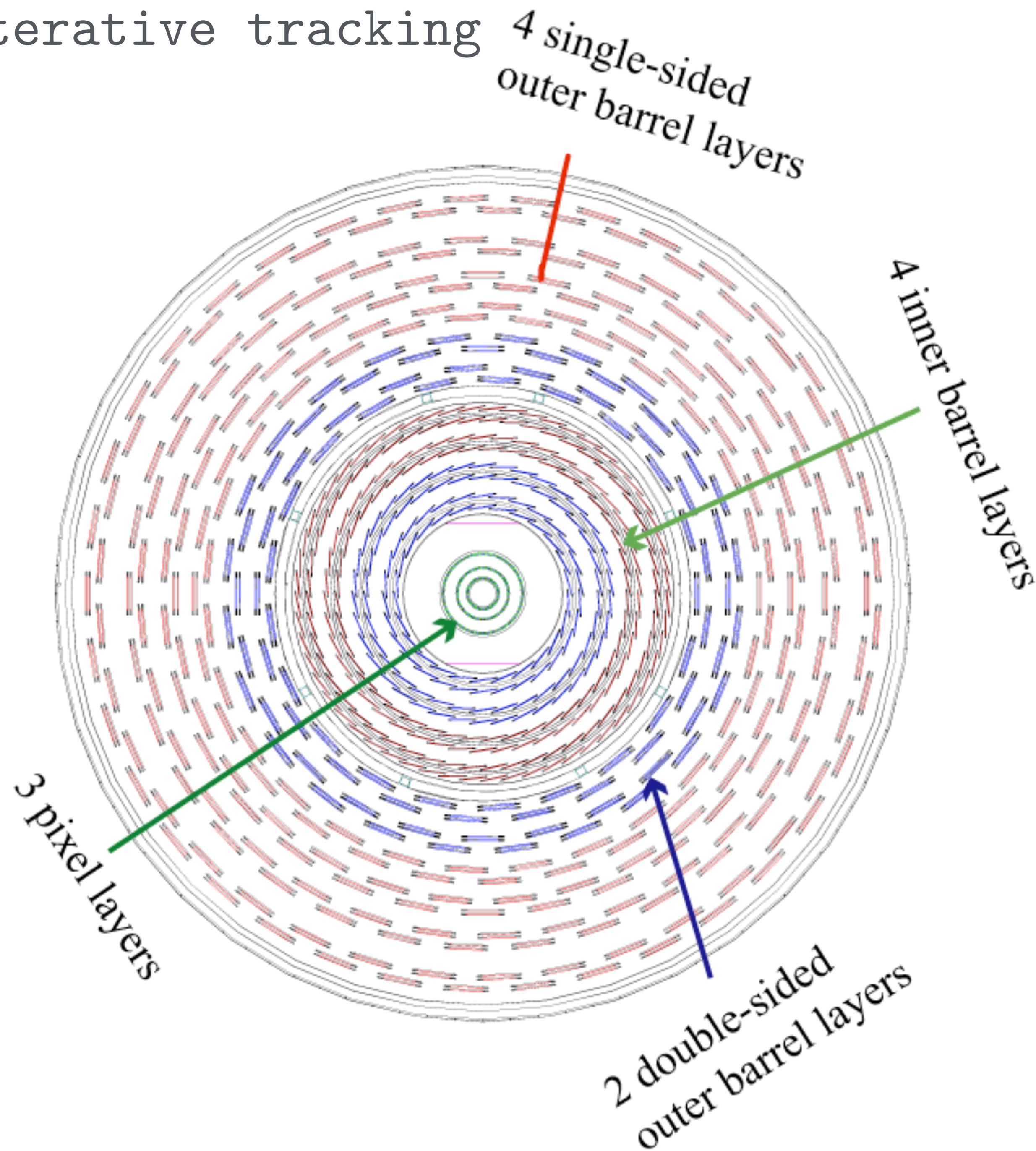


Track finding & reconstruction:

Iterative tracking

Fake tracks come from wrong combinations of hit associations

So, reduce the number of hits fed to the track finder



Track finding & reconstruction:

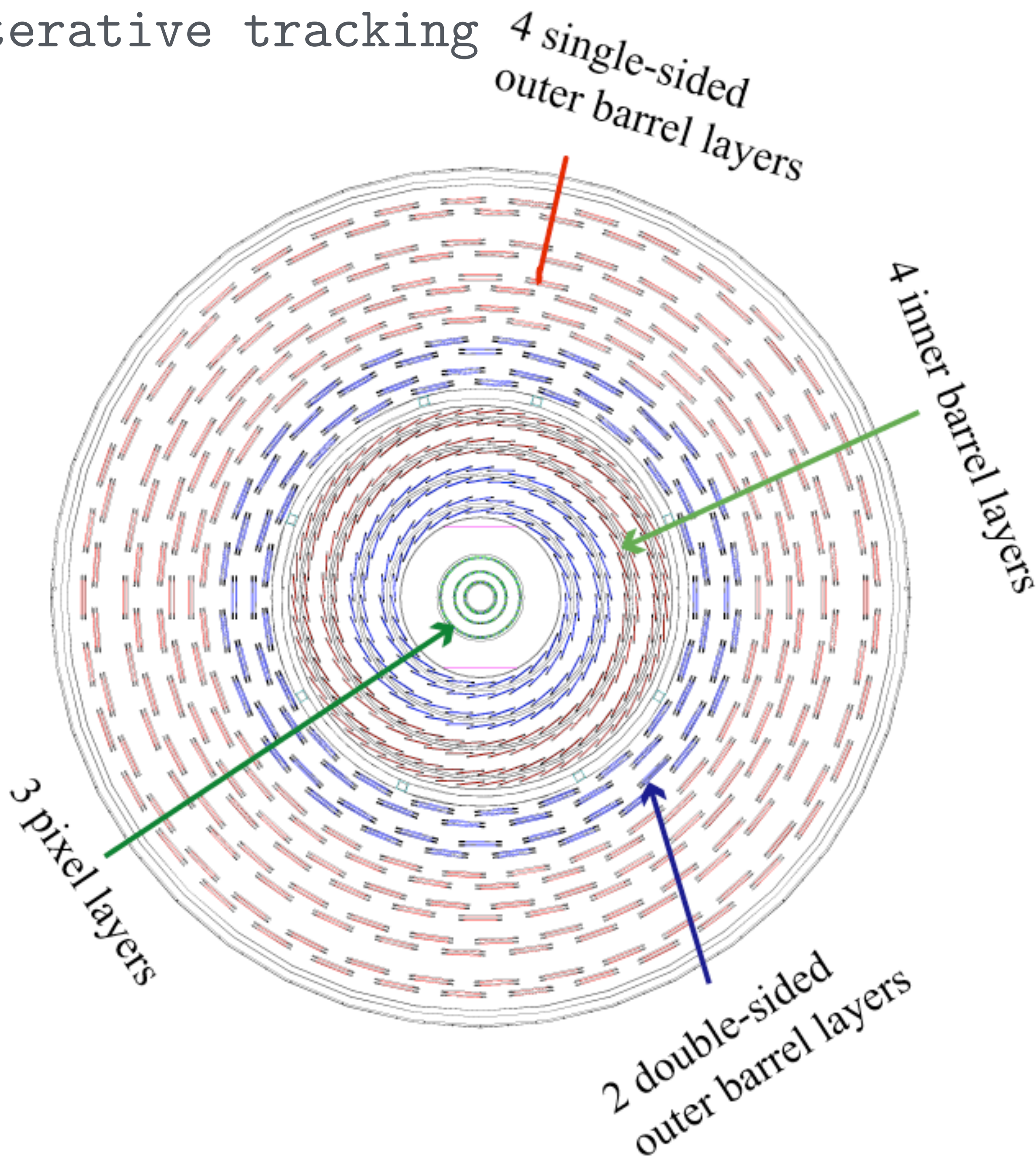
Iterative tracking

Start from a very pure track seeding

- Example: 3 pixel hits, very tight origin constraint, $p_T > 0.9$ GeV
- 75% efficiency, less than 1% fakes
- Reconstruct corresponding tracks (≥ 3 hits) & "remove" the used hits
- 40% of the hits are removed

Fake tracks come from wrong combinations of hit associations

So, reduce the number of hits fed to the track finder



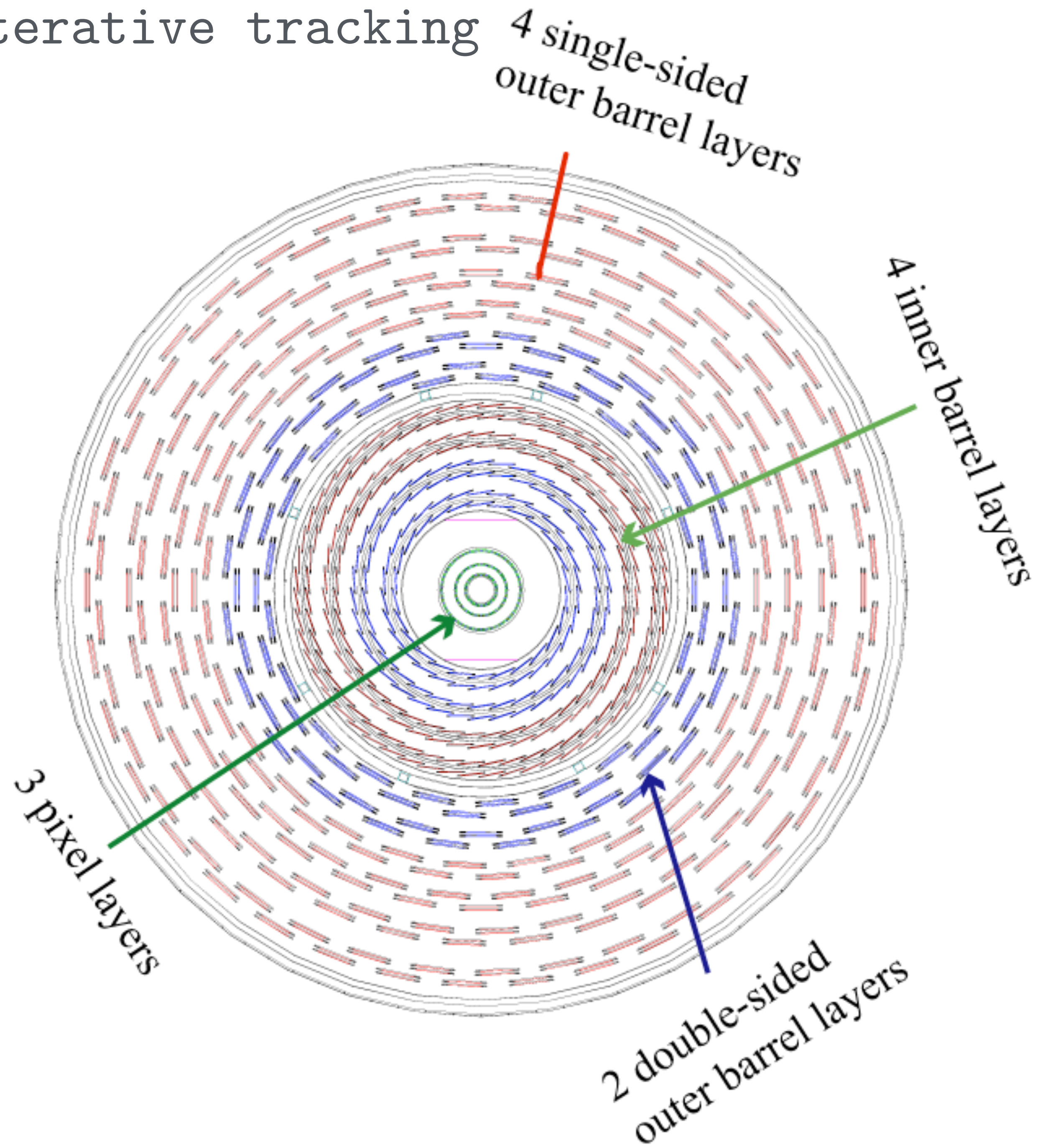
Track finding & reconstruction:

Iterative tracking

- Start from a very pure track seeding**
 - Example: 3 pixel hits, very tight origin constraint, $p_T > 0.9$ GeV, less than 1% fakes
- Next, try a looser seeding on 60% remaining hits**
 - Example: 2 pixel hits, very tight origin constraint, $p_T > 0.9$ GeV
 - adds 15% efficiency, still less than 1% fakes
 - Combinatorial possibilities much less
- Reconstruct the corresponding tracks (≥ 3 hits) & remove the used hits**
 - 10% of the hits are removed in this 2nd iteration

combinations

So, reduce the number of hits fed to the track finder



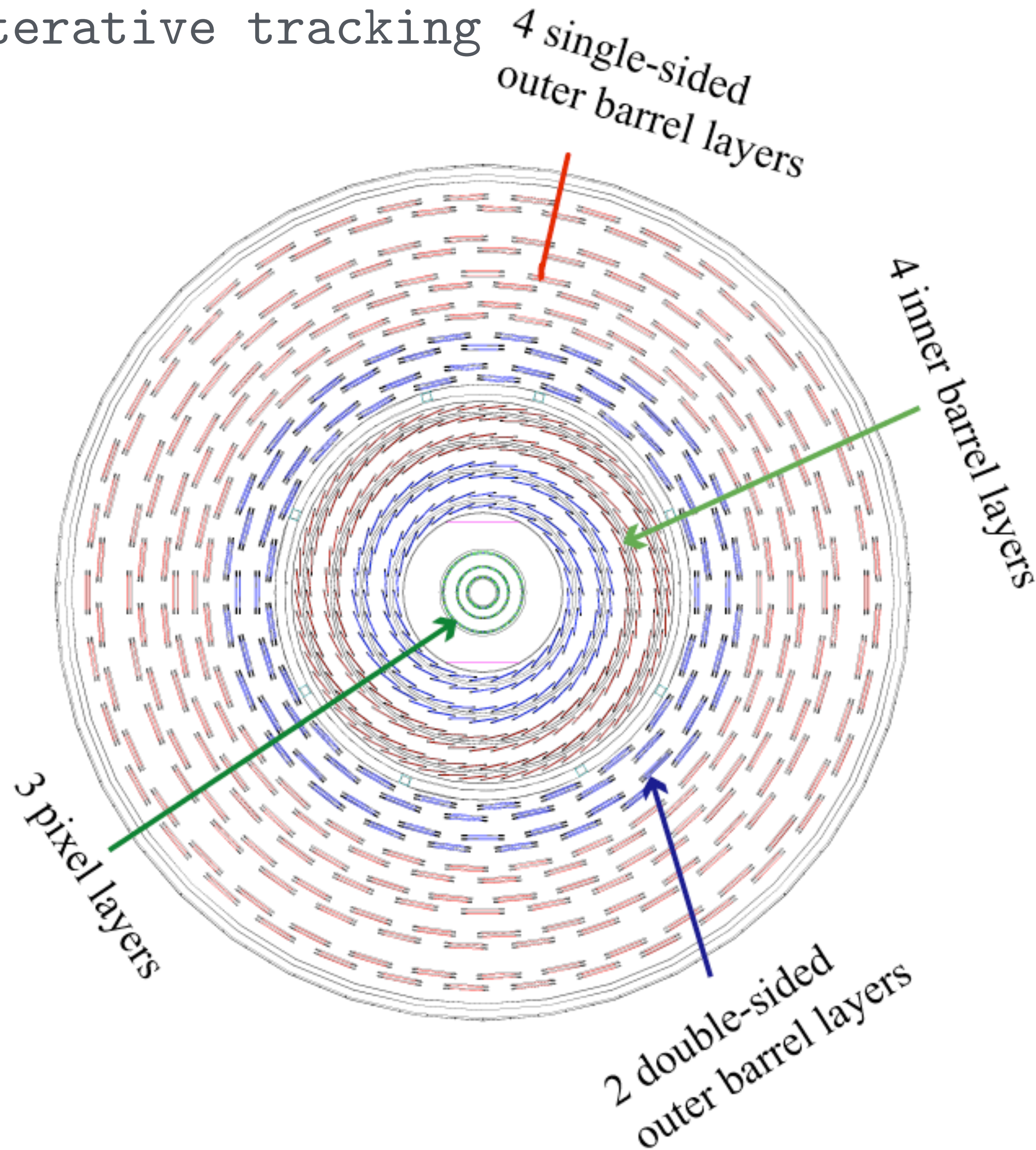
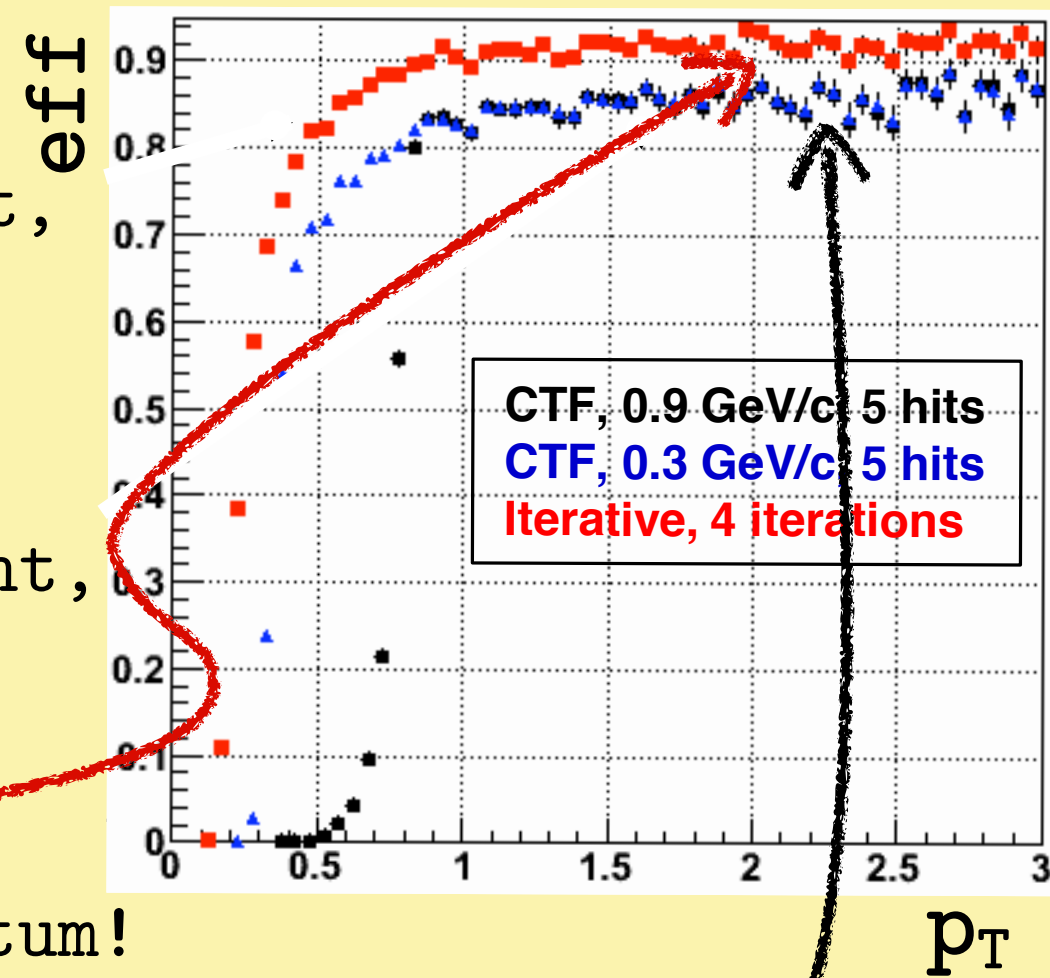
Track finding & reconstruction:

Iterative tracking

- Start from a very pure track seeding**
- Example: 3 pixel hits, very tight origin constraint, $p_T > 0.9$ GeV, less than 1% fakes
- Next, try a looser seeding on 60% remaining hits**
- Example: 2 pixel hits, very tight origin constraint, $p_T > 0.9$ GeV
- adds 15% efficiency, still less than 1% fakes

And so on...with more iterations

- 3rd iteration:
- 3 pixel hits, tight origin constraint, $p_T > 0.2$ GeV
- 4th iteration:
- 2 pixel hits, looser origin constraint, $p_T > 0.3$ GeV
- 93% efficiency, 1-2% fake rate
- down to very low momentum!
- Recall original situation
- 85% efficiency, 20% fake rate



Track finding & reconstruction: Iterative tracking

Start from a very pure seeding

- Example: 3 pixel hits, very tight origin constraint, $p_T > 0.5$ GeV

Next, try a looser seeding

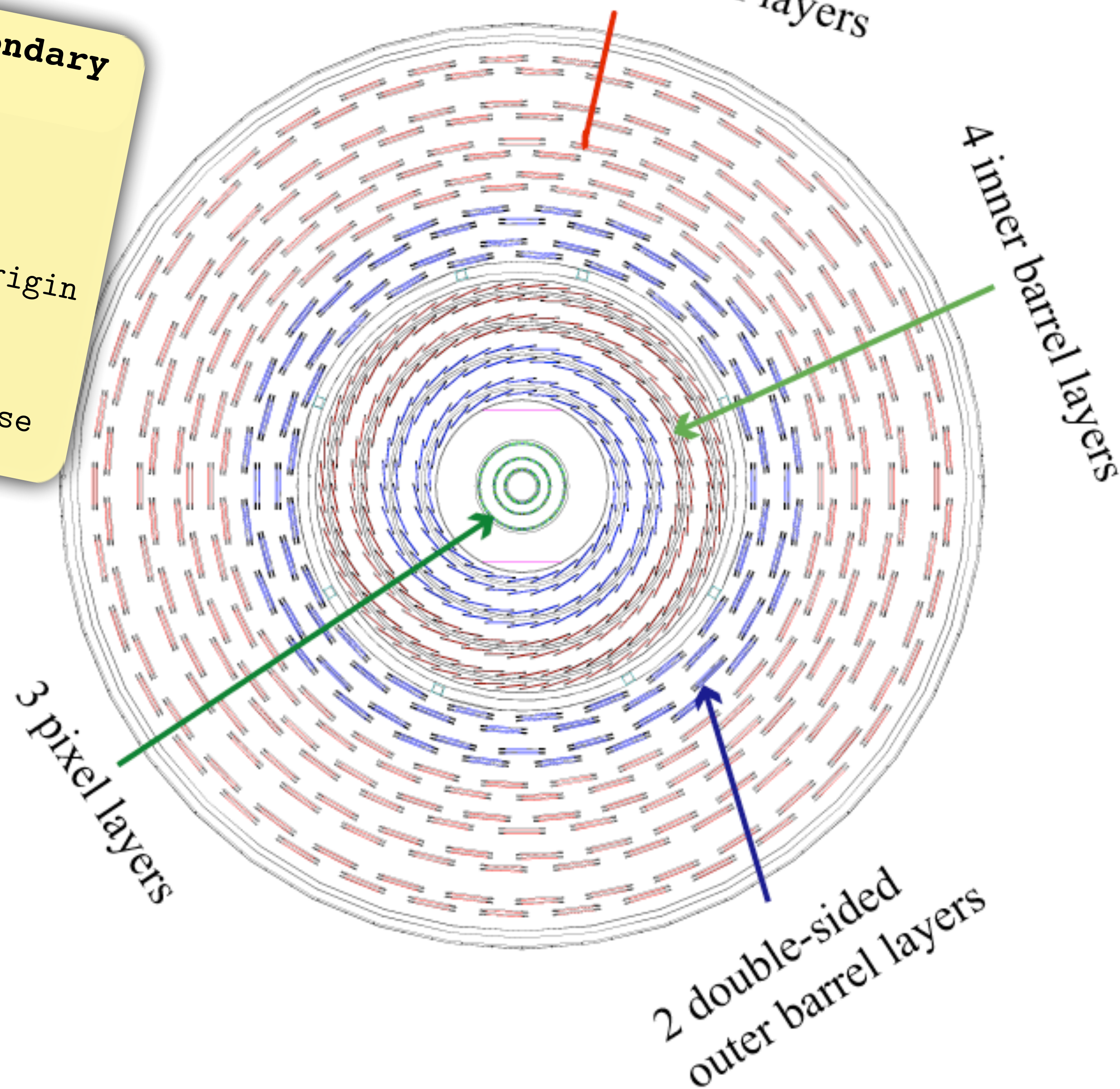
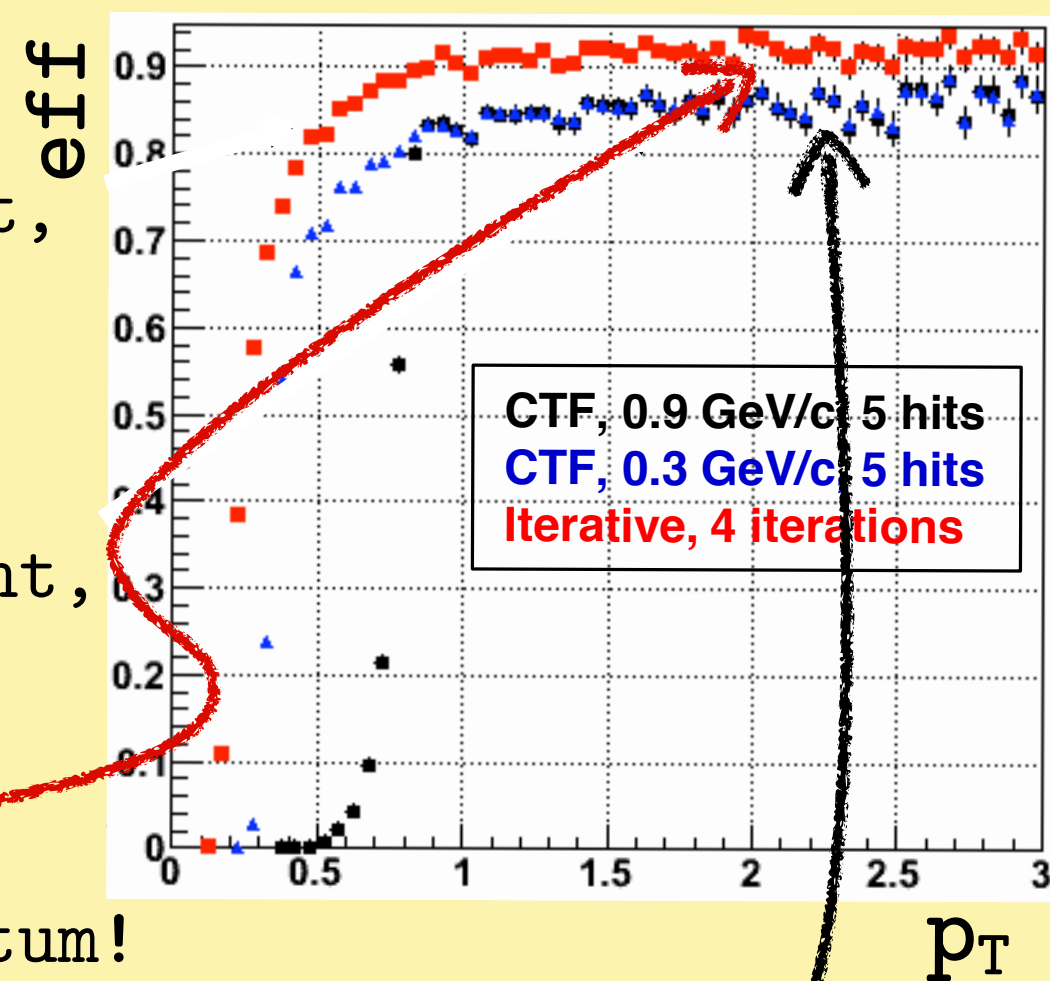
- Example: 2 pixel hits, loose origin constraint, $p_T > 0.3$ GeV
- adds 15% efficiency, so long as less than 1% fakes

And even try to catch secondary tracks

- Interactions, conversions, decays, ...
- 5th iteration:
 - Inner tracker seeding, loose origin constraint, $p_T > 0.5$ GeV
- 6th iteration:
 - Outer tracking seeding, very loose origin constraint, $p_T > 0.8$ GeV

And so on...with more iterations

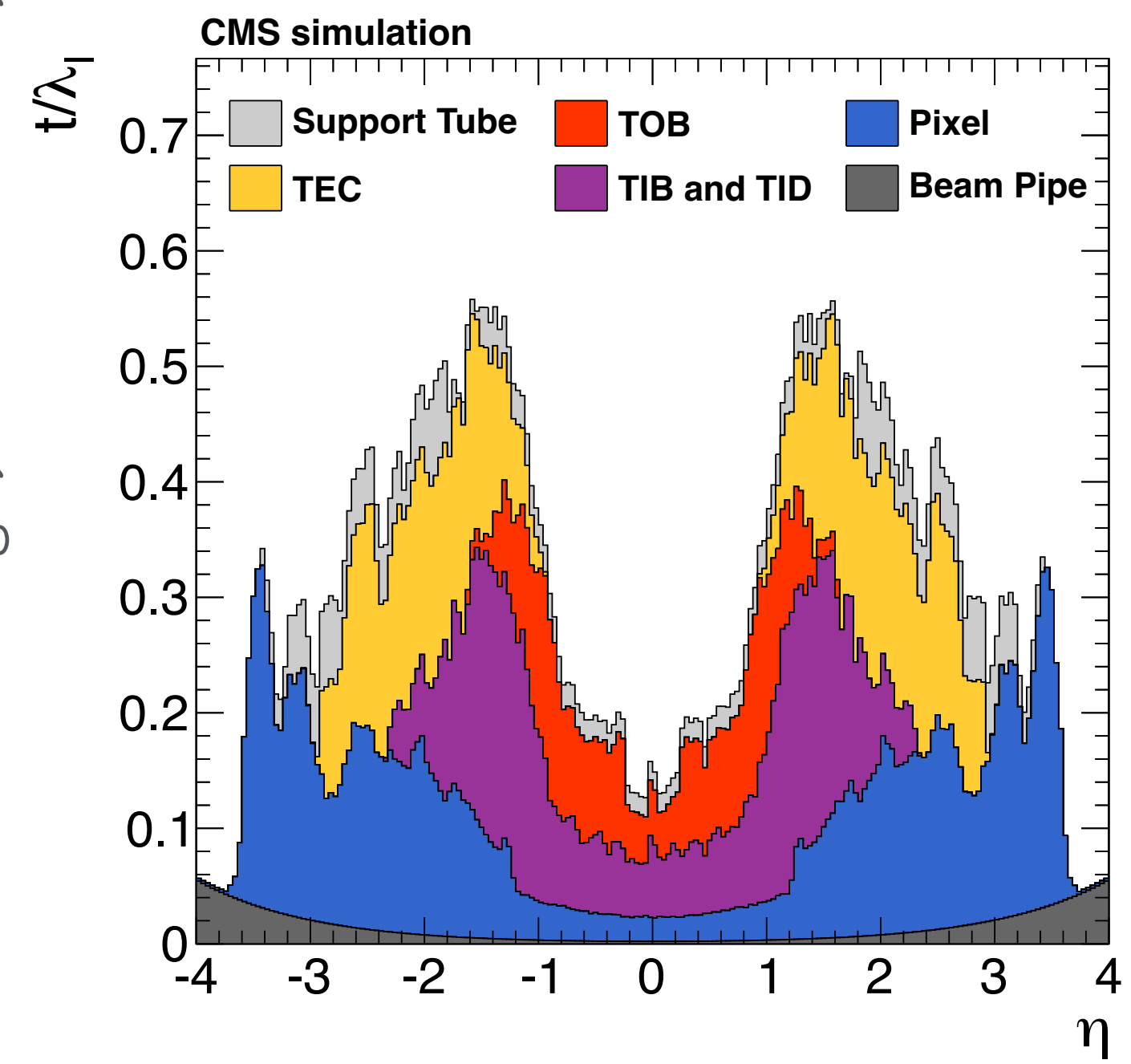
- 3rd iteration:
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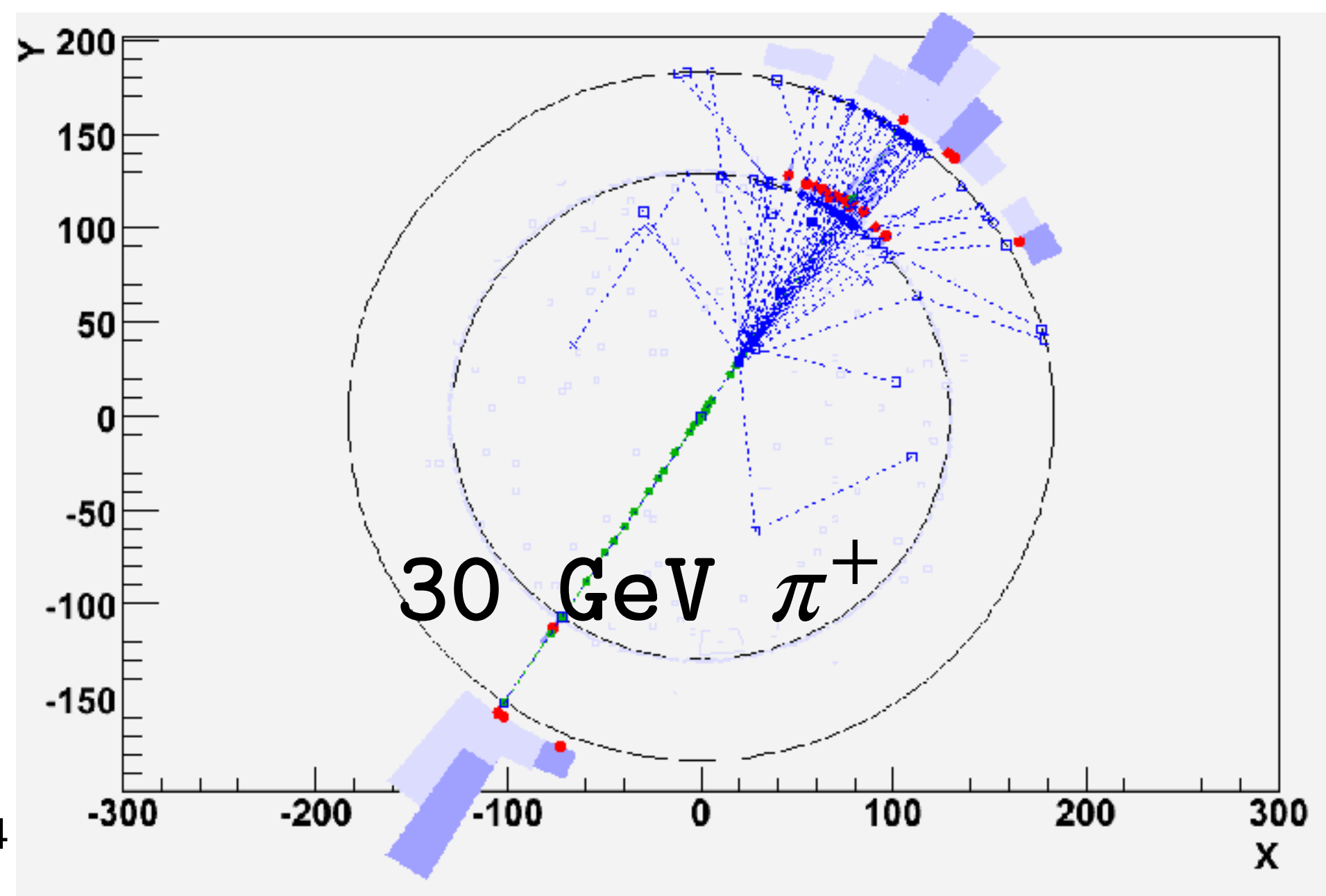
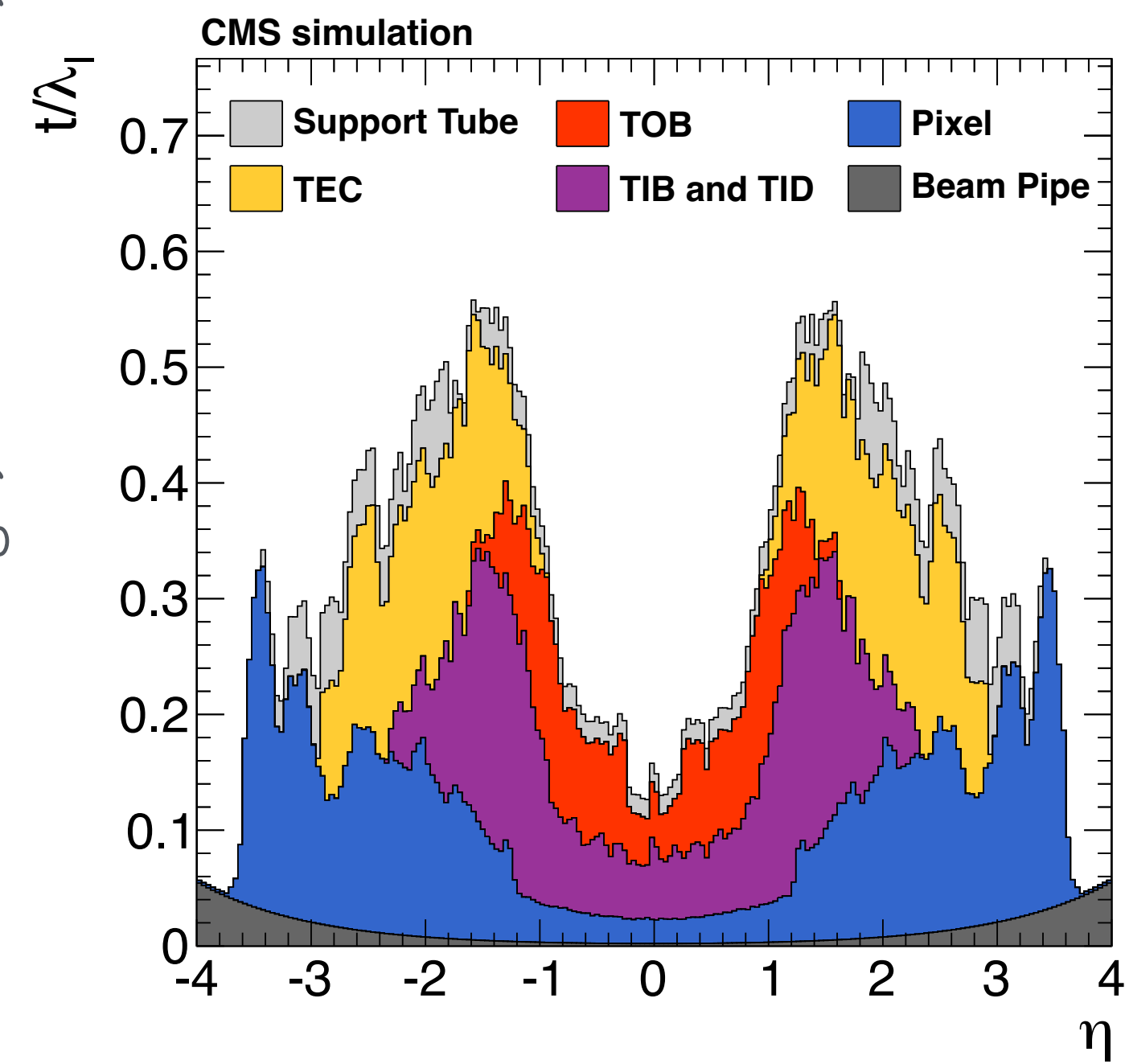
Important details! Tracker Material Budget

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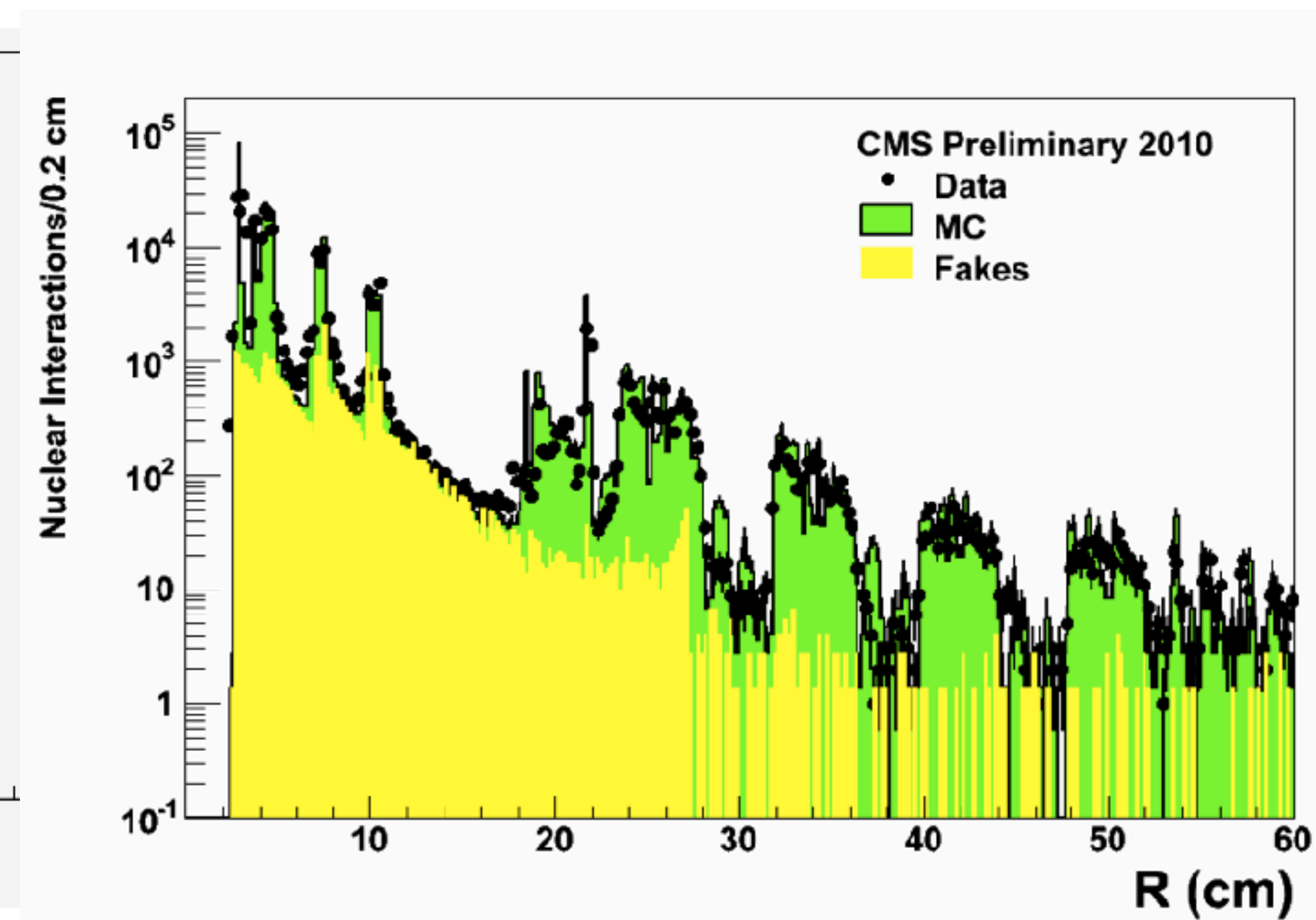
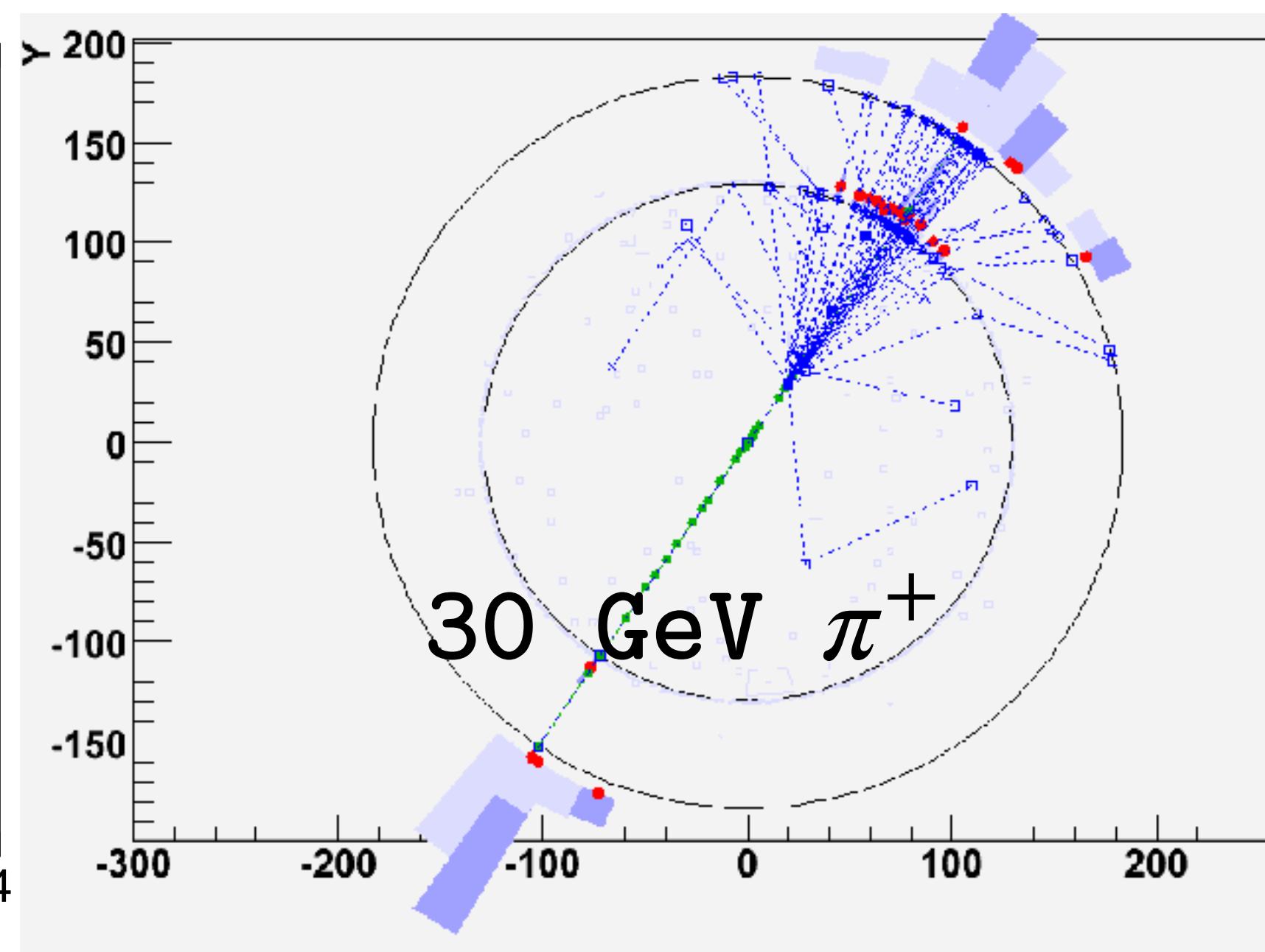
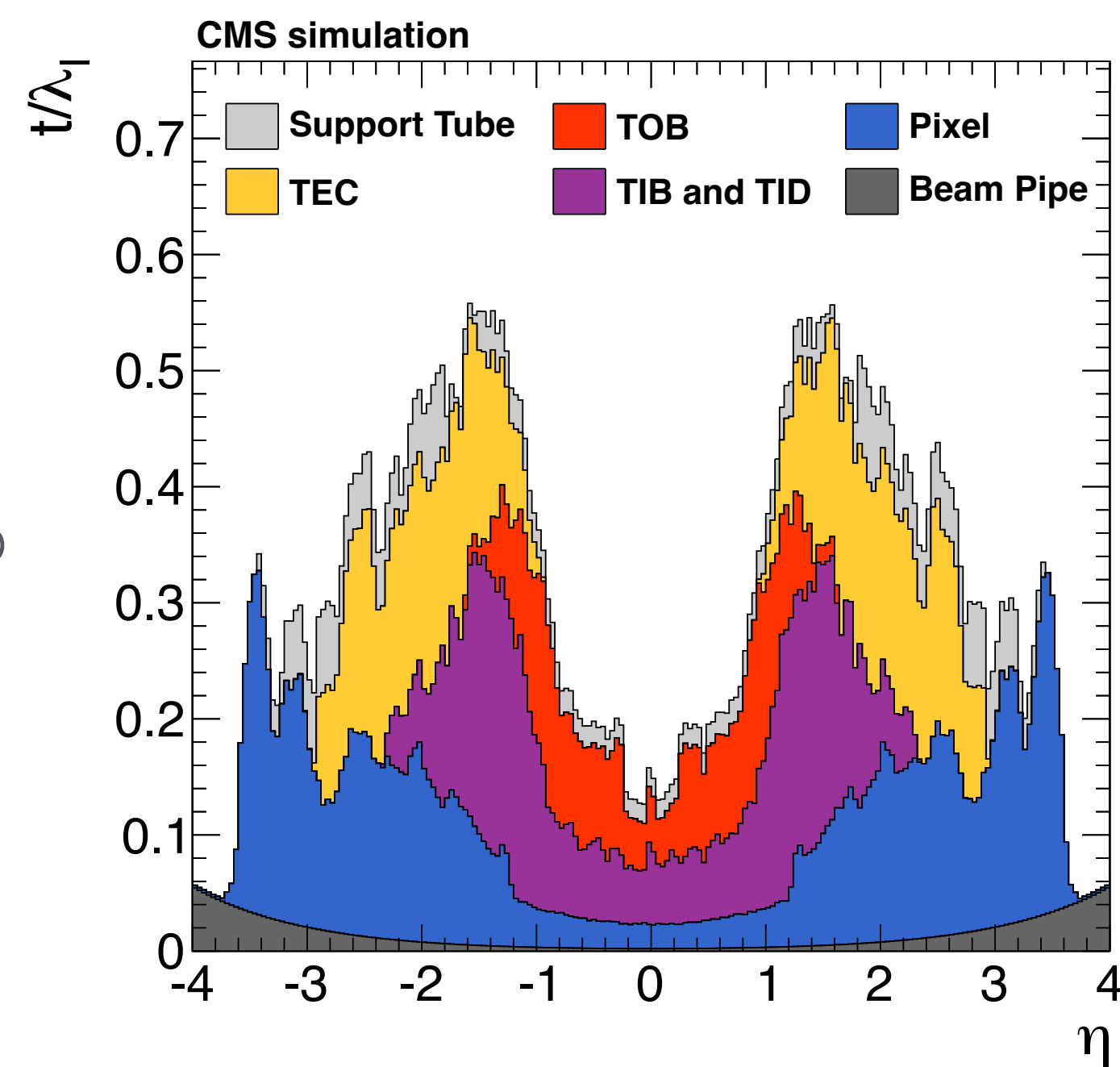
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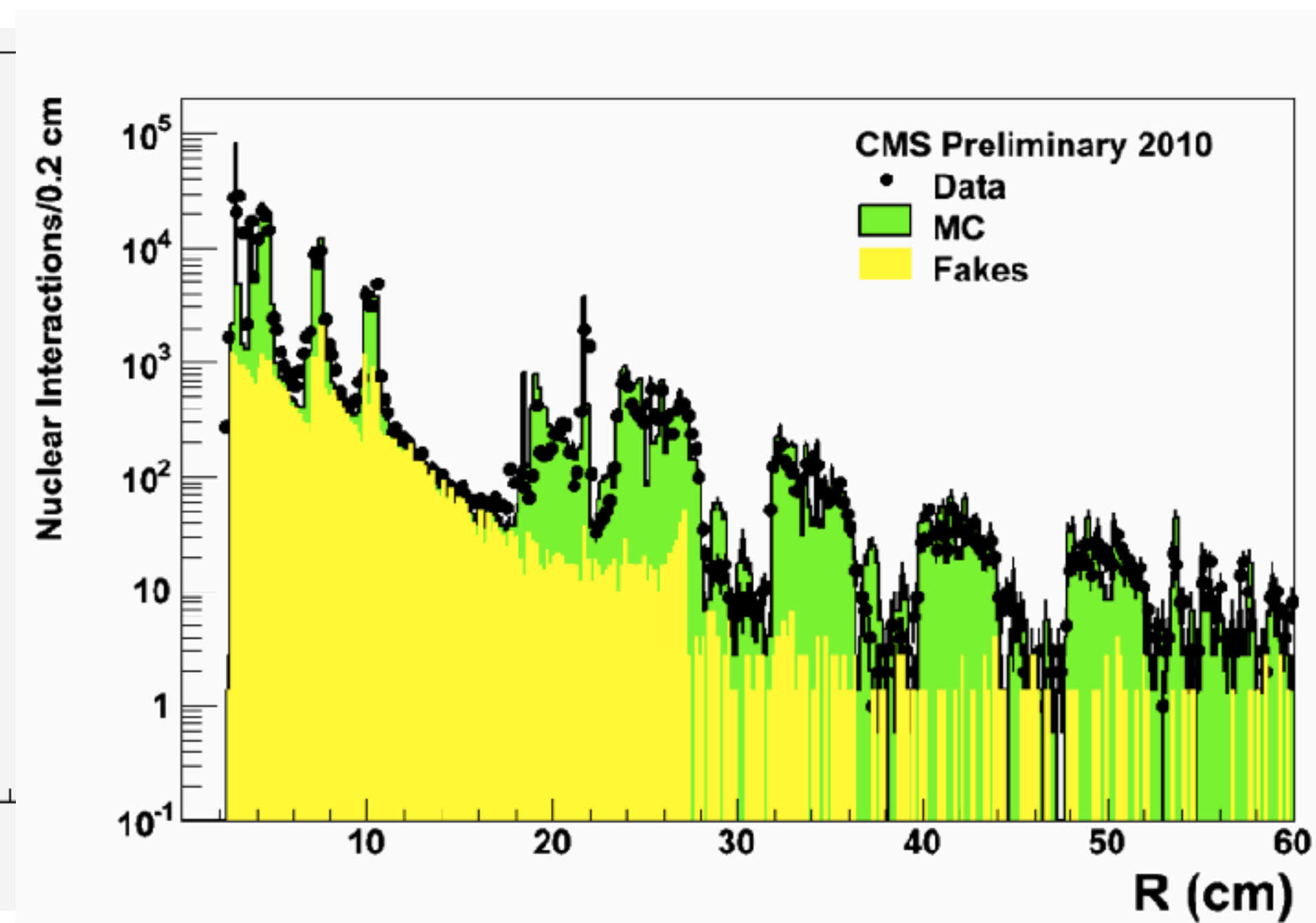
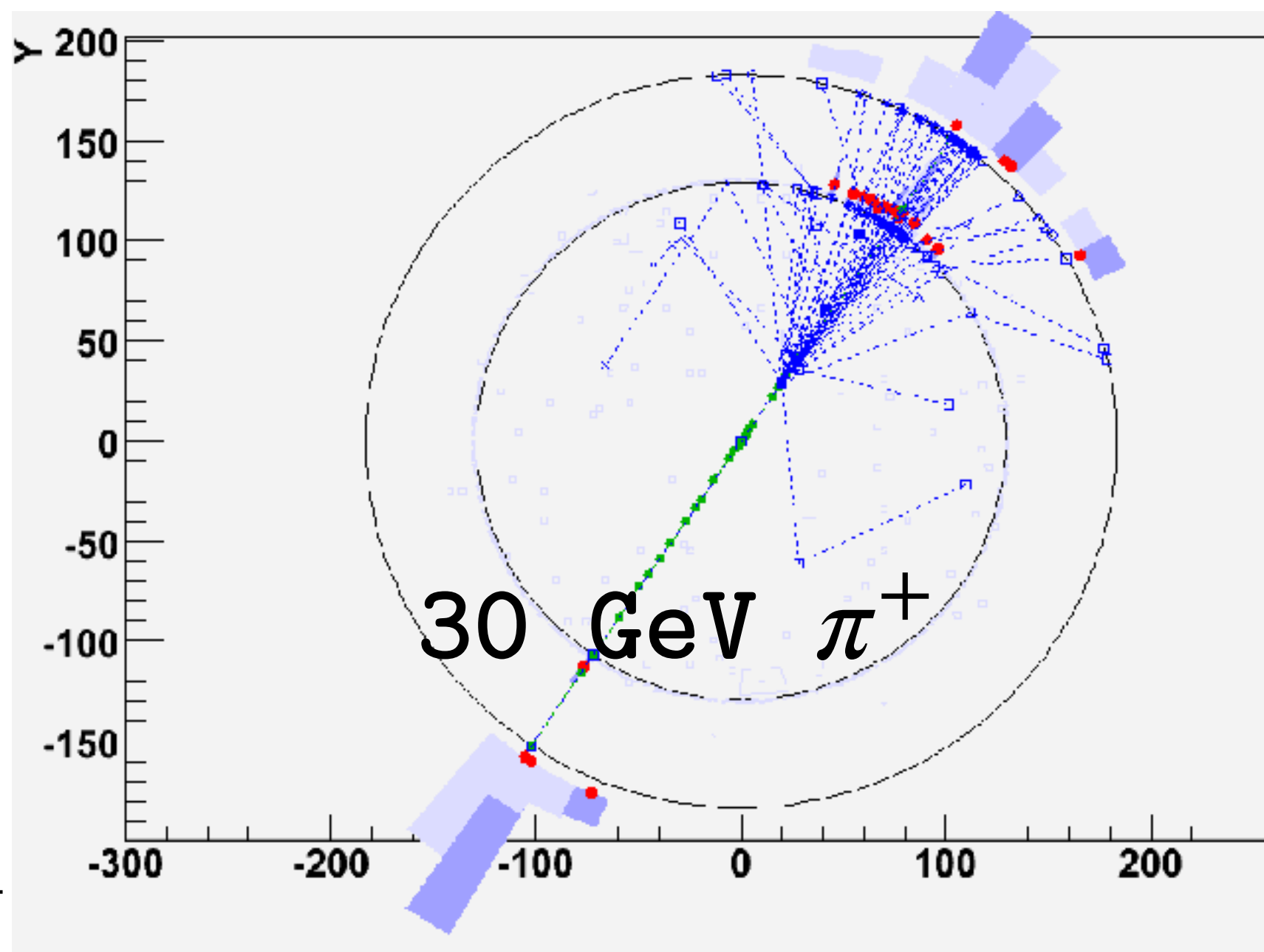
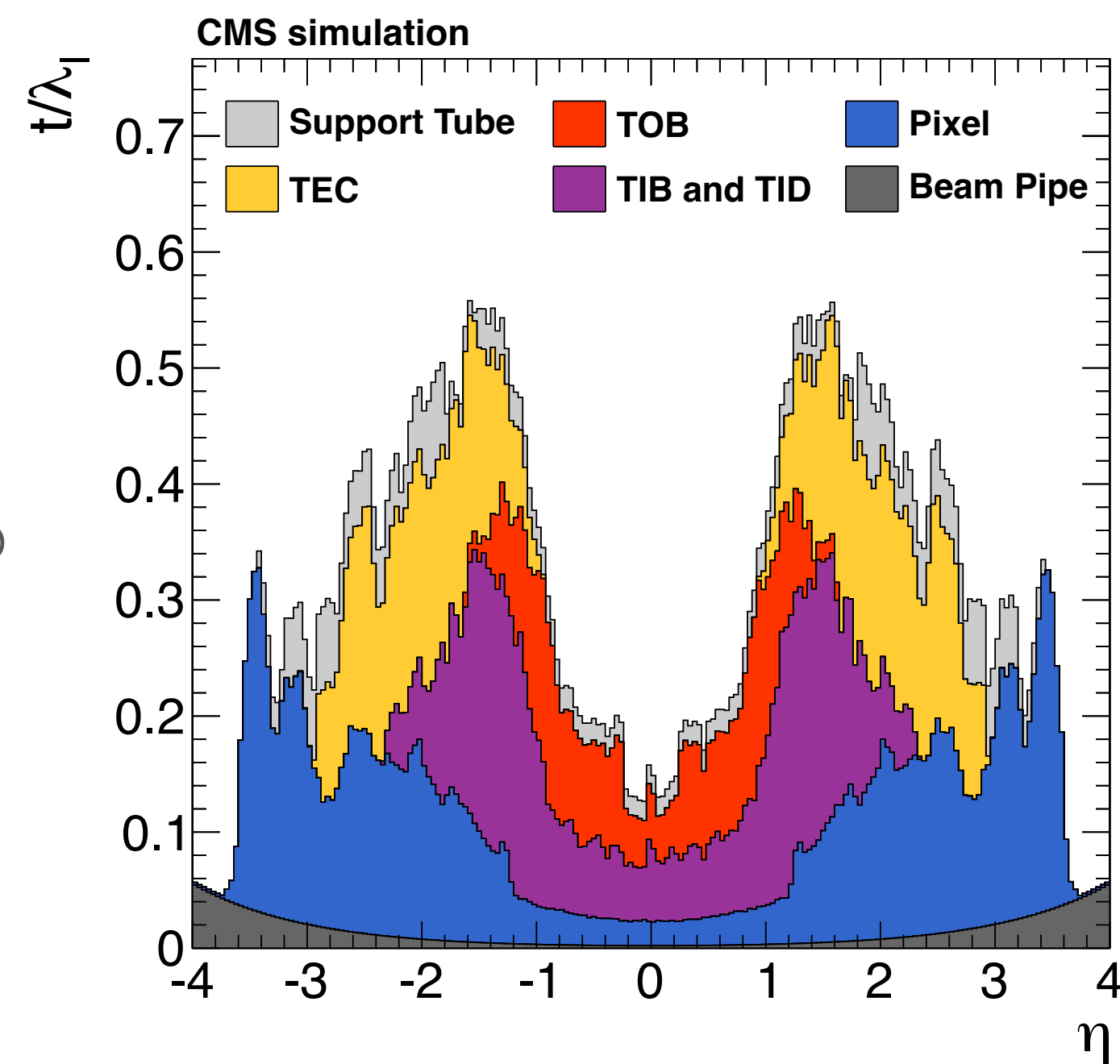
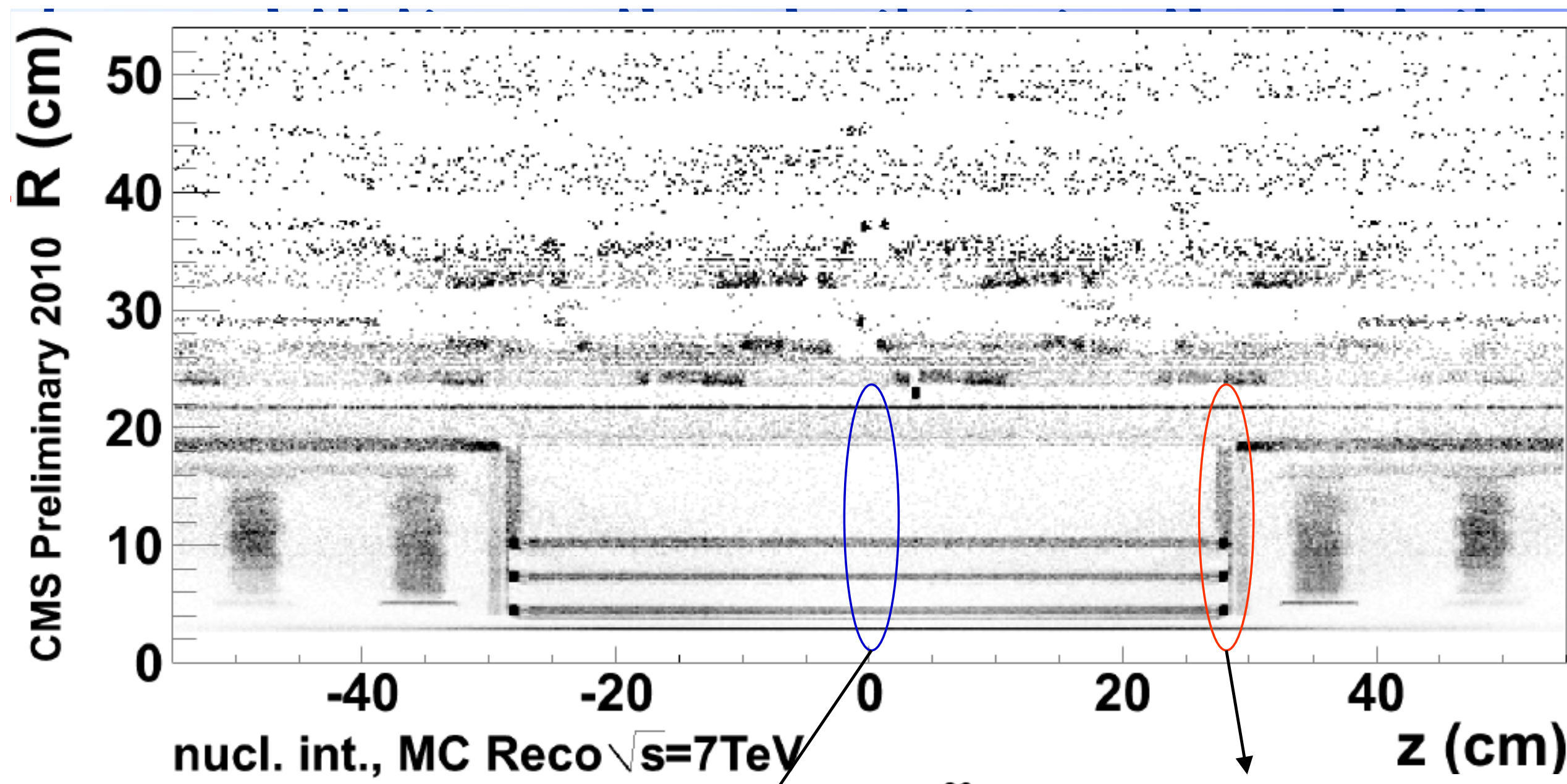


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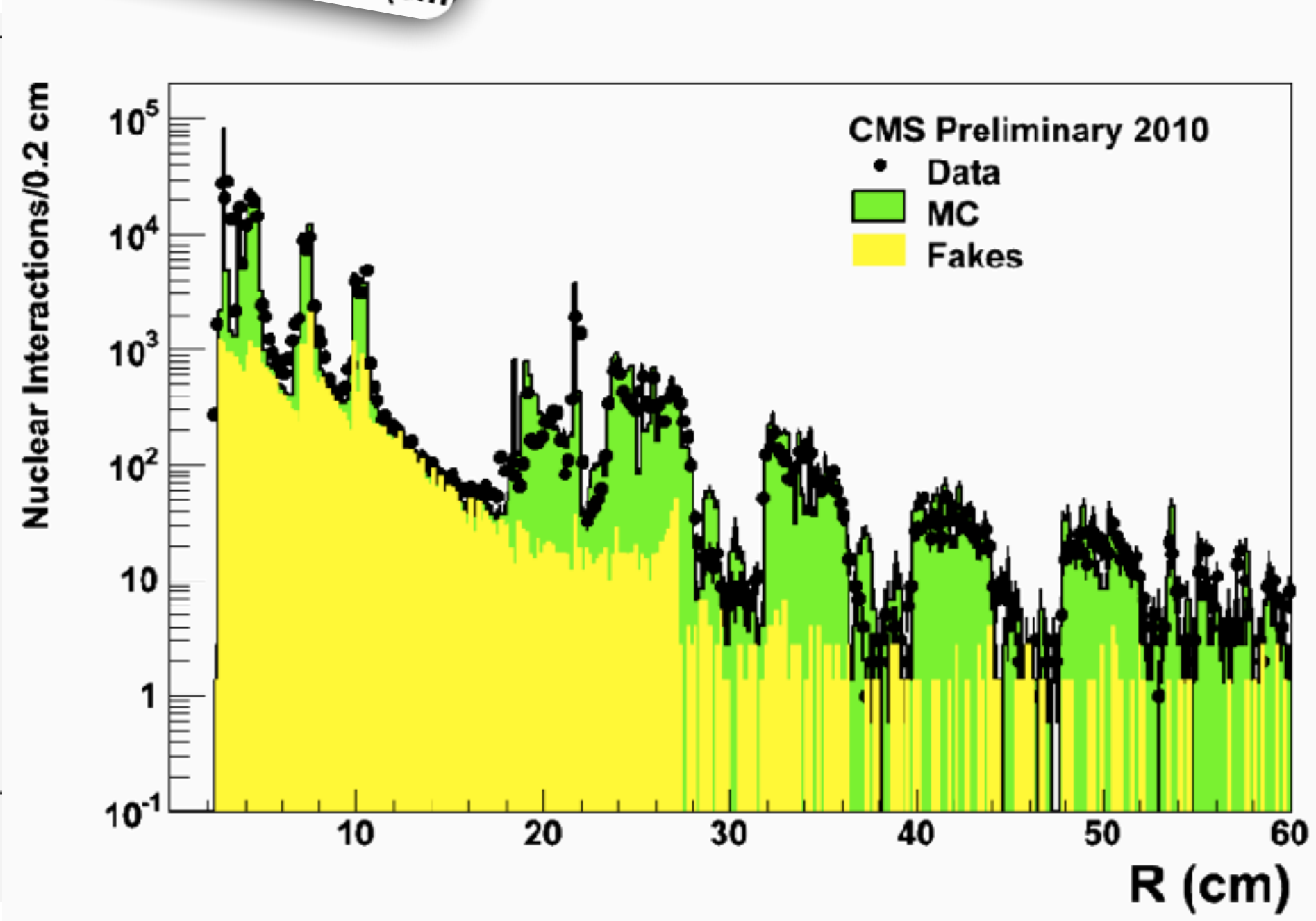
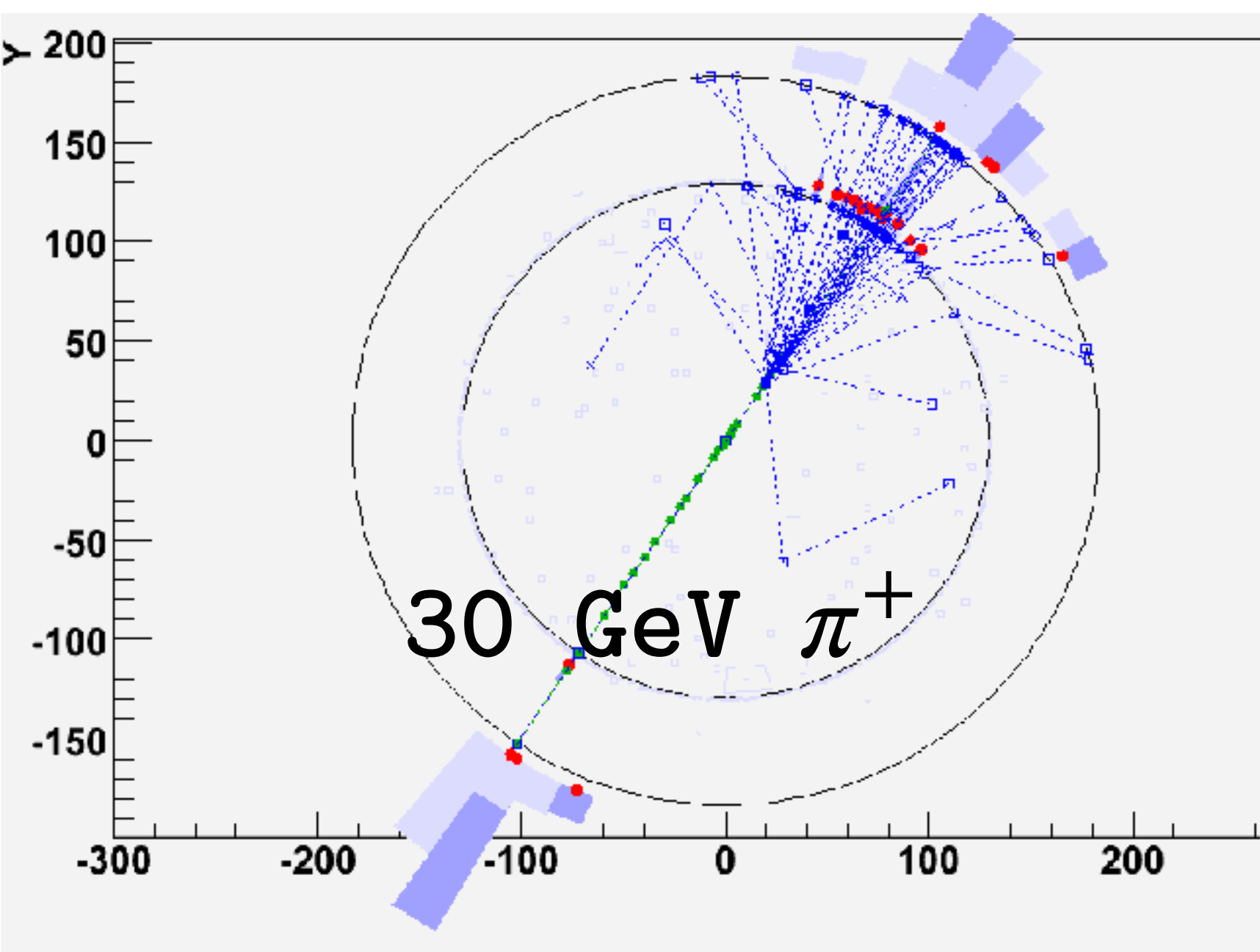
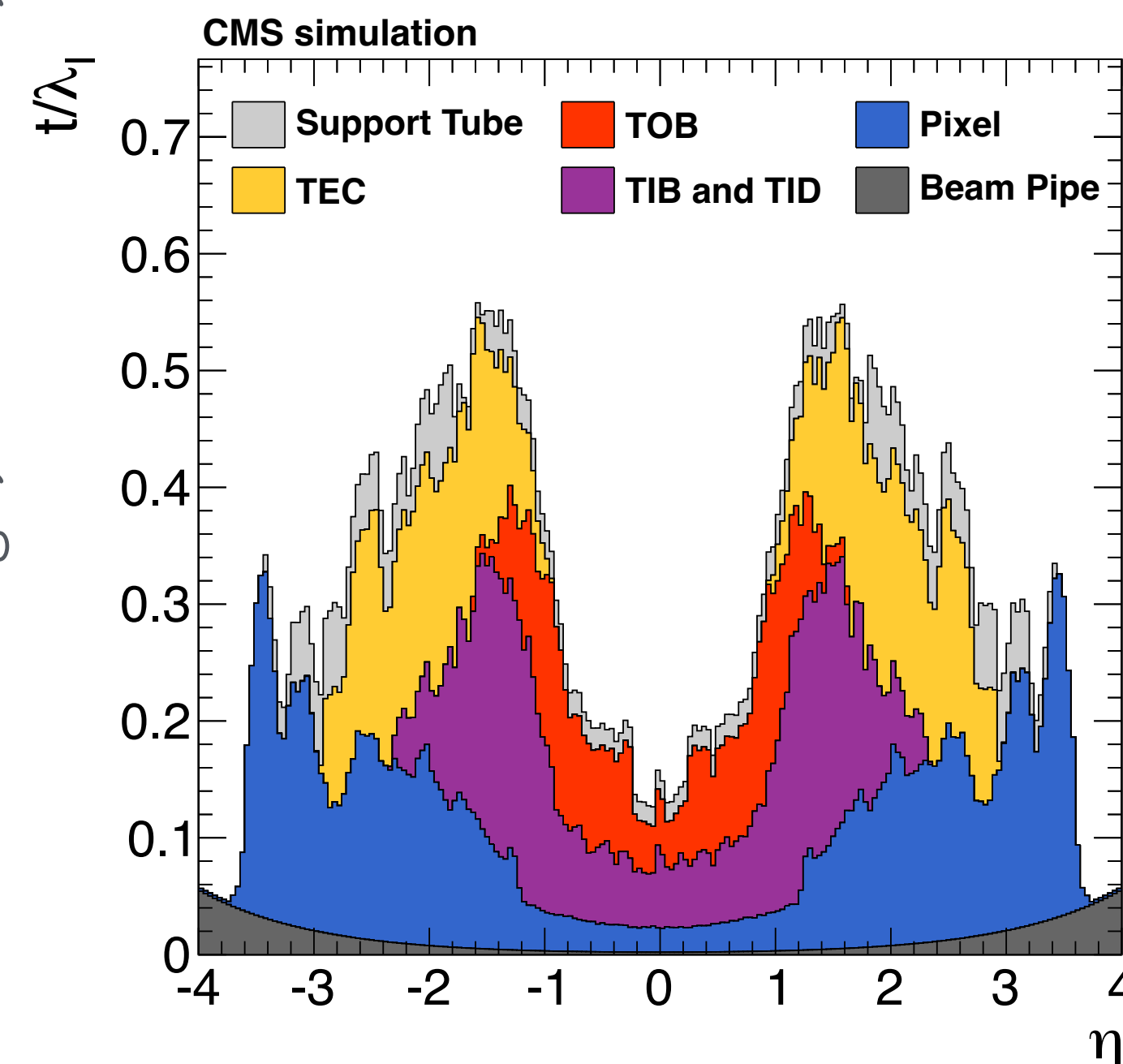
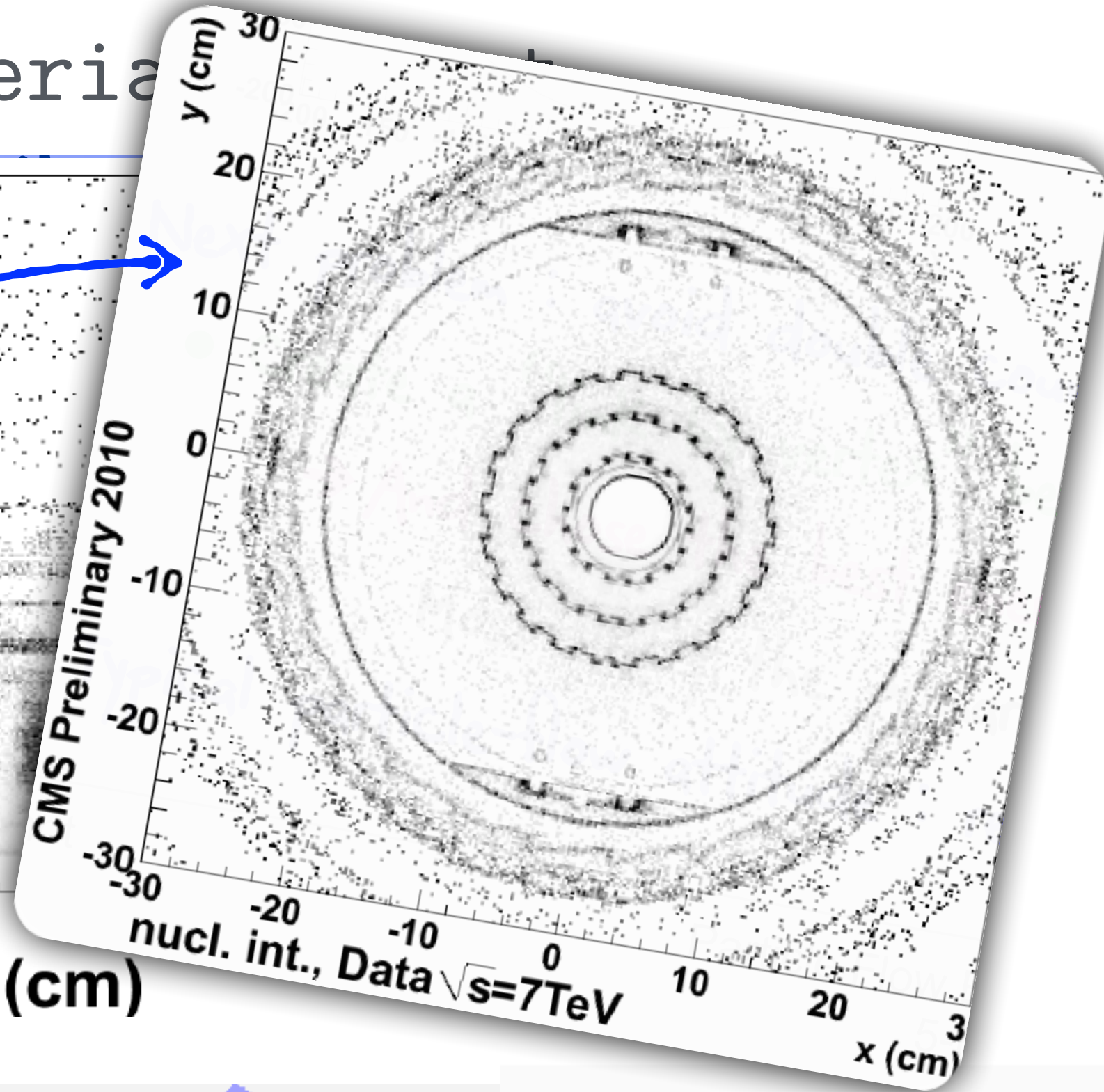
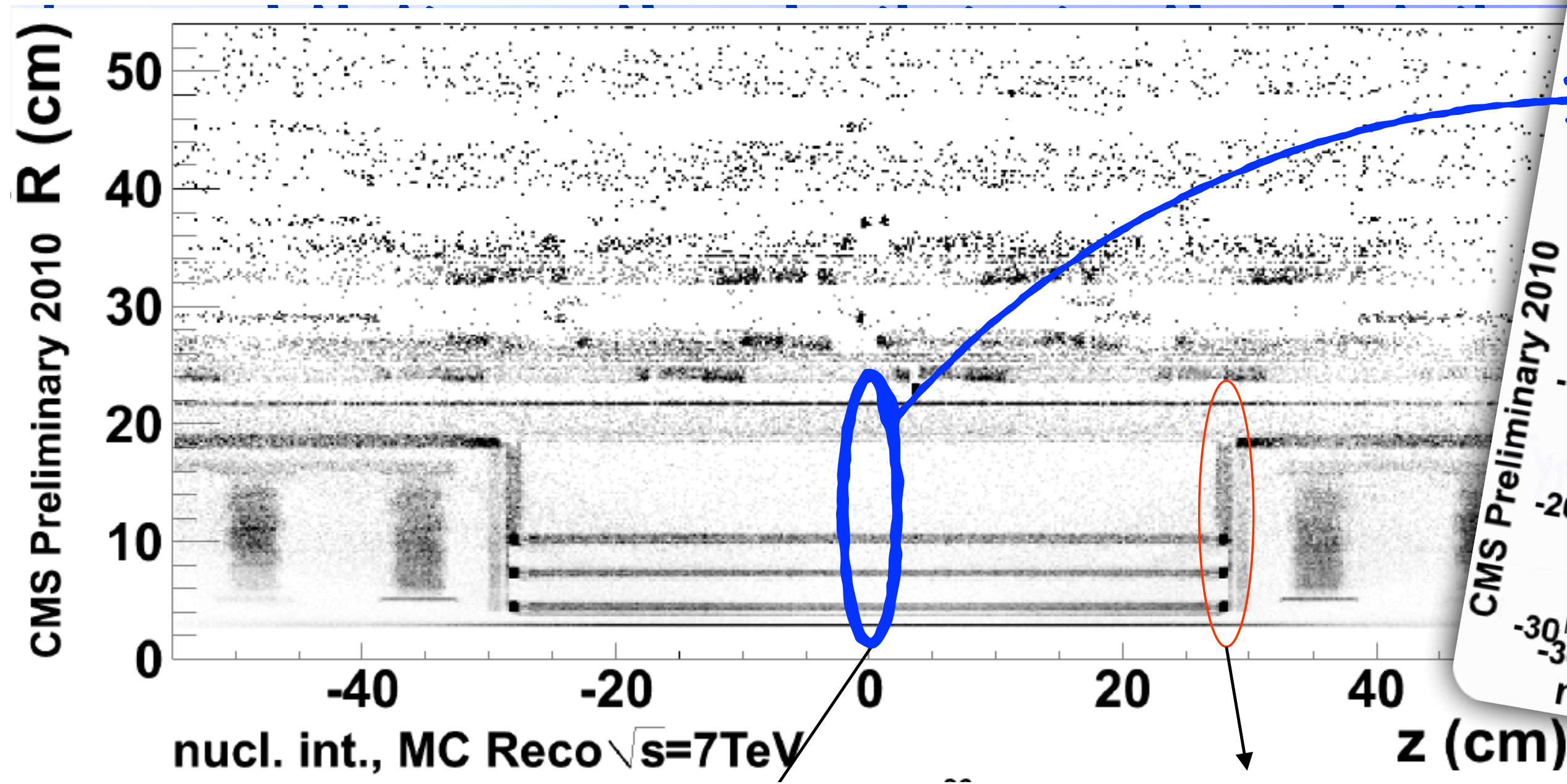


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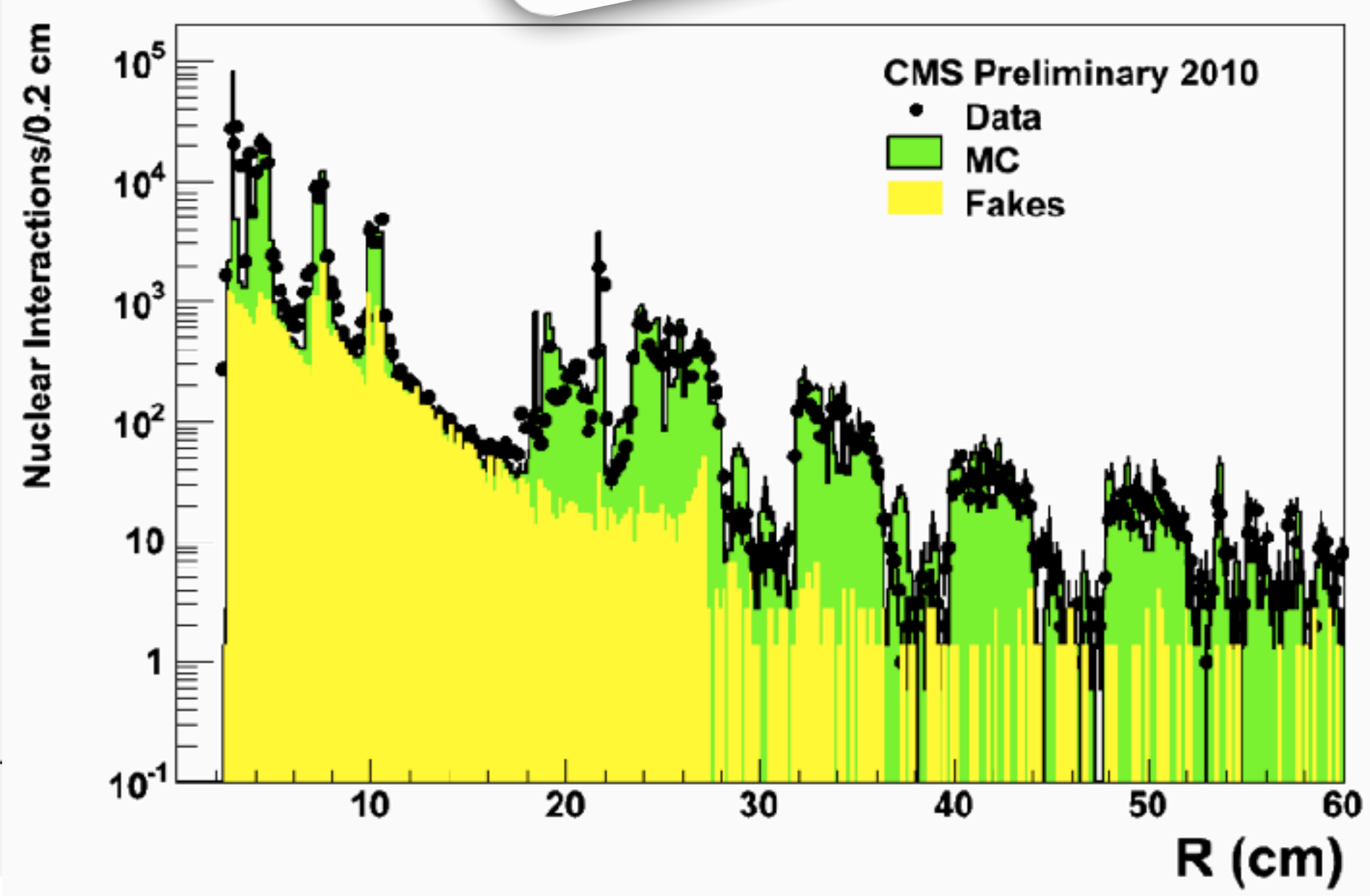
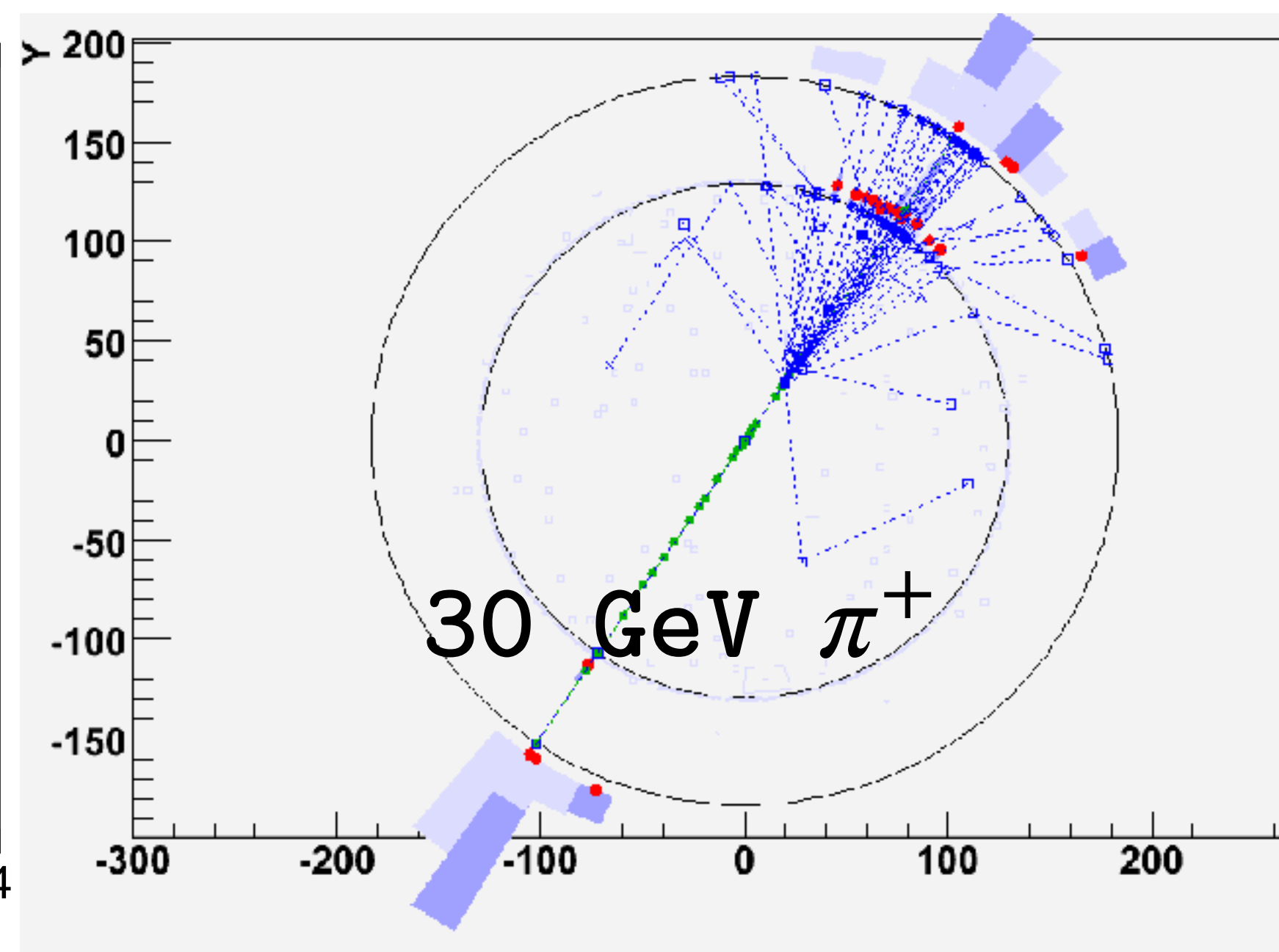
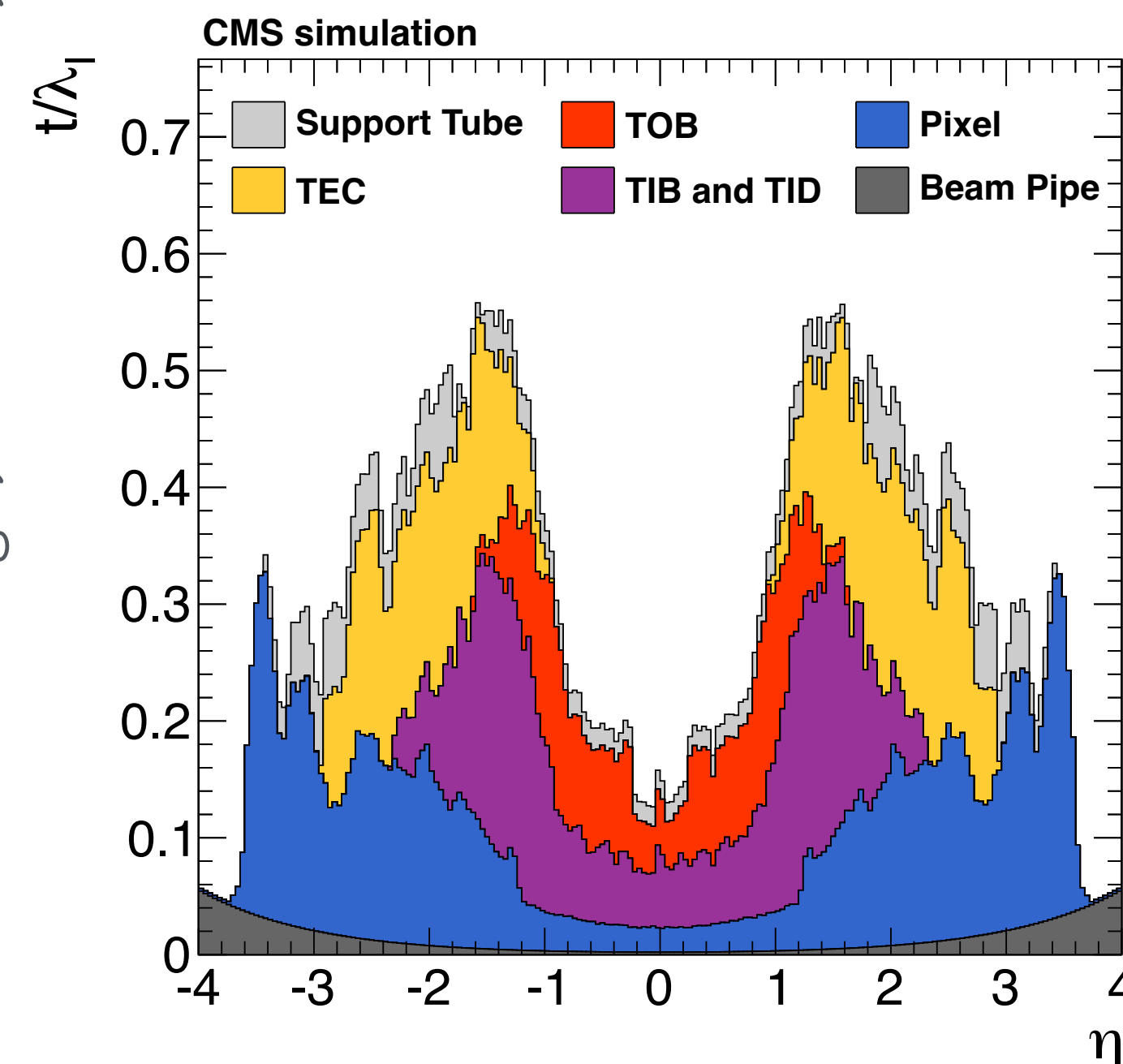
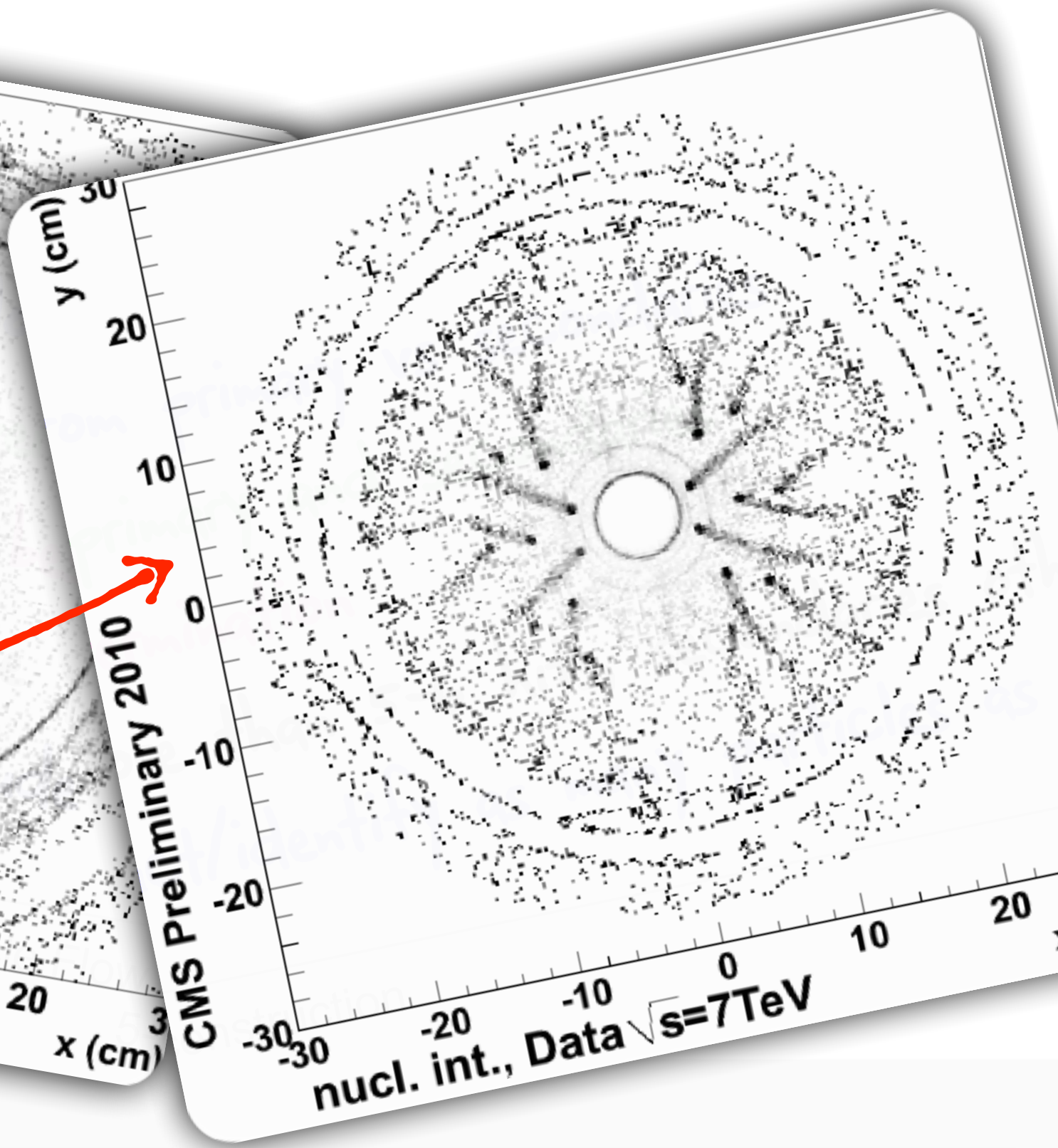
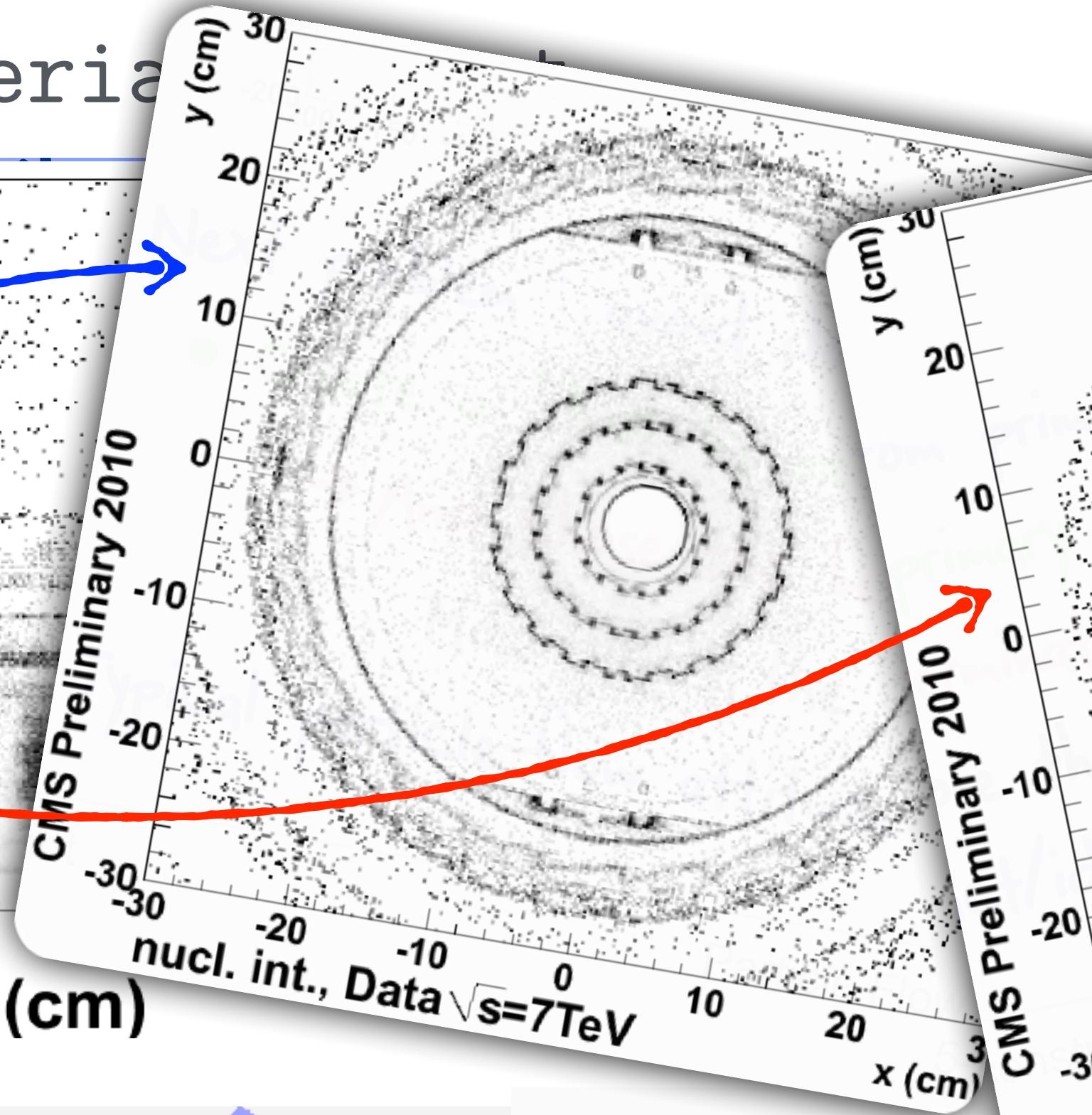
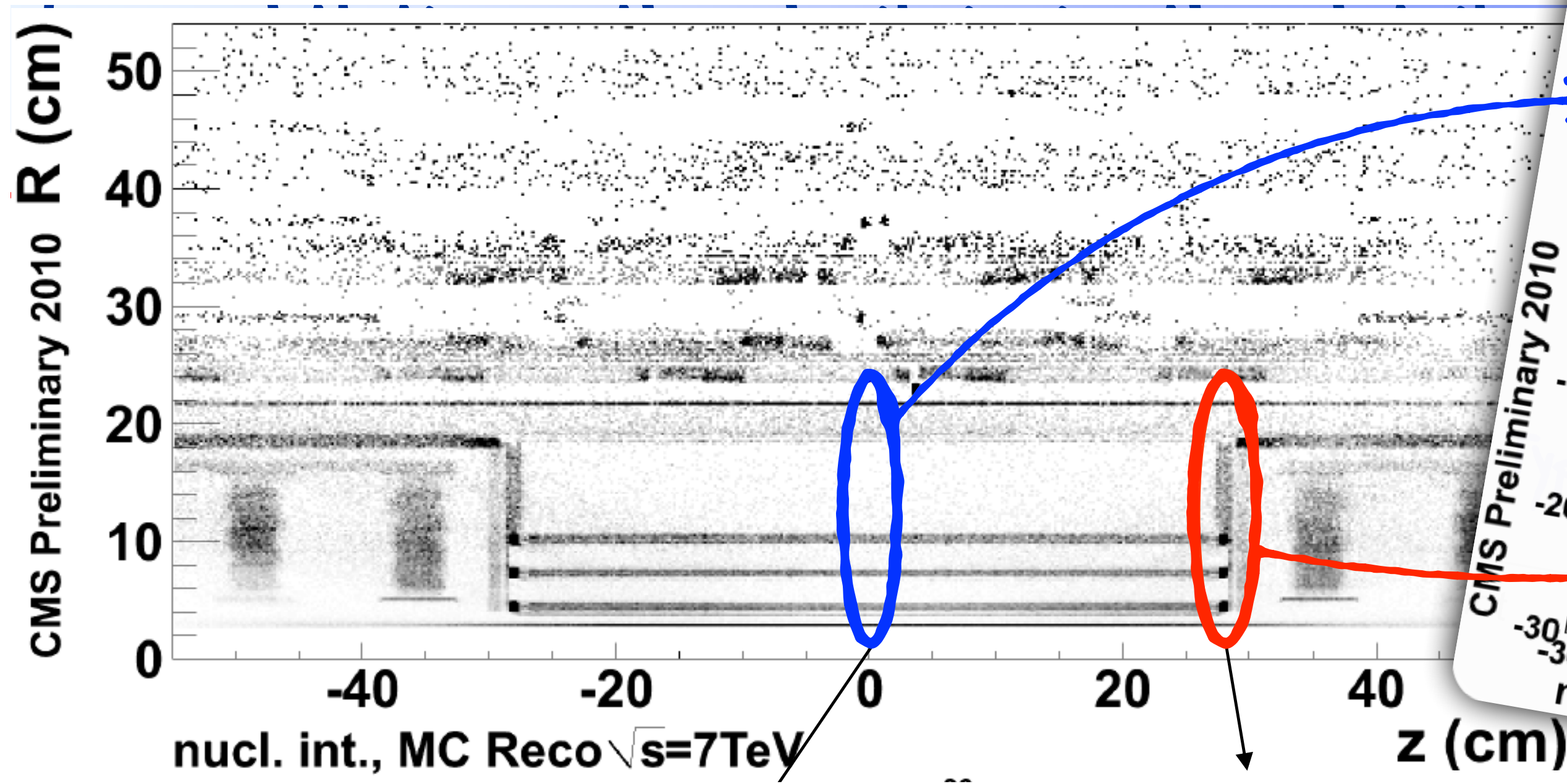
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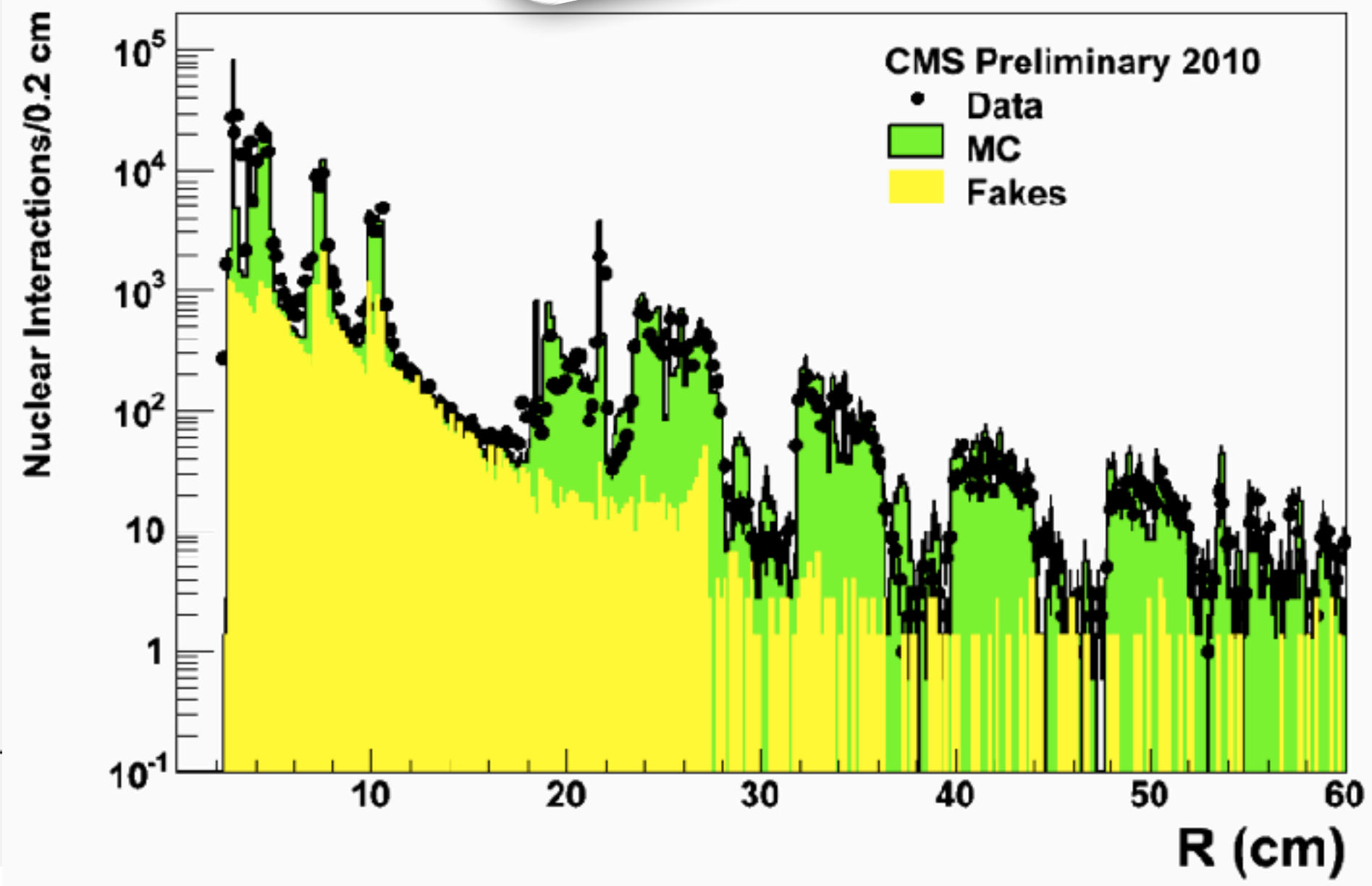
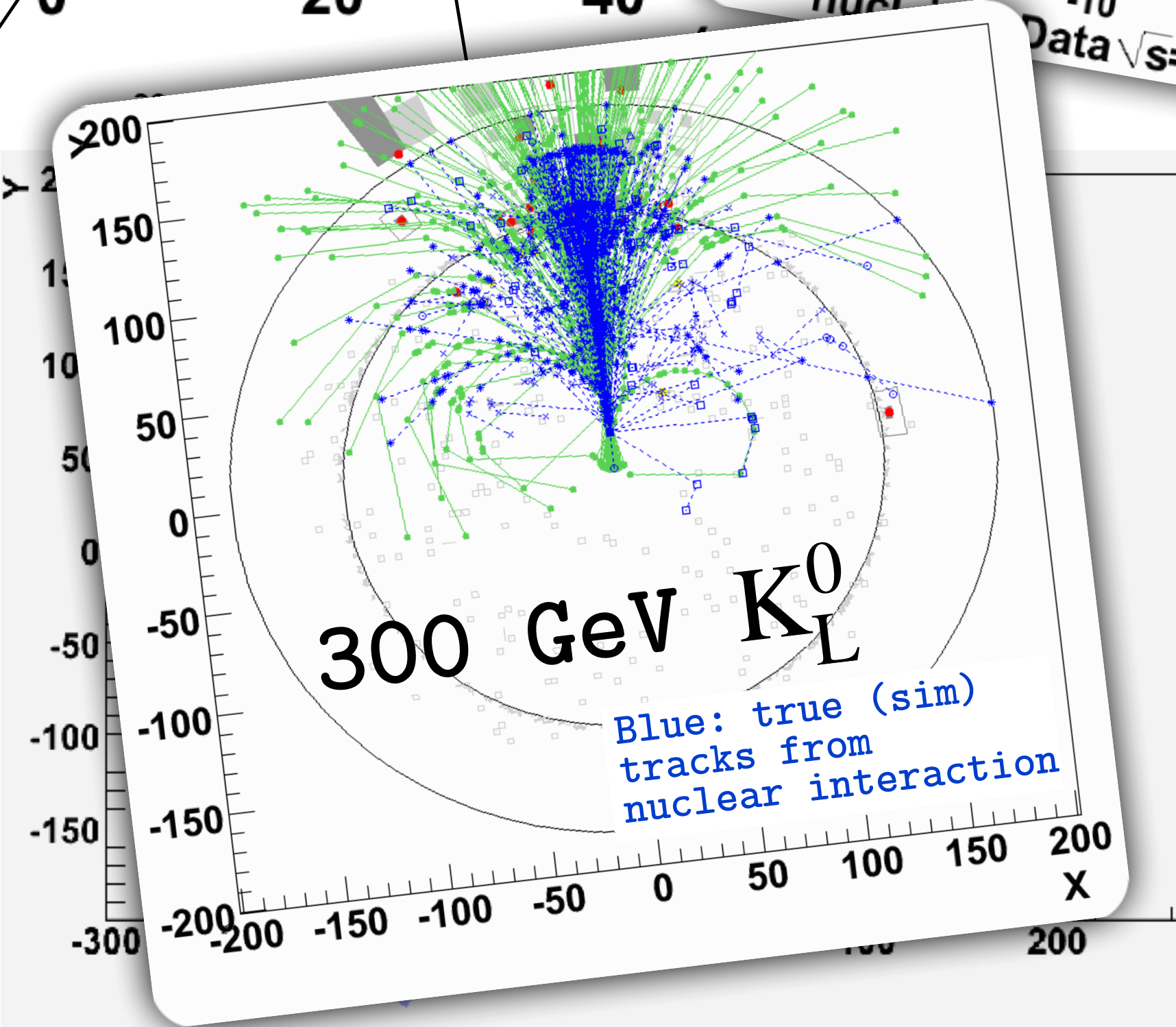
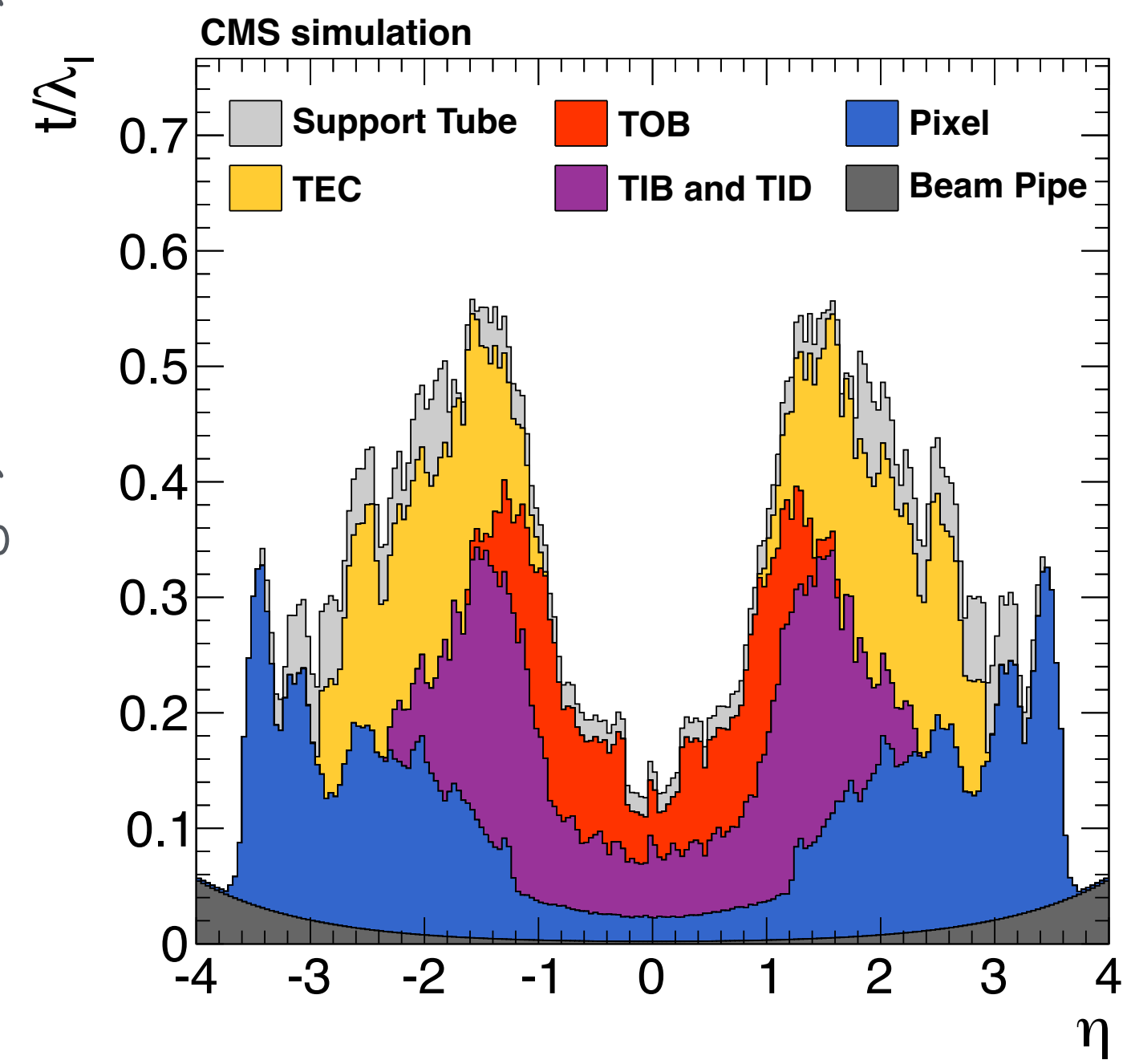
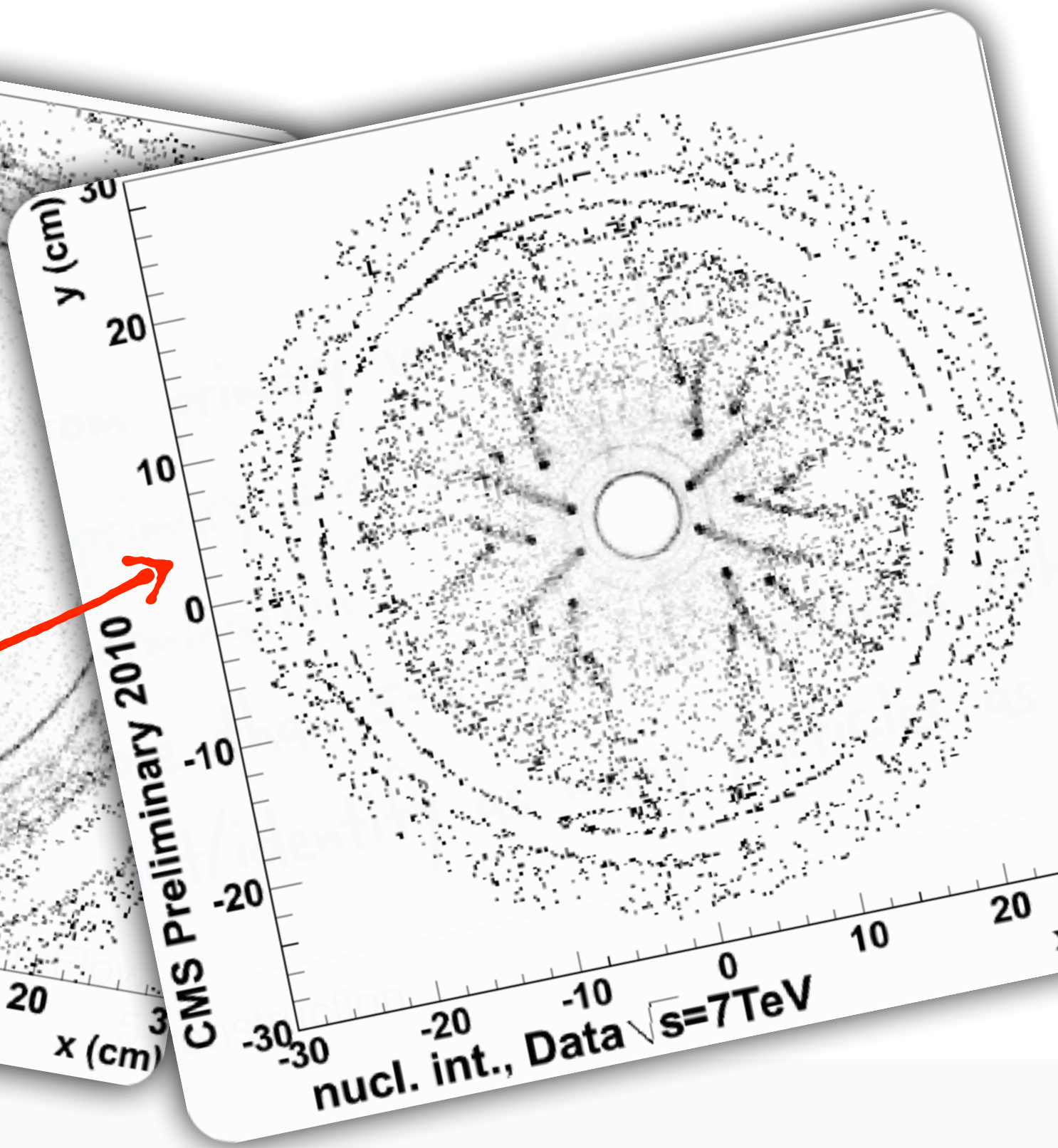
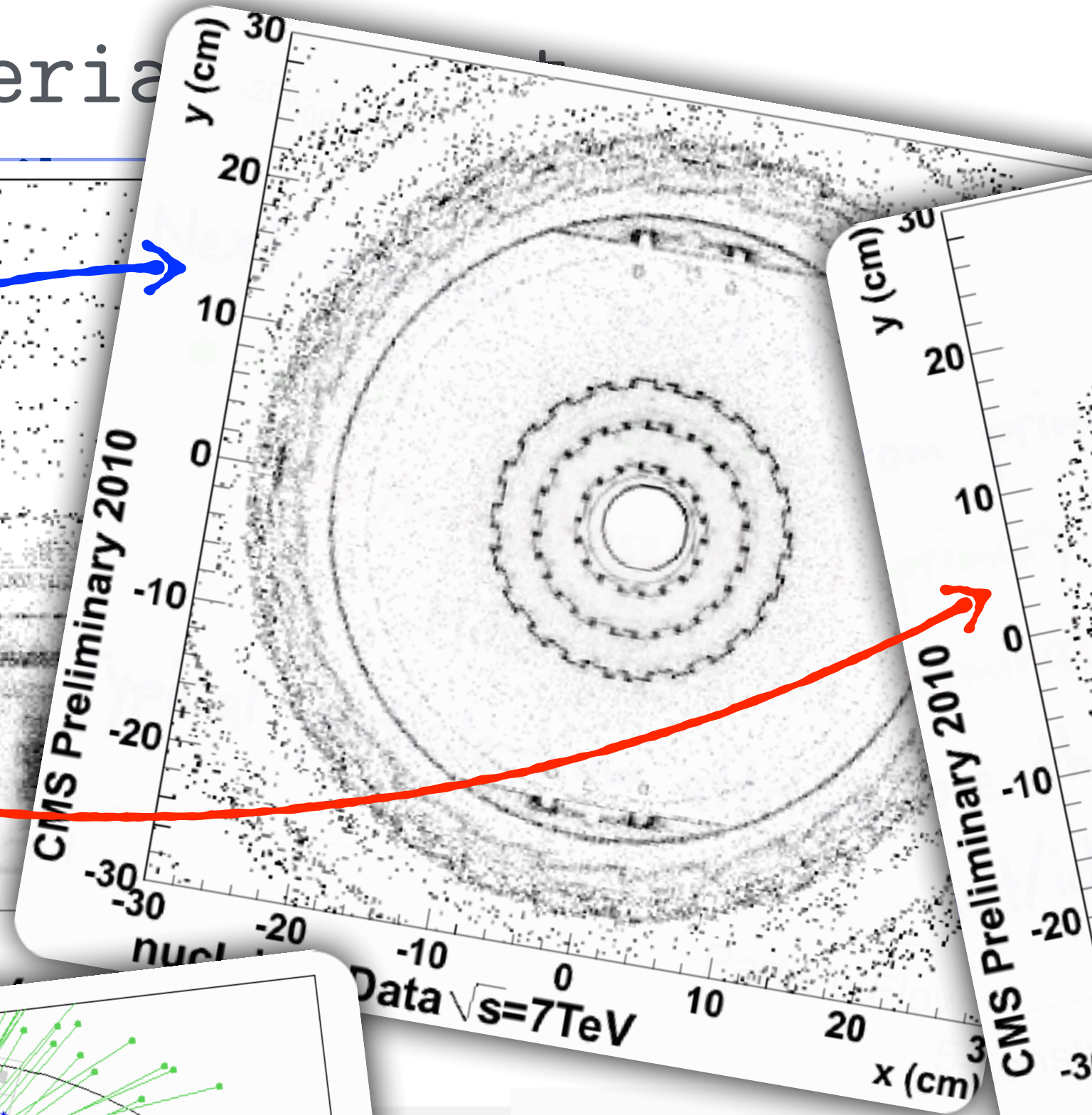
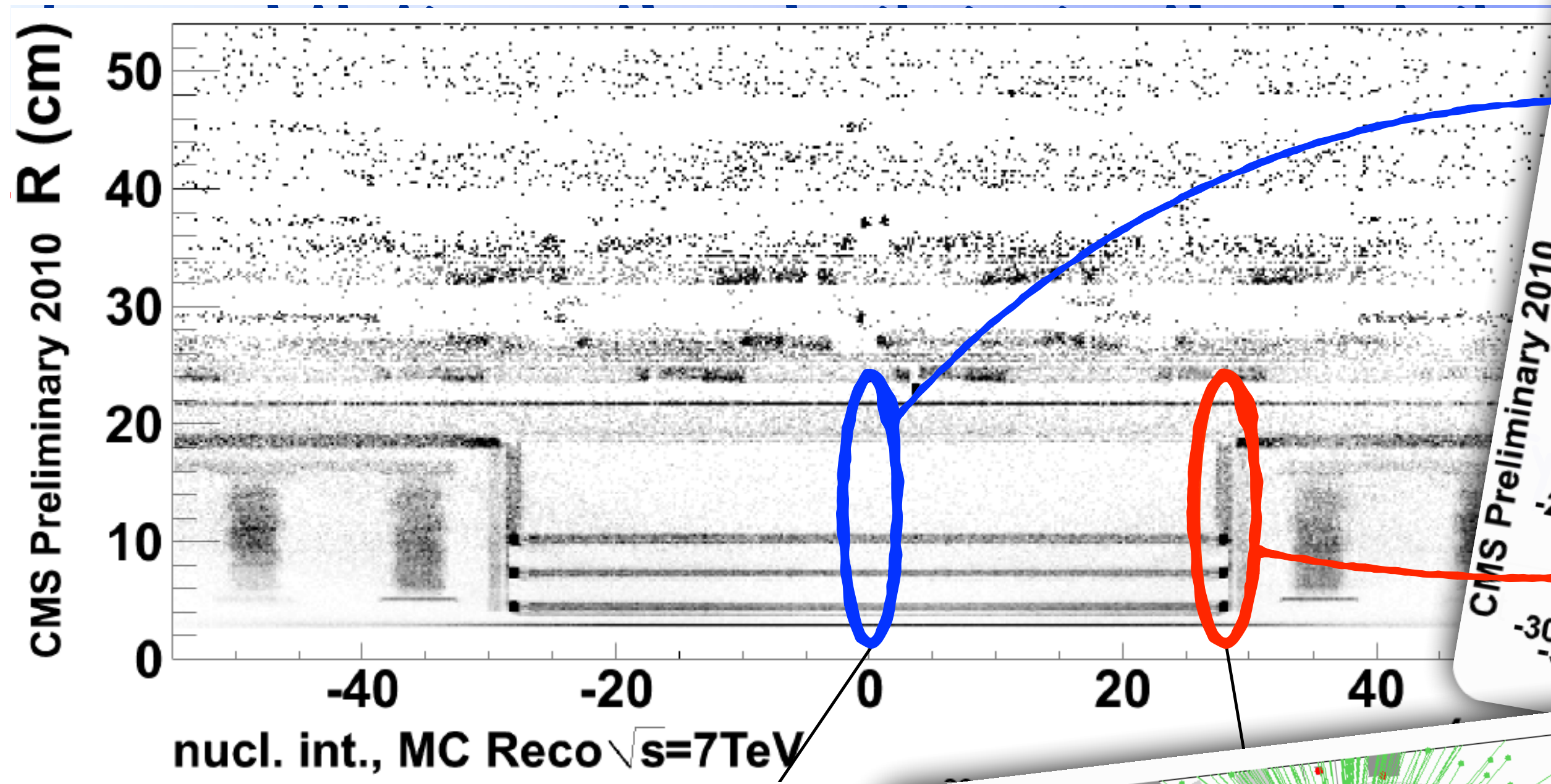
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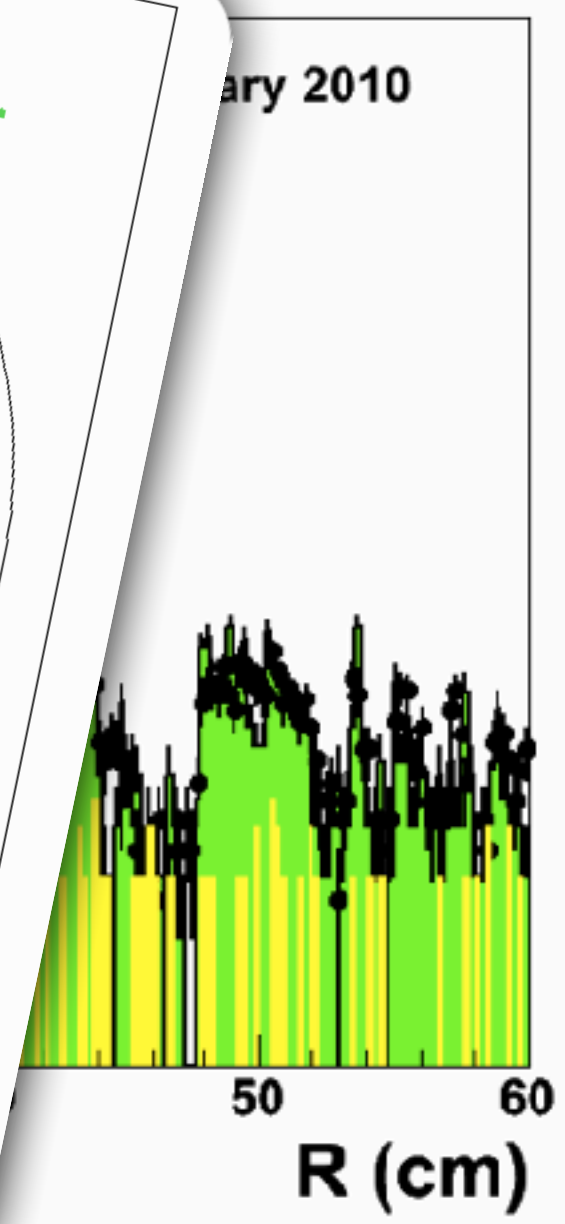
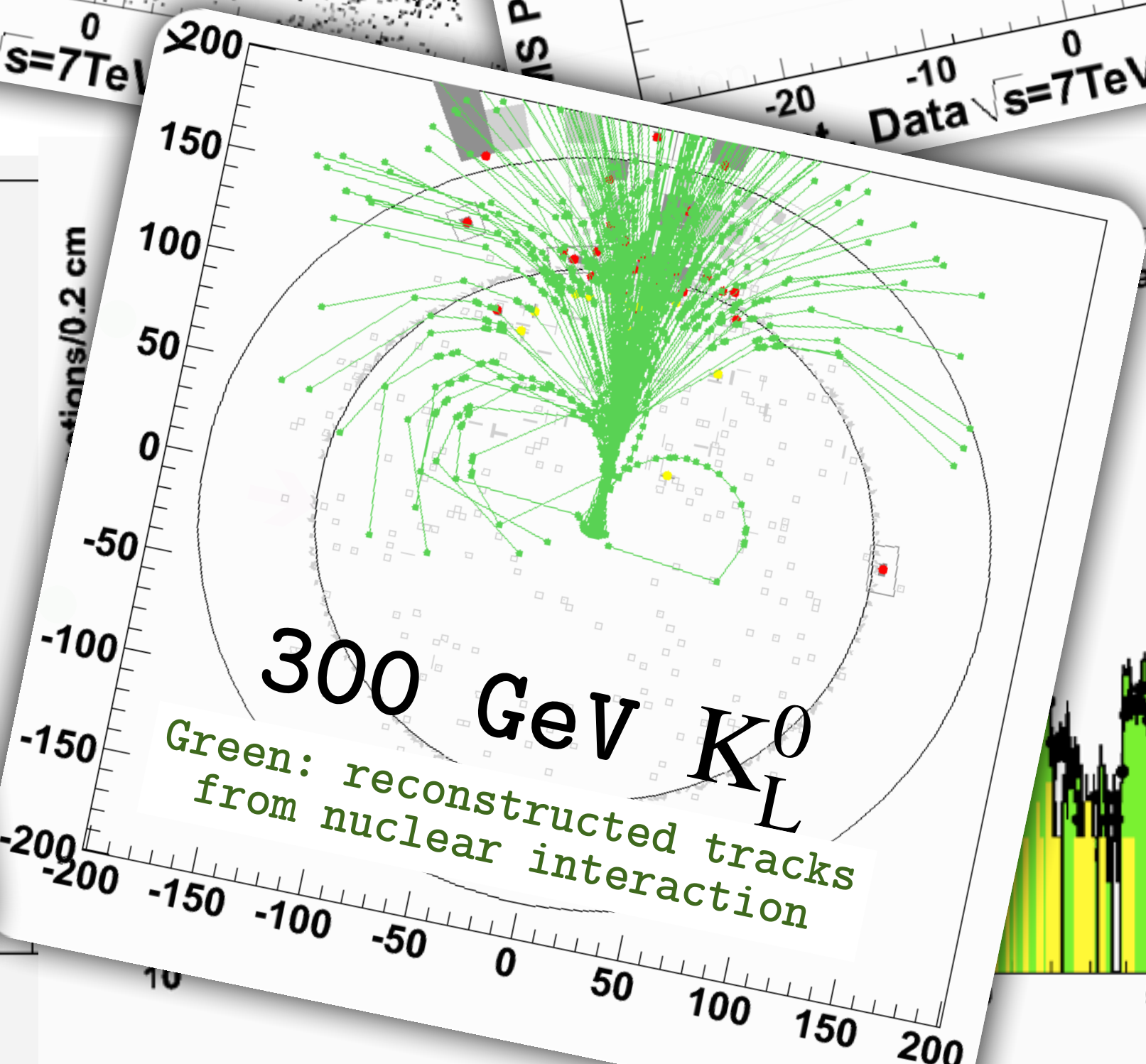
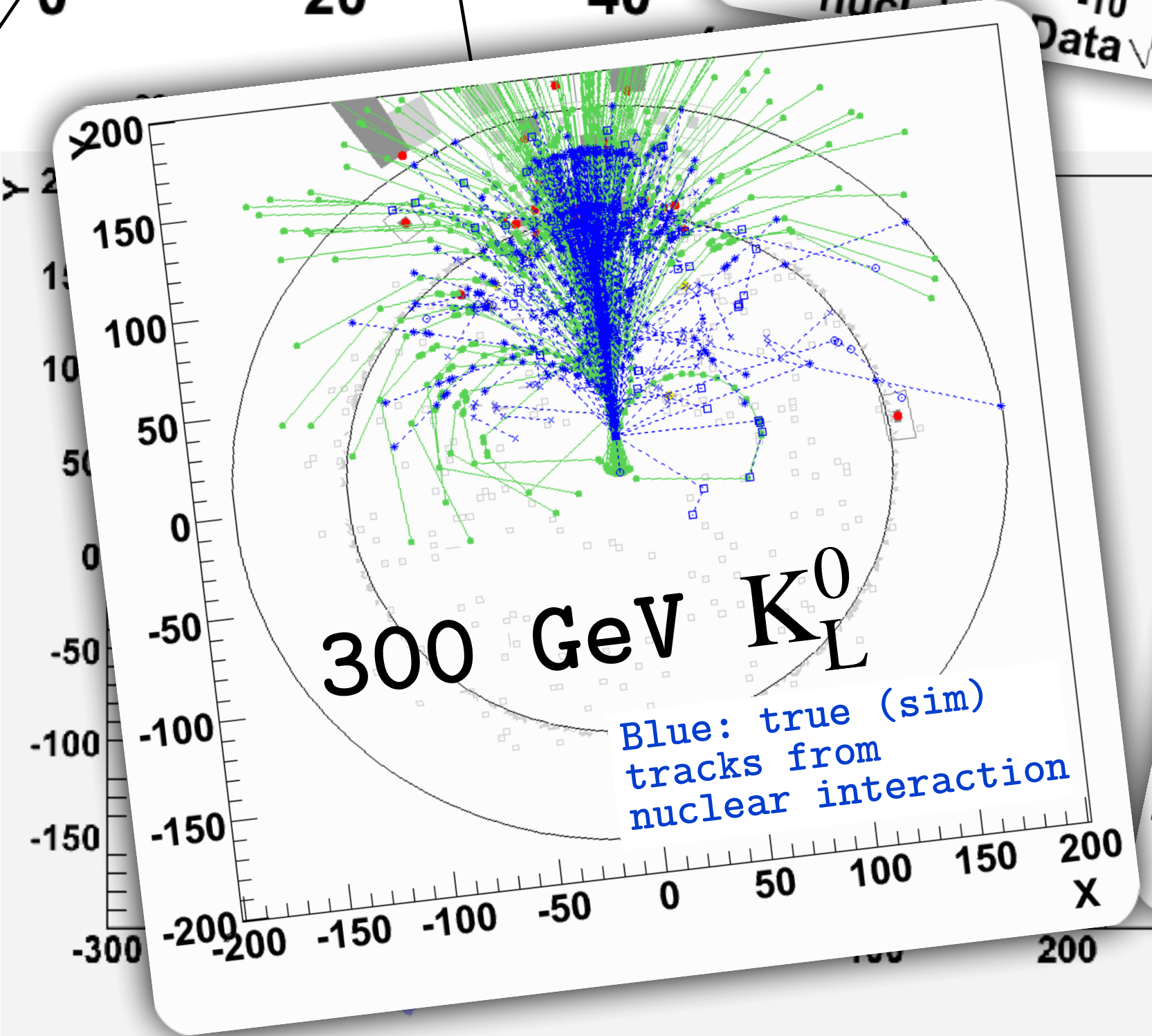
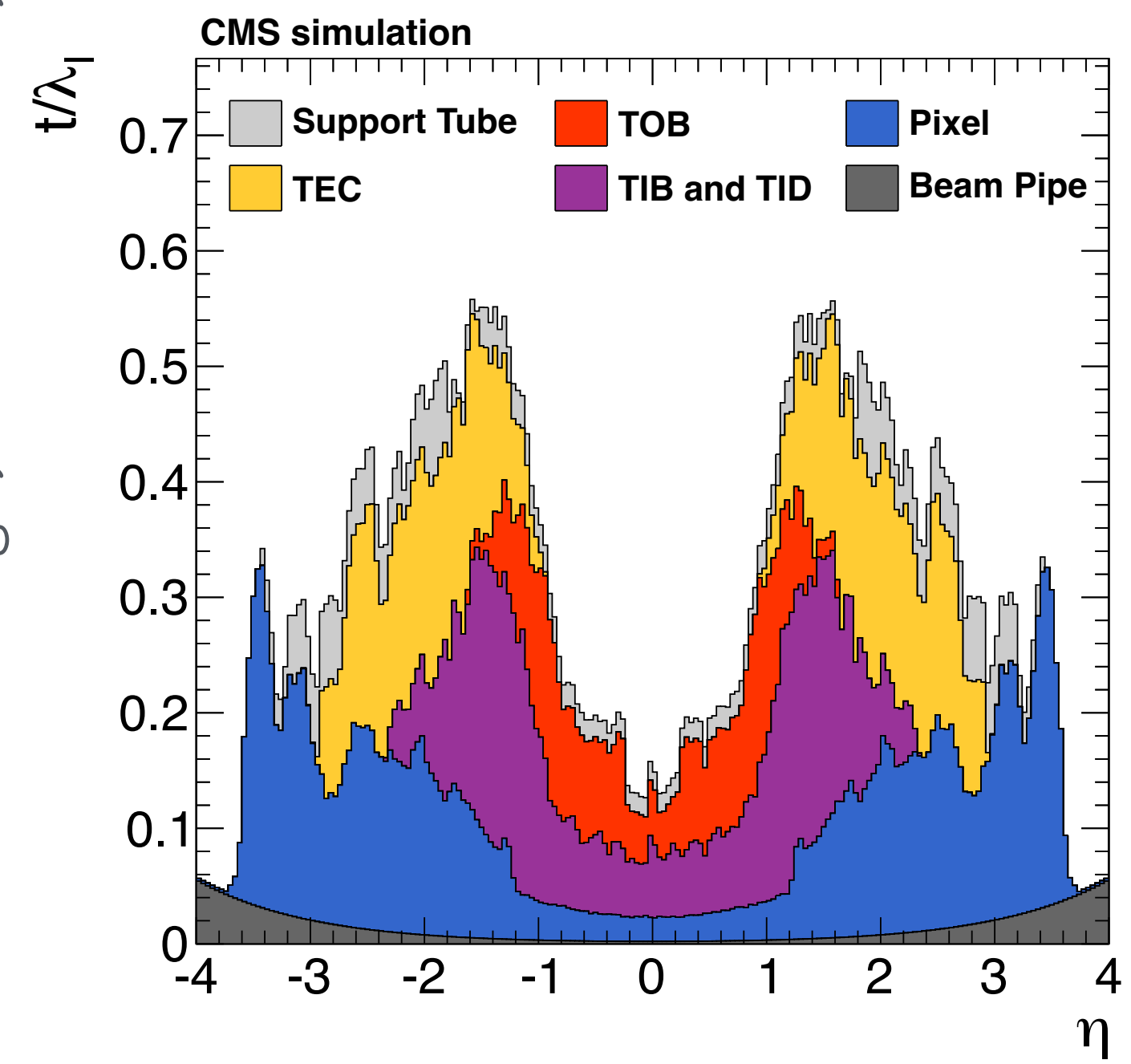
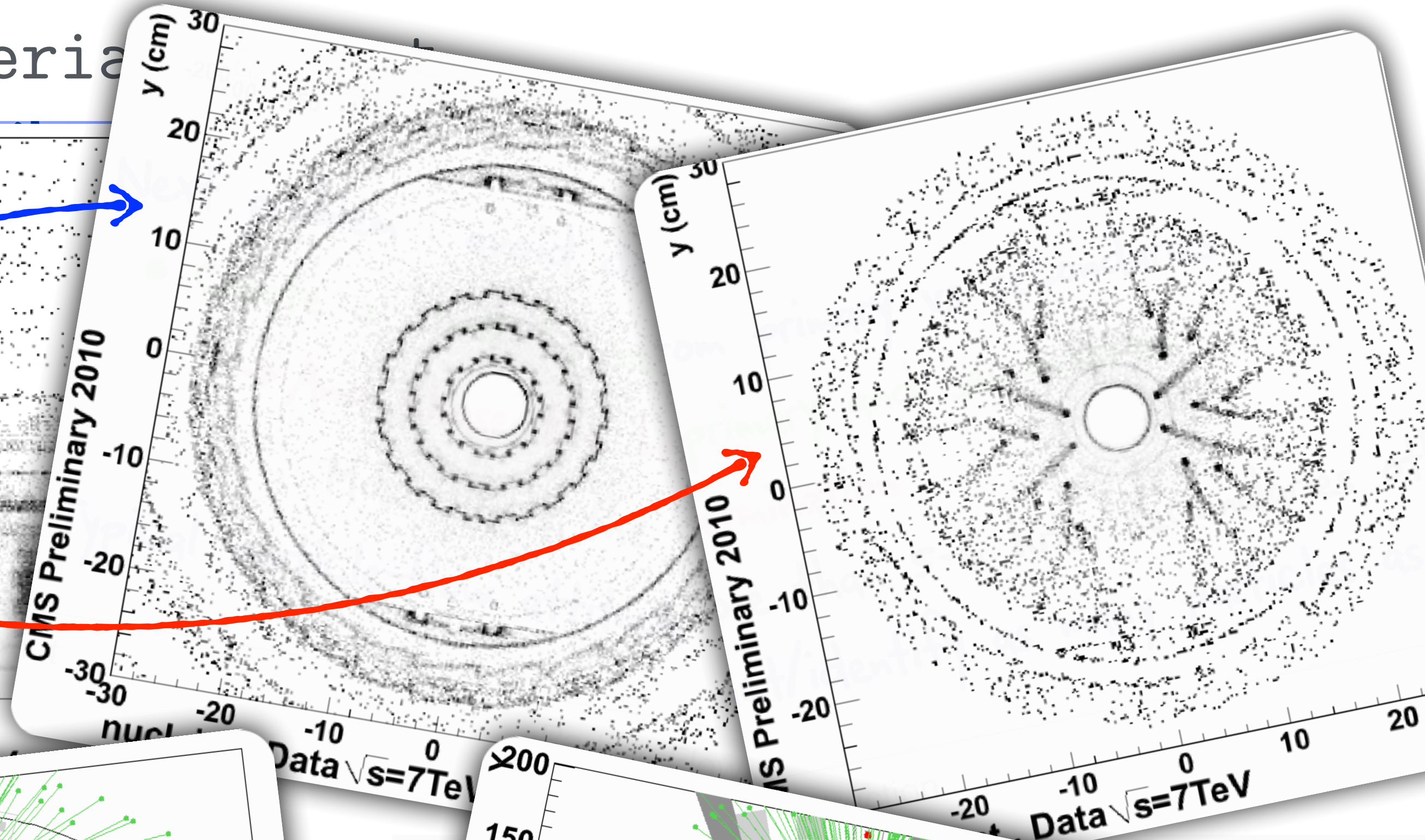
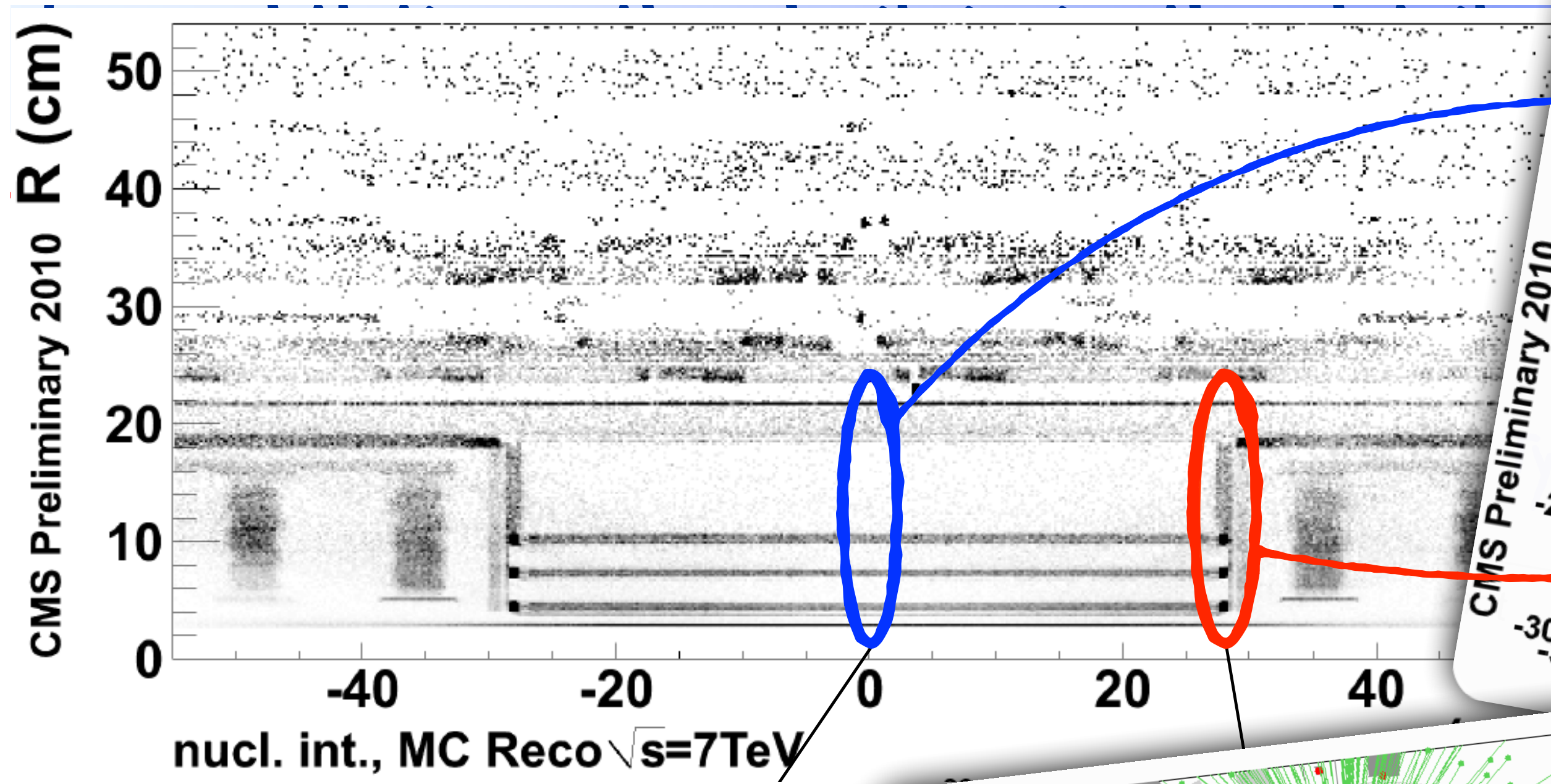
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Important details! Tracker Material



OK...I'll stop here