

GRAIN: Status & progress of GRAIN Working group

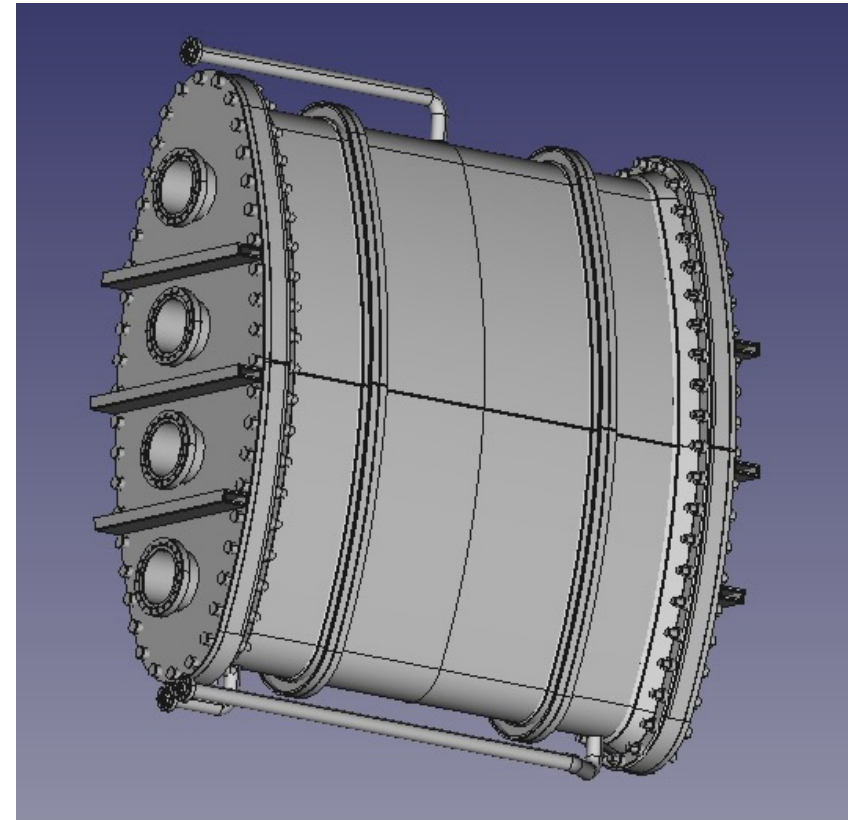
Conveners: Lea Di Noto – Univ. and INFN Genova
Alessandro Montanari- INFN Bologna

SAND General meeting,
May, 14th 2024

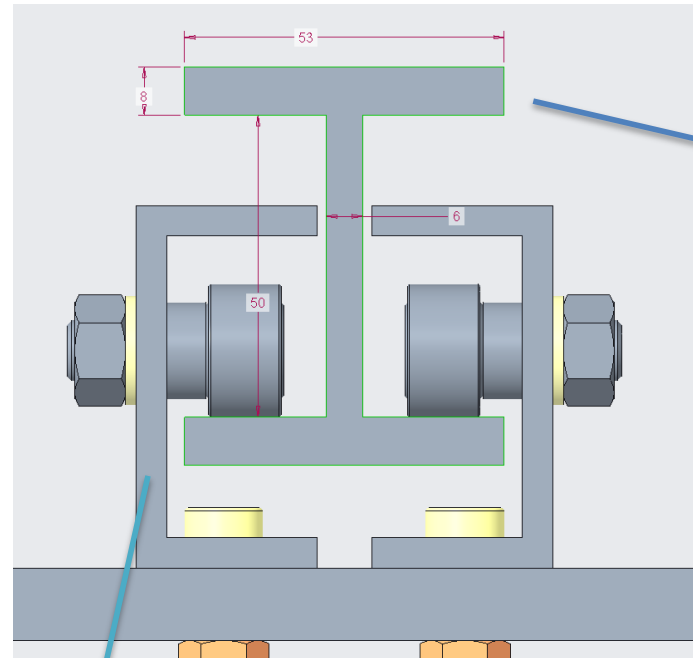
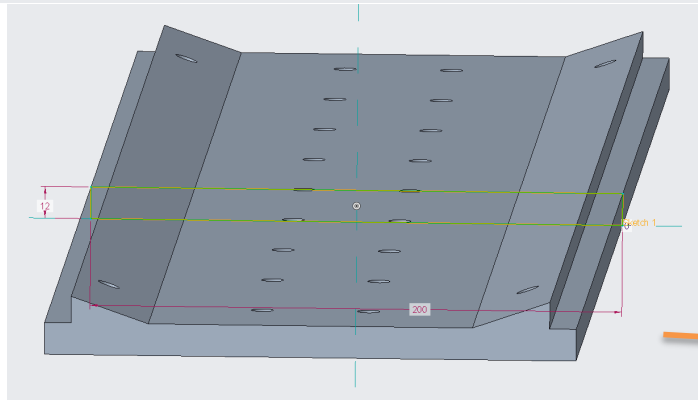
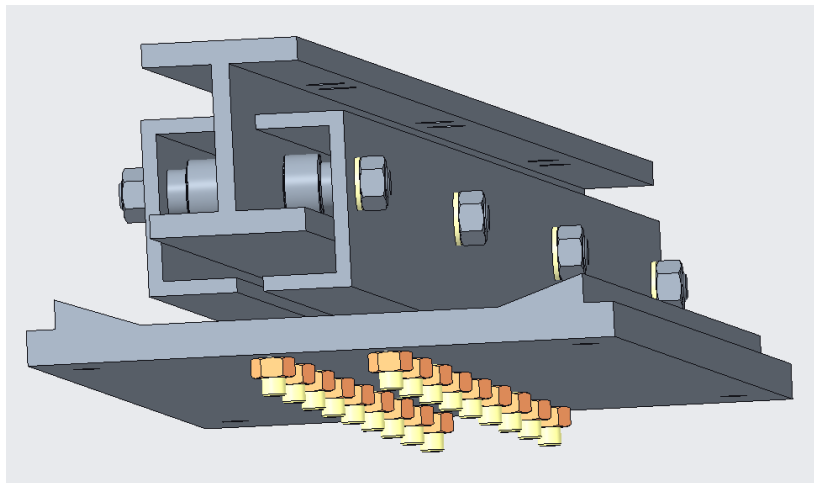


Inner Vessel Design

- Material:
 - Stainless Steel 316L seems adequate for our application
- Covers:
 - 30 mm thickness
- Simulation of Helicoflex sealing under way



Sliding System



IPE beam like:

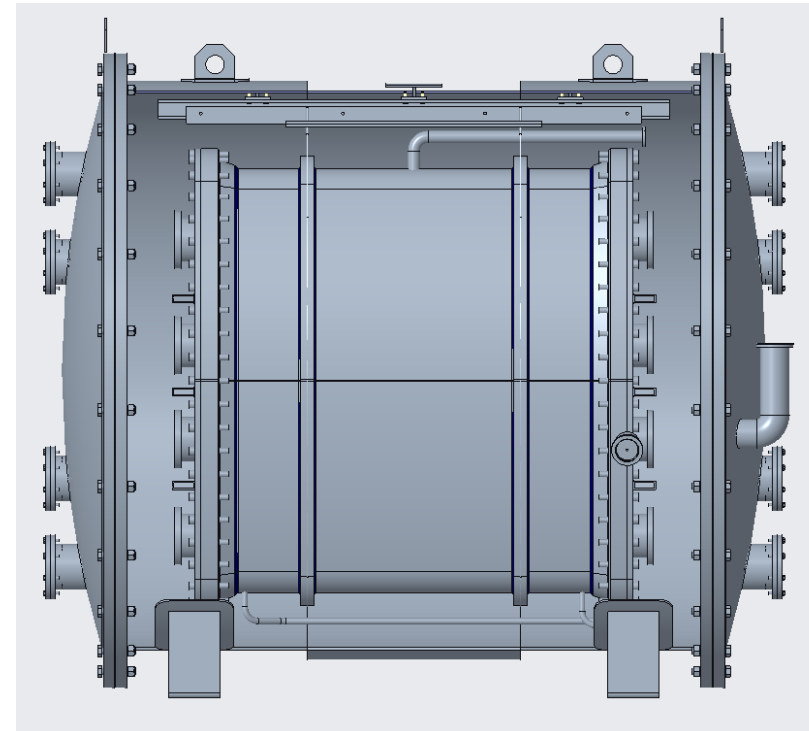
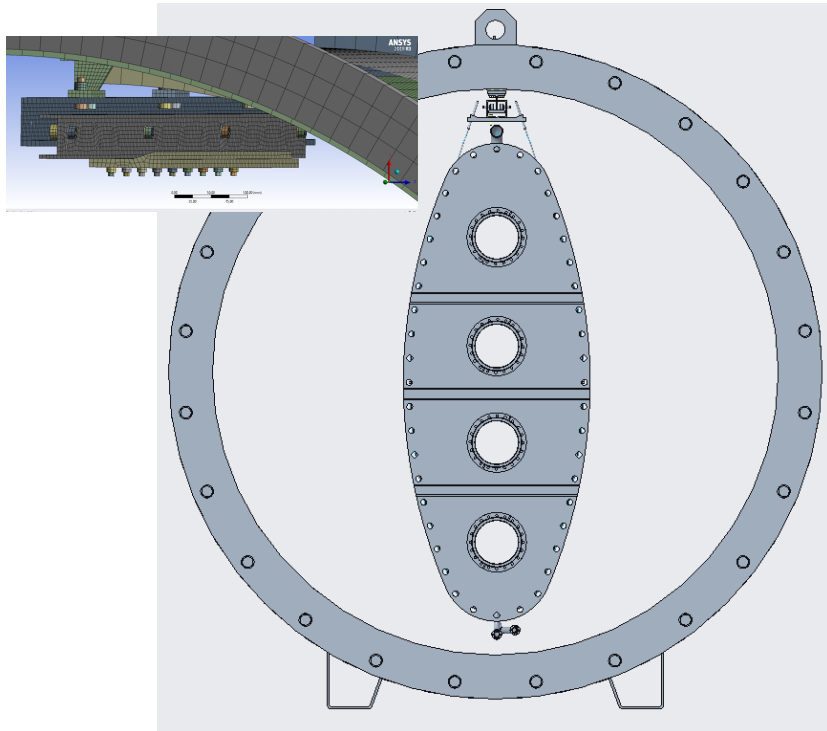
$h=66$ mm
 $b=53$ mm
 $t_f=8$ mm
 $t_w=6$ mm
 $L=1800$ mm

C beam IPA hot rolled, dimensions:
 $60 \times 30 \times 5$ mm, 1600 mm long

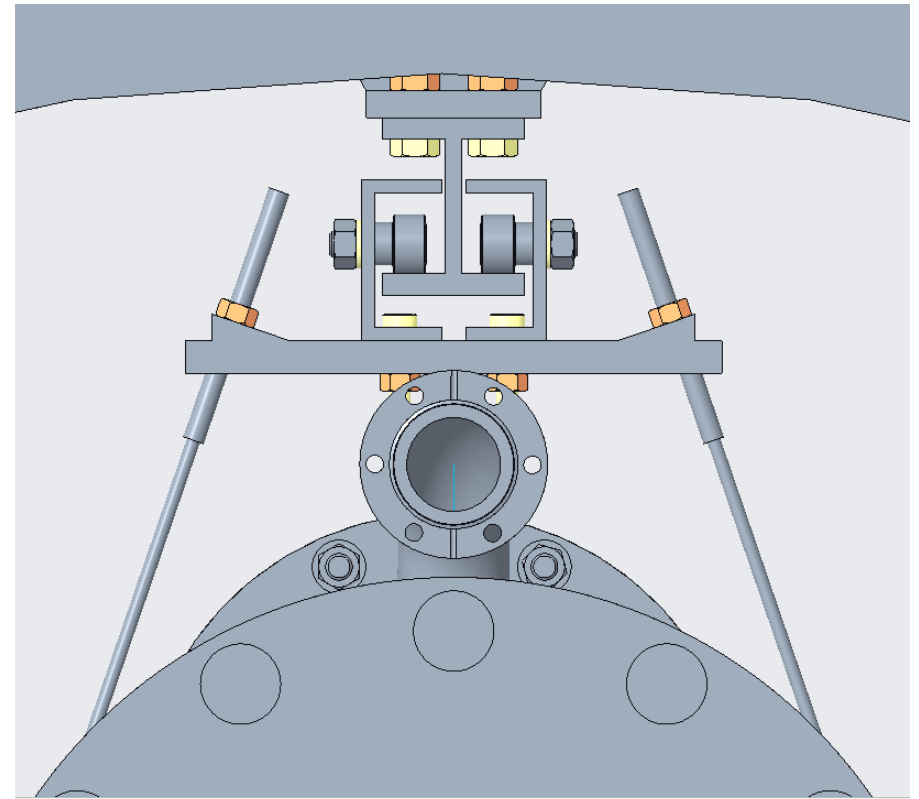
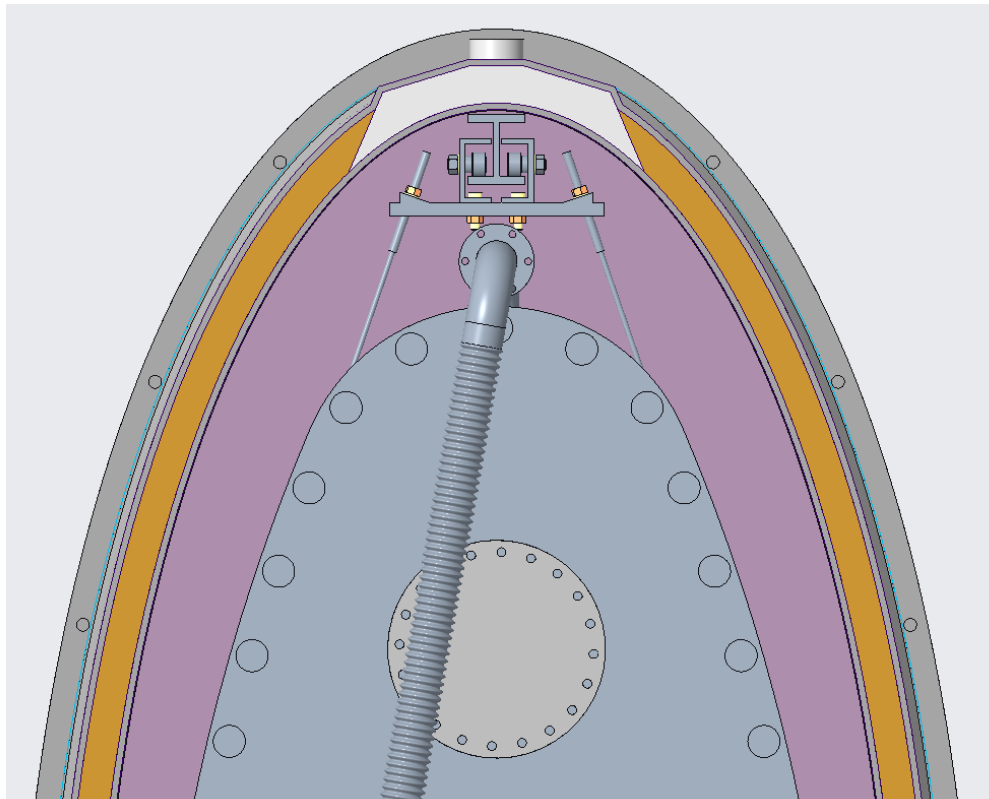
Plate $200 \times 12 \times 900$ mm

Montanstahl can produce
laser welded customised profiles
in 316L
1500 € for 3000 mm ca

Sliding inside Vacuum Tank in Legnaro



Sliding inside final External Vessel



Test Facility in Legnaro

- Refurbishment of old lines is under way
- Components of Control System have been delivered. Assembly must be done by an electrician
- Cryogenic complete scheme is preliminary designed:
 - Identify a unique company that will produce and certify the whole system
 - Only one tender with delivery split into different batches
- Meeting on 28 May at 14:00 with new LNL Director
(R.Pengo, M.Pallavicini, S.Bertolucci, L.Patrizii, A.Montanari, L.Di Noto, G. Piazza, A.Mengarelli).

Electronics

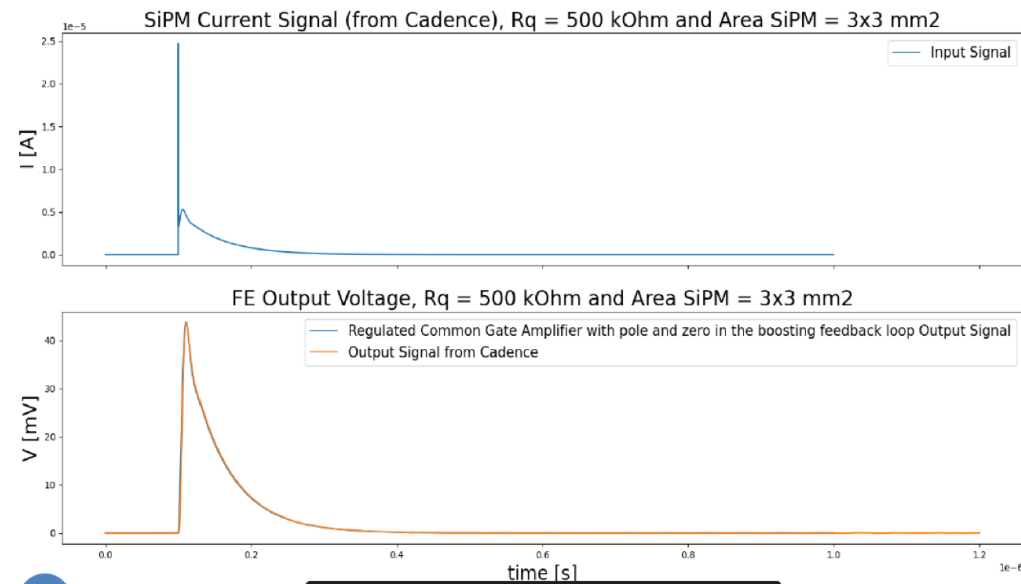
- Torino group has started to design a dedicated ASIC for GRAIN
 - A. Rivetti, M. Da Rocha Rolo, S. Durando (Post-doc), S. Blua (PhD), V. Pagliarino (master student)

Torino group is producing a reliable simulation of the signal shaping and digital processing from SiPM signal to the readout data



Front End simulation

(using Alcor Transfer function)



Current studies for electronics design

Architecture with few integrators for each pixel for each spill

- For each integrator we record:
 - Time with $O(100 \text{ ps})$ resolution for rising edge on a 0.5 pe threshold,
 - Time with $O(2 \text{ ns})$ resolution for falling edge
 - number of photons during the integration window
- Parameters under study for the ASIC design:
 - Number of integrators for each channel
 - Dynamic range for each channel (maximum number of photons)
 - SiPM parameters (quenching resistor, SiPM size, ..)

Genova and Bologna groups are studying the GRAIN performance with coded mask or lens for:

- tracking reconstruction
- calorimetric reconstruction
- multiple event identification

Number of capacitors

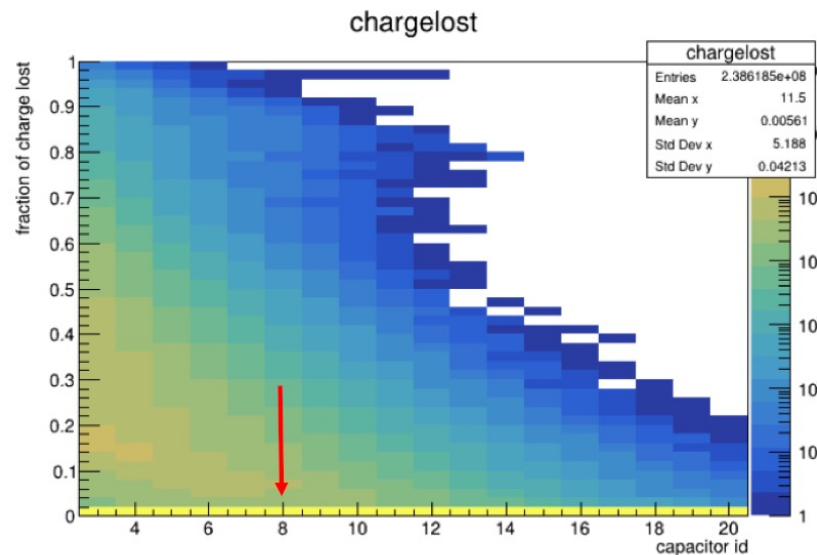
from spill simulations with coded masks

Fraction of lost charge per number of capacitors

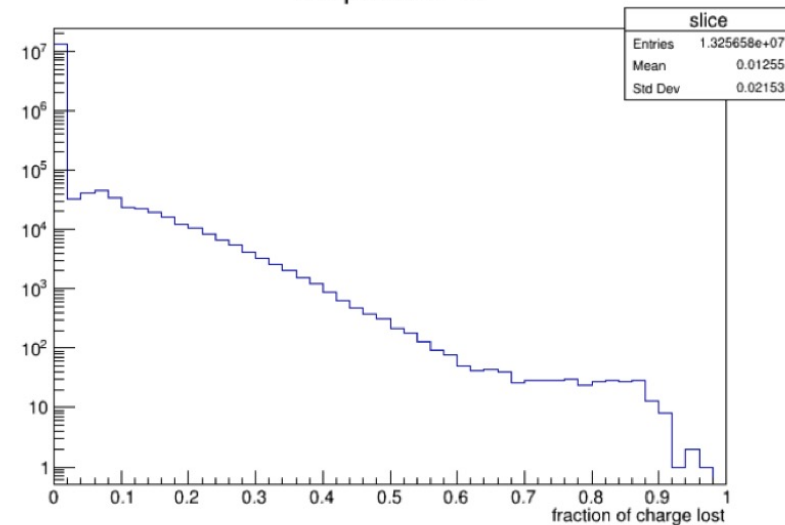
Rq = 2000 kOhm

$$Q_{lost} = \frac{\sum_{c>n} (n \text{ integrated photons})_c}{\text{total integrated photons}}$$

ALL cameras



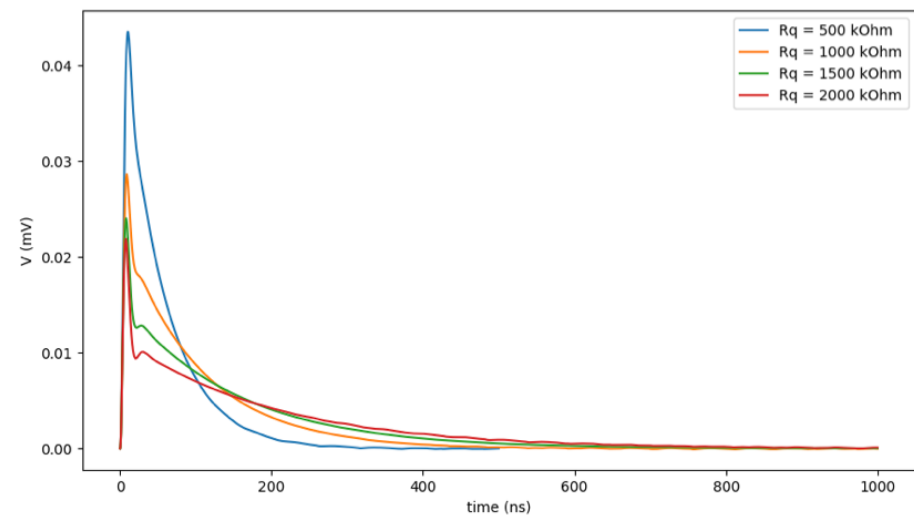
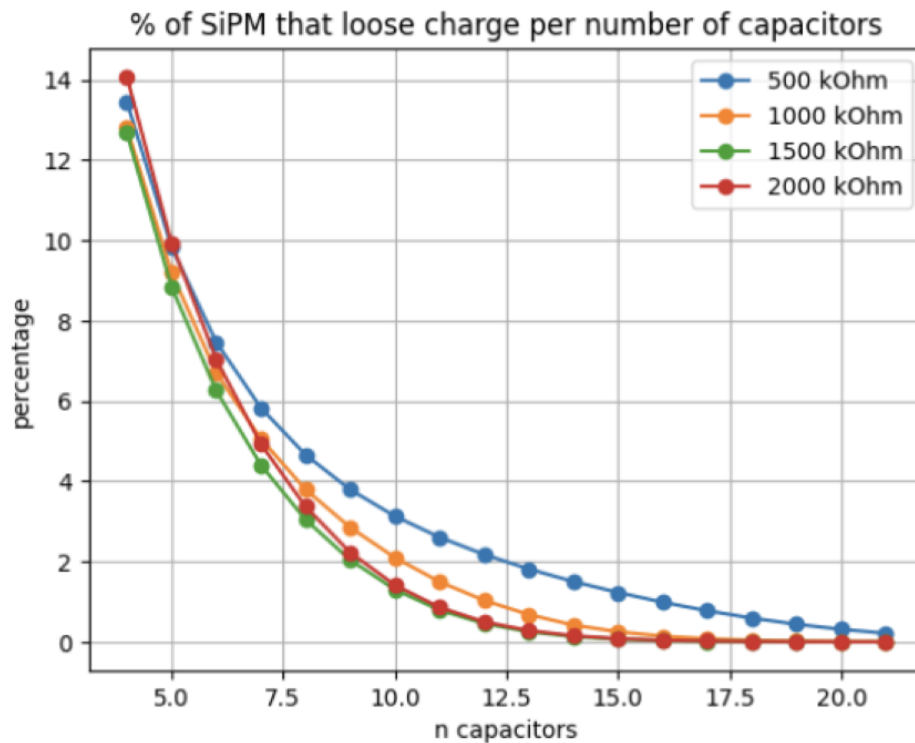
n capacitors = 8



Number of capacitors

from spill simulations with coded masks

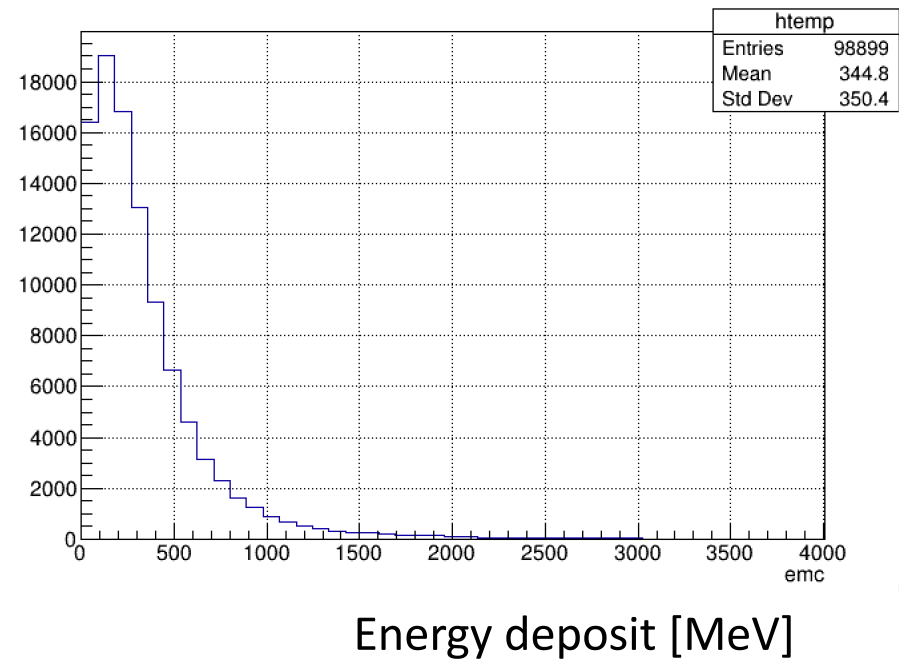
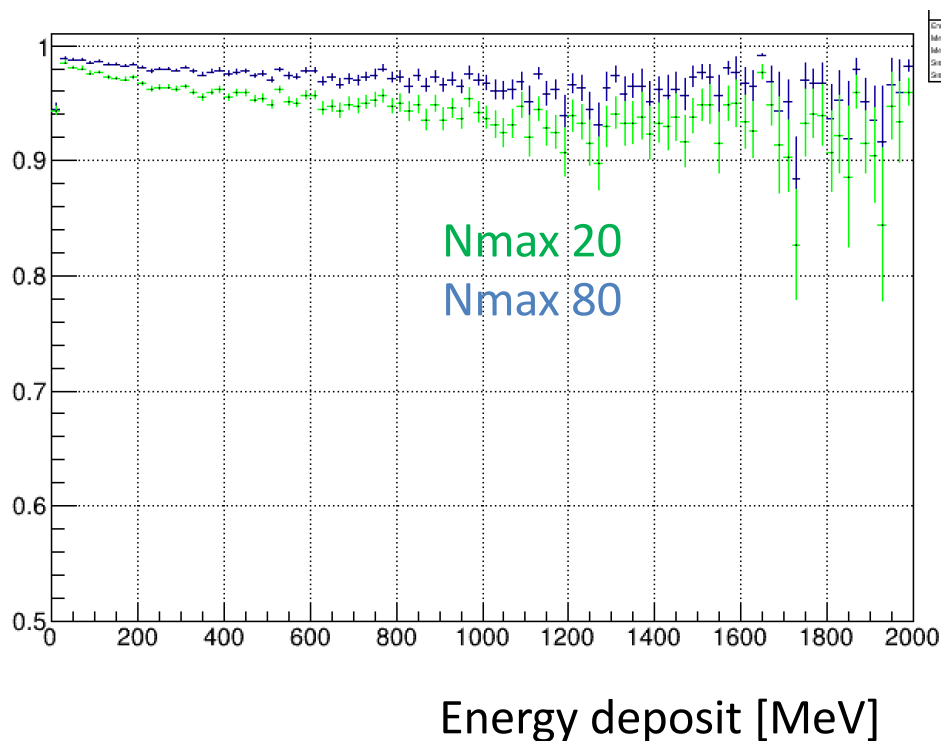
Considering different quenching resistors \rightarrow different signal time constant



Dynamic range optimization

from single interaction simulations with lenses

Neutrino interaction vertex in the the biggest fiducial volume
(0 cm from lens surfaces)



Timeline for ASIC

- Timeline was agreed with Torino group during the last meeting (9th May)

2024				2025				2026				2027			
Jan-Feb-Mar	Apr-May-June	Jul-Aug-Sept	Oct-Nov-Dec	Jan-Feb-Mar	Apr-May-Jun	Jul-Aug-Sept	Oct-Nov-Dec	Jan-Feb-Mar	Apr-May-Jun	Jul-Aug-Sept	Oct-Nov-Dec	Jan-Feb-Mar	Apr-May-Jun	Jul-Aug-Sept	Oct-Nov-Dec
Requirements definition															
Design															
								First production							
												Tests and validation			
												Design for second release			
												Final production			

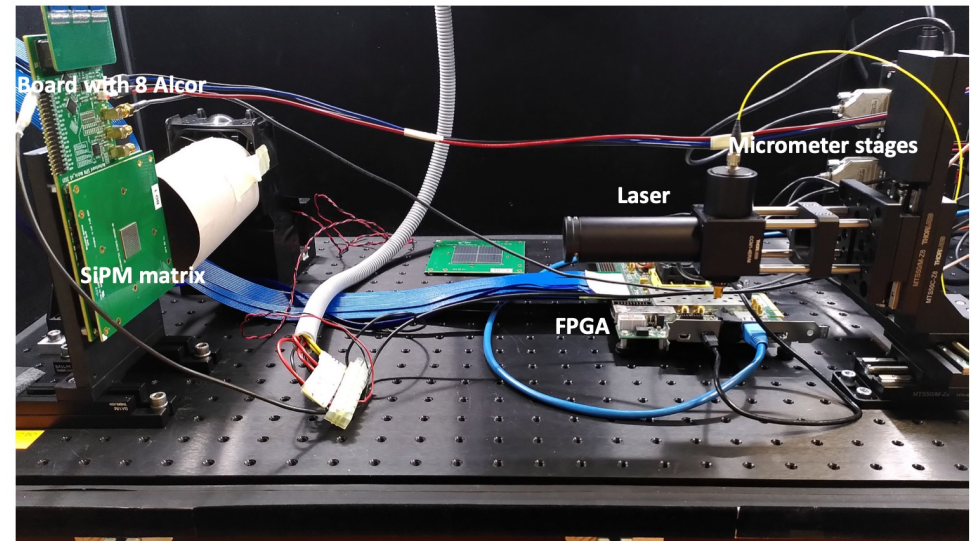
- 2 runs are foreseen
- by 1 month the requirements must be completed and integrated in the ASIC requirement document (GE-BO)
- The first phase: ASIC design (TO) → about 18 months (not more!)
 - Intermediate milestones to be agreed in the next meeting

Reconstruction algorithm

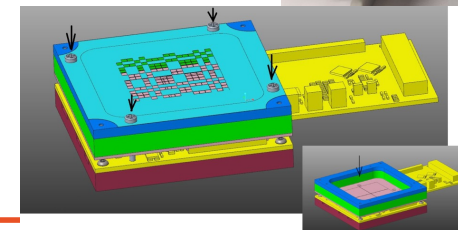
- **For coded mask:**
 - algorithm running on GPU, for a 3D reconstruction by using all the images
 - Algorithms was improved
 - quantitative evaluation of reconstruction performance is in progress
- **For lens based detector:**
 - ***Simple reconstruction*** based on fit on images available
 - MC info for matching tracks from different cameras still necessary
 - Evaluation of reconstruction performance with the latest geometry is in progress
 - Dedicated algorithm based on ***multiple-view projective geometry*** is under development
 - it was tested on point like or single tracks
 - current study on neutrino interaction events with 2 tracks

Detector prototypes

- We can test detector prototypes with a 16x16 SiPM matrix acquired by 8 Alcor chips
- Since December 2023 we have 2 Front End boards (at Bo and Ge)

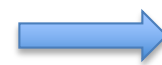
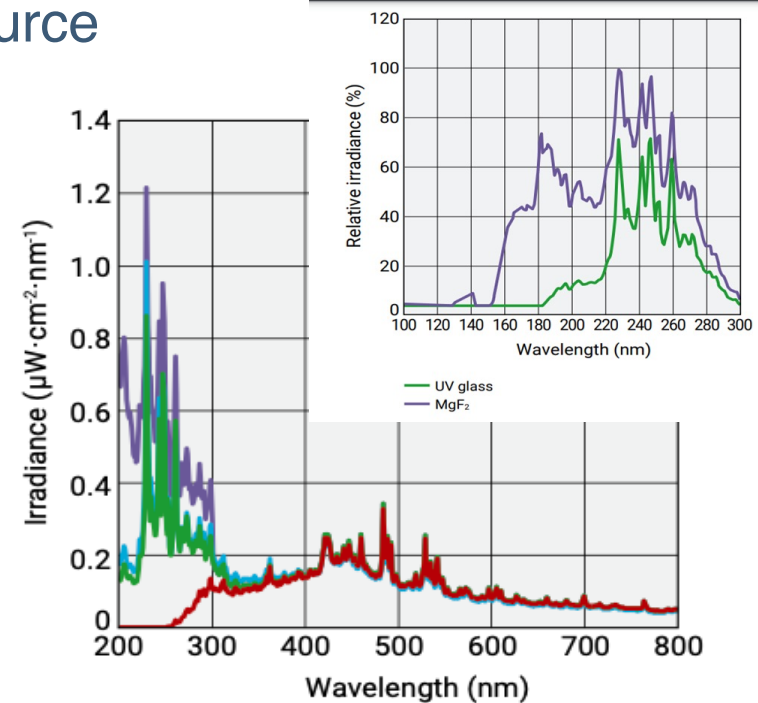


- DAQ with a Xilinx FPGA board is working (many improvements in the last period)
- First test with SiPM matrices already performed
- Tests with lenses or coded masks in ARTIC in the next weeks



First tests in Genova

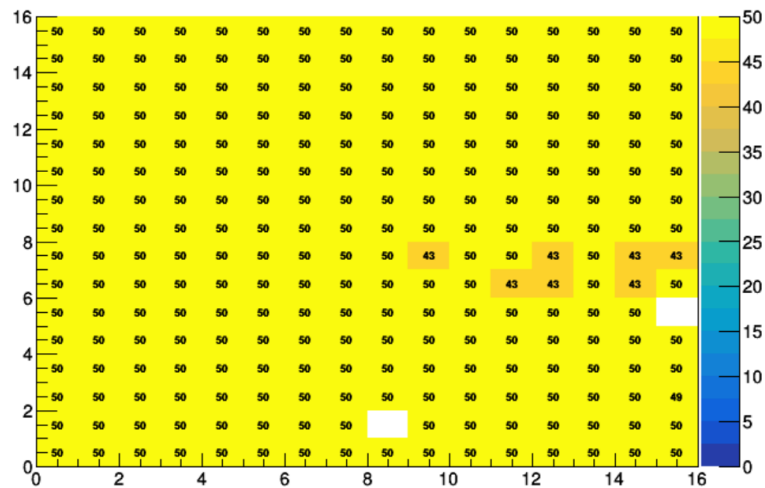
- First test with 256 channels SiPM matrix with TPB deposition
 - At room temperature or at liquid nitrogen temperature
 - with a pulsed 230 nm Xenon light source



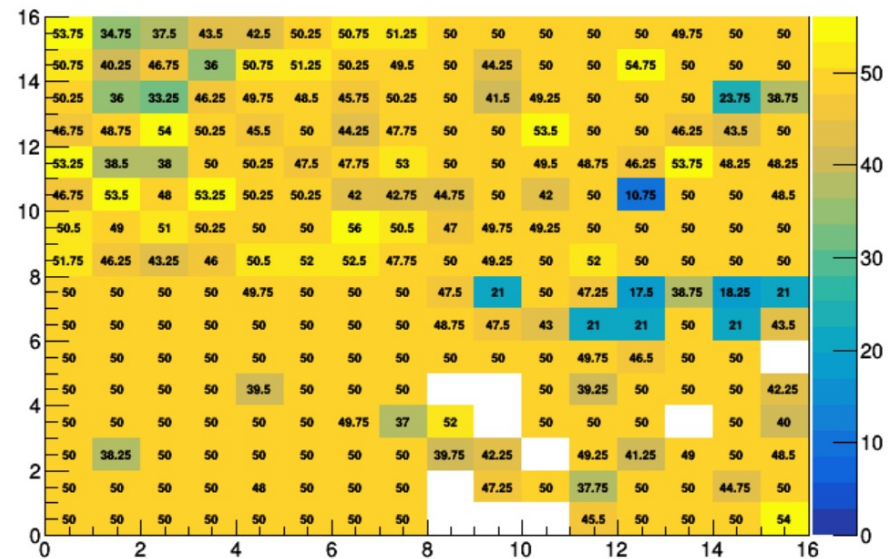
- Borosilicate glass (L11936)
- UV glass (L11937)
- Sapphire glass (L11938)
- MgF_2 (L14691)

First tests

- TDC calibration signal



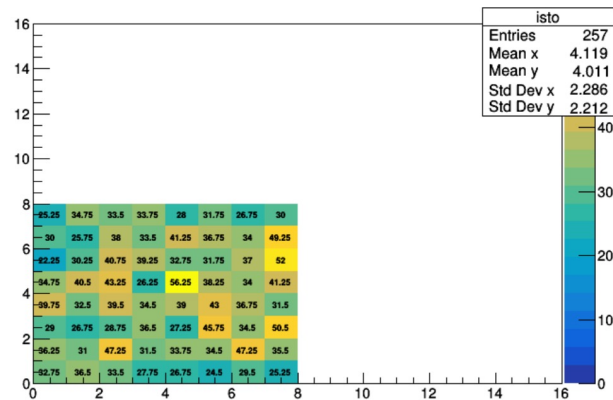
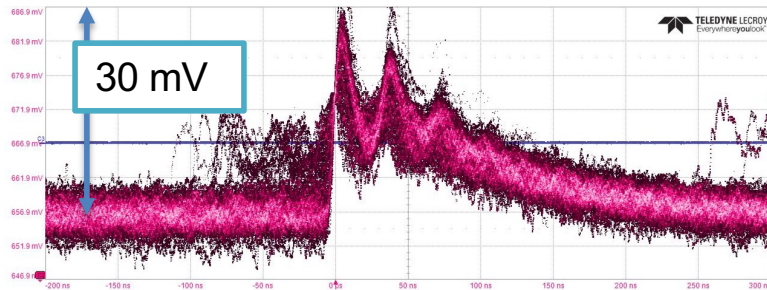
- Front End calibration signal
it depends on thresholds



50 counts were expected in each channel

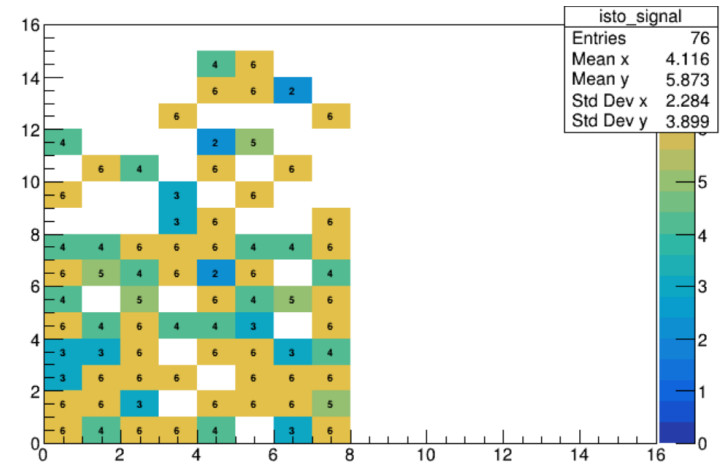
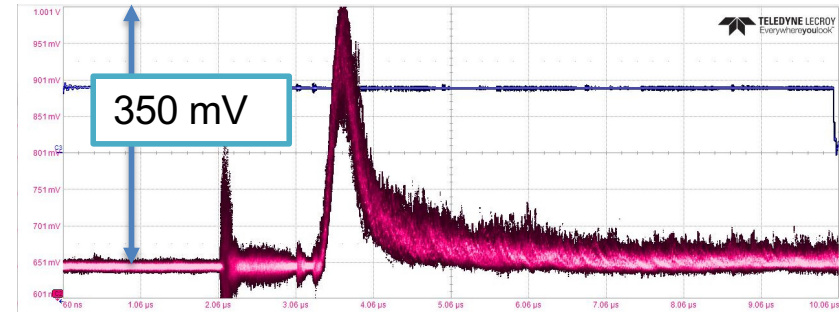
First tests

- Dark counts at room temperature



- Only 2 chips (64 channels) were acquired here
- 45 counts are expected for each channels

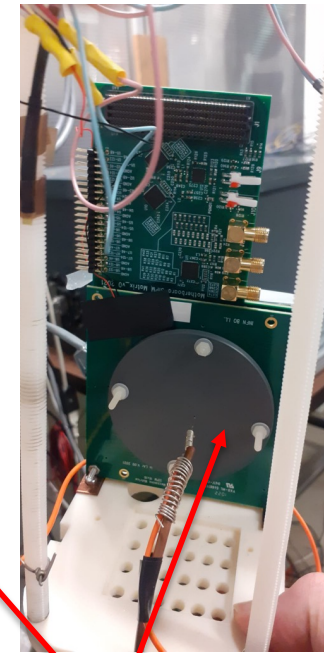
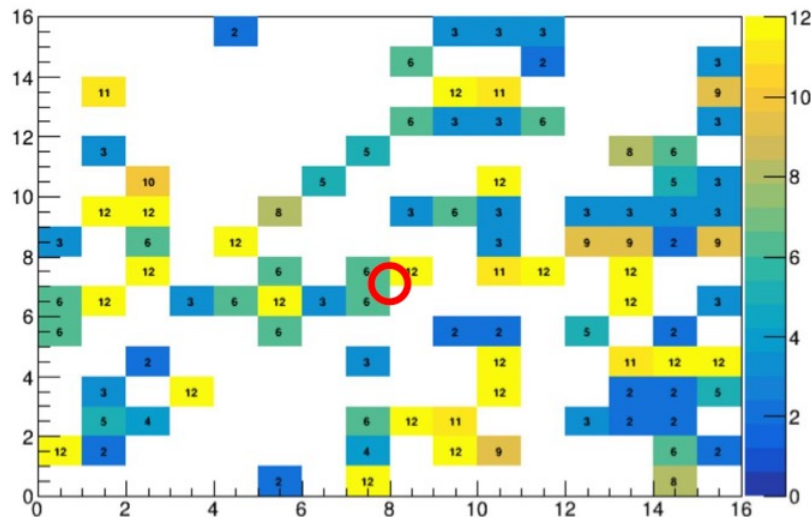
- Pulsed light signal



- Only 3 chips (96 channels) were acquired here
- 6 counts are expected for each channels

A problem with the TPB deposition

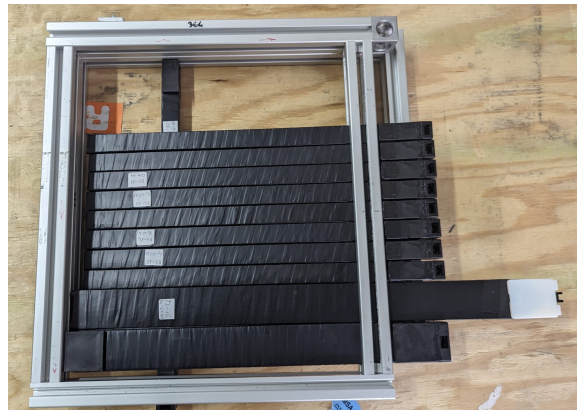
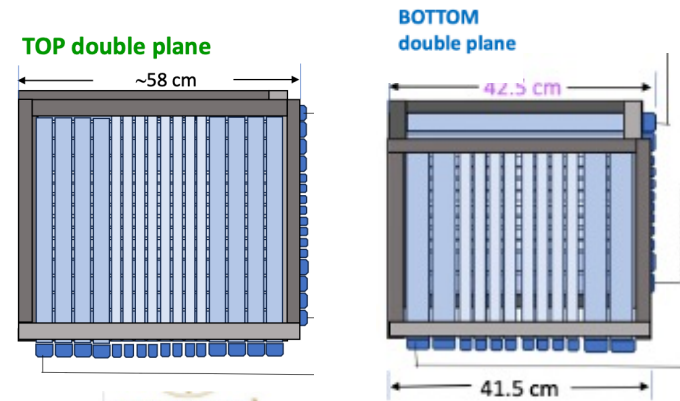
If we point the light on a single SiPM
the light is detected everywhere



- If we acquire the analog signal, the light signal is visible everywhere..
 - This is due to TPB deposition
 - we are design a proper grid for a new deposition
 - we will continue to test prototypes with visible light and matrix without TPB
- There is a very small hole

CRT for ARTIC

- Detector design completed
- Detector assembly and test: in progress



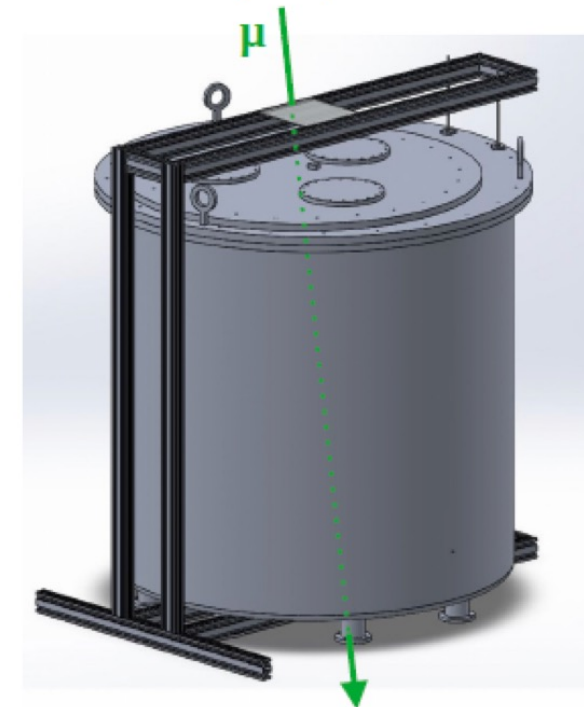
To-do list

- Mechanics design and realization (C-structure, scintillator-frames, trays, lifts, anchorings, ..) **COMPLETED**
- Wrapping of scintillator bars **COMPLETED**
- Mounting of single bars (SiPM, End-caps, PCB, connector, ...)
- Test of single bars **COMPLETED**
- Assembling of CRT planes and Installation on the mechanical structure
- Overall test and DAQ with cosmic rays

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CRT GOALS:

- Trigger for the LAr acquisition (fourfold coincidence)
- Two-view tracking to help the LAr event reconstruction



Trigger condition: Fourfold coincidence

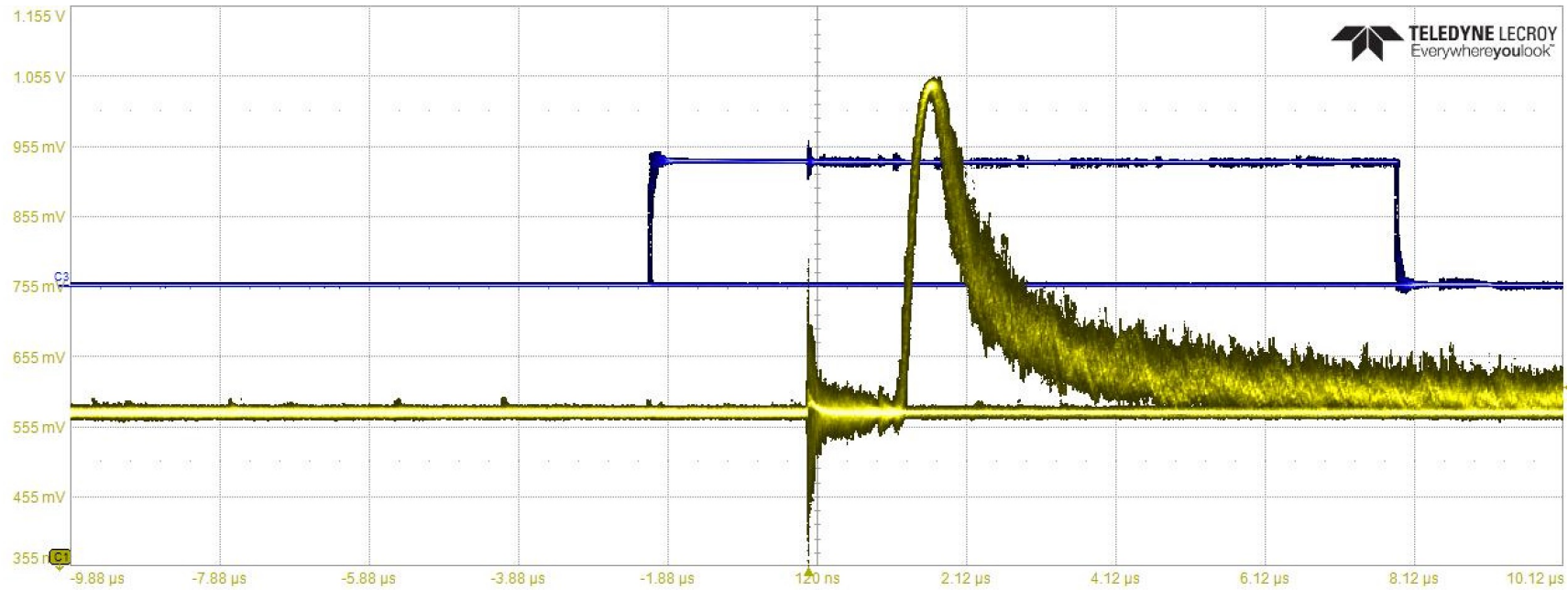
Conclusions

Many important activities are in progress :

- refurbishing in Legnaro
- Mechanical design for vessels and integration
- Reconstruction performance of neutrino interactions in GRAIN for TDR
- ASIC design with Torino group
 - a schedule was defined
- Test with prototypes
 - finally started, new results in the next future



Analog signal from Xenon lamp



Interactions in GRAIN and photon distribution on SiPM

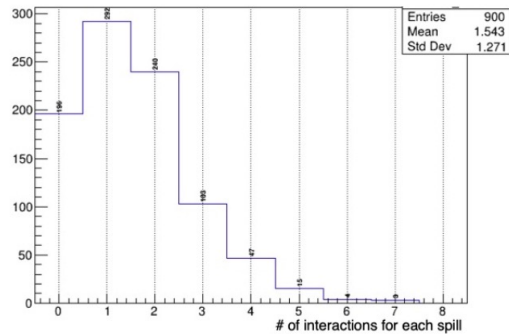


Figure 2: Number of neutrino interactions for each spill, whose tracks are detectable in GRAIN. A track is considered detectable if more than 6 MeV are deposited in the liquid Argon volume.

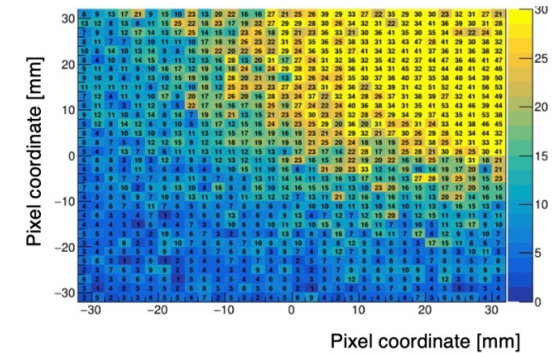
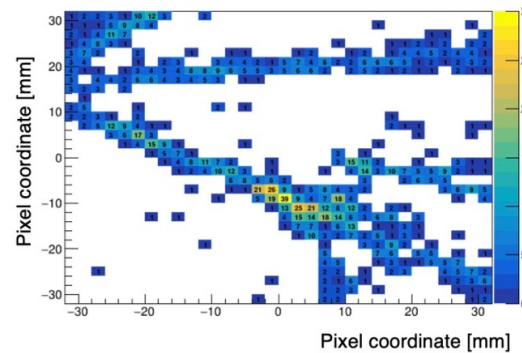
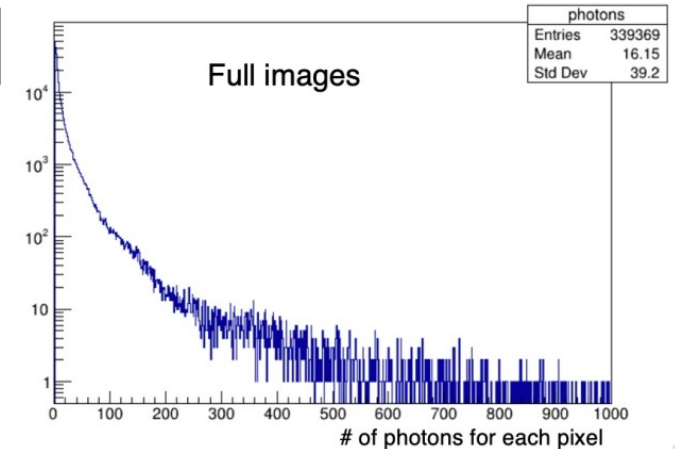
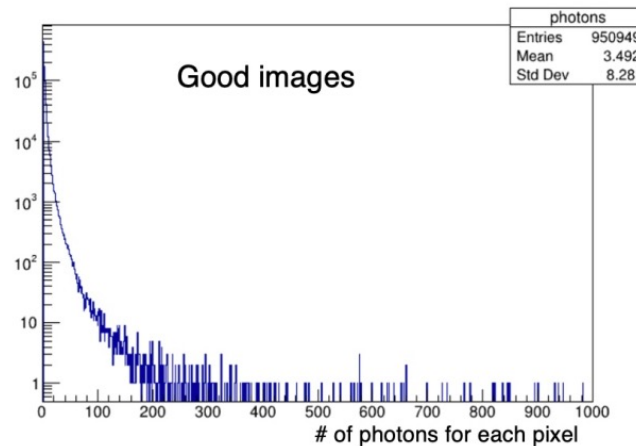
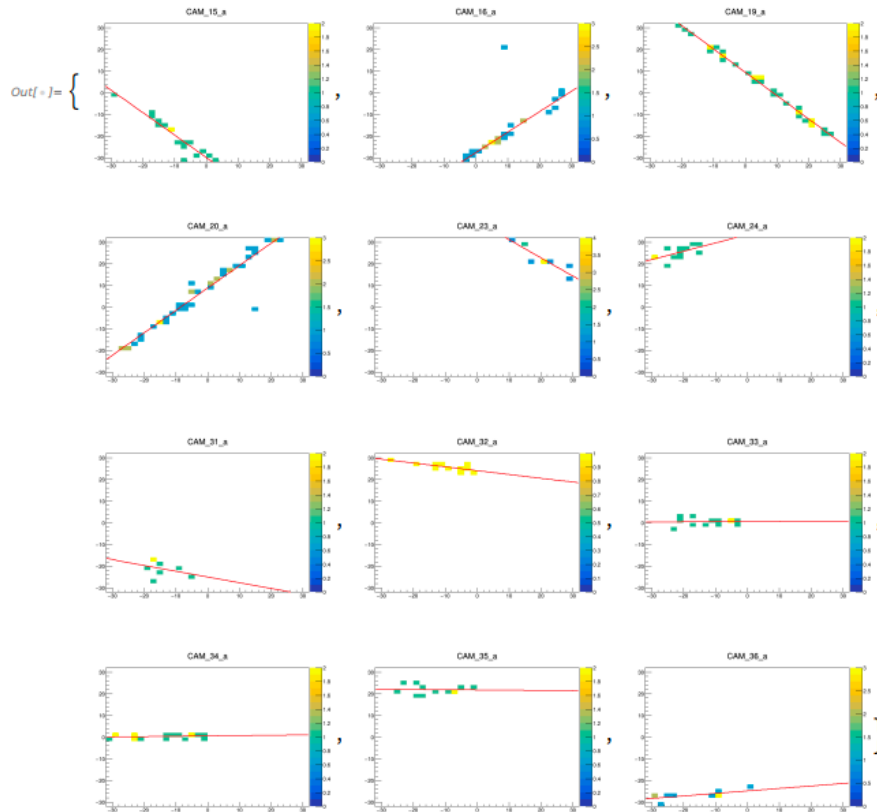
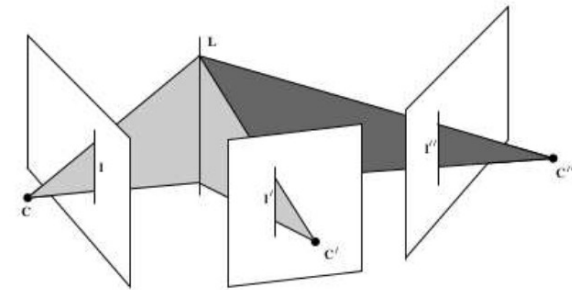


Figure 7: Example of images acquired by lens based detector. At left: a typical "good image" where vertex and tracks are clearly visible. At right: typical "full image" where 60% of pixels have collected photons.



Sim & Reconstruction

- Algorithm for track reconstruction under development by Lecce group



Global Multiple View Reconstruction of a Track

- The track is detected/seen by N cameras
- There are $M = \frac{N!}{2!(N-2)!}$ possible double-view reconstructions for the track
- We perform M reconstructions
- We take the mean value of the M possible reconstructions for each line parameter (director cosines (l, m, n))

$$l = \frac{\sum_{i < j}^N l_{ij}}{M} \quad m = \frac{\sum_{i < j}^N m_{ij}}{M} \quad n = \frac{\sum_{i < j}^N n_{ij}}{M} \quad (21)$$

i, j camera indices

- Analysis of intercepts of the M reconstructions

- Single track: tested
- Test with 2 tracks from neutrino interaction: in progress

Tests of prototypes in ARTIC

- Mechanics completed

