

# Extraction of Drell-Yan Angular Parameters in $pp$ Collisions with a 120 GeV Beam Energy Using a Deep-Learning Unfolding Algorithm

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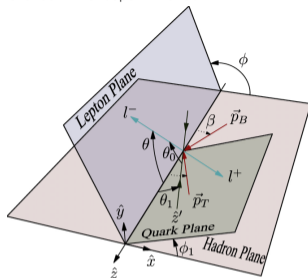
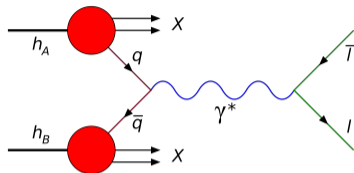
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Representing the FermiLab SeaQuest/E906 Collaboration  
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# Introduction

Definition of  $\phi$  and  $\cos\theta$  angles in the Collins-Soper frame.

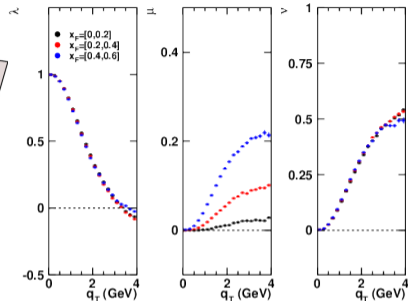


Drell-Yan angular cross-section;

$$\frac{d\sigma}{d\Omega} \propto 1 + \lambda \cos^2 \theta + \mu \sin 2\theta \cos \phi + \frac{\nu}{2} \sin^2 \theta \cos 2\phi$$

$\lambda$ ,  $\mu$ , and  $\nu$  angular parameters,  $\theta$  and  $\phi$  polar and azimuthal angles in the Collins-Soper frame

SeaQuest p+p at 120 GeV

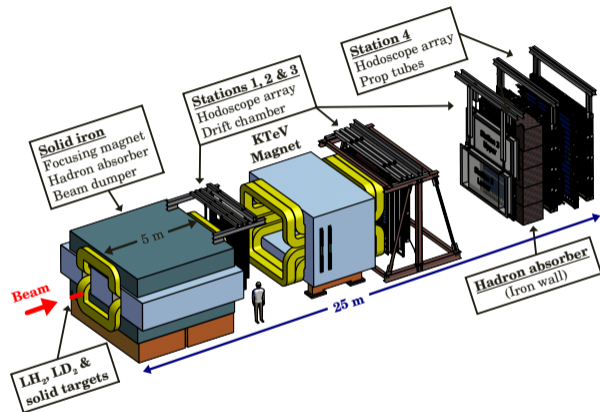


NLO pQCD predictions for  $\lambda$ ,  $\mu$ ,  $\nu$  as a function of  $q_T$  for SeaQuest experiment.<sup>1</sup>

<sup>1</sup>W.-C. Chang et al., *Phys. Rev. D* **99**, 014032, arXiv: 1811.03256 (hep-ph) (2019).

# SeaQuest/E906 Experiment

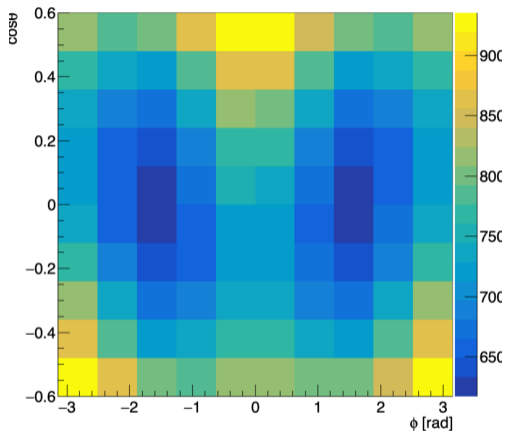
- ▶ Fixed target Drell-Yan experiment at Fermilab
- ▶ Use 120GeV beam energy from the main injector
- ▶ Measure the antiquark structure of the nucleon
- ▶ Provides unique access to the vanishing sea quark density at high  $x_B$
- ▶ Data collection was concluded in 2017



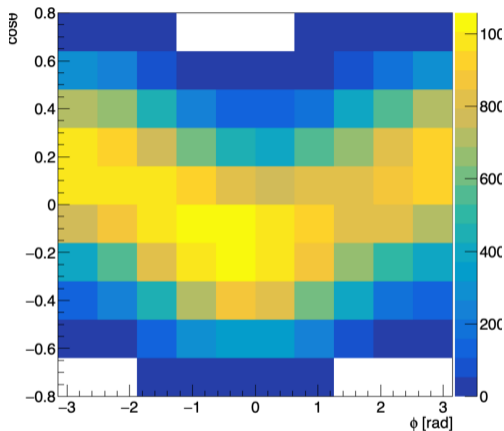
SeaQuest/E906 spectrometer.<sup>2</sup>

<sup>2</sup>C. A. Aidala et al., *Nucl. Instrum. Meth. A* **930**, 49–63, arXiv: 1706.09990 (physics.ins-det) (2019).

# Drell-Yan Angular Parameter Extraction



Simulated true level  $\cos\theta - \phi$  distributions with  $\lambda = 0.8, \mu = 0.1, \nu = 0.2$



Measured  $\cos\theta - \phi$  distributions with  $\lambda = 0.8, \mu = 0.1, \nu = 0.2$  using the reconstruction algorithm.

- Reco.  $\phi - \cos\theta$  distributions need to be corrected for detector effects (unfolding).

# Drell-Yan Angular Parameter Extraction

- ▶ Binned unfolding formulation;

$$\vec{m} = R\vec{t}$$

where  $\vec{m}$  is the measured distribution (reconstructed),  $\vec{t}$  is the true distribution (generated), and  $R$  is the response matrix given by:

$$R = Pr(\text{measured } i | \text{truth is } j)$$

- ▶ In general,  $R$  is not invertible. i.e., the unfolding problem does not have a unique solution.
- ▶ One common approach to address this problem is iterative Bayesian unfolding (IBU).<sup>3</sup>
- ▶ In higher dimensions, these binned methods do not scale well.

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<sup>3</sup>G. D'Agostini, *Nucl. Instrum. Meth. A* **362**, 487–498 (1995).

# Drell-Yan Angular Parameter Extraction

- ▶ We need to build a unbinned model achieving;
  - ▶ Background subtraction: Neural Positive Reweighting<sup>4</sup>
  - ▶ Corrections for detector smearing/detector efficiencies: OmniFold<sup>5</sup>
  - ▶ Parameter extraction using maximum likelihood estimation: RooFit<sup>6</sup>
- ▶ We use likelihood ratio estimators to iteratively calculate the weights in the unbinned unfolding method.<sup>7</sup>
- ▶ Let  $s$  be a classifier (a deep neural network) trained to distinguish samples drawn from  $p(x|\beta_0)$  and  $p(x|\beta_1)$ . Then, the likelihood ratio can be approximated as;<sup>8</sup>

$$\mathcal{L}(x) = \frac{p(x|\beta_0)}{p(x|\beta_1)} \approx \frac{s(x)}{1 - s(x)} \quad (1)$$

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<sup>4</sup>B. Nachman, J. Thaler, *Phys. Rev. D* **102**, 076004, arXiv: 2007.11586 (hep-ph) (2020).

<sup>5</sup>A. Andreassen et al., *Phys. Rev. Lett.* **124**, 182001, arXiv: 1911.09107 (hep-ph) (2020).

<sup>6</sup>W. Verkerke, D. P. Kirkby, *eConf C0303241*, ed. by L. Lyons, M. Karagoz, MOLT007, arXiv: physics/0306116 (2003).

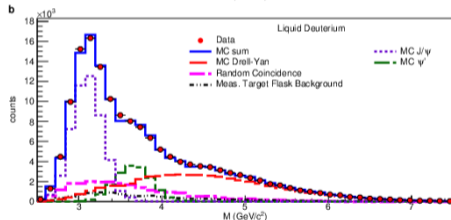
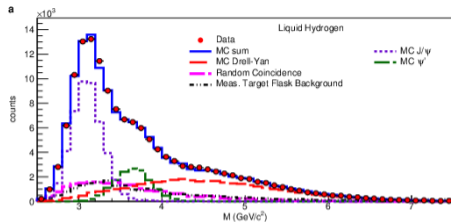
<sup>7</sup>K. Cranmer et al., arXiv: 1506.02169 (stat.AP) (June 2015).

<sup>8</sup>S. Rizvi et al., *JHEP* **02**, 136, arXiv: 2305.10500 (hep-ph) (2024).

# Case Study

- ▶ To demonstrate the unbinned unfolding method, we use the SeaQuest/E906 simulation framework to generate Monte Carlo (MC) events. These events are;
  - ▶ Generated using the PYTHIA event generator.
  - ▶ Generated events were then passed through the SeaQuest/E906 detector simulation (using GEANT4) to obtain the reconstructed detector information.
- ▶ Data set features;

Type	$\lambda$	$\mu$	$\nu$
Simulation	1.	0.	0.
Pseudo data	0.8	0.1	0.2
Background	0.5	-0.2	-0.1



SeaQuest MC data is in good agreement with real data.<sup>9</sup>

<sup>9</sup>J. Dove et al., *Nature* **590**, [Erratum: *Nature* 604, E26 (2022)], 561–565, arXiv: 2103.04024 (hep-ph) (2021).

# Model Summary

- ▶ Background subtraction;

$$\omega_1 : X^{\text{pseudo data with background}} \rightarrow X^{\text{pseudo data with no background}}$$

- ▶ Unfolding;

$$\omega_2 : X^{\text{simulation reconstructed}} \rightarrow X^{\text{pseudo data reconstructed}}$$

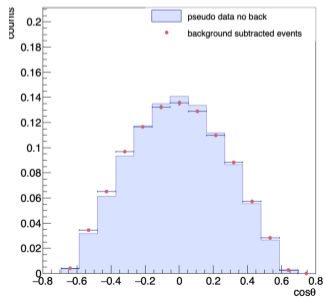
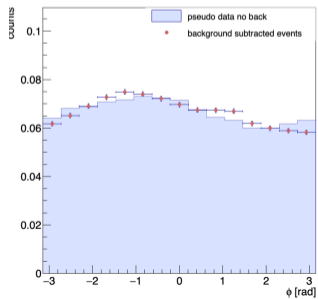
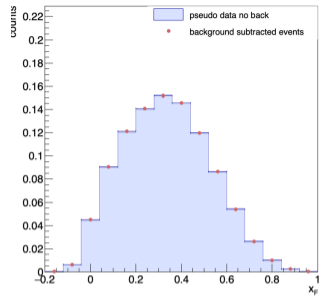
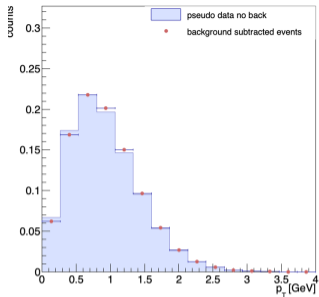
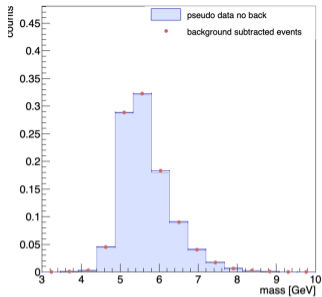
$$\omega_3 : X^{\text{simulation truth}} \rightarrow X^{\text{pseudo data truth}}$$

- ▶ Parameter extraction;

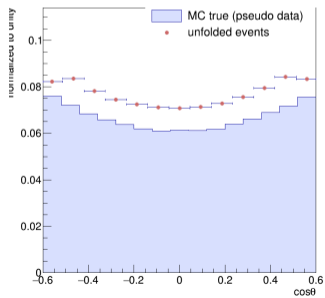
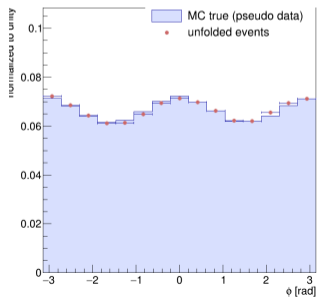
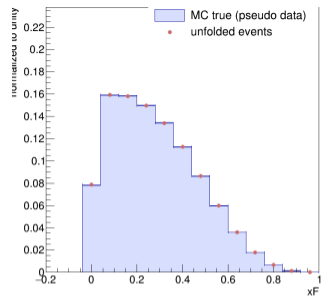
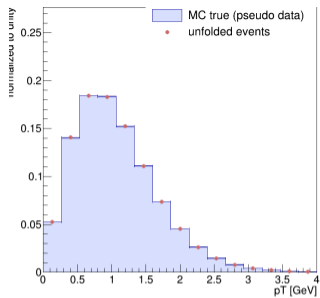
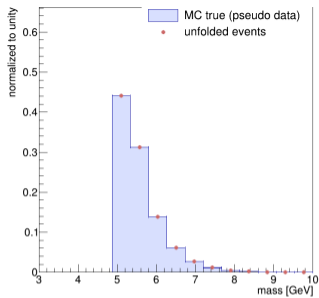
$$\ln(\mathcal{L}) = \sum_i \omega_i \ln[1 + \lambda \cos^2 \theta + \mu \sin 2\theta \cos \phi + \frac{\nu}{2} \sin^2 \theta \cos 2\phi]$$

where  $\omega_i$  are the weights calculated during the unfolding process.

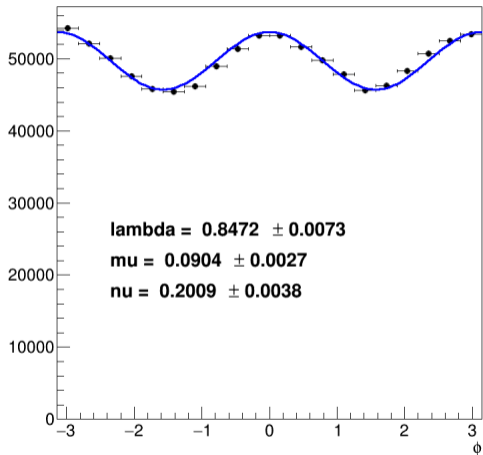




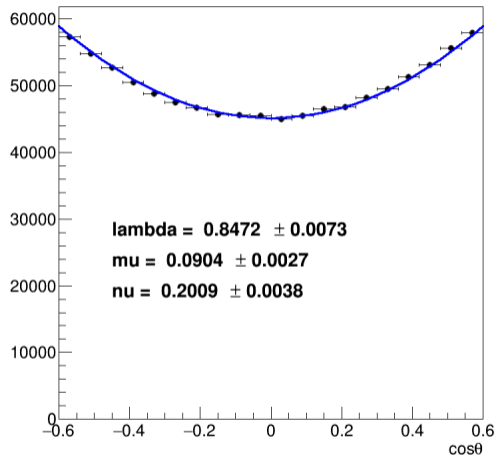
Background subtracted events.



Unfolded events.



Injected values  
 $\lambda = 0.8, \mu = 0.1, \nu = 0.2$



Extracted Angular Parameters Using Maximum Likelihood Estimation

# Neural Network Architecture

- ▶ We use feedforward deep neural network for;

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Num. linear layers	5
Num. of nodes per hidden layer	50
Activation function hidden layers	ReLU
Num. of batch normalization layers	5
Num. of dropout layers	2 ( $p = 0.2$ )
Final activation layer	Sigmoid
Early stopping patience	10
Learning rate	0.001
Optimizer	Adam
Criterion	weighted BCE
Input features	mass, $p_T$ , $x_F$ , $\phi$ , $\cos\theta$

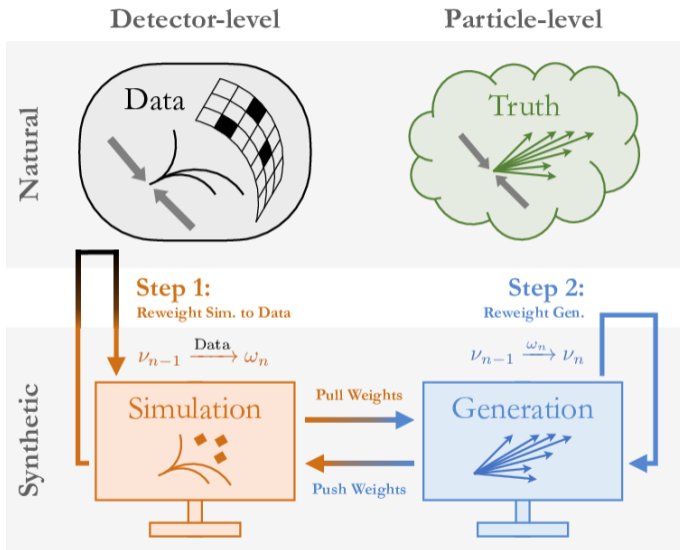
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- ▶ All the models are implemented using the PyTorch framework and trained with NVIDIA A100 GPUs in the Fermilab Elastic Analysis Facility.

## Summary

- ▶ The Drell-Yan process is an important experimental approach to exploring the partonic structure of nucleons.
- ▶  $\nu$  provides important information about the intrinsic transverse momentum of partons.
- ▶ Deep neural networks are excellent candidates for likelihood estimators due to their feature of approximating complex non-linear functions.
- ▶ We can use deep neural networks to unfold the measured (reconstructed) distributions to true distributions.
- ▶ Unbinned maximum likelihood estimation can be used to extract the Drell-Yan angular parameters with high accuracy.
- ▶ Acknowledgement: This work was supported in part by US DOE grant DE-FG02-94ER40847.

# Unfolding: OmniFold



## Maximum Likelihood Estimation: RooFit

- ▶ Consider the log likelihood function;

$$\ln(\mathcal{L}) = \sum_i \omega_i \ln[1 + \lambda \cos^2 \theta + \mu \sin 2\theta \cos \phi + \frac{\nu}{2} \sin^2 \theta \cos 2\phi]$$

where  $\omega_i$  are the weights calculated during the unfolding process.

- ▶ Optimal values for  $\lambda$ ,  $\mu$  and  $\nu$  can be extracted by minimizing  $-\ln(\mathcal{L})$ .

# Background subtraction

- ▶ Consider the following event types;

Type	weight	sign
Pseudo data + background ( $x^{\text{data with back}}$ )		+
Background ( $x^{\text{back}}$ )		-

- ▶ Typically, the background is combinatorics and it is calculated using the event mixing method.<sup>11</sup>
- ▶ We train a classifier ( $\hat{S}_{\text{back}}(x^{\text{data with back}}, x^{\text{back}})$ ) to distinguish  $x^{\text{data with back}}$ , ( $y = 1$ ) and  $[x^{\text{data with back}}, x^{\text{back}}]$ , ( $y = 0$ ) events with the weights. Then weights for the background subtracted events are;

$$W_{x^{\text{data with back}} \rightarrow x^{\text{data no back}}} = \frac{\hat{S}_{\text{back}}(x^{\text{data with back}}, x^{\text{back}})}{1 - \hat{S}_{\text{back}}(x^{\text{data with back}}, x^{\text{back}})}$$

<sup>11</sup>S. F. Pate et al., arXiv: 2302.04152 (hep-ex) (Feb. 2023).